Conclusion

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Clustering

Data $X_{n \times p} = (x_{ij})$ a matrix of numeric values

Each individual *i* belongs to a unique cluster $C_i \in \{1, ..., K\}$.

Aim identify C_i for each i based on individual profiles $(\mathbf{x}_i)_{1 \leq i \leq n}$

Methods

Distance-based

- k-means
- fuzzy C-means
- hierarchical clustering
- partitioning around medoids

Model-based

- gaussian mixture models
- mixture of multivariate t-distributions
- mixture of skew normal distributions

However, **X** is frequently incomplete... $\mathbf{x}_i = (\mathbf{x}_i^{obs}, \mathbf{x}_i^{miss})$

Ad-hoc methods

Introduction

- removing incomplete observations
- removing incomplete variables
- single imputation

Direct methods

- k-means (Chi et al., 2016; Honda et al., 2011; Wagstaff, 2004)
- fuzzy C-means (Zhang et al., 2016; Hathaway and Bezdek, 2001)
- gaussian mixture (Miao et al., 2016; Marbac et al., 2019; McCaw et al., 2022)

k-POD (Chi et al., 2016)

Chi et al. (2016) proposed a direct method for k-means clustering

k-means

k-POD

$$\underset{\mathbf{A}\in\mathcal{H}.\mathsf{B}}{\arg\min} \parallel \mathbf{X} - \mathbf{A}\mathbf{B} \parallel_{F}^{2} \qquad \underset{\mathbf{A}\in\mathcal{H}.\mathsf{B}}{\arg\min} \parallel P_{\Omega}(\mathbf{X}) - P_{\Omega}(\mathbf{A}\mathbf{B}) \parallel_{F}^{2}$$

- \mathcal{H} set of membership matrices $(n \times \kappa)$, $\mathbf{B}_{K \times p}$ matrix of centers coordinates
- || . || Frobenius norm
- $\Omega \subset \{1,\ldots,n\} imes \{1,\ldots,p\} o$ subset of the indices for observed entries
- P_{Ω} projection operator so that $[P_{\Omega}(\mathbf{X})]_{ij} = \left\{egin{array}{l} x_{ij} & ext{if } (i,j) \in \Omega \\ 0 & ext{otherwise} \end{array}
 ight.$

The criterion is optimised by alternating imputation by b_k and kmeans clustering

Available in the **kpodclustr** R package

FCM by optimal completion strategy (Hathaway and Bezdek, 2001)

fuzzy c-means

fuzzy c-means OCS

with $\Gamma_{K \times n} = (\gamma_{ki})$ degrees of membership; α fuzzification parameter

The criterion is optimised by alternating FCM and imputation by weighted centers

$$\gamma_{ki}^{\alpha} \leftarrow 1 / \sum_{\ell=1}^{K} \left(\frac{\| \mathbf{x}_{i} - \mathbf{b}_{k} \|_{2}^{2}}{\| \mathbf{x}_{i} - \mathbf{b}_{\ell} \|_{2}^{2}} \right)^{\frac{1}{\alpha - 1}} \\
b_{kj} \leftarrow \left(\sum_{i=1}^{n} \gamma_{ki}^{\alpha} x_{ij} \right) / \left(\sum_{i=1}^{n} \gamma_{ki}^{\alpha} \right) \\$$

$$x_{ij}^{miss} \leftarrow \left(\sum_{k=1}^{K} \gamma_{ki}^{\alpha} b_{kj} \right) / \left(\sum_{k=1}^{K} \gamma_{ki}^{\alpha} \right) \\$$

Ignorable-GMM (Marbac et al., 2019)

Gaussian mixture models (GMM)

$$f(x; \theta) = \sum_{k=1}^{K} \pi_k f_k(x; \theta_k) \qquad \theta = (\theta_k)_{1 \le k \le K}, \theta_k = (\mu_k, \Sigma_k)$$

Log-likelihood GMM

Log-likelihood ignorable-GMM

$$\sum_{i=1}^{n} \log \sum_{k=1}^{K} \pi_{k} \prod_{j=1}^{p} f_{kj}(x_{ij}; \theta_{kj}) \qquad \sum_{i=1}^{n} \log \sum_{k=1}^{K} \pi_{k} \prod_{j \in O_{i}} f_{kj}(x_{ij}; \theta_{kj})$$

