# Two-sided Matrix Regression 

Nayel Bettache, Cristina Butucea

## To cite this version:

Nayel Bettache, Cristina Butucea. Two-sided Matrix Regression. 2024. hal-04419650

HAL Id: hal-04419650

## https://hal.science/hal-04419650

Preprint submitted on 26 Jan 2024

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire HAL, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

# Two-sided Matrix Regression 

Nayel Bettache ${ }^{1}$ and Cristina Butucea ${ }^{1}$<br>${ }^{1}$ CREST, ENSAE, Institut Polytechnique de Paris, 5 avenue Henry Le Chatelier, 91120 Palaiseau, France

March 9, 2023


#### Abstract

The two-sided matrix regression model $Y=A^{*} X B^{*}+E$ aims at predicting $Y$ by taking into account both linear links between column features of $X$, via the unknown matrix $B^{*}$, and also among the row features of $X$, via the matrix $A^{*}$. We propose lowrank predictors in this high-dimensional matrix regression model via rank-penalized and nuclear norm-penalized least squares. Both criteria are non jointly convex; however, we propose explicit predictors based on SVD and show optimal prediction bounds. We give sufficient conditions for consistent rank selector. We also propose a fully data-driven rank-adaptive procedure. Simulation results confirm the good prediction and the rankconsistency results under data-driven explicit choices of the tuning parameters and the scaling parameter of the noise.


Key Words: Matrix regression, Multivariate response regression, Nuclear norm penalized, Oracle inequality, Rank penalized, Rank selection, Two-sided matrix regression.

## 1 Introduction

Supervised learning is often performed on large data bases. Matrix regression assumes that the data $Y$ can be well explained by a set of features given by the columns of the matrix $X$ and linear combinations of these columns. It is often the case in real-life that the rows of $Y$ can be explained by linear combinations of the rows of $X$.

For example, economic data store economic indicators as column features and countries as rows. Such a matrix is usually explained by a smaller matrix roughly containing a smaller number of countries (representatives of groups of geographically or economically close countries) and a few economic features or some factors produced out of all these indicators. We would like to predict a larger number of indicators for a larger number of countries, i.e. Y a $n \times p$ matrix, using the features $X$ a $m \times q$ matrix.
Recommendation systems want to predict the opinion of $n$ clients concerning $p$ items. We can use publicly available data on a number $m$ of different groups of clients and their affinity to a number $q$ of large categories of items in order to predict by evaluating the client's
correlation to the prescribed groups in the population and the item's weight in its category. We may include a multiple-label situation where the items belonging to a main category are also related to other categories.
Other examples can be given for meteorological data, medical or pharmaceutical data and so on.

Model. We observe the matrix $Y \in \mathbb{R}^{n \times p}$ and a design matrix $X \in \mathbb{R}^{m \times q}$ related via the two-sided matrix regression (2MR) model involving two parameter matrices $A^{*} \in \mathbb{R}^{n \times m}$ and $B^{*} \in \mathbb{R}^{q \times p}$ :

$$
\begin{equation*}
Y=A^{*} X B^{*}+E, \tag{1}
\end{equation*}
$$

where the noise matrix $E$ is assumed to have independent centered $\sigma$-sub-Gaussian entries.
The 2MR model encompasses known models like, e.g. matrix regression and matrix factorisation. Indeed, if $n=m$ and $A^{*}$ is the identity, the matrix model (1) becomes the (one-sided) matrix regression (MR) model $Y=X B^{*}+E$, see [18], [5], [17].
Assume now that $m=q$ and that the design matrix $X$ is the identity matrix of rank $m$ smaller than both $n$ and $p$. Our model becomes a factorisation model of the signal $M^{*}=A^{*} B^{*}$ observed with noise. The idea is to recover a low-rank structure generating the observed data. In 12 the authors have considered structured factorisation of the signal under assumptions that the rows of $A^{*}$ and the columns of $B^{*}$ have a common sparsity parameter and $X$, which they do not observe, has a much smaller dimension than $Y$.

The 2 MR model (1) is strongly related to other models, but we argue that it cannot be reduced to these other models of a different nature. Indeed, note that the entry $Y_{i j}$ of the matrix $Y$ can be written

$$
Y_{i j}=\operatorname{Tr}\left(X \cdot B_{\cdot, j}^{*} A_{i, \cdot}^{*}\right)+E_{i j},
$$

for any $i$ in $[n]$, where $[n]=\{1, \ldots, n\}$, and for any $j$ in $[p]$. Thus every entry $Y_{i j}$ brings information through the same design matrix $X$ on the rank 1 matrix $B_{\cdot, j}^{*} A_{i, .}^{*}$. This is unlike the trace-regression model or the more general matrix completion studied by [19], [14], where a different design matrix brings information on the parameter matrix $B^{*} A^{*}$.
Another way of writing model (1) is in the form of vector regression model, by stacking the columns of matrices $Y, X$ and $E$ into $\operatorname{vec}(Y), \operatorname{vec}(X)$ and $\operatorname{vec}(E)$, respectively, to get

$$
\begin{equation*}
\operatorname{vec}(Y)^{\top}=\operatorname{vec}(X)^{\top} \cdot A^{\top} \otimes B+\operatorname{vec}(E)^{\top} \tag{2}
\end{equation*}
$$

where $\otimes$ denotes the tensor product of two matrices. Under this relation, we predict a row vector of size $n p$ using a row vector of size $m q$ (the matrix of features has rank 1) via a parameter of size $(m q) \times(n p)$ which cannot go well unless the structure of $A$ and $B$ is trivial. This approach cannot take into account the matrix structure of the features, of the matrices $A^{*}, B^{*}$, and it gives poor results on that account.

This model has been introduced in time series by [6] as the auto-regressive matrix-valued model of order 1, MAR(1), $Y_{t}=A^{*} Y_{t-1} B^{*}+E_{t}$, observed at times $t$ in $[T]$. In this case $A^{*}$ and $B^{*}$ are squared matrices with spectral radii strictly less than 1 in order to ensure stability of the time series ( $X_{t}$ is thus stationary and causal). The authors propose three estimation methods: first, they use the vector form analogous to (2), stack the $T$ lines of $\operatorname{vec}\left(Y_{t}\right)^{\top}$ and
they use the nearest Kronecker product (NKP) problem to give estimators of $A^{*}$ and $B^{*}$ out of the global least squares estimator of $A^{* \top} \otimes B^{*}$; then, their next method minimizes the least squares over $A$ and $B$

$$
\min _{A, B} \frac{1}{T} \sum_{t=1}^{T}\left\|Y_{t}-A Y_{t-1} B\right\|_{F}^{2}
$$

by a sequential procedure minimizing over $A$ for fixed given $B$, then over $B$ for fixed $A$, and iterating; finally, they give an MLE procedure over $A$ and $B$ under a particular structure of the covariance matrix of $E$ and proceed also sequentially. Theoretical results state the asymptotic normality as $T$ tends to infinity, for fixed dimensions. However, the first procedure is cumbersome as the estimated matrix is very large, while the other two procedures are based on non-convex minimization without theoretical guarantees as to the limit points of the algorithm.
Least squares and MLE estimators with AIC and BIC penalties have been numerically studied by [10] of a more general time series model

$$
Y_{t}=\sum_{\ell=1}^{L} A_{\ell} Y_{t-\ell} B_{\ell}+E_{t}, \quad t=1, \ldots, T
$$

which is treated as $Y_{t}=A^{*} X_{t} B^{*}+E_{t}$, where $X_{t}$ is the block diagonal matrix containing the $L$-past observed matrices $Y_{t-1}, \ldots, Y_{t-L}$ and $A^{*}=\left(A_{1}, \ldots, A_{L}\right)$ and $B^{*}=\left(B_{1}^{\top}, \ldots, B_{L}^{\top}\right)^{\top}$ are the concatenated matrices in the previous equation.
Thus, our paper is motivated by the need to deal with high-dimensional data and finite (non-asymptotic) time (say $T=1$ ) in order to provide theoretical guarantees for prediction.

Contributions. We show in Section 2 that by using the SVD of matrices $Y=U_{Y} \Sigma_{Y} V_{Y}^{T}$ and $X=U_{X} \Sigma_{X} V_{X}^{T}$, the least squares procedure can be reduced to fitting predictors of the form $A_{0} \Sigma_{X} B_{0}$ to the diagonal matrix $\Sigma_{Y}$ with explicit relations between $A_{0}, B_{0}$ and $A, B$. There is a natural choice of predictors of $A_{0}$ and of $B_{0}$ under diagonal form. We study these predictors for given ranks $r$ and that we transform back into the original space of $Y$ without loss of prediction rate. Then we give a data-dependent rank selector and show that the predictors associated to it attain optimal bounds. We give sufficient conditions so that the rank selector is consistent. Finally, we slightly modify the procedure to be free of the parameter $\sigma$ of the noise and show new upper bounds in this case. In Section 3, we study the nuclear norm penalized least squares and show it attains the optimal bounds too. All proofs are in a dedicated section in the Appendix. Finally, we illustrate in Section 4 via numerical simulations the excellent prediction results of these fast running, explicit predictors.

Notations. For any integers $n$ and $m$ we denote $n \wedge m$ for the minimum between $n$ and $m$ and $n \vee m$ for the maximum between $n$ and $m$. For any matrix $M$ of size $n \times m$ and rank $r_{M}$, we denote its singular value decomposition (SVD) by $M=U_{M} \Sigma_{M} V_{M}^{\top}$, where $U_{M}$ belongs to $\mathcal{O}_{n}$ - the set of orthogonal matrices of size $n \times n, V_{M}$ belongs to $\mathcal{O}_{m}$ and

$$
\Sigma_{M}=\operatorname{Diag}_{n, m}\left(\sigma_{k}(M), 1 \leq k \leq r_{M}\right)
$$

Note that $\sigma_{1}(M), \ldots, \sigma_{r_{M}}(M)$ are the positive singular values of $M$ listed in decreasing order, and the $n \times m$ diagonal matrix $\operatorname{Diag}_{n, m}\left(\sigma_{k}(M), 1 \leq k \leq r_{M}\right)$ has diagonal entries in the list
and 0 elsewhere. Furthermore, denote $\|M\|_{F}^{2}=\sum_{k=1}^{n \wedge m} \sigma_{k}(M)^{2}$ its Frobenius norm, $\|M\|_{(2, q)}^{2}=$ $\sum_{k=1}^{q} \sigma_{k}(M)^{2}$ its Ky-Fan $(2, q)$ norm, $\|M\|_{o p}=\sigma_{1}(M)$ its operator norm, $\|M\|_{*}=\sum_{k=1}^{n \wedge m} \sigma_{k}(M)$ its nuclear norm, $M^{\dagger}$ its Moore-Penrose inverse, $r_{M}$ its rank and $M^{T}$ its transpose. For any matrices $M_{1}$ and $M_{2}$ in $\mathbb{R}^{n \times m},\left\langle M_{1}, M_{2}\right\rangle_{F}$ denotes the canonical scalar product, i.e. $\left\langle M_{1}, M_{2}\right\rangle_{F}=\operatorname{Tr}\left(M_{1}^{T} M_{2}\right)$. For any $r \in\left[r_{M}\right]$, we denote $[M]_{r}$ the best rank $r$ approximation of $M$ for the Frobenius norm. In the model (1), let us denote by $r^{*}$ the rank of $A^{*} X B^{*}$.

