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▶ To cite this version:

Carole Delenne, Vincent Guinot, Bernard Cappelaere. Weak form-based objective functions in hydrology Application to a 1D transport/degradation model. EGU General Assembly 2011, Apr 2011, Vienna, Austria. hal-04385241

HAL Id: hal-04385241 https://hal.science/hal-04385241v1

Submitted on 10 Jan 2024

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WEAK FORM-BASED OBJECTIVE FUNCTIONS IN HYDROLOGY APPLICATION TO A 1D TRANSPORT/DEGRADATION MODEL



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Context and Objective

Weak form-based objective functions (WOF) can be a good alternative to the classical distance-based functions (DOF) for model calibration [1]. WOF are monotone with respect to a given parameter when the sensitivity of the model output keeps a constant sign; then:

- The calibration problem is changed from an optimization problem into a root finding problem
- WOF are less prone to local extrema (when one parameter is to be calibrated, they have a single optimum)
- When several parameters are calibrated, their redundancy can be assessed by superimposing the contour lines of different WOF.

The objective is to apply WOF to the calibration of the degradation coefficient (k(t) depending on time) of a 1D pollutant transport/degradation model.

Model

Continuity and transport/degradation equations:

section:
$$A$$
 discharge: Q contaminant concentration: C degradation coefficient: k
$$\frac{\partial A(x,t)}{\partial t} + \frac{\partial Q(x,t)}{\partial x} = 0$$
 Simplified system

ow velocity:
$$u = Q/A$$

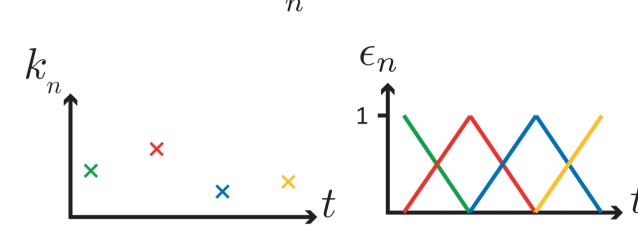
$$\frac{\partial C(x,t)}{\partial t} + u($$

Hypotheses:

Drawbacks of WOF:

- Water elevation controlled so that A independent of time $\Rightarrow Q$ independent of space
- -k(t) piecewise linear

$$k(t) = \sum_{n} k_n \epsilon_n$$



what does «as close as possible»

Calibration process

Requires observations / measurements

- The primary variable C(x,t) cannot be measured easily
- Use of a secondary variable: C(L,t) at the outlet
- Model output «as close as possible» to the data
- Classical measures of closeness (DOF): $D_p = \sum |e|^p$
- Weak form-based (monotone wrt k): $W_p = \sum e|e|^p$

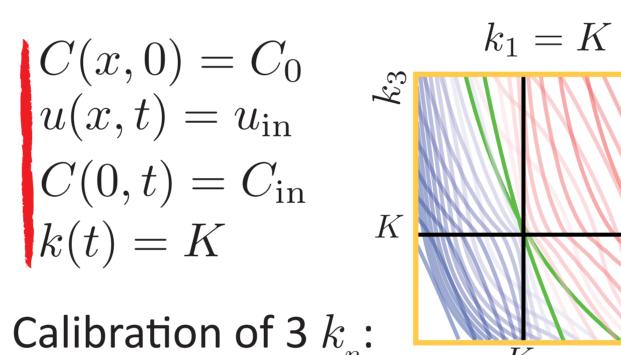
Application

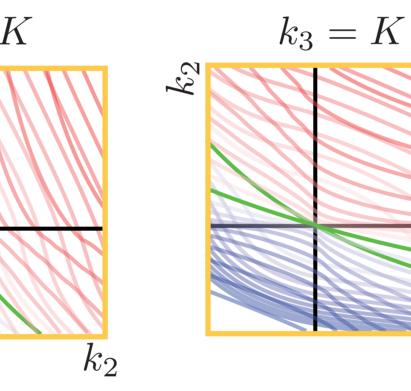
 $k(t) = \sum k_n \epsilon_n$

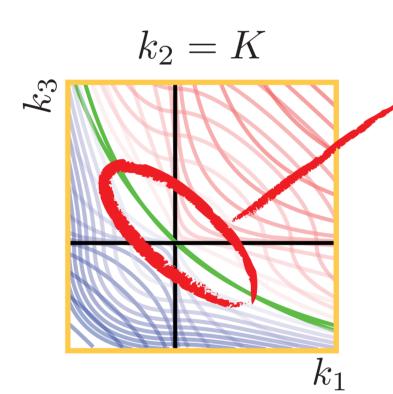
C(x,0) = 0.1 g/l

 $u(x,t) = 25 \pm 10\% \text{ (m/day)}$

Test 1 Generation of «observed» values with all parameters constant.







