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The Uranus System from Occultation Observations (1977-2006): Rings, Pole Direction, Gravity Field, and Masses of Cressida, Cordelia, and Ophelia

RICHARD G. FRENCH,¹ MATTHEW M. HEDMAN,² PHILIP D. NICHOLSON,³ PIERRE-YVES LONGARETTI,⁴ AND COLLEEN A. MCGHEE-FRENCH¹

¹*Department of Astronomy, Wellesley College, Wellesley MA 02481 USA*

²*Department of Physics, University of Idaho, Moscow, ID 83844 USA*

³*Astronomy Department, Cornell University, Ithaca NY 14853 USA*

⁴*Institut de Planétologie et d'Astrophysique de Grenoble, Grenoble, FR*

ABSTRACT

From an analysis of 31 Earth-based stellar occultations and three *Voyager 2* occultations spanning 1977–2006 (French et al. 2023a), we determine the keplerian orbital elements of the centerlines (COR) of the nine main Uranian rings to high accuracy, with typical RMS residuals of 0.2 – 0.4 km and 1- σ formal errors in a , ae , and $a \sin i$ of order 0.1 km, registered on an absolute radius scale accurate to 0.2 km at the 2- σ level. The λ ring shows more substantial scatter, with few secure detections. We identify a host of free and forced normal modes in several of the ring centerlines and inner and outer edges. In addition to the previously-known free modes $m = 0$ in the γ ring and $m = 2$ in the δ ring, we find two additional outer Lindblad resonance (OLR) modes ($m = -1$ and -2) and a possible $m = 3$ inner Lindblad resonance (ILR) mode in the γ ring. No normal modes are detected for rings 6, 5, 4, α , or β . Five separate normal modes are forced by small moonlets: the 3:2 inner ILR of Cressida with the η ring, the 6:5 ILR of Ophelia with the γ ring, the 23:22 ILR of Cordelia with the δ ring, the 14:13 ILR of Ophelia with the outer edge of the ϵ ring, and the counterpart 25:24 OLR of Cordelia with the ring's inner edge. The phases of the modes and their pattern speeds are consistent with the mean longitudes and mean motions of the satellites, confirming their dynamical roles in the ring system. We find no evidence of normal modes excited by internal planetary oscillations. We determine the width-radius relations for nearly all of the detected modes, with positive width-radius slopes for ILR modes (including the $m = 1$ elliptical orbits) and negative slopes for most of the detected OLR modes, supporting the standard self-gravity model for ring apse alignment. We find no convincing evidence for librations of any of the rings. The Uranus pole direction at epoch TDB 1986 Jan 19 12:00 is $\alpha_P = 77.311327 \pm 0.000141^\circ$ and $\delta_P = 15.172795 \pm 0.000618^\circ$. The slight pole precession predicted by Jacobson (2023) is not detectable in our orbit fits, and the absolute radius scale is not strongly correlated with the pole direction. From Monte Carlo fits to the measured apsidal precession and nodal regression rates of the eccentric and inclined rings, we determine the zonal gravitational coefficients $J_2 = (3509.291 \pm 0.412) \times 10^{-6}$, $J_4 = (-35.522 \pm 0.466) \times 10^{-6}$, and J_6 fixed at 0.5×10^{-6} , with a correlation coefficient $\rho(J_2, J_4) = 0.9861$, for a reference radius $R = 25559$ km. This result differs significantly from both earlier and more recent results (Jacobson 2014, 2023), owing to our inclusion of previously neglected systematic effects, such as the offset of semimajor axes of the geometric ring centerlines from their estimated dynamical centers of mass and the significant contributions of Cordelia and Ophelia to the precession rate of the ϵ ring. Although we cannot set useful independent limits on J_6 , we obtain strong joint constraints on combinations of J_2 , J_4 , and J_6 that are consistent with our measurements. These can be used to limit the range of realistic models of the planet's internal density distribution and wind profile with depth. The observed anomalous apsidal and nodal precession rates of the α and β rings are consistent with the presence of unseen moonlets with masses and orbital radii predicted by Chancia and Hedman (2016). The γ ring's putative $m = 3$ mode does not appear to be

forced by a satellite, whose predicted size would be too large to have avoided prior detection. If this mode is excluded from the orbit fit, the solution for the γ ring has a very large anomalous apsidal precession rate of unknown origin. From the amplitudes and resonance radii of normal modes forced by moonlets, we determine the masses of Cressida, Cordelia, and Ophelia. Their estimated densities decrease systematically with increasing orbital radius and generally follow the radial trend of the Roche critical density for a shape parameter $\gamma = 1.6$.

Keywords: occultations, planets: rings

1. INTRODUCTION

Prior to the discovery of the Uranian rings in 1977 (Elliot et al. 1977; Millis et al. 1977), Saturn was the only planet known to have rings, which in that pre-*Voyager* era were thought to be broad and diffuse, owing to viscous spreading associated with interparticle collisions. This simple paradigm was overturned by the detection of the narrow, eccentric, inclined Uranian rings that somehow manage to avoid circularization due to differential precession and to be sharp-edged and radially confined in the absence of direct evidence for shepherd satellites for most of the rings. The discovery of Jupiter’s dusty rings by *Voyager 1* in 1979 (Smith et al. 1979) expanded the scope and variety of rings in the solar system, and the subsequent *Voyager* Saturn encounters revealed a bewildering variety of complex ring structure, much of it produced by the gravitational influence of nearby satellites. The *Cassini* mission’s 13 year reconnaissance of the Saturn system greatly expanded our knowledge of the structure and dynamical environment of the rings (Colwell et al. 2009; Schmidt et al. 2009; Cuzzi et al. 2009; Charnoz et al. 2009; Cuzzi et al. 2018). From the *Voyager 2* flyby of Uranus in 1986, a closer view of its rings revealed the faint narrow λ ring, sheets of dusty ring material between the narrow rings, and a gallery of nearby tiny moons (Smith et al. 1986). Subsequent observations revealed additional details of this dusty and satellite-rich system (de Pater et al. 2002, 2006; Showalter and Lissauer 2006; de Pater et al. 2013). The census of giant planet ring systems in the solar system was extended by the detection of the Neptune’s ring arcs from stellar occultation observations (Hubbard 1986a; Hubbard et al. 1986b; Manfroid et al. 1986) and *Voyager 2* images (Smith et al. 1989). Several tiny trans-Neptunian objects have rings: 10199 Chariklo’s rings were discovered during a stellar occultation in 2013 (Braga-Ribas et al. 2014) and observed from the James Webb Space Telescope in 2022 (Santos-Sanz 2022), Centaur 2060 Chiron has possible ring material (Ortiz et al. 2015), and a 70 km-wide ring was detected in orbit around dwarf planet Haumea (Ortiz et al. 2017). Further afield, the search is on for evidence of ringed extra-solar planets (see Sicardy et al. (2018) for a recent discussion).

This observed wide variety of ring phenomena leaves us with many unanswered questions about their physical properties, internal structure, dynamics, origins, and evolution (Esposito and De Stefano 2018). The observational basis to advance our understanding of the narrow Uranian rings in particular rests in large part on an extensive set of stellar occultation observations obtained from 1977 to 2006, described in Paper 1 (French et al. 2023a). Here, we make use of these observations to determine accurate orbits for the Uranian rings and ring edges, the planet’s pole direction and gravity field, and the masses of the moonlets Cressida, Cordelia, and Ophelia.

The paper is organized as follows: In Section 2, we summarize the Earth-based and *Voyager 2* Uranus ring occultation observations used for this work. Section 3 presents our geometric model of the Uranus ring system and our kinematical model for the rings and ring edges. In Section 4 we present the orbits of the ten narrow rings and ring edges and identify a host of free and forced normal modes. Then, in Section 5, we determine the direction of the planet’s pole and the absolute ring radius scale, and in Section 6 we examine the widths, shapes, and masses of the rings. Next, in Section 7, we solve for the zonal gravity coefficients J_2 and J_4 , taking into account several important systematic effects that have been ignored in previous analyses. In Section 8 we summarize the evidence for anomalous precession in several rings and the possibility that it is caused by nearby unseen small satellites, and in Section 9 we estimate the masses and densities of Cressida, Cordelia, and Ophelia from their associated forced normal modes in the rings. In Section 10, we discuss the broader context of the dynamics of narrow ringlets, compare the Uranus and Saturn narrow rings, and identify persistent unsolved problems. Our main conclusions are summarized in Section 11.

2. OBSERVATIONS

The observations underlying the present work include 31 Earth-based stellar occultations by the narrow Uranian rings, sometimes viewed with multiple telescopes and at multiple wavelengths, and three *Voyager* occultations: one by the Radio Science Subsystem (RSS; Tyler et al. (1986); Gresh et al. (1989)) and stellar occultations of σ Sgr and β Per observed by the Photopolarimeter (PPS; Lane et al. (1986)) and the Ultraviolet Spectrometer (UVS; Holberg et al. (1987)). Paper 1 provides a detailed description of the Earth-based observations and a summary of the *Voyager* data. Here, we limit ourselves to a brief overview of the observations, emphasizing characteristics of the data and event geometry that affect the accuracy of the ring measurements used for this study and the scientific interpretation of our results.

2.1. Earth-based stellar occultations

For most of the 1977–2006 interval of occultation observations, the Uranus system presented a nearly pole-on view as seen from Earth, a geometry that favored the determination of the absolute radius scale of the rings while limiting the initial accuracy of their inclinations and of the planet’s pole direction. The majority of the Earth-based occultation events were observed between 1980–1990, when Uranus was traversing the Milky Way and high-SNR occultation opportunities were frequent. After the initial discovery observations, which were made at visual wavelengths, most occultations were observed in the infrared K band ($\lambda \sim 2.2 \mu\text{m}$), where a strong methane absorption band minimizes the planet’s signal within the photometric aperture. Most of the IR observations were made using InSb aperture photometers, centered on the occultation star but also containing the background signal from the rings, planet, and sky. Many events were recorded continuously in what is known as DC mode, most suitable for photometric conditions. In other cases, especially for faint stars or events with a strong background signal, observations were conducted in chopping mode, where the secondary mirror of the telescope rapidly nodded between the event star and the nearby sky, with filtering electronics recording the difference between the brightness within the aperture at these two alternate positions.

As an example of some of the best data used in this work, **Fig. 1** shows the observations of the May 24, 1985 occultation of U25 from Palomar Observatory’s 5 m Hale telescope. The bright star was observed in chopping mode under photometric conditions with excellent seeing and accurate tracking, resulting in high-SNR lightcurves with stable baselines. The figure shows the normalized ingress and egress signals as a function of equatorial plane radius. The radial misalignment of several of the ingress/egress ring event pairs is due primarily to their orbital eccentricities, most notably for the outermost ϵ ring. Most ring events are sharp and unresolved at this resolution, with the exception of low optical depth companions exterior to the η ring and interior to the δ ring (barely visible here in the ingress profile). Only the eccentric ϵ ring is radially resolved, narrower near periape (upper panel) than near apoapse. The orbital radius of the elusive λ ring is labeled, but it was not detected during either ingress or egress during this occultation. (The sharp dip in the signal just exterior to the egress ϵ ring is a calibration check of the normalized intensity of the occulted star.)

A gallery of the individual ring profiles for the U25 Palomar occultation is shown in **Fig. 2**, plotted in units of normalized flux as a function of ring plane radius (lower axis) and event time (upper axis) and arranged in parallel rows for ingress and egress, increasing radially from the innermost ring 6 to the outermost ϵ ring. The gap reflects the non-detection of the λ ring, noted above. Each profile is labeled by the ring name and event direction (I for ingress, E for egress), and a Quality Index (QI) in parentheses. As described in more detail in Paper 1, every individual Earth-based ring profile used in this study has been assigned a subjective quality index (QI), ranging from 1 (high-SNR profile with sharp ring edges well-matched by the model fit) to 4 (unreliable detection). For the observations shown, QI=1 for every ring event, but this is not the usual case – see Paper 1 for a complete survey of all occultations.

Most of the Uranian rings are at most a few km in width and are unresolved radially in the lightcurves, owing to the combined smoothing effects of Fresnel diffraction and the finite angular diameter of the occultation star. In some cases, the resolution is further limited by intrinsic instrumental time constants or by the sampling interval of the recorded data. For this event, the Fresnel diffraction scale $F \sim \sqrt{\lambda D/2} = 1.73 \text{ km}$, where λ is the observed wavelength and D

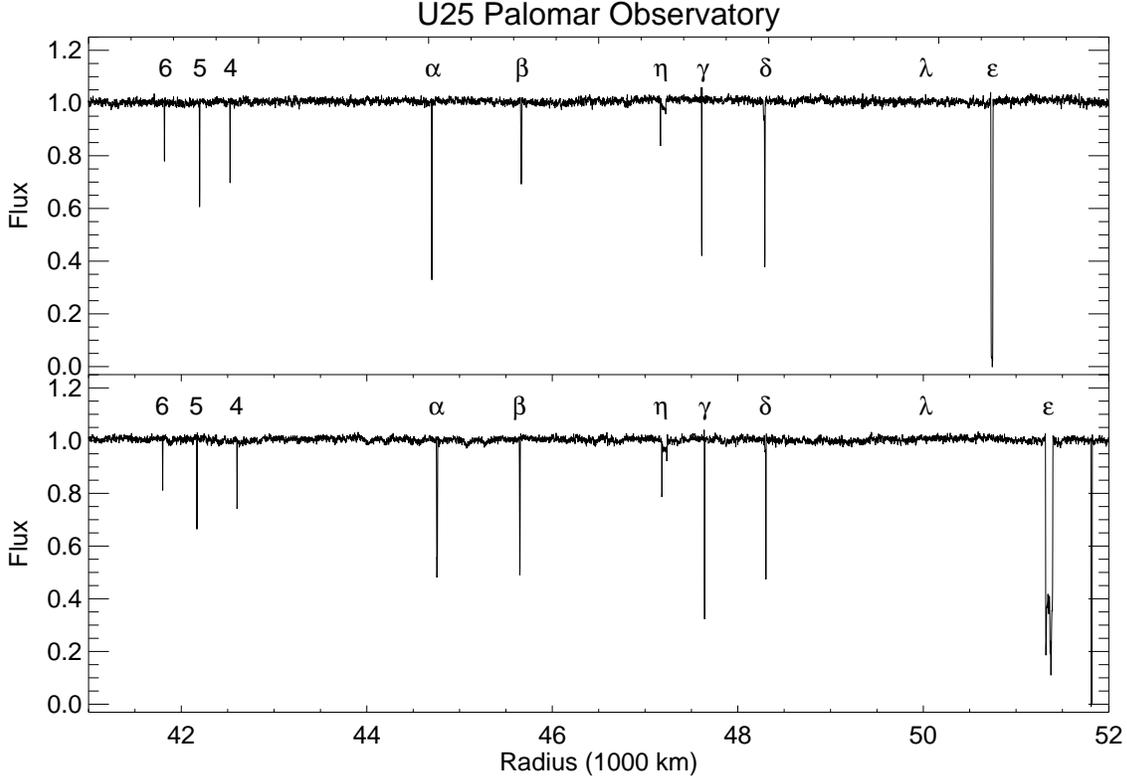


Figure 1. Observations of the May 24, 1985 occultation of U25 from Palomar Observatory’s 5 m Hale telescope at $\lambda = 2.2 \mu\text{m}$ (after Fig. 4.2 Nicholson et al. (2018a)). The orbital eccentricities of several of the narrow rings are evident from their radial misalignments between ingress (top) and egress (bottom). Only the egress ϵ ring profile shows internal structure at this scale. Both the η and δ rings have adjacent low-optical depth shoulders, not considered in this work. There is no hint of the elusive λ ring in this very high SNR observation, indicative of its azimuthal variability in optical depth and/or its dusty nature, rendering it less evident in IR observations.

is the distance between the observer (or spacecraft) and the ring plane, and the projected stellar diameter at Uranus was assumed to be $d_* = 5.254 \text{ km}$. In this case, the stellar smoothing dominated that by diffraction, but there are visible diffraction fringes in several of the observed profiles and both effects were included in the models. (Smoothing due to the $\lambda = 2 - 2.4 \mu\text{m}$ response of the K-band filter was also taken into account.) Each profile has been fitted to a square-well model in which the ring is assumed to be sharp-edged and radially uniform in opacity. The underlying square-well model is shown as a box function in red, and the corresponding smoothed model is overdrawn on the data. In this case, the models match the observations extremely well, as indicated in the assignment of $\text{QI}=1$ for all profiles.

In the examples shown above, diffraction effects are suppressed somewhat by the significant smoothing due to the relatively large projected diameter of the occulted star at Uranus. For fainter and more distant occultation stars, however, stellar smoothing is less significant and diffraction by the ring edges is more prominent. **Figure 3** shows the premier example of this: the egress γ ring profile observed from the Anglo-Australian Telescope (AAT) during the remarkable 4-day occultation of U36 in March/April 1987, when Uranus reversed direction at the retrograde point in its geocentric orbit and the consequent skyplane velocity of the star relative the projected ring edge was only $v_{\perp} = 0.90 \text{ km s}^{-1}$. The projected diameter of U36 was 0.548 km , significantly smaller than the Fresnel scale $F = 1.76 \text{ km}$. In this example, multiple diffraction fringes are closely matched by a model of the γ ring as a 0.73 km -wide square-well with a fractional transmission $f = 0.077$.

For our present purposes, the key observables from the full set of individual Earth-based occultation ring profiles are the times of the midline and edges from the fitted square-well models, which we treat as our best estimates of

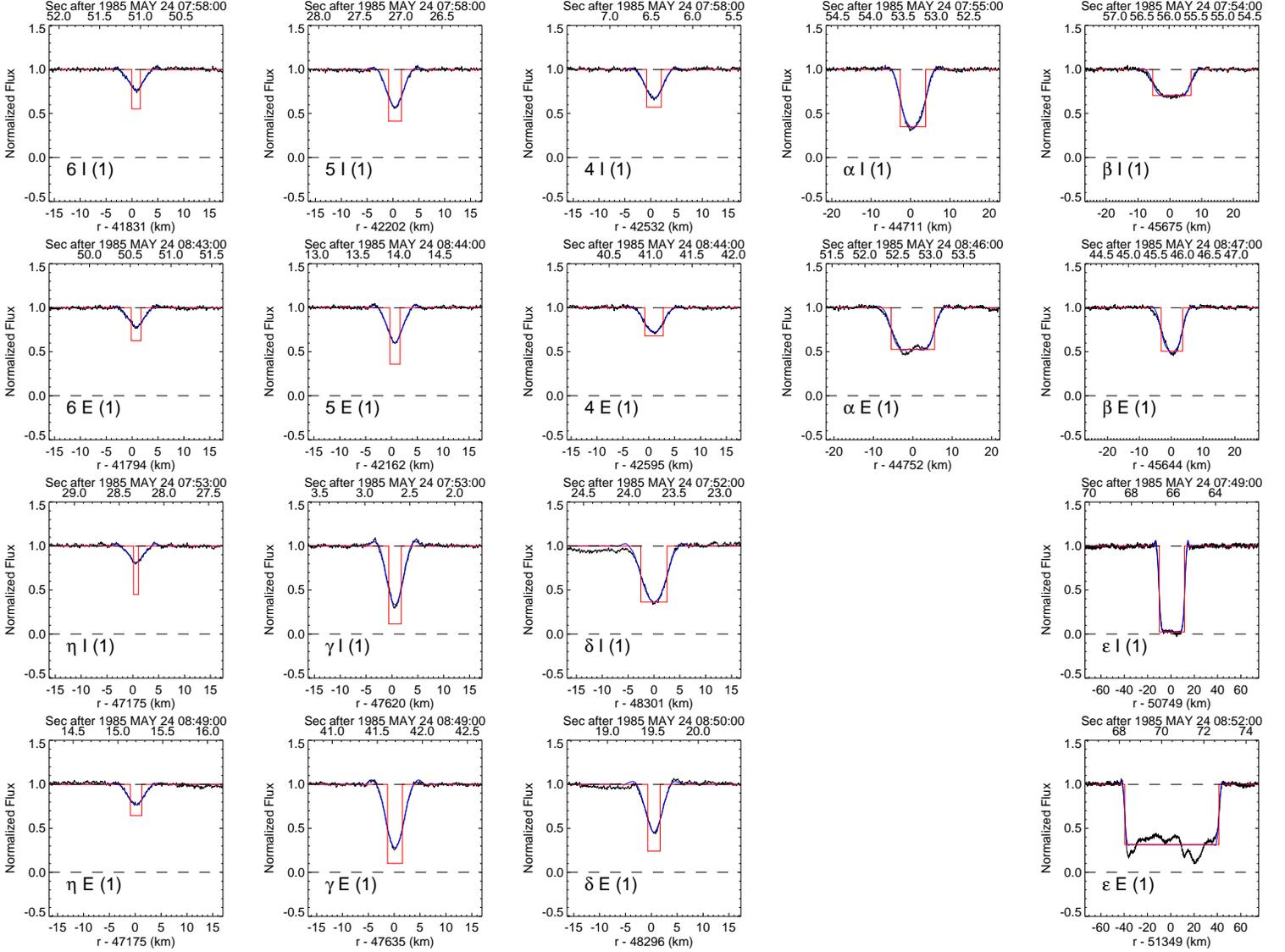


Figure 2. Gallery of individual ring profiles from the May 24, 1985 observations of the U25 event from Palomar Observatory’s 5 m Hale telescope, plotted as a function of ring plane radius (lower axis) and observed time in UTC (upper axis). The profiles are arranged in parallel rows (ingress, then egress), from the innermost ring 6 to the outermost ϵ ring. Square-well model fits are overplotted on each profile, showing the smoothing effects of diffraction and the finite angular size of the occulted star, and the geometric square-well model is shown as a box function in each panel. Rings are labeled by name, event direction (I for ingress, E for egress), and Quality Index (1 in all cases shown here – see text for details).

the midline and edges of the actual ring.¹ As described below, we determine the geometry of the Uranus ring system from least-squares fits to these ring midpoint and edge location times. In our final ring orbit models, the post-fit RMS radius errors of the midpoint measurements for the nine main rings are 0.212–0.401 km and somewhat larger for the ring edges, but in all cases well below the characteristic Fresnel scale for the observations.

Under these circumstances, it is appropriate to ask whether the square-well model accurately determines the widths and midlines of the narrow ring profiles that are at the heart of our investigation. We address this question in Appendix A, where we compare square-well model fits to the diffraction-limited *Voyager* RSS ring observations with the measured widths of the corresponding spatially resolved diffraction-corrected profiles. Our summary conclusion

¹ The equivalent width and mean opacity are also determined from the square-well fits, but we do not make use of this information in this study.

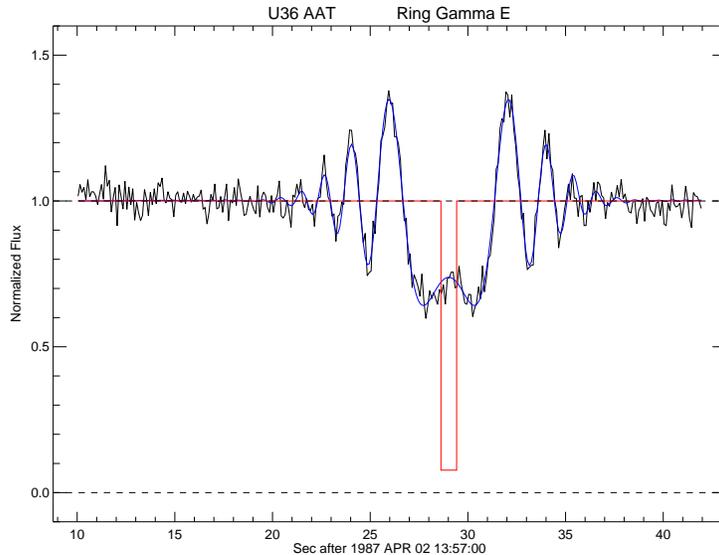


Figure 3. The egress γ ring profile observed from the AAT during the stellar occultation of U36 on April 2, 1987. The best-fitting square-well diffraction model is overplotted on the data, and the underlying box model of the ring is shown in red.

is that the square-well model demonstrably provides estimates of ring widths that are accurate at the level of a few hundred m for rings with intrinsically sharp edges, and are likely to be somewhat less accurate for rings with more gradual edges. To the extent that the fitted ring width can be viewed as equivalent to independent measurements of the inner and outer ring edges whose average defines the midline of the ring, the corresponding accuracy of the ring midline measurements is reduced by a factor of $1/\sqrt{2}$ to about 0.2 km, a bit smaller than but of the same order as the RMS error in the ring orbit fits presented below. In cases where one edge is sharp and the other is more gradual, the two test cases examined above show no systematic sense of error, with one ring width being underestimated and the other example being overestimated. These limitations should be kept in mind when assessing the accuracy of the ring orbit model fits to the observed measurements of the ring midlines and edges.

2.2. Imaging observations

Direct images of the Uranian rings provide additional information about their photometric properties that is complementary to the results from stellar occultations. Although we make no direct use of imaging data in this paper, preliminary (Showalter 2011) and more detailed recent (Hedman et al. 2023) analysis of *Voyager 2* wide- and narrow-angle camera (WAC/NAC) images have revealed periodic azimuthal brightness variations in several of the rings that are indicative of normal modes, some of which are also seen in our analysis. *Voyager* and *Hubble Space Telescope (HST)* observations of small Uranian moons have provided updated estimates of the ephemeris of Ophelia that we will compare to our results in Section 9 below. Ongoing and upcoming imaging observations from *JWST* will provide additional valuable information about the ring structure as well.

3. GEOMETRIC MODEL OF THE URANUS RING SYSTEM

3.1. General description

We determine the orbital elements of the rings and the pole direction and gravity field of Uranus from model fits to the measured midpoints of the occultation ring profiles from the complete set of observations described in Section 2, obtained from square-well model fits for the Earth-based stellar occultations and *Voyager* RSS data, and from direct measurement of midpoints of the spatially resolved *Voyager* PPS stellar occultation profiles. We make use of our well-tested orbit fitting code (RINGFIT) that implements the solar system barycenter (SSBC) occultation

geometry described in detail by French et al. (1993), with minor modifications described by French et al. (2010).² The code makes extensive use of the ICY interface to NASA’s NAIF SPICE toolkit (Acton 1996), which provides access to planetary ephemerides and spacecraft trajectory files. We use the J2000 heliocentric reference frame, the IAU 1976 model for the Earth shape (Abalakin 1981), and the ITRF93 Earth rotation model (Boucher et al. 1994). We account for general relativistic deflection by Uranus (including the effect of J_2) for Earth-based stellar occultations only, solving for the deflection at the time the occultation ray is closest to Uranus in the sky plane, rather than the time the occultation ray penetrates the ring plane, as implied by Eqs. (A20) – (A23) of French et al. (1993). (The difference amounts to only a few meters in the derived ring plane radius.)

3.1.1. Occultation stars

Until recently, the typical astrometric uncertainty in the parallax- and proper motion-corrected occultation star positions was substantially larger than the uncertainty in the Uranus ephemeris, and orbit fits to the rings included fitted corrections to the predicted star positions at the epoch of each occultation. With the release of the *Gaia* EDR3 and DR3 catalogs (Gaia Collaboration et al. 2021, 2022), the situation has reversed, with small but measurable systematic errors in the Uranus ephemeris in `ura111.bsp` and `de440.bsp` exceeding the star position uncertainties. To reduce these systematic errors, the `ura178` series of ephemerides (described in Section 3.3 below) was developed using the astrometric constraints provided by the full set of ring occultation events in Paper 1 for all but the γ and λ rings (R. Jacobson, pers. comm). We cross-referenced the predicted star positions for all Earth-based Uranus ring occultations, using VizieR (Ochsenbein et al. 2000), to obtain the J2000 *Gaia* DR3 catalog positions given in Table 2 of Paper 1. The *Voyager 2* stellar occultation stars σ Sgr and β Per are too bright to allow accurate *Gaia* DR3 positions, and for these stars we make use of the *Hipparcos* catalog positions (Perryman et al. 1997). As part of our orbit solution, we fit for corrections to selected star positions and proper motions under the assumption that the revised Uranus ephemeris is free of systematic errors.

3.1.2. Telescope coordinates

The geocentric coordinates of many of the telescopes used for this study are listed in multiple sources that are not always in agreement. For this work, we used modern GPS coordinates, when available. In all cases, these closely matched our estimates from Google Earth, and we therefore used Google Earth to estimate the locations of telescopes not otherwise known. **Table 1** lists our adopted coordinates for each telescope, including the observatory name, ID, telescope diameter, E longitude, latitude, altitude relative to the IAU 1976 Earth model, and geocentric coordinates x, y, z and radius ρ . These were converted to a custom SPK kernel file of observatory locations (`ObsCodes_Uranus_20220212.spk`) for use in our SPICE-based geometry calculations in our ring orbit fitting code.

² Detailed comparisons of our calculations of the event geometry of an inclined and eccentric ring occultation event with those by R. Jacobson, using an independent code, agree at the 0.002 km level in the derived ring plane radius for a given Earth-received event time.

Table 1. Observatory and telescope coordinates

Observatory	ID	Diam (cm)	E longitude			Latitude			alt (m)	x (km)	y (km)	z(km)	ρ (km)
Centro Astron. Hispano-Aleman (CAHA)	CAL	123	+357	27	11.675	+37	13	15.38	2161	5081.895	-226.036	3838.254	6372.515
Cerro Tololo Interamerican Obs. (CTIO)	807	400	+289	11	36.917	-30	10	10.78	2380	1815.052	-5213.997	-3187.844	6375.149
	C60	150	+289	11	35.700	-30	10	09.30	2380	1815.029	-5214.030	-3187.804	6375.149
European Souther Observatory	ESO	360	+289	16	05.900	-29	15	39.50	2400	1838.338	-5258.792	-3100.341	6375.460
	ES2	200	+289	15	48.000	-29	15	28.20	2317	1837.913	-5259.044	-3099.997	6375.378
	ES1	104	+289	15	41.900	-29	15	24.00	2321	1837.780	-5259.161	-3099.886	6375.382
NASA Infrared Telescope Facility (IRTF)	IRT	320	+204	31	40.932	+19	49	34.46	4212	-5464.326	-2493.467	2151.039	6379.907
	LAS	250	+289	17	45.784	-29	00	26.67	2270	1845.370	-5270.713	-3075.917	6375.410
Las Campanas Observatory	LAV	100	+289	17	59.053	-29	00	43.22	2270	1845.627	-5270.361	-3076.166	6375.409
Lowell Observatory	688	180	+248	27	47.436	+35	05	49.42	2204	-1918.477	-4861.173	3647.949	6373.311
McDonald Observatory	711	270	+255	58	40.667	+30	40	18.27	2103	-1330.794	-5328.793	3235.718	6374.709
Mount Stromlo	414	190	+149	00	31.968	-35	19	08.72	770	-4466.831	2683.001	-3667.254	6371.799
Observatorio del Teide	TEE	155	+343	29	20.740	+28	18	01.82	2395	5390.292	-1597.793	3007.004	6375.756
Palomar Observatory	675	508	+243	08	06.612	+33	21	22.57	1706	4678.798	11.472	4324.379	6371.149
Pic du Midi (OPMT)	586	200	+000	08	25.764	+42	56	14.52	2891	1815.052	-5213.997	-3187.844	6375.149
	PI1	106	+000	08	31.900	+42	56	11.20	2862	4678.846	11.612	4324.285	6371.120
S. African Astronomical Obs. (SAAO)	SAA	188	+020	48	41.710	-32	22	44.16	1768	5041.283	1916.170	-3396.939	6373.809
Siding Spring Observatory (AAT)	413	390	+149	04	02.208	-31	16	31.14	1164	-4681.032	2805.172	-3292.625	6373.572
Siding Spring Observatory (ANU)	ANU	230	+149	03	44.597	-31	16	17.88	1149	-4680.963	2805.674	-3292.268	6373.559
UK Infrared Telescope (UKIRT)	UKI	380	+204	31	46.890	+19	49	20.70	4194	-5464.370	-2493.677	2150.635	6379.890

3.2. Kinematical model for ring orbits

The RINGFIT orbit fitting code solves for the geometric ring orbital elements that minimize the sum of squared residuals between the observed and model ring plane radii, using a standard kinematical model for all ring features. Following [Nicholson et al. \(2014b\)](#), our basic model is of a precessing, inclined keplerian ellipse, specified by

$$r(\lambda, t) = \frac{a(1 - e^2)}{1 + e \cos f}, \quad (1)$$

where the true anomaly $f = \lambda - \varpi = \lambda - \varpi_0 - \dot{\varpi}(t - t_0)$. Here, r , λ , and t are the radius, inertial longitude, and time of the observation at the ring (not at the observer), a and e are the ring's semimajor axis and eccentricity, ϖ and $\dot{\varpi}$ are its longitude of periapse and apsidal precession rate, and t_0 is the epoch of the fit. For inclined rings, we include three additional parameters: i (the inclination relative to the mean ring plane), Ω_0 (the longitude of the ascending node) and $\dot{\Omega}$ (the nodal regression rate), and compute the intercept point of the occultation ray with the specified inclined ring plane. The zero-point for the inertial longitudes λ , ϖ_0 , and Ω_0 (as well as δ_m below) is the ascending node of Uranus's equator on Earth's equator of J2000, where the orientation of the Uranus pole is in the direction of positive angular momentum (*i.e.*, 180° from the IAU definition of the Uranus north pole). The apsidal and nodal rates $\dot{\varpi}$ and $\dot{\Omega}$ can be treated as free parameters in the orbit fit, or alternatively, as in [Nicholson et al. \(2014b\)](#), the expected secular rates $\dot{\varpi}_{sec}$ and $\dot{\Omega}_{sec}$ can be calculated from the combined effects of Uranus's zonal gravity harmonics J_2, J_4, J_6, \dots based on the results of [Borderies-Rappaport and Longaretti \(1994\)](#), and the secular precession induced by the planet's satellites according to the expressions:

$$\begin{aligned} \dot{\varpi}_{sec} = & \sqrt{\frac{GM}{a^3}} \left\{ \frac{3}{2} J_2 \left(\frac{R}{a} \right)^2 (1 + e^2 - 2 \sin^2 i) - \frac{15}{4} J_4 \left(\frac{R}{a} \right)^4 \right. \\ & \left. + \left[\frac{27}{64} J_2^3 - \frac{45}{32} J_2 J_4 + \frac{105}{16} J_6 \right] \left(\frac{R}{a} \right)^6 + \frac{1}{4} \sum_{j=1}^{M_o} \frac{m_j}{M} \alpha_{oj}^2 b_{3/2}^1(\alpha_{oj}) + \frac{1}{4} \sum_{j=1}^{M_i} \frac{m_j}{M} \alpha_{ij}^2 b_{3/2}^1(\alpha_{ij}) \right\} \quad (2) \end{aligned}$$

$$\begin{aligned} \dot{\Omega}_{sec} = & - \sqrt{\frac{GM}{a^3}} \left\{ \frac{3}{2} J_2 \left(\frac{R}{a} \right)^2 (1 + e^2 - \frac{1}{2} \sin^2 i) - \left[\frac{9}{4} J_2^2 + \frac{15}{4} J_4 \right] \left(\frac{R}{a} \right)^4 \right. \\ & \left. + \left[\frac{351}{64} J_2^3 + \frac{315}{32} J_2 J_4 + \frac{105}{16} J_6 \right] \left(\frac{R}{a} \right)^6 + \frac{1}{4} \sum_{j=1}^{M_o} \frac{m_j}{M} \alpha_{oj}^2 b_{3/2}^1(\alpha_{oj}) + \frac{1}{4} \sum_{j=1}^{M_i} \frac{m_j}{M} \alpha_{ij} b_{3/2}^1(\alpha_{ij}) \right\}, \quad (3) \end{aligned}$$

where the summation is carried out over outer (subscript o) and inner (subscript i) satellites of mass m_j and orbital radius a_{oj} or a_{ij} , where for outer satellites $\alpha_{oj} = a/a_{oj}$ and for inner satellites $\alpha_{ij} = a_{ij}/a$, and $b_{3/2}^1(\alpha_{oj})$ and $b_{3/2}^1(\alpha_{ij})$ are Laplace coefficients as defined by [Brouwer and Clemence \(1961\)](#). (Note that the Laplace coefficient factor α_{oj} is squared, whereas α_{ij} is to the first power only.) **Figure 4** shows radial dependence of satellite-induced secular precession in the vicinity of the ten narrow Uranian rings, with the individual contributions shown for each satellite. As we will see, the uncertainty in the fitted apse rates is as small as $4.2 \times 10^{-6} \text{ }^\circ \text{ d}^{-1}$ for the ϵ ring, comparable to the individual secular contributions of Oberon, Portia, and Puck to its precession rate.

The orbital semimajor axes a and masses used to compute the secular precession rate due to the major satellites are given in **Table 2**, from [Jacobson \(2023\)](#).³

Table 2. Major satellite orbits and masses from [Jacobson \(2023\)](#)

Satellite	a (km)	GM_{sat} ($\text{km}^3 \text{ s}^{-2}$)	$M_{\text{sat}}/M_{Ur} \times 10^{-6}$	M_{sat} ($\times 10^{20}$ kg)
Ariel	190928.	82.30 ± 1.20	14.204 ± 0.207	12.331 ± 0.180
Umbriel	265981.	86.00 ± 1.50	14.843 ± 0.259	12.885 ± 0.225
Titania	436283.	230.60 ± 3.40	39.800 ± 0.587	34.550 ± 0.509
Oberon	583447.	207.60 ± 5.00	35.830 ± 0.863	31.104 ± 0.749
Miranda	129828.	4.20 ± 0.20	0.7249 ± 0.0345	0.6293 ± 0.0300
Puck	86004.	0.1275 ± 0.0425	0.0220 ± 0.0073	0.0191 ± 0.0064

The corresponding results for the minor satellites are given in **Table 3**, with semimajor axes a from [Jacobson \(1998\)](#) and satellite properties from [Karkoschka \(2001a,b\)](#). Each satellite is modeled as a prolate spheroid with semimajor and semiminor axes A and B , respectively, and volume V given by

$$V = \frac{4\pi}{3}AB^2 \quad (4)$$

using the dimensions and uncertainties in Table V of [Karkoschka \(2001b\)](#). We estimate the fractional mass uncertainty for an assumed satellite density from the fractional uncertainty in its volume $\sigma(V)/V$, computed from the propagated uncertainties $\sigma(\sqrt{AB})$ and $\sigma(B/A)$.

The corresponding mass estimates and uncertainties are computed for an assumed mean density of uncompressed solid water ice $\rho = 0.90 \text{ gm cm}^{-3}$, which can be scaled for alternate assumed densities. Also included are the directly measured masses and inferred densities of Cordelia, Ophelia, and Cressida determined from the amplitudes and inferred locations of forced resonances between these moons and ring edges (see Section 9.2 below).

In addition to the keplerian orbit, the orbit model allows for a combination of free or forced modes of radial distortion $\Delta r(m, \lambda, t)$ given by

$$\Delta r(m, \lambda, t) = -A_m \cos(m\theta), \quad (5)$$

where

$$\theta = \lambda - \Omega_P(t - t_0) - \delta_m. \quad (6)$$

Here, m is the number of radial minima and maxima in the pattern, A_m and δ_m are the mode's radial amplitude and phase (the longitude at epoch of one of the m radial minima), respectively, and the pattern speed Ω_P is its angular rotation rate in inertial space. As explained in more detail by [Nicholson et al. \(2014b\)](#), Ω_P is expected to be close to that of a Lindblad resonance located at a ring particle's orbit, in which case

$$\Omega_P \simeq [(m - 1)n + \dot{\omega}_{\text{sec}}]/m, \quad (7)$$

where the mean motion n and apsidal precession rate $\dot{\omega}_{\text{sec}}$ are evaluated at the semimajor axis of the ring feature in question. A positive value of m corresponds to an inner Lindblad resonance (ILR)-type normal mode, expected at the

³ Since satellite masses are variously quoted in the literature in units of GM_{sat} , fractional planet mass M_{sat}/M_{Ur} , and kg, we list all three for convenient comparison.

Table 3. Minor satellite orbits, dimensions, densities, and masses^a

Satellite	a km	\sqrt{AB} km	B/A	$A \times B$ km \times km	V $\times 10^5$ km ³	$\frac{\sigma(V)}{V}$	ρ gm cm ⁻³	GM_{sat} $\times 10^{-3}$ km ³ s ⁻²	M_{sat}/M_{U_r} $\times 10^{-10}$	M_{sat} $\times 10^{16}$ kg
Cordelia	49752.000	21 \pm 3	0.7 \pm 0.2	25 \times 18	0.339	0.349	[0.90]	2.04 \pm 0.71	3.52 \pm 1.23	3.05 \pm 1.06
Cordelia ^b							1.79 ^{+0.97} _{-0.49}	4.06 \pm 0.38	7.00 \pm 0.66	6.08 \pm 0.57
Ophelia	53764.000	23 \pm 4	0.7 \pm 0.3	27 \times 19	0.408	0.504	[0.90]	2.45 \pm 1.24	4.23 \pm 2.13	3.67 \pm 1.85
Ophelia ^b							0.87 ^{+0.89} _{-0.30}	2.38 \pm 0.22	4.11 \pm 0.37	3.57 \pm 0.32
Bianca	59165.000	27 \pm 2	0.7 \pm 0.2	32 \times 23	0.709	0.299	[0.90]	4.26 \pm 1.27	7.35 \pm 2.20	6.38 \pm 1.91
Cressida	61767.000	41 \pm 2	0.8 \pm 0.3	46 \times 37	2.638	0.380	[0.90]	15.85 \pm 6.02	27.35 \pm 10.40	23.74 \pm 9.03
Cressida ^b							0.70 ^{+0.44} _{-0.21}	12.27 \pm 1.41	21.18 \pm 2.44	18.39 \pm 2.12
Desdemona	62659.000	35 \pm 4	0.6 \pm 0.2	45 \times 27	1.374	0.375	[0.90]	8.25 \pm 3.09	14.25 \pm 5.34	12.37 \pm 4.63
Juliet	64358.000	53 \pm 4	0.5 \pm 0.1	75 \times 37	4.301	0.230	[0.90]	25.83 \pm 5.95	44.59 \pm 10.26	38.71 \pm 8.91
Portia	66097.000	70 \pm 4	0.8 \pm 0.1	78 \times 63	12.968	0.148	[0.90]	77.90 \pm 11.55	134.44 \pm 19.93	116.71 \pm 17.30
Rosalind	69927.000	36 \pm 6	1.0 \pm 0.2	36 \times 36	1.954	0.314	[0.90]	11.74 \pm 3.69	20.26 \pm 6.36	17.59 \pm 5.52
Belinda	75255.000	45 \pm 8	0.5 \pm 0.1	64 \times 32	2.745	0.327	[0.90]	16.49 \pm 5.39	28.46 \pm 9.30	24.71 \pm 8.07
Puck	86004.000	81 \pm 2	1.0 \pm 0.1	81 \times 81	22.261	0.078	[0.90]	133.72 \pm 10.47	230.79 \pm 18.06	200.35 \pm 15.68

^a Except as noted, masses and uncertainties computed from satellite shapes from Table V of [Karkoschka \(2001b\)](#) and assumed density $\rho=0.90$ gm cm⁻³.

^b Inferred mass from the amplitude(s) of normal mode(s) forced on ring edge(s) and corresponding density computed from the tabulated satellite volume V . Density uncertainty computed from the combined volume and mass uncertainties. See Section 9.2.

outer edge of a ringlet, while a negative value of m corresponds to an outer Lindblad resonance (OLR)-type normal mode, expected at a ringlet's inner edge. In either case, Ω_P is positive. For orbits about an oblate planet, n is given by Eq. (8) of [Nicholson et al. \(2014b\)](#). For each free mode, the additional fit parameters are A_m , Ω_P and δ_m .

Equation (5) can also be used to describe radial perturbations forced by a Lindblad resonance with an external satellite, in which case the pattern speed, m -value, and phase are all determined by the satellite's orbital parameters; for a first-order Lindblad resonance, Ω_P is equal to the satellite's mean motion. The exact resonance location a_{res} is specified implicitly by Eq. 7. [Porco and Goldreich \(1987\)](#) were the first to compute such satellite resonance locations in the vicinity of the known Uranian rings.

Our final expression for the modeled shape of each ringlet in its orbital plane is

$$r_{\text{mod}}(\lambda, t) = r(\lambda, t) + \sum_{i=1}^M \Delta r(m_i, \lambda, t), \quad (8)$$

where M is the number of modeled free or forced normal modes.

In addition to the kinematical orbit parameters for each ring, the least-squares fit incorporates several fitable physical and geometrical parameters, including the direction of the (possibly precessing) planetary pole, offsets to the catalog positions or proper motions of Earth-based occultation stars (or, alternatively, skyplane offsets to Uranus ephemeris), and time offsets for selected telescope observations. RINGFIT also allows for a variety of weighting schemes, including iteratively computing the weight of each ring's observations from its RMS residuals, or alternatively using the RMS residuals of each separate set of telescope observations to determine the weight of each data point.

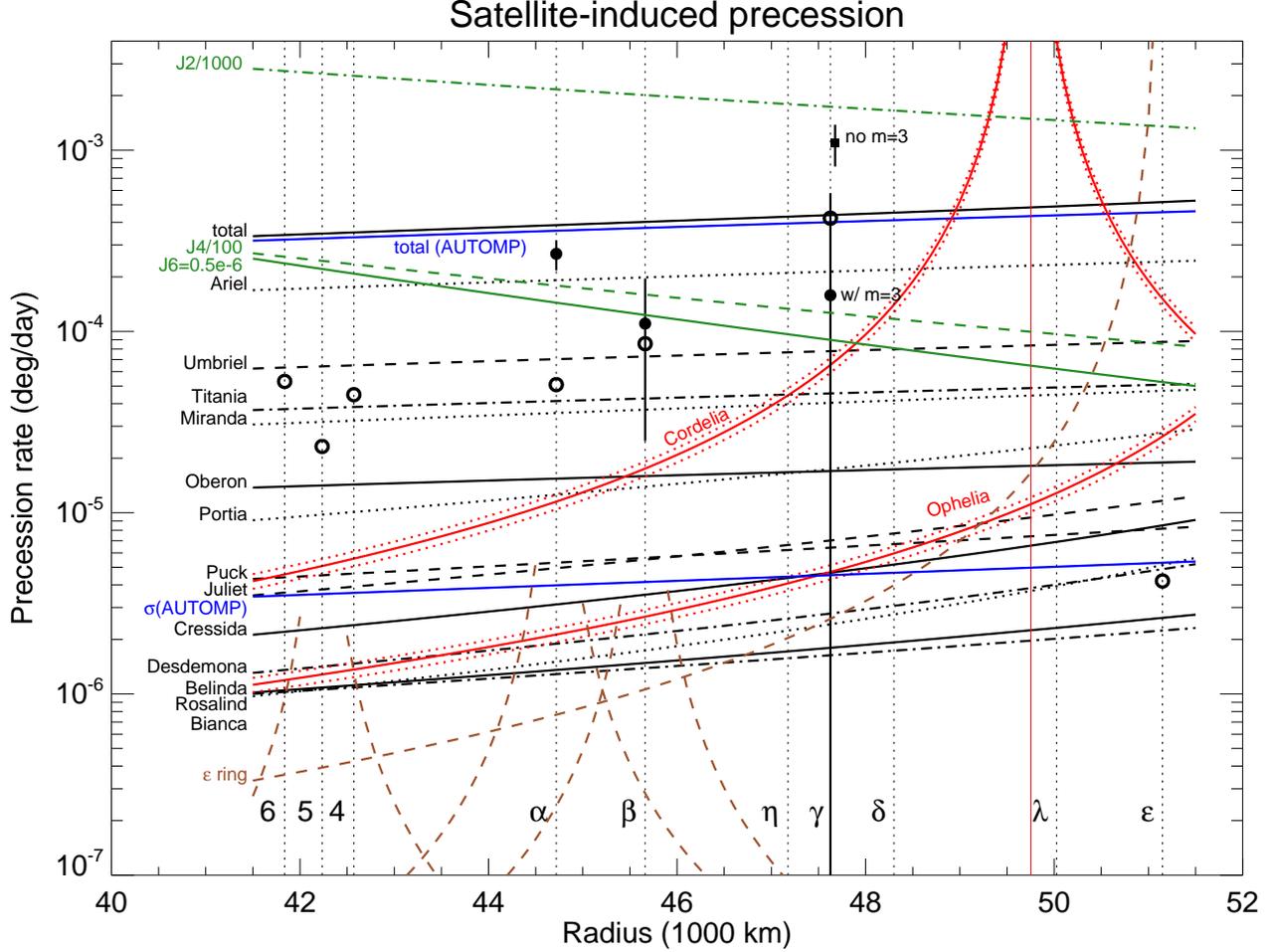


Figure 4. The magnitude of the secular apsidal and nodal precession rates due to Uranus’s satellites, plotted as a function of radius in the vicinity of the ten narrow rings. The black line labeled ‘total’ includes all the satellites except Cordelia and Ophelia, whose individual contributions are plotted as the upper and lower solid red lines, respectively, bracketed by the uncertainties shown by dotted red lines. The blue lines labeled ‘total (AUTOMP)’ and ‘ σ (AUTOMP)’ are the sum of the the satellite-induced precession rates from the six major satellites (Ariel, Umbriel, Titania, Oberon, Miranda, and Puck), and the quadratic sum of their uncertainties, calculated from the uncertainties in their masses (Jacobson 2014). The green lines show the radial dependence of the contributions to the precession rates of the rings by the gravitational coefficients J_2 and J_4 , scaled to be within the vertical range of the plot, and by a representative value of $J_6 = 0.5 \times 10^{-6}$. The filled circles show the inferred anomalous precession rates for the α , β , and γ rings, with error bars indicating their $1\text{-}\sigma$ uncertainties (see Section 8). The filled square shows the inferred anomalous precession rate of the γ ring for an alternate case in which the $m = 3$ mode is omitted from the orbit model. The open circles at the radii of the eccentric rings 6, 5, 4, α , β , and ϵ ring mark the formal uncertainties in their fitted apsidal precession rates. The dashed brown lines centered on the eccentric rings show the estimated magnitude of their contributions to predicted precession rates at nearby radii, for assumed masses of the rings. In all cases, these are quite small, falling below that due to Cressida.

