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Around the asymptotic properties of a two-dimensional parametrized Euler flow

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Abstract

We study the two-dimensional Euler flow solution to $\partial_t X(\cdot, x) = b(X(\cdot, x))$ for x in the torus $\mathbb{T}^2 := \mathbb{R}^2/2\pi\mathbb{Z}^2$, where b is the vector field defined on \mathbb{T}^2 by

 $b(x) = b(x_1, x_2) := (-A \cos x_1 - B \sin x_2, A \sin x_1 + B \cos x_2)$ with $A, B \in \mathbb{R} \setminus \{0\}$. We derive for any $x \in \mathbb{T}^2$, the asymptotics of X(t, x) as t tends to ∞ , depending on whether |A| = |B| or $|A| \neq |B|$. In the first case, the orbits of the flow are all bounded. In the second case, it turns out that one of the coordinates of X(t, x) is bounded with an explicit bound, while the other one is equivalent to a(x)t. The function a does not vanish in \mathbb{T}^2 and satisfies uniform bounds which depend on parameters A, B. When $|A| \neq |B|$, we also prove that for any global first integral u of the flow X with a periodic gradient, ∇u has at least a cluster point of roots in \mathbb{T}^2 . This shows the complexity as well as the interest of this two-dimensional Euler flow.

Keywords: 2D Euler flow, asymptotic expansion, invariant measure, rotation set, first integral

Mathematics Subject Classification: 34E05, 34E10, 37C10, 37C40

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1 Introduction

In this paper we study the asymptotic behavior of the following two-dimensional Euler flow X(t, x), for x in the torus $\mathbb{T}^2 := \mathbb{R}^2/2\pi\mathbb{Z}^2$, solution to the ODEs system

$$\begin{cases} \partial_t X_1(t,x) &= -A \cos\left(X_1(t,x)\right) - B \sin\left(X_2(t,x)\right) &=: b_1\left(X(t,x)\right) \\ \partial_t X_2(t,x) &= A \sin\left(X_1(t,x)\right) + B \cos\left(X_2(t,x)\right) &=: b_2\left(X(t,x)\right), \end{cases} \quad t \in [0,\infty), \quad (1.1)$$

where A, B are two fixed non-zero real parameters.

The vector field b defined by (1.1) represents the velocity solution to the steady Euler equation (see, *e.g.*, [16])

$$\partial_t \omega + \psi_1 \,\omega_2 - \psi_2 \,\omega_1 = 0, \tag{1.2}$$

where the function ω denotes the (scalar) fluid vorticity, and ψ solution to $-\Delta \psi = \omega$, denotes the stream function. By definition (1.1) we have

$$\omega(x) = (\operatorname{curl} b)(x) = (\partial_{x_1} b_2 - \partial_{x_2} b_1)(x) = A \cos x_1 + B \cos x_2 \quad \text{and} \quad \psi(x) = \omega(x).$$

Conditions of non-linear stability for plane stationary flows were derived by Arnold [1, 2] in the Sixties. According to [16, 7] the study of the stability of the flow (1.1) is actually relevant for the atmospheric flows. For example, Saturn's E Ring may be regarded as a two-dimensional flat torus, considering as in [16] (see in particular [7, Section 1.4.] and the references therein) the non-stationary Euler equation (1.2).

First of all, note that the existence of a global first integral of system (1.1) having a periodic gradient of period $2\pi\mathbb{Z}^2$, is far to be evident. Indeed, when $|A| \neq |B|$, we prove (see Corollary 3.5) that for any first integral $u \in C^1(\mathbb{R}^2)$ of (1.1), *i.e.* satisfying

$$\forall x \in \mathbb{T}^2, \ \forall t \in [0, \infty), \quad u(X(t, x)) = u(x), \tag{1.3}$$

with a periodic gradient, the gradient ∇u has at least a cluster point in \mathbb{T}^2 . This strong constraint compared to the non vanishing property of the very simple vector field *b* associated with the flow *X* (1.1) makes difficult or even impossible the derivation of a global first integral of *X*, but in the same time shows the interest of the flow *X*.

In the present context, we focus on the asymptotic properties of the flow X through the limits

$$\lim_{t \to \infty} \frac{X(t,x)}{t} \quad \text{for any } x \in \mathbb{T}^2,$$
(1.4)

and on the probability measures on \mathbb{T}^2 which are invariant for this flow (see Section 3.1). Actually, these two notions are strongly connected in dimension two in view of the Misiurewicz-Ziemian [11, Theorem 3.4] in the case of general two-dimensional flows, or in view of the Peirone result [12, Theorem 3.1] (see also [13, Theorem 4.1]) in the case of the ODE's flow.

On the one hand, in Section 2 we provide (see Theorem 2.1) the limits (1.4) of the flow $X(\cdot, x)$ for each point $x \in \mathbb{T}^2$. Two cases have to be distinguished according to the non-zero parameters A, B (the case AB = 0 has been studied in [5, Section 5.3.1]):

- If we have |A| = |B|, then the flow X can be computed explicitly thanks to a change of variables (see formula (2.21)), which gives immediately the asymptotics of $X(\cdot, x)$.
- Otherwise we have $|A| \neq |B|$, then the general Lemma 2.5 combined with the case (2) of the proof of [12, Theorem 3.1] allows us to prove that one of the coordinate $X_i(\cdot, x)$, i = 1, 2, of the flow is bounded with an explicit bound, while the other one $X_{3-i}(t, x)$ is equivalent to a(x)t as $t \to \infty$ for some non-zero real a(x). We also provide (see the part *iii*) of Theorem 3.1) uniform bounds from below and above for a, which depend on the two parameters A, B.

On the other hand, in Section 3 we characterize in the case $|A| \neq |B|$ (see Theorem 3.1) the invariant probability measures on \mathbb{T}^2 for the flow X (1.1), *i.e.* the probability measures μ on \mathbb{T}^2 such that for any $t \in \mathbb{R}$, $\mu \circ X^{-1}(t, \cdot) = \mu \circ X(-t, \cdot) = \mu$ on \mathbb{T}^2 . We prove that there does not exist any invariant probability measure with Lebesgue's density $\sigma(x) dx$ where σ is a non-negative function in $L^1_{\sharp}(\mathbb{T}^2)$ satisfying some weak positivity condition (see (3.11)). Moreover, we obtain any limit (1.4) of $X(\cdot, x)$ as the mass of the vector field b by a singular probability measure depending on $x \in \mathbb{T}^2$.

