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Point particle \mathcal{E} -models

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Abstract

We show that the same algebraic data that permit to construct the Lax pair and the r-matrix of an integrable non-linear σ -model in 1+1 dimensions can be also used for the construction of Lax pairs and of r-matrices of several other non-trivial integrable theories in 1+0 dimension. We call those new integrable theories the point particle \mathcal{E} -models, we describe their structure and give their physical interpretation. We work out in detail the point particle \mathcal{E} -modelsassociated to the bi-Yang-Baxter deformation of the SU(N) principal chiral model. In particular, for each complex flag manifold we thus obtain a two-parameter family of integrable models living on it.

1 Introduction

Integrable dynamical systems with finite and with infinite number degrees of freedom represent two related areas of research which often influenced each other in the past. The finite case is certainly more tractable analytically, but this fact does not really make easier the task to construct new integrable models comparing with the same task in the infinite case. Indeed, to identify the Lax pairs and the r-matrices of the models represent a tough problem in the both, finite and infinite, cases, and one may even argue that it was the progress in the infinite case in the sixties of the last century that changed the game also in the finite case and made possible to go beyond a few examples with finite (and low) number of degrees of freedom that had been known before. We stress at this point that the influence of the infinite on the finite was not merely at the level of a sort of inspiration but there exist explicit quantitative bridges linking the infinite to the finite. As an example of that situation we may mention the dynamics of a finite number of solitons of some infinite dimensional integrable field theories which turns out to be

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captured by the dynamics of the integrable systems with finite numbers of degrees of freedom, like the celebrated Calogero or Ruijsenaars-Schneider models [7, 42].

Nowadays, the integrability is still a very active domain of research, as we may wittness looking e.g. at the spectacular recent progress achieved in the field of integrable nonlinear σ -models describing string dynamics in curved backgrounds [22, 40, 10, 23, 8, 2, 9, 12, 11, 41, 13]. In the present article, we construct another bridge from the infinite to the finite, by associating nontrivial integrable systems with finite number of degrees of freedom to the recently constructed integrable nonlinear σ -models in 1+1 dimensions.

It turns out that the first order Hamiltonian dynamics of the most (if not all) of the known integrable nonlinear σ -models is expressible in terms of the so-called \mathcal{E} -models. Recall that the \mathcal{E} -model is a first order Hamiltonian dynamical system originally introduced in [18] in the context of generalized T-dualities in string theory and, somewhat surprisingly, it became clear only much later how useful is this concept also in the theory of integrable models [24, 26, 27, 33, 34, 36, 14, 15]. As its name suggests, the \mathcal{E} -model is constructed out of a quantity denoted by \mathcal{E} , which is actually any involutive symmetric linear operator acting on the Lie algebra \mathcal{D} of certain quadratic Lie group D referred to as the Drinfeld double. The symplectic form ω and the Hamiltonian $H_{\mathcal{E}}$ of the \mathcal{E} -model are given by the formulas¹

$$\omega = -\frac{1}{2} (l^{-1}dl \, \dot{\gamma} \, (l^{-1}dl)')_{L\mathcal{D}},\tag{1}$$

$$H_{\mathcal{E}} = \frac{1}{2} (l'l^{-1}, \mathcal{E} l'l^{-1})_{L\mathcal{D}}.$$
 (2)

Here $l = l(\sigma)$ is an element of the loop group LD and the prime denotes a particular derivative on the loop Lie algebra $L\mathcal{D}$ which is actually the standard derivative ∂_{σ} with respect to the loop parameter σ . Furthermore, $l^{-1}dl$ is the left-invariant Maurer-Cartan form on LD, $(.,.)_{L\mathcal{D}} \equiv \oint d\sigma(.,.)_{\mathcal{D}}$ is the non-degenerate ad-invariant symmetric bilinear form on $L\mathcal{D}$ where $(.,.)_{\mathcal{D}}$ is the canonical bilinear form with the same properties on \mathcal{D} .

Not every \mathcal{E} -model is integrable. However, if the data D, \mathcal{E} fulfil some sufficient conditions found in [39, 29] then the integrability is guaranteed, that is, one can construct the Lax matrix and the r-matrix of the \mathcal{E} -model $(\omega, H_{\mathcal{E}})$. Those sufficient conditions are quite simple and, what is essential for us, they have *finite* dimensional Lie algebraic character. Namely, it is required the existence of an one-parameter family of linear maps² $O(\lambda): \mathcal{D} \to \mathcal{G}$ verifying

$$[O(\lambda)x, O(\lambda)\mathcal{E}x]_{\mathcal{G}} = O(\lambda)[x, \mathcal{E}x]_{\mathcal{D}}, \quad \forall x \in \mathcal{D}$$
(3)

¹Strictly speaking, the phase space of the \mathcal{E} -model is the homogeneous space LD/D and the form ω on LD given by (1) is the pull-back of the true symplectic form by the projection map $LD \to LD/D$.

²If the spectral parameter λ takes a complex value, the map $O(\lambda)$ is considered as the map from \mathcal{D} to $\mathcal{G}^{\mathbb{C}}$.

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and of a two-parametric family of linear operators $\hat{r}(\lambda, \rho): \mathcal{G} \to \mathcal{G}$ verifying

$$[O^{\dagger}(\lambda)x, O^{\dagger}(\rho)y]_{\mathcal{D}} + O^{\dagger}(\lambda)[x, \hat{r}(\lambda, \rho)y]_{\mathcal{G}} + O^{\dagger}(\rho)[\hat{r}(\rho, \lambda)x, y]_{\mathcal{G}} = 0, \quad \forall x, y \in \mathcal{G}$$
 (4)

$$(O^{\dagger}(\lambda)x, O^{\dagger}(\rho)y)_{\mathcal{D}} + (x, \hat{r}(\lambda, \rho)y)_{\mathcal{G}} + (\hat{r}(\rho, \lambda)x, y)_{\mathcal{G}} = 0, \quad \forall x, y \in \mathcal{G}.$$
 (5)

Here \mathcal{G} is a Lie subalgebra of \mathcal{D} equipped with a quadratic structure $(.,.)_{\mathcal{G}}$ that is not necessarily induced by the quadratic structure $(.,.)_{\mathcal{D}}$, and $O(\lambda)^{\dagger}: \mathcal{G} \to \mathcal{D}$ is the adjoint of the operator $O(\lambda)$ defined by the relation

$$(O(\lambda)x, y)_{\mathcal{G}} = (x, O^{\dagger}(\lambda)y)_{\mathcal{D}}, \quad \forall x \in \mathcal{D}, \ y \in \mathcal{G}.$$

By now many solutions of the sufficient conditions (3), (4) and (5) are known, but our goal here is not to find yet some new ones. Instead, we want to show that to every known solution $D, \mathcal{E}, O(\lambda), \hat{r}(\lambda, \rho)$ of those sufficient conditions we may associate not just one integrable \mathcal{E} -model living on the loop group homogeneous space LD/D but also many other integrable theories with finite number of degrees of freedom living on appropriate homogeneous spaces of the group D. How this comes about?

Let $D, \mathcal{E}, O(\lambda), \hat{r}(\lambda, \rho)$ be a solution of the sufficient conditions (3),(4) and (5) and pick an element $\xi \in \mathcal{G} \subset \mathcal{D}$ such that it holds

$$\operatorname{ad}_{\xi}^{\mathcal{G}}\hat{r}(\lambda,\rho) - \hat{r}(\lambda,\rho)\operatorname{ad}_{\xi}^{\mathcal{G}} = 0, \quad \operatorname{ad}_{\xi}^{\mathcal{G}}O(\lambda) - O(\lambda)\operatorname{ad}_{\xi}^{\mathcal{D}} = 0.$$
 (6)

Then we can construct an integrable dynamical system living on a finite dimensional phase space which has the structure of the homogeneous space D/D_{ξ} , where D_{ξ} is the stabilizer of ξ by the adjoint action of D. The easiest way to describe the symplectic form and the Hamiltonian of this finite dynamical system is in terms of their pullbacks ω^{ξ} and H_{ξ}^{ξ} with respect to the projection map $D \to D/D_{\xi}$. They read

$$\omega^{\xi} = -\frac{1}{2} \left(l^{-1} dl \, \stackrel{\wedge}{,} \, (l^{-1} dl)' \right)_{\mathcal{D}},\tag{7}$$

$$H_{\mathcal{E}}^{\xi} = \frac{1}{2} \left(l' l^{-1}, \mathcal{E} l' l^{-1} \right)_{\mathcal{D}},\tag{8}$$

where

$$l'l^{-1} := \xi - \mathrm{Ad}_l \xi, \quad (l^{-1}dl)' := \mathrm{ad}_{\xi}(l^{-1}dl).$$

By an abuse of notation, we shall refer to ω^{ξ} and $H_{\mathcal{E}}^{\xi}$ as the symplectic form and the Hamiltonian and we shall call the dynamical system $(D/D_{\xi}, \omega^{\xi}, H_{\mathcal{E}}^{\xi})$ the point particle \mathcal{E} -model because of the similarity of the formulas (7),(8) with (1),(2).

Given the integrable string data $D, \mathcal{E}, O(\lambda), \hat{r}(\lambda, \rho)$, there are typically many solutions ξ of the supplementary conditions (6). The point particle \mathcal{E} -models based on the same data $D, \mathcal{E}, O(\lambda), \hat{r}(\lambda, \rho)$ but different choices of ξ are often dynamically nonequivalent. It is worth stressing that it is the expression $l'l^{-1} := \xi - \operatorname{Ad}_{l}\xi$ which is the crucial one for the whole construction. We elaborate more on its origin, on

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various choices of ξ and on the related residual gauge symmetries at the beginning of Section 3 and in Remark 4.1.

The \mathcal{E} -model, whether the standard string one living on LD/D or the point particle one living on D/D_{ξ} , is the first order Hamiltonian dynamical system. In order to give it a physical interpretation, we have to postulate which coordinates of the phase space play the role of coordinates on the configuration space and which are generalized momenta. In the stringy LD/D case, the momenta are parametrized via a choice of maximally isotropic subgroup H of the Drinfeld double D while the coordinates on the configuration space are expressed in terms of the functions on the space of cosets D/H. Said differently, the stringy \mathcal{E} -model is interpreted as the non-linear σ -model on the target space D/H, where the geometry of this target can be unambiguously extracted from the data (D, H, \mathcal{E}) (see [16, 17, 19, 29] for details).

In the point particle D/D_{ξ} case, the physical interpretation may be also achieved by choosing a maximally isotropic subgroup H of the Drinfeld double D, but the geometry of the configuration space, on which the point particle moves, depends on the choice of ξ . In Sections 5 and 6, we discuss several concrete examples working with two particular Drinfeld doubles of the group SU(N) and with various choices of $\xi \in \text{Lie}(SU(N))$. In all those cases the configuration space turns out to be an appropriate complex flag manifold. We do not provide all details here in the introduction, but we do give a flavour of what is going on by considering the Drinfeld double $D = T^*SU(2)$ and ξ being the generator of the Cartan subalgebra of su(2). Thus, for a suitable choice of \mathcal{E} , the configuration space turns out to be the standard sphere S^2 and the corresponding second order action of the point particle \mathcal{E} -model is

$$S = \frac{1}{2} \int dt \left(\dot{x}_1^2 + \dot{x}_2^2 + \dot{x}_3^2 + 4x_3 \right), \quad x_1^2 + x_2^2 + x_3^2 = 1.$$
 (9)

We recognize in (9) the action of the spherical mathematical pendulum in the homogeneous gravitational field which is of course known to be integrable. For comparison, in the string LD/D case, the same Drinfeld double $D = T^*SU(2)$ and the same operator \mathcal{E} turn out to give rise to the principal chiral model on the group SU(2) governed by the second order action

$$S = \frac{1}{2} \int d\tau d\sigma \operatorname{tr} \left(-(k^{-1}\dot{k})^2 + (k^{-1}k')^2 \right) =$$

$$= \int d\tau d\sigma \sum_{j=0}^{3} (\partial_{\tau} n_j \partial_{\tau} n_j - \partial_{\sigma} n_j \partial_{\sigma} n_j), \quad (10)$$

$$k = \begin{pmatrix} n_0 + in_3 & -n_1 + in_2 \\ n_1 + in_2 & n_0 - in_3 \end{pmatrix}, \quad n_0^2 + n_1^2 + n_2^2 + n_3^2 = 1.$$

Comparing the actions (9) and (10), we observe the the former is not the standard dimensional reduction of the latter. In particular, there is a potential

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The plan of the paper is as follows: In Section 2, we remind the structure of the LD/D string \mathcal{E} -models and, in Section 3, we describe in detail the structure of the D/D_{ξ} point particle \mathcal{E} -models. Then in Section 4, we show how to construct the Lax operators and the r-matrices of the integrable point particle \mathcal{E} -models out of the solutions $O(\lambda), \hat{r}(\lambda, \rho)$ of the sufficient conditions (3),(4) and (5). Then we work out examples of the point particle \mathcal{E} -models based on the Drinfeld doubles of the group SU(N); in Section 5 we work with the double $T^*SU(N)$ while in Section 6 with the Lu-Weinstein double $SL(N,\mathbb{C})$. In the both cases, we work out the second order actions on the configuration spaces which turn out to correspond to the motion of point particles on flag manifolds. We finish by conclusions and perspectives.

2 Reminder: stringy \mathcal{E} -models

Recall that the Drinfeld double D is a connected even-dimensional Lie group equipped with a bi-invariant pseudo-Riemannian metric of maximally-Lorentzian (split) signature. This pseudo-Riemannian metric naturally induces the non-degenerate ad-invariant symmetric bilinear form $(.,.)_{\mathcal{D}}$ defined on the Lie algebra \mathcal{D} of D.

