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Comparing Infinitary Systems for Linear Logic with Fixed Points

Anupam Das ✉

School of Computer Science, University of Birmingham, UK

Abhishek De ✉

School of Computer Science, University of Birmingham, UK

Alexis Saurin ✉

IRIF, CNRS, Université Paris Cité, France

INRIA π^3 , Paris, France

Abstract

Extensions of Girard’s *linear logic* by least and greatest fixed point operators (μ MALL) have been an active field of research for almost two decades. Various proof systems are known *viz.* finitary and non-wellfounded, based on explicit and implicit (co)induction respectively. In this paper, we compare the relative expressivity, at the level of provability, of two complementary infinitary proof systems: finitely branching non-wellfounded proofs (μ MALL $^\infty$) vs. infinitely branching well-founded proofs (μ MALL $_{\omega, \infty}$). Our main result is that μ MALL $^\infty$ is strictly contained in μ MALL $_{\omega, \infty}$.

For inclusion, we devise a novel technique involving infinitary rewriting of non-wellfounded proofs that yields a wellfounded proof in the limit. For strictness of the inclusion, we improve previously known lower bounds on μ MALL $^\infty$ provability from Π_1^0 -hard to Σ_1^1 -hard, by encoding a sort of Büchi condition for Minsky machines.

2012 ACM Subject Classification Theory of computation \rightarrow Linear logic; Theory of computation \rightarrow Proof theory

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1 Introduction

Fixed point logics have garnered significant interest from computational logicians over the years. In particular the extension of languages by least and fixed point operators, μ and ν respectively, has been comprehensively explored in modal logic [23, 38], arithmetic [22, 31], first-order logic [32, 14, 1], and linear logic [36, 7].

In terms of reasoning, least fixed points allow for *inductive* proof, while greatest fixed points, being dual to least fixed points, allow for *coinductive* proof. Naturally, the corresponding (co)induction proof rules must incorporate an arbitrary (co)invariant, a fundamental barrier to both proof theoretic investigations and (automated) proof search. To this end various alternative proof methods have been proposed, incorporating “infinitary behaviour” at the level of proofs:

- *Infinitary branching* (but wellfounded) systems have origins in the proof theory of arithmetic [10] and have been applied to numerous areas, including the modal μ -calculus [24, 37] and extensions of Kleene algebra [34, 27].
- More recently, *non-wellfounded* (but finitely branching) and *cyclic* proofs have been proposed for (co)inductive reasoning, originating in the modal μ -calculus [33, 2] and applied to theories of arithmetic [8, 9], type systems [26, 12, 11], and linear logic [36, 19, 6].



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A natural question to ask is whether all these approaches prove the same theorems or not. In this work, we examine this question in the setting of linear logic, μMALL . In particular, we compare the non-wellfounded system μMALL^∞ from [6] with a wellfounded infinitary branching system $\mu\text{MALL}_{\omega,\infty}$ inspired by [16]. This builds on previous work [13] that focused on comparing the various *finitary* systems for μMALL . Our main result is that $\mu\text{MALL}_{\omega,\infty}$ proves strictly more theorems than μMALL^∞ :

► **Theorem 1.** $\mu\text{MALL}^\infty \subsetneq \mu\text{MALL}_{\omega,\infty}$

Organisation and contributions. In Section 2, we recall the language of μMALL and present its various systems, in particular μMALL^∞ and $\mu\text{MALL}_{\omega,\infty}$. In Section 3 we prove the inclusion part of Theorem 1. Namely, we give a coinductive translation from μMALL^∞ to $\mu\text{MALL}_{\omega,\infty}$, and then exploit the correctness condition of μMALL^∞ to deduce that the image of this translation is wellfounded, Theorem 14. In Section 4 we reduce a “Büchi condition” for Minsky machines to μMALL^∞ provability, Proposition 32, implying the latter is Σ_1^1 -hard by [3], Theorem 33, yielding the strictness part of Theorem 1. Finally in Section 5 we give a Π_2^1 upper bound for μMALL^∞ , Theorem 35, by appealing to analytic determinacy of its “proof search game”. We present conclusions in Section 6. Our results are summarised in Figure 1.

Notation. For a formula φ we write $\varphi^n(x)$ for $\overbrace{\varphi(\varphi(\dots(\varphi(x))\dots))}^n$. We shall also frequently suppress or explicitly indicate variables as convenient, e.g. we often identify φ and $\varphi(x)$, using the latter when we want to distinguish (some occurrences of) the variable x . When working with binders, e.g. μ and ν , we shall employ a standard convention of using dots, e.g. $\mu x.\varphi$ or $\nu x.\psi$ to signify that the μ or ν binds as far as possible to the right.

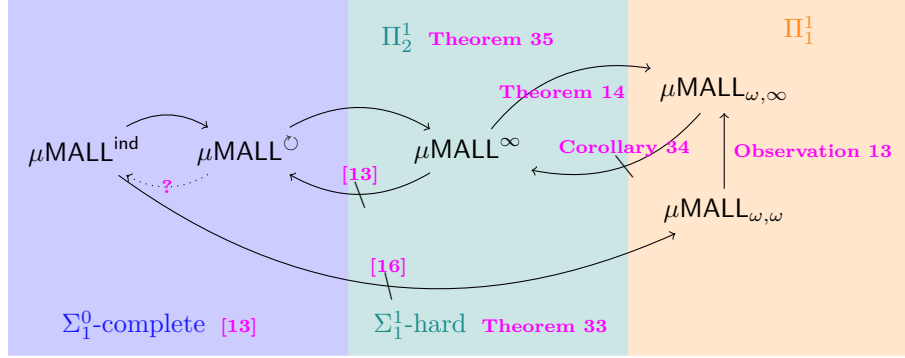
A note on (effective) descriptive set theory. In this work, we shall assume some familiarity with notions from (effective) descriptive set theory, namely the classes of the analytical hierarchy, Π_1^1 , Σ_1^1 , Π_2^1 etc. All necessary notions can be found in well-known textbooks like [29, 35] and via online resources.

2 Background

Linear logic, introduced by Girard [20], refines usual disjunction and conjunction into two orthogonal pairs of connectives: the *multiplicatives* \wp, \otimes and the *additives* $\oplus, \&$. Together with their units $\perp, \mathbf{1}, \mathbf{0}, \top$ respectively, the resulting logic MALL (“multiplicative additive linear logic”) is given in Figure 2 (colours may be ignored for now). Note here that the rules operate on *sequents*, which are finite multisets of formulas: commas denote multiset union, and set braces are omitted. Sequents are “one-sided”, i.e. Γ should be read as $\vdash \Gamma$.