Notation

- (e_1, e_2) denotes the canonical basis of \mathbb{R}^2 , and $0_{\mathbb{R}^2}$ denotes the null vector of \mathbb{R}^2 .
- I_2 is the unit matrix of $\mathbb{R}^{2\times 2}$.
- R_{\perp} denotes the (2×2) rotation matrix $\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$. For any $\xi \in \mathbb{R}^2$, ξ^{\perp} denotes the perpendicular vector $R_{\perp}\xi$.
- " \cdot " denotes the scalar product and $|\cdot|$ the euclidean norm in \mathbb{R}^2 .
- B(x, R) denotes the euclidean open ball of \mathbb{R}^2 centered on $x \in \mathbb{R}^2$ and of radius R > 0.
- dx denotes the Lebesgue measure on \mathbb{R}^2 .
- \mathbb{T}^k denotes the torus $\mathbb{R}^k/(2\pi\mathbb{Z}^k)$ for k=1,2.
- *M*[#](T²) denotes the set of Radon measures on the torus T², and *M*^p(T²) denotes the set
 of probability measures on T².
- $\mathscr{D}'(\Omega)$ denotes the set of the distributions on some open set Ω of \mathbb{R}^2 .
- $C_c^k(\mathbb{R}^2)$, $k \in \mathbb{N} \cup \{\infty\}$, denotes the space of the real-valued functions in $C^k(\mathbb{R}^2)$ with compact support in \mathbb{R}^2 .
- $C^k_{\sharp}(\mathbb{T}^2)$, resp. $W^{1,k}_{\sharp}(\mathbb{T}^2)$, $k \in \mathbb{N} \cup \{\infty\}$, denotes the space of the real-valued functions $f \in C^k(\mathbb{R}^2)$, resp. $f \in W^{1,k}_{\sharp}(\mathbb{R}^2)$ which are $2\pi \mathbb{Z}^2$ -periodic, *i.e.*

$$\forall k \in \mathbb{Z}^2, \ \forall x \in \mathbb{R}^2, \quad f(x + 2\pi k) = f(x).$$
(1.5)

• For any function $f \in L^1_{\sharp}(\mathbb{T}^2)$, we denote

$$\bar{f}^{x_1}(x_2) := \int_{\mathbb{T}^1} f(x_1, x_2) \, dx_1 \quad \text{and} \quad \bar{f} := \int_{\mathbb{T}^2} f(x) \, dx. \quad (1.6)$$

and for any Borel measure μ on \mathbb{T}^2 and any function $f \in L^1(\mathbb{T}^2, \mu)$, we denote

$$\mu(f) := \int_{\mathbb{T}^2} f(x) \,\mu(dx), \tag{1.7}$$

which is also extended to vector-valued functions in $L^1(\mathbb{T}^2,\mu)^2$.

• C denotes a positive constant which may vary from line to line.

2 Asymptotics of the flow

2.1 The main result

We have the following result.

Theorem 2.1. Let $A, B \in \mathbb{R} \setminus \{0\}$. Then, the flow X defined by (1.1) satisfies the following asymptotic alternative:

• Either we have $(-1)^i (|A| - |B|) < 0$ for some i = 1, 2. Then, we obtain that

$$\forall x \in \mathbb{T}^2, \quad \begin{cases} \left| X_i(\cdot, x) - x \right| < 2\pi & \text{in } [0, \infty) \\ \lim_{t \to \infty} \frac{X_{3-i}(t, x)}{t} = a(x) & \text{where } a(x) \neq 0. \end{cases}$$

$$(2.1)$$

• Or we have $B = \varepsilon A$ with $\varepsilon = \pm 1$. Then, for any $x \in \mathbb{T}^2$, the orbit $X(\mathbb{R}, x)$ is bounded in \mathbb{R}^2 . More precisely, defining the (2×2) matrix

$$J := \frac{1}{2} \begin{pmatrix} 1 & \varepsilon \\ -\varepsilon & 1 \end{pmatrix} \quad with \quad J^{-1} := \begin{pmatrix} 1 & -\varepsilon \\ \varepsilon & 1 \end{pmatrix}$$
(2.2)

and the closed grid of \mathbb{R}^2

$$\mathscr{G} := \left(\bigcup_{m \in \mathbb{Z}} \left[\frac{\pi}{4} + m\pi\right] \times \mathbb{R}\right) \bigcup \left(\bigcup_{n \in \mathbb{Z}} \mathbb{R} \times \left[\frac{\pi}{2} + n\pi\right]\right),\tag{2.3}$$

we get that

$$\forall i = 1, 2, \ \forall x \in J^{-1}(\mathbb{R}^2 \setminus \mathscr{G}), \quad \left| X_i(\cdot, x) - x_i \right| < 2\pi.$$
(2.4)

Remark 2.2. The asymptotic behavior is quite different between the cases $|A| \neq |B|$ and |A| = |B|. The reason of this difference is that the vector field b of (1.1) does not vanish in the case $|A| \neq |B|$ with no punctual orbit – see the preliminary step of the proof of [12, Theorem 3.1] – contrary to the case |A| = |B| which includes punctual orbits.

Remark 2.3. When A > 0 and B = 0, in [5, Section 5.3.1] we have got the following asymptotic expansion

$$X(t,x) = x - A t e_2 + O_K(1), \quad \forall t \in [0,\infty), \ \forall x \in K \times \mathbb{R},$$

$$(2.5)$$

where $O_K(1)$ is bounded uniformly with respect to $t \in [0, \infty)$, to $x_2 \in \mathbb{R}$, and to x_1 in any fixed compact set K of $\left(-\frac{\pi}{2}, \frac{\pi}{2}\right)$ modulo π . Expansion (2.5) can be thus regarded as a limit expansion as $B \to 0$ of (2.1). However, expansion (2.1) is finer than (2.5) for the coordinate $X_1(t, x)$, while it is the converse for the coordinate $X_2(t, x)$.

