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#### **Topology Proceedings**

#### ON LOCAL COMPACTNESS OF SPACES OF CONTINUOUS VALUATIONS

#### JEAN GOUBAULT-LARRECQ

ABSTRACT. We show that the spaces of continuous valuations, resp. subprobability valuations on a locally compact space is locally compact; similarly with probability valuations on locally compact, compact spaces. Continuous valuations are close cousins of measures. No separation property is assumed.

#### 1. Introduction

A continuous valuation on a topological space X is a close cousin of a Borel measure. Continuous valuations on X form a space  $\mathbf{V}X$ , with a topology known as the weak topology, and similarly for the subspaces  $\mathbf{V}_{\leq 1}X$  of subprobability valuations and  $\mathbf{V}_1X$  of probability valuations. We will define these notions more precisely below. It is known that  $\mathbf{V}_{\leq 1}$  preserves various properties: stable compactness [2, Theorem 39], being a continuous dcpo [16, Theorem 5.2], being a quasi-continuous dcpo [14, Theorem 5.1], for example. Some of these preservation theorems extend over to  $\mathbf{V}_1$  or to  $\mathbf{V}$ , but a conspicuously absent property in the list is local compactness. This is what we address in this paper.

The proof relies on credibilities, as already used in [14], on the Smyth powerdomain construction [23], on Jones' celebrated theorem that the probabilistic powerdomain preserves continuous dcpos [16, Theorem 5.2], and on a few things about certain functionals called superlinear previsions

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[12]. As a whole, the proof is therefore rather elaborate; but it also results from little more than an assemblage of previously known results, and as a consequence, is pretty short.

#### 2. Preliminaries

For background on topology, we refer the reader to [11].

A compact subset A of a space X is one such that one can extract a finite subcover from any of its open covers. No separation property is assumed. A subset A of X is saturated if and only if it is equal to the intersection of its open neighborhoods, or equivalently if and only if it is upwards-closed in the specialization preordering of X. The latter is defined by  $x \leq y$  if and only if every open neighborhood of x contains y.

A space X is *locally compact* if and only if every point has a base of compact neighborhoods, or equivalently of compact saturated neighborhoods, since for any compact subset K of X, the upward closure  $\uparrow K$  of K with respect to the specialization preordering of X is compact saturated. In non-Hausdorff spaces, a compact space may fail to be locally compact.

A space is  $T_0$  if and only if its specialization preordering is antisymmetric. An *irreducible* closed subset C of X is a non-empty closed subset such that, for any two closed subsets  $C_1$  and  $C_2$  of X such that  $C \subseteq C_1 \cup C_2$ , C is included in  $C_1$  or in  $C_2$  already; equivalently, if C intersects two open sets, it must intersect their intersection. A space X is *sober* if and only if it is  $T_0$  and every irreducible closed subset is of the form  $\downarrow x$  for some point  $x \in X$ . Every Hausdorff space, for example, is sober. The notation  $\downarrow x$  stands for the *downward closure* of x in X, namely the set of points y below x; that is also the closure of x. Symmetrically, x stands for the *upward closure* of x, namely the set of points x above x. This notation extends to x, for any subset x, denoting x.

A function  $f\colon P\to Q$  between posets is monotonic if and only if for all  $x,x'\in P, \ x\le x'$  implies  $f(x)\le f(x')$ . It is Scott-continuous if and only if f is monotonic and for every directed family  $(x_i)_{i\in I}$  with a supremum x in P, the (necessarily directed) family of elements  $f(x_i)$  has f(x) as supremum. A directed family is a non-empty family D such that any two elements of D have an upper bound in D. We write  $\sup^{\uparrow} D$  for the supremum of a directed family D. Scott-continuity is equivalent to continuity with the respective Scott topologies on P and Q. The Scott topology on a poset P consists of those subsets U that are upwards closed  $(x\in U \text{ and } x\le x' \text{ implies } x'\in U)$  and such that every directed family D that has a supremum in U intersects U.

A dcpo (short for directed-complete partial order) is a poset P in which every directed subset has a supremum. In a dcpo P, let  $x \ll y$  ("x is way below y") if and only if every directed family D such that  $y \leq \sup^{\uparrow} D$ 

contains an element  $d \in D$  such that  $x \leq d$ . A basis for P is a subset B such that, for every  $x \in P$ ,  $\downarrow_B x \stackrel{\text{def}}{=} \{b \in B \mid b \ll x\}$  is directed and has x as its supremum. A dcpo is continuous if and only if it has a basis. If so, the sets  $\uparrow b \stackrel{\text{def}}{=} \{x \in P \mid b \ll x\}$  form a base of the Scott topology.

Let  $\overline{\mathbb{R}}_+$  be the set of extended non-negative real numbers  $\mathbb{R}_+ \cup \{\infty\}$ , with its usual ordering. When needed, we will consider it with its Scott topology, whose open sets are the intervals  $]t,\infty]$ ,  $t\in\mathbb{R}_+$ , plus  $\emptyset$  and  $\overline{\mathbb{R}}_+$  itself. In passing,  $\overline{\mathbb{R}}_+$  is an example of a continuous dcpo, with  $s\ll t$  if and only if s=0 or s< t.

We write  $\mathcal{O}X$  for the lattice of open subsets of a space X. A continuous valuation on X is a map  $\nu \colon \mathcal{O}X \to \overline{\mathbb{R}}_+$  that is strict  $(\nu(\emptyset) = 0)$ , modular (for all  $U, V \in \mathcal{O}X$ ,  $\nu(U) + \nu(V) = \nu(U \cup V) + \nu(U \cap V)$ ) and Scott-continuous. We say that  $\nu$  is bounded if  $\nu(X) < \infty$ , a probability valuation if and only if  $\nu(X) = 1$ , and a subprobability valuation if and only if  $\nu(X) \leq 1$ .

