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Experimental set-up for thermal measurements at the nanoscale using an SThM probe with niobium nitride thermometer

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Scanning Thermal Microscopy (SThM) has become an important measurement tool for characterizing the thermal properties of materials at the nanometer scale. This technique requires a SThM probe that combines an Atomic Force Microscopy (AFM) probe and a very sensitive resistive thermometry; the thermometer being located at the apex of the probe tip allows the mapping of temperature or thermal properties of nanostructured materials with very high spatial resolution. The high interest of the SThM technique in the field of thermal nanoscience currently suffers from a low temperature sensitivity despite its high spatial resolution. To address this challenge, we developed a high vacuum-based AFM system hosting a highly sensitive niobium nitride (NbN) SThM probe to demonstrate its unique performance. As a proof of concept, we utilized this custom-built system to carry out thermal measurements using the 3ω method. By measuring the $V_{3\omega}$ voltage on the NbN resistive thermometer in vacuum conditions we were able to determine the SThM probe's thermal conductance and thermal time constant. The performance of the probe is demonstrated by doing thermal measurements in-contact with a sapphire sample.

I. INTRODUCTION

Mastering local temperature fields and thermophysical phenomena in nanometric-scale devices and structures plays a crucial role in growth of new technologies involving thermal issues [1–3]. One of the most critical examples is the production of unwanted heat in electronic transistors due to transport of electrons, which reduces the lifetime or induces failures in integrated electronic circuits and devices [4]. In addition, manipulating heat transport in nanostructures is of crucial interest, so as to utilize them for thermal energy conversion, storage technologies such as solid-state thermoelectric power nanogenerators [5-8] or for local refrigeration based on the Seebeck and Peltier effects [9, 10]. These developments require measurements of heat flow or thermal conductivity at the nanometer scale. Concerning heat transport in nano-contact or atomic junctions, numerous debated issues have been raised recently that clearly require new tools for further investigations [11–14]. Therefore, precise thermal measurements from micrometer to nanometer scales are essential for fundamental understanding of phonon heat transport but also for the optimized development of novel microelectronic, optoelectronic and innovative thermal nanodevices.

Among many different existing thermal measurement techniques [15, 16], scanning thermal microscopy (SThM) is one of the best available tool to probe temperature and thermal properties of materials with high spatial resolution at very small length scales [17–19]. The first development towards the thermal sensing was introduced by Williams and Wickramasinghe in 1986 [20]. They designed a probe for mapping the topography images of conducting and non-conducting materials to resolve the shortcomings of the Scanning Tunneling Microscopy (STM) technique, which is limited to conducting materials. The thermal probe was fabricated by placing a thermocouple junction at the end of the conventional STM tip, and the technique was known as Scanning Thermal Profiler (STP) [20]. In this technique, the temperature of the thermal probe works as an intermediate quantity for maintaining constant tip-sample distance, in a similar way to a STM, where the tunnelling current is used to regulate the height of the tip. Although the STP technique could not be used to make the thermal maps of the surface, this was the beginning of the Scanning Probe Microscopy (SPM)-based technique in thermal science. Afterwards, continuous efforts have been carried out in the field of thermal microscopy based on STM [21]. However, the major disadvantage of this technique is that an STM-based system can only be applied to electrically conducting samples. Conversely, the Atomic Force Microscopy (AFM) technique can be utilized on all kinds of solid materials such as metals, semi-metals, semiconductors and insulators. Therefore, AFM-based microscopy is preferred over STM for dielectrics. Since AFM is proven to be a versatile technique as various sensors at the AFM probe tip could be integrated, multiple aspects of localized measurement will be allowed, especially thermal ones [22].

A breakthrough in the field of thermal science took place in 1993 when Majumdar *et al.* [23] developed a thermal probe by replacing the conventional AFM probe with two metallic wires to form a thermocouple junction. This probe was adequate to map the surface topography and the thermal map of a metal-semiconductor field-effect transistor simultaneously. Notably, this AFMbased thermal microscope proposed by Majumdar *et al.* [23] could be accounted as a building block for the modern SThM setups. Its working principle is based on scanning the surface of a specific sample with a heat-sensitive AFM probe. A temperature gradient between the probe and the sample creates a heat flow that induces a change in the probe temperature-dependent physical property. For SThM, several types of thermo-sensitive sensors have been developed based on temperature dependent physical properties such as thermoelectric voltage [23–26], electrical resistance [27–31], thermal expansion [32] and fluorescence [33].

Among various possible thermometers, electrical resistance-based thermal sensors are the most widely used for their convenience of fabrication, use and sensitivity. The use of such sensors on AFM cantilevers for efficient SThM measurements requires a high temperature coefficient of the sensor's electrical resistance (TCR), low thermal conductivity of the probe materials and an electrically insulated support. This implies that, in order to maximize the heating of the sensor, it is preferable to use a cantilever with high thermal resistance, typically SiN. Commonly used materials for thermal sensors include metallic thin films of platinum [34], alloy of platinumrhodium (Pt90/Rh10) [27, 28], palladium [35, 36], low doped silicon probes [29] and alloy of platinum-carbon (Pt-C) [37]. The commercially available probes are of three kinds: either the Wollaston wire probe, palladium probes (Pd probes) with a SiN cantilever or doped Siprobes (DS probes) [11, 35, 38]. The Wollaston wire probe was the first commercialized probe; the cantilever is composed of a U-shaped Wollaston wire 75 μ m in diameter and the tip, which is also the probe's thermoresitive sensor, it consists of a V-shaped platinum-rhodium (Pt90/Rh10) filament obtained by electrochemical etching of the Wollaston wire. The documented spatial resolution and TCR of Wollaston wire probes are about $0.5 \ \mu \text{m}$ and $1.66 \times 10^{-3} \text{K}^{-1}$ respectively [38]. Meanwhile, for Pd probes, the cantilever is made of 500 nm thick SiN with an integrated Pd thin film at the apex of the tip which acts as a resistive thermal sensor. It can provide thermal images with sub-100 nm spatial resolution and its TCR is reported to be about $1.2 \times 10^{-3} \text{K}^{-1}$ [35]. Concerning DS probes, the cantilever is micromachined in a U shape with high doping level and a low doped platform, which operates as the thermal sensor [11]. The radius and height of the Si tip, which is supported on the low doped platform, are about 10 nm and 500 nm, allowing the mapping of materials with very high spatial resolution, but these probes suffer from a relatively low TCR of $1.2 \times 10^{-3} \mathrm{K}^{-1}$ and low thermal resistance of the cantilever [39].

Finally, through a compromise between thermal and spatial resolutions, available commercial thermal probes can reach high spatial resolution but exhibit a meagre thermal sensitivity. Such low thermal sensitivities compel the need of a high thermal exchange between the probe and the sample, *i.e.* a large temperature gradient is required, excluding measurements at low temperature differences (temperature oscillations smaller than 10 K). Indeed, as pointed out by Shi *et al.* [24], efficient SThM probes have to be fabricated using low thermal conductivity materials, like SiN or SiO₂, in order to minimize heat loss from the sample to the cantilever. Besides, newly developed SThM probes require innovative thermometry to reach drastic improvements in their thermal sensitivity [40] along with low-noise electronics for the acquisition of the thermal signal with high accuracy.

