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Spectral decomposition unlocks ascidian morphogenesis

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- ⁸ Abstract Describing morphogenesis generally consists in aggregating the multiple high
- 9 resolution spatiotemporal processes involved into reproducible low dimensional morphological
- ¹⁰ processes consistent across individuals of the same species or group. In order to achieve this
- ¹¹ goal, biologists often have to submit movies issued from live imaging of developing embryos
- either to a qualitative analysis or to basic statistical analysis. These approaches, however, present
- ¹³ noticeable drawbacks, as they can be time consuming, hence unfit for scale, and often lack
- standardisation and a firm foundation. In this work, we leverage the power of a continuum
- ¹⁵ mechanics approach and flexibility of spectral decompositions to propose a standardised
- ¹⁶ framework for automatic detection and timing of morphological processes. First, we quantify
- ¹⁷ whole-embryo scale shape changes in developing ascidian embryos by statistically estimating the
- ¹⁸ strain-rate tensor field of its time-evolving surface without the requirement of cellular
- ¹⁹ segmentation and tracking. We then apply to this data spectral decomposition in space using
- ²⁰ spherical harmonics and in time using wavelets transforms. These transformations result in the
- identification of the principal dynamical modes of ascidian embryogenesis and the automatic
- ²² unveiling of its blueprint in the form of spectograms that tell the story of development in ascidian
- 23 embryos.
- 24

25 Introduction

Morphogenesis, the emergence of shape in living systems, is a continuous process littered with 26 spatiotemporal dynamics at various timescales and lengthscales and significance. Developmental 27 biology aims at the identification, localisation, and timing of these processes. Once this work is car-28 ried out in a given species, embryogenesis can then be described as a series of stages delineated 29 in space and time by the identified landmarks Satoh (1978); Nishida (1986); Jeffery (1992); Keller 30 et al. (2003): Lemaire (2009): Sherrard et al. (2010): Hashimoto et al. (2015): Hashimoto and Munro 31 (2018): Guignard et al. (2020). In order to rigorously define development landmarks, biologists have 32 mostly had to submit imaged embryos either to qualitative analyses, or to rudimentary statistical 33 analysis. These methods however present major drawbacks. On the one hand, they can be time 34 consuming, hence unfit for scale. On the other hand, since morphogenetic processes tend to be 35 unique to a species, these simple methods often lack a general language and framework that per-36 mit comparative analyses. For instance, whereas the analysis of cell counts can inform about the 37 proliferation dynamics in a tissue, it does not reveal anything about the shape of the system. For 38 this purpose, other measurements such as length, width, height, aspect ratios or curvatures would 39 be more suitable. Although efforts have been made to automate the staging of development in 40 living systems *Jones et al.* (2022), these methods still rely on preliminary examination using tradi-41 tional methods.

