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Hydro-mechanical behaviour of high-density bentonite pellet upon partial hydration

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Abstract (150 words)

The hydro-mechanical behaviour of a high-density bentonite pellet, potential candidate for engineered barriers in high-level radioactive waste disposal, is investigated through laboratory tests. Water content and volumetric strain are first determined at various suctions (ranging from 9 MPa to 89 MPa) during partial hydration from its initial state. Afterward, compression tests allow the Young modulus and strength to be determined at various suctions. The experimental results are then interpreted by using an existing model describing the hydro-mechanical behaviour of an aggregate in compacted expansive clay. The analyses show that a single set of parameters is sufficient to predict the suction dependency of volumetric strain, Young modulus and compressive strengths. These findings would be helpful for further numerical investigations on the hydro-mechanical behaviour of granular bentonite-based engineered barriers by using both finite element and discrete element methods.

Keywords: Partial saturation; Expansive soils; Laboratory tests.

List of notations

ρ_s : particle density

ρ_d : dry density

e : void ratio

w : water content

D : pellet's diameter

H : pellet's total height

h : pellet's cylinder-shaped part height

R_c : pellet's curvature radius

s_0 : initial suction

ε_a : axial strain

ε_r : radial strain

ε_v : volumetric strain

N : axial load

E : Young modulus

ν : Poisson ratio

δ_n : normal displacement

S_r : degree of saturation

R_R : normal force at failure during radial compression

R_A : normal force at failure during axial compression

K_m : microstructural bulk modulus

\hat{p} : effective mean stress

α_m : material parameter

β_m : material parameter

C_A : material parameter relating axial strength to modulus

C_R : material parameter relating radial strength to modulus

1 **Introduction**

2 Bentonite-based materials are considered as candidate materials for engineered barriers in
3 radioactive waste disposal due to their low permeability, good radionuclides retention capacity,
4 and ability to swell upon hydration, which is an important property to fill the technological voids.
5 While many studies on the hydro-mechanical behaviour of bentonite-based engineered barriers
6 have focused on compacted blocks of bentonite, bentonite pellets/powder mixtures have also
7 been considered as an interesting alternative (Volckaert et al., 1996; van Geet et al., 2005;
8 Imbert and Villar, 2006; Hoffman et al., 2007; Alonso et al., 2011; Gens et al., 2011; Molinero-
9 Guerra et al., 2017).

10

11 After Kröhn (2005), vapour diffusion plays a significant – if not dominant – role in the
12 resaturation process of bentonite-based engineered barriers. In order to study the hydro-
13 mechanical behaviour of bentonite pellets mixtures upon hydration by vapour transfer,
14 accounting for the granular nature of the material (Molinera-Guerra et al., 2018*a,b*), numerical
15 simulations based on the discrete element method (DEM) (Cundall and Strack, 1979; Roux and
16 Chevoir, 2005; Agnolin and Roux, 2007; Than et al., 2017) could be an interesting way of
17 assessing the influence of pellets swelling on the mixtures behaviour. In DEM simulations, each
18 particle is modelled individually. A model describing the hydro-mechanical behaviour of a single
19 pellet is therefore required. As this approach is valid for granular materials, the model has to
20 focus on hydration state at which a pellet has not lost its initial structure.

21

22 For this purpose, the present study focuses on the hydro-mechanical behaviour of a single
23 pellet upon partial hydration. The vapour equilibrium technique is used to hydrate the pellet. At
24 equilibrium, the pellet volume and water content are determined, which allows determining the
25 relationship between volumetric strain and suction. Afterward, a compression test is performed
26 on the pellet to determine its stiffness and strength. Finally, the results are interpreted through
27 the conceptual framework proposed by Alonso et al. (1999).

28

29 **2. Material**

30 The material characterised in this study are sub-spherical MX80 bentonite pellets. MX80 is a
31 Na-bentonite from Wyoming, with high smectite contents, which main physical properties are
32 summarised in Table 1. Pellets are obtained through compaction of bentonite powder. They are
33 composed of a cylinder-shaped part and two spherical ends (Figure 1). Their initial properties
34 are shown in Table 2.

35

36 **3. Experimental methods**

37 Suction-controlled hydration is performed through the vapour equilibrium technique (Tang and
38 Cui, 2005; Delage et al., 2006). Pellets are placed within a desiccator containing a saturated salt
39 solution. When equilibrium is reached (verified by pellet mass), the pellets dimensions are
40 measured using a camera (one picture is taken from the side, Figure 1a, and pellet's height and
41 diameter are measured with an accuracy of 0.01 mm). Axial strain ε_a and radial strain ε_r are
42 determined by comparison of height and diameter with their initial values. Volumetric strain ε_V is
43 calculated as follows:

$$\varepsilon_V = (1 + \varepsilon_a)(1 + \varepsilon_r)^2 - 1 \quad (1)$$

44 Compression tests are carried out by using a load frame (Figure 2). The displacement rate is
45 imposed at 0.1 mm/min. Displacements are recorded by a displacement transducer and the
46 contact force between the pellet and the frame is recorded by a force transducer (with an
47 accuracy of 0.1 N).

