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# REPRESENTATIONS OF KNOT GROUPS INTO SL( $n, \mathbb{C})$ 

MICHAEL HEUSENER AND LEILA BEN ABDELGHANI


#### Abstract

We study the local structure of the representation variety of a knot group into $\mathrm{SL}(n, \mathbb{C})$ at certain diagonal representations. In particular we determine the tangent cone of the representation variety at these diagonal representations, and show that the latter can be deformed into irreducible representations. Furthermore, we use Luna's slice theorem to analyze the local structure of the character variety. 2020 MSC: 57K31; 57M05; 20C99 Keywords: knot group ; variety of representations ; variety of characters.


## 1. Introduction

The aim of this paper is to analyze the local structure of the varieties of representations and of characters of a knot group into the Lie group $\operatorname{SL}(n, \mathbb{C}), n \geq 2$, in the neighborhood of certain diagonal representations. It is a well known fact that if $\Gamma$ is a finitely generated group and $G$ is a linear algebraic group then the set $R(\Gamma, G)$ of representations $\Gamma \rightarrow G$ has the natural structure of an affine algebraic scheme (see [25]). A first approximation to the local structure of the representation variety at a given representation $\rho$ is given by its Zariski tangent space. Two finer approximations are the quadratic and the tangent cones (see works of W. Goldman and J. Millson [14, 15]).

Given a finitely generated group $\Gamma$, we denote by $R_{n}(\Gamma):=R(\Gamma, \operatorname{SL}(n, \mathbb{C}))$ the $\mathrm{SL}(n, \mathbb{C})$-representation variety of $\Gamma$. The group $\mathrm{SL}(n, \mathbb{C})$ acts on $R_{n}(\Gamma)$ by conjugation, and the algebraic quotient of this action is the variety of characters which will be denoted by $X_{n}(\Gamma):=R_{n}(\Gamma) / / \operatorname{SL}(n, \mathbb{C})$.

In this article, we focus on fundamental groups of exteriors of knots in homology spheres, and determine explicitly the quadratic and tangent cones of the representation variety at certain diagonal representations. For the fundamental group $\Gamma$ of the exterior of a knot $K$ in a homology sphere, we obtain a canonical surjection $h: \Gamma \rightarrow \mathbb{Z} \cong \Gamma / \Gamma^{\prime}$. The representation space $R_{n}(\mathbb{Z})$ is isomorphic to $\operatorname{SL}(n, \mathbb{C})$, and the surjection $h$ induces a closed immersion $R_{n}(\mathbb{Z}) \hookrightarrow R_{n}(\Gamma)$. In fact, $R_{n}(\mathbb{Z}) \subset R_{n}(\Gamma)$ forms an $\left(n^{2}-1\right)$ dimensional algebraic component of $R_{n}(\Gamma)$. A particular representation $\rho_{D} \in R_{n}(\Gamma)$ is given by a regular diagonal matrix $D=D\left(\lambda_{1}, \ldots, \lambda_{n}\right) \in \operatorname{SL}(n, \mathbb{C})$ i.e. all the diagonal elements are pairwise different. More precisely, we let $\rho_{D}: \Gamma \rightarrow \operatorname{SL}(n, \mathbb{C})$ denote the diagonal representation which factors through the abelianization $\Gamma / \Gamma^{\prime}$, and which is given by $\rho_{D}(\gamma)=D^{h(\gamma)}$ (see Section 2 for details). If none of the quotients $\lambda_{i} / \lambda_{j}$ is a root of the Alexander polynomial $\Delta_{K}$, then $\rho_{D}$ is a smooth point of $R_{n}(\mathbb{Z})$, and there exists a neighborhood of $\rho_{D}$ which consists only of representations with abelian images. On the other hand, if all quotients $\alpha_{i}=\lambda_{i} / \lambda_{i+1}, i=1, \ldots, n-1$, are simple roots of the Alexander polynomial $\Delta_{K}$ and if $\Delta_{K}\left(\lambda_{i} / \lambda_{j}\right) \neq 0$ for all $|i-j| \geq 2$, then there exists a representation $\rho_{D}^{(n)}$ into the solvable group of upper triangular matrices. The representation $\rho_{D}^{(n)} \in R_{n}(\Gamma)$ is reducible and non-semisimple. Its existence was motivated by a result of G. Burde [9] and G. de Rham [10]. The orbit of the representation $\rho_{D}^{(n)}$
under the action of conjugation of $\operatorname{SL}(n, \mathbb{C})$ is not closed, but is of maximal dimension and the closure of its orbit contains the diagonal representation $\rho_{D}$.

We obtain our main result which generalizes [22, Cor. 1.3], and [20, Thm. 1.2].
Theorem 1.1. Let $K$ be a knot in a three-dimensional integer homology sphere, and let $D=D\left(\lambda_{1}, \ldots, \lambda_{n}\right) \in \operatorname{SL}(n, \mathbb{C})$ be a regular diagonal matrix. If all quotients $\alpha_{i}=\lambda_{i} / \lambda_{i+1}$, $i=1, \ldots, n-1$, are simple roots of the Alexander polynomial $\Delta_{K}$ and if $\Delta_{K}\left(\lambda_{i} / \lambda_{j}\right) \neq 0$ for all $|i-j| \geq 2$, then there exists a unique algebraic component $R_{D}^{(n)}$ of $R_{n}(\Gamma)$ which passes through $\rho_{D}$ and which contains irreducible representations.

Moreover, $\operatorname{dim} R_{D}^{(n)}=\left(n^{2}+n-2\right)$, and $\rho_{D} \in R_{D}^{(n)}$ is a smooth point. The components $R_{n}(\mathbb{Z})$ and $R_{D}^{(n)}$ intersect transversally at the orbit of $\rho_{D}$.

Due to a result of A. Weil [33], the Zariski tangent space at a representation $\rho \in R_{n}(\Gamma)$ is contained in the space of crossed morphisms or 1 -cocycles $Z^{1}(\Gamma ; \operatorname{Ad} \rho)$. We call a cocycle $U \in Z^{1}(\Gamma ; \operatorname{Ad} \rho)$ integrable if there exists an analytic path $\rho_{t}$ in $R_{n}(\Gamma)$ such that $\rho_{0}=\rho$, and which is tangent to $U$ i.e. for all $\gamma \in \Gamma$ we have:

$$
U(\gamma)=\left.\frac{d \rho_{t}(\gamma)}{d t}\right|_{t=0} \rho(\gamma)^{-1}
$$

By work of W. Goldman [14], the first obstruction to integrability of the cocycle $U$ is given by the second cohomology class represented by its cup product $[U \smile U]$. We prove that for the diagonal representation $\rho_{D}$ and under the hypothesis of Theorem 1.1 this obstruction is sufficient:
Theorem 1.2. Under the hypothesis of Theorem 1.1, a tangent vector $U \in Z^{1}\left(\Gamma ; \operatorname{Ad} \rho_{D}\right)$ is integrable if and only if its cup product $[U \smile U]$ represents the trivial cohomology class in $H^{2}\left(\Gamma ; \operatorname{Ad} \rho_{D}\right)$.

Moreover, under the hypothesis of Theorem [1.1, we will show (see Section (4) that the tangent cone $T C_{\rho_{D}}\left(R_{n}(\Gamma)\right)$ at $\rho_{D}$ is the union of $2^{n-1}$ affine subspaces. It follows that for $n>2$ the representation $\rho_{D}$ is contained in at least $n$ and in at most $2^{n-1}$ components (see Remark 4.14). The component $R_{n}(\mathbb{Z})$ is the unique component of dimension $\left(n^{2}-1\right)$, and $R_{D}^{(n)}$ is the unique component of dimension $\left(n^{2}+n-2\right)$. The component $R_{n}(\mathbb{Z})$ contains only abelian representations and $R_{D}^{(n)}$ contains irreducible ones. All the other components contain non-abelian, reducible representations and their dimension ranges between $n^{2}$ and $n^{2}+n-3$.

Furthermore, we analyse in this paper (see Section 5) the local structure of the character variety $X_{n}(\Gamma)$ at the character $\chi_{D}$ of $\rho_{D}$. Let $t: R_{n}(\Gamma) \rightarrow X_{n}(\Gamma)$ be the canonical projection and denote by $X_{n}(\mathbb{Z}):=t\left(R_{n}(\mathbb{Z})\right)$ and $X_{D}^{(n)}:=t\left(R_{D}^{(n)}\right)$ the quotients of the components $R_{n}(\mathbb{Z})$ and $R_{D}^{(n)}$ respectively. In fact $t: R_{n}(\mathbb{Z}) \rightarrow X_{n}(\mathbb{Z}) \cong \mathbb{C}^{n-1}$ maps the matrix $A \in \operatorname{SL}(n, \mathbb{C})$ onto the coefficients of the characteristic polynomial of $A$ (see [11, Example 1.2]).

As the set $R_{n}^{i r r}(\Gamma)$ of irreducible representations in $R_{n}(\Gamma)$ is Zariski open and invariant by conjugation, its image $X_{n}^{i r r}(\Gamma)=t\left(R^{i r r}(\Gamma)\right)$ is Zariki open in $X_{n}(\Gamma)$. Their Zariski closures in $R_{n}(\Gamma)$ and $X_{n}(\Gamma)$ will be denoted by $\overline{R_{n}^{i r r}(\Gamma)}$ and $\overline{X_{n}^{i r r}(\Gamma)}$ respectively.
Theorem 1.3. Under the hypothesis of Theorem 1.1 we obtain:
(1) The character $\chi_{D}=t\left(\rho_{D}\right)$ is a smooth point of $\overline{X_{n}^{i r r}(\Gamma)}$.
(2) The character $\chi_{D}$ is a smooth point of each of the two $(n-1)$-dimensional components $X_{n}(\mathbb{Z})$ and $X_{D}^{(n)}$.
(3) The intersection of the two above components at $\chi_{D}$ is trivial:

$$
T_{\chi_{D}}^{Z a r} X_{n}(\mathbb{Z}) \cap T_{\chi_{D}}^{Z a r} X_{D}^{(n)}=\{0\} .
$$

(4) Let ad: $\mathfrak{s l}(n, \mathbb{C}) \rightarrow T_{\rho_{D}^{(n)}}^{Z a r} R_{n}(\Gamma)$ and $d t: T_{\rho_{D}^{(n)}}^{Z a r} R_{n}(\Gamma) \rightarrow T_{\chi D}^{Z a r} X_{n}(\Gamma)$ be the tangent morphisms induced by the conjugation action of $\mathrm{SL}(n, \mathbb{C})$ on $\rho_{D}^{(n)}$ and by the canonical projection $t: R_{n}(\Gamma) \rightarrow X_{n}(\Gamma)$. Then we have the exact sequence:

$$
\begin{aligned}
& 0 \rightarrow \mathfrak{s l}(n, \mathbb{C}) \xrightarrow{a d} T_{\rho_{D}^{(n)}}^{Z a r} R_{n}(\Gamma) \xrightarrow{d t} T_{\chi D}^{Z a r} \overline{X_{n}^{i r r}(\Gamma)} \rightarrow 0, \\
& \text { and } H^{1}\left(\Gamma, \operatorname{Ad} \rho_{D}^{(n)}\right) \cong T_{\chi_{D}}^{Z a a} \overline{X_{n}^{i r r}(\Gamma)} .
\end{aligned}
$$

Plan of the article. In Section 2 we recall some results that we will need in our study, and we introduce the necessary notations. The experienced reader can skip this section and use it as a reference. In Section 3 we construct the non-semisimple representation $\rho_{D}^{(n)}$, and we show that it is a smooth point of $R_{n}(\Gamma)$ contained in a unique component $R_{D}^{(n)}$ of dimension $n^{2}+n-2$. Furthermore, we prove that the component $R_{D}^{(n)}$ contains irreducible representations. In Section 4 we determine the quadratic cone of the diagonal representation $\rho_{D}$ and prove that it coincide with the tangent cone. Finally, in Section 5 we use our results to analyze the local structure of the character variety.

## 2. Notations and background results

For the convenience of the reader, we state in this section the definitions and results that will be used in the sequel. More precisely, subsection 2.1 is devoted to collect results and definitions from group cohomology. In subsection 2.2 we review some general facts about affine algebraic schemes, Zariski tangent space, quadratic and tangent cones. In subsection 2.4, we focus on the representation schemes and varieties. Finally, in Section 2.5 we recall some facts about the Alexander module, as well as certain cohomological results.
2.1. Group cohomology. The general reference for group cohomology is K. Brown's book [8, Chap. III]. Let $A$ be a $\Gamma$-module. We denote by $C^{*}(\Gamma ; A)$ the cochain complex and by $\delta: C^{n}(\Gamma ; A) \rightarrow C^{n+1}(\Gamma ; A)$ the coboundary operator. The coboundaries (respectively cocycles, cohomology) of $\Gamma$ with coefficients in $A$ are denoted by $B^{*}(\Gamma ; A)$ (respectively $Z^{*}(\Gamma ; A), H^{*}(\Gamma ; A)$. In what follows 1 -cocycles and 1 -coboundaries will be also called derivations and principal derivations respectively.

A short exact sequence:

$$
0 \rightarrow A_{1} \xrightarrow{i} A_{2} \xrightarrow{p} A_{3} \rightarrow 0
$$

of $\Gamma$-modules gives rise to a short exact sequence of cochain complexes:

$$
0 \rightarrow C^{*}\left(\Gamma ; A_{1}\right) \xrightarrow{i^{*}} C^{*}\left(\Gamma ; A_{2}\right) \xrightarrow{p^{*}} C^{*}\left(\Gamma ; A_{3}\right) \rightarrow 0 .
$$

We will make use of the corresponding long exact cohomology sequence (see [8, III. Proposition 6.1]):

$$
0 \rightarrow H^{0}\left(\Gamma ; A_{1}\right) \longrightarrow H^{0}\left(\Gamma ; A_{2}\right) \longrightarrow H^{0}\left(\Gamma ; A_{3}\right) \xrightarrow{\beta^{0}} H^{1}\left(\Gamma ; A_{1}\right) \longrightarrow \cdots
$$

Recall that the Bockstein homomorphism $\beta^{n}: H^{n}\left(\Gamma ; A_{3}\right) \rightarrow H^{n+1}\left(\Gamma ; A_{1}\right)$ is determined by the snake lemma: if $z \in Z^{n}\left(\Gamma ; A_{3}\right)$ is a cocycle and if $\tilde{z} \in\left(p^{*}\right)^{-1}(z) \subset C^{n}\left(\Gamma ; A_{2}\right)$ is any lift of $z$ then $\delta_{2}(\tilde{z}) \in \operatorname{Im}\left(i^{*}\right)$ where $\delta_{2}$ denotes the coboundary operator of $C^{*}\left(\Gamma ; A_{2}\right)$. It follows that any cochain $z^{\prime} \in C^{n+1}\left(\Gamma ; A_{1}\right)$ such that $i^{*}\left(z^{\prime}\right)=\delta_{2}(\tilde{z})$ is a cocycle and
that its cohomology class does only depend on the cohomology class represented by $z$. The cocycle $z^{\prime}$ represents the image of the cohomology class represented by $z$ under $\beta^{n}$.

By abuse of notation and if no confusion can arise, we will sometimes identify a cocycle with its cohomology class and will write $\beta^{n}(z)$ for a cocycle $z \in Z^{n}\left(\Gamma ; A_{3}\right)$ even if the map $\beta^{n}$ is only well defined on cohomology classes. This will simplify the notations.
Cup products. Let $A_{1}, A_{2}$ and $A_{3}$ be $\Gamma$-modules. The cup product of two cochains $u_{1} \in C^{p}\left(\Gamma ; A_{1}\right)$ and $u_{2} \in C^{q}\left(\Gamma ; A_{2}\right)$ is the cochain $u_{1} \smile u_{2} \in C^{p+q}\left(\Gamma ; A_{1} \otimes A_{2}\right)$ defined by:

$$
u_{1} \smile u_{2}\left(\gamma_{1}, \ldots, \gamma_{p+q}\right):=u_{1}\left(\gamma_{1}, \ldots, \gamma_{p}\right) \otimes \gamma_{1} \cdots \gamma_{p} \cdot u_{2}\left(\gamma_{p+1}, \ldots, \gamma_{p+q}\right) .
$$

Here $A_{1} \otimes A_{2}$ is a $\Gamma$-module via the diagonal action.
The cup-product is compatible with the boundary operator in the following sense:

$$
\delta\left(u_{1} \smile u_{2}\right)=\delta\left(u_{1}\right) \smile u_{2}+(-1)^{p} u_{1} \smile \delta\left(u_{2}\right) .
$$

When combined with any $\Gamma$-invariant bilinear map $A_{1} \otimes A_{2} \rightarrow A_{3}$, this gives a cup product:

$$
\begin{equation*}
\smile^{b}: C^{1}\left(\Gamma ; A_{1}\right) \times C^{1}\left(\Gamma ; A_{2}\right) \rightarrow C^{2}\left(\Gamma ; A_{3}\right) \tag{1}
\end{equation*}
$$

In this paper, we will mainly make use of two bilinear forms: the multiplication of complex numbers and the Lie bracket when $A=\mathfrak{g}$ is a Lie algebra. We will denote, respectively, $\smile \smile$. and $[\cdot \smile$.$] the corresponding cup products.$

Let $b: A_{1} \otimes A_{2} \rightarrow A_{3}$ be bilinear and let $z_{i} \in Z^{1}\left(\Gamma ; A_{i}\right), i=1,2$, be cocycles. We define $f: \Gamma \rightarrow A_{3}$ by $f(\gamma):=b\left(z_{1}(\gamma) \otimes z_{2}(\gamma)\right)$. A direct calculation gives: $d f\left(\gamma_{1}, \gamma_{2}\right)+$ $b\left(z_{1}\left(\gamma_{1}\right) \otimes \gamma_{1} \cdot z_{2}\left(\gamma_{2}\right)\right)+b\left(\gamma_{1} \cdot z_{1}\left(\gamma_{2}\right) \otimes z_{2}\left(\gamma_{1}\right)\right)=0$. This shows that:

$$
\begin{equation*}
d f+z_{1} \smile^{b} z_{2}+z_{2} \smile^{b \circ \tau} z_{1}=0 \tag{2}
\end{equation*}
$$

where $\tau: A_{1} \otimes A_{2} \rightarrow A_{2} \otimes A_{1}$ is the twist operator.
2.2. Affine algebraic schemes. This section can be skipped by readers familiar with schemes and can be used as a reference. For preliminaries to affine algebraic schemes we follow the development in Appendix A in [27]. For a summary of basic results the reader is invited to consult [21, Section 2.1]. General references for schemes include the books of D. Eisenbud and J. Harris [13], E. Kunz [24] and D. Mumford [28].

We are only interested in subschemes of a complex affine space $\mathbb{A}^{N}$. The coordinate algebra of $\mathbb{A}^{N}$ will be denoted by $S$ and it is isomorphic to the polynomial ring $\mathbb{C}\left[x_{1}, \ldots, x_{N}\right]$. A subscheme $X$ of $\mathbb{A}^{N}$ is given by an ideal $J:=J(X) \subset S$. Formally, an affine subscheme is a pair $X=(\operatorname{Spm}(S / J), S / J)$ where $|X|:=\operatorname{Spm}(S / J)$ is the maximal spectrum of the $\mathbb{C}$-algebra $S / J$ which carries the Zariski topology. The quotient $S / J$ is called the coordinate algebra or the algebra of regular functions of $X$, and will be denoted by $\mathcal{O}(X)$. A point $p$ of $|X|$ corresponds to a maximal ideal $\mathfrak{m}_{p}$ in $\mathcal{O}(X)$, and the value of the regular function $f \in \mathcal{O}(X)$ at $p$ is the reduction $f(p):=f \bmod \mathfrak{m}_{p}$. For any ideal $I \subset \mathcal{O}(X)$ we define $V(I)=\left\{p \in|X| \mid I \subset \mathfrak{m}_{p}\right\}$, and we can define the subscheme $Y=(V(I), \mathcal{O}(X) / I)$ (see [13, Section I.2.1]).

Let $X \subset \mathbb{A}^{N}$ be an affine subscheme and $p \in|X|$ a point. We denote $J:=J(X)$ the corresponding ideal of $S$. In the definition of the tangent space $T_{p}(X)$ one takes all $f \in J$, expanded around $p$ and take their linear parts. It is sufficient to take only the linear part of a finite set of generators of $J$. The tangent space $T_{p}(X)$ is the subscheme corresponding to the ideal $J_{p}^{(1)}$ generated by these homogeneous linear forms, i.e. $T_{p}(X)=V\left(J_{p}^{(1)}\right)$. In fact it is an affine subspace of $\mathbb{A}^{N}$.

The difference with the definition of the tangent cone $T C_{p}(X)$ to $X$ at $p$ is this: we take all $f \in J$, expand around $p$, and look not at their linear terms but at their leading
terms, all these leading terms generate an ideal $J_{p}^{(\infty)}$. Notice that the leading terms of a set of generators of $J$ is in general not sufficient.

Similar, for the quadratic cone $T Q_{p}(X)$ we take all $f \in J$, expand around $p$, and look at their leading term if its degree is at most two, all these leading terms generate an ideal $J_{p}^{(2)}$. We obtain:

$$
J_{p}^{(1)} \subset J_{p}^{(2)} \subset J_{p}^{(\infty)} \quad \text { and } \quad T_{p}(X) \supset T Q_{p}(X) \supset T C_{p}(X) .
$$

Notice that the tangent space is the smallest affine subspace of $\mathbb{A}^{N}$ which contains the tangent cone $T C_{p}(X)$ (see [28, III, §4] for more details).

Moreover, for each point $p \in|X|$ we have the following inequalities:

$$
\begin{equation*}
\operatorname{dim}_{p} X=\operatorname{dim} T C_{p}(X) \leq \operatorname{dim} T Q_{p}(X) \leq \operatorname{dim} T_{p}(X) \tag{3}
\end{equation*}
$$

The point $p$ is called nonsingular or smooth if the tangent cone equals the tangent space $T C_{p}(X)=T_{p}(X)$. Notice that $\operatorname{dim} T C_{p}(X)=\operatorname{dim} T_{p}(X)$ implies that $p$ is nonsingular.

An algebra is called reduced if it has no non-zero nilpotent elements. A scheme $X$ is called reduced if its coordinate algebra $\mathcal{O}(X)$ is reduced, and a point $p$ of $X$ is called reduced if its local ring $\mathcal{O}_{p}(X)$ is reduced. It follows from the local to global principle that $X$ is reduced if and only if every point of $|X|$ is reduced [24, IV.1].

In what follows we will give a sufficient condition on a point $p \in X$ to be reduced. More precisely, we will make use of the fact that the coordinate algebra of $T C_{p}(X)$ is isomorphic to the associated graded algebra of the local ring of $p \in X$ (see [28, III.§3], [24, Chap. 6, Prop. 1.2] and [21]).
Lemma 2.1. Let $X=\operatorname{Spm}\left(k\left[X_{1}, \ldots, X_{N}\right] / I\right) \subset \mathbb{A}^{N}$ be an affine scheme, and let $p \in X$ be a point. If the tangent cone $T C_{p}(X)$ is reduced then the local ring $\mathcal{O}_{p}(X)$ is also reduced and thus $p$ is reduced.