Remark 2.4. Assume that $(-1)^i (|A| - |B|) < 0$ for some i = 1, 2. Since the smooth vector field b associated with the flow X (1.1) satisfies

$$\forall x = (x_1, x_2) \in \mathbb{R}^2, \quad |b(x)|^2 = A^2 + B^2 + 2AB \sin(x_1 + x_2) \ge (|A| - |B|))^2 > 0, \quad (2.6)$$

it does not vanish in \mathbb{R}^2 . Then, applying the non-vanishing final argument of the proof of [3, Theorem 3.1] (¹) we deduce that the limit function *a* does not vanish either in \mathbb{T}^2 . Peirone's [12, Theorem 3.1] allows us to characterize more precisely the function *a* in (2.1). Indeed, following

¹This argument is based on the two-dimensional Franks [8, Theorem 3.5].

the case (1) of the proof of [12, Theorem 3.1], it turns out that for any $x \in \mathbb{T}^2$, there exist $T_x > 0$ and an integer $k_x \in \mathbb{Z} \setminus \{0\}$ such that the function a satisfies

$$a(x) = \frac{2\pi k_x}{T_x}.$$

Actually, there exists a periodic solution of period T_x in the torus \mathbb{T}^2 (rather than in the space \mathbb{R}^2) $X(\cdot, z_x)$ to (1.1) with $z_x \in \mathbb{T}^2$, satisfying

$$X(T_x, z_x) = z_x + 2\pi k_x e_{3-i}$$
 and $\lim_{t \to \infty} \frac{X(t, x)}{t} = a(x) e_{3-i}.$ (2.7)

However, it is not obvious to derive explicitly such a periodic solution Z, even for a simple system like (1.1).

There is an alternative to derive the limit (2.7). By virtue of [11, Theorem 2.4, 3.4] and [11, Remark 2.5] (see also [4, Appendix A]) involving the properties of the Herman rotation set [10] associated with a flow, for any $x \in \mathbb{T}^2$, there exists a probability measure μ_x on \mathbb{T}^2 invariant for the flow (1.1) such that

$$\lim_{t \to \infty} \frac{X(t,x)}{t} = \mu_x(b) = \int_{\mathbb{T}^2} b(y) \,\mu_x(dy).$$
(2.8)

Using Liouville's theorem (see, e.g., [14, Lecture 11]) the invariance of the probability measure μ_x is characterized by

$$\operatorname{div}\left(b\,\mu_x\right) = 0 \quad \text{in } \mathbb{T}^2. \tag{2.9}$$

But once again, it is difficult to get generally an explicit invariant probability measure for a given flow. This is the aim of Theorem 3.1 below for the two-dimensional Euler flow (1.1).

2.2 Proof of Theorem 2.1

2.2.1 Proof of the case $|A| \neq |B|$

The proof is based on the following general result.

Lemma 2.5. Let f be a function in $W^{1,\infty}_{\sharp}(\mathbb{R}/T\mathbb{Z})$, T > 0 (i.e. f is Lispschitz and periodic of period T in \mathbb{R}), let $x_0 \in \mathbb{R}$, and let x be a function in $C^1([0,\infty))$ such that $f(x(0)) \neq f(x_0)$. Then, we have the two following implications:

$$\begin{cases} x' + f(x) < f(x_0) & in [0, \infty) \Rightarrow x - x(0) < T & in [0, \infty), \\ x' + f(x) > f(x_0) & in [0, \infty) \Rightarrow x - x(0) > -T & in [0, \infty), \end{cases}$$
(2.10)

where $f(x) := f \circ x$.

Assume for instance that |A| > |B|, and set

$$\alpha := \frac{A}{|A|} = \pm 1 \quad \text{and} \quad \beta := \frac{B}{|A|} \in (-1, 1).$$
(2.11)

Then, consider the new coordinates y := x/|A| which leads us to the flow Y(t, y) := X(t, x)/|A| solution to the ODEs system

$$\begin{cases} \partial_t Y_1(t,y) = -\alpha \cos\left(|A|Y_1(t,y)\right) - \beta \sin\left(|A|Y_2(t,y)\right) \\ \partial_t Y_2(t,y) = \alpha \sin\left(|A|Y_1(t,y)\right) + \beta \cos\left(|A|Y_2(t,y)\right). \end{cases}$$
(2.12)

Fix $y = (y_1, y_2) \in \mathbb{R}^2$, and let $\theta \in [0, \pi/|A|]$ be such that

$$|\beta| < \alpha \, \cos(|A|\,\theta) \neq \pm \,\alpha \, \cos(|A|\,y_1).$$

Then, the first equation of (2.12) implies that

$$\begin{cases} \left| \partial_t Y_1(\cdot, y) + \alpha \cos\left(|A| Y_1(\cdot, y) \right) \right| < \alpha \cos(|A| \theta) & \text{in } [0, \infty) \\ \cos(|A| \theta) \neq \pm \cos(|A| y_1). \end{cases}$$

Therefore, applying the first inequality of (2.10) to the function $x(\cdot) := Y_1(\cdot, y_1)$ with $x_0 := \theta$ and $f(\cdot) := \alpha \cos(|A| \cdot)$ (which is |A|-Lipschitz and periodic of period $T := 2\pi/|A|$ in \mathbb{R}), then applying the second inequality of (2.10) to the function $x(\cdot) := Y_1(\cdot, y_1)$ with $x_0 := \pi/|A| - \theta$ and f, we get that

$$|Y_1(\cdot, y) - y_1| < T \text{ in } [0, \infty),$$

which implies the first estimate of (2.1) for i = 1. The proof is quite similar for i = 3, replacing Y_1 by Y_2 and permuting the roles of A and B.

On the other hand, let i := 1, 2. Then, recalling Remark 2.4 combined with the first estimate of (2.1) (we have just proved before) we get that for any $x \in \mathbb{T}^2$,

$$\exists \lim_{t \to \infty} \frac{X(t,x)}{t} \neq 0_{\mathbb{R}^2} \quad \text{and} \quad \lim_{t \to \infty} \frac{X_i(t,x)}{t} = 0,$$

which yields immediately the limit of (2.1).

