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## - To cite this version:

Éric Gaudron. ADELIC APPROXIMATION ON SPHERES. 2023. hal-04507592

## HAL Id: hal-04507592 <br> https://hal.science/hal-04507592

Preprint submitted on 16 Mar 2024

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# ADELIC APPROXIMATION ON SPHERES 

ÉRIC GAUDRON


#### Abstract

We establish an adelic version of Dirichlet's approximation theorem on spheres. Let $K$ be a number field, $E$ be a rigid adelic space over $K$ and $q: E \rightarrow K$ be a quadratic form. Let $v$ be a place of $K$ and $\alpha \in E \otimes_{K} K_{v}$ such that $q(\alpha)=1$. We produce an explicit constant $c$ having the following property. If there exists $x \in E$ such that $q(x)=1$ then, for any $T>c$, there exists $(v, \phi) \in E \times K$, with $\max \left(\|v\|_{E, v},|\phi|_{v}\right) \leq T$ and $\max \left(\|v\|_{E, w},|\phi|_{w}\right)$ controlled for any place $w$, satisfying $q(v)=\phi^{2} \neq 0$ and $|q(\alpha \phi-v)|_{v} \leq c|\phi|_{v} / T$. This remains true for some infinite algebraic extensions as well as for a compact set of places of $K$. Our statements generalize and improve on earlier results by Kleinbock \& Merrill (2015) and Moshchevitin (2017). The proofs rely on the quadratic Siegel's lemma in a rigid adelic space obtained by the author and Rémond (2017).


## 1. Introduction

Let $n \geq 1$ be an integer and $q: \mathbb{R}^{n} \rightarrow \mathbb{R}$ be a positive-definite quadratic form. The Euclidean variant of Dirichlet's approximation theorem asserts that, for any $\alpha \in \mathbb{R}^{n}$ and any real number $T>0$, there exists $(v, \phi) \in\left(\mathbb{Z}^{n} \times \mathbb{Z}\right) \backslash\{0\}$ such that

$$
0 \leq \phi \leq T \quad \text { and } \quad q(\alpha \phi-v) \leq \frac{n(\operatorname{det} q)^{1 / n}}{T^{2 / n}}
$$

where $\operatorname{det} q$ is the determinant of the symmetric matrix $A(q)$ associated to the quadratic form $q$ (in the canonical basis of $\mathbb{R}^{n}$ ). Its proof consists in applying Minkowski's theorem to the lattice $\mathbb{Z}^{n} \times \mathbb{Z}$ endowed with the Euclidean structure $q(\alpha \phi-v)+a \phi^{2}$ for a well-chosen positive real number $a$. In 2015, Kleinbock and Merrill published a similar statement in the particular case $q(x)=x_{1}^{2}+\cdots+x_{n}^{2}$ but with the additional property $q(v)=\phi^{2}$ satisfied by the solution $(v, \phi)[\mathrm{KM}]$. In their result $q(\alpha \phi-v)$ is bounded by $c(n) \phi / T$ for some positive constant $c(n)$. A generalization to any positivedefinite quadratic form such that $A(q) \in \mathrm{M}_{n}(\mathbb{Z})$ has been achieved by Moshchevitin [Mo] who, besides, gave an explicit constant depending on $n$ and $\operatorname{det} q$.

The aim of this article is to improve these constants while simplifying the proofs and providing an adelic generalization. Our first result makes use of the Hermite constant $\gamma_{n}$ in dimension $n$ which is the greatest first minimum of unimodular lattices in the Euclidean space $\mathbb{R}^{n}$.

Theorem 1.1. Let $q: \mathbb{R}^{n} \rightarrow \mathbb{R}$ be a positive-definite quadratic form such that $A(q)$ has integral coefficients. Assume that there exists $x \in \mathbb{Q}^{n}$ such that $q(x)=1$. Then, for all $\alpha \in \mathbb{R}^{n}$ such that $q(\alpha)=1$, for all real number $T \geq\left(2 \gamma_{n}\right)^{n / 2} \sqrt{\operatorname{det} q}$, there exist $v \in \mathbb{Z}^{n}$ and $\phi \in \mathbb{Z}$ with $1 \leq \phi \leq T$ satisfying

$$
q\left(\frac{v}{\phi}\right)=1 \quad \text { and } \quad q\left(\alpha-\frac{v}{\phi}\right) \leq \frac{\sqrt{8}\left(2 \gamma_{n}\right)^{n} \operatorname{det} q}{\phi T}
$$

Applying this statement to

$$
T^{\prime}=\max \left(T, \frac{\left(2 \gamma_{n}\right)^{n} \operatorname{det} q}{T}\right)
$$

for $T>0$, which always satisfies the condition $T^{\prime} \geq\left(2 \gamma_{n}\right)^{n / 2} \sqrt{\operatorname{det} q}$, leads to a variant where $T$ is only assumed to be positive. Besides the real number $\sqrt{8}\left(2 \gamma_{n}\right)^{n} \operatorname{det} q$ is smaller than the $n$th

[^0]root of the constant $\kappa_{f}$ which is in [Mo, Theorem 1] but we were unable to determine whether the dependency in $\operatorname{det} q$ is optimal or not.

The proof consists in finding a small isotropic vector $(v, \phi)$ of the quadratic form $Q(x, y)=$ $q(x)-y^{2}$ with the quadratic Siegel's lemma obtained by the author and Remond [GR2, Theorem 1.2]. In order to ensure the smallness of $q(\alpha \phi-v)$ we twist the product norm on $\mathbb{R}^{n} \times \mathbb{R}$ with a well-chosen isometry of $Q$, which is the argument at the heart of Kleinbock and Merrill's proof (written differently). Our proof is also inspired by Moshchevitin's proof, but we avoid any choice of basis. A generalization involving an algebraic extension $K$ of $\mathbb{Q}$ and several (archimedean or ultrametric) places of $K$ will be given in $\S 4$. The main argument of the proof is the same as the one of Theorem 1.1, but some new difficulties appear since the condition $\phi \neq 0$ is not automatic when $q$ is not anisotropic. That is why we prefer to start by proving this particular case.

Acknowledgement. I thank Gaël Rémond for his remarks on a previous version of this article.

## 2. Proof of Theorem 1.1

Let $\alpha \in \mathbb{R}^{n}$ such that $q(\alpha)=1$. Denote by $b: \mathbb{R}^{n} \times \mathbb{R}^{n} \rightarrow \mathbb{R}$ be the symmetric bilinear form associated to $q$.
2.1. The Euclidean lattice. Fix a real number $t \geq 1$. For any $(x, y) \in \mathbb{R}^{n} \times \mathbb{R}$, let us consider

$$
X=\frac{1}{2}\left(\frac{1}{t}+t\right) b(x, \alpha)+\frac{1}{2}\left(\frac{1}{t}-t\right) y \quad \text { and } \quad y=\frac{1}{2}\left(\frac{1}{t}-t\right) b(x, \alpha)+\frac{1}{2}\left(\frac{1}{t}+t\right) y
$$

as well as the linear map $\xi$ defined by $\xi(x, y)=(x-b(x, \alpha) \alpha+X \alpha, y)$. It is an automorphism of $\mathbb{R}^{n} \times \mathbb{R}$ of determinant 1. Indeed, since $q(\alpha) \neq 0$, the $q$-orthogonal subspace $\left\{x \in \mathbb{R}^{n} ; b(x, \alpha)=0\right\}$ is a supplement to $\mathbb{R} . \alpha$ in $\mathbb{R}^{n}$. The choice of a basis $e_{1}, \ldots, e_{n-1}$ of this hyperplane provides a basis $\left(e_{1}, 0\right), \ldots,\left(e_{n-1}, 0\right),(\alpha, 0),(0,1)$ of $\mathbb{R}^{n} \times \mathbb{R}$ in which the matrix of $\xi$ is written

$$
\left(\begin{array}{cc}
\mathrm{I}_{n-1} & 0 \\
0 & A
\end{array}\right) \quad \text { where } \quad A=\frac{1}{2}\left(\begin{array}{cc}
1 / t+t & 1 / t-t \\
1 / t-t & 1 / t+t
\end{array}\right) \quad \text { has determinant } 1 .
$$

