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► To cite this version:

Quentin Bammey, Rafael Grompone von Gioi, Jean-Michel Morel. Positional Learning to reverse-engineer the camera processing pipeline and detect image forgeries. International Conference on Computational Photography, Jul 2024, Lausanne, Switzerland. hal-04654099

HAL Id: hal-04654099

<https://hal.science/hal-04654099v1>

Submitted on 19 Jul 2024

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Positional Learning to reverse-engineer the camera processing pipeline and detect image forgeries

Quentin Bamme¹, Rafael Grompone von Gioi¹, Jean-Michel Morel²

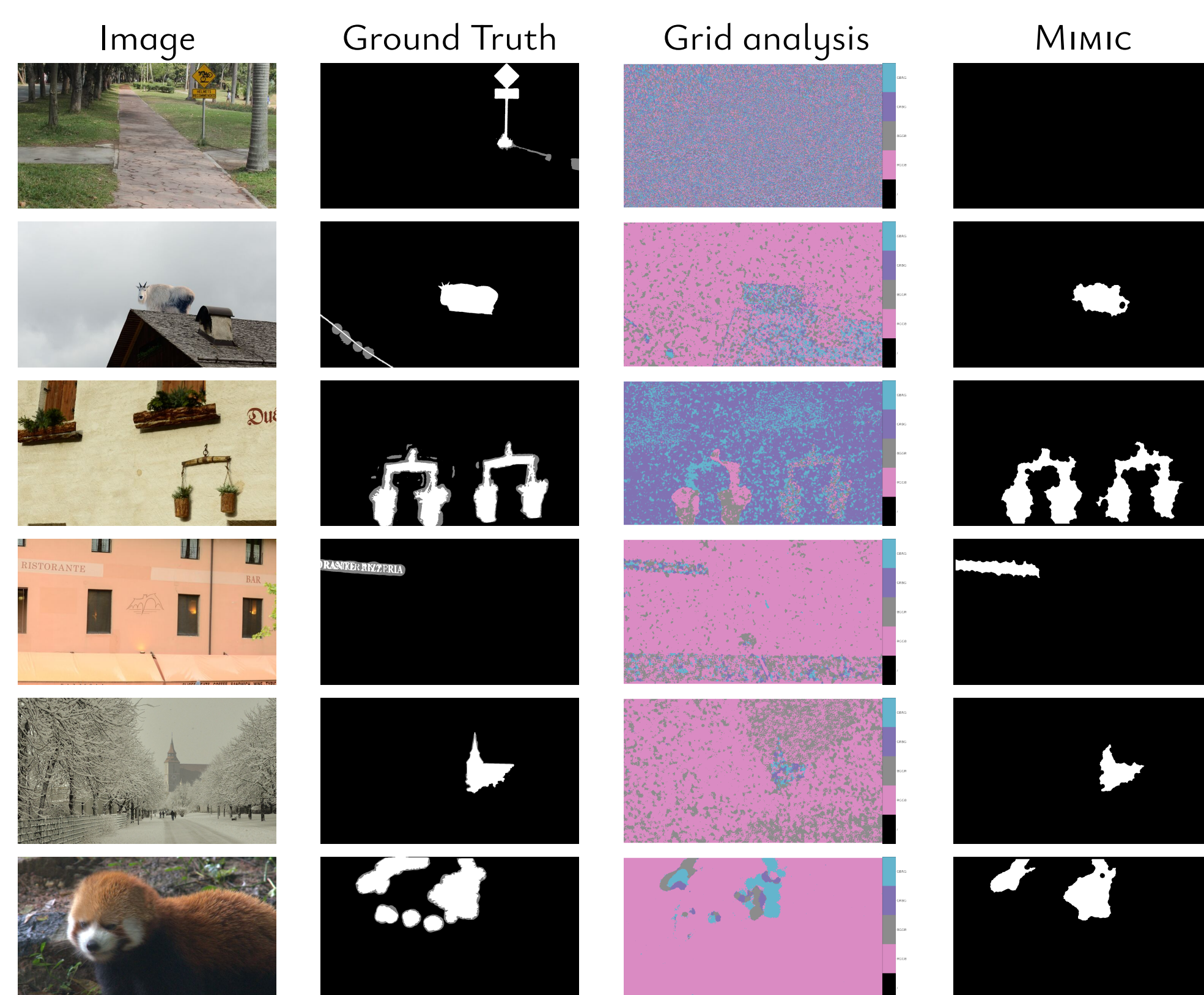
<https://bammey.com/>

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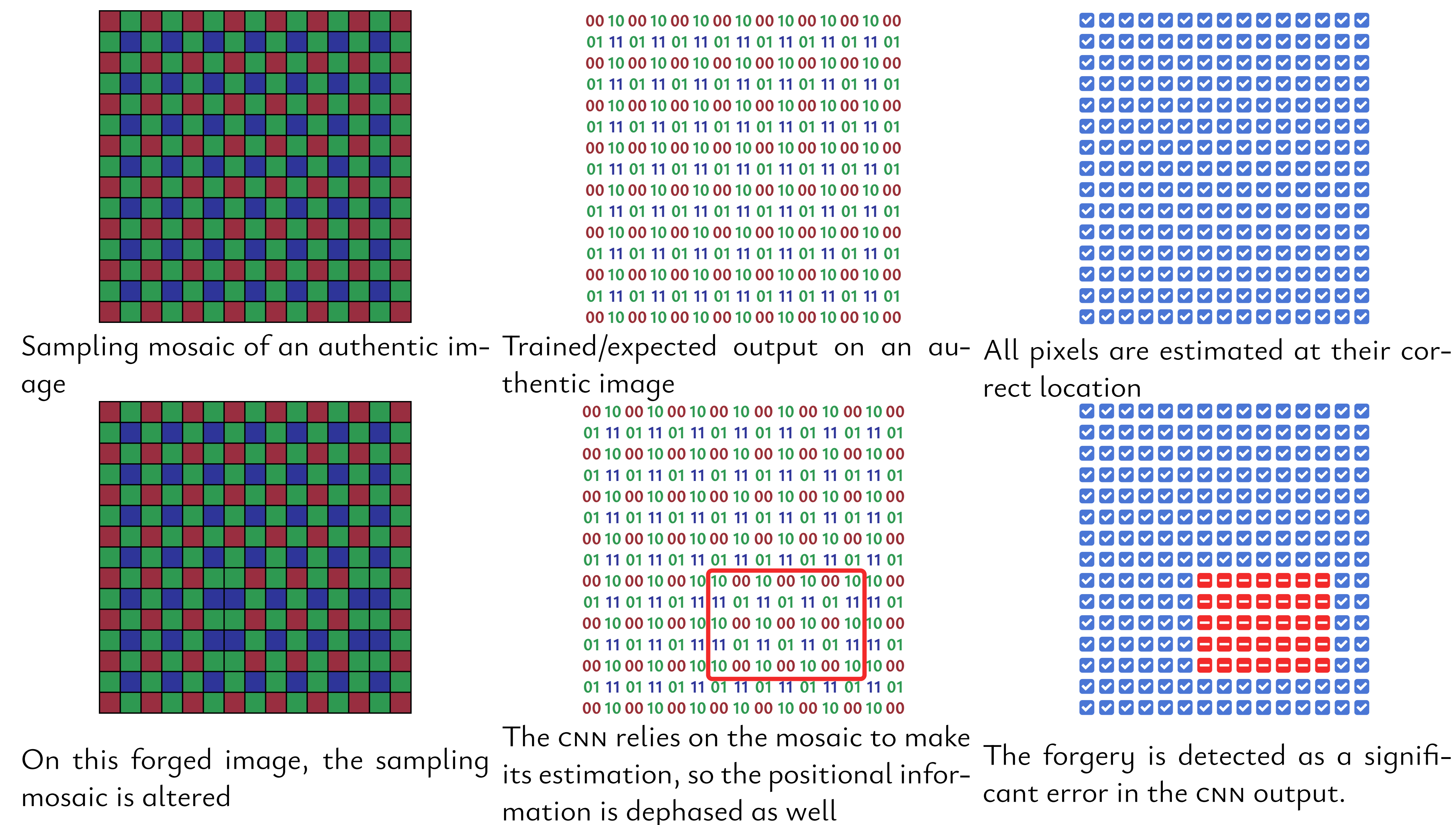
Abstract

As conventional tools and generative-AI-based methods alike can alter images in visually convincing ways, image editing is no longer reserved to experts. However, this ease of manipulation has given rise to malicious manipulation of images, resulting in the creation and dissemination of realistic but fake content to spread **disinformation** online, wrongfully incriminate someone, or commit fraud. The **detection** of such **forgeries** is paramount in exposing those deceitful acts. One approach involves **reverse-engineering** the image signal processing pipeline, to detect and localize inconsistencies. In this context, **positional learning** has emerged as a promising and explainable approach to **reveal underlying traces** of the signal processing pipeline. We show how it can be used to detect forgeries from inconsistencies in the image mosaic or compression history.

Results



Train a CNN to detect the modulo-(2, 2) position of each pixel



- ♦ Train the CNN on authentic images only, to estimate the modulo-(2, 2) position of each pixel.
- ♦ The network will need to learn to rely on **demosaicing artefacts** to extract the **positional information**.
- ♦ At **inference**: image forgeries lead to inconsistencies in the mosaic, which lead to errors in the output.
- ♦ Detect errors in the output to know the image is **forged!**

