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1 Investigation Into Debonding of Single Polypropylene Fiber Pullout

2 in Concrete Using X-Ray Microtomography and Mechanically

3

Regularized Digital Volume Correlation

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17 Abstract

18 To investigate the debonding process, an in-situ pullout experiment on an indented single 19 polypropylene fiber was conducted using X-ray microtomography. This study utilized mechanically 20 regularized global digital volume correlation (Reg-G-DVC) to measure the deformation fields of 21 the fiber, matrix, and interfaces during interfacial debonding. Reg-G-DVC mitigates the impact of low contrast on measurement uncertainties, ensures the convergence of DVC calculations, and 22 enables the element size to be reduced to improve the spatial resolution. The displacement jumps of 23 24 the shared nodes between the fiber and the matrix were used to quantify interfacial debonding. The 25 profiles of the normal and tangential components of the displacement jumps exhibited periodic 26 features corresponding to the geometry of the indented fiber as it was pulled out. Additionally, the 27 force-displacement curves displayed multi-peak fluctuations corresponding to the fiber geometry, 28 thereby indicating that the periodic indentation of the fiber enhanced friction and the cohesive force 29 between the fiber and the matrix during the pullout process. The displacement jumps along the fiber 30 was maximum at the embedded initiation and decreased along the fiber toward the embedded end.

31	The aforementioned research demonstrated the advantages of utilizing Reg-G-DVC in measuring
32	displacement fields during interfacial debonding, which provides deformation data for identifying
33	and validating interface models.
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36	Keywords: Fiber; Debonding; DVC measurements; CT analysis.

38 1 Introduction

39 Fiber-reinforced concrete (FRC) exhibits high toughness, ductility, impact resistance, and 40 fatigue resistance. In recent years, it has been widely employed in various engineering fields 41 including residential construction [1,2], bridge structures [3,4], pavements [5,6], and tunnel 42 linings [7-10] to cite a few. In FRCs, the fibers are interconnected with the cement/mortar matrix 43 through interfaces. When the material undergoes tensile loading and the matrix begins to crack, the 44 load is transmitted through the interface to the fibers. The fibers share the tensile load, thus 45 preventing further cracking of the matrix and enhancing the tensile strength of the material. In this 46 process, the matrix strength determines that of the material, whereas the mechanical characteristics 47 of the interface affect the reinforcement, toughening, and crack resistance of the fibers in the matrix. 48 Research indicates that the stress states between the fibers and the matrix in single-fiber pullout tests 49 are similar to those between bridging fibers and the cracking matrix during the cracking process of 50 FRCs [11]. Additionally, the shear stress-slip relationship observed experimentally is considered an 51 intrinsic property of the interface. Hence, scholars have investigated the mechanical bonding 52 characteristics of interfaces via fiber pullout experiments and numerical simulations [12-14]. They 53 have utilized parameters such as the pullout peak load, bonding strength, and pullout work to 54 characterize the bonding performance. These studies investigated the effects of factors such as fiber 55 type [15,16], surface features [17], embedment angle [18,19], matrix strength [19], and amount of 56 matrix constituents [20] on the interface bonding performance to infer interface damage and failure 57 conditions.

58 Fibers typically used in FRCs can be classified into three main categories: i) metal fibers (i.e., primarily steel fibers); ii) inorganic material fibers (i.e., generally glass or basalt fibers); and 59 iii) organic synthetic fibers (e.g., polypropylene, polyamide, polyester, polyacrylonitrile, and 60 61 polyvinyl alcohol fibers). Among them, the steel fibers have the widest application spectrum. 62 However, their high weight and cost, along with the potential issue of tire punctures when fibers protrude from surfaces, as reported in airports and highway pavements [21-23], have prompted the 63 64 search for alternative reinforcement materials. Synthetic fibers, which is a novel type of 65 reinforcement material, have rapidly developed and are utilized in concrete owing to their low cost, high strength, good elasticity, wear resistance, and corrosion resistance [24-26]. Studying the 66

67 interface bonding and slip mechanisms of synthetic fiber concrete may provide a theoretical basis68 for the design of synthetic fiber concrete.

69 Most studies regarding synthetic FRCs have primarily focused on the macroscopic mechanical 70 characteristics of fiber pullout [27-29]. In these studies, the pullout process was observed on a two-71 dimensional scale and the interface bonding and sliding processes between the matrix and fibers 72 were inferred [30]. However, in reality, interface bonding and sliding are complex three-dimensional 73 phenomena, and analyzing them solely from a two-dimensional perspective cannot accurately 74 capture the mechanical performance of interfaces. Therefore, a method to measure the internal 75 deformation of a material on a three-dimensional scale must be identified and the interface bonding 76 and sliding processes analyzed. Optical measurement methods such as photoelasticity [31], digital 77 image correlation (DIC) [32-34], and digital gradient sensing [35] offer advantages such as full-78 field coverage, noncontact nature, and visual interpretation, thus rendering them useful for assessing 79 stress or strain fields at interfaces and in matrices. However, methods such as photoelasticity and 80 digital gradient sensing require materials with photoelastic properties, and DIC is primarily used for 81 surface measurements. Although these methods have revealed some key aspects of the force 82 characteristics during pullout tests, they do not comprehensively capture three-dimensional features 83 at interfaces between fibers and cementitious matrices.

84 X-ray microtomography is a nondestructive and noncontact testing technique that has been 85 widely applied to observe the internal characteristics of concrete and to establish detailed numerical 86 models [36-38]. Derived from two-dimensional DIC, digital volume correlation (DVC) [39,40] 87 combined with X-ray microtomography is applied to investigating three-dimensional deformation 88 fields in specimens. Yang et al. [41], Mao et al. [42] and Chateau et al. [43] employed DVC to 89 analyze local deformations before crack initiation in concrete specimens under uniaxial compression, 90 which provided insights into early stage microcracks, which are difficult to distinguish directly via 91 microtomography imaging. Stamati et al. [44] used DVC to measure internal deformation fields and 92 their evolution in concrete specimens subjected to uniaxial and triaxial compression. Flansbjer et 93 al. [45] combined microtomography with DVC to capture the deformation field during pullout of 94 hooked-end steel fibers from a cementitious matrix, and studied the load transfer mechanism. In 95 these studies, the DVC method involved subsets whose length typically comprised tens of voxels, 96 which was much larger than the scale used in interface studies. The spatial resolution of DVC limits

97 its ability to precisely measure the deformation in interface areas. Hild et al. [46] and Leclerc et al. 98 [47] introduced mechanically regularized global DVC (Reg-G-DVC) based on the equilibrium gap. 99 This method not only ensures lower measurement uncertainties, but also enhances the spatial resolution of displacement field measurements, possibly to the voxel level. Tsitova et al. [48] 100 101 considered the heterogeneity of the material and used this method to measure the strain field of 102 mortar specimens under three-point bending experiments, and quantified three damage mechanisms. 103 Riccardi et al. [49] used this method to analyze the debonding of fiber-reinforced polymer anchors 104 in concrete during bending tests and described how the material degradation developed in the anchor 105 region. Jänicke et al. [50] employed Reg-G-DVC to quantify debonding of fibers embedded in two 106 brittle matrices, measured the relative motion at the interface, and analyzed the load-transfer 107 mechanism between the fiber and matrix.

