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A GEHRING-HAYMAN INEQUALITY FOR STRONGLY PSEUDOCONVEX DOMAINS

LUKASZ KOSIŃSKI, NIKOLAI NIKOLOV, AND PASCAL J. THOMAS

ABSTRACT. We prove that if D is a strongly pseudoconvex domain with $C^{2,\alpha}$ -smooth boundary, then the length of a geodesic for the Kobayashi-Royden infinitesimal metric between two points is bounded by a constant multiple of the Euclidean distance between the points.

1. INTRODUCTION AND MOTIVATION

In 1962, F.W. Gehring and W.K. Hayman [9] proved a conjecture of G. Piranian: there is an absolute constant C such that for any simply connected domain U strictly included in the complex plane, for any $z_1, z_2 \in U$, if γ_H is the hyperbolic geodesic from z_1 to z_2 , and γ any rectifiable curve from z_1 to z_2 contained in U , then

$$l(\gamma_H) \leq Cl(\gamma),$$

where l denotes Euclidean length. When U is convex, this just means that $l(\gamma_H) \leq C|z - w|$. There are also versions of this result for the diameters of the curves and for other metrics, see for instance the survey [23].

In the several complex variable settings, it is natural to ask similar questions about geodesics for the Kobayashi-Royden metric

$$\kappa_D(z; X) = \inf\{|\alpha| : \exists \varphi \in \mathcal{O}(\Delta, D), \varphi(0) = z, \alpha\varphi'(0) = X\},$$

and it seems realistic to restrict oneself to domains with some regularity. The best bounds known so far were of the form $C|z-w|^{1/m}$ for m -convex domains and strongly pseudoconvex domains, see [20], [19] and [21]. However, in the case of the unit ball, it is easy to see that geodesics, since they lie inside affine complex lines, must have length bounded by $\frac{\pi}{2}|z-w|$, which is much smaller in the critical case when z and w are

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close to each other. The goal of this note is to show that this type of bound still holds in regular enough strongly pseudoconvex domains.

Theorem 1. *Let D be a strongly pseudoconvex domain with $\mathcal{C}^{2,\alpha}$ -smooth boundary. Then there is $C > 0$ such that*

$$|z - w| \leq l(\gamma_{z,w}) \leq C|z - w|$$

for any $z, w \in D$ and any Kobayashi geodesic $\gamma_{z,w}$ joining z and w .

Observe that C here depends on the domain. For this result, it does not matter whether we consider the lengths of all curves or simply the Euclidean distance: since the domain is bounded, we may always assume that $|z - w| \leq c_0$ for some $c_0 > 0$, the inequality being trivial otherwise, and that z, w are close to ∂D , since when z, w are contained in some compact set $K \subset\subset D$, the Kobayashi-Royden and Euclidean metrics are equivalent, and so $l(\gamma_{z,w})$ is comparable to $|z - w|$. And for two points close to each other and to a \mathcal{C}^2 boundary, the lengths of curves connecting the points are comparable to their Euclidean distance.

The optimal class of domains to which this result can apply remains an open question: can we lower the regularity requirement? Can we allow finite type or even mere pseudoconvexity? Is that property even required? For really irregular domains, do we have a bound involving the lengths of connecting curves rather than the Euclidean distance? Can we have a universal constant if the bound involves the lengths of connecting curves? Of course, geodesics for the Kobayashi-Royden metric do not always exist, and the question would have to be rephrased using the existing notions of quasi-geodesics.

2. A CONSTRUCTION OF FRIDMAN-MA AND LEMPERT'S SCALING

Within this section, we shall outline the *global scaling* process which provides much more precise estimates than standard methods used so far (e.g. the ones involving squeezing functions).

In his seminal paper [15], Lempert showed that in a strongly convex domain D with \mathcal{C}^6 -boundaries any two points lie on a complex geodesic disc. To show the existence of a geodesic he used the scaling method: for a point p in the topological boundary ∂D of a strongly pseudoconvex domain D he found a neighborhood U and a biholomorphic map F on U such that $F(\partial D \cap U)$ was close in \mathcal{C}^6 -topology to a big part of the Euclidean sphere. The main weakness of the above construction is that it is not defined globally on D .

A similar construction was independently applied by Fridman and Ma [8] to the problem of exhaustion of smooth pseudoconvex domains at points of global strict convexity.

We will construct a global scaling on strongly pseudoconvex domains. *Scaling* here means that we use a precise automorphism of the Euclidean ball to scale while *global* means that scaling maps are defined on the whole \overline{D} , so that images of geodesics under scaling maps are still geodesics, while an explicit form for automorphisms is essential in carrying out precise estimates.

We shall try to keep the notation from both papers: \mathbb{B} denotes the unit Euclidean ball and B denotes the ball of radius 1 centered at $(-1, 0)$, that is $B = \mathbb{B} - (1, 0)$.

Fridman-Ma construction. Let D be a strongly pseudoconvex domain with $\mathcal{C}^{2,\alpha}$ -smooth boundary, $\alpha \in [0, 1]$. Note that for $\alpha = 0$ this covers the \mathcal{C}^2 case. Thanks to [7], that any boundary point $p \in \partial D$ can be exposed, that is to say, there is a biholomorphism Φ on a neighborhood of \overline{D} such that for $D' = \Phi(D)$, $p' = \Phi(p)$, p' is a point of *global strong convexity*, that is, there is a ball U such that $D \subset U$ and $p' \in \partial D \cap \partial U$. This will be the starting point for the Fridman-Ma construction [8], which we shall recall, but in addition we will keep track of the dependence of the transformations on the starting point p .

Let us start with the following definition.

Definition 2 (See [8, Definition 3.1]). *Let N, k be natural numbers, $N \geq 4$, $k \leq 2(N - 4)$. A \mathcal{C}^2 smooth domain $D \subset \mathbb{C}^n$, $0 \in \partial D$ is of type $C(N, k)$ if there is a defining function ρ of D near 0 of the form*

$$\rho(z) = 2 \operatorname{Re} z_1 + \operatorname{Re} \sum_{i,j=2}^n a_{ij} z_i z_j + d |z_1|^2 + N |z'|^2 + o(|z|^{2+\alpha}),$$

where $z' = (z_2, \dots, z_n)$, the numbers N, d and a_{ij} satisfy $d > 1$ and

$$(1) \quad \operatorname{Re} \sum_{i,j=2}^n a_{ij} z_i z_j + (N - 4 - k/2) |z'|^2 \geq 0 \quad \text{for } z' \in \mathbb{C}^{n-1}.$$

Remark 3. Note that (1) is equivalent to $|\sum_{i,j=2}^n a_{ij} z_i z_j| \leq (N - 4 - k/2) |z'|^2$. In particular, if $k = 2(N - 4)$, then $a_{ij} = 0$.

Since p is a point of global strong convexity, the same is true of nearby points. The construction is outlined in five steps below.