Continuous valuations are an alternative to measures that have become popular in domain theory [17, 16]. The first results that connected continuous valuations and measures are due to Saheb-Djahromi [21] and Lawson [19]. The current state of the art on this matter is the following. In one direction, every measure on the Borel  $\sigma$ -algebra of X induces a continuous valuation on X by restriction to the open sets, if X is hereditarily Lindelöf (namely, if every directed family of open sets contains a cofinal monotone sequence). This is an easy observation, and one half of Adamski's theorem [1, Theorem 3.1], which states that a space is hereditary Lindelöf if and only if every measure on its Borel  $\sigma$ -algebra restricts to a continuous valuation on its open sets. In the other direction, every continuous valuation on a space X extends to a measure on the Borel sets provided that X is an LCS-complete space [6, Theorem 1]. An LCScomplete space is a  $G_{\delta}$  subspace of a locally compact sober space, and the class of LCS-complete spaces contains all locally compact sober spaces, in particular all continuous depos from domain theory, all of M. de Brecht's quasi-Polish spaces [13] and therefore all Polish spaces.

The extension of a continuous valuation  $\nu$  to a measure on the Borel  $\sigma$ -algebra is unique if  $\nu$  is bounded. This is a consequence of the  $\pi$ - $\lambda$  theorem [3, Theorem 3.2], usually applied to probability measures [3, Theorem 3.3], but the same proof works for bounded measures.

Hence the above maps from Borel measures to continuous valuations and conversely, defined on hereditary Lindelöf LCS-complete spaces (in particular, quasi-Polish spaces), are inverse of each other when restricted to bounded measures and bounded continuous valuations.

Let  $\mathbf{V}X$  denote the space of continuous valuations on a space X, with the weak topology, defined by subbasic open sets  $[U>r] \stackrel{\mathrm{def}}{=} \{\nu \in \mathbf{V}X \mid \nu(U)>r\}$ , where  $U\in \mathcal{O}X$  and  $r\in \mathbb{R}_+$ . We define its subspace  $\mathbf{V}_1X$  of probability valuations and  $\mathbf{V}_{\leq 1}X$  (subprobability) similarly. In general, we write  $\mathbf{V}_{\bullet}X$ , where  $\bullet$  can be nothing, " $\leq$  1", or "1". The specialization ordering of each is the stochastic ordering  $\leq$  given by  $\nu \leq \nu'$  if and only if  $\nu(U) \leq \nu'(U)$  for every  $U \in \mathcal{O}X$ ; indeed,  $\nu \leq \nu'$  if and only if for every  $U \in \mathcal{O}X$ , for every  $V \in \mathcal{O}X$ , for every  $V \in \mathcal{O}X$  implies  $V \in [U>r]$ .

There is a related topology on spaces of probability measures. A sequence of probability measures  $P_n$ ,  $n \in \mathbb{N}$ , on a metric space converges weakly to a probability measure P if and only if  $\liminf_{n \in \mathbb{N}} P_n(U) \geq P(U)$  for every open subset U [4, Portmanteau Theorem 2.1]. It is easy to see that this is equivalent to: for every open subset U and for every  $r \in \mathbb{R}_+$ , P(U) > r implies that  $P_n(U) > r$  for n large enough. Hence we may define the weak topology on spaces of measures (not just probability measures) on a topological space X (not just a metric space) as given via a subbasis of sets  $\{P \mid P(U) > r\}$ ,  $U \in \mathcal{O}X$ ,  $r \in \mathbb{R}_+$ . We obtain the following.

**Proposition 2.1.** The weak topology makes the spaces  $\mathcal{M}_{\leq 1}X$  and  $\mathcal{M}_{1}X$  of subprobability, resp. probability measures homeomorphic to  $\mathbf{V}_{\leq 1}X$  and  $\mathbf{V}_{1}X$ , respectively, for every hereditarily Lindelöf LCS-complete space X.

 $\mathbf{V}_{\bullet}$  is the object part of an endofunctor on the category of topological spaces, whose morphism part is defined as follows: for every continuous map  $f \colon X \to Y$ ,  $\mathbf{V}_{\bullet}f$  maps every  $\nu \in \mathbf{V}_{\bullet}X$  to its *image valuation*  $f[\nu]$ , where  $f[\nu](V) \stackrel{\mathrm{def}}{=} \nu(f^{-1}(V))$  for every  $V \in \mathcal{O}Y$ .

We will prove slightly more than the fact that  $\mathbf{V}_{\bullet}$  preserves local compactness, where  $\bullet$  is nothing, " $\leq$  1", or "1". A space X is core-compact if and only if  $\mathcal{O}X$  is a continuous dcpo; every locally compact space is core-compact [11, Theorem 5.2.9]. The connection between the two notions can be made more precise as follows. Every topological space X has a sobrification  $\mathcal{S}(X)$  (or  $X^s$ ), which is the free sober space over X [11, Theorem 8.2.44]; then X is core-compact if and only if  $\mathcal{S}(X)$  is locally compact [11, Proposition 8.3.11].  $\mathcal{S}(X)$  can be built as the collection of irreducible closed subsets, with the topology whose open sets (all of them, not just a base) are  $\diamond U \stackrel{\mathrm{def}}{=} \{F \in \mathcal{S}(X) \mid F \cap U \neq \emptyset\}, \ U \in \mathcal{O}X$ . In particular,  $\diamond$ :  $U \mapsto \diamond U$  is an order-isomorphism between  $\mathcal{O}X$  and  $\mathcal{OS}(X)$ . This induces a homeomorphism between  $\mathbf{V}_{\bullet}X$  and  $\mathbf{V}_{\bullet}\mathcal{S}(X)$ .

