



HAL
open science

Statistical Field Theory and Neural Structures Dynamics II: Signals Propagation, Interferences, Bound States

Pierre Gosselin, Aileen Lotz

► **To cite this version:**

Pierre Gosselin, Aileen Lotz. Statistical Field Theory and Neural Structures Dynamics II: Signals Propagation, Interferences, Bound States. 2023. hal-04301181

HAL Id: hal-04301181

<https://hal.science/hal-04301181>

Preprint submitted on 30 Nov 2023

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

Statistical Field Theory and Neural Structures Dynamics II: Signals Propagation, Interferences, Bound States.

Pierre Gosselin* Aileen Lotz†

November 30, 2023

Abstract

We continue our study of a field formalism for large sets of interacting neurons, together with their connectivity functions. Expanding upon the foundation laid in ([9]), we formulate an effective formalism for the connectivity field in the presence of external sources. We proceed to deduce the propagation of external signals within the system. This enables us to investigate the activation and association of groups of bound cells.

1 Introduction

In this series of papers, we develop a field-theoretic approach to study the dynamics of connectivities in a system of interacting spiking neurons. To achieve this, in ([9]), we established a two-field model that describes both the dynamics of neural activity and the connectivity between points in the network. This field theory is the outcome of a two-step process and is based on a method originally developed in ([1]) and subsequently adapted for complex interacting systems in [2][3][4], and [5]. In the first step, we extend the standard formalism of dynamic equations for a large assembly of interacting neurons, as outlined in ([7]), to include a dynamic system accounting for the evolving nature of neural connectivity. We employ the formalism for connectivity functions presented in ([8]), which is rewritten in a format suitable for translation into field theory. In the second step, we transform this two sets of dynamic equations into a second-quantized Euclidean field theory, as detailed in (see [2][3][4] for the method). The action functional of this field theory depends on two fields. The first field, analogous to the one introduced in ([6]), characterizes the assembly of neurons, while the second field delineates the dynamics of connectivity between cells. Both fields are subject to self- interactions, depicting interactions across the network, and also interact mutually with one another, encapsulating the interdependencies between neural activities and connectivities. This field-based description encompasses both collective and individual aspects of the system. The system with these two fields is delineated by a field action functional that records the interactions at the microscopic level. This action functional comprehensively encapsulates the dynamics of the entire system.

This field-theoretic framework enables us to derive the system's effective action, as well as the corresponding background field, namely, the minimum of the effective action. This background field characterizes the collective state of the system. The field framework allows us to compute firing rates, i.e., neural activity, at each point in the system in a given background state. Additionally,

*Pierre Gosselin: Institut Fourier, UMR 5582 CNRS-UGA, Université Grenoble Alpes, BP 74, 38402 Saint Martin d'Hères, France E-Mail: Pierre.Gosselin@univ-grenoble-alpes.fr

†Aileen Lotz: Cerca Trova, BP 114, 38001 Grenoble Cedex 1, France. E-mail: a.lotz@cercatrova.eu

we can derive the propagation of perturbations in neural activity from one point to another. In a prior work ([6]), we demonstrated the existence of persistent nonlinear traveling waves along the network by considering the field action for neurons alone. In ([9]), where the field for connectivity functions is included in the system, our description enables the derivation of both background fields for neural interactions and connectivities, which minimize the action functional. These background fields represent the collective configurations of the system and dictate the potential static equilibria for neural activities and connectivities. These equilibria serve as the structural foundation of the system, governing fluctuations and the propagation of signals within it. They depend on internal parameters of the system and external stimuli. We showed the existence of several possible background states and their corresponding connectivities, the thread being mainly organized into groups of interconnected points.

Assuming that the timescale of connectivities is slower than that of individual cells, we have demonstrated how repeated activations at certain points can propagate along the thread, gradually altering the connectivity functions. Foroscillatory perturbations, the oscillatory response may exhibit interference phenomena. At points of constructive interference, both the background state for connectivities and average connectivities undergo modifications. These long-term modifications manifest as emerging states characterized by enhanced connectivities between specific points. These states are reflective of external activations and can be regarded as records of these activations. They are slowly fading over time but can be reactivated by external perturbations. Furthermore, the association of such emerging states arises if their activation occurs at similar times. The resultant state is a combination of two states, describable as a modification of the initial background state at several points. Activating one of the two states may reactivate their combination. Therefore, regardless of the cause of their activation, these enhanced connectivity states exhibit the characteristics of interacting partial neuronal assemblies.

Nonetheless, these results were derived solely by working with the connectivities field. We made use of the findings from ([6]) and did not establish our results based on interactions between the neuronal field and the connectivity field. The objective of the present work is to incorporate the interactions between these two fields and ultimately derive an effective action for the connectivities. Any modification in terms of cell activity resulting from external signals or cell interactions will then be then inherently encompassed within the effective action for the connectivity field.

This effective formalism enables us to contemplate the dynamics of the connectivity system as alterations of the connectivity field induced by external perturbations. The outcomes from ([9]) are thus recovered as transitions between initial and final states of this field. The outcomes from ([9]), such as the emergence of combined structures and the reactivation of one structure by another, thus occur within a coherent field description of the connectivity system.

This paper is organised as follows: In Part I, we provide an overview of the model and results from ([9]), Sections 2 and 3 revisit the individual dynamics of interacting neurons and the field-theoretic formulation of the model, respectively. In Section 4, we review the characteristics of the background states and qualitatively discuss the influence of external perturbations on these states.

To develop an effective field theory for the connectivity field, Part II integrates the degrees of freedom of the neuronal field in the presence of external sources out. Section 5 details the modifications to the neuronal field's path integral induced by the presence of sources. Section 6 computes the saddle-path neural activity in the presence of sources and derives the effects of interferences on this activity. Section 7 deduces the impact of interferences on the emergence of bound states.

In Part III, building on the previous sections, we derive an effective field theory for the connectivity field. Section 8 outlines the effective theory and the associated Green functions for the bound states. These Green functions are then utilized to investigate modifications in the con-

nectivity background state. In Section 9, we present various applications, including activations, associations, and reactivations of structures as externally induced transitions of the background states. We uncover the effects of interferences as consequences of these transitions. Section 10 is for the conclusion.

I. Model, static background fields and external perturbations

We present the dynamical model for cells activity and connectivities between a large set of cells. We recall the field translation of this model. We present the result of prtI: the static background fields along with the associated equilibrium connectivities and activities, and the perturbations associated with external sources. Details are given in prtI.

2 A dynamical system of interacting cells.

Following [2][3][4], we describe a system of a large number of neurons ($N \gg 1$). We define their individual equations and the dynamics for the connectivity functions.

2.1 Individual dynamics

We follow the description of [7] for coupled quadratic integrate-and-fire (QIF) neurons, but use the additional hypothesis that each neuron is characterized by its position in some spatial range.

Each neuron's potential $X_i(t)$ satisfies the differential equation:

$$\dot{X}_i(t) = \gamma X_i^2(t) + J_i(t) \quad (1)$$

for $X_i(t) < X_p$, where X_p denotes the potential level of a spike. When $X = X_p$, the potential is reset to its resting value $X_i(t) = X_r < X_p$. For the sake of simplicity, following ([7]) we have chosen the squared form $\gamma X_i^2(t)$ in (1). However any form $f(X_i(t))$ could be used. The current of signals reaching cell i at time t is written $J_i(t)$.

Our purpose is to find the system dynamics in terms of the spikes' frequencies. First, we consider the time for the n -th spike of cell i , $\theta_n^{(i)}$. This is written as a function of n , $\theta_n^{(i)}(n)$. Then, a continuous approximation $n \rightarrow t$ allows to write the spike time variable as $\theta^{(i)}(t)$. We thus have replaced:

$$\theta_n^{(i)} \rightarrow \theta^{(i)}(n) \rightarrow \theta^{(i)}(t)$$

The continuous approximation could be removed, but is convenient and simplifies the notations and computations. We assume now that the timespans between two spikes are relatively small. The time between two spikes for cell i is obtained by writing (1) as:

$$\frac{dX_i(t)}{dt} = \gamma X_i^2(t) + J_i(t)$$

and by inverting this relation to write:

$$dt = \frac{dX_i}{\gamma X_i^2 + J^{(i)}(\theta^{(i)}(n-1))}$$

Integrating the potential between two spikes thus yields:

$$\theta^{(i)}(n) - \theta^{(i)}(n-1) \simeq \int_{X_r}^{X_p} \frac{dX}{\gamma X^2 + J^{(i)}(\theta^{(i)}(n-1))}$$

Replacing $J^{(i)}(\theta^{(i)}(n-1))$ by its average value during the small time period $\theta^{(i)}(n) - \theta^{(i)}(n-1)$, we can consider $J^{(i)}(\theta^{(i)}(n-1))$ as constant in first approximation, and we find:

$$\theta^{(i)}(n) - \theta^{(i)}(n-1) \equiv G(\theta^{(i)}(n-1)) = \frac{\arctan\left(\frac{\left(\frac{1}{X_r} - \frac{1}{X_p}\right) \sqrt{\frac{J^{(i)}(\theta^{(i)}(n-1))}{\gamma}}}{1 + \frac{J^{(i)}(\theta^{(i)}(n-1))}{\gamma X_r X_p}}\right)}{\sqrt{\gamma J^{(i)}(\theta^{(i)}(n-1))}} \quad (2)$$

The activity or firing rate at t , $\omega_i(t)$, is defined by the inverse time span (2) between two spikes:

$$\omega_i(t) = \frac{1}{G(\theta^{(i)}(n-1))} \equiv F(\theta^{(i)}(n-1)) \quad (3)$$

Since we consider small time intervals between two spikes, we can write:

$$\theta^{(i)}(n) - \theta^{(i)}(n-1) \simeq \frac{d}{dt} \theta^{(i)}(t) - \omega_i^{-1}(t) = \varepsilon_i(t) \quad (4)$$

where the white noise perturbation $\varepsilon_i(t)$ for each period was added to account for any internal uncertainty in the time span $\theta^{(i)}(n) - \theta^{(i)}(n-1)$. This white noise is independent from the instantaneous inverse activity $\omega_i^{-1}(t)$. We assume these $\varepsilon_i(t)$ to have variance σ^2 , so that equation (4) writes:

$$\frac{d}{dt} \theta^{(i)}(t) - G(\theta^{(i)}(t), J^{(i)}(\theta^{(i)}(t))) = \varepsilon_i(t) \quad (5)$$

The $\omega_i(t)$ are computed by considering the overall current which, using the discrete time notation, is given by:

$$\begin{aligned} \hat{J}^{(i)}((n-1)) &= J^{(i)}((n-1)) \\ &+ \frac{\kappa}{N} \sum_{j,m} \frac{\omega_j(m)}{\omega_i(n-1)} \delta\left(\theta^{(i)}(n-1) - \theta^{(j)}(m) - \frac{|Z_i - Z_j|}{c}\right) T_{ij}((n-1, Z_i), (m, Z_j)) \end{aligned} \quad (6)$$

The quantity $J^{(i)}((n-1))$ denotes an external current. The term inside the sum is the average current sent to i by neuron j during the short time span $\theta^{(i)}(n) - \theta^{(i)}(n-1)$. The function $T_{ij}((n-1, Z_i), (m, Z_j))$ is the connectivity (or transfer) function between cells j and i . It measures the level of connectivity between i and j .

In this paper, the connectivity function is a dynamical object whose dynamic equations are described in the next paragraph. We will work in the continuous approximation, so that formula (6) is replaced by:

$$\hat{J}^{(i)}(t) = J^{(i)}(t) + \frac{\kappa}{N} \int \sum_j \frac{\omega_j(s)}{\omega_i(t)} \delta\left(\theta^{(i)}(t) - \theta^{(j)}(s) - \frac{|Z_i - Z_j|}{c}\right) T_{ij}((t, Z_i), (s, Z_j)) ds \quad (7)$$

Formula (7) shows that the dynamic equation (4) has to be coupled with the neurons activities equation:

$$\omega_i(t) = G(\theta^{(i)}(t), \hat{J}(\theta^{(i)}(t))) + v_i(t) \quad (8)$$

and $J^{(i)}(t)$ is defined by (7). A white noise $v_i(t)$ accounts for the possible deviations from this relation, due to some internal or external causes for each cell. We assume that the variances of $v_i(t)$ are constant, and equal to η^2 , such that $\eta^2 \ll \sigma^2$.

2.2 Connectivity functions dynamics

We describe the dynamics for the connectivity functions $T_{ij}((n-1, Z_i), (m, Z_j))$ between cells. To do so we adapt the description of ([8]) to our context. In this work, the connectivity functions depend on some intermediate variables and do not present any space index. The connectivity between neurons i and j satisfies a differential equation:

$$\frac{dT_{ij}}{dt} = -\frac{T_{ij}(t)}{\tau} + \lambda \hat{T}_{ij}(t) \sum_l \delta(t - \Delta t_{ij} - t_j^l) \quad (9)$$

where $\hat{T}_{ij}(t)$ represents the variation in connectivity, due to the synaptic interactions between the two neurons. The delay Δt_{ij} is the time of arrival at neuron i for a spike of neuron j . The time t_j^l accounts for time of neuron j spikes. The sum:

$$\sum_l \delta(t - \Delta t_{ij} - t_j^l)$$

counts the number of spikes emitted by neuron j and arriving at time t at neuron i .

The variation in connectivity satisfies itself an equation:

$$\frac{d\hat{T}_{ij}}{dt} = \rho \left(1 - \hat{T}_{ij}(t)\right) C_{ij}(t) \sum_k \delta(t - t_i^k) - \hat{T}_{ij}(t) D_i(t) \sum_l \delta(t - \Delta t_{ij} - t_j^l) \quad (10)$$

where $C_{ij}(t)$ and $D_i(t)$ measure the cumulated postsynaptic and presynaptic activity. The sum:

$$\sum_k \delta(t - t_i^k)$$

counts the number of spikes emitted at time t . Quantities $C_{ij}(t)$ and $D_i(t)$ follow the dynamics:

$$\frac{dC_{ij}}{dt} = -\frac{C_{ij}(t)}{\tau_C} + \alpha_C (1 - C_{ij}(t)) \sum_l \delta(t - \Delta t_{ij} - t_j^l) \quad (11)$$

$$\frac{dD_i}{dt} = -\frac{D_i(t)}{\tau_D} + \alpha_C (1 - D_i(t)) \sum_k \delta(t - t_i^k) \quad (12)$$

To translate these equations in our set up, we have to consider connectivity functions of the form:

$$T_{ij}((n_i, Z_i), (n_j, Z_j))$$

that include the positions of neurons i and j and the parameter n_i and n_j which are our counting variables of neurons spikes. However, equations (9), (10), (11), (12) include a time variable.

In our formalism, the time variable $\theta^{(i)}(n_i)$ is the time at which neuron i produces its n_i -th spike. We should write classical equations depending on these variables.

Moreover, the number of spikes $\sum_l \delta(t - \Delta t_{ij} - t_j^l)$ emitted by cell j at time t_j^l and the number of spikes $\sum_k \delta(t - t_i^k)$ emitted by cell i at time t are proportional to $\delta(\theta^{(j)}(n_j) - (t - \Delta t_{ij})) \omega_j(n_j)$ and $\delta(\theta^{(i)}(n_i) - t) \omega_i(n_i)$ respectively. Given the introduction of a spatial indices, we have the relation:

$$\Delta t_{ij} = \frac{|Z_i - Z_j|}{c}$$

and the first δ function writes:

$$\delta\left(\theta^{(j)}(n_j) - (t - \Delta t_{ij})\right) = \delta\left(\theta^{(j)}(n_j) - \left(\theta^{(i)}(n_i) - \frac{|Z_i - Z_j|}{c}\right)\right) \delta\left(\theta^{(i)}(n_i) - t\right)$$

As a consequence, we will write first the connectivity functions from i to j as:

$$T\left(\left(Z_i, \theta^{(i)}(n_i), \omega_i(n_i)\right), \left(Z_j, \theta^{(j)}(n_j), \omega_j(n_j)\right)\right)$$

This function, together with the variation in connectivity:

$$\hat{T}\left(\left(Z_i, \theta^{(i)}(n_i), \omega_i(n_i)\right), \left(Z_j, \theta^{(j)}(n_j), \omega_j(n_j)\right)\right)$$

along with the auxiliary variables:

$$C\left(\left(Z_i, \theta^{(i)}(n_i), \omega_i(n_i)\right), \left(Z_j, \theta^{(j)}(n_j), \omega_j(n_j)\right)\right)$$

and:

$$D\left(\left(Z_i, \theta^{(i)}(n_i), \omega_i(n_i)\right)\right)$$

satisfy the following translations of equations (9), (10), (11), (12):

$$\begin{aligned} & \nabla_{\theta^{(i)}(n_i)} T\left(\left(Z_i, \theta^{(i)}(n_i), \omega_i(n_i)\right), \left(Z_j, \theta^{(j)}(n_j), \omega_j(n_j)\right)\right) \\ &= -\frac{1}{\tau} T\left(\left(Z_i, \theta^{(i)}(n_i), \omega_i(n_i)\right), \left(Z_j, \theta^{(j)}(n_j), \omega_j(n_j)\right)\right) \\ & \quad + \lambda \left(\hat{T}\left(\left(Z_i, \theta^{(i)}(n_i), \omega_i(n_i)\right), \left(Z_j, \theta^{(j)}(n_j), \omega_j(n_j)\right)\right) \right) \delta\left(\theta^{(i)}(n_i) - \theta^{(j)}(n_j) - \frac{|Z_i - Z_j|}{c}\right) \end{aligned} \quad (13)$$

where \hat{T} measures the variation of T due to the signals send from j to i and the signals emitted by i . It satisfies the following equation:

$$\begin{aligned} & \nabla_{\theta^{(i)}(n_i)} \hat{T}\left(\left(Z_i, \theta^{(i)}(n_i), \omega_i(n_i)\right), \left(Z_j, \theta^{(j)}(n_j), \omega_j(n_j)\right)\right) \\ &= \rho \delta\left(\theta^{(i)}(n_i) - \theta^{(j)}(n_j) - \frac{|Z_i - Z_j|}{c}\right) \\ & \quad \times \left\{ \left(h(Z, Z_1) - \hat{T}\left(\left(Z_i, \theta^{(i)}(n_i), \omega_i(n_i)\right), \left(Z_j, \theta^{(j)}(n_j), \omega_j(n_j)\right)\right) \right) C\left(\theta^{(i)}(n)\right) h_C\left(\omega_i(n_i)\right) \right. \\ & \quad \left. - D\left(\theta^{(i)}(n)\right) \hat{T}\left(\left(Z_i, \theta^{(i)}(n_i), \omega_i(n_i)\right), \left(Z_j, \theta^{(j)}(n_j), \omega_j(n_j)\right)\right) h_D\left(\omega_j(n_j)\right) \right\} \end{aligned} \quad (14)$$

where h_C and h_D are increasing functions. In the set of equations (9), (10), (11), (12):

$$\begin{aligned} h_C\left(\omega_i(n_i)\right) &= \omega_i(n_i) \\ h_D\left(\omega_j(n_j)\right) &= \omega_j(n_j) \end{aligned}$$

We depart slightly from ([8]) by the introduction of the function $h(Z, Z_1)$ (they choose $h(Z, Z_1) = 1$), to implement some loss due to the distance. We may choose for example:

$$h(Z, Z_1) = \exp\left(-\frac{|Z_i - Z_j|}{\nu c}\right)$$

where ν is a parameter. Equation (14) involves two dynamic factors $C(\theta^{(i)}(n-1))$ and $D(\theta^{(i)}(n-1))$. The factor $C(\theta^{(i)}(n-1))$ describes the accumulation of input spikes. It is solution of the differential equation:

$$\begin{aligned} \nabla_{\theta^{(i)}(n-1)} C\left(\theta^{(i)}(n-1)\right) &= -\frac{C\left(\theta^{(i)}(n-1)\right)}{\tau_C} \\ & \quad + \alpha_C \left(1 - C\left(\theta^{(i)}(n-1)\right)\right) \omega_j\left(\theta^{(i)}(n-1) - \frac{|Z_i - Z_j|}{c}\right) \end{aligned} \quad (15)$$

The term $D(\theta_i(n-1))$ is proportional to the accumulation of output spikes and is solution of:

$$\nabla_{\theta^{(i)}(n-1)} D(\theta^{(i)}(n-1)) = -\frac{D(\theta^{(i)}(n-1))}{\tau_D} + \alpha_D \left(1 - D(\theta^{(i)}(n-1))\right) \omega_i(n_i) \quad (16)$$

For the purpose of field translation, we have to change the variables in the derivatives by the counting variable n_i

and replace $\nabla_{\theta^{(i)}(n_i)} \simeq \omega_i(n_i) \nabla_{n_i}$ in the previous dynamics equations. We thus rewrite the dynamic equations in the following form:

For the connectivity T :

$$\begin{aligned} & \nabla_{n_i} T \left(\left(Z_i, \theta^{(i)}(n_i), \omega_i(n_i) \right), \left(Z_j, \theta^{(j)}(n_j), \omega_j(n_j) \right) \right) \\ &= -\frac{1}{\tau \omega_i(n_i)} T \left(\left(Z_i, \theta^{(i)}(n_i), \omega_i(n_i) \right), \left(Z_j, \theta^{(j)}(n_j), \omega_j(n_j) \right) \right) \\ &+ \frac{\lambda}{\omega_i(n_i)} \left(\hat{T} \left(\left(Z_i, \theta^{(i)}(n_i), \omega_i(n_i) \right), \left(Z_j, \theta^{(j)}(n_j), \omega_j(n_j) \right) \right) \right) \delta \left(\theta^{(i)}(n_i) - \theta^{(j)}(n_j) - \frac{|Z_i - Z_j|}{c} \right) \end{aligned} \quad (17)$$

For the variation in connectivity \hat{T} :

$$\begin{aligned} & \nabla_{n_i} \hat{T} \left(\left(Z_i, \theta^{(i)}(n_i), \omega_i(n_i) \right), \left(Z_j, \theta^{(j)}(n_j), \omega_j(n_j) \right) \right) \\ &= \frac{\rho}{\omega_i(n_i)} \delta \left(\theta^{(i)}(n_i) - \theta^{(j)}(n_j) - \frac{|Z_i - Z_j|}{c} \right) \\ &\times \left\{ \left(h(Z, Z_1) - \hat{T} \left(\left(Z_i, \theta^{(i)}(n_i), \omega_i(n_i) \right), \left(Z_j, \theta^{(j)}(n_j), \omega_j(n_j) \right) \right) \right) C \left(\theta^{(i)}(n-1) \right) h_C(\omega_i(n_i)) \right. \\ &\left. - D \left(\theta^{(i)}(n-1) \right) \hat{T} \left(\left(Z_i, \theta^{(i)}(n_i), \omega_i(n_i) \right), \left(Z_j, \theta^{(j)}(n_j), \omega_j(n_j) \right) \right) h_D(\omega_j(n_j)) \right\} \end{aligned} \quad (18)$$

and for the auxiliary variables C and D :

$$\begin{aligned} \nabla_{n_i} C \left(\theta^{(i)}(n-1) \right) &= -\frac{C \left(\theta^{(i)}(n-1) \right)}{\tau_C \omega_i(n_i)} \\ &+ \alpha_C \left(1 - C \left(\theta^{(i)}(n-1) \right) \right) \frac{\omega_j \left(Z_j, \theta^{(i)}(n-1) - \frac{|Z_i - Z_j|}{c} \right)}{\omega_i(n_i)} \end{aligned} \quad (19)$$

and:

$$\nabla_{n_i} D \left(\theta^{(i)}(n-1) \right) = -\frac{D \left(\theta^{(i)}(n-1) \right)}{\tau_D \omega_i(n_i)} + \alpha_D \left(1 - D \left(\theta^{(i)}(n-1) \right) \right) \quad (20)$$

Then, to describe the connectivity by a field, we have to describe the connectivity as a set of vectors depending of a set of double indices kl (replacing ij) and interacting with the neurons activities, seen as independent variables indexed by i, j, \dots

We thus describe connectivity by a set of matrices:

$$\left(T_{kl}(n_{kl}), \hat{T}_{kl}(n_{kl}), (Z_{kl}(n_{kl}) = (Z_k, Z_l)), \theta^{(kl)}(n_{kl}), \omega_k(n_{kl}), \omega'_l(n_{kl}), C_{kl}(n_{kl}), D_k(n_{kl}) \right)$$

where n_{kl} is an internal parameter given by the average counting variable for cells or synapses firing simultaneously at point Z_k .

Then, we replace the description (17), (18), (19), (20) by a set of equation in which connectivity $T_{kl}(n_{kl})$ interact with all pairs of neurons at points Z_k , and Z_l whose average activities at time $\theta^{(kl)}(n_{kl})$ and $\theta^{(kl)}(n_{kl}) - \frac{|Z_k - Z_l|}{c}$ are given by $\omega_k(n_{kl}), \omega'_l(n_{kl})$ respectively. As a consequence, we

replace the notion of connectivity $T_{ij}((n-1, Z_i), (m, Z_j))$ between two specific neurons i and j by the average connectivity between the two sets of neurons with identical activities at each extremity of the segment (Z_i, Z_j) . This approximation justifies if we consider that neurons located at the same place and firing at the same rate can be considered as closely connected and in average identical.

Stated mathematically, variable is an average $n_{kl} = \bar{n}_i$ at a given time $\theta^{(kl)}$ and we assume that in average, connectivity variable $T_{kl}(n_{kl})$ interacts with all neurons pairs located at (Z_k, Z_l) at times $\theta^{(i)}(n_i) = \theta^{(kl)}(n_{kl})$. Writing $\bar{\omega}(Z_i, n_i)$ for the average activity, we impose $\bar{\omega}(Z_i, n_i) = \omega_k(n_{kl})$ and $\bar{\omega}(Z_j, n_j) = \omega_l(n_{kl})$ and $\theta^{(j)}(n_j) = \theta^{(kl)}(n_{kl}) - \frac{|Z_k - Z_l|}{c}$ respectively. The densities $T_{kl}(n_{kl})$ are thus the set of all connections between points Z_k , and Z_l between sets of synchronized neurons at Z_k and synchronized neurons at Z_l , i.e. between set of neurons or synapses at this points. In this point of view, we replace $\nabla_{\theta^{(i)}(n_i)} \simeq \omega_i(n_i) \nabla_{n_i}$ by:

$$\nabla_{\theta^{(kl)}(n_{kl})} \simeq \frac{\partial n_{kl}}{\partial \theta^{(kl)}(n_{kl})} \nabla_{n_{kl}} = \bar{\omega}(Z_i, n_i) \nabla_{n_{kl}}$$

As a consequence, the dynamic equations (17), (18), (19), (20) are replaced by:

$$\begin{aligned} \nabla_{n_{kl}} T_{kl}(n_{kl}) = & \left(- \sum_{i, n_i} \frac{1}{\tau \bar{\omega}(Z_i, n_i)} T_{kl}(n_{kl}) + \frac{\lambda}{\bar{\omega}(Z_i, n_i)} \hat{T}_{kl}(n_{kl}) \right) \\ & \times \delta \left(\theta^{(i)}(n_i) - \theta^{(kl)}(n_{kl}) \right) \delta(Z_k - Z_i) \delta(\omega_k(n_{kl}) - \bar{\omega}(Z_i, n_i)) \end{aligned} \quad (21)$$

$$\begin{aligned} & \nabla_{n_{kl}} \hat{T}(n_{kl}) \\ = & \left(\sum_{i, n_i} \left(h(Z_k, Z_l) - \hat{T}(n_{kl}) \right) C_{kl}(n_{kl}) h_C(\omega_i(n_i)) - \sum_{j, n_j} D_k(n_{kl}) \hat{T}(n_{kl}) h_D(\omega_j(n_j)) \right) \\ & \times \frac{\rho}{\bar{\omega}(Z_i, n_i)} \delta \left(\theta^{(i)}(n_i) - \theta^{(j)}(n_j) - \frac{|Z_i - Z_j|}{c} \right) \delta \left(\theta^{(i)}(n_i) - \theta^{(kl)}(n_{kl}) \right) \\ & \times \delta((Z_k, Z_l) - (Z_i, Z_j)) \delta(\omega_k(n_{kl}) - \bar{\omega}(Z_i, n_i)) \delta(\omega_l(n_{kl}) - \bar{\omega}(Z_j, n_j)) \end{aligned} \quad (22)$$

$$\begin{aligned} \nabla_{n_{kl}} C(n_{kl}) = & \left(- \frac{C(n_{kl})}{\tau_C \bar{\omega}(Z_i, n_i)} + \sum_{j, n_j} \alpha_C (1 - C_{kl}(n_{kl})) \frac{\omega_j(n_j)}{\bar{\omega}(Z_i, n_i)} \right) \\ & \times \delta \left(\theta^{(i)}(n_i) - \theta^{(j)}(n_j) - \frac{|Z_i - Z_j|}{c} \right) \delta \left(\theta^{(i)}(n_i) - \theta^{(kl)}(n_{kl}) \right) \delta((Z_k, Z_l) - (Z_i, Z_j)) \\ & \times \delta(\omega_k(n_{kl}) - \bar{\omega}(Z_i, n_i)) \delta(\omega_l(n_{kl}) - \bar{\omega}(Z_j, n_j)) \end{aligned} \quad (23)$$

$$\begin{aligned} \nabla_{n_{kl}} D_k(n_{kl}) = & \left(- \frac{D_k(n_{kl})}{\tau_D \bar{\omega}(Z_i, n_i)} + \frac{1}{\bar{\omega}(Z_i, n_i)} \sum_{i, n_i} \alpha_D (1 - D_k(n_{kl})) \omega_i(n_i) \right) \\ & \times \delta \left(\theta^{(i)}(n_i) - \theta^{(kl)}(n_{kl}) \right) \delta(Z_k - Z_i) \delta(\omega_k(n_{kl}) - \bar{\omega}(Z_i, n_i)) \delta(\omega_l(n_{kl}) - \bar{\omega}(Z_j, n_j)) \end{aligned} \quad (24)$$

Similarly, note that we can also rewrite the currents equation (6) as:

$$\hat{J}^{(i)}((n-1)) = J^{(i)}((n-1)) + \frac{\kappa}{N} \sum_{j, m} \frac{\omega_j(m)}{\omega_i(n-1)} \delta \left(\theta^{(i)}(n-1) - \theta^{(j)}(m) - \frac{|Z_i - Z_j|}{c} \right) T_{ij}((n-1, Z_i), (m, Z_j))$$

with:

$$T_{ij}((n_i, Z_i), (m_j, Z_j)) = \sum_{kl} T_{kl}(n_{kl}) \delta \left(\theta^{(i)}(n_i) - \theta^{(kl)}(n_{kl}) \right) \delta(\omega_k(n_{kl}) - \bar{\omega}(Z_i, n_i)) \delta(\omega_l(n_{kl}) - \bar{\omega}(Z_j, n_j)) \quad (25)$$

3 Field theoretic translation of the system

This section presents the translation of the system neurons+connectivities dynamics in terms of fields. The detailed derivation was given in ([9]).

3.1 translation of Equation (5) in terms of field theory

We have shown in [2][3][4] that the probabilistic description of dynamic system for a large number of degrees of freedom is equivalent to a statistical field formalism. A concise version of this method is given in ([5]) and this method was applied in ([9]) to derive the field theory counterpart of the system presented in section 2.

Within this formalism, the system is collectively described by a field, which is an element of the Hilbert space of complex functions. The arguments of these functions correspond to the parameters used to describe an individual neuron. In this study, we will present the results directly.

The fields action for the neurons activity is a functional for the field $\Psi(\theta, Z, \omega)$ and encompasses the dynamics (5) along with the activities described by (3) and (6):

$$S = -\frac{1}{2}\Psi^\dagger(\theta, Z, \omega) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - \omega^{-1} \right) \Psi(\theta, Z, \omega) \quad (26)$$

$$+ \frac{1}{2\eta^2} \int |\Psi(\theta, Z, \omega)|^2 \left(\omega^{-1} - G \left(J(\theta, Z) + \int \frac{\kappa \omega_1}{N \omega} \left| \Psi \left(\theta - \frac{|Z - Z_1|}{c}, Z_1, \omega_1 \right) \right|^2 T(Z, \theta, Z_1) dZ_1 d\omega_1 \right) \right)^2$$

Using the fact that $\eta^2 \ll 1$, we showed in ([9]) that we can restrict the fields to those of the form:

$$\Psi(\theta, Z) \delta \left(\omega^{-1} - \omega^{-1} \left(J, \theta, Z, |\Psi|^2 \right) \right) \quad (27)$$

where $\omega^{-1} \left(J, \theta, Z, |\Psi|^2 \right)$ satisfies:

$$\omega^{-1} \left(J, \theta, Z, |\Psi|^2 \right) \quad (28)$$

$$= G \left(J(\theta, Z) + \int \frac{\kappa}{N} \frac{\omega \left(J, \theta - \frac{|Z - Z_1|}{c}, Z_1, \Psi \right) T \left(Z, \theta, Z_1, \theta - \frac{|Z - Z_1|}{c} \right)}{\omega \left(J, \theta, Z, |\Psi|^2 \right)} \left| \Psi \left(\theta - \frac{|Z - Z_1|}{c}, Z_1 \right) \right|^2 dZ_1 \right)$$

The "classical" effective action becomes (see ([9])):

$$-\frac{1}{2}\Psi^\dagger(\theta, Z) \left(\nabla_\theta \left(\frac{\sigma_\theta^2}{2} \nabla_\theta - \omega^{-1} \left(J, \theta, Z, |\Psi|^2 \right) \right) \right) \Psi(\theta, Z) \quad (29)$$

with $\omega^{-1} \left(J, \theta, Z, |\Psi|^2 \right)$ given by equation (28). As in ([6]) we add to this action a stabilization potential $V(\Psi)$ ensuring an average activity of the system. The precise form of this potential is irrelevant here, but we assume that it has a minimum $\Psi_0(\theta, Z)$.

3.2 Translation for connectivity dynamics

The translation of the four action terms describing the connectivity dynamics (21), (22), (23) and (24) is straightforward. Taking into account the projection (27), we obtain four terms: $S_\Gamma^{(1)}$, $S_\Gamma^{(2)}$, $S_\Gamma^{(3)}$, $S_\Gamma^{(4)}$:

$$S_\Gamma^{(1)} = \int \Gamma^\dagger \left(T, \hat{T}, \theta, Z, Z', C, D \right) \nabla_T \left(\frac{\sigma_T^2}{2} \nabla_T - \left(-\frac{1}{\tau\omega} T + \frac{\lambda}{\omega} \hat{T} \right) \right) \Gamma \left(T, \hat{T}, \theta, Z, Z', C, D \right) \quad (30)$$

$$\begin{aligned}
S_{\Gamma}^{(2)} &= \int \Gamma^{\dagger} \left(T, \hat{T}, \theta, Z, Z', C, D \right) \\
&\times \nabla_{\hat{T}} \left(\frac{\sigma_{\hat{T}}^2}{2} \nabla_{\hat{T}} - \frac{\rho}{\omega} \left(\left(h(Z, Z') - \hat{T} \right) C |\Psi(\theta, Z)|^2 h_C(\omega) \right. \right. \\
&\quad \left. \left. - D \hat{T} \left| \Psi \left(\theta - \frac{|Z - Z'|}{c}, Z' \right) \right|^2 h_D(\omega') \right) \right) \Gamma \left(T, \hat{T}, \theta, Z, Z', C, D \right)
\end{aligned} \tag{31}$$

$$\begin{aligned}
S_{\Gamma}^{(3)} &= \Gamma^{\dagger} \left(T, \hat{T}, \theta, Z, Z', C, D \right) \\
&\times \nabla_C \left(\frac{\sigma_C^2}{2} \nabla_C + \left(\frac{C}{\tau_C \omega} - \alpha_C (1 - C) \frac{\omega' \left| \Psi \left(\theta - \frac{|Z - Z'|}{c}, Z' \right) \right|^2}{\omega} \right) \right) \\
&\times \Gamma \left(T, \hat{T}, \theta, Z, Z', C, D \right)
\end{aligned} \tag{32}$$

$$S_{\Gamma}^{(4)} = \Gamma^{\dagger} \left(T, \hat{T}, \theta, Z, Z', C, D \right) \nabla_D \left(\frac{\sigma_D^2}{2} \nabla_D + \left(\frac{D}{\tau_D \omega} - \alpha_D (1 - D) |\Psi(\theta, Z)|^2 \right) \right) \Gamma \left(T, \hat{T}, \theta, Z, Z', C, D \right) \tag{33}$$

with:

$$\begin{aligned}
\omega &= \omega \left(J, \theta, Z, |\Psi|^2 \right) \\
\omega' &= \omega \left(J, \theta - \frac{|Z - Z'|}{c}, Z', |\Psi|^2 \right)
\end{aligned}$$

and:

$$h(Z, Z') = \exp \left(-\frac{|Z - Z'|}{\nu c} \right)$$

3.3 Full action for the system and partition function

The full action for the system is obtained by gathering the different terms:

$$\begin{aligned}
S_{full} &= -\frac{1}{2} \Psi^{\dagger}(\theta, Z, \omega) \nabla \left(\frac{\sigma_{\theta}^2}{2} \nabla - \omega^{-1} \left(J, \theta, Z, |\Psi|^2 \right) \right) \Psi(\theta, Z) + V(\Psi) \\
&\quad + \frac{1}{2\eta^2} \left(S_{\Gamma}^{(0)} + S_{\Gamma}^{(1)} + S_{\Gamma}^{(2)} + S_{\Gamma}^{(3)} + S_{\Gamma}^{(4)} \right) + U \left(\left\{ |\Gamma(\theta, Z, Z', C, D)|^2 \right\} \right)
\end{aligned} \tag{34}$$

with $S_{\Gamma}^{(1)}$, $S_{\Gamma}^{(2)}$, $S_{\Gamma}^{(3)}$, $S_{\Gamma}^{(4)}$ given by (30), (31), (32), (33). In (34), we added a potential:

$$U \left(\left\{ |\Gamma(\theta, Z, Z', C, D)|^2 \right\} \right) = U \left(\int T \left| \Gamma \left(T, \hat{T}, \theta, Z, Z', C, D \right) \right|^2 dT d\hat{T} \right)$$

that models the constraint about the number of active connections in the system.

