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# Evaluation of the acoustic radiation of contrasted orthogonally stiffened plates from homogenized model

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## Abstract

This paper presents a study of the acoustic radiation from a ribbed plate with inner resonance. Based on explicit design rules and homogenized model for flexural waves, it reminds that bending wave propagation significantly differs from classical models in case of strong contrast between constituents, resulting into inner resonance. In order to demonstrate that this model advantageously supplements the Timoshenko orthotropic plate model, it links the atypical structural response on common vibroacoustic indicators, which are of value to discuss on different levels of abstraction. In either infinite or finite cases, the resulting indicators obtained from the homogenized model matches with classical trends outside frequency bands associated with local resonance, however inner resonance yields additional frequency ranges in which acoustic radiation is either strongly reduced or enhanced. For both mechanical and acoustic quantities, key indicators are successfully compared with classical theory for either poorly and highly contrasted ribbed plates in order to confirm the diversification of acoustic behaviors encompassed by the homogenized model.

*Keywords:* Homogenization, Contrasted structure, Ribbed plate, Inner resonance media, Acoustic radiation, Sound transmission loss

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## **1 Highlights**

- 2     • Homogenized model of ribbed plates discussed versus Timoshenko or-  
3       thotropic model
- 4     • Benefit of homogenized model over classical model for highly contrasted  
5       plates
- 6     • Theoretical influence of the locally resonant behavior on vibroacoustic  
7       indicators

## 8 Introduction

9 The use of ribbed panels in aerospace or automotive engineering is wide  
10 and the current trends associated with sound and vibration control have been  
11 a vector of development of new models and methods. Indeed the coupled  
12 problem of a vibrating plate in a fluid medium is related to fluid-structure  
13 interaction for which assumptions can be made either on the dynamic be-  
14 havior of the plate, the properties of the fluid governing the radiated field,  
15 the nature of the coupling between the plate and the fluid.

16 The acoustic field radiated by a plate is known from its vibratory re-  
17 sponse [1, 2]. The simple case of an infinite thin isotropic plate radiating in an  
18 infinite fluid domain shows the existence of a critical frequency below which  
19 the plate vibrates without radiating acoustic waves (subsonic regime with  
20 evanescent waves), and above which the plate radiates plane waves whose di-  
21 rection of propagation depends on the frequency (supersonic regime). While  
22 the infinite case has some analytical solutions for both regimes, the determi-  
23 nation of the acoustic field radiated in finite case requires the implementation  
24 of the Rayleigh integral based on the Green kernel available for given set of  
25 geometries. It is outlined that although the structural response of the plate  
26 can be determined or approached analytically using Rayleigh-Ritz method,  
27 virtual works principle, or by finite element or finite difference schemes, the  
28 acoustical response is only accessible through the resolution of the Rayleigh  
29 integral, that might be computationally expensive. For a complete review of  
30 structure-borne acoustics of rectangular panels and comprehensive review of  
31 numerical techniques to assess the low frequency radiation, one may respec-  
32 tively refer to the papers from [3, 4]. This overview of methods provides a  
33 reading grid for various experimental works in the scope of this paper, such  
34 as those of [5, 6].

35 A key point of this paper is the aspect of contrast, which can be either  
36 geometric or mechanical in nature. The modeling of this specific feature mod-  
37 ifies the structure of the bi-laplacian operator (classical Kirchhoff's descrip-  
38 tion) by introducing additional bending stiffness coefficients associated with  
39 orthotropy. The most common model for orthotropic plate was developed  
40 by Timoshenko [7] and applies to unidirectionally and orthogonally ribbed  
41 plates, beam grids, corrugated plates through the calculation of equivalent  
42 bending stiffness terms.

43 Focusing on ribbed plates, for which the orthotropic nature arises from  
44 the arrangement of stiffeners on a bare plate, it appears that the stiffeners

significantly affect its dynamic characteristics. One must cite the pioneering works of [8] who demonstrated that the radiation efficiency is increased below the critical frequency by assuming stiffeners as regularly spaced supports. A physical interpretation was introduced later in [9] and describes how the ribs may bring wavenumbers from the subsonic regime to the supersonic regime. Among the different theories to describe the dynamic behavior of periodic stiffened panel, one may refer to the wavenumber based method [10], the space-harmonic analysis [11], wave finite element method [12–14], and some analytical approaches [15–17], among which homogenization is a relevant theoretical framework for the construction of analytical models.

However, most of these works consider structures in which the mechanical properties of the constituents are poorly contrasted. Particularly, these studies give either analytical results on weakly contrasted structures, or numerical results on contrasted structures.

Among the analytical approaches, a benefit of periodic homogenization is to upscale the physics from the micro-scale to the macro-scale without assumption about the nature of the model to be found [18]. Also, giving that the resonant nature at the macroscopic scale comes from the contrast between the constituents, the transition from weakly to strongly contrasted, *i.e.* non-resonant to resonant, can be assessed. Indeed, the asymptotic homogenization is capable of precisely describe this transition of behavior through the scaling of geometrical and mechanical contrasts directly into the derivation process. In this way, one may cite the derivation of models of contrasted frames [19], plate-type structures such as laminated plates [20, 21], unidirectional ribbed plate [22], and orthogonally ribbed plates [23].

Although this analytical method is intrinsically limited to low frequencies, it is sufficient to capture the first eigenmodes of the structure while incorporating the effect of local resonance. As an example, the locally resonant nature of an infinite unidirectional ribbed plate was briefly introduced in [24] and showed that it brings additional frequency bands of radiation below the critical frequency, as well as evanescent waves below the critical frequency. Also, explicit design rules could allow to tune local resonance onto the coincidence frequency as in [25] and thus make it possible to reach improved sound insulation as already known for locally resonant mechanical or acoustical metamaterials, and recently demonstrated by [26–28].

Although numerous studies bring meaningful phenomenological interpretations on the radiation of resonant panels, only little attention has been paid to draw a parallel between an analytical model of contrasted ribbed and its

83 acoustic radiation compared to classical model.

84 In this paper, the acoustic radiation of a contrasted orthotropic plate is  
 85 reported in the infinite case and finite case. The paper is organized into three  
 86 sections. A preliminary description of the structure under study is introduced  
 87 in section 1, together with the underlying physics and associated mechanisms.  
 88 The models introduced will be exploited in the case of an infinite plate,  
 89 then of finite dimensions. Particularly, section 2 presents the outputs of  
 90 the model on common vibroacoustic indicators such as radiation efficiency,  
 91 acoustic impedance, and transmission loss. The section 3 deals with finite  
 92 plate analysis, and compares the response of the contrasted model with that  
 93 of Timoshenko, in terms of mean square velocity and sound transmission  
 94 loss.

## 95 1. Physical insight of ribbed plate models

### 96 1.1. Structure under study

97 The periodic orthogonally ribbed plate hereafter called 2D-ribbed plates  
 98 under study is depicted in Fig. 1. It comprises identical "micro"-plate ele-  
 99 ments (denoted  $\mathcal{P}$ ) connected to an orthogonal beam grid (denoted  $\mathcal{G}$ ), both  
 100 made of isotropic elastic materials. The beams of the grid are assumed signif-  
 101 icantly stiffer than the internal plates. We focus on the dynamic range such  
 102 that the size of the cell (or the width of  $\mathcal{P}$ ) is small compared to the wave-  
 103 length in the beam grid. The referential frame of unit vectors ( $\mathbf{e}_x, \mathbf{e}_y, \mathbf{e}_z$ ) is  
 104 such that  $\mathbf{e}_x$  and  $\mathbf{e}_y$  are the in-plane vectors along the orthogonal ribs, while  
 105  $\mathbf{e}_z$  is the out-of-plane vector. The beam grid  $\mathcal{G}$  is defined by perpendicular  
 106 beams. The stiffeners oriented along  $x$  (resp.  $y$ ) are identical and regularly  
 107 spaced by the length  $\ell_y$  (resp.  $\ell_x$ ).