3.3. Ephemerides

For this analysis, we used the recent JPL `ura178.bsp` Uranus satellite ephemerides, the `peph.ura178.bsp` planetary ephemerides, and the associated *Voyager 2* ephemeris `vgr2.ura178.bsp` at Uranus. These ephemerides were updated from the `ura111.bsp`, `ura116.bsp`, `vgr2.ura111.bsp`, and `de440.bsp` series (Jacobson 2014; Park et al. 2021), using constraints provided by the Uranus ring occultation data in Paper 1, excluding the γ and λ rings (Jacobson 2023). For the U0 observations, we used the SPICE kernel described in Paper 1 for the flight path of the Kuiper Airborne Observatory (KAO) during the occultation. The U137 and U138 Uranus ring occultations were observed

using the *HST*, for which we require accurate spacecraft ephemerides to compute the occultation geometry. There are two sources of *HST* ephemerides: JPL’s NAIF website⁴ hosts a single kernel file (`hst.bsp`) that is updated regularly and contains NORAD-provided two-line elements (TLE) that have an estimated accuracy of a few km, and the Space Telescope Science Institute (STScI) hosts individual files provided by the Flight Dynamics Facility at the Goddard Space Flight Center (GSFC). The ephemeris accuracy depends primarily on the level of solar activity, which affects drag, and is estimated to be better than 300 m, under most ranges of solar activity. For our orbit fits, we used the more accurate STScI files, which we converted from their original `*.orx` format to FITS files, using the IRAF task `hstephem`, and then to standard NAIF SPK format using the NAIF tool `mkspk`. The two custom-produced SPK files are `pg3f0000r.bsp` for U137 and `pg490000r.bsp` for U138.

The complete list of kernel files used in our analysis is given in **Table 4**.

Table 4. Spice kernels

File name ^a	Description
<code>pleph.ura178.bsp</code>	Planetary ephemerides, constrained by ring data in Paper 1
<code>ura178.bsp</code>	Major Uranus satellite ephemerides, constrained by ring data in Paper 1
<code>vgr2.ura178.bsp</code>	<i>Voyager 2</i> trajectory at Uranus, constrained by ring data in Paper 1
<code>ura115.bsp</code>	Minor Uranus satellite ephemerides
<code>earthstns_itrf93_040916.bsp</code>	Geocentric coordinates of DSN groundstations
<code>earth_720101_070426.bpc</code>	Earth rotation model
<code>ObsCodes_Uranus_20220212.spk</code>	Custom geocentric observer coordinates
<code>pg3f0000r.bsp</code>	<i>HST</i> ephemeris for U137
<code>pg490000r.bsp</code>	<i>HST</i> ephemeris for U138
<code>urkao_v1.bsp</code>	Custom ephemeris for KAO (U0)
<code>naif0012.tls</code>	leap seconds

^a All kernels listed are available from <ftp://ssd.jpl.nasa.gov/pub/eph> or as part of the Uranus ring occultation support bundle on PDS. See Appendix A of French et al. (2023b).

4. RING ORBIT FITS

The most recent comprehensive model for the orbital elements of the ten narrow Uranian rings was published by French et al. (1988), with updates provided in the review articles by French et al. (1991) and Nicholson et al. (2018a). Subsequently, more recent occultation data were incorporated into orbit models used to determine the geometry of the possible detection of the λ ring during the 1992 Jul 11 occultation of U103 (French et al. 1996), but no details were provided about the updated orbital elements. Jacobson (2014) utilized a subset of the both published and unpublished ring occultation data from 1977–1992 in an updated model for the keplerian orbits of eight of the ten narrow rings (excluding γ and δ , each of which was known to have significant normal modes), the gravity field of the planet, and the orientation of the pole. Finally, the tabulated residuals from an unpublished orbit fit were used by Chancia et al. (2017) to estimate the mass of the moon Cressida from its perturbation on the η ring.

Here, we extend these analyses by utilizing the full set of observations from 1977–2006 documented in Paper 1 to determine the orbital shapes of both the ring midlines and their edges. As a first step, we updated our search for normal modes, as described below.

4.1. Normal Modes

⁴ <https://naif.jpl.nasa.gov/pub/naif/HST/kernels/spk/>

The first evidence for normal modes in narrow ringlets was provided by French et al. (1986), who identified an $m = 2$ ILR in the shape of the δ ring and an $m = 0$ OLR in the shape of the γ ring.⁵ Subsequently, tentative detections of edge waves in the ϵ ring associated with resonances with Cordelia and Ophelia were reported by French and Nicholson (1995), based on a subset of the observations presented here, and Chancia et al. (2017) identified the signature of an $m = 3$ mode in the η ring, forced by Cressida. From the wealth of *Cassini* occultation observations, a host of free and forced normal modes have also been identified in Saturn’s ringlets and sharp ring edges, sometimes in astonishing numbers: the informally-designated “Strange” ringlet in the Cassini Division is both eccentric and inclined and has seven normal modes, and the inner edge of the Barnard Gap has 11 (French et al. 2016b)! (For a recent review of observations of narrow rings, gaps, and sharp edges at Saturn, Uranus, and Neptune, see Nicholson et al. (2018b) and references therein; for a detailed modern exposition of the theory of narrow rings and sharp edges, see Longaretti (2018).)

In our search for normal modes in the Uranian rings, we focus on the measured locations of the center of each ring (COR), although as noted above, dynamical arguments suggest that ILRs should be associated with outer edges of rings (OER) and OLRs with inner edges (IER). For ringlets only a few km wide, these distinctions may be unwarranted, and in any event the measurement of the COR from a square-well fit is necessarily affected by the locations of the IER and OER, each of which might be distorted by a local normal mode. Additional evidence for normal modes in the Uranian rings is provided by periodic azimuthal brightness variations in the rings in *Voyager* (Hedman et al. 2023) and *HST* images (Showalter 2011).

Our general procedure for identifying free and forced normal modes is as follows: For each ring feature (COR, IER, or OER), we begin with the best-fitting keplerian ellipse model and then scan the residuals over a range of pattern speeds Ω_P and candidate wavenumbers from $m = 1$ to $m = 30$ for ILR-type perturbations, and from $m = 0$ to $m = -30$ for OLR-type perturbations, solving for the best-fitting amplitude A_m and phase δ_m at each pattern speed. The range of values scanned for Ω_P for each mode is centered on the predicted value for the semimajor axis of the ring feature, based on Eq. 7, and is sufficiently broad to provide a sampling of the statistical significance of a putative detection. (In Section 4.5, we make use of similar information to set detection limits on the eccentricities and inclinations of some of the rings.) We then add the statistically significant detected modes to the kinematical model of the ring feature, fit for their amplitudes, pattern speeds and phases, and form a new set of residuals. We repeat the frequency scanning process to search for additional weaker modes. With the addition of successive normal modes, the RMS residual is reduced and the sensitivity to even weaker modes is increased.

We now describe the normal modes detected in this systematic search (none were identified at a statistically significant level for rings 6, 5, 4, α , β , or λ).

4.1.1. The η ring

The very narrow core of the η ring has no measurable eccentricity or inclination, but a normal mode scan reveals the presence of a forced $m = 3$ mode associated with Cressida, as first reported by Chancia et al. (2017). **Figure 5** shows the η ring COR $m = 3$ normal mode scan based on our complete set of observations. The pattern speed Ω_P for the best fit is displaced from the expected value for a free normal mode, and instead matches the mean motion of Cressida, as expected for a first-order Lindblad resonance. (We present quantitative results for this and other mode searches below, once all identified modes have been incorporated into our final orbit models for ring midlines and edges.) No other η ring normal modes were detected at a statistically significant level.

4.1.2. The γ ring

⁵ French et al. (1986) interpreted the δ and γ ring modes as being forced by unseen satellites because the pattern speeds differed measurably from the expected values for free normal modes located at the semimajor axes of the rings, but in retrospect this was based on an a value of GM for Uranus that subsequently proved to be in error by five times its estimated formal error. With an improved determination of GM , the resonance radii of the modes closely matched the semimajor axes of the rings, as expected for free normal modes unassociated with satellites.

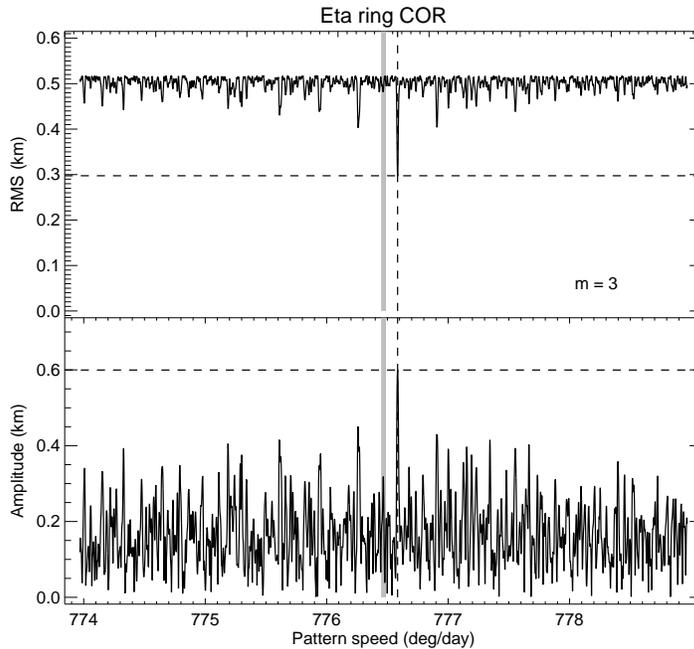


Figure 5. Normal mode scan of the η ring COR for $m = 3$. Upper panel: RMS residual as a function of Ω_P , centered on the predicted value for an $m = 3$ ILR, marked by a thick vertical gray line. The best-fitting pattern speed Ω_P (dashed vertical line) is faster than the predicted value, and matches the mean motion of Cressida. Lower panel: amplitude A_3 of the fitted $m = 3$ mode for each pattern speed. Our final orbit fit gives $A_3 = 0.600 \pm 0.069$ km, very similar to the result from the normal mode scan.

Unlike the δ and η rings, the γ ring is measurably eccentric, as demonstrated by the $m = 1$ COR normal mode scan of the residuals to a circular orbit model in **Fig. 6**. Here, no other modes are included, and the minimum RMS residual is quite large: 4.0 km. The best-fitting amplitude $A_1 = 4.94$ km from the scan, and the corresponding pattern speed marked by a vertical dashed line is very slightly faster than the predicted value for the ring’s semimajor axis. We will return to this disagreement in Section 7.2, where we determine Uranus’s gravity field from the observed apsidal and nodal precession rates of the rings.

The $m = 0$ normal mode amplitude is roughly equal to the $m = 1$ mode amplitude, as seen in the γ ring COR $m = 0$ normal mode scan (**Fig. 7**). Here, the best-fitting $m = 1$ mode from the final orbit fit has been included prior to the scan. (The upper limit to the RMS residual in the upper panel in this case is 4.2 km, a bit larger than in **Fig. 6** owing to the slightly different best-fitting keplerian ellipses in the two cases.)

We extended our search for γ ring normal modes over the range $m = -30$ to 30, and we successively added each statistically significant mode to our RINGFIT model and repeated the search for additional modes until none were found. To illustrate the signatures of the additional detected γ ring normal modes, the best fitting final model for all other detected modes was subtracted from the measured radii prior to performing the normal mode scans shown in each figure below. We present these in decreasing order of fitted mode amplitude A_m . Our search yielded the detection of the γ ring $m = -1$ OLR. Note that Eq. (7) implies that $\Omega_P \sim 2n \sim 2290^\circ \text{d}^{-1}$, much greater than the $m = 1$ apse rate $\dot{\varpi} \simeq 1.751^\circ \text{d}^{-1}$. The corresponding normal mode scan is shown in **Fig. 8**. The best-fitting pattern speed is slightly faster than that predicted for a free $m = -1$ mode at the COR, and the corresponding resonance radius is therefore somewhat interior to the midline of the ring. This is consistent with the anticipated association of OLRs with inner ring edges. The fitted amplitude $A_{-1} = 1.822 \pm 0.067$ km from our final orbit solution. In this and subsequent cases, the normal mode scans give slightly different values for the fitted amplitudes compared to our final orbit fit because the normal mode scans allow for an additional fitted parameter of a radial offset from the ring

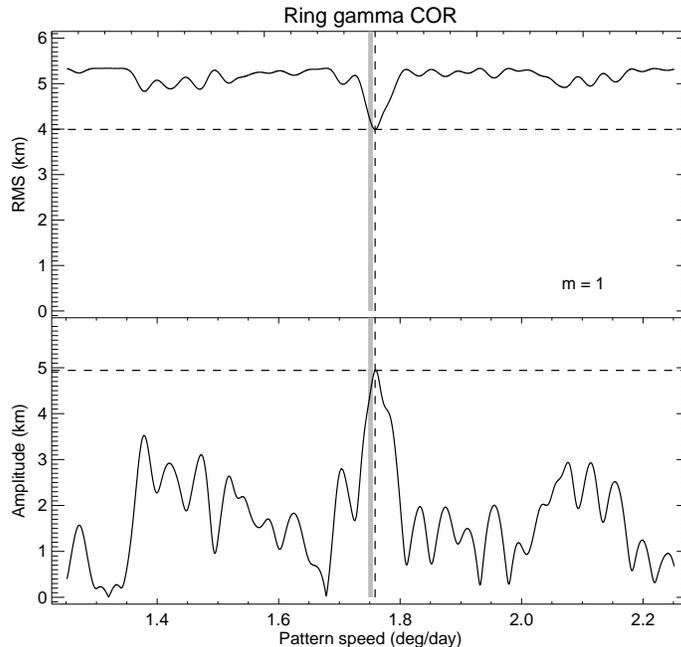


Figure 6. Normal mode scan of the residuals to a circular model for the γ ring COR for $m = 1$. Upper panel: RMS residual as a function of Ω_P , centered on the predicted value for an $m = 1$ ILR, marked by a thick vertical gray line. Lower panel: amplitude A_1 of the fitted $m = 1$ mode for each pattern speed. The best-fitting model based on this normal mode scan has $A_1 = 4.78$ km, compared to the final value $A_1 = 5.509 \pm 0.076$ km when all detected normal modes are included.

midline or edge, while in the final orbit fit all modes are constrained to be centered on the corresponding midline or edge.

We identified a second OLR in the γ ring’s midline: the $m = -2$ normal mode shown in **Fig. 9**. Once again, the best-fitting Ω_P is slightly faster than the predicted value for the COR, indicating that the resonance radius is interior to the COR as expected for an OLR. This mode is somewhat weaker than the $m = -1$ mode, with a fitted amplitude $A_{-2} = 0.690 \pm 0.076$ km from our final orbit solution.

We also detected the $m = 6$ ILR forced by Ophelia. **Figure 10** shows the γ ring COR $m = 6$ normal mode scan, with a clear offset in the best-fitting Ω_P compared to the predicted value for the ring’s semimajor axis, indicating that the resonance location is interior to the centerline of the ring. The best-fitting model has $A_6 = 0.637 \pm 0.063$ km from our final orbit solution. Similar scans (not shown) confirm that the $m = 6$ mode is also present on both ring edges.

Finally, there is evidence for a free $m = 3$ ILR with a resonance location near the outer edge of the γ ring. The normal mode scan is shown in **Fig. 11**. The best-fitting pattern speed corresponds to a resonance location exterior to the outer edge of the ringlet. There is no known satellite with the appropriate orbit to force this mode, and to assess the statistical significance of the detection, we performed a scan over a very wide range of pattern speeds. The two left panels of the figure show that the best-fitting normal mode lies very close to the predicted pattern speed and that there are no comparably strong aliases over the large range of pattern speeds considered. The upper right panel shows a histogram of the RMS residuals for all of the individual pattern speeds in the normal mode scans at left, plotted as the number of results N per bin of width 0.0005 km, with an arrow marking the value for the candidate $m = 3$ mode near the ring center. The lower right panel shows a similar histogram of the best-fitting amplitude for each pattern speed, showing the number of results N per bin of width 0.0018 km. Again, the arrow marks the candidate mode, which is well above the noise threshold.

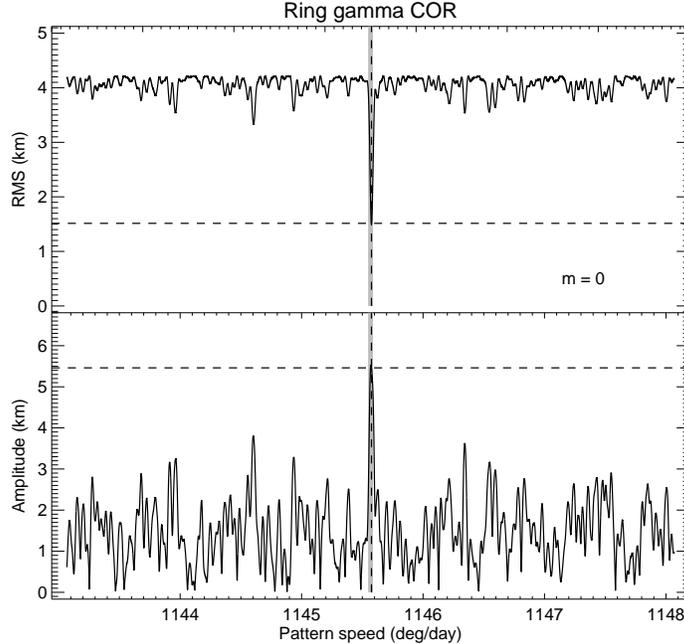


Figure 7. Normal mode scan of the γ ring COR for $m = 0$, after inclusion of best-fitting $m = 1$ mode from adopted orbit solution. Upper panel: RMS residual as a function of Ω_P , centered on the predicted value for an $m = 0$ OLR, marked by a thick vertical gray line. Lower panel: amplitude A_0 of the fitted $m = 0$ mode for each pattern speed. The best-fitting model has $A_0 = 5.509 \pm 0.076$ km from our final orbit solution.

The amplitude of the $m = 3$ mode is even stronger on the outer edge of the γ ring, as shown from the normal mode scan shown in **Fig. 12**, where we again have scanned over a wide range of pattern speeds. In this case (as for other ring edges), the RMS residuals are larger than for the COR normal mode scans because the fitted ring widths from the square-well model are less accurate than the ring midlines, as discussed above. On the other hand, we found no evidence for an $m = 3$ mode near the γ ring’s inner edge – the corresponding normal mode scan is shown in **Fig. 13**. As we discuss below, including the $m = 3$ mode not only reduces the RMS residuals of the COR fit but also reduces the inferred anomalous precession rate of the γ ring.

4.1.3. The δ ring

The δ ring has no detectable eccentricity or inclination, but the RMS residual of a circular orbit model is 2.35 km, nearly ten times that of the eccentric and inclined mode-free rings 6, 5, and 4, indicative of an unmodeled strong perturbation in the ring’s shape. In previous orbit models, this was attributed to an $m = 2$ mode, and this signature is clearly present in the normal mode scan shown in **Fig. 14**. The upper panel shows a sharp decrease in the RMS error at the predicted pattern speed for the semimajor axis of the ring, marked by a solid vertical line. The best-fitting Ω_P is marked by a solid dashed line, which in this case coincides with the predicted value. The lower panel shows the fitted amplitude of the normal mode at each assumed pattern speed in the scan, with a best-fitting value $A_2 \simeq 3.2$ km.

After including the free parameters for the $m = 2$ mode of the δ ring, we formed a new set of residuals and repeated the normal mode scan for the same set of possible wavenumbers. The results of this search revealed a weak but statistically significant $m = 23$ mode in the COR data, shown in **Fig. 15**. The RMS residual is further reduced and the fitted amplitude $A_{23} \simeq 0.34$ km in the normal mode scan (similar to $A_{23} = 0.339 \pm 0.063$ km from our final orbit fit). The pattern speed is slower than that expected for a free $m = 23$ mode located at the semimajor axis of the COR, and the corresponding resonance radius is somewhat exterior to the ring midline. Instead, the pattern speed and phase of the observed $m = 23$ mode match the orbital characteristics of Cordelia, as originally proposed by [Chancia et al.](#)

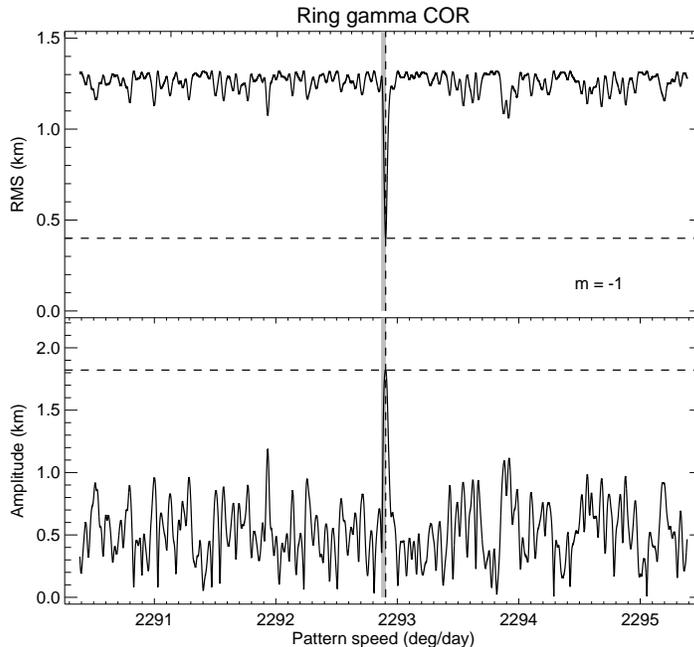


Figure 8. Normal mode scan of the γ ring COR for $m = -1$, after inclusion of modes $m = -2, 0, 1, 3$, and 6 from adopted orbit solution. Upper panel: RMS residual as a function of Ω_P , centered on the predicted value for an $m = -1$ OLR, marked by a thick vertical gray line. Lower panel: amplitude A_{-1} of the fitted $m = -1$ mode for each pattern speed. The best-fitting model has $A_{-1} = 1.822 \pm 0.067$ km from our final orbit solution.

(2017), who calculated the expected normal mode amplitude A_{23} for a range of assumed satellite masses and densities. Normal mode scans of δ ring IER and OER showed no detection of the $m = 23$ mode on either ring edge near the expected pattern speed, but the RMS noise level in these scans was substantially greater than the observed amplitude at the ring centerline, so the non-detections are not surprising. A search for the $m = 23$ mode in the width of the ring itself was also negative. No other δ ring normal modes were detected at a statistically significant level.

4.1.4. The ϵ ring

The inner and outer edges of the ϵ ring have long been associated with the nearby $m = -24$ OLR with Cordelia and the $m = 14$ ILR with Ophelia, respectively (Porco and Goldreich 1987). Chancia et al. (2017) showed that, for reasonable assumptions about the masses of the two satellites, the expected amplitudes of the corresponding edge waves would lie in the range $A_{-24} = 0.4 - 1.0$ km for the inner edge (IER) and a somewhat weaker $A_{14} = 0.25 - 0.7$ km at the OER. As noted above, French and Nicholson (1995) found tentative evidence for these edge waves. **Figure 16** shows the results of the $m = 14$ ILR normal mode scan of the ϵ ring OER. There is a convincing minimum in the RMS residuals at a pattern speed a bit faster than the value predicted for the ring edge, indicating that the resonance lies slightly interior to the outer edge. **Figure 17** shows the results of the $m = -24$ OLR normal mode scan of the ϵ ring IER. In this case, the best-fitting pattern speed is near Cordelia’s mean motion $\Omega_P \simeq 1074.52 \text{ }^\circ \text{ d}^{-1}$ and is slightly slower than that expected at the exact ring edge, indicating that the resonance is located within the ring itself, near the inner edge.

In Section 9, we confirm the association of these two normal modes with Cordelia and Ophelia on the basis of the fitted phases, pattern speeds, and amplitudes of the ϵ ring IER and OER edge waves compared to the expectations from satellite ephemerides, using the full set of observations reported here.

4.1.5. Signatures of the ϵ ring edge waves in the shape of the ring midline

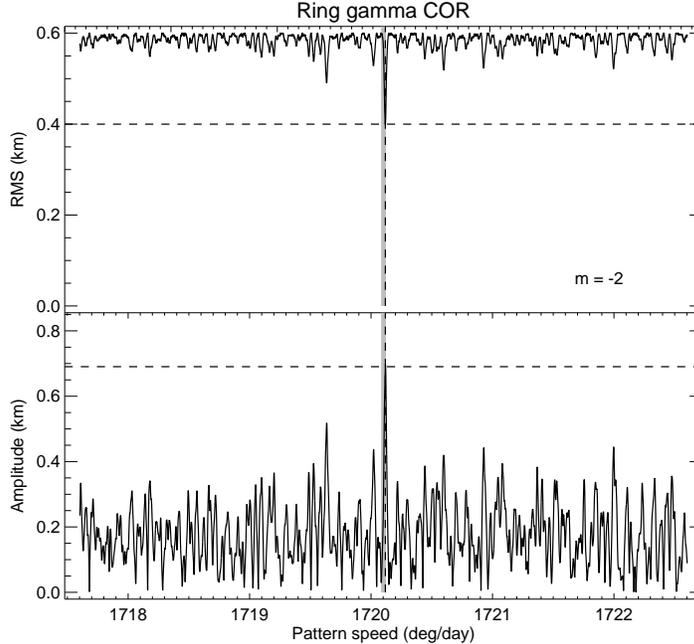


Figure 9. Normal mode scan of the γ ring COR for $m = -2$, after inclusion of modes $m = -1, 0, 1, 3$, and 6 from adopted orbit solution. Upper panel: RMS residual as a function of Ω_P , centered on the predicted value for an $m = -2$ OLR, marked by a thick vertical gray line. Lower panel: amplitude A_{-2} of the fitted $m = -2$ mode for each pattern speed. The best-fitting model has $A_{-2} = 0.690 \pm 0.076$ km from our final orbit solution.

While these normal modes are forced at the *edges* of the relatively wide ϵ ring and their dynamical influence might well be restricted to the immediate vicinity of the edges, the measured centerline of the ring should be offset by approximately one half of the sum of the local radial amplitudes of the two edge modes. We performed normal mode scans on the ϵ ring COR radius residuals for $m = 14$ and $m = -24$ and found weak but secure signatures of both modes, with the measured phases and pattern speeds being in excellent agreement with the values found at the corresponding ring edges, as discussed below in Section 9. **Figure 18** shows the results for $m = 14$ COR scan. Here, the vertical dashed line shows the best-fitting pattern speed near the value from our final orbit fit $\Omega_P = 956.418051 \pm 0.000269^\circ \text{ d}^{-1}$, close to the mean motion of Ophelia, with an amplitude $A_{14} = 0.383 \pm 0.071$ km, a bit more than half that at the OER, for which $A_{14} = 0.590 \pm 0.130$ km. **Figure 19** shows the results for the $m = -24$ COR scan. Here, the vertical dashed line is near the best-fitting $\Omega_P = 1074.522703 \pm 0.000142^\circ \text{ d}^{-1}$, very close to the mean motion of Cordelia (see Table 20), with an amplitude $A_{-24} = 0.443 \pm 0.061$ km from our final orbit fit, a bit less than half that at the IER, for which $A_{-24} = 1.011 \pm 0.107$ km.

4.1.6. Searches for other normal modes

We performed an orbit fit that included all of the normal modes identified above and used normal mode scans for wavenumbers between $m = -30$ and 30 to search for evidence of any additional statistically significant detections in the orbit fit residuals near the predicted pattern speeds, for all ring widths, edges and midlines. None were found. [Chancia et al. \(2017\)](#) identified two weak first-order resonances with predicted amplitudes $A_m \sim 0.1$ km for assumed moonlet densities $\rho = 0.9 \text{ g cm}^{-3}$: the 13:12 Cordelia resonance with the η ring and the 2:1 Portia resonance with ring 6. Our $3\text{-}\sigma$ detection limits for these modes are 0.204 km and 0.168 km, respectively, based on Rayleigh distribution fits to the amplitudes in the corresponding normal mode scans, placing them just out of reach for secure identification in our observations.

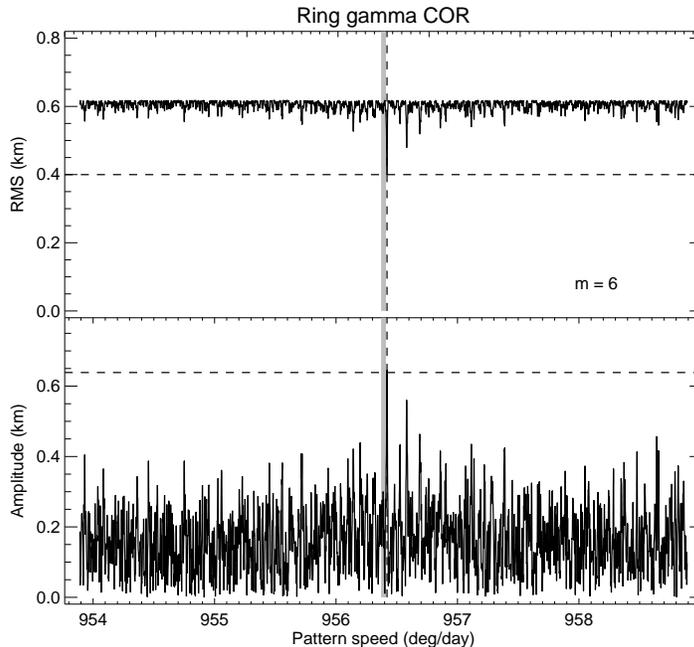


Figure 10. Normal mode scan of the γ ring COR for $m = 6$, forced by Ophelia, after inclusion of modes $m = -2, -1, 0, 1,$ and 3 from adopted orbit solution. Upper panel: RMS residual as a function of Ω_P , centered on the predicted value for an $m = 6$ ILR, marked by a thick vertical gray line. Lower panel: amplitude A_6 of the fitted $m = 6$ mode for each pattern speed. The best-fitting model has $A_6 = 0.637 \pm 0.063$ km from our final orbit solution.

Internal planetary oscillations provide another possible source for normal modes in the rings. Saturn’s C and B rings provide a tapestry revealing dozens of such signatures in occultation profiles (Rosen et al. 1991; Colwell et al. 2009; Baillié et al. 2011; Hedman and Nicholson 2013, 2014; French et al. 2019; Hedman et al. 2019; French et al. 2021; Hedman et al. 2022). Although the Uranus system of narrow rings provides incomplete radial coverage for possible modes, Saturn’s Maxwell ringlet – very similar in structure to the Uranus ϵ ring – is home to an $m = 2$ mode forced by Saturn’s internal oscillations, and provides an example of a narrow ringlet located precisely at the mode’s resonance radius (French et al. 2016a). As part of our normal mode survey, we searched for evidence of distortions in the shapes of the ring midlines and edges near the predicted values for wavenumbers and pattern speeds excited by resonances with fundamental Uranus normal modes (A’Hearn et al. 2022). We found no statistically significant matches with radial amplitudes $\Delta A_m > 0.2$ km, but the possibility remains that internal oscillations can reveal their presence in azimuthal variations in ring brightness seen in images, an important task for the future.

4.2. Adopted ring orbital elements and normal modes

Having characterized a set of detected normal modes, we then solved for the ring orbital elements and Uranus system geometry iteratively and in several stages, taking into account the greater accuracy of the ring midline measurements than those of the ring edges. We first used the COR (ring midline) observations to fit for the planet’s pole direction, time offsets for selected stations, and corrections to selected occultation star positions and proper motions, in addition to the orbital elements and normal modes of the nine principal rings. Next, we fitted separately for the IER/OER orbital elements and normal modes only, using the fitted widths and mid-times and assuming the system geometry, star positions, and station offset times established by the COR fit. Finally, we solved for the best circular orbit model for the λ ring and the skyplane offset positions of the secondary stars in the multiple-star U36 occultation and the binary star U102 occultation.

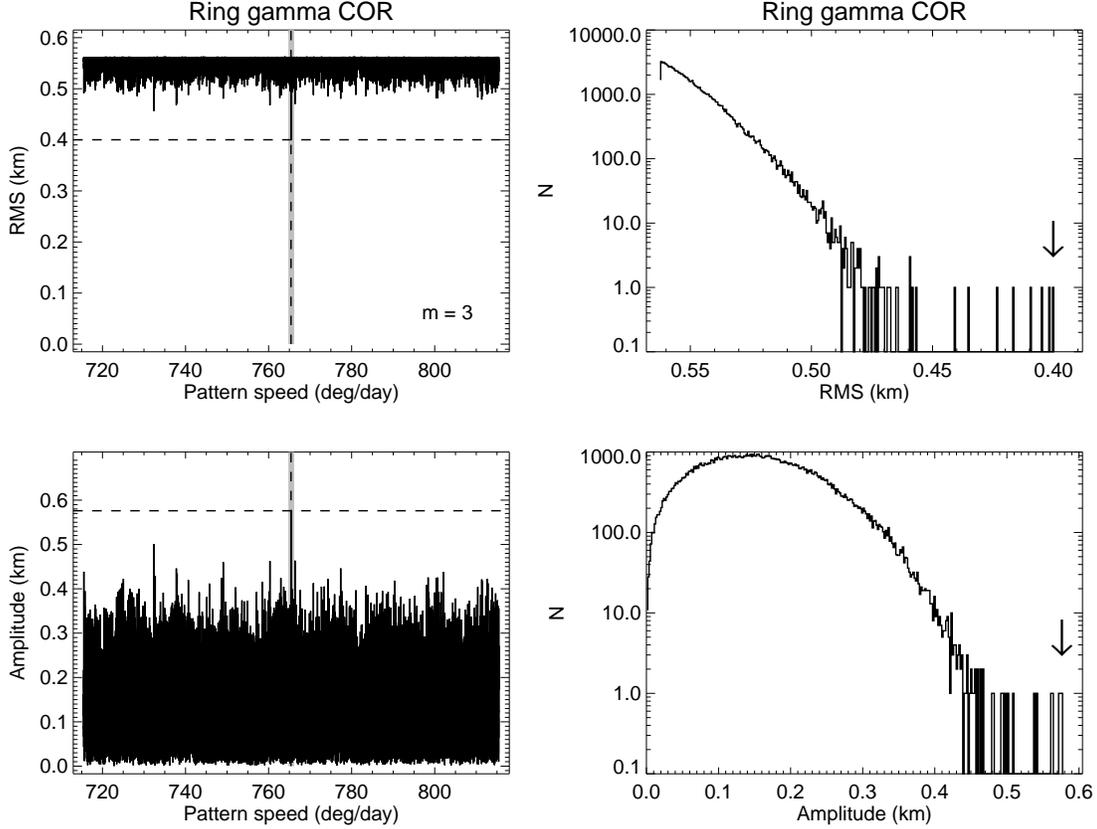


Figure 11. Normal mode scan of the γ ring COR for $m = 3$, performed over a wide range of pattern speeds to illustrate the statistical significance of the detection near the expected pattern speed. See text for details.

The combined results of the separate unweighted COR and IER/OER orbit fits for the ten narrow rings are given in **Tables 5** and **6**. For these fits, the apsidal precession and nodal regression rates $\dot{\varpi}$ and $\dot{\Omega}$ were included as separate free parameters for the rings with measurable eccentricity and inclination, respectively, rather than being constrained by the gravitational field of Uranus and the secular precession due to the satellites. We will return to these contributions below, when we evaluate the evidence for anomalous forced precession of individual rings and set constraints on J_2 , J_4 , and J_6 from the COR observations. Similarly, all normal mode pattern speeds and longitudes at epoch were included as separate free parameters, even for modes identified as being forced by Cressida, Cordelia, and Ophelia. Table 5 lists the fitted keplerian orbital elements to N ring event times for the IER/COR/OER of each ring, in increasing order of semimajor axis. (For the γ ring COR, we include the results of the nominal fit that includes the $m = 3$ mode as well as the alternate fit in which the $m = 3$ mode is omitted.) All errors listed are $1\text{-}\sigma$ formal errors from the separate unweighted least-squares fits for the COR observations and for the IER/OER data (which include the fitted ring widths from the square-well models discussed in Appendix A). Eccentricities ae and inclinations $a \sin i$ in square brackets were held fixed during orbit determination. The epoch of the fit t_0 is TDB 1986 Jan 19 12:00, near the time of the *Voyager 2* encounter with Uranus, chosen to be near the mid-point of the time interval of the entire set of observations so as to minimize the correlations between the fitted apse and node rates and the longitudes at epoch.⁶

The entries $\Delta\dot{\varpi}$ and $\Delta\dot{\Omega}$ are the differences between the observed apse and node rates and the predicted values computed for the fitted geometric semimajor axis a of the given feature. The predicted rates take into account the estimated secular apse or node precession due to both major and minor satellites.⁷ The entries $\Delta a_{\dot{\varpi}}$ and $\Delta a_{\dot{\Omega}}$ are

⁶ This is the same epoch used by Jacobson (2014, 2023).

⁷ The predicted rates tabulated here are based solely on the planet’s gravitational field and the satellite-induced precession. As discussed in Section 7.1, in solving for the gravitational field, we take into account the estimated difference between the semimajor axes of the geometric centers of the rings and their estimated radially averaged centers of mass. For a normal mode forced by a satellite, the predicted mode pattern speed corresponds to the satellite’s mean motion. We discuss these forced modes in Section 9.

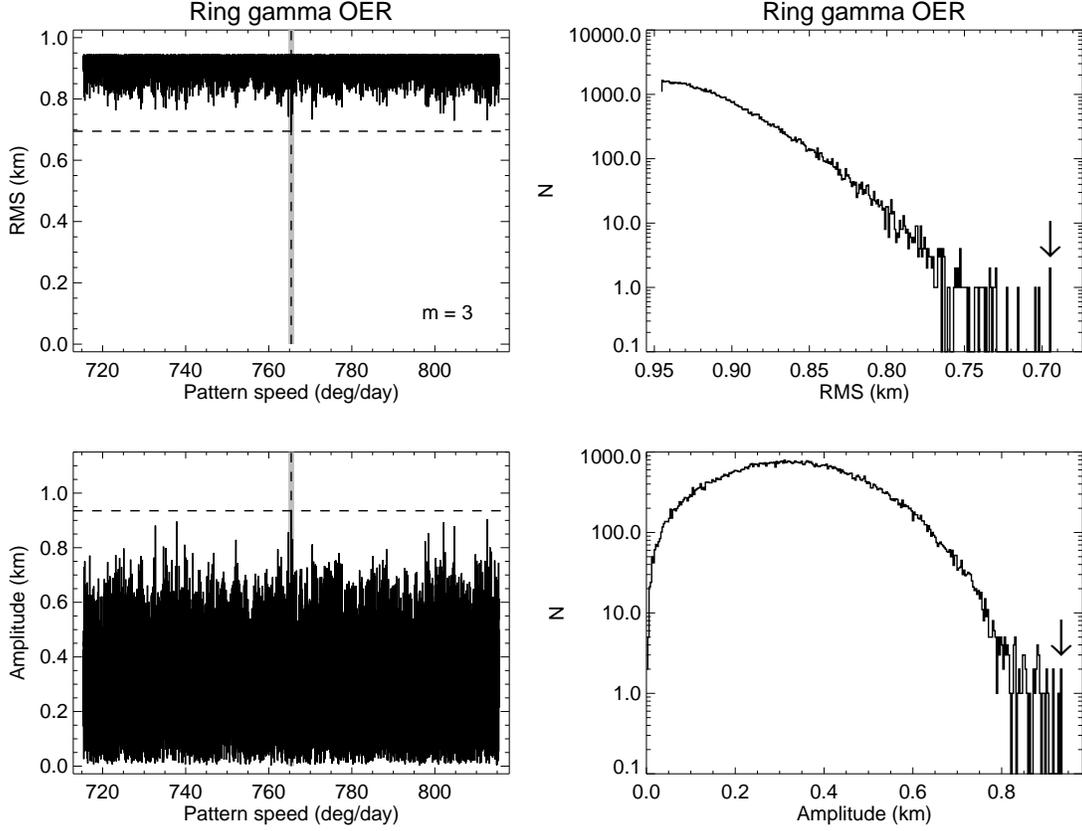


Figure 12. Normal mode scan of the γ ring OER for $m = 3$, performed over a wide range of pattern speeds to illustrate the statistical significance of the detection near the expected pattern speed for the rings's outer edge.

the corresponding differences for the fitted apse and node rates $\dot{\varpi}$ and $\dot{\Omega}$. In practice, we compute these iteratively to high precision, but they can be estimated to reasonable accuracy for $\Delta a_{\dot{\varpi}}$ and $\Delta a_{\dot{\Omega}}$ of order a few km from the linear approximations:

$$\Delta a_{\dot{\varpi}} \simeq \frac{\dot{\varpi}(\text{observed}) - \dot{\varpi}(\text{predicted})}{d\dot{\varpi}/da} = \frac{\Delta \dot{\varpi}}{d\dot{\varpi}/da} \quad (9)$$

and

$$\Delta a_{\dot{\Omega}} \simeq \frac{\dot{\Omega}(\text{observed}) - \dot{\Omega}(\text{predicted})}{d\dot{\Omega}/da} = \frac{\Delta \dot{\Omega}}{d\dot{\Omega}/da}. \quad (10)$$

Since $d\dot{\varpi}/da \propto -J_2 a^{-9/2} < 0$ and $d\dot{\Omega}/da \propto +J_2 a^{-9/2} > 0$, $\Delta \dot{\varpi}$ and $\Delta a_{\dot{\varpi}}$ have opposite signs, while $\Delta \dot{\Omega}$ and $\Delta a_{\dot{\Omega}}$ have the same signs.

Table 6 lists the fitted amplitudes A_m , phases δ_m , and pattern speeds Ω_P for all detected normal modes. For the γ ring, we include the results of two separate fits, one that included the suspected $m = 3$ mode and one in which that mode is omitted. The quantity $\Delta \Omega_P$ is the difference between the fitted pattern speed and the predicted value computed for the fitted geometric semimajor axis a (Table 5) and our adopted gravity field of the planet and satellites; Δa_{Ω} is the corresponding difference between the geometric semimajor axis and the predicted resonance radius for the fitted pattern speed, with the linear approximation:

$$\Delta a_{\Omega_P} \simeq \frac{\Omega_P(\text{observed}) - \Omega_P(\text{predicted})}{d\Omega_P/da} = \frac{\Delta \Omega_P}{d\Omega_P/da}. \quad (11)$$

From Eq. (7), $d\Omega_P/da \propto -(m-1)a^{-5/2}$, so the sign of Δa_{Ω_P} depends on both the sign of $(m-1)$ and the sign of $\Delta \Omega_P$.

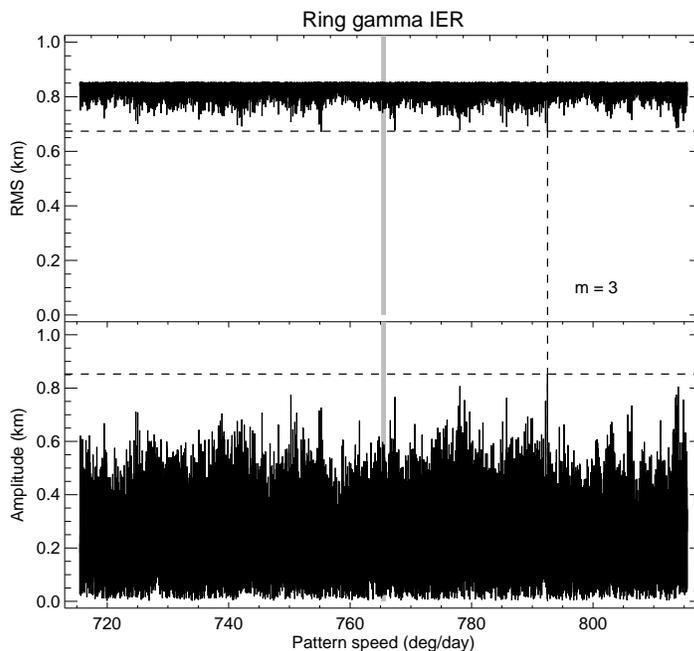


Figure 13. Normal mode scan of the γ ring IER for $m = 3$, showing no evidence for the mode in the vicinity of the expected pattern speed for this ring edge, shown as a thick vertical gray line.

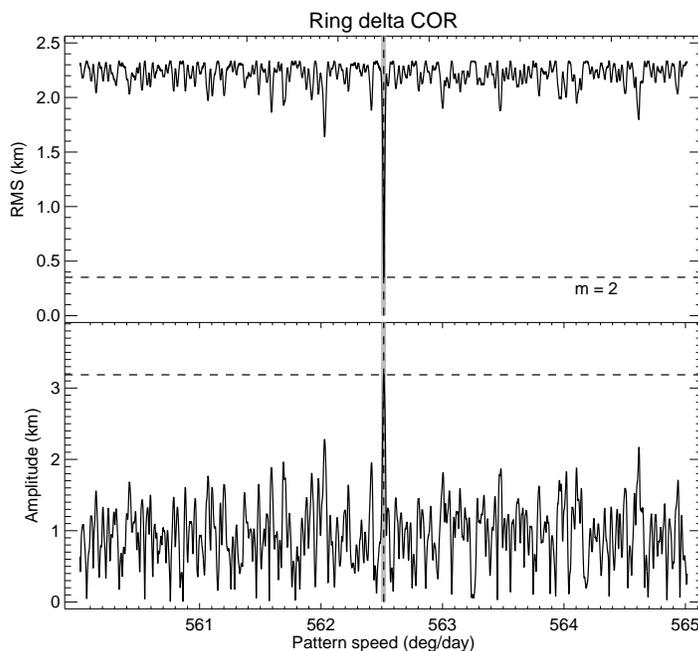


Figure 14. Normal mode scan of the δ ring COR for $m = 2$. Upper panel: RMS residual as a function of Ω_P , centered on the predicted value for an $m = 2$ ILR, marked by a thick vertical gray line. Lower panel: amplitude A_2 of the fitted $m = 2$ mode for each pattern speed. The best-fitting amplitude from the normal mode scan is $A_2 = 3.2$ km; from our final orbit fit, $A_2 = 3.169 \pm 0.059$ km.

