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Mathematical model of *Ehrlichia chaffeensis* transmission dynamics in dogs

Folashade B. Augusto¹, Ramsès Djidjou-Demasse^{2,3}, and Ousmane Seydi³

¹University of Kansas, Lawrence, Kansas USA

²MIVEGEC, University of Montpellier, CNRS, IRD, Montpellier, France

³Ecole Polytechnique de Thiès, Thiès Senegal

Abstract

Ehrlichia chaffeensis is a tick-borne disease transmitted by ticks to dogs. Few studies have mathematically modeled such tick-borne disease in dogs, and none have developed models that incorporate different ticks' developmental stages (discrete variable) as well as the duration of infection (continuous variable). In this study, we develop and analyze a model that considers these two structural variables using integrated semigroups theory. We address the well-posedness of the model and investigate the existence of steady states. The model exhibits a disease-free equilibrium and an endemic equilibrium. We calculate the reproduction number (\mathcal{T}_0). We establish a necessary and sufficient condition for the bifurcation of an endemic equilibrium. Specifically, we demonstrate that a bifurcation, either backward or forward, can occur at $\mathcal{T}_0 = 1$, leading to the existence, or not, of an endemic equilibrium even when $\mathcal{T}_0 < 1$. Finally, numerical simulations are employed to illustrate these theoretical findings.

Key words: amblyomma americanum, ehrlichia chaffeensis, age-structured model, bifurcation analysis

1 Introduction

Ehrlichiosis are tick-borne diseases caused by obligate intracellular rickettsias bacteria in the genera *Ehrlichia* [11, 10, 21, 44, 48]. These bacteria are classified within the group of the α -proteobacteria, order Rickettsiales, family Anaplasmataceae, genus *Ehrlichia* [21, 23]. This genus consists of obligate intracellular Gram-negative bacteria [10, 23, 44] that mainly infect leukocytes (such as monocytes, macrophages, granulocytes and neutrophils), and endothelial cells in mammals, and salivary glands, intestinal epithelium, and hemolymph cells of ticks [1, 4, 10, 14, 19, 26, 35]. The genus *Ehrlichia* comprises of six recognized tick-transmitted species: *E. canis*, *E. muris*, *E. chaffeensis*, *E. ewingii*, *E. minasensis*, and *E. ruminantium* [21, 26], and in recent times, other *Ehrlichia* species have been reported [1, 4, 26]. Going by our current knowledge, a large number of *Ehrlichia* species might not have been described [26].

The reservoir hosts for *Ehrlichia* species include numerous wild animals, as well as some domesticated species and livestock [23]. Some of these *Ehrlichia* species affect animals including pets such as cats and dogs [23, 52], and a limited number have been known to infect humans [11, 23, 41, 44, 52, 57, 58]. Specifically, *Ehrlichia canis*, *E. chaffeensis*, *E. ewingii*, *E. muris*,

and *E. ruminantium* are members of the genus *Ehrlichia* known to naturally infect various mammalian hosts such as cats, dogs, ruminants, and mice, and are responsible for emerging zoonoses in humans [1, 4, 19, 47].

Ehrlichia are tick-borne diseases transmitted by ticks in the family *Ixodidae*. *Rhipicephalus sanguineus* (brown dog tick) and *Ixodes ricinus* are vectors for *Ehrlichia canis* [23, 48]. *E. canis* can also be transmitted by *Amblyomma cajennense*, and experimentally by *Dermacentor variabilis* (American dog tick) [23]. In North America *A. americanum* (Lone Star tick) is the primary vector for both *E. chaffeensis* and *E. ewingii* [5, 7, 23, 44]. “Outside North America, *E. chaffeensis* has been found in ticks in the genera *Amblyomma*, *Haemaphysalis*, *Dermacentor*, and *Ixodes* in Asia, in *R. sanguineus* in Cameroon, and in *A. parvum* in Argentina” [23]. *Haemaphysalis flava* and *Ixodes persulcatus* complex ticks transmits *E. muris* [23]. *E. ruminantium* is the only known *Ehrlichia* species that infects cattle and it is found on the continent of Africa and a couple of Caribbean islands [4].

Ticks life-cycle span between 2-to-3 years depending on the species [18, 37]. They go through four life stages namely egg, six-legged larva, eight-legged nymph, and adult. To survive each life stage after hatching from eggs, the ticks must take a blood meal from a host; but, most ticks will die if they are unable to find a host [18]. Ticks feed once on a host, then falls off and develops into the next stage. [This feeding pattern create pathways for diseases to be transmitted from hosts to hosts](#) [56]. *Ixodes scapularis* (black-legged tick) life cycle generally lasts two years, while the life cycle of *Amblyomma americanum* (the lone star tick) is around three years long [37]. Some species like *Rhipicephalus sanguineus* (the brown dog tick) whose primary host is the domestic dog, prefer to feed on the same host during all its life stages [18, 56]. Since *R. sanguineus* are endophilic, they are found inside houses and dog kennels [56].

Dogs are susceptible to infection with multiple *Ehrlichia* spp., including *E. chaffeensis*, *E. ewingii*, and *E. canis* [7, 11, 25, 35, 39]. In 2019, over 200,000 dogs tested positive for antibodies against *Ehrlichia* spp. within the United States out of 7,056,709 dogs tested, while over 1000 dogs tested positive out of 168,216 dogs tested in Canada [34]. According to Gettings *et al.* [34] the distribution of infected dogs follows the distribution of the related tick vectors. For instance, *Amblyomma americanum* is commonly found on dogs and people in the southeastern and southcentral United States [11]. In Beall *et al.* [11] the overall seroprevalence of *E. canis*, *E. chaffeensis*, and *E. ewingii* across the United States in 2012 was 0.8%, 2.8%, and 5.1%, respectively. The highest *E. canis* seroprevalence of 2.3% was found in Arkansas, Louisiana, Oklahoma, Tennessee, and Texas. *E. chaffeensis* seroreactivity was 6.6% in Arkansas, Kansas, Missouri, and Oklahoma (the central region), and 4.6% in Georgia, Maryland, North Carolina, South Carolina, Tennessee and Virginia (the southeast region). Seroreactivity of *E. ewingii* was highest in the central region with 14.6% value while the southeast region had a seroractivity value of 5.9%.

Ehrlichia in dogs was discovered in the 1970s when military dogs were returning from the Vietnam war. They found this disease to be extremely severe in German Shepards, Doberman Pinschers, Belgium Malinois, and Siberian Huskies. Several studies including experimental researches and serological surveys have been carried out to understand *Ehrlichiosis* transmission in canine including *Ehrlichia Chaffeensis* [9, 10, 49, 50, 57]. We only found two quantitative studies modeling *Ehrlichiosis* in human [30, 31]. Thus, in this study, we developed a mathematical model for *Amblyomma americanum* in the Great Plains and dogs infected with *Ehrlichia Chaffeensis* with the aim of understanding the quantitative properties

of the model including the asymptotic dynamics of the disease in dogs across the Plains.

The rest of the paper is organized as follows: Section 2 gives the description of the model including the interactions between the ticks and dogs; Section 3 describes the results of the study. These results include the existence and uniqueness of solutions, the disease invasion process, and the bifurcation analysis. More precisely, we show that, depending on the sign of a constant \mathcal{C}_{bif} —referred to as the bifurcation parameter— which depends on model’s parameters, a bifurcation occurs at $\mathcal{T}_0 = 1$ that is either a forward or backward bifurcation. In a forward bifurcation, which occurs when $\mathcal{C}_{\text{bif}} < 0$, there exists a unique endemic equilibrium if and only if $\mathcal{T}_0 > 1$. However, in a backward bifurcation, which occurs when $\mathcal{C}_{\text{bif}} > 0$, no endemic equilibrium exists for $\mathcal{T}_0 \ll 1$ small enough; a unique endemic equilibrium exists if $\mathcal{T}_0 > 1$ while multiple equilibria exist when $0 \ll \mathcal{T}_0 < 1$ close enough to 1. Finally in Section 4 we numerically illustrate such bifurcation results.

2 Model formulation

The transmission model of *Ehrlichia Chaffeensis* incorporates two subgroups: dogs and ticks. At any time t , the dog population is divided into susceptible $S_D(t)$, infected $i_D(t, a)$, and chronically infected $c_D(t, a)$, recovered $R_D(t)$. Here, the variable a represents the time since infection. Thus, the total number of dogs at time t is quantified by

$$N_D(t) = S_D(t) + \int_0^\infty i_D(t, a)da + \int_0^\infty c_D(t, a)da + R_D(t).$$

The ticks population is structured into several stages: eggs (E), larva (L), nymph (N), and adult (A). We denote by $\mathcal{S} = \{E, L, N, A\}$ the set of ticks stages. Let $S_{Tk}(t)$ be the number of susceptible ticks of stage $K \in \mathcal{S}$ at time t . We also denote by $i_{Tk}(t, a)$ the number of infected ticks of stage $K \in \mathcal{S} \setminus \{E\}$ at time t and which are infected since time a . The model proposed assumes that there are no infected eggs. Therefore the total number of ticks of stage $k \in \mathcal{S} \setminus \{E\}$ at time t is given by

$$N_{Tk}(t) = S_{Tk}(t) + \int_0^\infty i_{Tk}(t, a)da. \quad (2.1)$$

The dogs-ticks infection life cycle is shown in Figure 1.

Dogs’ population dynamic. At any time t , infected ticks (which are infected since time a) induce an infection within the dogs’ population through the force of infection $\lambda_T(t, a)$, such that

$$\lambda_T(t, a) = \beta_T(a) \sum_{K \in \mathcal{S} \setminus \{E\}} i_{Tk}(t, a), \quad (2.2)$$

where β_T denotes the infectivity of infected ticks. Therefore, newly infected dogs are given by $\frac{S_D(t)}{N_D(t)} \int_0^\infty \lambda_T(t, a)da$ and $\epsilon \frac{R_D(t)}{N_D(t)} \int_0^\infty \lambda_T(t, a)da$, where ϵ is constant parameter accounting for the relative disease transmission to previously recovered dogs. Note that ϵ can be considered age-dependent ($\epsilon = \epsilon(a)$) with no more difficulties in the analysis proposed here. Thus, the

dogs population dynamic is then described by the below system

$$\left\{ \begin{array}{l} \frac{dS_D(t)}{dt} = \theta_D - \frac{S_D(t)}{N_D(t)} \int_0^\infty \lambda_T(t, a) da - \mu_D S_D(t), \\ i_D(t, 0) = \frac{S_D(t) + \epsilon R_D(t)}{N_D(t)} \int_0^\infty \lambda_T(t, a) da, \\ \frac{\partial i_D(t, a)}{\partial t} + \frac{\partial i_D(t, a)}{\partial a} = -(\mu_D + \gamma(a) + \delta_D(a) + \nu_D(a)) i_D(t, a), \\ \frac{\partial c_D(t, a)}{\partial t} + \frac{\partial c_D(t, a)}{\partial a} = -(\mu_D + \delta_C(a)) c_D(t, a) \\ c_D(t, 0) = \int_0^\infty \nu_D(a) i_D(t, a) da, \\ \frac{dR_D(t)}{dt} = \int_0^\infty \gamma(a) i_D(t, a) da - \epsilon \frac{R_D(t)}{N_D(t)} \int_0^\infty \lambda_T(t, a) da - \mu_D R_D(t). \end{array} \right. \quad (2.3)$$

In the above model, susceptible dogs are recruited at rate θ_D and all dogs die naturally at rate μ_D . Infected and chronically infected dogs have a disease-induced mortality rate δ_D and δ_C . Infected dogs progress to a chronic infection at rate ν_D . Finally, only non-chronic infections are assumed to recover from the infection at rate γ .

Ticks' population dynamic. At time t , infected dogs (chronic or not) induce an infection within the ticks population through the force of infection $\lambda_D(t)$, such that

$$\lambda_D(t) = \int_0^\infty [\beta_D^1(a) i_D(t, a) + \beta_D^2(a) c_D(t, a)] da,$$

where $\beta_D^j(a)$ denotes the infectivity of infected and chronically infected dogs a -time post infection. Therefore, newly infected ticks of stage $k \in \mathcal{S} \setminus \{E\}$ are given by $\frac{S_{Tk}(t)}{N_D(t)} \lambda_D(t)$. The ticks population dynamic is then described by the system below

$$\left\{ \begin{array}{l} \frac{dS_{TE}(t)}{dt} = r_E \left(1 - \frac{S_{TE}(t)}{K} \right) N_{TA}(t) - (\alpha_E + \mu_E) S_{TE}(t), \\ \frac{dS_{TL}(t)}{dt} = \alpha_E S_{TE}(t) - \frac{S_{TL}(t)}{N_D(t)} \lambda_D(t) - (\alpha_L + \mu_L) S_{TL}(t), \\ \frac{dS_{TN}(t)}{dt} = \alpha_L S_{TL}(t) - \frac{S_{TN}(t)}{N_D(t)} \lambda_D(t) - (\alpha_N + \mu_N) S_{TN}(t), \\ \frac{dS_{TA}(t)}{dt} = \alpha_N S_{TN}(t) - \frac{S_{TA}(t)}{N_D(t)} \lambda_D(t) - \mu_A S_{TA}(t), \\ \text{and for } k \in \mathcal{S} \setminus \{E\}, \\ i_{Tk}(t, 0) = \frac{S_{Tk}(t)}{N_D(t)} \lambda_D(t), \\ \frac{\partial i_{Tk}(t, a)}{\partial t} + \frac{\partial i_{Tk}(t, a)}{\partial a} = -(\mu_k + \alpha_k) i_{Tk}(t, a) \end{array} \right. \quad (2.4)$$

with $\alpha_A = 0$. In the above system of the ticks dynamic, the eggs' production rate at time t is $r_E (1 - \frac{S_{TE}(t)}{K}) N_{TA}(t)$, where r_E is the number of eggs produced by adult ticks N_{TA} , and the parameter K is the eggs' carrying capacity. Parameters $\alpha_{k,s}$ are ticks progression rates from the eggs' to adult' stage. The death rate of ticks at each k -stage is μ_k . The notations of all variables and parameters are summarized in Table 1.

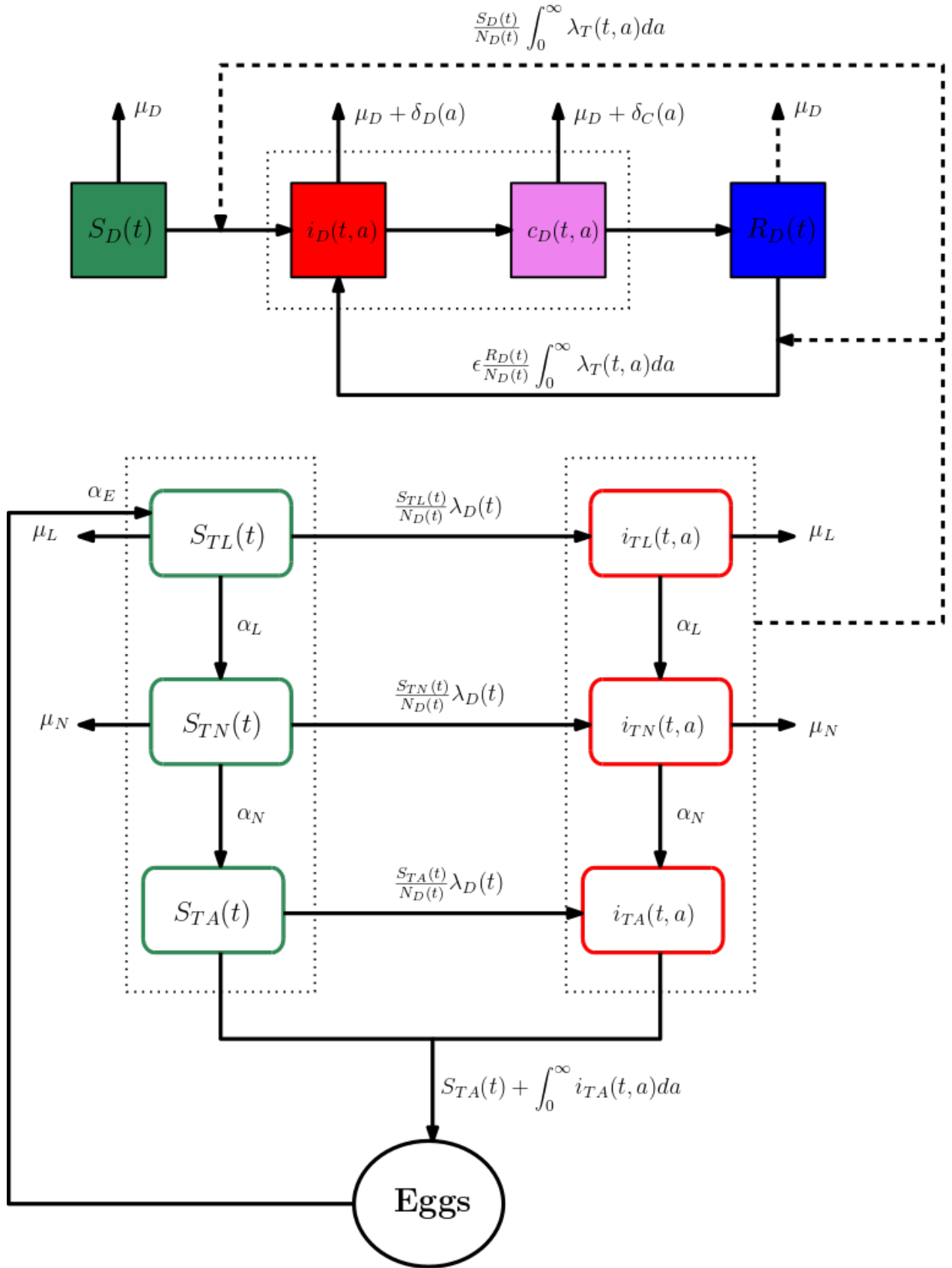


Figure 1: Flow chart of the model.

