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Mathieu Forget, Sandrine Adiba, Leonardo Gregory Brunnet, Silvia de Monte. Heterogeneous individual motility biases group composition in a model of aggregating cells. *Frontiers in Ecology and Evolution*, 2022, 10, pp.1052309. <10.3389/fevo.2022.1052309>. <hal-04334184>

HAL Id: hal-04334184

<https://hal.science/hal-04334184v1>

Submitted on 12 Dec 2023

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Heterogeneous individual motility biases group composition in a model of aggregating cells

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1 Abstract

2 Aggregative life cycles are characterized by alternating phases of unicellu-
3 lar growth and multicellular development. Their multiple, independent evolu-
4 tionary emergence suggests that they may have coopted pervasive properties
5 of single-celled ancestors. Primitive multicellular aggregates, where coordina-
6 tion mechanisms were less efficient than in extant aggregative microbes, must
7 have faced high levels of conflict between different co-aggregating populations.
8 Such conflicts within a multicellular body manifest in the differential reproduc-
9 tive output of cells of different types. Here, we study how heterogeneity in
10 cell motility affects the aggregation process and creates a mismatch between
11 the composition of the population and that of self-organized groups of active
12 adhesive particles. We model cells as self-propelled particles and describe ag-
13 gregation in a plane starting from a dispersed configuration. Inspired by the
14 life cycle of aggregative model organisms such as *Dictyostelium discoideum* or
15 *Myxococcus xanthus*, whose cells interact for a fixed duration before the onset
16 of chimeric multicellular development, we study finite-time configurations for
17 identical particles and in binary mixes. We show that co-aggregation results in

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18 three different types of frequency-dependent biases, one of which is associated to
19 evolutionarily stable coexistence of particles with different motility. We propose
20 a heuristic explanation of such observations, based on the competition between
21 delayed aggregation of slower particles and of evaporation of faster particles.
22 Unexpectedly, despite the complexity and nonlinearity of the system, biases can
23 be largely predicted from the behaviour of the two corresponding homogenous
24 populations. This model points to differential motility as a possibly important
25 factor in driving the evolutionary emergence of facultatively multicellular life-
26 cycles.

27 Introduction

28 Aggregative life cycles are set to the boundary between unicellular and mul-
29 ticellular organization. In aggregative life-cycles, initially sparse cells come to-
30 gether and form multicellular groups. Multicellular development following ag-
31 gregation is essential for the formation and successive dispersal of stress-resistant
32 dormant cells. Such cysts or spores seed subsequent generations, where cells un-
33 dergo unicellular, vegetative growth (Raper, 1940). Both in prokaryotes, e.g.
34 Myxobacteria, and in eukaryotes, e.g. Dictyostelids, multicellular development
35 is associated with cell differentiation and division of labor, analogous to organ-
36 isms, like metazoans, whose body derives from clonal growth. These two orders,
37 and in particular the model species *Myxococcus Xantus* and *Dyctiostelium dis-*
38 *coideum*, have thus been extensively regarded as highly informative on the tran-
39 sition from unicellular to multicellular organization (Strassmann and Queller,
40 2011; Forget et al., 2021; Vos and Velicer, 2009; Kraemer and Velicer, 2011).

41 A key feature of aggregative multicellular species is their motility, that al-
42 lows cells to actively pursue their bacterial preys during the solitary phase of
43 the life-cycle, and to engage in a series of collective behaviours, such as swarm-
44 ing (Shi et al., 1993) and collective taxis (Bonner et al., 1950). Individual cell
45 movement moreover allows cells to rapidly coalesce into multicellular aggregates
46 as a response to stressful environmental conditions, typically nutrient exhaus-
47 tion. Attaining collective functions without delay has been argued to constitute
48 an important adaptive advantage to aggregative versus clonal multicellularity
49 (Márquez-Zacarías et al., 2021).

50 As a side effect, it is almost inevitable that motility leads to mixing of
51 heterogenous cells to a much larger extent than in colonies of sessile microbes
52 or clonally growing multicellular organisms. Indeed, genetic chimerism occurs
53 naturally in aggregative multicellular species (Strassmann et al., 2000; Fortunato
54 et al., 2003b; Gilbert et al., 2007; Vos and Velicer, 2009; Kraemer and Velicer,
55 2011; Sathe et al., 2014). Within chimeric aggregates, genotypes reaping group
56 benefits *-i.e.* 'cheaters'– are expected to bear a selective advantage relative

57 to more 'cooperative' types. In the absence of positive assortment, selection
58 favours cheaters over cooperators, as reproductive gains are amplified across
59 cycles of multicellular aggregation. Such 'tragedy of the commons' scenario
60 (Hardin, 1968; Rankin et al., 2007) is commonly invoked as a threat to the
61 evolutionary stability of multicellularity, and of particular relevance close to the
62 transition from single cells to higher levels of integration (Clarke, 2014; Rainey
63 and De Monte, 2014).

64 In the absence of mechanisms that efficiently purge invading cheaters – such
65 as single-cell bottlenecks in clonally growing organisms – aggregative life cycles
66 are particularly fragile to cheating (Strassmann et al., 2000; Vos and Velicer,
67 2009). Theory indeed predicts that a sufficient degree of positive assortment,
68 or high relatedness, is necessary for cooperation to be evolutionarily stable
69 (Fletcher and Doebeli, 2009; Queller, 1994). If cooperators recognize coopera-
70 tors, for instance through mechanisms of kin recognition or green beard effects
71 (Hamilton, 1964), then cooperative groups can be advantaged over excluded
72 cheaters. Even though recognition mechanisms have been identified in *Dic-*
73 *tyostelium*, high segregation efficiency is only attained among distant species
74 (Sathe et al., 2014). Moreover, it is unlikely that highly sophisticated recogni-
75 tion systems were present before the multicellular organization was stabilized,
76 leaving the question open of how positive assortment was first established in
77 primitive multicellular life cycles (Clarke, 2014). More relevant to understand-
78 ing the independent repeated evolution of aggregative life cycles (Grosberg and
79 Strathmann, 2007) seem thus to be passive mechanisms of assortment. An-
80 cestral heterogeneity in individual cell properties, indeed, can be the source of
81 positive assortment also in the absence of cell-cell signalling and recognition.
82 Theoretical explorations have for instance shown that costly adhesive traits are
83 selected if they enhance group cohesion, even when cells reshuffling at every gen-
84 eration brakes identity of descent in multicellular groups (Garcia and De Monte,
85 2013; Garcia et al., 2014, 2015; van Gestel and Nowak, 2016).

86 Here, we focus on heterogeneity in motility as a possible source of assortment
87 when multicellular aggregates are generated by self-organization of moving cells,

88 represented as self-propelled disks that can stick to one another upon encounter
89 (Szabó et al., 2006). Heterogeneity in cell motility is observed both in *Myxo-*
90 *coccus Xanthus* (Vos and Velicer, 2008) and *D. discoideum*, where it has been
91 associated to diverse developmental fates (Azhar et al., 2001) and to efficient
92 foraging (Rossine et al., 2022). Differences in motility, moreover, have been
93 proposed to drive the emergence of life cycles with temporally compartmen-
94 talized phases of aggregation and disaggregation (Miele and De Monte, 2021).
95 A feature of such cycles, as well as of aggregative life cycles, is the collective
96 timescale that cells have at their disposal to aggregate. After a specific time
97 span, multicellular aggregates proceed to further developmental steps, or are
98 dispersed.

99 When different strains co-aggregate, the existence of a succession of well-
100 regulated developmental steps allows to measure their reproductive fitness in
101 terms of the fraction of spores (or cysts) they have produced at the moment
102 of dispersal. In *Dictyostelium*, 'spore bias' of a given strain, *i.e.* the deviation
103 in the proportion of spores of that strain from its proportion in the initial
104 mix, is thus commonly used as a metric for pair-wise comparison of the social
105 behaviour of different cellular populations (Strassmann et al., 2000; Fortunato
106 et al., 2003a; Buttery et al., 2010; Kuzdzal-Fick et al., 2010, 2011; Gilbert et al.,
107 2007). If aggregates all had a similar composition (no segregation), and cells
108 of different types behaved identically during development, spore bias would
109 be essentially set by the proportion of cells that did not join the aggregates,
110 the so-called 'loners' in *D. discoideum* (Dubravcic et al., 2014; Tarnita et al.,
111 2013; Martínez-García and Tarnita, 2016) or 'peripheral rods' in *M. xanthus*
112 (O'Connor and Zusman, 1991). The propensity of aggregative species to give rise
113 to non-aggregated cells has been proposed to be key to survival in unpredictably
114 fluctuating environments, and to the maintenance of diversity in natural settings
115 (O'Connor and Zusman, 1991; Dubravcic et al., 2014; Tarnita et al., 2015). If it
116 is known that the propensity of cells to aggregate depends on context (both on
117 the abiotic and biotic environmental conditions (Rossine et al., 2020; O'Connor
118 and Zusman, 1991)), the mechanisms determining how many and what cells are

119 more likely to aggregate are still unknown.

120 We leverage numerical methods developed in active matter physics to ex-
121 plore how heterogeneity in motility affects aggregation biases. Previous studies
122 on Brownian particles with different activity have focused on dense mixtures,
123 where Motility-Induced Phase Separation gives rise to the coexistence of a gas
124 of isolated particles with aggregates, even in the absence of adhesive forces be-
125 tween particles (Stenhammar et al., 2015; Rogel Rodriguez et al., 2020; Kolb
126 and Klotsa, 2020). Within aggregates, moreover, motility differences result in
127 sorting, with further implications in multicellular development (Beatrici and
128 Brunnet, 2011).

129 We characterize finite-time aggregation patterns in low-density binary mixes
130 of adhesive particles that only differ for their intrinsic motility. Given the po-
131 tential implications of such motility differences in the evolutionary origin of
132 aggregative multicellular life cycles, we propose a criterion to infer aggregation
133 bias in binary mixes from the properties of homogeneous populations. More-
134 over, we address the dependence of aggregation biases on the frequency of cells
135 of different motility, showing that non-trivial outcomes are possible, though not
136 all that could be expected to occur. A particularly interesting case is the es-
137 tablishment of frequency-dependent selection associated to the evolutionarily
138 stable coexistence of different motility types.

139 **Methods**

140 *Source code*

141 Simulations were performed using the Python language. The *Pytorch* li-
142 brary (Paszke et al., 2019) for tensor computation allowed us to reduce the
143 computational time while working with a large number of particles ($N = 10^4$).
144 The source code for the simulation can be found online ([https://github.com/
145 MathieuForget/HeteroSpeed_Aggregation.git](https://github.com/MathieuForget/HeteroSpeed_Aggregation.git)).

146 *Identification of aggregates*

147 Aggregates are defined as groups of at least 5 aggregated particles. To be
148 considered as aggregated, a particle has to be connected to at least 4 others par-
149 ticles in the final state of the simulation. Two particles are considered connected
150 if their pairwise distance is lower than R_0 .

151 *Variance in aggregates composition*

152 In order to quantify the level of segregation between the two particles types
153 in a binary mix, the variance in aggregate composition was scored and then nor-
154 malized by its maximum theoretical value. For each simulation, this maximum
155 value is computed by estimating the variance in aggregates composition after
156 having artificially segregated aggregated particles by dividing each type in ag-
157 gregates of size equal to the mean observed aggregates size. This corresponds to
158 a case where the same number of particles have aggregated, but they only group
159 with those of their same type. The normalized variance in aggregate composi-
160 tion thus goes from 0, when the particles are well mixed in the aggregates, to 1,
161 when the two particles types are completely segregated into distinct aggregates,
162 each composed by only one type of particles (Fig. 3B).

163 *Bias in aggregates composition*

164 At the end of each simulation, the mean proportion of each population in
165 the aggregates is estimated. The bias in aggregate composition of the focal
166 population is measured as the deviation between its mean proportion in the
167 aggregates and its proportion in the mix.