## 2 Rank penalized learning

In this section we propose rank adaptive predictors and provide theoretical guarantees for their error. First we give explicit predictors under the assumption that the ranks of the parameter matrices are known, then a selection procedure will allow to provide a datadependent rank selector and the associated rank-adaptive predictor. Even though we follow classical results for rank penalized (one-sided) matrix regression, e.g. [5], 9] and [3], we give details for the fixed rank two-sided matrix regression which is novel to the best of our knowledge. Surprisingly, explicit predictors can be proposed despite the identifiability issues of this model. Only after this, we proceed to rank selection and rank-adaptive learning.

### 2.1 Prediction for given ranks

Let $r$ belong to $\left[n \wedge p \wedge r_{X}\right]$. Let us build explicit predictors ( $\hat{A}_{r}, \hat{B}_{r}$ ) solutions to the nonconvex minimization problem

$$
\begin{equation*}
\min _{\substack{A, B: \\ A \wedge \operatorname{rank} B \leq r}}\|Y-A X B\|_{F}^{2} . \tag{3}
\end{equation*}
$$

Notice that the rank constraints on $A$ and $B$ use the same value $r$. Indeed the objective is to build a predictor for the signal $A^{*} X B^{*}$ which satisfies $\operatorname{rank}\left(A^{*} X B^{*}\right) \leq \min \left(r_{A^{*}}, r_{X}, r_{B^{*}}\right)$. In the steps of the proof of our results, we see that the upper bound of the risk depends on the ranks of $A^{*}$ and of $B^{*}$ only through their least value and no information can be recovered on the largest rank of the two. Hence it makes sense to look for $A$ and $B$ sharing the same rank as a dimension reduction technique without any impact on the final results.

The model (1) can be rewritten using the SVD of the observed matrix $Y$ and of the design matrix $X$ as

$$
\begin{equation*}
\Sigma_{Y}=A_{0}^{*} \cdot \Sigma_{X} \cdot B_{0}^{*}+E_{0}, \tag{4}
\end{equation*}
$$

where $A_{0}^{*}=U_{Y}^{T} A^{*} U_{X}, B_{0}^{*}=V_{X}^{T} B^{*} V_{Y}$ and $E_{0}:=U_{Y}^{T} \cdot E \cdot V_{Y}$. In the particular case where $E$ has independent entries with distribution $\mathcal{N}\left(0, \sigma^{2}\right)$ than so does $E_{0}$, see Lemma 5.1. Now, $\Sigma_{Y}$ and $\Sigma_{X}$ are diagonal matrices, not necessarily squared, not necessarily full rank. Given the invariance of the Frobenius norm by left or right multiplication with orthogonal matrices, we get that for any matrices $A \in \mathbb{R}^{n \times m}$ and $B \in \mathbb{R}^{q \times p}$ we have

$$
\|Y-A X B\|_{F}^{2}=\left\|\Sigma_{Y}-A_{0} \Sigma_{X} B_{0}\right\|_{F}^{2}
$$

where $A_{0}=U_{Y}^{T} A U_{X}$ and $B_{0}=V_{X}^{\top} B V_{Y}$ are obtained via analogous transformations to those relating the true underlying parameters.

Obviously, matrices $A$ and $A_{0}$ have the same rank, and the same holds for $B$ and $B_{0}$. Therefore, solving (3) is equivalent to solving for $\hat{A}_{0 r}$ and $\hat{B}_{0 r}$ solutions of

$$
\begin{equation*}
\min _{\substack{A_{0}, B_{0}: \\ \operatorname{rank} A_{0} \wedge \operatorname{rank} B_{0} \leq r}}\left\|\Sigma_{Y}-A_{0} \Sigma_{X} B_{0}\right\|_{F}^{2} \tag{5}
\end{equation*}
$$

Theorem 2.1 Let us define for $r \in\left[n \wedge p \wedge r_{X}\right]$

$$
\begin{equation*}
\hat{A}_{0 r}=\operatorname{Diag}_{n, m}\left(\sigma_{k}(Y), 1 \leq k \leq r \wedge r_{Y}\right) \quad \text { and } \quad \hat{B}_{0 r}=\operatorname{Diag}_{q, p}\left(\sigma_{k}(X)^{-1}, 1 \leq k \leq r\right) \tag{6}
\end{equation*}
$$

Then, $\left(\hat{A}_{0 r}, \hat{B}_{0 r}\right)$ belong to the set of solutions of problem (5) and the predictor $\hat{A}_{0 r} \Sigma_{X} \hat{B}_{0 r}$ satisfies for an absolute constant $C>0$ and for any $t>0$, the oracle inequality

$$
\begin{aligned}
&\left\|A_{0}^{*} \Sigma_{X} B_{0}^{*}-\hat{A}_{0 r} \Sigma_{X} \hat{B}_{0 r}\right\|_{F}^{2} \leq 9 \inf _{\substack{A_{0}, B_{0}: \\
\operatorname{rank} A_{0} \wedge \operatorname{rank} B_{0} \leq r}}\left\|A_{0}^{*} \Sigma_{X} B_{0}^{*}-A_{0} \Sigma_{X} B_{0}\right\|_{F}^{2} \\
&+24 C \sigma^{2}(1+t)^{2} \cdot r(n+p)
\end{aligned}
$$

with probability larger than $1-2 \exp \left(-t^{2}(\sqrt{n}+\sqrt{p})^{2}\right)$.
Next, from the explicit solutions $\left(\hat{A}_{0 r}, \hat{B}_{0 r}\right)$ of (5) we deduce explicit solutions of (3).
Corollary 2.2 Let us define for $r \in\left[n \wedge p \wedge r_{X}\right]$

$$
\begin{equation*}
\hat{A}_{r}=U_{Y} \hat{A}_{0 r} U_{X}^{T} \quad \text { and } \quad \hat{B}_{r}=V_{X} \hat{B}_{0 r} V_{Y}^{T} \tag{7}
\end{equation*}
$$

with $\hat{A}_{0 r}$ and $\hat{B}_{0 r}$ defined in (6). Then $\left(\hat{A}_{r}, \hat{B}_{r}\right)$ are solution to the problem (3) and the predictor $\hat{A}_{r} X \hat{B}_{r}$ satisfies for an absolute constant $C>0$ and for any $t>0$, the oracle inequality

$$
\left\|A^{*} X B^{*}-\hat{A}_{r} X \hat{B}_{r}\right\|_{F}^{2} \leq 9 \inf _{\substack{A, B: \\ \operatorname{rank} A \wedge \operatorname{rank} B \leq r}}\left\|A^{*} X B^{*}-A X B\right\|_{F}^{2}+24 C \sigma^{2}(1+t)^{2} \cdot r(n+p)
$$

with probability larger than $1-2 \exp \left(-t^{2}(\sqrt{n}+\sqrt{p})^{2}\right)$.
The proofs of Theorem 2.1 and of Corollary 2.2 can be found in Section 5 . In the proofs we explicit the bias in terms of the unknown matrix parameters:

$$
\inf _{\substack{A, B: \\ \operatorname{rank} A \wedge \operatorname{rank} B \leq r}}\left\|A^{*} X B^{*}-A X B\right\|_{F}^{2}=\sum_{k=r+1}^{r^{*}} \sigma_{k}\left(A^{*} X B^{*}\right)^{2} \cdot \mathbf{1}_{r<r^{*}}
$$

Note that our choice for the couple of predictors $\left(\hat{A}_{0 r}, \hat{B}_{0 r}\right)$ is not unique and we can easily derive families of solutions to the problem (5). Each family of solutions can be turned
into a solution to the problem (3). Indeed, consider $\left(\alpha \hat{A}_{0 r}, \frac{1}{\alpha} \hat{B}_{0_{r}}\right)$ with arbitrary $\alpha>0$. Alternatively, let $\lambda_{i}$ for all $i \leq m \wedge q$ be arbitrary positive numbers, then

$$
\left(\hat{A}_{0 r} \operatorname{Diag}_{m, m}\left(\lambda_{1}, \ldots, \lambda_{m \wedge q}\right), \operatorname{Diag}_{q, q}\left(\lambda_{1}^{-1}, \ldots, \lambda_{m \wedge q}^{-1}\right) \hat{B}_{0 r}\right)
$$

give the same prediction. Let us see that the same transformations applied to the parameter matrices $A_{0}^{*}$ and $B_{0}^{*}$ also lead to the same signal matrix $A_{0}^{*} \Sigma_{X} B_{0}^{*}$. Indeed, the model is non-identifiable and so, without further strong assumptions, we can only hope to learn the global signal, and not the parameters of the model.

Alternative predictors. Let us define a second couple of predictors ( $\tilde{A}, \tilde{B}_{r}$ ) producing exactly the same prediction as ( $\hat{A}_{r}, \hat{B}_{r}$ ) with the same theoretical properties, but having the advantage that $\tilde{A}$ is full rank and does not depend on $r$. Define

$$
\tilde{A}_{0}=I_{n, m} \quad \text { and } \quad \tilde{B}_{0 r}=\operatorname{Diag}_{q, p}\left(\frac{\sigma_{k}(Y)}{\sigma_{k}(X)}, 1 \leq k \leq r \wedge r_{Y}\right)
$$

where $I_{n, m}$ denotes the identity matrix of dimension $n \times m$, whereas $\tilde{B}_{0 r}$ has rank $r \wedge r_{Y}$. Using the analogous transformations we obtain

$$
\tilde{A}=U_{Y} I_{n, m} U_{X}^{T} \quad \text { and } \quad \tilde{B}_{r}=V_{X} \tilde{B}_{0 r} V_{Y}^{T} .
$$

It is easy to see that Theorem 2.1 is valid for $\tilde{A}_{0}$ and $\tilde{B}_{0 r}$, and that Corollary 2.2 is valid for $\tilde{A}$ and $\tilde{B}_{r}$.

