



HAL
open science

Supplementary material: The ultimate frontier: An optimality construction for homotopy inference

Dominique Attali, Hana Dal Poz Kouřimská, Christopher Fillmore, Ishika Ghosh, André Lieutier, Elizabeth Stephenson, Mathijs Wintraecken

► To cite this version:

Dominique Attali, Hana Dal Poz Kouřimská, Christopher Fillmore, Ishika Ghosh, André Lieutier, et al.. Supplementary material: The ultimate frontier: An optimality construction for homotopy inference. 2024. hal-04501285

HAL Id: hal-04501285

<https://hal.science/hal-04501285>

Preprint submitted on 12 Mar 2024

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.



Distributed under a Creative Commons Attribution 4.0 International License

Supplementary material: The ultimate frontier: An optimality construction for homotopy inference

Dominique Attali ✉

Université Grenoble Alpes, CNRS, Grenoble INP, GIPSA-lab
[Grenoble, France]

Hana Dal Poz Kouřimská ✉ 

IST Austria
[Klosterneuburg, Austria]

Christopher Fillmore ✉ 

IST Austria
[Klosterneuburg, Austria]

Ishika Ghosh ✉ 

IST Austria
[Klosterneuburg, Austria]
Michigan State University
[East Lansing, USA]

André Lieutier ✉

No affiliation
[Aix-en-Provence, France]

Elizabeth Stephenson ✉ 

IST Austria
[Klosterneuburg, Austria]

Mathijs Wintraecken ✉ 

Inria Sophia Antipolis, Université Côte d'Azur
[Sophia Antipolis, France]

Abstract

In the supplementary material for the media contribution we focus on the topological transitions of the thickening of the samples we consider. To improve readability we include the description of the construction, which can also be found in the main submission.

2012 ACM Subject Classification Theory of computation → Computational geometry

Keywords and phrases Homotopy, Inference, Sets of positive reach

Digital Object Identifier 10.4230/LIPIcs...

Funding This research has been supported by the European Research Council (ERC), grant No. 788183, by the Wittgenstein Prize, Austrian Science Fund (FWF), grant No. Z 342-N31, and by the DFG Collaborative Research Center TRR 109, Austrian Science Fund (FWF), grant No. I 02979-N35.

Mathijs Wintraecken: Supported by the European Union's Horizon 2020 research and innovation programme under the Marie Skłodowska-Curie grant agreement No. 754411, the Austrian science fund (FWF) grant No. M-3073, and the welcome package from IDEX of the Université Côte d'Azur.

Acknowledgements We thank Jean-Daniel Boissonnat, Herbert Edelsbrunner, and Mariette Yvinec for discussion.



© Dominique Attali, Hana Dal Poz Kouřimská, Christopher Fillmore, Ishika Ghosh, André Lieutier, Elizabeth Stephenson, and Mathijs Wintraecken ;

licensed under Creative Commons License CC-BY 4.0



Leibniz International Proceedings in Informatics

LIPICs Schloss Dagstuhl – Leibniz-Zentrum für Informatik, Dagstuhl Publishing, Germany

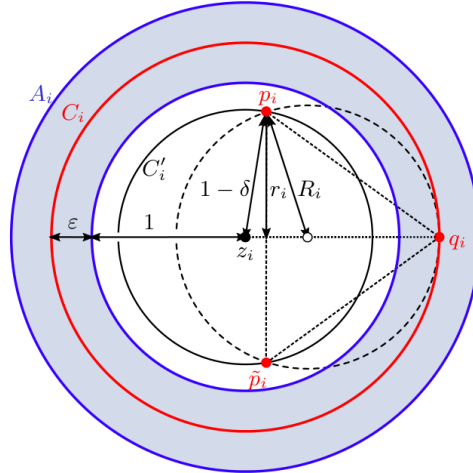
1 The construction

We construct the set \mathcal{S} (or the manifold \mathcal{M}) and the sample P that prove the optimality of our bounds. The video visualizes the construction. Note that due to rescaling it suffices to construct sets of reach equal to 1.

