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Multiscale analysis of Klf10's impact on the passive mechanical properties of murine skeletal muscle

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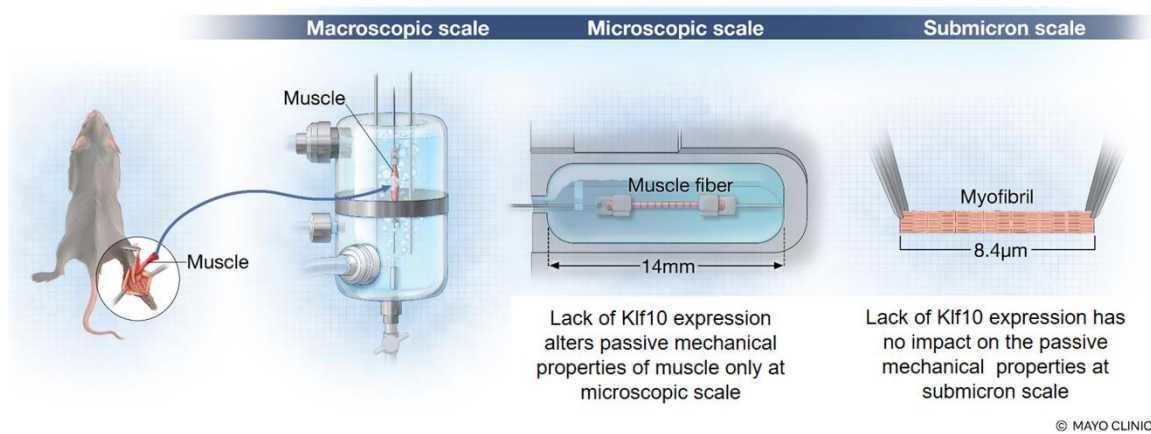
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HIGHLIGHTS

- Role of Klf10 on the passive behavior of muscle at three organizational scales.
- Klf10 impacts differentially the passive properties of the soleus and EDL muscles.
- Lack of Klf10 expression does not change the passive behavior of myofibrils.
- Disruption of Klf10 on skeletal muscle is primarily at the microscopic scale.

GRAPHICAL ABSTRACT



1 **ABSTRACT**

2 Skeletal muscle is a hierarchical structure composed of multiple organizational scales. A major
3 challenge in the biomechanical evaluation of muscle relates to the difficulty in evaluating the
4 experimental mechanical properties at the different organizational levels of the same tissue.
5 Indeed, the ability to integrate mechanical properties evaluated at various levels will allow for
6 improved assessment of the entire tissue, leading to a better understanding of how changes at
7 each level evolve over time and/or impact tissue function, especially in the case of muscle
8 diseases.

9 Therefore, the purpose of this study was to analyze a genetically engineered mouse model
10 (Klf10 KO: Krüppel-Like Factor 10 knockout) with known skeletal muscle defects to compare
11 the mechanical properties with wild-type (WT) controls at the three main muscle scales: the
12 macroscopic (whole muscle), microscopic (fiber) and submicron (myofibril) levels. Passive
13 mechanical tests (ramp, relaxation) were performed on two types of skeletal muscle (soleus and
14 extensor digitorum longus (EDL)).

15 Results of the present study revealed muscle-type specific behaviors in both genotypes only at
16 the microscopic scale. Interestingly, loss of Klf10 expression resulted in increased passive
17 properties in the soleus but decreased passive properties in the EDL compared to WT controls.

18 At the submicron scale, no changes were observed between WT and Klf10 KO myofibrils for
19 either muscle; these results demonstrate that the passive property differences observed at the
20 microscopic scale (fiber) are not caused by sarcomere intrinsic alterations but instead must
21 originate outside the sarcomeres, likely in the collagen-based extracellular matrix. The
22 macroscopic scale revealed similar passive mechanical properties between WT and Klf10 KO
23 hindlimb muscles.

1 The present study has allowed for a better understanding of the role of Klf10 on the passive
2 mechanical properties of skeletal muscle and has provided reference data to the literature which
3 could be used by the community for muscle multiscale modeling.

4 **Keywords: multiscale, mechanical properties, Klf10, mouse, skeletal muscle**

1 **1. Introduction**

2 Striated skeletal muscle represents approximately 40 % of the human body mass that is
3 multifunctional and highly adaptive to physiological and pathological conditions that may result
4 in muscle hypertrophy (due to increased mechanical load) or atrophy (inactivity, chronic
5 disease states) (Adams et al., 2003). From a structural point of view, striated skeletal muscle
6 tissue is a complex, hierarchical system which can be classified into four primary scales
7 (Tatarenko et al., 2022): macroscopic (mouse muscle diameter: about 1-3 cm), mesoscopic
8 (mouse single fascicle diameter: about 0.5-30 mm), microscopic (mouse single muscle fiber
9 diameter: 10-100 μm) and submicron (mouse single myofibril diameter: about 1-3 μm). The
10 macroscopic scale is represented by the whole muscle and the different collagen sheaths. Both
11 *in vivo* and *in vitro* techniques are currently used to characterize the morphological and
12 mechanical properties of an entire skeletal muscle. The mesoscopic scale corresponds to the
13 fascicles, which are surrounded by the perimysium tissue and is poorly characterized in the
14 literature (Meyer and Lieber, 2011). The microscopic scale is defined by a single muscle fiber
15 that is surrounded by the endomysium tissue, and *in vitro* mechanical techniques have been
16 used to analyze its mechanical properties. Structural analysis and orientation of fibers within a
17 muscle can be determined with specialized imaging techniques, such as diffusion tensor
18 imaging (Correia et al., 2018), ultrasound (Ternifi et al., 2020) and multiphoton microscopy
19 (Syverud et al., 2017). The submicroscopic scale is composed of myofibril filaments which can
20 be mechanically assessed by only a few research groups around the world (Herzog et al., 2014;
21 Linke et al., 2000).