Thus, the Euclidean norm $\|(x, y)\|=\left(q(x)+y^{2}\right)^{1 / 2}$ on $\mathbb{R}^{n} \times \mathbb{R}$ induces another norm $\|(x, y)\|_{t}=$ $\|\xi(x, y)\|$. In that way, we get an Euclidean lattice $E_{t}=\left(\mathbb{Z}^{n} \times \mathbb{Z},\|\cdot\|_{t}\right)$ whose volume does not depend on $t$ :

Lemma 2.1. The volume of $E_{t}$ is equal to $\sqrt{\operatorname{det} q}$.
Proof. The volume of $E_{t}$ is also that of $\xi\left(\mathbb{Z}^{n} \times \mathbb{Z}\right)$ with respect to the norm $\|\cdot\|$ that is, $|\operatorname{det} \xi| \times$ $\operatorname{vol}\left(\mathbb{Z}^{n} \times \mathbb{Z},\|\cdot\|\right)=\sqrt{\operatorname{det} q}$.
2.2. The quadratic form. Consider the regular quadratic form $Q(x, y)=q(x)-y^{2}$ on $\mathbb{Q}^{n} \times$ $\mathbb{Q}$ which is isotropic by hypothesis. Using that $x-b(x, \alpha) \alpha$ is $q$-orthogonal to $\alpha$, the equality $Q(\xi(x, y))=Q(x, y)$ can be checked for all $(x, y) \in \mathbb{R}^{n} \times \mathbb{R}$ with a direct calculation. In other words:

Lemma 2.2. The map $\xi$ is isometric with respect to $Q$.
At last, at every place $p$ of $\mathbb{Q}$, we can consider the norm $\|B\|_{p}$ of the bilinear form $B$ associated to $Q$ defined by

$$
\|B\|_{\infty}=\sup \left\{\left.\frac{\left|B\left((x, y),\left(x^{\prime}, y^{\prime}\right)\right)\right|}{\|(x, y)\|_{t}\left\|\left(x^{\prime}, y^{\prime}\right)\right\|_{t}} \right\rvert\,(x, y),\left(x^{\prime}, y^{\prime}\right) \in\left(\mathbb{R}^{n} \times \mathbb{R}\right) \backslash\{0\}\right\}
$$

in the archimedean case and by $\|B\|_{p}=\max _{0 \leq i, j \leq n}\left|B\left(e_{i}, e_{j}\right)\right|_{p}$ where $\left\{e_{0}, \ldots, e_{n}\right\}$ is the canonical basis of $\mathbb{Z}^{n+1}$ and the absolute value $|\cdot|_{p}$ on $\mathbb{Q}_{p}$ normalised with $|p|_{p}=p^{-1}$. By definition, the height $H(Q)$ of $Q$ is the product of all the norms $\|B\|_{p}$ over the places $p$ of $\mathbb{Q}$. Here we have the formula $B\left((x, y),\left(x^{\prime}, y^{\prime}\right)\right)=b\left(x, x^{\prime}\right)-y y^{\prime}$ which immediatly implies $\|B\|_{p}=1$ for all prime number $p$ since $b$ has integral coefficients. Moreover, as $\xi$ is a global isometry with respect to $Q$, we also have $\|B\|_{\infty}=\sup \left\{\left|B\left((x, y),\left(x^{\prime}, y^{\prime}\right)\right)\right| \mid\|(x, y)\|=\left\|\left(x^{\prime}, y^{\prime}\right)\right\|=1\right\}$. Then, Cauchy-Schwarz inequality applied to the positive-definite quadratic form $q(x)+y^{2}=\|(x, y)\|^{2}$ gives $\|B\|_{\infty}=1$. Hence, the height $H(Q)$ of $Q$ equals to 1 .
2.3. The quadratic Siegel's lemma. We now apply [GR2, Theorem 1.3] to the quadratic space $\left(E_{t}, Q\right)$ over $\mathbb{Q}$ (of dimension $n+1$ ) and we get $(v, \phi) \in \mathbb{Z}^{n} \times \mathbb{N}_{\geq 1}$ such that $Q(v, \phi)=0$ and

$$
\|(v, \phi)\|_{t} \leq\left(2 \gamma_{n} H(Q)\right)^{n / 2} H\left(E_{t}\right)
$$

(the height of a vector of $E_{t}$ equals to the norm of a multiple of this element, see [Ga2, Example 2 p.46]). The height $H\left(E_{t}\right)$ of $E_{t}$ is nothing but the volume of ( $\mathbb{Z}^{n} \times \mathbb{Z},\|\cdot\|_{t}$ ) [Ga2, p. 43] that is, $\sqrt{\operatorname{det} q}$ by Lemma 2.1. Also note that the constant $c_{\mathbb{Q}}^{\mathrm{BV}}(n)$ in the original statement is simply $\gamma_{n}^{n / 2}$ (see §4.1). As $H(Q)=1$ we get $\|(v, \phi)\|_{t} \leq\left(2 \gamma_{n}\right)^{n / 2} \sqrt{\operatorname{det} q}$ with $q(v / \phi)=1$.
2.4. Conclusion. We observe that

$$
q\left(\alpha-\frac{v}{\phi}\right)=\frac{2}{\phi}(\phi-b(v, \alpha))=\frac{2}{\phi t}(y-X)
$$

where $X, y$ are relative to $(v, \phi)$. Hence, since $X^{2}+y^{2} \leq q(v-b(v, \alpha) \alpha)+X^{2}+y^{2}=\|(v, \phi)\|_{t}^{2}$, Cauchy-Schwarz inequality provides the bound $q\left(\alpha-\frac{v}{\phi}\right) \leq 2 \sqrt{2}\|(v, \phi)\|_{t} / \phi t$. Next we note that, since $t \geq 1$,

$$
\phi=\frac{1}{2}\left(t-\frac{1}{t}\right) x+\frac{1}{2}\left(t+\frac{1}{t}\right) y \leq t \max (|X|,|y|) \leq t\|(v, \phi)\|_{t}
$$

We replace $\|(v, \phi)\|_{t}$ by $\left(2 \gamma_{n}\right)^{n / 2} \sqrt{\operatorname{det} q}$ and we set $T=t\left(2 \gamma_{n}\right)^{n / 2} \sqrt{\operatorname{det} q}$ to end the proof of Theorem 1.1.

## 3. Extended statement

In Theorem 1.1 the form $q$ plays two distinct roles since it is used both to define the set (ellipsoid) where the approximation takes place and to measure the quality of approximation. We can give a more general statement in which two quadratic forms appear: we will approximate points on $q=1$ using another quadratic form $q_{0}$ to measure the size of the approximation. Here it is natural to retain the hypothesis that $q_{0}$ be positive-definite but we can relax the condition on $q$, allowing some non definite forms.