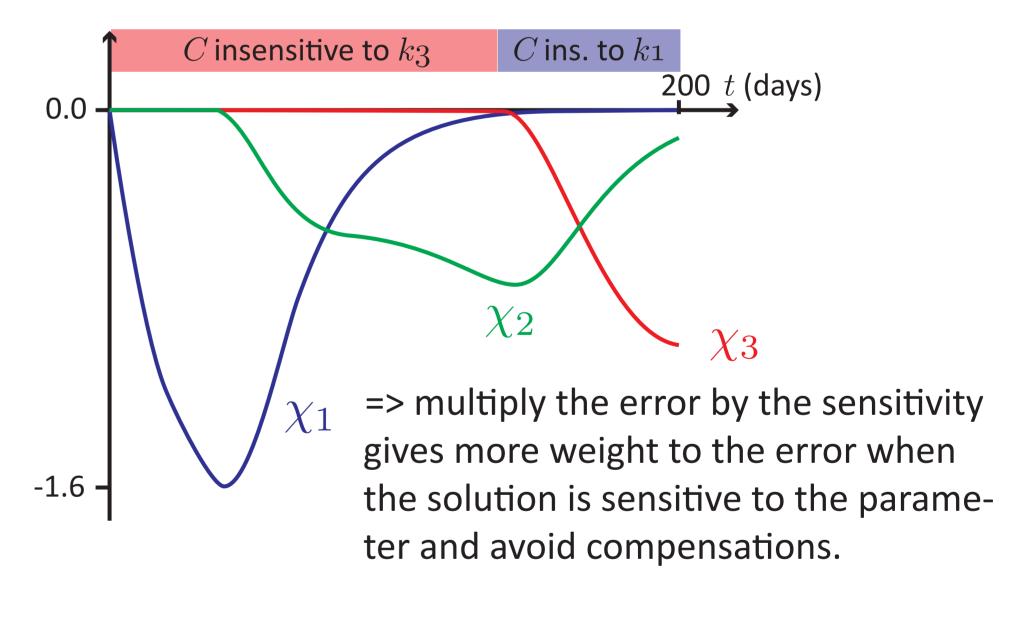




Each parameter calibrated using all the measurements

several values of (k_1,k_3) give acceptable

a parameter should not be calibrated using non-sensitive output for that parameter



Calibration of 1 parameter k_n with WOF:

– Choose a value for p and solve $W_p(k_p)=0$ using e.g.Newton's algorithm:

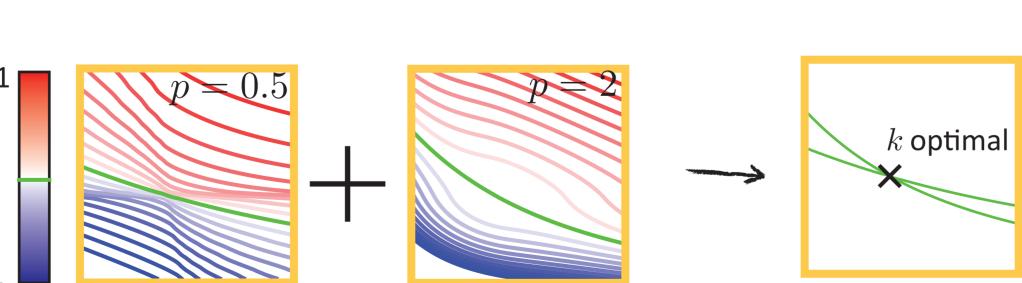
$$k_{i+1}=k_i-\frac{W_p}{W_p'} \quad \text{with } W_p'=p|e|^{p-1}\chi_n \text{ and } \chi_n=\frac{\partial C}{\partial k_n} \qquad \underbrace{\hspace{1cm}} \times \underbrace{\hspace{1cm}}$$

$$\frac{\partial \chi_n(x,t)}{\partial t} + u(x,t) \frac{\partial \chi_n(x,t)}{\partial x} = -k(t)\chi_n(x,t) - \epsilon_n C(x,t)$$

With χ_n obtained by solving the sensitivity equation:

Calibration of n parameters k_n with WOF

– Find the intersection of n WOF with n values for p.







