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## Wave propagation in random 2D turbulence: a multi-scale approach

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- 8 (Received xx; revised xx; accepted xx)
- 9 To study two-dimensional dispersive waves propagating over turbulent flows, a new and less
- 10 restrictive fast waves approximation is proposed using a multiscale setting. In this ansatz,
- 11 correlation lengths of the random small scale turbulence components can be considered
- 12 negligible in the wave packet propagating frame. Still, the large-scale flow can be relatively
- 13 strong, to significantly impact wavenumbers along the propagating rays. New theoretical
- 14 results, numerical tools and proxies are derived to describe ray and wave action distributions.
- 15 All model parameters can robustly be calibrated from the large-scale flow component only.
- 16 We illustrate our purpose with ocean surface gravity waves propagating in different types
- 17 of surface currents. The multiscale solution is demonstrated to efficiently document wave
- trapping effects by intense jets.
- 19 Key words:

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MSC Codes 76B15,76M35, 82B31,82C31, 37H10, 37L55

#### 21 1. Introduction

- 22 This paper aims to revisit the ray-path concept for fast waves propagating over heterogeneous
- 23 turbulent flows. Considering ocean surface wave propagation, many authors have already
- 24 discussed the random changes of rays subject to a random current (Voronovich 1991; White
- 25 & Fornberg 1998; Smit & Janssen 2019), and consequences on wave action distributions.
- 26 Closures have been derived in the Eulerian setting (Bal & Chou 2002; Klyatskin & Koshel
- 27 2015; Borcea et al. 2019; Kafiabad et al. 2019; Bôas & Young 2020; Garnier et al. 2020).
- 28 Some of these approaches can be traced back to wave-wave interactions models, e.g.
- 29 McComas & Bretherton (1977) (see also Kafiabad et al. 2019, and reference therein). In
- 30 most cases, the central assumption is either delta-correlated turbulence (Voronovich 1976;
- 31 Klyatskin 2005; Klyatskin & Koshel 2015) and/or fast waves in comparison to fluid flow
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velocities (White & Fornberg 1998; Dysthe 2001; Bal & Chou 2002; Borcea et al. 2019; 32 Kafiabad et al. 2019; Smit & Janssen 2019; Bôas & Young 2020; Garnier et al. 2020; Boury 33 et al. 2023; Wang et al. 2023). Medium variations may be slow and delta-correlations are 34 hardly justifiable in a fixed frame. Though, attached to a fast propagating wave group, the 35 medium may seem to vary rapidly, and the delta-correlation assumption makes more sense. 36 37 Another common assumption is frozen turbulence. In such a case, weak currents also implies conservation along ray of intrinsic frequency, wavenumber, and group velocity magnitude in 38 two dimension (Boury et al. 2023). Subsequently, most of wave dynamics closures neglect 39 variations and diffusion of frequency or wavenumber. 40

The diffusion of the wave action at large distance with a multiscale decomposition of the current has already been reported Bal & Chou (2002). However, an explicit formulation for the diffusivity has solely been derived for a zero large-scale current. More generally, fast wave models mostly rely either on zero or constant current components at larger scales. West (1978), for instance, discussed acoustic waves in a two-component random media, but no velocity was involved.

Hereafter, the proposed two-scale velocity decomposition falls into the family of stochastic 47 transport models (Kunita 1997; Mikulevicius & Rozovskii 2004; Resseguier et al. 2020a; 48 Zhen et al. 2023), including dynamics under Location Uncertainty (LU) (Mémin 2014; 49 50 Resseguier et al. 2017a) and Stochastic Advection by Lie Transport (SALT) (Holm 2015). Under this framework, resulting conservative stochastic closures build on time delta-51 52 correlation for the small-scale turbulence component (Cotter et al. 2017). Nonlinear wave Hamiltonian dynamics and wave influence on currents (e.g. stokes drift) have then been 53 derived (e.g. Crisan & Holm 2018; Bauer et al. 2020; Holm 2021; Holm & Luesink 2021; 54 Dinvay & Mémin 2022; Holm et al. 2023). Considering a single-wavevector current, solutions 55 for a monochromatic shallow water wave were developed Mémin et al. (2022). In the present 56 study, our objective is restricted to the influence of turbulent flows on linear waves. 57

After first recalling the principle of ray tracing method, we present the multiscale framework for fast waves dynamics, its physical ground and a calibration method for the closure. Simplified stochastic equations are then derived for ray dynamics and wave action spectrum, in both Lagrangian and Eulerian settings. For illustrative examples, numerical tools, analytic models and proxies are applied to ocean surface gravity waves propagating through two types of 2D turbulent flows: a typical slow homogeneous turbulence and a jet case.

#### 2. Characteristics of wave-packet rays

Isolating a single progressive group of quasi-regular wave train, it follows a form  $h(x,t)e^{\mathrm{i}\phi(x,t)}+\mathrm{c.c.}$ , for most properties. If a packet is to be followed, the phase,  $\phi(x,t)$ , must smoothly vary along the propagation, i.e.  $\phi(x,t)$  is differentiable. The relative frequency is then  $\omega=-\partial_t\phi(x,t)$ , and the wave number vector  $\mathbf{k}=\nabla\phi(x,t)$ , with wavenumber  $k=\|\mathbf{k}\|$  and direction given by the normalized wave-vector,  $\tilde{\mathbf{k}}=\mathbf{k}/k=\begin{pmatrix}\cos\theta_k\\\sin\theta_k\end{pmatrix}$ . To first order, such a train of waves is dispersive and the intrinsic frequency reads

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$$\omega - \mathbf{k} \cdot \mathbf{v} = \omega_0 = \begin{cases} \operatorname{cst.} \frac{1}{\alpha} k^{\alpha}, & \alpha \neq 0 \\ \operatorname{cst.} \log(k), & \alpha = 0 \end{cases}$$
 (2.1)

and propagates with its group velocity  $\mathbf{v}_g = \nabla_k \omega$ , constantly modified by the local velocity of the currents  $\mathbf{v}$ ,

$$\frac{\mathrm{d}x_r}{\mathrm{d}t} = v_g = v_g^0 + v,\tag{2.2}$$

where  $x_r$  is the centroid of a wave group,  $v_g^0 = \frac{\partial \omega_0(k)}{\partial k} \tilde{k}$  is the group velocity without currents, i.e. solely depending on the wave vector. For  $\alpha = 1$ , the medium is non-dispersive (e.g. acoustic waves).  $\alpha = 1/2$  corresponds to gravity waves over deep ocean  $(\omega_0 = \sqrt{gk})$ . The dominant wave-vector k within the group evolves according to

$$\frac{\mathrm{d}\boldsymbol{k}}{\mathrm{d}t} = -\boldsymbol{\nabla}\boldsymbol{v}^{\mathsf{T}}\boldsymbol{k}.\tag{2.3}$$

Equations (2.2)-(2.3) are the Hamilton's eikonal equations. Along the propagating ray, velocity gradients induce linear variations. Decelerating currents will, for instance, shorten waves, and reduce the group velocity. Traveling over fields of random velocities v, the wavevector k will also become randomly distributed. Scattering of ocean surface wave packets by random currents can generally be assumed to be weak, with ||v|| of order 0.5 m.s<sup>-1</sup>, much smaller than  $v_g^0 = ||v_g^0||$  of order 10 m.s<sup>-1</sup>. Yet, cumulative effects of these random surface currents can lead to strong convergence or divergence between initially nearby ray trajectories.

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To complete the wave field description, the wave action,  $A(\mathbf{x},t) = h^2(\mathbf{x},t)/\omega_0(k(\mathbf{x},t))$ , is considered to be an adiabatic invariant in absence of source terms. Wave action is then crucial to anticipate wave transformations by currents (White 1999). Unlike wave energy, wave action is conserved, in the absence of wave generation or dissipation. This action is the integral over wave-vectors of the action spectrum, N, also related to the wave energy spectrum, E:

$$A(\mathbf{x},t) = \int d\mathbf{k} \ N(\mathbf{x},\mathbf{k},t) = \int d\mathbf{k} \ \frac{E(\mathbf{x},\mathbf{k},t)}{\omega_0(\mathbf{k},t)}.$$
 (2.4)

Action and energy spectrum quantify action and energy by unit of surface (unit of x) and by unit of wave-vector surface (unit of k). Consider the (x, k) variable change between different times  $t_i$  and  $t_f$  integrating the characteristic eikonal equations (2.2)-(2.3)

$$\begin{pmatrix} \mathbf{x}_r(t_i) \\ \mathbf{k}(t_i) \end{pmatrix} \mapsto \begin{pmatrix} \mathbf{x}_r(t_f) \\ \mathbf{k}(t_f) \end{pmatrix} \tag{2.5}$$

By the Liouville theorem and since  $\nabla_x \cdot \frac{\mathrm{d}x_r}{\mathrm{d}t} + \nabla_k \cdot \frac{\mathrm{d}k}{\mathrm{d}t} = 0$ , the state-space of the "packet-by-packet" approach (the (x, k) space) does not contract nor dilates along time. Therefore, if wave dissipation is neglected, the wave action spectrum N is conserved Lavrenov (2013), i.e.

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$$N(x_r(t_i), k(t_i), t_i) = N(x_r(t_f), k(t_f), t_f).$$
 (2.6)

This result is extremely useful because it only involves quantities of the characteristics, i.e. each Fourier mode can be modified independently of the others. The wave energy spectrum can be computed from the characteristics

$$E\left(\mathbf{x}_r(t_f), \mathbf{k}(t_f), t_f\right) = \frac{\omega_0(\mathbf{k}(t_f))}{\omega_0(\mathbf{k}(t_i))} E\left(\mathbf{x}_r(t_i), \mathbf{k}(t_i), t_i\right). \tag{2.7}$$

starting with an initial incoming wave spectrum  $E(\mathbf{x}_r(t_i), \mathbf{k}(t_i), t_i)$  for every wave-vectors  $\mathbf{k}(t_i)$ , starting from a small set of spatial points  $\mathbf{x}_r(t_i)$ .