## 3. Credibilities, previsions and the Smyth powerdomain

The proof of our main theorem will rely on reducing the question to spaces of valuations on Smyth powerdomains, and on using notions of credibilities [10] and of previsions [9, 12]. We need to give a quick tour of the part of that theory that we need.

Let  $\mathcal{L}X$  denote the dcpo of all lower semicontinuous maps from X to  $\overline{\mathbb{R}}_+$ ; a map  $f\colon X\to \overline{\mathbb{R}}_+$  is lower semicontinuous if and only if it is continuous, where  $\overline{\mathbb{R}}_+$  is given its Scott topology. The ordering on  $\mathcal{L}X$  is the pointwise ordering. For every monotone map  $\nu\colon \mathcal{C}X\to \overline{\mathbb{R}}_+$ , for every  $h\in \mathcal{L}X$ , there is a Choquet integral  $\int_{x\in X} h(x)\,d\nu$ , defined as the indefinite Riemann integral  $\int_0^\infty \nu(h^{-1}(]t,\infty]))\,dt$ . We need to reprove in part some of the results of [10] on Choquet integrals, since that paper only considers integrals of maps from X to  $\mathbb{R}_+$ ; we will do this in Lemma 3.1 below.

A prevision on a space X is a Scott-continuous map  $F\colon \mathcal{L}X\to\overline{\mathbb{R}}_+$  that is positively homogeneous in the sense that F(ah)=aF(h) for all  $a\in\mathbb{R}_+$  and  $h\in\mathcal{L}X$ . There is a space  $\mathbb{P}X$  of previsions on X, whose topology is generated by sets  $[h>r]\stackrel{\mathrm{def}}{=}\{F\mid F(h)>r\},\,h\in\mathcal{L}X,\,r\in\mathbb{R}_+.$ 

For example, any continuous valuation  $\nu$  on X gives rise to a prevision  $G \colon h \mapsto \int_{x \in X} h(x) \, d\nu$ . Such a prevision is linear, in the sense that G(h+h') = G(h) + G(h') for all  $h, h' \in \mathcal{L}X$ . Let  $\mathbb{P}_P X$  be the subspace of  $\mathbb{P}X$  of linear previsions. In the reverse direction, every linear prevision  $G \in \mathbb{P}_P X$  gives rise to a continuous valuation  $U \mapsto G(\chi_U)$ , where  $\chi_U$  is the characteristic map of the open set U, and the two constructions are inverse of each other. Additionally, those two constructions define continuous maps between  $\mathbf{V}X$  and  $\mathbb{P}_P X$  [24, Satz 4.16]. We will therefore equate continuous valuations with linear previsions.

A prevision is *superlinear* if and only if  $G(h+h') \geq G(h) + G(h')$  for all  $h, h' \in \mathcal{L}X$ . As in [12], we write  $\mathbb{P}_{DP}X$  for the subspace of  $\mathbb{P}X$  consisting of superlinear previsions.

Among the continuous valuations, there are the probability valuations and the subprobability valuations. Similarly, we say that a prevision F is subnormalized (resp., normalized) iff  $F(\mathbf{1}+h) \leq \mathbf{1} + F(h)$  (resp., =) for every  $h \in \mathcal{L}X$ , where  $\mathbf{1}$  is the constant function with value 1. The homeomorphism between  $\mathbf{V}X$  and  $\mathbb{P}_{\mathbf{P}}X$  restricts to homeomorphisms between  $\mathbf{V}_{\leq 1}X$  (resp.,  $\mathbf{V}_{1}X$ ) and the subspace  $\mathbb{P}_{\mathbf{P}}^{\leq 1}X$  (resp.,  $\mathbb{P}_{\mathbf{P}}^{1}X$ ) of subnormalized (resp., normalized) linear previsions on X. We write  $\mathbb{P}_{\mathbf{DP}}^{\leq 1}X$ ,  $\mathbb{P}_{\mathbf{DP}}^{1}X$  for the corresponding spaces of (sub)normalized, superlinear previsions. In general, we write  $\mathbb{P}_{\mathbf{DP}}^{\bullet p}X$ , where  $\bullet$  can be nothing, " $\leq$  1", or "1".

For every topological space X, let  $\mathcal{Q}X$  be the collection of non-empty compact saturated subsets of X, ordered by reverse inclusion  $\supseteq$ . This

is the Smyth powerdomain of X [23]; see also [22, Section 7]. Let  $Q_VX$ be the same set, but with the upper Vietoris topology, whose basic open subsets are  $\Box U \stackrel{\text{def}}{=} \{Q \in \mathcal{Q}X \mid Q \subseteq U\}, U \in \mathcal{O}X$ . We will first use this in item (6) of Lemma 3.1 below. The functions  $\sum_{j=1}^m a_j \mathfrak{u}_{Q_j}$  of item (7) of the same lemma are the (simple) credibilities of [10, Theorem 6.18].

**Lemma 3.1.** The following properties hold, where  $h \in \mathcal{L}X$  and  $\nu$  is a monotonic map from  $\mathcal{O}X$  to  $\overline{\mathbb{R}}_+$ .

