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Estimation of constituent properties of concrete materials with an artificial neural network based method

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30 trained by using this dataset. Various types of validation of the ANN model are
31 performed. It is found that the proposed ANN based model can effectively predict the
32 frictional coefficient and cohesion of porous cement paste at the microscopic scale
33 with a very good accuracy.

34
35 **Keywords:** Multi-scale modeling; homogenization; parameter identification; artificial
36 neural network; concrete; heterogeneous materials

37 38 **1. Introduction**

39 Concrete materials are widely used in engineering structures. The
40 characterization of short and long term physical and mechanical properties is crucial
41 for the analysis of stability and durability of concrete structures. Like most
42 engineering materials, concrete materials are heterogeneous composites with complex
43 and multi-scale micro-structures. It is well-known that their macroscopic properties
44 are inherently related to micro-structural compositions and evolutions at different
45 scales. Based on experimental data, many macroscopic models have been developed
46 for describing mechanical behaviors of concretes. In general, these models are not
47 able to explicitly establish links between macroscopic properties and micro-structural
48 parameters. To overcome this shortcoming, micro-mechanical approaches have been
49 developed for estimating macroscopic mechanical properties of concrete composites
50 in terms of microstructural parameters and constituent properties. In particular, by
51 using nonlinear homogenization techniques, a number of analytical strength criteria
52 have been established for heterogeneous materials containing pores and inclusions at
53 different scales (Maghous et al., 2009; Shen et al., 2013; Shen et al. 2017; Shen et al.
54 2020). Basic on such criteria, full elastic-plastic models have been formulated by
55 considering hardening or damage (Shen et al., 2012; Bignonnet et al., 2016; Shen and
56 Shao, 2016; Shen et al. 2020a; Aldakheel, 2020). On the other hand, based on the full
57 simulations of representative volume elements by using suitable numerical methods,
58 different types of numerical homogenization techniques have also been developed for

59 the prediction of macroscopic responses of materials with complex micro-structures
60 (Cao et al., 2018a; Cao et al. 2018b; Cao et al., 2020). A number of micromechanical
61 models have been successively applied to cement-based materials (Ghorbanbeigi et al.,
62 2016; Paiva et al., 2017; Konigsberger et al. 2018; Zhang et al., 2020).

63 For all these micro-mechanics based models, the estimation of macroscopic
64 mechanical properties is inherently based on the description of microstructures and
65 local mechanical properties of constituent phases. For instance, for concrete materials,
66 typical microstructures are composed of cement paste (solid matrix), voids, inclusions
67 and interface transition zones. In many previous models, the local plastic yield or
68 strength criterion of the solid matrix is generally described the Drucker-Prager (DP)
69 linear function which is characterized by frictional and cohesion coefficients.
70 Therefore, the identification of such local mechanical properties at microscopic scales
71 is the key issue of micro-mechanical approaches. Advanced multi-scale testing
72 methods have been developed in order to realize direct measurement of local
73 mechanical properties, for instance nanoindentation and micro-bending tests
74 (Nemecek et al., 2016; Konigsberger et al., 2018; Qian et al., 2018; Lau et al., 2019).
75 However, in most cases, these experimental techniques are so far used for the
76 identification of local elastic properties and tensile strength at a given scale. It is not
77 easy to apply these techniques at different scales. In most case, optimal inversion
78 methods are usually adopted for the estimation of microscopic properties using
79 macroscopic measurements. The efficiency of these methods is not fully guaranteed
80 for cases of several parameters to be identified. More efficient and systematic
81 methods should be developed.

82 During the recent years, machine-learning (ML) based methods have been
83 rapidly developed in various engineering fields including materials science and
84 technology. Indeed, based on a deep training, such fully data-driven methods have
85 been proven to be a powerful and versatile problem-solving tool for both multi-scale
86 characterization and design of different types of engineering materials and structures.
87 For instance and without wanting to give an exhaustive review, anisotropic masonry

88 failure properties have been investigated with Artificial Neural Networks (Asteris and
89 Plevris, 2017). Stochastic vulnerability of masonry structures has further been
90 assessed (Asteris et al. 2019). ML based solutions have also been applied to mapping
91 and holistic design of natural hydraulic lime mortars (Apostolopoulou et al. 2020).
92 Some authors have proposed a hybrid combination of surrogate machine learning
93 models to predict concrete compressive strength (Asteris et al. 2021). Peak particle
94 velocity caused by blasting was predicted by using combinations of boosted-CHAID
95 and SVM Models with various kernels (Zeng et al. 2021). In some recent studies,
96 some authors have tried to estimate macroscopic strength of porous materials by using
97 Artificial Neural Networks (Shen et al. 2020b).

98 Therefore, among different types of ML-based solutions, Artificial Neural
99 Networks (ANN) are one of the mostly adopted methods. The ANN can accurately
100 identify and learn underlying relationships between input and output data without
101 considering explicit mathematical equations (Haykin, 2010). Besides, ANN-based
102 solutions are viewed as an effective alternative to traditional statistical analysis
103 techniques for function approximation and data fitting due to regardless of
104 assumptions about mathematical models (Rahman and Zhang, 2018). This type of
105 method has also been applied to identify constituent properties of concrete materials,
106 for instance, to identify the nanoscopic elastic modulus of different phases of
107 cementitious matrix (Ford et al. 2020), to get the abrasion performance of the fly
108 ash-based geopolymer (Lau et al. 2019). Some authors have also used the ANN
109 method to investigate the effect of carbon nanotubes on mechanical properties of
110 novel cement formulations (Konstantopoulos et al., 2020).

111 However, in most previous studies, the emphasis was put on the estimation of
112 macroscopic physical and mechanical properties. Among studies on the identification
113 of constituents mechanical properties, most are limited to elastic ones. Very few
114 studies are available on the estimation of failure or strength properties of constituents.
115 Moreover, in most previous studies, only one material scale was considered at the
116 same time while concrete materials are multi-scale composites. Therefore, there is

117 clearly a need to perform further investigations on the identification of strength
118 properties of constituents in multi-scale heterogeneous materials such as concrete.
119 This is the main objective of this work.

120 For this purpose, based on the artificial neural networks (ANN) technique, a new
121 numerical method is developed for the identification of local strength parameters of
122 solid cement paste by taking into account simultaneously effects of pores and
123 inclusions. In particular, an original strategy is developed by the combination of an
124 ANN model with an analytical strength criterion issued from three steps of nonlinear
125 homogenization. This one has the advantage of easily constructing a large data set by
126 using analytical solutions, for the ANN model training and verification. The present
127 paper is organized in three main parts. In Section 2, an analytical macroscopic
128 strength criterion for concrete-like composites is presented. With this model, a
129 sensitivity study is performed to identify the key microstructural parameters
130 controlling the macroscopic strength of materials and to formulate a simplified
131 analytical macroscopic strength criterion. The general procedure to build an ANN
132 model is presented in Section 3. The ANN model is used in Section 4 for the
133 prediction of the local friction and cohesion coefficients of porous cement phase at the
134 microscopic scale. Its accuracy is clearly demonstrated through comparisons with
135 analytical solutions. Some concluding remarks are finally presented in Section 5.

136 **2. Sensitivity analysis of microstructural parameters**

137 In order to identify the key microstructural parameters controlling the
138 macroscopic strength of concrete materials, a sensitivity study is first performed. It is
139 worth noticing that micro-structures of concrete materials are generally complex. For
140 instances, different types of Calcium silicate hydrate (C-S-H) are formed in cement
141 paste. Voids and inclusions of different sizes are distributed at different scales. The
142 macroscopic mechanical properties of concrete materials are inherently affected by
143 their local counterparts of constituent phases, their morphology, porosity and
144 volumetric fraction of inclusions. Further, interface transition zones (ITZ) are created
145 around aggregates and pores. They can significantly affect the macroscopic

146 mechanical properties of materials. It is hard to consider all these micro-structural
147 parameters at the same time.

148 In this study, the following methodology is adopted. We shall take advantage of
149 some analytical solutions issued from rigorous nonlinear homogenization techniques
150 to establish explicit relations between macroscopic strength of concrete and local
151 strength properties of cement paste, pores and inclusions. In this way, the macroscopic
152 strength criteria can be formulated in a closed form. Typical strength parameters such
153 as uniaxial compression and tension strengths can be very easily calculated with any
154 numerical simulations. Therefore, in view of ANN training, it is very easy to construct
155 a large data set with very simple calculations with the help of analytical strength
156 criteria. However, the shortcoming of this study is that the micro-structural
157 morphology of concrete materials should be simplified in order to establish analytical
158 strength criteria. For instance, it is mathematically very difficult to derive analytical
159 strength criteria by considering pores, inclusions and ITZ at the same time. As a
160 consequence, the effect of ITZ is omitted in this study. It could be taken into account
161 in future investigations by using direct numerical simulations of concrete
162 micro-structures to construct data set.

