Parking duration optimization for electric vehicles in a loss queueing system PGMO days 2022

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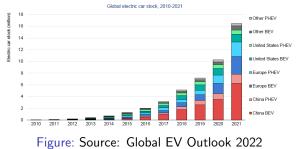
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Motivation

- Huge and quick development of electric mobility
- Increasing demand of parking spaces equipped with a charging point in the Charging Stations (CS)



- **Objectives**: Improving the Quality of Charging Service at public Charging Stations
- **Approach**: Mathematical modeling of Electric Vehicles (EV) arrivals/departures at a given site composed with one CS based on <u>queueing theory</u> [A.Aveklouris et al. (2019)]

- 2 Optimal average parking duration
- 3 Numerical simulation

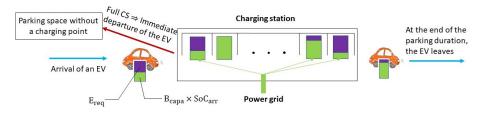


2 Optimal average parking duration

3 Numerical simulation



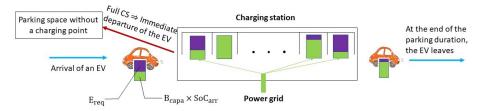
Stochastic model of EV arrivals/departures at a CS



Characteristics of Electric Vehicles

- Random arriving times: Poisson process of parameter λ
- Random need in energy $E_{\rm req}$ at arrival (exponential distribution with parameter $\mu)$
 - $\bullet\ B_{\rm capa}$: energy storage capacity
 - ${\rm SoC}_{\rm arr}:$ % of ${\rm B}_{\rm capa}$ at arrival
 - $E_{req} := B_{capa} \times (1 SoC_{arr})$
- Random parking duration T_{park} (\perp E_{req}) (exponential distribution with parameter ν)

Charging Station characteristics

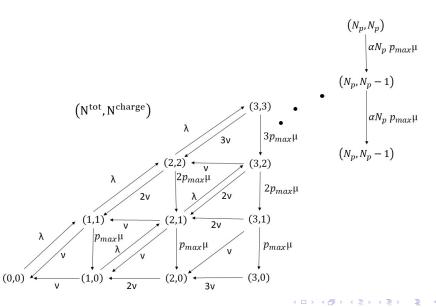


- N_p : nb of parking spots (all equipped with one Charging Point (CP))
- p_{max}: maximum power delivered for an EV
- α : proportion of the nb of CP that can deliver p_{max} simultaneously

Power scheduling: *smoothing*

• Each arriving EVs immediately starts to charge with power:

$$p(nb_EV_charging) = p_{max} \times \frac{min(\alpha N_p, nb_EV_charging)}{nb_EV_charging}$$



Energy received per EV

Notation

- E: random energy received
- A: event "the arriving EV is accepted"
- N_t^{charge} : number of charging EV at time t
- Energy received for a given EV:

$$egin{aligned} \mathrm{E} &= \mathbf{1}_\mathrm{A} imes \mathrm{E} + \mathbf{1}_{ar{\mathrm{A}}} imes \mathbf{0} \ &= \mathbf{1}_\mathrm{A} imes \int_{\mathrm{t_{start}}}^{\mathrm{t_{end}}} \mathrm{p}(\mathrm{N}_\mathrm{t}^{\mathrm{charge}}) \mathrm{dt} \end{aligned}$$

with

- $t_{end} = t_{start} + T_{charge} = t_{start} + min(T_{park}, T_{full})$
- $T_{\rm full}$ the solution in t to $\int_{t_{\rm start}}^t p(N_t^{\rm charge})\, dt = E_{\rm req}$
- Difficult to obtain the exact expected energy received

2 Optimal average parking duration

3 Numerical simulation

4 Conclusion

Motivation

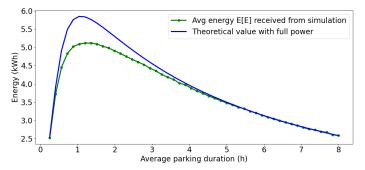
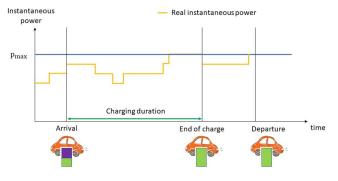


Figure: Expected energy received with respect to the average parking duration

- Model simulated using Simpy (discrete event simulation framework);
- Low avg parking duration \Rightarrow Little time for receiving energy;
- High avg parking duration ⇒ High blocking probability;
- Can we find the optimal avg parking duration ?

Approximation of the expected energy received per EV



 $\boldsymbol{E}[E] \approx \boldsymbol{P}(A) \times \boldsymbol{E}[T_{charging}] \times p_{max}$

- \tilde{E}_{num} : approximated expected energy received per EV with the exact P(A) at steady states (*Erlang B formula*)
- \tilde{E}_{ana} : approximated expected energy received per EV with an approximation on P(A)

Problem formulation

Notation

- $\bar{\mathbf{e}}_{req}$: avg need in energy
- λ : avg frequency of arrival
- \overline{t}_{park} : avg parking duration

$$(P_1) \quad \min_{\bar{\mathrm{t}}_{\mathrm{park}}>0} \tilde{\mathrm{E}}_{\mathrm{num}} = (1 - \frac{\frac{\lambda^{1\mathrm{p}}(\bar{\mathrm{t}}_{\mathrm{park}})^{1/\mathrm{p}}}{N_{\mathrm{p}}!}}{\sum_{j=0}^{N_{\mathrm{p}}} \frac{\lambda^{j}}{j!}(\bar{\mathrm{t}}_{\mathrm{park}})^{j}}) \times \frac{\mathrm{p}_{\mathsf{max}} \bar{\mathrm{e}}_{\mathrm{req}} \bar{\mathrm{t}}_{\mathrm{park}}}{\bar{\mathrm{e}}_{\mathrm{req}} + \mathrm{p}_{\mathsf{max}} \bar{\mathrm{t}}_{\mathrm{park}}}$$

