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Nonadiabatic Coupling in Trajectory Surface Hopping: Accurate Time Derivative Couplings by the Curvature-Driven Approximation

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Abstract. Trajectory surface hopping (TSH) is a widely used mixed quantum-classical dynamics method, which is used to simulate molecular dynamics with multiple electronic states. In TSH, the time-derivative coupling (TDC) is employed to propagate the electronic coefficients and in that way to determine when the electronic state on which the nuclear trajectory is propagated switches. In this work, we discuss nonadiabatic TSH dynamics algorithms employing curvature-driven approximation and overlap-based time derivative couplings, and we report test calculations on six photochemical reactions where we compare the results to one another and to calculations employing analytic nonadiabatic coupling vectors. We correct previous published results, thanks to a bug found in the software. We also provide additional more detailed studies of the time derivative couplings. Our results show good agreement between curvature-driven algorithms and overlap-based algorithms.

1. Introduction

In a recently published work¹, some of the current authors reported a benchmark study on the accuracy of various approximations to the time-derivative coupling (TDC) that governs electronic-wave-function-propagation algorithm in nonadiabatic dynamics calculations carried out by trajectory surface hopping^{2,3,4,5} (TSH). One of the conclusions was that the curvature-driven approximation to the TDC^{6,7,8} that was implemented in SHARC-MN v1.2 deviates from most of the other algorithms. Unfortunately, this was due to a bug in SHARC-MN v1.2. In this work, we show the high accuracy of the curvature-driven approximation, correcting the original conclusion. We also present additional discussion of various approximations to the TDC.

The deviation reported in ref. 1 was caused by a bug in SHARC-MN v1.2 in evaluating the curvature-driven time-derivative coupling (κ TDC) by second-order finite differences of energies, which we will call the energy formula. An alternative formula, called the gradient formula, involves the dot product of the velocity and first-order finite differences of gradients. The previous works using curvature-driven approximations and the gradient formula with SHARC-MN were not affected by the bug. (To be perfectly clear: None of the published work of the Minnesota group is affected by the bug.) Although the approach for evaluating the κ TDC to be preferred is the gradient formula, we do show here that the energy formula is accurate as well. Both formulas are coded correctly in SHARC-MN v2.0⁹ and SHARC 3.0,¹⁰ either may be used in future work.

In addition to correcting the results of the earlier benchmark that were affected by the bug, the present paper reports more extensive studies on electronic propagation algorithms. Specifically, we will show the accuracy of κ TDC when compared to the analytic TDC evaluated from nonadiabatic coupling vectors (NACs).

2. Theoretical Background

The most efficient methods for simulating electronically nonadiabatic processes are semiclassical methods, in which the electronic structure is modeled quantum mechanically, and nuclear motion follows a semiclassical trajectory.^{11,12,13,14,15,16,17,18,19,20} We consider calculations in the adiabatic representation, where the coupling of electronic states is due to the nonadiabatic coupling vector (NAC). We focus first on the coherent propagation of

electronic coefficients, but decoherence²¹ will be added below. The key step in coherently propagating the electronic coefficients in a trajectory surface hopping calculation is to evaluate the TDC. There are three kinds of algorithms for this: (i) NAC-based algorithms that compute the TDC as a scalar product between the NAC and the velocity vector;^{4,22} (ii) overlap-based algorithms approximate TDC by exact or approximate overlaps of electronic adiabatic wave functions at successive time steps^{23,24} (in the following discussion, we will call simply label such integrals as the overlap integral); (iii) curvature-driven algorithms approximate the TDC in terms of derivatives the adiabatic potential energy surfaces.^{6,7,8} (Algorithms that use nonadiabatic models – the original Landau–Zener model of Preston and Tully² or the Zhu–Nakamura model²⁵ – rather than propagating the electronic wave function are outside the scope of this discussion.)

NAC-based algorithms require computing NACs from electronic structure programs^{26,27} or from fitted diabatic potential energy matrices;²⁸ overlap-based algorithms require computing adiabatic-wave-function overlap integrals,²⁹ thereby avoiding NAC calculations; and curvature-driven algorithms avoid both NACs and overlaps. Not only are curvature-driven algorithms more efficient, but also, they can be interfaced with electronic structure methods for which NACs are not available (e.g., multi-state pair density functional theory.^{30,31}) or with machine-learned potentials for which the adiabatic wave functions are not available.^{32,33}

We emphasize the distinction between the propagation algorithm and the way to approximate the TDC. For dynamics methods that do not use NACs, we use "t" and " κ " as prefixes to denote which kind of approximation is used. For example, tTSH denotes a TSH dynamics method that uses an overlap-based algorithm, and κ TSH denotes a TSH method that uses a curvature-driven algorithm, whereas tCSDM and κ CSDM denote using these kinds of algorithms in the coherent switching with decay of mixing³⁴ (CSDM) dynamics method.

