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Sensitivity of lumped and semi-distributed hydrological models to 20 gridded precipitation products in a transboundary basin

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ABSTRACT

This study proposes a dual approach to assess 20 Gridded Precipitation Products (GPPs) within a transboundary region with complex topography. GPPs were first compared with observed precipitation to assess their spatio-temporal accuracy. They were then integrated into a lumped (GR4J) and a semi-distributed (MGB-IPH) hydrological model to evaluate their impact on streamflow simulations for three basins. Even if most GPPs effectively captured the dominant north–south precipitation gradient shaped by the Andean topography, the results show significant variations in GPP effectiveness across the considered basins. The most reliable GPPs for streamflow simulation across Katari, Ilave, and Ramis basins are MSWEP, CHIRPS, and MSWEP when considering the lumped GR4J model and SM2Rain_CCI, IMERG_FR, and SM2Rain_CCI when considering the semi-distributed MGB model. This discrepancy among the models shows that GPPs' reliability assessment is sensitive to the model structure and that different conclusions could be made according to the selected model. Our findings show that the GR4j lumped model is barely influenced by precipitation bias due to its buffering capacity. In contrast, the semi-distributed MGB-IPH model is sensitive to precipitation bias in space and time and therefore is more suitable to reveal GPP inconsistencies. Overall, this study not only provides GPP reliability feedback but also new insights on the respective limits and advantages of different assessment

31 methods (i.e., gauges, lumped and semi-distributed models). These findings support the development of a
32 practical framework for GPP selection according to the forecast use.

33 **1. Introduction**

34 Hydrological models are essential tools for water resources management and play a critical role in
35 shaping water governance strategies, particularly in transboundary basins where shared resources are subject to
36 differing national policies (Ter Horst et al., 2023; Sahu et al., 2023). Developing reliable models in these
37 contexts is especially challenging due to complex landscapes, limited availability of high-quality
38 hydrometeorological data, and the combined effect of policy differences, unequal technical capacity, and the
39 absence of formal data-sharing agreements (Nawaz et al., 2021; IWMI, 2021; Nguyen et al., 2018).

40 Accurate precipitation data are essential for hydrological modeling, yet mountainous and transboundary
41 regions—such as the Andean Altiplano—often suffer from sparse in situ observations (Satgé et al., 2019; De
42 Moraes Cordeiro & Blanco, 2021). To address these gaps, Gridded Precipitation Products (GPPs)—which
43 combine satellite data, ground-based observations, and reanalysis outputs—have become widely used and
44 continue to evolve through recent advances in remote sensing and artificial intelligence (Sun et al., 2018; Wang
45 et al., 2017; Zubieta et al., 2015; Ter Horst et al., 2023; Gao et al., 2023; Medrano et al., 2023). However, these
46 innovations also introduce new challenges for validation and calibration. Indeed, GPPs' reliability varies
47 considerably across environments due to the sensitivity of the retrieval methods to local climate, topography,
48 land surface emissivity, and land surface temperature contrast (Prat et al., 2021; Nwachukwu et al., 2020; Sun
49 et al., 2018; Prat et al., 2021; Cao et al., 2023; Satgé et al., 2021; Shiru et al., 2025), reinforcing the need for
50 context-specific assessments.

51 In South America, few studies have systematically evaluated the reliability of GPPs in the Andean
52 region. For instance, significant GPPs underestimation for intense rainfall events (Blacutt et al. 2015),
53 progressive decrease in GPPs estimates' reliability with increasing topographic slope (Satgé et al., 2016), and

54 lower GPPs performance across the wet than the dry region (Chen et al., 2022) were already reported.
55 Within the broader TDPS (Titicaca Desaguadero Poopó Salar) system, several studies have assessed GPPs'
56 reliability in comparison to gauge observations (Scheel et al., 2011; Quispe et al., 2023; Satgé et al., 2020)
57 and for climate (Torres-Batló & Martí-Cardona, 2020) and drought trends analysis (Satgé et al., 2017; Satgé
58 et al., 2019). Despite the known challenges, such as highly variable precipitation regimes and the influence of
59 orographic effects, research specific to the Lake Titicaca basin remains limited (e.g., Quispe et al., 2023;
60 Satgé et al., 2019; Medrano et al., 2023). Upon analyzing these studies, it appears that the best GPP can vary
61 significantly from one location to another, not only due to differences in the assessed GPPs but also because
62 of the specific gauge locations used as references, which are influenced by local environmental
63 characteristics.

64 Given that precipitation is a key input of hydrological models, it is essential to understand GPP's
65 hydrological applicability comprehensively. As of today, most hydrological modelling-based evaluations have
66 predominantly focused on either lumped (e.g., Beck et al., 2017; Jiang, 2019; Raimonet et al.; Maggioni et al.,
67 2013; Li et al., 2023; Andrade et al., 2024; Satgé et al., 2021), distributed (Gebrechorkos et al., 2024) or semi-
68 distributed (Tan et al., 2021; Zubieta et al., 2015; Dembélé et al., 2020) hydrological models. While lumped
69 models are widely used for their simplicity and low data requirements, their aggregated structure limits insights
70 into how GPPs capture spatial precipitation variability (Martel et al., 2020; Nguyen et al., 2023; Kling & Gupta,
71 2009; Wan et al., 2025). In contrast, semi-distributed models divide a basin into multiple sub-catchments, which
72 allows considering how GPPs capture precipitation spatial variability (Tan et al., 2021). Ideally, combining
73 both modeling approaches (i.e., lumped and semi-distributed) should provide a more robust assessment of
74 GPPs' performance; however, studies that integrate both lumped and semi-distributed models remain scarce. A
75 few exceptions include studies led in Iran (Jahanshahi et al., 2024) and China (Xu et al., 2014) assessing several
76 GPPs reliability for streamflow modeling using both lumped (HBV and Xinanjiang model, respectively) and
77 semi-distributed (SWAT) models. Similarly, GPPs' reliability for streamflow modeling was assessed in China,

78 considering both lumped (GR4J) and fully distributed (VIC) models (Guan et al., 2020). The evaluation
79 revealed that GPP reliability assessments were sensitive to the hydrological model considered, with
80 performance rankings differing between lumped and semi-distributed models.

81 The above-mentioned literature highlights the need for further research to comprehensively assess how
82 GPPs influence hydrological simulations under different model structures (lumped and semi-distributed),
83 particularly in the Andean region, where complex hydrological conditions and scarce observational data
84 complicate model evaluations. Moreover, Wan et al. (2025) pointed out that the influence of hydrological
85 model selection on streamflow simulations may be more significant in dry, high-elevation mountainous regions
86 than in wetter, lowland areas, highlighting the importance of considering regional characteristics when
87 assessing GPP performance.

88 In this context, our study assesses the reliability of 20 GPPs within the Lake Titicaca basin, a high-
89 altitude, transboundary catchment with distinct precipitation gradients, providing an ideal setting to evaluate
90 GPP applicability. For this purpose, GPPs are first assessed using ground-based rainfall observations to evaluate
91 their spatial and temporal accuracy. Next, we integrated them with two hydrological models—a lumped model
92 (GR4J) and a semi-distributed model (MGB-IPH)—to provide insights into the interaction between model
93 structure and precipitation uncertainty. Our study, focused on the South American Altiplano, presents a
94 comprehensive analytical framework applicable to a wide range of GPPs and replicable in other regions of the
95 world.

96 **2. Materials**

97 ***2.1 Study Area***

98 The Lake Titicaca Basin (57500 km²) is a key component of the TDPS (Titicaca, Desaguadero River, Lake
99 Poopó, and Coipasa Salt Lake) hydrological system that spans across Peru, Bolivia, and Chile (Fig.1) (Roche
100 et al., 1992). Lake Titicaca is the primary reservoir in a cascading system, where its waters flow through the
101 Desaguadero River into Lake Poopó and, ultimately, the Coipasa Salt Lake. The lake plays a crucial role in

102 maintaining the water balance and supporting the hydrological connectivity to downstream arid and semi-arid
103 regions (UNESCO, 2003; Satgé et al., 2021; Pillco Zolá et al., 2019; Canedo et al., 2016). With an average
104 water surface area of 8500 km² and a mean depth of 105 m, Lake Titicaca is the largest freshwater lake in South
105 America (Quispe et al., 2023; Pillco Zolá et al., 2019).

106 The Titicaca Lake basin is characterized by a tropical high-altitude climate with significant seasonal
107 variations. There is a pronounced wet season from December to March, followed by a long dry period from
108 April to November (Zubieta et al., 2021). The climate transitions from humid (around Lake Titicaca in the north
109 of TDPS) to semi-arid (near Lake Poopó) and arid (around Coipasa Salt Lake in the south), reflecting a strong
110 gradient in humidity. Temperatures generally range from 8°C to 10°C annually, dipping to around 4°C in winter
111 and rising to 12°C in summer. Lake Titicaca moderates the local climate, reducing the frequency and intensity
112 of frosts (Canedo et al., 2016; Medrano et al., 2023).

113 Considering the importance of Lake Titicaca and its basin within the TDPS system, our study initially
114 targets three pilot sub-basins (Katari, Ilave, and Ramis), chosen based on streamflow data availability. The
115 Ramis basin, covering an area of 14866 km², exhibits substantial variability in flow, with a coefficient of
116 variation (Cv) of 1.27. In comparison, the Katari basin, which spans 2519 km², has a narrower flow range but
117 a higher Cv of 2.06. Meanwhile, the Ilave basin, covering 7,720 km², has a broader flow range with a Cv of
118 1.91.