A stringy \mathcal{E} -model, introduced in [18, 24], is the first-order Hamiltonian dynamical system $(\omega, H_{\mathcal{E}})$ living on the loop group homogeneous space LD/D. The pull-backs of the symplectic form and of the Hamiltonian from LD/D on LD are respectively given by the formulas

$$\omega = -\frac{1}{2} (l^{-1}dl \, \, \dot{\gamma} \, (l^{-1}dl)')_{L\mathcal{D}}, \tag{11}$$

$$H_{\mathcal{E}} = \frac{1}{2} (l'l^{-1}, \mathcal{E} l'l^{-1})_{L\mathcal{D}}.$$
 (12)

Here $l = l(\sigma)$ is an element of the loop group LD and the prime denotes the derivative ∂_{σ} with respect to the loop parameter σ . Furthermore, $l^{-1}dl$ is the left-invariant Maurer-Cartan form on LD and $(.,.)_{LD} \equiv \oint d\sigma(.,.)_{\mathcal{D}}$ is the non-degenerate ad-invariant symmetric bilinear form on LD. Finally, $\mathcal{E}: \mathcal{D} \to \mathcal{D}$ is the \mathbb{R} -linear operator squaring to identity, symmetric with respect to the bilinear form $(., \mathcal{E}.)_{\mathcal{D}}$ and such that the bilinear form $(., \mathcal{E}.)_{\mathcal{D}}$ on \mathcal{D} is strictly positive definite.

It turns out, that the left action of the group LD on LD/D is generated by the moment map $j = l'l^{-1}$. The components of the current j then verify the Poisson

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current algebra

$$\{(j(\sigma_1), T_1)_{\mathcal{D}}, (j(\sigma_2), T_2)_{\mathcal{D}}\} = (j(\sigma_1), [T_1, T_2])_{\mathcal{D}}\delta(\sigma_1 - \sigma_2) + (T_1, T_2)_{\mathcal{D}}\delta'(\sigma_1 - \sigma_2), \quad (13)$$

which plays a crucial role in the dynamics of the \mathcal{E} -models. Indeed, the Poisson brackets (13) as well as the explicit form (12) of the Hamiltonian give the following first order equations of motion of the \mathcal{E} -model

$$\frac{\partial j}{\partial \tau} = \{j, H_{\mathcal{E}}\} = (\mathcal{E}j)' + [\mathcal{E}j, j].$$

3 Point particle \mathcal{E} -models

To every stringy \mathcal{E} -model, we associate a family of dynamical systems living in 1+0 dimension which we shall call the point particle \mathcal{E} -models. Given the stringy \mathcal{E} -model and its underlying Drinfeld double D, each member of this associated family corresponds to some choice of an element ξ from the Lie algebra \mathcal{D} of the double. Thus, if $\xi \in \mathcal{D}$, the symplectic form and the Hamiltonian of the corresponding point particle \mathcal{E} -model are given by the formulas (see for comparison (11) and (12))

$$\omega^{\xi} = -\frac{1}{2} \left(l^{-1} dl \, \stackrel{\wedge}{,} \, (l^{-1} dl)' \right)_{\mathcal{D}},\tag{14}$$

$$H_{\mathcal{E}}^{\xi} = \frac{1}{2} \left(l' l^{-1}, \mathcal{E} l' l^{-1} \right)_{\mathcal{D}},\tag{15}$$

where now

$$l'l^{-1} := \xi - \mathrm{Ad}_l \xi, \quad (l^{-1}dl)' := \mathrm{ad}_{\xi}(l^{-1}dl).$$

Let us give some motivation, why we start our construction from the expression $l'l^{-1} := \xi - \mathrm{Ad}_l \xi$. Consider first the string case and note that the standard derivative ∂_{σ} with respect to the loop parameter is the (outer) derivation of the loop Lie algebra $L\mathcal{D}$. Given a loop group element $l \in LD$, the expression $\partial_{\sigma} - \mathrm{Ad}_l \partial_{\sigma} \mathrm{Ad}_{l^{-1}}$ is then also a derivation acting on $L\mathcal{D}$ but that time it is the *inner* derivation because we have

$$\partial_{\sigma} - \mathrm{Ad}_{l} \partial_{\sigma} \mathrm{Ad}_{l^{-1}} = \mathrm{ad}_{\partial_{\sigma} l l^{-1}} \equiv \mathrm{ad}_{l' l^{-1}}.$$
 (16)

Summarizing, to the derivation ∂_{σ} and to the group element l we have associated another derivation $\mathrm{ad}_{\partial\sigma ll^{-1}}$ and it is the Lie algebra element $\partial_{\sigma}ll^{-1}$ featuring in it which plays the crucial role in the construction of the string symplectic form (11) and the string Hamiltonian (12).

The key observation which is at the origin of our construction in the present paper is the following. If we replace LD by the finite-dimensional group D and the outer derivation ∂_{σ} acting on $L\mathcal{D}$ by an arbitrary inner one ad_{ξ} acting on \mathcal{D} , then we can also associate an appropriate inner derivation to the pair ad_{ξ} and $l \in D$ by the analogue of the expression (16):

$$ad_{\xi} - Ad_{l}ad_{\xi}Ad_{l-1} = ad_{\xi - Ad_{l}\xi}.$$
(17)

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Again by the analogy with (16), we use the notation $l'l^{-1} := \xi - \operatorname{Ad}_{l}\xi$ because it permits us to write down in the finite dimensional case formally the identical expressions for the symplectic form (14) and the Hamiltonian (15) as the stringy expressions (11) and (12).

If we do not care for the integrability of the constructed dynamical system, then in the finite dimensional case whatever choice $\xi \in \mathcal{D}$ is consistent. Indeed, we observe that the Drinfeld-Kirillov form (14) is closed for every $\xi \in \mathcal{D}$ because it can be written as

$$\omega^{\xi} = -d(\xi, l^{-1}dl)_{\mathcal{D}}.\tag{18}$$

Note in this respect that the form ω^{ξ} is only presymplectic and not symplectic since it is never non-degenerate, whatever $\xi \in \mathcal{D}$ we choose. However, the form ω^{ξ} can be made symplectic in the canonical way by factorizing out all (gauge) vector fields in its kernel. Concretely, ω^{ξ} is the pull-back of a closed non-degenerate (hence truly symplectic) form ω_c^{ξ} living on the space of cosets D/D_{ξ} , where the gauge subgroup $D_{\xi} \subset D$ is determined by the condition that it stabilizes ξ under the adjoint action of D on \mathcal{D} . We have thus

$$\omega^{\xi} = \pi_{\xi}^* \omega_c^{\xi},$$

where $\pi_{\xi}: D \to D/D_{\xi}$ is the projection mapping. Note that the dimension of the phase space D/D_{ξ} depends substantially on the choice of ξ .

As far as the Hamiltonian (15) is concerned, it is worth remarking that it is invariant with respect to the residual D_{ξ} gauge symmetry by construction. Indeed, since the expression $l'l^{-1} := \xi - \operatorname{Ad}_{l}\xi$ is D_{ξ} -invariant, the Hamiltonian (15) is D_{ξ} -invariant, too. It is this invariance which is needed for the consistency of our construction because it guarantees that it exists a function $H_{\xi,c}^{\xi}$ living on the space of cosets D/D_{ξ} such that

$$H_{\mathcal{E}}^{\xi} = \pi_{\varepsilon}^* H_{\varepsilon,c}^{\xi}.$$

It is the function $H_{\mathcal{E},c}^{\xi}$ which is the Hamiltonian living on the symplectic manifold D/D_{ξ} .

All in all, the ξ -version of the point particle \mathcal{E} -model is the finite-dimensional dynamical system living on the symplectic manifold D/D_{ξ} , having the symplectic form ω_c^{ξ} and the Hamiltonian $H_{\mathcal{E},c}^{\xi}$. However, somewhat abusively, we shall often continue to refer to D as the phase space and to the quantities ω^{ξ} and $H_{\mathcal{E}}^{\xi}$ living on D as to the symplectic form and the Hamiltonian of the ξ -version of the point particle \mathcal{E} -model.

It turns out, that the left action ∇^L of the group D on the homogeneous space D/D_{ξ} is generated by the moment map $j = l'l^{-1}$. This means that it holds

$$\nabla_T^L f := \left(\frac{d}{ds}\right)_{s=0} f(e^{sT}l) = \{f, (j, T)_{\mathcal{D}}\}_{\xi}, \quad T \in \mathcal{D}$$
 (19)

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where f is a function on D/D_{ξ} and $\{.,.\}_{\xi}$ is a Poisson bracket induced by the symplectic form ω_c^{ξ} . In particular, we obtain from the bracket (19) the following Poisson current algebra (cf. the formula (13))

$$\{(j, T_1)_{\mathcal{D}}, (j, T_2)_{\mathcal{D}}\}_{\xi} = (j, [T_1, T_2])_{\mathcal{D}} + (T_1, [\xi, T_2])_{\mathcal{D}}. \tag{20}$$

As in the string case, the first order equations of motion of the point particle \mathcal{E} -model is

$$\frac{dj}{d\tau} = \{j, H_{\mathcal{E}}^{\xi}\}_{\xi} = (\mathcal{E}j)' + [\mathcal{E}j, j], \tag{21}$$

but now we have $(\mathcal{E}j)' = [\xi, \mathcal{E}j]$.

Integrable point particle \mathcal{E} -models 4

In this section, we deal with integrable point particle \mathcal{E} -models $(D/D_{\xi}, \omega^{\xi}, H_{\varepsilon}^{\xi})$. The most important conclusion of the present article is the fact that the stringy sufficient conditions of integrability (3),(4),(5) guarantee the integrability also in the point particle case provided they are supplemented by two more conditions (22), (24) involving the element ξ . We gather all those conditions as follows

1) It exists a one-parameter family of linear maps $O(\lambda): \mathcal{D} \to \mathcal{G}$ which verifies

$$\operatorname{ad}_{\xi}^{\mathcal{G}}O(\lambda) - O(\lambda)\operatorname{ad}_{\xi}^{\mathcal{D}} = 0, \tag{22}$$

$$[O(\lambda)x, O(\lambda)\mathcal{E}x]_{\mathcal{G}} = O(\lambda)[x, \mathcal{E}x]_{\mathcal{D}}, \quad \forall x \in \mathcal{D},$$
(23)

where \mathcal{G} is a Lie subalgebra of \mathcal{D} such that $\xi \in \mathcal{G}$;

2) It exists a two-parametric family of linear operators $\hat{r}(\lambda, \rho): \mathcal{G} \to \mathcal{G}$ which verifies

$$\operatorname{ad}_{\varepsilon}^{\mathcal{G}}\hat{r}(\lambda,\rho) - \hat{r}(\lambda,\rho)\operatorname{ad}_{\varepsilon}^{\mathcal{G}} = 0, \tag{24}$$

$$[O^{\dagger}(\lambda)x, O^{\dagger}(\rho)y]_{\mathcal{D}} + O^{\dagger}(\lambda)[x, \hat{r}(\lambda, \rho)y]_{\mathcal{G}} + O^{\dagger}(\rho)[\hat{r}(\rho, \lambda)x, y]_{\mathcal{G}} = 0, \quad \forall x, y \in \mathcal{G}, (25)$$

$$(O^{\dagger}(\lambda)x, O^{\dagger}(\rho)y)_{\mathcal{D}} + (x, \hat{r}(\lambda, \rho)y)_{\mathcal{G}} + (\hat{r}(\rho, \lambda)x, y)_{\mathcal{G}} = 0, \quad \forall x, y \in \mathcal{G},$$
 (26)

where the quadratic structure $(.,.)_{\mathcal{G}}$ on \mathcal{G} is not necessarily induced by the quadratic structure $(.,.)_{\mathcal{D}}$ on \mathcal{D} and $O(\lambda)^{\dagger}: \mathcal{G} \to \mathcal{D}$ is the adjoint of the operator $O(\lambda)$ defined by the relation

$$(O(\lambda)x, y)_{\mathcal{G}} = (x, O^{\dagger}(\lambda)y)_{\mathcal{D}}, \quad \forall x \in \mathcal{D}, y \in \mathcal{G}.$$

Remark 4.1 In the present paper we shall exclusively consider situations in which the subalgebra \mathcal{G} is compact. In this case, for whatever choice of $\xi \in \mathcal{G}$, it exists a Cartan subalgebra \mathcal{T} of \mathcal{G} such that \mathcal{E} belongs to \mathcal{T} therefore, without lack of generality, we may always consider ξ belonging to the Cartan subalgebra.

Having a solution $O(\lambda)$, $\hat{r}(\lambda, \rho)$ of the sufficient conditions 1), 2), we must show how to construct out of it the Lax pair $L(\lambda)$, $M(\lambda)$ and the dynamical r-matrix

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 $r(\lambda, \rho)$ governing the Poisson brackets of the matrix elements of the Lax matrix $L(\lambda)$. We do it similarly as in the string case [39, 29] by postulating

$$L(\lambda) = \xi - O(\lambda)j,\tag{27}$$

$$M(\lambda) = -O(\lambda)\mathcal{E}j. \tag{28}$$

Using (23), it can be checked easily, that the equations of motion (21) can be represented in the Lax form with spectral parameter

$$\{L(\lambda), H_{\mathcal{E}}\}_{\xi} = \frac{dL(\lambda)}{dt} = [L(\lambda), M(\lambda)]_{\mathcal{G}}.$$
 (29)

Now set

$$r(\lambda, \rho) = C_{AB}(\hat{r}(\lambda, \rho)T^A) \otimes T^B, \tag{30}$$

where C_{AB} is the inverse matrix of the matrix C^{AB} defined by

$$C^{AB} := (T^A, T^B)_{\mathcal{G}},$$
 (31)

and T^A is some basis of the Lie algebra \mathcal{G} on the choice of which actually the r-matrix (30) does not depend.