Table 1: State variables and parameters used for simulations.

Category	Description	Value (Unit) [Ref]
Variables		
t	Time	day
a	Time since infection	day
State Variables		
$S_D(t)$	Susceptible Dogs	
$i_D(t, a)$	Infected Dogs	
$c_D(t, a)$	Chronically infected Dogs	
$R_D(t)$	Recovered Dogs	
$S_{TE}(t)$	Number of Eggs	
$S_{Tk}(t)$ $k \in \{L, N, A\}$	Susceptible ticks at stage k L for Larva, N for Nymph, and A for Adult	
$i_{Tk}(t, a)$ $k \in \{L, N, A\}$	Infected ticks at stage k L for Larva, N for Nymph, and A for Adult	
Parameters		
θ_D	Birth rate of dogs	70,000 (day^{-1}) [45]
μ_D	Death rate of dogs	0.00027397 (day^{-1}) [15]
ϵ	Rate of reinfection in dogs	0.00444444 (day^{-1}) [42]
$\gamma(a)$	Rate of infected to recovered dogs	0.04761905 (day^{-1}) [38]
$\nu_D(a)$	Rate of acute to chronic infection in dogs	0.04761905 (day^{-1}) [38]
$\delta_D(a)$	Acute infection death rate in dogs	Variable (day^{-1})
$\delta_C(a)$	Chronic infection death rate in dogs	Variable (day^{-1})
$\beta_D^1(a)$	Disease transmission probability from infected dogs to ticks	Variable (No Unit)
$\beta_D^2(a)$	Disease transmission probability from chronically infected dogs to ticks	Variable (No Unit)
$\beta_T(a)$	Disease transmission probability from ticks to dogs	Variable (No Unit)
r_E	Ticks egg laying rate	Variable (day^{-1})
K	Ticks carrying capacity	1000000 (day^{-1}) [Assumed]
α_E	Maturation rate from tick eggs to larvae	0.0243902 (day^{-1}) [16]
α_L	Maturation rate from tick larvae to nymphs	0.00273973 (day^{-1}) [16]
α_N	Maturation rate from tick nymphs to adult	0.0037037 (day^{-1}) [16]
μ_E	Death rate of eggs	0.008 (day^{-1}) [6]
μ_k $k \in \{L, N, A\}$	Death rate of ticks at stage k L for Larva, N for Nymph, and A for Adult	0.003 (day^{-1}) [Assumed]

3 Main results

This section is devoted to the main results of this paper. Overall, our results are based on the following assumption on the parameters of system (2.3)-(2.4). More precisely, we assume that

Assumption 3.1.

1. The recruitment rate θ_D of susceptible dogs and the natural death rate μ_D are positive constants. The ticks' stage transition rates $\alpha_{k,s}$ and death rates $\mu_{k,s}$ are positive constants. The parameter ϵ , r_E and the carrying capacity K are positive constants;
2. Parameters $\gamma, \delta_D, \nu_D, \delta_C$ and the transmission rates β_T, β_D^k , $k = 1, 2$, belong in $L_+^\infty((0, +\infty), \mathbb{R}) \setminus \{0_{L^\infty}\}$;
3. The initial condition is such that $S_D(0) = S_{D0} > 0$, $R_D(0) = R_{D0} \geq 0$, $i_D(0, \cdot) = i_{D0} \in L_+^1((0, +\infty), \mathbb{R})$, $c_D(0, \cdot) = c_{D0} \in L_+^1((0, +\infty), \mathbb{R})$, $S_{Tk0}(0) = S_{Tk0} \geq 0$, and $i_{Tk}(0, \cdot) = i_{Tk0} \in L_+^1((0, +\infty), \mathbb{R})$ for $k \in \mathcal{S}$.

3.1 Existence and uniqueness of nonnegative solution

In this section, we state the results concerning the existence of a globally defined nonnegative solution to system (2.3)-(2.4).

In order to state our main results, we will rewrite the system in a more appropriate equivalent form. To do this, denote by \mathbf{e}_k , $k \in \{1, 2, 3\}$ and \mathbf{v}_k , $k \in \{1, 2\}$ the canonical basis of \mathbb{R}^3 and \mathbb{R}^2 , respectively. Thus, we can consider the states variables in a vector form by setting for every $t \geq 0$ and $a \geq 0$

$$\begin{cases} \mathbf{S}_T(t) = S_{TL}(t)\mathbf{e}_1 + S_{TN}(t)\mathbf{e}_2 + S_{TA}(t)\mathbf{e}_3, \\ i_T(t, a) = i_{TL}(t, a)\mathbf{e}_1 + i_{TN}(t, a)\mathbf{e}_2 + i_{TA}(t, a)\mathbf{e}_3, \\ i_D(t, a) = i_D(t, a)\mathbf{v}_1 + c_D(t, a)\mathbf{v}_2. \end{cases}$$

Moreover, we define the vector $\beta_D(a)$ of transmission rates with components $\beta_D^1(a)$ and $\beta_D^2(a)$, *i.e.*,

$$\beta_D(a) = \beta_D^1(a)\mathbf{v}_1 + \beta_D^2(a)\mathbf{v}_2,$$

and define the vector $\mathbf{1} = \mathbf{e}_1 + \mathbf{e}_2 + \mathbf{e}_3$. Let \mathbf{M} be ticks stage progression matrix from the larval stage to the adult stage, *i.e.*,

$$\mathbf{M} := \begin{pmatrix} \mu_L + \alpha_L & 0 & 0 \\ -\alpha_L & \mu_N + \alpha_N & 0 \\ 0 & -\alpha_N & \mu_A \end{pmatrix}. \quad (3.1)$$

Therefore, using the notation $\langle \cdot, \cdot \rangle$ to denotes the inner product in \mathbb{R}^2 and \mathbb{R}^3 and setting for all $a \geq 0$

$$\theta(a) := \begin{pmatrix} \gamma(a) + \delta_D(a) + \nu_D(a) & 0 \\ 0 & \delta_C(a) \end{pmatrix}, \quad (3.2)$$

Model (2.3)-(2.4) takes the following form

$$\left\{ \begin{array}{l} \frac{dS_D(t)}{dt} = \theta_D - \frac{S_D(t)}{N_D(t)} \int_0^\infty \beta_T(a) \langle \mathbf{1}, \mathbf{i}_T(t, a) \rangle da - \mu_D S_D(t), \\ \frac{\partial \mathbf{i}_D(t, a)}{\partial t} + \frac{\partial \mathbf{i}_D(t, a)}{\partial a} = -(\mu_D + \boldsymbol{\theta}(a)) \mathbf{i}_D(t, a), \\ \mathbf{i}_D(t, 0) = \frac{S_D(t) + \epsilon R_D(t)}{N_D(t)} \int_0^\infty \beta_T(a) \langle \mathbf{1}, \mathbf{i}_T(t, a) \rangle da \mathbf{v}_1 \\ \quad + \int_0^\infty \nu_D(a) \langle \mathbf{v}_1, \mathbf{i}_D(t, a) \rangle da \mathbf{v}_2, \\ \frac{dR_D(t)}{dt} = \int_0^\infty \gamma(a) \langle \mathbf{v}_1, \mathbf{i}_D(t, a) \rangle da - \epsilon \frac{R_D(t)}{N_D(t)} \int_0^\infty \beta_T(a) \langle \mathbf{1}, \mathbf{i}_T(t, a) \rangle da - \mu_D R_D(t), \end{array} \right. \quad (3.3)$$

and

$$\left\{ \begin{array}{l} \frac{dS_{TE}(t)}{dt} = r_E \left(1 - \frac{S_{TE}(t)}{K} \right) \left(\langle \mathbf{S}_T(t), \mathbf{e}_3 \rangle + \int_0^\infty \langle \mathbf{i}_T(t, a), \mathbf{e}_3 \rangle da \right) - (\alpha_E + \mu_E) S_{TE}(t), \\ \frac{d\mathbf{S}_T(t)}{dt} = \alpha_E S_{TE}(t) \mathbf{e}_1 - \mathbf{M} \mathbf{S}_T(t) - \frac{\mathbf{S}_T(t)}{N_D(t)} \int_0^\infty \langle \boldsymbol{\beta}_D(a), \mathbf{i}_D(t, a) \rangle da, \\ \frac{\partial \mathbf{i}_T(t, a)}{\partial t} + \frac{\partial \mathbf{i}_T(t, a)}{\partial a} = -\mathbf{M} \mathbf{i}_T(t, a), \\ \mathbf{i}_T(t, 0) = \frac{\mathbf{S}_T(t)}{N_D(t)} \int_0^\infty \langle \boldsymbol{\beta}_D(a), \mathbf{i}_D(t, a) \rangle da, \end{array} \right. \quad (3.4)$$

subject to the initial condition $S_D(0) = S_{D0} > 0$, $\mathbf{i}_D(0, \cdot) = \mathbf{i}_{D0} \in L_+^1((0, +\infty), \mathbb{R}^2)$, $R_D(0) = R_{D0} \in \mathbb{R}_+$, $S_{TE}(0) = S_{TE0} \in \mathbb{R}_+$, $\mathbf{i}_D(0, \cdot) = \mathbf{i}_{D0} \in L_+^1((0, +\infty), \mathbb{R}^2)$, $\mathbf{S}_T(0) = \mathbf{S}_{T0} \in \mathbb{R}_+^3$, and $\mathbf{i}_T(0, \cdot) = \mathbf{i}_{T0} \in L_+^1((0, +\infty), \mathbb{R}^3)$. The following result then concerns the existence and uniqueness of nonnegative solutions to (3.3)-(3.4).

Theorem 3.2. *Let Assumption 3.1 be satisfied. Then there exists a unique continuous globally defined integrated solution to (3.3)-(3.4). Moreover, if we set*

$$\boldsymbol{\Pi}(a, \tau) := e^{-\int_\tau^a (\mu_D + \boldsymbol{\theta}(l)) dl}, \quad \forall a \geq \tau \geq 0. \quad (3.5)$$

then the solution satisfies, for all $t \geq 0$ and $a \geq 0$,

$$\left\{ \begin{array}{l} \frac{dS_D(t)}{dt} = \theta_D - \frac{S_D(t)}{N_D(t)} \int_0^\infty \beta_T(a) \langle \mathbf{1}, \mathbf{i}_T(t, a) \rangle da - \mu_D S_D(t), \\ \frac{dR_D(t)}{dt} = \int_0^\infty \gamma(a) \mathbf{i}_D(t, a) da - \epsilon \frac{R_D(t)}{N_D(t)} \int_0^\infty \beta_T(a) \langle \mathbf{1}, \mathbf{i}_T(t, a) \rangle da - \mu_D R_D(t), \\ \frac{dS_{TE}(t)}{dt} = r_E \left(1 - \frac{S_{TE}(t)}{K} \right) \left(\langle \mathbf{S}_T(t), \mathbf{e}_3 \rangle + \int_0^\infty \langle \mathbf{i}_T(t, a), \mathbf{e}_3 \rangle da \right) - (\alpha_E + \mu_E) S_{TE}(t), \\ \frac{d\mathbf{S}_T(t)}{dt} = \alpha_E S_{TE}(t) \mathbf{e}_1 - \mathbf{M} \mathbf{S}_T(t) - \frac{\mathbf{S}_T(t)}{N_D(t)} \int_0^\infty \langle \boldsymbol{\beta}_D(a), \mathbf{i}_D(t, a) \rangle da, \end{array} \right.$$

$$\mathbf{i}_D(t, a) = \left\{ \begin{array}{l} \boldsymbol{\Pi}(a, a-t) \mathbf{i}_{D0}(a-t), \quad \text{if } a \geq t \\ \frac{S_D(t-a) + \epsilon R_D(t-a)}{N_D(t-a)} \int_0^\infty \beta_T(a) \langle \mathbf{1}, \mathbf{i}_T(t-a, \tau) \rangle d\tau \boldsymbol{\Pi}(a, 0) \mathbf{v}_1 \\ \quad + \int_0^\infty \nu_D(\tau) \langle \mathbf{v}_1, \mathbf{i}_D(t-a, \tau) \rangle d\tau \boldsymbol{\Pi}(a, 0) \mathbf{v}_2, \quad \text{if } a < t \end{array} \right.$$

and

$$\mathbf{i}_T(t, a) = \begin{cases} e^{-\mathbf{M}t} \mathbf{i}_{T0}(a - t) & \text{if } a \geq t \\ e^{-\mathbf{M}a} \frac{\mathbf{S}_T(t - a)}{N_D(t - a)} \int_0^\infty \langle \beta_D(\tau), \mathbf{i}_D(t - a, \tau) \rangle d\tau & \text{if } a < t. \end{cases}$$

Moreover, the total population of Dogs, $N_D(t)$, at time t is the unique solution to

$$\begin{cases} \frac{dN_D(t)}{dt} = \theta_D - \mu_D N_D(t) - \int_0^\infty \delta_D(a) i_D(t, a) da - \int_0^\infty \delta_C(a) c_D(t, a) da, & t > 0 \\ N_D(0) = S_{TE0} + S_{TL0} + S_{TN0} + S_{TA0} + \int_0^\infty [i_{TL0}(a) + i_{TN0}(a) + i_{TA0}(a)] da. \end{cases} \quad (3.6)$$

Proof. The existence and positiveness of solutions of system (2.3)-(2.4) can be addressed using an integrated semigroup approach and Volterra integral formulation. More precisely, a similar approach as in [51] can be applied for detailed proof of Theorem 3.2. However, here we give a brief sketch of such approach. For all $t \in \mathbb{R}$, let us set

$$u(t) = (S_D(t), R_D(t), 0_{\mathbb{R}^2}, \mathbf{i}_D(t, \cdot), S_{TE}(t), \mathbf{S}_T(t), 0_{\mathbb{R}^3}, \mathbf{i}_T(t, \cdot)) \in \mathcal{Y},$$

where \mathcal{Y} is the space

$$\mathcal{Y} = \mathbb{R} \times \mathbb{R} \times \mathbb{R}^2 \times L^1((0, \infty), \mathbb{R}^2) \times \mathbb{R}^3 \times \mathbb{R}^3 \times \mathbb{R}^3 \times L^1((0, \infty), \mathbb{R}^3).$$

Such a Banach space \mathcal{Y} is endowed with the usual product norm $\|\cdot\|_{\mathcal{Y}}$.