43

of morphogenesis in a given system is henceforth needed. Recent breakthroughs in microscopy 44 technology have propelled the resolution of live imaging data to the sub-cellular scale, allowing 45 for the uncovering of precise cell and tissue shape dynamics **Tassy et al.** (2006): Stelzer (2015): **Power and Huisken (2017)**. These advances have created an unprecedented opportunity for the 47 leveraging of computational methods in the study of morphogenesis Tassy et al. (2006): Michelin 48 et al. (2015): Stegmaier et al. (2016): Leggio et al. (2019): Guignard et al. (2020). The rigorous and 49 physically motivated framework of continuum mechanics accommodates itself well to the flow-50 like dynamics of biological tissues Humphrey (2003); Ambrosi et al. (2011); Blanchard et al. (2009); 51 Humphrey (2013): Streichan et al. (2018). Within this framework, strain-rate fields, which measure 52 the rate at which the shape of a system changes with time, are suited to characterise the dynamical 53 behaviour of the system. Moreover, mounting evidence have informed of the requirement for 5/ embryo-wide approaches in the study of morphogenetic flows Streichan et al. (2018): Mitchell 55 et al. (2022). However, although the evaluation of such global fields across the spatial and temporal 56 domains spanned by a system of interest may reveal valuable insights into its dynamical workings 57 Bar-Kochba et al. (2015); Stout et al. (2016); Patel et al. (2018), their sole determination might not 58 be sufficient for a holistic description of the behaviour of the system: there is a need for novel 59 methods to analyse them. 60 This is especially true when it comes to morphogenesis Dalmasso et al. (2021); Romeo et al. 61 (2021): Mitchell and Cislo (2022). The processes involved in development are inherently multiscale. 62 both in the spatial and temporal domains, and may interact or overlap Godard and Heisenberg 63 (2019); Dokmegang et al. (2021); Dokmegang (2022). As it is the case with several species Godard 64 and Heisenberg (2019), ascidian gastrulation is a playground featuring important displays of cellu-65 lar divisions and tissue mechanics, most notably endoderm invagination Lemaire (2009). The local 66 behaviors captured by indicators such as the strain-rate field might therefore arise from a non-67 trivial superposition of these dynamical modes, essentially making these measurements complex 68 to interpret without further analysis. Spectral decomposition, whereby a signal is broken down into 69 its canonical components, is well suited to the study of systems that exhibit multimodal behaviors 70 Romeo et al. (2021): Dalmasso et al. (2021). The benefits are at least two-folds: (i) individual con-71 stituents may represent distinct dynamical processes, thereby enabling the decoupling of physical 72 processes entangled in the data; (ii) only a handful of components may significantly contribute to 73 the original function, resulting in a compressed, lower dimensional representation that capture 74 the main features of the studied process. The canonical components usually take the form of well 75 known families of functions whose linear combination can reconstitute the original field. 76 In this work, we take advantage of segmented cellular data to develop a generic computational 77 framework able to identify and delineate the main features of morphogenesis. Our method takes 78 as input precise segmentations of cellular geometries, although only the embryonic surface would 79 suffice, and outputs spatiotemporal spectograms of ascidian development in the form of heatmaps 80 that highlight key developmental processes and stages of ascidian gastrulation. By virtue of a novel 81 meshing scheme derived from level-set methods, raw cell geometry data is first transformed into 82 a single time-evolving embryonic surface on which the strain-rate tensor field can be computed. 83 The accuracy of our inference of a strain-rate field relies on high-frequency temporal sampling. 84 characterised by small deformations of the embryonic surface between subsequent time points. 85 The morphomaps we present are a result of spectral analyses of the strain-rate fields, featuring 86 spherical harmonics decomposition in the spatial domain and wavelet decomposition in the tem-87 poral domain. In summary, our method can identify and classify dynamical morphogenetic events. 88 In particular, we are able to identify and distinguish the morphogenetic modes of gastrulation and 80 neurulation phases in ascidian development, recover the characteristic two step sequence of en-90 doderm invagination originally described using 3D analysis of cell shapes Sherrard et al. (2010). 91 and capture patterns of cellular divisions in ascidian development *Nishida* (1986). Moreover, our method identifies a distinctive stage of ascidian gastrulation. 'blastophore closure', which follows

A standardized method able to identify key milestones in development and lay out the blueprint

endoderm invagination and precedes neurulation.

95 Results

⁹⁶ Definition of Lagrangian markers on the surface of the embryo

In order to recover a continuum description of the dynamics in ascidian morphogenesis, we aim to 97 examine the time evolution of strain-rate fields across the entire surface of developing embryos. 98 This endeavour however presents at least two significant challenges. On the one hand, strain-rate qc computation requires the presence of fiducial markers on the surface of the embryo. Character-100 istically, this requirement is not always accounted for in the imaging of developing embryos. On 101 the other hand, the outer layer of the embryo being constituted of single cell apical faces, even 102 if such markers had been defined at an earlier time point, uncontrolled stochastic biological pro-103 cesses such as proliferation within the tissue might subsequently grossly uneven the distribution 104 of these markers, thus rendering the computed mechanical indicators at best imprecise. Given the 105 non-triviality of an experimental setup able to solve the described issues, a computational method 106 is required. The goal of such a method would be to computationally discretise an embryo surface 107 into a set of material particles whose trajectories can be tracked in small lapses of development. 108 The positions of these markers over time can then be used to derive mechanical indicators of de-109 velopment dynamics Humphrey (2003). 110

