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Left heart hemodynamics simulations with fluid-structure interaction and reduced valve modeling

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Abstract. The combination of reduced models of cardiac valve dynamics with a one-way kinematic uncoupling of blood flow and electromechanics is a widespread approach for reducing the complexity of cardiac hemodynamics simulations. This comes however with a number of shortcomings: artificial pressure oscillations, missing isovolumetric phases and valve laws without precise continuous formulation. This paper is aimed at overcoming these three difficulties while still mitigating computational cost. A novel reduced model of valve dynamics is proposed in which unidirectional flow is enforced in a mathematically sound fashion. Artificial pressure oscillations are overcome by considering a fluid-structure interaction model, which couples bi-ventricular electromechanics and blood flow in the left cavities. The interface coupling is solved in a partitioned fashion via an unconditionally stable loosely coupled scheme. A priori energy estimates are derived for both the continuous coupled problem and its numerical approximation. The benefits and limitations of the proposed approaches are illustrated in a comprehensive numerical study.

Keywords. Cardiac hemodynamics, fluid-structure interaction, reduced valve modeling, loosely coupled scheme.

1 Introduction

The numerical simulation of cardiac hemodynamics (that is, of blood flows in the chambers of heart) opens many fascinating perspectives for enhanced device design, treatment planning and clinical decision (see, e.g., [45, 49] for recent reviews), notably because computer simulations provide direct access to mechanical quantities (such as local pressures and shear stresses) which can hardly be measured in a non-invasive fashion. The genuine multi-physics nature of the heart function makes these simulations a permanent challenge in computational modeling and scientific computing. Indeed, a complete mathematical model of cardiac hemodynamics must involve also the interaction with different additional complex phenomena, such as cardiac electromechanics and valve dynamics.

The simulation of all the fluid-structure interaction phenomena involved in the heart is a complex problem, with only a few studies reported in the literature so far (see [38, 30, 26, 64, 63]). Heart valves are definitely a bottleneck of the problem, particularly due to their large deflections, fast dynamics and contact phenomena at high pressure-drops. Fortunately, not all

cardiac hemodynamics simulations require a complete multi-physics model of the heart, and alternative reduced modeling options can be considered depending on the relevant physics driving the phenomena of interest (see, e.g., [45, 49]).

With the purpose of reducing the computational complexity of the problem, several reduced models of cardiac hemodynamics have been proposed in the literature. One of the most widespread approaches consists in combining a reduced modeling of the valve dynamics with a one-way kinematic uncoupling of blood flow and cardiac electromechanics. In short, motion data, coming either from electromechanical simulations (see, e.g., [3, 39, 61, 70, 68, 69]) or from imaging measurements (see, e.g., [44, 43, 56, 18, 62, 40, 6, 7, 67]), is enforced on the boundaries of the fluid cavities, while the opening and closing of the valves is described by switching boundary conditions (see, e.g., [8, 4]) or via resistive immersed methods (see [2, 25, 61, 68]).

These modeling simplifications come however at a price. First, unphysical pressure oscillations are observed during the opening/closing phases of the valves. This often requires the prescription of artificial refractory periods. Second, the isovolumetric phases are neglected in the cardiac cycle, since the fluid pressure within the ventricle is not well defined in a fully enclosed domain with Dirichlet data. In [61] (see also [68]), this issue has been overcome by leveraging the natural leakage induced by the resistive immersed valve model (for moderate values of the resistance), but it requires an a priori knowledge of the ventricle pressure. And third, the opening/closing valve laws generally lack mathematical soundness. They are indeed defined in a time semi-discrete framework (as a discrete algorithm rather than as a mathematical model), without a clear continuous counterpart. The contributions of this paper are aimed at overcoming these three issues.

We first introduce a novel reduced valve model in which unidirectional flow is enforced in a mathematically sound fashion through an inequality constraint on the fluid velocity across the immersed valve. This naturally avoids the need of artificially switching between different interface conditions or between different values of the resistance. Related unilateral constraints have been proposed in another context with the purpose of deriving energy estimates for the Navier-Stokes equations with outflow boundary conditions (see [66, 53, 52]). In the context of kinematical uncoupling, numerical evidence indicates that this approach reduces the magnitude of the spurious pressure oscillations but it does not remove them.

We postulate that these artificial oscillations are due to the lack of compatibility between the kinematical data enforced on the cardiac cavities and the status of the reduced valve model. We investigate this hypothesis by proposing a cardiac hemodynamics model which combines the above mentioned reduced valve dynamics models with a fluid-structure interaction model in the left ventricle. Alternative fluid-structure interaction models for the left-ventricle have been proposed in [17, 47, 54, 9, 10]. A salient feature of the proposed approach is that it couples a bi-ventricular model of active cardiac mechanics with the Navier-Stokes system in the left heart. Furthermore, in order to mitigate computational complexity, notably with respect to the kinematically uncoupling approach, the interface coupling is numerically solved via a Robin-Robin loosely coupled scheme reported in [12] (see also [13, 11]), which is expected to deliver nearly optimal accuracy. An a priori energy estimate, guaranteeing unconditional energy stability, is derived for the resulting fully discrete method. A comprehensive numerical study, involving a simplified and a realistic left-heart geometry, illustrates the accuracy and robustness of the proposed approach. Numerical evidence indicates, in particular, that fluid-structure interaction removes the above mentioned spurious pressures oscillations, irrespectively of the considered reduced valve model.

The rest of the paper is organized as follows. Section 2 presents the different mathematical models considered in this paper: from active cardiac mechanics, blood flow and reduced valve modeling to kinematical uncoupling and fluid-structure interaction. The numerical approximation of the proposed coupled fluid-structure interaction system is addressed in Section 3. We introduce a loosely coupled scheme and derive an energy stability estimate. Section 4 is devoted the description and discussion of the numerical examples. Finally, a summary of the main results and some directions of future work are drawn in Section 5.

2 Problem setting and mathematical models

In this section, we introduce a distributed fluid-structure interaction model of the left ventricle. The myocardium is described as a passive hyperelastic material with an active law along the muscle fibers (Section 2.2), whereas fluid flow within the left cavities is modeled by the incompressible Navier-Stokes equations with a reduced modeling of the valve dynamics (Section 2.3).

2.1 Geometrical setting

We denote by $\Omega \subset \mathbb{R}^3$ the reference computational domain, partitioned as $\Omega_f \cup \Omega_s$, where Ω_f stands for the left heart fluid cavities and Ω_s represents the ventricles myocardium (see Figure 1). The fluid domain can be split into three regions $\Omega_f^{la} \cup \Omega_f^{ao} \cup \Omega_f^{lv}$, which respectively correspond to the fluid cavities in the left atria, ascending aorta and left ventricle. For the solid domain we consider the partition $\Omega_s^{lv} \cup \Omega_s^{rv}$, where Ω_s^{lv} and Ω_s^{rv} respectively denote the left and right ventricular myocardiums. As mentioned above, the present study focuses on the fluid-structure interaction between the left ventricular flow and the myocardium mechanics. This interaction takes place at the left ventricle endocardium interface, denoted by $\Gamma_1 \stackrel{\text{def}}{=} \partial\Omega_s^{lv} \cap \partial\Omega_f^{lv}$.

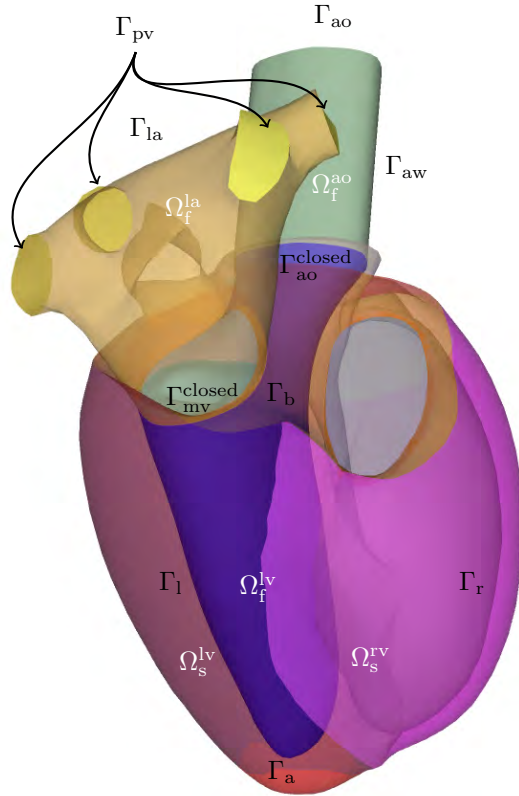


Figure 1: Geometrical description of the reference computational domain Ω .

2.2 Cardiac mechanics model

The mechanical response of the myocardium is described by the fundamental law of dynamics, formulated in a total Lagrangian approach, in terms of the deformation map $\phi : \Omega_s \times \mathbb{R}^+ \rightarrow \mathbb{R}^3$. This mapping describes the position of each point in the reference configuration at any given time instant. The solid displacement field $\mathbf{y} : \Omega_s \times \mathbb{R}^+ \rightarrow \mathbb{R}^3$ is defined as $\mathbf{y}(\mathbf{x}, t) \stackrel{\text{def}}{=} \phi(\mathbf{x}, t) - \mathbf{x}$ for all $\mathbf{x} \in \Omega_s$. We introduce the deformation gradient of the solid $\mathbf{F}_s \stackrel{\text{def}}{=} \nabla \phi = \mathbf{I} + \nabla \mathbf{y}$, where \mathbf{I} denotes the identity matrix. The Jacobian of the solid system is given by the relation $J_s \stackrel{\text{def}}{=} \det \mathbf{F}_s$. The boundary of Ω_s (see Figure 1) is assumed to be partitioned as $\Gamma_r \cup \Gamma_a \cup \Gamma_b \cup \Gamma_v \cup \Gamma_l$, where Γ_r denotes the endocardium of the right ventricle, Γ_a the apex of the heart, Γ_b the base of the heart, Γ_v the annulus of the mitral and tricuspid valves, and Γ_l the endocardium of the left ventricle. For simplicity, the solid is assumed to be clamped on Γ_v , and a viscoelastic boundary condition is enforced on $\Gamma_a \cup \Gamma_b$, which emulates the support provided by the surrounding tissue (e.g., as the pericardium).

The mechanical response of the cardiac tissue is described in terms of the second Piola-Kirchhoff stress tensor Σ , which is assumed to be composed of a passive contribution Σ_p , and an active contribution Σ_a . We relate both contributions using an extension of the classical Hill-Maxwell rheology scheme, which takes into account the nonlinear response, as outlined in [16, 41, 51]. Therefore, the overall second Piola-Kirchhoff stress tensor of the cardiac tissue can be expressed as $\Sigma = \Sigma_p + \Sigma_a$. The passive behavior, primarily influenced by the collagen and elastin matrix surrounding the heart fibers, is fully three-dimensional (3D) and is composed of hyperelastic and viscous contributions:

$$\Sigma_p = \frac{\partial W_e(\mathbf{E})}{\partial \mathbf{E}} + \frac{\partial W_v(\dot{\mathbf{E}})}{\partial \dot{\mathbf{E}}}, \quad (1)$$

where \mathbf{E} stands for the Green-Lagrange strain tensor, defined by the relation $\mathbf{E} \stackrel{\text{def}}{=} \frac{1}{2}(\mathbf{F}_s^T \mathbf{F}_s - \mathbf{I})$. The cardiac tissue is modeled as nearly incompressible and transversely isotropic, with a privileged direction along the fibers. The hyperelastic potential is given by the Holzapfel-Ogden constitutive law (see [37]), expressed as:

$$W_e = \mu_1(J_1 - 3) + \mu_2(J_2 - 3) + C_0 \exp(C_1(J_1 - 3)^2) + C_2 \exp(C_3(J_4 - 1)^2) + \kappa(J_s - 1) - \kappa \ln(J_s),$$

where J_1, J_2, J_4 denote the reduced invariants and $\mu_1, \mu_2, C_0, C_1, C_2, C_3$ are model parameters adjusted on the specific regions of the heart tissue. On the other hand, we model the viscous pseudo-potential with the simple relation:

$$W_v = \frac{\nu}{2} \mathbf{I} : (\dot{\mathbf{E}})^2, \quad (2)$$

where ν denotes the solid viscosity coefficient.

The active behavior, driven by the chemical reactions within myocytes that induce the contraction and relaxation of sarcomeres (resulting in the subsequent contraction and relaxation of the myocardium along the fibers of the heart), is modeled following the approach outlined in [16, 41]. The dynamics of the active stiffness k_c and of the contractile stress τ_c produced by the sarcomeres are hence given by

$$\begin{cases} \dot{k}_c = -(|u_e| + \alpha_d |\dot{e}_c|) k_c + n_0 k_0 |u_e|_+, \\ \dot{\tau}_c = -(|u_e| + \alpha_d |\dot{e}_c|) \tau_c + \dot{e}_c k_c + n_0 \sigma_0 |u_e|_+, \end{cases} \quad (3)$$

where e_c represents the extension along the fibers, which is further elaborated below, and u_e denotes the chemical activation (or electrical input) and $|x|_+ \stackrel{\text{def}}{=} \max\{x, 0\}$. The term $\alpha_d |\dot{e}_c|$ accounts for the bridges destruction upon rapid length changes. The parameter $0 \leq n_0 \leq 1$ is a reduction factor that accounts for the Frank-Starling effect, which describes the relation of the contraction with the current strain of the sarcomeres. The constant k_0 is the maximum stiffness, while σ_0 accounts for the solid contractibility.

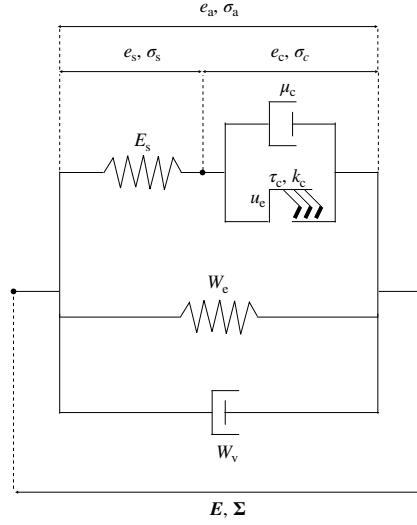


Figure 2: Rheological model from [16, 51].

Following [16, 51], the passive and active elements of the myocardium tissue are assembled using the rheological scheme of Figure 2. The total stress acting along the fiber is composed of contractile and elastic stresses, respectively denoted σ_c and σ_s . The contractile stress is given by the constitutive relation

$$\sigma_c = \tau_c + \mu_c \dot{e}_c, \quad (4)$$

where $\mu_c > 0$ is the dissipation coefficient. On the other hand, the elastic stress produced in the sarcomeres (due to the elastic response of the Z disks) can be modeled as

$$\sigma_s = E_s e_s, \quad (5)$$

where E_s represents the Young modulus of the elastic component of the sarcomeres and e_s is the elastic extension of these components. The overall stress along the fibers, denoted by σ_a , can be related with the contractile and elastic stresses according to the following relations (see [16]):

$$\sigma_a = \frac{\sigma_c}{1 + 2e_s} = \frac{\sigma_s}{1 + 2e_c}. \quad (6)$$

On the other hand, the extension along the fibers, denoted by e_a , is related with the contractile and elastic extensions as

$$1 + 2e_a = (1 + 2e_s)(1 + 2e_c). \quad (7)$$

Additionally, e_a is given in terms of the Green-Lagrange strain tensor as

$$e_a \stackrel{\text{def}}{=} \mathbf{a}^T \mathbf{E} \mathbf{a}, \quad (8)$$

where \mathbf{a} stands for the unit vector tangential to the cardiac fibers. The final relation for the active behaviour is described as

$$\boldsymbol{\Sigma}_a = \sigma_a \mathbf{a} \otimes \mathbf{a}.$$

Note that from, (7), we get

$$e_s = \frac{e_a - e_c}{1 + 2e_c}, \quad (9)$$

so that this expression can be used to eliminated e_s in the above relations. In particular, owing to (5) and (6), we have

$$\sigma_a = E_s \frac{e_a - e_c}{(1 + 2e_c)^2}. \quad (10)$$

Similarly, by combining (4), (6) and (9), we get the following dynamics for e_c

$$\mu_c \dot{e}_c + \tau_c = E_s \frac{(e_a - e_c)(1 + 2e_a)}{(1 + 2e_c)^3}.$$

We can then use (8) to express e_a in terms of \mathbf{E} in the two previous relations, which together with (3) closes the active modeling.

A lumped parameter (0D) model is used to describe the blood flow in the right cardiac cavities (see, e.g., [51]). The coupling with ventricular tissue is operated by the relations

$$\begin{cases} \mathbf{F}_s \boldsymbol{\Sigma} \mathbf{n}_s = -P_r \mathbf{n}_s & \text{on } \Gamma_r, \\ \int_{\Gamma_r} J_s \mathbf{u}_s \cdot \mathbf{F}_s^{-T} \mathbf{n}_s = Q_r(P_r, P_{ar,r}, P_{at,r}), \end{cases}$$

The first enforces the dynamic balance on the fluid-solid interface Γ_r , in terms of the unknown homogeneous fluid pressure P_r , while the second corresponds to the balance of mass in the right ventricular cavity, with Q_r denoting the net flux across the valves given by the function

$$Q_r(P_r, P_{ar,r}, P_{at,r}) \stackrel{\text{def}}{=} \begin{cases} K_{at,r}(P_r - P_{at,r}) & \text{if } P_r \leq P_{at,r}, \\ 0 & \text{if } P_{at,r} \leq P_r \leq P_{ar,r}, \\ K_{ar,r}(P_r - P_{ar,r}) & \text{if } P_r \geq P_{ar,r}. \end{cases} \quad (11)$$

Here, $P_{ar,r}$, $P_{at,r}$ respectively denote the right atrium and pulmonary artery pressures, respectively, while $K_{at,r}$, $K_{ar,r}$ stand for the conductances of the valves in the open configurations. Furthermore, a two-stage Windkessel system is used to model the impact of the external circulation on the dynamics of the unknown arterial pressure $P_{ar,r}$ (see, e.g., [36]), viz.,

$$\begin{cases} C_{p,r} \dot{P}_{ar,r} + \frac{P_{ar,r} - P_{d,r}}{R_{p,r}} = |Q_r|_+, \\ C_{d,r} \dot{P}_{d,r} + \frac{P_{d,r} - P_{ar,r}}{R_{p,r}} = \frac{P_{vs,r} - P_{d,r}}{R_{d,r}}, \end{cases} \quad (12)$$

where $P_{d,r}$ stands for the unknown distal pressure, $P_{vs,r}$ for a given remote venous pressure and $R_{p,r}$, $C_{p,r}$ and $R_{d,r}$, $C_{d,r}$ respectively denote the proximal and distal parameters.

The resulting active cardiac mechanics system reads therefore as follows: find the displacement $\mathbf{y} : \Omega_s \times \mathbb{R}^+ \rightarrow \mathbb{R}^3$, the velocity $\mathbf{u}_s : \Omega_s \times \mathbb{R}^+ \rightarrow \mathbb{R}^3$, with $\mathbf{u}_s = \partial_t \mathbf{y}$, the extension along the fibers $e_c : \Omega_s \times \mathbb{R}^+ \rightarrow \mathbb{R}$, the active stiffness $k_c : \Omega_s \times \mathbb{R}^+ \rightarrow \mathbb{R}^+$, the active tension $\tau_c : \Omega_s \times \mathbb{R}^+ \rightarrow \mathbb{R}$, the right ventricular pressure $P_r : \mathbb{R}^+ \rightarrow \mathbb{R}$, the right proximal pressure $P_{ar,r} : \mathbb{R}^+ \rightarrow \mathbb{R}$ and the right distal pressure $P_{d,r} : \mathbb{R}^+ \rightarrow \mathbb{R}$ such that

$$\left\{ \begin{array}{l} \rho_s \partial_t \mathbf{u}_s - \text{div}(\mathbf{F}_s \boldsymbol{\Sigma}(\mathbf{E}, e_c)) = \mathbf{0} \quad \text{in } \Omega_s, \\ \boldsymbol{\Sigma} = \frac{\partial W_e}{\partial \mathbf{E}} + \frac{\partial W_v}{\partial \dot{\mathbf{E}}} + \frac{E_s(\mathbf{a}^T \mathbf{E} \mathbf{a} - e_c)}{(1 + 2e_c)^2} \mathbf{a} \otimes \mathbf{a} \quad \text{in } \Omega_s, \\ \mu_c \dot{e}_c + \tau_c = E_s \frac{(\mathbf{a}^T \mathbf{E} \mathbf{a} - e_c)(1 + 2\mathbf{a}^T \mathbf{E} \mathbf{a})}{(1 + 2e_c)^3} \quad \text{in } \Omega_s, \\ \dot{k}_c = -(|u_e| + \alpha_d |\dot{e}_c|) k_c + n_0 k_0 |u_e|_+ \quad \text{in } \Omega_s, \\ \dot{\tau}_c = -(|u_e| + \alpha_d |\dot{e}_c|) \tau_c + \dot{e}_c k_c + n_0 \sigma_0 |u_e|_+ \quad \text{in } \Omega_s, \\ \mathbf{y} = \mathbf{0} \quad \text{on } \Gamma_v, \\ \mathbf{F}_s \boldsymbol{\Sigma} \mathbf{n}_s + a \mathbf{y} + b \mathbf{u}_s = \mathbf{0} \quad \text{on } \Gamma_a \cup \Gamma_b, \\ \mathbf{F}_s \boldsymbol{\Sigma} \mathbf{n}_s = -P_r \mathbf{n}_s \quad \text{on } \Gamma_r, \\ \int_{\Gamma_r} J_s \mathbf{u}_s \cdot \mathbf{F}_s^{-T} \mathbf{n}_s = Q_r(P_r, P_{ar,r}, P_{at,r}), \\ C_{p,r} \dot{P}_{ar,r} + \frac{P_{ar,r} - P_{d,r}}{R_{p,r}} = |Q_r|_+, \\ C_{d,r} \dot{P}_{d,r} + \frac{P_{d,r} - P_{ar,r}}{R_{p,r}} = \frac{P_{vs,r} - P_{d,r}}{R_{d,r}}, \end{array} \right. \quad (13)$$

where ρ_s stands for the solid density and $a, b > 0$ are given coefficients of the viscoelastic support boundary condition on $\Gamma_a \cup \Gamma_b$. The type of boundary conditions imposed on the left endocardium wall Γ_1 depends on the type of model coupling approach considered with the fluid in the left ventricle. This will be discussed in Section 2.4 below.