168 *Particles connectivity*

169 The number of particles that are closer than R_0 to a focal particle is used
170 as a proxy for its connectivity. We estimated populations mean connectivity
171 by averaging the connectivity of aggregated particles of a given type. In binary
172 mixes, the relative connectivity of this type was estimated as the deviation
173 between its mean connectivity and that of the other type of particles.

174 **Results**

175 *A self-propelled particles model for the aggregation of motile cells.*

176 In order for aggregation to bring together cells of different populations, cells
 177 need to be motile. Different aggregative organisms have different types of motil-
 178 ity and different shapes. Here, we consider a simple representation of moving
 179 cells as persistent Brownian walkers. This representation corresponds to obser-
 180 vations of single-cell motility in *Dictyostelium discoideum* (Golé et al., 2011; Li
 181 et al., 2011), and was used to model collective behaviour of keratocytes popu-
 182 lations (Szabó et al., 2006). Single cells are represented as self-propelled disks
 183 of equilibrium radius $R_{eq}/2$ (R_{eq} being the equilibrium distance between two
 184 interacting particles) that interact within a finite range R_0 . Interaction forces
 185 determine, together with stochastic fluctuations, the position of each disk and
 186 the orientation of each particle’s velocity. In order to avoid to define their be-
 187 haviour at the boundaries, particles are let move in a square of side L with
 188 periodic boundary conditions.

189 The equation of motion of a particle i with position $\mathbf{r}_i \in [L, L]$ is:

$$\frac{d\mathbf{r}_i}{dt} = v_0 \mathbf{n}_i + \mu \sum_{j=1}^N \mathbf{F}(d_{ij}). \quad (1)$$

190 where v_0 is the self-propelled speed of particle i , whose direction is given by a
 191 polarization unitary vector \mathbf{n}_i , N is the population size, and \mathbf{F} is the interaction
 192 force between particles i and j , that only depends on their Euclidean distance
 193 $d_{ij} = \|\mathbf{r}_j - \mathbf{r}_i\|$. The mobility parameter μ ensures dimensional consistence, and
 194 is set to 1 without loss of generality.

195 Cell-cell adhesion acts only on cells that are not too far apart. The model
 196 considers a radial, finite-range interaction force \mathbf{F} that is piecewise-linear in the
 197 distance d_{ij} (Fig. 1A). If $d_{ij} \leq R_{eq}$, the two particles i and j repulse each
 198 other strongly, in order to account for cell volume exclusion. If $R_{eq} < d_{ij} \leq R_0$,
 199 the two particles attract each other with an elastic force of intensity F_{adh} that
 200 quantifies adhesion strength. This choice reflects the possibility that cell shape

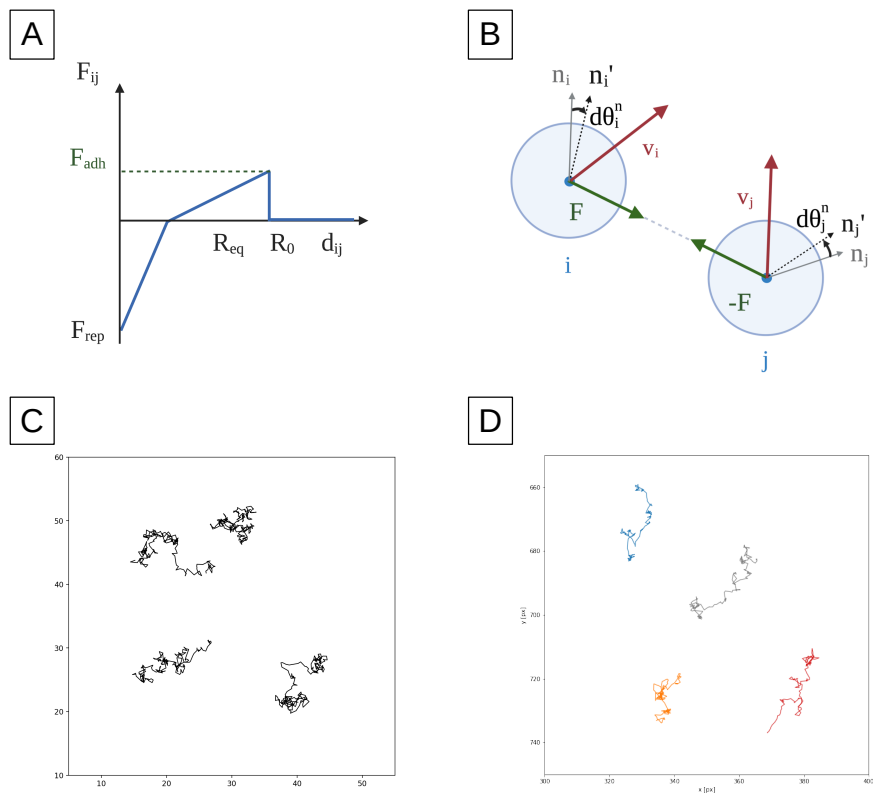


Figure 1: **Self-propelled particle model for migrating and interacting cells.** (A) Finite-range interaction forces $\mathbf{F}(d_{ij})$ between two particles of positions \mathbf{r}_i and \mathbf{r}_j and velocities \mathbf{v}_i and \mathbf{v}_j (accounting for both auto-propulsion and interaction forces, according to eq. 1) contribute to align \mathbf{n}'_i and \mathbf{n}'_j ($\mathbf{n}' = \mathbf{n}(t + dt)$), the direction of particles' auto-propelled velocities. These forces only act when the Euclidean distance $d_{ij} = |\mathbf{r}_i - \mathbf{r}_j| \leq R_0$. See text for the definition of the other variables. (B) Radial component of the force between the two particles. When $d_{ij} < R_{eq}$, particle i exerts a strong repulsive force on particle j . Otherwise, within the range of interaction R_0 , the latter attracts particle j with a weaker elastic force, representing adhesion between different cells. (C) Typical trajectories of isolated particles during a simulation ($t_f = 100$) using parameters values indicated in table S1 indicate that, in the absence of interactions, particles follow a persistent random walk resembling that of *Dictyostelium*'s single cells. (D) Trajectories of starved *Dictyostelium* cells recorded every 30 seconds during 1 hour.

201 deformation allows cells to be more distant than twice their equilibrium radius.

202 The radial force is thus defined as:

$$\mathbf{F}(d_{ij}) = \mathbf{e}_{ij} \begin{cases} F_{rep} \frac{d_{ij} - R_{eq}}{R_{eq}} & d_{ij} < R_{eq} \\ F_{adh} \frac{d_{ij} - R_{eq}}{R_0 - R_{eq}} & R_{eq} \leq d_{ij} \leq R_0 \\ 0 & R_0 \leq d_{ij} \end{cases} \quad (2)$$

203 where $\mathbf{e}_{ij} = \frac{\mathbf{r}_i - \mathbf{r}_j}{\|\mathbf{r}_i - \mathbf{r}_j\|}$ is the unitary vector connecting the centers of the two
204 particles.

205 The force \mathbf{F} and its action on particles' self-velocity are represented in Figs.
206 1A and B. In the simulations, time is discretized in steps of (short) duration dt .
207 Between two successive time steps, interaction forces induce a small incremental
208 change in the angle $\theta_i^n(t) = \arcsin(\mathbf{n}_i(t))$ of particle self-propelling velocity.
209 Even though there is no direct velocity alignment in this model, the action of
210 the force is to reduce the deviation of the particle velocity from the scattering
211 direction $\mathbf{v}_i = \frac{d\mathbf{r}_i}{dt}$ defined by eq. 2. Such a relaxation happens on the timescale
212 τ . The equation of motion for the angle is therefore:

$$\frac{d\theta_i^n}{dt} = \frac{1}{\tau} \arcsin \left[\left(\mathbf{n}_i \times \frac{\mathbf{v}_i}{|\mathbf{v}_i|} \right) \cdot \mathbf{e}_z \right] + \eta \xi_i \quad (3)$$

213 where \mathbf{e}_z is a unit vector orthogonal to the plane of motion. The cross product
214 is null when the velocity and the force are aligned, case in which the direction
215 of motion will not be altered by particles interaction.

216 In isolation (*i.e.*, in the absence of interaction forces $\mathbf{F} = 0$), particles move
217 as persistent random walkers. Typical trajectories, shown in Fig. 1C, are consis-
218 tent with previous (Golé et al., 2011; Li et al., 2011) and our own (Fig. 1D) ex-
219 perimental observation of individual *Dictyostelium discoideum* cells trajectories.
220 The orientation θ_i^n of the self-propelled velocity $v_i = v_0 \mathbf{n}_i$ (Eq. 1) is described
221 by a Wiener process (Huang and Cambanis, 1978), where a white angular noise
222 term $\eta \xi_i$ is added between successive time steps. $\xi_i(t)$ is a random variable
223 chosen with a uniform probability on the interval $[-2\pi, 2\pi]$, uncorrelated across
224 successive time steps. The noise intensity η defines the characteristic timescale
225 $\tau_r = 1/\eta^2$ of persistence of the random motion. The larger the angular noise,
226 the less persistent is the motion of the particle.

227 In the following, we will consider situations where τ_r is small (large η) com-
228 pared to the characteristic relaxation time τ , so that aggregates do not display
229 collective motility (in such regime, extensively studied in active matter (Grégoire
230 et al., 2003; Casiulis et al., 2020), groups are less well-defined than in cases where
231 particles form long-lived, quasi-stationary aggregates).

232 The self-propelled particles model was implemented through a custom Python
233 program ([https://github.com/MathieuForget/HeteroSpeed_Aggregation.](https://github.com/MathieuForget/HeteroSpeed_Aggregation.git)
234 [git](https://github.com/MathieuForget/HeteroSpeed_Aggregation.git)). Model’s parameters (collected in table S1) were set as described in the
235 Supplementary Information to reproduce the aggregation of a fraction of parti-
236 cles in multiple non-motile aggregates, with some particles remaining isolated,
237 similar to what is observed for aggregative multicellular species (Dubravcic et al.,
238 2014; O’Connor and Zusman, 1991).

239 *Finite-time states of homogeneous populations.*

240 We first explored how the system’s parameters affect the patterns of ag-
241 gregation of particles with identical velocities. Particular attention was given
242 to two parameters that can be controlled or at least measured in experiments,
243 and that are known to influence encounter rates among particles: the packing
244 fraction ρ and the particles’ self-propulsion speed v_0 .

245 The packing fraction is the ratio between the areas covered by the parti-
246 cles relative to the total area of the simulation space. It is thus proportional
247 to the population density, which is straightforward to tune in experimental set-
248 tings, and is known to critically affect collective behaviour in aggregative species
249 (Hashimoto et al., 1975). As motivated in the introduction, the speed of particle
250 displacement v_0 is interesting because heterogeneity in cell motility is known to
251 exist in aggregative species (Goury-Sistla et al., 2012; Vos and Velicer, 2008),
252 and it can be altered by changing growth conditions in the lab (Varnum et al.,
253 1986). Particle encounters become more likely when both packing fraction and
254 velocity are increased. However, increasing one or the other is not equivalent.

255 The self-organized patterns reached after a finite time by a population of
256 identical particles were examined for different values of speed v_0 and packing

257 fraction ρ (Fig. 2). Simulations were run for a fixed duration t_f . This choice
258 reflects the fact that cells do not have an infinite time at their disposal to
259 complete aggregation. In biological populations, such a timescale is set by the
260 duration of different phases of the life cycle or, for ancestral unicellular types,
261 by environmental variation. In the final state – analysed whether the system
262 had converged to its asymptotic configuration or not – aggregates were defined
263 as groups of at least 5 particles as described in the Methods. The setting of
264 a size threshold reflects the observation that in *Dictyostelium* aggregate speed
265 is positively correlated to size (Rieu et al., 2005; Bonner, 1995), so that small
266 slugs have impaired collective motility, and possibly development. Therefore,
267 their contribution to successive generations is akin to that of solitary cells.
268 More generally, size-dependence is a shared feature of many collective functions,
269 which require a quorum of composing cells for selection to start acting on them
270 (Cornforth et al., 2012).