 $O_i \subseteq 1, \ldots, p$ the subset of variables indices that are observed for individual i

The criterion is optimised by using an EM algorithm

Available in the VarSelLCM R package

Direct methods: pros and cons

Direct methods provide an elegant way to address missing values

However, the approach

- is not versatile
- has not been developed for all clustering methods

Multiple Imputation (MI)

- a popular method to address missing values
- could be potentially used for any clustering method

Direct methods: pros and cons

Direct methods provide an elegant way to address missing values

However, the approach

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- has not been developed for all clustering methods

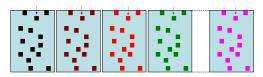
Multiple Imputation (MI)

- a popular method to address missing values
- could be potentially used for any clustering method

Multiple imputation (Rubin, 1987)

① Generate a set of M parameters $(\zeta_m)_{1 \leq m \leq M}$ of an imputation model to generate M plausible imputed data sets

$$f\left(X^{miss}|X^{obs},\zeta_{\mathbf{1}}\right)$$
 ... $f\left(X^{miss}|X^{obs},\zeta_{M}\right)$



- 2 Fit the analysis model on each imputed data set: $\hat{\psi}_m, \widehat{\mathrm{Var}}\left(\hat{\psi}_m\right)$
- 3 Combine the results using Rubin's rules

$$\mathbf{1} \hat{\boldsymbol{\psi}} = \frac{1}{M} \sum_{m=1}^{M} \hat{\boldsymbol{\psi}}_{m}$$

2
$$T = \frac{1}{M} \sum_{m=1}^{M} \widehat{\text{Var}} \left(\hat{\psi}_m \right) + \frac{1}{M-1} \sum_{m=1}^{M} \left(\hat{\psi}_m - \hat{\psi} \right)^2$$

Challenges in clustering

MI is not tailored for cluster analysis

- How to impute the incomplete data set?
- How to assess a "variability" accounting for missing values?
- How to "average" partitions?

Some works on the "averaging" step

- by stacking (Plaehn, 2019)
- by using consensus clustering methods (Faucheux et al., 2020; Bruckers et al., 2017; Basagana et al., 2013; Aschenbruck et al., 2022)

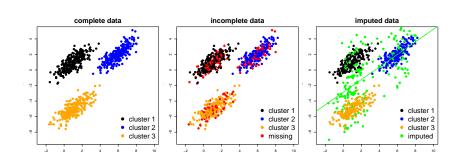
Aim: highlighting how imputation, analysis and pooling steps should be carried out

Introduction

Outline

- Introduction
- 2 MI for clustering Imputation Analysis Pooling
- 3 Simulation study Simulated data Real data
- 4 Conclusion

Imputation model for clustering: the issue



JM-DP (Kim et al., 2014)

Joint Modeling based on Dirichlet Process mixture of products of multivariate normal distributions

Based on a Bayesian formulation

$$egin{aligned} \mu_k | \Sigma_k &\sim \mathcal{N}\left(\mu_0, h^{-1}\Sigma_k
ight) \quad \Sigma_k &\sim \mathcal{W}^{-1}\left(df, G
ight) \ & ext{with } diag(G) = (g_1, ..., g_p) \ g_j &\sim \mathcal{G}\left(a_0, b_0
ight) \ &\pi_k = v_k \prod_{\ell < k} \left(1 - v_\ell
ight) \end{aligned}$$

- parameters: $\zeta = (\pi, \mu, \Sigma)$
- hyperparameters: h, μ_0 , df, a_0 , b_0 , a_{α} , b_{α}

 $(\zeta_m)_{1 \leq m \leq M}$ is generated using a Data-Augmentation algorithm

Introduction

Properties

JM-DP

- accounts for the heterogeneity
- accounts for the heteroscedasticity
- the number of clusters is only bounded

Modeling assumptions

based on the normality assumption

Available in the **DPImputeCont** (Kim, 2020) and **clusterMI** (Audigier, 2024) R packages

Fully conditional specification

Instead of specifying one joint distribution $f(X;\zeta)$, a conditional distribution is specified for each (incomplete) variable $f(X_j|X_{-j};\zeta_j)$