2.3 Fluid model with reduced valve dynamics

The dynamics of the fluid flow within the left cavities are described by the incompressible Navier-Stokes equations in arbitrary Lagrangian-Eulerian (ALE) formulation. The current configuration of the fluid domain, denoted by $\Omega_f(t)$, is hence parametrized by the so-called ALE map $\mathcal{A} : \Omega_f \times \mathbb{R}^+ \rightarrow \mathbb{R}^3$, with $\mathcal{A}_t \stackrel{\text{def}}{=} \mathcal{A}(\cdot, t)$ one-to-one and so that $\Omega_f(t) = \mathcal{A}(\Omega_f, t)$, for all $t > 0$. The ALE map \mathcal{A} can be given in terms of the displacement of the fluid domain $\mathbf{y}_f : \Omega_f \times \mathbb{R}^+ \rightarrow \mathbb{R}^3$, as $\mathcal{A}(\mathbf{x}, t) \stackrel{\text{def}}{=} \mathbf{x} + \mathbf{y}_f(\mathbf{x}, t)$. Note that both \mathcal{A} and \mathbf{y}_f are arbitrarily defined in the interior of Ω_f . With the ALE map, we can define the computational domain velocity, also called ALE velocity, as $\mathbf{w} = \partial_t \mathcal{A}$, the gradient of deformation $\mathbf{F} \stackrel{\text{def}}{=} \nabla \mathcal{A}$ and the Jacobian $J \stackrel{\text{def}}{=} \det \mathbf{F}$.

The boundary of the fluid domain Ω_f is assumed to be partitioned as $\Gamma_{1a} \cup \Gamma_{aw} \cup \Gamma_{pv} \cup \Gamma_{ao} \cup \Gamma_1$ (see Figure 1), where $\Gamma_{1a} \subset \partial\Omega_f^{1a}$ denotes the left atrium wall, $\Gamma_{ao} \subset \partial\Omega_f^{ao}$ the wall of the ascending aorta, $\Gamma_{pv} \subset \partial\Omega_f^{1a} \setminus \Gamma_{1a}$ the inlet of the pulmonary veins left atrium and $\Gamma_{ao}^{\text{out}} \subset \partial\Omega_f^{1a} \setminus \Gamma_{ao}$ the outlet of the ascending aorta. Furthermore, the closed configuration of the mitral and aortic valves are represented through two immersed surfaces, denoted by Γ_{mv} and Γ_{ao} , respectively, oriented with the normal vector \mathbf{n}_f along the flow direction.

Remark 1. For a given field f defined in the current configuration $\Omega_f(t)$, we shall use the notation \hat{f} to defined its corresponding ALE description in Ω_f , by composing with the ALE map, namely, $\hat{f}(\mathbf{x}, t) \stackrel{\text{def}}{=} f(\mathcal{A}(\mathbf{x}, t), t) \quad \forall \mathbf{x} \in \Omega_f$. Conversely, a given field defined in the reference configuration Ω_f can also be transported into the current configuration by composition with \mathcal{A}_t^{-1} . For the sake of simplicity, this composition is omitted. For instance, \mathbf{w} in (14)₁ below has to be read as $\mathbf{w} \circ \mathcal{A}_t^{-1}$.

The fluid problem in the left cavities with a reduced model of the valve dynamics consists in finding the fluid velocity $\hat{\mathbf{u}} : \Omega_f \times \mathbb{R}^+ \rightarrow \mathbb{R}^3$, and the fluid pressure $\hat{p} : \Omega_f \times \mathbb{R}^+ \rightarrow \mathbb{R}$, such that

$$\left\{ \begin{array}{l} \rho_f (\partial_t \mathbf{u}|_{\mathcal{A}} + (\mathbf{u} - \mathbf{w}) \cdot \nabla \mathbf{u}) - \text{div} \boldsymbol{\sigma}(\mathbf{u}, p) + \sum_{i \in \{\text{mv}, \text{ao}\}} \mathbf{f}_{\Gamma_i}(\mathbf{u} - \mathbf{w}, p) \delta_{\Gamma_i} = \mathbf{0} \quad \text{in } \Omega_f(t), \\ \text{div } \mathbf{u} = 0 \quad \text{in } \Omega_f(t), \\ \mathbf{u} = \mathbf{0} \quad \text{on } \Gamma_{1a} \cup \Gamma_{ao}, \\ \boldsymbol{\sigma}(\mathbf{u}, p) \mathbf{n}_f + \frac{\rho_f}{2} |\mathbf{u} \cdot \mathbf{n}_f|_- \mathbf{u} = -P_{\text{pv}, \text{ao}} \mathbf{n}_f \quad \text{on } \Gamma_{\text{pv}} \cup \Gamma_{\text{ao}}, \end{array} \right. \quad (14)$$

with ρ_f standing for the fluid density, δ_{Γ_i} for the Dirac measure on the immersed surface Γ_i and $\boldsymbol{\sigma}(\mathbf{u}, p)$ for the fluid Cauchy stress tensor, given by:

$$\boldsymbol{\sigma}(\mathbf{u}, p) \stackrel{\text{def}}{=} -p \mathbf{I} + 2\mu_f \boldsymbol{\varepsilon}(\mathbf{u}), \quad \boldsymbol{\varepsilon}(\mathbf{u}) \stackrel{\text{def}}{=} \frac{1}{2} (\nabla \mathbf{u} + \nabla \mathbf{u}^T),$$

where $\mu_f > 0$ denotes the dynamic viscosity of the fluid. Furthermore we have used the general notation $f \stackrel{\text{def}}{=} \hat{f} \circ \mathcal{A}_t^{-1}$, for any field \hat{f} defined in the reference configuration Ω_f .

As boundary conditions, we impose a non-slip condition on $\Gamma_{1a} \cup \Gamma_{aw}$, while we consider normal tractions on $\Gamma_{\text{pv}} \cup \Gamma_{\text{ao}}$. The enforced pressure $P_{\text{pv}, \text{ao}}(t)$ is analytically given in Γ_{pv} , while in Γ_{ao} it is determined through the one-stage Windkessel model. Furthermore, in order to circumvent the potential backflow induced numerical instabilities on Neumann boundaries (see, e.g., [23]), we include the following dissipative term, $\frac{\rho_f}{2} |\mathbf{u} \cdot \mathbf{n}_f|_- \mathbf{u}$, with $|x|_- \stackrel{\text{def}}{=} \max\{0, -x\}$. Finally, the term $\mathbf{f}_{\Gamma_i}(\mathbf{u} - \mathbf{w}, p)$ represents the fluid stress jump $\llbracket \boldsymbol{\sigma}(\mathbf{u}, p) \mathbf{n}_f \rrbracket$ induced by the opening and closing dynamics of the valve Γ_i , with the notation

$$\llbracket f \rrbracket \stackrel{\text{def}}{=} f^+ - f^-, \quad \llbracket f \mathbf{n} \rrbracket \stackrel{\text{def}}{=} \llbracket f \rrbracket \mathbf{n}, \quad f^\pm(\mathbf{x}) \stackrel{\text{def}}{=} \lim_{\epsilon \rightarrow 0^\pm} (f(\mathbf{x} + \epsilon \mathbf{n}_f)) \quad \forall \mathbf{x} \in \Gamma_i.$$

The term $\mathbf{f}_{\Gamma_i}(\mathbf{u} - \mathbf{w}, p)$ can be modeled in different ways. In this work, we consider the resistive immersed surface (RIS) approach and we propose as well a novel reduced valve modeling approach, with superior mathematical foundations.

2.3.1 Resistive immersed surface valve model

In the RIS model, introduced in [2] (see also [25, 61]), the expression of $\mathbf{f}_{\Gamma_i}(\mathbf{u} - \mathbf{w}, p)$ is given by a distributed Ohm's law, namely,

$$\mathbf{f}_{\Gamma_i}(\mathbf{u} - \mathbf{w}, p) = R_{\Gamma_i}(t)(\mathbf{u} - \mathbf{w}) \quad \text{on } \Gamma_i, \quad (15)$$

where $R_{\Gamma_i}(t)$ plays the role of a time-dependent resistance which regulates the fluid flow across the valve Γ_i . Typically, $R_{\Gamma_i}(t)$ vanishes when the valve is open and takes a large value R_{closed} whenever the valve is closed. The transition between

Algorithm 1 Explicit resistance update in the RIS valve model.

```

if  $R_{\Gamma_i}^{n-1} = R_{\text{closed}}$  (closed valve) then
  if  $\int_{\Gamma_i} \llbracket p^{n-1} \rrbracket > 0$  then
     $R_{\Gamma_i}^n = 0$ 
  else
     $R_{\Gamma_i}^n = R_{\text{closed}}^n$ 
  end if
else if  $R_{\Gamma_i}^{n-1} = 0$  (open valve) then
  if  $\int_{\Gamma_i} (\mathbf{u}^{n-1} - \mathbf{w}^n) \cdot \mathbf{n}_f \leq 0$  then
     $R_{\Gamma_i}^n = R_{\text{closed}}^n$ 
  else
     $R_{\Gamma_i}^n = 0$ 
  end if
end if

```

these two states of the valve depends on both the current status of the valve (closed or open) and on the nature of the flow across Γ_i . Roughly, the basic idea consists in closing the valve when the relative flow rate becomes negative (or smaller than a given tolerance) and opening the valve when the pressure jump across the valve reaches a positive value. The dependence of R_{Γ_i} on $\mathbf{u} - \mathbf{w}$ and p is hence rather intricate. In fact, instead of providing an explicit continuous expression of R_i in terms of $\mathbf{u} - \mathbf{w}$ and p , the RIS model is often formulated in a time semi-discrete framework by setting the valve resistance at time level n , $R_{\Gamma_i}^n$, as a function of $R_{\Gamma_i}^{n-1}$, $\mathbf{u}^{n-1} - \mathbf{w}^{n-1}$ and p^{n-1} via the procedure reported in Algorithm 1 (see [2]). Furthermore, refractory times and continuous transitions of the resistance are often necessary to mitigate the impact of pressure oscillations observed during the opening and closing of the valves.

2.3.2 Velocity-constrained valve model

We introduce here a novel reduced model for the valves, which, unlike the RIS model, has a sound mathematical formulation. The main idea of this modeling approach consists in enforcing unidirectional flow via an inequality constraint on the normal relative velocity at the interface Γ_i . This yields the optimality conditions

$$(\mathbf{u} - \mathbf{w}) \cdot \mathbf{n}_f \geq 0, \quad \llbracket \boldsymbol{\sigma}(\mathbf{u}, p) \mathbf{n}_f \rrbracket \cdot \mathbf{n}_f \geq 0, \quad \llbracket \boldsymbol{\sigma}(\mathbf{u}, p) \mathbf{n}_f \rrbracket \cdot \mathbf{n}_f (\mathbf{u} - \mathbf{w}) \cdot \mathbf{n}_f = 0 \quad \text{on } \Gamma_i, \quad (16)$$

with $i \in \{\text{ao}, \text{mv}\}$. Note that the stress jump $\llbracket \boldsymbol{\sigma}(\mathbf{u}, p) \mathbf{n}_f \rrbracket \cdot \mathbf{n}_f$ across the interface Γ_i corresponds to the (scalar) Lagrange multiplier associated with the inequality constraint $(\mathbf{u} - \mathbf{w}) \cdot \mathbf{n}_f \geq 0$. Thus, the second relation simply enforces that it has to be positive (when the valve is closed) or zero (when the valve is open). Finally, the third corresponds to the so-called complementary condition.

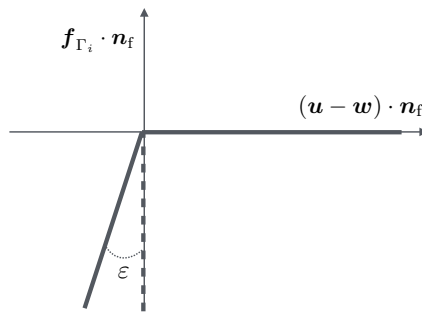


Figure 3: Graphical representation of the penalized velocity constraint (19) as a regularization of the ideal graph (dotted).

The optimality conditions (16) can equivalently be rewritten as the following non-linear identity (see, e.g., [19, Chapter 6]):

$$\llbracket \boldsymbol{\sigma}(\mathbf{u}, p) \mathbf{n}_f \rrbracket \cdot \mathbf{n}_f = \frac{1}{\varepsilon} \left| (\mathbf{u} - \mathbf{w}) \cdot \mathbf{n}_f - \varepsilon \llbracket \boldsymbol{\sigma}(\mathbf{u}, p) \mathbf{n}_f \rrbracket \cdot \mathbf{n}_f \right|_- \quad \text{on } \Gamma_i \quad (17)$$

for all $\varepsilon > 0$. In this work, we consider a penalized version of (17), which amounts to take ε sufficiently small, so that the stress contribution $\varepsilon \llbracket \boldsymbol{\sigma}(\mathbf{u}, p) \mathbf{n}_f \rrbracket \cdot \mathbf{n}_f$ in the right-hand side of (17) can be neglected. Furthermore, we assume no tangential friction, viz.,

$$\llbracket \boldsymbol{\sigma}(\mathbf{u}, p) \mathbf{n}_f \rrbracket \cdot \boldsymbol{\tau}_f = 0 \quad \text{on } \Gamma_i, \quad (18)$$

where $\boldsymbol{\tau}_f$ denotes the tangential basis vectors on Γ_i . We hence consider the following expression for \mathbf{f}_{Γ_i} :

$$\mathbf{f}_{\Gamma_i}(\mathbf{u} - \mathbf{w}, p) = -\frac{1}{\varepsilon} |(\mathbf{u} - \mathbf{w}) \cdot \mathbf{n}_f|_- \mathbf{n}_f \quad \text{on } \Gamma_i, \quad (19)$$

which is graphically represented in Figure 3.

There are several fundamental differences between the reduced valve models given by (15) and (18)-(19). First, the open and closing dynamics in (19) are entirely driven by the local sign of $(\mathbf{u} - \mathbf{w}) \cdot \mathbf{n}_f$ on Γ_i , without the need of the explicit switch between resistances of Algorithm 1. Second, in contrast to (15), the relation (19) can be straightforwardly combined with an implicit time-stepping scheme. This introduces a genuine non-linear term in the discrete problem, which can be handled in the fluid solver with a few Newton iterations (as in the numerical results of Section 4). Finally, it is worth noting that (owing to (18)) the fluid can slip tangentially along the valve whenever it is closed, which is not the case of (15). This could be avoided by adding a suitable penalty term on the tangential velocity in (18). This variant is not explored in this work.

2.3.3 Open valve configuration

In order to obtain a physiological flow pattern within the left ventricle (see, e.g., [48, 61]), the open configuration of the mitral valve, denoted here by $\Gamma_{mv}^{\text{open}}$ (see Figure 4), must be integrated within the blood flow model (14). To this purpose, a term similar to (15), supported on $\Gamma_{mv}^{\text{open}}$ and with associated resistance $R_{\Gamma_{mv}^{\text{open}}}$, is added we add to the momentum conservation equation (14)₁.

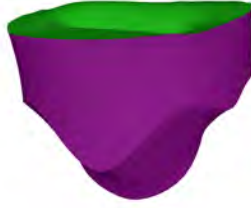


Figure 4: Geometry of the mitral valve: closed configuration (in green) and open configuration (in purple).

In the case of the RIS valve model of Section 2.3.1, the value of $R_{\Gamma_{mv}^{\text{open}}}$ is simply given in terms of the $R_{\Gamma_{mv}}$ (see, e.g., [2, 61]), that is,

$$R_{\Gamma_{mv}^{\text{open}}} = \begin{cases} 0 & \text{if } R_{\Gamma_{mv}} = R_{\text{closed}}, \\ R_{\text{closed}} & \text{if } R_{\Gamma_{mv}} = 0. \end{cases}$$

In the velocity-constrained model (Section 2.3.2), since there is no switch between resistances, the open configuration is activated in terms of the relative flow rate across the closed configuration, $Q_{mv} \stackrel{\text{def}}{=} \int_{\Gamma_{mv}} (\mathbf{u} - \mathbf{w}) \cdot \mathbf{n}_f$, as follows:

$$R_{\Gamma_{mv}^{\text{open}}} = \begin{cases} 0 & \text{if } Q_{mv} \leq Q_{\text{min}}, \\ R_{\text{closed}} & \text{if } Q_{mv} > Q_{\text{min}}, \end{cases}$$

where Q_{min} stands for a user-defined minimal flow tolerance which characterizes the closed valve configuration.

2.4 Model coupling approaches

In this work, cardiac hemodynamics are simulated by considering two different types of modeling coupling approaches on the left ventricle interface Γ_1 : kinematical uncoupling or one-way approach (KU) and fluid-structure interaction (FSI).

2.4.1 Kinematically uncoupled model

In this modeling approach, the fluid system (14) is solved with a prescribed motion of the fluid cavity $\Omega^f(t)$ through the relations

$$\begin{cases} \mathbf{y}_f = \mathcal{L}(\mathbf{y}_{\text{data}}), & \mathbf{w} = \partial_t \mathbf{y}_f, & \mathcal{A} = \mathbf{I}_{\Omega_f} + \mathbf{y}_f, & \Omega_f(t) = \mathcal{A}(\Omega_f, t), \\ \mathbf{u} = \mathbf{w} & \text{on } \Gamma_1. \end{cases} \quad (20)$$

Here, $\mathbf{y}_{\text{data}} : \Gamma_1 \times \mathbb{R}^+ \rightarrow \mathbb{R}^3$ denotes a given displacement of the left ventricle endocardium Γ_1 and the symbol \mathcal{L} stands for a (possibly nonlinear) lifting operator from Γ_1 to Ω_f . In practice, \mathbf{y}_{data} can be obtained from imaging measurements (see, e.g., [44, 43, 56, 18, 62, 40, 6, 7, 67]) or from electromechanical simulations (see, e.g., [3, 39, 61, 70, 68, 69]). In the latter

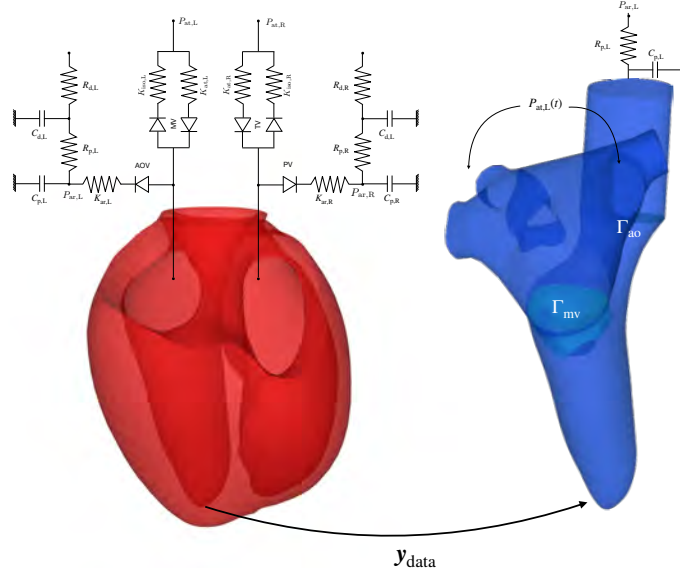


Figure 5: One-way kinematical uncoupling approach in the left ventricle.

case, this amounts to solve (13) with a lumped parameter description of the fluid also in the left heart, namely, by adding the relations

$$\begin{cases} \mathbf{F}_s \boldsymbol{\Sigma}(\mathbf{E}, e_c) \mathbf{n}_s = -P_1 \mathbf{n}_s & \text{on } \Gamma_1, \\ \int_{\Gamma_1} J_s \mathbf{u}_s \cdot \mathbf{F}_s^{-T} \mathbf{n}_s = Q_1(P_1, P_{ar,1}, P_{at,1}), \end{cases} \quad (21)$$

where P_1 , $P_{at,1}$ and $P_{ar,1}$ respectively stand for the pressure in the left ventricle, left atria and aorta, and Q_1 denotes a net flux valve function similar to (11). Finally, a two-stage Windkessel model, similar to (12), is considered to describe the dynamics of the unknown pressure $P_{ar,1}$. This approach is schematized in Figure 5.