Overlap-based algorithms are the most widely used due to their simplicity (they calculate only the one needed component of the NAC rather than all components followed by a scalar product to project out the component of interest) and due to their high accuracy for narrowly avoided crossings (or trivial crossings).^{35,36,37,38} The overlap may be computed accurately²⁹ or by several approximation schemes. The conversion of an overlap integral to the TDC is called

an HST²³ scheme in ref. 1, and ref. 1 provides the accuracy of two ways to approximate the overlap integral. The first one named HST(CIV) utilizes coefficients of configuration state functions in a configuration interaction calculation (also called CI vectors).³⁹ The HST(CIV) scheme neglects the contribution to the overlap integrals from the changes in the difference in the molecular orbitals at successive steps. The alternative, called HST(BiO), approximates the overlap by using a biorthogonal transformation of orbitals⁴⁰ that is implemented in *OpenMolcas*⁴¹ in Ref. 1. This is a better approximation because it includes the change in shape of the molecular orbitals, but it still neglects their translation due to the time step. As explained below, a related but more accurate approach than the HST scheme is to use the norm-preserving interpolation (NPI) scheme to evaluate the TDC.⁴² In SHARC and SHARC-MN, the NPI scheme is combined with substep propagators; this combination constitutes the NPI algorithm.⁴³

It has been proposed that the HST(CIV) scheme can be improved by diabatizing the orbitals at the current time step to those at the previous time step⁴⁴ (available in *Molpro*,⁴⁵ basically a block diagonalization that is done by maximizing overlaps of orbitals for a reference geometry), but that is not employed here or in *OpenMolcas*.

Another way to use the overlap integrals is the local diabatization method. In this approach, instead of using overlap integrals to calculate the TDC, one uses overlap integrals to construct a local diabatic representation, and one propagates electronic coefficients in the quasidiabatic basis.²⁴ This is called the local diabatization (LD) scheme.¹ Technically, one is not approximating the TDC, but since the method is closely related to the overlap methods used to approximate the TDC, we include it in this category. This kind of local diabatic representation was introduced for time-dependent propagation in 2001,²⁴ but basically the same idea was introduced for time-independent propagation of wave functions much earlier.⁴⁶

Next consider curvature-driven algorithms. There are two ways to approximate TDCs in curvature-driven algorithms,⁷ one uses first-order finite differences on the scalar product of the gradient with the velocity vector (gradient formula),⁷ and the other uses second-order finite differences of potential energies (energy formula).^{6,7,8} The gradient formula appears to be numerically more stable, and it is the preferred method.^{6,47,48,49} However, when employing TSH for internal conversion with propagation at any given time requiring the gradient of only

the active potential energy surface, the energy approach is more efficient because the gradient formula requires computing gradients of all electronic states. This advantage of the energy method is not present when one does κ CSDM⁷ or when one calculates intersystem crossing.^{50,51} (The reason why this advantage is not present for intersystem crossing calculations is that those calculations require all the gradients.⁵¹)

3. Sections

In the present work, we compare several schemes, included all three categories of algorithms, to investigate TSH nonadiabatic dynamics of six typical reaction systems. In section 4, we introduce the propagation of electronic coefficients and introduce various schemes and approximations for estimating the TDC. Section 5 provides some computational details. In section 6, we show two sets of simulation results; set 1 is used to test the accuracy of curvature-driven schemes, and set 2 is an investigation on how the curvature-driven approximation influences the nonadiabatic dynamics in detail. Section 7 has a summary of the conclusions.

4. Theory

This article is limited to internal conversion processes (processes that do not change the total electronic spin, which is assumed to be conserved), and in this section, we describe in detail the electronic propagators used in this work. Section 4.1 briefly recaps the electronic equation of motion. Section 4.2 summarizes the approximations to compute TDCs.

4.1. Coherent Electronic Equation of Motion

The time-dependent wave function can be written as

$$\Psi = \sum_{J} c_{J} \phi_{J} \tag{1}$$

where ϕ_J is a basis function, and c_J is an electronic state expansion coefficient. In the adiabatic representation the ϕ_J are eigenfunctions of the electronic Hamiltonian, and the coherent electronic equation of motion in the electronically adiabatic representation is

$$[\dot{c}_I]_{\mathsf{C}} = -\frac{i}{\hbar} \left(c_I V_I - i\hbar \sum_{J \neq I} c_J \sigma_{IJ} \right)$$
⁽²⁾

where an overdot denotes a time derivative, V_I is the adiabatic potential energy of state I, [...]_C denotes the coherent time development, and σ_{II} is an element of the TDC matrix σ between

electronic states I and J,

$$\sigma_{IJ} = \left\langle \phi_I \left| \frac{d}{dt} \right| \phi_J \right\rangle \tag{3}$$

The TDC can be written as

$$\sigma_{IJ} = \mathbf{d}_{IJ} \cdot \hat{\mathbf{R}} \tag{4}$$

where $\dot{\mathbf{R}}$ is the nuclear velocity vector, and \mathbf{d}_{II} is the NAC between electronic states I and J,

$$\mathbf{d}_{IJ} = \left\langle \phi_I \middle| \frac{\partial}{\partial \mathbf{R}} \middle| \phi_J \right\rangle \tag{5}$$

In labeling the various algorithms in the discussion below, we call direct use of eq (4) the analytic scheme for computing the TDC.