163 With this basic idea, the objective of sensitivity study presented here is to
164 hierarchize the influences of different micro-structural parameters on macroscopic
165 strength. Based on this study, a simplified formulation of the macroscopic strength
166 criterion is proposed.

167 **2.1 Presentation of analytical strength criterion and problem statement**

168 Based on the methodology presented above, we consider here concrete or rock
169 like composites containing two populations of pores and a family of inclusions at
170 three separate scales. The representative volume element (RVE) of heterogeneous
171 material is illustrated in Fig. 1.

172 At the macroscopic scale (cm), the material is represented by a homogenized
173 equivalent medium (HEM) whose strength properties are to be predicted. At the
174 mesoscopic scale (mm), mineral inclusions (quartz and calcite grains, aggregates etc.)

175 are distributed in a quasi-continuous matrix (for instance clay matrix or cement paste).
 176 At the microscopic scale (μm), this matrix phase contains a family of (large) pores
 177 (inter-particle pores of a few hundreds of nanometers to micrometers). At the
 178 nanoscopic scale (nm), small pores (intra-particle pores of a few nanometers) are
 179 embedded inside solid particles.

180

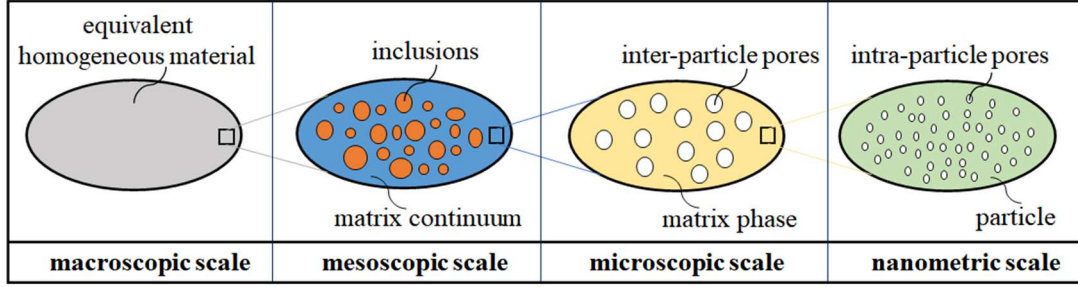


Fig. 1. RVE of heterogeneous materials with two families of pores and inclusions.

181

182 It is assumed that the solid phase at the nanoscopic scale is described by a
 183 pressure-sensitive Drucker-Prager type yield or strength criterion:

$$F^s = \tilde{\sigma}_d + T(\tilde{\sigma}_m - h) \leq 0 \quad (1)$$

184 where $\tilde{\sigma}$ denotes the stress tensor of the solid phase. $\tilde{\sigma}_m = tr\tilde{\sigma}/3$ is the mean stress.

185 $\tilde{\sigma}_d$ is the deviatoric stress defined as $\tilde{\sigma}_d = \sqrt{\tilde{\sigma}' : \tilde{\sigma}'}$, with $\tilde{\sigma}'$ being the deviatoric

186 part of the stress tensor. The parameter T denotes the frictional coefficient and h the

187 hydrostatic tensile strength (also related to internal cohesion) of the solid phase at the

188 nanoscopic scale. By performing three steps of nonlinear homogenization with the

189 modified secant method (Maghous et al., 2009; Shen et al., 2013, Cao et al., 2020),

190 one obtains the following close-form of the macroscopic strength criterion:

$$F = \frac{A + \frac{2B\rho}{3}}{1 + \frac{3\rho}{2} - \frac{5\rho}{6(\frac{A}{B} + 1)}} \Sigma_d^2 + B\Sigma_m^2 + C\Sigma_m - \left(D + \frac{4BD + C^2}{6A} \rho \right) = 0 \quad (2)$$

191 with the following coefficients:

$$A = \frac{1+\frac{2f}{3}}{T^2} \left(\frac{6T^2-13f-6}{4T^2-12f-9} \phi + 1 \right), \quad B = \frac{\frac{3+f}{2}}{T^2} \phi + \frac{3f}{2T^2} - 1, \quad (3)$$

$$C = 2(1-f)(1-\phi)h, \quad D = (1-f)^2(1-\phi)^2h^2.$$

192 In this criterion, Σ is the macroscopic stress tensor, $\Sigma_m = tr\Sigma/3$ is the mean stress
 193 and $\Sigma_d = \sqrt{\Sigma' : \Sigma'}$ is the deviatoric stress with Σ' being the macroscopic deviatoric
 194 stress tensor. ρ represents the volume fraction of inclusions, ϕ is the large porosity
 195 at the microscopic scale while f being the small porosity at the nanometric scale.

196 The strength criterion (2) is now applied to the case of uniaxial stress loading. At
 197 failure state, one has $\Sigma_d = R$, $\Sigma_m = (-1/3)R$, with R being the failure strength
 198 which can be determined by the following relation.

$$\left(\frac{A + \frac{2B\rho}{3}}{1 + \frac{3\rho}{2} - \frac{5\rho}{6\left(\frac{A}{B} + 1\right)}} + \frac{B}{9} \right) R^2 - \frac{C}{3}R - \left(D + \frac{4BD + C^2}{6A}\rho \right) = 0 \quad (4)$$

199 The above quadratic equation admits one positive and one negative solution,
 200 which respectively corresponds to the uniaxial tensile strength R_t and the uniaxial
 201 compression strength R_c . Therefore, by knowing the microstructural parameters
 202 parameters (ρ, ϕ, f) and the nanoscopic strength properties of solid cement particles
 203 (T, h) , it is easy to calculate the two basic macroscopic strength parameters (R_c, R_t) .
 204 But the objective here is to solve the corresponding inverse problem, consisting of
 205 identifying the values of the nanoscopic strength properties of solid cement particles
 206 (T, h) from the easily measurable macroscopic strength parameters (R_c, R_t) .

207 2.2 Sensitivity analysis

208 Before going to the resolution of the inverse problem, a sensitivity analysis is
 209 first realized. The objective is to quantify the dependency of two macroscopic
 210 strength parameters (R_c, R_t) on the three microstructural parameters (ρ, ϕ, f) in
 211 order to define their relative impact on the macroscopic strength.

212 Different types of methods are available for performing sensitivity analysis,
 213 including one-at-a-time method (OAT) (Czitrom, 1999; Saltelli and Annoni, 2010),
 214 the derivative-based local approaches (Cacuci et al., 2005; Griewank and Walther,
 215 2008), the regression analysis (Galton et al., 1989), the variance-based methods

216 (so-called Sobol method) (Sobol, 2001; Saltelli, 2002; Saltelli et al., 2010), the
 217 variogram analysis of response surfaces (VARs) (Razavi and Gupta, 2016a; Razavi
 218 and Gupta, 2016b), the Scatter plots (Paruolo et al., 2013) and others. The Sobol
 219 method is used in this paper because it can measure the sensitivity across the whole
 220 input space (i.e., the global method), handle nonlinear responses, and measure the
 221 impact of interactions in non-additive systems (Saltelli, 2002).

222 For the simplicity of presentation, only the influence of input parameters
 223 (ρ, ϕ, f, T, h) on the uniaxial compression strength R_c using Eq. (4) is analyzed here.
 224 For this purpose, the relationship between R_c and the input parameters is written as:

$$R_c = g(\mathbf{X}) \quad (5)$$

225 where $\mathbf{X} = [\rho, \phi, f, T, h]$. The calculation sequence of sensitivity analysis is as
 226 follows.