The partition function of the system is given by:

$$\exp \left(-S_{full} \left((\Psi^{\dagger}, \Psi), (\Gamma, \Gamma^{\dagger}) \right) \right) \mathcal{D}(\Psi^{\dagger}, \Psi) \mathcal{D}(\Gamma, \Gamma^{\dagger})$$

4 Background state and perturbation

4.1 Background state

We showed in ([9]) that S_{full} present several possible minima. These minima are characterized by the shape of $|\Psi(\theta, Z)|^2$ and $\Gamma(T, \hat{T}, \theta, Z, Z', C, D)$ for every point Z and doublet (Z, Z') . The derivation proceeds in several steps. We first derive the saddle point $|\Psi(\theta, Z)|^2$ of:

$$-\frac{1}{2}\Psi^\dagger(\theta, Z, \omega) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - \omega^{-1} (J, \theta, Z, |\Psi|^2) \right) \Psi(\theta, Z) + V(\Psi)$$

as a function of the connectivity field Γ and then work with an effective action:

$$S_\Gamma^{(0)} + S_\Gamma^{(1)} + S_\Gamma^{(2)} + S_\Gamma^{(3)} + S_\Gamma^{(4)}$$

for this field. In first approximation, the field Γ can be decomposed as a product:

$$\Gamma(T, \hat{T}, \theta, Z, Z', C, D) = \Gamma_C(\theta, Z, Z', C) \Gamma_D(\theta, Z, Z', D) \Gamma(\hat{T}, T, \theta, Z, Z')$$

and this allows to compute the background values for Γ_C and Γ_D , leading ultimately to consider an action $S_\Gamma^{(1)} + S_\Gamma^{(2)}$ for:

$$\Gamma(\hat{T}, T, \theta, Z, Z')$$

with C and D replaced by their background values $\langle C \rangle$ and $\langle D \rangle$. For later purposes we recall this action here:

$$\begin{aligned} & S(\Gamma(T, \hat{T}, \theta, Z, Z')) \tag{35} \\ = & \Gamma^\dagger(T, \hat{T}, \theta, Z, Z') \left[\nabla_T \left(\nabla_T - \left(\frac{-T + \lambda \hat{T}}{\tau \omega_0(Z)} \right) |\Psi(\theta, Z)|^2 \right) \right. \\ & + \nabla_{\hat{T}} \left(\nabla_{\hat{T}} - \rho \left((h(Z, Z') - \hat{T}) \langle C \rangle |\Psi_0(Z)|^2 \frac{h_C(\omega_0(Z) + \Delta \omega_0(Z, |\Psi|^2))}{\omega_0(Z)} \right. \right. \\ & \left. \left. - \eta H(\delta - T) - \langle D \rangle \hat{T} |\Psi_0(Z')|^2 \frac{h_D(\omega_0(Z'))}{\omega_0(Z)} \right) \right) \Gamma(T, \hat{T}, \theta, Z, Z') \end{aligned}$$

We derive the saddle-points solutions and compute the associated averages for a static regime and under some approximations. The background is determined by two possibilities for Γ for all (Z, Z') . These possibilities describe an activated state $\Gamma_a(T, \hat{T}, \theta, Z, Z', C, D)$ and an unactivated one $\Gamma_u(T, \hat{T}, \theta, Z, Z', C, D)$.

We also showed how to derive the average connectivities in such background states. These averages satisfy some set of equations:

$$\begin{aligned} \langle C_{Z, Z'} \rangle &= \frac{\alpha_C \omega' \left| \Psi \left(\theta - \frac{|Z-Z'|}{c}, Z' \right) \right|^2}{\frac{1}{\tau_C} + \alpha_C \omega' \left| \Psi \left(\theta - \frac{|Z-Z'|}{c}, Z' \right) \right|^2} \tag{36} \\ \langle D_{Z, Z'} \rangle &= \frac{\alpha_D \omega \left| \Psi(\theta, Z) \right|^2}{\frac{1}{\tau_D} + \alpha_D \omega \left| \Psi(\theta, Z) \right|^2} \end{aligned}$$

$$\begin{aligned}
\langle T(Z, Z') \rangle &= \lambda\tau \langle \hat{T}(Z, Z') \rangle \\
&= \frac{\lambda\tau h(Z, Z') \langle C_{Z, Z'}(\theta) |\Psi(\theta, Z)|^2 \rangle}{|\bar{\Psi}(\theta, Z, Z')|^2}
\end{aligned} \tag{37}$$

with:

$$|\bar{\Psi}(\theta, Z, Z')|^2 = \frac{C_{Z, Z'}(\theta) |\Psi(\theta, Z)|^2 h_C(\omega(\theta, Z)) + D_{Z, Z'}(\theta) \left| \Psi\left(\theta - \frac{|Z-Z'|}{c}, Z'\right) \right|^2 h_D\left(\omega\left(\theta - \frac{|Z-Z'|}{c}, Z'\right)\right)}{h_C(\omega(\theta, Z))} \tag{38}$$

for (Z, Z') an "a" (active) doublet, and:

$$\langle T(Z, Z') \rangle = 0 \tag{39}$$

$$\langle \hat{T}(Z, Z') \rangle = \frac{h(Z, Z') \langle C_{Z, Z'}(\theta) h_C(\omega(\theta, Z)) |\Psi(\theta, Z)|^2 \rangle - \eta}{\langle h_C(\omega(\theta, Z)) |\bar{\Psi}(\theta, Z, Z')|^2 \rangle} < 0 \tag{40}$$

We obtained under some assumptions and in the static case, the possible averages values for the connectvt functns:

$$\begin{aligned}
T(Z_-, Z'_+) &= \frac{\lambda\tau \exp\left(-\frac{|Z-Z'|}{\nu c}\right) \left(\frac{1}{\tau_D \alpha_D} + \frac{1}{b\bar{T}^2 \langle |\Psi_0(Z')|^2 \rangle_Z}\right)}{\frac{1}{\tau_D \alpha_D} + \frac{1}{\alpha_C \tau_C} + \frac{1}{b\bar{T}^2 \langle |\Psi_0(Z')|^2 \rangle_Z} + b\bar{T} \left(\bar{T} \langle |\Psi_0(Z')|^2 \rangle_{Z'}^2\right)^2} \simeq 0 \\
T(Z_+, Z'_+) &= \frac{\lambda\tau \exp\left(-\frac{|Z-Z'|}{\nu c}\right) \left(\frac{1}{\tau_D \alpha_D} + b\bar{T} \left(\bar{T} \langle |\Psi_0(Z')|^2 \rangle_Z^2\right)^2\right)}{\frac{1}{\tau_D \alpha_D} + \frac{1}{\alpha_C \tau_C} + b\bar{T} \left(\bar{T} \langle |\Psi_0(Z')|^2 \rangle_Z^2\right)^2 + b\bar{T} \left(\bar{T} \langle |\Psi_0(Z')|^2 \rangle_{Z'}^2\right)^2} \simeq \frac{\lambda\tau \exp\left(-\frac{|Z-Z'|}{\nu c}\right)}{2} \\
T(Z_+, Z'_-) &= \frac{\lambda\tau \exp\left(-\frac{|Z-Z'|}{\nu c}\right) \left(\frac{1}{\tau_D \alpha_D} + b\bar{T} \left(\bar{T} \langle |\Psi_0(Z')|^2 \rangle_Z^2\right)^2\right)}{\frac{1}{\tau_D \alpha_D} + \frac{1}{\alpha_C \tau_C} + b\bar{T} \left(\bar{T} \langle |\Psi_0(Z')|^2 \rangle_Z^2\right)^2 + \frac{1}{b\bar{T}^2 \langle |\Psi_0(Z')|^2 \rangle_{Z'}}} \simeq \lambda\tau \exp\left(-\frac{|Z-Z'|}{\nu c}\right) \\
T(Z_-, Z'_-) &\simeq \frac{\lambda\tau \exp\left(-\frac{|Z-Z'|}{\nu c}\right) + \frac{1}{b\bar{T}^2 \langle |\Psi_0(Z')|^2 \rangle_Z}}{1 + \frac{\tau_D \alpha_D}{\alpha_C \tau_C} + \frac{1}{b\bar{T}^2 \langle |\Psi_0(Z')|^2 \rangle_Z} + \frac{1}{b\bar{T}^2 \langle |\Psi_0(Z')|^2 \rangle_{Z'}}} \simeq \frac{\lambda\tau \exp\left(-\frac{|Z-Z'|}{\nu c}\right)}{2}
\end{aligned} \tag{41}$$

with $\bar{T} = \frac{\lambda\tau\nu cb}{2}$, b a coefficient characterizing the function G in the linear approximation¹ and $\langle |\Psi_0(Z')|^2 \rangle_Z^2$, $\langle |\Psi_0(Z')|^2 \rangle_{Z'}^2$ are some averaged background fields in regions surrounding Z and Z' respectvl. They are determined by a potential describing some average activity depending on the points. These results are derived under the assumption of a static field $\Psi_0(Z)$.

4.2 source induced perturbation of the static background state

In ([9]), we also showed with qualitative arguments how an external activation may modify the solutions of equations (36) and (37) (or (39) and (40)) for connectivity functions averages. Actually external signals modify the field $\Psi_0(\theta, Z)$:

$$\Psi_0(\theta, Z) \rightarrow \Psi_0(\theta, Z) + \delta\Psi(\theta, Z)$$

¹ $b \simeq G'(0)$

and induce a modification $\delta\omega(J, \theta, Z, |\Psi|^2)$. This modifies in turn the set of equations for $T(Z, Z')$. In ([6]) we showed that oscillating signals can induce non linear oscillatory response $\delta\omega(J, \theta, Z, |\Psi|^2)$ and produce interferences phenomena. These phenomena modify the solutions (41), linking points where interferences induced perturbations $\delta\omega(J, \theta, Z, |\Psi|^2)$ have a large amplitude, leading to some emerging connected structures. We also discussed how such structures may interact and activate each other.

However, these results were derived qualitatively in the context of switching static states. The next sections provide the dynamical study of these phenomena in terms of field theory.

II Effective field theoretic approach to transitions of connectivity states

In this part, we provide a rationale for adopting the local approach employed in the initial part of this study ([9]) by using the system's effective action. We elucidate the dynamic aspects of the system presented in ([9]) within the framework of the field model. This approach is non-local in nature due to the involvement of interactions between distant interconnected points.

The underlying principle remains consistent with our prior work. Our objective is to integrate the degrees of freedom of the neuron field with respect to the connectivity field, denoted as Γ . This procedure results in the generation of an effective action for the field Γ , enabling the investigation of state transitions in connectivity. However, within a dynamic context, this integration of degrees of freedom must account for external perturbations that alter the path integral associated with the neuron field Ψ . We will evaluate this path integral by developing a time-dependent series expansion for neural activity $\omega(J, \theta, Z)$, which depends both on the connectivity field and the perturbation component of the field Ψ , written $\Delta\Psi(\theta, Z)$.

5 Principle: Integration of neuron field degrees of freedom in presence of external perturbation

As a general method for integrating the Ψ degrees of freedom, we start with the action functional for cell field alone, along with its partition function:

$$\int \exp\left(\frac{1}{2}\Psi^\dagger(\theta, Z, \omega) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - \omega^{-1}(J, \theta, Z, |\Psi|^2)\right) \Psi(\theta, Z) + V(\Psi)\right) \mathcal{D}\Psi(\theta, Z) \quad (42)$$

We then compute this quantity as a function of the connectivity field Γ . Actually, the time scale of neuronal processes is shorter than that of connectivity dynamics, and perturbations first affect the equilibrium of the neuronal system. Subsequently, these perturbations propagate to influence connectivity dynamics.

To model some external perturbation that will propagate in the system, we modify (42) and consider the insertion, at some point Z_i and time θ_0 , the factor $a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2$ inside (42). The partition function is thus replaced by:

$$\int a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2 \exp\left(\frac{1}{2}\Psi^\dagger(\theta, Z, \omega) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - \omega^{-1}(J, \theta, Z, |\Psi|^2)\right) \Psi(\theta, Z) + V(\Psi)\right) \mathcal{D}\Psi(\theta, Z) \quad (43)$$

The squared field:

$$|\Psi(\theta, Z)|^2 = \Psi(\theta, Z) \Psi^\dagger(\theta, Z)$$

measures the density of activity at point Z and for a given time θ . The presence of the additional contribution:

$$|\Psi(Z_i, \theta_0)|^2 = \Psi(Z_i, \theta_0) \Psi^\dagger(Z_i, \theta_0)$$

in the integral corresponds, in the field framework, to the introduction of a punctual perturbation at time θ_0 from the background field equilibrium, as described by the term $\Psi^\dagger(Z_i, \theta_0)$, which is immediately switched off, as transcribed by $\Psi(Z_i, \theta_0)$.

In other words, the presence of $|\Psi(Z_i, \theta_0)|^2$ corresponds to a punctual signal sent from Z_i and time θ_0 that will propagate to the whole thread. The factor $a(Z_i, \theta_0)$ is the amplitude of this signal. To model several sources sending signals at the same moment θ_0 , we introduce a product:

$$\prod_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2$$

We will consider the possibility that the number of active sources may vary over time and consider a probabilistic combination of such sources. Furthermore, we intend to account for the periodic repetition of certain signals over time. Consequently, we will incorporate these elements into the path integral by including the factor:

$$\int \exp\left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2\right) d\theta_0 \quad (44)$$

The term $\sum_i a(Z_i, \theta) |\Psi(Z_i, \theta)|^2$ creates and cancels some stimulations at several points Z_i which deviate the field $\Psi(Z_i, \theta)$ from the static equilibrium. The exponential factor accounts for the possibility of multiple similar stimuli occurring at the same location, as required. The summation over θ_0 guarantees the signal's repetition over a certain time period. Furthermore, to ensure that perturbations only occur at specific points Z_i , we assume that the perturbation is implicitly tensored by:

$$\prod_{Z \neq Z_i} \delta(|\Psi(Z, \theta_0)|^2)$$

This will imply that outside the points Z_i , there is no initial perturbation of the system.

The path integral to consider is thus:

$$\begin{aligned} & \int \exp(-S(\Psi)) \int \exp\left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2\right) d\theta_0 \\ &= \int \exp\left(\frac{1}{2} \Psi^\dagger(\theta, Z) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - \omega^{-1}\right) \Psi(\theta, Z)\right) \int \exp\left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2\right) d\theta_0 \end{aligned} \quad (45)$$

Then, we evaluate the effect of the inserted term (44) on activities by expanding ω^{-1} as a serie of $\Delta\Psi(\theta, Z)$, the fluctuation of the field around the background field $\Psi_0(Z)$ induced by the perturbation. The knowledge of ω^{-1} in the perturbed background state will provide the effective activity, which will be incorporated into the action for the field Γ .

We replicate the sequential steps of the derivation as outlined in ([6]) and tailor them to our specific context. This series expansion subsequently enables us to calculate the transition in the background state induced by the perturbation (44) and derive the interferences phenomena presented in ([9]).

6 Activities $\omega(J, \theta, Z)$ series expansion in field in presence of external sources

This section computes the modification of ω^{-1} with respect to its background value due to an external perturbation. This is achieved by first computing the expansion of ω^{-1} in terms of field, and then by including the effect of the sources. These sources modify the background state at specific points, thereby influencing the activities.

6.1 Formal series expansion

We showed in ([6]) that in first approximation, the effective action for Ψ obtained by replacing:

$$\left| \Psi \left(\theta - \frac{|Z - Z_1|}{c}, Z_1 \right) \right|^2 \rightarrow \mathcal{G}_0(0, Z_1) + \left| \Psi_0(Z_1) + \Psi \left(\theta - \frac{|Z - Z_1|}{c}, Z_1 \right) \right|^2 \quad (46)$$

in (28), where $\mathcal{G}_0(0, Z_1)$ is the free Green function computed in ([6]). In average, $\mathcal{G}_0(0, Z_1)$ is some constant $\frac{1}{\lambda}$. The field $\Psi_0(Z_1)$ is some static background, while $\Psi \left(\theta - \frac{|Z - Z_1|}{c}, Z_1 \right)$ represents the dynamic part of the background field, i.e. a modification above the background state, which may be induced by external sources.

Formula (46) can be written in a more compact form if we define:

$$\bar{\mathcal{G}}_0(0, Z_1) = \mathcal{G}_0(0, Z_1) + |\Psi_0(Z_1)|^2 \quad (47)$$

and write:

$$\left| \Psi \left(\theta - \frac{|Z - Z_1|}{c}, Z_1 \right) \right|^2$$

as a shorthand for:

$$\Psi_0^\dagger(Z_1) \Psi \left(\theta - \frac{|Z - Z_1|}{c}, Z_1 \right) + \Psi_0(Z_1) \Psi^\dagger \left(\theta - \frac{|Z - Z_1|}{c}, Z_1 \right) + \left| \Psi \left(\theta - \frac{|Z - Z_1|}{c}, Z_1 \right) \right|^2$$

As a consequence, formula (46) writes:

$$\left| \Psi \left(\theta - \frac{|Z - Z_1|}{c}, Z_1 \right) \right|^2 \rightarrow \bar{\mathcal{G}}_0(0, Z_1) + \left| \Psi \left(\theta - \frac{|Z - Z_1|}{c}, Z_1 \right) \right|^2 \quad (48)$$

Taking (48) into account, our starting point the equation for (inverse) neurons activities:

$$\begin{aligned} \omega^{-1}(J, \theta, Z) &= G \left(J(\theta) + \frac{\kappa}{N} \int \frac{\omega \left(J, \theta - \frac{|Z - Z_1|}{c}, Z_1, \Psi \right) T \left(Z, \theta, Z_1, \theta - \frac{|Z - Z_1|}{c} \right)}{\omega \left(J, \theta, Z, |\Psi|^2 \right)} \right. \\ &\quad \left. \times \left(\bar{\mathcal{G}}_0(0, Z_1) + \left| \Psi \left(\theta - \frac{|Z - Z_1|}{c}, Z_1 \right) \right|^2 \right) dZ_1 \right) \end{aligned} \quad (49)$$

Then, we replace $T \left(Z, \theta, Z_1, \theta - \frac{|Z - Z_1|}{c} \right)$ in (49) by its average over the connectivity, which is, given (37):

$$\left\langle T \left(Z, \theta, Z_1, \theta - \frac{|Z - Z_1|}{c} \right) \right\rangle = T(Z, Z_1) W \left(\frac{\omega(\theta, Z)}{\omega \left(\theta - \frac{|Z - Z_1|}{c}, Z_1 \right)} \right) \quad (50)$$

where:

$$T(Z, Z_1) = h(Z, Z_1)$$

and:

$$\begin{aligned}
& W \left(\frac{\omega(\theta, Z)}{\omega\left(\theta - \frac{|Z-Z_1|}{c}, Z_1\right)} \right) \\
&= \frac{\lambda\tau h(Z, Z_1) \langle C_{Z, Z_1}(\theta) h_C(\omega(\theta, Z)) |\Psi(\theta, Z)|^2 \rangle}{h_C(\omega(\theta, Z)) |\bar{\Psi}(\theta, Z, Z_1)|^2} \simeq \frac{\lambda\tau h(Z, Z_1) \langle C_{Z, Z_1}(\theta) |\Psi(\theta, Z)|^2 \rangle}{|\bar{\Psi}(\theta, Z, Z_1)|^2}
\end{aligned}$$

Thus (49) writes:

$$\begin{aligned}
\omega^{-1}(J, \theta, Z) &= G \left(J(\theta) + \frac{\kappa}{N} \int T(Z, Z_1) \frac{\omega\left(\theta - \frac{|Z-Z_1|}{c}, Z_1\right) W\left(\frac{\omega(\theta, Z)}{\omega\left(\theta - \frac{|Z-Z_1|}{c}, Z_1\right)}\right)}{\omega(\theta, Z)} \right. \\
&\quad \left. \times \left(\bar{\mathcal{G}}_0(0, Z_1) + \left| \Psi\left(\theta - \frac{|Z-Z_1|}{c}, Z_1\right) \right|^2 \right) dZ_1 \right) \quad (51)
\end{aligned}$$

and we aim at expansion of the solutions of (51) around the static background equilibrium. To do so, we write the series expansion in $|\Psi(\theta^{(j)}, Z_1)|^2$ of $\omega^{-1}(J, \theta, Z)$ around its background state value:

$$\begin{aligned}
\omega^{-1}(J, \theta, Z) &= \omega^{-1}(\theta, Z)_{|\Psi|^2=0} \\
&\quad + \int \sum_{n=1}^{\infty} \left(\frac{\delta^n \omega^{-1}(J, \theta, Z)}{\prod_{i=1}^n \delta |\Psi(\theta - l_i, Z_i)|^2} \right)_{|\Psi|^2=0} \prod_{i=1}^n |\Psi(\theta - l_i, Z_i)|^2 \quad (52)
\end{aligned}$$

and finding $\omega(J, \theta, Z)$ amounts to finding the derivatives:

$$\frac{\delta^n \omega^{-1}(J, \theta, Z)}{\prod_{i=1}^n \delta |\Psi(\theta - l_i, Z_i)|^2}$$

These derivatives are computed by expanding the right-hand side of (51) in $|\Psi(\theta^{(j)}, Z_1)|^2$. We present the computations in the next paragraphs.

6.2 First term of the expansion

The first term in (52), $\omega^{-1}(\theta^{(i)}, Z)_{|\Psi|^2=0}$, is a solution of:

$$\begin{aligned}
& \omega^{-1}(\theta, Z)_{|\Psi|^2=0} \quad (53) \\
&= G \left(J + \frac{\kappa}{N} \int T(Z, Z_1) \frac{\omega_{|\Psi|^2=0}\left(\theta - \frac{|Z-Z_1|}{c}, Z_1\right)}{\omega_{|\Psi|^2=0}(\theta, Z)} W \left(\frac{\omega_{|\Psi|^2=0}(\theta, Z)}{\omega_{|\Psi|^2=0}\left(\theta - \frac{|Z-Z_1|}{c}, Z_1\right)} \right) (\bar{\mathcal{G}}_0(0, Z_1)) dZ_1 \right)
\end{aligned}$$

To uncover the internal dynamics of the system, we will first consider a constant external current $J(\theta) = J$, typically with $J = 0$. However, the findings of this section remain applicable even in the presence of a non-static current $J(\theta)$. The static solution of (53) satisfies:

$$\begin{aligned}
\omega^{-1}(J, Z) &= G \left(J + \frac{\kappa}{N} \int T(Z, Z_1) \frac{\omega(Z_1)}{\omega(Z)} W \left(\frac{\omega(Z)}{\omega(Z_1)} \right) \bar{\mathcal{G}}_0(0, Z_i) dZ_1 \right) \\
&\equiv G[J, \omega, Z]
\end{aligned}$$

We assume this solution to be known, and we chose to expand $\omega(J, \theta, Z)$ in (52) around this solution, the dynamics being determined by the time dependency of $|\Psi(\theta^{(j)}, Z_1)|^2$. We thus set:

$$\omega(\theta, Z)|_{|\Psi|^2=0} = \omega(J, Z)$$

6.3 Computation of the derivatives arising in the series

Appendices 1 and 2 compute the derivatives $\left(\frac{\delta^n \omega^{-1}(J, \theta, Z)}{\prod_{i=1}^n \delta |\Psi(\theta - l_i, Z_i)|^2} \right)_{|\Psi|^2=0}$ in (52).

Defining:

$$\begin{aligned} & \check{T}(\theta, Z, Z_1, \omega, \Psi) \\ = & - \frac{\frac{\kappa}{N} \omega(J, \theta, Z) T(Z, Z_1, \theta) G'[J, \omega, \theta, Z, \Psi]}{1 - \left(\int \frac{\kappa}{N} \omega\left(J, \theta - \frac{|Z-Z'|}{c}, Z'\right) \left(\bar{\mathcal{G}}_0(0, Z') + |\Psi\left(\theta - \frac{|Z-Z'|}{c}, Z'\right)|^2 \right) T(Z, Z', \theta) dZ' \right) G'[J, \omega, \theta, Z, \Psi]} \end{aligned} \quad (54)$$

and the operator with kernel:

$$\begin{aligned} \check{T}\left(\left(Z^{(l-1)}, \theta^{(l-1)}\right), \left(Z^{(l)}, \theta^{(l)}\right)\right) &= \check{T}\left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega_0\right) \\ &\times \delta\left(\left(\theta^{(l)} - \theta^{(l-1)}\right) - \frac{|Z^{(l-1)} - Z^{(l)}|}{c}\right) \end{aligned} \quad (55)$$

appendix 1 shows that:

$$\begin{aligned} & \frac{\delta \omega^{-1}(J, \theta, Z)}{\delta |\Psi(\theta - l_1, Z_1)|^2} \\ = & - \sum_{n=1}^{\infty} \int \frac{\omega^{-1}\left(J, \theta - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c}, Z_1\right)}{\left(\bar{\mathcal{G}}_0(0, Z_1) + |\Psi(\theta - l_1, Z_1)|^2\right)} \\ & \times \prod_{l=1}^n \check{T}\left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega, \Psi\right) \delta\left(l_1 - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c}\right) \prod_{l=1}^{n-1} dZ^{(l)} \end{aligned} \quad (56)$$

and appendix 2 builds on (56) to compute the derivative arising in the series expansion (52):

$$\left(\frac{\delta^n \omega(J, \theta, Z)}{\prod_{i=1}^n \delta |\Psi(\theta - l_i, Z_i)|^2} \right)_{|\Psi|^2=0} \prod_{i=1}^n |\Psi(\theta - l_i, Z_i)|^2 \quad (57)$$

by a graphical representation. We associate the squared field $|\Psi(\theta - l_i, Z_i)|^2$ to each point Z_i and draw m lines for $m = 1, \dots, n$. One of them at least is starting from Z . These lines are composed of an arbitrary number of segments and all the points Z_i are crossed by one line. Each line ends at a point Z_i . The starting points of the lines branch either at Z or at some point of an other line. There are m branching points of valence k including the starting point at Z . Apart from Z , the branching points have valence $3, \dots, n-1$.

To each line i of length L_i , we associate the factor:

$$F(\text{line}_i) = \prod_{l=1}^{L_i} \tilde{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega_0, \Psi \right) \quad (58)$$

$$\times \frac{-\omega_0 \left(J, \theta - \sum_{l=1}^{L_i} \frac{|Z^{(l-1)} - Z^{(l)}|}{c}, Z_i \right)}{\tilde{\mathcal{G}}_0(0, Z_i)}$$

and to each branching point $(X, \theta) = B$ of valence $k + 2$, we associate the factor:

$$F((X, \theta)) = \frac{\delta^k \left(\frac{\frac{\kappa}{N} T(Z, Z^{(l)}) F'[J, \theta, \omega_0, Z^{(l)}] \tilde{\mathcal{G}}_0(0, Z^{(l)})}{\omega_0(J, \theta, Z^{(l)})} \right)}{\delta^k \omega_0(J, \theta, Z^{(l)})} \quad (59)$$

and (57) writes as a series of lines contributions connected by the branching points:

$$\left(\frac{\delta^n \omega(J, \theta, Z)}{\prod_{i=1}^n \delta |\Psi(\theta - l_i, Z_i)|^2} \right)_{|\Psi|^2=0} \prod_{i=1}^n |\Psi(\theta - l_i, Z_i)|^2 \quad (60)$$

$$= \left(\sum_{m=1}^n \sum_{i=1}^m \sum_{(\text{line}_1, \dots, \text{line}_m)} \prod_i F(\text{line}_i) \prod_B F(B) \right) \prod_{i=1}^n |\Psi(\theta - l_i, Z_i)|^2$$

The graphical representation is generic. The integration over the set of lines also accounts for the degenerate case of lines that share some segments.

6.4 Summing the series expansion for $\omega(J, \theta, Z)$ in absence of external source: auxiliary path integral description

Having obtained the successive derivatives of $\omega(J, \theta, Z)$ in (60), we can now sum the corresponding series expansion for $\omega(J, \theta, Z)$. Appendix 2 uses formula (60) to derive a non-local formula for the summation of successive derivatives of $\omega(J, \theta, Z)$ and $\omega^{-1}(J, \theta, Z)$. Actually, equation (60) can be reformulated to calculate the expansion (133) as the sum of graphs for an auxiliary complex field $\Lambda(Z_i, \theta_i)$. The computation organizes the graphs in (60) so that their sum transforms into a summation over graphs drawn between an arbitrary number of branching points, viewed as vertices of arbitrary valence k with an associated factor (59). These vertices are connected by the edges of the graph with associated Green functions $\frac{1}{1 - (1 + |\Psi|^2) \tilde{T}}$ where \tilde{T} is the operator whose kernel is defined in (55). The factor $|\Psi|^2$ is the operator multiplication by $|\Psi(\theta, Z)|^2$ at point (θ, Z) .

Appendix 2 shows that the series expansion for activities has the following auxiliary path integral form:

$$\omega^{-1}(\theta, Z) = \omega_0^{-1}(J, \theta, Z) + \frac{\int \tilde{T} F^\dagger(Z, \theta) \exp \left(-S(F) - \int F(X, \theta) \omega_0^{-1}(J, \theta, Z) |\Psi(J, \theta, Z)|^2 d(X, \theta) \right) \mathcal{D}F}{\int \exp(-S(F)) \mathcal{D}F} \quad (61)$$

where the action for the auxiliary fields F and F^\dagger is:

$$S(F) = \int F(Z, \theta) \left(1 - |\Psi|^2 \tilde{T} \right) F^\dagger(Z, \theta) d(Z, \theta)$$

$$- \int F(Z, \theta) \tilde{T} \left(\theta - \frac{|Z - Z^{(1)}|}{c}, Z, Z^{(1)}, \omega_0 + \tilde{T} F^\dagger \right) F^\dagger \left(Z^{(1)}, \theta - \frac{|Z - Z^{(1)}|}{c} \right) dZ dZ^{(1)} d\theta$$

with:

$$\begin{aligned} & \check{T} \left(\theta - \frac{|Z^{(1)} - Z|}{c}, Z^{(1)}, Z, \omega_0 + \check{T}F^\dagger \right) \\ = & \check{T} \left(\theta - \frac{|Z^{(1)} - Z|}{c}, Z^{(1)}, Z, \omega_0(Z, \theta) + \int \check{T} \left(\theta - \frac{|Z - Z^{(1)}|}{c}, Z^{(1)}, Z, \omega_0 \right) F^\dagger \left(Z^{(1)}, \theta - \frac{|Z - Z^{(1)}|}{c} \right) dZ^{(1)} \right) \end{aligned}$$

6.5 Modification of $\omega(J, \theta, Z)$ due to source terms

Formula (61) was derived without considering the presence of source terms in the path integral (45). In Appendix 3, we show that these terms modify the formula (61) which can be replaced by:

$$\begin{aligned} & \omega^{-1}(\theta, Z) \tag{62} \\ = & \omega_0^{-1}(J, \theta, Z) \\ & + \frac{\int \check{T}F^\dagger(Z, \theta) \exp \left(-S(F) - \int F(X, \theta) \omega_0^{-1}(J, \theta, Z) |\Psi(J, \theta, Z)|^2 d(X, \theta) + \sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} F(Z_i, \theta) \right)}{\int \exp(-S(F)) \mathcal{D}F} \end{aligned}$$

This integral will be computed by a saddle path approximation.

6.6 Saddle path approximation

We then show that the saddle point approximation yields the equations for $F^\dagger(Z, \theta)$ and $F(Z, \theta)$:

$$\begin{aligned} & \left(\left(1 - |\Psi|^2 \check{T} \right) F^\dagger \right) (Z, \theta) - \left(\check{T}_{\omega_0^{-1} + \check{T}F^\dagger} F^\dagger \right) (Z, \theta) - \sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} \delta(Z - Z_i) = 0 \tag{63} \\ & F(Z, \theta) = 0 \end{aligned}$$

In this approximation, equation (62) for ω . becomes:

$$\omega(J, \theta, Z) = \omega_0(J, \theta, Z) + \check{T}F^\dagger(Z, \theta) \tag{64}$$

6.7 Series expansion for activities in the perturbed state

We show in appendix 3 that, in first approximation, we can replace $|\Psi|^2$ with $\frac{1}{\Lambda}$ in (63). When considering perturbations around a static background state, it enables us to rewrite the saddle point equation (63) as follows:

$$\left(\left(1 - \frac{1}{\Lambda} \check{T} \right) F^\dagger \right) (Z) - \left(\check{T}_{\omega_0 + \check{T}F^\dagger} F^\dagger \right) (Z) - \left(\sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} F(Z_i, \theta) \right) = 0$$

and to find a recursive solution for $\check{T}F^\dagger(Z)$ and $\omega(J, \theta, Z)$ by rewriting:

$$\begin{aligned} \check{T}F^\dagger &= \check{T} \frac{1}{\left(1 - \frac{1}{\Lambda} \check{T} - \check{T}_{\omega_0 + \check{T}F^\dagger} \right)} \left(\sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} F(Z_i, \theta) \right) \tag{65} \\ &= \check{T} \frac{1}{\left(1 - \left(1 + \frac{1}{\Lambda} \right) \check{T} - \left(\check{T}_{\omega_0 + \check{T}F^\dagger} - \check{T} \right) \right)} \left(\sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} F(Z_i, \theta) \right) \end{aligned}$$

Gathering (167) and (166), leads to the recursive formula under some approximations:

$$\begin{aligned} \check{T}F^\dagger &\simeq \sum_{n_1, \dots, n_2} \frac{\check{T}}{1 - (1 + \frac{1}{\Lambda})\check{T}} \left[\left(-\frac{\check{T}F^\dagger(Z_1)\check{T}}{\omega_0(Z_1)} \right)^{n_1} \right] \frac{1}{1 - (1 + \frac{1}{\Lambda})\check{T}} \left[\left(-\frac{\check{T}F^\dagger(Z_2)\check{T}}{\omega_0(Z_2)} \right)^{n_2} \right] \\ &\dots \frac{1}{1 - (1 + \frac{1}{\Lambda})\check{T}} \left(-\sum_i a(Z_i, \theta) \frac{\omega_0(J, \theta, Z_i)}{\Lambda^2} \right) \end{aligned}$$

We explain in appendix 3 how this formula builds recursively $\check{T}F^\dagger$. Keeping the lowest order solution of the saddle point in the local approximation $Z' \simeq Z$ leads to:

$$\begin{aligned} \check{T}F^\dagger &= \frac{\check{T}}{(1 - (1 + \frac{1}{\Lambda})\check{T})} \left[\sum_i a(Z_i, \theta) \frac{\omega_0(J, \theta, Z_i)}{\Lambda^2} \right] \\ &\equiv \int K(Z, \theta, Z_i, \theta_i) \left\{ \sum_i a(Z_i, \theta_i) \frac{\omega_0(J, \theta_i, Z_i)}{\Lambda^2} \right\} d\theta_i \end{aligned} \quad (66)$$

so that the correction to the background state activities (62) due to the stimuli become:

$$\omega^{-1}(J, \theta, Z) = \omega_0^{-1}(J, \theta, Z) + \int K(Z, \theta, Z_i, \theta_i) \left\{ \sum_i a(Z_i, \theta_i) \frac{\omega_0(J, \theta_i, Z_i)}{\Lambda^2} \right\} d\theta_i \quad (67)$$

Appendix 3 computes an estimation of the second term in the RHS at the lowest order for oscillating signals $a(Z_i, \theta) \propto a \exp(i\varpi\theta)$. We obtain:

$$\begin{aligned} \omega^{-1}(J, \theta, Z) &= \omega_0^{-1}(J, \theta, Z) + \frac{a \exp(-|Z - Z_0|)}{c\sqrt{(1 + 2\alpha|Z - Z_0|)^2 + (\frac{\varpi}{c})^2}} \\ &\times \exp\left(i\left(\frac{\varpi(|Z - Z_0|)}{c} - \arctan\left(\frac{\varpi}{c(1 + 2\alpha|Z - Z_0|)}\right)\right)\right) \sum_i \exp\left(i\frac{\varpi|Z_i - Z_0|}{c|Z - Z_0|}\right) \end{aligned} \quad (68)$$

and this terms induces interferences. As a consequence, for a large number of points Z_i :

$$\sum_i \exp\left(i\frac{\varpi|Z_i - Z_0|}{c|Z - Z_0|}\right) \simeq 0$$

except for the maxima of interferences with magnitude:

$$\frac{a \exp(-|Z - Z_0|)}{c\sqrt{(1 + 2\alpha|Z - Z_0|)^2 + (\frac{\varpi}{c})^2}}$$

Note that for these maxima and N large:

$$a = \sum_i \exp\left(i\frac{\varpi|Z_i - Z_0|}{c|Z - Z_0|}\right)$$

is proportional to N so that $a \gg 1$.