It is convenient to rewrite eq(2) in the more general matrix form

$$\dot{\mathbf{c}} = -\left(\frac{i}{\hbar}\mathbf{H}^{\text{elec}} + \boldsymbol{\sigma}\right)\mathbf{c} \tag{6}$$

where we dropped the subscript C to simplify the notation, \mathbf{H}^{elec} is the electronic Hamiltonian in a general basis (or, as we sometimes say, in a general representation), and $\boldsymbol{\sigma}$ is the TDC matrix in that basis. When we use the adiabatic representation, \mathbf{H}^{elec} is diagonal, and the diagonal matrix elements are the adiabatic potential energies V_I . When we use a diabatic representation, \mathbf{H}^{elec} is a nondiagonal matrix called the diabatic potential energy matrix (DPEM). The diagonal and off-diagonal matrix elements of DPEM are called diabatic potentials and diabatic couplings respectively. A diabatic representation is one where we can safely approximate $\boldsymbol{\sigma}$ as a zero matrix.⁵² Therefore, in a diabatic representation, the population transfer between diabatic electronic states is driven by off-diagonal matrix elements of the DPEM.

Electronic structure programs provide electronic wave functions in the adiabatic representation, and to propagate the electronic state coefficients in the adiabatic representation, one needs to compute or approximate σ . (The TDC can be neglected if one performs an adiabatic-to-diabatic transformation but the construction of global diabatic bases is laborious,⁵² especially for large molecules, so this is not usually done.) Approximate methods for computing σ are discussed in sections 4.2.1 to 4.2.3, and construction of locally diabatic states using the LD scheme is discussed in section 4.2.4.

4.2. Time Derivative Couplings

4.2.1. The Hammes-Schiffer–Tully Scheme

Hammes-Schiffer and Tully were the first to publish the relation shown in eq (4), and they proposed a scheme to compute the TDC using overlap integrals,²³

$$S_{IJ}(t,t^{+}) = \left\langle \phi_{I}(t) \middle| \phi_{J}(t^{+}) \right\rangle$$
⁽⁷⁾

where

$$t^+ \equiv t + \Delta t \tag{8}$$

and where $\phi_I(t)$ is the wave function of adiabatic electronic state *I* at time *t*, $\phi_J(t^+)$ is the wave function of adiabatic electronic state *J* at time t^+ , and Δt is the time step to propagate the nuclear equation of motion (in some algorithms, the electronic equation of motion is also propagated with time step Δt). The HST approximations are

$$\sigma_{IJ}^{\rm H}\left(t + \frac{1}{2}\Delta t\right) = \frac{S_{IJ}(t, t^+) - S_{JI}(t, t^+)}{2\Delta t}$$
(9)

and

$$\sigma_{IJ}^{\rm H}\left(t - \frac{1}{2}\Delta t\right) = \frac{S_{IJ}(t^-, t) - S_{JI}(t^-, t)}{2\Delta t}$$
(10)

where

$$t^{-} \equiv t - \Delta t \tag{11}$$

Therefore, one can approximate $\sigma_{IJ}(\mathcal{T})$ for any point in the time interval $t - \frac{1}{2}\Delta t \leq \mathcal{T} \leq t + \frac{1}{2}\Delta t$ by

$$\sigma_{IJ}^{\rm HST}(\mathcal{T}) = \sigma_{IJ}^{\rm H}\left(t - \frac{1}{2}\Delta t\right) + \frac{\mathcal{T} - \left(t - \frac{1}{2}\Delta t\right)}{\Delta t} \left(\sigma_{IJ}^{\rm H}\left(t + \frac{1}{2}\Delta t\right) - \sigma_{IJ}^{\rm H}\left(t - \frac{1}{2}\Delta t\right)\right)$$
(12)

Clearly, eq (12) linearly interpolates the TDC between two times, namely, $t - \frac{1}{2}\Delta t$ and $t + \frac{1}{2}\Delta t$. One disadvantage of such a linear interpolation is that it might completely miss the peak of the TDC when a NAC is narrowly distributed. This would make the integration of electronic coefficients wrong. Such a problem is amplified for trivial crossing situations. This deficiency has stimulated methods like norm-preserving interpolation and local diabatization algorithms, which will be discussed in later sections. When T = t, this becomes

$$\sigma_{IJ}^{\text{HST}}(t) = \frac{S_{IJ}(t,t^+) - S_{JI}(t,t^+) + S_{IJ}(t^-,t) - S_{JI}(t^-,t)}{4\Delta t}$$
(13)

One can use approximated overlap integrals instead of true overlap integrals in HST

scheme. As reviewed in Section 2, computing overlap integrals using only configuration interaction coefficients generates the so-called HST(CIV) scheme, and using configuration interaction coefficients and biorthonormal orbitals generates the HST(BiO) scheme.