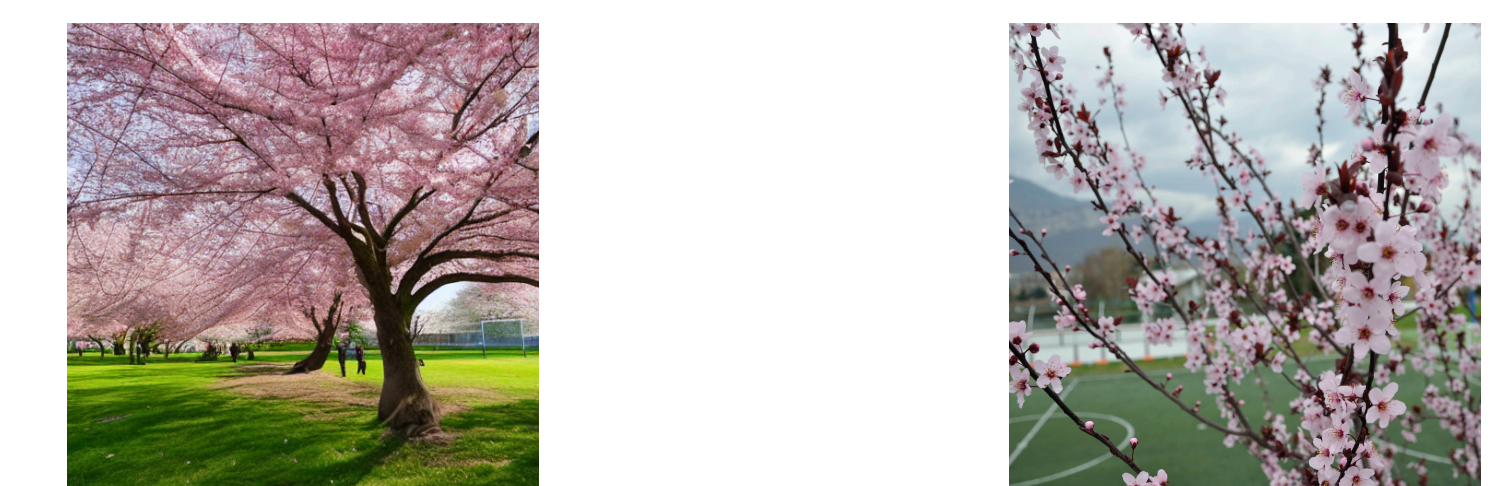
Automatic *a contrario* detection to control the tolerated rate of false positives

- ♦ Globally: ratio p_0 of pixels that have their position incorrectly detected
- ♦ In a given rectangle: k out of n pixels wrongly detected
- ♦ **Is there a forgery in this rectangle?**
- ♦ Threshold on the expected **number of false alarms** to statistically control the tolerated rate of false positives:

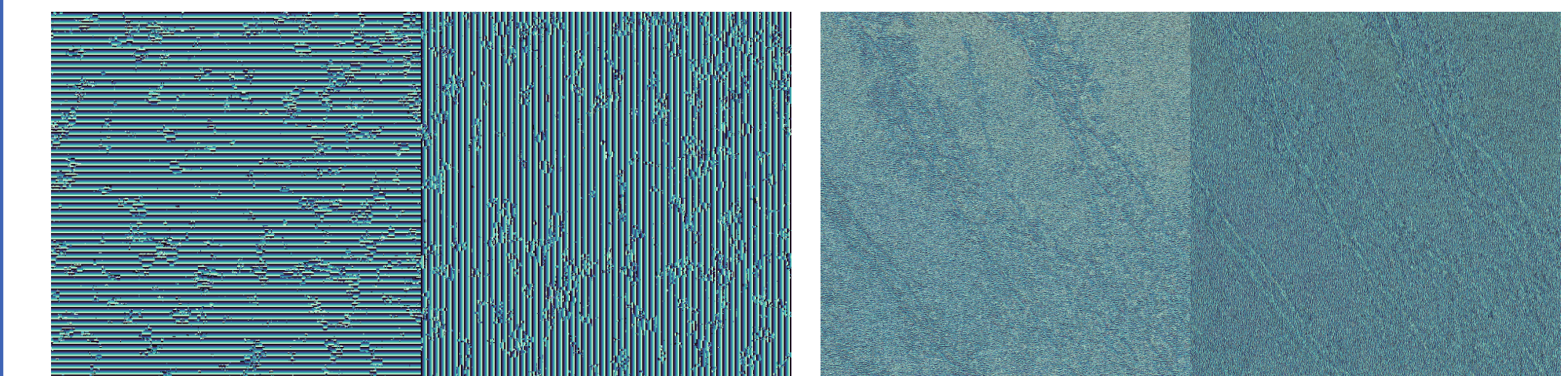
$$NFA = n_{tests} \cdot \mathbb{P}(k_{wrong} \geq k) = 2(X \cdot Y)^2 \sum_{i=k}^n \binom{n}{i} p_0^i (1 - p_0)^{n-i}$$

- ♦ Threshold at $10^{-3} \Rightarrow$ expect one false detection every 1000 images

Positional Learning also helps detect generated images



(a) Stable diffusion image (b) Real image from the Raise dataset



(c) Detected position of each pixel modulo 8, horizontally and vertically, on a Stable Diffusion image

(d) Detected position of each pixel modulo 8, horizontally and vertically, on a natural image from the Raise dataset

References

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Acknowledgements

This work has received funding by the European Union under the Horizon Europe vera.ai project, grant agreement number 101070093, and by the ANR under the APATE project, grant number ANR-22-CE39-0016. Centre Borelli is also a member of Université Paris Cité, SSA and INSERM.



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