227 **Step 1:** Randomly generate two independent 1000×5 sample matrices, i.e. each row is
 228 a sample point in the hyperspace of 5 dimensions. The value range of the parameter is:
 229 $\rho \in [0, 1]$, $\phi \in [0, 1]$, $f \in [0, 0.5]$, $T \in [0, 1]$, $h \in [0, 80]$. The generated matrices are
 230 recorded as \mathbf{A} , \mathbf{B} .

$$\mathbf{A} = \begin{bmatrix} \rho_1 & \phi_1 & f_1 & T_1 & h_1 \\ \rho_2 & \phi_2 & f_2 & T_2 & h_2 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ \rho_{1000} & \phi_{1000} & f_{1000} & T_{1000} & h_{1000} \end{bmatrix} \quad (6)$$

231

$$\mathbf{B} = \begin{bmatrix} \rho_1^* & \phi_1^* & f_1^* & T_1^* & h_1^* \\ \rho_2^* & \phi_2^* & f_2^* & T_2^* & h_2^* \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ \rho_{1000}^* & \phi_{1000}^* & f_{1000}^* & T_{1000}^* & h_{1000}^* \end{bmatrix} \quad (7)$$

232 **Step 2:** Build 5 further 1000×5 matrices $\mathbf{A}_B^{(i)}$, with $i = 1, 2, \dots, 5$, such that the i -th

233 column of $\mathbf{A}_B^{(i)}$ is equal to the i -th column of \mathbf{B} , and the remaining columns are from

234 \mathbf{A} . For instance $\mathbf{A}_B^{(3)}$ is as follows:

$$\mathbf{A}_B^{(3)} = \begin{bmatrix} \rho_1 & \phi_1 & f_1^* & T_1 & h_1 \\ \rho_2 & \phi_2 & f_2^* & T_2 & h_2 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ \rho_{1000} & \phi_{1000} & f_{1000}^* & T_{1000} & h_{1000} \end{bmatrix} \quad (8)$$

235

236 **Step 3:** Calculate the estimators by the method proposed in (Janson, 1999; Saltelli et
 237 al. 2010) with Eqs. (9)-(11). $(\mathbf{A})_j$ denotes the j -th row of the matrix \mathbf{A} , $(\mathbf{B})_j$ is the
 238 j -th row of the matrix \mathbf{B} , and $(\mathbf{A}_B^{(i)})_j$ represents the j -th row of the matrix $\mathbf{A}_B^{(i)}$.

$$V_{X_i}(E_{X \sim i}(Y|X_i)) = \frac{1}{1000} \sum_{j=1}^{1000} g(\mathbf{B})_j \left(g(\mathbf{A}_B^{(i)})_j - g(\mathbf{A})_j \right) \quad (9)$$

$$E_{X \sim i}(V_{X_i}(Y|X_{\sim i})) = \frac{1}{2000} \sum_{j=1}^{1000} \left(g(\mathbf{A})_j - g(\mathbf{A}_B^{(i)})_j \right)^2 \quad (10)$$

$$V(Y) = \frac{1}{1000} \sum_{j=1}^{1000} g(\mathbf{A})_j^2 - \left(\frac{1}{N} \sum_{j=1}^N g(\mathbf{A})_j \right)^2 \quad (11)$$

239 **Step 4:** Calculate the sensitivity indices using the estimators of step 3. The Sobol
 240 sensitivity index is defined as the ratio of partial variance to total variance (Sobol,
 241 2001). The first and total sensitivity index is given by Eqs. (12) and (13).

$$S_i = \frac{V_{X_i}(E_{X \sim i}(Y|X_i))}{V(Y)} \quad (12)$$

$$S_{Ti} = 1 - \frac{V_{X \sim i}(E_{X_i}(Y|X_{\sim i}))}{V(Y)} = \frac{E_{X \sim i}(V_{X_i}(Y|X_{\sim i}))}{V(Y)} \quad (13)$$

242

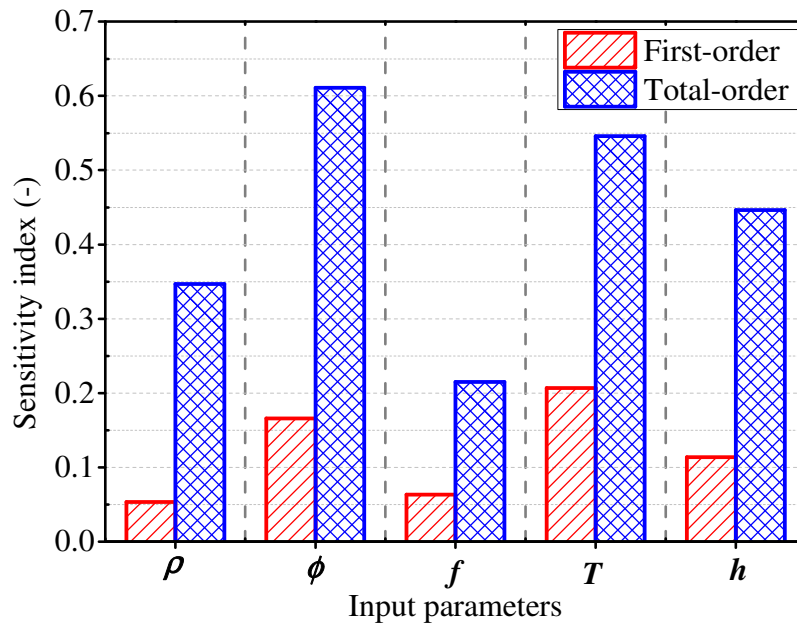


Fig. 2. Results of first-order and total-order index for input parameters.

243 The first-order and total-order indexes of five input parameters based on the
 244 Sobol method are presented in Fig. 2. Regarding the first-order sensitivity index, the
 245 three most relevant input features in order are $T > \phi > h$, while the two most
 246 non-significant features in order is $f > \rho$. For the total-order sensitivity index, the
 247 relevant input features in order are $\phi > T > h > \rho > f$. At the same time, there is a
 248 drastic difference between the first-order and total-order indexes for the same
 249 parameter. These results are consistent with the fact that the total-order sensitivity
 250 index considers the interaction among the input variables. According to the results
 251 obtained, one can consider that the small porosity f has the least influence on the
 252 macroscopic uniaxial compression strength. Very similar results can be obtained for
 253 the uniaxial tensile strength.

254 2.3 Simplification of analytical strength criterion

255 Based on the sensitivity study presented above, it seems that the effect of the
 256 nanoscopic porosity f on the macroscopic strength is relatively small. On the other
 257 hand, the porosity at the nanoscopic scale is also not easy to be accurately measured.
 258 In order to facilitate the solution of inverse problem, the microstructure of
 259 heterogeneous materials is simplified into three representative scales instead of four
 260 scales shown in Fig. 1. It is physically assumed that the intra-particle pores are
 261 merged into the solid cement paste phase, as suggested in (Konigsberger et al., 2018).
 262 The simplified microstructure is illustrated in Fig. 3.

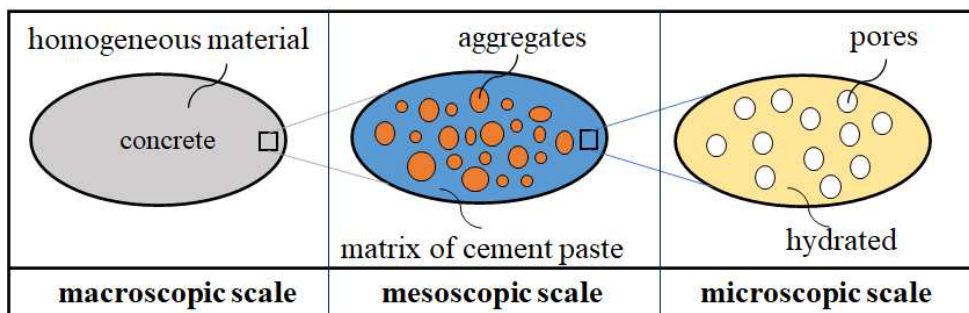


Fig. 3. Simplified RVE of concretes with pores and aggregates.

264

265 Accordingly, the macroscopic strength can be now obtained by making three
 266 steps of homogenization. This is equivalent to set $f = 0$ in the criterion (2) and the
 267 related coefficients (3). The simplified macroscopic strength criterion is expressed as:

$$F' = \frac{A' + \frac{2B'\rho}{3}}{1 + \frac{3\rho}{2} - \frac{5\rho}{6\left(\frac{A'}{B'} + 1\right)}} \Sigma_d^2 + B' \Sigma_m^2 + C' \Sigma_m - \left(D' + \frac{4B'D' + C'^2}{6A'} \rho \right) = 0 \quad (14)$$

268 with the following coefficients:

$$A' = \frac{1}{T'^2} \left(\frac{6T'^2 - 6}{4T'^2 - 9} \phi + 1 \right), \quad B' = \frac{3}{2T'^2} \phi - 1, \quad (15)$$

$$C' = 2(1 - \phi)h', \quad D' = (1 - \phi)^2 h'^2.$$

269 It is worth noticing that in the initial strength criterion (2), the parameters T and h
 270 respectively represents the frictional and cohesion coefficients of solid cement paste at
 271 the nanoscopic scale. In the simplified criterion (14), the parameters T' and h'
 272 denotes the frictional and cohesion coefficients of the porous cement paste at the
 273 microscopic scale. That means that their values include implicitly the effect of
 274 nanoscopic pores on the strength properties of cement paste.