MALL is distinguished from usual logics by its notable absence of structural rules for the multiplicatives: $\varphi \wp \varphi \vdash \varphi$ and $\mathbf{0} \vdash \varphi$ are not always satisfied. This is why sequents must be multisets (or lists), not sets. In a sense linear logic can be seen as a “symmetrisation” of intuitionistic logic, which only controls structural rules on one side of an implication, resulting in a sort of constructive logic that nonetheless enjoys a form of De Morgan duality, hence admitting the one-sided presentation herein.

This lack of structural behaviour is crucially what leads to the high complexity of provability in the presence of “exponentials” in usual linear logic or, in this work, in the presence of fixed points. See [13, Sect. 2] for some further discussion on the peculiarities of linear logic with fixed points compared to other similar logics.



■ **Figure 1** Relationships between systems in this work. Solid arrows \rightarrow denote inclusion, dashed arrows denote conservative extensions, negated arrows \nrightarrow denote non-inclusion.

In the remainder of this section, we shall introduce the language of (multiplicative additive) linear logic with fixed points, and present the systems investigated in this work.

2.1 μ MALL preliminaries

Let us fix two disjoint countable sets of propositional constants $\mathcal{A} = \{a, b, \dots\}$ and variables $\mathcal{V} = \{x, y, \dots\}$.

► **Definition 2** ((Pre)-formulas). μ MALL pre-formulas are given by the following grammar.

$$\varphi, \psi ::= \mathbf{0} \mid \top \mid \perp \mid \mathbf{1} \mid a \mid a^\perp \mid x \mid \varphi \wp \psi \mid \varphi \otimes \psi \mid \varphi \oplus \psi \mid \varphi \& \psi \mid \mu x \varphi \mid \nu x \varphi$$

where $a \in \mathcal{A}$, $x \in \mathcal{V}$, and μ, ν bind the variable x in φ . Free and bound variables, and capture-avoiding substitution are defined as usual. The subformula ordering is denoted \leq . When a pre-formula is closed (i.e. has no free variable), we simply call it a **formula**.

$\mu x \varphi$ and $\nu x \varphi$ are intended to denote the least and greatest fixed points of the operator $\lambda x \varphi$ in an appropriate semantics (cf., e.g., [16]). a^\perp is intended to be the negation of a . Note that, since variables have no negated instances, positivity of fixed point operators is implicit and no further condition is required.

Thanks to De Morgan duality in linear logic we may extend negation to all (pre-)formulas as a meta-operation, in the same way as for classical logic:

► **Definition 3.** **Negation** of a pre-formula φ , denoted φ^\perp , is the unique involution that satisfies the following.

$$\begin{aligned} (\mathbf{0})^\perp &= \top; & (\perp)^\perp &= \mathbf{1}; & a^{\perp\perp} &= a; & x^\perp &= x; \\ (\varphi \wp \psi)^\perp &= \varphi^\perp \otimes \psi^\perp; & (\varphi \oplus \psi)^\perp &= \varphi^\perp \& \psi^\perp; & (\mu x \varphi)^\perp &= \nu x \varphi^\perp. \end{aligned}$$

As expected, μ and ν are dual to each other; note also that fixed point variables are simply invariant under negation.

The first systems for μ MALL, here called μ MALL^{ind}, incorporate explicit (co)induction rules for the fixed points, inspired by similar developments in other fixed point logics like the μ -calculus [23, 39]. In our one-sided setting, μ MALL^{ind} is formally the extension of the system MALL in Figure 2 by:

$$\frac{\Gamma, \varphi(\mu x \varphi)}{\Gamma, \mu x \varphi} (\mu) \quad \frac{\psi^\perp, \varphi(\psi) \quad \Gamma, \psi}{\Gamma, \nu x \varphi} (\text{coind}) \quad (1)$$

Structural rules	$\frac{}{\varphi, \varphi^\perp} \text{ (id)} \quad \frac{\Gamma_1, \varphi \quad \Gamma_2, \varphi^\perp}{\Gamma_1, \Gamma_2} \text{ (cut)}$
Logical rules	$\frac{\Gamma, \varphi_1, \varphi_2}{\Gamma, \varphi_1 \wp \varphi_2} \text{ (}\wp\text{)} \quad \frac{\Gamma_1, \varphi_1 \quad \Gamma_2, \varphi_2}{\Gamma_1, \Gamma_2, \varphi_1 \otimes \varphi_2} \text{ (}\otimes\text{)} \quad \frac{\Gamma, \varphi_i}{\Gamma, \varphi_1 \oplus \varphi_2} \text{ (}\oplus_i\text{)} \quad \frac{\Gamma, \varphi_1 \quad \Gamma, \varphi_2}{\Gamma, \varphi_1 \& \varphi_2} \text{ (}\&\text{)}$
Logical rules (units)	$\frac{}{1} \text{ (}\mathbf{1}\text{)} \quad \frac{\Gamma}{\Gamma, \perp} \text{ (}\perp\text{)} \quad \frac{}{\Gamma, \top} \text{ (}\top\text{)} \quad \text{No rule for } \mathbf{0}$

■ **Figure 2** Inference rules for MALL, where $i \in \{1, 2\}$. Purple formulas in premiss(es) and conclusion are called *auxiliary* and *principal* respectively.

These rules are inspired by the second-order encoding of fixed points: $\nu x\varphi = \exists x((x \multimap \varphi) \otimes \varphi)$. Proofs of $\mu\text{MALL}^{\text{ind}}$ are defined as usual, but the system plays little role in this work; we present it only for context. At the level of their rules, the other systems considered in this work will only differ from $\mu\text{MALL}^{\text{ind}}$ in their ν -rules, using alternatives for (coind). All systems we consider will have the (μ) rule above (differing from the development in [16]).

2.2 Non-wellfounded system μMALL^∞

The standard “non-wellfounded” system for μMALL , here called μMALL^∞ , was introduced in [6], building on earlier work for the fragment without multiplicatives [36, 19]. It is an adaptation of systems for the modal μ -calculus from [33, 37] to the setting of linear logic.

► **Definition 4** (μMALL^∞ pre-proofs). *The rules of μMALL^∞ extend MALL by:*

$$\frac{\Gamma, \varphi(\mu x\varphi)}{\Gamma, \mu x\varphi} \text{ (}\mu\text{)} \quad \frac{\Gamma, \varphi(\nu x\varphi)}{\Gamma, \nu x\varphi} \text{ (}\nu\text{)} \quad (2)$$

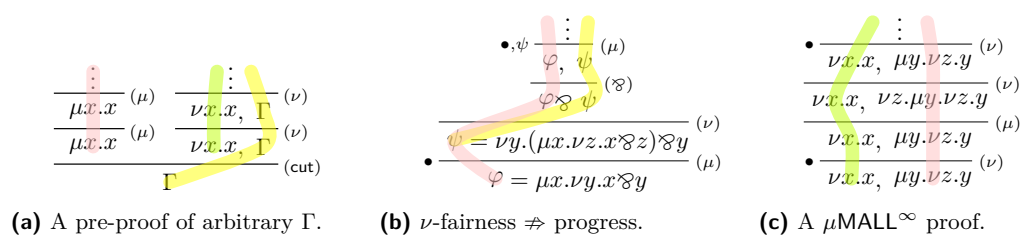
A **pre-proof** of μMALL^∞ , denoted P, P', \dots , is a possibly non-wellfounded tree generated from the inference rules of μMALL^∞ .

