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# On the behaviour of the guided jet mode in merging twin-jet systems

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There is currently considerable interest in the guided jet mode, as a result of recent works demonstrating it being the upstream component closing the loop of various resonant systems. For given supersonic jet operating conditions the mode is known to exist over only a finite-frequency range that, for a twin-jet system, has been observed to vary with both jet separation and solution symmetry. Vortex-sheet and finite-thickness linear stability models are employed to consider the behaviour of the guided jet mode as the two jets are brought together for both a planar and round twin-jet system. It is demonstrated that in both cases as the twin-jet system merges it forms a higher-order mode of an equivalent single-jet geometry. This then imposes a constraint on the guided jet mode as the existence region must change to meet the existence region of the equivalent geometry the system merges to, leading to the previously observed dependence on jet separation.

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# 1. Introduction

Modelling of coherent structures in jet flow has been of interest since pioneering works by Mollo-Christensen (1967) and Crow & Champagne (1971) demonstrated their presence in the previously considered stochastic flow. Among the structures considered is the upstream-propagating guided jet mode  $(k_p^-)$ , a mode first studied by Tam & Hu (1989). It is characterised as having a phase speed very close to the speed of sound, maintaining radial structure outside of the jet core (as such not confined within it) and travelling upstream towards the nozzle (Tam & Hu 1989). For a supersonic jet, at any given set of jet-operating conditions this mode will be propogative only within a finite band of frequencies - referred to as the existence region of the mode. The lower bound of this frequency band, where the mode moves away from the sonic line describing the freestream sound waves, is referred to as the branch point (cut-on) and the upper bound as the saddle point (cut-off). This saddle point is formed between the  $k_p^-$  mode and a downstream-propagating duct-like mode ( $k^+$ ) (Towne *et al.* 2017). For frequencies above the saddle point the  $k_p^-$  mode becomes evanescent, whereas it is convectively neutral between the branch and saddle points.

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Recent interest in the  $k_p^-$  mode has been motivated through the study of aeroacoustic resonance. The feedback loop characterising a given form of resonance consists of four components (Edgington-Mitchell 2019). The first is a downstream-propagating disturbance, often taken to be the Kelvin-Helmholtz (KH) mode, to some point downstream of the nozzle. Second is an interaction converting it to an upstream-propagating disturbance, being the third component of resonance. This disturbance then travels back to the nozzle where, via another interaction, it then excites a new downstream-propagating disturbance, the last component, and so closes the resonance loop. The form of the upstream-propagating component was historically considered to be a free-stream acoustic wave (Powell 1953), however recent work has suggested that it is instead the  $k_p^-$  mode which acts as the upstream component to close the resonance loop. A range of cases that have considered the  $k_p^-$  mode to close resonance include; an impinging jet (Tam & Ahuja 1990), jet-edge interaction (Jordan et al. 2018), and screech for both single (Shen & Tam 2002; Gojon et al. 2018; Edgington-Mitchell et al. 2018; Mancinelli et al. 2021) and twin (Nogueira & Edgington-Mitchell 2021; Stavropoulos et al. 2022) round jets. For the case of screech, high-amplitude discrete-frequency acoustic tones present in non-ideally expanded jets (Raman 1999; Edgington-Mitchell 2019), the finite existence region of the  $k_p^-$  mode then also serves as part of an explanation for the cut-on and cut-off of the screech tones (Mancinelli et al. 2019; Stavropoulos et al. 2023). Recent work by Edgington-Mitchell et al. (2021), following the hypothesis put forth by Tam & Tanna (1982), has demonstrated how interactions between the KH mode and the shockcell structure can result in the creation of new waves, including the  $k_p^-$  mode. Later in Nogueira et al. (2022) it was shown that the KH interacts with both the primary and suboptimal shock-cell wavenumbers to give rise to the  $k_p^-$  mode for different screech tones. As the shock-cell structure exhibits variations in the axial direction (Harper-Bourne & Fisher 1974), sub-optimal wavenumbers appear when taking an axial Fourier transform and thus represent these variations. This was then generalised by Edgington-Mitchell et al. (2022) to explain the observed screech mode staging (Merle 1957; Powell et al. 1992) in a round single jet.

The introduction of a second jet introduces additional complexities to the flow, as indicated through measurements of inter-jet pressure exceeding twice that of the singlejet value (Seiner *et al.* 1988), along with the complex, and often intermittent, coupling behaviour observed (Raman *et al.* 2012; Bell *et al.* 2021; Wong *et al.* 2023). Two new parameters introduced by the addition of a second jet are the jet separation distance and the symmetry of the system about each plane. Prior applications of linear stability theory to the round twin-jet system have shown how these parameters affect the growth rate of the KH mode (Morris 1990) and the allowable coupling forms (Rodríguez *et al.* 2022). For the  $k_p^-$  mode (upstream component in resonance) these parameters also play a role as they have been seen to affect its existence region (Du 1993; Stavropoulos *et al.* 2023). However, there is not currently an explanation as to why this behaviour occurs for the  $k_p^-$  mode.

In this work linear stability models will be applied to the supersonic twin-jet case, for both planar and round geometries, to examine the behaviour of the  $k_p^-$  mode as a function of the added twin-jet parameters jet separation and symmetry. Through considering changes in frequency of the  $k_p^-$  mode branch and saddle points, and thus the existence region of the mode, along with their radial structure, an explanation for why these characteristics are dependent on jet separation and symmetry will be sought.

The paper is organised as follows. The formulations for the numerical models, vortexsheet and finite-thickness, utilised are outlined in §2. Results are shown in §3, with concluding remarks made in §4.

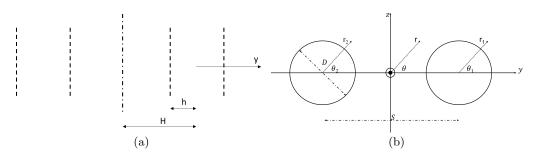


Figure 1: Setup of both the planar (a), and round (b) twin-jet geometries.

# 2. Mathematical models

### 2.1. Planar twin-jet vortex-sheet model

The planar twin-jet vortex-sheet model considered herein builds upon the planar singlejet model detailed in Martini *et al.* (2019). The planar jet is formed using two vortex sheets, each representing an infinitesimal-width shear layer across which both pressure and displacement are constant (Lessen *et al.* 1965; Michalke 1970; Morris 2010). To extend this to a planar twin-jet configuration, the symmetry line previously imposed at y = 0 for the single-jet case, is moved to a position of y = -H, the midpoint of the twinjet system, and no assumptions are made about the symmetry of the flow within each individual jet. This resultant configuration is illustrated in figure 1a. The two jets are separated by a total distance 2H and the length-scale used for non-dimensionalisation is the jet half-width h. Perturbations about the system of the form

$$\tilde{P} = P(y)e^{i(kx-\omega t)},\tag{2.1}$$

are considered where k is the wavenumber and  $\omega$  frequency. Following Martini *et al.* (2019) the form of the perturbed pressure amplitude P(y), referred to as the pressure eigenfunction, which in a given region takes the form

$$P(y) = C_a e^{\lambda_{i,o} y} + C_b e^{-\lambda_{i,o} y}.$$
(2.2)