Because $S_{IJ}(t, t^+)$ can be computed without computing NACs, the HST scheme, with either accurate or approximate overlap integrals, allows one to compute the TDC without computing NACs. In addition, the HST can alleviate the trivial crossing problem.⁴² Therefore, HST scheme is widely used.^{35,36,53,54,55}

4.2.2. The Norm Preserving Interpolation Scheme

The accuracy of the HST scheme depends on the time step because of the linear interpolation. An improved version developed by Meek and Levine⁴² and called normpreserving interpolation (NPI), includes higher-order contributions. The HST scheme can be considered as a linear approximation to the NPI scheme. The NPI scheme approximates the evolution of the electronic wave function in the time interval $t \le T \le t^+$ by using a twostate rotation matrix at time T:

$$\phi_{I}(\mathcal{T}) = \Theta(\mathcal{T})\phi_{I}(t) \tag{14}$$

where the elements of the rotation matrix $\Theta(\mathcal{T})$ are

$$\Theta_{II}(\mathcal{T}) = \cos\left(\cos^{-1}\left(S_{IJ}(t,t^{+})\right)\frac{\mathcal{T}-t}{\Delta t}\right)$$
(15)

$$\Theta_{IJ}(\mathcal{T}) = \sin\left(\sin^{-1}\left(S_{IJ}(t,t^{+})\right)\frac{\mathcal{T}-t}{\Delta t}\right)$$
(16)

Therefore,

$$\sigma_{IJ}^{\text{NPI}}(\mathcal{T}) = \left\langle \phi_{I}(t) \middle| \Theta^{\dagger}(\mathcal{T}) \frac{\partial}{\partial \mathcal{T}} \Theta(\mathcal{T}) \middle| \phi_{J}(t) \right\rangle$$
(17)

The NPI scheme is a higher-order way to use overlap integrals without requiring NACs. Although not implemented and never tested, one could imagine converting approaches like HST(CIV) and HST(BiO) to NPI(CIV) and NPI(BiO).

4.2.3. Curvature Approximation

The curvature approximation is very different from the HST or NPI schemes in that it does not require computing overlap integrals; all that is needed is the second-order time derivative of adiabatic potential energies. The curvature approximation stems from the Baeck-An coupling approximation⁶ that was originally derived for 1-dimensional systems by considering the relationship between the Lorentzian dependence of NACs along a diabatization coordinate and the linear vibronic coupling scheme and conjecturing that the approximation so derived could be useful not only near a diabatic crossing sems but also nearby. By recognizing that a trajectory is 1-dimensional propagation along a time coordinate, one can approximate the TDC in terms of the curvature of the potential energy surfaces along the time coordinate^{7,8} (that is why we call it the curvature approximation):

$$\Xi_{IJ}^{\kappa}(t) = \begin{cases} \frac{1}{2} \left[\frac{d^2 \Delta V_{IJ}(t)}{dt^2} \frac{1}{\Delta V_{IJ}(t)} \right]^{1/2} & \text{for radicand postive} \\ 0 & \text{for radicand negative} \end{cases}$$
(18)

$$\sigma_{IJ}^{\kappa}(t) = \Xi_{IJ}^{\kappa}(t) \text{ for } J > I$$
(19)

$$\sigma_{IJ}^{\kappa}(t) = -\Xi_{IJ}^{\kappa}(t) \text{ for } J < I$$
(20)

where

$$\Delta V_{IJ}(t) = V_I(t) - V_J(t) \tag{21}$$

The curvature approximation to the TDC is called KTDC.

We can consider two formulas for computing the second-order time derivative of $\Delta V_{IJ}(t)$: the *energy formula*,^{7,8} which can start at the third step with

$$\frac{d^2 \Delta V_{IJ}(t)}{dt^2} \approx \frac{1}{\Delta t^2} \Big[\Delta V_{IJ}(t) - 2\Delta V_{IJ}(t^-) + \Delta V_{IJ}(t - 2\Delta t) \Big]$$
(22)

and at the fourth step switch to

$$\frac{d^2 \Delta V_{IJ}(t)}{dt^2} \approx \frac{1}{\Delta t^2} \Big[2\Delta V_{IJ}(t) - 5\Delta V_{IJ}(t^-) + 4\Delta V_{IJ}(t - 2\Delta t) - \Delta V_{IJ}(t - 3\Delta t) \Big]$$
(23)

and the gradient formula,⁷

$$\frac{d^2 \Delta V_{IJ}(t)}{dt^2} \approx \frac{\Delta \dot{V}_{IJ}(t) - \Delta \dot{V}_{IJ}(t^-)}{\Delta t}$$
(24)

