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Looking for Equivalence between Maximum Likelihood and Sparse DOA Estimators

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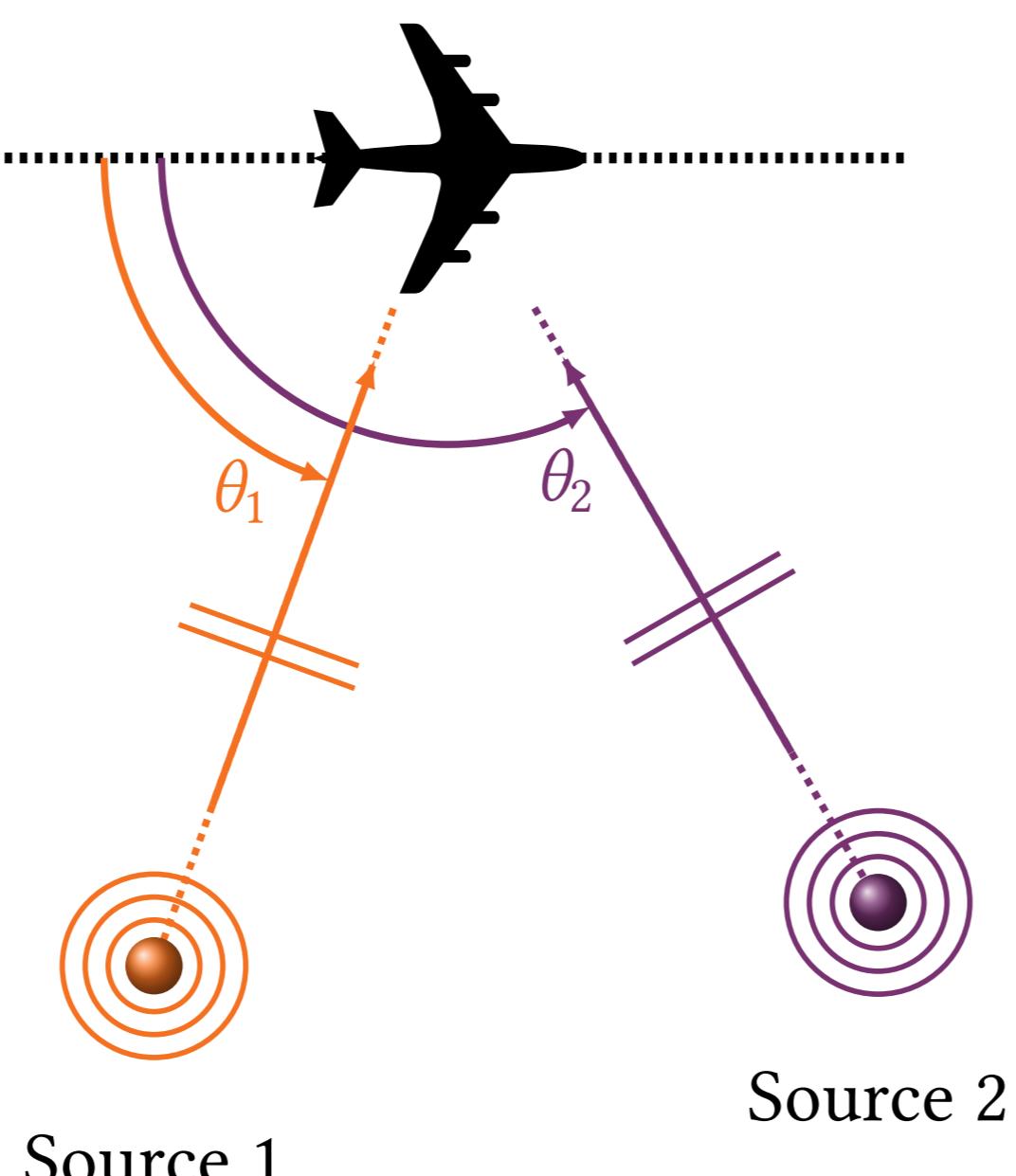


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ABSTRACT
Sparse Direction-of-Arrival (DOA) estimators depend on the regularization parameter λ which is often empirically tuned. In this work, conducted under the vectorized covariance matrix model, we are looking for theoretical equivalence between the Maximum Likelihood (ML) and sparse estimators. We show that under mild conditions, λ can be chosen thanks to the distribution of the minimum of the ML criterion in the case of two impinging sources. We derive this distribution under complex non-circular Gaussian noise. The corresponding λ choice is θ -invariant, only requiring an upper bound on the number of sources. Furthermore, it guarantees the global minimum of the sparse ℓ_0 -regularized criterion to be the ML solution. Numerical experiments confirm that, for the proposed λ , sparse and ML estimators yield the same statistical performance.

