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#### REVIEW ON RECENT WORKS ON VORTICES IN SUPERCONDUCTORS

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Résumé.- On passe en revue : a) les solutions numériques de la théorie de Gorkov pour le réseau ideal de vortex dans le domaine entier de champ et de température, et b) les solutions de la théorie de Ginzburg-Landau pour le réseau déformé et leurs applications à l'ancrage des vortex.

Abstract.- We review : a) the numerical solutions of Gorkov's theory for the ideal vortex lattice in the entire field-temperature plane, and b) the distorted-lattice solutions of the Ginzburg-Landau theory and their application to flux pinning.

1. THE IDEAL VORTEX LATTICE. - Following Gorkov's extension of the microscopic BCS theory of superconductivity /1/ the properties of the ideal flux line lattice (FLL) initially were calculated for about 15 years only in the special cases  $t = T/T_c \approx 1$  (Ginzburg-Landau (GL) and Neumann-Tewordt approximations) and  $b = B/B_{c2} \approx 1$  (linearized Gorkov theory). Solutions for the entire temperature-induction range have been obtained only recently using two numerical methods (I and II), which complement each other. This is visualized in figure 1 and in table I.



Fig. 1 : Range of validity in the temperature-induction-plane of various solution methods for Gorkov's equations

Method I, developed mainly by L. Kramer and W. Pesch, uses Eilenberger's energy-integrated Green functions of the electrons /2/. This version of Gorkov's theory applies to arbitrary electron mean free path, &. It is suitable for calculations of the thermodynamic /3,4,5/ and transport /6/ properties and the density of states /5,7/ of type-II superconductors. Since this method requires a large numerical effort /8/ it has been applied so far only to rotationally symmetric solutions. i.e. to the isolated vortex or, within a circular cell method, to the FLL with sufficiently large lattice spacing,  $d \gg Min(hv_{\rm F}/\pi kT, \ell)$ .

Method II, developed by the author, starts from Gorkov's free energy expression for clean superconductors ( $\ell = \infty$ ) and extends the BPT-approach /9-12/ to arbitrary induction. The Green functions are eliminated analytically using the spatial periodicity of  $|\Delta|$  (energy gap) and H (magnetic field). The resulting free energy is an explicit functional of  $|\Delta|$ and H and may be minimized by a Ritz variational method. We use a finite Fourier series with 5 independent coefficients as a trial function for H, and various periodic trial functions for  $|\Delta|^2$ . This method yields  $\Delta$ , H, and the magnetization curves with good accuracy even on a small computer.

We summarize some of the results :

The magnetic field of an isolated vortex at low temperatures exhibits a rather narrow and high peak at the vortex center. Such a sharp peak, degenerating even to a cusp at T = 0, was first calculated by Delrieu /13,14/ for a clean superconductor near H ... He found that the Fourier coefficients of H decrease slowly, as  $|\underline{K}|^{-3}$  where <u>K</u> is a reciprocal FLL vector, and to have alternating signs. The saddle points and the minima of H interchange their positions at t = 0.62 for the clean superconductor. At t = 0, H is zig-zag-shaped along the nearest neighbor directions. Method II confirmed this surprising behavior in the large induction range 0.5  $\stackrel{<}{_{\sim}}$  b < 1. At b  $\stackrel{\sim}{_{\sim}}$  0.5 the sharp minima of H almost touch the plane H = 0 and then flatten out. A further interesting result is that some of the Fourier

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Table I

	METHOD I	METHOD II	
STARTS FROM	ENERGY-INTEGRATED GREEN FUNCTIONS	FREE ENERGY FUNCTIONAL FOR PERIODIC $ \Delta $ AND H	
APPLICABLE TO	ALL MEAN FREE PATHS, STATIC AND TRANSPORT PROPERTIES	ONLY PURE MATERIALS (?) ONLY STATIC PROPERTIES (?)	
SOLUTION METHOD	SOLVES SYSTEM OF DIFF. EQS.	RITZ VARIATIONAL METHOD	
COMPUTATIONAL EFFORT	LARGE	MODEST	
FORM OF SOLUTIONS	CIRCULAR CELL	PERIODIC TRIAL FUNCTIONS	
INDUCTION RANGE	SMALL INDUCTIONS	ARBITRARY INDUCTION	
$\begin{tabular}{lllllllllllllllllllllllllllllllllll$	YES YES YES NO NO YES NO	NO NO YES YES YES YES YES YES	

coefficients of H are negative at b = 1 but become positive as b is lowered. Their vanishing at a certain value of b should be observable by neutron diffraction.