6.8 Graph expansion for the partition function and modified background activities

Once the activities $\omega(J, \theta, Z)$ are expressed as a function of the field, we can substitute their form in (45) to calculate the background state and equilibrium activity. In appendix 3 the graphs expansion of (45) is derived with $\omega^{-1}(J, \theta, Z)$ given by (67). To achieve this, we expand $|\Psi(\theta, Z_1)|^2$ around a quasi-static background state² $|\Psi_0(\theta, Z_1)|^2$ and $|\Psi(\theta, Z_1)|^2$ around $|\Psi_0(Z_1)|^2$ so that we replace:

$$\Psi(\theta, Z_1) \rightarrow \Psi_0(\theta, Z_1) + \Psi(\theta, Z_1)$$

and:

$$|\Psi(\theta, Z_1)|^2 \rightarrow |\Psi_0(Z_1)|^2 + \Psi_0^\dagger(Z_1)\Psi(\theta, Z_1) + \Psi_0(Z_1)\Psi^\dagger(\theta, Z_1) + |\Psi(\theta, Z_1)|^2$$

We are thus left with the following form for the path integral with external perturbations:

$$\begin{aligned} & \int \exp(-S(\Psi)) \int \exp\left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2\right) d\theta_0 \\ \equiv & \int \exp\left(\left(\frac{1}{2}(\Psi_0^\dagger(\theta, Z) + \Psi^\dagger(\theta, Z)) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - \left(\omega_0^{-1} - \frac{\Omega(\theta, \theta_0, Z)}{\omega_0^2(Z)}\right)\right) (\Psi_0(\theta, Z) + \Psi(\theta, Z))\right)\right) d\theta_0 \end{aligned}$$

with the correction $\Omega(\theta, \theta_0, Z)$ to the activities computed by (66):

$$\Omega(\theta, \theta_0, Z) = - \sum_i \omega_0^2(Z) K(Z, \theta, Z_i, \theta_0) \left\{ a(Z_i, \theta_0) \frac{\omega_0(\theta_0, Z_0)}{\Lambda^2} \right\}$$

The expansion of:

$$\exp \int \left(\Psi_0^\dagger(\theta, Z) + \Psi^\dagger(\theta, Z) \right) \nabla_\theta \left(\frac{\Omega(\theta, \theta_0, Z)}{\omega_0^2(Z)} (\Psi_0(\theta, Z) + \Psi(\theta, Z)) \right) \quad (69)$$

is performed in appendix 3. We specifically focus on the second-order expansion to identify the first order corrections to activities only, although higher orders can be determined using a similar approach. Our derivation shows that at this level of approximation and under the condition that $|\Psi_0(\theta, Z)|^2 \gg \frac{1}{\Lambda}$, formula (69) becomes:

$$\exp\left(A + B - \frac{1}{2}A^2\right)$$

where:

$$A = \frac{1}{\Lambda_1 \Lambda \omega_0^4(Z)} \int \left(\Psi_0^\dagger(\theta, Z) \nabla \left(2 \left(\int^\theta \int (\nabla \Omega(\theta, \theta_0, Z))^2 d\theta_0 \right) - \Lambda_1 \left(\int \Omega^2 d\theta_0 \right) \Psi_0(\theta, Z) \right) \right) dZ$$

and:

$$B = \left(\int \frac{\Psi_0^\dagger(\theta, Z)}{\omega_0^4(Z)} \sqrt{\int (\nabla \Omega(\theta, \theta_0, Z))^2 d\theta_0} \Psi_0(\theta, Z) dZ \right)^2$$

The term $B - \frac{1}{2}A^2$ is a correction to the potential for the background field $\Psi_0(\theta, Z)$. It should thus modify this background, but this can be neglected in first approximation.

²As quoted previously, the series expansion for activities is valid for a non constant background.

The correction to the activities comes from the term A and leads to switch the equilibrium inverse activities:

$$\omega_0^{-1}(Z) \rightarrow \omega_0^{-1}(Z) - \frac{A\omega_0^2(Z)}{\omega_0^2(Z)}$$

or, which is equivalent:

$$\omega_0(Z) \rightarrow \omega_0(Z) + A\omega_0^2(Z)$$

In a developed form, the equilibrium activities are modified by the term:

$$\omega_0(Z) \rightarrow \omega_0(Z) + \frac{1}{\Lambda_1 \Lambda \omega_0^4(Z)} \left(2 \left(\left(\int^\theta \int (\nabla \Omega(\theta, \theta_0, Z))^2 d\theta_0 \right) - \Lambda_1 \left(\int \Omega^2 d\theta_0 \right) \right) \right)$$

for a given background field $\Psi_0(\theta, Z)$.

6.9 Interferences

As explained after formula (68), the corrections $\Omega(\theta, \theta_0, Z)$ can be considered equal to zero outside the points of maximal interferences. At these points $\Omega(\theta, \theta_0, Z) = \tilde{T}F^\dagger$ is proportional to:

$$\bar{\Omega} = \frac{a \exp(-|Z - Z_0|)}{c \sqrt{(1 + 2\alpha |Z - Z_0|)^2 + \left(\frac{\alpha}{c}\right)^2}}$$

and the correction to activities are:

$$\begin{aligned} \omega_0(Z) &\rightarrow \omega_0(Z) + \frac{2 \left(\left(\int^\theta \int (\varpi \bar{\Omega})^2 d\theta_0 \right) - \Lambda_1 \left(\int \bar{\Omega}^2 d\theta_0 \right) \right)}{\Lambda_1 \Lambda \omega_0^2(Z)} \\ &\simeq \omega_0(Z) + \frac{2 \left(\left(T_\theta (\varpi \bar{\Omega})^2 \right) - \Lambda_1 (\bar{\Omega}^2) \right) T_\theta}{\Lambda_1 \Lambda \omega_0^2(Z)} \end{aligned}$$

where T_θ is the duration of the signals at time θ . Note that for $T_\theta \varpi^2 > \Lambda_1$, i.e. for long enough stimulation:

$$\frac{2 \left(\left(T_\theta (\varpi \bar{\Omega})^2 \right) - \Lambda_1 (\bar{\Omega}^2) \right) T_\theta}{\Lambda_1 \Lambda \omega_0^2(Z)}$$

Moreover, since $a \gg 1$, we also have $\bar{\Omega} \gg 1$ so that:

$$\omega_0(Z) + \frac{2 \left(\left(T_\theta (\varpi \bar{\Omega})^2 \right) - \Lambda_1 (\bar{\Omega}^2) \right) T_\theta}{\Lambda_1 \Lambda \omega_0^2(Z)} \gg \omega_0(Z) \quad (70)$$

and the stimulated cells have a much higher activity than others.

7 Implication of modified activities on the emergence of bound states

The modification in the background activity (70) allows to recover the existence of bound states as a consequence of interferences. Actually, given the formula for connectivity functions (37):

$$\begin{aligned} \langle T(Z, Z') \rangle &= \lambda \tau \langle \hat{T}(Z, Z') \rangle \\ &= \frac{\lambda \tau h(Z, Z') \langle C_{Z, Z'}(\theta) h_C(\omega(\theta, Z)) |\Psi(\theta, Z)|^2 \rangle}{C_{Z, Z'}(\theta) |\Psi(\theta, Z)|^2 h_C(\omega(\theta, Z)) + D_{Z, Z'}(\theta) \left| \Psi\left(\theta - \frac{|Z - Z'|}{c}, Z'\right) \right|^2 h_D\left(\omega\left(\theta - \frac{|Z - Z'|}{c}, Z'\right)\right)} \end{aligned}$$

So that:

$$\langle T(Z, Z') \rangle = 0 \quad (71)$$

if Z' belongs to the maxima of interferences, but Z does not. Moreover, if both Z and Z' belong to these maxima:

$$\langle T(Z, Z') \rangle \simeq \langle T(Z', Z) \rangle \quad (72)$$

As a consequence these maxima bind together, in a reciprocal manner. They form a connected set, relatively disconnected from the rest of the thread. The description of these sets has been given in the first article ([9]) of this work.

III Effective formalism for connectivity field

The preceding section has recovered the findings of the first part of this work ([9]). Certain bound states may emerge due to positive interferences in activity. To delve deeper into the dynamics of such states, we establish an effective field formalism for the connectivity field Γ . We also investigate several applications.

8 Effective field formalism approach to connectivity functions transitions

We investigate the modifications in activities, as derived in the preceding section, and analyze their influence on the background field of connectivities. Our focus lies in understanding the dynamic processes involved in transitioning between different background fields, which arises from perturbations in neural activity. To achieve this, we employ an effective action for the connectivity field, which is computed through an expansion of the system's action around a specific background. This expansion captures a situation in which the background field has been perturbed by external influences. Consequently, the actual state of the system at the moment of the transition which is still characterized by the previous background field, differs from the new equilibrium defined by the new background field and may undergo a transition to a new state. We leverage our effective formalism to quantitatively compute these transitions.

It is worth noting that, in this section, we consider the modification in activities as exogenous, primarily resulting from the sources. However, in the third part of this study, we will adopt a more comprehensive perspective, considering that the change in activities is itself contingent on the connectivity field.

8.1 Modified action for $\Gamma(T, \hat{T}, C, D)$

In the perturbed state considered in the previous section, the equilibrium activity has been shifted by an amount of $\delta\omega_0$ and the action of the system can be approximated by:

$$\begin{aligned} & -\frac{1}{2} \int \Psi_0^\dagger(\theta, Z) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - (\omega_0 + \delta\omega_0)^{-1} \right) \Psi_0(\theta, Z) + \int V(\Psi_0(\theta, Z)) + \delta V(\Psi_0(\theta, Z)) \quad (73) \\ & + \sum_{i=1}^4 S_\Gamma^{(i)} \left(\Gamma(T, \hat{T}, \theta, Z, Z', C, D) \right) \end{aligned}$$

where $\Psi_0(\theta, Z)$ is the neuron field equilibrium background state for $\Psi(\theta, Z)$. The deviation in activity and potential have been obtained in the previous section:

$$\delta\omega_0 \propto \frac{2 \left((T(\varpi\bar{\Omega})^2) - \Lambda_1(\bar{\Omega}^2) \right) T_\theta}{\Lambda_1 \Lambda \omega_0^2(Z)} \quad (74)$$

and:

$$\begin{aligned} & \delta V(\Psi_0(\theta, Z)) \quad (75) \\ = & \left(\int \frac{\Psi_0^\dagger(\theta, Z)}{\omega_0^4(Z)} \sqrt{\int (\nabla\Omega(\theta, \theta_0, Z))^2 d\theta_0} \Psi_0(\theta, Z) dZ \right)^2 \\ & - \frac{1}{2} \left(\frac{1}{\Lambda_1 \Lambda \omega_0^4(Z)} \int \left(\Psi_0^\dagger(\theta, Z) \nabla \left(2 \left(\int^\theta \int (\nabla\Omega(\theta, \theta_0, Z))^2 d\theta_0 \right) - \Lambda_1 \left(\int \Omega^2 d\theta_0 \right) \Psi_0(\theta, Z) \right) \right) dZ \right)^2 \end{aligned}$$

The form of the effective action (73) is justified by the distinct time scales governing neuronal activities and connectivities. In first approximation, equilibrium shifts in activities occur before we need to consider the dynamics of connectivities.

The modification in potential and equilibrium activities, as described in Equations (74) and (75) are expected to impact the background state $\Psi_0(\theta, Z)$. Nonetheless, given that the shift is localized at specific points, and considering that this potential characterizes some collective configuration, we can assume, in first approximation, that $\Psi_0(\theta, Z)$ remains unaffected by the signals. Consequently, the new background field for the connectivity field is shifted only at the points where $\Omega(\theta, \theta_0, Z) \neq 0$ and remains unchanged elsewhere.

This change is induced by the activities. Actually, in the perturbed state, after integrating over $\Psi_0(\theta, Z)$ the system is described by an effective action for the connectivity functions $\sum_{i=1}^4 S_\Gamma^{(i)}$ where $|\Psi(Z)|^2$ is set to $|\Psi_0|^2$ and $\omega(J, \theta, Z, |\Psi|^2)$ to $\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2)$ where $|\Psi_0|^2$ and $\omega_0(Z)$ correspond to the initial background state.

For $\frac{1}{\tau_C \alpha_C} \ll 1$ and $\frac{1}{\tau_D \alpha_D} \ll 1$ we can assume that C and D are close to $\frac{1}{2}$ and we write the effective action for $\Gamma(T, \hat{T}, C, D)$ by replacing C and D with their averages:

$$C \rightarrow \langle C(\theta) \rangle = \frac{\alpha_C \omega' \left\langle \left| \Psi \left(\theta - \frac{|Z-Z'|}{c}, Z' \right) \right|^2 \right\rangle}{\frac{1}{\tau_C} + \alpha_C \omega' \left\langle \left| \Psi \left(\theta - \frac{|Z-Z'|}{c}, Z' \right) \right|^2 \right\rangle} \equiv C(\theta) \quad (76)$$

$$D \rightarrow \langle D(\theta) \rangle = \frac{\alpha_D \omega \left\langle |\Psi(\theta, Z)|^2 \right\rangle}{\frac{1}{\tau_D} + \alpha_D \omega \left\langle |\Psi(\theta, Z)|^2 \right\rangle} \equiv D(\theta) \quad (77)$$

so that the effective action becomes:

$$\begin{aligned}
& S \left(\Gamma \left(T, \hat{T}, \theta, Z, Z', C, D \right) \right) \tag{78} \\
&= \Gamma^\dagger \left(T, \hat{T}, \theta, Z, Z', C, D \right) \left[\nabla_T \left(\nabla_T - \left(\frac{(-T + \lambda \hat{T})}{\tau \omega_0(Z) + \Delta \omega_0(Z, |\Psi|^2)} \right) |\Psi(\theta, Z)|^2 \right) \right. \\
&+ \nabla_{\hat{T}} \left(\nabla_{\hat{T}} - \rho \left(\left(h(Z, Z') - \hat{T} \right) C |\Psi_0(Z)|^2 \frac{h_C(\omega_0(Z) + \Delta \omega_0(Z, |\Psi|^2))}{\omega_0(Z) + \Delta \omega_0(Z, |\Psi|^2)} \right. \right. \\
&\left. \left. - \eta H(\delta - T) - D \hat{T} |\Psi_0(Z')|^2 \frac{h_D(\omega_0(Z') + \Delta \omega_0(Z', |\Psi|^2))}{\omega_0(Z) + \Delta \omega_0(Z, |\Psi|^2)} \right) \right) \Gamma \left(T, \hat{T}, \theta, Z, Z', C, D \right)
\end{aligned}$$

The minimization of this effective action yields a background field similar to the one derived using (35), but with modified averages:

$$\begin{aligned}
\langle T(Z, Z') \rangle &= \lambda \tau \langle \hat{T}(Z, Z') \rangle \tag{79} \\
&= \frac{\lambda \tau h(Z, Z') C_{Z, Z'} h_C(\omega_0(Z) + \Delta \omega_0(Z)) |\Psi_0(Z)|^2}{C_{Z, Z'} |\Psi_0(Z)|^2 h_C(\omega_0(Z)) + D_{Z, Z'} |\Psi_0(Z')|^2 h_D(\omega_0(Z'))}
\end{aligned}$$

for (Z, Z') an "a" (active) doublet, and:

$$\begin{aligned}
\langle T(Z, Z') \rangle &= 0 \\
\langle \hat{T}(Z, Z') \rangle &= \frac{h(Z, Z') C_{Z, Z'} h_C(\omega_0(Z) + \Delta \omega_0(Z)) |\Psi_0(Z)|^2 - \eta}{C_{Z, Z'} |\Psi_0(Z)|^2 h_C(\omega_0(Z)) + D_{Z, Z'} |\Psi_0(Z')|^2 h_D(\omega_0(Z'))} < 0 \tag{80}
\end{aligned}$$

for an "u" (unactive) doublet.

Ultimately, remark that the modification:

$$\omega_0(Z) + \Delta \omega_0(Z)$$

may induce some switches in connections in the new background field . Actually, if:

$$\begin{aligned}
h(Z, Z') C_{Z, Z'} h_C(\omega_0(Z)) |\Psi_0(Z)|^2 - \eta &< 0 \\
h(Z, Z') C_{Z, Z'} h_C(\omega_0(Z) + \Delta \omega_0(Z)) |\Psi_0(Z)|^2 - \eta &> 0
\end{aligned}$$

the connection becomes active, i.e. a connection is created between Z and Z' . On the other hand , if:

$$\begin{aligned}
h(Z, Z') C_{Z, Z'} h_C(\omega_0(Z)) |\Psi_0(Z)|^2 - \eta &> 0 \\
h(Z, Z') C_{Z, Z'} h_C(\omega_0(Z) + \Delta \omega_0(Z)) |\Psi_0(Z)|^2 - \eta &< 0
\end{aligned}$$

the connection may be deleted in the new background.

8.2 Expansion around the background state $\Gamma_0 \left(T, \hat{T}, \theta, Z, Z', C, D \right)$ and effective action

Dynamically, the transition between states is achieved by expanding (78) around the new background state, after perturbation. The expansion be will subsequently used to compute the transition

functions. The threshold term $\eta H(\delta - T)$ will be neglected in the sequel to consider only the active connections. The field is expanded as:

$$\begin{aligned}\Gamma(T, \hat{T}, \theta, Z, Z', C, D) &= \Gamma_0(T, \hat{T}, \theta, Z, Z', C, D) + \Delta\Gamma(T, \hat{T}, \theta, Z, Z', C, D) \\ \Gamma^\dagger(T, \hat{T}, \theta, Z, Z', C, D) &= \Gamma_0^\dagger(T, \hat{T}, \theta, Z, Z', C, D) + \Delta\Gamma^\dagger(T, \hat{T}, \theta, Z, Z', C, D)\end{aligned}$$

and the action writes:

$$\begin{aligned}& S\left(\Gamma(T, \hat{T}, \theta, Z, Z', C, D)\right) \\ &= S\left(\Gamma_0(T, \hat{T}, \theta, Z, Z', C, D)\right) + S_e\left(\Delta\Gamma(T, \hat{T}, \theta, Z, Z', C, D)\right)\end{aligned}\tag{81}$$

with:

$$\begin{aligned}& S_e\left(\Delta\Gamma(T, \hat{T}, \theta, Z, Z', C, D)\right) \\ &= \Delta\Gamma^\dagger(T, \hat{T}, \theta, Z, Z', C, D) \left[\nabla_T \left(\nabla_T - \frac{(\lambda(\hat{T} - \langle \hat{T} \rangle) - (T - \langle T \rangle))}{\tau\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2)} |\Psi_0(Z)|^2 \right) \right. \\ & \quad + \nabla_{\hat{T}} \left(\nabla_{\hat{T}} + \rho \left(C \frac{|\Psi_0(Z)|^2 h_C(\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2))}{\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2)} \right) \right. \\ & \quad \left. \left. + D \frac{|\Psi_0(Z')|^2 h_D(\omega_0(Z') + \Delta\omega_0(Z', |\Psi|^2))}{\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2)} \right) (\hat{T} - \langle \hat{T} \rangle) \right] \Delta\Gamma(T, \hat{T}, \theta, Z, Z', C, D)\end{aligned}\tag{82}$$

8.3 Individual transition functions

The effective action (81) enables the dynamic study of transitions between different connectivity states. This is based on the calculation of transition functions for individual states. We write a final state defined by some given values $(T, \hat{T}, \theta, C, D)_f$ between Z and Z' as:

$$\left\langle (T, \hat{T}, \theta, Z, Z', C, D)_f \right\rangle$$

and an initial state with given values $(T, \hat{T}, \theta, C, D)_i$ as:

$$\left\langle (T, \hat{T}, \theta, Z, Z', C, D)_i \right\rangle$$

The computation of transition function between two states, initial and final, is obtained by computing the Green functions:

$$\begin{aligned}& \left\langle (T, \hat{T}, \theta, Z, Z', C, D)_i (T, \hat{T}, \theta, Z, Z', C, D)_f \right\rangle \\ &= \int \Delta\Gamma\left((T, \hat{T}, \theta, Z, Z', C, D)_f\right) \Delta\Gamma^\dagger\left((T, \hat{T}, \theta, Z, Z', C, D)_i\right) \\ & \quad \times \exp\left(-S_e\left(\Delta\Gamma(T, \hat{T}, \theta, Z, Z', C, D)\right) + \alpha \left|\Delta\Gamma(T, \hat{T}, \theta, Z, Z', C, D)\right|^2\right) \mathcal{D}\Delta\Gamma\end{aligned}$$

where α is the inverse average time of transition of the system as we will see below.

Given the form of $S_e \left(\Delta\Gamma \left(T, \hat{T}, \theta, Z, Z', C, D \right) \right)$, the integral is given by:

$$\begin{aligned} & \left\langle \left(T, \hat{T}, \theta, Z, Z', C, D \right)_i \left(T, \hat{T}, \theta, Z, Z', C, D \right)_f \right\rangle \\ &= \left\langle \left(T, \hat{T}, \theta, Z, Z', C, D \right)_i \frac{1}{\alpha + O} \left(T, \hat{T}, \theta, Z, Z', C, D \right)_f \right\rangle \end{aligned}$$

where O is the operator:

$$\begin{aligned} O &= \nabla_T \left(\nabla_T + \frac{(T - \langle T \rangle) - (\lambda (\hat{T} - \langle \hat{T} \rangle))}{\tau\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2)} |\Psi_0(Z)|^2 \right) \\ &+ \nabla_{\hat{T}} \left(\nabla_{\hat{T}} + \rho \left(C \frac{|\Psi_0(Z)|^2 h_C (\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2))}{\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2)} \right. \right. \\ &\left. \left. + D \frac{|\Psi_0(Z')|^2 h_D (\omega_0(Z') + \Delta\omega_0(Z', |\Psi|^2))}{\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2)} \right) \right) (\hat{T} - \langle \hat{T} \rangle) \end{aligned} \quad (83)$$

To interpret the formulas in terms of time transition, we write also:

$$\begin{aligned} & \left\langle \left(T, \hat{T}, \theta, Z, Z', C, D \right)_i \left| \left(T, \hat{T}, \theta, Z, Z', C, D \right)_f \right. \right\rangle \\ &= \left\langle \left(T, \hat{T}, \theta, Z, Z', C, D \right)_i \left| \int_0^\infty \exp(-(\alpha + O)t) dt \left(T, \hat{T}, \theta, Z, Z', C, D \right)_f \right. \right\rangle \\ &= \int_0^\infty \exp(-\alpha t) \left\langle \left(T, \hat{T}, \theta, Z, Z', C, D \right)_i \left| \exp(-(\alpha + O)t) \left(T, \hat{T}, \theta, Z, Z', C, D \right)_f \right. \right\rangle dt \end{aligned}$$

That is $\left\langle \left(T, \hat{T}, \theta, Z, Z', C, D \right)_i \left(T, \hat{T}, \theta, Z, Z', C, D \right)_f \right\rangle$ is the Laplace transform of the time transition between two states defined by the operator O . This justifies the interpretation of α as the inverse of an average transition time. Moreover, this shows that the probabilities of transition of the system are defined by O . Before the Laplace transform, the probability of transition of the system between two states during a time span t is given by:

$$\begin{aligned} & P_t \left(\left(T, \hat{T}, \theta, Z, Z', C, D \right)_i, \left(T, \hat{T}, \theta, Z, Z', C, D \right)_f \right) \\ &= \left\langle \left(T, \hat{T}, \theta, Z, Z', C, D \right)_i \left| \exp(-Ot) \left(T, \hat{T}, \theta, Z, Z', C, D \right)_f \right. \right\rangle \end{aligned} \quad (84)$$

This probability satisfies a differential equation given in appendix 4. We show in this appendix that the transition between $\mathbf{T} - \langle \mathbf{T} \rangle$ and $\mathbf{T}' - \langle \mathbf{T} \rangle$ during a time t , written $G_0(\mathbf{T} - \langle \mathbf{T} \rangle, \mathbf{T}' - \langle \mathbf{T} \rangle, t)$, is given by:

$$\begin{aligned} & G_0(\mathbf{T} - \langle \mathbf{T} \rangle, \mathbf{T}' - \langle \mathbf{T} \rangle, t) \\ &= (2\pi)^{-1} (Det(\sigma(t)))^{-\frac{1}{2}} \\ &\quad \times \exp \left(-((\mathbf{T} - \langle \mathbf{T} \rangle) - M(t)(\mathbf{T}' - \langle \mathbf{T} \rangle)) t \frac{\sigma^{-1}(t)}{2} ((\mathbf{T} - \langle \mathbf{T} \rangle) - M(t)(\mathbf{T}' - \langle \mathbf{T} \rangle)) \right) \end{aligned} \quad (85)$$

where the matrices $M(t)$ and $\sigma(t)$ are defined in appendix 4.

For large t , the transition simplifies and writes:

$$G_0(\mathbf{T} - \langle \mathbf{T} \rangle, \mathbf{T}' - \langle \mathbf{T} \rangle) = (2\pi)^{-1} (Det(\sigma(\infty)))^{-\frac{1}{2}} \times \exp\left(-\frac{1}{2} ((\mathbf{T} - \langle \mathbf{T} \rangle))^t \sigma^{-1}(\infty) ((\mathbf{T} - \langle \mathbf{T} \rangle))\right) \quad (86)$$

with:

$$\sigma(\infty) = \begin{pmatrix} \frac{1}{u} + \frac{s^2}{uv(u+v)} & -\frac{s}{v(u+v)} \\ -\frac{s}{v(u+v)} & \frac{1-e^{-2tv}}{v} \end{pmatrix}$$

8.4 N states transition functions

Formula (85) generalizes directly for the transition of N states:

$$(\mathbf{T}(Z_i, Z_j) - \langle \mathbf{T}(Z_i, Z_j) \rangle) \equiv (\mathbf{T} - \langle \mathbf{T} \rangle)_{ij} \equiv \mathbf{T}_{ij} - \langle \mathbf{T} \rangle_{ij}$$

located at different points $(Z_i, Z_j)_{i,j}$ fluctuating around the background state, without interactions. We have:

$$\begin{aligned} & G_0\left((\mathbf{T} - \langle \mathbf{T} \rangle)_{ij}, ((\mathbf{T}' - \langle \mathbf{T} \rangle)_{ij}), t\right) \\ &= \prod_j G_0\left((\mathbf{T}_{ij} - \langle \mathbf{T}_{ij} \rangle), (\mathbf{T}'_{ij} - \langle \mathbf{T}_{ij} \rangle), t\right) \\ &= (2\pi)^{-N} (Det(\sigma(t)))^{-\frac{N}{2}} \\ & \quad \prod_{ij} \exp\left(-((\mathbf{T}_{ij} - \langle \mathbf{T}_{ij} \rangle) - M(t)(\mathbf{T}'_{ij} - \langle \mathbf{T}_{ij} \rangle))^t \frac{\sigma^{-1}(t)}{2} ((\mathbf{T}_{ij} - \langle \mathbf{T}_{ij} \rangle) - M(t)(\mathbf{T}'_{ij} - \langle \mathbf{T}_{ij} \rangle))\right) \end{aligned}$$

9 Several applications of the effective formalism

We present several applications of the effective formalism and compute the transitions between several activated states, including reactivation, association and sequences of activations. We recover the results presented in ([9]) as consequences of the effective field formalism.

9.1 Transition function approach to the change in connectivity background state

We apply the formalism to the dynamics around a modified background field. Assume that, due to the change in background activities, the $\Psi_0(\theta, Z)$ field action is modified from:

$$-\frac{1}{2} \int \Psi_0^\dagger(\theta, Z) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - (\omega_0)^{-1} \right) \Psi_0(\theta, Z) + \int V(\Psi_0(\theta, Z)) + \delta V(\Psi_0(\theta, Z))$$

to:

$$-\frac{1}{2} \int \Psi_0^\dagger(\theta, Z) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - (\omega_0 + \delta\omega_0)^{-1} \right) \Psi_0(\theta, Z) + \int V(\Psi_0(\theta, Z)) + \delta V(\Psi_0(\theta, Z))$$

where the background activity modification $\delta\omega_0$ is equal to zero except at some given points $(Z_j)_{j \in U}$ where U is a finite set. Consequently, the averages $\langle \mathbf{T}_{ij} \rangle$ are modified only at points Z_{ij} , $j \in U$ or $i \in U$. We define $\bar{U} = (ij, j \in U \text{ or } i \in U)$ and write $\langle \mathbf{T}_{ij} \rangle^{old}$ for the old background state and $\langle \mathbf{T}_{ij} \rangle^{new} = \langle \mathbf{T}_{ij} \rangle^{old} + \Delta \langle \mathbf{T}_{ij} \rangle$ for the new one. We have:

$$\begin{aligned} \Delta \langle \mathbf{T}_{ij} \rangle &\neq 0 \text{ for } ij \in \bar{U} \\ \Delta \langle \mathbf{T}_{ij} \rangle &= 0 \text{ otherwise} \end{aligned}$$

Consider the transition from a state corresponding to the previous background state to a other state We thus set:

$$\mathbf{T}'_{ij} = \langle \mathbf{T}_{ij} \rangle^{old}$$

As explained in the previous paragraph, the transition for the system of points $ij \in \bar{U}$ in the new background state is, up the normalization factor, given by:

$$\begin{aligned} & \prod_{ij} \exp \left(- \left((\mathbf{T}_{ij} - \langle \mathbf{T}_{ij} \rangle^{new}) - M(t) (\mathbf{T}'_{ij} - \langle \mathbf{T}_{ij} \rangle^{new}) \right)^t \frac{\sigma^{-1}(t)}{2} \left((\mathbf{T}_{ij} - \langle \mathbf{T}_{ij} \rangle^{new}) - M(t) (\mathbf{T}'_{ij} - \langle \mathbf{T}_{ij} \rangle^{new}) \right) \right) \\ = & \prod_{ij} \exp \left(- \left((\mathbf{T}_{ij} - \langle \mathbf{T}_{ij} \rangle^{new}) - M(t) \Delta \langle \mathbf{T}_{ij} \rangle \right)^t \frac{\sigma^{-1}(t)}{2} \left((\mathbf{T}_{ij} - \langle \mathbf{T}_{ij} \rangle^{new}) - M(t) \Delta \langle \mathbf{T}_{ij} \rangle \right) \right) \end{aligned}$$

wth:

$$M(t) = \begin{pmatrix} e^{-tu} & s \frac{e^{-tu} - e^{-tv}}{u-v} \\ 0 & e^{-tv} \end{pmatrix}$$

As time t increases, the corrections due to the gap between the initial value and the new background state reduces, so that in average $\mathbf{T}_{ij} \rightarrow \langle \mathbf{T}_{ij} \rangle^{new}$. The higher the values of u , v and s the faster the modification in connectivity functions. Considering that u and s are increasing function of the modified activity, the higher the average activity in the state, the lower the modification in the transition functions. Higher activity levels hinder the system from transitioning to the new equilibrium state.

9.2 Activation and reactivation of states

As before, an additional activation at one point for constant connectivities corresponds to the computation of a transition function. Assume now that, after stimulation for activities $\omega_0 \rightarrow \omega_0(Z) + \delta\omega_0(Z)$, the connectivities have experienced a transition: $\langle \mathbf{T}_{ij} \rangle^{new} = \langle \mathbf{T}_{ij} \rangle^{old} + \Delta \langle \mathbf{T}_{ij} \rangle$. This is equivalent to consider the modified action for the system:

$$\begin{aligned} & -\frac{1}{2} \int \Psi_0^\dagger(\theta, Z) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - (\omega_0 + \delta\omega_0)^{-1} \right) \Psi_0(\theta, Z) + \int V(\Psi_0(\theta, Z)) + \delta V(\Psi_0(\theta, Z)) \quad (87) \\ & + \sum_{i=1}^4 S_\Gamma^{(i)} \end{aligned}$$

Then, switching off the perturbation $\omega_0(Z) + \delta\omega_0(Z) \rightarrow \omega_0(Z)$ relatively quickly, the connectivities remain at their new level $\langle \mathbf{T}_{ij} \rangle^{new}$ for a while. Actually, as shown in appendix 1, the transmission of the perturbation of activities includes a factor:

$$\int \exp \left(-cl - \alpha \left((cl)^2 - |Z - Z_i|^2 \right) \right) \exp \left(i \frac{\varpi(l - |Z - Z_i|)}{c} \right) dl$$

so that after switching of this perturbation at some time t_0 , the correction to the activity decays with a factor $\exp(-ct - t_0)$. Considering again the time scale for the connectivities to be higher than for activities, the state $\langle \mathbf{T}_{ij} \rangle^{old} + \Delta \langle \mathbf{T}_{ij} \rangle$ will decay slowly to $\langle \mathbf{T}_{ij} \rangle^{old}$ over a timespan $T \gg 1$.

Assume now that at some time $t \ll T$, some perturbation raises again:

$$\omega_0(Z_m) \rightarrow \omega_0(Z_m) + \delta\omega_0(Z_m)$$

at some of the interferences maxima. Given (71) and (72) the perturbation will propagate only along the all set of maxima.

As a consequence, in this particular case, the computation of the series expansion for the corrections (65) to the activities simplifies. Actually, replacing the perturbation:

$$\sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} F(Z_i, \theta)$$

by:

$$\delta\omega_0(Z_m) \frac{\omega_0^{-1}(Z_m)}{\Lambda^2} F(Z_i, \theta)$$

representing the activation of one of the maxima, the correction (65) to activities becomes:

$$\begin{aligned} \check{T}F^\dagger &= \check{T} \frac{1}{\left(1 - \frac{1}{\Lambda}\check{T} - \check{T}_{\omega_0 + \check{T}F^\dagger}\right)} \left(\delta\omega_0(Z_m) \frac{\omega_0^{-1}(Z_m)}{\Lambda^2} F(Z_i, \theta) \right) \\ &= \check{T} \frac{1}{\left(1 - \left(1 + \frac{1}{\Lambda}\right)\check{T} - \left(\check{T}_{\omega_0 + \check{T}F^\dagger} - \check{T}\right)\right)} \left(\delta\omega_0(Z_m) \frac{\omega_0^{-1}(Z_m)}{\Lambda^2} F(Z_i, \theta) \right) \end{aligned} \quad (88)$$

The series expansion in \check{T} has to be performed over paths that connect the maxima since the operator \check{T} is nul outside these paths. Due to the exponential term in connectivity functions, in first approximation:

$$\delta\omega_0(Z) \simeq \check{T}(Z, Z_m)$$

if Z is an interference maximum, and:

$$\delta\omega_0(Z) \simeq 0$$

otherwise. As a consequence, the activation of one of these maxima reactivates the whole set. In turn, doing so and if the stimulation duration is long enough, the connectivity functions are reactivated towards $\langle \mathbf{T}_{ij} \rangle^{old} + \Delta \langle \mathbf{T}_{ij} \rangle$.