Let $\mathcal{M} : D(\mathcal{M}) \subset \mathcal{Y} \rightarrow \mathcal{Y}$ the linear operator defined by

$$D(\mathcal{M}) = \mathbb{R} \times \mathbb{R} \times \{0_{\mathbb{R}^2}\} \times W^{1,1}((0, \infty), \mathbb{R}^2) \times \mathbb{R}^3 \times \mathbb{R}^3 \times \{0_{\mathbb{R}^3}\} \times W^{1,1}((0, \infty), \mathbb{R}^3),$$

and

$$\mathcal{M} \begin{pmatrix} S_D \\ R_D \\ 0_{\mathbb{R}^2} \\ \mathbf{i}_D(\cdot) \\ S_{TE} \\ \mathbf{S}_T \\ 0_{\mathbb{R}^3} \\ \mathbf{i}_T(\cdot) \end{pmatrix} = \begin{pmatrix} -\mu_D S_D \\ -\mu_D R_D \\ -\mathbf{i}_D(0) \\ -\mathbf{i}'_D - (\mu_D + \boldsymbol{\theta}) \mathbf{i}_D \\ -(\alpha_E + \mu_E) S_{TE} \\ -\mathbf{M} \mathbf{S}_T \\ -\mathbf{i}_T(0) \\ -\mathbf{i}'_T - \mathbf{M} \mathbf{i}_T \end{pmatrix},$$

as well as the map $\mathcal{F} : \mathcal{Y} \rightarrow \mathcal{Y}$ such that

$$\mathcal{F} \begin{pmatrix} S_D \\ R_D \\ 0_{\mathbb{R}^2} \\ \mathbf{i}_D(\cdot) \\ S_{TE} \\ \mathbf{S}_T \\ 0_{\mathbb{R}^3} \\ \mathbf{i}_T(\cdot) \end{pmatrix} = \begin{pmatrix} \theta_D - \frac{S_D}{N_D} \int_0^\infty \beta_T(a) \langle \mathbf{1}, \mathbf{i}_T(a) \rangle da \\ \frac{S_D + \epsilon R_D}{N_D} \int_0^\infty \gamma(a) \langle \mathbf{v}_1, \mathbf{i}_D(a) \rangle da - \epsilon \frac{R_D}{N_D} \int_0^\infty \beta_T(a) \langle \mathbf{1}, \mathbf{i}_T(a) \rangle da \\ \int_0^\infty \beta_T(a) \langle \mathbf{1}, \mathbf{i}_T(a) \rangle da \mathbf{v}_1 + \int_0^\infty \nu_D(a) \langle \mathbf{v}_1, \mathbf{i}_D(a) \rangle da \mathbf{v}_2 \\ 0 \\ r_E \left(1 - \frac{S_{TE}}{K} \right) \left(\langle \mathbf{S}_T, \mathbf{e}_3 \rangle + \int_0^\infty \langle \mathbf{i}_T(a), \mathbf{e}_3 \rangle da \right) \\ \alpha_E S_{TE} \mathbf{e}_1 - \frac{S_T}{N_D} \int_0^\infty \langle \beta_D(a), \mathbf{i}_D(a) \rangle da \\ \frac{S_T}{N_D} \int_0^\infty \langle \beta_D(a), \mathbf{i}_D(a) \rangle da \\ 0 \end{pmatrix}.$$

Observe that the nonlinear map \mathcal{F} is not well defined on $\overline{D(\mathcal{M})}$ due to the term N_D and is then not locally Lipschitz continuous. Furthermore, for any $\zeta > 0$, let us introduce the space

$$\mathcal{Y}_\zeta = \{u \in \overline{D(\mathcal{M})} : \kappa(u) \geq \zeta\} \subset \overline{D(\mathcal{M})},$$

where $\kappa : \mathcal{Y} \rightarrow \mathcal{Y}$ is the operator defined by

$$\kappa(u) = S_D + \int_0^\infty i_D(a) da + \int_0^\infty c_D(a) da + R_D.$$

We can now define the nonlinear operator $F_\zeta : \mathcal{Y}_\zeta \rightarrow \mathcal{Y}$ by $F_\zeta \equiv F$. Therefore, system (3.3)-(3.4) can be rewritten as the following non-densely defined abstract Cauchy problem:

$$\frac{d}{dt}u(t) = \mathcal{M}u(t) + \mathcal{F}_\zeta(u(t)), \quad t > 0, \quad u(0) \in \mathcal{Y}_\zeta \cap \mathcal{Y}_+. \quad (3.7)$$

We then address the existence and uniqueness of bounded solutions to (3.7) in a manner similar to the approach in [51]. \square

3.2 Disease invasion process

System (3.3)-(3.4) exhibits two disease-free equilibria. More precisely, in an infection-free environment, we have a disease-free equilibrium either in the presence of dogs and ticks or only in the presence of dogs. But, only the former is interesting within this context because the disease is transmitted from dogs to ticks and vice versa. Such an equilibrium is named after the disease-free equilibrium of system (2.3)-(2.4). Let us introduce the following threshold parameter

$$\mathcal{R}_{ST}^0 = \frac{r_E}{\mu_A} \prod_{k \in \mathcal{S}} \frac{\alpha_k}{\alpha_k + \mu_k} = r_E \frac{\alpha_E}{\alpha_E + \mu_E} \frac{\alpha_L}{\alpha_L + \mu_L} \frac{\alpha_N}{\alpha_N + \mu_N} \frac{1}{\mu_A}. \quad (3.8)$$

The parameter \mathcal{R}_{ST}^0 accounts for the ticks' reproduction number and is such that, $\frac{\alpha_E}{\alpha_E + \mu_E}$ represents the fraction of eggs that progress to the larval stage, $\frac{\alpha_L}{\alpha_L + \mu_L}$ is the fraction of larval that progress to the nymphal stage, $\frac{\alpha_N}{\alpha_N + \mu_N}$ is the fraction of nymph that progress to the adult stage, $\frac{1}{\mu_A}$ is the life expectancy of adult ticks and r_E is the ticks egg laying rate. Furthermore, when $\mathcal{R}_{ST}^0 > 1$, the disease-free equilibrium of system (2.3)-(2.4) is given by

$$\mathcal{E}_0 := (\bar{S}_D, 0_{L^1((0, +\infty), \mathbb{R}^2)}, 0, \bar{S}_{TE}, \bar{S}_T, 0_{L^1((0, +\infty), \mathbb{R}^3)}), \quad (3.9)$$

where

$$\begin{cases} \bar{S}_D = \frac{\theta_D}{\mu_D}, \\ \bar{S}_{TE} = K \left(1 - \frac{1}{\mathcal{R}_{ST}^0}\right), \\ \bar{S}_T = \alpha_E \bar{S}_{TE} \sum_{k=1}^3 \mathbf{e}_k \prod_{j=1}^k \frac{\alpha_{j-1}}{\mu_j + \alpha_j}, \quad \text{with } \alpha_0 = 1, \alpha_3 = 0. \end{cases} \quad (3.10)$$

In the last equality, the correspondence $L \leftarrow 1$, $N \leftarrow 2$, and $A \leftarrow 3$ is used to facilitate the notations. See Section 6 for a detailed computation of \mathcal{E}_0 .

Next, we introduce the following threshold

$$\mathcal{T}_0 = \mathcal{T}_0^{D \rightarrow T} \times \mathcal{T}_0^{T \rightarrow D}, \quad (3.11)$$

where $\mathcal{T}_0^{D \rightarrow T}$ quantifies the transmission capability from dogs to ticks and $\mathcal{T}_0^{T \rightarrow D}$ the transmission capability from ticks to dogs. More precisely, we have

$$\mathcal{T}_0^{D \rightarrow T} = \underbrace{\int_0^\infty \beta_D^1(a) \pi_D(a) da}_{\text{Transmission from infected dogs to ticks}} + \underbrace{\int_0^\infty \beta_D^2(a) \pi_C(a) da \int_0^\infty \nu_D(a) \pi_D(a) da}_{\text{Transmission from chronically infected dogs to ticks}},$$

and

$$\mathcal{T}_0^{T \rightarrow D} = \sum_{k \in \mathcal{S} \setminus \{E\}} \frac{\bar{S}_k}{\sum_{j \in \mathcal{S} \setminus \{E\}} \bar{S}_j} \times \mathcal{T}_{0k}^{T \rightarrow D}, \quad (3.12)$$

Proportion ticks of stage k

where $\mathcal{T}_{0k}^{T \rightarrow D}$ denotes the vectorial capacity of ticks population of stage k and is explicitly given by

$$\mathcal{T}_{0k}^{T \rightarrow D} = \underbrace{\frac{\sum_{j \in \mathcal{S} \setminus \{E\}} \bar{S}_j}{\bar{S}_D}}_{\text{Ticks/Dogs ratio}} \times \underbrace{\int_0^\infty \beta_T(a) \langle \mathbf{1}, e^{-\mathbf{M}a} \mathbf{e}_k \rangle da}_{\text{Transmission from ticks at stage } k \text{ to Dogs}}, \quad (3.13)$$

with

$$\begin{cases} \pi_D(a) = e^{-\int_0^a (\mu_D + \delta_D(l) + \nu_D(l)) dl} = \mathbf{\Pi}(a, 0) \mathbf{v}_1, \\ \pi_C(a) = e^{-\int_0^a (\mu_D + \delta_C(l)) dl} = \mathbf{\Pi}(a, 0) \mathbf{v}_2. \end{cases} \quad (3.14)$$

The map $a \rightarrow \pi_D(a)$ (resp. $a \rightarrow \pi_C(a)$) describes the probability to still be infected (resp. chronically infected) a -time post-infection. Based on the above notations, we now state the invasion dynamics in terms of the threshold \mathcal{T}_0 defined in (3.11).

Theorem 3.3. *Let Assumption 3.1 be satisfied. Assume in addition that the ticks' reproduction number satisfies $\mathcal{R}_{ST}^0 > 1$. Then the following properties hold true:*

- i) *If $\mathcal{T}_0 < 1$ then the disease-free equilibrium \mathcal{E}_0 is locally asymptotically stable.*
- ii) *If $\mathcal{T}_0 > 1$ then the disease-free equilibrium \mathcal{E}_0 is unstable.*

The proof of Theorem 3.3 is given in Section 7.

3.3 Existence of an endemic equilibrium and bifurcation

In this section, we state our main result concerning necessary and sufficient conditions for the existence of an endemic equilibrium to system (3.3)-(3.4) and forward (resp. backward) bifurcation at $\mathcal{T}_0 = 1$. Denote by \mathcal{E}^* an endemic equilibrium to system (3.3)-(3.4) that is a time-independent solution to system (3.3)-(3.4).

$$\mathcal{E}^* = (S_{TE}^*, \mathbf{S}_T^*, \mathbf{i}_T^*, S_D^*, \mathbf{i}_D^*, R_D^*) \quad (3.15)$$

with

$$\begin{cases} N_D^* = S_{TE}^* + \int_0^\infty \langle \mathbf{1}, \mathbf{i}_T^*(a) \rangle da + \langle \mathbf{1}, \mathbf{S}_T^* \rangle + S_D^* \\ \quad + \int_0^\infty \langle \mathbf{v}_1, \mathbf{i}_D^*(a) \rangle da + \int_0^\infty \langle \mathbf{v}_2, \mathbf{i}_D^*(a) \rangle da + R_D^* \\ 0 = \theta_D - \mu_D N_D^* - \int_0^\infty \delta_D(a) \langle \mathbf{v}_1, \mathbf{i}_D^*(a) \rangle da - \int_0^\infty \delta_C(a) \langle \mathbf{v}_2, \mathbf{i}_D^*(a) \rangle da \end{cases} \quad (3.16)$$

such that $S_{TE}^* > 0$, $\mathbf{S}_T^* \in \text{int}(\mathbb{R}_+^3)$, $\mathbf{i}_T^* \neq 0_{L^1((0, +\infty), \mathbb{R}^3)}$, $S_D^* > 0$, $\mathbf{i}_D^* \neq 0_{L^1((0, +\infty), \mathbb{R}^2)}$, and $R_D^* > 0$. By means of scaling and a suitable change of variables, we prove in Section 8 that

the existence of an endemic equilibrium \mathcal{E}^* can be reduced to the existence of a positive solution of one equation with one unknown. More precisely, we prove that there exists an endemic equilibrium \mathcal{E}^* if and only if there exists $K > 0$ satisfying

$$\Delta(\mathcal{T}_0, K) = 1$$

with

$$\Delta(\mathcal{T}_0, K) := \frac{1 - I_D^\circ(\mathcal{T}_0, K) - (1 - \epsilon)R_D^\circ(\mathcal{T}_0, K)}{N_D^*(K)} f(K\mathcal{T}_0) \frac{1}{\mathcal{T}_0^{T \rightarrow D}} \mathcal{T}_0.$$

The maps $K \rightarrow N_D^*(K)$, $K \rightarrow R_D^\circ(\mathcal{T}_0, K)$, and $K \rightarrow I_D^\circ(\mathcal{T}_0, K)$ are given by

$$\begin{cases} N_D^*(K) := \frac{\theta_D}{\mu_D + \mathcal{T}_0^{T \rightarrow D} K \left(\int_0^\infty \delta_D(a) \pi_D(a) da + \int_0^\infty \delta_C(a) \pi_C(a) da \right)} \\ R_D^\circ(\mathcal{T}_0, K) := \mathcal{T}_0^{T \rightarrow D} \frac{K N_D^*(K)}{\epsilon K \mathcal{T}_0 f(K\mathcal{T}_0) + \mu_D N_D^*(K)} \int_0^\infty \gamma(a) \pi_D(a) da \\ I_D^\circ(\mathcal{T}_0, K) = K \mathcal{T}_0^{T \rightarrow D} \int_0^\infty \pi_D(a) da + K \mathcal{T}_0^{T \rightarrow D} \int_0^\infty \nu_D(a) \pi_D(a) da \int_0^\infty \pi_C(a) da \end{cases}$$

and the function $x \rightarrow f(x)$ is defined by

$$f(x) := \frac{\theta_D}{\mu_D} \sum_{k=1}^3 \left(\prod_{j=1}^k \frac{\mu_j + \alpha_j}{(\mu_j + \alpha_j) + x} \right) \frac{\bar{S}_k}{\sum_{j \in \mathcal{S} \setminus \{E\}} \bar{S}_j} \mathcal{T}_{0k}^{T \rightarrow D}$$

with $\mathcal{T}_0^{T \rightarrow D}$ (resp. $\mathcal{T}_{0k}^{T \rightarrow D}$) is the vectorial (k 's ticks stage vectorial) capacity given in (3.12) (resp. in (3.13)). Recall that in the above sum, we have used the notations $L \leftarrow 1$, $N \leftarrow 2$, and $A \leftarrow 3$ with $\alpha_3 = 0$. Furthermore, if we consider the bifurcation parameter

$$\begin{aligned} C_{\text{bif}}^{-1} &:= \frac{1}{\mu_D} \mathcal{T}_0^{T \rightarrow D} \left(\int_0^\infty \delta_D(a) \pi_D(a) da + \int_0^\infty \delta_C(a) \pi_C(a) da \right) \\ &\quad - \sum_{k=1}^3 \left(\sum_{j=1}^k \frac{1}{\mu_j + \alpha_j} \right) \frac{\bar{S}_k}{\sum_{j \in \mathcal{S} \setminus \{E\}} \bar{S}_j} \frac{\mathcal{T}_{0k}^{T \rightarrow D}}{\mathcal{T}_0^{T \rightarrow D}} \\ &\quad - (1 - \epsilon) \frac{1}{\mu_D} \mathcal{T}_0^{T \rightarrow D} \int_0^\infty \gamma(a) \pi_D(a) da \\ &\quad - \mathcal{T}_0^{T \rightarrow D} \int_0^\infty \pi_D(a) da - \mathcal{T}_0^{T \rightarrow D} \int_0^\infty \nu_D(a) \pi_D(a) da \int_0^\infty \pi_C(a) da \end{aligned}$$

then we have the following results whose proof is given in Section 8.

Theorem 3.4. *Let Assumption 3.1 be satisfied. Assume in addition that the ticks' reproduction number satisfies $\mathcal{R}_{ST}^0 > 1$. Then the following properties hold true*

- i) *If $\mathcal{C}_{\text{bif}} > 0$ then we have a backward bifurcation at $\mathcal{T}_0 = 1$, that is there exists an endemic equilibrium for $\mathcal{T}_0 < 1$ close to 1;*
- ii) *If $\mathcal{C}_{\text{bif}} < 0$ then we have a forward bifurcation at $\mathcal{T}_0 = 1$, that is there exists an endemic equilibrium for $\mathcal{T}_0 > 1$ close to 1 and no endemic equilibrium for $\mathcal{T}_0 < 1$ close to 1.*

4 Numerical simulations

In this section, we present numerical simulations to illustrate the forward and backward bifurcation results of Model (2.3)-(2.4). These simulations were conducted using finite volume numerical schemes implemented with the R software (<http://www.r-project.org/>). The values of the parameters used are given in Table 1. In all the figures, we have used the initial conditions $S_D(0) = 10$, $i_D(0, a) = 0.03a \max(0, 100 - a)$, $c_D(0, a) = 0.01a \max(0, 100 - a)$, $R_D(0) = 0$, $S_{TE}(0) = 1$, $S_{TL}(0) = 10$, $S_{TN}(0) = 0$, $S_{TA}(0) = 2$, $i_{TL}(0, a) = 0.01$, $i_{TN}(0, a) = 0.3$, $i_{TA}(0, a) = 1$. Given the parameter values in Table 1, the ticks' reproduction number $\mathcal{R}_{ST}^0 \approx 66.193$.

A forward bifurcation occurs at $\mathcal{T}_0 = 1$ (Theorem 3.4), which means that whenever $\mathcal{T}_0 < 1$, then the disease-free equilibrium \mathcal{E}_0 is locally asymptotically stable (Theorem 3.3) and no endemic equilibrium exists. Asymptotically, the disease go extinct (Figure 2 (b), where $\mathcal{T}_0 \approx 0.992$). However, if $\mathcal{T}_0 > 1$, then \mathcal{E}_0 is unstable (Theorem 3.3) and an endemic equilibrium exists if $C_{\text{bif}} < 0$ (Theorem 3.4). The disease is asymptotically persistent and the solution converges to the endemic equilibrium (Figure 2 (a), where $\mathcal{T}_0 \approx 1.103$ and $C_{\text{bif}} \approx -9.4 \times 10^{-4}$).