The gap parameter is found by both methods to exhibit a narrowing of the vortex core at very low t. This effect is most pronounced at small b and was investigated in more detail in /15,16/, where it was found that in a clean superconductor at t = 0 the slope  $d|\Delta|/dr$  becomes infinite at the vortex core. For the spatial average of  $|\Delta|^2$  method II gives the simple relationship  $<|\Delta|^2 > /\Delta_{BCS}^2 = 1-b \pm 0.05$ for all values of b, t, and for all GL-parameters K.

In the magnetization curves a first-order phase transition occurs at the penetration field  $H_{c1}^{\prime}$  in low- $\kappa$  clean materials. This is consistent with experiments. The curves B(Ha) (Ha is the applied field) obtained by method II and shown in figure 2 have a slightly S-shaped, almost vertical part from which H'1 and the induction jump B are determined by a Maxwell construction or by equating the area under the curve to  $\mu_{0,c}^{H^2}$ . A small change in the curves  $B(H_a)$  can, therefore, result in a large change of B, even if H' is almost unchanged. A quantitative agreement with experimental values for B, which have been measured with high accuracy by decoration, magnetic and neutron scattering experiments /17/, cannot be expected, mainly since the calculation is based on the simple BCS-model-interaction between electrons on a spherical Fermi surface and thus neglects "real metal effects".



Fig. 2 : Magnetization curves of a type-II superconductor at t = 0.5 for various values of κ. The dashed lines belong to metastable states

Finally we remark on cubic FLLs and on "FL attraction", an interpretation of the first order transition at  $H'_{cl}$ . These features have been of great interest, since they are clearly seen in some experiments on low- $\kappa$  material, but could be explained by GL theory. Several authors tried to derive Fl attraction analytically from the Gorkov equations and, at the same time, explain its origin. The numerical methods yield the attraction but do not give a simple explanation for it. The analytical calculations showed that a field reversal of the iso-

lated FL is not necessary for FL-attraction. It also would give too large a value for the equilibrium distance if the neighboring FL is assumed to sit in the field minimum. It is rather an additional potential term which compensates the magnetic repulsion and leads to a net attraction of FLs. This term, which may be called the "gap parameter", "core", or "condensation energy" attraction, is present even in the GL theory. For  $\kappa > 1/2^{1/2}$  it is always smaller than the repulsive term, but at  $\kappa = 1/2^{1/2}$  it exactly compensates the magnetic repulsion such that all FLconfigurations have equal free energy. For  $\kappa$  close to  $1/2^{1/2}$  any small correction to the GL free energy could possibly lead to a domination of the attractive term.

A similar statement holds for the symmetry of the FLL : the GL-theory and method II yield a stable triangular FLL for all values of b,  $\kappa$ , t. However, the difference in the free energies of the cubic and hexagonal symmetries is extremely small. Any small additional energy term could, therefore, suffice to stabilize the cubic lattice. Such a term, for example, may arise from coupling between the FLL and an anisotropic crystal lattice, but, as observed recently, a cubic FLL may occur also in a hexagonal matrix /18/.

2. ON A RIGOROUS TREATMENT OF FLUX PINNING .- Very recently some progress has been made towards a rigorous treatment of flux pinning at imperfections of the crystal lattice. As pointed out in various review articles /19-24/ there is still a discrepancy between experimental values of the volume pinning force P<sub>u</sub> obtained, for example, from flux-density gradients or from critical currents, and theoretical values obtained by a statistical summation of elementary pinning forces estimated from GL theory. This discrepancy may amount to several orders of magnitude if P<sub>v</sub> itself is compared and not, as is often done, just its square root. A particularly troublesome problem is the theoretically predicted but experimentally unobserved threshold for the elementary pinning forces, below which summation theories yield  $P_v = 0$ . Furthermore, the observed dependence of P $_{
m V}$  on magnetic history is not explained by existing summation theories /21/. These challenging problems are still unsolved, and a rigorous treatment starting from GL theory seems to be required. The work reviewed here is one step in this direction.