22 There have been studies aimed at analyzing tissues at different structural levels. Brynnel et
23 al. (2018) compared the passive properties between two fiber types (slow twitch and fast twitch)
24 of muscles in mice. Moreover, for the same animal model (rabbit), Ward et al. (2020) compared
25 the passive mechanical properties between fibers, bundles, fascicles and whole muscle. Meyer

1 et al. (2011) and Wood et al. (2014) compared the passive properties between fibers and bundles
2 in mice, and Marcucci et al. (2019) compared the mechanical behavior between slow and fast
3 fibers and bundles in humans. These models, based on experimental data, illustrated the
4 importance of each scale on the global tissue response, and the difficulty in experimentally
5 determining the mechanical properties at each scale of interest.

6 One of the major challenges in the biomechanical assessment of skeletal muscle relates to
7 the current inability to integrate the mechanical properties at each primary scale and to evaluate
8 changes of these properties over time to better understand the development and progression of
9 muscle disorders and diseases. Indeed, some studies have demonstrated the impact of alterations
10 in the structural and functional properties at different levels from the same tissue (tendon
11 (Aghaei et al., 2021); myocardium (Tueni et al., 2022); soleus muscle (Bensamoun et al.,
12 2006)). In addition, it has been demonstrated that genetic disorders resulting in muscle disease,
13 such as Duchenne muscular dystrophy (Desguerre et al., 2012), have a strong effect on different
14 structural scales leading to changes in whole muscle mechanical properties. A recent
15 publication (Pouletaut et al., 2023) provided a better understanding of passive mechanical
16 properties at the macro-micro and submicron scales, for healthy slow and fast twitch muscles.
17 The results have demonstrated that the Young's modulus and passive stresses have higher
18 values for the slow twitch (soleus) compared to the fast twitch (EDL: extensor digitorum
19 longus) muscle at only the macroscopic scale. This study showed the relevance of the choice of
20 the scale to study the impact of muscle type.

21 As a continuation of Pouletaut's study, a genetically modified mouse model, in which the
22 Krüppel-like factor 10 (Klf10) gene was knocked-out, has been utilized in the present study,
23 given that deletion of Klf10 is known to result in passive mechanical changes at the microscopic
24 scale (*i.e.* slow and fast muscle fiber) (Kammoun et al., 2016; Kammoun et al., 2017). Thus,
25 the purpose of this study was to analyze the passive mechanical properties at the macroscopic,

1 microscopic and submicron scales (Fig. 1), on mouse soleus and EDL muscles, to determine
2 how the macroscopic mechanical behavior of muscle is impacted by the properties of its
3 subcomponents at the microscopic and submicron scales in both healthy and Klf10 knockout
4 muscle tissues.

5

6 **2. Material and Methods**

7 *2.1. Animals*

8 In agreement with our previous studies characterizing the role of Klf10 on the mechanical
9 properties of adult female mouse skeletal muscle, we used 3-month-old WT (wild type) and
10 KLF10 KO (knockout) female mice generated from heterozygous breeding. All mice were
11 maintained in a temperature-controlled room ($22 \pm 2^\circ\text{C}$) with a light/dark cycle of 12 hours.
12 Animals had free access to water and were fed a standard laboratory chow *ad libitum*.
13 Anesthesia was performed via an isoflurane vaporizer (MiniHUB V2, TEM SEGA) device by
14 inhalation from $3 \text{ mg}\cdot\text{L}^{-1}$ to $1.5 \text{ L}\cdot\text{min}^{-1}$ during muscle dissection. Following dissection, mice
15 were euthanized by cervical dislocation according to the guidelines for the care and use of
16 experimental animals. The protocol was approved by the French ministry of higher education,
17 research, and innovation (Permit Number: DUO-4776) as well as the local ethics committee
18 (CREMEAP; Permit Number: APAFIS #8905-2021011109249708).

19

20 *2.2. Macroscopic scale*

21 *2.2.1. Preparation of the skeletal muscles and experimental set up*

22 Soleus ($N_{\text{WT}} = 9$, $N_{\text{KO}} = 6$) and EDL ($N_{\text{WT}} = 9$, $N_{\text{KO}} = 8$) muscles were carefully harvested
23 from the left hindlimb to ensure that muscles were not stretched during dissection and with
24 confirmation that no residual tissue from surrounding muscles was carried forward. For muscle
25 isolation, a suture (SofsilksTM, 4-0, 1.5Metric) was tied around the distal and proximal tendons;
26 then tendons were cut and removed, and muscles were placed in a bath containing a

1 physiological solution (50 mL sodium bicarbonate, 10 mL calcium chloride dihydrate, 9.6 g.L⁻¹
2 ¹ Krebs-Henseleit buffer powder) maintained at a temperature of 25 °C, pH 7.3 and a constant
3 oxygenation (95 % O₂ and 5 % CO₂) to mimic the *in vivo* environment (Fig. 1). Subsequently,
4 the proximal and the distal parts of the muscle were connected to a dual mode force transducer
5 (300C-LR dual-mode muscle lever, Aurora Scientific, Ontario, Canada) and to a hook,
6 respectively. A pair of flat platinum electrodes, connected to an external stimulator set at 1 A,
7 were placed on each side of the muscle. A SI610A Dynamics Muscle Control v5.420 software
8 (Aurora Scientific, Ontario, Canada) was used to control the displacement of the lever arm to
9 stretch the muscle at different velocities.

10

11 Prior to performing the passive mechanical tests, the muscle was placed at its optimal length
12 (L_o), *i.e.* the length where the muscle developed its maximal isometric force. Optimal length
13 was obtained for each muscle as follows. First, the muscle was set to its resting length (L_r),
14 which corresponds to the length where muscle develops a stable force of 10 mN (Canon et al.,
15 2008; Toscano et al., 2010), by applying three successive tetanus and three successive twitch
16 contractions. Each stimulation was spaced 30 s apart and both impulses were performed at a 40
17 Hz frequency for a period of 0.7 s (tetanus test) and instantaneously (twitch test). Between each
18 stimulation, a stretch was applied to the muscle to keep the initial force level of 10 mN constant.
19 Once L_r had been determined in this manner, the optimal length (L_o) was obtained by applying
20 successive twitch impulses, spaced 30 s apart, and by increasing the muscle length by
21 increments of 0.25 mm between each twitch until the muscle reached its maximal isometric
22 force.