Step 1. The translation

$$i) \quad z \mapsto T_p(z) := z - p,$$

the scaling (locally independent of p) and the unitary transformation

$$ii) \quad z \mapsto A(p)z,$$

which can be chosen so that if we write $\Phi_1 := A(p) \circ T_p$, $\Phi_1(D) \subset B$ and it admits a defining function ρ with expansion at 0 of the form

$$\begin{aligned} \rho(z) = & 2 \operatorname{Re} z_1 + \operatorname{Re} \sum_{i,j=1}^n a_{ij}(p) z_i z_j + \\ & \operatorname{Re} \sum_{j=1}^n c_j(p) z_1 \bar{z}_j + \sum_{j=2}^n N_j(p) |z_j|^2 + o(|z|^{2+(1-\epsilon)\alpha}), \forall \epsilon > 0, \end{aligned}$$

where we also have used $A(p)$ to diagonalize the possible hermitian terms $\sum_{i,j=2}^n c_{i,j} z_i \bar{z}_j$. The unitary matrix depends on the first and second-order derivatives of the defining function of D at p , so a_{ij} , c_j and N_j are functions of class \mathcal{C}^α of p .

Step 2. This is precisely [8, Lemma 3.2]. Namely, there is an integer $N \geq 4$ such that D is biholomorphic to a domain of the type $C(N, 0)$.

This is achieved by Fridman and Ma using an affine map

$$iii) \quad \Phi_2(z_1, z_2, \dots, z_n) = \left(z_1, z_2 + \frac{c_2(p)}{2N_2(p)} z_1, \dots, z_n + \frac{c_n(p)}{2N_n(p)} z_1 \right)$$

the coefficients of which are clearly of class \mathcal{C}^α , as are their inverses; rescaling maps Φ_3

$$iv) \quad z_j \mapsto t_j(p) z_j,$$

chosen so that $\Phi_3 \circ \Phi_2 \circ \Phi_1(D) \subset B$; the t_j are of class \mathcal{C}^α with respect to p . Then, as in [8, (3.7), p. 391] $\Phi_3 \circ \Phi_2 \circ \Phi_1(D)$ admits a defining function of the form

$$(2) \quad \begin{aligned} \rho(z) = & 2 \operatorname{Re} z_1 + 2 \operatorname{Re} \sum_{j=1}^n b_j(p) z_1 z_j + \\ & \operatorname{Re} \sum_{i,j=1}^n a_{ij}(p) z_i z_j + d |z_1|^2 + M |z'|^2 + o(|z|^{2+(1-\epsilon)\alpha}), \forall \epsilon > 0. \end{aligned}$$

We then apply an automorphism $\Phi_4 = \Phi_4^\epsilon$ of B of the form

$$v) \quad \Phi_4^\epsilon : z \mapsto \left(\frac{\epsilon z_1}{2-\epsilon+(1-\epsilon)z_1}, \frac{\sqrt{\epsilon(2-\epsilon)}}{2-\epsilon+(1-\epsilon)z_1} z' \right).$$

where ϵ is such that $\epsilon \sum_j |b_j(p)|$ is smaller than a given positive number λ chosen as in [8, Lemma 3.1, p. 390] ($\lambda = 1/8$ will do). In particular, since the b_j are continuous w.r.t to p , ϵ can be chosen locally independently of p . The resulting domain $\Phi_4 \circ \dots \circ \Phi_1(D)$ admits a defining function of the form (2) with new coefficients b'_j satisfying the hypotheses of [8, Lemma 3.1] and so applying a map $\Phi_5(z) = (z_1 + \sum_{j=1}^n b'_j z_1 z_j, z')$, then a contraction $\Phi_6(z) = \frac{M}{N} z$ with N an integer, $N > 8M$ we obtain that $\Phi_6 \circ \dots \circ \Phi_1(D)$ is of type $C(N, 0)$ [8, end of proof of Lemma 3.2, p. 392]. Again, it is straightforward to see that N can be chosen locally constant.

Step 3. The goal is to show that any domain of type $C(N, k)$ is biholomorphic to $C(N, k + 1)$. This is relevant only when $N \geq 5$ and $k \leq 2(N - 4) - 1$. Then the statement is precisely [8, Lemma 3.4]. The transformations used to achieve this statement are:

$$vi) \quad z \mapsto (z_1 + \sum_{i,j=2}^n b_{ij}(p)z_i z_j, z'),$$

where $b_{ij}(p) = \frac{1}{4(N-4-k/2)}a_{ij}(p)$,

vii) an automorphism Φ_4^ϵ of the ball B ,

where ϵ is chosen independently of p , and

viii) $z \mapsto (\frac{14}{15}z_1, \sqrt{\frac{14}{15}}z')$. Call Φ_7 the composition of those maps.

Step 4. Repeating Step 3 exactly $2(N-4)$ times, with maps $\Phi_7, \dots, \Phi_{2N-2}$, we get a domain whose defining function near 0 is of the form

$$(3) \quad \rho(z) = 2 \operatorname{Re} z_1 + d(p)|z_1|^2 + N|z'|^2 + o(|z|^{2+(1-\epsilon)\alpha}), \forall \epsilon > 0.$$

Step 5. Applying a map

$$ix) \quad \Phi_{2N-1}(z) = (d(p)z_1, (d(p)N)^{1/2}z'),$$

we can assume that $d(p) = N = 1$. Also, the coefficients are of class C^α . Thus $\Phi_{2N-1} \circ \dots \circ \Phi_1(D)$ which admits a defining function of the form

$$(4) \quad \rho(z) = 2 \operatorname{Re} z_1 + |z|^2 + o(|z|^{2+(1-\epsilon)\alpha}), \forall \epsilon > 0, \quad \text{as } z \rightarrow 0,$$

and that is contained in the ball rB of radius r centered at $(-r, 0)$ for some $r \geq 1$.

Definition 4. *If D is a C^2 domain and $p \in \partial D$ a point of strong pseudoconvexity, we denote $F_p := \Phi_{2N-1} \circ \dots \circ \Phi_1$ the map which results from the Fridman-Ma construction.*

Remark 5. It follows from the above construction that we can locally write $F_q(z) = \tilde{F}(z, \alpha_1(q), \dots, \alpha_M(q))$, where \tilde{F} is a holomorphic mapping and α_j are of class C^α (here M denotes the number of C^α smooth functions that appear in the construction of F_q). The same remains true for $F_q^{-1}(z)$.

In particular, the Jacobian of F_q with respect to z as well as that of its inverse F_q^{-1} vary locally C^α -continuously. In particular, F_q locally does not change the Euclidean distance between points.

For later purposes, we need to know that we can choose an appropriate p to make the Fridman-Ma construction.

Lemma 6. *For any $z \in D$ that is sufficiently close to $p_0 \in \partial D$, there exists $q \in \partial D$, close to p_0 , so that $F_q(z) \in (-1, 0) \times \{0\}^{n-1}$.*

Proof. Applying one Fridman-Ma transformation we can assume that $p_0 = 0$ and a defining ρ function of D near p_0 is of the form $\rho(z) = 2 \operatorname{Re} z_1 + |z|^2 + o(|z|^{2+(1-\epsilon)\alpha})$, as $z \rightarrow 0$.

As in Remark 5 write $F_q(z) = \tilde{F}(z, \alpha_1(q), \dots, \alpha_M(q))$, where α_j are \mathcal{C}^α -continuous, $\alpha_j(0) = 0$, $j = 1, \dots, M$.