- (1) The Choquet integral  $\int_{x \in X} h(x) d\nu$  is linear in  $\nu$ , monotonic and even Scott-continuous in  $\nu$ .
- (2) If  $\nu$  is Scott-continuous, then the Choquet integral is Scott-continuous in h.
- (3) If  $\nu$  is a continuous valuation, then the Choquet integral is also linear in h.
- (4) For every  $U \in \mathcal{O}X$ ,  $\int_{x \in X} \chi_U(x) d\nu = \nu(U)$ . (5) Given any continuous valuation  $\nu$  on  $\mathcal{Q}_V X$ , there is a Scottcontinuous map  $\nu^{\square} \colon \mathcal{O}X \to \overline{\mathbb{R}}_+$  defined by  $\nu^{\square}(U) \stackrel{def}{=} \nu(\square U)$  for every  $U \in \mathcal{O}X$ . Then, for every  $h \in \mathcal{L}X$ , the map  $h^* \colon Q \mapsto \min_{x \in Q} h(x)$  is in  $\mathcal{L}Q_{\mathbf{V}}X$  and  $\int_{x \in X} h(x) d\nu^{\square} = \int_{Q \in \mathcal{Q}_{\mathbf{V}}X} h^*(Q) d\nu$ .
- (6) For every compact saturated subset Q of X, the unanimity game  $\mathfrak{u}_Q \colon \mathcal{O}X \to \overline{\mathbb{R}}_+$ , which maps every  $U \in \mathcal{O}X$  to 1 if  $Q \subseteq U$  and to 0 otherwise, is a Scott-continuous map from  $\mathcal{O}X$  to  $\overline{\mathbb{R}}_+$ .
- (7) Letting  $\nu \stackrel{def}{=} \sum_{j=1}^{m} a_{j} \mathfrak{u}_{Q_{j}}$ , where each  $Q_{j}$  is compact saturated and  $a_{j} \in \mathbb{R}_{+}$ , the map  $F : \mathcal{L}X \to \overline{\mathbb{R}}_{+}$  defined by:

$$F(h) \stackrel{def}{=} \int_{x \in X} h(x) d\nu = \sum_{j=1}^{m} a_j \min_{x \in Q_j} h(x)$$

for every  $h \in \mathcal{L}X$ , is a superlinear prevision.

*Proof.* (1) The fact that the Choquet integral is linear in  $\nu$ , namely that it commutes with scalar products by non-negative real numbers and with addition of continuous valuations, follows from the linearity of indefinite Riemann integration. It is also monotonic in  $\nu$ . In order to show Scottcontinuity, we consider a directed family  $(\nu_i)_{i\in I}$ , with (pointwise) supremum  $\nu$ , and we observe that  $\int_{x\in X} h(x)\,d\nu = \int_0^\infty \sup_{i\in I} \nu_i(h^{-1}(]t,\infty]))\,dt$ . The key is that the maps  $t\mapsto \nu_i(h^{-1}(]t,\infty]))$  are antitone (all antitone maps are Riemann-integrable), and that indefinite Riemann integration of antitone maps f is Scott-continuous in f, see [24, Lemma 4.2]. Therefore  $\int_{x\in X} h(x) d\nu = \sup_{i\in I} \int_0^\infty \nu_i(h^{-1}(]t,\infty]) dt = \sup_{i\in I} \int_{x\in X} h(x) d\nu_i.$ (2) The proof works as Tix's original proof of the same result in the

special case where  $\nu$  is a continuous valuation [24, Satz 4.4], and relies

on [24, Lemma 4.2], just like item (1). Explicitly, let  $(h_i)_{i\in I}$  be a directed family in  $\mathcal{L}X$ , with (pointwise) supremum h. For every  $t\in \mathbb{R}_+$ ,  $h^{-1}(]t,\infty])=\{x\in X\mid \sup_{i\in I}^{\uparrow}h_i(x)>t\}=\bigcup_{i\in I}^{\uparrow}h_i^{-1}(]t,\infty])$ . Therefore,

$$\begin{split} \int_{x \in X} h(x) \, d\nu &= \int_0^\infty \nu(\bigcup_{i \in I} \uparrow h_i^{-1}(]t, \infty])) \, dt \\ &= \int_0^\infty \sup_{i \in I} \uparrow \nu(h_i^{-1}(]t, \infty])) \, dt \\ &= \sup_{i \in I} \uparrow \int_0^\infty \nu(h_i^{-1}(]t, \infty])) \, dt = \sup_{i \in I} \uparrow \int_{x \in X} h_i(x) \, d\nu, \end{split}$$

using the Scott-continuity of  $\nu$  and the Scott-continuity of indefinite Riemann integration of antitone maps.

- (3) This is a result of Tix [24, Satz 4.4].
- (4)  $\int_{x \in X} \chi_U(x) d\nu = \int_0^\infty \nu(\chi_U^{-1}(]t, \infty]) dt = \int_0^1 \nu(U) dt + \int_1^\infty 0 dt = \nu(U).$
- (5) This is as with [10, Lemma 7.5]. The fact that  $\nu^{\square}$  is Scott-continuous follows from the fact that  $\nu$  is, and that the  $\square$  operator is, too. For the latter, observe that for every directed family  $(U_i)_{i\in I}$  of open subsets of X, for every  $Q \in \mathcal{Q}_{\mathsf{V}}X$ ,  $Q \in \square \bigcup_{i\in I}^{\uparrow} U_i$  if and only if  $Q \subseteq \bigcup_{i\in I}^{\uparrow} U_i$ , which is equivalent to  $Q \subseteq U_i$  (namely,  $Q \in \square U_i$ ) for some  $i \in I$ , because Q is compact.