108 Each segment of stiffeners between two consecutive nodes is modeled as an  
 109 Euler-Bernoulli beam (denoted  $\mathcal{B}_x, \mathcal{B}_y$ ). The geometrical parameters of  $\mathcal{B}_j$ ,  
 110 with  $j = x, y$ , are  $(\ell_j, h_j, b_j, A_j)$  which stand respectively for their length,  $\mathbf{e}_z$ -  
 111 thickness, width with  $b_j = O(h_j)$  and section area  $A_j = h_j b_j$ . The mechanical  
 112 parameters  $(E_j, I_j = b_j h_j^3/12, G_j, \mathcal{I}_j, \rho_j, \Lambda_j = \rho_j A_j, \rho_j J_j)$  denote respectively  
 113 the Young Modulus, the bending inertia, the torsional modulus and torsional  
 114 inertia, the density, the linear mass, and the polar moment. The dimensions  
 115 of the sections  $\sqrt{A_j}$  are assumed small with respect to the lengths  $\ell_j$  so  
 116 that the behavior of the inter-node elements can be effectively modeled as  
 117 Euler-Bernoulli beams. It is further assumed that the geometrical and the

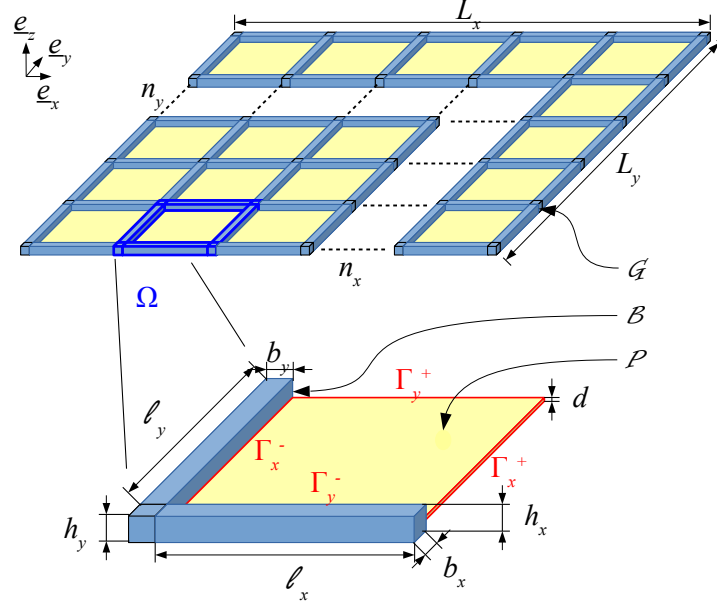


Figure 1: Orthogonally ribbed plate with beams constituting the beam grid  $\mathcal{G}$ , and focus on the unit cell  $\Omega$  made of micro-beams  $\mathcal{B}$  and internal micro-plate  $\mathcal{P}$

mechanical parameters of both types of beams  $\mathcal{B}_j$  are of the same order of magnitude.

The material of the micro-plates  $\mathcal{P}$  of area  $\ell_x \ell_y$  and thickness  $d$ , have a Young's modulus  $E_p$ , a Poisson's ratio  $\nu_p$  and a density  $\rho_p$ . The corrected plate modulus is  $E'_p = E_p / (1 - \nu_p^2)$ . The plate bending inertia is denoted  $I'_p = d^3 / 12$  and the surface mass  $\Lambda'_p = \rho_p d$ .

According to the ribbed plate illustrated in Fig. 1, two models are presented in the following : a poorly contrasted ribbed plate in section 1.2 and a highly contrasted plate model in section 1.3.

### 1.2. Summary of the 2D ribbed plate model without contrasts

As introduced previously, numerous studies dealing with orthogonally ribbed plates are based on Timoshenko description [7]. This description is originally given in statics and is commonly extended in the dynamic regime

132 by introducing  $-\omega^2\Lambda u$  on the right hand side of the equation. For an or-  
 133 thotropic plate defined in the  $(x, y)$  plane, the equation governing its trans-  
 134 verse displacement  $u$  takes the form of Eq. (1) with coefficients Eq. (2).

$$\left(D_x \frac{\partial^4}{\partial x^4} + D_y \frac{\partial^4}{\partial y^4} + 2D_{xy} \frac{\partial^4}{\partial x^2 \partial y^2}\right) u = \omega^2 \Lambda u \quad (1)$$

135 where the bending rigidities and mass are

$$D_x = \frac{E_x I_x}{l_y} + E'_p I_p; \quad D_y = \frac{E_y I_y}{l_x} + E'_p I_p; \quad D_{xy} = E'_p I_p; \quad \Lambda = \frac{\Lambda_x}{\ell_y} + \frac{\Lambda_y}{\ell_x} + \Lambda'_p \quad (2)$$

136 From the original description in statics, the expressions of respective  
 137 bending stiffness suggest that the plate contributes to the global rigidity  
 138 of the plate. This is understood since same order of magnitude, one cannot  
 139 neglect the effect of the plate to the beam grid. Also, introducing  $-\omega^2\Lambda u$  on  
 140 the right hand side of the equation without prior investigation might not be  
 141 fully appropriated to capture all the frequency dependent phenomena.

142 Moving to the case of contrasted plate would require a decoupling of the  
 143 beam grid and the plate, so that contrast is introduced in the plate either  
 144 with geometrical or mechanical parameters. The next section introduces the  
 145 contrast between the beam grid and the internal plates, and discusses how  
 146 contrast enriches Timoshenko description.

### 147 1.3. Summary of the homogenized ribbed plate model with contrasts

148 This subsection defines favorable conditions for inner resonance and sum-  
 149 marizes the derivation of the homogenized model. The homogenization pro-  
 150 cess is carried out according to the following steps : *i*) the homogenization of  
 151 periodic discrete media method enables to derive the dynamic model describ-  
 152 ing the transverse vibration of the beam grid only, *ii*) the coupling between  
 153 the beam grid and the internal plates is then introduced considering that  
 154 the grid is loaded by efforts and moments exerted by the plates attached to  
 155 it, *iii*) the calculation of the dynamic contribution of the resonant internal  
 156 plates driven by the motion of the grid.

#### 157 1.3.1. Contrasts definition and design rules

158 Inner resonance is defined so as the stiff orthogonal beam grid conveys  
 159 the large wavelength, while the soft internal plate experiences a local reso-  
 160 nance. Such a mixed regime within the cell results into *i*) an inhomogeneous



161 kinematics where the plate and grid displacements differ at the leading order  
 162 and *ii*) an asymmetrical coupling where the grid forces the soft plate.

163 First, as for the co-dynamic condition, the beam grid  $\mathcal{G}$  and  $\mathcal{P}$ -plate  
 164 fundamental resonances are of same order i.e.,  $O(\omega_{\mathcal{G}}) = O(\omega_p)$ , so that :

$$O\left(\frac{E'_p I'_p}{\Lambda'_p \ell^4}\right) = O\left(\frac{EI}{\Lambda L^4}\right) \quad \text{i.e.} \quad \frac{E'_p}{E} \frac{\rho}{\rho_p} = O\left(\frac{h^2}{d^2} \frac{\ell^4}{L^4}\right) = O\left(\varepsilon^4 \frac{h^2}{d^2}\right) \quad (3)$$

165 This relation highlights the significant contrasts of mechanical properties of  
 166 the constituting materials of the beam grid  $\mathcal{G}$  and  $\mathcal{P}$ -plate.

167 Second, as for the asymmetric coupling, the grid acts as the forcing system  
 168 that imposes its displacement to the internal plate which bring forces back on  
 169 the grid. Such a coupling between the transverse balance of the grid loaded  
 170 by the internal plates requires :

$$\text{div}(\mathbf{T}_{\mathcal{G}}) = O(T_p) \quad (4)$$

171 where  $\mathbf{T}_{\mathcal{G}}$  relates to the transverse shear force (unit kN) in the grid  $\mathcal{G}$  and  
 172  $T_p$  is the transverse linear shear force in the internal  $\mathcal{P}$ -plate (unit kN/m).

173 Thus, from Eq. (4) and recalling that  $b_k = O(h_k)$  one deduces the follow-  
 174 ing requirement

$$O\left(E \frac{bh^3}{L^4}\right) = O\left(E'_p \frac{d^3}{\ell^3}\right) \quad \text{i.e.} \quad \frac{E'_p}{E} = O\left(\frac{\ell^3}{d^3} \frac{\ell^4}{L^4}\right) = O\left(\varepsilon^4 \frac{h^2}{d^2}\right) \quad (5)$$

175 In practice,  $\rho/\rho_p = O(1)$  and the two conditions Eq. (3) and Eq. (5)  
 176 reduce to  $\frac{E'_p}{E} = O\left(\varepsilon^4 \frac{h^2}{d^2}\right)$ . For ribbed plate made of a single material  $E'_p =$   
 177  $E$ , and the inner-resonance arises when  $d/h = O(\ell^2/L^2)$ , i.e. for plates  $\mathcal{P}$   
 178 significantly thinner than the beams of the grid  $\mathcal{G}$ . If the plates material  
 179 is much softer than the grid material, namely  $E'_p = O(\varepsilon^4 E)$  then  $d/h =$   
 180  $O(\ell/L)$  enables the inner-resonance to occur. Note that in these realistic  
 181 cases, the bending stiffness of the plate is much smaller than that of the grid,  
 182 in accordance with the asymmetry of the coupling. The case of inverted  
 183 material properties so that the plate exhibits stiff properties and beam grid  
 184 soft properties is not assessed here.