### 2.2 Rank-adaptive prediction

In this section, we propose rank-adaptive predictors ( $\hat{A}_{\hat{r}}, \hat{B}_{\hat{r}}$ ) which are selected from the family $\left\{\left(\hat{A}_{r}, \hat{B}_{r}\right): r \in\left[n \wedge p \wedge r_{X}\right]\right\}$ by a model selection procedure analogous to that of [5]. Let us first define, for a generic matrix $M$ and any $\lambda>0$, the $\lambda-\mathrm{rank}$ of $M$ as

$$
r_{M}(\lambda)=1 \vee \sum_{k=1}^{\operatorname{rank} M} \mathbf{1}_{\sigma_{k}(M)^{2} \geq \lambda} .
$$

For given $\lambda>0$, let

$$
\begin{equation*}
\hat{r}:=\arg \min _{r \in\left[n \wedge p \wedge r_{X}\right]}\left\{\left\|Y-\hat{A}_{r} X \hat{B}_{r}\right\|_{F}^{2}+\lambda r\right\} . \tag{8}
\end{equation*}
$$

Consider the predictors introduced in (7) for the data-driven rank $\hat{r}$ as defined in (8). The next Theorem extends the oracle inequality to the rank-adaptive predictors ( $\hat{A}_{\hat{r}}, \hat{B}_{\hat{r}}$ ) associated to the estimated rank $\hat{r}$ and to some $\lambda>0$ large enough.
Theorem 2.3 The rank-adaptive predictors $\left(\hat{A}_{\hat{r}}, \hat{B}_{\hat{r}}\right)$ associated to $\hat{r}$ in (8) and to $\lambda$ such that, for some absolute constant $C>0$ and for any $t>0, \lambda \geq 4 C(1+t)^{2} \sigma^{2}(n+p)$, satisfy the oracle inequality

$$
\left\|A^{*} X B^{*}-\hat{A}_{\hat{r}} X \hat{B}_{\hat{r}}\right\|_{F}^{2} \leq \min _{r \in\left[n \wedge p \wedge r_{X}\right]}\left\{9 \sum_{k=r+1}^{r^{*}} \sigma_{k}\left(A^{*} X B^{*}\right)^{2} \cdot \mathbf{1}_{r<r^{*}}+6 \lambda r\right\}
$$

with probability larger than $1-2 \exp \left(-t^{2}(\sqrt{n}+\sqrt{p})^{2}\right)$.

Note that the minimum on the right-hand side of the previous display is always smaller than the value at $r=r^{*}$, giving under the assumptions of Theorem 2.3 that

$$
\left\|A^{*} X B^{*}-\hat{A}_{\hat{r}} X \hat{B}_{\hat{r}}\right\|_{F}^{2} \leq 6 r^{*} \lambda,
$$

with probability larger than $1-2 \exp \left(-t^{2}(\sqrt{n}+\sqrt{p})^{2}\right)$.
The bounds of order $r^{*}(n+p)$ attained by our procedure are analogous to those for the lowrank matrix regression models in [19] and [9]. Indeed, the 2MR model is more difficult than the MR model, (i.e. one of the matrices is known) and we will suppose known the matrix with larger rank in order to achieve the correct lower bounds. Thus the lower bounds for prediction in the low-rank MR model will be valid for our model.

### 2.3 Consistent rank selection

We study the consistency of the rank selector $\hat{r}$ in (8) and see when it recovers the true rank $r^{*}$ with high probability. First, we show that, for properly chosen $\lambda$, the data-driven rank $\hat{r}$ is actually the unique solution and coincides with the $\lambda$-rank of $Y, \hat{r}=r_{Y}(\lambda)$.

Proposition 2.4 If $\lambda>\sigma_{r_{Y}}(Y)^{2}$, there is a unique solution $\hat{r}$ to the optimisation problem in (8) and it is actually the $\lambda$-rank of $Y$, i.e. $\hat{r}=r_{Y}(\lambda)$.

Next, we prove that $\hat{r}$ recovers with high probability the $\lambda-\operatorname{rank}$ of $A^{*} X B^{*}$.
Proposition 2.5 Let $\lambda>0$ and denote by $r^{*}(\lambda)$ the $\lambda-r a n k$ of $A^{*} X B^{*}$. If for some constant $c$ in $(0,1), \sigma_{r^{*}(\lambda)}\left(A^{*} X B^{*}\right)^{2}>(1+c)^{2} \lambda$ and $\sigma_{r^{*}(\lambda)+1}\left(A^{*} X B^{*}\right)^{2}<(1-c)^{2} \lambda$, then

$$
\mathbb{P}\left(\hat{r}=r^{*}(\lambda)\right) \geq \mathbb{P}\left(\|E\|_{o p}^{2} \leq c^{2} \lambda\right) .
$$

In particular, if $\lambda \geq 2 C(n+p) \sigma^{2}(1+t)^{2} / c^{2}$ for some absolute constant $C>0$ and for any $t>0$, then $\hat{r}=r^{*}(\lambda)$ with probability larger than $1-2 \exp \left(-t^{2}(\sqrt{n}+\sqrt{p})^{2}\right)$.

Finally, remember that the fact that $r^{*}(\lambda)$ coincides with the true underlying rank $r^{*}$ is equivalent to having $\sigma_{r^{*}}\left(A^{*} X B^{*}\right)^{2} \geq \lambda>0$. The rank selector will then coincide with $r^{*}$ if $\lambda$ also satisfies $\sigma_{1}(E)^{2} \leq c^{2} \lambda$, for some absolute constant $c>0$. It is therefore necessary that a signal-to-noise ratio, given here by $\sigma_{r^{*}}\left(A^{*} X B^{*}\right)^{2} / \sigma_{1}(E)^{2}$ be significant in order to have the true underlying rank selected by $\hat{r}$. By combining this with the previous Propositions we get the following.

Proposition 2.6 Let $\lambda>0$. If for some constant $c$ in $(0,1), \sigma_{r^{*}}\left(A^{*} X B^{*}\right)^{2}>(1+c)^{2} \lambda$, then

$$
\mathbb{P}\left(\hat{r}=r^{*}\right) \geq \mathbb{P}\left(\|E\|_{o p}^{2} \leq c^{2} \lambda\right) .
$$

In particular, if $\lambda \geq 2 C(n+p) \sigma^{2}(1+t)^{2} / c^{2}$ for some absolute constant $C>0$ and for any $t>0$, then $\hat{r}=r^{*}$ with probability larger than $1-2 \exp \left(-t^{2}(\sqrt{n}+\sqrt{p})^{2}\right)$.

### 2.4 Data-driven rank-adaptive prediction

The rank selector $\hat{r}$ in (8) is used for building consistent predictors as detailed in Theorem 2.3 provided that the condition $\lambda \geq 4 C(1+t)^{2} \sigma^{2}(n+p)$ is satisfied. However the noise parameter $\sigma$ is not known in general settings. Thus a data dependent rank selector is needed for building consistent predictors in those cases. Motivated by the previous case where $\sigma^{2}$ was supposed known, we proceed as follows. First, we change the penalty to $\lambda \cdot r \widehat{\sigma}_{r}^{2}$ with

$$
\widehat{\sigma}_{r}^{2}=\frac{1}{n p}\left\|Y-\hat{A}_{r} X \hat{B}_{r}\right\|_{F}^{2} .
$$

Note that in the particular case of Gaussian noise $\widehat{\sigma}_{r}^{2}$ estimates the variance $\sigma^{2}$ of the noise. Next, given a largest possible value for the true rank $r_{\max } \leq n \wedge p \wedge r_{X}$, we define the data-driven rank selector

$$
\begin{equation*}
\bar{r}:=\arg \min _{r \in\left[r_{m a x}\right]}\left\{\left\|Y-\hat{A}_{r} X \hat{B}_{r}\right\|_{F}^{2}+\lambda \cdot r \widehat{\sigma}_{r}^{2}\right\} . \tag{9}
\end{equation*}
$$

Finally, we use the predictors $\left(\hat{A}_{\bar{r}}, \hat{B}_{\bar{r}}\right)$. The next theorem extends the upper bounds of Theorem 2.3 to these data-driven rank-adaptive predictors.

Theorem 2.7 The data-driven rank-adaptive predictors ( $\hat{A}_{\bar{r}}, \hat{B}_{\bar{r}}$ ) associated to $\bar{r}$ in (9) with $r_{\max } \leq n \wedge p \wedge r_{X}$, and to $\lambda=(1+\varepsilon) n p /\left(r_{\max } \vee r_{Y}\right)$ for some $\varepsilon>0$, satisfy for some absolute constant $C>0$ and for any $t>0$ the oracle inequality

$$
\begin{aligned}
\left\|A^{*} X B^{*}-\hat{A}_{\bar{r}} X \hat{B}_{\bar{r}}\right\|_{F}^{2} \leq \min _{r \in\left[r_{\max }\right]} & \left\{9\left\|A^{*} X B^{*}-\hat{A}_{r} X \hat{B}_{r}\right\|_{F}^{2}+6(1+\varepsilon) \cdot r \sigma_{r+1}\left(A^{*} X B^{*}\right)^{2}\right\} \\
& +12 C(2+\varepsilon)(1+t)^{2} \cdot \sigma^{2} r_{\max }(n+p),
\end{aligned}
$$

with probability larger than $1-2 \exp \left(-t^{2}(\sqrt{n}+\sqrt{p})^{2}\right)$.
Apply the Corollary 2.2, to get under the assumptions of Theorem 2.7 that

$$
\begin{aligned}
\left\|A^{*} X B^{*}-\hat{A}_{\bar{r}} X \hat{B}_{\bar{r}}\right\|_{F}^{2} \leq \min _{r \in\left[r_{\text {max }}\right]} & \left\{9^{2} \inf _{\substack{A, B: \\
r_{A} \wedge_{B} \leq r}}\left\|A^{*} X B^{*}-A_{r} X B_{r}\right\|_{F}^{2}+6(1+\varepsilon) \cdot r \sigma_{r+1}\left(A^{*} X B^{*}\right)^{2}\right\} \\
& +12(20+\varepsilon) C(1+t)^{2} \cdot \sigma^{2} r_{\max }(n+p)
\end{aligned}
$$

with probability larger than $1-2 \exp \left(-t^{2}(\sqrt{n}+\sqrt{p})^{2}\right)$.
Note that the minimum on the right-hand side of the previous display is always smaller than its value at $r=r^{*}$ if $r_{\max }$ is larger than $r^{*}$, giving under the assumptions of Theorem 2.7 that

$$
\left\|A^{*} X B^{*}-\hat{A}_{\bar{r}} X \hat{B}_{\bar{r}}\right\|_{F}^{2} \leq 12(20+\varepsilon) C(1+t)^{2} \cdot \sigma^{2} r_{\max }(n+p) .
$$

In order to compare to the previous results, note that the upper bound derived from Theorem 2.3 for the value $r=r^{*}$ and the least value $\lambda=4 C(1+t)^{2} \sigma^{2}(n+p)$ gives the very similar bound

$$
\left\|A^{*} X B^{*}-\hat{A}_{\hat{r}} X \hat{B}_{\hat{r}}\right\|_{F}^{2} \leq 24 C(1+t)^{2} \cdot \sigma^{2} r^{*}(n+p) .
$$

From a computational point of view, it is preferable to change $\widehat{\sigma}_{r}^{2}$ in some cases. For example, we use in our numerical simulations

$$
\widehat{\sigma}_{r}^{2}=\frac{1}{n p-(m \wedge q) r_{X}}\left\|Y-\hat{A}_{r} X \hat{B}_{r}\right\|_{F}^{2}
$$

when $n \geq m, p \geq q$ and thus $n p>(m \wedge q) r_{X}$. It is straightforward to prove the analogue of Theorem 2.7 by considering $\lambda=(1+\varepsilon)\left(n p-(m \wedge q) r_{X}\right) /\left(r_{\max } \vee r_{Y}\right)$.