1 2.2.2. *Passive mechanical properties using ramp and relaxation tests*

2 Preconditioning of the muscle samples was performed at L_o . Each sample underwent a
3 stretch-release cycle, repeated two times spaced 5 min apart (Canon et al., 2008). The decrease
4 of the hysteresis value was used to control the efficiency of the preconditioning.

5 After a rest of 5 min, soleus and EDL muscles underwent a ramp test with the stretch-release
6 cycle consisting of a stretch of 25% of optimal length ($L_o \approx 10$ mm) at a slow velocity of 1.67%
7 $L_o.s^{-1}$ (about 0.167 mm.s⁻¹) followed by a release at the same velocity, allowing for the
8 measurement of the instantaneous force (F_{i_Ramp}) reached at the maximum of the stretch. The
9 force-displacement curve was recorded, and a stress-strain curve was generated to measure the
10 Young's modulus (E) in the linear part of the loading curve between 60 and 80% of the maximal
11 strain (Hollenstein et al., 2006).

12 After a rest of 5 min, the viscoelastic properties were characterized through a relaxation test
13 using a fast stretching velocity of $5 L_o.s^{-1}$ (about 50 mm.s⁻¹) with an amplitude of stretch of 25%
14 L_o . Three parameters were measured: 1) the dynamic force (F_d), corresponding to the maximum
15 force reached at the end of the stretch, 2) the static force (F_{s_Relax}), corresponding to the steady
16 state force reached at the end of the holding period (*i.e.* at 250 s), and 3) the half time of
17 relaxation ($t_{1/2}$).

18 All forces (F_{s_Ramp} , F_d , F_{s_Relax}) were normalized relative to the initial cross-sectional (CSA)
19 area of the respective muscle to determine the dynamic (σ_d), the instantaneous (σ_{i_Ramp}) and the
20 static (σ_{s_Relax}) stresses. The cross-sectional area was calculated using the following equation
21 (Del Prete et al., 2008):

22
$$CSA(mm^2) = \frac{m(mg)}{L_f(mm) * 1.06(mg \cdot mm^{-3})} \quad (1)$$

23 where 1.06 (mg.mm⁻³) is the density of mammalian skeletal muscle, (m) is the muscle mass and
24 (L_f) the optimal fiber length which was calculated by multiplying the value L_o with the muscle

1 length ratio (0.44 for the EDL and 0.71 for soleus) as indicated in the literature (Del Prete et
2 al., 2008).

3 Following completion of the passive testing, muscles were removed from the bath and
4 weighed using an analytical laboratory balance (BP61S, SARTORIUS, Göttingen, Germany).

5

6 *2.3. Microscopic scale*

7 *2.3.1. Preparation of muscle fibers and experimental set up*

8 Skinned muscle fibers from an additional 5 WT and 5 KO mice were isolated from soleus
9 ($N_{WT} = 17$, $N_{KO} = 16$) and EDL ($N_{WT} = 16$, $N_{KO} = 15$) muscles from the left hindlimb. Following
10 dissection, muscles were permeabilized at 4 °C in a skinning solution with successive added
11 percentages of glycerol (12.5, 25 and 50 %) (Kammoun et al., 2016; Toursel et al., 2002; West
12 et al., 2013). The muscle samples were then stored in 50% glycerol / 50% relaxing solution at
13 -20 °C for a maximum of 5 weeks. Subsequently, using a light microscope (Leica™ M80,
14 Wetzlar, Germany), muscle fibers were isolated and placed in a small bath (14 x 4 mm) (Fig.
15 1) filled with the relaxing solution, corresponding to the skinning solution, at a controlled
16 temperature of 25 °C.

17 *2.3.2. Passive mechanical tests performed with single muscle fibers*

18 Single muscle fibers were attached at each extremity with an aluminium T-clip
19 (Photofabrication, St Neots, UK) respectively connected to a force transducer (5 mN) and to a
20 motor (1400A - 802D Permeabilized Fiber Test Apparatus - Aurora Scientific). Immediately
21 prior to mechanical testing, each fiber was manually stretched to a sarcomere length of 2.4 μm
22 by the same operator. The control of this length was performed with the placement of a region
23 of interest over 3 sarcomeres using ASI 900B video sarcomere length tools (Aurora Scientific,
24 Aurora, Ontario, Canada). After, its slack length ($L_s \approx 2$ mm) was measured using an optical
25 microscope (Leica™ DM IL LED, Wetzlar, Germany), composed of a 10 mm graticule in the
26 eyepiece, at a magnification of 20X. The average fiber diameter was determined using several

1 measurements along the fiber length. Subsequently, each fiber underwent two preconditioning
2 tests followed by two passive mechanical tests (ramp stretch, stress-relaxation) as previously
3 described (Kammoun et al., 2016).

4 Preconditioning tests were performed to limit the impact of the viscous effect on the
5 myofibrils (Rehorn et al., 2014). Accordingly, each fiber was stretched to 150% L_s (about 3
6 mm) at velocity of $0.00167 L_s \cdot s^{-1}$ (about $0.00333 \text{ mm s}^{-1}$) and relaxed at the same velocity. After
7 a 5 min rest period at the slack length, this preconditioning test was repeated twice. The
8 hysteresis loop was plotted for each preconditioning run. The hysteresis area was calculated
9 and the decrease in the hysteresis value was used to control the efficiency of preconditioning
10 (Kammoun et al., 2016).

11 The first passive mechanical test was a ramp stretch. The fibers were stretched to 150 % L_s
12 (about 3 mm) with a velocity of $0.033 L_s \cdot s^{-1}$ (about 0.066 mm s^{-1}) and released at the same
13 velocity, allowing the measurement of the instantaneous force (F_{i_Ramp}) reached at the end of
14 the stretch. As with the whole muscle test, the Young's modulus (E) was calculated using an
15 identical method (Hollenstein et al., 2006).