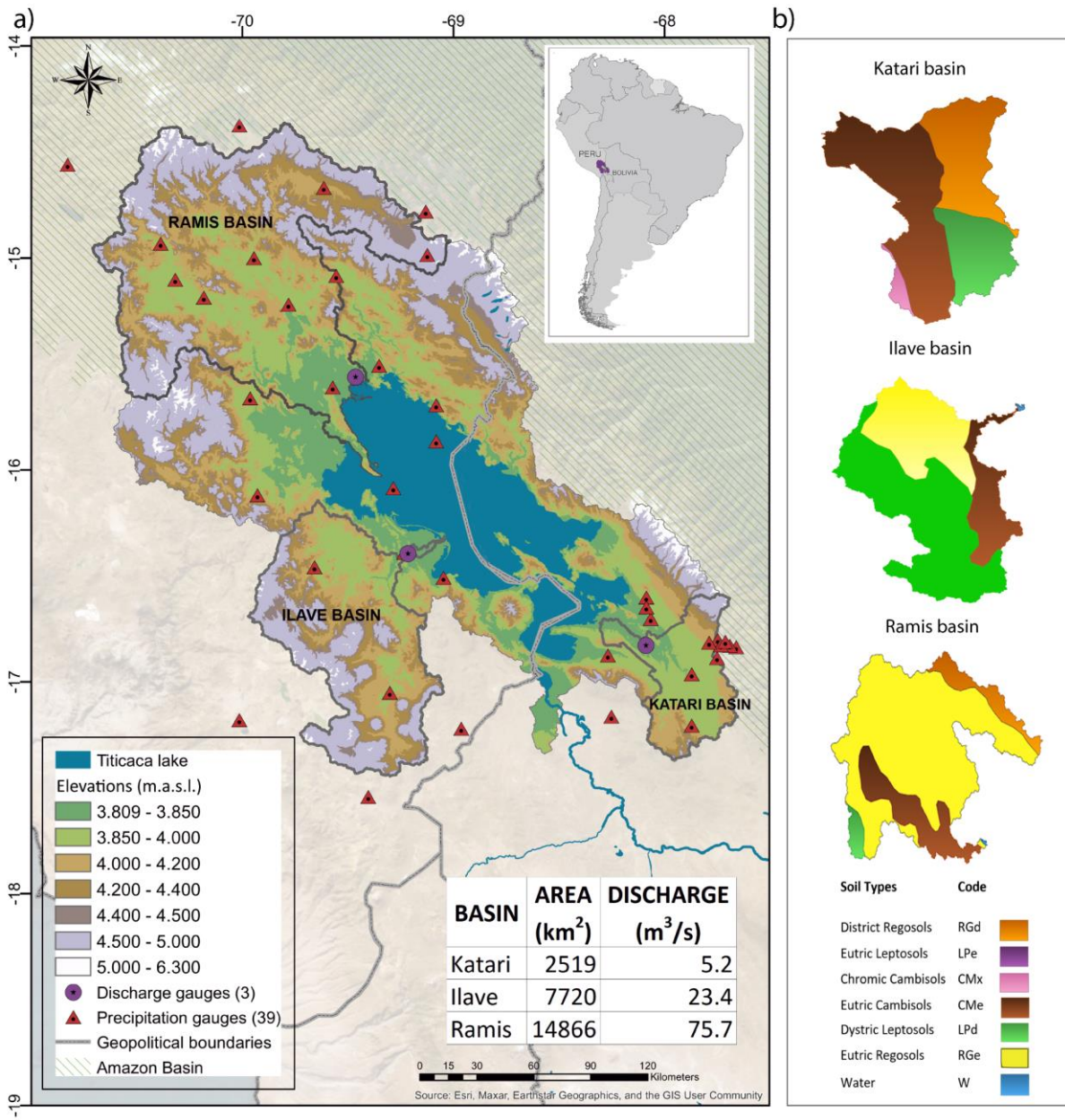


Figure 1 Study area location within (a) TDPS system with the location of precipitation and discharge stations across the three basins along with the South American map indicating the basin's position and the riparian countries, Bolivia and Peru; (b) soil types derived from SOTERLAC.

2.2 Datasets

2.2.1. Digital Elevation Model

With a three arc-second resolution, the MERIT-Hydro Digital Elevation Model (DEM) was used for watershed delineation and drainage network identification. A new algorithm was developed that automatically

126 identified river networks by distinguishing actual inland basins from artificial depressions often caused by
127 inaccuracies in the input elevation data (Yamazaki et al., 2019).

128 **2.2.2. Land Use Land Cover**

129 This study utilized a MODIS satellite-derived Land Cover Type product (MODIS/Terra+Aqua Land Cover
130 Type Yearly L3 Global 500 m SIN Grid, MCD12Q1). This product has a yearly temporal resolution and 500
131 m spatial resolution with global coverage, and its performance is well-documented (Friedl & Sulla-Menashe,
132 2022). The year 2007 was chosen as it falls within the study period from 2002 to 2015 to ensure a fair
133 representation of the basin's land use and land cover state.

134 **2.2.3. Soil data**

135 Soil information was obtained from the soils and terrains for Latin America and the Caribbean version
136 2 (SOTERLAC v.2) (Dijkshoorn et al., 2005). Using the FAO soil classification system, SOTERLAC was
137 constructed by compiling and harmonizing soil and terrain data from various national sources in Latin America
138 and the Caribbean, digitized at a 1:5 million scale resolution and validated through field verification and expert
139 reviews for accuracy. Fig. 1 shows the three subbasins' soil maps.

140 **2.2.4. Evapotranspiration**

141 Climate data, including temperature, humidity, wind speed, sunshine hours, and atmospheric pressure,
142 were sourced from the ERA5 reanalysis dataset for the period 2002-2015. ERA5, provided by ECMWF
143 (European Centre for Medium-Range Weather Forecasts), delivers hourly data with global coverage and a
144 spatial resolution of $0.25^\circ \times 0.25^\circ$ (Hersbach et al., 2020). This climate data was processed using Python and
145 later integrated into the MGB model (Modelo Hidrológico de Grandes Bacias, hereafter referred to as MGB)
146 to compute the potential evapotranspiration using the Penman-Monteith equation (Collischonn et al., 2007; De
147 Paiva et al., 2013; Allen & Food and Agriculture Organization of the United Nations, 1998).

148 **2.2.5. Observed precipitation and discharge**

The Servicio Nacional de Meteorología e Hidrología (SENAMHI) in Bolivia and Peru provided observed daily precipitation data for the period 2002-2015. A buffer was applied around each basin to ensure comprehensive spatial coverage, obtaining data from 39 stations in the three basins (Figure 1). Daily discharge measurements for the same period were obtained from the National Water Authority (ANA) in Peru and SENAMHI in Bolivia for each of the three basins.

2.2.6. Gridded precipitation products

Several GPPs have been developed in recent decades to meet the needs of hydrological analysis. These datasets utilize satellite observations, gauge measurements, atmospheric model simulations, or a combination of them (e.g., reanalysis products; see Table 1). Twenty specific gridded precipitation products were selected for this study as they provide extensive spatial coverage, high temporal resolution, and advanced integration methods.

The selected GPPs encompass various iterations of similar precipitation products, each differing in resolution and data correction levels. These versions range from primarily satellite-based to those enhanced with local observational corrections. Additionally, each version is tailored to meet different analytical needs due to its unique characteristics and availability timelines, ensuring that they serve distinct purposes within our hydrological analysis.

Table 1 Overview of the GPP adopted in this study. The Abbreviations: "R" stands for Reanalysis, "G" for Gauge, and "S" for satellite

Short name	Full name	Data source	Temporal coverage	Temporal resolution	Spatial coverage	Spatial resolution	References
CHIRP v.2	Climate Hazard Group InfraRed Precipitation	SR	1981–present	Daily	Global (LAND)	0.05°	(Funk et al., 2015)
CHIRPS v.2	Climate Hazard Group InfraRed Precipitation with Stations	SRG	1981–present	Daily	50°S to 50°N	0.05°	(Funk et al., 2015)
CMORP H_BLD	Bias-Corrected CMORPH Further Blended with Gauge Analysis	SG	1998–present	Daily	60°S to 60°N	0.25°	(Joyce et al., 2004)
CMORP H_CRT	CPC MORPHing technique (CMORPH) bias-corrected (CRT) V1.0	SG	1998-2015	Hourly	60°S to 60°N	0.25°	(Joyce et al., 2004)
ERA5	ERA5: Fifth Generation of ECMWF Atmospheric Reanalyses of the Global Climate	R	1979–present	Hourly	Global	0.25°	(Hersbach et al., 2020)
GSMaP_Adj v.6	Global Satellite Mapping of Precipitation-adjusted	SG	2000-present	Hourly	60°S to 60°N	0.1°	(Ushio et al., 2009; Kubota et al., 2020)
GSMaP_RT v.6	Global Satellite Mapping of Precipitation Standard	S	2000-present	Hourly	60°S to 60°N	0.1°	(Ushio et al., 2009;