48

49 Compression tests are performed in both axial and radial directions (Figure 3). In axial
50 compression tests (Figure 3a), contact between the load frame and the pellet is sub-punctual.
51 Assuming isotropic linear elastic behaviour, the Hertz law is adapted to obtain Young modulus
52 (Johnson, 1985):

$$N = \frac{1}{3} \frac{E}{1 - \nu^2} (2R_c)^{1/2} \delta_n^{3/2} \quad (2)$$

53 Where N is the axial load; E and ν are Young modulus and Poisson's ratio, respectively; δ_n is
54 the normal displacement.

55

56 In radial compression test (Figure 3b), the contact is assumed to be linear. Johnson (1985)'s
 57 elasticity law, relating normal displacement to normal force for a contact between an infinite
 58 plate and a cylinder, is applied to determine E .

$$\delta_n = 2 \frac{N}{h} \frac{1 - \nu^2}{\pi E} \left[2 \ln \left(2 \sqrt{\frac{\pi D}{2} \frac{E}{1 - \nu^2} \frac{N}{h}} \right) - 1 \right] \quad (3)$$

59 Figure 4 presents the results corresponding to $s = 89$ MPa. Several tests are performed and
 60 one curve is chosen to show the method for determination of E . For axial compression tests
 61 (Figure 4a), N increases with increasing displacement until failure. At failure, N decreases
 62 abruptly. The Hertz law (equation 2) is then used to fit experimental data from the start to the
 63 failure to determine E . In the present work, $\nu = 0.3$ for the sake of simplicity. For radial
 64 compression tests (Figure 4b), N increases with increasing displacement in two distinct phases:
 65 first, a slow increase; second, a more significant and sub-linear increase. The first phase is
 66 interpreted as the consequence of an imperfect contact between the frame and the pellet at the
 67 beginning of the test. As displacement increases, the contact becomes linear and the force-
 68 displacement relationship is significantly modified. Considering this hypothesis, equation (3) is
 69 used to fit experimental data only from the start of the second phase to the failure.

70

71 In the present work, beside the initial suction, eight suctions (ranging from 9 MPa to 82 MPa)
 72 are considered. For each one, several pellets are analysed to assess the repeatability of the
 73 experimental data.

74

75 **4. Experimental results**

76 Figure 5 presents w versus elapsed time during the suction equilibrium phase. From its initial
 77 value (12.2%), w increases quickly during the first days and equilibrium is reached after 10
 78 days, except for the lowest suction (9 MPa) where 30 days were necessary. The values
 79 obtained at equilibrium (Figure 5) are then plotted versus imposed suction in Figure 6a. Along
 80 the hydration path (decrease of suction from 89 MPa to 9 MPa) w increases from 12.2 % to 24.3
 81 %. Results obtained on the same materials (MX80) in other studies are also plotted. Within the
 82 investigated suction range, w - s relationships are similar and do not depend on the initial dry

83 density or hydration conditions. Figure 6b presents the degree of saturation (S_r) versus suction
84 which shows that S_r does not change significantly during this hydration phase.

85

86 Figure 7 presents the strains versus suction during this hydration phase. ϵ_a is generally higher
87 than ϵ_r . The mean values of ϵ_v , obtained from the mean values of ϵ_a and ϵ_r , are plotted. As
88 expected, ϵ_v keeps increasing upon hydration.

89

90 The mechanical properties (E and strength) are plotted versus suction in Figure 8. Moduli
91 obtained for both axial and radial compression tests are similar (Figure 8a) and a single mean
92 value is retained for both compression directions. These results confirm that the assumptions
93 used to interpret the compression tests (isotropic linear elastic behaviour, equations 2 & 3) are
94 appropriate. Upon hydration, the pellet modulus and strength decrease significantly.

95

96 Finally, the relationship between compressive strengths and modulus is presented in Figure 9. A
97 linear relationship is suggested for both axial and radial directions.

98

99 **5. Model**

100 In the present work, the pellet initial dry density is high and its behaviour is assumed to be
101 similar to that of an aggregate (*i.e.* the microstructural level) in compacted expansive clay
102 following the model proposed by Alonso et al. (1999).

103 Microstructural volumetric strain is written:

$$d\epsilon_{vm} = \frac{d\hat{p}}{K_m} = \frac{ds}{K_m} \quad (4)$$

104

$$K_m(s) = \frac{1}{\beta_m} \exp(\alpha_m s) \quad (5)$$

105 Where K_m is the microstructural bulk modulus, \hat{p} is the effective mean stress (equal to s in the
106 present study), α_m and β_m are material parameters.

107

108 From compression tests results, $\alpha_m = 0.024 \text{ MPa}^{-1}$ and $\beta_m = 0.016 \text{ MPa}^{-1}$ are obtained through
109 basic exponential regression (Figure 8a).

110

111 Integrating (5) from initial suction s_0 to a given suction s leads to:

$$\varepsilon_{vm} = \frac{\beta_m}{\alpha_m} [\exp(-\alpha_m s_0) - \exp(-\alpha_m s)] \quad (6)$$

112 Where α_m and β_m values, determined from compression tests results, are found to satisfactorily
113 model the volumetric strain upon hydration (Figure 7).