INTRODUCTION

□ DOA estimation : a classical signal processing problem with critical applications (radar, telecommunications...) [1]



☒ Objective : estimate the sources directions of arrival $\theta_1, \dots, \theta_M$

□ Numerous methods have been proposed : Capon's beamformer [2], MUSIC [3], ML [4]:

✗ MUSIC can not handle coherent sources

✗ ML is intractable for large number of sources

✗ Limited number of identifiable sources

☒ The vectorized covariance matrix model

✓ High number of identifiable sources

✓ Enhanced performances in severe scenarios

□ DOA estimation with the vectorized covariance matrix model : **sparse methods**

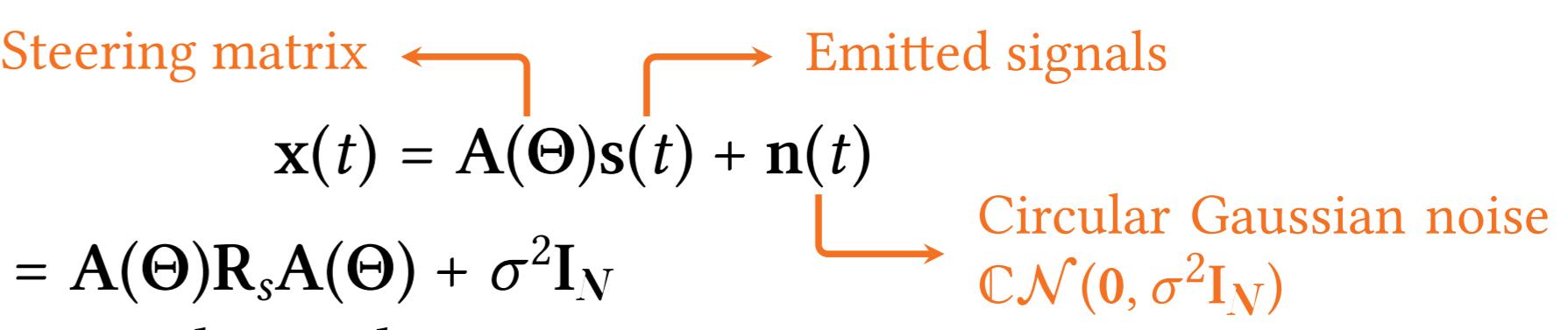
□ Sparse methods rely on the minimization of a regularized criterion parametrized by λ an hyperparameter which is **often empirically tuned**

☒ Contribution: we propose a novel θ -invariant regularization parameter choice that ensures equivalence between ML and sparse DOA estimators

THE VECTORIZED COVARIANCE MATRIX MODEL

Let M sources of directions $\Theta = \{\theta_1, \dots, \theta_M\}$ impinge on an array of N antennas

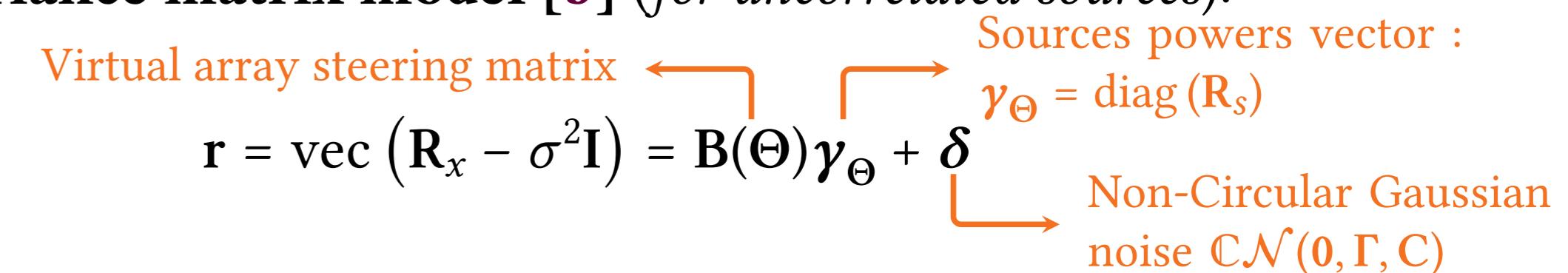
Classical model:



with covariance matrix $R_x = A(\Theta)R_sA(\Theta) + \sigma^2I_N$

✗ Number of identifiable sources limited to $N - 1$ sources

The vectorized covariance matrix model [5] (for uncorrelated sources):