To meet these requirements, we developed in this work a highly sensitive electro-thermal measurement setup by combining a thermal probe equipped with a highly sensitive niobium nitride (NbN) thermometer in a high vacuum-based scanning thermal microscopy system. The SThM setup was custom-built by modifying an Enviro-Scope SPM scanning probe microscope system, which involved designing and fabricating an adapted probe holder and integrating low-noise electronics for the data acquisition for thermal measurements, as it will be described in the following. We will show the temperature calibration of the electrical resistance of the highly sensitive NbN sensor integrated on flat substrate and at the tip of the AFM probe. Finally, we employed the dynamic 3ω -SThM mode under high vacuum conditions to determine the thermal properties of the probe [28, 31, 36, 41, 42]. The measured thermal properties were compared with theoretically calculated values based on the probe's geometry and composition. Results show that SThM experiments allow to obtain thermal properties at the nanoscale, as it will be demonstrated on a sapphire sample.

II. ADAPTATION OF THE AFM FOR VACUUM-BASED STHM MEASUREMENT

The first purpose of this work is to adapt the EnviroScope SPM instrument for quantitative thermal measurements at the nanoscale. In order to achieve this, we had to integrate the thermal control unit in the AFM instrument. Figure 1 shows the schematic representation of the AFM instrument that has been modified into SThM setup by integrating a thermal probe and thermal control unit. Generally, the thermal control unit incorporates some or all of the following elements: (a) a specific probe holder to install the SThM probe, the holder being used to establish an electrical connection between the probe and the external electronics, (b) low noise electronics that consist of several instruments such as a lock-in amplifier, a voltage to current converter able to deliver nanoampere, a variable resistance box, and a Wheatstone bridge or a differential bridge. This setup is used to measure the variation of resistance of the NbN thermometer to measure the temperature of the tip.



FIG. 1. Schematic representation of the SThM instrument where the regular AFM cantilever has been replaced by a SThM probe that has a temperature sensor at the tip apex. By applying an AC current I through the current source (piloted by the lock-in amplifier), a voltage V is measured by the lock-in amplifier to deduce the resistance of the thermometer.

SThM probe type	DS [11]	Pd probe [35]	NbN probe [40]
Thermal sensor	doped Si	Pd	NbN
Tip radius (μm)	0.02	0.1	0.05/0.2
Tip height (μm)	0.5	10	3
Sping constant (Nm^{-1})	1	0.35	0.15
Resistance (kOhm)	0.5	0.4	5 to 20
$TCR (\times 10^{-3} K^{-1})$	1.2	1.2	4.5

TABLE I. Comparisons of probe's parameters between DS, Pd and the NbN based probe of this work.

A. Micro and nanofabrication of the NbN thermal probe

Experiments will be carried out using NbN based SThM probes installed in the EnviroScope SPM instrument. The NbN probes are fabricated following a process that has been already described in a previous article [40] from a commercial SiN AFM probes OTR8-10 from Bruker $(\widehat{\mathbf{R}})$ having low thermal conductivity and electrical insulating properties. These probes have triangularshaped cantilevers and pyramidal-shaped tips with a tip height of 2.5 to 3.5 μ m. The length and width of these SiN cantilevers are 140 μ m and 30 μ m respectively, and 800 nm thick; the apex of the tip having a radius of curvature about 15 nm to 20 nm. The first characterizations of the cantilever indicate a resonance frequency of 22.33 kHz and a spring constant of 0.1544 Nm⁻¹. Since all the measurements will be performed under vacuum at a pressure of 5 $\times 10^{-6}$ mbar, there will be no water

meniscus and consequently the thermal exchange will be significantly smaller than measurements under air conditions (no heat transfer between the probe and the sample through the water meniscus that can condense at the contact and through the air) [43, 44]; this is an advantage to get more reproducible thermal measurements. However, the drawback is that the effective contact surface that will contribute to the thermal transport between the tip and the surface is *de-facto* reduced, the overall experiment being more sensitive to roughness and sample surface state. We decided then to work with a blunt tip to increase the exchange surface and hence the heat flow in a controllable way. Cutting part of the apex of the tip modifies the radius of curvature with an increased exchange surface, a square flat apex of about 250 nm side, as shown in Figure 2. To proceed with the fabrication of the blunt tip, one of the most critical parameters to take into consideration is the angle of the cutting plane. Indeed, in our AFM equipment, the installed probe has a



FIG. 2. Schematic illustration of the original AFM probe (a), and (b) FIB modified SThM probe having an equivalent diameter of tip about 250 nm, the yellow line indicates the gold leads and the green line the NbN thermometer located on one face of square based pyramid. (c) and (d) are the SEM images of the NbN-SThM probe with blunt tip with a square flat apex of about 250 nm side. (c) Top-view of AFM probe with the triangular-shaped cantilever and tip. (d) Close-up SEM micrograph of the blunt tip with integrated NbN thermometer near the apex of the tip.

tilted angle of 12° relative to the horizontal plane. In this respect, we considered this angle to cut properly the tip so that when the probe touches the sample, the size and shape of the contact of the tip and the sample surface are parallel, the contact being then equivalent to those of the tip apex.

To cut the SThM tip, we used the dual-beam platforms named as LEO-1530 field emission SEM system, combining a Scanning Electron Microscope (SEM) and a Focus Ion Beam (FIB) column. After having performed that step, we then proceeded with the optimized fabrication process to integrate the 70 nm thick NbN thin thermometric film at the apex of the AFM tip along with electrical 50 nm thick gold leads on the cantilever in a four-wire configuration as already described in a previous publication [40]. Figure 2 shows the SEM-FIB images of the SThM probe having a blunt tip with a mean diameter of ~ 250 nm. The contact surface of the probe has been increased potentially by one order of magnitude to lower the thermal interface resistance between the tip and sample during the thermal measurements under vacuum. However, we keep in mind that as this procedure

is enhancing the heat flux from tip to sample, the spatial resolution of the thermal measurement is partly degraded.