### 185 1.3.2. Homogenized formulation of the flexural behavior

186 Starting with the beam grid, the up-scaling process is performed through  
 187 HPDM method (namely Homogenization of Periodic Discrete Media). The

188 developments proceed into three steps, namely, the discretization of the dy-  
 189 namic balance, then the homogenization procedure itself through scale sepa-  
 190 ration assumption and normalization, leading to the continuous model from  
 191 the discrete pattern. This method applies under the key assumption of scale  
 192 separation. This means that the wavelength  $O(L)$  is much larger than the  
 193 period size  $O(l)$  and consequently  $\epsilon = l/L \ll 1$ . The macroscopic descrip-  
 194 tion of the grid, valid at the dominant order, is the limit behavior reached  
 195 for  $\epsilon = l/L \rightarrow 0$ . After these few steps, we are left with the following  
 196 macroscopic description of the grid at the leading order :

$$\left\{ \begin{array}{l} \text{div}(\mathbf{T}^{\mathcal{G}}) + \omega^2 \Lambda^{\mathcal{G}} u = 0 \quad ; \quad \Lambda^{\mathcal{G}} = \frac{\Lambda_x}{\ell_y} + \frac{\Lambda_y}{\ell_x} \\ \text{div}(\mathbf{M}^{\mathcal{G}}) - \mathbf{T}^{\mathcal{G}} - \omega^2 \mathbf{J}^{\mathcal{G}} \cdot \mathbf{grad}(u) = 0 \\ \mathbf{M}^{\mathcal{G}} = - \left( \begin{array}{cc} \frac{E_x I_x}{\ell_y} \partial_x^2 u & \frac{G_y J_y}{\ell_x} \partial_x \partial_y u \\ \frac{G_x J_x}{\ell_y} \partial_y \partial_x u & \frac{E_y I_y}{\ell_x} \partial_y^2 u \end{array} \right) \quad ; \quad \mathbf{J}^{\mathcal{G}} = \left( \begin{array}{cc} \rho_y J_y & 0 \\ 0 & \rho_x J_x \end{array} \right) \end{array} \right. \quad (6)$$

197 The governing equation Eq. (6) may be written under condensed form

$$\begin{aligned} \frac{E_x I_x}{\ell_y} \frac{\partial^4 u}{\partial x^4} + \frac{E_y I_y}{\ell_x} \frac{\partial^4 u}{\partial y^4} + \left( \frac{G_x I_x}{\ell_y} + \frac{G_y I_y}{\ell_x} \right) \frac{\partial^4 u}{\partial x^2 \partial y^2} \\ + \omega^2 \left( \frac{\rho_y J_y}{\ell_x} \frac{\partial^2 u}{\partial x^2} + \frac{\rho_x J_x}{\ell_y} \frac{\partial^2 u}{\partial y^2} \right) = \omega^2 \left( \frac{\Lambda_x}{\ell_y} + \frac{\Lambda_y}{\ell_x} \right) u \end{aligned} \quad (7)$$

198 The governing equation Eq. (6) shows the coupling between the flexural  
 199 and torsional behaviors. Note that in statics ( $\omega \rightarrow 0$ ), this model already  
 200 differs to that of Timoshenko Eq. (1). Note also that the inertial term con-  
 201 taining the polar moments  $\mathbf{J}^{\mathcal{G}}$  may be neglected in regards to those related to  
 202 the linear masses  $\Lambda^{\mathcal{G}}$ . Note finally that an additional inertial effect following  
 203 comment made in section 1.2.

204 The action of internal plates is then introduced in the beam grid model  
 205 in the form an external loading constituted by a shear force  $\mathcal{F}$  and a couple  
 206  $\mathcal{C}$  resulting from the contact forces. The rigorous calculation of these terms  
 207 is detailed in [23]. Calculating analytically these terms yield the effective  
 208 model of the 2D ribbed plate that describes the grid behavior enriched by

209 for the locally resonant internal plates:

$$\begin{cases} \text{div}(\mathbf{T}^{\mathcal{G}}) + \omega^2(\Lambda^{\mathcal{G}} + \Lambda'_p \langle \phi_{\omega} \rangle)u = 0 \\ \text{div}(\mathbf{M}^{\mathcal{G}}) - \mathbf{T}^{\mathcal{G}} - \omega^2 \mathbf{J}^{\mathcal{G}} \cdot \mathbf{grad}(u) = 0 \end{cases} \quad (8)$$

210 with  $\mathbf{M}^{\mathcal{G}}$  and  $\mathbf{J}^{\mathcal{G}}$  as defined in Eq. (6). Note also that the description could  
 211 be improved by considering the correction factors constituted by the higher  
 212 order terms of the asymptotic process. These could be relevant in case scale  
 213 separation is not fulfilled. The inner resonance effect appears in Eq. (8)  
 214 through the frequency dependent effective parameter  $\langle \phi_{\omega} \rangle$ , associated with  
 215 the dynamic motion of the internal plate. This results into a non conventional  
 216 apparent mass term whose determination is performed by integrating the  
 217 transverse displacement of the internal plate over its surface. Since there  
 218 is no analytical expression of this quantity for a square clamped plate, the  
 219 latter is approximated by that of a clamped circular plate. This provides an  
 220 approximated value, denoted  $\langle \phi_{\omega}^c \rangle$ , for a square plate of side  $l$  by matching  
 221 its first eigenfrequency with that of an equivalent circular plate of radius  $a$ .  
 222 The corresponding approximation reads:

$$\langle \phi_{\omega} \rangle \approx \langle \phi_{\omega}^c \rangle = \frac{4}{\delta a} \frac{I_1(\delta a) J_1(\delta a)}{I_1(\delta a) J_0(\delta a) + I_0(\delta a) J_1(\delta a)} \quad (9)$$

223 where  $a \approx 0.53l$  is the equivalent radius,  $J_k$  and  $I_k$  are the Bessel and modified  
 224 Bessel functions of the first/second kind,  $\delta$  is the wavenumber such that  
 225  $\delta^4 = \Lambda'_p \omega^2 / E'_p I_p$ . The denominator of Eq. (9) is the transcendental equation  
 226 whose roots  $\delta a$  are used to calculate the eigenfrequencies of the circular plate.  
 227 The matching is performed on the first mode, and determines the radius of  
 228 the equivalent circular plate, that is  $a = 0.53l$ . Although this reasoning is  
 229 empirical and based on the resemblance of the first mode shapes of a square  
 230 and circular plate, this estimate perfectly fits the first resonance but over-  
 231 predicts the eigenfrequency of the second mode with an error of 5%. (see  
 232 [23]).

233 The properties of  $\langle \phi_{\omega} \rangle$  are such that  $\langle \phi_{\omega} \rangle \rightarrow 1$  as  $\delta \rightarrow 0$  which means that  
 234 the effective mass is the real static mass, and  $\langle \phi_{\omega} \rangle \rightarrow \pm\infty$  as  $I_1(\delta a) J_0(\delta a) +$   
 235  $I_0(\delta a) J_1(\delta a) = 0$ , which roots corresponds to the plate's eigenfrequencies.

236

237 *1.3.3. Dispersion features*

238 Assuming an harmonic bending wave in the form  $u(\mathbf{x}) = \exp(ik_\theta \mathbf{n}_\theta \cdot \mathbf{x})$   
 239 propagating in the direction  $\mathbf{n}_\theta = \cos \theta \mathbf{e}_x + \sin \theta \mathbf{e}_y$ . Taking into account the  
 240 facts that the terms associated with polar moments  $\mathbf{J}^G$  are of weak magnitude  
 241 compared to the translational inertia, this term can be disregarded at the  
 242 leading order. Consequently, the bending wavenumber  $k_\theta(\omega)$  is given by :

$$k_\theta^4 \left( \frac{E_x I_x}{\ell_y} \cos^4 \theta + \frac{E_y I_y}{\ell_x} \sin^4 \theta + \left( \frac{G_x \mathcal{I}_x}{\ell_y} + \frac{G_y \mathcal{I}_y}{\ell_x} \right) \cos^2 \theta \sin^2 \theta \right) - \omega^2 (\Lambda^G + \Lambda'_p \langle \phi_\omega \rangle) = 0 \quad (10)$$

243 The inner resonance contained in  $\langle \phi_\omega \rangle$  leads to dispersion features that differs  
 244 distinctly from the classical bending case in which  $k \propto \sqrt{\omega}$  in the whole  
 245 frequency range. Significant changes are expected in the neighborhood of the  
 246 internal plate's eigenmodes. Wavenumbers will be the subject of a special  
 247 discussion in the section 2.1.