114

115 From Figure 9, it seems convenient to propose a linear relationship between pellet strengths
116 and modulus. The following relationships are proposed:

$$R_A = C_A E \quad (7)$$

117

$$R_R = C_R E \quad (8)$$

118 where C_A and C_R are material parameters relating the strength to the modulus for axial and
119 radial compression tests, respectively. $C_A = 1.206 \times 10^{-7} \text{ m}^{-2}$ and $C_R = 1.816 \times 10^{-7} \text{ m}^{-2}$ following
120 the fitting (Figure 9).

121

122 From (5), (7) and (8), the evolution of pellet strength upon hydration can be written:

$$R_A = 3 (1 - 2\nu) C_A \frac{1}{\beta_m} \exp(\alpha_m s) \quad (9)$$

123

$$R_R = 3 (1 - 2\nu) C_R \frac{1}{\beta_m} \exp(\alpha_m s) \quad (10)$$

124 Model predictions are presented in dash lines in Figure 9, along experimental results for
125 comparison.

126

127 **6. Discussion**

128 The experimental results show that partial hydration induces an increase in water content and
129 pellet volume and a decrease in Young modulus and strength. These trends agree with existing
130 results on bentonite-based materials (Wiebe et al., 1998; Blatz et al., 2002; Lloret et al., 2003;
131 Tang and Cui, 2009; Carrier et al., 2016). However, the volumetric strain obtained in the present
132 work (50% for hydration from 89 MPa to 9 MPa) is higher than that observed on a single MX80

133 bentonite aggregate (25%, after Tang and Cui 2009). In addition, the Young modulus measured
134 in the present work is generally one order of magnitude smaller than that measured by Carrier
135 et al. (2016) on MX80 bentonite clay film over the same suction range. It means that the
136 mechanical behaviour of the material is strongly dependent on the dimensions of the specimen.

137

138 In addition, it is interesting to note that the results obtained by compression tests (Figure 8a)
139 can be used to predict the results obtained by hydration (Figure 7). The role of total stress is
140 thus similar to that of suction as suggested by Alonso et al. (1999) for microstructural level.

141

142 The present work contributes to a more comprehensive approach to model the behaviour of a
143 single pellet. These results would be helpful for further numerical investigations on the hydro-
144 mechanical behaviour of granular bentonite using the finite element method with double-porosity
145 models (i.e. Alonso et al., 2011) where a single pellet corresponds to the micro-structural level.
146 Actually, Molinero Guerra et al. (2017) performed mercury intrusion porosimetry on a similar
147 bentonite pellet and found that the volume of macro-pores is negligible at high suction. Besides,
148 for numerical investigations using discrete element modelling, these results can be directly used
149 to describe the behaviour of a single pellet under hydro-mechanical loading.

150

151 However, it is worthy to mention that the behaviour of the pellet observed in the present work
152 doesn't correspond to all the assumptions proposed for an aggregate in the model of Alonso et
153 al. (1999): (i) the pellet is not fully-saturated; (ii) its behaviour is not reversible; (iii) the volumetric
154 behaviour of the pellet is not isotropic. In spite of these disagreements, the model would
155 correctly predict the hydro-mechanical behaviour of a pellet during this partial hydration path (up
156 to 9 MPa of suction). At suction lower than this value, the model would no longer be valid as the
157 pellet would disaggregate (as suggested by Saiyouri et al. 2004 for bentonite particles, Koliji et
158 al., 2010 and Cardoso et al., 2013 for clay aggregates less reactive than bentonite).

159

160 In addition to the volumetric behaviour, the strengths of the pellet under compression can be
161 also predicted by using the same values of α_m and β_m . These results can be explained by the
162 linear correlation between the strengths and the modulus. Actually, correlations between these

163 two properties were observed on various compacted clayey soils (Lee et al., 2005; Zeh and
164 Witt, 2007).

165

166 **7. Conclusions**

167 The behaviour of a single high-density bentonite pellet under hydration from 82 to 9 MPa of
168 suction and the variation of its mechanical properties during this path are investigated in this
169 study by laboratory tests. The results show an increase of pellet's volume and water content
170 upon suction decrease. At the same time, its mechanical properties (Young modulus and
171 strengths) decrease during hydration. When analysing the experimental result with an existing
172 model for compacted expansive soil and assuming that the pellet behaviour is similar to that of
173 an aggregate, a single set of parameters (α_m and β_m) can be used to predict the suction
174 dependency of volumetric strain, Young modulus and strengths.

175

176 The results from this work would be helpful for further numerical investigations (finite element
177 and discrete element methods) on the hydro-mechanical behaviour of granular bentonite-based
178 engineered barrier for geological radioactive waste disposal during the first years following the
179 installation.