В. **Thermal Probe Holder**

One of the main modifications in the microscope was to design and manufacture a novel thermal cantilever holder capable of performing resistive thermometry using fourwire electrical measurements. The most common requirements of the thermal cantilever holder are lightweight, easy installation and exchange of thermal probe, and compatibility with laser alignment. Figures 3 (a) and (b) show the geometry of the probe holder constructed in $SolidWorks(\widehat{\mathbf{R}})$. The main body of the cantilever holder is made of $Macor(\widehat{\mathbf{R}})$ ceramic-based glass with low thermal conductivity, electrically insulating, strong, rigid, and has zero porosity. This ceramic based-glass is well suited for measurements at ambient conditions as well as highvacuum SThM experiments. On this holder, the thermal probe is installed using a metal clamp with a tighten-



FIG. 3. The geometry of a new SThM cantilever holder used for thermal measurement. (a) Top view consists of four goldplated cylinders to establish the electrical contacts. (b) For driving cantilever oscillations in dynamic operation modes, a dither piezo is integrated on the backside of the holder. (c) and (d) Photographs of the SThM probe installed on the probe holder with the Au wire bonding. (e) and (f) represent the close-up optical images of the wire-bonded gold pads on the SThM chip.

ing screw and tilted 12° relative to the horizontal plane concerning the longest dimension. Since the SThM experiments will be performed using a resistive thermometer in four-wire configuration, we have integrated four gold-plated cylinders in the holder for establishing the electrical connections by microbonding. In addition, a dither piezo is integrated on the backside of the holder for operating the thermal cantilever in dynamic mode if needed. Figures 3 (c) and (d) illustrate the photograph of an SThM probe installed on the probe holder where Au wires were used to microbond the probe to gold plated cylinders. Figures 3 (e) and (f) show the close-up optical images of the wire-bonded gold pads on the SThM chip.



FIG. 4. Simplified schematic of the differential bridge used in the SThM setup for 3ω experiments. The gain of the first stage of the amplifier is two and the gain of the second stage is five. The variable resistance is used to compensate the $V_{1\omega}$ coming from the SThM NbN resistance. V-to-I refers to the voltage to current converter.

C. Low-noise electronics for data acquisition

The second important task in this work is to set-up the proper measurement chain to characterize the thermometer and perform thermal measurement using the 3ω method [28, 30, 45]. The electrical resistance of thermometer versus temperature will be obtained by a measurement based on a dynamic method using an AC current, the AC voltage being measured by a lock-in amplifier equipment. The thermal properties of the system are obtained by measuring the 3ω voltage, as it will be explained later, again requiring lock-in amplifier-based measurement chain.

In order to convert the AC voltage generated by the lock-in into a measuring current, we used an instrument developed at in-house that allows us to convert both DC and AC voltage into DC and AC current. This voltage to current converter can provide very stable electrical current from 1 nA to 1 mA with a very low thermal drift of about 1 ppm/°C.

To accurately measure the electrical signal and improve the signal-to-noise ratio, various measurement bridges can be considered. The classical Wheatstone bridge is the most widely used for SThM measurements. It requires two known resistances with an additional variable resistance and a resistive thermal probe. The basic principle of using the Wheatstone bridge is based on balancing the bridge. For that, the resistance of the thermal probe is balanced by tuning the variable resistance. During the experiment, a slight variation in the SThM probe temperature can be detected with high sensitivity. The disadvantage of this setup is that it cannot be utilized in a four-wire configuration [46]. Notably, four-wire geometry (like for the NbN probe) provides more localized measurements of the sensor electrical resistance since it does not include the electrical resistance of the electrical leads, the contact resistance and external measuring cables.

We then decided to use a homemade differential bridge setup adapted to two-terminal or four-terminal thermal probes built from three INA103 instrumentation amplifiers. Figure 4 illustrates the schematic of a simplified SThM setup with a current source, variable electrical resistance, lock-in amplifier, and the differential bridge that contains two amplification stages. When the differential bridge is balanced (the variable electrical resistance and the one of the thermal probe are equal) the output voltage at the first harmonic of the differential bridge is greatly reduced. Assuming that the variable resistance has a negligible temperature coefficient of resistance, the thermal signal will be obtained from the third harmonic of the output voltage of the differential bridge, as it will be explained later (see section III B). The amplification $(gain \times 10)$ of the differential bridge has been chosen to ease the low noise detection with the lock-in amplifier.

III. THERMAL PROBE: CALIBRATION AND CHARACTERIZATION

A. Calibration of the NbN thermometers

In this work, the NbN thin film used as a resistive thermometry sensor is the cornerstone of the SThM probe. The calibration of the thermometer is done by measuring the NbN electrical resistance R as a function of the temperature T. During the calibration procedure of Rversus T, the temperature of the NbN resistance is measured by a home-made temperature controller (TRMC2) using a calibrated platinum thermometer as a reference; the temperature being stable and regulated with a sensitivity better than 5 mK at 300K.

The performance of the NbN thermometer on the pyramid of the AFM probe is evaluated compared to NbN thermometers prepared on a regular Si/SiN flat surface. Indeed, we want to check that depositing the NbN materials on the non-planar pyramid of the tip does not change significantly the material properties.

The electrical characterizations of integrated NbN resistance on a flat SiN substrate and AFM probe are conducted using a four-probe measurement setup by applying current into the outer leads and measuring the voltage drop from the inner leads. The range of amplitude of the applied current $I_{1\omega} = I_0 \cos(\omega t)$ is chosen from 10 nA to 1 μ A that leads to a power dissipation in the sensor of $P_{2\omega} = R_0 I_{1\omega}^2$ from few tens of picowatts to few nanowatts preventing any sensor overheating during the calibration procedure. The voltage drop is constantly monitored using a lock-in-amplifier; a linear I-V behavior (not shown) is observed in that current range, that indicates negligible Joule heating inside the probe.

Figure 5 (a) shows the calibration curve of the NbN thermometer deposited on a regular Si/SiN flat substrate while Figure 5 (b) shows the calibration curve of the



FIG. 5. The electrical response and temperature coefficient of resistance of the NbN thermometers are illustrated as a function of temperature. (a) NbN thin film of thickness 70 nm was deposited on the flat Si/SiN substrate. The electrical resistance (black squares) and TCR (red squares) of NbN thin film are plotted as a function of temperature. The TCR was obtained to be around $|8 \times 10^{-3}|$ K⁻¹ near room temperature. (b) The black squares represent the experimentally obtained values of electrical resistance of the NbN thermometer on the SThM probe. The red squares represents the TCR of the NbN thermometer of the SThM probe showing a value of TCR to be around $|4.5 \times 10^{-3}|$ K⁻¹ near room temperature. All lines are guides to the eyes.

NbN thermometer integrated at the apex of the AFM probe; in insets the corresponding SEM image of each sample. The electrical resistance of the NbN thermometer is plotted as a function of temperature, where black squares are the experimentally measured value of electrical resistance. The red squares represents the absolute value of TCR $|\alpha|$ defined as $\alpha = 1/R \times dR/dT$ of the NbN thermometer on the flat surface, which is around $\alpha = -8 \times 10^{-3} \text{ K}^{-1}$ near room temperature, consistent with previously published results [47]. One should note that the negative TCR of the NbN thin film is a signature of a Mott-Anderson insulator materials, *i.e.* a type of materials that undergoes a transition to the insulating

state as the temperature is lowered [47, 48].