The constants  $C_a$  and  $C_b$  in 2.2 are referred to as eigenfunction coefficients, and  $\lambda_{i,o}$  is

$$\lambda_i = \sqrt{k^2 - \frac{1}{T}(\omega - Mk)^2},$$
  
$$\lambda_0 = \sqrt{k^2 - \omega^2},$$
(2.3)

where M is the acoustic Mach number, and T the temperature ratio between jet and freestream. Boundary conditions imposed on the twin-jet system are, continuity of pressure and displacement across each vortex sheet, bounding of the solution as  $y \to \infty$ , and imposing the symmetry condition at the midpoint of the two jets (y = -H). This symmetry condition is the solution having either zero gradient (symmetric) or is zerovalued (anti-symmetric). This results in the matrix equation

$$\mathbf{A}(k)\boldsymbol{c} = \mathbf{0},\tag{2.4}$$

where c contains the eigenfunction coefficients. Further details on the matrix terms can be found in Appendix B. Setting the determinant of  $\boldsymbol{A}$  equal to zero forms the dispersion relation for the planar twin jet and is used to obtain k, the system eigenvalue, for a given set of jet parameters. Once a given k has been found, 2.4 can then be used to obtain the corresponding eigenfunction coefficients c.

For considerations of the single planar jet the dispersion relation given in Martini et al. (2019) is used,

$$tanh(\lambda_i)^{\pm 1} + \frac{1}{T}\left(1 - \frac{kM}{\omega}\right)^2\left(\frac{\lambda_o}{\lambda_i}\right) = 0, \qquad (2.5)$$

with the pressure eigenfunctions given by,

$$P(y) = \begin{cases} \frac{e^{\lambda_i} \pm e^{-\lambda_i}}{e^{-\lambda_o}} e^{-\lambda_o y}, & y \ge h \\ e^{\lambda_i y} \pm e^{-\lambda_i y}, & -h \le y \ge h \\ \frac{e^{-\lambda_i} \pm e^{\lambda_i}}{e^{-\lambda_o}} e^{\lambda_o y}, & y \le -h \end{cases}$$
(2.6)

where the  $\pm$  terms in 2.5 and 2.6 indicate the symmetric or anti-symmetric solution, about the jet centre, respectively. A further generalisation of the planar vortex-sheet model for a system of N jets is provided in Appendix D.

#### 2.2. Finite-thickness model

The finite-thickness model follows the formulation used previously for round twin-jet systems (Nogueira & Edgington-Mitchell 2021; Stavropoulos *et al.* 2023). The two jets, each of diameter D, are separated by a centre-to-centre distance S as illustrated in figure 1(b). Solutions for the twin-jet system are denoted as either, SS, SA, AS, or AA, where each letter denotes symmetry (S) or anti-symmetry(A) about the x - y and x - z planes respectively (Rodríguez *et al.* 2018). All parameters are non-dimensionalised by D, free-stream sound speed, and density. The generalised eigenvalue problem can be expressed, here in terms of pressure, in the form

$$\mathbf{L}\hat{P} = k\mathbf{R}\hat{P},\tag{2.7}$$

with  $\hat{P} = Pe^{i\mu\theta}$  and operators **L** and **R** functions of the mean flow, its derivatives, and flow variables  $\omega$ ,  $M_j$ , S, and the ratio of specific heats  $\gamma$ . Here  $\mu$  is the Floquet exponent resulting from the Floquet ansatz which is associated with the different symmetries of the flow (Nogueira & Edgington-Mitchell 2021),  $\mu = 0$  describes a solution that is symmetric about the x-z plane and  $\mu = 1$  is anti-symmetric about it. Equation 2.7 utilises a Fourier discretisation in azimuth and Chebyshev polynomials in radius (Trefethen 2000), with boundary conditions imposed following previous works (Nogueira & Edgington-Mitchell 2021), with the matrix operators detailled in Stavropoulos *et al.* (2023). A numerical mapping (Bayliss & Turkel 1992) is applied to ensure appropriate resolution in the shear layer of the jets. The sparsity of the system is exploited to further reduce computational cost. The mean flow uses a hyperbolic-tangent velocity profile (Michalke 1971) of the form

$$U(r) = M\left[0.5 + 0.5 \tanh\left(\left(\frac{R_j}{r} - \frac{r}{R_j}\right)\frac{1}{2\delta}\right)\right],\tag{2.8}$$

with  $R_j$  the ideally expanded jet radius and  $\delta$  used to characterise the shear-layer thickness. In each case, the mean temperature is obtained from 2.8 through the Crocco-Busemann relation. A twin-jet mean flow is constructed through the addition of two single-jet mean flows, following Rodríguez (2021). When considering instead an elliptical

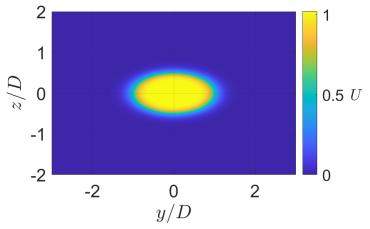


Figure 2: Sample elliptical jet mean flow, U, used for the finite-thickness model. Computed for  $M_j = 1.16$ , AR = 2, and  $\delta = 0.2$ .

geometry 2.8 is used with  $R_j = R_b$ , the boundary curve describing the ellipse

$$R_b = \frac{ab}{\sqrt{b^2 \cos^2(\theta) + a^2 \sin^2(\theta)}}.$$
(2.9)

Here b is the ellipse semi-minor axis, and a the semi-major axis as well as the length-scale used for normalisation. An example of a single elliptical jet mean flow using 2.9 and 2.8 is provided in figure 2, for an ideally expanded jet Mach number  $(M_j)$  of 1.16,  $\delta = 0.2$  and aspect ratio (AR) of 2.

# 3. Results

### 3.1. Planar twin jet

To aid in understanding the behaviour of a round twin-jet system a planar twin-jet system, as described in §2.1, is considered first. For two jets being brought together to the point of merging, the simplified geometry of the planar case allows for a more intuitive understanding of the result. As the planar jets merge they are expected to form a singular planar jet, with width twice that of the individual planar jets. The effect on the structure of the pressure eigenfunction as the two jets merge  $(H \rightarrow 1)$  is shown in figures 3 and 4 for both the symmetric and anti-symmetric solutions respectively. In each case the wavenumber of the  $k_p^{-}(0,2)$  mode is found through 2.4. Both the symmetric and anti-symmetric solutions exhibit coupled behaviour in the inter-jet region even at higher (H = 20) jet separations. The primary difference observed between the symmetric (figure 3) and anti-symmetric (figure 4) eigenfunctions is the enforced symmetry condition at the midpoint of the system, which is consistent with results seen for a round twin-jet system Stavropoulos et al. (2023). It is observed in both cases that as H decreases the eigenfunctions appear to approach a higher-order mode shape, signified by additional anti-nodes in the pressure eigenfunction when H = 1 (figure 3(f) and figure 4(f)). As such, the system reduces to that of a single planar jet with half-width 2h, referred to henceforth as the double-width jet. This higher-order mode the system reduces to for H = 1 is different depending on whether the symmetric or anti-symmetric solution is considered. In the symmetric case (figure 3) the amplitude at the midpoint between the jets increases with H before forming an anti-node. Conversely, the symmetry condition

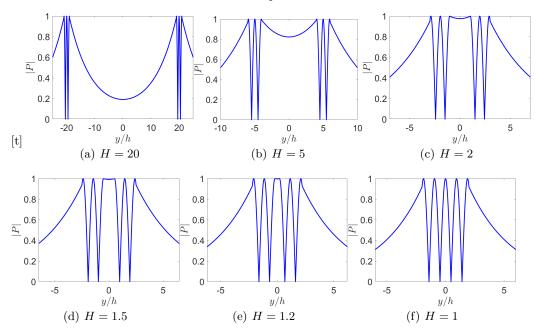


Figure 3: Variation in structure of the symmetric planar twin jet pressure eigenfunctions of the  $k_p^-$  (0,2) as the two jets merge  $(H \rightarrow 1)$ . Computed for,  $M_j = 1.16$ , St = 0.25and T computed through an isentropic relation. Eigenfunctions are normalised with the absolute value plotted.

for the anti-symmetric case forces a node to form at the centre (figure 4). This results in the anti-symmetric case converging to a mode of even higher order than the symmetric case.