Let us consider the map

$$\varphi : (-1, \delta) \times \partial D \ni (t, q) \mapsto F_q^{-1}(t, 0) \in \mathbb{C}^n,$$

which is well defined for $\delta > 0$ sufficiently small. In particular,

$$\varphi(t, q) = G(t, \alpha_1(q), \dots, \alpha_M(q))$$

for $q \in \partial D$ close 0, where G is holomorphic near 0 in \mathbb{C}^{1+M} . Moreover,

$$\varphi(t, 0) = (rt + o(t^2), 0) \text{ for some } r > 0, \text{ and } \varphi(0, q) = q$$

(the first equality above follows from formulas (iii) – (ix)). Consequently, we can write

$$(5) \quad \varphi(t, q) = (rt, 0) + q + t\Gamma(t, \alpha_1(q), \dots, \alpha_M(q)),$$

for Γ holomorphic near 0, $\Gamma(0) = 0$.

We need to show that there is $\epsilon > 0$ and a neighborhood U of p in ∂D such the range $\varphi((-\epsilon, \epsilon) \times U)$ contains a neighborhood of 0. This is already claimed in the proof of [6, Theorem 4.1]. The authors deduced this fact by claiming that φ is a local diffeomorphism near $t = 0$ and $q = 0$. This, however, is not the case, if $\alpha < 1$, as the mapping φ is only \mathcal{C}^α -smooth with respect to the variable q .

Nevertheless, a topological argument proves the above assertion also in the case when $\alpha = 0$, i.e. when ∂D is \mathcal{C}^2 smooth (in particular [6, Theorem 4.1] is salvaged in its full generality). Let us present how it can be done.

Let us write ∂D near 0 as $\operatorname{Re} z_1 = \tilde{\rho}(\operatorname{Re} z_2, z')$, where $\tilde{\rho}$ is $\mathcal{C}^{2,\alpha}$ smooth. For simplicity of notation, we shall identify \mathbb{C}^n with \mathbb{R}^{2n} writing $(z_1, \dots, z_n) = (s, x) = (s, x_2, \dots, x_{2n})$. Let V be a neighborhood of 0 in \mathbb{R}^{2n-1} and put $\psi(s, x) = (s + \tilde{\rho}(x), x)$ if $x \in V$ so that ψ is a \mathcal{C}^2 -smooth map that sends $\{0\} \times V$ diffeomorphically to U .

Consider $\Phi : (-\epsilon, \epsilon) \times V \rightarrow \mathbb{R}^{2n}$ given by $\Phi(t, x) = \psi^{-1}(\varphi(t, \psi(0, x)))$. Our aim is to show that $\Phi((-\epsilon, \epsilon) \times V)$ is a neighborhood of 0. In other words, we want to show (s, y_1, \dots, y_{2n}) is in the image of Φ , i.e. that there is (t, x) such that

$$(6) \quad \Phi(t, x) = (s, y)$$

providing that s and y are small. Write $\Phi = (\Phi_1, \dots, \Phi_{2n})$.

It follows from (5) that

$$\Phi(t, x) = (rt, x) + t\gamma(t, x),$$

where γ is continuous and $\gamma(0, 0) = 0$.

For a fixed x we are looking at the equation $\Phi_1(t, x) = s$. It follows from the implicit function theorem (Φ_1 depends smoothly on t as well

as on continuous functions α_j that we treat as coefficients) that this equation has a solution $t = t(s, x)$ which is of the form

$$(7) \quad t = s/r + s\delta(s, x)$$

where δ is continuous, $\delta(0) = 0$.

Plugging $t = s/r + s\delta(s, x)$ to $(\Phi_2, \dots, \Phi_n)(t, x)$ we get the mapping of the form

$$x \mapsto x + s\beta(s, x),$$

where again β is continuous and $\beta(0) = 0$. Fix a closed ball in V with 0 being its center and denote it by K . Take s sufficiently small so that $s\beta(s, x)$ is in $\frac{1}{2}K$ for any $x \in K$. Then, by the Brouwer fixed point theorem, $\frac{1}{2}K$ is contained in the image of $x \mapsto x + s\beta(s, x)$ (this is because for any $y \in \frac{1}{2}K$ the mapping $x \mapsto y - s\beta(s, x)$ sends K to K , so must have a fixed point). Thus, if s is small and $y \in \frac{1}{2}K$, equation (6) has a solution x ; then t is given by (7). \square

Lempert's scaling method.

We will use automorphisms of the ball \mathbb{B}

$$(8) \quad A_t(z) = \left(m_t(z_1), \sqrt{1-t^2} \frac{z'}{1+tz_1} \right), \text{ where } m_t(z_1) = \frac{z_1 + t}{1 + tz_1}.$$

Given a domain of the form $F_p(D)$, with ∂D of class $\mathcal{C}^{2,\alpha}$ and F_p as in Definition 4, we consider $D_0 = T_{e_1}(D)$ where $e_1 = (1, 0) \in \mathbb{C} \times \mathbb{C}^{n-1}$ and T_{e_1} is the translation $z \mapsto z + e_1$. Then D_0 admits a defining function of the form $\rho_0(z) = -1 + |z|^2 + o(|z|^{2+(1-\epsilon)\alpha})$, $\forall \epsilon > 0$, as $z \rightarrow e_1$, and that is contained in the ball B' of radius $1 + s'$ centered at $(-s', 0)$ for some $s' \geq 0$. Note that A_t^{-1} is well defined on B' and $A_t^{-1}(z) \rightarrow (-1, 0)$ uniformly on compact subsets of $B' \setminus \{e_1\}$ as $t \rightarrow 1$. Define

$$(9) \quad D_t = A_t^{-1}(D_0) \quad \text{and} \quad \rho_t(z) = \frac{|1 + tz_1|^2}{1 - t^2} \rho_0(A_t(z)), \quad t \in (0, 1).$$

Clearly $D_t = \{\rho_t < 0\}$ and $\rho_t(z)$ converges to $-1 + |z|^2$ locally uniformly in $\{\operatorname{Re} z_1 > -\alpha\}$ for any $\alpha < 1$ as $t \rightarrow 1$.

Summing up, for any $\beta > -1$:

- A1) $D_t \cap \{\operatorname{Re} z_1 > \beta\}$ converges to $\mathbb{B} \cap \{\operatorname{Re} z_1 > \beta\}$ in $\mathcal{C}^{2,\alpha}$ -topology (here and in the sequel this means convergence of defining functions),
- A2) D_t converges to the ball in the Hausdorff topology.

We now must restrict ourselves to the case when ∂D is of class $\mathcal{C}^{2,\alpha}$ with $\alpha > 0$. The reason is that we must use Lempert's work on complex geodesics [15, 17, 18] (see also a discussion in [10, Remark B]) and the arguments about the dependence and regularity of complex geodesics

fail if we merely assume \mathcal{C}^2 -smoothness [17, remark after the Main Theorem, p. 561].

