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▶ To cite this version:

Clément Erignoux, Alexandre Roget, Assaf Shapira, Marielle Simon. Hydrodynamic behavior near dynamical criticality of a facilitated conservative lattice gas. Physical Review E , 2024, 110 (3), pp.L032101. 10.1103/PhysRevE.110.L032101 . hal-04742490

HAL Id: hal-04742490 https://hal.science/hal-04742490v1

Submitted on 6 Jan 2025

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Hydrodynamic behavior near dynamical criticality of a facilitated conservative lattice gas

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(Dated: March 15, 2024)

We investigate a 2*d*-conservative lattice gas exhibiting a dynamical active-absorbing phase transition with critical density ρ_c . We derive the hydrodynamic equation for this model, showing that all critical exponents governing the large scale behavior near criticality can be obtained from two independent ones. We show that as the supercritical density approaches criticality, distinct length scales naturally appear. Remarkably, this behavior is different from the subcritical one. Numerical simulations support the critical relations and the scale separation.

Models displaying dynamical phase transitions have attracted increasing scrutiny in recent years. Such models are tightly related to self-organizing criticality: open systems dynamically adjust their density in order to reach a critical state at density ρ_c , often displaying non-trivial scaling properties. This phenomenon manifests itself, in a closed system, as a dynamical phase transition: below ρ_c , the system reaches an absorbing state, while above ρ_c , it remains in a quasi-stationary active state.

A fundamental example of such a model is the constrained *conservative lattice qas* (CLG) [1], also referred to as *facilitated exclusion process* in the recent literature. It is defined as an *exclusion particle system* (*i.e.* any system site cannot contain more than one particle) on a ddimensional lattice, where so-called *active particles* jump randomly at rate 1 to each empty nearest neighbor [2]. A particle is considered *active* if at least one of its neighboring sites is also occupied, and the total number of particles is conserved. Related models featuring an absorbing phase transition have generated an intense research activity, like for instance the paradigm Manna sandpile model [3-6]. In particular many of these models, including the CLG, exhibit a hyperuniform critical state [7, 8], for which we still have a limited knowledge. The CLG has been investigated numerically in [1, 7–9] when $d \geq 2$ and theoretically in [10–16] when d = 1. We focus here on

the 2-dimensional case, and recall some previous results already obtained in the 1-dimensional case.

Clearly, this system remains active whenever $\rho > 1/2$, and could reach an absorbing state whenever $\rho \leq 1/2$. It appears, however, that in dimension $d \geq 2$, the dynamical critical density ρ_c is strictly smaller than 1/2. That is, in the regime $(\rho_c, 1/2]$, even though an absorbing state will be ultimately reached in any finite system, on physically relevant timescales a quasi-stationary active state is observed. In order to illustrate this phenomenon, the average absorption time is numerically represented in Fig. 1 in both subcritical and supercritical regimes.

The CLG is reflection symmetric and isotropic, and therefore its macroscopic density profile ρ , taken in the diffusive space-time scaling limit, is expected to be a solution to the parabolic equation $\partial_t \rho = \operatorname{div}(D(\rho)\nabla\rho)$ with scalar diffusion coefficient $D(\rho)$. In the subcritical regime $\rho < \rho_c$ the particles become blocked in subdiffusive time scales (see Fig. 1a), therefore $D(\rho) = 0$. When the initial profile has both subcritical and supercritical regions, the supercritical phase progressively invades the subcritical "frozen" areas. That is, one should interpret the above hydrodynamic equation as a Stefan problem. In dimension 1 this result is established mathematically in [14], and exploits the explicit expression of the stationary states, a feature that is lost in higher dimensions.

In this letter we explore the scaling properties of the two-dimensional model, with a particular focus on the active phase. We study the critical exponents for all relevant macroscopic quantities, both theoretically and numerically, as it has been done for other models, for

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FIG. 1. Median absorption time in a closed box, of size changing from 5 to 100. In the subcritical phase (a) the absorption time grows sub-linearly with the system size. In the supercritical phase (b) it grows exponentially fast, and the figure illustrates nicely that the geometric correlation length, which separates the absorbing regime from the quasi-stationary regime, is roughly $\xi \approx 20$ at $\rho = 0.334$.

instance in [17]. We are able to deduce relationships between those critical exponents, which are of independent interest, and check them by simulations.

