

Separation of the orbits in representations of SO 2 and O 2 over R and C

Evelyne Hubert, Martin Jalard

▶ To cite this version:

Evelyne Hubert, Martin Jalard. Separation of the orbits in representations of SO 2 and O 2 over R and C. 2024. hal-04656738

HAL Id: hal-04656738 https://hal.science/hal-04656738

Preprint submitted on 22 Jul 2024

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers. L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

Separation of the orbits in representations of SO₂ and O₂ over \mathbb{R} and \mathbb{C}

Evelyne Hubert and Martin Jalard^{*} Inria Côte d'Azur, France

July 22, 2024

Abstract

We provide a minimal set of invariant polynomials separating all the orbits for representations of SO_2 and O_2 over \mathbb{C} and \mathbb{R} . We obtain very small cardinalities by selecting only polynomials of support of bounded dimension. Altough they suffice for a lot of applications, the obtained separating sets are much smaller than the already kwnown generating set. We also remark that real separating set are smaller than the complex ones. We next stratify entirely the orbit space through the evaluation of the invariant polynomials.

^{*}Contact: martin.jalard@inria.fr

Contents

1	Introduction	2
2	Arithmetics and wheels	3
3	Separating invariants for $SO_2(\mathbb{C})$ 3.1 With rational invariants3.2 With polynomial invariants	5 5 6
4	Separating invariants for $\mathrm{SO}_2(\mathbb{R})$	8
5	Separating invariants for $O_2(\mathbb{R})$ 5.1 Computation of the set5.2 Minimality5.3 Comparison to a generating set	9 9 11 13
6	Separating invariants for $\mathrm{O}_2(\mathbb{C})$	14
7	Stratification of the real orbit space	17
A	Irreducible representations of SO_2 and O_2	19

1 Introduction

We present minimal separating set for arbitrary representations of SO₂ and O₂ over \mathbb{C} (Theorems 3.4 and 6.1), and over \mathbb{R} (Theorems 4.2 and 5.1). Over the complex numbers, it means that our set separate closed orbits. Over the reals, it means more naturally that they separate all the orbits (Definition 4.1). We obtain significatively low cardinality: in $\mathcal{O}(n^2)$ for SO₂ and $\mathcal{O}(n^4)$ for O₂, where *n* is the dimension of the representation. Weyl already provided a minimal separating set for a direct summand of standard representations [Wey46]. We thus generalize this result to arbitrary representations. The irreducible representations of O₂(\mathbb{R}) are indexed by \mathbb{N} (Appendix A) and induce a lot of arithmetic difficulties.

The generators of the invariant algebra possess these separation property. Yet they are of very large cardinality. For $SO_2(\mathbb{C}) \cong \mathbb{C}^*$, these generators consist of monomials of large support in $\{1, ..., n\}$ and thus their numbers is up to 2^n . Yet for separation we show that one can choose monomials with bounded support. We prove that monomials of support of cardinality three separate the orbits. This comes from the arithmetical key Lemma 2.4. We next deduce the same for the action of $O_2(\mathbb{C})$, where invariants of support of cardinality at most four suffice. We thus find much smaller separating set contained in the generating set. Furthermore, we provide explicit expressions of the separating set whereas generating set are computed by heavy algorithms [Stu08; Des+23].

Despite of their smaller cardinalities, separating set can be used instead of generating set for many applications. For instance, a separating set induces an epimorphism onto the orbit space, and thus can be used to stratify the orbit space. A complete stratification of representations of $SO_2(\mathbb{R})$ and $O_2(\mathbb{R})$ is provided in Section 7.

Since the definition of separation is weaker over \mathbb{R} , the real separating set have significatively smaller cardinalities than the complex ones (see Example 4). Altough few studied in invariant theory, this difference is important for many applications concerning only the real numbers. As an example, real separating set are needed to compute universal invariant or equivariant networks converging on any compact [DG24; BV23]. The size of the separating set corresponds to the dimension of the first layer, thus the cardinality heavily reflects on the complexity.

We also highlight a great advantage to use rational invariants. Rational monomials of support of cardinality two suffice to separate the orbits of $SO_2(\mathbb{C})$, providing a rational separating set much smaller than the polynomial separating set (see Example 3.7). Altough less numerous, it separates many more orbits which are not closed. [Bür+21] yet study rational invariants to separate orbits of toric actions as the action of $SO_2(\mathbb{C})$. But the algorithms in [Bür+21] compute invariants for any support in [1, n]. A total set of separating invariants would bu much too large to be computed by that way.

We recall that if one has a separating set for a reductive group, almost all set of $2 \dim(\mathcal{V}) + 1$ linear combinations of the polynomials is a separating set [DK15]. But as discussed in [Kem24, Remark 6.2] it still is relevant to compute minimal separating set of higher cardinal. Indeed the linear combinations remove useful properties of the polynomials (the homogeneity or the low dimension of the supports).

We start giving some technical lemmas in Section 2. Separating sets are presented in Sections 3, 4, 5 and 5. We finish by the stratification in Section 7. Essential statements about linear representations are provided in Appendix A. For a real vector space \mathcal{V} , we note $\hat{\mathcal{V}} = \mathcal{V} \oplus i\mathcal{V}$ its complexification.

2 Arithmetics and wheels

The proofs of next sections rely on some technical lemmas of arithmetic. They describe how complex wheels intersects. In particular, the idea to keep only invariants of support two results from Lemma 2.4 and its Corollary.

Definition 2.1. For some $c \in \mathbb{C}^*$ and $a \in \mathbb{Z} \setminus \{0\}$, we define W_c^a the wheel of a^{th} roots of c: $W_c^a := \{z \in \mathbb{C}^* \mid z^a = c\}.$

Let u, v be two non zero vectors in the representation \mathcal{L}_a for some $a \in \mathbb{Z}^*$. Then, $W^{\frac{v}{u}}_{\frac{v}{u}}$ is the set of complex numbers z such that $\phi_a(u) = v$. For two integers $v, v' \in \mathbb{Z}$, we note $v \wedge v'$ their greatest common divisor and $v \vee v'$ their least positive common multiple.

Lemma 2.2. Let u, u', v, v' be integers and take the two set $U := \{u+kv, k \in \mathbb{Z}\}$ and $U' := \{u'+kv', k \in \mathbb{Z}\}$. There is the equivalence:

$$U \cap U' \neq \emptyset \Leftrightarrow (v \wedge v') \text{ divides } (u - u')$$

Proof. The Bezout identity ensures that $v \wedge v'$ is the least positive integer which is a linear combination of v and v'. Hence, for any integer $u, \exists k, k' \in \mathbb{Z}, u = kv' + k'v' \Leftrightarrow (v \wedge v')$ divides u. Then, $(v \wedge v')$ divides (u - u') iff $\exists k, k' \in \mathbb{Z}, u - u' = kv + k'v'$. This is equivalently $\underbrace{u - kv}_{\in U} = \underbrace{u' + k'v'}_{\in U'}$.

Corollary 2.3. Let c, c' be two complex numbers in \mathbb{C}^* and a, a' non zero integers. Then we have

$$W^a_c \cap W^{a'}_{c'} \neq \emptyset \Leftrightarrow c^{\frac{a \vee a'}{a}} = c'^{\frac{a \vee a'}{a'}}$$

In that case $W_c^a \cap W_{c'}^{a'} = W_{c^q c' q'}^{a \wedge a'}$, where q, q' are Bezout coefficients satisfying $aq + a'q' = a \wedge a'$.



Figure 1: Intersection of wheels

Proof. Let w be a root in $W_{c'}^{a'}$. Recall that $aa' = (a \lor a')(a \land a')$. Then, $w^{a \lor a'} = w^{\frac{aa'}{a \land a'}} = c^{\frac{a}{a \land a'}} = c^{\frac{a}{a \land a'}}$. Thus,

$$c^{\frac{a \vee a'}{a}} = c'^{\frac{a \vee a'}{a'}} \Leftrightarrow W_c^a \subset W_c^{a \vee a'} \underset{c \frac{a \vee a'}{a}}{\operatorname{and}} \operatorname{W}_{c'}^{a'} \subset W_c^{a \vee a'} \underset{c \frac{a \vee a'}{a}}{\operatorname{cn}}$$

Note $\varphi : \mathbb{Z} \to W^{a \vee a'}_{c \frac{a \vee a'}{a}}$ a surjective map with, for any integer $k, \varphi(k) = \varphi(0) * \exp\left(i\frac{2\pi k}{a \vee a'}\right)$. Then the preimage $\varphi^{-1}(W^a_c)$ is some $U = \left\{u + \frac{a \vee a'}{a}k, k \in \mathbb{Z}\right\}$ meanwhile the preimage $\varphi^{-1}(W^{a'}_{c'})$ is some U' = U'

 $\left\{u' + \frac{a \vee a'}{a'}k, k \in \mathbb{Z}\right\}$. However, $\left(\frac{a \vee a'}{a}\right) \wedge \left(\frac{a \vee a'}{a'}\right) = 1$. According to lemma 2.2, one has $U' \cap U \neq \emptyset$. This

gives $W_c^a \cap W_{c'}^{a'} \neq \emptyset$, and one deduces that $W_c^a \cap W_{c'}^{a'} = W_z^{a \wedge a'}$ for some unknown complex $z \in \mathbb{C}^*$. Nevertheless, for any $w \in W_c^a \cap W_{c'}^{a'} = W_z^{a \wedge a'}$ one has $c = w^a = w^{\frac{aa'}{a'}} = w^{(a \wedge a')\frac{a \vee a'}{a'}} = z^{\frac{a \vee a'}{a'}}$ and $c' = w^{a'} = w^{\frac{aa'}{a}} = w^{(a \wedge a')\frac{a \vee a'}{a}} = z^{\frac{a \vee a'}{a'}}$. If one choose, thanks to Bezout identity, q and q' such that $aq + a'q' = a \wedge a'$, then $q^{\frac{a \vee a'}{a'}} + q'\frac{a \vee a'}{a} = 1$. That is, $z = z^{q\frac{a \vee a'}{a'} + q'\frac{a \vee a'}{a}} = c^q c'q'$.

The following lemma is key in selecting invariants of low support:

Lemma 2.4. Let $U_1, ..., U_n$ be set as in Lemma 2.2 such that $\forall 1 \leq i < j \leq n, U_i \cap U_j \neq \emptyset$. Then, $\bigcap_{i=1}^{n} U_i \neq \emptyset$.

Proof. We proceed by induction. The lemma holds for n = 2. Take n > 2 such that the lemma holds for n-1. Then, $\bigcap_{i=1}^{n-1} U_i \neq \emptyset$ and one can rewrite $u_i = 0$ for $i \leq n-1$. Then, $\bigcap_{i=1}^{n-1} U_i = \{kM, k \in \mathbb{Z}\}$ with $M := \operatorname{lcm}(r_1, ..., r_{n-1})$. By Lemma 2.2 we have $U_i \cap U_n \neq \emptyset \Leftrightarrow (r_i \wedge r_n)$ divides $(u_i - u_n) \Leftrightarrow (r_i \wedge r_n)$ divides u_n . For all prime number p and integer u we note $\nu_p(u) = \max\{k \in \mathbb{N} \mid p^k \text{ divides } u\}$ the p-adic valuation of u.

$$\nu_p(u_n) \geq \max_{i \leq n-1} (\nu_p(r_i \wedge r_n)) \geq \max_{i \leq n-1} [\min(\nu_p(r_i), \nu_p(r_n)] \geq \min[\max_{i \leq n-1} (\nu_p(r_i)), \nu_p(r_n)] = \nu_p(M \wedge r_n)$$

This is, $M \wedge r_n$ divides u_n . Hence, apply the Lemma 2.2 again to have $U_n \cap \bigcap_{i=1}^{n-1} U_i \neq \emptyset$.

Corollary 2.5. Let $\{W_i = W_{c_i}^{a_i}, i \in I\}$ be a finite set of wheels such that any pair of them has a non empty intersection: $\forall i, j \in I, W_i \cap W_j \neq \emptyset$. Then, $\bigcap_{i \in I} W_i \neq \emptyset$.

Proof. Take $\{W_i = W_{c_i}^{a_i}, i \in I\}$ such a set. The union $\bigcup_{i \in I} W_i$ is contained in a big wheel W of cardinal $M = W_i$ $\operatorname{lcm}(a_i, i \in I)$, and one defines a surjective map $\varphi : \mathbb{Z} \to W$ with, for any integer $k, \varphi(k) = \varphi(0) \exp\left(i\frac{2\pi k}{M}\right)$. For $i \in I$, one has the preimage $U_i := \varphi^{-1}(W_i) = \left\{ u_i + k \frac{M}{a_i}, k \in \mathbb{Z} \right\}$. For any $i, j \in I$, $W_i \cap W_j \neq \emptyset \Rightarrow U_i \cap U_j \neq \emptyset$. According to lemma 2.4 then, $\bigcap_{i \in I} U_i \neq \emptyset$. This conversely gives $\bigcap_{i \in I} W_i \neq \emptyset$.

Not all pairwise intersections are necessary to get an overall intersection. It depends on the values of the integers a_i , as it appears on figure 2 with 2, 3, -6.

Proposition 2.6. Let $W_1 = W_{c_1}^{a_1}$, $W_2 = W_{c_2}^{a_2}$ and $W_3 = W_{c_3}^{a_3}$ be three wheels. Suppose that $W_1 \cap W_2$ and $W_1 \cap W_3$ are non empty. If a_1 divides $a_2 \vee a_3$, then $W_2 \cap W_3 \neq \emptyset$.