9.3 Distant activation

Consider the sequence of distant signals as in the first part:

$$\begin{aligned} \{\omega_0, T_0\} &\rightarrow \left\{ T \left(Z_M^{(\varepsilon_1)}, Z_M^{(\varepsilon_2)} \right), \omega_M \right\} \rightarrow \left\{ T \left(Z_M^{(\varepsilon_1)}, Z_M^{(\varepsilon_2)} \right), \omega_0 \right\} \\ &\rightarrow \left\{ T \left(Z_M^{(\varepsilon_1)}, Z_M^{(\varepsilon_2)} \right), \omega_0 \right\} + \left\{ T \left(Z_M'^{(\varepsilon_1)}, Z_M'^{(\varepsilon_2)} \right), \omega_M' \right\} \\ &\rightarrow \left\{ T \left(Z_M^{(\varepsilon_1)}, Z_M^{(\varepsilon_2)} \right), \omega_0 \right\} + \left\{ T \left(Z_M'^{(\varepsilon_1)}, Z_M'^{(\varepsilon_2)} \right), \omega_0 \right\} \end{aligned}$$

Starting from the equilibrium state, the sequence describes the subsequent activations of collective states due to some perturbations. This perturbation initially binds a set $\left(Z_M^{(\varepsilon_1)}, Z_M^{(\varepsilon_2)} \right)$ with high activity ω_M and high connectivity $T \left(Z_M^{(\varepsilon_1)}, Z_M^{(\varepsilon_2)} \right)$. Then, the activity dampens and returns to some equilibrium ω_0 . This new state may itself induce a transition involving another connected element $\left\{ T \left(Z_M'^{(\varepsilon_1)}, Z_M'^{(\varepsilon_2)} \right), \omega_0 \right\}$.

The transition can be described by considering the transitions computed by the path integrals

involving (45) and the action for the connectivity field:

$$\begin{aligned}
& \left\langle \prod_{Z,Z'} (T, \hat{T}, \theta, Z, Z', C, D) \right\rangle_f \left| \left(\exp \left(- \sum_{i=1}^4 S_{\Gamma}^{(i)} \left(\Gamma \left(T, \hat{T}, \theta, Z, Z', C, D \right) \right) \right) \right. \right. \\
& \times \int \mathcal{D}\Psi(\theta, Z) \exp \left(\frac{1}{2} \Psi^\dagger(\theta, Z) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - \omega^{-1} \right) \Psi(\theta, Z) - \int V(\Psi_0(\theta, Z)) \right) \\
& \times \int_{\theta_0^{(2)}}^{\theta_0^{(3)}} \exp \left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2 \right) d\theta_0 \\
& \left. \int_{\theta_0^{(1)}}^{\theta_0^{(2)}} \exp \left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2 \right) d\theta_0 \right) \left| \prod_{Z,Z'} (T, \hat{T}, \theta, Z, Z', C, D) \right\rangle_i \Bigg\rangle \quad (89)
\end{aligned}$$

where the product $\prod_{Z,Z'}$ is over points for which we study the transitions between different states $\left| (T, \hat{T}, \theta, Z, Z', C, D) \right\rangle_i$ and $\left| (T, \hat{T}, \theta, Z, Z', C, D) \right\rangle_f$. This transition is defined as a Green function for the field $\Gamma(T, \hat{T}, \theta, Z, Z', C, D)$:

$$\begin{aligned}
& \int D\Gamma(T, \hat{T}, \theta, Z, Z', C, D) \mathcal{D}\Psi(\theta, Z) \left(\prod_{Z,Z'} \Gamma \left((T, \hat{T}, \theta, Z, Z', C, D) \right)_f \right) \\
& \times \left(\prod_{Z,Z'} \Gamma^\dagger \left((T, \hat{T}, \theta, Z, Z', C, D) \right)_i \right) \\
& \times \exp \left(- \sum_{i=1}^4 S_{\Gamma}^{(i)} \left(\Gamma \left(T, \hat{T}, \theta, Z, Z', C, D \right) \right) + \frac{1}{2} \Psi^\dagger(\theta, Z) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - \omega^{-1} \right) \Psi(\theta, Z) - \int V(\Psi_0(\theta, Z)) \right) \\
& \times \int_{\theta_0^{(2)}}^{\theta_0^{(3)}} \exp \left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2 \right) d\theta_0 \int_{\theta_0^{(1)}}^{\theta_0^{(2)}} \exp \left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2 \right) d\theta_0
\end{aligned} \quad (90)$$

with $\theta_0^{(2)} \gg \theta_0^{(1)}$. The insertion of the exponential terms corresponds, as in (45), to two different perturbations distant in time, so that their effect are disconnected, due to the exponential decay of their persistence.

Expression (90) thus computes the transition function between two states where two distant perturbation have been inserted. Given that these perturbations are independent, the path integral can be computed by inserting a complete basis of states as border conditions. As a consequence (89) writes:

$$\begin{aligned}
& \left\langle \prod_{Z,Z'} (T, \hat{T}, \theta, Z, Z', C, D) \right\rangle_f \left| \exp \left(- \sum_{i=1}^4 S_{\Gamma}^{(i)} \left(\Gamma \left(T, \hat{T}, \theta, Z, Z', C, D \right) \right) + S(\Psi(\theta, Z)) \right) \right. \\
& \times \int_{\theta_0^{(2)}}^{\theta_0^{(3)}} \exp \left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2 \right) d\theta_0 \left| \prod_Z (Z, \theta) \right\rangle \left| \prod_{Z,Z'} (T, \hat{T}, \theta, Z, Z', C, D) \right\rangle \\
& \times \left\langle \prod_{Z,Z'} (T, \hat{T}, \theta, Z, Z', C, D) \right\rangle_i \left| \left\langle \prod_Z (Z, \theta) \right| \exp \left(- \sum_{i=1}^4 S_{\Gamma}^{(i)} \left(\Gamma \left(T, \hat{T}, \theta, Z, Z', C, D \right) \right) + S(\Psi(\theta, Z)) \right) \right. \\
& \left. \times \int_{\theta_0^{(1)}}^{\theta_0^{(2)}} \exp \left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2 \right) d\theta_0 \left| \prod_{Z,Z'} (T, \hat{T}, \theta, Z, Z', C, D) \right\rangle_i \right. \Bigg\rangle \quad (91)
\end{aligned}$$

The introduction of the complete set:

$$\left| \prod_Z (Z, \theta) \right\rangle \left| \prod_{Z, Z'} (T, \hat{T}, \theta, Z, Z', C, D) \right\rangle \left\langle \prod_{Z, Z'} (T, \hat{T}, \theta, Z, Z', C, D) \right| \left\langle \prod_Z (Z, \theta) \right|$$

in the amplitude(91) represents the projection on all possible states. It includes the possibility of multiple activations for $(T, \hat{T}, \theta, Z, Z', C, D)$ and (Z, θ) , modeling various potential types of connections at the same point. Technically this multiple states at the same points correspond to tensor products of states $|(Z, \theta)\rangle$ or $|\prod_{Z, Z'} (T, \hat{T}, \theta, Z, Z', C, D)\rangle$.

The sum over the inserted states $|\prod_Z (Z, \theta)\rangle$ can be carried out, yielding two factors of the type (45). The transition at stake becomes:

$$\begin{aligned} & \left\langle \prod_{Z, Z'} (T, \hat{T}, \theta, Z, Z', C, D) \right\rangle_f \left| \exp \left(- \sum_{i=1}^4 S_{\Gamma}^{(i)} \left(\Gamma \left(T, \hat{T}, \theta, Z, Z', C, D \right) \right) + S \left(\Psi \left(\theta, Z \right) \right) \right) \right. \quad (92) \\ & \int_{\theta_0^{(2)}}^{\theta_0^{(3)}} \exp \left(\sum_i a \left(Z_i, \theta_0 \right) |\Psi \left(Z_i, \theta_0 \right)|^2 \right) d\theta_0 \left| \prod_{Z, Z'} (T, \hat{T}, \theta, Z, Z', C, D) \right\rangle \\ & \times \left\langle \prod_{Z, Z'} (T, \hat{T}, \theta, Z, Z', C, D) \right\rangle \left| \exp \left(- \sum_{i=1}^4 S_{\Gamma}^{(i)} \left(\Gamma \left(T, \hat{T}, \theta, Z, Z', C, D \right) \right) + S \left(\Psi \left(\theta, Z \right) \right) \right) \right. \\ & \times \int_{\theta_0^{(1)}}^{\theta_0^{(2)}} \exp \left(\sum_i a \left(Z_i, \theta_0 \right) |\Psi \left(Z_i, \theta_0 \right)|^2 \right) d\theta_0 \left| \prod_{Z, Z'} (T, \hat{T}, \theta, Z, Z', C, D)_i \right\rangle \end{aligned}$$

and each transition can be computed independently. To describe the successive activations, we assume that the initial state:

$$\left| \prod_{Z, Z'} (T, \hat{T}, \theta, Z, Z', C, D)_i \right\rangle$$

is the background state $|\langle \mathbf{T}_{ij} \rangle^{old}\rangle$ previously described, corresponding to a product of background states at several points. We have observed that, given the insertion of a term similar to (45), the state $|\langle \mathbf{T}_{ij} \rangle^{old}\rangle$ undergoes a transition, with the highest probability, towards $|\langle \mathbf{T}_{ij} \rangle^{old} + \Delta \langle \mathbf{T}_{ij} \rangle\rangle$. The insertion of the complete set:

$$\left| \prod_{Z, Z'} (T, \hat{T}, \theta, Z, Z', C, D) \right\rangle \left\langle \prod_{Z, Z'} (T, \hat{T}, \theta, Z, Z', C, D) \right|$$

thus yields a projection:

$$\left| \langle \mathbf{T}_{ij} \rangle^{old} + \Delta \langle \mathbf{T}_{ij} \rangle \right\rangle \left\langle \langle \mathbf{T}_{ij} \rangle^{old} + \Delta \langle \mathbf{T}_{ij} \rangle \right|$$

and the transition reduces to:

$$\begin{aligned} & \left\langle \prod_{Z, Z'} (T, \hat{T}, \theta, Z, Z', C, D) \right\rangle_f \left| \exp \left(- \sum_{i=1}^4 S_{\Gamma}^{(i)} \left(\Gamma \left(T, \hat{T}, \theta, Z, Z', C, D \right) \right) + S \left(\Psi \left(\theta, Z \right) \right) \right) \right. \quad (93) \\ & \int_{\theta_0^{(2)}}^{\theta_0^{(3)}} \exp \left(\sum_i a \left(Z_i, \theta_0 \right) |\Psi \left(Z_i, \theta_0 \right)|^2 \right) d\theta_0 \left| \langle \mathbf{T}_{ij} \rangle^{old} + \Delta \langle \mathbf{T}_{ij} \rangle \right\rangle \left\langle \langle \mathbf{T}_{ij} \rangle^{old} + \Delta \langle \mathbf{T}_{ij} \rangle \right| \\ & \exp \left(- \sum_{i=1}^4 S_{\Gamma}^{(i)} \left(\Gamma \left(T, \hat{T}, \theta, Z, Z', C, D \right) \right) + S \left(\Psi \left(\theta, Z \right) \right) \right) \int_{\theta_0^{(1)}}^{\theta_0^{(2)}} \exp \left(\sum_i a \left(Z_i, \theta_0 \right) |\Psi \left(Z_i, \theta_0 \right)|^2 \right) d\theta_0 \left| \langle \mathbf{T}_{ij} \rangle^{old} \right\rangle \end{aligned}$$

The second insertion in (93) shifts the state $|\langle \mathbf{T}_{ij} \rangle^{old}\rangle$ with highest probability to some:

$$|\langle \mathbf{T}_{ij} \rangle^{old} + \Delta \langle \mathbf{T}_{ij} \rangle + \Delta' \langle \mathbf{T}_{ij} \rangle\rangle$$

with an amplitude:

$$\begin{aligned} & \left\langle \langle \mathbf{T}_{ij} \rangle^{old} + \Delta \langle \mathbf{T}_{ij} \rangle + \Delta' \langle \mathbf{T}_{ij} \rangle \left| \exp \left(- \sum_{i=1}^4 S_{\Gamma}^{(i)} \left(\Gamma \left(T, \hat{T}, \theta, Z, Z', C, D \right) \right) + S \left(\Psi \left(\theta, Z \right) \right) \right) \right. \\ & \int_{\theta_0^{(2)}}^{\theta_0^{(3)}} \exp \left(\sum_i a \left(Z_i, \theta_0 \right) |\Psi \left(Z_i, \theta_0 \right)|^2 \right) d\theta_0 \left| \langle \mathbf{T}_{ij} \rangle^{old} + \Delta \langle \mathbf{T}_{ij} \rangle \right\rangle \left\langle \langle \mathbf{T}_{ij} \rangle^{old} + \Delta \langle \mathbf{T}_{ij} \rangle \left| \right. \\ & \left. \exp \left(- \sum_{i=1}^4 S_{\Gamma}^{(i)} \left(\Gamma \left(T, \hat{T}, \theta, Z, Z', C, D \right) \right) + S \left(\Psi \left(\theta, Z \right) \right) \right) \int_{\theta_0^{(1)}}^{\theta_0^{(2)}} \exp \left(\sum_i a \left(Z_i, \theta_0 \right) |\Psi \left(Z_i, \theta_0 \right)|^2 \right) d\theta_0 \right| \langle \mathbf{T}_{ij} \rangle^{old} \rangle \end{aligned} \quad (94)$$

This computation describes formally the qualitative discussion about transitions presented in ([9]). The distant activation provides two independent structures of connections that can be reactivated independently as described by the sequence:

$$\rightarrow \left\{ T \left(Z_M^{(\varepsilon_1)}, Z_M^{(\varepsilon_2)} \right), \omega_0 \right\} + \left\{ T \left(Z_M'^{(\varepsilon_1)}, Z_M'^{(\varepsilon_2)} \right), \omega'_M \right\}$$

9.4 Subsequent activation

For a sequence of subsequent activations, as described in ([9]), we consider the scheme:

$$\begin{aligned} \{\omega_0, T_0\} & \rightarrow \left\{ T \left(Z_M^{(\varepsilon_1)}, Z_M^{(\varepsilon_2)} \right), \omega_M \right\} \\ & \rightarrow \left\{ T \left(Z_M^{(\varepsilon_1)}, Z_M^{(\varepsilon_2)} \right), \omega_M, T \left(Z_M'^{(\varepsilon_1)}, Z_M'^{(\varepsilon_2)} \right), \omega'_M, T \left(Z_M^{(\varepsilon_1)}, Z_M'^{(\varepsilon_2)} \right), T \left(Z_M'^{(\varepsilon_2)}, Z_M^{(\varepsilon_1)} \right) \right\} \\ & \rightarrow \left\{ T \left(Z_M^{(\varepsilon_1)}, Z_M^{(\varepsilon_2)} \right), \omega_0, T \left(Z_M'^{(\varepsilon_1)}, Z_M'^{(\varepsilon_2)} \right), \omega_0, T \left(Z_M^{(\varepsilon_1)}, Z_M'^{(\varepsilon_2)} \right), T \left(Z_M'^{(\varepsilon_2)}, Z_M^{(\varepsilon_1)} \right) \right\} \end{aligned} \quad (95)$$

Here the transition including the second structure is directly caused by the action of the first structure before its activity dampens.

Technically, the scheme of transitions (??) implies that the insertion of perturbations are no longer independent and the transition in (89) cannot be shared as a product. It rather writes:

$$\begin{aligned} & \left\langle \prod_{Z, Z'} \left(T, \hat{T}, \theta, Z, Z', C, D \right) \right|_f \left(\exp \left(- \sum_{i=1}^4 S_{\Gamma}^{(i)} \left(\Gamma \left(T, \hat{T}, \theta, Z, Z', C, D \right) \right) \right) \right) \\ & \times \int \mathcal{D}\Psi \left(\theta, Z \right) \exp \left(\frac{1}{2} \Psi^\dagger \left(\theta, Z \right) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - \omega^{-1} \right) \Psi \left(\theta, Z \right) - \int V \left(\Psi_0 \left(\theta, Z \right) \right) \right) \\ & \times \int_{\theta_0^{(2)}}^{\theta_0^{(3)}} \exp \left(\sum_i a \left(Z_i, \theta_0 \right) |\Psi \left(Z_i, \theta_0 \right)|^2 \right) d\theta_0 \int_{\theta_0^{(1)}}^{\theta_0^{(2)}} \exp \left(\sum_i a \left(Z_i, \theta_0 \right) |\Psi \left(Z_i, \theta_0 \right)|^2 \right) d\theta_0 \left| \langle \mathbf{T}_{ij} \rangle^{old} \right\rangle \end{aligned} \quad (96)$$

and projects the final set to some state $|\langle \mathbf{T}_{ij} \rangle^{old} + \{\Delta \langle \mathbf{T}_{ij} \rangle + \Delta' \langle \mathbf{T}_{ij} \rangle\}\rangle$. The additional activations $\{\Delta \langle \mathbf{T}_{ij} \rangle + \Delta' \langle \mathbf{T}_{ij} \rangle\}$ differ from the set $\Delta \langle \mathbf{T}_{ij} \rangle + \Delta' \langle \mathbf{T}_{ij} \rangle$ obtained in the previous paragraph. Actually, the set $\Delta \langle \mathbf{T}_{ij} \rangle + \Delta' \langle \mathbf{T}_{ij} \rangle$ describes a priori disconnected structures that can be activated independently, while $\{\Delta \langle \mathbf{T}_{ij} \rangle + \Delta' \langle \mathbf{T}_{ij} \rangle\}$ encompasses connections between elements of $\Delta \langle \mathbf{T}_{ij} \rangle$ and $\Delta' \langle \mathbf{T}_{ij} \rangle$. This implies that reactivation of one set $\Delta \langle \mathbf{T}_{ij} \rangle$ or $\Delta' \langle \mathbf{T}_{ij} \rangle$ will induce the reactivation of the other one.

10 Conclusion

We have shown how the effective field formalism for connectivity enables the derivation of results pertaining to the activation, association, reactivation... of states composed of interconnected sets of cells. These states originate from the deformation of the background fields induced by external sources. In the subsequent article of this series, we will explore the internal dynamics between such states as an outcome of the formalism. Ultimately, in Part IV, we will expand our formalism into a field theory for groups of interconnected states.

References

- [1] Kleinert H. Gauge Fields in Condensed Matter Vol. I , Superflow and Vortex Lines, Disorder Fields, Phase Transitions, Vol. II, Stresses and Defects, Differential Geometry, Crystal Melting. World Scientific, Singapore (1989).
- [2] Gosselin P, Lotz A Wambst M. A Path Integral Approach to Interacting Economic Systems with Multiple Heterogeneous Agents. <https://hal.archives-ouvertes.fr/hal-01549586v2> (2017).
- [3] Gosselin P, Lotz A Wambst M. A path integral approach to business cycle models with large number of agents. *Journal of Economic Interaction and Coordination* 15 (2020), 899-942.
- [4] Gosselin P, Lotz A Wambst M. A statistical field approach to capital accumulation. *Journal of Economic Interaction and Coordination* 16, pages 817–908 (2021).
- [5] Gosselin P, Lotz A Wambst M. A Statistical Field Perspective on Capital Allocation and Accumulation. Preprint <https://hal.archives-ouvertes.fr/hal-03659624> (2022).
- [6] Gosselin P, Lotz A Wambst M. Statistical Field Theory and Networks of Spiking Neurons, arxiv : 2009.14744
- [7] Montbrió E, Pazó D and Roxin A. Macroscopic description for networks of spiking neurons
- [8] Isbister J B, Eguchi A, Ahmad N, Galeazzi J M, Buckley M J and Stringer S. A new approach to solve the feature-binding problem in primate vision. *Interface Focus*, 820180021 (2018).
- [9] Gosselin P, Lotz A. Statistical Field Theory and strctrs Dynamics I

Appendix 1 Activities $\omega(J, \theta, Z)$ as functional of the field.

To obtain the activity $\omega(J, \theta, Z)$ as a fld series expansion, we start with the recursive relation defining $\omega^{-1}(J, \theta, Z)$. We then proceed in several steps. In this appendix we compute the first derivative in 1.1. They are estimated through fourier integrals in 1.2. Then we will obtain the whole series of derivatives by iterating this result in 2.

1.1 Computation of the first order derivatives in (52)

1.1.1 General formula

In the sequel, to simplify the notations:

$$\left| \Psi \left(\theta - \frac{|Z - Z_1|}{c}, Z_1 \right) \right|^2$$

stands for:

$$\bar{\mathcal{G}}_0(0, Z_1) + \left| \Psi \left(\theta - \frac{|Z - Z_1|}{c}, Z_1 \right) \right|^2$$

where³:

$$\bar{\mathcal{G}}_0(0, Z_1) = \mathcal{G}_0(0, Z_1) + |\Psi_0(Z_1)|^2$$

Using the recursive definition of $\omega^{-1}(J, \theta, Z)$:

$$\omega^{-1}(J, \theta, Z) = G \left(J(\theta, Z) + \int \frac{\kappa}{N} \frac{\omega \left(J, \theta - \frac{|Z - Z_1|}{c}, Z_1 \right)}{\omega(J, \theta, Z)} \left| \Psi \left(\theta - \frac{|Z - Z_1|}{c}, Z_1 \right) \right|^2 T(Z, Z_1, \theta) dZ_1 \right) \quad (97)$$

we first compute $\frac{\delta \omega^{-1}(J, \theta, Z)}{\delta |\Psi(\theta - l_1, Z_1)|^2}$:

$$\begin{aligned} & \frac{\delta \omega^{-1}(J, \theta, Z)}{\delta |\Psi(\theta - l_1, Z_1)|^2} \\ &= \frac{\delta G \left(J(\theta, Z) + \int \frac{\kappa}{N} \frac{\omega \left(J, \theta - \frac{|Z - Z'|}{c}, Z' \right)}{\omega(J, \theta, Z)} \left| \Psi \left(\theta - \frac{|Z - Z'|}{c}, Z' \right) \right|^2 T(Z, Z', \theta) dZ' \right)}{\delta |\Psi(\theta - l_1, Z_1)|^2} \end{aligned} \quad (98)$$

³See the discussion after (46)

Expanding the right hand side and regrouping $\frac{\delta\omega^{-1}(J,\theta,Z)}{\delta|\Psi(\theta-l_1,Z_1)|^2}$ on the left yields:

$$\begin{aligned}
& \frac{\delta\omega^{-1}(J,\theta,Z)}{\delta|\Psi(\theta-l_1,Z_1)|^2} \\
&= \frac{\frac{1}{\omega(J,\theta,Z)} \frac{\kappa}{N} T(Z,Z_1,\theta) G'[J,\omega,\theta,Z,\Psi] \omega\left(J,\theta-\frac{|Z-Z'|}{c},Z'\right) \delta\left(l_1-\frac{|Z-Z_1|}{c}\right)}{1-\left(\int \frac{\kappa}{N} \omega\left(J,\theta-\frac{|Z-Z'|}{c},Z'\right) T(Z,Z',\theta) \left|\Psi\left(\theta-\frac{|Z-Z'|}{c},Z'\right)\right|^2 dZ'\right) G'[J,\omega,\theta,Z,\Psi]} \\
&+ \frac{\frac{1}{\omega(J,\theta,Z)} \int \frac{\kappa}{N} \frac{\delta\omega\left(J,\theta-\frac{|Z-Z'|}{c},Z'\right)}{\delta|\Psi(\theta-l_1,Z_1)|^2} T(Z,Z',\theta) \left|\Psi\left(\theta-\frac{|Z-Z'|}{c},Z'\right)\right|^2 dZ' G'[J,\omega,\theta,Z,\Psi]}{1-\left(\int \frac{\kappa}{N} \omega\left(J,\theta-\frac{|Z-Z'|}{c},Z'\right) T(Z,Z',\theta) \left|\Psi\left(\theta-\frac{|Z-Z'|}{c},Z'\right)\right|^2 dZ'\right) G'[J,\omega,\theta,Z,\Psi]} \\
&+ \frac{\frac{1}{\omega(J,\theta,Z)} \int \frac{\kappa}{N} \omega\left(J,\theta-\frac{|Z-Z'|}{c},Z'\right) \frac{\partial T(Z,Z',\theta)}{\partial|\Psi(\theta-l_1,Z_1)|^2} \left|\Psi\left(\theta-\frac{|Z-Z'|}{c},Z'\right)\right|^2 dZ' G'[J,\omega,\theta,Z,\Psi]}{1-\left(\int \frac{\kappa}{N} \omega\left(J,\theta-\frac{|Z-Z'|}{c},Z'\right) T(Z,Z',\theta) \left|\Psi\left(\theta-\frac{|Z-Z'|}{c},Z'\right)\right|^2 dZ'\right) G'[J,\omega,\theta,Z,\Psi]} \quad (99)
\end{aligned}$$

neglecting $\frac{\partial T(Z,Z',\theta)}{\partial\omega\left(J,\theta-\frac{|Z-Z'|}{c},Z'\right)}$ in first approxmtn, this leads to:

$$\begin{aligned}
\frac{\delta\omega^{-1}(J,\theta,Z)}{\delta|\Psi(\theta-l_1,Z_1)|^2} &= \omega(J,\theta-l_1,Z_1) \tilde{T}_1(\theta,Z,Z_1,\omega,\Psi) \delta\left(l_1-\frac{|Z-Z_1|}{c}\right) \\
&+ \int \frac{\delta\omega\left(J,\theta-\frac{|Z-Z'|}{c},Z'\right)}{\delta|\Psi(\theta-l_1,Z_1)|^2} \left|\Psi\left(\theta-\frac{|Z-Z'|}{c},Z'\right)\right|^2 \tilde{T}_1(\theta,Z,Z',\omega,\Psi) dZ' \quad (100)
\end{aligned}$$

where we defined:

$$\begin{aligned}
\tilde{T}_1(\theta,Z,Z_1,\omega,\Psi) &= \frac{1}{\omega(J,\theta,Z)} \\
&\times \frac{\frac{\kappa}{N} T(Z,Z_1,\theta) G'[J,\omega,\theta,Z,\Psi] \delta\left(l_1-\frac{|Z-Z_1|}{c}\right)}{1-\left(\int \frac{\kappa}{N} \omega\left(J,\theta-\frac{|Z-Z'|}{c},Z'\right) T(Z,Z',\theta) \left|\Psi\left(\theta-\frac{|Z-Z'|}{c},Z'\right)\right|^2 dZ'\right) G'[J,\omega,\theta,Z,\Psi]} \quad (101)
\end{aligned}$$

Equation (100) shows that we also need $\frac{\delta\omega(J,\theta,Z)}{\delta|\Psi(\theta-l_1,Z_1)|^2}$ to compute $\frac{\delta\omega^{-1}(J,\theta,Z)}{\delta|\Psi(\theta-l_1,Z_1)|^2}$. This is obtained by:

$$\begin{aligned}
\frac{\delta\omega(J,\theta,Z)}{\delta|\Psi(\theta-l_1,Z_1)|^2} &= \frac{\delta F\left(J(\theta,Z) + \int \frac{\kappa}{N} \bar{W}\left(\frac{\omega\left(J,\theta-\frac{|Z-Z'|}{c},Z'\right)}{\omega(J,\theta,Z)}\right) \left|\Psi\left(\theta-\frac{|Z-Z'|}{c},Z'\right)\right|^2 T(Z,Z') dZ'\right)}{\delta|\Psi(\theta-l_1,Z_1)|^2} \\
&= \omega(J,\theta-l_1,Z_1) \tilde{T}(\theta,Z,Z_1,\omega,\Psi) \delta\left(l_1-\frac{|Z-Z_1|}{c}\right) \\
&+ \int \frac{\delta\omega\left(J,\theta-\frac{|Z-Z'|}{c},Z'\right)}{\delta|\Psi(\theta-l_1,Z_1)|^2} \left|\Psi\left(\theta-\frac{|Z-Z'|}{c},Z'\right)\right|^2 \tilde{T}(\theta,Z,Z',\omega,\Psi) dZ' \quad (102)
\end{aligned}$$

with:

$$\begin{aligned} & \tilde{T}(\theta, Z, Z_1, \omega, \Psi) \tag{103} \\ &= \frac{\frac{\kappa}{N} \omega(J, \theta, Z) T(Z, Z_1) \bar{W}' \left(\frac{\omega(J, \theta - \frac{|Z-Z_1|}{c}, Z_1)}{\omega(J, \theta, Z)} \right) F'[J, \omega, \theta, Z, \Psi]}{\omega^2(J, \theta, Z) + F'[J, \omega, \theta, Z, \Psi] \int \frac{\kappa \omega \left(J, \theta - \frac{|Z-Z'|}{c}, Z' \right)}{N} \bar{W}' \left(\frac{\omega \left(J, \theta - \frac{|Z-Z'|}{c}, Z' \right)}{\omega(J, \theta, Z)} \right) \left| \Psi \left(\theta - \frac{|Z-Z'|}{c}, Z' \right) \right|^2 T(Z, Z', \theta) dZ'} \end{aligned}$$

Equation (102) and (103) define $\frac{\delta \omega(J, \theta, Z)}{\delta |\Psi(\theta - l_1, Z_1)|^2}$ recursively. Actually, writing:

$$\begin{aligned} & \frac{\delta \omega \left(J, \theta - \frac{|Z-Z'|}{c}, Z' \right)}{\delta |\Psi(\theta - l_1, Z_1)|^2} \\ &= \int \omega \left(J, \theta - \frac{|Z-Z'|}{c} - \frac{|Z'-Z''|}{c}, Z'' \right) \tilde{T} \left(\theta - \frac{|Z-Z'|}{c}, Z', Z'', \omega, \Psi \right) \delta \left(\frac{|Z-Z'|}{c} + \frac{|Z'-Z''|}{c} - l_1 \right) dZ'' \\ &+ \int \frac{\delta \omega \left(J, \theta - \frac{|Z-Z'|}{c} - \frac{|Z'-Z''|}{c}, Z'' \right)}{\delta |\Psi(\theta - l_1, Z_1)|^2} \left| \Psi \left(\theta - \frac{|Z-Z'|}{c} - \frac{|Z'-Z''|}{c}, Z'' \right) \right|^2 \tilde{T} \left(\theta - \frac{|Z-Z'|}{c}, Z', Z'', \omega, \Psi \right) dZ'' \end{aligned}$$

we have:

$$\begin{aligned} & \frac{\delta \omega(J, \theta, Z)}{\delta |\Psi(\theta - l_1, Z_1)|^2} \\ &= \int \omega \left(J, \theta - \frac{|Z-Z'|}{c}, Z' \right) \tilde{T}(\theta, Z, Z_1, \omega, \Psi) \delta \left(\frac{|Z-Z'|}{c} - l_1 \right) dZ' \\ &+ \int \omega \left(J, \theta - \frac{|Z-Z'|}{c} - \frac{|Z'-Z''|}{c}, Z'' \right) \tilde{T} \left(\theta - \frac{|Z-Z'|}{c}, Z', Z'', \omega, \Psi \right) \\ &\times \left| \Psi \left(\theta - \frac{|Z-Z'|}{c}, Z' \right) \right|^2 \tilde{T}(\theta, Z, Z', \omega, \Psi) \delta \left(\frac{|Z-Z'|}{c} + \frac{|Z'-Z''|}{c} - l_1 \right) dZ' dZ'' \\ &+ \int \frac{\delta \omega \left(J, \theta - \frac{|Z-Z'|}{c} - \frac{|Z'-Z''|}{c}, Z'' \right)}{\delta |\Psi(\theta - l_1, Z_1)|^2} \left| \Psi \left(\theta - \frac{|Z-Z'|}{c} - \frac{|Z'-Z''|}{c}, Z'' \right) \right|^2 \\ &\times \tilde{T} \left(\theta - \frac{|Z-Z'|}{c}, Z', Z'', \omega, \Psi \right) \left| \Psi \left(\theta - \frac{|Z-Z'|}{c}, Z' \right) \right|^2 \tilde{T}(\theta, Z, Z', \omega, \Psi) dZ' dZ'' \end{aligned}$$

By a redefinition of \tilde{T} and \tilde{T}_1 :

$$\begin{aligned} & \tilde{T}(\theta, Z, Z', \omega, \Psi) \left| \Psi \left(\theta - \frac{|Z-Z'|}{c}, Z' \right) \right|^2 \rightarrow \tilde{T}(\theta, Z, Z', \omega, \Psi) \\ & \tilde{T}_1(\theta, Z, Z', \omega, \Psi) \left| \Psi \left(\theta - \frac{|Z-Z'|}{c}, Z' \right) \right|^2 \rightarrow \tilde{T}_1(\theta, Z, Z', \omega, \Psi) \end{aligned}$$

we find the series expansion:

$$\begin{aligned} \frac{\delta \omega(J, \theta, Z)}{\delta |\Psi(\theta - l_1, Z_1)|^2} &= \sum_{n=1}^{\infty} \frac{1}{|\Psi(\theta - l_1, Z_1)|^2} \int \omega \left(J, \theta - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c}, Z_1 \right) \tag{104} \\ &\times \prod_{l=1}^n \tilde{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega, \Psi \right) \delta \left(l_1 - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c} \right) \prod_{l=1}^{n-1} dZ^{(l)} \end{aligned}$$

and:

$$\begin{aligned} \frac{\delta\omega^{-1}(J, \theta, Z)}{\delta|\Psi(\theta - l_1, Z_1)|^2} &= \sum_{n=1}^{\infty} \frac{1}{|\Psi(\theta - l_1, Z_1)|^2} \int \omega \left(J, \theta - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c}, Z_1 \right) \tilde{T}_1 \left(\theta, Z, Z^{(1)}, \omega, \Psi \right) \\ &\times \prod_{l=2}^n \tilde{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega, \Psi \right) \delta \left(l_1 - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c} \right) \prod_{l=1}^{n-1} dZ^{(l)} \end{aligned} \quad (105)$$

with the convention that $Z^{(0)} = Z$ and $Z^{(n)} = Z_1$.