Figure 5 (b) depicts the temperature-dependent electrical resistance (black squares) and TCR (red squares) of the SThM probe. We measured the change in the electrical resistance from 16 k Ω up to 14 k Ω in the temperature range of 305 K to 335 K, leading to an extracted absolute value of TCR of $|\alpha| = 5 \times 10^{-3} \text{ K}^{-1}$ at room temperature. We can note that the measured electrical resistance and TCR of the NbN thermometer between the SThM probe and flat surface are different. This change of TCR could has various origins: variation of thickness or nitrogen contents in the NbN film. The observed decrease can be preferentially attributed to a higher amount of nitrogen contents in the NbN film on the pyramid leading to higher electrical resistance and, consequently, a lower TCR [47]. In the case of the SThM probe, a probable reason for the excess amount of nitrogen in the NbN film is potentially due to overheating at the AFM tip (thermally isolated compared to flat Si/SiN thick substrate) during the sputtering process.

B. Experimental conditions for thermal measurements by 3ω method using the NbN SThM probe

To qualify the potentialities of these NbN based SThM probes, we have performed thermal measurements, first, on the bare probe and then in contact with a sapphire sample of mean roughness less than 1 nm. The thermal measurements have been done by the 3ω method vastly used for the measurement of thermal conductance either on bulk substrate [45], on membrane [49] or on suspended nanowires [50].

The principle of the 3ω method relies on employing a one-dimensional thin metal film deposited on a sample that acts both as a heater and thermometer to create a heat source as depicted in Figures 6 (a) and (b) through an SEM picture and a simple thermal model. In 1999, Fiege *et al.* [51] combined the SThM with 3ω method to perform quantitative thermal measurements with higher accuracy, a method further developed since then [28, 30, 31, 36, 41]. The basic idea of this technique is the same as classical 3ω : an alternating current of angular frequency ω is applied through the NbN metal film that results in heating due to the Joule effect. The heat generated in the thermometer film at the apex of the probe (see Figure 6 (a)) induces temperature oscillations at angular frequency 2ω of the pyramid of the SThM probe. Therefore, temperature oscillation leads to a periodic change in the electrical resistance of the metal film at angular frequency 2ω . Since the thermometer is biased by a current at angular frequency ω , consequently, a voltage at angular frequency 3ω develops across the metallic line proportional to the temperature oscillation at 2ω . From this temperature oscillation, the thermal properties of the system beneath the thermometric line are extracted.



FIG. 6. (a) SEM image of the SThM probe used in this study. The red circle indicates the location of the heat source, the cantilever as a thermal link and the chip body as a heat sink. (b) Drawing of the thermal scheme of the cantilever, the heat is transported from the hot part of the SThM probe (heat source) to the chip body (heat sink) in vacuum conditions through the thermal conductance G_{probe} .

Let us mention the important equations proper to this active 3ω -SThM mode where the tip is self-heated by an AC current that results in significant Joule heating. As discussed above, since the current is given by $I_{1\omega} = I_0 cos(\omega t)$ then the electrical power $P_{2\omega}(\omega)$ dissipated in the NbN thermometer resistance R_0 of the SThM probe reads as:

$$P_{2\omega}(\omega) = \frac{R_0 I_0^2}{2} (1 + \cos(2\omega t))$$
 (1)

where

$$P_{2\omega} = \frac{R_0 I_0^2}{2}$$
 (2)

refers to the amplitude of the power dissipated in the NbN thermometer.

When the tip is not in physical contact with the sample, then the temperature oscillation in the probe is related to the heat flux and thermal conductance of the probe as:

$$Q_{2\omega}^{probe} = G_{probe}(T_{2\omega-oc}) \tag{3}$$

where $T_{2\omega-oc}$ is the amplitude of the temperature oscillation of the SThM probe where *oc* stands for out-ofcontact. Then, the thermal conductance of the SThM probe can be determined by equating the heat flux through the cantilever $(Q_{2\omega}^{probe})$ to the electrical power $P_{2\omega}$ (at low frequency) that is required to achieve the temperature oscillation amplitude $T_{2\omega-oc}$ of the NbN SThM probe above the room temperature:

$$P_{2\omega} = G_{probe} \times T_{2\omega-oc}$$

$$G_{probe} = \frac{R_0 I_0^2}{2T_{2\omega-o.c}}$$
(4)

In SThM studies, knowledge of the probe's thermal conductance (G_{probe}) is critical to evaluate the heat transport through the cantilever and build the adapted thermal model adapted to describe and reproduce the measurements in order to identify sample temperature or thermal properties. We can determine the G_{probe} by performing the experiment in vacuum conditions when the probe is in and out-of-contact configuration. An other important parameter is the thermal time constant of the probe as it is the time required to reach thermal equilibrium after a change of temperature of the NbN thermometer and governs the cut-off frequency of the probe as a thermal low-pass filter. We will measure and calculate it in the following using 3ω -SThM measurement.

The experiment is performed in high-vacuum conditions $(3 \times 10^{-6} \text{ mbar})$ when the probe is far from the sample. A predetermined AC current is supplied through the probe that results in Joule heating as illustrated in Figure 4. We measured the $V_{3\omega}^{rms}$ voltage amplitude response for various angular frequencies ω , rms refers to the root mean square value. In order to confirm the reliability of the experiment, $V_{3\omega}^{rms}$ signal should be linear with applied heating AC current I_{rms}^3 for a fixed frequency whatever the geometry of the transducers is [45, 49, 50]. This has been checked, as shown in Figure 7 (a), where a linear variation of $V_{3\omega}^{rms}$ is observed as a function of I_{rms}^3 at room temperature. The $V_{3\omega}^{rms}$ voltage amplitude variation has been recorded at various electrical frequencies while keeping the heating rms AC current at a value of 30 μ A. The noise on the 3 ω voltage has also been measured as presented in Figure 7 (b) showing a standard deviation of 2×10^{-6} V/ $\sqrt{\text{Hz}}$. This noise is far above the expected Johnson noise ($\approx 16 \text{ nV}/\sqrt{\text{Hz}}$) for a resistance of 16 kOhm at room temperature indicating the presence of other noise sources like the vibrations of the experimental set-up, electrical contact resistance between the thermometer and the leads etc... that need to be further investigated.

C. Measurement of the thermal properties of the cantilever

Now, by measuring the variation of $V_{3\omega}$ as a function of the angular frequency ω we will be able to extract an experimental thermal characteristic time of the SThM probe and compare it to the calculated one. Figure 8 shows the $V_{3\omega}$ voltage response of the probe as a function of electrical frequency in the absence of a laser beam on the backside of the SThM cantilever.



FIG. 7. (a) Measurement of the linear behaviour of $V_{3\omega}^{rms}$ and I_{rms}^3 for different particular frequencies. (b) Measurement of the $V_{3\omega}^{rms}$ voltage noise in the SThM probe inside the scanning thermal microscope setup at a base pressure of 5×10^{-6} mbar. Solid circles (black) are the $V_{3\omega}^{rms}$ voltage response of the thermal tip at 293 K as a function of time, measured using the SR-830 lock-in amplifier. The inset represents the histogram (orange) of the thermal probe corresponding to its voltage response with a Gaussian fit (solid black line).