Figure 2: Automatic intersection

Proof. Define a surjective map $\varphi : \mathbb{Z} \to W_1$ with, for any integer $k, \varphi(k) = \varphi(0) \exp\left(i\frac{2\pi k}{a_1}\right)$. One has the preimages $U_2 := \varphi^{-1}(W_1 \cap W_2) = \left\{ u_2 + k \frac{a_1}{a_1 \wedge a_2}, k \in \mathbb{Z} \right\}$ and $U_3 := \varphi^{-1}(W_1 \cap W_3) = \left\{ u_3 + k \frac{a_1}{a_1 \wedge a_3}, k \in \mathbb{Z} \right\}.$ Lemma 2.3 claims that $(U_2 \cap U_3 \neq \emptyset) \Leftrightarrow (M \text{ divides } u_2 - u_3)$, where $M = \left(\frac{a_1}{a_1 \wedge a_2} \wedge \frac{a_1}{a_1 \wedge a_3}\right)$. A piece of *p*-adic calculus provides $M = \frac{a_1}{a_1 \wedge (a_2 \vee a_3)}$. Then $a_1 \mid (a_2 \vee a_3) \Leftrightarrow M = 1$, and M divides $u_2 - u_3$. Otherwise we choose $c_1 = c_2 = 1$ and $c_3 = \exp\left(\frac{2i\pi a_3}{a_1}\right)$. Then, $c_2^{\frac{a_2 \vee a_3}{a_2}} c_3^{\frac{a_2 \vee a_3}{a_3}} = \exp\left(\frac{2i\pi a_3}{a_1}\frac{a_2 \vee a_3}{a_3}\right) = \exp\left(\frac{2i\pi a_2 \vee a_3}{a_1}\right) \neq 1$. Then lemma 2.3 claims that $W_2 \cap W_3 = \emptyset$.

Separating invariants for $SO_2(\mathbb{C})$ 3

In this section we provide minimal separating set for arbitrary representations of $SO_2(\mathbb{C})$. Let a_1, \ldots, a_n be positive integers and $a_{-1}, ..., a_{-m}$ negative integers. We consider the representation of $SO_2(\mathbb{C})$ on

$$\hat{\mathcal{V}} = \bigoplus_{i=1}^m \mathcal{L}_{a_{-i}} \oplus \bigoplus_{i=1}^n \mathcal{L}_{a_i}$$

(the irreducible representations \mathcal{L}_k are defined in Appendix A). With the coordinates $(v_{-m_1}, ..., v_{-1}, v_1, ..., v_n)$, the rational monomial $\mathfrak{m}_e = \prod_{i=-m}^n v_i^{e_i}$ corresponds to the vector $e = (e_{-m}, ..., e_n)$ in \mathbb{Z}^{n+m} . Consider the row matrix $A = (a_{-m}, ..., a_n)$. Then the module $M_A = \{e \in \mathbb{Z}^{n+m} | Ae = 0\}$ corresponds to the Laurent monomials in $\mathbb{C}(\hat{\mathcal{V}})^{SO_2(\mathbb{C})}$. The monoid $M_A^+ = \{e \in \mathbb{N}^{n+m} | Ae = 0\}$ corresponds to the monomials of positive degree in $\mathbb{C}[\hat{\mathcal{V}}]^{SO_2(\mathbb{C})}$ [Stu08, Lemma 1.4.2]. One naturally defines the support of a monomial \mathfrak{m}_e as the set of indices $1 \le i \le n$ such that $e_i \ne 0$.

We first exhibit a set of cardinality $\mathcal{O}(n^2)$ composed of rational monomials of support of size two which separates any orbits of support of size more than two. (Theorem 3.1). Next we deduce a polynomial set of cardinality $\mathcal{O}(n^3)$, separating any closed orbits, by adding some monomials of support of size three (Theorem 3.4). The latter needs not be minimal for inclusion. We thus give a criterion to remove redundant polynomials (Proposition 3.5).

With rational invariants 3.1

As pointed out in [Bür+21], rational invariants of tori separate many not closed orbits, something that is not possible with any set of polynomial invariants. Furthermore, a very low number of rational invariants allows to separate orbits.

Let u, v be two points in $\hat{\mathcal{V}}$. We note W_i the set of complex numbers z such that $\phi_i(g_z^+)(u_i) = v_i$. For some subscripts i, j, we note $W_{ij} = W_i \cap W_j$. When neither u_i nor v_i vanish, we note $c_i = \frac{v_i}{u_i}$, and then $W_i = W_{c_i}^{a_i}$ is the wheel of a_i^{th} roots of c_i .

Theorem 3.1. For any $-m \leq i < j \leq n$, we note $\varepsilon_{ij} = \frac{a_i \lor a_j}{a_i}$. Consider the set of rational invariant

$$f^* = \left\{ p_{ij} = v_i^{-\varepsilon_{ij}} \times v_j^{\varepsilon_{ji}}, -m \le i < j \le n \right\}$$

and take two point u and v with at least two non zero coordinates. Then,

 $\exists P \in f^*, P(u) \neq P(v) \Leftrightarrow u, v \text{ are not in the same orbit.}$

Proof. Firstly for any pair of integers $-m \leq i < j \leq n$, one has $\frac{a_i \vee a_j}{a_i} a_i - \frac{a_i \vee a_j}{a_j} a_j = 0$. Then p_{ij} is invariant. Take some $v \in \mathcal{C} \setminus \{0\}$, and $0 \leq i \leq n$ such that $a_i \neq 0$. Then, there exists some $1 \leq j \leq m$ such that $a_{-i} \neq 0$ and $p_{-ij}(v) \neq 0$. Hence the polynomials $\{p_{i-j}, 1 \leq j \leq m\}$ separate orbits with $v_i = 0$ from orbits with $v_i \neq 0$. We can suppose then that none of the coordinates of v vanishes.

Let's introduce u another point in C without zero coordinate such that for any $P \in f^*$, P(u) = P(v). For all $-m \leq i < j \leq n$, one has $p_{ij}(v) = p_{ij}(u) \Rightarrow \frac{p_{ij}(v)}{p_{ij}(u)} = c_i^{\varepsilon_{ij}} c_j^{-\varepsilon_{ji}} = 1$. Then, lemma 2.3 claims that $W_{ij} \neq \emptyset$. Corollary 2.4 ensures the existence of some non zero complex number z in the intersection $\bigcap_{i=1}^{n} W_i$. This number verifies $\rho(q_z^+)(u) = v$.

Only $\frac{N(N+1)}{2}$ invariant rational functions suffice to separate almost all the orbits for SO₂(\mathbb{C}). Note that rational invariants of support of size 1 do not exist. Hence, it is not possible to separate more orbits with rational invariants. As in $[B\ddot{u}r+21]$, we separate the last orbits (of support 0 and 1) by their support: Two points of support of size less than 1 lie on the same orbit iff they have the same support.

3.2With polynomial invariants

Functions p_{ij} of Theorem 3.1 are not polynomial whenever i and j have the same sign. One may need a set of invariant polynomials. Because they are smooth, invariant polynomials cannot separate non closed orbits from their closure. There is thus the following definition of separation:

Definition 3.2. [DK15, Definition 2.3.8] Let $\hat{\mathcal{V}}$ be a complex G-variety. A subset $S \subset \mathbb{C}[\mathcal{W}]^{G}$ is said to be separating if for any $u, v \in \mathcal{W}$,

$$\exists P \in \mathbb{C}[\mathcal{W}]^{\mathrm{G}}, \ P(u) \neq P(v) \Leftrightarrow \exists Q \in S, \ Q(u) \neq Q(v)$$

Since $SO_2(\mathbb{C})$ is the complexification of the compact Lie group $SO_2(\mathbb{R})$, it is a reductive group [Ser66, Theorem 5]. We then need to find a set separating closed orbits [MFK94]. The following lemma determines the closed orbits of SO₂(\mathbb{C}) in the representation $\hat{\mathcal{V}} = \bigoplus_{i=1}^{m} \mathcal{L}_{a_{-i}} \oplus \bigoplus_{i=1}^{n} \mathcal{L}_{a_i}$.

Lemma 3.3. Note $\mathcal{C} \subset \hat{\mathcal{V}}$ the subset of points in closed orbits. Then

$$v \in \mathcal{C} \Leftrightarrow (\exists i \le n, v_i \ne 0 \Leftrightarrow \exists j \le m, v_{-j} \ne 0)$$

Proof. Choose $v \in \mathcal{V}$ with some $1 \leq i \leq n$ satisfying $v_i \neq 0$. Assume that there exists a sequence $z_n \in \mathbb{C}^{\mathbb{N}}$ such that $\rho(g_{z_n}^+)(v)$ converges in $\hat{\mathcal{V}}$. Since SO₂(\mathbb{C}) acts regularly it implies that z_n converges toward some $z \in \mathbb{C}$. If $z \neq 0, \rho(g_{z_n}^+)(v)$ converges toward $\rho(g_z^+)(v)$, and this limits belongs to the orbit of v. If z = 0, suppose that $\exists j \leq n$ such that $v_j \neq 0$. Hence, $\frac{1}{z^n}v_j$ converges, and that is not possible. Otherwise, if $\forall j \leq m$, $v_{-j} = 0$, then $\rho(g_{z_n}^+)(v)$ converges to 0, and this limits does not belong to the orbit

of v. Hence v does not belong to a closed orbit.

Thanks to Bezout identity, for any integers i < j < k, we choose q, q' and r, r' integers such that $a_i q + a_k q' = a_i \wedge a_k$ and $a_j r + a_k r' = a_j \wedge a_k$. With respect to this choice, we construct the function

$$h_{ijk} = v_i^{q \,\varepsilon_{ijk}} \times v_j^{-r \,\varepsilon_{jik}} \times v_k^{q'_i \varepsilon_{ijk} - r' \,\varepsilon_{jik}}$$

where $\varepsilon_{ijk} = \frac{(a_i \wedge a_k) \vee (a_j \wedge a_k)}{a_i \wedge a_k}$. When $-m \leq k < 0 < i < j \leq n$ or $-m \leq i < j < 0 < k \leq n$, we can choose q, q' positive and r, r' negative. Then, h_{ijk} is a polynomial.

Theorem 3.4. The following set of invariant polynomials separates closed orbits:

$$f = \left\{ \begin{array}{ll} p_{ij}, & -m \le i < 0 \le j \le n \\ h_{ijk}, & -m \le k < 0 < i < j \le n \text{ or } -m \le i < j < 0 < k \le n \end{array} \right\}$$

Proof. Firstly take any $1 \le i < j \le n$ and $-m \le k \le -1$. We compute the weighted sum of the exponents to prove that h_{ijk} is invariant:

$$a_i q \varepsilon_{ijk} - a_j r \varepsilon_{jik} + a_k \left(q' \varepsilon_{ijk} - r' \varepsilon_{jik} \right) = (a_i \wedge a_k) \vee (a_j \wedge a_k) \left(\frac{qa_i + q'a_k}{a_i \wedge a_k} - \frac{ra_j + r'a_k}{a_j \wedge a_k} \right)$$
$$= (a_i \wedge a_k) \vee (a_j \wedge a_k) (1-1) = 0$$

Let u and v be two points in C such that for any $P \in f$, P(u) = P(v). Let $1 \le i < j \le n$ be indices such that $u_i, u_j \neq 0$. According to lemma 3.3, there also exists some $1 \leq k \leq m$ such that $u_k \neq 0$. Then, $p_{ik}(u) = p_{ik}(v)$ implies that $v_i, v_k \neq 0$ and $W_{ik} \neq \emptyset$. Following lemma 2.3 we have $W_{ik} = W_{c_i^q c_i^{q'}}^{a_i \wedge a_k}$, and similarly $W_{jk} = W_{c_j^r c_k^{r'}}^{a_j \wedge a_k}$. However,

$$\begin{split} \frac{h_{ijk}(v)}{h_{ijk}(u)} &= 1 \quad \Rightarrow \quad \left(\frac{v_i}{u_i}\right)^{q\varepsilon_{ijk}} \left(\frac{v_j}{u_j}\right)^{-r\varepsilon_{jik}} \left(\frac{v_k}{u_k}\right)^{q'\varepsilon_{ijk}-r'\varepsilon_{jik}} = 1 \\ &\Rightarrow \quad c_i^{q\varepsilon_{ijk}} c_j^{-r\varepsilon_{jik}} c_k^{q'\varepsilon_{ijk}-r'\varepsilon_{jik}} = 1 \\ &\Rightarrow \quad \left(c_i^q c_k^{q'}\right)^{\frac{(a_i \wedge a_k) \vee (a_j \wedge a_k)}{a_i \wedge a_k}} = \left(c_j^r c_k^{r'}\right)^{\frac{(a_i \wedge a_k) \vee (a_j \wedge a_k)}{a_j \wedge a_k}} \end{split}$$

Then, Lemma 2.3 claims that $W_{ik} \cap W_{jk} \neq \emptyset$. Equivalently this is $W_{ij} \neq \emptyset$. Similar computations holds for $1 \leq -i < -j \leq m$, $1 \leq k \leq n$. That is, any pair of wheels in $\{W_i, -m \leq i \leq n\}$ has a non empty intersection. According to lemma 2.4, one then find some $z \in \bigcap_{i=-m}^{n} W_i$. This non zero complex number verifies $\rho(g_z^+)(u) = v$.

The separating set of Theorem 3.4 is not minimal in general. We provide a criterion to remove the redundant polynomials:

Proposition 3.5. The set \mathcal{F} obtained removing h_{ijk} whenever a_k divides $(a_i \lor a_j)$ is a minimal separating set for the inclusion.