To achieve this fit, we first take advantage of the level set scheme described in Zhao et al. (2000) 111 to define static markers on the surface of the embryo at every timepoint of development. The gist 112 of our method resides in the definition of a homeomorphic map between the surface of the em-113 bryo $(S_1(t))$ and a topologically equivalent mesh $(S_2(t))$ whose number of vertices, faces and edges 114 remain fixed (fig. 2a). Conformal parametrisations of embryonic shape have been used in other 115 systems Alba et al. (2021). Here, the topologically equivalent mesh consists of a sphere resulting 116 from successive butterfly subdivisions of an icosahedron *Hardy and Steeb (2008)*. Using a homeo-117 morphic map, this mesh can be deformed to match the surface of the embryo at each time point of 118 development (fig. 2b). As in **Zhao et al.** (2000), the map is obtained by finding the positions of $S_2(t)$ 119 vertices that minimize the distance between both surfaces (fig. 2a, *right*). At the initial time point, 120 $S_2(t)$ is chosen to be a sphere enclosing the embryo. For various reasons, including computational 121 efficiency, variants of this method can be defined such that, for instance, at subsequent time steps, 122 linear combinations of the sphere and its deformations matching the embryo at preceding steps 123 are used. Further details are given in the Methods section. 124

Next, via a numerical study, we assert that markers defined as such behave as Lagrangian parti-125 cles in small increments of developmental dynamics. To support this point, we identify on the raw 126 dataset the positions of cellular junctions at the surface of the embryo and evaluate how well our 127 virtual markers mimic their movements in time. We measure the relative displacement between a 128 cellular junction (fig. 1c red points) and its corresponding vertex (fig. 1c, green points) at consecutive 129 time points. We take the difference between these distances and normalise it by the average side 130 length of cell apices. Despite gross approximations inherent to the nature of the dataset (geomet-131 ric meshes) and the process of identifying cellular junctions (averaging the barycenters of closest 132 triangles between three or more cells in contact), the displacement between cellular junctions and 133 their markers remains on average relatively small (under 8%, fig. 1d). We further show that this 134 characteristic is independent of the number of particles used in the method (sup fig. 1c), making it 135 a remarkable property of the scheme. This result sheds even more favorable light on the method 136 when considering that cellular junctions, precisely because they are the meeting point of three or 137 more cells, are expected to exhibit more chaotic behaviour than single cell particles. Moreover, 138 these numbers are skewed by large scale morphogenesis processes such as synchronised cell di-139 visions, as evidenced by spikes in fig. 1d. and fast-paced endoderm gastrulation, as highlighted by 140 higher errors at the vegetal pole of the embryo during this phase (red dots in fig. 1c, right). 141



Figure 1. Level-sets inspired Lagragian markers. a) *Left* Schematics of the level set method. *Right* Fundamentals of the numerical scheme that shapes S_2 into S_1 . **b)** Illustration of the method in action. *Left* Raw data consisting of geometric meshes of single cells spatially organised into the embryo. *Center* Embryo surface mesh resulting from the application of the level set scheme. *Right* Rendering of the embryonic surface. **c)** Tracking of cellular junctions. *Left* Identification of cellular junctions (*red dots*). *Center* Corresponding markers (*green dots*, defined as vertices on the computed embryonic surface closest to the junctions. *Right* Relative displacement between junctions and their markers at consecutive timepoints. **d)** Plot over time of the relative displacement between cellular junctions and their markers.

142 Strain rate Field describes ascidian morphogenesis

Once a mesh representing the surface has been constructed for the embryo surface, we proceed 143 with the computation of the strain-rate fields across the surface of the embryo and throughout 144 development timeline. Thanks to the Lagrangian nature of mesh vertices, a velocity field can be 145 defined on the mesh. Although particles at every given time point live on the 2D surface of the 146 embryo, their trajectories in time involve greater degrees of freedom in the 3D space. A correct 147 parametrisation of the velocity field at every position henceforth requires three coordinates $\mathbf{v}(\mathbf{x}) =$ 148 $(v_x(\mathbf{x}), v_y(\mathbf{x}), v_z(\mathbf{x}))^T$. The strain rate field is derived as the symmetric part of the discrete gradient 149 of the velocity field, computed as described in Mancinelli et al. (2018). Intuitively, the strain rate 150

evaluated on a given mesh vertex measures how the velocity vector varies in the neighbourhood
 this point *Mancinelli et al. (2018); De Goes et al. (2020)*.

$$D(t, \mathbf{X}) = sym(\nabla \mathbf{V}(t, \mathbf{X}))$$
(1)