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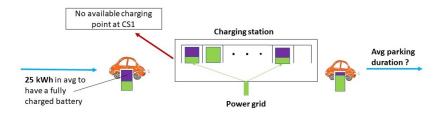
Prop.: unique solution $\bar{\rm t}_{\rm park}^{\rm opt,num}$ to (P1), but no close-form expression

$$\begin{array}{l} (P_2) \quad \min_{\bar{t}_{\mathrm{park}}>0} \tilde{\mathrm{E}}_{\mathrm{ana}} = \min(1, \frac{\mathrm{N}_{\mathrm{p}}}{\lambda \, \bar{t}_{\mathrm{park}}}) \times \frac{p_{\mathsf{max}} \, \bar{\mathrm{e}}_{\mathrm{req}} \, \bar{t}_{\mathrm{park}}}{\bar{\mathrm{e}}_{\mathrm{req}} + p_{\mathsf{max}} \, \bar{t}_{\mathrm{park}}} \\ \textbf{Prop.:} \ \bar{t}_{\mathrm{park}}^{\mathrm{opt,ana}} = \frac{\mathrm{N}_{\mathrm{p}}}{\lambda} \ \text{is the } \underline{\text{unique solution to }} (P_2) \end{array}$$

2 Optimal average parking duration

3 Numerical simulation

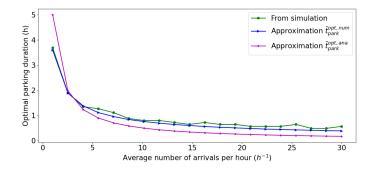
4 Conclusion



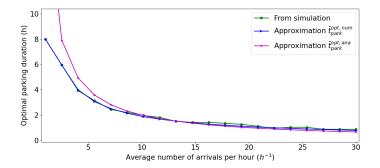
Charging station characteristics

- Power sizing coefficient $\alpha = 0.6$
- \bullet Maximum power per charging point $p_{\text{max}}=11~\text{kW}$

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- 5 parking spaces
 - Decreasing optimal parking duration wrt λ
 - \bullet For $\bar{\rm t}_{\rm park}^{\rm opt,num}:$ more accurate (Error \approx 5%)
 - \bullet For $\bar{t}_{park}^{opt,ana}:$ less accurate (Error \approx 50%)



20 parking spaces: more accurate approximations

• For $\bar{t}_{park}^{opt,num}$: error $\in [0\%, 10\%]$ • For $\bar{t}_{park}^{opt,ana}$: error $\in [0\%, 25\%]$

2 Optimal average parking duration

3 Numerical simulation



Main ideas

- Analysis of the parking duration effect on the expected energy received per EV
- Optimal average parking duration: trade-off between
 - enough time to charge
 - not overuse a parking space

Perspectives

- Find a pricing mechanism to reduce parking duration when needed
- Deepen the analysis of the exact energy received per EV
- Introduce several types of charging modes (with \neq power capacities)

Thank you for your attention

Dupont, Hayel, Jiménez, Wan, Beaude

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- A.Aveklouris, M.Vlasiou & B.Zwart (2019), 'Bounds and limit theorems for a layered queueing model in electric vehicle charging', *Queueing Systems* **93**, 83–137.
- Feldman, R. M. & Valdez-Flores, C. (2010), Applied Probability and Stochastic Processes, Springer.

Model: Number of charging EVs

 $2 \mbox{ forms of congestion : on the power and on the limited number of parking spaces }$

Notation

 $\bar{z} = Average$ number of charging EVs in stationary regime.

Fixed point equation for \bar{z} given by [A.Aveklouris et al. (2019)]

$$\bar{z} = \min(\lambda, \nu N_p) \mathbb{E}\left[\min\left(D, \frac{B}{p_{\max}}\max(1, \frac{\bar{z}}{\alpha N_p})\right)\right].$$
(1)

Proposition [Avg nb of charging EVs]:

In stationary regime, the average number of charging EVs is:

$$\bar{z} = \begin{cases} \frac{\min(\lambda,\nu N_p)}{\nu + p_{\max}\mu} & \text{if } \frac{\nu}{\nu + p_{\max}\mu} \le \alpha \text{ or } \frac{\lambda}{\nu + p_{\max}\mu} \le \alpha N_p, \\ \frac{\min(\lambda,\nu N_p) - p_{\max}\mu\alpha N_p}{\nu} & \text{else.} \end{cases}$$
(2)

Idea of the proof : Resolution of the fixed point equation 1. Dupont, Hayel, Jiménez, Wan, Beaude PGMO days Novemb

Model: Number of charging EVs

Markov process Z_t

- Z_t if a Markov process [Feldman & Valdez-Flores (2010)].
- Arrivals of Z_t : Poisson process of parameter λ .
- Departure process: Poisson process of parameter $\nu \times Z_t + \mu \times \min(Z_t, \alpha N_p)$.

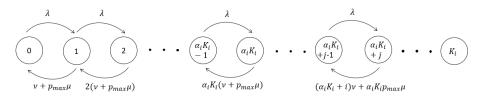


Figure: Transition rates of the Markov process Z_t