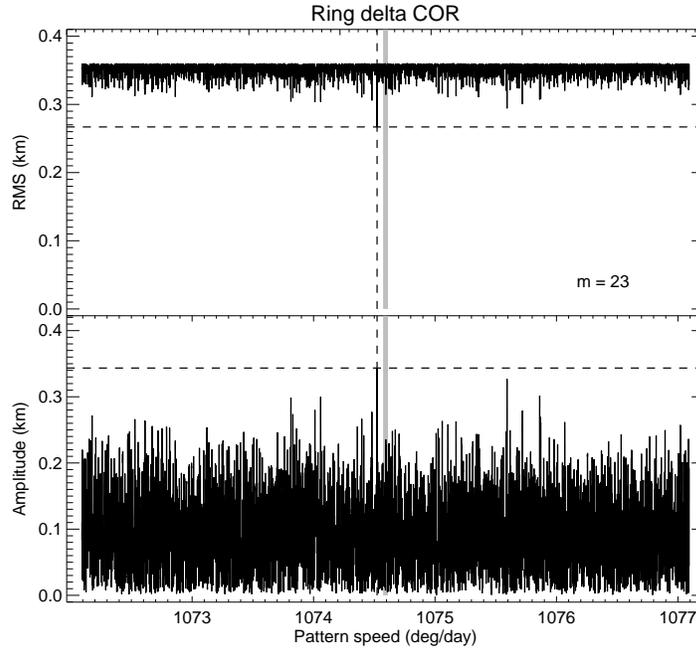


Figure 15. Normal mode scan of the δ ring COR for $m = 23$. Upper panel: RMS residual as a function of Ω_P , centered on the predicted value for an $m = 23$ ILR, marked by a thick vertical gray line. The best-fitting pattern speed Ω_P (dashed vertical line) is slower than the predicted value but matches the mean motion of Cordelia $\Omega_P = 1074.52^\circ \text{ d}^{-1}$. Lower panel: amplitude A_{23} of the fitted $m = 23$ mode for each pattern speed. The best-fitting normal mode scan value is $A_{23} = 0.34 \text{ km}$, close to the value from the final orbit fit of $A_{23} \simeq 0.339 \pm 0.063$.

We will make use of these relations in Section 6, when we examine the width, shape, and differential precession of the rings.

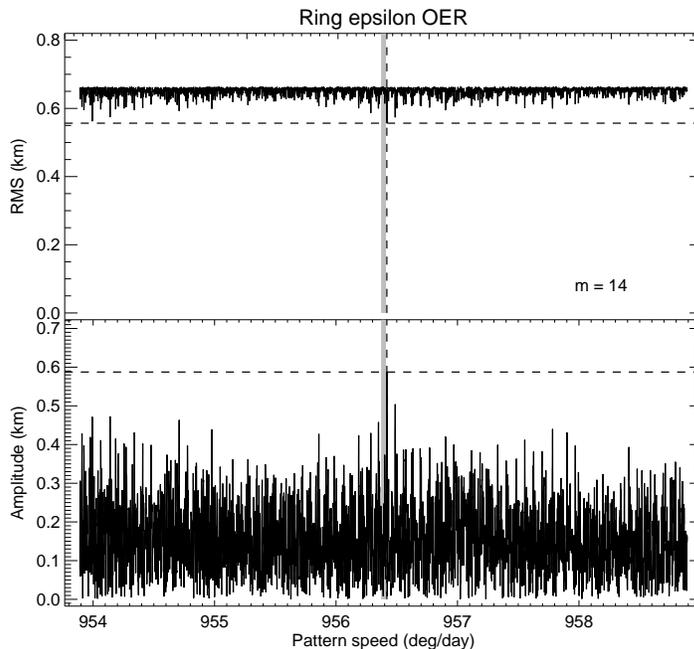


Figure 16. Normal mode scan of ϵ ring OER for $m = 14$, showing a minimum in the RMS residuals with amplitude $A_{14} \simeq 0.60$ km at a pattern speed near that of Ophelia's mean motion $\Omega_P \simeq 956.42$ $^{\circ}$ d^{-1} and slightly faster than that expected at the ring's outer edge (thick gray line).

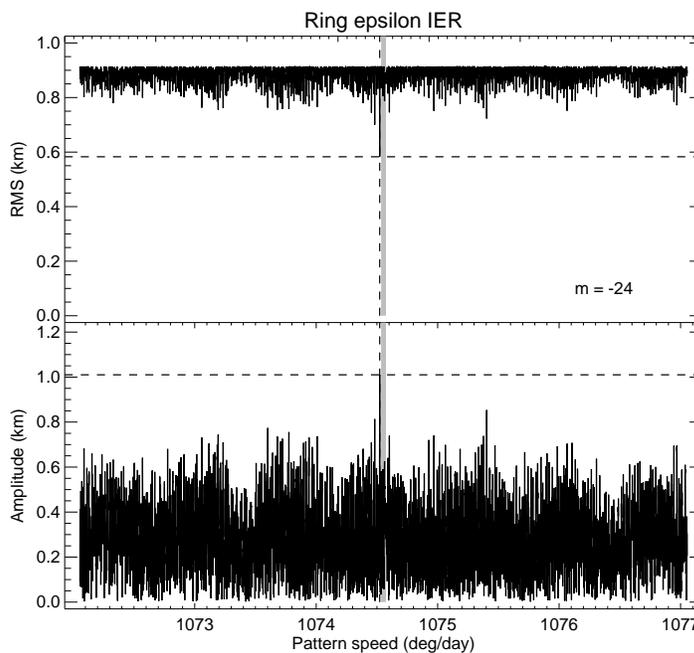


Figure 17. Normal mode scan of ϵ ring IER for $m = -24$, showing a minimum in the RMS residuals with amplitude $A_{-24} \simeq 1.0$ km at a pattern speed near that of Cordelia's mean motion $\Omega_P \simeq 1074.52$ $^{\circ}$ d^{-1} , and slightly slower than that expected at the ring's inner edge (thick gray line).

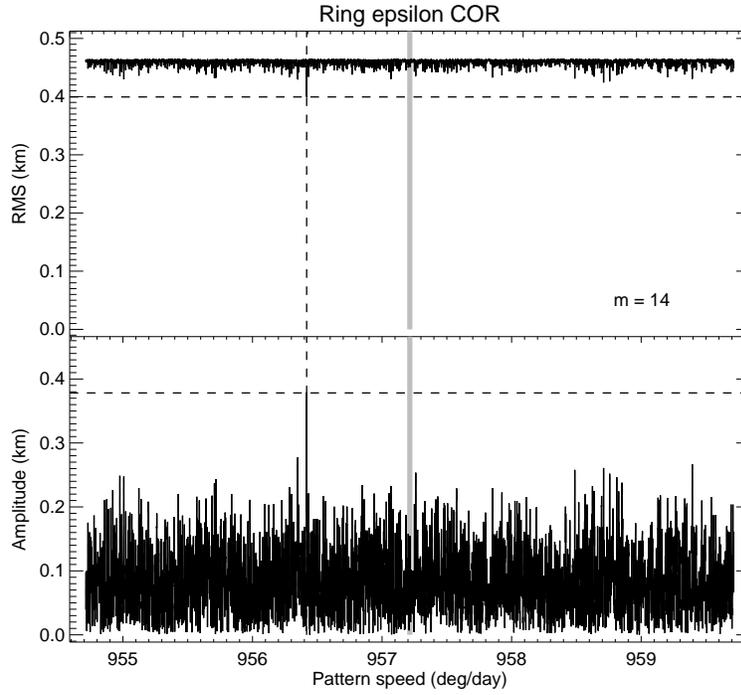


Figure 18. Normal mode scan of the ϵ ring COR for the $m = 14$ mode forced by Ophelia. The best-fitting pattern speed $\Omega_P = 956.418051 \pm 0.000269 \text{ }^\circ \text{ d}^{-1}$, close to the mean motion of Ophelia.

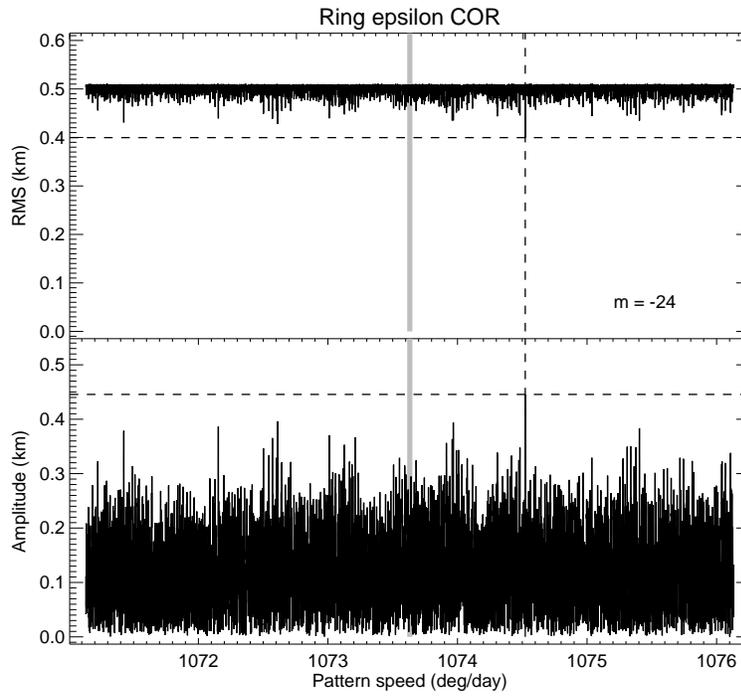


Figure 19. Normal mode scan of the ϵ ring COR for the $m = -24$ mode forced by Cordelia. The best-fitting $\Omega_P = 1074.522703 \pm 0.000142 \text{ }^\circ \text{ d}^{-1}$, close to the mean motion of Cordelia.

Table 5. Uranian ring keplerian orbital elements

Ring	Feature ^(a)	a (km)		ae (km)	ϖ_0 ($^\circ$) ^(b)		$\dot{\varpi}$ ($^\circ$ d ⁻¹)	$\Delta\dot{\varpi}$ ($^\circ$ d ⁻¹)	$\Delta a_{\dot{\varpi}}$ (km)
		N	RMS (km)	$a \sin i$ (km)	Ω_0 ($^\circ$)	$\dot{\Omega}$ ($^\circ$ d ⁻¹)	$\Delta\dot{\Omega}$ ($^\circ$ d ⁻¹)	$\Delta a_{\dot{\Omega}}$ (km)	
6	IER	41835.920 ± 0.102		42.068 ± 0.157	181.733 ± 0.213	2.7620198 ± 0.0001046	-0.0003140	1.352 ± 0.450	
		45	0.830	44.747 ± 0.320	90.465 ± 0.498	-2.7569020 ± 0.0001882	-0.0000256	-0.110 ± 0.813	
	COR	41837.092 ± 0.096		42.499 ± 0.077	181.657 ± 0.112	2.7619579 ± 0.0000516	-0.0001040	0.448 ± 0.222	
		50	0.263	44.643 ± 0.104	89.727 ± 0.272	-2.7565287 ± 0.0000502	0.0000766	0.331 ± 0.217	
	OER	41838.237 ± 0.102		42.930 ± 0.158	181.526 ± 0.209	2.7619237 ± 0.0001028	0.0001277	-0.550 ± 0.442	
		45	0.603	44.446 ± 0.323	88.850 ± 0.507	-2.7560947 ± 0.0001898	0.0002455	1.061 ± 0.820	
5	IER	42233.577 ± 0.089		80.052 ± 0.148	176.823 ± 0.089	2.6715990 ± 0.0000451	-0.0003241	1.456 ± 0.203	
		59	0.603	40.572 ± 0.270	297.500 ± 0.482	-2.6667586 ± 0.0001679	-0.0000154	-0.069 ± 0.757	
	COR	42234.893 ± 0.091		80.237 ± 0.076	176.819 ± 0.048	2.6715756 ± 0.0000227	-0.0000548	0.246 ± 0.102	
		67	0.212	40.951 ± 0.114	296.068 ± 0.259	-2.6663516 ± 0.0000445	0.0000998	0.450 ± 0.200	
	OER	42236.261 ± 0.089		80.463 ± 0.148	176.851 ± 0.089	2.6715450 ± 0.0000449	0.0002192	-0.985 ± 0.202	
		59	0.641	41.331 ± 0.270	294.460 ± 0.475	-2.6658983 ± 0.0001677	0.0002496	1.125 ± 0.756	
4	IER	42569.511 ± 0.089		44.931 ± 0.146	256.398 ± 0.183	2.5978170 ± 0.0000927	-0.0006562	3.057 ± 0.431	
		57	0.744	23.183 ± 0.313	339.064 ± 1.489	-2.5940762 ± 0.0004674	-0.0005631	-2.630 ± 2.183	
	COR	42571.124 ± 0.091		45.347 ± 0.076	255.880 ± 0.093	2.5980293 ± 0.0000433	-0.0000977	0.455 ± 0.202	
		63	0.264	23.413 ± 0.076	336.828 ± 0.671	-2.5932795 ± 0.0001121	-0.0001117	-0.522 ± 0.524	
	OER	42572.743 ± 0.089		45.742 ± 0.143	255.294 ± 0.181	2.5981594 ± 0.0000908	0.0003798	-1.769 ± 0.423	
		57	0.727	24.329 ± 0.308	333.891 ± 1.361	-2.5925059 ± 0.0004191	0.0003157	1.475 ± 1.958	
α	IER	44714.884 ± 0.083		32.512 ± 0.118	205.885 ± 0.213	2.1851508 ± 0.0000949	-0.0007266	4.229 ± 0.552	
		73	0.542	11.853 ± 0.276	206.062 ± 1.839	-2.1831510 ± 0.0005365	-0.0010535	-6.145 ± 3.130	
	COR	44718.473 ± 0.086		33.916 ± 0.062	206.074 ± 0.112	2.1855003 ± 0.0000510	0.0002392	-1.392 ± 0.297	
		81	0.249	12.005 ± 0.089	203.837 ± 0.894	-2.1813455 ± 0.0001311	0.0001373	0.801 ± 0.765	
	OER	44722.161 ± 0.084		35.335 ± 0.118	206.243 ± 0.195	2.1857991 ± 0.0000898	0.0011714	-6.819 ± 0.523	
		73	0.543	11.676 ± 0.289	202.596 ± 1.749	-2.1799630 ± 0.0005158	0.0008880	5.186 ± 3.012	
β	IER	45656.770 ± 0.087		18.573 ± 0.128	319.589 ± 0.435	2.0309488 ± 0.0001626	-0.0004852	3.103 ± 1.040	
		71	0.574	3.799 ± 0.194	224.376 ± 8.293	-2.0272655 ± 0.0019207	0.0007997	5.128 ± 12.315	

Table 5 continued on next page

Table 5 (continued)

Ring	Feature ^(a)	a (km)		ae (km)	ϖ_0 ($^\circ$) ^(b)		$\dot{\varpi}$ ($^\circ$ d ⁻¹)	$\Delta\dot{\varpi}$ ($^\circ$ d ⁻¹)	$\Delta a_{\dot{\varpi}}$ (km)
		N	RMS (km)	$a \sin i$ (km)	Ω_0 ($^\circ$)	$\dot{\Omega}$ ($^\circ$ d ⁻¹)	$\Delta\dot{\Omega}$ ($^\circ$ d ⁻¹)	$\Delta a_{\dot{\Omega}}$ (km)	
	COR	45661.056 ± 0.087		20.106 ± 0.071	317.925 ± 0.222		2.0308229 ± 0.0000857	0.0000590	-0.377 ± 0.548
		78	0.266	4.004 ± 0.070	232.878 ± 4.169		-2.0279790 ± 0.0006048	-0.0005821	-3.733 ± 3.880
	OER	45665.286 ± 0.089		21.745 ± 0.131	316.622 ± 0.383		2.0308319 ± 0.0001456	0.0007290	-4.664 ± 0.932
		71	0.468	3.851 ± 0.206	239.903 ± 7.558		-2.0287602 ± 0.0016596	-0.0020226	-12.970 ± 10.649
η	IER	47174.853 ± 0.093		[0.00] ^(c)					
		56	0.679	[0.00] ^(c)					
	COR	47176.009 ± 0.088		[0.00] ^(c)					
		60	0.297	[0.00] ^(c)					
	OER	47177.080 ± 0.093		[0.00] ^(c)					
		55	0.525	[0.00] ^(c)					
γ ring, including $m = 3$ normal mode									
γ	IER	47624.606 ± 0.103		5.016 ± 0.122	47.274 ± 1.570		1.7516631 ± 0.0006611	0.0001409	-1.091 ± 5.119
		76	0.536	[0.00] ^(c)					
	COR	47626.170 ± 0.089		5.306 ± 0.071	48.720 ± 0.858		1.7514650 ± 0.0004210	0.0001448	-1.121 ± 3.260
		83	0.401	[0.00] ^(c)					
	OER	47627.865 ± 0.100		5.470 ± 0.130	47.145 ± 1.458		1.7524301 ± 0.0005903	0.0013286	-10.286 ± 4.572
		76	0.692	[0.00] ^(c)					
γ ring, excluding $m = 3$ normal mode									
γ	IER	47624.606 ± 0.129		5.016 ± 0.153	47.274 ± 1.964		1.7516631 ± 0.0008271	0.0001409	-1.091 ± 6.405
		76	0.536	[0.00] ^(c)					
	COR	47626.289 ± 0.094		5.314 ± 0.074	47.573 ± 0.881		1.7524471 ± 0.0003578	0.0011422	-8.842 ± 2.771
		83	0.490	[0.00] ^(c)					
	OER	47627.987 ± 0.122		5.524 ± 0.157	46.394 ± 1.775		1.7536847 ± 0.0006681	0.0025990	-20.112 ± 5.175
		76	0.895	[0.00] ^(c)					
δ	IER	48297.775 ± 0.082		[0.00] ^(c)					
		73	0.608	[0.00] ^(c)					
	COR	48300.227 ± 0.082		[0.00] ^(c)					

Table 5 continued on next page

Table 5 (continued)

Ring	Feature ^(a)	a (km)		ae (km)	ϖ_0 ($^\circ$) ^(b)	$\dot{\varpi}$ ($^\circ$ d ⁻¹)	$\Delta\dot{\varpi}$ ($^\circ$ d ⁻¹)	$\Delta a_{\dot{\varpi}}$ (km)
		N	RMS (km)	$a \sin i$ (km)	Ω_0 ($^\circ$)	$\dot{\Omega}$ ($^\circ$ d ⁻¹)	$\Delta\dot{\Omega}$ ($^\circ$ d ⁻¹)	$\Delta a_{\dot{\Omega}}$ (km)
		80	0.273	[0.00] ^(c)				
	OER		48302.752 \pm 0.083	[0.00] ^(c)				
		72	0.683	[0.00] ^(c)				
λ	COR		50026.557 \pm 1.314	[0.00] ^(c)				
		8	3.477	[0.00] ^(c)				
ϵ	IER		51120.014 \pm 0.077	386.530 \pm 0.107	307.089 \pm 0.016	1.3632690 \pm 0.0000070	-0.0028286	30.128 \pm 0.075
		79	0.583	[0.00] ^(c)				
	COR		51149.279 \pm 0.081	405.894 \pm 0.062	307.076 \pm 0.009	1.3632575 \pm 0.0000042	-0.0001081	1.154 \pm 0.045
		89	0.396	[0.00] ^(c)				
	OER		51178.588 \pm 0.079	425.242 \pm 0.111	307.061 \pm 0.015	1.3632618 \pm 0.0000070	0.0026240	-28.026 \pm 0.075
		77	0.560	[0.00] ^(c)				

(a) COR: center of ring. RunIDs: ringfit_v1.9_Ur018M-RF-V0351-URA178-COR-v2 and ringfit_v1.9_Ur018M-RF-V0351-URA178-COR-lambda. IER: inner edge of ring, OER: outer edge of ring. RunID for all edges: ringfit_v1.9_Ur018M-RF-V0351-URA178-IER-OER-v4.

(b) The epoch is TDB 1986 Jan 19 12:00. The zero-point for inertial longitudes is the ascending node of Uranus's equator on Earth's equator of J2000, where the orientation of the Uranus pole is in the direction of positive angular momentum (*i.e.*, 180° from the IAU definition of the Uranus north pole).

(c) Eccentricities e and inclinations $a \sin i$ in square brackets were held fixed during orbit determination.

Table 6. Uranian ring normal modes

Ring	Feature ^(a)	m	A_m (km)	δ_m ($^\circ$)	Ω_p ($^\circ$ d ⁻¹)	$\Delta\Omega_p$ ($^\circ$ d ⁻¹)	Δa_p (km)
η	IER	3	0.452 ± 0.122	77.208 ± 5.798	776.585539 ± 0.002490	0.086574	-3.499 ± 0.101
	COR	3	0.600 ± 0.069	75.901 ± 2.359	776.584048 ± 0.001164	0.113697	-4.595 ± 0.047
	OER	3	0.677 ± 0.124	75.946 ± 3.819	776.584059 ± 0.001818	0.140201	-5.666 ± 0.073
γ ring, including $m = 3$ normal mode							
γ	IER	0	6.137 ± 0.138	309.462 ± 1.178	1145.576306 ± 0.000538	-0.050871	1.411 ± 0.015
		6	0.590 ± 0.110	33.405 ± 2.208	956.418079 ± 0.000877	-0.022759	0.754 ± 0.029
		-2	1.099 ± 0.146	35.175 ± 2.940	1720.120475 ± 0.001212	-0.071814	1.325 ± 0.022
		-1	1.656 ± 0.120	31.309 ± 4.318	2292.907872 ± 0.002002	-0.098006	1.357 ± 0.028
	COR	0	5.509 ± 0.076	311.695 ± 0.750	1145.576845 ± 0.000352	0.006033	-0.167 ± 0.010
		3	0.577 ± 0.073	54.989 ± 2.254	765.399832 ± 0.001152	-0.065364	2.706 ± 0.048
		6	0.637 ± 0.063	32.518 ± 1.171	956.419622 ± 0.000474	0.025958	-0.861 ± 0.016
		-2	0.690 ± 0.079	26.843 ± 2.762	1720.117977 ± 0.001217	0.010437	-0.193 ± 0.022
	OER	-1	1.822 ± 0.067	25.852 ± 2.169	2292.904186 ± 0.001054	0.011240	-0.156 ± 0.015
		0	4.702 ± 0.128	313.066 ± 1.574	1145.576675 ± 0.000698	0.066941	-1.857 ± 0.019
		3	0.935 ± 0.129	56.867 ± 2.520	765.397669 ± 0.001028	-0.026590	1.101 ± 0.043
		6	0.892 ± 0.117	28.027 ± 1.363	956.419529 ± 0.000560	0.076982	-2.552 ± 0.019
		-1	1.955 ± 0.122	25.258 ± 3.578	2292.903174 ± 0.001739	0.132603	-1.836 ± 0.024
γ ring, excluding $m = 3$ normal mode							
γ	IER	0	6.137 ± 0.172	309.462 ± 1.474	1145.576306 ± 0.000673	-0.050871	1.411 ± 0.019
		6	0.590 ± 0.138	33.405 ± 2.763	956.418079 ± 0.001097	-0.022759	0.754 ± 0.036
		-2	1.099 ± 0.183	35.175 ± 3.678	1720.120475 ± 0.001517	-0.071814	1.325 ± 0.028
		-1	1.656 ± 0.150	31.309 ± 5.403	2292.907872 ± 0.002505	-0.098006	1.357 ± 0.035
	COR	0	5.450 ± 0.079	311.233 ± 0.762	1145.576581 ± 0.000376	0.010044	-0.279 ± 0.010
		6	0.698 ± 0.066	30.504 ± 1.075	956.419653 ± 0.000442	0.029566	-0.980 ± 0.015
		-2	0.635 ± 0.083	27.010 ± 3.104	1720.120139 ± 0.001183	0.019028	-0.351 ± 0.022
		-1	1.807 ± 0.070	26.105 ± 2.325	2292.903886 ± 0.001134	0.019506	-0.270 ± 0.016
	OER	0	4.724 ± 0.160	313.481 ± 1.841	1145.575881 ± 0.000844	0.070553	-1.958 ± 0.023

Table 6 continued on next page

Table 6 (continued)

Ring	Feature ^(a)	m	A_m (km)	δ_m (°)	Ω_p (° d ⁻¹)	$\Delta\Omega_p$ (° d ⁻¹)	Δa_p (km)
		6	1.057 ± 0.140	26.147 ± 1.358	956.419580 ± 0.000563	0.080719	-2.676 ± 0.019
		-1	1.966 ± 0.151	22.643 ± 4.393	2292.903576 ± 0.002122	0.141832	-1.964 ± 0.029
δ	IER	2	2.349 ± 0.105	171.686 ± 1.527	562.516712 ± 0.000580	-0.042324	2.415 ± 0.033
	COR	2	3.169 ± 0.059	170.383 ± 0.666	562.516205 ± 0.000258	0.000146	-0.008 ± 0.015
		23	0.339 ± 0.063	6.844 ± 0.472	1074.523021 ± 0.000189	-0.072580	2.173 ± 0.006
	OER	2	4.035 ± 0.105	171.248 ± 0.885	562.516313 ± 0.000351	0.044481	-2.539 ± 0.020
ϵ	IER	-24	1.011 ± 0.107	2.916 ± 0.259	1074.522889 ± 0.000099	-0.034140	1.082 ± 0.003
	COR	14	0.383 ± 0.071	14.105 ± 0.628	956.418015 ± 0.000269	-0.798192	28.425 ± 0.010
		-24	0.443 ± 0.061	2.828 ± 0.346	1074.522703 ± 0.000142	0.888501	-28.177 ± 0.005
	OER	14	0.590 ± 0.130	14.904 ± 0.704	956.418119 ± 0.000298	0.024894	-0.887 ± 0.011

(a) COR: center of ring. RunIDs: ringfit_v1.9_Ur018M-RF-V0351-URA178-COR-v2 and ringfit_v1.9_Ur018M-RF-V0351-URA178-COR-lambda. IER: inner edge of ring, OER: outer edge of ring. RunID for all edges: ringfit_v1.9_Ur018M-RF-V0351-URA178-IER-OER-v4.

(b) The epoch is TDB 1986 Jan 19 12:00. The zero-point for inertial longitudes is the ascending node of Uranus's equator on Earth's equator of J2000, where the orientation of the Uranus pole is in the direction of positive angular momentum (*i.e.*, 180° from the IAU definition of the Uranus north pole). All longitudes reduced to the minimum value of $\lambda \bmod 360^\circ / |m|$.

4.3. *Offset times for selected events*

As discussed in Paper 1, the accuracy of the absolute timing of individual data sets is highly dependent on the availability of accurate time standards at each observatory, the methods used to incorporate time signals into the data streams, and the intrinsic and sometimes variable time delays introduced by filtering electronics and recording systems. For several occultations observed with multiple telescopes, there are significant systematic offsets between the predicted and observed event times. We incorporate these into our orbit fit by including these station offset times as free parameters, as given in **Table 7**. For each event, the absolute timing was anchored by observations from one or more telescopes that were assumed to have the most reliable time reference. Details of the timing for each of the Earth-based observations are included in Paper 1.

For the *Voyager* occultations, we fitted for along-track spacecraft time offsets relative to the nominal *Voyager* trajectory for the RSS occultation and the β Per stellar occultation. The JPL solution for the *Voyager* trajectory in `vgr2.ura178.bsp` assumed an offset time $dt = 0$ for the σ Sgr stellar occultation, and instead solved for an offset to the *Hipparcos* catalog position of this multiple star system. We have followed this prescription in our orbit fits as well.

Table 7. Fitted station offset times

Event	Station	Offset (s)
U12	ESO (2m)	-0.073 ± 0.016
	Las Campanas (IR)	0.099 ± 0.022
	Las Campanas (vis)	0.114 ± 0.019
U14	ESO (1m)	-0.091 ± 0.007
	Las Campanas (IR)	0.064 ± 0.006
	Pic du Midi	3.717 ± 0.009
	Pic du Midi (1m)	0.760 ± 0.012
	Teide (ingress)	0.040 ± 0.010
	Teide (egress)	0.467 ± 0.010
	McDonald Obs.	-0.024 ± 0.006
U25	McDonald Obs.	-0.024 ± 0.006
U36A	IRTF	-8.769 ± 0.262
U103	ESO (2m)	0.055 ± 0.013
U103	CTIO	-0.035 ± 0.013
U134	SAAO (egress)	0.475 ± 0.170
U137	HST	0.635 ± 0.008
U144	CAHA (ingress)	0.428 ± 0.068
	CAHA (egress)	0.724 ± 0.240
Vgr2 RSS	DSS-43	-0.013 ± 0.011
Vgr2 σ Sgr	PPS	[0.000]
Vgr2 β Per	PPS	-0.061 ± 0.016

4.4. *Orbit fit residuals*

The residuals of the separate COR and IER/OER fits summarized in Tables 5 and 6 are shown in **Fig. 20**. For the COR observations shown in the upper panel, the RMS residuals for the nine main rings range from 0.212 km for ring 5 to 0.401 km for the γ ring including the $m = 3$ mode and 0.490 km when the $m = 3$ mode is absent. For the IER/OER observations, the RMS residuals range from 0.468 km for β OER to 0.830 km for ring 6 IER, and 0.895 km for the γ ring OER when the $m = 3$ mode is excluded from the fit. In all, 651 data points were included in the COR fit, for an RMS per degree of freedom of 0.348 km. In comparison, the IER/OER fit included 1174 data points and an RMS per degree of freedom of 0.655 km. As noted previously, the COR measurements are intrinsically more accurate, which prompted the separate fits for the ring midlines and the ring edges.

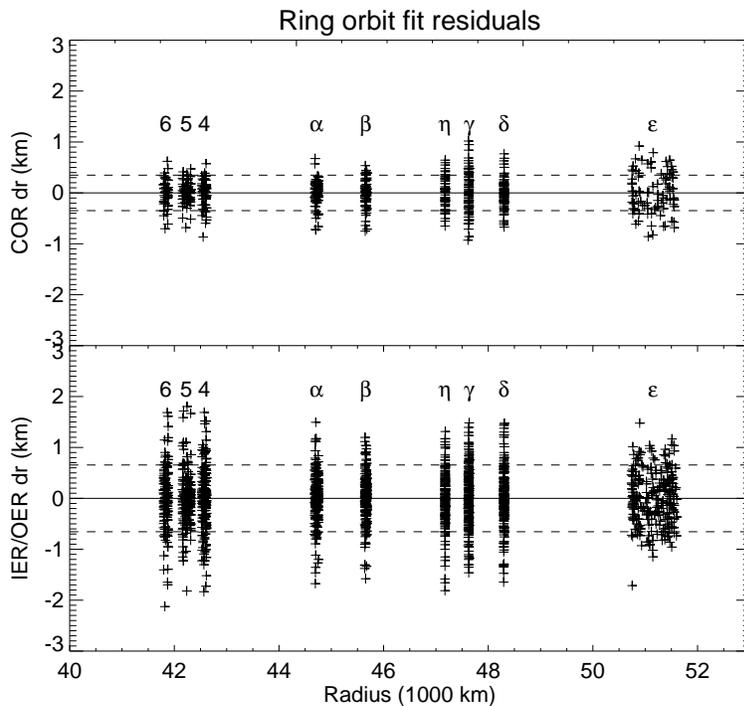


Figure 20. Ring plane residuals of the COR (top panel) and IER/OER (bottom panel) fits in Tables 5 and 6, including the γ ring $m = 3$ normal mode and excluding the λ ring. The dashed lines in each panel show the RMS residuals per degree of freedom for each fit.

Table 8 provides a more detailed view of the distribution of the COR fit RMS residuals by occultation event and observatory code. The total number of data points for each event is listed as N_{tot} , and for multi-station events, N gives the number of data points per station.

Table 8. RMS residuals by event and observatory

Star	Date	Obs	N_{tot}	N	RMS (km)
U0	1977-03-10	KAO	16		0.350
U2	1977-12-23	TEN	3		0.028
U5	1978-04-10	304	16		0.421
U9	1979-06-10	304	7		0.476
U11	1980-03-20	807	6		0.193
U12	1980-08-15		47		0.208
		807		13	0.205
		ESO		17	0.164
		LAS		8	0.257
		LAV		9	0.237
U13	1981-04-26	413	18		0.190

Table 8 continued on next page

Table 8 (*continued*)

Star	Date	Obs	N _{tot}	N	RMS (km)
U14	1982-04-22		87		0.324
		586		8	0.480
		807		18	0.274
		ES1		14	0.162
		LAS		16	0.305
		LAV		10	0.451
		PI1		5	0.363
		TEE		8	0.338
		TEN		8	0.237
U15	1982-05-01	414	17		0.371
U16	1982-06-04	675	18		0.278
U17B	1983-03-25	SAA	13		0.179
U23	1985-05-04		30		0.350
		711		9	0.299
		807		18	0.379
		TEN		3	0.306
U25	1985-05-24		54		0.259
		675		18	0.239
		711		18	0.178
		807		18	0.335
U28	1986-04-26	568	17		0.289
U34	1987-02-26	568	16		0.348
U36A	1987-04-02		25		0.264
		413		3	0.217
		568		5	0.332
		807		8	0.314
		ANU		1	0.058
		IR2		2	0.149
		UKI		6	0.190
U1052	1988-05-12	568	10		0.288
U65	1990-06-21	568	15		0.328
U83	1991-06-25	568	18		0.265
U84	1991-06-28	568	18		0.222
U102A	1992-07-08	568	6		0.385
U103	1992-07-11		27		0.281
		675		12	0.230
		ES2		15	0.316
U9539	1993-06-30	807	18		0.281
U134	1995-09-09		18		0.273
		SA1		9	0.284

Table 8 *continued on next page*

Table 8 (*continued*)

Star	Date	Obs	N_{tot}	N	RMS (km)
		SAA		9	0.261
U137	1996-03-16		22		0.336
		568		18	0.359
		HST		4	0.206
U138	1996-04-10		18		0.167
		675		9	0.165
		HST		9	0.168
U144	1997-09-30		15		0.445
		CAE		5	0.450
		CAI		5	0.495
		SAA		5	0.382
U149	1998-11-06		12		0.369
		568		6	0.395
		688		6	0.342
U0201	2002-07-29	675	12		0.411
U0602	2006-09-20	568	14		0.367

4.5. Limits on eccentricity and inclination

In our adopted final orbit model, several of the narrow rings have no detectable eccentricity and/or inclination. Nevertheless, we can set upper limits on these quantities from a statistical analysis of the patterns of orbit fit radial residuals for a given ring. We illustrate this procedure with the η ring. The top panel of **Fig. 21** shows the results of a series of least-squares fits to the residuals in the measurements of the η ring radius after subtraction of the best-fitting circular orbit and $m = 3$ normal mode, over a range of precession rates centered on the predicted apsidal rate appropriate for the ring’s fitted semimajor axis. The free parameters for each fit are the eccentricity and mean anomaly of the best-fitting ellipse with the assumed precession rate. The top panel shows the RMS residuals of each fit as a function of the assumed pattern speed, and the second panel shows the amplitude ae of the best-fitting ellipse. The solid vertical lines mark the expected precession rate for an eccentric ring with the actual radius of the η ring. If the ring were measurably eccentric, we would expect to see a sharp dip in the RMS residuals and a peak in the fitted amplitude, centered on this pattern speed. Instead, the best-fitting eccentric model for the η ring is marked by the vertical dashed lines, far removed from the physically significant expected precession rate. The bottom panel of the figure shows a histogram of the distribution of fitted amplitudes ($\Delta a = ae$) from the middle panel. The overplotted solid line shows the best-fitting Rayleigh distribution to this histogram, appropriate for a random one-sided distribution:

$$N(\Delta a) = N_0 \frac{\Delta a}{\sigma^2} \exp(-\Delta a^2/2\sigma^2), \quad (12)$$

where we fit for N_0 and σ . In this case, $\sigma(\Delta ae) = 0.063$ km, which is comparable to the $1\text{-}\sigma$ formal uncertainties of the rings with measurable eccentricities (Table 5). Setting the eccentricity detection limit at $2\text{-}\sigma$, the corresponding upper limit to the η ring’s eccentricity is $ae \lesssim 0.126$ km.

Using the same approach to estimate a detection limit for inclination, **Fig. 22** shows a scan over nodal regression rates for the η ring, where we follow the prescription given by Eqs. (8)–(11) of French et al. (2016b) to relate the observed radial residual Δr to the predicted radial displacement corresponding to the local vertical displacement of an

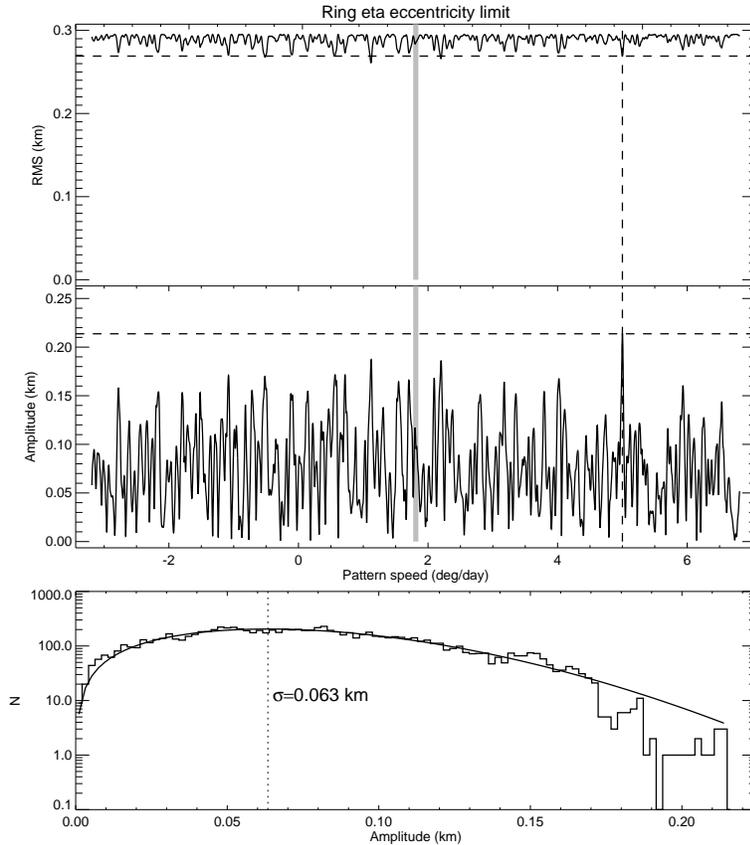


Figure 21. Statistical limit on the eccentricity of the η ring. The upper two panels show the null results of an $m = 1$ normal mode scan, with no detectable dip in the RMS residuals near the predicted apsidal precession rate for the observed semimajor axis of the ring, shown as a thick vertical gray line. The bottom panel shows a histogram of the amplitudes given by the individual least-squares fits for each assumed pattern speed, along with the best-fitting Rayleigh distribution with $\sigma = 0.063$ km.

inclined ring. Once again, there is no indication of a measurable inclination at the expected pattern speed (marked by a thick vertical gray line), with $\sigma(\Delta a \sin i) = 0.145$ km. Adopting the same $2\text{-}\sigma$ detection threshold, the upper limit to the inclination of the η ring is $a \sin i \lesssim 0.290$ km.

Proceeding in a similar fashion for the other rings, we obtain the results in **Table 9** for the $2\text{-}\sigma$ upper limits on the eccentricities and inclinations of all rings with no detected $m = 1$ mode and/or inclination.

Table 9. $2\text{-}\sigma$ eccentricity/inclinations limits

Ring	ae (km)	$a \sin i$ (km)
η	0.126	0.290
γ	–	0.286
δ	0.088	0.284
ϵ	–	0.158

4.6. The λ ring

The λ ring differs from the other nine narrow Uranian rings in the apparent wavelength dependence of its equivalent width (French et al. 1991) and in having an enhanced brightness in the forward scattering direction compared to

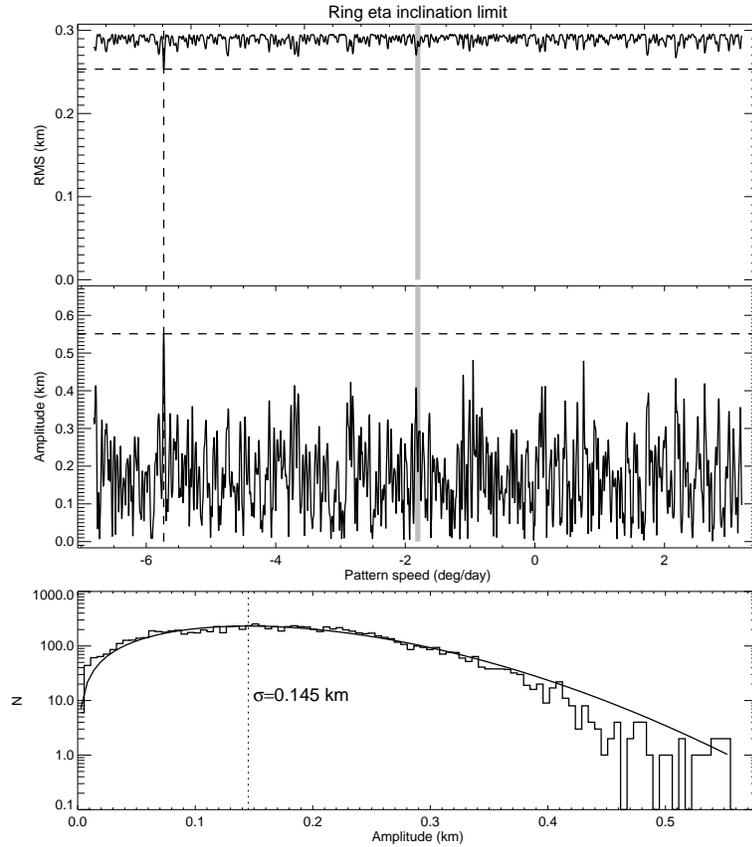


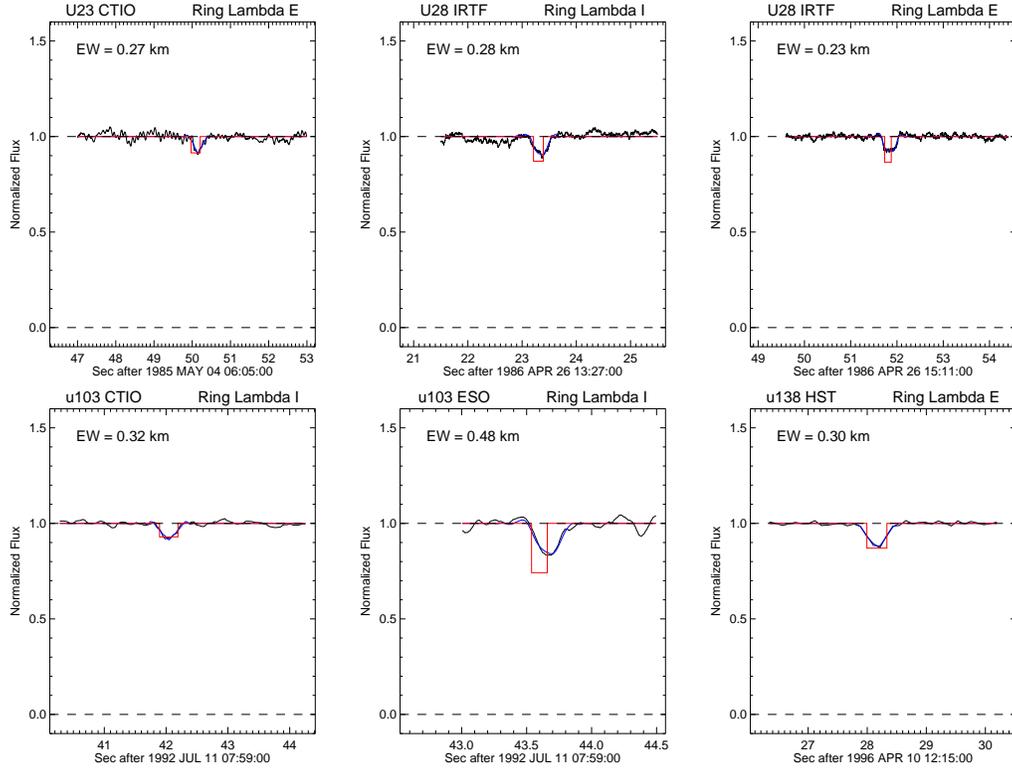
Figure 22. Statistical limit on the inclination of the η ring. The upper two panels show the null results of an $m = 1$ inclination scan, with no detectable dip in the RMS residuals near the predicted nodal regression rate for the observed semimajor axis of the ring, marked by a thick vertical gray line. The bottom panel shows a histogram of the amplitudes given by the individual least-squares fits for each assumed pattern speed, along with the best-fitting Rayleigh distribution with $\sigma = 0.145$ km.

the other narrow rings (Smith et al. 1986; Ockert et al. 1987). From a comparison of *Voyager* UVS and PPS stellar occultations ($\lambda = 0.11 \mu\text{m}$ and $0.27 \mu\text{m}$, respectively) and Earthbased IR observations at $\lambda = 2.2 \mu\text{m}$, Kangas and Elliot (1987) modeled the wavelength dependence of the equivalent depth of the fitted square-well profiles by assuming a two-component population of particles large compared to the observed wavelength and of smaller particles that scattered in the Mie regime with $\tau \propto 1/\lambda$. They derived an upper limit of 6% for the contribution of large particles to the total optical depth at $\lambda = 0.11 \mu\text{m}$. Collectively, these results suggest that the λ ring is primarily composed of micron-sized dust. However, it is also azimuthally variable, having arcs and clumps (Ockert et al. 1987; Colwell et al. 1990; Showalter 1995), some of which might have larger particles detectable in the IR. A detection at infrared wavelengths was reported for the U103 occultation from CTIO and possibly from ESO as well (French et al. 1996). Kangas (1989) identified several additional candidate λ ring events from an analysis of Earth-based occultations at $\lambda = 2.2 \mu\text{m}$, and to these we add a likely detection from the *HST* observations of the U138 occultation at $\lambda = 0.362 - 0.705 \mu\text{m}$ (see Paper 1 for observational details).

For the orbit fit presented here, we include the two secure *Voyager* PPS UV occultation detections (we omit the lower-SNR UVS observations for the same event, to avoid double-counting), five Earth-based IR candidate events, and the likely U138 *HST* detection, for a total of eight possible λ ring events, listed in Table 10. For each event, we include the observed radius r_{obs} , the residual dr relative to our adopted circular orbit fit, the ring profile equivalent width EW , and the wavelength of the observations. Radial profiles and square-well model fits to the six Earth-based candidate detections are shown in Fig. 23.

Table 10. Candidate λ ring occultation events.

Ring	Obs	Dir	UTC	r_{obs} (km)	dr (km)	EW (km)	λ (μm)
U23	807	E	1985-05-04T06:05:50.0905	50022.817	-3.740	0.27	2.20
σ Sgr	PPS	I	1986-01-24T05:30:42.3000	50025.105	-1.452	0.19	0.27
σ Sgr	PPS	E	1986-01-24T08:06:57.1900	50022.528	-4.030	0.19	0.27
U28	568	I	1986-04-26T13:27:23.3009	50032.187	5.630	0.28	2.20
U28	568	E	1986-04-26T15:11:51.8047	50029.089	2.532	0.23	2.20
U103	807	I	1992-07-11T07:59:42.0300	50026.778	0.221	0.32	2.20
U103	ES2	I	1992-07-11T07:59:43.5982	50023.378	-3.179	0.48	2.20
U138	HST	E	1996-04-10T12:15:28.1639	50030.576	4.018	0.30	0.362–0.705

**Figure 23.** Candidate Earth-based occultation detections of the λ ring. (The substantial offset of the U103 ESO model curve relative to the square well shown in red is due to the large instrumental time constant for that dataset – see Paper 1.)