The mathematical construction of the strain rate eq. 1 implies that its algebraic representation 153 takes the form of a second order tensor which can be written down as a 3×3 matrix (D)_{ii}. The diag-154 onal elements of this matrix capture the linear strain rate in the x, y, z axes, depicting the change 159 in length per unit length. The non-diagonal elements stand for shear strain rates in the the $xy_{x}z_{z}$ 156 and vz directions. Because D is symmetric, there exists an alternative representation which holds 157 stronger local geometric meaning. This representation is obtained by computing the eigenvectors 158 and eigenvalues of the strain rate tensor. Eigenvectors in this sense stand for orthogonal spatial di-159 rections that are not rotated, but only stretched, by the application of the strain rate matrix. They 160 define the principal axes of a coordinate system in which the strain rate tensor would be solely 161 composed of maximal linear strain rates (fig. 2a). From this decomposition, we derive a scalar field 162 that is computed at every mesh particle as the square root of the sum of the squared eigenval-163 ues of the strain-rate (fig. 2b). Intuitively, this field describes the magnitude of the rate of change 164 underwent by a particle at the surface of the embryo in the three orthogonal spatial directions of 165 most significant rate of change. 166

In order to minimize undesirable artifacts that may arise from numerical inefficiencies, we ap-167 ply a Gaussian filter to the strain rate tensor field before deriving the scalar field. At each particle 168 location, we apply a Gaussian convolution mask spanning its first and second order neighbour-169 hood. A similar smoothing process is also used in the time domain. Interestingly, this strain-rate 170 derived scalar field remarkably mirrors well-known features of ascidian development. Similarities 171 between the spatiotemporal distribution of morphogenesis processes described in the literature 172 and heatmaps of this field on the evolving embryo surface emerge. On the one hand, wider spatial 173 gradients of vellow to red depicting higher morphological activity portray the spatiotemporal lo-174 cations of endoderm invagination in the embryonic vegetal pole (fig. 2b, center-left), synchronised 175 rounds of division in the animal pole, and zippering in the neural plate Hashimoto et al. (2015) 176 (fig. 2b, center-right, right). On the other hand, known spatiotemporal locations of low morphologi-177 cal significance in the embryo exhibit stronger concentration of mechanical activity on cell bound-178 aries, with the corollary that cellular identities are mostly preserved (fig. 2b, t = 4hpb). A notable 170 by-product of this scalar field is the evidencing of the duality of the embryo as both a sum of parts 180 constituted of cells and an emerging entity in itself: the strain rate field clearly discriminates be-181 tween spatiotemporal locations where isolated single cell behaviours are preponderant and those 182 where coordinated cell behaviours dominate. 183

This brief overview already demonstrates the riches in a quantitative, spatially global and not event-driven approach to study morphogenesis. It also sets the stage for further analysis of morphogenesis dynamics in the ascidian embryo.

Spectral decomposition in space: Spherical harmonics reveal the main modes of ascidian morphogenesis

In order to capture relevant features of the strain rate field in the spatial domain, we conduct a 189 spectral analysis of the scalar strain rate field. The family of spherical harmonic functions stands 190 out as a de-facto standard for the study of signals defined on a unit sphere, and by extension on 191 surfaces homeomorphic to the sphere. Spherical harmonics form an infinite orthonormal basis of 192 functions defined on the surface of the sphere and represent a generalisation of the Fourier series 103 for functions of two variables Knaack and Stenflo (2005). Unsurprisingly, these functions play an 194 important role in many branches of science including quantum mechanics and geophysics *Knagck* 195 and Stenflo (2005); Dahlen and Tromp (2021). Spherical harmonics have recently been used in 106 studies of morphogenesis in zebrafish and mouse Romeo et al. (2021); Dalmasso et al. (2021). 197





¹⁹⁸ Spherical harmonic basis functions are indexed by two parameters (l, m), such that $l \ge 0$, $|m| \le l$ ¹⁹⁹ representing respectively the degree and order of the harmonic (Supplementary figure 3). A signal ²⁰⁰ defined on the sphere can be written as a linear combination of such functions. Decomposing a ²⁰¹ signal into spherical harmonics hence amounts to finding the coefficients f_{lm} of this weighted sum. ²⁰² In the case of our spatiotemporal scalar strain rate field, the coefficients f_{lm} are also a function of ²⁰³ time and can be obtained as shown in equation 2.

