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Article

Usable Analytical Expressions for Temperature Distribution Induced by Ultrafast Laser Pulses in Dielectric Solids

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Abstract: This paper focuses on the critical role of temperature in ultrafast direct laser writing processes, where temperature changes can trigger or exclusively drive certain transformations, such as phase transitions. It is important to consider both the temporal dynamics and spatial temperature distribution for the effective control of material modifications. We present analytical expressions for temperature variations induced by multi-pulse absorption, applicable to pulse durations significantly shorter than nanoseconds within a spherical energy source. The objective is to provide easy-to-use expressions to facilitate engineering tasks. Specifically, the expressions are shown to depend on just two parameters: the initial temperature at the center denoted as T_{00} and a factor R_τ representing the ratio of the pulse period τ_p to the diffusion time τ_d . We show that temperature, oscillating between T_{max} and T_{min} , reaches a steady state and we calculate the least number of pulses required to reach the steady state. The paper defines the occurrence of heat accumulation precisely and elucidates that a temperature increase does not accompany systematically heat accumulation but depends on a set of laser parameters. It also highlights the temporal differences in temperature at the focus compared to areas outside the focus. Furthermore, the study suggests circumstances under which averaging the temperature over the pulse period can provide an even simpler approach. This work is instrumental in comprehending the diverse temperature effects observed in various experiments and in preparing for experimental setup. It also aids in determining whether temperature plays a role in the processes of direct laser writing. Toward the end of the paper, several application examples are provided.

Keywords: temperature distribution; femtosecond pulsed laser; interaction laser–dielectric solid

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1. Introduction

In the context of an ultrafast laser interacting with solids, temperature plays a special role in the transformation processes. Some of the processes can be thermally activated, others can be temperature driven, such as phase transition but not thermally activated. The objective of this paper is to develop an analytic approximation to predict the behavior of the spatial temperature distribution and the temperature evolution over time according to the key laser parameter combinations and then to deduce their importance. This approach seeks to provide physical insight and semi-quantitative results without relying on heavy and overly detailed finite element calculations. This methodology resonates with the philosophy espoused by Paul Dirac in 1929, as documented in the Proceedings of the Royal Society of London [1]:

“The underlying physical laws necessary for the mathematical theory of a large part of physics and the whole of chemistry are thus completely known, and the difficulty is only that the exact application of these laws leads to equations much too complicated to be soluble. It therefore becomes desirable that approximate practical methods of applying

quantum mechanics should be developed, which can lead to an explanation of the main features of complex atomic systems without too much computation”.

In the ultrafast laser–matter interaction process, the energy from the laser pulse that has an extremely short pulse duration (10^{-11} – 10^{-14} s) is partially injected into a small focal volume of transparent dielectric solids. This intense laser pulse with high irradiance ($>10^{13}$ Wcm⁻²) in the focal region stimulates a series of complex dynamic processes, such as multiphoton ionization, tunneling ionization, inverse bremsstrahlung absorption, and avalanche ionization within an ultrashort time scale [2]. Such interactions lead to high-density electron excitations in condensed matter, creating plasma with high temperatures and pressures. This plasma expands rapidly in the focal zone, resulting in structural modifications as energy relaxes through phonon–electron interactions [3,4].

In the low repetition rate regime, thermal accumulation is usually negligible in the processing. The temperature decreases to the initial degree before the next pulse arrives. The non-linear nature of the optical absorption can confine the formed modifications to the focal volume. These advantages minimize the thermal collateral damage and heat-affected zone [5]. Thus, ultrafast laser direct writing (ULDW) is suggested as a general technique to induce highly localized modifications and optical structures within/near the focus in a wide range of transparent solids [6–11]. In this regime, denoted as non-thermal ULDW, the repetition rate (RR) is usually a few kilohertz, and the fabrication efficiency is also limited by the low pulse RR.

In contrast, when the pulse repetition rate of the ultrafast laser increases, the interval between successive laser pulses is less than the time needed for the absorbed energy to diffuse out of the focal volume and this induces an obvious localized heat accumulation effect [11–18]. In this case, for a given pulse energy, the temperature increases continuously in the focal zone before stabilizing. The final diffusion of the heat into the surrounding material may lead to a material melting beyond the focal volume over a longer time scale. In this regime, denoted as thermal ULDW, the melted modified region is much larger than the focus size. Paralleling to the wide applications of non-thermal ULDW, the localized thermal accumulation has been demonstrated to be important in the ULDW for inducing various phenomena and structures in the transparent solids and improving the performance of the fabricated devices. For example, the thermal accumulation can lead to a higher symmetry of the waveguide cross-section, reducing the propagation loss and enhancing the fabrication efficiency [12,15,16]. Thermal accumulation in the ULDW can also induce unique phenomena, such as elemental redistribution and local crystallization, which are nearly not achievable in the non-thermal ULDW [11,19–23]. In the thermal ULDW regime, the temperature distribution can work as a driving force to redistribute the elements or reorganize the structures in the thermal melted region. The thermal accumulation effect has also been reported to be critical for the formation of periodic nanogratings in some glass systems [24]. Moreover, the thermal accumulation induces a high temperature that can produce thermally excited free electrons, which seeds the avalanche ionization and significantly enhance absorptivity [25]. As a result, more energy can be absorbed, and this further increases thermal accumulation. Until now, thermal accumulation has been established to be an important assistant in many cases to help ULDW to achieve various applications in fundamental science and technological manufacturing [14–16,21,25,26]. Clarifying the principle of thermal ULDW and reviewing its current stage in the applications are highly urgent and significant for guiding future work [11,15,16].

For this aspect of the work, Lax et al. in 1977 [27] published the first paper that described the 3D spatial distribution of the temperature rise induced by the Beer–Lambert absorption of a static Gaussian CW laser beam in cylindrical geometry. Then, Sanders in 1984 [28] described an extension of these calculations for scanning beams and provided analytic expressions. In 1991, Haba et al. [29] described the calculation of a 3D spatial distribution for the Beer–Lambert absorption of a scanning Gaussian pulsed laser in cylindrical geometry. However, even if the expression was quite complete but numerically

solvable, there was no extended discussion on the laser/material parameters. Then, Eaton et al. [15] in 2005 and Zhang et al. [30] in 2007 performed finite difference calculations, for simple pulsed and CW Gaussian beams in spherical geometry, preventing easy material analysis. In 2007, Sakakura et al. [18] solved the Fourier equation in the frame of cylindrical geometry for energy delivered by a Gaussian pulsed fs laser (pulse duration 220 fs, RR 3 Hz, pulse energy $< 1 \mu\text{J}$). With such a weak RR, the calculation can be restricted to one pulse as the experimental measurement (a lens effect) was smaller than 1 ms. However, it is not a special case and for material treatment, a large number of pulses are required. That is why Miyamoto et al. [31] in the same year, deduced analytical expressions for scanning uniform pulsed laser energy deposition in a parallelepiped volume of width $2w$ corresponding to the scanning CW beam diameter at $1/e$ and length corresponding to the absorption length ($1/\alpha$). These calculations were used also by Beresna et al. [32] and applied to a particular case, i.e., borosilicate. In 2011, Miyamoto et al. [25] considered a cylindrical source with its full width dependent on z in order to account for the convergence of the beam or the non-linear properties including the self-focusing. In 2012, Shimizu et al. [33] used a static cylindrical Gaussian beam and Gaussian energy deposition in depth for multi-pulsed laser energy deposition but solved the problem numerically. Lastly, in 2019 and 2020, Rahaman et al. [34,35] proposed an analytical solution using Duhamel's theorem and Hankel's transform method, for a transient, two-dimensional thermal model. We summarized the above research in Table 1 below, to compare with our work.

Table 1. State of the art of the thermal simulation of laser–matter interactions.

Laser Type	Mode	Geometry	Source Shape	Solving Method	Refs.
CW	static	cylindrical	Gaussian(r) Beer–Lambert(z)	analytical	Lax [27]
pulsed	scanning	three axes	Gaussian(x,y) Beer–Lambert(z)	analytical	Sanders [28]
pulsed	scanning	three axes	Gaussian(x,y) Beer–Lambert(z)	analytical	Haba [29]
pulsed	static	spherical	Gaussian(r)	finite difference	Eaton [15] or Zhang [30]
pulsed	quasi-static	cylindrical	Gaussian(r) Beer–Lambert(z)	analytical one pulse	Sakakura[18]
CW	scanning	three axes	uniform deposition in parallelepiped volume	analytical	Miyamoto [31]
pulsed	static	cylindrical	Gaussian(r,z)	analytical	Miyamoto[25]
pulsed	static	cylindrical	Gaussian(r) Gaussian(z)	numerical	Shimizu [33]
pulsed	scanning	cylindrical	Gaussian(r) surface absorption	analytical	Rahaman [34,35]
pulsed	quasi-static	spherical	Gaussian(r)	analytical	this work

In short, the drawback in the available literature is that the authors did not provide simple expressions that allow the reader to easily understand how each parameter of lasers and materials influences the evolution of the temperature distribution, and to control the thermal effect in transparent materials with non-linear optical absorption for which the effect is mainly in volume for a focused beam. However, beyond this step that corresponds to the absorption of a small part of the pulse energy, the absorption becomes linear [36]. This is the reason why we present the analytical approach or link the properties of the materials to the shape of the temperature distribution and use it for explaining the phenomena such as:

- The appearance of several regions in the heat-affected volume including change of the structure of a glass, crystallization, phase separation, thermal erasure while writing providing that energy endo or exo is negligible in front of the laser one;
- The variations in the shape of the interaction volume according to the laser parameters like a change of laser track width, change of laser track morphology.

For this purpose, we restricted ourselves assuming that the physical properties of the material are independent of the temperature, but this does not prevent the possibility of physical deductions. We used the simplest solution of the Fourier equation in spherical geometry, i.e., a Gaussian shape along the perpendicular and longitudinal direction of the beam propagation direction. This applies not only to the sample surface but also to multiphoton absorption by stating the coordinate origin at the geometrical or effective focus. Since the typical application of this model is the thermal accumulation of a high focused beam in a material with non-linear absorption. Namely, the cylindrical symmetry and the Beer–Lambert law along z cannot be considered. We have also considered that the pulse duration (smaller than a few ns) is much smaller than the diffusion time so that the initial temperature distribution is defined by the shape of the absorbed energy source. This is applicable in most cases to femtosecond and nanosecond lasers as the diffusion time is usually of the order of a fraction of μs in inorganic glasses and a few μs in organic materials. In addition, material phase change and non-linear optical effects are not considered in this model except for the presence of coefficient A (see below).

This study was motivated by seeing nowadays that, as the means of simulation are easily accessible, the physical sense is hidden or even lost, which prevents the correct management of the laser parameters according to targeted property modifications.

2. Starting Formulation

From a theoretical point of view, the heat deposited at a point by the laser diffuses into the material by following Fourier's law $\vec{q} = -\vec{\kappa}\vec{\nabla}T$ where \vec{q} is the heat flow (energy per unit area and time). Fourier considers it to be linearly dependent on the temperature gradient. κ is the thermal conductivity, in general, a tensor of order 2 which relates the gradient vector of T to the flux. Its dimension is energy ($\text{J}/\text{m}^2\cdot\text{s}\cdot\text{K}$). For isotropic materials, such as glasses, one will suppose that this tensor is reduced to a scalar. To calculate (in principle) the evolution and distribution of T , we start with the law of the conservation of energy, $\frac{d\rho Q}{dt} + \vec{\nabla} \cdot \vec{q} = \text{source terms} - \text{sink terms}$. The source term is the laser energy density deposited per unit of time (i.e., absorbed laser power), written symbolically as $\frac{\delta\rho Q}{\delta t}$. Its spatial shape defines the symmetry of the problem. For the sake of simplicity for demonstrating physical conclusions, we have assumed spherical symmetry. This means that we do not take into account some changes of focal volume with incident pulse energy due to Kerr self-focusing and electron plasma defocusing. We assume that there were no heat annihilation terms (for example, endothermic chemical transformation), sink terms = 0. Using the definition of specific heat, $\frac{d\rho Q}{dt} = \rho \cdot C_p \cdot \frac{dT}{dt}$, ρ and C_p are the density and specific heat capacity, respectively. $\vec{\nabla} \cdot \vec{q} = \vec{\nabla} \cdot (-\vec{\kappa}\vec{\nabla}T) = -D_{th} \cdot \Delta T$, with diffusivity $D_{th} = \frac{\kappa}{\rho \cdot C_p}$, Δ is the Laplace operator written in spherical symmetry, $\Delta = \nabla^2 = \frac{\partial^2}{\partial r^2} + \frac{2\partial}{r\partial r}$. Considering a beam moving not too fast, convection can be neglected (i.e., the time derivative of the spatial coordinate), $\frac{dT}{dt}$ is thus written as $\frac{\partial T}{\partial t}$. Therefore, we obtain the following equation:

$$\frac{\partial T(r, t)}{\partial t} - D_{th} \cdot \Delta T(r, t) = \frac{1}{\rho C_p} \frac{\delta\rho Q}{\delta t} \quad (1)$$

Since the pulse duration is much less than the diffusion time (w^2/D_{th} with w is the beam waist radius at $1/e$), the latter is at the scale of 10^{-7} s and 10^{-6} s, the diffusion process

can be considered therefore to be well separated from the deposition process. During the pulse, a deposition of energy density takes place, but the diffusion does not begin, so $D_{th} \cdot \Delta T = 0$, and Equation (1) becomes:

$$\frac{\partial T(r, t)}{\partial t} = \frac{1}{\rho C_p} \frac{\delta \rho_Q}{\delta t} \quad (2)$$

Assuming a Gaussian shape of $\frac{\delta \rho_Q}{\delta t}(r, t) = \frac{A \cdot E_p}{\pi^{\frac{3}{2}} w^3} \cdot \exp\left[-\frac{r^2}{w^2}\right] \cdot f(t)$, where w is the beam waist radius (at $1/e$), $f(t)$ is the pulse shape (integral of $f(t)$ on the pulse time = 1), E_p is the energy of the pulse, A represents the absorbed fraction of the pulse energy. Therefore, $T(r, 0) - T_{room} = \frac{1}{\rho C_p} \int_{pulse} \frac{\delta \rho_Q}{\delta t} dt = T_{00} \cdot \exp\left[-\frac{r^2}{w^2}\right]$ with:

$$T_{00} = \frac{A \cdot E_p}{\pi^{\frac{3}{2}} \rho C_p w^3} \quad (3)$$

After pulse energy deposition, diffusion begins to operate, and Equation (1) becomes:

$$\frac{\partial T(r, t)}{\partial t} - D_{th} \cdot \Delta T(r, t) = 0 \quad (4)$$

Using the initial and boundary conditions on solutions of Equations (2) and (4), we obtain:

$$T(r, t) = T_{00} \cdot \frac{w^3}{(w^2 + 4D_{th} \cdot t)^{\frac{3}{2}}} \cdot \exp\left[-\left(\frac{r^2}{w^2 + 4D_{th} \cdot t}\right)\right] + T_{room} \quad (5)$$

Equation (5) describes a single-pulse-induced temperature distribution over time. T_{00} is the maximum temperature induced by a laser pulse at the focus center. T_{room} is the ambient temperature, which will be omitted for ease of calculation. The temperature should thus be understood as the temperature increment above the initial sample temperature.

It is important to note that when utilizing the spherical model, the deposited energy volume will consistently yield a higher temperature than reality, as the size along z is usually larger than the waist radius. Given our primary concern lies in assessing the temperature's dependence on various parameters, it is possible to adjust the actual calculated value, which is notably affected by the absorption fraction A , to align it more closely with reality.

