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# Mathematical modeling of intra- and inter-species interactions in mixed malaria within-host infections 

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#### Abstract

Malaria poses a significant global health challenge, with millions of cases and fatalities reported annually, primarily in the WHO African Region and South-East Asia Region. Mixed-species malaria infections are common but often underestimated, even in regions with low transmission rates. Mathematical models have been instrumental in studying parasite multiplication within hosts during mixed malaria infections, yet existing models typically focus on either intra-species or inter-species dynamics separately. However, both intra- and inter-species diversity are crucial in within-host malaria infection dynamics. In this study, we introduce a mathematical model for intra-species and inter-species interactions between $P$. vivax and $P$. falciparum, exploring their co-infection dynamics within hosts. We establish the properties of the model and conduct invasibility analysis in a multi-species and multigenotypes framework. We also perform the uniform persistence of parasites over time within the host and discuss several typical scenarios that the model can simulate. Our findings shed light on the complex dynamics of malaria co-infections and their clinical implications.


Keywords: Malaria; Within-host dynamics; Mixed-species infections; Intra- and inter-species interactions; Mathematical modelling; Non-linear dynamical system.

## 1 Introduction

Malaria continues to pose a major public health challenge, with approximately 247 million cases and 619,000 fatalities reported globally in 2021 [1]. The World Health Organization (WHO) African Region bears the highest malaria burden, followed by the South-East Asia Region. Human malaria, caused by various Plasmodium species like $P$. falciparum and $P$. vivax, involves a complex life cycle with stages in both mosquitoes [3] and human or animal hosts [7, 18]. Mosquito bites transmit sporozoites into the bloodstream, which travel to the liver and infect hepatocytes [18]. After replication, merozoites are released into the bloodstream to invade red blood cells, leading to cycles of replication and rupture [33]. Some parasites become gametocytes [38], which complete the life cycle when ingested by mosquitoes. Mixed human malaria parasite infections are widespread globally, occurring even in areas with low transmission rates. A significant proportion of malaria infections within individual hosts involve multiple species of Plasmodium simultaneously [30]. Numerous studies have highlighted the prevalence of mixedspecies malaria infections in various locations worldwide, e.g. [2, 20, 24, 30, 39]. Despite this prevalence, mixed Plasmodium species infections are often overlooked or underestimated [6, 24, 30].

Mathematical models have played a key role in the study of parasite multiplication within hosts during mixed malaria infections. Previous studies have developed various models to explore infection dynamics, with some focusing on multiple genotypes of a single species within a host, e.g. [8, 11, 23, 46], while others investigate mixedspecies infection dynamics with single genotypes within a host [17]. If inter-species diversity (e.g. P. vivax or $P$. falciparum) has been highlighted by a recent modeling approach as a key factor in maintaining intra-host coinfections due to their distinct ecological trait for RBCs preferences [17], no study combines both this inter-species diversity with intra-species diversity (i.e. multiple genotypes of $P$. vivax and $P$. falciparum) within an intra-host infection.

## 2 The model description

We introduce a within-host interaction dynamics between young RBCs (reticulocytes), denoted as $C_{1}$, mature RBCs, denoted as $C_{2}$, and two malaria species $P$. vivax and $P$. falciparum. At any given time $t$, the density of malaria parasites (merozoites) for P. vivax and P. falciparum are represented by $m_{1}(t, x)$ and $m_{2}(t, x)$ respectively where the variable $x \in \mathbb{R}$ is designated as the strain label. The density of parasitized red blood cells by $P$. vivax and $P$. falciparum is denoted by $v_{1}(t, a, x)$ and $v_{2}(t, a, x)$, where the structural variable $a$ stands for the time post parasitization. The model we considered then reads :

$$
\left\{\begin{array}{l}
\frac{\mathrm{d} C_{1}(t)}{\mathrm{d} t}=\Lambda-\mu_{1,2} C_{1}(t)-C_{1}(t) \int_{\mathbb{R}} \beta_{1}(x) m_{1}(t, x) \mathrm{d} x-C_{1}(t) \int_{\mathbb{R}} \beta_{2}(x) m_{2}(t, x) \mathrm{d} x,  \tag{2.1}\\
\frac{\mathrm{~d} C_{2}(t)}{\mathrm{d} t}=\mu_{1,2} C_{1}(t)-\mu_{2} C_{2}(t)-C_{2}(t) \int_{\mathbb{R}} \beta_{2}(x) m_{2}(t, x) \mathrm{d} x, \\
v_{1}(t, a=0, x)=C_{1}(t) \beta_{1}(x) m_{1}(t, x), \\
v_{2}(t, a=0, x)=\left(C_{1}(t)+C_{2}(t)\right) \beta_{2}(x) m_{2}(t, x), \\
\frac{\partial v_{j}(t, a, x)}{\partial t}+\frac{\partial v_{j}(t, a, x)}{\partial a}=-\left(\mu_{2}+\gamma_{j}(a, x)\right) v_{j}(t, a, x), \\
\frac{\partial m_{j}(t, x)}{\partial t}=\int_{\mathbb{R}} k(x-y) p_{j}(y)\left(\int_{0}^{\infty} \gamma_{j}(a, y) v_{j}(t, a, y) \mathrm{d} a\right) \mathrm{d} y-\left(\mu_{m, j}+I_{j}(x)\right) m_{j}(t, x) .
\end{array}\right.
$$

In the system (2.1), the parameters $1 / \mu_{1,2}$ and $1 / \mu_{2}$ respectively represent the duration of the young and mature stages of RBCs, while $\Lambda$ denotes the production rate of RBCs from the bone marrow. Contacts between merozoites and uninfected RBCs occur at rate $\beta_{j}$. $P$. vivax exhibits a preference for targeting young RBC stages, whereas P. falciparum targets all RBC stages. The parameter $\mu_{m, j}$ represents the natural death rates for merozoites. The functions $\gamma_{j}(a, x)$ represent the additional death rate of parasitized RBCs by the $j$-species of strain $x$ at time $a$ post parasitization, resulting in rupture. The rupture, at age $a$, of parasitized RBCs by the $j$-species of strain $y$ produce merozoites of strain $x$ at rate $k(x-y) p_{j}(y) \gamma_{j}(a, y)$, where $k(x-y)$ is the probability of mutation from strain $y$ to strain $x$. Hence, mutations randomly shift strains in the phenotype space during each infection generation, following a mutation kernel $k$. Finally, the effect of the immune system on the $j$-species of strain $x$ is denoted by $I_{j}(x)$. We present a summary of state variables and model parameters in Table 1. System (2.1) is coupled with the

Table 1: Withing host model variables and parameters

| Param | Description (unit) | Values |
| :---: | :---: | :---: |
|  | State variables |  |
| $C_{1}(t)$ | density of reticulocytes at time $t$ (Cell/ml) |  |
| $C_{2}(t)$ | density of mature RBCs at time $t$ ( $\mathrm{Cell} / \mathrm{ml}$ ) |  |
| $v_{j}(t, a, x)$ | density of parasitized RBC -pRBC - by pathogens $x$ of $j$-species at time $t$ which are parasitized since time a (Cell/ml) |  |
| $m_{j}(t, x)$ | density of merozoites $x$ of $j$-species at time $t$ (Cell/ml) |  |
|  | Parameters |  |
| $\Lambda$ | Production rate of RBC (RBC/h/ml) | $1.73 \times 10^{6}[5,31]$ |
| $1 / \mu_{1,2}$ | Duration of the RBC reticulocyte stage (h) | 36 [31] |
| $1 / \mu_{2}$ | Duration of the RBC mature stage (days) | 116.5[31] |
| $\mu_{m, j}$ | Decay rates of malaria parasites of the $j$-species (RBC/day) | 48[22] |
| $\tau_{j}$ | Erythrocytic cycle duration of the $j$-species (h) | 48 for P. falciparum [37] <br> 48 for P. vivax [37] |
| $p_{j}^{\max }$ | Maximal number of merozoites produced per pRBC by the $j$-species | 16 [5, 37] |
| $p_{j}(x)$ | Number of merozoites with value $x$ produced per pRBC by the $j$-species | Defined by (8.2) |
| $\gamma_{j}(a, x)$ | Rupture rate of pRBCs by $x$ of species $j$ since time $a$ | Defined by (8.1) |
| $I_{j}(x)$ | Cross-immune reaction to parasite $x$ of $j$-species | Defined by (8.3) |
| $\beta_{1}(x)$ | Infection rate of pathogens $x$ of the species 1 ( $\mathrm{RBC} / \mathrm{ml} /$ day $)$ | $6.27 \times 10^{-7}$ |
| $\beta_{2}(x)$ | Infection rate of pathogens $x$ of the species 2 ( $\mathrm{RBC} / \mathrm{ml} /$ day $)$ | $6.27 \times 10^{-8}$ |
| $\frac{1}{\sigma_{j}^{2}}$ | Selectivity level within the $j$-malaria species | $\frac{1}{0.03^{2}}$ |
| Initial conditions |  |  |
| $C_{1,0}$ | Density of reticulocytes | $\Lambda / \mu_{1,2}$ |
| $C_{2,0}$ | Density of of mature RBCs | $\Lambda / \mu_{2}$ |
| $v_{j, 0}$ | Density of pRBCs of the $j$-species | 0 |

following initial condition:

$$
C_{j}(0)=C_{j, 0}, \quad v_{j}(0, a, x)=v_{j, 0}(a, x), \quad m_{j}(0, x)=m_{j, 0}(x)
$$

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Let us set

$$
C(t)=\left(C_{1}(t), C_{2}(t)\right), \quad m(t, x)=\left(m_{1}(t, x), m_{2}(t, x)\right), \quad v(t, a, x)=\left(v_{1}(t, a, x), v_{2}(t, a, x)\right)
$$

Then, System (2.1) rewrites as

$$
\left\{\begin{array}{l}
\frac{\mathrm{d} C(t)}{\mathrm{d} t}=\bar{\Lambda}-\mu C(t)-\operatorname{diag}\left(\int_{\mathbb{R}} \kappa_{m} \beta(y) m(t, y) \mathrm{d} y\right) C(t)  \tag{3.1}\\
v(t, a=0, x)=\operatorname{diag}(\beta(x) m(t, x)) \kappa_{m}^{T} C(t) \\
\quad\left(\partial_{t}+\partial_{a}\right) v(t, a, x)=-\left(\mu_{2} \mathrm{I}_{\mathrm{d}}+\gamma(a, x)\right) v(t, a, x) \\
\partial_{t} m(t, x)=\int_{\mathbb{R}} k(x-y) p(y) \int_{0}^{\infty} \gamma(a, y) v(t, a, y) \mathrm{d} a \mathrm{~d} y-(\nu+I(x)) m(t, x)
\end{array}\right.
$$

where $\bar{\Lambda}=(\Lambda, 0)^{T}, \nu=\operatorname{diag}\left(\mu_{m, j}\right)_{j \in\{1,2\}}, \beta=\operatorname{diag}\left(\beta_{j}\right)_{j \in\{1,2\}}, I=\operatorname{diag}\left(I_{j}\right)_{j \in\{1,2\}}, \gamma=\operatorname{diag}\left(\gamma_{j}\right)_{j \in\{1,2\}}, p=$ 78

## 3 Model's abstract formulation and overall assumptions

$\operatorname{diag}\left(p_{j}\right)_{j \in\{1,2\}}$,

$$
\mu=\left(\begin{array}{cc}
\mu_{1,2} & 0 \\
-\mu_{1,2} & \mu_{2}
\end{array}\right), \quad \kappa_{m}=\left(\begin{array}{cc}
1 & 1 \\
0 & 1
\end{array}\right)
$$

Let the Banach space $\mathcal{X}=\mathbb{R}^{2} \times L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right) \times L^{1}\left(\mathbb{R}_{+} \times \mathbb{R}, \mathbb{R}^{2}\right) \times L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)$, which is endowed with the usual product norm

$$
\left\|(C, f, v, m)^{T}\right\|_{\mathcal{X}}=\|C\|_{\mathbb{R}^{2}}+\|f\|_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)}+\|v\|_{L^{1}\left(\mathbb{R}_{+} \times \mathbb{R}, \mathbb{R}^{2}\right)}+\|m\|_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)}
$$

Let $A: \mathcal{D}(A) \subset \mathcal{X} \rightarrow \mathcal{X}$ the linear operator defined on the domain $\mathcal{D}(A):=\mathbb{R}^{2} \times\left\{0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)}\right\} \times \mathcal{D}_{v} \times L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)$ by

$$
A\left(\begin{array}{c}
C \\
0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)} \\
v \\
m
\end{array}\right)=\left(\begin{array}{c}
-\mu C \\
-v(0, \cdot) \\
-\partial_{a} v-\left(\mu_{2} \mathrm{I}_{\mathrm{d}}+\gamma\right) v \\
-(\nu+I) m
\end{array}\right)
$$

with

$$
\mathcal{D}_{v}:=\left\{v \in L^{1}\left(\mathbb{R}_{+} \times \mathbb{R}, \mathbb{R}^{2}\right): v(\cdot, x) \in W^{1,1}\left(\mathbb{R}_{+}, \mathbb{R}^{2}\right) \text { a.e } x \in \mathbb{R} \text { and } \partial_{a} v \in L^{1}\left(\mathbb{R}_{+} \times \mathbb{R}, \mathbb{R}^{2}\right)\right\}
$$

We then define the set

$$
\mathcal{X}_{0}=\overline{\mathcal{D}(A)}=\mathbb{R}^{2} \times\left\{0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)}\right\} \times L^{1}\left(\mathbb{R}_{+} \times \mathbb{R}, \mathbb{R}^{2}\right) \times L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)
$$

and we introduce the non-linear map $F: \mathcal{X}_{0} \rightarrow \mathcal{X}$ defined by

$$
F\left(\begin{array}{c}
C  \tag{3.2}\\
0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)} \\
v \\
m
\end{array}\right)=\left(\begin{array}{c}
\bar{\Lambda}-\operatorname{diag}\left(\int_{\mathbb{R}} \kappa_{m} \beta(y) m(y) \mathrm{d} y\right) C \\
\operatorname{diag}(\beta m) \kappa_{m}^{T} C, \\
\left.0_{L^{1}\left(\mathbb{R}^{\prime}\right.} \times \mathbb{R}, \mathbb{R}^{2}\right) \\
\int_{\mathbb{R}} k(\cdot-y) p(y) \int_{0}^{\infty} \gamma(a, y) v(a, y) \mathrm{d} a \mathrm{~d} y
\end{array}\right)
$$

Note that $\overline{\mathcal{D}(A)} \neq \mathcal{X}$ hence $A$ is a linear operator with a non-dense domain. Therefore, by identifying $u(t)$ as

$$
\left(C(t), 0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)}, v(t, \cdot, \cdot), m(t, \cdot)\right)^{T}
$$

and letting $u_{0} \in \mathcal{X}_{0}$ the associated initial condition, System (3.1) writes as the following abstract Cauchy problem:

$$
\left\{\begin{array}{l}
\frac{\mathrm{d} u(t)}{\mathrm{d} t}=A u(t)+F(u(t))  \tag{3.3}\\
u(0)=u_{0}
\end{array}\right.
$$ assumption

## Assumption 3.1.

1. For each $j \in\{1,2\}$, the constants $\Lambda, \mu_{1,2}, \mu_{2}$, and $\mu_{m, j}$ are positive, while the functions $I_{j}, \beta_{j}, p_{j} \in L_{+}^{\infty}(\mathbb{R})$ and $\gamma_{j} \in L_{+}^{\infty}\left(\mathbb{R}_{+} \times \mathbb{R}\right)$.
2. The kernel $k$ is a non-negative function satisfying $k \in L^{\infty}(\mathbb{R}) \cap L^{1}(\mathbb{R})$ and $\int_{\mathbb{R}} k(x) \mathrm{d} x=1$.

While Assumption 3.1 guarantees the global well-posedness of the bounded and dissipative semiflow of (3.3), achieving compactness of the trajectories generated by such a semiflow necessitates additional assumptions. Indeed, the compactness of the trajectories is related to the compactness of the linear operator $U: L^{1}\left(\mathbb{R}_{+} \times \mathbb{R}, \mathbb{R}^{2}\right) \rightarrow$ $L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)$

$$
U[v](x)=\int_{\mathbb{R}} k(x-y) p(y) \int_{0}^{\infty} \gamma(a, y) v(a, y) \mathrm{d} a \mathrm{~d} y
$$

Let $\mathcal{X}_{0+}=\mathcal{X}_{0} \cap \mathcal{X}_{+}$with $\mathcal{X}_{+}$the positive cone of $\mathcal{X}$. System (3.3) is considered under the following quite general

## Assumption 3.2.

1. The functions $p_{j}: \mathbb{R} \rightarrow \mathbb{R}_{+}$are continuous, not identically null and $\lim _{|x| \rightarrow \infty} p_{j}(x)=0$, for each $j \in\{1,2\}$.
2. For each $R>0$ the function $x \longmapsto \sup _{|y| \leq R} k(x+y)$ belongs to $L^{1}(\mathbb{R})$.

Furthermore, stationary states of System (3.3) are strongly related to the spectral properties of the linear operator $L_{j} \in \mathcal{L}\left(L^{1}(\mathbb{R})\right)$, defined for each $j \in\{1,2\}$ by

$$
\begin{equation*}
L_{j} w(x)=\int_{\mathbb{R}} k(x-y) \Gamma_{j}(y) w(y) \mathrm{d} y, \quad \forall w \in L^{1}(\mathbb{R}) \tag{3.4}
\end{equation*}
$$

wherein

$$
\begin{equation*}
\Gamma_{j}(y)=\frac{p_{j}(y) \beta_{j}(y)}{\mu_{m, j}+I_{j}(y)} \times \underbrace{\int_{0}^{\infty} \gamma_{j}(a, y) \Pi_{j}(0, a, y) \mathrm{d} a}_{\text {average parasite's development period }} \tag{3.5}
\end{equation*}
$$

captures the reproductive value of the parasite of strain $y$ within species $j$, and where we denote by

$$
\Pi_{j}(a, b, x)=\exp \left(-\int_{a}^{b}\left(\mu_{2}+\gamma_{j}(\ell, x)\right) \mathrm{d} \ell\right)
$$

the survival probability of RBCs infected by strain $x$ of species $j$ from time $a$ to $b$ since infection. In general, the compactness property of the linear operator $L_{j}$ above holds as soon as Assumption 3.2 is replaced by:

In this section, we handle the well-posedness of the system (2.1).

### 4.1 The main result

117 By setting $X:=\mathbb{R}^{2} \times L^{1}\left(\mathbb{R}_{+} \times \mathbb{R}, \mathbb{R}^{2}\right) \times L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)$, and $X_{+}:=\mathbb{R}_{+}^{2} \times L_{+}^{1}\left(\mathbb{R}_{+} \times \mathbb{R}, \mathbb{R}^{2}\right) \times L_{+}^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)$ its positive cone, the main result of this section reads:

Theorem 4.1. Let Assumption 3.1 be satisfied. Then,

1. Problem (2.1) generates a globally defined strongly continuous semiflow on $X_{+}$, denoted by $\Phi$ and defined by

$$
\begin{equation*}
\Phi: \mathbb{R}_{+} \times X_{+} \ni\left(t, \widehat{u}_{0}\right) \longmapsto \Phi_{t}\left(\widehat{u}_{0}\right)=(C(t), v(t, \cdot, \cdot), m(t, \cdot)) \tag{4.1}
\end{equation*}
$$

That is, for each $\widehat{u}_{0}=\left(C_{0}, v_{0}, m_{0}\right) \in X_{+}$, there exists a unique mild solution $(C, v, m) \in \mathcal{C}\left(\mathbb{R}_{+}, X_{+}\right)$. Furthermore, the set

$$
\mathcal{S}:=\left\{\begin{array}{l|l}
\left(C_{0}, v_{0}, m_{0}\right) \in X_{+}: & \begin{array}{l}
C_{1,0} \leq \frac{\Lambda}{\mu_{1,2}}, C_{2,0} \leq \frac{\Lambda}{\mu_{2}} \\
\sum_{j=1}^{2}\left(C_{j, 0}+\left\|v_{j, 0}\right\|_{L^{1}\left(\mathbb{R}_{+} \times \mathbb{R}\right)}\right) \leq \frac{\Lambda}{\mu_{1,2}}+\frac{\Lambda}{\mu_{2}} \\
\left\|m_{j, 0}\right\|_{L^{1}(\mathbb{R})} \leq \frac{\left\|\gamma_{j}\right\|_{\infty}\left\|p_{j}\right\|_{\infty}}{\mu_{m, j}}\left(\frac{\Lambda}{\mu_{1,2}}+\frac{\Lambda}{\mu_{2}}\right), \quad \forall j \in\{1,2\}
\end{array} \tag{4.2}
\end{array}\right\}
$$

is positively invariant with respect to the semi-flow $\Phi$ and for each $\widehat{u}_{0} \in X_{+}$, the solution defined by (4.1) satisfies

$$
\left\{\begin{array}{l}
\limsup _{t \rightarrow+\infty} C_{1}(t) \leq \frac{\Lambda}{\mu_{1,2}} \text { and } \limsup _{t \rightarrow+\infty} C_{2}(t) \leq \frac{\Lambda}{\mu_{2}} \\
\limsup _{t \rightarrow+\infty} \sum_{j=1}^{2}\left(C_{j}(t)+\left\|v_{j}(t, \cdot, \cdot)\right\|_{L^{1}(\mathbb{R}+\times \mathbb{R})}\right) \leq \frac{\Lambda}{\mu_{1,2}}+\frac{\Lambda}{\mu_{2}}
\end{array}\right.
$$

and for $j \in\{1,2\}$

$$
\limsup _{t \rightarrow+\infty}\left\|m_{j}(t, \cdot)\right\|_{L^{1}(\mathbb{R})} \leq \frac{\left\|\gamma_{j}\right\|_{\infty}\left\|p_{j}\right\|_{\infty}}{\mu_{m, j}}\left(\frac{\Lambda}{\mu_{1,2}}+\frac{\Lambda}{\mu_{2}}\right) .
$$

2. The semi-flow $\Phi$ is point (and bounded) dissipative, i.e. there exists a bounded set $K \subset X_{+}$, that attracts each point of $X_{+}$(and each bounded set of $X_{+}$) i.e. $d_{H}\left(\Phi_{t}(w), K\right) \underset{t \rightarrow \infty}{\longrightarrow} 0$ for each $w \in X_{+}\left(\right.$and $d_{H}\left(\Phi_{t}(B), K\right) \underset{t \rightarrow \infty}{\longrightarrow}$ 0 for any bounded set $\left.B \subset X_{+}\right)$, where $d_{H}$ is the Hausdorff semi-distance [21] defined by $d_{H}(B, K)=$ $\sup _{w \in B} \inf _{v \in K}\|w-v\|_{X}$.
3. In addition to Assumption 3.1, we also require the fulfilment of Assumption 3.2. Then, the semi-flow $\Phi$ is asymptotically smooth in $X_{+}$, i.e. for any nonempty, closed, bounded and positively invariant set $B \subset X_{+}$, there exists a compact set $K \subset X_{+}$such that $\lim _{t \rightarrow \infty} d_{H}\left(\Phi_{t}(B), K\right)=0$. It follows that there exists a global attractor.

### 4.2 Proof of Theorem 4.1

To prove Theorem 4.1, we need to set a suitable framework for using integrated semigroups (see e.g. [26] and the references therein). We start by giving the following result about the resolvent of $A$ which simply arises from the definition of the linear operator.

Lemma 4.2 (Resolvent). Suppose that Assumption 3.1 is satisfied. Then for each $\lambda \in \mathbb{C}$ such that $\Re(\lambda)>$ $-\min \left\{\mu_{1,2}, \mu_{2}, \mu_{m, 1}, \mu_{m, 2}\right\}$, the resolvent of $A$ is given by

$$
\left(\lambda \mathrm{I}_{\mathrm{d}}-A\right)^{-1}\left(\begin{array}{l}
u_{1} \\
u_{2} \\
u_{3} \\
u_{4}
\end{array}\right)=\left(\begin{array}{c}
C \\
0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)} \\
v \\
m
\end{array}\right) \in \mathcal{X}_{0}
$$

for every $\left(u_{1}, u_{2}, u_{3}, u_{4}\right)^{T} \in \mathcal{X}$, with

$$
\left\{\begin{array}{l}
C=\left(\lambda \mathrm{I}_{\mathrm{d}}+\mu\right)^{-1} u_{1} \\
v(a, x)=e^{-\int_{0}^{a}\left(\lambda \mathrm{I}_{\mathrm{d}}+\mu_{2} \mathrm{I}_{\mathrm{d}}+\gamma(l, x)\right) \mathrm{d} l} u_{2}(x)+\int_{0}^{a} e^{-\int_{s}^{a}\left(\lambda \mathrm{I}_{\mathrm{d}}+\mu_{2} \mathrm{I}_{\mathrm{d}}+\gamma(l, x)\right) \mathrm{d} l} u_{3}(s, x) \mathrm{d} s \\
m(x)=\left(\lambda \mathrm{I}_{\mathrm{d}}+\nu+I(x)\right)^{-1} u_{4}(x)
\end{array}\right.
$$

and consequently, $A$ is resolvent positive.
Let $A_{0}: \mathcal{D}\left(A_{0}\right) \subset \mathcal{X}_{0} \rightarrow \mathcal{X}$ be the part of $A$ on $\mathcal{X}_{0}$, that is the linear linear operator

$$
A_{0} u:=A u, \forall u \in \mathcal{D}\left(A_{0}\right)=\left\{u \in \mathcal{D}(A): A u \in \mathcal{X}_{0}\right\}
$$

We also have the following lemma.