$$f_{lm}(t) = \oint f(\theta, \phi, t) Y_{lm}^*(\theta, \phi) dA$$
⁽²⁾

Here, Y_{lm}^* stands for the complex conjugate of the spherical harmonic Y_{lm} . Moreover, for a given degree *l*, each of the (2l + 1) spherical harmonics $(Y_{lm})_{|m| < l}$ spatially partitions the unit sphere into as many spatial domains indicating when a signal is positive, negative or null (Supp. Fig.4a). Figure 3a illustrate the projections of the scalar strain rate field to spherical harmonics $(Y_{lm})_{l \le 2, |m| < l}$ at t = 4.74hpf, and their mapping unto the surface of the embryo. These plots reveal for instance that while there is no embryo-wide dominant morphogenesis process at this time (l = 0, m = 0), smaller regions, notably the vegetal pole are experiencing significant morphological activity (l = 1, m = 0).

The contributions of each spherical harmonic to the global signal can be assessed more rigor-211 ously, and interpreted in the light of biology. To this effect, we observe the temporal dynamics 212 of the coefficients $f_{lm}(t)$ associated with each spherical harmonic. In analogy to Principal Compo-213 nents Analysis, we measure the average variance ratio over time of each harmonic with respect to 214 the original signal (Fig. 3b). With a variance ratio of 64.4%, the spherical harmonic Y_{00} , capturing 215 embryo-wide morphological activity, contributes the most to ascidian morphogenesis. Spherical 216 harmonic Y_{10} is the next contributor, coming second with a variance ratio of 4.1%. This observation 217 is warranted, as Y_{10} maps to the animal and vegetal poles of the embryo, which are the epicenters 218 of synchronised cellular divisions and endoderm invagination respectively leffery (1992): Lemaire 210 (2009). Interestingly, variances in the directions of Y_{00} and Y_{10} evolve in an antiphased pattern, 220 most notably in earlier parts of the plot, with Y_{00} contributing maximally (and Y_{10} minimally), during 221 periods of cell division, before relinquishing some variance shares to Y_{10} , which then peaks. This 222 suggests that while sporadic deformations induced by cellular divisions often dominate the land-223 scape of morphological activity, an observation consistent with studies in other species Cislo et al. 224 (2023), other localised, slower processes are at play in the embryo. The described pattern tends to 225 fade out in the later parts of the plot, suggesting a shift in development dynamics. 226

Furthermore, by observing the time dynamics of the coefficients themselves (Fig. 3c), one can 227 easily identify which parts of the embryo are concerned by the morphological changes depicted. 228 For instance, the positive peaks in $f_{10}(t)$ (Fig. 3c) indicate that the morphological processes at hand 229 take place in the northern hemisphere of the sphere. Remarkably, these coincide with rapid growth 230 in cell population and thus synchronous cell divisions, which are known to be restricted to the 231 animal pole of the ascidian embryo during endoderm invagination *leffery* (1992). In addition, most 232 of the dynamics captured by $f_{10}(t)$ are in the negative spectrum ($f_{10}(t) < 0$), pointing to the lower 233 hemisphere of the embryo, the foyer of several cell shape deformations at play in ascidian early 234 development. 235

The sporadic short-time scale cell division events in the animal pole coexist with numerous other features of morphogenesis, most notably, the larger scale continuous deformation process in endoderm invagination at the embryonic vegetal pole. Beside the peaks on the plots of the time series, it is not a trivial task to identify what other rich insights may be hidden in this data. A simple observation of the oscillatory patterns of these main modes hence paints an incomplete picture of ascidian morphogenesis. Extracting the footprint of all morphogenesis processes in these time series requires further analysis.

Spectral decomposition in time: Wavelets analysis of spherical harmonic signals unveils the blueprint of morphogenesis

Analysing timeseries often implies the understanding of how a signal is composed and how its com-245 ponents overlap in time. Wavelets have been put forward as effective multi-resolution tools able 246 to strike the right balance between resolution in time and resolution in frequency Torrence and 247 Compo (1998): Law and Weng (1995). Although they have been taken advantage of in the broader 248 context of biology, most notably in the analysis of brain and heart signals **Brunton and Kutz (2022)**. 249 they have so far been under-used in developmental biology. The reason might be found in the 250 reality that morphogenesis data is often not understood in term of time series. Our spherical har-251 monics decomposition of morphogenesis, inspired by similar endeavours in other fields **Dahlen** 252 and Tromp (2021): Knaack and Stenflo (2005), offers an unprecedented opportunity to leverage 253 the existing rich signal processing toolbox in development biology. In particular, enlisting the help 254 of wavelet transforms in unlocking the complex entanglements of the multiple morphological pro-255 cess at play during ascidian early development. We proceed to apply the Ricker wavelet transform 256 to our spherical harmonics time series, normalised by mean and standard deviation in different 257 time windows of interest. The result is a set of spectograms which decompose the signals into 258 canonical components organised in timelines that reveal the story ascidian morphogenesis. 259 First, we apply the wavelet transform on the timeseries $f_{oo}(t)$ to the entire time range covered 260