In the case of the absorption of N pulses, we easily obtain the evolution of the distribution considering the linearity of the differential equation and making up the sum of the solution for one impulsion but shifted in time $\tau_p = 1/RR$, where RR is the pulse repetition rate:

$$T(r, t) = T_{00} \cdot \sum_{\substack{n=0 \\ N-1=integer\ part(t \cdot f)}}^{N-1} \frac{w^3}{(w^2 + 4D_{th} \cdot t)^{3/2}} \cdot \exp\left[-\left(\frac{r^2}{w^2 + 4D_{th}(t - n \cdot \tau_p)}\right)\right] \quad (6)$$

With $\tau_d = w^2/4D_{th}$, $r_w = \frac{r}{w}$, Equation (6) reads:

$$T(r_w, t) = T_{00} \cdot \sum_{n=0}^{N-1} \frac{1}{\left(1 + \frac{t - n \cdot \tau_p}{\tau_d}\right)^{3/2}} \cdot \exp\left[-\left(\frac{r_w^2}{1 + \frac{t - n \cdot \tau_p}{\tau_d}}\right)\right] \quad (7)$$

We note that the variables involved in Equation (7) are the ratio between the period of the pulses τ_p and the diffusion times τ_d , while the other laser and material parameters are involved in the amplitude T_{00} . Therefore, we introduce the parameter R_τ :

$$R_\tau = \frac{\tau_p}{\tau_d} \quad (8)$$

Therefore, Equation (7) becomes:

$$\frac{T(r_w, t)}{T_{00}} = \sum_{\substack{n=0 \\ N-1 = \text{integer part} \left(\frac{t}{\tau_p}\right)}}^{N-1} \frac{1}{\left[1 + \left(\frac{t}{\tau_p} - n\right) \cdot R_\tau\right]^{\frac{3}{2}}} \cdot \exp\left[-\frac{(r_w)^2}{1 + \left(\frac{t}{\tau_p} - n\right) \cdot R_\tau}\right] \quad (9)$$

where N is the number of pulses defined from the time t .

The objective now is to compute the value of the temperature T according to the coordinate r_w when $N \gg 1/R_\tau$. We will show how the temperature changes with the number of pulses according to heat accumulation (hence R_τ), i.e., when T at the end of the period cumulates with the increase induced by the absorption of the next pulse. We will also describe the properties of the temperature on average in the pulse repetition period. We will also show that a steady state can be reached and give the practical number of pulses for that.

3. Final Temperatures at Steady State

At first, we separate the temperature problem into two cases: (1) at the center, i.e., $r_w = 0$; (2) for general cases when $r_w \neq 0$ including case (1). Again, for the sake of simplicity, T_{00} will be usually omitted. Therefore, the subsequent temperatures will virtually include T_{00} .

3.1. At the Center

At the center, $r_w = 0$, and thus, from Equation (9):

$$T(0, t) = \sum_{\substack{n=0 \\ N-1 = \text{integer part} \left(\frac{t}{\tau_p}\right)}}^{N-1} \frac{1}{\left[1 + \left(\frac{t}{\tau_p} - n\right) \cdot R_\tau\right]^{\frac{3}{2}}} \quad (10)$$

Calling $N_t = \frac{t}{\tau_p}$. The temperature evolutions over the generalized pulse number N_i for several R_τ are shown in Figure 1.

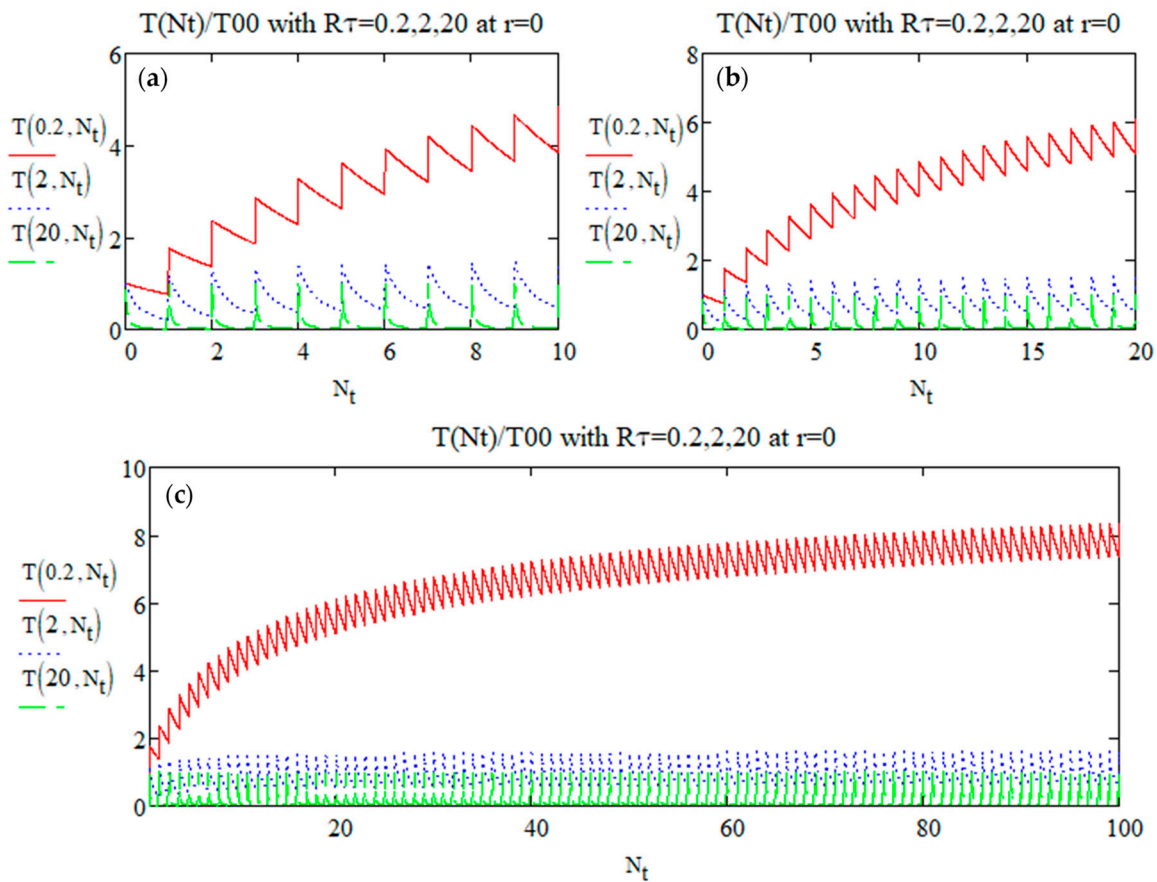


Figure 1. Plot of the relative temperature (Equation (10)) at the center $r_w = 0$ according to the generalized pulse number $N_t = \frac{t}{\tau_p}$ with $R_\tau = 0.2, 2, 20$ until several pulse numbers (a) 10, (b) 20, and (c) 100.

From Figure 1 we observe that:

- $T(0, N_t)$ oscillates between a minimum (T_{min}) and a maximum (T_{max}) in each period between two pulses;
- The oscillation amplitude (T_{osc}) seems to be the same, whatever R_τ ;
- T seems to reach a steady state as N_t becomes large (already seen in various papers [29,31,32]);
- The number of pulses to reach this ‘steady state’ appears very small for a large R_τ but larger for small R_τ values. For a larger R_τ , the temporal overlapping of temperature increase contributions from consecutive pulses is weaker, whereas it increases (heat accumulation) when R_τ is smaller.

3.1.1. The Oscillation Amplitude T_{osc}

We observe the oscillations of temperature on time in Figure 1 on each period. Just after the pulse energy deposition, the temperature experiences a sudden increase and then a slow decrease until the next pulse arrival. It is important to know the amplitude of the temperature oscillations (T_{osc}) because when T_{osc} is large, at the beginning of a period, temperature may be high enough for transformation but in a short time, and at the end of the period during a long time duration, the temperature can be low, maybe achieving another transformation. The middle part could therefore often be the most active part.

The Limit of the Temperature Oscillation Amplitude after an Infinite Number of Pulses

The question here is: how do the oscillations evolve in time according to the pulse number N for a given diffusion time? If the period is large (R_τ large), we expect independent pulses and thus the amplitude will be T_{00} . However, when the pulse period is small (R_τ small), can we imagine a smaller oscillation? The next calculation provides answers.

For that purpose, we compare the difference between the maximum T and minimum T of the N th pulse, $T_{max}(0,N) - T_{min}(0,N) = T(0, t_N) - T(0, t_{N+1} - \varepsilon)$, where ε is an arbitrary small quantity for ensuring that the number of pulses in the expression (11) is the same. T_{max} is defined just after the deposition of the N th pulse, so at the beginning of the pulse, $t_N = (N - 1)\tau_p$. T_{min} is at the end of the pulse period, just before the $(N + 1)$ th pulse arrival. Using Equation (10), we have:

$$\begin{aligned}
 T_{max}(0, N) &= T(0, t = t_N = (N - 1)\tau_p) = \sum_{n=0}^{N-1} \frac{1}{[1 + (N - 1 - n) \cdot R_\tau]^{\frac{3}{2}}} \\
 &= \sum_{n'=0}^{N-1} \frac{1}{[1 + n' \cdot R_\tau]^{\frac{3}{2}}}
 \end{aligned}
 \tag{11}$$

T_{min} will be at $t = N \cdot \tau_p - \varepsilon$, thus not containing the temperature contribution induced by the $(N + 1)$ th pulse, so:

$$\begin{aligned}
 T_{min}(0, N) &= T(0, t = t_{N+1} - \varepsilon = N \cdot \tau_p - \varepsilon) = \sum_{n=0}^{N-1} \frac{1}{[1 + (N - n) \cdot R_\tau]^{\frac{3}{2}}} \\
 &= \sum_{n'=1}^N \frac{1}{[1 + n' \cdot R_\tau]^{\frac{3}{2}}}
 \end{aligned}
 \tag{12}$$

Therefore,

$$T_{osc}(0, N) = T_{max}(0, N) - T_{min}(0, N) = 1 - \frac{1}{[1 + N \cdot R_\tau]^{\frac{3}{2}}}
 \tag{13}$$

and

$$T_{osc}(0, \infty) = \lim_{N \rightarrow \infty} T_{osc}(0, N) = 1
 \tag{14}$$

When $N \gg 1/R_\tau$, T_{osc} tends to 1. This means T_{00} in the absolute scale. T_{osc} according to the pulse number is shown in Figure 2. It reaches a maximum value 1, i.e., T_{00} , when $N \gg 1/R_\tau$. At the beginning of the irradiation, T_{osc} starts with a value smaller than T_{00} , where a smaller R_τ leads to a smaller oscillation at the beginning. When the pulse number N increases until some value, T_{osc} reaches T_{00} . When R_τ is large, e.g., 10, the amplitude is equal to T_{00} whatever N , as pulse contributions are separated (no overlapping). With the expression of T_{00} (Equation (3)), which is proportional to pulse energy (E_p), the temperature oscillation range can be determined.

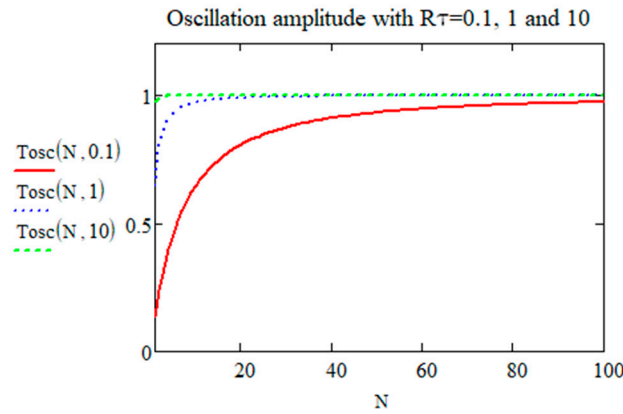


Figure 2. Temperature oscillation $T_{osc}(0, N)/T_{00}$ (here quoted $T_{osc}(N, R_\tau)$) dependence according to pulse number and for three values of $R_\tau = 0.1, 1,$ and 10 .

The Effective Number of Pulses for Reaching the Limit of $T_{osc}(N_{SSO}^0)$

When will the temperature in the material reach a stable oscillation? In practice, we can calculate a real number of pulses (N_{SSO}^0) to closely reach the oscillation limit. (In notation, N_{SSO}^0 , where *SSO* means steady state of oscillation, 0 means the situation when $r_w = 0$).

Consider when $T_{osc}(0, N_{SSO}^0) = (1 - \epsilon) \cdot T_{osc}(0, \infty)$, the limit is practically reached, where ϵ is a small quantity, i.e., a few % (based on the actual situation). Thus, it is:

$$\frac{|T_{ocs}(0, \infty) - T_{osc}(0, N_{SSO}^0)|}{T_{ocs}(0, \infty)} < \epsilon \tag{15}$$

Then, we have:

$$N_{SSO}^0 = \frac{1}{R_\tau} \left[\left(\frac{1}{\epsilon} \right)^{\frac{2}{3}} - 1 \right] \tag{16}$$

The plot of N_{SSO}^0 is shown in Figure 3, note that the actual number of pulses is the integer part above 1 (as ϵ should be smaller, bounded by $\epsilon = \frac{1}{[1+R_\tau]^3}$). Some specific parameters are given below for visualizing this value. With $\epsilon = 3\%$, when $R_\tau = 1$ (conceivable combinations of material parameters and laser RR), $N_{SSO}^0 = 9.36$. So, after 10 pulses, the amplitude of the oscillating temperature reaches $0.97 T_{00}$. When R_τ is large, e.g., $R_\tau = 10$, $N_{SSO}^0 = 0.94$, so only one pulse rules the oscillation amplitude, and we can understand that pulse contributions are separated. When R_τ is smaller, N_{SSO}^0 increases rapidly, e.g., $R_\tau = 0.1$, i.e., $1/R_\tau = 10$, $N_{SSO}^0 = 94$. Beyond N_{SSO}^0 pulses, the oscillation amplitude becomes almost constant. According to the pulse period, we can know the time to reach the constant oscillation amplitude. By comparing with pulse number $N = 1$ (blue dashed line in Figure 3), we can deduce in what condition (R_τ larger than which value) the temperature oscillation is constant since the first pulse.

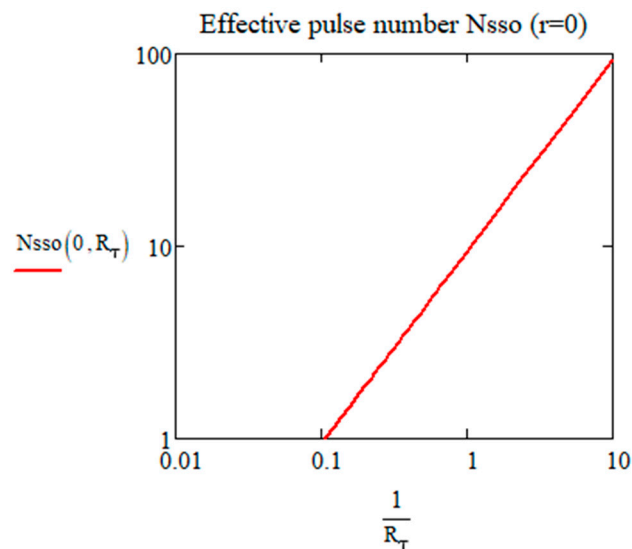


Figure 3. Number of pulses to reach the oscillation amplitude limit N_{ss0}^0 according to R_τ from 0.1 to 100, with $\varepsilon = 3\%$. For $1/R_\tau > 0.1$, weak heat conduction, large RR , and vice versa.

To conclude on this point, Equations (13) and (14) provides that the temperature oscillation amplitude is T_{00} after N_{ss0} pulses and at an oscillatory steady state. Equation (16) provides the effective number of pulses for reaching it. It takes more time when R_τ is very small (slow heat diffusion or high pulse RR) but the requested time remains quite small. In particular, the temperature oscillation amplitude is only relevant to certain laser parameters of a single pulse and material parameters of the energy-to-temperature conversion relationship, independent of RR and diffusion parameters.

T_{min} and T_{max}

We demonstrate in Appendix B that the temperature induced by laser pulses will not increase indefinitely but converge to a finite value. This defines a steady state that corresponds to the equilibrium between the energy supplied by the laser and the energy diffusing out of the irradiated voxel.