180

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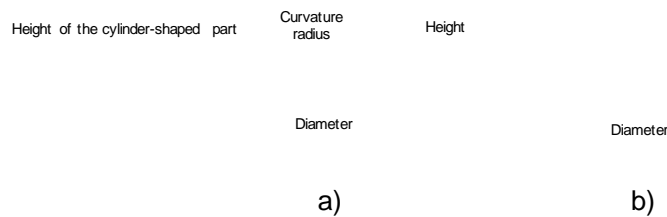
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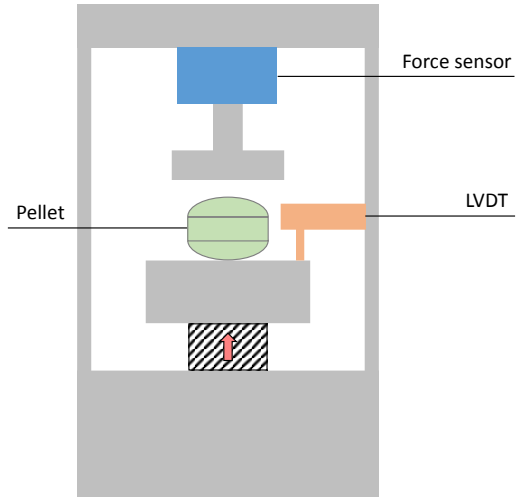
262 **Figure captions (images as individual files separate to your MS Word text file).**

263 Figure 1. Schematic views of a single pellet. Radial view (a) and axial view (b).



264

265 Figure 2. Load frame used to perform compression test. (a) Picture; (b) description



a)

b)

266

267

268

Figure 3. Schematic view of the compression tests: (a) axial compression; (b) radial compression.

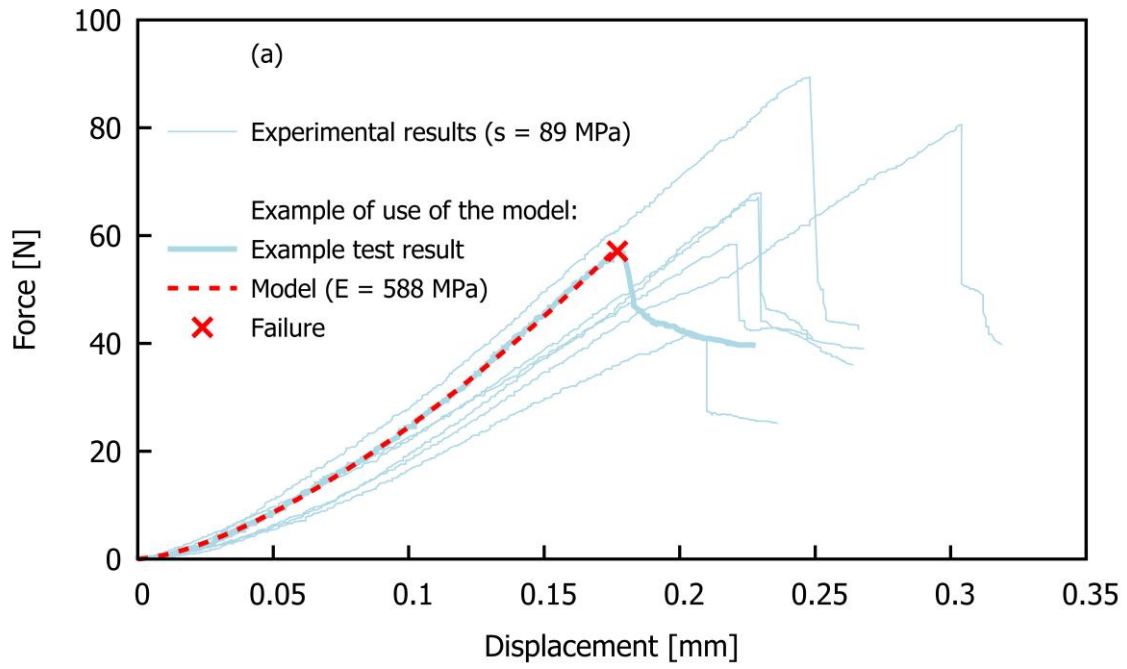
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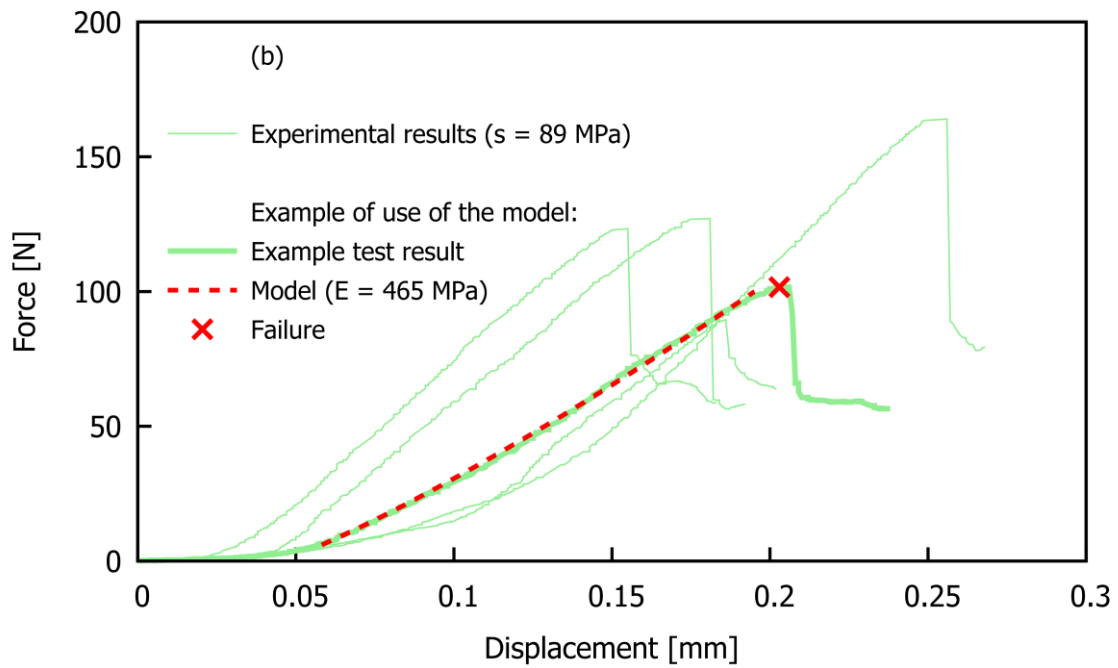
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Figure 4. Typical results of compression tests: (a) axial compression; (b) radial compression.