If $X$ is a scheme there exists a unique reduced subscheme $X_{\text {red }}$ of $X$ with reduced coordinate algebra $\mathcal{O}\left(X_{\text {red }}\right)=\mathcal{O}(X) / N$ (here $N$ is the nilradical of $\mathcal{O}(X)$, see [13, 21]). The topological spaces $|X|$ and $\left|X_{\text {red }}\right|$ are homeomorphic. Notice that if $p$ is a reduced point then the tangent spaces $T_{p}\left(X_{\text {red }}\right)$ and $T_{p}(X)$ coincide.
2.3. Curve tangents and quadratic cone. We recall in this section the link between the quadratic cone and the curve tangents up to second order. In what follows we consider the Artin algebras $A_{n}:=\mathbb{C}[t] /\left(t^{n+1}\right), n \in \mathbb{N}$. The algebra $A_{0}$ is identified with $\mathbb{C}$, and $A_{1}$ is commonly identified with dual numbers $\mathbb{C}[\epsilon], \epsilon^{2}=0$. We let $\pi_{n}: A_{n+1} \rightarrow A_{n}$ denote the canonical projection.

As in Section 2.2 we let $X \subset \mathbb{A}^{n}$ denote an affine algebraic subscheme with coordinate ring $\mathcal{O}(X)$. For very point $p \in X$ we let $\mathfrak{m}_{p} \subset \mathcal{O}(X)$ denote the corresponding maximal ideal and $\alpha_{p}: \mathcal{O}(X) \rightarrow \mathbb{C}$ the corresponding algebra morphism with $\operatorname{Ker}\left(\alpha_{p}\right)=\mathfrak{m}_{p}$. A tangent vector $v \in T_{p} X$ corresponds to a morphism $\alpha_{v}: \mathcal{O}(X) \rightarrow A_{1}$ such that $\pi_{0} \circ \alpha_{v}=\alpha_{p}$. We say that $v \in T_{p} X$ is a curve tangent of order two at $p$ if there exists a morphism $\alpha_{2}: \mathcal{O}(X) \rightarrow A_{2}$ such that $\pi \circ \alpha_{2}=\alpha_{v}$.
Lemma 2.2. Let $p \in X$ be a point. The space of curve tangents of order two at $p$ has the structure of an affine algebraic subscheme of $T_{p} X$. More precisely, it coincides with the quadratic cone of $X$ at $p$.
Proof. The coordinate ring of $X \subset \mathbb{A}^{n}$ has a presentation $\mathbb{C}\left[x_{1}, \ldots, x_{n}\right] /\left(f_{1}, \ldots, f_{m}\right)$. After an affine change of coordinates, and a change of generators of the ideal $J=$ $\left(f_{1}, \ldots, f_{m}\right)$, we can assume that $\mathfrak{m}_{p}=\left(x_{1}, \ldots, x_{n}\right) \supseteq J$,

$$
f_{i}=x_{i}+f_{i}^{(2)} \bmod \mathfrak{m}_{p}^{3} \quad \text { for } 1 \leq i \leq r, \underset{5}{\text { and }} f_{i}=f_{i}^{(2)} \bmod \mathfrak{m}_{p}^{3} \quad \text { for } r<i \leq m
$$

Here $f_{i}^{(2)}$ is the second homogenous component of $f_{i}=f_{i}^{(1)}+f_{i}^{(2)} \bmod \mathfrak{m}_{p}^{3}$.
The tangent space $T_{p} X$ is then given by the equations $x_{i}=0,1 \leq i \leq r$. Hence a substitution $x_{i}=a_{i} t, a_{i} \in \mathbb{C}$, defines an algebra morphism

$$
\alpha_{v}: \mathbb{C}\left[x_{1}, \ldots, x_{n}\right] /\left(f_{1}, \ldots, f_{m}\right) \rightarrow A_{1}
$$

if and only if $a_{i}=0,1 \leq i \leq r$. The corresponding tangent vector is $v=\left(a_{r+1}, \ldots, a_{n}\right) \in$ $T_{p} X$. Now, $\alpha_{v}$ extends to a morphism $\alpha_{2}: \mathcal{O}(X) \rightarrow A_{2}$ which is defined by the substitution $x_{i}=a_{i} t+b_{i} t^{2}, b_{i} \in \mathbb{C}$, if and only if

$$
b_{i}+f_{i}^{(2)}\left(0, \ldots, 0, a_{r+1}, \ldots, a_{n}\right)=0 \quad \text { for } 1 \leq i \leq r,
$$

and

$$
f_{i}^{(2)}\left(0, \ldots, 0, a_{r+1}, \ldots, a_{n}\right)=0 \quad \text { for } r+1 \leq i \leq m .
$$

Hence the coordinate algebra of second order curve tangents at $p$ is isomorphic to

$$
\begin{equation*}
\mathbb{C}\left[t_{1}, \ldots, t_{n-r}\right] /\left(g_{1}, \ldots, g_{m-r}\right) \tag{4}
\end{equation*}
$$

where $g_{j}\left(t_{1}, \ldots, t_{n-r}\right)=f_{r+j}^{(2)}\left(0, \ldots, 0, t_{1}, \ldots, t_{n-r}\right), 1 \leq j \leq m-r$, are homogenous polynomials of degree two.

The ideal of the quadratic cone $J^{(2)}$ is the ideal generated by the leading terms of polynomials of $J$ of degree lower or equal to two. We will show that $J^{(2)}$ coincides with the ideal $K$ which is generated by the leading terms of the generators of $J$ i.e. $J^{(2)}=K=\left(x_{1}, \ldots, x_{r}, f_{r+1}^{(2)}, \ldots, f_{m}^{(2)}\right)$. From this it follows directly that the algebra of the quadratic cone is isomorphic to the algebra defined in equation (4) i.e.

$$
\mathbb{C}\left[x_{1}, \ldots, x_{n}\right] / J^{(2)} \cong \mathbb{C}\left[t_{1}, \ldots, t_{n-r}\right] /\left(g_{1}, \ldots, g_{m-r}\right) .
$$

It is clear that $K \subset J^{(2)}$. In order to prove that $K \supset J^{(2)}$ we consider a polynomial $g \in J, g=\sum_{i=1}^{m} a_{i} f_{i}$ with polynomials $a_{i} \in \mathbb{C}\left[x_{1}, \ldots, x_{n}\right]$. Now a direct calculation shows that

$$
g^{(1)}=\sum_{i=1}^{r} a_{i}^{(0)} f_{i}^{(1)} \quad \text { and } \quad g^{(2)}=\sum_{i=1}^{m} a_{i}^{(0)} f_{i}^{(2)}+\sum_{i=1}^{r} a_{i}^{(1)} x_{i} .
$$

It follows from the first equation that the linear form $g^{(1)}$ is a linear combination of $x_{1}, \ldots, x_{r}$. Observe that the leading term of $g^{(1)}$ is zero if and only if $a_{i}^{(0)}=0,1 \leq$ $i \leq r$. In this case the leading term of $g$ is $g^{(2)}=\sum_{j=r+1}^{m} a_{j}^{(0)} f_{j}^{(2)}+\sum_{i=1}^{r} a_{i}^{(1)} x_{i}$ is in the ideal $K$.
2.4. Representation scheme and variety. The principal reference for this section is Lubotzky's and Magid's book [25]. To shorten notation we will simply write $\operatorname{SL}(n)$ and $\mathrm{GL}(n)$ instead of $\mathrm{SL}(n, \mathbb{C})$ and $\mathrm{GL}(n, \mathbb{C})$ respectively. The same notation applies for the Lie algebras $\mathfrak{s l}(n)=\mathfrak{s l}(n, \mathbb{C})$ and $\mathfrak{g l}(n)=\mathfrak{g l}(n, \mathbb{C})$.

Let $\Gamma$ be a finitely generated group. The set of all homomorphisms of $\Gamma$ into $\operatorname{SL}(n)$ has the structure of an affine scheme. More precisely, the $\operatorname{SL}(n)$ scheme of representations $R_{n}(\Gamma):=R(\Gamma, \mathrm{SL}(n))$ is defined as the spectrum of the universal algebra $A_{n}(\Gamma)$ :

$$
R_{n}(\Gamma):=\operatorname{Spm}\left(A_{n}(\Gamma)\right)
$$

(see [25] or [21] for more details). The scheme $R_{n}(\Gamma)$ is equipped with the Zariski topology. A single representation $\rho: \Gamma \rightarrow \mathrm{SL}(n)$ corresponds to a $\mathbb{C}$-algebra morphism $A_{n}(\Gamma) \rightarrow \mathbb{C}$ i.e. to a maximal ideal $\mathfrak{m}_{\rho} \subset A_{n}(\Gamma)$, and each maximal ideal $\mathfrak{m} \subset A_{n}(\Gamma)$ determines a representation $\rho_{\mathfrak{m}}: \Gamma \rightarrow \mathrm{SL}(n)$ (this follows from Zariski's Lemma). Hence a maximal ideal in $A_{n}(\Gamma)$ corresponds exactly to a representation $\Gamma \rightarrow \operatorname{SL}(n)$, and we will use this identification in what follows.

Notice that the universal algebra $A_{n}(\Gamma)$ might be not reduced. Therefore, one has to consider the underlying affine scheme with a possible non-reduced coordinate ring. For more details and a presentation of these notions see also [18, §2].

Associated to the representation scheme is the representation variety $R_{n}(\Gamma)_{\text {red }}$ with reduced coordinate ring. The representation variety $R_{n}(\Gamma)_{\text {red }}$ is a closed subscheme of $R_{n}(\Gamma)$. The underlying topological spaces of $R_{n}(\Gamma)$ and $R_{n}(\Gamma)_{\text {red }}$ are homeomorphic and hence $\operatorname{dim} R_{n}(\Gamma)=\operatorname{dim} R_{n}(\Gamma)_{\text {red }}$.

Let $\rho: \Gamma \rightarrow \mathrm{SL}(n)$ be a representation. The Lie algebra $\mathfrak{s l}(n)$ turns into a $\Gamma$-module via $\operatorname{Ad} \rho$. A 1 -cocycle or derivation $d \in Z^{1}(\Gamma ; \operatorname{Ad} \rho)$ is a map $d: \Gamma \rightarrow \mathfrak{s l}(n)$ satisfying

$$
d\left(\gamma_{1} \gamma_{2}\right)=d\left(\gamma_{1}\right)+\operatorname{Ad}_{\rho\left(\gamma_{1}\right)}\left(d\left(\gamma_{2}\right)\right) \quad \forall \gamma_{1}, \gamma_{2} \in \Gamma
$$

It was observed by A. Weil [33] that the tangent space $T_{\rho} R_{n}(\Gamma)_{\text {red }}$ of the representation variety at $\rho$ embeds into $Z^{1}(\Gamma ; \operatorname{Ad} \rho)$. More precisely, there is an isomorphism between the tangent space of the representation scheme $T_{\rho} R_{n}(\Gamma)$ at $\rho$ and the space of 1-cocycles $Z^{1}(\Gamma ; \operatorname{Ad} \rho)$ (see [25, Proposition 2.2]):

$$
T_{\rho} R_{n}(\Gamma) \cong Z^{1}(\Gamma ; \operatorname{Ad} \rho) .
$$

Informally speaking, given a smooth curve $\rho_{t}$ of representations through $\rho_{0}=\rho$ one gets a 1-cocycle $d: \Gamma \rightarrow \mathfrak{s l}(n)$ by defining:

$$
d(\gamma):=\left.\frac{d \rho_{t}(\gamma)}{d t}\right|_{t=0} \rho(\gamma)^{-1}, \quad \forall \gamma \in \Gamma .
$$

We obtain the following inequalities:

$$
\operatorname{dim}_{\rho} R_{n}(\Gamma)=\operatorname{dim}_{\rho} R_{n}(\Gamma)_{\text {red }} \leq \operatorname{dim} T_{\rho} R_{n}(\Gamma)_{\text {red }} \leq \operatorname{dim} T_{\rho} R_{n}(\Gamma)=\operatorname{dim} Z^{1}(\Gamma ; \operatorname{Ad} \rho)
$$

The two inequalities are independent and if $\operatorname{dim}_{\rho} R_{n}(\Gamma)=\operatorname{dim} T_{\rho} R_{n}(\Gamma)_{\text {red }}$ then $\rho$ is a smooth point of the representation variety $R_{n}(\Gamma)_{\text {red }}$. We call $\rho \in R_{n}(\Gamma)$ scheme smooth if $\operatorname{dim}_{\rho} R_{n}(\Gamma)=\operatorname{dim} Z^{1}(\Gamma ; \operatorname{Ad} \rho)$. The representation $\rho \in R_{n}(\Gamma)$ is called reduced if the local ring $\mathcal{O}_{\rho}\left(R_{n}(\Gamma)\right)$ is reduced. In this case $\operatorname{dim} T_{\rho} R_{n}(\Gamma)_{\text {red }}=\operatorname{dim} T_{\rho} R_{n}(\Gamma)$ holds independent from the first inequality. Therefore, a reduced representation is scheme smooth if and only if it is a smooth point of the representation variety.

It is easy to see that the tangent space to the orbit by conjugation $O(\rho)$ of $\rho$ corresponds to the space of principal derivations $B^{1}(\Gamma ; \operatorname{Ad} \rho)$. Here a principal derivation is a map $b: \Gamma \rightarrow \mathfrak{s l}(n)$ for which there exists $X \in \mathfrak{s l}(n)$ such that for all $\gamma \in \Gamma$ we have $b(\gamma)=\operatorname{Ad}_{\rho(\gamma)}(X)-X$. A detailed account can be found in [25].
2.5. The Alexander module. In this subsection we recall the main results from [4] concerning the Alexander module and certain cohomological results that we will use in the sequel (see also [1] and [2]).

Given a knot $K$ in a three-dimensional integer homology sphere $M^{3}$, we denote by $X=\overline{M^{3} \backslash V(K)}$ its exterior. Moreover, we let $\Gamma=\pi_{1}(X)$ denote the fundamental group and let $h: \Gamma \rightarrow \mathbb{Z}$ denote the abelianization morphism, so that $h(\gamma)=\operatorname{lk}(\gamma, K)$ is the linking number in $M^{3}$ between any loop realizing $\gamma \in \Gamma$ and $K$. There is a short exact splitting sequence:

$$
1 \rightarrow \Gamma^{\prime} \rightarrow \Gamma \rightarrow Z \rightarrow 1
$$

where $\Gamma^{\prime}=[\Gamma, \Gamma]$ denotes the commutator subgroup of $\Gamma$, and $Z=\langle t \mid-\rangle$ is a free cyclic group generated by a distinguished generator $t$ represented by a meridian of $K$. The surjection $\Gamma \rightarrow Z$ is given by $\gamma \mapsto t^{h(\gamma)}$. Hence $\Gamma$ can be written as a semi-direct product $\Gamma=\Gamma^{\prime} \rtimes Z$. Note that $\Gamma^{\prime}$ is the fundamental group of the infinite cyclic covering
$X_{\infty}$ of $X$. So $H_{1}\left(X_{\infty} ; \mathbb{Z}\right) \cong \Gamma^{\prime} / \Gamma^{\prime \prime}$. Moreover, the previous short exact splitting sequence induces the sequence:

$$
1 \rightarrow \Gamma^{\prime} / \Gamma^{\prime \prime} \rightarrow \Gamma / \Gamma^{\prime \prime} \rightarrow Z \rightarrow 1
$$

Hence $\Gamma / \Gamma^{\prime \prime}$ can be written as $\Gamma / \Gamma^{\prime \prime}=\Gamma^{\prime} / \Gamma^{\prime \prime} \rtimes Z$.
As $\Lambda:=\mathbb{C}\left[t^{ \pm 1}\right]$ is a principal ideal domain, the complex version $\Gamma^{\prime} / \Gamma^{\prime \prime} \otimes \mathbb{C} \cong H_{1}(\Gamma ; \Lambda)$ of the Alexander module decomposes into a direct sum of cyclic modules of the form $\Lambda /(t-\alpha)^{k}, \alpha \in \mathbb{C}^{*} \backslash\{1\}$ i.e. there exist $\alpha_{1}, \cdots, \alpha_{s} \in \mathbb{C}^{*} \backslash\{1\}$ such that:

$$
H_{1}(\Gamma ; \Lambda) \cong \tau_{\alpha_{1}} \oplus \cdots \oplus \tau_{\alpha_{s}} \quad \text { where } \quad \tau_{\alpha_{j}}=\bigoplus_{i_{j}=1}^{n_{\alpha_{j}}} \Lambda /\left(t-\alpha_{j}\right)^{r_{i_{j}}}
$$

denotes the $\left(t-\alpha_{j}\right)$-torsion of $H_{1}(\Gamma ; \Lambda)$.
A generator of the order ideal of $H_{1}(\Gamma ; \Lambda)$ is called the Alexander polynomial $\Delta_{K}(t) \in \Lambda$ of $K$ i.e. $\Delta_{K}(t)$ is the product:

$$
\Delta_{K}(t)=\prod_{j=1}^{s} \prod_{i_{j}=1}^{n_{\alpha_{j}}}\left(t-\alpha_{j}\right)^{r_{j_{i}}} .
$$

Notice that the Alexander polynomial is symmetric and is well defined up to multiplication by a unit $c t^{k}$ of $\Lambda, c \in \mathbb{C}^{*}, k \in \mathbb{Z}$. It is well known that $\Delta_{K}$ can be normalized such that $\Delta_{K}$ has only integer coefficients, and $\Delta_{K}(1)=1$. Hence the $(t-1)$-torsion of the Alexander module is trivial.
If $\alpha$ is a simple root of $\Delta_{K}(t)$ then the $(t-\alpha)$-torsion of the Alexander module is of the form $\mathbb{C}_{\alpha}=\Lambda /(t-\alpha)$. It follows from Blanchfield-duality [16, Chapter 7] that in this case the $\left(t-\alpha^{-1}\right)$-torsion of the Alexander module is of the same form $\mathbb{C}_{\alpha^{-1}}=\Lambda /\left(t-\alpha^{-1}\right)$, thus $\alpha^{-1}$ is also a simple root of $\Delta_{K}(t)$.

For completeness we will state the next result which shows that the cohomology groups $H^{*}\left(\Gamma ; \Lambda /(t-\alpha)^{k}\right)$ are determined by the Alexander module $H_{1}(\Gamma ; \Lambda)$. Recall that the action of $\Gamma$ on $\Lambda /(t-\alpha)^{k}$ is induced by $\gamma \cdot p(t)=t^{h(\gamma)} p(t)$. Denote by $\pi_{2}$ the composition:

$$
\pi_{2}: \Gamma^{\prime} \rightarrow \Gamma^{\prime} / \Gamma^{\prime \prime} \rightarrow \Gamma^{\prime} / \Gamma^{\prime \prime} \otimes \mathbb{C} \cong H_{1}(\Gamma ; \Lambda) .
$$

Proposition 2.3. Let $K \subset M^{3}$ be a knot in an integer homology sphere and $\Gamma=\Gamma^{\prime} \rtimes Z$ its group. Let $\alpha \in \mathbb{C}^{*}$ and let $\tau_{\alpha}=\bigoplus_{i=1}^{n_{\alpha}} \Lambda /(t-\alpha)^{r_{i}}$ denote the $(t-\alpha)$-torsion of the Alexander module $H_{1}(\Gamma ; \Lambda)$.
(1) If $\alpha=1$ then $\mathbb{C}=\mathbb{C}_{1}$ is the trivial $\Gamma$-module and

$$
H^{q}(\Gamma ; \mathbb{C}) \cong \begin{cases}\mathbb{C} & \text { for } q=0,1, \\ 0 & \text { for } q=2 .\end{cases}
$$

(2) For $\alpha \neq 1$ with $\Delta_{K}(\alpha) \neq 0$ we have:

$$
H^{q}\left(\Gamma ; \mathbb{C}_{\alpha}\right) \cong 0 \quad \text { for } q \geq 0
$$

(3) If $\alpha \in \mathbb{C}^{*}$ is a root of the Alexander polynomial $\Delta_{K}$ then the morphism

$$
\begin{aligned}
\Phi: \operatorname{Hom}_{\Lambda}\left(\Gamma^{\prime} / \Gamma^{\prime \prime} \otimes \mathbb{C}, \mathbb{C}_{\alpha}\right) & \rightarrow H^{1}\left(\Gamma^{\prime} \rtimes Z ; \mathbb{C}_{\alpha}\right) \\
U & \mapsto[\bar{U}] ; \bar{U}\left(x, t^{k}\right)=U\left(\pi_{2}(x)\right) \forall x \in \Gamma^{\prime}
\end{aligned}
$$

is an isomorphism and

$$
\begin{aligned}
\psi:=\Phi^{-1}: H^{1}\left(\Gamma^{\prime} \rtimes Z ; \mathbb{C}_{\alpha}\right) & \rightarrow \operatorname{Hom}_{\Lambda}\left(\Gamma^{\prime} / \Gamma^{\prime \prime} \otimes \mathbb{C}, \mathbb{C}_{\alpha}\right) \\
{[V] } & \mapsto \tilde{V} ; \tilde{V}\left(\pi_{2}(x)\right)=V(x, 1) \forall x \in \Gamma^{\prime} .
\end{aligned}
$$

(4) For $\alpha$ a simple root of $\Delta_{K}(t)$ we have:

$$
H^{q}\left(\Gamma ; \mathbb{C}_{\alpha}\right) \cong \begin{cases}0 & \text { for } q=0 \\ \mathbb{C} & \text { for } q=1,2\end{cases}
$$

In particular, as $H_{1}(\Gamma ; \Lambda) \cong \Gamma^{\prime} / \Gamma^{\prime \prime} \otimes \mathbb{C}=\Lambda /(t-\alpha) \oplus \tau$ where $\tau$ is a torsion $\Lambda$-module with no $(t-\alpha)$-torsion, $H^{1}\left(\Gamma ; \mathbb{C}_{\alpha}\right)$ is generated by the non-principal derivation $u_{\alpha}$ uniquely defined by the condition $\tilde{u}_{\alpha}\left(e_{\alpha}\right)=1$ and $\tilde{u}_{\alpha}(y)=0 \forall y \in \tau$ where $\left(e_{\alpha}\right)$ be a basis of $\Lambda /(t-\alpha)$.

Proof. For the proof see [2, Proposition 2.1 and Proof of Theorem 3.1].

The next lemma forms the basis for our subsequent results and is implicitly contained in [4, Proposition 3.5] (see also [2, Theorem 3.1], [1, Theorem 3.2]).

Lemma 2.4. Let $K \subset M^{3}$ be a knot in an integer homology sphere and $\Gamma$ its group. Let $\alpha \in \mathbb{C}^{*}$ be a simple root of the Alexander polynomial $\Delta_{K}$ and $h: \Gamma \rightarrow \mathbb{Z}$ the canonical epimorphism. The cup product:

$$
h \smile \cdot: H^{1}\left(\Gamma ; \mathbb{C}_{\alpha^{ \pm}}\right) \rightarrow H^{2}\left(\Gamma ; \mathbb{C}_{\alpha^{ \pm}}\right)
$$

is an isomorphism. In other words, if $u^{ \pm}$is a generator of $H^{1}\left(\Gamma ; \mathbb{C}_{\alpha^{ \pm}}\right)$then $H^{2}\left(\Gamma ; \mathbb{C}_{\alpha^{ \pm}}\right)$ is generated by $h \smile u^{ \pm}$.

Remark 2.5. Observe that by Equation 2 the cocycles $h \smile u^{ \pm}$and $-u^{ \pm} \smile h$ are cohomologous.