A more direct comparison between the twin-jet system at H = 1 and double-width jet can be seen in figure 5 for both the symmetric and anti-symmetric eigenfunctions. The solution for the double-width jet is found using the dispersion relation for a single planar jet, 2.5, but solved at a St twice that of the twin-jet case, due to the present formulation normalising by jet half-width which then becomes 2h. For both the symmetric and antisymmetric case in figure 5 the twin-jet solution matches exactly with the double-width jet confirming that the converged mode for H = 1 is a single-jet mode. A consideration of the eigenfunction behaviour of a planar twin-jet system as  $H \rightarrow 1$  has identified key behaviours. When the planar twin-jet system merges it becomes equivalent to a single planar jet of twice the width. At this the point of merging (H = 1) the pressure eigenfunction converges to a higher-order mode. For the symmetric case, as the two jets merge, a mode that previously had 3 peaks on each isolated jet forms a mode with 5 peaks in the merged jet (H = 1). An equivalent mode for the anti-symmetric case forms a mode with 6 peaks, indicating the formation of a higher-order mode for this symmetry.

This convergence to the double-width jet solution of the twin jet as  $H \to 1$  can also be observed when considering the branch and saddle point frequencies of the  $k_p^-$  (0,2) mode. It has been observed previously that the existence region formed by these bounds is strongly dependent on jet separation for a round twin-jet system (Du 1993; Stavropoulos *et al.* 2023) and this is also seen to be the case for a planar twin-jet system. Figure 6 shows the change in value of the branch and saddle points for both the symmetric and

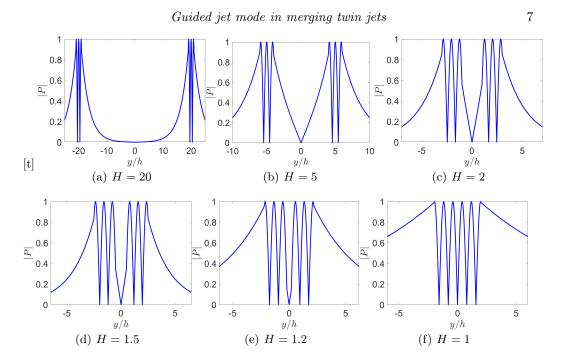


Figure 4: Variation in structure of the anti-symmetric planar twin jet pressure eigenfunctions of the  $k_p^-$  (0,2) mode as the two jets merge  $(H \rightarrow 1)$ . Shown for,  $M_j = 1.16$ , T computed through an isentropic relation, and St = 0.27, (a) and (b), 0.29, (c), and 0.3, (d)-(f). Eigenfunctions are normalised with the absolute value plotted.

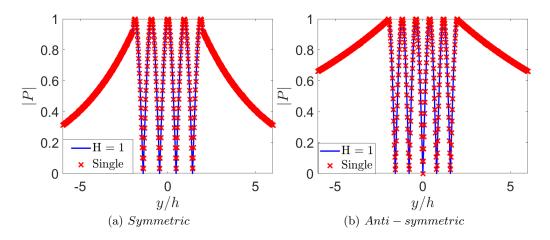


Figure 5: Eigenfunctions of the merged planar twin-jet system (H = 1) compared with those of the double-width single jet for both the symmetric solution, (a), and anti-symmetric solution (b). Shown for  $M_j = 1.16$ , and T computed through an isentropic relation. St values are 0.25 and 0.5 for (a), and 0.3 and 0.6 for (b), normalising using the twin and double-width jet length scales respectively.

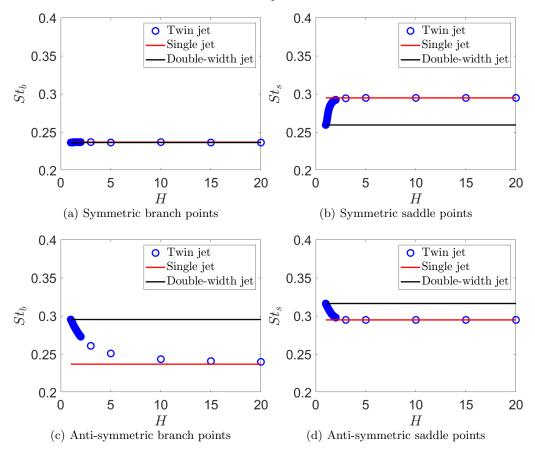


Figure 6: Branch and saddle points for the symmetric and anti-symmetric planar twin jet as a function of jet spacing H at  $M_j = 1.16$  and T from an isentropic relation. Present also in each figure is the corresponding value of the symmetric single planar jet. St values converged to at H = 1 correspond to half those of the double-width jet.

anti-symmetric case. For both symmetries the branch and saddle point values are seen to begin (large H) from the value of the symmetric planar single jet. This is not unexpected when considering figure 3 and figure 4, where it can be observed that for large H the twinjet eigenfunctions resemble two symmetric planar jets, with this also seen mathematically in Appendix B. As  $H \to 1$  figure 6 shows the twinjet branch and saddle points approach new values. The exception to this being figure 6(a), the symmetric solution saddle point, which remains virtually unchanged for all H. These new values the branch and saddle points converge to are all related to the double-width jet, being exactly half the values of the double-width jet branch and saddle points. Recalling that an equivalent double-width jet has St twice that of a planar twin jet, then figure 6 is indicating that when the twinjet system merges (H = 1) the branch and saddle points change to match those of the higher-order mode the system has now converged to.

The entire existence region of the  $k_p^-$  (0,2) mode is compared in figure 7 between the twin-jet system and the double-width jet, with the twin-jet values scaled to match the double-width jet normalisation. These are plotted for  $M_j = 1.16$ , H = 1 and an isentropic temperature ratio. Both twin and double-width jet are seen to exhibit exact agreement in

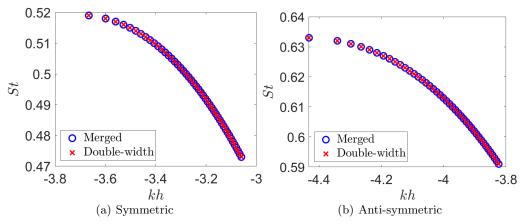


Figure 7: Comparison between the  $k_p^-(0,2)$  existence region between the planar twin jet (H = 1) and double-width jet for symmetric, (a), and anti-symmetric, (b). Computed for  $M_j$  1.16 and T from an isentropic relation. The twin-jet eigenvalues have been scaled by a factor of two to adjust them to the double-width jet normalisation.