								Kubota et al., 2020)
IMERG-ER v.6	Integrated Multi-satellitE Retrievals for GPM-IMERG–Early run v.6	S	2000–present	30 min	Global	0.1°		(Huffman et al., 2020)
IMERG-FR v. 6	Integrated Multi-satellitE Retrievals for GPM-IMERG–Final run v.6	SG	2000–present	30 min	Global	0.1°		(Huffman et al., 2020)
IMERG-LR v. 6	Integrated Multi-satellitE Retrievals for GPM-IMERG–Late run v.6	S	2000–present	30 min	Global	0.1°		(Huffman et al., 2020)
MERRA2_Flx	Modern-Era Retrospective Analysis for Research and Applications, Version 2 (MERRA-2) - Flux Precipitation Total	R	1980–present	hourly	Global	0.5°		(Gelaro et al., 2017)
MERRA2_LND	MERRA-2 Land Precipitation Total Correction	RG	1980–present	hourly	Global	0.5°		(Gelaro et al., 2017)
MSWEP v.2.8	Multi-Source Weighted Ensemble Precipitation v.2.8	SRG	1979–present	3 hr	Global	0.1°		(Beck et al., 2019)
PERSIAN_N_CDR	Precipitation Estimation from Remotely Sensed Information using Artificial Neural Networks - Climate Data Record	SG	1983–present	daily	60°S to 60°N	0.25°		(Ashouri et al., 2015)
PERSIAN_N_CSS_CDR	Precipitation Estimation from Remotely Sensed Information using Artificial Neural Networks-Cloud Classification System-Climate Data Record	SG	1983–present	3-hourly	60°S to 60°N	0.04°		(Sadeghi et al., 2021)
SM2Rain_CCI v.2	Soil Moisture to Rain from ESA Climate Change Initiative	S	1998–2021	Daily	Global (LAND)	0.1°		(Mosaffa et al., 2023)
TMPA_Adj	Tropical Rainfall Measuring Mission Multi-Satellite Precipitation Analysis - Adjusted	SG	1998-2019	2 hours	60°S to 60°N	0.25°		(Huffman et al., 2010; Huffman et al., 2018)
TMPA_RT	Tropical Rainfall Measuring Mission Multi-Satellite Precipitation Analysis - Real Time	S	2000-2019	3 hours	60°S to 60°N	0.25°		(Huffman et al., 2010; Huffman et al., 2018)
WFDEI_CRU	WATCH Forcing Data methodology applied to ERA-Interim data with CRU corrections	RG	1979-2015	Daily	Global	0.5°		(Weedon et al., 2014)
WFDEI_GPCC	WFDEI c2017 0.5 x 0.5-degree global meteorological forcing data	RG	1976-2016	Daily	Global	0.5°		(Weedon et al., 2018)

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168

2.3 Hydrological Models

169

2.3.1 MGB-IPH model

170

MGB is a semi-distributed model developed by the Federal University of Rio Grande do Sul and tailored

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for large-scale basins. It uses a combination of physical and conceptual equations to simulate key hydrological

172

processes, including infiltration, evapotranspiration, runoff, and river flow (Collischonn et al., 2007;

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Collischonn & Tucci, 2001). The model divides basins into smaller catchments, each with specific hydrological

174

balances (Siqueira et al., 2018).

Hydrological Response Units (HRUs) are defined based on combinations of soil types and land use (Haghnegahdar et al., 2015). Water and energy budgets for each HRU are calculated using a simplified reservoir model for soil (De Paiva et al., 2013) and the Penman-Monteith equation for evapotranspiration (Allen & FAO, 1998). Runoff and groundwater flows are routed using various methods, including linear reservoirs and hillslope routing (Todini, 1996). The Muskingum-Cunge equation is used to simulate water propagation within the drainage system. The model has been widely employed in watersheds exceeding 2,500 km² in South America and Africa (Fleischmann et al., 2017) and has been used in studies aiming at modeling the Amazon River basin and assessing climate change impacts (Paiva et al., 2011; Paiva et al., 2013; Siqueira et al., 2018; Brêda et al., 2020).

Table 2 lists the soil parameters used for calibration, including Wm and b, which Oliveira et al. (2019) identified as the most sensitive. These parameters significantly influence the simulation of maximum and minimum streamflows and overall model bias (Collischonn et al., 2007).

Table 2 MGB model parameters

Parameter	Units	Limits [min-max]	Description
Wm	mm	[50 – 1000]	Soil moisture capacity (the capacity of the soil to store rainwater, generating little or no runoff)
b	-	[0.01 – 1.6]	Defines the shape of the storage-saturation curve (controls the separation of runoff to saturation of the soil storage capacity)
Kbas	days	[0.05 – 5]	Controls flow during dry periods; affects baseflow generation
Kint	-	[4 – 40]	Amount of soil water that emerges as subsurface flow
CAP	mm/day	[0]	Flow rate from the subsurface reservoir to the surface soil layer
Wc	mm	[0.1–0.825×Wm]	Residual storage limits the flow of sub-surface and underground water
CS	-	[1-20]	Coefficient for surface water propagation in cells
CI	-	[50-200]	Coefficient for sub-surface water propagation in cells
CB	days	[1200 – 8000]	Delay parameter of the underground reservoir

2.3.2 GR4J Model

GR4J (Génie Rural à 4 paramètres Journalier) is a conceptual rainfall-runoff model developed in France (Perrin et al., 2003). It uses four parameters to simulate the hydrological cycle based on daily precipitation and potential evapotranspiration (PET) (Table 3). The model employs two reservoirs and two-unit hydrographs to convert rainfall into runoff, with adequate precipitation accounting for daily PET.

The GR4J model was selected for this study due to its proven reliability in a wide range of regions, including Europe (Fabre et al., 2015), Asia and Oceania (Wei et al., 2021), and Africa (Kodja et al., 2020; Faty et al., 2023; Ndiaye et al., 2024). In South America, the model has been applied with success in Chile (Ruelland et al., 2014; Hublart et al., 2015, 2016), Brazil (Satsgé et al., 2021), Ecuador (Pozo Valdivieso, 2024), and across the Titicaca region (Satsgé et al., 2019).

Table 3 GR4J model parameters

Parameter	Units	Limits [min-max]	Description
X_1	mm	[100-2000]	Maximum capacity of the production store
X_2	mm/day	[-5 - 3]	Groundwater exchange coefficient
X_3	mm	[20 - 300]	Maximum capacity of the routing store
X_4	days	[1.1 - 2.9]	Base time of the unit hydrograph

3. Methodology

3.1 Hydrological Modeling Set-up and Calibration

The three basins (Katari, Ilave, and Ramis) were delineated using IPH-Tools in QGIS. This tool utilizes a series of geoprocessing algorithms to (i) fill and remove depressions (sinks), (ii) calculate flow direction based on terrain slope, (iii) compute flow accumulation by determining the upstream contributing area, and (iv) delineate drainage areas and sub-basins. These steps resulted in a detailed drainage network segmented into micro-basins, forming the larger basin structure (Siqueira et al., 2016). Additional processing included stream ordering and thresholding to define the river network, ensuring accurate hydrological representation.

For the MGB model, HRUs were defined by integrating land cover data from MODIS and soil data from SOTERLAC using IPH-Tools. Essential baseline data for each HRU were stored in the MINI.gtp file and facilitated the modeling of localized hydrological processes within each sub-basin (Pontes et al., 2017). Potential Evapotranspiration (PET) was computed in MGB from ERA5 climate variables. Then, observed and GPP data were interpolated at the sub-basin level using Python scripts and formatted for the MGB model. Finally, Monte Carlo simulations were used to calibrate MGB for each of the products following a four-step process (Hostache et al., 2020):

1. Generate 10,000 MGB parameter sets using hypercube sampling

2. Run 10,000 MGB simulations using each of the previously generated parameter sets
3. Compute the KGE for each MGB simulation
4. Select the optimal parameter set providing the highest KGE value.

In the GR4J model, PET, derived from the MGB model outputs and observed, and GPP data were aggregated at the basin scale. Then, the open-source Modular Assessment of Rainfall-Runoff Models Toolbox v.1.2 (Knoben et al., 2019) was used to set up the model with the Nelder–Mead simplex algorithm for the objective function optimization (KGE) to calibrate it. The model was recalibrated independently for each GPP to tailor the model parameters to the unique characteristics of each precipitation dataset.

For both models (MGB and GR4J), a model warm-up was performed from 2002 to 2004, and the calibration was carried out from 2005 to 2012. The same calibration method was applied consistently for each GPP and basin, following a standardized approach across the dataset. Recent studies have adopted similar methodologies, such as Andrade et al. (2024), who utilized a uniform calibration strategy across multiple precipitation products to ensure comparability and robust model performance across diverse hydrological conditions.

3.2. GPPs accuracy assessment

3.2.1 Spatial Pattern Assessment

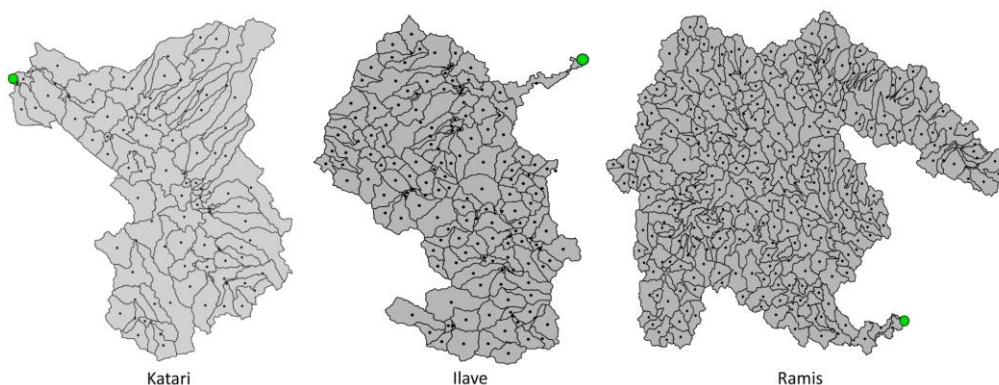
Annual-averaged precipitation maps for the 2002–2015 period were generated at a regional level for all 20 GPPs using downloaded daily data. The maps cover a quadrant that includes the three basins under study. These data were then mapped onto their original grids, maintaining the native resolution of each product to ensure consistency. This approach allows a clearer understanding of how differences in resolution may impact the spatial representation of precipitation patterns.

Observation Gauges were strategically selected within a rectangular area that encompasses each basin, extending 10 to 30 km beyond their boundaries to ensure the inclusion of relevant and reliable station data. Additionally, stations from the Amazon basin were included as reference points, allowing for a clearer

239 representation of the regional precipitation gradient. Furthermore, the annual average precipitation for each
240 station was calculated based on the available daily data. These values were then mapped using a color scale
241 ranging from 0 to 2000 mm/year, similar to those used for the GPPs. Finally, the resulting 21 maps were visually
242 assessed to analyse the spatial distribution of precipitation and its alignment with expected regional climatic
243 patterns.