In [17] and [18] Lempert considered the class S^k , where $k > 1$ is non-integer; we refer the reader to [17, p. 561] for a precise definition. If $D \in S^{m+\alpha}$, $m \in \mathbb{N}$, $0 < \alpha < 1$, then ∂D is of class $\mathcal{C}^{m,\alpha}$; if ∂D is of class $\mathcal{C}^{m,\alpha}$, then $D \in S^{m-1+\alpha}$. Thus it is proven in [17, Corollary 3.3] that any complex geodesic in a $\mathcal{C}^{2,\alpha}$ -smoothly bounded strictly convex domain D is in $\mathcal{C}^{1,\alpha}(\overline{\mathbb{D}})$. Also, the $\mathcal{C}^{1/2}(\overline{\mathbb{D}})$ norm of a complex geodesic f is uniformly bounded when $f(0)$ is within a compact subset of K of D , with bounds depending only on the diameter of D and normal curvatures of ∂D and on K [15, Proposition 13], so there is local uniformity with respect to the domain as well, in the sense of $\mathcal{C}^{2,\alpha}$ convergence of defining functions.

Using those a priori estimates in the \mathcal{C}^6 case and approximation (see [17, p. 562–563]), Lempert showed in [18, Proposition 3] that the bound on $\mathcal{C}^{1,\alpha}(\overline{\mathbb{D}})$ norm is in fact locally uniform. This implies the following.

Proposition 7. *Let D_n be a sequence of strictly convex domains such that their defining functions converge in the $\mathcal{C}^{2,\alpha}$ sense to the defining function of a strictly convex domain D . Let K be a compact subset of D and f_n a sequence of complex geodesics in D_n such that $f_n(0) \in K$. Then $\mathcal{C}^{1,\alpha}(\overline{\mathbb{D}})$ -norms of f_n are uniformly bounded, for n big enough, and a subsequence of (f_n) converges in the $\mathcal{C}^1(\overline{\mathbb{D}})$ topology to a complex geodesic we denote by f .*

Proof. It follows from the hypothesis that the $\mathcal{C}^\alpha(\overline{\mathbb{D}})$ norms of f'_n are uniformly bounded as well. Applying the Arzelà-Ascoli theorem to f'_n we can assume that a subsequence converges uniformly on $\overline{\mathbb{D}}$ to an analytic disc, say g . Also, a subsequence of (f_n) converges on $\overline{\mathbb{D}}$ to an analytic disc that we shall denote by f . Clearly $f' = g$ and a subsequence f_n converges to f in $\mathcal{C}^1(\overline{\mathbb{D}})$ topology. Note that f is a (unique) complex geodesic in D , because it verifies the extremality conditions from [15]. \square

Actually, something can still be said about complex geodesics in D in the case when $\alpha = 0$, that is when a strongly convex domain D has \mathcal{C}^2 -smooth boundary. Chirka, Coupet and Sukhov established in [5, Corollary 1.5] the $\mathcal{C}^{1-\epsilon}$ continuity up to the boundary for a holomorphic map f from \mathbb{D} with boundary values in a totally real \mathcal{C}^1 manifold M . The manifold to be considered here is, in the terminology of [17], $\widehat{\partial D} := \{(z, T_z^{\mathbb{C}} \partial D), z \in \partial D\} \subset \mathbb{C}^n \times \mathbb{P}^{n-1}$, while if we have a geodesic ϕ , the map has to be $(\phi, \dot{\phi})$, see [17, proof of Lemma 3.1]. Also, their result implies that one can control $\mathcal{C}^{1-\epsilon}$ norms of geodesic also under \mathcal{C}^2 -perturbations of ∂D (see the discussion following [5, Corollary 1.5]).

3. PROOF OF THEOREM 1

We shall divide the proof into two cases, according to whether the direction generated by z and w is “tangential” or “normal”. In order to give this a precise meaning, first recall that it is enough to prove our theorem for z, w in a neighborhood U of ∂D , which we will take small enough so that for any $z \in U \cap D$, there exists a unique point $\pi(z) \in \partial D$ such that $|z - \pi(z)| = \min\{|z - \zeta|, \zeta \in \mathbb{C}^n \setminus D\}$. We denote by n_z the outer unit normal to ∂D at $\pi(z)$, and write, for any vector v , $v_z := \langle v, n_z \rangle n_z$ where $\langle \cdot, \cdot \rangle$ stands for the usual Hermitian inner product.

We first deal with the (almost) “tangential” case.

Lemma 8. *Let D be a strongly pseudoconvex domain with $\mathcal{C}^{2,\alpha}$ boundary. There exists $\epsilon_0 > 0$ such that if $0 < \epsilon < \epsilon_0$, and if $z, w \in D$ satisfy $\delta(z) < \epsilon$, $|z - w| < \epsilon$ and $|(z - w)_z| < \epsilon|z - w|$, then z and w lie on a stationary map (thus on a complex geodesic) whose diameter is $o(1)$ as $\epsilon \rightarrow 0$. Moreover, $|(x - y)_x|/|x - y| = o(1)$ for any points x, y of this complex geodesic.*

Part of this result was proven in [3] under a \mathcal{C}^3 smoothness assumption (see also [11]). Below we shall show how to deduce it in the $\mathcal{C}^{2,\alpha}$ setting directly from Lempert’s work.

Proof. First make the additional assumption that D is convex. Since it is strongly pseudoconvex (bounded), it enjoys the visibility property ([2], or use [1] and the fact that the Gromov boundary of a Gromov hyperbolic space is always visible): given two distinct points $p, q \in \partial D$, and sequences $p_n \rightarrow p$, $q_n \rightarrow q$, there exists a compact set $K \subset D'$ such that for n large enough, the real geodesic from p_n to q_n intersects K . It is easy to see that this can be made uniform: as soon as $|p - q| \geq \delta > 0$, there is a $K_\delta \subset\subset D'$ such that geodesics from p_n to q_n eventually intersect K_δ . In particular, if the diameter of the complex geodesic through z and w is big enough, and z and w are close to the boundary, the complex geodesic needs to intersect a fixed compactum K , and thus meets the boundary transversely (uniformly with respect to the point in K , by [15, Proposition 14]). Therefore, for points on such a complex geodesic z, w which are close enough to each other and to the boundary, $|(z - w)_z| \geq C|z - w|$, where $C > 0$ is uniform. This contradicts the assumptions with ϵ_0 small enough, we would have a contradiction, so the assertion about the diameter is proved.

For general strongly pseudoconvex domains one can derive the assertion by exposing points as in [7]: using a biholomorphism on a neighborhood of \overline{D} , we can assume that $D \subset \mathbb{B}$, $p \in \partial D \cap \partial \mathbb{B}$. Furthermore by the regularity assumptions ∂D remains strongly convex in a neighborhood of p , so taking ϵ_0 small enough we may assume $z_n, w_n, q \in U$, a neighborhood of p such that $D \cap U$ is smooth strongly

convex and $U \cap \partial D$ is close to $U \cap \partial \mathbb{B}$. Consider the complex geodesic $f : \mathbb{D} \rightarrow D \cap U$ obtained for the convex domain $D \cap U$ by the argument above. This is a stationary map in the sense of Lempert [17, Section 3, p. 562, points 1–3], meaning in particular that there exists a $\mathcal{C}^{1/2}$ positive function $p(\zeta)$, $\zeta \in \partial \mathbb{D}$, such that the function $\tilde{f}(\zeta) := \zeta p(\zeta) \overline{n_{f(\zeta)}}$ extends to a holomorphic function on \mathbb{D} . Therefore it is also stationary as a map $f : \mathbb{D} \rightarrow D$.