No satisfactory keplerian elliptical model fitted these measurements, and our circular orbit fit gives $a = 50026.557 \pm 1.314$ km and an RMS residual of 3.477 km (Table 5), compared to the [Jacobson \(2014\)](#) value $a = 50024.16 \pm 0.96$, which was based on the combined *Voyager* PPS and UVS detections during the σ Sgr occultation and the `vgr2.ura111.bsp` ephemeris. A separate fit using the `vgr.ura178.bsp` ephemeris that included only the two *Voyager* points yielded $a = 50023.816 \pm 1.289$ km, close to the [Jacobson \(2014\)](#) result. With the addition of the *HST* detection, which we regard as convincing (in part because it was observed at wavelengths fairly close to the PPS sensitivity of $\lambda = 0.27 \mu\text{m}$), we obtained $a = 50026.069 \pm 2.37$ km with an RMS residual of 3.363 km.

Overall, the orbit fits to the λ ring show considerably more scatter than the other rings, even when restricted to the convincing *Voyager* detections. The *Voyager* images show evidence of an $m = 6$ pattern in the ring's radial position with an amplitude of 4.6 ± 0.9 km ([Showalter 1995](#)) that could be compatible with this excess scatter, but the occultation data are too sparse to confirm the existence of this pattern at this point. In the absence of additional secure observations, its semimajor axis should probably be regarded as uncertain at the level of a few km.

4.7. Multiple-star occultation geometry

Among the Uranus occultations reported in Paper 1, the ring profiles of two occultations revealed that they involved multiple-star systems. The occultation of U36 by Uranus and the rings was a remarkable multi-day event, lasting from 1987 Mar 30 through Apr 2 and occurring while Uranus was at the end of its retrograde loop as seen from Earth (Elliot et al. 1987). Besides the ring occultations of the primary star, additional secondary events involving three additional stars were observed, as described in detail in Paper 1. Similarly, star U102A was found to have a binary companion, U102B. We solved for the skyplane offsets Δf (east) and Δg (north) of secondary stars U36B and U36C relative to the primary star U36A (only one ring event was observed for U36D, preventing a unique determination of its offset position), and of star U102B relative to star U102A, from separate orbit fits to the secondary ring event times, with the results shown in **Table 11**.

Table 11. Skyplane positions of secondary stars

Star	Δf (km)	Δg (km)
U36B	$+9.15 \pm 0.32$	$+20.74 \pm 0.77$
U36C	-128.86 ± 0.32	$+138.53 \pm 0.77$
U102B	$+287.28 \pm 0.42$	-283.02 ± 1.80

4.8. Star positions, proper motions and planetary ephemeris offsets

Under the assumption that the *Gaia* DR3 star positions at the catalog epoch of TDB 2016 Jan 1 12:00 are more accurate than the proper motion-corrected positions, in our nominal orbit fit we solved for corrections to the catalog values of the proper motions of the Earth-based occultation stars. To provide alternative representations of the corrections to the relative positions of the star and planet for each occultation, we performed two additional fits: first, we assumed that the `ura178` series of ephemerides were exact and used the unmodified star catalog proper motions, solving for corrections to the predicted star positions for each occultation; next, we used the unmodified catalog values to compute the proper motion and parallax-corrected star positions for each observation, and instead fitted for skyplane offsets f_0 and g_0 (east and north) of Uranus relative to the ephemeris position for each occultation. All three fits returned virtually identical pole directions and ring orbital elements, as expected. **Table 12** lists the results of these three separate fits, and includes for each star the proper motion correction in RA ($d\alpha \cos \delta/dt$) and Dec ($d\delta/dt$), corrections to the catalog positions $d\alpha$ and $d\delta$, and sky-plane ephemeris offsets f_0 and g_0 , along with their correlation coefficient ρ (which was identical for the three fits). Except for a few outliers, mostly associated with multiple star systems, the fitted star offsets $d\alpha$ and $d\delta$ for most of the remaining events are on the order of a few mas. Similarly, the sky-plane ephemeris offsets f_0 and g_0 are well under 100 km, confirming that the substantial systematic drift in time of the `ura111` Uranus ephemeris that amounted to several hundred km in the sky plane by the time of the final ring occultation in 2006 has been effectively eliminated in the `ura178` ephemeris.⁸

5. URANUS POLE DIRECTION AND RING PLANE RADIUS SCALE

We determined the uncertainty in the Uranus pole direction and ring plane radius scale from a series of test fits, described below. The results are included in **Table 13** and shown in **Figs. 24** and **25**.

5.1. Uranus pole direction

- Fit 1: Nominal pole direction and ring orbital elements. This fit included the COR measurements of Earth-based and *Voyager* observations of the nine principal rings, resulting in the adopted orbital elements and normal modes

⁸ The *Gaia* DR3 catalog ID for each star is included in Table 2 of Paper 1.

Table 12. Fitted corrections to proper motions, star positions, and planet ephemeris

Star	Proper motion fit		Star offset fit		Ephemeris offset fit		ρ
	$d\alpha \cos \delta/dt$ (mas/yr)	$d\delta/dt$ (mas/yr)	$d\alpha$ (mas)	$d\delta$ (mas)	f_0 (km)	g_0 (km)	
U0	0.04476 ± 0.00028	0.01458 ± 0.00049	-1.7370 ± 0.0108	-0.5660 ± 0.0189	22.583 ± 0.141	7.357 ± 0.246	-0.009
U2	-0.05768 ± 0.00127	0.08987 ± 0.03230	2.1930 ± 0.0483	-3.4165 ± 1.2273	-30.649 ± 0.678	47.658 ± 17.144	-0.952
U5	0.06834 ± 0.00034	-0.03155 ± 0.00038	-2.5782 ± 0.0130	1.1901 ± 0.0142	33.119 ± 0.167	-15.291 ± 0.182	-0.236
U9	-0.02314 ± 0.00062	0.04092 ± 0.00258	0.8459 ± 0.0227	-1.4966 ± 0.0943	-10.931 ± 0.293	19.324 ± 1.217	0.889
U11	0.02566 ± 0.00092	-0.01070 ± 0.00039	-0.9183 ± 0.0330	0.3828 ± 0.0140	12.094 ± 0.434	-5.043 ± 0.184	-0.163
U12	-0.02100 ± 0.00029	-0.03987 ± 0.00087	0.7429 ± 0.0104	1.4103 ± 0.0307	-10.111 ± 0.141	-19.197 ± 0.418	0.621
U13	0.00444 ± 0.00023	0.00634 ± 0.00066	-0.1540 ± 0.0080	-0.2202 ± 0.0228	1.997 ± 0.104	2.852 ± 0.295	0.280
U14	0.13015 ± 0.00019	0.08204 ± 0.00052	-4.3854 ± 0.0063	-2.7647 ± 0.0176	57.299 ± 0.082	36.120 ± 0.231	0.150
U16	0.00340 ± 0.00024	-0.00384 ± 0.00052	-0.1142 ± 0.0081	0.1289 ± 0.0176	1.481 ± 0.106	-1.673 ± 0.228	0.104
U15	0.03359 ± 0.00023	-0.00179 ± 0.00067	-1.1310 ± 0.0078	0.0602 ± 0.0226	14.717 ± 0.102	-0.785 ± 0.295	0.208
U17B	0.02862 ± 0.00031	-0.00861 ± 0.00051	-0.9378 ± 0.0103	0.2822 ± 0.0167	12.579 ± 0.138	-3.787 ± 0.224	0.337
U23	0.03614 ± 0.00024	0.04487 ± 0.00032	-1.1082 ± 0.0074	-1.3756 ± 0.0100	14.650 ± 0.098	18.184 ± 0.132	0.175
U25	0.30159 ± 0.00022	0.16083 ± 0.00029	-9.2306 ± 0.0068	-4.9224 ± 0.0088	121.117 ± 0.089	64.590 ± 0.115	0.043
U28	0.04119 ± 0.00027	-0.05310 ± 0.00051	-1.2227 ± 0.0081	1.5763 ± 0.0150	16.341 ± 0.108	-21.063 ± 0.201	0.183
U34	0.42907 ± 0.00042	-0.28186 ± 0.00523	-12.3768 ± 0.0121	8.1289 ± 0.1507	174.952 ± 0.171	-114.803 ± 2.128	0.845
U36A	0.31706 ± 0.00029	-0.36079 ± 0.00056	-9.1173 ± 0.0083	10.3772 ± 0.0160	125.254 ± 0.114	-142.893 ± 0.220	-0.078
U1052	0.00355 ± 0.00089	-0.04157 ± 0.00037	-0.0981 ± 0.0247	1.1490 ± 0.0102	1.314 ± 0.331	-15.392 ± 0.137	0.049
U65	0.04912 ± 0.00042	0.00392 ± 0.00053	-1.2539 ± 0.0108	-0.1001 ± 0.0136	16.736 ± 0.144	1.336 ± 0.181	0.192
U83	0.04739 ± 0.00044	0.07387 ± 0.00051	-1.1620 ± 0.0109	-1.8112 ± 0.0125	15.566 ± 0.146	24.263 ± 0.168	0.205
U84	0.05320 ± 0.00067	0.03366 ± 0.00036	-1.3038 ± 0.0164	-0.8252 ± 0.0089	17.460 ± 0.220	11.051 ± 0.119	0.193
U102A	-0.57815 ± 0.00051	0.49276 ± 0.00250	13.5766 ± 0.0119	-11.5716 ± 0.0587	-182.414 ± 0.160	155.471 ± 0.789	-0.409
U103	0.02529 ± 0.00097	0.05789 ± 0.00036	-0.5939 ± 0.0229	-1.3590 ± 0.0085	7.981 ± 0.307	18.263 ± 0.115	0.324
U9539	0.00114 ± 0.00031	-0.04155 ± 0.00172	-0.0257 ± 0.0070	0.9353 ± 0.0387	0.347 ± 0.094	-12.624 ± 0.523	-0.239
U134	-0.01846 ± 0.00286	0.01964 ± 0.01047	0.3749 ± 0.0580	-0.3988 ± 0.2127	-5.187 ± 0.800	5.504 ± 2.932	0.983
U137	-0.01975 ± 0.00051	-0.02044 ± 0.00370	0.3909 ± 0.0100	0.4045 ± 0.0733	-5.768 ± 0.148	-5.964 ± 1.081	-0.873
U138	-0.02093 ± 0.00072	-0.01165 ± 0.00272	0.4130 ± 0.0142	0.2300 ± 0.0537	-5.981 ± 0.206	-3.332 ± 0.779	-0.818
U144	-0.05555 ± 0.00208	0.03560 ± 0.00405	1.0136 ± 0.0380	-0.6498 ± 0.0740	-14.230 ± 0.532	9.126 ± 1.037	0.905
U149	-0.05626 ± 0.00056	-0.06285 ± 0.00189	0.9649 ± 0.0095	1.0781 ± 0.0324	-13.951 ± 0.138	-15.582 ± 0.469	-0.280
U0201	-0.69338 ± 0.00185	0.43748 ± 0.00102	9.3095 ± 0.0248	-5.8740 ± 0.0136	-128.665 ± 0.343	81.183 ± 0.189	0.566
U0602	-0.53994 ± 0.00258	-0.36195 ± 0.00403	5.0120 ± 0.0240	3.3595 ± 0.0374	-69.474 ± 0.332	-46.570 ± 0.519	-0.278

^a Correlation coefficient.

given in Tables 5 and 6. The uncertainties in the pole direction are the formal 1- σ errors from the unweighted least squares fit to the ring observations, plotted as the black error ellipse in the Fig. 24.

- Fit 2: Adopted pole direction, including Voyager trajectory uncertainties. Fit 1 assumed that the *Voyager vgr2.ura178.bsp* ephemeris was exact and did not take into account the formal uncertainties in the spacecraft position that were estimated as part of the ephemeris solution. We conducted a series of Monte Carlo simulations in which we randomly displaced the nominal spacecraft position by the corresponding estimated uncertainty during each of the three separate occultations (RSS, σ Sgr, and β Per) to derive an error ellipse representing the pole direction uncertainties arising solely from the estimated *Voyager* ephemeris errors. We convolved this probability density function with the pole direction error ellipse from Fit 1 to derive a modified 1- σ error ellipse and correlation coefficient $\rho(\alpha_P, \delta_P)$ that accounted for the combined uncertainties in our orbit fit and the systematic uncertainties in the spacecraft trajectory. Overall, the *Voyager* trajectory uncertainty has a relatively small effect on the final error budget: the fitted pole direction is the same as in Fit 1, but the error estimates have increased modestly from $\sigma(\alpha_P) = 0.000128^\circ$ to 0.000141° , and from $\sigma(\delta_P) = 0.000472^\circ$ to 0.000618° . This result is shown as a red error ellipse in Fig. 24 and represents our best estimate of the final pole direction and its 1- σ error.
- Fit 3: Precession of the Uranus pole direction. For Fit 1, we assumed that the Uranus pole direction is fixed in time, but it is predicted to experience slight precession caused by the weak periodic torques supplied by the sun and the planet's satellites. Jacobson (2023) developed a trigonometric series representation of these contributions to the pole direction over time, derived from numerical integrations of the *ura178* satellite ephemerides.

Over the course of the 29-year interval of the ring occultation observations considered here, the corresponding predicted direction of the pole varied periodically by $\pm 0.0002^\circ$ in α_P and $\pm 0.00015^\circ$ in δ_P , following the dominant

short-period term in the series with a period of 17.79 years (6494 days), comparable to the leading terms E_1 and I_1 in Miranda’s eccentricity and inclination arguments (Laskar (1986), Table 3). For Fit 3, we adopted the trigonometric representation of the pole precession as a function of time, fitting for the pole direction at the TDB 1986 Jan 19.5 (*i.e.*, Jan 19 12:00) reference epoch assumed for the ring orbital elements. The brick-red oscillatory path labeled `ura178` is the pole direction given by this trigonometric series over the interval 1600–2600, beginning at the filled circle at the lower left of the path. The `ura178` pole direction over the interval of the occultation observations 1977–2006 is shown as a thicker circular line near the center of the figure. The semimajor axes of the rings and the RMS residuals for this fit were virtually identical to those in Fit 1, indicating that the predicted pole precession has little effect on the derived ring system geometry, as was also found by Jacobson (2014, 2023). The error ellipse for Fit 3 is slightly displaced from the Fit 1 error ellipse. Based on this insensitivity of our results to the inclusion of pole precession, we adopt a fixed pole direction of Fits 1 and 2 for our preferred orbit solution, with the error bars from Fit 2.

- Fit 4: Earth-based observations only. This fit included only the Earth-based ring occultation data and reveals the importance of the unique geometry of the *Voyager* occultations in helping to constrain the pole direction and radius scale. The corresponding elongated solid blue error ellipse in Fig. 24 reflects the strong correlation $\rho(\alpha_P, \delta_P) = -0.88$ resulting from the limited range of viewing geometry of the ring plane available from the ensemble of Earth-based observations. Although the *Voyager* data contributed only 38 ring measurements (compared to 613 Earth-based measurements), they significantly reduce the estimated error in the pole direction (and radius scale, as we show below). Note that the error ellipses for Fits 1 and 2 are nearly centered on the Fit 5 error ellipse, reflecting the fact that the *Voyager* ephemeris was constrained by both the Earth-based and spacecraft ring observations.
- Fit 5: Jacobson (2023) solution. This pole solution was determined as part of the development of the `ura178` series of ephemerides that made use of nearly all the Uranus ring occultation data in Paper 1, with the exception of the γ and λ rings. Extensive detailed comparisons of fits using only the COR ring data showed virtually perfect agreement between Jacobson’s test cases (personal communication) and our Fit 1 results, a robust confirmation of the validity of our two independent orbit fitting codes. In contrast to Fits 1–4, the Fit 5 pole solution was based on a comprehensive fit to extensive historical astrometric and spacecraft navigational data, resulting in a somewhat larger error ellipse (displaced slightly from our adopted Fit 1 pole) that incorporates uncertainties in these additional data sources and provides a more conservative estimate of the accuracy of the pole determination.
- Fit 6: Jacobson (2014) solution. The Jacobson (2014) pole direction at the J2000 epoch ($\alpha = 77.310 \pm 0.002^\circ$ and $\delta = 15.172 \pm 0.002^\circ$) was derived using a subset of the COR ring occultation observations included here, excluding the γ and δ rings and post-1991 data. The *Voyager* occultation geometry was calculated from the `vgr2.ura111.bsp` ephemeris, which was developed using extensive spacecraft navigation and satellite astrometry observations, but no ring occultation data. The Jacobson (2014) pole is shown as the dotted brown error ellipse with an assumed correlation $\rho(\alpha_P, \delta_P) = 0$. The systematic offset from the Fit 1 pole position is due primarily to differences between the updated `vgr2.ura178.bsp` ephemeris and the earlier spacecraft ephemeris, as well as to the use by Jacobson (2014) of keplerian ring orbital elements that modeled the η ring as inclined and eccentric, excluded the γ and δ rings, and neglected the contributions of normal modes to the η and ϵ ring shapes.⁹
- Fit 7: French et al. (1991) solution. The French et al. (1991) pole direction at the B1950 epoch ($\alpha = 76.5969 \pm 0.0034^\circ$ and $\delta = 15.1117 \pm 0.0033^\circ$) was derived using a subset of the ring occultation observations included here, excluding the post-1991 data, and based on an early *Voyager* ephemeris. The result (precessed to the J2000 frame) is shown as the dotted green error ellipse with an assumed correlation $\rho(\alpha_P, \delta_P) = 0$. The fitted pole direction is remarkably close to the Fit 1 result, although with a much larger error estimate. The similarity in pole directions for Fits 1 and 7 is due in part to the largely overlapping data sets and to a likely similarity in the two *Voyager* ephemerides.

⁹ In contrast, the Jacobson (2023) solution for the Uranus system geometry fitted for the same normal modes in the ring midlines as in our orbit fits, and closely matched our keplerian ring orbital elements.

Table 13. Uranus pole direction and ring plane radius scale

Fit	α_P (deg)	δ_P (deg)	$\rho^{(a)}$	$\Delta\alpha_P$ (deg)	$\Delta\delta_P$ (deg)	$\langle\Delta a\rangle$ (km)	$\sigma(\Delta a)$ (km)	Description
1	77.311327 ± 0.000128	15.172795 ± 0.000472	-0.22	—	—	—	—	nominal pole direction
2	77.311327 ± 0.000141	15.172795 ± 0.000618	-0.42	—	—	—	—	w/ Vgr trajectory errors
3	77.311210 ± 0.000128	15.172762 ± 0.000471	-0.22	-0.000117	-0.000033	-0.001	0.003	ura178 pole
4	77.311246 ± 0.000274	15.173393 ± 0.002013	-0.88	-0.000081	0.000597	0.278	0.027	Earth-based only
5	77.311200 ± 0.000400	15.172400 ± 0.001700	-0.39	-0.000127	-0.000395	—	—	Jacobson (2023)
6	77.310000 ± 0.003000	15.172000 ± 0.002000	[1.0]	-0.001327	-0.000795	-0.015	0.091	Jacobson (2014)
7	77.310877 ± 0.003400	15.174564 ± 0.003300	[1.0]	-0.000450	0.001768	-0.055	0.092	French et al. (1991)

^(a)Correlation coefficient $\rho(\alpha_P, \delta_P)$

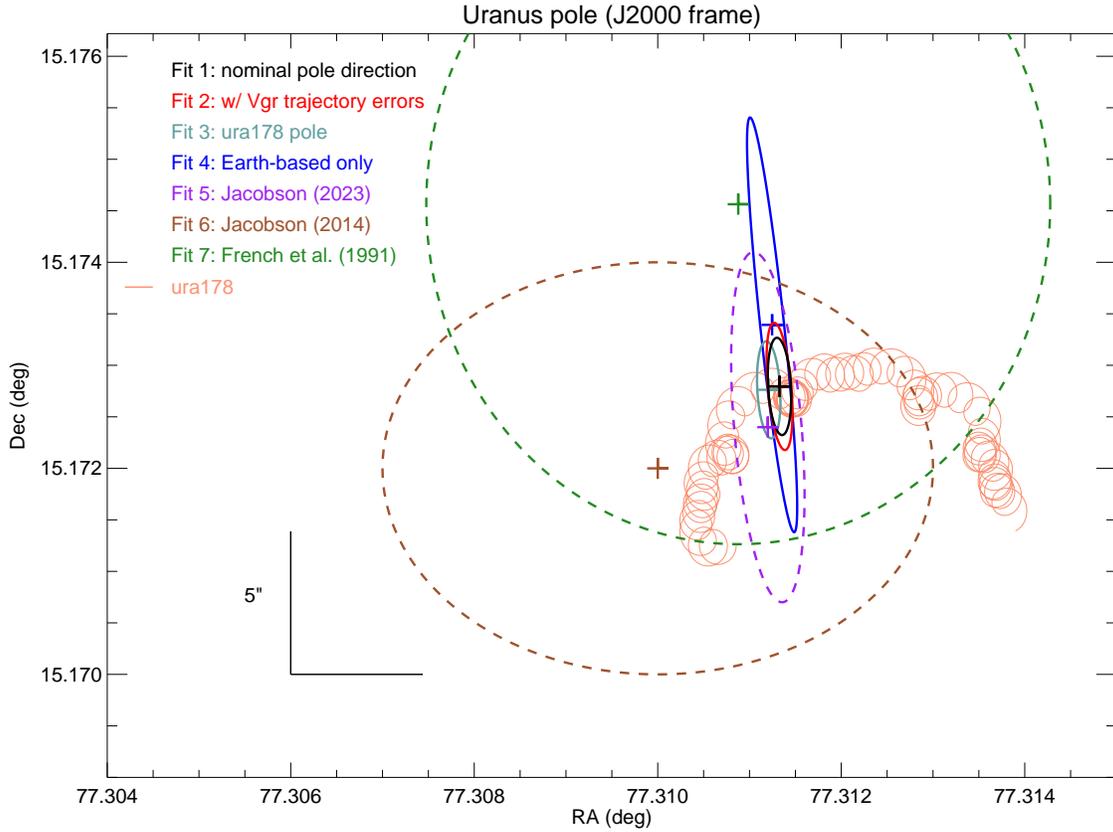


Figure 24. Uranus pole direction in the J2000 reference frame from the fits listed in Table 13. Ellipses are shown as solid lines for Uranus ring and pole fits performed using the data in Paper 1, and as dotted lines for previously published results. See text for details of each fit.

5.2. Ring plane radius scale

A secure dynamical association between satellite resonances and the narrow Uranian rings depends on the accuracy of the absolute radius scale. Figure 25 shows the differences Δa in the semimajor axes of the nine main rings between the fits listed in Table 13 and our adopted geometric solution (Fits 1 and 2 have identical pole direction and ring orbital elements, and differ only in the uncertainty in the pole direction), plotted as a function of orbital radius and displaced horizontally for clarity. (Note that Δa should not be confused with $\Delta a_{\dot{\varphi}}$, $\Delta a_{\dot{\Omega}}$, and Δa_{Ω_P} in Tables 5 and 6.) Table 13 includes $\langle\Delta a\rangle$, the average offset in fitted semimajor axes from the Fit 1 values, and $\sigma(\Delta a)$, the standard deviation of the offsets. The error bars on each point in the figure correspond to the individual 1- σ uncertainties in the

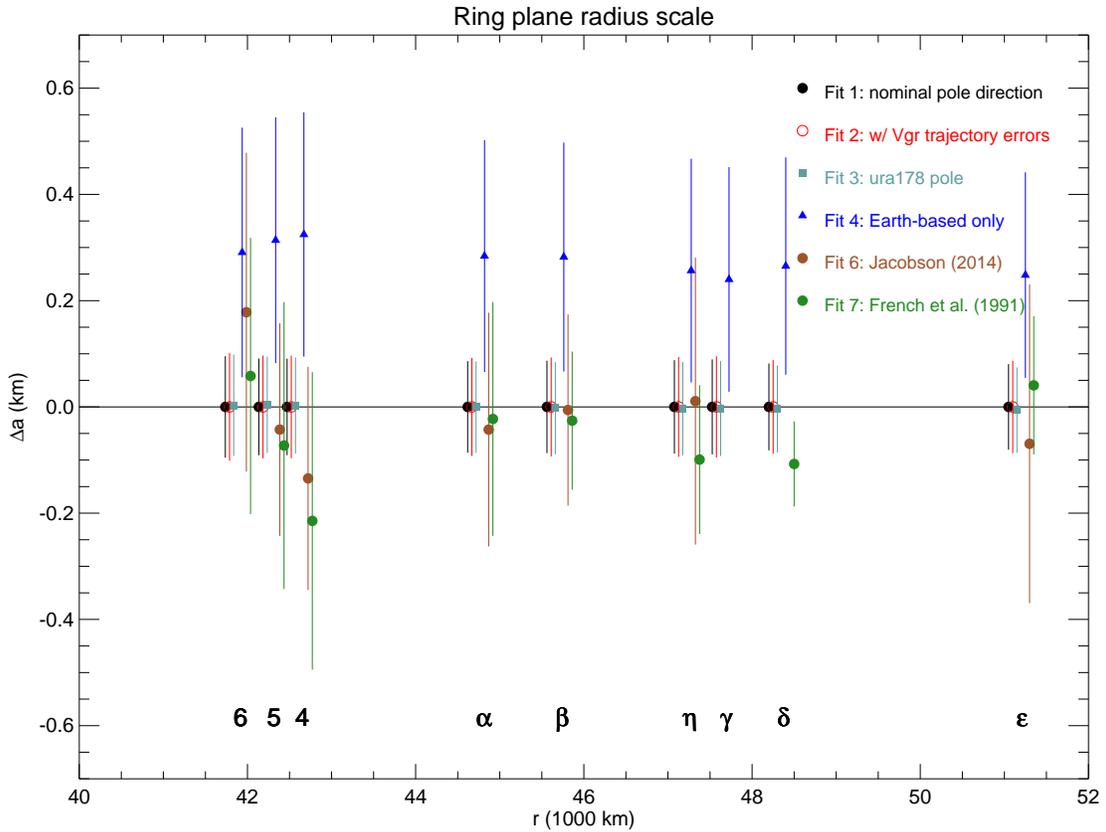


Figure 25. Ring plane radius scale. The differences Δa in the semimajor axes of the nine main rings between fits listed in Table 13 and our adopted geometric solution are shown as a function of orbital radius, displaced horizontally for clarity. The error bars on each point are the individual 1- σ uncertainties in the determination of the semimajor axis for each ring in each fit.

determination of the semimajor axis for each ring in each fit. The Fit 1 error bars are those in our adopted orbit fit in Table 5. As described above, for Fit 2 we incorporated the uncertainties in the *Voyager* ephemeris into the overall error estimate for the pole direction. From this same series of Monte Carlo simulations, the RMS scatter in the fitted semimajor axes of the rings due to spacecraft trajectory uncertainties was quite small, varying from 0.033 km for ring 6 to 0.027 for the ϵ ring. The error bars shown (in red) for Fit 2 were computed by combining these small errors in quadrature with the formal errors in Fit 1. The results are so similar to those in Fit 1 that we have not modified the error bars for the orbital elements in Table 13 to include the very small contribution due to spacecraft ephemeris uncertainties. The fitted semimajor axes and orbital elements from Fit 3, which included pole precession, are virtually identical to those in Fits 1 and 2, with $\langle \Delta a \rangle = -0.001$ km and $\sigma(\Delta a) = 0.003$ km.

Fit 4 (shown as blue squares in Fig. 25), based solely on Earth-based data, deserves special attention. The fitted semimajor axes are systematically higher ($\langle \Delta a \rangle = 0.278$ km), and with substantially larger error bars than in Fits 1 and 2 that included the *Voyager* data. The systematic offset in radius scale is directly related to the corresponding offset in the fitted pole directions between the same two fits shown in Fig. 24, and reflects the strong correlation between the absolute radius scale and the assumed pole direction. This is understandable on a geometric basis inasmuch as the separation of ingress and egress ring event times depends on the projection of the ring orbits into the skyplane resulting from the assumed orientation of the pole.

Finally, the radius scales of two previous determinations that included *Voyager* observations, but based on different spacecraft ephemerides, are very similar to our adopted solution: the Fit 6 (Jacobson 2014) semimajor axes differed from the Fits 1 and 2 values on average by only $\langle \Delta a \rangle = -0.015$ km, with an RMS scatter $\sigma(\Delta a) = 0.092$ km, and the corresponding Fit 7 (French et al. 1991) results were $\langle \Delta a \rangle = -0.053$ km and $\sigma(\Delta a) = 0.093$ km.

Based on the demonstrated importance of the *Voyager* observations to constraining the pole direction (Fig. 24), the resultant reduction in error estimates for the ring radii, and the similarity of the present and previously-published determinations of the radius scale based on independent *Voyager* ephemerides, we estimate that our adopted radius scale (Fits 1 and 2) is accurate to ~ 0.2 km at the $2\text{-}\sigma$ level.

6. RING WIDTHS, SHAPES, AND MASSES

We now turn to an examination of the widths, shapes, and masses of the rings, based on the centerline (COR) and edge (IER/OER) fits given in Tables 5 and 6. Since differential precession of an eccentric ringlet would result in streamline crossing on a dynamically short timescale compared to the presumed age of the ring, it is commonly assumed that narrow rings precess uniformly, enforced either by the collective effects of collisions and self-gravity or by external forcing from a satellite (see Longaretti (2018) for a detailed review of these and other proposed mechanisms). The self-gravity explanation was originally proposed by Goldreich and Tremaine (1979), motivated by the observed elliptical shape of the ϵ ring.

Borderies et al. (1983) developed a two-streamline self-gravity formalism that Nicholson et al. (2018b) applied to observations of narrow rings, and it provides a useful starting point for interpreting the observed variation of width with ring radius.¹⁰ In this model, differential precession is balanced by self-gravity for a free $m = 1$ mode (*i.e.*, not forced by a satellite) when the following equilibrium condition (Eq. (10.109), Longaretti (2018)) holds:

$$\frac{\delta\epsilon}{\epsilon} = \frac{21\pi}{4} J_2 \left(\frac{R}{a}\right)^2 \frac{M_{\text{Ur}}}{M_r} \left(\frac{\delta a'}{a}\right)^3 \frac{1}{H(q_e^2)}, \quad (13)$$

where ϵ and $\delta\epsilon$ are the mean eccentricity and the difference in eccentricities of the two streamlines, a and $\delta a'$ are the mean value and difference in the streamline semimajor axes, J_2 is the second-order gravitational harmonic coefficient with reference radius R , M_{Ur} is the planet mass, M_r is the ring mass, $q_e = a\delta\epsilon/\delta a'$, and

$$H(q_e^2) = \frac{1 - (1 - q_e^2)^{1/2}}{q_e^2(1 - q_e^2)^{1/2}}. \quad (14)$$

Relating the two-streamline quantities ϵ , $\delta\epsilon$ and $\delta a'$ to the observed eccentricities and semimajor axes of the ring edges, we have

$$\epsilon = e = e_{\text{COR}}, \quad (15)$$

$$\delta e = e_{\text{OER}} - e_{\text{IER}} \approx 2\delta\epsilon, \quad (16)$$

$$\delta a = a_{\text{OER}} - a_{\text{IER}} \approx 2\delta a', \quad (17)$$

and

$$a = a_{\text{COR}} \quad (18)$$

The eccentricity gradient q_e is identical for both the two-streamline model and the actual ring observations:

$$q_e = \frac{a\delta\epsilon}{\delta a'} = \frac{a\delta e/2}{\delta a/2} = \frac{a\delta e}{\delta a}. \quad (19)$$

The variation in the observed width with orbital radius around the elliptical ring is $dW/dr \simeq a\delta e/ae = \delta e/e = 2a\delta\epsilon/ae = 2\delta\epsilon/\epsilon$. Explicitly including the factors of two in Eqs. (16) and (17) when translating from the two-streamline quantities $\delta\epsilon$ and $\delta a'$ to their observational counterparts δe and δa , we have

$$\frac{dW}{dr} = \frac{\delta e}{e} = \frac{2\delta\epsilon}{\epsilon}. \quad (20)$$

(The dimensionless quantity $dW/dr \approx \delta e/e$ should not be confused with $q_e = a\delta e/\delta a$.)

¹⁰ We express these in terms of the *observed* widths and shapes of the normal modes at the actual ring edges and centerlines, rather than in terms of the spacing and eccentricities of the two streamlines, as assumed by Borderies et al. (1983) and Longaretti (2018). These alternate approaches differ by a factor of two in the definitions of several important geometric quantities. We identify these differences where they occur.

For $m \neq 1$, the corresponding result is

$$\frac{dW_m}{dr} = \frac{\delta e_m}{e_m} = \frac{2\delta\epsilon_m}{\epsilon_m}, \quad (21)$$

where $a\delta e_m$ is the difference in the mode amplitudes between the outer and inner ring edges and $a e_m$ is the COR mode amplitude A_m . (Note that the eccentricity gradient for $m \neq 1$ is $q_{em} = a\delta e_m/\delta a$.) For modes with $m \leq 0$, the self-gravity model predicts that the slope of the width-radius relation will be negative. In the derivation of Eqs. (20) and (21), an underlying assumption of the two-streamline formalism is that the fractional difference in mode amplitude e_m is small, which we will see is not necessarily true for the η , γ , and δ rings.

An additional quantity of interest is the mean gradient in periape longitude, given by

$$q_\varpi = -ae\delta\varpi_0/\delta a, \quad (22)$$

where $\delta\varpi_0 = \varpi_{\text{OER}} - \varpi_{\text{IER}}$ is the difference between the outer and inner ring edge pericenter longitudes. Eqs. (19) Eq. (22) together define a generalized q :

$$\begin{aligned} q \cos \gamma &= q_e \\ q \sin \gamma &= q_\varpi, \end{aligned} \quad (23)$$

where γ is the phase lag of the minimum width of the ring relative to pericenter. Similar expressions apply for the case $m \neq 1$. The ring width varies as

$$W(f) = \delta a[1 - q \cos(f - \gamma)], \quad (24)$$

where $f = \lambda - \varpi$ is the true anomaly of the ring's centerline. As noted by Nicholson et al. (2018b), $\tan \gamma \simeq -e\delta\varpi/\delta e$, and thus the phase lag can be much larger than the pericenter offset $\delta\varpi$ if $\delta e \ll e$. For a single mode, we require that $q < 1$ to avoid streamline crossing, although in the simultaneous presence of multiple modes this restriction may not apply to each mode individually.

In the idealized case of a uniformly precessing ring, the fitted apse rates of the IER, COR, and OER would be equal:

$$\dot{\varpi}(a_{\text{IER}}) = \dot{\varpi}(a_{\text{COR}}) = \dot{\varpi}(a_{\text{OER}}). \quad (25)$$

The inner edge of an eccentric ringlet must thus precess more slowly than expected for an isolated particle in orbit with semimajor axis a_{IER} , and the opposite is the case at the outer edge. Recalling the definitions from Section 4.2 given in Eqs. (9) – (11) (*i.e.*, that the fit parameter $\Delta\dot{\varpi}$ is the difference between the observed precession rate and that predicted from the planet's gravity harmonics and satellite precession contributions at the edge in question), uniform precession predicts that at the IER, one would expect $\Delta\dot{\varpi} < 0$ and $\Delta a_{\dot{\varpi}} > 0$. Similarly, for the OER one would expect $\Delta\dot{\varpi} > 0$ and $\Delta a_{\dot{\varpi}} < 0$. For $m \neq 1$, the corresponding conditions at the IER are $\Delta\Omega_P < 0$ and $\Delta a_{\Omega_P} > 0$ and for inclined ringlets, $\Delta\dot{\Omega} > 0$ and $\Delta a_{\dot{\Omega}} > 0$.

Under equilibrium conditions, where the inner and outer ring edges precess at the same rate as the COR, the simple self-gravity model predicts that $\Delta a_{\dot{\varpi}}(\text{COR}) = 0$ and thus that

$$\begin{aligned} \Delta a_{\dot{\varpi}}(\text{IER}) - \Delta a_{\dot{\varpi}}(\text{COR}) &= \Delta a_{\dot{\varpi}}(\text{IER}) = a_{\text{COR}} - a_{\text{IER}} > 0 \\ \Delta a_{\dot{\varpi}}(\text{OER}) - \Delta a_{\dot{\varpi}}(\text{COR}) &= \Delta a_{\dot{\varpi}}(\text{OER}) = a_{\text{COR}} - a_{\text{OER}} < 0. \end{aligned} \quad (26)$$

With this dynamical framework in mind, we next describe the shapes, widths, width-radius relations, and comparative precession rates across each ring obtained from the fitted keplerian and normal mode elements from Tables 5 and 6. **Table 14** lists the following quantities for each ring: mean semimajor axis \bar{a} , width $\overline{W} = \delta a$, wavenumber m , mode amplitude A_m , difference in mode amplitudes between the inner and outer edges $a\delta e_m = A_m(\text{OER}) - A_m(\text{IER})$, pericenter longitude difference between the outer and inner edges $\delta\varpi_{0m}$, gradients q_{em} and $q_{\varpi m}$, width-radius relation $dW_m/dr = a\delta e_m/\bar{a}e_m$, and $\delta\Omega_P$, the observed difference in pattern speeds between the outer and ring edges, defined for $m = 1$ as

$$\delta\Omega_P = \delta\dot{\varpi} = \dot{\varpi}(\text{OER}) - \dot{\varpi}(\text{IER}) \quad (27)$$

and for $m \neq 1$ as

$$\delta\Omega_P = \Omega_P(\text{OER}) - \Omega_P(\text{IER}). \quad (28)$$

Table 14. Width-radius results

Ring	\bar{a} km	\bar{W} km	m	A_m km	$a\delta e_m$ km	$\delta\varpi_{0m}$ deg	q_{em}	$q_{\varpi m}$	dW_m/dr	$\delta\Omega_p$ ° yr ⁻¹
6	41837.092	2.316	1	42.499	0.862	-0.207	0.372	0.077	0.020	-0.035
5	42234.893	2.684	1	80.237	0.412	0.028	0.153	-0.004	0.005	-0.020
4	42571.124	3.231	1	45.347	0.810	-1.103	0.251	0.277	0.018	0.125
α	44718.473	7.277	1	33.916	2.823	0.359	0.388	-0.139	0.083	0.237
β	45661.056	8.516	1	20.106	3.172	-2.967	0.372	1.105	0.158	-0.043
η	47176.009	2.227	3	0.600	0.224	-1.262	0.101	0.127	0.374	-0.540
γ	47626.170	3.258	1	5.306	0.454	-0.129	0.139	0.018	0.086	0.280
			0	5.509	-1.435	3.605	-0.440	1.587	-0.261	0.135
			6	0.637	0.302	-5.378	0.093	0.499	0.475	0.530
			-1	1.822	0.299	-6.051	0.092	0.556	0.164	—
			-2	0.690	-1.099	—	-0.337	—	-1.592	4.742
			3	0.577	0.935	—	0.287	—	1.622	-0.790
δ	48300.227	4.977	2	3.169	1.686	-0.438	0.339	0.148	0.532	-0.146
			23	0.339	—	—	—	—	—	—
ϵ	51149.279	58.574	1	405.894	38.712	-0.028	0.661	-0.019	0.095	-0.003

6.1. Rings 6, 5, 4, α , and β

We begin with the five inner rings, each of which has a measurable eccentricity and inclination but no detected free or forced normal modes. In **Fig. 26**, each column shows key characteristics for a given ring. In the top row, $\Delta r(\lambda) = r(\lambda) - a_{\text{COR}}$ is the difference between the model ring radius $r(\lambda)$ of the $m = 1$ mode (computed from Eq. (1) at the epoch of the orbit fit) and the mean semimajor axis a_{COR} , plotted as a function of inertial longitude λ at epoch for each ring’s inner edge (blue), midline (green), and outer edge (red). In the second row, the ring widths $W(\Delta r)$ are plotted as a function of $\Delta r = r_{\text{COR}} - a$. When the longitudes of the periapses of the two edges are aligned, $W(r)$ is a straight line with slope $dW/dr = \delta e/e$, but for misaligned apses, the shape is an ellipse. All five inner rings show a positive slope, as predicted for a self-gravitating eccentric ring by Eq. (20). The apses are most closely aligned for rings 6, 5, and α , with more significant misalignments for rings 4 and β , as indicated by the elliptical shapes of the width-radius relations.

The third row of Fig. 26 shows the semimajor axes (dashed lines) calculated from the fitted pattern speeds of the normal modes (in this case, the periapse precession rates) at the ring edges and midlines, compared to the observed ring midline and edge semimajor axes themselves, shown as solid lines. The computed semimajor axes (generically referred to as “resonance radii” to include the case of modes forced by satellites) based on the combined precessional effects of the gravity field of the planet and the known satellites closely match the ring midlines for all but ring α , which together with ring β precess somewhat faster than predicted for the mean radii of these rings. This anomalous precession may be due to small unseen satellites, as discussed below in Section 8.

Finally, the fourth row compares the observed pattern speeds of the IER, COR, and OER relative to the *predicted* pattern speed of the COR, plotted as a function of semimajor axis. In the ideal case of a uniformly precessing ring, the precession rates $\dot{\varpi}$ of the IER, COR, and OER should be equal. Systematic offsets between the observed and predicted COR precession rates are in some cases due to forced satellite modes, where the forcing frequency is close to but not equal to the COR precession rate, and is also affected in some cases by the difference between the geometric midline of a ring and its radial center of mass, an issue addressed in Section 7.1. Statistically significant differences in the pattern speeds at the ring edges such as those seen for rings 4 and α could be indications of libration or circulation of a normal mode, as has been observed at the outer edge of Saturn’s B ring (Spitale and Porco 2010; Nicholson et al. 2014a; French et al. 2023b). We explore these possibilities in Section 6.5.

6.2. The η and δ rings

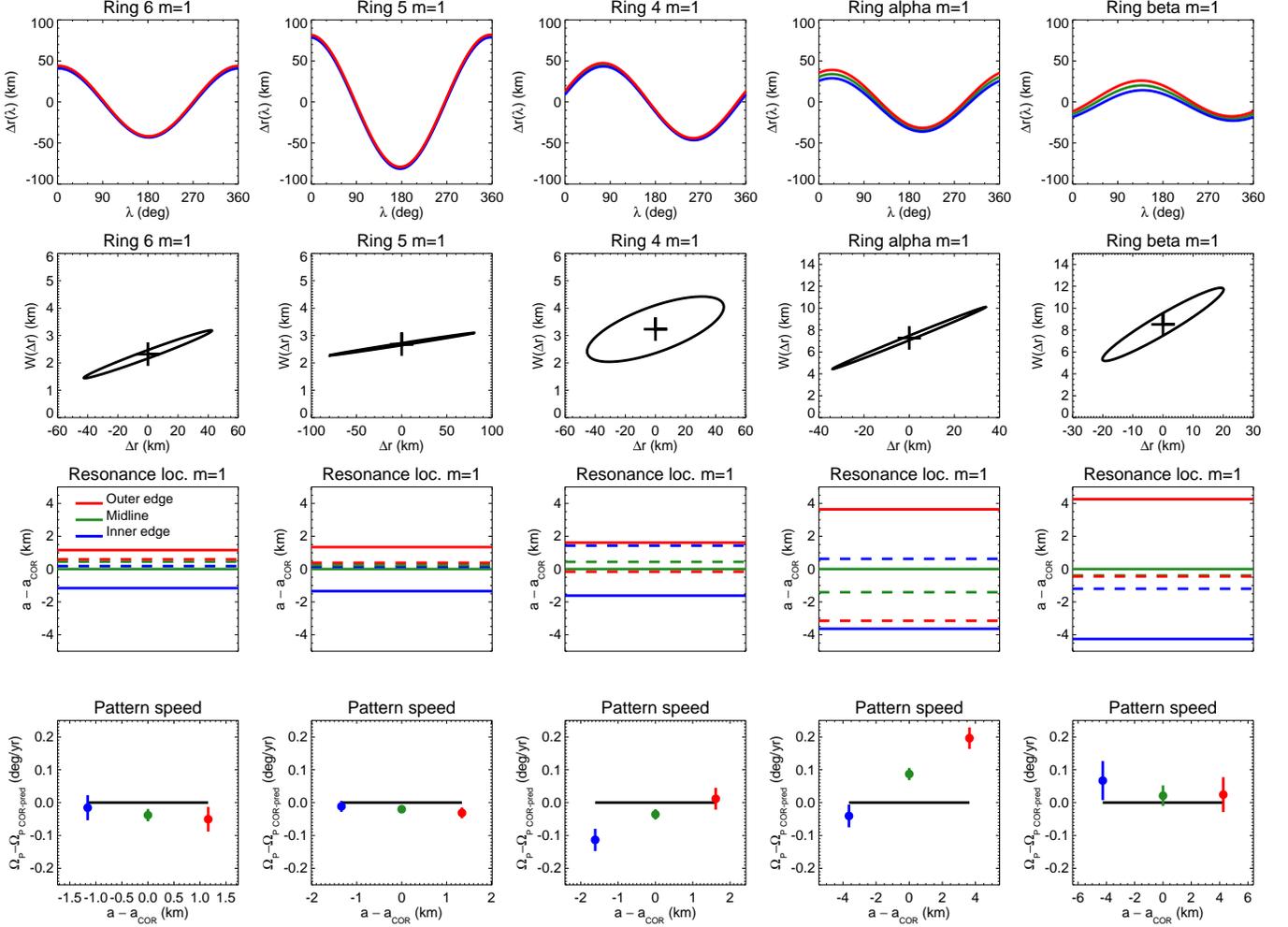


Figure 26. Width variations of rings 6, 5, 4, α , and β . The top row shows $\Delta r(\lambda)$, the variation of ring radius with inertial longitude λ at epoch for the IER, COR, and OER (blue, green, and red, respectively). The second row shows the corresponding variation of ring width $W(\Delta r)$, and the third row shows the predicted resonance radii for each detected mode (shown dashed) relative to ring’s semimajor axis a_{COR} , compared to the locations of the ring edges (shown as solid lines). The final row shows the differences in the observed pattern speeds of the inner and outer edges, and that of the COR, relative to the *predicted* COR value (based on the Uranus gravity field and satellite contributions to the precession rates), plotted as a function of semimajor axis relative to a_{COR} .

Figure 27 shows the corresponding results for the η and δ rings. In the top panel, the edge and midline locations are plotted as a function of $m\lambda$, since there are m complete normal mode cycles around the circumference of the ring. The η ring is nearly constant in width, with a very small but positive dW/dr , and has nearly aligned mode pericenters. The $m = 3$ normal mode is clearly driven by the 3:2 ILR with Cressida, as discussed by [Chancia et al. \(2017\)](#) and confirmed here by the resonance locations for the edges and midline being about 5 km interior to the ring and well-matched to the Cressida resonance radius calculated from the satellite mean motion of [Showalter and Lissauer \(2006\)](#), labeled as SL06. The fitted $m = 3$ pattern speeds for the IER, COR, and OER agree within the error bars, but are controlled by the forcing frequency of Cressida, rather than by the gravity field of the planet, resulting in the large vertical offset in the left panel in the fourth row of the figure.

The δ ring $m = 2$ mode has a substantial width variation, with nearly identical calculated resonance radii for the IER, COR, and OER falling very near to the ring midline. It has a positive width-radius relation, as expected from Eq. 21 for a self-gravitating ring with free normal mode $m > 1$, with nearly aligned pericenters at the ring midline

and edges. The fitted $m = 2$ pattern speeds for the IER, COR, and OER agree within the error bars, as shown in the middle panel in the fourth row of the figure.