108 Due to the addition of mechanical regularization, Reg-G-DVC allows for the use of finer mesh 109 sizes, thereby enhancing the spatial resolution of kinematic measurements, which improves the 110 measurements of displacements at interfaces between fibers and matrices. In this paper, the 111 displacement field and debonding process of the interface between a polypropylene fiber and a 112 cementitious matrix were studied by using Reg-G-DVC combined with an in-situ pullout test 113 scanned via microtomography. Section 2 introduces the experimental setup and procedures. Section 114 3 provides an analysis of the equivalent speckle size of the imaged sample as well as the 115 measurement uncertainty, and determines the DVC calculation parameters. Section 4 discusses the 116 measurement results, analyzes the displacement and gray level residual fields for different load 117 levels, as well as the debonding state of the interface between the fiber and the matrix.

118 **2 Materials and Methods**

119 **2.1 Specimens and Experimental Setup**

The matrix material employed for the investigated specimens was ordinary Portland cement (P.O.42.5, Datong, Shanxi, China). Fine aggregates were used (Zone II sand) with a fineness modulus of 2.81. The cement–mortar mix proportion was cement : water : sand = 1:0.45:1. The fiber utilized herein was tunnel lining spray concrete-specific, of indentation-type, and high-strength. It was a modified polypropylene coarse fiber produced by Ningbo Shike New Materials Technology 125 Co., Ltd. (Fig. 1(a)). It had a length of 40 mm, a cross-sectional width of 1 mm, and a thickness of 126 0.66 mm. The fiber surface featured diamond-shaped indentations with a spacing of 3 mm, and a 127 depth of 0.2 mm. The maximum width of the fiber section was 1.18 mm at indentation locations. Its 128 structure and images magnified $40 \times$ (using an optical microscope) are shown in Fig. 1(b). The 129 indentation increased the cohesive strength and friction force between the fiber and the matrix when 130 the fiber was pulled out.



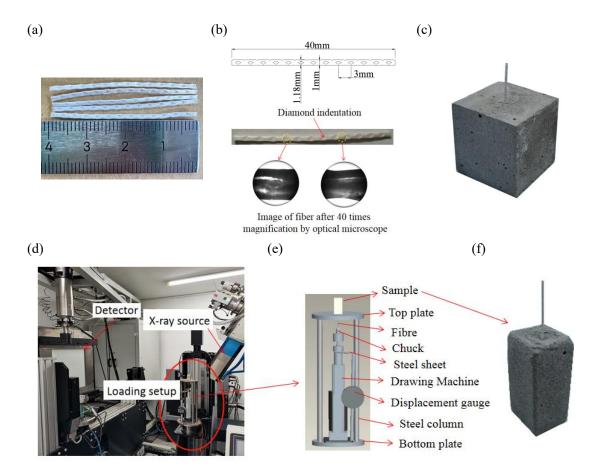


Fig. 1 Specimens and Experimental setup. (a) Polypropylene fibers. (b) Structural diagram and
magnified sections of a Polypropylene fiber. (c) Specimens for fiber pullout experiments (40 mm
× 40 mm × 40 mm). (d) CT System for in-situ fiber pullout. (e) Schematic illustration of pullout
experiments. (f) Specimens for in-situ fiber pullout experiments (20 mm × 20 mm × 40 mm).

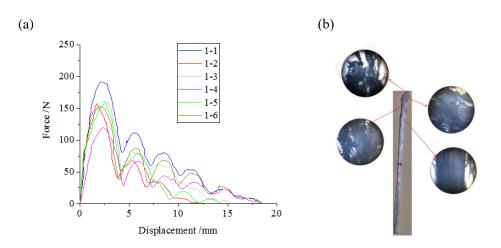
The mechanical parameters of the matrix were obtained via uniaxial compression tests. The Young's modulus was equal to 29 GPa, Poisson's ratio was 0.16, and the compressive strength was QPMPa. The mechanical parameters of the fiber were provided by the manufacturer (i.e., Young's modulus: 7.2 GPa, Poisson's ratio: 0.35, failure strength: 715 MPa, elongation at failure: 14%). 140 Cubic mortar specimens of size 40 mm \times 40 mm \times 40 mm were prepared for fiber pullout 141 experiments. A polypropylene fiber was embedded at the center of each specimen down to a depth 142 of 15 mm (Fig. 1(c)).

143 The microtomography system used for the experiment was equipped with an YXLON 225 kV 144 microfocus X-ray source and an XRD 1611 AP3 flat-panel detector with a definition of 145 2048 × 2048 pixels. A custom-designed experimental setup was developed for in-situ 146 microtomography scanning of fiber pullout. This setup comprised a main support frame, driving 147 motor (maximum pulling force = 2000 N, and loading speed = 0.28 mm/s), load sensor (range = 0to 3 kN, and standard uncertainty = 9 N), and displacement sensor (range = 0 to 50 mm, and standard 148 149 uncertainty = $10 \,\mu\text{m}$). During the experiment, the setup was fixed to the turntable of the 150 microtomography system. Fig. 1(d) shows the setup for in-situ single-fiber pullout test, and Fig. 1(e) 151 schematically illustrates the pullout setup. To minimize X-ray attenuation, the samples were further 152 prepared via wire cutting into 20 mm \times 20 mm \times 40 mm cubes, which were more suitable for in-153 situ microtomography scanning (Fig. 1(f)).

154

2.2 Single-Fiber Pullout Experiment

155 Pullout experiments were conducted on six specimens, and the corresponding force-156 displacement curves are shown in Fig. 2(a). The maximum, minimum, and average pullout peak 157 loads were 190, 120, and 153 N, respectively. The force-displacement curves exhibited multipeak 158 characteristics, which are related to the geometry of the indented fiber (Fig. 1). The larger cross-159 sectional width at the indentation location increases mechanical interlocking and friction forces 160 between the fiber and the matrix during pullout, thus resulting in periodic increases and decreases 161 in the reported forces. The distance between the peaks and corrugation spacing is approximately 162 3 mm, whereas the load at the peak gradually decreases as the pullout length increases. The 163 magnified morphology of the fiber after pullout observed under an optical microscope at $40 \times$ magnification is shown in Fig. 2(b). It revealed scratches on the fiber surface. The embedded 164 165 initiation of the fiber indicated less damage, whereas the embedded end showed severe damage with 166 burrs appearing on the surface, similar to those observed in post-abrasion.