For every  $Q \in \mathcal{Q}_{\mathsf{V}}X$ , the minimum of h(x) when x ranges over Q is reached, since Q is compact and non-empty. For every  $t \in \mathbb{R}_+$ ,  $Q \in h^{*-1}(]t,\infty]$ ) if and only if  $h^*(Q) > t$ . The latter certainly implies that h(x) > t for every  $x \in Q$ , hence that  $Q \in \Box h^{-1}(]t,\infty]$ ). Conversely, if  $Q \in \Box h^{-1}(]t,\infty]$ ), then let us pick  $x \in Q$  such that h(x) is the least value reached by h on Q; then  $h^*(Q) = h(x) > t$ , so  $Q \in h^{*-1}(]t,\infty]$ ). Hence  $h^{*-1}(]t,\infty]$ )  $= \Box h^{-1}(]t,\infty]$ ). This implies that  $h^*$  is in  $\mathcal{L}\mathcal{Q}_{\mathsf{V}}X$ , in particular.

Now:

$$\begin{split} \int_{Q\in\mathcal{Q}_{\mathbf{V}}X}h^*(Q)\,d\nu &= \int_0^\infty \nu(h^{*-1}(]t,\infty]))\,dt \\ &= \int_0^\infty \nu(\Box h^{-1}(]t,\infty])\,dt \\ &= \int_0^\infty \nu^\Box(h^{-1}(]t,\infty])\,dt = \int_{x\in X}h(x)\,d\nu^\Box. \end{split}$$

(6) Monotonicity is clear. For every directed family  $(U_i)_{i\in I}$  of open subsets of X,  $\mathfrak{u}_Q(\bigcup_{i\in I}^{\uparrow} U_i)=1$  if and only if  $Q\in \Box\bigcup_{i\in I}^{\uparrow} U_i$ , which is equivalent to the existence of an  $i\in I$  such that  $Q\in \Box U_i$  (equivalently,  $\mathfrak{u}_Q(U_i)=1$ ), as we have seen at the beginning of the proof of item (5).

(7) That would be a consequence of [10, Propositions 7.2, 7.6], except for the fact that our functions h take their values in  $\mathbb{R}_+$ . We verify that  $\int_{x\in X} h(x)\,d\nu = \sum_{j=1}^m a_j \int_{x\in X} h(x)\,d\mathfrak{u}_{Q_j} = \sum_{j=1}^m a_j \min_{x\in Q_j} h(x)$ : the first equality is by item (1), and the second one is because  $\int_{x\in X} h(x)\,d\mathfrak{u}_{Q_i}$  is equal to  $\int_0^\infty \mathfrak{u}_{Q_i}(h^{-1}(]t,\infty]))\,dt = \int_0^{\min_{x\in Q_i} h(x)} 1\,dt + \int_{\min_{x\in Q_i} h(x)}^\infty 0\,dt = \min_{x\in Q_i} h(x).$ 

It is easy to see that F(h) is superlinear, because  $\min_{x \in Q_i} ah(x) = a \min_{x \in Q_i} h(x)$  and  $\min_{x \in Q_i} (h(x) + h'(x)) \ge \min_{x \in Q_i} h(x) + \min_{x \in Q_i} h'(x)$ , for all  $a \in \mathbb{R}_+$  and  $h, h' \in \mathcal{L}X$ . Scott-continuity comes from the fact that  $F(h) = \int_{x \in X} h(x) \, d\nu$ , where  $\nu \stackrel{\text{def}}{=} \sum_{j=1}^m a_j \mathfrak{u}_{Q_j}$ , that  $\nu$  is Scott-continuous (by item (6)), and by using item (2).

Let us turn to  $Q_V$ . The specialization preordering of  $Q_VX$  is  $\supseteq$ , and in particular  $Q_VX$  is  $T_0$ . The Scott topology on QX is finer than the upper Vietoris topology, and coincides with it when X is locally compact and sober [11, Lemma 8.3.26], and then QX itself is a continuous dcpo [11, Proposition 8.3.25].

 $\mathcal{Q}_{\mathsf{V}}$  is an endofunctor on the category of topological spaces, whose action on continuous maps  $f\colon X\to Y$  is given by  $\mathcal{Q}_{\mathsf{V}}f(Q)\stackrel{\mathrm{def}}{=}\uparrow f[Q]$ , where f[Q] denotes the image of Q under f. That functor is part of a monad [22, Section 7], of which we need to know the unit  $\eta^{\mathcal{Q}}$ : for every space X, for every  $x\in X$ ,  $\eta_X^{\mathcal{Q}}(x)=\uparrow x$ . We also note that  $(\eta_X^{\mathcal{Q}})^{-1}(\Box U)=U$  for every  $U\in\mathcal{O}X$ .

By [12, Lemma 3.20], for every space X, there is a continuous map  $s_{\mathtt{DP}}^{\bullet} \colon \mathbb{P}_{\mathtt{DP}}^{\bullet} X \to \mathcal{Q}_{\mathtt{V}} \mathbb{P}_{\mathtt{P}}^{\bullet} X$  defined by  $s_{\mathtt{DP}}^{\bullet}(F) \stackrel{\mathrm{def}}{=} \{G \in \mathbb{P}_{\mathtt{P}}^{\bullet} X \mid G \geq F\}$ . The ordering  $\leq$  between previsions is the specialization ordering, which is pointwise, and  $\geq$  is the opposite ordering. Up to the homeomorphism between  $\mathbb{P}_{\mathtt{P}}^{\bullet} X$  and  $\mathbf{V}_{\bullet} X$ , we restate the latter as follows.