### 111 3. A new fast wave assumption

- 112 Commonly, the Eulerian current v is decomposed into a low-frequency large-scale component
- 113  $\overline{v}$  and a transient small-scale unresolved component v':

$$v = \overline{v} + v'. \tag{3.1}$$

115 From now, we shall consider divergence-free two-dimensional currents only.

## 3.1. The ray Lagrangian correlation time

- 117 To better characterize the wave dynamics in such a random environment, the covariance of the
- fluid velocity can be evaluated in the wave group frame. To take into account the small-scale
- unresolved component v', its Eulerian spatio-temporal covariance is considered, assuming
- statistical homogeneity and stationarity for the Eulerian velocity  $v_E'(t, x) = v'(t, x)$

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$$C_{ij}^{v_E'}(\delta t, \delta \mathbf{x}) = \mathbb{E}\left(v_i'(t, \mathbf{x})v_j'(t + \delta t, \mathbf{x} + \delta \mathbf{x})\right) = \mathbb{E}\left(v_i'(t, \mathbf{x}_r(t))v_j'(t + \delta t, \mathbf{x}_r(t) + \delta \mathbf{x})\right)$$
(3.2)

- where  $x_r$  is solution of (2.2) with an arbitrary initial position  $x_r^0$ . Then, we define,  $v_R'(t) =$
- 123  $v'(t, \mathbf{x}_r(t))$ , the Lagrangian velocity along the ray  $\mathbf{x}_r(t)$ . The temporal covariance of the
- small-scale component v' in the wave group frame is the covariance of that Lagrangian velocity:

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$$C_{ij}^{v_R'}(\delta t) = \mathbb{E}\left(v_i'(t, \mathbf{x}_r(t))v_j'(t + \delta t, \mathbf{x}_r(t + \delta t))\right) = C_{ij}^{v_E'}(\delta t, \mathbf{x}_r(t + \delta t) - \mathbf{x}_r(t)),$$
 (3.3)

126 Assume a typical isotropic form for this covariance:

$$C^{\nu_E'}(\delta t, \delta \mathbf{x}) = C\left(\frac{|\delta t|}{\tau_{\nu'}} + \frac{\|\delta \mathbf{x}\|}{l_{\nu'}}\right),\tag{3.4}$$

the covariance can be evaluated in the wave group frame for small time increment  $\delta t$ :

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$$C^{v_R'}(\delta t) = C\left(\frac{|\delta t|}{\tau_{v'}} + \frac{\|\mathbf{x}_r(t'+t) - \mathbf{x}_r(t')\|}{l_{v'}}\right) = C\left(\left(\frac{1}{\tau_{v'}} + \frac{\|\mathbf{v}_g\|}{l_{v'}}\right)|\delta t| + O(\delta t^2)\right). \tag{3.5}$$

- 130 Therefore,  $\left(\frac{1}{\tau_{v'}} + \frac{\|\mathbf{v}_g\|}{l_{v'}}\right)^{-1}$  is the correlation time of  $\mathbf{v}'(t, \mathbf{x}_r(t))$ . The same derivation is valid
- for  $\nabla (v')^{\mathsf{T}}(t, \mathbf{x}_r(t))$ . For fast waves, the along-ray correlation time of the small-scale velocity
- can be approximated by  $l_{v'}/v_g^0$ . The ratio  $\epsilon$ , between this along-ray correlation time and
- the characteristic time of the wave group properties evolution, will then control the time
- 134 decorrelation assumption of v':

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$$\epsilon = \frac{l_{\nu'}}{v_g^0} \| \nabla \mathbf{v}^\mathsf{T} \| \sim \frac{l_{\nu'}}{l_\nu} \frac{\| \mathbf{v} \|}{v_g^0}. \tag{3.6}$$

- Note the Eulerian small-scale velocity v' is not necessarily time uncorrelated, as assumed
- in Voronovich (1976); Klyatskin & Koshel (2015). Yet, for small enough  $\epsilon$ , the Lagrangian
- small-scale velocity along the ray can be considered time uncorrelated. From the expression
- of  $\epsilon$ , such a condition depends upon:
- $v_g^0$ , the fast wave group velocity
- $\|v\|$ , often slow but not always negligible compared to the intrinsic wave group,  $v_g^0$ .
- $l_{v'}/l_v$ , related to the separation between large scales  $\overline{v}$  and small scales v', e.g. the
- spatial filtering cutoff of the large-scale velocity  $\overline{v}$ , but also related to its kinetic energy (KE)
- distribution over spatial scales, typically the spectrum slope.

145 This along-ray partially time-decorrelation assumption is less restrictive than the usual fast wave approximation (White & Fornberg 1998; Dysthe 2001; Bal & Chou 2002; Borcea 146 et al. 2019; Kafiabad et al. 2019; Smit & Janssen 2019; Bôas & Young 2020; Garnier et al. 147 2020; Boury et al. 2023; Wang et al. 2023) – say  $\frac{\|\mathbf{v}\|}{v_p^0} \ll 1$  – and than the SALT-LU time-148 decorrelation used for turbulence dynamics (Mémin 2014; Holm 2015; Cotter et al. 2017; 149 Resseguier et al. 2020a) – say  $\frac{l_{\nu'}}{l_{\nu}} \ll 1$ . Similarly, this last validity criterion can be obtained 150 replacing in (3.2)-(3.6)  $x_r$  by the fluid particle Lagrangian path x (solution of  $\frac{dx}{dt} = v$ ) and thus  $v_g^0$  by v. These asymptotic models often rely on averaging or homogenization 151 152 techniques (Papanicolaou & Kohler 1974; White & Fornberg 1998) to derive Markovian 153 154 dynamics involving various types of diffusivity.

## 3.2. Ray absolute diffusivity and turbulence statistics: calibration

Diffusivity is a natural tool to specify statistics of uncorrelated random media. For waves in random media, we shall specify multi-point statistics, and the Fourier space is convenient for this purpose. We will first present scalar diffusivity and then distribute it over spatial scales to fully calibrate the random velocity v'.

The absolute diffusivity (or Kubo-type formula) usually corresponds, in the so-called diffusive regime, to the variance per unit of time of a fluid particle Lagrangian path  $\frac{d\mathbf{x}(t)}{dt} = v_L(t) = v(t, \mathbf{x}(t))$ . It is approximately equal to the velocity variance times its correlation time. The Eulerian velocity covariance (3.4) will thus induce an absolute diffusivity (Piterbarg & Ostrovskii 1997; Klyatskin 2005)

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$$\frac{1}{2}a^{L} = \int_{0}^{\infty} d\delta t \ C^{v'_{L}}(\delta t) = \int_{0}^{\infty} d\delta t \ C^{v'_{E}}(\delta t, \boldsymbol{x}(t+\delta t) - \boldsymbol{x}(t)) \approx \frac{1}{2}\tau_{v'} \ C(0). \tag{3.7}$$

Along a propagating wave group, a ray absolute diffusivity occurs and slightly differs from the usual absolute diffusivity to become

$$\frac{1}{2}a^{R} = \int_{0}^{\infty} d\delta t \ C^{\nu_{R}'}(\delta t) \approx \frac{1}{2} \left( \frac{1}{\tau_{\nu'}} + \frac{\|\nu_{g}\|}{l_{\nu'}} \right)^{-1} C(0) \approx \frac{1}{2} \frac{l_{\nu'}}{\nu_{g}^{0}} C(0). \tag{3.8}$$

The absolute diffusivity sets the amplitude of the small scale velocity v'. To calibrate its spatial correlations, we may focus on its Fourier transform,  $\widehat{v'}(\kappa, t)$ , denoting by  $\kappa = \kappa \begin{pmatrix} \cos \theta_{\kappa} \\ \sin \theta_{\kappa} \end{pmatrix}$ , the surface current wave-vector. By analogy with the current kinetic energy spectra  $E_{\kappa} = \frac{1}{2} \oint_{0}^{2\pi} d\theta_{\kappa} \kappa \frac{\|\widehat{v}(\kappa, t)\|^{2}}{(2\pi)^{2}}$ , Resseguier *et al.* (2017*b*, 2020*b*) decompose the absolute diffusivity scale by scale. Referring it to Absolute Diffusivity Spectral Density (ADSD), they defined it by

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$$\frac{1}{2}A^{R}(\kappa) = \frac{1}{2}\frac{1/\kappa}{v_{g}^{0}(k)} E_{k}(\kappa), \tag{3.9}$$

where k denotes the wave wavenumber and  $\kappa$  the current wavenumber. To calibrate an equivalent noise, we model v' by  $\sigma dB_t/dt$ , where  $dB_t/dt$  is a spatio-temporal white noise and  $\sigma$  denotes a spatial filtering operator which encodes spatial correlations through  $A_{v'}^R$  and the horizontal incompressibility condition ( $\nabla \cdot \sigma = 0$ ). Specifically, we assume an ADSD power law,  $A^R(\kappa) \approx A_0^R \kappa^{-\mu}$ , and we choose a divergence-free isotropic spatial filter  $\nabla^\perp \check{\psi}_\sigma$  such that

$$\mathbf{v}' = \sigma dB_t / dt = \nabla^{\perp} \check{\psi}_{\sigma} \star dB_t / dt, \tag{3.10}$$