Lemma 4.3. Suppose that Assumption 3.1 is satisfied. Then $A: \mathcal{D}(A) \subset \mathcal{X}_{0} \rightarrow \mathcal{X}$ is a Hille-Yosida linear operator. Furthermore, $\mathrm{s}\left(A_{0}\right)=\mathrm{s}(A)<0$ with $\mathrm{s}(A)$ (resp. $\mathrm{s}\left(A_{0}\right)$ ) the spectral bound of $A$ (resp. $A_{0}$ ), that is for $H \in\left\{A, A_{0}\right\}$

$$
\mathrm{s}(H):=\sup \{\Re(\lambda): \lambda \text { is in the spectral set of } H\}
$$

Consequently if $\omega_{A} \in\left(-\mathrm{s}\left(A_{0}\right), 0\right)$ there exists a constant $M_{A} \geq 1$ such that

$$
\left\|T_{A_{0}}(t)\right\|_{\mathcal{L}\left(\mathcal{X}_{0}\right)} \leq M_{A} e^{-\omega_{A} t}, \forall t \geq 0
$$

Proof. Considering the linear operators $A_{1}: \mathcal{D}(A) \rightarrow \mathcal{X}$ and $A_{2}: \mathcal{X}_{0} \rightarrow \mathcal{X}$ as follow

$$
A_{2}\left(\begin{array}{c}
C \\
0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)} \\
v \\
m
\end{array}\right)=\left(\begin{array}{c}
-\mu C \\
0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)} \\
0_{L^{1}\left(\mathbb{R}_{+} \times \mathbb{R}, \mathbb{R}^{2}\right)} \\
0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)}
\end{array}\right), \quad A_{1}:=A-A_{2}
$$

lead to the decomposition $A=A_{1}+A_{2}$. With Lemma 4.2 we see that

$$
\left\|\left(\lambda I_{d}-A_{1}\right)^{-1} u\right\|_{\mathcal{X}} \leq \frac{1}{\lambda+\omega_{0}}\|u\|_{\mathcal{X}}
$$

for each $u \in \mathcal{X}$ and $\lambda \in \mathbb{R}$ with $\lambda \geq-\omega_{0}$ and $\omega_{0}:=\min \left\{\mu_{1,2}, \mu_{2}, \mu_{m, 1}, \mu_{m, 2}\right\}$, leading to $\left\|\left(\lambda I_{d}-A_{1}\right)^{-n}\right\|_{\mathcal{L}(\mathcal{X})} \leq$ $\frac{1}{\left(\lambda+\omega_{0}\right)^{n}}$ for each $n \geq 1$ so that $A_{1}$ is a Hille-Yosida operator. Since $A_{2}$ is a bounded linear operator, it follows that $A$ is also a Hille-Yosida linear operator. Consequently, $A_{0}$, the part of $A$ on $\mathcal{X}_{0}$ generates a $C_{0}$-semigroup $\left\{T_{A_{0}}(t)\right\}_{t \geq 0}$ with growth bound $\omega\left(A_{0}\right) \in \mathbb{R}$. Next, we note that $\mathcal{X}_{0}$ is a AL-space implying that $\mathrm{s}\left(A_{0}\right)=\omega\left(A_{0}\right)$ [42, Theorem 3.14]. Recalling that [25, Lemma 2.1] $A$ and $A_{0}$ have the same spectral set, we conclude that $\mathrm{s}\left(A_{0}\right)=\mathrm{s}(A)$. The result follows from Lemma 4.2 and the fact that

$$
\mathrm{s}(A)=\inf \left\{\lambda \in \rho(A):(\lambda-A)^{-1} \mathcal{X}_{+} \subset \mathcal{X}_{0+}\right\}
$$

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### 4.2.1 Proof of items 1 and 2

The following proposition is devoted to items 1 and 2 of Theorem 4.1.
Proposition 4.4 (Global well-posedness, Boundedness, Dissipativity). Let Assumption 3.1 be satisfied. Then the by

$$
\begin{equation*}
U: \mathbb{R}_{+} \times X_{+} \ni\left(t, u_{0}\right) \longmapsto U(t) u_{0}=\left(C_{1}(t), C_{2}(t), 0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)}, v_{1}(t, \cdot, \cdot), v_{2}(t, \cdot, \cdot), m_{1}(t, \cdot), m_{2}(t, \cdot)\right)^{T} \tag{4.3}
\end{equation*}
$$

That is, for each $u_{0}=\left(C_{1,0}, C_{2,0}, 0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)}, v_{1,0}, v_{2,0}, m_{1,0}, m_{2,0}\right)^{T} \in \mathcal{X}_{0+}, U(\cdot) u_{0} \in \mathcal{C}\left(\mathbb{R}_{+}, \mathcal{X}_{0+}\right)$ is the unique mild solution to (3.3). Furthermore, the set $\mathcal{S}$ introduced by (4.2) is positively invariant with respect to the semiflow $U$ and for each $u_{0} \in \mathcal{X}_{0+}$, the solution defined by (4.3) satisfies

$$
\left\{\begin{array}{l}
\limsup _{t \rightarrow+\infty} C_{1}(t) \leq \frac{\Lambda}{\mu_{1,2}} \text { and } \limsup _{t \rightarrow+\infty} C_{2}(t) \leq \frac{\Lambda}{\mu_{2}} \\
\limsup _{t \rightarrow+\infty} \sum_{j=1}^{2}\left(C_{j}(t)+\left\|v_{j}(t, \cdot \cdot \cdot)\right\|_{L^{1}\left(\mathbb{R}_{+} \times \mathbb{R}\right)}\right) \leq \frac{\Lambda}{\mu_{1,2}}+\frac{\Lambda}{\mu_{2}}
\end{array}\right.
$$

and for $j \in\{1,2\}$

$$
\limsup _{t \rightarrow+\infty}\left\|m_{j}(t, \cdot)\right\|_{L^{1}(\mathbb{R})} \leq \frac{\left\|\gamma_{j}\right\|_{\infty}\left\|p_{j}\right\|_{\infty}}{\mu_{m, j}}\left(\frac{\Lambda}{\mu_{1,2}}+\frac{\Lambda}{\mu_{2}}\right)
$$

Proof. Thanks to Lemma 4.2 and Lemma 4.3, the linear operator $A$ is resolvent positive and a Hille-Yosida operator. The non-linear map $F$ is clearly continuous and locally Lipschitz due to Assumption 3.1. The local existence then follows from the classical result (see e.g. [27, Theorem 5.2.7, p. 226]). We now claim that

$$
\forall \varepsilon>0, \exists \lambda_{\varepsilon}: F(u)+\lambda_{\varepsilon} u \geq 0, \quad \forall u \in \mathcal{X}_{0+} \cap B_{\mathcal{X}}(0, \varepsilon)
$$

wherein $B_{\mathcal{X}}(0, \varepsilon)$ is the open ball in $\mathcal{X}$ centred at 0 with radius $\varepsilon$. Indeed, a sufficient condition for this inequality to hold is to choose $\lambda_{\varepsilon}$ such that

$$
\lambda_{\varepsilon} \geq \varepsilon\left(\left\|\beta_{1}\right\|_{\infty}+\left\|\beta_{2}\right\|_{\infty}\right)
$$

which proves the claim. It shows that the solution is non-negative due to [26, Proposition 5.3.2, p. 227]. We now prove the global existence. To this end, let $u_{0}=\left(C_{0}, 0, v_{0}(\cdot, \cdot), m_{0}(\cdot)\right)^{T} \in \mathcal{X}_{0+}$ be given. Then there exists $T_{\max } \in(0, \infty]$ such that if we set

$$
U(t) u_{0}=\left(C_{1}(t), C_{2}(t), 0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)}, v_{1}(t, \cdot, \cdot), v_{2}(t, \cdot, \cdot), m_{1}(t, \cdot), m_{2}(t, \cdot)\right),
$$

then for each $t \in\left[0, T_{\max }\right)$ and almost every $x \in \mathbb{R}$ we have

$$
v_{j}(t, a, x)= \begin{cases}v_{j, 0}(a-t, x) \Pi_{j}(a-t, a, x) & \text { if } t \leq a  \tag{4.4}\\ \left(\sum_{i=1}^{j} C_{i}(t-a)\right) \beta_{j}(x) m_{j}(t-a, x) \Pi_{j}(0, a, x) & \text { if } t>a\end{cases}
$$

and

$$
\left\{\begin{array}{l}
\frac{\mathrm{d} C_{1}(t)}{\mathrm{d} t}=\Lambda-\mu_{1,2} C_{1}(t)-C_{1}(t) \int_{\mathbb{R}} \beta_{1}(x) m_{1}(t, x) \mathrm{d} x-C_{1}(t) \int_{\mathbb{R}} \beta_{2}(x) m_{2}(t, x) \mathrm{d} x  \tag{4.5}\\
\frac{\mathrm{~d} C_{2}(t)}{\mathrm{d} t}=\mu_{1,2} C_{1}(t)-\mu_{2} C_{2}(t)-C_{2}(t) \int_{\mathbb{R}} \beta_{2}(x) m_{2}(t, x) \mathrm{d} x \\
\frac{\partial m_{j}(t, x)}{\partial t}=\int_{\mathbb{R}} k(x-y) p_{j}(y)\left(\int_{0}^{\infty} \gamma_{j}(a, y) v_{j}(t, a, y) \mathrm{d} a\right) \mathrm{d} y-\left(\mu_{m, j}+I_{j}(x)\right) m_{j}(t, x)
\end{array}\right.
$$

Note that using the $C_{1}$-equation we obtain

$$
\frac{\mathrm{d} C_{1}(t)}{\mathrm{d} t} \leq \Lambda-\mu_{1,2} C_{1}(t), \forall t \in\left[0, T_{\max }\right)
$$

from which we deduce that

$$
\begin{equation*}
C_{1}(t) \leq e^{-\mu_{1,2} t} C_{1,0}+\frac{\Lambda}{\mu_{1,2}}\left(1-e^{-\mu_{1,2} t}\right), \forall t \in\left[0, T_{\max }\right) \tag{4.6}
\end{equation*}
$$

so that

$$
\begin{equation*}
C_{1}(t) \leq M_{0}:=\max \left(C_{1,0}, \frac{\Lambda}{\mu_{1,2}}\right), \forall t \in\left[0, T_{\max }\right) \tag{4.7}
\end{equation*}
$$

Using (4.7), it follows from the $C_{2}$-equation of (4.5) that

$$
\begin{equation*}
\frac{\mathrm{d} C_{2}(t)}{\mathrm{d} t} \leq \mu_{1,2} C_{1}(t)-\mu_{2} C_{2}(t) \leq \mu_{1,2} M_{0}-\mu_{2} C_{2}(t), \forall t \in\left[0, T_{\max }\right) \tag{4.8}
\end{equation*}
$$

and by similar arguments we obtain

$$
\begin{equation*}
C_{2}(t) \leq M_{1}:=\max \left(C_{2,0}, \frac{\mu_{1,2} M_{0}}{\mu_{2}}\right), \forall t \in\left[0, T_{\max }\right) \tag{4.9}
\end{equation*}
$$

Next, summing the $C$-equations of (4.5) it follows that

$$
\frac{\mathrm{d}}{\mathrm{~d} t} \sum_{j=1}^{2} C_{j}(t)=\Lambda+\mu_{2} C_{1}(t)-\mu_{2} \sum_{j=1}^{2} C_{j}(t)-\sum_{j=1}^{2} \int_{\mathbb{R}} v_{j}(t, 0, x) \mathrm{d} x, \forall t \in\left(0, T_{\max }\right)
$$

From where we obtain for each $t \in\left[0, T_{\text {max }}\right)$

$$
\begin{equation*}
\sum_{j=1}^{2} C_{j}(t)=e^{-\mu_{2} t} \sum_{j=1}^{2} C_{j, 0}+\int_{0}^{t} e^{-\mu_{2}(t-a)}\left(\Lambda+\mu_{2} C_{1}(a)\right) \mathrm{d} a-\sum_{j=1}^{2} \int_{0}^{t} e^{-\mu_{2}(t-a)} \int_{\mathbb{R}} v_{j}(a, 0, x) \mathrm{d} x \mathrm{~d} a \tag{4.10}
\end{equation*}
$$

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Next, using (4.4) it follows that for each $t \in\left[0, T_{\max }\right)$

$$
\begin{align*}
\sum_{j=1}^{2} \int_{\mathbb{R}} \int_{0}^{\infty} v_{j}(t, a, x) \mathrm{d} a \mathrm{~d} x= & \sum_{j=1}^{2} \int_{\mathbb{R}} \int_{0}^{t} \Pi_{j}(0, a, x) v_{j}(t-a, 0, x) \mathrm{d} a \mathrm{~d} x  \tag{4.11}\\
& +\sum_{j=1}^{2} \int_{\mathbb{R}} \int_{t}^{\infty} v_{j, 0}(a-t, x) \Pi_{j}(a-t, a, x) \mathrm{d} a \mathrm{~d} x
\end{align*}
$$

Recalling that

$$
\Pi_{j}(a, \sigma, x) \leq e^{-\mu_{2}(\sigma-a)}, \forall \sigma \geq a \geq 0, x \in \mathbb{R}, j \in\{1,2\}
$$

we infer from (4.11) that for each $t \in\left[0, T_{\max }\right)$

$$
\begin{equation*}
\sum_{j=1}^{2} \int_{\mathbb{R}} \int_{0}^{\infty} v_{j}(t, a, x) \mathrm{d} a \mathrm{~d} x \leq \sum_{j=1}^{2} \int_{\mathbb{R}} \int_{0}^{t} e^{-\mu_{2}(t-a)} v_{j}(a, 0, x) \mathrm{d} a \mathrm{~d} x+e^{-\mu_{2} t} \sum_{j=1}^{2} \int_{\mathbb{R}} \int_{0}^{\infty} v_{j, 0}(a, x) \mathrm{d} a \mathrm{~d} x \tag{4.12}
\end{equation*}
$$

Therefore, setting

$$
R(t):=\sum_{j=1}^{2}\left(C_{j}(t)+\int_{\mathbb{R}} \int_{0}^{\infty} v_{j}(t, a, x) \mathrm{d} a \mathrm{~d} x\right), \forall t \in\left[0, T_{\max }\right)
$$

and summing (4.10) and (4.12) we obtain

$$
\begin{equation*}
R(t) \leq e^{-\mu_{2} t} R(0)+\int_{0}^{t} e^{-\mu_{2}(t-a)}\left(\Lambda+\mu_{2} C_{1}(a)\right) \mathrm{d} a, \forall t \in\left[0, T_{\max }\right) \tag{4.13}
\end{equation*}
$$

153 so that (4.7) combined with (4.13) implies

$$
\begin{equation*}
R(t) \leq M_{2}:=\max \left(R(0), \frac{\Lambda+\mu_{2} M_{0}}{\mu_{2}}\right), \forall t \in\left[0, T_{\max }\right) \tag{4.14}
\end{equation*}
$$

Thanks to (4.14), Assumption 3.1, and the $m_{j}$-equation in (4.5), we have for each $t \in\left[0, T_{\max }\right.$ )

$$
\frac{\mathrm{d}}{\mathrm{~d} t} \int_{\mathbb{R}} m_{j}(t, x) \mathrm{d} x \leq\left\|\gamma_{j}\right\|_{\infty}\left\|p_{j}\right\|_{\infty} M_{2}-\mu_{m, j} \int_{\mathbb{R}} m_{j}(t, x) \mathrm{d} x, j \in\{1,2\}
$$

so that

$$
\begin{equation*}
\int_{\mathbb{R}} m_{j}(t, x) \mathrm{d} x \leq \max \left(\frac{\left\|\gamma_{j}\right\|_{\infty}\left\|p_{j}\right\|_{\infty} M_{2}}{\mu_{m, j}}, \int_{\mathbb{R}} m_{j, 0}(x) \mathrm{d} x\right), j \in\{1,2\}, \forall t \in\left[0, T_{\max }\right) \tag{4.15}
\end{equation*}
$$

It is now clear from (4.7), (4.9), and (4.15) that for each $u_{0} \in \mathcal{X}_{0+}$ we have $T_{\max }:=T_{\max }\left(u_{0}\right)=+\infty$. Moreover, the positive invariance of the set $\mathcal{S}$ defined in (4.2) is a direct consequence of the estimates (4.7), (4.9), (4.14) and (4.15). Let us now prove the dissipativity of the semiflow generated by (3.3). To do so we first note that (4.6) implies that

$$
\begin{equation*}
\limsup _{t \rightarrow+\infty} C_{1}(t) \leq \frac{\Lambda}{\mu_{1,2}} \tag{4.16}
\end{equation*}
$$

Next, let $\epsilon>0$ be given. Thanks to (4.16) there exists $t_{0}:=t_{0}\left(\epsilon, u_{0}\right)>0$ such that

$$
\begin{equation*}
C_{1}(t) \leq \frac{\Lambda}{\mu_{1,2}}+\epsilon, \forall t \geq t_{0} \tag{4.17}
\end{equation*}
$$

Consequently, (4.8) and (4.17) imply that

$$
\frac{\mathrm{d} C_{2}(t)}{\mathrm{d} t} \leq \mu_{1,2}\left(\frac{\Lambda}{\mu_{1,2}}+\epsilon\right)-\mu_{2} C_{2}(t), \forall t \geq t_{0}
$$

that is

$$
\begin{equation*}
C_{2}(t) \leq e^{-\mu_{2}\left(t-t_{0}\right)} C_{2}\left(t_{0}\right)+\frac{\mu_{1,2}}{\mu_{2}}\left(\frac{\Lambda}{\mu_{1,2}}+\epsilon\right)\left(1-e^{-\mu_{2}\left(t-t_{0}\right)}\right), \forall t \geq t_{0} \tag{4.18}
\end{equation*}
$$

Recalling that $t \rightarrow C_{2}(t)$ is bounded on $[0,+\infty)$ it follows from (4.18) that

$$
\begin{equation*}
\limsup _{t \rightarrow+\infty} C_{2}(t) \leq \frac{\mu_{1,2}}{\mu_{2}}\left(\frac{\Lambda}{\mu_{1,2}}+\epsilon\right) \tag{4.19}
\end{equation*}
$$

Since $\epsilon>0$ is arbitrary in the above estimate (4.19) we conclude that

$$
\limsup _{t \rightarrow+\infty} C_{2}(t) \leq \frac{\Lambda}{\mu_{2}}
$$

To obtain the dissipativity concerning the $v_{j}$-components, we combine (4.7), (4.13), and (4.17) to obtain

$$
R(t) \leq e^{-\mu_{2} t} R(0)+\int_{0}^{t_{0}} e^{-\mu_{2}(t-a)}\left(\Lambda+\mu_{2} M_{0}\right) \mathrm{d} a+\int_{t_{0}}^{t} e^{-\mu_{2}(t-a)}\left(\Lambda+\mu_{2}\left(\frac{\Lambda}{\mu_{1,2}}+\epsilon\right)\right) \mathrm{d} a, \forall t \geq t_{0}
$$

from where

$$
\limsup _{t \rightarrow+\infty} R(t) \leq \frac{\Lambda}{\mu_{2}}+\frac{\Lambda}{\mu_{1,2}}+\epsilon
$$

Since $\epsilon>0$ can be chosen arbitrarily small we end up with

$$
\begin{equation*}
\limsup _{t \rightarrow+\infty} R(t) \leq \frac{\Lambda}{\mu_{2}}+\frac{\Lambda}{\mu_{1,2}} \tag{4.20}
\end{equation*}
$$

To complete the proof, we prove that the dissipativity holds along the $m_{j}$-components. To this end, we note that (4.20) implies that for each $\eta>0$, there exists $t_{1}:=t_{1}\left(\eta, u_{0}\right)>0$ such that $R(t) \leq \frac{\Lambda}{\mu_{2}}+\frac{\Lambda}{\mu_{1,2}}+\eta$ for all $t \geq t_{1}$. Consequently, we obtain from the $m_{j}$-equation that

$$
\frac{\mathrm{d}}{\mathrm{~d} t} \int_{\mathbb{R}} m_{j}(t, x) \mathrm{d} x \leq\left\|\gamma_{j}\right\|_{\infty}\left\|p_{j}\right\|_{\infty}\left(\frac{\Lambda}{\mu_{2}}+\frac{\Lambda}{\mu_{1,2}}+\eta\right)-\mu_{m, j} \int_{\mathbb{R}} m_{j}(t, x) \mathrm{d} x, j \in\{1,2\}, \forall t \geq t_{1}
$$

Using similar arguments as above, we obtain

$$
\limsup _{t \rightarrow+\infty} \int_{\mathbb{R}} m_{j}(t, x) \mathrm{d} x \leq \frac{\left\|\gamma_{j}\right\|_{\infty}\left\|p_{j}\right\|_{\infty}}{\mu_{m, j}}\left(\frac{\Lambda}{\mu_{2}}+\frac{\Lambda}{\mu_{1,2}}+\eta\right), \forall \eta>0
$$

The proof of Proposition 4.4 is completed.

### 4.2.2 Proof of item 3

 (2.1)), that is the third item of Theorem 4.1.Proposition 4.5 (Asymptotic smoothness of the semiflow). Let Assumptions 3.1 and 3.2 be satisfied. Then the nonlinear semiflow $\{U(t)\}_{t \geq 0}$ generated by (3.3) has the form

$$
U(t)=U_{1}(t)+U_{2}(t), \quad \forall t \geq 0
$$

with the following properties:
i) For each $t>0, U_{1}(t): \mathcal{X}_{0+} \rightarrow \mathcal{X}$, maps bounded sets of $\mathcal{X}_{0+}$ into relatively compact sets of $\mathcal{X}$;
ii) There exists $\xi:[0,+\infty) \times[0,+\infty) \rightarrow[0,+\infty)$ such that for each $\epsilon>0, \lim _{t \rightarrow+\infty} \xi(t, \epsilon) \rightarrow 0$ and if $u_{0} \in \mathcal{X}_{0+}$ with $\left\|u_{0}\right\|_{\mathcal{X}} \leq \epsilon$ then $\left\|U_{2}(t) u_{0}\right\|_{\mathcal{X}} \leq \xi(t, \epsilon)$ for all $t \geq 0$.

Proof. The proof of Proposition 4.5 will be given in a series of lemma. To this end, let us note that the nonlinear map $F$ defined in (3.2) can be written as $F=F_{1}+F_{2}$ where we have set for each $\left(C, 0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)}, v, m\right)^{T} \in \mathcal{X}_{0+}$

$$
F_{1}\left(\begin{array}{c}
C \\
0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)} \\
v \\
m
\end{array}\right)=\left(\begin{array}{c}
\bar{\Lambda}-\operatorname{diag}\left(\int_{\mathbb{R}} \kappa_{m} \beta(y) m(y) \mathrm{d} y\right) C \\
0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)}, \\
\left.0_{L^{1}\left(\mathbb{R}^{\infty}\right.} \times \mathbb{R}, \mathbb{R}^{2}\right) \\
\int_{\mathbb{R}} k(\cdot-y) p(y) \int_{0}^{\infty} \gamma(a, y) v(a, y) \mathrm{d} a \mathrm{~d} y
\end{array}\right)
$$

and

$$
F_{2}\left(\begin{array}{c}
C  \tag{4.21}\\
0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)} \\
v \\
m
\end{array}\right)=\left(\begin{array}{c}
0_{\mathbb{R}^{2}} \\
\operatorname{diag}(\beta m) \kappa_{m}^{T} C \\
0_{L^{1}\left(\mathbb{R}_{+} \times \mathbb{R}, \mathbb{R}^{2}\right)} \\
0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)}
\end{array}\right)
$$

It is worth noting that if Assumptions 3.1 and 3.3 are satisfied then $F_{1}$ maps bounded sets of $\mathcal{X}_{0+}$ into a relatively compact set of $\mathcal{X}_{0}$. Indeed, the first component of $F_{1}$ belongs to a finite-dimensional space while the last component

174 3.1 and 3.2 (see [14]). In the following, $B \subseteq \mathcal{X}_{0+}$ is a bounded subset of $\mathcal{X}_{0+}$. Recall that for each $u_{0} \in B$, the integrated (mild) solution $t \in[0,+\infty) \mapsto U(t) u_{0}$ of (3.3) is given by

$$
\begin{equation*}
U(t) u_{0}=T_{A_{0}}(t) u_{0}+\lim _{\lambda \rightarrow+\infty} \int_{0}^{t} T_{A_{0}}(t-s) \lambda(\lambda-A)^{-1} F\left(U(s) u_{0}\right) \mathrm{d} s, \forall t \geq 0 . \tag{4.22}
\end{equation*}
$$

Next, we define for each $u_{0} \in B$, the map $t \mapsto \hat{U}(t) u_{0}$ by

$$
\begin{equation*}
\hat{U}(t) u_{0}:=\lim _{\lambda \rightarrow+\infty} \int_{0}^{t} T_{A_{0}}(t-s) \lambda(\lambda-A)^{-1} F_{1}\left(U(s) u_{0}\right) \mathrm{d} s, t \geq 0 \tag{4.23}
\end{equation*}
$$

We also define the map $t \mapsto \check{U}(t) u_{0}$ as

$$
\begin{equation*}
\check{U}(t) u_{0}:=T_{A_{0}}(t) u_{0}, t \geq 0 \tag{4.24}
\end{equation*}
$$

and the map $t \mapsto \tilde{U}(t) u_{0}$ as

$$
\begin{equation*}
\tilde{U}(t) u_{0}:=\lim _{\lambda \rightarrow+\infty} \int_{0}^{t} T_{A_{0}}(t-s) \lambda(\lambda-A)^{-1} F_{2}\left(U(s) u_{0}\right) \mathrm{d} s, t \geq 0 \tag{4.25}
\end{equation*}
$$

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Let us note that the uniq
for each $u_{0} \in B$ we have

$$
\begin{equation*}
U(t) u_{0}=\hat{U}(t) u_{0}+\check{U}(t) u_{0}+\tilde{U}(t) u_{0}, \quad \forall t \geq 0 \tag{4.26}
\end{equation*}
$$

Note that using similar arguments to the proof of Proposition 4.4, one obtains that there exists $K_{0}:=K_{0}(B)>0$ such that

$$
\begin{equation*}
\sup _{t \geq 0, u_{0} \in B}\left\|U(t) u_{0}\right\|_{\mathcal{X}} \leq K_{0} \tag{4.27}
\end{equation*}
$$

Moreover, due to Lemma 4.3, the equality (4.24) and the boundedness of $B$, there exists $K_{1}:=K_{1}(B)>0$ such that

$$
\begin{equation*}
\sup _{u_{0} \in B}\left\|\check{U}(t) u_{0}\right\|_{\mathcal{X}} \leq e^{-\omega_{A} t} K_{1}, \quad \forall t \geq 0 \tag{4.28}
\end{equation*}
$$

We have the following lemma.

Lemma 4.6. Let Assumptions 3.1 and 3.2 be satisfied. Then, for each $T>0$, the set $\mathcal{B}:=\left\{\hat{U}(\cdot) u_{0} \in C\left([0, T], \mathcal{X}_{0}\right)\right.$ : $\left.u_{0} \in B\right\}$ is relatively compact in $C\left([0, T], \mathcal{X}_{0}\right)$.