## 3. Proof of the main theorem

This section is devoted to the proof of the first part of Theorem 1.1. Our strategy consists in introducing a certain solvable representation $\rho_{D}^{(n)} \in R_{n}(\Gamma)$ whose orbit contains in its closure the diagonal representation $\rho_{D}$. As a consequence, the representations $\rho_{D}$ and $\rho_{D}^{(n)}$ are on the same component (see subsection 3.1). Using a theorem of 19 based on cohomological calculations, we prove that $\rho_{D}^{(n)}$ is a smooth point of $R_{n}(\Gamma)$ which is contained in a unique irreducible component $R_{D}^{(n)}$ of dimension $n^{2}+n-2$ (see subsection 3.2). We finish the section by proving that $R_{D}^{(n)}$ contains irreducible representations by making use of Burnsides matrix lemma ( see subsection 3.3). It is to mention that our strategy reproduces in a certain manner the one used by [22] for the study of the local structure of the representation space $R_{2}(\Gamma)$ in the neighborhood of an abelian representation which corresponds to a simple root of the Alexander polynomial of the knot. It is based on the fact that $\rho_{D}^{(n)}$ is less singular than $\rho_{D}$ in the sense that $\operatorname{dim} O\left(\rho_{D}^{(n)}\right)=n^{2}-1$ whereas $\operatorname{dim} O\left(\rho_{D}\right)=n^{2}-n$ (see Proposition 3.6).
3.1. The triangular representation. Let $D=D\left(\lambda_{1}, \ldots, \lambda_{n}\right) \in \operatorname{SL}(n)$ be a diagonal matrix with $\lambda_{i} \neq \lambda_{j}$ for $i \neq j$. The aim of this section is to prove the existence of a certain upper triangular representation $\rho_{D}^{(n)}: \Gamma \rightarrow \operatorname{SL}(n)$. We will show that $\rho_{D}^{(n)} \in R_{n}(\Gamma)$ is a smooth point (see Theorem [3.3), whereas the diagonal representation $\rho_{D}=D^{h}$ is not (see Remark 3.4).

Assumption. Throughout this section we will assume that $\alpha_{i}:=\lambda_{i} / \lambda_{i+1}, i=1, \ldots, n-1$, are simple roots of the Alexander polynomial $\Delta_{K}(t)$ and that

$$
\Delta_{K}\left(\lambda_{i} / \lambda_{j}\right) \neq 0 \text { if }|i-j| \geq 2
$$

Lemma 3.1. If $u_{i}^{+} \in Z^{1}\left(\Gamma ; \mathbb{C}_{\alpha_{i}}\right), i=1, \ldots, n-1$, are derivations then there exist upper triangular representations $\rho_{D}^{(n)}: \Gamma \rightarrow \mathrm{SL}(n)$ of the form:

$$
\rho_{D}^{(n)}(\gamma)=\left(\begin{array}{ccccc}
1 & u_{1}^{+}(\gamma) & * & \ldots & *  \tag{5}\\
0 & 1 & u_{2}^{+}(\gamma) & \ddots & \vdots \\
\vdots & \ddots & \ddots & \ddots & * \\
\vdots & & \ddots & 1 & u_{n-1}^{+}(\gamma) \\
0 & \cdots & \cdots & 0 & 1
\end{array}\right) D\left(\lambda_{1}, \ldots, \lambda_{n}\right)^{h(\gamma)}
$$

Moreover, the closure of the orbit of $\rho_{D}^{(n)}$ contains the diagonal representation $\rho_{D}$. Proof. It is easy to verify that a map given by

$$
\rho(\gamma)=\left(\begin{array}{ccccc}
1 & z_{12}(\gamma) & * & \ldots & z_{1 n}(\gamma) \\
0 & 1 & z_{23}(\gamma) & \ddots & \vdots \\
\vdots & \ddots & \ddots & \ddots & * \\
\vdots & & \ddots & 1 & z_{n-1, n}(\gamma) \\
0 & \ldots & \ldots & 0 & 1
\end{array}\right) D\left(\lambda_{1}, \ldots, \lambda_{n}\right)^{h(\gamma)}
$$

is a representation if and only if for all $1 \leq i<j \leq n$ :

$$
\begin{aligned}
z_{i j}\left(\gamma_{1} \gamma_{2}\right) & =\sum_{k=i}^{j} z_{i k}\left(\gamma_{1}\right)\left(\frac{\lambda_{k}}{\lambda_{j}}\right)^{h\left(\gamma_{1}\right)} z_{k j}\left(\gamma_{2}\right) \\
& =\left(\frac{\lambda_{i}}{\lambda_{j}}\right)^{h\left(\gamma_{1}\right)} z_{i j}\left(\gamma_{2}\right)+\sum_{k=i+1}^{j-1}\left(z_{i k} \smile z_{k j}\right)\left(\gamma_{1}, \gamma_{2}\right)+z_{i j}\left(\gamma_{1}\right)
\end{aligned}
$$

holds. Here we have used the convention that $z_{i i}(\gamma)=1$ for $1 \leq i \leq n$ and $\gamma \in \Gamma$.
This equation is equivalent to

$$
-\delta z_{i j}=\sum_{i<k<j} z_{i k} \smile z_{k j} \quad \text { for all } 1 \leq i<j \leq n
$$

It implies that $z_{i, i+1} \in Z^{1}\left(\Gamma ; \mathbb{C}_{\alpha_{i}}\right)$ if $1 \leq i \leq n-1$ and

$$
-\delta z_{i j}=\sum_{i<k<j} z_{i k} \smile z_{k j} \in B^{2}\left(\Gamma ; \mathbb{C}_{\lambda_{i} / \lambda_{j}}\right) \quad \text { if } j-i \geq 2
$$

By Proposition [2.3, since $\lambda_{i} / \lambda_{j}$ is not a root of $\Delta_{K}$ for $|i-j| \geq 2$, we have $H^{2}\left(\Gamma ; \mathbb{C}_{\lambda_{i}} / \lambda_{j}\right)=$ 0 and the cocycle $\sum_{i<k<j} z_{i k} \smile z_{k j}$ is a coboundary. Notice also that by Proposition [2.3, there exist non principal derivations $z \in Z^{1}\left(\Gamma ; \mathbb{C}_{\alpha}\right)$ as $\alpha$ is a root of $\Delta_{K}(t)$.

For $t>0$, let $C_{t}$ be the diagonal matrix $C_{t}:=\operatorname{diag}\left(t^{n-1}, t^{n-2}, \ldots, 1\right)$. Then it is easy to see that $\lim _{t \rightarrow 0} C_{t} \rho_{D}^{(n)}(\gamma) C_{t}^{-1}=\rho_{D}(\gamma)$ for all $\gamma \in \Gamma$. This proves that $\rho_{D} \in \overline{O\left(\rho_{D}^{(n)}\right)}$.

Remark 3.2. (1) The representation $\rho_{D}^{(n)}$ is non-abelian if there exists $i_{0}, 1 \leq i_{0} \leq$ $n-1$, such that $u_{i_{0}}^{+}$is a non principal derivation. To see that suppose that a derivation $z_{i_{0}} \in Z^{1}\left(\Gamma ; \mathbb{C}_{\alpha_{i_{0}}}\right)$ is non-principal. By Lemma 2.1 of [22] we can find a set of generators $\gamma_{1}, \ldots, \gamma_{k}$ of $\Gamma$ such that $h\left(\gamma_{l}\right)=1$ for $l=1, \ldots, k$. As $z_{i_{0}}$ is non-principal, there exist $\gamma_{l}$ and $\gamma_{l^{\prime}}$ such that $z_{i_{0}}\left(\gamma_{l}\right) \neq z_{i_{0}}\left(\gamma_{l^{\prime}}\right)$. It follows that $\rho_{D}^{(n)}$ is non-abelian since the two matrices

$$
\left(\begin{array}{ll}
1 & b \\
0 & 1
\end{array}\right)\left(\begin{array}{cc}
\lambda_{i} & 0 \\
0 & \lambda_{i+1}
\end{array}\right) \quad \text { and } \quad\left(\begin{array}{cc}
1 & c \\
0 & 1
\end{array}\right)\left(\begin{array}{cc}
\lambda_{i} & 0 \\
0 & \lambda_{i+1}
\end{array}\right)
$$

commute if and only if $(b-c)=0$.
(2) Once the derivations $u_{i}^{+}, i=1, \cdots, n-1$, fixed, two such representations $\rho_{D}^{(n)}$ are conjugated. This claim is a consequence of the fact that $H^{2}\left(\Gamma ; \mathbb{C}_{\lambda_{i} / \lambda_{j}}\right)=0$ for $|i-j| \geq 2$, and the fact that adding a coboundary $b(\gamma)=\left(\left(\lambda_{i} / \lambda_{j}\right)^{h(\gamma)}-1\right) a$ to $z_{i, j}, j-i \geq 2$, can be realized by conjugation by the matrix $I_{n}-a E_{i}^{j}$. Here, $\left(E_{i}^{j}\right)_{1 \leq i, j \leq n}$ is the canonical basis of $\mathfrak{g l}(n)$.
The aim of this section is to prove the next theorem.
Theorem 3.3. Suppose that $\alpha_{i}=\lambda_{i} / \lambda_{i+1}, i=1, \ldots, n-1$, are simple roots of the Alexander polynomial $\Delta_{K}(t)$, and that $\Delta_{K}\left(\lambda_{i} / \lambda_{j}\right) \neq 0$ if $|i-j| \geq 2$. Then for given non-principal derivations $u_{i}^{+} \in Z^{1}\left(\Gamma ; \mathbb{C}_{\alpha_{i}}\right)$ the representation $\rho_{D}^{(n)}: \Gamma \rightarrow \mathrm{SL}(n)$ given by (5) is a scheme smooth representation of $R_{n}(\Gamma)$.

More precisely, $\rho_{D}^{(n)}$ is contained in a unique irreducible component $R_{D}^{(n)} \subset R_{n}(\Gamma)$ of dimension $n^{2}+n-2$ and the component $R_{D}^{(n)}$ contains irreducible representations.

Remark 3.4. (1) The component $R_{D}^{(n)} \subset R_{n}(\Gamma)$ depends only on $\lambda_{1}, \ldots, \lambda_{n}$ and not on the cocycles $u_{i}^{+}$. This follows since the $u_{i}^{+}$are non-principal and $H^{1}\left(\Gamma ; \mathbb{C}_{\alpha_{i}}\right) \cong$ $\mathbb{C}$. Adding a coboundary $b(\gamma)=\left(\alpha_{i}^{h(\gamma)}-1\right) a$ to $u_{i}^{+}$and multiplying $u_{i}^{+}$by a non-zero complex number $c \in \mathbb{C}^{*}$ can be realized by conjugation:

$$
\left(\begin{array}{cc}
1 & a \\
0 & 1
\end{array}\right)\left(\begin{array}{cc}
1 & u_{i}^{+}(\gamma) \\
0 & 1
\end{array}\right)\left(\begin{array}{cc}
\lambda_{i}^{h(\gamma)} & 0 \\
0 & \lambda_{i+1}^{h(\gamma)}
\end{array}\right)\left(\begin{array}{cc}
1 & -a \\
0 & 1
\end{array}\right)=\left(\begin{array}{cc}
1 & u_{i}^{+}(\gamma)+\left(\alpha_{i}^{h(\gamma)}-1\right) a \\
0 & 1
\end{array}\right)\left(\begin{array}{cc}
\lambda_{i}^{h(\gamma)} & 0 \\
0 & \lambda_{i+1}^{h(\gamma)}
\end{array}\right)
$$

and

$$
\left(\begin{array}{cc}
c^{1 / 2} & 0 \\
0 & c^{-1 / 2}
\end{array}\right)\left(\begin{array}{cc}
1 & u_{i}^{+}(\gamma) \\
0 & 1
\end{array}\right)\left(\begin{array}{cc}
\lambda_{i} & 0 \\
0 & \lambda_{i+1}
\end{array}\right)\left(\begin{array}{cc}
c^{-1 / 2} & 0 \\
0 & c^{1 / 2}
\end{array}\right)=\left(\begin{array}{cc}
1 & c u_{i}^{+}(\gamma) \\
0 & 1
\end{array}\right)\left(\begin{array}{cc}
\lambda_{i} & 0 \\
0 & \lambda_{i+1}
\end{array}\right) .
$$

(2) By Lemma 3.1, the diagonal representation $\rho_{D}$ is contained in the closure of the orbit of $\rho_{D}^{(n)}$, thus $\rho_{D}$ is contained in the irreducible component $R_{D}^{(n)}$. On the other hand, as an abelian representation, $\rho_{D}$ is contained in the irreducible component $R_{n}(\mathbb{Z})$. Consequently, $\rho_{D}$ is not a smooth point of $R_{n}(\Gamma)$.

For the proof of Theorem 3.3 we will make use of the following result (see [5, 22, 20, [19, 18]).

Proposition 3.5. Let $M$ be a connected and orientable 3-manifold with toroidal boundary $\partial M \cong S^{1} \times S^{1}$ and let $\rho: \pi_{1}(M) \rightarrow \mathrm{SL}(n)$ be a representation.
If $\operatorname{dim} H^{1}\left(\pi_{1}(M) ; \mathfrak{s l}(n)_{\operatorname{Ad} \rho}\right)=n-1$ then $\rho$ is a smooth point of the $\operatorname{SL}(n)$ representation variety $R_{n}\left(\pi_{1}(M)\right)$. More precisely, $\rho$ is contained in a unique component of dimension $n^{2}+n-2-\operatorname{dim} H^{0}\left(\pi_{1}(M) ; \mathfrak{s l}(n)_{\mathrm{Ad} \rho}\right)$.

The knot complement $X$ has a single torus boundary component. To prove the first part of Theorem 3.3, we are going to prove that $H^{0}\left(\Gamma, \mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}^{(n)}}\right)=0$ and $\operatorname{dim} H^{1}\left(\Gamma ; \mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}^{(n)}}\right)=n-1$. This calculation will occupy the following subsection. The proof of the existence of irreducible representations in the component $R_{D}^{(n)}$ is given in the last one.
3.2. Cohomolgical calculations. Hereafter, we will fix non-principal derivations $u_{i}^{ \pm}: \Gamma \rightarrow \mathbb{C}_{\alpha_{i} \pm}, 1 \leq i \leq n-1$, and we let $\rho_{D}^{(n)}$ be a representation as given by (55). Moreover, we will consider $\mathfrak{s l}(n)$ (respectively $\mathfrak{g l}(n))$ as a $\Gamma$-module via Ad $\rho_{D}^{(n)}$ and for simplicity we will write $\mathfrak{s l}(n)$ (respectively $\mathfrak{g l}(n))$ for $\mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}^{(n)}}$ (respectively $\left.\mathfrak{g l}(n)_{\operatorname{Ad}} \rho_{D}^{(n)}\right)$. Notice that we have the following isomorphism of $\Gamma$-modules: $\mathfrak{g l}(n) \cong \mathfrak{s l}(n) \oplus \mathbb{C} I_{n}$ where $\Gamma$ acts trivially on the center $\mathbb{C} I_{n}$ of $\mathfrak{g l}(n)$. It follows that:

$$
\begin{equation*}
H^{*}(\Gamma ; \mathfrak{g l}(n)) \cong H^{*}(\Gamma ; \mathfrak{s l}(n)) \oplus H^{*}(\Gamma ; \mathbb{C}) . \tag{6}
\end{equation*}
$$

To compute the cohomology groups $H^{*}(\Gamma ; \mathfrak{g l}(n))$ we will use an adequate filtration of the $\Gamma$-module $\mathfrak{g l}(n)$.
Let $\left(E_{1}, \ldots, E_{n}\right)$ denote the canonical basis of the space of column vectors. Hence $E_{i}^{j}:=E_{i} E_{j}^{\top}, 1 \leq i, j \leq n$, form the canonical basis of $\mathfrak{g l}(n)$. For a given family $\left(X_{i}\right)_{i \in I}$, $X_{i} \in \mathfrak{g l}(n)$, we let $\left\langle X_{i} \mid i \in I\right\rangle \subset \mathfrak{g l}(n)$ denote the subspace of $\mathfrak{g l}(n)$ generated by the family. For a given $k \in \mathbb{Z}, 1-n \leq k \leq n$, we define:

$$
\begin{equation*}
C_{k}=\left\langle E_{i}^{j} \in \mathfrak{g l}(n, \mathbb{C}) \mid j-i \geq k\right\rangle \tag{7}
\end{equation*}
$$

For all $\gamma \in \Gamma$ we have:

$$
\begin{equation*}
\gamma \cdot E_{i}^{j}=\left(\rho_{D}^{(n)}(\gamma) E_{i}\right)\left(E_{j}^{\top} \rho_{D}^{(n)}\left(\gamma^{-1}\right)\right) . \tag{8}
\end{equation*}
$$

More precisely, we obtain for $1 \leq i, j \leq n$,

$$
\rho_{D}^{(n)}(\gamma) E_{i}=\lambda_{i}^{h(\gamma)} E_{i}+\lambda_{i}^{h(\gamma)} u_{i-1}^{+}(\gamma) E_{i-1}+\cdots
$$

and

$$
\begin{aligned}
E_{j}^{\top} \rho_{D}^{(n)}\left(\gamma^{-1}\right) & =\lambda_{j}^{-h(\gamma)} E_{j}^{\top}+\lambda_{j+1}^{-h(\gamma)} u_{j}^{+}\left(\gamma^{-1}\right) E_{j+1}^{\top}+\cdots \\
& =\lambda_{j}^{-h(\gamma)} E_{j}^{\top}-\lambda_{j+1}^{-h(\gamma)}\left(\frac{\lambda_{j}}{\lambda_{j+1}}\right)^{-h(\gamma)} u_{j}^{+}(\gamma) E_{j+1}^{\top}+\cdots
\end{aligned}
$$

Here we have used the fact that, as $u_{j}^{+}$is a derivation, $u_{j}^{+}\left(\gamma^{-1}\right)=-\left(\lambda_{j} / \lambda_{j+1}\right)^{-h(\gamma)} u_{j}^{+}(\gamma)$. Hence for $E_{i}^{j} \in C_{k}$ we have:

$$
\begin{equation*}
\gamma \cdot E_{i}^{j}=\left(\frac{\lambda_{i}}{\lambda_{j}}\right)^{h(\gamma)} E_{i}^{j}+\left(\frac{\lambda_{i}}{\lambda_{j}}\right)^{h(\gamma)} u_{i-1}^{+}(\gamma) E_{i-1}^{j}-\left(\frac{\lambda_{i}}{\lambda_{j}}\right)^{h(\gamma)} u_{j}^{+}(\gamma) E_{i}^{j+1}+c_{k+2} \tag{9}
\end{equation*}
$$

for a certain element $c_{k+2} \in C_{k+2}$.
It follows from equation (9) that $C_{k}$ is a $\Gamma$-module. Hence we obtain the descending sequence of $\Gamma$-modules:

$$
\mathfrak{g l}(n, \mathbb{C})=C_{1-n} \supset C_{2-n} \ldots \supset C_{0} \supset \ldots \supset C_{n-1} \supset C_{n}=\{0\}
$$

Notice that $C_{0}$ is the Borel subalgebra and that the coordinate function $p_{1}^{n}: C_{n-1}=$ $\left\langle E_{1}^{n}\right\rangle \rightarrow \mathbb{C}_{\lambda_{1} / \lambda_{n}}$ induces an isomorphism.

A basis of the vector space $C_{k} / C_{k+1}$ is given by:

$$
\left\{\begin{array}{cc}
\left(E_{1}^{k+1}+C_{k+1}, E_{2}^{k+2}+C_{k+1}, \ldots, E_{n-k}^{n}+C_{k+1}\right) & \text { if } 0 \leq k \leq n-1 \\
\left(E_{|k|+1}^{1}+C_{k+1}, E_{|k|+2}^{2}+C_{k+1}, \ldots, E_{n}^{n-|k|}+C_{k+1}\right) & \text { if } 1-n \leq k \leq 0
\end{array}\right.
$$

Hence we have the following isomorphisms which are induced by the projections:

$$
\begin{array}{rlr}
p_{1}^{k+1} \oplus p_{2}^{k+2} \oplus \cdots \oplus p_{n-k}^{n}: C_{k} / C_{k+1} \xrightarrow{\cong} \oplus_{i=1}^{n-k} \mathbb{C}_{\lambda_{i} / \lambda_{k+i}} & \text { if } 0 \leq k \leq n-1, \\
p_{|k|+1}^{1} \oplus p_{|k|+2}^{2} \oplus \cdots \oplus p_{n}^{n-|k|}: C_{k} / C_{k+1} \xrightarrow{\rightrightarrows} \oplus_{i=1}^{n-|k|} \mathbb{C}_{\lambda_{i+|k|} / \lambda_{i}} & \text { if } 1-n \leq k<0 .
\end{array}
$$

As $\lambda_{i} / \lambda_{j},|i-j| \geq 2$, is not a root of the Alexander polynomial $\Delta_{K}$ and $\lambda_{i} / \lambda_{i+1}$, $1 \leq i \leq n-1$, is a simple root of $\Delta_{K}$, we obtain from Proposition 2.3

$$
\begin{align*}
& H^{0}\left(\Gamma ; C_{k} / C_{k+1}\right) \cong \begin{cases}0 & \text { if } k \neq 0, \\
\mathbb{C}^{n} & \text { if } k=0,\end{cases} \\
& H^{1}\left(\Gamma ; C_{k} / C_{k+1}\right) \cong \begin{cases}0 & \text { if } k \neq-1,0,1, \\
\mathbb{C}^{n} & \text { if } k=0, \\
\mathbb{C}^{n-1} & \text { if } k= \pm 1,\end{cases}  \tag{10}\\
& H^{2}\left(\Gamma ; C_{k} / C_{k+1}\right) \cong \begin{cases}0 & \text { if } k \neq \pm 1, \\
\mathbb{C}^{n-1} & \text { if } k= \pm 1 .\end{cases}
\end{align*}
$$

In what follows we will consider the following short exact sequence:

$$
\begin{equation*}
0 \rightarrow C_{k+1} \stackrel{i_{k}}{\longrightarrow} C_{k} \xrightarrow{p r_{k}} C_{k} / C_{k+1} \rightarrow 0 \tag{11}
\end{equation*}
$$

For $|k| \leq n-1$, the sequence (11) induces a long exact sequence in cohomology:

$$
\begin{align*}
0 \rightarrow H^{0}\left(\Gamma ; C_{k+1}\right) \rightarrow & H^{0}\left(\Gamma ; C_{k}\right) \rightarrow H^{0}\left(\Gamma ; C_{k} / C_{k+1}\right) \xrightarrow{\beta_{k}^{0}}  \tag{12}\\
H^{1}\left(\Gamma ; C_{k+1}\right) \rightarrow & H^{1}\left(\Gamma ; C_{k}\right) \rightarrow H^{1}\left(\Gamma ; C_{k} / C_{k+1}\right) \xrightarrow{\beta_{k}^{1}} \\
& H^{2}\left(\Gamma ; C_{k+1}\right) \rightarrow H^{2}\left(\Gamma ; C_{k}\right) \rightarrow H^{2}\left(\Gamma ; C_{k} / C_{k+1}\right) \rightarrow \cdots
\end{align*}
$$

and we will denote by $\beta_{k}^{*}: H^{*}\left(\Gamma, C_{k} / C_{k+1}\right) \rightarrow H^{*+1}\left(\Gamma, C_{k+1}\right)$ the connecting homomorphism.