We can write (105) in a more symmetric way. Defining:

$$\check{T} \left(\theta, Z, Z^{(1)}, \omega, \Psi \right) = -\omega^2 \left(J, \theta - \frac{|Z - Z_1|}{c}, Z_1 \right) \tilde{T}_1 \left(\theta, Z, Z^{(1)}, \omega, \Psi \right)$$

Relation (100) writes:

$$\begin{aligned} \frac{\delta\omega^{-1}(J, \theta, Z)}{\delta|\Psi(\theta - l_1, Z_1)|^2} &= -\omega^{-1}(J, \theta - l_1, Z_1) \check{T}(\theta, Z, Z_1, \omega, \Psi) \delta \left(l_1 - \frac{|Z - Z_1|}{c} \right) \\ &+ \int \frac{\delta\omega^{-1} \left(J, \theta - \frac{|Z - Z'|}{c}, Z' \right)}{\delta|\Psi(\theta - l_1, Z_1)|^2} \left| \Psi \left(\theta - \frac{|Z - Z'|}{c}, Z' \right) \right|^2 \check{T}(\theta, Z, Z', \omega, \Psi) dZ' \end{aligned}$$

and we have:

$$\begin{aligned} \frac{\delta\omega^{-1}(J, \theta, Z)}{\delta|\Psi(\theta - l_1, Z_1)|^2} &= -\sum_{n=1}^{\infty} \frac{1}{|\Psi(\theta - l_1, Z_1)|^2} \int \omega^{-1} \left(J, \theta - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c}, Z_1 \right) \\ &\times \prod_{l=1}^n \tilde{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega, \Psi \right) \delta \left(l_1 - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c} \right) \prod_{l=1}^{n-1} dZ^{(l)} \end{aligned} \quad (106)$$

1.1.2 Static approximation

We now use a static approximations (104) and (105). Actually, the values of $\tilde{T}_1(\theta, Z, Z_1, \omega, \Psi)$ and $\tilde{T}(\theta, Z, Z_1, \omega, \Psi)$ can be estimated for the static approximation for activity $\bar{\omega}^{-1}(\bar{J}, Z)$. Moreover, in the limit of small fluctuations, $\bar{\omega}^{-1}(\bar{J}, Z)$, $F'[J, \bar{\omega}, Z, \Psi]$ and $G'[J, \bar{\omega}, Z, \Psi]$ can be approximated by their average over Z , denoted $\bar{\omega}^{-1}$, \bar{F}' and \bar{G}' . We also have:

$$\frac{\bar{\omega}(J, Z')}{\bar{\omega}(J, Z)} \simeq 1$$

We also replace $|\Psi|^2$ by $\frac{1}{\sqrt{\frac{\pi}{2} \left(\frac{1}{\sigma^2 X_r} \right)^2 + \frac{2\pi\alpha}{\sigma^2}}}$. Moreover for $\bar{\omega}$, both \tilde{T}_1 and \tilde{T} can be considered independent of θ :

$$\begin{aligned} \tilde{T}_1(\theta, Z, Z_1, \bar{\omega}, \Psi) &\simeq \tilde{T}_1(Z, Z_1, \bar{\omega}) \\ &= \frac{1}{\sqrt{\frac{\pi}{2} \left(\frac{1}{\sigma^2 X_r} \right)^2 + \frac{2\pi\alpha}{\sigma^2}}} \frac{\frac{\kappa}{N} \bar{\omega}^{-1} T(Z, Z_1) \bar{G}'}{1 - \frac{\bar{G}' \bar{\omega} \int \frac{\kappa}{N} T(Z, Z') dZ'}{\sqrt{\frac{\pi}{2} \left(\frac{1}{\sigma^2 X_r} \right)^2 + \frac{2\pi\alpha}{\sigma^2}}} \end{aligned} \quad (107)$$

and:

$$\begin{aligned}\tilde{T}(\theta, Z, Z_1, \omega, \Psi) &\simeq \tilde{T}(Z, Z_1, \bar{\omega}) \\ &= \frac{1}{\sqrt{\frac{\pi}{2} \left(\frac{1}{\sigma^2 X_r} \right)^2 + \frac{2\pi\alpha}{\sigma^2}}} \frac{\frac{k}{N} T(Z, Z_1) \bar{F}'}{\frac{F' \int \frac{k}{N} T(Z, Z') dZ'}{\sqrt{\frac{\pi}{2} \left(\frac{1}{\sigma^2 X_r} \right)^2 + \frac{2\pi\alpha}{\sigma^2}}}}\end{aligned}\quad (108)$$

as a consequence $\tilde{T}_1(Z, Z_1, \bar{\omega})$ and $\tilde{T}(Z, Z_1, \bar{\omega})$ are functions of $|Z - Z_1|$ denoted $\tilde{T}_1(|Z - Z_1|)$ and $\tilde{T}(|Z - Z_1|)$. As a consequence (104) becomes:

$$\begin{aligned}&\frac{\delta\omega(J, \theta, Z)}{\delta|\Psi(\theta - l_1, Z_1)|^2} \\ &= \sum_{n=1}^{\infty} \frac{1}{|\Psi(\theta - l_1, Z_1)|^2} \int \omega \left(J, \theta - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c}, Z_1 \right) \prod_{l=1}^n \tilde{T}(|Z^{(l-1)} - Z^{(l)}|) \\ &\quad \times \delta \left(l_1 - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c} \right) \times \delta \left(Z - Z_1 - \sum_{l=1}^n (Z^{(l-1)} - Z^{(l)}) \right) \prod_{l=1}^{n-1} dZ^{(l)}\end{aligned}\quad (109)$$

and (105) can be estimated by:

$$\begin{aligned}&\frac{\delta\omega^{-1}(J, \theta, Z)}{\delta|\Psi(\theta - l_1, Z_1)|^2} \\ &= \sum_{n=1}^{\infty} \frac{1}{|\Psi(\theta - l_1, Z_1)|^2} \int \omega \left(J, \theta - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c}, Z_1 \right) \tilde{T}_1(|Z - Z_1|) \\ &\quad \times \prod_{l=2}^n \tilde{T}(|Z^{(l-1)} - Z^{(l)}|) \delta \left(l_1 - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c} \right) \delta \left(Z - Z_1 - \sum_{l=1}^n (Z^{(l-1)} - Z^{(l)}) \right) \prod_{l=1}^{n-1} dZ^{(l)}\end{aligned}\quad (110)$$

1.2 Estimation of (110) and (104) close to the permanent regime

The series (110) can be computed by using the Fourier transform of the Dirac functions:

$$\begin{aligned}&|\Psi(\theta - l_1, Z_1)|^2 \frac{\delta\omega^{-1}(J, \theta, Z)}{\delta|\Psi(\theta - l_1, Z_1)|^2} \\ &= \sum_{n=1}^{\infty} \int \omega(J, \theta - l_1, Z_1) \times \tilde{T}_1(|Z - Z^{(1)}|) \prod_{l=2}^n \tilde{T}(|Z^{(l-1)} - Z^{(l)}|) \exp \left(i\lambda \left(cl_1 - \sum_{l=1}^n |Z^{(l-1)} - Z^{(l)}| \right) \right) \\ &\quad \times \exp \left(i\lambda_1 \cdot \left(Z - Z_1 - \sum_{l=1}^n (Z^{(l-1)} - Z^{(l)}) \right) \right) d\lambda d\lambda_1 \prod_{l=1}^n |Z^{(l-1)} - Z^{(l)}|^2 d|Z^{(l-1)} - Z^{(l)}| dv_l\end{aligned}\quad (111)$$

where the unit vectors v_l are defined such that:

$$Z^{(l-1)} - Z^{(l)} = v_l |Z^{(l-1)} - Z^{(l)}|$$

We also define:

$$\begin{aligned}\lambda_1 \cdot (Z - Z_1) &= |\lambda_1| |Z - Z_1| \cos(\theta_1) \\ \lambda_1 \cdot v_l &= |\lambda_1| \cos(\theta_l)\end{aligned}$$

The angles θ_l are computed in the plane $(\lambda_1, Z - Z_1)$ between the projection of v_l and $Z - Z_1$.

Before computing the integrals in (111) for arbitrary connectivity functions, we develop the particular case of an exponential transfer function.

1.2.1 Exponential connectivity function

We first choose:

$$\begin{aligned}\tilde{T}\left(\left|Z^{(l-1)}-Z^{(l)}\right|\right) &= C\frac{\exp(-c\left|Z^{(l-1)}-Z^{(l)}\right|)}{\left|Z^{(l-1)}-Z^{(l)}\right|} \\ \tilde{T}_1\left(\left|Z^{(l-1)}-Z^{(l)}\right|\right) &\simeq \frac{A_1}{A}C\hat{T}\left(\left|Z^{(l-1)}-Z^{(l)}\right|\right)\end{aligned}\quad (112)$$

where, given (107) and (108):

$$\begin{aligned}\frac{A_1}{A} &= \frac{\tilde{T}_1\left(\theta-\sum_{l=1}^n\frac{\left|Z^{(l-1)}-Z^{(l)}\right|}{c}, Z, Z^{(1)}, \omega, \Psi\right)}{\tilde{T}\left(\theta-\sum_{l=1}^n\frac{\left|Z^{(l-1)}-Z^{(l)}\right|}{c}, Z, Z^{(1)}, \omega, \Psi\right)} \\ &= \frac{\frac{\frac{\kappa}{N}\bar{\omega}^{-1}T(Z, Z_1)\bar{G}'}{1-\frac{\bar{G}'\bar{\omega}\int\frac{\kappa}{N}T(Z, Z')dZ'}{\sqrt{\frac{\pi}{2}\left(\frac{1}{\sigma^2 X_r}\right)^2+\frac{2\pi\alpha}{\sigma^2}}}}}{\bar{\omega}+\frac{\frac{\kappa}{N}T(Z, Z_1)\bar{F}'}{\bar{F}'\int\frac{\kappa}{N}T(Z, Z')dZ'}{\sqrt{\frac{\pi}{2}\left(\frac{1}{\sigma^2 X_r}\right)^2+\frac{2\pi\alpha}{\sigma^2}}}}}{\bar{\omega}+\frac{\frac{\kappa}{N}T(Z, Z_1)\bar{F}'}{\bar{F}'\int\frac{\kappa}{N}T(Z, Z')dZ'}{\sqrt{\frac{\pi}{2}\left(\frac{1}{\sigma^2 X_r}\right)^2+\frac{2\pi\alpha}{\sigma^2}}}}}\right)^{-1} \simeq -(\bar{\omega}^{-1})^2\end{aligned}\quad (113)$$

We will disregard the factor $\frac{A_1}{A}$ that will be reintroduced in the end of the computation.

Using that $\sum_{l=1}^n(Z^{(l-1)}-Z^{(l)})=cl_1$, the right hand side of (111) becomes:

$$\begin{aligned}&\exp(-cl_1)\times\sum_{n=1}^{\infty}\int\exp\left(i\lambda\left(cl_1-\sum_{l=1}^n\left|Z^{(l-1)}-Z^{(l)}\right|\right)\right) \\ &\times\exp\left(i\lambda_1\left(Z-Z_1-\sum_{l=1}^n\left(Z^{(l-1)}-Z^{(l)}\right)\right)\right)d\lambda d\lambda_1\prod_{l=1}^n C\left|Z^{(l-1)}-Z^{(l)}\right|d\left|Z^{(l-1)}-Z^{(l)}\right|dv_l\end{aligned}$$

that can be written in terms of the angles as:

$$\begin{aligned}&\exp(-cl_1)\times\sum_{n=1}^{\infty}\int\exp(i\lambda cl_1+i|\lambda_1||Z-Z_1|\cos(\theta_1)) \\ &\times\exp\left(-i\sum_{l=1}^n(\lambda+|\lambda_1|\cos(\theta_l))\left|Z^{(l-1)}-Z^{(l)}\right|\right)d\lambda d\lambda_1\prod_{l=1}^n C\left|Z^{(l-1)}-Z^{(l)}\right|d\left|Z^{(l-1)}-Z^{(l)}\right|dv_l\end{aligned}\quad (114)$$

The integration over θ_i is:

$$\begin{aligned}&\pi\int_0^\pi\exp\left(-i(\lambda+|\lambda_1|\cos(\theta_l))\left|Z^{(l-1)}-Z^{(l)}\right|\right)\sin(\theta_l)d\theta_l \\ &= -\frac{\pi i}{|\lambda_1|\left|Z^{(l-1)}-Z^{(l)}\right|}\left(\exp\left(-i(\lambda-|\lambda_1|)\left|Z^{(l-1)}-Z^{(l)}\right|\right)-\exp\left(-i(\lambda+|\lambda_1|)\left|Z^{(l-1)}-Z^{(l)}\right|\right)\right) \\ &= \frac{\pi i}{|\lambda_1|\left|Z^{(l-1)}-Z^{(l)}\right|}\left(\exp\left(-i(\lambda+|\lambda_1|)\left|Z^{(l-1)}-Z^{(l)}\right|\right)-\exp\left(-i(\lambda-|\lambda_1|)\left|Z^{(l-1)}-Z^{(l)}\right|\right)\right)\end{aligned}$$

and (114) rewrites:

$$\begin{aligned}&\exp(-cl_1)\times\sum_{n=1}^{\infty}\int\frac{-\pi i}{|\lambda_1|\left|Z-Z_1\right|}\left(\exp(i\lambda cl_1+i|\lambda_1||Z-Z_1|)-\exp(i\lambda cl_1-i|\lambda_1||Z-Z_1|)\right) \\ &\times\prod_{l=1}^n C\frac{\pi i}{|\lambda_1|}\left(\exp\left(-i(\lambda+|\lambda_1|)\left|Z^{(l-1)}-Z^{(l)}\right|\right)-\exp\left(-i(\lambda-|\lambda_1|)\left|Z^{(l-1)}-Z^{(l)}\right|\right)\right) \\ &\times d\left|Z^{(l-1)}-Z^{(l)}\right|d\lambda|\lambda_1|^2d|\lambda_1|\end{aligned}$$

We can then perform the integrals over the norms $|Z^{(l-1)} - Z^{(l)}|$, which yields:

$$\begin{aligned} & \exp(-cl_1) \times \sum_{n=1}^{\infty} \int \frac{-\pi i}{|\lambda_1| |Z - Z_1|} (\exp(i\lambda cl_1 + i|\lambda_1| |Z - Z_1|) - \exp(i\lambda cl_1 - i|\lambda_1| |Z - Z_1|)) \\ & \times \prod_{l=1}^n C \frac{\pi}{|\lambda_1|} \left(\frac{1}{\lambda + |\lambda_1| - i\varepsilon} - \frac{1}{\lambda - |\lambda_1| - i\varepsilon} \right) d\lambda |\lambda_1|^2 d|\lambda_1| \end{aligned}$$

Performing the sum yields then the following expression for (114):

$$\begin{aligned} & \exp(-cl_1) \times \int \frac{-\pi i}{|\lambda_1| |Z - Z_1|} (\exp(i\lambda cl_1 + i|\lambda_1| |Z - Z_1|) - \exp(i\lambda cl_1 - i|\lambda_1| |Z - Z_1|)) \\ & \times \frac{-C \frac{2\pi}{(\lambda + |\lambda_1| - i\varepsilon)(\lambda - |\lambda_1| - i\varepsilon)}}{1 + C \frac{2\pi}{(\lambda + |\lambda_1| - i\varepsilon)(\lambda - |\lambda_1| - i\varepsilon)}} d\lambda |\lambda_1|^2 d|\lambda_1| \\ = & \exp(-cl_1) \times \int \frac{-\pi i}{|\lambda_1| |Z - Z_1|} (\exp(i\lambda cl_1 + i|\lambda_1| |Z - Z_1|) - \exp(i\lambda cl_1 - i|\lambda_1| |Z - Z_1|)) \\ & \times \frac{-2\pi C}{(\lambda + |\lambda_1| - i\varepsilon)(\lambda - |\lambda_1| - i\varepsilon) + 2\pi C} d\lambda |\lambda_1|^2 d|\lambda_1| \end{aligned}$$

Ultimately, the previous formula can be reduced to a single expression, by performing the change of variable $x = -|\lambda_1|$ in the term with $\exp(i\lambda cl_1 - i|\lambda_1| |Z - Z_1|)$ in factor. We obtain:

$$\exp(-cl_1) \times \int \frac{-\pi i}{|Z - Z_1|} \exp(i\lambda cl_1 + i\lambda_1 |Z - Z_1|) \frac{-2\pi C \lambda_1}{(\lambda + \lambda_1 - i\varepsilon)(\lambda - \lambda_1 - i\varepsilon) + 2\pi C} d\lambda d\lambda_1$$

where the integral over λ_1 is now performed with $\lambda_1 \in \mathbb{R}$. This integral is computed by the residue theorem, where the residues satisfy:

$$\lambda_1^2 = (\lambda - i\varepsilon)^2 + 2\pi C$$

leading to write (114) as:

$$\begin{aligned} & \exp(-cl_1) \times \int \frac{-\pi i}{|Z - Z_1|} \exp\left(i\lambda cl_1 + i\sqrt{(\lambda - i\varepsilon)^2 + 2\pi C} |Z - Z_1|\right) d\lambda \\ & + \exp(-cl_1) \times \int \frac{-\pi i}{|Z - Z_1|} \exp\left(i\lambda cl_1 - i\sqrt{(\lambda - i\varepsilon)^2 + 2\pi C} |Z - Z_1|\right) d\lambda \end{aligned} \quad (115)$$

We then perform the change of variable:

$$\begin{aligned} x &= \lambda + \sqrt{\lambda^2 + 2\pi C} \\ dx &= \left(1 + \frac{\lambda}{\sqrt{\lambda^2 + 2\pi C}}\right) d\lambda \\ &= \frac{x}{\sqrt{\lambda^2 + 2\pi C}} d\lambda = \frac{2x^2}{x^2 + 2\pi C} d\lambda \end{aligned}$$

and rewrite the exponents in (115) as:

$$\begin{aligned} \lambda cl_1 + \sqrt{(\lambda - i\varepsilon)^2 + 2\pi C} |Z - Z_1| &= \frac{cl_1 + |Z - Z_1|}{2} \left(\lambda + \sqrt{\lambda^2 + 2\pi C}\right) \\ &+ \frac{cl_1 - |Z - Z_1|}{2} \left(\lambda - \sqrt{\lambda^2 + 2\pi C}\right) \\ &= \frac{cl_1 + |Z - Z_1|}{2} \left(\lambda + \sqrt{\lambda^2 + 2\pi C}\right) - \frac{cl_1 - |Z - Z_1|}{2} \frac{2\pi C}{\lambda + \sqrt{\lambda^2 + 2\pi C}} \\ &= \frac{cl_1 + |Z - Z_1|}{2} x - \frac{cl_1 - |Z - Z_1|}{2} \frac{2\pi C}{x} \end{aligned}$$

and:

$$\lambda cl_1 - \sqrt{(\lambda - i\varepsilon)^2 + 2\pi C |Z - Z_1|} = \frac{cl_1 - |Z - Z_1|}{2} x - \frac{cl_1 + |Z - Z_1|}{2} \frac{2\pi C}{x}$$

As a consequence, expression (115) becomes:

$$\begin{aligned} & \exp(-cl_1) \times \int \frac{-\pi i}{|Z - Z_1|} \exp\left(i \left(\frac{cl_1 + |Z - Z_1|}{2} x - \frac{cl_1 - |Z - Z_1|}{2} \frac{2\pi C}{x} \right)\right) dx \\ & + \exp(-cl_1) \times \int \frac{-\pi i}{|Z - Z_1|} \exp\left(i \left(\frac{cl_1 - |Z - Z_1|}{2} x - \frac{cl_1 + |Z - Z_1|}{2} \frac{2\pi C}{x} \right)\right) dx \\ & + 2\pi C \exp(-cl_1) \times \int \frac{-\pi i}{|Z - Z_1|} \exp\left(i \left(\frac{cl_1 + |Z - Z_1|}{2} x - \frac{cl_1 - |Z - Z_1|}{2} \frac{2\pi C}{x} \right)\right) \frac{1}{x^2} dx \\ & + 2\pi C \times \int \frac{-\pi i}{|Z - Z_1|} \exp\left(i \left(\frac{cl_1 - |Z - Z_1|}{2} x - \frac{cl_1 + |Z - Z_1|}{2} \frac{2\pi C}{x} \right)\right) \frac{1}{x^2} dx \end{aligned}$$

Performing the change of variable $y = \frac{1}{x}$ in the two last expressions yields:

$$\begin{aligned} & \exp(-cl_1) (1 + 2\pi C) \times \left(\int \frac{-\pi i}{|Z - Z_1|} \exp\left(i \left(\frac{cl_1 + |Z - Z_1|}{2} x - \frac{cl_1 - |Z - Z_1|}{2} \frac{2\pi C}{x} \right)\right) dx \right. \\ & \left. + \int \frac{-\pi i}{|Z - Z_1|} \exp\left(i \left(\frac{cl_1 - |Z - Z_1|}{2} x - \frac{cl_1 + |Z - Z_1|}{2} \frac{2\pi C}{x} \right)\right) dx \right) \end{aligned}$$

and by analytic continuation $x \rightarrow ix$, this becomes:

$$\begin{aligned} & \exp(-cl_1) (1 + 2\pi C) \times \left(\int \frac{\pi}{|Z - Z_1|} \exp\left(- \left(\frac{cl_1 + |Z - Z_1|}{2} x - \frac{cl_1 - |Z - Z_1|}{2} \frac{2\pi C}{x} \right)\right) dx \right. \\ & \left. + \int \frac{\pi}{|Z - Z_1|} \exp\left(- \left(\frac{cl_1 - |Z - Z_1|}{2} x - \frac{cl_1 + |Z - Z_1|}{2} \frac{2\pi C}{x} \right)\right) dx \right) \end{aligned}$$

Ultimately, reintroducing the constraint $H(cl_1 - |Z - Z_1|)$ and the factor $\frac{A_1}{A}$, (111) writes:

$$\begin{aligned} |\Psi(\theta - l_1, Z_1)|^2 \frac{\delta\omega^{-1}(J, \theta, Z)}{\delta|\Psi(\theta - l_1, Z_1)|^2} &= (1 + 2\pi C) \frac{A_1 \exp(-cl_1)}{A |Z - Z_1|} \left(\sqrt{\frac{cl_1 - |Z - Z_1|}{cl_1 + |Z - Z_1|}} + \sqrt{\frac{cl_1 + |Z - Z_1|}{cl_1 - |Z - Z_1|}} \right) \\ &\quad \times K_1 \left(\frac{cl_1 - |Z - Z_1|}{2} 2\pi C \frac{cl_1 + |Z - Z_1|}{2} \right) \omega(J, \theta - l_1, Z_1) \\ &= (1 + 2\pi C) \frac{A_1 \exp(-cl_1)}{A |Z - Z_1|} \left(\sqrt{\frac{cl_1 - |Z - Z_1|}{cl_1 + |Z - Z_1|}} + \sqrt{\frac{cl_1 + |Z - Z_1|}{cl_1 - |Z - Z_1|}} \right) \\ &\quad \times K_1 \left(\pi C \frac{(cl_1)^2 - |Z - Z_1|^2}{2} \right) \omega(J, \theta - l_1, Z_1) \end{aligned} \quad (116)$$

In first approximation, the right hand side of (116) is:

$$\begin{aligned} & \frac{\exp(-cl_1) (cl_1 + |Z - Z_1|)}{B |Z - Z_1|} \exp\left(-\pi C \frac{(cl_1)^2 - |Z - Z_1|^2}{2}\right) \omega(J, \theta - l_1, Z_1) \\ & \sim \frac{\exp(-cl_1)}{B} \exp\left(-\pi C cl_1 \frac{cl_1 - |Z - Z_1|}{2}\right) H(cl_1 - |Z - Z_1|) \omega(J, \theta - l_1, Z_1) \end{aligned} \quad (117)$$

for $cl_1 \gg |Z - Z_1|$. This can also be replaced by a simplest form:

$$|\Psi(\theta - l_1, Z_1)|^2 \frac{\delta\omega^{-1}(J, \theta, Z)}{\delta|\Psi(\theta - l_1, Z_1)|^2} \simeq \frac{\exp\left(-cl_1 - \alpha \left((cl_1)^2 - |Z - Z_1|^2 \right)\right)}{B} H(cl_1 - |Z - Z_1|) \omega(J, \theta - l_1, Z_1) \quad (118)$$

where B and α are constants.

Using (106), the same computation can be performed by replacing \hat{T} with \tilde{T} and we obtain:

$$|\Psi(\theta - l_1, Z_1)|^2 \frac{\delta\omega^{-1}(J, \theta, Z)}{\delta|\Psi(\theta - l_1, Z_1)|^2} \simeq \frac{\exp\left(-cl_1 - \alpha\left((cl_1)^2 - |Z - Z_1|^2\right)\right)}{D} H(cl_1 - |Z - Z_1|) \omega^{-1}(J, \theta - l_1, Z_1) \quad (119)$$

with D a constant:

$$D = \frac{B}{\bar{\omega}^2}$$

with $\bar{\omega}(J)$ the average activity.

1.2.2 General formula

For an arbitrary connectivity function:

$$\tilde{T}\left(|Z^{(l-1)} - Z^{(l)}|\right) = C \exp\left(-c|Z^{(l-1)} - Z^{(l)}|\right) f\left(|Z^{(l-1)} - Z^{(l)}|\right)$$

we can factor $C \exp(-cl)$ as in the previous paragraph. It amounts to replace:

$$\tilde{T}\left(|Z^{(l-1)} - Z^{(l)}|\right) \rightarrow f\left(|Z^{(l-1)} - Z^{(l)}|\right)$$

We rewrite (111) as:

$$\begin{aligned} & |\Psi(\theta - l_1, Z_1)|^2 \frac{\delta\omega^{-1}(J, \theta, Z)}{\delta|\Psi(\theta - l_1, Z_1)|^2} \quad (120) \\ &= \sum_{n=1}^{\infty} \int \omega(J, \theta - l_1, Z_1) \times T_1''(\lambda + \lambda_1.v_1) dv_1 \prod_{l=2}^n \int T''(\lambda + \lambda_1.v_l) dv_l \exp(i\lambda cl_1 + i\lambda_1.(Z - Z_1)) d\lambda d\lambda_1 \\ &= \delta(|Z_1 - Z| - cl_1) \tilde{T}_1\left(|Z - Z^{(1)}|\right) \omega(J, \theta - l_1, Z_1) \\ &+ (-1)^n \int \omega(J, \theta - l_1, Z_1) \times \frac{T_1''(\lambda + \lambda_1.v_1)}{2} dv_1 \prod_{l=2}^n \int \frac{T''(\lambda + \lambda_1.v_l)}{2} dv_l \exp(i\lambda cl_1 + i\lambda_1.(Z - Z_1)) d\lambda d\lambda_1 \end{aligned}$$

With the convention that for $n = 1$, the product $\prod_{l=2}^n$ is set to be equal to 1. The functions T_1 and T are the fourier transform of $\tilde{T}_1 H$ and $\tilde{T} H$ respectively, and H is the heaviside function. Remark that the first term of (120) expresses the Dirac function $\delta(|Z_1 - Z| - cl_1)$ as a Fourier transform:

$$\begin{aligned} & \exp\left(i\lambda\left(cl_1 - \sum_{l=1}^n |Z^{(0)} - Z^{(l)}|\right)\right) \\ & \times \exp\left(i\lambda_1.\left(Z - Z_1 - \sum_{l=1}^n (Z^{(0)} - Z^{(l)})\right)\right) d\lambda d\lambda_1 |Z^{(0)} - Z^{(1)}|^2 d|Z^{(0)} - Z^{(1)}| dv_l \end{aligned}$$

Some terms of (120) can be written in a useful form for the sequel:

$$\begin{aligned} \frac{1}{2} \int T''(\lambda + \lambda_1.v_l) dv_l &= \pi \int_0^\pi T''(\lambda + |\lambda_1| \cos(\theta_l)) \sin(\theta_l) d\theta_l \\ &= \pi \int_{-1}^1 T''(\lambda + |\lambda_1| u) du \\ &= \frac{2\pi (T'(\lambda + |\lambda_1|) - T'(\lambda - |\lambda_1|))}{2|\lambda_1|} \\ &\equiv \tilde{T}(\lambda, |\lambda_1|) \quad (121) \end{aligned}$$

$$\begin{aligned}\int T_1''(\lambda + \lambda_1 \cdot v_l) dv_l &= \frac{2\pi(T_1'(\lambda + |\lambda_1|) - T_1'(\lambda - |\lambda_1|))}{2|\lambda_1|} \\ &\equiv \bar{T}_1(\lambda, |\lambda_1|)\end{aligned}\quad (122)$$

$$\begin{aligned}\exp(i\lambda_1 \cdot (Z - Z_1)) d\lambda_1 &= \exp(i \cos(\theta_1) |\lambda_1| |Z - Z_1|) \sin(\theta_1) |\lambda_1|^2 d|\lambda_1| d\theta_1 \\ &= \exp(iu |\lambda_1| |Z - Z_1|) |\lambda_1|^2 d|\lambda_1| du\end{aligned}\quad (123)$$

Remark that the functions of x :

$$\bar{T}(\lambda, x) = \frac{2\pi(T'(\lambda + x) - T'(\lambda - x))}{2x} \quad \text{and} \quad \bar{T}_1(\lambda, x) = \frac{2\pi(T_1'(\lambda + x) - T_1'(\lambda - x))}{2x}$$

are even.

1.2.3 Estimation of (120)

Using (121), (122) and (123), equation (120) becomes:

$$\begin{aligned}& |\Psi(\theta - l_1, Z_1)|^2 \frac{\delta\omega^{-1}(J, \theta, Z)}{\delta|\Psi(\theta - l_1, Z_1)|^2} \\ &= \sum_{n=1}^{\infty} (-1)^n \int \omega(J, \theta - l_1, Z_1) \times T_1(\lambda + \lambda_1 \cdot v_1) dv_1 \prod_{l=2}^n \int T(\lambda + \lambda_1 \cdot v_l) dv_l \exp(i\lambda cl_1 + i\lambda_1 \cdot (Z - Z_1)) d\lambda d\lambda_1 \\ &= - \int \omega(J, \theta - l_1, Z_1) \times \frac{\bar{T}_1(\lambda, |\lambda_1|)}{1 + \bar{T}(\lambda, |\lambda_1|)} \exp(i\lambda cl_1) \int_{-1}^1 \exp(iu |\lambda_1| |Z - Z_1|) |\lambda_1|^2 d|\lambda_1| dud\lambda \\ &= - \int \omega(J, \theta - l_1, Z_1) \times \frac{\bar{T}_1(\lambda, |\lambda_1|)}{1 + \bar{T}(\lambda, |\lambda_1|)} \exp(i\lambda cl_1) \left(2 \frac{\sin(|\lambda_1| |Z - Z_1|)}{|Z - Z_1|} |\lambda_1| \right) d|\lambda_1| d\lambda\end{aligned}\quad (124)$$

We remark that for even functions f , the following identity holds:

$$\begin{aligned}& \int_0^{+\infty} f(|\lambda_1|) 2 \frac{\sin(|\lambda_1| |Z - Z_1|)}{|Z - Z_1|} |\lambda_1| d|\lambda_1| \\ &= \int_0^{+\infty} f(x) \frac{\exp(ix|Z - Z_1|) - \exp(-ix|Z - Z_1|)}{i|Z - Z_1|} x dx \\ &= \int_0^{+\infty} f(x) \frac{\exp(ix|Z - Z_1|)}{i|Z - Z_1|} x dx + \int_{-\infty}^0 f(-x) \frac{\exp(ix|Z - Z_1|)}{i|Z - Z_1|} x dx \\ &= \int_{-\infty}^{+\infty} f(x) \frac{\exp(ix|Z - Z_1|)}{i|Z - Z_1|} x dx\end{aligned}$$

so that (124) becomes:

$$\begin{aligned}& |\Psi(\theta - l_1, Z_1)|^2 \frac{\delta\omega^{-1}(J, \theta, Z)}{\delta|\Psi(\theta - l_1, Z_1)|^2} \\ &= - \int \omega(J, \theta - l_1, Z_1) \times \frac{\bar{T}_1(\lambda, \lambda_1)}{1 + \bar{T}(\lambda, \lambda_1)} \frac{\lambda_1}{i|Z - Z_1|} \exp(i\lambda cl_1 + i\lambda_1 |Z - Z_1|) d\lambda_1 d\lambda \\ &= - \int \omega(J, \theta - l_1, Z_1) \times \frac{\pi(T_1'(\lambda + \lambda_1) - T_1'(\lambda - \lambda_1))}{\lambda_1 + \pi(T'(\lambda + \lambda_1) - T'(\lambda - \lambda_1))} \frac{\lambda_1}{i|Z - Z_1|} \\ &\quad \times \exp(i\lambda cl_1 + i\lambda_1 |Z - Z_1|) d\lambda_1 d\lambda \\ &= - \int \omega(J, \theta - l_1, Z_1) \times \frac{\pi(T_1'(\lambda + \lambda_1) - T_1'(\lambda - \lambda_1))}{\lambda_1 + \pi(T'(\lambda + \lambda_1) - T'(\lambda - \lambda_1))} \frac{\lambda_1}{i|Z - Z_1|} \\ &\quad \times \exp(iu(cl_1 + |Z - Z_1|)) \times \exp(iv(cl_1 - |Z - Z_1|)) d\lambda_1 d\lambda\end{aligned}\quad (125)$$

As in the previous paragraph, we also simplify (125) by writing T_1 as a function of T :

$$T'_1(\lambda + \lambda_1) - T'_1(\lambda - \lambda_1) = \frac{A_1}{A} (T'(\lambda + \lambda_1) - T'(\lambda - \lambda_1))$$

and by setting:

$$\begin{aligned} u &= \frac{\lambda + \lambda_1}{2} \\ v &= \frac{\lambda - \lambda_1}{2} \end{aligned}$$

so that we are lead to:

$$\begin{aligned} |\Psi(\theta - l_1, Z_1)|^2 \frac{\delta\omega^{-1}(J, \theta, Z)}{\delta|\Psi(\theta - l_1, Z_1)|^2} &= - \int \omega(J, \theta - l_1, Z_1) \times \frac{A_1}{A} \frac{\pi(T'_1(\lambda + \lambda_1) - T'_1(\lambda - \lambda_1))}{\lambda_1 + \pi(T'(\lambda + \lambda_1) - T'(\lambda - \lambda_1))} \frac{\lambda_1}{i|Z - Z_1|} \\ &\times \exp(iu(cl_1 + |Z - Z_1|)) \times \exp(iv(cl_1 - |Z - Z_1|)) d\lambda_1 d\lambda \end{aligned} \quad (126)$$

Remark that the particular case of the exponential connectivity function is encompassed in (125).

Actually, if we choose:

$$\tilde{T}\left(|Z^{(l-1)} - Z^{(l)}|\right) = C \frac{\exp(-c|Z^{(l-1)} - Z^{(l)}|)}{|Z^{(l-1)} - Z^{(l)}|}$$

we have:

$$\prod_{l=1}^n \tilde{T}\left(|Z^{(l-1)} - Z^{(l)}|\right) = \exp(-cl_1) \prod_{l=1}^n \frac{C}{|Z^{(l-1)} - Z^{(l)}|}$$

For such a choice, we have formally: $T = -iC \int (FH)$ where H is the heaviside function. As a consequence:

$$T'(\lambda) = CFH = -\frac{C}{\lambda + i\varepsilon}$$

and (126) is equivalent to the expressions of appendix 1.3.2.1.

In the general case, we write $\lambda_1^{(r)}$, $r = 1, \dots$ the solutions to the pole equation of (126):

$$\lambda_1 + \pi(T'(\lambda + \lambda_1) - T'(\lambda - \lambda_1)) = 0$$

For regular functions $T'(\lambda + \lambda_1)$ such that for $\lambda \rightarrow \infty$:

$$T'(\lambda + \lambda_1) \simeq \frac{g(\lambda + \lambda_1)}{(\lambda + \lambda_1)^l}$$

$$\int \frac{1}{(\lambda - s)^l} |\Psi(s)|$$

with $l > 0$ given and g bounded, the poles equation implies that for $\lambda \rightarrow \infty$:

$$\lambda_1 \simeq \pm\lambda$$

and as a consequence, we can write:

$$\lambda_1^{(r)} = \sqrt{\lambda^2 + h_r(\lambda)} \quad (127)$$

where $h_r(\lambda)$ is bounded.

We can compute the values of the residues at each pole by the first order expansion of $1 + \pi \frac{T'(\lambda + \lambda_1) - T'(\lambda - \lambda_1)}{\lambda_1}$:

$$\begin{aligned}
& 1 + \pi \frac{T'(\lambda + \lambda_1) - T'(\lambda - \lambda_1)}{\lambda_1} \\
& \simeq \pi \left(\frac{T'(\lambda + \lambda_1) - T'(\lambda - \lambda_1)}{\lambda_1} - \frac{T'(\lambda + \lambda_1^{(r)}) - T'(\lambda - \lambda_1^{(r)})}{\lambda_1^{(r)}} \right) \\
& \simeq \pi \left(\frac{\frac{1}{\pi} + T''(\lambda + \lambda_1^{(r)}) + T''(\lambda - \lambda_1^{(r)})}{\lambda_1^{(r)}} \right) \\
& \simeq \pi \left(\frac{T''(\lambda + \lambda_1^{(r)}) + T''(\lambda - \lambda_1^{(r)}) - \frac{T'(\lambda + \lambda_1^{(r)}) - T'(\lambda - \lambda_1^{(r)})}{\lambda_1^{(r)}}}{\lambda_1^{(r)}} \right)
\end{aligned}$$

For regular functions $T'(\lambda + \lambda_1)$, this can be expanded as:

$$2\pi\lambda_1^{(r)} \left(\sum_{k \geq 1} \frac{T^{(2k+2)}(\lambda)}{(2k)!} (\lambda_1^{(r)})^{2k-2} - \sum_{k \geq 1} \frac{T^{(2k+2)}(\lambda)}{(2k+1)!} (\lambda_1^{(r)})^{2k-2} \right)$$

and for relatively slowly varying functions, this reduces to:

$$1 + \pi \frac{T'(\lambda + \lambda_1) - T'(\lambda - \lambda_1)}{\lambda_1} \simeq 2\pi\lambda_1^{(r)} \frac{T^{(4)}(\lambda)}{3} \quad (128)$$

and the residue theorem implies to replace:

$$\begin{aligned}
& \frac{\pi (T_1'(\lambda + \lambda_1) - T_1'(\lambda - \lambda_1))}{\lambda_1 + \pi (T'(\lambda + \lambda_1) - T'(\lambda - \lambda_1))} \frac{\lambda_1}{i|Z - Z_1|} \\
& \rightarrow -\frac{i}{\pi |Z - Z_1|} \frac{3}{T^{(4)}(\lambda)}
\end{aligned} \quad (129)$$

in (126). Using (127) and (129) in (126) leads to:

$$\begin{aligned}
& |\Psi(\theta - l_1, Z_1)|^2 \frac{\delta\omega^{-1}(J, \theta, Z)}{\delta |\Psi(\theta - l_1, Z_1)|^2} \\
& \simeq \sum_r \frac{i}{\pi} \frac{1}{|Z - Z_1|} \int \omega(J, \theta - l_1, Z_1) \\
& \quad \times \frac{3}{T^{(4)}(\lambda)} \exp(iu(cl_1 + |Z - Z_1|)) \times \exp(iv(cl_1 - |Z - Z_1|)) d\lambda \\
& = \sum_r \frac{i}{\pi} \frac{1}{|Z - Z_1|} \int \omega(J, \theta - l_1, Z_1) \\
& \quad \times \frac{3}{T^{(4)}(\lambda)} \exp(iu(cl_1 + |Z - Z_1|)) \times \exp(iv(cl_1 - |Z - Z_1|)) d\lambda
\end{aligned}$$

where:

$$\begin{aligned}
u &= \frac{\lambda + \lambda_1^{(r)}}{2} = \frac{\lambda + f^{(r)}(\lambda)}{2} \\
v &= \frac{\lambda + \lambda_1^{(r)}}{2} = \frac{\lambda - f^{(r)}(\lambda)}{2}
\end{aligned}$$

As a consequence:

$$\begin{aligned}
v &= \lambda - \sqrt{\lambda^2 + h_r(\lambda)} \\
&= -\frac{h_r(\lambda)}{\lambda + \sqrt{\lambda^2 + h_r(\lambda)}} \\
&= -\frac{h_r(\lambda)}{u}
\end{aligned}$$

For $h_r(\lambda)$ varying slowly, we can replace $h_r(\lambda)$ by its average \bar{h}_r , and we have:

$$v = -\frac{\bar{h}_r}{u}$$

Replacing $T^{(4)}(\lambda)$ by its average $\bar{T}^{(4)}$, we find:

$$\begin{aligned}
|\Psi(\theta - l_1, Z_1)|^2 \frac{\delta\omega^{-1}(J, \theta, Z)}{\delta|\Psi(\theta - l_1, Z_1)|^2} &\simeq \sum_r \frac{i}{\pi} \frac{1}{|Z - Z_1|} \int \omega(J, \theta - l_1, Z_1) \\
&\times \frac{3}{\bar{T}^{(4)}} \exp(iu(cl_1 + |Z - Z_1|)) \times \exp\left(-i\frac{\bar{h}_r}{u}(cl_1 - |Z - Z_1|)\right) d\lambda
\end{aligned}$$

We can then apply the results of the previous paragraph for each r , and has a consequence, we obtain:

$$\begin{aligned}
|\Psi(\theta - l_1, Z_1)|^2 \frac{\delta\omega^{-1}(J, \theta, Z)}{\delta|\Psi(\theta - l_1, Z_1)|^2} &\simeq \sum_r (1 + \bar{h}_r) \frac{3}{\bar{T}^{(4)}} \omega(J, \theta - l_1, Z_1) \frac{\exp(-cl_1)}{|Z - Z_1|} \\
&\times \left(\sqrt{\frac{cl_1 - |Z - Z_1|}{cl_1 + |Z - Z_1|}} + \sqrt{\frac{cl_1 + |Z - Z_1|}{cl_1 - |Z - Z_1|}} \right) K_1 \left(\bar{h}_r \frac{(cl_1)^2 - |Z - Z_1|^2}{4} \right)
\end{aligned} \tag{130}$$

that becomes in first approximation:

$$|\Psi(\theta - l_1, Z_1)|^2 \frac{\delta\omega^{-1}(J, \theta, Z)}{\delta|\Psi(\theta - l_1, Z_1)|^2} \simeq \sum_r \frac{\exp\left(-cl_1 - \alpha_r \left((cl_1)^2 - |Z - Z_1|^2\right)\right)}{B_r} H(cl_1 - |Z - Z_1|) \omega(J, \theta - l_1, Z_1)$$

where the B_r are constant coefficients and $\alpha_r = \frac{\bar{h}_r}{4}$. As for (119), this also writes:

$$|\Psi(\theta - l_1, Z_1)|^2 \frac{\delta\omega^{-1}(J, \theta, Z)}{\delta|\Psi(\theta - l_1, Z_1)|^2} \simeq \sum_r \frac{\exp\left(-cl_1 - \alpha_r \left((cl_1)^2 - |Z - Z_1|^2\right)\right)}{D_r} H(cl_1 - |Z - Z_1|) \omega(J, \theta - l_1, Z_1) \tag{131}$$

for some constants D_r .