**Lemma 3.2.** For every topological space X, there is a continuous map  $s_{DP}^{\bullet} \colon \mathbb{P}_{DP}^{\bullet} X \to \mathcal{Q}_{V} \mathbf{V}_{\bullet} X$ , defined by:

$$s_{\mathrm{DP}}^{\bullet}(F) \stackrel{def}{=} \left\{ \nu' \in \mathbf{V}_{\bullet}X \; \middle| \; \forall h \in \mathcal{L}X, \int_{x \in X} h(x) \, d\nu' \geq F(h) \right\}.$$

In order to show that  $\mathbf{V}_{\bullet}X$  is locally compact (if X is), we will need to find enough compact subsets. They will be provided to us by the images of certain superlinear previsions under  $s_{\mathtt{DP}}^{\bullet}$ .

#### 4. The main theorem

We spend most of this section proving the following theorem. We remember that all locally compact spaces are core-compact.

**Theorem 4.1.** For every core-compact space X,  $\mathbf{V}X$  and  $\mathbf{V}_{\leq 1}X$  are locally compact. If X is also compact, then  $\mathbf{V}_1X$  is locally compact.

*Proof.* Replacing X by S(X) if necessary, we may assume that X is locally compact and sober.

A fundamental theorem due to Jones [16, Theorem 5.2] states that for every continuous dcpo P,  $\mathbf{V}_{\leq 1}P$  is a continuous dcpo under the stochastic ordering, and that a basis is given by the *simple valuations*, namely those of the form  $\sum_{i=1}^{n} a_i \delta_{x_i}$ , where each  $a_i$  is in  $\mathbb{R}_+$  and  $x_i \in P$ . The notation  $\delta_x$  refers to the *Dirac valuation* at x, defined by  $\delta_x(U) \stackrel{\text{def}}{=} 1$  if  $x \in U$ , 0 otherwise, for every  $U \in \mathcal{O}X$ .

A similar result holds for  $\mathbf{V}P$  [8, Theorem IV-9.16], and for  $\mathbf{V}_1P$  provided that P is also pointed [7, Corollary 3.3]. (A poset is *pointed* if and only if it has a least element.) We will apply those results to  $P \stackrel{\text{def}}{=} \mathcal{Q}X$ , and we notice that if X is compact, then P is pointed, as X itself will be the least element of P in that case.

Let  $\nu \in \mathbf{V}_{\bullet}X$ , and let  $\mathcal{U}$  be any open neighborhood of  $\nu$ . Then  $\nu$  is in some finite intersection of subbasic open sets  $\bigcap_{i=1}^n [U_i > r_i]$  that is included in  $\mathcal{U}$ , where each  $U_i$  is open in X and  $r_i \in \mathbb{R}_+$ . We consider  $\mu \stackrel{\text{def}}{=} \mathbf{V} \eta_X^{\mathcal{Q}}(\nu) \in \mathbf{V}_{\bullet} \mathcal{Q}_{\mathsf{V}} X$ . We recall that  $\eta_X^{\mathcal{Q}}$  is the unit of the  $\mathcal{Q}_{\mathsf{V}}$  monad, and maps every point  $x \in X$  to  $\uparrow x \in \mathcal{Q}_{\mathsf{V}} X$ . For every open subset U of X,  $\mu(\Box U) = \eta_X^{\mathcal{Q}}[\nu](\Box U) = \nu((\eta_X^{\mathcal{Q}})^{-1}(\Box U)) = \nu(U)$ . It follows that  $\mu$  is in  $\bigcap_{i=1}^n [\Box U_i > r_i]$ . The latter is open in the upper Vietoris topology on  $\mathbf{V}_{\bullet} \mathcal{Q}_{\mathsf{V}} X = \mathbf{V}_{\bullet} P$ , hence in the Scott topology of the stochastic ordering. Since X is locally compact and sober, P is a continuous dcpo, so  $\mathbf{V}_{\bullet} P$  is a continuous dcpo with a basis of simple valuations, and therefore there is a simple valuation  $\xi \stackrel{\text{def}}{=} \sum_{j=1}^m a_j \delta_{Q_j}$  in  $\mathbf{V}_{\bullet} P$  that is way below  $\mu$  and in  $\bigcap_{i=1}^n [\Box U_i > r_i]$ .

We may form  $\xi^{\square}$ , as in Lemma 3.1, item (5): for every  $U \in \mathcal{O}X$ ,  $\xi^{\square}(U) = \xi(\square U)$ . We check easily that  $\xi^{\square}$  is equal to  $\sum_{j=1}^{m} a_{j} \mathfrak{u}_{Q_{j}}$ . Using Lemma 3.1, item (7) allows us to build a superlinear prevision F on X by letting  $F(h) \stackrel{\text{def}}{=} \int_{x \in X} h(x) d\xi^{\square} = \sum_{j=1}^{m} a_{j} \min_{x \in Q_{j}} h(x)$  for every  $h \in \mathcal{L}X$ . Now  $s_{\mathtt{DP}}^{\bullet}(F)$  is a compact saturated subset of  $\mathbf{V}_{\bullet}X$ , by Lemma 3.2. We

Now  $s_{DP}^{\bullet}(F)$  is a compact saturated subset of  $\mathbf{V}_{\bullet}X$ , by Lemma 3.2. We claim that  $\nu$  is in the interior of  $s_{DP}^{\bullet}(F)$ , and that  $s_{DP}^{\bullet}(F)$  is included in  $\mathcal{U}$ ; this will end our proof.