Therefore, the proof of the case $|A| \neq |B|$ is done.

Proof of Lemma 2.5. First of all, there exists a unique $n \in \mathbb{Z}$ such that

$$x_0 + nT \le x(0) < x_0 + (n+1)T.$$

Moreover due to the periodicity of f and to $f(x(0)) \neq f(x_0)$, we have $x(0) \neq x_0 + nT$. Hence, we deduce that

$$x_0 + nT < x(0) < x_0 + (n+1)T.$$
(2.13)

Now, assume that the left hand-side of the first implication of (2.10) holds, and consider the solution y to the ODE

$$y' + f(y) = f(x_0)$$
 in $[0, \infty)$, $y(0) = x(0)$. (2.14)

Assume by contradiction that there exists $t \in [0, \infty)$ such that $y(t) = x_0 + nT$. Then, y and the constant function $y_s := x_0 + nT$ are both solutions to the ODE: $u' + f(u) = f(x_0)$ in $[0, \infty)$, and they agree at point t. Then, by an uniqueness argument we get that $y = y_s$, which due to (2.13) and (2.14) is not satisfied at the point 0. This leads us to a contraction. Similarly, the trajectory $y([0, \infty))$ cannot meet the point $x_0 + (n+1)T$. Therefore, by a connectedness argument we obtain that

$$x_0 + nT < y < x_0 + (n+1)T$$
 in $[0, \infty)$. (2.15)

This combined with (2.13) implies that

$$|y - x(0)| < T$$
 in $[0, \infty)$. (2.16)

Next, define the function z := x - y. Subtracting the equality (2.14) to the inequality satisfied by x, and using that f is k-Lipschitz for some k > 0, we get that

$$z' < f(x_0) - f(x) + f(y) - f(x_0) \le k |z| \quad \text{in } [0, \infty).$$
(2.17)

Since by (2.14) z(0) = 0, inequality (2.17) shows that z'(0) < 0, which implies that z < 0 in some interval $[0, t_0]$ with $t_0 > 0$. We can then consider

$$S := \sup \left\{ t \in [t_0, \infty) : z < 0 \text{ in } [t_0, t] \right\} \in [t_0, \infty].$$

Assume by contradiction that $S < \infty$. Then, we have

$$z < 0 \quad \text{in } [0, S) \quad \text{and} \quad z(S) = 0,$$

which combined with (2.17) implies that

$$\forall t \in [0, S), \quad \frac{d}{dt} (e^{kt} z(t)) = e^{kt} (z'(t) + k z(t)) < 0.$$

Hence, it follows that $0 = e^{kS}z(S) < e^0 z(0) = 0$, which leads us to a contradiction. Therefore, we have $S = \infty$, and by the same argument as above, we get that z = x - y < 0 in $[0, \infty)$. Finally, recalling (2.16) we obtain that x < y < x(0) + T.

The proof of the second implication of (2.10) is quite similar leading us to the inequality in $[0, \infty)$, which concludes the proof of Lemma 2.5.

2.2.2 Proof of the case |A| = |B|

Assume that $B = \varepsilon A$ with $\varepsilon = \pm 1$. Then, consider the new coordinates

$$y = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} x_1 + \varepsilon x_2 \\ -\varepsilon x_1 + x_2 \end{pmatrix} = J \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = J x.$$
(2.18)

where the marix J is defined by (2.2).

By (1.1) we are led to the new flow Y(t, y) := J X(t, x) solution to the ODEs system

$$\begin{cases} \partial_t Y_1(t,y) &= \frac{A}{2} \left(-\cos\left(X_1(t,x)\right) - \varepsilon \,\sin\left(X_2(t,x)\right) + \varepsilon \,\sin\left(X_1(t,x)\right) + \cos\left(X_2(t,x)\right) \right) \\ \partial_t Y_2(t,y) &= \frac{A}{2} \left(\varepsilon \,\cos\left(X_1(t,x)\right) + \sin\left(X_2(t,x)\right) + \sin\left(X_1(t,x)\right) + \varepsilon \,\cos\left(X_2(t,x)\right) \right), \end{cases}$$

or equivalently, using trigonometrical formulas we have

$$\begin{cases} \partial_t Y_1(t,y) = A \sin\left(\frac{X_1(t,x) + X_2(t,x)}{2}\right) \sin\left(\frac{X_1(t,x) - X_2(t,x)}{2}\right) \\ + \varepsilon A \cos\left(\frac{X_1(t,x) + X_2(t,x)}{2}\right) \sin\left(\frac{X_1(t,x) - X_2(t,x)}{2}\right) \\ \partial_t Y_2(t,y) = A \sin\left(\frac{X_1(t,x) + X_2(t,x)}{2}\right) \cos\left(\frac{X_1(t,x) - X_2(t,x)}{2}\right) \\ + \varepsilon A \cos\left(\frac{X_1(t,x) + X_2(t,x)}{2}\right) \cos\left(\frac{X_1(t,x) - X_2(t,x)}{2}\right). \end{cases}$$

This combined with (2.18) thus implies the new system depending on $\varepsilon = \pm 1$,

$$\begin{cases} \partial_t Y_1(t,y) = -\varepsilon A\left(\sin\left(Y_{\frac{3-\varepsilon}{2}}(t,y)\right) + \varepsilon \cos\left(Y_{\frac{3-\varepsilon}{2}}(t,y)\right)\right) \sin\left(Y_{\frac{3+\varepsilon}{2}}(t,y)\right) \\ \partial_t Y_2(t,y) = A\left(\sin\left(Y_{\frac{3-\varepsilon}{2}}(t,y)\right) + \varepsilon \cos\left(Y_{\frac{3-\varepsilon}{2}}(t,y)\right)\right) \cos\left(Y_{\frac{3+\varepsilon}{2}}(t,y)\right). \end{cases}$$
(2.19)

Now, assume for example that $\varepsilon = 1$. Then, system (2.19) reads as

$$\begin{cases} \partial_t Y_1(t,y) = -A\sqrt{2}\sin\left(Y_1(t,y) + \frac{\pi}{4}\right)\sin\left(Y_2(t,y)\right) \\ \partial_t Y_2(t,y) = A\sqrt{2}\sin\left(Y_1(t,y) + \frac{\pi}{4}\right)\cos\left(Y_2(t,y)\right). \end{cases}$$
(2.20)