271 At very low packing fractions, the system does not display any sizeable
272 aggregate. Indeed, particles do not have the time to overcome the average
273 distance that initially separates them. The same is true for denser populations
274 when either particles are very slow, or they are very fast. In both cases, the
275 final state is gas-like. For intermediate velocities and larger densities, particles
276 form aggregates of different geometry. Figures 2 and S1 represent, overlaid
277 to the heatmap of the fraction of aggregated particles, the final snapshot of
278 simulations and the variation in time of different population-level statistics.
279 Different possible qualitative outcomes of the aggregation process illustrated
280 there are discussed below.

281 At low packing fraction ρ and low velocity v_0 , particles self-organize into
282 a large number of relatively small aggregates (Fig. 2, case A). The isotropy
283 of the clusters reflects the homogeneity of the initial particle distribution. At
284 the end of the simulations, a sizeable fraction of particles are found outside
285 the aggregates. As indicated by the monotonous increase in the fraction of
286 aggregated particles over time (Fig. S1A), this is a finite-time effect and every
287 particle would eventually aggregate for higher t_f values (Fig. S2). Under these

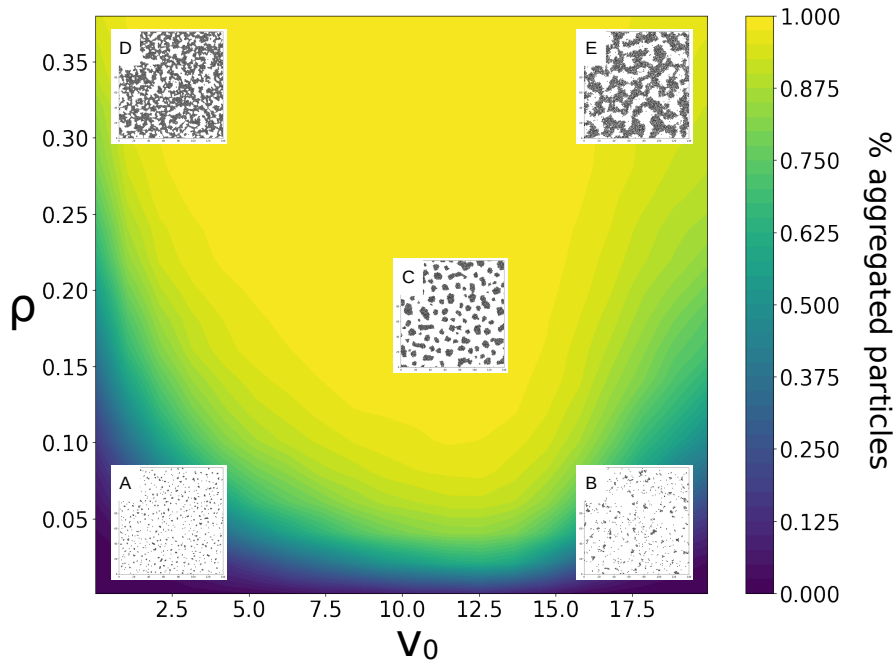


Figure 2: **Finite-time state diagram for a population of identical particles of speed v_0 and packing fraction ρ .** The fraction of aggregated particles at the end of the simulation ($t_f = 100$) is illustrated as a heatmap, indicating that the highest fraction of aggregated particles is reached for intermediate particle speeds. Overlaid, snapshots illustrate the final particle distribution for five cases (A, B, C, D, and E), whose aggregation dynamics is discussed in more detail in Supp. Fig. S1. Fixed parameters values are those indicated in table S1. The packing fraction was varied by changing L , keeping N constant.

288 conditions, the fate of each particle therefore depends on its local environment
 289 at the beginning of the simulation. This parallels the hypothesis by Rossine *et*
 290 *al* that local fluctuations in the concentration of a quorum signal explains why
 291 some *Dictyostelium* cells end up as loners at the end of aggregation (Rossine
 292 *et al.*, 2020).

293 At high particle speed and low packing fraction (Fig. 2, case B), the num-
 294 ber of aggregates quickly reaches a plateau and then slowly decreases, whereas
 295 aggregate mean size constantly increases over time (Fig. S1 B). Similarly to an
 296 Ostwald ripening process (Ostwald, 1896), particles evaporate (*i.e* detach) from

297 small groups to join bigger and more stable aggregates (Fig. S2). Aggregate
298 accretion is essentially limited by particles evaporation, causing a fraction of
299 particles to be always found outside the aggregates.

300 By continuously increasing particle speed at low packing fraction, the system
301 transitions between the two previously described states where particle clusters
302 coexist with non-aggregated particles. The latter have however different origin
303 depending on particle speed. At low particle speed, aggregation leaves out
304 "latecomer" particles that did not reach any aggregate within the finite time
305 of the simulation; at high speed, the "gas-like phase" is composed by particles
306 that have evaporated from aggregates. Increasing particle speed, the transition
307 between these two scenarios occurs through a phase where aggregation is very
308 efficient. The fraction of aggregated particles, indeed, first increases and then
309 decreases, and reaches a maximum at the optimal speed v_{opt} , which depends
310 weakly on the packing fraction ρ .

311 At such intermediate velocity and packing fractions (illustrated in Fig. 2,
312 case C), self-organization leads to the formation of multiple rounded aggregates,
313 that contain almost every particle. For much longer simulation times, aggregates
314 would coarsen and progressively merge into one single aggregate of size N , as
315 indicated by the combined decrease in aggregate number and increase in mean
316 size (Fig. S1, C). Such coarsening process however is largely irrelevant for
317 aggregation over finite times.

318 Finally, at higher packing fraction, particles rapidly self-organize into den-
319 dritic structures (Fig. 2, cases D and E). Similarly to what can be observed at
320 lower packing fractions, the few non-aggregated particles at low speed are "late-
321 comers", whereas at high particle speed, non-aggregated particles are "gas-like
322 particles", where – as for MIPS – steric interactions limit the coexistence of
323 multiple independent aggregates (Fily and Marchetti, 2012). The measure of
324 aggregates size is not meaningful under these conditions, the packing fraction
325 being so high that every particle is connected to a large number of other particles
326 virtually from the start.

327 *Differences in motility bias the outcome of aggregation*

328 Variation in particle speed gives rise to different finite-time aggregation pat-
329 terns in homogeneous populations, leading to the production of non-aggregated
330 cells through two qualitatively distinct routes: delayed aggregation and evapo-
331 ration. It is thus natural to expect that mixing particles of different speed would
332 reflect into differential rates of aggregation. It is however not obvious how the
333 emergent aggregation patterns, which result from individual interactions, are
334 related to the collective behaviour of the two particle types in isolation. In
335 order to explore this question, we run simulations of binary mixes of particles
336 with two different constant speeds v_1 and v_2 .

337 Let us first consider two 1:1 binary mixes where particles have self-propelled
338 velocities that are either both to the left, or both to the right of v_{opt} , so that
339 non-aggregated particles stem from the same of the two previously discussed
340 mechanisms (Fig. 3A).

341 Aggregation biases can manifest as differential fractions of particles that
342 aggregate, in aggregate composition, or in the topology of interactions within
343 aggregates. In order to separately discuss those features, we quantified three
344 statistical properties or order parameters (illustrated in Fig. 3B): segregation,
345 aggregation bias and connectivity. These metrics, moreover, are easy enough to
346 be measured in real populations, as long as there is a way to visually distinguish
347 two co-aggregating populations.

348 Segregation measures the degree of heterogeneity in aggregate composition.
349 Under high segregation, which could be expected if particles assorted preferen-
350 tially with those of the same type, the overall behaviour would be the superpo-
351 sition of the patterns of each composing population in isolation. By analysing
352 the final snapshot of a simulation, every aggregate was characterized by its com-
353 position (fraction of particles of each type). The variance of this quantity was
354 normalized by the maximal theoretical variance given the observed number of
355 aggregates and their size, computed when each aggregate is composed of only
356 one type of particles (see Methods). A null value of this metric indicates that
357 the two types are represented in similar proportion in all aggregates, whereas

358 this parameter converges towards 1 as the two types separate in different aggre-
359 gates (Fig 3B). In biological chimeras where cells are able to discriminate and
360 preferentially aggregate with kins (Gruenheit et al., 2017), this order param-
361 eter may therefore be close to 1, whereas in non-segregating populations it is
362 expected to have small values (only vanishing in the limit of infinite population
363 sizes, where fluctuations in the initial position of particles become irrelevant).

364 Aggregation bias was then estimated as the deviation between the mean ag-
365 gregate composition and the proportion of each type of particles in the initial
366 mix. This metric indicates to what extent differences in particle speed skew
367 their ability to aggregate. In aggregative microbes only cells that manage to
368 partake multicellular development have a chance to survive prolonged starva-
369 tion. The aggregation bias measured in chimeras can thus be used as a proxy
370 to connect the outcome of one cycle of aggregation with the long term success
371 of a population, in the absence of further developmentally-induced divergence
372 in cell fate (Dubravcic et al., 2014; Tarnita et al., 2013).

373 Finally, we quantified particles mean within-aggregate connectivity. For each
374 type of aggregated particles, connectivity is measured as the number of parti-
375 cles (of any type) to which a focal particle is connected within an aggregate.
376 Two particles are considered connected at a given time if they are closer than
377 the maximal distance of interaction R_0 (see Methods). High connectivity is
378 associated to a central position within an aggregate, whereas particles with a
379 lower connectivity are located closer to aggregates periphery. Connectivity thus
380 reflects different spatial arrangements within clusters. In extant aggregative
381 microbes, a more central or peripheral positioning can be associated to differen-
382 tial exposition to stress (Smukalla et al., 2008) or to differentiation cues (Julien
383 et al., 2000).

384 Figure 3C displays these three order parameters for two binary mixes of
385 particles with different speed, as per Fig. 3A. We refer to those as 'delayed
386 aggregation' (DA) mix and 'evaporation' (E) mix to signify the different origin
387 of non-aggregated particles.