We wish to show, that the quantity $r(\lambda, \rho)$ defined by (30) is the r-matrix of the point particle \mathcal{E} -model, which, following the general theory of the Lax integrable systems (cf. [1]), means the validity of the following fundamental relation

$$\{L(\lambda) \stackrel{\otimes}{,} L(\rho)\}_{\xi} = [r(\lambda, \rho), L(\lambda) \otimes \operatorname{Id}] - [r^p(\rho, \lambda), \operatorname{Id} \otimes L(\rho)].$$
 (32)

Here the notation r^p means

$$r^p = \sum_{\alpha} B_{\alpha} \otimes A_{\alpha},$$

provided r has the form

$$r = \sum_{\alpha} A_{\alpha} \otimes B_{\alpha}$$

for some family of elements $A_{\alpha}, B_{\alpha} \in \mathcal{G}$.

To see that the relation (32) is indeed satisfied, we calculate its matrix components. On the left-hand-side, we obtain for every $x, y \in \mathcal{G}$

$$\{(x, L(\lambda))_{\mathcal{G}}, (y, L(\rho))_{\mathcal{G}}\} = \{(x, O(\lambda)j)_{\mathcal{G}}, (y, O(\rho)j)_{\mathcal{G}}\} =$$

$$= (j, [O^{\dagger}(\lambda)x, O^{\dagger}(\rho)y]_{\mathcal{D}})_{\mathcal{D}} + (O^{\dagger}(\lambda)x, [\xi, O^{\dagger}(\rho)y]_{\mathcal{D}})_{\mathcal{D}}, \quad (33)$$

where we have used the Poisson brackets (20). On the right-hand-side, we obtain

$$-(O(\lambda)j, [x, \hat{r}(\lambda, \rho)y])_{\mathcal{G}} - (O(\rho)j, [\hat{r}(\rho, \lambda)x, y])_{\mathcal{G}} + ([\xi, x], \hat{r}(\lambda, \rho)y)_{\mathcal{G}} - ([\xi, y], \hat{r}(\rho, \lambda)x)_{\mathcal{G}}.$$
(34)

Now because of the conditions (25),(26) and (22), the expression (34) matches precisely (33).

The validity of the Lax equation (29) and of the relation (32) means by definition the integrability of the model.

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5 The Drinfeld double T^*K

Point particle principal chiral model 5.1

Let K be a simple compact connected and simply connected Lie group and denote by $(.,.)_{\mathcal{K}}$ the standard Killing-Cartan form on its Lie algebra \mathcal{K} . Then the cotangent bundle T^*K of the Lie group K can be given the structure of the Drinfeld double D. To see this, parametrize the elements of the cotangent bundle by the pairs (k,κ) , $k\in K$, $\kappa\in\mathcal{K}$. If 1 stands for the unit element of K and 0 is the neutral element of K (it is actually the unit element of the additive Abelian group underlying the vector space \mathcal{K}) then the unit element of $D = T^*K$ is

$$e = (1,0).$$

Furthermore, the inverse element is

$$(k, \kappa)^{-1} = (k^{-1}, -\mathrm{Ad}_{k^{-1}}\kappa).$$

and the group multiplication law reads

$$(k_1, \kappa_1)(k_2, \kappa_2) = (k_1 k_2, \kappa_1 + \operatorname{Ad}_{k_1} \kappa_2), \quad k_1, k_2 \in K, \ \kappa_1, \kappa_2 \in K.$$

The symmetric non-degenerate ad-invariant bilinear form $(.,.)_{\mathcal{D}}$ on the Lie algebra \mathcal{D} is given by

$$((\mu_1, \nu_1), (\mu_2, \nu_2))_{\mathcal{D}} = (\mu_1, \nu_2)_{\mathcal{K}} + (\mu_2, \nu_1)_{\mathcal{K}}, \quad \mu_{1,2}, \nu_{1,2} \in \mathcal{K},$$

where $(.,.)_{\mathcal{K}}$ is the standard Killing-Cartan form on \mathcal{K} . The form $(.,.)_{\mathcal{K}}$ is strictly negative definite while the form $(.,.)_{\mathcal{D}}$ has the split signature $(+,\ldots,+,-,\ldots,-)$. The ad-invariance can be checked by using the following formula expressing the adjoint action of D on \mathcal{D}

$$Ad_{(k,\kappa)}(\mu,\nu) = (Ad_k\mu, Ad_k\nu + ad_\kappa Ad_k\mu). \tag{35}$$

We may now define a natural \mathcal{E} -model on the double $D = T^*K$ by defining the operator $\mathcal{E}: \mathcal{D} \to \mathcal{D}$ as

$$\mathcal{E}(\mu,\nu) = -(\nu,\mu). \tag{36}$$

It is evident that $\mathcal{E}^2 = \text{Id}$, moreover the form $(., \mathcal{E}.)_{\mathcal{D}}$ is positive definite since

$$((\mu_1, \nu_1), \mathcal{E}(\mu_2, \nu_2))_{\mathcal{D}} = -(\mu_1, \mu_2)_{\mathcal{K}} - (\nu_1, \nu_2)_{\mathcal{K}}.$$
 (37)

Finally, the formula (37) implies also the symmetry of \mathcal{E}

$$\left(\mathcal{E}(\mu_1,\nu_1),(\mu_2,\nu_2)\right)_{\mathcal{D}} = \left((\mu_1,\nu_1),\mathcal{E}(\mu_2,\nu_2)\right)_{\mathcal{D}}.$$

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Let $\zeta \in \mathcal{K}$ be an element of the Lie algebra \mathcal{K} and denote by K_{ζ} its stabilizer under the adjoint action of K on K. It is then easy to derive from the formula (35), that the stabilizer D_{ξ} of the element $\xi = (\zeta, 0)$ is the cotangent bundle of the stabilizer K_{ζ} $D_{\varepsilon} = \{(k, \kappa) \in T^*K, k \in K_{\varepsilon}, \kappa \in \mathcal{K}_{\varepsilon}\}.$ In order to calculate the Hamiltonian and the symplectic form of the point particle \mathcal{E} -model for $D = T^*K$, \mathcal{E} given by Eq.(36) and $\xi = (\zeta, 0)$, it is convenient to parametrize the elements $l = T^*K$ as

$$l = (k, 0)(1, \rho), \qquad k \in K, \quad \rho \in \mathcal{K}.$$

Then we have

$$j \equiv l'l^{-1} = \xi - \mathrm{Ad}_{l}\xi = (k'k^{-1}, \mathrm{Ad}_{k}\rho'),$$
 (38)

where

$$k'k^{-1} := \zeta - \mathrm{Ad}_k\zeta, \quad \rho' := \mathrm{ad}_{\zeta}\rho.$$

Using the formula (15), we find

$$H_{\mathcal{E}}^{\xi} = -\frac{1}{2} (k'k^{-1}, k'k^{-1})_{\mathcal{K}} - \frac{1}{2} (\rho', \rho')_{\mathcal{K}}.$$
 (39)

In order to calculate the symplectic form (18), we need the formula for the left Maurer-Cartan form on D

$$l^{-1}dl \equiv (k, \kappa)^{-1}d(k, \kappa) = (k^{-1}dk, \operatorname{Ad}_{k^{-1}}(d\kappa)),$$

We obtain

$$\omega^{\xi} = d(\rho', k^{-1}dk)_{\mathcal{K}}.\tag{40}$$

The formulas (39) and (40) permit to write down the first order action principle for the point particle principal chiral model as

$$S(k,\rho) = \int dt \Big((\rho', k^{-1}\dot{k})_{\mathcal{K}} + \frac{1}{2} (k'k^{-1}, k'k^{-1})_{\mathcal{K}} + \frac{1}{2} (\rho', \rho')_{\mathcal{K}} \Big). \tag{41}$$

Note that the variable ρ' takes values in $\mathcal{K}_{\zeta}^{\perp}$. Varying the action (41) with respect to ρ' gives

$$\rho' = -P^{\perp}(k^{-1}\dot{k}),\tag{42}$$

where P^{\perp} is the orthogonal projector which projects on the vector space $\mathcal{K}_{\zeta}^{\perp}$. Inserting (42) back into the action (41) gives rise to the second order action

$$S(k) = \frac{1}{2} \int dt \Big(-(P^{\perp}k^{-1}\dot{k}, P^{\perp}k^{-1}\dot{k})_{\mathcal{K}} + (k^{-1}k', k^{-1}k')_{\mathcal{K}} \Big), \tag{43}$$

where

$$k^{-1}k' := k^{-1}(k'k^{-1})k = k^{-1}\zeta k - \zeta.$$

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Note that the action (43) describe the motion of a point particle on the space of cosets K/K_{ζ} . Indeed, the action (43) has a gauge symmetry $k(t) \to k(t)h(t)$, where h(t) is an arbitrary function of the time t taking values in the stabilizer group K_{ζ} .

For comparison, the stringy \mathcal{E} -model based on the same data $D = T^*K$ and \mathcal{E} given by (36) leads to the following second order action

$$S(k) = \frac{1}{2} \int dt d\sigma \Big(-(k^{-1}\dot{k}, k^{-1}\dot{k})_{\mathcal{K}} + (k^{-1}k', k^{-1}k')_{\mathcal{K}} \Big).$$

In particular, for K=SU(2) and $\zeta=\begin{pmatrix} \mathrm{i} & 0 \\ 0 & -\mathrm{i} \end{pmatrix}$ we obtain the actions listed already in the Introduction. In the point particle case it is that of the spherical pendulum in the homogeneous gravitational field

$$S = \frac{1}{2} \int dt \left(\dot{x}_1^2 + \dot{x}_2^2 + \dot{x}_3^2 + 4x_3 \right), \quad x_1^2 + x_2^2 + x_3^2 = 1$$

and in the stringy case it is that of the O(4) nonlinear σ -model in 1+1-dimensions

$$S = \int d\tau d\sigma \sum_{j=0}^{3} (\partial_{\tau} n_{j} \partial_{\tau} n_{j} - \partial_{\sigma} n_{j} \partial_{\sigma} n_{j}), \quad n_{0}^{2} + n_{1}^{2} + n_{2}^{2} + n_{3}^{2} = 1.$$

5.2 Integrability

Let us show that the point particle principal chiral model is integrable. For that we take the Lie algebra \mathcal{G} to be just \mathcal{K} equipped with its standard Killing-Cartan form $(.,.)_{\mathcal{G}} = (.,.)_{\mathcal{K}}$. By the very logic of this article, we borrow the required operators $O(\lambda)$, $\hat{r}(\lambda, \rho)$ from the stringy principal chiral model. They are given by [10, 28]

$$\hat{r}(\lambda, \rho) = \frac{\rho^2}{1 - \rho^2} \frac{1}{\rho - \lambda} \text{Id},$$

$$O(\lambda)(\mu, \nu) := \frac{\mu - \lambda \nu}{1 - \lambda^2}, \quad O^{\dagger}(\lambda)\mu = \left(\frac{-\mu \lambda}{1 - \lambda^2}, \frac{\mu}{1 - \lambda^2}\right) \quad (44)$$

and they therefore verify the conditions (23), (25), (26) automatically. We then check easily that the remaining conditions (22), (24) are also satisfied, so we conclude that the point particle principal chiral model (43) is integrable. Using (38), we find the corresponding Lax pair (27) and (28)

$$L(\lambda) = \zeta - \frac{1}{1 - \lambda^2} (k'k^{-1} - \lambda k\rho' k^{-1}),$$

$$M(\lambda) = -\frac{1}{1 - \lambda^2} (\lambda k' k^{-1} - k\rho' k^{-1}).$$
(45)

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Taking into account the equation (42), we can rewrite the Lax pair (45) as

$$L(\lambda) = \zeta - \frac{k'k^{-1} + \lambda kP^{\perp}(k^{-1}\dot{k})k^{-1}}{1 - \lambda^2},$$

$$M(\lambda) = -\frac{\lambda k'k^{-1} + kP^{\perp}(k^{-1}\dot{k})k^{-1}}{1 - \lambda^2}$$
(46)

and the Lax equation $\dot{L} = [L, M]_{\mathcal{K}}$ becomes

$$\frac{1}{1-\lambda^{2}} \left(-\partial_{\tau}(k'k^{-1}) + \left(kP^{\perp}(k^{-1}\dot{k})k^{-1}\right)' - \left[k'k^{-1}, kP^{\perp}(k^{-1}\dot{k})k^{-1}\right] \right) + \\
+ \frac{\lambda}{1-\lambda^{2}} \left(\left(k'k^{-1}\right)' - \partial_{\tau} \left(kP^{\perp}(k^{-1}\dot{k})k^{-1}\right) \right) = 0. \quad (47)$$

Since (47) must hold for all values of λ , we obtain two conditions to fulfill

$$-\partial_{\tau}(k'k^{-1}) + \left(kP^{\perp}(k^{-1}\dot{k})k^{-1}\right)' - [k'k^{-1}, kP^{\perp}(k^{-1}\dot{k})k^{-1}] = 0, \tag{48}$$

$$(k'k^{-1})' - \partial_{\tau} \left(kP^{\perp}(k^{-1}\dot{k})k^{-1} \right) = 0.$$
 (49)

In fact, the first condition (48) is fulfilled automatically, it is the so called Bianchi identity. The second condition (49) is the second order equation of motion of the point particle principal chiral model.