Proof. We try to remove a polynomial and determine if there exists two non separated orbits.

• Assume that we remove p_{ij} for some $-m \leq i < 0 \leq j \leq n$. We choose then $u_i = u_j = 1$ and $v_i = v_j = 2$ (other coordinates are supposed to be zero). Then, for any polynomial $P \in \mathcal{F}$, P(u) = P(v) = 0. However, for any $z \in \mathbb{C}^*$, $\rho(a^+)(u) = v \Rightarrow \begin{cases} z^{a_i} = c_i = 2 \\ z^{a_i} = c_i = 2 \end{cases}$ This is impossible since a_i and a_j have opposite sign

for any $z \in \mathbb{C}^*$, $\rho(g_z^+)(u) = v \Rightarrow \begin{cases} z^{a_i} = c_i = 2\\ z^{a_j} = c_j = 2 \end{cases}$. This is impossible since a_i and a_j have opposite sign. • Assume that we remove h_{ijk} for some $-m \leq k < 0 \leq i < j \leq n$. If a_k divides $(a_i \lor a_j)$ for some $-m \leq i < j < 0 < k \leq n$, recall that

$$\begin{cases} p_{ik}(u) = p_{jk}(v) \\ p_{jk}(u) = p_{jk}(v) \end{cases} \Leftrightarrow \begin{array}{c} W_i \cap W_k \neq \emptyset \\ W_j \cap W_k \neq \emptyset \end{cases}$$

But in that case, Lemma 2.6 ensures directly that

$$\left\{ \begin{array}{l} W_i \cap W_k \neq \emptyset \\ W_j \cap W_k \neq \emptyset \end{array} \Leftrightarrow W_{ik} \cap W_{jk} \neq \emptyset \end{array} \right.$$

Then, u and v are in the same orbit. On the opposite, suppose that a_k does not divide $a_i \wedge a_j$. We choose $u_i = v_i = u_k = v_k = u_j = 1$ but $v_j = \exp\left(\frac{ia_j\pi}{a_k}\right)$. Then, $c_i = c_k = 1$ while $c_j = \exp\left(\frac{ia_j\pi}{a_k}\right)$. Since W_{ik} and W_{jk} are non empty, $p_{ik}(u) = p_{ik}(v)$ and $p_{jk}(u) = p_{jk}(v)$. All the other polynomials in f vanish at u and v. However, as discussed in the proof of lemma 2.6, $W_i \cap W_j = \emptyset$ and u and v are not in the same orbit. \Box

Remark 3.6. The cardinal of f is bounded by $nm \leq \#f \leq nm + m\binom{n}{2} + n\binom{m}{2}$. The lower bound is reached when all the integers a_i are the same up to sign. The upper bound is reached when the integers a_i are pairwise relatively prime.

Our separating set is much smaller than a generating set. A minimal generating set is given by irreducible elements of M_A^+ , that is elements which are not the sum of two non trivial elements. We note \mathcal{M} this set. Algorithm 1.4.5 in [Stu08] computes them. Irreducible solutions come with many supports in $[\![1,n]\!]$. Hence the cardinal of \mathcal{M} is exponential in the dimension. The separating set provideed in Theorem 3.4 consists of irreducible solutions of support of size at most three. It selects furthermore at most one monomial for each support. Thus the cardinal is dominated by $\binom{n+m}{3} \sim (n+m)^3$. The difference appears clearly in the following example:

Example 3.7. Let $(\rho, \hat{\mathcal{V}})$ be the representation of $SO_2(\mathbb{C})$ on $\mathcal{L}_{-11} \oplus \mathcal{L}_2 \oplus \mathcal{L}_3 \oplus \mathcal{L}_5 \oplus \mathcal{L}_7 \oplus \mathcal{L}_{11}$. A minimal generating set consists of the following 26 irreducible monomials:

Whereas, Theorem 3.4 gives the following polynomial separating set of cardinal 11 (where 4 among the 10 polynomials of type h_{ijk} have been removed):

$$f := \left\{ \begin{array}{ccc} v_{-1}^2 v_1^{11} & v_{-1}^3 v_2^{11} & v_{-1}^5 v_3^{11} & v_{-1}^7 v_4^{11} & v_{-1} v_5 \\ h_{1,2,-1} = v_1^6 v_2^7 v_{-1}^3 & h_{1,3,-1} = v_1^6 v_3^2 v_{-1}^2 & h_{1,4,-1} = v_1^6 v_4^3 v_{-1}^3 \\ h_{2,3,-1} = v_2^4 v_3^2 v_{-1}^2 & h_{2,4,-1} = v_{-1}^3 v_2^4 v_4^3 & h_{3,4,-1} = v_3^9 v_4^3 v_{-1}^8 \end{array} \right\}$$

4 Separating invariants for $SO_2(\mathbb{R})$

In this section we introduce another definition of separation over reals. We next give a minimal separating set for representations of $SO_2(\mathbb{R})$ of cardinality $\left(\frac{\dim(\mathcal{V})}{2}\right)^2$ (Theorem 4.2). Since the definition of seaparation over \mathbb{R} is weaker, we obtain a much lower cardinality than its complex analogue provided by Theorem 3.4, where the cardinality is dominated by $\dim(\hat{\mathcal{V}})^3$. Example 4.4 exhibits clearly this difference.

Since $SO_2(\mathbb{R})$ and $O_2(\mathbb{R})$ are both compact, so do their orbits and polynomials can separate all the orbit space. This gives rise to a more natural definition of separation:

Definition 4.1. Let G be a real compact algebraic group acting on a real variety \mathcal{V} . A subset $S \subset \mathbb{R}[\mathcal{V}]^{G}$ is a separating set if for any $u, v \in \mathcal{V}$, polynomials in S agree on u and v iff u and v are in the same orbit.

This is why separating set over \mathbb{R} are thus frequently smaller than over \mathbb{C} . For instance, the orbit space of a complex finite group can be separated by dim $(\hat{\mathcal{V}})$ polynomials iff the group is a reflexion group. Whereas, many non reflexion groups have this strong property over ther reals [Duf09]. Thus the importance for many applications to provide specific separating set over the reals.

Consider the action of $SO_2(\mathbb{R})$ on $\mathcal{V} = \bigoplus_{i=1}^n \mathcal{V}_{a_i}$ where $a_1, ..., a_n \in \mathbb{N} \setminus \{0\}$ (the irreducible representations

 \mathcal{V}_{a_i} of $\mathrm{SO}_2(\mathbb{R})$ are defined in Appendix A). The complexification $\hat{\mathcal{V}}$ decomposes into $\bigoplus_{i=1}^n (\mathcal{L}_{a_i} \oplus \mathcal{L}_{-a_i})$. We

still endow $\hat{\mathcal{V}}$ with the complex coordinates $v_1, v_{-1}, \dots, v_n, v_{-n}$ as in Section 3. This is, for any $v \in \mathcal{V}$ and $1 \leq i \leq n, v_i = \overline{v_{-i}}$. Note that we have $v_i \neq 0 \Leftrightarrow v_{-i} \neq 0$. Hence the polynomials of type h_{ijk} can be ommitted.

Theorem 4.2. The following set of cardinality n^2 is a minimal separating set for $SO_2(\mathbb{R}) \curvearrowright \mathcal{V}$:

$$f(\mathbb{R}) = \left\{ \begin{array}{cc} 2\Re(p_{-ij}) = p_{-ij} + p_{-ji}, & 1 \le i \le j \le n \\ -2\Im(p_{-ij}) = \mathfrak{i} \left(p_{-ij} - p_{-ji} \right), & 1 \le i < j \le n \end{array} \right\}$$

Proof. Let u and v be two points in \mathcal{V} such that for any $1 \leq i \leq j \leq n$, $p_{-ij}(u) = p_{-ij}(v)$. For any integer $1 \leq i \leq n$, we note that $u_i = 0 \Leftrightarrow u_{-i} = 0 \Leftrightarrow \Re(p_{-ii}) = 0$. It remains then to separate the orbits in the subvariety $\mathcal{V} = \bigoplus_{j \neq i}^n \mathcal{V}_{a_j}$.

Hence we assume that none of the coordinates of u and v vanish. Then, quotients c_i and wheels W_i are well defined. For $1 \le i \le n$, $p_{ii}(u) = p_{ii}(v) \Rightarrow u_i u_{-i} = v_i v_{-i} \Rightarrow c_i = \frac{u_i}{v_i} = \frac{v_{-i}}{u_{-i}} = \frac{1}{c_i}$. Then, $|c_i| = 1$ and the wheel W_i is included in the unit circle \mathcal{U} . As discussed in section A.3, $z \in W_i \subset \mathcal{U} \Rightarrow g_z^+ \in \mathrm{SO}_2(\mathbb{R})$. Furthermore as in Section 3, for $1 \le i < j \le n$, $p_{-ij}(u) = p_{-ij}(v) \Rightarrow W_i \cap W_j \neq \emptyset$. Then lemma 2.4 ensures that $\bigcap^n W_i$ is not empty. For some $z \in \bigcap^n W_i$, one has $g_z^+ \in \mathrm{SO}_2(\mathbb{R})$ and $\rho(g_z^+)(v) = u$.

that $\bigcap_{i=1}^{n} W_i$ is not empty. For some $z \in \bigcap_{i=1}^{n} W_i$, one has $g_z^+ \in \mathrm{SO}_2(\mathbb{R})$ and $\rho(g_z^+)(v) = u$. Unfortunately the restrictions on \mathcal{V} of polynomials $p_{-ij} \in \mathbb{C}[\hat{\mathcal{V}}]^{\mathrm{SO}_2(\mathbb{C})}$ are not real. We nevertheless notice that on \mathcal{V} , $p_{-ij} = \overline{p_{-ji}}$. Then, $p_{ij} = p_{-ij} + p_{-ji} = 2\Re(p_{-ij})$ and $\mathfrak{i}(p_{-ij} - p_{-ji}) = -2\Im(p_{-ij})$ are real. \Box

Remark 4.3. When $a_1 = 1$ for any $1 \le i \le n$, the representation of $SO_2(\mathbb{R})$ on \mathcal{V} is isomorphic to the representation on $2 \times n$ matrices $\mathcal{M}_{2,n}(\mathbb{R})$. Then, $\Re(p_{-ij})$ is the standard scalar product between the i^{th} and j^{th} column, while $\Im(p_{-ij})$ is their determinant. Thus, the separating set $f(\mathbb{R})$ consist of the classical Weyl invariants [Wey46, Theorem 2.9.4].

Example 4.4. Consider the representation of $SO_2(\mathbb{R})$ on $\mathcal{V} = \mathcal{V}_2 \oplus \mathcal{V}_3 \oplus \mathcal{V}_5 \oplus \mathcal{V}_7$. Then, Theorem 4.2 provides a set of 16 invariant polynomials separating the orbits of $SO_2(\mathbb{R})$:

$$f(\mathbb{R}) = \left\{ \begin{array}{ccccc} 2v_1v_{-1} & v_{-2}^2v_1^3 + v_{-1}^3v_2^2 & v_{-3}^2v_1^5 + v_{-1}^5v_3^2 & v_{-4}^2v_1^7 + v_{-1}^7v_4^2 & 2v_2v_{-2} \\ v_{-3}^3v_2^5 + v_{-2}^5v_3^3 & v_{-4}^3v_2^7 + v_{-2}^7v_4^3 & 2v_3v_{-3} & v_{-4}^5v_3^7 + v_{-3}^7v_4^5 & 2v_4v_{-4} \\ & i\left(v_{-2}^2v_1^3 - v_{-1}^3v_2^2\right) & i\left(v_{-3}^2v_1^5 - v_{-1}^5v_3^2\right) & i\left(v_{-4}^2v_1^7 - v_{-1}^7v_4^2\right) \\ & i\left(v_{-3}^3v_2^5 - v_{-2}^5v_3^3\right) & i\left(v_{-4}^3v_2^7 - v_{-2}^7v_4^3\right) & i\left(v_{-4}^5v_3^7 - v_{-3}^7v_4^5\right) \end{array} \right\}$$

Whereas, 24 monomials among the 48 of type h_{ijk} are required to separate closed orbits of $SO_2(\mathbb{C})$ in \mathcal{V} . Thus Theorem 3.4 provides a separating set of cardinality 16 + 24 = 40.

Separating invariants for $O_2(\mathbb{R})$ 5

We now consider actions of $O_2(\mathbb{R}) \cong SO_2(\mathbb{R}) \rtimes C_2$. The twist induces the existence, for each indice *i*, of two wheels W_i and W_i^- . It forces us to add invariants of support three or four. Thus the separating set has a cardinality in $\mathcal{O}(n^4)$. Consider the representation of $O_2(\mathbb{R})$ on

$$\mathcal{V} := igoplus_{i=1}^q \mathcal{V}_{-1} \oplus igoplus_{i=1}^n \mathcal{V}_{a_i}$$

endowed with the coordinates $(d_1, ..., d_q, v_1, v_{-1}, ..., v_n, v_{-n})$. We obtain a separating set in Theorem 5.1, which is not minimal in general for the inclusion. We then give a criterion to remove redundant polynomials and get a minimal separating set in Proposition 5.6. We finish comparing the obtained separating set to a generating set provided by the algorithm of [Des+23].