388 We observed that the level of segregation is comparably low in the two mixes

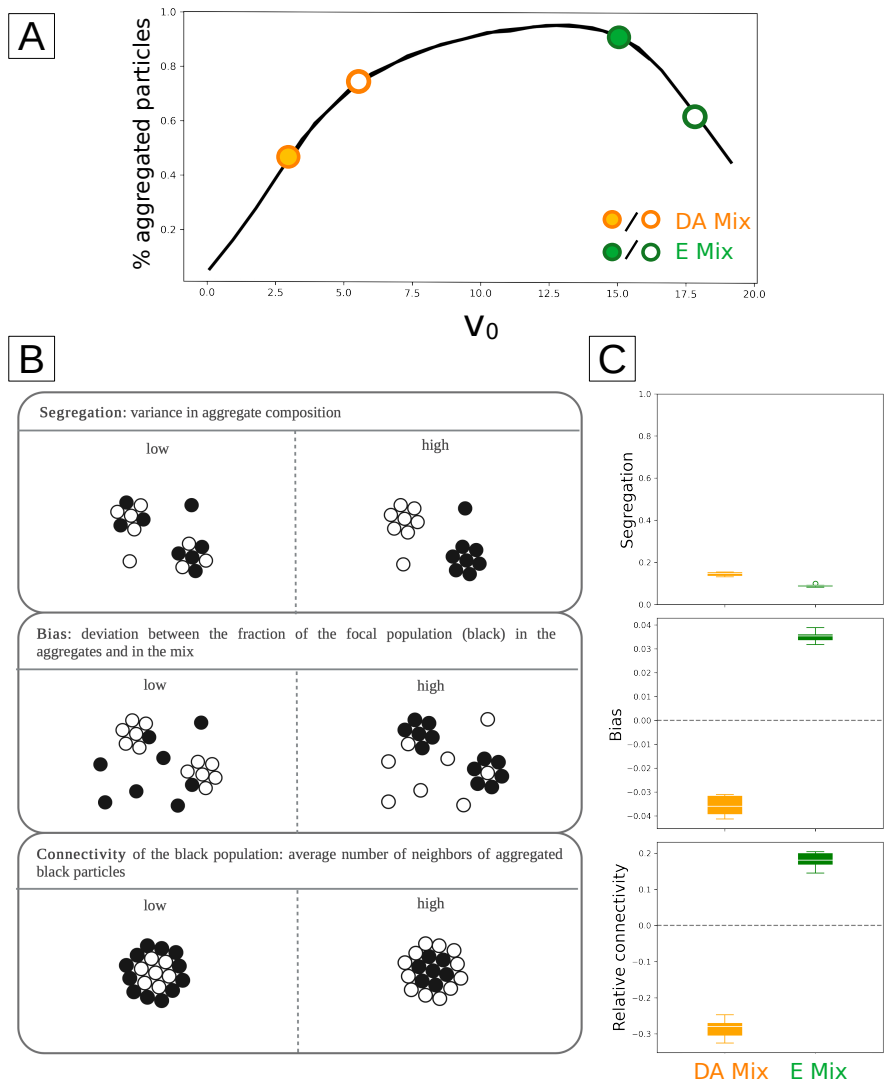


Figure 3: **Effect of heterogeneity in cell motility on the outcome of aggregation in two different types of binary mix.** (A) two populations of particles with different motility (DA mix: $v_1=3$ and $v_2=6$, E mix: $v_1=13$ and $v_2=16$) where mixed in equal proportion ($N = 10^4$, $\rho = 0.07$ for the total population). (B) Order parameters allowing to capture the effect of heterogeneity in particles motility on the outcome of aggregation. (C) Populations segregation, aggregation bias and mean connectivity within the aggregates estimated at the end of 6 independent simulations as described in B.

389 (Fig. 3C), suggesting that different aggregates have similar composition, but
390 statistical fluctuations. In other words, heterogeneity in particles motility does
391 not cause segregation of the two types and the mean aggregate composition is
392 representative of every group. It is therefore meaningful to use it to quantify
393 the effect of heterogeneity in particle speed on the outcome of aggregation.

394 By analysing biases in mean aggregates composition relative to the 1:1 com-
395 position of the mix, we found that the slower type was under-represented in
396 the aggregates (*i.e.* with a negative bias) in the DA mix, whereas the opposite
397 results was found in E mix. Heterogeneity in particle speed thus biases the
398 representation of the two co-aggregating populations in the aggregates, so that
399 particles that aggregate more efficiently in isolation are over-represented in the
400 aggregates. These are the type whose fraction of aggregated particles at $t = t_f$
401 is higher (Fig. 3A), *i.e.* the faster type in the DA mix and the slower type in
402 the E mix.

403 Mean particle connectivity of the two particles types indicates that, more-
404 over, particles that aggregate more efficiently in isolation are enriched in the
405 core of the aggregates. The type whose speed is closer to v_{opt} seems to nucleate
406 the aggregation of the other type and ends up being over-represented in the
407 aggregates at the end of the simulation.

408 *Differences in motility result into three types of frequency-dependent aggregation*
409 *biases.*

410 The process of self-organization responsible for the aggregation biases dis-
411 cussed above results from interactions between particles with different speed. It
412 is hence expected to be sensitive to the proportion of each type of particles in
413 the mix, which underpin the probability that particles of the same or different
414 types encounter. Frequency-dependent biases have been moreover observed in
415 aggregative multicellular species: the intensity of spore bias in *Dictyostelium*,
416 and sometimes even its sign (Sathe and Nanjundiah, 2018; Madgwick et al.,
417 2018), depend on the proportion of cells in the binary mix. Such frequency-
418 dependent social interactions can lead, on the evolutionary timescale, to regimes

419 where contrasting social strategies coexist, as we will discuss later. In order to
 420 identify the possible paths open to the evolution of aggregation in populations
 421 with heterogeneous cell motility, we investigated the effect of binary mix com-
 422 position on aggregation bias.

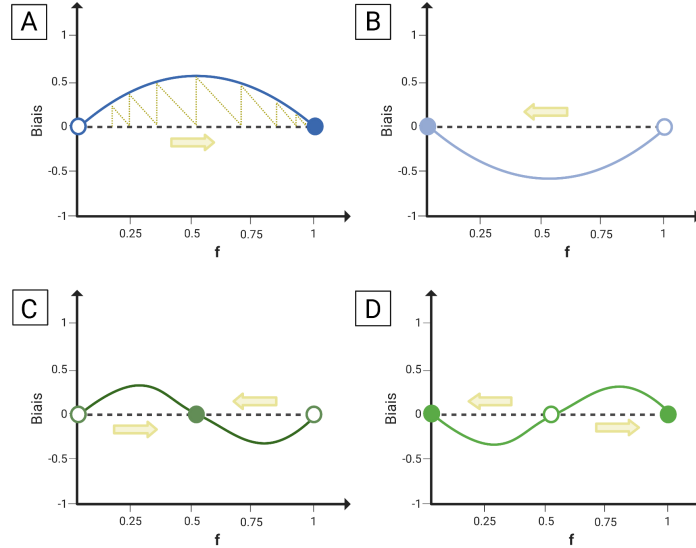


Figure 4: **Four qualitatively different frequency-dependent aggregation biases correspond to distinct evolutionary stable states.** Schematic representation of the four simplest classes of bias that can be obtained in a binary mix. The evolutionary dynamics of a binary mix composition (f) over many rounds of co-aggregation is represented by the yellow arrows. Stable equilibria are represented as filled circles and unstable ones as empty circles. The yellow dotted line in (A) illustrates the construction of the evolutionary trajectory: each round starts with a mix composition equal to the aggregates composition at the end of the previous round, that is obtained by adding to the initial composition the aggregation bias. The four classes of bias give rise to different evolutionary stable solutions: fixation of the focal type (A) exclusion of the focal type (B), coexistence of both types (C) and bistability (D).

423 Let f_1 be the proportion of particles with speed v_1 in the binary mix (then
 424 $f_2 = 1 - f_1$ is the proportion of particles with speed v_2). As indicated in Fig.
 425 4, there are only four qualitative types of biases that are continuous in the
 426 frequency f_1 and change sign at most once in the interval $[0, 1]$. These scenarios
 427 can be classified by looking at the variation of the bias for extreme values of

428 f_1 : when the slope of the bias has the same sign at low and high frequency,
429 the type associated with negative bias gets excluded over evolutionary times
430 (Fig. 4A and B); when there is positive (negative) frequency-dependence at low
431 (high) frequency, coexistence of the two types is evolutionary stable (Fig. 4C);
432 when there is negative (positive) frequency-dependence at low (high) frequency,
433 the monomorphic populations are two alternative evolutionary stable solutions
434 (Fig. 4D). Assuming that every aggregated particle has the same probability
435 of being transmitted to the next generation, which is reasonable for primitive
436 aggregative life-cycles, the shape of the bias in aggregate composition determines
437 the outcome of evolution over repeated cycles of aggregation and dispersal, as
438 exemplified in Fig. 4A.

439 We examined what types of bias could be observed in binary mixtures of
440 particles of different speed, and tried to establish a link to the properties of
441 homogeneous populations of each type on its own. Aggregate composition was
442 analysed in binary mixes of different composition, keeping the packing fraction
443 equal to 0.07. In order to reduce simulation time, we considered only extreme
444 f_1 values ($0 < f_1 < 0.05$ and $0.95 < f_1 < 1$).

445 We expect the aggregation process to be influenced both by the absolute and
446 by the relative value of the velocities of the two types of particles. We have thus
447 explored separately two scenarios: first, the speed of the first type was fixed
448 and that of the second type was changed; second, both speeds were changed,
449 but their difference was kept constant.

450 In the first analysis, the speed of particles of the focal population was set
451 to the 'optimal' value ($v_1 = v_{opt} = 13$) and the speed differential $\Delta v = v_1 -$
452 v_2 between the two particles types was gradually changed from negative to
453 positive. This scan (Fig. S3) confirms the intuition that the better aggregator
454 is always over-represented in the aggregates when mixed with particles with a
455 different speed, whatever the mix composition f_1 . Indeed, the bias in aggregate
456 composition of the better-aggregator (*i.e.* the v_1 -population) is systematically
457 positive at both low and high f_1 values. Moreover, the slope of the bias for low
458 and high f_1 increases with $|\Delta v|$, indicating that the bias intensity is positively

459 correlated with the level of heterogeneity between the two particles types.

460 In the second type of binary mix, where the speed differential Δv is kept
 461 constant while particle speeds are simultaneously increased, the slopes at ex-
 462 tremite frequencies instead change sign (Fig. S4). Besides the two cases where
 463 one particle type dominates for any frequency (Fig. 4 A and B), we observed
 464 also the frequency-dependent profile that predicts long-term coexistence (Fig. 4
 465 C). The latter occurs when binary mixes are composed of particles whose speed
 466 is on opposite sides of v_{opt} (Fig. S4, third and fourth row). The bias is in favor
 467 of the slower particles when they are at low frequency in the mix, whereas at
 468 high frequencies they are under-represented in the aggregates.

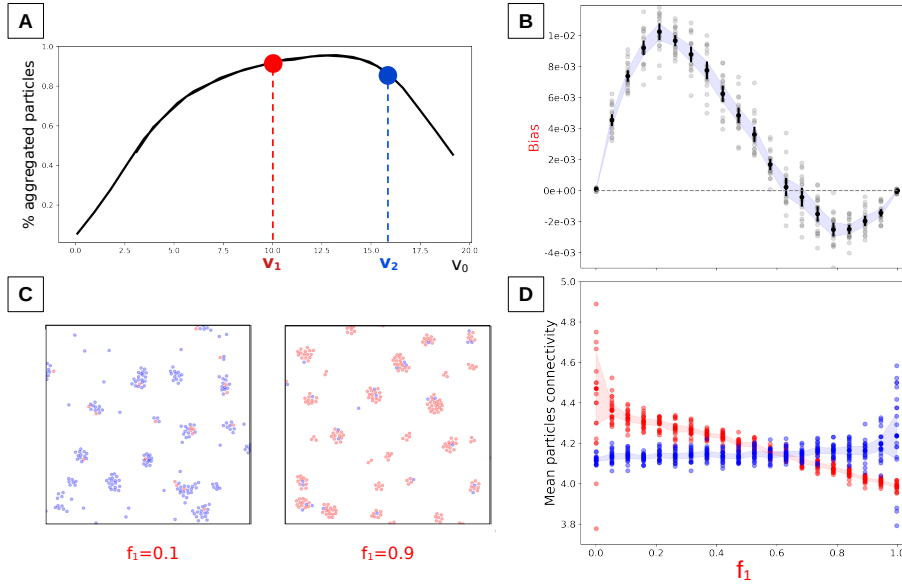


Figure 5: **Heterogeneity in particle speed induces biases whose sign depends on composition of the binary mix.** (A) Binary mix of particles with speed on both sides of v_{opt} . (B) Aggregation bias of the slower population when mixed in different proportion (f_1) with the faster population. (C) Zoom on snapshots of the final state of the system for $f_1 = 0.1$ and $f_1 = 0.9$. (D) Mean connectivity of the two types of aggregated particles as a function of f_1 . (B and D) Twenty independent simulations were run were for each f_1 value. The shaded area represents the 95% confidence interval.