2.4.2 Coupled fluid-structure interaction model

In this modeling approach, the dynamics of the solid (13) and of the fluid (14) are coupled through the following standard interface coupling conditions on the endocardial interface Γ_1 :

$$\begin{cases} \mathbf{y}_f = \mathcal{L}(\mathbf{y}|_{\Gamma_1}), & \mathbf{w} = \partial_t \mathbf{y}_f, & \mathcal{A} = \mathbf{I}_{\Omega_f} + \mathbf{y}_f, & \Omega_f(t) = \mathcal{A}(\Omega_f, t), \\ & & \mathbf{u} = \mathbf{u}_s \circ \mathcal{A}_t^{-1} & \text{on } \Gamma_1(t), \\ & \mathbf{F}_s \boldsymbol{\Sigma} \mathbf{n}_s = -J \hat{\boldsymbol{\sigma}}(\mathbf{u}, p) \mathbf{F}^{-T} \hat{\mathbf{n}}_f & \text{on } \Gamma_1. \end{cases} \quad (22)$$

The first relation enforces the so-called geometrical compatibility condition, the second corresponds to the kinematic continuity while the third enforces the dynamic equilibrium at the fluid-solid interface Γ_1 . This approach is schematized in Figure 6.

We conclude this section by providing an a priori energy estimate for the coupled system given by (13), (14) and (22).

A priori energy estimate. We define the total energy of the system as

$$\mathcal{E}(t) \stackrel{\text{def}}{=} \frac{\rho_f}{2} \|\mathbf{u}\|_{0, \Omega_f(t)}^2 + \frac{\rho_s}{2} \|\mathbf{u}_s\|_{0, \Omega_s}^2 + \int_{\Omega_s} W_e(\mathbf{y}) + \frac{1}{2} \int_{\Omega_s} E_s |e_s|^2 + \int_{\Omega_s} U_c + \frac{a}{2} \|\mathbf{y}\|_{\Gamma_a \cup \Gamma_b}^2 + \frac{C_{p,r}}{2} |P_{ar,r}|^2 + \frac{C_{d,r}}{2} |P_{d,r}|^2,$$

where the first two terms represent the instantaneous kinetic energy of the fluid and the solid, respectively. The third term corresponds to the elastic energy of the solid and the fourth term to the (passive) elastic energy of the heart fibers. The fifth term accounts for the microscopic elastic energy of the actin-myosin bridges, with U_c denoting the density of elastic energy stored in the sarcomeres and whose dynamics are given by the following relation (see [16]):

$$\dot{U}_c = -(|u_e| + \alpha_d |\dot{e}_c|) U_c + \tau_c \dot{e}_c + n_0 U_0 |u_e|_+, \quad (23)$$

where $U_0 > 0$ stands for the initial elastic energy in the sarcomeres.

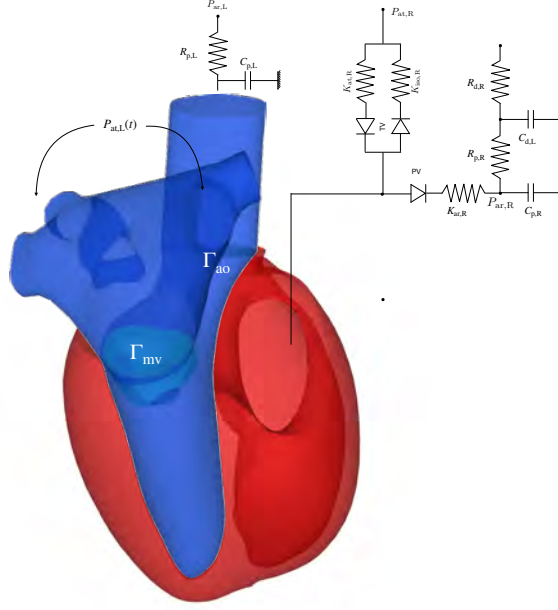


Figure 6: FSI coupling approach in the left ventricle.

Remark 2. As outlined in [16], from the relation (3) it follows that $k_c \in [0, k_0]$, provided that $k_c(0) \in [0, k_0]$. Furthermore, it follows from (23) that $U_c \geq \tau_c^2 / (2k_c) \geq 0$.

We also introduce the total energy dissipation rate of the system as

$$\begin{aligned} \mathcal{D}(t) \stackrel{\text{def}}{=} & 2\mu_f \|\boldsymbol{\varepsilon}(\mathbf{u})\|_{0, \Omega_f(t)}^2 \, ds + \sum_{i \in \{\text{mv}, \text{ao}\}} \int_{\Gamma_i} \mathbf{f}_{\Gamma_i} \cdot \mathbf{u} + \int_{\Omega_s} (|u_e| + \alpha_d |\dot{e}_c|) U_c + \int_{\Omega_s} \mu_c |\dot{e}_c|^2 + \int_{\Omega_s} \frac{\partial W_v}{\partial \dot{\mathbf{E}}} : \dot{\mathbf{E}} \\ & + b \|\mathbf{u}_s\|_{\Gamma_a \cup \Gamma_b}^2 + \left(K_{\text{ar},r} |P_r - P_{\text{ar},r}|_+^2 + K_{\text{at},r} |P_r - P_{\text{at},r}|_-^2 + \frac{|P_{\text{d},r} - P_{\text{ar},r}|^2}{R_{\text{p},r}} + \frac{|P_{\text{d},r}|^2}{R_{\text{d},r}} \right). \end{aligned}$$

Here, the first and second terms correspond to the dissipation induced, respectively, by the viscosity of the fluid and by the reduced modeling of the valves. Note, in particular, that the second term is non negative whenever the valves are fixed (i.e., $\mathbf{w}|_{\Gamma_i} = \mathbf{0}$). The third term represents the energy dissipated during the binding and unbinding mechanisms and the fourth the passive dissipation within the sarcomeres. Finally, the last two terms correspond respectively to the passive viscosity of the cardiac tissue and the dissipation induced by the reduced valve and circulation models.

The next result provides an a priori energy estimate for the coupled system (13), (14) and (22).

Theorem 1. Let $(\mathbf{y}, \mathbf{u}_s, e_c, k_c, \tau_c, \mathbf{y}_f, \mathbf{u}, p, P_r, P_{\text{ar},r}, P_{\text{d},r})$ be solution of the coupled system (13), (14) and (22). The following energy identity holds

$$\mathcal{E}(t) + \int_0^t \mathcal{D}(t) = \mathcal{E}(0) + \int_0^t \int_{\Omega_s} n_0 U_0 |u_e|_+ - \sum_{i \in \{\text{pv}, \text{ao}\}} \int_0^t \int_{\Gamma_i} P_i \mathbf{u} \cdot \mathbf{n}_f + \int_0^t \left(\frac{P_{\text{vs},r} P_{\text{d},r}}{R_{\text{d},r}} - K_{\text{at},r} P_{\text{at},r} |P_r - P_{\text{at},r}|_- \right), \quad (24)$$

where the second term in the right-hand side represents the positive work produced by the actin-myosin engines and the third and fourth terms the work delivered by the external pressures.

Proof. The proof follows by combining energy arguments from [27] and [16]. We first proceed by taking the scalar product of (13)₁ with \mathbf{u}_s and of (14)₁ with \mathbf{u} . By integrating the resulting expressions over Ω_s and $\Omega_f(t)$, respectively, and by adding them and using the interface conditions (22) and the boundary conditions in (13) and (14), we get the following fundamental identity:

$$\begin{aligned} & \underbrace{\int_{\Omega_f(t)} \rho_f \partial_t \mathbf{u} \cdot \mathbf{A} \cdot \mathbf{u} + \rho_f \int_{\Omega_f(t)} (\mathbf{u} - \mathbf{w}) \cdot \nabla \mathbf{u} \cdot \mathbf{u} + 2\mu \int_{\Omega_f(t)} |\boldsymbol{\varepsilon}(\mathbf{u})|^2 + \sum_{i \in \{\text{mv}, \text{ao}\}} \int_{\Gamma_i} \mathbf{f}_{\Gamma_i} \cdot \mathbf{u} + \sum_{i \in \{\text{pv}, \text{ao}\}} \frac{\rho_f}{2} \int_{\Gamma_i} |\mathbf{u} \cdot \mathbf{n}_f|_- |\mathbf{u}|^2}_{T_1} \\ & + \underbrace{\rho_s \int_{\Omega_s} \partial_t \mathbf{u}_s \cdot \mathbf{u}_s + \int_{\Omega_s} \boldsymbol{\Sigma} : D_{\mathbf{y}} \mathbf{E} \cdot \mathbf{u}_s + \int_{\Gamma_a \cup \Gamma_b} (a\mathbf{y} + b\mathbf{u}_s) \cdot \mathbf{u}_s + P_r \int_{\Gamma_r} J_s \mathbf{F}_s^{-T} \mathbf{n}_s \cdot \mathbf{u}_s}_{T_2} = - \underbrace{\sum_{i \in \{\text{pv}, \text{ao}\}} \int_{\Gamma_i} P_i \mathbf{u} \cdot \mathbf{n}_f}_{T_3}, \quad (25) \end{aligned}$$

where the linear operator $D_{\mathbf{y}}\mathbf{E}$ is defined as

$$D_{\mathbf{y}}\mathbf{E} \cdot \mathbf{v}_s \stackrel{\text{def}}{=} \frac{1}{2} (\mathbf{F}_s^T \nabla \mathbf{v}_s + (\nabla \mathbf{v}_s)^T \mathbf{F}_s).$$

We now proceed by estimating each term T_i , $i = 1, 2, 3$, separately. Using a change of variables, the identity $\partial_t J = \widehat{J \operatorname{div} \mathbf{w}}$, integration by parts in the convective term and (22), it follows that (see, e.g., [27]):

$$T_1 = \frac{\rho^f}{2} \frac{d}{dt} \int_{\Omega_f(t)} |\mathbf{u}|^2 + 2\mu \int_{\Omega_f(t)} |\boldsymbol{\epsilon}(\mathbf{u})|^2 + \sum_{i \in \{\text{mv}, \text{ao}\}} \int_{\Gamma_i} \mathbf{f}_{\Gamma_i} \cdot \mathbf{u}.$$

As regards the solid contributions, we first note that owing to (13)₂ and to (8) we have

$$\int_{\Omega_s} \boldsymbol{\Sigma} : \dot{\mathbf{E}} = \int_{\Omega_s} \left(\frac{\partial W_e}{\partial \mathbf{E}} + \frac{\partial W_v}{\partial \dot{\mathbf{E}}} \right) : \dot{\mathbf{E}} + \int_{\Omega_s} \sigma_a \mathbf{a}^T \dot{\mathbf{E}} \mathbf{a}. \quad (26)$$

On the other hand, by differentiating in time (8) and by using (7) and then (4) and (5), we get

$$\int_{\Omega_s} \sigma_a \mathbf{a}^T \dot{\mathbf{E}} \mathbf{a} = \int_{\Omega_s} \sigma_a \dot{e}_a = \int_{\Omega_s} \sigma_s \dot{e}_s + \int_{\Omega_s} \sigma_c \dot{e}_c = \int_{\Omega_s} E_s e_s \dot{e}_s + \int_{\Omega_s} \tau_c \dot{e}_c + \int_{\Omega_s} \mu_c \dot{e}_c^2.$$

By inserting this relation into (26) and using (23), we have

$$\begin{aligned} T_2 &= \frac{d}{dt} \left(\frac{\rho^s}{2} \int_{\Omega_s} |\mathbf{u}_s|^2 + \int_{\Omega_s} W_e + \frac{1}{2} \int_{\Omega_s} E_s |e_s|^2 + \int_{\Omega_s} U_c \right) + \int_{\Omega_s} \frac{\partial W_v}{\partial \dot{\mathbf{E}}} : \dot{\mathbf{E}} \\ &\quad + \frac{a}{2} \|\mathbf{y}\|_{\Gamma_a \cup \Gamma_b}^2 + b \|\mathbf{u}_s\|_{\Gamma_a \cup \Gamma_b}^2 + \int_{\Omega_s} \mu_c \dot{e}_c^2 + \int_{\Omega_s} (|u_e| + \alpha_d |\dot{e}_c|) U_c - \int_{\Omega_s} n_0 U_0 |u_e|_+. \end{aligned}$$

Finally, for the third term, using (13)₉ we get

$$T_3 = P_r Q_r = P_r |Q_r|_+ - P_r |Q_r|_- = (P_r - P_{\text{ar},r}) |Q_r|_+ + P_{\text{ar},r} |Q_r|_+ - P_r |Q_r|_-. \quad (27)$$

Owing to the expression of the valve function (11), we have

$$(P_r - P_{\text{ar},r}) |Q_r|_+ = K_{\text{ar},r} |P_r - P_{\text{ar},r}|_+^2.$$

On other hand, using a standard energy argument in (12), we obtain

$$P_{\text{ar},r} |Q_r|_+ = \frac{d}{dt} \left(\frac{C_{\text{p},r}}{2} |P_{\text{ar},r}|^2 + \frac{C_{\text{d},r}}{2} |P_{\text{d},r}|^2 \right) + \frac{|P_{\text{ar},r} - P_{\text{d},r}|^2}{R_{\text{p},r}} + \frac{|P_{\text{d},r}|^2}{R_{\text{d},r}} - \frac{P_{\text{vs},r} P_{\text{d},r}}{R_{\text{d},r}}.$$

For the last term in (27), using (11) again, we have

$$-P_r |Q_r|_- = -(P_r - P_{\text{at},r}) |Q_r|_- + P_{\text{at},r} |Q_r|_- = K_{\text{at},r} |P_r - P_{\text{at},r}|_-^2 + K_{\text{at},r} P_{\text{at},r} |P_r - P_{\text{at},r}|_-.$$

Finally, the energy equality (24) follows by gathering all the above relations into (25) and by integrating the resulting expression over the time interval $(0, t)$. This completes the proof. \square

Remark 3. *It should be noted that by using the Young's, Cauchy-Schwarz, trace and Korn's inequalities in the right-hand side of (24), we can absorb the velocity and Windkessel pressures contributions into $\mathcal{D}(t)$, which yields the a priori energy bound in terms of the problem data*

$$\mathcal{E}(t) + \frac{1}{2} \int_0^t \mathcal{D}(t) \leq \mathcal{E}(0) + \int_0^t \int_{\Omega_s} n_0 U_0 |u_e|_+ + \frac{C_T C_K}{\mu} \sum_{i \in \{\text{pv}, \text{ao}\}} \int_0^t \int_{\Gamma_i} |P_i|^2 + \frac{1}{2} \int_0^t (|P_{\text{vs},r}|^2 + K_{\text{at},r} |P_{\text{at},r}|^2),$$

where $C_T, C_K > 0$ denote the constants of the trace and Korn's inequalities, respectively. In particular, since $\mathbf{w}|_{\Gamma_i} = \mathbf{0}$ for $i \in \{\text{mv}, \text{ao}\}$, we have $\mathbf{f}_{\Gamma_i} \cdot \mathbf{u} \geq 0$, so that $\mathcal{D}(t) \geq 0$.

3 Numerical approximation

This section is devoted to the numerical approximation of the non-linear coupled system (13), (14) and (22).

3.1 Time semi-discretization: Robin-based loosely coupled scheme

The time interval $(0, T)$ is discretized into N sub-intervals (t_n, t_{n+1}) , where $t_n \stackrel{\text{def}}{=} \tau n$, $T = t_N$, and τ denotes the time-step length. In what follows, we shall make use of the following standard notation:

$$\partial_\tau f^{n+1} \stackrel{\text{def}}{=} \frac{1}{\tau}(f^{n+1} - f^n), \quad f^{n+\frac{1}{2}} \stackrel{\text{def}}{=} \frac{f^n + f^{n+1}}{2},$$

for the first-order backward finite difference and the midpoint value, respectively.

The fluid subproblem (14) is discretized in time using a first-order backward Euler scheme with a semi-implicit treatment of the convective term. For the solid subproblem (13), a modified mid-point scheme is considered for the momentum conservation equation (13)₁ with the so-called Gonzalez correction of the stresses, given by (see [35]):

$$\Sigma_g^{n+\frac{1}{2}} \stackrel{\text{def}}{=} \frac{\partial_\tau W_e(\mathbf{E}^{n+1}) - \frac{\partial W_e}{\partial \mathbf{E}}(\mathbf{E}^{n+\frac{1}{2}}) : \dot{\mathbf{E}}^{n+\frac{1}{2}}}{|\dot{\mathbf{E}}^{n+\frac{1}{2}}|^2} \dot{\mathbf{E}}^{n+\frac{1}{2}}, \quad (28)$$

with the definitions

$$\mathbf{E}^{n+\frac{1}{2}} \stackrel{\text{def}}{=} \mathbf{E}(\mathbf{y}^{n+\frac{1}{2}}), \quad \dot{\mathbf{E}}^{n+\frac{1}{2}} \stackrel{\text{def}}{=} \partial_\tau \mathbf{E}^{n+1}, \quad (29)$$

Owing to (1), the discrete passive stress tensor is given by

$$\Sigma_p^{n+\frac{1}{2}} \stackrel{\text{def}}{=} \frac{\partial W_e}{\partial \mathbf{E}}(\mathbf{E}^{n+\frac{1}{2}}) + \frac{\partial W_v}{\partial \dot{\mathbf{E}}}(\dot{\mathbf{E}}^{n+\frac{1}{2}}),$$

where, using the applying the chain rule and (2), the viscous-pseudo potential contribution yields

$$\frac{\partial W_v}{\partial \dot{\mathbf{E}}}(\dot{\mathbf{E}}^{n+\frac{1}{2}}) \stackrel{\text{def}}{=} \nu D_{\mathbf{y}} \mathbf{E}^{n+\frac{1}{2}} \cdot \mathbf{u}_s^{n+\frac{1}{2}}. \quad (30)$$

Following [16], the dynamics of the active component are discretized in time using a first-order backward Euler scheme in terms of the discrete variables e_c^{n+1} , $\varrho^{n+1} \stackrel{\text{def}}{=} \tau_c^{n+1}/\sqrt{k_c^{n+1}}$ and $\gamma^{n+1} \stackrel{\text{def}}{=} \sqrt{k_c^{n+1}}$, which guarantees the positiveness of k_c^{n+1} and the bound on the discrete elastic energy in the sarcomeres (see Remark 4 below).

For the time-discretization of the interface conditions (22), we build on the loosely coupled approach proposed in [12] (see also [55, 11]). This basically consists in combining an explicit treatment for the geometrical compatibility (22)₁ with the following Robin-Robin discretization of the kinematic/dynamic coupling conditions (22)_{2,3}:

$$\begin{cases} \mathbf{F}_s^{n+\frac{1}{2}} \bar{\Sigma}^{n+\frac{1}{2}} \mathbf{n}_s + \alpha \mathbf{u}_s^{n+\frac{1}{2}} = \alpha \hat{\mathbf{u}}^n - J^n \hat{\boldsymbol{\sigma}}(\mathbf{u}^n, p^n)(\mathbf{F}^n)^{-\text{T}} \hat{\mathbf{n}}_f & \text{on } \Gamma_1, \\ J^{n+1} \hat{\boldsymbol{\sigma}}(\mathbf{u}^{n+1}, p^{n+1})(\mathbf{F}^{n+1})^{-\text{T}} \hat{\mathbf{n}}_f + \alpha \hat{\mathbf{u}}^{n+1} = \alpha \mathbf{u}_s^{n+\frac{1}{2}} + J^n \hat{\boldsymbol{\sigma}}(\mathbf{u}^n, p^n)(\mathbf{F}^n)^{-\text{T}} \hat{\mathbf{n}}_f & \text{on } \Gamma_1, \end{cases} \quad (31)$$

where $\alpha > 0$ is the so-called Robin parameter (user-defined). A salient feature of (31), notably with respect alternative loosely coupled schemes reported in the literature (see, e.g., [5, 28, 57, 33, 32, 9]), is that the scheme can be proved to deliver unconditional stability and nearly optimal accuracy (see [12]).