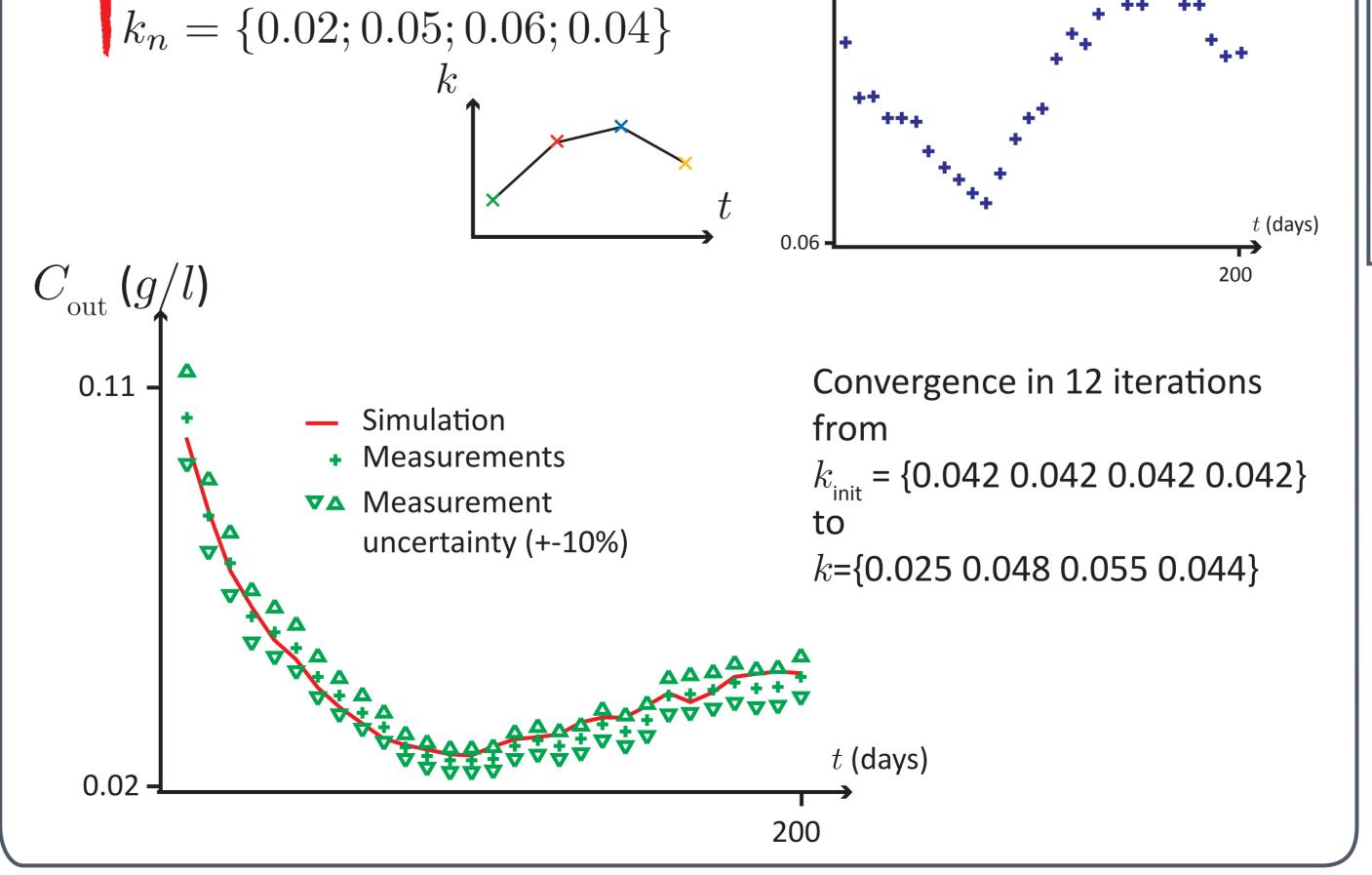
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Model error:

 $e = (C_{\rm sim} - C_{\rm obs})$

Test 2 Generation of «observed» values with variable, noisy input and «measurement» uncertainty

variable & noisy



Conclusions

- Weak form-based OF proves easier to use than distancebased OF in practice
- It is well-admitted that calibration and validation should be carried out using different data sets; we may also admit that they should be carried out using different types of OF!
- Sensitivity analysis can help select measurements to be used for calibration of any given parameter

Reference:

[1] V. Guinot, B. Cappelaere, C. Delenne and D. Ruelland, Towards improved criteria for hydrological model calibration: theoretical analysis of distance- and weak form-based functions, Journal of Hydrology, in press.