Up to the present, nearly all theoretical work on flux pinning used the concept of individual flux lines (FLs) interacting with each other and with the pinning centers by a two-body interaction. This picture is very useful. It can be derived from GL theory for sufficiently low induction. The interaction between FLs turns out to be composed of a magnetic repulsion and a condensation-energy attraction, which is most important for small  $\kappa$  /25,26/. Unfortunately, the interacting-FL picture breaks down as soon as the vortex cores begin to overlap. This happens already at rather low inductions b  $\frac{1}{2}$  0.3 as can be seen from figure 3 in reference /26/. In contrast to widespread opinion, this breakdown also occurs in superconductors with large K. The proper range of validity for the London model is, therefore, b  $\ll$  1 and not  $\kappa \gg$  1 (if the generalized interaction potential is used).



Fig. 3 : a) The elastic matrix component  $\tilde{\phi}_{xx}(k,0,0)$ . b) The compressional modulus  $c_{\mu}(k) = n\tilde{\phi}_{xx}(k,0,0)/k^2$ . Arbitrary units. Dashed lines : local continuum, dotted lines : lattice with short range forces, solid lines : FLL with  $k_{\rm B}/k_{\rm h}$  = 4 corresponding to  $\kappa$  = 4, b = 0.4, or  $\kappa$  = 0.9, b = 0.75

A rigorous treatment of the pinning problem /27-31/ should start from a free energy functional of the form /28/

$$= F_{o} + F_{1} + F_{d}$$
(1)

F

where  $F_0$  describes the homogeneous material and in the following shall be chosen as the GL functional;  $F_1$  is the perturbation caused by inhomogeneitis, and  $F_d$  introduces a driving force causes, e.g., by a transport current. In what follows we omit all surface phenomena by considering an infinite FLL, and we assume the perturbations  $F_1$  and  $F_d$  to be small. In principle the solutions  $\Psi$  (GL function) and <u>A</u> (vector potential) could be obtained by standard perturbation methods using an expansion in terms of some eigenfunctions. We do not follow this path but

rather use a perturbation method which retains, and thereby generalizes, the useful concepts of "FL positions" (defined as the zeros of  $\Psi$  and denoted by  $\underline{r}_{\downarrow}$  where  $\nu$  is a FL index, or by  $\underline{r}_{\downarrow}(z)$  for bent FLs, where z is a line parameter for which we choose the coordinate z along  $\underline{H}_{a}$ ) and "Force densities on FLs" (denoted by  $\underline{P}_{\nu}$  or by  $\underline{P}_{\nu}(z)$ , a force per cm). Both vectors  $\underline{r}_{\nu}(z)$  and  $\underline{P}_{\nu}(z)$  have only two independent components since we deal with lines.

The main trick of our method is the introduction of the "distorted-lattice solutions"  $\Psi_s$  and  $\underline{A}_s$ . They are defined as the solutions which minimize the unperturbed functional  $F_o$  with the constraint that  $\Psi_s$  have first order zeros along the FL positions  $\underline{r}_v(z)$ . After insertion of  $\Psi_s$  and  $\underline{A}_s$  the free energy functional (1) reduces merely to a function of all FL positions  $\underline{r}_v$  (or to a functional of the  $\underline{r}_v(z)$  if the FLs are bent). The minimization of F with respect to the FL-positions is equivalent to solving the force balance equation (virtual displacements !)

$$\frac{dF_{o}}{d\underline{r}_{v}(z)} + \frac{dF_{1}}{d\underline{r}_{v}(z)} + \frac{dF_{d}}{d\underline{r}_{v}(z)} =$$

$$-\underline{p}_{v}^{el}(z) - \underline{p}_{v}^{pin}(z) - \underline{p}_{v}^{driv}(z) = 0 \qquad (2)$$

for all values of v and z. Here the first term reproduces the normal definition of the elastic force, the second term defines the pinning force, and the last term is the driving force per unit length of each FL element.