## 3 Nuclear norm penalized learning

Nuclear norm penalized least squares is known to exhibit good properties, see [1] or [16]. Hence it may show advantages over rank-penalized methods. Let us define the nuclear norm penalized (NNP) optimisation problem

$$
\begin{equation*}
\min _{A, B}\|Y-A X B\|_{F}^{2}+2 \lambda \cdot\|A X B\|_{*} \tag{10}
\end{equation*}
$$

for some $\lambda>0$. The objective of the optimization problem is non-jointly convex in $A$ and $B$. Note that in matrix regression (when $A^{*}$ is the identity matrix) the nuclear norm of $X B$ has been used, see [14], or other adaptive forms depending on the feature matrix $X$, [15]. However, we exhibit explicit predictors belonging to the set of solutions of this problem and show an oracle inequality they satisfy.

Theorem 3.1 The predictors $(\bar{A}, \bar{B})$ defined by

$$
\begin{equation*}
\bar{A}=U_{Y} I_{n, m} U_{X}^{\top} \quad \text { and } \quad \bar{B}=V_{X} \cdot \operatorname{Diag}_{q, p}\left(\frac{\left(\sigma_{k}(Y)-\lambda\right)_{+}}{\sigma_{k}(X)}, 1 \leq k \leq r_{Y} \wedge r_{X}\right) V_{Y}^{\top} \tag{11}
\end{equation*}
$$

are solutions to the problem in 10. Moreover, if $\lambda$ is such that, for some absolute constant $C>0$ and for any $t>0, \lambda \geq 2 C(1+t)^{2} \sigma^{2}(n+p)$, they satisfy the oracle inequality

$$
\left\|A^{*} X B^{*}-\bar{A} X \bar{B}\right\|_{F}^{2} \leq 9 \min _{r \in\left[n \wedge p \wedge r_{X}\right]}\left\{\sum_{k=r+1}^{r^{*}} \sigma_{k}\left(A^{*} X B^{*}\right)^{2} \cdot \mathbf{1}_{r<r^{*}}+16 \lambda r\right\}
$$

with probability larger than $1-2 \exp \left(-t^{2}(\sqrt{n}+\sqrt{p})^{2}\right)$.
The proof can be found in Section 5 .
Remark. Another approach could be to consider the model under the vectorized form (2) and solve the problem

$$
\min _{A, B}\left\|\operatorname{vec}(Y)^{\top}-\operatorname{vec}(X)^{\top} \cdot A^{\top} \otimes B\right\|_{2}^{2}+2 \lambda\left\|A^{\top} \otimes B\right\|_{*},
$$

for some $\lambda>0$. Recall that $A^{\top} \otimes B$ denotes the tensor product of matrices $A^{\top}$ and $B$ and that we can write $\left\|A^{\top} \otimes B\right\|_{*}=\sum_{k, j \geq 1} \sigma_{k}(A) \sigma_{j}(B)$. However, the features are 1-dimensional
and we loose the structured information contained in the original matrix $X$. This approach could make more sense in the case of repeated observation $\left(Y_{t}, X_{t}\right)$ for $t$ in [ $T$ ], by stacking the rows $\operatorname{vec}\left(Y_{t}\right)^{\top}$ and $\operatorname{vec}\left(X_{t}^{\top}\right)$ into matrices $\mathbb{Y}$ and $\mathbb{X}$, respectively, and do a classical matrix regression. Even so, the usual assumptions on the feature matrix $\mathbb{X}$ in order to achieve good prediction are not reasonable in this context as they are not much related to the original matrix data sets $X_{t}, t$ in $[T]$.

Remark (Sufficient conditions for identifiability) We have indicated at several times that many couples of matrices $(A, B)$ solve the equation $M=A X B$ for a given matrix $M$. Given the SVD of the matrix $M$, we may reduce the dimensionality of the problem by choosing the solution $(A, B)$ given by $A=U_{M} A_{0} U_{X}^{\top}$ and $B=V_{X} B_{0} V_{M}^{\top}$, with $A_{0}$ and $B_{0}$ diagonal matrices such that

$$
\sigma_{k}(A) \sigma_{k}(X) \sigma_{k}(B)=\sigma_{k}(M), \quad \text { for all } k \leq r_{X} \wedge r_{A} \wedge r_{B} .
$$

Thus, even under diagonal forms we can only identify the product of respective singular values of $A$ and $B$. We can only hope to identify matrices $A$ and $B$ under very restrictive conditions where $X^{\top} X$ has full rank and either the matrix $A$ or the matrix $B$ is assumed to have known singular values, e.g. like a projector with singular values 1 or 0 . Few other setups are known to be identifiable in the literature of factorisation of matrices, e.g. non-negative matrix factorisation (NMF), see [7], NMF for topic models [11, [2], [13] or covariance matrix factorization [8].

## 4 Numerical Results

Let us set the dimensions of the observed matrix $Y$ to be $n=100$ and $p=300$, the dimensions of the design matrix $X$ to be $m=50$ and $q=60$. We randomly generate three matrices: $A^{*}$, $B^{*}$, and $X$, with independent random gaussian entries with mean 0 and variance 1 . These matrices are then projected onto the best low-rank matrix approximation, with the matrix $A^{*}$ having a rank $r_{A}^{*}=16$, the matrix $B^{*}$ having a rank $r_{B}^{*}=12$, and the matrix $X$ having a rank $r_{X}=25$. The signal matrix is defined as $A^{*} X B^{*}$ and shows a rank of 12 in all experiments. We also define various settings for the variance $\sigma^{2}$ of the Gaussian noise $E$ so that the signal-to-noise ratio $S N R:=\sigma_{r^{*}}\left(A^{*} X B^{*}\right)^{2} / \sigma_{1}(E)^{2}$ varies approximately in the range $[0.5,2]$.

Figure 1 illustrates the prediction performances of the predictor $\hat{A}_{r} X \hat{B}_{r}$, defined in 77), for different values of $r$. For $\sigma<8$ giving the $S N R$ approximately above the value 1 , the prediction risk decreases when the rank increases while remaining bounded from above by 12 and then increases with the rank when the rank is above 12. For $\sigma \geq 8$ giving the $S N R$ below the value 1 , the prediction risk decreases when the rank increases while remaining bounded from above by 11 and then increases with the rank when the rank is above 11. It highlights that the best predictor is achieved when $r=r^{*}=12$ for small noise variance levels (i.e. $\sigma<8$ ) and when $r=11$ for strong noise variance levels (i.e. $\sigma \geq 8$ ). This shows that there is a strong overfitting phenomenon in the case of strong noise and that it is therefore better to slightly underestimate the rank in these situations.


Figure 1: Evolution of the risk $\frac{\left\|\hat{A}_{r} X \hat{B}_{r}-A^{*} X B^{*}\right\|_{F}^{2}}{\left\|A^{*} X B^{*}\right\|_{F}^{2}}$ in function of $r$ for different values of $\sigma$


Figure 2: Evolution of the estimated $\hat{r}$ as a function of $\log (\lambda)$ for different values of $\sigma$

Figure 22 represents the predicted $\hat{r}$, defined in (8), for various values of $\lambda$. Independently of the noise variance level, for small values of $\lambda$ the estimated $\hat{r}$ is maximal and there is $\hat{r}=r_{X}=25$. This illustrates the previously exposed overfitting phenomenon, that is the higher the rank $r$, the lower the error $\left\|Y-\hat{A}_{r} X \hat{B}_{r}\right\|_{F}^{2}$. As $\lambda$ increases the penalty on the rank $r$ becomes more important in the minimization procedure and $\hat{r}$ decreases. However, for moderate values of $\lambda$ (i.e. approximately $\log (\lambda) \leq 5$ ) the smaller the noise variance level $\sigma$, the faster $\hat{r}$ decreases. Ultimately, for large values of $\lambda$ (i.e. approximately $\log (\lambda)>5$ ) the rate of decay of $\hat{r}$ as a function of $\lambda$ no longer depends on $\sigma$.

The numerical value of $\lambda$ is an important issue. We exhibit explicit (fast to calculate) procedures for the choice of this tuning parameter. In the case of known noise variance, the rule of thumb suggested by [4] indicates to choose

$$
\lambda(\sigma)=2 C(n+p) \sigma^{2}(1+t)^{2}
$$

in Theorem 2.3 with $t=0$, and $C=2$. The two solid vertical lines represent $\lambda$ (4.5) (blue) and $\lambda(10)$ (green). With these choices of the tuning parameter we get successful estimators of the underlying rank of the signal $\hat{r} \approx 12=r^{*}$. We underline that in the small noise regime the rank is slightly overestimated and in the strong noise regime it is slightly underestimated. This behaviour perfectly matches the results drawn from Figure 1 showing that overestimating the rank in small noise regime does not impact the performances and slightly underestimating it in strong noise regime improves the performances.

However, in real world applications the noise has unknown variance. This raises the question of how to choose a data-driven $\lambda$ in this case, without deteriorating the prediction. This situation is more challenging as it first requires an estimator of $\sigma^{2}$ before using the previously exposed rule of thumb. We choose the initial value of $r$ equal to $r_{X} \wedge n \wedge p$ and propose the $r$-dependent estimator $\widehat{\sigma}_{r}^{2}:=\frac{\left\|Y-\hat{A}_{r} X \hat{B}_{r}\right\|_{F}^{2}}{n p-(m \wedge q) r_{X}}$. It allows to compute the previously defined $\lambda\left(\widehat{\sigma}_{r}\right)$ and using this data-driven tuning parameter we produce the rank estimator $\bar{r}$. This procedure takes $r$ as an argument and returns $\lambda\left(\widehat{\sigma}_{r}\right)$ and $\bar{r}$. However, when $r$ is substantially larger than $r^{*}, \hat{A}_{r} X \hat{B}_{r}$ is overfitting $Y$ and performing this procedure once will not lead to a satisfying output $\bar{r}$. Hence we iterate while $\bar{r}<r$. We note $\lambda\left(\widehat{\sigma}_{\bar{r}}\right)$ and $\bar{r}$ the final outputs of the procedure. The two dashed vertical lines represent $\lambda\left(\widehat{\sigma}_{\bar{r}}\right)$ when $\sigma=4.5$ (cyan) and $\sigma=10$ (magenta). The proposed procedure exhibits great numerical properties.