The δ ring $m = 23$ mode is relatively weak, with $A_m = 0.342 \pm 0.063$ km, and is detectable only in the ring midline (see Table 6) – the outer and inner ring edges are shown as dashed lines in the upper right panel of the figure, and $W_m(\Delta r)$ is unobserved. The resonance location for the observed pattern speed matches the Jacobson (1998) value for the mean motion of Cordelia (labeled Jac98 in the figure), and lies just inside the outer edge of the δ ring. Once again, there is a large vertical offset between the observed pattern speed and the predicted COR pattern speed, since the $m = 23$ mode is controlled by the forcing frequency of Cordelia. We will make use of the measured amplitude and resonance location to estimate Cordelia’s mass in Section 9.

6.3. The γ ring

The γ ring has the most complex shape of all the Uranian rings, being distorted by six distinct normal modes. The contributions of each mode to the ring width and shape are shown in **Figure 28**, with the following notable features:

- The $m = 1$ mode has a large COR amplitude $A_1 = 5.306 \pm 0.071$ km and well-aligned apses, but it contributes rather little to the overall width variation of the ring itself, with a very small but positive slope $dW_m/dr = 0.086$. The outer edge of the ring shows an anomalously high $m = 1$ precession rate: from Table 5 (for the model including the $m = 3$ normal mode) the resonance radius computed from the fitted apse rate for the OER lies 8.591 km interior to the COR semimajor axis, as shown in the left panel of row three of Fig. 28.
- The $m = 0$ mode has a similarly large COR amplitude $A_0 = 5.511 \pm 0.076$ km, but unlike the $m = 1$ mode, it is narrowest at apoapse and widest at periapse, resulting in a negative value of dW_m/dr and slightly misaligned periapse phases, producing the elliptical shape of the $W_m(\Delta r)$ plot. The resonance location closely matches the semimajor axis of the ring. The negative slope of the width-radius relation is consistent with the self-gravity model prediction for an outer Lindblad resonance (OLR) with $m \leq 0$ (see Eq. (21)). The width of the γ ring is primarily controlled by the $m = 0$ mode and not the $m = 1$ mode, even though both modes have comparable $ae \sim 5$ km. This observation supports the physical argument posited by Nicholson et al. (2018b) that self-gravity needs to overcome only the relatively slow differential precession for an $m = 1$ perturbation, whereas for $m \neq 1$ it is necessary to overcome the much greater gradient in mean motion.
- The weaker $m = 6$ mode is driven by the 6:5 ILR with Ophelia, with edge and midline pattern speeds matching the Jacobson (1998) value for the satellite mean motion within its error bars (labeled Jac98 in the figure). The more accurate recent Ophelia mean motion (Robert French, personal communication – labeled RF23) has a predicted resonance location that closely matches that of the observed $m = 6$ pattern speed, lying within the ring itself. The proximity of the Ophelia 6:5 resonance to the inner edge of the γ ring is surprising and the opposite of standard theories of resonant shepherding. A potential analog to this structure is the ringlet ER1 in Saturn’s inner C ring. The outer edge of this ringlet falls near a resonance with a planetary normal mode (French et al. 2021), which is also the opposite of expectations since the pattern speed of this normal mode is faster than the ring’s orbital motion. Both these rings may have both their edges shepherded by their respective resonances, as predicted by Borderies et al. (1986).
- The $m = -1$ mode has a small positive $dW_m/dr = 0.164$, contradicting the expectation that for an isolated OLR, the slope should be negative. Given the multiple simultaneous modes in the γ ring and the small amplitude of this mode, this apparent discrepancy may not be dynamically significant.
- The $m = -2$ mode is undetectable on the outer edge of the ring, and is strongest on the inner edge. In this case, $dW_m/dr = -1.592$, negative as expected for this OLR, and second in magnitude of all measured modes in any of the rings, with the exception of the $m = 3$ mode described next.
- The $m = 3$ mode was detected only on the outer edge and midline of the ring, with a positive $dW_m/dr = 1.622$, the largest value for any of the modes identified here. The fitted apses of the COR and OER $m = 3$ modes

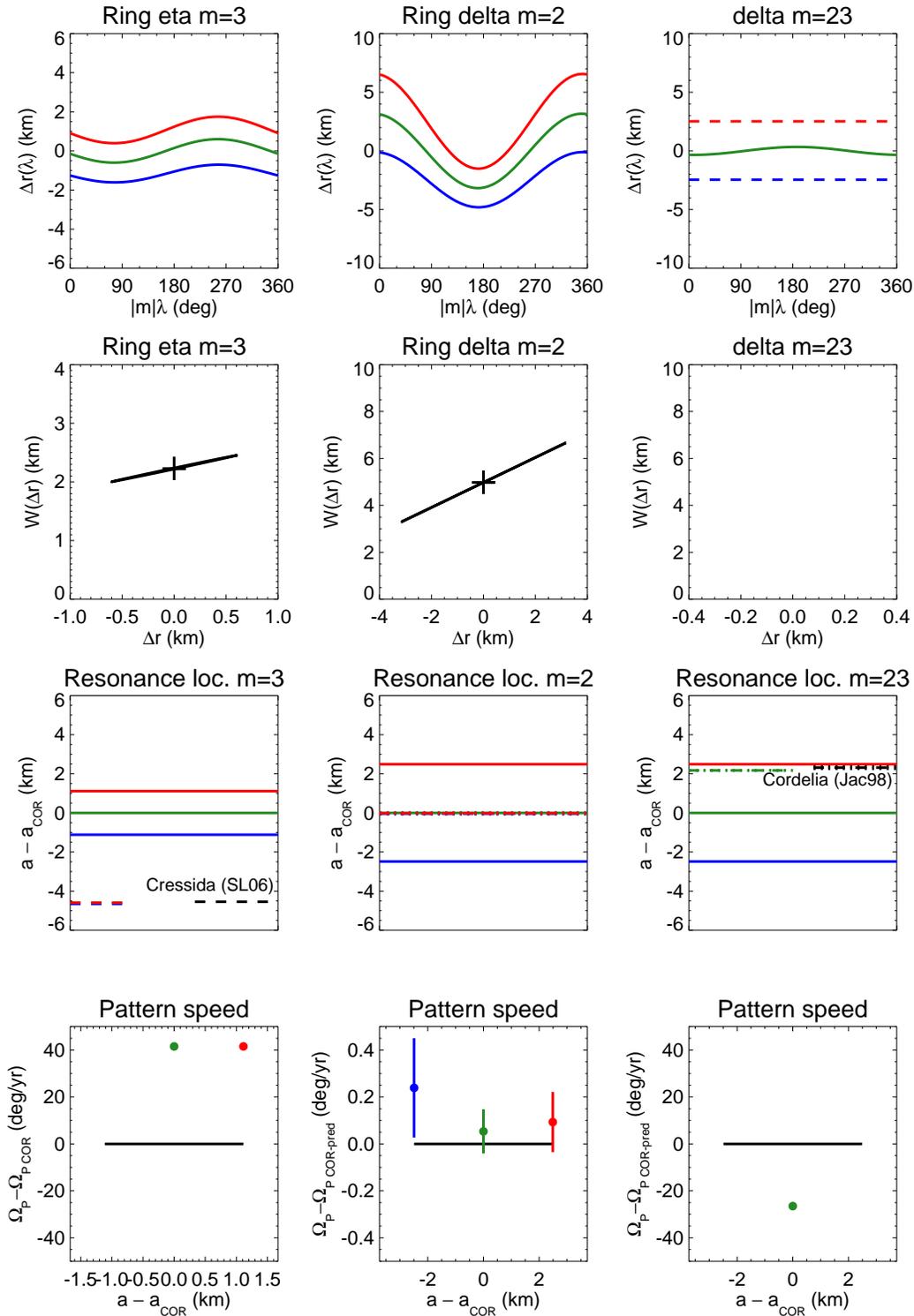


Figure 27. Width variations of rings η and δ , with the same layout as for Fig. 26. The predicted resonance location for Cressida, assuming the mean motion given by Showalter and Lissauer (2006) (labeled SL06), is shown as a dashed line for the η ring $m = 3$ mode, and lies ~ 5 km interior to the ring’s midline. The predicted resonance location for Cordelia, assuming the mean motion given by Jacobson (1998) (labeled Jac98), is shown as a dashed line for the δ ring $m = 23$ mode, and lies just interior to the outer edge of the ring. The $m = 23$ mode was not detected in the shape of the IER or OER of the δ ring.

are well-aligned and match closely in pattern speed. There is no known satellite that forces this mode. On the other hand, if this is a free mode, its resonance radius is quite far removed from the ring midline, unlike the other free modes identified in the Uranus system. The pattern speed of the $m = 3$ structure is much less than that expected for fundamental planetary normal modes (A’Hearn et al. 2022) and is significantly larger than the planet’s rotation rate (Desch et al. 1986; Warwick et al. 1986; Helled et al. 2010). Thus this pattern is unlikely to be generated by either a fundamental planetary normal mode or a persistent anomaly carried around by the planet’s winds similar to those that produce waves in Saturn’s rings (Hedman et al. 2022). If this signal turns out to be real and generated by the planet, it therefore would have to be due a more complex and possibly mixed planetary mode. A final possibility is that this putative detection is instead a random pattern emerging from the co-addition of five other modes to the shape of the ring. We will see below in Section 8, however, that exclusion of this mode from the ensemble of γ ring modes results in a very large anomalous $m = 1$ precession rate with no identifiable source. Furthermore, the RMS residuals for the γ ring COR fit when the mode is absent increase from 0.401 km to 0.490 km, the largest of any of the rings; for the OER, the increase is from 0.692 km to 0.895 km (Table 5). At this point, the origin of the $m = 3$ mode remains mysterious.

6.4. The ϵ ring

The ϵ ring is the widest and most eccentric of the Uranian rings, with a well-defined width-radius relation ($dW_m/dr = 0.095$) shown in Fig. 29. Its width varies by almost a factor of five, from 19.9 km at periapse to 97.3 km at apoapse. The periapses of the inner and outer edges are aligned to within 0.028° and the resonance radius for the $m = 1$ mode closely matches the midline of the ring, which is not surprising since the ϵ ring establishes a tie point for the determination of the planet’s gravity field that governs its precession rate. The very small systematic offset between the observed IER, COR, and OER pattern speeds and the predicted COR value is a consequence of the radial offset of the geometric center of the ring from the ring center of mass, discussed in Section 7.1. The resonance radius of the $m = -24$ OLR lies within the ring 1.082 km outside the ring’s IER, near to the $m = -24$ resonance of Cordelia computed from the mean motion given by Jacobson (1998), as shown at upper right. Similarly, the resonance radius of the $m = 14$ ILR also lies within the ring 0.887 km inside the ring’s OER, near to the mean motion resonance of Ophelia computed from the Jacobson (1998) mean motion, as shown at lower right. The more accurate recent Ophelia mean motion (Robert French, personal communication – labeled RF23) closely matches the observed $m = 14$ pattern speed.

6.5. Ring masses, surface densities, and a search for librations

In Section 6.1, we compared the pattern speeds of the inner and outer edges of the eccentric rings, and in several instances there appear to be significant differences that could be indications of librations, as has been observed at the outer edge of the B ring (Spitale and Porco 2010; Nicholson et al. 2014a; French et al. 2023b). Notably, $\Delta\dot{\varphi}$ for ring 4 and the α ring, and $\Delta\varpi_0$ for the β ring, appear to be significantly different from zero (see Table 5 and Fig. 26), although neither is statistically significant for the ϵ ring, where the experimental uncertainties are a factor of 10 smaller.

From the two-streamline self-gravity model of eccentric rings, Borderies et al. (1983) identified a characteristic libration frequency Ω_{sg} given by

$$\Omega_{\text{sg}} = \frac{n}{\pi} \frac{M_r}{M_{\text{Ur}}} \left(\frac{a}{\delta a'} \right)^2 H(q_e^2) = \frac{4n}{\pi} \frac{M_r}{M_{\text{Ur}}} \left(\frac{a}{\delta a} \right)^2 H(q_e^2), \quad (29)$$

where $n \simeq \sqrt{GM_{\text{Ur}}/a^3}$ is the ring particle mean motion and the factor of 4 in the right hand expression arises from the difference between $\delta a'$ and δa (Eq. (17)). The function $H(q_e^2)$ is defined in Eq. 14.

Assuming that self-gravity prevents differential precession due primarily to J_2 and combining Eqs. (13) and (29), the libration period for an eccentric ringlet $P_{\text{lib}} = 2\pi/\Omega_{\text{sg}}$ is given by

$$P_{\text{lib}} = \frac{8\pi}{21} \frac{a^{9/2}}{J_2 R^2 (GM_{\text{Ur}})^{1/2}} \frac{q_e}{ae}. \quad (30)$$

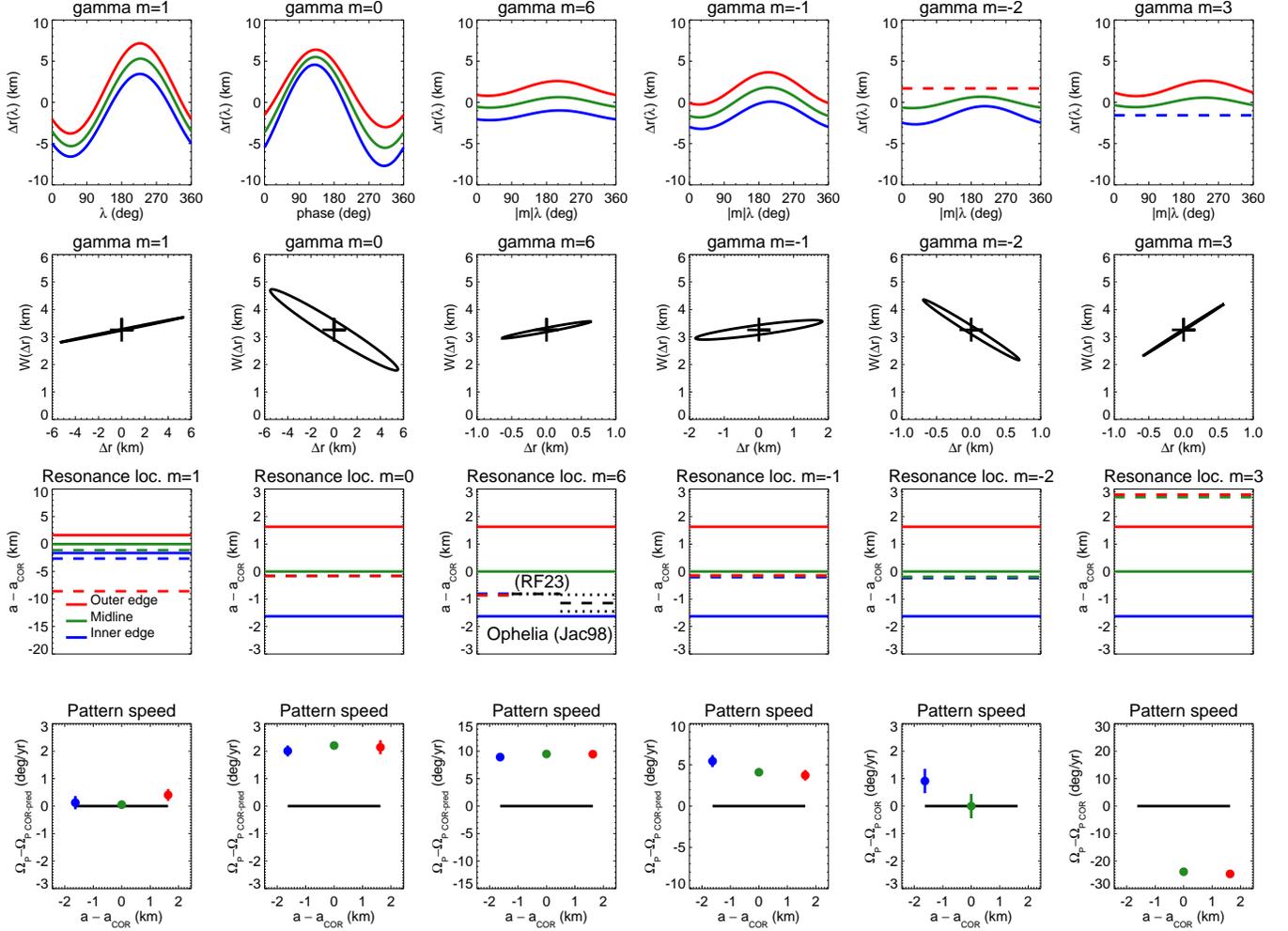


Figure 28. Width variations of the γ ring due to six normal modes, with the same layout as for Fig. 26. The predicted resonance location for Ophelia, assuming the mean motion given by Jacobson (1998) (labeled Jac98), is shown as a dashed line (bounded by its uncertainty) for the $m = 6$ mode, and lies within the ring, near its inner edge. The more accurate recent Ophelia mean motion (Robert French, personal communication – labeled RF23) has a predicted resonance location matching that of the observed $m = 6$ pattern speed. The $m = -2$ mode was not detected in the shape of the OER, and the $m = 3$ mode was not detected in the shape of the IER. The final row shows the differences in the observed pattern speeds of the inner and outer edges, and that of the COR, relative to the *predicted* COR value (based on the Uranus gravity field and satellite contributions to the precession rates), plotted as a function of semimajor axis relative to a_{COR} . Note the different vertical axis ranges for the final row of plots.

Alternatively, this can be written more simply as

$$P_{\text{lib}} = \left(\frac{2\pi}{\frac{d\dot{\omega}}{da} \delta a} \right) \frac{\delta e}{e} = P_{\Delta\dot{\omega}} \frac{\delta e}{e}, \quad (31)$$

where $\frac{d\dot{\omega}}{da} \delta a$ is just the differential precession frequency across the ring and the factor in parentheses is the corresponding differential precession period $P_{\Delta\dot{\omega}}$ of the inner and outer ring edges. Since $\delta e/e \ll 1$ for most of the eccentric rings, the predicted libration periods are considerably shorter than the differential precession periods.

Substituting numerical values appropriate for Uranus into Eq. (30),

$$P_{\text{lib}} = 960 \left(\frac{a}{50,000 \text{ km}} \right)^{9/2} \left(\frac{10 \text{ km}}{ae} \right) q_e \text{ yr}. \quad (32)$$

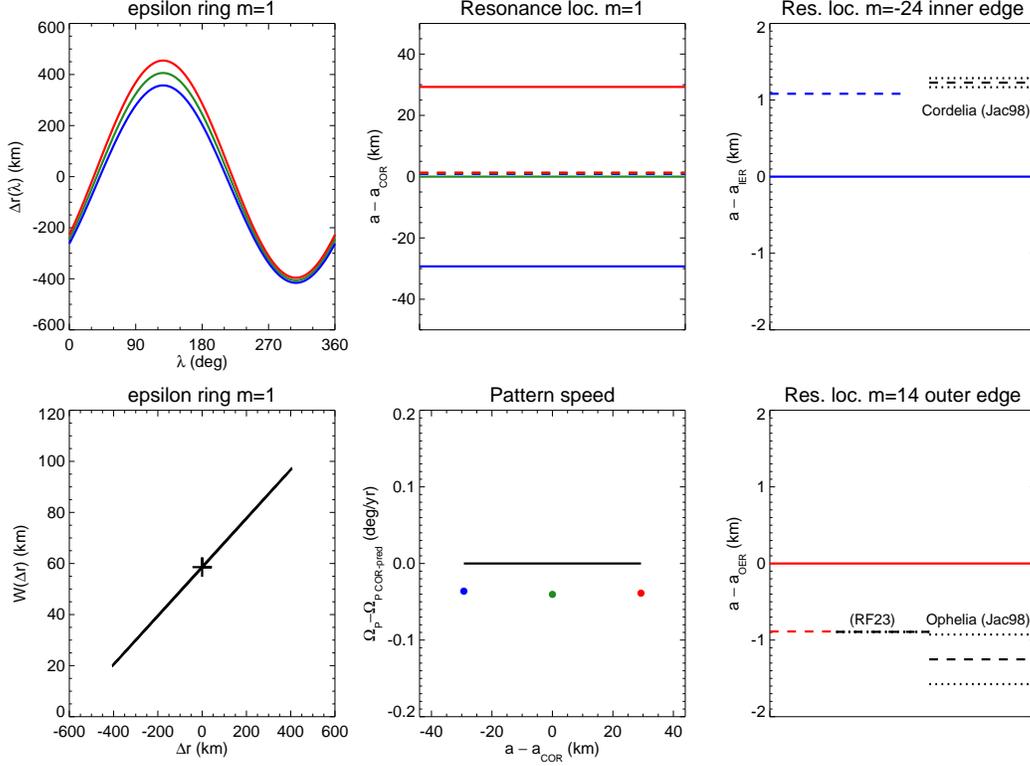


Figure 29. Width variations of the ϵ ring. Upper left: $\Delta r(\lambda)$, the variation of ring radius with inertial longitude λ at epoch for the IER, COR, and OER (blue, green, and red, respectively). Lower left: the corresponding variation of ring width $W(\Delta r)$. Upper middle: the predicted resonance radii corresponding to the observed apse rates at each ring edge relative to ring’s semimajor axis a_{COR} . Lower middle: the difference in the observed pattern speeds of the IER, COR, and IER relative to the predicted COR pattern speed, plotted as a function of semimajor axis relative to a_{COR} . Upper right: the resonance location of the $m = -24$ mode (shown as a dashed blue line) relative to the inner edge of the ϵ ring (solid blue line), computed from the fitted $m = -24$ pattern speed of the IER. The corresponding resonance location computed from the [Jacobson \(1998\)](#) mean motion of Cordelia (labeled Jac98) is shown as a black dashed line, bounded by its uncertainties shown as dotted lines. Lower right: the resonance location of the $m = 14$ mode (shown as a dashed red line) relative to the outer edge of the ϵ ring (solid red line), computed from the fitted $m = 14$ pattern speed of the OER. The corresponding resonance location computed from the [Jacobson \(1998\)](#) mean motion of Ophelia is shown as a black dashed line labeled Jac98, bounded by its uncertainties shown as dotted lines. The more accurate recent Ophelia mean motion ([Robert French, personal communication](#) – labeled RF23) has a predicted resonance location that closely matches that of the observed $m = 14$ pattern speed.

From the two-streamline self-gravity model, the mass of an eccentric ringlet (*i.e.*, with a free $m = 1$ mode) is given by

$$M_r = \frac{21\pi}{16} J_2 \left(\frac{R}{a} \right)^2 \left(\frac{e}{\delta e} \right) \left(\frac{\delta a}{a} \right)^3 \frac{M_{\text{Ur}}}{H(q_e^2)}. \quad (33)$$

For a ringlet with a free mode with $m \neq 1$, the corresponding relations are

$$P_{\text{lib}} = \frac{4\pi}{3(m-1)n} \frac{q_e}{e_m} = 3.1 \frac{1}{(m-1)} \left(\frac{a}{50,000 \text{ km}} \right)^{5/2} \left(\frac{10 \text{ km}}{ae_m} \right) q_e \text{ yr} \quad (34)$$

and

$$M_r = \frac{3\pi(m-1)}{8} \left(\frac{e_m}{\delta e_m} \right) \left(\frac{\delta a}{a} \right)^3 \frac{M_{\text{Ur}}}{H(q_e^2)}. \quad (35)$$

As noted by [Goldreich and Tremaine \(1979\)](#), the two-streamline self-gravity ring mass estimate differs from the results of more careful treatments that use a large number of streamlines $N \gg 2$. Assuming that q_e is constant across

the ring and that $\delta e/e \ll 1$, numerical results show that the many-streamline ring mass from the standard self-gravity (SSG) model converges almost exactly to

$$M_{\text{SSG}} = \frac{1}{2} M_r \quad (36)$$

for all of the eccentric Uranus rings.

The corresponding mean surface mass density from the many-streamline standard self-gravity model is given by

$$\Sigma_{\text{SSG}} = \frac{M_{\text{SSG}}}{2\pi a \delta a} = 3.18 \left(\frac{M_{\text{SSG}}}{10^{14} \text{ kg}} \right) \left(\frac{50,000 \text{ km}}{a} \right) \left(\frac{10 \text{ km}}{\delta a} \right) \text{ g cm}^{-2}. \quad (37)$$

The standard self-gravity model has been criticized on a number of grounds. For example, the derived surface densities for the α and β rings are quite low, and inconsistent with the inferred large particle sizes for these rings (French et al. 1991). Furthermore, the observed variations in the radial optical depth profile of the ϵ ring over a range of true anomalies disagree with model predictions (Graps et al. 1995). Goldreich and Porco (1987) pointed out that gas drag due to the extended hydrogen atmosphere of Uranus poses a severe problem for shepherding of the α and β rings unless their masses have been seriously underestimated. Finally, the model ignores potentially important dynamical effects, such as the requirement for ring shepherding that there be substantial collisional dissipation near ring edges (Borderies et al. 1982).

Motivated in part by these concerns, Chiang and Goldreich (2000) developed a heuristic collisional self-gravity (CSG) model for apse alignment of narrow eccentric rings that includes the pressure-induced accelerations resulting from interparticle collisions near ring edges. Their model assumes that $\delta e/e \ll 1$, that q_e is constant across the ring, and that the collisional pressure gradient is confined to a localized edge zone of radial scale $\lambda \simeq c_b/n$ (with dispersion velocity c_b and mean motion n) over which the ring surface density falls sharply to zero. The combined contributions to the precession rate across the ring due to planetary oblateness, ring self-gravity, and collisions uniquely determine the ring's radial surface density profile and total mass, for an assumed radial scale λ near the ring edge. By including the estimated effect of collisions, Chiang and Goldreich (2000) found surface densities for the α , β , and ϵ rings as large as $\Sigma = 75 - 100 \text{ g cm}^{-2}$, larger by more than a factor of 10 than the SSG values. Subsequently, Mosqueira and Estrada (2002) modified the treatment of the strong density gradients near ring edges in the Chiang and Goldreich (2000) model, but with generally similar results. Qualitatively, both of these CSG approaches result in large ring masses, concentrated near the ring edges, significantly exceeding the SSG values.

Using the width-radius results from Table 14, we have computed the masses and surface densities for each of the rings with a dominant free normal mode, using both the SSG and CSG models, as shown in Table 15, along with the libration periods P_{lib} predicted from the two-streamline SSG model. For the SSG calculations, we used $N=500$ streamlines. We adopted the computationally simpler Chiang and Goldreich (2000) solution to illustrate the collisional self-gravity approach, for a representative dispersion velocity of $c_b = 1 \text{ cm s}^{-1}$, corresponding to $\lambda = 35 - 50 \text{ m}$ over the ring system. (For the CSG calculations, we assumed a very large number of streamlines – $N=20,000$ – to ensure that the narrow transition zone near the ring edge was adequately sampled to provide accurate surface density values.) As these authors note, both M_{CSG} and Σ_{CSG} depend rather sensitively on the width of the ring edge transition region (or, equivalently, on the dispersion velocity), scaling approximately as $c_b^{1.5}$ in their model. In contrast, the Mosqueira and Estrada (2002) results are more weakly dependent on λ but nevertheless typically confine most of the ring mass to a small region near each edge.

To illustrate the general features of the SSG and CSG results, we show in Fig. 30 a set of radial surface density profiles computed for the α ring at quadrature, using $N=500$ streamlines. The surface density $\Sigma(a)$ is shown on a logarithmic scale at left. Under the assumption that the ring optical depth is proportional to the surface mass density, we show at right the corresponding radial optical depth profiles on a linear scale, normalized at the point of highest surface mass density. The legend at right applies to both panels. Notice first that the collisionless self-gravity profile (*i.e.*, the SSG model) has a convex shape, peaking at the midline of the ring, with a very low maximum surface mass density $\Sigma_{\text{SSG}} \simeq 1 \text{ g cm}^{-2}$. The Chiang and Goldreich (2000) results for $c_b = 1, 2$ and 4 cm s^{-1} (labeled CG2000) share the same general U-shape, but with substantially greater surface density than the SSG model, increasing as

Table 15. Ring masses, surface densities, and libration periods

Ring	$M_{\text{SSG}} \times 10^{14}$ (kg) ^a	Σ_{SSG} (g cm ⁻²) ^a	P_{lib} (yr) ^b	$M_{\text{CSG}} \times 10^{14}$ (kg) ^c	Σ_{CSG} (g cm ⁻²) ^d
6	0.04	0.58	37.6	6.78	111.37
5	0.23	3.20	8.5	7.51	105.47
4	0.11	1.23	25.6	8.13	94.05
α	0.19	0.93	66.3	12.46	60.96
β	0.15	0.60	118.1	13.52	55.33
δ^d	3.84	25.42	3.0		
ϵ	32.70	17.37	17.1	69.89	37.13

^a Computed using $N = 500$ streamlines in the standard self-gravity model (SSG), neglecting collisional effects.

^b Computed from Eq. (32).

^c Computed using $N = 20,000$ streamlines in the collisional self-gravity (CSG) model of [Chiang and Goldreich \(2000\)](#) for an assumed dispersion velocity $c_b = 1$ cm s⁻¹. As noted in the text, the ring mass and surface density scale as $c_b^{1.5}$.

^d Computed from the two-streamline self-gravity solution in Eq. (35) for $m = 2$.

c_b becomes larger and eventually reaching an average value $\Sigma_{\text{CSG}} > 100$ g cm⁻², but even larger values in excess of 1000 g cm⁻² near the ring edges. (In comparison, even the most opaque regions of Saturn’s B ring have surface densities in the range 100-140 g cm⁻² ([Hedman and Nicholson 2016](#).) The corresponding optical depth profiles at right are completely different from the bowl-shaped SSG profile, showing narrow opaque ring edge regions that increase in width with increasing c_b (or, equivalently, increasing λ), with much lower optical depth in the central region of the ring. To illustrate the modifications introduced by [Mosqueira and Estrada \(2002\)](#), we used their Eq. (20) representation of the collisional precession term to compute their CSG model, using $N = 500$ streamlines and $c_b = 2$ cm s⁻¹ (labeled ME2002). The derived surface density profile shows more massive edge regions than the [Chiang and Goldreich \(2000\)](#) models, with lower mass density in the interior of the ring near the midline. All of the CSG results shown have optical depth profiles that differ substantially from both the SSG model and (perhaps more significantly) are clearly a poor match to the observed shapes of the *Voyager* optical depth profiles (see Fig. B3).

Reviewing the entries in Table 15, the width-radius results for rings 6, 5, and 4 provide the first opportunity to estimate the masses and surface densities of these very narrow and morphologically similar rings. The SSG results yield very low but disparate surface densities Σ_{SSG} between 0.58–3.17 g cm⁻², roughly comparable to the α and β ring values. The CSG surface densities are larger by factors of ~ 100 , ranging from $\Sigma_{\text{CSG}} = 94$ to 111 g cm⁻², the largest of any of the rings shown. (We exclude the γ ring from the table because of the confounding and uncertain influence of its many normal modes.) The CSG surface densities for the α and β rings are in the range $\Sigma_{\text{CSG}} = 50$ –60 g cm⁻², similar to the results obtained by [Chiang and Goldreich \(2000\)](#), although the detailed models share the same issue in producing predicted radial optical depth profiles that differ substantially from the observations. The δ ring SSG surface density is computed from the $m = 2$ normal mode properties, rather than from the keplerian ellipse term in its orbital elements, yielding a value in between the ϵ ring SSG and CSG surface density values. For this very broad ringlet, the SSG and CSG models give broadly similar results, but very different predicted shapes for the radial optical depth profile.

In assessing the importance of collisional self-gravity to the narrow Uranian rings, we note that the physical assumptions of the [Chiang and Goldreich \(2000\)](#) model have a direct influence on the magnitude of the surface density enhancement relative to the standard self-gravity model. The most relevant of these relates to the magnitude of the very narrow scale λ over which the ring surface density drops to zero at the ring edge. More specifically, they assume that $\lambda \sim c_b/n$ where c_b is the ring velocity dispersion in the region of width w perturbed by the satellite responsible for the edge confinement, and n is the local mean motion. There is no explicit justification for this choice of λ in [Chiang and Goldreich \(2000\)](#), but it is consistent with the following arguments:

- On the one hand, λ cannot be smaller than c_b/n , otherwise the Rayleigh stability criterion would be violated (the pressure gradient would be large enough to change the specific angular momentum distribution from stable

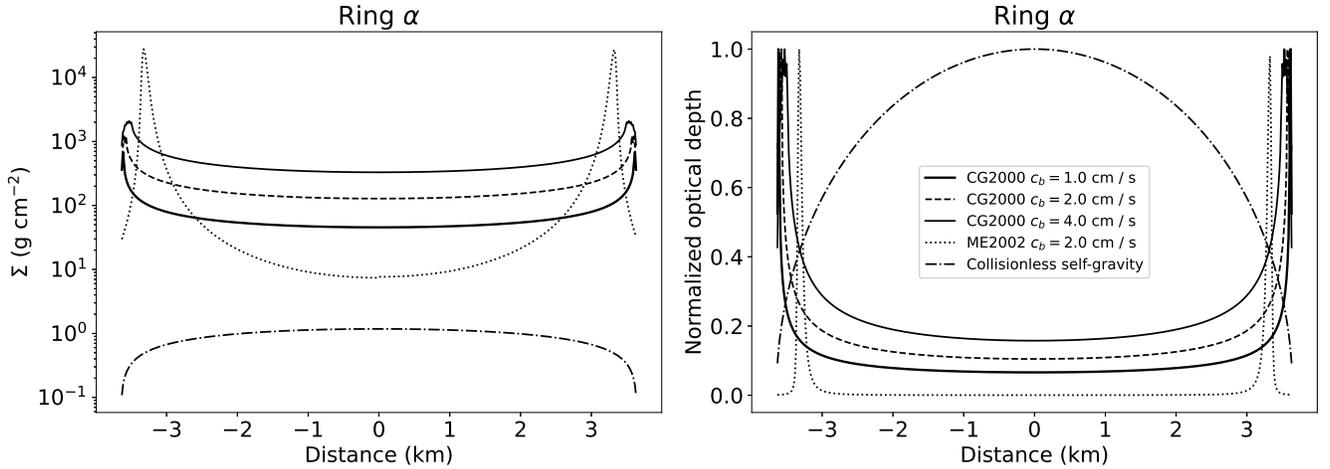


Figure 30. Surface density profiles for the α ring at quadrature, shown on a logarithmic scale and left and normalized by their maximum values at right on a linear scale to show their predicted normal optical depth profiles. The collisionless self-gravity model (SSG) has a convex shape in both panels and a very low mean surface density $\Sigma_{\text{SSG}} < 1 \text{ g cm}^{-2}$. Three CSG profiles computed using the Chiang and Goldreich (2000) model with dispersion velocities $c_b = 1, 2,$ and 4 cm s^{-1} show much larger mean surface densities, increasing $\propto c_b^{1.5}$, with characteristic U-shaped optical depth profiles at right. The alternate collisional model of Mosqueira and Estrada (2002) is included for $c_b = 2 \text{ cm s}^{-1}$, showing qualitatively similar high surface densities confined to the ring edges.

to unstable (Lin and Papaloizou 1993). If for some reason the drop in surface density at the edge occurred on a yet smaller scale, the ring edge would become unstable and broaden again until stability is restored and this minimum scale satisfied.

- On the other hand, choosing the smallest possible scale λ maximizes the pressure gradient at the edge and, as a consequence, the mass increase of a narrow ring at a given geometry with respect to the SSG model.

Maximizing the mass of the ring allowed Chiang and Goldreich (2000) to assess whether the CSG model is able to overcome the mass deficit problem pointed out by Goldreich and Porco (1987). But although explaining sharp ring edges was a puzzle when they were first discovered, making the edge as sharp as possible is not a dynamical necessity; ultimately, the scale λ is determined by (unknown) detailed properties of the ring stress tensor. As seen in Figs. 31, B1, and B2, there is no observational reason to assume that the inner edges of rings 6, 5, and 4 are as sharp as assumed by Chiang and Goldreich (2000), and the outer edges, while generally sharper, may be gradual on the scale of tens of meters. Given our current state of understanding, these points indicate that it is probably best to view the SSG surface density as a minimum value and the CSG one as a maximum one.

Turning now to the predicted libration periods in Table 15, note that for most rings they are decades long, making any such libration challenging to detect over the rather sparsely populated 30-year span of the occultation observations. At the other extreme, the $m = 2$ mode of the δ ring has a predicted libration period of only 3 years, which is comparable to the typical interval between observations and thus susceptible to aliasing. Using the algorithm of Nicholson et al. (2014a), we performed a series of fits for each ring, similar to normal mode scans, in which we specified a grid of possible libration periods between 1 and 100 years, solved for the best-fitting amplitude and phase of the libration for each period, and tabulated the RMS residuals for each fit. None of the scans returned a convincing, unique fit with a minimum RMS for a single libration period, and there was considerable aliasing for libration periods shorter than ~ 5 years owing to the sparse sampling of the observations on this timescale.

Looking in more detail at specific examples, Fig. 26 shows that the inner and outer edges of rings 4 and α have fitted apse rates that differ by $\Omega_P(\text{OER}) - \Omega_P(\text{IER}) = \delta\Omega_P \sim 0.1 - 0.2 \text{ }^\circ \text{ yr}^{-1}$ with OER and IER apses misaligned by $\delta\varpi = -1.10 \pm 0.26^\circ$ for ring 4 and by $+0.36 \pm 0.29^\circ$ for the α ring.

These can be compared to the apse misalignment expected over one quarter of a libration period $\Delta\varpi_{\text{lib}} = \Delta\Omega_P P_{\text{lib}}/4$. For ring 4, $\Delta\varpi_{\text{lib}} = 0.8^\circ$, of the same order as $\Delta\varpi$, meaning that the observed apse misalignment is of the same order as the range of excursions expected if the ring is librating. For the α ring, on the other hand, $\Delta\varpi_{\text{lib}} = 3.9^\circ$, more than an order of magnitude larger than the observed apse misalignment. If this ring is librating with a long period compared to the span of the observations, the probability of observing the apses so closely aligned would be rather small. If the ring is librating, $\Delta\Omega_P$ should be at its maximum when the apses are aligned. The ϵ ring has both well-aligned apses ($\Delta\varpi = -0.028^\circ$ from Table 5) and very small $\Delta\Omega_P < 0.0026^\circ \text{ yr}^{-1}$. Assuming simple harmonic motion, the amplitude of the libration $\Delta\phi \sim \Delta\Omega_P/\Omega_{\text{sg}} = \Delta\Omega_P P_{\text{lib}}/2\pi \sim 0.007^\circ$. That is, if the ϵ ring is indeed librating with a period of 17.1 yr, the fitted edge apses and apse rates imply that the amplitude of libration is very small ($\sim 0.01^\circ$), below the level of detectability in our libration scans.

In a more systematic attempt to set lower limits on librations, we make use of the fit results in Table 15 and proceed in the follow steps:

1. Assume that $\delta\varpi = A_L \cos[2\pi(t - t_0)/P_L]$, where P_L is the (unknown) libration period and A_L is the (unknown) libration amplitude.
2. It follows that $\delta\dot{\varpi} = -\frac{2\pi A_L}{P_L} \sin[2\pi(t - t_0)/P_L]$.
3. Assume the nominal values of P_L given in Table 15, based on the standard SSG model.
4. Use the observed value of either $\Delta\varpi$ or $\Delta\dot{\varpi}$ to estimate a lower limit on A_L . The larger amplitude A_L wins.

Following this prescription, we find that for the α ring, $\delta\dot{\varpi}$ dominates and $A_L > 2.4^\circ$. For the β, δ , and ϵ rings, $\delta\varpi$ dominates and $A_L > 3.0^\circ, 0.4^\circ$, and 0.03° , respectively. For rings 6, 5 and 4 the two limits are comparable (within a factor of 2), with $A_L > 0.2^\circ, 0.03^\circ$, and 1.1° , respectively.

In principle, more conclusive results could be obtained by subdividing the observations into several time intervals and mapping the variations of the fitted values of $\delta\Omega_P$ and $\delta\varpi$ over time to see if their phases matched the pattern expected for librations. This approach proved unsuccessful, however, owing to the uneven distribution of observations over time and the relatively small number of observations of each ring. We are left with the conclusion that any librations, if present, are at the margin of detectability.

7. URANUS GRAVITY FIELD

In the orbit fits for the eccentric and inclined rings given in Table 5, we treated the apsidal precession and nodal regression rates as kinematical parameters without any dynamical constraints. We now use the fitted apse and node rates to constrain the lowest-order zonal harmonic coefficients J_2, J_4 , and J_6 of the Uranus gravity field. An immediate challenge is that the radial range of the measurements spans less than 10,000 km, or equivalently, R/a in Eq. (2) varies only between 0.61 and 0.50 from the ring 6 to the ϵ ring, whereas to leading order the radial dependence of the J_n terms is a sequence of steepening power laws: the J_2 term $\propto a^{-7/2}$, $J_4 \propto a^{-11/2}$, and $J_6 \propto a^{-15/2}$. As a result, J_2, J_4 , and J_6 are strongly correlated, and in particular the ring occultation data alone cannot yield an independent estimate of J_6 , although the fit results provide coupled constraints on the trio J_2, J_4 , and J_6 . In this section, we identify additional systematic and random errors that affect the determination of the gravity field, quantify their effects on the derived J_n , and provide a prescription to compute the difference in standard deviations between our best-fitting model and other model gravity fields described by the first three even gravity harmonics.

7.1. Ring midlines, centers of opacity, and centers of mass

In addition to the challenge of a restricted radial range of observed apse and node rates noted above, a second complication that has not been previously addressed is that the apse and node rates in Table 5 are usually assumed to

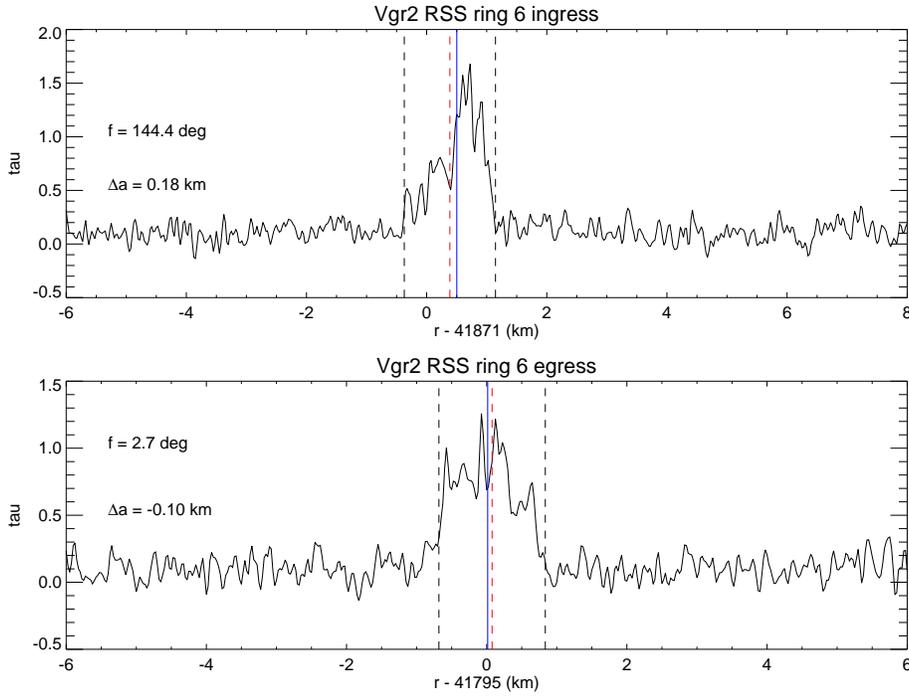


Figure 31. Ring 6 center of opacity (COO) estimated from *Voyager* RSS optical depth profiles. The derived values of r_{COO} are shown by the solid vertical blue line near the middle of each profile, but on opposite sides of the geometric center (COR) for ingress and egress, marked by the vertical dashed red lines mid-way between the two edges.

refer to the semimajor axes of the geometric ring midlines (COR), which may not correspond to the dynamical radius, or semimajor axis of the average center of mass (COM) of the rings. This is of particular concern for the ϵ ring, which has manifestly non-uniform internal radial structure, as seen in Fig. 2, but it applies to the other rings as well, as can be seen from the high-resolution *Voyager* RSS ring profiles. **Figure 31** shows the ingress and egress RSS optical depth profiles of ring 6. The ingress profile is near apoapse with true anomaly $f = 144.4^\circ$, while the egress profile is almost exactly at periapse, with $f = 2.7^\circ$. Under the simplifying approximation that optical depth is proportional to surface mass density, and thus using the center of opacity (COO) as a surrogate for the ring’s COM, we define the radii of the inner and outer ring edges r_{IER} and r_{OER} by the vertical dashed lines, chosen by eye, and determine the radius of the center of opacity r_{COO} by integrating the radial normal optical depth profile $\tau(r)$ using

$$r_{\text{COO}} = \frac{\int_{r_{\text{IER}}}^{r_{\text{OER}}} \tau(r) r dr}{\int_{r_{\text{IER}}}^{r_{\text{OER}}} \tau(r) dr}. \quad (38)$$

The derived values of r_{COO} for the two RSS ring 6 observations are shown by the solid vertical blue line near the middle of each radial profile. For both ingress and egress, this is offset from the midline of the ring, marked by the vertical dashed red line mid-way between the two edges. We then determine the equivalent offset of the ring semimajor axis center of opacity Δa_{COO} from the relation

$$\Delta a_{\text{COO}} = \left(\frac{r_{\text{COO}} - r_{\text{IER}}}{r_{\text{OER}} - r_{\text{IER}}} - \frac{1}{2} \right) \overline{W} \quad (39)$$

where \overline{W} is the mean width of the ring defined by the difference in semimajor axes of the OER and IER fits in Table 5. Numerically, $\Delta a_{\text{COO}} = +0.18$ km and -0.10 km for the ring 6 ingress and egress profiles, respectively.

In this instance, it is clear that the internal structure of ring 6 is quite different at the two locations sampled by the RSS occultations, which may not be representative of the structure at other ring longitudes. In any event, there are no streamline models for the internal structure of any of the rings that accurately capture the ring structure at

all longitudes, and we use the RSS observations to estimate the uncertainty of the ring COO or COM as well as its systematic offset from the geometric ring center determined from square-well fits to the ensemble of ring profiles.

We proceed similarly in Appendix B for the other eccentric rings, making additional use of the best Earth-based radial profiles for the ϵ ring in instances where it is wide enough to reveal internal structure. The derived centers of opacity are given in **Table 16**, which lists a_{COR} , the unweighted average values for Δa_{COO} and their RMS variation, the statistical significance $\Delta a_{\text{COO}}/\sigma(\Delta a_{\text{COO}})$, and finally of a_{COO} , with an uncertainty given by the sum in quadrature of $\sigma(a_{\text{COR}})$ and $\sigma(\Delta a_{\text{COO}})$.

Table 16. Ring center of opacity

Ring	a_{COR} (km)	Δa_{COO} (km)	$\frac{\Delta a_{\text{COO}}}{\sigma(\Delta a_{\text{COO}})}$	a_{COO} (km)
6	41837.092 ± 0.096	0.040 ± 0.193	0.208	41837.132 ± 0.215
5	42234.893 ± 0.091	0.169 ± 0.100	1.686	42235.061 ± 0.135
4	42571.124 ± 0.091	0.404 ± 0.087	4.620	42571.528 ± 0.126
α	44718.473 ± 0.086	0.172 ± 0.132	1.309	44718.645 ± 0.157
β	45661.056 ± 0.087	0.322 ± 0.274	1.175	45661.378 ± 0.288
γ	47626.170 ± 0.089	0.119 ± 0.125	0.954	47626.289 ± 0.153
ϵ	51149.279 ± 0.081	1.134 ± 0.488	2.324	51150.414 ± 0.495

The mean offset Δa_{COO} is positive for all seven eccentric rings but statistically significant at the $2\text{-}\sigma$ level only for ring 4 and the ϵ ring. We will make use of both the offsets and their uncertainties in our final determination of the Uranus gravity field.