Ex:
$$f(X_j|X_{-j};\zeta_j) = \mathcal{N}(X_{-j}\beta,\sigma^2)$$
 $\zeta_j = (\beta,\sigma)$

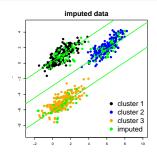
To impute the *m*th data set

- initialize \mathbf{x}_{i}^{miss} for all i
- for j in 1 ... p
 - a generate ζ_i based on observed individuals on X_i
 - b impute X_i^{miss} according to $f(X_j|X_{-j};\zeta_i)$
- repeat until convergence

Introduction

FCS-homo (Audigier et al., 2021)

Addressing the issue by using regression models including the class variable W as explanatory variable



FCS-homo

Simulation study

• generating X_i^{miss} given W is performed using regression models including a intercept specific to each cluster

$$f(X_j|X_{-j}, W; \zeta_j) = \mathcal{N}(X_{-j}\beta + \mu_w, \sigma^2) \quad \zeta_j = (\beta, \sigma, \mu_w)$$

 \bullet generating W given X by linear discriminant analysis

$$\mathbb{P}(W = w | X; \zeta_W) \propto exp(\delta_{w,x}) \qquad \zeta_W = (\pi, \mu, \Sigma)$$

FCS-homo

- addresses the cluster structure
- assumes homoscedastic regression models
- required a pre-defined number of clusters

Can be easily modified

- to account for heteroscedasticity (van Buuren, 2011)
- to improve sparsity (Zahid and Heumann, 2019)
- to address outliers (Templ et al., 2011)
- to use semi-parametric models (Morris et al., 2014)
- •

Available in the R package clusterMI (Audigier, 2024)

Analysis

Aim: From each each imputed data set X_m , compute a partition Ψ_m as well as an associated instability measure V_m

- Ψ_m can be obtain by any clustering algorithm
- V_m assesses how the Voronoi tessellation varies with the train sample for any clustering algorithm

Following Fang and Wang (2012)

- generate C bootstrap pairs $\left(\mathbf{X}_c, \tilde{\mathbf{X}}_c\right)_{1 \leq c \leq C}$ from \mathbf{X}
- perform cluster analysis from $\left(\mathbf{X}_{c}, \tilde{\mathbf{X}}_{c}\right)_{1 \leq c \leq C}$ to obtain $\left(\Psi_{c}, \tilde{\Psi}_{c}\right)$
- classify individuals of **X** from Ψ_c and $\tilde{\Psi}_c$ to obtain $\left(\Psi_c',\tilde{\Psi}_c'\right)$
- assess the instability $V=rac{1}{C}\sum_{c=1}^Crac{\delta(\Psi_c',\tilde{\Psi'}_c)}{n^2}$

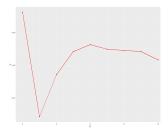


Figure: Instability (V) according to the number of clusters (K) 17/32

Partitions pooling

 Ψ_m the partition from (X^{obs}, X_m^{miss}) , which average $\widehat{\Psi}$ for $(\Psi_m)_{1 \leq m \leq M}$?

With complete data Jain (2017) extended to partitions

• the expected mean

$$\mathop{\mathsf{arg~min}}_{\Psi \in \mathcal{P}_{n,K}} \int_{\mathcal{P}_{n,K}} \delta^{\alpha}(\Psi^{\star},\Psi) d\pi(\Psi^{\star})$$

• the mean estimate $\underset{\Psi \in \mathcal{P}_{n,K}}{arg \ min} \sum_{i=1}^{n} \delta^{\alpha}(\Psi, \Psi_{j}) \qquad (1)$

with δ a dissimilarity, $\alpha \in \mathbb{N}$, $\mathcal{P}_{n,K}$ the set of with $(\Psi_j)_{1 \leq j \leq J}$ a set of observed partipartitions of n observations in K clusters tions

After MI

$$\widehat{\Psi} = \underset{\Psi \in \mathcal{P}_{n,K}}{\text{min}} \sum_{m=1}^{M} \delta^{\alpha}(\Psi, \Psi_m) \quad (\textit{median partition problem})$$

Properties

- Theoretically appealing, but solving (1) is highly challenging
- Iterative algorithms are required (Vega-Pons and Ruiz-Shulcloper, 2011)

Partitions pooling

 Ψ_m the partition from (X^{obs}, X_m^{miss}) , which average $\widehat{\Psi}$ for $(\Psi_m)_{1 \leq m \leq M}$?