We start by showing that  $s_{\mathtt{DP}}^{\bullet}(F) \subseteq \mathcal{U}$ . Let  $\nu'$  be any element of  $s_{\mathtt{DP}}^{\bullet}(F)$ . In other words, for every  $h \in \mathcal{L}X$ ,  $\int_{x \in X} h(x) \, d\nu' \geq F(h) =$ 

 $\begin{array}{l} \sum_{j=1}^m a_j \min_{x \in Q_j} h(x). \text{ For each } i \in \{1, \cdots, n\}, \text{ we apply this to } h \stackrel{\text{def}}{=} \chi_{U_i}; \\ \text{then } \min_{x \in Q_j} h(x) = \mathfrak{u}_{Q_j}(U_i), \text{ so } F(\chi_{U_i}) = \sum_{j=1}^m a_j \mathfrak{u}_{Q_j}(U_i) = \xi^{\square}(U_i) = \\ \xi(\square U_i), \text{ and therefore } \nu'(U_i) = \int_{x \in X} \chi_{U_i}(x) \, d\nu' \geq F(\chi_{U_i}) = \xi(\square U_i) > r_i, \\ \text{since } \xi \in [\square U_i > r_i]. \text{ Hence } \nu' \in \bigcap_{i=1}^n [U_i > r_i] \subseteq \mathcal{U}. \end{array}$ 

Next, we verify that  $\nu$  is in the interior of  $s_{\mathtt{DP}}^{\bullet}(F)$ . We use the fact that  $\xi$  is way below  $\mu$ , equivalently that  $\mu$  is in the open set  $\uparrow \xi$ . Since  $\mu = \mathbf{V} \eta_X^{\mathcal{Q}}(\nu)$ ,  $\nu$  is in  $(\mathbf{V} \eta_X^{\mathcal{Q}})^{-1}(\uparrow \xi)$ , which is open since  $\mathbf{V} \eta_X^{\mathcal{Q}}$  is continuous. It remains to show that  $(\mathbf{V} \eta_X^{\mathcal{Q}})^{-1}(\uparrow \xi)$  is included in  $s_{\mathtt{DP}}^{\bullet}(F)$ .

For every  $\nu' \in (\mathbf{V}\eta_X^{\mathcal{Q}})^{-1}(\uparrow \xi)$ , by definition  $\xi$  is way below, in particular less than or equal to  $\mu' \stackrel{\text{def}}{=} \mathbf{V}\eta_X^{\mathcal{Q}}(\nu')$ . The latter is such that  $\mu'(\Box U) = \eta_X^{\mathcal{Q}}[\nu'](\Box U) = \nu'((\eta_X^{\mathcal{Q}})^{-1}(\Box U)) = \nu'(U)$  for every  $U \in \mathcal{O}X$ . Hence  $\nu' = \mu'^{\Box}$ . By Lemma 3.1, item (5),  $\int_{x \in X} h(x) d\nu' = \int_{Q \in \mathcal{Q}_{\mathbf{V}}X} h^*(Q) d\mu'$ . Since  $\xi \leq \mu'$ , the latter is larger than or equal to  $\int_{Q \in \mathcal{Q}_{\mathbf{V}}X} h^*(Q) d\xi = \int_{x \in X} h(x) d\xi^{\Box} = F(h)$ , using Lemma 3.1, item (5) once again. We have shown that  $\int_{x \in X} h(x) d\nu' \geq F(h)$  for every  $h \in \mathcal{L}X$ , so  $\nu' \in s_{DP}^{\bullet}(F)$ , as promised.

When X is compact,  $\mathbf{V}_1X = s_{\mathtt{DP}}^{\bullet}(F)$ , where F is the normalized superlinear prevision  $h \in \mathcal{L}X \mapsto \int_{x \in X} h(x) \, d\mathfrak{u}_X = \min_{y \in X} h(y)$ . Indeed, for every probability valuation  $\nu$  on X, for every  $h \in \mathcal{L}X$ ,  $\int_{x \in X} h(x) \, d\nu \geq \int_{x \in X} \min_{y \in X} h(y) \, d\nu = \min_{y \in X} h(y)$ . We therefore obtain the following.

Fact 4.2. If X is compact, then  $V_1X$  is compact.

**Lemma 4.3.** Let  $\bullet$  be nothing, " $\leq 1$ ", or "1". For every space X,  $\mathbf{V}_{\bullet}X$  is sober.

*Proof.* For every space X,  $\mathbf{V}X$  is sober. The argument is due to R. Tix [24, Satz 5.4], following ideas by R. Heckmann (see [15, Section 2.3]). The sober subspaces of a sober space Z coincide with the subsets that are closed in the strong topology on Z [18, Corollary 3.5]. The latter is also known as the Skula topology, and is the smallest one generated by the original topology on Z and all the downwards-closed subsets. In particular, any closed subspace of a sober space is sober, any saturated subspace of a sober space is sober. Hence  $\mathbf{V}_{\leq 1}Y$  is sober, being equal to the closed subspace  $\mathbf{V}Y \setminus [Y > 1]$  of  $\mathbf{V}Y$ , and  $\mathbf{V}_1Y$  is sober, being upwards-closed in  $\mathbf{V}_{\leq 1}Y$ . □

**Corollary 4.4.** V and  $V_{\leq 1}$  restrict to endofunctors on the category of locally compact (resp., locally compact sober) spaces and continuous maps.  $V_1$  restricts to an endofunctor on the category of compact, locally compact (resp., compact, locally compact sober) spaces.

We finish with the mandatory application to spaces of measures, which follows directly, using the considerations developed in Section 2 on the relationship between measures and continuous valuations.