168 Fig. 2. Polypropylene fiber pullout results. (a) Force–displacement curves of specimens.

169 (b) Morphology of a fiber after its pullout.

170 Based on the afore-reported pullout curves, an in-situ pullout experiment was conducted. The 171 force-displacement curve is shown in Fig. 3(a). After the load application ceased, force relaxations 172 occurred and the scanning was conducted once stability was achieved. The green "x" positions on the curve indicate dwell points during loading, whereas the red circles depict the scanning points. 173 The latter ones correspond to forces equal to 0 N (unloaded), 56 N (dwell force of 126 N), 86 N 174 (dwell force of 161 N), 46 N after the peak load, and 0 N after the peak load. The reconstructed 175 volume size was $1200 \times 1200 \times 1380$ voxels, and each voxel corresponded to a physical size of 19 176 177 $\mu m \times 19 \,\mu m \times 19 \,\mu m$. The experiment was conducted at a beam voltage of 130 kV and a current 178 of 0.4 mA for 20 min. 1,200 projections were acquired over a 360° revolution. The images were 179 encoded over an 8-bit grayscale.

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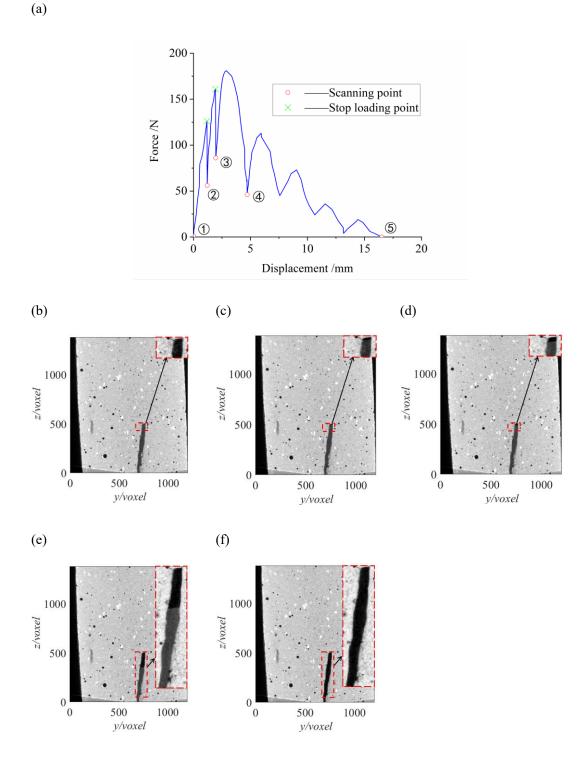


Fig. 3 Force-displacement curve for the in-situ pullout test and middle sections of steps 1 to 5.
(a) Force-displacement curve. (b) Step 1 (0N), (c) step 2 (126 N), (d) step 3 (161N), (e) step 4
(after peak load, 46 N) and (f) step 5 (after peak load, 0 N) sections.

192 Fig. 3(b) shows a middle section including the fiber with no applied load, and those with a

193 partially enlarged red box area of the fiber end at each loading stage are shown in Fig. 3(c,f), 194 respectively. With the aid of Fiji software [51], it was evaluated that approximately 3 voxels (57 195 μm) of the fiber were pulled out from the embedded end when the force was equal to 126 N 196 (Fig. 3(c)). When the pullout force reached 161 N (Fig. 3(d)), approximately 13 voxels (247 μm) 197 of the fiber were removed from the embedded end. Partial debonding of the fiber is observed in this 198 region, although the pullout load had not yet reached its peak level. The load was increased until it 199 reached its ultimate value. Then, at a load of 46 N after the peak, approximately 140 voxels (2660 200 μm) of the fiber were pulled out (Fig. 3(e)), and in the final stage, the fiber was completely pulled 201 out (Fig. 3(f)).

Throughout the pullout process, after the peak load was reached, the pullout curve exhibited the same characteristics as the reference single fiber pullout experiments (i.e., multipeak features associated with indentation spacing). Additionally, Fig. 3 shows that the fiber was orientated at an angle of ca. 7.5° in this section plane along the z-axis. This inclination angle may affect the pullout behavior.

207 Owing to significant artifacts near the lower portion of the specimen close to the supporting 208 top platen, and the limited effect of the upper part distant from the fiber extraction end, a VOI 209 comprising 421 layers of images that spanned 80 pixels upward from the fiber-embedded initiation 210 region to 500 pixels into the interior of the cement matrix. To avoid too heavy computations, the 211 region depicted in Fig. 4(a) was selected. It comprised $130 \times 130 \times 421$ voxels and served as the 212 VOI. Fig.4(b) and (c) respectively show the yOz section at x = 55 voxels, and xOz section at y = 50voxels. The enlarged image of the red box area section (x=55 voxels) and its adjacent 8-layer 213 214 sections (x = 51 - 54 voxels, x = 56 - 59 voxels) are shown in Fig. 4(d). The corresponding sections 215 in this area under a pull-out load of 126 N are displayed in Fig. 4(e). Based on a comparison between 216 Figs. 4(d) and (e), when the fiber was pulled out, pores and cracks in the nearby matrix closed, 217 which was caused by the inclined embedding of the fiber, thus resulting in lateral stresses on the 218 matrix.

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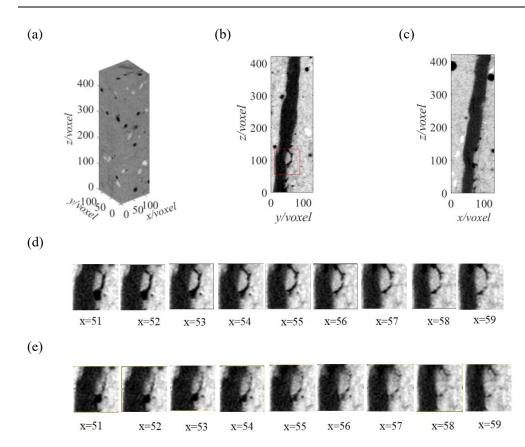


Fig. 4 Effect of fiber pullout on the matrix. (a) DVC calculation region (VOI). (b) *yOz* sections at

224 x = 55 voxels for the unloaded state. (c) Corresponding *xOz* sections at y = 50 voxels.

(d) Magnified views of sections when the applied force is equal to 0 N. (e) Corresponding sectionswhen the applied load was equal to 126 N.