Arbitrary non-wellfounded derivations may be fallacious, hence the affectation “pre-” above. Thus bona fide “proofs” must further satisfy a standard correctness criterion from non-wellfounded proof theory. At the same time the progressing criterion distinguishes the two fixed points, which have the same rules in Equation (2).

► **Definition 5** (Ancestry). *A formula occurrence φ in the conclusion of a rule instance is a **immediate ancestor** of an occurrence ψ in a premiss if they have the same colour, as typeset in Figure 2 and Equation (2). If φ and ψ are in a context $\Gamma, \Gamma_1, \Gamma_2$, we furthermore require that they are the same occurrences in the premiss and the conclusion.*

► **Remark 6** (On occurrences in multisets). Note that, in the definition above, we are implicitly assuming that the data structure of a sequent allows us to distinguish different occurrences of the same formula. This is a standard convention in structural proof theory that avoids low-level peculiarities of working with lists (necessitating additional exchange/permutation rules). To be clear, “sequents-as-multisets” should be construed as a sets of occurrences of formulas, e.g. by assigning a name to each occurrence. This is often made explicit in, e.g., type systems with explicit term annotations, but we gloss over this formality in favour of lightening the exposition.

► **Definition 7** (Threads and proof). *Given a branch B through a pre-proof, a **thread** is a maximal path in the graph of immediate ancestry of B . A thread is **progressing** if it has a minimal infinitely often principal formula, called **progress points**, (under \leq) that is a ν -formula. A pre-proof is a **proof** if each of its infinite branches has a progressing thread.*



■ **Figure 3** Some μMALL^∞ pre-proofs. We use identifiers like “•” to describe infinite proofs in a finite manner. Progressing, non-progressing, and “stable” threads are indicated in green, red, and yellow respectively.

► **Example 8.** In Figure 3 we give several examples of (pre-)proofs. Figure 3a is a pre-proof of an arbitrary sequent Γ , exemplifying the inconsistency of arbitrary pre-proofs. It is *not* a proof because the left infinite branch has no progressing thread. Figure 3b is also not a proof, despite its only infinite branch having infinitely many (ν) -steps. This is because the thread indicated in red has the μ -formula φ as its minimal infinitely often principal formula, not the ν -formula ψ . Note that every other thread is eventually stable on ψ (and hence not progressing). Finally Figure 3c is indeed a μMALL^∞ proof, as its only infinite branch has a progressing thread on $\nu x x$. (It also happens to have a non-progressing red thread on $\mu y \nu z y$.)

In this work we shall make crucial use of a (nontrivial) cut-elimination result for μMALL^∞ :

► **Theorem 9** ([6, 5]). *Every provable μMALL^∞ sequent has a proof without the (cut) rule.*

Finally, we briefly describe an important subsystem of μMALL^∞ where the underlying proof trees are *regular*.

► **Definition 10.** *A μMALL^∞ pre-proof is **cyclic** (a.k.a. **regular**) if it has finitely many distinct sub-pre-proofs. μMALL° is the class of formulas with cyclic μMALL^∞ .*

For instance the pre-proofs Figure 3a and Figure 3c are indeed regular whereas Figure 3b is not since at each iteration of the bullet the sequent has an extra occurrence of ψ (which is thenceforth non-principal). Like $\mu\text{MALL}^{\text{ind}}$, the circular system μMALL° will not play a significant role in this work.

► **Remark 11** (On exponentials). For the reader familiar with the exponentials of linear logic, it would be reasonable to ask about the expressivity of extensions of $\mu\text{MALL}^{\text{ind}}$, μMALL° , μMALL^∞ by the exponentials $!, ?$. It turns out that the resulting system is fully conservative over $\mu\text{MALL}^{\text{ind}}$, μMALL° , μMALL^∞ respectively, thanks to the fact that exponentials can be “coded” by fixed point formulas, as noticed by Baelde in [4]. On the other hand, our previous work [13] showed the systems $\mu\text{MALL}^{\text{ind}}$ and μMALL° are already Σ_1^0 -complete, matching the complexity of full linear logic with exponentials [28].

2.3 A well-founded system $\mu\text{MALL}_{\omega, \infty}$

One of the main points of this work is to compare the non-wellfounded system μMALL^∞ with an orthogonal notion of infinite proof: well-founded but infinitely branching. Such systems are common in proof theory and mathematical logic [10, 30] and have been compared to non-wellfounded systems in other settings [37]. To this end, we consider an “ ω -rule” for ν , motivated by continuous models, e.g. the phase semantics of [16].

► **Definition 12.** $\mu\text{MALL}_{\omega,\infty}$ is the extension of MALL by the rules:

$$\frac{\Gamma, \varphi(\mu x\varphi)}{\Gamma, \mu x\varphi}^{(\mu)} \quad \frac{\Gamma, \top \quad \Gamma, \varphi(\top) \quad \Gamma, \varphi(\varphi(\top)) \quad \dots}{\Gamma, \nu x\varphi}^{(\omega)} \quad (3)$$

Proofs of $\mu\text{MALL}_{\omega,\infty}$ are defined as usual: they are well-founded (possibly infinite) trees generated by the rules of $\mu\text{MALL}_{\omega,\infty}$.

The (ω) rule is inspired by the *inflationary* construction of fixed points, $\nu x\varphi = \bigcap_{\alpha \in \text{Ord}} \varphi^\alpha(\top)$. It is implicit in $\mu\text{MALL}_{\omega,\infty}$ that the ν operator is in a sense continuous, closing at ordinal ω , like in the models of phase semantics of [16]. In that work, a similar ω -branching system $\mu\text{MALL}_{\omega,\omega}$ has been proposed for μMALL but it further restricts μ -rules to:

$$\frac{\Gamma, \varphi^n(\mathbf{0})}{\Gamma, \mu x\varphi}^{(\mu^n)}$$

[16] shows that $\mu\text{MALL}_{\omega,\omega}$ is actually quite weak and does not even contain $\mu\text{MALL}^{\text{ind}}$. Retaining the usual (μ) rule in $\mu\text{MALL}_{\omega,\infty}$ is rather inspired by the *signatures* (a.k.a. *markings* or *assignments*) from [33, 11, 17]. In this work, we shall see that $\mu\text{MALL}_{\omega,\infty}$ in fact contains all the systems we have presented. In particular, note that, since there is no rule for $\mathbf{0}$ in MALL, we immediately have:

► **Observation 13.** $\mu\text{MALL}_{\omega,\omega} \subseteq \mu\text{MALL}_{\omega,\infty}$

3 Inclusion of μMALL^∞ in $\mu\text{MALL}_{\omega,\infty}$

In this section, we show one of our main results:

► **Theorem 14** (Simulating infinite height by infinite width). $\mu\text{MALL}^\infty \subseteq \mu\text{MALL}_{\omega,\infty}$.