5.3 Point particle on \mathbb{CP}^N

It is instructive to work out the point particle principal chiral model for the case of the group K = SU(N+1) and of the element

$$\zeta = i \begin{pmatrix} \mathbf{1}_N & 0\\ 0 & -N \end{pmatrix}, \tag{50}$$

where $\mathbf{1}_N$ stands for the unit $N \times N$ matrix. In this case the stabilizer group K_{ζ} is the biggest possible, it has the structure $S(U(N) \times U(1))$, where the factor U(1) is generated by the element ζ itself and U(N) is formed by the unitary matrices of the form $\begin{pmatrix} h & 0 \\ 0 & 1 \end{pmatrix}$. The configuration space K/K_{ζ} of the models is thus the space of cosets $SU(N+1)/S(U(N) \times U(1))$ which is nothing but the complex projective space \mathbb{CP}^N .

We now evaluate the second order action (43) on the \mathbb{CP}^N on the chart where the (N+1)-th homogeneous coordinate Z^{N+1} does not vanish. We can parametrize this chart by a complex N-vector χ of the norm strictly inferior to 1 so that the homogeneous coordinates Z^j , j=1,...,N+1 are of the form

$$Z^{1} = \lambda \chi^{1}, \ Z^{1} = \lambda \chi^{2}, \ \dots, \ Z^{N} = \lambda \chi^{N}, \ Z^{N+1} = \lambda \sqrt{1 - |\boldsymbol{\chi}|^{2}},$$
 (51)

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where λ is an arbitrary non-vanishing complex number. In what follows we choose $\lambda = 1$, which implies, in particular

$$\sum_{j=1}^{N+1} \bar{Z}^j Z^j = 1.$$

We fix the gauge in (43) by setting $k = \mathbf{1}_{N+1}$ for $\chi = \mathbf{0}$ and

$$k = \begin{pmatrix} \mathbf{1}_N - \alpha \boldsymbol{\chi} \otimes \boldsymbol{\chi}^{\dagger} & \boldsymbol{\chi} \\ -\boldsymbol{\chi}^{\dagger} & \sqrt{1 - |\boldsymbol{\chi}|^2} \end{pmatrix}, \ \alpha = \frac{1 - \sqrt{1 - |\boldsymbol{\chi}|^2}}{|\boldsymbol{\chi}|^2}, \ \boldsymbol{\chi} \neq \mathbf{0},$$
 (52)

which gives, in particular

$$k^{-1}k' = (N+1)i \begin{pmatrix} -\boldsymbol{\chi} \otimes \boldsymbol{\chi}^{\dagger} & \sqrt{1-|\boldsymbol{\chi}|^2}\boldsymbol{\chi} \\ \sqrt{1-|\boldsymbol{\chi}|^2}\boldsymbol{\chi}^{\dagger} & |\boldsymbol{\chi}|^2, \end{pmatrix}$$
 (53)

$$P^{\perp}k^{-1}\dot{k} =$$

$$= \begin{pmatrix} \mathbf{0} & \dot{\boldsymbol{\chi}} - \sqrt{1 - |\boldsymbol{\chi}|^2}\boldsymbol{\chi} - \alpha(\boldsymbol{\chi}^{\dagger}\dot{\boldsymbol{\chi}})\boldsymbol{\chi} \\ -\dot{\boldsymbol{\chi}}^{\dagger} + \sqrt{1 - |\boldsymbol{\chi}|^2}\boldsymbol{\chi}^{\dagger} + \alpha(\dot{\boldsymbol{\chi}}^{\dagger}\boldsymbol{\chi})\boldsymbol{\chi}^{\dagger} & 0 \end{pmatrix} (54)$$

$$(k^{-1}k', k^{-1}k')_{\kappa} = -2(N+1)^2|\boldsymbol{\chi}|^2.$$

The point particle principal chiral model action (43) therefore becomes

$$S(\boldsymbol{\chi}) = \int dt \left(\left| \dot{\boldsymbol{\chi}} - \sqrt{1 - |\boldsymbol{\chi}|^2} \boldsymbol{\chi} - \alpha (\boldsymbol{\chi}^{\dagger} \dot{\boldsymbol{\chi}}) \boldsymbol{\chi} \right|^2 - (N+1)^2 |\boldsymbol{\chi}|^2 \right).$$
 (55)

Using the notation (51) for $\lambda = 1$, the second-order action (55) can be rewritten as

$$S(\mathbf{Z}) = \int dt \left(|\dot{\mathbf{Z}}|^2 - |\mathbf{Z}^{\dagger} \dot{\mathbf{Z}}|^2 + (N+1)^2 (|Z_{N+1}|^2 - 1) + \Lambda(|\mathbf{Z}|^2 - 1) \right), \quad (56)$$

where Λ is a real Lagrange multiplier and a complex (N+1)-vector \boldsymbol{Z} has the components

$$oldsymbol{Z} = egin{pmatrix} Z_1 \ Z_2 \ dots \ Z_N \ Z_{N+1} \end{pmatrix}.$$

The action (56) is defined globally, that is it makes sense not only on the (dense open) chart χ but on the whole \mathbb{CP}^N space parametrized by the homogeneous coordinates normalized by the condition $|\mathbf{Z}|^2 = 1$. It has a gauge symmetry

$$Z \to e^{i\beta(t)}Z$$
, $\Lambda \to \Lambda - i\dot{\beta}(Z^{\dagger}\dot{Z} - \dot{Z}^{\dagger}Z) + \dot{\beta}^2|Z|^2$,

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$$Z = \begin{pmatrix} \chi_1 \\ \chi_2 \\ \vdots \\ \vdots \\ \chi_N \\ \sqrt{1 - |\chi|^2} \end{pmatrix} \equiv \begin{pmatrix} \chi \\ \sqrt{1 - |\chi|^2} \end{pmatrix}, \quad |\chi| < 1.$$
 (57)

Inserting (57) into the action (56), we recover the action (55).

Remark 5.1 The standard Fubini-Study metric on the \mathbb{CP}^N expressed in the normalized homogeneous coordinates is

$$ds_{FS}^2 = |d\mathbf{Z}|^2 - |\mathbf{Z}^{\dagger} d\mathbf{Z}|^2. \tag{58}$$

We thus observe, that that our point particle principal chiral model corresponds to the motion in the standard Fubini-Study metric and in the quadratic potential depending on just one of the normalized homogeneous coordinates.

We can make explicit also the first order action (41) . To do this, we parametrize $\rho' \in \mathcal{K}_{\zeta}^{\perp}$ in the block matrix way as

$$\rho' = i \begin{pmatrix} \mathbf{0} & \mathbf{w} \\ \mathbf{w}^{\dagger} & 0 \end{pmatrix}, \tag{59}$$

where \boldsymbol{w} is a complex N-vector. The first order action (41) on the chart where Z_{N+1} does not vanish is then

$$S(\boldsymbol{w}, \boldsymbol{\chi}) = -\int dt \Big(2\Im(\boldsymbol{w}^{\dagger}(\dot{\boldsymbol{\chi}} - \sqrt{1 - |\boldsymbol{\chi}|^2}\boldsymbol{\chi} - \alpha(\boldsymbol{\chi}^{\dagger}\dot{\boldsymbol{\chi}})\boldsymbol{\chi})) + + \boldsymbol{w}^{\dagger}\boldsymbol{w} + (N+1)^2\boldsymbol{\chi}^{\dagger}\boldsymbol{\chi} \Big). \quad (60)$$

It is convenient to trade³ the variable ${\boldsymbol w}$ for another one denoted as ${\boldsymbol p}$

$$p = w - \frac{w^{\dagger} \chi - \chi^{\dagger} w}{2\sqrt{1 - |\chi|^2}} \chi - \alpha(\chi^{\dagger} w) \chi,$$

the action (60) can be then rewritten as

$$\boldsymbol{w} = \boldsymbol{p} + \frac{\boldsymbol{p}^{\dagger} \boldsymbol{\chi} - \boldsymbol{\chi}^{\dagger} \boldsymbol{p}}{2\sqrt{1 - |\boldsymbol{\chi}|^2}} \boldsymbol{\chi} + \frac{\alpha}{\sqrt{1 - |\boldsymbol{\chi}|^2}} (\boldsymbol{\chi}^{\dagger} \boldsymbol{p}) \boldsymbol{\chi}.$$
 (61)

³ Inversely, we have

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$S(\boldsymbol{p}, \boldsymbol{\chi}) = \int dt \left(i\boldsymbol{p}^{\dagger} \dot{\boldsymbol{\chi}} - i \dot{\boldsymbol{\chi}}^{\dagger} \boldsymbol{p} - \boldsymbol{p}^{\dagger} \boldsymbol{p} - \frac{(\boldsymbol{\chi}^{\dagger} \boldsymbol{p} + \boldsymbol{p}^{\dagger} \boldsymbol{\chi})^{2}}{4(1 - |\boldsymbol{\chi}|^{2})} \right) + \int dt \left(\frac{1}{4} (\boldsymbol{\chi}^{\dagger} \boldsymbol{p} - \boldsymbol{p}^{\dagger} \boldsymbol{\chi})^{2} + (N+1)^{2} \boldsymbol{\chi}^{\dagger} \boldsymbol{\chi} \right). \quad (62)$

Looking at the first order actions (60), (62), we can deduce the symplectic form and the Hamiltonian of the model to be

$$\omega = -2d\Im(\boldsymbol{w}^{\dagger}(d\boldsymbol{\chi} - d(\sqrt{1 - |\boldsymbol{\chi}|^2})\boldsymbol{\chi} - \alpha(\boldsymbol{\chi}^{\dagger}d\boldsymbol{\chi})\boldsymbol{\chi})), \tag{63}$$

$$H = \boldsymbol{w}^{\dagger} \boldsymbol{w} + (N+1)^2 \boldsymbol{\chi}^{\dagger} \boldsymbol{\chi}, \tag{64}$$

or

$$\omega = \mathrm{i} d\boldsymbol{p}^{\dagger} \wedge d\chi + \mathrm{i} d\boldsymbol{\chi}^{\dagger} \wedge d\boldsymbol{p}, \tag{65}$$

$$H = \boldsymbol{p}^{\dagger} \boldsymbol{p} + \frac{(\boldsymbol{\chi}^{\dagger} \boldsymbol{p} + \boldsymbol{p}^{\dagger} \boldsymbol{\chi})^{2}}{4(1 - |\boldsymbol{\chi}|^{2})} + \frac{1}{4} (\boldsymbol{\chi}^{\dagger} \boldsymbol{p} - \boldsymbol{p}^{\dagger} \boldsymbol{\chi})^{2} + (N + 1)^{2} \boldsymbol{\chi}^{\dagger} \boldsymbol{\chi}.$$
(66)

As for the first order equations of motion, they read

$$i\dot{\boldsymbol{\chi}} = \boldsymbol{p} + \frac{\boldsymbol{\chi}^{\dagger}\boldsymbol{p} + \boldsymbol{p}^{\dagger}\boldsymbol{\chi}}{2(1 - |\boldsymbol{\chi}|^2)}\boldsymbol{\chi} - \frac{1}{2}(\boldsymbol{\chi}^{\dagger}\boldsymbol{p} - \boldsymbol{p}^{\dagger}\boldsymbol{\chi})\boldsymbol{\chi},$$
 (67)

$$i\dot{\boldsymbol{p}} = \frac{\boldsymbol{\chi}^{\dagger}\boldsymbol{p} + \boldsymbol{p}^{\dagger}\boldsymbol{\chi}}{2(1 - |\boldsymbol{\chi}|^{2})}\boldsymbol{p} + (N+1)^{2}\boldsymbol{\chi} + \frac{(\boldsymbol{\chi}^{\dagger}\boldsymbol{p} + \boldsymbol{p}^{\dagger}\boldsymbol{\chi})^{2}}{4(1 - |\boldsymbol{\chi}|^{2})^{2}}\boldsymbol{\chi} + \frac{1}{2}(\boldsymbol{\chi}^{\dagger}\boldsymbol{p} - \boldsymbol{p}^{\dagger}\boldsymbol{\chi})\boldsymbol{p}.$$
(68)

5.4 Symplectic reduction

It is more convenient and also more elegant to rewrite the first order data (63),(64) or (65),(66) in a global way, that is without restricting to the chart where Z_{N+1} does not vanish. We do it via a suitable symplectic reduction of a certain dynamical system $(\tilde{\omega}, \tilde{H})$ living on a complex symplectic manifold $\mathbb{C}^{N+1} \times \mathbb{C}^{N+1}$ parametrized by two (N+1)-vectors $\boldsymbol{Y}, \boldsymbol{Z}$,

$$oldsymbol{Z} = egin{pmatrix} Z_1 \ Z_2 \ dots \ Z_N \ Z_{N+1} \end{pmatrix}, \quad oldsymbol{Y} = egin{pmatrix} Y_1 \ Y_2 \ dots \ \ddots \ dots \ Y_N \ Y_{N+1} \end{pmatrix}.$$

The (non-reduced) symplectic form on $\mathbb{C}^{N+1} \times \mathbb{C}^{N+1}$ is given by

$$\tilde{\omega} = \frac{1}{2} (d\mathbf{Y}^{\dagger} \wedge d\mathbf{Z} - d\mathbf{Z}^{\dagger} \wedge d\mathbf{Y}) = d\Re(\mathbf{Y}^{\dagger} d\mathbf{Z}), \tag{69}$$