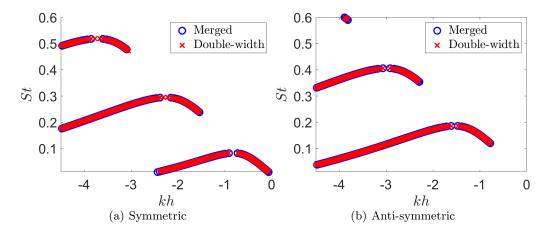


Figure 8: Comparison of (kh, St) eigenvalue pairs between the planar twin jet (H = 1) and double-width jet for symmetric, (a), and anti-symmetric, (b). Computed for  $M_j$  1.16 and T from an isentropic relation. The twin-jet eigenvalues have been scaled by a factor of two to adjust them to the double-width jet normalisation.

the symmetric, figure 7(a), and anti-symmetric, figure 7(b), cases. This agreement is to be expected as the twin-jet system is forced to match the double-width jet as  $H \to 1$ , a criterion imposed by the pressure eigenfunction behaviour. This constraint then forces the branch and saddle points (and consequently, the existence region) of the  $k_p^-$  (0,2) mode to align with the higher-order mode of the double-width jet the system has converged to. A change in branch or saddle point will only not occur if the value already corresponds to that of the double-width jet, as seen for the symmetric branch point in figure 6(a). A larger range in St is considered in figure 8, for the same jet parameters as in figure 7. This demonstrates that the results observed thus far for the  $k_p^-$  (0,2) mode in a planar jet, hold for other modes also. These modes also converge to the double-width jet solution as

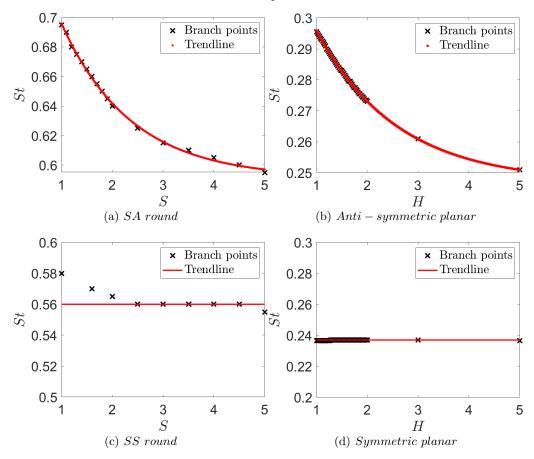


Figure 9: Dependence of the  $k_p^-$  (0, 2) branch point with jet separation for both the SA (a) and SS (c) round twin jet, and the anti-symmetric (b) and symmetric (d) planar twin jet. Computed for  $M_j = 1.16$  and  $\delta = 0.2$  (round twin jet). Overlaid on (a) and (b) is an exponential trendline, with a constant trendline on (c) and (d).

 $H \to 1$ , and will experience changes in their branch and saddle point values with H to align with the double-width jet solution. This explanation for the  $k_p^-$  (0,2) mode branch and saddle point behaviour in a planar twin-jet system now motivates the investigation of the round twin-jet system.

#### 3.2. Round twin jet

For the round twin-jet system it has been seen previously that the SA symmetry  $k_p^-$  (0,2) mode, exhibits a strong dependence on jet separation (Stavropoulos *et al.* 2023). The behaviour of both the SS and SA symmetry round twin-jet branch points are compared to those of the symmetric and anti-symmetric planar twin-jet system in figure 2.7. Results for the round twin-jet system are obtained using 2.7 and 2.8 with  $\delta = 0.2$ . In the SA (figure 9(a)) and anti-symmetric (figure 9(b)) systems the branch points both exhibit a strong exponential trend as the jets are brought together. A similar agreement in trends can be seen between the SS (figure 9(c)) and symmetric (figure 9(d)) branch points. Here the branch points exhibit a constant trend with jet separation and only at very low jet separations is there a change (being at lower jet separation than

previous considerations of the SS  $k_p^-(0,2)$  mode Du (1993); Stavropoulos et al. (2023)) which is greater for the SS round twin jet than the symmetric planar twin jet. The similarity in trends of figure 9 suggests that the round twin-jet system is also converging to an equivalent geometry when S = 1 driving this change in branch point frequency. The behaviour of the round twin-jet pressure eigenfunctions can then also be considered, as  $S \to 1$ . These are presented in figure 10 for the SA symmetry at  $M_i = 1.16$  and  $\delta = 0.2$ . As the two round jets are brought together the SA symmetry condition enforced at the system midpoint becomes an additional node as part of a higher-order mode. This is the same behaviour as was observed previously for the anti-symmetric planar twin-jet system (figure 4). The eigenfunction behaviour of the SS symmetry can also be considered and is illustrated in figure 11. Here the SS symmetry condition enforced at the system midpoint becomes an anti-node and the twin-jet system reduces to a higher-order mode, again in-line with observations of the planar twin jet (figure 5). Comparing the SS and SA eigenfunctions at S = 1 (figures 10(d) and 11(d)) the same difference as previously identified for the planar twin-jet system  $(\S3.1)$  is observed, the SA solution converges to an even higher-order mode than the SS solution. Figures 10 and 11 further indicate that the round twin-system is converging to some equivalent geometry.

The geometry of a round twin-jet system does not lend itself to an obvious equivalent geometry when the two jets merge, unlike the planar twin-jet system discussed previously (§3.1). Instead a comparison will be made with ellipses of differing AR. The two ARs considered are 1.5 and 2, with each shown superimposed over the S = 1 round twin-jet system in figure 12. The AR 1.5 case (figure 12(a)) provides a match with the outer edges of the two jets, whilst the AR 2 case (figure 12(b)) is an ellipse of equal area to the twin-jet system. The S = 1 SA round twin-jet existence region is compared to (k, St)pairs computed for the elliptical jet, using 2.9 to define the mean flow boundary, in figure 13. Here  $M_i = 1.16$  and  $\delta = 0.2$ , with  $\mu = 0, 1$  for the ellipse and S = 1 for the twin jet. In figure 13 both the St and k values for the round twin-jet system are scaled by a factor of  $\sqrt{\frac{AR}{2}}$  to use the same normalisation as the ellipse. It can be seen that of the ARs considered, the merged round twin-jet system more closely resembles the AR 2 ellipse (figure 13 (b) and (d)). This is evident from the close agreement observed at the region near the branch point, and the similar behaviour of the twin jet and elliptical jet mode branches. Conversely in the AR 1.5 case (figure 13(a) and (c)) the existence regions for the elliptical and round twin jet do not show alignment. Note that this is not implying that a round twin-jet system converges to a perfect ellipse, but that an AR 2 ellipse could be considered a close approximation to the resultant converged geometry. Considering now just the AR 2 case, comparisons between the pressure eigenfunctions for the ellipse and round twin jet can be made to further consider the similarities. These are given in figure 14 at the branch point, for the radial profile along the y axis (figures 14(a) and (b), and the pressure contours (figure 14(b)-(d)). In figure 14(a) the shape of the eigenfunctions agree well between the elliptical and twin-jet solutions. The difference between the  $\mu = 1$  ellipse and SA round twin jet is in the eigenfunction amplitudes, with the first and third nodes having greater magnitude for the ellipse than the round twin jet. When considering instead the  $\mu = 0$  ellipse and SS round twin jet (figure 14(b)) a greater degree of difference is observed between the two eigenfunctions. For y/D > 1 the elliptical eigenfunction decays at a slower rate than the twin-jet eigenfunction, and at y/D = 0 there is disagreement seen between the two. Comparing the pressure contours for the  $\mu = 1$  ellipse and SA round twin jet (figures 14(c) and (d)) indicates a similar location for the maximum pressure with differences in the contours occurring outside of this region. This is similarly observed when comparing the  $\mu = 0$  ellipse and SS round