244 3.2.2 Temporal Accuracy Analysis

245 To ensure a uniform data distribution across the study area, the 20 GPPs and gauge observations were
246 interpolated using the sub-basin discretization approach of the MGB model (Figure 2). In MGB, the watershed
247 is divided into sub-units called minibasins, which correspond to immediate contribution areas to a river segment
248 and are delineated based on digital elevation models and geoprocessing algorithms. We have applied the inverse
249 distance weighting method, assigning values to the centroid of each minibasin. This approach allows for a more
250 accurate representation of the spatial heterogeneity of physical characteristics and hydrological fluxes within
251 the watershed. The interpolated precipitation in each mini-basin was subsequently used for statistical analyses,
252 ensuring a more consistent comparison between different precipitation products.



253
254 Figure 2 Minibasins with their corresponding centroids, and in green, the outlets of each basin

255 Following the described process, the temporal accuracy of the GPPs was assessed by comparing the spatially
256 averaged GPP values to the spatially averaged gauge observations at a daily time step. Taylor diagrams
257 (Taylor, 2001) were used to visualize this comparison based on three key metrics:

- Correlation (R, Eq. 1): Measures the strength and direction of the linear relationship between observed and GPP values, represented by the angular position in the Taylor diagram.
- Standard Deviation (σ , Eq. 2): Reflects the variability of the dataset around its mean.
- Centered Root-Mean-Square Difference (CRMSD, Eq. 3): Evaluates discrepancies between observed and GPP patterns, focusing on differences in spatial or temporal structures.

Bias (Eq. 4) was also calculated to quantify systematic estimation errors.

$$R = \frac{1}{N-1} \sum_{i=1}^N \left(\frac{X_i - \bar{X}}{\sigma_X} \right) \left(\frac{Y_i - \bar{Y}}{\sigma_Y} \right) \quad (1)$$

$$\sigma = \sqrt{\frac{1}{N} \sum_{i=1}^N (X_i - \bar{X})^2} \quad (2)$$

$$CRMSD = \sqrt{\frac{1}{N} \sum_{i=1}^N (X_i - \bar{X} - Y_i + \bar{Y})^2} \quad (3)$$

$$Bias (\%) = \left(\frac{\sum (Y_i - X_i)}{\sum X_i} \right) * 100 \quad (4)$$

Where X_i and Y_i represent the observed and simulated values, respectively, \bar{X} and \bar{Y} are the means of the observed and GPPs values, σ_X and σ_Y are the standard deviations of the observed and GPPs values and N is the number of observations.

3.3 GPPs as input precipitation data within Hydrological Models

For each Gridded Precipitation Product (GPP) and model (MGB and GR4J), streamflow simulations were conducted across the three basins for the calibration period: 2005-2012. To assess the reliability of the simulated streamflow, KGE values were computed for this period (Eq. 5), focusing on evaluating model performance rather than optimizing it for predictive purposes, as evaluating the validation period could

introduce additional sources of uncertainty. In recent years, KGE has been extensively employed to calibrate and evaluate hydrological models (Liu, 2020). The application of KGE within the context of this study is justified by its ability to provide nuanced insights into the model's behavior, providing a more balanced assessment of model errors compared to the Nash-Sutcliffe Efficiency (NSE) (Gupta et al., 2009). The KGE values range from negative infinity to one, with a value of one representing perfect agreement and negative values indicating poor performance.

$$KGE = 1 - \sqrt{(R - 1)^2 + (\alpha - 1)^2 + (\beta - 1)^2} \quad (5)$$

Where R is the Correlation coefficient between the observed X_i and simulated Y_i values. α is the ratio of the means (Eq. 6), and β is the ratio of the coefficients of variation (Eq. 7)

$$\alpha = \frac{\bar{Y}}{\bar{X}} \quad (6)$$

$$\beta = \frac{\sigma_Y/\bar{Y}}{\sigma_X/\bar{X}} \quad (7)$$

4. Results

4.1. GPPs Spatial Pattern Assessment

Figure 3 presents the annual-averaged precipitation maps for the 2002–2015 period for all 20 GPPs, preserving their native resolutions (Table 1). The figure also includes observation gauges. The assessment reveals notable differences in how each dataset represents spatial precipitation patterns across the study area, highlighting variations in resolution, consistency, and potential outliers.

The area of interest represented in Figure 3 not only covers the Titicaca basin but also extends into a portion of the Amazon Basin, which experiences markedly higher precipitation levels (Molina-Carpio et al., 2023). This broader regional analysis captures the transition between the humid north-eastern areas, influenced by Amazonian rainfall patterns, and the drier south-western regions. In that sense, a transparent precipitation

296 gradient is observed across the region, reflecting the described gradient captured by most of the products;
297 however, differences in resolution and absolute precipitation values lead to varying degrees of agreement.

298 Some GPPs, such as CHIRPS, GSMaP_RT, IMERG-FR, MSWEP, TMPA_Adj, and WFDEI_CRU,
299 align more closely with the expected precipitation distribution. The observation stations in Figure 3 provide
300 additional context, notably confirming the transition from humid to drier zones influenced by the Amazon.
301 Some products like CHIRPS and IMERG-FR capture this feature more effectively.

302 On the other hand, ERA5 and MERRA2_FLX exhibit a significant overestimation of precipitation
303 across the entire domain, deviating considerably from other datasets. Regarding SM2RAIN_CCI, although its
304 coverage is limited in some areas, where data is available, it follows the typical precipitation pattern observed
305 across multiple products.

306 When considering spatial resolution, a higher resolution does not always lead to a better representation
307 of precipitation gradients. For example, TMPA_Adj, WFDEI_CRU, and WFDEI_GPCC, despite having
308 coarser resolutions, appear to represent precipitation distribution well. In contrast, PERSIANN_CSS_CDR,
309 despite having the highest resolution among all GPPs, does not align with the general trend observed across
310 most products, suggesting a potential overestimation.

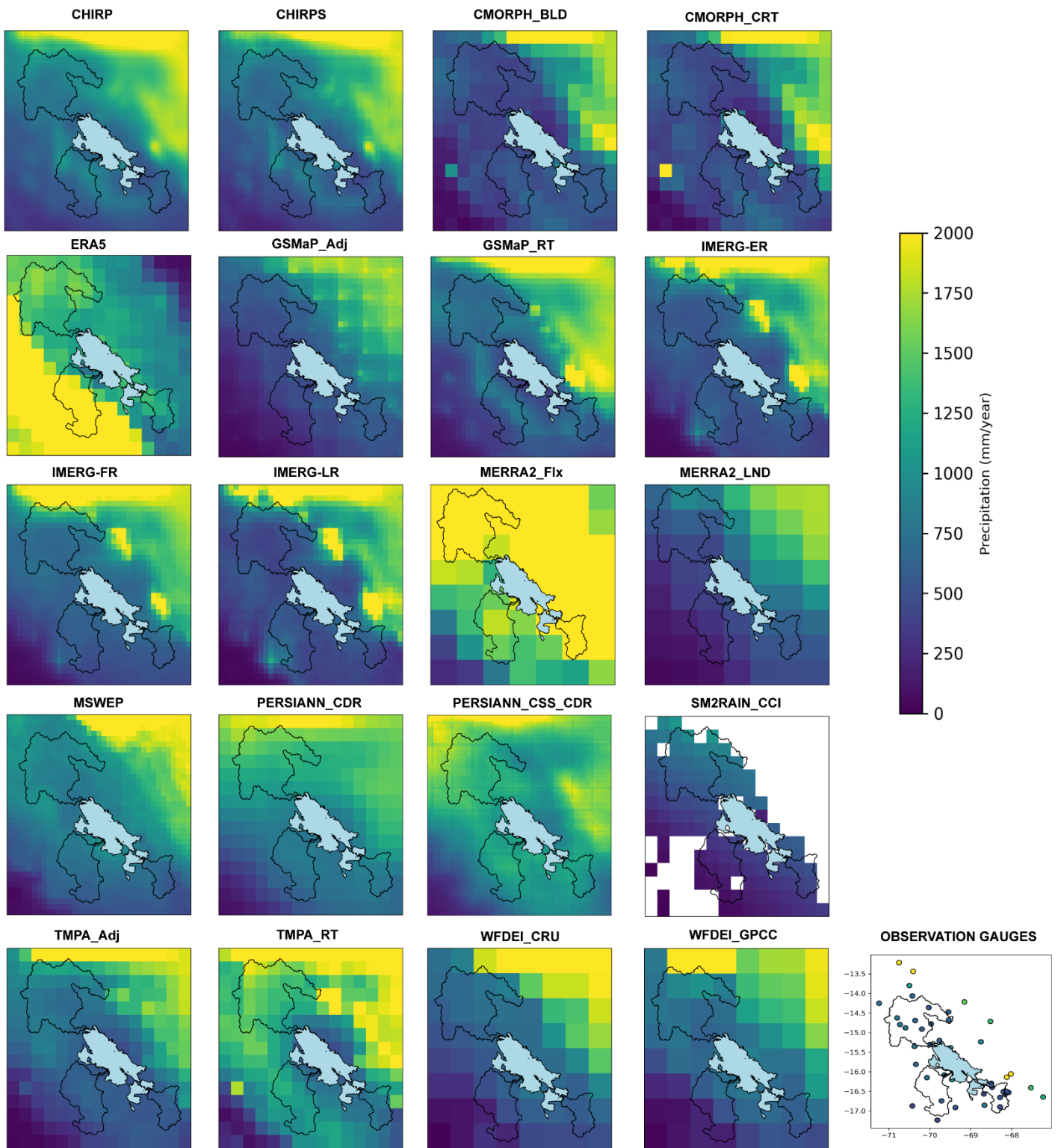


Figure 3 Annual average precipitation maps derived from the 20 GPPs and gauge observations for the 2002-2015 period.