We used the experimental results presented in Figure 8 (a) obtained under vacuum conditions for determining the thermal conductance of the probe when the AFM laser is off. The electrical resistance R_0 of the thermometer of this probe was measured to be 16 kOhm at room temperature with a calibrated TCR value of $4.5 \times 10^{-3} \text{K}^{-1}$. The amplitude of the electrical power dissipated in the NbN thermometer was about $14.4 \ \mu\text{W}$ as calculated using Eq. 2 that leads to increase the temperature at the apex of the tip. In the following equation, we take the very low frequency limit of the temperature oscillations:

$$T_{2\omega} = \frac{2V_{3\omega}^{rms}}{R_0 I_{rms}\alpha} \tag{5}$$

noting that it is relatively frequency-independent up to 5 Hz. We used Eq. 6 to determine the amplitude of the temperature oscillation of the probe $T_{2\omega}$ estimated to be about 5.9 K. When the probe is not in contact with the sample under vacuum conditions, then, the electric power $(P_{2\omega})$ is equivalent to the heat that flows from the NbN thermometer along the cantilever to the heat bath (the chip):

$$P_{2\omega} = Q_{probe} = G_{probe} T_{2\omega} \tag{6}$$

Using Eq. 6, knowing the applied power and the measured $T_{2\omega}$, the thermal conductance of the probe is approximately $2.4 \times 10^{-6} \text{WK}^{-1}$.

The experimental thermal time constant of the probe can be defined as $\tau_{th} = (2\pi f_{cutoff})^{-1}$, where f_{cutoff} is the cut-off frequency at which the $V_{3\omega}$ voltage is attenuated by a factor of $\sqrt{2}$ of the maximum value [25]. The experimentally obtained value of the cut-off frequency is about 60 Hz (see Figure 8 (a)), and the measured thermal time constant of the SThM probe is about 3 ms, a value in relatively good agreement with the order of magnitude of millisecond found from rough calculations, as we will show below.

D. Calculation of the expected thermal conductance and thermal time constant

Here, we will calculate the expected probe's thermal conductance and thermal time constant using the geometry, dimension, and thermal conductivity of the various materials from which the probe is made. For simplicity, we first divided the SiN cantilever into two rectangular plates, having length, width, and thickness of $200 \ \mu m$, $40 \ \mu m$, and $0.8 \ \mu m$ respectively. Second, we used the literature value of the thermal conductivity (κ) and specific heat (C_p) of the SiN, which are approximately $3 \text{ Wm}^{-1}\text{K}^{-1}$ and 0.8 $\text{Jg}^{-1}\text{K}^{-1}$ respectively [49, 52, 53]. Using these data of the SiN cantilever, we estimated the thermal conductance due to SiN material (G = kS/l;S cross-section area and l is the length) to be approximately 10^{-6} WK⁻¹. In addition, we took into account the four electrical gold leads with the following dimensions: length 200 μ m, width 2 μ m, and thickness 50 nm. The obtained thermal conductance due to the electrical leads is equivalent to $6\times 10^{-7}~{\rm WK^{-1}}.$ As all the thermal conductances are in parallel, they are additive, we then estimated the total thermal conductance G_{probe} of the probe to be on the order of 1.6 $\times 10^{-6}$ WK⁻¹.

This value is a little lower than the one measured above from the material composition of the probe $G_{probe} = 2.4 \times 10^{-6} \text{ WK}^{-1}$; this can be explain by the fact that we omitted, in the calculation, the contribution to the thermal transport of the probe of the gold reflecting layer on the back side of the AFM probe.

In order to go beyond the approximate calculation of the probe's thermal properties, we used the Finite Element Method (FEM) to numerically simulate the ther-



FIG. 8. a) Measurement of the $V_{3\omega}^{rms}$ voltage amplitude and corresponding temperature oscillation amplitude of the SThM probe at 2ω as a function of electrical frequencies in vacuum conditions. b) The measured $V_{3\omega}^{rms}$ in black dots is plotted against the frequency whereas the red dots stands for the finite element method (FEM) simulation results. (c) Temperature profile in the probe cantilever as calculated by FEM, the temperature is given by the color scale that goes from 0 K (dark red) to 16 K (light yellow).

mal behavior of the probe. A similar methodology as the one presented in ref. [31] was carried out where the 3D model constructed for this work follows the geometrical, electrical and thermal properties of the different materials of the NbN SthM probe as described in a previous work [40]. The model couples the electrical current with heat transfer module so that Joule heating is simulated in the probe by applying an electrical current as a boundary condition in the NbN layer. Concerning thermal boundary conditions, we assume that all free surfaces are adiabatic surfaces, this is consistent with the experiments done in vacuum where there is no convection loss. We can also neglect the heat flow through radiation since temperature gradients are small. The 3ω voltage is obtained by post-processing the results of the temporal evolution of the voltage across the probe and isolating its 3ω component from the first harmonic.

In Fig. 8(b), we report an excellent agreement between experimental results and simulations for both 3ω rms voltage and frequency behavior. The discrepancy observed at frequencies above the cut-off frequency may be attributed to the slight deviations in the properties of the fabricated probe, especially its specific heat. The temperature profile along the probe is given in Fig. 8(c) where the hot spot is clearly located at the apex of the pyramid.

The thermal time constant τ_{th} can be defined as the ratio of specific heat to thermal conductance of the system:

$$\tau_{th} = C_p / G_{probe} \tag{7}$$

where C_p is the heat capacity with a unit of JK⁻¹. First, we wanted to calculate the mass of the heat source (as depicted in Figure 6) located at the end of the cantilever; note that here we only considered the SiN material for calculation. The density of the SiN is taken from the literature which is 3 gcm^{-1} [49, 54]. Second, the volume of the heat source is calculated to be $6.5 \times 10^{-9} \text{ cm}^3$, using length, width and thickness of 30 μ m, 20 μ m and $0.8 \ \mu m$, respectively corresponding to the isothermal triangular area of the cantilever (see Figure 6). Finally, the mass of the heat source is found to be 1.5 ng. Then, the heat capacity C_p can be calculated by multiplying the mass with the specific heat of the SiN and found to be $\tau_{th} = 1.2 \times 10^{-9} \text{ JK}^{-1}$. Using Eq. 7, the thermal time constant is then estimated to be on the order of the millisecond.