It is clear that for any $m \in \mathbb{Z}$ and $y_2 \in \mathbb{R}$, $Y(\cdot, y) = y := (-\frac{\pi}{4} + m\pi, y_2)$ is a stationary solution to system (2.20). Moreover, we can check that for any $y_1 \in -\frac{\pi}{4} + 2n\pi + (-\pi, \pi)$,

$$\begin{cases} Y_1(t,y) = -\frac{\pi}{4} + 2n\pi + 2\arctan\left[e^{(-1)^{n+1}A\sqrt{2}t}\tan\left(\frac{y_1}{2} + \frac{\pi}{8}\right)\right] \\ Y_2(t,y) = \frac{\pi}{2} + n\pi, \end{cases} \quad (2.21)$$

is also solution to system (2.20). Then, collecting all these solutions we obtain that the closed set \mathscr{G} defined by (2.3) is composed of trajectories of the flow Y: either stationary points along lines parallel to direction y_2 , or closed line segments parallel to direction y_1 . Hence, since the trajectories of the flow do not intersect, for any $y \in \mathbb{R}^2 \setminus \mathscr{G}$, the trajectory $Y(\mathbb{R}, y)$ lies in one of the connected components of $\mathbb{R}^2 \setminus \mathscr{G}$ which are the open squares of side π defined by

$$Q_{m,n} := \left(-\frac{\pi}{4} + m\pi, -\frac{\pi}{4} + (m+1)\pi\right) \times \left(\frac{\pi}{2} + n\pi, \frac{\pi}{2} + (n+1)\pi\right) \quad \text{for } (m,n) \in \mathbb{Z}^2.$$
(2.22)

Therefore, we get that

$$\forall i = 1, 2, \ \forall y \in \mathbb{R}^2 \setminus \mathscr{G}, \quad \left| Y_i(\cdot, y) - y_i \right| < \pi$$

Finally, this combined with the change of coordinates (2.18) yields the desired estimates (2.4). The case $\varepsilon = -1$ is quite similar, which concludes the proof of Theorem 2.1.

3 Invariant measures and rotation set

3.1 Some recalls of ergodic theory

Let b a vector field in $C^1_{\sharp}(\mathbb{T}^2)$. A probability measure μ in $\mathscr{M}_{\sharp}(\mathbb{T}^2)$ is said to *invariant for some* flow X associated with the vector field b by

$$\begin{cases} \partial_t X(t,x) = b(X(t,x)), & t \in \mathbb{R} \\ X(0,x) = x \in \mathbb{T}^2, \end{cases}$$
(3.1)

if one has

$$\forall t \in \mathbb{R}, \ \forall \psi \in C^0_{\sharp}(\mathbb{T}^2), \quad \int_{\mathbb{T}^2} \psi(X(t,y)) \, d\mu(y) = \int_{\mathbb{T}^2} \psi(y) \, d\mu(y). \tag{3.2}$$

By virtue of Liouville's theorem (see, e.g., [9, Theorem 1, Section 2.2]) condition (3.2) means that

$$\operatorname{div}\left(b\,\mu\right) = 0 \quad \text{in } \mathbb{T}^2,\tag{3.3}$$

or equivalently, with the variational formulation (see, e.g., [4, Proposition])

$$\forall \varphi \in C^1_{\sharp}(\mathbb{T}^2), \quad \int_{\mathbb{T}^2} b(x) \cdot \nabla \varphi(x) \, \mu(dx) = 0. \tag{3.4}$$

Alternatively, define the set

$$\mathscr{I}_b := \left\{ \mu \in \mathscr{M}_p(\mathbb{T}^2) : \mu \text{ invariant for the flow } X \right\},$$
(3.5)

where $\mathcal{M}_{p}(\mathbb{T}^{2})$ is the set of probability measures on \mathbb{T}^{2} . Also define the two following non-empty subsets of \mathbb{R}^{2} :

• The set of all the limit points of the sequences $(X(n,x)/n)_{n\geq 1}$ for $x\in \mathbb{T}^2$ (denoted by $\rho_{\mathbf{p}}(b)$ in [11])

$$\mathsf{A}_b := \bigcup_{x \in \mathbb{T}^2} \left[\bigcap_{n \ge 1} \overline{\left\{ \frac{X(k, x)}{k} : k \ge n \right\}} \right].$$
(3.6)

When b does not vanish in \mathbb{T}^2 , by virtue of Peirone's [12, Theorem 3.1] the former definition is reduced to

$$\mathsf{A}_{b} = \left\{ \lim_{t \to \infty} \frac{X(t, x)}{t} : x \in \mathbb{T}^{2} \right\}.$$
(3.7)

• The so-called Herman [10] rotation set (recall notation (1.7))

$$\mathsf{C}_b := \left\{ \mu(b) : \mu \in \mathscr{I}_b \right\} \tag{3.8}$$

which is a compact convex subset of \mathbb{R}^2 .

An implicit consequence of the Misiurewicz-Ziemian results [11, Theorem 2.4, Remark 2.5] and [11, Corollary 2.6] shows that

$$\mathsf{A}_b \subset \mathsf{C}_b = \operatorname{conv}\,(\mathsf{A}_b).$$

However, in dimension two [11, Theorem 3.4 (c)] shows that actually the set A_b (3.6) is convex which thus implies that

$$\mathsf{C}_b = \mathsf{A}_b. \tag{3.9}$$

When in addition b does not vanish in \mathbb{T}^2 , we thus deduce from (3.7) that

$$\mathsf{C}_{b} = \left\{ \mu(b) : \mu \in \mathscr{I}_{b} \right\} = \left\{ \lim_{t \to \infty} \frac{X(t, x)}{t} : x \in \mathbb{T}^{2} \right\} = \mathsf{A}_{b}.$$
(3.10)

This links closely the invariant probability measures for the flow X (3.1) and the limit points of the flow.

3.2 The case of the two-dimensional Euler flow

The invariant probability measures (3.2) and the Herman rotation set (3.8) for the flow X defined by (1.1) are characterized as follows.