Let $E$ be a vector space over a field $K$ and $q: E \rightarrow K$ a quadratic form. The isotropy index $i(q)$ of $q$ is the maximal dimension of totally isotropic subspaces of $q$. The induced quadratic form $Q(x, y)=q(x)-y^{2}$ on $E \times K$ verifies $i(Q)-i(q) \in\{0,1\}$. In fact $i(Q)=i(q)+1$ when the anisotropic part of $q$ in the Witt decomposition takes the value 1. Given a positive-definite quadratic form $q_{0}: \mathbb{R}^{n} \rightarrow \mathbb{R}$, we denote by $\|\cdot\|=\sqrt{q_{0}}$ the associated Euclidean norm on $\mathbb{R}^{n}$ and by $\lambda_{1}=\min \left\{\|\lambda\| \mid \lambda \in \mathbb{Z}^{n} \backslash\{0\}\right\}$ the first minimum of the Euclidean lattice $\left(\mathbb{Z}^{n},\|\cdot\|\right.$ ). A quadratic form $q(x)={ }^{\mathrm{t}} x A(q) x$ associated with a symmetric matrix $A(q) \in \mathrm{M}_{n}(\mathbb{R})$ (not necessarily positive-definite) also inherits a norm by the formula

$$
\|q\|_{\infty}=\max \left\{{ }^{\mathrm{t}} x A(q) y \mid x, y \in \mathbb{R}^{n},\|x\|=\|y\|=1\right\}
$$

In this context we have the following statement.
Theorem 3.1. Let $\alpha \in \mathbb{R}^{n}$ such that $q(\alpha)=1$. Define

$$
\mathcal{T}_{0}=n^{n / 2}\left(2 \max \left(1,\|q\|_{\infty}\right)\right)^{(n-i(q)) / 2}\|\alpha\| \sqrt{\operatorname{det} q_{0}}
$$

and $\mathcal{T}=\max \left(\mathcal{T}_{0}^{1 /(i(q)+1)},\left(\sqrt{2} / \lambda_{1}\right)^{i(q)} \mathcal{T}_{0}\right)$. Assume that $A(q) \in \mathrm{M}_{n}(\mathbb{Z})$ and that $i(Q)>i(q)$ where $Q(x, y)=q(x)-y^{2}$. Then, for all real number $T \geq \mathcal{T}$, there exists $(v, \phi) \in \mathbb{Z}^{n} \times \mathbb{Z}$ satisfying $q(v)=\phi^{2} \neq 0$,

$$
\|v\|^{2}+(\phi\|\alpha\|)^{2} \leq\left(\|\alpha\|\|b(\cdot, \alpha)\|_{\mathrm{op}, \infty} T\right)^{2} \quad \text { and } \quad|q(\alpha \phi-v)| \leq \frac{2 \sqrt{2} \mathcal{T}^{2} \phi}{T} \times\|b(\cdot, \alpha)\|_{\mathrm{op}, \infty}
$$

Here $\|b(\cdot, \alpha)\|_{\mathrm{op}, \infty}$ denotes the operator norm of the linear form $x \mapsto b(x, \alpha)={ }^{\mathrm{t}} x A(q) \alpha$ on $\left(\mathbb{R}^{n},\|\cdot\|\right)$. It can be bounded by $\|q\|_{\infty}\|\alpha\|$. If the proof of Theorem 3.1 follows the same lines as those of Theorem 1.1, the new difficulty is to ensure $\phi \neq 0$ even though $q$ is not assumed to be definite. To solve this problem, we introduce a maximal totally $Q$-isotropic sublattice $\Omega$ of $\mathbb{Z}^{n} \times \mathbb{Z}$ of small volume and we distinguish two cases according to the value of the first minimum of $\Omega$. The proof is a special case of that of Theorem 4.1 (see §4.4). Let us just say that the quantity $n^{n}$
in $\mathcal{T}_{0}$ is a bound for $\gamma_{i(q)+1}^{i(q)+1} \gamma_{n-i(q)}^{n-i(q)}$ which appears in $\mathcal{T}_{0}$ during the proof (see Theorem 4.1 and the discussion at the end of the article).

## 4. Adelic generalization

4.1. Let $K / \mathbb{Q}$ be an algebraic extension. Its set of places has a structure of topological measure space $(V(K), \sigma)$ described in [GR1, § 2]. For $v \in V(K)$ we denote by $K_{v}$ the topological completion of $K$ at $v$ and $|\cdot|_{v}$ is the unique absolute value on $K_{v}$ such that $|p|_{v} \in\left\{1, p, p^{-1}\right\}$ for every prime number $p$. The module $|f|$ of an integrable bounded function $f: V(K) \rightarrow(0+\infty)$ such that $\{v \in V(K) ; f(v) \neq 1\}$ is contained in a compact subset is the positive real number

$$
|f|=\exp \left(\int_{V(K)} \log (f(v)) \mathrm{d} \sigma(v)\right)
$$

Given an integer $n \geq 1$, a place $v \in V(K)$ and $x=\left(x_{1}, \ldots, x_{n}\right) \in \mathbb{R}^{n}$, write

$$
m_{v}(x)= \begin{cases}\left(x_{1}^{2}+\cdots+x_{n}^{2}\right)^{1 / 2} & \text { if } v \mid \infty \\ \max \left(x_{1}, \ldots, x_{n}\right) & \text { if } v \nmid \infty\end{cases}
$$

Then $|x|_{v}=m_{v}\left(\left|x_{1}\right|_{v}, \ldots,\left|x_{n}\right|_{v}\right)$ defines a norm on $K_{v}^{n}$ for all $v \in V(K)$. Let $\mathbb{A}_{K}=K \otimes \mathbb{Q}_{\mathbb{Q}} \mathbb{A}_{\mathbb{Q}}$ be the adèles of $K$. A rigid adelic space (of dimension $n$ ) is a $n$-dimensional $K$-vector space $E$ endowed with norms $\|\cdot\|_{E, v}$ on $E_{v}=E \otimes_{K} K_{v}$ for all $v \in V(K)$, satisfying the following property: there exist an isomorphism $\varphi: E \rightarrow K^{n}$ and an adelic matrix $\left(A_{v}\right)_{v \in V(K)} \in \mathrm{GL}_{n}\left(\mathbb{A}_{K}\right)$ such that

$$
\forall x \in E_{v}, \quad\|x\|_{E, v}=\left|A_{v} \varphi_{v}(x)\right|_{v}
$$

where $\varphi_{v}=\varphi \otimes \operatorname{id}_{K_{v}}: E_{v} \rightarrow K_{v}^{n}$ is the natural extension of $\varphi$ to $E_{v}$. The height $H(E)$ of $E$ is the module of $v \mapsto\left|\operatorname{det} A_{v}\right|_{v}$ and the height $H_{E}(x)$ of $x \in E \backslash\{0\}$ is the module of $v \mapsto\|x\|_{E, v}$. The dual space $E^{\vee}$ has a rigid adelic structure given by the transpose map ${ }^{\mathrm{t}} \varphi^{-1}: E^{\vee} \rightarrow K^{n}$ and $\left({ }^{\mathrm{t}} A_{v}^{-1}\right)_{v \in V(K)}$. Besides the product $E \times K$ has a natural rigid adelic structure given by the norms $\|(x, y)\|_{E \times K, v}=m_{v}\left(\|x\|_{E, v},|y|_{v}\right)$ for all $(x, y) \in E_{v} \times K_{v}$.

