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An Effective Model for Boundary Vortices in Thin-Film Micromagnetics

Radu Ignat* Matthias Kurzke†

November 12, 2023

Abstract

Ferromagnetic materials are governed by a variational principle which is nonlocal, non-convex and multiscale. The main object is given by a unit-length three-dimensional vector field, the magnetization, that corresponds to the stable states of the micromagnetic energy. Our aim is to analyze a thin film regime that captures the asymptotic behavior of boundary vortices generated by the magnetization and their interaction energy. This study is based on the notion of “global Jacobian” detecting the topological defects that *a priori* could be located in the interior and at the boundary of the film. A major difficulty consists in estimating the nonlocal part of the micromagnetic energy in order to isolate the exact terms corresponding to the topological defects. We prove the concentration of the energy around boundary vortices via a Γ -convergence expansion at the second order. The second order term is the renormalized energy that represents the interaction between the boundary vortices and governs their optimal position. We compute the expression of the renormalized energy for which we prove the existence of minimizers having two boundary vortices of multiplicity 1. Compactness results are also shown for the magnetization and the corresponding global Jacobian.

AMS classification: Primary: 82D40, Secondary: 35B25, 49J45

Keywords: Γ -convergence, boundary vortex, renormalized energy, Jacobian, compactness, canonical harmonic map, micromagnetics.

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1 Introduction

The aim of the paper is to develop a mathematical analysis of thin ferromagnetic films in a *boundary vortex* regime. This regime is characterized by the concentration of the micromagnetic energy around topological point singularities located at the boundary of the film, the so-called boundary vortices. Our mathematical approach consists in determining an asymptotic expansion by Γ -convergence that is precise enough to capture the interaction energy between the boundary vortices that governs their location at the boundary of the sample.

We start by a brief introduction to micromagnetics which is a nonconvex, nonlocal and multi-scale variational principle. For that, we consider a ferromagnetic sample of cylindrical shape

$$\boldsymbol{\omega} = \omega \times (0, t) \subset \mathbb{R}^3$$

where $\omega \subset \mathbb{R}^2$ is the transversal section with diameter $\ell > 0$ and $t > 0$ is the thickness of the cylinder $\boldsymbol{\omega}$. We assume that $\omega \subset \mathbb{R}^2$ is a simply-connected domain of class $C^{1,1}$. The behavior of the magnetic moments inside the sample is described by the magnetization \mathbf{m} which is a three-dimensional ($3D$) unit-length vector field

$$\mathbf{m} = (m, m_3) : \boldsymbol{\omega} \rightarrow \mathbb{S}^2, \quad m = (m_1, m_2).$$

Here **bold symbols** always denote a $3D$ quantity, *italic symbols* denote $1D$ or $2D$ quantities and \mathbb{S}^2 is the unit sphere in \mathbb{R}^3 . The magnetization represents a stable state of the micromagnetic energy, considered here in the absence of anisotropy and applied magnetic field:

$$E^{3D}(\mathbf{m}) = A^2 \int_{\boldsymbol{\omega}} |\nabla \mathbf{m}|^2 dx + \int_{\mathbb{R}^3} |\nabla U|^2 dx,$$

where $\mathbf{x} = (x, x_3) \in \mathbb{R}^3$ stands for the $3D$ space variable with the differential operator $\nabla = (\nabla, \partial_{x_3})$, while $x = (x_1, x_2) \in \mathbb{R}^2$ and $\nabla = (\partial_{x_1}, \partial_{x_2})$. The first term in E^{3D} is called *exchange energy* and penalizes the variations of \mathbf{m} according to the exchange length of the material $A > 0$ that is typically on the order of nanometers.

The second term is the nonlocal *magnetostatic energy* that is carried by the H^1 stray-field potential $U : \mathbb{R}^3 \rightarrow \mathbb{R}$ generated by \mathbf{m} via the static Maxwell's equation:

$$\Delta U = \nabla \cdot (\mathbf{m} \mathbf{1}_{\boldsymbol{\omega}}) \quad \text{in the sense of distributions in } \mathbb{R}^3,$$

where $\mathbf{1}_{\boldsymbol{\omega}}$ is the characteristic function of $\boldsymbol{\omega}$,

$$\text{i.e.,} \quad \int_{\mathbb{R}^3} \nabla U \cdot \nabla \zeta dx = \int_{\boldsymbol{\omega}} \mathbf{m} \cdot \nabla \zeta dx, \quad \text{for every } \zeta \in C_c^\infty(\mathbb{R}^3) \quad (1.1)$$

(see Appendix A). In other words, the stray field ∇U is the L^2 Helmholtz projection onto gradient fields of the magnetization \mathbf{m} (extended by zero outside the sample ω).

The combination of nonconvexity (through the saturation condition $|\mathbf{m}| = 1$ in ω) and nonlocality (through the coupling with Maxwell's equation) leads to rich magnetic pattern formation. Depending on the length scales of the system (e.g. the exchange length A , the thickness t and width ℓ of the sample ω), experiments have shown different types of singular patterns, such as domain walls and vortices. To predict and describe these microscopic structures occurring across a wide range of spatial scales poses many challenging mathematical problems that have led to a substantial amount of recent research, see e.g. DeSimone et al. [12] and Ignat [19].

1.1 A thin film regime

We are interested in analyzing the asymptotic behavior of the magnetization and of the micro-magnetic energy E^{3D} in a special thin film regime where boundary vortices appear. For that, it is convenient to use instead of the three length scales ℓ , t and A of the model, the following two dimensionless parameters¹:

$$h := \frac{t}{\ell} > 0 \quad \text{and} \quad \eta := \frac{A}{\ell} > 0.$$

Rescaling. We consider $\eta = \eta(h)$ as a function of h and nondimensionalize in length with respect to ℓ , i.e. $\hat{\mathbf{x}} = \frac{\mathbf{x}}{\ell}$,

$$\hat{\mathbf{x}} \in \Omega_h = \Omega \times (0, h) \subset \mathbb{R}^3, \quad \Omega = \frac{\omega}{\ell} \subset \mathbb{R}^2,$$

(so, the transversal section Ω has diameter one), $\mathbf{m}_h(\hat{\mathbf{x}}) = \mathbf{m}(\mathbf{x})$, $U_h(\hat{\mathbf{x}}) = \frac{1}{\ell}U(\mathbf{x})$. Then we rescale the energy at the energetic level of boundary vortices to $\hat{E}_h(\mathbf{m}_h) = \frac{1}{A^2 t |\log \varepsilon|} E^{3D}(\mathbf{m})$, where

$$\varepsilon = \frac{\eta^2}{h |\log h|}$$

is a function $\varepsilon(h)$ of h standing for the core size of a boundary vortex. We will always assume $h \ll 1$ and $\varepsilon \ll 1$. **Skipping the hat** [^] **from now on**, we will use the following quantities:

$$E_h(\mathbf{m}_h) = \frac{1}{h |\log \varepsilon|} \int_{\Omega_h} |\nabla \mathbf{m}_h|^2 dx + \frac{1}{\eta^2 h |\log \varepsilon|} \int_{\mathbb{R}^3} |\nabla U_h|^2 dx, \quad (1.2)$$

where

$$\mathbf{m}_h : \Omega_h \rightarrow \mathbb{S}^2, \quad \Delta U_h = \nabla \cdot (\mathbf{m}_h \mathbf{1}_{\Omega_h}) \quad \text{in} \quad \mathbb{R}^3. \quad (1.3)$$

Notation. We use the following notation: $a \ll b$ or $a = o(b)$ if $\frac{a}{b} \rightarrow 0$, as well as $a \lesssim b$ or $a = O(b)$ if there exists a universal $C > 0$ such that $a \leq Cb$ and finally, $a \sim b$ if $a \lesssim b$ and $b \lesssim a$. We adopt the constant convention, which means that constants called C can change their value from one line to the next. The notation ‘‘a sequence / family $h \rightarrow 0$ ’’ or similar will be used both to refer to a sequence $h_k \rightarrow 0$ or to a continuous parameter $h \rightarrow 0$.

¹ h stands for the aspect ratio of the sample ω , while η , the reduced exchange length, corresponds to the core size of interior vortices. Both parameters h and η will be small in our regime.