Proposition 3.6. Suppose that $\alpha_{i}=\lambda_{i} / \lambda_{i+1}, i=1, \ldots, n-1$, are simple roots of the Alexander polynomial $\Delta_{K}(t)$, and that $\Delta_{K}\left(\lambda_{i} / \lambda_{j}\right) \neq 0$ if $|i-j| \geq 2$. Then for given non-principal derivations $u_{i}^{+} \in Z^{1}\left(\Gamma ; \mathbb{C}_{\alpha_{i}}\right)$ the representation $\rho_{D}^{(n)}: \Gamma \rightarrow \mathrm{SL}(n)$ given by (5) verifies:

$$
H^{0}\left(\Gamma, \mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}^{(n)}}\right)=\{0\} \quad \text { and } \quad \operatorname{dim} H^{1}\left(\Gamma, \mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}^{(n)}}\right)=n-1
$$

Proof. It follows from (10) that $H^{2}\left(\Gamma, C_{k} / C_{k+1}\right)=0$ for $|k| \geq 2$; hence from the long exact sequence (12) we obtain isomorphisms $H^{*}\left(\Gamma ; C_{k+1}\right) \stackrel{\cong}{\leftrightarrows} H^{*}\left(\Gamma ; C_{k}\right)$ for $|k| \geq 2$.

From this and (10) we obtain:

$$
0=H^{*}\left(\Gamma ; C_{n-1}\right) \xrightarrow{\cong} H^{*}\left(\Gamma ; C_{n-2}\right) \xrightarrow{\cong} \cdots \xrightarrow{\cong} H^{*}\left(\Gamma ; C_{2}\right)
$$

and

$$
H^{*}\left(\Gamma ; C_{-1}\right) \xrightarrow{\cong} H^{*}\left(\Gamma ; C_{-2}\right) \xrightarrow{\cong} \cdots \xrightarrow{\cong} H^{*}\left(\Gamma ; C_{1-n}\right)=H^{*}(\Gamma ; \mathfrak{g l}(n, \mathbb{C})) .
$$

Now, $H^{*}\left(\Gamma ; C_{2}\right)=0$ and $C_{2} \subset C_{-1}$ imply that:

$$
H^{*}\left(\Gamma ; C_{-1}\right) \stackrel{\cong}{\rightrightarrows} H^{*}\left(\Gamma ; C_{-1} / C_{2}\right) .
$$

Therefore it will be sufficient to compute the dimension of $H^{*}\left(\Gamma ; C_{-1} / C_{2}\right)$.
We have the following inclusions:

$$
C_{-1} \supset C_{0} \supset C_{1} \supset C_{2} \quad \rightarrow{ }_{13} C_{-1} / C_{2} \supset C_{0} / C_{2} \supset C_{1} / C_{2} .
$$

Thus we obtain two exact sequences of $\Gamma$-modules:

$$
\begin{array}{r}
0 \rightarrow C_{1} / C_{2} \rightarrow C_{0} / C_{2} \rightarrow C_{0} / C_{1} \rightarrow 0 \\
0 \rightarrow C_{0} / C_{2} \rightarrow C_{-1} / C_{2} \rightarrow C_{-1} / C_{0} \rightarrow 0 \tag{14}
\end{array}
$$

The short exact sequence (13) induces the following long sequence in cohomology:

$$
\begin{aligned}
0 \rightarrow H^{0}\left(\Gamma ; C_{0} / C_{2}\right) \rightarrow H^{0}(\Gamma & \left.; C_{0} / C_{1}\right) \xrightarrow{\beta^{0}} H^{1}\left(\Gamma ; C_{1} / C_{2}\right) \rightarrow H^{1}\left(\Gamma ; C_{0} / C_{2}\right) \\
& \rightarrow H^{1}\left(\Gamma ; C_{0} / C_{1}\right) \xrightarrow{\beta^{1}} H^{2}\left(\Gamma ; C_{1} / C_{2}\right) \rightarrow H^{2}\left(\Gamma ; C_{0} / C_{2}\right) \rightarrow 0
\end{aligned}
$$

since by equation (10), $H^{0}\left(\Gamma ; C_{1} / C_{2}\right)=0$ and $H^{2}\left(\Gamma ; C_{0} / C_{1}\right)=0$.
In order to determine the connection operators $\beta^{*}, *=0,1$, we fix a basis $E_{i}^{i}+C_{1}$, $i=1, \ldots, n$, of $C_{0} / C_{1}$. Then $\left\{E_{i}^{i}+C_{1}\right\}_{1 \leq i \leq n}$ is a basis of $H^{0}\left(\Gamma ; C_{0} / C_{1}\right)$, and the cocycles $U_{j}: \Gamma \rightarrow C_{1} / C_{2}, j=1, \ldots, n-1$, given by $U_{j}(\gamma)=u_{j}^{+}(\gamma) E_{j}^{j+1}+C_{2}$ represent a basis of $H^{1}\left(\Gamma ; C_{1} / C_{2}\right)$.

Now we let $\delta^{*}$ denote the coboundary operator of the complex $C^{*}(\Gamma ; \mathfrak{g l}(n))$. Then equation (9) gives directly:

$$
\delta^{0}\left(E_{i}^{i}\right)(\gamma)=\gamma \cdot E_{i}^{i}-E_{i}^{i}=u_{i-1}^{+}(\gamma) E_{i-1}^{i}-u_{i}^{+}(\gamma) E_{i}^{i+1}+c_{2}
$$

for a certain element $c_{2} \in C_{2}$. Therefore, $\beta^{0}\left(E_{i}^{i}+C_{1}\right)=U_{i-1}-U_{i}+C_{2}$ where $U_{0}$ and $U_{n}$ are understood to be zero. Hence the matrix of $\beta^{0}$ with respect to the basis $\left\{E_{i}^{i}+C_{2}\right\}_{1 \leq i \leq n}$ and $\left\{U_{j}\right\}_{1 \leq j \leq n-1}$ of $H^{0}\left(\Gamma ; C_{0} / C_{1}\right)$ and $H^{1}\left(\Gamma ; C_{1} / C_{2}\right)$ respectively is the $(n-1) \times n$ matrix:

$$
M=\left(\begin{array}{ccccc}
-1 & 1 & 0 & \ldots & 0  \tag{15}\\
0 & -1 & 1 & 0 & \vdots \\
\vdots & \ddots & \ddots & \ddots & 0 \\
0 & \ldots & 0 & -1 & 1
\end{array}\right)
$$

of rank $n-1$. Hence $\beta^{0}$ is surjective.
Similarly, $\left\{h E_{i}^{i}+C_{2}\right\}_{1 \leq i \leq n}$ represents a basis of $H^{1}\left(\Gamma ; C_{0} / C_{1}\right)$, and

$$
\delta^{1}\left(h E_{i}^{i}\right)\left(\gamma_{1}, \gamma_{2}\right)=\left(u_{i-1}^{+} \smile h\right)\left(\gamma_{1}, \gamma_{2}\right) E_{i-1}^{i}-\left(u_{i}^{+} \smile h\right)\left(\gamma_{1}, \gamma_{2}\right) E_{i}^{i+1}+c_{2}
$$

where $u_{0}^{+}$and $u_{n}^{0}$ are understood to be zero. By Lemma 2.4 and Remark [2.5, the 2-cocycles $u_{i}^{+} \smile h \in Z^{2}\left(\Gamma ; \mathbb{C}_{\alpha_{i}}\right)$ represent generators of $H^{2}\left(\Gamma ; \mathbb{C}_{\alpha_{i}}\right)$. Hence the matrix of $\beta^{1}$ with respect to the basis $\left\{h E_{i}^{i}+C_{2}\right\}_{1 \leq i \leq n}$ and $\left\{\left(u_{i}^{+} \smile h\right) E_{i}^{i+1}+C_{2}\right\}_{1 \leq i \leq n-1}$ of $H^{1}\left(\Gamma ; C_{0} / C_{1}\right)$ and $H^{2}\left(\Gamma ; C_{1} / C_{2}\right)$ respectively is also the $(n-1) \times n$ matrix $M$ of equation (15). Hence $\beta^{1}$ is also surjective.

As a consequence $H^{2}\left(\Gamma ; C_{0} / C_{2}\right)=0$ and we obtain the two short exact sequences:

$$
0 \rightarrow H^{0}\left(\Gamma ; C_{0} / C_{2}\right) \rightarrow H^{0}\left(\Gamma ; C_{0} / C_{1}\right) \rightarrow H^{1}\left(\Gamma ; C_{1} / C_{2}\right) \rightarrow 0,
$$

and

$$
0 \rightarrow H^{1}\left(\Gamma ; C_{0} / C_{2}\right) \rightarrow H^{1}\left(\Gamma ; C_{0} / C_{1}\right) \rightarrow H^{2}\left(\Gamma ; C_{1} / C_{2}\right) \rightarrow 0
$$

We deduce that, $\operatorname{dim} H^{0}\left(\Gamma ; C_{0} / C_{2}\right)=\operatorname{dim} H^{1}\left(\Gamma ; C_{0} / C_{2}\right)=1($ see (10) $)$.
Observe that $H^{1}\left(\Gamma ; C_{0} / C_{2}\right)$ is generated by $\left\langle h I_{n}+C_{2}\right\rangle$, where $I_{n}$ is the identity matrix of order $n$.

Now consider the short exact sequence (14) which induces the following sequence in cohomology:

$$
\begin{aligned}
& 0 \rightarrow H^{0}\left(\Gamma ; C_{0} / C_{2}\right) \rightarrow H^{0}\left(\Gamma ; C_{-1} / C_{2}\right) \rightarrow H^{0}\left(\Gamma ; C_{-1} / C_{0}\right) \rightarrow H^{1}\left(\Gamma ; C_{0} / C_{2}\right) \\
& \rightarrow H^{1}\left(\Gamma ; C_{-1} / C_{2}\right) \rightarrow H^{1}\left(\Gamma ; C_{-1} / C_{0}\right) \rightarrow H^{2}\left(\Gamma ; C_{0} / C_{2}\right) \\
& \rightarrow H^{2}\left(\Gamma ; C_{-1} / C_{2}\right) \rightarrow H^{2}\left(\Gamma ; C_{-1} / C_{0}\right) \rightarrow \cdots .
\end{aligned}
$$

As $H^{0}\left(\Gamma ; C_{-1} / C_{0}\right)=0$ and $H^{2}\left(\Gamma ; C_{0} / C_{2}\right)=0$ we obtain the isomorphism:

$$
H^{0}\left(\Gamma ; C_{0} / C_{2}\right) \stackrel{\cong}{\rightarrow} H^{0}\left(\Gamma ; C_{-1} / C_{2}\right)
$$

and the short exact sequence

$$
\begin{equation*}
0 \rightarrow H^{1}\left(\Gamma ; C_{0} / C_{2}\right) \rightarrow H^{1}\left(\Gamma ; C_{-1} / C_{2}\right) \rightarrow H^{1}\left(\Gamma ; C_{-1} / C_{0}\right) \rightarrow 0 . \tag{16}
\end{equation*}
$$

In conclusion

$$
\left\{\begin{array}{l}
\operatorname{dim} H^{0}(\Gamma ; \mathfrak{g l}(n))=\operatorname{dim} H^{0}\left(\Gamma ; C_{-1} / C_{2}\right)=\operatorname{dim} H^{0}\left(\Gamma ; C_{0} / C_{2}\right)=1 \\
\operatorname{dim} H^{1}(\Gamma ; \mathfrak{g l}(n))=\operatorname{dim} H^{1}\left(\Gamma ; C_{-1} / C_{2}\right)=1+(n-1)=n
\end{array}\right.
$$

Now, equation (6) gives $\operatorname{dim} H^{0}(\Gamma ; \mathfrak{s l}(n))=0$, and $\operatorname{dim} H^{1}(\Gamma ; \mathfrak{s l}(n))=n-1$.

Remark 3.7. The cohomology groups $H^{0}\left(\Gamma ; C_{0} / C_{2}\right)$ and $H^{1}\left(\Gamma ; C_{0} / C_{2}\right)$ are generated by $I_{n}+C_{2}$ and $h I_{n}+C_{2}$ respectively where $I_{n}$ denotes the identity matrix. This follows since $\operatorname{Ker} \beta^{0}$, and $\operatorname{Ker} \beta^{1}$ are generated by $I_{n}+C_{1}$ and $h I_{n}+C_{1}$ respectively.

We call a cochain $c: \Gamma \rightarrow \mathfrak{g l}(n)$ traceless if $\operatorname{tr}(c(\gamma))=0$ for all $\gamma \in \Gamma$. Notice that a cochain is traceless if and only if it takes values in $\mathfrak{s l}(n) \subset \mathfrak{g l}(n)$. Every principal derivation $b: \Gamma \rightarrow \mathfrak{g l}(n)$ is traceless, and hence we can define traceless cohomology classes.

It is clear that each traceless cocycle $Z^{1}\left(\Gamma ; C_{-1}\right)$ represents a cohomology class in $H^{1}(\Gamma ; \mathfrak{s l}(n))$. Reciprocally, we have the following:

Corollary 3.8. Each element of $H^{1}(\Gamma ; \mathfrak{s l}(n))$ can be represented by a traceless cocycle in $Z^{1}\left(\Gamma ; C_{-1}\right)$. Moreover, two traceless cocycles in $Z^{1}\left(\Gamma ; C_{-1}\right)$ represent the same cohomology class in $H^{1}(\Gamma ; \mathfrak{s l}(n))$ if and only if their projections represent the same cohomology class in $H^{1}\left(\Gamma ; C_{-1} / C_{0}\right)$. In other words, the composition map:

$$
H^{1}(\Gamma ; \mathfrak{s l}(n)) \hookrightarrow H^{1}(\Gamma ; \mathfrak{g l}(n)) \cong H^{1}\left(\Gamma ; C_{-1}\right) \rightarrow H^{1}\left(\Gamma ; C_{-1} / C_{0}\right)
$$

is an isomorphism.
Proof. The first part follows easily since a principal derivation with values in $\mathfrak{g l}(n)$ is traceless, and since $H^{1}\left(\Gamma ; C_{-1}\right) \xrightarrow{\cong} H^{1}(\Gamma ; \mathfrak{g l}(n))$ is an isomorphism. More precisely, traceless cohomology classes in $H^{1}\left(\Gamma ; C_{-1}\right)$ correspond exactly to cohomology classes in $H^{1}(\Gamma ; \mathfrak{s l}(n)) \subset H^{1}(\Gamma ; \mathfrak{g l}(n))$. Also, each cochain $c: \Gamma \rightarrow C_{2}$ is traceless, and therefore traceless cohomology classes in $H^{1}\left(\Gamma ; C_{-1} / C_{2}\right)$ are defined. Next, notice that a traceless cohomology class in $H^{1}\left(\Gamma ; C_{-1}\right)$ projects onto a traceless cohomology class in $H^{*}\left(\Gamma ; C_{-1} / C_{2}\right)$. We consider the sequence (16)

$$
0 \rightarrow H^{1}\left(\Gamma ; C_{0} / C_{2}\right) \rightarrow H^{1}\left(\Gamma ; C_{-1} / C_{2}\right) \rightarrow H^{1}\left(\Gamma ; C_{-1} / C_{0}\right) \rightarrow 0 .
$$

If a cohomology class in $H^{1}\left(\Gamma ; C_{-1} / C_{2}\right)$ projects onto the trivial class in $H^{1}\left(\Gamma ; C_{-1} / C_{0}\right)$ then it is in the image of $H^{1}\left(\Gamma ; C_{0} / C_{2}\right) \rightarrow H^{1}\left(\Gamma ; C_{-1} / C_{2}\right)$. By Remark 3.7
$\operatorname{Im}\left(H^{1}\left(\Gamma ; C_{0} / C_{2}\right) \rightarrow H^{1}\left(\Gamma ; C_{-1} / C_{2}\right)\right)$ is generated by $h I_{n}+C_{2}$. It follows that the class is trivial or non-traceless. We obtain the following isomorphism:

$$
H^{1}(\Gamma ; \mathfrak{s l}(n))=H_{0}^{1}(\Gamma ; \mathfrak{g l}(n)) \cong H_{0}^{1}\left(\Gamma ; C_{-1}\right) \xrightarrow{\rightrightarrows} H_{0}^{1}\left(\Gamma ; C_{-1} / C_{2}\right) \xrightarrow{\cong} H^{1}\left(\Gamma ; C_{-1} / C_{0}\right) .
$$

Here $H_{0}^{1}($.$) denotes the traceless cohomology classes.$
Propositions 3.5 and 3.6 prove the first part of Theorem 3.3. The last part of Theorem 3.3 will be proved in the next subsection.

### 3.3. Irreducible $\mathrm{SL}(n)$ representations.

Proof of the last part of Theorem 3.3. In order to prove that there are irreducible deformations of $\rho_{D}^{(n)}$ we will make use of Burnsides matrix lemma stating that a representation $\rho: \Gamma \rightarrow \mathrm{GL}(n)$ is irreducible if and only if the image $\rho(\Gamma)$ generates the matrix algebra $M_{n}(\mathbb{C})$.

Let $\Gamma=\left\langle S_{1}, \ldots, S_{k} \mid W_{1}, \ldots, W_{k-1}\right\rangle$ be a presentation of the knot group $\Gamma$ such that $h\left(S_{i}\right)=1$ for all $1 \leq i \leq k$. Such a presentation of deficency one exists always (see Section 2 in [22]).

Recall that $\rho_{D}^{(n)}: \Gamma \rightarrow \mathrm{SL}(n)$ is a representation given by (5) and satisfying the conditions of Theorem 3.3:

$$
\rho_{D}^{(n)}(\gamma)=\left(\begin{array}{ccccc}
1 & u_{1}^{+}(\gamma) & z_{13}^{+}(\gamma) & \ldots & z_{1 n}^{+}(\gamma) \\
0 & 1 & u_{2}^{+}(\gamma) & \ddots & \vdots \\
\vdots & \ddots & \ddots & \ddots & z_{n-2, n}^{+}(\gamma) \\
\vdots & & \ddots & 1 & u_{n-1}^{+}(\gamma) \\
0 & \cdots & \cdots & 0 & 1
\end{array}\right) D\left(\lambda_{1}, \ldots, \lambda_{n}\right)^{h(\gamma)}
$$

Modulo conjugation of the representation $\rho_{D}^{(n)}$, we can assume that $u_{1}^{+}\left(S_{1}\right)=\ldots=$ $u_{n-1}^{+}\left(S_{1}\right)=0$ and that $z_{i j}^{+}\left(S_{1}\right)=0$ for $j-i \geq 2,1 \leq i<j \leq n$. This conjugation corresponds to adding principal derivations to the derivations $u_{i}^{+}, 1 \leq i \leq n-1$, and to the cochains $z_{i j}^{+} ; j-i \geq 2$. Thus we can suppose that $\rho_{D}^{(n)}\left(S_{1}\right)=D\left(\lambda_{1}, \ldots, \lambda_{n}\right)$.

Since the derivations $u_{i}^{+}$are not principal there exists for each $i, 1 \leq i \leq n-1$, a generator $S_{j_{i}}, j_{i} \in\{2, \ldots, k\}$ such that $u_{i}^{+}\left(S_{j_{i}}\right) \neq 0$. Now, for each $i, 1 \leq i \leq n-1$, we chose a non-principal derivation $u_{i}^{-} \in Z^{1}\left(\Gamma ; \mathbb{C}_{\lambda_{i+1} / \lambda_{i}}\right)$. By Corollary 3.8, there exists a cocycle $V_{n-1} \in Z^{1}(\Gamma ; \mathfrak{s l}(n))$ of the form:

$$
V_{n-1}=u_{1}^{-} E_{2}^{1}+u_{2}^{-} E_{3}^{2}+\ldots+u_{n-1}^{-} E_{n}^{n-1}+X
$$

where $X \in C^{1}\left(\Gamma, C_{0}\right)$. Up to adding principal derivations to the derivations $u_{i}^{-}$we may assume that $u_{i}^{-}\left(S_{1}\right)=0, \forall 1 \leq i \leq n-1$. By arguing as in the proof of Lemma 5.5 of [5] it can be proved that $u_{i}^{-}\left(S_{j_{i}}\right) \neq 0,1 \leq i \leq n-1$.

Let $\rho_{t}$ be a deformation of $\rho_{D}^{(n)}$ with leading term $V_{n-1}$ :

$$
\rho_{t}=\left(I_{n}+t V_{n-1}+o(t)\right) \rho_{D}^{(n)}, \text { where } \lim _{t \rightarrow 0} \frac{o(t)}{t}=0
$$

As the set of diagonal matrices with non vanishing pairwise different entries is Zariski open, we may suppose that for sufficiently small $t, \rho_{t}\left(S_{1}\right)=D\left(a_{1}(t), \ldots, a_{n}(t)\right)$ is such that $a_{i}(t) \neq 0$, and $a_{i}(t) \neq a_{j}(t)$ for $i \neq j$. Recall that the diagonal elements $\lambda_{i}$ are pairwise different. It follows that the matrix $E_{i}^{i}$ is a polynomial in $\rho_{t}\left(S_{1}\right)$. For if $\mathbb{C}\left[\rho_{t}\left(S_{1}\right)\right]$ denotes the algebra generated by $\rho_{t}\left(S_{1}\right)$ we have $\mathbb{C}\left[E_{1}^{1}, \ldots, E_{n}^{n}\right] \supset \mathbb{C}\left[\rho_{t}\left(S_{1}\right)\right]$, $\operatorname{dim} \mathbb{C}\left[\rho_{t}\left(S_{1}\right)\right]=n$, and hence $\mathbb{C}\left[E_{1}^{1}, \ldots, E_{n}^{n}\right]=\mathbb{C}\left[\rho_{t}\left(S_{1}\right)\right]$.

Let $\mathcal{A}_{t}$ denote the algebra generated by $\rho_{t}(\Gamma)$. Since $\rho_{t}\left(S_{1}\right) \in \mathcal{A}_{t}$ we have that $E_{i}^{i} \in \mathcal{A}_{t}$ for all $1 \leq i \leq n$. Hence if $B=\left(b_{i j}\right) \in \mathcal{A}_{t}$ then:

$$
E_{i}^{i} B E_{j}^{j}=b_{i j} E_{i}^{j} \in \mathcal{A}_{t} .
$$

We consider

$$
E_{i}^{i} \rho_{t}\left(S_{j_{i}}\right) E_{i+1}^{i+1}=\left(\lambda_{i+1} u_{i}^{+}\left(S_{j_{i}}\right)+o(1)\right) E_{i}^{i+1} .
$$

We have $\lambda_{i+1} u_{i}^{+}\left(S_{j_{i}}\right) \neq 0$, thus for $t$ sufficently small we have $E_{i}^{i+1} \in \mathcal{A}_{t}$.
Similarly,

$$
E_{i+1}^{i+1} \rho_{t}\left(S_{j_{i}}\right) E_{i}^{i}=\left(t \lambda_{i} u_{i}^{-}\left(S_{j_{i}}\right)+o(t)\right) E_{i+1}^{i}
$$

We have $\lambda_{i} u_{i}^{-}\left(S_{j_{i}}\right) \neq 0$ and hence for sufficiently small $t \neq 0$ we have $t\left(\lambda_{i} u_{i}^{-}\left(S_{j_{i}}\right)+\right.$ $o(t) / t) \neq 0$. Therefore $E_{i+1}^{i} \in \mathcal{A}_{t}$.