248 *1.4. Concluding remarks*

249 As an extension to the classical orthotropic plate equation Eq. (1) with  
 250 coefficients Eq. (2) proposed by Timoshenko, homogenization introduces a  
 251 dynamic description taking into account contrast between the beam and  
 252 internal plates. Such an extended formulation is found as :

$$\begin{aligned} \frac{E_x I_x}{\ell_y} \frac{\partial^4 u}{\partial x^4} + \frac{E_y I_y}{\ell_x} \frac{\partial^4 u}{\partial y^4} + \left( \frac{G_x \mathcal{I}_x}{\ell_y} + \frac{G_y \mathcal{I}_y}{\ell_x} \right) \frac{\partial^4 u}{\partial x^2 \partial y^2} \\ + \omega^2 \left( \frac{\rho_y J_y}{\ell_x} \frac{\partial^2 u}{\partial x^2} + \frac{\rho_x J_x}{\ell_y} \frac{\partial^2 u}{\partial y^2} \right) = \omega^2 (\Lambda^G + \Lambda_p \langle \phi_\omega \rangle) u \end{aligned} \quad (11)$$

253 Remarking that the terms associated with polar moments are of weak  
 254 magnitude compared to the inertia, this term can be neglected at the leading  
 255 order, so that Eq. (11) degenerates into

$$\left( D_x \frac{\partial^4}{\partial x^4} + D_y \frac{\partial^4}{\partial y^4} + 2D_{xy} \frac{\partial^4}{\partial x^2 \partial y^2} \right) u = \omega^2 (\Lambda^G + \Lambda_p \langle \phi_\omega \rangle) u \quad (12)$$

256 where the bending stiffness and mass are

$$D_x = \frac{E_x I_x}{\ell_y} ; D_y = \frac{E_y I_y}{\ell_x} ; D_{xy} = \frac{G_x \mathcal{I}_x}{\ell_y} + \frac{G_y \mathcal{I}_y}{\ell_x} ; \Lambda^G = \frac{\Lambda_x}{\ell_y} + \frac{\Lambda_y}{\ell_x} \quad (13)$$

From Eq. (11) with coefficients Eq. (13), two important observations are made. First, the structure of the differential operation changes in such a way it still contains the bi-laplacian operator and includes additional terms of bending and torsional stiffness with rotational inertia. Second, the reference equation Eq. (1) with coefficients Eq. (2) no longer considers the plate contribution in the elastic part, but in the inertial part. The plate is no longer contained in the bending stiffness. This is fully consistent with the fact that a contrasted ribbed plate will exhibit a dynamic behavior mostly governed by the grid, and the internal plates will affect the global response only around frequency bands in which their dynamic behavior differs from that of the grid.

From this introduction on the mechanical part, the sound radiation from plates can be modeled assuming it is either infinite or finite. The next two sections 2 and 3 are respectively dedicated to infinite and finite cases.

## 2. Acoustic radiation - Infinite case

This section presents an investigation onto a infinite ribbed plate. In anticipation of an experimental investigation, the dimensions of the internal plates are calculated so as to correspond to a feasible plate. Two designs are obtained : first is denoted  $\mathcal{R}_1^\infty$ , and is associated with geometrical and mechanical contrast between the grid and internal plate considering the ribs are identical in the two directions, second is denoted  $\mathcal{R}_2^\infty$ , and introduces stiffeners of different dimensions in the two directions, in order to better exhibit the orthotropic nature of the plate. According to the indicators defined in section 2.1, as well as the geometrical parameters and mechanical properties given in Table 1, Table 2, the investigation will be expanded in terms of radiation efficiency (section 2.2) and transmission loss (section 2.3).

### 2.1. Methods and chosen sets of parameters

As for the methods, let consider an infinite plate with incident acoustic plane wave, as illustrated in Fig. 2. The expressions the transmission coefficient is derived from *i*) the acoustic pressure of the incident, reflected and transmitted waves, *ii*) the pressure difference on both face of the plate combined with *iii*) the continuity of pressure and velocity at the fluid-solid interface.

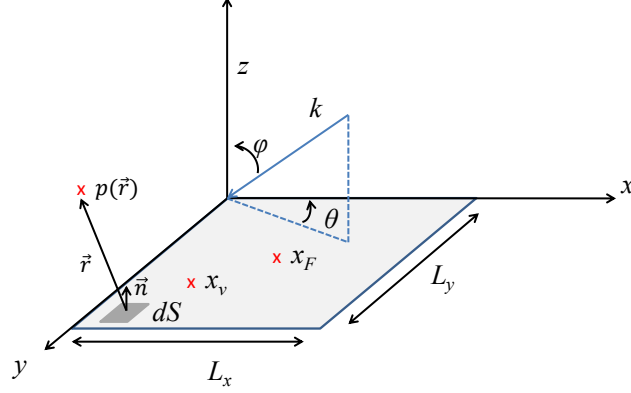


Figure 2: Notations used for the sound radiation investigation : ribbed plate in the  $(x, y)$  plane, angle of incident plane wave  $\phi$ , azimuth angle  $\theta$  of wave propagating in the plate. Location of point force  $x_F$  and observation point  $x_v$  for calculation of structural response. Elementary radiating surface  $dS$  with normal direction  $\mathbf{n}$  towards receiver point.

290 Let us consider an infinite orthotropic plate driven by an incident pressure  
 291  $p(x, y, z)$  which governing equation is :

$$\left( D_x \frac{\partial^4}{\partial x^4} + D_y \frac{\partial^4}{\partial y^4} + 2D_{xy} \frac{\partial^4}{\partial x^2 \partial y^2} \right) u - \omega^2 \Lambda u = p(x, y, z) \quad (14)$$

292 When the pressure field is supposed of the form of an incident plane wave  
 293 with a wavenumber  $k = \omega/c_0$ , an incidence angle  $\phi$  and an azimuth angle  
 294  $\theta$ . In this case, the incidence angle  $\phi$  is the angle between the wave vector  
 295 and the normal direction to the plate, and the azimuth angle  $\theta$  gives its  
 296 orientation in the plane of the plate. As for the incident plane wave, we state  
 297  $p(x, y, z)$  as:

$$p(x, y, z) = p_0 \exp(-i(k_x x + k_y y + k_z z)) \quad (15)$$

298 with  $k_x = k \sin \phi \cos \theta$ ,  $k_y = k \sin \phi \sin \theta$ ,  $k_z = k \cos \phi$  are the acoustic  
 299 wavenumbers in the different directions.

300 On the surface of the plate,  $p(x, y, z = 0) = p_0 \exp(-i(k_x x + k_y y))$ , the  
 301 transverse displacement on the plate, solution of the equation Eq. (14) is  
 302 searched with the form:

$$u(x, y) = U \exp(-ik \sin \phi (\cos \theta x + \sin \theta y)) \quad (16)$$

303 The ratio between the acoustic pressure to the velocity of the plate is intro-  
 304 duced as the surface impedance  $Z_s = p/v = p/i\omega u$ .

305 The forms of the pressure and the displacement are the same as for the  
 306 infinite isotropic plate but in case of orthotropic plate, due to the angle  
 307 dependence of the flexural wavenumber  $k_p$ , the relation becomes

$$(D_x \cos^4 \theta + D_y \sin^4 \theta + 2D_{xy} \cos^2 \theta \sin^2 \theta)(k^4 \sin^4 \phi - k_p^4(\theta))u = p \quad (17)$$

308 and therefore, the surface impedance is defined by:

$$Z_s(\theta, \phi) = \frac{-i}{\omega} (D_x \cos^4 \theta + D_y \sin^4 \theta + 2D_{xy} \cos^2 \theta \sin^2 \theta) (k^4 \sin^4 \phi - k_p^4(\theta)) \quad (18)$$

309 Due to the orthotropic nature of plate, and thus the existence of two  
 310 critical frequencies, the coincidence frequency band exhibiting a typical gap  
 311 becomes broader and smoother. A relatively small difference between the  
 312 bending rigidity of stiffeners produces a small difference between their respec-  
 313 tive critical frequencies. As the difference of stiffness increases, the critical  
 314 frequencies might be separated by one or two orders of magnitude.

315 From this observation, the usual expression of surface impedance  $Z_s$  in-  
 316 cludes these two critical frequencies, whose depend not only on the angle of  
 317 incidence  $\phi$  of the incident plane wave, but also on the azimuth angle  $\theta$  in  
 318 the plane of the plate (see Fig. 2). The surface impedance of the orthotropic  
 319 plate is thus :

$$Z_s = j\omega\Lambda \left( 1 - \left( \frac{f}{f_{c,x}} \cos^2 \theta + \frac{f}{f_{c,y}} \sin^2 \theta \right)^2 \sin^4 \phi \right) \quad (19)$$

320 For a given angle of incidence  $\phi$ , the transmission coefficient  $\tau$  is defined  
 321 by :

$$\tau_{(\phi,\theta)} = \frac{1}{\left| \frac{Z_s}{2Z_0} + 1 \right|^2} \quad (20)$$

322 with  $Z_0 = \rho_0 c_0 / \cos \phi$  the normal impedance of the fluid and  $Z_s$  the surface  
 323 impedance of the plate. The calculation of this transmission coefficient in  
 324 diffuse field conditions is performed by integrating Eq. (20) over all angles  
 325 of incidence. Assuming plane wave incidence uniformly distributed over all  
 326 angles, the statistical transmission factor is :

$$\tau_d = \frac{2}{\pi} \int_0^{\pi/2} \left( 2 \int_0^{\pi/2} \tau_{(\phi,\theta)} \cos \phi \sin \phi d\phi \right) d\theta \quad (21)$$

Introducing finally  $\tau$  as Eq. (20), the diffuse field transmission coefficient is formulated as :

$$\tau_d = \frac{2}{\pi} \int_0^{\pi/2} \int_0^1 \frac{d(\sin^2 \phi) d\theta}{\left| \frac{Z_s}{2Z_0} + 1 \right|^2} \quad (22)$$

In the following, the evaluation of this term is performed numerically. In addition to the transmission coefficient, the reduction index  $R$  is introduced as  $R = -10 \log(\tau_d)$ .