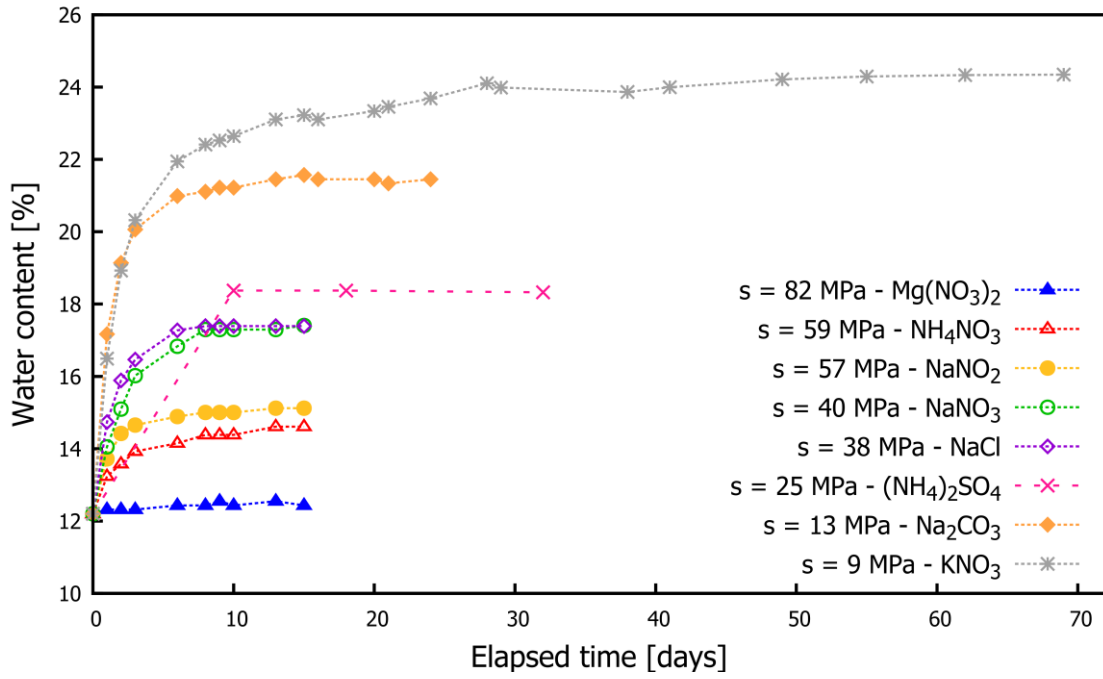


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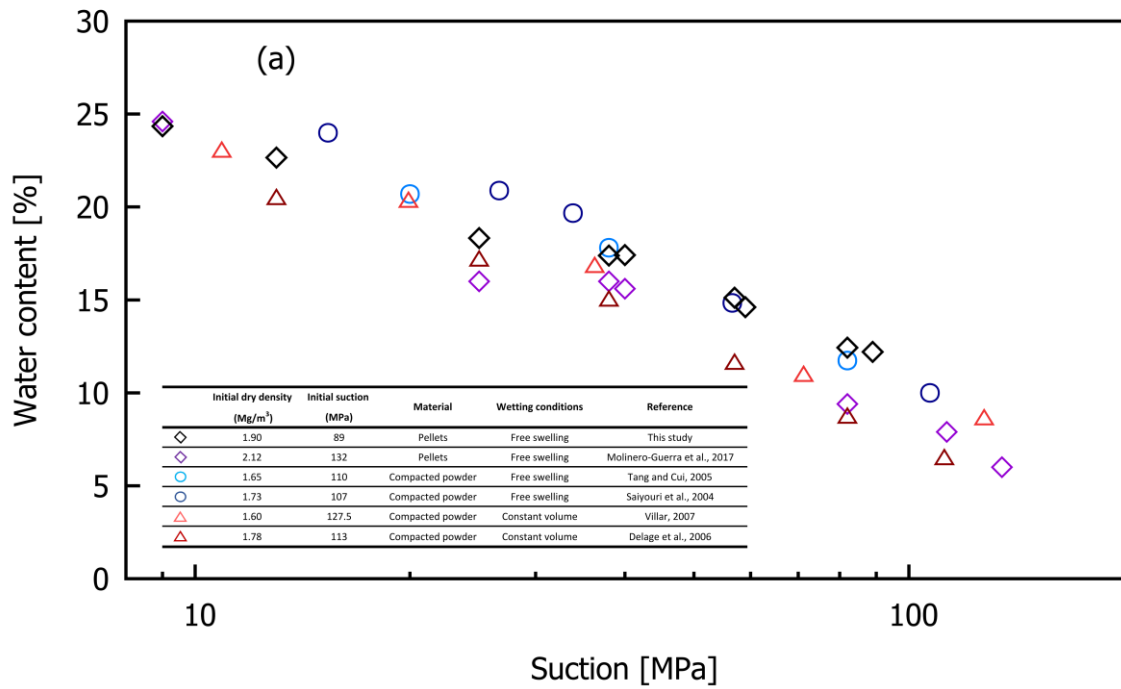
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273 Figure 5. Water content versus elapsed