The Limit of T_{max} and T_{min}

T_{min} : The analytical expression of the minimum temperature is transformed from the sum expression Equation (12), with details found in Appendix C. Therefore, we obtain:

$$T_{min}(0, N) \approx \frac{1}{2(1 + R_\tau)^{\frac{3}{2}}} + \frac{1}{2(1 + N \cdot R_\tau)^{\frac{3}{2}}} + \frac{2}{R_\tau} \left[\frac{1}{\sqrt{1 + R_\tau}} - \frac{1}{\sqrt{1 + N \cdot R_\tau}} \right] \tag{17}$$

This expression shows the increase of T_{min} according to N and R_τ . It is plotted in Figure 4.

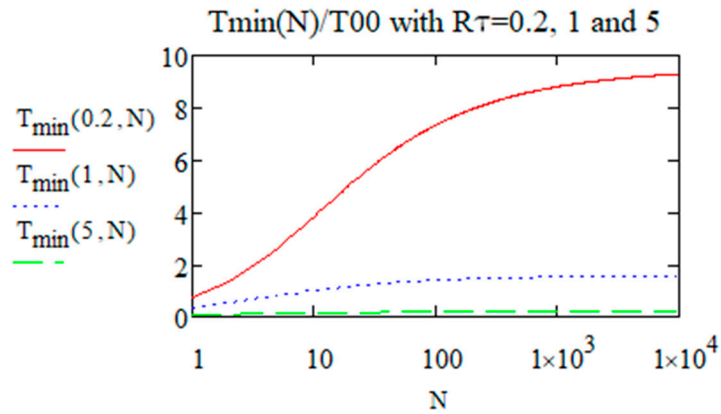


Figure 4. T_{min}/T_{00} at $r_w = 0$ according to N increasing from 1 to 10,000 when $R_\tau = 0.2, 1,$ and 5 .

The final limit of T_{min} , i.e., when $N \gg 1/R_\tau$ is given below:

$$T_{min}(0, \infty) = \frac{1}{2(1 + R_\tau)^{\frac{3}{2}}} + \frac{2}{R_\tau} \frac{1}{\sqrt{1 + R_\tau}} \approx \frac{2}{R_\tau} \frac{1}{\sqrt{1 + R_\tau}} \tag{18}$$

The same method has been applied to obtain the T_{max} limit, and the detail can be also found in Appendix C. We have thus:

$$T_{max}(0, N) \approx 1 + \frac{1}{2[1 + R_\tau]^{3/2}} + \frac{1}{2[1 + (N - 1)R_\tau]^{3/2}} + \frac{2}{R_\tau} \left[\frac{1}{\sqrt{[1 + R_\tau]}} - \frac{1}{\sqrt{1 + (N - 1)R_\tau}} \right] \tag{19}$$

When $N \gg 1/R_\tau$, the T_{max} limit is:

$$T_{max}(0, \infty) = 1 + \frac{1}{2(1 + R_\tau)^{\frac{3}{2}}} + \frac{2}{R_\tau} \frac{1}{\sqrt{1 + R_\tau}} \approx 1 + \frac{2}{R_\tau} \frac{1}{\sqrt{1 + R_\tau}} \tag{20}$$

From these expressions, we see that the difference between $T_{max}(0, \infty)$ and $T_{min}(0, \infty)$ is 1, which is consistent with the oscillation amplitude limitation (Equation (14)).

When R_τ reaches 0 (e.g., by increasing pulse RR or with the material of small thermal conductivity), Equations (18) and (20) are approximately proportional to $\frac{2}{R_\tau}$. Reintroducing here exceptionally T_{00} (Equation (3)), we obtain:

$$T_{max}(0, \infty) \sim T_{min}(0, \infty) \sim T_{00} \cdot \frac{2}{R_\tau} = \frac{2AE_p}{\pi^{\frac{3}{2}}\rho C_p w^3 R_\tau} = \frac{2AE_p \tau_d}{\pi^{\frac{3}{2}}\rho C_p w^3 \tau_p} = \frac{2AE_p f}{\pi^{\frac{3}{2}} D_{th} \rho C_p w} = \frac{2AP}{\pi^{\frac{3}{2}} kW} \tag{21}$$

with P being the average power.

We note that the temperature is now dependent on the incident laser power as is the case for CW lasers, and inversely dependent on the thermal conductivity (κ), whereas T_{00} was dependent on the incident pulse energy (E_p), not on the thermal diffusivity but just on the heat capacity of the material. This is due to large time-overlapping of the pulse contribution when R_τ reaches 0.

Therefore, increasing the pulse RR with constant E_p leads to a faster temperature increase but NOT with constant average power. The same maximal temperature can be achieved with or without heat accumulation. However, T_{min} , which is negligible in front of T_{max} for large R_τ values, increases until it almost equals T_{max} for small R_τ values (large RR).

The Effective Number of Pulses for Reaching the Limit of T_{min} and T_{max} (N_{ssmin}^0, N_{ssmax}^0)

N_{ssmin} : The effective number of pulses to reach the steady state N_{ss} is defined to have temperature reaching T_{min} or T_{max} . As the same definition as for N_{sso} , the first approximation of N_{ssmin} is obtained by solving the following assertion, $\frac{|T_{min}(0,N)-T_{min}(0,\infty)|}{T_{min}(0,\infty)} < \varepsilon$, with ε being a small quantity. Posing $X = \frac{1}{\sqrt{1+N \cdot R_\tau}}$, it reads $\frac{X^3}{2} - \frac{2}{R_\tau} X + \varepsilon \cdot T_{min}(0,\infty) > 0$. This cubic equation has three roots, where the physical one is $X < \frac{\varepsilon \cdot T_{min}(0,\infty)}{\frac{2}{R_\tau}}$. Therefore,

$$N_{ssmin}^0 > \frac{1}{R_\tau} \left[\left(\frac{2}{R_\tau \cdot \varepsilon \cdot T_{min}(0,\infty)} \right)^2 - 1 \right] \tag{22}$$

N_{ssmax} : With the same method, we obtain:

$$N_{ssmax}^0 > \frac{1}{R_\tau} \left[\left(\frac{2}{R_\tau \cdot \varepsilon \cdot T_{max}(0,\infty)} \right)^2 - 1 \right] \tag{23}$$

The N_{ss} for reaching closely the steady state (with ε departure). $T_{osc}(0,\infty)$, $T_{min}(0,\infty)$, and $T_{max}(0,\infty)$ are plotted in Figure 5 according to R_τ (with $\varepsilon = 3\%$).

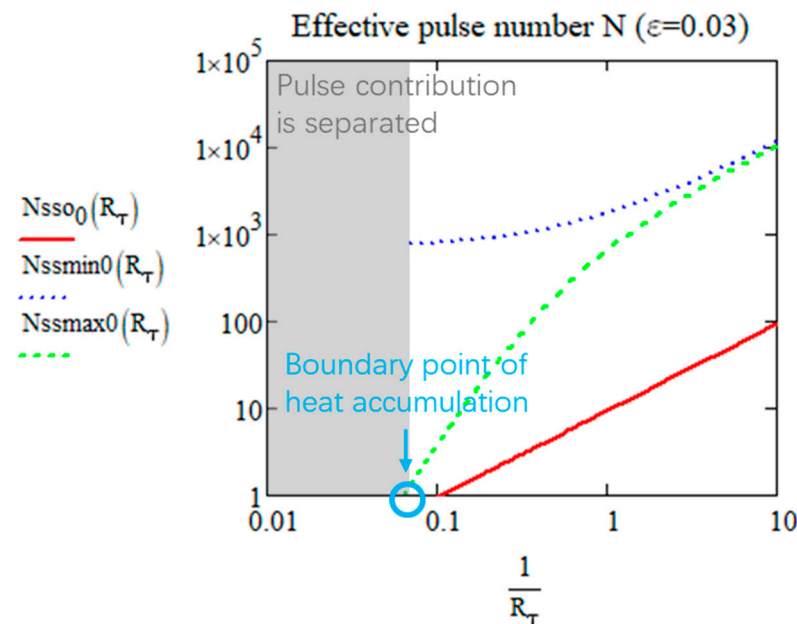


Figure 5. The effective number to reach the limit of T_{osc} , T_{min} , and T_{max} according to R_τ from 0.1 to 100 for $\varepsilon = 0.03$. The boundary point is at $R_\tau = 15.7$.

From Figure 5, we can see that with $1/R_\tau$ increasing, the effective pulse numbers for reaching the steady state increases whether for T_{osc} , T_{min} , or T_{max} . For practical use, it is better to define one N_{ss} for calculation. When R_τ is large, since the value of T_{min} is almost 0 (no pulse superimposition), it is therefore not meaningful to take it into consideration. For N_{sso} and N_{ssmax} , the value converges to 0 when R_τ is large because it can be considered to be already at steady state when the pulses are separated. As observed, the green dash is always higher than the red line when $N > 1$, and the oscillation reaches the steady state faster than T_{max} . Therefore, N_{ssmax}^0 is the suitable and practical number of pulses needed for reaching the steady state. Some examples for the N_{ssmax} value are shown in Table 2 (with $\varepsilon = 0.03$ for organic materials and $\varepsilon = 0.06$ for inorganic materials):

Table 2. Pulse number needed (N_{ss}) for reaching the steady state in materials, using Equation (23).

	SiO ₂	LNS	STS	Glycine	Zeonex	Sucrose	Nifedipine
τ_d (μ s)	0.28	0.235	0.04	0.28	0.42	4.9	1.63
RR(kHz)	200	200	200	200	200	200	200
R_τ	18	21	125	18	12	1	3
N_{ssmax}	1	1	1	1	3	641	80

We observe that for the inorganic material examples in the table, with $RR = 200$ kHz, there is no heat accumulation, pulse contributions are separated, there is no transient time, and the time variation of T is from one pulse contribution. However, for the organic material examples, except for glycine crystal, with same RR , the laser induces heat accumulation. Therefore, not only can we deduce from the known laser and material parameters whether or not there will be heat accumulation, but we can also easily backtrack on how to choose a laser RR that avoids or guarantees heat accumulation in a particular material.

We can thus define the boundary between the two domains by $N_{ssmax}(R_\tau, \epsilon) = 1$ as shown in Figure 5 by the blue point. When the effective pulse number is equal to 1, the pulse contribution is separated, so it is considered that there is no heat accumulation. This is the heat accumulation definition we propose with a new perspective. R_τ varies with the level of sensitivity of the targeted transformation, for $\epsilon = 0.03$, $R_\tau = 15.7$, for $\epsilon = 0.06$, $R_\tau = 7$, for instance.

From N_{ssmax} together with the laser pulse RR , we know the time needed to reach the steady state. Accordingly, the time for reaching the steady state t_{ss}^0 is (considering the effective number to reach the T_{max} limit):

$$t_{ss}^0 = N_{ssmax}^0 \tau_p = \tau_d \left[\left(\frac{2}{R_\tau \cdot \epsilon \cdot T_{max}(0, \infty)} \right)^2 - 1 \right] \tag{24}$$

Figure 6 show the plots versus $\frac{1}{R_\tau} = \frac{RR \cdot w^2}{4 \cdot D_{th}}$ according to three different diffusion times: 0.28 μ s (silica, glycine), 1.63 μ s for nifedipine, and 4.9 μ s for sucrose.

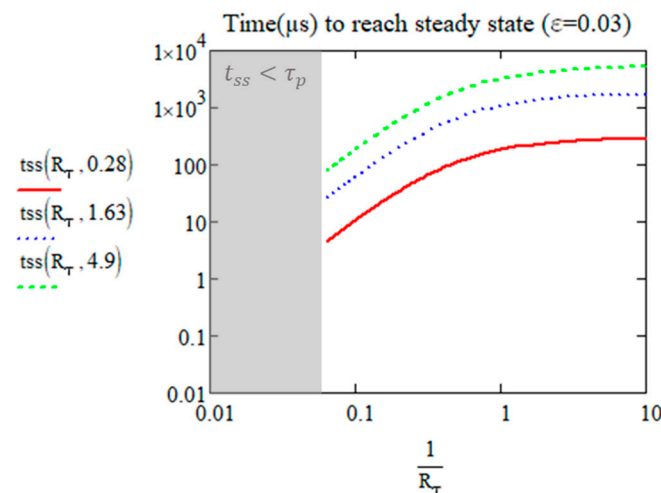


Figure 6. The time in μ s to reach the steady state according to $1/R_\tau$ value for glycine or silica (red), nifedipine (blue dash), and sucrose (green). The value of the second parameter in t_{ss} corresponds to τ_d in Table 2.

For small enough values of R_τ , the time reaches the value τ_d/ϵ^2 , i.e., $1111\tau_d$ for $\epsilon = 3\%$. Note that for inorganic glass and glycine crystal cited above with $\tau_d = 0.28$ μ s, this time is smaller than 1 ms (red profile). However, for sucrose and nifedipine, this time is

5.5 ms and 1.8 ms, respectively. In any case, the important fact is the independency of the transient time with R_τ for small values (see for $R_\tau < 1$) and thus it is bounded to quite a small value.

For large enough values of R_τ , this time is limited by the period τ_p that increases with R_τ .

3.2. Time Behavior out of the Center ($r_w = r/w \neq 0$)

When ($r_w \neq 0$, we come back to the expression Equation (10):

$$T(r_w, t) = \sum_{\substack{n=0 \\ N-1 = \text{integer part}(t/\tau_p)}^{N-1}} \frac{1}{\left[1 + \left(\frac{t}{\tau_p} - n\right) \cdot R_\tau\right]^{3/2}} \cdot \exp\left[-\frac{(r_w)^2}{1 + \left(\frac{t}{\tau_p} - n\right) \cdot R_\tau}\right]$$

Figure 7 shows the temperature evolution based on the above expression over time at two relative distances $r_w = 1$ (Figure 7a,b) and $r_w = 2$ (Figure 7c,d).

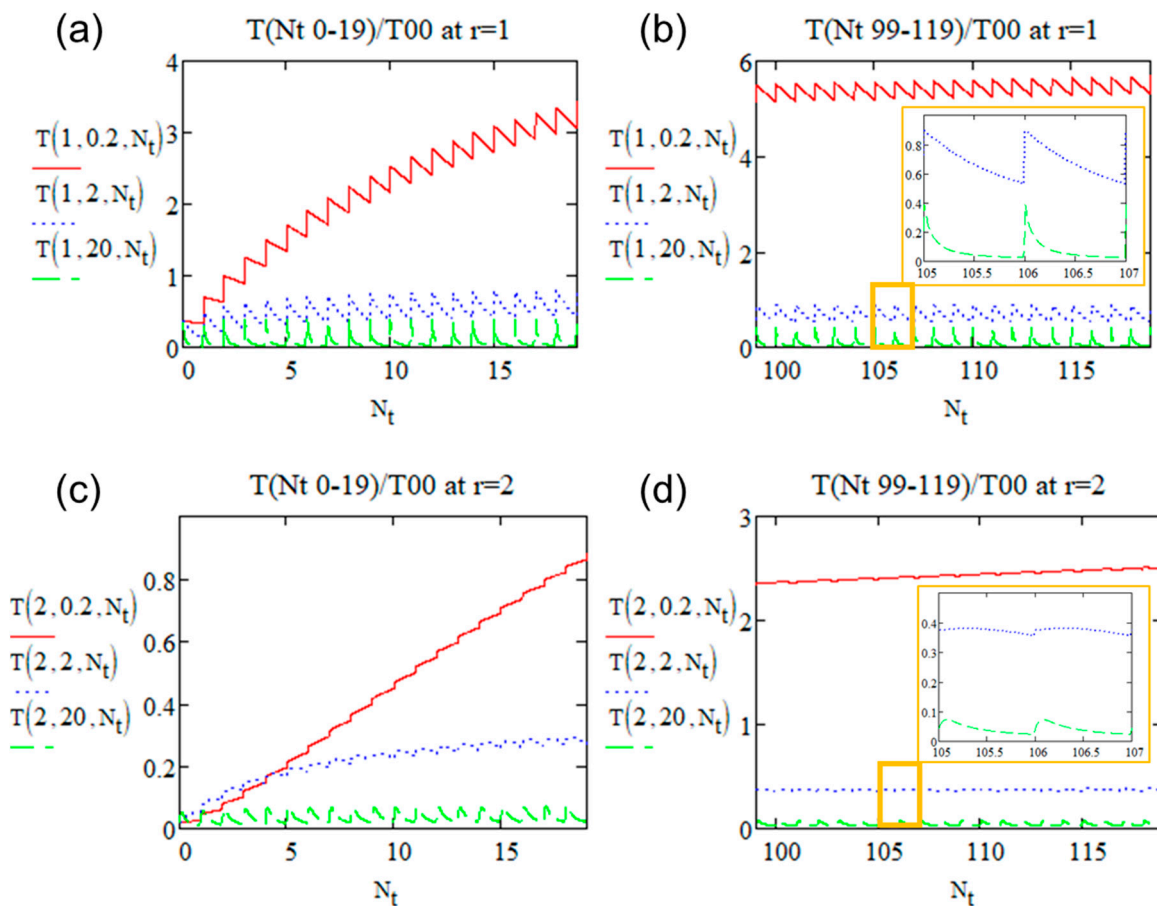


Figure 7. Plot of the relative temperature (T/T_{00}) with $R_\tau = 0.2, 2, 20$ at (a,b) $r = w$ from (a) pulse 1 to pulse 20 and (b) pulse 100 to pulse 120 (c,d) $r = 2w$ from (c) pulse 1 to pulse 20 and (d) pulse 100 to pulse 120. Inserts (b,d) zoom of pulse 106–108 of $R_\tau = 2$ and 20 at $r = w$ and $r = 2w$, respectively.