Note in particular the stark contrast with the system $\mu\text{MALL}_{\omega,\omega}$ from [16], which does not even contain $\mu\text{MALL}^{\text{ind}}$, cf. Figure 1. To prove this result, throughout this section we work only with cut-free μMALL^∞ proofs, without loss of generality by Theorem 9. Furthermore, to prevent issues with productivity along a coinductive definition, we will employ a standard technique (e.g.[30]) of “bootstrapping” our μMALL systems with an explicit repetition rule

$\frac{\Gamma}{\Gamma} (=)$.¹ While this does affect the notion of pre-proof it does not affect the notion of *proof*

in μMALL^∞ : the progressing condition implies that no infinite branch can have a tail of repetitions, and so $(=)$ steps can be contracted while preserving closedness (each sequent still concludes a step).

3.1 Projections

In order to prove Theorem 14 we first need to define notion of “proof projection” that allows us to extract from a μMALL^∞ proof its “finite approximations”. Throughout this section we will consider sequents $\Gamma = \Gamma(\psi_1, \dots, \psi_k)$ where some occurrences of ψ_1, \dots, ψ_k in Γ are distinguished. Note that the distinguished occurrences of, say ψ_i , may include some, none,

¹ Note that this addition could be avoided by using “explicit” approximants à la [37, 16].

or all of the occurrences of ψ_i in Γ . This notation allows for distinguished ψ_i occurrences to be subformulas of formulas in Γ , and also for some ψ_i and ψ_j to be the same formula when $i \neq j$. For $\vec{\psi} = (\nu x_1 \varphi_1, \dots, \nu x_k \varphi_k)$, an **assignment** is simply a list $\vec{n} = (n_1, \dots, n_k) \in \omega^k$. We will write $\vec{\psi}^{\vec{n}} := (\varphi_1^{n_1}(\top), \dots, \varphi_k^{n_k}(\top))$, the list obtained by *assigning* each n_i to each ψ_i .

► **Definition 15 (Projections)**. For a pre-proof P of $\Gamma(\vec{\psi})$, where $\vec{\psi} = (\nu x_1 \varphi_1, \dots, \nu x_k \varphi_k)$, and an assignment $\vec{n} = (n_1, \dots, n_k) \in \omega^k$, we define the **projection** $P(\vec{n})$ a pre-proof of $\Gamma(\vec{\psi}^{\vec{n}})$ by coinduction on P as follows:

1. If P ends with a step ρ for which no distinguished formula occurrence is principal,

$$\frac{\frac{P_1}{\Gamma_1(\vec{\psi})} \quad \dots \quad \frac{P_m}{\Gamma_m(\vec{\psi})}}{\Gamma(\vec{\psi})}^{(\rho)}, \text{ then } P(\vec{n}) := \frac{\frac{P_1(\vec{n})}{\Gamma_1(\vec{\psi}^{\vec{n}})} \quad \dots \quad \frac{P_m(\vec{n})}{\Gamma_m(\vec{\psi}^{\vec{n}})}}{\Gamma(\vec{\psi}^{\vec{n}})}^{(\rho)}.$$

2. If P ends with a step for which some distinguished formula occurrence is principal,

$$P(0, \vec{n}) := \frac{}{\top, \Gamma(\top, \vec{\psi}^{\vec{n}})}^{(\top)}$$

$$\frac{\frac{P'}{\varphi(\nu x \varphi), \Gamma(\nu x \varphi, \vec{\psi})}}{\nu x \varphi, \Gamma(\nu x \varphi, \vec{\psi})}^{(\nu)}, \text{ then } P(n+1, \vec{n}) := \frac{\frac{P'(n, n+1, \vec{n})}{\varphi(\varphi^n(\top)), \Gamma(\nu x \varphi, \vec{\psi})}}{\varphi^{n+1}(\top), \Gamma(\varphi^{n+1}(\top), \vec{\psi}^{\vec{n}})}^{(=)}$$

Note that, in the final case of the definition above, the length of the assignment may increase if $\nu x \varphi$ distinguishes multiple occurrences in the sequent. This is why, even though we shall only ever use projections on a single formula later, we must make the definition above more general. This is also a barrier towards any arguments by explicit induction on assignments; e.g. Lemma 16 later is demonstrated rather by an argument by infinite descent, a now standard leitmotif of non-wellfounded proof theory.

3.2 Properties of branches along projections

For μMALL^∞ pre-proofs P we associate to each of its (maximal) branches B its **induced** branch $B(\vec{n})$ in $P(\vec{n})$ in the expected way. Formally $B(\vec{n})$ is defined by coinduction on B , following the cases of Definition 15:

1. $\left(\frac{B_i}{\Gamma_i(\vec{\psi})}^{(\rho)} \right) (\vec{n}) := \frac{B_i(\vec{n})}{\Gamma_i(\vec{\psi}^{\vec{n}})}^{(\rho)}$
2. $\left(\frac{B'}{\frac{\varphi(\nu x \varphi), \Gamma(\nu x \varphi, \vec{\psi})}{\nu x \varphi, \Gamma(\nu x \varphi, \vec{\psi})}^{(\nu)}} \right) (0, \vec{n}) := \frac{}{\top, \Gamma(\top, \vec{\psi}^{\vec{n}})}^{(\top)}$
 $\left(\frac{B'}{\frac{\varphi(\nu x \varphi), \Gamma(\nu x \varphi, \vec{\psi})}{\nu x \varphi, \Gamma(\nu x \varphi, \vec{\psi})}^{(\nu)}} \right) (n+1, \vec{n}) := \frac{B'(n, n+1, \vec{n})}{\varphi(\varphi^n(\top)), \Gamma(\varphi^{n+1}(\top), \vec{\psi}^{\vec{n}})}^{(=)}$

Clearly the map $B \mapsto B(\vec{n})$ from branches of P to branches of $P(\vec{n})$ is surjective. It is also clear that if B is finite then so is $B(\vec{n})$. The remainder of this section is devoted to establishing a stronger property: as long as B is finite or progressing, so is $B(\vec{n})$. To this end we need the following important properties of the action of projections on threads:

► **Lemma 16** (Projections on progressing threads terminate). *For a μMALL^∞ pre-proof P of $\Gamma(\nu x\varphi, \vec{\psi})$, a branch B of P along which $\nu x\varphi$ extends to a progressing thread, and $n \in \omega$, the branch $B(n, \vec{n})$ is finite.*

Proof sketch. Suppose otherwise and take the (maximal) sequence $(n_i)_{i < \alpha \leq \omega}$ of numbers assigned to the progressing thread $\nu x\varphi$ in the construction of $B(n, \vec{n})$ above. By local inspection notice that $(n_i)_{i < \alpha}$ is monotone non-increasing, and furthermore strictly decreases whenever $\nu x\varphi$ is principal. Thus α must be finite and bounds the length of $B(n, \vec{n})$. ◀

We also have that projections “lower threads” disjoint from their distinguished formulas, by inspection of the description of $B(\vec{n})$ above:

► **Lemma 17** (Projections preserve disjoint threads). *Let P be a pre-proof of $\Gamma(\vec{\psi})$ and B a branch of P with $B(\vec{n})$ infinite. If B is progressing then so is $B(\vec{n})$. Moreover, if $(\varphi_i)_{i < \omega}$ is a progressing thread² along B disjoint from all $\vec{\psi}$ with progress points $(\varphi_{i_j})_{j < \omega}$, then $(\varphi_i)_{i < \omega}$ is also progressing in $B(\vec{n})$ with progress points $(\varphi_{i_j})_{j < \omega}$.*

Note that $B(\vec{n})$ may still be finite when B is infinite in case there is another progressing thread along B on a distinguished formula, cf. Lemma 16. Recalling that the map $B \mapsto B(\vec{n})$ from branches of P to branches of $P(\vec{n})$ is surjective, we have immediately from Lemma 17:

► **Proposition 18** (Projections on proofs are proofs). *If P is a μMALL^∞ proof, so is $P(\vec{n})$.*

3.3 The ω -translation

We need to give a translation from μMALL^∞ proofs to $\mu\text{MALL}_{\omega, \infty}$ ones. We break this up into two steps: first we give the translation, and then prove that the image of this translation is wellfounded. To this end we shall refer to “pre-proofs” of $\mu\text{MALL}_{\omega, \infty}$ too, which may be both infinitely wide and infinitely deep.

► **Definition 19** (ω -translation). *For μMALL^∞ pre-proofs P , we define the $\mu\text{MALL}_{\omega, \infty}$ pre-proof P^ω by coinduction on P as follows:*

1. if $P = \frac{\frac{P_1}{\Gamma_1} \quad \dots \quad \frac{P_k}{\Gamma_k}}{\Gamma} (\rho)$ with $\rho \neq \nu$, then $P^\omega := \frac{\frac{P_1^\omega}{\Gamma_1} \quad \dots \quad \frac{P_k^\omega}{\Gamma_k}}{\Gamma} (\rho)$
(i.e. \cdot^ω commutes with ρ when $\rho \neq \nu$).
2. Otherwise, if $P = \frac{\frac{P'}{\Gamma, \varphi(\nu x\varphi)}}{\Gamma, \nu x\varphi} (\nu)$ then $P^\omega := \frac{\frac{\frac{P'(0)^\omega}{\Gamma, \top} \quad \frac{P'(1)^\omega}{\Gamma, \varphi(\top)}}{\Gamma, \top} (\top)}{\Gamma, \nu x\varphi} (\omega)$.

Note that, whichever rule P ends with, the translation above is *productive* (it prints a rule for each coinductive case) and so P^ω is indeed well-defined by coinduction (just like projections and induced branches before). Note also that the translation is defined for arbitrary pre-proofs, not only proofs. Indeed a pre-proof P may be sent to a non-wellfounded pre-proof P^ω by the translation, e.g. if P has no (ν) step, then already $P^\omega = P$. In particular, simply having infinitely many (ν) steps along every infinite branch of P does not suffice to imply wellfoundedness of P^ω . Let us see some examples to illustrate this:

² Recall that P is cut-free, so we may assume the thread starts at the root.

► **Observation 22.** *If B is finite, then so is $B^{\vec{n}}$.*

This follows by induction on the length of B . From here we are able to show:

► **Lemma 23.** *For P a pre-proof, $B^{\vec{n}}$ a branch of P^ω : if B is progressing then $B^{\vec{n}}$ is finite.*

Formally this follows by induction on the height of the first progress point of a progressing thread along B , following the definition of branches $B^{\vec{n}}$. During the argument we must often appeal to the properties of branches along projections from Section 3.2. Of course from here our main result immediately follows:

Proof of Theorem 14. Let P be a μMALL^∞ proof. By Lemma 23 above, all branches of its ω -translation P^ω are finite. Thus P^ω is indeed wellfounded and so a proof of $\mu\text{MALL}_{\omega,\infty}$. ◀

4 μMALL^∞ is Σ_1^1 -hard

A natural question to ask now is if $\mu\text{MALL}_{\omega,\infty}$ can be embedded in μMALL^∞ . [37] shows that the ω -branching calculus of the modal μ -calculus can be embedded in its corresponding non-wellfounded calculus. The argument crucially depends on the fact that any proof of a formula φ has finitely many distinct sequents (modulo identifying approximations); however, such a condition does not hold in μMALL due to the absence of structural rules. In fact, we prove that the inclusion result of the previous section, Theorem 14, is strict.

In order to do so we will give a Σ_1^1 lower bound for μMALL^∞ that is incompatible with the natural Π_1^1 upper bound for $\mu\text{MALL}_{\omega,\infty}$. To this end, we encode a Büchi' condition for Minsky machines in terms of μMALL^∞ provability. This significantly improves a Π_1^0 lower bound from previous work [13], which was proved by reduction from non-halting of Minsky machines.

Throughout this section we shall write a^n for $\overbrace{a \wp \dots \wp a}^n$ (which is equivalent to $a^n(\perp)$).