time during the suction equilibrium phase.

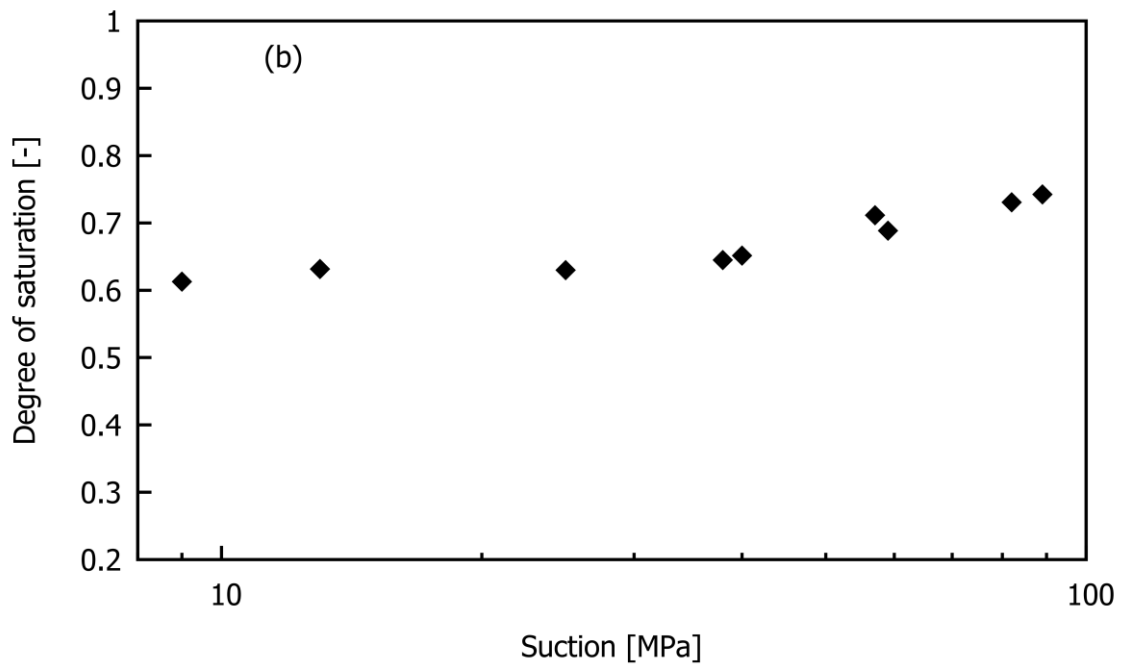


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275 Figure 6. (a) Water content versus suction; (b) Degree of saturation versus suction.

