



Géosciences pour une Terre durable

brqm

DESIGN, CONSTRUCTION AND IN SITU TESTING OF A MUON CAMERA FOR EARTH SCIENCE AND CIVIL ENGINEERING APPLICATIONS.

Ignacio LÁZARO ROCHE

Thesis defense for the degree of Ph.D. in Earth & Universe Sciences 8 October 2018





OUTLINE

- 1. Introduction
 - Context
 - Muons
- 2. MUST² camera
 - Principle
- 3. Signal
 - Formation
 - Trajectory reconstruction
- 4. Experimental results
 - Calibration tests
 - Study case
- 5. Considerations towards industrialization
- 6. Conclusions & outlook





	Introduction	MUST ² camera	Signal	Experimental results	Industrialization	Conclusions
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INTRODUCTION - Context

Figure from Géoportail, source BRGM.

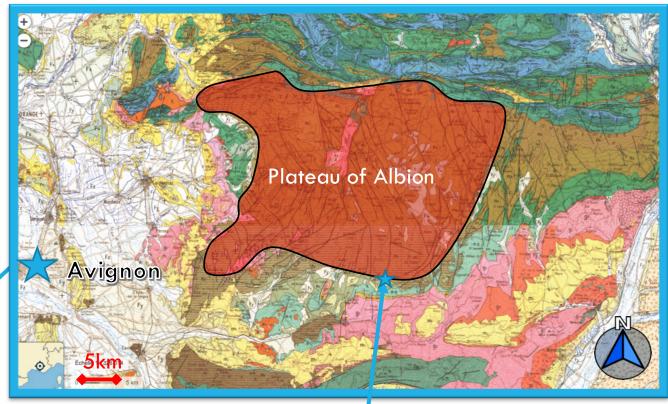




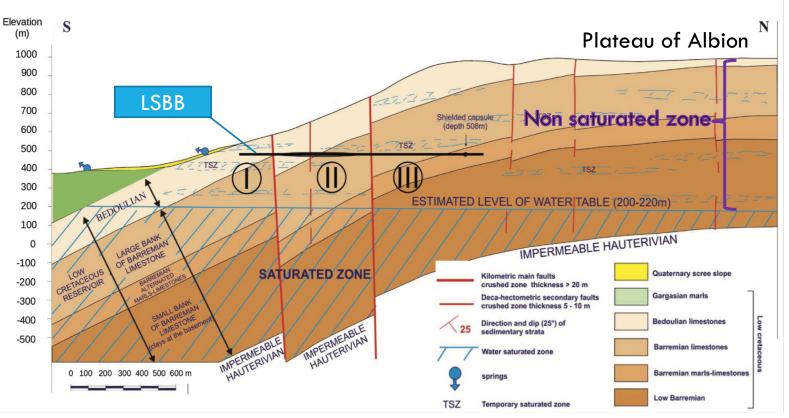


Figure from MODIS project by NASA.

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INTRODUCTION - Context





The fluid flows across the unsaturated zone

- This mass motion results into volumetric mass fluctuations: local density variations
- Hydraulic timescale?
- Hydraulic volumetric?
- Strong porosity and permeability heterogeneities
- Experimental site: carbonate reservoir
 Access to the non saturated zone in LSBB
- Fontaine de Vaucluse water catchment

Figure from Sénéchal, (2013)

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INTRODUCTION - Context

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How to measure temporal density variations?

- The muon flux decreases progressively, with an absorption correlated with the medium opacity*
- Cosmic muons are able to penetrate up to several hundreds of meters underground
- Muographic measurements in transmission do not require a direct contact between the target volume and the detector
- Provides complementary information to other techniques
- Cosmic muons are a natural, permanent, passive source
- Muons average flux at sea level $\sim 10.000 \ \mu/(m^2 \cdot min \cdot 2\pi sr)$

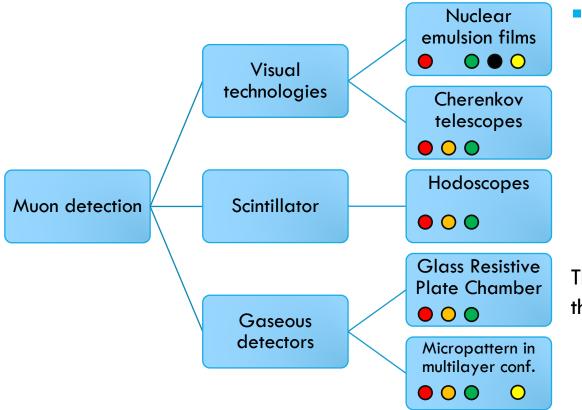
*Opacity is the density integrated over the path length

Animation adapted from Cosmus project from U. of Chicago. Cosmic shower originated by a 1EeV proton over Genève.

INTRODUCTION - Muons



Which muon detection technology?



- Requirements for the targeted application:
 - Retrieve the particle trajectory (zenith and azimuth angles)
 - Temporal information of the detected muons
 - Angular resolution compatible with geophysical techniques
 - Big angular acceptance
 - Compact and transportable for narrow operation

There was no muon detection technology capable of fulfilling all the requirements:

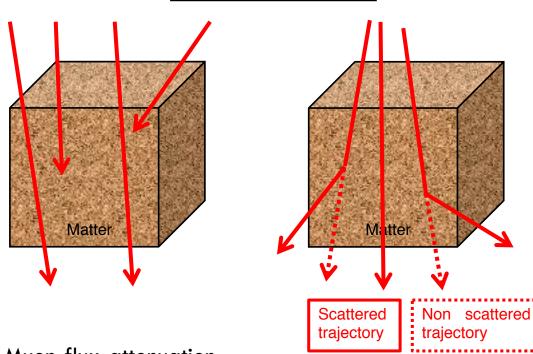
Need for a new technology





INTRODUCTION - Muons

What should we measure?



Muon transmission

Muon flux attenuation due to energy loss

Muon scattering

- Two kinds of approaches depending on the muon interaction
- Based on the screening effect of matter on the natural flux of cosmic muons
- Both interactions take place simultaneously
- Their contribution varies depending on the case,
 transmission is more sensitive to absorption when imaging big rock volumes

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INTRODUCTION - Muons



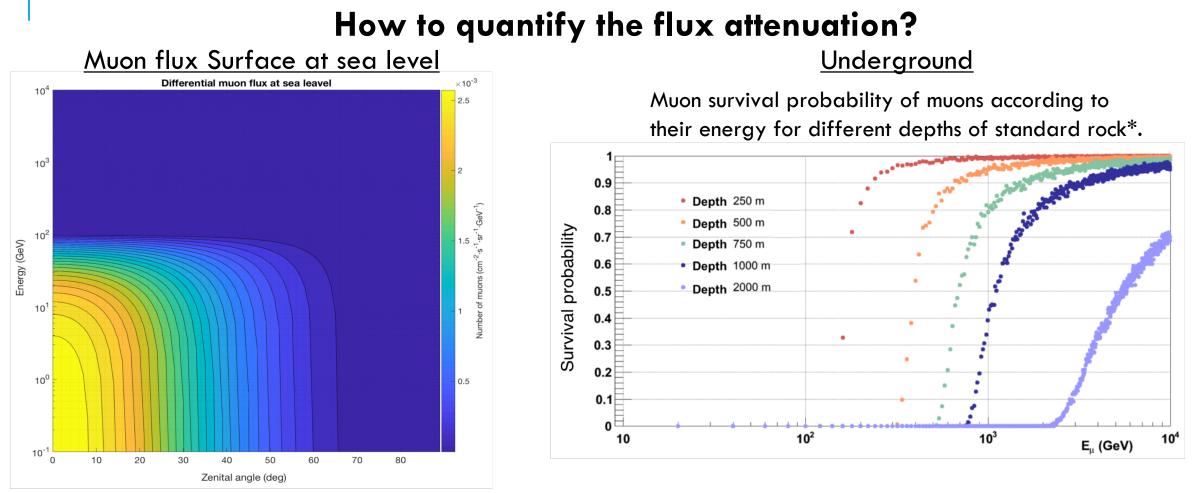


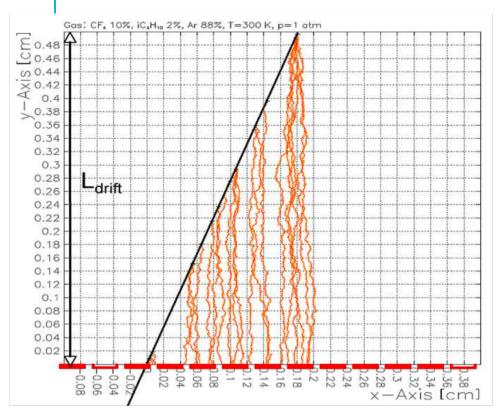
Figure of Angular and energy distribution of the differential muon flux at sea level obtained with the Gaisser's model with Tang parameters [Tang, 2006].

Simulation made with MUSIC code and 10.000 muons per depth. *Standard rock (A=22, Z=11, ρ =2,65 g/cm^3) Figure from [Hivert, 2017].