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where

$$oldsymbol{Z}^\dagger = egin{pmatrix} ar{Z}_1 & ar{Z}_2 & \dots & ar{Z}_N & ar{Z}_{N+1} \end{pmatrix}, \quad oldsymbol{Y}^\dagger = egin{pmatrix} ar{Y}_1 & ar{Y}_2 & \dots & ar{Y}_N & ar{Y}_{N+1} \end{pmatrix}$$

and the Hamiltonian is given by⁴:

$$\tilde{H}(\mathbf{Y}, \mathbf{Z}) = \frac{1}{4} |\mathbf{Z}|^2 |\mathbf{Y}|^2 - \frac{1}{4} |\mathbf{Z}^{\dagger} \mathbf{Y}|^2 + (N+1)^2 (1 - |Z_{N+1}|^2).$$
 (70)

Consider now a symplectic reduction of the dynamical system $(\tilde{\omega}, \tilde{H})$ induced by two Poisson-commuting constraints

$$\mathbf{Y}^{\dagger}\mathbf{Z} - \mathbf{Z}^{\dagger}\mathbf{Y} = 0, \quad \mathbf{Z}^{\dagger}\mathbf{Z} - 1 = 0, \tag{71}$$

which generate, via the Poisson brackets, two commuting flows

$$\phi_{\beta_1}(\boldsymbol{Y}, \boldsymbol{Z}) = (e^{i\beta_1} \boldsymbol{Y}, e^{i\beta_1} \boldsymbol{Z}), \quad \phi_{\beta_2}(\boldsymbol{Y}, \boldsymbol{Z}) = (\boldsymbol{Y} + \beta_2 \boldsymbol{Z}, \boldsymbol{Z}). \tag{72}$$

It turns out, that this symplectic reduction gives precisely the first order data (63),(64) of the point particle principal chiral model (56). Indeed, on the chart where Z_{N+1} does not vanish, we may completely slice the flows (72) on the constraints (71) by the following supplementary constraints

$$Z_{N+1} - \bar{Z}_{N+1} = 0, \quad \mathbf{Y}^{\dagger} \mathbf{Z} + \mathbf{Z}^{\dagger} \mathbf{Y} = 0.$$
 (73)

In order to describe the symplectic form $\tilde{\omega}$ restricted to the submanifold (71),(73), we first solve the constraints (71),(73) in terms of two N-vector variables $\boldsymbol{\xi}, \boldsymbol{\chi}$ such that $|\boldsymbol{\chi}| < 1$:

$$Y = -2i \begin{pmatrix} \xi \\ -\frac{\chi^{\dagger} \xi}{\sqrt{1-\chi^2}} \end{pmatrix}, \quad Z = \begin{pmatrix} \chi \\ \sqrt{1-\chi^2} \end{pmatrix},$$
 (74)

Set also⁵

$$\boldsymbol{w} := \sqrt{\mathbf{1}_N + \frac{\boldsymbol{\chi} \otimes \boldsymbol{\chi}^{\dagger}}{1 - |\boldsymbol{\chi}|^2}} \boldsymbol{\xi} = \boldsymbol{\xi} + \frac{\alpha}{\sqrt{1 - |\boldsymbol{\chi}|^2}} (\boldsymbol{\chi}^{\dagger} \boldsymbol{\xi}) \boldsymbol{\chi}. \tag{77}$$

⁵ Inversely, we have

$$\xi = \boldsymbol{w} - \alpha(\boldsymbol{\chi}^{\dagger} \boldsymbol{w}) \boldsymbol{\chi}, \tag{75}$$

and we have also

$$m{p} = m{\xi} + rac{m{\chi}^\dagger m{\xi} - m{\xi}^\dagger m{\chi}}{2(1 - |m{\chi}|^2)} m{\chi}, \quad m{\xi} = m{p} - rac{1}{2} (m{\chi}^\dagger m{p} - m{p}^\dagger m{\chi}) m{\chi},$$

$$\chi^{\dagger} \boldsymbol{p} - \boldsymbol{p}^{\dagger} \chi = \frac{\chi^{\dagger} \boldsymbol{w} - \boldsymbol{w}^{\dagger} \chi}{\sqrt{1 - |\chi|^2}} = \frac{\chi^{\dagger} \boldsymbol{\xi} - \boldsymbol{\xi}^{\dagger} \chi}{1 - |\chi|^2},$$
$$\chi^{\dagger} \boldsymbol{p} + \boldsymbol{p}^{\dagger} \chi = \sqrt{1 - |\chi|^2} (\chi^{\dagger} \boldsymbol{w} + \boldsymbol{w}^{\dagger} \chi) = \chi^{\dagger} \boldsymbol{\xi} + \boldsymbol{\xi}^{\dagger} \chi. \quad (76)$$

⁴A similar Hamiltonian, however without the potential term, was recently considered in [5] as a basis of (quantum) symplectic reduction leading to the standard mechanical \mathbb{CP}^N -model.

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With the notation (77), the symplectic form $\tilde{\omega}$ and the Hamiltonian \tilde{H} restricted to (71),(73) become, respectively, $\omega = -2d\Im(\boldsymbol{w}^{\dagger}(d\boldsymbol{\chi} - d(\sqrt{1-|\boldsymbol{\chi}|^2})\boldsymbol{\chi} - \alpha(\boldsymbol{\chi}^{\dagger}d\boldsymbol{\chi})\boldsymbol{\chi})),$ $H(\boldsymbol{w},\boldsymbol{\chi}) = \boldsymbol{w}^{\dagger}\boldsymbol{w} + (N+1)^2\boldsymbol{\chi}^{\dagger}\boldsymbol{\chi}.$

We wish also to rewrite the first order equations of motion (67),(68) in the global way, that is without restriction to the chart where $Z_{N+1} \neq 0$. To do that we first derive the equations of motion of the non-reduced dynamical system $(\tilde{\omega}, \tilde{H})$. We deduce from (69),(70) that the first order action of the non-reduced system $(\tilde{\omega}, \tilde{H})$ reads

We have thus recovered the principal chiral first order data (63),(64).

$$S(\boldsymbol{Y}, \boldsymbol{Z}) = \int dt (\Re(\boldsymbol{Y}^{\dagger} \dot{\boldsymbol{Z}}) - \tilde{H}(\boldsymbol{Y}, \boldsymbol{Z})). \tag{78}$$

By varying the action (78), we find

$$\dot{\boldsymbol{Z}} - \frac{1}{2}\boldsymbol{Y}|\boldsymbol{Z}|^2 + \frac{1}{2}(\boldsymbol{Z}^{\dagger}\boldsymbol{Y})\boldsymbol{Z} = 0, \tag{79}$$

$$\dot{\mathbf{Y}} + \frac{1}{2}|\mathbf{Y}|^2 \mathbf{Z} - \frac{1}{2}(\mathbf{Y}^{\dagger} \mathbf{Z})\mathbf{Y} - 2(N+1)^2 Z_{N+1} \mathbf{e}_{N+1} = 0.$$
 (80)

Remark 5.2 Alternatively, we can find the non-reduced equations of motion (79),(80) by calculating the Poisson brackets of \mathbf{Z}, \mathbf{Y} with \tilde{H} , knowing that the Poisson brackets induced by $\tilde{\omega}$ are

$$\{Z_j, \bar{Y}_k\} = \{\bar{Z}_j, Y_k\} = 2\delta_{jk}, \quad \{Z_j, \bar{Z}_k\} = \{Y_j, \bar{Y}_k\} = 0,$$
$$\{Z_j, Y_k\} = \{Z_j, Z_k\} = \{Y_j, Y_k\} = \{\bar{Z}_j, \bar{Y}_k\} = \{\bar{Z}_j, \bar{Z}_k\} = \{\bar{Y}_j, \bar{Y}_k\} = 0.$$

Remark 5.3 Because the constraints (71) Poisson-commute with the unreduced Hamiltonian \tilde{H} , we have also

$$\frac{d(\mathbf{Z}^{\dagger}\mathbf{Z} - 1)}{dt} = 0, \quad \frac{d(\mathbf{Z}^{\dagger}\mathbf{Y} - \mathbf{Y}^{\dagger}\mathbf{Z})}{dt} = 0.$$
 (81)

Of course, the validity of (81) can be established also as the direct consequence of (79), (80).

By the general principles of symplectic reduction, the reduced dynamics is nothing but the unreduced dynamics of flow-invariant observables on the constraint surface (71). Setting

$$\boldsymbol{K} := \boldsymbol{Y} - (\boldsymbol{Z}^{\dagger} \boldsymbol{Y}) \boldsymbol{Z}, \tag{82}$$

we observe that the variables Z, K are flow invariant with respect to the second flow ϕ_{β_2} but not with respect to the first one ϕ_{β_1} . However, the following matrix variables W, \mathcal{J} are flow invariant with respect to the both flows

$$\mathcal{W} := i(N+1)(\mathbf{Z} \otimes \mathbf{Z}^{\dagger} - \mathbf{e}_{N+1} \otimes \mathbf{e}_{N+1}^{\dagger}),$$

$$\mathcal{J} = \frac{1}{2} \mathbf{K} \otimes \mathbf{Z}^{\dagger} - \frac{1}{2} \mathbf{Z} \otimes \mathbf{K}^{\dagger}.$$
(83)

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Note that both \mathcal{W} and \mathcal{J} are traceless anti-Hermitian matrices.

From (79), (80), we find that on the constraint surface (71) it holds

$$\dot{\boldsymbol{Z}} = \frac{1}{2}\boldsymbol{K}, \quad \dot{\boldsymbol{K}} = -\frac{1}{2}|\boldsymbol{K}|^2\boldsymbol{Z} + 2(N+1)^2Z_{N+1}(\boldsymbol{e}_{N+1} - \bar{Z}_{N+1}\boldsymbol{Z}),$$

and hence

$$\dot{\mathcal{W}} = [\mathcal{J}, \mathcal{W} - \zeta], \quad \dot{\mathcal{J}} = [\zeta, \mathcal{W}], \tag{84}$$

where ζ is given by (50). The equations (84) are the reduced first order equations of motions written in the global way.

Remark 5.4 It is instructive to see how we can recover form (84) the first order equations of motions (67),(68) valid on the chart where $Z_{N+1} \neq 0$. For that, we use Eqs.(61),(74),(77),(82),(83) to express the components of the N-vector variables χ , p in terms of the matrix elements of the matrices \mathcal{J}, \mathcal{W} . For $\alpha = 1, \ldots, N$, we find

$$\chi_{\alpha} = \frac{-i\mathcal{W}_{\alpha,N+1}}{\sqrt{(N+1)(-i\mathcal{W}_{N+1,N+1} + N + 1)}},$$
(85)

$$p_{\alpha} = i \frac{(N+1)\mathcal{J}_{\alpha,N+1} - i[\mathcal{J}, \mathcal{W} - \zeta]_{\alpha,N+1}}{2\sqrt{(N+1)(-i\mathcal{W}_{N+1,N+1} + N + 1)}} + i \frac{\mathcal{W}_{\alpha,N+1}[\mathcal{J}, \mathcal{W} - \zeta]_{N+1,N+1}}{2\sqrt{N+1}(-i\mathcal{W}_{N+1,N+1} + N + 1)^{\frac{3}{2}}}.$$
(86)

We note, that the expressions on the r.h.s. of (85),(86) are well defined on the chart where $Z_{N+1} \neq 0$. Finally, we use (84) to calculate the time derivatives of (85),(86) which gives, after some work, precisely (67),(68).

Define now two λ -dependent matrices $L(\lambda), M(\lambda)$ as

$$L(\lambda) = \zeta - \frac{\lambda \mathcal{J} + \mathcal{W}}{1 - \lambda^2}, \quad M(\lambda) = -\frac{\mathcal{J} + \lambda \mathcal{W}}{1 - \lambda^2},$$
 (87)

where ζ is given by (50). Inserting the expressions (87) into the Lax equation $\dot{L}(\lambda) = [L(\lambda), M(\lambda)]$ gives

$$-\frac{\lambda \dot{\mathcal{J}} + \dot{\mathcal{W}}}{1 - \lambda^2} = \frac{-\lambda[\zeta, \mathcal{W}] + [\mathcal{W} - \zeta, \mathcal{J}]}{1 - \lambda^2}.$$
 (88)

The validity of the relation (88) for every λ is thus equivalent to the fulfillment of the following two conditions

$$\dot{\mathcal{W}} = [\mathcal{J}, \mathcal{W} - \zeta], \quad \dot{\mathcal{J}} = [\zeta, \mathcal{W}],$$

which are nothing but the reduced equations of motion (84). In this way, we have just established the Lax integrability of the point particle principal chiral model on \mathbb{CP}^N . It may seem that we have just pulled out the Lax pair (87) out of a hat but it is not the case. Actually, by the general construction presented in Section

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5.2 we know that the principal chiral model admits the Lax pair (45), but what is the relation between (45) and (87)? Well, it turns out that the Lax pair (45) is nothing but the Lax pair (87). This can be seen by inserting the formulas (52),(59) into (45) and using the formulas (74),(75). In particular, it holds

$$\mathcal{J} = -k\rho' k^{-1}, \quad \mathcal{W} = k' k^{-1}, \quad l' l^{-1} = (\mathcal{W}, -\mathcal{J}).$$

Lu-Weinstein Drinfeld double $SL(N+1,\mathbb{C})$ 6

Bi-Yang-Baxter deformation: the general case 6.1

In this section, we work out the point particle version of a particular two-parametric deformation of the principal chiral model which is called in the literature the bi-Yang-Baxter model or the Klimčík model [21, 22]. It is a particular case of the \mathcal{E} -model based on the Lu-Weinstein Drinfeld double D, where D is the special complex linear group $SL(N+1,\mathbb{C})$ viewed as real group (i.e. it has the dimension $2(N^2+2N)$ as the real manifold). The non-degenerate symmetric ad-invariant bilinear form $(.,.)_{\mathcal{D}}$ on the Lie algebra $sl(N+1,\mathbb{C})$ is defined by taking a suitable normalized imaginary part of the trace

$$(X,Y)_{\mathcal{D}} = \frac{-1}{\eta} \Im \operatorname{tr}(XY), \quad X,Y \in sl(N+1,\mathbb{C}), \quad \eta > 0.$$

The two half-dimensional isotropic subgroups K and \tilde{K} are respectively the special unitary group SU(N+1) and the upper-triangular group AN with real positive numbers on the diagonal the product of which is equal to 1.

