

Towards Common Data Exchange Formats for Seafloor Geodesy

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Towards common data exchange formats for seafloor geodesy Recent development of the GNSS-A Data Standardization Task Force

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1) Scripps, Univ. of Washington & Ocean Network Canada (source: D. Schmidt & M. Heesemann)



2) IUEM Brest & LIENSs La Rochelle (source: J.-Y. Royer & P. Sakic)



Goals

The goals of the task force were defined as follows:

- Enable the shareability of the seafloor geodesy data collected by the different research groups around the world.
- Give **better visibility** to seafloor geodetic data.
- Respect the **FAIR data principles** (Findable, Accessible, Interoperable, Reusable).
- A special emphasis has to be given to the **interoperability** of seafloor geodetic data, i.e., the possibility to easily use data of one research group with the software of another one.
- Identify how data can be **easily stored in existing** repositories or establish expectations for new repositories.
- Establish community-supported data standards that can be adopted by the repositories/data centers.

Initially, the task force attempted an exhaustive inventory of all the seafloor geodetic techniques. Given the main interest in **GNSS-Acoustic** for the initial participants during the first meeting, it was agreed to start discussions with this **technique.** Nevertheless, the task force is interested in a **wide** range of techniques and will likely revisit them in the future e.g. acoustic ranging, ocean bottom pressure sensors (OBP), tiltmeters...

How to federate the international seafloor geodesy community while making GNSS-A data acquired around the World interoperable?

⇒ Yes

The necessity to explicitly include both the send and receive ping epochs? If not, which one is the best? \Rightarrow We include both

What data level (raw versus initially processed) is appropriate for broad dissemination of GNSS-A data, and ingestion by processing codes?

 \Rightarrow **UTC scale**, a reference epoch in the header, and the seconds w.r.t. the reference for each event

What should be the standardized reference frame for the position of the surface platform?

 \Rightarrow **ECEF representation**. A sufficient level of detail must be provided regarding the reference frame in the metadata/header

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Since the 19th of October 2022, representatives of the seafloor geodesy community have met on a regular basis within an *ad hoc* working group called the GNSS-Acoustics Data Standardization Task Force (GADSTF). This task force has been placed **under the umbrella of the** International Association of Geodesy's Inter-Commission **Committee on Marine Geodesy** (ICCM).

Main points discussed within the Task Force so far

Should we continue with ASCII/CSV style for GNSS-A data?

• Such a data representation style is more or less "universal" since all the members of the Task Force currently use it. • "such representation format must remain community-driven".

⇒ Level 1: raw observation i.e. RINEXs, lever arms, waveforms... \Rightarrow Level 2: a "master configuration + main data" file with preprocessed data

Which time scale/representation should we adopt for the recorded epochs?



8 : Nagoya University, Earthquake and Volcano Research Center, Nagoya, Japan 9 : University of Houston, Dept of Civil and Environmental Engineering, Houston, USA 10 : Institute of Industrial Science, University of Tokyo, Tokyo, Japan



4) Japan Coast Guards (source: S. Watanabe)

Prototype for a future common exchange format

Draft of GNSS-A data format standardization

Version 0.231129 before discussion of the standardization Taskforce meeting of the 29th November 2023

Definitions of column in GNSS-A standard CSV format Table 1. Definitions of column in GNSS-A standard CSV format

Index	Necessity	Description		
MT_ID	Essential	ID of mirror transponder		
TravelTime	Essential	Observed travel time (net value) [sec.]		
T_transmit	Essential	Transmission time of acoustic signal [sec. from origin]		
X_transmit	Essential	Transducer position at T_transmit in ECEF [m]		
Y_transmit	Essential	Transducer position at T_transmit in ECEF [m]		
Z_transmit	Essential	Transducer position at T_transmit in ECEF [m]		
T_receive	Essential	Reception time of acoustic signal [sec. from origin]		
X_receive	Essential	Transducer position at T_receive in ECEF [m]		
Y_receive	Essential	Transducer position at T_receive in ECEF [m]		
Z_receive	Essential	Transducer position at T_receive in ECEF [m]		
ant_X0	Optional	GNSS position at T_transmit in ECEF [m]		
ant_Y0	Optional	GNSS position at T_transmit in ECEF [m]		
ant_Z0	Optional	GNSS position at T_transmit in ECEF [m]		
roll0	Optional	Roll at T_transmit (in degree)		
		<pre>*rotation around "forward" axis in ATD offset</pre>		
pitch0	Optional	Pitch at T_transmit (in degree)		
		<pre>*rotation around "rightward" axis in ATD offset</pre>		
heading0	Optional	Heading at T_transmit (in degree from north)		
		<pre>*rotation around "downward" axis in ATD offset</pre>		
ant_X1	Optional	GNSS position at T_receive in ECEF [m]		
ant_Y1	Optional	GNSS position at T_receive in ECEF [m]		
ant_Z1	Optional	GNSS position at T_receive in ECEF [m]		
roll1	Optional	Roll at T_receive (in degree)		
pitch1	Optional	Pitch at T_receive (in degree)		
heading1	Optional	Heading at T_receive (in degree from north)		
[other]	Optional	Any other optional indices		
		* should be defined in the header or other documents		

Definitions of site information file in GNSS-A standard format

Current discussion in the Task Force intent to store these metadata either:

In the header of the data stored in a CSV as in the Table 1

In a separated dedicated file such as YAML

Variable	Format	Description
Site_name	character	GNSS-A site name or code
Campaign	character	Observation campaign name
TimeOrigin	YYYY-MM-DD hh:mm:ss.s	Origin of time used in the file [UTC]
RefFrame	character	Reference frame used in the file
MTlist	list of character	List of ID of mirror transponders
[*]_appPos	list of float	Approximate positions of transponder <i>in</i> <i>ECEF</i> [m] [*] should be replaced with MT's ID.
ATDoffset (optional)	list of float	ATD offset (or local-tie/ lever-arm) defined as the vector of GNSS to transducer with [forward, rightward, downward] in [m]
[<i>other</i>] (optional)	N/A	Any other optional values * should be clearly defined in comments or other documents
Comments (optional)	character	Any other optional comments

3) Tohoku University (source: M. Kido)







5) Nagoya University (source: K. Tadokoro)

Future topics of discussion

- Establish standards for low-level data to be included as Level 1 data (GNSS record as RINEX, raw waveform, etc.).
- Identify the best data quality indicators for GNSS/A data.
- How to improve metadata records.
- The appropriateness of archiving GNSS/A data in a binary format, such as NetCDF
- Define a naming convention for the data files, seafloor sites, and campaigns.
- Establish **new task forces** for other seafloor geodetic data types, **especially for ocean** bottom pressure.

We welcome new members to join the task force! Help us to strengthen the international seafloor geodetic community!







get the report the Task Force provided to the IAG for the IUGG'23

> https://hal.science/ hal-04319233

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