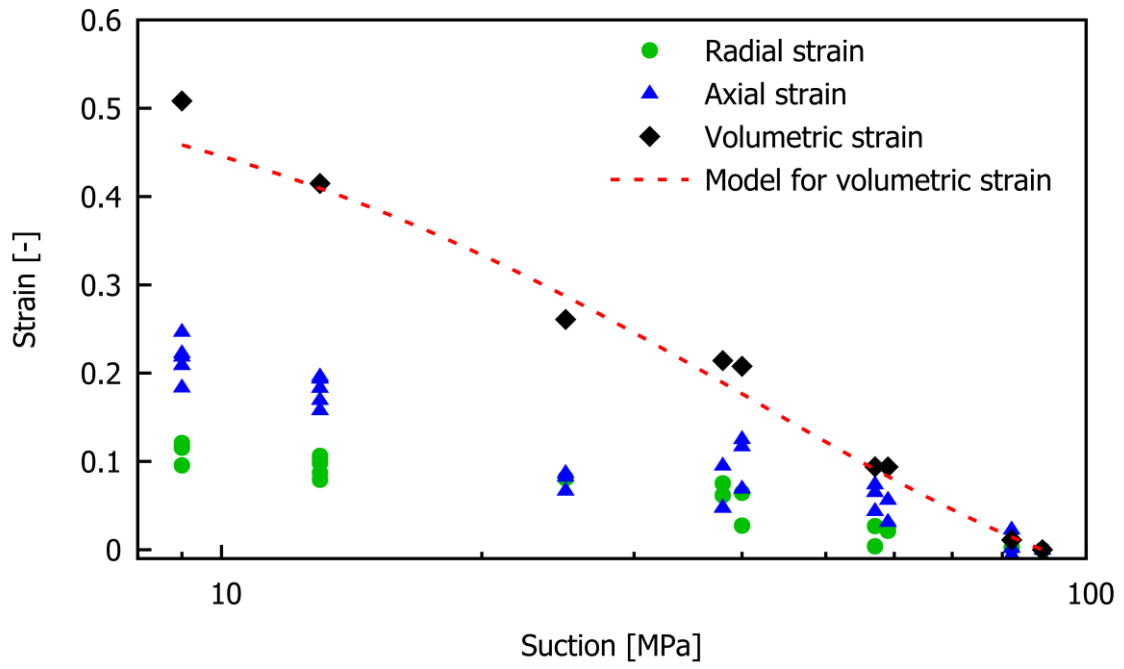


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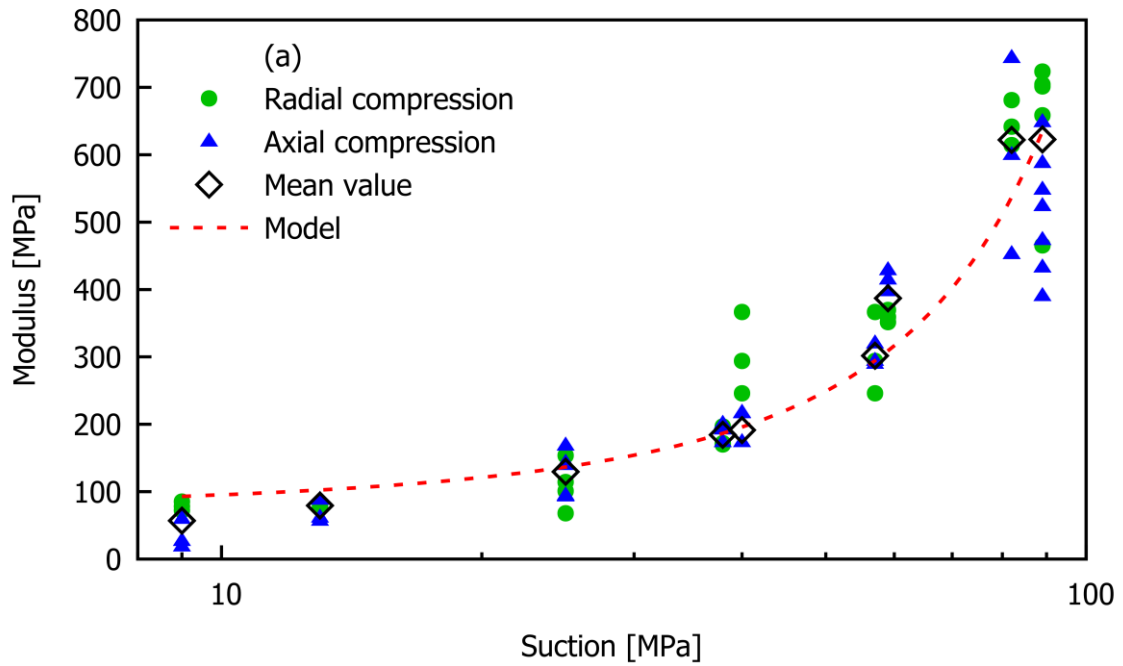
278 Figure 7. Axial, radial and volumetric strains versus suction.