1.1 Sets of positive reach

The construction of a set \mathcal{S} that illustrates the tightness of our bound for sets of positive reach goes as follows: We define \mathcal{S} to be a union of annuli A_i in \mathbb{R}^2 , each of which has inner radius 1 and outer radius $1 + 2\varepsilon$. We lay the annuli in a row at distance at least 2 away from each other and number them from $i = 0$.

The sample P consists of circles C_i of radius $1 + \varepsilon$ lying in the middle of the annuli ($C_i \subseteq A_i$), and pairs of points $\{p_i, \tilde{p}_i\}$. Each pair $\{p_i, \tilde{p}_i\}$ lies in the disk inside the annulus A_i , at a distance δ from A_i , and the two points lie at a distance $2r_i$ from each other. The bisector of p_i and \tilde{p}_i intersects the circle C_i in two points. We let q_i be the intersection point that is closest to p_i (and thus \tilde{p}_i). We denote the circumradius of $p_i\tilde{p}_iq_i$ by R_i and note that $R_i \geq r_i$. Similarly, we let q'_i be the intersection point that is furthest¹ from p_i (and thus \tilde{p}_i). We denote the circumradius of $p_i\tilde{p}_iq'_i$ by R'_i .



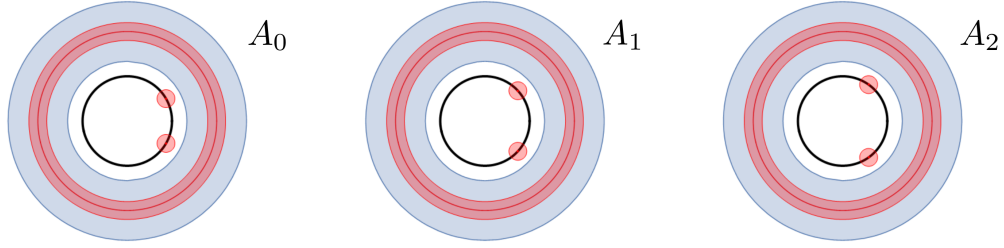
■ **Figure 1** Each annulus A_i is sampled by a circle C_i and a pair of points $\{p_i, \tilde{p}_i\}$. The circumradius is indicated by R_i .

We set $r_0 = \frac{\delta + \varepsilon}{2}$ and, for $i \geq 0$,

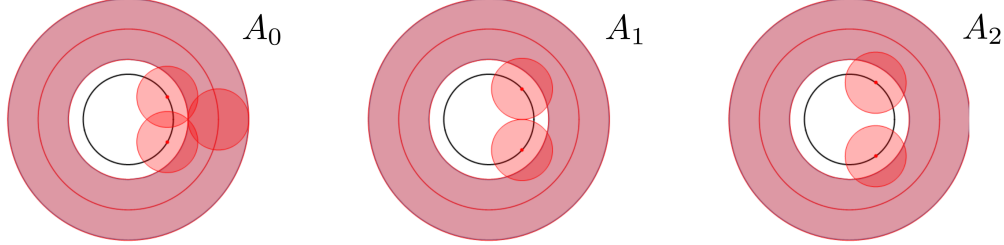
$$r_{i+1} = \begin{cases} R_i, & \text{if } R_i < 1 - \delta, \\ 1 - \delta, & \text{otherwise.} \end{cases}$$

We stop the sequence at the first value of $i = k$ such that $r_k = 1 - \delta$. Our constructed set \mathcal{S} consists of the finitely many annuli $A_0 \cup A_1 \cup \dots \cup A_k$ and our sample P is defined as $\bigcup_{0 \leq i \leq k} C_i \cup \{p_i, \tilde{p}_i\}$.

