

Conception et commande de robots quadrupèdes

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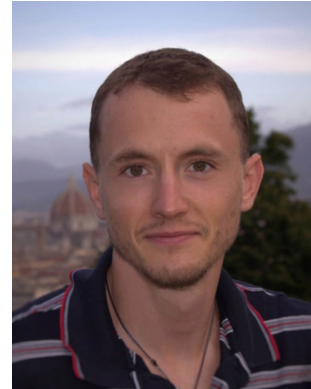
Merci !



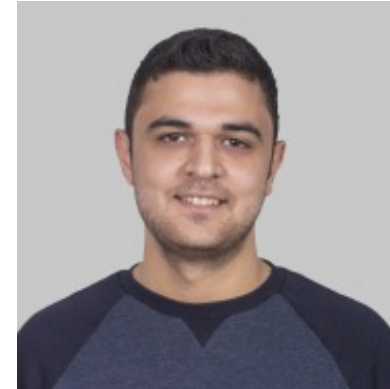
Thomas Flayols



Pierre-Alexandre Léziart



Gabriele Fadini



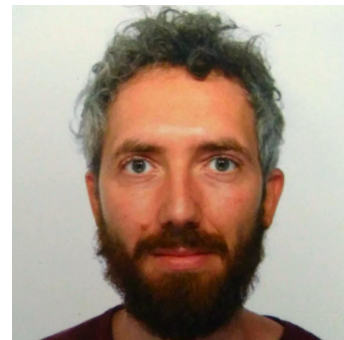
Michel Aractingi



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Tomi Silander



Andrea Del Prete



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