The proposed time semi-discrete approximation of the coupled problem (13), (14) and (22) reads therefore as follows: For $n \geq 0$:

1. Solve active solid: Find $\mathbf{y}^{n+1} : \Omega^s \rightarrow \mathbb{R}^3$, $\mathbf{u}_s^{n+1} : \Omega^s \rightarrow \mathbb{R}^3$, $e_c^{n+1} : \Omega^s \rightarrow \mathbb{R}$, $\varrho^{n+1} : \Omega^s \rightarrow \mathbb{R}$, $\gamma^{n+1} : \Omega^s \rightarrow \mathbb{R}^+$ and

$(P_r^{n+1}, P_{ar,r}^{n+1}, P_{dr,r}^{n+1}) \in \mathbb{R}^3$ such that $\mathbf{u}_s^{n+\frac{1}{2}} = \partial_\tau \mathbf{y}^{n+1}$ and

$$\left\{ \begin{array}{l} \rho_s \partial_\tau \mathbf{u}_s^{n+1} - \operatorname{div} \left(\mathbf{F}_s^{n+\frac{1}{2}} \overline{\boldsymbol{\Sigma}}^{n+\frac{1}{2}} \right) = \mathbf{0} \quad \text{in } \Omega_s, \\ \overline{\boldsymbol{\Sigma}}^{n+\frac{1}{2}} = \boldsymbol{\Sigma}_p^{n+\frac{1}{2}} + \boldsymbol{\Sigma}_g^{n+\frac{1}{2}} + \frac{E_s (\mathbf{a}^\top \mathbf{E}^{n+\frac{1}{2}} \mathbf{a} - e_c^{n+\frac{1}{2}})}{(1 + 2e_c^{n+\frac{1}{2}})^2} \mathbf{a} \otimes \mathbf{a} \quad \text{in } \Omega_s, \\ \gamma^{n+1} \varrho^{n+1} + \mu_c \partial_\tau e_c^{n+1} = E_s \frac{(\mathbf{a}^\top \mathbf{E}^{n+\frac{1}{2}} \mathbf{a} - e_c^{n+\frac{1}{2}}) (1 + 2\mathbf{a}^\top \mathbf{E}^{n+\frac{1}{2}} \mathbf{a})}{(1 + 2e_c^{n+\frac{1}{2}})^3} \quad \text{in } \Omega_s, \\ \partial_\tau (\gamma^{n+1})^2 = - (|u_e^{n+1}| + \alpha_d |\partial_\tau e_c^{n+1}|) (\gamma^{n+1})^2 + n_0 k_0 |u_e^{n+1}|_+ \quad \text{in } \Omega_s, \\ \partial_\tau \varrho^{n+1} = \gamma^{n+1} \partial_\tau e_c^{n+1} + \frac{n_0 \sigma_0 |u_e^{n+1}|_+}{\gamma^{n+1}} \left(1 - \frac{k_0}{2\sigma_0 \gamma^{n+1}} \varrho^{n+1} \right) - \frac{1}{2} (|u_e^{n+\frac{1}{2}}| + |\partial_\tau e_c^{n+1}|) \varrho^{n+1} \quad \text{in } \Omega_s, \\ \mathbf{F}_s^{n+\frac{1}{2}} \overline{\boldsymbol{\Sigma}}^{n+\frac{1}{2}} \mathbf{n}_s = - (a \mathbf{y}^{n+\frac{1}{2}} + b \mathbf{u}_{s,h}^{n+\frac{1}{2}}) \quad \text{on } \Gamma_a \cup \Gamma_b, \\ \mathbf{y}^{n+1} = \mathbf{0} \quad \text{on } \Gamma_v, \\ \mathbf{F}_s^{n+\frac{1}{2}} \overline{\boldsymbol{\Sigma}}^{n+\frac{1}{2}} \mathbf{n}_s = - P_r^{n+\frac{1}{2}} \mathbf{n}_s \quad \text{on } \Gamma_r, \\ \int_{\Gamma_1} J_s^{n+\frac{1}{2}} \mathbf{u}_s^{n+\frac{1}{2}} \cdot (\mathbf{F}_s^{n+\frac{1}{2}})^{-\top} \mathbf{n}_s = Q_r (P_r^{n+\frac{1}{2}}, P_{ar,r}^{n+\frac{1}{2}}, P_{at,r}^{n+\frac{1}{2}}), \\ \mathbf{F}_s^{n+\frac{1}{2}} \overline{\boldsymbol{\Sigma}}^{n+\frac{1}{2}} \mathbf{n}_s + \alpha \mathbf{u}_s^{n+\frac{1}{2}} = \alpha \widehat{\mathbf{u}}^n - J^n \widehat{\boldsymbol{\sigma}}(\mathbf{u}^n, p^n) (\mathbf{F}^n)^{-\top} \widehat{\mathbf{n}}_f \quad \text{on } \Gamma_1, \\ C_{p,r} \partial_\tau P_{ar,r}^{n+1} + \frac{P_{ar,r}^{n+\frac{1}{2}} - P_{dr,r}^{n+\frac{1}{2}}}{R_{p,r}} = |Q_r^{n+\frac{1}{2}}|_+, \\ C_{d,r} \partial_\tau P_{dr,r}^{n+1} + \frac{P_{dr,r}^{n+\frac{1}{2}} - P_{ar,r}^{n+\frac{1}{2}}}{R_{p,r}} = \frac{P_{vs,r}(t_{n+\frac{1}{2}}) - P_{dr,r}^{n+\frac{1}{2}}}{R_{d,r}}. \end{array} \right. \quad (32)$$

2. Fluid domain update:

$$\mathbf{y}_f^{n+1} = \mathcal{L}(\mathbf{y}^{n+1}|_{\Gamma_1}), \quad \mathbf{w}^{n+1} = \partial_\tau \mathbf{y}_f^{n+1}, \quad \mathcal{A}^{n+1} = \mathbf{I}_{\Omega_f} + \mathbf{y}_f^{n+1} \quad \text{in } \Omega_f^{n+1} = \mathcal{A}^{n+1}(\Omega_f). \quad (33)$$

3. Solve fluid: Find $\widehat{\mathbf{u}}^{n+1} : \Omega_f \rightarrow \mathbb{R}^3$ and $\widehat{p}^{n+1} : \Omega_f \rightarrow \mathbb{R}$ such that

$$\left\{ \begin{array}{l} \rho_f \partial_\tau \mathbf{u}^{n+1}|_{\mathcal{A}} + \rho_f (\mathbf{u}^n - \mathbf{w}^{n+1}) \cdot \nabla \mathbf{u}^{n+1} - \operatorname{div} \boldsymbol{\sigma}(\mathbf{u}^{n+1}, p^{n+1}) + \sum_{i \in \{\text{mv}, \text{ao}\}} \mathbf{f}_{\Gamma_i}^{n+1} \delta_{\Gamma_i} = \mathbf{0} \quad \text{in } \Omega_f^{n+1}, \\ \operatorname{div} \mathbf{u}^{n+1} = 0 \quad \text{in } \Omega_f^{n+1}, \\ \mathbf{u}^{n+1} = \mathbf{0} \quad \text{in } \Gamma_{la} \cup \Gamma_{aw}, \\ \boldsymbol{\sigma}(\mathbf{u}^{n+1}, p^{n+1}) \mathbf{n}_f + \frac{\rho_f}{2} |\mathbf{u}^n \cdot \mathbf{n}_f|_- \mathbf{u} = - P_{pv,ao}^{n+1} \mathbf{n}_f \quad \text{on } \Gamma_{pv} \cup \Gamma_{ao}, \\ J^{n+1} \widehat{\boldsymbol{\sigma}}(\mathbf{u}^{n+1}, p^{n+1}) (\mathbf{F}^{n+1})^{-\top} \widehat{\mathbf{n}}_f + \alpha \widehat{\mathbf{u}}^{n+1} = \alpha \mathbf{u}_s^{n+\frac{1}{2}} + J^n \widehat{\boldsymbol{\sigma}}(\mathbf{u}^n, p^n) (\mathbf{F}^n)^{-\top} \widehat{\mathbf{n}}_f \quad \text{on } \Gamma_1. \end{array} \right.$$

Remark 4. As shown in [16], the scheme (32) preserves the sign properties of $k_c^{n+1} \in (0, n_0 k_0)$ as well as the bound $U_c^{n+1} \geq (\tau_c^{n+1})^2 / (2k_c^{n+1}) \geq 0$.

3.2 Finite element approximation: fully discrete scheme

For the spatial approximation of the time semi-discrete scheme introduced in the previous section, we adopt a finite element methodology. To this purpose, we let $\mathcal{T}_{s,h}$ and $\mathcal{T}_{f,h}$ be simplicial triangulations of the reference domains Ω_s and Ω_f , respectively, where the subscript $h > 0$ indicates the level of spatial refinement. We assume that $\mathcal{T}_{s,h}$ and $\mathcal{T}_{f,h}$ match on the fluid-solid interface Γ_1 , and that $\mathcal{T}_{f,h}$ is also fitted to the immersed surfaces Γ_{mv}^{cl} , Γ_{ao}^{cl} and Γ_{mv}^{op} . We define the following finite element spaces for the fluid velocity, fluid pressure and fluid domain displacement, respectively,

$$\begin{aligned} \mathbf{V}_{f,h} &\stackrel{\text{def}}{=} \left\{ \widehat{\mathbf{v}}_{f,h} \in [C^0(\Omega_f)]^3 : \widehat{\mathbf{v}}_{f,h}|_K \in [\mathbb{P}_1(K)]^3 \quad \forall K \in \mathcal{T}_{f,h} \right\}, \\ Q_{f,h} &\stackrel{\text{def}}{=} \left\{ \widehat{q}_h \in C^0(\Omega_f \setminus (\Gamma_{mv}^{\text{cl}} \cup \Gamma_{ao}^{\text{cl}} \cup \Gamma_{mv}^{\text{op}})) : \widehat{q}_h|_K \in \mathbb{P}_1(K) \quad \forall K \in \mathcal{T}_{f,h} \right\}, \\ \mathbf{W}_{f,h} &\stackrel{\text{def}}{=} \left\{ \mathbf{y}_{f,h} \in \mathbf{V}_{f,h} : \mathbf{y}_{f,h} = \mathbf{0} \quad \text{on } \Gamma_{mv}^{\text{cl}} \cup \Gamma_{ao}^{\text{cl}} \cup \Gamma_{mv}^{\text{op}} \right\}. \end{aligned} \quad (34)$$

Note that the discrete pressure space $Q_{f,h}$ is made of piece-wise affine functions which are globally continuous in Ω_f except across the immersed valves Γ_{mv}^{cl} , Γ_{ao}^{cl} and Γ_{mv}^{op} . This is fundamental in order to guarantee interfacial mass conservation across the valves. For the approximation of the solid displacement and velocity, we consider the finite elements space

$$\mathbf{V}_{s,h} \stackrel{\text{def}}{=} \left\{ \mathbf{v}_{s,h} \in [C^0(\Omega_s)]^3 : \mathbf{v}_{s,h}|_K \in [\mathbb{P}_1(K)]^3 \quad \forall K \in \mathcal{T}_{s,h}, \quad \mathbf{v}_{s,h}|_{\Gamma_v} = \mathbf{0} \right\}.$$

We also introduce the interface matching trace space

$$\mathbf{\Lambda}_h \stackrel{\text{def}}{=} \left\{ \mathbf{v}_{s,h}|_{\Gamma_1} : \mathbf{v}_{s,h} \in \mathbf{V}_{s,h} \right\} = \left\{ \widehat{\mathbf{v}}_{f,h}|_{\Gamma_1} : \widehat{\mathbf{v}}_{f,h} \in \mathbf{V}_{f,h} \right\},$$

which will be used in the formulation of the spatial discrete counterpart of (31). Finally, we denote by $\mathcal{L}_h : \mathbf{\Lambda}_h \rightarrow \mathbf{W}_{f,h}$ a given discrete counterpart of the lifting operator \mathcal{L} involved in (33).

The dynamics of the active mechanics variables e_c^{n+1} , ϱ^{n+1} and γ^{n+1} in (32) are discretized in space (element-wise) using a collocation scheme at each quadrature point \mathbf{q}_l , $l = 1, \dots, N_{q,h}$, where $N_{q,h} \stackrel{\text{def}}{=} |\mathcal{T}_{s,h}| n_q$ and n_q denotes the number of quadrature points in each element of the triangulation $\mathcal{T}_{s,h}$. This yields a total number of $N_{q,h}$ degrees of freedom for each discrete unknown, viz., given by the arrays

$$\mathbf{e}_{c,h}^{n+1} \stackrel{\text{def}}{=} \left\{ e_{c,l}^{n+1} \right\}_{l=1}^{N_{q,h}}, \quad \mathbf{\varrho}_h^{n+1} \stackrel{\text{def}}{=} \left\{ \varrho_l^{n+1} \right\}_{l=1}^{N_{q,h}}, \quad \boldsymbol{\gamma}_h^{n+1} = \left\{ \gamma_l^{n+1} \right\}_{l=1}^{N_{q,h}}. \quad (35)$$

The proposed fully discrete approximation of the non-linear coupled problem (13), (14) and (22) is detailed in Algorithm 2. In the solid step (36), the symbols \mathbf{a}_l , $\mathbf{E}_l^{n+\frac{1}{2}}$, $\boldsymbol{\Sigma}_{p,l}^{n+\frac{1}{2}}$, $\boldsymbol{\Sigma}_{g,l}^{n+\frac{1}{2}}$, $\overline{\boldsymbol{\Sigma}}_l^{n+\frac{1}{2}}$ indicate the evaluation of the corresponding field at the quadrature point \mathbf{q}_l , $l = 1, \dots, N_{q,h}$. Note that the stress along the fibers at \mathbf{q}_l is evaluated in terms of the discrete unknowns (35), which is then integrated via quadrature formula in the discrete principle of virtual work of the solid. It is also worth noting that, at each Newton iteration of (36), the increments associated to the unknowns (35) can be eliminated from the solid tangent system by a static condensation procedure (see, e.g., [51]).

As in [12], the fluid trilinear form the fluid sub-problem (38) is given by the relation

$$\begin{aligned} a_{\Omega_f^{n+1}}(\mathbf{u}_h^n, \mathbf{w}_h^{n+1}; (\mathbf{u}_h^{n+1}, p_h^{n+1}), (\mathbf{v}_{f,h}, q_h)) &\stackrel{\text{def}}{=} \rho_f \int_{\Omega_f^{n+1}} (\mathbf{u}_h^n - \mathbf{w}_h^{n+1}) \cdot \nabla \mathbf{u}_h^{n+1} \cdot \mathbf{v}_{f,h} + \frac{\rho_f}{2} \int_{\Omega_f^{n+1}} (\text{div } \mathbf{u}_h^n) \mathbf{u}_h^{n+1} \cdot \mathbf{v}_{f,h} \\ &\quad - \frac{\rho_f}{2} \int_{\Gamma_1^{n+1}} (\mathbf{u}_h^n - \mathbf{u}_s^{n+\frac{1}{2}}) \cdot \mathbf{n}_f \mathbf{u}_h^{n+1} \cdot \mathbf{v}_{f,h} \\ &\quad + 2\mu_f \int_{\Omega_f^{n+1}} \boldsymbol{\epsilon}(\mathbf{u}_h^{n+1}) : \boldsymbol{\epsilon}(\mathbf{v}_{f,h}) - \int_{\Omega_f^{n+1}} p^{n+1} \text{div } \mathbf{v}_{f,h} + \int_{\Omega_f^{n+1}} q_h \text{div } \mathbf{u}_h^n \\ &\quad + s_{f,h}(\mathbf{u}_h^n, \mathbf{w}_h^{n+1}; (\mathbf{u}_h^{n+1}, p^{n+1}), (\mathbf{v}_h^f, q_h)). \end{aligned} \quad (40)$$

The second term in the right-hand side corresponds to the so-called Temam's trick (see, e.g., [59]), to cope with the fact that the discrete fluid velocities are not divergence-free. The third term is a strongly consistent interfacial stabilization, introduced in [12], which serves to balance the contributions of the convective term on the interface, by noting that $\mathbf{u}^n|_{\Gamma_1} \neq \mathbf{w}^{n+1}|_{\Gamma_1} = \mathbf{u}_s^{n+\frac{1}{2}}|_{\Gamma_1}$. Finally, the last term in (40) corresponds to the Streamline Upwind Petrov-Galerkin (SUPG)/Pressure-Stabilized Petrov-Galerkin (PSPG) stabilization (see, e.g., [60]), which guarantees robustness for high local Reynolds numbers and with respect to the lack of inf-sup stability in the fluid velocity/pressure discrete spaces $\mathbf{V}_{f,h}/Q_{f,h}$.

On the other hand, to cope with the stability issues related to the lack of discrete geometric conservation law (see, e.g., [24]), the fluid sub-problem (38) includes the following weakly consistent stabilization term (from [58, Chapter 5]):

$$s_{\text{GCL}}^{n+1}(\mathbf{u}_h^n, \mathbf{w}_h^{n+1}; \mathbf{u}_h^{n+1}, \mathbf{v}_{f,h}) \stackrel{\text{def}}{=} -\frac{\rho_f}{2\tau} \left(\int_{\Omega_f^{n+1}} \mathbf{u}_h^{n+1} \cdot \mathbf{v}_{f,h} - \int_{\Omega_f^n} \mathbf{u}_h^{n+1} \cdot \mathbf{v}_{f,h} \right) + \frac{\rho_f}{2} \int_{\Omega_f^{n+1}} (\text{div } \mathbf{w}^{n+1}) \mathbf{u}_h^{n+1} \cdot \mathbf{v}_{f,h}. \quad (41)$$

Finally, it is also worth noting that the relation (39) in Algorithm 2 is nothing but the spatial discrete counterpart of (34)₂, in which the intermediate variable $\boldsymbol{\lambda}_h^{n+1}$ approximates the interfacial fluid stress on the reference configuration $J^{n+1} \widehat{\boldsymbol{\sigma}}(\mathbf{u}^{n+1}, p^{n+1})(\mathbf{F}^{n+1})^{-\text{T}} \widehat{\mathbf{n}}_f$ as a variational residual (see [12, 11]).

3.3 Discrete energy bound: unconditional stability

The purpose of this section is to derive an energy bound for the numerical approximation of the coupled problem (13), (14) and (22) provided by Algorithm 2. For $n \geq 1$, the discrete energy and the discrete is defined as

$$\begin{aligned} \mathcal{E}_h^n &\stackrel{\text{def}}{=} \frac{\rho_f}{2} \|\mathbf{u}_h^n\|_{0,\Omega_f^n}^2 + \frac{\rho_s}{2} \|\mathbf{u}_{s,h}^n\|_{0,\Omega_s}^2 + \int_{\Omega_s} W_e(\mathbf{E}^n) + \frac{\tau}{2} \left(\alpha \|\widehat{\mathbf{u}}_h^n\|_{0,\Gamma_1}^2 + \frac{1}{\alpha} \|\boldsymbol{\lambda}_h^n\|_{0,\Gamma_1}^2 \right) + \int_{\Omega_s} \frac{E_s}{2} |e_{s,h}^n|^2 + \int_{\Omega_s} U_c^n \\ &\quad + \frac{a}{2} \|\boldsymbol{\gamma}_h^n\|_{\Gamma_a \cup \Gamma_b}^2 + \frac{C_{p,r}}{2} |P_{\text{ar},r}^n|^2 + \frac{C_{d,r}}{2} |P_{\text{d},r}^n|^2, \end{aligned}$$

Algorithm 2 Fully discrete Robin-based loosely coupled scheme.