16 The second passive mechanical test was a relaxation test. Over a period of 60 s, the fiber was
17 rapidly stretched to 150 % L_s (about 3 mm) at a high velocity of $3.3 L_s \cdot s^{-1}$ (about 6.6 mm s^{-1})
18 and released to its slack length. The dynamic force F_d , corresponding to the maximal force
19 value, reached at the end of the stretch, and the static force F_{s_Relax} measured at the end of the
20 test, before the fiber was released, were recorded. In addition, the half time of relaxation was
21 measured.

22 All measured forces (F_{i_Ramp} , F_d , F_{s_Relax}) were divided by the initial average anatomical
23 cross-sectional area of the fiber to obtain dynamic (σ_d), instantaneous (σ_{i_Ramp}) and static
24 (σ_{s_Relax}) stresses.

25

1 2.4. *Submicron scale*

2 2.4.1. *Preparation of the myofibrils and experimental set up*

3 Myofibrils were extracted from the soleus ($N_{WT} = 11$, $N_{KO} = 11$) and EDL ($N_{WT} = 11$, N_{KO}
4 = 11) muscles of an additional 6 WT and 6 KO mice. To isolate the myofibrils, muscles were
5 first skinned as described above. A small piece of the skinned muscles (about 5 mm in length
6 and 2 mm in width) was placed in a microcentrifuge tube containing rigor solution and vortexed
7 to separate individual myofibrils (Joumaa et al., 2008).

8

9 2.4.2. *Passive mechanical test performed with myofibrils*

10 Myofibrils were placed in a bath on the stage of an inverted microscope and attached to a
11 glass needle at one end, and to a nanolever at the other end (Fig. 1), allowing for length changes
12 and force measurements, respectively (Powers et al., 2017). The sarcomere striation pattern of
13 the myofibrils was projected onto a linear photodiode array for determination of individual
14 sarcomere lengths. The diameter of the myofibrils was measured at a magnification of 250X
15 and used to determine the cross-sectional area of myofibrils.

16 Subsequently, myofibrils were set at an average sarcomere length of 2.4 μm . They were then
17 passively stretched at a speed of 0.1 $\mu\text{m}\cdot\text{s}^{-1}$ to an average sarcomere length of 3.4 μm . The
18 stretch was held for 20 seconds until a steady-state force was reached, and then released. Passive
19 force reached at steady-state, *i.e* at the end of the test, was determined and converted to static
20 stress (σ_s) by dividing the recorded force by the cross-sectional area of each myofibril.

21

22 2.5. *Statistical analysis*

23 The SystatTM V11 software (Systat Software Inc., CA, USA) was used for all statistical
24 analyses. Non-parametric two-sample Mann-Whitney tests were used to compare all parameter

1 values at a given scale between the WT and KLF10 KO genotypes. Results were considered
2 significant for $p < 0.05$.

3 **3. Results**

4

5 *3.1. Comparison between Klf10 KO and WT soleus across scales*

6 Figure 2 depicts the comparison of the stress curves between WT and Klf10 KO soleus at
7 each scale.

8 At the macroscopic scale (Fig. 3), all passive parameters (σ_{i_Ramp} , E , σ_d , σ_{s_Relax} , $t_{1/2}$) obtained
9 for WT controls and Klf10 KO soleus muscle were within the same range (Fig. 3A, Table 1A).
10 However, none of these reached statistical significance (Table 2).

11 At the microscopic scale, a significant difference ($P < 0.01$) was observed for all of the
12 parameters analyzed (Fig. 3B, Table 1B, Table 2), excepted for the half relaxation time,
13 between fibers extracted as a function of mouse genotype.

14 At the submicron scale, no significant difference was found for the static stresses (σ_s) of
15 myofibril filament between WT and Klf10 KO animals (Fig. 3C, Table 1C, Table 2). Of note,
16 there was much more variability between individual myofibrils isolated from Klf10 KO mice.

17 To conclude, particularly at the microscopic scale, there were significantly higher values (P
18 < 0.01) in the passive stresses and Young's modulus of the Klf10 KO soleus fibers.

19

20 *3.2. Comparison between Klf10 KO and WT EDL across scales*

21 Figure 4 depicts the comparison of the stress curves between WT and Klf10 KO EDL at each
22 scale.

1 At the macroscopic scale (Fig. 5A), all passive parameters (σ_{i_Ramp} , E , σ_d , σ_{s_Relax}) for the
2 Klf10 KO were slightly higher compared to the WT control (Table 3A). However, none of
3 these, including the half relaxation time, reached statistical significance (Table 4).

4 At the microscopic scale (Fig. 5B), a significant difference ($P < 0.01$) was observed for all
5 of the parameters analyzed (Table 3B, Table 4), excepted for the half relaxation time, between
6 WT and Klf10 KO fibers.

7 At the submicron scale, no significant difference was found for the static stresses (σ_s) of
8 myofibril filaments between WT and Klf10 KO animals (Fig. 5C, Table 3C, Table 4).

9 Overall, particularly at the microscopic scale, there were significant lower values ($P < 0.01$)
10 in the passive stresses and Young's modulus of the EDL muscle in the absence of Klf10
11 expression.

12

13 **4. Discussion**

14 Klf10 is known to be highly expressed in skeletal muscle (Subramaniam et al., 1995;
15 Subramaniam et al., 1998), and we have previously reported multiple scale impacts through
16 phenotypic differences in the skeletal muscle organization: increase of fiber diameter
17 (Kammoun et al., 2017), shorter sarcomere length (Kammoun et al., 2020), etc. We have also
18 discovered substantial differences in mitochondrial localization and function (Kammoun et al.,
19 2020), particularly in the soleus muscle. At the molecular level, we have also demonstrated
20 significant impacts of Klf10 on muscle metabolism (Baroukh et al., 2022).