Macroscopic observables. Of particular interest are the critical and near criticality behavior of the model. It has been noted in [7] that the CLG could have two separate length scales near criticality. While in their simulations these two scales seem to coincide, we will see here that in the supercritical phase they differ. Let us define:

• The geometric correlation length ξ_{\perp} : this is the scale which is mostly used in the literature [18, Section 3.3], and is the one discussed in [1]. It describes the spread of activity. More precisely, to sustain activity, particle clusters must self-activate, *i.e.*, a particle activates its neighbor, which further activates its neighbors, until closing a cycle and reactivating the particle we started with. The diameter of this self-activated structure is described by the geometric correlation length ξ_{\perp} .

This means that, for a finite system of size L, if $L \ll \xi_{\perp}$, then there is no quasi-stationary state, and in that case activity will decay until dying out. On the other hand, if $L \gg \xi_{\perp}$, then the activity behaves in the same manner as $L = \infty$.

• The 2-point correlation length $\xi_{\times}(\rho)$: This is the length over which the 2-point correlation function decays. This scale is referred to as the *crossover length* in [7], where the authors show, in the subcritical phase, that: below ξ_{\times} the absorbing state is *hyperuniform* [19, 20]; above ξ_{\times} it is Poisson-like.

Both length scales diverge when approaching criticality, as $\xi_{\perp} \sim (\rho - \rho_c)^{-\nu_{\perp}}$ and $\xi_{\times} \sim (\rho - \rho_c)^{-\nu_{\times}}$, for some critical exponents ν_{\perp} and ν_{\times} , which we now investigate.

In [1, 7], several other critical exponents are determined. Notably, in the latter the authors show that the CLG's absorbing state is hyperuniform, *i.e.* the number of particles N in a ball or radius R has standard deviations of order R^{ζ} , for ζ smaller than d/2.

We are interested in the hydrodynamic behavior of the CLG, whose diffusion coefficient $D(\rho)$ behaves, close to ρ_c , as $(\rho - \rho_c)^{\alpha}$ for some exponent α . In order to understand the noise's amplitude, we also consider the compressibility $\chi(\rho) \sim (\rho - \rho_c)^{\gamma}$. For the CLG, the dominant parameter for the system is the density of active particles, $\rho_a(\rho)$. However, the notion of active particles is in fact ambiguous, since one may or may not count as ac*tive* particles who are fully surrounded by other particles (and therefore cannot move). For this reason, we distinguish between $\rho_a(\rho) \sim (\rho - \rho_c)^{\beta}$, the density of particles having at least one occupied neighbor (which is the one considered in [1]), and the activity $a(\rho) \sim (\rho - \rho_c)^b \leq 3\rho_a$, which counts the local number of possible jumps. We will see further that in fact both exponents β and b coincide (Fig. 3). This means that the perimeter of clusters of active particles is of the same order as their volume.

Relations between critical exponents. By numerical simulations we are able to get all the critical exponents in the case d = 2. In dimension d = 1, we have exact values, as discussed below.

A number of relations can be derived between the relevant critical exponents [18]. Most of them are standard, a detailed derivation will be given in a companion article [21]. The first one ties the compressibility to the particle fluctuations and the activity correlation length, as

$$\gamma = \nu_{\times} (d - 2\zeta). \tag{1}$$

This relation can be obtained by considering the structure factor $S_{\rho}(k)$ (see [22, Section II.2.1]), which encapsulates the 2-point statistics of the distribution at a fixed time [19]. By the scaling hypothesis, $S_{\rho}(k)$ can only depend on k via the combination $\xi_{\times}k$. Moreover, $S_{\rho}(0) = \chi(\rho)$, and at criticality $S_{\rho_c}(k) \sim C|k|^{d-2\zeta}$ when |k| is small. These three facts impose the form

$$S_{\rho}(k) = \chi \left(1 + \frac{C}{\chi \xi_{\times}^{d-2\zeta}} |\xi_{\times} k|^{d-2\zeta} \right), \tag{2}$$

and hence $\chi \xi_{\times}^{d-2\zeta}$ remains of order 1 as $\rho \to \rho_c$. This implies equation (1).