For $n \geq 0$:

1. Solve active solid: Find $(\mathbf{y}_h^{n+1}, \mathbf{u}_{s,h}^{n+1}, \mathbf{e}_{c,h}^{n+1}, \mathbf{q}_h^{n+1}, \gamma_h^{n+1}, P_r^{n+1}, P_{ar,r}^{n+1}, P_{d,r}^{n+1}) \in \mathbf{V}_{s,h} \times \mathbf{V}_{s,h} \times \mathbb{R}^{N_{q,h}} \times \mathbb{R}^{N_{q,h}} \times (\mathbb{R}^+)^{N_{q,h}} \times \mathbb{R} \times \mathbb{R} \times \mathbb{R}$ with $\mathbf{u}_{s,h}^{n+\frac{1}{2}} = \partial_\tau \mathbf{y}_h^{n+1}$ and such that

$$\left\{ \begin{array}{l} \rho_s \int_{\Omega_s} \partial_\tau \mathbf{u}_{s,h}^{n+1} \cdot \mathbf{v}_{s,h} + \int_{\Omega_s} \overline{\boldsymbol{\Sigma}}^{n+\frac{1}{2}} : D_{\mathbf{y}} \mathbf{E}^{n+\frac{1}{2}} \cdot \mathbf{v}_{s,h} + \alpha \int_{\Gamma_1} \mathbf{u}_{s,h}^{n+\frac{1}{2}} \cdot \mathbf{v}_{s,h} + \int_{\Gamma_a \cup \Gamma_b} (\alpha \mathbf{y}_h^{n+\frac{1}{2}} + b \mathbf{u}_{s,h}^{n+\frac{1}{2}}) \cdot \mathbf{v}_{s,h} = \\ \quad + \alpha \int_{\Gamma_1} \widehat{\mathbf{u}}_h^n \cdot \mathbf{v}_{s,h} - \int_{\Gamma_1} \boldsymbol{\lambda}_h^n \cdot \mathbf{v}_{s,h} - \int_{\Gamma_r} J_s^{n+\frac{1}{2}} P_r^{n+\frac{1}{2}} (\mathbf{F}_s^{n+\frac{1}{2}})^{-T} \mathbf{v}_{s,h} \cdot \mathbf{n}_s, \\ \overline{\boldsymbol{\Sigma}}_l^{n+\frac{1}{2}} = \boldsymbol{\Sigma}_{p,l}^{n+\frac{1}{2}} + \boldsymbol{\Sigma}_{g,l}^{n+\frac{1}{2}} + \frac{E_s (\mathbf{a}_l^T \mathbf{E}_l^{n+\frac{1}{2}} \mathbf{a}_l - e_{c,l}^{n+\frac{1}{2}})}{(1 + 2e_{c,l}^{n+\frac{1}{2}})^2} \mathbf{a}_l \otimes \mathbf{a}_l, \\ \gamma_l^{n+1} \varrho_l^{n+1} + \mu_c \partial_\tau e_{c,l}^{n+1} = E_s \frac{(\mathbf{a}_l^T \mathbf{E}_l^{n+\frac{1}{2}} \mathbf{a}_l - e_{c,l}^{n+\frac{1}{2}}) (1 + 2\mathbf{a}_l^T \mathbf{E}_l^{n+\frac{1}{2}} \mathbf{a}_l)}{(1 + 2e_{c,l}^{n+\frac{1}{2}})^3}, \\ \partial_\tau (\gamma_l^{n+1})^2 = - \left(|u_{e,l}^{n+1}| + \alpha_d |\partial_\tau e_{c,l}^{n+1}| \right) (\gamma_l^{n+1})^2 + n_0 k_0 |u_{e,l}^{n+1}|_+, \\ \partial_\tau \varrho_l^{n+1} = \gamma_l^{n+1} \partial_\tau e_{c,l}^{n+1} + \frac{n_0 \sigma_0 |u_{e,l}^{n+1}|_+}{\gamma_l^{n+1}} \left(1 - \frac{k_0}{2\sigma_0 \gamma_l^{n+1}} \varrho_l^{n+1} \right) - \frac{1}{2} \left(|u_{e,l}^{n+\frac{1}{2}}| + |\partial_\tau e_{c,l}^{n+1}| \right) \varrho_l^{n+1}, \\ \int_{\Gamma_1} J_s^{n+\frac{1}{2}} \mathbf{u}_{s,h}^{n+\frac{1}{2}} \cdot (\mathbf{F}_s^{n+\frac{1}{2}})^{-T} \mathbf{n}_s = Q_r (P_r^{n+\frac{1}{2}}, P_{ar,r}^{n+\frac{1}{2}}, P_{at,r}^{n+\frac{1}{2}}), \\ C_{p,r} \partial_\tau P_{ar,r}^{n+1} + \frac{P_{ar,r}^{n+\frac{1}{2}} - P_{d,r}^{n+\frac{1}{2}}}{R_{p,r}} = |Q_r^{n+\frac{1}{2}}|_+, \\ C_{d,r} \partial_\tau P_{d,r}^{n+1} + \frac{P_{d,r}^{n+\frac{1}{2}} - P_{ar,r}^{n+\frac{1}{2}}}{R_{p,r}} = \frac{P_{vs,r}(t_{n+\frac{1}{2}}) - P_{d,r}^{n+\frac{1}{2}}}{R_{d,r}}, \end{array} \right. \quad (36)$$

for all $\mathbf{v}_{s,h} \in \mathbf{V}_{s,h}$ and $l = 1, \dots, N_{q,h}$.

2. Update fluid domain:

$$\mathbf{y}_{f,h}^{n+1} = \mathcal{L}_h(\mathbf{y}_h^n|_{\Gamma_1}), \quad \mathbf{w}_h^{n+1} = \partial_\tau \mathbf{y}_{f,h}^{n+1}, \quad \mathcal{A}_h^{n+1} = \mathbf{I}_{\Omega_f} + \mathbf{y}_{f,h}^{n+1}, \quad \Omega_f^{n+1} = \mathcal{A}_h^{n+1}(\Omega_f). \quad (37)$$

3. Solve fluid: Find $(\widehat{\mathbf{u}}_h^{n+1}, \widehat{p}_h^{n+1}) \in \mathbf{V}_{f,h} \in Q_{f,h}$ such that

$$\begin{aligned} & \rho_f \partial_\tau \int_{\Omega_f^{n+1}} \mathbf{u}_h^{n+1} \cdot \mathbf{v}_{f,h} - \rho_f \int_{\Omega_f^{n+1}} (\operatorname{div} \mathbf{w}_h^{n+1}) \mathbf{u}_h^{n+1} \cdot \mathbf{v}_{f,h} + a_{\Omega_f^{n+1}}(\mathbf{u}_h^n, \mathbf{w}_h^{n+1}; (\mathbf{u}_h^{n+1}, p_h^{n+1}), (\mathbf{v}_{f,h}, q_h)) \\ & + s_{\text{GCL}}^{n+1}(\mathbf{u}_h^n, \mathbf{w}_h^{n+1}; \mathbf{u}_h^{n+1}, \mathbf{v}_{f,h}) + \sum_{i \in \{\text{mv}, \text{ao}\}} \int_{\Gamma_i} \mathbf{f}_{\Gamma_i}(\mathbf{u}_h^{n+1} - \mathbf{w}_h^{n+1}, p^{n+1}) \cdot \mathbf{v}_{f,h} + \frac{\rho_f}{2} \int_{\Gamma_{\text{pv}, \text{ao}}} |\mathbf{u}_h^n \cdot \mathbf{n}_f|_- \mathbf{u}_h^{n+1} \cdot \mathbf{v}_{f,h} \\ & + \alpha \int_{\Gamma_1} \widehat{\mathbf{u}}_h^{n+1} \cdot \widehat{\mathbf{v}}_{f,h} = \alpha \int_{\Gamma_1} \mathbf{u}_{s,h}^{n+\frac{1}{2}} \cdot \widehat{\mathbf{v}}_{f,h} + \int_{\Gamma_1} \boldsymbol{\lambda}_h^n \cdot \widehat{\mathbf{v}}_{f,h} - \int_{\Gamma_{\text{pv}} \cup \Gamma_{\text{ao}}} P_{\text{pv}, \text{ao}}^{n+1} \mathbf{v}_{f,h} \cdot \mathbf{n}_f \end{aligned} \quad (38)$$

for all $(\widehat{\mathbf{v}}_{f,h}, \widehat{q}_h) \in \mathbf{V}_{f,h} \times Q_{f,h}$.

4. Interfacial fluid stress update: Set $\boldsymbol{\lambda}_h^{n+1} \in \boldsymbol{\Lambda}_h$ with

$$\boldsymbol{\lambda}_h^{n+1} = \boldsymbol{\lambda}_h^n + \alpha (\mathbf{u}_{s,h}^{n+\frac{1}{2}} - \widehat{\mathbf{u}}_h^{n+1}) \quad \text{on } \Gamma_1. \quad (39)$$

and the discrete dissipation rate as

$$\begin{aligned}
\mathcal{D}_h^n &\stackrel{\text{def}}{=} 2\mu_f \|\boldsymbol{\epsilon}(\mathbf{u}_h^n)\|_{0,\Omega_f^n}^2 + \sum_{i \in \{\text{mv,ao}\}} \int_{\Gamma_i} \mathbf{f}_{\Gamma_i} \cdot \mathbf{u}_h^n + \alpha \|\mathbf{u}_{s,h}^{n-\frac{1}{2}} - \widehat{\mathbf{u}}_h^{n-1}\|_{0,\Gamma_1}^2 + \int_{\Omega_s} \frac{\partial W_v}{\partial \dot{\mathbf{E}}}(\dot{\mathbf{E}}^{n-\frac{1}{2}}) : \dot{\mathbf{E}}^{n-\frac{1}{2}} \\
&+ \int_{\Omega_s} (|u_e^n| + \alpha_d |\partial_\tau e_c^n|) U_c^n + \int_{\Omega_s} \mu_c |\partial_\tau e_c^n|^2 + b \|\mathbf{u}_s^n\|_{\Gamma_a \cup \Gamma_b}^2 + K_{\text{ar,r}} |P_r^{n-\frac{1}{2}} - P_{\text{ar,r}}^{n-\frac{1}{2}}|_+^2 \\
&+ K_{\text{at,r}} |P_r^{n-\frac{1}{2}} - P_{\text{at,r}}(t_{n-\frac{1}{2}})|_-^2 + \frac{|P_{\text{d,r}}^{n-\frac{1}{2}} - P_{\text{ar,r}}^{n-\frac{1}{2}}|^2}{R_{\text{p,r}}} + \frac{|P_{\text{d,r}}^{n-\frac{1}{2}}|^2}{R_{\text{d,r}}}.
\end{aligned}$$

The following result establishes the energy stability of the discrete approximation provided by Algorithm 2. A salient feature of this results is that, up to some numerical dissipation, Algorithm 2 satisfies an energy estimate similar to the one provided by Theorem 1 for the continuous coupled problem (13), (14) and (22).

Theorem 2. *Let $\left\{(\mathbf{y}_h^{n+1}, \mathbf{u}_{s,h}^{n+1}, \mathbf{e}_c^{n+1}, \boldsymbol{\varrho}^{n+1}, \boldsymbol{\gamma}^{n+1}, \mathbf{u}_h^{n+1}, p_h^{n+1}, \boldsymbol{\lambda}_h^{n+1})\right\}_{n=0}^{N-1} \subset \mathbf{V}_{s,h} \times \mathbf{V}_{s,h} \times \mathbb{R}^{N_{q,h}} \times \mathbb{R}^{N_{q,h}} \times \mathbb{R}^{N_{q,h}} \times \mathbf{V}_{f,h} \times Q_{f,h} \times \boldsymbol{\Lambda}_h$ be given by Algorithm 2. The following energy estimate holds:*

$$\begin{aligned}
\mathcal{E}_h^n + \sum_{m=0}^{n-1} \tau \mathcal{D}_h^{m+1} &\leq \mathcal{E}_h^0 + \sum_{m=0}^{n-1} \tau \int_{\Omega} U_0 |u_e^{m+1}|_+ - \sum_{i \in \{\text{pv,ao}\}} \sum_{m=0}^{n-1} \tau \int_{\Gamma_i} P_i(t_{m+1}) \mathbf{u}_h^{m+1} \cdot \mathbf{n}_f \\
&+ \sum_{m=0}^{n-1} \tau \frac{P_{\text{vs,r}}(t_{m+\frac{1}{2}}) P_{\text{d,r}}^{m+\frac{1}{2}}}{R_{\text{d,r}}} - \sum_{m=0}^{n-1} \tau K_{\text{at,r}} P_{\text{at,r}}(t_{m+\frac{1}{2}}) |P_r^{m+\frac{1}{2}} - P_{\text{at,r}}(t_{m+\frac{1}{2}})|_-. \quad (42)
\end{aligned}$$

Proof. The proof builds on the energy arguments reported in [12] and [16]. We first proceed by taking $\mathbf{v}_{s,h} = \mathbf{u}_{s,h}^{n+\frac{1}{2}}$ in (36). Owing to the relation $D_{\mathbf{y}} \mathbf{E}^{n+\frac{1}{2}} \cdot \mathbf{u}_{s,h}^{n+\frac{1}{2}} = \dot{\mathbf{E}}^{n+\frac{1}{2}} \stackrel{\text{def}}{=} \partial_\tau \mathbf{E}^{n+1}$ and by using (28), the stiffness term yields

$$\begin{aligned}
\int_{\Omega_s} \overline{\boldsymbol{\Sigma}}^{n+\frac{1}{2}} : D_{\mathbf{y}} \mathbf{E}^{n+\frac{1}{2}} \cdot \mathbf{u}_{s,h}^{n+\frac{1}{2}} &= \int_{\Omega_s} \frac{\partial W_e}{\partial \mathbf{E}}(\mathbf{E}^{n+\frac{1}{2}}) : \dot{\mathbf{E}}^{n+\frac{1}{2}} + \int_{\Omega_s} \boldsymbol{\Sigma}_g^{n+\frac{1}{2}} : \dot{\mathbf{E}}^{n+\frac{1}{2}} + \int_{\Omega_s} \frac{\partial W_v}{\partial \dot{\mathbf{E}}}(\dot{\mathbf{E}}^{n+\frac{1}{2}}) : \dot{\mathbf{E}}^{n+\frac{1}{2}} \\
&+ \int_{\Omega_s} \sigma_a^{n+\frac{1}{2}} \mathbf{a} \otimes \mathbf{a} : \partial_\tau \mathbf{E}^{n+1}, \quad (43) \\
&= \int_{\Omega_s} \partial_\tau W_e(\mathbf{E}^{n+1}) + \int_{\Omega_s} \frac{\partial W_v}{\partial \dot{\mathbf{E}}}(\dot{\mathbf{E}}^{n+\frac{1}{2}}) : \dot{\mathbf{E}}^{n+\frac{1}{2}} + \int_{\Omega_s} \sigma_a^{n+\frac{1}{2}} \partial_\tau e_a^{n+1},
\end{aligned}$$

where, according to (10) and (8), we have used the notations

$$\sigma_{a,l}^{n+\frac{1}{2}} \stackrel{\text{def}}{=} E_s \frac{e_{a,l}^{n+\frac{1}{2}} - e_{c,l}^{n+\frac{1}{2}}}{(1 + 2e_{c,l}^{n+\frac{1}{2}})^2}, \quad e_{a,l}^{n+\frac{1}{2}} \stackrel{\text{def}}{=} a_l^T \mathbf{E}_i^{n+\frac{1}{2}} \mathbf{a}_l$$

for $l = 1, \dots, N_{q,h}$. It hence only remains to estimate the last term in (43) coming from the active contribution. It should be noted that a little abuse of notation is made in this term, where the integral over Ω_s has to be read as a quadrature formula. To this purpose, we also introduce the notations

$$e_{s,l}^{n+1} \stackrel{\text{def}}{=} \frac{e_{a,l}^{n+1} - e_{c,l}^{n+1}}{1 + 2e_{c,l}^{n+1}}, \quad \sigma_{s,l}^{n+\frac{1}{2}} \stackrel{\text{def}}{=} E_s e_{s,l}^{n+\frac{1}{2}}, \quad \sigma_{s,l}^{n+\frac{1}{2}} \stackrel{\text{def}}{=} \gamma_l^{n+1} \varrho_l^{n+1} + \mu_c \overline{e_{c,l}^{n+\frac{1}{2}}},$$

which yields the stress identities

$$\sigma_{a,l}^{n+\frac{1}{2}} = \frac{\sigma_{c,l}^{n+\frac{1}{2}}}{1 + 2e_{s,l}^{n+\frac{1}{2}}} = \frac{\sigma_{s,l}^{n+\frac{1}{2}}}{1 + 2e_{c,l}^{n+\frac{1}{2}}}.$$

Additionally, we also introduce the collocated discrete elastic energy stored in the sarcomeres

$$\partial_\tau U_{c,l}^{n+1} = \gamma_l^{n+1} \varrho_l^{n+1} \partial_\tau e_{c,l}^{n+1} - (|u_{e,l}^{n+1}| + \alpha_d |\partial_\tau e_{c,l}^{n+1}|) U_{c,l}^{n+1} + n_0 U_0 |u_{e,l}^{n+1}|_+. \quad (44)$$

By combining the above relations, we have

$$\begin{aligned}
\sigma_{a,l}^{n+\frac{1}{2}} &= \sigma_{s,l}^{n+\frac{1}{2}} \partial_\tau e_{s,l}^{n+1} + \sigma_{c,l}^{n+\frac{1}{2}} \partial_\tau e_{c,l}^{n+1} \\
&= \frac{E_s}{2} \partial_\tau |e_{s,l}^{n+1}|^2 + \gamma_l^{n+1} \varrho_l^{n+1} \partial_\tau e_{c,l}^{n+1} + \mu_c |\partial_\tau e_{c,l}^{n+1}|^2.
\end{aligned}$$

Therefore, by using (44), we finally get

$$\begin{aligned} \int_{\Omega_s} \sigma_a^{n+\frac{1}{2}} \partial_\tau e_a^{n+1} &= \int_{\Omega_s} \frac{E_s}{2} \partial_\tau |e_s^{n+1}|^2 + \int_{\Omega_s} \mu_c |\partial_\tau e_s^{n+1}|^2 \\ &\quad + \int_{\Omega_s} \left(\partial_\tau U_c^{n+1} + (|u_e^{n+1}| + \alpha_d |\partial_\tau e_c^{n+1}|) U_c^{n+1} - n_0 U_0 |u_e^{n+1}|_+ \right). \end{aligned}$$

By gathering all the above contributions, the energy balance of the solid system yields

$$\begin{aligned} \frac{\rho_s}{2} \partial_\tau \|\mathbf{u}_{s,h}^{n+1}\|_{0,\Omega_s}^2 + \partial_\tau \int_{\Omega_s} W_e(\mathbf{E}^{n+1}) + \partial_\tau \int_{\Omega} \left(\frac{E_s}{2} |e_s^{n+1}|^2 + U_c^{n+1} \right) + \int_{\Omega_s} \frac{\partial W_v}{\partial \dot{\mathbf{E}}}(\dot{\mathbf{E}}^{n+\frac{1}{2}}) : \dot{\mathbf{E}}^{n+\frac{1}{2}} + \int_{\Omega_s} \mu_c |\partial_\tau e_s^{n+1}|^2 \\ + \int_{\Omega} (|u_e^{n+1}| + \alpha_d |\partial_\tau e_c^{n+1}|) U_c^{n+1} + \alpha \int_{\Gamma_1} (\mathbf{u}_{s,h}^{n+1} - \widehat{\mathbf{u}}_h^n) \cdot \dot{\mathbf{y}}_h^{n+1} - \int_{\Gamma_1} \boldsymbol{\lambda}_h^n \cdot \dot{\mathbf{y}}_h^{n+1} \\ = \int_{\Omega} n_0 U_0 |u_e^{n+1}|_+ - \int_{\Gamma_r} J_s^{n+\frac{1}{2}} P_r^{n+\frac{1}{2}} (\mathbf{F}_s^{n+\frac{1}{2}})^{-T} \mathbf{u}_{s,h}^{n+1} \cdot \mathbf{n}_s. \end{aligned} \quad (45)$$