275 One considers again the uniaxial compression or tension test. At the failure state,
 276 the strength criterion (14) becomes:

$$\left(\frac{A' + \frac{2B'\rho}{3}}{1 + \frac{3\rho}{2} - \frac{5\rho}{6\left(\frac{A'}{B'} + 1\right)}} + \frac{B'}{9} \right) R^2 - \frac{C'}{3} R - \left(D' + \frac{4B'D' + C'^2}{6A'} \rho \right) = 0 \quad (16)$$

277 Two solutions of this equation correspond to the uniaxial tensile strength R_t and
 278 compressive strength R_c . These two macroscopic strength coefficients are functions
 279 of the microstructural parameters ρ, ϕ and the microscopic strength parameters
 280 T', h' . The inverse problem to be solved here is the determination of two microscopic
 281 strength parameters T', h' from the known values of microstructural parameters ρ, ϕ
 282 and the macroscopic strength properties (R_c, R_t) , which can be easily measured by
 283 standard testing methods. This is a strongly nonlinear problem which is solved by an
 284 ANN-based method in this study.

285 **3. Main steps of building an ANN model**

286 The ANN originated from the biological nervous system and is optimized and
 287 applied to the deep learning algorithms (McCulloch and Pitts, 1943). The basic ANN
 288 is composed of artificial neurons connected to each other. The connections between
 289 neurons are used to transmit signals (called synapses). Each neuron first receives
 290 signals, then processes them, and finally sends signals to the neurons connected to it.
 291 Such ANNs are able to learn from observational data in the so-called training process
 292 and then to predict unknown results. The use of ANNs provides an efficient way to
 293 solve large size regression or classification problems. In this section, the main steps of
 294 establishing an ANN model are introduced.

295 Depending on the physical problems and the selected hyper-parameters, the
 296 original dataset is generally divided into three parts (train dataset, validation dataset,
 297 and test dataset) (Frank et al., 2014). The three parts of dataset are introduced into the
 298 model for training and testing. If the test results are satisfactory, the training ends.
 299 Otherwise, it is decided to continue the training process to optimize the
 300 hyper-parameters of the model, and the amount of original data can be increased if
 301 possible. The flowchart for building an ANN model is illustrated in Fig. 4.

302

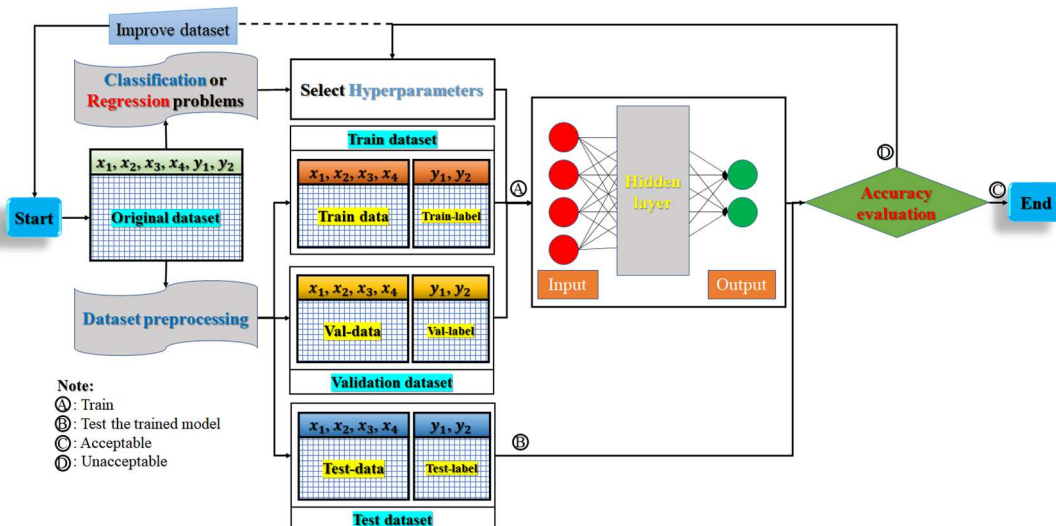


Fig. 4. Flowchart for building an ANN model

303

304 **3.1 Original dataset preprocessing**

305 The ANN modeling is based on the dataset, which is composed of input-data and
 306 output-label. The classification of input and output is determined according to the
 307 physical nature of problem. Meanwhile, it is difficult to obtain an accurate training
 308 model for different scales of input data (Haykin, 2010). Therefore, the preprocessing
 309 of the original data is very important to the modelling.

310 The preprocessing of the dataset includes two parts in general, one is the
 311 reasonable division of the dataset, and the other is the normalization or
 312 standardization of the dataset. The division of the dataset is mainly to complete the
 313 training and testing of the model, the commonly used allocation ratio is 60%, 20%
 314 and 20% for train, validation and test respectively (Hashemi et al., 2020; Jiang et al.,
 315 2020). The normalization or standardization of input and output data is to prevent
 316 overriding between different scales of numbers and premature saturation of hidden
 317 nodes (Haykin, 2010). This is completed by using Equation (17) (Ozgoren et al. 2013;
 318 Jiang et al., 2020) or (18) (Ciaburro et al., 2020):

$$x_i = 0.8 \left(\frac{k_i - k_{min}}{k_{max} - k_{min}} \right) + 0.1 \quad (17)$$

319 where i , k_i , x_i , k_{max} , k_{min} are the serial number of the dataset, the actual value of
 320 the data, the normalized value, the maximum and minimum values of k_i in the data
 321 samples, respectively.

$$x_i = \frac{k_i - \mu}{\sigma} \quad (18)$$

322 where μ and σ are the mean and standard deviation in the data samples,
 323 respectively.

324 For the convenience of description, one takes 4-inputs and 2-outputs containing
 325 10,000 series of original dataset as an example. This does not lose generality. In the
 326 beginning, the original dataset ($10k \times 6$ represents 10,000 rows and 6 columns) is
 327 randomly divided into two groups, one is the train group ($8k \times 6$), the other is the test
 328 group ($2k \times 6$). Subsequent, split the train group into two parts train-data (input
 329 parameters: $8k \times 4$) and train-label (output parameters: $8k \times 2$). Similarly, the test
 330 group also turns into two parts, namely, test-data ($2k \times 4$) and test-label ($2k \times 2$).
 331 Besides, Eq. (17) or (18) is used to normalize the train-data and test-data of the

332 previous step. It is worth noticing that the train-label and test-label do not need to be
 333 normalized. At the last, to make the prediction results of the model more accurate,
 334 10,000 sets of data are selected from the train-label and the normalized train-data to
 335 make up a validation dataset, which is composed of validation-data ($2k \times 4$) and
 336 validation-label ($2k \times 2$). In this way, the required train dataset, validation dataset,
 337 and test dataset are obtained. The detailed steps are indicated in Fig. 5. The data set
 338 used in this study can be found in the shared file mentioned in the Supplementary
 339 Information at the end of this paper.

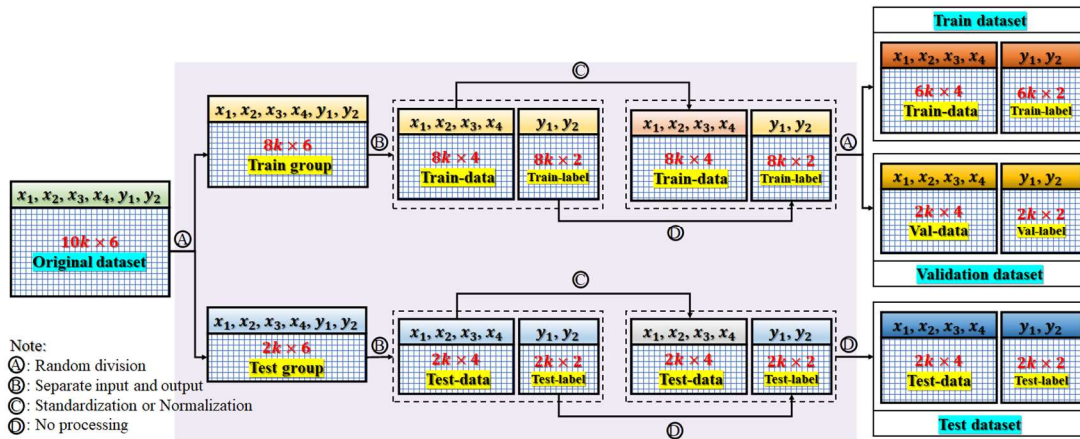


Fig. 5 Original dataset preprocessing process

340 3.2 Determination of network structure and algorithm

341 There are several types of ANNs such as feed-forward, radial basis function, and
 342 recurrent neural networks. For most engineering problems (Ghritlahre and Prasad,
 343 2018; Jiang et al., 2020; Guijo-Rubio et al., 2020, Shen et al., 2020), the most
 344 commonly used one is the feed-forward neural network structure with the
 345 back-propagation (BP) algorithm (Fig. 6). The BP neural network is then adopted in
 346 this study.