Corollary 4.5. For every hereditarily Lindelöf, LCS-complete space X—in particular, for every quasi-Polish space X—if X is locally compact, then  $\mathcal{M}_{\leq 1}X \cong \mathbf{V}_{\leq 1}X$  are locally compact; if X is locally compact and compact, then  $\mathcal{M}_{1}X \cong \mathbf{V}_{1}X$  are locally compact and compact.

The locally compact, quasi-Polish spaces are exactly the locally compact, sober, second-countable spaces [5, Theorem 44]. It is easy to see that the  $\mathbf{V}_{\bullet}$  functor preserves second countability. Using Lemma 4.3, we obtain our final corollary.

**Corollary 4.6.** For every locally compact quasi-Polish space X,  $\mathcal{M}_{\leq 1}X \cong \mathbf{V}_{\leq 1}X$  are locally compact and quasi-Polish.

#### 5. Conclusion

When trying to show that a space Z is locally compact, the direct approach—which is how we proceeded—consists in picking an arbitrary point  $z \in Z$ , an arbitrary open neighborhood V of z, and to find a compact (saturated) neighborhood Q of z included in V. The main difficulty is in finding enough compact saturated sets Q.

Previous work has shown that  $\mathbf{V}_{\leq 1}X$  is stably compact for every stably compact space X, and gives a hint at what compact saturated subsets of  $\mathbf{V}_{\leq 1}X$  we may need for the task [2, Theorem 39]. (A stably compact space is a compact, locally compact sober space that is *coherent*, in the sense that the intersection of any two compact saturated subsets is compact.) Indeed, in that case, the subsets  $[Q \geq r]^{\leq 1} \stackrel{\text{def}}{=} \{ \nu \in \mathbf{V}_{\leq 1}X \mid \forall U \in \mathcal{O}X, Q \subseteq U \Rightarrow \nu(U) \geq r \}$  form the required family of compact saturated sets, where Q ranges over the compact saturated subsets of X and  $r \in \mathbb{R}_+$ . We might therefore assume that analogous sets  $[Q \geq r]^{\bullet} \stackrel{\text{def}}{=} \{ \nu \in \mathbf{V}_{\bullet}X \mid \forall U \in \mathcal{O}X, Q \subseteq U \Rightarrow \nu(U) \geq r \}$  would be compact saturated in  $\mathbf{V}_{\bullet}X$ , and could be used to form enough compact saturated neighborhoods of points  $\nu \in \mathbf{V}_{\bullet}X$ , when X is locally compact sober—but without coherence (or compactness).

Without using the detour through superlinear previsions, however, it is not completely clear how one might prove that  $[Q \geq r]^{\bullet}$  is compact, to start with. It is true that  $[Q \geq r]^{\bullet}$  is compact saturated in  $\mathbf{V}_{\bullet}X$ , for every compact saturated subset Q of any topological space X, and for every  $r \in \mathbb{R}_+$ . Indeed,  $[Q \geq r]^{\bullet} = s_{\mathrm{DP}}^{\bullet}(F)$ , where F is the superlinear prevision  $h \in \mathcal{L}X \mapsto r \int_{x \in X} h(x) d\mathfrak{u}_Q$ , as one may check by using Lemma 3.1.

However, the proof we have given needs many more compact saturated subsets, and we have obtained them as  $s_{\mathtt{DP}}^{\bullet}(F)$  for superlinear previsions of the form  $h \in \mathcal{L}X \mapsto \int_{x \in X} h(x) \, d \sum_{i=1}^n a_i \mathfrak{u}_{Q_i}$ . In general,  $s_{\mathtt{DP}}^{\bullet}(F)$  is compact saturated in  $\mathbf{V}_{\bullet}X$ , for any superlinear prevision F on X. This naturally leads to the following question.

(1) What are the compact saturated subsets of  $\mathbf{V}_{\bullet}X$ , for an arbitrary topological space X?

In investigating (1), one may restrict X to some interesting subclasses. The answer to (1) is already known for stably compact spaces: the compact saturated subsets of  $\mathbf{V}_{\leq 1}X$  are exactly the intersections of finite unions of sets of the form  $[Q \geq r]^{\leq 1}$  given as above [2]. One should also compare this with Prokhorov's characterization of compact sets of probability measures as those sets that are uniformly tight [20], see also the fundamental paper by Topsøe [25]. In the meantime, one should observe that for every topological space X, there is a continuous map  $r_{\mathrm{DP}} \colon \mathcal{Q}_{\mathsf{V}}(\mathbf{V}_{\bullet}X) \to \mathbb{P}_{\mathrm{DP}}^{\bullet}X$  such that  $r_{\mathrm{DP}} \circ s_{\mathrm{DP}}^{\bullet} = \mathrm{id}_{\mathbb{P}_{\mathrm{DP}}^{\bullet}X}$  and  $s_{\mathrm{DP}}^{\bullet} \circ r_{\mathrm{DP}} \leq \mathrm{id}_{\mathcal{Q}_{\mathsf{V}}(\mathbf{V}_{\bullet}X)}$  [12, Proposition 3.22], and that those maps define a homeomorphism between  $\mathbb{P}_{\mathrm{DP}}^{\bullet}X$  and the subspace  $\mathcal{Q}_{\mathsf{V}}^{cvx}(\mathbf{V}_{\bullet}X)$  of convex elements of  $\mathcal{Q}_{\mathsf{V}}\mathbf{V}_{\bullet}X$  [12, Theorem 4.15]. Hence the convex compact saturated subsets of  $\mathbf{V}_{\bullet}X$  are known: they are exactly the sets  $s_{\mathrm{DP}}(F)$ , where F is a superlinear prevision on X.

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