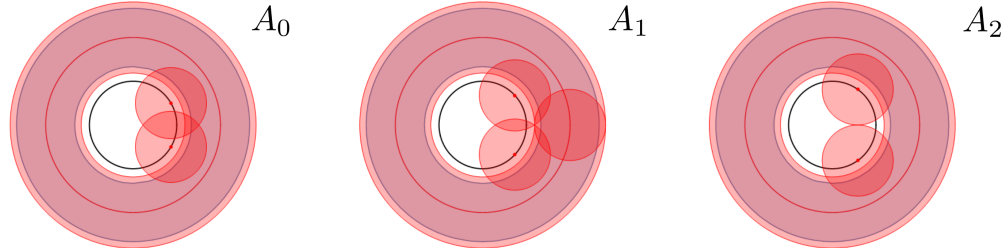
¹ If both intersection points are equidistant (as will be the case for $i = k$) we choose arbitrarily.



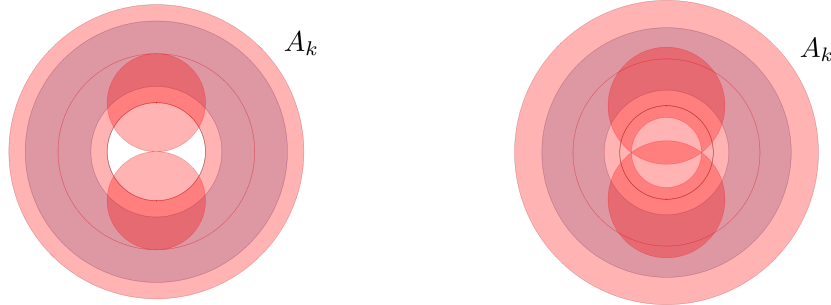
(a) For all $r < r_0$, the union of balls $(C_i \cup \{p_i, \tilde{p}_i\}) \oplus B(r)$ has three connected components.



(b) At radius r_1 , the cycle in the union of balls $(C_0 \cup \{p_0, \tilde{p}_0\}) \oplus B(r)$ at the annulus A_0 dies, while a cycle is created in the union of balls $(C_1 \cup \{p_1, \tilde{p}_1\}) \oplus B(r)$ at the annulus A_1 .



(c) At radius r_2 , the cycle in the union of balls at the annulus A_1 dies, while a cycle is created in the union of balls at the annulus A_2 .



(d) The set $(C_k \cup \{p_k, \tilde{p}_k\}) \oplus B(r)$ at radius $r_k = 1 - \delta$. The two ‘holes’ are identical.

(e) The two ‘holes’ of the set $(C_k \cup \{p_k, \tilde{p}_k\}) \oplus B(r)$ fill up simultaneously.

■ **Figure 2** The changing homology of the set $P \oplus B(r)$ in the annuli A_0, A_1, A_2 , and A_k .

For every $r \geq 0$, the union of balls $P \oplus B(r)$ has different homology than the set \mathcal{S} , where we use \oplus to denote the Minkowski sum. We describe the development of the topology of the sets $(C_i \cup \{p_i, \tilde{p}_i\}) \oplus B(r)$ as r increases:

- For $r \in [0, r_0)$, each set $(C_i \cup \{p_i, \tilde{p}_i\}) \oplus B(r)$ has three connected components, as illustrated in Figure 2a. The three components merge into one at $r = r_0$, as the two balls $\{p_i\} \oplus B(r)$ and $\{\tilde{p}_i\} \oplus B(r)$ intersect the set $C_i \oplus B(r)$.
- For $r \in [r_i, r_{i+1})$, the set $(C_i \cup \{p_i, \tilde{p}_i\}) \oplus B(r)$ has the homotopy type of two circles that share a point (also known as a wedge of two circles or a bouquet), as illustrated in

Figures 2b and 2c. The smaller ‘hole’ creating the additional cycle appears when $r = r_i$. The hole persists until $r = R_i = r_{i+1}$. All sets $(C_j \cup \{p_j, \tilde{p}_j\}) \oplus B(r)$ with $j \neq i$ have the homotopy type of a circle.