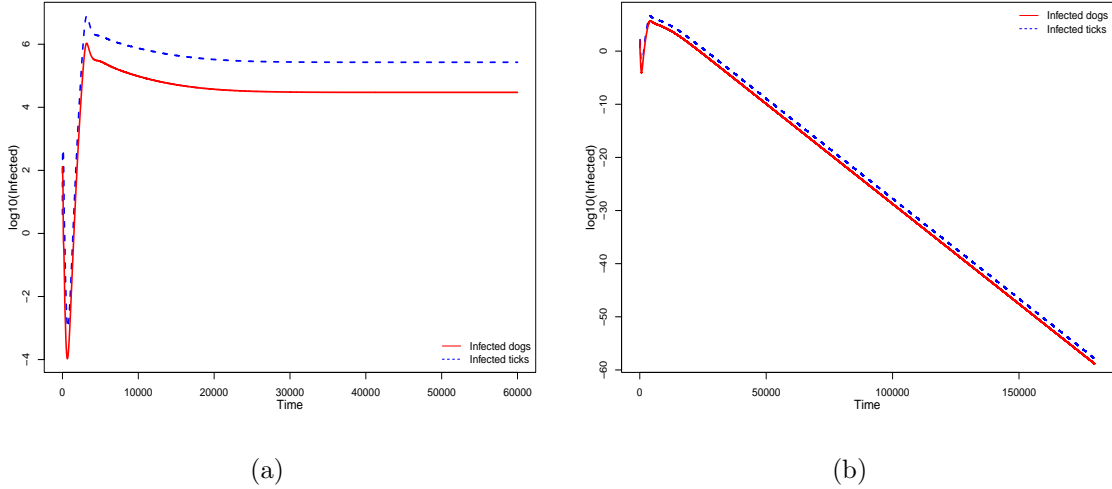


Figure 2: Forward bifurcation diagram with convergence either to (a) the endemic equilibrium when $\mathcal{T}_0 \approx 1.103 > 1$; (b) the disease-free equilibrium when $\mathcal{T}_0 \approx 0.992 < 1$. Here $r_E = 1$, $\delta_D(a) = 1.735 \times 10^{-4}$, $\delta_C(a) = 3.47 \times 10^{-4}$, $\beta_D^2(a) = 0.038$, $\beta_T(a) = 0.15504$, and $C_{\text{bif}} = -9.4 \times 10^{-4}$ are fixed. The probability of infection $\beta_D^1(a)$ is considered constant with: (a) $\beta_D^1(a) = 0.076$ and (b) $\beta_D^1(a) = 0.0506$. The other parameters are given by Table 1.

A backward bifurcation occurs at $\mathcal{T}_0 = 1$. This means that whenever $\mathcal{T}_0 > 1$, the disease-free equilibrium is unstable and there exists a unique endemic equilibrium. In such situation, the solutions converge asymptotically to this endemic equilibrium (Figures 3 (a)), where $\mathcal{T}_0 \approx 1.318$). By contrast to the forward bifurcation (Figures 2 and 4 (a)), when $\mathcal{T}_0 < 1$ and $C_{\text{bif}} \approx 5.21 \times 10^{-4} > 0$ there exists an endemic equilibrium (Theorem 3.4). Furthermore, there exists a threshold $\mathcal{T}_0^* \approx 0.422 < 1$ such that (i) for $\mathcal{T}_0 < \mathcal{T}_0^*$, there is no endemic equilibrium and the solutions converge to the disease-free equilibrium (Figures 3 (b) and 4 (b), where $\mathcal{T}_0 \approx 0.415 < \mathcal{T}_0^*$) and (ii) for $\mathcal{T}_0^* < \mathcal{T}_0 < 1$, there exist an endemic equilibrium such that, depending on the initial condition, the solution can converge to this endemic equilibrium (Figures 3 (c) and 4 (b), where $\mathcal{T}_0^* < \mathcal{T}_0 \approx 0.843$).

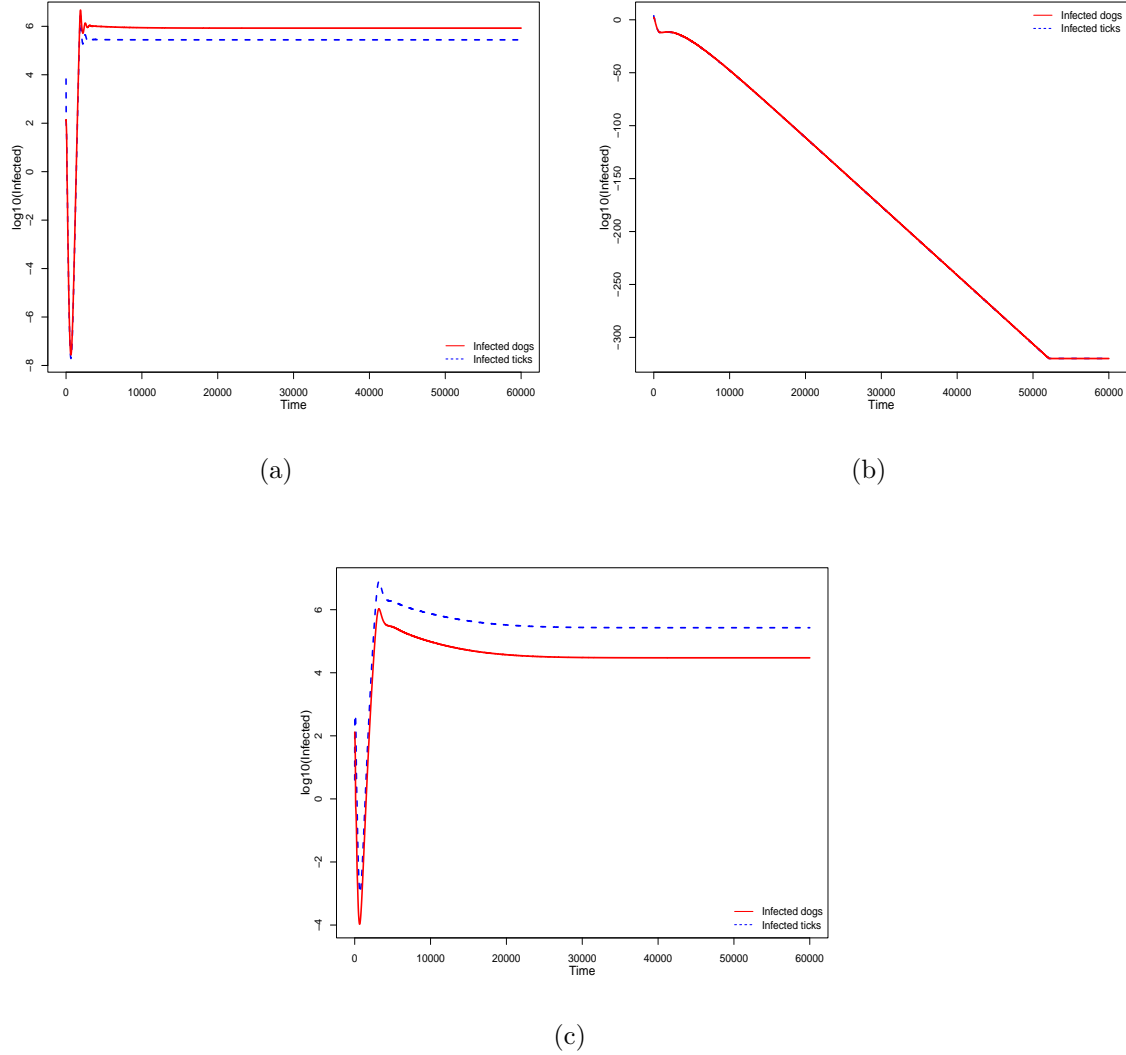


Figure 3: Backward bifurcation diagram with convergence either to (a) the endemic equilibrium when $\mathcal{T}_0 \approx 1.318 > 1$; (b) the disease-free equilibrium when $\mathcal{T}_0 \approx 0.415 < \mathcal{T}_0^* < 1$; (c) the endemic equilibrium when $\mathcal{T}_0^* < \mathcal{T}_0 \approx 0.843 < 1$. Here $r_E = 1$, $\delta_D(a) = 0.1735$, $\delta_C(a) = 0.347$, $\beta_D^2(a) = 0.608$, $\beta_T(a) = 0.15504$, and $C_{\text{bif}} = 5.21 \times 10^{-4}$ are fixed. The probability of infection $\beta_D^1(a)$ is considered constant with: (a) $\beta_D^1(a) = 0.76$, (b) $\beta_D^1(a) = 0.304$, and (c) $\beta_D^1(a) = 0.456$. The other parameters are given by Table 1.

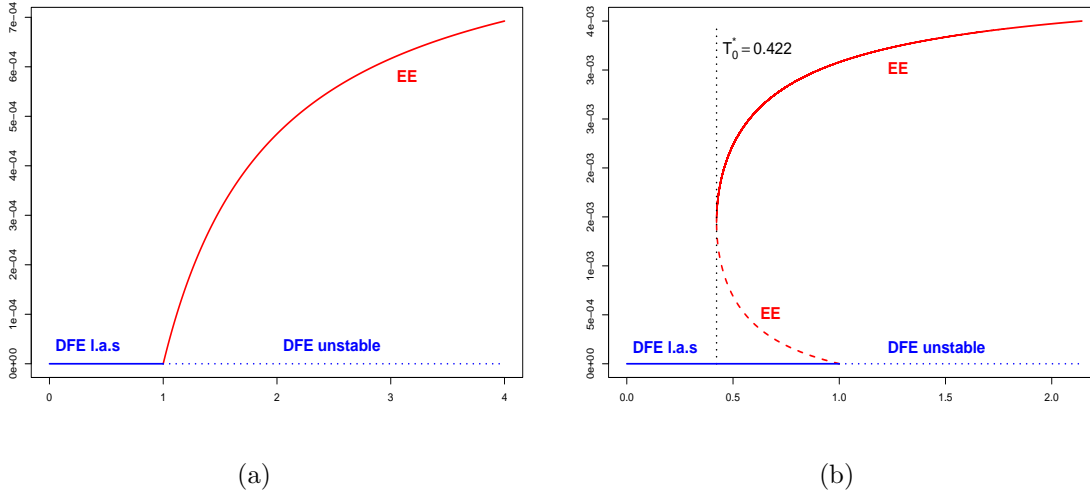


Figure 4: Forward and backward bifurcation diagram. (a) Forward bifurcation diagram with $C_{\text{bif}} = -9.4 \times 10^{-4}$ where all the parameters are the same as in Figure 2. (b) Backward bifurcation diagram with $C_{\text{bif}} = 5.21 \times 10^{-4}$ and the parameters are the same as in Figure 3. Note that C_{bif} does not depend on the parameter β_D^1 .

5 Discussion and Conclusions

Discussion

In this work, we have developed a novel partial differential equation (PDE) model that extends classical epidemiological models proposed for tick-borne diseases (see [30, 31]). The model proposed here incorporates the ability to accurately account for the different ticks developmental stages (discrete variable) as well as the variations in infectiousness over the course of infection (continuous variable). In our study, we established the mathematical well-posedness of the model using the integrated semigroups theory. However, the presence of singularity in the force of infection whenever the total dogs' population is zero introduces a complication to the analysis. **Note that this is a mathematical construct, since without dogs the model would not hold nor make sense.**

We derived an explicit formula for the reproduction number \mathcal{T}_0 , extending the classical formula. We identified two possible behaviors around $\mathcal{T}_0 = 1$. The first scenario involves a forward bifurcation, indicating that an epidemic can only occur if $\mathcal{T}_0 > 1$. In the second scenario, a backward bifurcation is observed, where an epidemic can arise if $\mathcal{T}_0 < 1$, provided that \mathcal{T}_0 is sufficiently close to 1. These findings have significant epidemiological implications, especially in an endemic region where controlling the epidemic is of importance. In the forward bifurcation case, simply reducing the reproduction number \mathcal{T}_0 below 1 is sufficient to halt the epidemic. However, in the backward bifurcation scenario, the number must be reduced below a second threshold, denoted as \mathcal{T}_0^* .

The epidemiological implication of the backward bifurcation phenomenon is that the classical requirement of having the basic reproduction number (\mathcal{R}_0) less than one is no longer sufficient to ensure effective disease eradication or elimination [36]. This implies that disease can

invade to a relatively high endemic level once the reproduction number \mathcal{R}_0 is more than one; decreasing \mathcal{R}_0 below one do not necessarily make the disease disappear, see Figure 3 (b) and Figure 2 in [36]. Backward bifurcation have been shown to occur in several vector-borne disease models [2, 12, 22, 28, 29, 32, 43, 51]. For instance Garba *et al.* [32] showed for a dengue model the possibility of backward bifurcation where a locally stable disease-free equilibrium coexists with a locally stable endemic equilibrium. Also the age-structure malaria and Chikungunya models in [2, 28, 29, 51] were shown to exhibit backward bifurcation when \mathcal{R}_0 is less than one. This phenomenon is equally possible in the absence of any age-structure [2, 28, 29]. Backward bifurcation in these vector-borne disease models are induced by disease induced mortality. Furthermore, backward bifurcation can equally be induced by several other factors like vaccination [3, 13, 24, 53], exogenous re-infection which are known to occur in tuberculosis models [17, 27, 54], and cross-immunity for instance in a two strain influenza transmission model [33]. Other epidemiological mechanism like differential susceptibility in risk-structured models could also cause backward bifurcation in disease transmission models [36]. We should note that the age-structured *Ehrlichia chaffeensis* model (2.3)-(2.4) include disease induce death (δ_D and δ_C) in the dog population and hence the source of the backward bifurcation.

Conclusion

In conclusion, we have developed a novel partial differential equation model of *Ehrlichia chaffeensis* transmission dynamics in dogs. The model incorporates the different developmental life stages of ticks (discrete variable) as well as the duration of infection (continuous variable). The following results were obtained from our theoretical analysis and numerical simulations:

- (i) The developed model is well-posed;
- (ii) The model always exhibits a disease-free equilibrium along with an endemic equilibrium;
- (iii) The model has a reproduction number, denoted as \mathcal{T}_0 ;
- (iii) A necessary and sufficient condition for the bifurcation of an endemic equilibrium was established using semigroup approach;
- (iv) A bifurcation (forward or backward), can occur at $\mathcal{T}_0 = 1$.