Regime. We will focus on the following regime of thin films (i.e., the aspect ratio $h \ll 1$ is very small) where the rescaled energy E_h in (1.2) is expected to concentrate around boundary vortices:

$$\eta, h \ll 1 \quad \text{and} \quad \frac{1}{|\log h|} \ll \varepsilon \ll 1. \quad (1.4)$$

Note that (1.4) is equivalent with $h \ll \eta^2 \ll h|\log h| \ll 1$, so that $|\log h| \sim |\log \eta|$. As $a \ll b \ll 1$ implies $a|\log a| \ll b|\log b| \ll 1$, we deduce for $a = \frac{1}{|\log h|}$ and $b = \varepsilon$:

$$\frac{\log |\log h|}{|\log h|} \ll \varepsilon |\log \varepsilon|. \quad (1.5)$$

Also note that in terms of ε and η , (1.4) can be written as

$$\eta \ll 1 \quad \text{and} \quad \frac{1}{|\log \eta|} \ll \varepsilon \ll 1.$$

In particular, one has $|\log \varepsilon| \leq \log |\log \eta|$ and as $|\log h| \sim |\log \eta|$, it implies $|\log \varepsilon| \lesssim \log |\log h|$. Some of our results are only valid in the following regime, which is narrower than (1.5):

$$\frac{\log |\log h|}{|\log h|} \ll \varepsilon \quad (1.6)$$

Obviously, if $\eta(h), \varepsilon(h), h \ll 1$, then (1.6) implies (1.4). Possible choices for $\eta(h)$ for which $\varepsilon(h)$ satisfies (1.6) are $\eta^2 = Ch|\log h|^\beta$ for some $0 < \beta < 1$ and $C > 0$. The choice $\eta^2 = Ch \log |\log h|$ with $C > 0$ is an example for which (1.4) holds true but (1.6) does not.

Our regime (1.4) fills the gap in the analysis of thin film regimes in micromagnetics between the regimes $\eta^2 = O(h)$ studied by Moser [39] and $\eta^2 = O(h|\log h|)$ analysed by Kohn-Slastikov [28]. We refer to Subsection 2 for a discussion of the thin film regimes in micromagnetics.

A reduced 2D model. A key point in our analysis concerns the behavior of the micromagnetic energy E_h (given in (1.2)) in the asymptotic regime (1.4). As the aspect ratio h tends to 0, the appropriate quantity to study is the vertical average magnetization \mathbf{m}_h (given in (1.3)) defined in the 2D section Ω :

$$\bar{\mathbf{m}}_h(x) = \frac{1}{h} \int_0^h \mathbf{m}_h(x, x_3) dx_3, \quad x \in \Omega \subset \mathbb{R}^2, \quad (1.7)$$

to which the stray field potential $\bar{U}_h : \mathbb{R}^3 \rightarrow \mathbb{R}$ is associated via

$$\Delta \bar{U}_h = \nabla \cdot (\bar{\mathbf{m}}_h \mathbf{1}_{\Omega_h}) \quad \text{in} \quad \mathbb{R}^3. \quad (1.8)$$

Note that the unit-length constraint is convexified by averaging, i.e. $|\mathbf{m}_h| = 1$ yields $|\bar{\mathbf{m}}_h| \leq 1$, so

$$\bar{\mathbf{m}}_h = (\bar{m}_h, \bar{m}_{h,3}) : \Omega \rightarrow \bar{B}^3$$

where \bar{B}^3 is the closed unit ball in \mathbb{R}^3 .

We will prove that in the regime (1.4), the 3D micromagnetic model reduces to a 2D model for the average magnetization $\bar{\mathbf{m}}_h$. The major difficulty consists in determining the scaling of the nonlocal part of the rescaled energy E_h in the regime (1.4). More precisely, the stray field energy penalizes the distance of the in-plane average \bar{m}_h to the unit circle \mathbb{S}^1 inside Ω as well as the normal component $(\bar{m}_h \cdot \nu)$ at the boundary $\partial\Omega$ where

$$\nu = (\nu_1, \nu_2)$$

stands for the outer unit normal vector at $\partial\Omega$. Thus, we introduce the following reduced 2D energy functional associated to the average magnetization $\bar{\mathbf{m}}_h$ with $|\bar{\mathbf{m}}_h| \leq 1$ defined in the 2D simply-connected $C^{1,1}$ domain Ω :

$$\bar{E}_h(\bar{\mathbf{m}}_h) = \frac{1}{|\log \varepsilon|} \left(\int_{\Omega} |\nabla \bar{\mathbf{m}}_h|^2 dx + \frac{1}{\eta^2} \int_{\Omega} (1 - |\bar{m}_h|^2) dx + \frac{1}{2\pi\varepsilon} \int_{\partial\Omega} (\bar{m}_h \cdot \nu)^2 d\mathcal{H}^1 \right). \quad (1.9)$$

We can extend the definition of \bar{E}_h to all of $H^1(\Omega; \mathbb{R}^3)$ by setting $\bar{E}_h(\mathbf{m}) = \infty$ if $|\mathbf{m}| > 1$ on a set of positive measure.

Theorem 1 *Let $\Omega_h = \Omega \times (0, h)$ with $\Omega \subset \mathbb{R}^2$ be a simply connected $C^{1,1}$ domain. In the regime (1.4), we consider a family of magnetizations $\{\mathbf{m}_h : \Omega_h \rightarrow \mathbb{S}^2\}_{h \rightarrow 0}$ with associated stray field potentials $\{U_h : \mathbb{R}^3 \rightarrow \mathbb{R}\}_{h \rightarrow 0}$ given by (1.3) and we assume*

$$\limsup_{h \rightarrow 0} E_h(\mathbf{m}_h) < \infty.$$

Then

$$E_h(\mathbf{m}_h) \geq \bar{E}_h(\bar{\mathbf{m}}_h) - o(1) \quad \text{as } h \rightarrow 0.$$

Moreover, in the more restrictive regime (1.6), we have the following improved estimate:

$$E_h(\mathbf{m}_h) \geq \bar{E}_h(\bar{\mathbf{m}}_h) - o\left(\frac{1}{|\log \varepsilon|}\right) \quad \text{as } h \rightarrow 0. \quad (1.10)$$

If \mathbf{m}_h are independent of x_3 (i.e., $\mathbf{m}_h = \bar{\mathbf{m}}_h$), then in the regime (1.4) there holds $E_h(\mathbf{m}_h) = \bar{E}_h(\bar{\mathbf{m}}_h) - o(1)$, while in the regime (1.6) we have $E_h(\mathbf{m}_h) = \bar{E}_h(\bar{\mathbf{m}}_h) - o\left(\frac{1}{|\log \varepsilon|}\right)$ as $h \rightarrow 0$.

Let us highlight the role of the above estimates: while the full micromagnetic energy E_h is nonlocal (due to the stray field), the reduced energy \bar{E}_h becomes local in terms of the average magnetization, so easier to handle.² However, the samples are still large compared to the core size of a boundary vortex. See Section 2 for more details. Moreover, the improved energy estimate (1.10) is essential to carry out the asymptotic Γ -development of the 3D energy E_h at the second order that allows us to determine the interaction between boundary vortices.

In [22], we have studied the energy functional for 2D maps $u \in H^1(\Omega; \mathbb{R}^2)$:

$$E_{\varepsilon, \eta}(u) = \int_{\Omega} |\nabla u|^2 dx + \frac{1}{\eta^2} \int_{\Omega} (1 - |u|^2)^2 dx + \frac{1}{2\pi\varepsilon} \int_{\partial\Omega} (u \cdot \nu)^2 d\mathcal{H}^1.$$

Comparing this to \bar{E}_h , we have for $u = \bar{m}_h$ that $(1 - |u|^2) \geq (1 - |u|^2)^2$. Since $|\nabla(\bar{\mathbf{m}}_h \cdot e_3)|^2 \geq 0$, we deduce

$$\bar{E}_h(\bar{\mathbf{m}}_h) \geq \frac{1}{|\log \varepsilon|} E_{\varepsilon, \eta}(\bar{m}_h), \quad (1.11)$$

and so the lower bounds obtained for $E_{\varepsilon, \eta}$ in [22] will provide lower bounds for \bar{E}_h and in turn for E_h (by Theorem 1). For maps $\bar{\mathbf{m}}_h = (\bar{m}_h, 0)$ with values into $\mathbb{S}^1 \times \{0\}$, (1.11) is an equality and will allow us to obtain matching upper bounds. See Section 4 for details.

²Physically, the regime (1.4) corresponds to fairly small magnetic samples where the nonlocality is lost. For example, Néel walls have a core of size $\frac{\eta^2}{h}$, which in this regime is $\gg 1$, so too large to be contained within the sample of size $O(1)$.