Finally, for the last term on the right endocardial boundary, we have

$$\int_{\Gamma_r} J_s^{n+\frac{1}{2}} P_r^{n+\frac{1}{2}} (\mathbf{F}_s^{n+\frac{1}{2}})^{-T} \mathbf{u}_{s,h}^{n+1} \cdot \mathbf{n}_s = P_r^{n+\frac{1}{2}} Q_r^{n+\frac{1}{2}},$$

so that, by proceeding in a similar fashion as in the proof of Theorem 1, we have

$$\begin{aligned} P_r^{n+\frac{1}{2}} Q_r^{n+\frac{1}{2}} &= K_{ar,r} |P_r^{n+\frac{1}{2}} - P_{ar,r}^{n+\frac{1}{2}}|_+^2 + \frac{C_{p,r}}{2} \partial_\tau |P_{ar,r}^{n+1}|^2 + \frac{C_{d,r}}{2} \partial_\tau |P_{d,r}^{n+1}|^2 + \frac{|P_{ar,r}^{n+\frac{1}{2}} - P_{d,r}^{n+\frac{1}{2}}|^2}{R_{p,r}} + \frac{|P_{d,r}^{n+\frac{1}{2}}|^2}{R_{d,r}} \\ &\quad + K_{at,r} |P_r^{n+\frac{1}{2}} - P_{at,r}^{n+\frac{1}{2}}|_-^2 + K_{at,r} P_{at,r}^{n+\frac{1}{2}} |P_r^{n+\frac{1}{2}} - P_{at,r}^{n+\frac{1}{2}}|_- - \frac{P_{vs,r}^{n+\frac{1}{2}} P_{d,r}^{n+\frac{1}{2}}}{R_{d,r}}. \end{aligned}$$

The energy balance of the fluid subproblem is obtained by taking $(\widehat{\mathbf{v}}_{f,h}, \widehat{q}_h) = (\widehat{\mathbf{u}}_h^{n+1}, \widehat{p}_h^{n+1})$ in (38). By integrating by parts in the convective term, using the relation $\mathbf{w}_h^{n+1}|_{\Gamma_1} = \mathbf{u}_{s,h}^{n+\frac{1}{2}}|_{\Gamma_1}$ and the fact that $s_{f,h} \geq 0$, we have

$$a_{\Omega^f,n}(\mathbf{u}_h^{n-1}, \mathbf{w}_h^n; (\mathbf{u}_h^n, p_h^n), (\mathbf{u}_h^n, p_h^n)) \geq 2\mu \|\boldsymbol{\epsilon}(\mathbf{u}_h^n)\|_{0,\Omega^f,n}^2 + \frac{\rho^f}{2} \int_{\Omega^f,n} (\operatorname{div} \mathbf{w}_h^n) |\mathbf{u}_h^n|^2.$$

By combining this bound with (41) and (39), we finally get the following energy estimate for the fluid:

$$\begin{aligned} \frac{\rho^f}{2} \partial_\tau \|\mathbf{u}_h^{n+1}\|_{0,\Omega_f^{n+1}}^2 + 2\mu_f \|\boldsymbol{\epsilon}(\mathbf{u}_h^{n+1})\|_{0,\Omega_f^{n+1}}^2 + \sum_{i \in \{\text{mv}, \text{ao}\}} \int_{\Gamma_i} \mathbf{f}_{\Gamma_i}(\mathbf{u}_h^{n+1} - \mathbf{w}_h^{n+1}, p^{n+1}) \cdot \mathbf{u}_h^{n+1} \\ \leq \int_{\Gamma_1} \boldsymbol{\lambda}_h^{n+1} \widehat{\mathbf{u}}_h^{n+1} - \int_{\Gamma_{pv} \cup \Gamma_{ao}} P_{pv,ao}^{n+1} \mathbf{u}_h^{n+1} \cdot \mathbf{n}_f. \end{aligned} \quad (46)$$

We now proceed by adding the relations (45) and (46), and after some mathematical manipulations, it only remains to control the following interfacial terms on the right-hand side:

$$\underbrace{\alpha \langle \widehat{\mathbf{u}}_h^n - \mathbf{u}_{s,h}^{n+\frac{1}{2}}, \mathbf{u}_{s,h}^{n+\frac{1}{2}} \rangle - \langle \boldsymbol{\lambda}_h^n, \mathbf{u}_{s,h}^{n+\frac{1}{2}} \rangle + \langle \boldsymbol{\lambda}_h^{n+1}, \mathbf{u}_h^{n+1} \rangle}_{T_1}.$$

These terms can be handled as in [12], which yields

$$T_1 = \frac{\alpha}{2} \left(\|\widehat{\mathbf{u}}_h^n\|_{0,\Gamma_1}^2 - \|\widehat{\mathbf{u}}_h^{n+1}\|_{0,\Gamma_1}^2 \right) + \frac{1}{2\alpha} \left(\|\boldsymbol{\lambda}_h^n\|_{0,\Gamma_1}^2 - \|\boldsymbol{\lambda}_h^{n+1}\|_{0,\Gamma_1}^2 \right) - \alpha \|\mathbf{u}_{s,h}^{n+\frac{1}{2}} - \widehat{\mathbf{u}}_h^n\|_{0,\Gamma_1}^2.$$

The energy bound (42) then follows by multiplying by τ the resulting expression and then summing over $m = 0, \dots, n-1$, which completes the proof. \square

We conclude this section by noting that, using an argument as in Remark 3, the following energy bound can be inferred from (42):

$$\begin{aligned} \mathcal{E}_h^n + \sum_{m=0}^{n-1} \frac{\tau}{2} \mathcal{D}_h^{m+1} \leq \mathcal{E}_h^0 + \sum_{m=0}^{n-1} \tau \int_{\Omega} U_0 |u_e^{m+1}|_+ + \frac{C_T C_K}{\mu} \sum_{i \in \{\text{pv}, \text{ao}\}} \sum_{m=0}^{n-1} \tau \|P_i(t_{m+1})\|_{0,\Gamma_i}^2 + \sum_{m=0}^{n-1} \frac{\tau}{2} |P_{vs,r}(t_{m+\frac{1}{2}})|^2 \\ + \sum_{m=0}^{n-1} \frac{\tau K_{at,r}}{2} |P_{at,r}(t_{m+\frac{1}{2}})|^2, \end{aligned}$$

which guarantees the unconditional stability of Algorithm 2 in the energy norm.

4 Numerical results

In this section, we present the numerical results of the left heart hemodynamics obtained using both the kinematical uncoupling approach (Section 4.1) and a fluid-structure interaction model in the left ventricle (Section 4.2.2). The computational geometries used in the numerical examples were obtained from the Zygote heart model. For the solid we isolate the right and left ventricles and the endocardial surfaces are smoothed, with the `3-matic` software (Materialise), by removing trabeculae and papillary muscles (see Figure 7(a)). For the fluid, the endocardial surface of the left ventricle is first extracted and a volume mesh of the left ventricle cavity is constructed, which ensures the interface matching nature of the fluid and solid meshes (see Figure 7(b)). The endocardial surfaces of the left atrium and of the ascending aorta are then extracted from the Zygote heart model, and volume meshes of these cavities are then generated, by incorporating the closed configuration of the immersed mitral $\Gamma_{mv}^{\text{closed}}$ and aortic $\Gamma_{ao}^{\text{closed}}$ valves, and the open configuration of the mitral valve $\Gamma_{mv}^{\text{open}}$ in the fluid domain. These immersed surfaces are duplicated in the fluid mesh (cracked mesh), which facilitates the introduction of strong discontinuities in the pressure approximation across the valves. The solid and fluid volume meshes are made of tetrahedra, and obtained using the 3D meshing software `Gmsh` (see [31]). More specifically, the solid mesh is composed of 45,584 vertices and 106,747 tetrahedra, while the fluid mesh is composed of 28,090 vertices and 148,333 tetrahedra.

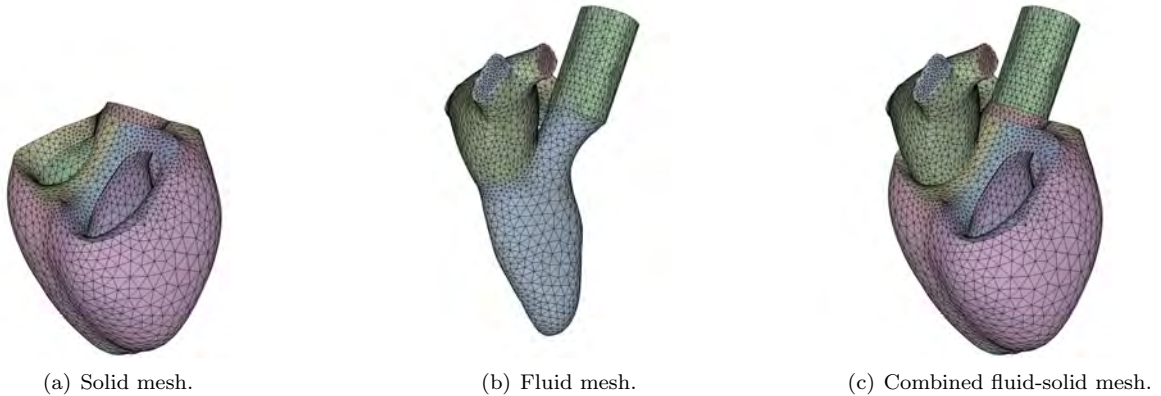


Figure 7: Computational meshes for the fluid and the solid sub-domains.

All the numerical computations have been performed using the fluid solver of the `FELISce`¹ library and the cardiac mechanics solver of the `MoReFEM`² library. Owing to the genuine partitioned nature of Algorithm 2, the FSI coupling is performed by linking the two softwares in a segregated fashion, via an external coupling interface based on the `ZeroMQ`³ message passing library.

4.1 Kinematical uncoupling

In this section, we use the kinematic uncoupling modeling approach to delve into the influence on the left heart hemodynamics of the reduced valve models introduced in Sections 2.3.1 and 2.3.2. First, the 3D-0D cardiac mechanics problem (13) and (21) is solved with an analytical electrical input u_e , which mimics the FitzHugh-Nagumo dynamics (see [29, 46]), and initiates at the apex of the heart. Afterwards, the fluid problem (14) and (20) is solved separately, using the left endocardial motion provided by 3D-0D cardiac mechanics solve, for both the RIS and the velocity-constrained reduced valve models.

| Parameter | Left Ventricle | Right Ventricle |
|-------------------------------|---------------------|---------------------|
| μ_1 (Pa) | 0.0 | 0.0 |
| μ_2 (Pa) | 0.0 | 0.0 |
| C_0 (Pa) | $1.9 \cdot 10^3$ | $1.9 \cdot 10^3$ |
| C_1 | $1.1 \cdot 10^{-1}$ | $1.1 \cdot 10^{-1}$ |
| C_2 (Pa) | $1.9 \cdot 10^3$ | $1.9 \cdot 10^3$ |
| C_3 | $1.1 \cdot 10^{-1}$ | $1.1 \cdot 10^{-1}$ |
| ν (N s m^{-1}) | 70. | 70. |
| κ (Pa) | $2 \cdot 10^5$ | $2 \cdot 10^5$ |

Table 1: Passive physical parameters of the cardiac mechanics model.

¹<https://gitlab.inria.fr/felisce>

²<https://gitlab.inria.fr/MoReFEM>

³<https://zeromq.org>

| Parameter | Left Ventricle | Right Ventricle |
|-------------------------------|------------------|-------------------|
| α_d | 1.5 | 1.5 |
| σ_0 (Pa) | $4.6 \cdot 10^5$ | $3.72 \cdot 10^5$ |
| E_s (Pa) | $3 \cdot 10^7$ | $3 \cdot 10^7$ |
| k_0 (Pa) | $1 \cdot 10^5$ | $1 \cdot 10^5$ |
| η (N s m ⁻¹) | 70. | 70. |

Table 2: Active physical parameters of the cardiac mechanics model.

| Parameter | Left Ventricle | Right Ventricle |
|--|----------------------|--------------------|
| C_p (m ³ Pa ⁻¹) | $2 \cdot 10^{-9}$ | $2 \cdot 10^{-10}$ |
| R_p (Pa s m ⁻³) | $2 \cdot 10^7$ | $1 \cdot 10^7$ |
| C_d (m ³ Pa ⁻¹) | $5.05 \cdot 10^{-9}$ | $1 \cdot 10^{-8}$ |
| R_d (Pa s m ⁻³) | $2 \cdot 10^8$ | $3 \cdot 10^7$ |
| P_{vs} (Pa) | $1 \cdot 10^3$ | $1 \cdot 10^3$ |

Table 3: Parameters Windkessel model

| Parameter | Left Ventricle |
|--|----------------|
| ρ_f (kg m ⁻³) | 1006 |
| μ_f (Pa s) | 0.004 |
| $R_{\text{closed}}^{\Gamma_{\{mv,ao\}}}$ (kg m ⁻² s ⁻¹) | 10^7 |
| R_{open} (kg m ⁻² s ⁻¹) | 10^7 |
| ε (Vel. Constrained) (m ² s kg ⁻¹) | 10^{-7} |

Table 4: Physical parameters of the fluid model.

The values of the considered physical parameters for the cardiac and fluid models are reported in Tables 1–4. The ventricles are assumed to be initially in a pre-loaded configuration, corresponding to the beginning of the diastolic phase. This initial configuration is obtained by solving a static version of (13) (i.e., time derivatives are set to zero) with a preload pressure of $P_r = 25$ Pa in the right ventricle and of $P_l = 500$ Pa in the left ventricle. The initial configuration of the fluid domain is then retrieved by lifting the initial solid displacement via (20)₁. The fluid is assumed to be initially at rest.

The electromechanical and fluid simulations cover a complete heart beat with a duration of $t = 0.85$ s. We consider a fixed time step of $\tau = 5 \cdot 10^{-4}$ seconds for the solid domain, and $\tau = 10^{-3}$ seconds for the fluid domain. The smaller time step in the solid is necessary to ensure convergence during the ventricular contraction phase.

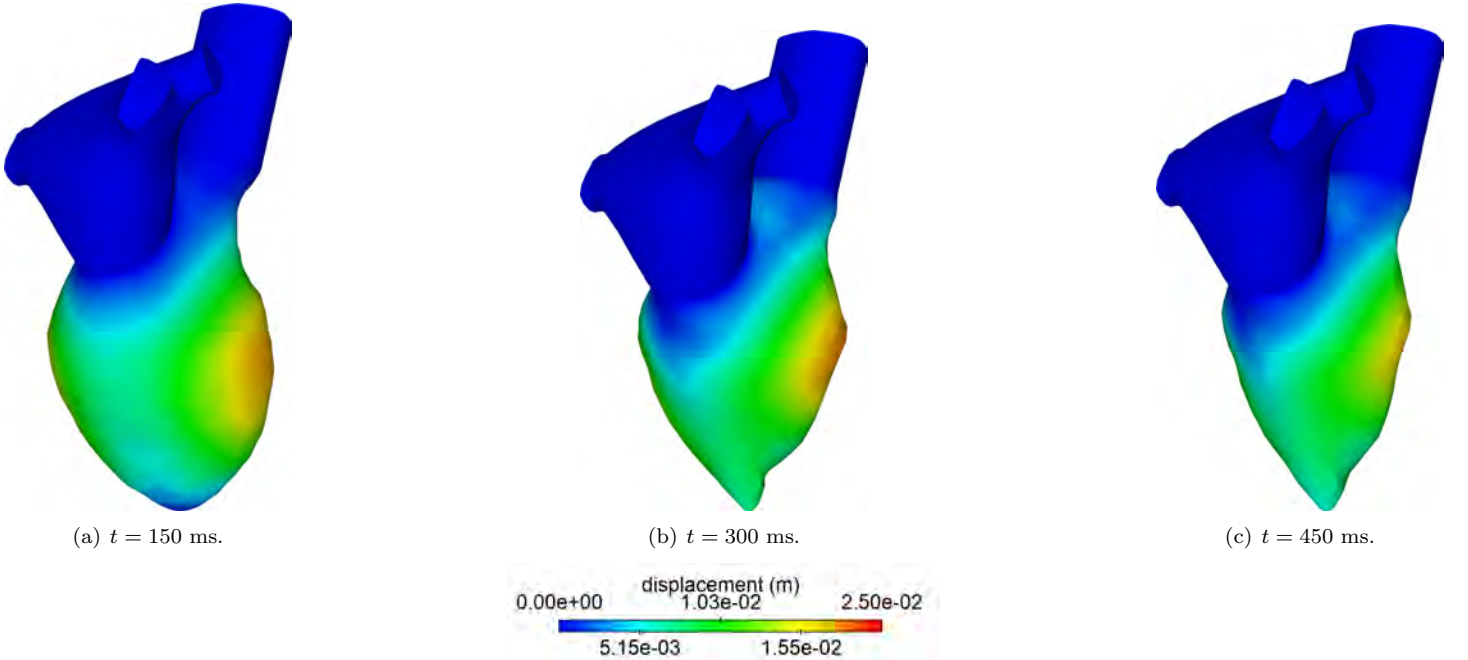


Figure 8: Deformed left heart cavity configurations and snapshots of the endocardial displacement magnitude at three different time instants.

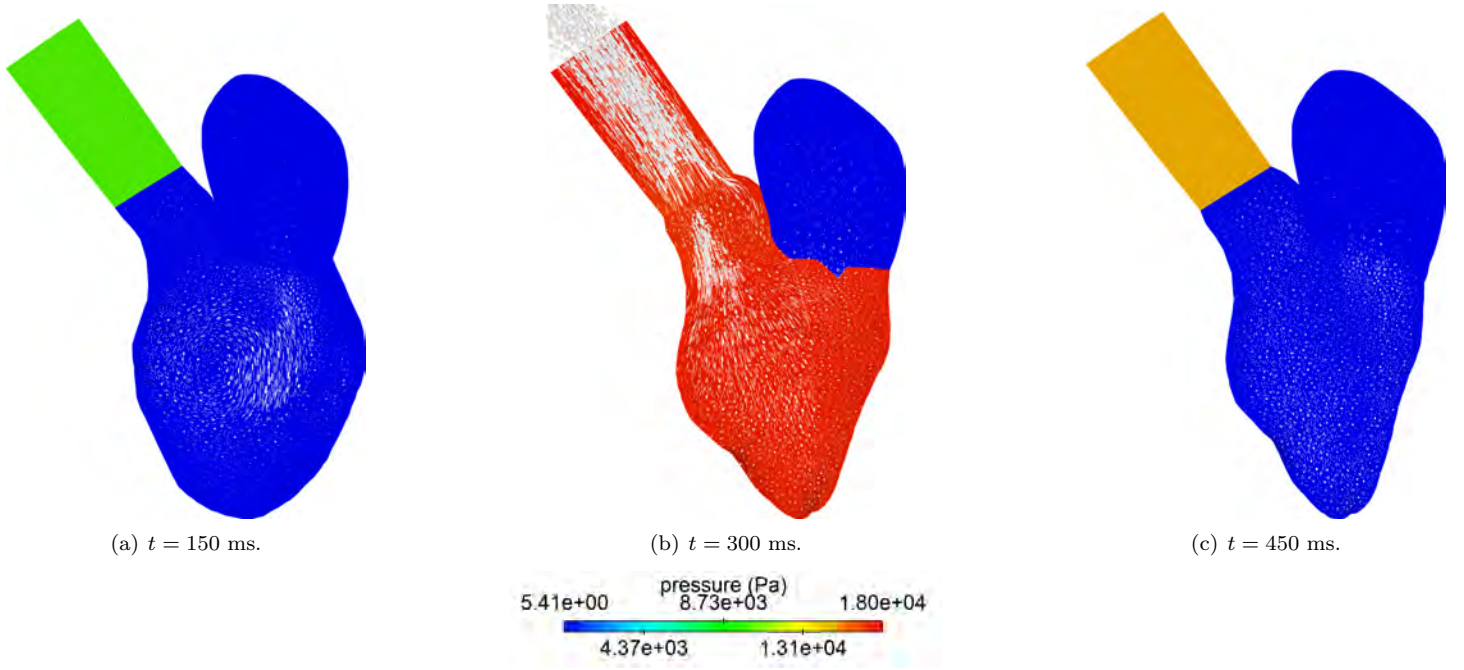


Figure 9: Long axis snapshots of the pressure and velocity fields at three different time instants.

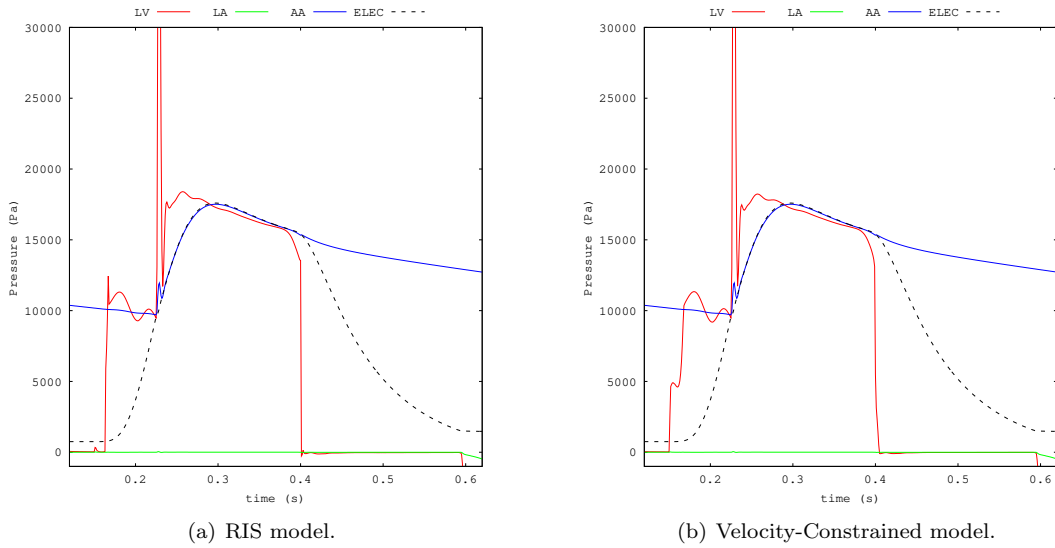


Figure 10: Simulated Wiggers diagrams.