3.- THE DISTORTED-LATTICE SOLUTIONS.- Until recently, solutions of the GL equations for a distorted FLL were known only for low inductions, where  $|\Psi|$  is essentially constant, H is a linear superposition of isolated vortex fields, and the free energy is a sum over the two-body interactions between FLs (or FL-elements if bending is allowed). At larger inductions, only periodic solutions were known. Periodic solutions, as a matter of principle, do not tell anything about the inhomogeneously distorted lattice. Furthermore, they cannot give the forces on each FL in the FLL, but these are required in order to calculate the strain caused by a pinning center. The force on one FL has to be calculated from the free energy of a FLL in which the given FL is slightly displaced.

One, therefore, needs distorted-lattice solutions which apply to the entire induction range 0 < b < 1. We find these by the following method /28/: first, we calculate the correction to the perriodic solutions  $\Psi_o$  and  $\underline{A}_o$  linear in the displacements  $\underline{s}_V(z) = \underline{r}_V(z) - \underline{R}_V$  from the regular positions  $\underline{R}_V = (X_V; Y_V; z)$ . For convenience we do this for periodic displacement fields,  $\underline{s}_V(z) =$ 

 $\operatorname{Re}\{\underline{s}_{o} \exp(i\underline{k}\underline{R}_{v})\}\$ ; the generalization to non-periodic displacements is by linear superposition. A divergence at  $k/(1-b) \rightarrow 0$  is removed by means of the nonlinear terms in the GL equations. In the results for  $\Psi$ , <u>A</u> and F appear two characteristic wave vectors,

$$k_{\Psi}^2 = (1-b)2/\xi^2 = k_B^2(1-b)/b$$
, (3)

$$k_{h}^{2} = \langle |\Psi|^{2} \rangle / \lambda^{2} % k_{\Psi}^{2} / 2\kappa^{2} ,$$
 (4)

where  $\xi$  is the coherence length,  $\lambda = \kappa \xi$ , and  $k_B = (2b)^{1/2}/\xi$  is the radius of the circularized Brillouin zone (BZ). The results can be transcribed into expressions which apply even to large displacements if the strain is small, e.g.,

$$|\Psi(\underline{\mathbf{r}})| = |\Psi_{0}(\underline{\mathbf{r}})| [1 + \frac{b}{2\xi^{2}} \sum_{\underline{K}} \operatorname{Re} \{ \frac{\underline{i}\underline{s}_{0}(\underline{k}+\underline{K})}{k_{\Psi}^{2} + (\underline{k}+\underline{K})^{2}} e^{\underline{i}(\underline{k}+\underline{K})\mathbf{r}} \} ]$$
  
+  $0(\underline{s}_{0}^{2}) \cdot (5)$ 

becomes :

$$|\Psi(\underline{\mathbf{r}})| = |\Psi_{0}(\underline{\mathbf{r}}-\underline{\mathbf{s}}(\underline{\mathbf{r}}))|(1 + \frac{b}{2\xi^{2}}, \frac{\operatorname{div} \underline{\mathbf{s}}(\underline{\mathbf{r}})}{k_{\Psi}^{2} + k^{2}}) + 0(\underline{\mathbf{k}}^{2}, \underline{\mathbf{s}}^{2}_{0}).$$
(6)

where  $\underline{s}(\underline{r}) = \operatorname{Re}\{\underline{s}_{0} \exp(i\underline{k}\underline{r})\}\$  and  $k = |k| < 0.7 k_{B}$ .

As a next step, the corresponding expressions are calculated for the limit  $b \ll 1$ . They turn out to be very similar to the results for  $b \gtrsim 1$  if appropriate representations are chosen. The high induction results approximately apply, therefore, to the entire induction range 0 < b < 1. One can quite generally state that extensions to low b of results derived at high b give ordinarily much better approximations than extensions of the London model to larger b.