1.2 Global Jacobian

We want to explain now the topological challenges carried by the reduced $2D$ energy \bar{E}_h defined in (1.9). It is similar to the standard Ginzburg-Landau functional studied in the seminal book of Bethuel-Brezis-Helein [5], i.e.,

$$u \in H^1(\Omega \subset \mathbb{R}^2; \mathbb{R}^2) \mapsto \int_{\Omega} e_{\eta}(u) dx \quad \text{with } e_{\eta}(u) = |\nabla u|^2 + \frac{1}{\eta^2}(1 - |u|^2)^2, \quad \eta > 0. \quad (1.12)$$

However, the reduced energy \bar{E}_h leads to richer singular pattern formation due to the additional penalty term at the boundary. Indeed, we expect that stable states of \bar{E}_h generate both interior and boundary vortices (see Moser [38]).³ Therefore, we need to define a notion of *global Jacobian* capable of detecting topological singularities in the interior as well as at the boundary of the sample. We refer to our previous paper [22] for more details. In our setting, the $2D$ map u in (1.12) plays the role of the in-plane components of the average magnetization $\bar{\mathbf{m}}_h$, i.e., $u = (\bar{\mathbf{m}}_h \cdot \mathbf{e}_1, \bar{\mathbf{m}}_h \cdot \mathbf{e}_2)$ where $(\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3)$ is the Cartesian basis in \mathbb{R}^3 .

Global Jacobian. For a $2D$ map $u \in H^1(\Omega; \mathbb{R}^2)$ defined on the $C^{1,1}$ domain $\Omega \subset \mathbb{R}^2$, we call *global Jacobian* of u the following linear operator $\mathcal{J}(u) : W^{1,\infty}(\Omega) \rightarrow \mathbb{R}$ acting on Lipschitz test functions:⁴

$$\langle \mathcal{J}(u), \zeta \rangle := - \int_{\Omega} u \times \nabla u \cdot \nabla^{\perp} \zeta dx, \quad \text{for every Lipschitz function } \zeta : \Omega \rightarrow \mathbb{R},$$

where $\nabla^{\perp} = (-\partial_{x_2}, \partial_{x_1})$ and $a \times b = a_1 b_2 - a_2 b_1$ for any two vectors $a = (a_1, a_2) \in \mathbb{R}^2$ and $b = (b_1, b_2) \in \mathbb{R}^2$. In particular,

$$\langle \mathcal{J}(u), 1 \rangle = 0.$$

On the one hand, the global Jacobian carries the topological information in the interior of Ω , where it coincides (up to a multiplicative constant) with the standard Jacobian of u detecting the interior vortices that we call *interior Jacobian* in the sequel, i.e.,

$$\text{jac}(u) = \det(\nabla u) = \partial_{x_1} u \times \partial_{x_2} u \in L^1(\Omega).$$

Indeed, integration by parts for Lipschitz test functions $\zeta \in W_0^{1,\infty}(\Omega)$ vanishing at the boundary $\partial\Omega$ yields

$$\langle \mathcal{J}(u), \zeta \rangle = 2 \int_{\Omega} \text{jac}(u) \zeta dx \quad \text{if } \zeta = 0 \text{ on } \partial\Omega$$

(see e.g. the proof of [22, Proposition 2.1]). On the other hand, the global Jacobian also carries the topological information at the boundary $\partial\Omega$ and will enable us to detect the boundary vortices; more precisely, we define the *boundary Jacobian* of u to be the linear operator $\mathcal{J}_{bd}(u) : W^{1,\infty}(\Omega) \rightarrow \mathbb{R}$ given by

$$\mathcal{J}_{bd}(u) := \mathcal{J}(u) - 2 \text{jac}(u). \quad (1.13)$$

³In [38], Moser studies (1.2) neglecting the out-of-plane component of the magnetization and in the special regime where $\varepsilon = \eta^{\alpha}$, with $\alpha \in (0, 1]$. The author proves that global minimizers nucleate two boundary vortices if $\alpha < 1$, while for $\alpha = 1$, either two boundary vortices or an interior vortex are possible. For a similar problem, a more refined analysis was performed by Alama et al. [1].

⁴Note that $u \times \nabla u \in L^1(\Omega; \mathbb{R}^2)$ for $u \in H^1(\Omega; \mathbb{R}^2)$. More generally, the global Jacobian $\mathcal{J}(u)$ extends naturally to a map $u \in L^p(\Omega; \mathbb{R}^2)$ with $\nabla u \in L^q(\Omega; \mathbb{R}^{2 \times 2})$ where $\frac{1}{p} + \frac{1}{q} = 1$, $p, q \in [1, \infty]$; in particular, this is the case for $u \in W^{1,1}(\Omega; \mathbb{S}^1)$.

In fact, the operator $\mathcal{J}_{bd}(u)$ acts only on the boundary of $\partial\Omega$: For maps u that are smooth up to the boundary, integration by parts yields⁵

$$\langle \mathcal{J}_{bd}(u), \zeta \rangle = - \int_{\partial\Omega} (u \times \partial_\tau u) \zeta \, d\mathcal{H}^1 \quad \text{for every Lipschitz function } \zeta : \Omega \rightarrow \mathbb{R}$$

(for the general case $u \in H^1(\Omega; \mathbb{R}^2)$, see [22, Proposition 2.2]). Here and throughout the paper,

$$\tau = \nu^\perp = (-\nu_2, \nu_1)$$

is the unit tangent vector at $\partial\Omega$ such that (ν, τ) form an oriented frame, and we write ∂_τ for the derivative along the boundary.

Note that for unit-length maps $u : \Omega \rightarrow \mathbb{S}^1$ that admit a smooth lifting $\varphi : \Omega \rightarrow \mathbb{R}$, i.e., $u = (\cos \varphi, \sin \varphi)$ in Ω , the interior Jacobian of u vanishes, so that the whole topological information is carried by the tangential derivative of the lifting φ at the boundary:

$$\text{jac}(u) = 0, \quad \mathcal{J}(u) = \mathcal{J}_{bd}(u) = -\partial_\tau \varphi \mathcal{H}^1 \llcorner \partial\Omega \quad \text{and} \quad \langle \mathcal{J}_{bd}(u), 1 \rangle = 0 \quad \text{if } |u| = 1 \text{ in } \Omega. \quad (1.14)$$

Typically, in our model, the limiting global Jacobian in the regime (1.4) is a measure supported on the boundary $\partial\Omega$, of the form $J = -\varkappa \mathcal{H}^1 \llcorner \partial\Omega + \pi \sum_{j=1}^N d_j \delta_{a_j}$ for N distinct boundary vortices $a_j \in \partial\Omega$ with $d_j \in \mathbb{Z} \setminus \{0\}$ and \varkappa the curvature on $\partial\Omega$. The necessary condition $\langle J, 1 \rangle = 0$ yields, via the Gauss-Bonnet formula, the following topological constraint on the multiplicities d_j :

$$\pi \sum_{j=1}^N d_j = \int_{\partial\Omega} \varkappa \, d\mathcal{H}^1 = 2\pi, \quad \text{i.e.,} \quad \sum_{j=1}^N d_j = 2$$

(see e.g. [22]).

1.3 Γ -expansion for boundary vortices

In Theorem 1 we have connected the 3D micromagnetic energy E_h in (1.2) to a reduced 2D energy for the average magnetizations that are defined on the 2D transversal section Ω . This reduction result plays a fundamental role in proving our main Theorem 9 below. First, we show that the global Jacobian of the average magnetizations converges (up to extraction) to a measure supported at the boundary $\partial\Omega$ provided a certain energy bound of the magnetizations in the regime (1.4). This limit measure involves a finite sum of Dirac measures at the boundary vortices $a_j \in \partial\Omega$ having nonzero multiplicities $d_j \in \mathbb{Z} \setminus \{0\}$ that satisfy the topological constraint $\sum d_j = 2$. Next, we prove a Γ -convergence result (at the first order) for the 3D energy E_h where the Γ -limit depends on the number of boundary vortices detected by the global Jacobian in the regime (1.4). Finally, if we restrict to the narrower regime (1.6), we will prove a Γ -expansion at the second order of the 3D energy E_h that enables us to capture the positions of boundary vortices. More precisely, the second order term in this Γ -expansion involves the renormalized energy, similar to that of Bethuel-Brezis-Hélein [5] (see [22]) that is introduced via \mathbb{S}^1 -valued canonical harmonic maps with prescribed boundary vortices.