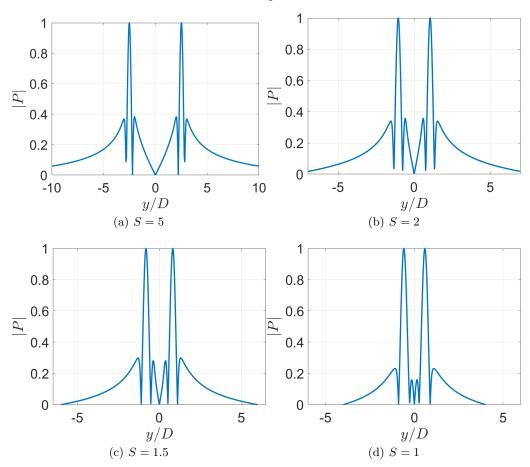


Figure 10: Variation in structure of the SA round twin jet pressure eigenfunctions of the  $k_p^-$  (0,2) mode as the two jets merge ( $S \rightarrow 1$ ). Computed for,  $M_j = 1.16$  and  $\delta = 0.2$ . Values of St are 0.595 (a), 0.64 (b), 0.665 (c), and 0.695 (d). Eigenfunctions are normalised with the absolute value plotted.

twin jet (figures 14(e) and (f)). In both cases greater differences between the elliptical and twin-jet contours are seen near to the z axis (larger values of  $\theta$  as described by figure 1(b)). This result is consistent with comparisons of mean flow velocity profiles between the ellipse and S = 1 round twin jet (see Appendix C), where it observed that differences between the velocity profiles occur for large values of  $\theta$ . Trends in the pressure eigenfunction radial profiles, from branch point to saddle point are compared in figure 15. For the SA round twin jet (figure 15(a)) and  $\mu = 1$  ellipse (figure 15(b)) both are seen to display similar behaviour in the pressure eigenfunction as St increases towards the saddle point value. Differences between the two geometries are observed in the pressure eigenfunction amplitudes and the profile at the saddle point. When considering the SS round twin jet (figure 15(c)) and  $\mu = 0$  ellipse (figure 15(d)) similar agreement between the geometries is observed, however at y/D = 0 the SS twin jet increases in amplitude as St increases to a larger extent than the  $\mu = 0$  ellipse does. Combined figures 14 and 15, like figure 13, indicate that the equivalent geometry a round twin-jet system merges to is close in shape to an AR 2 ellipse.

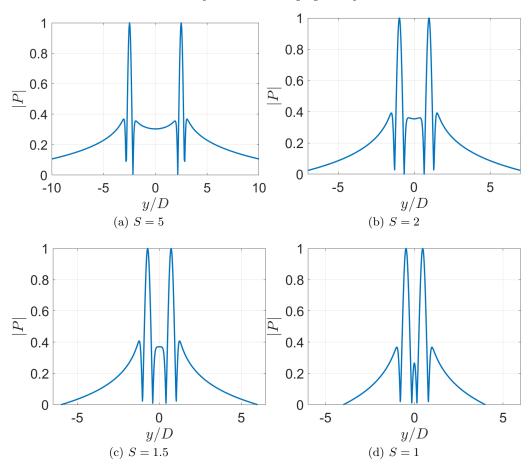


Figure 11: Variation in structure of the SS round twin jet pressure eigenfunctions of the  $k_p^-$  (0,2) mode as the two jets merge  $(S \to 1)$ . Computed for,  $M_j = 1.16$  and  $\delta = 0.2$ . Values of St are 0.555 (a), 0.565 (b), 0.57 (c), and 0.58 (d). Eigenfunctions are normalised with the absolute value plotted.

# 4. Conclusion

This work sought to explain the strong observed dependence of the  $k_p^-$  (0,2) with jet separation in a twin-jet system. A planar twin-jet model was first considered due to the simplified geometry it provided. The model demonstrated that as the two jets are brought together a higher-order mode is formed, for a single-jet system of twice the jet width. This then imposes a constraint on the branch and saddle point frequencies of the  $k_p^-$  (0,2) to match those of the higher-order mode branch. To meet this constraint the values must then change with jet separation, leading to the previous observations of jet separation dependence. The symmetry condition of the system, symmetric or anti-symmetric, influences the shape of the higher-order mode that is formed. An antisymmetric system leads to a greater order mode than a symmetric system, and so results in a greater change in branch and saddle point values. The same behaviour was observed also for the round twin-jet system which converges to an equivalent geometry similar to an AR 2 ellipse. A higher-order mode similar to that of an elliptical jet was formed as the jets were brought together, with the existence region of the  $k_p^-$  (0,2) mode then

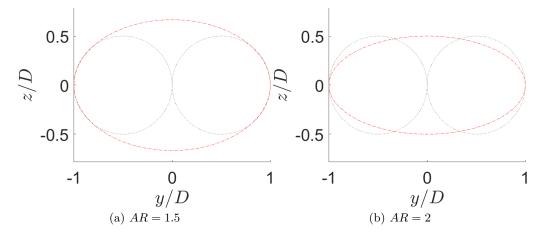


Figure 12: Geometric comparison between the S = 1 round twin-jet system and an elliptical jet of AR 1.5 (a), and 2 (b).

constrained to match. As this  $k_p^-$  (0,2) mode behaviour is due to a geometric effect, in converging to an equivalent single-jet geometry as the individual jets merge, such behaviour will be observed in any twin-jet system.