Looking carefully at the small-strain results, one finds that they can be reproduced from the following more transparent expressions, which we assume to approximately apply to arbitrary distortions (if b,  $\langle |\Psi|^2 \rangle$ ,  $k_{\Psi}$ , and  $k_h$  are allowed to vary spatially) and to arbitrary b and  $\kappa$  ( $\phi$  is the phase of  $\Psi$ ) :  $|\Psi(\underline{\mathbf{r}})|^2 =$  $\langle |\Psi|^2 \rangle \cdot \exp\{\frac{b}{1-b}\} \prod_{\mathcal{V}} \exp\{-\int dz \frac{\exp[-|\underline{\mathbf{r}}-\underline{\mathbf{r}}_{\mathcal{V}}(z_{\mathcal{V}})|k_{\Psi}]}{|\underline{\mathbf{r}}-\underline{\mathbf{r}}_{\mathcal{V}}(z_{\mathcal{V}})|}\},$ (7)

grad 
$$\phi(\underline{\mathbf{r}}) = \operatorname{rot} \sum_{v} \oint d\underline{\mathbf{r}}_{v} \frac{1}{2|\underline{\mathbf{r}}-\underline{\mathbf{r}}_{v}|},$$
 (8)  

$$\underline{\mathbf{H}}(\underline{\mathbf{r}}) = \sum_{v} \oint d\underline{\mathbf{r}}_{v} \frac{\phi_{o} \mathbf{k}_{h}^{2}}{\mu_{o}^{4\pi}} \frac{\exp\{-\left[(\underline{\mathbf{r}}-\underline{\mathbf{r}}_{v})^{2} + \xi^{2}/2\right]^{1/2}\}}{\left[(\underline{\mathbf{r}}-\underline{\mathbf{r}}_{v})^{2} + \xi^{2}/2\right]^{1/2} c},$$
 (9)

where  $C \lesssim 1$ . Equations (7) to (9) reduce to the correct solutions in all special cases investigated so far, (7) and (8) exhibit the correct singularities along the FLs, and (9) satisfies div <u>H</u> = 0. These expressions should be useful trial functions in numerical calculations going beyond linear elasticity theory.

4. THE ELASTIC RESPONSE OF THE FLL.- The elastic energy of the strained FLL has the general form

$$F_{e1} = \frac{1}{2} \int_{BZ} \frac{dk_x dk_y}{4\pi^2 n} \int \frac{dk_z}{2\pi} \frac{dk_z}{2\pi} \{\tilde{\phi}_{xx} |\tilde{s}_x|^2 + \tilde{\phi}_{xy} (\tilde{s}_x \tilde{s}_x + \tilde{s}_x \tilde{s}_y) + \tilde{\phi}_{yy} |\tilde{s}_y|^2\}, \quad (10)$$

where n =  $B/\varphi_{0},~\widetilde{\varphi}_{\alpha\beta}(\underline{k})$  is the elastic matrix of the FLL,

$$\widetilde{\underline{s}}(\underline{k}) = \sum_{v} \int dz \, \exp\{i(k_{x}X_{v} + k_{y}Y_{v} + k_{z}z)\} \, \underline{s}_{v}(z) \, (11)$$

=  $(\tilde{s}_x; \tilde{s}_y; 0)$  is the Fourier transform of the displacement field,  $\tilde{\phi}_{\alpha\beta}(\underline{k})$  and  $\underline{\tilde{s}}(\underline{k})$  are periodic in the  $k_x - k_y$ -plane, and the integration is over the first BZ of the FLL. For the FLL with hexagonal symmetry one has within local elasticity theory

$$\widetilde{\phi}_{\alpha\beta}(\underline{k}) = \frac{1}{n} \left\{ \begin{array}{c} c_{11} k_x^2 + c_{66} k_y^2 + c_{44} k_z^2 ; & (c_{11} - c_{66}) k_x k_y \\ (c_{11} - c_{66}) k_x k_y ; & c_{66} k_x^2 + c_{11} k_y^2 + c_{44} k_z^2 \end{array} \right\}$$
(12)

where  $\rm c_{11}$  is the uniaxial compressional modulus,  $\rm c_{66}$  the shear modulus, and  $\rm c_{_{44}}$  the tilt modulus of the FLL.