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228 2.3 Regularized Global DVC

In this study, Reg-G-DVC was employed to measure displacement fields. The underlying principle of this method is as follows. The reference and deformed volumes correspond to f and g, respectively. Under the assumption of grayscale conservation, the displacement field $\mathbf{u}(\mathbf{x})$ is determined by minimizing the sum of squared differences

$$\min_{\{\mathbf{u}\}} \Phi_c^2 = \sum_{\text{VOI}} \left[f(\mathbf{x}) - g(\mathbf{x} + \mathbf{u}(\mathbf{x})) \right]^2$$
(1)

where volume of interest (VOI) represents the selected region within the reference volume. Similar to the discretization of finite-element models, the displacement of any point within an element is expressed in terms of nodal displacements u_i , which are gathered in the column vector {**u**}, and corresponding shape functions $N_i(\mathbf{x})$

$$\mathbf{u}(\mathbf{x}) = \sum_{i} u_i \mathbf{N}_i(\mathbf{x}) \tag{2}$$

237 The gray residual φ_c is defined as the absolute difference in gray levels between the reference

volume and the deformed volume corrected by the measured displacement field $\mathbf{u}(\mathbf{x})$

$$\varphi_{c}\left(\mathbf{x}\right) = \left|\mathbf{f}\left(\mathbf{x}\right) - g\left(\mathbf{x} + \mathbf{u}\left(\mathbf{x}\right)\right)\right|$$
(3)

and the dimensionless correlation residual ρ_{dvc} is defined as

240
$$\rho_{dvc} = \frac{1}{(\max(f(\mathbf{x})) - \min(f(\mathbf{x})))} \sqrt{\frac{1}{\text{VOI}} \sum (f(\mathbf{x}) - g[\mathbf{x} + \mathbf{u}(\mathbf{x})])^2}$$
(4)

Using a Gauss-Newton scheme, the minimization problem expressed in Equation (1) is transformed into an iterative solution to linear systems of equations

$$[\mathbf{M}]\{\mathbf{d}\mathbf{u}\}-\{\mathbf{b}\}^{i}=\{\mathbf{0}\}$$
(5)

243 with

$$b_m^i = \int_{\text{VOI}} \left(\nabla f(\mathbf{x}) \cdot \mathbf{N}_m(\mathbf{x}) \right) (f(\mathbf{x}) - g(\mathbf{x} + \mathbf{u}^i(\mathbf{x}))) d\mathbf{x}$$
(6)

$$M_{mn} = \int_{\text{VOI}} (\nabla f(\mathbf{x}) \cdot \mathbf{N}_m(\mathbf{x})) (\nabla f(\mathbf{x}) \cdot \mathbf{N}_n(\mathbf{x})) d\mathbf{x}$$
(7)

$$\mathbf{d}\mathbf{u} = \mathbf{u}^{i+1} - \mathbf{u}^i \tag{8}$$

where $[\mathbf{M}]$ is the DVC Hessian matrix, $d\mathbf{u}$ the iterative displacement increment.

A regularization approach can be used to address the ill-posed problem of DVC by introducing a penalty function. According to linear elasticity, the equilibrium equations in a finite-element sense read

$$[\mathbf{K}]\{\tilde{\mathbf{u}}\} = \{\mathbf{f}\} \tag{9}$$

where **[K]** is the global stiffness matrix, $\{\tilde{\mathbf{u}}\}\$ the mechanically admissible nodal displacement vector, and $\{\mathbf{f}\}\$ the nodal force vector. By substituting the measured values $\{\mathbf{u}\}\$ into the previous equation, the equilibrium residual, which is also known as the equilibrium gap, is expressed as

$$\{\mathbf{f}_r\} = [\mathbf{K}]\{\mathbf{u}\} - \{\mathbf{f}\}$$
(10)

251 Without considering body forces, the internal nodes experience zero externally applied forces.

252 Therefore, the displacement $\{u\}$ should minimize the L2 norm of the mechanical residual forces

$$\Phi_m^2 = \left\{ \mathbf{u} \right\}^{\mathrm{T}} \left[\mathbf{K} \right]^{\mathrm{T}} \left[\mathbf{K} \right] \left\{ \mathbf{u} \right\}$$
(11)

253 Introducing Equation (11) as a penalty term into Equation (1), the nodal displacement vector $\{\mathbf{u}\}$

254 minimizes the weighted sum of the correlation residual Φ_c^2 and force residual Φ_m^2 . To make the 255 two cost functions dimensionless, a plane waveform is considered

$$\tilde{\Phi}_m^2 = \frac{\Phi_m^2}{\{\mathbf{v}\}^{\mathrm{T}} [\mathbf{K}]^{\mathrm{T}} [\mathbf{K}] \{\mathbf{v}\}}, \quad \tilde{\Phi}_c^2 = \frac{\Phi_c^2}{\{\mathbf{v}\}^{\mathrm{T}} [\mathbf{M}] \{\mathbf{v}\}}, \quad (12)$$

where $\mathbf{v} = \mathbf{v}_0 e^{i\mathbf{k}\cdot\mathbf{x}}$ represents the displacement field of a plane waveform, \mathbf{v}_0 the displacement amplitude vector, and \mathbf{k} the wavevector. The total cost function Φ_t is written as [47]

$$\Phi_t^2 = \tilde{\Phi}_c^2 + \omega \tilde{\Phi}_m^2 \tag{13}$$

$$\omega = \left(2|\mathbf{k}|\pi\ell_{reg}\right)^4 \tag{14}$$

where ω denotes the regularization weight, and ℓ_{reg} the regularization length. Introducing the equilibrium residual as a penalty provides a significant smoothing effect for high-frequency oscillating fields that are not mechanically admissible. Equation (13) is minimized using a Gauss-Newton scheme and the nodal displacements are measured.

3 Uncertainty Analysis and Determination of Calculation Parameters

3.1 Analysis of Equivalent Speckle Size in FRC

When measuring deformations using DVC, the microstructure of both fiber and matrix in the FRC serves as carrier of kinematic information, which directly affects the reliability of displacement calculations. The regions corresponding to the matrix and the fiber were selected separately, as shown in Fig. 5(a) and (b). The image shows that the gray level distribution was confined within relatively narrow ranges, thus indicating the absence of ideal contrast. The effect of the fiber pullout process on the upper region of the specimen was minimal, and the deformation in this region between the two scans was negligible. Consequently, the correlation residual φ_c in Equation (3) of

- this region can be regarded as due acquisition noise and reconstruction artifacts (Fig. 5(c)).
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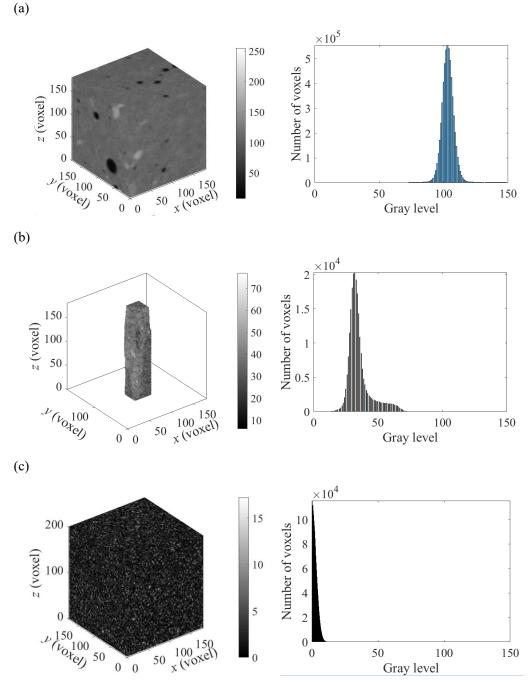


Fig. 5 Gray level images and histograms of three regions of interest. (a) Matrix, (b) Fiber,(c) Noise.