4.2.GPPs' temporal reliability

Key statistical metrics were computed to assess the temporal reliability of the GPPs in the Katari, Ilave, and Ramis basins. These indicators provide insights into each GPP's ability to replicate observed precipitation patterns in terms of variability, agreement with observations, and systematic deviations. Table 4 presents the statistical evaluation of each product for the three basins.

Table 4 Statistical indicators for the evaluation of GPPs' temporal performance in the three basins (Katari, Ilave, Ramis).

Basin	Product	STDs	CRMSD	CCOEF	Bias	Basin	STDs	CRMSD	CCOEF	Bias	Basin	STDs	CRMSD	CCOEF	Bias
KATARI	CHIRP	1.10	0.59	0.84	6	ILAVE	0.97	0.51	0.87	18	RAMIS	1.16	0.46	0.92	26
	CHIRPS	1.05	0.54	0.86	-2		0.88	0.43	0.90	4		1.02	0.43	0.91	9
	CMORPH_BL	1.09	0.62	0.83	5		0.61	0.60	0.83	-19		0.65	0.53	0.88	-32
	CMORPH_CRT	0.91	0.57	0.82	-11		0.60	0.59	0.85	-18		0.67	0.49	0.90	-29
	ERA5	2.66	2.09	0.69	301		1.28	0.51	0.93	86		1.31	0.60	0.90	56
	GSMaP	1.08	0.61	0.83	6		0.70	0.64	0.77	-40		1.00	0.75	0.72	-22
	GSMaP_RT	1.07	0.71	0.77	22		0.80	0.64	0.77	0		0.84	0.54	0.84	3
	IMERG-ER	1.07	0.54	0.87	10		0.83	0.37	0.93	-13		0.76	0.43	0.92	-8
	IMERG-FR	1.17	0.55	0.88	16		0.92	0.34	0.94	-10		1.08	0.35	0.94	21
	IMERG-LR	1.08	0.53	0.87	3		0.84	0.36	0.94	-16		0.70	0.43	0.93	-20
	MERRA2_FLX	3.44	2.87	0.67	430		1.90	1.08	0.91	155		3.10	2.44	0.75	503
	MERRA2_LND	1.02	0.39	0.93	5		0.50	0.59	0.90	-51		0.79	0.50	0.87	-19
	MSWEP	1.14	0.43	0.93	20		1.17	0.38	0.95	15		1.28	0.42	0.96	32
	PERSIANN_CDR	1.33	0.70	0.86	56		8.80	8.76	0.25	-424		1.46	0.69	0.91	85
	PERSIANN_CSS_CDR	1.61	1.03	0.78	93		1.44	0.69	0.90	76		1.48	0.76	0.88	94
	SM2Rain_CCI	0.84	0.50	0.87	-23		0.40	0.67	0.89	-75		1.07	0.43	0.92	1
	TMPA_Adj	1.02	0.59	0.83	5		0.89	0.41	0.91	-7		1.05	0.44	0.91	19
	TMPA_RT	1.31	0.81	0.79	42		1.25	0.62	0.87	64		1.66	0.92	0.87	106
	WFDEI_CRU	1.09	0.58	0.85	7		0.87	0.43	0.90	-24		1.10	0.42	0.92	2
	WFDEI_GPCC	1.06	0.55	0.86	13		0.90	0.40	0.92	-14		1.07	0.39	0.93	16

To better understand the performance of the GPPs in capturing precipitation variability, we use a Taylor diagram, which provides a comprehensive visualization of key statistical metrics (Figure 4). This approach allows for an integrated assessment of correlation, variability, and centered root mean square deviation (CRMSD), facilitating a direct comparison across datasets. Additionally, a bias bar graph is included to highlight systematic deviations from observed precipitation, offering further insight into the tendencies of each product in the three basins. Figure 4 presents these results, summarizing the statistical performance of the GPPs.

The Taylor diagram reveals notable differences in the performance of GPPs across the three basins. Overall, CHIRPS, IMERG-FR, and MSWEP exhibit the highest correlation coefficients ($CCOEF > 0.90$) across all basins, indicating strong agreement with the reference dataset. In contrast, products such as GSMaP_Adj and MERRA2_FLX display significantly lower correlation values ($CCOEF < 0.75$), with PERSIANN_CDR

330 showing particularly high CRMSD values mainly in the Ilave basin, suggesting substantial errors in capturing
331 the temporal variability of precipitation. Due to the extreme values of standard deviation (STD) or CRMSD,
332 some products were removed from the Taylor diagrams for clarity: ERA5 and MERRA2_FLX in the Katari
333 basin, PERSIANN_CDR in the Ilave basin, and MERRA2_FLX in the Ramis basin.

334 Regarding bias, MERRA2_FLX, PERSIANN_CDR, and ERA5 present the most pronounced absolute
335 bias in the three basins. In comparison, CHIRPS and IMERG-ER show relatively low bias values across the
336 three basins. A basin-specific bias analysis highlights that the Ilave basin generally exhibits the lowest bias
337 among GPPs, with most products displaying values within $\pm 50\%$. Among the analyzed products, GSMaP_RT
338 stands out due to its low bias across all basins. Notably, in the Ilave basin, GSMaP_RT presents a bias of 0%,
339 indicating an almost perfect agreement in magnitude. It is important to note that, due to the scale used in the
340 bias plot (ranging from -100% to 100%), products that exceeded this range were still plotted, but their bias
341 values were displayed in white text on the bars.

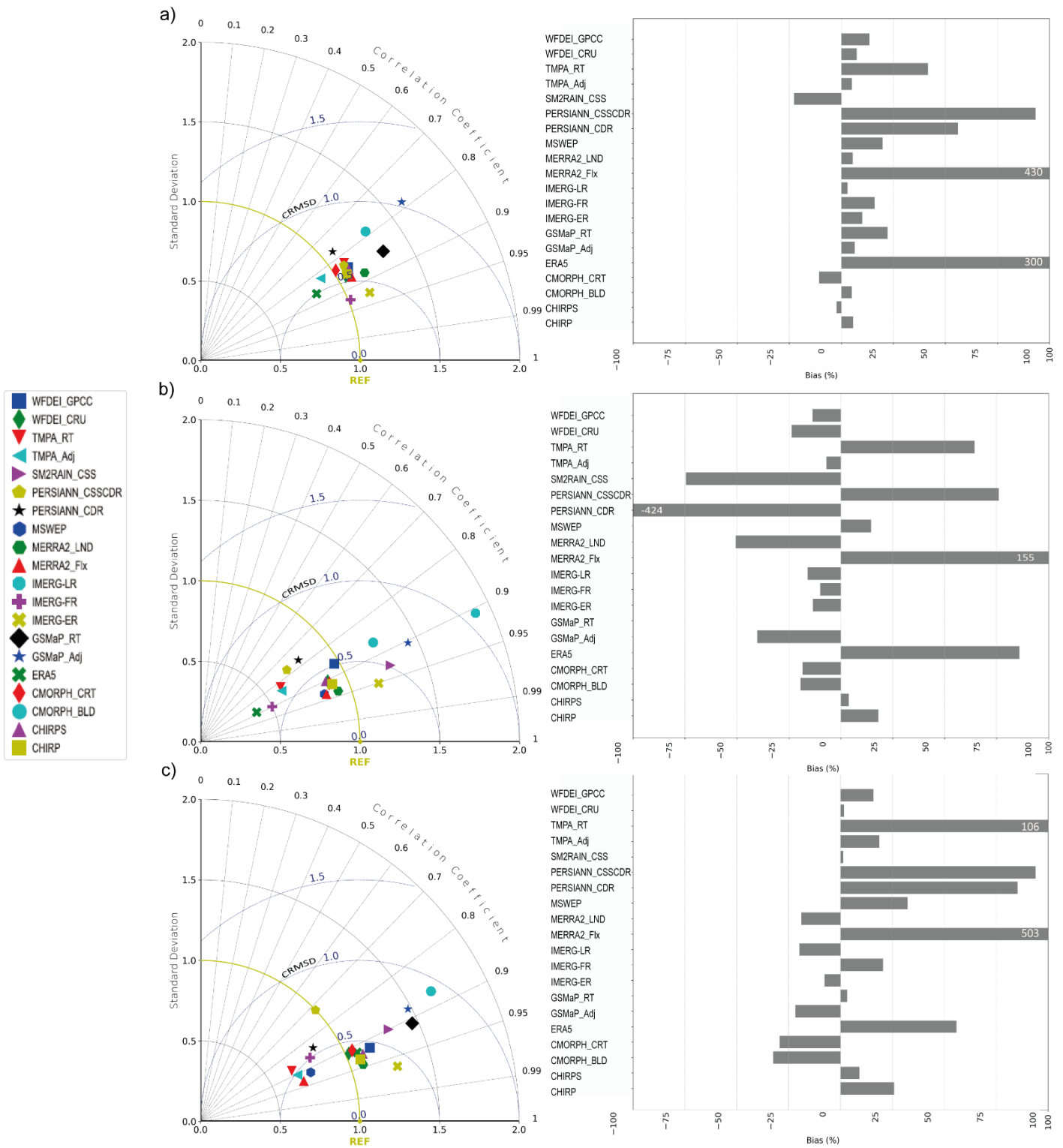


Figure 4 Taylor diagrams (left column) and bias bar charts (right column) comparing the different precipitation datasets for the (a) Katari, (b) Ilave, and (c) Ramis basins (one row for each basin). In the Taylor diagrams, precipitation datasets with a standard deviation beyond the plot range were excluded (Katari->MERRA2_Flx, Ilave->PERSIANN_CDR, Ramis-> MERRA2_Flx). Adjacent to each Taylor diagram, a bar chart shows the bias calculation for each dataset, plotted within the range of -100 % to 100%. Bars exceeding this range are marked with their respective bias percentage inside the bar.