Proof. Let $T>0$ be given and define $\mathcal{B}$ as in the Lemma. The proof will be done by using the Arzelà-Ascoli theorem. To do so, we have to prove that for each $t \geq 0$, the set $\mathcal{B}(t):=\left\{\hat{U}(t) u_{0}: u_{0} \in B\right\}$ is compact in $\mathcal{X}_{0}$ and $\mathcal{B}$ is an equicontinuous family. Let us note that $F_{1}\left(U(s) u_{0}\right) \in \mathcal{X}_{0}$ for all $s \geq 0, u_{0} \in B$ so that (4.23) becomes

$$
\hat{U}(t) u_{0}=\int_{0}^{t} T_{A_{0}}(t-s) F_{1}\left(U(s) u_{0}\right) \mathrm{d} s, \forall t \geq 0, \forall u_{0} \in B
$$

Thanks to (4.27) we can define the bounded set

$$
B_{0}:=\left\{U(t) u_{0}: t \geq 0, u_{0} \in B\right\}
$$

The compactness of $F_{1}$ implies that $F_{1}\left(B_{0}\right)$ is relatively compact. Recalling that $(s, y) \mapsto T_{A_{0}}(s) y$ is continuous, we deduce that the set

$$
\left\{T_{A_{0}}(t-s) F_{1}\left(U(s) u_{0}\right): s \in[0, t], u_{0} \in B\right\} \subset\left\{T_{A_{0}}(t-s) F_{1}(y): s \in[0, t], y \in B_{0}\right\}
$$

is relatively compact. By a theorem by Mazur, we conclude that for each $t>0$ the set

$$
\mathcal{B}(t)=\left\{\int_{0}^{t} T_{A_{0}}(t-s) F_{1}\left(U(s) u_{0}\right) \mathrm{d} s: u_{0} \in B\right\}
$$

is relatively compact. This proves that for each $t \geq 0$, the set $\mathcal{B}(t)$ is relatively compact. To complete the proof, we have to prove that $\mathcal{B}$ is equicontinuous. To this end, let $0 \leq t_{0} \leq t \leq T$ be given. Then we have

$$
\begin{aligned}
\hat{U}(t) u_{0}-\hat{U}\left(t_{0}\right) u_{0} & =\int_{t_{0}}^{t} T_{A_{0}}(t-s) F_{1}\left(U(s) u_{0}\right) \mathrm{d} s+\int_{0}^{t_{0}}\left[T_{A_{0}}(t-s)-T_{A_{0}}\left(t_{0}-s\right)\right] F_{1}\left(U(s) u_{0}\right) \mathrm{d} s \\
& =\int_{t_{0}}^{t} T_{A_{0}}(t-s) F_{1}\left(U(s) u_{0}\right) \mathrm{d} s+\int_{0}^{t_{0}}\left[T_{A_{0}}\left(t-t_{0}+s\right)-T_{A_{0}}(s)\right] F_{1}\left(U\left(t_{0}-s\right) u_{0}\right) \mathrm{d} s
\end{aligned}
$$

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$$
\begin{equation*}
\left\|\hat{U}(t) u_{0}-\hat{U}\left(t_{0}\right) u_{0}\right\|_{\mathcal{X}} \leq \sup _{y \in B_{0}}\left\|F_{1}(y)\right\|_{\mathcal{X}} \int_{t_{0}}^{t} M_{A} e^{-\omega_{A}(t-s)} \mathrm{d} s+t_{0} \sup _{s \in\left[0, t_{0}\right], y \in F_{1}\left(B_{0}\right)}\left\|T_{A_{0}}\left(t-t_{0}+s\right) y-T_{A_{0}}(s) y\right\|_{\mathcal{X}} \tag{4.29}
\end{equation*}
$$

The equicontinuity of $\mathcal{B}$ follows from (4.29) and the fact that $F_{1}\left(B_{0}\right)$ is relatively compact.
Due to (4.26)-(4.27) and Lemma 4.6, our Proposition 4.5 is a consequence of the following lemma.
Lemma 4.7. Let Assumptions 3.1 and 3.2 be satisfied. Then, the nonlinear maps $\{\tilde{U}(t)\}_{t \geq 0}$ defined in (4.25) has the form

$$
\tilde{U}(t)=\tilde{V}(t)+\tilde{Z}(t), \quad \forall t \geq 0
$$

with the following properties:
i) For each $t>0, \tilde{V}(t): \mathcal{X}_{0+} \rightarrow \mathcal{X}$, maps $B$ into relatively compact sets of $\mathcal{X}$;
ii) There exists a constant $\tilde{K}:=\tilde{K}(B)>0$ such that $\left\|\tilde{Z}(t) u_{0}\right\|_{\mathcal{X}} \leq \tilde{K}(1+t) e^{-\omega_{A}^{+} t}$, for all $t \geq 0$ and $u_{0} \in B$. The positive constant $\omega_{A}^{+}>0$ is defined as $\omega_{A}^{+}:=\min \left\{\omega_{A}, \mu_{2}\right\}$ with $\omega_{A}$ defined in Lemma 4.3.

Proof. Let us set for each $t \geq 0, u_{0} \in B$

$$
U(t) u_{0}:=\left(C_{1}^{u_{0}}(t), C_{2}^{u_{0}}(t), 0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)}, v_{1}^{u_{0}}(t, \cdot, \cdot), v_{2}^{u_{0}}(t, \cdot, \cdot), m_{1}^{u_{0}}(t, \cdot), m_{2}^{u_{0}}(t, \cdot)\right)
$$

and

$$
\left\{\begin{aligned}
& \hat{U}(t) u_{0}:=\left(\hat{C}_{1}^{u_{0}}(t), \hat{C}_{2}^{u_{0}}(t), 0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)}, \hat{v}_{1}^{u_{0}}(t, \cdot \cdot), \hat{v}_{2}^{u_{0}}(t, \cdot, \cdot), \hat{m}_{1}^{u_{0}}(t, \cdot), \hat{m}_{2}^{u_{0}}(t, \cdot)\right) \\
& \tilde{U}(t) u_{0}:=\left(\tilde{C}_{1}^{u_{0}}(t), \tilde{C}_{2}^{u_{0}}(t), 0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)}, \tilde{v}_{1}^{u_{0}}(t, \cdot, \cdot), \tilde{v}_{2}^{u_{0}}(t, \cdot, \cdot), \tilde{m}_{1}^{u_{0}}(t, \cdot), \tilde{m}_{2}^{u_{0}}(t, \cdot)\right) \\
& \check{U}(t) u_{0}:=\left(\check{C}_{1}^{u_{0}}(t), \check{C}_{2}^{u_{0}}(t), 0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)}, \check{v}_{1}^{u_{0}}(t, \cdot, \cdot), \check{v}_{2}^{u_{0}}(t, \cdot, \cdot), \check{m}_{1}^{u_{0}}(t, \cdot), \check{m}_{2}^{u_{0}}(t, \cdot)\right)
\end{aligned}\right.
$$

so that we get for each $t \geq 0, j \in\{1,2\}$ and $u_{0} \in B$ :

$$
\left\{\begin{align*}
C_{j}^{u_{0}}(t) & =\hat{C}_{j}^{u_{0}}(t)+\check{C}_{j}^{u_{0}}(t)+\tilde{C}_{j}^{u_{0}}(t),  \tag{4.30}\\
m_{j}^{u_{0}}(t, \cdot) & =\hat{m}_{j}^{u_{0}}(t, \cdot)+\check{m}_{j}^{u_{0}}(t, \cdot)+\tilde{m}_{j}^{u_{0}}(t, \cdot), \\
v_{j}^{u_{0}}(t, \cdot, \cdot) & =\hat{v}_{j}^{u_{0}}(t, \cdot, \cdot)+\check{v}_{j}^{u_{0}}(t, \cdot \cdot)+\tilde{v}_{j}^{u_{0}}(t, \cdot, \cdot) .
\end{align*}\right.
$$

Note that, using (4.28) we have for each $j \in\{1,2\}$ and $t \geq 0$ the following estimates

$$
\begin{cases}\sup _{u_{0} \in B}\left|\check{C}_{j}^{u_{0}}(t)\right| & \leq K_{1} e^{-\omega_{A} t}  \tag{4.31}\\ \sup _{u_{0} \in B}\left\|\check{m}_{j}^{u_{0}}(t, \cdot)\right\|_{L^{1}(\mathbb{R})} & \leq K_{1} e^{-\omega_{A} t},\end{cases}
$$

while (4.27) gives the following estimates

$$
\left\{\begin{array}{l}
\sup _{u_{0} \in B}\left|C_{j}^{u_{0}}(t)\right| \leq K_{0}, \forall t \geq 0  \tag{4.32}\\
\sup _{u_{0} \in B}\left\|m_{j}^{u_{0}}(t, \cdot)\right\|_{L^{1}(\mathbb{R})} \leq K_{0}, \forall t \geq 0
\end{array}\right.
$$

Using (4.21) and (4.25) it follows that $t \mapsto\left(\tilde{C}^{u_{0}}(t), \tilde{v}^{u_{0}}(t, \cdot, \cdot), \tilde{m}^{u_{0}}(t, \cdot)\right.$ satisfies, in the mild sense, the following system

$$
\left\{\begin{array}{l}
\frac{\mathrm{d} \tilde{C}^{u_{0}}(t)}{\mathrm{d} t}=-\mu \tilde{C}^{u_{0}}(t) \\
\tilde{v}^{u_{0}}(t, a=0, x)=\operatorname{diag}\left(\beta(x) m^{u_{0}}(t, x)\right) \kappa_{m}^{T} C^{u_{0}}(t), \\
\left(\partial_{t}+\partial_{a}\right) \tilde{v}^{u_{0}}(t, a, x)=-\left(\mu_{2} \mathrm{I}_{\mathrm{d}}+\gamma(a, x)\right) \tilde{v}^{u_{0}}(t, a, x), \\
\partial_{t} \tilde{m}^{u_{0}}(t, x)=-(\nu+I(x)) \tilde{m}^{u_{0}}(t, x)
\end{array}\right.
$$

with initial conditions $\tilde{C}^{u_{0}}(0)=0, \tilde{m}^{u_{0}}(0, \cdot)=0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)}$ and $\tilde{v}^{u_{0}}(0, \cdot, \cdot)=0_{L^{1}\left(\mathbb{R}+\times \mathbb{R}, \mathbb{R}^{2}\right)}$. Consequently, we have

$$
\begin{equation*}
\tilde{C}^{u_{0}}(t)=0, \quad \tilde{m}^{u_{0}}(t, \cdot)=0_{L^{1}\left(\mathbb{R}, \mathbb{R}^{2}\right)}, \quad \forall u_{0} \in B, \quad \forall t \geq 0 \tag{4.33}
\end{equation*}
$$

and for each $j \in\{1,2\}, t \geq 0, a \geq 0$ and $u_{0} \in B$ :

$$
\begin{equation*}
\tilde{v}_{j}^{u_{0}}(t, a, \cdot)=1_{[0, t]}(a) \beta_{j}(\cdot) \Pi_{j}(0, a, \cdot)\left(\sum_{i=1}^{j} C_{i}^{u_{0}}(t-a)\right) m_{j}^{u_{0}}(t-a, \cdot) \tag{4.34}
\end{equation*}
$$

Hence, we infer from (4.30) and (4.33) that for each $j \in\{1,2\}, t \geq 0$ and $u_{0} \in B$ :

$$
\left\{\begin{align*}
m_{j}^{u_{0}}(t, \cdot) & =\hat{m}_{j}^{u_{0}}(t, \cdot)+\check{m}_{j}^{u_{0}}(t, \cdot),  \tag{4.35}\\
C_{j}^{u_{0}}(t) & =\hat{C}_{j}^{u_{0}}(t)+\check{C}_{j}^{u_{0}}(t) .
\end{align*}\right.
$$

Moreover, using (4.35) we obtain from (4.31) and (4.32) that for each $j \in\{1,2\}$ and $t \geq 0$ :

$$
\begin{equation*}
\sup _{u_{0} \in B}\left|\hat{C}_{j}^{u_{0}}(t)\right| \leq K_{0}+K_{1} \tag{4.36}
\end{equation*}
$$

Next, note that using (4.34) and (4.35), we have for each $t \geq 0, a \geq 0, j \in\{1,2\}, x \in \mathbb{R}$ and $u_{0} \in B$ :

$$
\begin{aligned}
\tilde{v}_{j}^{u_{0}}(t, a, x)= & 1_{[0, t]}(a) \beta_{j}(x) \Pi_{j}(0, a, x)\left(m_{j}^{u_{0}}(t-a, x) \sum_{i=1}^{j} \check{C}_{i}^{u_{0}}(t-a)+\check{m}_{j}^{u_{0}}(t-a, x) \sum_{i=1}^{j} \hat{C}_{i}^{u_{0}}(t-a)\right) \\
& +1_{[0, t]}(a) \beta_{j}(x) \Pi_{j}(0, a, x) \sum_{i=1}^{j} \hat{C}_{i}^{u_{0}}(t-a) \hat{m}_{j}^{u_{0}}(t-a, x)
\end{aligned}
$$

so that for each $t \geq 0$ and $u_{0} \in B$ :

$$
\tilde{v}_{j}^{u_{0}}(t, \cdot, \cdot)=\tilde{w}_{j}^{u_{0}}(t, \cdot, \cdot)+\tilde{z}_{j}^{u_{0}}(t, \cdot, \cdot)
$$

where we have set for all $t \geq 0, a \geq 0$ and $u_{0} \in B$ :

$$
\begin{aligned}
\tilde{w}_{j}^{u_{0}}(t, a, x) & =1_{[0, t]}(a) \beta_{j}(x) \Pi_{j}(0, a, x)\left(m_{j}^{u_{0}}(t-a, x) \sum_{i=1}^{j} \check{C}_{i}^{u_{0}}(t-a)+\check{m}_{j}^{u_{0}}(t-a, x) \sum_{i=1}^{j} \hat{C}_{i}^{u_{0}}(t-a)\right) \\
\tilde{z}_{j}^{u_{0}}(t, a, x) & =1_{[0, t]}(a) \beta_{j}(x) \Pi_{j}(0, a, x)\left(\sum_{i=1}^{j} \hat{C}_{i}^{u_{0}}(t-a)\right) \hat{m}_{j}^{u_{0}}(t-a, x)
\end{aligned}
$$

Using (4.31), (4.32) and (4.36) it is easy to prove that there exists a constant $\tilde{K}_{1}>0$, depending only on $B$ such that

$$
\left\|\tilde{w}_{j}^{u_{0}}(t, \cdot, \cdot)\right\|_{L^{1}} \leq \tilde{K}_{1}(1+t) e^{-\min \left\{\omega_{A}, \mu_{2}\right\} t}, \forall t \geq 0, j \in\{1,2\}
$$

We now conclude the proof by proving that for each $t>0$, the set $\left\{\tilde{z}_{j}^{u_{0}}(t, \cdot, \cdot): u_{0} \in B\right\}$ is relatively compact in $L^{1}\left(\mathbb{R}_{+} \times \mathbb{R}\right)$. To do so, let $\left\{\tilde{z}_{j}^{n}(t, \cdot, \cdot): n \in \mathbb{N}\right\}$ be a bounded sequence in $\left\{\tilde{z}_{j}^{u_{0}}(t, \cdot, \cdot): u_{0} \in B\right\}$. Thanks to Lemma 4.6, the set $\left\{\hat{m}_{j}^{n}: n \in \mathbb{N}\right\}$ is compact in $C\left([0, t], L^{1}(\mathbb{R})\right)$ and $\left\{\hat{C}_{j}^{n}: n \in \mathbb{N}\right\}$ is compact in $C([0, t], \mathbb{R})$. Consequently, there exists $\hat{m}_{j}^{\infty} \in C\left([0, t], L^{1}(\mathbb{R})\right)$ and $\hat{C}_{j}^{\infty} \in C([0, t], \mathbb{R})$ such that

$$
\lim _{n \rightarrow+\infty} \hat{m}_{j}^{n}=\hat{m}_{j}^{\infty} \quad \text { in } C\left([0, t], L^{1}(\mathbb{R})\right)
$$

and

$$
\lim _{n \rightarrow+\infty} \hat{C}_{j}^{n}=\hat{C}_{j}^{\infty} \text { in } C([0, t], \mathbb{R})
$$

Next, setting for each $t \geq 0, a \geq 0, x \in \mathbb{R}$ :

$$
\tilde{z}_{j}^{\infty}(t, a, x)=1_{[0, t]}(a) \beta_{j}(x) \Pi_{j}(0, a, x) \sum_{i=1}^{j} \hat{C}_{i}^{\infty}(t-a) \hat{m}_{j}^{\infty}(t-a, x)
$$

it follows easily that

$$
\lim _{n \rightarrow+\infty} \tilde{z}_{j}^{n}(t, \cdot, \cdot)=\tilde{z}_{j}^{\infty}(t, \cdot, \cdot) \text { in } L^{1}\left(\mathbb{R}_{+} \times \mathbb{R}\right)
$$

This ends the proof of Proposition 4.5.
Finally, the simple use of [21, Lemma 3.2.3, p. 37] ends the proof of Theorem 4.1.

## 5 Stationary states

We investigate the existence of stationary states that are solutions $\left(C_{1}^{*}, C_{2}^{*}, v_{1}^{*}, v_{2}^{*}, m_{1}^{*}, m_{2}^{*}\right)$ of the following system with $j \in\{1,2\}$ :

$$
\left\{\begin{array}{l}
0=\Lambda-\mu_{1,2} C_{1}^{*}-C_{1}^{*} \int_{\mathbb{R}} \beta_{1}(x) m_{1}^{*}(x) \mathrm{d} x-C_{1}^{*} \int_{\mathbb{R}} \beta_{2}(x) m_{2}^{*}(x) \mathrm{d} x  \tag{5.1}\\
0=\mu_{1,2} C_{1}^{*}-\mu_{2} C_{2}^{*}-C_{2}^{*} \int_{\mathbb{R}} \beta_{2}(x) m_{2}^{*}(x) \mathrm{d} x \\
v_{j}^{*}(a=0, x)=\left(\sum_{i=1}^{j} C_{i}^{*}\right) \beta_{j}(x) m_{j}^{*}(x) \\
\partial_{a} v_{j}^{*}(a, x)=-\left(\mu_{2}+\gamma_{j}(a, x)\right) v_{j}^{*}(a, x), \\
\int_{\mathbb{R}} k(x-y) p_{j}(y)\left(\int_{0}^{\infty} \gamma_{j}(a, y) v_{j}^{*}(a, y) \mathrm{d} a\right) \mathrm{d} y=\left(\mu_{m, j}+I_{j}(x)\right) m_{j}^{*}(x)
\end{array}\right.
$$

The parasite-free equilibrium denoted by $E_{0}$ always exists and is defined by

$$
\begin{equation*}
E_{0}=\left(C_{1}^{E_{0}}, C_{2}^{E_{0}}, 0,0,0,0\right), \quad \text { with } \quad C_{1}^{E_{0}}=\frac{\Lambda}{\mu_{1,2}}, C_{2}^{E_{0}}=\frac{\Lambda}{\mu_{2}} \tag{5.2}
\end{equation*}
$$

The endemic stationary states rely on the spectral analysis of the linear operators $L_{j}$, defined by (3.4) whose properties have been reminded in Proposition 3.4. We define the following thresholds:

$$
\begin{equation*}
\mathcal{R}_{1}=\frac{\Lambda}{\mu_{1,2}} r\left(L_{1}\right), \quad \mathcal{R}_{2}=\left(\frac{\Lambda}{\mu_{1,2}}+\frac{\Lambda}{\mu_{2}}\right) r\left(L_{2}\right) \quad \text { and } \quad \mathcal{R}_{0}=\max \left\{\mathcal{R}_{1}, \mathcal{R}_{2}\right\} \tag{5.3}
\end{equation*}
$$

We can state the following result:
Theorem 5.1. Let Assumptions 3.1 and 3.3 be satisfied.

1. If $\mathcal{R}_{1}>1$, then System (2.1) has an equilibrium $E_{1}=\left(C_{1}^{E_{1}}, C_{2}^{E_{1}}, v_{1}^{E_{1}}, 0_{L^{1}\left(\mathbb{R}_{+} \times \mathbb{R}\right)}, m_{1}^{E_{1}}, 0_{L^{1}(\mathbb{R})}\right)$ where

$$
\begin{align*}
& C_{1}^{E_{1}}=\frac{C_{1}^{E_{0}}}{\mathcal{R}_{1}}, \quad C_{2}^{E_{1}}=\frac{C_{2}^{E_{0}}}{\mathcal{R}_{1}}, \quad v_{1}^{E_{1}}(a, x)=C_{1}^{E_{1}} \beta_{1}(x) m_{1}^{E_{1}}(x) \Pi_{1}(0, a, x), \\
& m_{1}^{E_{1}}(x)=\mu_{1,2}\left(\mathcal{R}_{1}-1\right)\left(\int_{\mathbb{R}} \frac{\beta_{1}(z) \phi_{1}(z)}{\mu_{m, 1}+I_{1}(z)} \mathrm{d} z\right)^{-1} \times \frac{\phi_{1}(x)}{\mu_{m, 1}+I_{1}(x)} \tag{5.4}
\end{align*}
$$

2. If $\mathcal{R}_{2}>1$, then System (2.1) has an equilibrium $E_{2}=\left(C_{1}^{E_{2}}, C_{2}^{E_{2}}, 0_{L^{1}(\mathbb{R}+\times \mathbb{R})}, v_{2}^{E_{2}}, 0_{L^{1}(\mathbb{R})}, m_{2}^{E_{2}}\right)$ where

$$
\begin{align*}
& C_{1}^{E_{2}}=\frac{\Lambda}{\mu_{1,2}+\int_{\mathbb{R}} \beta_{2}(z) m_{2}^{E_{2}}(z) \mathrm{d} z}, \quad C_{2}^{E_{2}}=\frac{\Lambda}{\mu_{1,2}+\int_{\mathbb{R}} \beta_{2}(z) m_{2}^{E_{2}}(z) \mathrm{d} z} \times \frac{\mu_{1,2}}{\mu_{2}+\int_{\mathbb{R}} \beta_{2}(z) m_{2}^{E_{2}}(z) \mathrm{d} z}, \\
& v_{2}^{E_{2}}(a, x)=\left(C_{1}^{E_{2}}+C_{2}^{E_{2}}\right) \beta_{2}(x) m_{2}^{E_{2}}(x) \Pi_{2}(0, a, x), \quad m_{2}^{E_{2}}(x)=\frac{\lambda_{2}}{\mu_{m, 2}+I_{2}(z)} \phi_{2}(x) \tag{5.5}
\end{align*}
$$

where $\lambda_{2}$ is the unique positive solution of the following equation

$$
1=\frac{\mu_{1,2} \Lambda r\left(L_{2}\right)}{\mu_{1,2}+\lambda_{2} \int_{\mathbb{R}} \frac{\beta_{2}(z) \phi_{2}(z)}{\mu_{m, 2}+I_{2}(z)} \mathrm{d} z}\left(\frac{1}{\mu_{1,2}}+\frac{1}{\mu_{2}+\lambda_{2} \int_{\mathbb{R}} \frac{\beta_{2}(z) \phi_{2}(z)}{\mu_{m, 2}+I_{2}(z)} \mathrm{d} z}\right)
$$

3. If the following assumption holds

$$
\begin{equation*}
1<\frac{\mathcal{R}_{2}}{\mathcal{R}_{1}}<1+\frac{\mu_{1,2}}{\mu_{2}} \quad \text { and } \quad \mathcal{R}_{1}>1+\left(1+\frac{\mu_{2}}{\mu_{1,2}}\right) \frac{\frac{\mathcal{R}_{2}}{\mathcal{R}_{1}}-1}{1+\frac{\mu_{1,2}}{\mu_{2}}-\frac{\mathcal{R}_{2}}{\mathcal{R}_{1}}} \tag{5.6}
\end{equation*}
$$

then System (2.1) has a unique positive equilibrium $E^{*}=\left(C_{1}^{E^{*}}, C_{2}^{E^{*}}, v_{1}^{E^{*}}, v_{2}^{E^{*}}, m_{1}^{E^{*}}, m_{2}^{E^{*}}\right)$ such that

$$
\left\{\begin{align*}
C_{1}^{E^{*}} & =\frac{\Lambda}{\mu_{1,2}+\sum_{k=1}^{2} \int_{\mathbb{R}} \beta_{k}(z) m_{k}^{E^{*}}(z) \mathrm{d} z}  \tag{5.7}\\
C_{2}^{E^{*}} & =\frac{\Lambda \mu_{1,2}}{\left(\mu_{1,2}+\sum_{k=1}^{2} \int_{\mathbb{R}} \beta_{k}(z) m_{k}^{E^{*}}(z) \mathrm{d} z\right)\left(\mu_{2}+\int_{\mathbb{R}} \beta_{2}(z) m_{2}^{E^{*}}(z) \mathrm{d} z\right)} \\
v_{1}^{E^{*}}(a, x) & =C_{1}^{E^{*}} \beta_{1}(x) m_{1}^{E^{*}}(x) \Pi_{1}(0, a, x), \\
v_{2}^{E^{*}}(a, x) & =\left(C_{1}^{E^{*}}+C_{2}^{E^{*}}\right) \beta_{2}(x) m_{2}^{E^{*}}(x) \Pi_{2}(0, a, x) \\
m_{1}^{E^{*}}(x) & =\frac{\lambda_{1}}{\mu_{m, 1}+I_{1}(x)} \phi_{1}(x) \\
m_{2}^{E^{*}}(x) & =\frac{\lambda_{2}}{\mu_{m, 2}+I_{2}(x)} \phi_{2}(x)
\end{align*}\right.
$$

where $\lambda_{1}$ and $\lambda_{2}$ are positive constants given by

$$
\lambda_{1}=\mu_{1,2} \frac{\mathcal{R}_{1}-\left(1+\frac{\lambda_{2}}{\mu_{1,2}} \int_{\mathbb{R}} \frac{\beta_{2}(z) \phi_{2}(z)}{\mu_{m, 2}+I_{2}(z)} \mathrm{d} z\right)}{\int_{\mathbb{R}} \frac{\beta_{1}(z) \phi_{1}(z)}{\mu_{m, 1}+I_{1}(z)} \mathrm{d} z}, \quad \lambda_{2}=\frac{\left(\mu_{1,2}+\mu_{2}\right)\left(\frac{\mathcal{R}_{2}}{\mathcal{R}_{1}}-1\right)}{\left(1+\frac{\mu_{1,2}}{\mu_{2}}-\frac{\mathcal{R}_{2}}{\mathcal{R}_{1}}\right) \int_{\mathbb{R}} \frac{\beta_{2}(z) \phi_{2}(z)}{\mu_{m, 2}+I_{2}(z)} \mathrm{d} z}
$$

We can observe that the stationary state $E_{1}$ corresponds to the scenario where only $P$. vivax is present, whereas only $P$. falciparum is present at the stationary state $E_{2}$. Both species can be found at the positive stationary state $E^{*}$, see Figure 1. Note that the condition (5.6) necessarily implies that $\mathcal{R}_{2}>\mathcal{R}_{1}>1$.