Figure 8 provides some snapshots of the endocardial displacement magnitude. During the filling phase (Figure 8(a)), the fluid domain primarily displaces laterally. In contrast, during the ejection phase (Figure 8(b)), a significant displacement is observed near the apex of the left ventricle, representing its contraction. The isovolumic relaxation phase (Figure 8(c)) shows a slight decrease in the displacements due to the isovolumetric constraint.

In Figure 9 we have reported the fluid pressure and velocity fields obtained with the velocity constrained model on a long axis cut plane of the left heart at three different time instants. Similar results are obtained with the RIS model, which are omitted here for the sake of conciseness. At the filling phase (Figure 9(a)), the emergence of a single vortex that rotates clockwise is clearly visible, which is in agreement with available physiological observations (see, e.g., [21, 22]). At this stage, the pressure in the left atrium is slightly large than in the left ventricle, which induces blood flow from the left atrium to the left ventricle. On the other hand, the pressure in the aorta is higher than in the left ventricle, indicating that the aortic valve is closed, and there is no flux in that region. During the ejection phase (Figure 9(b)), there is a flux from the left ventricle to the aorta, with a slightly higher pressure in the former region. At this stage, the pressure in the left atrium is lower than in the left ventricle, indicating that the mitral valve is closed, and there is no flux in this region. Finally, during the iso-volumetric relaxation phase, the pressure inside the left ventricle is higher than in the left atrium but lower than in the aorta, indicating that both the mitral and aortic valves are closed.

Figure 10 presents the numerical Wiggers diagrams obtained with the RIS model and the velocity constrained reduced valve models. For comparison purposes, the 0D left ventricular pressure provided by the cardiac mechanics model (13) is also shown. One can clearly see that both models produce strong spurious oscillations in the ventricular pressure, which are not observed in cardiac mechanics simulation. The peak pressure occurs at $t = 225$ and $t = 226$ ms with values of $1.7 \cdot 10^7$ Pa and 44101.3 Pa for the RIS and the velocity constrained model, respectively. Lower oscillations are thus observed in the latter. Moreover, the RIS model exhibits a more pronounced delay in the onset of iso-volumetric relaxation. However, the oscillations persist irrespective of the valve model considered. These results suggest that the presence of spurious oscillations may be more related to the type of model coupling approach between the fluid and solid than to the reduced model considered for the valves.

4.2 Fluid-structure interaction

The purpose of this section is twofold. We first consider a representative simplified two-dimensional setting in which numerical evidence on the accuracy of Algorithm 2 is provided (Section 4.2.1). The impact of the free Robin coefficient α and of the number of corrections iterations is addressed in this example. Finally, in the context of the coupled FSI problem (13), (14) and (22), we delve into the capabilities of Algorithm 2 to provide physiological simulations of the left heart hemodynamics (Section 4.2.2), notably with respect to KU results of the previous section.

4.2.1 Academic test case

We consider a simplified two-dimensional geometrical setting which retains the main fundamental ingredients of the cardiac cycle phases in the left ventricle. The fluid domain Ω_f is assumed to be partitioned in three disjoint sub-domains $\Omega_{f,1} \stackrel{\text{def}}{=} [0, 2.5] \times [0, 3]$, $\Omega_{f,2} \stackrel{\text{def}}{=} [2.5, 11.5] \times [0, 3]$, and $\Omega_{f,3} \stackrel{\text{def}}{=} [11.5, 14] \times [0, 3]$ which respectively correspond to the atrium, the left ventricle and the aorta. The mitral and aortic valves are described by the immersed interfaces $\Gamma_{12} \stackrel{\text{def}}{=} \partial\Omega_{f,1} \cap \Omega_{f,2}$ and $\Gamma_{23} \stackrel{\text{def}}{=} \partial\Omega_{f,2} \cap \Omega_{f,3}$, respectively. The boundaries are partitioned as follows: $\partial\Omega_{f,1} = \Gamma_{f,1}^{\text{in}} \cup \Gamma_{f,1}^{\text{t}} \cup \Gamma_{f,1}^{\text{b}} \cup \Gamma_{12}$, $\partial\Omega_{f,2} = \Gamma_1 \cup \Gamma_{f,2}^{\text{b}} \cup \Gamma_{12} \cup \Gamma_{23}$ and $\partial\Omega_{f,3} = \Gamma_{f,3}^{\text{out}} \cup \Gamma_{f,3}^{\text{t}} \cup \Gamma_{f,3}^{\text{b}} \cup \Gamma_{23}$, see Figure 11.

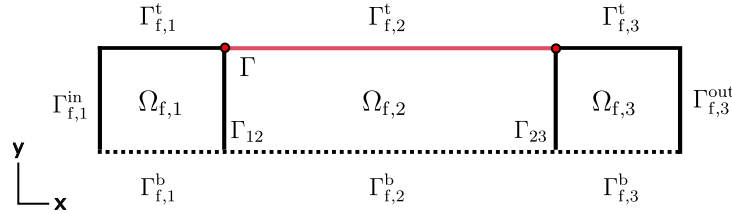


Figure 11: Geometrical configuration.

Flow in the fluid cavities is described by the Navier-Stokes system (14) with the RIS model (15) for the valves. The dynamics of the myocardial wall Γ_1 are described by a non-linear Timoshenko beam model (see, e.g., [15]), with the following source term which replicates the effect of the active contraction/relaxation:

$$\mathbf{f}^b(\mathbf{x}, t) = \begin{cases} 5075 \tanh(100(t - (0.1 + T))) + 5075 & \text{for } 0 \leq t \leq 0.18 + T, \\ -5075 \tanh(100(t - (0.2 + T))) + 5075 & \text{for } 0.18 + T < t \leq T, \end{cases}$$

where T represents the period of the volumetric force, with $T = 0.225$ s. As regards the boundary conditions, the solid domain is clamped at its extremities. A non-slip condition is imposed on the fluid upper wall $\Gamma_{f,1}^{\text{t}} \cup \Gamma_{f,3}^{\text{t}}$, and a symmetry condition on the fluid bottom walls of the fluid domains $\Gamma_{f,1}^{\text{b}} \cup \Gamma_{f,2}^{\text{b}} \cup \Gamma_{f,3}^{\text{b}}$. Finally, the following Neumann conditions at the inlet and outlet fluid boundaries:

$$\begin{cases} \boldsymbol{\sigma}(\mathbf{u}, p)\mathbf{n}_f = -100\mathbf{n}_f & \text{on } \Gamma_{f,1}^{\text{in}}, \\ \boldsymbol{\sigma}(\mathbf{u}, p)\mathbf{n}_f = -\left(10000 + R \int_{\Gamma_{f,3}^{\text{out}}} \mathbf{u} \cdot \mathbf{n}_f\right)\mathbf{n}_f & \text{on } \Gamma_{f,3}^{\text{out}}. \end{cases}$$

with $R = 1.5 \cdot 10^4 \text{Pa s m}^{-3}$. The fluid and the solid are assumed to be initially at rest. As material properties, the fluid density is set to $\rho_f = 1006 \text{kg m}^{-3}$, and the dynamic viscosity is $\mu = 0.004 \text{Pa s}$. For the the solid density is $\rho^s = 1200 \text{kg m}^{-3}$, the Young's modulus is $E = 10^5 \text{Pa}$, and the Poisson ratio is $\nu = 0.5$.

The resulting coupled problem is approximated numerically using Algorithm 2 as in Section 3, with the exception that the Timoshenko beam is discretized using MITC beam elements. In particular, the fluid mesh is composed of 2202 triangles, while the solid mesh is composed of 40 segments.

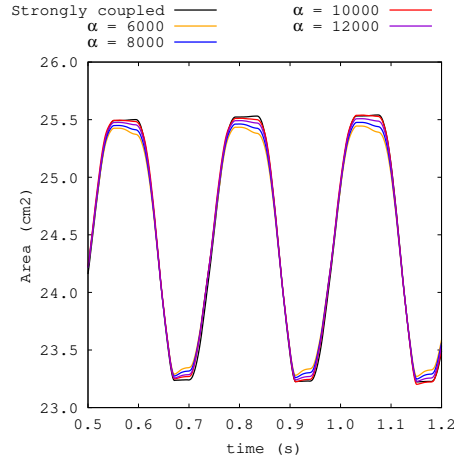


Figure 12: Temporal evolution of the area $|\Omega_{f,2}^n|$ obtained with the strongly coupled scheme and Algorithm 2 for different values α and three correction iterations.

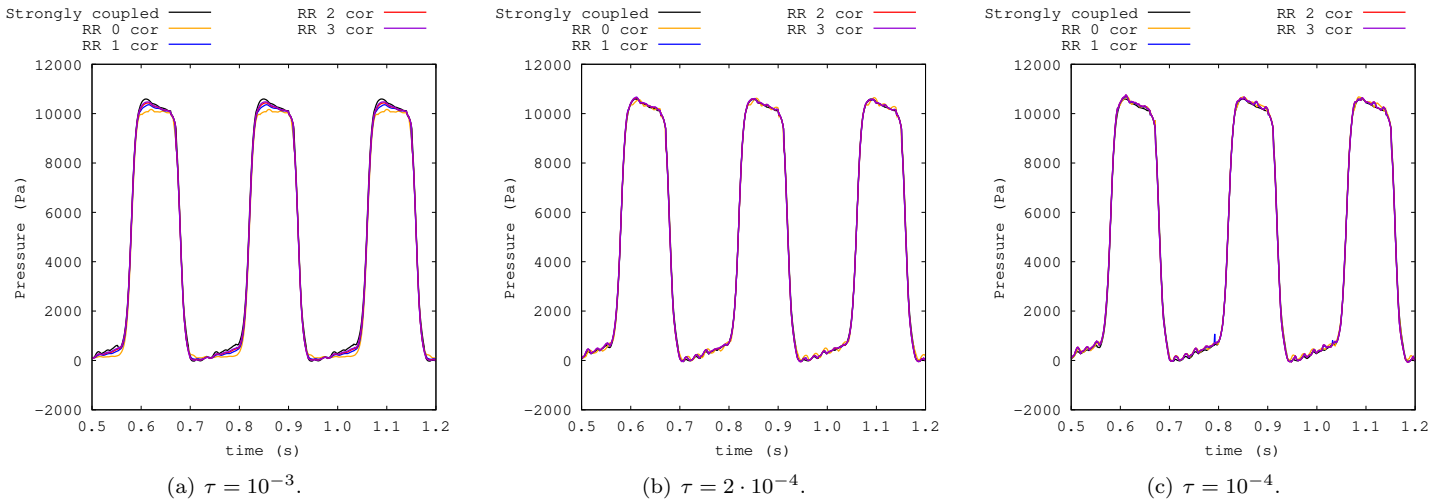


Figure 13: Time history of pressure obtained with the strongly coupled scheme and Algorithm 2 for $\alpha = 10^4$ and different time-step lengths.

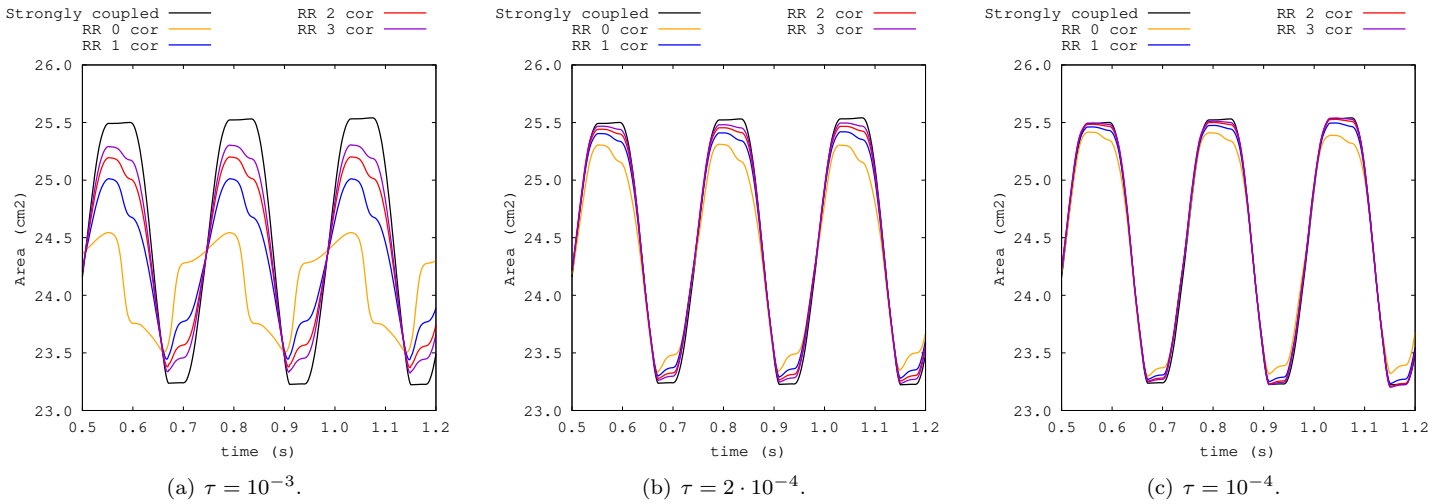


Figure 14: Time history of the area $|\Omega_{f,2}^n|$ obtained with the strongly coupled scheme and Algorithm 2 for $\alpha = 10^4$ and different time-step lengths.

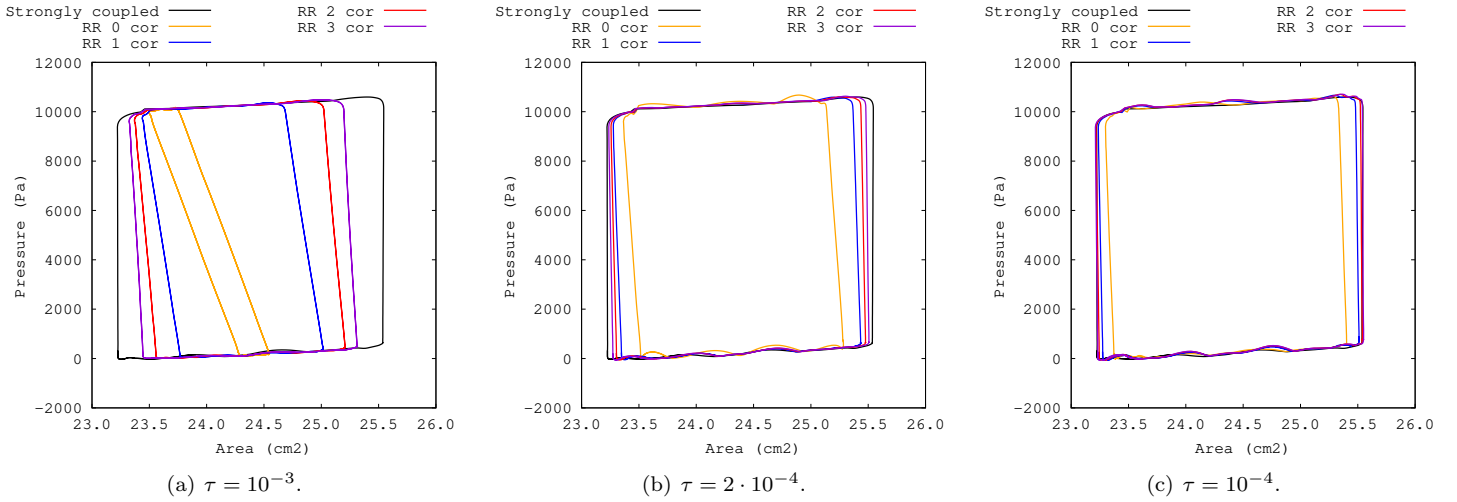


Figure 15: Pressure-area loops obtained with the strongly coupled scheme and Algorithm 2 for $\alpha = 10^4$ and different time-step lengths.

Figure 12 provides the temporal evolution of the ventricular area $|\Omega_{f,2}^n|$ obtained with Algorithm 2 for different values of α , with $\tau = 10^{-4}$, and considering three iteration corrections. We recall that one correction iteration amounts to perform once more the three steps of Algorithm 2 with updated Robin conditions. For comparison purposes, the results obtained with a strongly coupled scheme are also reported. We can clearly see that the accuracy of Algorithm 2 is sensitive to the values of α . In particular, small and large values of α can compromise accuracy. These results are also in agreement with the error estimates provided in [12], which postulate an optimal value scaling as $\alpha = \mathcal{O}(\sqrt{\rho_s E})$.

Figure 13 shows the evolution of the average pressure within the ventricular cavity $\Omega_{f,2}^n$ for different time-step lengths $\tau \in \{10^{-3}, 2 \cdot 10^{-4}, 10^{-4}\}$ and corrections iterations in Algorithm 2. The value of the Robin parameter is fixed and set to $\alpha = 10^4 \text{ kg m}^{-2} \text{ s}^{-2}$, based on the results of Figure 12. Once more, for comparison purposes we also show the results obtained with a strongly coupled scheme, with a fixed time step of $\tau = 10^{-4}$. As the number of corrections iteration increases or the time-step length τ decreases, the pressure approximation provided by Algorithm 2 converges to the reference provided by the strongly coupled scheme. For large τ , further correction iterations are necessary for accuracy. However, for moderate and small values of τ , the approximation is close to the reference solution irrespectively of the number of corrections iterations. Regardless of the improvement in accuracy when increasing the number of corrections iterations or decreasing the time-step lengths, there are no significant differences in the evolution of the pressure with respect to these user-defined parameters.

The temporal evolution of the area of the fluid domain $\Omega_{f,2}^n$ is reported in Figure 14. We can clearly observe that the area is more sensitive than the pressure to the time-step length and the number of correction iterations. Particularly, the evolution of the area is underestimated for large values of τ or a small number of correction iterations. A salient feature of the results of Figure 14, is that it provided numerical evidence on that Algorithm 2 can accurately capture phases of constant areas (the isovolumetric phases in the cardiac hemodynamics setting) by reducing τ or by increasing the number of correction iterations. Similar conclusions can be inferred from Figure 15, which provides the pressure-area loops obtained with the strongly coupled scheme and Algorithm 2 for $\alpha = 10^4$ and different time-step lengths. The maximum pressure remains similar for all cases, regardless of the time-step length or the number of correction iterations. Nevertheless, the impact of these user-defined parameters on the area is evident. In general, the smaller the time-step lengths, the fewer iteration corrections are necessary to capture the iso-area phases.

4.2.2 Left heart hemodynamics

The purpose of this section is to illustrate numerically the capabilities of Algorithm 2 to provide meaningful left heart hemodynamics simulations, via the approximation of the coupled FSI problem (13), (14) and (22). We also compare the impact on these simulations of the two reduced valve dynamics models presented in Section 2.3. The geometrical setting, initial conditions and computational meshes are the same as in Section 4.1. The considered physical parameters are also those reported in Tables 1–4. We simulate three heartbeats, each with a duration of $t = 0.85 \text{ s}$. Based on the results of Algorithm 2 in the simplified cardiac example of Section 4.2.1, we set $\tau = 2.5 \cdot 10^{-4} \text{ s}$, $\alpha = 10^4 \text{ kg m}^{-2} \text{ s}^{-2}$ and two correction iterations are performed at each time-step, to accurately capture the isovolumetric phases. In the following, we only present the results of the last heartbeat, that is, for the time interval $[1.7\text{s}, 2.55\text{s}]$.