✓ Allows the processing of at most $N^2 - 1$ sources with *increased resolution*

Maximum Likelihood estimation on the vectorized covariance matrix model:

Pre-whitening $y = Wr = B_w(\Theta)y_\Theta + \delta_w$ with $W = \Gamma^{-1/2}, B_w(\Theta) = WB(\Theta), \delta_w = W\delta$

ML estimation $\hat{\Theta} = \arg \min J_{ML}(\Theta)$ with $J_{ML}(\Theta) = y^H \Pi^\perp(\Theta) y$

✗ Minimizing J_{ML} requires M -dimensional non-convex optimization with numerous local minima

☒ Objective : solve the ML through sparse DOA estimators

SPARSE MODELING AND SPARSE ESTIMATION

Sparse modeling

□ Let $\Phi = \{\varphi_1, \dots, \varphi_G\}$ a grid of G pre-defined directions such that $\Theta \subset \Phi$

□ $B_w(\Phi) = W [b(\varphi_1), \dots, b(\varphi_G)] : N^2 \times G$ matrix containing the virtual array response $b(\varphi_g)$ in each of the G grid directions

□ **Sparse** vectorized covariance matrix model

$$y = B_w(\Theta)y_\Theta + \delta_w = B_w(\Phi)\gamma_0 + \delta_w$$

Sparse $G \times 1$ vector with only M non null coefficients

□ DOAs corresponds to the directions φ_G of γ_0 non zeros components

Sparse estimation

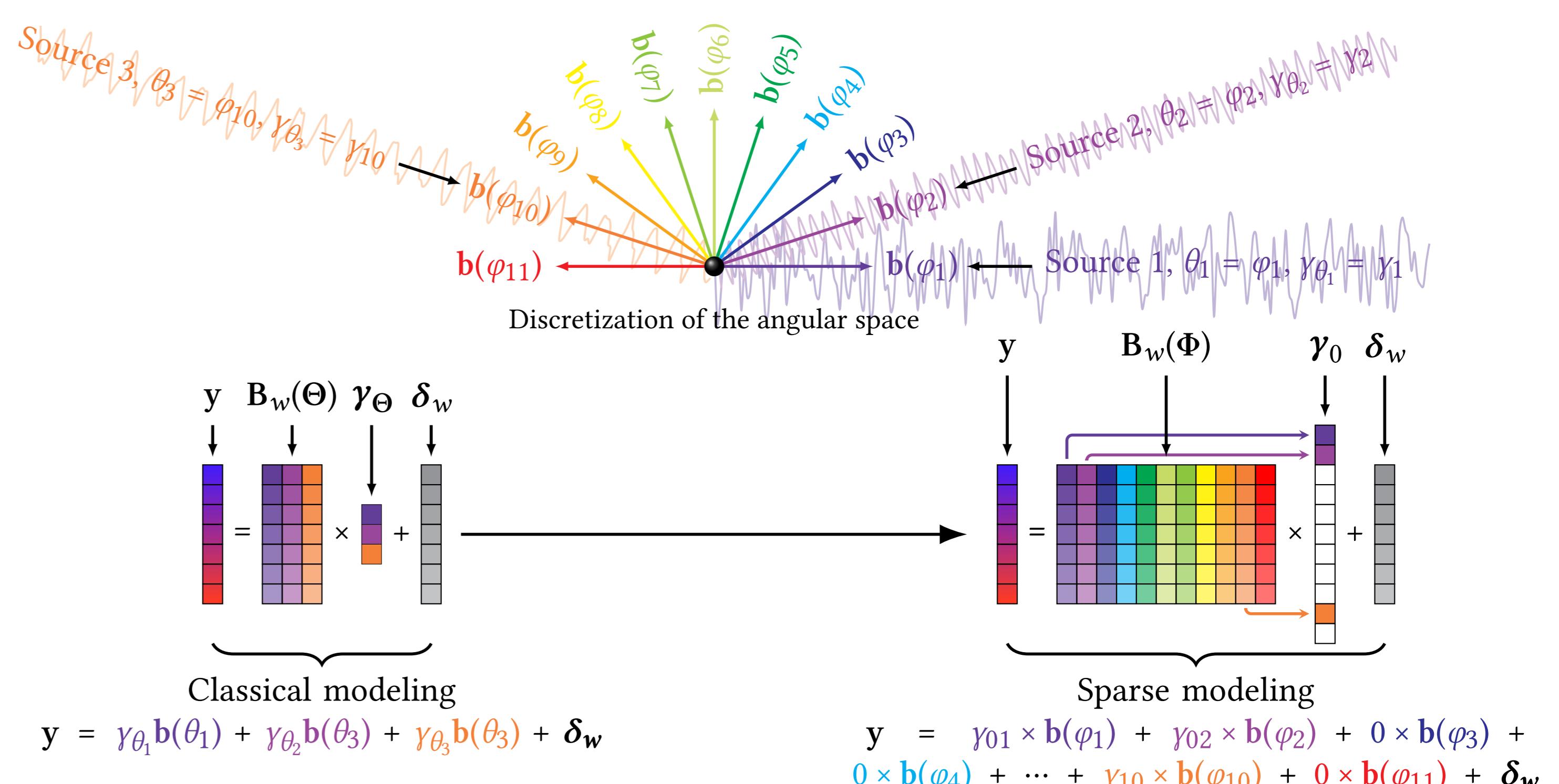
✗ $G \gg N^2$: the problem is ill-posed

□ Use of the sparsity prior : regularized problem formulation

□ Penalty function Ψ : ℓ_0 norm, Continuous Exact ℓ_0 (CEL0) [6]

$$\hat{y} = \arg \min_y J_\Psi(\lambda, y) \quad \text{with} \quad J_\Psi(\lambda, y) = \frac{1}{2} \|y - B_w(\Phi)y\|_2^2 + \Psi(\lambda, y)$$