Finally, numerical simulations generated in the same context, with different values for the true underlying ranks, show similar excellent prediction bounds, combined with correct rank selection. Together with the current case where $\min \left(r_{A}^{*}, r_{X}, r_{B}^{*}\right)=r_{B}^{*}$, we have explored successfully the cases $\min \left(r_{A}^{*}, r_{X}, r_{B}^{*}\right)=r_{A}^{*}, \min \left(r_{A}^{*}, r_{X}, r_{B}^{*}\right)=r_{X}$ and $\min \left(r_{A}^{*}, r_{X}, r_{B}^{*}\right)=$ $r_{A}^{*}=r_{X}=r_{B}^{*}$.

## 5 Proofs

Basic facts For any matrix $M \in \mathbb{R}^{n \times m},\|M\|_{*}^{2} \leq r_{M}\|M\|_{F}^{2}$. In addition, for any matrices $M_{1}$ and $M_{2}$ in $\mathbb{R}^{n \times m}$, the following inequalities hold $\left\langle M_{1}, M_{2}\right\rangle_{F} \leq\left\|M_{1}\right\|_{*}\left\|M_{2}\right\|_{o p}$ and $\| M_{1}+$
$M_{2}\left\|_{F} \leq\right\| M_{1}\left\|_{F}+\right\| M_{2} \|_{F}$. Furthermore, if we set $a=\operatorname{rank} M_{1} \wedge \operatorname{rank} M_{2}$ then $\left\langle M_{1}, M_{2}\right\rangle_{F} \leq$ $\left\|M_{1}\right\|_{(2, a)}\left\|M_{2}\right\|_{(2, a)}$.

Lemma 5.1 Let $E$ be a $n \times p$ random matrix whose entries are independent and having Gaussian distribution $\mathcal{N}\left(0, \sigma^{2}\right)$. If $U$ and $V$ belong to $\mathcal{O}_{n}$ and $\mathcal{O}_{p}$ respectively, then $E_{0}:=$ $U^{\top} E V$ has independent entries with Gaussian distribution $\mathcal{N}\left(0, \sigma^{2}\right)$.

Proof of Lemma 5.1. Note that we can vectorize the matrix $E_{0}$ and get that

$$
\operatorname{vec}\left(E_{0}\right)=\left(V^{\top} \otimes U^{\top}\right) \cdot \operatorname{vec}(E)
$$

where $\operatorname{vec}(E)$ is a Gaussian vector of dimension $n p$, centered, with variance $\sigma^{2} I_{n p}$. Moreover, the tensor product $V^{\top} \otimes U^{\top}$ belongs to $\mathcal{O}_{n p}$, thus $\operatorname{vec}\left(E_{0}\right)$ is still a Gaussian vector with distribution $\mathcal{N}_{n p}\left(0, \sigma^{2} I_{n p}\right)$.

Recall that, for an arbitrary matrix $M$, we denote $U_{M} \Sigma_{M} V_{M}^{\top}$ its SVD.
Lemma 5.2 If $M^{*}$ is a $n \times p$ matrix of rank $r^{*}$, than for any $r \leq n \wedge p$, we have

$$
\inf _{M: \operatorname{rank} M \leq r}\left\|M-M^{*}\right\|_{F}^{2}=\sum_{k=r+1}^{r^{*}} \sigma_{k}\left(M^{*}\right)^{2} \cdot \mathbf{1}_{r<r^{*}},
$$

and the infimum is attained by the projection $\left[M^{*}\right]_{r}$ of $M^{*}$ on the space of $n \times p$ matrices with rank $r$ given by the matrix

$$
\left[M^{*}\right]_{r}=U_{M^{*}} \cdot \operatorname{Diag}_{n, p}\left(\sigma_{1}\left(M^{*}\right), \ldots, \sigma_{r \wedge r^{*}}\left(M^{*}\right)\right) \cdot V_{M^{*}}^{\top}
$$

### 5.1 Proof of Theorem 2.1

Let $r \in\left[n \wedge p \wedge r_{X}\right]$ and $\left(\hat{A}_{0 r}, \hat{B}_{0 r}\right)$ defined in (66). Let us denote here $M_{0}^{*}=A_{0}^{*} \Sigma_{X} B_{0}^{*}$ and $\hat{M}_{0}=\hat{A}_{0 r} \Sigma_{X} \hat{B}_{0 r}$. By construction, $\hat{M}_{0}$ is the projection $\left[\Sigma_{Y}\right]_{r}$ of $\Sigma_{Y}$ onto the set of matrices with rank less than or equal to $r$, in the sense of Lemma 5.2. Therefore,

$$
\left\|\Sigma_{Y}-\hat{M}_{0}\right\|_{F}^{2} \leq\left\|\Sigma_{Y}-\left[M_{0}^{*}\right]_{r}\right\|_{F}^{2}
$$

We recall that in our model $\Sigma_{Y}=M_{0}^{*}+E_{0}$ which leads to

$$
\left\|M_{0}^{*}-\hat{M}_{0}+E_{0}\right\|_{F}^{2} \leq\left\|M_{0}^{*}-\left[M_{0}^{*}\right]_{r}+E_{0}\right\|_{F}^{2} .
$$

We expand the squares and arrange terms to get

$$
\left\|M_{0}^{*}-\hat{M}_{0}\right\|_{F}^{2} \leq\left\|M_{0}^{*}-\left[M_{0}^{*}\right]_{r}\right\|_{F}^{2}+2\left\langle\hat{M}_{0}-\left[M_{0}^{*}\right]_{r}, E_{0}\right\rangle_{F} .
$$

Now, since $\operatorname{rank}\left(\hat{M}_{0}\right)=r$ and $\operatorname{rank}\left(\left[M_{0}^{*}\right]_{r}\right) \leq r$, we get that $\operatorname{rank}\left(\hat{M}_{0}-\left[M_{0}^{*}\right]_{r}\right) \leq 2 r$. This inequality gives

$$
\begin{aligned}
\left\|M_{0}^{*}-\hat{M}_{0}\right\|_{F}^{2} & \leq\left\|M_{0}^{*}-\left[M_{0}^{*}\right]_{r}\right\|_{F}^{2}+2\left\|E_{0}\right\|_{(2,2 r)} \cdot\left\|\hat{M}_{0}-\left[M_{0}^{*}\right]_{r}\right\|_{(2,2 r)} \\
& \leq\left\|M_{0}^{*}-\left[M_{0}^{*}\right]_{r}\right\|_{F}^{2}+2\left\|E_{0}\right\|_{(2,2 r)} \cdot\left\|\hat{M}_{0}-\left[M_{0}^{*}\right]_{r}\right\|_{F} \\
& \leq\left\|M_{0}^{*}-\left[M_{0}^{*}\right]_{r}\right\|_{F}^{2}+2\left\|E_{0}\right\|_{(2,2 r)} \cdot\left(\left\|\hat{M}_{0}-M_{0}^{*}\right\|_{F}+\left\|M_{0}^{*}-\left[M_{0}^{*}\right]_{r}\right\|_{F}\right) .
\end{aligned}
$$

We apply the inequality $2 x y \leq \alpha x^{2}+\alpha^{-1} y^{2}$ with $x, y \geq 0$ and $\alpha>0$. We obtain, for real numbers $\alpha>1$ and $\beta>0$,

$$
\left(1-\alpha^{-1}\right) \cdot\left\|M_{0}^{*}-\hat{M}_{0}\right\|_{F}^{2} \leq\left(1+\beta^{-1}\right) \cdot\left\|M_{0}^{*}-\left[M_{0}^{*}\right]_{r}\right\|_{F}^{2}+(\alpha+\beta) \cdot\left\|E_{0}\right\|_{(2,2 r)}^{2}
$$

Let us use that $\left\|E_{0}\right\|_{(2,2 r)}^{2} \leq 2 r \cdot\left\|E_{0}\right\|_{o p}^{2}$ and Lemma 5.2 to further get

$$
\begin{equation*}
\left\|M_{0}^{*}-\hat{M}_{0}\right\|_{F}^{2} \leq \frac{1+\beta^{-1}}{1-\alpha^{-1}} \cdot \inf _{M: \operatorname{rank} M \leq r}\left\|M_{0}^{*}-M\right\|_{F}^{2}+\frac{\alpha+\beta}{1-\alpha^{-1}} \cdot 2 r\left\|E_{0}\right\|_{o p}^{2} \tag{12}
\end{equation*}
$$

Noticing that for any matrices $A_{0}, B_{0}$ having rank less than or equal to $r, \operatorname{rank}\left(A_{0} \Sigma_{X} B_{0}\right) \leq$ $r_{A_{0}} \wedge r_{X} \wedge r_{B_{0}} \leq r$, we deduce that

$$
\inf _{M: \operatorname{rank} M \leq r}\left\|M_{0}^{*}-M\right\|_{F}^{2} \leq \inf _{\substack{A_{0}, B_{0}: \\ \operatorname{rank} A_{0} \wedge \operatorname{rank} \\ B_{0} \leq r}}\left\|M_{0}^{*}-A_{0} \Sigma_{X} B_{0}\right\|_{F}^{2}
$$

Indeed, the second inf is taken over a possibly smaller family of matrices. We actually show that equality holds in the previous display. Indeed, by Lemma 5.2 we have that $\inf _{M: \operatorname{rank} M \leq r}\left\|M_{0}^{*}-M\right\|_{F}^{2}=\sum_{k=r+1}^{r^{*}} \sigma_{k}\left(M_{0}^{*}\right)^{2} \cdot \mathbf{1}_{r<r^{*}}$, where $r^{*}=\operatorname{rank}\left(M_{0}^{*}\right)$. Recall that $M_{0}^{*}=A_{0}^{*} \Sigma_{X} B_{0}^{*}$ is a product of diagonal matrices, giving that $r^{*}=\min \left(r_{X}, r_{A_{0}^{*}}, r_{B_{0}^{*}}\right)$ and $\sigma_{k}\left(M_{0}^{*}\right)=\sigma_{k}\left(A_{0}^{*}\right) \sigma_{k}(X) \sigma_{k}\left(B_{0}^{*}\right) \cdot \mathbf{1}_{k \leq r^{*}}$. Thus, the particular choice

$$
A_{0 r}:=\operatorname{Diag}_{n, m}\left(\sigma_{1}\left(A_{0}^{*}\right), \ldots, \sigma_{r \wedge r_{A_{0}^{*}}}\left(A_{0}^{*}\right)\right) \text { and } B_{0 r}:=\operatorname{Diag}_{q, p}\left(\sigma_{1}\left(B_{0}^{*}\right), \ldots, \sigma_{r \wedge r_{B_{0}^{*}}}\left(B_{0}^{*}\right)\right)
$$

solves exactly the problem giving $M_{0}^{*}=A_{0 r} \Sigma_{X} B_{0 r}$. Finally,

$$
\begin{equation*}
\inf _{M: \text { rank } M \leq r}\left\|M_{0}^{*}-M\right\|_{F}^{2}=\inf _{\substack{A_{0}, B_{0}: \\ \operatorname{rank} A_{0} \wedge \operatorname{rank} \\ B_{0} \leq r}}\left\|M_{0}^{*}-A_{0} \Sigma_{X} B_{0}\right\|_{F}^{2} . \tag{13}
\end{equation*}
$$