The following Lemma implies that $\mathcal{A}_{t}=M_{n}(\mathbb{C})$ and $\rho_{t}$ is irreducible.
Lemma 3.9. The $2(n-1)$ matrices $\left\{E_{i}^{j}| | i-j \mid=1\right\}$ generate the full matrix algebra $M_{n}(\mathbb{C})$.

Proof. Let $\mathcal{A}:=\mathbb{C}\left[E_{i}^{j}| | i-j \mid=1\right]$. We will proceed by induction on $1 \leq i \leq n$ to prove that all elementary matrices $E_{i}^{j}, 1 \leq j \leq n$, are in $\mathcal{A}$.

For the first step of the induction, a direct calculation gives:

$$
E_{1}^{1}=E_{1}^{2} E_{2}^{1}, \quad E_{1}^{3}=E_{1}^{2} E_{2}^{3}, \quad E_{1}^{4}=E_{1}^{3} E_{3}^{4}, \quad \cdots \quad, E_{1}^{n}=E_{1}^{n-1} E_{n-1}^{n} .
$$

Hence $E_{1}^{i} \in \mathcal{A}$ for $1 \leq i \leq n$.
Suppose now that the result is true for $1 \leq i<n$ and let prove that $E_{i+1}^{j} \in \mathcal{A}$ for $1 \leq j \leq n$.

Clearly $E_{i+1}^{i}, E_{i+1}^{i+2}, E_{i+1}^{i+1}=E_{i+1}^{i} E_{i}^{i+1} \in \mathcal{A}$. For $1 \leq j \leq n$ and $j \notin\{i, i+1, i+2\}$, we have $E_{i+1}^{j}=E_{i+1}^{i} E_{i}^{j} \in \mathcal{A}$ by the induction hypothesis. This ends the proof.

## 4. The diagonal representation

The aim of this section is to prove Theorem 1.2. Throughout this section we will assume that $\lambda_{i} / \lambda_{i+1}, i=1, \ldots, n-1$, is a simple root of the Alexander polynomial $\Delta_{K}(t)$, and that $\Delta_{K}\left(\lambda_{i} / \lambda_{j}\right) \neq 0$ if $|i-j| \geq 2$. Notice that, by the symmetry of $\Delta_{K}(t)$, the quotients $\lambda_{i+1} / \lambda_{i}$ are also simple roots of the Alexander polynomial (see the paragraph preceeding Proposition (2.3).

Let $D=D\left(\lambda_{1}, \ldots, \lambda_{n}\right) \in \mathrm{SL}(n)$ be the diagonal matrix with $\lambda_{i} \neq \lambda_{j}$ for $i \neq j$ and let $\rho_{D}$ be the abelian representation given by $\rho_{D}(\gamma)=D^{h(\gamma)}$.

Recall that the quadratic cone at a representation $\rho \in R_{n}(\Gamma)$, introduced by W. Goldman [14], is an obstruction to integrability:

$$
\begin{equation*}
T Q_{\rho}\left(R_{n}(\Gamma)\right)=\left\{U \in Z^{1}(\Gamma ; \operatorname{Ad} \rho) \mid[U \smile U] \sim 0\right\} \subset T_{\rho} R_{n}(\Gamma) \cong Z^{1}(\Gamma ; \operatorname{Ad} \rho) . \tag{17}
\end{equation*}
$$

We will calculate the quadratic cone at the abelian representation $\rho_{D}$. More precisely, first we will compute a basis of the Zariski tangent space $Z^{1}\left(\Gamma ; \mathfrak{s l}(n)_{\mathrm{Ad} \rho}\right)$ (see Section 4.1), then we will determine the ideal $I$ generated by the quadratic obstruction (17) (see Section(4.2). After that we will show that the ideal $I$ is radical (see Lemma 4.9), and that $I$ is in fact an intersection of prime ideals generated by linear forms (see Lemma 4.10). This guarantees that the quadratic cone is reduced. Finally, we will prove in Section 4.5 that every cocycle in the quadratic cone $T Q_{\rho_{D}}\left(R_{n}(\Gamma)\right)$ is integrable, and hence the quadric cone coincides with the tangent cone.
4.1. The Zariski tangent space at the diagonal representation. Observe that we have the following decomposition:

$$
\begin{equation*}
\mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}} \cong \bigoplus_{i \neq j} \mathbb{C}_{\lambda_{i} / \lambda_{j}} \oplus \mathbb{C}^{n-1} \tag{18}
\end{equation*}
$$

In what follows we fix the following non principal derivations:

$$
h \in Z^{1}(\Gamma ; \mathbb{C}), \quad u_{i}^{+} \in Z^{1}\left(\Gamma ; \mathbb{C}_{\lambda_{i} / \lambda_{i+1}}\right), \quad u_{i}^{-} \in Z^{1}\left(\Gamma ; \mathbb{C}_{\lambda_{i+1} / \lambda_{i}}\right),
$$

$i=1, \ldots, n-1$. Notice that $Z^{1}(\Gamma ; \mathbb{C})=H^{1}(\Gamma ; \mathbb{C})$ since $\mathbb{C}$ is a trivial $\Gamma$-module.
Recall that $E_{i}^{j}=E_{i} E_{j}^{\top}, 1 \leq i, j \leq n$, form the canonical basis of $M_{n}(\mathbb{C})$ and that $E_{i}^{j} E_{k}^{l}=\delta_{k}^{j} E_{i}^{l}$. Hence

$$
\begin{equation*}
\left[E_{i}^{j}, E_{k}^{l}\right]=\delta_{k}^{j} E_{i}^{l}-\delta_{i}^{l} E_{k}^{j} . \tag{19}
\end{equation*}
$$

In what follows we will consider the cohomology classes represented by the following cocycles:

$$
\begin{equation*}
H_{i}=h\left(E_{i}^{i}-E_{i+1}^{i+1}\right), \quad U_{i}^{+}=u_{i}^{+} E_{i}^{i+1}, \text { and } U_{i}^{-}=u_{i}^{-} E_{i+1}^{i} ; i \in\{1, \ldots, n-1\} . \tag{20}
\end{equation*}
$$

Lemma 4.1. The $3 n-3$ cohomology classes represented by $H_{i}, U_{i}^{+}$and $U_{i}^{-}, i \in$ $\{1, \ldots, n-1\}$, form a basis of $H^{1}\left(\Gamma ; \mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}}\right)$.

Roughly speaking, this means that the cohomology $H^{1}\left(\Gamma ; \mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}}\right)$ is concentrated around the diagonal, and

$$
\begin{align*}
\operatorname{dim} Z^{1}\left(\Gamma ; \mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}}\right) & =n^{2}+2 n-3, \\
\operatorname{dim} B^{1}\left(\Gamma ; \mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}}\right) & =n^{2}-n,  \tag{21}\\
\operatorname{dim} H^{1}\left(\Gamma ; \mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}}\right) & =3(n-1) .
\end{align*}
$$

Moreover, we have $\operatorname{dim} H^{0}\left(\Gamma ; \mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}}\right)=(n-1)$. As a consequence:

$$
\begin{equation*}
\operatorname{dim} H^{2}\left(\Gamma ; \mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}}\right)=2(n-1) . \tag{22}
\end{equation*}
$$

Lemma 4.2. For the representation $\rho_{D} \in R_{n}(\Gamma)$ we have an isomorphism

$$
T_{\rho_{D}} R_{n}(\Gamma)_{\text {red }} \xlongequal{\cong} Z^{1}\left(\Gamma ; \mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}}\right) .
$$

Proof. Every principal derivation is integrable, and the derivations (20) are seen to be integrable:

$$
\begin{equation*}
\rho_{t}^{\left(H_{i}\right)}(\gamma)=\exp \left(t H_{i}(\gamma)\right) \rho_{D}(\gamma), \quad \text { and } \quad \rho_{t}^{\left(U_{i}^{ \pm}\right)}(\gamma)=\exp \left(t U_{i}^{ \pm}(\gamma)\right) \rho_{D}(\gamma) \tag{23}
\end{equation*}
$$

This follows since diagonal matrices commute, and $\left(E_{i}^{i+1}\right)^{2}=\left(E_{i+1}^{i}\right)^{2}=0$.
Remark 4.3. The fact that the space of 1-cocycles $Z^{1}\left(\Gamma ; \mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}}\right)$ is isomorphic to the Zariski tangent space $T_{\rho_{D}} R_{n}(\Gamma)$ does not imply that the representation $\rho_{D}$ is scheme reduced. In order to prove this property for $\rho_{D}$, we will show in Theorem 4.13 that the tangent cone at $\rho_{D}$ is reduced and then apply Lemma 2.1.
4.2. The cup product of cocycles at the diagonal representation. In general, each cocycle $U \in Z^{1}\left(\Gamma ; \mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}}\right)$ has the form:

$$
\begin{equation*}
U=\sum_{i=1}^{n-1} x_{i} U_{i}^{+}+y_{i} U_{i}^{-}+z_{i} H_{i}+C \tag{24}
\end{equation*}
$$

where $C \in B^{1}\left(\Gamma ; \mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}}\right)$ is a principal derivation, and $x_{i}, y_{i}, z_{i} \in \mathbb{C}$.

Lemma 4.4. Let $H_{i}$, and $U_{i}^{ \pm}$be the cocycles defined in Equation (20). Then

$$
\left[H_{i} \smile H_{j}\right]=0, \quad\left[U_{i}^{ \pm} \smile U_{j}^{ \pm}\right] \sim 0, \text { and }\left[U_{i}^{\mp} \smile U_{j}^{ \pm}\right] \sim 0 .
$$

Proof. The first relation $\left[H_{i} \smile H_{j}\right]=0$ is obvious since diagonal matrices commute.
The next relations $\left[U_{i}^{ \pm} \smile U_{j}^{ \pm}\right] \sim 0$ (same sign), follow directly if $j \notin\{i+1, i-1\}$ as by (19):

$$
\left[E_{i}^{i+1}, E_{j}^{j+1}\right]=\delta_{j}^{i+1} E_{i}^{j+1}-\delta_{i}^{j+1} E_{j}^{i+1}= \begin{cases}0 & \text { if } j \notin\{i+1, i-1\} \\ E_{i}^{i+2} & \text { if } j=i+1 \\ -E_{i-1}^{i+1} & \text { if } j=i-1\end{cases}
$$

and $H^{2}\left(\Gamma ; \mathbb{C}_{\lambda_{i} / \lambda_{i+2}}\right)=0$ for $|i-j| \geq 2$.
If $j=i+1$ then $u_{i}^{+} \smile u_{i+1}^{+} \in Z^{2}\left(\Gamma ; \mathbb{C}_{\lambda_{i} / \lambda_{i+2}}\right)=B^{2}\left(\Gamma ; \mathbb{C}_{\lambda_{i} / \lambda_{i+2}}\right)$ since $\Delta_{K}\left(\lambda_{i} / \lambda_{j}\right) \neq 0$ if $|i-j| \geq 2$. The same argument applies for $j=i-1$. This proves $\left[U_{i}^{+} \smile U_{j}^{+}\right] \sim 0$. The proof of $\left[U_{i}^{-} \smile U_{j}^{-}\right] \sim 0$ is similar.

Now, consider $\left[U_{i}^{ \pm}, U_{j}^{\mp}\right]$ (opposite signs):

$$
\left[E_{i}^{i+1}, E_{j+1}^{j}\right]=\delta_{j+1}^{i+1} E_{i}^{j}-\delta_{i}^{j} E_{j+1}^{i+1}= \begin{cases}0 & \text { if } j \neq i \\ E_{i}^{i}-E_{i+1}^{i+1} & \text { if } j=i\end{cases}
$$

Hence $\left[U_{i}^{ \pm}, U_{j}^{\mp}\right]=0$ if $i \neq j$, and $\left[U_{i}^{ \pm}, U_{i}^{\mp}\right]=\left(u_{i}^{+} \smile u_{i}^{-}\right)\left(E_{i}^{i}-E_{i+1}^{i+1}\right)$. Now, $u_{i}^{+} \smile u_{i}^{-} \sim 0$ since $H^{2}(\Gamma ; \mathbb{C})=0$. This imples $\left[U_{i}^{ \pm}, U_{i}^{\mp}\right] \sim 0$.
Lemma 4.5. The $2(n-1)$ cocycles $\left[H_{i} \smile U_{i}^{ \pm}\right], i=1, \ldots, n-1$, represent a basis of $H^{2}\left(\Gamma ; \mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}}\right)$.
Proof. By (19) we obtain:

$$
\begin{aligned}
{\left[H_{i} \smile U_{i}^{+}\right]\left(\gamma_{1}, \gamma_{2}\right) } & =h\left(\gamma_{1}\right)\left(\frac{\lambda_{i}}{\lambda_{i+1}}\right)^{h\left(\gamma_{1}\right)} u_{i}^{+}\left(\gamma_{2}\right)\left[E_{i}^{i}-E_{i+1}^{i+1}, E_{i}^{i+1}\right] \\
& =2\left(h \smile u_{i}^{+}\right)\left(\gamma_{1}, \gamma_{2}\right) E_{i}^{i+1} .
\end{aligned}
$$

By a similar calculation we obtain $\left[H_{i} \smile U_{i}^{-}\right]=-2\left(h \smile u_{i}^{-}\right) E_{i+1}^{i}$. The lemma follows from the decomposition (18), Lemma 2.4, and equation (22).
Lemma 4.6. For the generators (20) of $H^{1}\left(\Gamma ; \mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}}\right)$, and $\epsilon \in\{ \pm\}$ we have:

$$
\left[H_{i} \smile U_{j}^{\epsilon}\right]= \begin{cases}0 & \text { if }|i-j|>1, \\ -\epsilon\left(h \smile u_{i-1}^{\epsilon}\right) E_{i-1}^{i} & \text { if } j=i-1, \\ 2 \epsilon\left(h \smile u_{i}^{\epsilon}\right) E_{i}^{i+1} & \text { if } j=i, \\ -\epsilon\left(h \smile u_{i+1}^{\epsilon}\right) E_{i+1}^{i+2} & \text { if } j=i+1 .\end{cases}
$$

Proof. Direct calculation using Equation 2,
We are now ready to calculate $[U \smile U]$.
Proposition 4.7. Let $U \in Z^{1}\left(\Gamma ; \mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}}\right)$ be a cocycle of the form:

$$
U=\sum_{i=1}^{n-1} x_{i} U_{i}^{+}+y_{i} U_{i}^{-}+z_{i} H_{i}+C
$$

where $C \in B^{1}\left(\Gamma ; \mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}}\right)$ is a principal derivation, and $x_{i}, y_{i}, z_{i} \in \mathbb{C}$.
Then $[U \smile U] \sim 0$ if and only if for all $i=1, \ldots, n-1$ :

$$
\begin{equation*}
\left(2 z_{i}-z_{i-1}-z_{i+1}\right) x_{i}=0 \quad \text { and } \quad\left(2 z_{i}-z_{i-1}-z_{i+1}\right) y_{i}=0 . \tag{25}
\end{equation*}
$$

Proof. It follows from Lemma 4.6 that $\left[H_{i} \smile U_{j}^{ \pm}\right] \sim 0$ if $|i-j|>1$. This and Lemma 4.4 give:

$$
\begin{aligned}
{[U \smile U] \sim } & \sum_{i=1}^{n-1} x_{i} z_{i-1}\left[H_{i-1} \smile U_{i}^{+}\right]+x_{i} z_{i}\left[H_{i} \smile U_{i}^{+}\right]+x_{i} z_{i+1}\left[H_{i+1} \smile U_{i}^{+}\right] \\
& +x_{i-1} z_{i}\left[H_{i} \smile U_{i-1}^{+}\right]+x_{i} z_{i}\left[H_{i} \smile U_{i}^{+}\right]+x_{i+1} z_{i}\left[H_{i+1} \smile U_{i+1}^{+}\right] \\
& +y_{i} z_{i-1}\left[H_{i-1} \smile U_{i}^{-}\right]+y_{i} z_{i}\left[H_{i} \smile U_{i}^{-}\right]+y_{i} z_{i+1}\left[H_{i+1} \smile U_{i}^{-}\right] \\
& +y_{i-1} z_{i}\left[H_{i} \smile U_{i-1}^{-}\right]+y_{i} z_{i}\left[H_{i} \smile U_{i}^{-}\right]+y_{i+1} z_{i}\left[H_{i+1} \smile U_{i+1}^{-}\right]
\end{aligned}
$$

Here we have put $x_{0}=y_{0}=z_{0}=x_{n}=y_{n}=z_{n}=0$. With this convention we obtain:

$$
\begin{equation*}
\frac{1}{2}[U \smile U] \sim \sum_{i=1}^{n-1}\left(2 z_{i}-z_{i-1}-z_{i+1}\right)\left(x_{i}\left[H_{i} \smile U_{i}^{+}\right]+y_{i}\left[H_{i} \smile U_{i}^{-}\right]\right) . \tag{26}
\end{equation*}
$$

Now, by Lemma 4.5, the $2(n-1)$ cocycles $\left[H_{i} \smile U_{i}^{ \pm}\right], i=1, \ldots, n-1$, represent a basis of $H^{2}\left(\Gamma ; \mathfrak{s l}(n)_{\operatorname{Ad} \rho_{D}}\right)$. This proves the proposition.
4.3. The ideal defining the quadratic cone. In what follows we will use the following proposition:

Proposition 4.8. Let $\Gamma$ be a finitely generated group and $\rho \in R_{n}(\Gamma)$ a representation. We fix a basis $\left(v_{1}, \ldots, v_{k}\right)$ of $T_{\rho} R_{n}(\Gamma) \cong Z^{1}(\Gamma, \operatorname{Ad} \rho)$, and we let $\left(x_{1}, \ldots, x_{k}\right)$ denote the coordinates with respect to this basis. Then the quadratic cone of $R_{n}(\Gamma)$ at $\rho$ is given by the equations

$$
\sum_{i, j=1}^{k} x_{i} x_{j}\left[v_{i} \smile v_{j}\right] \sim 0
$$

Proof. Following W. Goldman a cocycle $u \in Z^{1}(\Gamma, \operatorname{Ad} \rho)$ is a curve tangent of second order if and only if the 2 -cocycle (the cup-bracked) $[u \smile u] \sim 0$ is a coboundary. By Lemma 2.2 the curve tangents of second order coincide with the quadratic tangent cone.

Let $R$ denote the polynomial ring $R:=\mathbb{C}\left[x_{1}, \ldots, x_{n-1}, y_{1}, \ldots, y_{n-1}, z_{1}, \ldots, z_{n-1}\right]$. In what follows we are interested in the ideal:

$$
\begin{equation*}
I^{(2)}=\left(\left(2 z_{i}-z_{i-1}-z_{i+1}\right) x_{i},\left(2 z_{i}-z_{i-1}-z_{i+1}\right) y_{i} \mid i=1, \ldots, n-1\right) \tag{27}
\end{equation*}
$$

which is generated by the equations (25).
Lemma 4.9. The ideal $I^{(2)} \subset R$ is a radical ideal i.e. $I^{(2)}$ is its own radical.
Proof. Consider the linear transformation $f$ of $\mathbb{C}^{3(n-1)}$ given by:

$$
f\left(x_{i}\right)=x_{i}, \quad f\left(y_{i}\right)=y_{i}, \quad \text { and } \quad f\left(z_{i}\right)=-z_{i-1}+2 z_{i}-z_{i+1}
$$

where we have put $z_{0}=z_{n}=0$. The linear transformation $f$ extends to an algebra isomorphism of $R$ which maps the ideal $J$ :

$$
J=\left(x_{i} z_{i}, y_{i} z_{i} \mid i=1, \ldots, n-1\right) \subset R
$$

to $I^{(2)}$. Notice that the ideal $J$ is a monomial ideal i.e. $J$ is an ideal generated by monomials. Hence it follows from [17, Corollary 1.2.5] that $J$ is a radical ideal, and therefore $I^{(2)}$ also.

The fact that $I^{(2)}$ is a radical ideal implies that $I^{(2)}$ is the intersection of finitely many prime ideals. In order to describe these prime ideals we let $2^{n-1}$ denote the powerset of $\{1, \ldots, n-1\}$, and for $\iota \in 2^{n-1}$ we denote by $\iota^{c}:=\{1, \ldots, n-1\} \backslash \iota$ the complement of $\iota$. The size of $\iota \in 2^{n-1}$ will be denoted by $|\iota|$. We are interested in the ideals $I_{\iota}$, $\iota \in 2^{n-1}$, given by:

$$
I_{\iota}=\left(2 z_{i}-z_{i-1}-z_{i+1}, x_{j}, y_{j} \mid i \in \iota \text { and } j \in \iota^{c}\right) .
$$

Notice that $I_{\iota} \subset R$ is a prime ideal. In fact $I_{\iota}$ is generated by linear equations, and $R / I_{\iota}$ is isomorphic to a polynomial algebra. The scheme

$$
V_{\iota}:=\left(R / I_{\iota}, \operatorname{Spm}\left(R / I_{\iota}\right)\right) \subset \mathbb{A}^{3(n-1)}
$$

is an affine subspace of $\mathbb{A}^{3(n-1)}$ given by the equations

$$
\begin{cases}2 z_{i}-z_{i-1}-z_{i+1}=0 & \text { for } i \in \iota  \tag{28}\\ x_{j}=y_{j}=0 & \text { for } j \in \iota^{c} .\end{cases}
$$

Hence $V_{\iota}$ is a reduced scheme and

$$
\begin{equation*}
\operatorname{dim} V_{\iota}=3(n-1)-|\iota|-2\left|\iota^{c}\right|=3(n-1)-|\iota|-2((n-1)-|\iota|)=n-1+|\iota| \tag{29}
\end{equation*}
$$

Given a set $E \subset R$ we will denote its zero locus by $V(E) \subset \mathbb{A}^{3(n-1)}$.
Lemma 4.10. The radical ideal $I^{(2)}$ is the intersection of the prime ideals $I_{\iota}$ :

$$
I^{(2)}=\bigcap_{\iota \in 2^{n-1}} I_{\iota}
$$

Proof. Since $I^{(2)}$ and $\bigcap_{\iota \in 2^{n-1}} I_{\iota}$ are both radical ideals it will be sufficient to prove that

$$
V\left(I^{(2)}\right)=V\left(\bigcap_{\iota \in 2^{n-1}} I_{\iota}\right)=\bigcup_{\iota \in 2^{n-1}} V\left(I_{\iota}\right)
$$

If $S$ and $T$ are two finite sets of polynomials then $V(S) \cup V(T)=V(S T)$, where $S T$ denotes the set of all products of an element of $S$ by an element of $T$. Therefore, we obtain:

$$
V\left(\left(2 z_{i}-z_{i-1}-z_{i+1}\right) x_{i},\left(2 z_{i}-z_{i-1}-z_{i+1}\right) y_{i}\right)=V\left(x_{i}, y_{i}\right) \cup V\left(2 z_{i}-z_{i-1}-z_{i+1}\right) .
$$

Hence

$$
\begin{aligned}
V\left(I^{(2)}\right) & =\bigcap_{i=1}^{n-1}\left(V\left(x_{i}, y_{i}\right) \cup V\left(2 z_{i}-z_{i-1}-z_{i+1}\right)\right) \\
& =\bigcup_{\iota \in 2^{n-1}}\left(\left(\bigcap_{i \in \iota} V\left(2 z_{i}-z_{i-1}-z_{i+1}\right)\right) \cap\left(\bigcap_{j \in \iota^{c}} V\left(x_{j}, y_{j}\right)\right)\right) \\
& =\bigcup_{\iota \in 2^{n-1}} V\left(2 z_{i}-z_{i-1}-z_{i+1}, x_{j}, y_{j} \mid i \in \iota \text { and } j \in \iota^{c}\right) \\
& =\bigcup_{\iota \in 2^{n-1}} V\left(I_{\iota}\right)
\end{aligned}
$$

which proves the lemma.
4.4. The quadratic cone at the diagonal representation. In order to describe the quadratic cone at $\rho_{D}$ we choose the basis of $Z^{1}\left(\Gamma ; \operatorname{Ad} \rho_{D}\right)$ given by the non principal derivations $H_{i}, U_{i}^{ \pm}, i=1, \ldots, n-1$ from equation (20), and the $\left(n^{2}-n\right)$ principal derivations $B_{k}^{l}, 1 \leq k, l \leq n, k \neq l$, given by

$$
B_{k}^{l}(\gamma)=\left(\left(\lambda_{k} / \lambda_{l}\right)^{h(\gamma)}-1\right) E_{k}^{l}
$$

By means of this basis we obtain an identification $\mathbb{A}^{n^{2}+2 n-3} \cong Z^{1}\left(\Gamma ; \operatorname{Ad} \rho_{D}\right)$, and we let $\left(x_{i}, y_{i}, z_{i}, t_{k}^{l}\right), i=1, \ldots, n-1,1 \leq k, l \leq n, k \neq l$, denote the coordinates of $\mathbb{A}^{n^{2}+2 n-3}$.