Equation (12) applies to a FL continuum. For a discrete lattice with nearest neighbor interactions, the parabolae  $k_x^2$  and  $k_y^2$  are replaced by periodic functions of the type  $[(2/d)\sin(kd/2)]^2$ , and the local approximation (12) still applies if  $k \ll k_B \sim \pi/d$ , i.e., if the strain varies slowly over the lattice spacing d. For the FLL with moderate or large b or  $\kappa$  the interaction is of long range, and the picture changes completely as shown in figure 3. The correct GL-result for  $\tilde{\phi}_{\alpha\beta}^-$  a simple sum (for b  $\ll$  1) or a double sum (for b  $\sim$  1) over reciprocal FLL vectors - may be approximated for k < 0.7  $k_B$  by an expression similar to equation (12) but with  $c_{11}$  and  $c_{\mu\mu}$  replaced by functions of  $k = |\underline{k}|$  :

$$c_{11}(k) = B^2 \frac{dH_a}{dB} \frac{1}{(1 + k^2/k_h^2)(1 + k^2/k_{\Psi}^2)}$$
(13)

$$c_{44}(k) = \frac{B^2}{\mu_0} \frac{1}{1 + k^2/k_h^2} + B (H_a - B/\mu_0)$$
 (14)

and with unchanged shear modulus  $c_{66} \approx B^2 (dH_a/dB)$ (1-b)<sup>2</sup>/10b $\kappa^2$ . Equations (13) and (14) and the modified equation (12) apply to arbitrary b and  $\kappa$  and are called the "continuum" or "isotropic" approximation.

Our results show that for the FLL local elasticity theory applies only if  $k \ll k_h$ , i.e. if the strain varies slowly over the length  $\lambda/(1-b)^{1/2}$ , which may be much larger than  $d = 2.7 \ \lambda/\kappa b^{1/2}$ . As <u>k</u> goes from 0 to  $k_B$ ,  $c_{11}$  (k) and  $c_{44}$  (k) decrease by factors  $k_h^2 k_\psi^2 / k_B^2 = (1-b)^2 / 2b^2 \ \kappa^2$  and  $2k_h^2 k_B^2 = (1-b) / b \kappa^2$ , respectively. The correct lattice sums for  $\delta_{\alpha\beta}(\underline{k})$  yield an even larger decrease of the FLL stiffness and also exhibit a pronounced anisotropy close to the BZ boundary.

The compliance  $1/\tilde{\phi}_{xx}(k,0,0)$  is sharply peaked at the BZ boundary. As a consequence, planar pinning forces yield a weakly damped oscillatory displacement field, with amplitude usually much larger than the constant strain superimposed to it /30/. This surprising result follows even from the London model. It means that, close to a planar pinning center, neighboring FLL planes are shifted in opposite direction.

The dispersion of the compressional and the tilt moduli has a large effect on the maximum value of the elastic FL displacements caused by local pinning forces. This is shown in table II for planar forces, line forces parallel and perpendicular to the FLs, and for point forces. The results of the previous ( $S_L$ ) and the present ( $S_{NL}$ ) theories may differ by several orders of magnitude ; they coincide only for line forces parallel (more precisely : at an angle less than ( $c_{cc}/c_{ut}$ )<sup>1/2</sup>  $\gtrsim$  (1-b)/3K) to the FLs.

The linear elastic behavior of a lattice of straight FLs can be reproduced to good accuracy by the induction-dependent potential

$$\nabla(\mathbf{r}) = \frac{\phi_0 k_h^2}{\mu_0 2\pi} \left[ \mathbf{K}_0(\mathbf{k}_h \mathbf{r}) - \mathbf{K}_0(\mathbf{k}_{\Psi} \mathbf{r}) \right]$$
(15)

between FLs, where  $r = |\underline{r}_{v} - \underline{r}_{u}|$  and  $K_{o}$  is the Hankel function. This means that for small strain the FLL behaves as if the FLs interact by the twobody potential (15) composed of a magnetic repulsion of range  $\lambda/(1-b)^{1/2}/32/$  and a "core attraction" of