6 The disease-free equilibrium of (2.3)-(2.4)

The dynamic of ticks in the absence of infection is governed by the following system of equations

$$\begin{cases} \frac{dS_{TE}(t)}{dt} = r_E \left(1 - \frac{S_{TE}(t)}{K}\right) S_{TA}(t) - (\mu_E + \alpha_E) S_{TE}(t) \\ \frac{dS_{TL}(t)}{dt} = \alpha_E S_{TE}(t) - (\mu_L + \alpha_L) S_{TL}(t) \\ \frac{dS_{TN}(t)}{dt} = \alpha_L S_{TL}(t) - (\mu_N + \alpha_N) S_{TN}(t) \\ \frac{dS_{TA}(t)}{dt} = \alpha_N S_{TN}(t) - \mu_A S_{TA}(t) \end{cases} \quad (6.1)$$

with initial condition $S_{TE}(0) = S_{TE0} \geq 0$, $S_{TL}(0) = S_{TL0} \geq 0$, $S_{TN}(0) = S_{TN0} \geq 0$, and $S_{TA}(0) = S_{TA0} \geq 0$. It is easy to see that $\{0\} \times \mathbb{R}_+^3$ is invariant with respect to the ordinary differential equation so that if $S_{TE0} = 0$ then the larval, nymphal, and adult stages exponentially goes to 0. From this, we have that a necessary condition for the ticks to persist

$Y_0 := \{0_{\mathbb{R}^3}\} \times L^1((0, +\infty), \mathbb{R}^3)$. Let $\mathcal{A}_D : D(\mathcal{A}_D) \subset X_0 \rightarrow X$ and $\mathcal{A}_T : D(\mathcal{A}_T) \subset Y_0 \rightarrow Y$ be the linear operators defined by

$$\mathcal{A}_D \begin{pmatrix} 0_{\mathbb{R}^2} \\ \varphi \end{pmatrix} = \begin{pmatrix} -\varphi(0) \\ -\varphi' - (\mu_D + \boldsymbol{\theta}_D(\cdot)\varphi) \end{pmatrix} \quad \text{and} \quad \mathcal{A}_T \begin{pmatrix} 0_{\mathbb{R}^3} \\ \phi \end{pmatrix} = \begin{pmatrix} -\phi(0) \\ -\phi' - \mathbf{M}\phi \end{pmatrix}$$

with

$$D(\mathcal{A}_D) = \{0_{\mathbb{R}^2}\} \times W^{1,1}((0, +\infty), \mathbb{R}^2) \quad \text{and} \quad D(\mathcal{A}_T) = \{0_{\mathbb{R}^3}\} \times W^{1,1}((0, +\infty), \mathbb{R}^3).$$

Let $\mathcal{A} : D(\mathcal{A}) \subset Y_0 \times X_0 \rightarrow Y \times X$ with

$$D(\mathcal{A}) = D(\mathcal{A}_D) \times D(\mathcal{A}_T) \quad \text{and} \quad \mathcal{A} \begin{pmatrix} \varphi \\ \phi \end{pmatrix} = \begin{pmatrix} \mathcal{A}_D[\varphi] \\ \mathcal{A}_T[\phi] \end{pmatrix}.$$

Let $\mathcal{B} : X_0 \times Y_0 \rightarrow X \times Y$ be the bounded linear operator defined by

$$\mathcal{B} \begin{pmatrix} \varphi \\ \phi \end{pmatrix} = \begin{pmatrix} \left(\mathbf{v}_1 \mathcal{P}_T[\phi] + \mathbf{v}_2 \mathcal{Q}_D[\varphi] \right) \\ 0_{L^1((0, +\infty), \mathbb{R}^2)} \\ \frac{\bar{\mathcal{S}}_T}{\bar{\mathcal{S}}_D} \begin{pmatrix} \mathcal{W}_D[\varphi] \\ 0_{L^1((0, +\infty), \mathbb{R}^3)} \end{pmatrix} \end{pmatrix} \quad (7.3)$$

where we have set for each $\varphi = \begin{pmatrix} 0_{\mathbb{R}^2} \\ \varphi \end{pmatrix} \in X_0$

$$\begin{cases} \mathcal{W}_D[\varphi] := \int_0^\infty \langle \boldsymbol{\beta}_D(a), \varphi(a) \rangle da \\ \mathcal{P}_D[\varphi] := \int_0^\infty \gamma(a) \langle \mathbf{v}_1, \varphi(a) \rangle da \\ \mathcal{Q}_D[\varphi] := \int_0^\infty \nu_D(a) \langle \mathbf{v}_1, \varphi(a) \rangle da \end{cases}$$

and each $\phi = \begin{pmatrix} 0_{\mathbb{R}^3} \\ \phi \end{pmatrix} \in Y_0$

$$\begin{cases} \mathcal{W}_T[\phi] := \int_0^\infty \langle \mathbf{e}_3, \phi(a) \rangle da \\ \mathcal{P}_T[\phi] := \int_0^\infty \beta_T(a) \langle \mathbf{1}, \phi(a) \rangle da. \end{cases}$$

Hence, setting for all $t > 0$

$$\varphi_D(t) := \begin{pmatrix} 0_{\mathbb{R}^2} \\ \mathbf{i}_D(t, \cdot) \end{pmatrix} \quad \text{and} \quad \phi_T(t) := \begin{pmatrix} 0_{\mathbb{R}^3} \\ \mathbf{i}_T(t, \cdot) \end{pmatrix}$$

and

$$\varphi_{D0} := \begin{pmatrix} 0_{\mathbb{R}^2} \\ \mathbf{i}_D(0, \cdot) \end{pmatrix} \quad \text{and} \quad \phi_{T0} := \begin{pmatrix} 0_{\mathbb{R}^3} \\ \mathbf{i}_T(0, \cdot) \end{pmatrix}$$

the system (7.1)-(7.2) can be rewritten as the following abstract Cauchy problem

$$\begin{cases} \frac{d}{dt} \begin{pmatrix} \varphi_D(t) \\ \phi_T(t) \end{pmatrix} = \mathcal{A} \begin{pmatrix} \varphi_D(t) \\ \phi_T(t) \end{pmatrix} + \mathcal{B} \begin{pmatrix} \varphi_D(t) \\ \phi_T(t) \end{pmatrix}, \quad t > 0 \\ \begin{pmatrix} \varphi_D(0) \\ \phi_T(0) \end{pmatrix} = \begin{pmatrix} \varphi_{D0} \\ \phi_{T0} \end{pmatrix} \in X_0 \times Y_0. \end{cases} \quad (7.4)$$

In order to define the threshold that determines the local asymptotic stability of the disease-free equilibrium, we need first to prove the following lemma. Before proceeding, let us set $X_+ := \mathbb{R}_+^2 \times L^1((0, +\infty), \mathbb{R}^2)$, $Y_+ := \mathbb{R}_+^2 \times L^1((0, +\infty), \mathbb{R}^2)$, $X_{0+} := X_+ \cap X_0$, and $Y_{0+} := Y_+ \cap Y_0$.

Lemma 7.1. *Let Assumption 3.1 be satisfied. Then the following properties hold true*

- i) \mathcal{A} is resolvent positive i.e., $(\lambda - \mathcal{A})^{-1}$ maps $X_+ \times Y_+$ into itself for all large λ in the resolvent set $\rho(\mathcal{A})$ of \mathcal{A} ;
- ii) The spectral bound $s(\mathcal{A})$ i.e.

$$s(\mathcal{A}) = \sup \{ \Re(\lambda) : \lambda \in \sigma(\mathcal{A}) \} \quad (7.5)$$

satisfies $s(\mathcal{A}) < 0$ and $(s(\mathcal{A}), +\infty) \subset \rho(\mathcal{A}_D) \cap \rho(\mathcal{A}_T)$.

Proof. In order to obtain the conclusion of the lemma, we first prove that \mathcal{A} is resolvent positive. To do this, let us note that if $\lambda \in \rho(\mathcal{A}_D) \cap \rho(\mathcal{A}_T)$ then $\lambda \in \rho(\mathcal{A})$ and

$$(\lambda - \mathcal{A})^{-1} \begin{pmatrix} \tilde{\varphi} \\ \tilde{\phi} \end{pmatrix} = \begin{pmatrix} (\lambda - \mathcal{A}_D)^{-1}[\tilde{\varphi}] \\ (\lambda - \mathcal{A}_T)^{-1}[\tilde{\phi}] \end{pmatrix}$$

so that the resolvent of \mathcal{A} is obtained by determining the resolvent of \mathcal{A}_D and \mathcal{A}_T . By standard computations, we have for each $\lambda \in \rho(\mathcal{A}_D)$ and $\tilde{\varphi} = \begin{pmatrix} \mathbf{x} \\ \tilde{\varphi} \end{pmatrix} \in Y$

$$\begin{aligned} (\lambda - \mathcal{A}_D)^{-1} \begin{pmatrix} \mathbf{x} \\ \tilde{\varphi} \end{pmatrix} &= \begin{pmatrix} 0_{\mathbb{R}^2} \\ \varphi \end{pmatrix} \\ \iff \varphi(a) &= e^{-\lambda a} \mathbf{\Pi}(a, 0) \mathbf{x} + \int_0^a e^{-\lambda(a-\tau)} \mathbf{\Pi}(a, \tau) \tilde{\varphi}(\tau) d\tau, \quad a \geq 0 \end{aligned} \quad (7.6)$$

(where $\mathbf{\Pi}(a, 0)$ is defined in (3.5)) while for each $\lambda \in \rho(\mathcal{A}_T)$ and $\tilde{\phi} = \begin{pmatrix} \mathbf{y} \\ \tilde{\phi} \end{pmatrix} \in X$ we have

$$\begin{aligned} (\lambda - \mathcal{A}_T)^{-1} \begin{pmatrix} \mathbf{y} \\ \tilde{\phi} \end{pmatrix} &= \begin{pmatrix} 0_{\mathbb{R}^3} \\ \phi \end{pmatrix} \\ \iff \phi(a) &= e^{-\lambda a} e^{-\mathbf{M}a} \mathbf{y} + \int_0^a e^{-\lambda(a-\tau)} e^{-\mathbf{M}(a-\tau)} \tilde{\phi}(\tau) d\tau, \quad a \geq 0. \end{aligned} \quad (7.7)$$

Next, recalling the definition of \mathbf{M} and $\boldsymbol{\theta}(a)$ respectively in (3.1) and (3.2) it follows that if

$$\begin{cases} \lambda > -\min(\mu_L + \alpha_L, \mu_N + \alpha_N, \mu_A) =: -\mu_{1,-} < 0 \\ \text{and } \lambda > -\mu_D - \min(\text{essinf}_{\mathbb{R}^+} \boldsymbol{\theta}_{11}(a), \text{essinf}_{\mathbb{R}^+} \boldsymbol{\theta}_{22}(a)) =: -\mu_{2,-} < 0 \end{cases} \quad (7.8)$$

then $\lambda \in \rho(\mathcal{A}_D) \cap \rho(\mathcal{A}_T)$. Next, recalling from [8, 46] if \mathcal{A} is resolvent positive then

$$\begin{cases} s(\mathcal{A}) = \inf \{ \lambda \in \rho(\mathcal{A}) : (\lambda - \mathcal{A})^{-1}(X_+ \times Y_+) \subseteq (X_+ \times Y_+) \} \\ (s(\mathcal{A}), +\infty) \subseteq \rho(\mathcal{A}) \end{cases} \quad (7.9)$$

and we infer from (7.6)-(7.9) that $s(\mathcal{A}) < 0$. The proof is completed. \square

Thanks to Lemma 7.1 and the positiveness of the bounded linear operator \mathcal{B} (i.e. it maps $X_{0+} \times Y_{0+}$ into $X_+ \times Y_+$), one can use the theory developed in [55] to define a threshold which determines the sign of $s(\mathcal{A} + \mathcal{B})$ i.e. the spectral bound of $\mathcal{A} + \mathcal{B}$ given by

$$s(\mathcal{A} + \mathcal{B}) = \sup \{ \Re(\lambda) : \lambda \in \sigma(\mathcal{A} + \mathcal{B}) \}.$$

More precisely, we set

$$\widehat{\mathcal{T}}_0 := r(\mathcal{B}(-\mathcal{A})^{-1}) \quad (7.10)$$

where $r(\mathcal{B}(-\mathcal{A})^{-1})$ is the spectral radius of the bounded linear operator $\mathcal{B}(-\mathcal{A})^{-1}$. The following lemma will allow us to obtain the relationship between the sign of $\widehat{\mathcal{T}}_0 - 1$ and the growth bound of the C_0 -semigroup generated by $(\mathcal{A} + \mathcal{B})_0$ *i.e.*, the part of $\mathcal{A} + \mathcal{B}$ in $X_0 \times Y_0$. Note that latter threshold $\widehat{\mathcal{T}}_0$ does not exhibit explicitly the parameters of the model but this will be resolved after proving the local stability properties.

Lemma 7.2. *Let Assumption 3.1 be satisfied. Then $s(\mathcal{A} + \mathcal{B})$ and $\widehat{\mathcal{T}}_0 - 1$ have the same sign. Moreover, we have the following properties*

- i) $s((\mathcal{A} + \mathcal{B})_0) = s(\mathcal{A} + \mathcal{B}) = \omega_0((\mathcal{A} + \mathcal{B})_0)$ with $\omega_0((\mathcal{A} + \mathcal{B})_0)$ the growth bound of the C_0 -semigroup generated by $(\mathcal{A} + \mathcal{B})_0$
- ii) $\omega_{0,ess}((\mathcal{A} + \mathcal{B})_0) \leq \omega_0(\mathcal{A}_0) = s(\mathcal{A}_0) = s(\mathcal{A})$ with $\omega_{0,ess}((\mathcal{A} + \mathcal{B})_0)$ the essential growth bound of the C_0 -semigroup generated by $(\mathcal{A} + \mathcal{B})_0$ and \mathcal{A}_0 is the part of \mathcal{A} in $X_0 \times Y_0$.

Proof. We first note that $X \times Y$ is an AL-space [55, Theorem 3.14] with positive cone $X_+ \times Y_+$ that is normal and generating (see [55]) so that

$$s(\mathcal{A}_0) = \omega_0(\mathcal{A}_0) \quad \text{and} \quad s((\mathcal{A} + \mathcal{B})_0) = \omega_0((\mathcal{A} + \mathcal{B})_0) \quad (7.11)$$

with $\omega_0(\mathcal{A}_0)$ the growth bound of the C_0 -semigroup generated by \mathcal{A}_0 . The first assertion of the lemma is a direct application of [55, Theorem 3.5]. Next, we prove properties i) and ii). Since $\rho(\mathcal{A}) = \rho(\mathcal{A}_0)$ and $\rho(\mathcal{A} + \mathcal{B}) = \rho((\mathcal{A} + \mathcal{B})_0)$ (see [40]) it follows that $s(\mathcal{A}_0) = s(\mathcal{A})$ and $s((\mathcal{A} + \mathcal{B})_0) = s(\mathcal{A} + \mathcal{B})$. This proves i) and the equality $\omega_0(\mathcal{A}_0) = s(\mathcal{A}_0) = s(\mathcal{A})$. Next, note that \mathcal{B} is compact since $\mathcal{B}(X_0 \times Y_0)$ is a finite-dimensional space. Therefore, we infer from [20, Theorem 1.2] that $\omega_{0,ess}((\mathcal{A} + \mathcal{B})_0) \leq \omega_0(\mathcal{A}_0)$ and the proof is completed. \square

Lemma 7.3. *Let Assumption 3.1 be satisfied. Assume in addition that the ticks' reproduction number satisfies $\mathcal{R}_{ST}^0 > 1$. Then the disease-free equilibrium is locally asymptotically stable if $\widehat{\mathcal{T}}_0 < 1$ and unstable if $\widehat{\mathcal{T}}_0 > 1$.*

Proof. If $\widehat{\mathcal{T}}_0 < 1$ then by Lemma 7.3 we have $\omega_0((\mathcal{A} + \mathcal{B})_0) < 0$ resulting to the local asymptotic stability of the disease-free. If $\widehat{\mathcal{T}}_0 > 1$ then $\omega_0((\mathcal{A} + \mathcal{B})_0) > 0$ and since $\omega_{0,ess}((\mathcal{A} + \mathcal{B})_0) < 0$ it follows that $\omega_{0,ess}((\mathcal{A} + \mathcal{B})_0) < \omega_0((\mathcal{A} + \mathcal{B})_0)$. Therefore, using [20, Theorem 3.2.] one knows that $(\mathcal{A} + \mathcal{B})_0$ has an isolated positive eigenvalue. Thus we refer to [40, Proposition 5.7.4]) that the disease-free equilibrium is unstable. \square

The threshold $\widehat{\mathcal{T}}_0$ defined in (7.10) is somehow abstract and does not allow the interpretation of the stability of the disease-free to be made in terms of the parameters of the model. Therefore, we will give in the following and equivalent threshold which incorporate explicitly the parameters of the model. To this end, we first make a remark that allows us to simplify the determination of \mathcal{T}_0 . Let us set $Y_1 = \mathbb{R}^2 \times L^1((0, +\infty), \mathbb{R}^2)$, and $X_1 = \mathbb{R}^3 \times L^1((0, +\infty), \mathbb{R}^3)$. Next, we observe that $Y_1 \times X_1$ is finite-dimensional and $\mathcal{B}(Y_0 \times X_0) \subseteq Y_1 \times X_1$ so that the spectral bound of $\mathcal{B}(-\mathcal{A})^{-1}$ coincides with the spectral bound of $\mathcal{B}(-\mathcal{A})_{|Y_1 \times X_1}^{-1}$. The advantage of considering $\mathcal{B}(-\mathcal{A})_{|Y_1 \times X_1}^{-1}$ is that we can obtain the spectral radius by solving an eigenvalue problem of a matrix.

Proposition 7.4. *Let Assumption 3.1 be satisfied. Assume in addition that the ticks' reproduction number satisfies $\mathcal{R}_{ST}^0 > 1$ and set*

$$\mathcal{T}_0 = \frac{1}{\bar{S}_D} \int_0^\infty \beta_T(a) \langle \mathbf{1}, e^{-\mathbf{M}a} \bar{\mathbf{S}}_T \rangle da \left[\int_0^\infty \beta_D^1(a) \pi_D(a) da + \int_0^\infty \nu_D(a) \pi_D(a) da \int_0^\infty \beta_D^2(a) \pi_C(a) da \right]. \quad (7.12)$$

Then $\widehat{\mathcal{T}}_0 - 1$ and $\mathcal{T}_0 - 1$ have the same sign.