Figure 1: Qualitative view of areas for the existence of equilibria according to $\mathcal{R}_{1}$ and $\frac{\mathcal{R}_{2}}{\mathcal{R}_{1}}$. In zone 1 there is only $E_{0}$ since $\mathcal{R}_{0}<1$. Zone 2 is bounded by $\mathcal{R}_{1}>1$ and $\mathcal{R}_{2}<1$, whence $E_{0}$ and $E_{1}$ are present. Zone 3 is bounded by $\mathcal{R}_{1}<1$ and $\mathcal{R}_{2}>1$, so that $E_{0}$ and $E_{2}$ exist. In zones 4 and 5 , the conditions $\mathcal{R}_{1}>1$ and $\mathcal{R}_{2}>1$ are satisfied so that $E_{0}, E_{1}$ and $E_{2}$ are present in both zones. However, the condition (5.6) holds in zone 5 but not in zone 4 , whence $E^{*}$ is only present in zone 5 .

Proof.

1. At the stationary state $E_{1}$, System (5.1) rewrites

$$
\left\{\begin{align*}
0 & =\Lambda-\mu_{1,2} C_{1}^{E_{1}}-C_{1}^{E_{1}} \int_{\mathbb{R}} \beta_{1}(x) m_{1}^{E_{1}}(x) \mathrm{d} x  \tag{5.8}\\
0 & =\mu_{1,2} C_{1}^{E_{1}}-\mu_{2} C_{2}^{E_{1}} \\
v_{1}^{E_{1}}(0, x) & =C_{1}^{E_{1}} \beta_{1}(x) m_{1}^{E_{1}}(x) \\
\partial_{a} v_{1}^{E_{1}}(a, x) & =-\left(\mu_{2}+\gamma_{1}(a, x)\right) v_{1}^{E_{1}}(a, x) \\
0 & =\int_{\mathbb{R}} k(x-y) p_{1}(y)\left(\int_{0}^{\infty} \gamma_{1}(a, y) v_{1}^{E_{1}}(a, y) \mathrm{d} a\right) \mathrm{d} y-\left(\mu_{m, 1}+I_{1}(x)\right) m_{1}^{E_{1}}(x)
\end{align*}\right.
$$

The first two equations of (5.8) lead to

$$
C_{1}^{E_{1}}=C_{1}^{E_{0}} \frac{\mu_{1,2}}{\mu_{1,2}+\int_{\mathbb{R}} \beta_{1}(z) m_{1}^{E_{1}}(z) \mathrm{d} z}, \quad C_{2}^{E_{1}}=C_{2}^{E_{0}} \frac{\mu_{1,2}}{\mu_{1,2}+\int_{\mathbb{R}} \beta_{1}(z) m_{1}^{E_{1}}(z) \mathrm{d} z}
$$

and we have from the $v_{1}$-equation

$$
v_{1}^{E_{1}}(a, x)=C_{1}^{E_{1}} \beta(x) m_{1}^{E_{1}}(x) \Pi_{1}(0, a, x)
$$

Substituting the above expressions of $C_{1}^{E_{1}}$ and $v_{1}^{E_{1}}$ into the last equation of (5.8), it comes

$$
\begin{equation*}
\frac{\Lambda}{\mu_{1,2}+\int_{\mathbb{R}} \frac{\beta_{1}(z)}{\mu_{m, 1}+I_{1}(z)} \bar{m}_{1}(z) \mathrm{d} z} L_{1} \bar{m}_{1}(x)=\bar{m}_{1}(x) \tag{5.9}
\end{equation*}
$$

where we have set $\bar{m}_{1}=\left(\mu_{m, 1}+I_{1}\right) m_{1}^{E_{1}}$ and $L_{1}$ is the linear operator introduced by (3.4). Then, by Proposition 3.4 we find from (5.9) that $\bar{m}_{1}=\lambda_{1} \phi_{1}$, where $\lambda_{1}$ is a positive constant. Moreover, by (5.9) we have

$$
\frac{1}{r\left(L_{1}\right)}=\frac{\Lambda}{\mu_{1,2}+\lambda_{1} \int_{\mathbb{R}} \frac{\beta_{1}(z) \phi_{1}(z)}{\mu_{m, 1}+I_{1}(z)}} \mathrm{d} z .
$$

i.e.

$$
\lambda_{1}=\mu_{1,2}\left(\frac{\Lambda}{\mu_{1,2}} r\left(L_{1}\right)-1\right)\left(\int_{\mathbb{R}} \frac{\beta_{1}(z) \phi_{1}(z)}{\mu_{m, 1}+I_{1}(z)} \mathrm{d} z\right)^{-1}
$$

from which we obtain the equilibrium $E_{1}$ defined by (5.4).
2. Similarly, for the stationary state $E_{2}$ we have

$$
\begin{aligned}
C_{1}^{E_{2}} & =\frac{\Lambda}{\mu_{1,2}+\int_{\mathbb{R}} \beta_{2}(z) m_{2}^{E_{2}}(z) \mathrm{d} z}, \\
C_{2}^{E_{2}} & =\frac{\Lambda}{\mu_{1,2}+\int_{\mathbb{R}} \beta_{2}(z) m_{2}^{E_{2}}(z) \mathrm{d} z} \cdot \frac{\mu_{1,2}}{\mu_{2}+\int_{\mathbb{R}} \beta_{2}(z) m_{2}^{E_{2}}(z) \mathrm{d} z}, \\
v_{2}^{E_{2}}(a, x) & =\left(C_{1}^{E_{2}}+C_{2}^{E_{2}}\right) \beta_{2}(x) m_{2}^{E_{2}}(x) \Pi_{2}(0, a, x),
\end{aligned}
$$

and

$$
\begin{equation*}
\frac{\Lambda}{\mu_{1,2}+\int_{\mathbb{R}} \frac{\beta_{2}(z) \bar{m}_{2}(z)}{\mu_{m, 2}+I_{2}(z)} \mathrm{d} z}\left(1+\frac{\mu_{1,2}}{\mu_{2}+\int_{\mathbb{R}} \frac{\beta_{2}(z) \bar{m}_{2}(z)}{\mu_{m, 2}+I_{2}(z)} \mathrm{d} z}\right) L_{2} \bar{m}_{2}(x)=\bar{m}_{2}(x) \tag{5.10}
\end{equation*}
$$

where we have set $\bar{m}_{2}=\left(\mu_{m, 2}+I_{2}\right) m_{2}^{E_{2}}$ and $L_{2}$ is the linear operator defined by (3.4). Again from Proposition 3.4 we find from (5.10) that $\bar{m}_{2}=\lambda_{2} \phi_{2}$, where $\lambda_{2}$ is a positive constant. Moreover, by (5.10) we have

$$
\begin{equation*}
\frac{1}{r\left(L_{2}\right)}=\frac{\Lambda}{\mu_{1,2}+\lambda_{2} \int_{\mathbb{R}} \frac{\beta_{2}(z) \phi_{2}(z)}{\mu_{m, 2}+I_{2}(z)} \mathrm{d} z}\left(1+\frac{\mu_{1,2}}{\mu_{2}+\lambda_{2} \int_{\mathbb{R}} \frac{\beta_{2}(z) \phi_{2}(z)}{\mu_{m, 2}+I_{2}(z)} \mathrm{d} z}\right) \tag{5.11}
\end{equation*}
$$

The right-hand side of (5.11) is continuous and strictly decreasing in $\lambda_{2}$, so a necessary and sufficient condition to have a nontrivial endemic equilibrium is $\frac{1}{r\left(L_{2}\right)}<\frac{\Lambda}{\mu_{1,2}}\left(1+\frac{\mu_{1,2}}{\mu_{2}}\right)$, i.e. $\mathcal{R}_{2}>1$. This ends the computation of the equilibrium $E_{2}$ defined by (5.5). Note that an explicit expression of $\lambda_{2}$ reads

$$
\lambda_{2}=\frac{\mu_{2}+\mu_{1,2}\left(1-\frac{\Lambda r\left(L_{2}\right)}{\mu_{1,2}}\right)+\sqrt{\left(\mu_{2}+\mu_{1,2}\left(1-\frac{\Lambda r\left(L_{2}\right)}{\mu_{1,2}}\right)\right)^{2}+4 \mu_{1,2} \mu_{2}\left(\mathcal{R}_{2}-1\right)}}{2 \int_{\mathbb{R}} \frac{\beta_{2}(z) \phi_{2}(z)}{\mu_{m, 2}+I_{2}(z)} \mathrm{d} z} .
$$

3. From System (5.1), the positive equilibrium $E^{*}$ is such that

$$
\begin{aligned}
& C_{1}^{E^{*}}=\frac{\Lambda}{\mu_{1,2}+\sum_{k=1}^{2} \int_{\mathbb{R}} \beta_{k}(z) m_{k}^{E^{*}}(z) \mathrm{d} z} \\
& C_{2}^{E^{*}}=\frac{\Lambda \mu_{1,2}}{\left(\mu_{1,2}+\sum_{k=1}^{2} \int_{\mathbb{R}} \beta_{k}(z) m_{k}^{E^{*}}(z) \mathrm{d} z\right)\left(\mu_{2}+\int_{\mathbb{R}} \beta_{2}(z) m_{2}^{E^{*}}(z) \mathrm{d} z\right)} \\
& v_{1}^{E^{*}}(a, x)=C_{1}^{E^{*}} \beta_{1}(x) m_{1}^{E^{*}}(x) \Pi_{1}(0, a, x), \quad v_{2}^{E^{*}}(a, x)=\left(C_{1}^{E^{*}}+C_{2}^{E^{*}}\right) \beta_{2}(x) m_{2}^{E^{*}}(x) \Pi_{2}(0, a, x)
\end{aligned}
$$

Substituting the above estimates into the last equation of (5.1) we obtain the following system:

$$
\left\{\begin{array}{l}
\frac{\Lambda}{\mu_{1,2}+\sum_{j=1}^{2} \int_{\mathbb{R}} \frac{\beta_{j}(z)}{\mu_{m, j}+I_{j}(z)} \bar{m}_{j}(z) \mathrm{d} z} L_{1} \bar{m}_{1}(x)=\bar{m}_{1}(x),  \tag{5.12}\\
\frac{\Lambda}{\mu_{1,2}+\sum_{j=1}^{2} \int_{\mathbb{R}} \frac{\beta_{j}(z)}{\mu_{m, j}+I_{j}(z)} \bar{m}_{j}(z) \mathrm{d} z}\left(1+\frac{\mu_{1,2}}{\mu_{2}+\int_{\mathbb{R}} \frac{\beta_{2}(z)}{\mu_{m, 2}+I_{2}(z)} \bar{m}_{2}(z) \mathrm{d} z}\right) L_{2} \bar{m}_{2}(x)=\bar{m}_{2}(x)
\end{array}\right.
$$

where we have set $\bar{m}_{j}=\left(\mu_{m, j}+I_{j}\right) m_{j}^{E^{*}}$. We get $\bar{m}_{j}=\lambda_{j} \phi_{j}$ with positive constants $\lambda_{j}$. Furthermore, (5.12) gives

$$
\left\{\begin{array}{l}
\frac{1}{r\left(L_{1}\right)}=\frac{\Lambda}{\mu_{1,2}+\sum_{j=1}^{2} \lambda_{j} \int_{\mathbb{R}} \frac{\beta_{j}(z)}{\mu_{m, j}+I_{j}(z)} \phi_{j}(z) \mathrm{d} z} \\
\frac{1}{r\left(L_{2}\right)}=\frac{\Lambda}{\mu_{1,2}+\sum_{j=1}^{2} \lambda_{j} \int_{\mathbb{R}} \frac{\beta_{j}(z)}{\mu_{m, j}+I_{j}(z)} \phi_{j}(z) \mathrm{d} z}\left(1+\frac{\mu_{1,2}}{\mu_{2}+\lambda_{2} \int_{\mathbb{R}} \frac{\beta_{2}(z)}{\mu_{m, 2}+I_{2}(z)} \phi_{2}(z) \mathrm{d} z}\right)
\end{array}\right.
$$

i.e.

$$
\left\{\begin{align*}
1= & \mathcal{R}_{1} \frac{\mu_{1,2}}{\mu_{1,2}+\sum_{j=1}^{2} \lambda_{j} \int_{\mathbb{R}} \frac{\beta_{j}(z)}{\mu_{m, j}+I_{j}(z)} \phi_{j}(z) \mathrm{d} z}  \tag{5.13}\\
1= & \frac{\mathcal{R}_{2}\left(\frac{1}{\mu_{1,2}}+\frac{1}{\mu_{2}}\right)^{-1}}{\mathcal{R}_{1} \mu_{1,2}}\left(1+\frac{\mu_{1,2}}{\mu_{2}+\lambda_{2} \int_{\mathbb{R}} \frac{\beta_{2}(z)}{\mu_{m, 2}+I_{2}(z)} \phi_{2}(z) \mathrm{d} z}\right)
\end{align*}\right.
$$

The right-hand side of the second equation of (5.13) is continuous and strictly decreasing in $\lambda_{2}$. Thus, the necessary and sufficient condition for the existence of $\lambda_{2}>0$ reads:

$$
\frac{\mathcal{R}_{2}\left(\frac{1}{\mu_{1,2}}+\frac{1}{\mu_{2}}\right)^{-1}}{\mathcal{R}_{1} \mu_{1,2}}\left(1+\frac{\mu_{1,2}}{\mu_{2}}\right)>1 \text { and } \frac{\mathcal{R}_{2}\left(\frac{1}{\mu_{1,2}}+\frac{1}{\mu_{2}}\right)^{-1}}{\mathcal{R}_{1} \mu_{1,2}}<1
$$

that is equivalent to

$$
1<\frac{\mathcal{R}_{2}}{\mathcal{R}_{1}}<1+\frac{\mu_{1,2}}{\mu_{2}}
$$

Still from the second equation of (5.13), we obtain

$$
\lambda_{2} \int_{\mathbb{R}} \frac{\beta_{2}(z) \phi_{2}(z)}{\mu_{m, 2}+I_{2}(z)} \mathrm{d} z=\frac{\left(\mu_{1,2}+\mu_{2}\right)\left(\frac{\mathcal{R}_{2}}{\mathcal{R}_{1}}-1\right)}{\left(1+\frac{\mu_{1,2}}{\mu_{2}}\right)-\frac{\mathcal{R}_{2}}{\mathcal{R}_{1}}}
$$

It then remains to find $\lambda_{1}$. Note that the right-hand side of the first equation of (5.13) is continuous and strictly decreasing in $\lambda_{1}$. Thus, the necessary and sufficient condition for the existence of $\lambda_{1}>0$ is

$$
\frac{\mathcal{R}_{1} \mu_{1,2}}{\mu_{1,2}+\lambda_{2} \int_{\mathbb{R}} \frac{\beta_{2}(z) \phi_{2}(z)}{\mu_{m, 2}+I_{2}(z)} \mathrm{d} z}>1
$$

i.e.

$$
\mathcal{R}_{1}>1+\left(1+\frac{\mu_{2}}{\mu_{1,2}}\right) \frac{\frac{\mathcal{R}_{2}}{\mathcal{R}_{1}}-1}{1+\frac{\mu_{1,2}}{\mu_{2}}-\frac{\mathcal{R}_{2}}{\mathcal{R}_{1}}}
$$

and we have

$$
\lambda_{1}=\mu_{1,2} \frac{\mathcal{R}_{1}-\left(1+\frac{\lambda_{2}}{\mu_{1,2}} \int_{\mathbb{R}} \frac{\beta_{2}(z) \phi_{2}(z)}{\mu_{m, 2}+I_{2}(z)} \mathrm{d} z\right)}{\int_{\mathbb{R}} \frac{\beta_{1}(z) \phi_{1}(z)}{\mu_{m, 1}+I_{1}(z)} \mathrm{d} z} .
$$

The computation of the positive stationary state $E^{*}$, defined by (5.7), concludes here.

## 6 Basic reproduction numbers and invasion fitness

The basic reproduction number, commonly represented as $\mathcal{R}_{0}$, is defined within this context as the total number of new malaria parasites originating from a single parasite introduced into a parasite-free RBCs environment [4, 12]. In an initially unparasitized RBCs population, this metric can ascertain the potential for a parasite strain to propagate within that RBCs environment. Conversely, when the RBCs population is initially colonized by a resident parasite strain, the invasion fitness is employed to assess whether a new parasite strain can successfully invade this RBCs environment or not. In this context, the calculation of both the $\mathcal{R}_{0}$ and the invasion fitness relies on the nextgeneration operator approach $[12,43]$ and the standard adaptive dynamics methodology [13, 19, 32, 35].

### 6.1 The basic reproduction number

Proposition 6.1. Let Assumption 3.1 holds.

1. Let $j \in\{1,2\}$. The basic reproduction number of strain $x$ within the $j$-species, denoted by $\mathcal{R}_{j}(x)$, is such that

$$
\begin{equation*}
\mathcal{R}_{j}(x)=\left(\sum_{i=1}^{j} C_{i}^{E_{0}}\right) \int_{\mathbb{R}} k(x-y) \Gamma_{j}(y) \mathrm{d} y \tag{6.1}
\end{equation*}
$$

where $\Gamma_{j}$ is the reproduction function introduced by (3.5) and the constants $C_{i}^{E_{0}}$ are defined by (5.2).
2. For each $j \in\{1,2\}$ the threshold quantity $\mathcal{R}_{j}$ introduced by (5.3) is the basic reproduction number of the $j$-species, while $\mathcal{R}_{0}$ defined by (5.3) is the basic reproduction number of System (2.1).

Proof. Let $j \in\{1,2\}$. Let us denote by $b_{j}(t, x)$ the number of parasites, of strain $x$ within the species $j$, that are newly produced at time $t$. From (2.1) we get

$$
b_{j}(t, x)=\int_{\mathbb{R}} k(x-y) p_{j}(y)\left(\int_{0}^{\infty} \gamma_{j}(a, y) v_{j}(t, a, y) \mathrm{d} a\right) \mathrm{d} y
$$

Then, linearizing the system (2.1) around the parasite-free stationary state $E_{0}$, and using Volterra's formulation, we obtain

$$
v_{j}(t, a, x)= \begin{cases}v_{j, 0}(a-t, x) \Pi_{j}(a-t, a, x) & \text { if } t \leq a \\ \left(\sum_{i=1}^{j} C_{i}^{E_{0}}\right) \beta_{j}(x) m_{j}(t-a, x) \Pi_{j}(0, a, x) & \text { if } t>a\end{cases}
$$

Therefore,

$$
\begin{align*}
b_{j}(t, x)= & \left(\sum_{i=1}^{j} C_{i}^{E_{0}}\right) \int_{\mathbb{R}} k(x-y) p_{j}(y) \beta_{j}(y)\left(\int_{0}^{t} \gamma_{j}(a, y) m_{j}(t-a, y) \Pi_{j}(0, a, y) \mathrm{d} a\right) \mathrm{d} y \\
& +\int_{\mathbb{R}} k(x-y) p_{j}(y)\left(\int_{t}^{\infty} \gamma_{k}(a, y) v_{j, 0}(a-t, x) \Pi_{j}(a-t, a, y) \mathrm{d} a\right) \mathrm{d} y \tag{6.2}
\end{align*}
$$

Furthermore, we have

$$
m_{j}(t, x)=e^{-\left(\mu_{m, j}+I_{j}(x)\right) t} m_{j, 0}(x)+\int_{0}^{t} e^{-\left(\mu_{m, j}+I_{j}(x)\right)(t-s)} b_{j}(s, x) \mathrm{d} s
$$

By the above expression, (6.2) rewrites as follows
$b_{j}(t, x)=\left(\sum_{i=1}^{j} C_{i}^{E_{0}}\right) \int_{\mathbb{R}} k(x-y) p_{j}(y) \beta_{j}(y) \int_{0}^{t} \gamma_{j}(a, y) \Pi_{j}(0, a, y) \int_{0}^{t-a} e^{-\left(\mu_{m, j}+I_{j}(y)\right)(t-a-s)} b_{j}(s, y) \mathrm{d} s \mathrm{~d} a \mathrm{~d} y+g_{j}(t, x)$
where $g_{j}(t, x)$ accounts for the number of parasites produced by the initial condition:

$$
\begin{aligned}
g_{j}(t, x)= & \left(\sum_{i=1}^{j} C_{i}^{E_{0}}\right) \int_{\mathbb{R}} k(x-y) p_{j}(y) \beta_{j}(y)\left(\int_{0}^{t} e^{-\left(\mu_{m, j}+I_{j}(y)\right)(t-a)} m_{j, 0}(y) \gamma_{j}(a, y) \Pi_{j}(0, a, y) \mathrm{d} a\right) \mathrm{d} y \\
& +\int_{\mathbb{R}} k(x-y) p_{j}(y)\left(\int_{t}^{\infty} \gamma_{k}(a, y) v_{j, 0}(a-t, x) \Pi_{j}(a-t, a, y) \mathrm{d} a\right) \mathrm{d} y
\end{aligned}
$$

Since

$$
p_{j}(y) \beta_{j}(y) \int_{0}^{t} \gamma_{j}(a, y) \Pi_{j}(0, a, y) \int_{0}^{t-a} e^{-\left(\mu_{m, j}+I_{j}(y)\right)(t-a-s)} b_{j}(s, y) \mathrm{d} s \mathrm{~d} a=\int_{0}^{t} b_{j}(t-a, y) F_{j}(a, y) \mathrm{d} a
$$

wherein

$$
F_{j}(a, y)=e^{-\left(\mu_{m, j}+I_{j}(y)\right) a} p_{j}(y) \beta_{j}(y) \int_{0}^{a} \gamma_{j}(s, y) \Pi_{j}(0, s, y) e^{\left(\mu_{m, j}+I_{j}(y)\right) s} \mathrm{~d} s
$$

then the equality (6.3) becomes

$$
b_{j}(t, x)=\left(\sum_{i=1}^{j} C_{i}^{E_{0}}\right) \int_{0}^{t} \int_{\mathbb{R}} k(x-y) F_{j}(a, y) b_{j}(t-a, y) \mathrm{d} y \mathrm{~d} a+g_{j}(t, x)
$$

Given the formulation above, the basic reproduction number $\mathcal{R}_{j}(x)$ of strain $x$ within the $j$-species is computed as the spectral radius $r\left(G_{j}[x]\right)$ of the next-generation operator $G_{j}[x]$, as defined by:

$$
G_{j}[x]: L^{1}(\mathbb{R}) \ni v \mapsto\left(\sum_{i=1}^{j} C_{i}^{E_{0}}\right) \int_{0}^{\infty} \int_{\mathbb{R}} k(x-y) F_{j}(a, y) v(y) \mathrm{d} y \mathrm{~d} a \in \mathbb{R}
$$

Then it comes that

$$
\mathcal{R}_{j}(x)=\left(\sum_{i=1}^{j} C_{i}^{E_{0}}\right) \int_{0}^{\infty} \int_{\mathbb{R}} k(x-y) F_{j}(a, y) \mathrm{d} y \mathrm{~d} a=\left(\sum_{i=1}^{j} C_{i}^{E_{0}}\right) \int_{\mathbb{R}} k(x-y) \Gamma_{j}(y) \mathrm{d} y
$$

where the last equality comes from $\int_{0}^{\infty} F_{j}(a, y) \mathrm{d} a=\Gamma_{j}(y)<\infty$, with $\Gamma_{j}$ the reproduction function introduced by (3.5). We now introduce the linear operator $G_{j}$, such that

$$
G_{j}(v)(x)=G_{j}[x] v, \quad \forall v \in L^{1}(\mathbb{R}), \quad \forall x \in \mathbb{R}
$$

Observe that $G_{j}=\left(\sum_{i=1}^{j} C_{i}^{E_{0}}\right) L_{j}$, where $L_{j}$ is the linear operator introduced by (3.4). Then, the basic reproduction number of the $j$-species is calculated as the spectral radius of the next generation operator $G_{j}$, i.e.

$$
r\left(G_{j}\right)=\left(\sum_{i=1}^{j} C_{i}^{E_{0}}\right) r\left(L_{j}\right)
$$

Note that the spectral radius of $G_{j}$ satisfies $r\left(G_{j}\right)=\mathcal{R}_{j}$, where $\mathcal{R}_{j}$ is the threshold parameter introduced by (5.3), which proves the first point. In addition, the next generation operator of the overall system is $G=\operatorname{diag}\left(G_{1}, G_{2}\right)$, so that the basic reproduction number $\mathcal{R}_{0}$ of System (2.1) is given by

$$
\mathcal{R}_{0}=\max \left\{\mathcal{R}_{1}, \mathcal{R}_{2}\right\} .
$$

### 6.2 Invasion in a parasitized RBCs environment

Let us introduce the notation $\left(x_{1}, x_{2}\right)$ to represent a parasite population, where $x_{1}$ denotes the parasite strain of the first species (i.e. P. vivax) and $x_{2}$ represents the parasite strain of the second species (i.e. P. falciparum). The notation $\left(x_{1}, \emptyset\right)$ indicates the absence of the second species, whereas ( $\left.\emptyset, x_{2}\right)$ signifies the absence of the first species. We also denote by $f_{\left(x_{1}, x_{2}\right)}\left(y_{1}, y_{2}\right)$ the invasion fitness of a mutant with phenotype $\left(y_{1}, y_{2}\right)$ in the resident population set by the equilibrium $E^{\left(x_{1}, x_{2}\right)}$ of phenotype $\left(x_{1}, x_{2}\right)$. Then $f_{\left(x_{1}, x_{2}\right)}\left(y_{1}, y_{2}\right)=\left(f_{\left(x_{1}, x_{2}\right)}^{1}\left(y_{1}\right), f_{\left(x_{1}, x_{2}\right)}^{2}\left(y_{2}\right)\right)$, where $f_{\left(x_{1}, x_{2}\right)}^{j}\left(y_{j}\right)$ is the invasion fitness of a mutant of strain $y_{j}$ within $j$-species in the resident population set by the equilibrium $E^{\left(x_{1}, x_{2}\right)}$ of strain $\left(x_{1}, x_{2}\right)$. Hence, a mutant strain $y_{j}$ within the $j$-species in the resident population, as defined by the equilibrium $E^{\left(x_{1}, x_{2}\right)}$, will spread whenever $f_{\left(x_{1}, x_{2}\right)}^{j}\left(y_{j}\right)>0$. We then have the following results of the invasion fitness:

Proposition 6.2. Let Assumptions 3.1 and 3.3 be satisfied. Let us define the following thresholds:

$$
\mathcal{R}_{1}^{x_{1}}=C_{1}^{E_{0}} \Gamma_{1}\left(x_{1}\right) \quad \text { and } \quad \mathcal{R}_{2}^{x_{2}}=\left(C_{1}^{E_{0}}+C_{2}^{E_{0}}\right) \Gamma_{2}\left(x_{2}\right)
$$

1. Scenario 1: both species (i.e. P. vivax and P. falciparum) are the resident. Assume that

$$
1<\frac{\mathcal{R}_{2}^{x_{2}}}{\mathcal{R}_{1}^{x_{1}}}<1+\frac{\mu_{1,2}}{\mu_{2}} \quad \text { and } \quad \mathcal{R}_{1}^{x_{1}}>1+\left(1+\frac{\mu_{2}}{\mu_{1,2}}\right)\left(\frac{\frac{\mathcal{R}_{2}^{x_{2}}}{\mathcal{R}_{1}^{x_{1}}}-1}{\left(1+\frac{\mu_{1,2}}{\mu_{2}}\right)-\frac{\mathcal{R}_{2}^{x_{2}}}{\mathcal{R}_{1}^{x_{1}}}}\right) .
$$

The above condition ensures the existence of the resident equilibrium $E^{\left(x_{1}, x_{2}\right)}$ and we have

$$
f_{\left(x_{1}, x_{2}\right)}\left(y_{1}, y_{2}\right)=\binom{\frac{C_{1}^{\left(x_{1}, x_{2}\right)}}{C_{1}^{E_{0}}}\left(\mathcal{R}_{1}^{y_{1}}-\mathcal{R}_{1}^{x_{1}}\right)}{\frac{\sum_{i=1}^{2} C_{i}^{\left(x_{1}, x_{2}\right)}}{\sum_{i=1}^{2} C_{i}^{E_{0}}}\left(\mathcal{R}_{2}^{y_{2}}-\mathcal{R}_{2}^{x_{2}}\right)}
$$

with $C_{1}^{\left(x_{1}, x_{2}\right)}$ and $C_{2}^{\left(x_{1}, x_{2}\right)}$ respectively the size of young and mature $R B C$ s in the environment set by the resident. Hence, we have

$$
\begin{equation*}
\operatorname{sign}\left(f_{\left(x_{1}, x_{2}\right)}^{1}\left(y_{1}\right)\right)=\operatorname{sign}\left(\mathcal{R}_{1}^{y_{1}}-\mathcal{R}_{1}^{x_{1}}\right) \quad \text { and } \quad \operatorname{sign}\left(f_{\left(x_{1}, x_{2}\right)}^{2}\left(y_{2}\right)\right)=\operatorname{sign}\left(\mathcal{R}_{2}^{y_{2}}-\mathcal{R}_{2}^{x_{2}}\right) . \tag{6.4}
\end{equation*}
$$

2. Scenario 2: only the first species (i.e. P. vivax) is the resident. Assume that $\mathcal{R}_{1}^{x_{1}}>1$ which guarantees the existence of the resident equilibrium $E^{\left(x_{1}, \emptyset\right)}$. Then, we have

$$
f_{\left(x_{1}, \emptyset\right)}\left(y_{1}, y_{2}\right)=\binom{\frac{C_{1}^{x_{1}}}{C_{1}^{E_{0}}}\left(\mathcal{R}_{1}^{y_{1}}-\mathcal{R}_{1}^{x_{1}}\right)}{\frac{C_{1}^{x_{1}}}{C_{1}^{E_{0}}}\left(\mathcal{R}_{2}^{y_{2}}-\mathcal{R}_{1}^{x_{1}}\right)}
$$

with $C_{1}^{x_{1}}$ and $C_{2}^{x_{1}}$ respectively the size of young and mature $R B C s$ in the environment set by the resident. We obtain

$$
\operatorname{sign}\left(f_{\left(x_{1}, \emptyset\right)}^{1}\left(y_{1}\right)\right)=\operatorname{sign}\left(\mathcal{R}_{1}^{y_{1}}-\mathcal{R}_{1}^{x_{1}}\right), \quad \text { and } \quad \operatorname{sign}\left(f_{\left(x_{1}, \emptyset\right)}^{2}\left(y_{2}\right)\right)=\operatorname{sign}\left(\mathcal{R}_{2}^{y_{2}}-\mathcal{R}_{1}^{x_{1}}\right)
$$

3. Scenario 3: only the second species (i.e. P. falciparum) is the resident. Assume that $\mathcal{R}_{2}^{x_{2}}>1$, which guarantees the existence of the resident equilibrium $E^{\left(\emptyset, x_{2}\right)}$. We then have

$$
f_{\left(\emptyset, x_{2}\right)}\left(y_{1}, y_{2}\right)=\left(\begin{array}{c}
\frac{C_{1}^{x_{2}}}{C_{1}^{E_{0}}}\left(\begin{array}{c}
\mathcal{R}_{1}^{y_{1}}-\frac{\left(\sum_{i=1}^{2} C_{i}^{x_{2}}\right) / C_{1}^{x_{2}}}{\left(\sum_{i=1}^{2} C_{i}^{E_{0}}\right) / C_{1}^{E_{0}}} \mathcal{R}_{2}^{x_{2}} \\
\\
\frac{\left(\sum_{i=1}^{2} C_{i}^{x_{2}}\right)}{\left(\sum_{i=1}^{2} C_{i}^{E_{0}}\right)}\left(\mathcal{R}_{2}^{y_{2}}-\mathcal{R}_{2}^{x_{2}}\right)
\end{array}\right) .
\end{array}\right)
$$

with $C_{1}^{x_{2}}$ and $C_{2}^{x_{2}}$ respectively the size of young and mature $R B C$ in the environment set by the resident. Then:

$$
\begin{align*}
& \operatorname{sign}\left(f_{\left(\emptyset, x_{2}\right)}^{1}\left(y_{1}\right)\right)=\operatorname{sign}\left(\mathcal{R}_{1}^{y_{1}}-\frac{\left(\sum_{i=1}^{2} C_{i}^{x_{2}}\right) / C_{1}^{x_{2}}}{\left(\sum_{i=1}^{2} C_{i}^{E_{0}}\right) / C_{1}^{E_{0}}} \mathcal{R}_{2}^{x_{2}}\right),  \tag{6.5}\\
& \operatorname{sign}\left(f_{\left(\emptyset, x_{2}\right)}^{2}\left(y_{2}\right)\right)=\operatorname{sign}\left(\mathcal{R}_{2}^{y_{2}}-\mathcal{R}_{2}^{x_{2}}\right) \tag{6.6}
\end{align*}
$$

Proof. Scenario 1: both species are resident. Let $E^{\left(x_{1}, x_{2}\right)}$ be the equilibrium set by the resident population of strain $\left(x_{1}, x_{2}\right)$. Such an equilibrium satisfies:

$$
E^{\left(x_{1}, x_{2}\right)}=\left(C_{1}^{\left(x_{1}, x_{2}\right)}, C_{2}^{\left(x_{1}, x_{2}\right)}, v_{1}^{\left(x_{1}, x_{2}\right)}(.) \delta_{x_{1}}(\cdot), m_{1}^{\left(x_{1}, x_{2}\right)} \delta_{x_{1}}(\cdot), v_{2}^{\left(x_{1}, x_{2}\right)}(.) \delta_{x_{2}}(\cdot), m_{2}^{\left(x_{1}, x_{2}\right)} \delta_{x_{2}}(\cdot)\right)
$$

At the equilibrium $E^{\left(x_{1}, x_{2}\right)}$, System (2.1) rewrites

$$
\left\{\begin{align*}
& 0=\Lambda-C_{1}^{\left(x_{1}, x_{2}\right)}\left(\mu_{1,2}+\beta_{1}\left(x_{1}\right) m_{1}^{\left(x_{1}, x_{2}\right)}+\beta_{2}\left(x_{2}\right) m_{2}^{\left(x_{1}, x_{2}\right)}\right)  \tag{6.7}\\
& 0=\mu_{1,2} C_{1}^{\left(x_{1}, x_{2}\right)}-C_{2}^{\left(x_{1}, x_{2}\right)}\left(\mu_{2}+\beta_{2}\left(x_{2}\right) m_{2}^{\left(x_{1}, x_{2}\right)}\right), \\
& \frac{v_{j}^{\left(x_{1}, x_{2}\right)}(0)}{}=\left(\sum_{k=1}^{j} C_{k}^{\left(x_{1}, x_{2}\right)}\right) \beta_{j}\left(x_{j}\right) m_{j}^{\left(x_{1}, x_{2}\right)}, \\
& \frac{\mathrm{d} v_{j}^{\left(x_{1}, x_{2}\right)}}{\mathrm{d} a}(a)=-\left(\mu_{2}+\gamma_{j}\left(a, x_{j}\right)\right) v_{j}^{\left(x_{1}, x_{2}\right)}(a), \\
& m_{j}^{\left(x_{1}, x_{2}\right)}=\frac{p_{j}\left(x_{j}\right)}{\mu_{m, j}+I_{j}\left(x_{j}\right)} \int_{0}^{\infty} \gamma_{j}\left(a, x_{j}\right) v_{j}^{\left(x_{1}, x_{2}\right)}(a) \mathrm{d} a
\end{align*}\right.
$$

for each $j \in\{1,2\}$. From (6.7) we deduce that

$$
\left\{\begin{aligned}
C_{1}^{\left(x_{1}, x_{2}\right)} & =\frac{\Lambda}{\mu_{1,2}+\beta_{1}\left(x_{1}\right) m_{1}^{\left(x_{1}, x_{2}\right)}+\beta_{2}\left(x_{2}\right) m_{2}^{\left(x_{1}, x_{2}\right)}}, \\
C_{2}^{\left(x_{1}, x_{2}\right)} & =\frac{\Lambda \mu_{1,2}}{\mu_{1,2}+\beta_{1}\left(x_{1}\right) m_{1}^{\left(x_{1}, x_{2}\right)}+\beta_{2}\left(x_{2}\right) m_{2}^{\left(x_{1}, x_{2}\right)}} \times \frac{1}{\mu_{2}+\beta_{2}\left(x_{2}\right) m_{2}^{\left(x_{1}, x_{2}\right)}}, \\
v_{j}^{\left(x_{1}, x_{2}\right)}(a) & =\left(\sum_{k=1}^{j} C_{k}^{\left(x_{1}, x_{2}\right)}\right) \beta_{j}\left(x_{j}\right) m_{j}^{\left(x_{1}, x_{2}\right)} \Pi_{j}\left(0, a, x_{j}\right) .
\end{aligned}\right.
$$

Replacing the above expressions into the last equation of (6.7) it comes

$$
\left\{\begin{array}{l}
1=\frac{\Lambda}{\mu_{1,2}+\beta_{1}\left(x_{1}\right) m_{1}^{\left(x_{1}, x_{2}\right)}+\beta_{2}\left(x_{2}\right) m_{2}^{\left(x_{1}, x_{2}\right)}} \Gamma_{1}\left(x_{1}\right) \\
1=\frac{\Lambda}{\mu_{1,2}+\beta_{1}\left(x_{1}\right) m_{1}^{\left(x_{1}, x_{2}\right)}+\beta_{2}\left(x_{2}\right) m_{2}^{\left(x_{1}, x_{2}\right)}}\left(1+\frac{\mu_{1,2}}{\mu_{2}+\beta_{2}\left(x_{2}\right) m_{2}^{\left(x_{1}, x_{2}\right)}}\right) \Gamma_{2}\left(x_{2}\right)
\end{array}\right.
$$

i.e.

$$
\left\{\begin{array}{l}
1=\frac{\Lambda}{\mu_{1,2}+\beta_{1}\left(x_{1}\right) m_{1}^{\left(x_{1}, x_{2}\right)}+\beta_{2}\left(x_{2}\right) m_{2}^{\left(x_{1}, x_{2}\right)}} \Gamma_{1}\left(x_{1}\right),  \tag{6.8}\\
1=\frac{\Gamma_{2}\left(x_{2}\right)}{\Gamma_{1}\left(x_{1}\right)}\left(1+\frac{\mu_{1,2}}{\mu_{2}+\beta_{2}\left(x_{2}\right) m_{2}^{\left(x_{1}, x_{2}\right)}}\right)
\end{array}\right.
$$

The right-hand side of the second equation of (6.8) is strictly decreasing in $m_{2}^{\left(x_{1}, x_{2}\right)}$. Thus, a necessary and sufficient condition for a positive solution $m_{2}^{\left(x_{1}, x_{2}\right)}$ is

$$
\begin{equation*}
\frac{\Gamma_{2}\left(x_{2}\right)}{\Gamma_{1}\left(x_{1}\right)}<1 \text { and } \frac{\Gamma_{2}\left(x_{2}\right)}{\Gamma_{1}\left(x_{1}\right)}\left(1+\frac{\mu_{1,2}}{\mu_{2}}\right)>1 \tag{6.9}
\end{equation*}
$$

Observe that

$$
\frac{\mathcal{R}_{2}^{x_{2}}}{\mathcal{R}_{1}^{x_{1}}}=\frac{C_{1}^{E_{0}}+C_{2}^{E_{0}}}{C_{1}^{E_{0}}} \times \frac{\Gamma_{2}\left(x_{2}\right)}{\Gamma_{1}\left(x_{1}\right)}=\left(1+\frac{\mu_{1,2}}{\mu_{2}}\right) \frac{\Gamma_{2}\left(x_{2}\right)}{\Gamma_{1}\left(x_{1}\right)} .
$$

Therefore, conditions (6.9) are equivalent to

$$
1<\frac{\mathcal{R}_{2}^{x_{2}}}{\mathcal{R}_{1}^{x_{1}}}<1+\frac{\mu_{1,2}}{\mu_{2}} .
$$

Still from the system (6.8), the second equation then gives

$$
m_{2}^{\left(x_{1}, x_{2}\right)} \beta_{2}\left(x_{2}\right)=\frac{\left(\mu_{1,2}+\mu_{2}\right)\left(\frac{\mathcal{R}_{2}^{x_{2}}}{\mathcal{R}_{1}^{x_{1}}}-1\right)}{\left(1+\frac{\mu_{1,2}}{\mu_{2}}\right)-\frac{\mathcal{R}_{2}^{x_{2}}}{\mathcal{R}_{1}^{x_{1}}}}
$$

For $m_{1}^{\left(x_{1}, x_{2}\right)}$, the right-hand side of the first equation of (6.8) is strictly decreasing in $m_{1}^{\left(x_{1}, x_{2}\right)}$ with limit 0 when $m_{1}^{\left(x_{1}, x_{2}\right)} \rightarrow \infty$. So, a necessary and sufficient condition for a positive solution $m_{1}^{\left(x_{1}, x_{2}\right)}$ is

$$
\frac{\mu_{1,2}}{\mu_{1,2}+\beta_{2}\left(x_{2}\right) m_{2}^{\left(x_{1}, x_{2}\right)}} \mathcal{R}_{1}^{x_{1}}>1 \Longleftrightarrow \mathcal{R}_{1}^{x_{1}}>1+\left(1+\frac{\mu_{2}}{\mu_{1,2}}\right)\left(\frac{\frac{\mathcal{R}_{2}^{x_{2}}}{\mathcal{R}_{1}^{x_{1}}}-1}{\left(1+\frac{\mu_{1,2}}{\mu_{2}}\right)-\frac{\mathcal{R}_{2}^{x_{2}}}{\mathcal{R}_{1}^{x_{1}}}}\right) .
$$

In summary, the resident equilibrium $E^{\left(x_{1}, x_{2}\right)}$ exists if and only if the following conditions are satisfied

$$
1<\frac{\mathcal{R}_{2}^{x_{2}}}{\mathcal{R}_{1}^{x_{1}}}<1+\frac{\mu_{1,2}}{\mu_{2}} \quad \text { and } \quad \mathcal{R}_{1}^{x_{1}}>1+\left(1+\frac{\mu_{2}}{\mu_{1,2}}\right)\left(\frac{\frac{\mathcal{R}_{2}^{x_{2}}}{\mathcal{R}_{1}^{x_{1}}}-1}{\left(1+\frac{\mu_{1,2}}{\mu_{2}}\right)-\frac{\mathcal{R}_{2}^{x_{2}}}{\mathcal{R}_{1}^{x_{1}}}}\right)
$$

We now assume that a mutant with phenotype $\left(y_{1}, y_{2}\right)$ causes a small perturbation of the system set out by the resident equilibrium $E^{\left(x_{1}, x_{2}\right)}$. Thus, we set

$$
\left\{\begin{aligned}
C_{j}(t) & =C_{j}^{\left(x_{1}, x_{2}\right)}+b_{j}(t) \\
v_{j}(t, a, x) & =v_{j}^{\left(x_{1}, x_{2}\right)}(a) \delta_{x_{j}}(x)+g_{j}(t, a) \delta_{y_{j}}(x), \\
m_{j}(t, x) & =m_{j}^{\left(x_{1}, x_{2}\right)} \delta_{x_{j}}(x)+h_{j}(t) \delta_{y_{j}}(x)
\end{aligned}\right.
$$

for each $j \in\{1,2\}$. We remind that by (2.1)we have

$$
\left\{\begin{aligned}
v_{j}(t, 0, x) & =\left(\sum_{k=1}^{j} C_{k}(t)\right) \beta_{j}(x) m_{j}(t, x) \\
\left(\partial_{t}+\partial_{a}\right) v_{j}(t, a, x) & =-\left(\mu_{2}+\gamma_{j}(a, x)\right) v_{j}(t, a, x) \\
\partial_{t} m_{j}(t, x) & =\int_{\mathbb{R}} k(x-y) p_{j}(y) \int_{0}^{\infty} \gamma_{j}(a, y) v_{j}(t, a, y) \mathrm{d} a \mathrm{~d} y-\left(\mu_{m, j}+I_{j}(x)\right) m_{j}(t, x)
\end{aligned}\right.
$$

for each $j \in\{1,2\}$. Then, the small perturbations for infection $g_{1}, g_{2}, h_{1}$ and $h_{2}$, are governed by the following system of equations around $E^{\left(x_{1}, x_{2}\right)}$, with $x_{j} \neq y_{j}$ :

$$
\left\{\begin{aligned}
g_{j}(t, 0)= & \left(\sum_{k=1}^{j} C_{k}^{\left(x_{1}, x_{2}\right)}\right) \beta_{j}\left(y_{j}\right) h_{j}(t), \\
\left(\partial_{t}+\partial_{a}\right) g_{j}(t, a)= & -\left(\mu_{2}+\gamma_{j}\left(a, y_{j}\right)\right) g_{j}(t, a), \\
h_{j}^{\prime}(t) \delta_{y_{j}}(\cdot)= & k\left(\cdot-y_{j}\right) p_{j}\left(y_{j}\right) \int_{0}^{\infty} \gamma_{j}\left(a, y_{j}\right) g_{j}(t, a) \mathrm{d} a+k\left(\cdot-x_{j}\right) p_{j}\left(x_{j}\right) \int_{0}^{\infty} \gamma_{j}\left(a, x_{j}\right) v_{j}^{\left(x_{1}, x_{2}\right)}(a) \mathrm{d} a \\
& -\left(\mu_{m, j}+I_{j}(\cdot)\right)\left(m_{j}^{\left(x_{1}, x_{2}\right)} \delta_{x_{j}}(\cdot)+h_{j}(t) \delta_{y_{j}}(\cdot)\right)
\end{aligned}\right.
$$

for each $j \in\{1,2\}$. By integrating $h_{j}^{\prime}(t) \delta_{y_{j}}(z)$ and since $\int_{\mathbb{R}} k(y-z) \mathrm{d} z=1$, for any $y$, it comes

$$
\left\{\begin{aligned}
g_{j}(t, 0)= & \left(\sum_{k=1}^{j} C_{k}^{\left(x_{1}, x_{2}\right)}\right) \beta_{j}\left(y_{j}\right) h_{j}(t), \\
\left(\partial_{t}+\partial_{a}\right) g_{j}(t, a)= & -\left(\mu_{2}+\gamma_{j}\left(a, y_{j}\right) g_{j}(t, a),\right. \\
h_{j}^{\prime}(t)= & p_{j}\left(y_{j}\right) \int_{0}^{\infty} \gamma_{j}\left(a, y_{j}\right) g_{j}(t, a) \mathrm{d} a+p_{j}\left(x_{j}\right) \int_{0}^{\infty} \gamma_{j}\left(a, x_{j}\right) v_{j}^{\left(x_{1}, x_{2}\right)}(a) \mathrm{d} a \\
& -\left(\mu_{m, j}+I_{j}\left(x_{j}\right)\right) m_{j}^{\left(x_{1}, x_{2}\right)}-\left(\mu_{m, j}+I_{j}\left(y_{j}\right)\right) h_{j}(t)
\end{aligned}\right.
$$

for each $j \in\{1,2\}$. Note that by definition of the resident equilibrium $E^{\left(x_{1}, x_{2}\right)}$, we have

$$
\begin{equation*}
p_{j}\left(x_{j}\right) \int_{0}^{\infty} \gamma_{j}\left(a, x_{j}\right) v_{j}^{\left(x_{1}, x_{2}\right)}(a) \mathrm{d} a-\left(\mu_{m, j}+I_{j}\left(x_{j}\right)\right) m_{j}^{\left(x_{1}, x_{2}\right)}=0, \quad \forall j \in\{1,2\} \tag{6.10}
\end{equation*}
$$

It follows, for each $j \in\{1,2\}$, that:

$$
\left\{\begin{align*}
g_{j}(t, 0) & =\left(\sum_{i=1}^{j} C_{i}^{\left(x_{1}, x_{2}\right)}\right) \beta_{j}\left(y_{j}\right) h_{j}(t)  \tag{6.11}\\
\left(\partial_{t}+\partial_{a}\right) g_{j}(t, a) & =-\left(\mu_{2}+\gamma_{j}\left(a, y_{j}\right)\right) g_{j}(t, a) \\
h_{j}^{\prime}(t) & =p_{j}\left(y_{j}\right) \int_{0}^{\infty} \gamma_{j}\left(a, y_{j}\right) g_{j}(t, a) \mathrm{d} a-\left(\mu_{m, j}+I_{j}\left(y_{j}\right)\right) h_{j}(t)
\end{align*}\right.
$$

Denoting by $M_{j}^{\left(x_{1}, x_{2}\right)}\left(t, y_{j}\right)$ the number of newly produced parasites of species $j$ at time $t$ with phenotype $y_{j}$ in a resident population $\left(x_{1}, x_{2}\right)$, we see that

$$
M_{j}^{\left(x_{1}, x_{2}\right)}\left(t, y_{j}\right)=p_{j}\left(y_{j}\right) \int_{0}^{\infty} \gamma_{j}\left(a, y_{j}\right) g_{j}(t, a) \mathrm{d} a
$$

Through similar computations employed in deriving the reproductive numbers in the proof of Proposition 6.1, it follows that

$$
M_{j}^{\left(x_{1}, x_{2}\right)}\left(t, y_{j}\right)=\int_{0}^{t} F_{j}^{\left(x_{1}, x_{2}\right)}\left(a, y_{j}\right) M_{j}^{\left(x_{1}, x_{2}\right)}\left(t-a, y_{j}\right) \mathrm{d} a+H_{j}\left(t, y_{j}\right)
$$

where $H_{j}$ accounts for the initial condition of (6.11) and

$$
F_{j}^{\left(x_{1}, x_{2}\right)}\left(a, y_{j}\right)=e^{-\left(\mu_{m, j}+I_{j}\left(y_{j}\right)\right) a}\left(\sum_{i=1}^{j} C_{i}^{\left(x_{1}, x_{2}\right)}\right) p_{j}\left(y_{j}\right) \beta_{j}\left(y_{j}\right) \int_{0}^{a} \gamma_{j}\left(s, y_{j}\right) \Pi_{j}\left(0, s, y_{j}\right) e^{\left(\mu_{m, j}+I_{j}\left(y_{j}\right)\right) s} \mathrm{~d} s
$$

As a result of the above formulation, we find that the basic parasitic reproduction number $\mathcal{R}\left(y_{j}, E^{\left(x_{1}, x_{2}\right)}\right)$ of a mutant strain $y_{j}$, in the resident population of strain $\left(x_{1}, x_{2}\right)$ is given by

$$
\mathcal{R}\left(y_{j}, E^{\left(x_{1}, x_{2}\right)}\right)=\int_{0}^{\infty} F_{j}^{\left(x_{1}, x_{2}\right)}\left(a, y_{j}\right) \mathrm{d} a=\left(\sum_{i=1}^{j} C_{i}^{\left(x_{1}, x_{2}\right)}\right) \Gamma_{j}\left(y_{j}\right)
$$

Therefore, the invasion fitness $f_{\left(x_{1}, x_{2}\right)}\left(y_{1}, y_{2}\right)$ of a mutant strain $\left(y_{1}, y_{2}\right)$ in the resident population $E^{\left(x_{1}, x_{2}\right)}$ writes

$$
\begin{equation*}
f_{\left(x_{1}, x_{2}\right)}\left(y_{1}, y_{2}\right)=\binom{\mathcal{R}\left(y_{1}, E^{\left(x_{1}, x_{2}\right)}\right)-1}{\mathcal{R}\left(y_{2}, E^{\left(x_{1}, x_{2}\right)}\right)-1}=\binom{\frac{C_{1}^{\left(x_{1}, x_{2}\right)}}{C_{1}^{E_{0}}} \mathcal{R}_{1}^{y_{1}}-1}{\frac{\sum_{i=1}^{2} C_{i}^{\left(x_{1}, x_{2}\right)}}{\sum_{i=1}^{2} C_{i}^{E_{0}}} \mathcal{R}_{2}^{y_{2}}-1} \tag{6.12}
\end{equation*}
$$

