

Somatosensory-based tongue response to tongue stretch perturbation during steady state vowel production: EMG data and biomechanical modeling

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Somatosensory-based tongue response to tongue stretch perturbation during steady state vowel production: EMG data and biomechanical modeling <u> gipsa</u>-lab

2 mm

(Ito et al., 2020

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TB

J

time [s]

PTB

[Hz]

Introduction

Tongue posture can be controlled using on-line sensory feedback for the stabilization of produced speech sounds. Although reflex mechanisms such as stretch reflex have been known to be involved in neural feedback control for the limb system, previous studies have been failed to provide evidence for any short-latency reflex in the human tongue (Bratzlavsky and van der Ecken 1974, Neilson et al., 1979). Reflex resp. Passive resp.

In our behavioral study using tongue-stretch perturbation, a relatively quick compensatory response (< 130 ms) was found for tongue posture stabilization in vowel production, which might be driven by short-latency reflex mechanisms (Ito et al. 2020).

To further investigate this idea, this study aims to show neurophysiological evidence for reflex in the tongue during vowel production by the recording of tongue muscle activity.

We examined

- 1) whether the tongue EMG showed an increase with short latency in response to the tongue perturbation during speech production.
- 2) whether the observed response is due to an artifact by comparing with the resting task.
- 3) whether the observed response can be voluntarily modulated.
- 4) whether the observed response can be task-specific.

Method



2. Non-speech task (N-Sp): Produce the muscle activation of the tongue at the same level of the one in the speech task by monitoring filtered muscle activation



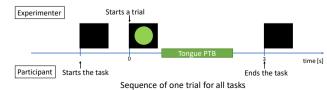
Sequence of trials with tongue perturbation

Session 2: Voluntarily reaction task (VR)

- Produce the vowel /i/ as in the speech task
- Produce a maximum muscle contraction when the perturbation was perceived

Session 3: Vowel production task (No tongue perturbation)

- Sustain the vowels /i/, /e/, /ε/, /a/ and /u/ in pseudo-randomized order
- Recorded five productions in each vowel



Data analysis:

- · EMG data was filtered by 30-2000 Hz band-pass filter, rectified and smoothed
- · All data was aligned at the perturbation onset.
- · Amplitude was calculated using 10 ms temporal window (Bk, R1, R2 and R3).

Results

Force

Experimental setup:

PC with EMG amp. DATA Recording

Tongue perturbation

EMG Signal

Electromyographic recording (EMG)

electrodes (Ishiwata et al. 1997)

OOS, OOI and Masseter: bipolar surface recording

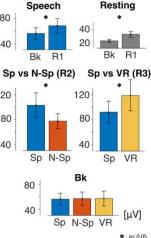
1 N of force in stepwise shape for 1 [s]

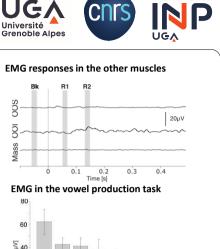
· Applied in the randomly selected trials

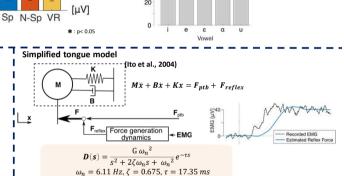
Reflex responses in response to the tongue perturbation R2 R1 80 120. 40 100 [JN] 120 80 EMG 80 Speech 60 NonSpeech 40 Voluntarily Reaction Resting 40 20 04 0.2 0 time [s]

Simulations: 3D tongue model (Calka et al., 2023)

Orbicularis







Summary

- A reflex response was clearly induced in response to the tongue perturbation.
- The response latency in the resting task was similar to that of the main reflex response, suggesting no evidence of a short-latency reflex associated with mono-synaptic reflex.
- The peak response in the non-speech task was smaller than in the speech task, suggesting that the reflex gain was specifically modulated for speech task.
- · Using the recorded EMG response, the observed displacement change was successfully reproduced through mathematical simulation.

Reflex mechanism contributes to the compensatory mechanism of the tongue posture stabilization for speech production.

Acknowledgement

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Tongue muscle: unipolar recording using intraoral surface

Passive response

0.38 0.4

Time (s)

0 3/ 0.36

Robotic device

Placement of surface electrode on the tongue muscle





0.42 0 44

Surface of the tongue