According to the autocorrelation calculation, the equivalent speckle diameters of the fiber, matrix, and noise are 8.2, 6.6, and 2.6 voxels, respectively. The equivalent speckle sizes of both the fiber and the matrix in the reference image exceeded those of noise. This observation indicates that the contrast in the image was predominantly affected by material heterogeneities instead of noise, thereby ensuring the effectiveness of DVC measurements.

287 **3.2 Uncertainty Analysis**

Considering the effect of noise during the scanning process and reconstruction artifacts, the 288 first scan (with a pulling force of 0 N) and the second scan (with a pulling force of 126 N) of the 289 290 matrix area, as shown in Fig. 5(a), were used as the reference and deformed images, respectively, to 291 evaluate the measurement uncertainty of the cementitious matrix. For the fiber, because two images 292 of the fiber in the unloaded state were not acquired, the gray level residual between the two scans 293 of the matrix in the unloaded state was regarded as noise. This noise was added to the reference 294 image to generate a 'deformed image,' and the measurement uncertainty was assessed for these two 295 volumes.

296 Using Reg-G-DVC, the element size was set to 5 voxels, and regularization lengths of 80, 40, 297 and 20 voxels were selected. Fig. 6(a) and (b) show the variations in standard displacement 298 uncertainties for the matrix along the x-, y-, and z-directions, and maximum principal strain 299 uncertainties in a double-logarithmic plot when increasing the regularization length. The scattered 300 points represent the measured values, and the dashed lines depict the fitted curve (with a power law). 301 According to theoretical analyses [47], the value of the exponent b corresponding to displacement 302 uncertainties is -1.5, and that corresponding to maximum the standard principal strain uncertainty 303 is -2.5. It is found from Fig. 6(a) and (b) that the exponents approach the predicted values. As the 304 regularization length was increased, both standard uncertainties decreased (faster for the strains wrt. 305 the displacements). The uncertainty levels in the three directions were generally similar.

Fig. 6(c) and (d) show the variations in standard displacement and maximum principal strain uncertainties of the fiber in a double-logarithmic coordinate system when increasing the regularization length. The general trends are similar to those in the matrix.

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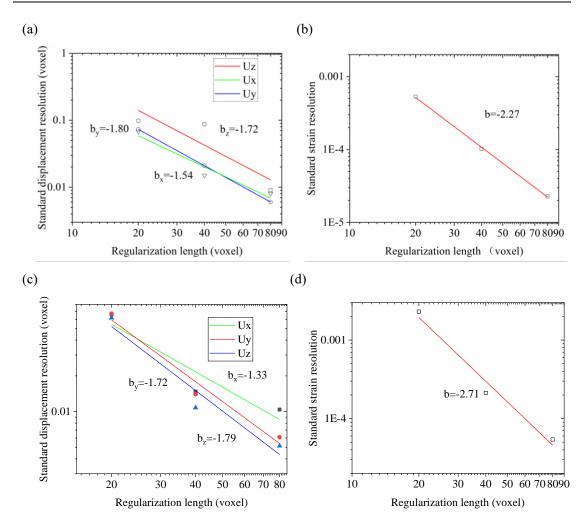


Fig. 6 Uncertainties vs. regularization length. The colored lines depict power law interpolations.
(a) Standard displacement uncertainties in the matrix, (b) Corresponding maximum principal
strain uncertainty. (c) Standard displacement uncertainties in the fiber, (d) Corresponding
maximum principal strain uncertainty.

321 The numerical values of the standard displacement uncertainties σ of fiber and matrix 322 obtained using Reg–G-DVC were equal to 0.01 voxels and 0.05 voxels, respectively, when the 323 regularization length was set to 40 voxels.

324 **3.3 DVC Parameters**

The VOI is shown in Fig. 4(a). To obtain high-spatial-resolution deformation fields for analyzing the kinematics at the interface between the fiber and the cementitious matrix, a small element size was selected. Reducing the element size may increase the measurement uncertainty, even result in divergence in DVC calculations. In the present case, when the mesh size was set to 329 $5 \times 5 \times 5$ voxels, the calculations did not converge with classical (i.e., unregularized) DVC. 330 However, "regularization relaxation" steps were employed in the Reg-G-DVC calculations to ensure 331 that the initial displacements at each iteration were within reasonable ranges. It consisted in first 332 enforcing the largest regularization length. Once DVC had converged, the next DVC step was run 333 with a lower regularization as well as initialized with the previous solution, and so on. Reg-G-DVC 334 calculations were performed separately for the selected cementitious matrix and fiber regions of 335 interest determined during the uncertainty analysis to select an appropriate regularization length. 336 The microtomography images obtained at a load of 0 N were used as the reference volume, whereas 337 those acquired at force levels of 126 and 161 N were used as deformed volumes. The mechanical residual $\rho_{mec} = \sqrt{\Phi_m^2}$ and the correlation residual ρ_{dvc} in the matrix and the fiber under different 338 339 loads and regularization lengths were computed (Fig. 7).

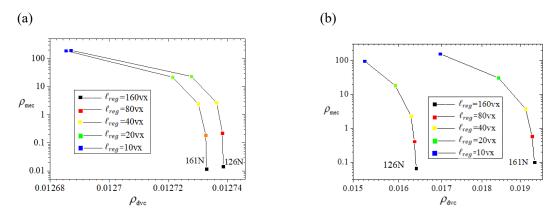


Fig. 7 Mechanical residual ρ_{mec} and correlation residual ρ_{dvc} under different loads and regularization lengths. (a) Matrix. (b) Fiber.

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343 As shown in Fig. 7(a) and (b), the mechanical residual decreased significantly as the 344 regularization length ℓ_{reg} increased, whereas the gray level residual changed less, which means 345 that the hypothesis of elasticity was satisfied in both constituents. For the matrix and fiber, when 346 ℓ_{reg} decreased from 160 to 10 voxels, the increment of the gray level residual was only 10⁻⁵ and 347 10⁻³. Therefore, a large regularization length ℓ_{reg} can be selected for the DVC calculations. 348 However, the fiber cross-sectional thickness was only 0.66mm (approximately 35 voxels), and 349 extremely high values may cause the fiber deformation to be overly smooth. In the following, 350 $\ell_{reg} = 40$ voxels was chosen.