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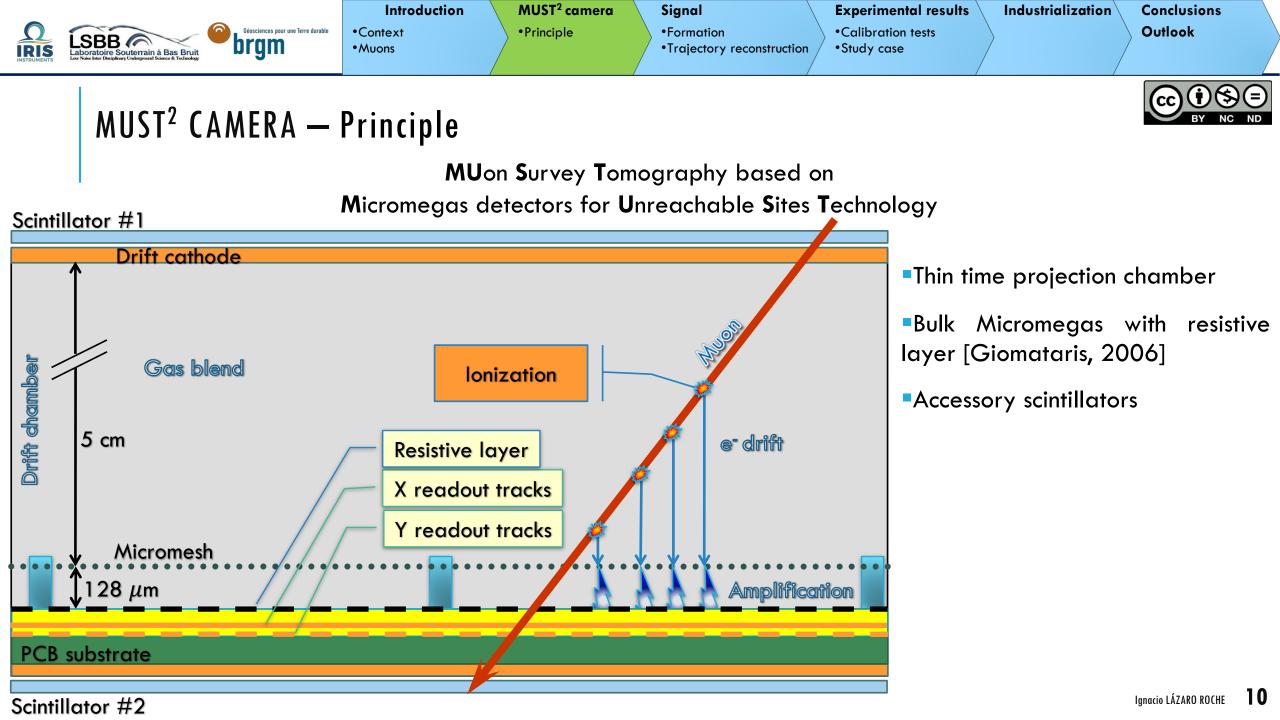
MUST² CAMERA – Principle



Simulation of the passage of a muon inside a detector made with Garfield++ code by R. Veenhof [Veenhof, 2010].

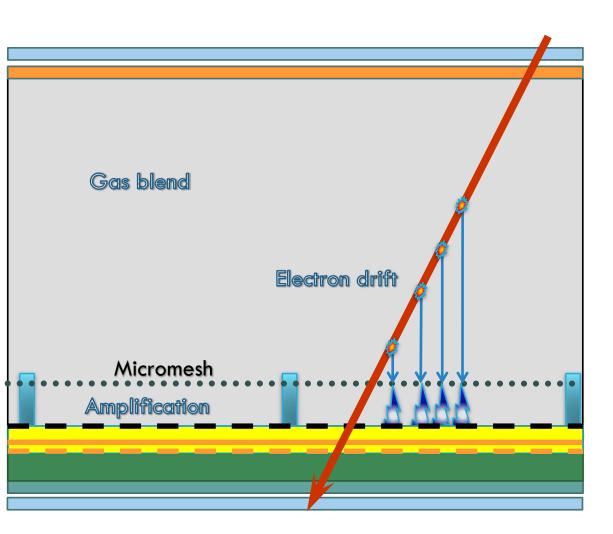
How to measure the trajectory of a muon?

- Conversion of the incident radiation into primary e⁻ and ions.
- Ionizations generated randomly, stochastic process
- The primary electrons drift towards the amplification zone
- The longitudinal and transverse diffusion should me minimized





MUST² CAMERA – Principle



Considerations towards TPC operation

- Gas choice
- Adequate projection of primary electrons
- Minimize neutralization of e⁻ by the micromesh
- Enough signal amplification
- Reliable trigger



SIGNAL — Formation

How to optimize the signal?

Signal strength =
$$N_T \cdot (1 - R) \cdot (1 - A) \cdot T \cdot G \cdot k$$

Physical processes of the detector

- N_T = total ionization per path length (Gas choice)
- R = Recombination after primary ionization (\vec{E}_{drift})
- A = attachment to gas constituents during scattering (Gas contaminants)
- T = Micromesh e⁻ transparency (Micromesh geometry and $\vec{E}_{drift} / \vec{E}_{amp}$ ratio)
- **G** = detector gain (\vec{E}_{amp})
- k = conversion factor between the charge generated and the signal read by the electronics (readout design and electronics configuration)



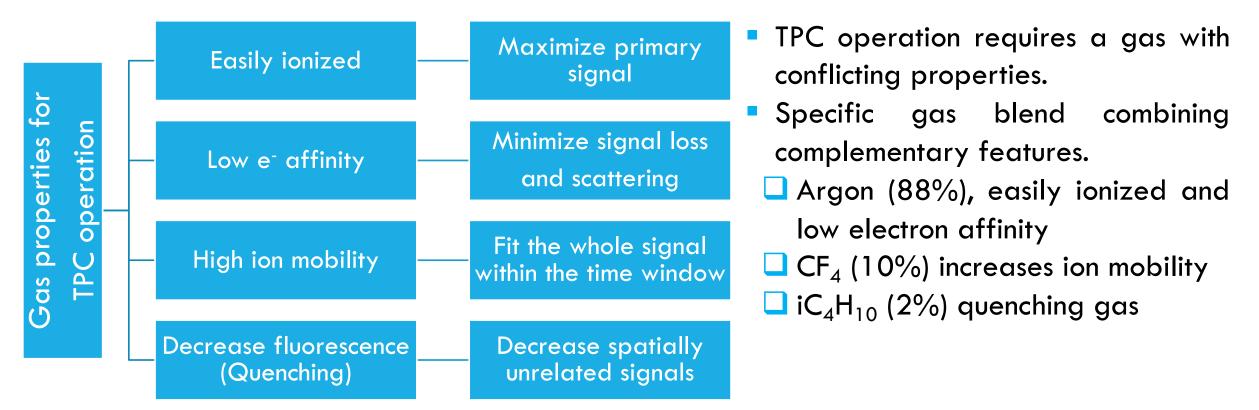
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SIGNAL — Formation

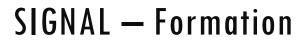
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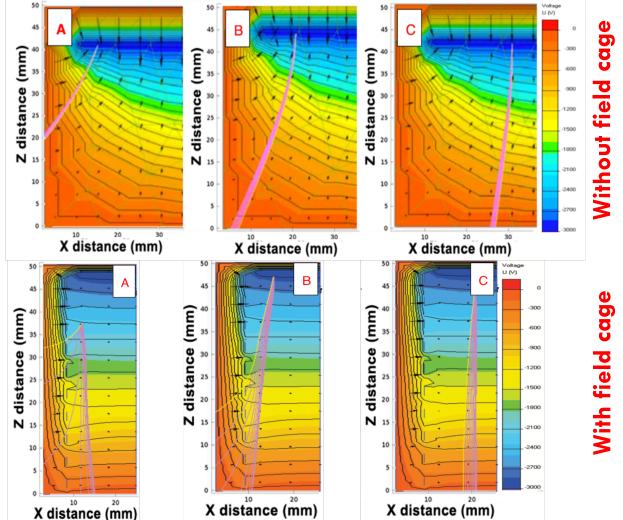
How to choose the gas?





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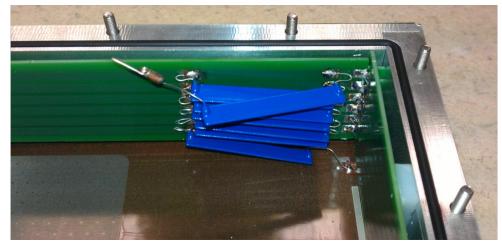




Figures show the most probable path of the electron inside the TPC drift chamber according to their position. Simulation are made for 10 electrons each with QuickField code.

How to obtain a straight projection in a TPC?