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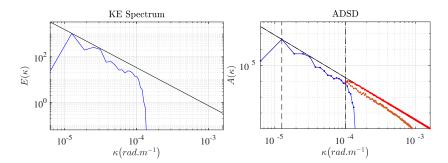


Figure 1: KE spectrum  $(m^2.s^{-2}/({\rm rad.}m^{-1}))$  (left) and ADSD  $(m^2.s^{-1}/({\rm rad.}m^{-1}))$  (right) of the resolved high-resolution velocity,  $A^R$ , in brown, low-resolution velocity,  $A^R_{\overline{\nu}}$ , in blue, and modeled stochastic velocity,  $A^R_{\nu'}(\kappa) = A^R_0 \kappa^{-\mu} - A^R_{\overline{\nu}}(\kappa)$ , in red. For the ADSD power law,  $A^R(\kappa) \approx A^R_0 \kappa^{-\mu}$ , we impose the theoretical KE spectrum slope  $-\frac{5}{3}$  (black solid line), coherently with homogeneous SQG dynamics (see "Numerical results" section). The residual ADSD (red line) is set to extrapolate that power law at small scales.

and  $\frac{\partial i \kappa^3}{(2\pi)^2} |\widehat{\psi}_{\sigma}(\kappa)|^2 = \frac{1}{2} \oint_0^{2\pi} d\theta_{\kappa} \kappa \frac{\|\widehat{\sigma dB_t}(\kappa)\|^2}{(2\pi)^2 dt} = A_{\nu'}^R(\kappa)$ . The power law assumption enables automatic closure calibration:  $A_{\nu'}^R(\kappa) = A_0^R \kappa^{-\mu} - A_{\overline{\nu}}^R(\kappa)$ , from instantaneous large-scale current statistics  $A_{\overline{\nu}}^R$  only (Resseguier *et al.* 2020*b*) as illustrated in figure 1.

## 4. Statistical wave dynamics

In a stochastic framework, the Stratonovich or Itō notations can both be used (Kunita 1997; Oksendal 1998). Under Stratonovich calculus rules, expressions become similar to deterministic ones. Specifically, stochastic versions of linearized dynamical equations are obtained by replacing  $\mathbf{v}$  by  $\overline{\mathbf{v}} + \sigma \circ \mathrm{d}B_t/\mathrm{d}t$ . Then, the stochastic transport of phase,  $\frac{\mathrm{d}}{\mathrm{d}t}\phi = \omega_0(\|\nabla\phi\|)$ , i.e. – up to that velocity replacement – the Stratonovich dispersion relation is exactly (2.1). The method of characteristics also applies. Note, one can switch from Stratonovich to Itō notations, where  $\mathbf{v}'$  corresponds to  $\sigma \mathrm{d}B_t/\mathrm{d}t$ . The characteristics equations (2.2)-(2.3) also remain unchanged for homogeneous and isotropic  $\mathbf{v}'$ :

$$\begin{cases}
dx_r = (v_g^0 + \overline{v})dt + \sigma dB_t, \\
dk = -\nabla (\overline{v}dt + \sigma dB_t)^{\mathsf{T}}k.
\end{cases} (4.1)$$

## 4.1. Single-ray stochastic differential equations

When studying a single ray in an homogeneous and isotropic turbulence (3.10), the wave-vector dynamics simplifies. In the local crest-oriented frame, the influence of small scale currents can be solely represented by four one-dimensional white noise forcings.

Notably, dynamics of wave-vectors (2.3) are similar to tracer gradient dynamics (Bühler 2009; Plougonven & Zhang 2014). Only the coupled ray path dynamics (2.2) differs. Accordingly, we follow the notations and derivations of the mixing analysis from Lapeyre *et al.* (1999) and references therein. Without loss of generality, the large-scale velocity can be parameterized as

$$\overline{\boldsymbol{v}} = \overline{\boldsymbol{v}} \begin{pmatrix} \cos \overline{\theta} \\ \sin \overline{\theta} \end{pmatrix} \quad \text{and} \quad \boldsymbol{\nabla} \overline{\boldsymbol{v}}^{\mathsf{T}} = \frac{1}{2} \begin{bmatrix} \overline{\sigma} \sin 2\overline{\phi} & \overline{\omega} + \overline{\sigma} \cos 2\overline{\phi} \\ -\overline{\omega} + \overline{\sigma} \cos 2\overline{\phi} & -\overline{\sigma} \sin 2\overline{\phi} \end{bmatrix}. \tag{4.2}$$

The influence of the large-scale currents on the ray dynamics (4.1), expressed in the local crest-oriented frame ( $\tilde{k}$ ,  $\tilde{k}^{\perp}$ ), is straightforward (Lapeyre *et al.* 1999). The small-scale

currents force the ray dynamics through a stochastic noise. For a single ray  $(x_r, k) = (x_r, y_r, k \cos \theta_k, k \sin \theta_k)$ , this noise can be rigorously described by four independent one-dimensional white noises only (see Appendix),  $\dot{B}_t^{(1)}$ ,  $\dot{B}_t^{(2)}$ ,  $\dot{B}_t^{(3)}$ , and  $\dot{B}_t^{(4)}$ , and:

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$$\frac{\mathrm{d}}{\mathrm{d}t}x_r = v_g^0 \cos\theta_k + \overline{v}\cos\overline{\theta} + \sqrt{a_0}\dot{B}_t^{(1)}, \tag{4.3}$$

$$\frac{\mathrm{d}}{\mathrm{d}t}y_r = v_g^0 \sin\theta_k + \overline{v}\sin\overline{\theta} + \sqrt{a_0}\dot{B}_t^{(2)},\tag{4.4}$$

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$$\frac{\mathrm{d}}{\mathrm{d}t}\log k = -\overline{\sigma}\sin(\zeta) + \gamma_0 + \sqrt{\gamma_0}\dot{B}_t^{(3)}, \tag{4.5}$$

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$$\frac{\mathrm{d}}{\mathrm{d}t}\theta_k = \frac{1}{2}(\overline{\omega} - \overline{\sigma}\cos(\zeta)) + \sqrt{3\gamma_0}\dot{B}_t^{(4)}, \tag{4.6}$$

where  $\zeta = 2(\theta_k + \overline{\phi})$  and

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$$a_0 = \frac{1}{2dt} \mathbb{E} \|\sigma dB_t\|^2 = \int_0^{+\infty} A_{v'}^R(k) dk, \tag{4.7}$$

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$$\gamma_0 = \frac{1}{8dt} \mathbb{E} \| \nabla_{\mathbf{x}} (\sigma dB_t)^{\mathsf{T}} \|^2 = \frac{1}{4} \int_0^{+\infty} k^2 A_{\nu'}^R(k) dk \tag{4.8}$$

Diffusivity constants depend through (3.9) on both the correlation length and the spectrum slope of the small-scale velocity. Contrasting the classical fast wave approximation, the wavenumber does vary. This is due to (i) the finite large-scale strain rate,  $\overline{\sigma}$ , and (ii) the small-scale isotropic velocity model (3.10). This isotropy assumption and its implication are discussed in Appendix. Note that neither large-scale nor small-scale component is assumed to be steady, even though the small-scale time variations are mainly driven by the wave speed and not by their Eulerian correlation time. The current unsteadiness can also lead to wavenumber variations (Dong et al. 2020; Cox et al. 2023; Boury et al. 2023). Given a known wavevector angle, it leads to a wavenumber evolution 

$$k(t) = k(0) \exp\left(-\int_0^t \overline{\sigma} \sin(2(\theta_k + \overline{\phi}))\right) \exp\left(\gamma_0 t + \sqrt{\gamma_0} B_t^{(3)}\right), \tag{4.9}$$

and hence the complete wavevector distribution, i.e. the wave spectrum. The second exponential factor in (4.9) is a geometric Brownian motion. Its mean diverges in time exponentially rapidly. Physically, shear and strain of v' tends to shorten the wavelength (Voronovich 1991; Boury *et al.* 2023) leading to this divergence. This factor has a log-normal distribution, suggesting possible extreme transient wavenumber events. This generalizes previous results Voronovich (1991); Klyatskin & Koshel (2015), obtained with neglecting the time-correlated current component,  $\overline{v}$ .

For completeness, the action distribution over space and wave vector can be derived. Some approaches consider finite-size wave trains either through additional equations (Jonsson 1990; White & Fornberg 1998) or re-meshing (Hell *et al.* in preparation). Otherwise, each ray transports its action spectrum (2.6) and we need to numerically combine many rays (Lavrenov 2013), or rely on analytic approximations. Typically, we solve (4.3)-(4.5) exhibiting,  $p(x, k|x_r^0, k_r^0, t)$ , the distribution of the ray (x, k) at time t given initial conditions  $(x_r^0, k^0)$ . Then, by analogy with tracers in incompressible turbulence (Piterbarg & Ostrovskii 1997, equation (1.31)) we can evaluate the wave action spectrum mean – or any point-wise statistics – as follows

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$$\mathbb{E}N(\mathbf{x}, \mathbf{k}, t) = \iint d\mathbf{x}_r^0 d\mathbf{k}^0 N^0(\mathbf{x}_r^0, \mathbf{k}_r^0) p(\mathbf{x}, \mathbf{k} | \mathbf{x}_r^0, \mathbf{k}^0, t)$$
(4.10)

where  $N^0$  is the initial wave action spectrum. Integrating this expression over wavevectors,

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we note that the wave action mean solely depends of group positions distribution

$$\mathbb{E}A(\mathbf{x},t) = \iint d\mathbf{x}_r^0 d\mathbf{k}^0 N^0(\mathbf{x}_r^0, \mathbf{k}_r^0) p(\mathbf{x}|\mathbf{x}_r^0, \mathbf{k}^0, t)$$
(4.11)

Multi-point action statistics – e.g. focusing  $\mathbb{E}\|\nabla_x A\|^2$  – rely on multi-ray correlations, encoded in the stochastic characteristic equations (4.1), but not the simplified model (4.3)-(4.6). Alternatively, Eulerian descriptions of wave action dynamics directly provide action distribution over space and wave vector.