With complete data Jain (2017) extended to partitions

the expected mean

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Properties

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Mirkin-based methods

 δ chosen as the number of disagreements between partitions

$$\delta\left(\Psi,\Psi'\right) = \sum_{(i,i')} \delta_{ii'} \qquad \qquad \delta_{ii'} = \begin{cases} 1 & \text{if } i \text{ and } i' \text{ belong to the same cluster} \\ & \text{in one partition and not in the other} \\ 0 & \textit{otherwise} \end{cases}$$

Two methods can be exhibited

- 1 BOK: the space of solutions is constrained to $(\Psi_m)_{1 \le m \le M}$ instead of $\mathcal{P}_{n,K}$
- 2 SAOM: the BOK solution is improved by using stochastic relabeling of individuals

Properties

 The error for the BOK solution does not exceed two times the error of the optimal partition (Filkov and Skiena, 2004)

$$\sum_{m=1}^{M} \delta(\Psi_{BOK}, \Psi_{m}) \leq 2 \sum_{m=1}^{M} \delta(\Psi_{opt}, \Psi_{m})$$

SAOM provides a better solution, but computationally intensive

NMF-based methods

Non negative matrix factorization is powerful method widely used for solving many optimization problems

Principle

ullet consider the Mirkin distance for δ

MI for clustering

 rewrite the optimization problem in terms of connectivity matrices $(U_m)_{1 < m < M}$ instead of partitions $(\Psi_m)_{1 < m < M}$

$$\underset{\Psi \in \mathcal{P}_{\kappa}^{K}}{\operatorname{argmin}} \sum_{m=1}^{M} \delta(\Psi, \Psi_{m}) \Longleftrightarrow \underset{\mathbf{U} \in \mathcal{U}}{\operatorname{argmin}} \parallel \bar{\mathbf{U}} - \mathbf{U} \parallel_{F}^{2}$$

with
$$\bar{\mathbf{U}} = \frac{1}{M} \sum_{m=1}^{M} \mathbf{U}_{m}$$

Properties

- can be solved using various algorithms (Lee and Seung, 2001; Li et al., 2007)
- monotone convergence
- no label switching problem, various choices for K_m are available

Instability after MI (Audigier and Niang, 2022)

Following Fang and Wang (2012), the within instability can be assessed by

$$\frac{1}{M} \sum_{m=1}^{M} V_{m}$$

while the **between instability** can be computed by averaging the proportions of disagreements

$$\frac{1}{M^2} \sum_{m=1}^{M} \sum_{m'=1}^{M} \delta\left(\mathbf{\Psi}_{m}, \mathbf{\Psi}_{m'}\right) / n^2$$

the total instability T is

$$T = \frac{1}{M} \sum_{m=1}^{M} \frac{\mathbf{V_m}}{\mathbf{V_m}} + \frac{1}{M^2} \sum_{m=1}^{M} \sum_{m'=1}^{M} \delta\left(\mathbf{\Psi_m}, \mathbf{\Psi_{m'}}\right) / n^2$$

Properties

Based on a simulation study

 pooling partitions using NMF-based methods is less time consuming and more accurate than Mirkin-based methods

- a larger value for M improves the partition accuracy ($M \approx 20$)
- T provides an accurate estimate for the number of clusters with missing values

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Simulation design: data generation

Complete data generation

Introduction

A base-case configuration: GMM with K=3 components

$$n_k = 250$$
 (for all k in $\{1, 2, 3\}$), $\Delta = 2$ $\rho = 0.3$

10 other configurations varying: the separability between clusters, the number of clusters, the cluster size, the balance between clusters sizes and the heteroscedasticity.