As an illustration of the effect of the offset Δa_{COO} on the computed precession rate, note that at the radius of the ϵ ring, $d\dot{\omega}/da = -9.355 \times 10^{-5} \text{ }^\circ \text{ d}^{-1} \text{ km}^{-1}$, and the corresponding change in apse rate for $\Delta a_{\text{COO}} = 1.134$ km from Table 16 is $\Delta\dot{\omega} = -1.06 \times 10^{-4} \text{ }^\circ \text{ d}^{-1}$. To put this in context, the formal error in the apse rate $\sigma(\dot{\omega})$ for the ϵ COR from Table 5 is just $4.2 \times 10^{-6} \text{ }^\circ \text{ d}^{-1}$, and thus the radial change Δa_{COO} corresponds to change of $\Delta\dot{\omega}/\sigma(\dot{\omega}) \sim -1.06 \times 10^{-4}/4.2 \times 10^{-6}$, or a 25σ change in the predicted apse rate. Note that for the ϵ ring COR in Table 5, $\Delta a_{\dot{\omega}} = 1.154 \text{ km} \simeq \Delta a_{\text{COO}} = 1.134 \text{ km}$, demonstrating that the adopted gravity field takes into account the systematic difference between the ring’s COR and COO.

Figure 32 (top panel) shows the observed ring apse and node rates from Table 5, plotted as solid dots, compared to the smooth curve computed from our adopted gravity model (Fit 18 in Table 17), described below in Section 7.2. The second panel shows the difference $\Delta\dot{\omega}$ between the individually fitted apse rates from Table 5 (with their error bars) and the rates predicted by the adopted gravity model (solid dots), and from individual alternative fits (shown as open circles) that ignored the apse and node rates of each ring in turn when fitting for J_2 and J_4 . (Both series of fits account for the offsets Δa_{COO} .) The bottom panel shows $\Delta\dot{\Omega}$ for the node rates of the measurably inclined rings. The observed apse and node rates generally match the predicted values, with the possible exceptions of the α , β , and γ ring apse rates. In Section 8, we will examine the evidence for anomalous precession rates of these rings and evaluate possible explanations.

7.2. Determining the planetary gravity field from ring precession rates

Historically, the most accurate estimates of the Uranus gravity field have been derived from the observed precession rates of the rings (French et al. 1988; Jacobson 2014). With the inclusion of all ring occultation data between 1977–2006, the uncertainties in the ring apsidal and nodal rates have been substantially reduced compared to prior determinations. As we will show, however, both the mean values of J_2 and J_4 and their realistic uncertainties from ring occultation data are significantly affected by the assumed value of J_6 and by previously ignored systematic and random errors in: (1) the estimates of the ring centers of opacity (COO), (2) the absolute radius scale, and (3) the estimated contributions of both major and minor satellites to the ring precession rates. In this section, we review

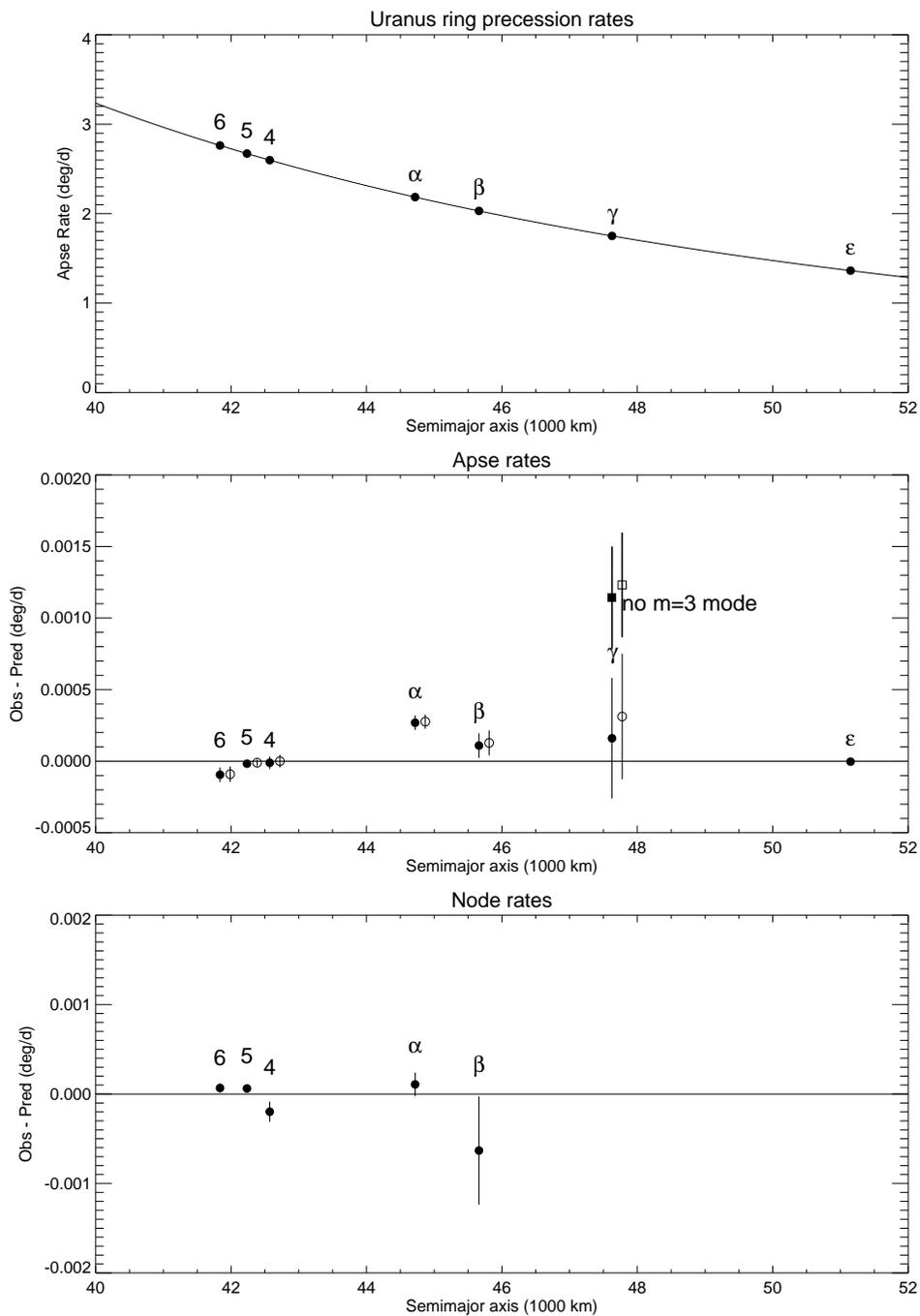


Figure 32. Uranus ring apse and node precession rates. The top panel shows the observed apse rates of the eccentric rings, overplotted with the predicted radial variation in apse rate computed from the adopted gravity model (Fit 15 in Table 17). The middle panel shows the differences between the observed and predicted apse rates $\Delta\dot{\omega}$ for each ring’s center of opacity (COO), (unlike the Table 5 values, which apply to the ring’s geometric centers (COR)), plotted as filled symbols. The open symbols show the estimated anomalous precession based on separate fits for J_2 and J_4 that excluded the contribution of individual rings to the gravity field solution. These are listed in Table 18. Rings α , β , and possibly γ appear to have anomalously high precession rates compared to the predictions from the gravity model. For the γ ring orbit fit that excluded the $m = 3$ mode, the anomalous precession is even higher (shown as a filled and open squares). The bottom panel shows the node rate difference $\Delta\dot{\Omega}$ for the inclined rings.

previous gravity field determinations and estimate the influence of these error sources on the derived gravity harmonics. Although we cannot obtain an independent estimate of J_6 , we derive a set of observationally constrained linear relations between J_2 , J_4 , and J_6 based on their strong mutual correlations in the ring orbit fits.

7.2.1. Previous determinations of the Uranus gravity field

French et al. (1988) determined J_2 and J_4 from orbit fits to ring occultation observations from 1977–1986, with the results listed as Fit 1 in **Table 17**, converted from their assumed reference radius of $R = 26200$ km to $R = 25559$ km. Jacobson (2014) solved for J_2 and J_4 from a comprehensive analysis of all available *Voyager* navigation data and selected ring occultation measurements, and in a separate solution from the ring data alone. These results are listed as Fits 2 and 3, respectively.¹¹ Jacobson (2014) assumed that $J_6 = 0$, but the quoted uncertainties in J_2 and J_4 incorporated an *a priori* uncertainty $\sigma(J_6) = 1.0 \times 10^{-6}$, as well as *a priori* uncertainties on other parameters of the fit including the absolute radius scale and the pole direction. The resulting “rings only” solution (Fit 3) is shown in **Fig. 33** as the large solid-line brown ellipse.

More recently, Jacobson (2023) estimated J_2 and J_4 as part of a global solution for the Uranus ephemeris and system properties, based on a comprehensive analysis of historical astrometry, navigation data, and ring occultation observations. He set $J_6 = (0.58 \pm 0.12) \times 10^{-6}$, based on a suite of Uranus interior models by Neunschwander and Helled (2022), and the satellite contribution to the precession of the rings was included for Ariel, Umbriel, Titania, Oberon, Miranda, and Puck only, ignoring the minor satellites. (The assumed masses of these six satellites are included in Table 2.) The Jacobson (2023) results are shown **Fig. 33** as Fit 4, where the error bars include estimated uncertainties in the astrometry and navigation data used for the fit.

Table 17. Uranus gravity parameters

Fit	$J_2 \times 10^{-6}$	$J_4 \times 10^{-6}$	$J_6 \times 10^{-6}$	$\rho(J_2, J_4)$	Note
1	3513.23 ± 0.34	-30.32 ± 4.73	–	–	French et al. (1988) (converted to $R = 25559$ km)
2	3510.7 ± 0.7	-34.2 ± 1.3	0.0 ± 1.0	0.9784	Jacobson (2014) adopted solution
3	3510.5 ± 1.3	-34.4 ± 1.3	0.0 ± 1.0	0.9784	Jacobson (2014) “rings only” solution
4	3510.465 ± 0.058	-34.145 ± 0.082	0.58 ± 0.12	0.9887	Jacobson (2023) (ura178 ephemeris)
5	3510.464 ± 0.066	-34.158 ± 0.092	[0.58]	0.9384	COR – 6 satellites (AUTOMP)
6	3510.474 ± 0.056	-34.135 ± 0.081	[0.58]	0.9853	COR wtd fit to apse/node rates (AUTOMP)
7	3511.175 ± 0.065	-33.492 ± 0.092	[0.50]	0.9384	COR + COO offsets (Table 16) – 6 satellites (AUTOMP)
8	3510.975 ± 0.065	-34.030 ± 0.092	[0.0]	0.9384	Fit 7 but $J_6 = 0 \times 10^{-6}$
9	3511.374 ± 0.065	-32.954 ± 0.092	[1.0]	0.9384	Fit 7 but $J_6 = 1 \times 10^{-6}$
10	3511.201 ± 0.065	-33.528 ± 0.092	[0.50]	0.9384	Fit 7 with $\Delta a = +0.2$ km for all rings
11	3510.723 ± 0.065	-33.957 ± 0.092	[0.50]	0.9384	Fit 7 including all but Cordelia and Ophelia
12	3509.291 ± 0.067	-35.522 ± 0.094	[0.50]	0.9383	Fit 7 incl. all sats, basis for Monte Carlo Fit 15
13	3513.217 ± 0.065	-31.669 ± 0.091	[0.50]	0.9384	Fit 7 excluding all satellites
14	3509.337 ± 0.065	-35.438 ± 0.091	[0.50]	0.9387	COO, all satellites, rings 6,5,4 ϵ for J_n
15	3509.291 ± 0.412	-35.522 ± 0.466	[0.50]	0.9861	Adopted solution: Fit 12 w/ composite error estimates
16	3509.291 ± 0.385	-35.522 ± 0.433	[0.50]	0.9957	Monte Carlo errors from COO fits to apse/node rates only
17	3509.291 ± 0.134	-35.522 ± 0.147	[0.50]	0.9997	Monte Carlo errors from satellite mass uncertainties only
18	3509.291 ± 0.026	-35.522 ± 0.036	[0.50]	0.1412	Monte Carlo errors from radius scale uncertainty only
Quantity	Value				Note
GM_U	$5793950.300 \text{ km}^3 \text{ s}^{-2}$				Jacobson (2023)
R	25559 km				Reference radius for J_n
dJ_4/dJ_2	+1.134				slope of error ellipse of adopted solution
dJ_4/dJ_2	+2.69540				slope of line connecting COO $J_6 = (0, 1) \times 10^{-6}$
dJ_2/dJ_6	+0.39909				over range $J_6 = (0, 1) \times 10^{-6}$
dJ_4/dJ_6	+1.07570				over range $J_6 = (0, 1) \times 10^{-6}$
$dJ_2/d\Delta a$	$+0.130 \times 10^{-6} \text{ km}^{-1}$				from Fits 7 and 10
$dJ_4/d\Delta a$	$-0.180 \times 10^{-6} \text{ km}^{-1}$				from Fits 7 and 10

¹¹ The correlation coefficient $\rho(J_2, J_4)$ for these fits was provided by R. Jacobson, personal communication.

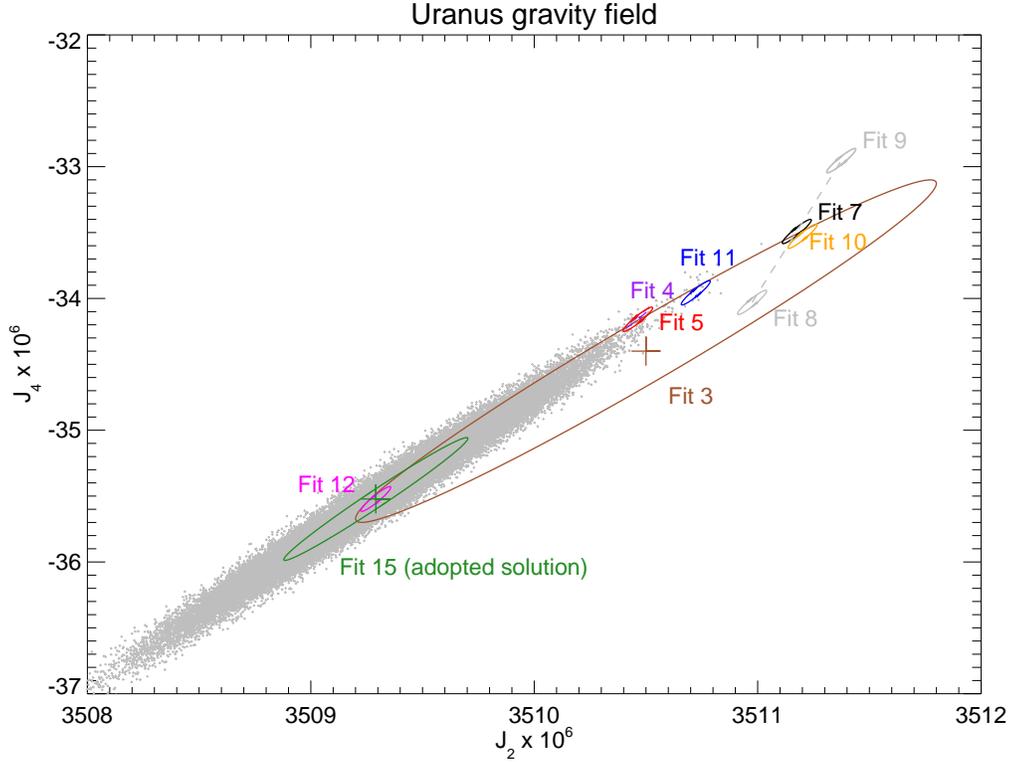


Figure 33. Results of a suite of fits for J_2 and J_4 , under a variety of assumptions about the value of J_6 , the contributions of major and minor satellites to the ring precession rates, the differences between the ring COR and COO, and the absolute radius scale of the rings. The fit numbers correspond to the results in Table 17. The adopted fit (Fit 15) includes error estimates derived from the Monte Carlo set of solutions marked by the gray dots, representing the range of variation in J_2 and J_4 associated with estimated error sources. See text for details.

7.2.2. Uranus gravity field from COR ring orbital elements

To provide an initial estimate of J_2 and J_4 from the complete set of COR measurements used to derive the orbital elements in Tables 5 and 6, we performed Fit 5, using the same fit parameters as our adopted COR fit except that the ring apse and node rates were calculated from the best-fitting values of J_2 and J_4 , a fixed value for J_6 , and the secular precession forced by the satellites included only Ariel, Umbriel, Titania, Oberon, Miranda, and Puck, omitting the estimated contributions of the smaller moons displayed in Fig. 4. To provide a direct comparison with Jacobson (2023), we let $J_6 = 0.58 \times 10^{-6}$. This solution is plotted as the red error ellipse in Fig. 33. The fitted values for J_2 and J_4 are very similar to the Jacobson (2023) result (Fit 4), showing that these two independent solutions based largely on the same set of observations yield nearly identical results.

Next, in Fit 6, we determined J_2 and J_4 from a weighted fit to the apse and node rates in Table 5, again assuming $J_6 = 0.58 \times 10^{-6}$. As seen in Table 17, the results are similar to Fit 5, but with slightly smaller error bars and a larger correlation coefficient. The fitted values and error bars are quite close to the Jacobson (2023) results in Fit 4 as well. This confirms that the primary constraints on J_2 and J_4 in the full RINGFIT results are the apse and node rates, while the other free parameters have less influence on the fitted values and uncertainties of the gravity parameters.

In a separate fit, not included in Table 17, we allowed J_6 to be an additional free parameter, but the resulting formal errors in all three gravity parameters were very large, the retrieved value of J_6 was implausibly large, and the correlations between the parameters were nearly singular.

7.2.3. Uranus gravity field from COO ring orbital elements

To explore the effects on the derived gravity field of applying the ring radius corrections associated with the COO measurements, in Fit 7 we applied the offsets Δa_{COO} from Table 16 to the fitted ring semimajor axes when computing the precession rates and let $J_6 = 0.5 \times 10^{-6}$, with all other fit conditions as in Fit 5. The result is shown as a black error ellipse and is significantly displaced from the COR solution (Fit 5), demonstrating the sensitivity of J_2 and J_4 to the differences between the geometric ring centers (COR) and their dynamical centers (COO).

7.2.4. Sensitivity of J_2 and J_4 to the assumed value of J_6

Although our experiment with Fit 5 described above demonstrates that we cannot fit simultaneously for J_2 , J_4 , and J_6 , we can nevertheless quantify the sensitivity of the results to assumed (fixed) values of J_6 . In Fits 8 and 9, we let $J_6 = (0.0, 1.0) \times 10^{-6}$ respectively, applied the COO offsets as before, and solved for J_2 and J_4 . The results are shown as the labeled gray error ellipses in Fig. 33, bracketing the COO Fit 7 that assumed $J_6 = 0.5 \times 10^{-6}$. From this pair of fits, we find the partial derivatives dJ_2/dJ_6 and dJ_4/dJ_6 listed at the bottom of Table 17. The ratio of these gives the slope of the line connecting the COO $J_6 = (0.0, 1.0) \times 10^{-6}$ solutions, shown as the gray dashed line in the figure and listed in Table 17.

7.2.5. Sensitivity of J_2 and J_4 to the absolute radius scale

To quantify the effect of a possible systematic error in the overall absolute ring radius scale, in Fit 10 we repeated Fit 7, but assumed a systematic radius scale error of $\Delta a = +0.2$ km (our $2\text{-}\sigma$ estimate, as shown in Section 5.2). The result of the fit is shown as the orange error ellipse in Fig. 33, only slightly displaced from Fit 7, indicating that a radius scale error at this level has only a modest effect on the derived gravity field. This is evident in the small magnitude of the differentials $dJ_2/d\Delta a$ and $dJ_4/d\Delta a$ included at the bottom of Table 17.

7.2.6. Effects of minor satellites on the derived gravity field

Previous published determinations of J_2 and J_4 have taken into account the secular precession due to Ariel, Umbriel, Titania, Oberon, Miranda, and Puck, but have ignored the contributions of the smaller moonlets. As shown in Fig. 4, several of these minor satellites each have predicted secular precession rates for several of the eccentric rings that are larger than those due to Oberon and Puck, and in particular Cordelia and Ophelia are estimated to contribute jointly to precession rate of the ϵ ring at a level of $\dot{\omega} > 10^{-4} \text{ }^\circ \text{ d}^{-1}$, greater than that of any of the other satellites except Ariel. To quantify the effect of the minor satellites, we first performed Fit 11, similar to Fit 7 except for the inclusion of all moons except Cordelia and Ophelia. The fitted values of J_2 and J_4 are significantly offset from the Fit 7 values, with the results shown as the blue error ellipse in Fig. 33. Then, in Fit 12 we added the predicted precession due to tiny Cordelia and Ophelia, with the resultant values of J_2 and J_4 shown as the magenta error ellipse, shifted even further from the Fit 7 values that used only the six most massive moons. For comparison, in Fit 13 we ignored the effects of all satellites when computing the ring precession rates. The resulting values are off-scale to the upper right of the figure. The differences between Fits 7, 11, 12 and 13 demonstrate the sensitivity of the derived values of J_2 and J_4 to the assumed minor satellite masses and the uncertainties in the masses of both major and minor satellites. We evaluate these effects below.

7.3. The influence of the α , β , and γ rings on the derived gravity field

Figure 32 shows that the apse rates of the α , β , and γ rings in the COR fit for J_2 and J_4 are systematically faster than predicted from the gravity solution. To quantify the influence of these three rings on the derived gravity field, we performed Fit 14, in which we applied COO corrections, included the effects of all major and minor satellites, but allowed the apse and node rates of the α , β , and γ rings to be free parameters, rather than being constrained by J_2 and J_4 . Only rings 6, 5, 4, and ϵ were so constrained. As shown in Table 17, the fitted values for J_2 and J_4 differed only slightly from the Fit 12 results, indicating that the possibly anomalous precession rates of the α , β , and γ rings do not produce a significant systematic shift in the derived gravity field.

7.3.1. Effects of random and systematic errors on the derived gravity field

So far, we have separately estimated the sensitivity of the derived values of J_2 and J_4 to the assumed value of J_6 , to differences between ring centerlines and centers of opacity (COR and COO, respectively), to possible systematic errors in the absolute radius scale, and to the contributions of small moons to the ring precession rates. All of these systematic effects have associated uncertainties that affect the robustness of the fitted gravity field. To quantify the effects of both random and systematic errors on the derived gravity field, we performed a series of Monte Carlo fits that sampled a random distribution of estimated uncertainties in key quantities that affect the best-fitting solution for J_2 and J_4 . We used the conditions of Fit 12 (including all satellites and the COO offset) as our nominal best fit for J_2 and J_4 . Then, for each of 50,000 fits, we applied separate offsets to the semimajor axes of each ring, drawn randomly from a normal distribution with the corresponding individual standard deviation in the COO semimajor axis $\sigma(\Delta a_{\text{COO}})$. To account for the uncertainty in the absolute radius scale, we applied an additional single random systematic offset Δa to the semimajor axes of *all* of the rings, drawn from a normal distribution with a standard deviation of 0.2 km. Finally, to account for uncertainties in the masses of both major and minor satellites when computing their contributions to each ring’s secular precession rate, we applied offsets to the individual satellite masses drawn randomly from a normal distribution with a standard deviation for each major satellite taken from [Jacobson \(2023\)](#) and for the minor satellites from [Table 3](#), assuming our derived masses for Cressida, Cordelia, and Ophelia.

We determined J_2 and J_4 for each Monte Carlo instance from a least squares fit to the entire system geometry, with the apse and node rates of the eccentric and inclined rings being determined from the combined effects of the modeled gravity field and satellite contributions, assuming $J_6 = 0.5 \times 10^{-6}$ for all fits. The ensemble of fitted values of J_2 and J_4 represents the probability density function (PDF) associated with the applied random errors. To determine the corresponding error ellipse, we first determined the mean values of J_2 and J_4 and their standard deviations from the distribution of their fitted values. Next, we estimated the correlation coefficient $\rho(J_2, J_4)$ by determining its value such that the corresponding 1- σ error ellipse for $\sigma(J_2)$ and $\sigma(J_4)$ enclosed $e^{-1/2} \simeq 0.6065$ of the fitted values, as appropriate for the complementary cumulative probability distribution of a bivariate normal distribution (see [Appendix C](#)). The results are given in [Table 17](#) as Fit 15, our adopted solution and error bars. The mean values for J_2 and J_4 match those from Fit 12, as expected, but with much larger uncertainties, owing to the incorporation in the Monte Carlo runs of the estimated random errors in Δa_{COO} , Δa , and the satellite contributions to the ring precession rates.

To quantify the various contributions to the total error budget, we performed three separate Monte Carlo runs. For Fit 16, we included only the estimated errors due to standard deviations in the COO semimajor axes $\sigma(\Delta a_{\text{COO}})$. For Fit 17, we included only the contributions of the uncertainty in satellite masses to the error budget. Finally, in Fit 18, we included only the uncertainty in the absolute radius scale. The results are given in [Table 17](#). In all cases, the mean values of J_2 and J_4 matched those of our adopted solution, as expected, and the quoted error bars correspond to the standard deviations in the fitted values J_2 and J_4 from the 50,000 individual random samples for each series. These fits show that the dominant source of error in the Monte Carlo runs is associated with the uncertainty in the locations of the ring centers of opacity (*i.e.*, the random errors in Δa_{COO}). On the other hand, the substantial displacement of the best-fitting J_2 and J_4 that included only the AUTOMP satellites from our adopted solution accentuates the importance of including the effects of the minor satellites when computing the predicted precession rates of the rings.

7.3.2. Adopted gravity field solution and uncertainties

Our adopted solution for the Uranus gravity field is from Fit 15: $J_2 = (3509.291 \pm 0.412) \times 10^{-6}$, $J_4 = (-35.522 \pm 0.466) \times 10^{-6}$, and $\rho(J_2, J_4) = 0.9861$. These represent the best-fitting values of J_2 and J_4 from Fit 12, which used the entire set of ring observations, corrected for the estimated differences between COO and COR values, including the contribution to ring precession of both major and minor satellites, and assume $J_6 = 0.5 \times 10^{-6}$. The formal errors $\sigma(J_2)$ and $\sigma(J_4)$ and correlation $\rho(J_2, J_4)$ for Fit 12 account for random errors of the observations alone, whereas the Monte Carlo results summarized in Fit 15 account as well for the estimated uncertainties in Δa_{COO} , Δa , and the satellite contributions to the ring precession rates.

A striking characteristic of the results in Table 17 and evident in Fig. 33 is the small size of formal error ellipses in J_2 and J_4 from the individual fits, compared to the much larger differences in J_2 and J_4 that stem from a range of assumptions about the value of J_6 , the satellites included in the calculation of secular precession, the choice of COR or COO for ring semimajor axes, the absolute radius scale, and realistic uncertainties in these quantities. Some of these differences can be predicted on the basis of the observed strong correlations between J_2 , J_4 , and J_6 , as we show below. Nevertheless, the large size of the error ellipse of our final solution compared to the formal errors of the individual fits underscores the consequences of our limited knowledge of the internal radial structure of the rings that determines their dynamical semimajor axes, as well as uncertainties in the masses of the minor satellites, especially Cordelia and Ophelia, which primarily affect the ϵ ring’s predicted precession rate, a key constraint on the gravity field determination.

7.3.3. Correlations between J_2 , J_4 , and J_6

The strong correlations between J_2 , J_4 , and J_6 can be used to restrict the range of models for the interior structure and differential rotation of Uranus that are consistent with the ring occultation solution for the planet’s gravity field. In Appendix C, we evaluate these results numerically and provide a prescription to compute the difference in standard deviations between a model gravity field described by the first three gravity harmonic coefficients $\{J'_2, J'_4, J'_6\}$ and our adopted solution.

8. ANOMALOUS PRECESSION RATES

Our determination of the gravity field of Uranus relies on a model of the radial dependence of ring apsidal precession and nodal regression rates that includes the effects of the planet and the known satellites. From an examination of the post-fit residuals in apse rate for individual rings, we can set limits on possible unseen moonlets, such as those that have been proposed to account for quasi-periodic optical depth variations in the α and β ring *Voyager* RSS optical depth profiles (Chancia and Hedman 2016). Figure 32 shows small positive residuals for the apse rate of these two rings, and also for the γ ring. Here, we determine the range of moonlet masses and orbital radii that could account for these residuals, and set limits on the anomalous precession in the vicinity of the eccentric rings.

We estimated the detection limits for anomalous precession rates of the eccentric rings from a series of fits in which we solved for full set of geometric and orbital parameters as in our adopted solution, except that we let each eccentric and possibly inclined ring in turn have its apse and node rates fitted as free parameters but solved for J_2 and J_4 from the other rings. The differences between the fitted values and the apse rates computed from Fit 12 in Table 17 (accounting for Δa_{COO}) are listed in Table 18, which summarizes our measured values and upper limits for anomalous precession. These are plotted as open circles in the middle panel of Fig. 32.

Table 18. Limits on anomalous precession rates

Ring	$\Delta\dot{\omega}$ (10^{-5} ° d $^{-1}$)	Description
6	-9.07 ± 5.31	No detected anomalous precession
5	-1.04 ± 2.30	No detected anomalous precession
4	$+0.02 \pm 4.48$	No detected anomalous precession
α	27.66 ± 4.99	Consistent with Chancia and Hedman (2016) wake model
β	12.79 ± 8.74	Consistent with Chancia and Hedman (2016) wake model
γ	31.21 ± 43.84	$m = 3$ mode included in orbit model
γ	123.16 ± 36.54	$m = 3$ mode not included in orbit model
ϵ	–	Not determinable from orbit model

8.1. Rings 6, 5, and 4

The precession rates of rings 6, 5, and 4 all contributed to the determination of the gravity field, so it is not surprising that there are no detected anomalous precession rates for these rings, although a single outlier among them would perhaps have been detectable.

8.2. The α ring

Chancia and Hedman (2016) proposed that wakes observed in the *Voyager* RSS α ring radial profiles could be produced by a moonlet with orbital radius $a_s = 44825_{-12}^{+22}$ km (compared to the α ring COR semimajor axis $a = 44718.470 \pm 0.086$ km) and mass $M_{sI} = (3_{-2}^{+4}) \times 10^{14}$ kg (or $M_{sI}/M_{Ur} = (3.46_{-2.30}^{+4.61}) \times 10^{-12}$) from the ingress profile and $M_{sE} = (1.0_{-0.6}^{+18}) \times 10^{14}$ kg (or $M_{sE}/M_{Ur} = (1.15_{-2.65}^{+20.7}) \times 10^{-12}$) from the egress profile. In **Fig. 34**, the solid diagonal line indicates the satellite mass, as a function of the orbital distance exterior to the ring COR, that would be required to produce the estimated anomalous precession rate $\Delta\dot{\omega} = (27.66 \pm 4.99) \times 10^{-5} \text{ }^\circ \text{ d}^{-1}$ of the α ring, from Table 18.

The dotted lines bound the uncertainty. The dashed diagonal line (visible at upper right) gives the corresponding results for a moonlet interior to the ring. The relative locations of the rings exterior to the α ring are shown as vertical dashed lines, and the masses of representative satellites are plotted as horizontal dotted lines, along with an estimate for the ϵ ring mass ratio $M_\epsilon/M_{Ur} = 7.57 \times 10^{-11}$ (Nicholson et al. 2014b). Selected moonlet radii r are shown for an assumed average density $\rho = 1 \text{ g cm}^{-3}$. For example, a Cordelia-sized moon orbiting 500 km from the α ring could produce the observed anomalous precession rate.

For comparison, the Chancia and Hedman (2016) estimates of the hypothetical moonlet's mass and distance from the α ring (using the more reliable RSS ingress profile) are shown by the labeled dot, with error bars that overlap the range of masses inferred from the measured anomalous precession rate of the α ring. This provides supportive evidence for an unseen icy moonlet with a radius $\gtrsim 4 \text{ km} \simeq 100 \text{ km}$ exterior to the α ring.

8.3. The β ring

Similarly, Chancia and Hedman (2016) proposed that wakes observed in the β ring radial profiles could be produced by a moonlet with orbital radius $a_s = 45738_{-4}^{+8}$ km (compared to the β ring COR semimajor axis $a = 45661.051 \pm 0.087$ km) and mass $M_{sI} = (0.5_{-0.2}^{+0.3}) \times 10^{14}$ kg (or $M_{sI}/M_{Ur} = (0.58_{-0.23}^{+0.35}) \times 10^{-12}$) from the ingress RSS profile and $M_{sE} = (0.7_{-0.2}^{+0.4}) \times 10^{14}$ kg (or $M_{sE}/M_{Ur} = (0.81_{-0.23}^{+0.46}) \times 10^{-12}$) from the egress RSS profile. In **Fig. 35**, the solid diagonal line indicates the satellite mass, as a function of the orbital distance exterior to the ring COR, that would be required to produce the estimated anomalous precession rate $\Delta\dot{\omega} = (12.79 \pm 8.74) \times 10^{-5} \text{ }^\circ \text{ d}^{-1}$ of the β ring. The dotted lines bound the uncertainty. The dashed diagonal line (visible at upper right) gives the corresponding results for a moonlet orbiting interior to the ring. The relative locations of the rings exterior to the β ring are shown as vertical dashed lines.

For comparison, the Chancia and Hedman (2016) estimate of the hypothetical moonlet mass and distance from the β ring from the more reliable RSS ingress profile is shown by the labeled dot, with error bars that overlap the range of masses inferred from the estimated anomalous precession rate of the ring. As with the α ring, this provides supportive evidence for an unseen moonlet the produced the wake signature in the ring profile, in this case with a radius $\gtrsim 3 \text{ km} \sim 80 \text{ km}$ exterior to the β ring.

8.4. The γ ring

Finally, we examine the evidence for possible unseen moonlets in the vicinity of the γ ring. The putative $m = 3$ normal mode resulted in a small positive but uncertain anomalous precession rate $\Delta\dot{\omega} = (14.48 \pm 42.10) \times 10^{-5} \text{ }^\circ \text{ d}^{-1}$ (Table 5), consistent with zero. When the $m = 3$ mode is excluded from the fit, the anomalous precession has a substantially larger value: from Table 18, $\Delta\dot{\omega} = (123.16 \pm 36.54) \times 10^{-5} \text{ }^\circ \text{ d}^{-1}$, plotted as a filled square in **Fig. 32**. **Figure 36** shows the satellite masses required to account for both of these possibilities. The upper solid and dashed

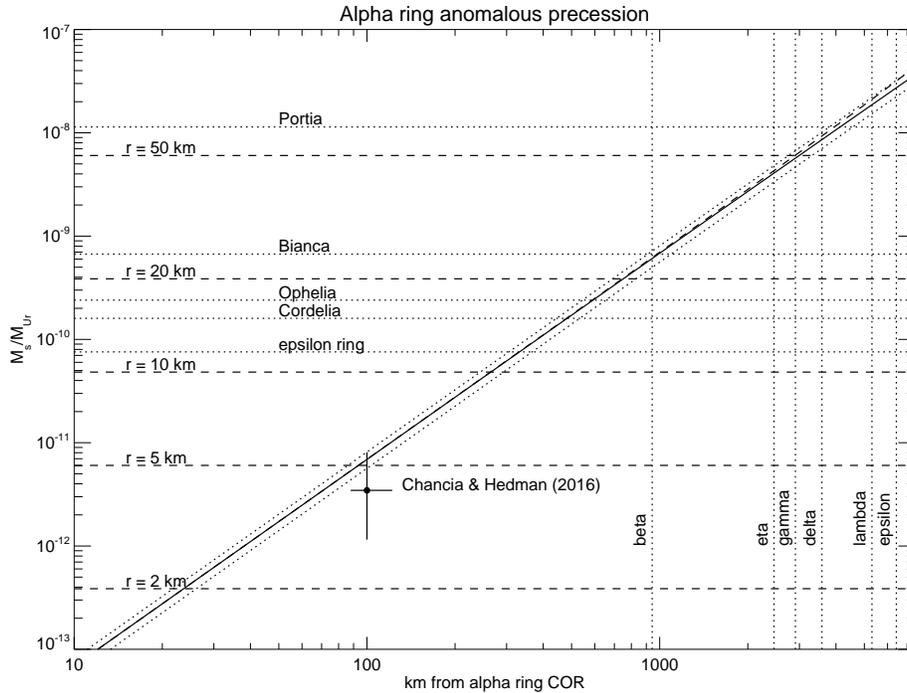


Figure 34. Satellite size and mass required to match the observed anomalous precession rate of the α ring, plotted as a function of orbital distance from the semimajor axis of the ring’s COR and shown as a solid diagonal line, bounded by dotted lines indicating its uncertainty. The dashed black line that deviates from the solid line at the upper right corresponds to satellite orbits interior to the α ring’s semimajor axis. Representative masses and radii of moonlets and the ϵ ring are shown, assuming $\rho = 1 \text{ g cm}^{-3}$. The locations of the rings exterior to the α ring are marked by vertical dotted lines. The black dot with error bars marks the hypothetical satellite mass and orbital radius proposed by [Chancia and Hedman \(2016\)](#) to account for wakes observed in the *Voyager* RSS α ring radial profiles. The predictions from the observed anomalous precession rate match within the error bars.

diagonal lines correspond to the fit that excluded the $m = 3$ mode, giving the inferred satellite mass as a function of distance exterior to or interior to the γ ring COR, respectively. When the $m = 3$ mode is included in the fit, the predicted satellite masses are smaller, with the nominal estimates based on the measured anomalous precession rate of the $m = 1$ mode being shown as the red solid and dashed lines, defined as before, with the upper limit shown as the red dotted line. (There is no corresponding lower limit, since $\sigma(\Delta\dot{\omega})$ exceeds its measured value.)

The amplitude and location of the putative $m = 3$ mode provide an independent constraint on the mass and location of a hypothetical satellite that forces the mode. The resonance location for the $m = 3$ mode is $\sim 1.101 \text{ km}$ exterior to the outer edge of the ring, and if the mode is forced by a first-order ILR with an unseen satellite, its mean motion would be $\Omega_P(\text{OER}) = n = 765.3977^\circ \text{ d}^{-1}$, with a corresponding semimajor axis $a = 62366.66 \text{ km}$, a few hundred km interior to the orbit of Desdemona. Based on the amplitude of the COR mode $A_3 = 0.577 \pm 0.073 \text{ km}$ and the distance from resonance $\Delta a_P = 2.706 \pm 0.048 \text{ km}$, the required satellite mass would be $m_{\text{sat}}/M_{\text{Ur}} = 12.5 \times 10^{-10}$, or about twice the mass of Cordelia (see Section 9). This is too large to have escaped previous detection in *Voyager* images and would probably produce a detectable perturbation in Cordelia’s orbit. Furthermore, it is too small to account for the $m = 1$ anomalous precession. On this basis, we reject the hypothesis that the $m = 3$ mode is forced by an external satellite. If instead the $m = 3$ mode is unforced or entirely absent, and we assume that the lower radius limit of detectable satellite is $\sim 10 \text{ km}$, the inferred $m = 1$ anomalous precession rate could be provided by a hidden moonlet orbiting within 150–250 km on either side of the γ ring, assuming $\rho = 1 \text{ g cm}^{-3}$.

8.5. The ϵ ring

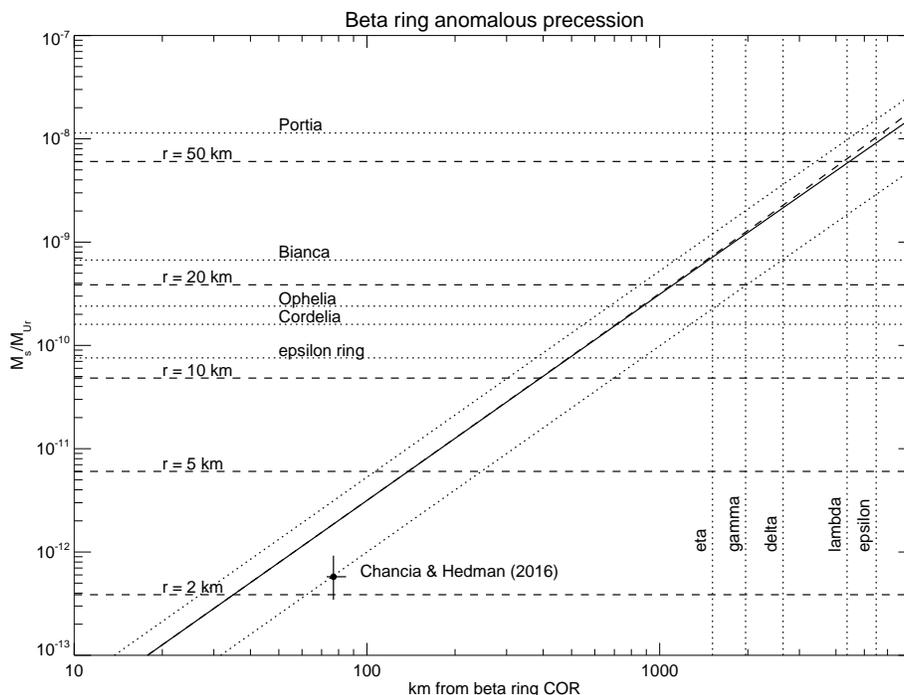


Figure 35. Satellite size and mass required to match the observed anomalous precession rate of the β ring, plotted as a function of orbital distance from the semimajor axis of the the ring’s COR and shown as a solid diagonal line, bounded by dotted lines indicating its uncertainty. The dashed black line that deviates from the solid line at the upper right corresponds to satellite orbits interior to the β ring’s semimajor axis. Representative masses and radii of moonlets and the ϵ ring are shown, assuming $\rho = 1 \text{ g cm}^{-3}$. The locations of the rings exterior to the β ring are marked by vertical dotted lines. The black dot with error bars marks the hypothetical satellite mass and orbital radius proposed by [Chancia and Hedman \(2016\)](#) to account for wakes observed in the *Voyager* RSS β ring radial profiles. The predictions from the observed anomalous precession rate match within the error bars.

The ϵ ring precession rate was the main tie point for the inferred gravity field, and so no measurable anomalous precession was detectable.

9. MOONLET ORBITS, MASSES, AND DENSITIES

Five of the detected normal modes in the Uranian rings appear to be forced by nearby satellite resonances: the η ring 3:2 ILR with Cressida, the γ ring 6:5 ILR and the ϵ OER 14:13 ILR with Ophelia, and the δ ring 23:22 ILR and the ϵ IER 24:25 OLR with Cordelia. In this section, we examine the satellite-driven modes detected at ring midlines or edges, compare their pattern speeds and phases with the mean motions and orbital longitudes at epoch of the three satellites, and estimate the masses and densities of the satellites from the amplitudes of the modes.

9.1. Satellite-driven normal modes

First-order Lindblad resonances of wavenumber m located near narrow rings produce radial forces that excite normal modes: m -lobed distortions in the ring particle orbits that rotate with a pattern speed matching the satellite’s mean motion. In the idealized case where ring material can be viewed as independent test particles, the periapse of the distortion is aligned with the mean longitude of the satellite for orbits interior to the resonant radius, with the apoapse being so aligned for particles orbiting exterior to the resonance ([Murray and Dermott 1999](#)). Examples in the Saturn system include the Titan 1:0 ILR in the C ring, where the orientations of a host eccentric features on either side of the resonance match these expectations (see Fig. 19 [Nicholson et al. \(2014b\)](#)), and the Mimas 2:1 ILR near the outer edge of the B ring, where eccentric features in the Cassini Division exterior to the resonance all have their apoapses closely aligned with Mimas (see Fig. 25 [French et al. \(2016b\)](#)).

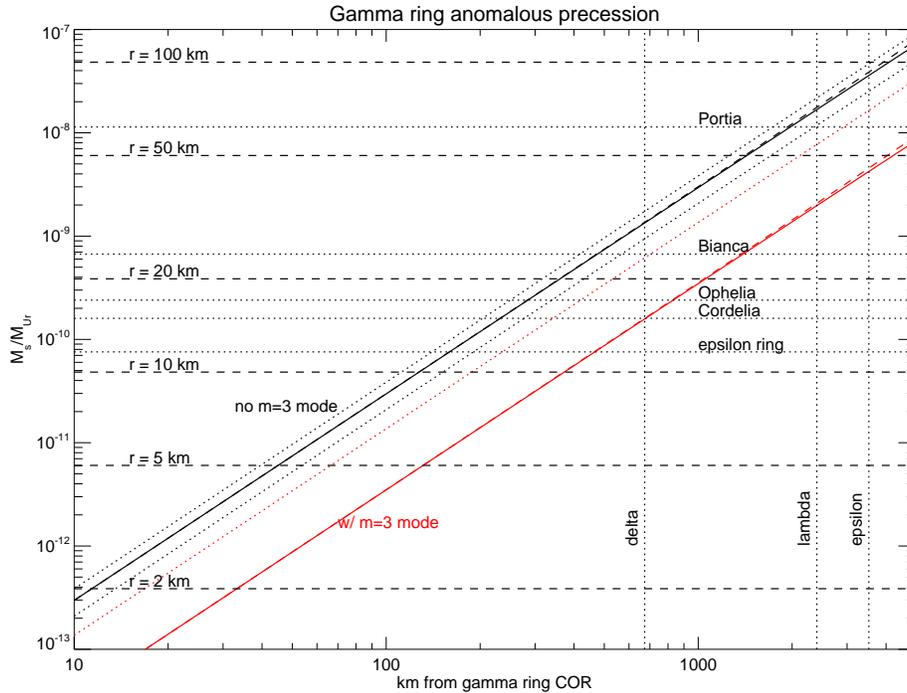


Figure 36. Satellite size and mass required to match the observed anomalous precession rate of the γ ring, plotted as a function of orbital distance from the ring’s COR. The orbit fit that excluded the $m = 3$ mode had a very high anomalous precession rate, resulting in corresponding large satellite masses, as shown by the solid black diagonal line, bounded by dotted lines denoting its uncertainty. For the alternative case that included the $m = 3$ mode, the anomalous precession rate was lower, resulting in smaller predicted satellites, as indicated by the solid red diagonal line, bounded by its upper uncertainty as a red dotted line. The dashed black and red lines that deviate from the solid lines at the upper right correspond to satellite orbits interior to the γ ring’s semimajor axis. Representative masses and radii of moonlets and the ϵ ring are shown, assuming $\rho = 1 \text{ g cm}^{-3}$. The locations of the rings exterior to the γ ring are marked by vertical dotted lines.

The situation is more complicated for an eccentric narrow ring affected by nearby resonances when the ring’s self-gravity is taken into account (see Longaretti (2018) for an extensive review). In this case, streamline models show that the torque balance at the ring edges can result in shepherding, which serves to account for both the sharp edges of a narrow ring and the absence of differential precession across the ring. As applied to the ϵ ring, this model predicts that the outer edge is confined by the Ophelia 14:13 ILR and the inner edge is confined by the Cordelia 24:25 OLR, each producing an m -lobed edge wave. In the absence of dissipation, the forced mode (periapse/apoapse) is predicted to be aligned with the satellite mean longitude for an (ILR/OLR), respectively, and when dissipation is present, the relevant apse (lags/leads) the satellite mean longitude in angle for an (ILR/OLR), respectively. (In Appendix D, we justify these statements on dynamical grounds.)

Finally, both theoretical and numerical models show that under special circumstances a single shepherd satellite can confine a narrow ring (Goldreich et al. 1995; Hänninen and Salo 1994, 1995; Lewis et al. 2011), but the applicability of these results to the Uranian rings has not been explored in detail.