- Simulations of the electron drift within the TPC reveal **deviations** from straight path near the frame perimeter.
- Electric field cage reduces this unwanted effect





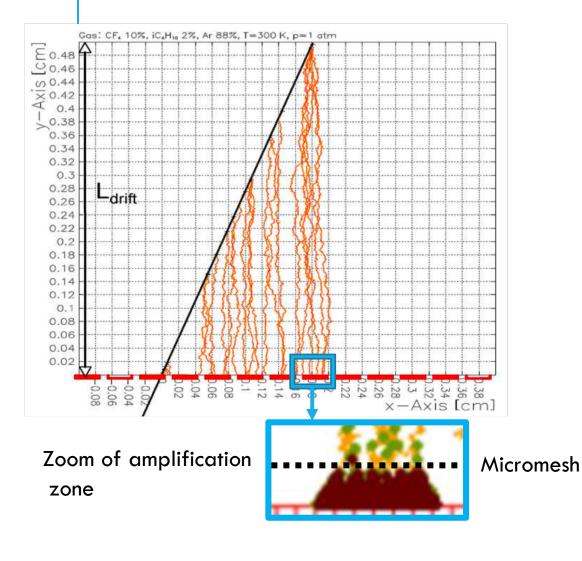


MUST² camera •Principle

Signal •Formation •Trajectory reconstruction Conclusions Outlook



SIGNAL — Formation



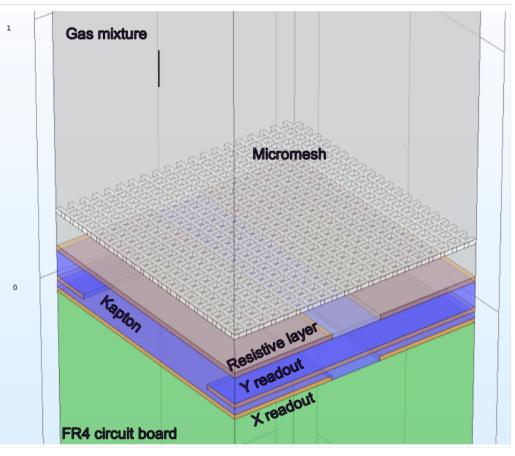
How is the signal formation near the amplification zone?

- Primary electrons arrive near the micromesh
- A small fraction of electrons is neutralized against the micromesh [Nikolopoulos, 2011]
- The stronger electric field accelerates the electrons and causes avalanches (Gain $\sim 10^4$)
- The displacement of charges induces signal into the micromesh and the readout tracks

Simulation of the passage of a muon inside the MUST² camera made with Garfield++ code by R. Veenhof [Veenhof, 2010].



SIGNAL — Formation



Which readout suits better?

- The big active surface and angular resolution required results into a high granularity readout
- Pixel-based detectors lead to high number of channels (n² channels)
- Strip based detectors require less electronics (2n channels)
- The price to pay:
 - Heterogeneity in terms of charge induced in the X and Y planes

Scheme of the unit cell of the Micromegas detector. Performed with COMSOL multiphysics[®].



SIGNAL — Formation



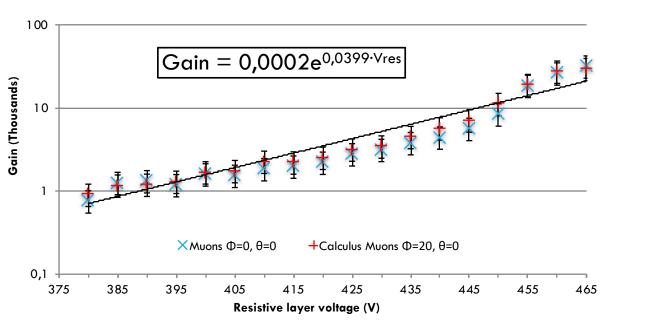
How to quantify the signal amplification?

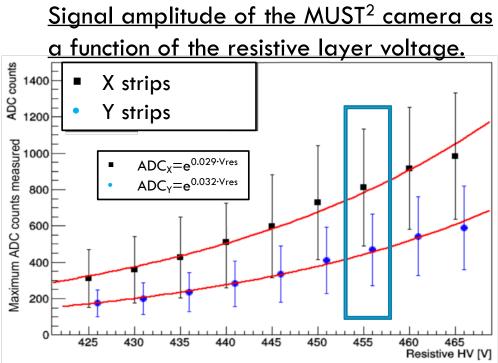
$$Gain = \frac{\Delta I}{N_T \cdot d \cdot \frac{\mu}{S} \cdot charge \ of \ e^-}$$

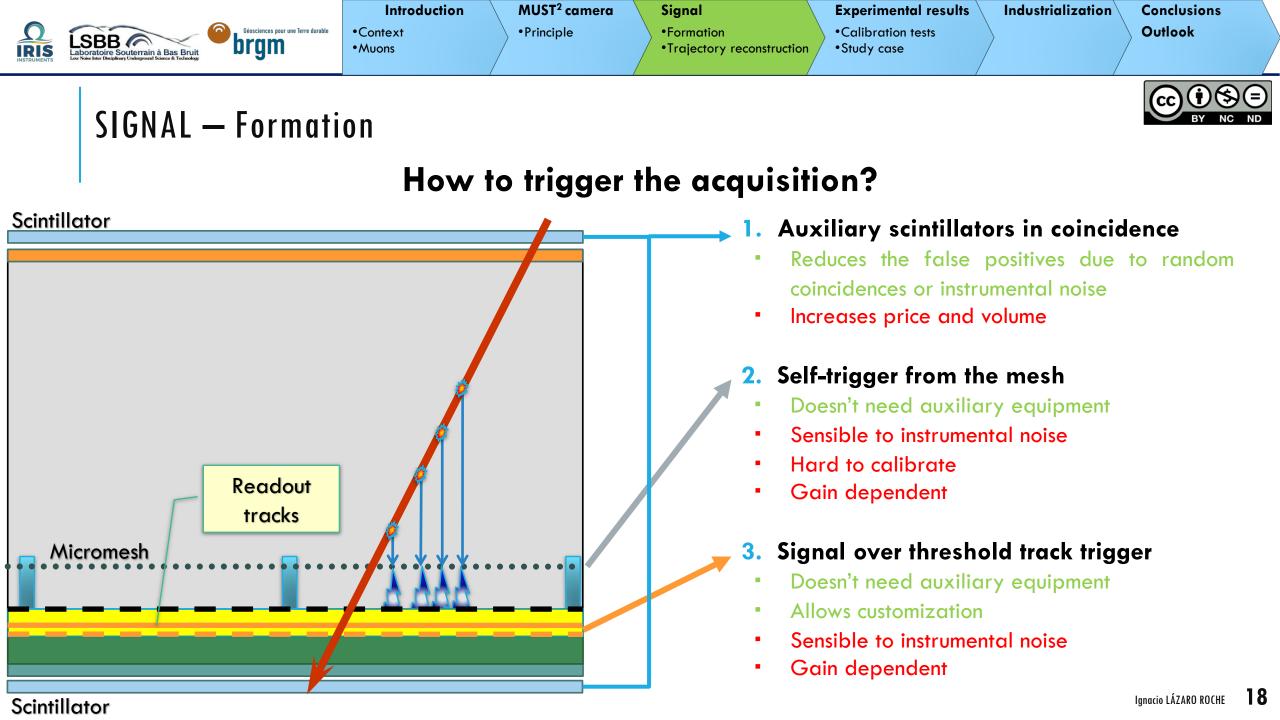
 $\Delta I =$ Average variation of the current consumption between spills and breaks (nA) N_T·d = Number of electron-ion pairs induced by the muon

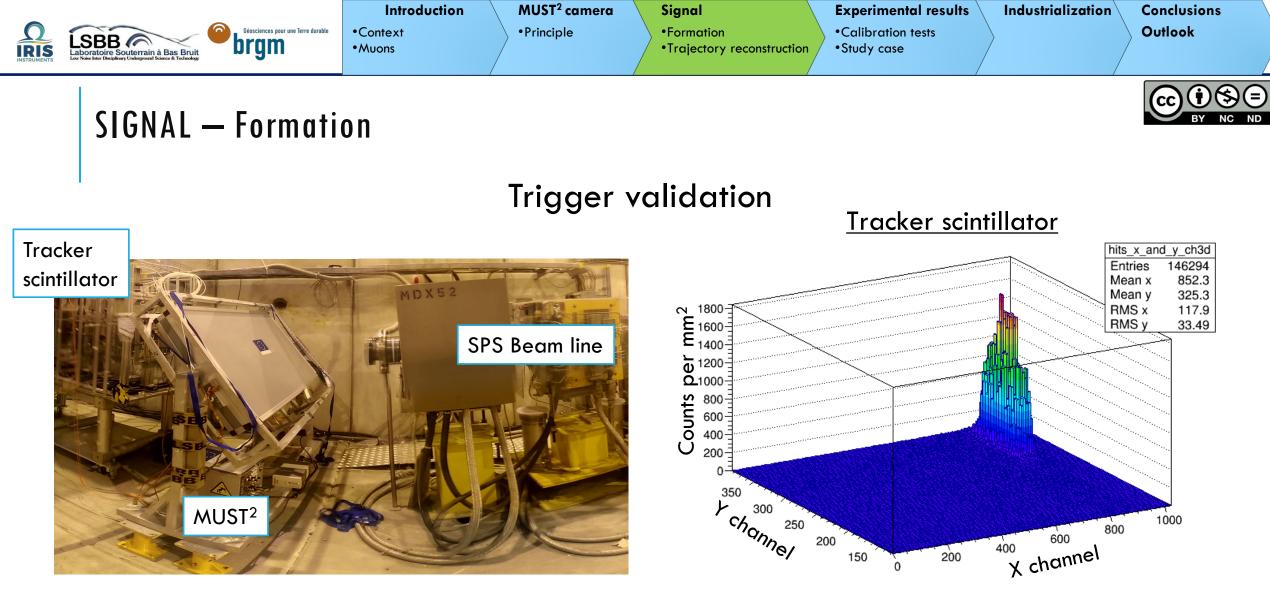
 μ/s = Number of muons per second during the measurement (Muons per spill/spill length).