#### 4.2. Eulerian dynamics and action diffusion

Wave action spectrum is transported along a 4-dimensional volume-preserving stochastic flow (4.1). Again by analogy with incompressible turbulence (Resseguier *et al.* 2017*a*), the stochastic transport of wave action spectrum in Itō notations reads

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$$\partial_{t}N + (\mathbf{v}_{g}^{0} + \overline{\mathbf{v}} + \sigma \frac{\mathrm{d}B_{t}}{\mathrm{d}t}) \cdot \nabla_{\mathbf{x}}N + \left(-\nabla_{\mathbf{x}}(\overline{\mathbf{v}} + \sigma \frac{\mathrm{d}B_{t}}{\mathrm{d}t})^{\mathsf{T}}\mathbf{k}\right) \cdot \nabla_{\mathbf{k}}N$$

$$= \begin{bmatrix} \nabla_{\mathbf{x}} \\ \nabla_{\mathbf{k}} \end{bmatrix} \cdot \left(\mathbf{D} \begin{bmatrix} \nabla_{\mathbf{x}} \\ \nabla_{\mathbf{k}} \end{bmatrix} N\right) = \frac{1}{2}a_{0}\Delta_{\mathbf{x}}N + \frac{1}{2}\gamma_{0}\frac{1}{k}\partial_{k}\left(k^{3}\partial_{k}N\right) + \frac{3}{2}\gamma_{0}\partial_{\theta_{k}}^{2}N. \tag{4.12}$$

The RHS is reminiscent to Eq. (3.16) in Bôas & Young (2020) and Eq. (36) in Smit & Janssen (2019), and more generally to rapid wave models. Nevertheless, equation (4.12) is not averaged and explicitly involves large-scale currents and noise terms (terms with factor  $\frac{dB_t}{dt}$ ). Differences with Smit & Janssen (2019); Bôas & Young (2020) for the diffusivity estimates and the detailed computation of the 4 × 4 diffusion matrix  $\boldsymbol{D}$  can be found in Appendix. Itō notations of (4.12) explicitly separate mean terms (e.g. diffusion terms) and zero-mean noise terms. Here, the Eulerian Itō notations reveal that coefficients  $\frac{1}{2}a_0$ ,  $\frac{1}{2}\gamma_0$ , and  $\frac{3}{2}\gamma_0$  act to diffuse wave action in space, wavenumber and wave-vector angle, respectively.

#### 5. Numerical experiments

To illustrate these developments, we consider ocean surface gravity waves propagating over a dynamical flow region. Ray tracing through synthetic surface currents will provide a benchmark. It will be shown that a broad range of the current scales can be replaced by the stochastic parametrization (3.10) without affecting ray scattering and action distribution. Theoretical results (4.3)-(4.12) will suggest approximate analytic solutions.

#### 5.1. Surface current dynamics

273 Simplified upper ocean dynamics are considered to follow:

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$$(\partial_t + \mathbf{v} \cdot \nabla) \Theta = 0 \text{ with } \mathbf{v} = -\nabla^{\perp} (-\Delta)^{-\xi} \Theta.$$
 (5.1)

Two extreme cases: the Surface Quasi-Geostrophic dynamics ( $\xi = \frac{1}{2}$ ) (Pierrehumbert 275 1994; Lapeyre 2017), abbreviated SQG, and the two-dimensional Euler dynamics ( $\xi = 1$ ), 276 abbreviated 2D Euler. SQG is a dynamics with an extreme locality (KE spectrum slope -5/3) 277 whereas 2D Euler has an extreme non-locality (KE spectrum slope -3). The objective is to test 278 how the proposed closures apply for both dynamics - and possibly beyond validity of rapid 279 wave models – to also be useful for any more realistic upper ocean dynamics. Additionally, 280 test cases are developed to assess the multiscale stochastic closure in both homogeneous and 281 heterogeneous propagating medium. First, surface fast waves travel in a homogeneous and 282 283 isotropic SQG turbulence, then waves propagate in a spatially localized 2D Euler turbulence, mimicking an oceanic jet. For both SQG and 2D Euler dynamics, a reference simulation is 284

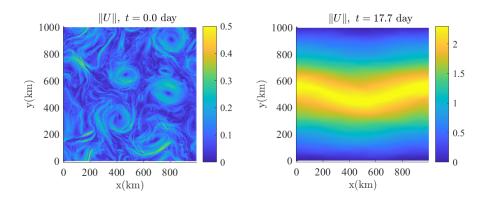


Figure 2: Current velocity norm of the SQG homogeneous turbulence (left) and of the 2D Euler jet current at high-resolution  $(512 \times 512)$ .

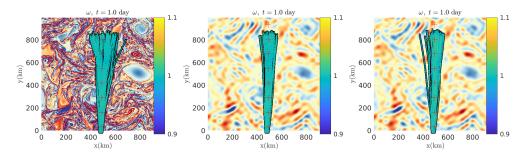


Figure 3: Swell interacting with a high-resolution (512 × 512) deterministic SQG current (left), a low-resolution (32 × 32) deterministic SQG current (middle) and a low-resolution (32 × 32) deterministic SQG current plus (one realization of) the time-uncorrelated stochastic model (right) – colored by the corresponding wave amplitude (right-hand side colorbar) – computed by forward advection and superimposed on the current vorticity  $\omega = \nabla^{\perp} \cdot \nu$ . The red cross indicate where the bidirectional wave spectra of figure 4 are computed.

obtained at a resolution  $512 \times 512$  for a 1000-km squared domain, through a pseudo-spectral code (Resseguier *et al.* 2017*b*, 2020*b*). Once initialized, the current velocity v is about 0.1 m.s<sup>-1</sup> for the homogeneous turbulence and 1 m.s<sup>-1</sup> for the jet (see figure 2).

## 5.2. Rays scattering in homogeneous SQG turbulence

A wave system enters the bottom boundary, propagating to the top. The carrier incident wave has an intrinsic wave group velocity of 10 m/s, i.e. wavelength  $\lambda = 250$  m. Its envelope is Gaussian with an isotropic spatial extension of  $30\lambda$ . The left panels of figures 3 and 4 illustrates the resulting branched regime, spreading the wavevectors (figure 4) of the incoming waves. From bottom to top, spectral diffusion occurs (figure 4), in the direction orthogonal (here  $k_x$ ) to the propagation (here  $k_y$ ), in line with equation (4.6). This accelerates – along the propagation – the wave position spread (figure 3). This acceleration is explained by the ray equation (4.3) dominated by the intrinsic wave group velocity.

To mimic a badly resolved  $\overline{v}$  field, v is smoothed at a resolution  $32 \times 32$ . Using this coarse-scale current, middle panels of figures 3 and 4, the branched regime is strongly depleting, i.e. the spectral small-scale turbulence diffusion is missing. A stochastic current v' is then

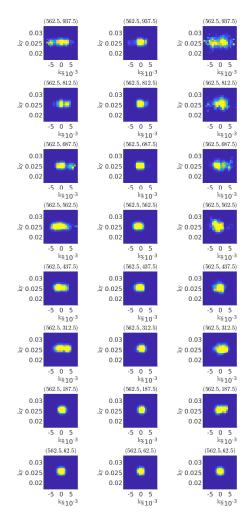


Figure 4: Bidirectional wave spectra, computed by backward advection, at 8 locations along a vertical axis (the mean wave propagation direction) resulting from a swell interacting with a high-resolution (512 × 512) deterministic SQG current (left), a low-resolution (32 × 32) deterministic SQG current (middle) and a low-resolution (32 × 32) deterministic SQG current plus (one realization of) the stochastic model (3.10) (right). The spatial locations where the spectra are calculated are specified on top of each image. We point out these locations on figure 3 by the red crosses.

added for ray tracing (4.1). This stochastic component is divergence-free and has a self-similar distribution of energy across spatial scales (3.10) (see figure 1). The resulting spatial and spectral spreads are now comparable to simulations with high-resolution currents. For this setting, the stochastic closure provides satisfying results for a sufficiently well-resolved large-scale current. The key decorrelation ratio  $\epsilon = \frac{l_{\nu'}}{l_{\nu}} \frac{\|\nu\|}{\nu_g^0}$  indeed depends on the resolution through  $l_{\nu'}$ . The large-scale current  $\overline{\nu}$  is resolved on a 32×32 grid, i.e. with a resolution

 $l_{v'} = \frac{\|\nabla v^{\mathsf{T}}\|}{\|\nabla v'^{\mathsf{T}}\|} l_v = 0.33 \ l_v$ . As such  $\epsilon = 4.1 \times 10^{-3}$ , computed with  $v_g^0 \simeq 10 \ \mathrm{m.s^{-1}}$  and  $\|v\| \simeq 0.12 \ \mathrm{m.s^{-1}}$ , so  $\frac{\|v\|}{v_g^0} \simeq 1.2 \times 10^{-2}$ , which is sufficiently small to make the proposed 307 model applicable. 308 From the ADSD estimate (equation (3.9) illustrated by figure 1) and (4.7)-(4.8), evaluations 309 of the diffusivity coefficients  $a_0$  and  $\gamma_0$  are straightforward. Previously discussed Smit & 310 311 312