Plugging this into (12) and considering the particular choice $\alpha=3 / 2$ and $\beta=1 / 2$ give the theorem:

$$
\left\|A_{0}^{*} \Sigma_{X} B_{0}^{*}-\hat{A}_{0 r} \Sigma_{X} \hat{B}_{0 r}\right\|_{F}^{2} \leq 9 \inf _{\substack{A_{0}, B_{0}: \\ \operatorname{rank} A_{0} \wedge \text { rank } B_{0} \leq r}}\left(\left\|A_{0}^{*} \Sigma_{X} B_{0}^{*}-A_{0} \Sigma_{X} B_{0}\right\|_{F}^{2}\right)+12 r\left\|E_{0}\right\|_{o p}^{2}
$$

The last step is the high-probability bound on $\left\|E_{0}\right\|_{o p}$. Recall that $E_{0}=U_{Y}^{\top} E V_{Y}$ with $U_{Y}$ in $\mathcal{O}_{n}$ and $V_{Y}$ in $\mathcal{O}_{p}$ and therefore $E_{0}$ and $E$ have the same singular values. Therefore $\|E\|_{o p}=\left\|E_{0}\right\|_{o p}$. The noise matrix $E$ has independent, centered, $\sigma$-sub-Gaussian entries and its spectral norm verifies (see [20]) for some absolute constant $C>0$

$$
\begin{equation*}
\mathbb{P}\left(\|E\|_{o p}^{2} \leq 2 C \sigma^{2} \cdot(1+t)^{2}(n+p)\right) \geq 1-2 e^{-t^{2}(\sqrt{n}+\sqrt{p})^{2}}, \quad \text { for any } t>0 . \tag{14}
\end{equation*}
$$

Moreover, $\mathbb{E}\left[\|E\|_{o p}\right] \leq \sqrt{C} \sigma(\sqrt{n}+\sqrt{p})$.

### 5.2 Proof of Corollary 2.2

Recall the notation $M_{0}^{*}=A_{0}^{*} \Sigma_{X} B_{0}^{*}$ and $\hat{M}_{0}=\hat{A}_{0 r} \Sigma_{X} \hat{B}_{0 r}$ with $\hat{A}_{0 r}$ and $\hat{B}_{0 r}$ given by (6) and let us denote $M^{*}=A^{*} X B^{*}$ and $\hat{M}=\hat{A}_{r} X \hat{B}_{r}$ with $\hat{A}_{r}$ and $\hat{B}_{r}$ given by (7). Notice that the Frobenius norm and the rank are invariant under left or right multiplication by orthogonal matrices. Therefore, we follow the lines of the proof of Theorem 2.1 and see that $\|Y-\hat{M}\|_{F}^{2}=\left\|\Sigma_{Y}-\hat{M}_{0}\right\|_{F}^{2}$ and $\operatorname{rank} M^{*}=\operatorname{rank} M_{0}^{*}=r^{*}$. Also, $\hat{M}$ is the projection $[Y]_{r}$ of $Y$ on the space of matrices with rank less than or equal to $r$. Finally, the equality (13) can be pushed forward

$$
\inf _{M: \operatorname{rank} M \leq r}\left\|M_{0}^{*}-M\right\|_{F}^{2}=\inf _{\substack{A_{0}, B_{0}: \\ \operatorname{rank} A_{0} \wedge \operatorname{rank} B_{0} \leq r}}\left\|M_{0}^{*}-A_{0} \Sigma_{X} B_{0}\right\|_{F}^{2}=\inf _{\substack{A, B: \\ \operatorname{rank} A \wedge \operatorname{rank} B \leq r}}\left\|M^{*}-A X B\right\|_{F}^{2} .
$$

Indeed, we have one-to-one transformations of $A_{0}, B_{0}$ into $A, B$, respectively, and equality of the Frobenius norms. This finishes the proof.

### 5.3 Proof of Theorem 2.3

By definition of $\hat{r}=\hat{r}(\lambda)$, we have that, for all $r \in\left[n \wedge p \wedge r_{X}\right]$,

$$
\left\|Y-\hat{A}_{\hat{r}} X \hat{B}_{\hat{r}}\right\|_{F}^{2}+\lambda \hat{r} \leq\left\|Y-\hat{A}_{r} X \hat{B}_{r}\right\|_{F}^{2}+\lambda r .
$$

Since $\hat{A}_{r} X \hat{B}_{r}$ is the projection $[Y]_{r}$ of $Y$ on the space of matrices $M$ with rank $M \leq r$, we get that for all matrices $A$ and $B$ such that $\operatorname{rank} A \wedge \operatorname{rank} B \leq r$

$$
\left\|Y-\hat{A}_{r} X \hat{B}_{r}\right\|_{F}^{2} \leq\|Y-A X B\|_{F}^{2}
$$

Indeed, $\operatorname{rank}(A X B) \leq r$ and Pythagora's theorem gives the former inequality. We deduce that

$$
\left\|Y-\hat{A}_{\hat{r}} X \hat{B}_{\hat{r}}\right\|_{F}^{2}+\lambda \hat{r} \leq\|Y-A X B\|_{F}^{2}+\lambda r .
$$

Next, replace $Y=A^{*} X B^{*}+E$, expand the squares and rearrange terms to get

$$
\begin{aligned}
\left\|A^{*} X B^{*}-\hat{A}_{\hat{r}} X \hat{B}_{\hat{r}}\right\|_{F}^{2} & \leq\left\|A^{*} X B^{*}-A X B\right\|_{F}^{2}+\lambda(r-\hat{r}) \\
& +2\left\langle E, \hat{A}_{\hat{r}} X \hat{B}_{\hat{r}}-A X B\right\rangle .
\end{aligned}
$$

Let us denote by $\hat{M}(\hat{r})=\hat{A}_{\hat{r}} X \hat{B}_{\hat{r}}, M(r)=A X B$ and see that $\operatorname{rank}(\hat{M}(\hat{r})-M(r)) \leq \hat{r}+r$. We have

$$
\begin{aligned}
\left\langle E, \hat{A}_{\hat{r}} X \hat{B}_{\hat{r}}-A X B\right\rangle & \leq\|E\|_{o p} \cdot\|\hat{M}(\hat{r})-M(r)\|_{*} \\
& \leq\|E\|_{o p} \cdot \sqrt{\hat{r}+r}\|\hat{M}(\hat{r})-M(r)\|_{F} \\
& \leq\|E\|_{o p} \cdot \sqrt{\hat{r}+r}\left(\left\|M^{*}-\hat{M}(\hat{r})\right\|_{F}+\left\|M^{*}-M(r)\right\|_{F}\right) .
\end{aligned}
$$

Then, using twice the inequality $2 x y \leq \alpha x^{2}+\alpha^{-1} y^{2}$ with $x, y \geq 0$ and $\alpha>0$, we obtain for arbitrary real numbers $\alpha>1, \beta>0$ :

$$
\begin{aligned}
\left(1-\alpha^{-1}\right)\left\|M^{*}-\hat{M}(\hat{r})\right\|_{F}^{2} & \leq\left(1+\beta^{-1}\right)\left\|M^{*}-M(r)\right\|_{F}^{2} \\
& +(\alpha+\beta)\|E\|_{o p}^{2}(r+\hat{r})+\lambda(r-\hat{r}) .
\end{aligned}
$$

Consequently, if $(\alpha+\beta)\|E\|_{o p}^{2} \leq \lambda$ :

$$
\left(1-\alpha^{-1}\right)\left\|M^{*}-\hat{M}(\hat{r})\right\|_{F}^{2} \leq\left(1+\beta^{-1}\right)\left\|M^{*}-M(r)\right\|_{F}^{2}+2 \lambda r
$$

for all $r$ in $\left[n \wedge p \wedge r_{X}\right]$ and all $M(r)=A X B$ with $\operatorname{rank} A \wedge \operatorname{rank} B \leq r$. We get the result by replacing again $\alpha=3 / 2$ and $\beta=1 / 2$. Then we use that

$$
\min _{\substack{A, B \\ \operatorname{rank} A \wedge \text { ank } B \leq r}}\left\|A^{*} X B^{*}-A X B\right\|_{F}^{2}=\sum_{k=r+1}^{r^{*}} \sigma_{k}\left(A^{*} X B^{*}\right)^{2}
$$

and the high-probability bounds in (14).

### 5.4 Proofs of results in Section 2.3

Proof of Proposition 2.4. For any $r$ in $\left[n \wedge p \wedge r_{X}\right]$, we have that $\hat{A}_{r} X \hat{B}_{r}=[Y]_{r}$ is the projection of $Y$ on the space of matrices having rank smaller than or equal to $r$. Now, write

$$
\begin{aligned}
F(r): & =\left\|Y-\hat{A}_{r} X \hat{B}_{r}\right\|_{F}^{2}+\lambda r \\
& =\sum_{k=r+1}^{r_{Y}} \sigma_{k}(Y)^{2} \cdot \mathbf{1}_{r<r_{Y}}+\lambda r \\
& =\sum_{k=r+1}^{r_{Y}}\left(\sigma_{k}(Y)^{2}-\lambda\right) \cdot \mathbf{1}_{r<r_{Y}}+\lambda r_{Y} .
\end{aligned}
$$

It is easy to see that $F$ as a function of $r$ has a unique minimum at $r_{Y}(\lambda)$ if $\lambda>\sigma_{r_{Y}}(Y)^{2}$, but is minimal and constant for $r=r_{Y}, \ldots,\left(n \wedge p \wedge r_{X}\right)$ whenever $\lambda \leq \sigma_{r_{Y}}(Y)^{2}$.
Proof of Proposition 2.5. By definition of $\hat{r}$, we have $k>\hat{r}$ if and only if $\lambda>\sigma_{k}(Y)^{2}$ and $k<\hat{r}$ if and only if $\lambda \leq \sigma_{k+1}(Y)^{2}$. In our model $Y=A^{*} X B^{*}+E$, the Weyl inequality gives $\left|\sigma_{k}\left(A^{*} X B^{*}\right)-\sigma_{k}(Y)\right| \leq \sigma_{1}(E)$ for all $k$. The events on $\hat{r}$ can be written in terms of $\sigma_{1}(E)=\|E\|_{o p}$ as follows. We have

$$
\begin{array}{lll}
\{k>\hat{r}\} & \text { implies } & \lambda>\left(\sigma_{k}\left(A^{*} X B^{*}\right)-\sigma_{1}(E)\right)^{2}, \\
\{k<\hat{r}\} & \text { implies } & \lambda \leq\left(\sigma_{k+1}\left(A^{*} X B^{*}\right)+\sigma_{1}(E)\right)^{2} .
\end{array}
$$

Thus $\{\hat{r} \neq k\}$ implies either $\sigma_{1}(E)>\sigma_{k}\left(A^{*} X B^{*}\right)-\sqrt{\lambda}$ or $\sigma_{1}(E) \geq \sqrt{\lambda}-\sigma_{k+1}\left(A^{*} X B^{*}\right)$. Let us take $k=r^{*}(\lambda)$. Then the assumption that $\sigma_{r^{*}(\lambda)}\left(A^{*} X B^{*}\right)>(1+c) \sqrt{\lambda}$ gives that $\sigma_{1}(E)>$ $c \sqrt{\lambda}$ and the assumption that $\sigma_{r^{*}(\lambda)+1}\left(A^{*} X B^{*}\right)<(1-c) \sqrt{\lambda}$ gives also that $\sigma_{1}(E)>c \sqrt{\lambda}$. Thus,

$$
\mathbb{P}\left(\hat{r} \neq r^{*}(\lambda)\right) \leq \mathbb{P}\left(\sigma_{1}(E)>c \sqrt{\lambda}\right) .
$$

The proof is finished using the inequality (14).