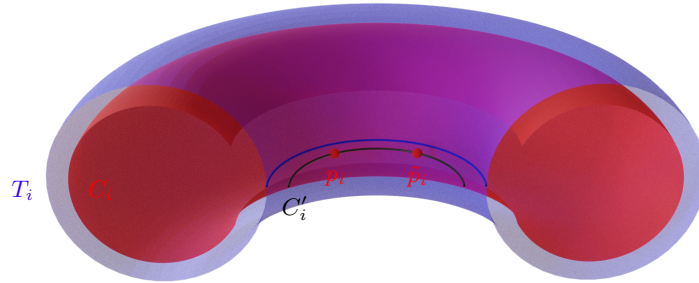
- At $r = r_k = 1 - \delta$, all sets $(C_i \cup \{p_i, \tilde{p}_i\}) \oplus B(r)$ have the homotopy type of a circle but the last one, $(C_k \cup \{p_k, \tilde{p}_k\}) \oplus B(r)$, which has the homotopy type of two circles that share a point (see Figure 2d). Unlike the other cases, however, the ‘holes’ in the set $(C_k \cup \{p_k, \tilde{p}_k\}) \oplus B(r)$ are identical, and disappear simultaneously at $r = R_k$ (Figure 2e). For every larger r , the set $(C_k \cup \{p_k, \tilde{p}_k\}) \oplus B(r)$ is contractible.
- Recall that R'_i denotes the circumradius of the triangle $p_i \tilde{p}_i q'_i$. For $i < k$, $R'_k < R'_i < 1 + \varepsilon$, and each set $(C_i \cup \{p_i, \tilde{p}_i\}) \oplus B(r)$ becomes contractible at R'_i .
- At $r = 1 + \varepsilon$ the connected components of $P \oplus B(r)$ merge.

1.2 Manifolds

The construction of the set \mathcal{M} that illustrates the tightness of our bound for manifolds goes as follows: We define \mathcal{M} to be a union of tori of revolution T_i in \mathbb{R}^3 . Each of these tori is the 1-offset of a circle (in the horizontal plane) of radius 2 in \mathbb{R}^3 .

We number the tori from $i = 0$, and lay them out in a row at a distance at least 2 apart from one another. Due to this assumption, the reach of \mathcal{M} equals 1.

The sample P consists of sets C_i which are tori with a part cut out, and pairs of points $\{p_i, \tilde{p}_i\}$ lying inside the hole of each torus T_i . To construct each set C_i we take the δ -offset of T_i , keep the part that lies inside the solid torus bounded by T_i , and remove an ε -neighbourhood of the circle obtained by revolving the point $(1, 0, 0)$ around the z -axis; see the red set in Figures 3 and 4.

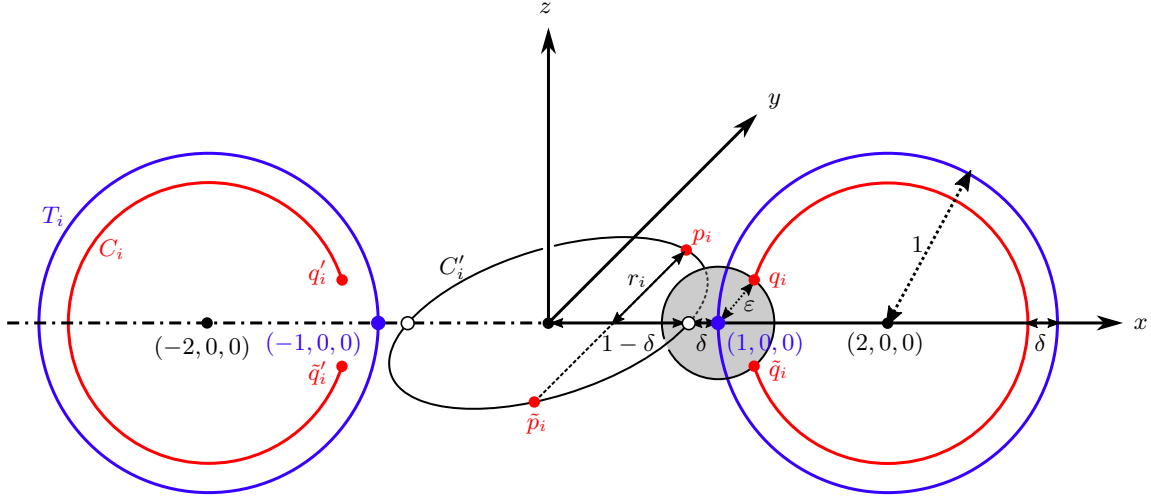


■ **Figure 3** The (half of the) torus T_i depicted in blue; the sample — the set C_i and the points p_i and \tilde{p}_i — in red. In black we indicate the circle C'_i . The closest point projection of this circle onto \mathcal{M} is indicated in blue.