In what follows we will identify $\mathbb{C}\left[x_{i}, y_{i}, z_{i}\right] \otimes \mathbb{C}\left[t_{k}^{l}\right]$ with $\mathbb{C}\left[x_{i}, y_{i}, z_{i}, t_{k}^{l}\right]$. This corresponds to the identification $\mathbb{A}^{3 n-3} \times \mathbb{A}^{n^{2}-n}=\mathbb{A}^{n^{2}+2 n-3}$ Moreover, we let $\widetilde{I}^{(2)}$ and $\widetilde{I}_{\iota}$ denote the ideals

$$
\widetilde{I}^{(2)}:=I^{(2)} \otimes \mathbb{C}\left[t_{k}^{l}\right] \subset \mathbb{C}\left[x_{i}, y_{i}, z_{i}, t_{k}^{l}\right] \quad \text { and } \quad \widetilde{I}_{\iota}:=I_{\iota} \otimes \mathbb{C}\left[t_{k}^{l}\right] \subset \mathbb{C}\left[x_{i}, y_{i}, z_{i}, t_{k}^{l}\right]
$$

respectively. We will write $\widetilde{V}_{\iota}:=V\left(\widetilde{I}_{\iota}\right) \subset \mathbb{A}^{n^{2}+2 n-3}$ for short.
Proposition 4.11. The quadratic cone $T Q_{\rho_{D}} R_{n}(\Gamma) \subset T_{\rho_{D}} R_{n}(\Gamma)$ is a union of affine subspaces, and under the identification $T_{\rho_{D}} R_{n}(\Gamma) \cong Z^{1}\left(\Gamma ; \operatorname{Ad} \rho_{D}\right) \cong \mathbb{A}^{n^{2}+2 n-3}$, we obtain:

$$
T Q_{\rho_{D}} R_{n}(\Gamma)=V\left(\widetilde{I}^{(2)}\right)=\bigcup_{\iota \in 2^{n-1}} \widetilde{V}_{\iota}
$$

In particular, as the ideal $\widetilde{I}^{(2)}$ is radical, the quadratic cone $T Q_{\rho_{D}} R_{n}(\Gamma)$ is reduced.
Proof. First we will show that if an ideal $I \subset \mathbb{C}\left[x_{i}, y_{i}, z_{i}\right]$ is radical, then $I \otimes \mathbb{C}\left[t_{k}^{l}\right] \subset$ $\mathbb{C}\left[x_{i}, y_{i}, z_{i}\right] \otimes \mathbb{C}\left[t_{k}^{l}\right]$ is also radical. To this end, notice that for any ideal $I \subset \mathbb{C}\left[x_{i}, y_{i}, z_{i}\right]$ we have

$$
\left(\mathbb{C}\left[x_{i}, y_{i}, z_{i}\right] \otimes \mathbb{C}\left[t_{k}^{l}\right]\right) /\left(I \otimes \mathbb{C}\left[t_{k}^{l}\right]\right) \cong\left(\mathbb{C}\left[x_{i}, y_{i}, z_{i}\right] / I\right) \otimes \mathbb{C}\left[t_{k}^{l}\right] .
$$

Moreover, the tensor product of two reduced $\mathbb{C}$-algebras is reduced [6, V, $\S 15$, Thm 3]. This implies that if $I \subset \mathbb{C}\left[x_{i}, y_{i}, z_{i}\right]$ is radical, then $I \otimes \mathbb{C}\left[t_{k}^{l}\right] \subset \mathbb{C}\left[x_{i}, y_{i}, z_{i}\right] \otimes \mathbb{C}\left[t_{k}^{l}\right]$ is also radical. Consequently the ideals $\widetilde{I}_{\iota}$ are radical, and

$$
\widetilde{V}_{\iota}=V\left(\widetilde{I}_{\iota}\right)=V\left(I_{\iota}\right) \times \mathbb{A}^{n^{2}-n} \subset \mathbb{A}^{3 n-3} \times \mathbb{A}^{n^{2}-n}=\mathbb{A}^{n^{2}+2 n-3}
$$

is an affine subspace.
For two closed subschemes $X_{k}=\left(R / I_{k}, \operatorname{Spm}\left(R / I_{k}\right)\right), k=1,2$, of $\mathbb{A}^{N}$ their union is defined by:

$$
X_{1} \cup X_{2}=\left(R /\left(I_{1} \cap I_{2}\right), \operatorname{Spm}\left(R /\left(I_{1} \cap I_{2}\right)\right)\right)
$$

(see [24, Section I.§4] and [13, Section I.2.1]). As the intersection of radical ideals is radical, the assertion follows from Lemma 4.10.

In what follows, given an element $\iota \in 2^{n-1}$, we will identify the linear subspace of $Z^{1}\left(\Gamma ; \operatorname{Ad} \rho_{D}\right)$ defined by the radical ideal $\widetilde{I}_{\iota}$ with the affine subspace $\widetilde{V}_{\iota}$. Notice that by equation (29) we have:

$$
\operatorname{dim} \widetilde{V}_{\iota}=n^{2}-n+(n-1+|\iota|)=n^{2}-1+|\iota| .
$$

Therefore, there is exactly one component $\widetilde{V}_{\emptyset}$ of dimension $n^{2}-1$ and exactly one component $\widetilde{V}_{\{1, \ldots, n-1\}}$ of dimension $n^{2}+n-2$. These components are of minimal, respectively, maximal dimension. If $n=2$ then there are no other components, but for $n>2$ there are.

We can easily idendify the component of minimal dimension $n^{2}-1$ : the surjection $h: \Gamma \rightarrow \mathbb{Z}$ induces a closed immersion (see Proposition 1.7 of [25]) $h^{*}: R_{n}(\mathbb{Z}) \hookrightarrow R_{n}(\Gamma)$. Its image $h^{*}\left(R_{n}(\mathbb{Z})\right)$ is the subvariety of abelian representations of $\Gamma$ and will be denoted
by $R_{a b}$. Notice that $R_{a b} \cong \mathrm{SL}(n)$ is an irreducible ( $n^{2}-1$ )-dimensional component of $R_{n}(\Gamma)$.

Proposition 4.12. Let $\widetilde{V}_{\{1, \ldots, n-1\}}$ and $\widetilde{V}_{\emptyset}$ be the components of extreme dimension in the quadratic cone $T Q_{\rho_{D}} R_{n}(\Gamma)$. Then

$$
T_{\rho_{D}} R_{D}^{(n)}=\widetilde{V}_{\{1, \ldots, n-1\}} \quad \text { and } \quad T_{\rho_{D}} R_{a b}=\widetilde{V}_{\emptyset} .
$$

Therefore, $\rho_{D}$ is a smooth point of each of the two components $R_{D}^{(n)}$ and $R_{a b}$ which intersect transversely at the orbit of $\rho_{D}$.
Proof. The irreducible algebraic component $R_{a b}$ has dimension $n^{2}-1$, and is isomorphic to $\mathrm{SL}(n)$. Hence $\rho_{D} \in R_{a b}$ is a smooth point. A tangent vector in $T_{\rho_{D}} R_{a b}$ is a linear combination of $\left\{H_{1}, \ldots, H_{n-1}\right\}$ and $\left\{B_{k}^{l}\right\}$ therefore $T_{\rho_{D}} R_{a b}$ corresponds to a subspace of $\widetilde{V}_{\emptyset}$. Now, $T_{\rho_{D}} R_{a b}=\widetilde{V}_{\emptyset}$ follows since

$$
\operatorname{dim} \widetilde{V}_{\emptyset}=n^{2}-1=\operatorname{dim} T_{\rho_{D}} R_{a b} .
$$

By Lemma 3.1, the representation $\rho_{D}$ is contained in the closure of the orbit of $\rho_{D}^{(n)}$ and hence is contained in the component $R_{D}^{(n)}$ of maximal dimension $n^{2}+n-2$.

The tangent cone $T C_{\rho_{D}} R_{D}^{(n)}$ has only components of dimension $\left(n^{2}+n-2\right)$, and is contained in the quadratic cone $T Q_{\rho_{D}} R_{D}^{(n)}$. On the other hand, $T Q_{\rho_{D}} R_{D}^{(n)}$ is contained in $T Q_{\rho_{D}} R_{n}(\Gamma)$, and therefore $T C_{\rho_{D}} R_{D}^{(n)}$ is contained in $\widetilde{V}_{\{1, \ldots, n-1\}}$ since this is the unique ( $n^{2}+n-2$ )-dimensional component of maximal dimension of $T Q_{\rho_{D}} R_{n}(\Gamma)$ (see Lemma 4.11). Hence $T C_{\rho_{D}} R_{D}^{(n)}=\widetilde{V}_{\{1, \ldots, n-1\}}$ is a linear subspace. This implies that the tangent space $T_{\rho_{D}} R_{D}^{(n)}$ coincides with the tangent cone $T C_{\rho_{D}} R_{D}^{(n)}$, and $\rho_{D} \in R_{D}^{(n)}$ is a smooth point. Finally, for $\widetilde{V}_{\emptyset}$ and $\widetilde{V}_{\{1, \ldots, n-1\}}$ we have

$$
\begin{aligned}
\operatorname{dim}\left(\widetilde{V}_{\{1, \ldots, n-1\}}+\widetilde{V}_{\emptyset}\right) & =\operatorname{dim}\left(\widetilde{V}_{\{1, \ldots, n-1\}}\right)+\operatorname{dim}\left(\widetilde{V}_{\emptyset}\right)-\operatorname{dim} B^{1}(\Gamma, \operatorname{Ad} \rho) \\
& =n^{2}+n-2+n^{2}-1-\left(n^{2}-n\right) \\
& =n^{2}+2 n-3=\operatorname{dim} T_{\rho_{D}} R_{n}(\Gamma)
\end{aligned}
$$

4.5. The tangent cone at the diagonal representation. In this section, we will prove that every cocycle in the quadratic cone at $\rho_{D}$ is an integrable cocycle. More precisely, we construct an arc of representations with endpoint $\rho_{D}$ and tangent to a given cocycle in the quadratic cone.
Theorem 4.13. Every component $\widetilde{V}_{\iota}$ is contained in the tangent cone $T C_{\rho_{D}} R_{n}(\Gamma)$. Therefore, the tangent cone $T C_{\rho_{D}} R_{n}(\Gamma)$ and quadratic cone $T Q_{\rho_{D}} R_{n}(\Gamma)$ coincide. Hence the tangent cone $T C_{\rho_{D}} R_{n}(\Gamma)$ is reduced, and consequently the diagonal representation $\rho_{D}$ is a reduced point of the representation variety.

In what follows we let $A \oplus B$ denote the direct sum of the matrices $A$ and $B$ :

$$
A \oplus B=\left(\begin{array}{c|c}
A & \mathbf{0} \\
\hline \mathbf{0} & B
\end{array}\right) .
$$

The case $n=3$. Before treating the general case, we shall consider the case $n=3$ i.e. $D=\operatorname{diag}\left(\lambda_{1}, \lambda_{2}, \lambda_{3}\right)$.

As in Theorem 3.3 we suppose that $\lambda_{1} / \lambda_{2}$ and $\lambda_{2} / \lambda_{3}$ are simple roots of the Alexander polynomial $\Delta_{K}(t)$, and that $\lambda_{1} / \lambda_{3}$ is not a root of $\Delta_{K}(t)$. By Proposition 4.11 the quadratic cone $T Q_{D} R_{3}(\Gamma)$ has four components $\widetilde{V}_{\emptyset}, \widetilde{V}_{\{1\}}, \widetilde{V}_{\{2\}}$ and $\widetilde{V}_{\{1,2\}}$. Let us consider these components :
$\widetilde{V}_{\emptyset}:$ : The component $\widetilde{V}_{\emptyset}$ is 8 -dimensional. Up to principal derivations the vector space $\widetilde{V}_{\emptyset}$ is generated by the two cocycles $H_{1}=h\left(E_{1}^{1}-E_{2}^{2}\right)$ and $H_{2}=h\left(E_{2}^{2}-E_{3}^{3}\right)$. Each linear combination of these cocycles is integrable and

$$
\rho_{t}^{\left(c_{1} H_{1}+c_{2} H_{2}\right)}(\gamma)=\exp \left(t\left(c_{1} H_{1}+c_{2} H_{2}\right)(\gamma)\right) \rho_{D}(\gamma)
$$

is clearly an arc of representations as diagonal matrices commute.
$\widetilde{V}_{\{1,2\}}:$ : This component is a 10 -dimensional vector space. Up to principal derivations it is generated by the four cocycles $U_{k}^{ \pm}$for $k=1,2$. By Proposition 4.12 the representation $\rho_{D}$ is a smooth point of the component $R_{D}^{(3)}$, and $\widetilde{V}_{\{1,2\}}$ is the tangent space $T_{\rho_{D}} R_{D}^{(3)}$. Hence every vector in $\widetilde{V}_{\{1,2\}}$ is integrable.
$\widetilde{V}_{\{1\}}:$ : This component is a 9-dimensional vector space which is generated, up to coboundaries, by the three cocycles $H:=H_{1}+2 H_{2}=\left(\begin{array}{ccc}h & 0 & 0 \\ 0 & h & 0 \\ 0 & 0 & -2 h\end{array}\right)$ and by $U_{1}^{ \pm}$. In order to show that every cocycle in $\widetilde{V}_{\{1\}}$ is integrable we have to show that the linear combination

$$
c H+d^{+} U_{1}^{+}+d^{-} U_{1}^{-}=\left(\begin{array}{ccc}
c h & d^{+} u_{1}^{+} & 0 \\
d^{-} u_{1}^{-} & c h & 0 \\
0 & 0 & -c 2 h
\end{array}\right), c, d^{+}, d^{-} \in \mathbb{C},
$$

is integrable. We will see that the cocycle

$$
U=\left(\begin{array}{ccc}
0 & d^{+} u_{1}^{+} & 0 \\
d^{-} u_{1}^{-} & 0 & 0 \\
0 & 0 & 0
\end{array}\right)
$$

is integrable in a specific way. To this end, we choose a complex number $z_{1}$ such that $z_{1}^{2}=\lambda_{1} \lambda_{2}$, and we consider the decomposition of the matrix $D=z_{1} D_{1} \oplus z_{2} D_{2}$ where $D_{1}=\operatorname{diga}\left(\lambda_{1} / z_{1}, \lambda_{2} / z_{1}\right) \in \operatorname{SL}(2), z_{2}=\lambda_{3}$, and $D_{2}=(1) \in \operatorname{SL}(1)$. Now, $\rho_{D_{1}}: \Gamma \rightarrow \mathrm{SL}(2)$ is a representation which verifies the hypothesis of Theorem 1.1, and the cocycle $U_{1}:=\left(\begin{array}{cc}0 & d^{+} u_{1}^{+} \\ d^{-} u_{1}^{-} & 0\end{array}\right)$ is integrable i.e. there exist an analytic path of representations $\rho_{t}^{\left(U_{1}\right)}: \Gamma \rightarrow \operatorname{SL}(2)$ such that $\rho_{0}^{\left(U_{1}\right)}=\rho_{D_{1}}$, and

$$
\left.\frac{d}{d t} \rho_{t}^{\left(U_{1}\right)}(\gamma)\right|_{t=0} \rho_{D_{1}}(\gamma)^{-1}=U_{1}(\gamma)=\left(\begin{array}{cc}
0 & d^{+} u_{1}^{+}(\gamma) \\
d^{-} u_{1}^{-}(\gamma) & 0
\end{array}\right)
$$

for all $\gamma \in \Gamma$. Finally we define a path of representations $\rho_{t}^{(c H+U)}: \Gamma \rightarrow \mathrm{SL}(3)$ by

$$
\rho_{t}^{(c H+U)}(\gamma)=\exp (t c H(\gamma))\left(z_{1}^{h(\gamma)} \rho_{t}^{(2)}(\gamma) \oplus z_{2}^{h(\gamma)}\right)
$$

Notice that $\rho_{t}^{(c H+U)}$ is a representation since the block matrices commute. Moreover,
$\rho_{0}^{(c H+U)}(\gamma)=I_{3}\left(z_{1}^{h(\gamma)} \rho_{D_{1}}(\gamma) \oplus z_{2}^{h(\gamma)}\right)=\left(\begin{array}{ccc}z_{1}\left(\begin{array}{cc}\lambda_{1} / z_{1} & 0 \\ 0 & \lambda_{2} / z_{1}\end{array}\right) & 0 \\ 0 & 0 & z_{2}\end{array}\right)^{h(\gamma)}=\rho_{D}(\gamma)$,
and

$$
\left.\frac{d}{d t} \rho_{t}^{(c H+U)}(\gamma)\right|_{t=0} \rho_{D}(\gamma)^{-1}=\left(c H(\gamma)+\left(U_{1}(\gamma) \oplus 0\right)\right)=(c H+U)(\gamma) .
$$

$\widetilde{V}_{\{2\}}:$ This case is similar to the previous case.

The general case. In order to describe the general case we need some notations. First we describe the cocycles in $\widetilde{V}_{\iota}$ for a proper subset $\iota \in 2^{n-1}, \iota \neq \emptyset$. For such $\iota$ we let denote $\iota^{c}=\left\{j_{1}, \ldots, j_{l}\right\} \subset\{1, \ldots, n-1\}$ where $0=j_{0}<j_{1}<j_{2}<\cdots<j_{l}<j_{l+1}=n$, and we define $n_{s}:=j_{s}-j_{s-1}, s=1, \ldots, l+1$. Notice that $\sum_{s=1}^{l+1} n_{s}=n$.

Now, equations (28) give that for each $i \in \iota$ we have $U_{i}^{ \pm} \in \widetilde{V}_{\iota}$, and for $s=1, \ldots, l$ we have $F_{n_{s}} \in \widetilde{V}_{\iota}$ where $F_{n_{s}}$ denotes the diagonal matrix

$$
F_{n_{s}}=\operatorname{diag}(\underbrace{0, \ldots, 0}_{n_{1}+\cdots+n_{s-1}}, \underbrace{n_{l+1} h}_{n_{s}}, \underbrace{0, \ldots, 0}_{n_{s+1}+\cdots+n_{l}}, \underbrace{-n_{s} h}_{n_{l+1}}) .
$$

Therefore,

$$
\widetilde{V}_{\iota}=\left\langle U_{i}^{ \pm}, F_{n_{s}} \mid i \in \iota, s=1, \ldots, l\right\rangle \oplus B^{1}\left(\Gamma ; \operatorname{Ad} \rho_{D}\right) .
$$

Notice that we have for all $U_{i}^{ \pm}$with $i \in \iota$ and all $F_{n_{s}}$ that $F_{n_{s}}(\gamma)$ and $U_{i}^{ \pm}(\gamma)$ commute for all $\gamma \in \Gamma$. Then a cocycle $U \in \widetilde{V}_{\iota}$ can be written as a linear combination of the diagonal matrices $F_{n_{s}}$, and block matrices:

$$
\left(\begin{array}{ccc}
U_{n_{1}} & &  \tag{30}\\
0 & \ddots & 0 \\
& & U_{n_{l+1}}
\end{array}\right)=\bigoplus_{s=1}^{l+1} U_{n_{s}}
$$

where for all $1 \leq s \leq l+1$ :

$$
U_{n_{s}}=\left(\begin{array}{ccccc}
0 & u_{j_{s-1}+1}^{+} & 0 & \cdots & 0 \\
u_{j_{s-1}+1}^{-} & 0 & u_{j_{s-1}+2}^{+} & \ddots & \vdots \\
0 & u_{j_{s-1}+2}^{-} & \ddots & \ddots & 0 \\
\vdots & \ddots & \ddots & \ddots & u_{j_{s}-1}^{+} \\
0 & \cdots & 0 & u_{j_{s}-1}^{-} & 0
\end{array}\right)
$$

Here, $u_{k}^{+} \in Z^{1}\left(\Gamma, \mathbb{C}_{\lambda_{k} / \lambda_{k+1}}\right)$ and $u_{k}^{-} \in Z^{1}\left(\Gamma, \mathbb{C}_{\lambda_{k+1} / \lambda_{k}}\right)$ where $j_{s-1}+1 \leq k \leq j_{s}-1$.
Proof ot Theorem 4.13. First we notice that every diagonal cocycle is integrable, and for $F=\sum_{s=1}^{l} c_{s} F_{s} \in V_{\iota}$ we define

$$
\rho_{t}^{(F)}(\gamma)=\exp (t F(\gamma)) .
$$

For the non diagonal cocycles we proceed as in Example 4.5, Let $U \in \widetilde{V}_{\iota}$ be a given cocycle. We will use the decomposition (30)

$$
U=\bigoplus_{s=1}^{l+1} U_{n_{s}},
$$

we split up a diagonal matrix $D=D\left(\lambda_{1}, \ldots \lambda_{n}\right) \in \operatorname{SL}(n)$ accordingly as $D=\tilde{D}_{1} \oplus \cdots \oplus$ $\tilde{D}_{l+1}$, where $\tilde{D}_{s}=D\left(\lambda_{j_{s-1}+1}, \ldots, \lambda_{j_{s}}\right)$ is build from $n_{s}$ consecutive diagonal entries of $D$. We choose $z_{s} \in \mathbb{C}^{*}$ such that $z_{s}^{n_{s}}=\operatorname{det}\left(\tilde{D}_{s}\right)$, and we define $D_{s}:=z_{s}^{-1} \tilde{D}_{s} \in \operatorname{SL}\left(n_{s}\right)$. We obtain

$$
D=z_{1} D_{1} \oplus \cdots \oplus z_{l+1} D_{l+1} .
$$

Now, $\rho_{D_{s}}$ verifies the hypotheses of Lemma 3.1 and Theorem 3.3, and therefore there is a ( $n_{s}^{2}+n_{s}-2$ )-dimensional irreducible component $R_{D_{s}}^{\left(n_{s}\right)} \subset R_{n_{s}}(\Gamma)$. By Lemma 4.2 we have

$$
T_{\rho_{D_{s}}} R_{D_{s}}^{\left(n_{s}\right)}=\left\langle u_{j_{s-1}+1}^{ \pm}, \ldots, u_{25}^{ \pm}\right\rangle \oplus B^{1}\left(\Gamma ; \operatorname{Ad} \rho_{D_{s}-1}\right) .
$$

Notice that in the case $n_{s}=1$ we have $D_{s}=(1) \in \operatorname{SL}(1)=\{(1)\}$ is the trivial group and $R_{D_{s}}^{(1)}$ is zero-dimensional and contains only the trivial representation.