To a rigid adelic space $E$ over $K$ can be attached its first minimum of Roy-Thunder $\lambda_{1}^{\Lambda}(E)=$ $\inf \left\{H_{E}(x) ; x \in E \backslash\{0\}\right\}$ and its first minimum of Bombieri-Vaaler $\lambda_{1}^{\mathrm{BV}}(E)$ which is the infimum of $r>0$ such that there exists $x \in E \backslash\{0\}$ satisfying $\sup _{v \mid \infty}\|x\|_{E, v} \leq r$ and $\sup _{v \nmid \infty}\|x\|_{E, v} \leq 1$ (note that $\left.\lambda_{1}^{\Lambda}(E) \leq \lambda_{1}^{\mathrm{BV}}(E)\right)$. The last minimum $\lambda_{n}^{*}(E)$ is defined in the same way where $x$ is replaced by the vectors of a basis of $E$. They give rise to the following constants: Given $* \in\{\Lambda, B V\}$ and a positive integer $n$, let us define

$$
c_{K}^{*}(n)=\sup _{E} \frac{\lambda_{1}^{*}(E)^{n}}{H(E)} \in(0,+\infty]
$$

where $E$ varies among the rigid adelic spaces over $K$ of dimension $n$. Recall that Minkowski's second theorem implies $\left(\lambda_{1}^{*}(E)\right)^{n-1} \lambda_{n}^{*}(E) \leq c_{K}^{*}(n) H(E)$ [GR1, Theorem 4.12] and, if we set $c_{1}(K)=$ $c_{K}^{\mathrm{BV}}(1)$, then $\lambda_{i}^{\mathrm{BV}}(E) \leq c_{1}(K) \Lambda_{i}(E)$ for all $1 \leq i \leq n$ [GR1, Proposition 4.8] and so $c_{K}^{\mathrm{BV}}(n) \leq$ $c_{1}(K)^{n} c_{K}^{\Lambda}(n)$. For all $*$, we have $c_{\mathbb{Q}}^{*}(n)=\gamma_{n}^{n / 2}$ and $c_{K}^{*}(n) \leq\left(n \delta_{K / \mathbb{Q}}\right)^{n / 2}$ when $K$ is a number field of root discriminant $\delta_{K / \mathbb{Q}}$ [GR1, Proposition 5.1]. It is also known [GR1, §5.2] that $c_{\mathbb{Q}}^{*}(1)=1$ and, for $n \geq 2$,

$$
c_{\overline{\mathbb{Q}}}^{*}(n)=\exp \left(\frac{n}{2}\left(\frac{1}{2}+\cdots+\frac{1}{n}\right)\right)
$$

However, the constant $c_{K}^{*}(n)$ may be infinite when $n \geq 2$. For instance, this is the case when $K$ is a Northcott field of infinite degree (see Corollary 1.2 and Proposition 4.10 of [GR1]). We say that $K$ is a Siegel field if $c_{K}^{\Lambda}(n)$ is finite for all $n \geq 1$. At last, a quadratic space $(E, q)$ is a rigid adelic space $E$ endowed with a quadratic form $q: E \rightarrow K$. For $v \in V(K)$ and $b: E \times E \rightarrow K$ the symmetric bilinear form associated to $q$, the norm $\|q\|_{v}$ is the supremum of $|b(x, y)|_{v} /\|x\|_{E, v}\|y\|_{E, v}$ for non-zero $x, y \in E \otimes_{K} K_{v}$. The height $H(q)$ of $q$ is the module of $v \mapsto\|q\|_{v}$ if $q \neq 0$ and 0 otherwise. We also write $H(1, q)$ for the module of $v \mapsto \max \left(1,\|q\|_{v}\right)$.
4.2. Main statements. Let $K / \mathbb{Q}$ be a Siegel field and let $(E, q)$ be an adelic quadratic space over $K$ of dimension $n \geq 1$. We present two statements according to the isotropy index of the quadratic form $Q(x, y)=q(x)-y^{2}$ on $E \times K$, which, as we have seen, is equal to $i(q)$ or $i(q)+1$. Let us begin with the case $i(Q)=i(q)+1$. For $v \in V(K)$, write $\epsilon_{v}=1$ if $v \mid \infty$ and 0 otherwise.

Theorem 4.1. Let $V \subset V(K)$ be a compact subset. Let $\left(\alpha_{v}, t_{v}\right)_{v \in V(K)} \in(E \times K) \otimes_{K} \mathbb{A}_{K}$ be such that $q\left(\alpha_{v}\right)=1$ and $\left|t_{v}\right|_{v}>1$ for all $v \in V$. Let $\alpha: V(K) \rightarrow \mathbb{R}$ the function defined by $\alpha(v)=$ $\left\|\alpha_{v}\right\|_{E, v}$ if $v \in V$ and $\alpha(v)=1$ if $v \notin V$. Let us assume that the quadratic form $Q(x, y)=q(x)-y^{2}$ on $E \times K$ has its isotropy index $i(Q)$ equal to $i(q)+1$. Define

$$
\mathcal{T}_{0}=c_{K}^{\mathrm{BV}}(i(Q)) c_{K}^{\Lambda}(n+1-i(Q))(2 H(1, q))^{(n+1-i(Q)) / 2}|\alpha| H(E)
$$

and

$$
\mathcal{T}=\max \left(\mathfrak{T}_{0}^{1 / i(Q)},\left(\sqrt{2} / \lambda_{1}^{\mathrm{BV}}(E)\right)^{i(Q)-1} \mathcal{T}_{0}\right)
$$

We assume that $c_{1}(K)$ is finite (in particular $\mathcal{T}$ is finite). For $v \in V$, define

$$
T_{v}=(2 \mathcal{T})^{\epsilon_{v}}\left\|\alpha_{v}\right\|_{E, v}\left\|b\left(\cdot, \alpha_{v}\right)\right\|_{E^{\vee}, v}\left|t_{v} / 2\right|_{v}
$$

Then, for all $\varepsilon>0$, there exists $(v, \phi) \in E \times K$ satisfying $q(v)=\phi^{2} \neq 0$ and such that:

$$
\begin{gather*}
\forall v \notin V, \quad m_{v}\left(\|v\|_{E, v},|\phi|_{v}\right) \leq((1+\varepsilon) \mathcal{T})^{\epsilon_{v}},  \tag{1}\\
\forall v \in V, \quad m_{v}\left(\|v\|_{E, v},|\phi|_{v}\left\|\alpha_{v}\right\|_{E, v}\right) \leq(1+\varepsilon)^{\epsilon_{v}} T_{v} \tag{2}
\end{gather*}
$$

and

$$
\begin{equation*}
\forall v \in V, \quad\left|q\left(\alpha_{v} \phi-v\right)\right|_{v} \leq\left((1+\varepsilon) 2 \sqrt{2} \mathcal{T}^{2}\right)^{\epsilon_{v}}\left(\frac{|\phi|_{v}}{T_{v}}\right)\left\|\alpha_{v}\right\|_{E, v}\left\|b\left(\cdot, \alpha_{v}\right)\right\|_{E^{\vee}, v}^{2} \tag{3}
\end{equation*}
$$

The number $\left\|b\left(\cdot, \alpha_{v}\right)\right\|_{E^{\vee}, v}$ is the operator norm of the linear form $x \mapsto b\left(x, \alpha_{v}\right)$ on $E_{v}$. Besides the number $|\alpha|$ is the module of the map $\alpha$ (see the beginning of $\S 4.1$ ). When $K$ is a number field we can take $\varepsilon=0$. A discussion about the constant of $\mathcal{T}_{0}$ is made at the end of the article.