By (6.10), we have

$$
\frac{C_{1}^{\left(x_{1}, x_{2}\right)}}{C_{1}^{E_{0}}} \mathcal{R}_{1}^{x_{1}}=1 \quad \text { and } \quad \frac{\sum_{i=1}^{2} C_{i}^{\left(x_{1}, x_{2}\right)}}{\sum_{i=1}^{2} C_{i}^{E_{0}}} \mathcal{R}_{2}^{x_{2}}=1
$$

from where (6.12) rewrites as

$$
f_{\left(x_{1}, x_{2}\right)}\left(y_{1}, y_{2}\right)=\binom{\frac{C_{1}^{\left(x_{1}, x_{2}\right)}}{C_{1}^{E_{0}}}\left(\mathcal{R}_{1}^{y_{1}}-\mathcal{R}_{1}^{x_{1}}\right)}{\frac{\sum_{i=1}^{2} C_{i}^{\left(x_{1}, x_{2}\right)}}{\sum_{i=1}^{2} C_{i}^{E_{0}}}\left(\mathcal{R}_{2}^{y_{2}}-\mathcal{R}_{2}^{x_{2}}\right)}
$$

Scenario 2: only the first species (i.e. P. vivax) is resident. Using calculations similar to those of Scenario 1, the equilibrium $E^{\left(x_{1}, \emptyset\right)}=\left(C_{1}^{x_{1}}, C_{2}^{x_{1}}, v_{1}^{x_{1}}(a) \delta_{x_{1}}(\cdot), m_{1}^{x_{1}} \delta_{x_{1}}(\cdot), v_{2}^{x_{1}}=0, m_{2}^{x_{1}}=0\right)$ set by the resident $\left(x_{1}, 0\right)$ exists if and only if $\mathcal{R}_{1}^{x_{1}}>1$ and then we have

$$
\left\{\begin{aligned}
C_{1}^{x_{1}} & =C_{1}^{E_{0}} \frac{\mu_{1,2}}{\mu_{1,2}+\beta_{1}\left(x_{1}\right) m_{1}^{x_{1}}} \\
C_{2}^{x_{1}} & =C_{2}^{E_{0}} \frac{\mu_{1,2}}{\mu_{1,2}+\beta_{1}\left(x_{1}\right) m_{1}^{x_{1}}}, \\
v_{1}^{x_{1}}(a) & =C_{1}^{x_{1}} \beta_{1}\left(x_{1}\right) m_{1}^{x_{1}} \Pi_{1}\left(0, a, x_{1}\right) \\
m_{1}^{x_{1}} & =\frac{\mu_{1,2}}{\beta_{1}\left(x_{1}\right)}\left(\mathcal{R}_{1}^{x_{1}}-1\right)
\end{aligned}\right.
$$

Furthermore, the reproduction number $\mathcal{R}\left(y_{j}, E_{1}^{\left(x_{1}, \emptyset\right)}\right)$ of a mutant with phenotype $y_{j}$, in the resident population set by $E_{1}^{\left(x_{1}, 0\right)}$ is given by

$$
\mathcal{R}\left(y_{j}, E_{1}^{\left(x_{1}, \emptyset\right)}\right)=\int_{0}^{\infty} F_{j}^{x_{1}}\left(a, y_{j}\right) \mathrm{d} a=\left(\sum_{i=1}^{j} C_{i}^{x_{1}}\right) \Gamma_{j}\left(y_{j}\right) .
$$

Hence the invasion fitness $f\left(x_{1}, \emptyset\right)\left(y_{1}, y_{2}\right)$ writes

$$
f_{\left(x_{1}, \emptyset\right)}\left(y_{1}, y_{2}\right)=\binom{\frac{C_{1}^{x_{1}}}{C_{1}^{E_{0}}}\left(\mathcal{R}_{1}^{y_{1}}-\mathcal{R}_{1}^{x_{1}}\right)}{\frac{C_{1}^{x_{1}}}{C_{1}^{E_{0}}}\left(\mathcal{R}_{2}^{y_{2}}-\mathcal{R}_{1}^{x_{1}}\right)}
$$

Scenario 3: only the second species (i.e. P. falciparum) is resident. As for the previous scenarios, we find that the resident equilibrium $E^{\left(\emptyset, x_{1}\right)}=\left(C_{1}^{x_{2}}, C_{2}^{x_{2}}, v_{1}^{x_{2}}=0, m_{1}^{x_{2}}=0, v_{2}^{x_{2}}(a) \delta_{x_{2}}(\cdot), m_{2}^{x_{2}} \delta_{x_{2}}(\cdot)\right)$ is such that

$$
\left\{\begin{aligned}
C_{1}^{x_{2}} & =C_{1}^{E_{0}} \frac{\mu_{1,2}}{\mu_{1,2}+\beta_{2}\left(x_{2}\right) m_{2}^{x_{2}}} \\
C_{2}^{x_{2}} & =C_{2}^{E_{0}} \frac{\mu_{1,2} \mu_{2}}{\left(\mu_{1,2}+\beta_{2}\left(x_{2}\right) m_{2}^{x_{2}}\right)\left(\mu_{2}+\beta_{2}\left(x_{2}\right) m_{2}^{x_{2}}\right)} \\
v_{1}^{x_{2}}(a) & =\left(C_{1}^{x_{2}}+C_{2}^{x_{2}}\right) \beta_{2}\left(x_{2}\right) m_{2}^{x_{2}} \Pi_{2}\left(0, a, x_{2}\right)
\end{aligned}\right.
$$

where $m_{2}^{x_{2}}$ is the unique positive solution to the following equation (provided that $\mathcal{R}_{2}^{x_{2}}>1$ ):

$$
\frac{\mu_{1,2}}{\mu_{1,2}+\beta_{2}\left(x_{2}\right) m_{2}^{x_{2}}}\left(C_{1}^{E_{0}}+C_{2}^{E_{0}} \frac{\mu_{2}}{\mu_{2}+\beta_{2}\left(x_{2}\right) m_{2}^{x_{2}}}\right) \Gamma_{2}\left(x_{2}\right)=1
$$

Applying the same methodology as in the previous section, we find that the reproduction number $\mathcal{R}\left(y_{j}, E^{\left(\emptyset, x_{2}\right)}\right)$ of a mutant strain $y_{j}$, in the resident population $E_{1}^{\left(\emptyset, x_{2}\right)}$ is given by

$$
\mathcal{R}\left(y_{j}, E_{2}^{\left(\emptyset, x_{2}\right)}\right)=\left(\sum_{i=1}^{j} C_{i}^{x_{2}}\right) \Gamma_{j}\left(y_{j}\right) .
$$

Thus the invasion fitness writes

$$
f_{\left(\emptyset, x_{2}\right)}\left(y_{1}, y_{2}\right)=\binom{\frac{C_{1}^{x_{2}}}{C_{1}^{E_{0}}}\left(\mathcal{R}_{1}^{y_{1}}-\frac{\left(\sum_{i=1}^{2} C_{i}^{x_{2}}\right) / C_{1}^{x_{2}}}{\left(\sum_{i=1}^{2} C_{2}^{E_{0}}\right) / C_{1}^{E_{0}}} \mathcal{R}_{2}^{x_{2}}\right)}{\frac{\left(\sum_{i=1}^{2} C_{i}^{x_{2}}\right)}{\left(\sum_{i=1}^{2} C_{i}^{E_{0}}\right)}\left(\mathcal{R}_{2}^{y_{2}}-\mathcal{R}_{2}^{x_{2}}\right)}
$$

Finally, note that

$$
\left(C_{1}^{x_{2}}+C_{2}^{x_{2}}\right) / C_{1}^{x_{2}}=1+\frac{C_{2}^{E_{0}}}{C_{1}^{E_{0}}} \frac{\mu_{2}}{\left(\mu_{2}+\beta_{2}\left(x_{2}\right) m_{2}^{x_{2}}\right)}
$$

whence

$$
\frac{\left(C_{1}^{x_{2}}+C_{2}^{x_{2}}\right) / C_{1}^{x_{2}}}{\left(C_{1}^{E_{0}}+C_{2}^{E_{0}}\right) / C_{1}^{E_{0}}}=\left(1+\frac{C_{2}^{E_{0}}}{C_{1}^{E_{0}}} \frac{\mu_{2}}{\mu_{2}+\beta_{2}\left(x_{2}\right) m_{2}^{x_{2}}}\right)\left(1+\frac{C_{2}^{E_{0}}}{C_{1}^{E_{0}}}\right)^{-1}<1
$$

## 7 Parasite's extinction and uniform persistence

In this section, we analyze parasite extinction and persistence in relation to the thresholds $\mathcal{R}_{j}$ introduced by (5.3). These thresholds are vital in understanding how parasite populations behave over time within the host. We

### 7.1 Technical materials

We explore the properties of a perturbed linear system around the equilibrium $E_{0}$ defined in (5.2). We consider $\epsilon \in \mathbb{R}$ to be sufficiently small such that

$$
C_{i}^{E_{0}}+\epsilon>0, \quad \forall i \in\{1,2\} .
$$

For $j \in\{1,2\}$, we examine the linear problem given by

$$
\left\{\begin{align*}
v_{j}^{\epsilon}(t, a=0, x) & =\beta_{j}(x) m_{j}^{\epsilon}(t, x)\left(\sum_{i=1}^{j}\left(C_{i}^{E_{0}}+\epsilon\right)\right)  \tag{7.1}\\
\frac{\partial v_{j}^{\epsilon}(t, a, x)}{\partial t}+\frac{\partial v_{j}^{\epsilon}(t, a, x)}{\partial a} & =-\left(\mu_{2}+\gamma_{j}(a, x)\right) v_{j}^{\epsilon}(t, a, x) \\
\frac{\partial m_{j}^{\epsilon}(t, x)}{\partial t} & =\int_{\mathbb{R}} k(x-y) p_{j}(y)\left(\int_{0}^{\infty} \gamma_{j}(a, y) v_{j}^{\epsilon}(t, a, y) \mathrm{d} a\right) \mathrm{d} y-\left(\mu_{m, j}+I_{j}(x)\right) m_{j}^{\epsilon}(t, x)
\end{align*}\right.
$$

with initial conditions $v_{j}^{\epsilon}(0, \cdot, \cdot)=v_{j, 0} \in L^{1}\left(\mathbb{R}_{+} \times \mathbb{R}, \mathbb{R}\right)$ and $m_{j}^{\epsilon}(0, \cdot)=m_{j, 0} \in L^{1}(\mathbb{R}, \mathbb{R})$. It is noteworthy that these systems are independent of each other as $j$ varies from 1 to 2 . For the rest of this section, $j$ is fixed in $\{1,2\}$. We can express the $j$-system as the following abstract formulation:

$$
\left\{\begin{align*}
\frac{\mathrm{d} \ell_{j}(t)}{\mathrm{d} t} & =\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right) \ell_{j}(t)  \tag{7.2}\\
\ell_{j}(0) & =\ell_{j, 0} \in \mathcal{Y}_{0}
\end{align*}\right.
$$

where $\mathcal{Y}=L^{1}(\mathbb{R}, \mathbb{R}) \times L^{1}\left(\mathbb{R}_{+} \times \mathbb{R}, \mathbb{R}\right) \times L^{1}(\mathbb{R}, \mathbb{R})$ and $\mathcal{Y}_{0}=\left\{0_{L^{1}}\right\} \times L^{1}\left(\mathbb{R}_{+} \times \mathbb{R}, \mathbb{R}\right) \times L^{1}(\mathbb{R}, \mathbb{R})$. The Banach space $\mathcal{Y}$ is endowed with the usual product norm. The bounded linear operator $\mathcal{F}_{j}^{\epsilon}: \mathcal{Y}_{0} \rightarrow \mathcal{Y}$ is defined as

$$
\mathcal{F}_{j}^{\epsilon}\left(\begin{array}{c}
0_{L^{1}}  \tag{7.3}\\
v_{j} \\
m_{j}
\end{array}\right)=\left(\begin{array}{c}
\beta_{j} m_{j} \sum_{i=1}^{j}\left(C_{i}^{E_{0}}+\epsilon\right) \\
0_{L^{1}(\mathbb{R}+\times \mathbb{R}, \mathbb{R})} \\
\int_{\mathbb{R}} k(\cdot-y) p_{j}(y) \int_{0}^{\infty} \gamma_{j}(a, y) v_{j}(a, y) \mathrm{d} a \mathrm{~d} y
\end{array}\right), \quad \forall\left(\begin{array}{c}
0_{L^{1}} \\
v_{j} \\
m_{j}
\end{array}\right) \in \mathcal{Y}_{0}
$$

Meanwhile, $\mathcal{V}_{j}: \mathcal{D}\left(\mathcal{V}_{j}\right) \subset \mathcal{Y}_{0} \rightarrow \mathcal{Y}$ is given by

$$
\mathcal{V}_{j}\left(\begin{array}{c}
0_{L^{1}} \\
v_{j} \\
m_{j}
\end{array}\right)=\left(\begin{array}{c}
-v_{j}(0, \cdot) \\
-\partial_{a} v_{j}-\left(\mu_{2}+\gamma_{j}\right) v_{j} \\
-\mu_{m, j} m_{j}-I_{j} m_{j}
\end{array}\right), \quad \forall\left(\begin{array}{c}
0_{L^{1}} \\
v_{j} \\
m_{j}
\end{array}\right) \in \mathcal{D}\left(\mathcal{V}_{j}\right)
$$

with $\mathcal{D}\left(\mathcal{V}_{j}\right)=\left\{0_{L^{1}}\right\} \times \mathcal{D}_{j, v} \times L^{1}(\mathbb{R}, \mathbb{R})$ and

$$
\mathcal{D}_{j, v}:=\left\{v \in L^{1}\left(\mathbb{R}_{+} \times \mathbb{R}, \mathbb{R}\right): v(\cdot, x) \in W^{1,1}\left(\mathbb{R}_{+}, \mathbb{R}\right) \text { a.e } x \in \mathbb{R} \text { and } \partial_{a} v \in L^{1}\left(\mathbb{R}_{+} \times \mathbb{R}, \mathbb{R}\right)\right\}
$$

By employing arguments similar to those in Lemma 4.3, it can be shown that the spectral bound $\mathbf{s}\left(\mathcal{V}_{j}\right)$ of $\mathcal{V}_{j}$ satisfies $s\left(\mathcal{V}_{j}\right)<0$. Furthermore, the linear operator $\mathcal{V}_{j}$ is resolvent positive, and for each $\lambda>\mathrm{s}\left(\mathcal{V}_{j}\right)$, we have

$$
\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)^{-1}\left(\begin{array}{l}
u_{1} \\
u_{2} \\
u_{3}
\end{array}\right)=\left(\begin{array}{c}
0_{L^{1}} \\
v_{j} \\
m_{j}
\end{array}\right) \in \mathcal{Y}_{0}
$$

for every $\left(u_{1}, u_{2}, u_{3}\right)^{T} \in \mathcal{Y}$, with

$$
\left\{\begin{array}{l}
v_{j}(a, x)=e^{-\lambda a} \Pi_{j}(0, a, x) u_{1}(x)+\int_{0}^{a} e^{-\lambda(a-s)} \Pi_{j}(s, a, x) u_{2}(s, x) \mathrm{d} s, \quad a \geq 0, x \in \mathbb{R}  \tag{7.4}\\
m_{j}(x)=\frac{1}{\lambda+\mu_{m, j}+I_{j}(x)} u_{3}(x), \quad x \in \mathbb{R}
\end{array}\right.
$$

Therefore, setting

$$
\begin{equation*}
\mathcal{T}_{j, \lambda}^{\epsilon}:=\mathrm{r}\left(\mathcal{F}_{j}^{\epsilon}\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)^{-1}\right), \quad \forall \lambda>\mathrm{s}\left(\mathcal{V}_{j}\right) \tag{7.5}
\end{equation*}
$$

it follows from [42, Theorem 3.4] that the following sign equality holds true

$$
\operatorname{sgn}\left(\mathcal{T}_{j, \lambda}^{\epsilon}-1\right)=\operatorname{sgn}\left(-\lambda+\mathrm{s}\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)\right), \quad \forall \lambda>\mathrm{s}\left(\mathcal{V}_{j}\right)
$$

Since $\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}$ and $\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}$, the part of $\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}$ in $\mathcal{Y}_{0}$ have the same spectral set [25, Lemma 2.1], we also have the following equality

$$
\begin{equation*}
\operatorname{sgn}\left(\mathcal{T}_{j, \lambda}^{\epsilon}-1\right)=\operatorname{sgn}\left(-\lambda+\mathrm{s}\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)\right)=\operatorname{sgn}\left(-\lambda+\mathrm{s}\left(\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)\right), \quad \forall \lambda>\mathrm{s}\left(\mathcal{V}_{j}\right) \tag{7.6}
\end{equation*}
$$

Denote by $\mathcal{Y}_{1}$ the Banach space

$$
\mathcal{Y}_{1}=L^{1}(\mathbb{R}, \mathbb{R}) \times\left\{0_{L^{1}}\right\} \times L^{1}(\mathbb{R}, \mathbb{R})
$$

In the following, we provide a more explicit characterization of $\mathcal{T}_{j, \lambda}^{\epsilon}$ given by (7.5). To do so, let us first note that using [16, Lemma 2.2] one knows that $\mathcal{F}_{j}^{\epsilon}\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)^{-1}$ has the same spectral radius as its restriction on $\mathcal{Y}_{1}$. Next, observe that for each $\lambda>\mathbf{s}\left(\mathcal{V}_{j}\right)$ and $\left(u_{1}, 0_{L^{1}}, u_{3}\right)^{T} \in \mathcal{Y}_{1}$, we have from (7.3) and (7.4)

$$
\mathcal{F}_{j}^{\epsilon}\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)^{-1}\left(\begin{array}{c}
u_{1}  \tag{7.7}\\
0_{L^{1}} \\
u_{3}
\end{array}\right)=\left(\begin{array}{c}
\mathcal{G}_{j, \epsilon}^{\lambda}\left(u_{3}\right) \\
0_{L^{1}} \\
\mathcal{H}_{j}^{\lambda}\left(u_{1}\right)
\end{array}\right)
$$

where we have set for each $u_{1}, u_{3} \in L^{1}(\mathbb{R}, \mathbb{R})$

$$
\mathcal{G}_{j, \epsilon}^{\lambda}\left(u_{3}\right)(x):=\sum_{i=1}^{j}\left(C_{i}^{E_{0}}+\epsilon\right) \frac{\beta_{j}(x)}{\lambda+\mu_{m, j}+I_{j}(x)} u_{3}(x), \forall x \in \mathbb{R}
$$

and

$$
\mathcal{H}_{j}^{\lambda}\left(u_{1}\right)(x):=\int_{\mathbb{R}} k(x-y) p_{j}(y) \int_{0}^{\infty} \gamma_{j}(a, y) e^{-\lambda a} \Pi_{j}(0, a, y) \mathrm{d} a u_{1}(y) \mathrm{d} y, \forall x \in \mathbb{R}
$$

From (7.7), it follows that for each $\left(u_{1}, 0_{L^{1}}, u_{3}\right)^{T} \in \mathcal{Y}_{1}$,

$$
\left(\mathcal{F}_{j}^{\epsilon}\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)^{-1}\right)^{2}\left(\begin{array}{c}
u_{1}  \tag{7.8}\\
0_{L^{1}} \\
u_{3}
\end{array}\right)=\left(\begin{array}{c}
\mathcal{G}_{j, \epsilon}^{\lambda} \circ \mathcal{H}_{j}^{\lambda}\left(u_{1}\right) \\
0_{L^{1}} \\
\mathcal{H}_{j}^{\lambda} \circ \mathcal{G}_{j, \epsilon}^{\lambda}\left(u_{3}\right)
\end{array}\right)
$$

and since $\mathrm{r}\left(\mathcal{H}_{j}^{\lambda} \circ \mathcal{G}_{j, \epsilon}^{\lambda}\right)=\mathrm{r}\left(\mathcal{G}_{j, \epsilon}^{\lambda} \circ \mathcal{H}_{j}^{\lambda}\right)$ and $\mathrm{r}\left(\left(\mathcal{F}_{j}^{\epsilon}\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)^{-1}\right)^{2}\right)=\mathrm{r}\left(\mathcal{F}_{j}^{\epsilon}\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)^{-1}\right)^{2}$, it follows from (7.5) and (7.8) that

$$
\mathcal{T}_{j, \lambda}^{\epsilon}=\sqrt{\mathrm{r}\left(\left(\mathcal{F}_{j}^{\epsilon}\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)^{-1}\right)^{2}\right)}=\sqrt{\mathrm{r}\left(\mathcal{H}_{j}^{\lambda} \circ \mathcal{G}_{j, \epsilon}^{\lambda}\right)}, \quad \forall \lambda>\mathrm{s}\left(\mathcal{V}_{j}\right)
$$

Moreover, the linear operator $\mathcal{H}_{j}^{\lambda} \circ \mathcal{G}_{j, \epsilon}^{\lambda}: L^{1}(\mathbb{R}, \mathbb{R}) \rightarrow L^{1}(\mathbb{R}, \mathbb{R})$ is explicitly given, for $\lambda>\mathrm{s}\left(\mathcal{V}_{j}\right)$, by

$$
\left(\mathcal{H}_{j}^{\lambda} \circ \mathcal{G}_{j, \epsilon}^{\lambda}\right) w(x)=\sum_{i=1}^{j}\left(C_{i}^{E_{0}}+\epsilon\right) \int_{\mathbb{R}} k(x-y) \Gamma_{j}^{\lambda}(y) w(y) \mathrm{d} y, \quad \forall w \in L^{1}(\mathbb{R})
$$

with

$$
\Gamma_{j}^{\lambda}(y):=\frac{p_{j}(y) \beta_{j}(y)}{\lambda+\mu_{m, j}+I_{j}(y)} \int_{0}^{\infty} \gamma_{j}(a, y) e^{-\lambda a} \Pi_{j}(0, a, y) \mathrm{d} a .
$$

From the above discussion, we have the following results.
Proposition 7.1. Let Assumptions 3.1 and 3.3 be satisfied. Then $\mathbf{s}\left(\mathcal{V}_{j}\right)<0$ and we have the following properties:
i) $\operatorname{sgn}\left(\mathcal{T}_{j, \lambda}^{\epsilon}-1\right)=\operatorname{sgn}\left(-\lambda+\mathrm{s}\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)\right)=\operatorname{sgn}\left(-\lambda+\mathrm{s}\left(\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)\right)$, for all $\lambda>\mathrm{s}\left(\mathcal{V}_{j}\right)$.
ii) For each $\lambda>\mathbf{s}\left(\mathcal{V}_{j}\right)$, the linear operator $\left(\mathcal{F}_{j}^{\epsilon}\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)^{-1}\right)^{2}: \mathcal{Y}_{1} \rightarrow \mathcal{Y}_{1}$ is compact and positive.
iii) For each $\lambda>\mathrm{s}\left(\mathcal{V}_{j}\right)$, the spectral radius $\mathcal{T}_{j, \lambda}^{\epsilon}$ of $\mathcal{F}_{j}^{\epsilon}\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)^{-1}$ satisfies $\mathcal{T}_{j, \lambda}^{\epsilon}=\sqrt{\mathrm{r}\left(\mathcal{H}_{j}^{\lambda} \circ \mathcal{G}_{j, \epsilon}^{\lambda}\right)}$.

Next, we establish a key result essential for proving the global asymptotic stability of the equilibrium $E_{0}$ and the uniform persistence of the parasites. Prior to proceeding, we note that when $\lambda=0$ and $\epsilon=0$, the following equality holds:

$$
\mathcal{T}_{j, 0}^{0}=\sqrt{\mathcal{R}_{j}}
$$

where the thresholds $\mathcal{R}_{j}$ are defined in (5.3).

Lemma 7.2. Let Assumptions 3.1 and 3.3 be satisfied. Then we have the following properties:

1. If $\mathcal{R}_{j}<1$ then there exists $\epsilon_{0}>0$ such that for each $\epsilon \in\left[0, \epsilon_{0}\right)$ we have $\mathrm{s}\left(\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)=\omega\left(\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)<0$

Proof. Before presenting the proofs of Items 1 and 2, we begin with some remarks. Let $\lambda>s\left(\mathcal{V}_{j}\right)$ be given. Recall from the preceding discussions that for all $\lambda>s\left(\mathcal{V}_{j}\right)$, the linear operator $\mathcal{F}_{j}^{\epsilon}\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)^{-1}$ has the same spectral radius as its restriction $\mathcal{F}_{j}^{\epsilon}\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)^{-1}: \mathcal{Y}_{1} \rightarrow \mathcal{Y}_{1}$. Let us set

$$
\mathcal{N}_{j, \epsilon}(\lambda):=\mathcal{F}_{j}^{\epsilon}\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)_{\mid \mathcal{Y}_{1}}^{-1}: \mathcal{Y}_{1} \rightarrow \mathcal{Y}_{1}, \forall \lambda>\mathrm{s}\left(\mathcal{V}_{j}\right)
$$

so that

$$
\mathrm{r}\left(\mathcal{N}_{j, \epsilon}(0)\right)=\mathrm{r}\left(\mathcal{F}_{j}^{\epsilon}\left(-\mathcal{V}_{j}\right)^{-1}\right) \Longrightarrow \mathcal{T}_{j, 0}^{\epsilon}=\mathrm{r}\left(\mathcal{N}_{j, \epsilon}(0)\right)=\sqrt{\mathrm{r}\left(\mathcal{N}_{j, \epsilon}(0)^{2}\right)}
$$

Moreover, owing to the fact that $\mathcal{Y}$ is an AL-space, we have the following equality [42, Theorem 3.14]:

$$
\mathbf{s}\left(\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)=\omega\left(\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)
$$

With these observations in place, we proceed to complete the proof.