Janssen (2019), the spatial diffusivity is extremely weak:  $a_0 = 6.4 \times 10^{-1} \text{ m}^2 \text{ s}^{-1}$  (spatial variations in ray equations (4.3)-(4.4) of about  $\sqrt{a_0t} = 230 \text{ m}$  during 1 day). In contrast, the spectral angle diffusivity is large:  $3\gamma_0 = 3.0 \times 10^{-8} \text{ rad}^2 \text{ s}^{-1}$ . Along our 1-day simulation, neglecting large-scale velocity influence, (4.6) leads to a Brownian wave vector angle variations  $\delta\theta_k = \theta_k - \theta_k(0) = \sqrt{3\gamma_0}B_t^{(4)}$  with a standard deviation  $\sigma_{\delta\theta_k} = \sqrt{3\gamma_0t} = 5.2 \times 10^{-2} \text{ rad} \approx 3.0^\circ$ , eventually increasing the wave group spectral maximal extension from 313 314 315 316

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$$\pm 2\sigma_{k_x} = \pm 2\frac{2\pi}{30\lambda} = \pm 1.7 \times 10^{-3} \text{ rad.m}^{-1} \text{ to } \pm 2\sigma_{k_x} \approx \pm 2\sqrt{\left(\frac{2\pi}{30\lambda}\right)^2 + \left(k\sigma_{\delta\theta_k}\right)^2} = \pm 3.1 \times 10^{-3}$$

rad.m<sup>-1</sup>, confirmed by figure 4. This figure also illustrates the wave action diffusion induced 318 by diffusivity  $\gamma_0$ , well predicted by the Eulerian wave action model (4.12). In the branched 319 regime, the increased angle variability leads, by advection, to a spatial spread. The simplified ray equation (4.3) gives  $\delta x \approx \int_0^t v_g^0 \cos \theta_k \approx v_g^0 \int_0^t \delta \theta_k \approx v_g^0 \sqrt{3\gamma_0} \int_0^t B_{t'}^{(4)}$  with maximal 320 321 extension  $\pm 2\sigma_x \approx \pm 2v_p^0 \sqrt{\gamma_0 t^3} \approx \pm 52$  km, in agreement with figure 3. Finally, we estimate a 322 first-order delay along the propagation  $\delta t = t - (y - y(0))/v_g^0 \approx \int_0^t (1 - \sin \theta_k) \approx \frac{1}{2} \int_0^t \delta \theta_k^2 \approx 1$ 323

 $\frac{3}{2}\gamma_0 \int_0^t (B_{t'}^{(4)})^2$ , with mean value  $\mathbb{E}\delta t = \frac{3}{4}\gamma_0 t^2$ . 324

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## 5.3. Wave groups trapped in a 2D Euler turbulent jet

Tests are now performed for rays traveling in fast and strongly heterogeneous 2D Euler flows. 326 Classical fast wave models – assuming flows of weak amplitude and often uniform statistics – 327 are expected to fail here. Jets exhibit strong current gradients (e.g. Kudryavtsev et al. 2017) 328 creating strong ray focusing and possibly rogue events. Passing through localized spatial 329 330 structures, caustics can appear but solely from unrealistically collimated wave trains (White & Fornberg 1998; Heller et al. 2008; Wang et al. 2023). Occurrences strongly reduce for 331 finite directional spread (Slunyaev & Shrira 2023). Here, wave groups are trapped in a jet, but 332 nonlinear wave interactions are neglected. The high-resolution numerical simulations (see 333 figure 5) reveal that even linear wave trains are well trapped in adversarial currents. Freund 334 & Fleischman (2002) observed a similar behavior for acoustic waves in a 3D turbulent jet. 335 Note that during our simulation, rays cross the domain several times (because of the doubly 336 periodic boundary conditions, see appendix for technical details). Top (resp. bottom) of the 337 jet, the vorticity and thus – at first order – rays curvatures (Dysthe 2001) are negative (resp. 338 positve). Therefore, rays oscillate around the jet. A toy model can explain this behavior. 339 Following the multiscale stochastic approach (4.3)-(4.6), wave scattering is also taken into 340 account. 341

For very-coarsed-grained (4  $\times$  4) current  $\overline{v}$ , oscillation remains, but most of the scattering vanishes, as illustrated by figure 6. Moreover, the curvature of the jet creates artificial wave focusing at t = 8 and 10 days. Introducing a time-uncorrelated model (3.10) corrects the resolution issue on figure 7. Figure 8 plots the current ADSD. The current is strong ( $||v|| \approx 1.4$ m.s<sup>-1</sup>), and the usual fast wave approximation cannot be applied  $(\frac{\|\mathbf{v}\|}{v_g^0} \simeq 1.2 \times 10^{-1})$ . However, the proposed modified fast wave model is valid, even at the very coarse  $4 \times 4$  resolution. Indeed, 2D Euler spectra are steeper than for SQG dynamics, and the length scale ratio is

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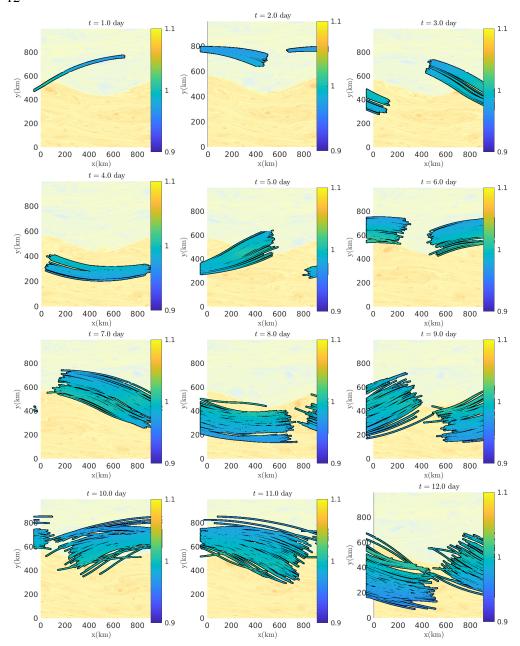


Figure 5: Rays facing a high-resolution (512 × 512) deterministic 2D Euler jet current – colored by the corresponding wave amplitude (right-hand side colorbar) – computed by forward advection and superimposed on the current vorticity  $\omega = \nabla^{\perp} \cdot \nu$ .

already significant at this resolution,  $\frac{l_{\nu'}}{l_{\nu}} = 0.14$ , and the derived time-decorrelation ratio is small:  $\epsilon = \frac{l_{\nu'}}{l_{\nu}} \frac{\|\mathbf{v}\|}{v_g^0} = 1.6 \times 10^{-2}$ .

Furthermore, by approximating the under-resolved current  $\overline{v}$ , an analytic stochastic solution can be obtained for a ray traveling against the current. The large-scale pattern of the jet takes

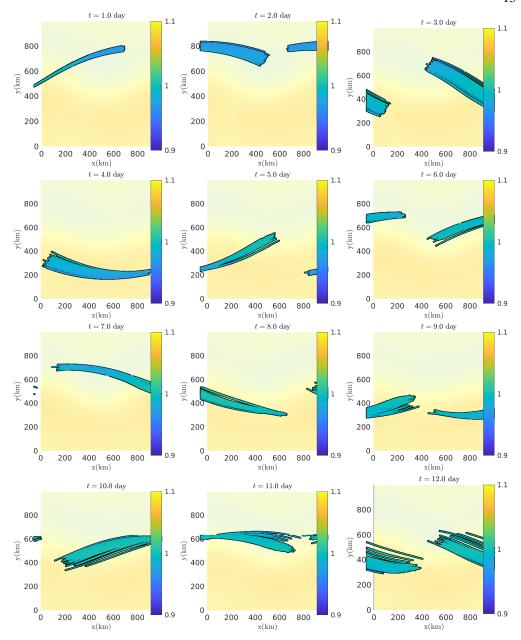


Figure 6: Rays facing a low-resolution (4 × 4) deterministic 2D Euler jet current – colored by the corresponding wave amplitude (right-hand side colorbar) – computed by forward advection and superimposed on the current vorticity  $\omega = \nabla^{\perp} \cdot \mathbf{v}$ .

353 a quadratic form

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$$\overline{u} \approx \overline{U}_0 - \frac{1}{2}\overline{\beta} \left( y - \frac{L_y}{2} \right)^2$$
 and  $\overline{v} \approx 0$ , with  $\overline{U}_0, \overline{\beta} < 0$  (5.2)

Note, the toy model (5.2) simply considers a straight jet, neglecting its curvature. For weak subgrid currents and a ray,  $(x_r, y'_r + \frac{L_y}{2}, k, \theta_k)$ , propagating mainly to the right,  $\theta_k$  is small

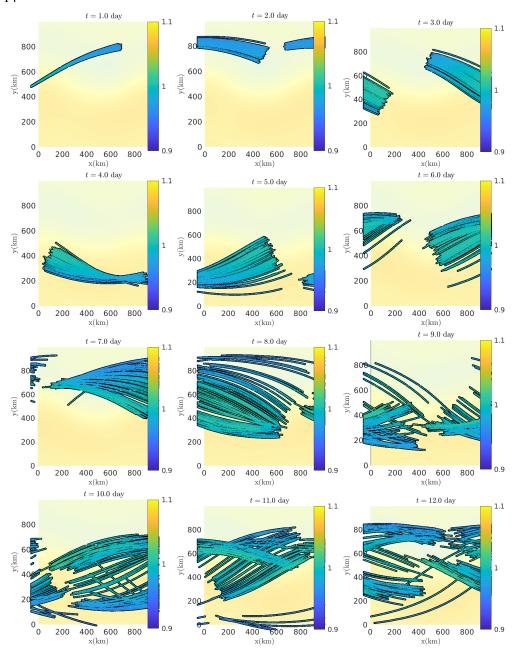


Figure 7: Rays facing a low-resolution (4 × 4) deterministic 2D Euler jet current plus (one realization of) the time-uncorrelated stochastic model – colored by the corresponding wave amplitude (right-hand side colorbar) – computed by forward advection and superimposed on the current vorticity  $\omega = \nabla^{\perp} \cdot \nu$ .