469 Biases in aggregates composition however appear rather weak and noisy

470 (as indicated by the large confidence intervals). We thus ran 20 independent
471 simulations for f_1 values ranging from 0 to 1 and using a larger speed differential
472 ($\Delta v = 6$) to confirm that binary mixes composed of particles whose speed
473 falls on different sides of v_{opt} sustain long-term coexistence. As expected, this
474 combination yielded a more conspicuous and less variable bias (Fig. 5B).

475 Mean connectivity of aggregated particles for the two particles types pro-
476 vided mechanistic information on the underpinning of such frequency-dependent
477 bias. Figure 5D shows that particles with higher connectivity *-i.e.* more central
478 in the aggregates – are over-represented in the aggregated fraction, irrespective
479 of their speed, consistent with previous observations (Fig. 3C). When slow par-
480 ticles are in low proportion in the mix, aggregates are essentially composed of
481 fast particles. In such aggregates, fast particles have lower connectivity (Fig.
482 5C and D), *i.e.* a peripheral location, so that they can be pushed out of the
483 aggregate by stochastic fluctuations and evaporate. Slow particles, on the other
484 hand, have a high chance of being integrated in an aggregate quickly formed by
485 fast particles, hence the positive bias in aggregates composition is in their favor.
486 When slow particles are in high proportion in the binary mix, they prevail in the
487 aggregates. Due to their higher speed, fast particles join aggregates earlier and
488 are thus located closer to the aggregates center than slow particles (Fig. 5C).
489 The central location of fast particles prevents their evaporation, and delayed
490 aggregation simultaneously causes slow particles to be under-represented in the
491 aggregates. On longer timescales, however, all slow particles join an aggregate,
492 and fast particles are expected to sort to the periphery of aggregates (?). The
493 bias against particles that are too slow to aggregate is therefore expected to
494 progressively vanish as the time t_f available to aggregate increases.

495 Numerical simulations of the binary mix of Fig. 5 were run for twice and
496 five times longer time spans ($t_f = 200$ and $t_f = 500$). As predicted, the range of
497 f_1 values for which the slower particles are under-represented in the aggregated
498 fraction decreases accordingly, and vanishes for the longest period (Fig. 6).

499 When aggregation lasts long enough, so that all particles end up aggregating,
500 evaporation of fast particles is thus the only source of aggregation biases. Hence,

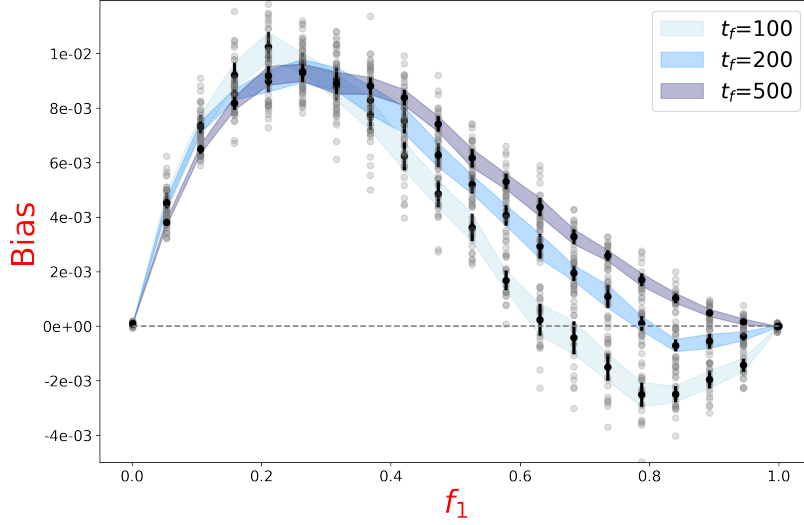


Figure 6: **Prolonged aggregation mitigates the frequency-dependent inversion of bias.** Aggregation bias of the v_1 -population as a function of its frequency f_1 in a binary mix of particles ($v_1 = 10$ and $v_2 = 16$), estimated after different simulation time (t_f). 20 replicates were performed for each f_1 value. The shaded area represents the 95% confidence interval.

501 only the bias in favour of slower particles (Fig. 4) is asymptotically observed.
 502 As a consequence, the existence of life cycles that bound the duration of the
 503 aggregation phase could support the evolutionary maintenance of highly motile
 504 cells, being otherwise counter-selected, and simultaneously the establishment of
 505 a polymorphic equilibrium.

506 Alongside particle speed, adhesion strength is certainly a parameter that
 507 plays a key role in determining the outcome of an aggregation process. More-
 508 over, it is likely to be heterogeneous in cellular populations. The complete
 509 examination of the interplay of speed and adhesion heterogeneity is beyond the
 510 scope of this work, however it is important to consider the extent to which the
 511 conclusions drawn so far keep holding when adhesion strength is varied.

512 *Biases induced by heterogeneity in particles motility depend predictably on par-*
513 *ticles adhesion strength.*

514 In addition to particle speed and packing fraction (Fig. 2), particle adhe-
515 sion strength is also expected to affect aggregation efficiency. This parameter
516 indeed determines the probability that two particles stick together when they
517 encounter. Increasing particles adhesion strength can thus be expected to re-
518 duce the rate at which particles evaporate from aggregates, hence affect the
519 balance between evaporation and delayed aggregation.

520 The fraction of aggregated particles at the end of the simulation was esti-
521 mated for a range of particle speeds and adhesion strengths in a population
522 with homogeneous speed in order to obtain a quantitative understanding of
523 how particle adhesive strength influences the outcome of aggregation. Figure
524 S5 displays the proportion of aggregated particles for packing fraction $\rho = 0.07$.

525 Variation in F_{adh} does not affect the outcome of aggregation for small particle
526 speeds. In this regime, aggregation over a finite time is indeed limited by the low
527 encounter rate of isolated slow particles. As soon as particles are fast enough to
528 interact, almost any adhesion strength except the weakest leads to aggregation.
529 The fraction of aggregated particles increases with their speed to the point where
530 evaporation starts being important. The higher v_0 , the higher the force intensity
531 required to counterbalance the effect of evaporation. In the Supplementary
532 Information, we present a microscopic model that predicts the quadratic relation
533 between F_{adh} and particle speed observed in the simulations (Fig. 7A).

534 Let us now consider a binary mix of particles with different speed, where
535 adhesion strength varies uniformly for both particle types, while other param-
536 eters are the same as for Fig. 5 ($v_1 = 10$, $v_2 = 16$, $\rho = 0.07$). We previously
537 proposed that the type of bias in aggregates composition depends on the relative
538 position of v_1 and v_2 , relative to v_{opt} . We can now check that this assumption
539 correctly predicts the change of the bias when v_{opt} changes as a function of F_{adh} .
540 For any fixed couple of velocities v_1 and v_2 , there are three possible ranges of
541 F_{adh} where v_{opt} is located to the left, to the right, or in between their values,
542 as illustrated in Fig. 7. By choosing adhesion strengths that belong to such

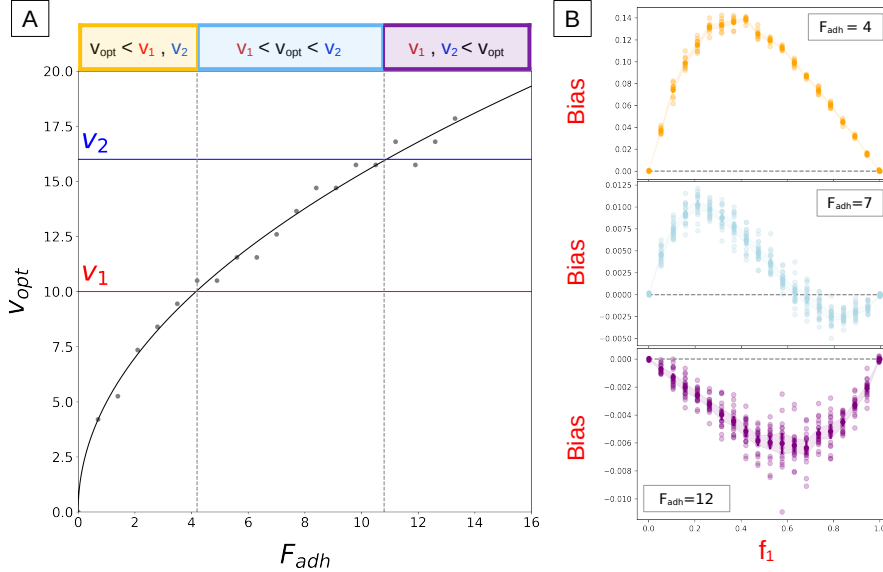


Figure 7: **Particle adhesion affects the outcome of aggregation in binary mixes of particles with heterogeneous speed.** (A) Particle speed v_{opt} for which the proportion of aggregated particles at $t = t_f$ is highest increases with the intensity of adhesive forces F_{adh} (see Fig. S5). The curve $v_{opt} \sim \sqrt{F_{adh}}$ (see Supplementary Information for a derivation from microscopic principles) was fitted to the optimal speed obtained from simulations (grey dots). Three F_{adh} ranges can be defined depending on the relative position of v_1 , v_2 and v_{opt} (indicated by different colours), as previously discussed for varying v_0 . (B) Aggregation bias of the slower population measured at the end of simulations of the binary mix described in Fig. 5, for adhesive strength within the ranges indicated in the left panel ($F_{adh} = 4$, $F_{adh} = 7$ and $F_{adh} = 12$).

543 intervals, we can retrieve the same qualitative form of bias as predicted: for low
 544 adhesion strengths, where both velocities are larger than v_{opt} , slower particles
 545 are positively biased (Fig. 7B, orange); for high adhesion strengths, the oppo-
 546 site occurs because of delayed aggregation (Fig. 7B, purple); for intermediate
 547 adhesion strengths, positive frequency-dependence is observed (Fig. 7B, blue).

548 Overall, when the two co-aggregating populations are on both side of v_{opt} ,
 549 aggregates composition is biased because of the interplay of two counteracting
 550 processes: evaporation of fast particles and delayed aggregation of slow parti-

551 cles. The relative contribution of these two factors determines the sign of the
552 bias and depends on the balance of the types in the binary mix. When the speed
553 of both particle types is smaller than v_{opt} , the slower is under-represented in the
554 aggregates due to delayed aggregation. When both speeds are larger than v_{opt} ,
555 the slower type is over-represented in the aggregates due to the higher evapora-
556 tion of faster particles. Finally, when $v_1 < v_{opt} < v_2$, the competition between
557 delayed aggregation of the slower particles and evaporation of the faster particles
558 provides different results if one or the other particle is at low frequency, giving
559 rise to a frequency-dependent bias. As long as the duration of the aggregation
560 phase is finite, then, the evolutionary dynamics is predicted to stabilize the co-
561 existence of different types of particles. Interestingly, the frequency-dependent
562 bias associated to bistability (Fig. 4D) was not observed. This scenario would
563 require particles faster than v_{opt} to be over-represented in the aggregates when
564 abundant (low f_1 values), which can only be achieved if differential evaporation
565 in favor of fast-particles can be compensated. Theoretically, this may occur if
566 fast particles were surrounded by a "shell" of slow particles, which, for initially
567 uniformly assorted particles, would require additional mechanisms of spatial
568 sorting. It may, for instance, be achievable if slower particles were also less
569 adhesive (Garcia et al., 2014).

570 These results show that, somehow unexpectedly given the complexity of the
571 self-organized dynamics and the transient nature of aggregation patterns, biases
572 in binary mixes can be predicted once the behaviour of the two populations in
573 isolation is characterized.