Our second statement concerns the other case $i(Q)=i(q)$.
Theorem 4.2. Consider

$$
\mathcal{T}_{1}=4 \min \left(c_{1}(K), \frac{c_{K}^{\mathrm{BV}}(n+1-i(Q))}{c_{K}^{\Lambda}(n+1-i(Q))}\right)^{2}\left(\frac{\sqrt{2}}{\lambda_{1}^{\mathrm{BV}}(E)}\right)^{i(Q)} \mathcal{T}_{0}^{2}
$$

(where $\mathcal{T}_{0}$ has been defined in the previous theorem). If $i(Q)=i(q) \geq 1$ then Theorem 4.1 remains true provided $\mathfrak{T}_{0}$ which is in the definition of $\mathcal{T}$ be replaced by $\max \left\{\mathcal{T}_{0}, \mathcal{T}_{1}\right\}$.
4.3. Preparatory statements. In this part we prove three auxiliary results useful for the proofs of Theorems 4.1 and 4.2. The notation are those of these statements.

Since only the absolute value of $t_{v}$ occurs, we can assume $t_{v}=\left|t_{v}\right|_{v}$ if $v \in V$ is archimedean. For $v \in V$, define $\mathcal{X}_{v}, \mathrm{y}_{v} \in K_{v}$ with the formulas of $\S 2.1$, where $(\alpha, t)$ is replaced by $\left(\alpha_{v}, t_{v}\right)$, and $b: E \times E \rightarrow K$ is still the symmetric bilinear form associated to $q$. Let $E_{t}$ be the rigid adelic space $E \times K$ where each norm at $v \in V$ has been twisted in the following way:

$$
\forall(x, y) \in E_{v} \times K_{v}, \quad\|(x, y)\|_{E_{t}, v}=m_{v}\left(\left\|x-b\left(x, \alpha_{v}\right) \alpha_{v}+X_{v} \alpha_{v}\right\|_{E, v},\left\|y_{v} \alpha_{v}\right\|_{E, v}\right)
$$

(when $v \notin V$, we have $\left.\|(x, y)\|_{E_{t}, v}=m_{v}\left(\|x\|_{E, v},|y|_{v}\right)=\|(x, y)\|_{E \times K, v}\right)$. So, to build this norm, we first modify the norm on $E \times K$ at $v$ by multiplying the second component by $\alpha(v)$ and then we compose with the automorphism $\xi_{v}(x, y)=\left(x-b\left(x, \alpha_{v}\right) \alpha_{v}+X_{v} \alpha_{v}, y_{v}\right)$ of $E_{v} \times K_{v}$, which has determinant 1. In particular we have $H\left(E_{t}\right)=|\alpha| H(E \times K)=|\alpha| H(E)$. Here are two properties of the norm $\|\cdot\|_{E_{t}, v}$.

Lemma 4.3. For all $v \in V, x \in E \otimes_{K} K_{v}$ and $y \in K_{v}$, we have

$$
m_{v}\left(\|x\|_{E, v},\left\|y \alpha_{v}\right\|_{E, v}\right) \leq 2^{\epsilon_{v}}\left|t_{v} / 2\right|_{v}\left(\left\|b\left(\cdot, \alpha_{v}\right)\right\|_{E^{\vee}, v}\left\|\alpha_{v}\right\|_{E, v}\right)\|(x, y)\|_{E_{t}, v}
$$

Proof. The question is to bound the operator norm of $\xi_{v}^{-1}$ when $E_{v} \times K_{v}$ is endowed with the norm $m_{v}\left(\|x\|_{E, v},\left\|y \alpha_{v}\right\|_{E, v}\right)$. For any $(x, y) \in E_{v} \times K_{v}$, we have the formula $\xi_{v}^{-1}(x, y)=$ $\left(x-b\left(x, \alpha_{v}\right) \alpha_{v}+X_{v}^{\prime} \alpha_{v}, y_{v}^{\prime}\right)$ where

$$
X_{v}^{\prime}=\frac{1}{2}\left(t_{v}+\frac{1}{t_{v}}\right) b\left(x, \alpha_{v}\right)+\frac{1}{2}\left(t_{v}-\frac{1}{t_{v}}\right) y \quad \text { and } \quad y_{v}^{\prime}=\frac{1}{2}\left(t_{v}-\frac{1}{t_{v}}\right) b\left(x, \alpha_{v}\right)+\frac{1}{2}\left(t_{v}+\frac{1}{t_{v}}\right) y
$$

When $v \in V$ is ultrametric, we have

$$
\max \left(\left\|X_{v}^{\prime} \alpha_{v}\right\|_{v},\left\|y_{v}^{\prime} \alpha_{v}\right\|_{E, v}\right) \leq \max \left(\|x\|_{E, v},\left\|y \alpha_{v}\right\|_{E, v}\right) \times\left|t_{v} / 2\right|_{v}\left\|b\left(\cdot, \alpha_{v}\right)\right\|_{E^{\vee}, v}\left\|\alpha_{v}\right\|_{E, v}
$$

since $\left|t_{v}\right|_{v} \geq 1$ and

$$
\begin{equation*}
\left|b\left(x, \alpha_{v}\right)\right|_{v} \leq\left\|b\left(\cdot, \alpha_{v}\right)\right\|_{E^{\vee}, v}\|x\|_{E, v} \quad \text { and } \quad 1=\left|b\left(\alpha_{v}, \alpha_{v}\right)\right|_{v} \leq\left\|b\left(\cdot, \alpha_{v}\right)\right\|_{E^{\vee}, v}\left\|\alpha_{v}\right\|_{E, v} \tag{4}
\end{equation*}
$$

We easily deduce that the same bound holds for $\max \left(\left\|x-b\left(x, \alpha_{v}\right) \alpha_{v}+X_{v}^{\prime} \alpha_{v}\right\|_{E, v},\left\|y_{v}^{\prime} \alpha_{v}\right\|_{E, v}\right)$, which gives the desired result. When $v$ is archimedean, observe that
$m_{v}\left(\left\|x-b\left(x, \alpha_{v}\right) \alpha_{v}+X_{v}^{\prime} \alpha_{v}\right\|_{E, v},\left\|y_{v}^{\prime} \alpha_{v}\right\|_{E, v}\right)^{2} \leq\left(\|x\|_{E, v}+\left\|\left(X_{v}^{\prime}-b\left(x, \alpha_{v}\right)\right) \alpha_{v}\right\|_{E, v}\right)^{2}+\left\|y_{v}^{\prime} \alpha_{v}\right\|_{E, v}^{2}$.
We note

$$
\left\|\left(X_{v}^{\prime}-b\left(x, \alpha_{v}\right)\right) \alpha_{v}\right\|_{E, v} \leq \frac{1}{2}\left(t_{v}+\frac{1}{t_{v}}-2\right)\left\|b\left(x, \alpha_{v}\right) \alpha_{v}\right\|_{E, v}+\frac{1}{2}\left(t_{v}-\frac{1}{t_{v}}\right)\left\|y \alpha_{v}\right\|_{E, v}
$$

and

$$
\left\|y_{v}^{\prime} \alpha_{v}\right\|_{E, v} \leq \frac{1}{2}\left(t_{v}-\frac{1}{t_{v}}\right)\left\|b\left(x, \alpha_{v}\right) \alpha_{v}\right\|_{E, v}+\frac{1}{2}\left(t_{v}+\frac{1}{t_{v}}\right)\left\|y \alpha_{v}\right\|_{E, v}
$$