We observe the following differences according to radius $r_w = 0, 1, 2$:

- The amplitude of oscillation is less than 1 (in the unit of T_{00}) for increasing radius;
- The maximum temperature during a period is still at the beginning of the pulse deposition for $r_w = 1$ with these three R_τ , while at $r_w = 2$ the maximum temperature is no more at the beginning. That is because there is time for heat to diffuse from the

center to r_w . This renders the following calculation of T_{max} for increasing radius to be more complex.

3.2.1. T_{osc} , T_{min} , and T_{max}

The Limit of T_{max} and T_{min} (when $N \gg 1/R_\tau$)

To calculate the oscillation amplitude T_{osc} , it is the same as the case of $r_w = 0$. In general, we compare the difference between the maximum T and minimum T in the N th pulse period. T_{min} is still considered at the end of the N th one, i.e., when $t = N \cdot \tau_p$ before the absorption of the $(N + 1)$ th pulse, so:

$$T_{min}(r_w, N) = \sum_{n=0}^{N-1} \frac{1}{[1 + (N - n) \cdot R_\tau]^{\frac{3}{2}}} \exp\left[-\frac{(r_w)^2}{1 + (N - n) \cdot R_\tau}\right] \quad (25)$$

However, since T_{max} in some situations can be in the middle of the pulse period, we set x_m , $0 \leq x_m \leq 1$ to define the place where the T_{max} is. Therefore, T_{max} is at the time $t = (N - 1 + x_m)\tau_p$:

$$T_{max}(r_w, N) = \sum_{n=0}^{N-1} \frac{1}{[1 + (N - 1 + x_m - n) \cdot R_\tau]^{\frac{3}{2}}} \exp\left[-\frac{(r_w)^2}{1 + (N - 1 + x_m - n) \cdot R_\tau}\right] \quad (26)$$

This expression is also a general expression to describe both T_{max} and T_{min} , while T_{min} appears at the end of the period, i.e., $x_m = 1$, as well as the case when $r_w = 0$, T_{max} appears at the beginning of the period with $x_m = 0$.

The position of the maximum x_m is solved as a function of R_τ , r_w , and N . When considering the steady state, when $N \gg 1/R_\tau$, x_m is shown below, and the results of the cumbersome calculation details can be found in Appendix D:

$$x_m = \frac{\sqrt{R_\tau} \sqrt{9R_\tau + 32(r_w)^2} - 3R_\tau - 8}{8R_\tau} \quad (27)$$

Based on Equation (27), when considering different values of r_w and R_τ , the thermal calculation can be divided into two situations (see Appendix D):

Situation 1: $x_m = 0$, when, $r_w < \sqrt{\frac{3}{2} + \frac{2}{R_\tau}}$ whatever R_τ or R_τ small enough (less than $\frac{2}{r_w^2 - 1.5}$ when $r_w^2 > 1.5$).

Situation 2: $x_m \neq 0$, i.e., $r_w > \sqrt{\frac{3}{2} + \frac{2}{R_\tau}}$, in this situation the maximum temperature is in the middle of the period, and the expressions of T_{max} and T_{osc} should contain x_m .

(1) For situation 1, when $x_m = 0$, the limit of T_{osc} is described as:

$$T_{osc}(r_w, N) = T_{max}(r_w, N) - T_{min}(r_w, N) = \exp[-(r_w)^2] - \frac{\exp\left[-\frac{(r_w)^2}{1 + N \cdot R_\tau}\right]}{(1 + N \cdot R_\tau)^{\frac{3}{2}}} \xrightarrow{N \gg 1/R_\tau} \exp[-(r_w)^2] \quad (28)$$

The amplitude of the temperature oscillations reaches $T_{00} \cdot \exp[-(r_w)^2]$ whatever R_τ . It is consistent with our observations in Figure 7, e.g., the amplitudes are $0.368 T_{00}$ and $0.018 T_{00}$ at $r_w = 1$ and $r_w = 2$, respectively.

Therefore, for T_{min} and T_{max} , using the trapezoidal rule for approximation as for $r_w = 0$, we have T_{min} from Equation (25):

$$T_{min}(r_w, N) \approx \frac{1}{2} \left[\frac{\exp \left[-\frac{(r_w)^2}{1+R_\tau} \right]}{(1+R_\tau)^{3/2}} + \frac{\exp \left[-\frac{(r_w)^2}{1+N \cdot R_\tau} \right]}{(1+N \cdot R_\tau)^{3/2}} \right] + \frac{\sqrt{\pi}}{R_\tau \cdot r_w} \left[\operatorname{erf} \left(\frac{r_w}{\sqrt{1+R_\tau}} \right) - \operatorname{erf} \left(\frac{r_w}{\sqrt{1+N \cdot R_\tau}} \right) \right]$$

$$T_{min}(r_w, N) \xrightarrow{N \gg 1/R_\tau} T_{min}(r_w, \infty) = \frac{\exp \left[-\frac{(r_w)^2}{1+R_\tau} \right]}{2(1+R_\tau)^{3/2}} + \frac{\sqrt{\pi}}{R_\tau \cdot r_w} \operatorname{erf} \left(\frac{r_w}{\sqrt{1+R_\tau}} \right) \tag{29}$$

$\frac{\exp \left[-\frac{(r_w)^2}{1+R_\tau} \right]}{2(1+R_\tau)^{3/2}}$ is called part 1, and $\frac{\sqrt{\pi}}{R_\tau \cdot r_w} \operatorname{erf} \left(\frac{r_w}{\sqrt{1+R_\tau}} \right)$ is called part 2 for further use. T_{max} is $T_{min} + T_{osc}$.

(2) For situation 2, even if x_m influences the T_{max} and T_{osc} , its influence is bounded. When $x_m = 0$ is used, we calculate the temperature at the beginning of the period and the maximum is thus larger (with a non-zero x_m). However, how much larger? In which situations should we care about it? From the analysis, the details are described in Appendix D, we found that the difference appears only around $r_w = 1.6$ to 4 when R_τ is large.

T_{min} is the same as situation 1. For T_{max} , using the trapezoidal rule for approximation as for $r_w \neq 0$, we have T_{max} from Equation (26):

$$T_{max}(r_w, N, x_m) \approx \frac{\exp \left[-\frac{(r_w)^2}{1+x_m \cdot R_\tau} \right]}{[1+x_m \cdot R_\tau]^{\frac{3}{2}}} + \frac{\exp \left[-\frac{(r_w)^2}{1+(1+x_m) \cdot R_\tau} \right]}{2[1+(1+x_m) \cdot R_\tau]^{\frac{3}{2}}} + \frac{\exp \left[-\frac{(r_w)^2}{1+(N-1+x_m) \cdot R_\tau} \right]}{2[1+(N-1+x_m) \cdot R_\tau]^{\frac{3}{2}}} + \frac{\sqrt{\pi}}{R_\tau \cdot r_w} \left\{ \operatorname{erf} \left[\frac{r_w}{\sqrt{[1+(1+x_m) \cdot R_\tau]}} \right] - \operatorname{erf} \left[\frac{r_w}{\sqrt{[1+(N-1+x_m) \cdot R_\tau]}} \right] \right\}$$

$$\xrightarrow{N \gg 1/R_\tau} \frac{\exp \left[-\frac{(r_w)^2}{1+x_m \cdot R_\tau} \right]}{[1+x_m \cdot R_\tau]^{\frac{3}{2}}} + \frac{\exp \left[-\frac{(r_w)^2}{1+(1+x_m) \cdot R_\tau} \right]}{2[1+(1+x_m) \cdot R_\tau]^{\frac{3}{2}}} + \frac{\sqrt{\pi}}{R_\tau \cdot r_w} \left\{ \operatorname{erf} \left[\frac{r_w}{\sqrt{[1+(1+x_m) \cdot R_\tau]}} \right] \right\} \tag{30}$$

$\frac{\exp \left[-\frac{(r_w)^2}{1+x_m \cdot R_\tau} \right]}{[1+x_m \cdot R_\tau]^{\frac{3}{2}}}$, $\frac{\exp \left[-\frac{(r_w)^2}{1+(1+x_m) \cdot R_\tau} \right]}{2[1+(1+x_m) \cdot R_\tau]^{\frac{3}{2}}}$, $\frac{\sqrt{\pi}}{R_\tau \cdot r_w} \left\{ \operatorname{erf} \left[\frac{r_w}{\sqrt{[1+(1+x_m) \cdot R_\tau]}} \right] \right\}$ are called part 1, 2, and 3, respectively.

The general expression of T_{osc} (when N tends to infinity or larger than the effective number for reaching the steady state) is given as T_{max} (Equation (30)) minus T_{min} (Equation (29)), and it reads:

$$T_{osc}(R_\tau, r_w) = \frac{\exp \left[-\frac{(r_w)^2}{1+x_m \cdot R_\tau} \right]}{[1+x_m \cdot R_\tau]^{\frac{3}{2}}} + \frac{\exp \left[-\frac{(r_w)^2}{1+(1+x_m) \cdot R_\tau} \right]}{2[1+(1+x_m) \cdot R_\tau]^{\frac{3}{2}}} + \frac{\sqrt{\pi}}{R_\tau \cdot r_w} \left\{ \operatorname{erf} \left[\frac{r_w}{\sqrt{[1+(1+x_m) \cdot R_\tau]}} \right] \right\} - \frac{\exp \left[-\frac{(r_w)^2}{1+R_\tau} \right]}{2(1+R_\tau)^{\frac{3}{2}}} - \frac{\sqrt{\pi}}{R_\tau \cdot r_w} \operatorname{erf} \left(\frac{r_w}{\sqrt{1+R_\tau}} \right) \tag{31}$$

Part 1 in Equation (29) and part 2 in Equation (30) are smaller than the other parts by a factor 10, so they can be approximately omitted to simplify the expressions in practice.

$$T_{osc}(R_\tau, r_w) \approx \frac{\exp\left[-\frac{(r_w)^2}{1+x_m \cdot R_\tau}\right]}{[1+x_m \cdot R_\tau]^{\frac{3}{2}}} + \frac{\sqrt{\pi}}{R_\tau \cdot r_w} \left\{ \operatorname{erf}\left[\frac{r_w}{\sqrt{[1+(1+x_m) \cdot R_\tau]}}\right] \right\} - \frac{\sqrt{\pi}}{R_\tau \cdot r_w} \operatorname{erf}\left(\frac{r_w}{\sqrt{1+R_\tau}}\right) \quad (32)$$

It is worth noticing (see Appendix D, Figure A4a,b) that when R_τ increases, T_{osc} exhibits a small departure from the exact value at around $r_w = 2$, attributed to the existence of a non-zero x_m . This departure, if it is generally not negligible, is nevertheless bounded. It is calculated to be $\frac{1}{2.44(r_w)^3}$ for a large R_τ (details are shown in Appendix D Figure A4c,d by plotting T_{osc} according to r_w and R_τ). Therefore, the range of T_{osc} is given by Equations (33) and (34):

$$T_{osc}(R_\tau, r_w) \xrightarrow{R_\tau \rightarrow 0} \exp[-(r_w)^2] \quad (33)$$

$$T_{osc}(R_\tau, r_w) \xrightarrow{R_\tau \rightarrow \infty} \frac{1}{2.44(r_w)^3} \quad (34)$$

We note that the oscillation amplitude T_{osc} at situation 1 is $\exp[-(r_w)^2]$ which is the minimum, while in situation 2, the amplitude is larger due to the influence of x_m , with a maximum value of $\frac{1}{2.44(r_w)^3}$ at the place around $r_w = 2$. By now, with these temperature expressions, we obtain the spatial distribution of the minimum and maximum temperature for a given R_τ at steady state, shown in Figure 8. The temperature is oscillating between these two temperature profiles, and note that at $r_w = 0$, the difference is always 1 regardless of R_τ .

We have now all the information for plotting the T distribution with any R_τ value.

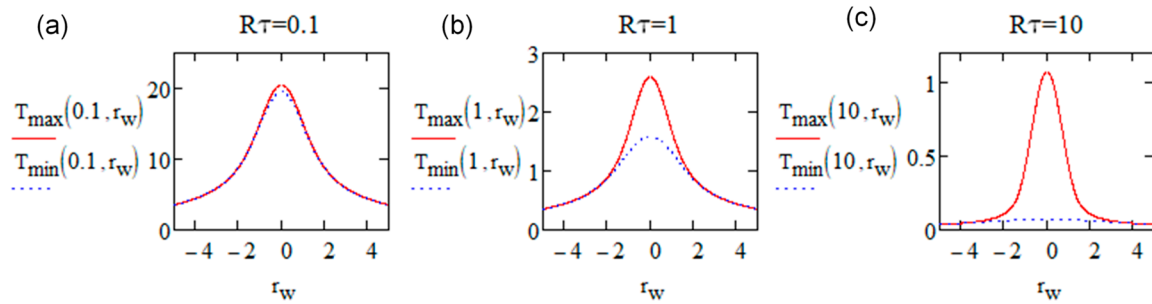


Figure 8. Spatial distribution of T_{min} (blue dash, by Equation (29)) and T_{max} (red, by Equation (30) and Equation (27)) according to the relative radius r_w when (a) $R_\tau = 0.1$, (b) $R_\tau = 1$, and (c) $R_\tau = 10$.

From Figure 8, we can see that when R_τ is small (large frequency or small diffusivity), T_{min} and T_{max} have no large relative difference compared to their average values because the oscillation amplitude is always limited to $\exp[-(r_w)^2]$ whereas the T_{mean} amplitude is converging to $2/R_\tau$ (heat accumulation). This case is interesting if a rather stable temperature is requested. Then, pulse energy can be adjusted for compensating the pulse RR increase. It is also worth noting that, by decreasing R_τ , the shape of the curve converges to the $\operatorname{erf}(r_w)$ curve and decreases much slower than a Gaussian one.

For large values of R_τ (small frequency or large diffusivity), the oscillations are relatively large as the pulses are separated and thus T_{min} appears to have small values. It is negligible (<3%) when $R_\tau > 16$ or <6% for $R_\tau > 7$). This limits the domain of heat accumulation. The calculation shows that the shape of T_{max} is also converging with increasing R_τ to the shape of the beam energy distribution (Gaussian, here $\exp[-(r_w)^2]$) independent of R_τ . This translates that the maximum is almost whatever the radius, at the

beginning of the period. This is not true exactly only around $r = 2w$ where a few % departure from the Gaussian shape of T_{max} is demonstrated.