Appendix 2 Non local expansion for $\omega(\theta, Z)$ and propagation of signals.

We can generalize the findings of appendix 1 to calculate and estimate the successive derivatives of $\omega(J, \theta, Z)$.

In 2.1 we will compute the successive derivatives through a graphical expansion. Section 2.2 that the series expansion in the field of $\omega(J, \theta, Z)$ can be summed and expressed as an auxiliary path integral depending on the connectivity functions. This integral can be approximated through a saddle point approximation to obtain a formula for the activity $\omega(J, \theta, Z)$. The results are obtained without considering the external sources that initiate fluctuations around the background state. In section 2.3, we include the external sources to compute the expansion of $\omega(J, \theta, Z)$. Once obtained, we analyze in section 2.4 the effect of the signal propagation on $\omega(J, \theta, Z)$. In section 2.5 we extend these results to systems with multiple fields, including excitatory and inhibitory interactions.

2.1 n-th derivatives of $\omega(\theta, Z)$ and $\omega^{-1}(\theta, Z)$ at $|\Psi_0|^2$

2.1.1 General formula

Based on the results of Appendix 1, we can now compute $\omega(J, \theta, Z)$, $\omega^{-1}(J, \theta, Z)$ and their derivatives

$$\frac{\delta^n \omega(J, \theta, Z)}{\prod_{i=1}^n \delta |\Psi(\theta - l_i, Z_i)|^2}$$

and:

$$\frac{\delta^n \omega^{-1}(J, \theta, Z)}{\prod_{i=1}^n \delta |\Psi(\theta - l_i, Z_i)|^2}$$

It allows to compute the expansion of the effective action, and also to study the solutions of (97) without the locality assumption.

2.1.1.1 Series expansion for the first order derivative of $\omega(\theta, Z)$ Recall that $\omega(\theta, Z)$ is solution of (28):

$$\begin{aligned} \omega^{-1}(\theta, Z) &= G \left(J(\theta) + \frac{\kappa}{N} \int T(Z, Z_1, \theta) \frac{\omega\left(\theta - \frac{|Z-Z_1|}{c}, Z_1\right)}{\omega(\theta, Z)} \right. \\ &\quad \left. \times \left(\bar{\mathcal{G}}_0(0, Z_1) + \left| \Psi\left(\theta - \frac{|Z-Z_1|}{c}, Z_1\right) \right|^2 \right) dZ_1 \right) \end{aligned} \quad (132)$$

where:

$$T(Z, Z_1, \theta) = \langle T \rangle(Z, Z_1)$$

and where, for the sake of simplicity, the expression:

$$\left| \Psi\left(\theta - \frac{|Z-Z_1|}{c}, Z_1\right) \right|^2$$

will stand for⁴:

$$\Psi_0^\dagger(Z_1) \Psi\left(\theta - \frac{|Z-Z_1|}{c}, Z_1\right) + \Psi_0(Z_1) \Psi^\dagger\left(\theta - \frac{|Z-Z_1|}{c}, Z_1\right) + \left| \Psi\left(\theta - \frac{|Z-Z_1|}{c}, Z_1\right) \right|^2$$

To find the internal dynamics of the system we will consider $J(\theta) = J$, a constant external current, usually $J = 0$. We use a series expansion in $|\Psi(\theta^{(j)}, Z_1)|^2$ of the right hand side of (132) and write:

$$\begin{aligned} \omega(\theta^{(i)}, Z) &= \omega(\theta^{(i)}, Z)_{|\Psi|^2=0} \\ &\quad + \int \sum_{n=1}^{\infty} \left(\frac{\delta^n \omega(J, \theta, Z)}{\prod_{i=1}^n \delta |\Psi(\theta - l_i, Z_i)|^2} \right)_{|\Psi|^2=0} \prod_{i=1}^n |\Psi(\theta - l_i, Z_i)|^2 \end{aligned} \quad (133)$$

⁴See discussion after (47)

The first term (133), i.e. $\omega(\theta^{(i)}, Z)|_{|\Psi|^2=0}$, is a solution of:

$$F \left(J + \frac{\kappa}{N} \int T(Z, Z_1, \theta) \frac{\omega\left(\theta - \frac{|Z-Z_1|}{c}, Z_1\right)}{\omega(\theta, Z)} |\Psi_0(Z_1)|^2 dZ_1 \right)$$

One solution is the static frequency (74) solution of:

$$\begin{aligned} \omega(J, Z) &= F \left(J + \frac{\kappa}{N} \int T(Z, Z_1) \frac{\omega(Z_1)}{\omega(Z)} |\Psi_0(Z_1)|^2 dZ_1 \right) \\ &\equiv F[J, \omega, Z] \end{aligned}$$

but any time dependent solution for $|\Psi|^2 = 0$ is also possible. This arises for non constant current $J(\theta)$. Equation (133) is the expansion of $\omega(\theta^{(i)}, Z)$ around this solution, the dynamics depending on $|\Psi(\theta^{(j)}, Z_1)|^2$. We set:

$$\omega(\theta^{(i)}, Z)|_{|\Psi|^2=0} = \omega_0(J, Z)$$

The first derivative $\frac{\delta\omega(J, \theta, Z)}{\delta|\Psi(\theta-l_1, Z_1)|^2}$ in (133) has been computed in Appendix 1. It is given by:

$$\begin{aligned} \frac{\delta\omega^{-1}(J, \theta, Z)}{\delta|\Psi(\theta-l_1, Z_1)|^2} &= - \sum_{n=1}^{\infty} \frac{1}{\left(\bar{\mathcal{G}}_0(0, Z_1) + |\Psi(\theta-l_1, Z_1)|^2\right)} \int \omega^{-1} \left(J, \theta - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c}, Z_1 \right) \\ &\times \prod_{l=1}^n \check{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega, \Psi \right) \delta \left(l_1 - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c} \right) \prod_{l=1}^{n-1} dZ^{(l)} \end{aligned} \quad (134)$$

where:

$$\begin{aligned} &\check{T}(\theta, Z, Z_1, \omega, \Psi) \\ &= - \frac{\frac{\kappa}{N} \omega(J, \theta, Z) T(Z, Z_1, \theta) G'[J, \omega, \theta, Z, \Psi] \delta \left(l_1 - \frac{|Z-Z_1|}{c} \right) \left(|\Psi_0(Z_1)|^2 + \left| \Psi \left(\theta - \frac{|Z-Z_1|}{c}, Z_1 \right) \right|^2 \right)}{1 - \left(\int \frac{\kappa}{N} \omega \left(J, \theta - \frac{|Z-Z'|}{c}, Z' \right) \frac{\partial T(Z, Z', \theta)}{\partial \omega(J, \theta, Z)} \left| \Psi \left(\theta - \frac{|Z-Z'|}{c}, Z' \right) \right|^2 dZ' \right) G'[J, \omega, \theta, Z, \Psi]} \end{aligned} \quad (135)$$

with the convention that $Z^{(0)} = Z$ and $Z^{(n)} = Z_1$. The derivative (134) was then evaluated in Appendix 5 using combinations of K_1 functions, but for the purpose of the computation of the successive derivatives of $\omega(J, \theta, Z)$, we will work, temporarily, with the general formula (134). Equation (134) yield recursively $\frac{\delta\omega(J, \theta, Z)}{\delta|\Psi(\theta-l_1, Z_1)|^2}$ in terms of past activities. Applied to the case $|\Psi|^2 = 0$, the factor (135) simplifies:

$$\begin{aligned} \check{T}(\theta, Z, Z_1, \omega_0) &\equiv \check{T}(\theta, Z, Z_1 \omega_0, 0) \\ &= - \frac{\frac{\kappa}{N} \omega_0(J, \theta, Z) T(Z, Z_1, \theta) G'[J, \omega, \theta, Z, \Psi] |\Psi_0(Z_1)|^2}{1 - \left(\int \frac{\kappa}{N} \omega_0(J, Z') \frac{\partial T(Z, Z', \theta)}{\partial \omega(J, \theta, Z)} |\Psi_0(Z')|^2 dZ' \right) G'[J, \omega, \theta, Z, \Psi]} \end{aligned} \quad (136)$$

or in first approximation:

$$\begin{aligned} \check{T}(\theta, Z, Z_1, \omega_0, \Psi) &\equiv \check{T}(Z, Z_1, \omega_0) \\ &\simeq - \frac{\frac{\kappa}{N} T(Z, Z_1, \theta) G'[J, \omega, \theta, Z, \Psi] |\Psi_0(Z_1)|^2}{\omega_0^{-1}(J, Z)} \end{aligned} \quad (137)$$

and (134) becomes:

$$\begin{aligned}
\left(\frac{\delta \omega^{-1}(J, \theta, Z)}{\delta |\Psi(\theta - l_1, Z_1)|^2} \right)_{|\Psi|^2=0} &= - \sum_{n=1}^{\infty} \int \frac{\omega_0^{-1} \left(J, \theta - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c}, Z_1 \right)}{\tilde{\mathcal{G}}_0(0, Z_1)} \\
&\times \prod_{l=1}^n \tilde{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega_0, 0 \right) \\
&\times \delta \left(l_1 - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c} \right) \prod_{l=1}^{n-1} dZ^{(l)}
\end{aligned} \tag{138}$$

2.1.1.2 Graphical representation of the successive derivatives The n -th term in (138) can be understood graphically as a sum over the set of broken paths with n segments, each path linking $Z^{(l-1)}$ and $Z^{(l)}$ during a timespan of $\frac{|Z^{(l-1)} - Z^{(l)}|}{c}$. To each point of the segment, we associate the factor:

$$\begin{aligned}
&\tilde{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega_0, \Psi \right) \\
&\simeq \frac{\frac{\kappa}{N} \tilde{T}(Z^{(l-1)}, Z^{(l)}) G' \left[J, \omega_0, \theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)} \right] |\Psi_0(Z_l)|^2}{\omega_0^{-1} \left(J, \theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)} \right)}
\end{aligned} \tag{139}$$

Ultimately, the product of factor is multiplied by the activity at the last point:

$$\frac{\omega_0^{-1} \left(J, \theta - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c}, Z_1 \right)}{|\Psi_0(Z_1)|^2} \tag{140}$$

and by $|\Psi(\theta - l_1, Z_1)|^2$. The integrals over the points $Z^{(l)}$ and the sum over n , the length of the broken paths, yield the first order contribution to the expansion (133).

The next terms in the expansion of (133) are the derivatives $\left(\frac{\delta^n \omega^{-1}(J, \theta, Z)}{\prod_{i=1}^n \delta |\Psi(\theta - l_i, Z_i)|^2} \right)_{|\Psi|^2=0}$ which are obtained by successive derivations of (134) and (135) by $|\Psi(\theta - l_2, Z_2)|^2$ and evaluated at $|\Psi|^2 = 0$. The l_i are ordered such that $l_1 < \dots < l_n$. These derivatives are obtained by differentiating either:

$$-\omega_0^{-1} \left(J, \theta - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c}, Z_n \right)$$

or the successive factors:

$$\prod_{l=1}^n \tilde{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega, \Psi \right)$$

The first possibility amounts to write $\frac{\delta \omega(J, \theta - l_1, Z_1)}{\delta |\Psi(\theta - l_2, Z_2)|^2}$ using (134). Graphically it amounts to write broken lines from Z_1 to Z_2 and associate to each broken line the factor (139), (140) and $|\Psi(\theta - l_2, Z_2)|^2$.

The second possibility is obtained by computing for each l :

$$\frac{\delta \tilde{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega, \Psi \right)}{\delta |\Psi(\theta - l_2, Z_2)|^2} \quad (141)$$

Which can be written as:

$$\begin{aligned} & \frac{\delta \tilde{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega, \Psi \right)}{\delta |\Psi(\theta - l_2, Z_2)|^2} \\ = & \int d\Delta dZ' \frac{\delta \tilde{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega, \Psi \right)}{\delta \omega^{-1} \left(J, \theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c} - \Delta, Z' \right)} \frac{\delta \omega^{-1} \left(J, \theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c} - \Delta, Z' \right)}{\delta |\Psi(\theta - l_2, Z_2)|^2} \end{aligned}$$

This derivative can be described graphically by assigning to some point $Z^{(l)}$ of the initial line the factor:

$$\frac{\delta \tilde{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega, \Psi \right)}{\delta \omega^{-1} \left(J, \theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c} - \Delta, Z' \right)}$$

issuing a new succession of segments representing $\frac{\delta \omega^{-1} \left(J, \theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c} - \Delta, Z' \right)}{\delta |\Psi(\theta - l_2, Z_2)|^2}$ and then summing over Δ and Z' . In first approximation, we can set $\Delta = 0$ and $Z' = Z^{(l)}$, so that the factor is:

$$\left(\frac{\delta \tilde{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega, \Psi \right)}{\delta \omega^{-1} \left(J, \theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)} \right)} \right)_{|\Psi|^2=0}$$

and the new succession of segments represents $\frac{\delta \omega^{-1} \left(J, \theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)} \right)}{\delta |\Psi(\theta - l_2, Z_2)|^2}$.

More generally, differentiating successively $\hat{T}(\theta, Z, Z_1 \omega, |\Psi|^2)$, corresponds to insert the vertices:

$$\frac{\delta^k \tilde{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega, \Psi \right)}{\prod_{i=1}^k \delta \omega^{-1} \left(J, \theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c} - \Delta_l, Z_l \right)} \simeq \frac{\delta^k \left(\frac{\tilde{T}(Z^{(l-1)}, Z^{(l)}) G' [J, \omega_0, Z^{(l)}] |\Psi_0(Z_l)|^2}{\omega_0^{-1}(J, \theta, Z^{(l)})} \right)}{\delta^k \omega_0^{-1}(J, \theta, Z^{(l)})}$$

with k new segments representing $\frac{\delta \omega^{-1} \left(J, \theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c} - \Delta_l, Z_l \right)}{\delta |\Psi(\theta - l_l, Z_l)|^2}$.

Gathering the two possibilities forementioned and iterating this procedures yields a graphical representation for:

$$\left(\frac{\delta^n \omega^{-1}(J, \theta, Z)}{\prod_{i=1}^n \delta |\Psi(\theta - l_i, Z_i)|^2} \right)_{|\Psi|^2=0} \prod_{i=1}^n |\Psi(\theta - l_i, Z_i)|^2 \quad (142)$$

We associate the squared field $|\Psi(\theta - l_i, Z_i)|^2$ to each point Z_i . For $m = 1, \dots, n$, we draw m lines. At least one of them is starting from Z . These lines are composed of an arbitrary number of segments and all the points Z_i are crossed by one line. Each line ends at a point Z_i . The starting points of the lines have to branch either at Z , either at some point of an other line. There are m branching points of valence k including the starting point at Z . Apart from Z the branching points have valence $3, \dots, n-1$. To each line i of length L_i , we associate the factor:

$$\begin{aligned}
F(\text{line}_i) &= \prod_{l=1}^{L_i} \frac{\frac{\kappa}{N} T(Z^{(l-1)}, Z^{(l)}) G' \left[J, \omega_0, \theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)} \right] \bar{\mathcal{G}}_0(0, Z^{(l)})}{\omega_0^{-1} \left(J, \theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)} \right)} \\
&\quad \times \frac{-\omega_0^{-1} \left(J, \theta - \sum_{l=1}^{L_i} \frac{|Z^{(l-1)} - Z^{(l)}|}{c}, Z_i \right)}{\bar{\mathcal{G}}_0(0, Z_i)} \\
&= \prod_{l=1}^{L_i} \tilde{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega_0, \Psi \right) \frac{-\omega_0^{-1} \left(J, \theta - \sum_{l=1}^{L_i} \frac{|Z^{(l-1)} - Z^{(l)}|}{c}, Z_i \right)}{\bar{\mathcal{G}}_0(0, Z_i)}
\end{aligned} \tag{143}$$

and to each branching point $(X, \theta) = B$ of valence $k+2$ arising in the expansion, we associate the factor:

$$F((X, \theta)) = \frac{\delta^k \left(\frac{\tilde{T}(Z^{(l-1)}, Z^{(l)}) G' [J, \omega_0, Z^{(l)}] |\Psi_0(Z_l)|^2}{\omega_0^{-1}(J, \theta, Z^{(l)})} \right)}{\delta^k \omega_0^{-1}(J, \theta, Z^{(l)})} \tag{144}$$

and (142) writes:

$$\begin{aligned}
&\left(\frac{\delta^n \omega^{-1}(J, \theta, Z)}{\prod_{i=1}^n \delta |\Psi(\theta - l_i, Z_i)|^2} \right)_{|\Psi|^2=0} \prod_{i=1}^n |\Psi(\theta - l_i, Z_i)|^2 \\
&= \left(\sum_{m=1}^n \sum_{i=1}^m \sum_{(\text{line}_1, \dots, \text{line}_m)} \prod_i F(\text{line}_i) \prod_B F(B) \right) \prod_{i=1}^n |\Psi(\theta - l_i, Z_i)|^2
\end{aligned} \tag{145}$$

The integral over the branch points is implicit. The factor $F(B)$ for a branch point B is defined in (144). The graphical representation is generic. While integrating over the set of lines, the degenerate case of lines that share some segments is taken into account.

2.1.2 Approximate expression for the n -th derivatives of $\omega^{-1}(\theta, Z)$

The results of the section 5 can then be used with (145) to compute:

$$\frac{\delta^n \omega^{-1}(J, \theta, Z)}{\prod_{i=1}^n \delta |\Psi(\theta - l_i, Z_i)|^2}$$

in the approximation of the dominant contribution. To each line from a branching point $\theta - l'_j, Z'_j$ to $\theta - l_i, Z_i$ (the branching point can be one of the $\theta - l_i, Z_i$) we associate a factor of the type, as in (118):

$$\frac{\exp(-c(l_i - l'_j) - \gamma(c(l_i - l'_j) - |Z'_j - Z_i|))}{D} H(c l_1 - |Z - Z_1|)$$

The dominant contribution is obtained when the set $\{l'_j, Z'_j\}$ is equal to $\{l_j, Z_j\}$ and the product over the branching points yields a contribution whose form is:

$$\frac{\delta^n \omega^{-1}(J, \theta, Z)}{\prod_{i=1}^n \delta |\Psi(\theta - l_i, Z_i)|^2} \simeq \frac{\exp\left(-cl_n - \gamma \left(\sum_{i=1}^{n-1} \left((c(l_i - l_{i+1}))^2 - |Z_i - Z_{i+1}|^2\right)\right)\right)}{D^n} \quad (146)$$

$$\times H \left(cl_n - \sum_{i=1}^{n-1} |Z_i - Z_{i+1}| \right) \prod_{i=1}^n \frac{\omega_0^{-1}(J, \theta - l_i, Z_i)}{\bar{\mathcal{G}}_0(0, Z_i)}$$

with $Z_1 = Z$ and $l_n > \dots > l_1$ and B a constant coefficient (see (119)).

Formula (106) shows that the previous computations are also valid for the derivatives of $\omega(J, \theta, Z)$. We thus obtain the generalization of (119):

$$\frac{\delta^n \omega(J, \theta, Z)}{\prod_{i=1}^n \delta |\Psi(\theta - l_i, Z_i)|^2} \simeq \frac{\exp\left(-cl_n - \alpha \left(\sum_{i=1}^{n-1} \left((c(l_i - l_{i+1}))^2 - |Z_i - Z_{i+1}|^2\right)\right)\right)}{B^n} \quad (147)$$

$$\times H \left(cl_n - \sum_{i=1}^{n-1} |Z_i - Z_{i+1}| \right) \prod_{i=1}^n \frac{\omega_0(J, \theta - l_i, Z_i)}{\bar{\mathcal{G}}_0(0, Z_i)}$$

The only difference is the appearance of different coefficients α and B in the expression.

2.2 Series for $\omega^{-1}(\theta, Z)$

2.2.1 Reordering the graphical sum (145)

We now sum the series expansion (133):

$$\omega^{-1}(\theta^{(i)}, Z) = \omega^{-1}(\theta^{(i)}, Z)_{|\Psi|^2=0} \quad (148)$$

$$+ \int \sum_{n=1}^{\infty} \left(\frac{\delta^n \omega^{-1}(J, \theta, Z)}{\prod_{i=1}^n \delta |\Psi(\theta - l_i, Z_i)|^2} \right)_{|\Psi|^2=0} \prod_{i=1}^n |\Psi(\theta - l_i, Z_i)|^2$$

by reordering the sums in the RHS of (145).

To do so, we first compute the sum over the lines between (Z, θ) and (Z_1, θ_1) and of given length $L_i = n$ of the product of factors $\tilde{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega_0, \Psi \right)$ in $F(\text{line}_i)$ (see (143) for the definition of $F(\text{line}_i)$). This sum is computed in (138). We call the result $G_0^{(n)}((Z, \theta), (Z_1, \theta_1))$, so that:

$$G_0^{(n)}((Z, \theta), (Z_1, \theta_1)) = \int \prod_{l=1}^n \tilde{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega_0 \right)$$

$$\times \delta \left((\theta - \theta_1) - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c} \right) \prod_{l=1}^{n-1} dZ^{(l)}$$

$$= \int \prod_{l=1}^n \tilde{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega_0 \right) \delta \left((\theta^{(l)} - \theta^{(l-1)}) - \frac{|Z^{(l-1)} - Z^{(l)}|}{c} \right) \prod_{l=1}^{n-1} dZ^{(l)} d\theta_l$$

with $(Z^{(0)}, \theta^{(0)}) = (Z, \theta)$ and $(Z^{(n)}, \theta^{(n)}) = (Z_1, \theta_1)$.

Then, we sum over the length n of the lines and the factor associated to the sum of lines, written $G_0((Z, \theta), (Z_1, \theta_1))$, is:

$$G_0((Z, \theta), (Z_1, \theta_1)) = \sum_{n=1}^{\infty} \int \prod_{l=1}^n \check{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega_0 \right) \times \delta \left(\left(\theta^{(l)} - \theta^{(l-1)} \right) - \frac{|Z^{(l-1)} - Z^{(l)}|}{c} \right) \prod_{l=1}^{n-1} dZ^{(l)} d\theta_l$$

The function $G_0((Z, \theta), (Z_1, \theta_1))$ is a series expansion that can be summed:

$$G_0((Z, \theta), (Z_1, \theta_1)) = \check{T} (1 - \check{T})^{-1} ((Z, \theta), (Z_1, \theta_1)) \quad (149)$$

with:

$$\check{T} \left((Z^{(l-1)}, \theta^{(l-1)}), (Z^{(l)}, \theta^{(l)}) \right) = \check{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega_0 \right) \times \delta \left(\left(\theta^{(l)} - \theta^{(l-1)} \right) - \frac{|Z^{(l-1)} - Z^{(l)}|}{c} \right)$$

As a consequence, equation (145) can be rewritten as a sum over the branch points.:

$$\begin{aligned} & \omega^{-1} \left(\theta^{(i)}, Z \right) - \omega^{-1} \left(\theta^{(i)}, Z \right)_{|\Psi|^2=0} \\ &= \int \sum_n \left(\frac{\delta^n \omega^{-1}(J, \theta, Z)}{\prod_{i=1}^n \delta |\Psi(\theta - l_i, Z_i)|^2} \right)_{|\Psi|^2=0} \prod_{i=1}^n |\Psi(\theta - l_i, Z_i)|^2 dl_i dZ_i \\ &= \left(\sum_{m=1}^n \sum_{i=1}^m \sum_B \sum_{(\overline{line}_1, \dots, \overline{line}_m)} \prod_i G_0(\overline{line}_i) \prod_B F(B) \right) \prod_{i=1}^n |\Psi(\theta - l_i, Z_i)|^2 \end{aligned} \quad (150)$$

The sum $\sum_{(\overline{line}_1, \dots, \overline{line}_m)}$ is over the finite set of m segments connecting two branch points and respecting the constraint given above (143). If \overline{line}_i connects two branch points $((X_1, \theta_1), (X_2, \theta_2))$, then $G_0(\overline{line}_i)$ is equal to $G_0((X_1, \theta_1), (X_2, \theta_2))$. At each branch point we insert $\frac{|\Psi(\theta - l_k, Z_k)|^2}{\mathcal{G}_0(0, Z_k)}$ and for a terminal point $-\frac{\omega_0^{-1}(J, \theta - l_k, Z_k) |\Psi(\theta - l_k, Z_k)|^2}{\mathcal{G}_0(0, Z_k)}$. We will normalize $|\Psi|^2$ by $\bar{\mathcal{G}}_0$, so that $|\Psi(\theta - l_k, Z_k)|^2$ will stand for $\frac{|\Psi(\theta - l_k, Z_k)|^2}{\mathcal{G}_0(0, Z_k)}$.

Now the sums in (150) can be reordered in the following way. We consider the lines from (θ, Z) to a final point, and sum over the branch points of valence 2 crossed by these lines, that is points crossed or reached only by this line. We then sum the contributions over all these lines. For instance, if a line crosses only one branch point, the associated contribution will include two propagators $G_0 = \check{T} (1 - \check{T})^{-1}$, one between the initial point and the branch point, one between the branch point and the final point plus the factors inserted at each point. Summing over all possible branch points crossed by a line yields the factor associated to the overall sum of single lines crossing

the points Z_k :

$$\begin{aligned}
& \check{T} (1 - \check{T})^{-1} \sum_{n \geq 0} \int \prod_{l=1}^{n-1} \left\{ \int (|\Psi(\theta - l_i, Z_l)|^2 dZ_l dl) \check{T} (1 - \check{T})^{-1} \right\} |\Psi(\theta - l_n, Z_n)|^2 \frac{-\omega_0^{-1}(J, \theta - l_n, Z_n)}{\mathcal{G}_0(0, Z_n)} \\
&= \check{T} (1 - \check{T})^{-1} \frac{1}{1 - |\Psi(\theta, Z)|^2 \check{T} (1 - \check{T})^{-1}} |\Psi(\theta - l_n, Z_n)|^2 \frac{-\omega_0^{-1}(J, \theta - l_n, Z_n)}{\mathcal{G}_0(0, Z_n)} \\
&= \check{T} \frac{1}{1 - (1 + |\Psi|^2) \check{T}} |\Psi(\theta - l_n, Z_n)|^2 \frac{-\omega_0^{-1}(J, \theta - l_n, Z_n)}{\mathcal{G}_0(0, Z_n)} \tag{151}
\end{aligned}$$

with $Z_0 = X_1$ and $Z_{k+1} = X_2$ and $\prod_{l=1}^0$ is set to 1. The l_i are ranked such that: $l_1 < \dots < l_k$. We sum over all contributions of field insertions between (X_1, θ_1) and (X_2, θ_2) and integrate over the intermediate points. The factor $|\Psi|^2$ is seen as the operator multiplication by $|\Psi(\theta, Z)|^2$ at the point (θ, Z) .

The sum (151) over the single lines is the Green function of the operator $1 - (1 + |\Psi|^2) \check{T}$ with \check{T} and $-|\Psi(\theta - l_n, Z_n)|^2 \omega_0(J, \theta - l_n, Z_n)$ inserted at the starting and ending points. This quantity can be seen as a block $[(X_1, \theta_1), (X_2, \theta_2)]$.

2.2.2 Path integral formulation

The series expansion (150) for $\omega^{-1}(\theta^{(i)}, Z)$ can ultimately be rewritten as a sum over the number m of branch points (X_i, θ_i) with valence $k_i > 2$: we draw all connected graphs whose vertices are the branch points $(X_1, \theta_1) \dots (X_m, \theta_m)$. We attach k_i blocks to the vertex (X_i, θ_i) , the endpoint of one of them and the starting point of the others are fixed by the vertex. To each vertex, the factor $F((X_i, \theta_i))$ defined in (144) is associated. The extremities of the blocks that are not fixed are free and integrated over, except one of them which is equal to (Z, θ) . Then the series (61) is the sum over m and over all types of graphs with m vertices.

Note that the sum of graph can be computed without ordering in time the fields. It amounts to replace (150) by:

$$\omega^{-1}(\theta^{(i)}, Z) - \omega^{-1}(\theta^{(i)}, Z)_{|\Psi|^2=0} = \int \frac{1}{n!} \sum_n \left(\frac{\delta^n \omega^{-1}(J, \theta, Z)}{\prod_{i=1}^n \delta |\Psi(\theta - l_i, Z_i)|^2} \right)_{|\Psi|^2=0} \prod_{i=1}^n |\Psi(\theta_i, Z_i)|^2 d\theta_i dZ_i$$

As a consequence, the symmetry factor of equivalent graphs factored by $\prod_{i=1}^n |\Psi(\theta_i, Z_i)|^2$ and integrated over $\prod_{i=1}^n d\theta_i dZ_i$ is:

$$\frac{1}{n!} \frac{n!}{\prod_V k_V!}$$

where the product is over the vertices of valence k_V of the graph. The factor $n!$ comes from the exchange between the vertices $\prod_{i=1}^n |\Psi(\theta_i, Z_i)|^2$. The $k_V!$ accounts for the exchange of the k_V vertices among the same graph.

The sum of lines connected by vertices can then be computed using the Green function $\frac{1}{1 - (1 + |\Psi|^2) \check{T}}$ connecting the vertices of all possible valences.

As a consequence, the generating function for the graphs is equal to the partition function for an auxiliary complex field $F(X, \theta)$ with free Green function equal to $\frac{1}{1-(1+|\Psi|^2)\check{T}}$ and interaction terms generating the various graphs with arbitrary number of vertices. The free part of the action for $F(X, \theta)$ is thus:

$$\int F(X, \theta) \left(1 - (1 + |\Psi|^2) \check{T}\right) F^\dagger(X, \theta) d(X, \theta)$$

and the interaction terms have to induce the graphs with factor (144). The $k + 2$ valence vertex, with $k \geq 1$ is thus described by a term involving (144) and writes:

$$\begin{aligned} & \int F(Z^{(1)}, \theta^{(1)}) \frac{\delta^k \left(\check{T} \left(\theta^{(1)} - \frac{|Z^{(1)} - Z^{(2)}|}{c}, Z^{(1)}, Z^{(2)}, \omega_0 \right) \right)}{k! \prod_{l=3}^{k+2} \delta^k \omega_0^{-1}(J, \theta^{(l)}, Z^{(l)})} F^\dagger \left(Z^{(2)}, \theta^{(1)} - \frac{|Z^{(1)} - Z^{(2)}|}{c} \right) \\ & \times \prod_{l=3}^{k+2} \check{T} \left((Z^{(1)}, \theta^{(1)}), (\theta^{(l)}, Z^{(l)}) \right) \left(F^\dagger(\theta^{(l)}, Z^{(l)}) \right) \prod_{l=1}^{k+2} d(\theta^{(l)}, Z^{(l)}) \\ = & \int F(Z^{(1)}, \theta^{(1)}) \frac{\delta^k \left(\check{T} \left(\theta^{(1)} - \frac{|Z^{(1)} - Z^{(2)}|}{c}, Z^{(1)}, Z^{(2)}, \omega_0 \right) \right)}{k! \prod_{l=3}^{k+2} \delta^k \omega_0^{-1}(J, \theta^{(l)}, Z^{(l)})} F^\dagger \left(Z^{(2)}, \theta^{(1)} - \frac{|Z^{(1)} - Z^{(2)}|}{c} \right) \\ & \times \prod_{l=3}^{k+2} \check{T} \left(\theta^{(1)} - \frac{|Z^{(1)} - Z^{(l)}|}{c}, Z^{(1)}, Z^{(l)}, \omega_0 \right) F^\dagger(\theta^{(l)}, Z^{(l)}) d\theta^{(1)} \prod_{l=1}^{k+2} dZ^{(l)} \end{aligned}$$

Having found the free part of the action and the required vertices, the sum of all graphs (150) yields, for $\frac{|\Psi(J, \theta_i, Z_i)|^2}{\mathcal{G}_0(\theta, Z_i)} \rightarrow |\Psi(J, \theta_i, Z_i)|^2$:

$$\begin{aligned} & \omega_0^{-1}(J, \theta, Z) + \sum_{n=1}^{\infty} \frac{1}{n!} \frac{\int \check{T} F^\dagger(Z, \theta) \int \prod_{i=1}^n (-\omega_0^{-1}(J, \theta_i, Z_i)) |\Psi(J, \theta_i, Z_i)|^2 F(Z_i, \theta_i) d(Z_i, \theta_i) \exp(-S(F)) \mathcal{D}F}{\exp(-S(F)) \mathcal{D}F} \\ = & \omega_0^{-1}(J, \theta, Z) + \frac{\int \check{T} F^\dagger(Z, \theta) \exp\left(-S(F) - \int F(X, \theta) \omega_0^{-1}(J, \theta, Z) |\Psi(J, \theta, Z)|^2 d(X, \theta)\right) \mathcal{D}F}{\int \exp(-S(F)) \mathcal{D}F} \end{aligned} \quad (152)$$

with:

$$\begin{aligned} S(F) & = \int F(X, \theta) \left(1 - (1 + |\Psi|^2) \check{T}\right) F^\dagger(X, \theta) d(X, \theta) \\ & - \int F(Z^{(1)}, \theta^{(1)}) \sum_k \frac{\delta^k \left(\check{T} \left(\theta^{(1)} - \frac{|Z^{(1)} - Z^{(2)}|}{c}, Z^{(1)}, Z^{(2)}, \omega_0 \right) \right)}{k! \prod_{l=3}^{k+2} \delta^k \omega_0^{-1}(J, \theta^{(l)}, Z^{(l)})} F^\dagger \left(Z^{(2)}, \theta^{(1)} - \frac{|Z^{(1)} - Z^{(2)}|}{c} \right) \\ & \times \prod_{l=3}^{k+2} \check{T} \left(\theta^{(1)} - \frac{|Z^{(1)} - Z^{(l)}|}{c}, Z^{(1)}, Z^{(l)}, \omega_0 \right) F^\dagger(\theta^{(l)}, Z^{(l)}) d\theta^{(1)} \prod_{l=1}^{k+2} dZ^{(l)} \end{aligned}$$

The sum can be computed, and we have the more compact expression:

$$\begin{aligned}
S(F) &= \int F(Z, \theta) \left(1 - |\Psi|^2 \check{T}\right) F^\dagger(Z, \theta) d(Z, \theta) \\
&\quad - \int F(Z, \theta) \check{T} \left(\theta - \frac{|Z - Z^{(1)}|}{c}, Z, Z^{(1)}, \omega_0^{-1} + \check{T}F^\dagger\right) \\
&\quad \times F^\dagger\left(Z^{(1)}, \theta - \frac{|Z - Z^{(1)}|}{c}\right) dZ dZ^{(1)} d\theta
\end{aligned} \tag{153}$$

where:

$$\begin{aligned}
&\check{T} \left(\theta - \frac{|Z^{(1)} - Z|}{c}, Z^{(1)}, Z, \omega_0^{-1} + \check{T}F^\dagger\right) \\
= &\check{T} \left(\theta - \frac{|Z^{(1)} - Z|}{c}, Z^{(1)}, Z, \right. \\
&\left. \omega_0(Z, \theta) + \int \check{T} \left(\theta - \frac{|Z - Z^{(1)}|}{c}, Z^{(1)}, Z, \omega_0\right) F^\dagger\left(Z^{(1)}, \theta - \frac{|Z - Z^{(1)}|}{c}\right) dZ^{(1)}\right)
\end{aligned}$$

Integral (152) will be computed in the saddle point approximation. It is obtained by replacing F^\dagger and F with their values minimizing action $S(F)$ defined in (153). But before doing so, we will use a perturbation expansion of (152) to rewrite the source term:

$$- \int F(X, \theta) \omega_0^{-1}(J, \theta, Z) |\Psi(J, \theta, Z)|^2 d(X, \theta)$$

as a function of the stimuli:

$$\sum_i a(Z_i, \theta) |\Psi(Z_i, \theta)|^2$$

Appendix 3 Expansion for $\omega^{-1}(J, \theta, Z)$ in presence of external sources

In this appendix, we include the impact of external sources in the computation of the activity $\omega(J, \theta, Z)$. This allows then to derive the propagation of external signal along the thread. Ultimately, we generalize the results to several types of interacting cells.