The characteristics of the forced normal modes identified in the Uranian rings are summarized in **Table 19**. For each mode, we include from Tables 5 and 6 the fitted semimajor axis a of the feature, the wavenumber m , its amplitude A_m , the pattern speed Ω_m , and the distance of the predicted resonance radius from the observed ring feature $\Delta a_P = a_{\text{res}} - a$. Also listed are the mean satellite longitude at epoch λ_{sat} from the `ura111` ephemeris and the longitude difference $\Delta\lambda = \delta'_m - \lambda_{\text{sat}}$, where δ'_m is defined modulo $360^\circ/m$ as the inertial longitude at epoch relative to nearest apse, as identified in the final column.¹² Error bars reflect the uncertainties in δ'_m and do not include the

¹² For an m -lobed normal mode, the phase offset of the mode apse and the satellite longitude is given by $m\Delta\lambda$.

very small uncertainties in the satellite longitude at epoch (see Table 4, [Jacobson \(1998\)](#)). Following [Chancia et al. \(2017\)](#), we estimate the satellite mass $M_{\text{sat}}/M_{\text{Ur}}$ from the mode amplitude A_m in the vicinity of a Lindblad resonance and the distance from resonance $|\Delta a_P|$ using Eq. (10.22) from [Murray and Dermott \(1999\)](#):

$$A_m = \frac{2\alpha a^2 (M_{\text{sat}}/M_{\text{Ur}}) |f_d|}{3(m-1) |\Delta a_P|}, \quad (40)$$

where $\alpha = a/a_s$ (the ratio of the ring and satellite semimajor axes) and f_d is the Laplace factor, given by [Murray and Dermott \(1999\)](#). (As noted by [Chancia et al. \(2017\)](#), $\frac{2\alpha|f_d|}{m-1}$ varies between 1.5 and 1.6, depending on m .) This relationship is based on test-particle approximation that is strictly applicable only in the evanescent region of the mode and at least 1/4 wavelength from the resonance, and so it is probably best thought of as an approximate scaling estimate, rather than as a dynamically rigorous result for all of the forced modes considered here.

Table 19. Satellite-driven normal modes

Satellite	Ring	a km	Δa_P km	m	A_m km	$m_{\text{sat}}/M_{\text{Ur}}$ $\times 10^{-10}$	Ω_P $^{\circ} \text{d}^{-1}$	δ'_m ^(a) deg	λ_{sat} ^(b) deg	$\Delta\lambda$ ^(c) deg	apse
Cressida	η (COR)	47176.009	-4.595	3	0.600 ± 0.069	21.18 ± 2.44	776.584048 ± 0.001164	15.90 ± 2.36	17.44	-1.54 ± 2.36	apoapse
Ophelia	γ (IER)	47624.606	0.754	6	0.590 ± 0.110		956.418079 ± 0.000877	303.40 ± 2.21	298.08	5.33 ± 2.21	apoapse
	γ (COR)	47626.170	-0.861	6	0.637 ± 0.063	4.23 ± 0.42	956.419622 ± 0.000474	302.52 ± 1.17	298.08	4.44 ± 1.17	apoapse
Cordelia	γ (OER)	47627.865	-2.552	6	0.892 ± 0.117		956.419529 ± 0.000560	298.03 ± 1.36	298.08	-0.05 ± 1.36	apoapse
	ϵ (COR)	51149.279	28.425	14	0.383 ± 0.071		956.418015 ± 0.000269	296.96 ± 0.63	298.08	-1.12 ± 0.63	periapse
	ϵ (OER)	51178.588	-0.887	14	0.590 ± 0.130	3.67 ± 0.81	956.418119 ± 0.000298	297.76 ± 0.70	298.08	-0.32 ± 0.70	periapse
	δ (COR)	48300.227	2.173	23	0.339 ± 0.063	5.58 ± 1.09	1074.523021 ± 0.000189	69.45 ± 0.47	70.00	-0.55 ± 0.47	periapse
	ϵ (IER)	51120.014	1.082	-24	1.011 ± 0.107	7.83 ± 0.83	1074.522889 ± 0.000099	70.42 ± 0.26	70.00	0.41 ± 0.26	apoapse
	ϵ (COR)	51149.279	-28.177	-24	0.443 ± 0.061		1074.522703 ± 0.000142	70.33 ± 0.35	70.00	0.33 ± 0.35	apoapse

^a The epoch is 1986 Jan 19 12:00 (TDB). δ'_m is the observed longitude of the mode's periapse or apoapse, as specified in the final column. It is ambiguous by additive multiples of $360^{\circ}/m$, adjusted to minimize the magnitude of $\Delta\lambda$.

^b Mean longitude of the satellite at the epoch, from the `ura111` ephemeris.

^c $\Delta\lambda = \delta'_m - \lambda_{\text{sat}}$. Error bars reflect the uncertainties in δ'_m and do not include the uncertainties in the satellite ephemerides (see Table 4, [Jacobson \(1998\)](#)).

All of the normal modes in Table 19 have pattern speeds that are very close to those of the satellites associated in the resonances. **Table 20** lists the weighted average pattern speeds of all identified modes associated with Cressida, Ophelia, and Cordelia, as well as satellite mean motions from published and unpublished sources.

9.1.1. Cressida

The $m = 3$ ILR forced by Cressida in the η ring was first identified by [Chancia et al. \(2017\)](#), based on a ring orbit fit to a subset of the data used in our current analysis. The Cressida resonance lies $\Delta a_P = -4.595$ km interior to the ring COR. We find $A_m = 0.600 \pm 0.069$ km, $\Omega_P = 776.584048 \pm 0.001164^{\circ} \text{d}^{-1}$, $\delta'_m = 15.90 \pm 2.36^{\circ}$, and $\Delta\lambda = -1.54 \pm 2.36^{\circ}$ from 60 η ring COR measurements, comparable to but with smaller error bars than the [Chancia et al. \(2017\)](#) values of $A_m = 0.667 \pm 0.113$ km, $\Omega_P = 776.58208 \pm 0.00169^{\circ} \text{d}^{-1}$, and $\Delta\lambda = -2.72 \pm 6.12^{\circ}$ from 49 measurements.

Table 20. Satellite mean motions

Satellite	Source	Ω_P ($^{\circ} \text{d}^{-1}$)
Cressida	This work	776.584048 ± 0.001164
	Jacobson (1998)	776.582414 ± 0.000022
	Showalter and Lissauer (2006)	776.582789 ± 0.000059
	Robert French (pers. comm.)	$776.5826393 \pm 0.0000053$
Ophelia	This work	956.418404 ± 0.000171
	Jacobson (1998)	956.42833 ± 0.00908
	Robert French (pers. comm.)	956.418293 ± 0.000037
Cordelia	This work	1074.522858 ± 0.000075
	Jacobson (1998)	1074.51832 ± 0.00187

The pattern speed of the 3:2 ILR in the η ring is reasonably consistent with previous values for Cressida’s mean motion, differing by 1.4σ from the [Jacobson \(1998\)](#) value, by 1.1σ from the [Showalter and Lissauer \(2006\)](#) value, and by 1.2σ from the unpublished value (Robert French, pers. comm) based on an analysis of *HST* images.

These results are consistent with the test particle interpretation of the response of the η ring to the Cressida resonance, which is too distant to produce single-sided shepherding. Since the resonance is interior to the ringlet, the normal mode apoapse is predicted to be aligned with the satellite, as observed, with no statistically significant lead or lag in longitude.

9.1.2. *Cordelia and Ophelia*

The $m = 6$ ILR Ophelia resonance has long been recognized as being located near to the γ ring ([Porco and Goldreich 1987](#)), and as described in Section 4.1 and tabulated in Table 5, we detected the $m = 6$ mode at the ring midline and both edges, with the measured amplitude A_m increasing systematically from 0.591 ± 0.110 km at the IER, to 0.637 ± 0.063 km at the COR, and finally to 0.891 ± 0.117 km at the OER. The resonance radius lies $\Delta a_P = -2.552$ km interior to the ring OER, where the mode amplitude is greatest. The mode apoapse leads Ophelia by $\Delta\lambda = +5.33 \pm 2.21^\circ$ at the ring’s IER, by $+4.44 \pm 1.17^\circ$ at the ring’s COR, and at the OER, where the $m = 6$ mode amplitude the largest, the apoapse is nearly aligned with Ophelia: $\Delta\lambda = -0.05 \pm 1.36^\circ$.

The dynamics of the γ ring are complex, with the simultaneous presence of five free normal modes and the Ophelia 6:5 ILR forced mode that is located within the ring itself (Fig. 28). The near-alignment of the $m = 6$ mode apoapse with Ophelia is as expected if the ring material responds as isolated test particles to the satellite’s forcing, but this neglects the possibly significant role of self-gravity for this narrow ringlet of high average optical depth. The apparently statistically-significant phase offsets of the mode at the ring’s inner edge and midline have no obvious explanation.

As shown previously in Sections 4.1.4 and 4.1.5, normal mode scans revealed the presence of the $m = 14$ ILR with Ophelia in the ϵ OER and COR, and the $m = -24$ OLR with Cordelia in the ϵ IER and COR. The final values for the mode amplitudes, phases, and pattern speeds when included in our adopted orbit fit are given in Table 5 and in more detail in Table 19. The periapse of the $m = 14$ OER mode lags behind Ophelia by $\Delta\lambda = -0.55 \pm 0.47^\circ$, as expected for a normal mode at the outer edge of the ring, and the apoapse of the $m = -24$ IER mode leads Cordelia by $\Delta\lambda = 0.41 \pm 0.26^\circ$, again in keeping with the dynamical arguments presented in Appendix D for a forced normal mode at the inner edge of a ring in the presence of dissipation.

The $m = 23$ ILR Cordelia resonance was first associated with the δ ring by [Porco and Goldreich \(1987\)](#). We detected the signature of this resonance in our normal mode scans of the δ ring COR, although the fitted mode amplitude is only $A_{23} = 0.339 \pm 0.063$ km, too small to be detectable in either of the noisier ring edge (IER/OER) orbit fit residuals. The resonance is located slightly outside of the ring COR ($\Delta a_P = 2.173$ km). The test-particle model predicts that the mode periapse should be aligned with Cordelia, as observed. There is a marginally-detectable lag in the orientation of periapse behind Cordelia at the $1\text{-}\sigma$ level: $\Delta\lambda = -0.55 \pm 0.54^\circ$, perhaps due to dissipation in the ring.

Comparisons of the pattern speeds and orbital longitudes of the normal modes and the `ura115` ephemeris values for Ophelia and Cordelia are shown in **Fig. 37**. The top left panel shows the fitted pattern speeds and their error bars for the γ ring IER/COR/OER $m = 6$ mode measurements and the ϵ ring COR and OER $m = 14$ results, compared to the [Jacobson \(1998\)](#) value. The weighted mean value of our measurements is shown by the solid green line, bracketed by the estimated uncertainty. The dashed blue lines show the rather large $1\text{-}\sigma$ uncertainty in Ophelia’s mean motion from [Jacobson \(1998\)](#). All of the measured pattern speeds are systematically below the `ura115` ephemeris value by $\simeq 0.01^\circ \text{ d}^{-1}$. The weighted mean pattern speed for the normal modes of $\Omega_P = 956.418404 \pm 0.000171^\circ \text{ d}^{-1}$ is just $\sim 0.65\sigma$ from the unpublished value of $\Omega_P = 956.418293 \pm 0.000037^\circ \text{ d}^{-1}$ shown in red, derived from *HST* observations (Robert French, personal communication). The lower left panel shows the longitude differences $\Delta\lambda$ between the measured phases of the detected modes and the mean longitude of Ophelia at the epoch. The γ ring $m = 6$ normal mode apoapse leads the satellite for the IER and COR, but aligns with the satellite at the OER. On the other hand, the periapse of the ϵ ring $m = 14$ ILR at the ring’s outer edge lags behind Ophelia, as expected in the presence of dissipation.

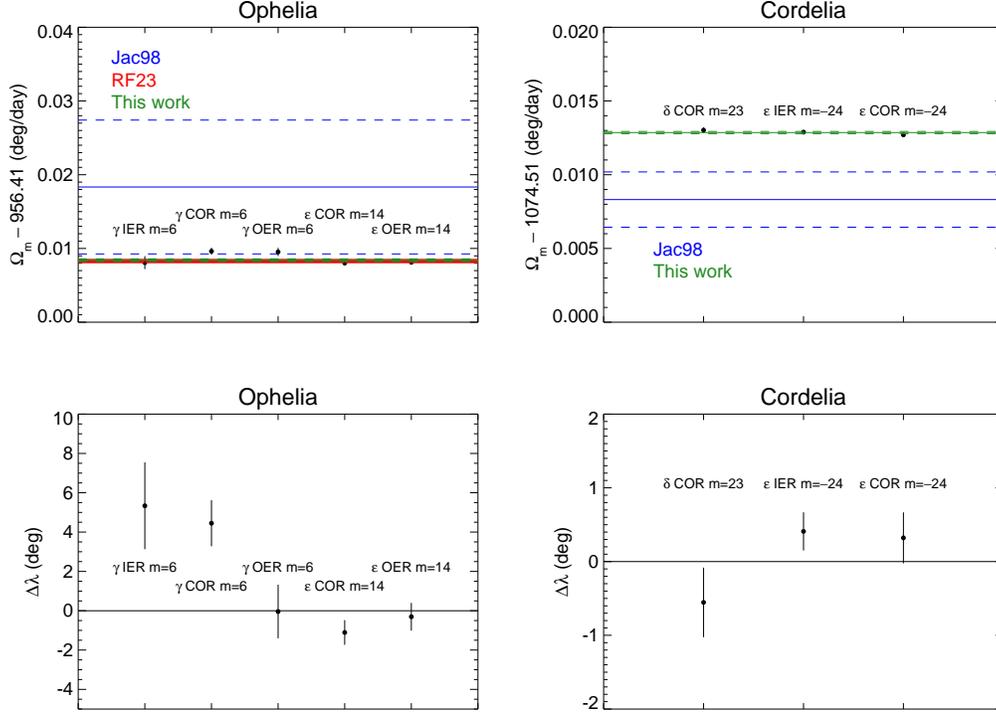


Figure 37. Pattern speed and phase comparison for the observed normal modes forced by Ophelia and Cordelia. The upper left panel shows the observed pattern speeds Ω_m for each of five labeled modes associated with Ophelia, plotted as filled circles with error bars. The solid horizontal lines mark the mean motions of Ophelia (bounded by their uncertainties, shown dashed) reported by [Jacobson \(1998\)](#) (shown in blue and labeled Jac98) and Robert French (pers. comm.) shown in red and labeled RF23, compared to the weighted average of the mode pattern speeds from this work, shown in green. The upper right panel compares the [Jacobson \(1998\)](#) and our results for Cordelia. The bottom panels show the longitude differences $\Delta\lambda$ between the fitted periapse or apoapse longitudes and the satellite mean longitudes at epoch from the `ura115` satellite ephemeris (from Table 19).

The right column of Fig. 37 shows the comparable results for Cordelia. In this case, the best fitting pattern speeds for the δ ring COR $m = 23$ mode and the ϵ ring $m = -24$ mode values for the IER and COR are in excellent mutual agreement, although they lie above the [Jacobson \(1998\)](#) values, which have much larger error bars. In the lower right panel, the longitude of the apoapse of the δ ring $m = 23$ normal mode lags slightly behind Cordelia, while the ϵ ring’s inner edge mode associated with the Cordelia 24:25 OLR leads the satellite, as expected in the presence of dissipation.

9.2. Moonlet masses and densities

The densities of Cressida, Ophelia, and Cordelia can be estimated from the ratio of their masses given in Table 19 to their volumes, calculated from the prolate satellite dimensions from Table IV of [Karkoschka \(2001a\)](#). These can be compared to the Roche critical density ρ_{Roche}

$$\rho_{\text{Roche}} = \frac{4\pi\rho_p}{\gamma(a/R_p)^3} = \frac{3M_p}{\gamma a^3}, \quad (41)$$

where ρ_p , R_p and M_p are the planet’s density, radius, and mass, a is the distance from the planet, and γ is a dimensionless parameter associated with the mass distribution and shape of the satellite ([Tiscareno et al. 2013](#)). An object without material strength and density less than ρ_{Roche} would be pulled apart, and thus the critical density curve represents a tidally governed lower limit to density of gravitationally bound aggregates. Following [Porco et al. \(2007\)](#) and [Tiscareno et al. \(2013\)](#), we assume $\gamma = 1.6$, corresponding to the case when the satellite’s mass is assumed to be uniform in density and distributed into the shape of its Roche lobe.

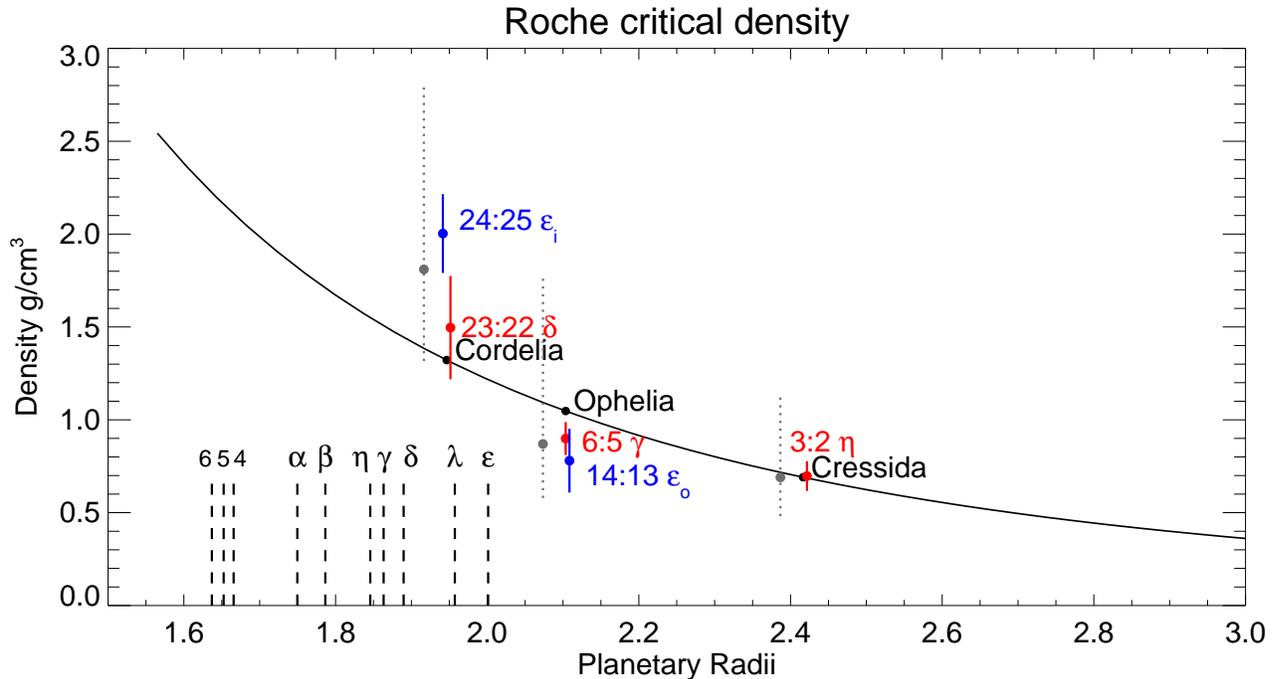


Figure 38. Densities of Cordelia, Ophelia, and Cressida computed from fitted normal mode amplitudes A_m , distances from resonance Δa_P , and satellite dimensions from Karkoschka (2001b). Here, we use the COR amplitudes for the η , δ and γ ring resonances, since the ring midline fits have smaller formal errors than the edge amplitudes that are based on noisier data. The error bars on the individually marked resonances reflect only the contribution of the fractional errors of A_m to the overall error budget, which is dominated by the satellite volume uncertainties. The gray dots are the weighted mean densities for each satellite and the dotted error bars correspond to the combined uncertainties in the mode amplitudes and the satellite volumes (Table 3). The Roche critical density is plotted as a solid line for shape parameter $\gamma = 1.6$ and $R_p = 25559$ km, with filled circles at the orbital radii of the satellites. Dashed vertical lines are labeled with the locations of the ten narrow rings.

The computed satellite densities are plotted as a function of orbital radius in **Fig. 38**. Cordelia and Ophelia each have two separate resonances that yield mutually-consistent densities with overlapping error bars computed from the uncertainties in the fitted mode amplitudes alone, although the realistic uncertainty in their average value (plotted in gray) is dominated by the contribution of the much larger satellite volume uncertainty. Even taking these larger error estimates into account, the calculated satellite densities appear to decrease with orbital radius by about a factor of two from innermost Cordelia to outermost Cressida. For comparison, the Roche critical density is plotted as a solid line, assuming that the shape parameter $\gamma = 1.6$. It increases inward quite rapidly, from 0.5 g cm^{-3} at $2.6 R_p$ to over 2.0 g cm^{-3} at ring 6, supporting the view that the Uranian rings are more rocky and less porous than Saturn’s rings (Tiscareno et al. 2013). For smaller values of γ , the critical density curve would lie above the measured densities and require that the moonlets have material strength. The observed densities follow the overall trend of the Roche critical density curve for $\gamma = 1.6$, which may reflect the formation process and possible orbital migration of these small moons.

10. DISCUSSION

10.1. Ring orbits, width variations, and masses

The most secure results from nearly three decades of occultation observations of the narrow rings of Uranus are their orbital shapes and width variations. Although the number of individual occultation observations for a given ring is at most just 89 (well below the ~ 150 – 260 for Saturn’s rings from *Cassini* occultation observations), the long time-baseline and remarkable geometric accuracy of the orbit reconstructions enables the detection of normal modes and width variations of the rings on a scale of ~ 0.2 km for the Uranian rings. The internal structure of the narrowest of the rings is largely unresolved in Earth-based observations, preventing the accurate reconstruction of streamline

models that could provide detailed information about self-gravity wakes, ring confinement mechanisms, and signatures of unseen satellites.

Standard self-gravity (SSG) models predict unrealistically small ring masses and surface densities and fail to match the actual variations in $q_e(r)$ observed in the rings, but they successfully predict the slopes of the observed width-radius relations for nearly all of the inner and outer Lindblad resonances detected in the rings. Collisional self-gravity models (CSG) predict much larger ringlet masses and surface densities more consistent with expectations based on particle size estimates, but they sequester the bulk of the mass in narrow regions near the ring edges, predicting U-shaped radial optical depth profiles that are a poor match to high-resolution *Voyager* occultation observations. More work is needed to ascertain whether the differences between the various predicted profiles and the observed profiles can be explained as the result of variations in the effective opacity of the ring material across each ring, or if they instead require a more complex dynamical model that produces a more uniform optical depth profile. Here, it might prove fruitful to compare the Uranus results with surface densities of Saturn’s rings in regions of comparable optical depth.

The accurate determination of the orbits and width-radius relations for the detected normal modes provides strong evidence for the overall balance between differential precession due to planetary oblateness and to self-gravity in preserving the apse alignment of the inner and outer edges of the eccentric ringlets. Only a subset of the Uranus rings have excited normal modes, but the γ ring’s five free modes puts it in the class of several of Saturn’s rings and ring edges that have as many or more normal modes. The excitation mechanism behind the observed modes is poorly understood, although it seems likely that non-linear coupling between modes might be responsible for the simultaneous presence of many modes, as seems to be the case for the complex shape of the outer edge of the B ring (French et al. 2023b).

While we found no statistically significant evidence for normal modes driven by internal planetary oscillations, it is important to note that the patterns generated by satellite resonances on the ϵ , δ and γ rings are relatively subtle, and finding resonances with planetary normal modes is more challenging because their pattern speeds cannot be accurately predicted in advance. This lack of detections therefore does not rule out the possibility that planetary normal modes are responsible for confining some of these rings. Still, these data, combined with more detailed analyses of the internal structures and longitudinal brightness variations within each of these rings, should help constrain the properties of the planet’s internal normal modes.

10.2. Ring-moonlet connections

Among the host of narrow rings in the solar system, only the ϵ ring is securely established as being confined by shepherd satellites, with the inner satellite Cordelia having a 24:25 OLR with the ring’s inner edge and the outer satellite Ophelia having a 14:13 ILR with the outer edge (Porco and Goldreich 1987). The amplitudes, pattern speeds, and phases of the edge waves match dynamical expectations and provide estimates of the masses of the confining satellites. The resonance radii of both edge modes are located within the ring, ~ 1 km from the corresponding ring edge. In the future, it will be interesting to compare these values with numerical simulations.

In addition to their roles as shepherd satellites for the ϵ ring, Cordelia and Ophelia each are the source of an additional forced normal mode in the rings: the 23:22 ILR of Cordelia with the δ ring and the 6:5 ILR of Ophelia with the γ ring. Cressida’s 3:2 ILR with the η ring provides a third example. The orientations of the excited normal modes in all three cases match a simple test-particle interpretation of the ring response to the satellite forcing (although the complex dynamics of the γ ring remain to be investigated in detail). An example of this mechanism in the Saturn system is provided by the Barnard Gap outer edge, which is perturbed by a Prometheus 5:4 ILR. Here, the apoapse of the mode is aligned with the satellite, as expected from the test-particle model (French et al. 2016b).

The internal structure of several narrow ringlets has been interpreted as evidence for satellite wakes generated by unseen moonlets near the δ ring (Horn et al. 1988) and the α and β rings (Chancia and Hedman 2016). Although our study offers no additional supporting evidence for a δ ring moonlet, our measurements of anomalous precession rates in both the α and β rings are consistent with the mass estimates for the proposed unseen moonlets near α and β rings, making them just below the level of detectability in *Voyager* or *HST* images. Direct detections of these moons may

have to await a future mission to the Uranus system, but these small moons could produce localized disturbances in nearby rings that could be detectable in *HST* or *JWST* images.

A provocative result of our study is the striking trend of moonlet densities with orbital distance from Uranus. Taken at face value, the densities of Cordelia, Ophelia, and Cressida follow the systematic trend of the Roche critical density for $\gamma = 1.6$, rising from 0.71 g cm^{-3} for outermost Cressida to double that value for innermost Cordelia. This finding is consistent with these moons having relatively little internal strength, which is compatible with the overall architecture of the Uranian ring-moon system (Tiscareno et al. 2013). This strikes an interesting contrast with the Neptune system, whose innermost moons must have sufficient internal strength to survive at their current locations (Tiscareno et al. 2013; Brozović et al. 2020)

Cordelia’s high density is particularly interesting because it is comparable to the densities of the much larger moons Ariel (1.54 g cm^{-3}), Umbriel (1.52 g cm^{-3}), Titania (1.65 g cm^{-3}) and Oberon (1.67 g cm^{-3}), and is actually larger than the density of Miranda (1.18 g cm^{-3}) (Thomas 1988; Jacobson 2014). This exceptionally high density likely has implications for the origins and evolution of these small moons. For example, according to standard tidal theory, Cordelia should be migrating inwards, so perhaps Cordelia represents the dense core of a larger moon whose outer layers have been stripped away by tidal forces. In this scenario, the ϵ ring would be composed of the last bits of material lost from Cordelia’s surface.

10.3. Uranus gravity field, internal structure, and winds

Accurate measurements of the gravity fields of giant planets can provide powerful constraints on their internal structure and the depth and nature of their wind profiles, as has been shown recently for Saturn and Jupiter from *Cassini* and *Juno* measurements of high-order gravitational moments (Iess et al. 2018, 2019; Dietrich et al. 2021; Kulowski et al. 2021; Militzer et al. 2022; Galanti et al. 2022). Uranus has very strong winds at the cloud level, with features at $\pm 60^\circ$ latitude moving around the planet over 200 m s^{-1} faster than the those near the equator (Hammel et al. 2001, 2005; Sromovsky and Fry 2005). If these winds penetrate far enough into Uranus’ interior, they could significantly influence the planet’s gravity field. Kaspi et al. (2013) concluded that the difference between the observed value of J_4 and the predicted value based on relatively simple interior models was sufficient to constrain the dynamics to the outermost 0.15% of the total mass of Uranus, corresponding to a relatively thin weather layer no more than about 1,000 kilometers deep. More recently, Movshovitz and Fortney (2022) showed that the moment of inertia (MoI) is tightly correlated with the gravity field beyond J_2 , and that to improve interior models and the MoI determination, the planet’s rotation period must be known to comparable precision. Neuenschwander and Helled (2022) demonstrated that knowledge of J_6 to 10% accuracy is required to constrain wind depths on Uranus: relatively high values of $J_6 = (59.9\text{--}69.04) \times 10^{-8}$ can only be explained by the existence of deep winds with a penetration depth of more than 250 km, whereas lower values $J_6 = (46.12\text{--}53.76) \times 10^{-8}$ do not allow for deep winds with a penetration depth as large as 1100 km. Significantly, they also demonstrated that more accurate values of J_2 and J_4 can further constrain the density distribution and narrow the range of predicted solutions in J_6 , J_8 , and MoI of Uranus and Neptune. Finally, Soyuer et al. (2023) conclude from model studies that the scale height of the zonal winds on Uranus is below $\sim 0.03R_U$ (770 km), somewhat shallower than found by Kaspi et al. (2013).

Nearly all of these modeling efforts for the interior structure and dynamics of Uranus have made use of the Jacobson (2014) values for J_2 and J_4 listed under Fits 2 and 3 in Table 17, but they have not yet exploited the strong degree of correlation between the measured values of J_2 and J_4 as an additional constraint. Although we are unable to set useful limits on J_6 alone, as we have shown in Table 17 and Fig. 33, our adopted gravity field solution based on a more complete set of ring observations provides tighter limits not only on J_2 and J_4 , but also on allowed combinations of values of J_2 , J_4 , and J_6 , after accounting for systematic uncertainties in the center of opacity of the rings, the absolute radius scale, and the masses of the major and minor satellites. The prescription in Appendix C can be used to restrict the range of density distributions and wind models for Uranus that are consistent with the ring occultation results, although significant advances in our understanding of the planet’s internal structure will probably require high-precision gravity measurements possible only from an orbiting spacecraft (Movshovitz and Fortney 2022).

10.4. *Open questions and future prospects*

Decades after their discovery, the Uranian rings continue to raise vexing dynamical puzzles. What confines the narrow rings? How can they maintain their eccentricities and inclinations in the presence of differential apsidal and nodal precession rates? What are their connections with the planet’s host of small moons? How recently were they formed, and what is the time scale for significant evolution of ring systems? The findings presented in this paper demonstrate the richness and complexity of the Uranian ring system, and its potential to illuminate other aspects of the Uranus system. Already, these rings have provided constraints of the gravity field of Uranus itself, estimates the mass densities of several known satellites, and evidence for a number of still-unseen moons. Future observations by earth-based telescopes or missions to the Uranus system could therefore provide key insights into multiple aspects of Ice Giant Systems (National Academies of Sciences, Engineering, and Medicine 2022).

On the one hand, detailed studies of the structure and dynamics of the Uranian rings will provide additional insights into the interiors of Ice Giants. Continued monitoring of the rings’ orbital evolution will yield increasingly tight constraints on the higher-order components of the planet’s gravitational field. At the same time, if any structures in the rings can be attributed to resonances with oscillations or asymmetries in the planetary normal modes (A’Hearn et al. 2022), those structures will provide novel information about the internal structures of Ice Giants, which are still largely unconstrained (Helled 2022).

Meanwhile, further studies of these rings should clarify whether small moons do in fact exist near the rings. The sizes, locations and densities of such moons will constrain the conditions under which solid material is more likely to accrete or fragment, which is relevant to not only the Uranian rings and moons, but also the formation of moons and planets more generally.

11. CONCLUSIONS

Our main results are summarized below:

- From an analysis of 31 Earth-based stellar occultations and three *Voyager 2* occultations spanning 1977–2006 (Paper 1), we have determined the keplerian orbital elements of the centerlines (COR) of the nine main Uranian rings to high accuracy, with typical RMS residuals of 0.2 – 0.4 km and $1\text{-}\sigma$ formal errors in a , ae , and $a \sin i$ of order 0.1 km, registered on an absolute radius scale accurate to 0.2 km at the $2\text{-}\sigma$ level. The λ ring shows more substantial scatter, with limited secure detections.
- We characterized a host of free and forced normal modes in several of the ring centerlines and inner and outer edges (IER/OER). In addition to the previously-known free modes $m = 0$ in the γ ring and $m = 2$ in the δ ring, we have identified two additional OLR modes ($m = -1$ and -2) and a possible $m = 3$ mode in the γ ring. No normal modes were detected for rings 6, 5, 4, α , or β .
- The origin of the γ ring’s putative $m = 3$ mode is mysterious. Its pattern speed is much slower than oscillation frequencies expected from internal oscillations of the planet, and it is unlikely to be due to an unseen satellite, whose predicted size would be too large to have avoided prior detection. If it is an unforced mode, it is unusual in having its resonance radius more than 1 km exterior to the ring’s outer edge. If the mode is omitted from the orbit solution, the γ ring has a very large anomalous apsidal precession rate of unknown origin.
- Five separate normal modes are forced by small moonlets: the 3:2 inner Lindblad resonance (ILR) of Cressida with the η ring, the 6:5 ILR of Ophelia with the γ ring, the 23:22 ILR of Cordelia with the δ ring, the 14:13 ILR of Ophelia with the outer edge (OER) of the ϵ ring, and the counterpart 25:24 OLR of Cordelia with the ring’s inner edge. The phases of the modes and their pattern speeds are consistent with the mean longitudes and mean motions of the satellites, confirming their dynamical roles in the ring system.
- From separate orbit fits to the ring edge measurements obtained from square-well model fits to individual ring profiles, we determined the width-radius relations for nearly all of the detected modes, with positive width-radius

slopes for ILR modes (including the $m = 1$ elliptical orbits) and negative slopes for most of the detected OLR modes, as predicted by standard self-gravity models. Ring mass and surface density estimates based on standard self-gravity and collisional self-gravity models differ by orders magnitude and predict radically different radial optical depth profiles. These differences are unresolved at present, and warrant additional investigation. We found no convincing evidence for librations of any of the rings.

- The Uranus pole direction at epoch TDB 1986 Jan 19 12:00 is $\alpha_P = 77.311327 \pm 0.000141^\circ$ and $\delta_P = 15.172795 \pm 0.000618^\circ$, where the error bars take into account possible systematic errors in the *Voyager* ephemeris. The slight pole precession predicted by [Jacobson \(2023\)](#) was not detectable in our orbit fits, and the absolute radius scale is not strongly correlated with the pole direction.
- From Monte Carlo fits to the measured apsidal precession and nodal regression rates of the eccentric and inclined rings, we determined the zonal gravitational coefficients $J_2 = (3509.291 \pm 0.412) \times 10^{-6}$ and $J_4 = (-35.522 \pm 0.466) \times 10^{-6}$ with a correlation coefficient $\rho(J_2, J_4) = 0.9861$ and J_6 held fixed at $= 0.5 \times 10^{-6}$, for a reference radius $R = 25559$ km. This result is significantly displaced from previous results ([Jacobson 2014](#)), owing to the inclusion of previously neglected systematic effects. The quoted errors account for systematic differences (and their uncertainties) between the fitted semimajor axes of the ring centerlines (COR) and their estimated centers of opacity (COO), a surrogate for the center of mass (COM) semimajor axes that should be used when computing the radial gradient in the apse and node rates. The minor satellites Cordelia and Ophelia contribute significantly to the precession rate of the ϵ ring, affecting the final solution for J_2 and J_4 . Although we cannot set useful independent limits on J_6 , we obtain strong joint constraints on combinations of J_2, J_4 , and J_6 that are consistent with our measurements. These can be used to limit the range of realistic models of the planet’s internal density distribution and wind profile with depth.
- The measured anomalous apsidal and nodal precession rates of the α and β rings are consistent with the presence of unseen moonlets with masses and orbital radii predicted by [Chancia and Hedman \(2016\)](#).
- From the amplitudes and resonance radii of normal modes forced by moonlets, we determined the masses of Cressida, Cordelia, and Ophelia. Their estimated densities vary systematically with orbital radius and generally follow the radial trend of the Roche critical density for a shape parameter $\gamma = 1.6$. This may provide an important clue to the formation process and possible orbital migration of these small moons.

12. ACKNOWLEDGEMENTS

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APPENDIX

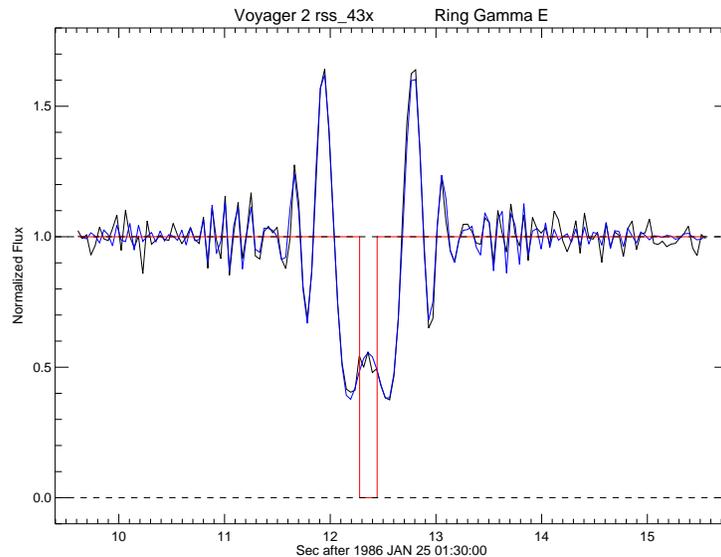


Figure A1. Raw intensity profile of *Voyager 2* γ ring egress profile, uncorrected for diffraction. The best-fitting square-well model is overplotted, and the box function square-well model is shown in red, with a width of 1.37 km.

A. VOYAGER 2 OCCULTATIONS AND SQUARE-WELL MODEL EVALUATION

The *Voyager 2* radio and stellar occultations provide our current best view of the fine-scale radial internal structure of the narrow Uranian rings. (For a detailed description of the *Voyager* observations and of the shapes and observed structure of each ring, see French et al. (1991).) The high-SNR σ Sgr occultation chord intersected only the δ , λ , and ϵ rings, while the lower-SNR β Per event spanned the entire ring system on ingress and egress. The viewing geometry of the two stellar occultations was quite different from all other Uranus ring occultations, providing additional constraints on the Uranus pole direction.

The *Voyager* RSS data present an excellent opportunity to assess the accuracy of the square-well model approximation to ring structure because the raw observations are affected by diffraction with a Fresnel scale $F \sim 1.6 - 2.3$ km, comparable to typical values for Earth-based stellar occultations, while the diffraction-reconstructed data reveal the true ring structure at 50 m resolution (Gresh et al. 1989). **Figure A1** shows the diffraction pattern visible in the uncorrected RSS observations of the egress γ ring profile, along with the best-fitting square-well model to the measured intensity. It closely resembles the diffraction pattern in Fig. 3. In this instance, the best fitting square-well model is 1.37 km wide and nearly opaque, with a corresponding diffraction pattern computed for the event geometry that matches the observations for about seven fringes on either side.

Unlike stellar occultation observations, however, the availability of phase information in the recorded RSS signal enables the diffraction effects to be greatly reduced using Fresnel inversion (Marouf et al. 1986). The diffraction-corrected profile for this profile is shown in **Fig. A2**, at a processing resolution of 50 m. The upper panel shows the optical depth profile, with sharp edges and perhaps some evidence of noise-limited internal structure. The lower panel shows the reconstructed intensity profile, which is a more appropriate representation for comparison with a square-well model. In this instance, the ring does indeed resemble a square-well with sharp edges and a measured width of 1.43 km, determined from Eq. (A1) below (shown dashed), very close to the 1.37 km width of the square-well fit to the diffraction-limited data. Note that the radius scale is from the data in the PDS archive file, and not from the current orbit determination.¹³

The close agreement between the measured width and the width obtained from the square-well model demonstrates its accuracy and applicability for actual observations of an intrinsically sharp-edged ring with an intensity profile that

¹³ VG_2803/U_RINGS/EASYDATA/KM00_025/RU1P2XGE.TAB

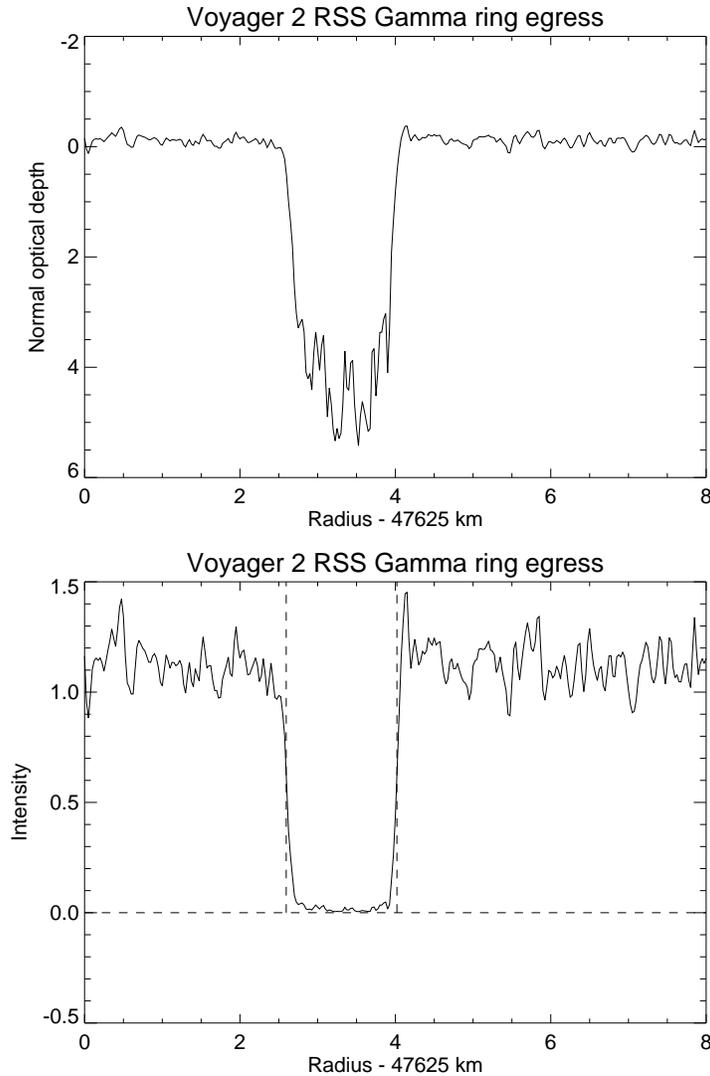


Figure A2. Diffraction-reconstructed RSS egress γ ring profile at an effective resolution of 50 m, plotted as a function of normal optical depth (upper panel) and normalized intensity (lower panel). The width of the reconstructed profile determined from Eq. (A1) is 1.427 km, shown by the vertical dashed lines, very similar to the 1.370 km width obtained from the square-well model fit to the diffraction-limited profile shown in Fig. A1.

resembles a box function. As shown by Gresh et al. (1989), however, several of the Uranian rings have radially variable internal structure, and not all of them have sharp edges. We repeated the exercise described above and compared the ring widths determined from the square-well fits of the diffraction-limited RSS observations to the observed ring widths of the diffraction-corrected profiles. To provide an objective measure of the ring width, we define the edges as the locations where

$$I = 1 - f(1 - \min I), \quad (\text{A1})$$

where I is the normalized diffraction-corrected signal intensity and $f = 0.364$, a value chosen to minimize the mean offset between the square-well model widths obtained from fits to the complete set of diffraction-limited RSS ring profiles and the actual ring widths estimated from the diffraction-corrected profiles as given by Eq. (A1). Here, f corresponds to the chosen fractional drop in the signal (from unit intensity to $\min I$, the minimum observed intensity of a ring profile) that formally defines the edge of the ring. The results of these comparisons are given in Table A1, which lists the ingress and egress width estimates and their differences for each ring. The mean difference in width

$dW = 0.002$ km between the square-well fits and the measured widths is very small, and the standard deviation $\sigma(dW) = 0.27$ km.

Table A1. Comparison of square-well and *Voyager* ring widths

Ring	Dir ^a	W (km) ^b (square-well)	W (km) ^c <i>Voyager</i>	dW (km)
6	I	0.899	1.141	-0.242
6	E	1.408	1.337	0.071
5	I	2.615	2.376	0.239
5	E	1.169	1.279	-0.111
4	I	1.405	1.295	0.110
4	E	1.880	1.663	0.217
α	I	9.423	8.676	0.747
α	E	3.866	4.120	-0.254
β	I	5.069	5.081	-0.012
β	E	8.334	8.099	0.235
η	I	1.371	1.479	-0.108
η	E	1.105	1.220	-0.115
γ	I	3.648	3.745	-0.097
γ	E	1.371	1.427	-0.056
δ	I	5.182	5.777	-0.595
δ	E	2.229	2.272	-0.044
ϵ	I	22.247	22.315	-0.068
ϵ	E	74.855	74.776	0.079

^a I: ingress E:egress

^b Square-well fits provide the COR midtimes of *Voyager* RSS profiles used in ring orbit fits.

^c From Eq. (A1) with $f = 0.364$.

Shown graphically in **Fig. A3**, it is evident from these results that, except for two outliers (the ingress α and δ ring profiles), all of the measured width differences dW are within $1\text{-}\sigma$ of zero. Of particular relevance for the measured normal mode distortions of selected ring edges in Section 4.1, we find that the RSS η ring profiles have measured width differences $|dW| \leq 0.115$ km, the γ ring profiles have $|dW| \leq 0.097$ km, and ϵ ring profiles have $|dW| \leq 0.079$ km, suggesting that the square-well fitted widths to these intrinsically sharp-edged rings are reliable, at least for ring profiles that are not significantly smoothed by the finite angular diameters of the occultation stars or by instrumental time constants.

The two exceptions noted above for the α and δ rings illustrate some of the challenges of defining a metric for ring widths that reflects their actual internal structure. **Figure A4** shows the RSS diffraction-reconstructed α ingress ring profile, with the vertical dashed lines marking the ring edges as defined by Eq. (A1). The marked outer edge reasonably matches the moderately sharp outer edge of the ring, but the marked inner edge is clearly a compromise between the abrupt drop in intensity near 44734 km and the gradual variation in ring opacity between 44729–44734 km. (Note that the radius scale is from the data in the PDS archive file, and not from the current orbit determination.¹⁴) The best-fitting square-well model fit is shown in **Fig. A5**, where the underlying structure of the α ring’s inner edge (seen at right in this time-ordered ingress profile) is resolved at the level of a few km and resembles the observed structure near the inner edge of the *Voyager* RSS diffraction-corrected profile. The square-well model accurately matches the outer edge but not the inner edge, resulting in likely systematic errors in the fitted midtimes and widths for at least some Earth-based α ring profiles.

A similar situation prevails for the δ ingress event, whose RSS diffraction-reconstructed profile is shown in **Fig. A6**. Again, the outer edge of the ring is seen to be intrinsically quite sharp, but the inner edge is indistinct, with the ring’s opacity increasing gradually over a radial range of ~ 3 km before reaching a maximum near mid-ring. The vertical dashed lines mark the ring edges as defined by Eq. (A1). (Note that the radius scale is from the data in the PDS archive file, and not from the current orbit determination.¹⁵) In this instance, the square-well model fit, shown in

¹⁴ VG_2803/U_RINGS/EASYDATA/KM00_025/RU1P2XAI.TAB

¹⁵ VG_2803/U_RINGS/EASYDATA/KM00_025/RU1P2XDI.TAB

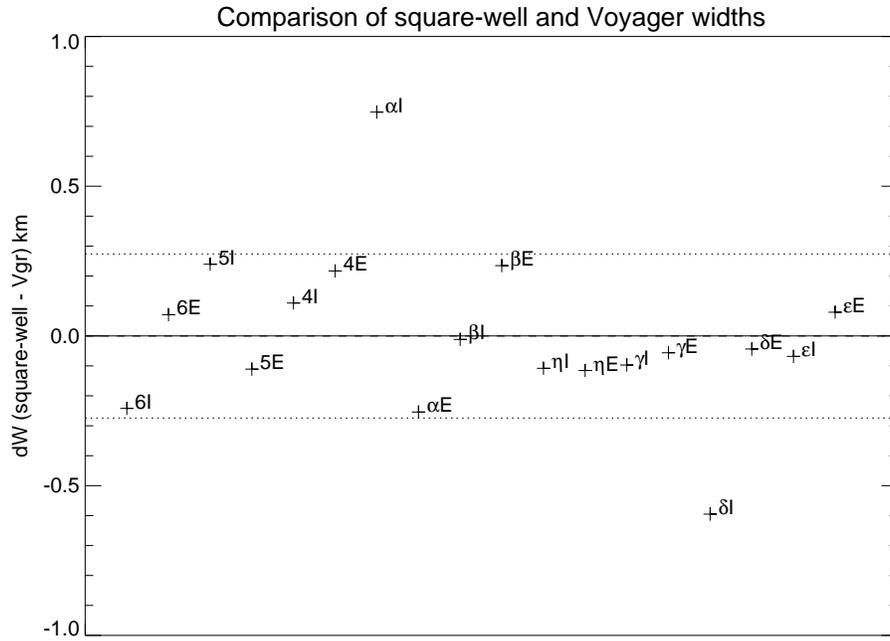


Figure A3. Differences dW between the widths of *Voyager* RSS ring profiles obtained from square-well model fits to the uncorrected diffraction patterns in the raw data and the measured widths of the diffraction-corrected profiles using Eq. (A1) with $f = 0.364$. The dotted lines mark the $\pm 1\text{-}\sigma$ values computed from the full set of residuals, including the two outlier points (αI and δI). The barely visible dashed line shows the mean offset in dW of the measurements.