Figure 16 presents the pressure and volume time-histories of the left ventricle and the associated pressure-volume loops obtained with Algorithm 2 and the two reduced valve models. Both reduced models yield similar results, which is also consistent with the results presented in Section 4.1. However, unlike the kinematic uncoupling approach, here no spurious

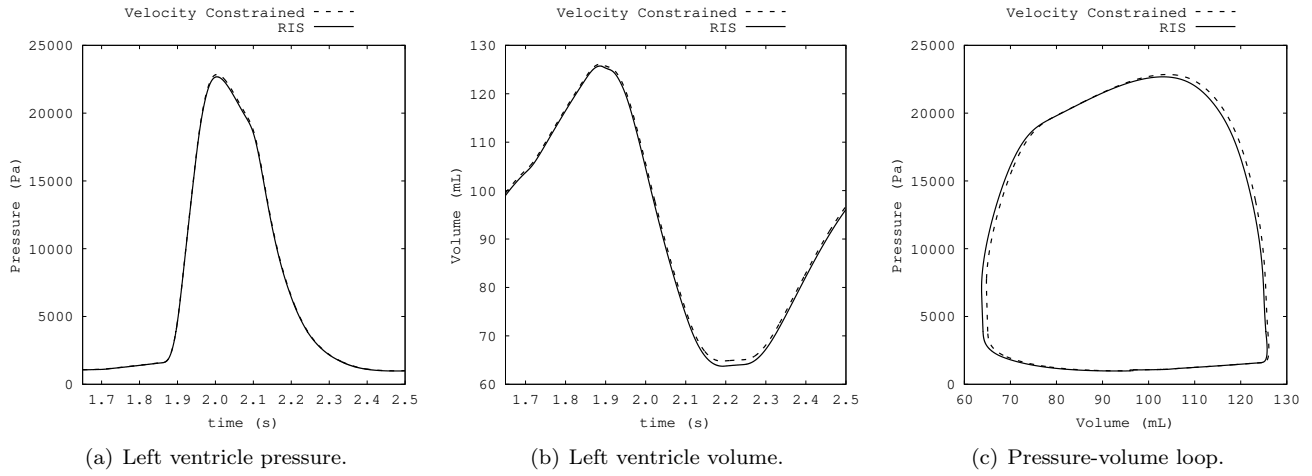


Figure 16: Pressure and volume time-histories obtained with Algorithm 2, with $\tau = 2.5 \cdot 10^{-4}$, $\alpha = 10^4$ and two correction iterations.

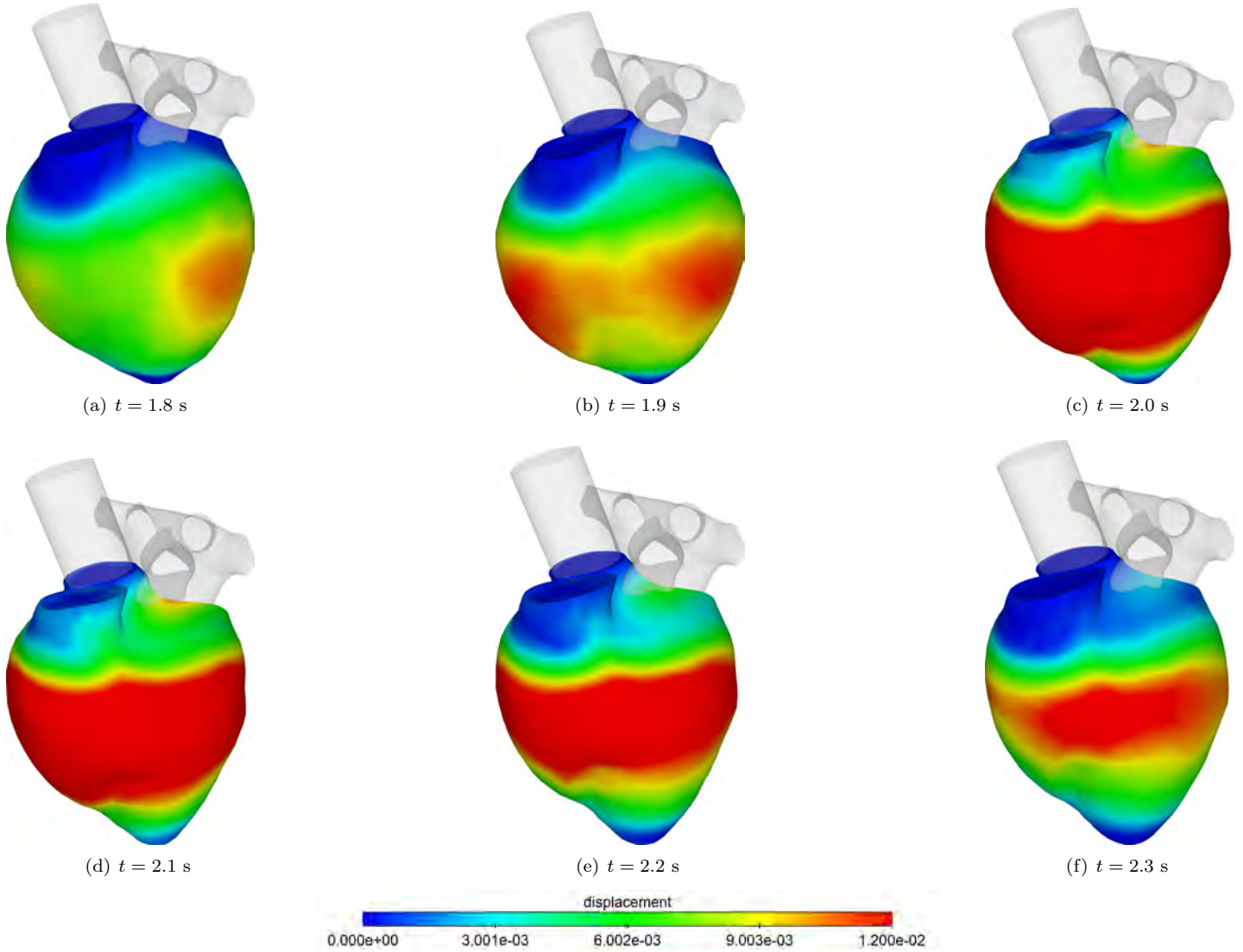


Figure 17: Snapshots of the solid displacement magnitude (deformed configuration) at different time instants, obtained with Algorithm 2, with $\tau = 2.5 \cdot 10^{-4}$, $\alpha = 10^4$ and two correction iterations.

pressure oscillations are seen. This provides numerical evidence on that, as postulated in the introduction, the artificial

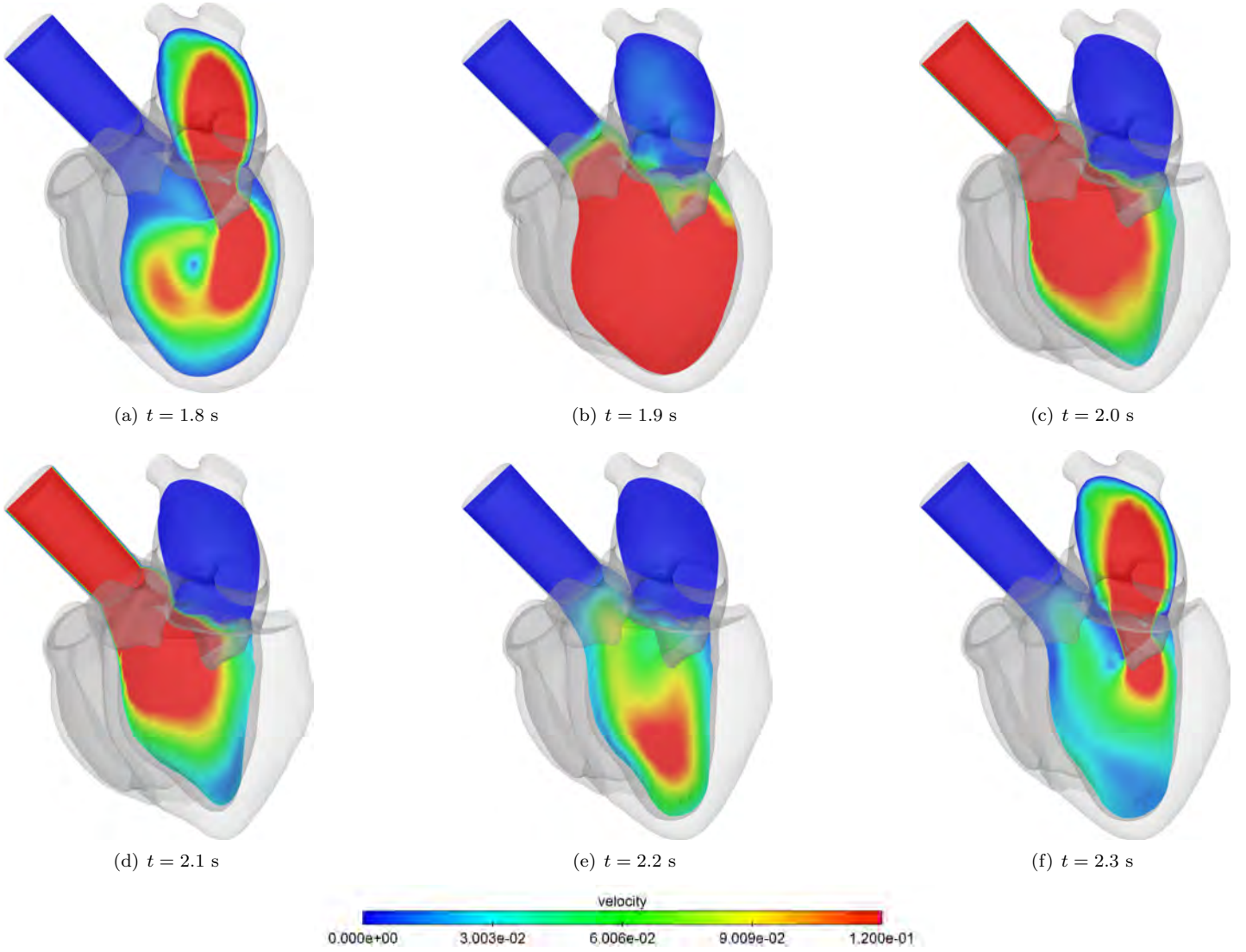


Figure 18: Snapshots of the fluid velocity magnitude at different time instants (deformed configuration) obtained with Algorithm 2, with $\tau = 2.5 \cdot 10^{-4}$, $\alpha = 10^4$ and two correction iterations.

pressure oscillation observed with the kinematic uncoupling approach are due the lack of compatibility between the kinematical constraint and the status of the reduced valve model. It is also worth noting that the results of Figure 16 show a good reproduction of isovolumic phases.

For illustration purposes, snapshots of the displacement, velocity and pressure fields of the solid and the fluid are presented in Figures 17, 18 and 19, respectively. The cycle starts with the ventricles entering a phase of passive filling. During this phase, the mitral and tricuspid valves are open, allowing blood flow from the atria to the ventricles (see Figure 18(a)). At this stage, the fluid forms a jet immediately after the mitral valve, leading to the generation of a vortex ring that rotates clockwise, located almost at the intermediate section of the left ventricle, as shown in Figure 19(a). This is consistent with biomedical literature (see, e.g., [22, 21]). This flow induces an increase in volume in the left ventricle, and also in the right ventricle due to the lumped parameter fluid coupled with it (see Figure 17(a)). The rate of volume rise remains nearly constant from the mid-to-late diastolic phase. The filling phase continues until the ventricles begin to contract, which marks the end of the diastolic phase. During this phase, the flow from the left atrium to the left ventricle remains relatively constant at a rate of 57.56 mL s^{-1} . The end-diastolic volume (EDV) is $\text{EDV}_l = 105.85 \text{ mL}$ for the right ventricle and $\text{EDV}_r = 125.72 \text{ mL}$ for the left ventricle, consistently with physiological values reported in literature (see, e.g., [20, 34, 42]).

At the end of the diastolic phase, the cardiac cycle transitions into the systolic phase, marked by the ventricular contraction. This contraction leads to an increase in the intraventricular pressure of the right and left ventricles. The increase in the intraventricular pressure induces a backflow from the ventricles to the atrium, leading to the closure of the tricuspid and mitral valves in the right and left ventricle, respectively. This marks the beginning of the isovolumic contraction phase, during which both cavities are closed while the ventricles contract. During this stage, the intraventricular pressure increases but remains lower than the aortic pressure, as seen in Figure 19(b). The displacements, on the other hand, remain similar to those of the end-diastolic stage (see Figure 17(b)). Figure 18(b) illustrates the velocity field, which becomes more homogeneous

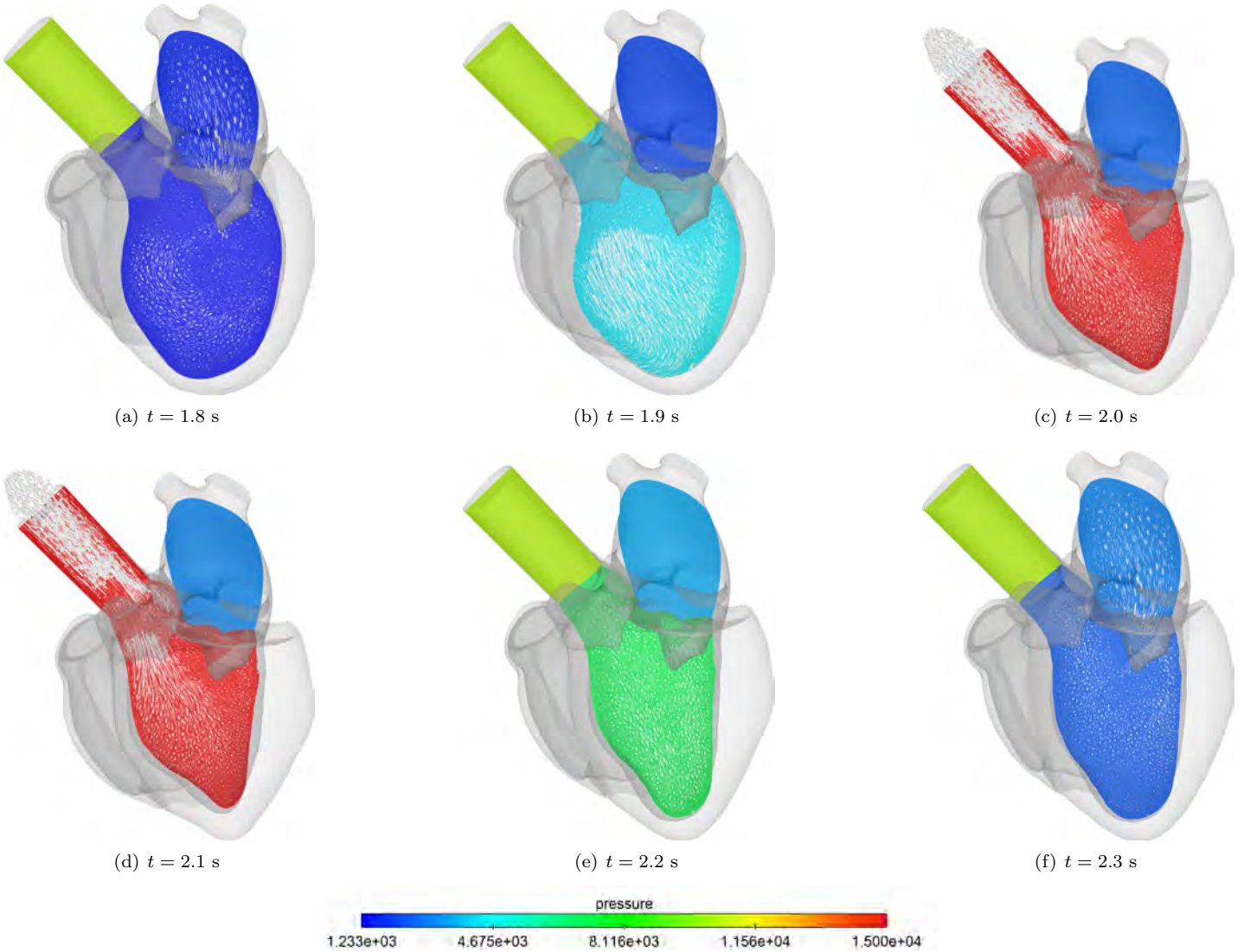


Figure 19: Snapshots of the fluid pressure and velocity fields at different time instants (deformed configuration) obtained with Algorithm 2, with $\tau = 2.5 \cdot 10^{-4}$, $\alpha = 10^4$ and two correction iterations.

due to the contraction of the myocardium.

The isovolumic contraction phase persists until the pulmonary and aortic valves open, as the intraventricular pressures increases to a value higher than the pressures in the pulmonary artery and aorta. This results in the opening of the pulmonary and aortic valves, marking the beginning of the ejection phase. This phase is characterized by the ejection of the blood from the right ventricle into the pulmonary artery and from the left ventricle into the aorta. This phenomenon is evidenced by the substantial deformation in both the right and left ventricles, accompanied by a downward movement of the ventricular base, as it can be appreciated in Figures 17(c) and 17(d). During the first part of this phase, the intraventricular pressures continue to increase reaching maximum values of $p_{l,\max} = 22849$ Pa and $p_{r,\max} = 4494.78$ Pa at $t = 2.004$ s and $t = 1.99825$ s, respectively, consistently with the physiological ranges reported in the literature (see, e.g., [1, 14, 50]). The fluid in the left ventricle reduces as the ventricle contracts, reducing gradually the intraventricular pressure and the blood flux from the left ventricle into the aorta. Figures 18(c), 18(c) illustrate the unsteady nature of the flow, with a maximum flow rate of 319.13 mLs $^{-1}$ at $t = 2.00875$ s followed by a constant decrease towards the end of the ejection phase, in correspondence with the small deformations of the ventricles.

The ejection fraction (EF) represents the percentage of blood leaving the heart during contraction, given by $EF \stackrel{\text{def}}{=}} SV/EDV$ where SV represents the stroke volume, computed as $SV \stackrel{\text{def}}{=} EDV - ESV$, with EDV representing end-diastolic volume, and ESV representing end-systolic volume. The ejection fraction of the left ventricle is $EF = 0.457$, within the physiological range reported in the literature (see, e.g., [20, 65]).

During the last part of the ejection phase, the ventricles start to repolarize. This electrical change triggers the relaxation of the heart muscles, gradually easing the contraction of the ventricles. As the ventricular contraction diminishes, the pressure inside the ventricles drops below the pressure in the pulmonary artery and aorta (see Figure 19(e)). This drop in pressure causes the pulmonary and aortic valves to close, while the tricuspid and mitral valves remain closed. This phenomenon signifies

the start of the isovolumetric relaxation phase, during which both ventricular chambers remain closed as the ventricles continue to relax and return to their original configuration, as seen in Figure 17(e). Similar to the isovolumetric contraction stage, the velocity field becomes more homogeneous during this phase (see Figure 18(e)). During the isovolumetric relaxation phase, the intraventricular pressure continues to decrease until its value is lower than the pressure in the atrium. Subsequently, the tricuspid valve and mitral valve open, initiating the filling stage and starting a new heart cycle.

5 Conclusion

In this paper, we have introduced a novel reduced model of valve dynamics which circumvents the limitations of traditional resistive immersed surface (RIS) approaches, where valve laws are given in a pure algorithmic fashion. The basic idea consists in enforcing unidirectional flow through a penalized inequality constraint on the normal velocity of the fluid. The price to pay (notably with respect to RIS) is a semi-smooth non-linearity in the fluid solver, which can however be efficiently handled with a few Newton iterations. The numerical comparisons between RIS and the velocity constrained models indicate that, though different in essence, they deliver rather similar results. In particular, artificial pressure oscillations are observed in both when combined with a one-way kinematic uncoupling approach.

An alternative left heart hemodynamics modeling approach which combines the above mentioned reduced valve dynamics models with a fluid-structure interaction (FSI) coupling in the left ventricle has also been proposed. In order to mitigate the computational complexity of the coupled system, the interface coupling is solved with a Robin-Robin loosely coupled scheme (Algorithm 2). A salient feature of the proposed method is that an a priori energy analysis (Theorem 2) guarantees the unconditional stability of the fully discrete approximations. The left heart hemodynamics simulations showed that the above mentioned spurious pressure oscillations are removed by the FSI coupling, irrespectively of the reduced valve model considered. The results also showed that the proposed loosely coupled scheme is able to reproduce physiological isovolumetric phases with a temporal grid of around 4000 time-steps per cardiac cycle (i.e., $\tau = 2 \cdot 10^{-4}$ s), a couple of correction iterations and a judicious choice of the Robin coefficient α (previously tuned in a simplified cardiac setting). Finally, simulated biomarkers such as ejection fractions, end-diastolic volume and min/max ventricular pressures were within the physiological ranges.

Extensions of this work can explore several directions. A more comprehensive left heart hemodynamics model can be considered by incorporating an FSI model of the mitral valve. A further extension of the present approach is to tackle the question of second-order accuracy in the loosely coupled scheme. Finally, ongoing work focuses on the electromechanical simulation of the atria using 3D-shell elements, that are known to facilitate the coupling with surrounding media.

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