Calculated gain as a function of the resistive voltage







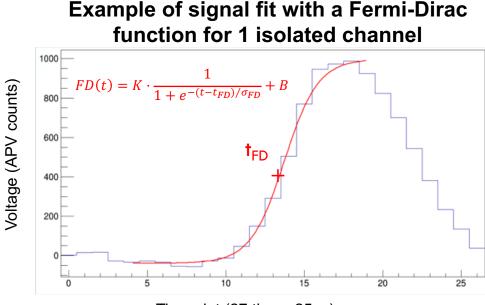


Muon beam test at CERN thanks to RD51 collaboration

Histograms with the detected events per mm² for different positions



SIGNAL — Trajectory reconstruction How to retrieve temporal information?



Time slot (27 times 25ns)

- Reconstruction of a single channel signal
- Signal fit
 - Allows determining the signal rise time (t_{FD})with a few ns resolution
 - Determines the hit tracks in X and Y axes





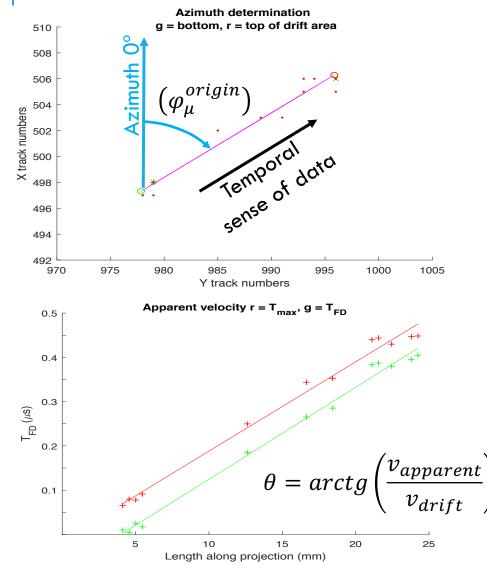
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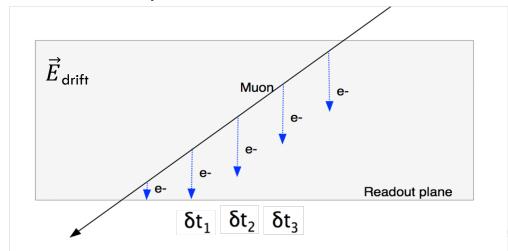


SIGNAL — Trajectory reconstruction



How to retrieve the muon trajectory?

- The arrival time of e⁻ is distance-dependent
- The e⁻ drift speed is known and constant for a given \vec{E}
- The time difference provides information about the original height of the ionization point
- The azimuth angle can be calculated by the orientation of points along the readout plane
- The zenith angle is related to the length of track and time interval between points

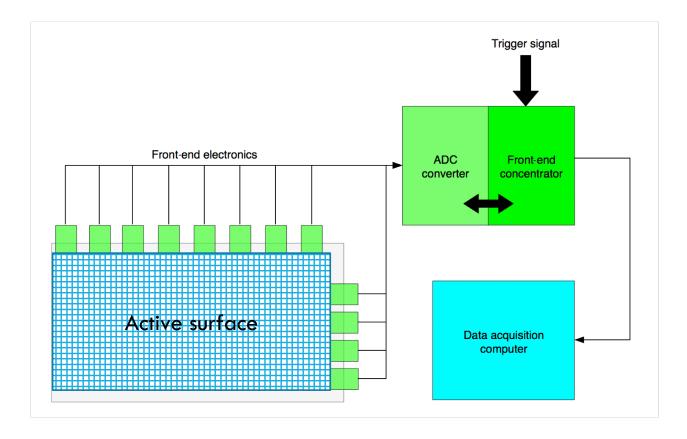


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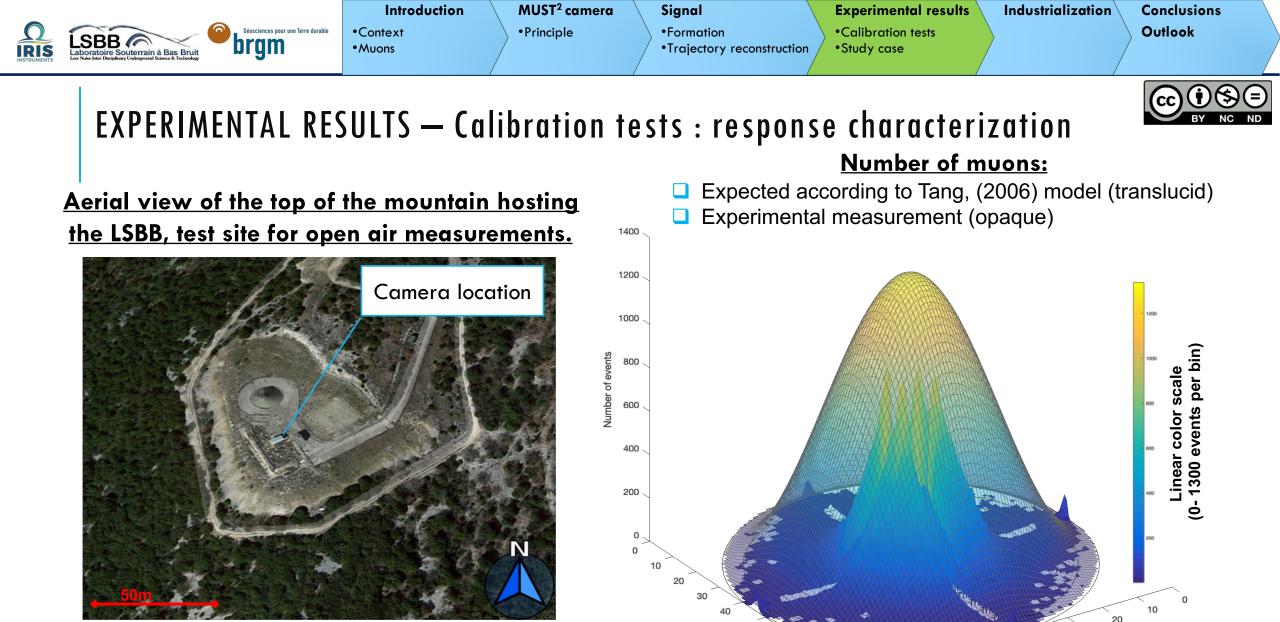


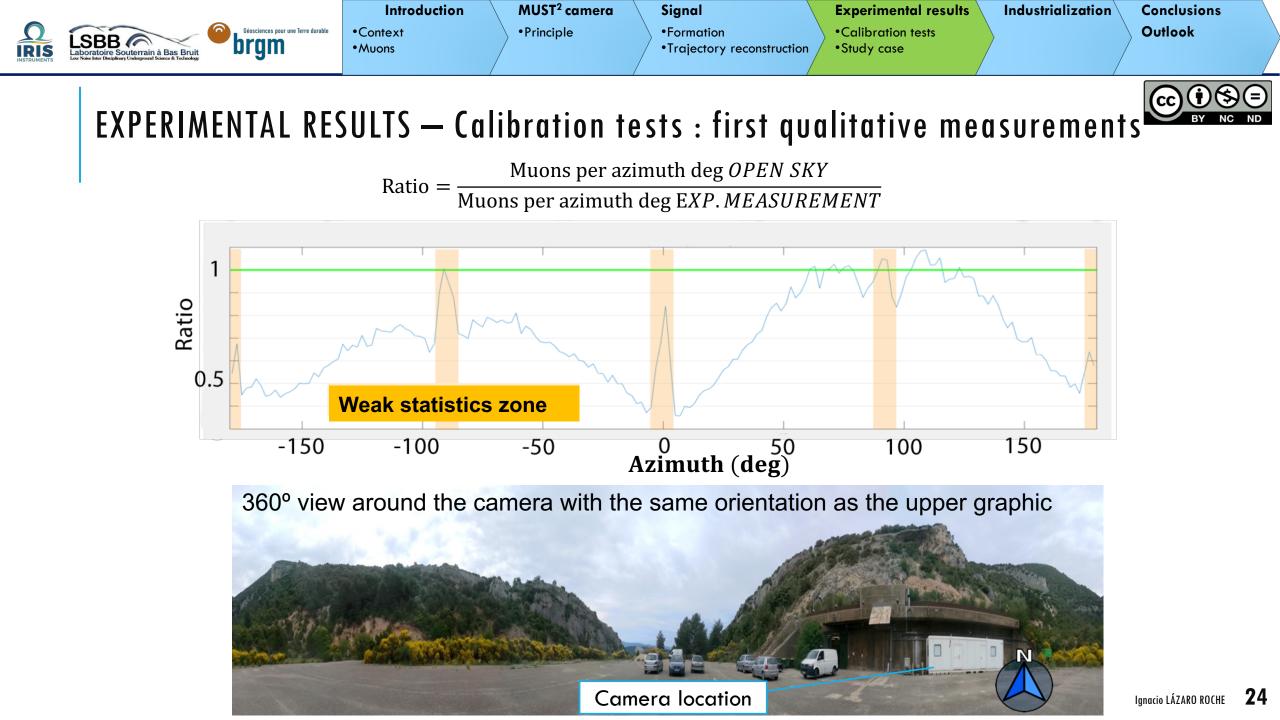
SIGNAL — Trajectory reconstruction

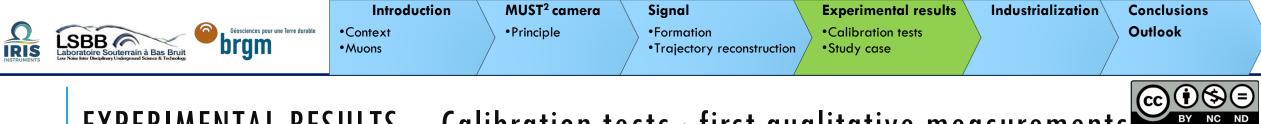
How to instrument the camera?