Theorem 3.1. Assume that $|A| \neq |B|$ for the vector field b defined in (1.1). Then, we have the following results:

i) There does not exist any non-negative function $\sigma \in L^1_{\sharp}(\mathbb{T}^2)$ whose integrals over its two sections are a.e. positive, i.e.

$$\begin{cases} \overline{\sigma}^{x_2}(x_1) = \int_{\mathbb{T}^1} \sigma(x_1, x_2) \, dx_2 > 0 \quad a.e. \ x_1 \in \mathbb{T}^1 \\ \overline{\sigma}^{x_1}(x_2) = \int_{\mathbb{T}^1} \sigma(x_1, x_2) \, dx_1 > 0 \quad a.e. \ x_2 \in \mathbb{T}^1, \end{cases}$$
(3.11)

such that the $\sigma(x) dx$ is an invariant probability measure for the flow X.

ii) Moreover, for any $\zeta \in \mathsf{C}_b$, there exist $T \in (0, \infty)$ and $z \in \mathbb{T}^2$ such that the orbit $X(\cdot, z)$ is periodic of period T in the torus \mathbb{T}^2 , i.e.

$$\exists k \in \mathbb{Z}^2, \ X(T, z) = z + 2\pi k, \tag{3.12}$$

and

$$\zeta = \mu_{T,z}(b) \quad \text{where} \quad \mu_{T,z}(\varphi) := \frac{1}{T} \int_0^T \varphi \big(X(t,z) \big) \, dt \quad \text{for } \varphi \in C^0_{\sharp}(\mathbb{T}^2), \tag{3.13}$$

is an invariant probability measure which is singular with respect to Lebesgue's measure. In other words, Herman's rotation set is characterized by

$$\mathsf{C}_{b} = \left\{ \mu_{T,z}(b) \,, \, T > 0, \, z \in \mathbb{T}^{2} : X(T,z) - z \in 2\pi \mathbb{Z}^{2} \right\}.$$
(3.14)

iii) Finally, assume that |A| > |B|. Denoting

$$\begin{cases} \xi_{\mu} := \mu(\cos x_1) e_1 + \mu(\sin x_1) e_2 \\ \eta_{\mu} := \mu(\sin x_2) e_1 + \mu(\cos x_2) e_2, \end{cases} \quad for \ \mu \in \mathscr{I}_b, \tag{3.15}$$

the asymptotics flow function a defined by (2.1) satisfies the bounds from below and above (with the convention: $\inf_{\alpha} = \infty$)

$$\begin{cases} \inf_{x \in \mathbb{T}^2} |a(x)| \ge \min\left(m_{AB}\left(|A| - |B|\right), \inf_{\{\mu \in \mathscr{I}_b : |\xi_\mu| \le |\eta_\mu|\}} |A\xi_\mu + B\eta_\mu|\right) > 0, \\ m_{AB} := \frac{1}{\sqrt{2}} \inf_{\mu \in \mathscr{I}_b} \sqrt{|\xi_\mu|^2 + |\eta_\mu|^2} \in (0, 1], \end{cases}$$
(3.16)

and

$$\begin{cases}
\sup_{x \in \mathbb{T}^2} |a(x)| \leq \sqrt{\left(|A| + |B|\right)^2 - M_{AB}^2}, \\
M_{AB} := \inf_{\mu \in \mathscr{I}_b} \int_{\mathbb{T}^2} |b - \mu(b)| \, \mu(dx) > 0.
\end{cases}$$
(3.17)

Remark 3.2. Due to (2.6) the vector field b in (1.1) does not vanish when $|A| \neq |B|$. Hence, thanks to the first step of the proof of Peirone's [12, Theorem 3.1], for any periodic orbit in the torus the integer vector k in (3.12) is not null.

Remark 3.3. The part *i*) of Theorem 3.1 means that for any non-negative function σ in $L^1_{\sharp}(\mathbb{T}^2)$ satisfying the weak positivity condition (3.11), the vector field σb is not realizable as a divergence free field, or in conductivity term, as a current field. The dual problem (which is equivalent in dimension two) *i.e.* the realizability of a gradient field as an electric field has been addressed in [6] with a very simple counter-example [6, Example 2.7], but involving both regular (at least continuous) and positive functions σ . Here, the two-dimensional Euler flow induced by the vector field *b* (1.1) provides a more definite counter-example of realizability, since here the functions σ are only assumed to be in $L^1_{\sharp}(\mathbb{T}^2)$ rather than regular, and are only non-negative with condition (3.11) rather than positive a.e. in \mathbb{T}^2 .

Remark 3.4. On the one hand, as |A| - |B| tends to 0, the bound from below (3.16) clearly converges to 0. This asymptotic result is consistent with the picture of bounded orbits in the case |A| = |B| (see above the second part of Theorem 2.1 and Section 2.2.2), which due to the set equality (3.9) implies that the Herman rotation set C_b (3.8) is reduced to the unit set $\{0_{\mathbb{R}_2}\}$.

On the other hand, the bound from above (3.17) has actually a general scope. Indeed, the proof of the part *iii*) of Theorem 3.1 below shows that the vector field $b \in C^1(\mathbb{T}^2)^2$ needs to satisfy the two following conditions

$$\left\{x \in \mathbb{T}^2 : b(x) = 0_{\mathbb{R}^2}\right\} = \emptyset \quad \text{and} \quad \forall \xi \in \mathbb{R}^2, \ \#\left\{x \in \mathbb{T}^2 : b(x) = \xi\right\} < \infty.$$
(3.18)

Then, we still deduce from (3.10) the extension of (3.17)

$$\begin{cases} \sup_{x \in \mathbb{T}^2} \left| \lim_{t \to \infty} \frac{X(t, x)}{t} \right| \le \sqrt{\|b\|_{L^{\infty}(\mathbb{T}^2)^2}^2 - M_b^2}, \\ M_b := \inf_{\mu \in \mathscr{I}_b} \int_{\mathbb{T}^2} |b - \mu(b)| \, \mu(dx) > 0. \end{cases}$$
(3.19)

Corollary 3.5. Assume there exists a first integral u in $C^1(\mathbb{R}^2)$ of the flow (1.1) having a periodic gradient of period $2\pi\mathbb{Z}^2$. Then, ∇u has at least a cluster point of roots in the torus \mathbb{T}^2 .