For R_τ intermediate values, the temperature oscillations are limited between T_{max} and T_{min} . This is shown with particular cases with a shoe box in [31] for $R_\tau = 2$ and 20 or in [32] for $R_\tau = 20$.

However, in this paper, we regard that when $r_w > 2$, the difference between T_{min} and T_{max} is vanishing. We see this in [37].

Therefore, we can deduce in particular, in whatever situation of r_w and R_τ , the temperature oscillations can be neglected and the use of an average temperature is applicable.

Other application remarks:

- (1) In the intermediate cases around $R_\tau = 1$, the center of the heat-affected zone experiences large temperature oscillations whereas the periphery temperature is not oscillating. This may induce differences in the modification structures along the radius. Specifically, the pedestal of the curve, borne by T_{min} , increases in width with R_τ as $1.75 + \frac{1}{16} R_\tau \frac{R_\tau + 145}{R_\tau + 20}$;
- (2) For smaller R_τ values, during the transient period (before N_{ss}), the width of the temperature distribution starts with the beam waist (Gaussian) and then increases until a size which is defined by R_τ . It does not increase indefinitely over time. The order of magnitude is one w per two orders of magnitude on R_τ , e.g., the trace width at 1 MHz is twice the one at 10 kHz.

The Effective Number of Pulses for Reaching the Temperature Limits

Since x_m is not negligible in very limited circumstances, the effective numbers of pulses for reaching the limit of T_{osc} , T_{min} , and $T_{max}(N_{r_{ss}/ssmin/ssmax})$ are given in the situation when $x_m = 0$.

With the same definition as we calculated in $r_w = 0$, with ϵ being a small quantity and $X = \frac{1}{\sqrt{1+N \cdot R_\tau}}$, we have $\frac{|T_{osc/max/min}(r_w, N) - T_{osc/max/min}(r_w, \infty)|}{T_{osc/max/min}(r_w, \infty)} < \epsilon$. Therefore, the $N_{r_{ss}/ssmin/ssmax}$ solutions are shown below:

$$N_{r_{ss}}^r > \frac{-3 \cdot W \left[-\frac{1}{3} e^{-\frac{1}{3} r_w^2} \cdot r_w^2 \cdot \epsilon^{\frac{2}{3}} \right] - 2r_w^2}{3 \cdot R_\tau \cdot W \left[\left(-\frac{1}{3} e^{-\frac{1}{3} r_w^2} \cdot r_w^2 \cdot \epsilon^{\frac{2}{3}} \right) \right]} = \frac{1}{R_\tau} \left[-\frac{2r_w^2}{3 \cdot W \left[\left(-\frac{1}{3} e^{-\frac{1}{3} r_w^2} \cdot r_w^2 \cdot \epsilon^{\frac{2}{3}} \right) \right]} - 1 \right] \quad (35)$$

This expression does not have an analytic root without using the tabulated function W , i.e., the Lambert W function (defined as $\omega e^\omega = z, \omega = W(z)$). In practice, since $X^2 \ll 1$, by approximation, it becomes:

$$N_{r_{ss}}^r > \frac{1}{R_\tau} \left[\left(\frac{1}{\epsilon \cdot \exp[-(r_w)^2]} \right)^{\frac{2}{3}} - 1 \right] \quad (36)$$

For $N_{r_{ssmin}}^r$ and $N_{r_{ssmax}}^r$, with the approximation of $\text{erf}(X \cdot r_w) \approx \frac{2}{\sqrt{\pi}} X \cdot r_w$,

$$N_{r_{ssmin}}^r > \frac{1}{R_\tau} \left[\left(\frac{2}{R_\tau \cdot \epsilon \cdot T_{min}(r_w, \infty)} \right)^2 - 1 \right] \quad (37)$$

$$N_{r_{ssmax}}^r > \frac{1}{R_\tau} \left[\left(\frac{2}{R_\tau \cdot \epsilon \cdot T_{max}(r_w, \infty)} \right)^2 - 1 \right] \quad (38)$$

The behavior of $N_{r_{ss}}^r$ according to R_τ for $r_w = 0$ has already been shown in Figure 5, with an overall increase. We have plotted $N_{r_{ss}}$ and $N_{r_{ssmax}}$, according to r_w , for $R_\tau = 10$ as

an example, as shown in Figure 9a, and the plot of the related time for reaching the steady state (using N_{ssmax} and with diffusion time $0.28 \mu s$) in Figure 9b.

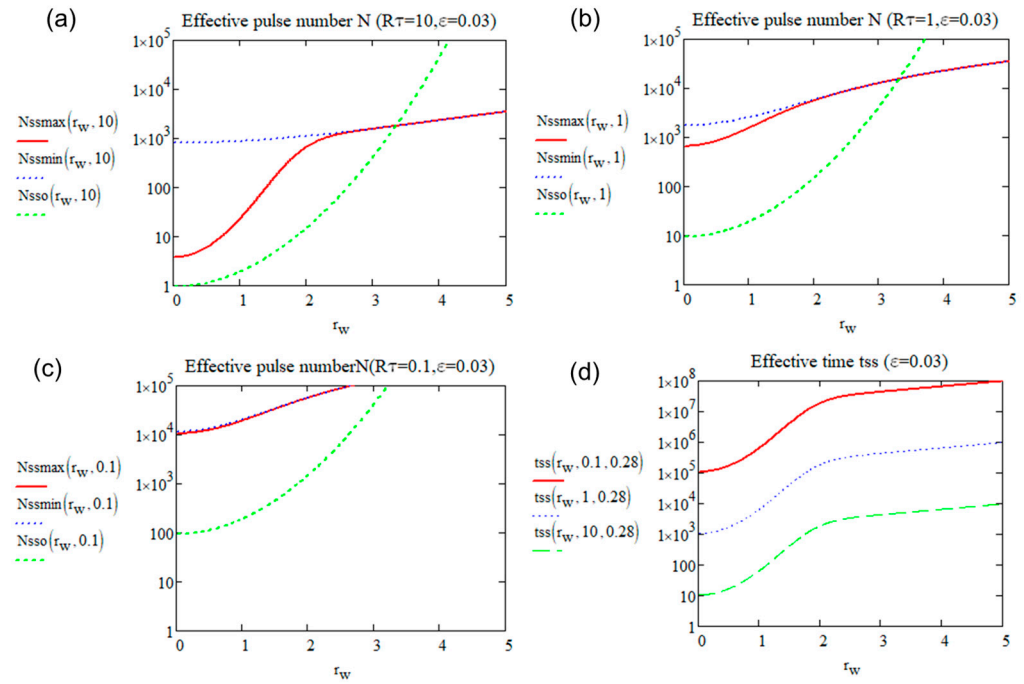


Figure 9. (a–c) Effective number of N_{ssmax} (red), N_{ssmin} (blue dash), and N_{ssso} (green) for reaching a steady state according to r_w from 0 to 5 when (a) $R_\tau = 10$; (b) $R_\tau = 1$; (c) $R_\tau = 0.1$. (d) The time (in μs) for reaching the steady state according to r_w from 0 to 5 when $R_\tau = 0.1, 1$, and 10 .

From Figure 9, we can see that as r_w increases, it takes more pulses (three orders of magnitude more) and this corresponds to a longer time to reach the steady state. Therefore, in reality, even though at the exact center of the beam, the temperature is stable, the periphery is still evolving. In particular, in the case of a moving beam, the maximum speed of scanning is limited by the change at the focus periphery increasing from zero.

4. The Mean Temperature in the Period between Two Pulses

For many transformations induced by laser irradiation (fictive temperature, crystallization, erasure of previously induced structures, stress relaxation, and so on), the large temperatures occurring within a pulse period are so brief that the system has no time to significantly respond. On the contrary, for smaller temperatures occurring at the end of the period, the system may have time to respond if the temperatures are not too small (this is the case for overlapping pulse contribution, i.e., heat accumulation). Therefore, the system responds efficiently predominantly for intermediate temperatures in the main part of the period. On the other hand, when R_τ is small (large pulse RR versus diffusion time), temperature oscillations are relatively small whatever the radius, or for large radius values whatever R_τ values (see Figure 8), the temperature oscillation can be neglected. For these, the use of an average temperature is relevant. In any case, the average value can be a guide for following the temperature distribution in space and its evolution. Hence, this section is devoted to simple expressions of average temperature values in the function of material and laser parameters.

We define the averaging by $\bar{T}(r, N) = \frac{1}{\tau_p} \int_{\text{at } N}^{\text{pulse period}} T(r, t) dt$, and this gives:

$$\bar{T}(r, N) = \frac{1}{\tau_p} \int_{\text{pulse period at } N} T(r, t) dt \tag{39}$$

N.B. due to software problem, the average temperature is sometimes quoted as \bar{T} and sometimes T_{mean} . They have the same meaning.

4.1. Temperature at the Center ($\bar{T}(0, N)$)

$$\bar{T}(0, N) = \frac{1}{\tau_p} \int_{\frac{t}{\tau_p}=N-1}^{\frac{t}{\tau_p}=N} \sum_{n=0}^{N-1} \frac{1}{\left[1 + \left(\frac{t}{\tau_p} - n\right) \cdot R_\tau\right]^{\frac{3}{2}}} dt \tag{40}$$

The two summations can be permuted as they do not operate on the same variables and are independent. We obtain:

$$\bar{T}(0, N) = \frac{1}{\tau_p} \sum_{n=0}^{N-1} \int_{\frac{t}{\tau_p}=N-1}^{\frac{t}{\tau_p}=N} \frac{1}{\left[1 + \left(\frac{t}{\tau_p} - n\right) \cdot R_\tau\right]^{\frac{3}{2}}} dt = \frac{1}{R_\tau} \sum_{n=0}^{N-1} \left[-\frac{2}{\left[1 + \left(\frac{t}{\tau_p} - n\right) \cdot R_\tau\right]^{\frac{1}{2}}} \right]_{\frac{t}{\tau_p}=N-1}^{\frac{t}{\tau_p}=N} = \frac{2}{R_\tau} \left(1 - \frac{1}{\sqrt{1 + N \cdot R_\tau}}\right) \tag{41}$$

This result is obtained without approximation. Then, when $N \gg 1/R_\tau$:

$$\bar{T}(0, \infty) = \lim_{N \gg 1/R_\tau} \bar{T}(0, N) = \frac{2}{R_\tau} \tag{42}$$

We note that here, the steady state temperature at the center will reach:

$$\frac{2 \cdot T_{00}}{R_\tau} = \frac{2A \cdot P}{\pi^{\frac{3}{2}} k W} \tag{43}$$

It is the same expression as for $T_{max}(0, \infty)$ or $T_{min}(0, \infty)$ for small R_τ values. We can note in Figure 10 that $T_{max}(0, \infty)$ and $T_{min}(0, \infty)$ approach $\bar{T}(0, \infty)$ when R_τ is decreasing. $T_{max}(0, \infty)$ goes to 1 and $T_{min}(0, \infty)$ goes to 0 when R_τ is large. From Figure 10, we can also find the heat accumulation bound already defined in Figure 5 (with $\varepsilon = 0,03$). It corresponds to $T_{min}(0, \infty) = 0,03$ and $R_\tau = 12$. On the other hand, when $T_{min}(0, \infty)$ departs from $T_{max}(0, \infty)$ by less than approximately 10%, we can admit that the average T is applicable, i.e., for R_τ smaller than 0.17 (purple circle). In this case, we can apply the simple expression Equation (43).

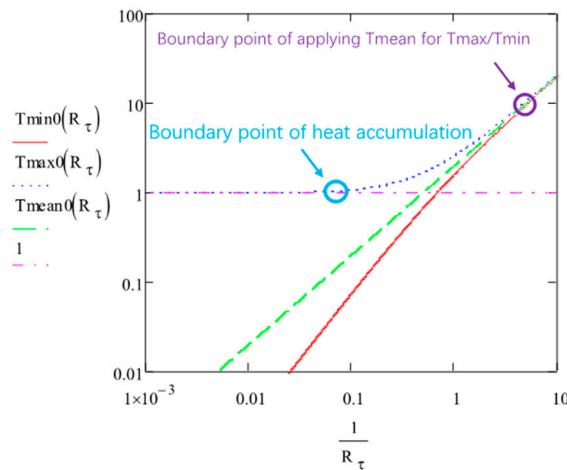


Figure 10. The plots of $T_{min}(0, \infty)$ (red), $T_{max}(0, \infty)$ (blue dash), and $\bar{T}(0, \infty)$ (T_{mean} , green dash) according to $1/R_\tau$. The defined boundary points of heat accumulation and negligible oscillation in the system are marked by a blue circle and purple circle, respectively (for definitions, see text).

The Effective Number of Pulses for Reaching the Limit $\bar{T}(0, \infty)$ (N_{ssm}^0)

With the same definition as above, the number of pulses to reach $\bar{T}(0, \infty)$, i.e., $\frac{|\bar{T}(0, \infty) - \bar{T}(0, N)|}{\bar{T}(0, \infty)} < \epsilon$, N_{ssm}^0 is obtained:

$$N_{ssm}^0 > \frac{1}{R_\tau} \left[\left(\frac{1}{\epsilon} \right)^2 - 1 \right] \tag{44}$$

N_{ssm}^0 are compared to N_{ssmax}^0 and N_{ss0}^0 in Figure 11. The steady state of the mean temperature is reached as T_{max} .

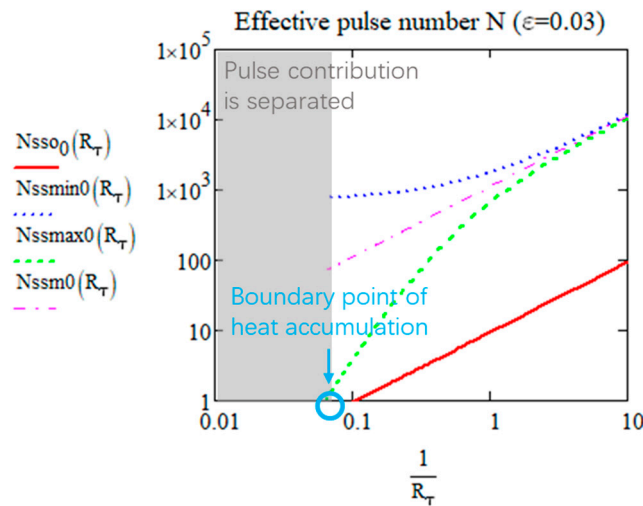


Figure 11. The effective number of pulses to reach the limit of T_{osc} (red), T_{min} (blue dash), T_{max} (green dash), and T_{mean} (pink dash) according to R_τ from 0 to 5.

Therefore, the time for reaching the steady state here is not R_τ dependent: $\tau_D \left[\left(\frac{1}{\epsilon} \right)^2 - 1 \right] \approx \frac{\tau_D}{\epsilon^2} = 1111\tau_D$ when $\epsilon = 0.03$. It is the value of the maximum t_{ss} for reaching a steady state when $R_\tau \rightarrow 0$ (Figure 6).

With these analytical expressions of temperature at the steady state at the center of the focus ($T_{osc}, T_{min}(0, \infty), T_{max}(0, \infty), \bar{T}(0, \infty)$), and the needed number of pulses ($N_{ss0}^0, N_{ssmax}^0, N_{ssm}^0$), we have a clear view of how parameter R_τ influences the thermal

situation at the focus center. The problem is now to extend these results to any place out of the center.