574 Discussion

575 When multicellularity emerged from unicellular ancestors, a transition oc-
576 curred from populations under selection for individual properties to a higher
577 level of biological organization, where collective adaptation became possible.
578 Aggregative multicellularity, one of the two routes followed in this transition,
579 involves the integration of cell aggregation into a life-cycle that also encompasses

580 free living. Cell aggregation offers a mechanism of fast and transient grouping,
581 that may be adaptive for coping with rapidly and unpredictably changing en-
582 vironments (Márquez-Zacarías et al., 2021). As a side-effect of fast grouping,
583 multicellular aggregates are however generally composed of a mosaic of cells in
584 different phenotypic states. Also observed in extant aggregative species (Fortu-
585 nato et al., 2003b; Sathe et al., 2010; Gilbert et al., 2007), single-cell heterogene-
586 ity between co-aggregating cells may have been particularly important for the
587 early steps of the transition to aggregative multicellularity, as it can promote the
588 recruitment of ancestral functions towards incipient division of labour. On the
589 other hand, before mechanisms of assortment evolved to reduce it, intra-group
590 heterogeneity might have caused widespread genetic conflicts that threatened
591 multicellular organization.

592 Differences in cell properties between co-aggregating cells is known to bias
593 their probability to differentiate into dormant phenotypes at the end of multice-
594 lular development (Forget et al., 2021). However, understanding the evolution-
595 ary implications of such single-cell heterogeneity on the outcome of aggregation
596 is currently limited by a lack of mechanistic explanations, in particular of how
597 initial diversity translates into biases in the composition of multicellular aggre-
598 gates. Among the many features that display cell-to-cell variation, cell motility
599 can be expected to directly impact the probability that a cell joins a multi-
600 cellular aggregate, and therefore affect spore bias. Indeed, as already pointed
601 out for *D. discoideum* loners (Dubravcic et al., 2014; Tarnita et al., 2015) only
602 aggregated cells can differentiate into spores and survive the dispersal phase of
603 the life cycle.

604 We used individual-based simulations to confirm the intuition that hetero-
605 geneity in cell motility affects the outcome of aggregation. Heterogeneity in
606 single-cell properties is known to act within multicellular aggregates, where cell
607 sorting can be a source of bias in the developmental fate of cells (Jones et al.,
608 1989; Houle et al., 1989; Umeda and Inouye, 2004; Strandkvist et al., 2014). We
609 showed that biases can also emerge during aggregation, before cells experience
610 proper 'social' interactions. In primitive aggregative life-cycles, before the evo-

611 lution of cell coordination mechanisms susceptible of reshuffling or canceling out
612 aggregation biases, cell motility properties inherited from a unicellular ancestor
613 may therefore have been recruited for their effects on group adaptation.

614 Numerical exploration of different binary mixes highlighted three types of
615 aggregation biases resulting from heterogeneity in particles motility. Notably,
616 when particles that are too slow to join a group before the end of aggregation
617 are mixed with particles that are fast enough to leave an aggregate, the sign of
618 the bias in the aggregated fraction changes with frequency. Slow particles are
619 over-represented in the aggregates when they are rare in the population, but
620 the opposite is true when they are in a high proportion. This type of frequency-
621 dependent bias allows to stabilize polymorphism in populations of interacting
622 genotypes (Hudson et al., 2002; Brännström and Dieckmann, 2005). Frequency-
623 dependent spore bias has been invoked (Madgwick et al., 2018; Parkinson et al.,
624 2011) as a possible mechanisms for the maintenance of the diversity of strains
625 observed in natural populations of aggregative species, such as *Dictyostelium*
626 (Francis and Eisenberg, 1993; Fortunato et al., 2003b) or *Myxococcus xanthus*
627 (Kraemer and Velicer, 2011; Vos and Velicer, 2009). However, it is typically
628 associated to developmental biases that emerge in the course of the multicellular
629 stage of the life cycle (Madgwick et al., 2018; Parkinson et al., 2011). We have
630 shown that such biases can also emerge passively from heterogeneity in single-
631 cell properties during aggregation. As such, they may have stabilized genetic
632 chimerism early in the transition to aggregative multicellularity, even before
633 development became highly regulated and contributed to limit genetic conflicts
634 in primitive aggregative life-cycle.

635 Beyond its constructive role on fostering polymorphism during aggregation,
636 heterogeneity in cell speed can also play an active role in later developmen-
637 tal stages. Motility-induced cell sorting within multicellular aggregates (Jones
638 et al., 1989; Beatrici and Brunnet, 2011) indeed paves the way towards the ex-
639 ploitation of morphogen gradients for establishing differential cell fates. Hence,
640 biases in aggregates composition induced by heterogeneity in cell speed dur-
641 ing aggregation could have concomitantly fueled the evolution of division of

642 labor. In extant aggregative species such as *D. discoideum* and *M. xanthus*,
643 position within an aggregate is known to determine cell probability to form a
644 spore (Araki et al., 1997; Huang et al., 1997; Julien et al., 2000). In a model
645 describing cell arrangement within *Dictyostelium* slugs, slower cells sort to the
646 back during migration (Umeda and Inouye, 2004), thus populating preferen-
647 tially the region that will eventually turn into the spore mass. Developmental
648 sorting can act in the same or opposite direction relative to aggregation biases.
649 In the evaporation-limited region, faster particles are doubly disadvantaged, as
650 they would be both over-represented in the loners and in the stalk. Motility
651 differences instead act in opposite directions, and could even cancel out, when
652 non-aggregated particles are mostly slow particles delaying their aggregation. In
653 this region, slow particles are indeed under-represented in the aggregates, but
654 once they have joined an aggregate, they are expected to sort to the back of the
655 slug hence to differentiate into spores. Combining aggregation and multicellular
656 development delineates an evolutionary trade-off between being sufficiently fast
657 to join an aggregate during aggregation on the one hand, and sufficiently slow
658 to sort to the back of the slugs on the other hand.

659 When cell motility is a heritable trait, aggregation biases induced by hetero-
660 geneity in single-cell properties underpin its evolutionary trajectory over mul-
661 tiple cycles of aggregation and dispersal. We can imagine that cell motility
662 evolves by the appearance of mutant cells whose speed is a small variation of
663 the resident population. The bias in aggregate formation then determines the
664 likelihood that the mutant trait substitutes the resident, as illustrated in Fig. 4.
665 Our results indicate that, as long as both the mutant and the resident traits are
666 on the same side of v_{opt} , selection will push particles to approach the optimal,
667 intermediate velocity for which aggregation is maximally efficient. Indeed, the
668 better aggregator in isolation is always over-represented in the aggregates, so
669 that evolution would climb the gradient of the proportion of aggregated par-
670 ticles, that is concave and has a unique maximum (Fig. 3A). However, if the
671 resident and the mutant fall on the opposite sides of v_{opt} – which is increasingly
672 likely, as the optimal value is approached – polymorphic solutions become avail-

673 able, where particles with different motility can coexist. Evolutionary branching
674 is possible in such a situation, as predicted in models for the adaptive dynamics
675 of social strategies (Doebeli, 2004). As discussed above, and argued elsewhere
676 (Miele and De Monte, 2021), coexistence of slow and fast cells may be inte-
677 gral to the establishment of aggregative life cycles, perhaps even before the two
678 phenotypes were unified as plastic manifestations of one single genotype.

679 During the last decades, emergent patterns of populations of self-propelled
680 particles have been at the core of research in active matter physics (Marchetti
681 et al., 2013). In particular, motility-induced phase separation has been evi-
682 denced as a state where steric interactions generate, in sufficiently dense popu-
683 lations, the coexistence of gas and aggregated phases (Fily and Marchetti, 2012).
684 We focused instead on smaller densities, where we could observe the emergence
685 of multiple particle aggregates, similar to a field of aggregation of slime moulds.
686 At these packing fractions, adhesion plays a fundamental role in determining the
687 aggregation pattern. The probability that cells remain together upon encounter
688 indeed derives by a balance between adhesive forces and self-velocity, modulated
689 by fluctuations. Several qualitatively different particle arrangements have been
690 identified as steady-states of populations whose particles are both adhesive and
691 align their motion (Grégoire et al., 2003). Before stabilizing their distribution on
692 asymptotic patterns, active particles also display transient clustering (Ostwald,
693 1896; van der Linden et al., 2019). Such long-lasting regimes can be relevant
694 for biological populations, where aggregation occurs over a finite timescale. In-
695 cluding non-stationary patterns led us to identify two possible regimes where
696 clusters coexist with isolated particles. At low speed, non-aggregated particles
697 are "latecomers" that did not have the chance to interact with other particles by
698 the end of the simulation. Their proportion in the aggregated fraction depends
699 on the duration of aggregation, other than on particle density, and is expected
700 to converge to one as the system reaches its stationary state. A consequence
701 of time-constrained aggregation is that, when they are rare, slow particles are
702 overrepresented in aggregates relative to particles fast enough to evaporate, but
703 have a negative bias when common. Such a frequency-dependent bias is not

704 found in simple models where diversity among interacting agents is depicted
705 in terms of fixed social strategies. Game theoretical representations of interac-
706 tions within multicellular bodies indeed typically predict that 'cheater' types,
707 that have by definition a positive bias, would be evolutionary stable in the
708 absence of mechanisms favouring interactions among kins (Strassmann et al.,
709 2000; Strassmann and Queller, 2011). Contrary to explanations based on strate-
710 gic decision-making of cells during multicellular development (Madgwick et al.,
711 2018), we propose here that frequency-dependent biases can also be established
712 by passive mechanisms, based on individual heterogeneity. It will be the subject
713 of future studies whether such dependence is robust to heterogeneity in other
714 parameters. In particular, adhesion on top of velocity could be chosen as a
715 heterogeneous trait, possibly correlated with speed.

716 These extensions can be informed by experimental observations of aggrega-
717 tive multicellular microbes, where parameters – at least those controlling single-
718 cell motility may be estimated for specific populations. The possibility that
719 frequency-dependent biases are induced during the aggregation phase could be
720 tested in extant aggregative microbes. The aggregation dynamics of populations
721 with different motility could be assessed when they aggregate separately, and
722 in chimeras with different proportions of two types. We are not aware of non-
723 invasive methods to modulate *Dictyostelium* motility. One possible strategy to
724 generate populations with differential motility is to apply contrasting selective
725 pressures in a directed evolution experiment (Adiba et al., 2022).

726 More generally, a better understanding of the mechanical properties of uni-
727 cellular organisms may prove essential to capture the diversity of paths leading
728 to current forms of multicellular organization.

729 **Conclusion**

730 During aggregation, heterogeneity in single cell motility induces self-organization
731 between co-aggregating cells. On the timescale of aggregation, this simple and
732 passive mechanism results into non-trivial biases in the outcome of aggregation.

733 On longer timescales, such biases are expected to have important implications
734 on the genetic diversity of aggregative species as well as on the evolution of
735 aggregative life cycles. Motility properties inherited from unicellular ancestors
736 may thus have played a pivotal role in the transition to aggregative multicellu-
737 larity.

738 **Acknowledgments**

739 The authors are grateful to Gabriel Peyré for his help in optimizing the
740 Python program. The authors also thank Thibaut Arnoulx de Pirey Saint
741 Alby for helpful discussions on the link between the adhesion strength and
742 the rate of evaporation and Nirbhay Patil for discussions on active matter
743 physics. This work has received support under the program "Investissements
744 d'Avenir" launched by the French Government and implemented by ANR with
745 the references ANR-10-LABX-54 MEMOLIFE and ANR-10-IDEX-0001-02
746 PSL* Université Paris, Q-life ANR-17-CONV-6150005, and the project ANR-
747 19-CE45-0002 'ADHeC' PSL research University. L. Brunnet thanks the Brazil-
748 ian agencies CNPq and Capes for their support.