According to the design rules favorable to inner resonance presented above and considering a feasibility criterion, two designs are obtained : first is denoted  $\mathcal{R}_1^\infty$ , and is associated with geometrical and mechanical contrast between the grid and internal plate considering the ribs are identical in the two directions, second is denoted  $\mathcal{R}_2^\infty$ , and introduces stiffeners of different dimensions in the two directions. The geometrical parameters and mechanical properties are respectively given in Table 1 and Table 2. The models use hysteretic damping ratio introduced as an imaginary part of the Young's modulus  $E = E(1 + i\eta)$ , with  $\eta = 1\%$  for aluminium and  $5\%$  for perspex.

Table 1: Geometrical parameters and mechanical properties associated with the 2D infinite ribbed plate  $\mathcal{R}_1^\infty$ .

$n_x = n_y = \infty$	$E$ (GPa), $\nu$	$\rho$ (kg/m <sup>3</sup> )	Dimensions (m)
Beam grid	$E_b=69$ ; $\nu_b = 0.3$	$\rho_b=2700$	$h_x = h_y = 1.5 \cdot 10^{-2}$ $b_x = b_y = 1.5 \cdot 10^{-2}$
Internal plates	$E_p=2$ ; $\nu_p = 0.37$	$\rho_p=1200$	$l_x = l_y = 7 \cdot 10^{-2}$ $d = 3 \cdot 10^{-3}$

Following the design  $\mathcal{R}_1^\infty$  in Table 1, the exact critical frequency is the same in both directions  $f_{c,j} = \frac{c^2}{2\pi} \sqrt{\frac{\lambda_j + \lambda_p D \langle \phi_\omega \rangle}{D_j}}$ . The first resonance frequency of the internal plate is  $f_1^r = 1386$  Hz.

Following the design  $\mathcal{R}_2^\infty$  in Table 2, the exact critical frequencies in both directions  $f_{c,j} = \frac{c^2}{2\pi} \sqrt{\frac{\lambda_j + \lambda_p D \langle \phi_\omega \rangle}{D_j}}$  could be estimated numerically. As an approximation, out of the inner resonance frequency bands, this critical



Table 2: Geometrical parameters and mechanical properties associated with the 2D infinite ribbed plate  $\mathcal{R}_2^\infty$ .

$n_x = n_y = \infty$	$E$ (GPa), $\nu$	$\rho$ (kg/m <sup>3</sup> )	Dimensions (m)
Beam grid	$E_b=69$ ; $\nu_b = 0.3$	$\rho_b=2700$	$h_x = 1.10^{-2}$ , $h_y = 0.75.10^{-2}$ $b_x = b_y = 1.10^{-2}$
Internal plates	$E_p=2$ ; $\nu_p = 0.37$	$\rho_p=1200$	$l_x = l_y = 7.6.10^{-2}$ $d = 3.10^{-3}$

frequency is bounded by that of a simple plate radiating in half-space  $f_c^- = \frac{c^2}{2\pi} \sqrt{\frac{\lambda_b}{D_x}}$ , that is  $f_c^- = 1613$  Hz as the lower bound, and will not be greater than that of the rib and internal plate at rest  $f_{c,j}^+ = \frac{c^2}{2\pi} \sqrt{\frac{\lambda_j + \lambda_p}{D_j}}$ , that is  $f_{c,x}^+ = 2520$  Hz as the upper bound. This can be systematically verified. The same observation is valid for the other direction, respectively  $f_{c,y}^- = 2520$  Hz, and  $f_{c,y}^+ = 3323$  Hz. Also, the first resonance frequency of the internal plate is  $f_1^r = 1190$  Hz, and the second resonance frequency is  $f_2^r = 3261$  Hz.

The effective mass  $\langle \phi_\omega \rangle$  associated to internal for both design is plotted in Fig. 3 for both designs. The trends observed is consistent with the behavior with the comment provided along Eq. (9), where the two resonance frequencies clearly appear.

From Fig. 4, it can be shown that due to inner resonance, the flexural wavenumber, calculated from Eq. (10), can significantly vary below and above the critical frequency. Classical results of acoustic radiation below and above the critical frequency can be obtained for 60 Hz and 900 Hz respectively. However, in case of inner resonance, the flexural wavelength can be significantly greater than acoustic wavelength below the critical frequency, giving rise to unconventional acoustic radiation. Alternatively, the flexural wavelength can be significantly lower than acoustic wavelength above the critical frequency, giving rise to unconventional generation of evanescent acoustic waves.

## 2.2. Radiation efficiency

An usual indicator to evaluate if a vibrating surface is a good sound radiator is the radiation efficiency denoted  $\sigma$  defined in terms of wavenumbers

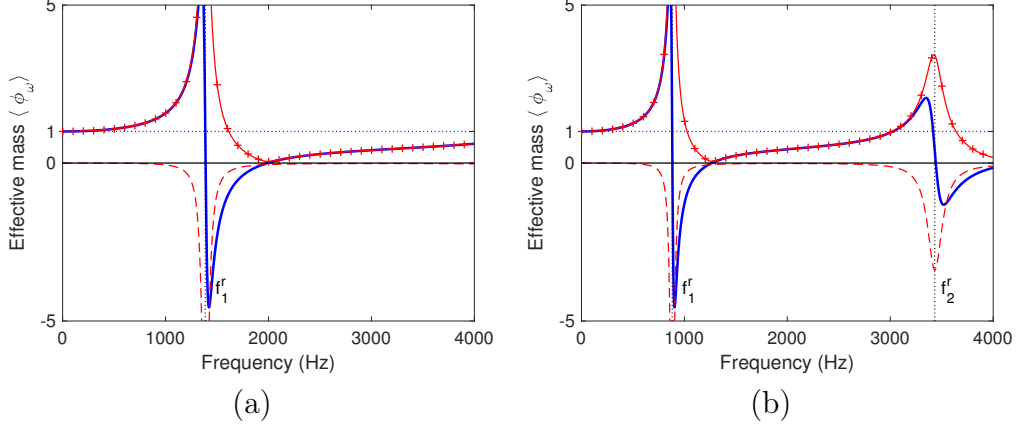


Figure 3: Dimensionless effective mass  $\phi_\omega$  associated with one single internal plate : real part (—), imaginary part (---), modulus (—+—), normalized static mass  $y = 1$  (····). For plate  $\mathcal{R}_1^\infty$  (a) and plate  $\mathcal{R}_2^\infty$  (b).

as  $\sigma = 1/\sqrt{1 - k_p^2/k^2}$ . In this formula, we assume  $k_p < k$  ; when the flexural wavelength in the plate increases with respect to the acoustic wavelength in air, the radiation efficiency tends to 1. The radiation efficiency is illustrated in Fig. 5 for both designs introduced above. As for the plate  $\mathcal{R}_1^\infty$ , for which stiffeners are identical in both directions,  $\sigma$  is the same for  $\theta = 0$  or  $\pi/2$ , and the tuning of the inner resonance frequency onto the critical frequency decreases significantly the radiation factor in this region where the plate is known to be acoustically transparent. As for the plate  $\mathcal{R}_2^\infty$ , for which stiffeners are different in both directions,  $\sigma$  is illustrated for  $\theta = 0$  and  $\theta = \pi/2$  and the influence of resonance frequencies is exhibited.

Radiation efficiency is an indicator for observing a preliminary manifestation of the local resonance effect. It gives an indication of the behavior in the main directions of orthotropy. A global description obtained from an integration on all angles, in the plate and in the air is proposed in the following section.

### 2.3. Sound transmission loss

#### 2.3.1. Results for a single incidence angle

Two incidence angle are considered here for the acoustic wave reaching the plate : normal incidence condition  $\phi = 0$ , oblique incidence condition  $\phi = \pi/3$ .