E. Impact of the laser beam

When operating an AFM measurement, one needs to shine a laser beam on the cantilever to get the probe into contact with the sample to be measured with a controlled force between the probe and the sample or to perform force-distance curves. In this work using the EnviroScop, the laser beam has a power of 1 mW knowing that only a fraction of the power will be absorbed by the cantilever. This power will contribute to raise the DC probe's temperature and modify its thermal response. In Figure 9, the impact of the laser beam on the temperature oscillation amplitude is illustrated. This change can be explained by considering the DC overheating in the thermal probe via absorption of the laser beam. In our measurement we have measured that this increase in the probe's DC temperature in turn decreases the electrical resistance R_0 and its TCR. R_0 of the NbN thermometer from 16 k Ω to 15 k Ω corresponding to a $\Delta T_{DC} = 14$ K. Consequently, we observed the reduction in the voltage amplitude of the $V_{3\omega}$ in presence of the laser and the

corresponding decrease in the amplitude of temperature oscillations $T_{2\omega}$ as shown in Figures 10 (a) and (b). However, this change in the amplitude of $T_{2\omega}$ does not prevent further measurements in contact by $V_{3\omega}$ -SThM experiment as we will see in the following.



FIG. 9. Temperature oscillation amplitude $T_{2\omega}$ as a function of electrical frequency in-presence and in-absence of the laser beam on the probe cantilever.

In Figure 9, when the laser illuminates the cantilever, the induced temperature oscillation amplitude in the probe is reduced from around 6 K to 5 K for an electrical power dissipated in the SThM probe of 13.4×10^{-6} W by using an applied current of 30 μ A in the electrical resistance of the NbN thermometer of 15 k Ω . In this case, we measured a G_{probe} to be 2.7×10^{-6} WK⁻¹, a higher value than the one measured from the laser-off experiment. Since all the 3 ω -SThM measurements will be carried out in the presence of the laser, the precise knowledge of G_{probe} in the laser-on configuration is essential to quantify the amount of heat exchanged between the probe and a sample surface.

IV. STHM MEASUREMENT IN CONTACT AND OUT-OF-CONTACT ON SAPPHIRE SAMPLE

After having demonstrated that we can obtain the thermal conductance of the cantilever from the 3ω measurement, we will proceed with a thermal conductivity measurement using the SThM probe of a reference sample in contact, in this case sapphire, using the SThM probe operated in contact mode.

In the previous section, we demonstrated that the thermal conductance of the cantilever of the probe is obtained from 3ω measurements. In this section, we proceed with the measurement of the thermal conductivity of a reference sample, in this case crystalline sapphire, operating the SThM in contact mode. This measurement requires an appropriate thermal model. We will first discuss the details of the SThM thermal model developed to interpret the $V_{3\omega}$ voltage, to understand the different routes of heat transport under vacuum conditions and to extract the thermal resistance or thermal conductance of the system.

A. Thermal model for thermal conductance measurement in contact

The comparison of the SThM thermal models between non-contact and in-contact is presented in Figure 10, the probe being operated under vacuum in active 3ω mode in both cases. In the non-contact mode (see Figures 10 (a) to (c)), the heat transport can only occur from the tip to the chip body, which is represented by the heat flow Q_{probe} , the chip body acting as a heat sink at room temperature. The in-contact mode, Figures 10 (d) to (f)), results in opening another channel to heat flow from the probe into the sample. Due to the heat transport into the sample, the measured amplitude of temperature variation of the probe decreases, as shown in Figure 10 (f) as compared to Figure 10 (c).

In case of contact, the additional thermal paths to G_{probe} are of two kinds, firstly the thermal contact conductance between the tip and the surface G_c and second the thermal conductance that corresponds to spreading the heat in the sample G_{sample} .

First, the thermal contact conductance G_c will refer to the thermal conductance of the SiN-sample mechanical contact between the probe and the sample. $R_c = 1/G_c$ naturally includes the thermal boundary resistance that occurs at the interface between two dissimilar materials or the same material with different crystallographic orientations that leads to temperature discontinuity at the interface. As a contact is never perfect, different parameters can influence R_c [18, 19] such as (i) water, contamination or oxide layers that can cover surfaces and (ii) surface roughness or weak coupling bonds between the atoms of contacting solids. Advanced contact models have been developed to account for the weak coupling. The transmission probability is then related to the mechanical coupling spring between the two solids.

 G_{sample} describes the conductance of heat flow into the material specimen under investigation. In case of a bulk homogeneous sample with an isotropic thermal conductivity κ and whose dimensions are much larger than the dimension of the heat source the SThM probe's hot apex can be modeled as a circular heat source at the flat apex of radius b_c . Then, the thermal spreading conductance of the sample can be expressed as [55]:

$$G_{sample,spread} = K\kappa b_c \tag{8}$$

where K is a geometrical factor describing the heat spreading within the sample, κ the thermal conductivity of the sample and b_c is the total contact radius that takes into account all the mechanisms of heat transfer through the solid-solid contact. K = 4 is often used for a discoïdal contact as the heat source can be considered to be isothermal due to its small dimensions [36]. If b_c is lower than the average mean free path of energy carriers in the material Λ , another thermal resistance within the sample must be considered at the level of the contact [56]. In order to account analytically for the partly ballistic dissipation in the substrate, we can rely on Wexler's approach [57], where thermal resistance is the sum of the diffusive and ballistic resistances [58]. It was shown numerically that the maximal error induced by this approach is 11 % [59]. The ballistic thermal resistance, is given by [57]:

$$G_{sample,bal} = \frac{k}{\Lambda} \frac{3\pi b_c^2}{4} \tag{9}$$

Since these conductances are in parallel then the total thermal conductance associated with the contact is given by:

$$\frac{1}{G_{sample}} = \frac{1}{G_{sample,spread}} + \frac{1}{G_{sample,bal}}$$
(10)

Moreover, a thermal conductance between the NbN sensor and the tip apex ($G_{tip-apex}$) acts as an additional thermal conductance to G_c and G_s since the NbN sensor is not located only close to the tip apex as depicted in Fig. 2 b. For the NbN probe used in this work, the NbN thermometer is located all along one face of the square based pyramid (3 μ m height, and 800 nm of SiN), then the thermal conductance of NbN sensor and SiN pyramid $G_{tip-apex}$ is estimated to be on the order of 10^{-4} WK⁻¹, a thermal conductance much larger than any other thermal conductance of the probe (cantilever, contact, sample etc...); we will then neglect it in the following.

Note that $G_{tip-apex}$ could also include a contribution of ballistic heat conduction at the tip apex if the characteristic size at the tip apex and the contact (b_c) are smaller than the average mean free path of energy carriers in the tip's material, specifically when the tip material is made of a crystalline semiconductor material. This is not the case for the amorphous SiN tip used in this work since the phonon mean free path for silicon nitride has been estimated to be smaller than the nanometer scale [49].