### 5.5 Proof of Theorem 2.7

The optimization problem (9) can be written, after replacing $\widehat{\sigma}_{r}^{2}$, as follows

$$
\bar{r} \in \arg \min _{r \in\left[r_{\text {max }}\right]}\left\|Y-\hat{A}_{r} X \hat{B}_{r}\right\|_{F}^{2}\left(1+\frac{\lambda r}{n p}\right) .
$$

We denote by $\bar{M}=\hat{A}_{\bar{r}} X \hat{B}_{\bar{r}}, \hat{M}_{r}=\hat{A}_{r} X \hat{B}_{r}$ and $M^{*}=A^{*} X B^{*}$. With this notation it follows that, for $r \leq r_{\text {max }}$,

$$
\|Y-\bar{M}\|_{F}^{2}\left(1+\frac{\lambda \bar{r}}{n p}\right) \leq\left\|Y-\hat{M}_{r}\right\|_{F}^{2}\left(1+\frac{\lambda r}{n p}\right) .
$$

Developing the squares and using the equality $Y=M^{*}+E$, we get

$$
\left\|M^{*}-\bar{M}\right\|_{F}^{2} \leq\left\|M^{*}-\hat{M}_{r}\right\|_{F}^{2}+2\left\langle E, \bar{M}-\hat{M}_{r}\right\rangle_{F}+\frac{\lambda r}{n p}\left\|Y-\hat{M}_{r}\right\|_{F}^{2}-\frac{\lambda \bar{r}}{n p}\|Y-\bar{M}\|_{F}^{2}
$$

We now use the upper bound $\left\langle E, \bar{M}-\hat{M}_{r}\right\rangle_{F} \leq\|E\|_{o p}\left\|\bar{M}-\hat{M}_{r}\right\|_{*}$ and the definition of $\bar{M}$ and $\hat{M}_{r}$ to derive

$$
\left\|M^{*}-\bar{M}\right\|_{F}^{2} \leq\left\|M^{*}-\hat{M}_{r}\right\|_{F}^{2}+2\|E\|_{o p}\left\|\bar{M}-\hat{M}_{r}\right\|_{*}+\frac{\lambda r}{n p} \sum_{k>r} \sigma_{k}(Y)^{2}-\frac{\lambda \bar{r}}{n p} \sum_{k>\bar{r}} \sigma_{k}(Y)^{2} .
$$

Let us note that we use $\sigma_{k}(Y)=0$ in case $k>r_{Y}$. We recall that $\left\|\bar{M}-\hat{M}_{r}\right\|_{*} \leq \sqrt{r+\bar{r}}$. $\left\|\bar{M}-\hat{M}_{r}\right\|_{F}$ and further obtain

$$
\begin{aligned}
\left\|M^{*}-\bar{M}\right\|_{F}^{2} & \leq\left\|M^{*}-\hat{M}_{r}\right\|_{F}^{2}+2\|E\|_{o p} \sqrt{r+\bar{r}}\left(\left\|M^{*}-\bar{M}\right\|_{F}+\left\|M^{*}-\hat{M}_{r}\right\|_{F}\right) \\
& +\frac{\lambda r}{n p} \sum_{k>r} \sigma_{k}(Y)^{2}-\frac{\lambda \bar{r}}{n p} \sum_{k>\bar{r}} \sigma_{k}(Y)^{2} .
\end{aligned}
$$

Using twice the inequality $2 a b \leq \alpha a^{2}+\alpha^{-1} b^{2}$ for $a, b>0$, with $\alpha>1$ first and with $\beta>0$ second, we get

$$
\begin{align*}
\left(1-\alpha^{-1}\right)\left\|M^{*}-\bar{M}\right\|_{F}^{2} & \leq\left(1+\beta^{-1}\right)\left\|M^{*}-\hat{M}_{r}\right\|_{F}^{2}+(\alpha+\beta)\|E\|_{o p}^{2}(r+\bar{r}) \\
& +\frac{\lambda r}{n p} \sum_{k>r} \sigma_{k}(Y)^{2}-\frac{\lambda \bar{r}}{n p} \sum_{k>\bar{r}} \sigma_{k}(Y)^{2} . \tag{15}
\end{align*}
$$

We now distinguish the two cases: $r \leq \bar{r}$ and $r>\bar{r}$. In the first case, namely $r \leq \bar{r}$, we bound from above as follows:

$$
\begin{aligned}
\frac{\lambda r}{n p} \sum_{k>r} \sigma_{k}(Y)^{2}-\frac{\lambda \bar{r}}{n p} \sum_{k>\bar{r}} \sigma_{k}(Y)^{2} & =\frac{\lambda}{n p}\left(r \sum_{k=r+1}^{\bar{r}} \sigma_{k}(Y)^{2}+(r-\bar{r}) \sum_{k>\bar{r}} \sigma_{k}(Y)^{2}\right) \\
& \leq \frac{\lambda}{n p} r(\bar{r}-r) \sigma_{r+1}(Y)^{2} \\
& \leq \frac{2 \lambda r}{n p}(\bar{r}-r)\left(\sigma_{r+1}\left(M^{*}\right)^{2}+\|E\|_{o p}^{2}\right) \\
& \leq \frac{2 \lambda r}{n p} r_{\max } \sigma_{r+1}\left(M^{*}\right)^{2}+\frac{2 \lambda r_{\max }}{n p}(\bar{r}-r)\|E\|_{o p}^{2}
\end{aligned}
$$

where we used Weyl inequality $\sigma_{r+1}(Y) \leq \sigma_{r+1}\left(M^{*}\right)+\|E\|_{o p}$ leading to $\sigma_{r+1}(Y)^{2} \leq 2\|E\|_{o p}^{2}+$ $2 \sigma_{r+1}\left(M^{*}\right)^{2}$. We plug this into (15) to get

$$
\begin{aligned}
\left(1-\alpha^{-1}\right)\left\|M^{*}-\bar{M}\right\|_{F}^{2} & \leq\left(1+\beta^{-1}\right)\left\|M^{*}-\hat{M}_{r}\right\|_{F}^{2}+\frac{2 \lambda r_{\max }}{n p} r \sigma_{r+1}\left(M^{*}\right)^{2} \\
& +r\|E\|_{o p}^{2}\left(\alpha+\beta-\frac{2 \lambda r_{\max }}{n p}\right) \\
& +\bar{r}\|E\|_{o p}^{2}\left(\alpha+\beta+\frac{2 \lambda r_{m a x}}{n p}\right)
\end{aligned}
$$

for all $r \leq \bar{r}$ belonging to $\left[r_{\max }\right]$. Thus, for $\lambda$ such that $\frac{2 \lambda \cdot\left(r_{\max } \vee r_{Y}\right)}{n p}=(1+\varepsilon)(\alpha+\beta)$ for some $\varepsilon>0$ we get

$$
\begin{aligned}
\left(1-\alpha^{-1}\right)\left\|M^{*}-\bar{M}\right\|_{F}^{2} & \leq \min _{r \in[\bar{r}]}\left\{\left(1+\beta^{-1}\right)\left\|M^{*}-\hat{M}_{r}\right\|_{F}^{2}+(1+\varepsilon)(\alpha+\beta) r \sigma_{r+1}\left(M^{*}\right)^{2}\right\} \\
& +(2+\varepsilon)(\alpha+\beta) r_{\max }\|E\|_{o p}^{2} .
\end{aligned}
$$

We now focus on the second case, namely $r>\bar{r}$. We observe that in this case,

$$
\begin{aligned}
\frac{\lambda r}{n p} \sum_{k>r} \sigma_{k}(Y)^{2}-\frac{\lambda \bar{r}}{n p} \sum_{k>\bar{r}} \sigma_{k}(Y)^{2} & =\frac{\lambda}{n p}\left((r-\bar{r}) \sum_{k>r} \sigma_{k}(Y)^{2}-\bar{r} \sum_{k=\bar{r}+1}^{r} \sigma_{k}(Y)^{2}\right) \\
& \leq \frac{\lambda(r-\bar{r})}{n p}\left(r_{Y}-r\right) \sigma_{r+1}(Y)^{2} \\
& \leq \frac{2 \lambda r}{n p} r_{Y} \cdot \sigma_{r+1}\left(M^{*}\right)^{2}+\frac{2 \lambda(r-\bar{r})}{n p} \cdot\left(r_{Y} \vee r_{\max }\right)\|E\|_{o p}^{2},
\end{aligned}
$$

by a similar reasoning in the previous case. We plug this into (15) to get

$$
\begin{aligned}
\left(1-\alpha^{-1}\right)\left\|M^{*}-\bar{M}\right\|_{F}^{2} & \leq\left(1+\beta^{-1}\right)\left\|M^{*}-\hat{M}_{r}\right\|_{F}^{2}+\frac{2 \lambda \cdot r_{\max } \vee r_{Y}}{n p} r \sigma_{r+1}\left(M^{*}\right)^{2} \\
& +r\|E\|_{o p}^{2}\left(\alpha+\beta+\frac{2 \lambda \cdot r_{\max } \vee r_{Y}}{n p}\right) \\
& +\bar{r}\|E\|_{o p}^{2}\left(\alpha+\beta-\frac{2 \lambda \cdot r_{\max } \vee r_{Y}}{n p}\right) .
\end{aligned}
$$

With the same choice of $\lambda$ such that $\frac{2 \lambda \cdot r_{\max } \vee r_{Y}}{n p}=(1+\varepsilon)(\alpha+\beta)$ for some $\varepsilon>0$ we get also in this case that

$$
\begin{aligned}
\left(1-\alpha^{-1}\right)\left\|M^{*}-\bar{M}\right\|_{F}^{2} & \leq \min _{\bar{r}<r \leq r_{\max }}\left\{\left(1+\beta^{-1}\right)\left\|M^{*}-\hat{M}_{r}\right\|_{F}^{2}+(1+\varepsilon)(\alpha+\beta) r \sigma_{r+1}\left(M^{*}\right)^{2}\right\} \\
& +(2+\varepsilon)(\alpha+\beta) r_{\max }\|E\|_{o p}^{2} .
\end{aligned}
$$

Taking $\alpha=3 / 2$ and $\beta=1 / 2$ and combining both cases leads to the following result

$$
\left\|M^{*}-\bar{M}\right\|_{F}^{2} \leq \min _{r \in\left[r_{\text {max }}\right]}\left\{9\left\|M^{*}-\hat{M}_{r}\right\|_{F}^{2}+6(1+\epsilon) \cdot r \sigma_{r+1}\left(M^{*}\right)^{2}\right\}+6(2+\epsilon) \cdot r_{\max }\|E\|_{o p}^{2},
$$

where we choose $\lambda$ such that $\lambda \cdot r_{\max } \vee r_{Y}=(1+\varepsilon) n p$ for some $\varepsilon>0$. We conclude by using the inequality (14).