- Requirements:
- Good enough temporal resolution
- Highly scalable
- 🔲 Modular
- Relatively inexpensive (big number of channels)
- Challenges:
- Network configuration, distance between elements
- Adapt existing or develop new software tools for data acquisition
- Live data management and analysis

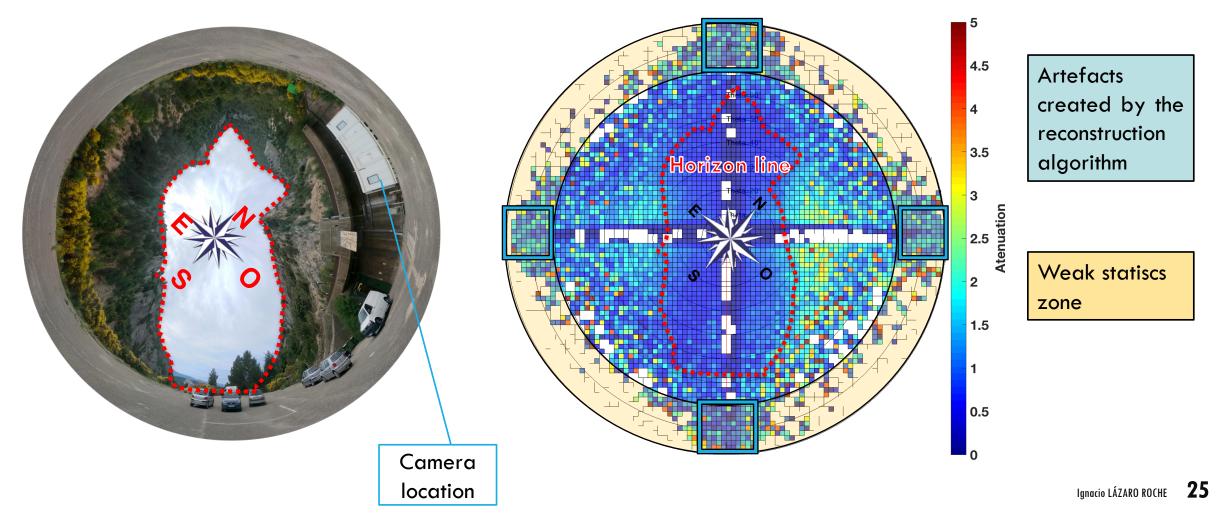






EXPERIMENTAL RESULTS — Calibration tests : first qualitative measurements

360° view around the camera



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Known topology



Monitored parameters:

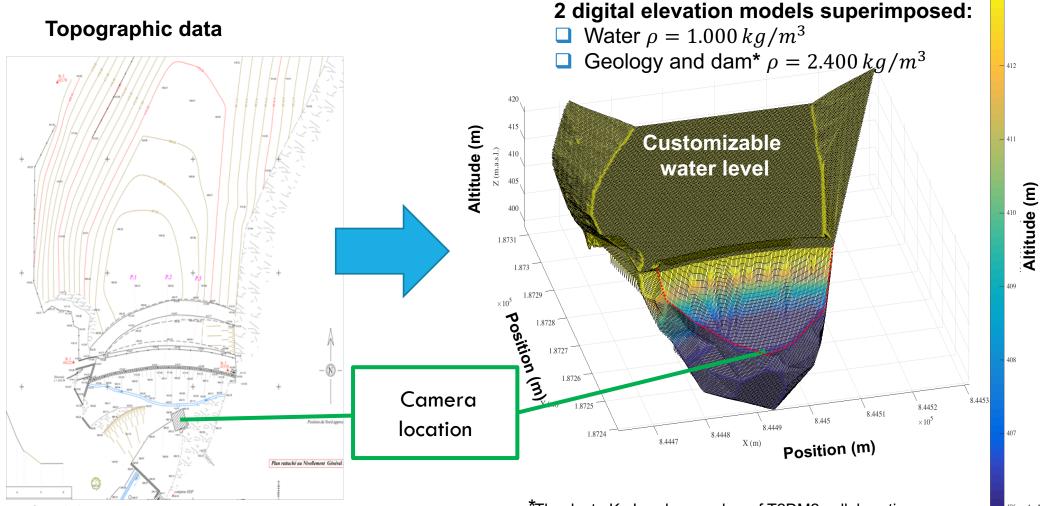
Temperature, humidity and atmospheric pressure inside the valve house

Level, temperature and conductivity of reservoir's waterPrecipitations (only known water source)







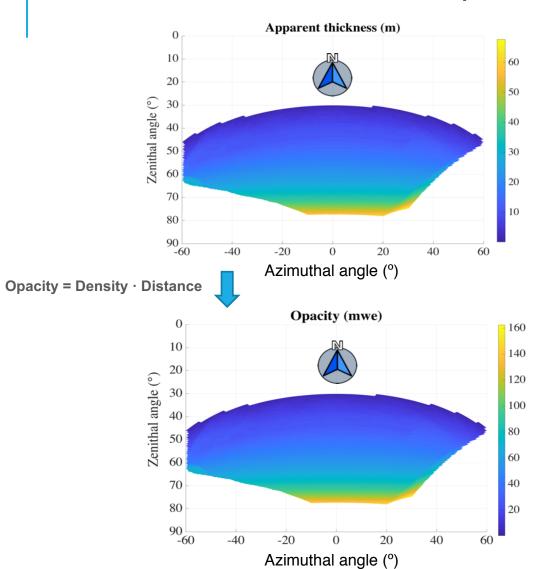


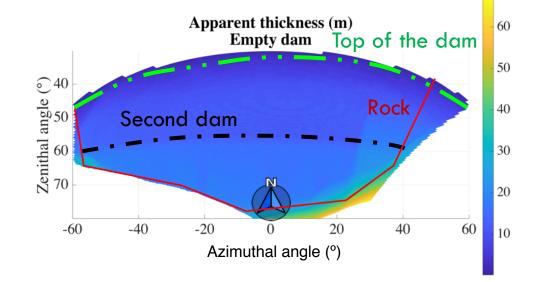
Source: Société du canal de Provence

*Thanks to K. Jourde, member of T2DM2 collaboration

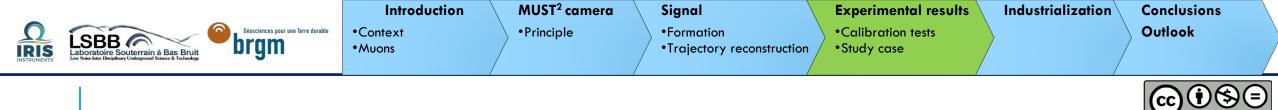
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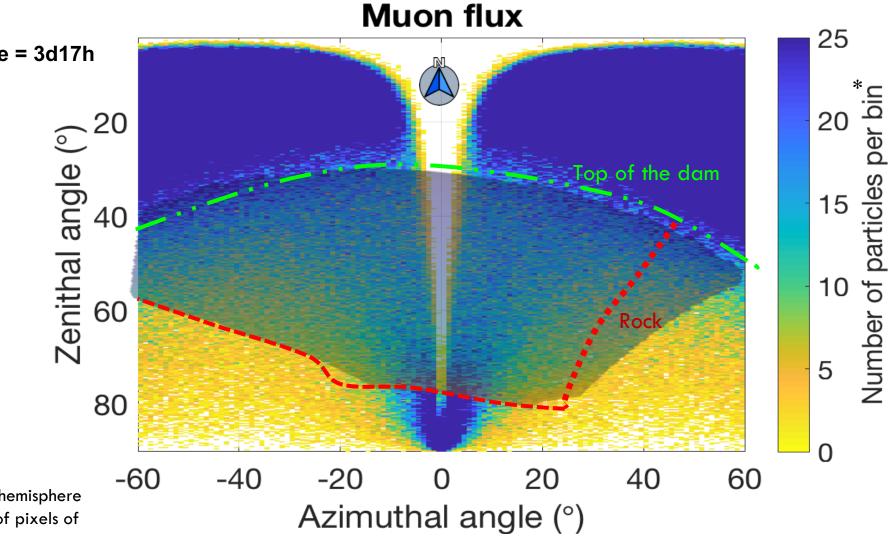
	Introduction	MUST ² camera	Signal	Experimental results	Industrialization	Conclusions
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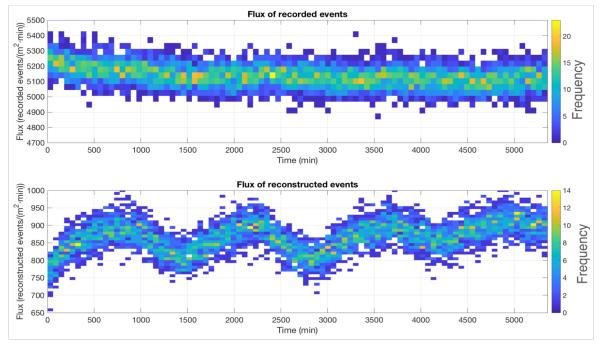
Integration time = 3d17h

*Bin = Representation of the hemisphere over the camera in a matrix of pixels of dimension 360x360