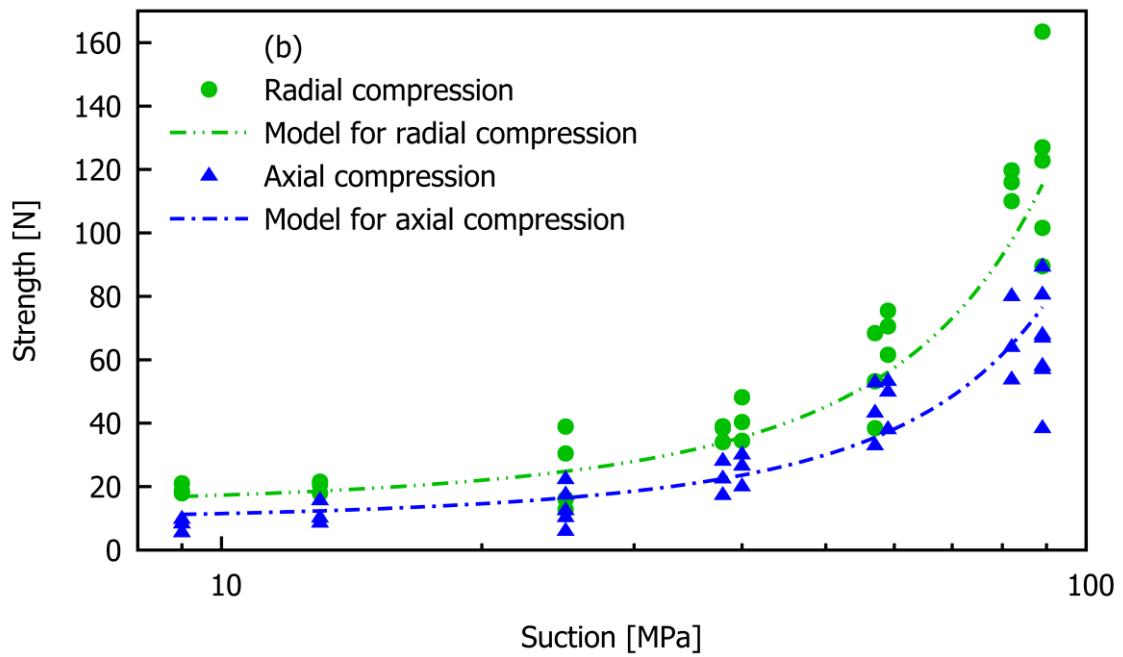
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280 Figure 8: (a) Modulus versus suction for axial and radial compression tests; (b) Strength versus

281 suction for axial and radial compression tests.

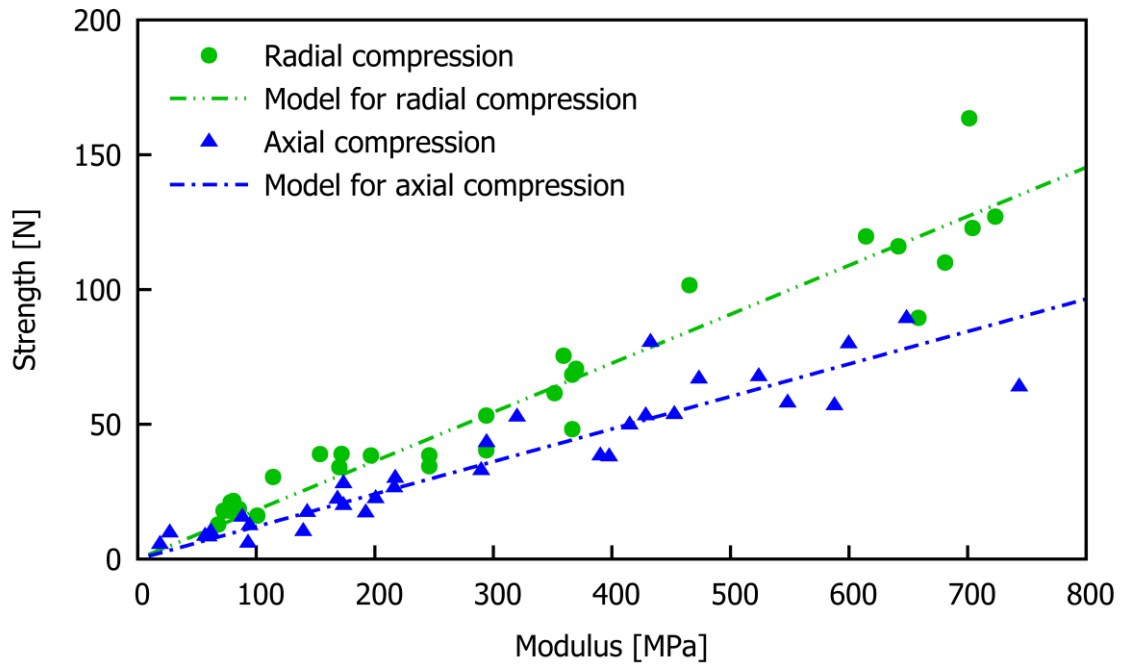


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284 Figure 9: Strength versus modulus for both axial and radial compression tests.



285

286 Table 1. Physical properties of MX80 bentonite

| Property | Value |
|---|--------|
| Particle density, ρ_s (Mg/m ³) | 2.77 |
| Smectite content (%) | 80 |
| Liquid limit (%) | 560 |
| Plastic limit (%) | 53 |
| CEC (meq/g) | 98/100 |

287

288 Table 2. Initial properties of the pellets

| Property | Value |
|--|-------|
| Dry density, ρ_d (Mg/m ³) | 1.90 |
| Void ratio, e (-) | 0.46 |
| Water content, w (%) | 12.2 |
| Diameter, D (mm) | 7.0 |
| Height, H (mm) | 7.0 |
| Height of the cylinder-shaped part, h (mm) | 5.0 |
| Curvature radius, R_c (mm) | 6.5 |
| Suction, s_0 (MPa) | 89 |

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