3. 1 Computation of graphs expansion in stimulated state

So far, the results for activity $\omega(J, \theta, Z)$ are derived without external source. We now include these ones in the path integral to correct our previous expressions.

3.1.1 Modified expression for $\omega^{-1}(J, \theta, Z)$ in presence of external source

For given connectivity functions, we want to compute the path integral for $\Psi(\theta, Z)$ given a series of signals through time at some particular points. As explained in the text, this amounts to introduce in the path integral the factor:

$$\int \exp\left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2\right) d\theta_0$$

The term $\sum_i a(Z_i, \theta) |\Psi(Z_i, \theta)|^2$ corresponds to create and cancel some stimulation that makes the field $\Psi(Z_i, \theta)$ to deviate from the static equilibrium. The exponential factor stands for the possibility of several similar stimuli at the same point. The sum over θ ensures the repetition of the signal through some period of time. Recall that the perturbation is implicitly, tensored by:

$$\prod_{Z \neq Z_i} \delta(|\Psi(Z, \theta_0)|^2)$$

to ensure that the perturbation arises only at points Z_i .

The path integral to consider is thus:

$$\begin{aligned} & \int \exp(-S(\Psi)) \int \exp\left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2\right) d\theta_0 \\ &= \int \exp\left(\frac{1}{2}\Psi^\dagger(\theta, Z) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - \omega^{-1}\right) \Psi(\theta, Z)\right) \int \exp\left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2\right) d\theta_0 \end{aligned}$$

with ω^{-1} given by the auxiliary path integral (152):

$$\omega^{-1} = \omega_0^{-1}(J, Z) + \frac{\int \check{T}F^\dagger(Z, \theta) \exp\left(-S(F) - \int F(X, \theta) \omega_0^{-1}(J, \theta, Z) |\Psi(J, \theta, Z)|^2 d(X, \theta)\right) \mathcal{D}F}{\int \exp(-S(F)) \mathcal{D}F}$$

We start by expanding perturbatively:

$$\begin{aligned} & \int \exp\left(\frac{1}{2}\Psi^\dagger(\theta, Z) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - \omega^{-1}\right) \Psi(\theta, Z)\right) \int \exp\left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2\right) d\theta_0 \\ &= \int \exp\left(\frac{1}{2}\Psi^\dagger(\theta, Z) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - \omega_0^{-1}(J, Z)\right) \Psi(\theta, Z)\right) \\ & \quad \times \exp\left(-\frac{1}{2}\Psi^\dagger(\theta, Z) \nabla \left(\frac{\int \check{T}F^\dagger(Z, \theta) \exp\left(-S(F) - \int F(X, \theta) \omega_0^{-1}(\theta, Z) |\Psi(\theta, Z)|^2 d(X, \theta)\right) \mathcal{D}F}{\int \exp(-S(F)) \mathcal{D}F}\right) \Psi(\theta, Z)\right) \\ & \quad \times \int \exp\left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2\right) d\theta_0 \\ &= \int \exp\left(\frac{1}{2}\Psi^\dagger(\theta, Z) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - \omega_0^{-1}(J, Z)\right) \Psi(\theta, Z)\right) \\ & \quad \times \frac{1}{n!} \left(-\frac{1}{2}\Psi^\dagger(\theta, Z) \nabla \left(\frac{\int \check{T}F^\dagger(Z, \theta) \exp\left(-S(F) - \int F(X, \theta) \omega_0^{-1}(J, \theta, Z) |\Psi(\theta, Z)|^2 d(X, \theta)\right) \mathcal{D}F}{\int \exp(-S(F)) \mathcal{D}F}\right) \Psi(\theta, Z)\right)^n \\ & \quad \times \int \exp\left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2\right) d\theta_0 \end{aligned} \tag{154}$$

We then compute the graphs associated to the case $n = 1$ so that we compute the graphs

associated to:

$$\begin{aligned}
& \int \exp \left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2 \right) d\theta_0 \\
& \times \int \Psi^\dagger(\theta, Z) \nabla \left[- \frac{\int \check{T} F^\dagger(Z, \theta) \exp \left(-S(F) - \int F(X, \theta) \omega_0^{-1}(J, \theta, Z) |\Psi(J, \theta, Z)|^2 d(X, \theta) \right) \mathcal{D}F}{\int \exp(-S(F)) \mathcal{D}F} \right] \Psi(\theta, Z) \\
& = \int \exp \left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2 \right) d\theta_0 \times \int \Psi^\dagger(\theta, Z) \\
& \times \nabla \left[- \sum_{n=1}^{\infty} \frac{1}{n!} \frac{\int \check{T} F^\dagger(Z, \theta) \int \prod_{i=1}^n (-\omega_0^{-1}(J, \theta_i, Z_i)) |\Psi(J, \theta_i, Z_i)|^2 F(Z_i, \theta_i) d(Z_i, \theta_i) \exp(-S(F)) \mathcal{D}F}{\exp(-S(F)) \mathcal{D}F} \right] \Psi(\theta, Z)
\end{aligned} \tag{155}$$

To compute the contractions induced by the Wick theorem, we will use the two remarks: first, we do not contract $\Psi^\dagger(\theta, Z)$ and $\Psi(\theta, Z)$ outside the brackets in (155) with the source $\int \exp \left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2 \right) d\theta_0$ since it would imply the appearance of non connected graphs or vanishing contributions. Actually, the terms inside the brackets are evaluated at $\theta_i < \theta$ and we assume that the perturbation $\Psi(\theta, Z)$ is null before the action of the source.

Second, the loops arising from the series expansion can be neglected. Actually, we have seen that expanding

$$\begin{aligned}
S(F) & = \int F(Z, \theta) \left(1 - |\Psi|^2 \check{T} \right) F^\dagger(Z, \theta) d(Z, \theta) - \int F(Z, \theta) \check{T} \left(\theta - \frac{|Z - Z^{(1)}|}{c}, Z, Z^{(1)}, \omega_0^{-1} + \check{T} F^\dagger \right) \\
& \quad \times F^\dagger \left(Z^{(1)}, \theta - \frac{|Z - Z^{(1)}|}{c} \right) dZ dZ^{(1)} d\theta
\end{aligned}$$

in series of $|\Psi|^2$ corresponds to a sum of lines crossing $|\Psi|^2$ at some points that are integrated over. Contracting two such fields $|\Psi(Z, \theta)|^2 |\Psi(Z', \theta')|^2$ contracts two lines crossing (Z, θ) and (Z', θ') . This imposes $Z = Z'$ but also, due to the contractions:

$$\overbrace{\Psi^\dagger(\theta, Z) \Psi(\theta', Z)} \overbrace{\Psi^\dagger(\theta', Z) \Psi(\theta, Z)}$$

that $\theta' = \theta$. Actually, the first propagator imposes $\theta' < \theta$ and the second one $\theta < \theta'$. This means that the loop corresponding to the contraction involves integrals over a set whose measure is equal to 0: the integration over the set of lines forming the loop imposes that the length of these two lines are equal, but with no δ function to implement this condition.

Once these remarks made, given the presence of the term $\prod_{Z \neq Z_i} \delta(|\Psi(Z, \theta_0)|^2)$ in the path integral, the n -th term of the sum:

$$\frac{1}{n!} \frac{\int \check{T} F^\dagger(Z, \theta) \int \prod_{i=1}^n (-\omega_0^{-1}(J, \theta_i, Z_i)) |\Psi(J, \theta_i, Z_i)|^2 F(Z_i, \theta_i) d(Z_i, \theta_i) \exp(-S(F)) \mathcal{D}F}{\exp(-S(F)) \mathcal{D}F} \tag{156}$$

is contracted, by Wick theorem, with:

$$\int \frac{1}{n!} \left(\sum_i a(Z_i, \theta) |\Psi(Z_i, \theta)|^2 \right)^n d\theta \tag{157}$$

Actually, given our introductive remarks, contracting the n -th term in the sum with:

$$\int \frac{1}{n!} \left(\sum_i a(Z_i, \theta) |\Psi(Z_i, \theta)|^2 \right)^k d\theta$$

for $k < n$ induces the presence of loops that are negligible, and for $k > n$ induces the presence of disconnected graphs where the sources term are contracted with themselves. Such graphs are cancelled since the normalization of the path integral keeps only connected graphs.

To compute the contraction between (156) and (157), recall that:

$$|\Psi(\theta, Z_1)|^2$$

arising in (156) stands for:

$$\Psi_0^\dagger(Z_1) \Psi(\theta, Z_1) + \Psi_0(Z_1) \Psi^\dagger(\theta, Z_1) + |\Psi(\theta, Z_1)|^2$$

and the contractions are:

$$\overbrace{\Psi^\dagger(\theta, Z) \Psi(\theta', Z)} \rightarrow \frac{1}{\Lambda} \overbrace{\Psi^\dagger(\theta, Z) \nabla_\theta \Psi(\theta, Z)} = \frac{1}{\Lambda \Lambda_1}$$

$$\overbrace{\Psi_0^\dagger(\theta, Z) \Psi(\theta', Z)} = \overbrace{\Psi^\dagger(\theta, Z) \Psi_0(\theta', Z)} = 0$$

We normalize $\frac{1}{\Lambda \Lambda_1} \equiv \frac{1}{\Lambda}$. Considering $\theta < \theta_i$ leads to a contribution and since that due to the form of the propagator for Ψ , there is no loop, it amounts to replace the contractions $|\Psi(Z_i, \theta)|^2 |\Psi(J, \theta_{i'}, Z_{i'})|^2$ by $\frac{\delta(\theta_i - \theta_{i'}) \delta(Z_i - Z_{i'})}{\Lambda^2}$. and this leads to the expression for the contraction between (156) and (157):

$$\frac{1}{n!} \frac{\sum_{(i_1, \dots, i_n)} \int \prod_{l=1}^n \left(-\frac{\omega_0^{-1}(J, \theta, Z_{i_l})}{\Lambda^2} \right) a(Z_{i_l}, \theta) F(Z_{i_l}, \theta) \exp(-S(F)) \mathcal{D}F}{\exp(-S(F)) \mathcal{D}F} \quad (158)$$

Reintroducing $\Psi^\dagger(\theta, Z) \nabla$ on the left and $\Psi(\theta, Z)$ on the right of (158) and summing over n these contributions gives the contraction (155):

$$\begin{aligned} & \overbrace{\Psi^\dagger(\theta, Z) \nabla \left[\frac{\int \tilde{T}F^\dagger(Z, \theta) \exp\left(-S(F) - \int F(X, \theta) \omega_0^{-1}(J, \theta, Z) |\Psi(J, \theta, Z)|^2 d(X, \theta)\right) \mathcal{D}F}{\int \exp(-S(F)) \mathcal{D}F} \right]} \\ & \times \overbrace{\Psi(\theta, Z) \int \exp\left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2\right) d\theta_0} \\ \rightarrow & \int \tilde{T}F^\dagger(Z, \theta) \exp\left(-S(F) - \sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} F(Z_i, \theta)\right) \end{aligned}$$

The contractions $\Psi(J, \theta_i, Z_i) \Psi^\dagger(J, \theta'_i, Z'_i)$ in the internal lines can also be replaced by $\frac{\exp(-\Lambda_1(\theta_i - \theta'_i)) \delta(Z_i - Z'_i)}{\Lambda}$.

The same applies to the powers of:

$$\left\{ -\frac{1}{2} \Psi^\dagger(\theta, Z) \nabla \left(\frac{\int \tilde{T}F^\dagger(Z, \theta) \exp\left(-S(F) - \int F(X, \theta) \omega_0^{-1}(J, \theta, Z) |\Psi(\theta, Z)|^2 d(X, \theta)\right) \mathcal{D}F}{\int \exp(-S(F)) \mathcal{D}F} \right) \Psi(\theta, Z) \right\}^n$$

contrctd wth (157). The absence of loops allows to replace:

$$\left(\exp \left(-S(F) - \int F(X, \theta) \omega_0^{-1}(J, \theta, Z) |\Psi(\theta, Z)|^2 d(X, \theta) \right) \right)^n$$

by:

$$\left(\int \check{T} F^\dagger(Z, \theta) \exp \left(-S(F) - \sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(Z_i)}{\Lambda^2} F(Z_i, \theta) \right) \right)^n$$

As a consequence, the perturbation expansion (154) rewrites:

$$\begin{aligned} & \int \exp \left(\frac{1}{2} \Psi^\dagger(\theta, Z) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - \omega^{-1} \right) \Psi(\theta, Z) \right) \int \exp \left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2 \right) d\theta_0 \\ &= \int d\theta_0 \int \exp \left(\frac{1}{2} \Psi^\dagger(\theta, Z) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - \omega^{-1} \right) \Psi(\theta, Z) \right) \end{aligned}$$

with:

$$\omega^{-1}(J, \theta, Z) = \omega_0^{-1}(J, Z) + \frac{\int \check{T} F^\dagger(Z, \theta) \exp \left(-S(F) - \sum_i a(Z_i, \theta_0) \frac{\omega_0^{-1}(J, \theta_0, Z_i)}{\Lambda^2} F(Z_i, \theta) \right) \mathcal{D}F}{\int \exp(-S(F)) \mathcal{D}F} \quad (159)$$

and $S(F)$ obtained by replacing $|\Psi(\theta, Z)|^2$ with $\frac{1}{F}$:

$$\begin{aligned} S(F) &= \int F(Z, \theta) \left(1 - |\Psi|^2 \check{T} \right) F^\dagger(Z, \theta) d(Z, \theta) \\ &\quad - \int F(Z, \theta) \check{T} \left(\theta - \frac{|Z - Z^{(1)}|}{c}, Z, Z^{(1)}, \omega_0^{-1} + \check{T} F^\dagger \right) F^\dagger \left(Z^{(1)}, \theta - \frac{|Z - Z^{(1)}|}{c} \right) dZ dZ^{(1)} d\theta \end{aligned} \quad (160)$$

3.1.2 Saddle point approximation for activity auxiliary path integral

Integral (159) will be computed in the saddle point approximation. It is obtained by replacing F^\dagger and F with their values minimizing action $S(F)$ defined in (153). This yields the equations for $F^\dagger(Z, \theta)$ and $F(Z, \theta)$:

$$\left(\left(1 - |\Psi|^2 \check{T} \right) F^\dagger \right) (Z, \theta) - \left(\check{T}_{\omega_0^{-1} + \check{T} F^\dagger} F^\dagger \right) (Z, \theta) + \sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} \delta(Z - Z_i) = 0 \quad (161)$$

or, using (160):

$$\left(\left(1 - \frac{1}{\Lambda} \check{T} \right) F^\dagger \right) (Z, \theta) - \left(\check{T}_{\omega_0^{-1} + \check{T} F^\dagger} F^\dagger \right) (Z, \theta) + \sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} \delta(Z - Z_i) = 0 \quad (162)$$

and:

$$F(Z, \theta) = 0$$

Under the saddle point approximation, equation (159) becomes:

$$\omega^{-1}(J, \theta, Z) = \omega_0^{-1}(J, \theta, Z) + \check{T} F^\dagger(Z, \theta) \quad (163)$$

and (162) leads to write recursively:

$$F^\dagger = \frac{1}{\left(1 - |\Psi|^2 \check{T} - \check{T}_{\omega_0 + \check{T}F^\dagger}\right)} \left[- \sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} \right] \quad (164)$$

so that using (163) yields in first approximatin:

$$\omega^{-1}(J, \theta, Z) = \omega_0^{-1}(J, \theta, Z) - \check{T} \frac{1}{\left(1 - (|\Psi|^2 + 1) \check{T}\right)} \left[\sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} \right] \quad (165)$$

This will be applied to the expansion around the static case.

3.1.3 Expansion around static case

We estimate the correction $\check{T}F^\dagger(Z, \theta)$ given by (??), in the static state. We rewrite the expression of $T(Z, Z')$:

$$T(Z, Z') = \frac{\lambda\tau \exp\left(-\frac{|Z-Z'|}{\nu c}\right)}{1 + \frac{\omega'|\Psi(Z', \omega')|^2}{\omega|\Psi(Z, \omega)|^2}}$$

and $\check{T}(Z, Z')$ is equal to:

$$\check{T}(Z, Z') = -\frac{\frac{\kappa}{N}T(Z, Z_1)G'[J, \omega_0 Z]|\Psi_0(Z_1)|^2}{\omega_0^{-1}(J, Z)}$$

Given our previous choices, $F'[J, \omega_0 Z] = -\frac{b}{(\omega_0(J, Z))^2}$, so that, for b normalized to 1:

$$\check{T}(Z, Z') = \frac{\frac{\kappa}{N}T(Z, Z')|\Psi_0(Z')|^2}{\omega_0(J, Z)} = \frac{\kappa}{N} \frac{\lambda\tau \exp\left(-\frac{|Z-Z'|}{\nu c}\right) \left(|\Psi_0(Z')|^2\right)^2}{\omega_0 |\Psi_0(Z)|^2 + \omega'_0 |\Psi_0(Z')|^2}$$

We also need to estimate:

$$\begin{aligned} & \check{T}(Z, Z', \omega_0 + \check{T}F^\dagger) \\ &= \frac{\kappa}{N} \frac{\lambda\tau \exp\left(-\frac{|Z-Z'|}{\nu c}\right) \left(|\Psi_0(Z')|^2\right)^2}{(\omega_0 + \check{T}F^\dagger(Z)) |\Psi_0(Z)|^2 + (\omega'_0 + \check{T}F^\dagger(Z')) |\Psi_0(Z')|^2} \\ &= \check{T}(Z, Z', \omega_0) \\ & \quad - \frac{\lambda\tau \exp\left(-\frac{|Z-Z'|}{\nu c}\right) \left(|\Psi_0(Z')|^2\right)^2 \left(\check{T}F^\dagger(Z) |\Psi_0(Z)|^2 + \check{T}F^\dagger(Z') |\Psi_0(Z')|^2\right)}{\left(\omega_0 |\Psi_0(Z)|^2 + \omega'_0 |\Psi_0(Z')|^2\right) \left((\omega_0 + \check{T}F^\dagger(Z)) |\Psi_0(Z)|^2 + (\omega'_0 + \check{T}F^\dagger(Z')) |\Psi_0(Z')|^2\right)} \\ &= \check{T}(Z, Z', \omega_0) - \frac{\left(\check{T}F^\dagger(Z) |\Psi_0(Z)|^2 + \check{T}F^\dagger(Z') |\Psi_0(Z')|^2\right)}{\left((\omega_0 + \check{T}F^\dagger(Z)) |\Psi_0(Z)|^2 + (\omega'_0 + \check{T}F^\dagger(Z')) |\Psi_0(Z')|^2\right)} \check{T}(Z, Z', \omega_0) \end{aligned}$$

In the local approximation $Z' = Z$, this yields a series expansion:

$$\check{T}_{\omega_0 + \check{T}F^\dagger} - \check{T} \simeq \sum_{n \geq 1} \left(-\frac{\check{T}F^\dagger(Z)}{\omega_0(Z)} \right)^n \check{T} \quad (166)$$

The saddle point equation (162) is rewritten:

$$\left(\left(1 - \frac{1}{\Lambda} \check{T} \right) F^\dagger \right) (Z) - \left(\check{T}_{\omega_0 + \check{T}F^\dagger} F^\dagger \right) (Z) + \left(\sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} F(Z_i, \theta) \right) = 0$$

and this leads to:

$$\begin{aligned} \check{T}F^\dagger &= \check{T} \frac{1}{\left(1 - \frac{1}{\Lambda} \check{T} - \check{T}_{\omega_0 + \check{T}F^\dagger} \right)} \left(\sum_i -a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} F(Z_i, \theta) \right) \\ &= \check{T} \frac{1}{\left(1 - \left(1 + \frac{1}{\Lambda} \right) \check{T} - \left(\check{T}_{\omega_0 + \check{T}F^\dagger} - \check{T} \right) \right)} \left(\sum_i -a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} F(Z_i, \theta) \right) \end{aligned} \quad (167)$$

Gathering (167) and (166), leads to the recursive formula:

$$\begin{aligned} \check{T}F^\dagger &\simeq \sum_{n_1, \dots, n_2} \frac{\check{T}}{1 - \left(1 + \frac{1}{\Lambda} \right) \check{T}} \left[\left(-\frac{\check{T}F^\dagger(Z_1)}{\omega_0(Z_1)} \check{T} \right)^{n_1} \right] \frac{1}{1 - \left(1 + \frac{1}{\Lambda} \right) \check{T}} \left[\left(-\frac{\check{T}F^\dagger(Z_2)}{\omega_0(Z_2)} \check{T} \right)^{n_2} \right] \\ &\dots \frac{1}{1 - \left(1 + \frac{1}{\Lambda} \right) \check{T}} \left(\sum_i -a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} \right) \end{aligned}$$

Recursively, (??) leads to replace $\check{T}_{\omega_0 + \check{T}F^\dagger} - \check{T}$ by:

$$\left[\sum_{n_i \geq 1} \frac{\kappa}{N} \frac{\lambda \tau |\Psi_0(Z_i)|^2}{2\Lambda \omega_0} \left(-\frac{\check{T}F^\dagger(Z_i)}{\omega_0} \right)^{n_i} \right]$$

Graphically, we fix k Z_i vertices of valence n_i , $i = 1, \dots, k$ with $k \in \mathbb{N}$, $n_i \in \mathbb{N}$. Draw all graphs connected and simply connected crossing these vertices with the given valence. To each edge, associate $\frac{1}{1 - \left(1 + \frac{1}{\Lambda} \right) \check{T}}$, to each vertex, associate $\prod_1^n \frac{-\check{T}}{\omega_0(Z_i)}$. The factors associated to the edges are connected to one term of the product. The graphs are ordered in time starting from one edge. The first edge is composed with \check{T} .

3.1.4 Lowest order expansion in local approximation

A first order compact approximation of (167) can also be obtained by writing in the local approximation $Z' \simeq Z$:

$$\begin{aligned} \check{T}(Z, Z', \omega + \check{T}F^\dagger) - \check{T} &= -\frac{\kappa}{N} \frac{\left(\check{T}F^\dagger(Z) |\Psi_0(Z)|^2 + \check{T}F^\dagger(Z') |\Psi_0(Z')|^2 \right)}{\left((\omega_0 + \check{T}F^\dagger(Z)) |\Psi_0(Z)|^2 + (\omega'_0 + \check{T}F^\dagger(Z')) |\Psi_0(Z')|^2 \right)} \check{T}(Z, Z', \omega) \\ &\simeq -\frac{(\check{T}F^\dagger(Z))}{(\omega_0(Z) + \check{T}F^\dagger(Z))} \check{T}(Z, Z', \omega_0) \end{aligned} \quad (168)$$

and then the solution (167) of the saddle point equation at zeroth order leads to:

$$\check{T}F^\dagger = \check{T}_1 \left[-\sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} \right] \quad (169)$$

with:

$$\check{T}_1 = \frac{\check{T}}{\left(1 - \left(1 + \frac{1}{\Lambda} \right) \check{T} \right)}$$

That is, using (163), we recover a first approximation f (165):

$$\omega^{-1}(J, \theta, Z) = \omega_0^{-1}(J, \theta, Z) + \frac{\check{T}}{\left(1 - \left(1 + \frac{1}{\Lambda} \right) \check{T} \right)} \left[-\sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} \right] \quad (170)$$

3.1.5 Higher order terms in local approximation

We can go to higher orders and insert this formula (169) in (168):

$$\check{T}(Z, Z', \omega + \check{T}F^\dagger) - \check{T} \simeq - \frac{\check{T}_1 \left[- \sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} \right]}{\omega_0(Z) + \check{T}_1 \left[- \sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} \right]} \check{T}$$

This allows to solve the saddle point equation at the first order by writing (167):

$$\check{T}F^\dagger = \check{T} \frac{1}{\left(1 - \frac{1}{\Lambda} \check{T} - \check{T}_{\omega_0 + \check{T}F^\dagger}\right)} \left(\sum_i -a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} F(Z_i, \theta) \right) \quad (171)$$

where we define the effective scale of connectivities:

$$\frac{1}{\Lambda_1((\omega_0(J, \theta, Z_i)_i))} = \frac{1}{\Lambda} - \frac{\check{T}_1 \left[- \sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} \right]}{\omega_0(Z) + \check{T}_1 \left[- \sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} \right]}$$

Computing explictely the integrals, this leads to rewrite (163):

$$\begin{aligned} \omega^{-1}(J, \theta, Z) &= \omega_0^{-1}(J, \theta, Z) \\ &+ \int^{\theta_i} \check{T} \left(1 - \left(1 + \frac{1}{\Lambda_1((\omega_0(J, \theta, Z_i)_i))} \right) \check{T} \right)^{-1} (Z, \theta, Z_i, \theta_i) \left[- \sum_i a(Z_i, \theta_i) \frac{\omega_0(J, \theta_i, Z_i)}{\Lambda^2} d\theta_i \right] \\ &\equiv \sum_i \int K(Z, \theta, Z_i, \theta_i) \left\{ a(Z_i, \theta_i) \frac{\omega_0(J, \theta_i, Z_i)}{\Lambda^2} \right\} d\theta_i \end{aligned} \quad (172)$$

Note that we can go recursively to the next orders, by replacing $K(Z, \theta, Z_i, \theta_i)$ with:

$$K(Z, \theta, Z_i, \theta_i) \simeq -\check{T} \left(1 - \left(1 + \frac{1}{\Lambda_2((\omega_0(J, \theta, Z_i)_i))} \right) \check{T} \right)^{-1} \quad (173)$$

wher:

$$\frac{1}{\Lambda_2((\omega_0(J, \theta, Z_i)_i))} = \frac{1}{\Lambda} - \frac{\check{T}_2 \left[- \sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} \right]}{\omega_0(Z) + \check{T}_2 \left[- \sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2} \right]}$$

along with:

$$\check{T}_2 = \frac{\check{T}}{\left(1 - \left(1 + \frac{1}{\Lambda_1((\omega_0(J, \theta, Z_i)_i))} \right) \check{T} \right)}$$

and so on, the next order being obtained by replacing:

$$\left(1 + \frac{1}{\Lambda} \right) \check{T}$$

by:

$$\left(1 + \frac{1}{\Lambda_2((\omega_0(J, \theta, Z_i)_i))} \right) \check{T}$$

3.2 Estimation of the propagated signal and correction to activities.

Once the kernel $K(Z, \theta, Z_i, \theta_i)$ for signals propagation has been computed, we can study the modification in activity induced by external signals propagating along the thread.

3.2.1 Propagated signal

We first estimate the transmitted signal from the sources to the points of the thread given in (172):

$$\int K(Z, \theta, Z_i, \theta_i) \left\{ \sum_i a(Z_i, \theta_i) \frac{\omega_0^{-1}(J, \theta_i, Z_i)}{\Lambda^2} \right\} d\theta_i$$

at the lowest order. Expanding:

$$-\frac{\check{T}}{(1 - (1 + \frac{1}{\Lambda})\check{T})} \sum_i a(Z_i, \theta) \frac{\omega_0^{-1}(J, \theta, Z_i)}{\Lambda^2}$$

computes the sum of lines starting at one Z_i . The lines connects points $Z_{i_l} - Z_{i_{l+1}}$ such that $\check{T}(Z_{i_l}, Z_{i_{l+1}})$ is different from 0. Considering oscillating signals $a(Z_i, \theta) \propto \exp(i\varpi\theta)$, and assuming "quite" straight lines of length $|Z - Z_i|$ from Z to Z_i , due to the exponential factor in the transitions, leads to a phase shift proportional to $\exp\left(i\frac{\varpi|Z_i - Z_0|}{c|Z - Z_0|}\right)$ where $Z_0 \in \{Z_i\}$ is the closest point to Z . Taking into account corrections due to the length around $|Z - Z_i|$ contributes to a phase shift of $\exp\left(i\frac{\varpi(l - |Z - Z_i|)}{c}\right)$ in the integral:

$$\int K(Z, \theta, Z_i, \theta_i) \left\{ \sum_i a(Z_i, \theta_i) \frac{\omega_0^{-1}(J, \theta_i, Z_i)}{\Lambda^2} \right\} d\theta_i$$

Moreover for $K(Z, \theta, Z_i, \theta_i)$ proportional to the product between the average of T along the path and the exponential factor computed in the previous section, we obtain:

$$\begin{aligned} & \int K(Z, \theta, Z_i, \theta_i) \left\{ \sum_i a(Z_i, \theta_i) \frac{\omega_0^{-1}(J, \theta_i, Z_i)}{\Lambda^2} \right\} d\theta_i & (174) \\ & \propto \int \sum_i a(Z_i, \theta_i) \exp\left(-cl - \alpha\left((cl)^2 - |Z - Z_i|^2\right)\right) \exp\left(i\frac{\varpi l}{c}\right) dl \left(\exp\left(i\frac{\varpi(l - |Z - Z_i|)}{c}\right) \exp\left(i\frac{\varpi|Z_i - Z_{i+1}|}{c|Z - Z_i|}\right) \right) \\ & \propto \int \sum_i a(Z_i, \theta_i) \exp\left(-cl - \alpha\left((cl)^2 - |Z - Z_i|^2\right)\right) \exp\left(i\frac{\varpi(l - |Z - Z_i|)}{c}\right) \exp\left(i\frac{\varpi(|Z - Z_i|)}{c}\right) \\ & \simeq \int \sum_i a(Z_i, \theta_i) \exp\left(-cl - \alpha\left((cl)^2 - |Z - Z_i|^2\right)\right) \exp\left(i\frac{\varpi(l - |Z - Z_i|)}{c}\right) \exp\left(i\frac{\varpi(|Z - Z_0|)}{c}\right) \exp\left(i\frac{\varpi|Z_i - Z_0|}{c|Z - Z_0|}\right) \end{aligned}$$

Now, the integral:

$$Z = \int \exp\left(-cl - \alpha\left((cl)^2 - |Z - Z_i|^2\right)\right) \exp\left(i\frac{\varpi(l - |Z - Z_i|)}{c}\right) dl$$

arisng n (174) is computed by writing:

$$\begin{aligned} \left((cl)^2 - |Z - Z_i|^2\right) &= (cl - |Z - Z_i|)^2 - 2\left(|Z - Z_i|^2 - |Z - Z_i|cl\right) \\ &= (cl - |Z - Z_i|)^2 + 2|Z - Z_i|(cl - |Z - Z_i|) \end{aligned}$$

so that:

$$Z = \int \exp\left(- (cl - |Z - Z_i|) - |Z - Z_i| - \alpha \left((cl - |Z - Z_i|)^2 + 2|Z - Z_i|(cl - |Z - Z_i|) \right)\right) \exp\left(i \frac{\varpi (cl - |Z - Z_i|)}{c}\right) dl$$

and the integral becomes:

$$\begin{aligned} Z &= \frac{\exp(-|Z - Z_i|)}{c} \int \exp(-Y(1 + 2\alpha|Z - Z_i|) - \alpha Y^2) \exp\left(i \frac{\varpi Y}{c}\right) dY \\ &= \frac{\exp\left(-|Z - Z_i| + \frac{(1+2\alpha|Z-Z_i|)^2}{4\alpha} - i \frac{\varpi(1+2\alpha|Z-Z_i|)}{2c\alpha}\right)}{c} \int_{\frac{(1+2\alpha|Z-Z_i|)}{2\alpha}} \exp(-\alpha Y^2) \exp\left(i \frac{\varpi Y}{c}\right) dY \end{aligned}$$

this result can be approximated by:

$$\begin{aligned} Z &\simeq \frac{\exp(-|Z - Z_i|)}{c} \int \exp(-Y(1 + 2\alpha|Z - Z_i|)) \exp\left(i \frac{\varpi Y}{c}\right) dY \\ &\simeq \frac{\exp(-|Z - Z_i|)}{c(1 + 2\alpha|Z - Z_i| + i \frac{\varpi}{c})} = \frac{\exp(-|Z - Z_i|)}{c\sqrt{(1 + 2\alpha|Z - Z_i|)^2 + (\frac{\varpi}{c})^2}} \exp\left(-i \arctan\left(\frac{\varpi}{c(1 + 2\alpha|Z - Z_i|)}\right)\right) \end{aligned}$$

Inserting the reslt in (174) ylds th prpgtd sgnl:

$$\begin{aligned} &\int K(Z, \theta, Z_i, \theta_i) \left\{ \sum_i a(Z_i, \theta_i) \frac{\omega_0^{-1}(J, \theta_i, Z_i)}{\Lambda^2} \right\} d\theta_i \\ &\propto \sum_i a(Z_i, \theta_i) \frac{\exp(-|Z - Z_i|)}{c\sqrt{(1 + 2\alpha|Z - Z_i|)^2 + (\frac{\varpi}{c})^2}} \\ &\quad \times \exp\left(i \left(\frac{\varpi(|Z - Z_0|)}{c} - \arctan\left(\frac{\varpi}{c(1 + 2\alpha|Z - Z_i|)}\right) \right)\right) \exp\left(i \frac{\varpi|Z_i - Z_0|}{c|Z - Z_0|}\right) \end{aligned}$$

At the first order in $\frac{|Z_i - Z_0|}{|Z - Z_0|}$, this is:

$$\begin{aligned} &\int K(Z, \theta, Z_i, \theta_i) \left\{ \sum_i a(Z_i, \theta_i) \frac{\omega_0^{-1}(J, \theta_i, Z_i)}{\Lambda^2} \right\} d\theta_i \\ &\simeq \frac{\exp(-|Z - Z_0|)}{c\sqrt{(1 + 2\alpha|Z - Z_0|)^2 + (\frac{\varpi}{c})^2}} \\ &\quad \times \exp\left(i \left(\frac{\varpi(|Z - Z_0|)}{c} - \arctan\left(\frac{\varpi}{c(1 + 2\alpha|Z - Z_0|)}\right) \right)\right) \sum_i a(Z_i, \theta_i) \exp\left(i \frac{\varpi|Z_i - Z_0|}{c|Z - Z_0|}\right) \end{aligned}$$

For $a(Z_i, \theta_i)$ constant equal to a ths rdcs t:

$$\begin{aligned} &\int K(Z, \theta, Z_i, \theta_i) \left\{ \sum_i a(Z_i, \theta_i) \frac{\omega_0^{-1}(J, \theta_i, Z_i)}{\Lambda^2} \right\} d\theta_i \tag{175} \\ &\simeq \frac{a \exp(-|Z - Z_0|)}{c\sqrt{(1 + 2\alpha|Z - Z_0|)^2 + (\frac{\varpi}{c})^2}} \exp\left(i \left(\frac{\varpi(|Z - Z_0|)}{c} - \arctan\left(\frac{\varpi}{c(1 + 2\alpha|Z - Z_0|)}\right) \right)\right) \sum_i \exp\left(i \frac{\varpi|Z_i - Z_0|}{c|Z - Z_0|}\right) \end{aligned}$$

leading to interferences. For large number of points Z_i :

$$\sum_i \exp\left(i \frac{\varpi|Z_i - Z_0|}{c|Z - Z_0|}\right) \simeq 0$$

except for the maxima of interferences with magnitude:

$$\frac{a \exp(-|Z - Z_0|)}{c \sqrt{(1 + 2\alpha |Z - Z_0|)^2 + \left(\frac{\alpha}{c}\right)^2}}$$

so that (175) localizes this point.