5.1Computation of the set

In addition to the wheels W_i and W_{-i} introduced in Section 3, we note W_i^- and W_{-i}^- the set of complex numbers such that

$$\begin{cases} \forall z \in W_i^-, \quad \rho_{a_i}(g_z^-)(u_i, u_{-i}) = (*, v_{-i}) \\ \forall z \in W_{-i}^-, \quad \rho_{a_i}(g_z^-)(u_i, u_{-i}) = (v_i, *) \end{cases}$$

When the quotients $c_i^- = \frac{v_{-i}}{u_i}$ and $c_{-i}^- = \frac{v_i}{u_{-i}}$ are well defined we have $W_i^- = W_{c_i^-}^{a_i}$ and $W_{-i}^- = W_{c_{-i}^-}^{-a_i}$. For any $1 \leq i \leq n$, we note $W_I = W_i \cap W_{-i}$ (the set of complex numbers such that $\rho_{a_i}(g_z^+)(u_i, u_{-i}) = (v_i, v_{-i})$) and $W_I^- = W_i^- \cap W_{-i}^-$ (the set of complex numbers such that $\rho_{a_i}(g_z^-)(u_i, u_{-i}) = (v_i, v_{-i})$). We introduce $\mathcal{T}(n) \subset [\![1, n]\!]^3$ and $\mathcal{Q}(n) \subset [\![1, n]\!]^4$ the set of ordered triplets and quadruplets:

$$(i,j,k) \in \mathcal{T}(n) \Leftrightarrow \left\{ \begin{array}{c} i < j \\ k \in \llbracket 1,n \rrbracket \setminus \{i,j\} \end{array} \right. \quad (i,j,k,l) \in \mathcal{Q}(n) \Leftrightarrow \left\{ \begin{array}{c} i < j, \ k < l \\ \{i,j\} \cap \{k,l\} = \emptyset \\ i+j \le k+l \\ If \ i+j = k+l, \ i < k \end{array} \right. \right\}$$

Theorem 5.1. The following set of polynomials separates orbits with respect to the action $O_2(\mathbb{R}) \sim \mathcal{V}$:

$$\mathcal{F}(\mathbb{R}) = \begin{cases} P_{ij} = p_{-ij} + p_{-ji} & 1 \le i \le j \le n \\ T_{ijk} = (p_{-ik} - p_{-ki})(p_{-jk} - p_{-kj}), & (i, j, k) \in \mathcal{T}(n) \\ Q_{ijkl} = (p_{-ij} - p_{-ji})(p_{-kl} - p_{-lk}), & i, j, k, l \in \mathcal{Q}(n) \\ D_{ij} = d_i d_j, & 1 \le i \le j \le q \\ S_{ijk} = \mathfrak{i} (p_{-ij} - p_{-ji}) d_k, & 1 \le i < j \le n, \quad 1 \le k \le q \end{cases}$$

To prove it, we take u and v two points in V such that for any $P \in \mathcal{F}(\mathbb{R}), P(u) = P(v)$ and check that there exists some $g \in O_2(\mathbb{R})$ verifying $\rho(g)(u) = v$. As for Theorem 4.2 we assume that none of the coordinates of u and v vanish. Then for any $1 \le i \le n$, quotients c_i, c_i^- and wheels W_I, W_I^- are well defined and we notice that

$$P_{ii}(u) = P_{ii}(v) \Rightarrow u_i u_{-i} = v_i v_{-i} \Rightarrow \begin{cases} c_i = \frac{v_i}{u_i} = \frac{u_{-i}}{v_{-i}} = \frac{1}{c_i} \\ c_i^- = \frac{v_{-i}}{u_i} = \frac{u_i}{v_{-i}} = \frac{1}{c_i^-} \end{cases}$$

Then, $|c_i| = |c_i^-| = 1$ and the wheels W_i, W_i^- are both included in the unit circle \mathcal{U} . As discussed in Appendix A.3, $z \in \mathcal{U} \Rightarrow g_z^+, g_z^- \in O_2(\mathbb{R})$. We next prove the following sequence of lemmas:

Lemma 5.2. For any integer $1 \le i \le n$, we have $W_i = W_{-i} = W_I$ and $W_i^- = W_{-i}^- = W_I^-$.

Proof. By assumption we have $P_{ii}(u) = P_{ii}(v) \Rightarrow u_i u_{-i} = v_i v_{-i}$. Since no coordinate vanish, $c_i = \frac{v_i}{u_i} = \frac{u_{-i}}{v_{-i}} = \frac{1}{c_{-i}}$ and $c_i^- = \frac{v_{-i}}{u_i} = \frac{u_{-i}}{v_i} = \frac{1}{c_{-i}^-}$. This implies $W_i = W_{-i}$ and $W_i^- = W_{-i}^-$.

Lemma 5.3. For any integers $1 \le i < j \le n$, we have $W_{IJ} \ne \emptyset$ or $W_{IJ}^- \ne \emptyset$. *Proof.* We notice that $p_{-ij}(v) = v_{-i}^{\varepsilon_{ij}} v_j^{\varepsilon_{ji}} = u_{-i}^{\varepsilon_{ij}} c_i^{\varepsilon_{ij}} u_j^{\varepsilon_{ji}} c_j^{\varepsilon_{ji}} = c_i^{\varepsilon_{ij}} c_j^{\varepsilon_{ji}} p_{-ij}(u)$. It provides

$$\begin{array}{lll} P_{-ij}(u) = P_{-ij}(v) & \Leftrightarrow & p_{-ij}(u) + p_{-ji}(u) = p_{-ij}(v) + p_{-ji}(v) \\ & \Leftrightarrow & p_{-ij}(u) + p_{-ji}(u) = c_i^{\varepsilon_{ij}} c_j^{\varepsilon_{ji}} p_{-ij}(u) + c_{-i}^{\varepsilon_{ij}} c_{-j}^{\varepsilon_{ji}} p_{-ji}(u) \\ & \Leftrightarrow & p_{-ij}(u) + p_{-ji}(u) = c_i^{\varepsilon_{ij}} c_j^{\varepsilon_{ji}} p_{-ij}(u) + c_i^{-\varepsilon_{ij}} c_j^{-\varepsilon_{ji}} p_{-ji}(u) \end{array}$$

This can be viewed as a second order equation of unknown $c_i^{\varepsilon_{ij}} c_j^{\varepsilon_{ji}}$, which has the two solutions $c_i^{\varepsilon_{ij}} c_j^{\varepsilon_{ji}} = 1$ or $c_i^{\varepsilon_{ij}}c_j^{\varepsilon_{ji}} = \frac{p_{-ji}(u)}{p_{-ij}(u)}$. The first solution implies $W_{ij} \neq \emptyset$ by lemma 2.3, and lemma 5.2 completes in $W_{IJ} \neq \emptyset$. The second solution gives $p_{-ij}(u) = c_i^{-\varepsilon_{ij}} c_j^{-\varepsilon_{ji}} p_{-ji}(u) = p_{-ji}(v)$, and

$$p_{-ij}(v) = p_{-ji}(u) \Rightarrow v_{-i}^{\varepsilon_{ij}} v_j^{\varepsilon_{ji}} = u_{-j}^{\varepsilon_{ji}} u_i^{\varepsilon_{ij}} \Rightarrow \left(\frac{v_{-i}}{u_i}\right)^{\varepsilon_{ij}} = \left(\frac{v_j}{u_{-j}}\right)^{\varepsilon_{ji}} \Rightarrow \left(c_i^-\right)^{\varepsilon_{ij}} = \left(c_{-j}^-\right)^{\varepsilon_{ji}}$$

Then lemma 2.3 claims that $W_{-ij}^- \neq \emptyset$, and lemma 5.2 completes in $W_{IJ}^- \neq \emptyset$.

Lemma 5.4. Let $(i, j, k) \in \mathcal{T}(n)$. Then, one has $\begin{cases} W_{IK} \neq \emptyset \\ W_{JK} \neq \emptyset \end{cases}$ or $\begin{cases} W_{IK}^- \neq \emptyset \\ W_{IK}^- \neq \emptyset \end{cases}$.

Proof. Following Lemma 5.3 we have $p_{-ij}(u) = p_{-ij}(v)$ or $p_{-ij}(u) = p_{-ji}(v)$, and this is $(p_{-ij} - p_{-ij})(u) = p_{-ij}(v)$ $\pm (p_{-ij} - p_{-ij})(v)$. Note furthermore that

$$\begin{cases} p_{-ij}(u) = p_{-ij}(v) \Rightarrow W_{IJ} \neq \emptyset \\ p_{-ij}(u) = p_{-ji}(v) \Rightarrow W_{IJ}^- \neq \emptyset \end{cases}$$

This holds also for j, k. Recall that we have $T_{ijk}(u) = T_{ijk}(v)$:

$$(p_{-ik} - p_{-ki})(-p_{-jk} - p_{-kj})(u) = (p_{-ik} - p_{-ki})(-p_{-jk} - p_{-kj})(v)$$

 $(p_{-ik} - p_{-ki})(-p_{-jk} - p_{-kj})(w) = (p_{-ik} - p_{-kj})(w) \neq 0 \text{ and } (p_{-jk} - p_{-kj})(w) = (p_{-jk} - p_{-kj})(v) \neq 0. \text{ Then,}$ $p_{-ik}(u) = p_{-ik}(v) \neq 0 \text{ and } p_{-jk}(u) = p_{-jk}(v) \neq 0. \text{ This is, } \begin{cases} W_{IK} \neq \emptyset \\ W_{JK} \neq \emptyset \end{cases}$ $\bullet \text{ If } (p_{-ik} - p_{-ki})(u) = -(p_{-ik} - p_{-ki})(v) \neq 0 \text{ and } (p_{-jk} - p_{-kj})(u) = -(p_{-jk} - p_{-kj})(v) \neq 0. \text{ Then,}$ $p_{-ik}(u) = p_{-ki}(v) \neq 0 \text{ and } p_{-jk}(u) = p_{-kj}(v) \neq 0. \text{ This is, } \begin{cases} W_{IK} \neq \emptyset \\ W_{JK} \neq \emptyset \end{cases}$ $\bullet \text{ If } (p_{-ik} - p_{-ki})(u) = -(p_{-ik} - p_{-ki})(v) \neq 0. \text{ This is, } \begin{cases} W_{IK}^{-} \neq \emptyset \\ W_{JK}^{-} \neq \emptyset \end{cases}$ $\bullet \text{ If } (p_{-ik} - p_{-ki})(u) = 0, \text{ then } p_{-ik}(v) \neq 0. \text{ This is, } \begin{cases} W_{IK}^{-} \neq \emptyset \\ W_{JK}^{-} \neq \emptyset \end{cases}$ $\bullet \text{ If } (p_{-ik} - p_{-ki})(u) = 0, \text{ then } p_{-ik}(v) = p_{-ki}(v) = p_{-ki}(v) \neq 0. \text{ We thus have both } W_{IK} \neq \emptyset$ $\bullet \text{ and } W_{IK}^{-} \neq \emptyset. \text{ However Lemma 5.3 ensures that } W_{KJ} \neq \emptyset \text{ or } W_{KJ}^{-} \neq \emptyset. \text{ We deduce that } \begin{cases} W_{IJ} \neq \emptyset \\ W_{KJ} \neq \emptyset \end{array}$ $\left\{ \begin{array}{c} W_{IJ}^{-} \neq \emptyset \\ W_{KJ}^{-} \neq \emptyset \end{array} \right.$

Lemma 5.5. Let $(i, j, k, l) \in \mathcal{Q}(n)$. Then one has $\begin{cases} W_{IJ} \neq \emptyset \\ W_{KL} \neq \emptyset \end{cases}$ or $\begin{cases} W_{IJ}^- \neq \emptyset \\ W_{KL}^- \neq \emptyset \end{cases}$

Proof. It is the same proof than for Lemma 5.4, but with the polynomial equality $Q_{ijkl}(u) = Q_{ijkl}(v)$.

We are now able to prove Theorem 5.1. According to lemmas 5.4 and 5.5 we have

$$\forall 1 \le i < j \le n \text{ and } 1 \le k < l \le n, \quad \left\{ \begin{array}{c} W_{IJ} \ne \emptyset \\ W_{KL} \ne \emptyset \end{array} or \; \left\{ \begin{array}{c} W_{IJ}^- \ne \emptyset \\ W_{KL}^- \ne \emptyset \end{array} \right. \right.$$

This is equivalent to $(\forall 1 \le i < j \le n, W_{IJ} \ne \emptyset)$ or $(\forall 1 \le i < j \le n, W_{IJ}^- \ne \emptyset)$. Then, according to Corollary 2.4, there exists $z \in \bigcap_{i=1}^{n} W_{I}$ (+) or $z \in \bigcap_{i=1}^{n} W_{I}^{-}$ (-).

Furthermore for any $1 \leq i \leq q$, the polynomial D_{ii} ensures that $|d_i| = |d'_i|$. This is, $\rho_{-1}(g_z^+)(d_i) = d'_i$ or $\rho_{-1}(g_z^-)(d_i) = d'_i$. If one has (+) but not (-) then there is $1 \le i < j \le n$ with $W_{II}^- = \emptyset$, and this is $(p_{-ij} - p_{-ji})(u) = (p_{-ij} - p_{-ji})(v) \neq 0$. One notices that for any $1 \leq k \leq q$, $S_{ijk}(u) = S_{ijk}(v) \Rightarrow d_k = d'_k$. Then, $\rho(g_z^+)(u) = v$. Conversely, if one has (+) but not (-) then there is $1 \le i < j \le n$ with $W_{IJ}^- = \emptyset$, and this is $(p_{-ij} - p_{-ji})(u) = -(p_{-ij} - p_{-ji})(v) \neq 0$. One notices that for any $1 \leq k \leq q$, $S_{ijk}(u) = S_{ijk}(v) \Rightarrow S_{ijk}(v) = S_{ijk}(v)$ $d_k = -d'_k$. Then, $\rho(g_z)(u) = v$.