4 DVC Results and Debonding Analysis

Reg-G-DVC was utilized to measure the internal displacement and strain fields of the tested specimen during various stages of fiber pullout. The kinematic fields are first discussed and followed by a quantitative analysis of debonding. The calculation region is shown in Fig. 5(a).

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4.1 Deformation Field Analysis

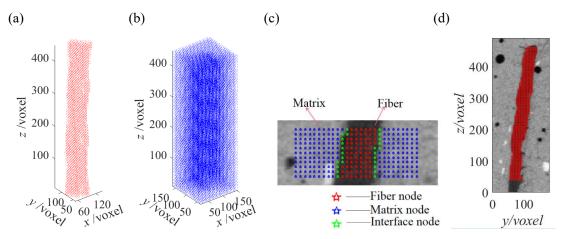
To analyze debonding at the fiber-matrix interface during the pullout process, a separate calculation strategy was adopted in which DVC analyses were performed independently for the fiber and the matrix. The microtomography images obtained at a loading of 0 N were used as the reference volume, whereas those acquired at loading levels of 126 and 161 N were used as the deformed volumes. The specific steps were as follows:

361 (1) Image Segmentation. The reference microtomography image corresponding to the 362 reference volume was segmented into fiber and matrix regions using Fiji software [51]. The image contrast was enhanced using image enhancement tools, an appropriate threshold was selected for 363 364 binarization, and morphological post-processing was applied to the segmented image. A series of 365 erosions followed by dilations was used as opening operations to smoothen the fiber boundary voxels. After segmentation, the gray levels of the fiber region were set to 255, and the matrix region 366 367 was set to 0. The binarized image served as template for the subsequent region-based DVC 368 calculation.

369 (2) *Regional DVC Calculations.* The regions containing both the fiber and matrix were 370 discretized into elements with a size of $5 \times 5 \times 5$ voxels. The regularization lengths were set to 80 371 and 40 voxels, respectively. The templates obtained from image segmentation of Step (1) were used 372 to determine the corresponding elements and nodes for the fiber/matrix regions. The fiber and matrix 373 comprised 4,123 and 52,661 elements, respectively. Separate DVC calculations were conducted for 374 these two regions.

375 (3) *Debonding Analysis*. Based on the results obtained from the region-based DVC calculations
of Step (2), the displacement jumps at the fiber-matrix interface (split) nodes i.e., their relative
displacements, were determined. This analysis allowed the debonding process at the interface to be
quantified.

379 Schematic diagrams of the fiber and matrix elements are shown in Fig. 8(a) and (b), 380 respectively. The split nodes at the fiber-matrix interface are displayed in Fig. 8(c), where the blue 381 and red markers represent nodes in the matrix and fiber region, respectively, whereas the green 382 markers depict the split nodes at the interface. Interfacial debonding is examined by analyzing the 383 relative motions of the split nodes.



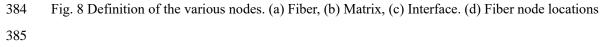
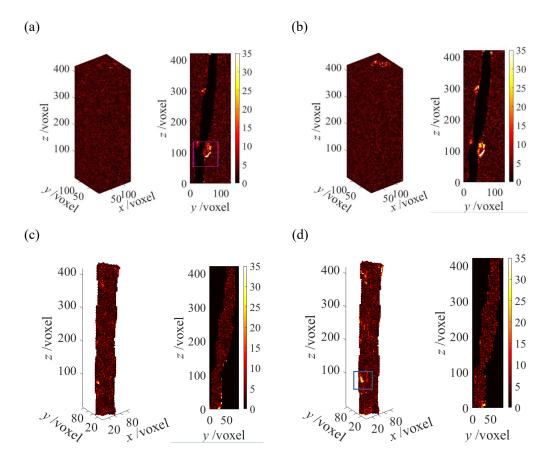


Fig. 8(d) shows the nodes within the fiber region for a yOz section corresponding to x = 90 voxels in the reference configuration. The segmented region was deemed accurate, and the nodes at the fiber-matrix interface coincided with the actual interface.

389 The gray-level residual fields of the matrix and fiber obtained using Reg-G-DVC for pulling 390 forces of 126 and 161 N are shown in Fig. 9(a) and (d). For both scans, their value is of the order of 391 3 gray levels in the matrix, whereas they reached ca. 4 gray levels within the fiber. The fact that the 392 gray-level residuals remained very small allowed us to deem the DVC registrations successful. In 393 addition, as shown in Fig. 9(a) and (b), the residuals in some areas of the matrix near the interface 394 were greater than those in other areas, such as the magenta box area. When F = 126 N, the order of magnitude of the residuals was 10 voxels, and when F = 161 N, the residuals reached 20 voxels. 395 396 This observation indicates that damage may have occurred in that area of the matrix, and damage 397 grew with the increase in pulling force. The elements in that region did not satisfy the assumption 398 of elasticity in the mechanical regularization term. This issue can be addressed by introducing a 399 damage variable to reduce the weight of the penalization, thereby enhancing the accuracy of the 400 DVC results [52]. From Fig. 9(c) and (d), it is observed that some areas in the fiber near the interface 401 had large residuals, such as the blue box area, which may be due to the fact that the segmented fiber

contained a small amount of matrix.

403



404 Fig. 9 Gray-level residual fields. In the matrix when F = 126 N (a) and F = 161 N (b); 405 in the fiber when F = 126 N (c) and F = 161 N (d).

406

The combined displacement fields of both regions (including the split nodes) after rigid body 407 408 rotation and translation corrections are shown in Fig. 10. From Fig. 10(a), it is observed that when 409 the pulling force was equal to 126 N, the fiber experienced approximately 6 voxels (0.11 mm) of 410 displacement at the embedded end, and about 12 voxels (0.23 mm) at the initiation region. As shown 411 in Fig. 10(b), when the pulling force was equal to 161 N, the fiber underwent about 16 voxels 412 (0.30 mm) of motion at the embedded end, and approximately 28 voxels (0.53mm) at the initiation 413 region. It was expected that the displacements at the initiation region were greater than at the 414 embedded end. Furthermore, when the fiber was subjected to a downward pulling force, there was 415 an overall downward displacement, and this displacement increased with higher pulling force.