Making z, w even closer to p as needed, we may assume that $\overline{f(\mathbb{D})} \cap \partial(D \cap U)$ is contained in ∂D and close enough to p so that for any $z \in D$, $\operatorname{Re}\langle z - f(\zeta), n_{f(\zeta)} \rangle < 0$. A winding number argument then shows that the equation $\langle z - f(\zeta), \overline{\tilde{f}(\zeta)} \rangle = 0$ admits a unique solution $F(z)$ in \mathbb{D} , which has to be holomorphic, and this uniqueness shows that $F(f(\zeta)) = \zeta$ for any $\zeta \in \mathbb{D}$ (in other words we have a left-inverse, see [14]) and therefore the map f is indeed a complex geodesic for z, w with respect to D .

The last statement in the Lemma follows from [12, Theorem 3]: if x, y are in the range of a complex geodesic φ , then $|(x - y)_x| \lesssim |x - y| \operatorname{diam}(\varphi)^1$. \square

Corollary 9. *Let D be a domain in \mathbb{C}^n and $p \in \partial D$ a strongly pseudoconvex point. If $z, w \in D$ are close to p and $|(z - w)_z|/|z - w|$ is sufficiently small, then there is a unique real geodesic for z, w and it is induced by a complex one.*

Proof. Recall there is a neighborhood U of p so that there exists a biholomorphism on a neighborhood of $\overline{D \cap U}$ making D convex.

Let φ be any complex geodesic passing through z, w . By Lemma 8, the range of φ is close to the boundary, its diameter is also small, so we may assume $\varphi(\mathbb{D}) \subset U$. So after biholomorphism we can reduce ourselves to stationary discs in a strictly convex domain D' .

Inside the complex geodesic φ there can only be one real geodesic, that we shall denote by γ , $\gamma(0) = z$, $\gamma(t_1) = w$. Suppose that there is another real geodesic between z and w , say η . Then for some t_0 the point $\eta(t_0)$ must lie outside the range of φ and we can choose it so that $|(\eta(0) - \eta(t))_{\eta(0)}|/|\eta(0) - \eta(t)|$ is small for all $t \in [0, 1]$. As in Lemma 8 take a complex geodesic ψ passing through $\eta(0)$ and $\eta(t_0)$; it has to be close to η when t_0 is chosen close to $\sup\{t : \eta(t) \notin \varphi(\mathbb{D})\}$. Consider the one-parameter family of maps from the unit disc to D' given by $(1 - \theta)\varphi + \theta\psi$, then they are extremal for z, w and for θ close to 0, [14, Lemma 3.2] shows that they must be proper into D' , a contradiction. \square

3.1. Theorem 1 – tangential case. Let $z_n, w_n \in D$ be such that $z_n, w_n \rightarrow p \in \partial D$, and $|(z_n - w_n)_{z_n}|/|z_n - w_n| \rightarrow 0$. Let φ_{z_n, w_n} be the

¹As usual, $f \lesssim g$ means that $f \leq Cg$ for some uniform constant $C > 0$ (depending only on D); $f \simeq g$ is understood analogously

unique complex geodesic that passes through z_n and w_n . Let γ_{z_n, w_n} be the unique real geodesic for z_n, w_n , induced by φ_{z_n, w_n} .

We shall follow the notation from Section 2. For each n , take a point $p_n \in \overline{\varphi_{z_n, w_n}(\mathbb{D})}$ so that $p_n \rightarrow p$ and then apply the transformation F_{p_n} . Let $D_n := F_{p_n}(D)$. So we are reduced to the case where $p = (1, 0) \in \partial D_n$ lies in the range of the closed analytic disc $\overline{\varphi_{z_n, w_n}(\mathbb{D})}$ and D_n near the point p is given by the inequality

$$(10) \quad \{|z|^2 + o(|z - p|^{2+\alpha}) < 1\}.$$

We now drop the subscript from the notation and write D for D_n and z, w for z_n, w_n . For $t \in (0, 1)$, $D_t := A_t^{-1}(D)$ as in (9).

Then for t well chosen, close to 1, $\psi_{z, w} := A_t^{-1} \circ \varphi_{z, w}$ is a complex geodesic in D_t that lies entirely in $\{\operatorname{Re} z_1 \geq 0\}$, with its boundary intersecting $\{\operatorname{Re} z_1 = 0\}$; it is close in \mathcal{C}^1 topology on $\overline{\mathbb{D}}$ to a geodesic in \mathbb{B}_n , after a possible reparametrization. Its range intersects a fixed compact subset K of \mathbb{B} , independent of n , and contains $(1, 0)$ in its closure.

Complex geodesics in \mathbb{B}_n are intersections of \mathbb{B}_n with complex affine lines. Therefore, a simple argument shows that any complex geodesic $\psi = (\psi_1, \tilde{\psi})$ in \mathbb{B}_n contained in $\{\operatorname{Re} z_1 \geq 0\}$ that passes through $(1, 0)$, and such that $\psi(0) \in K$, satisfies the following uniform estimates:

$$\left| \frac{\tilde{\psi}(\mu)}{1 + t\psi_1(\mu)} - \frac{\tilde{\psi}(\lambda)}{1 + t\psi_1(\lambda)} \right| \simeq |\mu - \lambda| \simeq |\tilde{\psi}(\mu) - \tilde{\psi}(\lambda)|.$$

Trivially,

$$|\psi_1(\mu) - \psi_1(\lambda)| \lesssim |\lambda - \mu|,$$

again uniformly. By \mathcal{C}^1 convergence argument, all these uniform estimates remain true for the geodesics $\psi_{z, w}$ (after proper reparametrizations). In particular, if $x = (x_1, x')$, $y = (y_1, y')$ are two points lying in the range of any $\psi_{z, w}$, then

$$(11) \quad \left| \frac{y'}{1 + ty_1} - \frac{x'}{1 + tx_1} \right| \simeq |y' - x'| \simeq |y - x|.$$

Let x, y be in the range of $\eta_{z, w} := A_t^{-1}(\gamma_{z, w})$. Clearly,

$$A_t(x) - A_t(y) = \left(\frac{(1 - t^2)(y_1 - x_1)}{(1 + tx_1)(1 + ty_1)}, (1 - t^2)^{1/2} \left(\frac{y'}{1 + ty_1} - \frac{x'}{1 + tx_1} \right) \right).$$

In particular, by the estimates from (11):

$$(12) \quad |A_t(y) - A_t(x)| \simeq (1 - t^2)^{1/2} |y - x|,$$

where \simeq is uniform.

As already mentioned, $\eta_{z, w}$ are real geodesics, induced by $\psi_{z, w}$. The geodesics $\psi_{z, w}$ intersect a fixed compact set K . By Proposition 7 and its proof, they are uniformly $\mathcal{C}^{1+\alpha}$ -smooth on the closed disc in the sense that their $\mathcal{C}^{1+\alpha}$ -norms (so \mathcal{C}^1 as well) are uniformly bounded,

which implies the assertion of Theorem 1 for $\eta_{z,w}$. From this and (12) one can deduce the assertion for $\gamma_{z,w} = A_t(\eta_{z,w})$.