Proof. We first give the explicit form of the linear operator $\mathcal{B}(-\mathcal{A})_{|X_1 \times Y_1}^{-1}$. Let $\begin{pmatrix} \varphi_1 \\ \phi_1 \end{pmatrix} \in X_1 \times Y_1$ be given with $\varphi_1 := \begin{pmatrix} \mathbf{x} \\ 0_{L^1((0,+\infty),\mathbb{R}^2)} \end{pmatrix}$ and $\phi_1 := \begin{pmatrix} \mathbf{y} \\ 0_{L^1((0,+\infty),\mathbb{R}^3)} \end{pmatrix}$. Then using the resolvent formula of \mathcal{A}_D and \mathcal{A}_T respectively in (7.6) and (7.7) we obtain

$$(-\mathcal{A}_D)^{-1}[\varphi_1] = \begin{pmatrix} 0_{\mathbb{R}^2} \\ \mathbf{\Pi}(\cdot, 0)\mathbf{x} \end{pmatrix} =: \varphi_0 \quad (7.13)$$

and

$$(-\mathcal{A}_T)^{-1}[\phi_1] = \begin{pmatrix} 0_{\mathbb{R}^3} \\ e^{-\mathbf{M}\cdot}\mathbf{y} \end{pmatrix} =: \phi_0. \quad (7.14)$$

Hence using the explicit form of \mathcal{B} in (7.3) it comes

$$\mathcal{B}(-\mathcal{A})^{-1} \begin{pmatrix} \varphi_1 \\ \phi_1 \end{pmatrix} = \mathcal{B} \begin{pmatrix} \varphi_0 \\ \phi_0 \end{pmatrix} = \begin{pmatrix} \left(\begin{array}{c} \mathbf{v}_1 \mathcal{P}_T[\phi_0] + \mathbf{v}_2 \mathcal{Q}_D[\varphi_0] \\ 0_{L^1((0,+\infty),\mathbb{R}^2)} \\ \frac{\bar{\mathbf{S}}_T}{\bar{S}_D} \begin{pmatrix} \mathcal{W}_D[\varphi_0] \\ 0_{L^1((0,+\infty),\mathbb{R}^3)} \end{pmatrix} \end{array} \right) \end{pmatrix} \quad (7.15)$$

with

$$\begin{cases} \mathbf{v}_1 \mathcal{P}_T[\phi_0] + \mathbf{v}_2 \mathcal{Q}_D[\varphi_0] = \mathbf{v}_1 \int_0^\infty \beta_T(a) \langle \mathbf{1}, e^{-\mathbf{M}a} \mathbf{y} \rangle da + \mathbf{v}_2 \int_0^\infty \nu_D(a) \langle \mathbf{v}_1, \mathbf{\Pi}(a, 0)\mathbf{x} \rangle da \\ \mathcal{W}_D[\varphi_0] = \int_0^\infty \langle \beta_D(a), \mathbf{\Pi}(a, 0)\mathbf{x} \rangle da \end{cases}$$

so that the spectral radius of $\mathcal{B}(-\mathcal{A})^{-1}$ is given by the spectral radius of the linear operator $\mathcal{C} : \mathbb{R}^2 \times \mathbb{R}^3 \rightarrow \mathbb{R}^2 \times \mathbb{R}^3$ given by

$$\mathcal{C} \begin{pmatrix} \mathbf{x} \\ \mathbf{y} \end{pmatrix} = \begin{pmatrix} \mathbf{v}_1 \int_0^\infty \beta_T(a) \langle \mathbf{1}, e^{-\mathbf{M}a} \mathbf{y} \rangle da + \mathbf{v}_2 \int_0^\infty \nu_D(a) \langle \mathbf{v}_1, \mathbf{\Pi}(a, 0)\mathbf{x} \rangle da \\ \frac{\bar{\mathbf{S}}_T}{\bar{S}_D} \int_0^\infty \langle \beta_D(a), \mathbf{\Pi}(a, 0)\mathbf{x} \rangle da \end{pmatrix}$$

Since \mathcal{C} is a positive linear operator of finite-dimensional spaces, its spectral radius $\widehat{\mathcal{T}}_0$ is an eigenvalue. Moreover, let $\begin{pmatrix} \mathbf{x} \\ \mathbf{y} \end{pmatrix} \in \mathbb{R}^2 \times \mathbb{R}^3$ be a non zero vector such that $\mathcal{C} \begin{pmatrix} \mathbf{x} \\ \mathbf{y} \end{pmatrix} = \widehat{\mathcal{T}}_0 \begin{pmatrix} \mathbf{x} \\ \mathbf{y} \end{pmatrix}$.

Then we have the following system of equations

$$\begin{cases} \mathbf{v}_1 \int_0^\infty \beta_T(a) \langle \mathbf{1}, e^{-\mathbf{M}a} \mathbf{y} \rangle da + \mathbf{v}_2 \int_0^\infty \nu_D(a) \langle \mathbf{v}_1, \mathbf{\Pi}(a, 0)\mathbf{x} \rangle da = \widehat{\mathcal{T}}_0 \mathbf{x} \\ \frac{\bar{\mathbf{S}}_T}{\bar{S}_D} \int_0^\infty \langle \beta_D(a), \mathbf{\Pi}(a, 0)\mathbf{x} \rangle da = \widehat{\mathcal{T}}_0 \mathbf{y} \end{cases} \quad (7.16)$$

from where we obtain the equality

$$\mathbf{y} = \frac{1}{\widehat{\mathcal{T}}_0} \frac{\bar{\mathbf{S}}_T}{\bar{S}_D} \int_0^\infty \langle \beta_D(a), \mathbf{\Pi}(a, 0)\mathbf{x} \rangle da. \quad (7.17)$$

Hence, plugging (7.17) into the first equation of (7.16) gives

$$\begin{aligned} \mathbf{v}_1 \frac{1}{\widehat{\mathcal{T}}_0} \frac{1}{\overline{S}_D} \int_0^\infty \beta_T(a) \langle \mathbf{1}, e^{-\mathbf{M}a} \overline{\mathbf{S}}_T \rangle da \int_0^\infty \langle \boldsymbol{\beta}_D(a), \boldsymbol{\Pi}(a, 0) \mathbf{x} \rangle da \\ + \mathbf{v}_2 \int_0^\infty \nu_D(a) \langle \mathbf{v}_1, \boldsymbol{\Pi}(a, 0) \mathbf{x} \rangle da = \widehat{\mathcal{T}}_0 \mathbf{x}. \end{aligned}$$

Thus, setting $\mathbf{x} = x_1 \mathbf{v}_1 + x_2 \mathbf{v}_2$ and recalling that $\langle \boldsymbol{\beta}_D(a), \boldsymbol{\Pi}(a, 0) \mathbf{v}_1 \rangle = \beta_D^1(a) \pi_D(a)$, $\langle \boldsymbol{\beta}_D(a), \boldsymbol{\Pi}(a, 0) \mathbf{v}_2 \rangle = \beta_D^2(a) \pi_C(a)$, and $\langle \mathbf{v}_1, \boldsymbol{\Pi}(a, 0) \mathbf{v}_1 \rangle = \pi_D(a)$ we obtain by identification

$$\begin{cases} \frac{1}{\overline{S}_D} \int_0^\infty \beta_T(a) \langle \mathbf{1}, e^{-\mathbf{M}a} \overline{\mathbf{S}}_T \rangle da \int_0^\infty [x_1 \beta_D^1(a) \pi_D(a) + x_2 \beta_D^2(a) \pi_C(a)] da = \widehat{\mathcal{T}}_0^2 x_1 \\ x_1 \int_0^\infty \nu_D(a) \pi_D(a) da = \widehat{\mathcal{T}}_0 x_2 \end{cases}$$

so that

$$\begin{aligned} \frac{1}{\overline{S}_D} \int_0^\infty \beta_T(a) \langle \mathbf{1}, e^{-\mathbf{M}a} \overline{\mathbf{S}}_T \rangle da \left[x_1 \int_0^\infty \beta_D^1(a) \pi_D(a) da \right. \\ \left. + \frac{1}{\widehat{\mathcal{T}}_0} x_1 \int_0^\infty \nu_D(a) \pi_D(a) da \int_0^\infty \beta_D^2(a) \pi_C(a) da \right] = \widehat{\mathcal{T}}_0^2 x_1. \end{aligned} \quad (7.18)$$

From the above computations, we see that $\begin{pmatrix} x \\ y \end{pmatrix}$ is the null vector if and only if $x_1 = 0$. Therefore, the spectral radius of \mathcal{C} satisfies

$$\widehat{\mathcal{T}}_0^2 = \frac{1}{\widehat{\mathcal{T}}_0} \mathcal{T}_{0,2} + \mathcal{T}_{0,3} \quad (7.19)$$

with

$$\begin{cases} \mathcal{T}_{0,2} := \frac{1}{\overline{S}_D} \int_0^\infty \beta_T(a) \langle \mathbf{1}, e^{-\mathbf{M}a} \overline{\mathbf{S}}_T \rangle da \int_0^\infty \beta_D^1(a) \pi_D(a) da \\ \mathcal{T}_{0,3} := \frac{1}{\overline{S}_D} \int_0^\infty \beta_T(a) \langle \mathbf{1}, e^{-\mathbf{M}a} \overline{\mathbf{S}}_T \rangle da \int_0^\infty \nu_D(a) \pi_D(a) da \int_0^\infty \beta_D^2(a) \pi_C(a) da. \end{cases}$$

Next, observe that $\widehat{\mathcal{T}}_0$ defined in (3.11) is also given by $\widehat{\mathcal{T}}_0 = \mathcal{T}_{0,2} + \mathcal{T}_{0,3}$. Moreover, by similar computations, one obtains that the non-zero eigenvalues of \mathcal{C} satisfy

$$\lambda^3 = \mathcal{T}_{0,2} + \lambda \mathcal{T}_{0,3}. \quad (7.20)$$

To prove that $\widehat{\mathcal{T}}_0 - 1$ and $\mathcal{T}_0 - 1$ have the same sign, we will make use of (7.19) and (7.20). Indeed if $\widehat{\mathcal{T}}_0 = 1$ then (7.19) implies that $\mathcal{T}_0 = 1$. If $\mathcal{T}_0 = 1$ then (7.20) becomes $\lambda^3 = (1 - \mathcal{T}_{0,3}) + \lambda \mathcal{T}_{0,3}$ with $1 - \mathcal{T}_{0,3} \geq 0$ so that the non-zero solution of (7.20) have modulus less than one. This proves that $\widehat{\mathcal{T}}_0 = 1$ whenever $\mathcal{T}_0 = 1$. To complete the proof, we observe that if $\mathcal{T}_0 > 1$ then (7.19) implies that $1 < \mathcal{T}_0^2 = \frac{1}{\widehat{\mathcal{T}}_0} \mathcal{T}_{0,2} + \mathcal{T}_{0,3} < \mathcal{T}_{0,2} + \mathcal{T}_{0,3} = \mathcal{R}_0$. Similarly if $\mathcal{T}_0 < 1$ then $\mathcal{R}_0 < 1$. \square

8 Proof of Theorem 3.4

In order to determine the endemic equilibrium of the model (3.3)-(3.4), we proceed in several steps. In the first step, we give an equivalent system to (8.1), the second step is concerned with the solvability of (8.2), and the last step concerns the bifurcation properties. In this section,

we will always suppose that Assumption 3.1 is satisfied and $\mathcal{R}_{ST}^0 > 1$. Let us note that using the notation (3.14) together with Theorem 3.2, one knows that an endemic equilibrium \mathcal{E}^* defined in (3.15) satisfies

$$\begin{cases} 0 = r_E \left(1 - \frac{S_{TE}^*}{K}\right) \left(\langle \mathbf{S}_T^*, \mathbf{e}_3 \rangle + \int_0^\infty \langle \mathbf{i}_T^*(a), \mathbf{e}_3 \rangle da\right) - (\alpha_E + \mu_E) S_{TE}^* \\ \mathbf{i}_T^*(a) = \frac{1}{N_D^*} \int_0^\infty \langle \beta_D(a), \mathbf{i}_D^*(a) \rangle da e^{-\mathbf{M}a} \mathbf{S}_T^* \\ 0_{\mathbb{R}^3} = \alpha_E S_{TE}^* \mathbf{e}_1 - \frac{1}{N_D^*} \int_0^\infty \langle \beta_D(a), \mathbf{i}_D^*(a) \rangle da \mathbf{S}_T^* - \mathbf{M} \mathbf{S}_T^* \end{cases} \quad (8.1)$$

and

$$\begin{cases} 0 = \theta_D - \frac{S_D^*}{N_D^*} \int_0^\infty \beta_T(a) \langle \mathbf{1}, \mathbf{i}_T^*(a) \rangle da - \mu_D S_D^* \\ \mathbf{i}_D^*(a) = \frac{S_D^* + \epsilon R_D^*}{N_D^*} \int_0^\infty \beta_T(a) \langle \mathbf{1}, \mathbf{i}_T^*(a) \rangle da \pi_D(a) \mathbf{v}_1 \\ \quad + \int_0^\infty \nu_D(\tau) \langle \mathbf{v}_1, \mathbf{i}_D^*(a) \rangle da \pi_C(a) \mathbf{v}_2 \\ 0 = \int_0^\infty \gamma(a) \langle \mathbf{v}_1, \mathbf{i}_D^*(a) \rangle da - \epsilon \frac{R_D^*}{N_D^*} \int_0^\infty \beta_T(a) \langle \mathbf{1}, \mathbf{i}_T^*(a) \rangle da - \mu_D R_D^* \\ 0 = \theta_D - \mu_D N_D^* - \int_0^\infty \delta_D(a) \langle \mathbf{v}_1, \mathbf{i}_D^*(a) \rangle da - \int_0^\infty \delta_C(a) \langle \mathbf{v}_2, \mathbf{i}_D^*(a) \rangle da. \end{cases} \quad (8.2)$$

On the stationary states of ticks: Let us first prove the following lemma which describes the stationary states of the eggs.

Lemma 8.1. *The total number of eggs remains unchanged at the endemic and the disease-free equilibrium i.e $\bar{S}_{TE}^* = \bar{S}_{TE}$. Moreover, we always have*

$$\mathbf{S}_T^* + \int_0^\infty \mathbf{i}_T^*(a) da = \bar{\mathbf{S}}_T. \quad (8.3)$$

Proof. Note that, using the third equation of (8.1) we have

$$0_{\mathbb{R}^3} = \alpha_E S_{TE} \mathbf{M}^{-1} \mathbf{e}_1 - \frac{1}{N_D^*} \int_0^\infty \langle \beta_D(a), \mathbf{i}_D^*(a) \rangle da \mathbf{M}^{-1} \mathbf{S}_T^* - \mathbf{S}_T^* \quad (8.4)$$

Next, integrating the second equation of (8.1) it follows that

$$\begin{aligned} \int_0^\infty \mathbf{i}_T^*(a) da &= \frac{1}{N_D^*} \int_0^\infty \langle \beta_D(a), \mathbf{i}_D^*(a) \rangle da \int_0^\infty e^{-\mathbf{M}a} \mathbf{S}_T^* da \\ &= \frac{1}{N_D^*} \int_0^\infty \langle \beta_D(a), \mathbf{i}_D^*(a) \rangle da \mathbf{M}^{-1} \mathbf{S}_T^* \end{aligned} \quad (8.5)$$

Thus, by combining (8.4) and (8.5) we obtain

$$\int_0^\infty \mathbf{i}_T^*(a) da + \mathbf{S}_T^* = \alpha_E S_{TE}^* \mathbf{M}^{-1} \mathbf{e}_1 = \frac{S_{TE}^*}{\bar{S}_{TE}} \bar{\mathbf{S}}_T. \quad (8.6)$$

Therefore, plugging (8.6) in the first equation of (8.9) we obtain the following equality

$$0 = r_E \left(1 - \frac{S_{TE}^*}{K}\right) \frac{S_{TE}^*}{\bar{S}_{TE}} \langle \bar{\mathbf{S}}_T, \mathbf{e}_3 \rangle - (\alpha_E + \mu_E) S_{TE}^* \quad (8.7)$$

or equivalently

$$0 = r_E \left(1 - \frac{S_{TE}^*}{K} \right) \langle \bar{\mathbf{S}}_T, \mathbf{e}_3 \rangle - (\alpha_E + \mu_E) \bar{S}_{TE}. \quad (8.8)$$

The right-hand side of (8.8) is a decreasing function of S_{TE}^* so that the unique solution to (8.7) is $S_{TE}^* = \bar{S}_{TE}$. The equality (8.3) now follows from (8.6). \square

Thanks to Lemma 8.1 the system of equations (8.1) is equivalent to

$$\begin{cases} \mathbf{i}_T^*(a) = \frac{1}{N_D^*} \int_0^\infty \langle \boldsymbol{\beta}_D(a), \mathbf{i}_D^*(a) \rangle da e^{-\mathbf{M}a} \mathbf{S}_T^* \\ 0_{\mathbb{R}^3} = \alpha_E S_{TE} \mathbf{e}_1 - \frac{1}{N_D^*} \int_0^\infty \langle \boldsymbol{\beta}_D(a), \mathbf{i}_D^*(a) \rangle da \mathbf{S}_T^* - \mathbf{M} \mathbf{S}_T^*. \end{cases} \quad (8.9)$$