If one has both (+) and (-), then for any $1 \le i < j \le n$, $(p_{-ij} - p_{-ji})(u) = (p_{-ij} - p_{-ji})(v) = 0$. Note that for any $1 \le i \le j \le q$ with $u_i \ne 0$ and $u_j \ne 0$, $D_{ij}(u) = D_{ij}(v) \Rightarrow \frac{d_i}{d_i} = \frac{d'_j}{d_j}$. Suppose that all these quotients are positive. Then $\rho(q_z^+)(u) = v$. Conversely, if all these quotients are negative, then $\rho(q_z^-)(u) = v$. Anyway there exists some $g \in O_2(\mathbb{R})$ verifying $\rho(g)(u) = v$ and Theorem 5.1 is proven.

5.2Minimality

In general, the separating set of Theorem 5.1 is not minimal for inclusion. We identify the redundant polynomials:

Proposition 5.6. Upon the following removals, $\mathcal{F}(\mathbb{R})$ is a minimal separating set:

• If $(i, j, k) \in \mathcal{T}(n)$ is a triplet such that $a_k | (a_i \vee a_j), a_i | (a_k \vee a_j)$ and $a_j | (a_i \vee a_k)$, we remove T_{ijk} , T_{jki} and T_{ikj} .

- If $(i, j, k) \in \mathcal{T}(n)$ is a triplet such that a_k divides $a_i \vee a_j$, we keep T_{ijk} but remove T_{jki} and T_{ikj} .
- If $(i, j, k, l) \in \mathcal{Q}(n)$ is such that $(a_i \wedge a_j \text{ divides } a_k \vee a_l)$ or $(a_k \wedge a_l \text{ divides } a_i \vee a_j)$, we remove Q_{iikl} .

Proof. Again we try to remove a polynomial and determine if there exists two non separated orbits. Recall that we need points in the real trace, that is points verifying $v_i = \overline{v}_i$ for all i. For the polynomials of type P we refer to section 3.

• Assume that we remove T_{jki} and T_{ikj} for some $(i, j, k) \in \mathcal{T}(n)$. By lemma 5.4, $T_{ijk}(u) = T_{ijk}(v)$ ensures

that $\begin{cases} W_{IK}^{\delta} \neq \emptyset \\ W_{JK}^{\delta} \neq \emptyset \end{cases}$ for some $\delta = \pm 1$. Then, if a_k divides $a_i \lor a_j$, it results directly by Proposition 2.5 that $W_{I,IK}^{\delta} \neq \emptyset$. This is u and v belong to the same orbit.

On the opposite, suppose that we remove the polynomial T_{ijk} altough a_i does not divides $a_k \vee a_j$ and a_j does not divides $a_k \vee a_i$. We choose u and v as in the following table.

	i	-i	j	-j	k	-k
u	1	1	1	1	$\exp\left(-\mathfrak{i}a_k\pi\left(\frac{1}{a_i}+\frac{1}{a_j}\right)\right)$	$\exp\left(\mathfrak{i}a_k\pi\left(\frac{1}{a_i}+\frac{1}{a_j}\right)\right)$
v	1	1	1	1	$\exp\left(\mathfrak{i}a_k\pi\left(\frac{1}{a_i}-\frac{1}{a_j}\right)\right)$	$\exp\left(\mathfrak{i}a_k\pi\left(\frac{1}{a_j}-\frac{1}{a_i}\right)\right)$

These choices clearly provide $c_i = c_i^- = c_j = c_j^- = 1$. We also compute $c_k =$ $\exp\left(\frac{2i\pi a_k}{a_i}\right) \text{ and } c_k^- = \exp\left(\frac{2ia_k\pi}{a_j}\right). \text{ Note for instance that that } c_k^{\frac{a_j\vee a_k}{a_k}}c_j^{\frac{a_j\vee a_k}{a_j}} = \exp\left(\frac{2i\pi a_k}{a_i}\frac{a_j\vee a_k}{a_k}\right) = \exp\left(2i\pi\frac{a_j\vee a_k}{a_i}\right) \neq 1. \text{ Lemma 2.3 provides by that way the in$ tersections described in the right figure. We deduce that polynomials of type P agree on u and v. So do T_{jki} and T_{ikj} . All the others polynomials in $\mathcal{F}(\mathbb{R})$ vanish. Altough, *u* and *v* are not in the same orbit. • Assume that we remove Q_{ijkl} for some $(i, j, k, l) \in \mathcal{Q}(n)$ such that $a_i \wedge a_j$ divides $a_k \vee a_l$. Take *u* and *v*

such that $\begin{cases} W_{IJ}^{\delta} \neq \emptyset \\ W_{IJ}^{-\delta} = \emptyset \end{cases}$ for some $\delta = \pm 1$. By Lemma 5.4, polynomials of type T ensure that $W_{IJ}^{\delta} \cap W_K^{\delta} \neq \emptyset$ and $W_{IJ}^{\delta} \cap W_{L}^{\delta} \neq \emptyset$. However, the whell W_{IJ}^{δ} is of cardinality $a_i \wedge a_j$. Then, the criterion of Proposition 2.6 gives $W_{KL}^{\delta} \neq \emptyset$, and u and v are in the same orbit.

On the opposite, assume that $a_i \wedge a_j$ does not divides $a_k \vee a_l$ and $a_k \wedge a_l$ does not divides $a_i \vee a_j$. We choose u and v as in the following table.

	i	-i	j			-j			k	-k		l		-l		
u	1	1	exp ($\left(-\mathfrak{i}rac{a_j\pi}{a_k\wedge a_l} ight)$		$\exp\left(-\frac{1}{2}\right)$	$\left(\mathfrak{i}rac{a_j\pi}{a_k\wedge a_l} ight)$)	1	1	$\exp\left(-\frac{1}{2}\right)$	$\left(-\mathfrak{i}rac{a_l\pi}{a_i\wedge a_j} ight)$	exp	$\left(\mathfrak{i}\frac{a_l\pi}{a_i\wedge a_j}\right)$		
v	1	1	exp ($\left(-\mathfrak{i}rac{a_j\pi}{a_k\wedge a_l} ight)$		$\exp\left(-\frac{1}{2}\right)$	$\left(\mathfrak{i}rac{a_j\pi}{a_k\wedge a_l} ight)$)	1	1	\exp	$\left(\mathfrak{i}\frac{a_l\pi}{a_i\wedge a_j}\right)$	$\exp\left(-\frac{1}{2}\right)$	$\left(-\mathfrak{i}\frac{a_l\pi}{a_i\wedge a_j}\right)$		

These choices clearly provide $c_i = c_i^- = c_j = c_k = c_k^- = c_l^- = 1$. We find also $c_j^- = c_j^- = c_$ $\exp\left(\frac{2i\pi a_j}{a_k \wedge a_l}\right) \text{ and } c_l = \exp\left(\frac{2i\pi a_l}{a_i \wedge a_j}\right). \text{ Note for instance that } \left(c_i^-\right)^{\frac{a_i \vee a_j}{a_i}} \left(c_i^-\right)^{\frac{a_i \vee a_j}{a_j}} = \exp\left(\frac{2i\pi a_j}{a_k \wedge a_l}\frac{a_i \vee a_j}{a_j}\right) = \exp\left(\frac{2i\pi a_i \vee a_j}{a_k \wedge a_l}\right) \neq 1. \text{ Lemma 2.3 provides by that way the}$ intersections described in the right figure. We deduce that polynomials of type P and T agree on u and v. So do Q_{ikjl} and Q_{iljk} . All the others polynomials in $\mathcal{F}(\mathbb{R})$ vanish. Altough, u and v are not in the same orbit.



K

• Assume that we remove D_{ii} for some $1 \leq i \leq q$. We choose then $d_i = 1$ but $d'_i = 2$. Then all the polynomials in $\mathcal{F}(\mathbb{R})$ vanish. Altough, u and v are not in the same orbit.

• Assume that we remove D_{ij} for some $1 \le i < j \le q$. We choose then $d_i = d'_i = d_j = 1$ but $d'_j = -1$. Then $D_{ii}(u) = D_{ii}(v) = D_{jj}(u) = D_{jj}(v) = 1$ while all the others polynomials in $\mathcal{F}(\mathbb{R})$ vanish. Altough, uand v are not in the same orbit.

• Assume that we remove S_{ijk} for some $1 \le i < j \le r$ and $1 \le k \le q$. We choose then $d_k = 1, d'_k = -1$, $(u_i, u_{-i}) = (v_i, v_{-i}) = (1, 1)$ and $(u_j, u_{-j}) = (v_j, v_{-j}) = (\exp(i\sqrt{2}), \exp(-i\sqrt{2}))$. Here W_{IJ} is not empty because it contains at least 1, while W_{IJ}^- is empty because $\sqrt{2}$ is not rational. Then P_{ii}, P_{ij} and P_{jj} agree on u and v. All the other polynomials in $\mathcal{F}(\mathbb{R})$ vanish on u and v. Altough, $W_{IJ}^{-} = \emptyset$, thus u and v are not in the same orbit.

Remark 5.7. The obtained minimal separating set thus has a cardinality bounded by

$$n^{2} \sim \underbrace{\frac{n(n+1)}{2}}_{P_{ij}} + \underbrace{\frac{q(q+1)}{2}}_{D_{ij}} + \underbrace{q\binom{n}{2}}_{S_{ijk}} \leq \#\mathcal{F}(\mathbb{R}) \leq \underbrace{\frac{n(n+1)}{2}}_{P_{ij}} + \underbrace{3\binom{n}{3}}_{T_{ijk}} + \underbrace{3\binom{n}{4}}_{Q_{ijkl}} + \underbrace{\frac{q(q+1)}{2}}_{D_{ij}} + \underbrace{q\binom{n}{2}}_{S_{ijk}} \sim n^{4}$$

The lower bound is reached when all the integers a_i are equal to 1.

Remark 5.8. When $a_1 = 1$ for any $1 \le i \le n$ and q = 0, the representation of $O_2(\mathbb{R})$ on \mathcal{V} is isomorphic to the representation on $2 \times n$ matrices $\mathcal{M}_{2,n}(\mathbb{R})$. All the polynomials of type T and Q are removed. Only the polynomials P_{ij} for $1 \le i \le j \le n$ remain, and they are the sacalar product between the i^{th} and j^{th} columns. Here again, the separating set $\mathcal{F}(\mathbb{R})$ consist of the well known Weyl invariants [Wey46, Theorem 2.9.A].

5.3 Comparison to a generating set

It is relevant to compare the obtained separating set with a generating set. A set generating the invariant algebra $\mathbb{C}[\hat{\mathcal{V}}]^{O_2(\mathbb{C})}$ is presented in [Des+23]. It provides polynomials which are real on the real trace, such that the generating set obtained generates both $\mathbb{C}[\mathcal{V}]^{O_2(\mathbb{C})}$ and $\mathbb{R}[\mathcal{V}]^{O_2(\mathbb{R})}$ (recall that since $SO_2(\mathbb{C})$ is reductive, $\mathbb{C}[\hat{\mathcal{V}}]^{O_2(\mathbb{C})} = \mathbb{R}[\mathcal{V}]^{O_2(\mathbb{R})} \otimes_{\mathbb{R}} \mathbb{C})$. Consider the action of $O_2(\mathbb{C})$ on $\mathcal{V} = \mathcal{V}_0^p \oplus \mathcal{V}_{-1}^q \oplus \bigoplus_{i=1}^n \mathcal{V}_{a_i}$ with coordinates $(t_1, ..., t_p, d_1, ..., d_q, v_1, v_{-1}, ..., v_n, v_{-n})$. We note $Z := \{y_m y_{-m}, m \leq r\}$ the set of irreducible invariant monomials that are real.

Theorem 5.9. [Des+23, Theorem 5.5] The set of polynomials

$$B = \left\{ \begin{array}{ll} T_i = t_i, \quad D_{ij} = d_i d_j, \quad R_m = y_m y_{-m}, \quad R_e = \Re(\mathfrak{m}_e), \quad I_{ef} = \Im(\mathfrak{m}_e)\Im(\mathfrak{m}_f), \quad \mathcal{S}_{ie} = d_i \Im(\mathfrak{m}_e) \end{array} \right\}$$

where $\mathfrak{m}_e, \mathfrak{m}_f$ are chosen such that neither $\mathfrak{m}_e \mathfrak{m}_f$ nor $\mathfrak{m}_e \overline{\mathfrak{m}_f}$ contains a real monomial $y_m y_{-m} \in Z$, is a generating set for the action of $O_2(\mathbb{C})$ on \mathcal{V} .