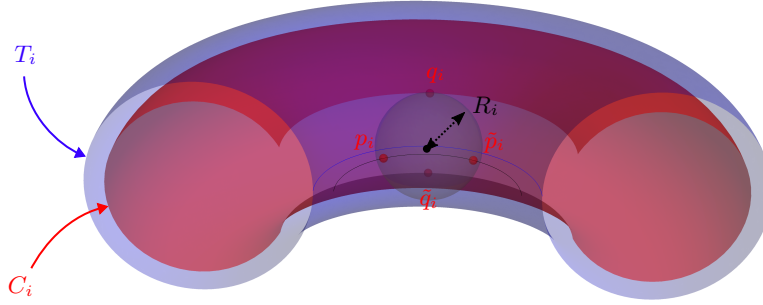
Let C'_i be the circle found by revolving the point $(1 - \delta, 0, 0)$ around the z -axis. Each pair of points, p_i and \tilde{p}_i , lies on C'_i at a distance $2r_i$ from each other. Let q_i and \tilde{q}_i be the two points in the intersection of the bisector of p_i and \tilde{p}_i and the set C_i that lie closest to p_i and \tilde{p}_i . Note that q_i and \tilde{q}_i lie on the boundary² of C_i , and $\{q_i, \tilde{q}_i\} = \pi_{C_i} \left(\frac{p_i + \tilde{p}_i}{2} \right)$, where π_{C_i} denotes the closest point projection on C_i . Denote the circumradius of the simplex $p_i \tilde{p}_i q_i \tilde{q}_i$ by R_i ; see Figure 5.

We denote the mirror images of q_i and \tilde{q}_i in the yz plane of Figure 4 by q'_i and \tilde{q}'_i . Similarly, we write R'_i for the circumradius of $p_i \tilde{p}_i q'_i \tilde{q}'_i$.

² Here we think of C_i as a manifold with boundary.



■ **Figure 4** The sets T_i , C_i and C'_i are obtained by rotating around the z -axis, respectively, the blue circles, the red arcs and the white point.



■ **Figure 5** The torus T_i (in blue), the sample $C_i \cup \{p_i, \tilde{p}_i\}$ (in red), the points q_i, \tilde{q}_i (in red), and the circumsphere of $p_i \tilde{p}_i q_i \tilde{q}_i$ (in light grey below).

We define the distance $2r_i$ between each pair of points p_i and \tilde{p}_i inductively. We set the distance r_0 such that the balls $B(p_0, r)$ and $B(\tilde{p}_0, r)$ start to intersect at the same value of r as the balls $B(q_0, r)$ and $B(\tilde{q}_0, r)$ start to intersect:

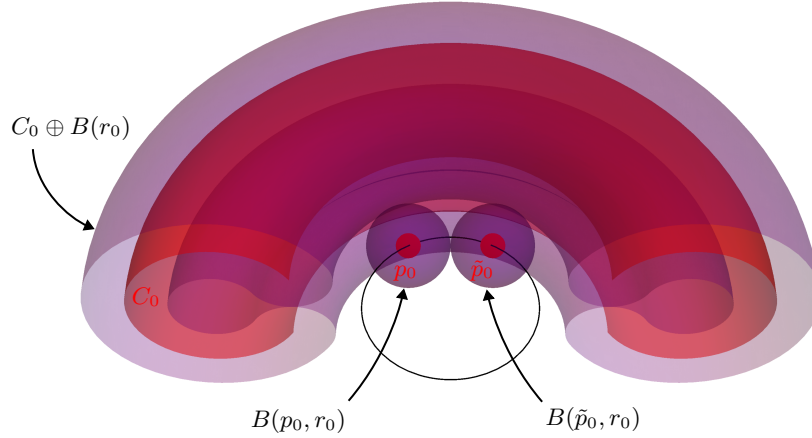
$$r_0 = \frac{1}{2}d(q_0, \tilde{q}_0) = \sqrt{\epsilon^2 - \left(\frac{\epsilon^2 - \delta^2 + 2\delta}{2}\right)^2}$$