347

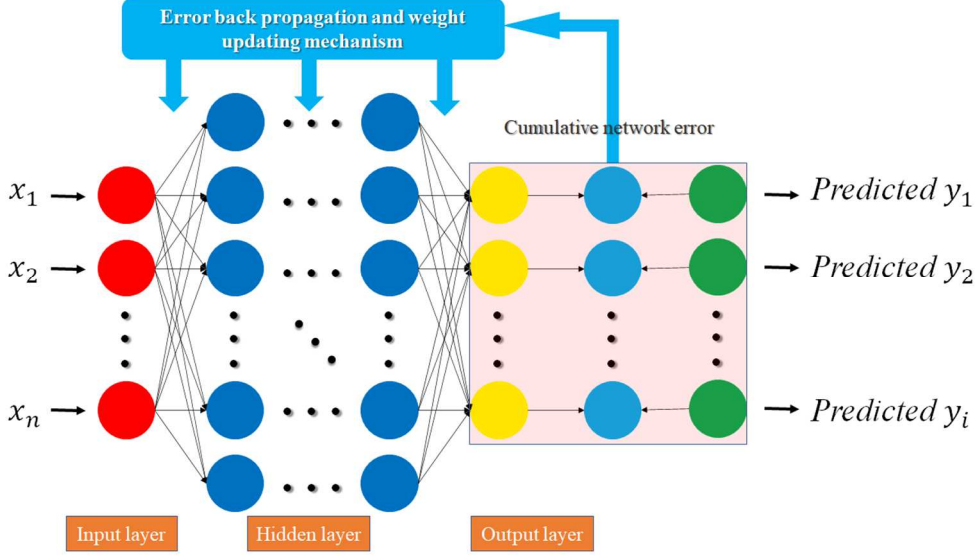


Fig. 6. A multi-layer feed-forward ANN model with a back-propagation algorithm

348

349 A neural network has multiple layers, including one input, one output, and one or
 350 more hidden layers with a specific number of neurons in each layer. The neurons in
 351 each layer have two functions: the summation and activation, which are used to sum
 352 the weighted inputs and to activate this summation to produce the outputs,
 353 respectively. The internal structure of a neuron is described in Fig. 7. The l -th layer
 354 has n neurons while the $(l - 1)$ -th layer has m neurons. The input/output relationship
 355 of a neuron is indicated in a matrix form as follows:

$$a_i^l = \sigma \left(\sum_{j=1}^m \mathbf{w}_{ij}^l \mathbf{a}_j^{l-1} + \mathbf{b}_i^l \right) \quad (19)$$

356 where \mathbf{w}_{ij}^l is the weight matrix from the $(l - 1)$ -th layer to the l -th layer, \mathbf{b}_i^l is the
 357 bias vector for inputs on the l -th layer, The indices range $i = 1, 2, \dots, n$, and $j =$
 358 $1, 2, \dots, m$. σ represents the activation function. The most widely used activation
 359 functions are : $\sigma(x) = \tanh x$ (hyperbolic tangent), $\sigma(x) = \max(0, x)$ (ReLU),
 360 $\sigma(x) = \frac{1}{1 + \exp(-x)}$ (Sigmoid), $\sigma(x) = \ln(1 + \exp x)$ (Softplus) and $\sigma(x) = x$
 361 (linear) etc. It is worth noticing that the values of weight coefficient and bias are
 362 essential for the ANN based simulation. Detailed and interesting discussions on this
 363 aspect have been presented in some recent studies (Asteris and Mokos, 2020; Le et al.,
 364 2021; Asteris et al., 2021; Armaghani et al., 2021). However, it is not easy to present

365 their values directly in the paper. The values of weights and bias used in the present
 366 study are given in the shared file mentioned in the Supplementary Information at the
 367 end of the paper.

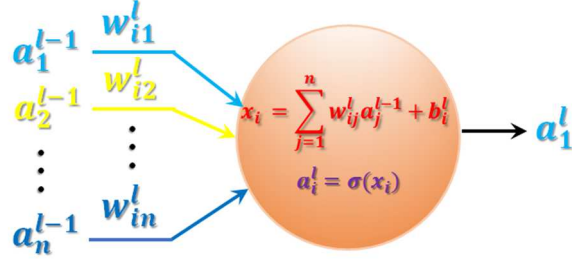


Fig. 7. Artificial neuron

368

369 After the network is established, the model needs to be trained with the
 370 preprocessed dataset to achieve the target output. The training process is through
 371 adjusting the weights and bias of the network to obtain minimizing the defined loss
 372 function (or cost function), e.g., the mean squared error (MSE) defined in Eq. (20)
 373 (Ashrafian et al., 2020) between the target output and the predicted output for
 374 regression problems. At the validation phase, the mean absolute error (MAE) defined
 375 in Eq. (21) (Ashrafian et al., 2020) is used.

$$MSE = \frac{1}{n} \sum_{i=1}^n [f(x_i) - y_i]^2 \quad (20)$$

$$MAE = \frac{1}{n} \sum_{i=1}^n |f(x_i) - y_i| \quad (21)$$

376 in which $f(x_i)$ denotes the ANN prediction, y_i is the true value. Note that in order
 377 to speed up the training procedure, the gradient of loss function over all the training
 378 inputs will be approximated by the one over a small number batch-size (mini-batch),
 379 randomly chosen from training data.

380 In the BP neural network with a gradient-based optimization algorithm, the
 381 cumulative network error between its final output and the actual value is
 382 back-propagated to quickly adjust the values of the weights in the whole network as
 383 shown in Fig. 6. For more theoretical details about ANN training, readers can refer to
 384 some reference literatures (Hassan et al., 2009; Deo and Sahim, 2015; Ghritlahre and

385 Prasad, 2018; Ford et al. 2020; Hashemi et al., 2020; Guijo_Rubio et al., 2020;
 386 Delgado et al., 2020; Ghorpade et al., 2020; Hegde and Rokseth, 2020). In this paper,
 387 the algorithm for first-order gradient-based optimization of stochastic objective
 388 functions is adopted (Chang et al., 2019). It is based on adaptive estimates of
 389 lower-order moments:

$$g_t = \nabla_{\theta} J(\theta_{t-1}), m_t = \beta_1 m_{t-1} + (1 - \beta_1) g_t, \quad (22)$$

$$v_t = \beta_2 v_{t-1} + (1 - \beta_2) g_t^2, \hat{m}_t = \frac{m_t}{1 - \beta_1^t}, \hat{v}_t = \frac{v_t}{1 - \beta_2^t}, \theta_t = \theta_{t-1} - \frac{\alpha \times \hat{m}_t}{\sqrt{\hat{v}_t + \varepsilon}}$$

390 where m_t and v_t are the first-order and second-order momentum. β_1 and β_2 are
 391 their exponential decay rate while \hat{m}_t and \hat{v}_t are the corresponding modifications of
 392 m_t and v_t . α indicates the learning rate. ε is a very small constant to avoid
 393 denominator to be zero.

394

395 3.3 Verification of the trained ANN model

396 The test datasets are used to verify the prediction ability of the optimized ANN
 397 model. To have a more comprehensive and better comparison, some statistical error
 398 analysis parameters are used as criteria to evaluate the model.

399 The important statistical parameters used in this study include the relative error
 400 (RE), absolute relative error (ARE), average absolute relative error (AARE),
 401 maximum absolute relative error (Max-ARE), and coefficient of determination (R^2)
 402 (Hashemi et al., 2020). These parameters can be calculated as follows:

$$\mu_i = \frac{x_{ipr} - x_{iac}}{x_{iac}} \times 100\% \quad (23)$$

$$\mu_{ia} = |\mu_i| \quad (24)$$

$$\bar{\mu} = \frac{\sum_{i=1}^n \mu_{ia}}{n} \quad (25)$$

$$\mu_{max} = \max(\mu_{ia}) \quad (26)$$

$$R^2 = 1 - \frac{\sum_{i=1}^n (x_{iac} - x_{ipr})^2}{\sum_{i=1}^n (x_{ipr} - \bar{x})^2}, \bar{x} = \frac{\sum_{i=1}^n x_{iac}}{n} \quad (27)$$

403 In these relations, x_{iac} represents i -th actual value, x_{ipr} represents i -th predicted
 404 value, μ_i represents i -th RE, μ_{ia} represents i -th ARE, $\bar{\mu}$ represents AARE, μ_{max}
 405 represents Max-ARE.