► **Definition 24.** *A Minsky machine \mathcal{M} is a tuple (Q, r_1, r_2, I) where Q is a finite set of states, r_1, r_2 are two registers and I is a set of instructions of the form $\text{INC}(p, r_i, q)$ or $\text{JZDEC}(p, r_i, q_0, q_1)$, for $p, q, q_0, q_1 \in Q$ and $i \in \{1, 2\}$, that manipulate the current state and the contents of the registers.*

The operational semantics of \mathcal{M} is given by its configuration graph, whose vertices are configurations, of form $\langle q, a, b \rangle \in Q \times \mathbb{N} \times \mathbb{N}$, and whose edges are induced from I by:

$$\begin{array}{ll} \langle p, a, b \rangle \xrightarrow{\text{INC}(p, r_1, q)} \langle q, a + 1, b \rangle & \langle p, a, b \rangle \xrightarrow{\text{INC}(p, r_2, q)} \langle q, a, b + 1 \rangle \\ \langle p, 0, b \rangle \xrightarrow{\text{JZDEC}(p, r_1, q_0, q_1)} \langle q_0, 0, b \rangle & \langle p, a, 0 \rangle \xrightarrow{\text{JZDEC}(p, r_2, q_0, q_1)} \langle q_0, a, 0 \rangle \\ \langle p, a + 1, b \rangle \xrightarrow{\text{JZDEC}(p, r_1, q_0, q_1)} \langle q_1, a, b \rangle & \langle p, a, b + 1 \rangle \xrightarrow{\text{JZDEC}(p, r_2, q_0, q_1)} \langle q_1, a, b \rangle \end{array}$$

A run is a maximal path in the configuration graph.

► **Theorem 25 ([3]).** *Given a Minsky machine \mathcal{M} and a state q_0 , checking whether there exists an infinite run starting from $\langle q_0, 0, 0 \rangle$ that visits q_0 infinitely often is Σ_1^1 -hard.*

For the rest of the section, let us fix a Minsky machine $\mathcal{M} = (Q, r_1, r_2, I)$. Construe $\{a, b, z_a, z_b\} \cup Q$ as a set of propositional constants (assuming $\{a, b, z_a, z_b\} \cap Q = \emptyset$) and $\{x, y\}$ as a set of variables. We use a and z_a (respectively, b and z_b) to represent the contents of the register r_1 (respectively, r_2). Define $\text{parity} : Q \rightarrow \{x, y\}$ by $\text{parity}(q) = x$ if $q = q_0$ and $\text{parity}(q) = y$ otherwise. Define the following:

$$\begin{aligned}
[\text{INC}(p, r_1, q)] &:= p^\perp \otimes (q \wp a \wp \text{parity}(q)) \\
[\text{INC}(p, r_2, q)] &:= p^\perp \otimes (q \wp b \wp \text{parity}(q)) \\
[\text{JZDEC}(p, r_1, q, q')] &:= p^\perp \otimes (((\text{parity}(q) \wp q) \& z_a) \oplus (a^\perp \otimes (\text{parity}(q') \wp q'))) \\
[\text{JZDEC}(p, r_2, q, q')] &:= p^\perp \otimes (((\text{parity}(q) \wp q) \& z_b) \oplus (b^\perp \otimes (\text{parity}(q') \wp q'))) \\
\psi &:= \mu y. \left(\bigoplus_{\text{ins} \in I} [\text{ins}] \right) \\
\varphi &:= \psi(\nu x. \psi)
\end{aligned}$$

Finally, define $\text{Inv} := ((b^\perp)^* \otimes z_a^\perp) \oplus ((a^\perp)^* \otimes z_b^\perp)$ where we write $\varphi^* = \mu x. (1 \oplus (\varphi \otimes x))$.

► **Proposition 26.** *For any $n \in \mathbb{N}$, the sequents b^n, z_a, Inv and a^n, z_b, Inv are provable.*

Define $\text{CP} : Q \rightarrow \{\nu x. \psi, \varphi\}$ such that $\text{CP}(q) = \nu x. \psi$ if $q = q_0$ and $\text{CP}(q) = \varphi$ otherwise.

► **Lemma 27** (One step simulation). *Let $\langle p, m, n \rangle$ be a configuration such that $\langle p, m, n \rangle \xrightarrow{\text{ins}} \langle q, m', n' \rangle$, for $\text{ins} \in I$. The following “move” gadget has a finite μMALL^∞ derivation:*

$$\frac{\text{CP}(q), q, a^{m'}, b^{n'}, \text{Inv}}{\text{CP}(p), p, a^m, b^n, \text{Inv}} \text{ (mv}_{\text{ins}})$$

Moreover, if $p = q_0$ then (mv_{ins}) has a (ν) step (for which $\nu x \psi$ is principal, necessarily).

► **Lemma 28.** *If there exists a run of \mathcal{M} from q_0 such that q_0 is visited infinitely often, the sequent $\nu x. \psi, q_0, \text{Inv}$ has a μMALL^∞ proof.*

Proof sketch. Let $\mathcal{R}(p_0) = (\langle p_i, m_i, n_i \rangle)_{0 \leq i < \omega}$ be an infinite run of \mathcal{M} from q_0 (so $p_0 = q_0$). We construct a pre-proof $P(p_0)$ of $\nu x. \psi, q_0, \text{Inv}$ by coinduction on $\mathcal{R}(q_0)$, simply by simulating each step of the run by the one-step “move” gadgets from Lemma 27 (see Figure 4 for a visualisation). We now argue that $P(p_0)$ is progressing, and so is indeed a μMALL^∞ proof.

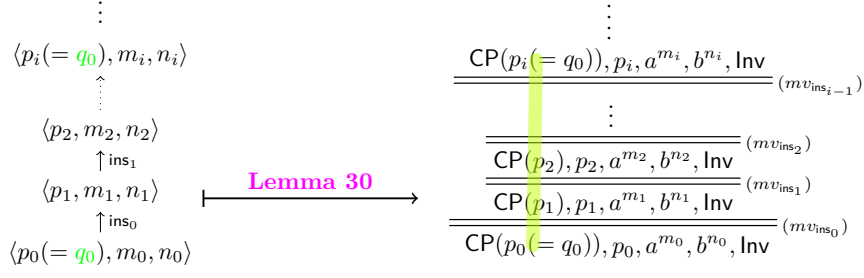
First, observe that $P(p_0)$ has exactly one infinite branch that has infinitely many occurrences of “move” gadgets (mv_{ins}) . Furthermore, every time there is a move rule with a conclusion of the form $\text{CP}(q_0), q_0, a^m, b^n, \text{Inv}$, there is a (ν) step, necessarily on $\text{CP}(q_0) = \nu x \psi$, by Lemma 27. So, since q_0 occurs infinitely often in the run, and by cut-freeness, there is an infinite thread τ along the formulas $\text{CP}(p_i)$ which is infinitely often principal for $\text{CP}(q_0) = \nu x \psi$ (the indicated green thread in Figure 4). Finally, by inspection of the formulas $\text{CP}(p_i)$ and the rules of μMALL^∞ , every formula occurring in τ must have $\nu x \psi$ as a subformula. Thus τ is indeed progressing, and so $P(p_0)$ is a μMALL^∞ proof as required. ◀

4.1 Background on focusing

In order to prove the converse of Lemma 28 above, we have to account for all possible proofs. In order to tame the space of possibilities we shall appeal to “focusing”, a standard technique in proof search. Informally, focused proofs are a family of proofs that have more structure than usual sequent calculus proofs.