21 The basis for the present study was to analyze the impact of Klf10 gene deletion on the
22 passive mechanical properties of fast and slow twitch skeletal muscles at the macroscopic,
23 microscopic and submicron scales. More specifically, at each scale, we have evaluated only the
24 linear elastic properties of this tissue and have compared the results to those obtained from WT

1 littermate controls. Future directions of this work will be to apply different strain rates to the
2 muscle tissue, with passive mechanical tests, which would allow for the study of the non-linear
3 responses such as Meyer's study (Meyer et al., 2011b). In addition, it is of interest to use the
4 same amplitude of strain for all specimens in order to compare the mechanical behaviors
5 between the scales.

6 An efficient way to describe the mechanical behaviors of a muscle at different scales is
7 through finite element modeling (Wheatley et al., 2016; Wheatley et al., 2017). Such modeling
8 includes a constitutive law with multiscale parameters (mechanical behavior of the underlying
9 components, microscopic and macroscopic architecture, fast and slow fibers, *etc.*) by
10 homogenization methods (May-Newman et al., 1998; Röhrle et al., 2012, Spyrou et al., 2017,
11 2019). The macroscopic behavior of the tissue is predicted by complex scale shifting operations
12 representing the intersecting phenomena between the components. In spite of these different
13 elements, the multiscale link between mechanical properties of muscle fibers and the global
14 homogenized functional behavior of striated skeletal muscle remains underexplored. One of the
15 reasons for this state of affairs is that the development and validation of such muscle models
16 requires not only the measurement of experimental data of anatomical and morphological types,
17 but also functional (or mechanical) data at both the macroscopic, microscopic and submicron
18 scales.

19 To begin to address this void, we sought to evaluate the biomechanical properties of skeletal
20 muscle at various scales and to explore how such mechanical evaluation may reveal known
21 structural phenomena. Results from the present study indicate that only the passive mechanical
22 behaviors at the microscopic scale were significantly different between Klf10 KO and WT
23 animals for both of the muscles analyzed (soleus and EDL). It should be noted that opposite
24 variations in the passive mechanical parameters for soleus and EDL were observed whereby
25 the KO fibers showed higher and lower values compared to WT fibers, respectively. These

1 results demonstrated that Klf10 has a fiber-type specific impact on skeletal muscle at the
2 microscopic scale. This may be due to the different roles of Klf10 on the oxidative and
3 glycolytic signaling pathways (Kammoun et al., 2017; Kammoun et al., 2020).

4 To gain insight into the origin of the Klf10 KO passive behaviors observed at the different
5 scales, myofibril filaments were tested as they represent the primary mechanical properties of
6 the sarcomere without the confounding effect of any extra-cellular passive components.
7 Interestingly, similar values were found between WT and Klf10 KO myofibrils for both
8 muscles. Since the primary, and virtually exclusive, passive forces in myofibrils originate from
9 the sarcomeric protein titin, it is safe to assume that the titin isoforms in Klf10 KO and WT are
10 similar and have similar mechanical properties. Indeed, a complementary analysis (Pouletaut et
11 al., 2021) on the molecular weights of titin for WT and Klf10 KO mice showed that there is no
12 difference in titin isoforms. Therefore, it may reasonably be concluded that the changes in the
13 passive properties found at the fiber level do not originate from sarcomeric structures. Thus, the
14 observed fiber-type specific changes in passive force in Klf10 KO mice are likely in the collagen-
15 based extracellular matrix surrounding the fiber.

16 Of future interest is to additionally incorporate characterization at the mesoscopic scale (*i.e.*
17 the fascicle), but at present established and validated techniques have not been reported (Meyer
18 et al., 2011a). Fascicles are surrounded by the perimysium and are composed of fibers also
19 surrounded with collagenous extracellular tissues (endomysium). Therefore, it is likely that the
20 extracellular matrix contributes to the overall mechanical properties of the whole muscle.
21 Indeed, Brashear et al. (2021) showed that the structural organization of the collagen fibers
22 within the ECM impacts the mechanical properties of the tissue. Interestingly, we have
23 previously demonstrated that loss of Klf10 expression results in a modification of the collagen
24 network which may also contribute to altered mechanical properties (Doucet et al., 2011;
25 Gumez et al., 2010). In addition, DiMario et al. (2018) demonstrated an impact of Klf10 in the

1 fibrosis process of the Duchenne myopathy disease. However, similar passive mechanical
2 properties were observed between WT and Klf10 KO hindlimb muscles in the present study. It
3 is possible that use of higher strains in these tests would allow for the detection of macroscopic
4 differences that are not observed with lesser strains. In addition, it is of interest to analyze the
5 role of Klf10 in mediating the composition and maintenance of extracellular matrix components
6 such as collagens in soleus and EDL muscles. Moreover, the cytoskeleton and/or cytoplasm
7 components and properties of muscle fiber cells could also be analyzed.

8 Recently, non-invasive imaging techniques such as elastography (Kammoun et al., 2019;
9 Qin et al., 2013) make it possible to characterize such mechanical properties *in vivo* allowing
10 for longitudinal assessment and ultimately non-invasive monitoring of pathological progression
11 in the case of specific muscle diseases. In a previous study (Ternifi et al., 2020), ultrasound
12 shear wave (SWE) elastography was performed on Klf10 KO mice and the passive mechanical
13 behaviors of a group of muscles were measured as it was not possible to independently analyze
14 slow and fast twitch muscles. Nevertheless, non-invasive imaging techniques are promising
15 tools for assessment of selected mechanical properties at the macroscopic scale, but at present,
16 *in vitro* multiscale investigation is still required for comprehensive analysis of the mechanical
17 properties at the different structural levels of muscle.

18 It has been shown that bones and tendons adapt their mechanical properties when muscles
19 change their function, for example in disease, aging or disuse. Such adaptations also take place
20 within the different structural levels of muscle, as reflected in the data presented here, thus,
21 possibly providing a better understanding of the effects of Klf10 and the mechanisms by which
22 such adaptations are initiated. This knowledge may serve in multiscale finite element models
23 of muscles in general and Klf10 KO muscles specifically. Our results regarding the differential
24 impact of Klf10 at the different structural levels may be useful in the modeling of other genetic
25 muscle diseases (such as Duchenne myopathy (DiMario et al., 2018)) when trying to identify

1 mechanisms of action, treatment therapies, and the prediction of function through disease-
2 specific muscle models.