406

407 **4. An ANN model to estimate T' and h'**

408 This section describes the building of an ANN method based model to predict T'
409 and h' and the evaluation of the developed model.

410 **4.1 Original dataset source**

411 Based on Eq. (16), the purpose here is to generate the dataset $(\rho, \phi, T', h', R_c, R_t)$.
412 In this study, a loop algorithm is used to generate 10,000 sets of data. The core steps
413 of the calculation are as follows.

414 **Step 1:** Randomly assign values to the four parameters (ρ, ϕ, T', h') respectively. The
415 selected value ranges are $\rho \in [0, 1]$, $\phi \in [0, 1]$, $T' \in [0, 1]$, $h' \in [0, 80]$. Then, go to step
416 2.

417 **Step 2:** Check whether each set assigned in the step 1 meets the requirement that the
418 denominator is not zero for the mathematical definition. Here one refers to: $T' \neq 0$,
419 $4T'^2 - 9 \neq 0$, $A' \neq 0$, $B' \neq 0$, $\frac{A'}{B'} + 1 \neq 0$, $1 + \frac{3\rho}{2} - \frac{5\rho}{6(\frac{A'}{B'} + 1)} \neq 0$. If it meets the
420 mathematical conditions, go to step 3, otherwise return to step 1.

421 **Step 3:** Bring the sets that meet the requirements in step 2 into Eq. (16) and solve it.
422 Then, go to step 4.

423 **Step 4:** Judge if the product of the two roots in step 3 is less than 0 (It is stipulated
424 that the compressive strength value is positive and the tensile strength value is
425 negative in Eq. (16), so the solution of the equation must be one positive and one
426 negative). If the product is less than 0, go to step 5, else return to step 1.

427 **Step 5:** The positive roots of Eq. (16) solved in step 4 are assigned to compressive
428 strength R_c , while the absolute value of negative root is assigned to tensile strength
429 R_t . Then, go to step 6.

430 **Step 6:** Check whether each value of R_c and R_t respectively meets: $1 < R_c < 100$
431 and $\frac{1}{20} * R_c < R_t < \frac{1}{10} * R_c$ (for most ordinary concrete materials, the compressive
432 strength is generally between 1 to 100 MPa, and the tensile strength is $\frac{1}{20}$ - $\frac{1}{10}$ times
433 the compressive strength (Gaedicke at al., 2020)). If yes, print $\rho, \phi, T', h', R_c, R_t$;

434 Else, return to step 1.

435 The flowchart for generating the dataset is shown in Fig. 8. A Python script was
 436 developed to automate the collection of data through the above process.

437

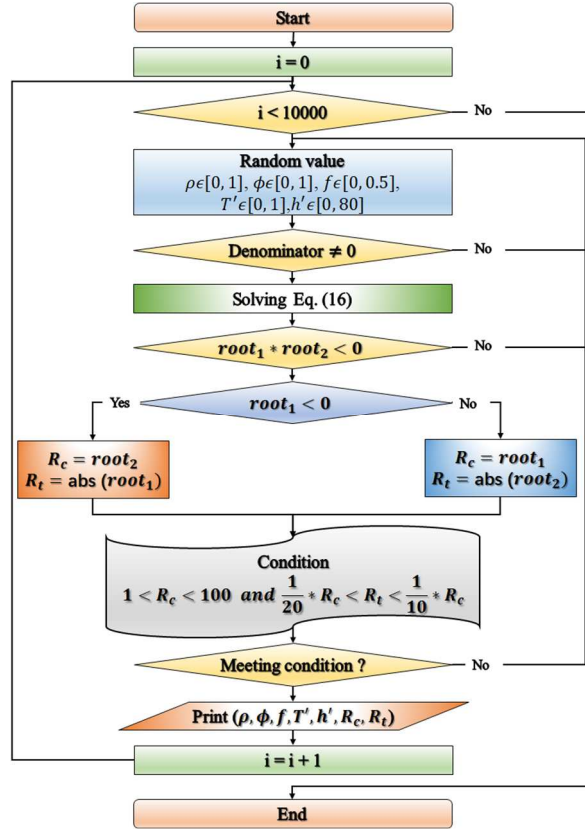


Fig. 8 The flowchart for data generation

438 4.2 Construction of the ANN model

439 In this study, an advanced open-source neural network library Keras (2020) is
 440 used to train the ANN model, able to run on TensorFlow (by Google), CNTK (by
 441 Microsoft), or Theano (Team et al., 2016). TensorFlow is employed in this work to
 442 solve the regression problem consisting in predicting the values of T' and h' . A BP
 443 neural network with four hidden layers and 100 neurons in each is constructed. The
 444 network structure is shown in Fig. 9. It is important to outpoint that the choice of
 445 ANN architecture is the first important step in developing an ANN model that best
 446 suits the problem in hand. Unfortunately, there is no guidance for selecting the
 447 optimal ANN architecture. For instance, the number of layers and neurons are two
 448 hyper-parameters of the model, which cannot be learnt during the training process. In

449 the present work, inspired by previous studies on similar problems (Asteris and
 450 Plevris, 2017; Asteris and Mocos, 2020; Ford et al. 2020; Konstantopoulos et al.,
 451 2020), preliminary calculations were performed by taking different numbers of layers
 452 and neurons. The accuracy and loss function were compared. Based on such
 453 comparisons, the ANN architecture shown in Fig. 9 is chosen. As it will be shown in
 454 Section 4.3, this architecture provides a very high accuracy. The input/output data and
 455 hyper-parameters for this study are presented in Table 1. The MSE is used as the loss
 456 function and the Adam ($\beta_1 = 0.9$, $\beta_2 = 0.999$, $\alpha = 0.001$, $\varepsilon = 10e^{-8}$) is adopted
 457 as the optimizer. The training and validation processes are illustrated in terms of the
 458 MAE. Further, the Batch-size is 50 and maximum number of epochs is 10,000 for
 459 training.

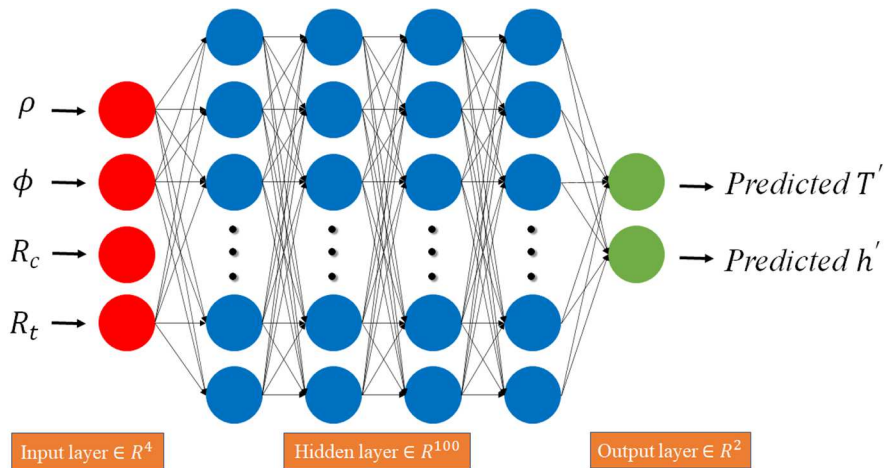


Fig.9. Established BP neural network model

460

461

Table 1: Hyper-parameters of the ANN model for prediction of T' and h'

Input layer	Hidden layer	Output layer	Loss function	Optimizer
ρ, ϕ, R_c, R_t	$4 \times 100 \times \text{ReLU}$	T', h'	MSE	Adam

462

463 Another important step for constructing an ANN model is the choice of
 464 activation function. As mentioned in sub-section 3.2, there are five widely used
 465 activation functions for ANN models. In order to make our choice, we have made
 466 preliminary calculations in order to compare these five functions, by using 6000 data
 467 sets for training, 2000 for validation and 2000 for test of the ANN model. It was seen
 468 that the output results of the activation functions ReLU, sigmoid and softplus were