Proof of Theorem 3.1.

Proof of part i). Assume for instance that |A| > |B|, and that there exists an invariant probability measure $\sigma(x) dx$ for the flow X (1.1) with Lebesgue's density $\sigma \in L^1_{\sharp}(\mathbb{T}^2)$ satisfying the weak positivity (3.11). By Liouville's theorem (3.3) combined with a classical duality result there exists a function ψ with $\nabla \psi \in L^1_{\sharp}(\mathbb{T}^2)$ such that (recall the third notation)

$$\sigma b = \nabla^{\perp} \psi \text{ in } \mathbb{R}^2, \tag{3.20}$$

or equivalently,

$$\begin{cases} \sigma(x) \left(A \cos x_1 + B \sin x_2 \right) = \partial_{x_2} \psi(x) \\ \sigma(x) \left(A \sin x_1 + B \cos x_2 \right) = \partial_{x_1} \psi(x) \end{cases} \quad \text{a.e. } x = (x_1, x_2) \in \mathbb{T}^2. \tag{3.21}$$

Recalling (2.6) equalities (3.10) hold true. This combined with (2.1) and (3.20) implies that there exists $x_{\sigma} \in \mathbb{T}^2$ such that

$$\overline{\nabla\psi} = -\left(\overline{\sigma \, b}\right)^{\perp} = -\left(\lim_{t \to \infty} \frac{X(t, x_{\sigma})}{t}\right)^{\perp} = -a(x_{\sigma}) \, e_2^{\perp} = a(x_{\sigma}) \, e_1, \quad \text{with } a(x_{\sigma}) \neq 0.$$

Then, since the function $\psi_{\sharp}: y \mapsto (\psi(y) - \overline{\nabla \psi} \cdot y)$ is in $W^{1,1}_{\sharp}(\mathbb{T}^2)$, we get that

$$\overline{\partial_{x_2}\psi}^{x_2}(x_1) = \frac{1}{2\pi} \int_{-\pi}^{\pi} \partial_{x_2}\psi(x_1, x_2) \, dx_2 = \frac{1}{2\pi} \int_{-\pi}^{\pi} \partial_{x_2}\psi_{\sharp}(x_1, x_2) \, dx_2 = 0 \quad \text{a.e. } x_1 \in \mathbb{T}^1.$$
(3.22)

Therefore, integrating the second equality of (3.21) with respect to variable x_2 and taking into account (3.11) and (3.22), it follows that

$$\left|\cos x_{1}\right| = \left|-\frac{B}{A} \frac{\overline{\sigma} \sin x_{2}^{x_{2}}(x_{1})}{\overline{\sigma}^{x_{2}}(x_{1})}\right| \le \frac{|B|}{|A|} \quad \text{a.e. } x_{1} \in \mathbb{T}^{1},$$

$$(3.23)$$

which, making x_1 tend to 0, contradicts our assumption |A| > |B|.

Proof of part ii). Let $\zeta \in C_b$. By (3.10) there exists $x \in \mathbb{T}^2$ such that

$$\zeta = \lim_{t \to \infty} \frac{X(t, x)}{t}.$$
(3.24)

Then, consider the T_x -periodic (in the torus \mathbb{T}^2) orbit $X(\cdot, z_x)$ satisfying (2.7) for some i = 1, 2, and consider the probability measure μ_{T_x, z_x} defined by (3.13). Due to the semi-group property satisfied by the flow, we have for any $s \in \mathbb{R}$ and any $\varphi \in C^0_{\sharp}(\mathbb{T}^2)$,

$$\begin{split} \mu_{T_x,z_x}\big(\varphi(X(s,\cdot))\big) &= \frac{1}{T_x} \int_0^{T_x} \varphi\big(X(s,X(t,z_x))\big) \, dt = \frac{1}{T_x} \int_0^{T_x} \varphi\big(X(s+t,z_x)\big) \, dt \\ &= \frac{1}{T_x} \int_s^{s+T_x} \varphi\big(X(t,z_x)\big) \, dt = \frac{1}{T_x} \int_0^{T_x} \varphi\big(X(t,z_x)\big) \, dt, \end{split}$$

since the function $\varphi(X(\cdot, z_x))$ is T_x -periodic in \mathbb{R} taking into account the first equality of (2.7). Hence, μ_{T_x, z_x} is an invariant probability measure for the flow X. Moreover, again using (2.7) we get that

$$\mu_{T_x,z_x}(b) = \frac{1}{T_x} \int_0^{T_x} b\big(X(t,z_x)\big) \, dt = \frac{1}{T_x} \int_0^{T_x} \partial_t X(t,z_x) \, dt = \frac{X(T_x,z_x) - z_x}{T_x} = a(x) \, e_{3-i},$$

which combined with (3.24) implies the desired equalities $\zeta = \mu_{T_x, z_x}(b)$ and (3.14).

Proof of bound (3.16). By the definition of the vector field b in (1.1) and the definitions (3.15) of the vectors ξ_{μ}, η_{μ} , we have

$$\forall \mu \in \mathscr{I}_b, \quad \mu(b) = A \,\xi_\mu + B \,\eta_\mu.$$

Since the vector field b does not vanish in \mathbb{T}^2 by (2.6), from the set equality (3.10) and the non vanishing property of the function a in (2.1), we deduce that

$$\inf_{x \in \mathbb{T}^2} |a(x)| = \inf_{\mu \in \mathscr{I}_b} |\mu(b)| \quad \text{and} \quad \forall \mu \in \mathscr{I}_b, \ |\mu(b)| = \left| A \xi_\mu + B \eta_\mu \right| > 0.$$
(3.25)