The set given by Theorem 5.9 is not minimal for inclusion. It can be significatively trimmed by a complementary algorithm explained in [Des+23, Section 6]. This algorithm relies on the fact that, thanks to Hilbert series, we know in advance the dimension of the linear space of invariants for a given multi degree. Most of polynomials among I_{ef} can in fact be eliminated this way. Nevertheless, this task has heavy cost. As in Section 3 the generating set is built from monomials of any support in [1, n], and the cardinality grows like 2^n . While, the separating set is built from irreducible monomials with support of size at most 4, thus the cardinality is dominated by $\binom{n}{4} \sim n^4$. Furthermore, in practice, most of the polynomials of type Q_{ijkl} are removed (see Example 5.10). We have implemented the algorithm with Maple to make the effective comparison:

Example 5.10. Consider the actions of $O_2(\mathbb{R})$ on $\mathcal{V} = \mathcal{V}_{-1}^3 \oplus \mathcal{V}_2 \oplus \mathcal{V}_3 \oplus \mathcal{V}_5 \oplus \mathcal{V}_7$ endowed with coordinates $(d_1, ..., d_3, v_1, v_{-1}, ..., v_4, v_{-4})$. Algorithm 1.4.5 in [Stu08] provides a set of cardinality $\#\mathcal{M} = 64$ complex irreducible monomials which are invariant for the action of $SO_2(\mathbb{C})$. Among them are the four monomials $Z := \{v_1v_{-1}, v_2v_{-2}, v_3v_{-3}, v_4v_{-4}\}$ and 60 monomials $\mathfrak{m}_e \in \mathcal{M} \setminus Z$ with $\mathfrak{m}_e \neq \overline{\mathfrak{m}_e}$. They induce 3 polynomials of type I_{ef} . We obtain then a generating set \mathcal{G} of cardinality 6 + 4 + 30 + 3 * 30 + 3 = 133 for the action of $O_2(\mathbb{C})$:

$$\mathcal{G} = \begin{cases} \begin{array}{ccccc} d_1^2 & d_1 d_2 & d_1 d_3 & d_2^2 & d_2 d_3 & d_3^2 \\ & v_1 v_{-1} & v_2 v_{-2} & v_3 v_{-3} & v_4 v_{-4} \\ & \mathfrak{m}_e + \overline{\mathfrak{m}_e}, & \mathfrak{m}_e \in \mathcal{M} \setminus Z & d_i \left(\mathfrak{m}_e - \overline{\mathfrak{m}_e}\right), & 1 \leq i \leq 3 \text{ and } \mathfrak{m}_e \in \mathcal{M} \setminus Z \\ & \left(-v_{-2}^2 v_1^3 + v_{-1}^3 v_2^2\right) \left(-v_{-4}^5 v_3^7 + v_{-3}^7 v_4^5\right) & \left(-v_{-3}^2 v_1^5 + v_{-1}^5 v_3^2\right) \left(-v_{-4}^3 v_2^7 + v_{-2}^7 v_4^3\right) \\ & \left(-v_{-3}^2 v_2^5 + v_{-2}^5 v_3^3\right) \left(-v_{-4}^2 v_1^7 + v_{-1}^7 v_4^2\right) \end{cases}$$

The elimination algorithm [Des+23, Section 6], altough heavy, cannot remove more than the three last polynomials. These are in fact the polynomials of type Q_{ijkl} and according to Proposition 5.6, we can remove them. Theorem 5.1 provides then a separating set of cardinality 46:

In some circumstances, one assumes that the coordinate d_1 does not vanish. For instance, when we study the restriction of a representation of $SO_3(\mathbb{R})$ via a Seshadri slice [HJ24]. In that situation the separating set is drastically simplified:

Corollary 5.11. Consider the representation of $SO_2(\mathbb{R})$ on $\mathcal{V}^* := \mathcal{V}_{-1}^* \oplus \bigoplus_{i=2}^q \mathcal{V}_{-1} \oplus \bigoplus_{i=1}^n \mathcal{V}_{a_i}$, where $\mathcal{V}^* = \mathcal{V}_{-1} \setminus \{0\}$. Then we have the following separating set of cardinality $q + n^2$:

$$\mathcal{F}^* = \left\{ \begin{array}{rrr} P_{ij} &=& \frac{1}{2}(p_{-ij} + p_{-ji}) & 1 \le i \le j \le n \\ D_{1j} &=& d_1 d_j, & 1 \le j \le q \\ S_{ij1} &=& \mathfrak{i} \left(p_{-ij} - p_{-ji} \right) d_1, & 1 \le i < j \le n \end{array} \right\}$$

Proof. Consider $u = (d_1, ..., d_q, u_1, u_{-1}, ..., u_n, u_{-n})$ and $v = (d'_1, ..., d'_q, v_1, v_{-1}, ..., v_n, v_{-n})$ two points in \mathcal{V}^* where polynomials of \mathcal{F}^* agree. Since $d'_1 \neq 0$ we can fix $\delta = \frac{d_1}{d'_1} = \pm 1$. Then, $\forall \ 2 \leq j \leq q$, $D_{1j}(u) = D_{1j}(v) \Rightarrow \frac{d_j}{d'_j} = \delta$.

Furthermore, for all $1 \leq i \leq j \leq n$, $P_{ij}(u) = P_{ij}(v)$ ensures that $W_{IJ} \neq \emptyset$ or $W_{IJ}^- \neq \emptyset$. Then, $S_{ij1}(u) = S_{ij1}(v) \Rightarrow W_{IJ}^{\delta} \neq \emptyset$. Corollary 2.5 claims that there exists some $z \in \bigcap_{i=1}^{n} W_{IJ}^{\delta}$. This complex verifies $\rho(g_z^{\delta})(u) = v$.

6 Separating invariants for $O_2(\mathbb{C})$

In this section we give a polynomial separating set for an arbitrary representation of $O_2(\mathbb{C})$ (Theorem 6.1). As for $SO_2(\mathbb{R})$ we delete redundant polynomials to get a minimal separating set in Proposition 6.6.

We consider the representation of $O_2(\mathbb{C})$ on

$$\hat{\mathcal{V}} = \bigoplus_{i=1}^{q} \hat{\mathcal{V}}_{-1} \oplus \bigoplus_{i=1}^{n} \hat{\mathcal{V}}_{a_i}$$

where $a_1, ..., a_n \in \mathbb{N} \setminus \{0\}$. The great difficulty over \mathbb{C} is the degenerated coordinates: it is possible to have, for some $1 \leq i \leq n$, $v_i = 0$ while $v_{-i} \neq 0$. It implies many disjoint cases in the proofs. It requires also to add some polynomials of type H_{ijk} in the separating set:

Theorem 6.1. The following set of polynomials separates closed orbits with respect to the action $O_2(\mathbb{C}) \curvearrowright \hat{\mathcal{V}}$:

$$\mathcal{F} = \begin{cases} P_{ij} = p_{-ij} + p_{-ji} & 1 \le i \le j \le n \\ H_{ijk} = n_{ij-k} + n_{-i-jk} & (i, j, k) \in \mathcal{T}(n) \\ T_{ijk} = (p_{-ik} - p_{-ki})(p_{-jk} - p_{-kj}), & (i, j, k) \in \mathcal{T}(n) \\ Q_{ijkl} = (p_{-ij} - p_{-ji})(p_{-kl} - p_{-lk}), & (i, j, k, l) \in \mathcal{Q}(n) \\ D_{ij} = d_i d_j, & 1 \le i \le j \le q \\ S_{ijk} = \mathfrak{i} (p_{-ij} - p_{-ji}) d_k, & 1 \le i < j \le n \text{ and } 1 \le k \le q \end{cases}$$

To prove it, we take $u = (d_1, ..., d_q, u_1, u_{-1}, ..., u_n, u_{-n})$ and $v = (d'_1, ..., d'_q, v_1, v_{-1}, ..., v_n, v_{-n})$ in \mathcal{C} such that for any $P \in \mathcal{F}$, P(u) = P(v) and exhibit some $g \in O_2(\mathbb{C})$ verifying $\rho(g)(u) = v$. We first notice some facts about degenerated indices. Take *i* such that u_i or u_{-i} vanish. Then $P_{ii}(u) = P_{ii}(v) = 0$ ensures that v_i or v_{-i} vanish as well. Moreover, assume that we have $u_i \neq 0$ while $u_{-i} = 0$. By Lemma 3.3, there exists some $1 \leq j \leq n$ such that $u_{-j} \neq 0$. Then $P_{ij}(u) = P_{ij}(v) \neq 0$ and we necessarily have $v_i \neq 0$ or $v_j \neq 0$. The pairs (u_i, u_{-i}) and (v_i, v_{-i}) have has many vanishing components. There is a common $\delta = \pm 1$ such that for any degenerated indice $i, u_i = 0 \Leftrightarrow v_{\delta \times i} = 0$. And then, $W_i^{\delta} \neq \emptyset$ while $W_i^{-\delta} = \emptyset$.

The sequence of lemmas in Section 5 holds with non degenerated indices over \mathbb{C} with the same proofs. We thus prove similar statements when some involved coordinates vanish:

Vanishing coordinates	Defined quotient	$W_I = W_i \cap W_{-i}$	$W_I^- = W_i^- \cap W_{-i}^-$
$u_i and v_i$	c_{-i}	W_{-i}	Ø
u_{-i} and v_{-i}	c_i	W_i	Ø
$u_i and v_{-i}$	c_{-i}^{-}	Ø	W^{-i}
u_{-i} and v_i	c_i^-	Ø	W_i^-

Lemma 6.2. For any degenerated indice $1 \le i \le n$, we have one of the rows of the following table:

Proof. Suppose that $u_i = v_i = 0$. Then for any $z \in \mathbb{C}^*$ one has $z^{a_i}u_i = 0 = v_i$ while $z^{-a_i}u_i = 0 \neq v_{-i}$. This is $W_i = \mathbb{C}^*$ and $W_i^- = \emptyset$. Other rows of the table are obtained by similar considerations.

Lemma 6.3. For any integers $1 \le i < j \le n$, we have $W_{IJ} \ne \emptyset$ or $W_{IJ}^- \ne \emptyset$.

Proof. Suppose that $u_i = v_i = 0$. By lemma 5.2, $W_I = W_{-i}$ while $W_J = W_j = W_{-j}$.

$$\begin{aligned} P_{ij}(v) &= P_{ij}(u) \quad \Leftrightarrow \quad p_{-ij}(u) = u_{-i}^{\varepsilon_{ij}} u_j^{\varepsilon_{ji}} = v_{-i}^{\varepsilon_{ij}} v_j^{\varepsilon_{ji}} = p_{-ij}(v) \\ & \Leftrightarrow \quad c_{-i}^{\varepsilon_{ij}} = c_j^{\varepsilon_{ji}} \end{aligned}$$

Then lemma 2.3 claims that $W_{-ij} \neq 0$, and lemma 5.2 completes in $W_{IJ} \neq \emptyset$. By similar computations, we can fill the following table:

Vanishing coordinates	δ	Non empty intersection	Vanishing coordinates	δ	Non empty intersection
u_i, v_i	+	W_{IJ}	u_i, v_{-i}	-	W_{IJ}^{-}
u_{-i}, v_{-i}	+	W _{IJ}	u_{-i}, v_i	-	W_{IJ}^{-}
u_i, v_i, u_{-j}, v_{-j}	+	W_{IJ}	u_i, v_{-i}, u_{-j}, v_j	-	W_{IJ}^{-}
u_{-i}, v_{-i}, u_j, v_j	+	W _{IJ}	u_{-i}, v_i, u_j, v_{-j}	-	W_{IJ}^{-}
u_i, v_i, u_j, v_{-j}	+	Unknown	u_i, v_{-i}, u_j, v_{-j}	-	Unknown
$u_{-i}, v_{-i}, u_{-j}, v_{-j}$	+	Unknown	u_{-i}, v_i, u_{-j}, v_j	-	Unknown

The unknown cases of the table need the polynomials of the type H_{ijk} to be solved. Assume that $u_i = u_j = v_i = v_j = 0$. Since $u \in C \setminus \{0\}$, lemma 3.3 ensures that there exists $1 \le k \le n$ with $u_k \ne 0$. The known cases of the table ensure that W_{IK} and W_{JK} are not empty. Then,

$$\begin{split} H_{ijk}(v) &= H_{ijk}(u) \quad \Leftrightarrow \quad u_{-i}^{q \, \varepsilon_{ijk}} u_{-j}^{-r \, \varepsilon_{jik}} u_{k}^{\left(q' \, \varepsilon_{ijk} - r' \, \varepsilon_{jik}\right)} = v_{-i}^{q \, \varepsilon_{ijk}} v_{-j}^{-r \, \varepsilon_{jik}} v_{k}^{\left(q' \, \varepsilon_{ijk} - r' \, \varepsilon_{jik}\right)} \\ & \Leftrightarrow \quad \left(c_{-i}^{q} c_{k}^{q'}\right)^{\varepsilon_{ijk}} = \left(c_{-i}^{r} c_{k}^{r'}\right)^{\varepsilon_{jik}} \end{split}$$

and Lemma 2.3 ensures that $W_{IJK} \neq \emptyset$. By inclusion W_{IJ} is not empty. The other unknown rows of the table are solved by similar considerations.

Lemma 6.4. Let $(i, j, k) \in \mathcal{T}(n)$ be some triple. Then, one has $\begin{cases} W_{IK} \neq \emptyset \\ W_{JK} \neq \emptyset \end{cases}$ or $\begin{cases} W_{IK}^- \neq \emptyset \\ W_{JK}^- \neq \emptyset \end{cases}$.

Proof. If $p_{-ij}(u) \neq 0$ or $p_{-ji}(u) \neq 0$ and $p_{-jk}(u) \neq 0$ or $p_{-kj}(u) \neq 0$, we refer to the proof of Lemma 5.4.

Suppose that $p_{-ik}(u) = p_{-ki}(u) = 0$ while the indice j is not degenerated. Then, $u_i = u_k = 0$ or $u_{-i} = u_{-k} = 0$. In the first case, since $u \in \mathcal{C} \setminus \{0\}$, we can find some $1 \le t \le n$ such that $u_{-t} \ne 0$ and $p_{-ti}(u) \ne 0$. In the second case we can find some $1 \le t \le n$ such that $u_t \ne 0$ and $p_{-it}(u) \ne 0$. Anyway then

$$T_{ijt}(u) = T_{ijt}(v) \Rightarrow \begin{cases} W_{IT} \neq \emptyset \\ W_{JT} \neq \emptyset \end{cases} \quad or \begin{cases} W_{IT}^- \neq \emptyset \\ W_{JT}^- \neq \emptyset \end{cases}$$

However, Lemma 6.2 ensures that $W_I^{\delta} \neq \emptyset$ while $W_I^{-\delta} = \emptyset$. It follows by Lemma 6.3 that $\begin{cases} W_{IT}^{\delta} \neq \emptyset \\ W_{JT}^{\delta} \neq \emptyset \end{cases}$. We deduce that $\begin{cases} W_{IK}^{\delta} \neq \emptyset \\ W_{KI}^{\delta} \neq \emptyset \end{cases}$.