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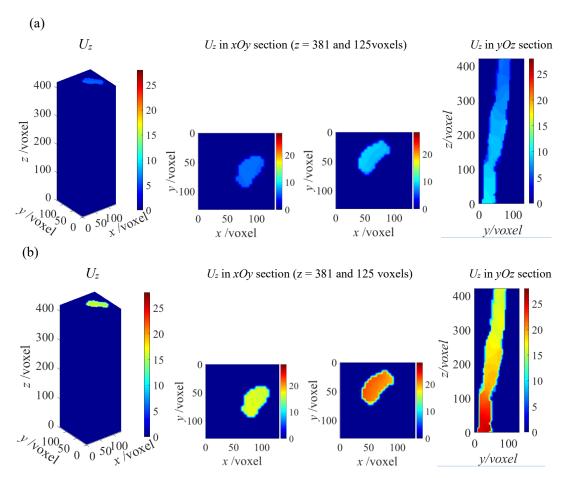
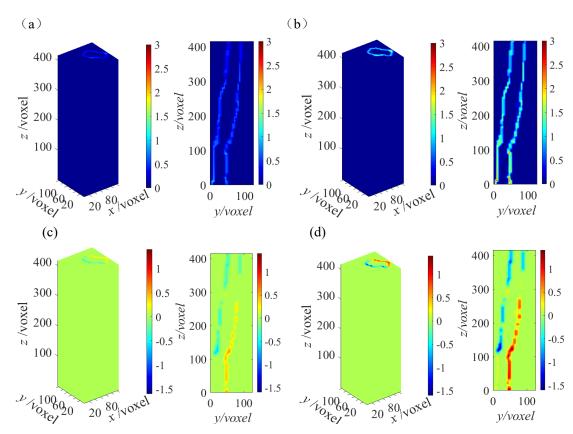


Fig. 10 Displacement fields in the *z*-direction expressed in voxels when the pulling force is equal
to (a) 126 N and (b) 161 N.

421 Based on the displacement fields obtained from separate calculations, the strain fields were 422 computed by differentiating the finite-element shape-functions. Fig. 11 shows three-dimensional 423 and sectional views of the maximum principal strain and shear strain fields. From Fig. 11(a) and (b), 424 it is observed that significant strains occurred at the interface during fiber pullout. Under a pulling 425 force of 126N, the strain distribution was relatively uniform. When the pulling force increased to 426 161N, the strain levels increased, and it is observed that the strains were higher at some positions, 427 which was due to the presence of indentations on the fiber surface. From Figs. 11(c) and (d), it is 428 seen that the shear strain \mathcal{E}_{xz} distribution at the interface was uneven. This observation may 429 indicate an uneven distribution of interfacial bonding strength along the pull-out direction.

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433 Fig. 11. Strain fields. Maximum principal strain when F = 126 N (a) and F = 161 N. Shear strain 434 \mathcal{E}_{xz} when F = 126 N (c) and F = 161 N (d).

435 **4.2 Debonding Analysis**

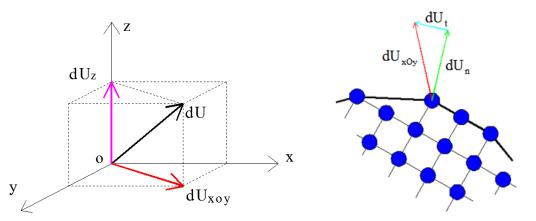
To analyze the debonding process during fiber pullout from the matrix, the displacement jumpof the split nodes is defined as

438

$$d\mathbf{U} = \mathbf{U}_{\text{fiber}} - \mathbf{U}_{\text{matrix}} \tag{15}$$

439 To assess the debonding conditions, the displacement jump vector dU is decomposed into vertical (z-axis) dU_z and horizontal (within the xOy plane) dU_{xoy} components; dU_{xoy} is decomposed 440 441 into dU_t and dU_n (Fig. 12), where dU_n and dU_t are the displacement jumps along the 442 normal and tangential directions of the fiber surface in the xOy plane (slice plane), respectively. 443 When analyzing debonding, the measurement uncertainty was considered to avoid false alarms (i.e., 444 detecting debonded nodes in the repeat scans). The same volumes as in Section 3.2 were used to 445 evaluate the standard uncertainty of the displacement jump components. The results are as follows: $\sigma_{dU_n} = 0.06, \sigma_{dU_1} = 0.09$ and $\sigma_{dU_2} = 0.04$ voxel. The debonding threshold was selected as five times 446

the uncertainty of the displacement jump component [50]. Thus, the detection thresholds for dU_n , dU_t , and dU_z are equal to 0.3, 0.45 and 0.2 voxel, respectively. The nodes with the displacement jump exceeding the detection threshold are assumed to be debonded.

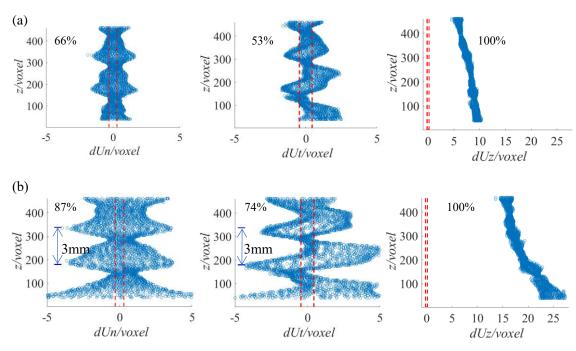


451 Fig. 12. Decomposition dU into z-direction and normal and tangential displacement jumps in the 452 xOy plane.

453

In Fig. 13, the distribution of normal, tangential and longitudinal displacement jumps are 454 455 presented for pullout forces equal to 126 and 161 N. The horizontal axis represents the displacement 456 jump of nodes, while the vertical axis represents the position of the node in the longitudinal 457 (z-) direction. The displacement jumps of the nodes outside the two dashed red lines were greater 458 than the detection threshold, and they were labeled as debonded. The percentage in the figures 459 reports that of debonded nodes relative to the total number of split nodes. It is observed that the 460 normal and tangential displacement jumps within were unevenly distributed and related to the 461 geometric shape of the fiber. The indentation spacing was 158 voxels, which corresponded to 3 mm, 462 and the interval between significant changes in displacement jump was approximately 3 mm as well. 463 This feature was more pronounced when the pulling force reached 161 N. When the pulling force was equal to 126 N, the longitudinal displacement jump varied between 4.6 and 10.3 voxels, which 464 465 was at least one order of magnitude higher than the detection threshold, thereby indicating that the fiber was completely debonded. When the pulling force reached 161N, the longitudinal 466 displacement jump continued to increase, now ranging from 13.6 to 27.3 voxels. 467

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- 469



470 Fig. 13 Normal, tangential and longitudinal displacement jumps when the pullout force as equal to
471 126 N (a) and 161 N (b).

Fig. 14 shows 3D renderings of displacement jumps along the normal, tangential and longitudinal directions. Fig.14(a) and (b) show that the normal and tangent displacement jumps are unevenly distributed, exhibiting positive values on one side of the fiber and negative values on the other side, with a central region of approximately 0 level. Fig.14(c) indicates that when the pullout force reached 126 N, 6 to 12 voxels displacement jumps were detected between the fiber and the matrix. When the pullout force reached 161 N, 16 to 28 voxels displacement jumps were detected, and the displacement jump from the embedded end to the embedded initiation region of the fiber gradually increased.