749 **Supplementary Figures**

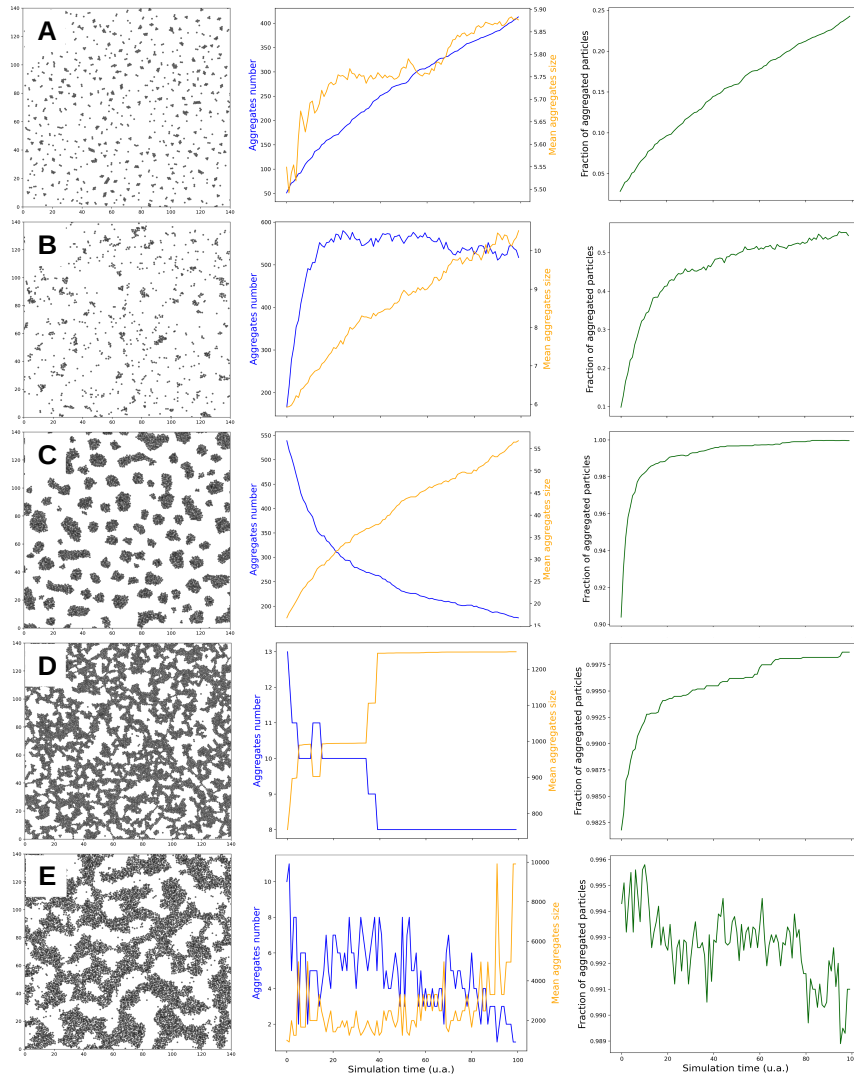


Figure S1: **Variation in particle speed and packing fraction produces different aggregation dynamics.** Snapshots of the final state (first column) of the system and evolution of aggregate number and aggregate mean size (second column), as well as the fraction of aggregated particles over time (third column), for simulations ran using the 5 pairs of parameters values displayed in Fig. 2. The five different regimes discussed in the text correspond to different variations of the three order parameters.

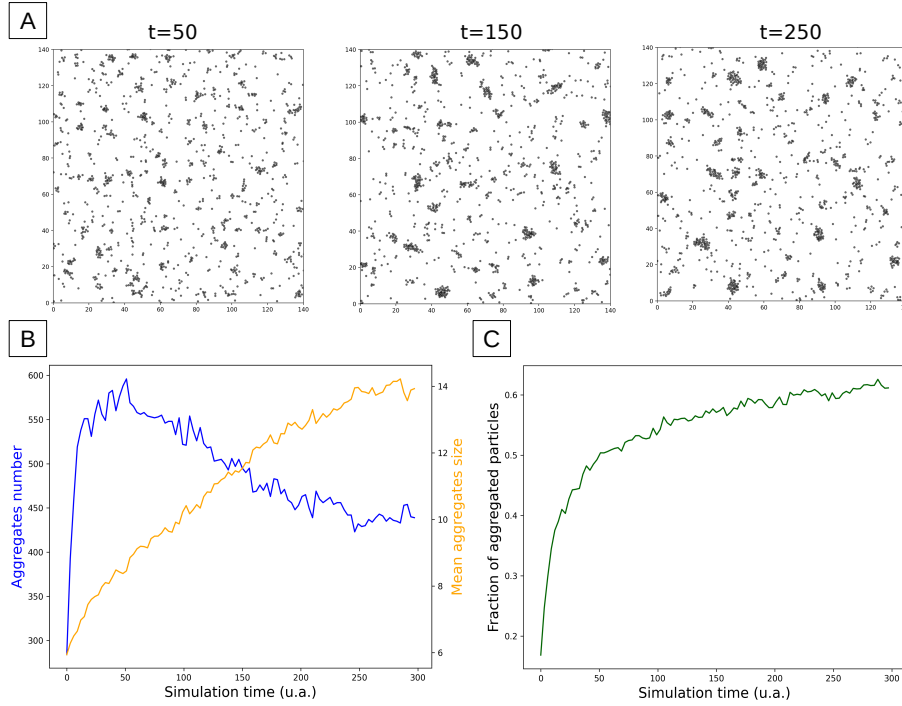


Figure S2: **Aggregates' long-term coarsening dynamics at high speed and small packing fraction.** During the time span $t_f = 100$, self-organization of fast particles leads to the rapid formation of a large number of small aggregates. On longer timescales, however, particles evaporate from small and unstable aggregates and attach to larger-size aggregates that are more stable (A, snapshots of the system state at $t = 50$, $t = 150$ and $t = 250$). Similarly to Ostwald's ripening processes (Ostwald, 1896), this results in a decrease in the number of aggregates (B). The fraction of aggregated particles (C) saturates at a value smaller than 1, indicating that in the asymptotic state the aggregated phase coexists with the gas phase, as in MIPS (Fily and Marchetti, 2012). In this simulation, $\rho = 0.07$, $v_0 = 17.5$, and other parameters were set as indicated in table S1.

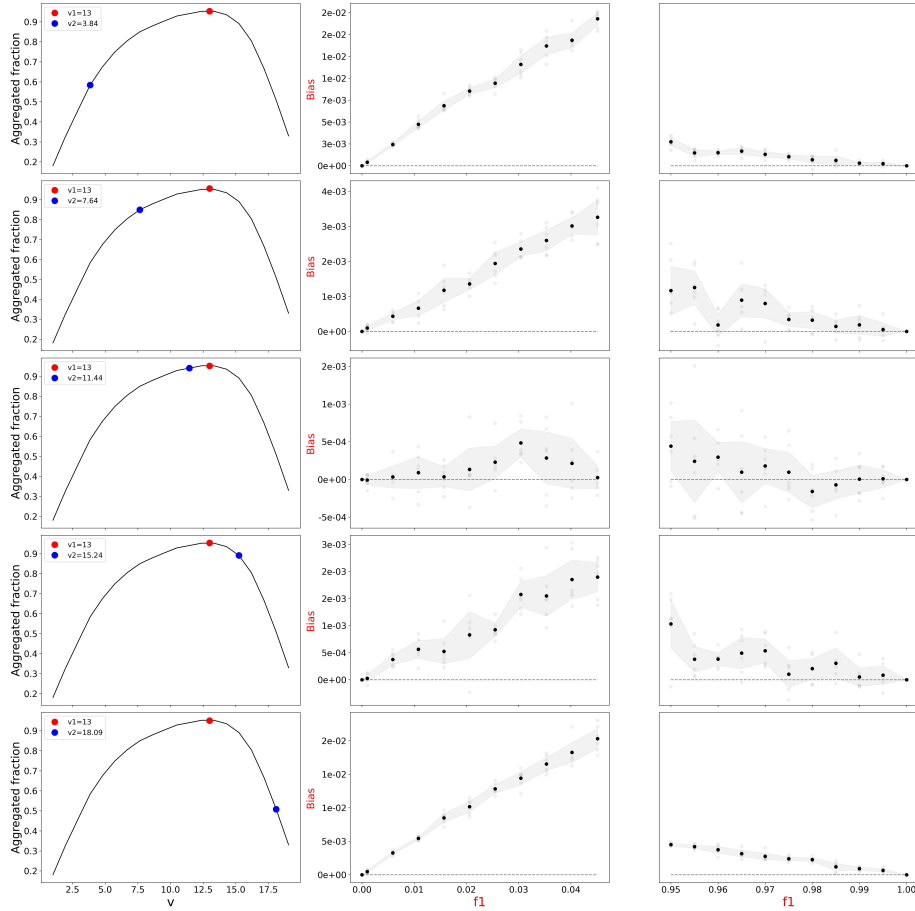


Figure S3: **Bias in binary mixes where the focal population has constant speed, and speed differential varies.** The first column displays the fraction of aggregated particles when each population aggregates separately at the same total packing fraction $\rho = 0.07$ (other parameters were set as indicated in table S1). Red dots indicate the constant speed $v_1 = 13$ of the focal population, blue dots the speed v_2 . The second and third column illustrate the bias relative to the focal population at the extremes of the interval $[0, 1]$. Black dots are averages of six replicates, the shaded area represents the 95% confidence interval.

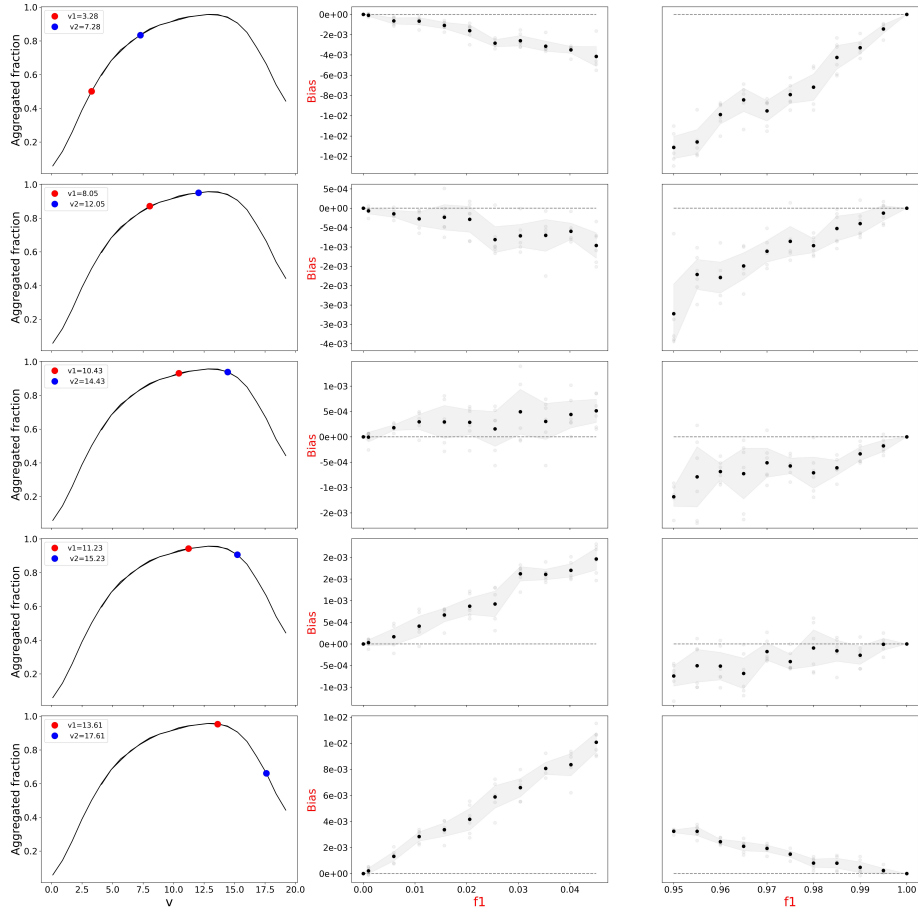


Figure S4: **Bias in binary mixes where the speed of the two populations is changed, while maintaining a fixed speed differential.** The first column displays the fraction of aggregated particles when each population aggregates separately at the same total packing fraction $\rho = 0.07$ (other parameters were set as indicated in table S1). Red dots indicate the speed v_1 of the slower, focal population, blue dots the speed v_2 , chosen such that the speed difference $\Delta v = 4$. The second and third column illustrate the bias relative to the focal, slower population at the extremes of the interval $[0, 1]$. Black dots are averages of six replicates, the shaded area represents the 95% confidence interval.