3

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12

13 **Declaration of competing interest**

14 The authors declare that they have no competing financial interests or personal relationships
15 that could have appeared to influence the work reported in this paper.

16

17 **References**

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Figures

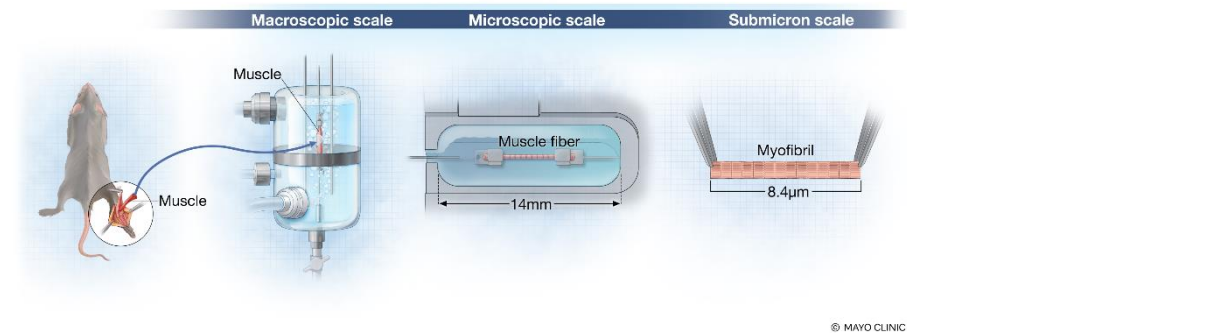


Fig. 1. Representation of the mechanical tests realized on healthy mouse at the macroscopic (muscle), microscopic (fiber) and submicron (myofibril) scales.

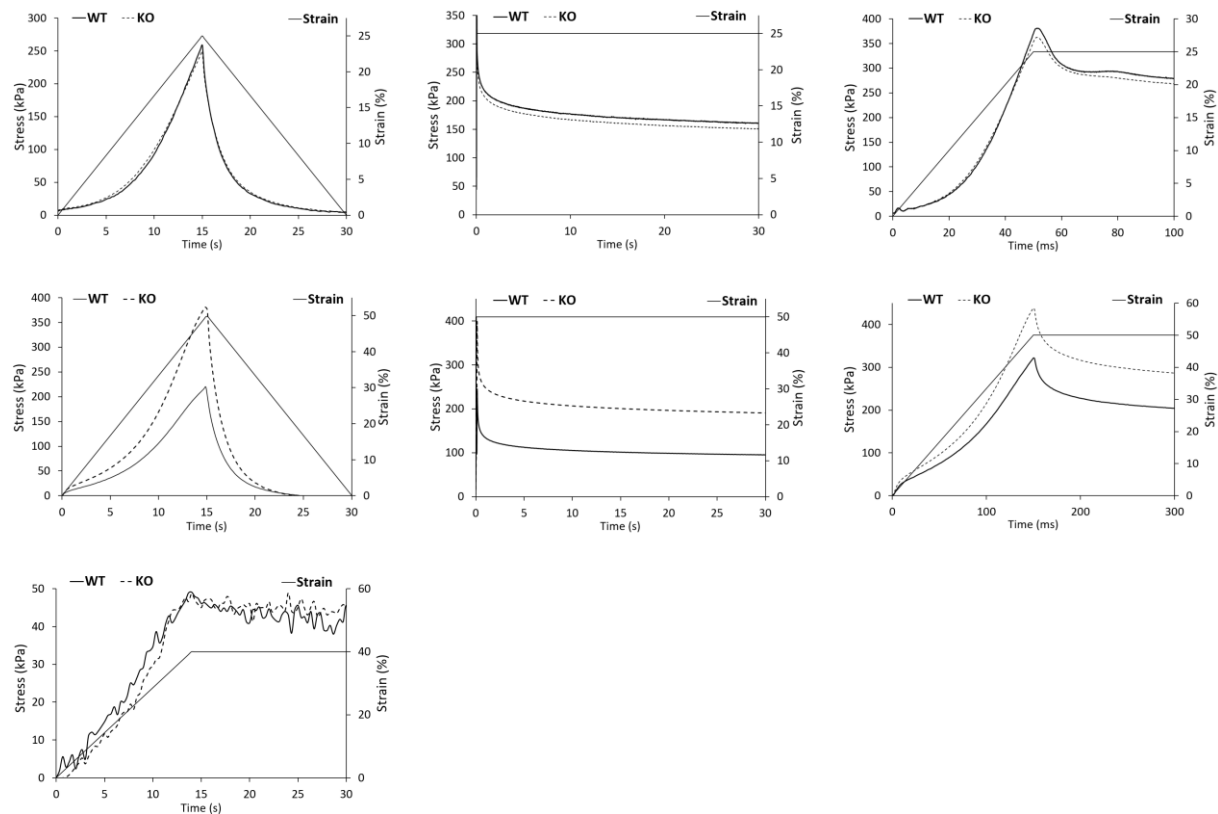
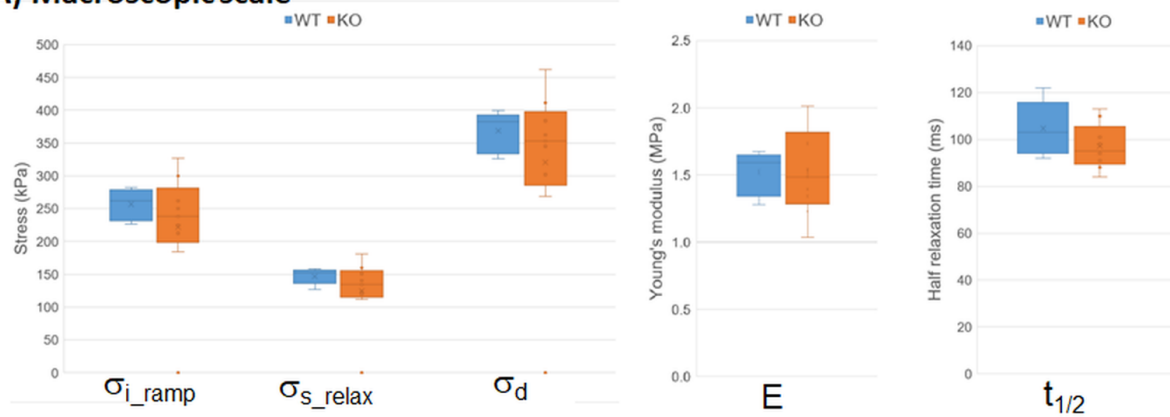
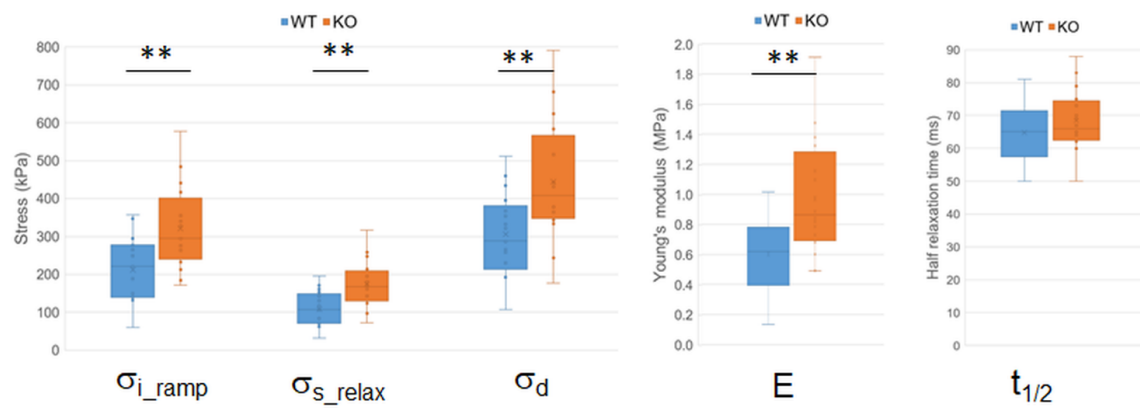