Missing data generation

• MCAR:
$$\mathbb{P}(r_{ii} = 0) = \tau$$
 $\forall i, j$

• MCAR:
$$\mathbb{P}(r_{ij} = 0) = \tau$$
 $\forall i, j$
• MAR: $\mathbb{P}(r_{ij} = 0) = \Phi(a_{\tau} + x_{i1})$ $\forall j \neq 1$

• $\tau \in \{10\%, 25\%, 40\%\}$

Conclusion

Introduction

For each incomplete data set (200 per configuration), 3 clustering methods are applied: k-means, fuzzy c-means, clustering by GMM

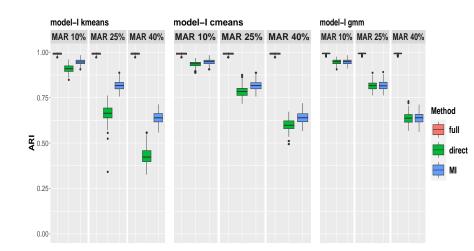
MI¹ is compared to competitive direct methods

- k-POD (Chi et al., 2016, The American Statistician) implemented in the kpodclustr R package
- FCM by optimal completion strategy (Hathaway and Bezdek, 2001, IEEE Transactions on Systems, Man, and Cybernetics, Part B (Cybernetics))
- Ignorable-GMM (Marbac et al., 2019, Journal of Classification) implemented in the VarSelLCM R package

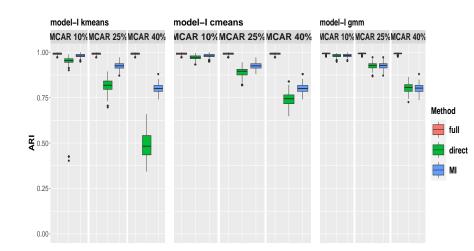
Criteria: Adjusted Rand Index

 $^{^{1}(}JM-DP, M = 20, pooling by NMF)$

Results: base-case, MAR



Results: base-case, MCAR



<u>'Su</u>mmary

Based on simulated data under mixture model distribution

- MI outperforms direct methods for kmeans and fuzzy c means
- MI and direct methods provide similar ARI for GMM
- Differences between MI and direct method highlighted for kmeans with more separated clusters
- Similar results by modifying the number of clusters, the cluster size, the balance between clusters sizes and the heteroscedasticity

Real data sets

Data

	Varia bles						Size of cluster	
	п	p	Туре	Number for which Shapiro rejects normality	K	Silhouette Index	(min)	(max)
wine	178	13	Real	7	3	0.57	48	71
ovarian	216	100	Real	64	2	0.50	95	121
iris	150	4	Real	1	3	0.52	50	50
glass	214	9	Real	9	2	0.56	51	163
breast cancer	699	9	Discrete	9	2	0.59	241	458

- Gaussian assumption seems not observed
- p large
- n_k small compared to p
- partitions not obvious

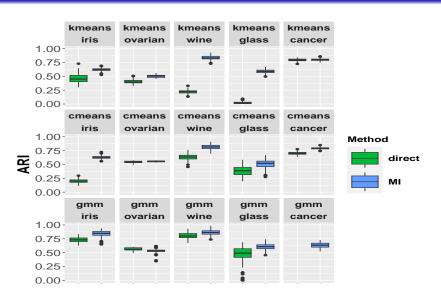
Simulation design

Data sets generation

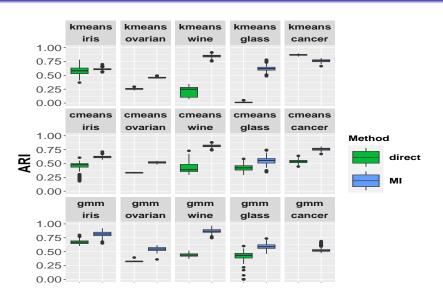
- 25% missing values (MCAR or a MAR mechanism)
- 200 missing data patterns per mechanism

Data sets analysis

- missing values are addressed by MI (FCS-homo, M = 20)
- cluster analysis by k-means, fuzzy c-means or GMM
- pooling using NMF



Real data, MAR



Take-home message

MI is a competitive method for addressing missing values in clustering

- for model-based or distance-based methods
- good performances on real data

In practice

- A suitable imputation model is required
- A large value for M is recommended
- The number of clusters can be easily estimated
- Mixed data can be handled
- Available in the clusterMI R package

Some perspectives

- Investigating other imputation models dedicated to large data sets
- Developing indices for clustering with missing values

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