and the simplified ray equation (4.4) determines the group position with respect to the jet  $y'_r$ 

$$\frac{\mathrm{d}}{\mathrm{d}t}y_r' \approx v_g^0 \sin(\theta_k) = v_g^0 \theta_k + O(\theta_k^2). \tag{5.3}$$

For frozen turbulence, the wave-number and hence  $v_g^0$  will not significantly vary. The other

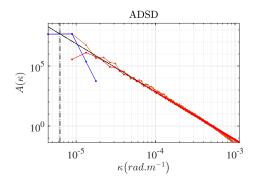


Figure 8: ADSD  $(m^2.s^{-1}/(rad.m^{-1}))$  of the resolved high-resolution jet velocity in brown, low-resolution jet velocity in blue, and modeled stochastic velocity, in red. The theoretical spectrum slope -3 (black solid line) is imposed, consistent with homogeneous 2D Euler dynamics. The residual ADSD (red line) is set to extrapolate that power law at small scales.

ray equation (4.3) localizes the group along the jet,  $x_r \approx x_r(0) + (v_g^0 - \overline{u})t$ , dropping the  $O(\theta_k^2)$  from now on. Moreover,  $\tilde{k}^{\perp} \cdot \nabla \overline{v}^{\intercal} \tilde{k} \approx -\partial_y \overline{u}$  and the dynamics of wave vector angle (4.6) simplifies to a stochastic oscillator equation:

$$\frac{\mathrm{d}^2}{\mathrm{d}t^2} y_r' = v_g^0 \frac{\mathrm{d}}{\mathrm{d}t} \theta_k = -\partial_y (v_g^0 \overline{u}) + v_g^0 \sqrt{3\gamma_0} \dot{B}_t^{(4)} = -\overline{\omega}_r^2 y_r' + v_g^0 \sqrt{3\gamma_0} \dot{B}_t^{(4)}. \tag{5.4}$$

with  $\overline{\omega}_r = \sqrt{|v_g^0 \overline{\beta}|}$ . Here  $v_g^0 \overline{u}$  plays the role of a potential, trapping the rays in the jet vicinity, whereas the noise accounts for wave scattering. Solution of this linear equation is known (e.g. Resseguier *et al.* 2017*a*, Eq.(51)-(55)):

$$y_{r}(t) = \underbrace{\frac{L_{y}}{2} + y_{r}'(0)\cos(\overline{\omega}_{r}t) + \frac{v_{g}^{0}}{\overline{\omega}_{r}}\theta_{k}(0)\sin(\overline{\omega}_{r}t)}_{=\mathbb{E}(y_{r}(t))} + \underbrace{Y_{y_{0}}\sqrt{\overline{\omega}_{r}}\int_{0}^{\tau}\sin(\overline{\omega}_{r}(t-r))dB_{r}^{(4)}}_{=y_{r}''(t)}, (5.5)$$

with  $Y_{\gamma_0} = v_g^0 \sqrt{3\gamma_0/\overline{\omega}_r^3}$ . The wavevector angle solution is similar. The solution ensemble mean,  $\mathbb{E}y_r$ , is a simple coherent deterministic oscillator. This mean solution describes well 368 369 the interaction between the group and the under-resolved current from figure 6. From the 370 coarse-scale vorticity shear plotted in figure 9 in the vicinity of the jet, we can estimate 371  $\overline{\beta} = -2.7 \times 10^{-11} \text{m}^{-1}.\text{s}^{-1}$ . It yields an oscillation frequency  $\overline{\omega}_r = 1.3 \times 10^{-5} \text{rad.s}^{-1}$  i.e. a 372 period of  $2\pi/\overline{\omega}_r = 5.7$  days, in agreement with the ray tracing simulations. Note that the 373 high-resolution vorticity shear, left panel of figure 9, does not suggest any relevant values to 374 375 explain the ray oscillations. Only the proposed multiscale current decomposition provides a quantitative explanation for these oscillations, and by extension for trapping rays inside the 376 377 jet. Added to the mean solution, the random parts,  $y_r''(t)$ , are continuous summations of zeromean incoherent wave fluctuations. At each time r, the additive random forcing introduces 378 an oscillation. But, the influence of the past excitations is weighed by sine wave due to the 379 phase change. The group position and wavevector angle are Gaussian random variables (as 380 linear combinations of independent Gaussian variables). Therefore, their finite dimensional 381 382 law (i.e. the multi-time probability density function) are entirely defined by their mean and covariance functions. Specifically,

$$384\mathbb{E}\left(y_r''(t)y_r''(t+\tau)\right) = \frac{1}{4}Y_{\gamma_0}^2\left(\cos(\overline{\omega}_r\tau)\left(2\overline{\omega}_rt - \sin(2\overline{\omega}_rt)\right) + \sin(\overline{\omega}_r\tau)\left(1 - \cos(2\overline{\omega}_rt)\right)\right). \tag{5.6}$$

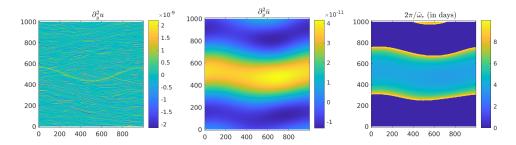


Figure 9: Vorticity shear  $\partial_y^2 u$  of the deterministic 2D Euler jet current at high-resolution (512 × 512) (left), at low-resolution (4 × 4) (middle), and the corresponding swell system period  $2\pi/\overline{\omega}_r$ . Far from the jet (±200 km away), the vorticity shear becomes zero or even positive, so period larger than 10 days are cropped.

In particular, the variance of the vertical positions reads  $\sigma_y^2(t) = \frac{1}{4}Y_{\gamma_0}^2 \ (2\overline{\omega}_r t - \sin(2\overline{\omega}_r t))$ . At  $t = 2\pi/\overline{\omega}_r$ , the group has oscillated once around the jet and the maximal position extension reaches  $\pm 2\sigma_y = \pm 2\sqrt{\pi} \ Y_{\gamma_0} = \pm 42$  km, well confirmed by ray simulations. In contrast, usual fast wave models (e.g. Smit & Janssen 2019) do not consider the interplay between smooth and rough currents, and hence solely predict a classical branched regime with a much faster vertical location spreading:  $\pm 2\sigma_y = \pm 2\sqrt{(2\pi)^3/3} \ Y_{\gamma_0} = \pm 217$  km. For large time, our multiscale approach predicts a scaling in t, much slower than the usual  $t^3$  scaling of the branched regime.

From the group vertical location and wavevector angle, we can also solve (4.5) analytically to estimate the group wavenumber variations. For small wavevector angles,  $-\int_0^t \overline{\sigma} \sin(\zeta) \approx 2 \int_0^t \overline{\omega} \theta_k = 2\overline{\beta} \int_0^t y_r' \theta_k$  and (4.9) together with the analytic solutions for  $y_r'$  and  $\theta_k$  give a closed stochastic expression for the group wavenumber. Thus, the wavenumber factor  $\exp(2\overline{\beta} \int_0^t y_r' \theta_k)$  oscillates at frequency  $2\overline{\omega}_r$  and the oscillations modulate the wave amplitude:  $h = \sqrt{E} = \sqrt{\omega_0 N} = \text{cst.} k^{\frac{1}{4}}$ . The modulations are associated with wave-current energy exchanges Boury *et al.* (2023), visible in the colored rays, figures 5, 6 and 7, when the groups enter and exit the jet.

Finally, the conditional ray distribution,  $p(\mathbf{x}, \mathbf{k}|\mathbf{x}_r^0, \mathbf{k}^0, t)$ , the action spectrum mean from (4.10) and the action mean from (4.11) can all be derived. For a system initially localized in  $(0, \frac{L_y}{2})$  with action  $A^0$ , wavenumber  $k^0$  and a  $\sigma_{\delta\theta_k}^0$ -width Gaussian angular spreading, propagating to the right, the action mean reads

$$\mathbb{E}A(x,y,t) = A^0 \delta \left( x - (v_g^0(k^0) - \overline{u}(y))t \right) \mathcal{N} \left( y - \frac{L_y}{2} \middle| \tilde{\sigma}_y^2(t) \right), \tag{5.7}$$

with  $\mathcal{N}\left(\bullet \middle| \tilde{\sigma}_y^2(t)\right)$ , a Gaussian function with variance  $\tilde{\sigma}_y^2(t) = \sigma_y^2(t) + \left(\frac{v_g^0}{\overline{\omega}_r}\sin(\overline{\omega}_r t)\sigma_{\delta\theta_k}^0\right)^2$ .

The action is advected in the horizontal direction, and slowly diffuses along the vertical

6. Conclusion

direction.

Developed to generalize the ray-path concept for waves propagating over an heterogeneous turbulence, a practical stochastic framework is derived. For fast waves, the smallest scales of a turbulent flow decorrelate along the wave propagation. Flows with steeper spectra decorrelate faster, leading to a broader validity range of fast wave approximations. The proposed framework encodes both large-scale refraction and random scattering effects on wave statistical properties. The mean wave-action statistics are directly linked to resolved strain-rate and vorticity, but also to unresolved KE spectral properties. Both Eulerian and Lagrangian views are presented. A convenient calibration method is also proposed for the subgrid parametrization.