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# Appendix A. Variation with jet parameters

This work has focused on the behaviour of the  $k_p^-$  (0,2) mode with S and solution symmetry. Here consideration is made for how other jet parameters ( $M_j$  and T) affect the branch point St value for a round twin-jet system. In each case the value considered will be  $St_r$  which is defined as the ratio between the round twin-jet St value and the equivalent round single-jet St value for the same jet conditions. Calculations here use the round twin-jet vortex-sheet model (Morris 1990; Du 1993; Stavropoulos *et al.* 2022), as the lower computational cost facilitates a wider parameter space exploration. The dispersion relation for the round twin jet is

$$\sum_{m=0}^{\infty} A_m[a_{nn}\delta_{mn} \pm (-1)^m c_{mn}] = 0,$$
 (A 1)

with

$$a_{nn} = \frac{1}{(1 - \frac{kM}{\omega})^2} - \frac{1}{T} \frac{\lambda_o}{\lambda_i} \frac{K_n'(\frac{D_j \lambda_0}{2}) I_n(\frac{D_j \lambda_i}{2})}{I_n'(\frac{D_j \lambda_0}{2}) K_n(\frac{D_j \lambda_0}{2})},$$
(A 2)

and

$$c_{mn} = (-1)^n \epsilon_n [K_{m-n}(\lambda_0 S) \pm K_{m+n}(\lambda_0 S)] \left[ \frac{I_n(\frac{D_j \lambda_0}{2})}{K_n(\frac{D_j \lambda_0}{2})} \frac{1}{(1-\frac{kM}{\omega})^2} - \frac{1}{T} \frac{\lambda_o}{\lambda_i} \frac{I_n(\frac{D_j \lambda_i}{2}) I'_n(\frac{D_j \lambda_0}{2})}{K_n(\frac{D_j \lambda_0}{2}) I'_n(\frac{D_j \lambda_0}{2})} \right]$$
(A 3)

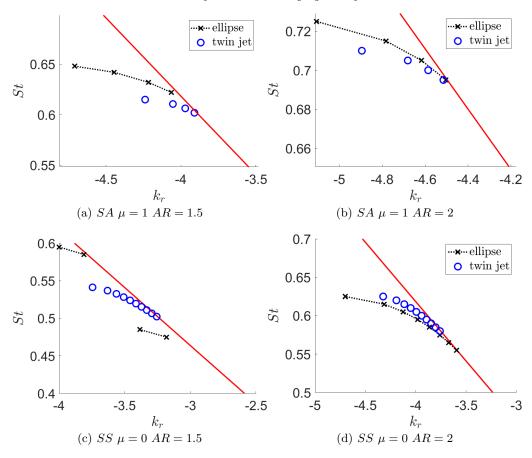


Figure 13: Comparison of the existence regions of the SS and SA S = 1 round twin-jet  $k_p^-$  (0,2) mode and the  $\mu = 0$ , 1 elliptical jet mode branch it lies closest to. Computed for  $M_j = 1.16$ ,  $\delta = 0.2$ , and AR = 1.5 (a), (c) and 2 (b), (d). Values of St for the twin-jet system are scaled to match the normalisation of the elliptical St. Included also is the sonic line representing the free-stream acoustic waves in red.

Here  $I_n$  and  $K_n$  are the modified Bessel functions of first and second kind,  $\delta_{mn}$  is the Kronecker delta,  $\epsilon_n = 0.5$  for n = 0 and  $\epsilon_n = 1$  otherwise, m the azimuthal mode number, and the  $\pm$  terms in A 1 and A 3 describe the solution being symmetric (+) or anti-symmetric (-) about the x - y and x - z planes respectively. All other parameters are as described previously for the planar vortex-sheet model (§2.1). Using A 1, contours describing the change in  $St_r$  across  $M_j$  are presented for the SA solution symmetry in figure 16 for different values of the temperature ratio T. Across the values of T considered the same trend is observed. The SA branch point Sts are of larger value than the single jet at lower S, and move towards the single-jet value as S increases. As T is increased it results in the twin-jet values approaching those of the single jet sooner with increasing S. It is only in figure 16(a) that a dependence on  $M_j$  can be seen. However this result uses an isentropic temperature relation for T, which is dependent on  $M_j$ . As such it can be stated that  $M_j$  does not influence the behaviour of the SA symmetry twin-jet branch points relative to those of the single jet. A final comparison is shown in figure 17 for all four solution symmetries of a twin-jet system, SS, SA, AS and AA. As the AS and

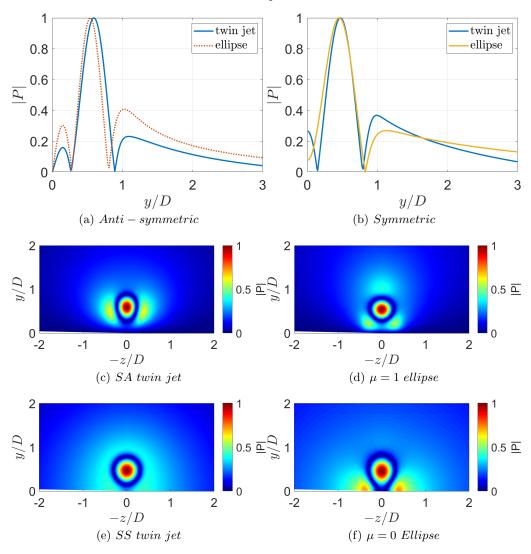


Figure 14: Pressure eigenfunctions of the  $\mu = 0$  and 1 ellipses, and the SS and SA S = 1 round twin jet computed at the branch point. Shown for the radial profile (a) and (b), anti-symmetric contours (c) and (d), and symmetric contours (e) and (f). Computed for  $M_j = 1.16$ , and  $\delta = 0.2$ . Eigenfunctions are normalised with the absolute value plotted.

AA symmetries cannot support axisymmetric modes, by construction, the behaviour of the  $k_p^-$  (1, 1) mode will be considered instead. Comparing figure 17(b) with figure 16(a) highlights that the (1, 1) mode reaches the single-jet value sooner with increasing S than the (0, 2) mode. Indicating that as the round twin-jet system merges ( $S \rightarrow 1$ ) the different modes of the jet all converge to higher-order modes at different rates. Comparing the behaviours of the different symmetries it is seen that the SS and AS symmetries (figure 17(a) and (c)) and the SA and AA symmetries (figure 17(b) and (d)) display similar behaviour. The SS and AS symmetries branch point values decrease from the singlejet value as S decreases, whilst the SA and AA symmetry branch points increase in value. The difference between the two groupings of symmetry is their symmetry or anti-

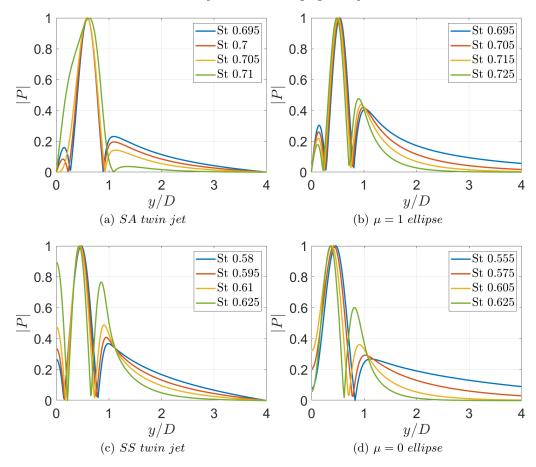


Figure 15: Comparison of the pressure eigenfunction behaviour between the S = 1 round twin jet, (a) and (c), and the AR 2 ellipse, (b) and (d), when moving from the branch to saddle point. Computed for  $M_j = 1.16$ ,  $\delta = 0.2$ , and AR = 2. Eigenfunctions are normalised with the absolute value plotted along the y axis.

symmetry about the x-z plane. In §3.2 it was observed that the SS and SA symmetries converge to a geometry similar to an AR 2 ellipse with symmetry or anti-symmetry about the x-z plane. Hence, figure 17 is indicating that the higher-order mode the  $k_p^-$  (1, 1) mode converges to exists at a higher St range for the equivalent geometry the SA and AA symmetries converge to, than for the equivalent geometry of the merged SS and AS symmetries.