4.3. Hydrological Model Performance Sensitivity to GPPs

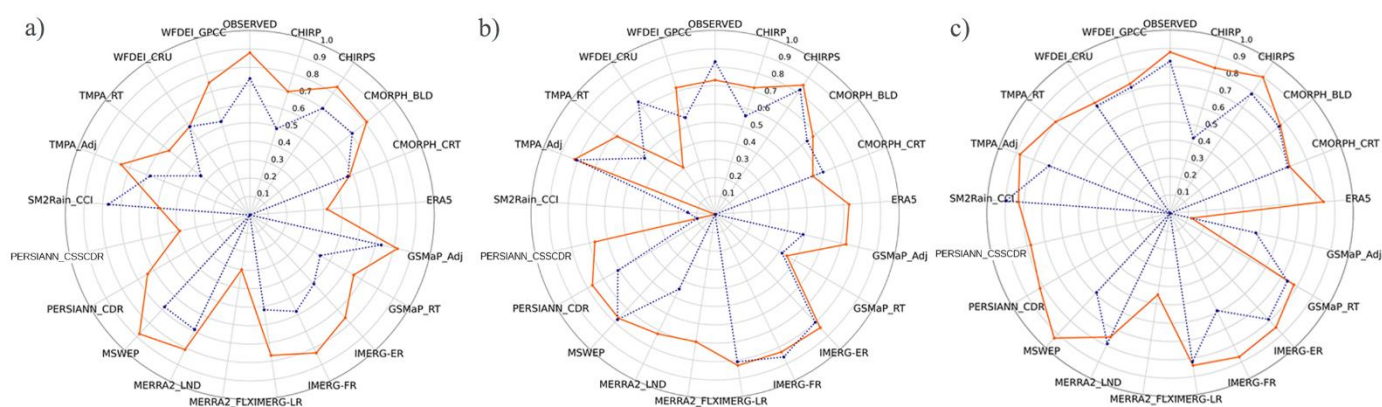
The impact of the GPPs on the performance of both models was assessed by comparing streamflow simulations using these products as input in Figure 5. For each GPP, distinct parameter sets were calibrated to optimize the model's responses to the characteristics of precipitation data.

In the Katari basin, GR4J showed high performance, while MGB had moderate performance represented by KGE with CHIRPS (0.84, 0.70), MSWEP (0.88, 0.68), and IMERG_FR (0.83, 0.58), respectively. In contrast, SM2Rain_CCI led to good performance in MGB (0.77) but had a weaker influence on GR4J (0.49), suggesting its robustness in semi-distributed simulations. Finally, PERSIANN_CSS_CDR, MERRA2_FLX, and ERA5 resulted in poor performance in both models ($KGE < 0.50$).

In the Ilave basin, the GR4J and MGB models both achieved high performance, as reflected by KGE values, with IMERG_FR (0.83, 0.86), IMERG_LR (0.83, 0.81), and CHIRPS (0.85, 0.82), demonstrating their consistency across models. In contrast, some GPPs showed strong performance in GR4J but were less effective in MGB, such as GSMaP_Adj (0.73, 0.49), ERA5 (0.73, <0), and MERRA2_LND (0.72, 0.45), suggesting a model-dependent sensitivity to precipitation inputs. Conversely, WFDEI_CRU contributed to good performance in MGB ($KGE = 0.74$) but failed to adequately support GR4J ($KGE = 0.31$). Finally, SM2Rain_CCI and GSMaP_RT resulted in poor performance in both models ($KGE < 0.50$).

The evaluation of GPPs in the Ramis basin shows a clear differentiation between datasets that perform consistently well across hydrological models and those with model-dependent effectiveness. SM2Rain_CCI (0.83, 0.90), IMERG_LR (0.84, 0.82), and CHIRPS (0.90, 0.79) demonstrated high performance in both GR4J and MGB. Meanwhile, MSWEP (0.93, 0.59) showed very high performance in GR4J but only regular performance in MGB, while ERA5 (0.84, <0) and PERSIANN_CDR (0.82, <0) also exhibited strong results in GR4J but were ineffective in MGB. On the other hand, GSMaP_Adj (0.12, 0.48) and MERRA_FLX (0.45, <0) yielded poor performance in both models, indicating their limited applicability for hydrological modeling in the Ramis basin.

372 In summary, CHIRPS and IMERG products showed consistently strong performance across both
 373 hydrological models, achieving high skills in all basins. In contrast, MSWEP performed well in all basins with
 374 the lumped GR4J model, while ERA5 showed good performance only in the Ilave and Ramis basins. However,
 375 both products exhibited substantially lower performance in the semi-distributed MGB model. Conversely,
 376 SM2Rain_CCI (in Katari) and WFDEI_CRU (in Ilave) yielded better results with MGB than with GR4J,
 377 highlighting the influence of model structure. Finally, PERSIANN_CSS_CDR and MERRA2_FLX
 378 consistently exhibited low performance in both models ($KGE < 0.50$), indicating limited suitability for
 379 streamflow simulation in this context.



380
 381 Figure 5 Radar charts showing KGE results for both hydrological models in the Katari (a), Ilave (b), and Ramis (c) basins. The simulation with
 382 MGB is represented in a blue dashed line, while the simulation with GR4J is shown in an orange solid line.

383 Figure 6 shows streamflow hydrographs simulated for the Katari, Ramis, and Ilave basins, obtained
 384 using the GR4J and MGB hydrological models. Each row within the figure corresponds to a different basin and
 385 showcases the comparative performance of the models under the influence of various precipitation datasets.
 386 For each basin, we employed the observed streamflow plus the GPPs IMERG_FR, CHIRPS, SM2RAIN, and
 387 PERSIANN_CCS (for Ilave). These products were selected based on their potential to capture relevant
 388 hydrological trends and represent varying precipitation data processing methodologies (Table 1).

389 In the Katari Basin, the GR4J model consistently underestimates low flows across all evaluated
 390 precipitation products, resulting in flatter and less variable low flow periods. Peak flow events are also
 391 frequently underestimated. Additionally, streamflow seasonality is characterized by erratic variability,

392 particularly when run with SM2RAIN. This model tends to smooth out the seasonal fluctuations in streamflow
393 more uniformly throughout the year compared to observed data.

394 In contrast, the MGB in the Katari basin exhibits improved sensitivity to low-magnitude events.
395 Simulation using IMERG_FR exhibits greater fluctuations and occasionally overestimates peak flows. On the
396 other hand, simulation using SM2RAIN_CCI offers a more accurate representation of the observed peak flows.
397 Overall, the MGB model demonstrates a better response to variations in precipitation inputs, which is reflected
398 in its handling of seasonal streamflow dynamics.

399 In the Ilave Basin, the GR4J model consistently underestimates low flows when utilizing GPPs, leading
400 to less variable and generally flatter low flow periods. This underestimation also extends to peak flows, where
401 the model fails to accurately simulate these events' intensity. Additionally, the seasonality of streamflow shows
402 significant discrepancies. Notably, erratic variability is observed when simulations incorporate
403 PERSIANN_CSS_CDR. In contrast, simulations using IMERG_FR and CHIRPS tend to more accurately
404 capture the expected seasonal variability, although they still struggle with precise amplitude and timing.

405 The MGB model in the Ilave basin also underestimates low flows. For peak flows, simulations using
406 IMERG_FR and CHIRPS provide a good representation. In contrast, simulation using PERSIANN_CSS leads
407 to a notable overestimation of both low and peak flows, depicting actual water flow conditions
408 misrepresentations.

409 In the Ramis Basin, the GR4J model underestimates low flows when processing data from GPPs. The
410 model frequently captures peak flows' magnitude accurately but tends to overestimate them in specific years.
411 The seasonality of streamflow is well replicated, except for the simulation using SM2RAIN_CCI.

412 Switching to the MGB model in the Ramis basin improves the sensitivity to low-magnitude events,
413 introducing more fluctuations. The MGB performs well on peak flow representations, except for some
414 overestimations when using SM2RAIN_CCI. Nonetheless, the MGB model tends to increase variability,
415 potentially leading to an excessive representation of seasonal variations.