Anticipated, random horizontal currents delay wave arrival and augment the initial radiative transport equation with a directional diffusive term. These phenomena are illustrated with numerical simulations, analytical solutions, and quantitative proxies describing weak homogeneous turbulence. Using these proxies, measured delays in ray arrivals, estimated wave energy spectral characteristics and decays, and/or varying directional spread shall then be used to more quantitatively interpreted the upper the turbulent underlying flow properties.

The generalized fast wave approximation does takes into account wavenumber variation and handles strong heterogeneous flows, like localized jets with strong current gradients. As compared to numerical simulations, numerical and theoretical results explain and quantify ray trapping effects by jets, unlike usual fast wave approaches.

428 Among fast wave literature, isotropic diffusion and, hence, wavenumber diffusion may 429 (e.g. Voronovich 1991) or may not (e.g. Bôas & Young 2020) comes into play (see last 430 Appendix for details). Future works could adapt our convenient stochastic calculus framework 431 to the second models family. Besides, further analytical developments could consider finite-432 size wave groups, their dynamics (Jonsson 1990; White & Fornberg 1998) and statistical 433 distributions, or alternatively the Eulerian action dynamics (4.12) with all its multi-point 434 stochastic structure. When achieved, this next theoretical development could provide new 435 means to analyze wave dynamics with subsequent fast simulations of ensembles. Beside 436 comprehension and analysis, our stochastic simulation tools aim at eventually facilitate 437 future ensemble-based data assimilation algorithms (Smit et al. 2021). 438

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- Data availability statement. SCALIAN DS owns a portion of the developed code intellectual property.
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- 447 **Author contributions.** VR developed the theory. VR and EH wrote the code and performed numerical experiments. VR and BC wrote the paper.

## 449 Appendix A. Stochastic forcing covariance

In this appendix, we will compute the conditionnal covariance of the stochastic forcing of our eikonal characteristic equations (4.1), that is:

$$2\mathbf{D} \stackrel{\triangle}{=} \frac{1}{\mathrm{d}t} \mathbb{E}_t \left\{ \begin{pmatrix} \sigma \mathrm{d}B_t \\ \mathrm{d}\boldsymbol{\eta}_t \end{pmatrix} \begin{pmatrix} \sigma \mathrm{d}B_t \\ \mathrm{d}\boldsymbol{\eta}_t \end{pmatrix}^\mathsf{T} \right\} = \begin{bmatrix} \boldsymbol{a} & \boldsymbol{\Sigma}_{\boldsymbol{\eta},\sigma} \\ \boldsymbol{\Sigma}_{\boldsymbol{\eta},\sigma}^\mathsf{T} & \boldsymbol{\Sigma}_{\boldsymbol{\eta}} \end{bmatrix}$$
(A 1)

where,  $d\eta_t = -\nabla(\sigma dB_t)^T k$ , denotes the wave-vector stochastic forcing and,  $\Sigma_{\eta} dt$ , its covariance, and  $\mathbb{E}_t \{ \bullet \} \triangleq \mathbb{E} \{ \bullet | x_r(t), k(t) \}$  stands for the conditional expectation evaluated with given characteristics  $(x_r(t), k(t))$  at the current time t. Note that in the appendix we use Itō notations only.

The subgrid velocity,  $\mathbf{v}' = \sigma \mathrm{d}B_t/\mathrm{d}t$  is constructed in Fourier space with a divergence-free isotropic spatial filter  $\nabla^{\perp}\psi_{\sigma}$  (see (3.10)).

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$$\widehat{\mathbf{v}'}(\mathbf{\kappa},t) = \int d\mathbf{x} \ \mathbf{v}'(\mathbf{x},t)e^{-\mathrm{i}\mathbf{\kappa}\cdot\mathbf{x}} = \widehat{\sigma dB_t}/dt(\mathbf{\kappa},t) = \mathrm{i}\mathbf{\kappa}^{\perp}\widetilde{\psi}_{\sigma}(\kappa)\widehat{dB_t}(\mathbf{\kappa})/dt, \qquad (A2)$$

The computation of the variance tensor **a** is classical and straightforward from the definition

of the inverse Fourier transform and the identity 
$$\mathbb{E}\left\{\widehat{dB_t}(\kappa_1)\overline{dB_t}(\kappa_2)\right\} = (2\pi)^2\delta(\kappa_1 - \kappa_2)dt$$
.

We simply need to split the integral of the stochastic forcing spectrum over the current wavevector  $\kappa = \kappa(\cos\theta_{\kappa}, \sin\theta_{\kappa})$ :

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$$\boldsymbol{a} = \frac{1}{(2\pi)^4 dt} \iint d\boldsymbol{\kappa}_1 d\boldsymbol{\kappa}_1 \, \mathbb{E}_t \left\{ \widehat{\sigma dB_t}(\boldsymbol{\kappa}_1, \boldsymbol{k}) \widehat{\overline{\sigma dB_t}}^{\mathsf{T}}(\boldsymbol{\kappa}_2, \boldsymbol{k}) \right\} e^{\mathrm{i}(\boldsymbol{\kappa}_1 - \boldsymbol{\kappa}_2) \cdot \boldsymbol{x}}, \tag{A 3}$$

$$= \frac{1}{(2\pi)^2} \int d\kappa \, \kappa^2 |\widetilde{\psi}_{\sigma}(\kappa)|^2 \begin{pmatrix} -\sin\theta_{\kappa} \\ \cos\theta_{\kappa} \end{pmatrix} \begin{pmatrix} -\sin\theta_{\kappa} \\ \cos\theta_{\kappa} \end{pmatrix}^{\mathsf{T}}, \tag{A4}$$

$$= \frac{1}{(2\pi)^2} \int_0^\infty \oint_0^{2\pi} d\kappa d\theta_{\kappa} \kappa^3 |\widehat{\psi}_{\sigma}(\kappa)|^2 \begin{pmatrix} \sin^2 \theta_{\kappa} & -\sin \theta_{\kappa} \cos \theta_{\kappa} \\ -\sin \theta_{\kappa} \cos \theta_{\kappa} & \cos^2 \theta_{\kappa} \end{pmatrix}, \quad (A.5)$$

$$= \frac{2}{2\pi} a_0 \oint_0^{2\pi} d\theta_\kappa \begin{pmatrix} \sin^2 \theta_\kappa & -\sin \theta_\kappa \cos \theta_\kappa \\ -\sin \theta_\kappa \cos \theta_\kappa & \cos^2 \theta_\kappa \end{pmatrix}, \tag{A 6}$$

$$= a_0 \mathbb{I}_d. \tag{A7}$$

Now, the Fourier transform of the wave-vector stochastic forcing is

470 
$$d\widehat{\boldsymbol{\eta}}_t = -\overline{\boldsymbol{\nabla}(\sigma dB_t)}^{\mathsf{T}} \boldsymbol{k} = -\mathrm{i} \kappa (\mathrm{i} \kappa^{\perp} \widetilde{\boldsymbol{\psi}}_{\sigma} \widehat{dB_t}) \cdot \boldsymbol{k} = -\kappa (\boldsymbol{k}^{\perp} \cdot \kappa) \widehat{\boldsymbol{\psi}}_{\sigma} \widehat{dB_t}.$$
 (A 8)

Then, applying the crest-oriented rotation matrix,  $M_k = |\tilde{k} \quad \tilde{k}^{\perp}|$ , leads to

$$d\widehat{\mathbf{Z}}_{t} = \mathbf{M}_{k}^{\mathsf{T}} d\widehat{\boldsymbol{\eta}}_{t} = -\begin{pmatrix} \widetilde{\mathbf{k}} \cdot \boldsymbol{\kappa} \\ \widetilde{\mathbf{k}}^{\perp} \cdot \boldsymbol{\kappa} \end{pmatrix} (\mathbf{k}^{\perp} \cdot \boldsymbol{\kappa}) \widetilde{\psi}_{\sigma} d\widehat{\mathbf{B}}_{t} = -\begin{pmatrix} \cos \delta \theta \sin \delta \theta \\ \sin^{2} \delta \theta \end{pmatrix} \kappa^{2} k \ \widehat{\psi}_{\sigma} d\widehat{\mathbf{B}}_{t}, \quad (A 9)$$

with  $\delta\theta = \theta_K - \theta_k$ . From there, we can evaluate the conditional covariance matrix  $\Sigma_Z = \frac{1}{\mathrm{d}t}\mathbb{E}_t\left\{\mathrm{d}\mathbf{Z}_t\mathrm{d}\mathbf{Z}_t^T\right\}$  of  $\mathrm{d}\mathbf{Z}_t$  as before:

475 
$$\Sigma_{Z} = \frac{1}{(2\pi)^{4} dt} \iint d\boldsymbol{\kappa}_{1} d\boldsymbol{\kappa}_{1} \mathbb{E}_{t} \left\{ d\widehat{\boldsymbol{Z}}_{t}(\boldsymbol{\kappa}_{1}, \boldsymbol{k}) \overline{d\widehat{\boldsymbol{Z}}_{t}^{\mathsf{T}}(\boldsymbol{\kappa}_{2}, \boldsymbol{k})} \right\} e^{\mathrm{i}(\boldsymbol{\kappa}_{1} - \boldsymbol{\kappa}_{2}) \cdot \boldsymbol{x}}, \tag{A 10}$$

$$= \frac{1}{(2\pi)^2} \int_0^{\infty} \oint_0^{2\pi} d\kappa d\delta\theta \, \kappa^5 k^2 |\widehat{\psi}_{\sigma}(\kappa)|^2 \begin{pmatrix} \cos^2 \delta\theta \sin^2 \delta\theta & \cos \delta\theta \sin^3 \delta\theta \\ \cos \delta\theta \sin^3 \delta\theta & \sin^4 \delta\theta \end{pmatrix}, (A11)$$

$$= \gamma_0 k^2 \begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix}. \tag{A 12}$$

478 Finally, we come back to the canonical frame to get  $\Sigma_{\eta}$ 

$$\Sigma_{\eta} = \mathbb{E}_{t} \left\{ d \boldsymbol{\eta}_{t} d \boldsymbol{\eta}_{t}^{\mathsf{T}} \right\} = \boldsymbol{M}_{k} \Sigma_{Z} \boldsymbol{M}_{k}^{\mathsf{T}} = \gamma_{0} k^{2} \left[ \tilde{\boldsymbol{k}} \tilde{\boldsymbol{k}}^{\mathsf{T}} + 3 \tilde{\boldsymbol{k}}^{\perp} \left( \tilde{\boldsymbol{k}}^{\perp} \right)^{\mathsf{T}} \right]$$
(A 13)

480 For noises cross-correlations, by isotropy, it is also straightforward to show that

$$\Sigma_{n,\sigma} = 0. \tag{A 14}$$

The stochastic forcings of  $x_r$  and k are hence (conditionally) independent from one another.

