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# On the modeling of elasto-acoustic network of pipes composed of straight waveguides and curved joints

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Left

Interface:

(*k*)





Right

(k + 1)

Periodic systems → N identical substructures (length d)
FE model of a substructure → wave mode basis

**1.** Transfer matrix:

 $\begin{bmatrix} \mathbf{q}_{\mathrm{L}}^{(k+1)} \\ -\mathbf{F}_{\mathrm{L}}^{(k+1)} \end{bmatrix} = \mathbf{S} \begin{bmatrix} \mathbf{q}_{\mathrm{L}}^{(k)} \\ -\mathbf{F}_{\mathrm{L}}^{(k)} \end{bmatrix}$ 

Wave Finite Element (WFE) method

q : displacement (solid) and velocity potential (acoustic)F : elastic and acoustic forces

- 2.  $\mathbf{S} + \mathbf{S}^{-1}$  transformation  $\rightarrow 2n$  eigenvalues  $\mu_j$  and eigenvectors  $\phi_j$  of  $\mathbf{S}$ :
  - n right-going wave modes ( $\mu$ ,  $\Phi$ ) and n left-going wave modes ( $\mu^*$ ,  $\Phi^*$ )
  - Wavenumber  $\beta_j : \mu_j = \exp(-i\beta_j d)$
  - Waveshapes :  $\mathbf{\Phi} = \begin{bmatrix} \mathbf{\Phi}_q \\ \mathbf{\Phi}_F \end{bmatrix}$  and  $\mathbf{\Phi}^* = \begin{bmatrix} \mathbf{\Phi}_q^* \\ \mathbf{\Phi}_F^* \end{bmatrix}$
- 3. Wave mode expansion for a substructure boundary (k)

 $\mathbf{q}_{\mathrm{L}}^{(k)} = \mathbf{q}_{\mathrm{R}}^{(k)} = \mathbf{\Phi}_{\mathrm{q}} \boldsymbol{\mu}^{k-1} \mathbf{Q} + \mathbf{\Phi}_{\mathrm{q}}^{\star} \boldsymbol{\mu}^{N+k-1} \mathbf{Q}^{\star}$  $-\mathbf{F}_{\mathrm{L}}^{(k)} = \mathbf{F}_{\mathrm{R}}^{(k)} = \mathbf{\Phi}_{\mathrm{F}} \boldsymbol{\mu}^{k-1} \mathbf{Q} + \mathbf{\Phi}_{\mathrm{F}}^{\star} \boldsymbol{\mu}^{N+k-1} \mathbf{Q}^{\star}$ 



- Elastic domain: steel
- Acoustic domain: water
- Rayleigh damping
- Geometrical parameters:
  - Pipe radius: 0.05 m
  - Pipe thickness: 0.005 m
- Substructure length:  $d = 2 \times 10^{-3}$  m
- Joint radius:  $R_i = 0.20 m$





Numerical results

 $\mathbf{Q}, \mathbf{Q}^*$ : wave amplitude vectors at the left and right ends of the pipe

Joint modeling: Craig-Bampton (CB) method with basis enrichment

• Large-sized FE model → Reduction is needed !

 $\mathbb{D}^{j} = -\omega^{2}\mathbb{M}^{j} + i\omega\mathbb{G}^{j} + \mathbb{K}^{j}$ 

 $\mathbb{D}^{j}$ : dynamic stiffness matrix

Transformation matrices:

Elastic part:

Acoustic part:

 $\begin{bmatrix} \mathbf{X}_{st}^{A} \\ \mathbf{I} \end{bmatrix}$ 

 $\boldsymbol{\Gamma}_{\mathrm{CB}}^{\mathrm{E}} = \begin{bmatrix} \widetilde{\mathbf{X}}_{\mathrm{el}}^{\mathrm{E}} & \widetilde{\mathbf{\mathcal{U}}}^{\mathrm{E}} & \mathbf{X}_{\mathrm{st}}^{\mathrm{E}} \\ \mathbf{0} & \mathbf{0} & \mathbf{I} \end{bmatrix}$ 

$$\Gamma_{\rm CB}^{\rm A} = \begin{bmatrix} \widetilde{\mathbf{X}}_{\rm el}^{\rm A} & \widetilde{\mathbf{U}}^{\rm A} \\ \mathbf{0} & \mathbf{0} \end{bmatrix}$$

 $\mathbf{T}_{\mathrm{CB}} = \begin{bmatrix} \mathbf{\Gamma}_{\mathrm{CB}}^{\mathrm{E}} & \mathbf{0} \\ \mathbf{0} & \mathbf{\Gamma}_{\mathrm{CB}}^{\mathrm{A}} \end{bmatrix}$ 

 $\mathbf{X}_{st}^{E,A}$  : matrix of static modes  $\widetilde{\mathbf{X}}_{el}^{E,A}$  : matrix of fixed-interface modes  $\widetilde{\mathbf{\mathcal{U}}}^{E,A}$ : enrichment vectors

$$\Rightarrow \widetilde{\mathbb{D}^{j}} = (\mathbf{T}_{CB})^{T} \mathbb{D}^{j} \mathbf{T}_{CB} \text{ where } \operatorname{size}(\widetilde{\mathbb{D}^{j}}) \ll \operatorname{size}(\mathbb{D}^{j})$$

Figure : (a) Dispersion curves (real and imaginary parts of  $\beta_j d$  are plotted in continuous and dashed lines, respectively) and (b) group velocities of modes



Figure : Power scattering coefficients for the joint: (a) transmission and (b) reflection  $T(0,1) \rightarrow T(0,1)$ . Fluid-filled pipe in blue lines, and empty pipe in black lines.

### **Reduction strategy**

Table : Elapsed times to compute the solutions using the FE method, the full WFE, and the WFE method with CB reduction for the joint

# Scattering matrix

• Scattering matrix of the joint ( $\mathbb{C}^{j}$ ) (depends on  $\mathbb{D}^{j}$  and wave modes):

 $\begin{bmatrix} \mathbf{Q}_1^{\star} \\ \mathbf{Q}_2 \end{bmatrix} = \begin{bmatrix} \mathbb{C}_{11}^{j} & \mathbb{C}_{12}^{j} \\ \mathbb{C}_{21}^{j} & \mathbb{C}_{22}^{j} \end{bmatrix} \begin{bmatrix} \boldsymbol{\mu}^{N_1} \mathbf{Q}_1 \\ \boldsymbol{\mu}^{N_2} \mathbf{Q}_2^{\star} \end{bmatrix}$ 

- $N_1$ : number of substructures in waveguide 1
- $N_2$ : number of substructures in waveguide 2
- $\mathbb{C}_{11}^{J}$ : transmission coefficients between waveguides 1 and 2

#### **References:**

[1] J.-M. Mencik and M. N. Ichchou. Wave finite elements in guided elastodynamics with internal fluid. International Journal of Solids and Structures, 44(7):2148–2167, April 2007.

[2] Q. H. Tran, M. Ouisse, and N. Bouhaddi. A robust component mode synthesis method for stochastic damped vibroacoustics. Mechanical Systems and Signal Processing, 24(1):164–181, January 2010.

Method	Time (s)	Reduction (%)
FE	8711	
WFE	6904	20.75
WFE + reduction	2704	68.95

Computation of wave modes (WFE) only takes 265s

## Conclusions

- Elasto-acoustic responses of networks of pipes can be quickly computed using the WFE method and the CB reduction with basis enrichment.
- Fluid loading effect affects the scattering of the torsional mode at a curved joint.