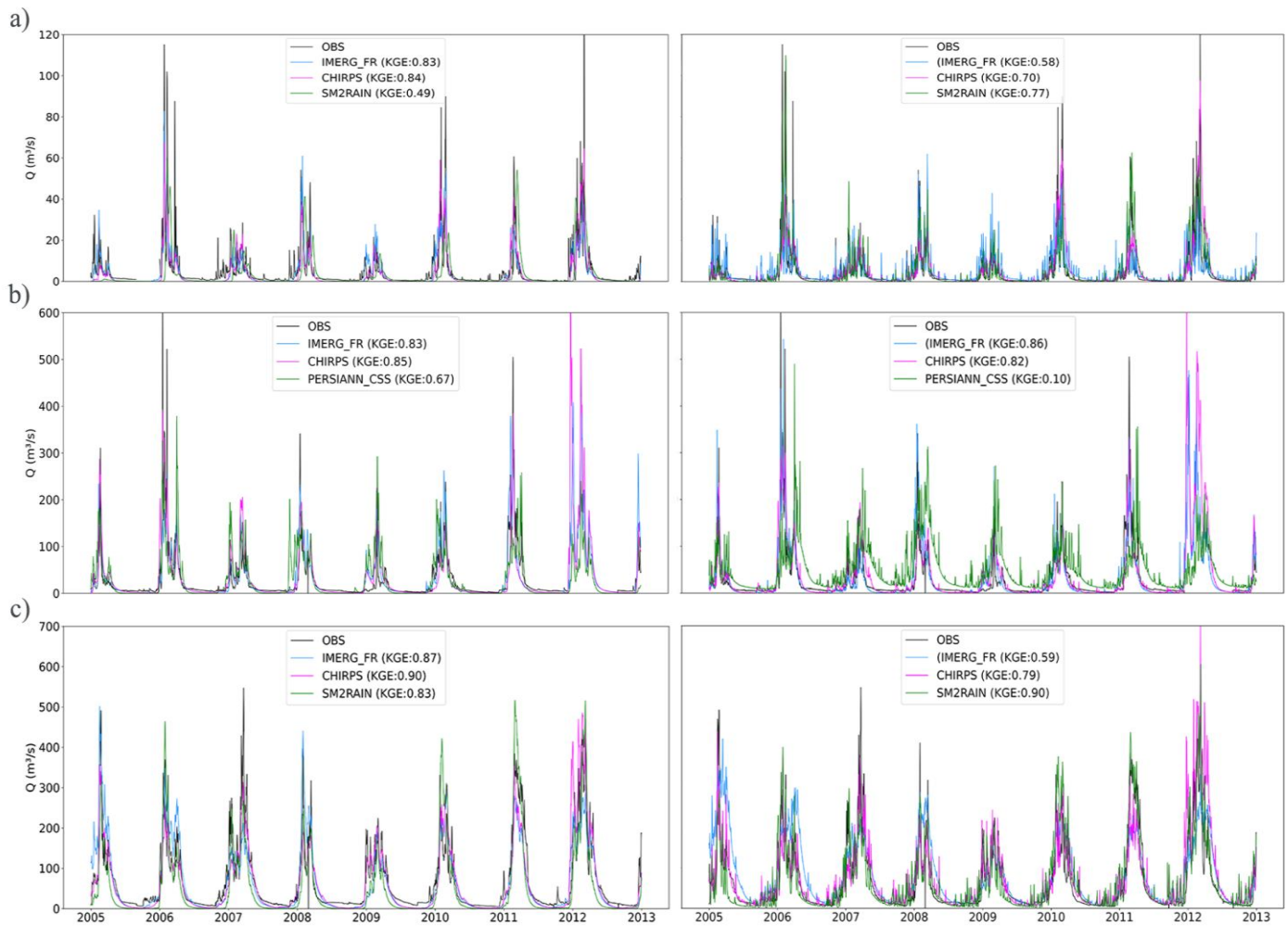


Figure 6 Comparative hydrographs of streamflow Simulations across a) Katari, b) Ilave, and c) Ramis Basins using GR4J (left) and MGB Models (right)

5. Discussion

5.1. GPP assessment in comparison to gauge observations

When addressing whether spatial resolution affects GPPs' reliability, the results show that spatial resolution may not be critical in determining accuracy. For example, PERSIANN_CSS_CDR, with the highest spatial resolution (0.04°), shows moderate correlation and significant bias, whereas MERRA2_LND, with a relatively coarse resolution (0.5°), demonstrates strong accuracy in some basins. The inclusion of gauge information tends to improve GPPs accuracy, as seen in CHIRPS, which generally shows the best performance because of additional gauge-based adjustments that are not included in CHIRP. A similar observation applies to MERRA2_LND (gauges adjusted) and _Flx (no gauges adjusted) that display distinct behaviors, with

428 MERRA2_LND systematically outperforming MERRA2_Flx (Reichle et al., 2011). In the case of TMPA_Adj
429 and _RT, the gauge-based adjustment significantly decreases the bias in TMPA_Adj compared to TMPA_RT.
430 However, the gauges' adjustment is not always relevant, as shown with IMERG and CMORPH versions'
431 products showing very similar performance between the non-corrected and the gauge-adjusted products.

432 Regarding how GPPs compare in their ability to represent spatial precipitation gradients, all GPPs
433 (except ERA5, MERRA2_Flx, MERRA2_Lnd, PERSIANN_CDR, and PERSIANN_CSS_CDR) reveal a
434 general pattern marked by a gradient from higher precipitation in the northeast to lower amounts in the
435 southwest. This gradient is well supported, given that the substantial difference in rainfall in the north-eastern
436 part of the region can be attributed to the Andes Mountains, which intercept much of the moisture coming from
437 the Amazon region (Insel et al., 2010; Zubieta et al., 2015).

438 Despite seemingly representing regional precipitation patterns, SM2Rain_CCI has too many gaps
439 (especially in the north-eastern region) due to (i) incomplete CCI soil moisture grid coverage and (ii) the
440 inherent characteristics of the algorithms used to convert soil moisture data into precipitation estimates (Miao
441 et al., 2023). The discrepancies in the accuracy of this product suggest the need for region-specific calibration
442 (Satgé et al., 2020; Levizzani et al., 2020).

443 Compared to the state of the art, the high reliability of CHIRPS across the three basins aligns with
444 previous research conducted in the Andean and other mountainous regions (López-Bermeo et al., 2022; Newell
445 et al., 2023; Satgé et al., 2019), as well as in neighboring basins like the La Plata Basin (Cerón et al., 2020) and
446 the Upper Cauca River Basin in Colombia (Romero-Hernández et al., 2024), emphasizing its effectiveness in
447 complex topographical settings.

448 Furthermore, the consistent underestimation of precipitation by CMORPH_CRT in the three basins is
449 also reflected in the study of Zubieta et al. (2015) while the poor accuracy of PERSIANN' GPPs characterized
450 by significant overestimations in complex terrains is in line with previous studies led in Pakistan and
451 Madagascar (Hussain et al., 2018; Ollivier et al., 2023). The overall good reliability of IMERG (ER, LR, and

FR) and MSWEP in comparison to available GPPs was also demonstrated in Brazil (Satgé et al., 2021), Madagascar (Ollivier et al., 2023), and Africa (Kouakou et al., 2023; Nwachukwu et al., 2020).

5.2. *GPPs assessment in hydrological models*

The ability of hydrological models to accurately simulate streamflow is heavily dependent on the accuracy and appropriateness of the input precipitation data, which must align with each basin's unique hydrological and climatological conditions (Tobin & Bennett, 2014). Variations in GPP's performance arise from discrepancies in data sources, retrieval algorithms, and the methodologies employed in bias corrections, introducing significant uncertainties in model representation of rainfall-runoff processes (Vergara et al., 2014; Zubieta et al., 2015). Additionally, the inherent uncertainties in model parameters and structure further compound these challenges, affecting the reliability of streamflow predictions, especially in arid regions where episodic low flows complicate calibration (Andrade et al., 2024).

In this context, GPP's spatial distribution should influence the performance of the hydrological models, particularly the semi-distributed MGB model, which incorporates spatial variability. In lumped models (i.e., GR4J), spatial variability is less critical, as these models rely more on the total precipitation amount and temporal distribution. However, the results indicate that spatial variability was not a decisive factor in model performance. Indeed, despite offering the highest spatial resolution, PERSIANN_CSS_CDR (0.04°) provides one of the least reliable streamflow simulations in MGB (KGE close to 0 or negative). Actually, the three most efficient GPPs for streamflow modeling in the three basins—Katari (SM2Rain_CCI 0.1°, GSMaP_Adj 0.1° and CMORPH_BLD 0.25°), Ilave (IMERG_FR 0.1°, CHIRPS 0.05°, and TMPA_Adj 0.25°), and Ramis (SM2Rain_CCI 0.1°, IMERG_LR 0.1° and MERRA_LND 0.5 °)—are not consistently those with the highest spatial resolution.

Among the considered GPPs, CHIRPS demonstrates a substantial positive impact on the performance of both hydrological models. This finding is consistent with previous literature review based on more than a hundred research articles (Du et al., 2024) and studies led across Brazil (Satgé et al., 2021) and Africa (Kouakou

et al., 2023; Satgé et al., 2019). MSWEP exhibited notably lower KGE for the MGB model in the Ramis basin, while GR4J performed very well with this GPP, surpassing the model using observed data. The high performance of MSWEP with lumped models was also highlighted in Brazil's Amazon region (Satgé et al., 2021). Likewise, ERA5, MERRA2_FLX, and PERSIANN_CSS_CDR showed a moderate impact on the performance of GR4J. In contrast, their performance with MGB was notably poor, suggesting that models like MGB may be particularly sensitive to the overestimation of rainfall (Bias>100%).

Considering the MGB model, the highest KGE values were achieved with SM2Rain_CCI in the Ramis and Katari basins. The lower KGE observed in the Ilave basin is likely due to underestimating precipitation (Bias=-74%). The results from the SM2Rain_CCI in the Ramis and Katari basins indicate that this product can provide valuable precipitation estimates that align well with observed data in specific regions and favourable local conditions for satellite soil moisture measurements (Satgé et al., 2020). Indeed, as observed by MODIS, the considered basins are mainly covered by grasslands, which have low interference on satellite soil moisture estimates used to derive precipitation estimates by SM2Rain algorithm.

5.3. *Lumped vs. semi-distributed hydrological models*

The analysis indicates that GPPs closely matching observed data in terms of temporal patterns and total precipitation (e.g., CHIRPS, MSWEP, and IMERG-ER, FR, LR) are likely to improve streamflow simulations in both models in the three basins. The two models' performance variability likely originates from how they conceptualize the basin's hydrological functioning. However, inaccuracies in representing precipitation intensity reflected statistically by the bias can lead to suboptimal results with MGB. At the same time, GR4J appears more resilient to such biases represented in Figure 7 (e.g., ERA5, TMPA_RT, PERSIANN_CSS_CDR, PERSIANN_CDR, and MERRA2_FLX). Given these differences in sensitivity to precipitation biases, it is important to examine the specific characteristics of the models further.