Then, using (4), we can factorize by the product $\left\|b\left(\cdot, \alpha_{v}\right)\right\|_{E^{\vee}, v}\left\|\alpha_{v}\right\|_{E, v}$ and we see that

$$
\left(2 m_{v}\left(\left\|x-b\left(x, \alpha_{v}\right) \alpha_{v}+X_{v}^{\prime} \alpha_{v}\right\|_{E, v},\left\|y_{v}^{\prime} \alpha_{v}\right\|_{E, v}\right) /\left\|b\left(\cdot, \alpha_{v}\right)\right\|_{E^{\vee}, v}\left\|\alpha_{v}\right\|_{E, v}\right)^{2}
$$

is bounded by

$$
\left(\left(t_{v}+\frac{1}{t_{v}}\right)\|x\|_{E, v}+\left(t_{v}-\frac{1}{t_{v}}\right)\left\|y \alpha_{v}\right\|_{E, v}\right)^{2}+\left(\left(t_{v}-\frac{1}{t_{v}}\right)\|x\|_{E, v}+\left(t_{v}+\frac{1}{t_{v}}\right)\left\|y \alpha_{v}\right\|_{E, v}\right)^{2}
$$

We develop this expression and substitute the product $2\|x\|_{E, v}\left\|y \alpha_{v}\right\|_{E, v}$ by $\|x\|_{E, v}^{2}+\left\|y \alpha_{v}\right\|_{E, v}^{2}$ to finally obtain the desired bound $4 t_{v}^{2} m_{v}\left(\|x\|_{E, v},\left\|y \alpha_{v}\right\|_{E, v}\right)^{2}$.

When $y=0$ we can prove a better estimate, which does not depend on $t_{v}$.
Lemma 4.4. For all $v \in V(K)$ and $x \in E \otimes_{K} K_{v}$, we have $\|x\|_{E, v} \leq 2^{\epsilon_{v} / 2}\|(x, 0)\|_{E_{t}, v}$.
Proof. If $v \in V(K) \backslash V$ then $\|(x, 0)\|_{E_{t}, v}=\|(x, 0)\|_{E \times K, v}=\|x\|_{E, v}$ and the result is clear. Let $v \in V$ be an archimedean place and $x \in E \otimes_{K} K_{v}$. From the definition of the $v$-norm of $E_{t}$, the number $\|(x, 0)\|_{E_{t}, v}^{2}$ equals

$$
\left\|x-b\left(x, \alpha_{v}\right) \alpha_{v}+\frac{1}{2}\left(t_{v}+\frac{1}{t_{v}}\right) b\left(x, \alpha_{v}\right) \alpha_{v}\right\|_{E, v}^{2}+\left|\frac{1}{2}\left(t_{v}-\frac{1}{t_{v}}\right) b\left(x, \alpha_{v}\right)\right|_{v}^{2}\left\|\alpha_{v}\right\|_{E, v}^{2}
$$

Put $\theta=\frac{1}{2}\left(t_{v}+\frac{1}{t_{v}}-2\right) b\left(x, \alpha_{v}\right) \alpha_{v}$ and bound from below the first norm by $\left|\|x\|_{E, v}-\|\theta\|_{E, v}\right|$ (reverse triangle inequality). Also note that $t_{v}-1 / t_{v} \geq t_{v}+1 / t_{v}-2 \geq 0$ since $t_{v}$ is a real number greater than 1. In particular the norm of $\left(t_{v}-1 / t_{v}\right) b\left(x, \alpha_{v}\right) \alpha_{v} / 2$ is greater or equal than $\|\theta\|_{E, v}$. We conclude with

$$
\|(x, 0)\|_{E_{t}, v}^{2} \geq\left(\|x\|_{E, v}-\|\theta\|_{E, v}\right)^{2}+\|\theta\|_{E, v}^{2} \geq \frac{\|x\|_{E, v}^{2}}{2}
$$

When $v \in V$ is ultrametric, the norm $\|(x, 0)\|_{E_{t}, v}$ is

$$
\max \left(\left\|x-b\left(x, \alpha_{v}\right) \alpha_{v}+\frac{1}{2}\left(t_{v}+\frac{1}{t_{v}}\right) b\left(x, \alpha_{v}\right) \alpha_{v}\right\|_{E, v},\left\|\frac{1}{2}\left(t_{v}-\frac{1}{t_{v}}\right) b\left(x, \alpha_{v}\right) \alpha_{v}\right\|_{E, v}\right)
$$

Since $\left|t_{v}\right|_{v}>1$ we have $\left|t_{v}-1 / t_{v}\right|_{v}=\left|t_{v}\right|_{v}=\left|t_{v}+1 / t_{v}-2\right|_{v}$ so that

$$
\|(x, 0)\|_{E_{t}, v}=\max \left(\|x+\theta\|_{E, v},\|\theta\|_{E, v}\right) \geq\|x\|_{E, v}
$$

At last, we also need the following statement.

Lemma 4.5. The height of $Q$ satisfies $H(Q) \leq H(1, q)$.
Proof. Let $B$ be the bilinear form associated to $Q$ and $v \in V(K)$. Let $x, x^{\prime} \in E_{v}$ and $y, y^{\prime} \in K_{v}$. From the expression $B\left((x, y),\left(x^{\prime}, y^{\prime}\right)\right)=b\left(x, x^{\prime}\right)-y y^{\prime}$, we get

$$
\left|B\left((x, y),\left(x^{\prime}, y^{\prime}\right)\right)\right|_{v} \leq\left|b\left(x, x^{\prime}\right)\right|_{v}+|y|_{v}\left|y^{\prime}\right|_{v} \leq\|q\|_{v}\|x\|_{E, v}\left\|x^{\prime}\right\|_{E, v}+|y|_{v}\left|y^{\prime}\right|_{v}
$$

(the sum can be replaced by a maximum when $v$ is ultrametric). We factorize by max $\left(1,\|q\|_{v}\right)$ and we use the Cauchy inequality to obtain

$$
\left|B\left((x, y),\left(x^{\prime}, y^{\prime}\right)\right)\right|_{v} \leq \max \left(1,\|q\|_{v}\right)\|(x, y)\|_{E \times K, v}\left\|\left(x^{\prime}, y^{\prime}\right)\right\|_{E \times K, v}
$$

which implies $\|Q\|_{v} \leq \max \left(1,\|q\|_{v}\right)$ when $v \notin V$ since, in this case, $\|\cdot\|_{E_{t}, v}=\|\cdot\|_{E \times K, v}$. When $v \in V$, we observe that $B\left((x, y),\left(x^{\prime}, y^{\prime}\right)\right)=b\left(x, x^{\prime}\right)-b\left(y \alpha_{v}, y^{\prime} \alpha_{v}\right)$ and so

$$
\left|B\left((x, y),\left(x^{\prime}, y^{\prime}\right)\right)\right|_{v} \leq\|q\|_{v} m_{v}\left(\|x\|_{E, v},\left\|y \alpha_{v}\right\|_{E, v}\right) m_{v}\left(\left\|x^{\prime}\right\|_{E, v},\left\|y^{\prime} \alpha_{v}\right\|_{E, v}\right)
$$