⁵A Lipschitz function $\zeta : \Omega \rightarrow \mathbb{R}$ has a unique Lipschitz extension to $\bar{\Omega} = \Omega \cup \partial\Omega$ that we consider (tacitly) in the following.

Canonical harmonic maps and renormalized energy. The canonical harmonic maps we consider in this paper are \mathbb{S}^1 -valued smooth harmonic maps $m_* = e^{i\phi_*}$ in Ω (i.e., $\Delta\phi_* = 0$ in Ω) that are tangent on the boundary $\partial\Omega$ except at N boundary vortices $a_j \in \partial\Omega$ where m_* winds according to the multiplicities d_j .

Definition 2 Let $\Omega \subset \mathbb{R}^2$ be a bounded, simply connected, $C^{1,1}$ regular domain and ν be the unit outer normal field on $\partial\Omega$ with the tangent field $\tau = \nu^\perp$ and the curvature \varkappa . For $N \geq 1$, we consider N distinct points $a_1, \dots, a_N \in \partial\Omega$ with the multiplicities $d_1, \dots, d_N \in \mathbb{Z} \setminus \{0\}$ such that $\sum_{j=1}^N d_j = 2$ and a BV function $\phi : \partial\Omega \rightarrow \mathbb{R}$ such that $e^{i\phi} \cdot \nu = 0$ on $\partial\Omega \setminus \{a_1, \dots, a_N\}$ and

$$\partial_\tau \phi = \varkappa - \pi \sum_{j=1}^N d_j \delta_{a_j} \quad \text{on } \partial\Omega.$$

If ϕ_* is the harmonic extension to Ω of ϕ , then $m_* = e^{i\phi_*}$ is a **canonical harmonic map** associated to $\{(a_j, d_j)\}$.

Remark 3 Note that the function ϕ in Definition 2 exists on $\partial\Omega$ because of the constraint $\sum_{j=1}^N d_j = 2$ that is equivalent via Gauss-Bonnet formula to the zero total mass of the (signed) measure $\partial_\tau \phi$, i.e., $\int_{\partial\Omega} \partial_\tau \phi = 0$. Moreover, the function ϕ is uniquely determined on $\partial\Omega$ up to an additive constant in $\pi\mathbb{Z}$. Thus, for every prescribed boundary vortices $\{a_j\}_{1 \leq j \leq N}$ with multiplicities $\{d_j\}_{1 \leq j \leq N}$, there are **exactly two canonical harmonic map** associated to $\{(a_j, d_j)\}$, i.e., $m_* = \pm e^{i\phi_*}$ for the harmonic extension ϕ_* to Ω of ϕ .

We prove the following characterization of canonical harmonic maps. Compared to the results in the seminal book of Bethuel-Brezis-Hélein [5], the novelty here consists in dealing with the constraint that the canonical harmonic maps are tangent to the boundary away from the prescribed boundary vortices.

Theorem 4 Let B_1 be the unit disk, $\{a_j\}_{1 \leq j \leq N}$ be $N \geq 1$ distinct points on ∂B_1 with multiplicities $d_1, \dots, d_N \in \mathbb{Z} \setminus \{0\}$ such that $\sum_{j=1}^N d_j = 2$. Consider a point $b \in \partial B_1 \setminus \{a_1, \dots, a_N\}$. Then any canonical harmonic map with prescribed boundary vortices $\{(a_j, d_j)\}_{1 \leq j \leq N}$ on ∂B_1 has the form

$$m_*(z) = \pm ib \prod_{j=1}^N \left(\frac{z - a_j}{|z - a_j|} \frac{|b - a_j|}{b - a_j} \right)^{d_j}, \quad \text{for all } z \in B_1. \quad (1.15)$$

If $\Omega \subset \mathbb{R}^2$ is a domain such that⁶ there exists a C^1 conformal diffeomorphism $\Phi : \overline{B_1} \rightarrow \overline{\Omega}$ with inverse Ψ , then

$$M_*(w) = m_*(\Psi(w)) \frac{\Phi'(\Psi(w))}{|\Phi'(\Psi(w))|} \quad \text{for every } w \in \Omega, \quad (1.16)$$

is the canonical harmonic map with prescribed boundary vortices $\{(\Phi(a_j), d_j)\}$ on $\partial\Omega$.

If in the formula (1.15) in the unit disk B_1 , we let $b \rightarrow a_1$, then $\frac{b-a_1}{|b-a_1|} \rightarrow \pm ia_1$ implying that any canonical harmonic map with prescribed boundary vortices $\{(a_j, d_j)\}_{1 \leq j \leq N}$ on ∂B_1 has the

⁶ By Kellogg's theorem, the existence of such C^1 conformal diffeomorphism holds for $C^{1,\alpha}$ simply connected bounded domains $\Omega \subset \mathbb{R}^2$, where $0 < \alpha < 1$.

form⁷

$$m_*(z) = \pm (ia_1)^{1-d_1} \prod_{j=1}^N \left(\frac{z-a_j}{|z-a_j|} \right)^{d_j} \prod_{j \neq 1} \left(\frac{a_1-a_j}{|a_1-a_j|} \right)^{-d_j} \quad \text{for every } z \in B_1$$

(similar formulas are obtained when b tends to another boundary vortex a_j). In particular, for $N = 2$ boundary vortices $a \neq a'$ on ∂B_1 with multiplicities $d_1 = d_2 = 1$, the canonical map is

$$m_*(z) = \pm \frac{(z-a)(z-a')|a-a'|}{|z-a||z-a'|(a-a')} \quad \text{for every } z \in B_1.$$

Renormalized energy. The interaction energy between boundary vortices is englobed in the so-called renormalized energy that we define in the following for multiplicities $d_j \in \{\pm 1\}$. This is a natural constraint on the multiplicities d_j appearing in Ginzburg-Landau type functionals when computing the exact second order expansion (in the sense of Γ -convergence).

Definition 5 *Let the transversal section $\Omega \subset \mathbb{R}^2$ be a bounded, simply connected, $C^{1,1}$ regular domain and \varkappa be the curvature on $\partial\Omega$. Consider $\phi : \partial\Omega \rightarrow \mathbb{R}$ to be a BV function such that $e^{i\phi} \cdot \nu = 0$ on $\partial\Omega \setminus \{a_1, \dots, a_N\}$ for $N \geq 2$ distinct points $a_j \in \partial\Omega$ and⁸*

$$\partial_\tau \phi = \varkappa - \pi \sum_{j=1}^N d_j \delta_{a_j} \quad \text{on } \partial\Omega \quad \text{with } d_j \in \{\pm 1\} \text{ and } \sum_{j=1}^N d_j = 2.$$

If ϕ_* is the harmonic extension to Ω of ϕ , then the **renormalized energy** of $\{(a_j, d_j)\}$ is

$$W_\Omega(\{(a_j, d_j)\}) = \lim_{\rho \rightarrow 0} \left(\int_{\Omega \setminus \bigcup_{j=1}^N B_\rho(a_j)} |\nabla \phi_*|^2 dx - N\pi \log \frac{1}{\rho} \right), \quad (1.17)$$

where $B_\rho(a_j)$ is the disk of radius ρ centered at a_j .

We prove the following formula of the renormalized energy:

Theorem 6 *Let B_1 be the unit disk, $\{a_j\}_{1 \leq j \leq N}$ be $N \geq 2$ distinct points on ∂B_1 with multiplicities $d_1, \dots, d_N \in \{\pm 1\}$ such that $\sum_{j=1}^N d_j = 2$. Then the renormalized energy defined in (1.17) satisfies*

$$W_{B_1}(\{(a_j, d_j)\}) = -2\pi \sum_{1 \leq j < k \leq N} d_j d_k \log |a_j - a_k|.$$

If $\Omega \subset \mathbb{R}^2$ is a $C^{1,1}$ simply connected bounded domain, let $\Phi : \overline{B_1} \rightarrow \overline{\Omega}$ a C^1 conformal diffeomorphism with inverse Ψ . Then for any $N \geq 2$ distinct points $\{a_j\}_{1 \leq j \leq N}$ on $\partial\Omega$ with multiplicities $d_1, \dots, d_N \in \{\pm 1\}$ such that $\sum_{j=1}^N d_j = 2$, the renormalized energy is given by

$$\begin{aligned} W_\Omega(\{(a_j, d_j)\}) &= -2\pi \sum_{1 \leq j < k \leq N} d_j d_k \log |\Psi(a_k) - \Psi(a_j)| + \sum_{k=1}^N \pi(d_k - 1) \log |\Psi'(a_k)| \\ &\quad + \int_{\partial\Omega} \varkappa \left(\sum_{j=1}^N d_j \log |\Psi(w) - \Psi(a_j)| - \log |\Psi'(w)| \right) d\mathcal{H}^1, \end{aligned}$$

where \varkappa is the curvature of $\partial\Omega$.