A similar scaling relation can be obtained for the geometric correlation length. Indeed, at scales smaller than ξ_{\perp} the system looks critical, so that the critical density fluctuations are larger than $\rho - \rho_c$, and "hide" the off-criticality. The scale ξ_{\perp} is therefore characterized by the relation $\xi_{\perp}^{\zeta-d} \approx \rho - \rho_c$. This yields the following relation:

$$\nu_{\perp}(d-\zeta) = 1. \tag{3}$$

The next relation stems from Einstein's relation $D = \sigma/\chi$ and the fact that the noise amplitude is determined by the number of possible particle jumps $\sigma = a$ (see [22, Section II.2] for instance): this leads to

$$\alpha = b - \gamma. \tag{4}$$

Finally, the following relation is a consequence of a particular property of the CLG, called *gradient condition* [22, 23], which relies on well-chosen jump rates for the system. Under this condition,

$$\partial_t \langle n_i \rangle = \sum_{j \sim i} \left\{ \langle n_{a,j} \rangle - \langle n_{a,i} \rangle \right\},\tag{5}$$

where $\langle n_i \rangle$ (resp. $\langle n_{a,i} \rangle$) denotes the average number of particles (resp. active particles) at site *i*. At the macroscopic level, this identity translates as

$$\partial_t \rho = \Delta \big(\rho_a(\rho) \big), \tag{6}$$

and yields in turn that $D(\rho) = \rho'_a(\rho)$. Near criticality, this implies

$$\alpha = \beta - 1. \tag{7}$$

Note that equations (4) and (7) give $\beta - b = 1 - \gamma$. As an interesting consequence, the fact that $\beta = b$, *i.e.* that clusters of active particles have volume and perimeter of the same order, implies $\gamma = 1$. In Table I we give all exponents in both d = 1 and d = 2 cases. The former are exact values, while the latter are numerically computed.

Hydrodynamics and scale invariance. Near criticality, we are interested in the macroscopic evolution of $u := \rho - \rho_c$. It evolves according to the fluctuating hydrodynamic equation

$$\partial_t u = \operatorname{div} \left(D \nabla u + \sqrt{2D\chi} W \right).$$
 (8)

The noise W depends on the scale at which we look: at distances above ξ_{\times} correlations are small and W is white noise, while for distances smaller than ξ_{\times} the noise W will have non-trivial correlations:

$$\langle W(0,0) \cdot W(x,t) \rangle = \begin{cases} \delta(t)\delta(x), & |x| > \xi_{\times}, \\ \delta(t)|x|^{-\vartheta}, & |x| < \xi_{\times}, \end{cases}$$
(9)

obs.	D	χ	ξ_{\perp}	$\xi_{ imes}$	$\operatorname{Var}(N)$	ρ_a	a	
exp.	α	γ	$ u_{\perp} $	$\nu_{ imes}$	ζ	β	b	z
d = 1	0	1	1	1	0	1	1	2
d = 2	-0.38	$1 \ and \ 1.07$	0.77	1.8	0.70	0.62	0.62	1.51
			0.78^{a}		$0.775^{\rm b}$	0.63^{a}		1.52^{a}

^a obtained in [1]

 $^{\rm b}$ obtained in [7]

TABLE I. Critical exponents related to observables, in d = 1and d = 2. The 1-dimensional exponents are exact, see below. In the 2-dimensional case, the first line is obtained either directly from our simulation results, or extracted from scaling relations. The second line contains simulation results taken from previous articles. In our case, the exponents ν_{\times} and ζ are extracted from the simulation of Fig. 4. The exponents β and b are taken from the one of Fig. 3a. The exponent γ is simulated twice: the value 1 obtained from Fig. 3 and equation (4). The value 1.07 is obtained from Fig. 4. The exponent α is calculated using equation (7), ν_{\perp} from equation (3) and z from (11).

for some exponent ϑ . In the regime below ξ_{\times} , the density fluctuations are proportional to $\ell^{\zeta-d}$, hence equation (8) must be invariant under the parameter rescaling

$$(u, x, t) \mapsto \left(\frac{u}{\ell^{d-\zeta}}, \frac{x}{\ell}, \frac{t}{\ell^z}\right).$$
 (10)

This forces ϑ to be equal $1 - \zeta/d$, and

$$z = (\zeta - d)(1 - \beta) + 2.$$
(11)

We emphasize that on a length above ξ_{\times} the scale invariance is not the same, and in particular the dynamic exponent z will change. This scale separation has been noted qualitatively in [1].