1. Assuming $\mathcal{R}_{j}<1$, then $\mathcal{T}_{j, 0}^{0}=\sqrt{r\left(\mathcal{N}_{j, 0}(0)^{2}\right)}<1$, we observe that $\mathcal{N}_{j, \epsilon}(0)^{2}$ given by (7.8) for $\lambda=0$ is compact for each $\epsilon \geq 0$, and the mapping $\epsilon \in[0,+\infty) \mapsto \mathcal{N}_{j, \epsilon}(0)^{2} \in \mathcal{L}\left(\mathcal{Y}_{1}\right)$ is continuous. Hence, according to [10, Theorem 2.1], the function $\epsilon \in[0,+\infty) \mapsto r\left(\mathcal{N} j, \epsilon(0)^{2}\right)$ is also continuous. Consequently, there exists $\epsilon_{0}>0$ such that $\mathcal{T}_{j, 0}^{\epsilon}<1$ for all $\epsilon \in\left[0, \epsilon_{0}\right)$. Using the equality (7.6), we deduce that $s\left(\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)<0$ for all $\epsilon \in\left[0, \epsilon_{0}\right)$.
2. Assume that $\mathcal{R}_{j}>1$, then $\mathcal{T}_{j, 0}^{0}=\sqrt{\mathrm{r}\left(\mathcal{N}_{j, 0}(0)^{2}\right)}>1$. Let $\epsilon_{1}>0$ be small enough such that $C_{i}^{E_{0}}+\epsilon>0$ for each $i \in\{1,2\}$ and $\epsilon \in\left(-\epsilon_{1}, 0\right]$. Using similar arguments as for the first item, it follows that there exists $\epsilon_{0} \in\left[0, \epsilon_{1}\right)$ such that

$$
\mathcal{T}_{j, 0}^{\epsilon}=\sqrt{\mathrm{r}\left(\mathcal{N}_{j, \epsilon}(0)^{2}\right)}>1, \forall \epsilon \in\left(-\epsilon_{0}, 0\right]
$$

If Assumption 3.2 is also satisfied then using similar arguments than in Proposition 4.5 we can prove that

$$
T_{\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}}(t)=U_{1}(t)+U_{2}(t), t \geq 0
$$

where $U_{i}(t): \mathcal{Y}_{0} \rightarrow \mathcal{Y}_{0}, i \in\{1,2\}$ are bounded linear operators. Moreover, $U_{1}(t)$ is compact for each $t>0$ and $U_{2}(t)$ satisfies the estimate

$$
\left\|U_{2}(t)\right\|_{\mathcal{L}\left(\mathcal{Y}_{0}\right)} \leq K_{0}(1+t) e^{-\omega_{1} t}, \forall t \geq 0
$$

for some constants $K_{0}>0$ and $\omega_{1}>0$. Consequently, using the same arguments in [45, Proposition 2.4] we have

$$
\omega_{0, \text { ess }}\left(\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right) \leq \limsup _{t \rightarrow+\infty} \frac{\ln \left(\left\|U_{2}(t)\right\|_{\mathcal{L}\left(\mathcal{Y}_{0}\right)}\right)}{t} \leq-\omega_{1}
$$

and since $\lambda_{j}^{\epsilon}=\omega\left(\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)>0$ (by using (7.6)) it follows that $\omega_{0, \text { ess }}\left(\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)<\omega\left(\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)=\lambda_{j}^{\epsilon}=$ $\mathrm{s}\left(\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)$. The result follows from [45, Proposition 2.5] or [26, Proposition 4.6.5].

The above Lemma 7.2 has the following consequence.
Corollary 7.3. Let Assumptions 3.1 and 3.3 be satisfied. Let $\epsilon_{0}>0$ be small enough such that the conclusions of Lemma 7.2 hold. If $\mathcal{R}_{j}<1$ then for each $\epsilon \in\left[0, \epsilon_{0}\right.$ ), the zero solution of (7.2) (or equivalently (7.1)) is globally exponentially stable in $\mathcal{Y}_{0}$. Consequently, for each initial conditions $v_{j}^{\epsilon}(0, \cdot, \cdot)=v_{j, 0} \in L_{+}^{1}\left(\mathbb{R}_{+} \times \mathbb{R}, \mathbb{R}\right)$ and $m_{j}^{\epsilon}(0, \cdot)=m_{j, 0} \in L_{+}^{1}(\mathbb{R}, \mathbb{R})$ we have

$$
\lim _{t \rightarrow+\infty}\left(\int_{\mathbb{R}} m_{j}^{\epsilon}(t, x) \mathrm{d} x+\int_{\mathbb{R}} \int_{0}^{\infty} v_{j}^{\epsilon}(t, a, x) \mathrm{d} a \mathrm{~d} x\right)=0
$$

We end this section by proving the asynchronous exponential growth properties of the semigroup generated by

Proposition 7.4. Let Assumptions 3.1, 3.2, and 3.5 be satisfied. Let $\epsilon_{0}>0$ be small enough such that the conclusions of Lemma 7.2 hold. If $\mathcal{R}_{j}>1$ then for each $\epsilon \in\left(-\epsilon_{0}, 0\right]$ there exists a rank one projector $\mathcal{P}_{j}^{\epsilon}: \mathcal{Y}_{0} \rightarrow \mathcal{Y}_{0}$ such that

$$
\mathcal{P}_{j}^{\epsilon} T_{\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}}(t)=T_{\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}}(t) \mathcal{P}_{j}^{\epsilon}=e^{\lambda_{j}^{\epsilon} t} \mathcal{P}_{j}^{\epsilon}, \forall t \geq 0, \text { with } \lambda_{j}^{\epsilon}=\mathbf{s}\left(\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)>0
$$

and for each $\ell_{j, 0} \in \mathcal{Y}_{0+} \backslash\left\{0_{\mathcal{Y}_{0}}\right\}$ we have $\left\|\mathcal{P}_{j}^{\epsilon} \ell_{j, 0}\right\|_{\mathcal{Y}}>0$. Moreover, we have $e^{-\lambda_{j}^{\epsilon} t} T_{\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}}(t) \rightarrow \mathcal{P}_{j}^{\epsilon}$, when $t \rightarrow+\infty$, in the operator norm topology.

Proof. The proof relies on the Asynchronous Exponential Growth (AEG) property established by [45, Proposition 2.5], [44, Theorem 3.3] or [9, Theorem 9.10, Theorem 9.11]. Assume that $\mathcal{R}_{j}>1$. Thanks to Lemma 7.2 we have the equality $\lambda_{j}^{\epsilon}=\mathrm{s}\left(\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)=\omega\left(\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)>0$ for all $\epsilon \in\left(-\epsilon_{0}, 0\right]$. Moreover, by using the same arguments in the proof of Lemma 7.2 we have the strict inequality $\omega_{0, \text { ess }}\left(\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)<\omega\left(\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)$ with $\omega_{0, \text { ess }}\left(\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)$ is the essential growth bound of $\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}$. Therefore, to obtain the AEG property, we will prove that the semigroup generated by $\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}$ is positive irreducible. To do so, let us note that for each $\lambda$ in the resolvent set of $\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}$ we have from [25, Lemma 2.1]

$$
\begin{equation*}
\left(\lambda \mathrm{I}_{\mathrm{d}}-\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)^{-1}=\left(\lambda \mathrm{I}_{\mathrm{d}}-\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)\right)_{\mid \mathcal{Y}_{0}}^{-1} \tag{7.9}
\end{equation*}
$$

and the semigroup generated by $\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}$ is positive irreducible if there exists $\lambda_{0} \in \mathbb{R}$ such that $\left(\lambda \mathrm{I}_{\mathrm{d}}-\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)^{-1}$ is irreducible for each $\lambda>\lambda_{0}$ (see [9, Proposition 7.6]). Next, note that using (7.9) it follows that there exists $\lambda_{0}>0$ large enough such that for each $\lambda \geq \lambda_{0}$ and $\ell_{0} \in \mathcal{Y}_{0}$ we have

$$
\begin{equation*}
\left(\lambda \mathrm{I}_{\mathrm{d}}-\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)^{-1} \ell_{0}=\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)^{-1} \sum_{n=0}^{\infty}\left(\mathcal{F}_{j}^{\epsilon}\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)^{-1}\right)^{n} \ell_{0} \tag{7.10}
\end{equation*}
$$

Next let $\ell_{0} \in \mathcal{Y}_{0+}$ with $\ell_{0}=\left(0_{L^{1}}, u_{2}, u_{3}\right)^{T}$ be given. Let us set $\ell_{2}=\left(0_{L^{1}}, u_{2}, 0_{L^{1}}\right)^{T}, \ell_{3}=\left(0_{L^{1}}, 0_{L^{1}}, u_{3}\right)^{T}$ and

$$
\widehat{\ell}_{3}:=\mathcal{F}_{j}^{\epsilon}\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)^{-1} \ell_{2}
$$

Note that from the resolvent formula (7.3) and (7.4) we have $\widehat{\ell}_{3}=\left(0_{L^{1}}, 0_{L^{1}}, \widehat{u}_{3}\right)^{T}$ with

$$
\widehat{u}_{3}(x):=\int_{\mathbb{R}} k(x-y) p_{j}(y) \int_{0}^{\infty} \gamma_{j}(a, y)\left(\int_{0}^{a} e^{-\lambda(a-s)} \Pi_{j}(s, a, y) u_{2}(s, y) \mathrm{d} s\right) \mathrm{d} a \mathrm{~d} y
$$

that is by the Fubini's theorem

$$
\begin{equation*}
\widehat{u}_{3}(x):=\int_{\mathbb{R}} k(x-y) p_{j}(y) \int_{0}^{\infty}\left(\int_{s}^{\infty} \gamma_{j}(a, y) e^{-\lambda(a-s)} \Pi_{j}(s, a, y) \mathrm{d} a\right) u_{2}(s, y) \mathrm{d} s \mathrm{~d} y \tag{7.11}
\end{equation*}
$$

Next, using (7.10) we have

$$
\left(\lambda \mathrm{I}_{\mathrm{d}}-\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)^{-1} \ell_{0} \geq\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)^{-1}\left(\sum_{n=0}^{3}\left(\mathcal{F}_{j}^{\epsilon}\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)^{-1}\right)^{n} \ell_{3}+\sum_{n=0}^{3}\left(\mathcal{F}_{j}^{\epsilon}\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)^{-1}\right)^{n} \widehat{\ell}_{3}\right)
$$

Moreover using (7.7) and (7.8) we obtain

$$
\sum_{n=0}^{3}\left(\mathcal{F}_{j}^{\epsilon}\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)^{-1}\right)^{n} \ell_{3}=\left(\begin{array}{c}
\mathcal{G}_{j, \epsilon}^{\lambda}\left(u_{3}\right)+\mathcal{G}_{j, \epsilon}^{\lambda} \circ \mathcal{H}_{j}^{\lambda} \circ \mathcal{G}_{j, \epsilon}^{\lambda}\left(u_{3}\right) \\
0_{L^{1}} \\
u_{3}+\mathcal{H}_{j}^{\lambda} \circ \mathcal{G}_{j, \epsilon}^{\lambda}\left(u_{3}\right)
\end{array}\right)
$$

and

$$
\sum_{n=0}^{3}\left(\mathcal{F}_{j}^{\epsilon}\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)^{-1}\right)^{n} \widehat{\ell}_{3}=\left(\begin{array}{c}
\mathcal{G}_{j, \epsilon}^{\lambda}\left(\widehat{u}_{3}\right)+\mathcal{G}_{j, \epsilon}^{\lambda} \circ \mathcal{H}_{j}^{\lambda} \circ \mathcal{G}_{j, \epsilon}^{\lambda}\left(\widehat{u}_{3}\right) \\
0_{L^{1}} \\
\widehat{u}_{3}+\mathcal{H}_{j}^{\lambda} \circ \mathcal{G}_{j, \epsilon}^{\lambda}\left(\widehat{u}_{3}\right)
\end{array}\right)
$$

from which:

$$
\left(\lambda \mathrm{I}_{\mathrm{d}}-\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}\right)^{-1} \ell_{0} \geq\left(\lambda \mathrm{I}_{\mathrm{d}}-\mathcal{V}_{j}\right)^{-1}\left(\begin{array}{c}
\mathcal{G}_{j, \epsilon}^{\lambda} \circ \mathcal{H}_{j}^{\lambda} \circ \mathcal{G}_{j, \epsilon}^{\lambda}\left(\widehat{u}_{3}\right)+\mathcal{G}_{j, \epsilon}^{\lambda} \circ \mathcal{H}_{j}^{\lambda} \circ \mathcal{G}_{j, \epsilon}^{\lambda}\left(u_{3}\right)  \tag{7.12}\\
0_{L^{1}} \\
\mathcal{H}_{j}^{\lambda} \circ \mathcal{G}_{j, \epsilon}^{\lambda}\left(\widehat{u}_{3}\right)+\mathcal{H}_{j}^{\lambda} \circ \mathcal{G}_{j, \epsilon}^{\lambda}\left(u_{3}\right)
\end{array}\right)
$$ To conclude the proof, we note that Assumptions 3.1, 3.3, and 3.5 (see [14]) imply that the linear operator $\mathcal{H}_{j}^{\lambda} \circ \mathcal{G}_{j, \epsilon}$ is positive irreducible. Moreover, (7.11) also provides that $\widehat{u}_{3}=0_{L^{1}}$ if and only if $u_{2}=0_{L^{1}}$. Consequently if either $u_{2} \neq 0_{L^{1}}\left(\right.$ i.e $\left.\widehat{u}_{3} \neq 0_{L^{1}}\right)$ or $u_{3} \neq 0_{L^{1}}$ then we have for almost every $x \in \mathbb{R}$

$$
\left\{\begin{array}{l}
\mathcal{G}_{j, \epsilon}^{\lambda} \circ \mathcal{H}_{j}^{\lambda} \circ \mathcal{G}_{j, \epsilon}^{\lambda}\left(\widehat{u}_{3}\right)(x)+\mathcal{G}_{j, \epsilon}^{\lambda} \circ \mathcal{H}_{j}^{\lambda} \circ \mathcal{G}_{j, \epsilon}^{\lambda}\left(u_{3}\right)(x)>0  \tag{7.13}\\
\mathcal{H}_{j}^{\lambda} \circ \mathcal{G}_{j, \epsilon}^{\lambda}\left(\widehat{u}_{3}\right)(x)+\mathcal{H}_{j}^{\lambda} \circ \mathcal{G}_{j, \epsilon}^{\lambda}\left(u_{3}\right)(x)>0
\end{array}\right.
$$

${ }_{333}$ Thus, we infer from the resolvent formula of $\mathcal{V}_{j},(7.12)$ and (7.13) that the resolvent of $\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}$ is positive irreducible for all $\lambda \geq \lambda_{0}$.

### 7.2 Parasite's extinction

In this section, we prove that if $\mathcal{R}_{j}<1$, then the $j$-species goes to extinction as times goes to infinity. Consequently, if $\mathcal{R}_{0}=\max \left\{\mathcal{R}_{1}, \mathcal{R}_{2}\right\}<1$, then all species extinct as times goes to infinity. Moreover, we also show that if $\mathcal{R}_{0}>1$ then the parasite-free equilibrium state is unstable.

Proposition 7.5. Let Assumptions 3.1 and 3.3 be satisfied. Let $j \in\{1,2\}$ be given. If $\mathcal{R}_{j}<1$ then for each initial condition $\widehat{u}_{0}=\left(C_{0}, v_{0}, m_{0}\right)^{T} \in X_{+}$, the $j$-species goes to extinction, that is

$$
\lim _{t \rightarrow+\infty}\left(\int_{\mathbb{R}} m_{j}(t, x) \mathrm{d} x+\int_{\mathbb{R}} \int_{0}^{\infty} v_{j}(t, a, x) \mathrm{d} a \mathrm{~d} x\right)=0
$$

Proof. Assume that $\mathcal{R}_{j}<1$. Let $\epsilon_{0}>0$ be fixed small enough such that Corollary 7.3 is satisfied for all $\epsilon \in\left[0, \epsilon_{0}\right)$. Let us fix $\epsilon \in\left[0, \epsilon_{0}\right)$. Let $\widehat{u}_{0}=\left(C_{0}, v_{0}, m_{0}\right) \in X_{+}$be any initial condition. Thanks to Proposition 4.4 there exists $t_{0}:=t_{0}\left(\widehat{u}_{0}, \epsilon\right)>0$ such that

$$
C_{i}(t) \leq C_{i}^{E_{0}}+\epsilon, \forall t \geq t_{0}, i=1,2
$$

Consequently, we have, in a mild sense, for each $t \geq t_{0}$

$$
\left\{\begin{array}{l}
v_{j}(t, a=0, x) \leq \beta_{j}(x) m_{j}^{\epsilon}(t, x)\left(\sum_{i=1}^{j}\left(C_{i}^{E_{0}}+\epsilon\right)\right) \\
\frac{\partial v_{j}(t, a, x)}{\partial t}+\frac{\partial v_{j}(t, a, x)}{\partial a}=-\left(\mu_{2}+\gamma_{j}(a, x)\right) v_{j}(t, a, x)
\end{array}\right.
$$

and

$$
\frac{\partial m_{j}(t, x)}{\partial t}=\int_{\mathbb{R}} k(x-y) p_{j}(y)\left(\int_{0}^{\infty} \gamma_{j}(a, y) v_{j}(t, a, y) \mathrm{d} a\right) \mathrm{d} y-\left(\mu_{m, j}+I_{j}(x)\right) m_{j}(t, x)
$$

Therefore, using the comparison theorem in [28] we obtain for all $t \geq 0$

$$
\left\{\begin{array}{l}
0_{L^{1}} \leq v_{j}\left(t+t_{0}, \cdot, \cdot\right) \leq v_{j}^{\epsilon}(t, \cdot, \cdot)  \tag{7.14}\\
0_{L^{1}} \leq m_{j}\left(t+t_{0}, \cdot\right) \leq m_{j}^{\epsilon}(t, \cdot)
\end{array}\right.
$$

where $t \mapsto\left(v_{j}^{\epsilon}(t, \cdot, \cdot), m_{j}^{\epsilon}(t, \cdot)\right)^{T}$ is the mild solution to $(7.1)$ with initial condition $\left(v_{j}\left(t_{0}, \cdot, \cdot\right), m_{j}\left(t_{0}, \cdot\right)\right)^{T}$ at time $t=0$. The result follows from (7.14) and Corollary 7.3.

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Proposition 7.6. Let Assumptions 3.1 and 3.3 be satisfied. The parasite-free equilibrium state is globally asymptotically stable in $X_{+}$if $\mathcal{R}_{0}=\max \left\{\mathcal{R}_{1}, \mathcal{R}_{2}\right\}<1$. More precisely, if $\mathcal{R}_{0}<1$ then for each initial condition $\widehat{u}_{0}=\left(C_{0}, v_{0}, m_{0}\right) \in X_{+}$, we have

$$
\begin{equation*}
\lim _{t \rightarrow+\infty}\left(\int_{\mathbb{R}} m_{j}(t, x) \mathrm{d} x+\int_{\mathbb{R}} \int_{0}^{\infty} v_{j}(t, a, x) \mathrm{d} a \mathrm{~d} x\right)=0, j \in\{1,2\} \tag{7.15}
\end{equation*}
$$

and

$$
\lim _{t \rightarrow+\infty} C_{i}(t)=C_{i}^{E_{0}}, i \in\{1,2\}
$$ If in addition Assumption 3.2 is satisfied, then the parasite-free equilibrium is unstable whenever $\mathcal{R}_{0}>1$.

Proof. If $\mathcal{R}_{0}=\max \left\{\mathcal{R}_{1}, \mathcal{R}_{2}\right\}<1$ then (7.15) clearly follows from Proposition 7.5. To prove the convergence of the $C_{i}$-components, we note that the boundedness of $t \mapsto C_{i}(t), i \in\{1,2\}$ on $[0,+\infty)$ implies that (see [40, Proposition A.14]) there exist sequences $\left(t_{n}^{i}\right)$ and $\left(s_{n}^{i}\right)$ with $t_{n}^{i} \rightarrow+\infty$ and $s_{n}^{i} \rightarrow+\infty$ such that

$$
\left\{\begin{array} { l } 
{ C _ { i } ( t _ { n } ^ { i } ) \rightarrow C _ { i } ^ { \infty } = \operatorname { l i m s u p } _ { t \rightarrow + \infty } C _ { i } ( t ) }  \tag{7.16}\\
{ C _ { i } ^ { \prime } ( t _ { n } ^ { i } ) \rightarrow 0 }
\end{array} \quad \text { and } \left\{\begin{array}{l}
C_{i}\left(s_{n}^{i}\right) \rightarrow C_{i, \infty}=\liminf _{t \rightarrow+\infty} C_{i}(t) \\
C_{i}^{\prime}\left(s_{n}\right) \rightarrow 0
\end{array}\right.\right.
$$

Therefore, using (7.16) and the $C_{1}$-equation in (7.1) it comes

$$
0=\Lambda-\mu_{1,2} C_{1}^{\infty} \quad \text { and } 0=\Lambda-\mu_{1,2} C_{1, \infty} \Longrightarrow C_{1}^{\infty}=C_{1, \infty}=\frac{\Lambda}{\mu_{1,2}}
$$

that is

$$
\begin{equation*}
\lim _{t \rightarrow+\infty} C_{1}(t)=\frac{\Lambda}{\mu_{1,2}} \tag{7.17}
\end{equation*}
$$

Next, using the $C_{2}$-equation in (7.1) combined with (7.16) and (7.17) it follows that

$$
0=\mu_{1,2} \frac{\Lambda}{\mu_{1,2}}-\mu_{2} C_{2}^{\infty} \text { and } 0=\mu_{1,2} \frac{\Lambda}{\mu_{1,2}}-\mu_{2} C_{2, \infty}
$$

Therefore $C_{2, \infty}=C_{2}^{\infty}=\frac{\Lambda}{\mu_{2}}$ providing that $C_{2}(t) \rightarrow \frac{\Lambda}{\mu_{2}}$ when $t$ goes to $+\infty$. The local stability of the parasite-free equilibrium simply follows from the first item of Lemma 7.2 since the linearization of (3.3) around $E_{0}$ is (7.2) (up to the $C_{i}$-components) with $\epsilon=0$. Finally, the fact that the parasite-free equilibrium is unstable whenever $\mathcal{R}_{0}>1$ follows from the second item of Lemma 7.2.

### 7.3 Uniform persistence of parasites

In this section, we always assume that $\mathcal{R}_{0}>1$. To obtain the uniform persistence of the parasites, we introduce the maps $\xi: X_{+} \rightarrow \mathbb{R}_{+}$defined for each $\left(C_{0}, v_{0}, m_{0}\right)^{T} \in X_{+}$by

$$
\xi\left(C_{0}, v_{0}, m_{0}\right):=\sum_{j=1}^{2}\left(\int_{\mathbb{R}} m_{j, 0}(x) \mathrm{d} x+\int_{\mathbb{R}} \int_{0}^{\infty} v_{j, 0}(a, x) \mathrm{d} a \mathrm{~d} x\right)
$$

It is clear that $\xi$ is nonnegative and continuous on $X_{+}$. Next, we define the sets

$$
\mathbb{M}_{0}:=\left\{\left(C_{0}, v_{0}, m_{0}\right)^{T} \in X_{+}: \xi\left(C_{0}, v_{0}, m_{0}\right)>0\right\}
$$

and

$$
\partial \mathbb{M}_{0}:=\left\{\left(C_{0}, v_{0}, m_{0}\right)^{T} \in X_{+}: \xi\left(C_{0}, v_{0}, m_{0}\right)=0\right\}
$$

so that $X_{+}=\mathbb{M}_{0} \cup \partial \mathbb{M}_{0}$. We first prove the following lemma which states that if $\left(C_{0}, v_{0}, m_{0}\right)^{T} \in \partial \mathbb{M}_{0}$ then, independently of $\mathcal{R}_{0}$, the parasites-free equilibrium is always globally asymptotically stable on $\partial \mathbb{M}_{0}$.

Proof. The first equality of (7.18) follows from the uniqueness of the solutions of (7.1). The convergence of $C_{i}(t)$ to $C_{i}^{E_{0}}$, for $i=1,2$ can then be proven by similar arguments in Proposition 7.6.