We first classify the connectives of μMALL by two polarities: **positive** and **negative**. Inferences for negative connectives are *invertible*, i.e. they preserve provability bottom-up, but the positive inferences do not in general. The negative (respectively, positive) connectives of μMALL^∞ are $\&, \wp, \perp, \top, \nu$ (respectively, $\otimes, \oplus, 1, 0, \mu$).³

³ Observe that both the μ and ν rules are invertible. See [6] for an explanation of the choice.



■ **Figure 4** Simulation of an infinite run by a μMALL^∞ proof.

By assigning arbitrary polarities to atomic variables one can extend the notion to formulas in such a way that each formula is either positive or negative, depending on its top-level connective. A sequent is *positive* if it contains *only* positive or atomic formulas, otherwise it is *negative*. A *focused proof*, briefly, is one where bottom-up:

- only negative rules are applied on negative sequents; and,
- only positive rules are applied on positive sequents;
- any positive auxiliary formula of a positive rule must be principal for the next step;

Note that the focusing discipline described above ensure that, when reaching a positive sequent, bottom-up, positive rules are “hereditarily applied” on a particular positive formula, called the *focus*, until one reaches a negative sequent again. Importantly we have:

► **Theorem 29** ([6]). *If Γ has a cut-free μMALL^∞ proof, it also has one that is focused.*⁴

4.2 Provability implies run existence

In this subsection we prove the converse of Lemma 28 above:

► **Lemma 30.** *If the sequent $\nu x.\psi, q_0, \text{Inv}$ is provable in μMALL^∞ , then there exists a run of \mathcal{M} from the configuration $\langle q_0, 0, 0 \rangle$ such that q_0 is visited infinitely often.*

We shall henceforth assume that all μMALL^∞ proofs are cut-free, under Theorem 9, and focused, under Theorem 29. More specifically we assign atomic polarities as follows: a, b, z_a, z_b and q are negative for any state $q \in Q$. We first make a simple observation that will aid our proof.

▷ **Claim 31.** Inv is not principal in the lowest rule of any focused proof of $\psi, p, a^m, b^n, \text{Inv}$.

Proof. The sequent $\psi, p, a^m, b^n, \text{Inv}$ is positive so if Inv is active, then it is the focus. Without loss of generality, assume that the first rule is (\oplus_1) with principal formula Inv . Then, the auxiliary formula is $(b^\perp)^* \otimes z_a$. Since the outermost connective is positive, we must immediately apply the (\otimes) rule. One of the premisses is of the form Δ, z_a^\perp with z_a^\perp as focus and we cannot apply any inference rule. Because Δ cannot be z_a , the identity rule is ruled out and no other rules are possible since z_a is an atom. ◁

We can now prove the main result of this subsection:

⁴ The focusing result in [6] is for a logic without atoms but the proof technique can be straightforwardly extended to account for atoms.

Proof. The proof has two parts. We first show that one can carve out an infinite run \mathcal{R} of \mathcal{M} from $\langle q_0, 0, 0 \rangle$ from a focussed proof of $\nu x.\psi, q_0, \text{Inv}$. Then, we show that q_0 is visited infinitely often along \mathcal{R} .

Let P be a focussed proof of $\nu x.\psi, q_0, \text{Inv}$. We claim that P can be factored as follows where $p_0 = q_0$, $m_0 = 0$, and $n_0 = 0$.

This factorisation yields the required infinite run $(\langle p_i, m_i, n_i \rangle)_{i \in \omega}$ where for all i ,

$$\langle p_i, m_i, n_i \rangle \xrightarrow{\text{ins}_i} \langle p_{i+1}, m_{i+1}, n_{i+1} \rangle.$$

Furthermore, if P is a proof, then there are infinitely many occurrences of $\nu x.\psi$ along this branch but, since $\text{CP}(p_i) = \nu x.\psi$ only when $p_i = q_0$ we obtain that q_0 occurs infinitely often in the run. Therefore, we are left to prove that P can be factored as described.

We will give a proof-search argument to show that every pre-proof of $\text{CP}(p), p, a^m, b^n, \text{Inv}$ goes through $\text{CP}(q), q, a^{m'}, b^{n'}, \text{Inv}$ such that $\langle p, m, n \rangle \xrightarrow{\text{ins}} \langle p', m', n' \rangle$ for some instruction ins . If $p = q_0$ and $\text{CP}(p) = \nu x.\psi$ then the unique rule that can be applied is (ν) to obtain the sequent $\varphi, p, a^m, b^n, \text{Inv}$ (otherwise $\text{CP}(p)$ is anyway φ). From Claim 31, we get that Inv cannot be the focus. Therefore, φ is the focus and the next rules are necessarily (μ) and \oplus respectively whence we have the sequent $[\text{ins}], p, a^m, b^n, \text{Inv}$ for some instruction ins . If ins is not an instruction that can be fired at p , proof-search immediately fails. If ins is an increment, it is trivial to obtain the result. If ins is a decrement of the form $p^\perp \otimes (((\text{CP}(q) \wp q) \& z_a) \oplus (a^\perp \otimes (\text{CP}(q') \wp q')))$, we need to make sure that the control goes to the appropriate state depending on whether r_1 is zero or not. We will show that an erroneous choice fails proof-search. We have two cases:

Case 1. Suppose we have $a^\perp \otimes (\text{CP}(q') \wp q'), b^n, \text{Inv}$. Here $a^\perp \otimes (\text{CP}(q') \wp q')$ is the focus since in the earlier step $(\text{CP}(q) \wp q) \& z_a \oplus (a^\perp \otimes (\text{CP}(q') \wp q'))$ was the focus. Therefore we have sequent of the form $\vdash \Delta, a^\perp$ where a^\perp is the focus and Δ cannot be $\{a\}$.

Case 2. Suppose we have $(\text{CP}(q) \wp q) \& z_a, a^m, b^n, \text{Inv}$. This is a negative sequent, so the next rule is necessarily $(\&)$ and we have a premiss of the form $z_a, a^m, b^n, \text{Inv}$ where Inv is the focus. It is easy to check that for choices (\oplus_1) and (\oplus_2) , proof-search fails. \blacktriangleleft

Putting Lemmas 28 and 30 together we have:

► **Proposition 32 (Reduction).** \mathcal{M} has an infinite run from q_0 visiting q_0 infinitely often if and only if there is a μMALL^∞ proof of $\nu x.\psi, q_0, \text{Inv}$.

By Theorem 25 we thus have:

► **Theorem 33.** μMALL^∞ is Σ_1^1 -hard.

From here, we can conclude strictness of the inclusion from Theorem 14:

► **Corollary 34.** μMALL^∞ and $\mu\text{MALL}_{\omega, \infty}$ prove different sets of theorems.