469 among the best ones in terms of MAE, MSE and R^2 . The differences between them
 470 were very small. The quality of two other functions was clearly below these three. As
 471 ReLU is well-known in literature and widely used in previous studies, it is taken in
 472 this work. It is a traditional and efficient activation function with two main advantages:
 473 more efficient gradient descent and back propagation, and simpler calculation process.
 474

475 4.3 Verification of the trained model

476 The evolutions of the loss function and the MAE of the training set and the
 477 validation set in the training data are illustrated in Fig. 10 as functions of the number
 478 of epochs. It can be seen that the proposed neural network model converges very
 479 quickly. After continuous learning and self-adjustment of the network, the loss
 480 function drops rapidly. Simultaneously, the MAE is further reduced. The final values
 481 of MAE and loss function are 1.03625×10^{-3} and 2.05×10^{-6} for the training dataset
 482 and 8.18333×10^{-4} , 1.36×10^{-6} for the validation dataset.
 483

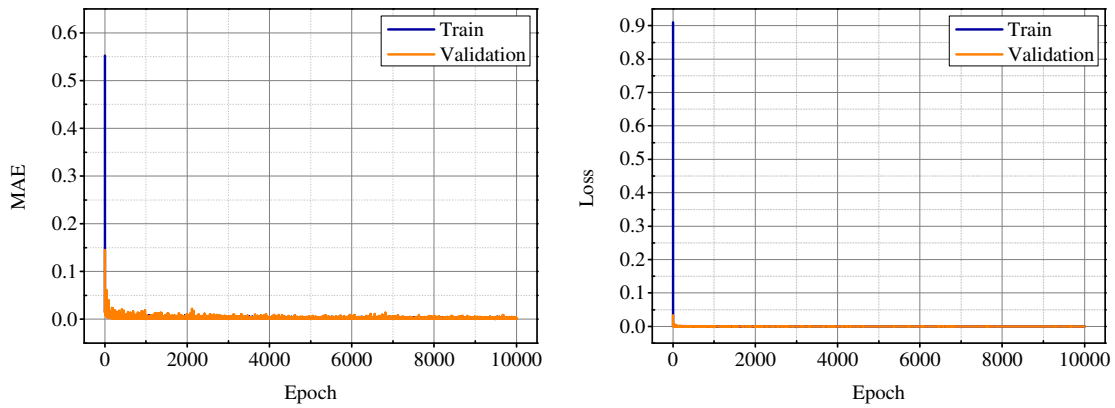


Fig. 10. MAE and loss function evolution during training process

484

485 In order to evaluate the accuracy of ANN-based model, in Fig. 11, one shows the
 486 relative errors of predicted T' and h' for 2,000 selected data. For the value of T' ,
 487 most of the relative errors are between ± 0.15 while those of h' are between ± 0.25 . In
 488 Fig. 12, one plots the predicted values versus exact ones to visualize their correlations.
 489 Very high values of R^2 are obtained (0.997 for T' and 1 for h'). These results
 490 indicate the high prediction accuracy of the BP neural network model.

491

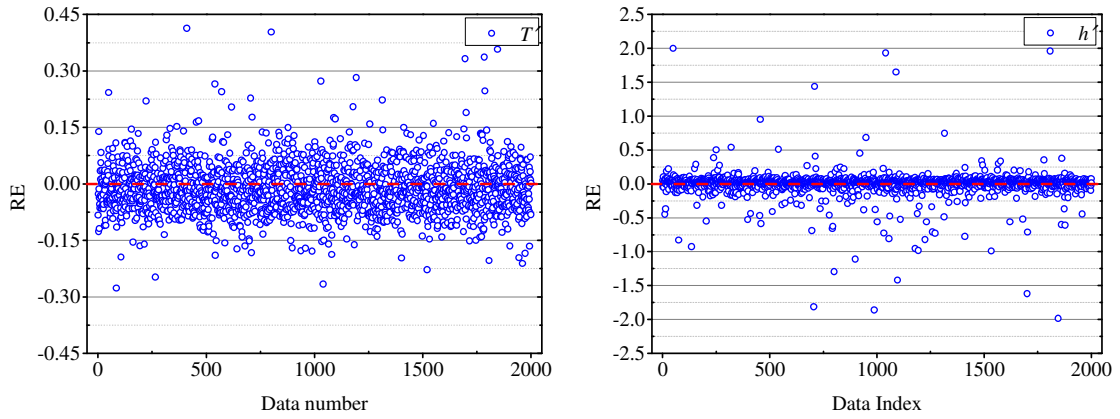


Fig. 11: Relative errors (RE) of predicted microscopic strength parameters

492

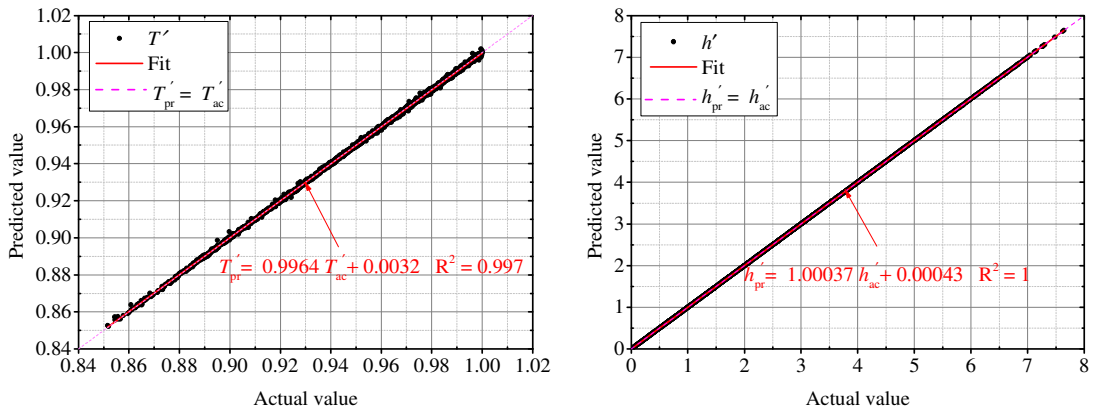


Fig. 12: Correlation between predicted and exact values of T' and h'

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Further, in Fig. 13, one shows the direct comparisons between the predicted and exact values of T' and h' for 200 data sets, together with the relative errors (RE). It can be seen that for most of the selected data points, the relative errors are relatively small (except several noises). This again demonstrates that the BP neural network model has a high accuracy.