a. Spherical harmonics decomposition of the strain rate eigen field





Figure 3. Spherical harmonics decomposition of morphogenesis. a) Example of Spherical harmonics decomposition of the scalar strain rate field mapped to the embryo at t = 4.74 hpf. **b)** Time evolution of the variance ratios of the main modes of ascidian early morphogenesis (Y_{00} and Y_{10}). The cell population dynamic is also included in the plot for clarity. **c)** Time evolution of the coefficients f_{00} and f_{10} associated with spherical harmonics (Y_{00} and Y_{10}). The cell population count is also included in the plot for clarity.

by our dataset, comprising both gastrulation and neurulation (fig. 4a). Mirroring this timeseries, 261 the high frequency events depicted by yellow blobs at the top of the heatmap represent periods of 262 synchronized division across the embryo. The dark band in the middle separating two large regions 263 depicts a short transition phase delimiting two phases of ascidian early development. The timing 264 of these stages as reflected in the scalogram matches the timeline of gastrulation and neurulation. 265 Within both phases, the concentric gradients from red to yellow culminating in dense yellow spots 266 in the center of both regions portray increasing morphodynamics. 267 To better understand the specifics of ascidian gastrulation, we restricted the wavelet transform 268

to the gastrulation period ($t \in [4, 6.3]$ hpf). The resulting spectogram (fig. 4b) shows that ascidian gastrulation unfolds itself in two major phases, delineated on the scalogram by the dark region at the center of the heatmap. The timeline of these events, strengthened by an analysis of topological holes in the embryo (supplementary fig. 4a) support the hypothesis that these phases correspond to endoderm invagination followed by the near-closing of the future gut, a process initiated by the collective motion of lateral mesoderm cells known as *blastophore closure*. Both the timeseries (mostly in the negative spectrum) and the scalogram of $f_{10}(t)$ (fig. 4c) adds another layer of validity

(mostly in the negative spectrum) and the scalogram of $f_{10}(t)$ (fig. 4c) adds another layer of validity to this conclusion: the large yellow blob occupying the majority the plot surface highlights that fact

to this conclusion: the large yellow blob occupying the majority the plot surface highlights that fact that regions of the embryo covered by spherical harmonic Y_{10} , hence endoderm and mesoderm cells, are subject to intense and prolonged morphological processes.

The first of these two phases, namely endoderm invagination, has been thoroughly investigated 279 in literature. Most notably, it was identified that endoderm invagination was driven by two distinct 280 mechanisms of endoderm single cells Sherrard et al. (2010): first, cells constricted apically by reduc-281 ing the surface area of the apices, flattening the convex vegetal pole of the embryo setting the stage 282 for invagination. This was followed by animal vegetal shortening of their lateral faces, triggering 283 endoderm invagation. The wavelet transform restricted to the period of endoderm invagination 284 applied to $f_{20}(t)$, whose corresponding spherical harmonic function $Y_{20}(t)$ maps more precisely to 285 the endoderm, beautifully captures this two-steps process (fig. 4d). The timing revealed by this 286

scalogram is in accordance with an analysis endoderm cell shape ratios (supplementary fig. 4b).

