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On a Fast Direct Solver for High Order Integral Equations: Results for Low-to-Middle Frequencies

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Abstract—In this work, we present a fast direct solver for integral equations-based electromagnetic scattering that is compatible with spatial discretization of arbitrary order. The proposed approach leverages a suitably preconditioned combined field formulation and involves the regularization of the elliptic spectrum through the extraction of a specifically chosen equivalent circulant problem. The procedure yields a compressed representation of the inverse system matrix in the form of a matrix amenable to fast inversion and a single-skeleton low-rank perturbation. In addition to proposing the fast direct solution framework, this contribution presents the algorithms and explores the intricacies that enable the high-order discretization of the underlying integral equations and is supported by numerical results illustrating its effectiveness.

I. INTRODUCTION

Integral equation (IE) methods are widely used to solve radiation and scattering problems across a wide range of frequencies and common equations are the electric, magnetic, and combined field integral equations (EFIE, MFIE, and CFIE respectively). One of their attractive features is that they only require the discretization of the boundary of the scatterer. Nonetheless, the matrices that result from the discretization procedure are dense and ill-conditioned in several regimes. Solving classical IE schemes typically has a computational complexity greater than quadratic for high frequency regimes. One way to lower this computational complexity are fast matrix-vector products (MVP) used with iterative solvers for efficient solutions. Nevertheless, this approach becomes less attractive when the matrix systems need to be solved for numerous right-hand sides (RHS), as is required, for instance, in computing backscattering cross-sections. To overcome this, different fast-direct solver (FDS) methods have been implemented, such as [3] or references therein. Recently, a new FDS based on a preconditioned combined field integral equation (CFIE) and that enhances compressibility of the system matrix by extracting a circulant matrix, has been presented [1]. The overall scheme yields a single skeleton form to be stored for the whole extracted part, such that accurate solutions for multiple RHSs can be obtained efficiently. This method however, did not allow for high order discretization, thereby limiting its ability to harness their faster convergence rates.

Our work extends the previously introduced fast direct solver scheme [1], expanding its capabilities to include highorder functions. The new scheme yields a representation of the inverse system matrix in the form of a matrix amenable to fast inversion and a single-skeleton low-rank perturbation. The new algorithms and corresponding theoretical framework are presented in this contribution and are accompanied by numerical results, showing the effectiveness of the high-order scheme.

II. BACKGROUND AND NOTATION

Consider a perfectly electrically conducting (PEC) object delimited by a 2-dimensional convex contour γ , excitated by a TE time-harmonic incident electromagnetic field ($\mathbf{E}_{inc}, \mathbf{H}_{inc}$) of angular frequency ω . This object is situated within a medium characterized by a permittivity ε , permeability μ , impedance $\eta = \sqrt{\mu/\varepsilon}$, and wavenumber $k = \omega \sqrt{\mu\varepsilon}$. The CFIE that establishes the relationship between the induced tangential current density j on the surface γ and the incident electric and magnetic fields is

$$\frac{1}{ik}\mathcal{N}^{k}(j_{t}) + \left(\frac{\mathcal{I}}{2} - \mathcal{D}^{k}\right)(j_{t}) = -\frac{1}{\eta}E_{t}^{\mathrm{inc}} - H_{z}^{\mathrm{inc}}, \quad (1)$$

where $\mathcal{N}^k(j_t) \coloneqq -\frac{\partial}{\partial n} \int_{\gamma} \frac{\partial}{\partial n'} g_k(\mathbf{r}, \mathbf{r}') j_t(r') dr', \ \mathcal{D}^k(j_t) \coloneqq \int_{\gamma} \frac{\partial}{\partial n'} g_k(\mathbf{r}, \mathbf{r}') j_t(r') dr', \ \text{and} \ g_k(\mathbf{r}, \mathbf{r}') \coloneqq i/4 H_0^{(1)}(k||\mathbf{r} - \mathbf{r}'||),$ where $H_0^{(1)}$ indicates the Hankel function of the first kind. The boundary elements used to expand the current density j_t are scalar piecewise polynomials λ_i^p , forming a complete space of order p, in which cell-to-cell continuity is appropriately enforced. After Galerkin testing, the discrete system reads

$$\frac{1}{ik}\mathbf{N}^{k}\mathbf{j} + \left(\frac{\mathbf{G}}{2} - \mathbf{D}^{k}\right)\mathbf{j} = -\frac{1}{\eta}\mathbf{e} - \mathbf{h}, \qquad (2)$$

with $[\mathbf{e}]_i = \int_{\gamma} \lambda_i^p(\mathbf{r}) E_t^{\text{inc}}(\mathbf{r}) d\mathbf{r}$, $[\mathbf{h}]_i = \int_{\gamma} \lambda_i^p(\mathbf{r}) H_t^{\text{inc}}(\mathbf{r}) d\mathbf{r}$, $[\mathbf{N}^k]_{ij} = \langle \lambda_i^p, \mathcal{N}^k \lambda_j^p \rangle$, $[\mathbf{D}^k]_{ij} = \langle \lambda_i^p, \mathcal{D}^k \lambda_j^p \rangle$, $[\mathbf{G}^k]_{ij} = \langle \lambda_i^p, \lambda_j^p \rangle$, with $\langle f, g \rangle = \int_{\gamma} f(\mathbf{r}) g(\mathbf{r}) d\mathbf{r}$.