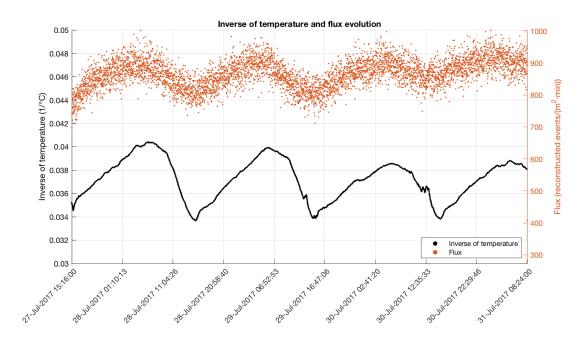
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Temperature influence on the muon flux measurement



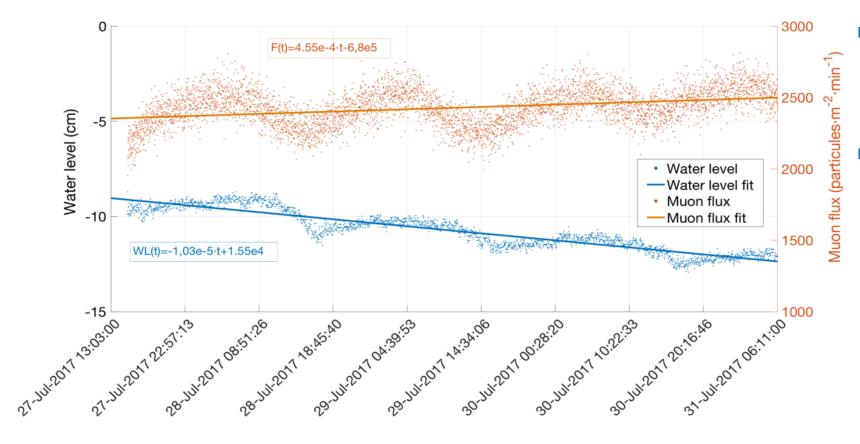
- 2 well differentiated behaviors:
 - Small variations in events triggered by the scintillators
 - Sinusoidal shape for reconstructed events with MUST²



 Influence of the inverse of temperature in the signal reconstruction performance



Temporal evolution of muon flux and water level



- Strong sine-wave behaviour due to the effect of the temperature in both the barometer used to determine the water level and the MUST² camera
- The linear regression of the whole data shows that the emptying trend of the dam is related to a rise of the muon flux



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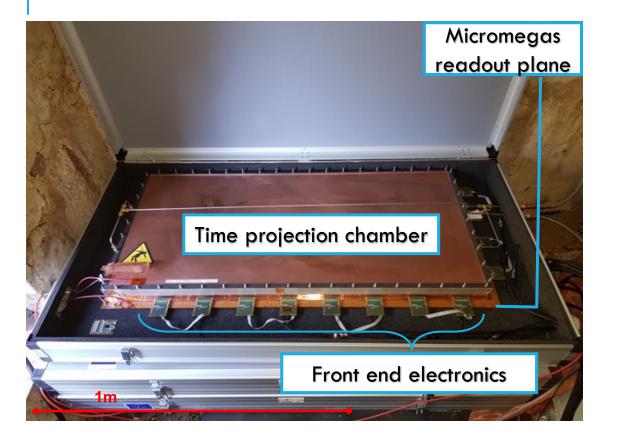
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CONSIDERATIONS TOWARDS INDUSTRIALIZATION



- Max. external dimensions 144 x 79 x 12 cm
- •Weight ~28 kg
- Angular acceptance up to 80° when triggered with external scintillators

Angular resolution better than 1° for particles with angles of incidence over 17°

Patented in 2016 [Lázaro, 2016]



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CONSIDERATIONS TOWARDS INDUSTRIALIZATION



- Gas flow remote control and monitoring
- Filter gas impurities and contaminants
- Custom gas bottle according to context

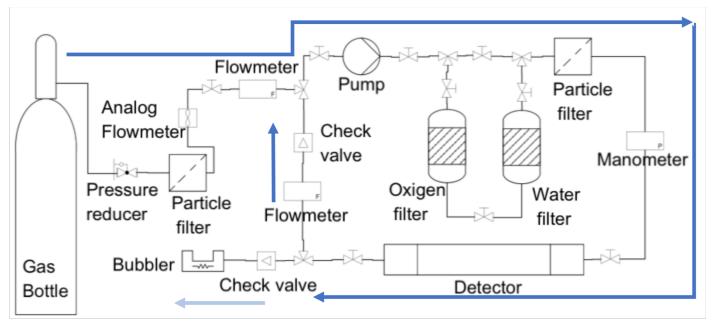




Figure by NASA.

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CONSIDERATIONS TOWARDS INDUSTRIALIZATION



Technology readiness level TRL 9 Actual system "flight proven" through successful mission operations BRGM TRL 8 Actual system completed and "flight qualified" through test and demonstration (ground or space) TRL 7 System prototype demonstration in a space environment IRIS TRL 6 System/subsystem model or prototype demonstration in a relevant environment (ground or space) TRL 5 Component and/or breadboard validation in relevant environment TRL 4 Component and/or breadboard validation in laboratory environment LSBB TRL 3 Analytical and experimental critical function and/or characteristic proof-ofconcept TRL 2 Technology concept and/or application formulated TRL 1 Basic principles observed and reported

Ph.D. complementary partnership

LSBB

Original promoter of the project
 Provides a well-adapted environment for muography

IRIS Instruments

Expertise in industrialization

Build bridges between the different muographic projects

BRGM

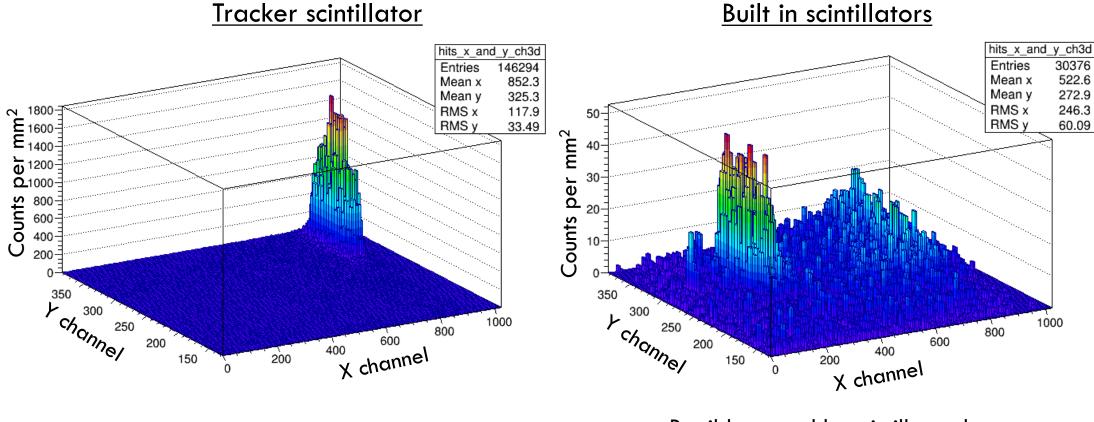
National geological survey with vocation of developing new techniques and methodologies for better understanding the subsurface

Potential user of the technology



CONSIDERATIONS TOWARDS INDUSTRIALIZATION

Importance of a reliable trigger



Histograms with the detected events per mm² for different positions

Possibly caused by scintillator damage during transport or operation



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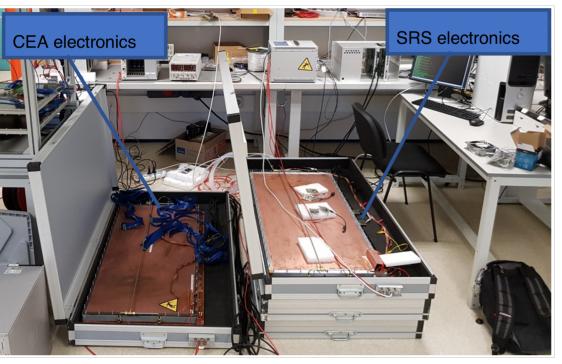
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CONSIDERATIONS TOWARDS INDUSTRIALIZATION Electronics alternatives



Experimental setup overview for the electronics comparison.

Different tested electronics and configurations

2 independent acquisitions, SRS triggered by 2 scintillator coincidence and DREAM self-triggered by signal over threshold

Trigger signal from 2 scintillators in coincidence mode propagated to SRS and DREAM simultaneously

- Dream self-trigger signal propagated to SRS
- All test concluded with successful data acquisition
- A thorough analysis was not possible due to:
- Operational parameters optimized for SRS and cloned for CEA

Needs data format adaptation



CONCLUSIONS

The technology MUST² is a useful tool for the direction-sensitive measurement of the muon flux
 The test beam results allowed a good characterization of the performance of the camera
 The outdoor measurements have validated the field transportability and reliability
 But gain temperature dependence and only 2 cm water level variation

 \checkmark Possibility to do long term campaigns, need to improve the data management and analysis

 \checkmark The track reconstruction algorithm has room for improvement in order to enhance the robustness of the results



OUTLOOK - SHORT TERM GOALS

Further development is required :

 \checkmark Control the long term stability of the gain

> Dynamic control of the camera gain as a function of the temperature

Remove Blind spots from the reconstruction algorithm

New approach for data analysis

✓ Software capable of live data acquisition/analysis

 \checkmark Minimize the heterogeneity of the camera

Modification of the current design







OUTLOOK — FUTURE OF THE PROJECT

 Construction and deployment at the LSBB of a network of 20 autonomous cameras integrating all the improvements (funded by FEDER LSBB2020)

✓ Versatile setup configurations for experiments:

>Monitoring: network of stand-alone cameras

Deep measurements: clustered cameras

>Multilayer operation: stacked

Scatter measurements: tracker upstream/downstream object (different scales)



ACKNOWLEDGEMENTS





Géosciences pour une Terre durable





















Saint-Saturnin-lès-Apt









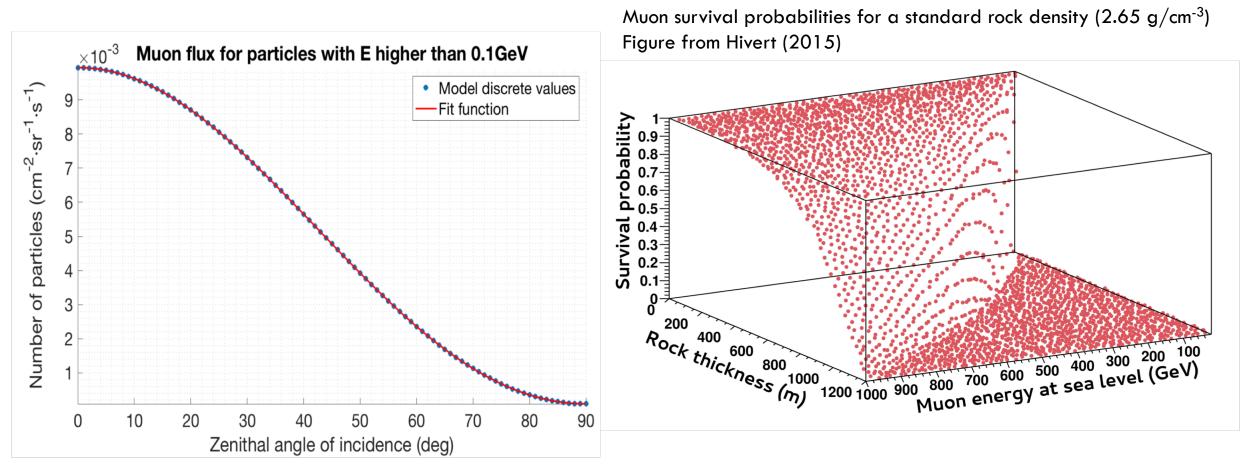
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Underground muon flux

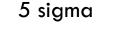


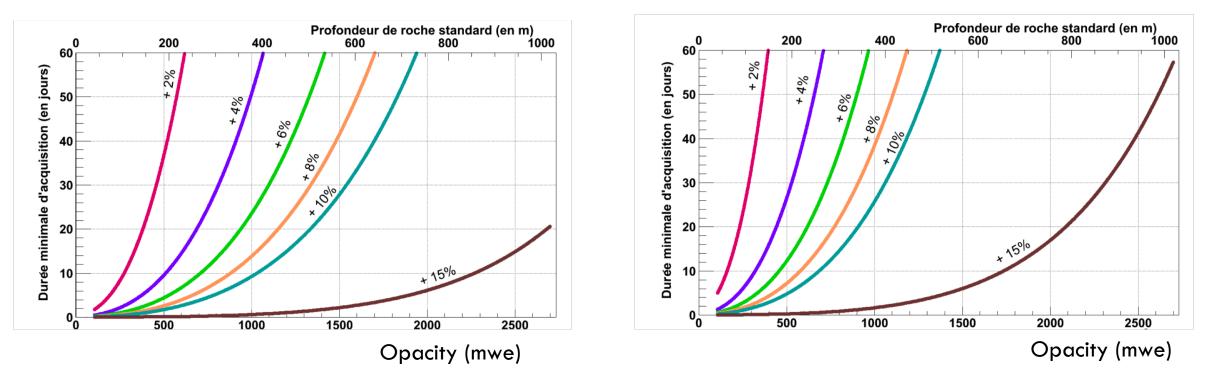
Muon flux integrated over energy at sea level as a function of the zenith angle.



Estimating the integration time

3 sigma

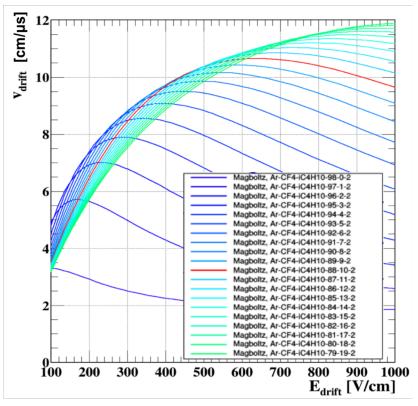




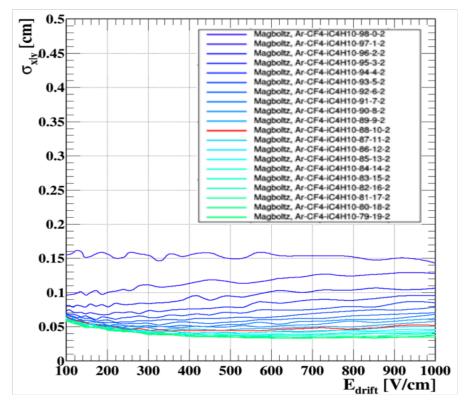
Active surface of 1m², angular acceptance 10° Figures from Hivert (2015)



Simulation results for electron mean drift velocity as a function of the drift electric field.



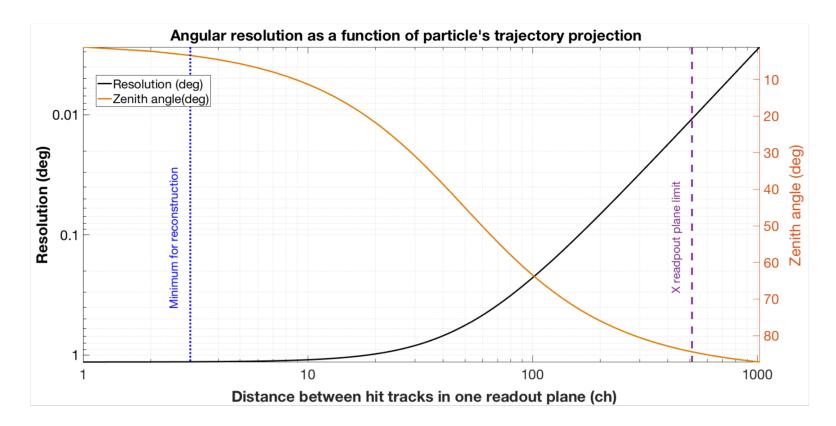
Simulation results for transverse diffusion as a function of the drift electric field.



Figures obtained with MAGBOLTZ code.

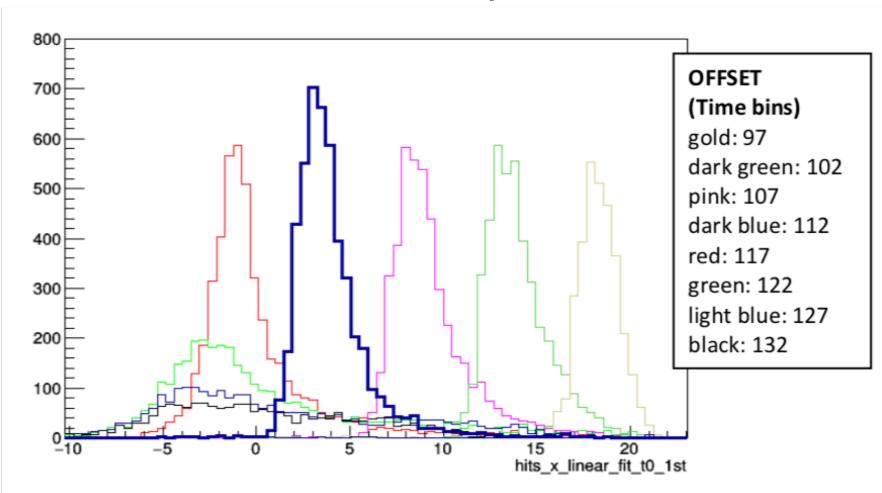


Angular resolution of the MUST² camera as a function of the muon's trajectory projection over the readout plane.