The gradient formula follows from

$$\Delta \dot{V}_{IJ}(t) = \frac{\partial \Delta V_{IJ}(t)}{\partial \mathbf{R}} \cdot \dot{\mathbf{R}}$$
(25)

Note that for a small enough step size, these two formulas should give the same result. The gradient formula is more stable numerically than the energy formula because lower-order finite differences are always more stable. However, when one uses the TSH method without spin-orbit coupling with the energy formula, one needs gradients only for the active surface, but the gradient formula requires gradients for all electronic states, which can add to the computational cost. For methods that uses self-consistent potentials,^{34,56,57,58,59,60,61,62} or for calculations that include spin-orbit coupling,^{50,51,63,64} the gradient formula should be preferred.

We denote the energy κ TDC formula as κ TDC/E and its result as $\sigma_{IJ}^{\kappa/E}(t)$; we denote the gradient κ TDC formula as κ TDC/G and its result as $\sigma_{IJ}^{\kappa/G}(t)$.

4.2.4. Local Diabatization scheme

Instead of directly approximating the TDC, the LD scheme performs an adiabatic to diabatic transformation,²⁴ because such diabaticity is only valid within a time step, the states are locally but not globally diabatic. The locally diabatic states are defined by

$$\mathbf{H}^{\mathrm{LD}}(t^{+}) = \mathbf{S}(t, t^{+})\mathbf{H}(t^{+})\mathbf{S}(t, t^{+})^{\dagger}$$
(26)

One assumes that the electronic coefficients are the same in the adiabatic and diabatic bases at time t; then the propagation from time t to t^+ is carried out diabatically,

$$\dot{\mathbf{c}} = -\left(\frac{i}{\hbar}\mathbf{H}^{\text{elec}}\right)\mathbf{c}$$
⁽²⁷⁾

As in the HST and NPI schemes, one can use approximated overlap integrals in performing the locally diabatic transformation shown in eq (26).

4.2.5. Summary of Time-Derivative couplings

We have introduced the following schemes to compute or approximate the TDC: analytic scheme, HST scheme, NPI scheme, κ TDC/E formula, and κ TDC/G formula. Furthermore, one can think of the LD scheme as an effective computation of the TDC by constructing a locally diabatic basis. For the schemes using overlap integrals, one may use either exact or approximated overlap integrals, where the HST(CIV) scheme and HST(BiO) scheme are prominent examples of the latter. If one uses exact overlap integrals and a small enough step size, the overlap methods and LD method should yield results identical to the analytic method because the overlap method is an analytically correct way to calculate the needed component of the NAC, but curvature-driven methods differ from the analytic method even for a converged step size because the curvature-driven method involves an approximation to the NAC.

In the above notation, the NAC-based algorithm uses the analytic scheme; the overlapbased algorithms use HST schemes, NPI schemes, or LD schemes (where we use plural "schemes" because of the possibility of using accurate or variously approximated overlap integrals); and the curvature-driven algorithms use κ TDC/E or κ TDC/G formulas.

5. Computational Details

We present two sets of simulations in this work. The first set of simulations is like that of ref. 1 except that we use the bug-fixed SHARC-MN v2.0; note that SHARC 3.0 has the same code for these calculations as SHARC-MN v2.0, and thus the calculations could have been equivalently done with SHARC 3.0. The second set of simulations involves a more detailed study of the accuracy of TDC approximations.

In the first set of simulations, six different systems have been studied, namely, *cis*azomethane (*cis*-AZM), *trans*-azomethane (*trans*-AZM), *cis*-azobenzene (*cis*-AZB), *trans*azobenzene (*trans*-AZB), butyrolactone, and furanone. All electronic structure calculations are performed with *OpenMolcas*.⁴¹ State averaged complete active space self-consistent field theory (SA-CASSCF)^{65,66} is employed for the electronic structure, and the number of states averaged, the active space, and basis set used for each system is summarized in Table 1. Table 1 also gives the number of trajectories in each ensemble and the simulation time. The initial conditions are sampled from the ground-state Wigner distribution implemented with Newton-X^{67,68}.

system		electronic structure	dynamics simulation		
		number of states averaged	basis sot	number of	simulation
		and active space size	Dasis set	trajectories	time (fs)
cis-AZM	N=N /	SA(2)-CASSCF(6,4)	6-31G(d)	100	145
trans-AZM	N=N	SA(2)-CASSCF(6,4)	6-31G(d)	200	350
cis-AZB	N=N	SA(4)-CASSCF(14,12)	ANO-RCC-VDZP	100	100
trans-AZB	N=N	SA(4)-CASSCF(14,12)	ANO-RCC-VDZP	100	100
butyrolactone		SA(3)-CASSCF(10,8)	ANO-RCC-VDZP	200	100
furanone		SA(3)-CASSCF(12,10)	ANO-RCC-VDZP	100	150

Table 1. Electronic structure and dynamics details for simulation set 1

For each system, five schemes for computing the TDC are employed, namely, the analytic scheme, LD scheme, HST(CIV) scheme, HST(Bio) scheme, and κ TDC/E formula. (We present only results with the correct SHARC-MN v2.0 and do not repeat the incorrect results from ref 1 caused by the bug in SHARC-MN v1.2.) We used four different dynamics programs as specified with time steps and number of electronic substeps in Table 2.