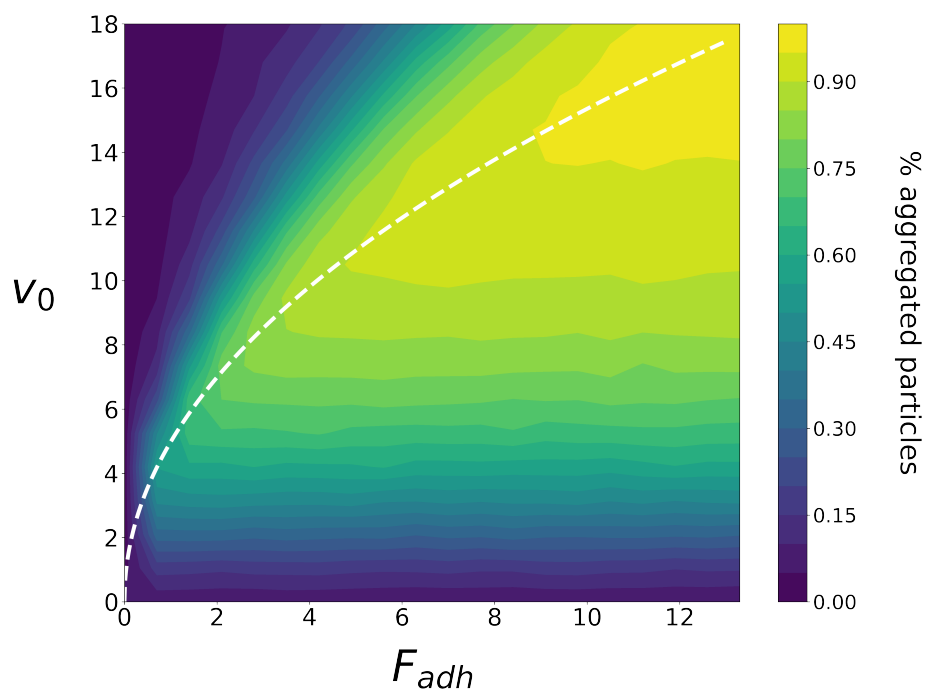


Figure S5: **Fraction of aggregated particles at the end of the simulation as a function of particles adhesive strength and particle speed.** The packing fraction was fixed to 0.07 and the remaining parameters of the model were set as indicated in table S1. The white dotted line represents a fit of the points corresponding to the highest fraction of aggregated particles with Eq. 5.

750 **Supplementary Information**

751 *Parameters choice*

752 The fixed parameters of the model were set as indicated in table S1. As in
753 Szabo et al. (Szabó et al., 2006), we used a fixed time step dt of $dt = 0.05 * R_0/v_0 = 0.01$. This value is sufficiently small so that, between two successive
754 time-steps, two particles cannot cross each other's interaction range without
755 interacting.

756 The interaction parameters F_{rep} and F_{adh} were set so that particles do not
757 collapse (volume exclusion) and can detach from aggregates (evaporation) when
758 v_0 is increased. The equilibrium radius R_{eq} and the interaction range R_0 are
759 such that particles only interact with their direct neighbours, in order to model
760 cell interaction through physical contact. Interactions mediated by diffusing
761 signals could be approximated by choosing larger radii, but that would require
762 making additional assumption on signal take-up by neighbouring cells. The
763 intensity of angular noise η and the relaxation time of interaction τ were set
764 such that particles clusters do not display collective motion, similar to what can
765 be observed during early aggregation of *Dictyostelium discoideum*. Indeed, a
766 low level of angular noise and/or a low relaxation time favor collective motion
767 of particles as interactions contribute to aligning the self-propelled velocity and
768 nematic order emerges. Moreover, we chose a relatively high value of η so that,
769 in the absence of particles interaction, the trajectory of a particle resembles that
770 of a starved *D. discoideum* cells in the absence of interaction with other cells,
771 *i.e.* at low cell density (See Fig. 1C and D for a comparison).
772

773 Other parameters were set to match the order of magnitude of observations
774 of *D. discoideum* under standard laboratory conditions: cell size $R_{eq}^{exp} = 11\mu\text{m}$
775 (De Palo et al., 2017), cell speed $v^{exp} = 11\mu\text{m}/\text{min}$ (McCann et al., 2010) and
776 duration of *Dictyostelium* aggregation $t_f^{exp} = 12\text{h}$.

In order to compute the final time of numerical integration t_f that corre-
sponds to the finite duration of aggregation, we used the following relationship

obtained by dimensional analysis:

$$t_f = \frac{t_f^{exp} v^{exp}}{R_{eq}^{exp}} \frac{R_{eq}}{v_0} \approx 100 \quad (4)$$

Table S1: Model parameters values

Parameter	value
N	10000
t_f	100
dt	0.01
v_0	8
μ	1
η	10
τ	5
v_0	8
F_{adh}	7
F_{rep}	40
R_{eq}	1.1
R_0	1.6
L	364
$\rho = N\pi(R_{eq}/2)^2/L^2$	0.07

777 *Link between optimal velocity v_{opt} and adhesion force F_{adh}*

Simulations of the self-propelled particles system suggest that v_{opt} and F_{adh} scale like:

$$v_{opt} = a\sqrt{F_{adh}} \quad (5)$$

778 where a is a constant (Fig. S5, white dotted line, and Fig. 7A, black line).

In order to understand such a relationship from a theoretical point of view, let us consider the collision between a self-propelled and a stationary particle (for instance, one that belongs to an aggregate – whose average speed is very small), as illustrated in Fig. S6. The equations of motion for each particle in the simulation are:

$$\frac{d\mathbf{r}_i(t)}{dt} = v_0\mathbf{n} + \mu\mathbf{F} \equiv \mathbf{v} \quad (6)$$

$$\frac{d\theta(t)}{dt} = \frac{1}{\tau}\arcsin(\mathbf{n} \times \frac{\mathbf{v}}{v}) + \eta\xi_j(t) \quad (7)$$

779 where \mathbf{r}_i is the position of particle i , v_0 its self-propelled speed, \mathbf{n} a polariza-
 780 tion unitary vector with angle θ , μ the mobility, τ is the characteristic time
 781 for the polarization to align in the scattering direction defined by \mathbf{v} , η is the
 782 noise intensity which defines a characteristic timescale $\tau_r \sim 1/\eta^2$ of the white
 783 rotational noise $\xi(t)$. For the analysis that follows, we consider a large value
 784 for the alignment and rotational characteristic times, so that the polarization
 785 direction (not the scattering direction) remains constant.

786 We want to estimate the duration of the contact between two particles when
 787 they encounter, that is the time they spend at a distance of less than the interac-
 788 tion range R_0 . Comparison between this timescale and the timescale necessary
 789 for a particle to escape from an interaction will provide a scaling relation be-
 790 tween the force intensity and the optimal velocity.

Consider a particle that is travelling with velocity \mathbf{v} approaching the station-
 ary particle. When the incident particle falls within the range R_0 , one has to
 take into account the deviation in its trajectory that results from the attractive
 force. Since the force acts radially, we have to evaluate the velocity in the radial

direction (defined pointing outwards relative to the stationary particle) resulting from the self-propulsion and the action of the force. This is the projection in that direction of eq. 6:

$$v_r = v_0 \cos \alpha + \mu F_{adh}, \quad (8)$$

791 where α is the angle between the radial direction and the direction of the particle
792 velocity (Fig. S6).

In the absence of angular noise, the incident particle will remain within the range of the force as long as the velocity in the outward radial direction is small enough to compensate the last term in eq. 8. The two particles detach when v_r is zero, which happens at a critical angle α^* where the components of the force and self-propulsion have opposite signs. That occurs when $\cos \alpha^* = \frac{\mu F_{adh}}{v_0}$ (Fig. S6). A small value for α^* implies a small value for the outward velocity component and, consequently, a longer contact time. We may then estimate the contact time as proportional to the attraction force range, R_0 and $\cos \alpha^*$ and inversely proportional to the speed, v_0 , that is, $\tau_{ctc} \approx \frac{R_0 \cos \alpha^*}{v_0}$. From these relations, one obtains the following scaling:

$$\tau_{ctc} \approx \frac{R_0 \mu F_{adh}}{v_0^2} \quad (9)$$

793 The larger τ_{ctc} , the longer two particles remain attached.

794 For a given F_{adh} , let us consider a population of particles with high v_0 so that
795 aggregation is limited by evaporation. Decreasing v_0 results in an increase in
796 τ_{ctc} , particles thus escape at a lower rate and the fraction of aggregated particles
797 increases. When $\tau_{ctc} > \tau$, however, whatever the speed, the incident particle will
798 remain bound, as its self-propulsion will be quickly reoriented along a tangent
799 direction. Once the particles enter such an 'orbit' upon contact, further increase
800 in the contact time (corresponding to a decrease in v_0) has no effect. A decrease
801 in the fraction of aggregated particles can nonetheless occur because of delayed
802 aggregation, and more so, the slower are the particles. The optimal v_0 (*i.e.*
803 v_{opt}) for which the fraction of aggregated particles is the highest is thus reached
804 when $\tau_{ctc} = \tau$.

This condition yields:

$$v_{opt} = \frac{\sqrt{R_0 \mu F_{adh}}}{\tau} \quad (10)$$

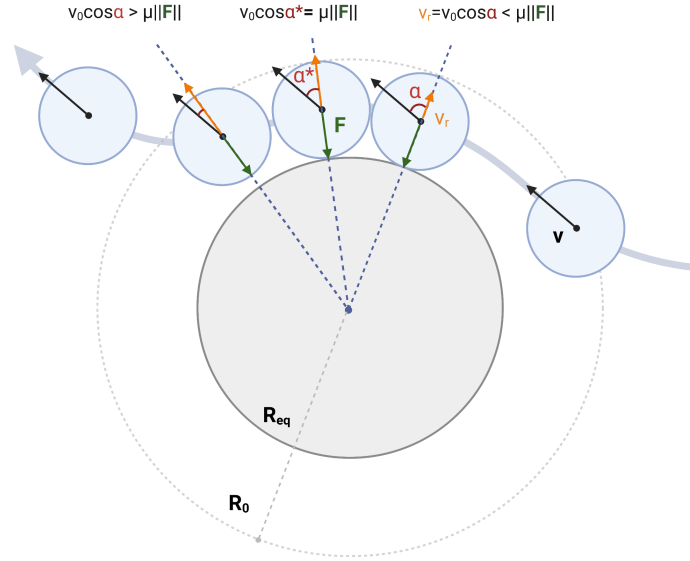


Figure S6: **Timing of particles interaction.** A self-propelled particle (blue, represented at successive times) comes into contact with a stationary particle (grey). The size of the stationary particle is enhanced for the sake of visualization. The alignment and rotational characteristic times are considered sufficiently large so that the polarization direction of the self-propelled particle remains constant during the encounter with the stationary one. The self-propelled particle detaches from the stationary particle when the projection of its self-propulsion in the direction connecting the particle centers is larger than the adhesive strength.

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