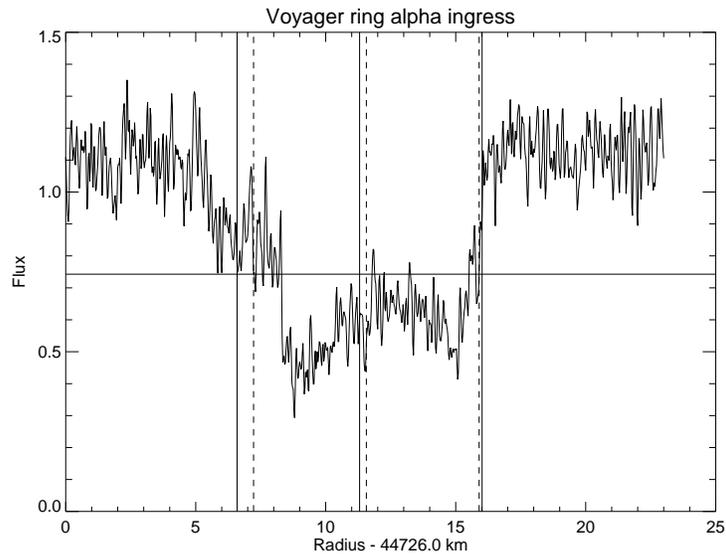


Figure A4. Radial profile of the diffraction-corrected *Voyager* RSS observations of the α ring during ingress. The dashed vertical lines mark the midline and the inner and outer edges of the ring as estimated using Eq. (A1) with $f = 0.364$, corresponding to the flux level marked by the solid horizontal line. The solid vertical lines mark the corresponding radii as determined from the square-well model fit to the diffraction-limited RSS profile, based on the radius scale of the archived profiles on the PDS, which differs slightly from the radius scale of our adopted orbit solution.

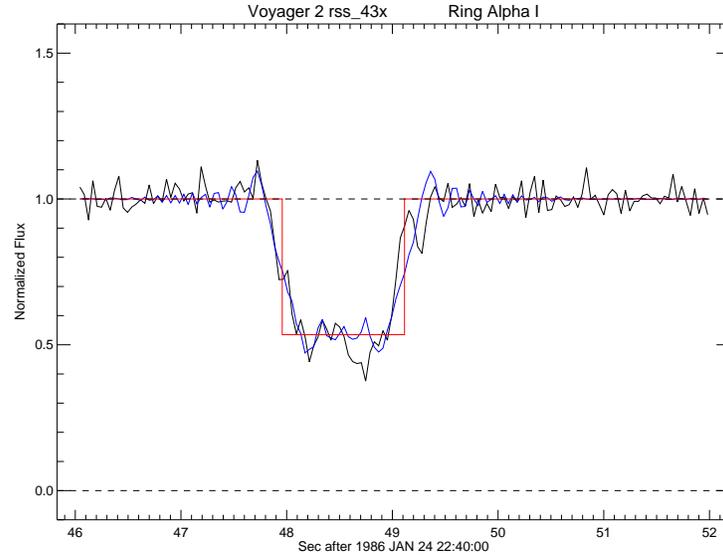


Figure A5. Square-well model fit to the uncorrected diffraction-limited *Voyager* RSS α ring ingress profile. Note the good fit of the square-well model to the sharp outer edge of the ring (at left) and the poor fit to the more gradual inner edge at right.

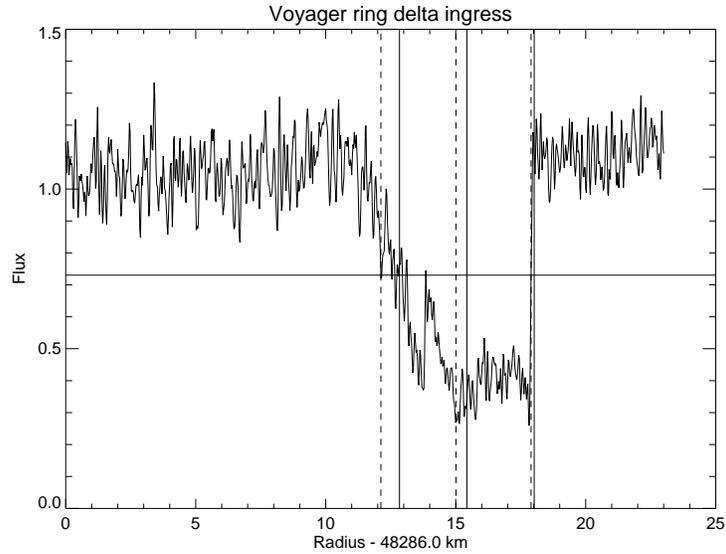


Figure A6. Radial profile of the diffraction-corrected *Voyager* RSS observations of the δ ring during ingress. The dashed vertical lines mark the midline and the inner and outer edges of the ring as estimated using Eq. (A1) with $f = 0.364$, corresponding to the flux level marked by the solid horizontal line. The solid vertical lines marks the corresponding radii as determined from the square-well model fit to the diffraction-limited RSS profile, based on the radius scale of the archived profiles on the PDS, which differs slightly from the radius scale of our adopted orbit solution.

Fig. A7, underestimates the measured width of the high-resolution profile. Notice that the diffraction fringes at the left (earlier in time, corresponding to the outer edge of this ingress profile) match the data for several fringes, whereas the diffraction-limited RSS observations of the inner edge show much more disorder, resulting from the lack of a sharp inner ring edge.

Given this level of disagreement between the square-well results and the actual ring observations for rings with non-sharp edges, one could envision a generalization of the simple square-well picture to a multi-well model that fitted the data to a more realistic radial opacity profile. Unfortunately, the radial optical depth profiles of the narrow Uranian

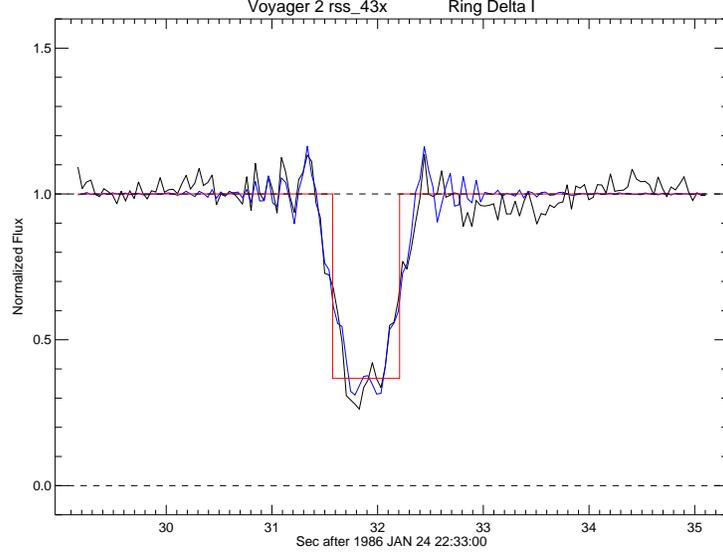


Figure A7. Square-well model fit to the uncorrected diffraction-limited *Voyager* RSS δ ring ingress profile. The sharp outer edge of the ring at left is well-matched by the square-well model, but the modeled diffraction fringes for the inner edge at right are a poor match to the observed diffraction pattern of the gradual inner edge.

rings at different ring longitudes do not follow a simple, discernible pattern, and thus it has not proven possible to construct an N -streamline model for any of the rings that accurately matches the observed structure at all longitudes.

B. CENTER OF OPACITY (COO) FROM VOYAGER AND EARTH-BASED RING OCCULTATION PROFILES

In Section 7.1, we distinguished between the observed radius of a ring’s centerline (COR) and its radius derived from its radially-integrated optical depth (COO), using the *Voyager* ring 6 occultation profiles as an example in Fig. 31. We apply this same method to *Voyager* ring occultation profiles for rings 5, 4, α , β , γ , and ϵ in Figs. B1–B6. For the ϵ ring, we have made additional use of the *Voyager* σ Sgr optical depth profiles, in part because the RSS ingress profile sampled the ring near periapse ($f = 30.0^\circ$) with noise-affected high optical depths. (Note that RSS optical depths are twice as large as comparable spacecraft or Earth-based stellar occultation profiles, due to diffraction scattering signal loss.) The four *Voyager* profiles yield values of Δa_{COR} ranging from 0.46 to 1.53 km. The ring is also radially resolved in several of the Earth-based stellar occultations. We have selected thirteen of the highest SNR profiles from this set. To minimize the effects of uncertain normalization that afflict estimates of high optical depth when the observed normalized stellar flux is near zero, we limited our selection to profiles more than 90° from periapse, shown in Fig. B7. They yielded values of Δa_{COR} ranging from 0.54 to 1.95 km, comparable in average and range to the *Voyager* results. The mean ϵ ring value for $\Delta a_{\text{COR}} = 1.134 \pm 0.488$ km.

The derived centers of opacity for all the eccentric ringlets are given in Table 16, which lists a_{COR} , the unweighted average values for Δa_{COO} and their RMS variation, the statistical significance $\Delta a_{\text{COO}}/\sigma(\Delta a_{\text{COO}})$, and finally of a_{COO} , with an uncertainty given by the sum in quadrature of $\sigma(a_{\text{COR}})$ and $\sigma(\Delta a_{\text{COO}})$.

C. THE COMPATIBILITY OF A MODEL GRAVITY FIELD $\{J'_2, J'_4, J'_6\}$ WITH THE ADOPTED SOLUTION FROM RING OCCULTATIONS

In Section 7, we noted the strong correlations between J_2 , J_4 , and J_6 in the gravity field determination from the Uranus ring occultation data. Here, we use the observed correlations to provide a prescription for determining the compatibility of model values $\{J'_2, J'_4, J'_6\}$ with the adopted gravity field.

First, we quantify the approximate relationship between J_2 and J_4 . Given the strong correlation between J_2 and J_4 (reflected in the narrowness of the error ellipse for Fit 15 shown in Fig. 33), it is possible to construct an approximate

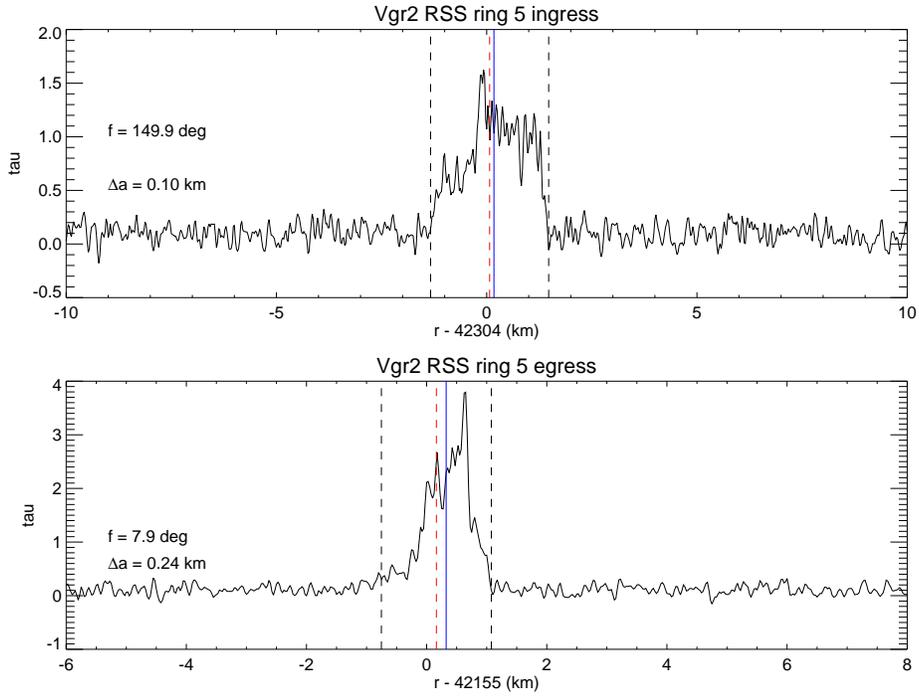


Figure B1. Ring 5 center of opacity from *Voyager* RSS optical depth profiles.

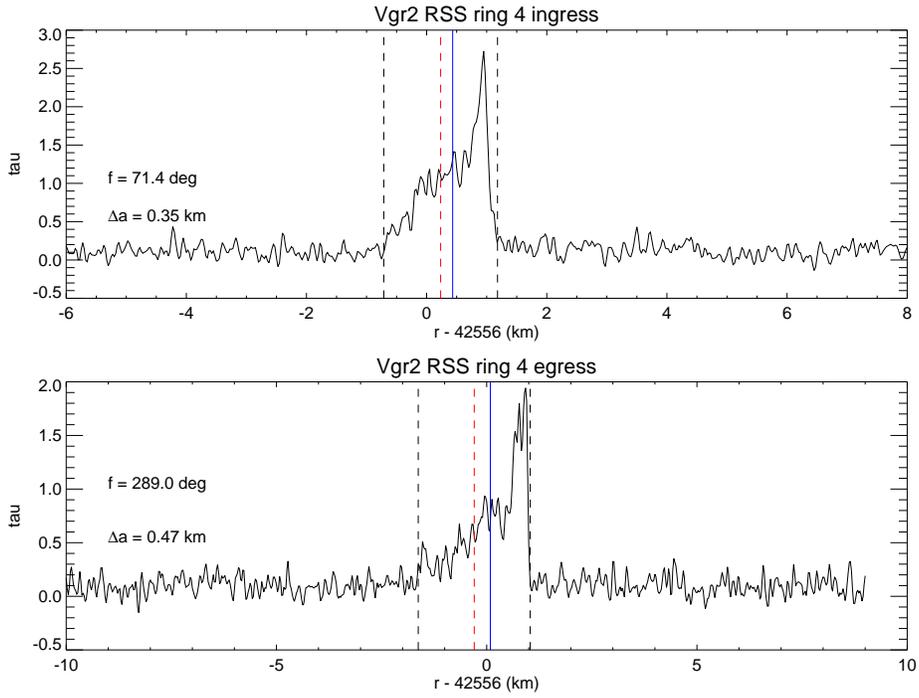


Figure B2. Ring 4 center of opacity from *Voyager* RSS optical depth profiles.

relationship between the two leading terms in the gravitational field. Under the restricted circumstances that $J_6 = 0$, the local value of dJ_4/dJ_2 can be estimated by setting the differential of the leading terms in $\dot{\varpi}$ to zero:

$$d\dot{\varpi} = \left(\frac{GM_{\text{Ur}}}{a^3}\right)^{1/2} \left[\frac{3}{2} dJ_2 \left(\frac{R}{a}\right)^2 - \frac{15}{4} dJ_4 \left(\frac{R}{a}\right)^2 \right] = 0, \quad (\text{C1})$$

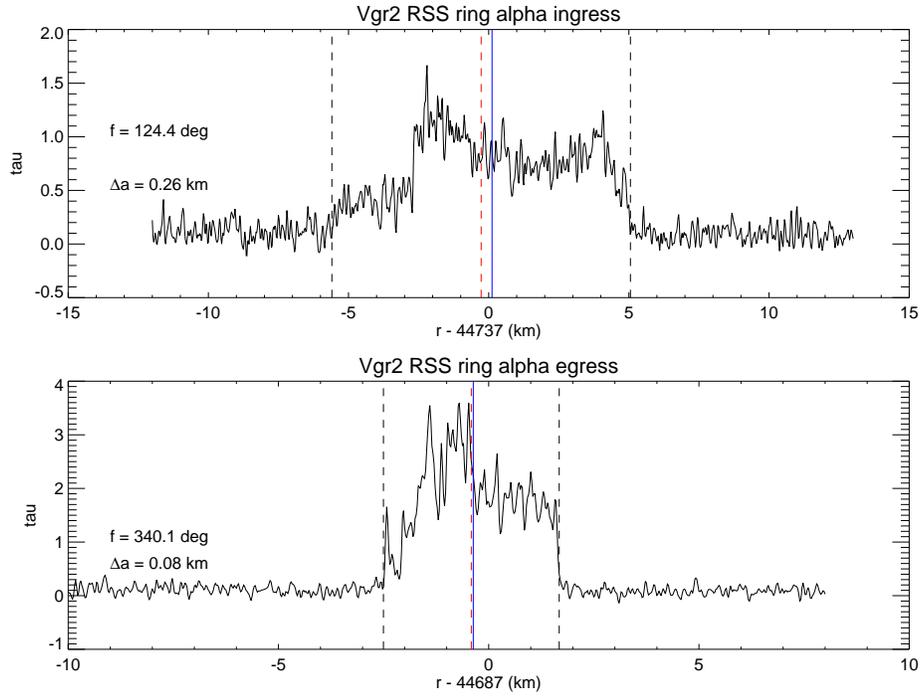


Figure B3. Ring α center of opacity from *Voyager* RSS optical depth profiles.

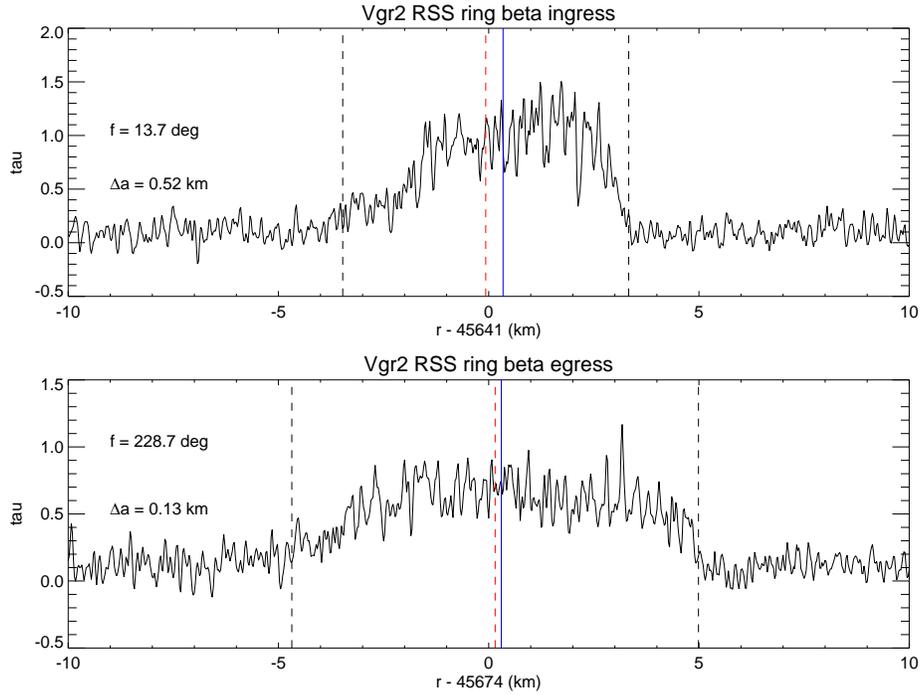


Figure B4. Ring β center of opacity from *Voyager* R/coS optical depth profiles.

from which we find

$$dJ_4/dJ_2 = \frac{2}{5} \left(\frac{a}{R} \right)^2 = 1.24 \left(\frac{a}{45000 \text{ km}} \right)^2, \quad (\text{C2})$$

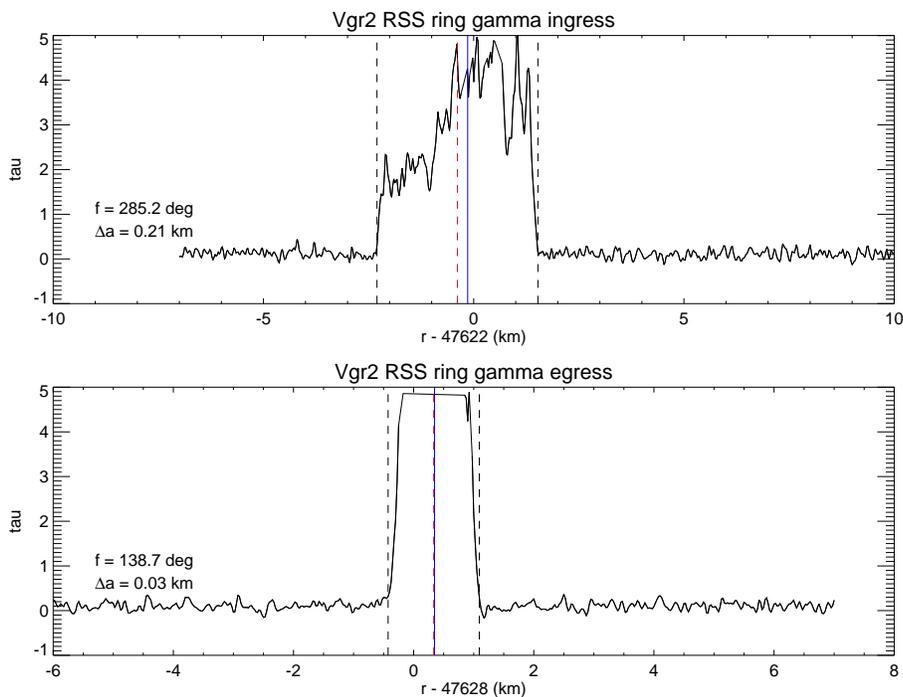


Figure B5. Ring γ center of opacity from *Voyager* RSS optical depth profiles.

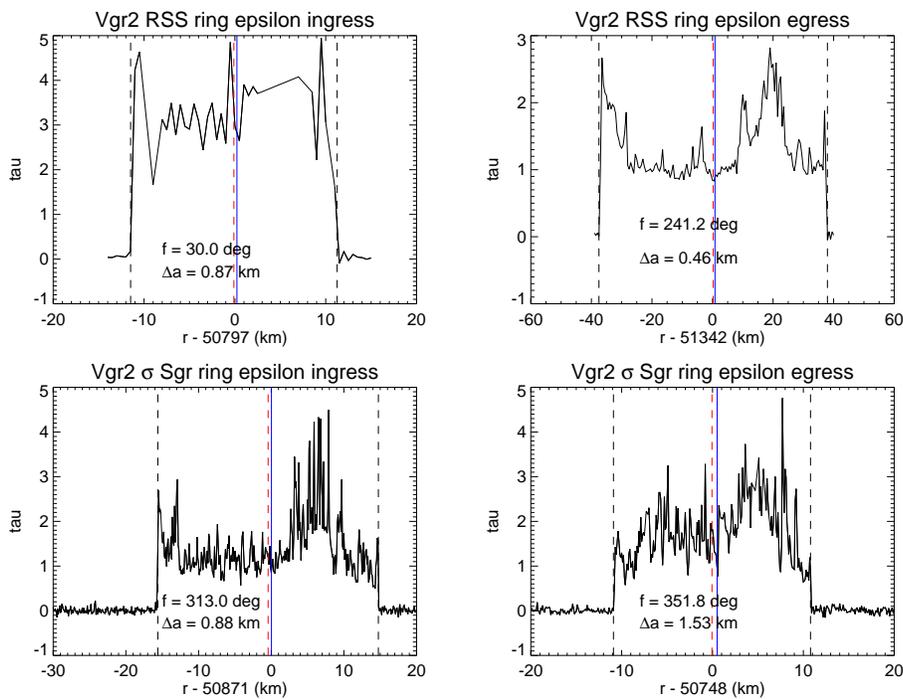


Figure B6. Ring ϵ center of opacity from *Voyager* RSS and σ Sgr optical depth profiles. Note that stellar occultation geometric optical depths should be multiplied by a factor of two before comparison with RSS normal optical depths.

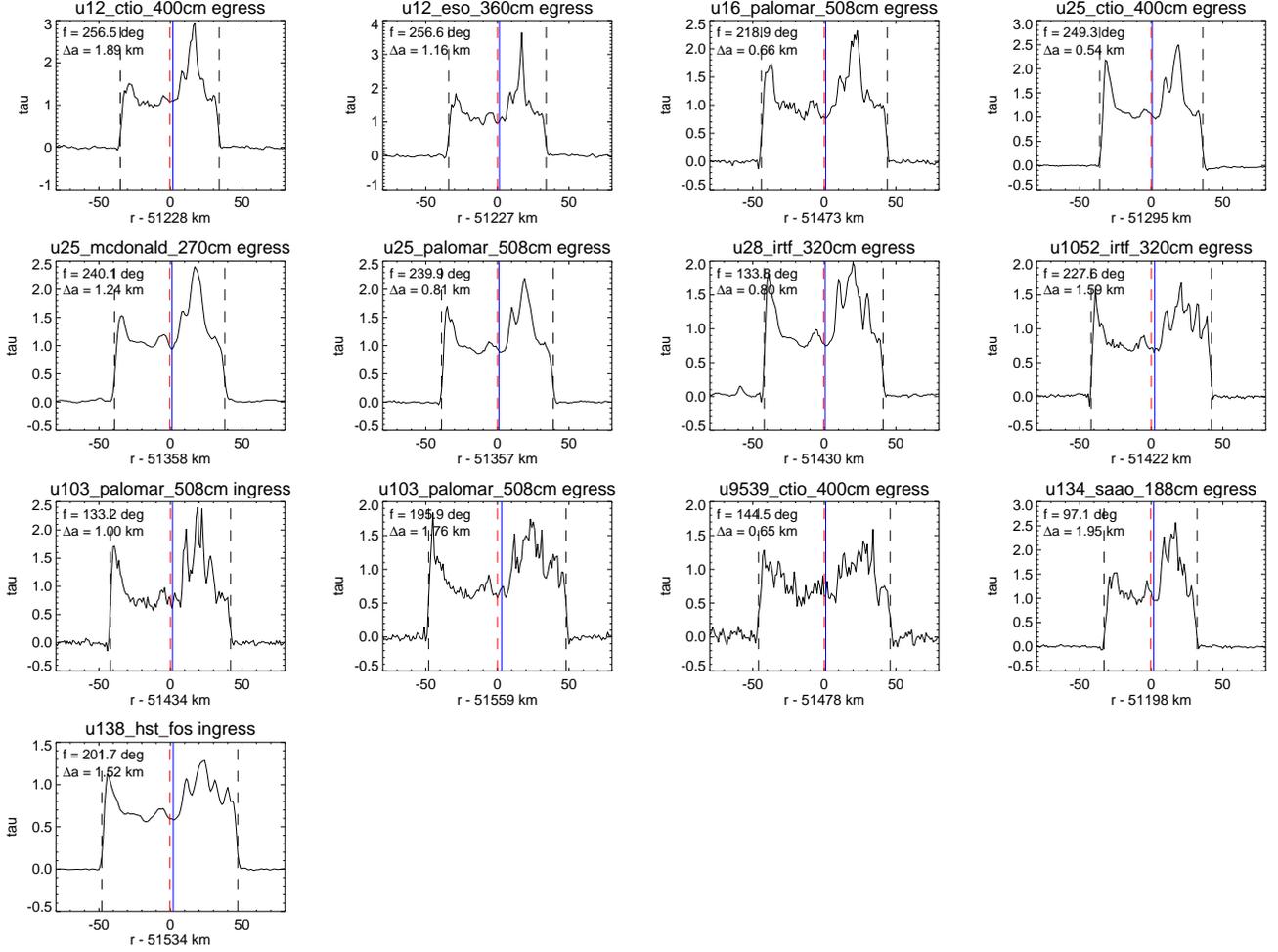


Figure B7. Estimates of the ϵ ring center of opacity (COO) from Earth-based occultation profiles. Note that stellar occultation geometric optical depths should be multiplied by a factor of two before comparison with RSS normal optical depths. See text for details.

Setting a in Eq. (C2) to 44695 km, the mean of the semimajor axes of rings 6, 5, 4, α , β , and ϵ (those with accurate apse rates), and letting $R = 25559$ km, we obtain $dJ_4/dJ_2 \simeq 1.223$. This is close to the slope of the long axis of the error ellipse for our adopted fit in Fig. 33, given by $dJ_4/dJ_2 = \tan \theta = 1.134$, where θ is defined in Eq. (C20) below. Under a linear approximation, a model value J'_4 that is consistent with the observed values of J_2 and J_4 and an assumed model value J'_2 is given by

$$J'_4(J'_2) \simeq J_4 + \frac{dJ_4}{dJ_2}(J'_2 - J_2). \quad (\text{C3})$$

Evaluated numerically:

$$J'_4(J'_2) \simeq [-35.533 + 1.134 \times (J'_2 - 3509.281)] \times 10^{-6}. \quad (\text{C4})$$

Next, we assume that the partial derivatives in Table 17 accurately represent the sensitivity of the fitted values for $J_2(J_6, \Delta a)$ and $J_4(J_6, \Delta a)$ in our adopted solution (Fit 15) to small differences from our assumed values of $J_6 = 0.5 \times 10^{-6}$ and $\Delta a = 0$. Then the following relations specify the values of J_2 and J_4 predicted to result from a fit in which J_6 and the systematic radius scale offset have the fixed *a priori* values J'_6 and Δa :

$$J_2(J'_6, \Delta a) = J_2(0.5 \times 10^{-6}, 0) + \frac{dJ_2}{dJ_6}(J'_6 - 0.5 \times 10^{-6}) + \frac{dJ_2}{d\Delta a}\Delta a \quad (\text{C5})$$

$$J_4(J'_6, \Delta a) = J_4(0.5 \times 10^{-6}, 0) + \frac{dJ_4}{dJ_6}(J'_6 - 0.5 \times 10^{-6}) + \frac{dJ_4}{d\Delta a} \Delta a. \quad (\text{C6})$$

Numerically, our final values for J_2 and J_4 map onto the corresponding values for non-zero J'_6 and Δa according to:

$$J_2(J'_6, \Delta a) = 3509.281 \times 10^{-6} + 0.39909 \times (J'_6 - 0.5 \times 10^{-6}) + 0.130 \times 10^{-6} \Delta a (\text{km}) \quad (\text{C7})$$

$$J_4(J'_6, \Delta a) = -35.533 \times 10^{-6} + 1.07570 \times (J'_6 - 0.5 \times 10^{-6}) - 0.180 \times 10^{-6} \Delta a (\text{km}). \quad (\text{C8})$$

To determine whether any planetary gravity model $\{J'_2, J'_4, J'_6, \Delta a\}$ falls within the $1\text{-}\sigma$ error ellipse of our adopted solution, the Mahalanobis distance r must be ≤ 1 , where

$$r = \sqrt{\frac{x'^2}{\lambda_1} + \frac{y'^2}{\lambda_2}}, \quad (\text{C9})$$

and λ_1 and λ_2 are the eigenvalues of the (J_2, J_4) covariance matrix:

$$\text{covar}(J_2, J_4) = \begin{bmatrix} a & b \\ b & c \end{bmatrix}, \quad (\text{C10})$$

with

$$a = \sigma^2(J_2), \quad (\text{C11})$$

$$b = \rho(J_2, J_4) \sigma(J_2) \sigma(J_4), \quad (\text{C12})$$

and

$$c = \sigma^2(J_4), \quad (\text{C13})$$

and x' and y' are defined below.¹⁶ The halfwidths of the two axes of the error ellipse are given by $\sqrt{\lambda_1}$ and $\sqrt{\lambda_2}$, where

$$\lambda_1 = \frac{a+c}{2} + \sqrt{\left(\frac{a-c}{2}\right)^2 + b^2}, \quad (\text{C14})$$

and

$$\lambda_2 = \frac{a+c}{2} - \sqrt{\left(\frac{a-c}{2}\right)^2 + b^2}. \quad (\text{C15})$$

The following transformation rotates the error ellipse by θ :

$$x' = x \cos \theta + y \sin \theta \quad (\text{C16})$$

$$y' = -x \sin \theta + y \cos \theta, \quad (\text{C17})$$

where

$$x = J'_2 - J_2(J'_6, \Delta a), \quad (\text{C18})$$

$$y = J'_4 - J_4(J'_6, \Delta a), \quad (\text{C19})$$

and the rotation angle θ is specified by

$$\theta = \tan^{-1}(\lambda_1, b), \quad (\text{C20})$$

where the arguments of the arctangent are the column entries of the covariance matrix eigenvectors, simplified by multiplying by their common divisor.

From our adopted gravity parameters (Fit 15 in Table 17), $\sigma(J_2) = 0.412 \times 10^{-6}$, $\sigma(J_4) = 0.466 \times 10^{-6}$, and $\rho(J_2, J_4) = 0.9861$, yielding the numerical values $\lambda_1 = 3.84252 \times 10^{-13}$, $\lambda_2 = 2.64830 \times 10^{-15}$, $a = 1.697440 \times 10^{-13}$, $b = 1.893233 \times 10^{-13}$, $c = 2.17156 \times 10^{-13}$, and $\theta = 48.5686^\circ$.

¹⁶ <https://cookierobotics.com/007/>

The complementary cumulative probability $\text{CCP}(r)$ that a given sample has a standard deviation $\geq r$ by chance for a given $(J'_2, J'_4, J'_6, \Delta a)$ is given by

$$\text{CCP}(r) = e^{-r^2(J'_2, J'_4, J'_6, \Delta a)/2}, \quad (\text{C21})$$

appropriate for a two-dimensional gaussian distribution, where r is given by Eq. (C9). Note that $\text{CCP}(1) = 0.6065$, $\text{CCP}(2) = 0.1353$, $\text{CCP}(3) = 0.0111$, and $\text{CCP}(4) = 0.0003$. In comparison, the complementary cumulative probability for a one-dimensional normal distribution is given by $\text{erfc}(r/\sqrt{2})$, yielding the more familiar corresponding values $1\sigma = 0.3173$, $2\sigma = 0.0455$, $3\sigma = 0.0027$, and $4\sigma = 0.0001$.

The inverse relationship

$$r = \sqrt{-2 \ln \text{CCP}(r)} \quad (\text{C22})$$

provides the factor r for a given confidence level $\text{CCP}(r)$. For example, the values of r corresponding to $\text{CCP}=30\%$, 10% and 1% cutoff values for acceptable interior models that are consistent with our gravity measurements are 1.55, 2.15 and 3.03, respectively.

The prescription for computing the difference in standard deviations $r(J'_2, J'_4, J'_6, \Delta a)$ between a model with assumed values $\{J'_2, J'_4, J'_6, \Delta a\}$ and our adopted solution is:

- Specify values for J'_2, J'_4, J'_6 , and Δa .
- Compute $J_2(J'_6, \Delta a)$ and $J_4(J'_6, \Delta a)$ from Eqs. (C7) and (C8).
- Compute x and y from Eqs. (C18) and (C19).
- Compute x' and y' from Eqs. (C16) and (C17), using the given numerical value for θ .
- Compute r from Eq. (C9) and the given numerical values for λ_1 and λ_2 .

D. ALIGNMENT OF ILR AND OLR RING EDGE MODE APSES RELATIVE TO FORCING SATELLITE

In the main body of the paper, we have assumed the following properties of ring edge modes forced by a satellite:

- In the absence of dissipation, the forced mode (periapse/apoapse) is aligned with the satellite mean longitude for an (ILR/OLR), respectively.
- In the presence of dissipation, the relevant apse is (lagging/leading) the satellite mean longitude in angle for an (ILR/OLR), respectively.

Here, we justify these assumptions on dynamical grounds by drawing on well-known results for ILR edge modes and making use of an exact formal symmetry between inner and outer edge modes to determine the corresponding OLR edge mode properties.

ILR edge modes are to date much more extensively studied than OLR ones; in particular, detailed numerical solutions are available only for ILR edge modes. It turns out that a few properties, including simple geometric features, can only be obtained through detailed solutions of the dynamical equations. OLR edge mode properties must therefore also be obtained from such detailed solutions.

In the large $|m|$ limit, the dynamical equations display an exact formal symmetry between inner and outer edge modes. This symmetry allows us to deduce a number of properties of inner edge modes from outer edge ones.¹⁷

¹⁷ The large m limit applies quantitatively as soon as $|m|$ is larger than a few; the approximation is also semi-quantitatively relevant even for $|m| = 2$.

Let us show this explicitly. In the streamline formalism, the mode structure is controlled by two dynamical equations, one for the mode eccentricity profile and one for its apsidal shift profile. In a discrete, N -streamlines formulation, these equations read (see Longaretti 2018 and Longaretti 2023 for details):

$$\sum_{j \neq i} \frac{\bar{n}}{\pi} \frac{m_j}{M_p} a^2 H(q_{ij}^2) \frac{\epsilon_i - \epsilon_j}{(\Delta a_{ij})^2} - [\kappa_i - m(\Omega_i - \Omega_P)] \epsilon_i = -\bar{n} \frac{a \Psi_{m,k}}{2GM_p}, \quad (\text{D1})$$

$$\begin{aligned} \sum_{j \neq i} \frac{\bar{n}}{\pi} \frac{m_j}{M_p} a^2 H(q_{ij}^2) \frac{\epsilon_i \sin m \Delta_i - \epsilon_j \sin m \Delta_j}{(\Delta a_{ij})^2} - [\kappa_i - m(\Omega_i - \Omega_P)] \epsilon_i \sin m \Delta_i \\ = \frac{2\pi}{\bar{n} m_i} \Delta^\pm \left(\frac{a}{q} \frac{d\epsilon}{da} t_1 \right). \end{aligned} \quad (\text{D2})$$

In these equations, m is the azimuthal wavenumber (number of lobes of the edge mode), a_i , ϵ_i and Δ_i are the semi-major axis, eccentricity and apsidal shift of streamline i ($\Delta_i = -\delta_i$ in the notation of Eq. 8 of the present paper), m_j the mass of streamline j , $\Delta a_{ij} = a_j - a_i$, \bar{n} is the mean motion at the mode resonance and a the resonance location, $q_{ij} = a(\epsilon_j - \epsilon_i)/\Delta a_{ij}$, κ_i and Ω_i the epicyclic radial frequency and angular rotation velocity of streamline i , M_p the planet mass (here Uranus), Ω_P the mode pattern speed, $\Psi_{m,k}$ the satellite forcing term, $H(q_{ij})$ a dimensionless function of order unity which arises from the nonlinearity of the ring self-gravity, and t_1 is an effective stress tensor quantity, characterizing the ring viscous dissipation. The viscous coefficient t_1 is a function of the nonlinearity parameter $q = |ade/da|$; $t_1 < 0$ in the absence of viscous overstability, and $|t_1| \rightarrow 0$ when $q \rightarrow 0$. Finally, $\Delta^\pm X$ is the variation of X across the current streamline (outer boundary minus inner boundary value of X). The azimuthal wavenumber m is positive at an inner Lindblad resonance and negative at an outer Lindblad resonance.

The first term on the left-hand side of both equations represents the effect of the ring self-gravity, the second term the frequency drift with respect to the pattern speed, as by definition $\kappa - m(\Omega - \Omega_P) = 0$ at the resonance. On the right-hand side, one finds the satellite forcing term in the first equation and the ring internal (collisional) dissipation in the second one. The two equations are very similar; in particular the left-hand sides are formally identical under the substitution $\epsilon \leftrightarrow \epsilon \sin m \Delta$.

Furthermore, one can write

$$\kappa_i - m(\Omega_i - \Omega_P) = \frac{3\Omega(m-1)}{2a} (a_i - a) \simeq \frac{3\Omega m}{2a} (a_i - a), \quad (\text{D3})$$

for $|m| > 1$. The mode exists mostly outside the resonance at an ILR and inside the resonance at an OLR. The second equality applies in the large $|m|$ limit.

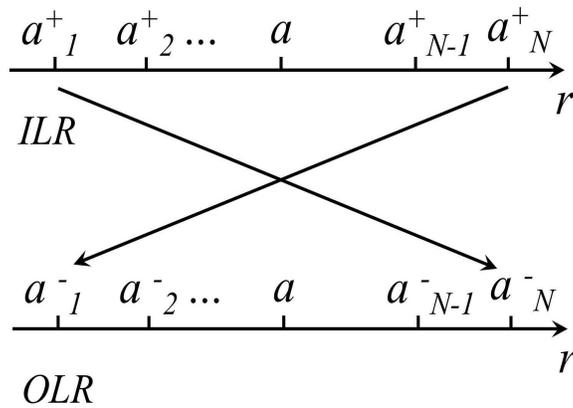


Figure D1. Sketch of the ILR/OLR streamline symmetry: streamline semimajor axes a_i are symmetrized with respect to the resonance location a , while keeping their index order. As a consequence, they are ordered in increasing semimajor axis order at ILR but decreasing semimajor axis at OLR.

This large $|m|$ limit reveals an interesting symmetry property between an ILR and an OLR equations with the same but opposite m wavenumbers (see Fig. D1). To see this, let us make a formal correspondence between an ILR and an OLR. We assume for now that the two resonance radii are equal.¹⁸ We specify the streamlines semi-major axes of an ILR edge mode by a ‘+’ superscript as a_i^+ . We also define a mirror set of streamlines with respect to the resonance location, with semi-major axes $a_i^- = a - (a_i^+ - a)$; by construction, a_i^- is the symmetric location of a_{N+1-i}^+ , with respect to the resonance location a . Calling $m^+ > 0$ the ILR azimuthal wavenumber and $m^- = -m^+ < 0$ the OLR one, in the large $|m|$ limit,

$$\kappa_i^+ - m^+(\Omega_i^+ - \Omega_P) = \kappa_i^- - m^-(\Omega_i^- - \Omega_P), \quad (\text{D4})$$

with the same meaning for the superscripts + and – on the frequencies, e.g. $\kappa_i^+ = \kappa(a_i^+)$. Defining similarly ϵ_i^\pm and Δ_i^\pm , this symmetry implies that the left-hand sides of Eqs. (D1) and (D2) are unchanged under the substitution $m^+ \leftrightarrow m^-$, $a_i^+ \leftrightarrow a_i^-$ if one assumes $\epsilon_i^- = \epsilon_i^+$ and $\Delta_i^- = \Delta_i^+$.

This would also provide the correct OLR mode solution from the ILR one if the right-hand sides were unchanged. However, this is not the case, due to changes in the right-hand sides under the ILR/OLR symmetry.

Let us start with Eq. (D1). In the large m limit, and for leading order inner Lindblad resonances ($k = 0$, the only ones of interest here):

$$\begin{aligned} \Psi_{m,0}(a) &\simeq -\frac{GM_s}{a_s} \frac{2m}{\pi} [2K_0(2/3) + K_1(2/3)] \\ &\simeq -\frac{GM_s}{a_s} \frac{5.04m}{\pi} \simeq -\frac{GM_s}{a_s} \frac{5m}{3}, \end{aligned} \quad (\text{D5})$$

where M_s is the satellite mass, a_s its semimajor axis, and K_0 and K_1 are modified Bessel functions (see Goldreich and Tremaine 1980 for this approximation). The same expression holds for a leading order OLR of same $|m|$. Note that $\Psi_{m,k} < 0$ at an ILR and > 0 at an OLR due to the change of sign of m .

These remarks have the following implication: *under the substitution of an ILR by an OLR as described above and assuming for simplicity that $\Psi_{m^-,k} = -\Psi_{m^+,k}$ — which is nearly true in the $|m| \gg 1$ limit — the ILR solution of Eq. (D1) is also a solution of the OLR form of the equation under the substitution $\epsilon^- = -\epsilon^+$.* In other words, the eccentricity profile of an ILR forced mode is also the eccentricity profile of the associated OLR (with the meaning specified above for this association), once this profile is antisymmetrized with respect to the resonance location.

This sign change has a notable consequence. From known numerical solutions of the forced mode equations at an ILR (Longaretti 2023), dissipationless ILR modes have their periapse aligned with the origin of phases of the forcing potential (i.e., the mean longitude of the satellite for leading order Lindblad resonances). The change of sign implies that, at an OLR, the apoapse is aligned with the satellite mean longitude instead, as $a(1 - \epsilon)$ (periapse) becomes $a(1 + \epsilon)$ (apoapse).

Let us now consider Eq. (D2). The symmetry just described leaves the nonlinearity parameter profile $q = |ade/da|$ unchanged but symmetrized with respect to the resonance location. Relatedly ade/da is also symmetric with respect to the resonance location (due to the change of sign of the eccentricity, the derivative remains positive). This implies that $(a/q)(de/da)t_1$ is symmetric as well, so that, for any given streamline, the right-hand side of Eq. (D2) changes sign under the symmetry discussed here, but is otherwise left unchanged. Therefore, $\Delta_i^- = -\Delta_i^+$ is the correct solution at an OLR under the same symmetry (as ϵ has changed sign according to the preceding discussion of the eccentricity profile and m changes sign as well).

To sum up: under the ILR/OLR symmetry described above, the ILR solution for a forced edge mode is also a solution at an OLR under antisymmetrization of the eccentricity ϵ and apsidal shift Δ profiles with respect to the resonance location. As a consequence, the mode apoapse is aligned with the satellite mean longitude in the absence of

¹⁸ This is hypothetical, and only for the sake of displaying the OLR/ILR edge mode symmetry. This does not imply that such a configuration of degenerate ILR and OLR resonances actually exists in rings.

dissipation. When dissipation is added, the apoapse is expected to be leading (in angle) with respect to the satellite mean longitude because the mode global phase $m\phi + m\Delta$ vanishes for some positive ϕ (ϕ is the azimuthal angle of the mode in the rotating frame). At an ILR, the mode periapse is nearly aligned with and lagging with respect to the satellite instead.

The conclusions just stated on the nature of the apse aligned with the satellite for an ILR/OLR forced mode are robust, but the sign of the lag applies for the simplest physical context only, and is therefore subject to various qualifications. These are discussed in the body of the text.

Note finally that the sign of the lag is consistent with the requirement that angular momentum exchanges with the satellite flow from the inside to the outside, in order for the satellite to confine a ring edge. This conclusion follows very simply from the following generic torque expression

$$T_s = \int da \pi m a \sigma_0 \Psi_{m,k} \epsilon \sin m\Delta, \quad (\text{D6})$$

which is valid for inner and outer resonances (Longaretti 1992, 2018). For an ILR edge mode, $m > 0$, $\Psi_{m,k} < 0$ and $\epsilon \sin m\Delta > 0$ so that $T_s < 0$, as expected (see Longaretti 2023 for actual eccentricity and apsidal shift profiles to substantiate this statement). For an OLR edge mode, and because of the ILR/OLR symmetry shown in this Appendix, $m < 0$, $\Psi_{m,k} > 0$ and $\epsilon \sin m\Delta < 0$ so that $T_s > 0$, again in line with expectations.

The arguments presented here are exact for identical ILR/OLR resonance locations and identical but opposite satellite forcing terms for both an ILR and an OLR. These requirements are not satisfied in reality, but the difference is only quantitative, not qualitative. In particular, for the large $|m|$ resonances of interest in the Uranian rings context, the relative quantitative difference introduced with respect to actual resonance locations and satellite forcing magnitudes is a small fraction of unity. Such a small difference will produce barely noticeable deviations in the OLR eccentricity and apsidal shift profiles from their symmetric ILR counterpart, for any given satellite. Furthermore, the qualitative issues examined here (which apse is nearly aligned with the satellite, and sign of their small lags) are independent of the quantitative details, such as the satellite mass, the azimuthal wavenumber, and the resonance location.

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