TDC Scheme	time step (fs)	# of substeps	software
analytic	0.5	100	SHARC 2.1
LD	0.5	1^a	Newton-X
HST(CIV)	0.48	96	OpenMolcas
HST(BiO)	0.48	96	OpenMolcas
κTDC/E	0.5	100	SHARC-MN v2.0

Table 2. Dynamics methods details for set 1

^{*a*}The implementation in Newton-X for the LD scheme does not use a substep propagator. It propagates the coefficient over the full time step. See for example, eq 6 of ref 67.

All calculations employed Tully's fewest-switches version⁵ of trajectory surface hopping with an energy-based decoherence correction (EDC).⁶⁹ The constant *C* in the EDC formula is set to the standard value of 0.1 hartree.

After a hop, nuclear velocity is rescaled along the velocity vector direction in all calculations, and all frustrated hops are ignored. These choices were adopted for consistency with ref 1, but we remind the reader that our preferred choice for momentum adjustment is using a projected NAC⁷⁰ when NACs are available, or a projected effective NAC when they are not, and our preferred choice for the treatment of frustrated hops is the ∇V scheme.⁷¹ (Projected NACs, projected velocities, and the ∇V scheme are all now available in SHARC MN v2.0⁹ and SHARC 3.0.¹⁰)

The second set of simulations is a detailed investigation of the TDC approximations for *cis*-AZM and *trans*-AZM dynamics. Four TDC schemes are compared, namely the LD scheme, NPI scheme, κ TDC/E formula, and κ TDC/G formula. The electronic structure method, dynamics method, and initial condition selection are identical to set 1. The *Molpro*

software package is used for SA-CASSCF calculations.⁴⁵ We used a locally modified version of SHARC MN v2.0 that enables us to compute all TDCs by different schemes at the same time.

6. Results

6.1. Ensemble Averaged Population for All Systems

First, as in ref. 1, we study the accuracy of κ TDC/E formula as compared to the other schemes. Table 3 shows the extent of energy nonconservation in the trajectories, and Figure 1 shows the ensemble-averaged populations as functions of time. Notice that the results of the analytic scheme shown in Figure 1 have very small differences from those reported in ref 1 because in ref 1, the analytic scheme was done by Newton-X, whereas in the current study, it is done by SHARC-MN v2.0. All trajectories that failed to conserve energy within 0.5 eV are discarded in the analysis of set 1.

Table 3 reports the percentage of trajectories that fail to conserve energy within a given threshold for each scheme for all six systems. In TSH calculations, the algorithm employed to propagate the electronic coefficients has no direct effect on energy conservation because the trajectory propagates on a single potential energy surface between hops. However, the algorithm does affect active state switches. Since energy conservation is enforced by construction at a hop, the energy nonconservation may be attributed to the regions between hops. For surface-hopping simulations, energy nonconservation may have therefore have more than one source: finite difference error or roundoff in the algorithm with which the nuclear motion is integrated, numerical inexactness of the energy gradients, and – in direct dynamics with SA-CASSCF – energy nonsmoothness of the SCF convergence. In the general case, nonsmoothness of SCF convergence has two possible causes: (i) Sometimes this is due to orbitals that go into or out of the active space. (ii) However, in other situations, some active orbitals and some inactive orbitals may have different mixtures in different steps. In light of these considerations, the relation of energy conservation or nonconservation to the scheme is for evaluating the TDC is complicated, and different algorithms and different molecules may be more or less sensitive to various factors. Upon comparing algorithms, Table 3 shows, nevertheless, that, on average, all methods have similar energy conservation when applied with the same time step, although HST(CIV) does show the worst conservation. Upon

comparing molecules, though, there is one exception to the good energy conservation, namely *trans*-AZB; Table 3 shows a larger number of trajectories with poor energy conservation for all schemes for this molecule.