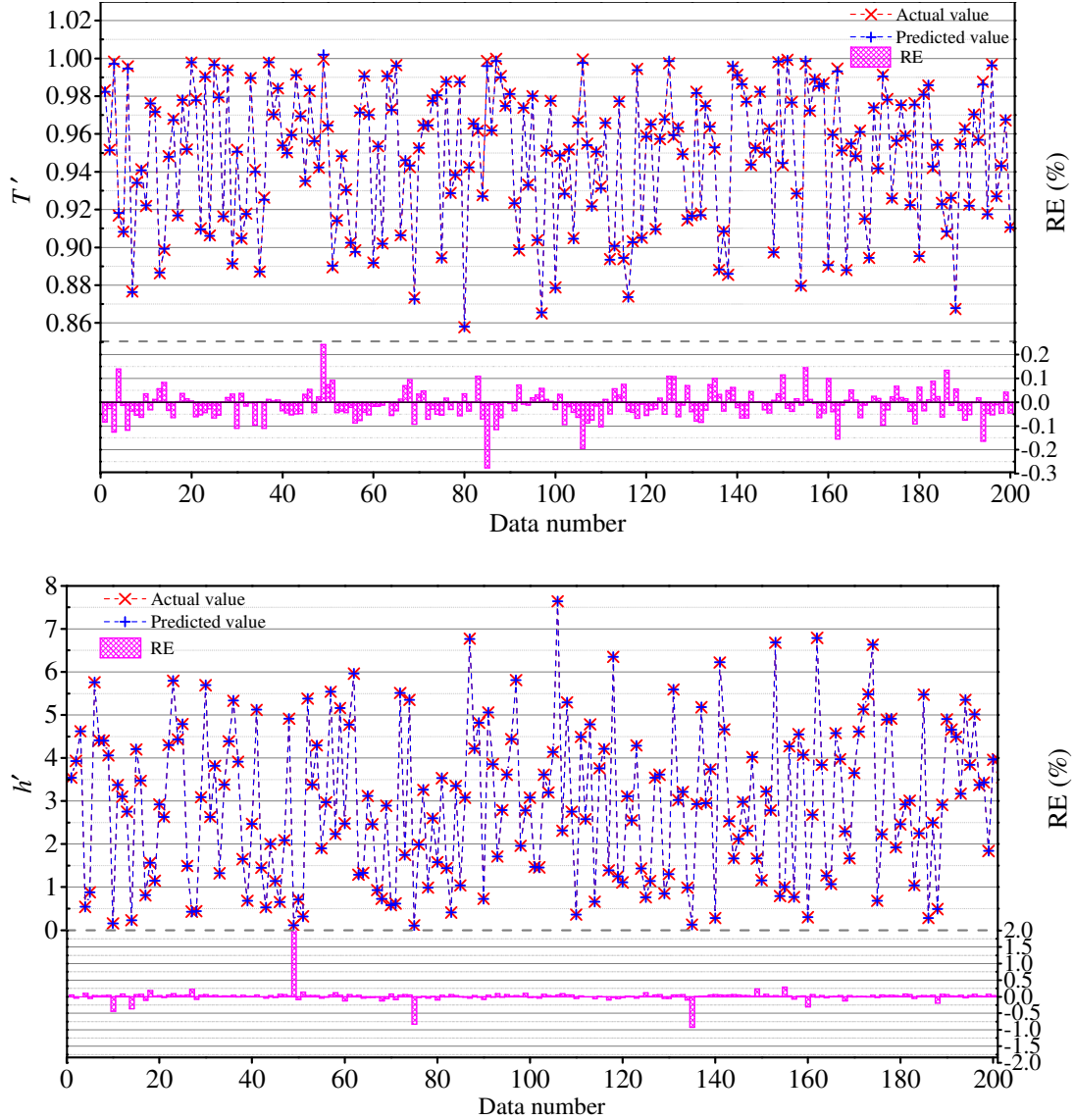


Fig. 13. Comparisons between predicted and exact values of T' and h' for 200 data sets

500

501 In order to better understand the error origin of the proposed model, more
 502 detailed analyses are presented in Fig. 14 and Fig. 15. From Fig. 14, one can see that
 503 the Max-ARE of T' and h' are 0.41% and 2.0%, and their AARE are 0.05% and
 504 0.07%, respectively. In addition, ARE of T' is less than 0.13% for 95% of the data,
 505 and higher than 0.27% for only 0.5%. Similarly, ARE of h' is 1.42% for 95% of the
 506 data and 0.2% for only 0.5%. In Fig. 15, the values of ARE are classified in four
 507 levels respectively in terms of $ARE > 1\%$, $0.5\% < ARE < 1\%$, $0.2\% < ARE < 0.5\%$,
 508 and $ARE < 0.2\%$. The amount of data whose error is less than 1% occupies more than

509 99.4% for predicting T' and h' . There is an excellent predictive accuracy for the
 510 ANN-based model. The detailed comparisons between the test data obtained from the
 511 analytical strength criterion and the predicted values of friction T' and cohesion h'
 512 are also presented in the shared file mentioned in the Supplementary Information at
 513 the end of the paper.

514 However, it is worth noticing that for engineering application purpose, it would
 515 be necessary to check the accuracy of the ANN based method by comparing
 516 numerical predictions with experimental results. We recall that the main objective of
 517 the present work is to identify the microscopic strength parameters (friction and
 518 cohesion) of porous cements paste from the measured macroscopic strength
 519 parameters (uniaxial compression and tension strengths). Therefore, for a complete
 520 experimental validation, it is need to have a complete set of experimental data on
 521 concrete samples with known micro-structures for which both macroscopic and
 522 microscopic strength parameters are measured. Unfortunately, we do not have so far
 523 such data in hand. We shall take up this exciting challenge in future studies. Therefore,
 524 the accuracy of the proposed ANN based model is verified by comparisons with the
 525 analytical solutions.

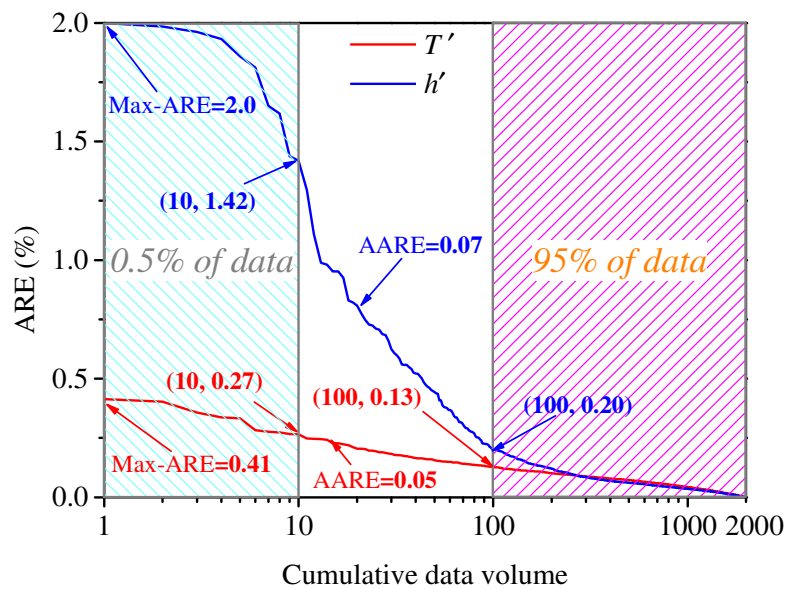


Fig. 14. ARE distribution of T' and h'

526

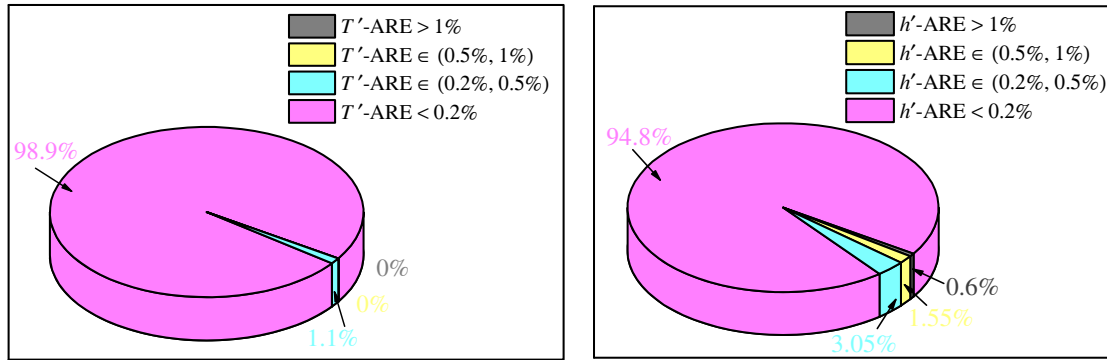


Fig. 15. Proportions of errors of T' and h' in terms of four levels of ARE

527 5. Conclusions

528 In this paper, an ANN based numerical method has been developed for
 529 identification of microscopic strength properties of concrete-like composites. This
 530 method can be also applied to other types of heterogeneous materials. Therefore, this
 531 machine-learning method provides an efficient way for the calibration of local
 532 properties of constituent phases at different scales, a crucial challenge of multi-scale
 533 modeling of heterogeneous materials.

534 In the present study, the dataset used for training and validation was generated
 535 with the help of a close-form strength criterion issued from an analytical
 536 homogenization procedure. This dataset can be enriched by any other kinds of data,
 537 either from direct numerical simulations of micro-structures or experimental tests.

538 In the case considered here, the proposed method has shown a very good
 539 accuracy for the prediction of frictional coefficient and cohesion of cement paste at
 540 the microscopic scale. The ANN model contained a BP algorithm and four hidden
 541 layers with 100 neurons in each one. With a database of 10,000 sets, the probability of
 542 the absolute relative error (ARE) of less than 1% exceeds 99%.

543 In future studies, with the enrichment of dataset by adding results from direct
 544 simulations of different types of micro-structures, in particular by considering ITZ, it
 545 will be possible to directly evaluate macroscopic mechanical properties of concrete
 546 materials, for which any analytical homogenization solutions cannot be found. Also,
 547 with the ANN based inverse optimization method proposed here, it will be also
 548 identify local mechanical properties of constituents in complex micro-structural

549 morphology such as those of ITZ. As an exciting challenge, the efficiency of the
550 proposed ANN based method can also be verified by suitable experimental data. For
551 this purpose, multi-scale laboratory tests should be performed on typical concrete
552 samples with controlled micro-structures (porosity, mineral compositions,
553 morphology) for which both macroscopic and microscopic mechanical properties can
554 be measured.

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