We define representations $\rho_{t}^{(U)}: \Gamma \rightarrow \mathrm{SL}(n)$ by

$$
\rho_{t}^{(U)}(\gamma)=\bigoplus_{s=1}^{l+1} z_{s}^{h(\gamma)} \rho_{t}^{\left(U_{s}\right)}(\gamma)
$$

where $\rho_{t}^{\left(U_{s}\right)}: \Gamma \rightarrow \mathrm{SL}\left(n_{s}\right)$ is a family such that

$$
\left.\frac{d}{d t} \rho_{t}^{\left(U_{s}\right)}(\gamma)\right|_{t=0} \cdot \rho_{D_{n_{s}}}(\gamma)^{-1}=U_{s}(\gamma)
$$

Notice that $\rho_{0}^{(U)}=\rho_{D}$, and it follows directly that

$$
\left.\frac{d}{d t} \rho_{t}^{(U)}(\gamma)\right|_{t=0} \cdot \rho_{D}(\gamma)^{-1}=U(\gamma)
$$

Finally notice that the matrices $\rho_{t}^{(U)}(\gamma)$ and $\rho_{t}(F)(\gamma)$ commute for all $F$ and $U$ in $\widetilde{V}_{\iota}$. Therefore, $\rho_{t}^{(F+U)}: \Gamma \rightarrow \mathrm{SL}(n)$ given by

$$
\rho_{t}^{(F+U)}(\gamma)=\rho_{t}^{(F)}(\gamma) \cdot \rho_{t}^{(U)}(\gamma)
$$

is a path of representation, and its derivative in $t=0$ gives the cocyle $F+U \in \widetilde{V}_{\iota}$.
The last assertion is an immediate consequence of Proposition 4.11] and Lemma 2.1.
Remark 4.14. For each $k, 0 \leq k \leq n-1$, there is at least one irreducible algebraic component of $R_{n}(\Gamma)$ of dimension $n^{2}-1+k$ which contain $\rho_{D}$. So there are at least $n$ irreducible components of $R_{n}(\Gamma)$ which contain $\rho_{D}$. An example is the torus knot $T(3,2)$, and $n=3$. The representation variety $R_{3}\left(\Gamma_{3,2}\right)$ has exactly three algebraic components (see [29, Theorem 1.1]). All the components contain the diagonal representation $\rho_{D}$ where $D=\operatorname{diag}(\exp (\pi / 3), 1, \exp (-\pi / 3))$ (see Section 6.3).

On the other hand, there are at most $\binom{n-1}{k}$ components of dimension $n^{2}-1+k$ which contain $\rho_{D}$. Hence there are at most $2^{n-1}$ components through $\rho_{D}$. An example is given by the torus knot $T(3,4)$, and $n=3$. The representation variety $R_{3}\left(\Gamma_{3,4}\right)$ has exactly two algebraic components of dimension 9 [29, Theorem 1.1]. With help of [29, Proposition 9.1] it is possible to prove that the diagonal representation of $\Gamma_{3,4}$ which maps the meridian to $D=\operatorname{diag}\left(\xi^{4}, \xi, \xi^{-5}\right)$ for $\xi=\exp (i \pi / 18)$ is contained in both components. Moreover, the representation $\rho_{D}$ verifies the hypothesis of Theorem 3.3, and therefore $\rho_{D}$ is contained in 4 components. (See the discussion in Section 6.2.)

## 5. Local structure of the character variety

Our aim in this section is to study the local structure of the character variety in a neighborhood of the abelian character $\chi_{D}$. Most results in the literature concern the characters of irreducible representations. Very little is known in the case where the character corresponds to that of an abelian representation.
We will make use of the Luna's Étale Slice Theorem which is a tool for the local study of the character variety $X_{n}(\Gamma)$.

The general references for this section are [26], [12], [7], [32, [25].
5.1. A slice étale. Let $G$ be a reductive algebraic group acting on an affine variety $X$ and let $X / / G$ be the quotient variety.

The following result is of independant importance and it appears implicitely in [32].
Theorem 5.1. Let $G$ be a reductive algebraic group acting on an affine variety $X$. Let $x \in X$ be such that the orbit $G(x)$ is closed in $X$.

Then there exist a locally closed subvariety $\mathcal{S}$ of $X$ such that:

$$
T_{x}^{Z a r} X \cong T_{x}^{Z a r}(G(x)) \oplus T_{x}^{Z a r} \mathcal{S} .
$$

Moreover, if $x$ is a smooth point of $X$ then

$$
T_{t(x)}^{Z a r}(X / / G) \cong T_{0}\left(T_{x}^{Z a r} \mathcal{S} / / G_{x}\right)
$$

where $t: X \rightarrow X / / G$ is the quotient morphism.
Proof. Since the orbit $G(x)$ is closed in $X$, by Luna's Étale Slice theorem, there exists a locally closed subvariety $\mathcal{S}$ of $X$ such that $\mathcal{S}$ is affine and contains $x, \mathcal{S}$ is $G_{x}$ invariant, the image of the $G$-morphism $\psi: G \times_{G_{x}} \mathcal{S} \rightarrow X$ induced by the action of $G$ on $X$ is a saturated open subset $U$ of $X$ and the restriction of $\psi: G \times{ }_{G_{x}} \mathcal{S} \rightarrow U$ is strongly étale.

Thus, we obtain the following isomorphisms:

$$
\begin{equation*}
T_{(e, x)}^{Z a r} \psi: T_{(e, x)}^{Z a r} G \times_{G_{x}} \mathcal{S} \stackrel{ }{\cong} T_{x}^{Z a r} U \cong T_{x}^{Z a r} X \tag{31}
\end{equation*}
$$

and
$T_{[(e, x)]}^{Z a r}(\psi / / G): T_{[(e, x)]}^{Z a r}\left(G \times_{G_{x}} \mathcal{S} / / G\right) \cong T_{[x]}^{Z a r}\left(S / / G_{x}\right) \xrightarrow{\cong} T_{[x]}^{Z a r}(U / / G)=T_{[x]}^{Z a r}(X / / G)$.
Moreover, as $x$ is a smooth point of $X$, and using Luna's Slice Theorem at smooth points, we obtain that $T_{x}^{Z a r} X=T_{x}^{Z a r}(G(x)) \oplus T_{x}^{Z a r} \mathcal{S}$ and there exists an étale $G_{x^{-}}$ invariant morphism $\phi: \mathcal{S} \rightarrow T_{x}^{Z a r} \mathcal{S}$ such that $\phi(x)=0, T_{x} \phi=I d$, the image of $\phi$ is a saturated open subset $W$ of $T_{x}^{Z a r} \mathcal{S}$ and the restriction of $\phi: \mathcal{S} \rightarrow W$ is a strongly étale $G_{x}$-morphism. As a consequence, we have the following isomorphism:

$$
\begin{equation*}
T_{[x]}^{Z a r}\left(\phi / / G_{x}\right): T_{[x]}^{Z a r}\left(S / / G_{x}\right) \xrightarrow{\cong} T_{0}\left(W / / G_{x}\right)=T_{0}\left(T_{x}^{Z a r} \mathcal{S} / / G_{x}\right) \tag{33}
\end{equation*}
$$

By combining the preceding isomorphisms (32) and (33), we obtain the desired isomorphism:

$$
T_{[x]}^{Z a r}(X / / G) \cong T_{0}\left(T_{x}^{Z a r} \mathcal{S} / / G_{x}\right)
$$

5.2. Tangent spaces to slices and cohomology. The reductive group $G=\operatorname{SL}(n)$ acts by conjugation on $R_{n}(\Gamma)$. More precisely, for $A \in \mathrm{SL}(n)$ and $\rho \in R_{n}(\Gamma)$ we define $(A \cdot \rho)(\gamma)=A \rho(\gamma) A^{-1}$ for all $\gamma \in \Gamma$. We will write $\rho \sim \rho^{\prime}$ if there exists $A \in \operatorname{SL}(n)$ such that $\rho^{\prime}=A \cdot \rho$, and we will call $\rho$ and $\rho^{\prime}$ equivalent. For $\rho \in R_{n}(\Gamma)$ we define its character $\chi_{\rho}: \Gamma \rightarrow \mathbb{C}$ by $\chi_{\rho}(\gamma)=\operatorname{tr}(\rho(\gamma))$. We have $\rho \sim \rho^{\prime} \Rightarrow \chi_{\rho}=\chi_{\rho^{\prime}}$. By [25, Theorem 1.28]), if $\rho$ and $\rho^{\prime}$ are semisimple, then $\rho \sim \rho^{\prime}$ if and only if $\chi_{\rho}=\chi_{\rho^{\prime}}$.

The algebraic quotient or GIT quotient for the action of $\operatorname{SL}(n)$ on $R_{n}(\Gamma)$ is called the character variety. This quotient will be denoted by $X_{n}(\Gamma)=R_{n}(\Gamma) / / \mathrm{SL}(n)$. The character variety is not necessary an irreducible affine algebraic set. Work of C. Procesi [31] implies that there exists a finite number of group elements $\left\{\gamma_{i} \mid 1 \leq i \leq M\right\} \subset \Gamma$ such
that the image of $t: \mathbb{R}_{n}(\Gamma) \rightarrow \mathbb{C}^{M}$ given by $t(\rho)=\left(\chi_{\rho}\left(\gamma_{1}\right), \ldots, \chi_{\rho}\left(\gamma_{M}\right)\right)$ can be identified with the affine algebraic set $X_{n}(\Gamma) \cong t\left(R_{n}(\Gamma)\right)$. This justifies the name character variety.

Let $t: R_{n}(\Gamma) \rightarrow X_{n}(\Gamma) ; \rho \mapsto \chi_{\rho}$ be the canonical projection. Then $t$ is a regular morphism and for all $\gamma \in \Gamma, I_{\gamma}: X_{n}(\Gamma) \rightarrow \mathbb{C} ; \chi_{\rho} \mapsto \chi_{\rho}(\gamma)=\operatorname{tr}(\rho(\gamma))$ is a regular morphism.

For $\rho \in R_{n}(\Gamma)$, denote the stabilizer of $\rho$ under the $G$-action by conjugation on $R_{n}(\Gamma)$ by $G_{\rho}$. It is the centralizer of $\rho(\Gamma)$ in $G$.

Proposition 5.2. Let $\rho$ be a representation in $R_{n}(\Gamma)$ such that the orbit $G(\rho)$ of $\rho$ is closed in $R_{n}(\Gamma)$.

Let $R_{\rho}$ be an affine subvariety of $R_{n}(\Gamma)$ which contains $\rho$ and which is invariant under the conjugation action of $G$. Let $\mathcal{S}$ be a slice of $R_{\rho}$ at $\rho$.

Then

$$
T_{\rho}^{Z a r} \mathcal{S} \cong T_{\rho}^{Z a r} R_{\rho} / T_{\rho}^{Z a r} G(\rho) \quad \text { and } \quad T_{[\rho]}^{Z a r}\left(R_{\rho} / / G\right) \cong T_{[\rho]}^{Z a r}\left(\mathcal{S} / / G_{\rho}\right)
$$

Moreover, if $\rho$ is a smooth point of $R_{\rho}$ then

$$
T_{[\rho]}^{Z a r}\left(R_{\rho} / / G\right) \cong T_{0}\left(T_{\rho}^{Z a r} \mathcal{S} / / G_{\rho}\right) .
$$

In particular, if $\rho$ is a reduced smooth point of $R_{n}(\Gamma)$ such that the orbit $G(\rho)$ of $\rho$ is closed in $R_{n}(\Gamma)$ then there exists a slice $\mathcal{S}$ of $R_{n}(\Gamma)$ at $\rho$ such that

$$
T_{\rho}^{Z a r} \mathcal{S} \cong H^{1}(\Gamma, \operatorname{Ad} \rho) \quad \text { and } \quad T_{[\rho]}^{Z a r} X_{n}(\Gamma) \cong T_{0}\left(H^{1}(\Gamma, \operatorname{Ad} \rho) / / G_{\rho}\right)
$$

The proof of this result is implicitely contained in [3] and [32]. But for the sake of completeness, we will reproduce it here.

Proof. We have just to prove the first isomorphism. All the other assertions are an immediate consequence of Theorem 5.1.

Let $\psi: G \times_{G_{\rho}} \mathcal{S} \rightarrow R_{\rho}$ be the $G$-morphism étale given by Luna's Theorem and $U:=$ $\operatorname{Im} \psi$. We denote by $\theta$ the isomorphism $G(\rho) \xrightarrow{\theta} G / G_{\rho} ; \theta\left(g \rho g^{-1}\right)=[g]$ for $g \in G$.

As the fibration $G \rightarrow G / G_{\rho}$ is locally trivial, the morphism $p: \quad G \times{ }_{\rho} \mathcal{S} \rightarrow G / G_{\rho}$; $[g, v] \mapsto[g]$ is also a locally trivial fibration with fiber $g \mathcal{S}$ in the étale topology (30]). Let $Z$ be an open set trivializing $G / G_{\rho}$; then there exists a morphism étale $\phi: Z \times \mathcal{S} \rightarrow$ $p^{-1}(Z) ;([g], \varphi) \mapsto[g, \varphi]$ such that $p \circ \phi=p r_{1}$ where $p r_{1}: Z \times \mathcal{S} \rightarrow \mathcal{S}$ is the projection on the first component.

Consider the following chain of morphisms:

$$
\begin{aligned}
T_{\rho}^{Z a r} \mathcal{S} \xrightarrow{j_{2}} T_{\rho}^{Z a r} G(\rho) \oplus T_{\rho}^{Z a r} \mathcal{S} \xrightarrow{d \oplus \oplus i d} & T_{[e]}^{Z a r} G / G_{\rho} \oplus T_{\rho}^{Z a r} \mathcal{S} \xrightarrow{d \phi} \\
& T_{[e, \rho]}^{Z a r}\left(G \times_{G_{\rho}} \mathcal{S}\right) \xrightarrow{d \psi} T_{\rho}^{Z a r} R_{\rho} \xrightarrow{q} T_{\rho}^{Z a r} R_{\rho} / T_{\rho}^{Z a r} G(\rho)
\end{aligned}
$$

where $j_{2}$ is the natural inclusion and $q$ is the canonical projection. As $p^{-1}(Z)$ is open in $G \times_{G_{\rho}} \mathcal{S}$ and $\phi, \psi$ étale, we obtain that $d \phi$ and $d \psi$ are isomorphisms. Moreover, it is easy to see that $d \psi \circ d \phi \circ(d \theta \oplus i d) \circ j_{2}=d i$ where $i: S \rightarrow R_{\rho}$ is the natural inclusion.

On the other hand, let $j_{1}: T_{\rho}^{Z a r} G(\rho) \rightarrow T_{\rho}^{Z a r} G(\rho) \oplus T_{\rho}^{Z a r} \mathcal{S}$ be the inclusion map; then $d \psi \circ d \phi \circ(d \theta \oplus i d) \circ j_{1}$ is the natural inclusion $T_{\rho}^{Z a r} G(\rho) \rightarrow T_{\rho}^{Z a r} R_{\rho}$. As a consequence, $\alpha=q \circ d i: T_{\rho}^{Z a r} S \rightarrow T_{\rho}^{Z a r} R_{\rho} / T_{\rho}^{Z a r} G(\rho)$ is an isomorphism and $s=d i \circ$ $\alpha^{-1}: T_{\rho}^{Z a r} R_{\rho} / T_{\rho}^{Z a r} G(\rho) \rightarrow T_{\rho}^{Z a r} R_{\rho}$ is a section for $q$. Thus $T_{\rho}^{Z a r} \mathcal{S} \cong T_{\rho}^{Z a r} R_{\rho} / T_{\rho}^{Z a r} G(\rho)$.
5.3. Local structure of the character variety. As the set $R_{n}^{i r r}(\Gamma)$ of irreducible representations in $R_{n}(\Gamma)$ is Zariski open, its image $X_{n}^{i r r}(\Gamma)=t\left(R^{i r r}(\Gamma)\right)$ is Zariki open in $X_{n}(\Gamma)$. Their Zariski closures in $R_{n}(\Gamma)$ and $X_{n}(\Gamma)$ will be denoted by $\overline{R_{n}^{i r r}(\Gamma)}$ and $\overline{X_{n}^{i r r}(\Gamma)}$.

For the proof of the next Proposition, we will make use of the following result which was proven in [Boyer-Zhang, Lemma 4.1] for the group $G=\operatorname{SL}(2)$ and which generalizes easily to the group $G=\operatorname{SL}(n)$.

Lemma 5.3. For any algebraic component $X_{0} \subset X_{n}(\Gamma)$ such that $\operatorname{dim} X_{0}>0$, there is an algebraic component $R_{0}$ of $t^{-1}\left(X_{0}\right)$ which satisfies $t\left(R_{0}\right)=X_{0}$.

If $X_{0}$ contains the character of an irreducible representation, then $R_{0}$ is invariant under conjugation, contains irreducible representations and is uniquely determined by $X_{0}$.
Proposition 5.4. Let $\chi_{D}$ be the character $\chi_{D}=\chi\left(\rho_{D}^{(n)}\right)=\chi\left(\rho_{D}\right)$. Denote by $X_{n}(\mathbb{Z}):=t\left(R_{n}(\mathbb{Z})\right)$ and $X_{D}^{(n)}:=t\left(R_{D}^{(n)}\right)$ the quotients of the components $R_{n}(\mathbb{Z})$ and $R_{D}^{(n)}$ respectively. Then
(1) The character $\chi_{D}$ is a smooth point of $\overline{X_{n}^{i r r}(\Gamma)}$.
(2) The character $\chi_{D}$ is a smooth point of each of the two $(n-1)$-dimensional components $X^{(n)}$ and $X_{n}(\mathbb{Z})$.
(3) The intersection of the two above components at $\chi_{D}$ is transverse, i.e.

$$
T_{\chi_{D}}^{Z a r} X_{n}(\mathbb{Z}) \cap T_{\chi_{D}}^{Z a r} X^{(n)}=\{0\} .
$$

Proof. (1) As the irreducible component $R_{D}^{(n)}$ contains irreducible representations (Theorem (1.1), $X^{(n)}:=t\left(R_{D}^{(n)}\right)$ is an irreducible component of $\overline{X_{n}^{i r r}(\Gamma)}$ and $\operatorname{dim} X^{(n)}=\operatorname{dim} R_{D}^{(n)}-\left(n^{2}-1\right)=n-1$ ([25).

To see that $X^{(n)}$ is the only component of $\overline{X_{n}^{i r r}(\Gamma)}$ to contain $\chi_{D}$, suppose that another does as well. Then there exists an irreducible component $X_{0} \subset \overline{X_{n}^{i r r}(\Gamma)}$ distinct from $X^{(n)}$ such that $\chi_{D} \in X_{0}$.

Let $R_{0} \subset R_{n}(\Gamma)$ be the unique algebraic component invariant under conjugation, which contains irreducible representations and such that $t\left(R_{0}\right)=X_{0}$ (Lemma 5.3). Evidently $R_{0} \neq R_{D}^{(n)}$. Let $\phi \in R_{0}$ such that $t(\phi)=\chi_{D}=t\left(\rho_{D}\right)$. As $R_{0}$ is invariant under conjugation and closed, we obtain $\overline{G(\phi)} \subset R_{0}$. By Lemma 1.26 of [25], $\overline{G(\phi)}$ contains a semisimple representation $\phi_{0}$. Thus $t\left(\phi_{0}\right)=t(\phi)=t\left(\rho_{D}\right)$. As $\phi_{0}$ and $\rho_{D}$ are semisimple, we conclude that $\phi_{0} \sim \rho_{D}$ and by the same $\rho_{D} \in R_{0}$. By our analysis of the tangent cone of $\rho_{D}, R_{D}^{(n)}$ is the only algebraic component of $R_{n}(\Gamma)$ containing irreducible representations and the representation $\rho_{D}$. We conclude that $R_{0}=R_{D}^{(n)}$ which contradicts our hypothesis.
(2) The orbit $G\left(\rho_{D}\right)$ is closed in $R_{n}(\Gamma)$ with $\operatorname{dim} G\left(\rho_{D}\right)=n^{2}-n$ and, as $D=\rho_{D}(\mu)$ is a regular element of $\mathrm{SL}(n)$, the stabilizer $G_{\rho_{D}}$ of $\rho_{D}$ is the set of diagonal matrices $\mathbb{T}:=\left(\mathbb{C}^{*}\right)^{(n-1)}$.

Now, recall that for the abelian representation $\rho_{D}, H^{1}\left(\Gamma ; \operatorname{Ad} \rho_{D}\right)$ is identified with $\mathbb{A}^{3(n-1)}$ by choosing the basis represented by the cocycles $\left(U_{i}^{+}, U_{i}^{-}, H_{i}\right), 1 \leq$ $i \leq n-1$.

The $G_{\rho_{D}}$-action on $Z^{1}\left(\Gamma ; \operatorname{Ad} \rho_{D}\right)$ descends to an action on $H^{1}\left(\Gamma ; \operatorname{Ad} \rho_{D}\right)$. More precisely, the action of a diagonal matrix $\operatorname{diag}\left(t_{1}, \ldots, t_{n}\right) \in \mathbb{T}$ on a cocycle in
$H^{1}\left(\Gamma ; \operatorname{Ad} \rho_{D}\right)$ is given by

$$
\begin{aligned}
& \left(t_{1}, \ldots, t_{n}\right) \cdot\left(U_{1}^{+}, U_{1}^{-}, \ldots, U_{n-1}^{+}, U_{n-1}^{-}, H_{1}, \ldots, H_{n-1}\right)= \\
& \quad\left(\frac{t_{1}}{t_{2}} U_{1}^{+}, \frac{t_{2}}{t_{1}} U_{1}^{-}, \ldots, \frac{t_{n}}{t_{n-1}} U_{n-1}^{+}, \frac{t_{n-1}}{t_{n}} U_{n-1}^{-}, H_{1}, \ldots, H_{n-1}\right) .
\end{aligned}
$$

The action is then trivial on the abelian cocycles $H_{i}, 1 \leq i \leq n-1$. Furthermore, $\mathbb{C}^{*}$ acts on $\mathbb{C}^{2}$ by $\lambda \cdot\left(z_{1}, z_{2}\right)=\left(\lambda z_{1}, 1 / \lambda z_{2}\right)$ then $\mathbb{C}^{2} / / \mathbb{C}^{*} \cong \mathbb{C}$.

In particular, $V_{\emptyset} / /\left(\mathbb{C}^{*}\right)^{n-1} \cong V_{\emptyset}$ and $V_{\{1, \ldots, n-1\}} / /\left(\mathbb{C}^{*}\right)^{n-1} \cong(\mathbb{C})^{n-1}$.
It is a well known fact that $X_{n}(\mathbb{Z}):=t\left(R_{n}(Z)\right)$ is an irreducible component of $X_{n}(\Gamma)$ of dimension $n-1$ and that $\chi_{D}$ is a smooth point of $X_{n}(\mathbb{Z})$ (see [11, Example 1.2])). Thus $\operatorname{dim}_{\chi_{D}} X_{n}(\mathbb{Z})=n-1$.