Now, since $B$ is invariant by $\xi_{v}$ (Lemma 2.2), if we replace $(x, y)$ and ( $x^{\prime}, y^{\prime}$ ) by their images by $\xi_{v}$, we deduce $\left|B\left((x, y),\left(x^{\prime}, y^{\prime}\right)\right)\right|_{v} \leq\|q\|_{v}\|(x, y)\|_{E_{t}, v}\left\|\left(x^{\prime}, y^{\prime}\right)\right\|_{E_{t}, v}$ then $\|Q\|_{v} \leq\|q\|_{v}$. Thus, in all cases we have $\|Q\|_{v} \leq \max \left(1,\|q\|_{v}\right)$ which leads to $H(Q) \leq H(1, q)$.
4.4. Proof of Theorem 4.1. According to [GR2, Corollary 3.2], there exists a maximal $Q$ isotropic subspace $\{0\} \neq F \subset E_{t}$ (of dimension $i(Q)$ ) such that $(1+\varepsilon)^{-1 / 2 n} \leq 2 H(Q) \Lambda_{1}\left(E_{t} / F\right)^{2}$. Bounding from above $\Lambda_{1}\left(E_{t} / F\right)$ by $\left(c_{K}^{\Lambda}(n+1-i(Q)) H\left(E_{t} / F\right)\right)^{1 /(n+1-i(Q))}$ and using $H\left(E_{t} / F\right)=$ $H\left(E_{t}\right) / H(F)=|\alpha| H(E) / H(F)$, we deduce the upper bound

$$
H(F) \leq(1+\varepsilon)^{1 / 2} c_{K}^{\Lambda}(n+1-i(Q))(2 H(Q))^{(n+1-i(Q)) / 2}|\alpha| H(E)
$$

which leads to $H(F) \leq(1+\varepsilon)^{1 / 2} \mathcal{T}_{0} / c_{K}^{\mathrm{BV}}(i(Q))$ with Lemma 4.5. Since $i(Q)>i(q)$, we have $F \not \subset E \times\{0\}$. To build the vector $(v, \phi)$ of Theorem 4.1, we distinguish two cases.
(i) If $\lambda_{1}^{\mathrm{BV}}(F)<\lambda_{1}^{\mathrm{BV}}(E) / \sqrt{2}$, we consider $0<\varepsilon^{\prime} \leq \varepsilon$ such that $\left(1+\varepsilon^{\prime}\right)^{1 / 2} \lambda_{1}^{\mathrm{BV}}(F)<\lambda_{1}^{\mathrm{BV}}(E) / \sqrt{2}$ and $(v, \phi) \in F \backslash\{0\}$ such that $\|(v, \phi)\|_{E_{t}, v} \leq\left(\left(1+\varepsilon^{\prime}\right)^{1 / 2} \lambda_{1}^{\mathrm{BV}}(F)\right)^{\epsilon_{v}}$ for all $v \in V(K)$. By Lemma 4.4 and the choice of $\varepsilon^{\prime}$, we have $\phi \neq 0$. Moreover $\lambda_{1}^{\mathrm{BV}}(F) \leq\left(c_{K}^{\mathrm{BV}}(i(Q)) H(F)\right)^{1 / i(Q)}$, so that $\|(v, \phi)\|_{E_{t}, v} \leq((1+\varepsilon) \mathcal{T})^{\epsilon_{v}}$ for all $v \in V(K)$.
(ii) If $\lambda_{1}^{\mathrm{BV}}(F) \geq \lambda_{1}^{\mathrm{BV}}(E) / \sqrt{2}$, we consider $(v, \phi) \in F$ such that $\phi \neq 0$ and $\|(v, \phi)\|_{E_{t}, v} \leq$ $\left((1+\varepsilon)^{1 / 2} \lambda_{i(Q)}^{\mathrm{BV}}(F)\right)^{\epsilon_{v}}$ for all $v \in V(K)$. We can do that since $F \not \subset E \times\{0\}$ and every basis of $F$ contains a vector whose last coordinate is non-zero. We bound

$$
\lambda_{i(Q)}^{\mathrm{BV}}(F) \leq \frac{c_{K}^{\mathrm{BV}}(i(Q)) H(F)}{\lambda_{1}^{\mathrm{BV}}(F)^{i(Q)-1}} \leq(1+\varepsilon)^{1 / 2} \mathcal{T}
$$

Thus, in both cases, there exists $(v, \phi) \in E \times K$ such that $\phi \neq 0, q(v)=\phi^{2}$ (because $(v, \phi) \in$ $F$ is $Q$-isotropic) and $\|(v, \phi)\|_{E_{t}, v} \leq((1+\varepsilon) \mathcal{T})^{\epsilon_{v}}$ for all $v \in V(K)$. These inequalities yield the first assertion of Theorem 4.1, since when $v \notin V$, we have $\|(v, \phi)\|_{E_{t}, v}=\|(v, \phi)\|_{E \times K, v}=$ $m_{v}\left(\|v\|_{E, v},|\phi|_{v}\right)$. Now, let us consider $v \in V$. The second assertion of Theorem 4.1 is a direct consequence of Lemma 4.3 and the definition of $T_{v}$. At last, for (3), note that $q\left(\alpha_{v} \phi-v\right)=$ $2\left(y_{v}-x_{v}\right) \phi / t_{v}$. From

$$
\left|X_{v}\right|_{v}=\left|b\left(v-b\left(v, \alpha_{v}\right) \alpha_{v}+X_{v} \alpha_{v}, \alpha_{v}\right)\right|_{v} \leq\left\|b\left(\cdot, \alpha_{v}\right)\right\|_{E^{\vee}, v}\left\|v-b\left(v, \alpha_{v}\right) \alpha_{v}+X_{v} \alpha_{v}\right\|_{E, v}
$$

and $\left|y_{v}\right|_{v}=\left|b\left(y_{v} \alpha_{v}, \alpha_{v}\right)\right|_{v} \leq\left\|b\left(\cdot, \alpha_{v}\right)\right\|_{E^{\vee}, v}\left\|y_{v} \alpha_{v}\right\|_{E, v}$ we deduce

$$
\left|y_{v}-X_{v}\right|_{v} \leq(\sqrt{2})^{\epsilon_{v}}\left\|b\left(\cdot, \alpha_{v}\right)\right\|_{E^{\vee}, v}\|(v, \phi)\|_{E_{t}, v}
$$

and so

$$
\left|q\left(\alpha_{v} \phi-v\right)\right|_{v} \leq\left|\frac{2 \phi}{t_{v}}\right|_{v}\left\|b\left(\cdot, \alpha_{v}\right)\right\|_{E^{\vee}, v}((1+\varepsilon) \sqrt{2} \mathcal{T})^{\epsilon_{v}}
$$

We conclude with the formula linking $t_{v}$ and $T_{v}$.
Theorem 3.1 can be deduced from Theorem 4.1: Choose $K=\mathbb{Q}$ and the singleton $V=\{\infty\}$ (archimedean place of $\mathbb{Q}$ ). Take $E=\mathbb{Q}^{n}$ with the norms $|\cdot|_{p}$ at $p \in V(\mathbb{Q}) \backslash\{\infty\}$ and $\|x\|_{E, \infty}=$ $\sqrt{q_{0}(x)}$. In other words $E$ corresponds to the Euclidean lattice $\left(\mathbb{Z}^{n}, \sqrt{q_{0}}\right)$ and, in particular, we have $H(E)=\sqrt{\operatorname{det} q_{0}}$ and $\lambda_{1}^{\mathrm{BV}}(E)=\lambda_{1}$. The integrality hypothesis on the coefficients of $A(q)$ gives $\|q\|_{p} \leq 1$ for all $p \neq \infty$ so that $H(1, q)=\max \left(1,\|q\|_{\infty}\right)$. Also choose $t_{\infty}=T / \mathcal{T}$. The equality $i(Q)=i(q)+1$ as well as the bound $c_{\mathbb{Q}}^{\mathrm{BV}}(i(q)+1) c_{\mathbb{Q}}^{\Lambda}(n-i(q)) \leq n^{n}$ (see $\left.\S 4.6\right)$ allow to conclude.