### 5.6 Proof of Theorem 3.1

We proceed by solving the problem in two steps for solving the optimization problem (10) which can be equivalently written as

$$
\min _{\substack{A, B \\ M=A X B}} \min _{M}\|Y-M\|_{F}^{2}+2 \lambda \cdot\|M\|_{*},
$$

for $\lambda>0$. The solution to the problem in $M$ is explicit and it is known to be obtained from $Y$ by soft-thresholding of its eigenvalues: $\bar{M}=U_{Y} \operatorname{Diag}_{n, p}\left(\left(\sigma_{k}(Y)-\lambda\right)_{+}\right) V_{Y}^{\top}$, where we used the SVD of $Y: U_{Y} \Sigma_{Y} V_{Y}^{\top}$. Next, we project $\bar{M}$ on the space of matrices $A X B$ for $A$ and $B$ in Frobenius norm. It is easy to check that our choice of $\bar{A}, \bar{B}$ are exact solutions, that is $\bar{M}=\bar{A} X \bar{B}$.

Similarly to the proof of Theorem 2.3 , by applying the definition of $\bar{M}$, expanding the squares and rearranging terms we get for all $M$ :

$$
\begin{aligned}
\left\|\bar{M}-M^{*}\right\|_{F}^{2} & \leq\left\|M^{*}-M\right\|_{F}^{2}+2\langle E, \bar{M}-M\rangle+2 \lambda\left(\|M\|_{*}-\|\bar{M}\|_{*}\right) \\
& \leq\left\|M^{*}-M\right\|_{F}^{2}+2 \sqrt{\lambda}\left(\|\bar{M}-M\|_{*}+\|M\|_{*}-\|\bar{M}\|_{*}\right),
\end{aligned}
$$

under the event that $\|E\|_{o p}^{2} \leq \lambda$. We use the decomposability of the nuclear norm of matrices as in [5], to find $\bar{M}_{1}$ and $\bar{M}_{2}$ such that $\bar{M}=\bar{M}_{1}+\bar{M}_{2},\|\bar{M}\|_{*}=\left\|\bar{M}_{1}\right\|_{*}+\left\|\bar{M}_{2}\right\|_{*}$ and $\|\bar{M}-M\|_{*}=\left\|\bar{M}_{1}-M\right\|_{*}+\left\|\bar{M}_{2}\right\|_{*}$. Moreover, $\operatorname{rank}\left(\bar{M}_{1}\right) \leq 2 \operatorname{rank}(M)$. This implies

$$
\begin{aligned}
\left\|\bar{M}-M^{*}\right\|_{F}^{2} & \leq\left\|M^{*}-M\right\|_{F}^{2}+4 \sqrt{\lambda}\left\|\bar{M}_{1}-M\right\|_{*} \\
& \leq\left\|M^{*}-M\right\|_{F}^{2}+4 \sqrt{\lambda} \sqrt{3 \operatorname{rank}(M)} \cdot\left\|\bar{M}_{1}-M\right\|_{F} \\
& \leq\left\|M^{*}-M\right\|_{F}^{2}+4 \sqrt{\lambda} \sqrt{3 \operatorname{rank}(M)} \cdot\left(\left\|\bar{M}-M^{*}\right\|_{F}+\left\|M-M^{*}\right\|_{F}\right) .
\end{aligned}
$$

We obtain for arbitrary real numbers $\alpha>1$ and $\beta>0$, for all $M$,

$$
\left(1-\alpha^{-1}\right)\left\|\bar{M}-M^{*}\right\|_{F}^{2} \leq\left(1+\beta^{-1}\right)\left\|M^{*}-M\right\|_{F}^{2}+4(\alpha+\beta) \lambda \cdot 6 \operatorname{rank}(M)
$$

For the particular values $\alpha=3 / 2$ and $\beta=1 / 2$, we get

$$
\begin{aligned}
\left\|\bar{M}-M^{*}\right\|_{F}^{2} & \leq \min _{M}\left\{9\left\|M^{*}-M\right\|_{F}^{2}+144 \lambda \cdot \operatorname{rank}(M)\right\} \\
& \leq 9 \min _{r \in\left[n \wedge p \wedge r_{X}\right]}\left\{\min _{M: \operatorname{rank} M=r}\left\|M^{*}-M\right\|_{F}^{2}+16 \lambda \cdot r\right\} .
\end{aligned}
$$

Recall that $\min _{M: \operatorname{rank} M=r}\left\|M^{*}-M\right\|_{F}^{2}=\sum_{K=r+1}^{r^{*}} \sigma_{K}\left(M^{*}\right)^{2} \cdot \mathbf{1}_{r<r^{*}}$ to get the final result.

## 6 Auxiliary results

```
Algorithm 1 Data-driven procedure for selecting \(\bar{r}\) and \(\lambda\)
Input: data X, Y
Require: \(n p \geq(m \wedge q) r_{X}>0\)
Define: \(\widehat{\sigma}_{r}^{2}:=\frac{\left\|Y-\hat{A}_{r} X \hat{B}_{r}\right\|_{F}^{2}}{n p-(m \wedge q) r_{X}}\)
Define: \(\lambda(\sigma):=4(n+p) \sigma^{2}\)
Define: \(\hat{r}_{\lambda}:=\arg \min _{r \in\left[n \wedge p \wedge r_{X}\right]}\left(\left\|Y-\hat{A}_{r} X \hat{B}_{r}\right\|_{F}^{2}+\lambda \cdot r\right)\)
Initialize: \(r \leftarrow r_{X} \wedge n \wedge p, \bar{r} \leftarrow \hat{r}_{\lambda\left(\widehat{\sigma}_{r}^{2}\right)}\)
    while \(\bar{r}<r\) do
        \(r \leftarrow \bar{r}\)
        \(\bar{r} \leftarrow \hat{r}_{\lambda\left(\hat{\sigma}_{r}^{2}\right)}\)
    end while
    Output: \(\bar{r}, \lambda\left(\widehat{\sigma}_{\bar{r}}^{2}\right)\)
```

Acknowledgment. The authors thank the French National Research Agency (ANR) under the grant Labex Ecodec (ANR-11-LABEX-0047).

## References

[1] Francis R Bach. Consistency of trace norm minimization. The Journal of Machine Learning Research, 9:1019-1048, 2008.
[2] Xin Bing, Florentina Bunea, and Marten Wegkamp. Optimal estimation of sparse topic models. The Journal of Machine Learning Research, 21(1):7189-7233, 2020.
[3] Xin Bing and Marten H. Wegkamp. Adaptive estimation of the rank of the coefficient matrix in high-dimensional multivariate response regression models. Ann. Statist., 47(6):3157-3184, 2019.
[4] Lucien Birgé and Pascal Massart. Minimal penalties for gaussian model selection. Probability theory and related fields, 138:33-73, 2007.
[5] Florentina Bunea, Yiyuan She, and Marten H. Wegkamp. Optimal selection of reduced rank estimators of high-dimensional matrices. The Annals of Statistics, 39(2):1282-1309, 2011.
[6] Rong Chen, Han Xiao, and Dan Yang. Autoregressive models for matrix-valued time series. Journal of Econometrics, 222(1):539-560, 2021.
[7] David Donoho and Victoria Stodden. When does non-negative matrix factorization give a correct decomposition into parts? Advances in neural information processing systems, 16, 2003.
[8] Jianqing Fan, Yuan Liao, and Martina Mincheva. High dimensional covariance matrix estimation in approximate factor models. Annals of statistics, 39(6):3320, 2011.
[9] Christophe Giraud. Low rank multivariate regression. Electron. J. Stat., 5:775-799, 2011.
[10] Nan-Jung Hsu, Hsin-Cheng Huang, and Ruey S. Tsay. Matrix autoregressive spatiotemporal models. J. Comput. Graph. Statist., 30(4):1143-1155, 2021.
[11] Zheng Tracy Ke and Minzhe Wang. Using svd for topic modeling. Journal of the American Statistical Association, pages 1-16, 2022.
[12] Olga Klopp, Yu Lu, Alexandre B. Tsybakov, and Harrison H. Zhou. Structured matrix estimation and completion. Bernoulli, 25(4B):3883-3911, 2019.
[13] Olga Klopp, Maxim Panov, Suzanne Sigalla, and Alexandre Tsybakov. Assigning topics to documents by successive projections. arXiv preprint arXiv:2107.03684, 2021.
[14] Vladimir Koltchinskii, Karim Lounici, and Alexandre B. Tsybakov. Nuclear-norm penalization and optimal rates for noisy low-rank matrix completion. Ann. Statist., 39(5):2302-2329, 2011.
[15] Chen Kun, Dong Hongbo, and Chan Kung-Sik. Reduced rank regression via adaptive nuclear norm penalization. Biometrika, 100:901-920, 2013.
[16] Sahand Negahban and Martin J Wainwright. Estimation of (near) low-rank matrices with noise and high-dimensional scaling. Proceedings of the 27 th International Conference on Machine Learning, 2011.
[17] Sahand N. Negahban, Pradeep Ravikumar, Martin J. Wainwright, and Bin Yu. A unified framework for high-dimensional analysis of $M$-estimators with decomposable regularizers. Statist. Sci., 27(4):538-557, 2012.
[18] Guillaume Obozinski, Martin J. Wainwright, and Michael I. Jordan. Support union recovery in high-dimensional multivariate regression. Ann. Statist., 39(1):1-47, 2011.
[19] Angelika Rohde and Alexandre B Tsybakov. Estimation of high-dimensional low-rank matrices. The Annals of Statistics, 39(2):887-930, 2011.
[20] Roman Vershynin. High-dimensional probability, volume 47 of Cambridge Series in Statistical and Probabilistic Mathematics. Cambridge University Press, Cambridge, 2018. An introduction with applications in data science, With a foreword by Sara van de Geer.