Observe that we can prove this known result by applying the Proposition 5.2 to the representation $\rho_{D}$ as a smooth point of the affine variety $R_{n}(\mathbb{Z})$ to obtain a slice $\mathcal{S}_{A b}$ of $R_{n}(\mathbb{Z})$ such that

$$
T_{\rho_{D}}^{Z a r} \mathcal{S}_{A b} \cong T_{\rho_{D}}^{Z a r} R_{n}(\mathbb{Z}) / T_{\rho_{D}}^{Z a r} G(\rho) \cong V_{\emptyset}
$$

and

$$
T_{\chi D}^{Z a r} X_{n}(\mathbb{Z}) \cong T_{\chi D}^{Z a r}\left(R_{n}(\mathbb{Z}) / / \mathrm{SL}(n)\right) \cong T_{0}\left(T_{\rho}^{Z a r} \mathcal{S}_{A b} / / \mathbb{T}\right) \cong T_{0}\left(V_{\emptyset} / /\left(\mathbb{C}^{*}\right)^{n-1}\right) \cong V_{\emptyset}
$$

So we deduce that $\operatorname{dim} T_{\chi_{D}}^{Z a r} X_{n}(\mathbb{Z})=n-1=\operatorname{dim} X_{n}(\mathbb{Z})$ and $\chi_{D}$ is a smooth point of $X_{n}(\mathbb{Z})$.

Again, by applying the Proposition 5.2 to the representation $\rho_{D}$ as a smooth point of the affine variety $R_{D}^{(n)}$ to obtain a slice $\mathcal{S}$ of $R_{D}^{(n)}$ such that

$$
T_{\rho_{D}}^{Z a r} \mathcal{S} \cong T_{\rho_{D}}^{Z a r} R_{D}^{(n)} / T_{\rho_{D}}^{Z a r} G(\rho) \cong V_{\{1, \ldots, n-1\}}
$$

and
$T_{\chi_{D}}^{Z a r} X^{(n)} \cong T_{\chi_{D}}^{Z a r}\left(R_{D}^{(n)} / / \mathrm{SL}(n)\right) \cong T_{0}\left(T_{\rho}^{Z a r} \mathcal{S} / /\left(\mathbb{C}^{*}\right)^{n-1}\right) \cong T_{0}\left(V_{\{1, \ldots, n-1\}} / /\left(\mathbb{C}^{*}\right)^{n-1}\right) \cong(\mathbb{C})^{n-1}$.
So we deduce that $\operatorname{dim} T_{\chi_{D}}^{Z a r} X^{(n)}=n-1=\operatorname{dim} X^{(n)}$ and thus $\chi_{D}$ is a smooth point of $X^{(n)}$.
(3) Note that, as $T_{\chi D}^{Z a r} X_{n}(\mathbb{Z}) \cong V_{\varnothing}, T_{\chi D}^{Z a r} X^{(n)} \cong V_{\{1, \ldots, n-1\}}$ and $V_{\varnothing} \cap V_{\{1, \ldots, n-1\}}=\{0\}$, we obtain that $T_{\chi_{D}}^{Z a r} X_{n}(\mathbb{Z}) \cap T_{\chi_{D}}^{Z a r} X^{(n)}=\{0\}$. This implies that the intersection of the two components $X_{n}(\mathbb{Z})$ and $X^{(n)}$ at $\chi_{D}$ is transverse.

There is an analogue of the following theorem when the considered representation is an irreducible one ([25, Theorem 2.13]).

Theorem 5.5. Let ad: $T_{\rho_{D}^{(n)}}^{Z a r} G\left(\rho_{D}^{(n)}\right) \rightarrow T_{\rho_{D}^{(n)}}^{Z a r} R_{n}(\Gamma)$ and dt: $T_{\rho_{D}^{(n)}}^{Z a r} R_{n}(\Gamma) \rightarrow T_{\chi D}^{Z a r} X_{n}(\Gamma)$ be the tangent morphisms induced by the conjugation action of $\operatorname{SL}(n)$ on $\rho_{D}^{(n)}$ and by the canonical projection $t: R_{n}(\Gamma) \rightarrow X_{n}(\Gamma)$.

Then we have the exact sequence

$$
0 \rightarrow T_{\rho_{D}^{(n)}}^{Z a r} G\left(\rho_{D}^{(n)}\right) \xrightarrow{a d} T_{\rho_{D}^{(n)}}^{Z a r} R_{n}(\Gamma) \xrightarrow{d t} T_{\chi_{D}}^{Z a r} \overline{X_{n}^{i r r}(\Gamma)} \rightarrow 0
$$

and $H^{1}\left(\Gamma ; \operatorname{Ad} \rho_{D}^{(n)}\right) \cong T_{\chi D}^{Z a r} \overline{X_{n}^{i r r}(\Gamma)}$.

Proof. Consider the commutative diagram:

$$
\begin{gathered}
T_{\rho_{D}^{(n)}}^{Z a r} G\left(\rho_{D}^{(n)}\right) \xrightarrow{\iota} \operatorname{Inn}\left(\Gamma, \operatorname{Ad} \rho_{D}^{(n)}\right)=B^{1}\left(\Gamma ; \operatorname{Ad} \rho_{D}^{(n)}\right) \\
\downarrow{ }^{(n d} \\
\downarrow{ }^{j} \\
T_{\rho_{D}^{(n)}}^{Z a r} R(\Gamma)
\end{gathered}
$$

where $\iota: \mathfrak{s l}(n) \ni a \mapsto\left(\iota_{a}: \gamma \mapsto \operatorname{Ad}_{\rho_{D}^{(n)}(\gamma)} a-a ; \forall \gamma \in \Gamma\right)$.
Now $j$ is injective and $\iota$ is injective as $H^{0}\left(\Gamma ; \operatorname{Ad} \rho_{D}^{(n)}\right)=0$ (Proposition 3.6), so $a d$ is injective too. By the commutativity of the above diagram and for all $a \in \mathfrak{s l}(n)$, we have $a d(a)=\frac{d \rho_{s}}{d s}{ }_{\mid s=0}$ where $\rho_{s}(\gamma)=\left(I+s\left(\operatorname{Ad} \rho_{D}^{(n)}(\gamma) a-a\right)\right) \rho_{D}^{(n)}(\gamma) ; \forall \gamma \in \Gamma$.

Thus, for all $\gamma \in \Gamma, d I_{\gamma} \circ d t \circ a d(a)=\frac{d}{d s}{ }_{\mid s=0}\left(\operatorname{tr} \rho_{s}(\gamma)\right)=\operatorname{tr}\left(a \rho_{D}^{(n)}(\gamma)-\rho_{D}^{(n)}(\gamma) a\right)=0$ and $d t \circ a d(a)=0$.
To prove that Ker $d t=\operatorname{Im} a d$, let $\left.\frac{d \rho_{s}}{d s} \right\rvert\, s=0 \in \operatorname{Ker} d t$ where $\rho_{s}(\gamma)=(I+s U(\gamma)) \rho_{D}^{(n)}(\gamma)$ and $U \in Z^{1}\left(\Gamma, \operatorname{Ad} \rho_{D}^{(n)}\right)$. The relation $d t\left(\left.\frac{d \rho_{s}}{d s}\right|_{\mid s=0}\right)=0$ implies that $\frac{d}{d s}{ }_{\mid s=0}\left(\operatorname{tr} \rho_{s}(\gamma)\right)=$ $0 \forall \gamma \in \Gamma$.

By Corollary 3.8 and modulo conjugation by a coboundary, we may assume that there exist complexes $\epsilon_{i} \in \mathbb{C}$, and cochains $a_{i} \in C^{1}(\Gamma, \mathbb{C}), 1 \leq i \leq n-1$, such that the cocycle $U \in Z^{1}\left(\Gamma ; \operatorname{Ad} \rho_{D}^{(n)}\right)$ is of the form:

$$
U=\left(\begin{array}{ccccc}
a_{1} & * & * & \ldots & * \\
\epsilon_{1} u_{1}^{-} & a_{2} & * & \ddots & \vdots \\
0 & \epsilon_{2} u_{2}^{-} & a_{3} & \ddots & \vdots \\
\vdots & \ddots & \ddots & \ddots & * \\
0 & \ldots & 0 & \epsilon_{n-1} u_{n-1}^{-} & a_{n}
\end{array}\right) \in Z^{1}\left(\Gamma ; \operatorname{Ad} \rho_{D}^{(n)}\right) \text {. }
$$

Thus $0=\left.\frac{d}{d s}\right|_{s=0}\left(\operatorname{tr} \rho_{s}(\gamma)\right)$ implies that:

$$
\sum_{i=1}^{n} \lambda_{i}^{h(\gamma)} a_{i}(\gamma)+\sum_{i=1}^{n-1} \lambda_{i+1}^{h(\gamma)} \epsilon_{i} u_{i}^{-}(\gamma) u_{i}^{+}(\gamma)=0 \quad \forall \gamma \in \Gamma
$$

As a consequence, we obtain:

$$
\sum_{i=1}^{n} a_{i}(\gamma)+\sum_{i=1}^{n-1} \epsilon_{i} u_{i}^{-}(\gamma) u_{i}^{+}(\gamma)=0 \quad \forall \gamma \in \Gamma^{\prime}
$$

Now $\sum_{i=1}^{n} a_{i}(\gamma)=0$ as $U \in Z^{1}\left(\Gamma ; \operatorname{Ad} \rho_{D}^{(n)}\right)$, so we obtain:

$$
\sum_{i=1}^{n-1} \epsilon_{i} u_{i}^{-}(\gamma) u_{i}^{+}(\gamma)=0 \quad \forall \gamma \in \Gamma^{\prime}
$$

The fact that the derivations $u_{i}^{ \pm}, 1 \leq i \leq n-1$, factor through $\Gamma^{\prime \prime}$ give the equation:

$$
\sum_{i=1}^{n-1} \epsilon_{i} u_{i}^{-}(x) u_{i}^{+}(x)=0 \quad \forall x \in \Gamma^{\prime} / \Gamma^{\prime \prime} \otimes \mathbb{C}
$$

Recall that as $\alpha_{i}=\lambda_{i} / \lambda_{i+1}, 1 \leq i \leq n-1$ are simple roots of the Alexander polynomial $\Delta_{K}$ and $\Delta_{K}\left(\lambda_{i} / \lambda_{j}\right) \neq 0 \quad \forall|i-j| \geq 2$, the Alexander module decomposes as $\oplus_{i=1}^{n-1}\left(\Lambda / t-\alpha_{i} \oplus \Lambda / t-\alpha_{i}^{-1}\right) \oplus \tau$ where $\tau$ is a torsion $\Lambda$-module with no $\left(t-\alpha_{i}^{ \pm}\right)$-torsion. Choose a basis $\left(e_{1}^{+}, e_{1}^{-}, \ldots, e_{n-1}^{+}, e_{n-1}^{-}\right)$of $\oplus_{i=1}^{n-1}\left(\Lambda / t-\alpha_{i} \oplus \Lambda / t-\alpha_{i}^{-1}\right)$.

Modulo coboundaries, we may suppose that the non principal derivations $u_{i}^{ \pm} ; 1 \leq i \leq$ $n-1$ are generators of $H^{1}\left(\Gamma ; \mathbb{C}_{\alpha^{ \pm}}\right)$as described in Proposition 2.3. In particular,

$$
u_{i}^{ \pm}\left(e_{i}^{ \pm}\right)=1 ; u_{i}^{ \pm}\left(e_{i}^{\mp}\right)=0 ; u_{i}^{ \pm}\left(e_{j}^{ \pm}\right)=u_{i}^{ \pm}\left(e_{j}^{\mp}\right)=0 \forall 1 \leq i \neq j \leq n-1
$$

Evaluating the preceeding equation at $x=e_{i}^{+}+e_{i}^{-}, 1 \leq i \leq n-1$, gives:

$$
\begin{aligned}
0 & =\sum_{j=1}^{n-1} \epsilon_{j} u_{j}^{-}\left(e_{i}^{+}+e_{i}^{-}\right) u_{j}^{+}\left(e_{i}^{+}+e_{i}^{-}\right) \\
& =\epsilon_{i} u_{i}^{-}\left(e_{i}^{+}+e_{i}^{-}\right) u_{i}^{+}\left(e_{i}^{+}+e_{i}^{-}\right) \\
& =\epsilon_{i} u_{i}^{-}\left(e_{i}^{-}\right) u_{i}^{+}\left(e_{i}^{+}\right) \\
& =\epsilon_{i} .
\end{aligned}
$$

We obtain that $\epsilon_{i}=0 \forall 1 \leq i \leq n-1$ and the cocycle $U \in Z^{1}\left(\Gamma ; \operatorname{Ad} \rho_{D}^{(n)}\right)$ is thus of the form:

$$
U=\left(\begin{array}{cccc}
\tilde{a}_{1} & * & \ldots & * \\
0 & \tilde{a}_{2} & \ddots & \vdots \\
\vdots & \ddots & \ddots & * \\
0 & \ldots & 0 & \tilde{a}_{n}
\end{array}\right) \in Z^{1}\left(\Gamma, C_{0}\right)
$$

By Remark 3.7 the traceless cohomolgy group $H_{0}^{1}\left(\Gamma ; C_{0} / C_{2}\right) \cong 0$, thus the cocycle $U \in$ Ker $d t$ is in fact a coboundary and Ker $d t=\operatorname{Im} a d$.

Finally, the surjectivity of the morphism $d t$ is a consequence of the fact that $\operatorname{rg}(d t)=\operatorname{dim} T_{\rho_{D}^{(n)}}^{Z a r} R_{n}(\Gamma)-\operatorname{rg}(a d)=n^{2}-1+n-1-\left(n^{2}-1\right)=n-1=\operatorname{dim} T_{\chi_{D}}^{Z a r} \overline{X_{n}^{i r r}(\Gamma)}$.

## 6. Examples

In this paragraph we discuss and illustrate by some examples the significance of our results in light of what is already known in the literature.
6.1. Knots with quadratic Alexander polynomial. For SL(3) and knots with a quadratic Alexander polynomial Theorem [3.3] follows from the results in [19]. More precisely, up to an action of the center $\left\{I_{3}, \omega I_{3}, \omega^{2} I_{3}\right\}$ of $\operatorname{SL}(3)$, every diagonal representation which verifies the conditions of Theorem 3.3 is the composition of an diagonal representation in $\mathrm{SL}(2)$ with the canonical representation $r_{3}: \mathrm{SL}(2) \rightarrow \mathrm{SL}(3)$. To see this, let $K$ be such a knot with a root $\alpha$, and let $\rho_{D}$ be an abelian representation of $K$ which maps the meridian to

$$
\left(\begin{array}{ccc}
\lambda_{1} & 0 & 0 \\
0 & \lambda_{2} & 0 \\
0 & 0 & \lambda_{3}
\end{array}\right) \in \operatorname{SL}(3)
$$

with $\lambda_{i}, 1 \leq i \leq 3$ pairwise distinct. Then

$$
\left\{\begin{array}{l}
\lambda_{1} \lambda_{2} \lambda_{3}=1 \\
\lambda_{1} / \lambda_{2}=\alpha^{\epsilon_{1}} ; \epsilon_{1}= \pm 1 \\
\lambda_{2} / \lambda_{3}=\alpha^{\epsilon_{2}} ; \epsilon_{2}= \pm 1
\end{array}\right.
$$

We obtain that $\lambda_{1}=\lambda_{3} \alpha^{\epsilon_{1}+\epsilon_{2}}, \lambda_{2}=\lambda_{3} \alpha^{\epsilon_{2}}, \epsilon_{1}, \epsilon_{2}= \pm 1$ and $\lambda_{3}^{3} \alpha^{\epsilon_{1}+2 \epsilon_{2}}=1$. The condition $\lambda_{1} \neq \lambda_{3}$ implies that $\epsilon_{1}=\epsilon_{2}$ and $\lambda_{3}=\alpha^{-\epsilon_{1}} \omega^{k}$ with $\omega$ a primitive 3rd root of unity. As a consequence

$$
\rho_{D}(\mu)=\omega^{k}\left(\begin{array}{ccc}
\alpha^{\epsilon_{1}} & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & \alpha^{-\epsilon_{1}}
\end{array}\right)=\omega^{k} r_{2}\left(\begin{array}{cc}
\alpha^{\epsilon_{1} / 2} & 0 \\
0 & \alpha^{-\epsilon_{1} / 2}
\end{array}\right) .
$$

This proves the claim.
6.2. The torus knot $T(3,4)$. On the other hand, if the Alexander polynomial is not quadratic, there might be deformations which can not be detected by the results in [19]. To see this let us consider the torus knot $T(3,4)$ which is the knot $8_{19}$ in the knot tables. The knot group is $\Gamma_{3,4}=\left\langle a, b \mid a^{3}=b^{4}\right\rangle$, a meridian is given by $m=a b^{-1}$, and the Alexander polynomial is $\Delta_{3,4}(t)=\left(1-t+t^{2}\right)\left(1-t^{2}+t^{4}\right)$ is the product of two cyclotomic polynomials $\phi_{6}(t)$ and $\phi_{12}(t)$. The abelianization $h: \Gamma_{3,4} \rightarrow\langle t \mid-\rangle$ is given by $h(a)=t^{4}$ and $h(b)=t^{3}$. The abelian representation of $\Gamma_{3,4}$ which maps the meridian to

$$
\left(\begin{array}{ccc}
\lambda_{1} & 0 & 0 \\
0 & \lambda_{2} & 0 \\
0 & 0 & \lambda_{3}
\end{array}\right)=\left(\begin{array}{ccc}
\xi^{4} & 0 & 0 \\
0 & \xi & 0 \\
0 & 0 & \xi^{-5}
\end{array}\right)
$$

for $\xi=\exp (i \pi / 18)$ verifies the hypothesis of Theorem 3.3, $\lambda_{1} / \lambda_{2}=\xi^{3}$ is a primitive 12 -th root of unity, $\lambda_{2} / \lambda_{3}=\xi^{6}$ is a primitive 6 -th root of unity, and $\lambda_{1} / \lambda_{3}=\xi^{9}$ is not a root of $\Delta_{3,4}(t)$. Therefore by Theorem 3.3 the abelian representation admits irreducible deformations, and is contained in a 10 -dimensional component of $R_{3}\left(\Gamma_{3,4}\right)$. These deformations can not be detected by the results in [19].
Finally there are deformations of diagonal representations which are not detected by Theorem 3.3. The $\mathrm{SL}(2)$-character variety of $\Gamma_{3,4}$ has 4 one-dimensional components, three of these components $V_{1}, V_{2}$ and $V_{3}$ contain characters of irreducible representations and one component contains only characters of abelian (reducible) representations. Each component $V_{i}$ is parametrized by the trace of the meridian, and contains exactly two characters of abelian representations which are limit of irreducible representations (see for example [23]). In order to obtain irreducible $\mathrm{SL}(3)$ representations of $\Gamma_{3,4}$, we can compose irreducible $\mathrm{SL}(2)$-representation with the canonical representation $r_{3}: \mathrm{SL}(2) \rightarrow$ SL(3) (see Proposition 3.1 in [19]). In this way we obtain 6 diagonal representations which are limit of irreducible representations. For example, let $\rho_{a b}: \Gamma_{3,4} \rightarrow \mathrm{SL}(2)$ be given by

$$
a \mapsto A=\left(\begin{array}{cc}
\eta & 0 \\
0 & \eta^{-1}
\end{array}\right) \text { and } b \mapsto B=\left(\begin{array}{cc}
\zeta & 0 \\
0 & \zeta^{-1}
\end{array}\right)
$$

where $\eta=\exp (i \pi / 3)$ is a primitive 6 -th root of unity, and $\zeta=\exp (i \pi / 4)$ is a primitive 8 -th root of unity. Then $\eta \zeta^{-1}$ is a primitive 24 -th root of unity, and $r_{3} \circ \rho_{a b}$ maps the meridian $m=a b^{-1}$ to the diagonal matrix

$$
\left(\begin{array}{ccc}
\lambda_{1} & 0 & 0 \\
0 & \lambda_{2} & 0 \\
0 & 0 & \lambda_{3}
\end{array}\right)=\left(\begin{array}{ccc}
\left(\eta \zeta^{-1}\right)^{2} & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & \left(\eta \zeta^{-1}\right)^{-2}
\end{array}\right) .
$$

Now, $\lambda_{1} / \lambda_{2}=\exp (i \pi / 6)$ and $\lambda_{2} / \lambda_{3}=\lambda_{1}$ are primitive 12-th roots of unity, and $\lambda_{1} / \lambda_{3}=$ $\lambda_{1}^{2}$ is a primitive 6 -th root of unity. Therefore, all three quotients are roots of $\Delta_{3,4}(t)$ the deformations of this abelian representation are not detected by Theorem 3.3, On the other hand, Proposition 3.1 in [19] shows that the representation $r_{3} \circ \rho_{a b}$ admits irreducible deformations. Moreover, it is possible to prove that the representation $\rho_{a b}$ is contained in a 12 -dimensional component of the $\mathrm{SL}(3)$-representation space $R_{3}\left(\Gamma_{3,4}\right)$ (see [29, Proposition 8.2]).
6.3. The trefoil knot. By Proposition 4.12 we know that the representation $\rho_{D}$ a smooth point of the two components $R_{D}^{(n)}$ and $R_{a b}$. For other components this might be not the case.

This situation occurs already for the trefoil knot and representations of its knot group $\Gamma$ to SL(3). It follows from work of J. Porti and V. Muñoz that $R_{3}(\Gamma)$ has tree algebraic components. One component of irreducible representations, one component of totally reducible representations, and one component of partially reducible representations [29].

The primitive 6th root of unity $\eta=\exp (i \pi / 3)$ is a simple root of the Alexander polynomial $\Delta(t)=t^{2}-t+1$. Moreover we choose $\lambda$ a primitive 12 th root of unity such that $\lambda^{2}=\eta$. It follows that $\rho_{D\left(\lambda, \lambda^{-1}\right)} \in R_{2}(\Gamma)$ is contained in a 4 -dimensional component $R_{D}^{(2)} \subset R_{2}(\Gamma)$.

If $n=3$ and $D=D\left(\lambda^{2}, 1, \lambda^{-2}\right)$, we obtain two families of partially reducible representations $\phi, \psi: \mathbb{C}^{*} \times R_{D}^{(2)} \hookrightarrow R_{3}(\Gamma)$ given by

$$
\phi(s, \varrho)(\gamma)=\left(s^{h(\gamma)} \varrho(\gamma)\right) \oplus s^{-2 h(\gamma)} \quad \text { and } \quad \psi(s, \varrho)(\gamma)=s^{2 h(\gamma)} \oplus\left(s^{-h(\gamma)} \varrho(\gamma)\right) .
$$

The two families are contained in the same component of partially reducible representation of $R_{3}(\Gamma)$. This component is 9-dimensional. Notice also that $\phi(s, \varrho)$ and $\psi\left(s^{-1}, \varrho\right)$ are conjugate in $R_{3}(\Gamma)$.
Now observe that the image of $D \phi\left(\lambda, \rho_{D_{1}}\right)$ is contained in $\widetilde{V}_{1}$ and that the image of $D \psi\left(\lambda, \rho_{D_{1}}\right)$ is contained in $\widetilde{V}_{2}$. Hence the tangent space of $\rho_{D}$ at the variety of partially irreducible representations contains $\widetilde{V}_{1}+\widetilde{V}_{2}$ which is 12 -dimensional. This implies that $\rho_{D}$ is a singular point of the component of partially reducible representations.

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