The main result of this section is the following.
Theorem 7.8. Let Assumptions 3.1, 3.2, and 3.5 be satisfied. Assume in addition that $1<\min \left(\mathcal{R}_{1}, \mathcal{R}_{2}\right) \leq \mathcal{R}_{0}$. Then, the semiflow $\left\{\Phi_{t}\right\}_{t \geq 0}$ is $\xi$-strongly uniformly persistent on $\mathbb{M}_{0}$. More precisely, there exists $\eta>0$ such that for each initial condition $\overline{\widehat{u}}_{0}=\left(C_{0}, v_{0}, m_{0}\right)^{T} \in \mathbb{M}_{0}$ we have

$$
\liminf _{t \rightarrow+\infty} \xi\left(\Phi_{t}\left(\widehat{u}_{0}\right)\right) \geq \eta
$$

Proof. Assume that $1<\min \left(\mathcal{R}_{1}, \mathcal{R}_{2}\right) \leq \mathcal{R}_{0}$. Let $\epsilon_{0}>0$ be small enough such the conclusions of Proposition 7.4 hold true for each $\epsilon \in\left(-\epsilon_{0}, 0\right]$ and $j \in\{1,2\}$. In the following, $\epsilon$ is fixed in $\epsilon \in\left(-\epsilon_{0}, 0\right)$. Since $\left\{\Phi_{t}\right\}_{t \geq 0}$ has a compact global attractor, our result is obtained once we prove that the semiflow $\left\{\Phi_{t}\right\}_{t>0}$ is $\xi$-weakly uniformly persistent on $\mathbb{M}_{0}[29,40]$ that is there exists $\eta_{0}>0$ such that for each initial condition $\widehat{u}_{0}=\left(C_{0}, v_{0}, m_{0}\right)^{T} \in \mathbb{M}_{0}$ we have

$$
\begin{equation*}
\limsup _{t \rightarrow+\infty} \xi\left(\Phi_{t}\left(\widehat{u}_{0}\right)\right) \geq \eta_{0} \tag{7.19}
\end{equation*}
$$

To prove (7.19), we argue by contradiction. Before proceeding, let us first note that for each initial condition $\widehat{u}_{0}=\left(C_{0}, v_{0}, m_{0}\right)^{T} \in \mathbb{M}_{0}$ that is $\xi\left(\widehat{u}_{0}\right)>0$, we can prove by standard arguments that

$$
\begin{equation*}
\xi\left(\Phi_{t}\left(\widehat{u}_{0}\right)\right)=\sum_{j=1}^{2}\left(\int_{\mathbb{R}} m_{j}(t, x) \mathrm{d} x+\int_{\mathbb{R}} \int_{0}^{\infty} v_{j}(t, a, x) \mathrm{d} a \mathrm{~d} x\right)>0, \forall t \geq 0 \tag{7.20}
\end{equation*}
$$

Let $\eta_{0}>0$ be small enough such that

$$
\left\{\begin{array}{l}
\frac{\Lambda}{\mu_{1,2}+2 \eta_{0}} \geq C_{1}^{E_{0}}+\epsilon=\frac{\Lambda}{\mu_{1,2}}+\epsilon  \tag{7.21}\\
\frac{\left(\mu_{1,2}+2 \eta_{0}\right)\left(\mu_{2}+2 \eta_{0}\right)}{\mu_{0}} \geq C_{2}^{E_{0}}+\epsilon=\frac{\Lambda}{\mu_{2}}+\epsilon
\end{array}\right.
$$

Let $\widehat{u}_{0} \in \mathbb{M}_{0}$ such that

$$
\begin{equation*}
\limsup _{t \rightarrow+\infty} \xi\left(\Phi_{t}\left(\widehat{u}_{0}\right)\right)=\limsup _{t \rightarrow+\infty}\left(\int_{\mathbb{R}} m_{j}(t, x) \mathrm{d} x+\int_{\mathbb{R}} \int_{0}^{\infty} v_{j}(t, a, x) \mathrm{d} a \mathrm{~d} x\right)<\eta_{0} . \tag{7.22}
\end{equation*}
$$

Then there exists $t_{0}:=t_{0}\left(\widehat{u}_{0}\right)>0$ such that

$$
\begin{equation*}
\left(\int_{\mathbb{R}} m_{j}(t, x) \mathrm{d} x+\int_{\mathbb{R}} \int_{0}^{\infty} v_{j}(t, a, x) \mathrm{d} a \mathrm{~d} x\right) \leq \eta_{0}, \forall t \geq t_{0} \tag{7.23}
\end{equation*}
$$

From (7.23) and the $C_{i}$-equations of (7.1) we obtain

$$
\left\{\begin{array}{l}
C_{1}^{\prime}(t) \geq \Lambda-\left(\mu_{1,2}+\eta_{0}\right) C_{1}(t), t \geq t_{0}  \tag{7.24}\\
C_{2}^{\prime}(t) \geq \mu_{1,2} C_{1}(t)-\left(\mu_{2}+\eta_{0}\right) C_{2}(t), t \geq t_{0}
\end{array}\right.
$$

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Since $t \rightarrow C_{1}(t)$ is bounded on $[0,+\infty)$, there exists a sequence $\left(t_{n}\right)$ with $t_{n} \rightarrow+\infty$ such that $C_{1}\left(t_{n}\right) \rightarrow C_{1, \infty}=$ $\liminf _{t \rightarrow+\infty} C_{1}(t)$ and $C_{1}^{\prime}\left(t_{n}\right) \rightarrow 0$ (see [40, proposition A.14]). Therefore, using the first equation of (7.24) we obtain

$$
\begin{equation*}
\liminf _{t \rightarrow+\infty} C_{1}(t)=C_{1, \infty} \geq \frac{\Lambda}{\mu_{1,2}+\eta_{0}} \tag{7.25}
\end{equation*}
$$

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Since $\frac{\Lambda}{\mu_{1,2}+\eta_{0}}>\frac{\Lambda}{\mu_{1,2}+2 \eta_{0}}$, the inequality (7.25) implies that there exists $t_{1}:=t_{1}\left(\widehat{u}_{0}\right)>t_{0}$ such that

$$
\begin{equation*}
C_{1}(t) \geq \frac{\Lambda}{\mu_{1,2}+2 \eta_{0}}, \forall t \geq t_{1} \tag{7.26}
\end{equation*}
$$

Consequently, we have from the second equation of (7.24) that

$$
C_{2}^{\prime}(t) \geq \mu_{1,2} \frac{\Lambda}{\mu_{1,2}+2 \eta_{0}}-\left(\mu_{2}+\eta_{0}\right) C_{2}(t), t \geq t_{1}
$$

Using similar arguments as for the $C_{1}$-equation, we obtain

$$
\begin{equation*}
C_{2, \infty}:=\liminf _{t \rightarrow+\infty} C_{2}(t) \geq \frac{\mu_{1,2} \Lambda}{\left(\mu_{1,2}+2 \eta_{0}\right)\left(\mu_{2}+\eta_{0}\right)} \tag{7.27}
\end{equation*}
$$

Since $\frac{\mu_{1,2} \Lambda}{\left(\mu_{1,2}+2 \eta_{0}\right)\left(\mu_{2}+\eta_{0}\right)}>\frac{\mu_{1,2} \Lambda}{\left(\mu_{1,2}+2 \eta_{0}\right)\left(\mu_{2}+2 \eta_{0}\right)}$ we infer from (7.27) that there exists $t_{2}:=t_{2}\left(\widehat{u}_{0}\right)>t_{1}$ such that

$$
\begin{equation*}
C_{2}(t) \geq \frac{\mu_{1,2} \Lambda}{\left(\mu_{1,2}+2 \eta_{0}\right)\left(\mu_{2}+2 \eta_{0}\right)}, \quad \forall t \geq t_{2} \tag{7.28}
\end{equation*}
$$

$$
\begin{equation*}
C_{i}(t) \geq C_{i}^{E_{0}}+\epsilon, \quad \forall t \geq t_{2}, \quad i=1,2 \tag{7.29}
\end{equation*}
$$

The latter inequality (7.29) implies that the $m_{j}$ and $v_{j}$ components of (2.1), with $j \in\{1,2\}$, satisfy for each $t \geq t_{2}$

$$
\left\{\begin{array}{l}
v_{j}(t, a=0, x) \geq \sum_{i=1}^{j}\left(C_{i}^{E_{0}}+\epsilon\right) \beta_{j}(x) m_{j}(t, x) \\
\frac{\partial v_{j}(t, a, x)}{\partial t}+\frac{\partial v_{j}(t, a, x)}{\partial a}=-\left(\mu_{2}+\gamma_{j}(a, x)\right) v_{j}(t, a, x) \\
\frac{\partial m_{j}(t, x)}{\partial t}=\int_{\mathbb{R}} k(x-y) p_{j}(y)\left(\int_{0}^{\infty} \gamma_{j}(a, y) v_{j}(t, a, y) \mathrm{d} a\right) \mathrm{d} y-\left(\mu_{m, j}+I_{j}(x)\right) m_{j}(t, x)
\end{array}\right.
$$

Thus we obtain by comparison principles in [28] that

$$
0 \leq v_{j}^{\epsilon}(t, \cdot, \cdot) \leq v_{j}\left(t+t_{2}, \cdot, \cdot\right), j \in\{1,2\} \quad \text { and } 0 \leq m_{j}^{\epsilon}(t, \cdot) \leq m_{j}\left(t+t_{2}, \cdot\right), j \in\{1,2\}
$$

for all $t \geq 0$ where $t \mapsto\left(v_{j}^{\epsilon}(t, \cdot, \cdot), m_{j}^{\epsilon}(t, \cdot)\right)$ is the mild solution to (7.1) with initial condition $v_{j}^{\epsilon}(0, \cdot, \cdot)=v_{j}\left(t_{2}, \cdot, \cdot\right)$ and $m_{j}^{\epsilon}(0, \cdot)=m_{j}\left(t_{2}, \cdot\right)$. Setting for each $t \geq 0$ and $j \in\{1,2\}, \ell_{j}^{\epsilon}(t):=\left(0_{L^{1}}, v_{j}^{\epsilon}(t, \cdot, \cdot), m_{j}^{\epsilon}(t, \cdot)\right)$ and $\ell_{j, 0}^{\epsilon}:=$ $\left(0_{L^{1}}, v_{j}^{\epsilon}\left(t_{0}, \cdot \cdot \cdot\right), m_{j}^{\epsilon}\left(t_{0}, \cdot\right)\right)$ it comes

$$
\ell_{j}^{\epsilon}(t)=T_{\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}}(t) \ell_{j, 0}^{\epsilon}, \quad \forall t \geq 0, j \in\{1,2\} .
$$

Since $\mathcal{R}_{j}>1$ for $j \in\{1,2\}$, we infer from Proposition 7.4 that $\lambda_{j}^{\epsilon}>0$ for $j \in\{1,2\}$ and

$$
\begin{equation*}
\lim _{t \rightarrow+\infty} e^{-\lambda_{j}^{\epsilon} t}\left\|T_{\left(\mathcal{F}_{j}^{\epsilon}+\mathcal{V}_{j}\right)_{0}}(t) \ell_{j, 0}^{\epsilon}\right\|=\left\|\mathcal{P}_{j}^{\epsilon} \ell_{j, 0}^{\epsilon}\right\| \tag{7.30}
\end{equation*}
$$

Since

$$
\left\|\ell_{j, 0}^{\epsilon}\right\|=\int_{\mathbb{R}} m_{j}\left(t_{0}, x\right) \mathrm{d} x+\int_{\mathbb{R}} \int_{0}^{\infty} v_{j}\left(t_{0}, a, x\right) \mathrm{d} a \mathrm{~d} x, j \in\{1,2\}
$$

it follows from (7.20) and Proposition 7.4 that $\left\|\mathcal{P}_{1}^{\epsilon} \ell_{1,0}^{\epsilon}\right\|+\left\|\mathcal{P}_{2}^{\epsilon} \ell_{2,0}^{\epsilon}\right\|>0$. Without loss of generality, assume that $\left\|\mathcal{P}_{1}^{\epsilon} \ell_{1,0}^{\epsilon}\right\|>0$. Then (7.30) implies that

$$
\left\|T_{\left(\mathcal{F}_{1}^{\epsilon}+\mathcal{V}_{1}\right)_{0}}(t) \ell_{1,0}^{\epsilon}\right\|=\int_{\mathbb{R}} m_{1}(t, x) \mathrm{d} x+\int_{\mathbb{R}} \int_{0}^{\infty} v_{1}(t, a, x) \mathrm{d} a \mathrm{~d} x \underset{t \rightarrow+\infty}{\rightarrow}+\infty
$$

which is a contradiction to (7.22). The proof is completed.

## 8 Parameterization of the model and its typical simulation dynamics

For the numerical simulations, the ruptured functions $\gamma_{j}$ are taken as

$$
\gamma_{j}(a, x)= \begin{cases}0 & \text { if } a<\tau_{j}  \tag{8.1}\\ \alpha_{j} & \text { if } a \geq \tau_{j}\end{cases}
$$

where $\tau_{j}$ is the erythrocytic cycle duration of the $j$-species (see Table 1 for given values). We fix $\alpha_{j}=10$ for all species such that the average parasite's development period: $\int_{0}^{\infty} \exp \left(-\int_{0}^{a} \gamma_{j}(\sigma, x) \mathrm{d} \sigma\right) \mathrm{d} a=\tau_{j}+1 / \alpha_{j} \approx \tau_{j}$. We assume the mutation kernel is described by a Gaussian distribution $k(x)=k_{\varepsilon}(x)=\left(2 \pi \varepsilon^{2}\right)^{-\frac{1}{2}} e^{-\frac{1}{2}\left(\frac{x}{\varepsilon}\right)^{2}}$ for the mutation kernel, where $\varepsilon>0$ represents the standard deviation of the Gaussian mutation kernel within the phenotypic space. Malaria parasites infection efficiencies $\beta_{j}$ are assumed independent of the phenotypic values $x$, such that $\beta_{j}(x)=\beta_{j}$ for all $x$. For each simulated scenario, we assume that both the production rate $p_{j}$ and the immune response $I_{j}$ depend on the phenotypic trait $x$. More precisely, we define

$$
\begin{align*}
p_{j}(x) & =p_{j}^{\max } \times \mathcal{N}\left(x_{j}^{*}, \sigma_{j}\right)(x)  \tag{8.2}\\
I_{j}(x) & =I_{j}^{\max } \times \mathcal{N}\left(x_{j}^{*}, s_{j}\right)(x) \tag{8.3}
\end{align*}
$$

where $x_{j}^{*}$ is the dominant parasite phenotype within the $j$-malaria species. The constants $p_{j}^{\max }$ and $I_{j}^{\max }$ are respectively the maximal production rates and the maximal effect of the immune system on the dominant phenotype.

The parameter $\sigma_{j}$ allows quantifying the selectivity level $\left(\frac{1}{\sigma_{j}^{2}}\right)$ within the $j$-malaria species, while $s_{j}$ accounts for the cross immunity effect. Finally, $\mathcal{N}\left(x_{j}^{*}, s_{j}\right)$ is set for the normal probability density distribution with mean $x_{j}^{*}$ and standard deviation $s_{j}$.

Model (2.1) can then be used to illustrate various dynamics depending on the specific scenario of interest. Here we illustrate the typical dynamics simulated with the model for two scenarios.

The first scenario is when the immune system is inefficient on both malaria species ( $P$. vivax for species 1 , and $P$. falciparum for species 2). Clearly, in the absence of the immune system effect, the dominant parasite phenotype, $x_{1}^{*}$, within $P$. vivax can grow because $\mathcal{R}_{1}\left(x_{1}^{*}\right) \mid I_{1} \equiv 0>1$ (Figure 2A). This is also the case for the dominant parasite phenotype, $x_{2}^{*}$, within $P$. falciparum (Figure 2B). However, although reducing the basic reproduction numbers of both species, the immune system is not sufficiently efficient to keep the dominant parasite phenotypes below the growth threshold and we still have $\mathcal{R}_{j}\left(x_{j}^{*}\right)>1$ with the effect of the immune system (Figure 2C). The model depicts the evolutionary dynamics of interactions between $P$. vivax and $P$. falciparum in the presence of the immune system (Figures 2D,E,F). Malaria parasites of both species entirely evade control by the immune system. Figure 2D depicts the dynamics of malaria parasites and RBCs, while Figures 2 E and F illustrate the evolutionary dynamics of malaria parasites for $P$. vivax and $P$. falciparum, respectively. In this scenario, although both species coexist in equilibrium in the long term, with $P$. falciparum dominating (Figure 3), the short-term dynamics, crucial for promptly addressing infected hosts, present a contrasting configuration. Indeed, when the initial presence of both species is nearly equal, there ensues a phase where $P$. vivax predominates almost exclusively for a some duration (Figure 2D). This short-term dynamic aligns closely with the period it takes to treat a case of malaria from the onset of infection to the manifestation of symptoms.

In the second scenario, the immune system is inefficient on $P$. falciparum, species 2, and efficient on $P$. vivax, species 1. As a result, at the end, only $P$. vivax is under control because $\mathcal{R}_{1}\left(x_{1}^{*}\right)<1$, while $P$. falciparum remains uncontrolled because $\mathcal{R}_{2}\left(x_{2}^{*}\right)>1$ (Figures 4 and 5).

## 9 Conclusion and discussion

Human malaria is caused by various species of Plasmodium, such as P. falciparum and P. vivax. Mixed infections with multiple Plasmodium species are common globally but often go unrecognized or underestimated [24, 30]. Mathematical models have been developed to study parasite multiplication within hosts during mixed malaria infections $[8,11,17,23,46]$. However, these models typically address infection dynamics separately, focusing on either multiple genotypes of a single species within a host $[8,11,23,46]$, or mixed-species infection dynamics with single genotype within a host [17]. Both the within-species and inter-species diversity play crucial roles in the dynamics of malaria infection within the host. Indeed, different Plasmodium species have varying preferences for RBCs, and such ecological characteristics is fundamental to capture species diversity within the same host [17]. Furthermore, the within-species diversity is sustained by a large number of antigenic variants, exerting significant pressure on the host's immune system and which can facilitate the establishment of prolonged infections by the parasite [36, 41].

Here, we present a within-host malaria infection model incorporating the dynamics of RBCs production. We account for uninfected RBCs, including reticulocytes and mature RBCs, as well as an age-structured dynamics for parasitized RBCs. This age structure represents the time since the RBC was parasitized, allowing for a continuous description of the parasitized RBC population. The model, formulated using partial differential equations (PDEs), enables tracking of the development and maturation of parasitized RBCs, as well as a detailed depiction of the rupture of parasitized RBCs and the release of merozoites [15]. The proposed model accounts for the influence of the immune system trough the parameter function $I_{j}$, considering both the selectivity within malaria species and the cross-immunity effect. However, the model formulation explicitly allows for the introduction of the effects of interventions targeting either $P$. falciparum or $P$. vivax for treatment interventions.

We prove that the basic reproduction number $\mathcal{R}_{j}(x)$ for strain $x$ within the $j$-species can be explicitly determined using (6.1). However, deriving an explicit formula for the basic reproduction number $\mathcal{R}_{j}$ at the species level for the $j$-species is more challenging. The estimate of $\mathcal{R}_{j}$ given by (5.3) is essentially determined by the principal eigenvalue of the linear operator $L_{j}$ defined by (3.4) for any probability kernel $k$ satisfying Assumption 3.3. Though, a more explicit estimation of $\mathcal{R}_{j}$ can be accurately given when the mutation kernel $k$ depends on a small positive parameter (say $\varepsilon \ll 1$ ) with the scaling form:

$$
k_{\varepsilon}(x)=\varepsilon^{-1} k\left(\varepsilon^{-1} x\right)
$$

The parameter $\varepsilon>0$ can be interpreted as the variance of mutations in the phenotypic space. More precisely, let


Figure 2: Typical evolutionary dynamics considering the inefficiency of immune system on both malaria species (Figure 1, zone 5). (A-B) The immune system $I_{j}(x)$ and the basic reproduction numbers $\mathcal{R}_{j}(x)$ without the effect of immune system for $P$. vivax, species 1 , and $P$. falciparum, species 2. (C) The basic reproduction numbers with the effect of immune system. (D) Time evolution of young RBCs $C_{1}$ and mature RBCs $C_{2}$. (E-F) Distribution of the malaria parasites $m_{1}(t, x)$ and $m_{2}(t, x)$ with respect to time $t$ and the phenotypic trait $x$. Here, parameter values are $\left(I_{1}^{\max }, I_{2}^{\max }\right)=(10,50),\left(s_{1}, s_{2}\right)=$ $(0.09,0.09), m_{1}(0, x)=10^{5} \mathcal{N}(0.1,0.1)(x), m_{2}(0, x)=10^{5} \mathcal{N}(-0.1,0.1)(x)$, or default as shown in Table 1.


Figure 3: The long-term dynamics depicted in Figure 2 reveal a stable coexistence of both species, with $P$. falciparum exhibiting dominance of parasites.
us introduce the set

$$
\mathcal{S}_{j}=\left\{x \in \mathbb{R}: \Gamma_{j}(x)=\left\|\Gamma_{j}\right\|_{\infty}\right\}
$$

This set is commonly known as the set of Evolutionary Attractors (or dominant phenotypic values) as described in


Figure 4: Typical evolutionary dynamics considering the inefficiency of immune system on P. falciparum and its efficiency on P. vivax (Figure 1, zone 2). Panels A-F are same as to those presented in Figure 2. Here, parameter values are $\left(I_{1}^{\max }, I_{2}^{\max }\right)=(50,50),\left(s_{1}, s_{2}\right)=(0.1,0.09), m_{1}(0, x)=$ $10^{5} \mathcal{N}(0.1,0.1)(x), m_{2}(0, x)=10^{5} \mathcal{N}(-0.1,0.1)(x)$, or default as shown in Table 1.


Figure 5: The long-term dynamics depicted in Figure 4 reveal a stable persistence of only $P$. falciparum.
classical adaptive dynamics theory (e.g. [19, 32]). Indeed, when $\varepsilon>0$ is small and the reproductive function $\Gamma_{j}$ is at least of class $\mathcal{C}^{1}$ with a finite number of maxima, it has been demonstrated in [14, Theorem 2.2] that these dominant phenotypic values coincide with the set $\mathcal{S}_{j}$. Moreover, let us denote by $L_{j}^{\varepsilon}$ the operator $L_{j}$, see (3.4), with the kernel $k$ replaced by $k_{\varepsilon}$, results in [14, Theorem 2.2] indicate that the spectral radius $r\left(L_{j}^{\varepsilon}\right)$ of $L_{j}^{\varepsilon}$ satisfies, for sufficiently small $\varepsilon$,

$$
r\left(L_{j}^{\varepsilon}\right)=\Gamma_{j}\left(x^{*}\right)+\mathcal{O}(\varepsilon), \quad \text { for all } x^{*} \in \mathcal{S}_{j}
$$

Based on the aforementioned estimation, we have

$$
\mathcal{R}_{j}=\left(\sum_{i=1}^{j} C_{i}^{E_{0}}\right) \Gamma_{j}\left(x^{*}\right)+\mathcal{O}(\varepsilon)
$$

for all $x^{*} \in \mathcal{S}_{j}$. Moreover, if $\varepsilon \ll 1$, the profile of the endemic equilibrium $E_{j}$, with respect to $x \in \mathbb{R}$, can be more precisely determined. Indeed, if $\mathcal{S}_{j}=\left\{x_{j}^{*}\right\}$ and $\left(\sum_{i=1}^{j} C_{i}^{E_{0}}\right) \Gamma_{j}\left(x_{j}^{*}\right)>1$, then the unique positive stationary state $E_{j} \equiv E_{j}^{\varepsilon}$ is concentrated around the evolutionary attractor $x_{j}^{*}$ in the phenotypic space $\mathbb{R}$. For further details on this concentration phenomenon, we refer to [14, Theorem 2.3].

Through our analysis, we have determined the condition (5.6) under which $P$. vivax (species 1 ) and $P$. falciparum (species 2) can coexist. Note that the estimate (5.6) highlights a significant advantage of $P$. vivax when coexisting with $P$. falciparum, as the coexistence condition always implies $\mathcal{R}_{1}<\mathcal{R}_{2}$. We further determine the invasion fitness of a mutant in a resident population. Such invasibility analysis allows us to determine the invasibility capability for various scenarios at both the within- and between-species scales. According to Proposition 6.2, we observe that an optimization principle based on the reproduction numbers $\mathcal{R}_{j}$ is applicable either when both $P$. vivax and $P$. falciparum are the resident, or when only $P$. vivax is the resident, see (6.4). Indeed, in such a scenarios, the coexistence of multiple strains of the same species, whether $P$. vivax or $P$. falciparum, is not possible, and an intraspecies competitive exclusion principle prevails. However, the situation becomes more intricate when only $P$. falciparum serves as the resident. In the scenario where only $P$. falciparum is the resident, the coexistence of multiple strains of $P$. falciparum becomes unattainable, see (6.6). In such a configuration, the emergence of an initially rare mutant strain $y_{1}$ within the $P$. vivax species takes place when the reproductive capability $\mathcal{R}_{1}^{y_{1}}$ of the mutant strain on young RBCs and the reproductive capability $\mathcal{R}_{2}^{x_{2}}$ of the resident strain on young RBCs satisfy the condition $\mathcal{R}_{1}^{y_{1}}>\frac{\left(C_{1}^{x_{2}}+C_{2}^{x_{2}}\right) / C_{1}^{x_{2}}}{\left(C_{1}^{E_{0}}+C_{2}^{E_{0}}\right) / C_{1}^{E_{0}}} \mathcal{R}_{2}^{x_{2}}$, see (6.5). In this latter inequality, it is worth noting that the quantity $\frac{\left(C_{1}^{x_{2}}+C_{2}^{x_{2}}\right) / C_{1}^{x_{2}}}{\left(C_{1}^{E_{0}}+C_{2}^{E_{0}}\right) / C_{1}^{E_{0}}}$ is always less than unity. It means that the proportion of young RBCs in a parasite-free environment is smaller than the proportion of young red blood cells in the environment set by the resident strain.

As an example of the invasibility analysis in a multi-species and multi-genotypes setting, one may consider the scenario where $P$. falciparum has established an equilibrium, resulting in a resident parasite population primarily dominated by the phenotypic value $x_{2}$, where $\mathcal{R}_{2}^{x_{2}}>1$ (Figure 6 A ). Now, suppose an initially rare mutant population of $P$. vivax is introduced, characterized by a dominant phenotype $y_{1}$ (Figure 6A). The ability of this mutant population to invade is determined by the sign of the invasion fitness $f_{\left(\emptyset, x_{2}\right)}^{1}\left(y_{1}\right)$ as defined in (6.5). More precisely, in the first invasibility scenario, the mutant population induced by the dominant phenotype $y_{1}$ satisfies $\mathcal{R}_{1}^{y_{1}}<$ $\frac{\left(C_{1}^{x_{2}}+C_{2}^{x_{2}}\right) / C_{1}^{x_{2}}}{\left(C_{1}^{E_{0}}+C_{2}^{E_{0}}\right) / C_{1}^{E_{0}}} \mathcal{R}_{2}^{x_{2}}$ (Figure 6A). Consequently, since $f_{\left(\emptyset, x_{2}\right)}^{1}\left(y_{1}\right)<0$, this mutant population fails to invade the initial resident population (Figure 6B). Conversely, in the second invasibility scenario, the mutant population satisfies $\mathcal{R}_{1}^{y_{1}}>\frac{\left(C_{1}^{x_{2}}+C_{2}^{x_{2}}\right) / C_{1}^{x_{2}}}{\left(C_{1}^{E_{0}}+C_{2}^{E_{0}}\right) / C_{1}^{E_{0}}} \mathcal{R}_{2}^{x_{2}}$ (Figure 6 C ). As a result, since $f_{\left(\emptyset, x_{2}\right)}^{1}\left(y_{1}\right)>0$, this mutant population succeeds in invading the initial resident population (Figure 6D). It is noteworthy that the threshold $\frac{\left(C_{1}^{x_{2}}+C_{2}^{x_{2}}\right) / C_{1}^{x_{2}}}{\left(C_{1}^{E_{0}}+C_{2}^{E_{0}}\right) / C_{1}^{E_{0}}} \mathcal{R}_{2}^{x_{2}}$, above which the mutant population with the dominant strain $y_{1}$ can proliferate in the environment established by the resident population, is consistently greater than unity. Therefore, merely having a mutant with $\mathcal{R}_{1}^{y_{1}}>1$ is insufficient to ensure invasibility (Figures $6 \mathrm{~A}, \mathrm{~B}$ ). A similar invasibility analysis can be designed for the case where $P$. vivax is the resident population. Such invasibility analysis particularly highlights the importance of interactions between $P$. falciparum, $P$. vivax and the acquisition of immunity in the context of malaria within-host infections [6].

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## Conflict of interest

We declare no conflict of interest.


Figure 6: Invasibility of a $P$. vivax population in a feedback environment set by a $P$. falciparum population. A-B: $\left(I_{1}^{\max }, I_{2}^{\max }\right)=(29,100)$ and the mutant fails in invading. C-D: $\left(I_{1}^{\max }, I_{2}^{\max }\right)=$ $(26,100)$ and the mutant succeed in invading. Other parameter values are $\left(s_{1}, s_{2}\right)=(0.09,0.05)$, or default as shown in Table 1. For the initial condition, we undertake a two-step process. In Step 1, we initially simulate the model considering only species 2 ( $P$. falciparum), setting the initial conditions as follows: $m_{1}(0, x)=0, m_{2}(0, x)=10^{5} \mathcal{N}(-0.1,0.1)(x)$. In Step 2 , with species 2 already at equilibrium as established in Step 1, we introduce a mutant of species 1 ( $P$. vivax) with initial conditions given by $m_{1}(0, x)=\mathcal{N}\left(y_{1}, 0.1\right)(x)$, where $y_{1}$ is maximising $\mathcal{R}_{1}$.

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