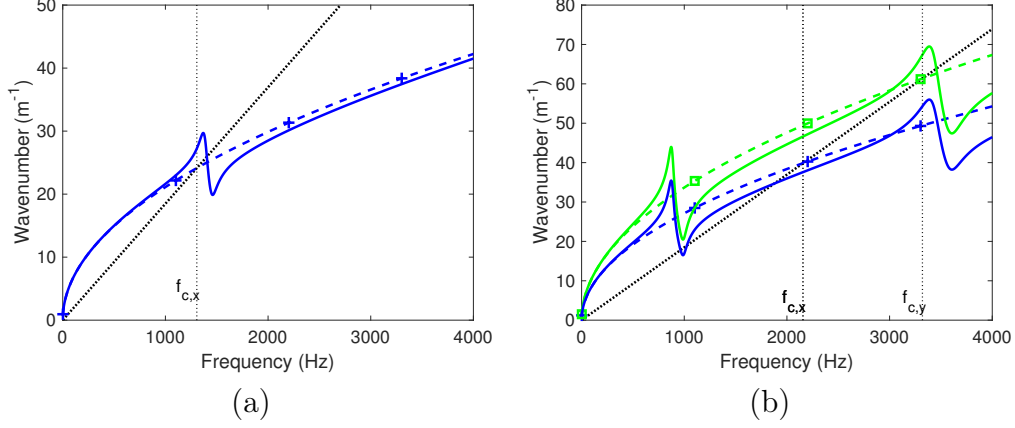


Figure 4: Flexural wavenumber in the  $x$ - and  $y$ - direction without inner resonance (resp.  $(-+ -)$  and  $(-\square-)$ ) and with inner resonance (resp.  $(-)$ ,  $(-)$ ), acoustic wavenumber in air ( $\cdots$ ), and vertical dotted lines located at crossings indicated critical frequencies. For plate  $\mathcal{R}_1^\infty$  (a) and plate  $\mathcal{R}_2^\infty$  (b).

As for the normal incidence condition, Eq. (18) simplifies so as elastic effects vanish and only inertial effect remain, that is consistent with the mass law approximation, which gives a quite appropriate description for frequencies lower than the critical frequency. The normal incidence transmission loss is illustrated for the two design in Fig. 6.

As for the oblique incidence, an arbitrary angle for the propagating wave in the plate is chosen as  $\theta = \pi/3$ . After passing the coincidence frequency, the transmission loss exhibits strong frequency dependence and the bending stiffness (elastic effects) becomes predominant over the mass law. This effect is illustrated in Fig. 7 for 3 values of incidence angle, which shows that the classic trends are correctly recovered, *i.e.* the coincidence frequency decreases as the angle of incidence get closer to the grazing incidence, and that the introduction of local resonance is perceptible in specific interval without modified the change of slope below and above the coincidence frequency.

To extend these results to diffuse field, one may integrate over all possible incidence angles  $\phi$  of the acoustic wave in air and possible directions of propagation  $\theta$  of bending wave in the plate. The limits of the domains of integration are withdrawn since they correspond to grazing incidences and can give numerical errors.

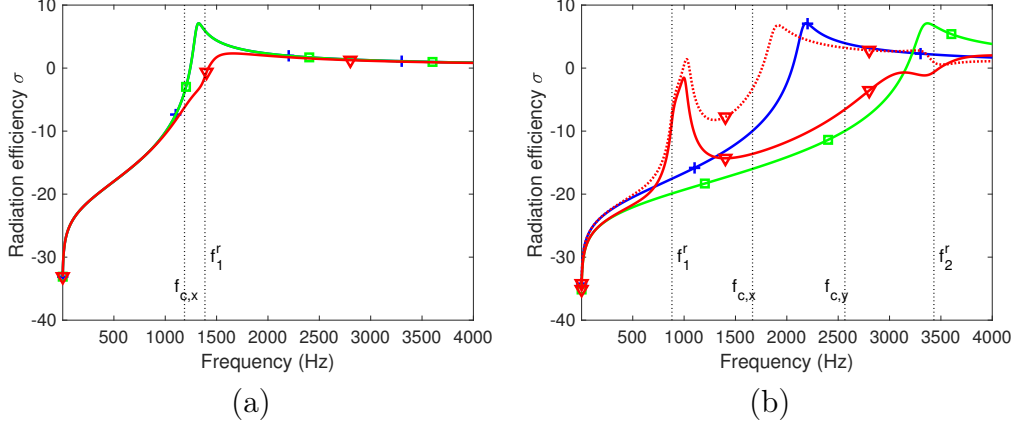


Figure 5: Radiation efficiency of orthotropic plate with inner resonance for  $\theta = \pi/2$  ( $-\nabla-$ ),  $\theta = 0$  ( $\cdots\nabla\cdots$ ), equivalent isotropic plate in  $x$ - direction ( $-\square-$ ) and  $y$ -direction ( $-\square-$ ). For plate  $\mathcal{R}_1^\infty$  (a) and plate  $\mathcal{R}_2^\infty$  (b).

### 2.3.2. Results in diffuse field conditions

The transmission loss is now calculated for the two designs. For each design, the transmission loss of the plate considering inert internal plates and the plate with the dynamic of the internal plates is plotted to best evidence the local resonance.

As for the design of the ribbed plate  $\mathcal{R}_1^\infty$  given in Table 1, the diffuse field transmission loss clearly shows the coincidence frequency of the equivalent isotropic plate in the  $x$ - direction and the plate at rest. The small shift in coincidence frequency is due to the increase of mass. However the most noticeable effects lies in the increase of transmission loss around the coincidence frequency. Minor fluctuations visible at high frequency are due to the discretization of the angle interval and are not related with inner resonance.

As for the design of the ribbed plate  $\mathcal{R}_2^\infty$  given in Table 2. Several quantities are illustrated, namely, the transmission loss associated with the equivalent isotropic plate along  $x$ - and  $y$ -, that associated with the orthotropic plate without inner resonance (disabling the frequency dependent term in Eq. (11), that is  $\langle\phi_\omega\rangle = 1$ ), and that including the local resonance. Comparison is shown in Fig. 8 and shows the two critical frequencies associated with the equivalent isotropic plates along  $-x$  and  $-y$ , since these have different bending stiffness in the two directions. A relatively small difference between rigidities produces a small difference between critical frequencies. The ribs increase the bending stiffness but lowers the critical frequency. This may

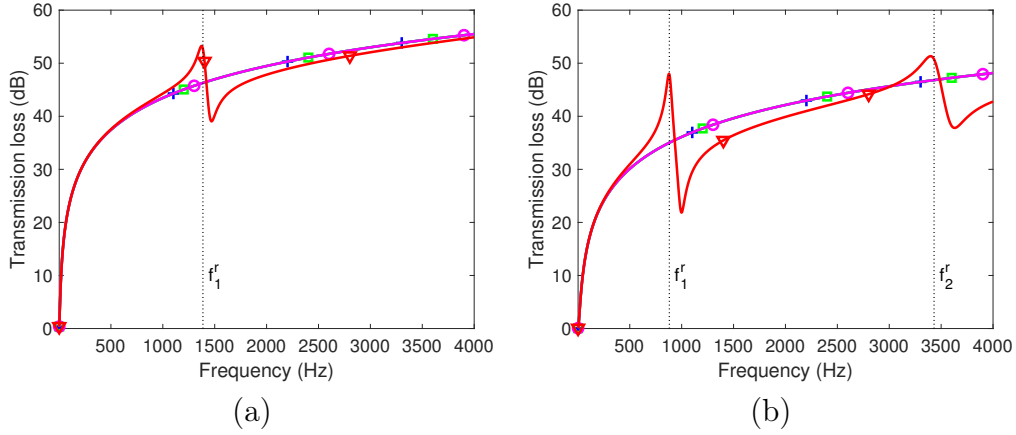


Figure 6: Normal incidence transmission loss of orthotropic plate with inner resonance ( $-\nabla-$ ), plate at rest ( $-\circ-$ ), equivalent isotropic plate in  $x$ - direction ( $-\oplus-$ ) and  $y$ - direction ( $-\square-$ ). For plate  $\mathcal{R}_1^\infty$  (a) and plate  $\mathcal{R}_2^\infty$  (b).

lead to an increased transparency in the useful frequency range. However, the locally resonant nature can be put to good use since it provides an additional mechanism of attenuation in some frequency bands. In this way, the transmission loss of the orthotropic plate exhibits a dip between the aforementioned critical frequencies. When introducing the resonance of internal plates, additional fluctuations related to eigenmodes of the vibrating internal plates contribute to the increase or decrease of transmission loss at their corresponding frequencies.