III. METHODS

The matrix system (2) can be preconditioned with a modified version of the preconditioner proposed in [2], which results in the following discrete system

$$\mathbf{C}\mathbf{j} = -\frac{ik}{\eta}\mathbf{S}^{\tilde{k}}\mathbf{G}^{-1}\mathbf{e} - \left(\frac{\mathbf{G}}{2} + \mathbf{D}^{\tilde{k}}\right)\mathbf{G}^{-1}\mathbf{h},\qquad(3)$$

with

$$\mathbf{C} = \mathbf{S}^{\tilde{k}} \mathbf{G}^{-1} \mathbf{N}^{k} + \left(\frac{\mathbf{G}}{2} + \mathbf{D}^{\tilde{k}}\right) \mathbf{G}^{-1} \left(\frac{\mathbf{G}}{2} - \mathbf{D}^{k}\right), \quad (4)$$

where $\tilde{k} := k + 0.4ik^{1/3}a^{-2/3}$, and a is a suitable average of the radii of curvature along γ .

The FDS scheme is based on the separation of the system matrix **C** into a main part for which some fast algebra arithmetic is available, and a compressible rank-deficient reminder. The main part arises from the discretization of an equivalent circular problem generating a matrix C_c that entails the computation of the same operators appearing in (4) on a circular curve γ_c of the same perimeter as γ . Finally, $C_e := C - C_c$ represents the remaining extracted part that exhibits a rank deficiency.

Because C_c is built out of products and linear combination of matrices with structured circularity, generically designated as O_c in the following, it can be stored an multiplied to a vector in quasi-linear complexity. In particular, when discretized with order one functions, O_c is circulant, which enables fast matrix operations through the fast Fourier transform (FFT). However, for higher basis order p, these matrices are no longer circulant. To recover fast manipulations of O_c , we organize the matrix elements into a matrix composed of circulant blocks

$$\mathbf{O_{c}} = \begin{bmatrix} \mathbf{O}_{c}^{11} & \mathbf{O}_{c}^{12} & \dots \\ \vdots & \ddots & \\ \mathbf{O}_{c}^{p1} & & \mathbf{O}_{c}^{pp} \end{bmatrix}, \qquad (5)$$

where each block \mathbf{O}_{c}^{ij} is internally circulant. Despite not being exactly circulant, with suitable generalization, this structure can be exploited to enable fast matrix operations via FFT operations performed at a block level. The main idea stems from the possibility to diagonalize \mathbf{O}_{c} in quasi linear time with the following expression

$$\mathbf{K}_{(p,n)}^{T} \tilde{\mathbf{F}}_{p}^{*} \mathbf{O}_{c} \tilde{\mathbf{F}}_{p} \mathbf{K}_{(p,n)} = \begin{bmatrix} \mathbf{B}^{11} & 0 & \dots \\ \vdots & \ddots & \\ 0 & \mathbf{B}^{nn} \end{bmatrix}, \quad (6)$$

where $\mathbf{B}^{ij} \in \mathbb{C}^{p \times p}$, $\mathbf{K}_{(p,n)}$ is the commutation matrix, n is the number of vertices, and $\tilde{\mathbf{F}}_p = \mathbf{I}_p \otimes \mathbf{F}$, with \mathbf{F} being the discrete Fourier transform matrix, \otimes the Kronecker product and \mathbf{I}_p an identity matrix with p diagonal elements. The matrix $\tilde{\mathbf{F}}_p$ can be implicitly manipulated using the FFT. Consequently, by noting also that $\mathbf{K}_{(p,n)}$ benefits from permutation matrix properties (such as $\mathbf{K}_{(p,n)}^{-1} = \mathbf{K}_{(p,n)}^{\mathrm{T}}$).

To finalize the scheme, the extracted part is compressed into a non-hierarchical low-rank form $\mathbf{C}_e \approx \mathbf{U}\mathbf{V}^T$, and the inversion of **C** is performed through the Woodbury identity

$$\mathbf{C}^{-1} = \mathbf{C}_c^{-1} - \mathbf{C}_c^{-1} \mathbf{U} \left(\mathbf{I} + \mathbf{V}^T \mathbf{C}_c^{-1} \mathbf{U} \right)^{-1} \mathbf{V}^T \mathbf{C}_c^{-1}, \quad (7)$$

which can efficiently computed by exploiting the low-rank form and the fast algebra operations described above.

IV. NUMERICAL RESULTS

To validate the new direct solution scheme, it is applied on an ellipse of with a semi-major axis $a = \cosh(1)$ and a semi-minor axis $b = \sinh(1)$. The numerical results reported in Fig. 1 and Fig. 2 show (i) for an appropriate compression threshold ε the proposed scheme delivers high accuracy solution and (ii) that increasing the order p does not

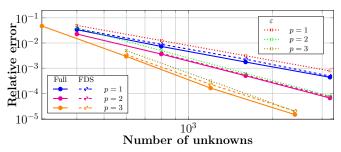


Fig. 1: Current accuracy for $k = 40 \text{ m}^{-1}$, where ε is the compression threshold set on $\mathbf{C}_e \approx \mathbf{U}\mathbf{V}^{\mathrm{T}}$.

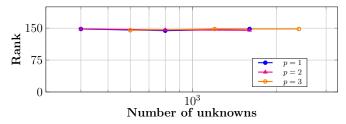


Fig. 2: ε -rank of $\mathbf{C}_e \approx \mathbf{U}\mathbf{V}^{\mathrm{T}}$ for $\varepsilon = 10^{-2}$ and $k = 40 \text{ m}^{-1}$.

significantly impact the ε -rank (and compressibility) of the extracted part This shows that our FDS scheme is capable of preserving the better accuracies of high order schemes, while maintaining a reduced complexity, and simplicity of the compressed representation.

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