Else, suppose that $p_{-ij}(u) = p_{-ji}(u) = p_{-kj}(u) = p_{-jk}(u) = 0$. Here each pair (i,j) and (k,j) has a degenerated indice. Then Lemma 6.3 concludes that $\begin{cases} W_{IJ}^{\delta} \neq \emptyset \\ W_{KJ}^{\delta} \neq \emptyset \end{cases}$ and the lemma holds.

Lemma 6.5. Let $(i, j, k, l) \in \mathcal{Q}(n)$. Then one has $\begin{cases} W_{IJ} \neq \emptyset \\ W_{KL} \neq \emptyset \end{cases}$ or $\begin{cases} W_{IJ}^- \neq \emptyset \\ W_{KL}^- \neq \emptyset \end{cases}$.

Proof. If $p_{-ii}(u) \neq 0$ or $p_{-ii}(u) \neq 0$ and $p_{-kl}(u) \neq 0$ or $p_{-lk}(u) \neq 0$, we refer to the real proof of Lemma 5.5. Suppose that $p_{-ij}(u) = p_{-ji}(u) = 0$ while $p_{-kl}(u) \neq 0$ or $p_{-lk}(u) \neq 0$. That is, $u_i = u_j = 0$ or $u_{-i} = u_{-j} = 0$. In the first case, by Lemma 3.3, there exists some $1 \le t \le n$ such that $u_{-t} \ne 0$ and $p_{-ti}(u) \neq 0$. In the second case we can find some $1 \leq t \leq n$ such that $u_t \neq 0$ and $p_{-it}(u) \neq 0$. Anyway then
$$\begin{split} p_{-ti}(u) &= 0. \text{ In the second case we can find some } 1 \leq i \leq n \text{ such that } u_{t} \neq 0 \text{ and } p_{-ti}(u) \neq 0. \text{ In the second case we can find some } 1 \leq i \leq n \text{ such that } u_{t} \neq 0 \text{ and } p_{-ti}(u) \neq 0. \text{ In find, usp} \text{ that } \\ Q_{itkl}(u) &= Q_{itkl}(v) \Rightarrow \begin{cases} W_{IT} \neq \emptyset \\ W_{KL} \neq \emptyset \end{cases} \text{ or } \begin{cases} W_{IT}^{-} \neq \emptyset \\ W_{KL}^{-} \neq \emptyset \end{cases}. \text{ However, Lemma 6.2 ensures that } W_{I}^{\delta} \neq \emptyset \text{ while } \\ W_{I}^{-\delta} &= \emptyset. \text{ It follows by Lemma 6.3 that } \begin{cases} W_{IT}^{\delta} \neq \emptyset \\ W_{KL}^{\delta} \neq \emptyset \end{cases}, \text{ and } \begin{cases} W_{IJ}^{\delta} \neq \emptyset \\ W_{KL}^{\delta} \neq \emptyset \end{cases} \\ W_{KL}^{\delta} \neq \emptyset \text{ Otherwise, } p_{-ij}(u) = p_{-ji}(u) = p_{-kl}(u) = p_{-lk}(u) \neq 0, \text{ that is each pair } (i, j) \text{ and } (k, l) \text{ has a degenerated } \end{cases} \end{split}$$

indice. Lemma 6.3 implies that $\begin{cases} W_{IJ}^{\delta} \neq \emptyset \\ W_{KL}^{\delta} \neq \emptyset \end{cases}$ and the lemma holds.

Once we have Lemmas 6.4 and 6.5, it is possible to conclude the proof of Theorem 6.1 as the real analogue in Section 5.

In general, the separating set of Theorem 6.1 is not minimal for the inclusion. We remove redundant polynomials to get a minimal separating set:

Proposition 6.6. In addition to those of Proposition 5.6, we make the following removals: • For any $(i, j, k) \in \mathcal{T}(n)$ such that a_k divides $a_i \vee a_j$, we remove H_{ijk} . Then the separating set \mathcal{F} is minimal for the inclusion.

Proof. We try to remove a polynomial and find two non separated closed orbits. For the polynomials of type P, T, Q, D and S we refer to section 5.

Assume that we remove H_{ijk} for some $(i, j, k) \in \mathcal{T}(n)$. We take u and v satisfying one of the four unknown cases of Lemma 6.3 (otherwise, polynomials of type P, T, Q, D and S suffice to determine if u and v are in te same orbit). This is:

$$\left\{ \begin{array}{l} W_{I}^{\delta} \neq \emptyset \\ W_{J}^{\delta} \neq \emptyset \end{array} \right. \text{ and } \left\{ \begin{array}{l} W_{I}^{-\delta} = \emptyset \\ W_{J}^{-\delta} = \emptyset \end{array} \right.$$

If there exists another integer $l \neq k$ such that $P_{il}(u) \neq 0$, then by Lemma 6.3, $W_{IJ}^{\delta} \neq \emptyset$ and u and v are in the same orbit. Otherwise, by Lemma 3.3, k is the only integer such that P_{ik} and P_{jk} do not vanish at u and v. Then, by Lemma 6.3 we have $\begin{cases} W_{IK}^{\delta} \neq \emptyset \\ W_{JK}^{\delta} \neq \emptyset \end{cases}$. If a_k divides $a_i \lor a_j$, Proposition 2.5 claims directly that $W_{II}^{\delta} \neq \emptyset$ and u and v lies in the same orbit.

On the opposite, if a_k does not divides $a_i \vee a_j$, we choose u and v as in the following table:

	i	-i	j	-j	k	-k
u	1	0	1	0	1	1
v	1	0	$\exp\left(\frac{2i\pi a_j}{a_k}\right)$	0	1	1

These choices imply first that $W_I^- = W_J^- = \emptyset$. We next note $c_i = c_k = 1$ while $c_j = \exp\left(\frac{2i\pi a_j}{a_k}\right)$. Then, $c_i^{\frac{a_i \vee a_j}{a_i}} c_j^{\frac{a_i \vee a_j}{a_j}} = \exp\left(\frac{2i\pi a_j}{a_k}\frac{a_i \vee a_j}{a_j}\right) = \exp\left(2i\pi\frac{a_i \vee a_j}{a_k}\right) \neq 1$. Lemma 2.3 provides by that way the intersections described in the right figure. We deduce that P_{ik} and P_{jk} agree at u and v while all the other polynomials in \mathcal{F} vanish. Altough, u and v are not in the same orbit.



Remark 6.7. The obtained minimal separating set thus has cardinality bounded by

$$n^{2} \sim \underbrace{\frac{n(n+1)}{2}}_{P_{ij}} + \underbrace{\frac{q(q+1)}{2}}_{D_{ij}} + \underbrace{\frac{q\binom{n}{2}}{2}}_{S_{ijk}} \leq \#\mathcal{F}(\mathbb{R}) \leq \underbrace{\frac{n(n+1)}{2}}_{P_{ij}} + \underbrace{3\binom{n}{3}}_{H_{ijk}} + \underbrace{3\binom{n}{3}}_{T_{ijk}} + \underbrace{3\binom{n}{4}}_{Q_{ijkl}} + \underbrace{\frac{q(q+1)}{2}}_{D_{ij}} + \underbrace{q\binom{n}{2}}_{S_{ijk}} \sim n^{4}$$

The lower bound is reached when all the integers a_i are equal to 1.

Example 6.8. Let us consider again the representation of $O_2(\mathbb{C})$ on $\hat{\mathcal{V}} := \hat{\mathcal{V}}_{-1}^3 \oplus \hat{\mathcal{V}}_2 \oplus \hat{\mathcal{V}}_3 \oplus \hat{\mathcal{V}}_5 \oplus \hat{\mathcal{V}}_7$. To the real separating set of cardinality 46 introduced in Example 5.10 are added 12 polynomials of type H:

$$\left\{ \begin{array}{cccccccc} H_{2,3,1} & H_{1,2,3} & H_{1,3,2} & H_{2,4,1} & H_{1,2,4} & H_{1,4,2} \\ H_{3,4,1} & H_{1,3,4} & H_{1,4,3} & H_{3,4,2} & H_{2,3,4} & H_{2,4,3} \end{array} \right)$$

We then obtain a separating set for $SO_2(\mathbb{C}) \curvearrowright \hat{\mathcal{V}}$ of cardinality 58 by Theorem 6.1. The difference of cardinality between real and complex separating set still exists but is less remarkable than for the representations of $SO_2(\mathbb{C})$ and $SO_2(\mathbb{R})$ (see Example 4.4).

7 Stratification of the real orbit space

In this section we give a stratification of the orbit space through the real separating set of Sections 4 and 5. From the evaluation of the polynomials of $f(\mathbb{R})$ or $\mathcal{F}(\mathbb{R})$ at some point $v \in \mathcal{V}$, we provide inequalities determining the isotropy class of v.

Definition 7.1. Let G be a compact group and ρ a continuous representation on a vector space \mathcal{V} . Take v a point in \mathcal{V} . The isotropy group of v is defined as $G_v = \{g \in G \mid \rho(g)(v) = v\}$. Two points are of same orbit type when their isotropy groups are conjugated. The isotropy stratum Σ_J is the subset of points whose isotropy group is conjugated to J < G:

$$\Sigma_{\mathbf{J}} = \{ v \in V \text{ such that } \mathbf{G}_v \in [\mathbf{J}] \}$$

There is a partial order among isotropy classes. Namely, when J_1, J_2 are two isotropy groups, one notes

$$[J_1] < [J_2] \Leftrightarrow \exists K \in [J_1] \text{ such that } K < J_2$$

This induces a partial order among isotropy conjugacy classes, and one defines the isotropy stratum closure which corresponds to the set of points stabilized by at least a member of [J]:

$$\overline{\Sigma_J} = \bigcup_{[J] < [K]} \Sigma_K$$

The possible isotropy classes in $\mathrm{SO}_2(\mathbb{R})$ are $[\{I_2\}]$, $[\mathrm{SO}_2(\mathbb{R})]$ itself and $[\mathrm{C}_k]$ the cyclic groups of order $k \in \mathbb{N} \setminus \{0\}$ (Figure 3). The possible isotropy classes in $\mathrm{O}_2(\mathbb{R})$ are $[\{I_2\}]$, $[\mathrm{SO}_2(\mathbb{R})]$, $[\mathrm{O}_2(\mathbb{R})]$, $[\mathrm{C}_k]$ for $k \in \mathbb{N} \setminus \{0\}$ and $[\mathrm{D}_k]$ the dihedral groups of order $2k \in \mathbb{N}^*$ (Figure 4). The isotropy class $[\mathrm{C}_k]$ has a single representant: the subgroup of $\mathrm{SO}_2(\mathbb{R})$ generated by g_z^+ where z is a k^{th} primitive root. However, the isotropy class $[\mathrm{D}_k]$ has an infinite number of conjugated representants. These are the subgroups of $\mathrm{O}_2(\mathbb{R})$ generated by C_k and a symmetry $g_z^- \in \mathrm{O}_2(\mathbb{R})$.



The decomposition into irreducible components $\mathcal{V} = \bigoplus_{i=1}^{q} \mathcal{V}_{-1} \oplus \bigoplus_{i=1}^{n} \mathcal{V}_{a_i}$ helps to compute the stabilizer of a point. The isotropy group of $v \in \mathcal{V}$ is the intersection of the isotropy groups of its projections onto each representations in the irreducible decomposition [Oli14]. This leads to the following Theorem:

Theorem 7.2. Consider the action of $SO_2(\mathbb{R})$ on \mathcal{V} . Let v be a point in \mathcal{V} .

- For $k \in \mathbb{N} \setminus \{0\}$, $v \in \overline{\Sigma_{C_k}}$ iff for all i such that k does not divides a_i , $\begin{cases} \Re(p_{-ii})(v) = 0 \\ \Im(p_{-ii})(v) = 0 \end{cases}$
- $v \in \overline{\Sigma_{\mathrm{SO}_2(\mathbb{R})}}$ iff for all $i \le n$, $\begin{cases} \Re(p_{-ii})(v) = 0\\ \Im(p_{-ii})(v) = 0 \end{cases}$

Proof. For any $k \in \mathbb{N}^*$, the possible isotropy classes in \mathcal{V}_k are $\mathrm{SO}_2(\mathbb{R})$ and C_k , and the only point of isotropy class $\mathrm{SO}_2(\mathbb{R})$ is (0,0). By intersection then, the isotropy group G_v is $\mathrm{C}_{\varphi(v)}$, where $\varphi(v)$ is the gcd of all a_i such that the projection of v onto \mathcal{V}_{a_m} is not zero, or equivalently $p_{-ii}(v) \neq 0$. If there is no such a_i , then G_v is $\mathrm{SO}_2(\mathbb{R})$.

Theorem 7.3. Consider the action of $O_2(\mathbb{R})$ on \mathcal{V} . Let v be a point in \mathcal{V} .