#### Appendix B. Single ray dynamics 483

The Itō noise  $\begin{pmatrix} \sigma dB_t \\ d\eta_t \end{pmatrix}$  is white in time and conditionally Gaussian. Its conditional single-484

point distribution is fully determined by its zero mean and its local covariance matrix (given 485

- 486 by equations (A1), (A7), (A13) and (A14)). In particular, we can replace this noise by
- another zero-mean Gaussian vector with the same covariance without changing the single-487

ray dynamics – typically replacing 
$$\sigma dB_t$$
 by  $\sqrt{a_0} \begin{pmatrix} dB_t^{(1)} \\ dB_t^{(2)} \end{pmatrix}$  and  $d\mathbf{Z}_t$  by  $-\sqrt{\gamma_0}k \begin{pmatrix} dB_t^{(3)} \\ \sqrt{3}dB_t^{(4)} \end{pmatrix}$ . It

yields the simplified ray equations (4.3)-(4.4). 489

Then note that from Itō lemma (Oksendal 1998)  $d\tilde{\mathbf{k}} = d \begin{pmatrix} \cos \theta_k \\ \sin \theta_k \end{pmatrix} = \tilde{\mathbf{k}}^{\perp} d\theta_k - \frac{1}{2} \tilde{\mathbf{k}} d < 0$ 490

 $\theta_k, \theta_k >_t$  where  $\langle \bullet, \bullet \rangle_t$  denotes the quadratic covariation. Th 491

492 
$$\mathrm{d}\boldsymbol{k} = \mathrm{d}k\,\tilde{\boldsymbol{k}} + k\mathrm{d}\tilde{\boldsymbol{k}} + \mathrm{d} < k, \,\tilde{\boldsymbol{k}} > = (\mathrm{d}k - \frac{1}{2}k\mathrm{d} < \theta_k, \theta_k >_t)\tilde{\boldsymbol{k}} + (k\mathrm{d}\theta_k + \mathrm{d} < k, \theta_k >_t)\tilde{\boldsymbol{k}}^{\perp} \,(\mathrm{B}\,1)$$

Projecting this equation and  $dk = -\nabla \overline{v}^{\mathsf{T}} k dt + d\eta_t$  on  $\tilde{k}$  and  $\tilde{k}^{\perp}$ , we have 493

$$\begin{cases}
dk = -\tilde{\mathbf{k}} \cdot \nabla \overline{\mathbf{v}}^{\mathsf{T}} \mathbf{k} dt + (dZ_t)_1 + \frac{1}{2} k d < \theta_k, \theta_k >_t \\
k d\theta_k = -\tilde{\mathbf{k}}^{\perp} \cdot \nabla \overline{\mathbf{v}}^{\mathsf{T}} \mathbf{k} dt + (dZ_t)_2 - d < k, \theta_k >_t
\end{cases} , \tag{B 2}$$

495 
$$\begin{cases} dk = -\tilde{\mathbf{k}} \cdot \nabla \overline{\mathbf{v}}^{\mathsf{T}} \mathbf{k} dt + (dZ_{t})_{1} + \frac{1}{2} k^{-1} d < Z_{2}, Z_{2} >_{t} \\ d\theta_{k} = -\tilde{\mathbf{k}}^{\perp} \cdot \nabla \overline{\mathbf{v}}^{\mathsf{T}} \tilde{\mathbf{k}} dt + k^{-1} (dZ_{t})_{2} + \frac{1}{2} k^{-2} d < Z_{1}, Z_{2} >_{t} \end{cases}$$
(B 3)

The treatment of the large-scale terms  $\tilde{k} \cdot \nabla \overline{v}^{\mathsf{T}} \tilde{k}$  and  $\tilde{k}^{\perp} \cdot \nabla \overline{v}^{\mathsf{T}} \tilde{k}$  is classical. Interested 496 readers can refer to Lapeyre et al. (1999) for details. From Ito lemma again,  $d \log k =$ 497  $dk/k - \frac{1}{2}d < k, k >_t/k^2$  leading to the simplified wave-vector dynamics (4.5)-(4.6). 498

## Appendix C. Subgrid flow anisotropy and comparison with other works

Throughout this paper, we have considered an isotropic model for the stochastic subgrid 500 velocity (3.10). The isotropic diffusivity matrix  $\mathbf{a} = a_0 \mathbb{I}_d$  is a good illustration of this. In 501 contrast, many authors (e.g. White & Fornberg 1998; Bôas & Young 2020; Smit & Janssen 502 2019) assume isotropic and homogeneous turbulence and obtain anisotropic stochastic 503 subgrid models for  $\frac{\|\bar{\mathbf{v}}\|}{v_0^0} \to 0$ . In these approaches, the integral over  $\delta\theta$  in diffusivity matrix 504 computations (A 4) and (A 12) involve singular integrations over the direction  $v_g^0 = v_g^0 \tilde{k}$ . It makes appear a Dirac delta function,  $2\pi\delta(\kappa \cdot v_g^0) = \frac{2\pi}{\kappa v_g^0} (\delta(\theta_\kappa - \theta_k - \frac{\pi}{2}) + \delta(\theta_\kappa - \theta_k + \frac{\pi}{2}))$ 505 506 (see Appendix in Bôas & Young 2020). This precision imposes a statistical anisotropy for  $\sigma dB_t$  (oriented along k) and  $d\eta_t$  (oriented along  $k^{\perp}$ ), eventually leading to a covariance 507 508  $\Sigma_Z = \gamma_0 k^2 \begin{vmatrix} 0 & 0 \\ 0 & 16 \end{vmatrix}$  (Eq. (3.17) in Bôas & Young (2020) and Eq. (24) in Smit & Janssen 509

- (2019)), no noise  $dZ_1$ , and no Brownian motion  $B_t^{(3)}$ . Moreover, because of scaling assumption, Bôas & Young (2020) neglect the spatial diffusivity matrix,  $\boldsymbol{a}$ , while Smit 510
- 511
- & Janssen (2019) find  $\mathbf{a} = 4a_0 \left( \mathbb{I}_d + \frac{5}{4} \tilde{\mathbf{k}} \tilde{\mathbf{k}}^{\mathsf{T}} \right)$  (Eq. (22)-(23)). In this anisotropic framework, 512
- the Stratonovich wavevector equation (2.3),  $d\mathbf{k} = -\nabla(\overline{v}dt + \sigma \circ dB_t)^{\mathsf{T}}\mathbf{k}$ , would involve an 513
- 514 additional drift term in Itō notations.

499

Further developing this anisotropic stochastic closure is an interesting avenue. Neverthe-515

less, in the present study, we adopt the isotropic model for  $\sigma dB_t$ , which is much more

517 convenient for multi-ray numerical simulations.

## Appendix D. Jet simulation

Again, currents are simulated at a resolution  $512 \times 512$  on a 1000-km-width squared domain

through the same code. A backward velocity  $v_{\rm Bk}$  forces a leftward jet structure.

521 
$$\partial_t \omega + \boldsymbol{v} \cdot \boldsymbol{\nabla} \omega = S_{\omega} \text{ with } \boldsymbol{v} = \boldsymbol{\nabla}^{\perp} \Delta^{-1} (\omega + \omega_{Bk}).$$
 (D 1)

522  $S_{\omega}$  encompasses the linear drag and the hyperviscosity, and the background vorticity,  $\omega_{\rm Bk}$ ,

is a smooth step function with a wavy interface at  $y = Y_{Bk}(x)$ :

$$\omega_{\rm Bk}(x,y) = \Omega_{\rm Bk} \left( \frac{1}{2} - \operatorname{erf}\left(\frac{y - Y_{\rm Bk}(x)}{L_{\rm w}^{\omega}}\right) \right) \text{ with } Y_{\rm Bk}(x) = L_y \left( \frac{1}{2} + \frac{1}{30} \cos\left(\frac{2\pi}{L_x}x\right) \right) \quad (D \ 2)$$

To better highlight the interplay between ray oscillations and scattering, we consider very-collimated swells, with a spatial extension of  $100\lambda = 25$  km.

very-commated swens, with a spatial extension of  $100\lambda = 23$  km.

Besides, the curvature of the simulated jet can force an additional faster oscillation around

the jet for small enough wavevector angle. Indeed, a wave group traveling exactly rightward would cross an alternation of positive and negative verticity regions with a period  $L_{\perp}/(v^0)$ 

would cross an alternation of positive and negative vorticity regions with a period  $L_x/(v_g^0 -$ 

 $\overline{U}_0$ )  $\approx 1$  day  $< 2\pi/\overline{\omega}_r$ . Here, we set an initial wavevector angle large enough to prevent the additional harmonics.

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