We then define

$$r_{i+1} = \begin{cases} R_i, & \text{if } R_i < 1 - \delta, \\ 1 - \delta, & \text{otherwise.} \end{cases}$$

We stop the sequence at the first value of $i = k$ such that $r_i = 1 - \delta$. In [1] we show that such a value indeed exists.

The manifold \mathcal{M} thus consists of the finitely many tori $T_0 \cup T_1 \cup \dots \cup T_k$, and the sample P is defined as $\bigcup_{0 \leq i \leq k} (C_i \cup \{p_i, \tilde{p}_i\})$.



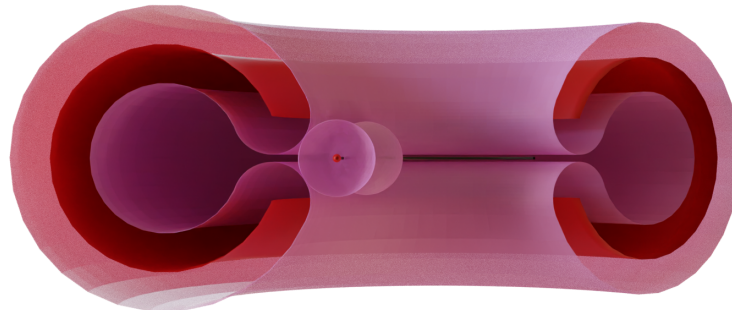
■ **Figure 6** The situation at r_0 . The sample P in red and its thickening $P \oplus B(r)$ (or boundary of the thickening) in purple. The balls $B(p_0, r_0)$ and $B(\tilde{p}_0, r_0)$ touch and the thickened torus $C_0 \oplus B(r_0)$ ‘closes up’ and generates 2-homology.

For every $r \geq 0$, the union of balls $P \oplus B(r)$ has different homology than the set \mathcal{M} . We describe the development of the topology of the sets $\bigcup_{i=0}^k (C_i \cup \{p_i, \tilde{p}_i\}) \oplus B(r) = P \oplus B(r)$ as r increases. For this we need to introduce some notation: We denote half the distance from p_i to C_i by τ . That is,

$$2\tau = \sqrt{|\delta^2 + \varepsilon^2 + \delta(\varepsilon^2 - \delta^2 + 2\delta)|} = \sqrt{|\varepsilon^2(1 + \delta) + \delta^2(3 - \delta)|}.$$

Write s and s' for the points on C_0 that are closest to p_0 and write \tilde{s} and \tilde{s}' for the points on C_0 that are closest to \tilde{p}_0 .

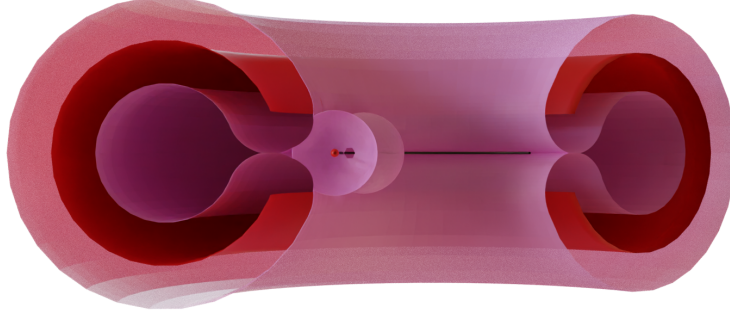
- For $r \in [0, \min(\tau, r_0))$ each set $(C_i \cup \{p_i, \tilde{p}_i\}) \oplus B(r)$ has three connected components. It has the homotopy type of a circle and two points.