Fig. 2. Representative stress vs time curves for an exemplar ramp test (left side) and an exemplar relaxation test (middle side with a zoom of the initial stress on the right side), at the macroscopic (A), microscopic (B) and submicron (C) scales from wild type (WT) and Klf10 knockout (KO) soleus muscles. For the ramp test, the velocities were approximately $0.167 \text{ mm}\cdot\text{s}^{-1}$, $66 \text{ }\mu\text{m}\cdot\text{s}^{-1}$, $0.1 \text{ }\mu\text{m}\cdot\text{s}^{-1}$ for muscle, fiber and myofibril, respectively. For the relaxation test, the velocities were approximately $50 \text{ mm}\cdot\text{s}^{-1}$ and $6.6 \text{ mm}\cdot\text{s}^{-1}$ for muscle and fiber, respectively.

(A) Macroscopic scale



(B) Microscopic scale



(C) Submicron scale

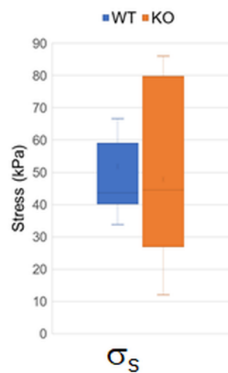


Fig. 3. Boxplots of instantaneous stress (σ_{i_Ramp}), static stress (σ_s , σ_{s_Relax}), dynamic stress (σ_d), Young's modulus (E) and half relaxation time ($t_{1/2}$) values of the soleus muscle components at the (A) macro and (B) micro scales, and for the ramp test and the relaxation test. ** : $p < 0.01$ (Mann-Whitney's test).