GR4J proved more effective at reproducing streamflow at the basin outlet, likely due to its simpler, lumped structure, which is less sensitive to spatial variability and intensity errors in precipitation. This

500 observation aligns with the “hydrological model adaptability” framework of Wang et al. (2023), who
501 demonstrated that a conceptual lumped model (Xinanjiang) can absorb moderate systematic biases in
502 precipitation inputs. Indeed, GR4J’s conceptual design allows it to compensate for overestimations in rainfall
503 by calibrating parameters such as the groundwater exchange coefficient (X2, Table 3)—which controls surface–
504 groundwater exchanges—the model can buffer errors arising from excessive precipitation estimates. The high
505 sensitivity of this parameter enables GR4J to adjust for discrepancies, thereby improving streamflow
506 predictions even where rainfall overestimation might otherwise skew hydrological outputs (Andrade et al.,
507 2024).

508 To further analyze the relationship between precipitation bias and model performance, Figure 7 presents
509 the correlation between bias and KGE across different GPPs. This visualization highlights how MGB and GR4J
510 respond differently to over and underestimations in precipitation, providing additional insights into their
511 respective sensitivities to input data uncertainties. Our first observation is that despite PERSIANN_CDR,
512 TMPA_RT, and ERA5 overestimating precipitation, the KGE remained above 0.6 for most of the basin using
513 GR4J.

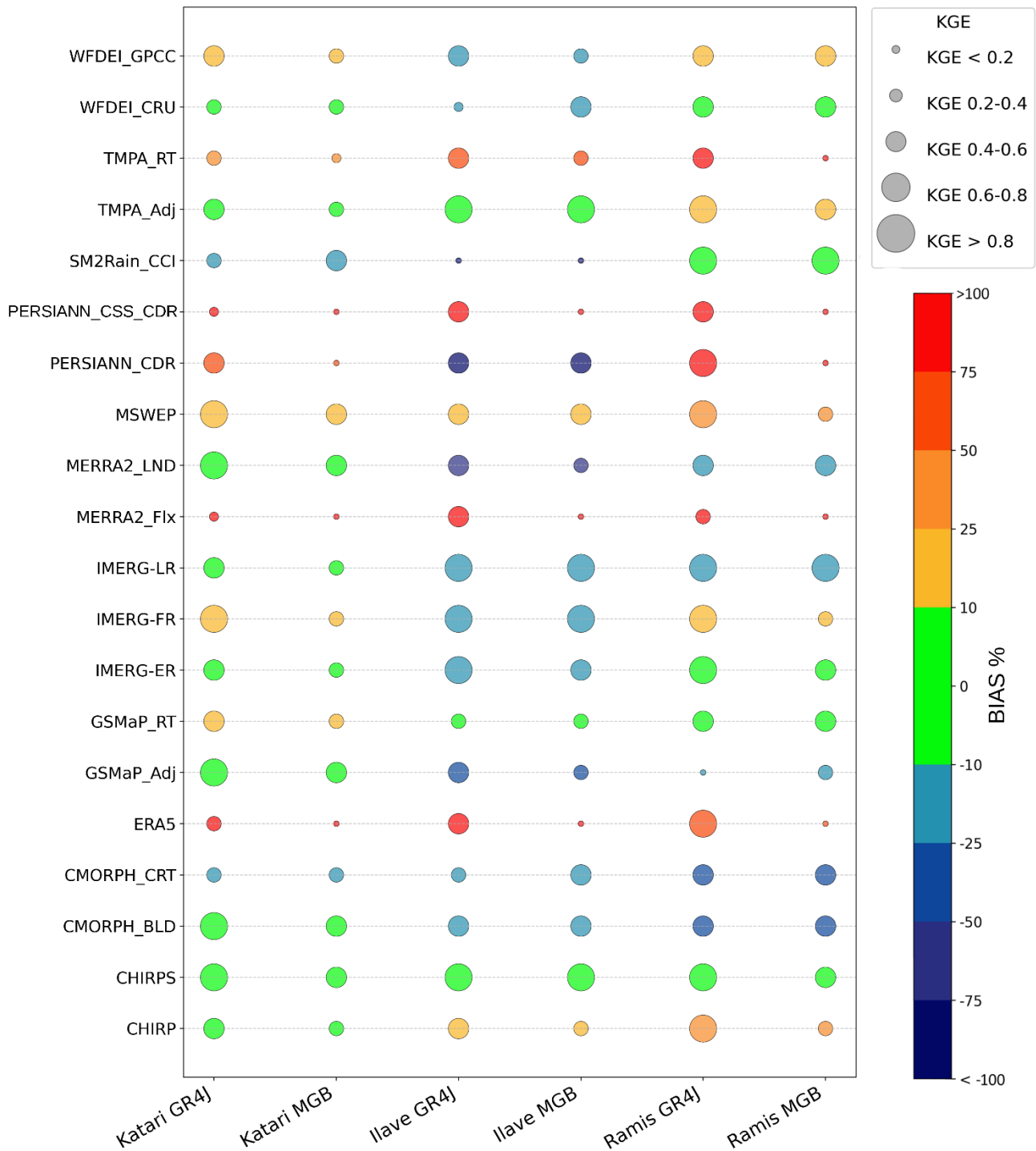
514 The MGB model is more sensitive to the spatial distribution of precipitation data and quantity and
515 cannot always compensate for significant inaccuracies in precipitation inputs, as seen in Figure 7. When
516 precipitation magnitude is well represented, with a bias close to zero, MGB successfully simulates streamflow
517 that closely matches observed values, as seen with SM2RAIN_CCI and TMPA_Adj. Moreover, MGB exhibits
518 greater robustness to negative biases, achieving a KGE above 0.8 in Katari (SM2RAIN_CCI), Ilave
519 (WFDEI_GPCC, IMERG-ER, IMERG-FR, IMERG-LR, CMORPH_CRT, CMORPH_BLD), and Ramis
520 (MERRA_LND, IMERG_ER, CMORPH_BLD, and CMORPH_CRT).

521 Noting that GPP biases significantly influence hydrological model performance, implementing bias
522 correction techniques could enhance GPP applicability. For instance, statistical bias correction methods (e.g.,
523 Machine Learning-Based) have been successfully applied (Li et al., 2023). Additionally, data fusion

524 approaches, which integrate multiple GPPs with ground-based observations, could help reduce uncertainties by
525 leveraging the strengths of different datasets (Chen et al., 2024).

526 The performance of the MGB model also appears to be influenced by basin size, with higher KGE values
527 observed in larger basins. The highest KGE was obtained in the Ramis basin (14,866 km², KGE=0.9), followed
528 by Ilave (7,720 km², KGE=0.86) and Katari (2,519 km², KGE=0.77) (Figure 5). This trend is consistent with
529 the fact that the MGB model was specifically designed for large-scale basins, which may explain the decline in
530 performance as basin size decreases. In large basins, spatial aggregation of precipitation data can smooth out
531 localized discrepancies and reduce the impact of errors in rainfall distribution (Vergara et al., 2014; Satgé et
532 al., 2021). In smaller basins, the influence of local-scale precipitation errors may be more pronounced, leading
533 to greater discrepancies between simulated and observed streamflow. Still, GR4J reliability slightly decreased
534 with the basin size, with the highest KGE of 0.93, 0.85, and 0.88 for the Ramis, Ilave, and Katari basins,
535 respectively (Figure 5), in line with a previous study carried out in the Amazon region (Satgé et al., 2021).

536 When representing streamflow variability, MGB tends to capture rapid fluctuations in streamflow, as
537 seen in Figure 6, whereas GR4J produces smoother hydrographs with attenuated peaks and troughs. This
538 difference in variability may influence the KGE calculation, as higher fluctuations in MGB-simulated
539 streamflow can introduce discrepancies in correlation, variability, and bias components, leading to lower KGE
540 values. In contrast, GR4J's smoother representation may result in higher KGE values if it better aligns with
541 general observed trends, even if it does not capture extreme events as effectively as MGB.



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Figure 7 Bubble plot illustrating the relationship between bias and KGE for the 20 GPPs across the GR4J and MGB hydrological models in the Katari, Ilave, and Ramis basins. Each bubble represents a model simulation using a given GPP, with its color indicating bias and size indicating KGE.

6. Conclusions

This study evaluated the performance of 20 Gridded Precipitation Products (GPPs) at the daily time step by comparing their estimates with the one observed by the meteorological stations network and using them as input for two hydrological models—the lumped GR4J and the semi-distributed MGB. By assessing the spatial and temporal accuracy of GPPs and their impact on streamflow simulations, the study offers several key insights:

- Based on the gauge's assessment, a moderate range in GPPs reliability is observed, showing the limit of such an approach. Moreover, such assessment is subject to uncertainties related to the different spatial scales between gauges (point measurements) and GPPs (gridded observations).
- Based on the hydrological modelling assessment, the range of model performance across the 20 GPPs was substantial, with apparent differences in GPPs' reliability depending on the considered basin and hydrological model.
- Due to its lumped structure, GR4J streamflow modeling is barely influenced by precipitation bias, making it suitable for small and less complex basins. On the contrary, due to its semi-distributed structure, MGB is sensitive to precipitation bias in space and time and therefore more suitable for large and complex basins.
- The models' structure influenced high and low flow streamflow simulation with GR4J (MGB) showing greater stability in low (high) flows than MGB (GR4J).
- From an end-user perspective, GPP-driven streamflow simulations outperformed gauge-based ones in two basins, confirming their potential to mitigate the effects of sparse and uneven station networks.
- High-spatial resolution GPPs (i.e., PERSIANN_CSS_CDR) did not necessarily yield better hydrological outcomes, suggesting that spatial resolution alone is not a reliable predictor of GPP performance.

These findings contribute to a deeper understanding of how model structure interacts with precipitation uncertainty in complex, high-altitude basins. The results provide practical recommendations for selecting

GPPs and modeling strategies in transboundary and data-scarce environments. Due to the observed GPP reliability variation in space, future research should explore ensemble-based approaches that integrate multiple GPPs along with additional variables affecting precipitation dynamics in space and time (e.g., topography, cloud cover properties, vegetation, temperature, atmospheric variables) to improve precipitation monitoring across the region.

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