#### 2.4. Concluding remarks on infinite case

This section introduced the relevant quantities to look at when investigating the radiation of plates. Two realistic designs are obtained : first is associated with geometrical and mechanical contrast between the grid and internal plate, second introduces different stiffeners in the two directions, in order to better exhibit the orthotropic nature of the plate, still with inner resonance. Preliminary examination of wavenumbers suggests that in case of inner resonance, the flexural wavelength can be greater than the acoustic wavelength below the critical frequency, giving rise to acoustic radiation, and alternatively, it can be lower than acoustic wavelength above the critical frequency, giving rise to unconventional generation of evanescent acoustic waves. This is then confirmed by the observation of radiation efficiency, which shows that tuning the inner resonance frequency around the critical

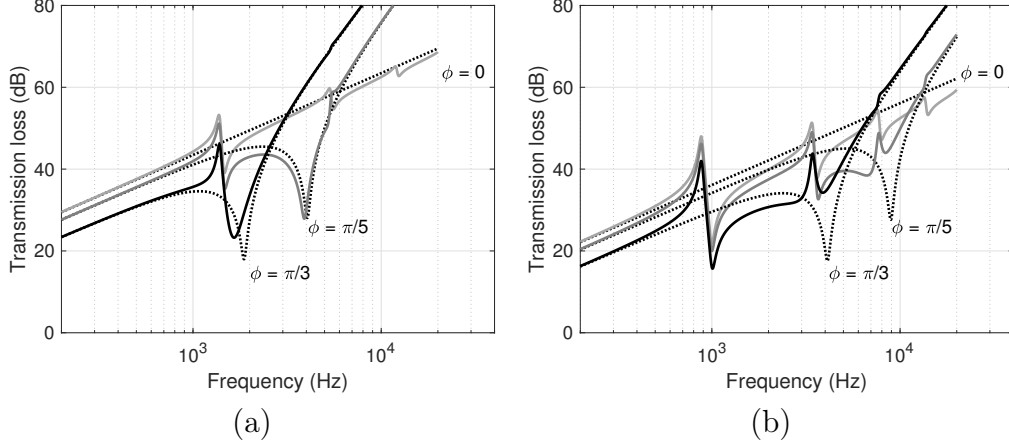


Figure 7: Oblique incidence transmission loss of orthotropic plate with inner resonance (—), plate at rest (···), for  $\phi = 0, \pi/5, \pi/3$ , from light to dark grey. For plate  $\mathcal{R}_1^\infty$  (a) and plate  $\mathcal{R}_2^\infty$  (b).

frequency leads to significant attenuation. Finally, exploring the trends of transmission loss in either single incidence angle or diffuse field shows that the locally resonant nature of the plate bring additional attenuation in the coincidence region where the plate is known to be acoustically transparent.

### 3. Acoustic radiation - Finite case

The previous designs  $\mathcal{R}_1^\infty$  and  $\mathcal{R}_2^\infty$  are supplemented by finite dimensions  $L_x = L_y = 0.7$  m, and are denoted  $\mathcal{R}_1$  and  $\mathcal{R}_2$ .  $\mathcal{R}_1$  has  $n_x = n_y = 8$  cells,  $\mathcal{R}_2$  has  $n_x = n_y = 7$  cells. For explanatory purposes and in order to demonstrate the effect of locally resonant nature of the plate on the sound transmission loss, the simply supported case is chosen since it offers an analytical solution in the form of a double summation of sine terms. The location of point force and observation point for calculation of structural response are sketched in Fig. 2. From this setup, structural frequency response functions are assessed in section 3.1, then mean square velocity is commented in section 3.2. The behaviors identified make it possible to better understand the shape of the transmission loss curve in section 3.3.

#### 3.1. Comparison of Timoshenko and homogenized model

This section briefly presents the structural response of the orthogonally ribbed plate modeled either with Timoshenko equation Eq. (1) or homog-

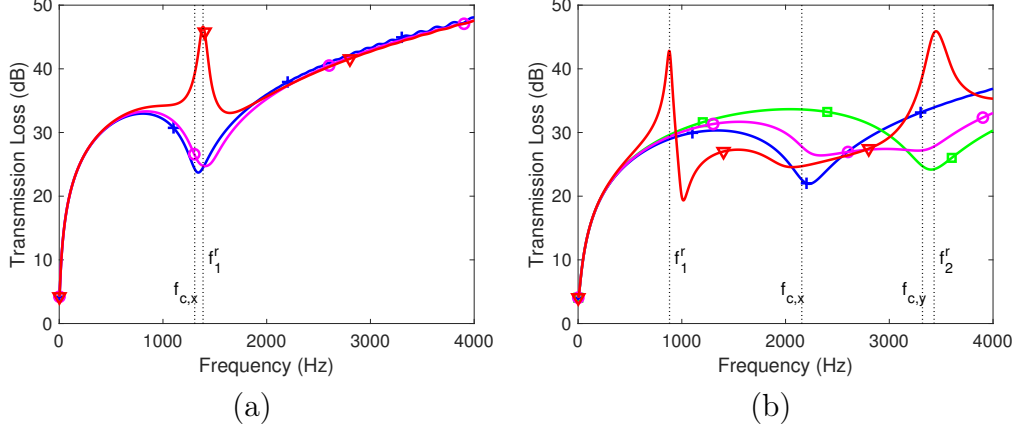


Figure 8: Diffuse field transmission loss of orthotropic plate with inner resonance ( $-\triangle-$ ), plate at rest ( $-\circ-$ ), equivalent isotropic plate in  $x$ - direction ( $-\circ-$ ) and  $y$ - direction ( $-\square-$ ). For plate  $\mathcal{R}_1^\infty$  (a) and plate  $\mathcal{R}_2^\infty$  (b).

473 enized model with inner resonance Eq. (11). For this purpose, a struc-  
 474 tural point force is located at coordinates  $x_F = (L_x/2, L_y/2)$  and the trans-  
 475 verse velocity is calculated at a virtual observation point with coordinates  
 476  $x_v = (L_x/3, L_y/3)$ . In this way, the structural frequency response func-  
 477 tion defined as the ratio of velocity versus input force, namely mobility  
 478  $M(\omega) = i\omega u/F$ , is calculated analytically. For the sake of simplicity,  
 479 plates with simply supported boundary conditions all around are consid-  
 480 ered since there are distinct solutions for the wavenumbers  $k_x$  and  $k_y$  and  
 481 it provides an analytical solution. The solution for the transverse displace-  
 482 ment field  $u(x, y, \omega)$  is formulated as the infinite sum of all possible solutions  
 483  $u(x, y, \omega) = \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} u_{m,n}(\omega) \Psi_{m,n}(x, y)$ , where  $\Psi_{m,n}(x, y)$  is the  $(m, n)$   
 484 mode shape function and  $w_{m,n}(\omega)$  the associated amplitude. In case of a  
 485 plate supported along all four edges, the modal functions are  $\Psi_{m,n}(x, y) =$   
 486  $\sin(m\pi x/L_x) \sin(n\pi y/L_y)$ . This modal summation technique can be approx-  
 487 imated as a finite sum as  $u(x, y, \omega) \approx \sum_{m=1}^M \sum_{n=1}^N u_{m,n}(\omega) \Psi_{m,n}(x, y)$ , where  
 488  $M$  and  $N$  are the number of modes considered. Considering 50 modes, the  
 489 computational time is about 4 seconds and associated results are given for  
 490 both designs on Fig. 9. The structural mobility is calculated as

491  
 492 Apart from the inner resonance frequencies specific to each design, the  
 493 very low frequency behavior is well captured by the homogenized model, as  
 494 well as the trend in rather high frequency domain. In addition, the response

495 from homogenized model exhibits proper drops of amplitude at the frequen-  
 496 cies identified as inner resonance frequencies, which makes it possible to rely  
 497 on its ability to predict local phenomena.

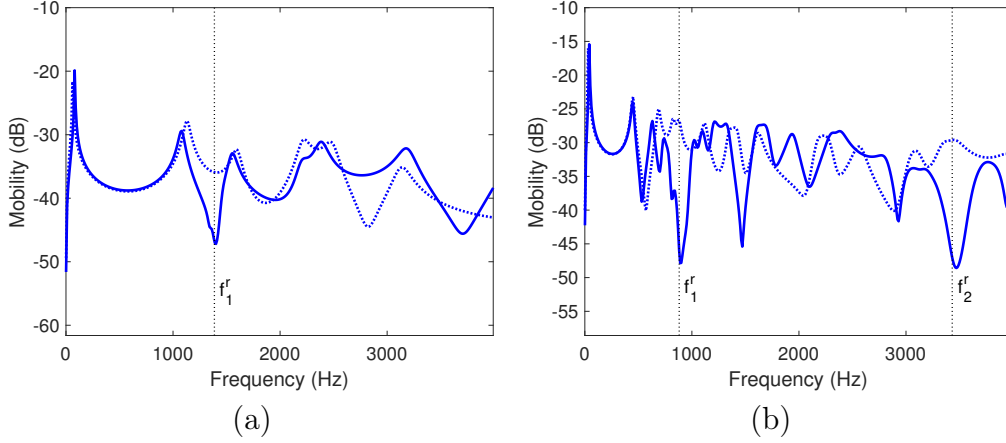


Figure 9: Structural mobility (ref:1m/s/N) of simply supported orthotropic plate with inner resonance computed analytically from homogenized model (—) and Timoshenko model (···). For plate  $\mathcal{R}_1$  (a) and plate  $\mathcal{R}_2$  (b).