Inspection of the trajectories indicate that error in energy conservation is mostly caused by sudden jumps in potential energy surfaces; however, although in general active orbitals can mix from one time step to the next (within the active space), no rotation of orbitals in and out the active space was observed in the present work, demonstrating a rather stable active space. This indicates that type-ii nonconservation is involved. An example is illustrated in Figure S1 in the SI, which shows a prototypical trajectory that conserves energy better than 0.2 eV, but nevertheless shows this kind of problem. The top panel of Figure S1 is the TDC evaluated by the κ TDC/E formula, and the bottom panel is the potential energy surface as a function of time. The sudden jumps are highlighted with circles in the bottom panel; apparently, these sudden jumps cause artificial local spikes of TDCs. This example shows how one must be careful to distinguish errors caused by the dynamic algorithms, from errors caused by the underlying direct electronic structure calculations, or from the coupling between the two. Indeed, with direct dynamics methods, small or large instabilities in the electronic structure calculations can have consequences on the dynamics results, and different dynamics algorithms have different behaviors with respect to details of electronic structure calculation.

Threshold	analytic	LD	HST(Bio)	HST(CIV)	кTDC/Е			
<i>cis</i> -azomethane								
0.5 eV	2	2	3	2	2			
0.2 eV	2	2	3	2	3			
<i>trans</i> -azomethane								
0.5 eV	2	1	0	0	0			
0.2 eV	2	1	0	0	0			
<i>cis</i> -azobenzene								
0.5 eV	0	1	3	5	2			
0.2 eV	24	19	23	22	21			
<i>trans</i> -azobenzene								
0.5 eV	1	7	4	18	12			
0.2 eV	34	42	37	63	48			
		b	outyrolactone					
0.5 eV	2	1	1	8	1			
0.2 eV	11	12	10	23	20			
			furanone					
0.5 eV	2	1	4	4	3			
0.2 eV	6	2	7	8	13			
			Average					
0.2 eV	13	13	13	20	18			
Average omitting trans-AZB								
0.2 eV	9	7	9	11	11			

Table 3. Percentages of trajectories that do not conserve energy within a given threshold amount



Figure 1. Ensemble-averaged population as a function of time for (a) *cis*-azomethane, (b) *trans*-azomethane, (c) *cis*-azobenzene, (d) *trans*-azobenzene, (e) butyrolactone, (f) furanone. For panels a, b, c, d, the ground-state population is shown as dotted curve. For panels e and f, we show the populations for S_0 , S_1 , and S_2 in separate subpanels.

Figure 1 shows that KTDC/E gives accurate time-dependent populations for most systems, with the only exception being *trans*-AZB. The differences are not due to poor energy conservation because trajectories with poor energy conservation are removed from the analysis. Furthermore, the smaller sudden jumps that may still be present are there in all schemes. It seems that the different schemes do not have all the same sensitivity to details of the electronic structure calculations.

We do not discuss the chemical aspects of the photochemical behaviors for the six systems because that is already given in ref 1.

6.2 Comparisons of TDCs from Various Schemes

Next, we discuss the dynamics calculation of set 2, which are used to compare TDCs computed by different schemes. All trajectories that failed to conserve energy within 0.2 eV are discarded in the analysis of set 2. We compare TDCs computed by the analytic scheme, the NPI scheme, the κ TDC/E formula, and the κ TDC/G formula. The ensemble averaged population as a function of time for *cis-* and *trans-*AZM is shown in Figure S2 in the SI; the results are very similar to those in panels a and b of Figure 1. (The analytic and κ TDC/E results in Figure 1 and Figure S2 are not the same because the results in Figure S2 are from a different dynamic simulation using *Molpro*.)

To assess the accuracy of the TDC computed by various methods, especially by the curvature-driven approximations, we plotted the TDCs evaluated from κ TDC/E, κ TDC/G, and NPI formulas versus analytic TDCs along the trajectory. The TDC shown in the figures has units of 1/(aut), where aut is the atomic unit of time, which equals 0.02419 fs. Scatter plots for every time step for the whole ensemble are shown in Figure 2. In Figure 2 we do not include those points correspond to κ TDC equals zero because they cannot be shown in a logarithm plot. To assess the corresponding analytic TDCs of such points, histograms of points with κ TDC/G or κ TDC/E equal to zero are shown in Figure S3 in SI. Clearly these points correspond to small analytic TDC values.

The color of each point in Figure 2 corresponds to the energy gap according to the color bar shown on the right of each panel. We see that the κ TDC/E and κ TDC/G formulas tend to overestimate the TDCs compared with analytic TDC for points where the TDC is small, i.e.,

less than 10⁻³. However, we expect that the rate of internal conversion is typically dominated by regions where the coupling is large, and inaccuracies in regions where the coupling is weak are expected to have only a small effect on the overall accuracy in most cases. Therefore, the points that are especially important for photochemical dynamics are those for which the TDC is relatively large. Those are the points toward the upper right of the plots. As expected, they tend to be blue, indicating that they correspond to places where the energy gap is small. For large TDCs and small gaps we see a good correlation of the curvature-driven TDC and the analytic TDC.



Figure 2. The scatter plot of TDCs evaluated from κ TDC/E (right), κ TDC/G (mid), NPI (right) formulas compared with the analytic TDC for both *cis*- and *trans*-AZM molecule.