4.2. Temperature out of the Focus Center ($\bar{T}(r, N)$)

With the definition $\bar{T}(r, N) = \frac{1}{\tau_p} \int_{\text{pulse period at } N} T(r, t) dt$, we have the average temperature in a period as:

$$\bar{T}(r_w, N) = \frac{1}{\tau_p} \int_{\frac{t}{\tau_p}=N-1}^{\frac{t}{\tau_p}=N} \sum_{n=0}^{N-1} \frac{1}{\left[1 + \left(\frac{t}{\tau_p} - n\right) \cdot R\tau\right]^{\frac{3}{2}}} \cdot \exp\left[-\frac{(r_w)^2}{1 + \left(\frac{t}{\tau_p} - n\right) \cdot R\tau}\right] \cdot dt = \frac{\sqrt{\pi}}{R\tau \cdot r_w} \cdot \left[erf(r_w) - erf\left(\frac{r_w}{\sqrt{1 + N \cdot R\tau}}\right)\right] \xrightarrow{N \gg \frac{1}{R\tau}} \frac{\sqrt{\pi}}{R\tau \cdot r_w} erf(r_w) \tag{45}$$

$$\text{So } \bar{T}(r_w, \infty) = \frac{\sqrt{\pi}}{R\tau \cdot r_w} erf(r_w)$$

This limit when $N \gg 1/R\tau$ is shown in Figure 12 and compared to the Gaussian shape of T_{max} when $R\tau$ is large and when $R\tau$ is small. When $T_{max}(r)$ is Gaussian for the first case, $T_{max}(r)$ has the same shape that T_{mean} has for the second case. As the erf function tends to 1 (already for $r_w > 2$), the function tends to be hyperbolic and thus decreases much slower than a Gaussian one (see Figure 12). The amplitude is $\frac{2}{R\tau}$. It is inversely proportional to $R\tau$ whatever $R\tau$ value.

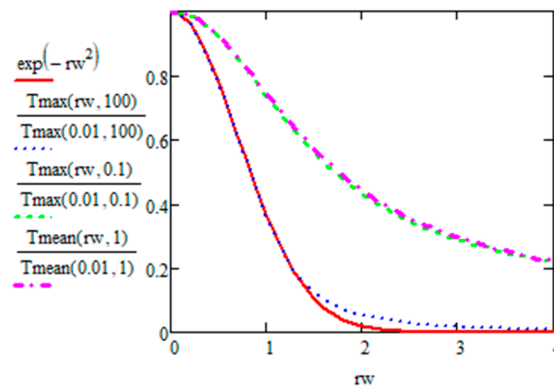


Figure 12. Plot of normalized $T_{max}(r_w, R\tau)$ and $\bar{T}(r_w, R\tau)$ at the steady state for $R\tau = 0.1$ and 100 for T_{max} and 1 for T_{mean} .

Consistently with the previously calculated T_{max} and T_{min} , the T_{mean} curve width is equal to the beam Gaussian for large $R\tau$ values and to the curve limit given in Equation 45 and shown in Figure 8a which is wider.

The Effective Number of Pulses for Reaching the Limit of T_{mean} (N_{ssm}^r)

The effective number of pulses N_{ssm}^r with the approximation $erf(X \cdot r_w) \approx \frac{2}{\sqrt{\pi}} X \cdot r_w$ as $X(N, R\tau) = \frac{1}{\sqrt{1 + N \cdot R\tau}} < 1$, is solved to be:

$$N_{ssm}^r(r_w) > \frac{1}{R\tau} \left[\left(\frac{2}{R\tau \cdot \varepsilon \cdot \bar{T}(r_w, R\tau)} \right)^2 - 1 \right] = \frac{1}{R\tau} \left[\left(\frac{2 \cdot r_w}{\varepsilon \cdot \sqrt{\pi} \cdot erf(r_w)} \right)^2 - 1 \right] \tag{46}$$

From the expression above, we see that the periphery of the distribution is stabilized later than the center as we noticed already in the previous section.

5. Application Examples

To demonstrate the practical significance of the aforementioned calculations, we are discussing below several problems where we can apply these equations to analyze the temperature effects.

Laser-induced crystallization. It is known that for crystallizing a glass, it is necessary to control temperature and time in order to penetrate the crystallization domain [38]. A method for reaching it with a pulsed laser is described in [39]. It is shown that crystallization with a single pulse is possible from the solid state if the beam scanning speed is sufficiently low according to the nucleation time and crystallization growth rate. For a larger scanning speed, it is necessary to increase the pulse energy or the RR to reach the crystallization domain. This is for the formation of nanocrystals that are orientable with laser polarization. The decrease in the speed leads to the growth of the nanocrystals. In turn, crystallization is still possible if the speed is increased but the pulse energy should be increased. In such a way, the temperature overcomes the melting one during a time long enough in the pulse period and the material is melted in such a way that crystallization does not progress more after each pulse. From the calculations in this paper, the best method appears to be a high RR with moderate pulse energy in order to maintain T (control of T_{max} and T_{min}) around the crystallization temperature.

Erasure process during laser writing. In the case of pure silica, there is a first regime called type I for which the refractive index increases for pure silica glasses [40,41]. It is partly produced by a change in fictive temperature [42,43]. For that, the time for the temperature to decrease until a given value of temperature has to be larger than the relaxation time of the glass. This time is roughly defined by the cooling time which is itself defined by the moving spatial curve for one pulse [44]. Pulse energy can be adjusted consequently.

In the case of the materials in which type II transformation is achievable giving rise to a large birefringence based on self-organized nanograting (NG) and nanopores, there is a pulse-energy–RR–scanning-speed-related domain [45,46]. This domain is limited for large pulse energies depending on RR. In addition, for large RR values, the retardance decreases until it is no longer possible to write NGs. One of the hypotheses is the following: NG is based on the existence of nanopores distributed in a self-organized NG [9]. Recent work [47] shows that the thermal stability of such an object is defined by the viscosity that itself depends on T . Therefore, as T increases when pulse energy and RR are increased, they have to be limited to avoid an in-pulse erasure after creation during the pulse.

Concurrent processes. In organic materials, according to pulse energy and RR for the same mean power, two different processes are observed whereas we could believe that modification is just dependent on mean power (i.e., dose) [48]. One is the destruction of the material at low RR and high E_p , while the other is the creation of luminophores at high RR and low E_p . We explain this by looking at the amplitude of the T oscillations; we can say that for the first case, the oscillations are large whereas for the other case, they are small. In the first case, the temperature is overcoming the decomposition temperature of the material but not in the second case.

Size of the crystallized trace. In [49], we find a size of the heat-affected zone that is much larger for the glass called Silica-SrTiO₃ than for Silica-LiNbO₃ for comparable laser parameters. R_τ for the first is 84 and for the second is 11. The first remark is that there is almost no heat accumulation (separated pulse contribution to the temperature) especially for the STS glass. For this glass, it is even possible to use the formula for one contribution. Then, the size is defined by the lowest maximal temperature according to the radius (Equation (30)) at least larger than T_g . Note that due to the expected size of the trace, the use of T_{mean} is possible for intermediate R_τ values (Equation (45)).

$$\frac{\sqrt{\pi}}{R\tau \cdot r_w} \operatorname{erf}(r_w) = \bar{T}(r_w, \infty) = \frac{T_g}{T_{00}}$$

Crown effect. In [49], we also find an example of a crystallized shell (the center is not crystallized). Similarly, as above, there is a highest maximal temperature that is equal to $T_{melting}$. Above this temperature, the viscosity decreases strongly and other processes may appear (see [49]) to be blocking crystallization on cooling.

Speed effect on the laser trace width. In glasses for mid IR [50], the energy threshold for the appearance of a sudden spatial broadening depends on the scanning speed, so we can deduce that it is not related to temperature as the writing speed is not involved in the thermal diffusion for a speed lower than a few m/s.

There are also some remarks that we can deduce from the calculation:

- If a process is actually independent of RR , it does not depend on temperature (see [46]);
- The number of pulses received by the material locally depends on the scanning speed. As the number of pulses for reaching a steady state is different at the center than at the periphery, it is possible that the appearance of the trace on the edge depends on the scanning speed during the transient stage;
- However, the transient stage is not dependent on the pulse energy.

6. Conclusions

This study derives analytical expressions for the temperature distribution at the steady state induced by ultrafast multi-pulses within a spherical geometry, based on the laser and constant material parameters. These expressions depend only on two parameters: the initial temperature at the center (denoted as T_{00}) and a quantity R_τ , defined as the ratio of the pulse period τ_p to the diffusion time τ_d . We recall that temperature oscillates between T_{max} and T_{min} , eventually reaching a steady state, and we calculate the minimum number of pulses required to attain this state. For ease of use, a geometry with spherical symmetry was chosen for the energy deposition in order to lead to simple temperature expressions compiled in Table 3. The Table 4 is a further simplification usable in most of the cases. This approach also facilitates a clear and precise definition of the onset of heat accumulation.

Table 3. Analytical expressions of final temperature and the effective number for reaching steady state. *: condition of r_w, R_τ (Equation (27), Figure A2).

		$r_w = 0$		
	$T(\mathbf{0}, N)$	$T(\mathbf{0}, N \rightarrow \infty)$	$N_{ss}^0(\epsilon, R_\tau)$	
$T_{osc}(\mathbf{0}, N)$	$1 - X^3$	1	$\frac{1}{R_\tau} \left[\left(\frac{1}{\epsilon} \right)^{2/3} - 1 \right]$	
$T_{min}(\mathbf{0}, N)$	$\frac{1}{2} [X1^3 + X^3] + \frac{2}{R_\tau} [X1 - X]$	$\frac{1}{2} X1^3 + \frac{2}{R_\tau} X1$	$\frac{1}{R_\tau} \left[\left(\frac{2}{R_\tau \cdot \epsilon \cdot T_{min}(\infty)} \right)^2 - 1 \right]$	
$T_{max}(\mathbf{0}, N)$	$1 + T_{min}(N)$	$1 + T_{min}(\infty)$	$\frac{1}{R_\tau} \left[\left(\frac{2}{R_\tau \cdot \epsilon \cdot T_{max}(\infty)} \right)^2 - 1 \right]$	
$\bar{T}(\mathbf{0}, N)$	$\frac{2}{R_\tau} (1 - X)$	$\frac{2}{R_\tau}$	$\frac{1}{R_\tau} \left[\left(\frac{1}{\epsilon} \right)^2 - 1 \right]$	
		$r_w \neq 0$ *		
	$T(\mathbf{r}, N)$	$T(\mathbf{r}, N \rightarrow \infty)$	$N_{ss}^r(\epsilon, R_\tau)$	
$T_{osc}(\mathbf{r}, N)$	$exp[-(r_w)^2] - X^3 exp[-(X \cdot r_w)^2]$	$exp[-(r_w)^2]$	$\frac{1}{R_\tau} \left[\left(\frac{1}{\epsilon \cdot exp[-(r_w)^2]} \right)^{2/3} - 1 \right]$	
$T_{min}(\mathbf{r}, N)$	$\frac{1}{2} [X1^3 exp[-(X1 \cdot r_w)^2] + X^3 exp[-(X \cdot r_w)^2]] + \frac{\sqrt{\pi}}{R_\tau \cdot r_w} [erf(X1 \cdot r_w) - erf(X \cdot r_w)]$	$\frac{1}{2} X1^3 exp[-(X1 \cdot r_w)^2] + \frac{\sqrt{\pi}}{R_\tau \cdot r_w} erf(X1 \cdot r_w)$	$\frac{1}{R_\tau} \left[\left(\frac{2}{R_\tau \cdot \epsilon \cdot T_{min}(\infty)} \right)^2 - 1 \right]$	

$T_{max}(\mathbf{r}, N)$	$\exp[-(r_w)^2] + T_{min}(N)$	$\exp[-(r_w)^2] + T_{min}(\infty)$	$\frac{1}{R_\tau} \left[\left(\frac{2}{R_\tau \cdot \varepsilon \cdot T_{max}(\infty)} \right)^2 - 1 \right]$
$\bar{T}(\mathbf{r}, N)$	$\frac{\sqrt{\pi}}{R_\tau \cdot r_w} \cdot [\text{erf}(r_w) - \text{erf}(X \cdot r_w)]$	$\frac{\sqrt{\pi}}{R_\tau \cdot r_w} \text{erf}(r_w)$	$\frac{1}{R_\tau \tau} \left[\left(\frac{2 \cdot r_w}{\varepsilon \sqrt{\pi} \cdot \text{erf}(r_w)} \right)^2 - 1 \right]$

Table 4. Practical approximated analytical expressions of final temperature and the effective number for reaching steady state. With $X(N, R_\tau) = \frac{1}{\sqrt{1+N \cdot R_\tau}}$ and $X1(R_\tau) = \frac{1}{\sqrt{1+R_\tau}}$. *: condition of r_w, R_τ (Equation (27), Figure A2).

		$r_w = 0$	$r_w \neq 0$ *	
$T(\mathbf{0}, N \rightarrow \infty)$		$N_{ss}^0(\varepsilon, R_\tau)$	$T(\mathbf{r}, N \rightarrow \infty)$	$N_{ss}^r(\varepsilon, R_\tau)$
$T_{osc}(\mathbf{r}, N)$	1	$\frac{1}{R_\tau} \left[\left(\frac{1}{\varepsilon} \right)^{2/3} - 1 \right]$	$\exp[-(r_w)^2]^*$	$\frac{1}{R_\tau} \left[\left(\frac{1}{\varepsilon \cdot \exp[-(r_w)^2]} \right)^{2/3} - 1 \right]$
$T_{min}(\mathbf{r}, N)$	$\frac{2}{R_\tau} X1$	$\frac{1}{R_\tau} \left[\left(\frac{2}{R_\tau \cdot \varepsilon \cdot T_{min}(\infty)} \right)^2 - 1 \right]$	$\frac{\sqrt{\pi}}{R_\tau \cdot r_w} \text{erf}(X1 \cdot r_w)$	$\frac{1}{R_\tau} \left[\left(\frac{2}{R_\tau \cdot \varepsilon \cdot T_{min}(\infty)} \right)^2 - 1 \right]$
$T_{max}(\mathbf{r}, N)$	$1 + T_{min}(\infty)$	$\frac{1}{R_\tau} \left[\left(\frac{2}{R_\tau \cdot \varepsilon \cdot T_{max}(\infty)} \right)^2 - 1 \right]$	$\exp[-(r_w)^2] + T_{min}(\infty)$	$\frac{1}{R_\tau} \left[\left(\frac{2}{R_\tau \cdot \varepsilon \cdot T_{max}(\infty)} \right)^2 - 1 \right]$
$\bar{T}(\mathbf{r}, N)$	$\frac{2}{R_\tau}$	$\frac{1}{R_\tau} \left[\left(\frac{1}{\varepsilon} \right)^2 - 1 \right]$	$\frac{\sqrt{\pi}}{R_\tau \cdot r_w} \text{erf}(r_w)$	$\frac{1}{R_\tau} \left[\left(\frac{2 \cdot r_w}{\varepsilon \sqrt{\pi} \cdot \text{erf}(r_w)} \right)^2 - 1 \right]$

We analyzed the distribution of the temperature oscillations relative to the radius from the center and the parameter R_τ . Oscillations are large at the center for large R_τ values but decrease strongly for a large radius $r_w > 2$, i.e., for the periphery where the light intensity decreases almost by a factor of 10. On the contrary, oscillations are minimal everywhere for small R_τ values (i.e., high frequency or low thermal diffusivity). In such conditions, the average of the temperature from the last period can be used, yielding even simpler expressions. Additionally, we found that the periphery of the focus reaches the steady state later than the center. By examining the pulse number required for the steady state according to the radius, we can better control transformations in these regions and understand the variations from the center.

This work aids in understanding how temperature variations influence different experimental observations, mentioned at the end. It can also be helpful to detect if temperature is acting on the processes of direct laser writing.

Future work includes refining this approach by considering the asymmetry of fs focus, making differences between transversal radius and depth to deduce how the trace changes over time. Another interesting point is the T dependence of the physical–chemical parameters, but this cannot be investigated without finite element calculation. Our approach allows us to choose the most representative parameters for applying such a calculation. In addition, the asymmetry of the focal volume, along and perpendicular to the propagation axis, is a refinement of the present calculations that we could be interested in to include variations with the pulse energy (like Kerr focusing, plasma density defocusing, plasma mirror).

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Conflicts of Interest: The authors declare no conflicts of interest.

Appendix A

Table A1. Glossary of laser and material parameters.