One-dimensional case. The one-dimensional case d = 1 has been recently under scrutiny, and its macroscopic evolution is now quite well understood. It has been proved rigorously [13, 14] that the critical density is given by $\rho_c = 1/2$, and the diffusive supercritical phase progressively invades the subcritical phase via flat interfaces, until either one of the phases disappears. In this respect, a crucial feature of the one-dimensional case lies in its explicit supercritical grand canonical states π_{ρ} either parametrized by the density $\rho \geq 1/2$ or the active density $\rho_a(\rho) = (2\rho - 1)/\rho$. These grand canonical states can be defined sequentially, by filling an arbitrary site with probability ρ , and then following each empty site by a particle with probability 1, but each particle by another particle with probability $\rho_a(\rho)$.

Precisely, the hydrodynamic limit in d = 1 is given by $\partial_t \rho = \partial_x (D(\rho) \partial_x \rho)$, with diffusion coefficient

$$D(\rho) = \rho'_a(\rho) = \rho^{-2} \mathbf{1}_{\{\rho > \rho_c\}}$$
(12)

and critical exponent $\alpha = 0$. The explicit construction of the grand-canonical state π_{ρ} yields the other observables for $\rho \geq \rho_c$, as well as their critical exponent (see [15]): namely the activity $a(\rho) = \rho^{-1}(1-\rho)(2\rho-1)$ with b = 1, and the compressibility $\chi(\rho) = \rho(1-\rho)(2\rho-1)$, with $\gamma = 1$. Moreover, the stationary measure can be seen as a nearest-neighbor spin system with chemical potential μ , and an interaction which gives infinite costs to two neighboring empty sites. This can be solved using standard methods involving the transfer matrix (see [24, Chapter 6]), which here is given by

$$\begin{pmatrix} 0 & e^{-\mu} \\ 1 & e^{-\mu} \end{pmatrix}.$$

All the relevant quantities and exponents for the onedimensional model are listed in Table I.

Numerical simulations. We note that in finite systems the critical density depends slightly on the geometry, so that in the analysis of the simulated data we do not enforce a single critical density for systems of different sizes or boundary conditions.

In order to numerically derive the diffusion coefficient and verify relation (7), we simulate a cylindrical system, *i.e.* periodic in the vertical direction, of size L put in contact at the left and right boundaries with particle reservoirs with respective densities λ_l and λ_r . More specifically, at the boundary, particles are removed at rate $1 - \lambda_l$, $1 - \lambda_r$, and empty sites are filled at rate λ_l , λ_r . In our simulations, boundary particles are always considered active.

When $\lambda_l = \lambda_r = \lambda$ the system reaches a quasistationary state with density $\rho(\lambda)$. For our particular choice of boundary interactions, $\rho_a(\rho(\lambda)) = \lambda$, meaning that the reservoirs enforce the density of active particles and not the total density of particles. This relation is, however, not universal, and depends on the exact boundary dynamics considered.

In order to estimate the diffusion coefficient, we fix $\lambda_l = \lambda$ and $\lambda_r = \lambda + \varepsilon$ with small $\varepsilon > 0$. We measure the total net number of particles N_t crossing the system up to time t. In general, we expect the current to be proportional to ε

$$\frac{N_t}{t} = K(\lambda)\varepsilon, \tag{13}$$

where $K(\lambda) = D(\rho)\rho'(\lambda)$. Since our system is gradient and for our specific choice of reservoirs, we should obtain K = 1. which is verified by our simulation, see Fig. 2. In particular this shows that $\alpha = \beta - 1$.

In more general models (for instance when the gradient property is not satisfied) we do not necessarily expect K to be constant, but still of order 1 (namely, neither diverging nor decaying as $\rho \to \rho_c$).

The scaling exponents β and b can be found by simulating the system with cylindrical geometry, maintaining one reservoir at density $\lambda_l = 0$ and the other one at density $\lambda_r = 1$. We then measure, at each section x of the cylinder, $\rho(x)$, $\rho_a(x)$ and a(x). See Fig. 3.

Thanks to the gradient property of the model and our choice of reservoirs, ρ_a grows linearly with the horizontal



FIG. 2. N_t as a function of t for different reservoir densities. See equation (13).