²⁸⁸ Spectral decomposition of morphogenesis in experimentally perturbed embryo

To assess how our framework adapts to different phenotypes, we set out to conduct a spectral de-289 composition of morphogenesis in an experimental manipulated embryo. In this particular mutant, 290 MEK kinase was inhibited, which resulted in a massive re-specification of vegetal cell fates, and 291 a disruption of endoderm invagination *Guignard et al. (2020*). We applied to the mutant dataset 292 (fig 5a top) each of the steps in our workflow. First an evolving mesh matching the shape of the 293 embryo at every time point was obtained through the level set scheme. Then, a strain rate tensor 294 field was computed over the surface of the embryo throughout development time (fig 5a bottom) 295 A spatiotemporal spectral analysis was subsequently conducted using spherical harmonics on the 296 mutant surface and wavelet analysis of the timeseries of the coefficients of the main harmonic 297 modes. In order to meaningfully compare the dynamics of the mutant development against those 298 of the wild-type embryo, the analysis was carried out the 64-cell stage. 200

Similar to the wildtype (WT) embyro, the main harmonic modes in the mutant development 300 were Y_{00} and Y_{10} with respective variance ratios 73.68% and 1.65%, making the timeseries $f_{00}(t)$ and 301 $f_{10}(t)$ the main focus of our examination. The temporal dynamics of these coefficients already 302 reveal major differences between the two strains of ascidians (fig 5b). On the one hand, the drop 303 in the share of Y_{10} is telling of the lower order of morphological activity in the vegetal hemisphere. 304 The difference with WT embryos is even more striking when considering that they are deprived 305 of cell division in their vegetal hemisphere. On the other hand, the peaks and lows of $f_{10}(t)$ which 306 coincide with growth in cell numbers, are not restricted either to the negative or positive domain 307 of the curve. This implies that, contrary to the WT, synchronous cell divisions are not restricted to 308 one hemisphere of the embryo. 300

The wavelet transform applied to timeseries $f_{00}(t)$ and $f_{10}(t)$ yield spectograms which bring fur-310 ther insights into the mutant morphogenesis (fig 5c). On the one hand, the heatmap of $f_{co}(t)$ hints 311 to two distinct phases of the mutant development during the observed time span (fig 5c top). The 312 timing of the second phase seems to coincide with the advent of the major wave of cell divisions 313 in the embryo. On the other hand, plots of the scalogram of $f_{10}(t)$ appears to concur with the hy-314 pothesis of very low morphological activity in the vegetal pole. The constant red on this heatmap 315 reflects unchanging levels of morphological activity at the vegetal pole of the embryo and confirms 316 the absence of drastic cell deformations that usually drive invagination. This is in alignment with 317 the perturbation induced by MEK kinase which prevents invagination for happening in the mutant 318 endoderm. 319

320 Discussion

Ray Keller's roadmap of morphogenesis studies establishes a clear path for understanding the biomechanical processes involved in development *Keller et al.* (2003). In his proposed workflow.





the first step is to determine when and where cells move. Identifying regions of significant mor-323 phological activity in space and time has usually followed a script consisting of observing via a mi-324 croscope the developing system, formulating a hypothesis of what is happening in the system, and 325 subsequently affirming or refuting the hypothesis using qualitative analysis. This method, which 326 has successfully propelled the field of developmental biology to its current heights, nevertheless 327 has some limitations. Distinct morphogenesis events can overlap both in space and time, render-328 ing eye observation vulnerable to misinterpretation. Second, these methods are not automated, 329 hence do not scale. 330

In this work, we attempted to develop an alternative approach to probing development in liv-

a. Wavelet transform (WT) on $f_{00}(t)$ for gastrulation + neurulation period ($t \in [4, 8.7]$ hpf) Gastrulation

a. Ascidian mutant morphogenesis + strain rate mapped to the surface of the mutant



b. Timeseries of f_{00} and f_{10}



C. Wavelet transform on $f_{00}(t)$ and $f_{10}(t)$ for Mutant embryo





ing systems. Our approach takes advantage of the recent boom in the availability of single cell 332 shape tracking data to propose a generic method able to identify interesting defining morpholog-333 ical processes through space and time in developing embryos. The method takes as input data 334 consisting of evolving cell geometries and outputs a series of spatial heatmaps showcasing in the 335 time-frequency domains the most salient traits of morphogenesis in the studied embryo. There is 336 however no requirement for segmented cells: the method can be extended to accommodate mi-337 croscopy imaging data. Our framework presents over the traditional eye test method multiple ad-338 vantages. First, the workflow is fully automated, providing an unprecedented hands-off approach 339 in preliminary studies of morphogenesis. Another outstanding advantage over traditional is that 340 our workflow is able to compress the story of the development, such that, in a single image, one can 341 grasp the essence of morphogenesis in a system of interest. In particular, our method has been 342 able to neatly discriminate between the gastrulation and neurulation phases of ascidian early de-343 velopment, identify a second phase of gastrulation: blastophore closure which follows invagination, 344 reconstitute the two-step process of endoderm invagination during the gastrulation phase, while 345

clearly distinguishing between short scale division events and low frequency tissue-wide deforma tions.