Theorem 1.1 also follows from Theorem 4.1 in the same way by further choosing $q_{0}=q$. This implies $|\alpha|=\|\alpha\|_{E, \infty}=\|b(\cdot, \alpha)\|_{E^{\vee}, \infty}=\|q\|_{\infty}=H(1, q)=1$. Besides, since $i(Q)=1$, we have both $\mathcal{T}=\mathcal{T}_{0}$ and $c_{\mathbb{Q}}^{\mathrm{BV}}(i(Q)) c_{\mathbb{Q}}^{\Lambda}(n+1-i(Q))=c_{\mathbb{Q}}^{\Lambda}(n)=\gamma_{n}^{n / 2}$.
4.5. Proof of Theorem 4.2. The proof of Theorem 4.1 still works the same way when the maximal $Q$-isotropic subspace $F$ introduced at the beginning of the proof satisfies $F \not \subset E \times\{0\}$. Thus, in this case, Theorem 4.2 is proved. So now we can assume that $F \subset E \times\{0\}$. We shall consider the image of $F$ by a certain $Q$-isometry, image not contained in $E \times\{0\}$, with which we shall apply the same method as Theorem 4.1. More precisely, we claim that there exist $a \in E_{t} / F$ and a maximal $Q$-isotropic subspace $F_{a} \subset E_{t}$ satisfying the following three conditions: (i) $F_{a} \not \subset$ $E \times\{0\},(i i) H_{E_{t} / F}(a) \leq 2(1+\varepsilon)^{1 / 4 n} \lambda_{n+1-i(Q)}^{\mathrm{BV}}\left(E_{t} / F\right)$ and $(i i i) H\left(F_{a}\right) \leq 2 H(Q) H_{E_{t} / F}(a)^{2} H(F)$. Indeed, the space $F_{a}$ comes from the key lemma of [GR2, §3], whereas the element $a \in E_{t} / F$ is chosen in the same way as the beginning of the proof of [GR2, Theorem 7.1] (page 234 with, here, $Z(I)=E \times\{0\})$. Besides, the minimum $\lambda_{n+1-i(Q)}^{\mathrm{BV}}\left(E_{t} / F\right)$ can be bounded in two different ways: either by $c_{1}(K) \Lambda_{n+1-i(Q)}\left(E_{t} / F\right)$ [GR1, Proposition 4.8] and then by $c_{1}(K) c_{K}^{\Lambda}(n+1-$ $i(Q)) H\left(E_{t} / F\right) / \Lambda_{1}\left(E_{t} / F\right)^{n-i(Q)}$ or, directly, by $c_{K}^{\mathrm{BV}}(n+1-i(Q)) H\left(E_{t} / F\right) / \lambda_{1}^{\mathrm{BV}}\left(E_{t} / F\right)^{n-i(Q)}$ and then by $c_{K}^{\mathrm{BV}}(n+1-i(Q)) H\left(E_{t} / F\right) / \Lambda_{1}\left(E_{t} / F\right)^{n-i(Q)}$ since $\lambda_{1}^{\mathrm{BV}}\left(E_{t} / F\right) \geq \Lambda_{1}\left(E_{t} / F\right)$. In both cases, we bound from below $\Lambda_{1}\left(E_{t} / F\right)$ by $(1+\varepsilon)^{-1 / 4 n}(2 H(Q))^{-1 / 2}$ (definition of $F$ ). Thus (with $i(Q) \geq 1) \lambda_{n+1-i(Q)}^{\mathrm{BV}}\left(E_{t} / F\right)$ is smaller than

$$
(1+\varepsilon)^{(n-1) / 4 n} \min \left(c_{1}(K) c_{K}^{\Lambda}(n+1-i(Q)), c_{K}^{\mathrm{BV}}(n+1-i(Q))\right)(2 H(Q))^{(n-i(Q)) / 2} \frac{H\left(E_{t}\right)}{H(F)}
$$

This information put in the previous estimate of $H\left(F_{a}\right)$ implies

$$
\begin{aligned}
H\left(F_{a}\right) \leq & (1+\varepsilon)^{1 / 2} \times 4 \min \left(c_{1}(K) c_{K}^{\Lambda}(n+1-i(Q)), c_{K}^{\mathrm{BV}}(n+1-i(Q))\right)^{2} \\
& \times(2 H(Q))^{n+1-i(Q)}(|\alpha| H(E))^{2} / H(F)
\end{aligned}
$$

We have $H(F) \geq \lambda_{1}^{\mathrm{BV}}(F)^{i(Q)} / c_{K}^{\mathrm{BV}}(i(Q))$ and, since $F \subset E \times\{0\}$, we also have $\lambda_{1}^{\mathrm{BV}}(F) \geq \lambda_{1}^{\mathrm{BV}}(E \times$ $\{0\})$ so $\lambda_{1}^{\mathrm{BV}}(F) \geq \lambda_{1}^{\mathrm{BV}}(E) / \sqrt{2}$ by Lemma 4.4. Reporting these estimates in the previous bound for $H\left(F_{a}\right)$, we obtain $H\left(F_{a}\right) \leq(1+\varepsilon)^{1 / 2} \mathcal{T}_{1} / c_{K}^{\mathrm{BV}}(i(Q))$ with Lemma 4.5. It is then enough to resume the demonstration of Theorem 4.1 by replacing $F$ by $F_{a}$ (and so $\mathcal{T}_{0}$ by $\mathcal{T}_{1}$ ) to conclude.
4.6. The constant $c_{K}^{\mathrm{BV}}(i(Q)) c_{K}^{\Lambda}(n+1-i(Q))$ in $\mathcal{T}_{0}$ is finite (only) when $K$ is Siegel field with $c_{1}(K)<+\infty$. This happens e.g. when $K$ is number field or $[\bar{K}: K] \leq 2$ or, also, when $K=\cup_{n} K_{n}$ is the union of a tower of number fields $\left(K_{n}\right)_{n \in \mathbb{N}}$ of bounded root discriminants [GR1, Lemma 5.8]. Besides, the following estimates, valid for all $n \geq 1$ and $i \in\{0, \ldots, n-1\}$, may be of interest:
(1) when $K$ is a number field of root discriminant $\delta_{K / \mathbb{Q}}$, we have

$$
c_{K}^{\mathrm{BV}}(i+1) c_{K}^{\Lambda}(n-i) \leq n^{n / 2} \delta_{K / \mathbb{Q}}^{(n+1) / 2},
$$

(2) when $K=\overline{\mathbb{Q}}$, we have

$$
c_{\overline{\mathbb{Q}}}^{\mathrm{BV}}(i+1) c_{\overline{\mathbb{Q}}}^{\Lambda}(n-i) \leq c_{\overline{\mathbb{Q}}}^{\Lambda}(n) \leq n^{n / 2} .
$$

The first one derives from $c_{K}^{\mathrm{BV}}(n) \leq\left(n \delta_{K / \mathbb{Q}}\right)^{n / 2}$ and the bound $(i+1)^{i+1}(n-i)^{n-i} \leq n^{n}$ (the function $a \mapsto(a+i) \log (a+i)-a \log a$ is increasing). The second bound is a consequence of the formula given for $c_{\mathbb{Q}}^{*}(n)$ coupled with the estimate $a H_{a}+b H_{b} \leq(a+b-1) H_{a+b-1}+1$ satisfied by the harmonic number $H_{a}=1+1 / 2+\cdots+1 / a$ for all positive integers $a, b$ and proven by induction on $b$.

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[^0]:    MSC 2020: 11R56, 11E12, 11J13.
    Keywords: Diophantine approximation, quadratic form, approximation on sphere, rigid adelic space, quadratic Siegel's lemma.

    Date: 2024-03-16 18:41:50.
    The author is supported by the ANR-23-CE40-0006-01 Gaec project. With the aim of its open access publication, he applies a CC BY open access license to this manuscript.