⁷For $N = 1$ (so, $d_1 = 2$), we use the convention that $\prod_{j \neq 1} \left(\frac{a_1 - a_j}{|a_1 - a_j|} \right)^{-d_j} = 1$ as an empty product, thus, $m_*(z) = \pm \frac{i}{a_1} \left(\frac{z - a_1}{|z - a_1|} \right)^2$.

⁸Such a function ϕ exists and is uniquely determined on $\partial\Omega$ up to an additive constant in $\pi\mathbb{Z}$, see Remark 3.

At the minimal level, we will prove that the energy functional E_h concentrates asymptotically on two boundary vortices of multiplicities 1. To locate these two boundary vortices, the following result is essential:

Corollary 7 *Let $\Omega \subset \mathbb{R}^2$ be a bounded, simply connected, $C^{1,1}$ regular domain. Then there exists a minimizer (a_1^*, a_2^*) of the renormalized energy (for the multiplicities $d_1^* = d_2^* = 1$):*

$$W_\Omega(\{(a_1^*, 1), (a_2^*, 1)\}) = \min \left\{ W_\Omega(\{(a_1, 1), (a_2, 1)\}) : a_1, a_2 \in \partial\Omega \text{ distinct points} \right\}. \quad (1.18)$$

In particular, if $\Omega = B_1$, then a_1^ and a_2^* are diametrically opposed and $W_\Omega(\{(a_1^*, 1), (a_2^*, 1)\}) = -2\pi \log 2$.*

Remark 8 Let us formally analyse minimizing configurations in (1.18) for a general bounded $C^{1,1}$ simply connected domain Ω with curvature \varkappa on the boundary $\partial\Omega$. If $\Phi : \overline{B_1} \rightarrow \overline{\Omega}$ is a C^1 conformal diffeomorphism with inverse Ψ , setting $b_1 = \Psi(a_1) \in \partial B_1$, $b_2 = \Psi(a_2) \in \partial B_1$ for two distinct points $a_1, a_2 \in \partial\Omega$ with $d_1 = d_2 = 1$, then Theorem 6 implies

$$\begin{aligned} W_\Omega(\{(a_1, 1), (a_2, 1)\}) \\ = -2\pi \log |\Psi(a_1) - \Psi(a_2)| + \int_{\partial\Omega} \varkappa \left(\log |\Psi(w) - b_1| + \log |\Psi(w) - b_2| - \log |\Psi'(w)| \right) d\mathcal{H}^1. \end{aligned}$$

After the change of variable $z = \Psi(w)$, we obtain

$$\begin{aligned} W_\Omega(\{(a_1, 1), (a_2, 1)\}) \\ = -2\pi \log |b_1 - b_2| + \int_{\partial B_1} \varkappa(\Phi(z)) |\Phi'(z)| \left(\log |z - b_1| + \log |z - b_2| + \log |\Phi'(z)| \right) d\mathcal{H}^1(z). \end{aligned}$$

Then any minimal configuration (a_1^*, a_2^*) in (1.18) corresponds to points $b_1^* = \Psi(a_1^*)$ and $b_2^* = \Psi(a_2^*)$ that are expected to be the furthest apart and for which the curvature \varkappa at a_1^* and a_2^* is the highest (as $\log |z - b_j^*|$ is negative for z close to b_j^* , $j = 1, 2$), but there is a nontrivial competition between these effects through the influence of the conformal map.

In particular, for an ellipse domain Ω , a_1^* and a_2^* are expected to be placed at the two poles of major axis as this configuration maximizes the diameter and the curvature of $\partial\Omega$. Also, if Ω is a “smoothed” rectangle (i.e., every corner is replaced by a convex $C^{1,1}$ curve), then the two boundary vortices a_1^* and a_2^* are expected to be diagonally opposed (so called S -state) as again this configuration maximizes the distance $|a_1^* - a_2^*|$ and the curvature of $\partial\Omega$. We refer to [3] for a more detailed discussion of the situation in rectangles and computations of the relevant energies.

This scenario is similar to the one analysed by Ignat-Jerrard [20] in a Ginzburg-Landau model for tangent vector fields on a two-dimensional Riemannian manifold: on surfaces of genus 0, two vortices of degree one nucleate and the optimal position of such a pair of vortices is expected to maximize the distance between the vortices and the Gauss curvature of the surface.

Γ -expansion. We can now state the main theorems of the paper, which contain several compactness results and two orders of energy expansion by Γ -convergence. We start with compactness and lower bound.

Theorem 9 Let $\Omega \subset \mathbb{R}^2$ be a bounded, simply connected, $C^{1,1}$ regular domain. If $h \rightarrow 0$, $\eta = \eta(h) \rightarrow 0$ and $\varepsilon = \varepsilon(h) \rightarrow 0$ satisfy the regime (1.4), then the following holds: Assume $\mathbf{m}_h \in H^1(\Omega_h; \mathbb{S}^2)$ is a sequence of magnetizations such that

$$\limsup_{h \rightarrow 0} E_h(\mathbf{m}_h) < \infty$$

with E_h defined in (1.2) and let $\bar{\mathbf{m}}_h = (\bar{m}_h, \bar{m}_{h,3})$ be the average defined in (1.7).

- (i) **Compactness of the global Jacobian and of the traces $\bar{\mathbf{m}}_h|_{\partial\Omega}$.** For a subsequence, the global Jacobians of the in-plane averages $\mathcal{J}(\bar{m}_h)$ converge to a measure J on the closure $\bar{\Omega}$, in the sense that⁹

$$\sup_{|\nabla\zeta| \leq 1 \text{ in } \Omega} |\langle \mathcal{J}(\bar{m}_h) - J, \zeta \rangle| \rightarrow 0 \quad \text{as } h \rightarrow 0, \quad (1.19)$$

J is supported on $\partial\Omega$ and has the form

$$J = -\varkappa \mathcal{H}^1 \llcorner \partial\Omega + \pi \sum_{j=1}^N d_j \delta_{a_j} \quad \text{with} \quad \sum_{j=1}^N d_j = 2 \quad (1.20)$$

for $N \geq 1$ distinct boundary vortices $a_j \in \partial\Omega$ carrying the non-zero multiplicities¹⁰ $d_j \in \mathbb{Z} \setminus \{0\}$. Moreover, for a subsequence, the trace of the averages $\bar{\mathbf{m}}_h|_{\partial\Omega}$ converges as $h \rightarrow 0$ in $L^p(\partial\Omega)$ (for every $p \in [1, \infty)$) to $(e^{i\phi}, 0) \in BV(\partial\Omega; \mathbb{S}^1 \times \{0\})$ for a BV lifting ϕ of the tangent field $\pm\tau$ on $\partial\Omega$ determined (up to a constant in $\pi\mathbb{Z}$) by $\partial_\tau\phi = -J$ on $\partial\Omega$.

- (ii) **First order lower bound.** The energy satisfies

$$\liminf_{h \rightarrow 0} E_h(\mathbf{m}_h) \geq \pi \sum_{j=1}^N |d_j|.$$

- (iii) **Single multiplicity and second order lower bound.** If additionally $\frac{\log|\log h|}{|\log h|} \ll \varepsilon$ and

$$\limsup_{h \rightarrow 0} |\log \varepsilon| \left(E_h(\mathbf{m}_h) - \pi \sum_{j=1}^N |d_j| \right) < \infty,$$

then the multiplicities satisfy $d_j = \pm 1$ for $1 \leq j \leq N$ and the finer energy lower bound holds:

$$\liminf_{h \rightarrow 0} |\log \varepsilon| (E_h(\mathbf{m}_h) - \pi N) \geq W_\Omega(\{(a_j, d_j)\}) + \gamma_0 N,$$

where $\gamma_0 = \pi \log \frac{e}{4\pi}$ is a constant and the renormalized energy W_Ω is defined in (1.17).