The thermal conductance from the tip to the sample defined as G_{t-s} is then the combination of three conductances in series, *i.e.* the thermal contact conductance between the tip-sample G_c , the thermal spreading conductance G_{sample} and that at the tip apex $G_{tip-apex}$ the thermal conductance between the NbN thermometer and the tip pyramid, G_{t-s} can be written as:

$$\frac{1}{G_{t-s}} = \frac{1}{G_c} + \frac{1}{G_{sample}} \tag{11}$$



FIG. 10. Comparison of the SThM thermal models between the out of contact (left) and the in-contact (right) regimes under vacuum conditions. (a) Schematic representation of the heat transfer through the probe and (b) the corresponding thermal model. (c) The sketch shows $T_{2\omega-oc}$ temperature amplitude oscillation of the SThM probe (out-of-contact). (d) Schematic of heat transfer interactions between the probe and the sample. (e) the thermal model when the tip is contacted to the sample, and (f) the measured temperature amplitude $T_{2\omega-ic}$ response from the SThM probe.

To establish the appropriate thermal modelling, we need to consider an experimental protocol with two different measurements of temperature oscillation of the probe: 1-when the probe is out-of-contact with an oscillation temperature of $T_{2\omega-oc}$ and 2-when the probe is in-contact $T_{2\omega-ic}$; the indices *ic* refer to in-contact mode.

Considering that the dissipated electrical power at the apex of the tip is identical to a first order in both cases when the probe is far from the sample or in contact, the balanced power equation between the total heat generated in the probe and the different routes of heat flux can be written as follows:

$$P_{2\omega} = G_{probe} T_{2\omega - oc} \tag{12}$$

when the tip is out-of-contact, and :

$$P_{2\omega} = (G_{probe} + G_{t-s})T_{2\omega-ic} \tag{13}$$

when the tip is in-contact with the sample.

Then, from the Eqs. 12 and 13 the thermal contact conductance G_c or the sample conductance G_{sample} can be directly expressed as a function of G_{probe} , known from out-of-contact measurement, and the two measured quantities $T_{2\omega-oc}$ and $T_{2\omega-ic}$, we then have either:

$$G_c = \frac{G_{sample}}{\left(\frac{G_{sample}}{G_{probe}} \left(\frac{T_{2\omega-ic}}{T_{2\omega-oc}-T_{2\omega-ic}}\right) - 1\right)}$$
(14)

or

$$G_{sample} = \frac{G_c}{\left(\frac{G_c}{G_{probe}} \left(\frac{T_{2\omega-ic}}{T_{2\omega-o.c} - T_{2\omega-ic}}\right) - 1\right)}$$
(15)

In this work, where the tip is brought into contact with a bulk crystalline sapphire sample, we will utilize Eq. 14 to determine the thermal contact conductance G_c , a value of which the order of magnitude is essential for further study on unknown thermal conductivity materials.

B. Thermal contact conductance at the solid-solid interface

The mechanical contact between the SThM tip and the solid surface refers to the solid-solid interface. We already discussed that the heat flux through the heated tip into the solid sample depends on the thermal conductivity of the sample *i.e.* implies an increase in the thermal conductance associated to the heat amount transferred from the heated sensor and the sample G_{t-s} with increasing sample's thermal conductivity, as proposed by Majumdar [17]. However, the existence of thermal contact conductance G_c at the solid-solid interface limits the tip-sample thermal conductance G_{t-s} . The value of G_c between the



FIG. 11. Averaged $T_{2\omega}$ amplitude oscillation of temperature measured versus frequency in out-of-contact and in-contact configurations with a sapphire sample $(\kappa_{sapphire}=34 \text{ Wm}^{-1}\text{K}^{-1})$ for an AC current of $30\mu\text{A}$ and an applied force of 5 nN. Red squares indicate the measured signal in the out-of-contact mode and red line is used to guide the eyes whereas black dots correspond to the in-contact measured temperature with blue line to guide the eyes. The inset shows the change of $T_{2\omega}$ between in-contact and out-ofcontact mode, $\Delta T_{2\omega}$, at low frequency.

SThM tip and the sample surface will be the most important parameters that sets the sensitivity in thermal conductivity measurement of the SThM probe.

The following protocol is utilized to perform the 3ω -SThM measurement of the thermal contact conductance G_c of the probe to the sample. We carried out experiments on various locations on the sample surface with a constant applied force of few nanonewtons. Then the $V_{3\omega}$ signal is measured as a function of frequency in outof-contact mode first that will serve as a reference and second in-contact mode. An average of the signal for each location is taken over twenty cycles of out-of-contact and in-contact experiments. Finally, the averaged $T_{2\omega}$ temperature is used to extract the value of the contact resistance using Eq. 14, where all the other parameters are known such as G_{sample} and G_{probe} .

We performed that SThM measurement of G_c on a well-known crystalline sapphire samples. Figure 11 allows the comparison of the $T_{2\omega}$ temperature oscillation of the SThM probe (extracted from $V_{3\omega}$ signal) in-contact and out-of-contact with the sapphire sample as a function of frequency. The red squares are the measured temperature oscillations of the probe in out-of-contact configuration corresponding to temperature $T_{2\omega-oc}$ and black dots represent the measured temperature in-contact with the sample and correspond to $T_{2\omega-ic}$. In the inset of Figure 11 $\Delta T_{2\omega} = T_{2\omega-oc} - T_{2\omega-ic}$ is plotted showing a difference of 134 mK (at frequencies smaller than 10 Hz for an applied force of 5 nN) in the temperature oscillation



FIG. 12. Averaged $T_{2\omega}$ amplitude oscillation of temperature measured versus frequency in out-of-contact and in-contact configurations with a sapphire sample $(\kappa_{sapphire}=34 \text{ Wm}^{-1}\text{K}^{-1}, \text{ AC current of } 30\mu\text{A})$ for different forces exerted on the cantilever. Red dots indicate the measured signal in the out-of-contact mode and color lines are used for the various applied forces from 5 nN to 50 nN.

between out-of-contact and in-contact configurations.

The same experiment has been done for different exerted forces, as it is shown Figure 12. The inset of Figure 12 is clearly illustrating that this technique is sensitive enough to detect a change of $T_{2\omega}$ with an increased force. The thermal coupling is improved and consequently the change in the temperature oscillation $T_{2\omega}$ increases from 134 mK for 5 nN to 164 mK for 50nN. We can also notice that at high frequencies (f > 40 Hz), the amplitude of the $T_{2\omega}$ temperature oscillations are similar for all configurations. That is because the penetration depth of the heat flux is minimal at high frequency and meaning that the sample in contact is not probed anymore. Since at high frequency only the probe is measured, then the superposition of the $T_{2\omega}$ curves for frequencies greater than 40 Hz is a good indication of the quality of the measurement.