### 498 3.2. Effect on mean square velocity

499 The mean square velocity is a structural indicator of the radiation per-  
 500 formance, it is defined as the quadratic normal component of the structural  
 501 velocity integrated over the surface of the plate  $S$  as  $\tilde{v} = \sqrt{1/S \int_S |i\omega u|^2}$ .  
 502 The mean square velocity is calculated from this expression for both designs  
 503 with same location of excitation point as in the previous section 3.1.

504 As illustrated in Fig. 10, the global modes are correctly predicted by the  
 505 two models, especially in the low frequency region. However, strong disparity  
 506 appears around the inner resonance frequencies, and the homogenized model  
 507 shows better capability in predicting the gap induced by local resonance.  
 508 Indeed, it is derived as a beam grid enriched by local motion of internal  
 509 plates. As contrast between beam grid and plate constituents increases, the  
 510 amplitude of motion experienced by internal plates becomes much different  
 511 than that of the beam grid, leading to a poorer accuracy of Timoshenko  
 512 model and giving advantage to the homogenized model.



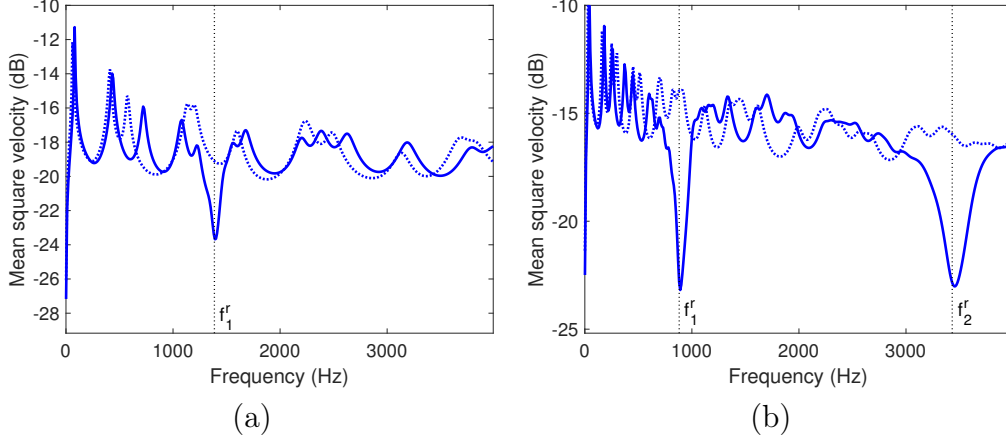


Figure 10: Mean square velocity (ref:1m/s/N) of orthotropic plate with inner resonance computed analytically from homogenized model (—) and Timoshenko model (···). For plate  $\mathcal{R}_1$  (a) and plate  $\mathcal{R}_2$  (b).

### 3.3. Effect on transmission loss

The transmission loss is here investigated by supplementing the previous model with simply supported plate. As for the structural part, the input vibratory field is the the same as the one calculated in section 3.1. As for the acoustic part, the notations are indicated in Fig. 2. The Rayleigh integral is implemented as it is known to be an efficient basis to calculate sound radiation from finite sized plane surface set into an infinite rigid baffle. The infinite baffle simplifies the general Helmholtz formulation so that only one integral is left, and the acoustic pressure is :

$$p(\mathbf{r}, \omega) = \frac{j\omega\rho}{2\pi} \iint_S \frac{v_n(\mathbf{r}_S) \exp(-ikR)}{R} dS \quad (23)$$

where  $v_n(\mathbf{r}_S)$  is the normal velocity field over the surface,  $k$  is the acoustic wavenumber and  $R = \|\mathbf{r}_S - \mathbf{r}\| = \sqrt{(x - x')^2 + (y - y')^2 + z'^2}$  is the distance between each elementary source point on the plate  $\mathbf{r}_S = (x, y, 0)$  and the receiver point  $\mathbf{r} = (x', y', z')$ . The sources are defined by subdividing the plate into a regular grid of  $100 \times 100$  elementary sources. For the calculation of transmission loss,  $z' \ll 1$ .

The results in terms of sound transmission loss are represented in Fig. 11. Since our phenomenon occurs in a narrow interval, the choice is made not to adopt the classical representation in third octave bands. For both plates,

we see that inner resonance introduces additional loss in the sound transmission. To best emphasize the locally resonant feature, it is compared as in Fig. 10 with the Timoshenko model to show the interval of differences. The homogenized model is also used with internal plates at rest, which does not correspond to a physical case but associated with a asymptotic behavior.

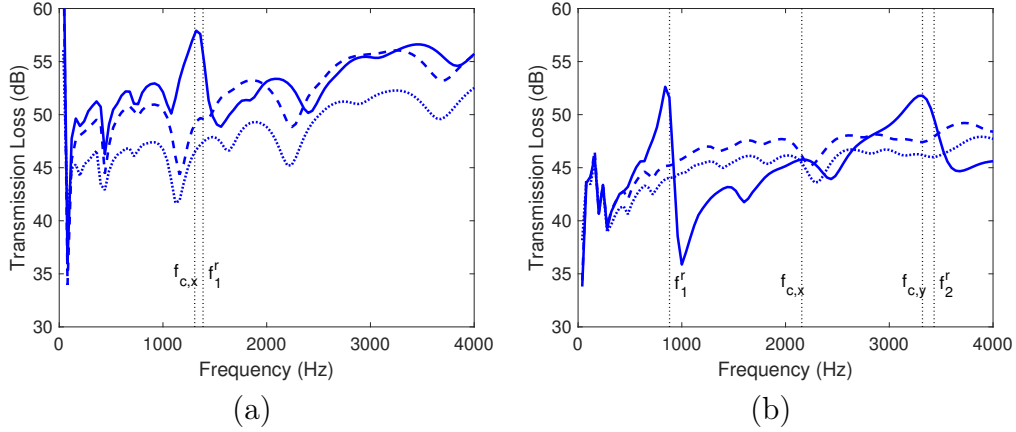


Figure 11: Transmission loss estimated analytically in case of finite plate, from homogenized model with resonant plates (—), homogenized with plates at rest (---), and from Timoshenko model (···). For plate  $\mathcal{R}_1$  (a) and plate  $\mathcal{R}_2$  (b).

## Conclusion

Based on explicit design rules and homogenized plate model, this paper brings phenomenological interpretation on the radiation of ribbed plates, and specifically focuses on the parallel between an homogenized analytical model of contrasted ribbed and its acoustic radiation compared to the Timoshenko orthotropic plate model. For ribbed plates with strong contrasts between constituents, it is firstly demonstrated that this model supplements Timoshenko model. The latter is suitable for ribbed plates in which the rigidity of the plate is introduced in the bending stiffness of the ribs, whereas the homogenized model can be seen as a beam grid whose dynamic behavior is corrected by the motion of vibrating internal plates. Investigations of the acoustic radiation from an infinite and finite orthogonally ribbed plate are based on two designs associated with strong and low contrast between constituents, in order to better exhibit the orthotropic nature of the plate.

551 As a preliminary comprehensive study case, the infinite plate case is pre-  
552 sented. The limit behavior of equivalent isotropic plates in the two directions  
553 of orthotropy are successfully identified. The radiation efficiency exhibits the  
554 transition from non-radiating to radiating domains marked out by the criti-  
555 cal frequency. The effect of the local resonance is also evidenced and results  
556 in an unconventional increase or reduction of the radiation below or above  
557 the critical frequency.

558 As a complementary case, analytical predictions of mean square veloc-  
559 ity and transmission loss are commented for finite plates. It comes out that  
560 the homogenized provides enhanced estimation of behavior in inner frequency  
561 ranges compared to Timoshenko model. The examination of the sound trans-  
562 mission loss demonstrates the attenuation in the neighborhood of inner res-  
563 onance.

564 Although the homogenization process could be further applied on various  
565 cell geometries, this paper specifically outlines the relevancy of the homog-  
566 enized model and demonstrates its ability to predict acoustic radiation of  
567 contrasted plates. The large amount of possible setups suggest adjustable  
568 resonant properties of the panel behavior, and offers the possibility of either  
569 broadband or narrow band attenuation.

## 570 CRediT author statement

571 **Pascal Fossat:** Conceptualization, Methodology, Software, Writing -  
572 original draft, Writing - review & editing. **Thomas Brion:** Methodology,  
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574 tion, Writing - review & editing, Validation, Project administration, Funding  
575 acquisition. **Olivier Bareille:** Supervision, Project administration, Funding  
576 acquisition.

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