## Appendix B. Matrix terms for the planar model

In the planar twin-jet model the flow can be divided into three distinct regions. These are; the region between the jets (-H < y < h), the region inside the jet (-h < y < h), and the region away from the other jet (y > h). Using 2.2 the pressure in each of the

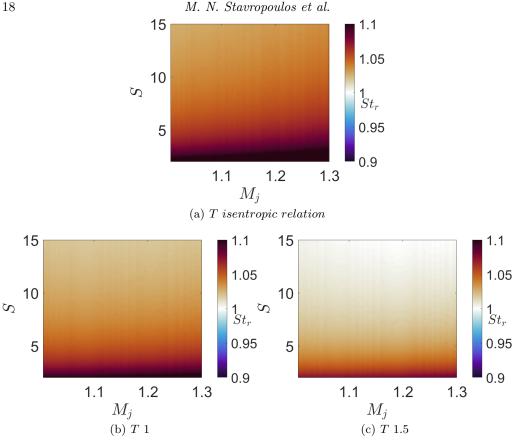


Figure 16: Variation in the ratio of the SA round twin-jet  $k_p^-$  (0,2) branch point and the single-jet equivalent, across S and  $M_j$ . Computed for T using an isentropic relation (a), T = 1 (b), and T = 1.5 (c).

regions can be written as

$$P(y) = C_1 e^{\lambda_o y} + C_2 e^{-\lambda_o y} - H < y < -h,$$
  

$$P(y) = C_3 e^{\lambda_i y} + C_4 e^{-\lambda_i y} -h < y < h,$$
  

$$P(y) = C_5 e^{\lambda_o y} + C_6 e^{-\lambda_o y} y > h.$$
(B1)

The requirement for the pressure to be bounded dictates that  $C_5$  must be zero. Imposing the symmetry boundary condition at y = -H yields a relation between  $C_1$  and  $C_2$ , allowing the pressure in the inter-jet region to be re-written as

$$P(y) = C_1 \left( e^{\lambda_0 y} \pm e^{-2H\lambda_0} e^{-\lambda_0 y} \right), \tag{B2}$$

where it can be noted that for sufficiently large H the single-jet solution is recovered. Applying this to B1 yields the eigenvalue problem described by 2.4 where,

$$\boldsymbol{A} = \begin{bmatrix} e^{-\lambda_o} \pm e^{-2H\lambda_0} e^{\lambda_o} & -e^{-\lambda_i} & -e^{\lambda_i} & 0\\ \frac{\lambda_o}{\omega^2} \left( e^{-\lambda_o} \mp e^{-2H\lambda_0} e^{\lambda_o} \right) & \frac{-\lambda_i e^{-\lambda_i}}{\frac{1}{T} (kM - \omega)^2} & \frac{\lambda_i e^{\lambda_i}}{\frac{1}{T} (kM - \omega)^2} & 0\\ 0 & -e^{\lambda_i} & -e^{-\lambda_i} & e^{-\lambda_0}\\ 0 & \frac{\lambda_i e^{\lambda_i}}{\frac{1}{T} (kM - \omega)^2} & \frac{-\lambda_i e^{-\lambda_i}}{\frac{1}{T} (kM - \omega)^2} & \frac{\lambda_0}{\omega^2} e^{-\lambda_0} \end{bmatrix}, \quad (B3)$$

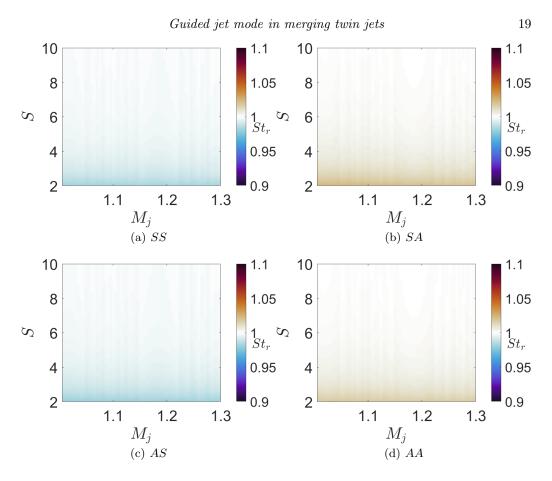


Figure 17: Variation in the ratio of the round twin-jet  $k_p^-$  (1,1) branch point and the single-jet equivalent, across S and  $M_j$ . Computed using an isentropic relation for T and for SS (a), SA (b), AS (c), and AA (d) solution symmetry.

and

$$\boldsymbol{c} = \begin{bmatrix} C_1 \\ C_3 \\ C_4 \\ C_6 \end{bmatrix}. \tag{B4}$$

# Appendix C. Comparison of velocity profiles

Additional detail is provided on the differences between the elliptical jet mean flow and the merged round twin-jet mean flow. Both mean flows are illustrated in figure 18 for the elliptical (a), and round twin jet (b) respectively. These are computed for  $M_j =$ 1.16,  $\delta = 0.2$ , AR = 2 (ellipse), and S = 1 (round twin jet). A qualitative view of figure 18 indicates that the two mean flows are quite different, particularly in their respective behaviour close to the z axis. A more quantitative comparison is made in figure 19 where the velocity profiles are compared along multiple angles,  $\theta$ , measured from the y axis (see figure 1(b)). For lower  $\theta$  (figure 19(a)-(d)) there is strong agreement observed between the two mean flows. It is only at larger  $\theta$  (figure 19(e) and (f)) that the two mean flows display noticeable difference. As such, this provides a strong justification for considering M. N. Stavropoulos et al.

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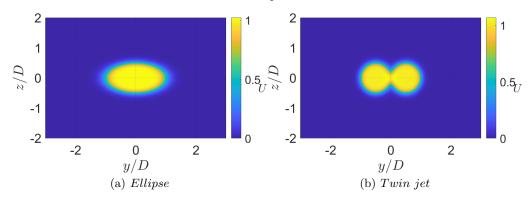


Figure 18: Visual comparison of the mean flows for an AR 2 ellipse, (a), and S = 1 twin jet, (b). Computed for  $M_j = 1.16$  and  $\delta = 0.2$ 

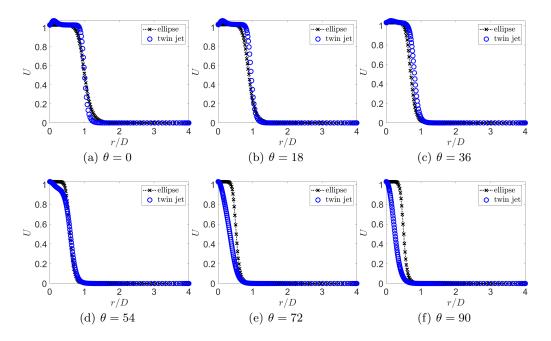


Figure 19: Comparison of mean flow axial velocity profiles between the AR 2 ellipse and S = 1 twin jet. Computed for  $M_j = 1.16$ ,  $\delta = 0.2$  at  $\theta$  of 0, (a), 18, (b), 36, (c), 54, (d), 72, (e), and 90, (f), all measured from the positive y axis.

an AR 2 ellipse as a substitute for the equivalent geometry of a merged round twin-jet system.