Note that for each nonnegative constant $\eta_0 \geq 0$ the matrix $\mathbf{M} + \eta_0 \mathbf{I}_3$ (where \mathbf{I}_3 is the identity operator on \mathbb{R}^3) is invertible with inverse $(\mathbf{M} + \eta_0 \mathbf{I}_3)^{-1}$ satisfying

$$(\mathbf{M} + \eta_0 \mathbf{I}_3)^{-1} \mathbf{e}_1 = \sum_{k=1}^3 \left(\prod_{j=1}^k \frac{\alpha_{j-1}}{\mu_j + \alpha_j + \eta_0} \right) \mathbf{e}_k, \quad \text{with } \alpha_0 = 1, \alpha_3 = 0, \quad (8.10)$$

and where the correspondence $L \leftarrow 1$, $N \leftarrow 2$, and $A \leftarrow 3$ is used. Therefore, using (8.9) together with (8.10), for $\eta_0 = \frac{1}{N_D^*} \int_0^\infty \langle \boldsymbol{\beta}_D(a), \mathbf{i}_D^*(a) \rangle da$, it follows that

$$\mathbf{S}_T^* = \alpha_E S_{TE} \sum_{k=1}^3 \mathbf{e}_k \prod_{j=1}^k \frac{N_D^* \alpha_{j-1}}{N_D^* (\mu_j + \alpha_j) + \int_0^\infty \langle \boldsymbol{\beta}_D(a), \mathbf{i}_D^*(a) \rangle da}, \quad (8.11)$$

with $\alpha_0 = 1$ and $\alpha_3 = 0$. Thus, recalling the expression of $\bar{\mathbf{S}}_T$ in (6.4) we obtain

$$\mathbf{S}_T^* = \sum_{k=1}^3 \langle \bar{\mathbf{S}}_T, \mathbf{e}_k \rangle \mathbf{e}_k \prod_{j=1}^k \frac{N_D^* (\mu_j + \alpha_j)}{N_D^* (\mu_j + \alpha_j) + \int_0^\infty \langle \boldsymbol{\beta}_D(a), \mathbf{i}_D^*(a) \rangle da} \quad (8.12)$$

and the system of equations (8.9) becomes equivalent to

$$\begin{cases} \mathbf{S}_T^* = \sum_{k=1}^3 \left(\prod_{j=1}^k \frac{\mu_j + \alpha_j}{(\mu_j + \alpha_j) + W_D^*} \right) \langle \bar{\mathbf{S}}_T, \mathbf{e}_k \rangle \mathbf{e}_k & (8.13a) \end{cases}$$

$$\begin{cases} \mathbf{i}_T^*(a) = W_D^\diamond e^{-\mathbf{M}a} \mathbf{S}_T^* & (8.13b) \end{cases}$$

$$\begin{cases} W_D^\diamond = \int_0^\infty \left\langle \boldsymbol{\beta}_D(a), \frac{\mathbf{i}_D^*(a)}{N_D^*} \right\rangle da. & (8.13c) \end{cases}$$

From the above comments, it follows that \mathbf{S}_T^* and \mathbf{i}_T^* are entirely determined by the variables W_D^\diamond and $\frac{\mathbf{i}_D^*}{N_D^*}$.

On the stationary states of dogs: In order to obtain an equivalent formulation to (8.2) we introduce the new variables

$$\mathbf{i}_D^\diamond(a) := \frac{\mathbf{i}_D^*(a)}{N_D^*}, \quad S_D^\diamond := \frac{S_D^*}{N_D^*} \quad \text{and} \quad R_D^\diamond := \frac{R_D^*}{N_D^*}. \quad (8.14)$$

Next, we set

$$P_T^* := \int_0^\infty \beta_T(a) \langle \mathbf{1}, \mathbf{i}_T^*(a) \rangle da, \quad (8.15)$$

and

$$\begin{cases} P_D^\diamond := \int_0^\infty \gamma(a) \langle \mathbf{v}_1, \mathbf{i}_D^\diamond(a) \rangle da \\ Q_D^\diamond := \int_0^\infty \nu_D(a) \langle \mathbf{v}_1, \mathbf{i}_D^\diamond(a) \rangle da, \\ U_D^\diamond := \int_0^\infty \delta_D(a) \langle \mathbf{v}_1, \mathbf{i}_D^*(a) \rangle da \\ U_C^\diamond := \int_0^\infty \delta_C(a) \langle \mathbf{v}_2, \mathbf{i}_D^*(a) \rangle da \end{cases} \quad (8.16)$$

With these new variables, system (8.2) becomes

$$\begin{cases} 0 = \theta_D - S_D^\diamond P_T^* - \mu_D N_D^* S_D^\diamond \\ N_D^* \mathbf{i}_D^\diamond(a) = (S_D^\diamond + \epsilon R_D^\diamond) P_T^* \pi_D(a) \mathbf{v}_1 + N_D^* Q_D^\diamond \pi_C(a) \mathbf{v}_2 \\ 0 = N_D^* P_D^\diamond - \epsilon R_D^\diamond P_T^* - \mu_D N_D^* R_D^\diamond \\ 0 = \theta_D - \mu_D N_D^* - N_D^* U_D^\diamond - N_D^* U_C^\diamond \end{cases} \quad (8.17)$$

which is equivalent to

$$\begin{cases} N_D^* = \frac{\theta_D}{\mu_D + U_D^\diamond + U_C^\diamond} \\ S_D^\diamond = \frac{\theta_D}{\mu_D N_D^* + P_T^*} \\ R_D^\diamond = \frac{N_D^* P_D^\diamond}{\epsilon P_T^* + \mu_D N_D^*} \\ \mathbf{i}_D^\diamond(a) = \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} P_T^* \pi_D(a) \mathbf{v}_1 + Q_D^\diamond \pi_C(a) \mathbf{v}_2. \end{cases} \quad (8.18)$$

Next, we show the relationship between P_T^* and W_D^\diamond defined respectively in (8.13c) and (8.15). To do so, we integrate (8.13b) to obtain

$$P_T^* = W_D^\diamond \int_0^\infty \beta_T(a) \langle \mathbf{1}, e^{-\mathbf{M}a} \mathbf{S}_T^* \rangle da \quad (8.19)$$

and by using the expression of \mathbf{S}_T^* defined in (8.13a) we obtain the following more explicit formula

$$P_T^* = W_D^\diamond \sum_{k=1}^3 \left(\prod_{j=1}^k \frac{\mu_j + \alpha_j}{(\mu_j + \alpha_j) + W_D^\diamond} \right) \frac{\bar{S}_k}{\sum_{j \in \mathcal{S} \setminus \{E\}} \bar{S}_j} \mathcal{T}_{0k}^{T \rightarrow D} \bar{S}_D, \quad (8.20)$$

with $\mathcal{T}_{0k}^{T \rightarrow D}$ the k 's stage vectorial capacity defined in (3.13).

In the following, we determine the equations for the variables P_D^\diamond , Q_D^\diamond , U_D^\diamond , U_C^\diamond and W_C^\diamond defined in (8.16). To this end, recalling that $\beta_D(a) = \beta_D^1(a) \mathbf{v}_1 + \beta_D^2(a) \mathbf{v}_1$, we use successively the equation of $\mathbf{i}_D^\diamond(a)$ in (8.18) to obtain

$$\left\{ \begin{aligned} W_D^\diamond &= \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} P_T^* \int_0^\infty \beta_D^1(a) \pi_D(a) da \end{aligned} \right. \quad (8.21a)$$

$$\left\{ \begin{aligned} &+ Q_D^\diamond \int_0^\infty \beta_D^2(a) \pi_C(a) da \end{aligned} \right. \quad (8.21b)$$

$$\left\{ \begin{aligned} P_D^\diamond &= \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} P_T^* \int_0^\infty \gamma(a) \pi_D(a) da \end{aligned} \right. \quad (8.21c)$$

$$\left\{ \begin{aligned} Q_D^\diamond &= \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} P_T^* \int_0^\infty \nu_D(a) \pi_D(a) da \end{aligned} \right. \quad (8.21d)$$

$$\left\{ \begin{aligned} U_D^\diamond &= \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} P_T^* \int_0^\infty \delta_D(a) \pi_D(a) da \end{aligned} \right. \quad (8.21e)$$

$$\left\{ \begin{aligned} U_C^\diamond &= \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} P_T^* \int_0^\infty \delta_C(a) \pi_C(a) da. \end{aligned} \right. \quad (8.21f)$$

Note that, plugging (8.21d) into (8.21a) gives the following equality

$$\left\{ \begin{aligned} W_D^\diamond &= \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} P_T^* \left[\int_0^\infty \beta_D^1(a) \pi_D(a) da \right. \\ &\quad \left. + \int_0^\infty \nu_D(a) \pi_D(a) da \int_0^\infty \beta_D^2(a) \pi_C(a) da \right]. \end{aligned} \right. \quad (8.22)$$

Let us now define the function

$$f(W_D^\diamond) := \sum_{k=1}^3 \left(\prod_{j=1}^k \frac{\mu_j + \alpha_j}{(\mu_j + \alpha_j) + W_D^\diamond} \right) \frac{\bar{S}_k}{\sum_{j \in \mathcal{S} \setminus \{E\}} \bar{S}_j} \mathcal{T}_{0^k}^{T \rightarrow D} \bar{S}_D \quad (8.23)$$

and observe that the vectorial capacity $\mathcal{T}_0^{T \rightarrow D}$ is given by

$$\mathcal{T}_0^{T \rightarrow D} = \frac{f(0)}{\bar{S}_D} \quad (8.24)$$

so that

$$\left\{ \begin{aligned} \mathcal{T}_0 &= \frac{f(0)}{\bar{S}_D} \left[\int_0^\infty \beta_D^1(a) \pi_D(a) da \right. \\ &\quad \left. + \int_0^\infty \nu_D(a) \pi_D(a) da \int_0^\infty \beta_D^2(a) \pi_C(a) da \right]. \end{aligned} \right. \quad (8.25)$$

In the following, we rewrite our system of equations by using the variable

$$K := \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} \frac{P_T^*}{\mathcal{T}_0^{T \rightarrow D}}. \quad (8.26)$$

To do so, we first observe that (8.22) and (8.20) take respectively the following form

$$W_D^\diamond = K \mathcal{T}_0 \quad \text{and} \quad P_T^* = W_D^\diamond f(W_D^\diamond) = K \mathcal{T}_0 f(K \mathcal{T}_0) \quad (8.27)$$

while (8.21) is now given by

$$\left\{ \begin{aligned} W_D^\diamond &= \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} P_T^* \int_0^\infty \beta_D^1(a) \pi_D(a) da & (8.28a) \\ &+ Q_D^\diamond \int_0^\infty \beta_D^2(a) \pi_C(a) da & (8.28b) \\ P_D^\diamond &= K \mathcal{T}_0^{T \rightarrow D} \int_0^\infty \gamma(a) \pi_D(a) da & (8.28c) \\ Q_D^\diamond &= K \mathcal{T}_0^{T \rightarrow D} \int_0^\infty \nu_D(a) \pi_D(a) da & (8.28d) \\ U_D^\diamond &= K \mathcal{T}_0^{T \rightarrow D} \int_0^\infty \delta_D(a) \pi_D(a) da & (8.28e) \\ U_C^\diamond &= K \mathcal{T}_0^{T \rightarrow D} \int_0^\infty \delta_C(a) \pi_C(a) da. & (8.28f) \end{aligned} \right.$$

Hence, using the first equation of (8.18) together with (8.28e), and (8.28f) we obtain the following necessary conditions

$$N_D^*(K) := \frac{\theta_D}{\mu_D + K \mathcal{T}_0^{T \rightarrow D} (\int_0^\infty \delta_D(a) \pi_D(a) da + \int_0^\infty \delta_C(a) \pi_C(a) da)}. \quad (8.29)$$

Furthermore, the second, third and fourth equation of (8.18) together with (8.27), (8.28c) and (8.28d) provide

$$\left\{ \begin{aligned} R_D^\diamond(\mathcal{T}_0, K) &:= \mathcal{T}_0^{T \rightarrow D} \frac{K N_D^*(K)}{\epsilon K \mathcal{T}_0 f(K \mathcal{T}_0) + \mu_D N_D^*(K)} \int_0^\infty \gamma(a) \pi_D(a) da & (8.30a) \\ S_D^\diamond(\mathcal{T}_0, K) &:= \frac{\theta_D}{\mu_D N_D^*(K) + K \mathcal{T}_0 f(K \mathcal{T}_0)} & (8.30b) \\ i_D^\diamond(a) &:= K \mathcal{T}_0^{T \rightarrow D} \pi_D(a) \mathbf{v}_1 + K \mathcal{T}_0^{T \rightarrow D} \int_0^\infty \nu_D(a) \pi_D(a) da \pi_C(a) \mathbf{v}_2. & (8.30c) \end{aligned} \right.$$

Moreover, from the equality $P_T^* = K \mathcal{T}_0 f(K \mathcal{T}_0)$ and (8.26) it comes that for $K > 0$ we must have the following equality

$$1 = \frac{S_D^\diamond(\mathcal{T}_0, K) + \epsilon R_D^\diamond(\mathcal{T}_0, K)}{N_D^*(K)} \frac{f(K \mathcal{T}_0)}{\mathcal{T}_0^{T \rightarrow D}} \mathcal{T}_0. \quad (8.31)$$

Recalling that we have the necessary condition $S_D^\diamond + R_D^\diamond + \int_0^\infty \langle \mathbf{1}, i_D^\diamond(a) \rangle da = 1$, we consider the following equation

$$\Delta(\mathcal{T}_0, K) = 1$$

with

$$\Delta(\mathcal{T}_0, K) := \frac{1 - (1 - \epsilon) R_D^\diamond(\mathcal{T}_0, K) - I_D^\diamond(\mathcal{T}_0, K)}{N_D^*(K)} \frac{f(K \mathcal{T}_0)}{\mathcal{T}_0^{T \rightarrow D}} \mathcal{T}_0 \quad (8.32)$$

and

$$I_D^\diamond(\mathcal{T}_0, K) := K \mathcal{T}_0^{T \rightarrow D} \int_0^\infty \pi_D(a) da + K \mathcal{T}_0^{T \rightarrow D} \int_0^\infty \nu_D(a) \pi_D(a) da \int_0^\infty \pi_C(a) da. \quad (8.33)$$

Lemma 8.2. *There exists an endemic equilibrium to (3.3)-(3.4) if and only if there exists $K > 0$ such that $\Delta(\mathcal{T}_0, K) = 1$.*

Proof. The necessity of the lemma follows from the preceding arguments. Next, we prove the sufficiency. To this end, assume that there exists $K > 0$ such that $\Delta(\mathcal{T}_0, K) = 1$. Let N_D^* be given by the right-hand side of (8.29). Let R_D^\diamond and \mathbf{i}_D^\diamond be given respectively by the right-hand side of (8.30a) and (8.30c). Observe that with these definitions we have

$$I_D^\diamond(\mathcal{T}_0, K) = \int_0^\infty \langle \mathbf{1}, \mathbf{i}_D^\diamond \rangle da \quad (8.34)$$

so that setting

$$S_D^\diamond := 1 - R_D^\diamond - I_D^\diamond(\mathcal{T}_0, K) \quad (8.35)$$

it comes from (8.32)

$$1 = \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} \frac{f(K\mathcal{T}_0)}{\mathcal{T}_0^{T \rightarrow D}} \mathcal{T}_0. \quad (8.36)$$

Note that setting $W_D^\diamond = K\mathcal{T}_0$, $P_T^* = W_D^\diamond f(W_D^\diamond)$, with f defined in (8.23), and multiplying (8.36) by K it follows that

$$K = \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} \frac{P_T^*}{\mathcal{T}_0^{T \rightarrow D}} \quad \text{and} \quad W_D^\diamond = \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} \frac{P_T^*}{\mathcal{T}_0^{T \rightarrow D}} \mathcal{T}_0. \quad (8.37)$$

Therefore, our definition of R_D^\diamond and \mathbf{i}_D^\diamond respectively in (8.30a) and (8.30c) together with (8.37) give us

$$\begin{cases} R_D^\diamond = \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} P_T^* \frac{N_D^*}{\epsilon P_T^* + \mu_D N_D^*} \int_0^\infty \gamma(a) \pi_D(a) da \\ \mathbf{i}_D^\diamond(a) = \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} P_T^* \pi_D(a) \mathbf{v}_1 + \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} P_T^* \int_0^\infty \nu_D(a) \pi_D(a) da \pi_C(a) \mathbf{v}_2. \end{cases} \quad (8.38)$$