Parameters	Definitions	Units
A	Fraction of reflected light by the plasma	none
α	Light absorption	μm^{-1}
ε	A small quantity of computational needs	none
τ_p	Period of the pulses	μs
τ_D	Heat diffusion time $\tau_D = \frac{w^2}{4D_T}$	μs
R_τ	τ_p/τ_D	none
w	Beam waist radius (at $1/e$)	μm
D_T	Thermal diffusivity $D_T = \frac{\kappa}{\rho \cdot c_p}$	m^2/s
κ	Thermal conductivity	$\text{W}/(\text{m}\cdot\text{K})$
E_p	Pulse energy	J
f	Pulse repetition rate	MHz
ρ	Density	kg/m^3
C_p	Specific heat capacity	$\text{J}/(\text{kg}\cdot\text{K})$

Table A2. Thermal physico-chemical data of some materials and processing parameters.

	ρ (kg/m^3)	C_p ($\text{J}/(\text{kg}\cdot\text{K})$)	κ ($\text{W}/(\text{m}\cdot\text{K})$)	D_T (m^2/s)	τ_D (μs)	Melting Point (K)
STS glass	3887	410	10.1	6.34×10^{-6}	0.039	1585
LNS glass	3830	650	2.65	1.06×10^{-6}	0.235	1530
SiO ₂ (glass)	2200	703	1.38	8.92×10^{-7}	0.28	1983
Borosilicate (Schott D263) [40]	2510	820	0.96	4.66×10^{-7}	0.534	1324
Glycine	1160.7	1266	1.3 [51]	8.85×10^{-7}	0.283	506 (decomp.)
Zeonex	1010	1000	0.045	4.445×10^{-8}	5.624	553
Nifedipine	1300	1000	0.2	1.54×10^{-7}	1.63	446
Sucrose	1587	1243.1	0.1	5.07×10^{-8}	4.93	458 (decomp.)

Appendix B. The Existence of a Bound for T_{max} and T_{min}

Does T_{max} theoretically have a limitation?

Since the temperature is the sum of the temperature contribution induced by each pulse, as shown in Equation (10), we need to know the convergence of this sum when the time or pulse number N increases to infinity. A condition necessary but not sufficient is that the increase between the T_{max} just after $N + 1$ pulses and just after N pulses, i.e., $t_N = (N - 1) \tau_p$ and $t_{N+1} = N \tau_p$, is tending to 0. It is:

$$\begin{aligned}
 T_{max}(0, t_{N+1}) - T_{max}(0, t_N) &= \sum_{n=0}^N \frac{1}{[1 + (N - n) \cdot R_\tau]^{\frac{3}{2}}} - \sum_{n=0}^{N-1} \frac{1}{[1 + (N - 1 - n) \cdot R_\tau]^{\frac{3}{2}}} \\
 &= \frac{1}{[1 + N \cdot R_\tau]^{\frac{3}{2}}}
 \end{aligned} \quad (\text{A1})$$

When R_τ is fixed, Equation (A1) goes to 0 when N tends to infinity. It is the same if we consider the difference of T_{min} .

On the other hand, the sum expression of Equations (11) and (12) can be proved to be convergent by using the p-series test, since the p value in them ($p = 3/2$) is larger than 1 [52].

Appendix C. Expression Approximation

To calculate the limit of the temperature, we start with the evolution of the minimum temperature on each period as long as N increases to infinity (so, with Equation (12), the limit of $T_{min}(0, t_{N+1})$ with $N \gg 1/R_\tau$).

Here, we introduce the approximation derived from the trapezoidal rule for the calculation of the integral, which is:

$$\sum_{n=0}^{N-1} f(n) \approx \frac{f(0) + f(N-1)}{2} + \int_0^{N-1} f(n)dn \tag{A2}$$

Here,

$$f(n) = \frac{1}{[1 + (N - n) \cdot R_\tau]^{\frac{3}{2}}}$$

with an error smaller than $\frac{(N-1)^3}{12N^3} f''(n)n$.

Therefore, with this approximation, we obtain:

$$T_{min}(0, N) \approx \frac{1}{2(1 + R_\tau)^{\frac{3}{2}}} + \frac{1}{2(1 + N \cdot R_\tau)^{\frac{3}{2}}} + \frac{2}{R_\tau} \left[\frac{1}{\sqrt{1 + R_\tau}} - \frac{1}{\sqrt{1 + N \cdot R_\tau}} \right] \tag{A3}$$

When N goes to infinity, $T_{min}(0, N)$ goes to:

$$T_{min}(0, \infty) = \frac{1}{2(1 + R_\tau)^{\frac{3}{2}}} + \frac{2}{R_\tau} \frac{1}{\sqrt{1 + R_\tau}} \approx \frac{2}{R_\tau} \frac{1}{\sqrt{1 + R_\tau}} \tag{A4}$$

T_{max} : The same method has been applied to obtain the T_{max} limit but with the last term from the sum extracted out (due to the nature of the trapezoidal rule, there is a sharp increment in the temperature of the last pulse, which should not be averaged out):

$$\sum_{n=0}^{N-1} f(n) \approx f(N-1) + \frac{f(0) + f(N-2)}{2} + \int_0^{N-2} f(n)dn \tag{A5}$$

$$f(n) = \frac{1}{[1 + (N - 1 - n) \cdot R_\tau]^{\frac{3}{2}}}$$

We have thus:

$$T_{max}(0, N) \approx 1 + \frac{1}{2[1 + R_\tau]^{3/2}} + \frac{1}{2[1 + (N - 1)R_\tau]^{3/2}} + \frac{2}{R_\tau} \left[\frac{1}{\sqrt{[1 + R_\tau]}} - \frac{1}{\sqrt{[1 + (N - 1)R_\tau]}} \right] \tag{A6}$$

T_{max} can also be obtained by the T_{min} Equation (A4) + T_{osc} (Equation (13)), thus:

$$T_{max}(0, N) = 1 + \frac{1}{2[1 + R_\tau]^{3/2}} - \frac{1}{2[1 + N \cdot R_\tau]^{3/2}} + \frac{2}{R_\tau} \left[\frac{1}{\sqrt{[1 + R_\tau]}} - \frac{1}{\sqrt{[1 + N \cdot R_\tau]}} \right] \tag{A7}$$

Both Equation (A6) or Equation (A7), when N tends to infinity:

$$T_{max}(0, \infty) = 1 + \frac{1}{2(1 + R_\tau)^{3/2}} + \frac{2}{R_\tau} \frac{1}{\sqrt{1 + R_\tau}} \approx 1 + \frac{2}{R_\tau} \frac{1}{\sqrt{1 + R_\tau}} \tag{A8}$$

The errors: For T_{min} , the error is smaller than $\frac{(N-1)^3}{12N^3} f''(n)$ with $f''(n) = \frac{15 \cdot R_\tau^2}{4[1+(N-n) \cdot R_\tau]^{7/2}}$ with $0 \leq n \leq N - 1$ [53,54] and has to be compared with $T_{min}(0, \infty) = \frac{1}{2[1+R_\tau]^{3/2}} + \frac{2}{R_\tau} \frac{1}{\sqrt{1+R_\tau}}$. The error is smaller than 1.1% for any value of R_τ , as shown in Figure A1a.

For T_{max} , we have an error smaller than $\frac{(N-2)^3}{12(N-1)^3} f''(n)$ with $f''(n) = \frac{15 \cdot R_\tau^2}{4[1+(N-1-n) \cdot R_\tau]^{7/2}}$ with $0 \leq n \leq N - 2$. The error has to be compared with $\frac{T_{max}(0, \infty)}{T_0} = 1 + \frac{1}{2[1+R_\tau]^{3/2}} + \frac{2}{R_\tau} \frac{1}{\sqrt{1+R_\tau}}$. The error is smaller than 1.7% for any value of R_τ , as shown in Figure A1b.

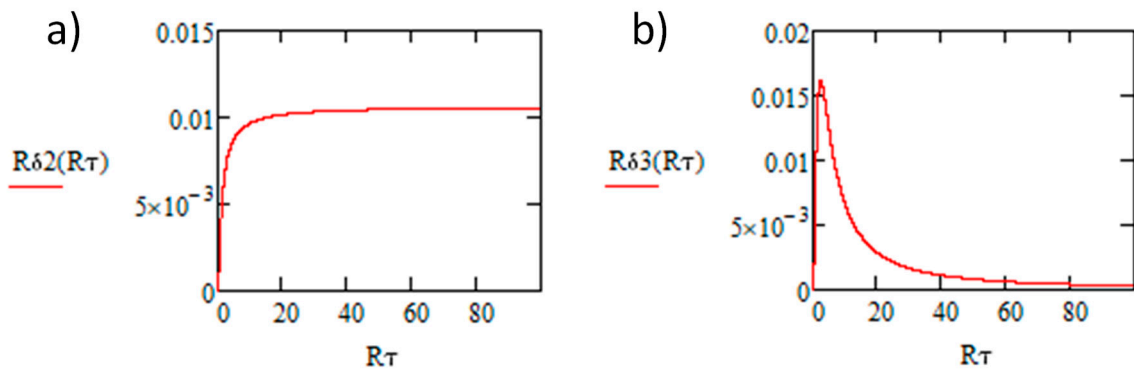


Figure A1. The error in using the trapezoidal rule for the approximation of computing. (a) T_{min} and (b) T_{max} versus R_τ .

Appendix D. About Situation 2 in Section 3.2.1: When the T_{max} is in the Middle of a Pulse Period

To calculate the oscillation amplitude T_{osc} for $r \neq 0$, same as the case of $r_w = 0$, in general, we compare the difference between the maximum T and minimum T of the N th pulse period. T_{min} is considered still at the end of the N th pulse, i.e., when $t = N \cdot \tau_p$ without the $(N + 1)$ th pulse, so:

$$T_{min}(r_w, N) = \sum_{n=0}^{N-1} \frac{1}{[1 + (N - n) \cdot R_\tau]^{3/2}} \exp \left[-\frac{(r_w)^2}{1 + (N - n) \cdot R_\tau} \right] \tag{A9}$$

while T_{max} in some situations can be in the middle of the pulse period, we thus set $x_m, 0 \leq x_m \leq 1$ to define the place where the T_{max} is. Therefore, T_{max} is at $t = (N - 1 + x_m)\tau_p$:

$$T_{max}(r_w, N) = \sum_{n=0}^{N-1} \frac{1}{[1 + (N - 1 + x_m - n) \cdot R_\tau]^{3/2}} \exp \left[-\frac{(r_w)^2}{1 + (N - 1 + x_m - n) \cdot R_\tau} \right] \tag{A10}$$

This expression is the general expression to describe both T_{max} and T_{min} , while T_{min} appearing at the end of the period means $x_m = 1$, as well as the case when $r_w = 0$, T_{max} appears at the beginning of the period with $x_m = 0$.

To find the place of the maximum in the period, we search for the root x_m of the derivative of Equation (A10). We obtain the root x_m as a function of R_τ and r_w and N , but to know only the final situation, and also for mathematical solvability, x_m is described as Equation (A11) as $N \gg 1/R_\tau$. The x_m values according to R_τ , r_w are plotted in Figure A2.

$$x_m = \frac{\sqrt{R_\tau} \sqrt{9R_\tau + 32(r_w)^2} - 3R_\tau - 8}{8R_\tau} \tag{A11}$$

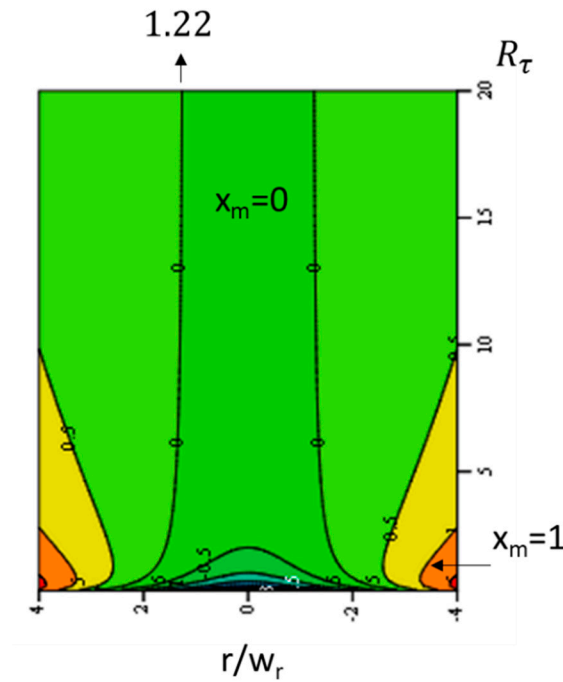


Figure A2. 2D map of the solution x_m according to R_τ and the reduced radius (r/w). Lines correspond to iso x_m .

In Figure A2, $x_m = 0$ is located in the center of this map (at $r_w = 0$), the boundary is between dark green and green, below it x_m is negative and it should be considered to be 0 (this is the maximum T location), i.e., the blue and purple area is also $x_m = 0$. In this parameter region (r_w, R_τ), the maximum of temperature is at the beginning of the period. From green to yellow then orange, the x_m value increases to 0.5 then to 1, i.e., the maximum of temperature is in the middle of the period or even at the end. The boundary between yellow–green and orange is the boundary of $x_m = 1$, thus with the parameters in the orange region and red region, $x_m = 1$. When in the parameter region of (r_w, R_τ), the $x_m > 1$ is also considered to be 1. The thermal calculation can be divided into two situations:

- (1) $x_m = 0$, for $r_w < \sqrt{\frac{3}{2} + \frac{2}{R_\tau}}$ or R_τ small enough (less than $\frac{2}{r_w^2 - 1.5}$ when $r_w^2 > 1.5$). In this situation, x_m can be omitted from the expression.
- (2) $x_m \neq 0$, for $r_w > \sqrt{\frac{3}{2} + \frac{2}{R_\tau}}$ or $R_\tau > \frac{2}{r_w^2 - 1.5}$ when $r_w^2 > 1.5$, x_m will be appearing in the temperature expressions.

To further analyze the condition in situation 2 that x_m can be set to 0, since x_m only influences the value of T_{max} and T_{osc} , we analyze T_{max} by Equation (A10) with x_m in it and

the one without x_m . Figure A3a,b displays the spatial distribution of T_{max} with the x_m of the value depending on r_w (red) and the one with $x_m = 0$ for whatever r_w (blue dash).

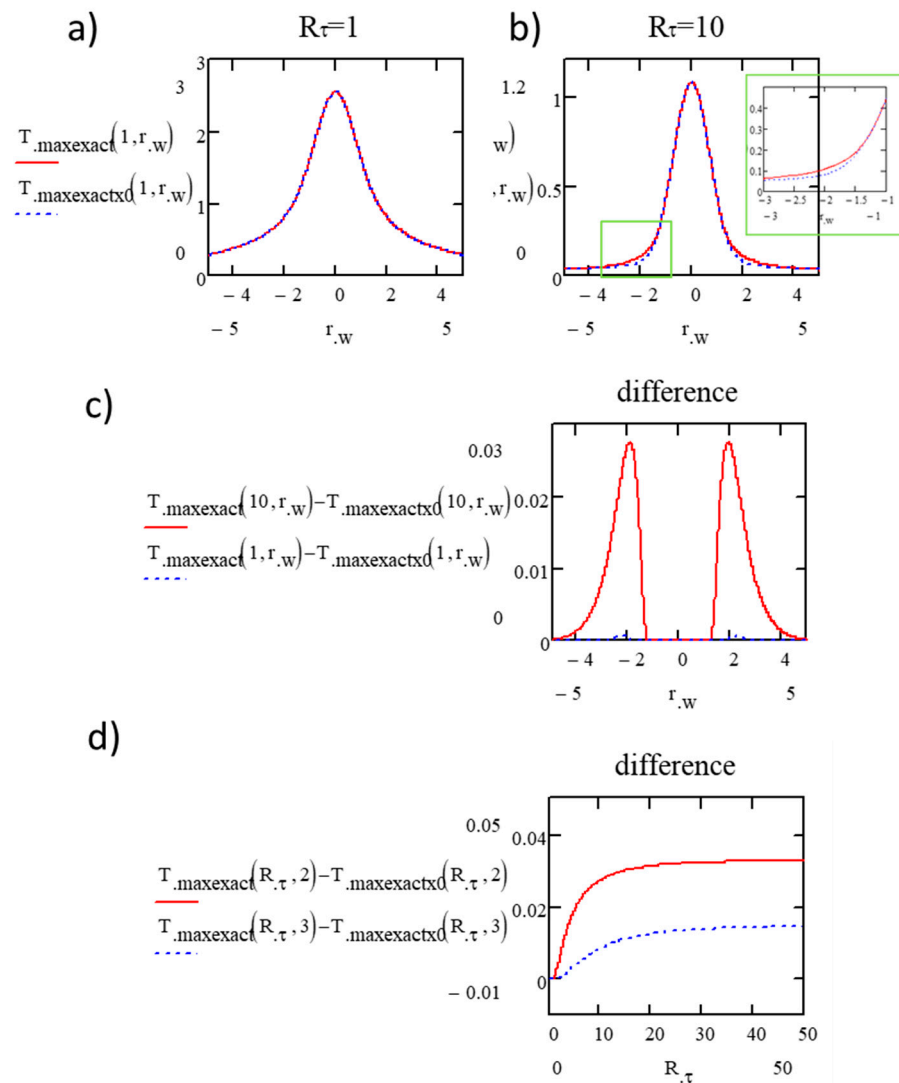


Figure A3. (a,b) Spatial distribution of T_{max} with the exact expression (x_m is a function of R_τ, r_w) and simplified expression ($x_m = 0$). (a) $R_\tau = 1$, (b) $R_\tau = 10$. (c) The differences between the two expressions of $R_\tau = 10$ (red) and 1 (blue dash). (d) The differences between these two expressions according to R_τ .