We choose for ξ an element of the Cartan subalgebra of the isotropic subalgebra \mathcal{K} . The symplectic form then reads

$$\omega^{\xi} = -d(\xi, l^{-1}dl)_{\mathcal{D}} = \frac{1}{\eta} d\Im\operatorname{tr}\left(\xi l^{-1}dl\right)$$

The two-parametric family of the \mathcal{E} -operators, is given by [25]

$$\mathcal{E}_{\eta,\mu}X = \frac{i}{2} \frac{\eta^2 + \mu^2 R^2 - 1}{\eta} X - \frac{i}{2} \frac{\eta^2 - \mu^2 R^2 + 1}{\eta} X^{\dagger} - \mu R X^{\dagger}, \quad X \in sl(N+1,\mathbb{C}),$$
(89)

where $R: sl(N+1,\mathbb{C}) \to sl(N+1,\mathbb{C})$ is the Yang-Baxter operator defined on the Chevalley basis of $sl(N+1,\mathbb{C})$ as

$$RE^{\alpha} = -\operatorname{sign}(\alpha)iE^{\alpha}, \quad RH^{j} = 0.$$
 (90)

The Hamiltonian of the point particle bi-Yang-Baxter model then reads

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$H_{\eta,\mu}^{\xi} = \frac{1}{2} (l'l^{-1}, \mathcal{E}_{\eta,\mu} l'l^{-1})_{\mathcal{D}} = \frac{\mu}{2n} \operatorname{Str} (l'l^{-1}R(l'l^{-1})^{\dagger}) +$ $+\frac{1}{4}\operatorname{tr}\left(l'l^{-1}(\eta^{-2}-\mu^2\eta^{-2}R^2+1)(l'l^{-1})^{\dagger}\right)+$ $+\frac{1}{4}\Re \operatorname{tr}\left(l'l^{-1}(\eta^{-2}-\mu^2\eta^{-2}R^2-1)(l'l^{-1})\right).$ (91)

We may parametrize $l \in D$ in the Iwasawa way as

$$l = gb = gan, \quad g \in SU(N+1), \ b = an \in AN, \quad a \in A, \ n \in N.$$
 (92)

We have denoted by A the subgroup of the diagonal matrices of AN and by N the subgroup of the matrices in AN having just units on the diagonal.

In a dense open subset of SU(N+1), we can parametrize g as

$$g = kk_{\xi},$$

where k_{ξ} belong to the stabilizer K_{ξ} . In this parametrization, the symplectic form ω^{ξ} becomes

$$\omega^{\xi} = -d(\xi, l^{-1}dl)_{\mathcal{D}} = -d(b\xi b^{-1}, k_{\xi}^{-1}k^{-1}dkk_{\xi} + k_{\xi}^{-1}dk_{\xi})_{\mathcal{D}} - d(\xi, n^{-1}a^{-1}dan + n^{-1}dn)_{\mathcal{D}} =$$

$$= -d(k_{\xi}b\xi b^{-1}k_{\xi}^{-1}, k^{-1}dk)_{\mathcal{D}} - d(\xi, n^{-1}a^{-1}dan)_{\mathcal{D}} = -d(k_{\xi}b\xi b^{-1}k_{\xi}^{-1} - \xi, k^{-1}dk)_{\mathcal{D}}.$$
(93)

We find in the block form

$$k_{\xi}b\xi b^{-1}k_{\xi}^{-1} - \xi = -\eta(R - i)[\xi, \rho],$$

where $\rho \in \mathcal{K}$ and R is the Yang-Baxter operator.

As far as the Hamiltonian is concerned, we first use the Iwasawa decomposition (92) to find

$$l'l^{-1} = k'k^{-1} + \eta(R_{k^{-1}} - i)(k\rho'k^{-1}),$$

where

$$R_{k^{-1}} := \mathrm{Ad}_k R \mathrm{Ad}_{k^{-1}}.$$

Then we use (91) to find

$$H_{\eta,\mu}^{\xi} = -\frac{1}{2} \operatorname{tr} \left((\rho')^2 + (k^{-1}k' + (\eta R + \mu R_k)\rho')^2 \right). \tag{94}$$

The first order action corresponding to the data (93), (94) is therefore

$$S_{\eta,\mu}(k,\rho') = \int dt \operatorname{tr}\left(\rho' k^{-1} \dot{k} + \frac{1}{2} (\rho')^2 + \frac{1}{2} (k^{-1} k' + (\eta R + \mu R_k) \rho')^2\right). \tag{95}$$

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Note that the variable ρ' takes values⁶ in K_{ξ}^{\perp} . It is sometimes convenient to use a variable $\chi \in \mathcal{K}$ instead of \mathcal{K}_{ξ} and a Lagrange multiplier $A \in \mathcal{K}_{\xi}$ forcing χ to become $\rho' \in \mathcal{K}_{\varepsilon}^{\perp}$. Explicitely,

$$S_{\eta,\mu}(k,\chi,A) = \int dt \operatorname{tr}\left(\chi(k^{-1}\dot{k} - A) + \frac{1}{2}\chi^2 + \frac{1}{2}(k^{-1}k' + (\eta R + \mu R_k)\chi)^2\right). \tag{96}$$

We can then easily eliminate the field χ , which gives

$$S_{\eta,\mu}(k,A) = -\frac{1}{2} \int dt \operatorname{tr} \left((k^{-1}\dot{k} - A + k^{-1}k') \frac{1}{1 - \eta R - \mu R_k} (k^{-1}\dot{k} - A - k^{-1}k') \right),$$

or, equivalently,

$$S_{\eta,\mu}(k,A) = \frac{1}{2} \int dt \operatorname{tr} \left((k^{-1}k')^2 - (V(k) - A) \frac{1}{1 - (\eta R + \mu R_k)^2} (V(k) - A) \right), \tag{97}$$

where

$$V(k) := k^{-1}\dot{k} - (\eta R + \mu R_k)k^{-1}k'.$$

Varying the actions (95) and (97) respectively with respect to ρ' and A gives

$$\rho'(k) = -\frac{1}{1_{\perp} - P^{\perp}(\eta R + \mu R_k)^2 P^{\perp}} P^{\perp}(k^{-1}\dot{k} - (\eta R + \mu R_k)k^{-1}k'), \qquad (98)$$

$$A(k) = PV(k) + P(\eta R + \mu R_k)^2 P^{\perp} \frac{1}{1_{\perp} - P^{\perp}(\eta R + \mu R_k)^2 P^{\perp}} P^{\perp} V(k), \qquad (99)$$

where P and P^{\perp} are orthogonal projectors on K_{ξ} and K_{ξ}^{\perp} , respectively.

Inserting (98) back into the action (95) or (99) back in (97) gives rise to the second order action

$$S_{\eta,\mu}(k) = \frac{1}{2} \int dt \, \text{tr} \, (k^{-1}k')^2 + \frac{1}{2} \int dt \, \text{tr} \, \left(-P^{\perp}V(k) \frac{1}{1_{\perp} - P^{\perp}(\eta R + \mu R_k)^2 P^{\perp}} P^{\perp}V(k) \right). \tag{100}$$

By construction, the action (100) lives on the flag⁷ manifold K/K_{ξ} . This can be verified directly by checking its gauge invariance with respect to the gauge

 $^{^6 \}mathrm{Note}$ also that the Yang-Baxter operator R restricted to the subspace $K_{\mathcal{E}}^{\perp}$ has a trivial kernel, which means that it behaves as a complex structure similarly as in the infinite dimensional context

⁷r-matrix-deformations of flag manifold σ -models were studied in [4]. The standard dimensional reduction of the models [4] gives mechanical models which differ from ours because they miss potential terms and only the metric is deformed. As we have already stated in the Introduction, this is consistent because what we do here is not quite the dimensional reduction. Indeed, we do not let the space derivative terms vanish but we rather replace them with the commutators with ξ which yields indeed the potential terms. The reason of being of our procedure resides in the fact that we obtain in this way the mechanical Lax pairs from the field-theoretical ones automatically. Whether Lax pairs (if they exist) of the standardly dimensionally reduced models [4] could be also obtained in one or in other way from the field theoretical ones is not clear to us.

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transformation $k \to kh$, $h \in K_{\xi}$. First of all we find

$$V(kh) = \mathrm{Ad}_{h^{-1}}(V(k) - \eta \Pi_h k^{-1} k') + h^{-1} \dot{h},$$

$$P^{\perp}(\eta R + \mu R_{kh})^{2} P^{\perp} = P^{\perp}(\eta R + \mu \text{Ad}_{h^{-1}} R_{k} \text{Ad}_{h})^{2} P^{\perp} =$$

$$= P^{\perp} \text{Ad}_{h^{-1}} (\eta R + \mu R_{k} + \eta \Pi_{h})^{2} \text{Ad}_{h} P^{\perp}, \quad (101)$$

where

$$\Pi_h := (R_{h^{-1}} - R).$$

Because of the relations

$$[R, P^{\perp}] = 0, \quad [Ad_h, P^{\perp}] = 0, \quad [R, Ad_h P^{\perp}] = 0,$$

we infer that the image of the operator Π_h is in \mathcal{K}_{ξ} , while K_{ξ}^{\perp} is in the kernel of Π_h . This implies

$$P^{\perp}V(kh) = \mathrm{Ad}_{h^{-1}}(P^{\perp}V(k)),$$
 (102)

$$P^{\perp}(\eta R + \mu R_{kh})^{2} P^{\perp} = \operatorname{Ad}_{h^{-1}} P^{\perp}(\eta R + \mu R_{k} + \eta \Pi_{h})^{2} P^{\perp} \operatorname{Ad}_{h} =$$

$$= \operatorname{Ad}_{h^{-1}} P^{\perp}(\eta R + \mu R_{k})^{2} P^{\perp} \operatorname{Ad}_{h}. \quad (103)$$

The relations (102), (103) then imply the gauge invariance of the action (100).

6.2 Integrability

Let us show that the point particle bi-Yang-Baxter model is integrable for whatever choice of ξ . For that we take the Lie algebra \mathcal{G} to be just \mathcal{K} equipped with its standard Killing-Cartan form $(.,.)_{\mathcal{G}} = (.,.)_{\mathcal{K}}$ and, by the very logic of this article, we borrow the required operators $O(\lambda)$, $\hat{r}(\lambda,\rho)$ from the stringy bi-Yang-Baxter context. They are given by [28]

$$O(\lambda)j = f_0(\lambda)\frac{j - j^{\dagger}}{2} + (f_1(\lambda) + \mu(1 - f_0(\lambda))R)\frac{j + j^{\dagger}}{2i\eta},$$
 (104)

$$O(\lambda)^{\dagger}W = (-\eta i f_0(\lambda) - f_1(\lambda) + \mu(1 - f_0(\lambda))R)W,$$

$$\hat{r}_{bi-YB}(\lambda, \rho) = (1 - f_0(\rho)) \left(\frac{f_0(\lambda)f_1(\rho) + f_1(\lambda)f_0(\rho)}{f_0(\lambda) - f_0(\rho)} Id - \mu R\right), \tag{105}$$

where

$$f_0(\lambda) = \frac{1 + \eta^2 - \mu^2}{2} + \frac{\sqrt{(1 + \eta^2 - \mu^2)^2 + 4\mu^2}}{2} \cosh \lambda,$$
$$f_1(\lambda) = \frac{\sqrt{(1 + \eta^2 - \mu^2)^2 + 4\mu^2}}{2} \sinh \lambda.$$

We know that $O(\lambda)$, $\hat{r}(\lambda, \rho)$ given by (104), (105) satisfy the stringy conditions (23), (25), (26) automatically. We must then check that the purely point particle

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conditions (22), (24) are also satisfied. This follows from the fact that the Yang-Baxter operator R commutes with ad_{ξ} , as can be checked from (90) and from the relation

$$\operatorname{ad}_{\xi} E^{\alpha} = \alpha(\xi) E^{\alpha}, \quad \operatorname{ad}_{\xi} H^{j} = 0.$$

We conclude, by the general construction of Section 4, that the Lax pair of the point particle bi-Yang-Baxter model is therefore given by (27), (28)

$$L(\lambda) = \xi - O(\lambda)j, \quad M(\lambda) = -O(\lambda)\mathcal{E}j.$$

6.3 Bi-Yang-Baxter deformation: particular cases

Let us evaluate the second order action (100) for the group K = SU(2). In this case, the Yang-Baxter operators R, R_k can be written as

$$R = -\frac{1}{2} \operatorname{ad}_{\xi}, \quad R_k = R - \frac{1}{2} \operatorname{ad}_{k^{-1}k'}.$$

Using the parametrization

$$k = \begin{pmatrix} u & -\bar{v} \\ v & \bar{u} \end{pmatrix}, \quad u\bar{u} + v\bar{v} = 1,$$

we find

$$P^{\perp}V(k) = \begin{pmatrix} 0 & \bar{v}d\bar{u} - \bar{u}d\bar{v} + 2(\eta + \mu)\bar{u}\bar{v} \\ udv - vdu - 2(\eta + \mu)uv & 0 \end{pmatrix}.$$