- (iv) **Strong compactness of the rescaled magnetization.** Under the assumptions in (iii), we also have for every $q \in [1, 2)$ the bound

$$\limsup_{h \rightarrow 0} \frac{1}{h} \int_{\Omega_h} |\nabla \mathbf{m}_h|^q dx < \infty.$$

⁹This quantity is stronger than the usual $W^{-1,1}(\Omega)$ -norm because our test functions in (1.19) are not necessarily zero on the boundary $\partial\Omega$.

¹⁰These multiplicities correspond to twice the winding number around the boundary vortices.

For a subsequence we have that $\tilde{\mathbf{m}}_h(x, x_3) : \Omega_1 \rightarrow \mathbb{S}^2$ defined by $\tilde{\mathbf{m}}_h(x, x_3) = \mathbf{m}_h(x, hx_3)$ converges strongly in every $L^p(\Omega_1)$, $1 \leq p < \infty$, to a $W^{1,q}$ -map $\tilde{\mathbf{m}} = (\tilde{m}, 0)$ with $|\tilde{\mathbf{m}}| = |\tilde{m}| = 1$ and $\partial_{x_3} \tilde{\mathbf{m}} = 0$, i.e., $\tilde{\mathbf{m}} = \tilde{\mathbf{m}}(x) \in W^{1,q}(\Omega, \mathbb{S}^1 \times \{0\})$ for every $q \in [1, 2)$. Moreover, the global Jacobian¹¹ $\mathcal{J}(\tilde{m})$ coincides with the measure J on $\bar{\Omega}$ given in (1.20).

We have a corresponding upper bound statement constructing a recovery sequence:

Theorem 10 *Let $\Omega \subset \mathbb{R}^2$ be a bounded, simply connected, $C^{1,1}$ regular domain, $h > 0$ and $\eta = \eta(h) > 0$ satisfying regime (1.4). Given any collection of $N \geq 1$ distinct points $\{a_j \in \partial\Omega\}_{1 \leq j \leq N}$ and $\{d_j \in \mathbb{Z} \setminus \{0\}\}_{1 \leq j \leq N}$ with $\sum_{j=1}^N d_j = 2$, we can find $\mathbf{M}_h = (M_h, 0) \in H^1(\Omega_h; \mathbb{S}^1)$ with the following properties:*

- (i) \mathbf{M}_h is independent of x_3 , i.e. $\partial_{x_3} \mathbf{M}_h = 0$ in Ω_h .
- (ii) For any $0 < x_3 < h$, the global Jacobians $\mathcal{J}(M_h(\cdot, x_3))$ of the in-plane averages $M_h(\cdot, x_3)$ converge in the sense of (1.19) to $J = -\varkappa \mathcal{H}^1 \llcorner \partial\Omega + \pi \sum_{j=1}^N d_j \delta_{a_j}$ as $h \rightarrow 0$, the average $\bar{\mathbf{M}}_h$ converges to $(m_*, 0)$ in $L^p(\Omega)$ and $L^p(\partial\Omega)$ for every $p \in [1, \infty)$, where m_* is a canonical harmonic map associated to $\{(a_j, d_j)\}$ and

$$\lim_{h \rightarrow 0} E_h(\mathbf{M}_h) = \pi \sum_{j=1}^N |d_j|.$$

- (iii) If furthermore $|d_j| = 1$ for all $j = 1, \dots, N$ and the narrower regime (1.6) holds, then \mathbf{M}_h satisfies

$$\lim_{h \rightarrow 0} |\log \varepsilon|(E_h(\mathbf{M}_h) - \pi N) = W_\Omega(\{(a_j, d_j)\}) + N\gamma_0.$$

The results of Theorems 9 and 10 generalize those we obtained [22] for the reduced energy \bar{E}_h (restated as Theorem 18 below), and in fact our proof uses Theorem 1 to connect these results.

By standard properties of Γ -convergence and our previous work in [22], we deduce:

Corollary 11 *If $\Omega \subset \mathbb{R}^2$ is a bounded, simply connected, $C^{1,1}$ regular domain, $h \rightarrow 0$, $\eta = \eta(h) \rightarrow 0$ and $\varepsilon = \varepsilon(h) \rightarrow 0$ satisfy the regime (1.4) and \mathbf{m}_h are minimizers of E_h as defined in (1.2), then the following holds: There exists a subsequence $h \rightarrow 0$ such that the global Jacobians $\mathcal{J}(\bar{m}_h)$ of the in-plane averages \bar{m}_h satisfy*

$$\mathcal{J}(\bar{m}_h) \rightarrow J = -\varkappa \mathcal{H}^1 \llcorner \partial\Omega + \pi(\delta_{a_1^*} + \delta_{a_2^*})$$

in the sense of (1.19), for $a_1^*, a_2^* \in \partial\Omega$ and the energy satisfies

$$\lim_{h \rightarrow 0} E_h(\mathbf{m}_h) = 2\pi.$$

If additionally the assumption $\frac{\log |\log h|}{|\log h|} \ll \varepsilon$ is satisfied, then $a_1^* \neq a_2^*$, the pair (a_1^*, a_2^*) minimizes¹² $W_\Omega(\{(a_1, 1), (a_2, 1)\})$ over the set $\{(a_1, a_2) \in \partial\Omega \times \partial\Omega : a_1 \neq a_2\}$ and

$$\lim_{h \rightarrow 0} |\log \varepsilon|(E_h(\mathbf{m}_h) - 2\pi) = W_\Omega(\{(a_1^*, 1), (a_2^*, 1)\}) + 2\pi \log \frac{e}{4\pi};$$

¹¹The global Jacobian $\mathcal{J}(\tilde{m})$ is well-defined as $\tilde{m} \in W^{1,1}(\Omega, \mathbb{S}^1)$, compare with footnote 4.

¹²For the existence of minimizers of W_Ω , recall Corollary 7.

furthermore, the sequence $\tilde{\mathbf{m}}_h(x, x_3) : \Omega_1 \rightarrow \mathbb{S}^2$ defined by $\tilde{\mathbf{m}}_h(x, x_3) = \mathbf{m}_h(x, hx_3)$ converges strongly in every $L^p(\Omega_1)$, $1 \leq p < \infty$, to an x_3 -invariant $W^{1,q}$ -map $\tilde{\mathbf{m}} = (m_*, 0)$ with m_* is a canonical harmonic map associated to $\{(a_1^*, 1), (a_2^*, 1)\}$ in Ω .

Remark 12 In the unit disk $\Omega = B_1$, by Theorem 6 and Corollary 7, the renormalized energy for two boundary vortices of multiplicities 1 has the form $W_{B_1}(\{(a_1, 1), (a_2, 1)\}) = -2\pi \log |a_1 - a_2|$ and any minimal configuration is given by two diametrically opposed points a_1^* and a_2^* on ∂B_1 yielding $W_{B_1}(\{(a_1^*, 1), (a_2^*, 1)\}) = -2\pi \log 2$. Together with Corollary 11, we obtain

$$\lim_{h \rightarrow 0} |\log \varepsilon| (E_h(\mathbf{m}_h) - 2\pi) = -2\pi \log 2 + 2\pi \log \frac{e}{4\pi} = 2\pi \log \frac{e}{8\pi}.$$

Remark 13 Theorem 9 (iii) and Corollary 11 suggest that for minimizers \mathbf{m}_h of E_h , no higher degree transitions can occur, as the limit only shows singularities of multiplicity 1. This is similar to results for interior Ginzburg-Landau vortices [5]. Generalizing from minimizers to critical points, the situation appears fundamentally different between boundary and interior vortices, as can be seen from the (blow up) results in the whole plane or the half plane: For Ginzburg-Landau vortices, (unstable) solutions of higher degrees were shown to exist by Hervé-Hervé [16] and Chen-Elliott-Qi [9]. In the boundary vortex case, solutions on a half plane can only have a single transition by results of Toland [42] and Cabré-Solà-Morales [7]. By recent results of Baffetti et al. [4] for critical points of an \mathbb{S}^1 -valued model of boundary vortices on a bounded domain, it is impossible for these transitions to cluster at distances that are $\gg \varepsilon$, but $\ll 1$, so the limit can only have singularities of multiplicity 1.

Remark 14 We have required that the domain is simply connected. The results are **false** for doubly connected domains, but analogous results to ours can be expected to hold for domains of higher connectivity. Doubly connected domains (like an annulus) are special because they support continuous vector fields that are tangential to the boundary **everywhere**, and there are even examples of smooth magnetizations on such domains for which the stray field vanishes, as noted in the physics literature by Arrott et al. [2].