We can see from Figure A3a that when $R_\tau = 1$, the two expressions have no obvious differences, i.e., even when $x_m \neq 0$, the approximation by omitting x_m in the expression is feasible. While when $R_\tau = 10$ (Figure A3b), there are differences appearing around $r_w = 2$. The difference distribution is emphasized in Figure A3c. From it, we can see the difference appears around $r_w = 1.6$ to 4. The maximum of the difference is around $r_w = 2$. However, it can be not negligible if T_{00} is large. In addition, we observe that the difference around 2 becomes larger as R_τ increases from 1 to 10. Figure A3d shows the difference according to R_τ at $r_w = 2$ and 3. From Figure A3d, the differences seem to have a limit which is less than 0.04. Therefore, using the expressions of situation 1 to approximately simulate situation 2, i.e., always $x_m = 0$ is feasible practically, only to have a lower T_{max} and smaller T_{osc} around $r_w = 2$, the error will be less than $0.04 T_{00}$.

Why is the largest difference at $r_w = 2$? That is because when r_w is small enough, x_m is 0; while when r_w is very large, the temperature is quickly decreasing, not mentioning

the case when R_τ is large. Therefore, $r_w = 2$ is the middle value that is not small enough to cross the $x_m = 0$ boundary, and not so far away to have a low temperature.

For calculating the analytical expression of the amplitude of temperature, T_{osc} at $r > 0$, due to a non-zero x_m value, the parts in the summation of T_{max} at this point can no longer be eliminated with the parts of T_{min} , except in situation 1. We give the analytical expression for situation 1 first, and the general expression will be presented after having given the expressions for T_{min} and T_{max} .

When $x_m = 0$, the limit of T_{osc} is described as:

$$T_{osc}(r, N) = T_{max}(r, N) - T_{min}(r, N) = \exp[-(r_w)^2] - \frac{\exp\left[-\frac{(r_w)^2}{1+N \cdot R_\tau}\right]}{(1+N \cdot R_\tau)^{\frac{3}{2}}} \xrightarrow{N \gg 1/R_\tau} \exp[-(r_w)^2] \quad (A12)$$

The amplitude of the oscillations appears to be $T_{00} \cdot \exp[-(r_w)^2]$.

For T_{min} and T_{max} , using the trapezoidal rule for approximation as for $r_w \neq 0$, we have T_{min} from Equation (A9):

$$T_{min}(r_w, N) \approx \frac{1}{2} \left[\frac{\exp\left[-\frac{(r_w)^2}{1+R_\tau}\right]}{(1+R_\tau)^{3/2}} + \frac{\exp\left[-\frac{(r_w)^2}{1+N \cdot R_\tau}\right]}{(1+N \cdot R_\tau)^{3/2}} \right] + \frac{\sqrt{\pi}}{R_\tau \cdot r_w} \left[\operatorname{erf}\left(\frac{r_w}{\sqrt{1+R_\tau}}\right) - \operatorname{erf}\left(\frac{r_w}{\sqrt{1+N \cdot R_\tau}}\right) \right] \quad (A13)$$

$$\xrightarrow{N \gg 1/R_\tau} \frac{\exp\left[-\frac{(r_w)^2}{1+R_\tau}\right]}{2(1+R_\tau)^{3/2}} + \frac{\sqrt{\pi}}{R_\tau \cdot r_w} \operatorname{erf}\left(\frac{r_w}{\sqrt{1+R_\tau}}\right) \quad (A14)$$

We call $\frac{\exp\left[-\frac{(r_w)^2}{1+R_\tau}\right]}{2(1+R_\tau)^{3/2}}$ part 1, and $\frac{\sqrt{\pi}}{R_\tau \cdot r_w} \operatorname{erf}\left(\frac{r_w}{\sqrt{1+R_\tau}}\right)$ part 2.

Furthermore, T_{max} from Equation (A10):

$$T_{max}(r_w, N, x_m) \approx \frac{\exp\left[-\frac{(r_w)^2}{1+x_m \cdot R_\tau}\right]}{[1+x_m \cdot R_\tau]^{\frac{3}{2}}} + \frac{\exp\left[-\frac{(r_w)^2}{1+(1+x_m) \cdot R_\tau}\right]}{2[1+(1+x_m) \cdot R_\tau]^{\frac{3}{2}}} + \frac{\exp\left[-\frac{(r_w)^2}{1+(N-1+x_m) \cdot R_\tau}\right]}{2[1+(N-1+x_m) \cdot R_\tau]^{\frac{3}{2}}} + \frac{\sqrt{\pi}}{R_\tau \cdot r_w} \left\{ \operatorname{erf}\left[\frac{r_w}{\sqrt{[1+(1+x_m) \cdot R_\tau]}}\right] - \operatorname{erf}\left[\frac{r_w}{\sqrt{[1+(N-1+x_m) \cdot R_\tau]}}\right] \right\}$$

$$\xrightarrow{N \gg 1/R_\tau} \frac{\exp\left[-\frac{(r_w)^2}{1+x_m \cdot R_\tau}\right]}{[1+x_m \cdot R_\tau]^{\frac{3}{2}}} + \frac{\exp\left[-\frac{(r_w)^2}{1+(1+x_m) \cdot R_\tau}\right]}{2[1+(1+x_m) \cdot R_\tau]^{\frac{3}{2}}} + \frac{\sqrt{\pi}}{R_\tau \cdot r_w} \left\{ \operatorname{erf}\left[\frac{r_w}{\sqrt{[1+(1+x_m) \cdot R_\tau]}}\right] \right\} \quad (A15)$$

$\frac{\exp\left[-\frac{(r_w)^2}{1+x_m \cdot R_\tau}\right]}{[1+x_m \cdot R_\tau]^{\frac{3}{2}}}$, $\frac{\exp\left[-\frac{(r_w)^2}{1+(1+x_m) \cdot R_\tau}\right]}{2[1+(1+x_m) \cdot R_\tau]^{\frac{3}{2}}}$, $\frac{\sqrt{\pi}}{R_\tau \cdot r_w} \left\{ \operatorname{erf}\left[\frac{r_w}{\sqrt{[1+(1+x_m) \cdot R_\tau]}}\right] \right\}$ are called part 1, 2, and 3, respectively.

The general expression of T_{osc} (when N tends to infinity or larger than the effective number) is given as Equations (A14) and (A15), and it reads:

$$T_{osc}(R_\tau, r_w) = \frac{\exp\left[-\frac{(r_w)^2}{1+x_m \cdot R_\tau}\right]}{[1+x_m \cdot R_\tau]^{\frac{3}{2}}} + \frac{\exp\left[-\frac{(r_w)^2}{1+(1+x_m) \cdot R_\tau}\right]}{2[1+(1+x_m) \cdot R_\tau]^{\frac{3}{2}}} + \frac{\sqrt{\pi}}{R_\tau \cdot r_w} \left\{ \operatorname{erf}\left[\frac{r_w}{\sqrt{[1+(1+x_m) \cdot R_\tau]}}\right] \right\} - \frac{\exp\left[-\frac{(r_w)^2}{1+R_\tau}\right]}{2(1+R_\tau)^{\frac{3}{2}}} - \frac{\sqrt{\pi}}{R_\tau \cdot r_w} \operatorname{erf}\left(\frac{r_w}{\sqrt{1+R_\tau}}\right) \quad (A16)$$

Part 1 in Equation (A14) and part 2 in Equation (A15) (i.e., $\frac{\exp\left[-\frac{(r_w)^2}{1+(1+x_m) \cdot R_\tau}\right]}{2[1+(1+x_m) \cdot R_\tau]^{\frac{3}{2}}}$ and $\frac{\exp\left[-\frac{(r_w)^2}{1+R_\tau}\right]}{2(1+R_\tau)^{\frac{3}{2}}}$) are smaller than the other parts by a factor of 10, so they can be approximately omitted to simplify the expressions in practice. Then, we obtain:

$$T_{osc}(R_\tau, r_w) \approx \frac{\exp\left[-\frac{(r_w)^2}{1+x_m \cdot R_\tau}\right]}{[1+x_m \cdot R_\tau]^{\frac{3}{2}}} + \frac{\sqrt{\pi}}{R_\tau \cdot r_w} \left\{ \operatorname{erf}\left[\frac{r_w}{\sqrt{[1+(1+x_m) \cdot R_\tau]}}\right] \right\} - \frac{\sqrt{\pi}}{R_\tau \cdot r_w} \operatorname{erf}\left(\frac{r_w}{\sqrt{1+R_\tau}}\right) \quad (A17)$$

The plots in Figure A4a are T_{osc} according to r_w at $R_\tau = 0.1, 1,$ and 10 , accompanied with $\exp[-(r_w)^2]$ (the result of situation 1) for comparison, while the distribution difference between the exact and the approximation is shown in Figure A4b. It is the same as the difference for T_{max} as in Figure A3c. It is also plotted according to R_τ , with $r_w = 2$ and 3 , accompanied with $\exp[-(2)^2]$ and $\exp[-(3)^2]$.

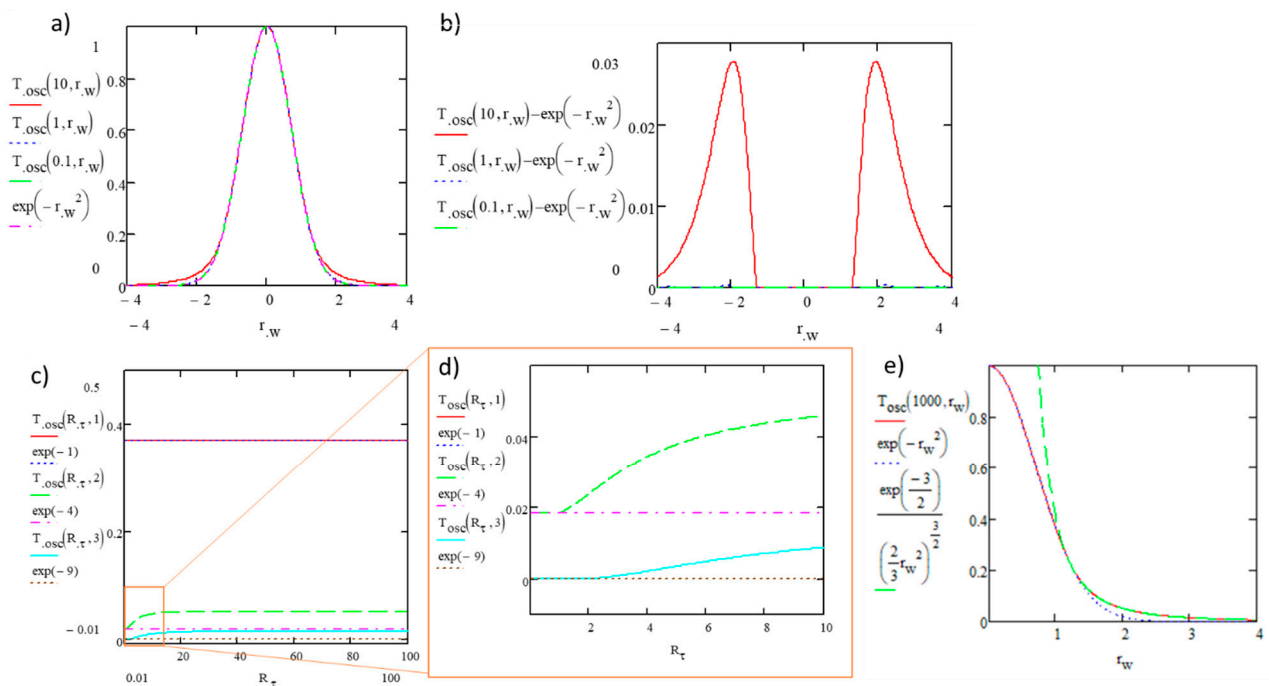


Figure A4. (a) Spatial distribution of T_{osc} with the real expression (x_m is a function of R_τ, r_w) when $R_\tau = 10, 1,$ and 0.1 , and the reduced expression ($x_m = 0$) in the pink dash. (b) The differences between the two expressions according to r_w . (c) T_{osc} with the real expression (x_m is a function of R_τ, r_w), and the reduced expression ($x_m = 0$) according to R_τ at $r_w = 1, 2, 3$. (d) A zoom of R_τ from 0 to 10. (e) T_{osc} distribution when $R_\tau = 1000$ (red), comparing with Tosc in situation 1 (blue dash) and the maximum T_{osc} value when $R_\tau \rightarrow \infty$ according to r_w (green).

Similarly to T_{max} , we note that from Figure A4a, when R_τ increases, attributed to the non-zero value of x_m , compared to situation 1 ($x_m = 0$), the oscillation amplitude has only

a small increase around $r_w = 2$ which is sometimes not negligible. The R_τ dependence is shown in Figure A4c,d, and we note that in Figure A4c, the oscillation amplitude at $r_w = 2$ (green dash) and $r_w = 1$ (cyan) increases when R_τ increases, until it reaches a limit. These limits are calculated to be $\frac{\exp\left[-\frac{3}{2}\right]}{\left[\frac{2}{3}(r_w)^2\right]^{3/2}}$ when $R_\tau \rightarrow \infty$ (from Equation (A11), $x_m \cdot R_\tau \xrightarrow{R_\tau \rightarrow \infty} \frac{2}{3}(r_w)^2 - 1$). Figure A4e shows this limit value according to r_w around $r_w = 2$. Therefore, the range of T_{osc} is given by Equations (A18) and (A19):

$$T_{osc}(R_\tau, r_w) \xrightarrow{x_m = 0 \text{ and in particular when } R_\tau \rightarrow 0 \text{ whatever } r_w} \exp[-(r_w)^2] \quad (\text{A18})$$

$$T_{osc}(R_\tau, r_w) \xrightarrow{R_\tau \rightarrow \infty \text{ and } r_w \text{ around } 2} \frac{1}{2.44(r_w)^3} \quad (\text{A19})$$

We note that the oscillation amplitude T_{osc} at situation 1 is $\exp[-(r_w)^2]$ which is the minimum, while in situation 2, the amplitude is larger due to the influence of x_m , with a maximum value of $\frac{1}{2.44(r_w)^3}$ at a place around $r_w = 2$. Therefore, in practice and for accuracy, consistent with Figure A4e, when $r_w < 1.2$ or R_τ is small, we can apply Equation (A18). Furthermore, when $r_w > 1.2$ or R_τ is large, Equation (A19) can be applied for T_{osc} . Even though, by using situation 1 for all the situations, the error will be less than the limits shown in Figure A4c.

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