Moreover, using (8.37) one also note that our definition of N_D^* in (8.29) leads to

$$\begin{aligned} \mu_D N_D^* &= \theta_D - (S_D^\diamond + \epsilon R_D^\diamond) P_T^* \int_0^\infty \delta_D(a) \pi_D(a) da \\ &\quad - (S_D^\diamond + \epsilon R_D^\diamond) P_T^* \int_0^\infty \delta_C(a) \pi_C(a) da. \end{aligned} \quad (8.39)$$

Next, we observe that the R_D^\diamond -equation in (8.38) is equivalent to

$$\mu_D N_D^* R_D^\diamond = -\epsilon P_T^* R_D^\diamond + (S_D^\diamond + \epsilon R_D^\diamond) P_T^* \int_0^\infty \gamma(a) \pi_D(a) da. \quad (8.40)$$

Note that from the above formulas of R_D^\diamond and \mathbf{i}_D^\diamond in (8.38) we have the following identities

$$\begin{cases} \int_0^\infty \nu_D(a) \langle \mathbf{v}_1, \mathbf{i}_D^\diamond(a) \rangle da = \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} P_T^* \int_0^\infty \nu_D(a) \pi_D(a) da \\ \int_0^\infty \gamma(a) \langle \mathbf{v}_1, \mathbf{i}_D^\diamond(a) \rangle da = \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} P_T^* \int_0^\infty \gamma(a) \pi_D(a) da \\ \int_0^\infty \delta_D(a) \langle \mathbf{v}_1, \mathbf{i}_D^\diamond(a) \rangle da = \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} P_T^* \int_0^\infty \delta_D(a) \pi_D(a) da \\ \int_0^\infty \delta_C(a) \langle \mathbf{v}_2, \mathbf{i}_D^\diamond(a) \rangle da = \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} P_T^* \int_0^\infty \nu_D(a) \pi_D(a) da \\ \quad \times \int_0^\infty \delta_C(a) \pi_C(a) da \end{cases} \quad (8.41)$$

from where we can rewrite (8.39), (8.40) and the \mathbf{i}_D^* -equation in (8.38) as follow

$$\begin{cases} \mu_D N_D^* &= \theta_D - N_D^* \int_0^\infty \delta_D(a) \langle \mathbf{v}_1, \mathbf{i}_D^\diamond(a) \rangle da - N_D^* \int_0^\infty \delta_C(a) \langle \mathbf{v}_2, \mathbf{i}_D^\diamond(a) \rangle da \\ \mu_D N_D^* R_D^\diamond &= -\epsilon P_T^* R_D^\diamond + N_D^* \int_0^\infty \gamma(a) \langle \mathbf{v}_1, \mathbf{i}_D^\diamond(a) \rangle da \\ \mathbf{i}_D^\diamond(a) &= \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} P_T^* \pi_D(a) \mathbf{v}_1 + \int_0^\infty \nu_D(a) \langle \mathbf{v}_1, \mathbf{i}_D^\diamond(a) \rangle da \pi_C(a) \mathbf{v}_2. \end{cases} \quad (8.42)$$

Next, observe that

$$\begin{cases} \mathbf{i}_D^\diamond(a)' &= -(\mu_D + \boldsymbol{\theta}(a)) \mathbf{i}_D^\diamond(a) \\ \mathbf{i}_D^\diamond(0) &= \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} P_T^* \mathbf{v}_1 + \int_0^\infty \nu_D(a) \langle \mathbf{v}_1, \mathbf{i}_D^\diamond(a) \rangle da \mathbf{v}_2 \end{cases} \quad (8.43)$$

so that by integrating (8.43) from 0 to $+\infty$ we obtain

$$-\frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} P_T^* \mathbf{v}_1 - \int_0^\infty \nu_D(a) \langle \mathbf{v}_1, \mathbf{i}_D^\diamond(a) \rangle da \mathbf{v}_2 = - \int_0^\infty (\mu_D + \boldsymbol{\theta}(a)) \mathbf{i}_D^\diamond(a) da$$

and by using (8.41) it follows that

$$\begin{aligned} \mu_D \int_0^\infty \langle \mathbf{1}, \mathbf{i}_D^\diamond(a) \rangle da &= \frac{S_D^\diamond + \epsilon R_D^\diamond}{N_D^*} P_T^* - \int_0^\infty (\gamma(a) + \delta_D(a)) \langle \mathbf{v}_1, \mathbf{i}_D^\diamond(a) \rangle da \\ &\quad - \int_0^\infty \delta_C(a) \langle \mathbf{v}_2, \mathbf{i}_D^\diamond(a) \rangle da. \end{aligned} \quad (8.44)$$

Next, multiply (8.45) by N_D^* and use the first equation of (8.42) to obtain

$$\mu_D N_D^* \int_0^\infty \langle \mathbf{1}, \mathbf{i}_D^\diamond(a) \rangle da = (S_D^\diamond + \epsilon R_D^\diamond) P_T^* - \theta_D + \mu_D N_D^* - N_D^* \int_0^\infty \gamma(a) \langle \mathbf{v}_1, \mathbf{i}_D^\diamond(a) \rangle da \quad (8.45)$$

Hence, summing (8.45) and the second equation of (8.42) it follows that

$$\begin{aligned} S_D^\diamond P_T^* - \theta_D + \mu_D N_D^* &= \mu_D N_D^* \int_0^\infty \langle \mathbf{1}, \mathbf{i}_D^\diamond(a) \rangle da + \mu_D N_D^* R_D^\diamond \\ &= \mu_D N_D^* (1 - S_D^\diamond) \end{aligned} \quad (8.46)$$

that is

$$0 = \theta_D - S_D^\diamond P_T^* - \mu_D N_D^* S_D^\diamond \iff S_D^\diamond = \frac{\theta_D}{\mu_D N_D^* + P_T^*}. \quad (8.47)$$

Finally, we infer from the \mathbf{i}_D^\diamond -equation of (8.42), the equality (8.47) together with our definition of R_D^\diamond , and N_D^* that (8.18) is satisfied. The proof is completed by using the fact that we have set $P_T^* = W_D^\diamond f(W_D^\diamond)$ with $W_D^\diamond = K \mathcal{T}_0$ and f given by (8.23). \square

Thanks to Lemma 8.2, the existence of positive equilibrium to (3.3)-(3.4) is subjected to the existence of $K > 0$ such that

$$\Delta(\mathcal{T}_0, K) = 1 \quad (8.48)$$

where $\Delta(\mathcal{T}_0, K)$ is given by (8.32) and (8.33). Before studying the existence of solution to (8.48), we first observe that from (8.29), (8.30) and (8.33) we have

$$\begin{cases} N_D^*(0) = \frac{\theta_D}{\mu_D} = \bar{S}_D \\ R_D^\diamond(\mathcal{T}_0, 0) = I_D^\diamond(\mathcal{T}_0, 0) = 0, \quad \forall \mathcal{T}_0 \geq 0. \end{cases} \quad (8.49)$$

We also note that for each $\mathcal{T}_0 > 0$ we have

$$\lim_{K \rightarrow +\infty} R_D^\circ(\mathcal{T}_0, K) = l > 0 \quad \text{and} \quad \lim_{K \rightarrow +\infty} I_D^\circ(\mathcal{T}_0, K) = +\infty \quad (8.50)$$

with

$$l := \frac{1}{\epsilon \mathcal{T}_0^{T \rightarrow D}} \frac{\theta_D \int_0^\infty \gamma(a) \pi_D(a) da}{\int_0^\infty \delta_D(a) \pi_D(a) da + \int_0^\infty \delta_C(a) \pi_C(a) da}.$$

Therefore, using the equality $\mathcal{T}_0^{T \rightarrow D} = \frac{f(0)}{\bar{S}_D}$ it follows from (8.49) and (8.32) that

$$\Delta(\mathcal{T}_0, 0) = \mathcal{T}_0 \quad \text{and} \quad \lim_{K \rightarrow +\infty} \Delta(\mathcal{T}_0, K) = -\infty. \quad (8.51)$$

It is now clear from (8.51) that for each $\mathcal{T}_0 > 0$ there exists $\bar{K} := \bar{K}(\mathcal{T}_0) > 0$ such that $\Delta(\mathcal{T}_0, \bar{K}) = 0$. In particular, if $\mathcal{T}_0 > 1$ then there exists $K_0 \in (0, \bar{K})$ such that $\Delta(\mathcal{T}_0, K_0) = 1$ leading to the existence of an endemic equilibrium.

On the forward and backward bifurcations: In the following, we deal with the existence of forward and backward bifurcation at $\mathcal{T}_0 = 1$. Roughly speaking, we have to prove that there exists a positive map K_0 defined in some right neighborhood (forward bifurcation) or left neighborhood (backward bifurcation) of $\mathcal{T}_0 = 1$ such that $\Delta(\mathcal{T}_0, K_0(\mathcal{T}_0)) = 1$ and $K_0(1) = 0$. Since $\Delta(1, 0) = 1$, one can prove the existence of forward and backward bifurcations using implicit function theorem which is reduced here to the study of $\partial_K \Delta(1, 0)$. This motivates the following lemma.

Lemma 8.3. *The following property is satisfied*

$$\partial_{\mathcal{T}_0} \Delta(\mathcal{T}_0, 0) = 1, \quad \forall \mathcal{T}_0 > 0 \quad (8.52)$$

and

$$\begin{aligned} \partial_K \Delta(1, 0) &= \frac{1}{\mu_D} \mathcal{T}_0^{T \rightarrow D} \left(\int_0^\infty \delta_D(a) \pi_D(a) da + \int_0^\infty \delta_C(a) \pi_C(a) da \right) \\ &\quad - \sum_{k=1}^3 \left(\sum_{j=1}^k \frac{1}{\mu_j + \alpha_j} \right) \frac{\bar{S}_k}{\sum_{j \in \mathcal{S} \setminus \{E\}} S_j} \frac{\mathcal{T}_{0k}^{T \rightarrow D}}{\mathcal{T}_0^{T \rightarrow D}} \\ &\quad - (1 - \epsilon) \frac{1}{\mu_D} \mathcal{T}_0^{T \rightarrow D} \int_0^\infty \gamma(a) \pi_D(a) da \\ &\quad - \mathcal{T}_0^{T \rightarrow D} \int_0^\infty \pi_D(a) da - \mathcal{T}_0^{T \rightarrow D} \int_0^\infty \nu_D(a) \pi_D(a) da \int_0^\infty \pi_C(a) da. \end{aligned}$$

Proof. Since $\Delta(\mathcal{T}_0, 0) = \mathcal{T}_0$ for each $\mathcal{T}_0 > 0$ the first equality of the lemma follows. To compute $\partial_K \Delta(1, 0)$, it is enough to take the derivative of $\Delta(1, K)$ with respect to K at $K = 0$. To do so let us first note that by using (8.32) we have

$$N_D^*(K) \Delta(1, K) = \frac{f(K)}{\mathcal{T}_0^{T \rightarrow D}} - [(1 - \epsilon) R_D^\circ(1, K) + I_D^\circ(1, K)] \frac{f(K)}{\mathcal{T}_0^{T \rightarrow D}}.$$

Recalling that $\Delta(1, 0) = 1$, $N_D^*(0) = \frac{\theta_D}{\mu_D} = \bar{S}_D$, $R_D^\circ(1, 0) = I_D^\circ(1, 0) = 0$ and taking the derivative of $N_D^*(K) \Delta(1, K)$ with respect to K at $K = 0$ it follows that

$$\bar{S}_D \partial_K \Delta(1, 0) = -\frac{dN_D^*(0)}{dK} + \frac{f'(0)}{\mathcal{T}_0^{T \rightarrow D}} - \bar{S}_D [(1 - \epsilon) \partial_K R_D^\circ(1, 0) + \partial_K I_D^\circ(1, 0)].$$

By straightforward computations, we obtain from (8.29) and (8.33) that

$$\frac{dN_D^*(0)}{dK} = -\frac{\bar{S}_D}{\mu_D} \mathcal{T}_0^{T \rightarrow D} \left(\int_0^\infty \delta_D(a) \pi_D(a) da + \int_0^\infty \delta_C(a) \pi_C(a) da \right)$$

and

$$\partial_K I_D^\diamond(1, 0) = \mathcal{T}_0^{T \rightarrow D} \int_0^\infty \pi_D(a) da + \mathcal{T}_0^{T \rightarrow D} \int_0^\infty \nu_D(a) \pi_C(a) da \int_0^\infty \pi_C(a) da.$$

To complete the proof it remains to compute $\partial_K R_D^\diamond(1, 0)$ and $f'(0)$. We first compute $\partial_K R_D^\diamond(1, 0)$. To this end, we compute the derivative of $R_D^\diamond(1, K)$ from (8.30a) with respect to K and set $K = 0$ to obtain

$$\partial_K R_D^\diamond(1, 0) = \frac{1}{\mu_D} \mathcal{T}_0^{T \rightarrow D} \int_0^\infty \gamma(a) \pi_D(a) da.$$

To compute $f'(0)$ recall that

$$f(W_D^\diamond) := \sum_{k=1}^3 \left(\prod_{j=1}^k \frac{\mu_j + \alpha_j}{(\mu_j + \alpha_j) + W_D^\diamond} \right) \frac{\bar{S}_k}{\sum_{j \in \mathcal{S} \setminus \{E\}} \bar{S}_j} \mathcal{T}_{0k}^{T \rightarrow D} \bar{S}_D$$

so that setting

$$\hat{f}_k(W_D^\diamond) := \prod_{j=1}^k g_j(W_D^\diamond), \quad k = 1, 2, 3, \quad g_j(W_D^\diamond) := \frac{\mu_j + \alpha_j}{(\mu_j + \alpha_j) + W_D^\diamond}$$

we obtain

$$f(W_D^\diamond) := \sum_{k=1}^3 \hat{f}_k(W_D^\diamond) \frac{\bar{S}_k}{\sum_{j \in \mathcal{S} \setminus \{E\}} \bar{S}_j} \mathcal{T}_{0k}^{T \rightarrow D} \bar{S}_D.$$

Therefore, computing the derivative of $\ln(\hat{f}_k(W_D^\diamond))$ one obtains

$$\hat{f}_k'(W_D^\diamond) = \hat{f}_k(W_D^\diamond) \sum_{j=1}^k \frac{g_j'(W_D^\diamond)}{g_j(W_D^\diamond)}$$

and since $\hat{f}_k(0) = g_k(0) = 1$ it follows that

$$\hat{f}_k'(0) = \sum_{j=1}^k g_j'(0) = -\sum_{j=1}^k \frac{1}{\mu_j + \alpha_j}$$

that is

$$f'(0) = -\sum_{k=1}^3 \left(\sum_{j=1}^k \frac{1}{\mu_j + \alpha_j} \right) \frac{\bar{S}_k}{\sum_{j \in \mathcal{S} \setminus \{E\}} \bar{S}_j} \mathcal{T}_{0k}^{T \rightarrow D} \bar{S}_D. \quad (8.53)$$

The proof is completed. \square

Thanks to Lemma 8.3 one knows that if $\partial_K \Delta(1, 0) = C_{\text{bif}}^{-1} \neq 0$ then by the implicit function theorem there exists $\xi \in (0, 1)$ and a smooth map $K_0 : (1 - \xi, 1 + \xi) \rightarrow \mathbb{R}$ such that

$$\Delta(\mathcal{T}_0, K_0(\mathcal{T}_0)) = 1, \quad \forall \mathcal{T}_0 \in (1 - \xi, 1 + \xi) \quad \text{and} \quad K_0(1) = 0. \quad (8.54)$$

Thus, up to reduce ξ , it follows that the sign of K_0 on $(1 - \xi, 1 + \xi)$ is given by the sign of $\frac{dK_0(\mathcal{T}_0)}{d\mathcal{T}_0}$ at $\mathcal{T}_0 = 1$. Differentiating (8.54) with respect to \mathcal{T}_0 and using Lemma 8.3 we obtain

$$\frac{dK_0(1)}{d\mathcal{T}_0} = -\frac{\partial_{\mathcal{T}_0}\Delta(1, 0)}{\partial_K\Delta(1, 0)} = -C_{\text{bif}}$$

so that

- If $C_{\text{bif}} > 0$ then, up to reduce ξ , we have $K_0(\mathcal{T}_0) > 0$ for $\mathcal{T}_0 \in (1 - \xi, 1)$ which corresponds to a backward bifurcation ;
- If $C_{\text{bif}} < 0$ then, up to reduce ξ , $K_0(\mathcal{T}_0) > 0$ for $\mathcal{T}_0 \in (1, 1 + \xi)$ which corresponds to a forward bifurcation.

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Conflicts of Interest

The authors declare that there is no conflict of interest regarding the publication of this paper.

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