3.2. Theorem 1 – non-tangential case: preparatory results. A visibility lemma for the class of “Goldilocks” domains (which includes finite type domains) was given by Bharali-Zimmer [2]. The following visibility lemma is essentially due to Bracci-Fornaess-Wold [3], but we need a slightly more general form:

Lemma 10. *Let $\alpha > -1$ and D_n be a family of domains $D_n \subset \mathbb{B}$ such that $D_n \cap \{\operatorname{Re} z_1 \geq \alpha\}$ converges to $\mathbb{B} \cap \{\operatorname{Re} z_1 \geq \alpha\}$ in \mathcal{C}^2 topology. Let $z_n, w_n \in D_n$ converge to p and q respectively, where $p, q \in \partial\mathbb{B} \cap \{\operatorname{Re} z_1 > \alpha\}$, $p \neq q$. Then there is $K \subset \subset \mathbb{B}$ such that any real geodesic σ_n in D_n for z_n, w_n intersects K .*

If instead of a sequence of domains D_n a fixed one is considered, the result was proven in [3] (see also [2]). A glimpse at their reasoning ensures us that estimates achieved there depend just on the normal curvature of the domain.

Proof. We can reparametrize $\sigma_n : [a_n, b_n] \rightarrow D_n$ by arc-length so that $\delta_n(\sigma_n(0)) \leq \delta_n(\sigma_n(t))$, where $\delta_n(x) = \operatorname{dist}(x, \partial D_n)$. Since D_n are uniformly bounded, $|\sigma_n'(t)| \leq L$ for some uniform constant L .

On the other hand, for n big enough the normal curvature of ∂D_n restricted to $\{\operatorname{Re} z_1 \geq \alpha + \epsilon\}$, where ϵ is small enough, is close to the one of \mathbb{B} . In particular, all D_n satisfy an exterior ball condition with a uniform constant. From this we deduce the existence of $C > 0$ such that

$$(13) \quad k_{D_n}(x, v) \geq C \frac{\|v\|}{\sqrt{\delta_n(x)}}$$

for $x \in D_n \cap \{\operatorname{Re} z_1 \geq \alpha + \epsilon\}$.

The same curvature-type argument shows that ∂D_n restricted to $\{\operatorname{Re} z_1 \geq \alpha + \epsilon\}$ satisfies a uniform interior ball condition. Therefore, there is a uniform $k \in \mathbb{N}$ so that any two points in D_n can be connected with a chain of k balls of a fixed radius. From this, we gain an estimate

$$K_{D_n}(z, w) \leq C + \frac{1}{2} \log \frac{1}{\delta_n(z)} + \frac{1}{2} \log \frac{1}{\delta_n(w)},$$

with a uniform $C > 0$.

Now it is enough to notice that a curve that remains too close to the boundary at all times has length bigger than the above estimate for the Kobayashi distance because of (13), or to repeat an argument from [3, Proof of Proposition 2.2] or [2, Section 5]. \square

Lemma 11. *Suppose that D_{t_n} converges to \mathbb{B} as in A1) and A2) when $t_n \rightarrow 1$. Let $z_n, w_n \in D_{t_n}$ be such that $z_n \rightarrow (1, 0)$ and $w_n \rightarrow (-1, 0)$. Let φ_n be a real geodesic for k_{D_n} joining z_n and w_n , parametrized so that*

for some $\alpha_n, \beta_n > 0$, $\varphi_n(-\alpha_n) = w_n$, $\varphi_n(\beta_n) = z_n$, and $\operatorname{Re} \varphi_n(0)_1 = 0$. Then inside any compact subset $K \subset \mathbb{B}^N$, the geodesics φ_n converge in the \mathcal{C}^1 topology to a geodesic line in \mathbb{B} between $(-1, 0)$ and $(1, 0)$, and for any $\epsilon, \delta_0 > 0$, there exists $n(\epsilon, K, \delta_0)$ such that for any $z', w' \in K \cap \varphi_n$ with $|z' - w'| \geq \delta_0$, then for $n \geq n(\epsilon, K, \delta_0)$, $l(\varphi_n|_{[z', w']}) \leq (1 + \epsilon)|z' - w'|$.

The same holds if we change the assumption on z_n to the following: $z_n \in (0, 1) \times \{0\}^{N-1}$ (possibly replacing the geodesic line by a ray).

Proof. Take $\tilde{\beta} < \beta < 1$ close to 1. Take $s_n := \max\{t : \operatorname{Re} \varphi_n(t)_1 = -\beta\}$, $\tilde{s}_n := \min\{t : \operatorname{Re} \varphi_n(t)_1 = -\tilde{\beta}\}$, $\tilde{t}_n := \max\{t : \operatorname{Re} \varphi_n(t)_1 = \tilde{\beta}\}$, $t_n := \min\{t : \operatorname{Re} \varphi_n(t)_1 = \beta\}$, and corresponding points $x_n = \varphi_n(s_n)$, $\tilde{x}_n = \varphi_n(\tilde{s}_n)$, $\tilde{y}_n = \varphi_n(\tilde{t}_n)$ and $y_n = \varphi_n(t_n)$. It follows from the visibility lemmas applied to x_n, \tilde{x}_n and to y_n, \tilde{y}_n that there are compact sets $K_1 \subset \{-\beta < \operatorname{Re} z_1 < -\tilde{\beta}\}$ and $K_2 \subset \{\tilde{\beta} < \operatorname{Re} z_1 < \beta\}$ that intersect the ranges of the geodesics φ_n .

Since the φ_n form an equicontinuous family, we get that a subsequence of φ_n converges to a real geodesic φ in the ball that intersects K_1 and K_2 and passes through 0. Letting $\tilde{\beta}$ tend to 1, we get the convergence on all compact sets. The statement about lengths comes from the fact that the real geodesic for the ball between z' and w' is close to a line.

The second assertion can be deduced in a similar way. \square

3.3. Proof by contradiction: Claims. Suppose that the estimate in Theorem 1 fails. Then there are sequences of points $z_n, w_n \in D$, joined by a geodesic $\gamma_n = \gamma_{z_n, w_n}$ such that

$$(14) \quad l(\gamma_n) \geq a_n |z_n - w_n|, \text{ where } a_n \rightarrow \infty.$$

Our goal is to obtain Claim 1, and then to prove Claim 2 which contradicts the previous one.

Since the ratio of the Euclidean and Kobayashi-Royden infinitesimal metrics are bounded above and below on any compactum, it is enough to consider the case at least one of the points z_n, w_n escapes from any compact set, so passing to a subsequence and exchanging z_n and w_n if needed, we may assume $z_n \rightarrow p \in \partial D$.

Then we may reduce ourselves to the case where w_n converges to the same boundary point. Indeed, if the distance between z_n and w_n did not converge to 0, then by (14) the lengths of the curves γ_n would go to infinity and switching z_n and w_n , if necessary, we could pick points $w'_n \in \gamma_n$, such that $|w'_n - z_n| \rightarrow 0$ while $l(\gamma_n|_{[w'_n, z_n]})$ remains big.