■ **Figure 7** The two balls $\{p_0, \tilde{p}_0\} \oplus B(r)$ start touching $C_0 \oplus B(r)$. For these particular parameters $\tau < r_0$, which means that the set directly after this point has the homotopy type of a bouquet of circles.

- For $r \in [\min(\tau, r_0), \max(\tau, r_0))$ there are two possibilities depending on whether $\tau < r_0$ or $\tau > r_0$. In the first case the set $(C_0 \cup \{p_0, \tilde{p}_0\}) \oplus B(r)$ is homotopic to three topological circles that have a single point in common (also called a bouquet of three circles), see

Figure 7. If $r_0 < \tau$ the set $(C_0 \cup \{p_0, \tilde{p}_0\}) \oplus B(r)$ will have the homotopy type of a torus and two points.



■ **Figure 8** The 2-cycle of the torus is being created in $C_0 \oplus B(r)$. At this point, also the two balls $\{p_0, \tilde{p}_0\} \oplus B(r)$ start touching.

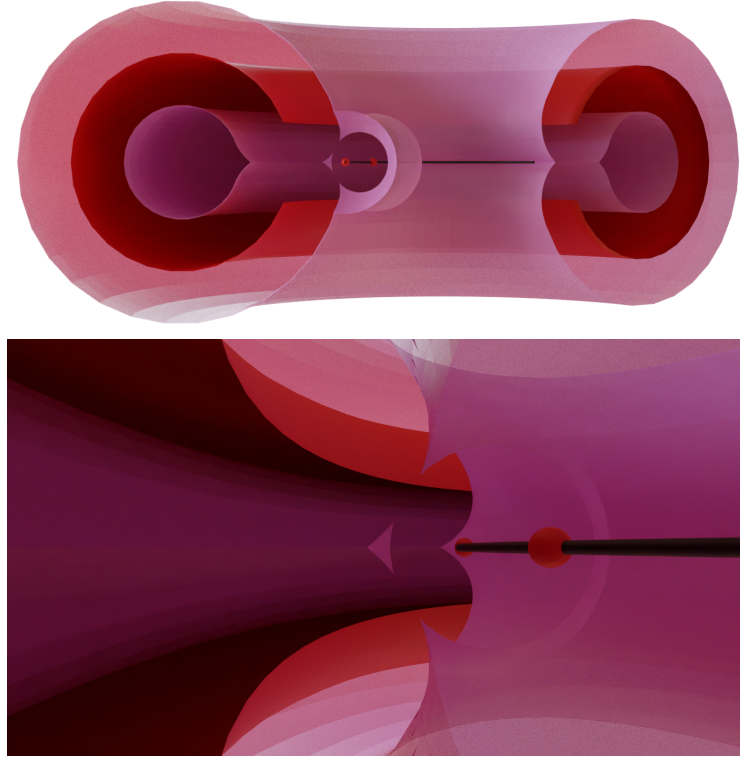
- For $r \in [\max(\tau, r_0), r_1)$ there are again a number of possibilities. Before we distinguish the cases we make some observations. We note that by assumption (on r) the line segments $p_0\tilde{p}_0$, p_0s , p_0s' , $\tilde{p}_0\tilde{s}$, and $\tilde{p}_0\tilde{s}'$ are contained in $(C_0 \cup \{p_0, \tilde{p}_0\}) \oplus B(r)$. The points s , s' , \tilde{s} , and \tilde{s}' all lie on a 2-cycle (slightly deformed torus) that is contained in $(C_0 \cup \{p_0, \tilde{p}_0\}) \oplus B(r)$, see Figure 8. The circumcentre of the simplex $p_0\tilde{p}_0q_0\tilde{q}_0$ is not contained in $(C_0 \cup \{p_0, \tilde{p}_0\}) \oplus B(r)$, again by assumption on r . We want to determine if the line segments $p_0\tilde{p}_0$, p_0s , p_0s' , $\tilde{p}_0\tilde{s}$, and $\tilde{p}_0\tilde{s}'$ form parts of some 1-cycles (and if so how many) or if the circumcentre of $p_0\tilde{p}_0q_0\tilde{q}_0$ is enclosed in a void.