Outline of the paper

The rest of the paper is organized as follows: In the next section, we describe a panorama of thin film regimes and the main features of interior and boundary vortices in micromagnetics. In Section 3, we reduce the nonlocal 3D energy E_h energy to the simplified local functional \bar{E}_h in (1.9) by showing that these energies are close to each other up to $o(\frac{1}{|\log \varepsilon|})$ (or $o(1)$ for the highest order of Γ -development), see Theorem 1. This is done by a careful series of estimates that refine results of Gioia-James [15], Carbou [8] and Kohn-Slastikov [28] in a more quantitative way. In Section 4, we prove Theorem 9 using the analysis of the simplified local functional \bar{E}_h in (1.9) from our companion article [22]. In Section 5, we prove the properties of the canonical harmonic maps and the renormalized energy stated in Theorems 4 and 6 as well as Corollary 7. We end with an appendix proving the characterization of the stray field in (1.1).

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2 Related models. Micromagnetic vortices

Our choice of thin film regime (1.4) is not the only one that leads to a thin film Γ -limit. In fact, there is a whole range of possible limits, and we give a short panoramic overview here, see Figure 1. We always assume $h \ll 1$ which corresponds to thin film regimes. The most obvious thin film limit (of letting $h \rightarrow 0$) corresponds to small magnetic samples where $\eta > 0$ is fixed (i.e., $A \sim \ell$); this regime has been studied by Gioia-James [15] (see also Kreisbeck [29] for an alternate approach). The resulting Γ -limit is somewhat degenerate in the sense that it is minimized by all constant in-plane magnetizations and does not depend on the shape of the film. Recently, Morini-Slastikov [37] also studied small films with additional surface roughness and were able to derive a homogenized thin film limit, with constant minimizers determined by the geometry of the roughness.

The case of larger magnetic samples $\eta \ll 1$, i.e., the exchange length A is small compared with the diameter ℓ , is more important as it is physically achievable. There are different convergence rates of $\eta(h) \rightarrow 0$ as $h \rightarrow 0$ corresponding to samples of various size and leading to various regimes where different effects come into play. Three types of singular pattern of the magnetization occur: Néel walls, interior and boundary micromagnetic vortices. The choice of the asymptotic regimes will correspond to the energy ordering of these three patterns (for more details, see [12]). All of the regimes we study are separated only by logarithmic (or even doubly logarithmic) terms. For this reason, the sharp separation of regimes found by Γ -convergence is more prominent in the analysis than in physical or numerical experiments at finite sample sizes. We list some regimes and the related results by increasing sample size, corresponding to decreasing η .

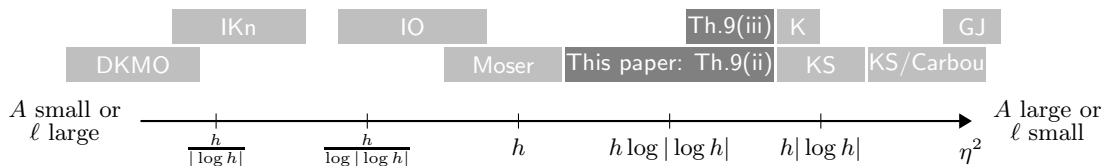


Figure 1: An approximate panoramic view (not to scale) of thin film limits and their range of validity (results of this article in dark grey, others in light grey: DKMO=DeSimone et al. [10], IKn=Ignat-Knüpfer [21], IO=Ignat-Otto [27], Moser [39], KS=Kohn-Slastikov [28], Carbou [8], GJ=Gioia-James [15]). The results of K=Kurzke [31, 30, 32] can be interpreted as a limit at the left “larger films” end of the KS regime.

In the regime of relatively small films, characterized by $\eta^2 \gg h|\log h|$, the exchange term in the energy dominates completely and the magnetization becomes a constant unit-length vector in the film plane. A corresponding Γ -limit was derived by Kohn-Slastikov [28], related to earlier work by Carbou [8]. Their result is that the nonlocal magnetostatic energy reduces to a local contribution of the boundary $\frac{1}{2\pi} \int_{\partial\Omega} (m \cdot \nu)^2 d\mathcal{H}^1$, which selects the preferred directions of the constant magnetization vector.

Slightly larger films, where $\eta^2 = \alpha h|\log h|$ with $0 < \alpha < \infty$, were also studied by Kohn-Slastikov. Here, the limiting magnetizations are still required to lie in the film plane, but no longer need to be constant. Instead, the exchange energy and the boundary contribution compete, and

the rescaled energy Γ -converges to

$$E_{KS}^\alpha(m) = \alpha \int_{\Omega} |\nabla m|^2 dx + \frac{1}{2\pi} \int_{\partial\Omega} (m \cdot \nu)^2 d\mathcal{H}^1, \quad m \in H^1(\Omega; \mathbb{S}^1).$$

A second limit, describing the behavior of $\frac{1}{\alpha} E_{KS}^\alpha$ when $\alpha \rightarrow 0$, was examined by Kurzke [31, 30, 32]. There is no $m \in H^1(\Omega; \mathbb{S}^1)$ that satisfies $m \cdot \nu = 0$ on $\partial\Omega$ if Ω is a simply connected domain. For this reason, the boundary term cannot be made zero, and for small α we obtain the emergence of boundary vortices, where the magnetization quickly rotates from $m \approx \tau$ to $m \approx -\tau$ over a boundary segment of length $O(\alpha)$ (see Section 2.1 for further details). The highest order term in the energy expansion relates to the number of boundary vortices, while their interaction is governed by a renormalized energy appearing as the next order term in the energy expansion as $\alpha \rightarrow 0$. However, the significance of these results in the context of the full micromagnetic energy remained unclear for a long time; the main purpose of the present paper is to clarify this.

Our Theorem 9 in the present article directly relates to the micromagnetic energy and shows that the double limit procedure of Kohn-Slastikov and Kurzke yields the correct result for the highest order of the energy and its concentration at boundary vortices if we are in the regime $h \ll \eta^2 \ll h|\log h|$. In the narrower regime $h \log |\log h| \ll \eta^2 \ll h|\log h|$, we obtain the same renormalized energy as Kurzke.

The next regime, $\eta^2 = O(h)$, was studied by Moser [38, 39, 40]. Here, both the magnetostatic and exchange terms survive in the limit, and again, an incompatibility produces boundary vortices. To highest order, the energy is proportional to the number of vortices. The corresponding boundary vortex interaction is nonlocal here, in contrast to the local renormalized energy of the present article. For a review of these models, we refer to Kurzke-Melcher-Moser [33].

In large thin films corresponding to the regime $\eta^2 \ll h$, Néel walls nucleate in the magnetic sample. The (symmetric) Néel wall is a transition layer describing a one-dimensional in-plane rotation connecting two (opposite) directions of the magnetization. It is a two-length scale object with a core of size of order $\frac{\eta^2}{h}$ and two logarithmically decaying tails (see [35, 36, 11, 24]). Various aspects of Néel walls (existence of topological Néel walls with prescribed winding number, interaction between Néel walls, cross-over from symmetric to asymmetric Néel walls etc.) have been analyzed recently (see e.g. [14, 13, 17, 24, 25, 26]).

We now describe briefly three sub-regimes for the limit $\eta^2 \ll h$ where the nonlocality of the reduced energy is carried by the $H^{-1/2}$ norm of the volume charges $\nabla \cdot m$ inside Ω yielding the highest order energy of Néel walls (for more details, see section 7.2. in [19]). The sub-regime $\eta^2 |\log \frac{\eta^2}{h}| \gg \frac{h}{\log |\log h|}$ yielding

$$\frac{h}{\log |\log h| \cdot \log \log |\log h|} \ll \eta^2 \ll h$$

was studied by Ignat-Otto [27]: next to the nonlocal term, the reduced energy penalizes the out-of-plane component m_3 . The constraint $m \cdot \nu = 0$ is imposed (so no \mathbb{S}^1 -valued boundary vortices nucleate in that model); thus, the Landau state is composed by Néel walls and topological point singularities where $m_3 = \pm 1$ nucleating either in the interior or at boundary of Ω .