3.2.2 Estimation of correction to activities

Recall that:

$$|\Psi(\theta, Z_1)|^2$$

stands for:

$$\Psi_0^\dagger(\theta, Z_1) \Psi(\theta, Z_1) + \Psi_0(\theta, Z_1) \Psi^\dagger(\theta, Z_1) + |\Psi(\theta, Z_1)|^2$$

where $\Psi_0(\theta, Z_1)$ is quasi static (see the remark in the text) and ultimately, we are left with the following form for the path integral over Ψ :

$$\begin{aligned} & \int \exp(-S(\Psi)) \int \exp\left(\sum_i a(Z_i, \theta_0) |\Psi(Z_i, \theta_0)|^2\right) d\theta_0 \\ \equiv & \int \exp\left(\frac{1}{2}(\Psi_0^\dagger(\theta, Z) + \Psi^\dagger(\theta, Z)) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - \left(\omega_0^{-1} - \frac{\Omega(\theta, \theta_0, Z)}{\omega_0^2(Z)}\right)\right) (\Psi_0(\theta, Z) + \Psi(\theta, Z))\right) d\theta_0 \end{aligned} \quad (176)$$

with:

$$\Omega(\theta, \theta_0, Z) = \sum_i \omega_0^2(Z) K(Z, \theta, Z_i, \theta_0) \left\{ a(Z_i, \theta_0) \frac{\omega_0^{-1}(\theta_0, Z_0)}{\Lambda^2} \right\}$$

The expression (176) includes several contributions:

First, the expansion of:

$$\frac{1}{2}(\Psi_0^\dagger(\theta, Z) + \Psi^\dagger(\theta, Z)) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - \omega_0^{-1}\right) (\Psi_0(\theta, Z) + \Psi(\theta, Z))$$

around $\Psi_0(\theta, Z)$ includes the terms:

$$\begin{aligned} & \frac{1}{2} \Psi^\dagger(\theta, Z) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - \omega_0^{-1}\right) \Psi(\theta, Z) \\ & + \frac{1}{2} \Psi_0^\dagger(\theta, Z) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - \omega_0^{-1}\right) \Psi(\theta, Z) + \frac{1}{2} (\Psi^\dagger(\theta, Z)) \nabla \left(\frac{\sigma_\theta^2}{2} \nabla - \omega_0^{-1}\right) (\Psi_0(\theta, Z)) \end{aligned}$$

The first one is the free action for $\Psi(\theta, Z)$, while the two other terms compute the modifications of the effective action due to fluctuations $\Psi(\theta, Z)$. They contribute to the effective action above the classical approximation.

The last terms:

$$\left(\Psi_0^\dagger(\theta, Z) + \Psi^\dagger(\theta, Z)\right) \nabla_\theta \left(\frac{\Omega(\theta, \theta_0, Z)}{\omega_0^2(Z)} (\Psi_0(\theta, Z) + \Psi(\theta, Z))\right)$$

encompass the corrections due to the external perturbations.

To find these corrections, we will compute the expansion of:

$$\exp\left(\int \left(\Psi_0^\dagger(\theta, Z) + \Psi^\dagger(\theta, Z)\right) \nabla_\theta \left(\frac{\Omega(\theta, \theta_0, Z)}{\omega_0^2(Z)} (\Psi_0(\theta, Z) + \Psi(\theta, Z))\right)\right)$$

in the pth ntgrl. We consider the second order expansion to find the first corrections to activities. The field contractions are obtained in the local approximation:

$$\begin{aligned}\overbrace{\Psi^\dagger(\theta, Z) \Psi(\theta', Z)} &\rightarrow \frac{1}{\Lambda} \overbrace{\Psi^\dagger(\theta, Z) \nabla_\theta \Psi(\theta, Z)} = \frac{1}{\Lambda \Lambda_1} \\ \overbrace{\Psi^\dagger(\theta, Z) \nabla_\theta \Psi(\theta', Z)} &\rightarrow \frac{1}{\Lambda} \overbrace{\Psi^\dagger(\theta, Z) \nabla_\theta \Psi(\theta, Z)} = \frac{\Lambda_1}{\Lambda \Lambda_1} = \frac{1}{\Lambda} \\ \overbrace{\Psi_0^\dagger(\theta, Z) \Psi(\theta', Z)} &= \overbrace{\Psi^\dagger(\theta, Z) \Psi_0(\theta', Z)} = 0\end{aligned}$$

The first order of the expansion has the contributions:

$$\frac{\Psi_0^\dagger(\theta, Z)}{\omega_0^2(Z)} \nabla_\theta \left(\frac{\Omega(\theta, \theta_0, Z)}{\omega_0^2(Z)} \right) \Psi_0^\dagger(\theta, Z) + \frac{\Lambda_1}{\Lambda \omega_0^2(Z)} \left(\frac{\Omega(\theta, \theta_0, Z)}{\omega_0^2(Z)} \right) + \frac{1}{\Lambda \omega_0^2(Z)} \nabla_\theta \left(\frac{\Omega(\theta, \theta_0, Z)}{\omega_0^2(Z)} \right)$$

that are equal to 0 due to the integral over θ_0 . For oscillating signals, this integral is equal to 0.

Second order in the local approximation :

$$\begin{aligned}&\left(\int \frac{\Psi_0^\dagger(\theta, Z)}{\omega_0^4(Z)} (\nabla \Omega) \Psi_0(\theta, Z) dZ \right)^2 \\ &+ \frac{2}{\omega_0^4(Z)} \left(\int \Psi_0^\dagger(\theta, Z) \nabla \Omega \Psi(\theta, Z) \int \overbrace{\Psi^\dagger(\theta', Z) \nabla \Omega \Psi_0(\theta', Z)} dZ \right) \\ &+ \frac{1}{\omega_0^4(Z)} \left(\int \Psi^\dagger(\theta, Z) \nabla \Omega \Psi(\theta, Z) \int \overbrace{\Psi^\dagger(\theta', Z) \nabla \Omega \Psi(\theta', Z)} dZ \right)\end{aligned}$$

Considering $|\Psi_0(\theta, Z)|^2 \gg \frac{1}{\Lambda}$, this leads to:

$$\begin{aligned}&\left(\int \frac{\Psi_0^\dagger(\theta, Z)}{\omega_0^4(Z)} (\nabla \Omega) \Psi_0(\theta, Z) dZ \right)^2 \\ &+ \frac{2}{\Lambda_1 \Lambda \omega_0^4(Z)} \left(\int \Psi_0^\dagger(\theta, Z) (\nabla \Omega) \nabla \Omega \Psi_0(\theta, Z) dZ \right) - \frac{2}{\Lambda \omega_0^4(Z)} \left(\int \Psi_0^\dagger(\theta, Z) \Omega \nabla \Omega \Psi_0(\theta, Z) dZ \right) \\ = &\left(\int \frac{\Psi_0^\dagger(\theta, Z)}{\omega_0^4(Z)} (\nabla \Omega) \Psi_0(\theta, Z) dZ \right)^2 \\ &+ \frac{2}{\Lambda_1 \Lambda \omega_0^4(Z)} \left(\int \left(\Psi_0^\dagger(\theta, Z) \nabla \left(\left(\int^\theta (\nabla \Omega)^2 \right) \Psi_0(\theta, Z) \right) + O(\nabla \Psi_0(\theta, Z)) \right) dZ \right) \\ &- \frac{1}{\Lambda \omega_0^4(Z)} \left(\int \left(\Psi_0^\dagger(\theta, Z) \nabla \Omega^2 \Psi_0(\theta, Z) + O(\nabla \Psi_0(\theta, Z)) \right) dZ \right) \\ \simeq &\left(\int \frac{\Psi_0^\dagger(\theta, Z)}{\omega_0^4(Z)} (\nabla \Omega) \Psi_0(\theta, Z) dZ \right)^2 + \frac{1}{\Lambda_1 \Lambda \omega_0^4(Z)} \int \left(\Psi_0^\dagger(\theta, Z) \nabla \left(2 \left(\left(\int^\theta (\nabla \Omega)^2 \right) - \Lambda_1 \Omega^2 \Psi_0(\theta, Z) \right) \right) \right) dZ\end{aligned}$$

first contribution in first prxm when integration over θ_0 :

$$B = \left(\int \frac{\Psi_0^\dagger(\theta, Z)}{\omega_0^4(Z)} \sqrt{\int (\nabla \Omega(\theta, \theta_0, Z))^2 d\theta_0} \Psi_0(\theta, Z) dZ \right)^2$$

second contribution:

$$A = \frac{1}{\Lambda_1 \Lambda \omega_0^4(Z)} \int \left(\Psi_0^\dagger(\theta, Z) \nabla \left(2 \left(\left(\int^\theta \int (\nabla \Omega(\theta, \theta_0, Z))^2 d\theta_0 \right) - \Lambda_1 \left(\int \Omega^2 d\theta_0 \right) \Psi_0(\theta, Z) \right) \right) \right) dZ \quad (177)$$

The contributions A and B obtained can be gathered in an exponential and lead in first approximation to a term:

$$\exp \left(A + B - \frac{1}{2} A^2 \right)$$

The term $B - \frac{1}{2} A^2$ is a correction to the potential.

This implies a correction to activities:

$$\omega_0^{-1}(Z) - \frac{A \omega_0^2(Z)}{\omega_0^2(Z)}$$

Using (177), this leads to a modification:

$$\omega_0(Z) \rightarrow \omega_0(Z) + A \omega_0^2(Z)$$

which is:

$$\omega_0(Z) \rightarrow \omega_0(Z) + \frac{1}{\Lambda_1 \Lambda \omega_0^2(Z)} \left(2 \left(\left(\int^\theta \int (\nabla \Omega(\theta, \theta_0, Z))^2 d\theta_0 \right) - \Lambda_1 \left(\int \Omega^2 d\theta_0 \right) \right) \right)$$

As explained above, the corrections $\Omega(\theta, \theta_0, Z)$ can be considered as nul outside the points of maximal interferences. At these points $\Omega(\theta, \theta_0, Z)$ is proportional to:

$$\bar{\Omega} = \frac{a \exp(-|Z - Z_0|)}{c \sqrt{(1 + 2\alpha |Z - Z_0|)^2 + \left(\frac{\alpha}{c}\right)^2}}$$

and the correction to drequencies are:

$$\begin{aligned} \omega_0(Z) &\rightarrow \omega_0(Z) + \frac{2 \left(\left(\int^\theta \int (\varpi \bar{\Omega})^2 d\theta_0 \right) - \Lambda_1 \left(\int \bar{\Omega}^2 d\theta_0 \right) \right)}{\Lambda_1 \Lambda \omega_0^2(Z)} \\ &\simeq \omega_0(Z) + \frac{2 \left(\left(T_\theta (\varpi \bar{\Omega})^2 \right) - \Lambda_1 (\bar{\Omega}^2) \right) T_\theta}{\Lambda_1 \Lambda \omega_0^2(Z)} \end{aligned}$$

where T_θ is the duration of the signals at time θ .

As a consequence, in presence of the signals, the states is transformed from the background activities to modification of magnitude:

$$\Delta \omega_0 = \frac{2 \left(\left(T_\theta (\varpi \bar{\Omega})^2 \right) - \Lambda_1 (\bar{\Omega}^2) \right) T_\theta}{\Lambda_1 \Lambda \omega_0^2(Z)}$$

at points of additive interferences, and 0 elsewhere. The shift may be positive or negative depending on the parameters of the system.

In the sequel, we consider $T_\theta \simeq T$.

3.3 Extension: Excitatory vs inhibitory interaction

The previous results computing the perturbations in activities may be extended straightforwardly in the case of two types of interactions. We consider n populations, each characterized by their activities $i = 1, \dots, n$. They interact positively or negatively. Each population is defined by a field Ψ_i and activities $\omega_i(\theta, Z)$. The details are given in part 1. Equations for activities are defined by:

$$\begin{aligned} \omega_i^{-1}(\theta, Z) &= G_i \left(J(\theta) + \frac{\kappa}{N} \int T(Z, Z_1) \frac{\omega_j \left(\theta - \frac{|Z-Z_1|}{c}, Z_1 \right)}{\omega_i(\theta, Z)} G^{ij} \right. \\ &\quad \left. \times W \left(\frac{\omega_i(\theta, Z)}{\omega_j \left(\theta - \frac{|Z-Z_1|}{c}, Z_1 \right)} \right) \left(\bar{G}_{0j}(0, Z_1) + \left| \Psi_j \left(\theta - \frac{|Z-Z_1|}{c}, Z_1 \right) \right|^2 \right) dZ_1 \right) \end{aligned} \quad (178)$$

For example, if $i, j = 1, 2$, a matrix g of the form:

$$G = \begin{pmatrix} 1 & -g \\ -g & 1 \end{pmatrix}$$

represents inhibitory interactions between the two populations. More generally, the matrix G is $n \times n$ with coefficients in the interval $[-1, 1]$. The sum over indices is understood for j . The resolution of (178) follows the same principle as for (132), with a vector of activities. The expansion of the first order derivative is:

$$\begin{aligned} \left(\frac{\delta \omega^{-1}(J, \theta, Z)}{\delta |\Psi(\theta - l_1, Z_1)|^2} \right)_{|\Psi|^2=0} &= - \sum_{n=1}^{\infty} \int \prod_{l=1}^n \tilde{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega_0, 0 \right) \\ &\quad \times \Omega_0 \left(J, \theta - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c}, Z_1 \right) \times \delta \left(l_1 - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c} \right) \prod_{l=1}^{n-1} dZ^{(l)} \end{aligned}$$

with ω_0 a n component vector describing a solution for $|\Psi|^2 = 0$. The matrices $\Omega_0^{-1} \left(J, \theta - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c}, Z_1 \right)$ and $D(|\Psi|^2)$ are diagonal with components $\omega_{0i}^{-1} \left(J, \theta - \sum_{l=1}^n \frac{|Z^{(l-1)} - Z^{(l)}|}{c}, Z_1 \right)$ and $|\Psi_i|^2$ respectively on the diagonal. More generally, for any expression $H(\omega_{0i}, |\Psi_i|^2)$, we define $D(H(\omega_0, |\Psi|^2))$ the diagonal matrix with components $H(\omega_{0i}, |\Psi_i|^2)$.

The quantity $\Omega(J, \theta, Z) |\Psi|^2$ is a vector with components $\omega_i(J, \theta, Z) |\Psi_i|^2$. The expressions $\left(\frac{\delta \omega^{-1}(J, \theta, Z)}{\delta |\Psi(\theta - l_1, Z_1)|^2} \right)_{|\Psi|^2=0}$ and $\tilde{T} \left(\theta - \sum_{j=1}^{l-1} \frac{|Z^{(j-1)} - Z^{(j)}|}{c}, Z^{(l-1)}, Z^{(l)}, \omega_0, 0 \right)$ are $n \times n$ matrices:

$$\left(\left(\frac{\delta \omega^{-1}(J, \theta, Z)}{\delta |\Psi(\theta - l_1, Z_1)|^2} \right)_{|\Psi|^2=0} \right)_{ij} = \left(\frac{\delta \omega_i^{-1}(J, \theta, Z)}{\delta |\Psi_j(\theta - l_1, Z_1)|^2} \right)_{|\Psi|^2=0}$$

and:

$$\begin{aligned} &\tilde{T}_{ij}(\theta, Z, Z_1, \omega, \Psi) \\ &= - \frac{G^{ij} \frac{\kappa}{N} \omega_i(J, \theta, Z) T(Z, Z_1) G'_i[J, \omega, \theta, Z, \Psi]}{1 + G^{ij} \left(\int \frac{\kappa}{N} \omega_j \left(J, \theta - \frac{|Z-Z'|}{c}, Z' \right) \left(\bar{G}_{0j}(0, Z') + \left| \Psi_j \left(\theta - \frac{|Z-Z'|}{c}, Z' \right) \right|^2 \right) T(Z, Z') dZ' \right) G'_i[J, \omega, \theta, Z, \Psi]} \end{aligned}$$

The factor associated to the sum of single lines (151) crossing the points Z_k generalizes straightforwardly and is given by:

$$\begin{aligned}
& -\check{T} (1 - \check{T})^{-1} \prod_{l=1}^{n-1} \left\{ \left(D \left(|\Psi(\theta - l_i, Z_l)|^2 \right) dZ_l dl_l \right) \check{T} (1 - \check{T})^{-1} \right\} D \left(|\Psi(\theta - l_n, Z_n)|^2 \omega_0^{-1}(J, \theta - l_n, Z_n) \right) \\
&= -\check{T} (1 - \check{T})^{-1} \frac{1}{1 - D \left(|\Psi(\theta, Z)|^2 \right) \check{T} (1 - \check{T})^{-1}} D \left(|\Psi(\theta - l_n, Z_n)|^2 \omega_0^{-1}(J, \theta - l_n, Z_n) \right) \\
&= -\check{T} \frac{1}{1 - \left(1 + D \left(|\Psi|^2 \right) \right) \check{T}} D \left(|\Psi(\theta - l_n, Z_n)|^2 \omega_0^{-1}(J, \theta - l_n, Z_n) \right) \tag{179}
\end{aligned}$$

Then, we compute $\omega^{-1}(J, \theta, Z)$ by writing the action for an auxiliary field which is the same as in appendix 6.2:

$$\begin{aligned}
S(F) &= \int F(Z, \theta) \left(1 - D \left(|\Psi|^2 \right) \check{T} \right) F^\dagger(Z, \theta) d(Z, \theta) \\
&\quad - \int F(Z, \theta) \check{T} \left(\theta - \frac{|Z^{(1)} - Z|}{c}, Z^{(1)}, Z, \omega_0 + \check{T} F^\dagger \right) F^\dagger \left(Z^{(1)}, \theta - \frac{|Z - Z^{(1)}|}{c} \right) dZ dZ^{(1)} d\theta^{(1)}
\end{aligned}$$

where $F(Z, \theta)$ is a n components vector, and $F^\dagger(Z, \theta)$ is the hermitian conjugate. The activity vector is thus given by the integral:

$$\omega^{-1}(J, \theta, Z) = \omega_0^{-1}(J, \theta, Z) + \frac{\int \check{T} F^\dagger(Z, \theta) \exp \left(-S(F) - \int F(X, \theta) D \left(|\Psi|^2 \omega_0^{-1}(J, \theta, Z) \right) d(X, \theta) \right) \mathcal{D}F}{\exp(-S(F)) \mathcal{D}F}$$

where F^\dagger satisfies in the saddle point approximation:

$$\left(\left(1 - D \left(|\Psi|^2 \right) \check{T} \right) F^\dagger \right) (Z, \theta) - \left(\check{T}_{\omega_0 + \check{T}(\omega_0 |\Psi|^2)} F^\dagger \right) (Z, \theta) - D \left(|\Psi|^2 \omega_0 \right) = 0$$

In first approximation:

$$\check{T}_{\omega_0 + \check{T}(\omega_0 |\Psi|^2)} \simeq D \left(\frac{\omega(J, \theta, Z)}{\omega(J, \theta, Z) + \check{T} \left(\left(|\Psi|^2 \omega_0 \right) \right)} \right) \check{T}_{\omega_0}$$

and the previous equation becomes:

$$\left(\left(1 - D \left(|\Psi|^2 \right) \check{T} \right) F^\dagger \right) (Z, \theta) - D \left(\frac{\omega_0}{\omega_0 + \check{T} F^\dagger} \right) \check{T} F^\dagger(Z, \theta) - D(\omega_0) |\Psi|^2 \simeq 0 \tag{180}$$

As for the basic case, under the saddle point approximation:

$$\omega(J, \theta, Z) = \omega_0(J, \theta, Z) + \check{T} F^\dagger(Z, \theta)$$

Equation (180) can be solved recursively. As in the one component field case, we find in first approximation:

$$\begin{aligned}
\check{T} F^\dagger &= A \frac{1}{1 - \left(\check{T}_{\omega_0 + A\omega_0 |\Psi|^2} - \check{T} \right) \check{T}^{-1} A} \omega_0 |\Psi|^2 \\
&\simeq A \frac{1}{1 - D \left(\frac{\omega_0}{\omega_0 + A\omega_0 |\Psi|^2} \right) A} \omega_0 |\Psi|^2 \tag{181}
\end{aligned}$$

with:

$$\begin{aligned}
A &= \frac{\check{T}}{1 - (1 + D(|\Psi|^2))\check{T}} = \frac{1}{(1 + D(|\Psi|^2))} \frac{(1 + D(|\Psi|^2))\check{T}}{1 - (1 + D(|\Psi|^2))\check{T}} \\
&= \frac{\check{T}}{1 - \check{T} - D(|\Psi|^2)\check{T}} \\
&= \frac{\check{T}}{1 - \check{T}} \sum_{n \geq 0} \left(D(|\Psi|^2) \frac{\check{T}}{1 - \check{T}} \right)^n
\end{aligned}$$

and the generalization of (151) is obtained by diagonalization of \check{T} . For two fields, we write:

$$(1 + D(|\Psi|^2))\check{T} = \begin{pmatrix} \check{T}_1 \left((1 + (|\Psi_1|^2)) \omega_{01} \right) & -g\check{T}_2 \left((1 + (|\Psi_2|^2)) \omega_{02} \right) \\ -g\check{T}_1 \left((1 + (|\Psi_1|^2)) \omega_{01} \right) & \check{T}_2 \left((1 + (|\Psi_2|^2)) \omega_{02} \right) \end{pmatrix}$$

Assuming ω_{01} and ω_{02} changing slowly in time, we have:

$$(1 + D(|\Psi|^2))\check{T} = U\check{T}_D U^{-1}$$

$$\begin{aligned}
\check{T}_D &= \begin{pmatrix} \frac{1}{2} \left(\check{T}_1 + \check{T}_2 - \sqrt{4g^2\check{T}_1\check{T}_2 + (\check{T}_1 - \check{T}_2)^2} \right) & 0 \\ 0 & \frac{1}{2} \left(\check{T}_1 + \check{T}_2 + \sqrt{4g^2\check{T}_1\check{T}_2 + (\check{T}_1 - \check{T}_2)^2} \right) \end{pmatrix} \\
U &= \begin{pmatrix} -\frac{1}{2g} \left(\check{T}_1 - \check{T}_2 - \sqrt{4g^2\check{T}_1\check{T}_2 + (\check{T}_1 - \check{T}_2)^2} \right) & \check{T}_2 \\ \check{T}_1 & \frac{1}{2g} \left(\check{T}_1 - \check{T}_2 - \sqrt{4g^2\check{T}_1\check{T}_2 + (\check{T}_1 - \check{T}_2)^2} \right) \end{pmatrix}
\end{aligned}$$

As a consequence:

$$\check{T} = UD \left(\frac{\exp(-cl_1 - \alpha(\check{T}_D) \left((cl_1)^2 - |Z - Z_1|^2 \right))}{B(\check{T}_D)} H(cl_1 - |Z - Z_1|) \right) U^{-1}$$

with $\alpha(\check{T})$ and $B(\check{T})$ are vectors. That is, given our conventions:

$$\check{T} = U \begin{pmatrix} \frac{\exp(-cl_1 - \alpha_1(\check{T}_D) \left((cl_1)^2 - |Z - Z_1|^2 \right))}{B_1(\check{T})} & 0 \\ 0 & \frac{\exp(-cl_1 - \alpha_2(\check{T}_D) \left((cl_1)^2 - |Z - Z_1|^2 \right))}{B_2(\check{T})} \end{pmatrix} U^{-1} H(cl_1 - |Z - Z_1|)$$

For connectivity functions $T_i(Z, Z_1)$ that are proportional $T_i(Z, Z_1) = C_i T_0(Z, Z_1)$, the change of basis yields the diagonalized connectivity function:

$$T_D(Z, Z_1) = \begin{pmatrix} \frac{1}{2} \left(C_1 + C_2 - \sqrt{4g_1^2 C_1 C_2 + (C_1 - C_2)^2} \right) & 0 \\ 0 & \frac{1}{2} \left(C_1 + C_2 + \sqrt{4g_1^2 C_1 C_2 + (C_1 - C_2)^2} \right) \end{pmatrix} T_0(Z, Z_1)$$

Appendix 5.2 shows that $\alpha_i(\check{T})$ and $B_i(\check{T})$ are proportional to the averages of \check{T}_{iD} and $1 + \check{T}_{iD}$, more precisely:

$$D(\alpha(\check{T})) \propto \begin{pmatrix} \frac{1}{2} \left(C_1 + C_2 - \sqrt{4g_1^2 C_1 C_2 + (C_1 - C_2)^2} \right) & 0 \\ 0 & \frac{1}{2} \left(C_1 + C_2 + \sqrt{4g_1^2 C_1 C_2 + (C_1 - C_2)^2} \right) \end{pmatrix}$$

$$D(B(\check{T})) \propto \begin{pmatrix} \frac{1}{2} \left(C_1 + C_2 - \sqrt{4g_1^2 C_1 C_2 + (C_1 - C_2)^2} \right) & 0 \\ 0 & \frac{1}{2} \left(C_1 + C_2 + \sqrt{4g_1^2 C_1 C_2 + (C_1 - C_2)^2} \right) \end{pmatrix}$$

As a consequence, by multiplication with U and U^{-1} , we find that:

$$\frac{(1 + D(|\Psi|^2)) \check{T}}{1 - (1 + D(|\Psi|^2)) \check{T}} = \frac{\exp(-cl_1 - (1 + D(\langle |\Psi|^2 \rangle)) \Phi((cl_1)^2 - |Z - Z_1|^2))}{B} H(cl_1 - |Z - Z_1|)$$

with:

$$\Phi = \begin{pmatrix} C_1 & -gC_2 \\ -gC_1 & C_2 \end{pmatrix}$$

$$B = 1 + 2\pi (1 + D(\langle |\Psi|^2 \rangle)) \Lambda$$

where the constants C_1 and C_2 are as in Appendix 5 to define \check{T}_1 and \check{T}_2 .

Then, the modification to activities to the lowest order writes:

$$\begin{aligned} \omega^{-1}(J, \theta, Z) &= \omega_0^{-1}(J, \theta, Z) + \hat{T} \Lambda^\dagger(Z, \theta) \\ &= \int K(Z, \theta, Z_i, \theta_i) \left\{ - \sum_i a(Z_i, \theta_i) \frac{D(\omega_0^{-1}(J, \theta_i, Z_i))}{\Lambda^2} \right\} d\theta_i \\ &= \int \frac{\exp(-cl_i - (1 + D(\langle |\Psi|^2 \rangle)) \Phi((cl_i)^2 - |Z - Z_i|^2))}{B} \left\{ - \sum_i a(Z_i, \theta_i) \frac{D(\omega_0^{-1}(J, \theta_i, Z_i))}{\Lambda^2} \right\} d\theta_i \end{aligned} \tag{182}$$

The phenomenon of interferences will occur, but will be mitigated by the intertwining of inhibitory and enhancing interactions that are encompassed in matrix Φ .

Remark ultimately that the previous results generalizes to a system with n interacting components, and an analogous to (182) holds. If we look to higher expansion, we consider the expansion of $A((Z, \theta), (Z_1, \theta - l_1))$:

$$A((Z, \theta), (Z_1, \theta - l_1)) \simeq D \left(\frac{1}{(1 + D(\langle |\Psi|^2 \rangle))} \right) \tag{183}$$

$$\times \left(\frac{\exp(-cl_1 - (1 + D(\langle |\Psi|^2 \rangle)) \Lambda((cl_1)^2 - |Z - Z_1|^2))}{B} H(cl_1 - |Z - Z_1|) \right)$$

As a consequence, the expansion of (181) is:

$$\begin{aligned}
\omega(Z, \theta) &= \omega_0(J, \theta, Z) + \int \sum_{k=0}^{\infty} \prod_{i=0}^{k-1} \frac{\exp\left(-cl_i - \left(1 + D\left(\langle |\Psi|^2 \rangle\right)\right) \Lambda\left((cl_i)^2 - \frac{|Z_i - Z_{i+1}|}{c}\right)\right)}{B} \\
&\quad \times D\left(\frac{\omega_0(\theta - l_i, Z_i)}{\omega_0(\theta - l_i, Z_i) + A\omega_0|\Psi|^2(\theta - l_i, Z_i)} \frac{\omega_0(J, \theta - l_k, Z_k)}{\left(1 + D\left(\langle |\Psi|^2 \rangle\right)\right)}\right) \\
&\quad \times \frac{\exp\left(-cl_k - \left(1 + D\left(\langle |\Psi|^2 \rangle\right)\right) \Lambda\left((cl_k)^2 - \frac{|Z_{k-1} - Z_k|}{c}\right)\right)}{B} |\Psi(\theta - l_k, Z_k)|^2 dZ_i dl_i \quad (184)
\end{aligned}$$

Appendix 4 Computation of Green functions

Given the definition (83) of operator O , the time-dependent version:

$$P_i\left(\left(T, \hat{T}, \theta, Z, Z', C, D\right)_i, \left(T, \hat{T}, \theta, Z, Z', C, D\right)_f\right)$$

of the transition function defined in (84)) satisfies the associated differential equation:

$$\begin{aligned}
\frac{\partial}{\partial t} P &= \nabla_T \left(\nabla_T + \frac{(T - \langle T \rangle) - (\lambda(\hat{T} - \langle \hat{T} \rangle))}{\tau\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2)} |\Psi_0(Z)|^2 \right) P \\
&\quad + \nabla_{\hat{T}} \left(\nabla_{\hat{T}} + \rho \left(C \frac{|\Psi_0(Z)|^2 h_C(\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2))}{\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2)} \right. \right. \\
&\quad \left. \left. + D \frac{|\Psi_0(Z')|^2 h_D(\omega_0(Z') + \Delta\omega_0(Z', |\Psi|^2))}{\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2)} \right) \right) (\hat{T} - \langle \hat{T} \rangle) P \quad (185)
\end{aligned}$$

This equation can be written in the matricial notation:

$$\frac{\partial}{\partial t} P = \left(\nabla^2 + (\nabla)^t \gamma \mathbf{x} \right) P \quad (186)$$

with:

$$\begin{aligned}
\gamma &= \begin{pmatrix} \frac{|\Psi_0(Z)|^2}{\tau\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2)} & -\frac{\lambda|\Psi_0(Z)|^2}{\tau\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2)} \\ 0 & \rho C \frac{|\Psi_0(Z)|^2 h_C(\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2))}{\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2)} \\ & + \rho D \frac{|\Psi_0(Z')|^2 h_D(\omega_0(Z') + \Delta\omega_0(Z', |\Psi|^2))}{\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2)} \end{pmatrix} \\
\mathbf{x} &= \begin{pmatrix} T - \langle T \rangle \\ \hat{T} - \langle \hat{T} \rangle \end{pmatrix}
\end{aligned}$$

We define the background dependent parameters:

$$\begin{aligned}
u &= \frac{|\Psi_0(Z)|^2}{\tau\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2)} \\
v &= \rho C \frac{|\Psi_0(Z)|^2 h_C(\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2))}{\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2)} + \rho D \frac{|\Psi_0(Z')|^2 h_D(\omega_0(Z') + \Delta\omega_0(Z', |\Psi|^2))}{\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2)} \\
s &= -\frac{\lambda|\Psi_0(Z)|^2}{\tau\omega_0(Z) + \Delta\omega_0(Z, |\Psi|^2)}
\end{aligned}$$

The transition functions are obtained by defining the matricial quantities $M(t) \mathbf{x}$ and $\sigma(t)$:

$$M(t) \mathbf{x} = \begin{pmatrix} e^{-tu} & s \frac{e^{-tu} - e^{-tv}}{u-v} \\ 0 & e^{-tv} \end{pmatrix} (\mathbf{T} - \langle \mathbf{T} \rangle)$$

and:

$$\begin{aligned}
\sigma(t) &= 2 \int_0^t \begin{pmatrix} e^{-2tu} + s^2 \frac{(e^{-tu} - e^{-tv})^2}{(u-v)^2} & s e^{-tv} \frac{e^{-tu} - e^{-tv}}{u-v} \\ s e^{-tv} \frac{e^{-tu} - e^{-tv}}{u-v} & e^{-2tv} \end{pmatrix} dt \\
&= - \begin{pmatrix} \frac{e^{-2tu}}{u} + s^2 \frac{\frac{e^{-2tu}}{u} - 4 \frac{e^{-t(u+v)}}{u+v} + \frac{e^{-2tv}}{v}}{(u-v)^2} & s \frac{2 \frac{e^{-t(u+v)}}{u+v} - \frac{e^{-2tv}}{v}}{u-v} \\ s \frac{2 \frac{e^{-t(u+v)}}{u+v} - \frac{e^{-2tv}}{v}}{u-v} & \frac{e^{-2tv}}{v} \end{pmatrix} \\
&= \begin{pmatrix} \frac{1-e^{-2tu}}{u} + s^2 \frac{\frac{(u-v)^2}{uv(u+v)} - \left(\frac{e^{-2tu}}{u} - 4 \frac{e^{-t(u+v)}}{u+v} + \frac{e^{-2tv}}{v} \right)}{(u-v)^2} & s \frac{\frac{v-u}{v(u+v)} - \left(2 \frac{e^{-t(u+v)}}{u+v} - \frac{e^{-2tv}}{v} \right)}{u-v} \\ s \frac{\frac{v-u}{v(u+v)} - \left(2 \frac{e^{-t(u+v)}}{u+v} - \frac{e^{-2tv}}{v} \right)}{u-v} & \frac{1-e^{-2tv}}{v} \end{pmatrix}
\end{aligned}$$

The transition between $\mathbf{T} - \langle \mathbf{T} \rangle$ and $\mathbf{T}' - \langle \mathbf{T} \rangle$ during a time t is written $G_0(\mathbf{T} - \langle \mathbf{T} \rangle, \mathbf{T}' - \langle \mathbf{T} \rangle, t)$ is obtained as the solution of (186) and is given directly by:

$$\begin{aligned}
&G_0(\mathbf{T} - \langle \mathbf{T} \rangle, \mathbf{T}' - \langle \mathbf{T} \rangle, t) \\
&= (2\pi)^{-1} (Det(\sigma(t)))^{-\frac{1}{2}} \\
&\quad \times \exp \left(-((\mathbf{T} - \langle \mathbf{T} \rangle) - M(t)(\mathbf{T}' - \langle \mathbf{T} \rangle))^t \frac{\sigma^{-1}(t)}{2} ((\mathbf{T} - \langle \mathbf{T} \rangle) - M(t)(\mathbf{T}' - \langle \mathbf{T} \rangle)) \right)
\end{aligned} \tag{187}$$

Starting from the initial background state $\mathbf{T}' = \langle \mathbf{T} \rangle_0$, as t increases, the difference between initial background state and the new one is progressively reduced, as the factor:

$$M(t)(\mathbf{T}' - \langle \mathbf{T} \rangle) = \begin{pmatrix} e^{-tu} & s \frac{e^{-tu} - e^{-tv}}{u-v} \\ 0 & e^{-tv} \end{pmatrix} (\mathbf{T}' - \langle \mathbf{T} \rangle)$$

goes to 0.

Ultimately, remark that for large t , the transition function simplifies and writes:

$$\begin{aligned}
G_0(\mathbf{T} - \langle \mathbf{T} \rangle, \mathbf{T}' - \langle \mathbf{T} \rangle) &= (2\pi)^{-1} (Det(\sigma(\infty)))^{-\frac{1}{2}} \\
&\quad \times \exp \left(-\frac{1}{2} ((\mathbf{T} - \langle \mathbf{T} \rangle))^t \sigma^{-1}(\infty) ((\mathbf{T} - \langle \mathbf{T} \rangle)) \right)
\end{aligned} \tag{188}$$

with:

$$\sigma(\infty) = \begin{pmatrix} \frac{1}{u} + \frac{s^2}{uv(u+v)} & -\frac{s}{v(u+v)} \\ -\frac{s}{v(u+v)} & \frac{1-e^{-2tv}}{v} \end{pmatrix}$$