This brings us to our case analysis. Firstly, the triangle p_0ss' (and therefore the triangle $\tilde{p}_0\tilde{s}\tilde{s}'$) can be acute or obtuse. If it is acute we need to distinguish whether the circumradius of p_0ss' lies inside $[\max(\tau, r_0), r_1)$ or not. If the circumradius does lie inside the interval $[\max(r_{-1}, r_0), r_1)$ then below that value of the circumradius the line segments p_0s , p_0s' , $\tilde{p}_0\tilde{s}$, and $\tilde{p}_0\tilde{s}'$ are not part of any boundary. This means that there are either three or one non-trivial 1-cycles. In both other cases (an acute triangle, but r larger than the circumradius, or obtuse) these line segments do not contribute to a non-trivial cycle.

Secondly, we consider the triangle $p_0\tilde{p}_0q_0$ (and symmetrically the triangle $p_0\tilde{p}_0\tilde{q}_0$). This triangle is acute thanks to [1, Lemma 20]. If r is smaller than the circumradius of this triangle, the segment $p_0\tilde{p}_0$ contributes to a 1-cycle. If r is larger than the circumradius of this triangle, the segment $p_0\tilde{p}_0$ no longer contributes to a 1-cycle.

If none of the segments $p_0\tilde{p}_0$, p_0s , p_0s' , $\tilde{p}_0\tilde{s}$, and $\tilde{p}_0\tilde{s}'$ form parts of some 1-cycles, then the circumcentre of $p_0\tilde{p}_0q_0\tilde{q}_0$ is enclosed in a void (2-cycle), see Figure 9.

- For every $i \geq 2$ and $r \in [r_{i-1}, r_i)$, the set $(C_i \cup \{p_i, \tilde{p}_i\}) \oplus B(r)$ has homotopy type of a torus with either a circle or a 2-sphere attached, depending on whether the radius r is smaller or larger than the circumradius of the triangle $p_i\tilde{p}_iq_i$. The tunnel or void appears when $r = r_{i-1}$ (and in the case of a tunnel it may change from a tunnel to a void when r equals the circumradius of triangle $p_i\tilde{p}_iq_i$) and disappears at $r = R_i = r_{i+1}$.
- At $r = r_k = 1 - \delta$, the homotopy type of all sets $C_i \oplus B(r)$ changes from that of a torus to that of a circle, since the ‘interior’ of the torus fills up.
- For $r \geq 1 - \delta$, the set $(C_k \cup \{p_k, \tilde{p}_k\}) \oplus B(r)$ has, at first, the homotopy type of two circles that share a point. The two gaps creating the two 1-cycles are identical. Thus, as the radius r increases, the homotopy type of the set $(C_k \cup \{p_k, \tilde{p}_k\}) \oplus B(r)$ changes from



■ **Figure 9** We see the void from two different viewpoints.

that of two circles that share a point to that of two 2-spheres that share a point (there are two voids that around the circumcentres of $p_k, \tilde{p}_k q_k, \tilde{q}_k$ and $p_k, \tilde{p}_k q'_k, \tilde{q}'_k$, which fill up when $r = R_k$), to that of a point.

Similarly, the homology type of every other set $(C_i \cup \{p_i, \tilde{p}_i\}) \oplus B(r)$ changes from that of a circle to that of a 2-sphere (when r equals the circumradius of the triangle $p_i, \tilde{p}_i q'_i$ which is also the circumradius of $p_i, \tilde{p}_i \tilde{q}'_i$), to that of a point (at $r = R'_i$). This happens for r larger than $1 - \delta$ because as long as $r < 1 - \delta$, the z -axis in Figure 4 is not intersected by the thickening of the sample P .

References

- 1 Dominique Attali, Hana Dal Poz Kouřimská, Christopher Fillmore, Ishika Ghosh, André Lieutier, Elizabeth Stephenson, and Mathijs Wintraecken. Tight bounds for the learning of homotopy à la Niyogi, Smale, and Weinberger for subsets of Euclidean spaces and of Riemannian manifolds. *arXiv preprint arXiv:2206.10485, accepted for SoCG 2024*, 2024.