Claim 0. It is enough to focus on the case when $|(\gamma_n(t) - \gamma_n(s))_{\gamma_n(t)}| \geq C|\gamma_n(t) - \gamma_n(s)|$, for all s, t , for some uniform constant C , where normal length is taken with respect to $p \in \partial D$.

Proof of the claim. Actually, if the opposite inequality were true for some t, s , where C is small enough, we would deduce that γ_n is contained in a complex geodesic, according to Corollary 9. From Lemma 8 we would get that this is actually covered by the tangential case. \square

It follows from Claim 0 that it suffices to measure the length of γ_n projected to the normal direction. Denote this *normal* length by l_N .

Claim 1. There exist a sequence of domains D_n , points $\zeta_n, \nu_n \in D_n$ and real geodesics η_n in D_n joining them such that $\zeta_n = \eta_n(t_n)$, $\nu_n = \eta_n(-s_n)$, and

- (1) For any $\beta > -1$, the domains D_n converge to \mathbb{B} in $\mathcal{C}^{2,\alpha}$ topology when restricted to $\{\operatorname{Re} z_1 \geq \beta\}$;
- (2) $(1, 0) \in \partial D_n$ and the defining functions of D_n near $(1, 0)$ are of the form (10);
- (3) $\zeta_n \in (0, 1) \times \{0\}^{N-1}$, $\zeta_n \rightarrow (1, 0)$, and $\nu_n \rightarrow (-1, 0)$, and setting $\xi_n = \eta_n(0)$, $\operatorname{Re}(\xi_n)_1 = 0$, $\xi_n \rightarrow (0, x)$ as $n \rightarrow \infty$;
- (4) $l_N(\eta_n|_{[0, t_n]}) \rightarrow \infty$, as $n \rightarrow \infty$.

We shall prove Claim 1 in several steps.

The following simple observation will be used several times, so let us state it as a separate result. Recall that m_t is defined in (8).

Lemma 12. 1) Let $\delta : I \rightarrow \mathbb{D}$ be a curve. Let $t \in (0, 1)$ be such that $\tilde{\delta} := m_t^{-1} \circ \delta$ is contained in $\{\operatorname{Re} \lambda \geq \beta\}$, $\beta > -1$. Then

$$|\delta(s_1) - \delta(s_2)| \simeq (1 - t^2) |\tilde{\delta}(s_1) - \tilde{\delta}(s_2)|, \quad s_1, s_2 \in I.$$

Consequently,

$$l(\delta) \simeq (1 - t^2) l(\tilde{\delta}).$$

The estimates above depend only on β .

2) Suppose additionally

$$(15) \quad \left| \tilde{\delta}(s_2) - \tilde{\delta}(s_1) \right| \leq l(\tilde{\delta}|_{[s_1, s_2]}) \leq (1 + \epsilon) \operatorname{Re}(\tilde{\delta}(s_2) - \tilde{\delta}(s_1)),$$

where $s_1, s_2 \in I$. Assume also that $|\operatorname{Im} \tilde{\delta}(s)| < \epsilon$, $s \in I$, where $\epsilon > 0$ is small enough. Then

$$l(\delta|_{[s_1, s_2]}) \leq C_\beta (1 + \epsilon) \operatorname{Re}(\delta(s_2) - \delta(s_1)).$$

Proof. If $\operatorname{Re} x_1, \operatorname{Re} y_1 \geq -\beta$, then $|1 + tx_1|$ and $|1 + ty_1|$ are between $1 - \beta$ and 2, so by direct computations $|m_t(x_1) - m_t(y_1)| \simeq (1 - t^2) |y_1 - x_1|$.

The second part is technical, as well. The first part and assumption (15) imply that $l(\delta|_{[s_1, s_2]}) \leq c_\beta (1 + \epsilon) (1 - t^2) \operatorname{Re}(\tilde{\delta}(s_2) - \tilde{\delta}(s_1))$.

To get the assertion, compute

$$\operatorname{Re}(\delta(s_2) - \delta(s_1)) = (1 - t^2) \operatorname{Re} \left(\frac{\tilde{\delta}(s_2) - \tilde{\delta}(s_1)}{(1 + t\tilde{\delta}(s_1))(1 + t\tilde{\delta}(s_2))} \right)$$

Since $|\operatorname{Im} \tilde{\delta}(s)| < \epsilon$, the argument of the denominator is bounded by $C\epsilon$, and by (15), so is the argument of the numerator. So we get

$$\operatorname{Re}(\delta(s_2) - \delta(s_1)) \geq (1 - t^2)(1 - C\epsilon) \operatorname{Re}(\tilde{\delta}(s_2) - \tilde{\delta}(s_1)),$$

which finishes the proof. \square

Let us come back to the proof of Claim 1. Let $p_n \in \partial D$ minimize the distance from z_n to ∂D . Clearly $p_n \rightarrow p$. Using a Fridman-Ma transformation, we can assume that $p_n = (1, 0)$ and that ∂D is near $(1, 0)$ of the form (10). Let A_t be given by (8).

Choose t_n such that $A_{t_n}^{-1}(\gamma_n) \subset \{\operatorname{Re} z_1 \geq 0\}$ and $A_{t_n}^{-1}(\gamma_n) \cap \{\operatorname{Re} z_1 = 0\} \neq \emptyset$.

Step 1. $t_n \rightarrow 1$ as $n \rightarrow \infty$.

Proof. This comes from the fact that a Gromov hyperbolic metric space X (with boundary) does not have geodesic loops, i.e. isometric maps γ from \mathbb{R} such that $\lim_{t \rightarrow \pm\infty} \gamma(t) = p \in \partial_G X$, where $\partial_G X$ is the Gromov boundary of X and the convergence is in the sense defined for that boundary. Recall that a bounded strongly pseudoconvex domain in \mathbb{C}^n endowed with the Kobayashi distance is Gromov hyperbolic and its Gromov boundary coincides with the Euclidean boundary [1].

Suppose that some subsequence, again denoted by t_n , remains bounded away from 1. We may restrict attention to a neighborhood of p and thus assume it is a point of global strong convexity. The geodesics (γ_n) pass through z_n and points on the surface $A_{t_n}(\{\operatorname{Re} z_1 = 0\})$, which are far away from each other. Thus the visibility applies and allows us to choose $K \subset\subset \mathbb{B}$ such that every γ_n intersects it.

Choose a sequence $s_n \rightarrow 1$ slowly enough so that $A_{s_n}^{-1}(z_n)$ and $A_{s_n}^{-1}(w_n)$ still tend to p , so the starting and ending points of $A_{s_n}^{-1}(\gamma_n)$ are both close to $(1, 0)$. But $A_{s_n}^{-1}(K)$ converges to the point $(-1, 0)$. Whence $A_{s_n}^{-1}(\gamma_n)$ is convergent to a nontrivial geodesic line in \mathbb{B} with both extremities tending to the same boundary point, a contradiction with the non existence of geodesic loops. \square

Let $\tilde{z}_n = A_{t_n}^{-1}(z_n)$, $\tilde{w}_n = A_{t_n}^{-1}(w_n)$, and $\tilde{\gamma}_n := A_{t_n}^{-1}(\gamma_n)$.