This combined with the continuity of the mapping

$$\mu \in \mathscr{I}_b \mapsto \left| A \, \xi_\mu + B \, \eta_\mu \right|$$

defined on the compact set of invariant probability measures \mathscr{I}_b for the weak-* measures topology, implies that

$$\inf_{\mu \in \mathscr{I}_b} \left| A \, \xi_\mu + B \, \eta_\mu \right| = \min \left(\inf_{\{\mu \in \mathscr{I}_b : |\xi_\mu| \ge |\eta_\mu|\}} \left| A \, \xi_\mu + B \, \eta_\mu \right|, \inf_{\{\mu \in \mathscr{I}_b : |\xi_\mu| \le |\eta_\mu|\}} \left| A \, \xi_\mu + B \, \eta_\mu \right| \right) > 0.$$
(3.26)

Then, by the Cauchy-Schwarz inequality we have

$$|\xi_{\mu}|^{2} + |\eta_{\mu}|^{2} \le \sum_{i=1}^{2} \left(\mu(\cos^{2} x_{i}) + \mu(\sin^{2} x_{i}) \right) = 2.$$

Again applying the Cauchy-Schwarz inequality the constant m_{AB} of (3.16) thus satisfies the estimate

$$1 \ge m_{AB} = \frac{1}{\sqrt{2}} \inf_{\mu \in \mathscr{I}_b} \sqrt{|\xi_{\mu}|^2 + |\eta_{\mu}|^2} \ge \frac{1}{\sqrt{2(A^2 + B^2)}} \inf_{\mu \in \mathscr{I}_b} \left(A |\xi_{\mu}| + B |\eta_{\mu}| \right)$$
$$\ge \frac{1}{\sqrt{2(A^2 + B^2)}} \inf_{\mu \in \mathscr{I}_b} \left| A \xi_{\mu} + B \eta_{\mu} \right| > 0.$$

Now, focus on the second infimum of (3.26). Using the triangle inequality we have for any $\mu \in \mathscr{I}_b$ satisfying $|\xi_{\mu}| \geq |\eta_{\mu}|$ which also implies that $|\xi_{\mu}| \geq m_{AB}$,

$$\left|A\,\xi_{\mu} + B\,\eta_{\mu}\right| = |\xi_{\mu}| \left|A\,\frac{\xi_{\mu}}{|\xi_{\mu}|} + B\,\frac{\eta_{\mu}}{|\xi_{\mu}|}\right| \ge |\xi_{\mu}| \left(|A| - |B|\,\frac{|\eta_{\mu}|}{|\xi_{\mu}|}\right) \ge m_{AB}\left(|A| - |B|\right).$$

Therefore, recalling (3.25) and (3.26) we obtain immediately the bound (3.16) with $m_{AB} > 0$. *Proof of bound* (3.17). Assume by contradiction that there exists an invariant probability measure $\mu \in \mathscr{I}_b$ for the flow X, satisfying $b = \mu(b) \mu$ -a.e. in \mathbb{T}^2 . Then, the set J of the points $z \in \mathbb{T}^2$ solutions to the equation $b(z) = \mu(b)$ is clearly finite (we can check that $1 \leq \#J \leq 4$). Hence, there exists a non-empty subset I of J such that the probability measure μ reads as

$$\mu = \sum_{z \in I} \mu(\{z\}) \, \delta_z \text{ on } \mathbb{T}^2, \quad \text{with} \quad \forall \, z \in I, \ \mu(\{z\}) > 0 \text{ and } \sum_{z \in I} \mu(\{z\}) = 1.$$

Hence, recalling (3.4) we have

$$\forall \varphi \in C^1_{\sharp}(\mathbb{T}^2), \quad \int_{\mathbb{T}^2} b(x) \cdot \nabla \varphi(x) \, \mu(dx) = \sum_{z \in I} \mu(\{z\}) \, b(z) \cdot \nabla \varphi(z) = 0,$$

which due to the arbitrariness of the function φ implies that for any $z \in I$, $b(z) = 0_{\mathbb{R}^2}$, and leads us to contradiction. Therefore, we get that

$$\forall \, \mu \in \mathscr{I}_b, \quad \int_{\mathbb{T}^2} \left| b - \mu(b) \right| \, \mu(dx) > 0.$$

This combined with the compactness of the set \mathscr{I}_b of the invariant probability measures implies that the infimum M_{AB} of (3.17) is positive.

Next, by the Cauchy-Schwarz inequality we have for any $\mu \in \mathscr{I}_b$,

$$\begin{split} M_{AB}^2 &\leq \int_{\mathbb{T}^2} |b - \mu(b)|^2 \,\mu(dx) &= \mu(|b|^2) - |\mu(b)|^2 \\ &= A^2 + B^2 + 2AB \left(\int_{\mathbb{T}^2} \sin(x_1 + x_2) \,\mu(dx) \right) - |\mu(b)|^2 \\ &\leq \left(|A| + |B| \right)^2 - |\mu(b)|^2, \end{split}$$

which implies that

$$\forall \mu \in \mathscr{I}_b, \quad |\mu(b)|^2 \le \left(|A| + |B|\right)^2 - M_{AB}^2.$$

This combined with (2.1) and (3.10) thus yields the desired bound (3.17).

The proof of Theorem 3.1 is now complete.

Proof of Corollary 3.5. Assume by contradiction that for $|A| \neq |B|$, there exists a first integral u in $C^1(\mathbb{R}^2)$ of system (1.1), whose periodic gradient $\nabla u \in C^0_{\sharp}(\mathbb{T}^2)^2$ has a finite number of roots in the torus \mathbb{T}^2 . Hence, taking the derivative of (1.3) with respect to t, we have

$$\forall t \in [0,\infty), \quad \nabla u (X(t,x)) \cdot b (X(t,x)) = 0,$$

and for t = 0, we get that $\nabla u \cdot b = 0$ in \mathbb{T}^2 . Since the vector field does not vanish in \mathbb{T}^2 (recall (2.6)), there exists a function $\sigma \in C^0_{\sharp}(\mathbb{T}^2)$ such that $\nabla^{\perp} u = \sigma b$ in \mathbb{T}^2 . The continuous function σ does not vanish in $\mathbb{R}^2 \setminus \{\nabla u = 0\}$ which by assumption is a connected open set of \mathbb{R}^2 . It follows that σ has a constant sign, say positive, in $\mathbb{R}^2 \setminus \{\nabla u = 0\}$. This combined with the continuity of σ implies that the weak positivity condition (3.11) holds true, and thus contradicts the part i) of Theorem 3.1.

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