FIG. 3. Simulating $\rho(x)$, $\rho_a(x)$ and a(x) in a system with reservoirs $\lambda_l = 0$, $\lambda_r = 1$.

distance, from λ_l at x = 0 to λ_r at x = 1. This is verified in our simulation (Fig. 3a). Thanks to this result, the relation $\rho_a \propto (\rho - \rho_c)^{\beta}$ can then be written as $\rho \sim \rho_c + x^{1/\beta}$. By fitting $\rho(x)$ in Fig. 3a we obtain $\beta = 1.60^{-1} =$ 0.62. Finally, noting that for small x the activity a is linear in x (Fig. 3b), we conclude $\beta = b$.

In order to find the remaining exponents, we estimate the structure factor $S_{\rho}(k)$ for different values of ρ . This



FIG. 4. We show here a collapse of $S_{\rho}(k)$ for different values of ρ . Fitting the data shows that $\chi(\rho) = 0.61(\rho - 0.3361)^{-1.07}$ and $\xi_{\times} = 0.03(\rho - 0.3361)^{-1.77}$. Indeed, after this rescaling the curves $S_{\rho}(k)$ collapse as expressed in equation (2). The fit (black curve) is given by $S_{\rho}(k) = 0.61(\rho - 0.3361)^{1.07} + 0.07|k|^{0.60}$.

is done on a system with periodic boundaries (in both directions). By fitting the data to equation (2), posing $\chi = C_{\chi}(\rho - \rho_c)^{\gamma}$ and $\xi_{\times} = C_{\times}(\rho - \rho_c)^{-\nu_{\times}}$, we obtain the values in Table I. See Fig. 4.

All the simulations used in this article are open access, available at https://github.com/alexandreroget/2D_FacilitatedExclusionProcess.

Conclusion. In this article, we discussed the critical scaling for the CLG. We saw that there are three independent critical exponents, β , b, and ζ , that all other exponents ($\alpha, \gamma, \nu_{\perp}, \nu_{\times}, z$) could be deduced from. Due to repulsion, active cluster sizes are of order 1, so their perimeter is proportional to the volume, thus $\beta = b$ and all scaling is described by two independent exponents.

We numerically computed several critical exponents for the 2d-CLG (see Table I), and confronted them both with those critical relations, and the numerical values in [1] and [7] for CLG with simultaneous jumps. We obtained very good agreement between them; with the exception of ζ and ν_{\times} . While our numerical values fit the theoretical relations introduced above, they are different from those of [7]. The reason seems to be that we approach the critical state from $\rho > \rho_c$, while [7] do from $\rho < \rho_c$. Recently, [8] went further investigating the approach to hyperuniformity from the subcritical regime; on the contrary to [7], they find that the critical exponent ν_{\times} (which they denote γ_1) is different from ν_{\perp} .

We emphasize the existence of two distinct correlation lengths, one characterizing the size of self-activating clusters, and the other one characterizing the two-points correlation decay. This distinction is a specific feature of the quasi-stationary regime (ρ_c , 1/2), and for this reason does not exist in one dimension. We conjecture that it is a common feature of any dimension $d \ge 2$, because the rigid structure necessary to reach a frozen state at density $\rho = 1/2 - \varepsilon$ results in the quasi-stationary regime.

Unlike in the one-dimensional case, the diffusion coefficient $D(\rho)$ has negative exponent (see Table I), and is therefore discontinuous at ρ_c . We note that the diffusion term operating in the supercritical phase instantly creates at the boundary non-zero density gradients. Therefore, this discontinuity does not create a quantitative different behavior than the 1*d*-Stefan problem, which has a finite critical diffusion coefficient (12). That is, subcritical regions are frozen while particles in supercritical regions diffuse; and the interfaces between them move as the supercritical regions invade the subcritical ones. The divergence of D is balanced out by small non-zero density gradients, resulting in a finite current. Hence, as in dimension one, the interfaces move with finite speed.

ACKNOWLEDGMENTS

This project is partially supported by the ANR grant MICMOV (ANR-19-CE40-0012) of the French National Research Agency (ANR). It has received funding from the European Research Council (ERC) under the European Union's Horizon 2020 research and innovative program (grant agreement n° 715734), and from Labex CEMPI (ANR-11-LABX-0007-01).

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