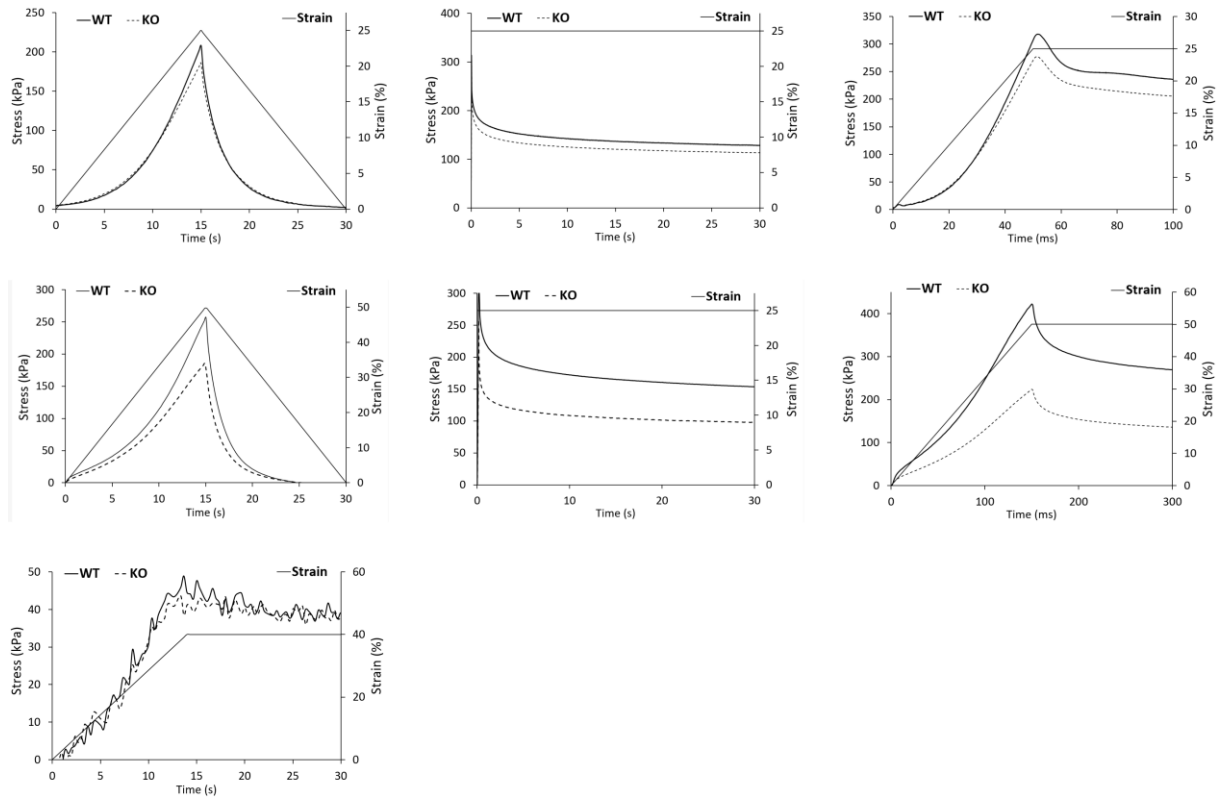
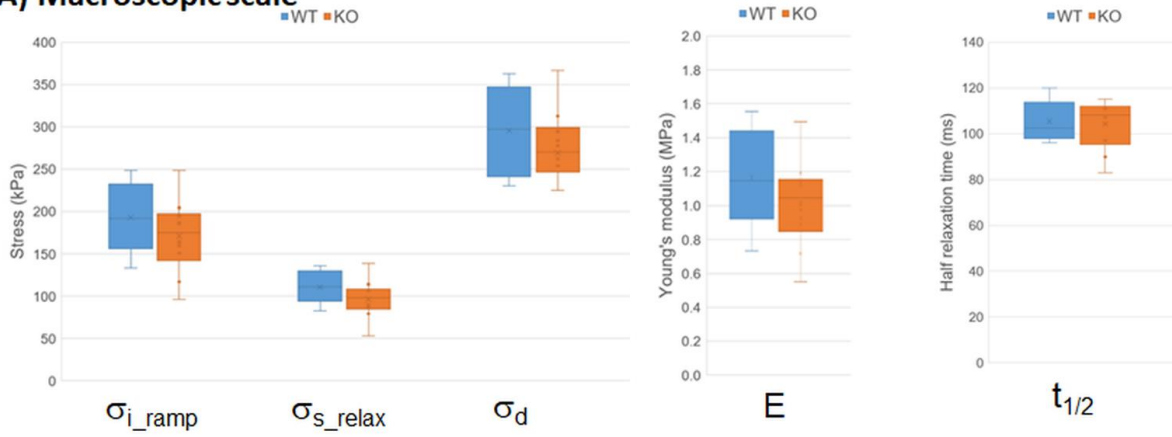
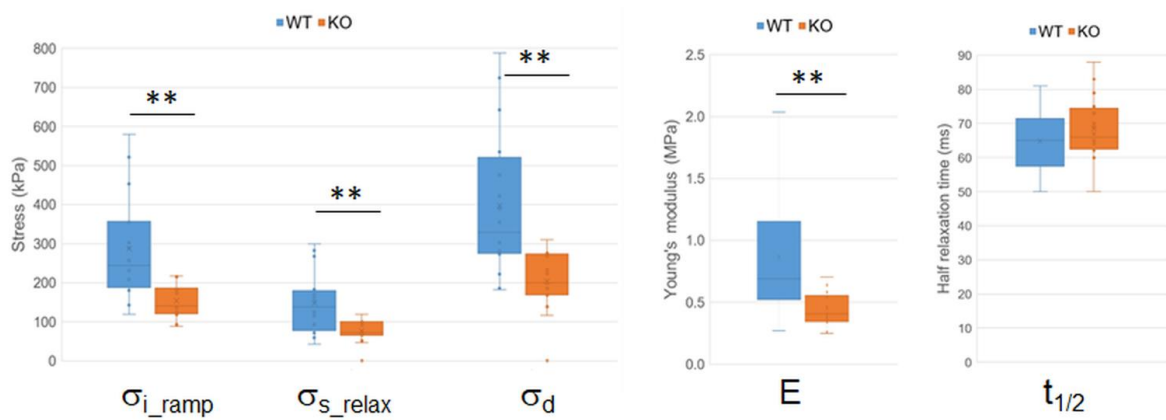


Fig. 4. Representative stress vs time curves for an exemplar ramp test (left side) and an exemplar relaxation test (middle side with a zoom of the initial stress on the right side), at the macroscopic (A), microscopic (B) and submicron (C) scales from wild type (WT) and *Klf10* knockout extensor digitorum longus (EDL) muscles. For the ramp test, the velocities were approximately $0.167 \text{ mm}\cdot\text{s}^{-1}$, $66 \text{ }\mu\text{m}\cdot\text{s}^{-1}$, $0.1 \text{ }\mu\text{m}\cdot\text{s}^{-1}$ for muscle, fiber and myofibril, respectively. For the relaxation test, the velocities were approximately $50 \text{ mm}\cdot\text{s}^{-1}$ and $6.6 \text{ mm}\cdot\text{s}^{-1}$ for muscle and fiber, respectively.

(A) Macroscopic scale



(B) Microscopic scale



(C) Submicron scale

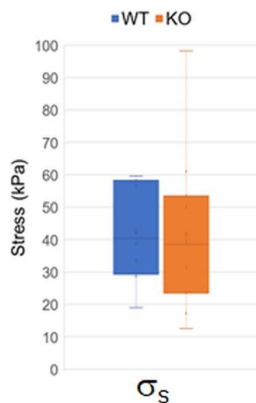


Fig. 5. Boxplots of instantaneous stress (σ_{i_Ramp}), static stress (σ_s , σ_{s_Relax}), dynamic stress (σ_d), Young's modulus (E) and half relaxation time ($t_{1/2}$) values of the extensor digitorum longus (EDL) muscle components at the (A) macro and (B) micro scales, and for the ramp test and the relaxation test. * : $p < 0.05$; ** : $p < 0.01$ (Mann-Whitney's test).