Setting

$$x_1 - ix_2 = 2u\bar{v}, \quad x_3 = u\bar{u} - v\bar{v},$$

we obtain

$$(1_{\perp} - P^{\perp}(\eta R + \mu R_k)^2 P^{\perp})^{-1} i \begin{pmatrix} 0 & y_1 - iy_2 \\ y_1 + iy_2 & 0 \end{pmatrix} =$$

$$= i(1 + \eta^{2} + \mu^{2} + 2\mu\eta x_{3})^{-1} \times \times \left(\begin{pmatrix} 0 & y_{1} - iy_{2} \\ y_{1} + iy_{2} & 0 \end{pmatrix} + \frac{4\mu^{2}\Re(uv(y_{1} - iy_{2}))}{1 + (\eta + \mu x_{3})^{2}} \begin{pmatrix} 0 & \bar{u}\bar{v} \\ uv & 0 \end{pmatrix} \right)$$
(106)

The action (100) thus becomes

$$S_{\eta,\mu} = \frac{1}{4} \int dt \left(\frac{\dot{x}_1^2 + \dot{x}_2^2 + \dot{x}_3^2 + \frac{\mu^2 (x_1 \dot{x}_2 - x_2 \dot{x}_1)^2}{1 + (\eta + \mu x_3)^2}}{1 + \eta^2 + \mu^2 + 2\mu \eta x_3} \right) + \int dt (x_3 - 1) \frac{2 - (\eta - \mu)^2 (x_3 - 1)}{1 + \eta^2 + \mu^2 + 2\mu \eta x_3}. \quad (107)$$

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Working in the standard spherical coordinates

$$x_1 = \sin \theta \cos \phi$$
, $x_2 = \sin \theta \sin \phi$, $x_3 = \cos \theta$,

the action (107) becomes

$$S_{\eta,\mu} = \frac{1}{4} \int dt \frac{\dot{\theta}^2}{1 + \eta^2 + \mu^2 + 2\mu\eta\cos\theta} + \frac{1}{4} \int dt \frac{\sin^2\theta\dot{\phi}^2}{1 + \eta^2 + \mu^2\cos^2\theta + 2\mu\eta\cos\theta} + \int dt(\cos\theta - 1) \frac{2 - (\eta - \mu)^2(\cos\theta - 1)}{1 + \eta^2 + \mu^2 + 2\mu\eta\cos\theta}.$$
(108)

For $\mu = 0$, we have

$$S_{\eta} = \frac{1}{4} \int dt \left(\frac{\dot{x}_{1}^{2} + \dot{x}_{2}^{2} + \dot{x}_{3}^{2}}{1 + \eta^{2}} + 4(x_{3} - 1) \frac{2 - \eta^{2}(x_{3} - 1)}{1 + \eta^{2}} \right)$$

$$S_{\eta} = \frac{1}{4} \int dt \left(\frac{\dot{\theta}^{2} + \sin^{2}\theta \dot{\phi}^{2}}{1 + \eta^{2}} + 4(\cos\theta - 1) \frac{2 - \eta^{2}(\cos\theta - 1)}{1 + \eta^{2}} \right).$$

We note that, up to a renormalization by a constant, the Fubini-Study metric does not change in the case $\mu=0$ and only the potential term gets substantially deformed.

Consider now the case K = SU(3) and

$$\xi = i \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix}.$$

We give the details of the computation in Appendix, here we write just the result in the following dense parametrization [6] of the homogeneous space $K/K_{\xi} = \mathbb{CP}^2$

$$k = \begin{pmatrix} a & -\bar{b} & 0 \\ b & \bar{a} & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos \theta & 0 & \sin \theta \\ 0 & 1 & 0 \\ -\sin \theta & 0 & \cos \theta \end{pmatrix}, \quad a\bar{a} + b\bar{b} = 1.$$

The bi-YB action (100) then is

$$S_{\eta,\mu}(k) = \int dt \ \Delta_2 \left(\frac{\beta}{|a|^2 |b|^2} W_5^2 + \epsilon_2 W_6^2 + 2q W_5 W_6 \right) +$$

$$+ \int dt \ \Delta_1 \left(\left(\frac{\beta}{|a|^2 |b|^2} + \delta \right) W_4^2 + \epsilon_1 W_7^2 + 2p W_4 W_7 \right) - 9 \int dt \sin^2 \theta, \tag{109}$$

where

$$W_4 = \sin\theta\cos\theta \Im(\bar{a}\dot{a} + \bar{b}\dot{b}), \quad W_5 = \dot{\theta} - 3\sin\theta\cos\theta(\eta + \mu),$$

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Similarly as in the SU(2) case, the second order action (109) describes a dynamical system living on the complex projective space equipped with the doubly deformed Fubini-Study metric and with a nontrivial potential. Needless to say, the action (109) is somewhat cumbersome, however, it is quite remarkable that it is underlied by the simple and transparent first order Hamiltonian structure given by the point particle \mathcal{E} -model.

Finally, we work out the case $K=SU(N), \ \mu=0$ for ξ given by the block matrix

$$\xi = i \begin{pmatrix} \mathbf{1}_N & 0 \\ 0 & -N \end{pmatrix}.$$

For that, we parametrize \mathbb{CP}^N like in (52)

$$k = \begin{pmatrix} \mathbf{1}_N - \alpha \boldsymbol{\chi} \otimes \boldsymbol{\chi}^{\dagger} & \boldsymbol{\chi} \\ -\boldsymbol{\chi}^{\dagger} & \sqrt{1 - |\boldsymbol{\chi}|^2} \end{pmatrix}, \ \alpha = \frac{1 - \sqrt{1 - |\boldsymbol{\chi}|^2}}{|\boldsymbol{\chi}|^2}, \ \boldsymbol{\chi} \neq \mathbf{0},$$

which gives, in particular

$$k^{-1}k' = (N+1)\mathrm{i} \begin{pmatrix} -\boldsymbol{\chi} \otimes \boldsymbol{\chi}^{\dagger} & \sqrt{1-|\boldsymbol{\chi}|^2}\boldsymbol{\chi} \\ \sqrt{1-|\boldsymbol{\chi}|^2}\boldsymbol{\chi}^{\dagger} & |\boldsymbol{\chi}|^2 \end{pmatrix},$$

$$P^{\perp}k^{-1}\dot{k} = \begin{pmatrix} \mathbf{0} & \dot{\boldsymbol{\chi}} - \sqrt{1 - |\boldsymbol{\chi}|^2}\boldsymbol{\chi} - \alpha(\boldsymbol{\chi}^{\dagger}\dot{\boldsymbol{\chi}})\boldsymbol{\chi} \\ -\dot{\boldsymbol{\chi}}^{\dagger} + \sqrt{1 - |\boldsymbol{\chi}|^2}\boldsymbol{\chi}^{\dagger} + \alpha(\dot{\boldsymbol{\chi}}^{\dagger}\boldsymbol{\chi})\boldsymbol{\chi}^{\dagger} & 0 \end{pmatrix}$$
$$(k^{-1}k', k^{-1}k')_{\mathcal{K}} = -2(N+1)^2|\boldsymbol{\chi}|^2.$$

The point particle Yang-Baxter model action (100) for $\mu = 0$ therefore becomes

$$S_{\eta}(\boldsymbol{\chi}) = \frac{1}{2} \int dt \left(-(1+\eta^{2})^{-1} \left(P^{\perp} (k^{-1}\dot{k} - \eta Rk^{-1}k') \right)^{2} + (k^{-1}k')^{2} \right) =$$

$$= \int dt \left(\frac{\left| \dot{\boldsymbol{\chi}} - \sqrt{1-|\boldsymbol{\chi}|^{2}} \boldsymbol{\chi} - \alpha(\boldsymbol{\chi}^{\dagger} \dot{\boldsymbol{\chi}}) \boldsymbol{\chi} - \eta(N+1) \sqrt{1-|\boldsymbol{\chi}|^{2}} \boldsymbol{\chi} \right|^{2}}{1+\eta^{2}} - (N+1)^{2} |\boldsymbol{\chi}|^{2} \right). \tag{110}$$

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Using the homogeneous coordinates (cf. (57)), we obtain a more elegant global expression for the Yang-Baxter second order action (110)

$$S_{\eta}(\mathbf{Z}) = \int dt \left(\frac{|\dot{\mathbf{Z}}|^2 - |\mathbf{Z}^{\dagger}\dot{\mathbf{Z}}|^2}{1 + \eta^2} + \frac{(N+1)^2}{1 + \eta^2} \left((2\eta^2 + 1)|Z_{N+1}|^2 - \eta^2 |Z_{N+1}|^4 \right) + \Lambda(|\mathbf{Z}|^2 - 1) \right).$$

7 Conclusions and perspectives

In the present article, we have introduced the point particle \mathcal{E} -models, which are the first order Hamiltonian dynamical systems associated to a Drinfeld double D, to an element ξ of the quadratic Lie algebra \mathcal{D} of D and to a symmetric involution $\mathcal{E}: \mathcal{D} \to \mathcal{D}$. Comparing with the infinite dimensional stringy \mathcal{E} -models, based solely on the data (D, \mathcal{E}) , the point particle models are finite dimensional; the dimensions of their phase spaces D/D_{ξ} depend on the dimension of D and of the stabilizer subgroup D_{ξ} .

Similarly as in the string case, we have shown that many of the point particle \mathcal{E} -models are integrable and we have also identified the sufficient conditions which ensure the integrability. Those conditions (3), (4), (5) are in fact the same in the point particle and in the string case, which means that it is easy to construct many new integrable point particle models by borrowing from the string literature the known solutions of (3), (4), (5). The only thing to check is whether the chosen $\xi \in \mathcal{D}$ verifies the supplementary purely point particle condition (6). Fortunately, the condition (6) turns out to be only mildly restrictive, in particular, for the Drinfeld doubles $T^*SU(N)$ and $SL(N,\mathbb{C})$ many choices of ξ satisfy it, leading to the physical systems living on the complex flag manifolds.

As for the perspectives, the obvious task would be to generalize the point particle \mathcal{E} -models along the lines of the string generalization leading from the standard (or non-degenerate) \mathcal{E} -models to the degenerate ones [20, 27]. If this point particle generalization can be found, the next question to ask would be what are the sufficient condition of its integrability. The fact that those sufficient conditions are already known in the degenerate string case [30] should be helpful.

Another open issue is a quantization of the point particle \mathcal{E} -models, in particular of the integrable ones. This does not look a priori difficult, because, similarly as in the stringy case, the basic observables of the point particle \mathcal{E} -models are the \mathcal{D} -valued currents j verifying the finite dimensional version of the Poisson current algebra (20). Since the Poisson brackets (20) seem easy to quantize, this should lead to the complete quantization of the model provided we know well the theory of representations of the given Drinfeld double D.

A successful quantization of the integrable point particle \mathcal{E} -models could bring about also an additional benefit, namely, it could shed light on the difficult problem of the quantization of the so-called non-ultralocal theories [37, 38, 31, 32] among which typically belong the integrable non-linear σ -models. In the non-ultra-local case, the Lax matrix elements at different values of the loop parameter do not

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commute. There is no loop parameter in the finite dimensional case, so that the ultra-local problem cannot arise there, but the algebraic similarity of the finite and of the infinite, notably almost the same structure of the Lax operator and of the r-matrix, might provide some clues how to quantize in the infinite case once the finite case quantization is accomplished.

In the infinite-dimensional case, the \mathcal{E} -models are submitted to the renormalization group flow, that is a given \mathcal{E} -model flows in the into another one and the direction and the rapidity of the flow is given by the initial value of the operator \mathcal{E} . In particular, there are algebraically distinguished "fixed point" or "conformal" operators \mathcal{E} which do not flow at all. The detailed classification of those fixed points was recently performed in [35] in the both non-degenerate and degenerate cases. It could be interesting to work out the proporties of the conformal \mathcal{E} -models in the point particle case.