Step 2. The following uniform estimates hold:

$$l_N(\gamma_n) \simeq (1 - t_n^2) l_N(\tilde{\gamma}_n),$$

and

$$|z_n - w_n|_{z_n} \simeq (1 - t_n^2) |\tilde{z}_n - \tilde{w}_n|$$

as $n \rightarrow \infty$. Consequently,

$$(16) \quad l(\tilde{\gamma}_n)/|\tilde{z}_n - \tilde{w}_n| \simeq l(\gamma_n)/|z_n - w_n| \geq a_n.$$

Proof. This is a direct consequence of Lemma 12. \square

Step 3. There is no $K \subset\subset \mathbb{B}$ such that both \tilde{z}_n and \tilde{w}_n lie in K for any $n \in \mathbb{N}$ large enough.

Proof. If there was, there would be a constant $C_K > 1$ such that $C_K^{-1}k_{D_n}(z; v) \leq \|v\| \leq C_K k_{D_n}(z; v)$ for $z \in K$, and therefore $C'_K > 1$ such that $(C'_K)^{-1}|\tilde{z}_n - \tilde{w}_n| \leq l(\tilde{\gamma}_n) \leq C'_K|\tilde{z}_n - \tilde{w}_n|$, which contradicts (16). \square

Step 4. $\liminf_{n \rightarrow \infty} |\tilde{z}_n - \tilde{w}_n| > 0$.

Proof. If this statement were false, then (possibly passing to a subsequence) \tilde{z}_n, \tilde{w}_n would converge to $(1, 0)$, according to Step 3 and the fact that $\tilde{z}_n \in (0, 1) \times \{0\}^{N-1}$. Since the geodesics $\tilde{\gamma}_n$ touch $\{\operatorname{Re} z_1 = 0\}$ (which is far from $(1, 0)$), the argument from Step 1 provides us with a contradiction. \square

Step 5. $l_N(\tilde{\gamma}_n) \rightarrow \infty$ as $n \rightarrow \infty$.

Proof. A direct consequence of Steps 2 and 4. \square

End of proof of Claim 1. From Step 4 and Lemma 10 we deduce that $\tilde{\gamma}_n$ intersects a fixed compact subset K_0 of \mathbb{B} . For each n , choose $x_n \in K_0 \cap \tilde{\gamma}_n$. Step 2 ensures that the lengths of curves from x_n to \tilde{z}_n or from x_n to \tilde{w}_n converge to infinity. If the first possibility holds, then by the arguments from Step 3 \tilde{z}_n goes to the boundary, and we put $\zeta'_n = \tilde{z}_n$ and $\nu'_n = x_n$.

If the second one holds, we apply Fridman-Ma construction with respect to points $q_n \in \partial D_n$ from Lemma 6. It follows from the Fridman-Ma construction that it preserves the fact that lengths go to infinity or not. Then define ζ'_n to be (the new) \tilde{w}_n , and ν'_n to be (the new) x_n .

Now we need to redefine ζ'_n and ν'_n a bit so that ν_n escapes to $(-1, 0)$. It will be straightforward: the ν'_n remain within a fixed compact set that will be pushed towards $(-1, 0)$ under appropriate automorphisms of the ball.

We set $\eta_n := A_{s_n}^{-1}(\tilde{\gamma}_n)$, $\zeta_n := A_{s_n}^{-1}(\zeta'_n)$, and $\nu_n := A_{s_n}^{-1}(\nu'_n)$ where $(s_n)_n \subset (0, 1)$ is to be chosen increasing to 1, so that ν_n tends to $(-1, 0)$. Now let ξ_n be a point on $\eta_n \cap \{\operatorname{Re} z_1 = 0\}$. We can pick $(s_n)_n$ converging to 1 slowly enough so that the lengths of the curves η_n from ξ_n to ζ_n still tend to infinity.

The assertion on normal lengths is clear (compare Claim 0 and Step 2). \square

Claim 2. Let D_n, η_n be as in Claim 1 and satisfy properties (1), (2), and (3). Then

$$(17) \quad \frac{l_N(\eta_n|_{[0, t_n]})}{|\eta_n(0) - \eta_n(t_n)|_{\eta_n(0)}} = O(1),$$

as $n \rightarrow \infty$.

Proof of Claim 2. Let $A^{-k} := A_{1/2}^{-1} \circ \dots \circ A_{1/2}^{-1}$ and $m^{-k} := m_{1/2}^{-1} \circ \dots \circ m_{1/2}^{-1}$, where the automorphism $A_{1/2}$ and Möbius map are defined in (8).

First note that composing with A^{-k} makes domains D_n closer to \mathbb{B} when $k \rightarrow \infty$. For the simplicity of notation write $\delta = \eta_n^1$ (the first complex coordinate of η_n).

Fix $\epsilon > 0$. Since $\zeta_n \in (0, 1) \times \{0\}^{N-1}$, we have $m^{-k}((\zeta_n)_1) > 0$ for $k \leq k(n)$, and since $m^{-k}(\nu_n)$ is closer to $(-1, 0)$ than ν_n for $k \geq 0$, it follows from the second assertion of Lemma 11 applied to $m^{-k}(\eta_n)$ that if n is big enough, then $|\operatorname{Im}(m^{-k}(\delta(s)))| < \epsilon$ for s and $k \geq 0$ such that $\operatorname{Re}(m^{-k}(\delta(s))) = 0$. Fix $-1 < \beta_1 < \beta_2 < 0$ so that $m^{-1}(i[-\epsilon, \epsilon]) \subset \{\beta_1 < \operatorname{Re} z_1 < \beta_2\}$.

By the Denjoy-Wolff theorem $m^{-k}((\zeta_n)_1) \rightarrow -1$ as $k \rightarrow \infty$. Therefore we can pick a finite number of points $0 = t_0 < s_1 < \dots < s_k < t_n \leq s_{k+1}$ that satisfy the following equalities $\operatorname{Re} m^{-1}(\delta(s_1)) = 0$, $\operatorname{Re} m^{-2}(\delta(s_2)) = 0, \dots, \operatorname{Re} m^{-(k+1)}(\delta(s_{k+1})) = 0$.

It follows from our construction that $\beta_1 < \operatorname{Re}(m^{-(j+1)}(\delta(s_j))) < \beta_2$ while $\operatorname{Re}(m^{-(j+1)}(s_{j+1})) = 0$. by Lemma 11, we have a bound on the imaginary part of $m^{-(j+1)} \circ \delta$ on $[s_j, s_{j+1}]$. So (15) is satisfied, and Lemma 12 applied to $\tilde{\delta}|_{[s_1, s_2]} := m^{-(j+1)} \circ \delta|_{[s_j, s_{j+1}]}$ and $m_t^{-1} := m^{-(j+1)}$ provides us with the estimate

$$l(\delta|_{[s_j, s_{j+1}]}) \leq C(1 + \epsilon) \operatorname{Re}(\delta(s_{j+1}) - \delta(s_j)),$$

where the constant C is uniform. From this, we trivially get the assertion. \square

Proof of Theorem 1. Claims 1 and 2 contradict each other. \square

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