Table II

TYPE OF PINNING FORCE	MAXIMUM FL. DISPLACEMENT		CORRECTION FACTOR $S_{NL}^{}/S_{L}^{}$		
	s <sub>L</sub>	s <sub>NL</sub>	GENERAL EXPRESSION	EXAMPLE $\kappa = 1.5$	$b = 0.8$ $\kappa = 30$
PLANAR FORCE PAIR δ(x-D) - δ(x+D)	$\sim \frac{1}{c_{11}} \sim \frac{1}{b^2}$	$\sim \frac{\kappa^2}{(1-b)^2}$	$1 + \frac{d}{D} \kappa^2 \left(\frac{b}{1-b}\right)^2$	100	40000
LINE FORCE PARALLEL δ(x) δ(y)	$\sqrt{\frac{1}{c_{66}}} \sim \frac{\kappa^2}{b(1-b)^2}$	$\sqrt{\frac{\kappa^2}{b(1-b)^2}}$	1	1	1
LINE FORCE PERPENDICULAR δ(x) δ(z)	$\sim \frac{1}{\sqrt{c_{11} c_{44}}} \sim \frac{1}{b^2}$	$\sim \frac{\kappa^2}{\sqrt{b} (1-b)^{3/2}}$	$1 + \frac{2\kappa^2}{3 \ln(D/d)} \left(\frac{b}{1-b}\right)^{3/2}$	10	4000
POINT FORCE δ(x) δ(y) δ(z)	$\sim \frac{1}{\sqrt{c_{66} c_{44}}} \sim \frac{\kappa}{b^{3/2} (1-b)}$	$\sim \frac{\kappa^2}{b(1-b)^{3/2}}$	$1 + \frac{\kappa}{\sqrt{2}} \left(\frac{b}{1-b}\right)^{1/2}$	3	50

range 0.7  $\xi/(1-b)^{1/2}$ . This potential could be used to calculate, at least approximately, some nonlinear elastic properties of the FLL.

5. PINNING FORCES.- As an example, we illustrate the pinning forces derived from the above theory for the case of a point pinning center with diameter  $\lesssim \, \xi \, \text{and}$ with position  $\underline{a} = (a_x; a_y; a_z)$ . A general expression for the perturbation energy of such a defect is

$$F_{1} = \alpha_{0} |\Psi|^{2} + \frac{1}{2} \beta_{0} |\Psi|^{4} + \gamma_{0} |(\frac{\nabla}{i\kappa} - \underline{A})\Psi|^{2} + \frac{\mu_{0}H}{i\kappa} + \frac{1}{2} \chi_{0} H^{2}$$
(16)

where  $\Psi = \Psi(\underline{a})$ ,  $\underline{A} = \underline{A}(\underline{a})$ , and  $\alpha_0$ ,  $\beta_0$ ,  $\gamma_0$ ,  $\underline{\mu}_0$ ,  $\chi_0$  are constants. For small inductions we find (a) that  $\underline{P}_{(z)}(z)$  depends only on the distance  $|\underline{r}_{(z)}(z)-\underline{a}|$  between FL element and defect and (b) that all types of pinning forces can be derived from potentials which depend on this distance. These properties were expected and have been used in summation theories. At larger inductions b > 0.3 the character of pinning forces changes: The  $P_{(z)}(z)$  in general depend on  $r_{(z)}(z)$ and on a separately. The forces exhibit different behavior depending on the interaction type. This is shown in figure 4 : Magnetic forces ( $\mu_0 \neq 0$  or  $X_0 \neq 0$ ) still decrease monotonically with  $|\underline{r}_{i}(z)-\underline{a}|$  and still derive from a potential. But defects coupling to  $\Psi(\alpha_0 \neq 0, \beta_0 \neq 0, \text{ or } \gamma_0 \neq 0)$  are oscillatory functions of  $r_{ij}(z)$  and do not derive from a potential. In particular, the entire force field vanishes identically when the pinning center coincides with the



POSITION OF PINNING CENTER-

Fig. 4 : The force exerted by a point pinning center situated at  $\underline{r} = \underline{a}$  on the FL at  $\underline{r}_{,} = 0$ , plotted for three different types of interaction, equation (18). L.h.s. : The x-component of the force plotted versus a, for a = 0R.h.s. : <sup>y</sup>Lines of equal force in the <u>a</u>-plane

axis of any FL. This means that a pinning center located at a FL center does not exert a force on any FL if it couples to Y, but it repells or attracts all FLs (except the one it is sitting at) if it couples to H. This result is due to the fact that the general expression for  $|\Psi|$  is a product (7) of factors each of which has a zero along one FL, whereas H is the sum (9) of modified isolated vortex fields which decrease monotonically.

These results show that our concept of pinning forces, and of the elastic response of the FLL

to them, has to be modified at medium and large inductions.

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