Proof. Clearly $\mu\text{MALL}_{\omega, \infty} \in \Pi_1^1$: $\mu\text{MALL}_{\omega, \infty}$ proves Γ just if:

“every set of sequents closed under $\mu\text{MALL}_{\omega, \infty}$ rules contains Γ ”

Note here that closure of a set X of sequents under $\mu\text{MALL}_{\omega, \infty}$ is indeed arithmetical; in particular closure under the (ω) -rule is Π_2^0 : “for every sequent $\Gamma, \nu x\varphi$ not in X there exists $n \in \omega$ such that $\Gamma, \varphi^n(\top)$ is not in X .”

On the other hand, if $\mu\text{MALL}^\infty = \mu\text{MALL}_{\omega, \infty}$ then $\mu\text{MALL}_{\omega, \infty}$ would be Σ_1^1 -hard, by Theorem 33, contradicting its Π_1^1 membership as $\Sigma_1^1 \not\subseteq \Pi_1^1$. \blacktriangleleft

Finally Corollary 34 and Theorem 14 together imply Theorem 1, our main result.

5 A Π_2^1 upper bound on μMALL^∞

Our Σ_1^1 -hardness result, Theorem 33, places μMALL^∞ definitively in the analytical hierarchy. Previously the best known lower bound was Π_1^0 from [13]. In terms of upper bounds, a naïve Σ_3^1 upper bound is readily obtained by the description of μMALL^∞ -provability:

“there *exists* a preproof s.t., for all infinite branches, there *exists* a progressing thread.”

Note here that checking whether a given thread is progressing is indeed arithmetical: “there *exists* some $n \in \mathbb{N}$ and a formula $\nu x\varphi$ that is *infinitely often* principal, and such that *every* formula in the thread after position n has $\nu x\varphi$ as a subformula”. In fact we can improve this upper bound considerably, comprising the main result of this section:

► **Theorem 35** ($\exists 0^\#$). $\mu\text{MALL}^\infty \in \Pi_2^1$.

Note that this result, strictly speaking, depends on the existence of $0^\#$ (as indicated), a principle independent of ZFC, but over which it is equivalent to lightface analytic determinacy [21]. To demonstrate this result we employ ideas from proof search, namely game theoretic formulations therein inspired by previous work [25, 18].

► **Definition 36** (Proof search game, for μMALL^∞). *The proof search game for μMALL^∞ is a two-player game played between Prover (**P**), whose positions are inference steps of μMALL^∞ , and Denier (**D**), whose positions are sequents of μMALL^∞ . A play of the game starts from a particular sequent: at each turn, **P** chooses an inference step with the current sequent as conclusion, and **D** chooses a premiss of that step; the process repeats from this sequent and the two players continue taking turns as long as possible.*

P wins an infinite play of the game if the branch constructed has a progressing thread.⁵

It is not hard to see that winning strategies for **P** correspond to non-wellfounded proofs:

► **Observation 37.** **P** has a winning strategy from Γ iff there is a μMALL^∞ proof of Γ .

When the state space is finite, e.g. for the μ -calculus, the corresponding proof search game is finite-memory determined, yielding regular completeness of the proof system [33]. We do not have this property here, but the characterisation above nonetheless allows us to view **D** strategies as a form of “semantics” for μMALL^∞ under determinacy:

► **Proposition 38** ($\exists 0^\#$). *The proof search game for μMALL^∞ is determined.*

This is a consequence of (lightface) analytic determinacy, as the winning condition is indeed Σ_1^1 : “there *exists* a progressing thread”. From here we readily obtain our upper bound:

Proof of Theorem 35. There is a μMALL^∞ proof of a sequent Γ if and only if **P** has a winning strategy from Γ by Observation 37, if and only if there is no winning strategy for **D** from Γ , by Proposition 38. The latter is clearly a Π_2^1 property:

“for every **D**-strategy there *exists* a play for which there *exists* a progressing thread” ◀

⁵ In the case of deadlock, the player with no valid move loses.

6 Conclusion

In this work, we compared the expressivity of the infinitary systems μMALL^∞ and $\mu\text{MALL}_{\omega,\infty}$ for linear logic with fixed points, and improved bounds on their complexity, cf. Figure 1. We conclude this paper with some remarks on potential future directions of research.

- It would be pertinent to extend our comparison to systems with *wider* branching, indexed by some ordinal α , say $\mu\text{MALL}_{\alpha,\infty}$. Similar systems were considered in [16, 15]. Such systems become weaker (i.e. have fewer theorems) as α increases, as more cases must be proved to derive a ν formula. In this sense it would be particularly interesting if we could show that μMALL^∞ coincides with some $\mu\text{MALL}_{\alpha,\infty}$, calibrating the strength of μMALL^∞ according to some ordinal measure. Let us point out that such an ordinal must be sufficiently large to evade a Π_1^1 upper bound, as for $\mu\text{MALL}_{\omega,\infty}$, due to Σ_1^1 -hardness of μMALL^∞ ; at the same time the systems $\mu\text{MALL}_{\alpha,\infty}$ must reach a limit by $\alpha = \omega_1$, for cardinality reasons, giving a naïve upper bound.
- It would also be interesting to prove bona fide metalogical properties, such as cut-elimination and focusing, for $\mu\text{MALL}_{\omega,\infty}$ (and friends), just like for μMALL^∞ in [6] and for several other infinitely branching systems in related areas [30, 24, 34]. Let us point out that the embedding of μMALL^∞ in $\mu\text{MALL}_{\omega,\infty}$ of Section 3 does not introduce cuts, arguably evidence that $\mu\text{MALL}_{\omega,\infty}$ might enjoy a well-behaved proof theory. We expect such a result to be easier to establish than the analogous results for μMALL^∞ , thanks to the underlying wellfoundedness of $\mu\text{MALL}_{\omega,\infty}$.
- What is the exact complexity of μMALL^∞ ? This question remains open after this work, but we have significantly narrowed the gap to the range between Σ_1^1 and Π_2^1 . It would also be pertinent to investigate the complexity of the infinitary wellfounded system $\mu\text{MALL}_{\omega,\infty}$ (and $\mu\text{MALL}_{\omega,\omega}$ and friends). Let us point out also that the (weaker) Π_1^0 lower bound for μMALL^∞ from [13] applied already to the alternation-free fragment of μMALL^∞ .⁶ Our Σ_1^1 lower bound crucially uses a single alternation to mimic the Büchi condition on Minsky machines. It would be interesting to further investigate the effect of alternation on the complexity of systems we have investigated.
- Can the assumption of lightface analytic determinacy be dropped from Theorem 35? Attempting to do so has been beyond the scope of this work.

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⁶ “Alternation-free” means that no μ occurs under a ν and vice-versa.

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