In order to achieve this fit, raw cell shape data underwent a series of transformations includ-348 ing a level-sets driven homeomorphic map of the unit sphere to the developing embryo's surface. 349 the computation of the strain rate field of embryo deformations through time using successive 350 iterations of this map, a spherical harmonics decomposition of this strain-rate field, and wavelet 351 decomposition of the most significant spherical harmonics time series. Each of these transfor-352 mations comes with its own challenges, but also delivers new perspectives for the study of living 353 systems. Our level set scheme excels at defining a homeomorphic map between the unit sphere 354 and surface of the embryo. It goes without saying that in order for the deformed sphere to best 355 match the shape of the embryo, a high sampling of points on the unit sphere is required. A com-356 promise is however necessary between this sampling and, on the one hand, the overall spatial 357 resolution of the raw data, on the other hand, the induced computational complexity. In its cur-358 rent form, the scheme produces approximations of Lagragian particles only under the assumption 350 of small deformations in the embryo. Hence, the sampling rate during microscopy imaging is of 360 critical importance: the shorter intervals between two successive frames of the movie, the more 361 Lagragian-like the particles are expected to behave. 362

Given the provision of tracked surface particles meshed at every frame in a triangular network. 363 the evaluation of the strain rate field is straightforward, and enables, among others, a unified de-364 scription of complex cell-level and tissue-level dynamics **Blanchard et al.** (2009), such as drastic 365 deformations and synchronised divisions. The accuracy of this field is affected, as previously, by 366 both the spatial sampling of material points on the unit sphere and the timely sampling of morpho-367 genesis frames. A visualisation of the eigenvalue field derived from this tensor field on the surface 368 of the embryo can already highlight significant processes in morphogenesis. The decomposition of 369 this field into spherical harmonics allows a better appreciation of the spatial patterns of morpho-370 logical activity in the embryo, each harmonic mapping a region of space. Our spherical harmonics 371 decomposition of morphogenesis results in a set of timeseries of coefficients associated with each 372 harmonic, representing to the best of our acknowledge, the first comprehensive timeseries-based 373 description of morphogenesis. This transformation unleashes the full power of signal processing 374 tools into studies of morphogenesis. The basis of spherical harmonics being infinite, a challenge 375 here is to discriminate between harmonics that significantly contribute to the composed signal 376 and those that do not. Here, this was done by singling-out harmonics which contributed the most 377 to the variance of the strain rate field. Furthermore, the filtration of principal harmonics modes 378 enables the representation of morphogenesis in a significantly compressed form, in comparison 379 to the initial datasets. This lower dimensional representation of morphogenesis can be helpful. 380 among others, in modelling the physical dynamics of the system *Romeo et al.* (2021). Another chal-381 lenge is with the interpretability of the harmonics, which is subject to the alignment of the embryos. 382 The datasets used in this paper presented the advantage that their y - axis was guasi-aligned with 383 their *vegetal – animal* axis. For embryos which do not have this property, prior processing to align 384 them will be required. Alternatively, rotation-invariant representations can be used to appropri-385 ately interprete the harmonics. 386

Despite describing canonical interactions in the space of spherical harmonic functions, our 387 spherical timeseries still represent composed signals in time. We use the Ricker Wavelet as a math-388 ematical microscope to zoom-in and zoom-out through these signals in order to identify their fun-380 damentals components. This operation results in two-dimensional time-frequency heatmaps that 390 showcase, for each time-series, the footprint of its canonical high and low frequency components. 301 which can be mapped to biological processes. The sum of these tell the story of morphogenesis 392 in the region corresponding to the spherical harmonic. Here, it might also be useful to wisely tar-393 get windows of time of interest, and to normalise the data such that interesting transitions can be 394 picked up easily by the wavelet transforms. The resulting heatmaps can be fed to analytic work-395 flows such as deep neural networks for further studies. Example scenarios could include varia-

- ³⁹⁷ tional studies of morphogenesis processes in different wild-type or mutant embryo. Furthermore,
- the workflow presented in this paper can be applied to the examination of single cell morphological
- ³⁹⁹ behaviours in development.
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