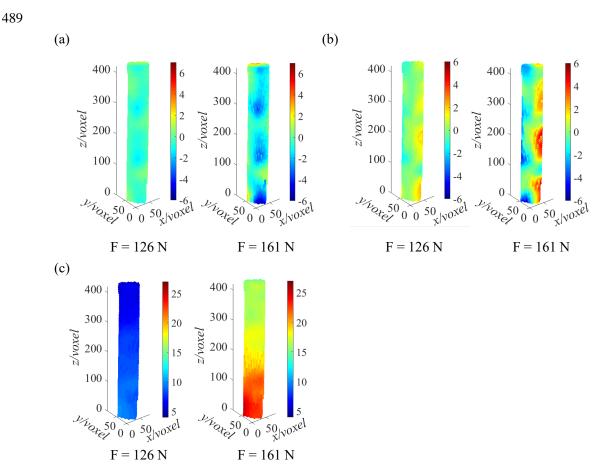
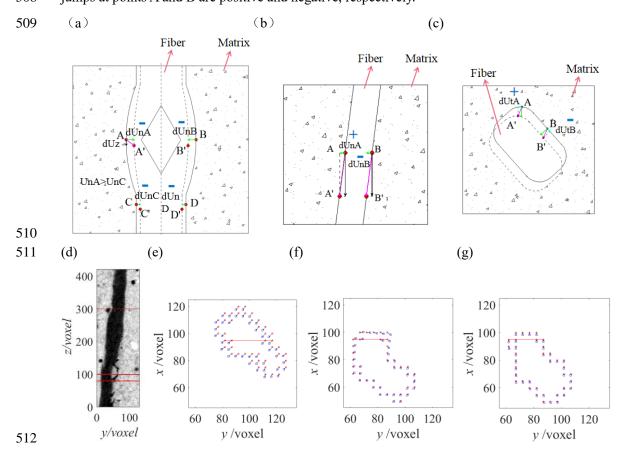


Fig. 14 3D renderings of displacement jump fields for the normal (a), tangential (b) andlongitudinal (c) components.

492 Based on the definition of the positive and negative directions of the normal displacement jumps of the fiber shown in Fig. 12, combined with Fig. 14, it is inferred that the relative motion of 493 494 different nodes during fiber pullout was complex. Fig. 15 was drawn for a specific analysis of 495 Fig. 14(a) and (b). Fig.15(a) and (c) represent schematic diagrams of the fiber pull-out scenario. Fig. 15(a) shows that if the fiber is vertically embedded and contracts radially during pullout, then 496 497 the normal displacement jumps of all nodes within the xOy plane should be negative and the 498 magnitude is related to the indentation location. Positions with significant indentation (e.g., points 499 A and B) experienced higher negative normal displacement jumps within the xOy plane, whereas 500 other positions (e.g., points C and D) underwent lower levels. Owing to the inclined placement of 501 the fiber, it moved in the direction indicated by the green arrow in Fig. 15(b) during pullout within 502 the xOy plane, causing the normal displacement jumps within the xOy plane to be positive on one 503 side (point A) and negative on the other side (point B).

504 The impact of inclined fiber embedding on the tangential displacement jumps in the *xOy* plane

is shown in Fig. 15(c). Under pulling forces F = 0 and 161 N, the positions of the fiber in the *xOy* section are depicted by the solid and dashed lines, respectively. It is seen that point A on the fiber will move to point A', and point B will move to point B'. Therefore, the tangential displacement jumps at points A and B are positive and negative, respectively.



513 Fig. 15 Analysis diagram of normal and tangential displacement jumps in the *xOy* plane.

(a) Vertical pull-out. (b) Normal relative position and (c) tangential relative position before and after oblique pull-out. (d) Grayscale image of yOz section. Displacement jumps in xOy sections when (e) z = 300 voxels, (f) z = 100 voxels and (g) z = 80 voxels.

Based on the displacement jumps, typical sections were selected to analyze the reasons for the uneven distribution of displacement jumps in xOy sections. Fig. 15(d) shows a grayscale image of the yOz cross-section. The displacement jumps in xOy sections corresponding to three different heights (z=300, 100, 80 voxels) are shown in Fig. 15(e) and (g). The red pentagrams in Fig. 15(e) and (g) indicate the node positions at a pull-out force F = 0 N, while the blue circles indicate the new positions when F = 161N. In Fig. 15(e), all four nodes on the red line move in the negative ydirection due to the inclination of the fiber toward the negative y-axis. In Fig. 15(f), all four nodes on the red line move along the positive *y*-direction due to the inclination of the fiber toward the positive y-axis. In Fig. 15(g), the four nodes on the red line experienced minimal motion in the *y*direction, indicating that there was no inclination of the fiber at that location.

528 **5 Conclusion**

In this study, the interface between polypropylene fibers (typically used as synthetic reinforcement) and concrete was investigated. Mechanically regularized DVC was employed to perform three-dimensional quantifications of the development of interface debonding during an insitu pullout test. The main conclusions were as follows:

(1) Reg-G-DVC incorporates mechanical regularization, thereby enhancing the spatial resolution of displacement measurements. When the element size was reduced to as low as 5 voxels, and the regularization length was set to 40 voxels, the maximum standard displacement uncertainties for the mortar matrix and the fiber were equal to 0.09 and 0.11 voxels, respectively. The deformation fields of the mortar matrix and fibers during the pre-peak pullout process were captured. Pronounced strain concentrations were observed at the interface, revealing the deformation characteristics of the interface.

(2) Debonding of the interface could be effectively analyzed by using the normal and tangential displacement jumps and the relative displacement along the fiber direction at the split nodes between the fiber and the matrix. The distribution of normal and tangential displacement jumps exhibited periodic fluctuations corresponding to the fiber geometry. The maximum displacement jump along the fiber occurred at the embedded initiation, and it decreased along the fiber toward the embedded end. As the pull-out force increased, the debonding zone extended from the embedded initiation to the embedded end of the fiber.

(3) The indentations on the fiber surface caused the fiber size to change periodically along the length, which significantly affected both macroscopic and microscopic characteristics obtained from the analysis of an in-situ fiber pullout test. The force–displacement curve showed multipeak features beyond the ultimate force, and the displacement jumps along the fiber surface in the normal and tangential directions had periodic fluctuations corresponding to the indentation spacing. This observation indicates that the periodic indentation on the fiber enhanced the friction and cohesive forces between the fiber and the matrix during the pull-out process. In addition, the influence of

- 554 fiber geometry on pull-out was also observed through the strain distribution at the interface, where
- 555 significant strain concentrations existed at locations with smaller fiber cross-sectional widths.
- 556 This study demonstrated the feasibility and advantages of using Reg-G-DVC to measure and 557 analyze displacement fields during interface debonding. Additionally, it provided quantitative 558 support for validating interface models and identifying full-field deformation parameters by 559 utilizing this research framework to obtain deformation data.
- 560

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570 and Writing-Review.

571

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