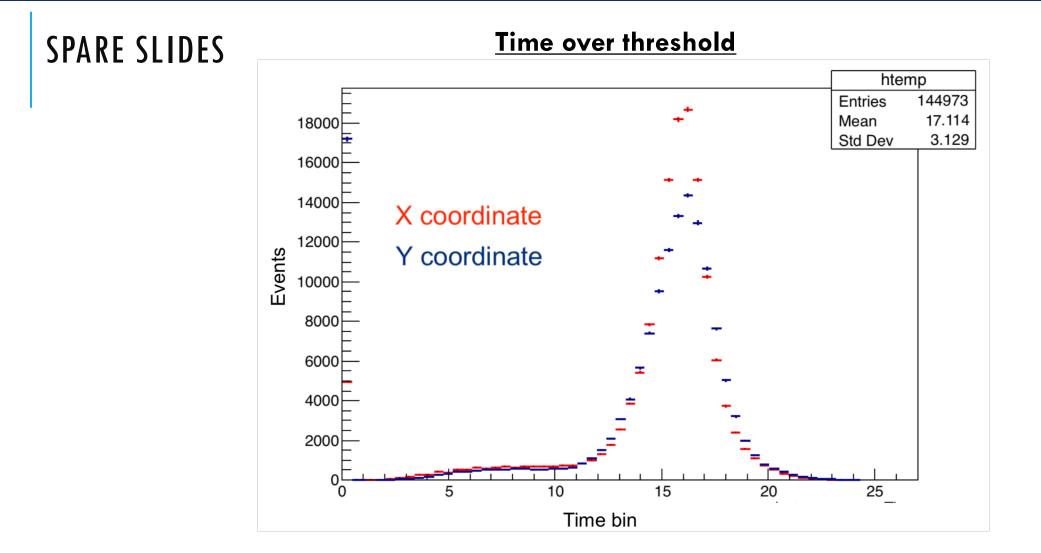




Electronics latency





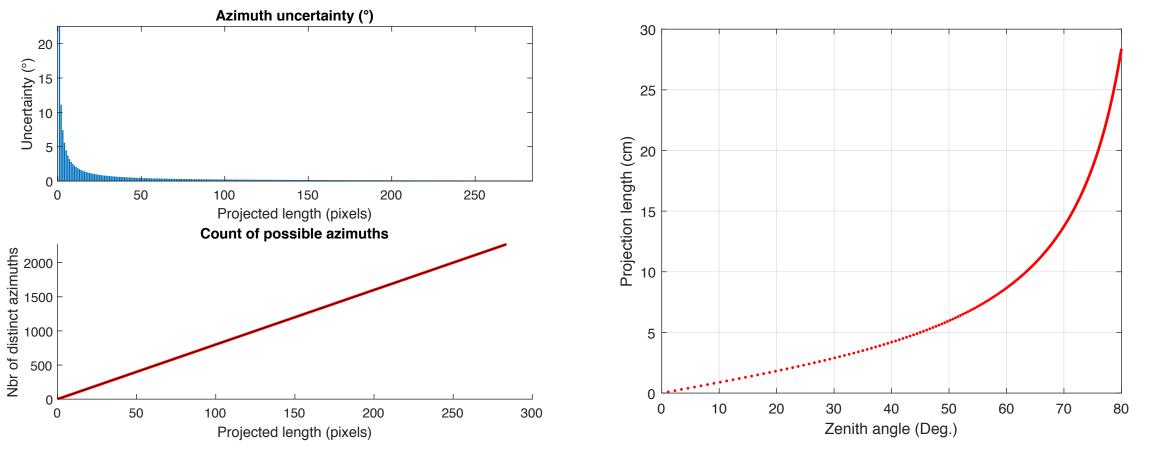


The value of $17,114\pm3,129$ time slots corresponds to $427,85\pm78,22$ ns, in good agreement with the value stumated with the theoretical drift speed.



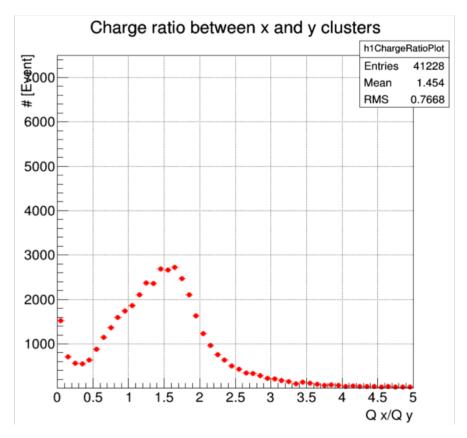
Angular resolution of the MUST² camera as a function of the muon's trajectory projection over

the readout plane.





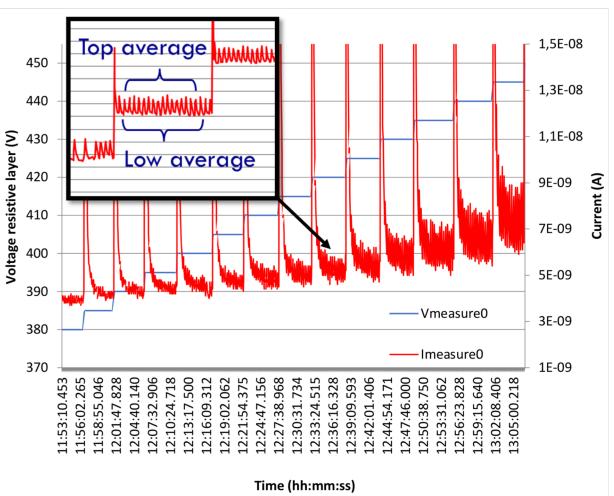
Charge ratio between readout layers



Charge is computed as the total sum of all ADC counts during 675 ns.



Current and voltage of the resistive layer during the test beam



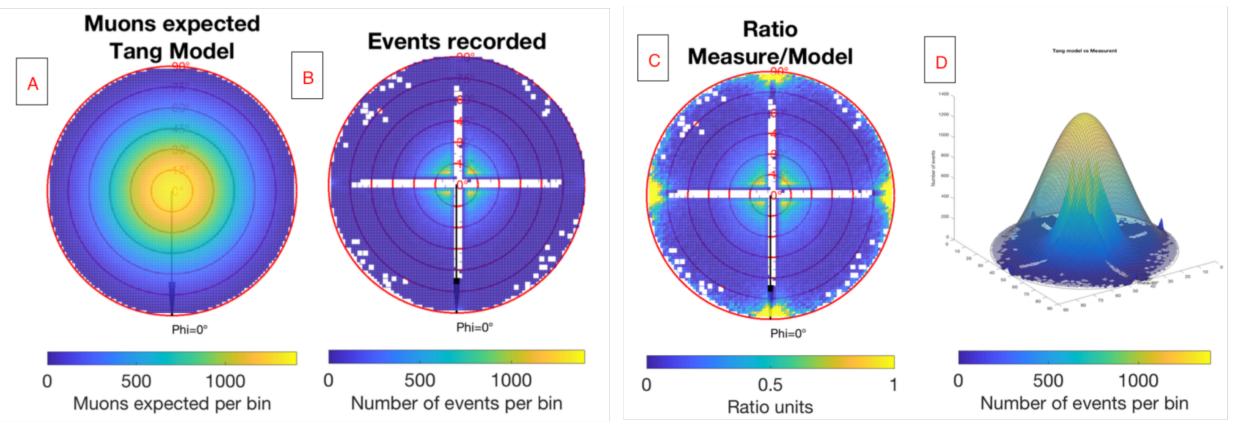
$$Gain = \frac{\Delta I}{N_T \cdot d \cdot {}^{\mu} / {}_S \cdot charge \ of \ e^-}$$

The number of produced electrons depends on the muon incident angle.

Two independent gain scans with different angles



Polar chart of the muon arrival distribution for the Tang model and experimental measurements.



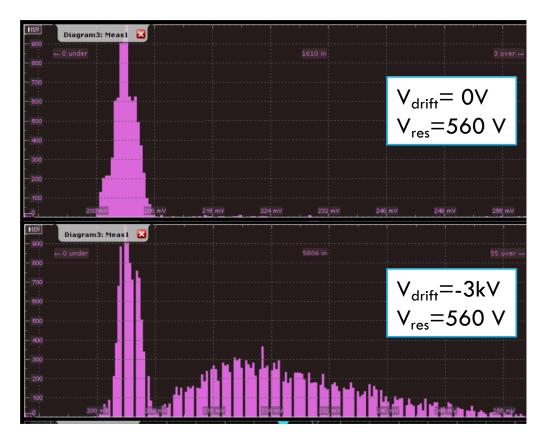


Isolated micromesh

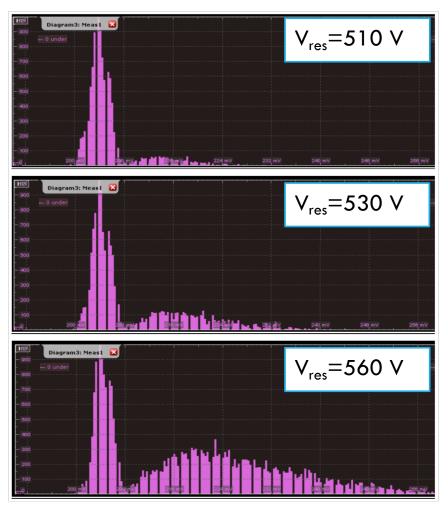




Trigger from the mesh test



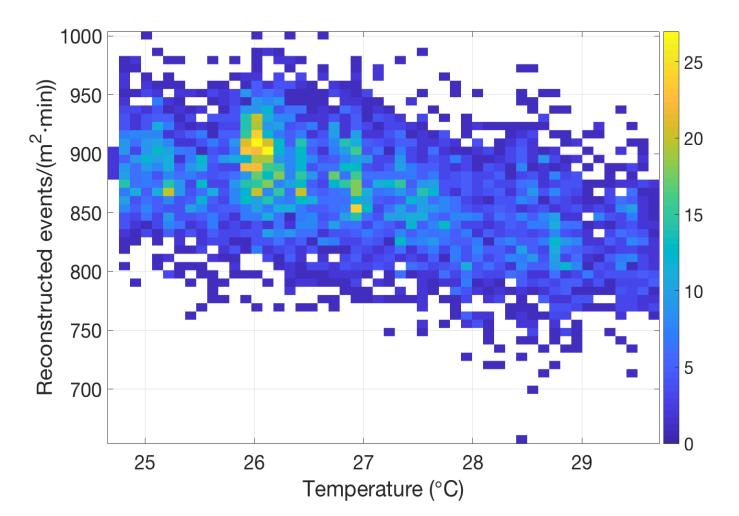
Signal apparition associated to the activation of the TPC



Signal amplitude modification as a function of the gain



Influence of temperature in the reconstructed muon flux





Environmental parameters during acquisition