Next we compare the curvature-driven algorithms with overlap-based algorithms. Specifically, we investigated the time at which a hop happens for *cis*- and *trans*-AZM trajectories that use κ TDC/E and κ TDC/G approaches as compared to those that use the LD scheme. This is shown in Figure 3. (Although other discussion involves comparing to analytic TDCs, the comparison for when a hop occurs is carried out using LD trajectories because LD trajectories should have no trivial crossing problem. A figure similar to Figure 3 but that compares the hopping time for *cis*- and *trans*-AZM trajectories that use κ TDC/E, κ TDC/G approaches, and NPI schemes with analytic scheme is shown in Figure S4 in the SI.) The orange and blue points in Figure 3 are for *cis*- and *trans*-AZM respectively. The times are comparable because we used a fixed time step and the same random number seeds for the different methods. Figure 3 shows reasonably good correspondence between the methods.



Figure 3. The time (in fs) at which a hop occurs for trajectories that use κ TDC/E (on the left) and κ TDC/G (on the right) formulas as compared to the time at which a hop occurs with the LD scheme. Orange and blue points are for *cis*- and *trans*-AZM respectively.

Figure 4 compares the TDCs evaluated with κ TDC/E and κ TDC/G formulas to the analytic TDCs for the geometries where hops happen in *cis*- and *trans*-AZM trajectories. This figure shows that both κ TDC/E and κ TDC/G approaches are reasonably accurate, but κ TDC/G is generally closer than κ TDC/E to the analytic TDC. The curvature-driven scheme appears to be more accurate when the coupling is large than when it is small. The main limitation of the trajectories in Figure 4 is probably the semiclassical nature of the dynamics algorithms and the propagation on a non-self-consistent potential in surface hopping calculations, not the quantitative values of the coupling constants. The main conclusion to be drawn from Figure 4 is that the curvature-driven approximation works well for most trajectories.



Figure 4. Scatter plot of TDCs evaluated with κ TDC/E (left) and κ TDC/G (right) approaches as compared to analytic TDC at the geometries where hop occur. Orange and blue are points for *cis*- and *trans*-AZM trajectories respectively.

Figure 5 shows the TDC and potential energy as functions of time for a randomly selected *cis*-AZM trajectory. A similar plot for *trans*- AZM is shown in Figure S5 in the SI. We see especially good agreement in the important region where the TDC is large. We thus draw the same conclusions as from Figure 4.



Figure 5. A randomly selected trajectory for *cis*-AZM. The upper left panel shows the TDC evaluated by the analytic scheme, the NPI scheme, and the κ TDC/E and κ TDC/G formulas as functions of time. The upper right panel is a zoom on the region between 40 and 60 fs. The bottom left panel shows the potential energy as a function of time for both ground and excited state as well as the potential energy V_{active} of the active state; the bottom right panel zooms this for 40–60 fs.

7. Concluding Remarks

We showed that the previous large differences in ensemble populations as functions of time predicted by trajectory surface hopping calculations using the curvature-driven algorithm and by trajectory surface hopping calculations using the NAC-based or overlap-based algorithms is removed when a bug is fixed in SHARC-MN. This work shows that the correct application of the curvature-driven methods leads to good agreement of curvature-driven algorithms with analytic evaluation of the time derivative coupling from NACs, and this good performance is consistent with good performance we have obtained^{7,47,49,72} on other problems. We also showed that accurate results can be obtained with both the energy and gradient formulas (denoted as κ TDC/E and κ TDC/G respectively) for the curvature-driven approximations to the time-derivative coupling.

We have demonstrated the accuracy of curvature-driven approximation and the overlapbased approximations not only for ensemble-averaged populations as functions of time but also by examining the times at which hops occur and the magnitudes of TDC along the trajectory. In the regions where the coupling is large, there is good agreement of the couplings obtained analytically from NACs, those obtained from overlap integrals, and those obtained by the curvature-driven formulas.

The curvature-driven approximation to the TDC is available for κ TSH calculations in SHARC-MN v2.0,⁹ SHARC 3.0,¹⁰ ANT⁷³ and Newton-X^{67,68} (in Newton-X, the curvature-driven approximation for the TDC is called Baeck-An coupling). The curvature-driven approximation to the TDC along with a curvature-driven approximation to an effective NAC⁷ is available for κ CSDM calculations (which require all components of the NAC or an effective NAC) is available in SHARC-MN v2.0, SHARC 3.0, and ANT. Use of the curvature-driven approximation eliminates the cost, limited availability, and inconvenience of

using analytic NACs. In addition to expense and inconvenience, even when NACs are available, they present problems due to phases, origin dependence, improper treatment of electronic translation, spurious long-range couplings, and artificial nuclear translational and rotational components, all of which are avoided when using the curvature-driven approximation.

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