The thermal conductivity of the sapphire sample used in this work has been previously measured by regular 3ω method and found to be of $34 \text{ Wm}^{-1}\text{K}^{-1}$ on the very same material [60, 61], knowing that the average mean free path of phonons in sapphire is about 130 nm [62], it gives $G_{sample,spread} = 1.7 \times 10^{-5} \text{ WK}^{-1}$ and $G_{sample,bal} = 9.6 \times 10^{-6} \text{ WK}^{-1}$. From the equivalent radius of the tip apex measured by SEM to be 125 nm using the Eq. 14 we can estimate the G_{sample} to be $6.15 \times 10^{-6} \text{ WK}^{-1}$. Using the experimental results obtained in this work for out-of-contact and in-contact $T_{2\omega}$ along with Eq. 14, we can estimate the thermal conductance of the probe-sapphire contact to be $7.4 \times 10^{-8} \text{ WK}^{-1}$, which can be translated into thermal boundary resistance per surface of 8.0×10^{-7} Km²W⁻¹. Identical measurements were performed on silicon smooth surface of thermal conductivity of 148 Wm⁻¹K⁻¹ and a thermal conductance of the contact of 8.9×10^{-8} WK⁻¹ has been measured, a value relatively closed to the one measured on sapphire.

These measurements of thermal boundary resistance can be compared to Pd probes (SiN probe) in vacuum ($P < 10^{-3}$ mbar) having a curvature radius close to the NbN probe where a G_c on the order of 1.4 to 16×10^{-8} WK⁻¹ has been measured in the past, a value very close to 7.4×10^{-8} WK⁻¹ measured in this work [31, 63–65].

C. Sensitivity function

In order to characterize the performance of the NbN probe regarding the measurement of thermal conductivity κ of materials or thermal contact conductance, it is appropriate to calculate the dimensionless sensitivity functions defined as:

$$S(G_{sample}) = \frac{G_{sample}}{T_{2\omega-ic}} \frac{d\Delta T_{2\omega}}{dG_{sample}}$$
(16)

Using Eq. 14, we obtain :

$$\Delta T_{2\omega} = \frac{T_{2\omega-ic}G_{sample}G_c}{G_p(G_{sample} + G_c)} \tag{17}$$

Replacing G_{sample} by the simple spreading thermal conductance given by Eq. 8 for a fixed thermal contact conductance G_c , we get for the sensitivity function expressed as a function of κ :

$$S(\kappa) = \frac{4b_c G_c^2 \kappa}{G_p (G_c + 4b_c \kappa)^2} \tag{18}$$

Similarly, we can calculate the sensitivity function as a function of the contact conductance per surface $g_c = G_c/4b_c^2$, for a fixed thermal conductivity of sample κ :

$$S(g_c) = \frac{4b_c^2 \kappa^2 g_c}{G_p (\kappa + b_c g_c)^2}$$
(19)

In Fig. 13 both sensitivity functions are shown. In Fig. 13(a) $S(\kappa)$ is plotted as a function of the thermal conductivity κ of the sample that will be probed during an SThM experiment (for a fixed thermal contact conductance G_c as measured in this work on sapphire); the dashed lines indicate the performance of the probe for different targeted percentages of sensitivity of the thermal conductivity $\Delta \kappa / \kappa$ calculated from the signal to noise ratio $V_{3\omega}^{rms}/noise$ as obtained from Fig. 7. In Fig. 13(b) $S(g_c)$ is plotted as a function of the thermal conductivity of sample 1, 10 and 100 Wm⁻¹K⁻¹.

This shows that the probe characterized in this work has its optimum sensitivity for sample of thermal conductivity of $0.15 \text{ Wm}^{-1}\text{K}^{-1}$. However, if the experimental resolution targeted for the thermal conductance



FIG. 13. (a) Sensitivity function as calculated from the probe parameters of this work as a function of the thermal conductivity of sample under study. The dashed lines illustrate the performance of the probe for different targeted percentages of sensitivity of the thermal conductivity $\Delta \kappa / \kappa$ calculated from the signal to noise ratio $V_{3\omega}^{rms}/noise$. (b) Sensitivity function as a function of the thermal conductivity of sample : 1, 10 and 100 Wm⁻¹K⁻¹.

measurement defined as $\Delta \kappa / \kappa$ is above 1% then a wide thermal conductivity range is accessible from 0.002 to 13 Wm⁻¹K⁻¹ as it is shown in Fig. 13(a). Finally, if a lower tolerance is acceptable (above 10%), measurement up to 100 Wm⁻¹K⁻¹ is possible, demonstrating the very wide thermal conductivity range of few orders of magnitude that is accessible with the NbN thermal probe. Similarly, Fig. 13(b) illustrates the potential performance of the NbN probe is studying thermal contact conductance, with a particular sensitivity when measuring thermal contact on highly conductive samples (100 Wm⁻¹K⁻¹) like silicon for instance.

V. CONCLUSION

In summary, we have presented the experimental setup necessary to perform scanning thermal microscopy measurement using NbN thermal probes. The experimental environment including the AFM instrument, the probe holder, and the measurement chain has been described in details. The fabrication and the calibration of the SThM probe equipped with a highly sensitive NbN thermometer have been done in the AFM instrument. The present work demonstrates the potential of this experimental set-up coupled to highly sensitive NbN thermal probes for thermal transport measurement at the nanoscale. Thermal experiments based on the 3ω technique show the operability of these probes. We underline that we performed the experiments by inducing a temperature variation of only ~ 5 K between the probe and the sample in 3ω -SThM mode, which is significantly lower than the temperature variation used in most DC or AC heating active modes. Generally, a temperature gradient of more than few tens of Kelvin between the probe and sample is used for SThM measurements [26, 30, 31, 39, 66].

The main advantages of that new SThM probe rely on the use of smaller temperature gradients allowing better temperature resolution and greater stability of the probe over time by avoiding changes in its electrical properties due to temperature-dependent phenomena such as thermometer annealing. Using small temperature gradients will be particularly important when measuring samples having physical (mainly mechanical and thermal) properties that depend strongly on temperature. However, measurements in active DC mode with the NbN tip heated to several tens of Kelvin are still possible, which is particularly useful for studying the thermomechanical behavior of polymer materials for example. The NbN thermometers are more sensitive than those used in comparable thermal probes. However, the NbN thermometers are a little less sensitive on the AFM probe pyramid than the state-of-art of NbN thermometer on regular flat surface obtained in our group showing a significant margin of

progress for these probes in the near future. Additionally, unlike most SThM resistive probes, which are measured via two terminals, the response of the NbN thermometer on the AFM tip is measured using four-terminal wires. This allows better control of the response of the NbN sensor alone, since the electrical resistance of the connecting wires is not involved in the measurement. Moreover, the flat end of the tip is not coated with NbN, which limits mechanical wear on the thermal sensor and therefore ensures better measurement reproducibility.

The demonstration of such an instrument opens up numerous possibilities for high resolution thermal measurements at very small length scale, from the local temperature or thermal conductivity of composites and nanomaterials to the thermal conductance of nanometric-sized contacts.

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Data Availability Data are available upon request to the corresponding author.

Supplementary Materials The supplementary materials bring more data on the thermal conductance of the probe-sapphire contact, comparison with the thermal contact resistances found in literature and measured values in this work and finally the calculation from the measurement of the thermal resistance of the mechanical contact R_c as a function of the force applied.

Competing interests The authors declare no competing interests.

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