Data fidelity Penalty

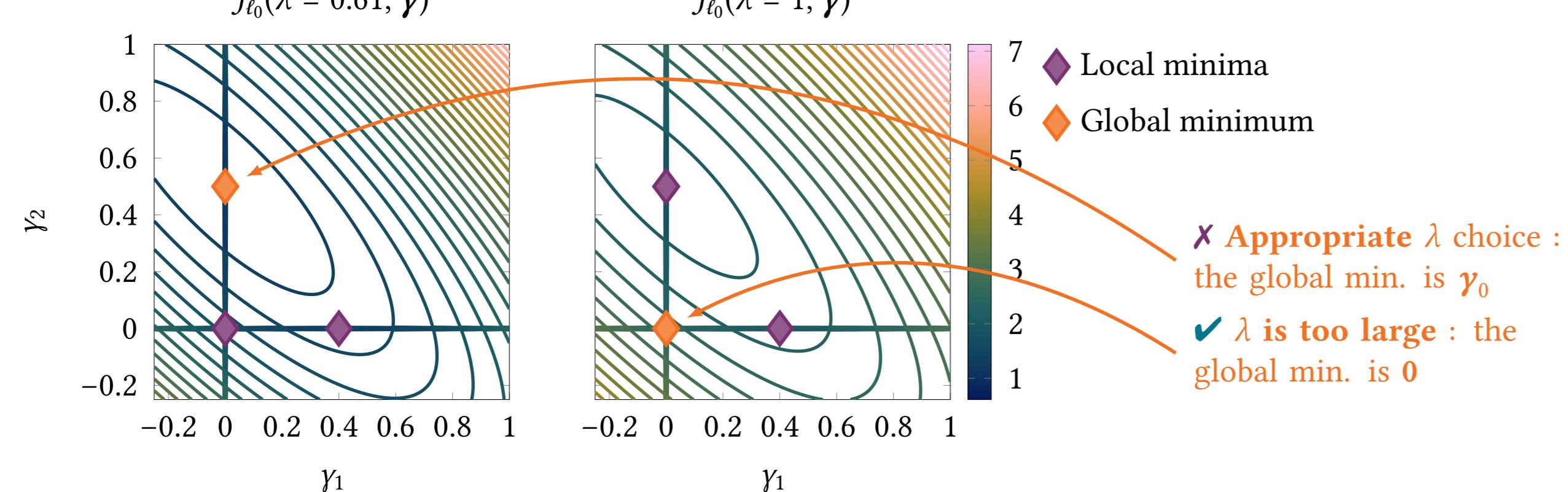


REGULARIZATION PARAMETER λ CHOICE

□ λ balances data fidelity towards the solution sparsity

Example : influence of the regularization parameter on the criterion minima

Contour lines of J_{ℓ_0} : $y = \begin{bmatrix} 1 \\ 0.5 \end{bmatrix}, B = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$ and $\gamma_0 = \begin{bmatrix} 0 \\ 0.5 \end{bmatrix}$.



☒ Equivalence: both ML and sparse criterion have the same global minimizer

□ Delmer's [7] interval $[\lambda^-, \lambda^+]$ ensures the equivalence but the statistics of λ^-, λ^+ :

✗ Are difficult to compute

✗ Depend on the directions

☒ Contributions[8]:

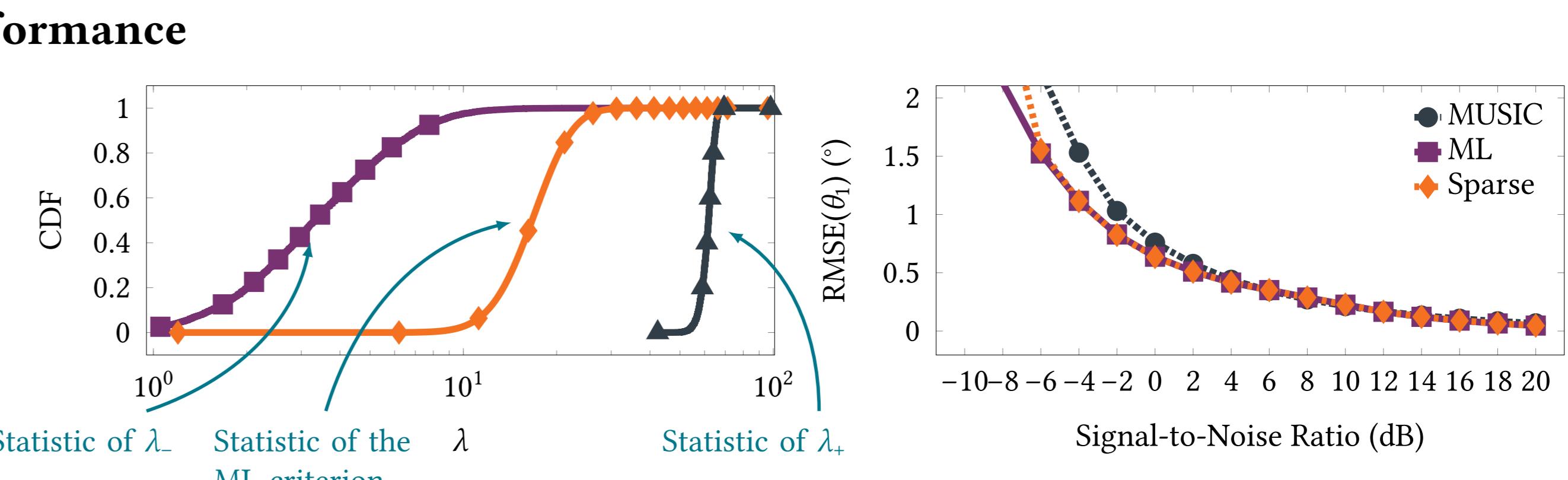
□ The min. of the ML, ϵ , criterion belongs to the interval $[\lambda^-, \lambda^+]$

□ ϵ follows, asymptotically, a χ^2 distribution with $N^2 - M$ degrees of freedom

□ θ -invariant distribution

□ The proposed λ choice belongs to the interval $[\lambda^-, \lambda^+]$: it ensures equivalence with the ML

□ Numerical simulations confirm that both ML and sparse estimators have the same statistical performance



CONCLUSION

□ Novel θ -invariant regularization parameter choice

□ Ensuring equivalence between sparse and ML DOA estimators

□ Efficient implementation of the ML

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