- For any $k \in \mathbb{N} \setminus \{0\}$, $v \in \overline{\Sigma_{C_k}}$ iff $\forall 1 \le i \le n$ such that $a_i \ne 0$ [k], $P_{ii}(v) = 0$.
- For any $k \in \mathbb{N} \setminus \{0\}$, $v \in \overline{\Sigma_{D_k}}$ iff $\begin{cases} \forall 1 \le i \le n \mid a_i \ne 0 [k], \ P_{ii}(v) = 0. \\ \forall 1 \le i < j \le n, \ \left(P_{ij}^2 4P_{ii}^{\varepsilon_{ij}} P_{jj}^{\varepsilon_{ji}}\right)(v) = 0. \\ \forall 1 \le i \le q, \ D_{ii}(v) = 0. \end{cases}$
- $v \in \overline{\Sigma_{SO_2(\mathbb{R})}}$ iff for all $i \leq n$, $P_{ii}(v) = 0$.
- $v \in \overline{\Sigma_{O_2(\mathbb{R})}}$ iff for all $i \leq n$, $P_{ii}(v) = 0$ and for all $1 \leq i \leq q$, $D_{ii}(v) = 0$.

Proof. We look at the possible isotropy classes of the projection on each irreducible representation:

- For any $k \ge 2$, the possible isotropy classes in \mathcal{V}_k are $O_2(\mathbb{R})$ and D_k , and the only point of isotropy class $O_2(\mathbb{R})$ is (0,0).
- The possible isotropy classes in \mathcal{V}_{-1} are $SO_2(\mathbb{R})$ and $O_2(\mathbb{R})$, and the only point of stabilizer $O_2(\mathbb{R})$ is 0.

We first identify the subset $\operatorname{Stab}(v)^+ = \operatorname{Stab}(v) \cap \operatorname{SO}_2(\mathbb{R})$. As for Theorem 7.3, $\operatorname{Stab}(v)^+ = C_{\varphi(v)}$, where $\varphi(v)$ is the gcd of all a_i such that the projection of v onto \mathcal{V}_{a_i} is not zero, equivalently $P_{ii}(v) \neq 0$. If there is no such a_i , then $\operatorname{Stab}(v)^+ = \operatorname{SO}_2(\mathbb{R})$.

We next determine if there exists a symmetry $g_z^- \in \operatorname{Stab}(v)$. If not, $\operatorname{Stab}(v) = \operatorname{Stab}(v)^+$. If yes, $\operatorname{Stab}(v) = \operatorname{Stab}(v)^+ \rtimes C_2$. There exists $z \in \mathbb{C}^*$ such that $\rho(g_z^-)(v) = v$ iff $\bigcap_{i=1}^n W_I^- \neq \emptyset$ and $\forall 1 \leq i \leq q, \ d_i = 0$. We then check that for all $1 \leq i < j \leq n$,

$$\begin{split} \left(P_{ij}^2 - 4P_{ii}^{\varepsilon_{ij}} P_{jj}^{\varepsilon_{ji}} \right)(v) &= 0 & \Leftrightarrow \quad v_{-i}^{2\varepsilon_{ij}} v_j^{2\varepsilon_{ji}} + 2(v_{-i}v_i)^{\varepsilon_{ij}} (v_{-j}v_j)^{\varepsilon_{ji}} + v_i^{2\varepsilon_{ij}} v_{-j}^{2\varepsilon_{ji}} - 4(v_{-i}v_i)^{\varepsilon_{ij}} (v_{-j}v_j)^{\varepsilon_{ji}} \\ & \Leftrightarrow \quad v_{-i}^{2\varepsilon_{ij}} v_j^{2\varepsilon_{ji}} - 2(v_{-i}v_i)^{\varepsilon_{ij}} (v_{-j}v_j)^{\varepsilon_{ji}} + v_i^{2\varepsilon_{ij}} v_{-j}^{2\varepsilon_{ji}} = 0 \\ & \Leftrightarrow \quad (p_{-ij} - p_{-ji}) (v)^2 = 0 \\ & \Leftrightarrow \quad W_{IJ}^- \neq \emptyset \end{split}$$

Furthermore we have $\forall 1 \leq i \leq q, \ d_i = 0 \Leftrightarrow \forall 1 \leq i \leq q, \ D_{ii}(v) = 0.$

Remark 7.4. Altough the groups C_2 and D_1 are isomorphic, they are not conjugated in $SO_2(\mathbb{R})$. They thus represent two distinct isotropy classes, as enumerated in Theorem 7.3. The corresponding strata form two distinct irreducible varieties in the orbit space.

Example 7.5. Consider the representation of $O_2(\mathbb{R})$ on $S = \mathcal{V}_{-1}^3 \oplus \mathcal{V}_0 \oplus \mathcal{V}_1^3 \oplus \mathcal{V}_2^2 \oplus \mathcal{V}_3$ endowed with the coordinates $(d_1, d_2, d_3, t_1, v_1, v_{-1}, v_2, v_{-2}, v_3, v_{-3}, v_4, v_{-4}, v_5, v_{-5}, v_6, v_{-6})$. This action corresponds to the reduction of the action of $SO_3(\mathbb{R})$ on the space of piezoelectricity tensors Piez thanks to a Sechadri slice [HJ24]. The stratification of the orbit space $S/O_2(\mathbb{R})$ allows to deduce almost everywhere the isotropy group of tensors in Piez. Namely, for any $h \in S$ we have:

$$\begin{array}{l} \bullet h \in \overline{\Sigma_{C_2}} \Leftrightarrow P_{11}(h) = P_{22}(h) = P_{33}(h) = P_{66}(h) = 0. \\ \bullet h \in \overline{\Sigma_{C_3}} \Leftrightarrow P_{11}(h) = P_{22}(h) = P_{33}(h) = P_{44} = P_{55}(h) = 0. \\ \bullet h \in \overline{\Sigma_{D_1}} \Leftrightarrow \left\{ \begin{array}{l} \forall 1 \leq i < j \leq 6, \ \left(P_{ii}^{\varepsilon_{ij}} P_{jj}^{\varepsilon_{ji}} - P_{ij}^2 \right)(v) = 0. \\ D_{11}(h) = D_{22}(h) = D_{33} = (h) = 0 \end{array} \right. \\ \bullet h \in \overline{\Sigma_{D_2}} \Leftrightarrow \left\{ \begin{array}{l} P_{11}(h) = P_{22}(h) = P_{33}(h) = P_{66}(h) = 0 \\ \left(P_{44}P_{55} - P_{45}^2 \right)(v) = 0 \\ D_{11}(h) = D_{22}(h) = D_{33} = (h) = 0 \end{array} \right. \\ \bullet h \in \overline{\Sigma_{D_3}} \Leftrightarrow \left\{ \begin{array}{l} P_{11}(h) = P_{22}(h) = P_{33}(h) = P_{44}P_{55}(h) = 0 \\ D_{11}(h) = D_{22}(h) = D_{33} = (h) = 0 \end{array} \right. \\ \bullet h \in \overline{\Sigma_{SO_2(\mathbb{R})}} \Leftrightarrow P_{11}(h) = P_{22}(h) = P_{33}(h) = P_{44}(h) = P_{55}(h) = P_{66}(h) = 0. \\ \bullet h \in \overline{\Sigma_{O_2(\mathbb{R})}} \Leftrightarrow \left\{ \begin{array}{l} P_{11}(h) = P_{22}(h) = P_{33}(h) = P_{44} = P_{55}(h) = P_{66}(h) = 0. \\ D_{11}(h) = D_{22}(h) = D_{33} = (h) = 0 \end{array} \right. \\ \end{array} \right.$$

A Irreducible representations of SO₂ and O₂

We recall essential properties of representations of SO₂ and O₂. SO₂(\mathbb{C}) is in fact the torus \mathbb{C}^* and there is a semidirect product $O_2(\mathbb{C}) \cong SO_2(\mathbb{C}) \rtimes C_2$. For $z \in \mathbb{C}^*$ we note $g_z^+ = (z, 1) \in SO_2(\mathbb{C})$ and $g_z^- = (z, -1) \in O_2(\mathbb{C})$. As it is abelian, SO₂(\mathbb{C}) has irreducible representations of dimension one. These are gathered pairwise to form the irreducible representations of O₂(\mathbb{C}):

Theorem A.1. The irreducible representations of $SO_2(\mathbb{C})$ consist of (ϕ_j, \mathcal{L}_j) , $j \in \mathbb{Z}$ where $\mathcal{L}_j = \mathbb{C}$ and for $z \in \mathbb{C}^*$, $\phi_j(g_z^+) = z^j$.

Theorem A.2. [GSS88] The irreducible representations of $O_2(\mathbb{C})$ consist of

• $(\rho_i, \hat{\mathcal{V}}_i)$ for $i \in \mathbb{N} \setminus \{0\}$, where $\hat{\mathcal{V}}_i = \mathbb{C}^2$ and for any $z \in \mathbb{C}^*$, $\rho_i(g_z^+) = \begin{pmatrix} z^i & 0 \\ 0 & z^{-i} \end{pmatrix}$ and $\rho_i(g_z^-) = \begin{pmatrix} z^{-i} & 0 \\ 0 & z^{-i} \end{pmatrix}$

 $\begin{pmatrix} 0 & z^{-i} \\ z^i & 0 \end{pmatrix}.$

• The trivial representations $(\rho_0, \hat{\mathcal{V}}_0)$, and the determinant $(\rho_{-1}, \hat{\mathcal{V}}_{-1})$, both of dimension one.

The standard parameterization of $SO_2(\mathbb{R})$ is $\left\{ \begin{pmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{pmatrix}, \theta \in \mathbb{R} \right\}$. The conjugation by $P := \begin{pmatrix} 1 & \mathbf{i} \\ 1 & -\mathbf{i} \end{pmatrix}$ recovers the parameterization

$$O_2(\mathbb{R}) \cong \left\{ g_z^+ = \begin{pmatrix} z & 0\\ 0 & \frac{1}{z} \end{pmatrix}, z \in \mathcal{U} \right\} \cup \left\{ g_z^- = \begin{pmatrix} 0 & \frac{1}{z}\\ z & 0 \end{pmatrix}, z \in \mathcal{U} \right\},$$

where $\mathcal{U} \subset \mathbb{C}$ is the unit circle. We obtain the irreducible representations restricting the complex representations to the real trace:

Theorem A.3. The irreducible representations of $SO_2(\mathbb{R})$ consist of

- (ρ_i, \mathcal{V}_i) , for $i \in \mathbb{N} \setminus \{0\}$.
- The trivial representations (ρ_0, \mathcal{V}_0) .

Theorem A.4. The irreducible representations of $O_2(\mathbb{R})$ are

- (ρ_i, \mathcal{V}_i) , for $i \in \mathbb{N}^*$.
- The trivial representations (ρ_0, \mathcal{V}_0) and the determinant $(\rho_{-1}, \mathcal{V}_{-1})$.

For each *i* we endow $\hat{\mathcal{V}}_i$ with coordinates (v_i, v_{-i}) . On the real trace $\mathcal{V}_i \subset \hat{\mathcal{V}}_i$, the coordinates satisfy $v_i = \overline{v_{-i}}$. Througout the article we ignore the trivial representations. Indeed, to separate the orbits in a representation with an additional trivial part \mathcal{L}_0^k , it suffices to add the linear polynomials $\{t_i, 1 \leq i \leq k\}$.

References

- [BV23] B Blum-Smith and S. Villar. "Machine learning and invariant theory". In: Notices of the American Mathematical Society (2023).
- [Bür+21] P. Bürgisser, M. Doğan, V. Makam, M. Walter, and A. Wigderson. "Polynomial time algorithms in invariant theory for torus actions". In: arXiv preprint arXiv:2102.07727 (2021).
- [DK15] H. Derksen and G. Kemper. Computational invariant theory. 2nd. Springer-Verlag, 2015.
- [Des+23] Boris Desmorat, Marc Olive, Nicolas Auffray, Rodrigue Desmorat, and Boris Kolev. "Computation of minimal covariants bases for 2D coupled constitutive laws". In: International Journal of Engineering Science 191 (2023), p. 103880.
- [Duf09] Emilie Dufresne. "Separating invariants and finite reflection groups". In: Advances in Mathematics 221.6 (2009), pp. 1979–1989.
- [DG24] Nadav Dym and Steven J Gortler. "Low-Dimensional Invariant Embeddings for Universal Geometric Learning". In: Foundations of Computational Mathematics (2024), pp. 1–41.
- [GSS88] M. Golubitsky, I. Stewart, and D. Schaeffer. Singularities and groups in bifurcation theory. Vol. II. Vol. 69. Applied Mathematical Sciences. New York: Springer-Verlag, 1988.
- [HJ24] Evelyne Hubert and Martin Jalard. "Algebraically independent generators for the invariant field of SO 3 (R) and O 3 (R) representations R 3 \oplus H". working paper or preprint. June 2024. URL: https://inria.hal.science/hal-04604969.
- [Kem24] Gregor Kemper. "Invariant Theory: a Third Lease of Life". In: arXiv preprint arXiv:2403.12709 (2024).
- [MFK94] David Mumford, John Fogarty, and Frances Kirwan. *Geometric invariant theory.* Vol. 34. Springer Science & Business Media, 1994.
- [Oli14] M. Olive. "Géométrie des espaces de tenseurs Une approche effective appliquée à la mécanique des milieux continus". PhD thesis. AMU, 2014.
- [Ser66] Jean Pierre Serre. Algebres de Lie semi-simples complexes. New York ; Amsterdam : W. A. Benjamin, 1966.
- [Stu08] Bernd Sturmfels. Algorithms in invariant theory. Springer Science & Business Media, 2008.
- [Wey46] H Weyl. The classical groups: their invariants and representations. Vol. 45. Princeton university press, 1946.