Appendix

Here we work out in detail the bi-YB action (100) for the case K = SU(3) and $\xi = i \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix}$. The action lives on the homogeneous space $K/K_{\xi} = \mathbb{CP}^2$ which we densely parametrize as in [6]

$$k = \begin{pmatrix} a & -\bar{b} & 0 \\ b & \bar{a} & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos \theta & 0 & \sin \theta \\ 0 & 1 & 0 \\ -\sin \theta & 0 & \cos \theta \end{pmatrix}, \quad a\bar{a} + b\bar{b} = 1.$$

We then find

$$\begin{split} k^{-1}k' &= 3\mathrm{i} \sin \theta \begin{pmatrix} -\sin \theta & 0 & \cos \theta \\ 0 & 0 & 0 \\ \cos \theta & 0 & \sin \theta \end{pmatrix}, \quad Rk^{-1}k' &= 3\sin \theta \begin{pmatrix} 0 & 0 & \cos \theta \\ 0 & 0 & 0 \\ -\cos \theta & 0 & 0 \end{pmatrix} \\ k'k^{-1} &= 3\mathrm{i} \sin \theta \begin{pmatrix} a\bar{a}\sin \theta & a\bar{b}\sin \theta & a\cos \theta \\ b\bar{a}\sin \theta & b\bar{b}\sin \theta & b\cos \theta \\ \bar{a}\cos \theta & \bar{b}\cos \theta & -\sin \theta \end{pmatrix}, Rk'k^{-1} &= 3\sin \theta \begin{pmatrix} 0 & a\bar{b}\sin \theta & a\cos \theta \\ -b\bar{a}\sin \theta & 0 & b\cos \theta \\ -\bar{a}\cos \theta & -\bar{b}\cos \theta & 0 \end{pmatrix}, \\ R_kk^{-1}k' &= -3\sin \theta \begin{pmatrix} 0 & -\bar{a}\bar{b}\sin \theta\cos \theta & -\cos \theta \\ \sin \theta\cos \theta ab & 0 & ab\sin^2 \theta \\ \cos \theta & -\sin^2 \theta \bar{a}\bar{b} & 0 \end{pmatrix}, \\ P^{\perp}V(k) &= P^{\perp}(k^{-1}\dot{k} - (\eta R + \mu R_k)k^{-1}k') = \begin{pmatrix} 0 & 0 & \dot{\theta} \\ 0 & 0 & 0 \\ -\dot{\theta} & 0 & 0 \end{pmatrix} + \\ +\sin \theta \begin{pmatrix} 0 & 0 & \cos \theta(\bar{a}\dot{a} + \bar{b}\dot{b} - 3(\eta + \mu)) \\ 0 & 0 & (a\dot{b} - \dot{a}b - 3\mu ab\sin^2 \theta) \\ \cos \theta(\bar{a}\dot{a} + \bar{b}\dot{b} + 3(\eta + \mu)) & (\dot{a}\bar{b} - \bar{a}\dot{b} + 3\mu \bar{a}\bar{b}\sin^2 \theta) \end{pmatrix}, \end{split}$$

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$k^{-1}\dot{k} = \begin{pmatrix} \cos^2\theta(\bar{a}\dot{a} + \bar{b}\dot{b}) & \cos\theta(\dot{\bar{a}}\bar{b} - \bar{a}\dot{\bar{b}}) & \sin\theta\cos\theta(\bar{a}\dot{a} + \bar{b}\dot{b}) + \dot{\theta} \\ \cos\theta(a\dot{b} - \dot{a}b) & -(\bar{a}\dot{a} + \bar{b}\dot{b}) & \sin\theta(a\dot{b} - \dot{a}b) \\ \sin\theta\cos\theta(\bar{a}\dot{a} + \bar{b}\dot{b}) - \dot{\theta} & \sin\theta(\dot{\bar{a}}\bar{b} - \bar{a}\dot{\bar{b}}) & \sin^2\theta(\bar{a}\dot{a} + \bar{b}\dot{b}) \end{pmatrix}.$

Now an element χ of the su(3) is encoded in a vector column (x_i) , $i = 1, \ldots 8$, such that

$$\chi = i \begin{pmatrix} x_3 + y & x_1 - ix_2 & x_4 - ix_5 \\ x_1 + ix_2 & -x_3 + y & x_6 - ix_7 \\ x_4 + ix_5 & x_6 + ix_7 & -2y \end{pmatrix}.$$

We have in this basis

Set

$$a = a_1 + ia_2$$
, $b = b_1 + ib_2$, $c = \cos \theta$, $s = \sin \theta$.

Then

$$\mathrm{Ad}_k = \begin{pmatrix} 2a_1^2 + 2b_2^2 - 1 & 2(a_1a_2 - b_1b_2) & 2(a_1b_1 + a_2b_2) & 0 & 0 & 0 & 0 & 0 \\ -2(a_1a_2 + b_1b_2) & 2a_1^2 + 2b_1^2 - 1 & 2(a_1b_2 - a_2b_1) & 0 & 0 & 0 & 0 & 0 \\ 2(a_2b_2 - a_1b_1) & -2(a_1b_2 + a_2b_1) & 2a_1^2 + 2a_2^2 - 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & a_1 & a_2 & -b_1 & b_2 & 0 \\ 0 & 0 & 0 & 0 & -a_2 & a_1 & -b_2 & -b_1 & 0 \\ 0 & 0 & 0 & 0 & b_1 & b_2 & a_1 & -a_2 & 0 \\ 0 & 0 & 0 & 0 & -b_2 & b_1 & a_2 & a_1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix} \times$$

$$\times \begin{pmatrix} c & 0 & 0 & 0 & 0 & s & 0 & 0 \\ 0 & c & 0 & 0 & 0 & 0 & -s & 0 \\ 0 & 0 & 1 - \frac{s^2}{2} & sc & 0 & 0 & 0 & -\frac{3s^2}{2} \\ 0 & 0 & -sc & 1 - 2s^2 & 0 & 0 & 0 & -3sc \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ -s & 0 & 0 & 0 & 0 & c & 0 & 0 \\ 0 & s & 0 & 0 & 0 & 0 & c & 0 \\ 0 & 0 & -\frac{s^2}{2} & sc & 0 & 0 & 0 & 1 - \frac{3s^2}{2} \end{pmatrix}$$

Set

$$\sigma = \Im(ab) = a_1b_2 + a_2b_1, \ \tau = -\Re(ab) = -a_1b_1 + a_2b_2, \quad \sigma^2 + \tau^2 = |a|^2|b|^2.$$

Then

$$R_k = \begin{pmatrix} 0 & 1 - 2c^2 a \bar{a} & -c(c^2 + 1)\sigma & -2c^2 s\sigma & 0 & 0 & 2csa\bar{a} & 3cs^2\sigma \\ 2c^2 a \bar{a} - 1 & 0 & -c(c^2 + 1)\tau & -2c^2 s\tau & 0 & 2csa\bar{a} & 0 & 3cs^2\tau \\ c(c^2 + 1)\sigma & c(c^2 + 1)\tau & 0 & 0 & cs & s(c^2 + 1)\sigma & -s(c^2 + 1)\tau & 0 \\ 2c^2 s\sigma & 2c^2 s\tau & 0 & 0 & s^2 - c^2 & 2cs^2\sigma & -2cs^2\tau & 0 \\ 0 & 0 & -cs & c^2 - s^2 & 0 & 0 & 0 & -3cs \\ 0 & -2csa\bar{a} & -s(c^2 + 1)\sigma & -2cs^2\sigma & 0 & 0 & -1 + 2s^2a\bar{a} & 3s^3\sigma \\ -2csa\bar{a} & 0 & s(c^2 + 1)\tau & 2cs^2\tau & 0 & 1 - 2s^2a\bar{a} & 0 & -3s^3\tau \\ -cs^2\sigma & -cs^2\tau & 0 & 0 & cs & -s^3\sigma & s^3\tau & 0 \end{pmatrix}$$

Set

$$\gamma = \cos 2\theta, \quad \xi = \sin 2\theta$$

Then we find

$$1^{\perp} - P^{\perp}(\eta R + \mu R_k)^2 P^{\perp} = \begin{pmatrix} \epsilon_1 & 0 & p\tau & p\sigma \\ 0 & \epsilon_2 & -q\sigma & q\tau \\ p\tau & -q\sigma & \beta + \delta\tau^2 & \delta\tau\sigma \\ p\sigma & q\tau & \delta\tau\sigma & \beta + \delta\sigma^2 \end{pmatrix} =$$

$$= \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \sigma & \tau \\ 0 & 0 & -\tau & \sigma \end{pmatrix} \begin{pmatrix} \epsilon_1 & 0 & 0 & p \\ 0 & \epsilon_2 & -q & 0 \\ 0 & -q & \frac{\beta}{\tau^2 + \sigma^2} & 0 \\ p & 0 & 0 & \frac{\beta}{\tau^2 + \sigma^2} + \delta \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \sigma & -\tau \\ 0 & 0 & \tau & \sigma \end{pmatrix}$$

where

$$\epsilon_1 = 1 + (\eta + \mu \gamma)^2 + \mu^2 \xi^2 (\tau^2 + \sigma^2), \quad \epsilon_2 = 1 + \eta^2 + \mu^2 + 2\eta \mu \gamma,$$

$$p = \mu \xi s(\eta - \mu(|a|^2 - |b|^2)), \quad q = \eta \mu \xi s, \quad \beta = 1 + (\eta + \mu)^2 - 4\eta \mu s^2 |a|^2, \quad \delta = -4\mu^2 s^2.$$

For the inverse matrix we find

$$(1^{\perp} - P^{\perp}(\eta R + \mu R_k)^2 P^{\perp})^{-1} =$$

$$= \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \frac{\sigma}{\sigma^2 + \tau^2} & \frac{\tau}{\sigma^2 + \tau^2} \\ 0 & 0 & -\frac{\tau}{\sigma^2 + \tau^2} & \frac{\sigma}{\sigma^2 + \tau^2} \end{pmatrix} \begin{pmatrix} \Delta_1(\frac{\beta}{\sigma^2 + \tau^2} + \delta) & 0 & 0 & \Delta_1 p \\ 0 & \frac{\Delta_2 \beta}{\sigma^2 + \tau^2} & \Delta_2 q & 0 \\ 0 & \Delta_2 q & \Delta_2 \epsilon_2 & 0 \\ \Delta_1 p & 0 & 0 & \Delta_1 \epsilon_1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \frac{\sigma}{\sigma^2 + \tau^2} & -\frac{\tau}{\sigma^2 + \tau^2} \\ 0 & 0 & \frac{\tau}{\sigma^2 + \tau^2} & \frac{\sigma}{\sigma^2 + \tau^2} \end{pmatrix}$$

where

$$\Delta_1 = \frac{\sigma^2 + \tau^2}{\epsilon_1 \beta + (\epsilon_1 \delta - p^2)(\sigma^2 + \tau^2)}, \quad \Delta_2 = \frac{\sigma^2 + \tau^2}{\epsilon_2 \beta - q^2(\sigma^2 + \tau^2)}.$$

We have

$$P^{\perp}V(k) = \begin{pmatrix} V_4(k) \\ V_5(k) \\ V_6(k) \\ V_7(k) \end{pmatrix} = \begin{pmatrix} sc \Im(\bar{a}\dot{a} + \bar{b}\dot{b}) \\ \dot{\theta} + sc \Re(\bar{a}\dot{a} + \bar{b}\dot{b}) - 3(\eta + \mu)sc \\ s\Im(a\dot{b} - \dot{a}b) - 3\mu\sigma s^3 \\ s\Re(a\dot{b} - \dot{a}b) + 3\mu\tau s^3 \end{pmatrix}.$$

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This gives

$$-\frac{1}{2}\operatorname{tr}(P^{\perp}V(k)(1^{\perp} - P^{\perp}(\eta R + \mu R_k)^2 P^{\perp})^{-1}P^{\perp}V(k)) =$$

$$= \begin{pmatrix} W_4(k) & W_5(k) & W_6(k) & W_7(k) \end{pmatrix} \begin{pmatrix} \Delta_1(\frac{\beta}{\sigma^2 + \tau^2} + \delta) & 0 & 0 & \Delta_1 p \\ 0 & \frac{\Delta_2 \beta}{\sigma^2 + \tau^2} & \Delta_2 q & 0 \\ 0 & \Delta_2 q & \Delta_2 \epsilon_2 & 0 \\ \Delta_1 p & 0 & 0 & \Delta_1 \epsilon_1 \end{pmatrix} \begin{pmatrix} W_4(k) \\ W_5(k) \\ W_6(k) \\ W_7(k) \end{pmatrix},$$
(111)

where

$$\begin{pmatrix} W_4(k) \\ W_5(k) \\ W_6(k) \\ W_7(k) \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \frac{\sigma}{\sigma^2 + \tau^2} & -\frac{\tau}{\sigma^2 + \tau^2} \\ 0 & 0 & \frac{\tau}{\sigma^2 + \tau^2} & \frac{\sigma}{\sigma^2 + \tau^2} \end{pmatrix} \begin{pmatrix} V_4(k) \\ V_5(k) \\ V_6(k) \\ V_7(k) \end{pmatrix} = \begin{pmatrix} sc\Im(\bar{a}\dot{a} + bb) \\ \dot{\theta} - 3sc(\eta + \mu) \\ s\Re(\frac{\dot{b}}{b} - \frac{\dot{a}}{a}) + 3\mu s^3 \\ -s\Im(\frac{\dot{b}}{b} - \frac{\dot{a}}{a}) \end{pmatrix}. \tag{112}$$

Inserting (111) into the general bi-YB action (100) gives the \mathbb{CP}^2 doubly deformed action (109)

$$S_{\eta,\mu}(k) = \int dt \, \Delta_2 \left(\frac{\beta}{|a|^2 |b|^2} W_5^2 + \epsilon_2 W_6^2 + 2q W_5 W_6 \right) + \int dt \Delta_1 \left(\left(\frac{\beta}{|a|^2 |b|^2} + \delta \right) W_4^2 + \epsilon_1 W_7^2 + 2p W_4 W_7 \right) - 9 \int dt \sin^2 \theta \quad (113)$$

presented in Section 6.3.

For $\mu = \eta = 0$, the equations (111), (112) become

$$-\frac{1}{2}\operatorname{tr}\left(P^{\perp}V(k)P^{\perp}V(k)\right) = W_4^2 + W_5^2 + |a|^2|b|^2(W_6^2 + W_7^2),\tag{114}$$

$$\begin{pmatrix} W_4(k) \\ W_5(k) \\ W_6(k) \\ W_7(k) \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \frac{\sigma}{\sigma^2 + \tau^2} & -\frac{\tau}{\sigma^2 + \tau^2} \\ 0 & 0 & \frac{\tau}{\sigma^2 + \tau^2} & \frac{\sigma}{\sigma^2 + \tau^2} \end{pmatrix} \begin{pmatrix} V_4(k) \\ V_5(k) \\ V_6(k) \\ V_7(k) \end{pmatrix} = \begin{pmatrix} sc\Im(\bar{a}\dot{a} + \bar{b}\dot{b}) \\ \dot{\theta} \\ s\Re(\frac{\dot{b}}{b} - \frac{\dot{a}}{a}) \\ -s\Im(\frac{\dot{b}}{b} - \frac{\dot{a}}{a}) \end{pmatrix},$$

which can be checked to correspond to the non-deformed Fubini-Study metric on \mathbb{CP}^2 .

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