# Appendix D. Formulation for an N-jet planar system

In this work a planar twin-jet vortex-sheet model was described extending the planar single-jet vortex-sheet model previously considered (Martini *et al.* 2019). Here the formulation is generalised even further for a system of n planar jets each separated by a distance 2H, where  $n \ge 1$ . In a system of n jets each jet is described using 2 vortex



Figure 20: Set-up of the planar n-jet system for both an even, (a), and odd, (b), number of jets.

sheets, one for each jet boundary, resulting in a total of 2n vortex sheets. As was done for the twin planar jet (§2.1) the system of n jets will be divided in two with either a symmetric or anti-symmetric condition applied at the midpoint, leaving only n vortex sheets to consider. This set-up is illustrated in figure 20. To begin, the formulation for a symmetric solution is considered (figure 20(a)). The n vortex sheets result in n + 1 flow regions. These regions may be inside or outside of a jet and have a general form for the perturbed pressure amplitudes following 2.2, where a < b. This results in 2n+2 unknown coefficients, requiring the same number of boundary conditions to solve. Two boundary conditions are obtained through applying the symmetry condition at y = -H, and imposing the solution to be bounded as  $y \to \infty$ . The remaining 2n boundary conditions arise from applying continuity of pressure and displacement across each of the n vortex sheets. Each value  $A_{uv}$  of  $\mathbf{A}$ , in 2.4, is defined as the term multiplying the coefficient  $C_v$ as follows,

$$e^{-\lambda_o H} C_1 \mp e^{\lambda_o H} C_2 = 0, \tag{D1}$$

for u = 1,

$$e^{\lambda_o(\frac{u-2}{4}(2H)-1)}C_{v-1} + e^{-\lambda_o(\frac{u-2}{4}(2H)-1)}C_v - e^{\lambda_i(\frac{u-2}{4}(2H)-1)}C_{v+1} - e^{-\lambda_i(\frac{u-2}{4}(2H)-1)}C_{v+2} = 0, \quad (D\,2)$$

for even u and odd  $\frac{u}{2}$ ,

$$\frac{\lambda_o}{\omega^2} e^{\lambda_o (\frac{u-3}{4}(2H)-1)} C_{v-2} - \frac{\lambda_o}{\omega^2} e^{-\lambda_o (\frac{u-3}{4}(2H)-1)} C_{v-1} - \frac{\lambda_i}{\frac{1}{T}(kM-\omega^2)} e^{\lambda_i (\frac{u-3}{4}(2H)-1)} C_v + \frac{\lambda_i}{\frac{1}{T}(kM-\omega^2)} e^{-\lambda_i (\frac{u-3}{4}(2H)-1)} C_{v+1} = 0 \quad (D3)$$

for odd u and odd  $\frac{u-1}{2}$ ,

$$e^{\lambda_{i}(\frac{u-4}{4}(2H)+1)}C_{v-1} + e^{-\lambda_{i}(\frac{u-4}{4}(2H)+1)}C_{v} - e^{\lambda_{0}(\frac{u-4}{4}(2H)+1)}C_{v+1} - e^{-\lambda_{0}(\frac{u-4}{4}(2H)+1)}C_{v+2} = 0 \quad (D4)$$

for even u and even  $\frac{u}{2}$ ,

$$-\frac{\lambda_{i}}{\frac{1}{T}(kM-\omega^{2})}e^{\lambda_{i}(\frac{u-5}{4}(2H)+1)}C_{v-2} + \frac{\lambda_{i}}{\frac{1}{T}(kM-\omega^{2})}e^{-\lambda_{i}(\frac{u-5}{4}(2H)+1)}C_{v-1} + \frac{\lambda_{o}}{\omega^{2}}e^{\lambda_{o}(\frac{u-5}{4}(2H)+1)}C_{v} - \frac{\lambda_{o}}{\omega^{2}}e^{-\lambda_{o}(\frac{u-5}{4}(2H)+1)}C_{v+1} = 0 \quad (D5)$$

for odd u and even  $\frac{u-1}{2}$ ,

$$C_{2n+1} = 0, (D 6)$$

for u = 2n + 2. The  $\mp$  term in D1 refers to a symmetric or anti-symmetric solution respectively. Equations D2 and D4 describe continuity of displacement whilst D3 and D5 describe continuity of pressure. In D2 and D3 the equations describe moving from a region outside of the jets to a region inside a jet, whilst D4 and D5 describing moving from within a jet to outside of it. Factors involving u and 2H in each of the exponential terms describe the location of the vortex sheet, along the y axis, where that boundary condition is applied. In this way 2.4 can then be built and subsequently solved to compute wavenumbers, k, for an n-planar jet system. For odd values of n the midpoint of the system lies through the middle of a jet (figure 20(b)). This changes the locations of both the symmetry line and vortex sheets forming a new set of equations,

$$C_1 \mp C_2 = 0, \tag{D7}$$

for u = 1,

$$e^{\lambda_o(\frac{u-2}{4}(2H)+1)}C_{v+1} + e^{-\lambda_o(\frac{u-2}{4}(2H)+1)}C_{v+2} - e^{\lambda_i(\frac{u-2}{4}(2H)+1)}C_{v-1} - e^{-\lambda_i(\frac{u-2}{4}(2H)+1)}C_v = 0, \quad (D\,8)$$

for even u and odd  $\frac{u}{2}$ ,

$$\frac{\lambda_o}{\omega^2} e^{\lambda_o(\frac{u-3}{4}(2H)+1)} C_v - \frac{\lambda_o}{\omega^2} e^{-\lambda_o(\frac{u-3}{4}(2H)+1)} C_{v+1} - \frac{\lambda_i}{\frac{1}{T}(kM-\omega^2)} e^{\lambda_i(\frac{u-3}{4}(2H)+1)} C_{v-2} + \frac{\lambda_i}{\frac{1}{T}(kM-\omega^2)} e^{-\lambda_i(\frac{u-3}{4}(2H)+1)} C_{v-1} = 0 \quad (D9)$$

for odd u and odd  $\frac{u-1}{2}$ ,

$$e^{\lambda_{i}(\frac{u}{4}(2H)+1)}C_{v+1} + e^{-\lambda_{i}(\frac{u}{4}(2H)-1)}C_{v+2} - e^{\lambda_{0}(\frac{u}{4}(2H)+1)}C_{v-1} - e^{-\lambda_{0}(\frac{u}{4}(2H)-1)}C_{v} = 0 \quad (D\,10)$$

for even u and even  $\frac{u}{2}$ ,

$$-\frac{\lambda_{i}}{\frac{1}{T}(kM-\omega^{2})}e^{\lambda_{i}(\frac{u-1}{4}(2H)-1)}C_{v} + \frac{\lambda_{i}}{\frac{1}{T}(kM-\omega^{2})}e^{-\lambda_{i}(\frac{u-1}{4}(2H)-1)}C_{v+1} + \frac{\lambda_{o}}{\omega^{2}}e^{\lambda_{o}(\frac{u-1}{4}(2H)-1)}C_{v-2} - \frac{\lambda_{o}}{\omega^{2}}e^{-\lambda_{o}(\frac{u-1}{4}(2H)-1)}C_{v-1} = 0 \quad (D\,11)$$

for odd u and even  $\frac{u-1}{2}$ ,

$$C_{2n+1} = 0,$$
 (D 12)

for u = 2n + 2.

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