Ignat-Knüpfer [21] studied a further regime of slightly larger films, characterized by $\frac{h}{|\log h|} \ll \eta^2 |\log \frac{\eta^2}{h}| \ll \frac{h}{\log |\log h|}$, yielding

$$\frac{h}{|\log h| \cdot \log |\log h|} \ll \eta^2 \ll \frac{h}{\log |\log h| \cdot \log \log |\log h|}.$$

The model is described by \mathbb{S}^1 -valued magnetizations, so the system nucleates Néel walls and boundary vortices. It is proved in [21] that the Landau state in circular thin film is given by a peculiar vortex structure, driven by a topological Néel wall of winding number 1 accompanied by a pair of micromagnetic boundary vortices (so the S-state is less favorable in that model).

In very large films, characterized by $\eta^2 \ll \frac{h}{|\log h|}$, the contribution of the exchange energy disappears completely, and one obtains a purely magnetostatic model driven by $\|\nabla \cdot m\|_{H^{-1/2}}^2$ where the constraint $|m| = 1$ relaxes to $|m| \leq 1$, see DeSimone et al. [10, 12].

A very interesting question is how to describe pattern formation involving different length scales in a rigorous way. For example, boundary vortices, interior vortices and Néel walls scale differently, so they are not expected to be simultaneously captured by minimizing a single Γ -limit. Nevertheless, in this example the scales are only separated by logarithms, so phenomena involving more than one type of pattern can be physically observed. To cover this within the frameworks described above would necessitate going beyond minimizers and to study also higher-energy metastable states.

2.1 Topological point defects

We further present some heuristics on interior and boundary vortices that shows the importance of the global Jacobian. More details can be found in [22].

Interior vortex. The prototype of an interior vortex is given by a map

$$\mathbf{m} = (m, m_3) : B_1 \rightarrow \mathbb{S}^2$$

defined in a circular cross-section $\Omega = B_1$ of a thin film that minimizes the reduced energy \bar{E}_h defined in (1.9) under the boundary condition

$$m = \tau \quad \text{on} \quad \partial B_1, \quad (2.1)$$

where $\tau(x) = (-x_2, x_1)$ is a tangent vector at $x \in \partial B_1$. (Recall that B_1 is the unit disk in \mathbb{R}^2 .) Thus, the magnetization turns in-plane at the boundary, in particular, m carries a topological degree $\deg(m, \partial\Omega) = 1$. As for the Ginzburg-Landau energy, a localized region is created at the center that is the core of the vortex of size η . The difference consists in the polarity carried by micromagnetic interior vortex according to the value $m_3 = \pm 1$ at the vortex point given by the topologic zero of m where the magnetization \mathbf{m} becomes perpendicular to the horizontal plane (see Figure 2). Note that the reduced energy \bar{E}_h (renormalized by $|\log \varepsilon|$) controls the Ginzburg-Landau

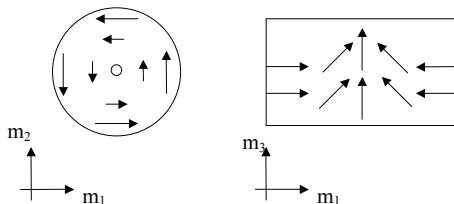


Figure 2: Micromagnetic interior vortex of winding number one and polarity one.

energy defined in (1.12), i.e.,

$$|\log \varepsilon| \bar{E}_h(\mathbf{m}) = \int_{\Omega} |\nabla \mathbf{m}|^2 dx + \frac{1}{\eta^2} \int_{\Omega} (1 - |m|^2) dx \geq \int_{\Omega} e_{\eta}(m) dx$$

since $|\nabla m|^2 \leq |\nabla(m, m_3)|^2$ and $(1 - |m|^2)^2 = m_3^4 \leq m_3^2 = 1 - |m|^2$. Thus, the analogy with the theory of Ginzburg-Landau vortices (see [5] and the review paper [18, Section 7]) yields:

$$\min_{(2.1)} \bar{E}_h(\mathbf{m}) = \frac{2\pi |\log \eta|}{|\log \varepsilon|} + O\left(\frac{1}{|\log \varepsilon|}\right) \quad \text{as } \varepsilon, \eta \rightarrow 0.$$

As $m = \tau$ at the boundary, the boundary Jacobian of m (defined in (1.13)) is carried by the curvature $\varkappa = 1$ on $\partial\Omega$ (without any singular part), while the interior Jacobian of m asymptotically concentrates on a Dirac measure δ_0 at the origin (up to a multiplicative constant); summing up, the global Jacobian of m is given by

$$\mathcal{J}(m) = 2\pi\delta_0 - \varkappa \mathcal{H}^1 \llcorner \partial\Omega + o(1) \quad \text{as } \varepsilon, \eta \rightarrow 0.$$

Boundary vortex. The typical situation is given by an \mathbb{S}^1 -valued map m that minimizes the reduced energy in the unit disk $\Omega = B_1$ (i.e., $m_3 = 0$ in B_1):

$$\bar{E}_h(m) = \frac{1}{|\log \varepsilon|} \left(\int_{\Omega} |\nabla m|^2 dx + \frac{1}{2\pi\varepsilon} \int_{\partial\Omega} (m \cdot \nu)^2 d\mathcal{H}^1 \right) \quad \text{with } m : \Omega \rightarrow \mathbb{S}^1,$$

where $\nu = x$ on ∂B^2 . This problem has been analyzed by Kurzke [31, 30] and Moser [38]: any minimizer m is an harmonic map of unit length driven by a pair of boundary vortices P_1 and P_2 that are expected to be diametrically opposed of degree $1/2$ (see Figure 3). A boundary vortex of degree $1/2$ corresponds to an in-plane transition of the magnetization m along the boundary from $-\tau$ to $\tau = \nu^\perp$, i.e., the lifting of m has an asymptotically jump of $-\pi$ (see Figure 4). The transition is regularized due to the exchange energy and the core of the boundary vortex has size ε . The cost of such a transition is given by

$$\frac{1}{2} \bar{E}_h(m) = \pi + O\left(\frac{1}{|\log \varepsilon|}\right).$$

As m is smooth of unit-length in Ω , the interior Jacobian of m vanishes so that the global Jacobian of m is concentrated at the boundary: it is asymptotically given by a measure of regular part carried by the negative of the curvature, $-\varkappa = -1$ on $\partial\Omega$ and of singular part carried by two Dirac measures at P_1 and P_2 :

$$\mathcal{J}(m) = \mathcal{J}_{bd}(m) = 2\pi \left(\frac{1}{2} \delta_{P_1} + \frac{1}{2} \delta_{P_2} \right) - \varkappa \mathcal{H}^1 \llcorner \partial\Omega + o(1) \quad \text{as } \varepsilon, \eta \rightarrow 0.$$

Comparing with the interior vortex case, we see a justification for calling these “half-degree” vortices. However, for notational convenience we have written $\pi d_j \delta_{a_j}$ with $d_j \in \mathbb{Z}$ instead of $2\pi d_j \delta_{a_j}$ with $d_j \in \frac{1}{2}\mathbb{Z}$ in the remainder of this paper.

In our regime (1.4) and with the energy scaling (1.2), an “essential” interior vortex will asymptotically induce infinite energy (because $|\log \varepsilon| \ll |\log \eta|$ as $\varepsilon, \eta \rightarrow 0$) while boundary vortices carry only finite energy. Therefore, we expect that no essential interior vortex nucleates for magnetizations of uniformly bounded energy so that our \mathbb{S}^2 -valued magnetizations can be approximated by \mathbb{S}^1 -valued maps (this expectation can be made rigorous using the estimates of [23], see [22, Theorem 3.1]) and the global Jacobian asymptotically concentrates at the boundary according to (1.20).

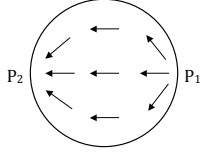


Figure 3: Two boundary vortices P_1 and P_2 of degree $1/2$.

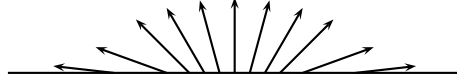


Figure 4: Boundary vortex of degree $+1/2$ in the upper half-plane $\mathbb{R} \times (0, \infty)$ within the frame $(\nu = -e_2, \tau = e_1)$.

3 Reduction to a local model. Proof of Theorem 1

In this section we relate the nonlocal 3D micromagnetic energy E_h for the magnetization \mathbf{m}_h in (1.2) to the simpler local 2D energy functional \bar{E}_h for the average $\bar{\mathbf{m}}_h$ in (1.9). The aim is to prove Theorem 1; for that, the key estimate is given in the following result. It is a more quantitative version of estimates of Carbou [8] and Kohn-Slastikov [28].

Lemma 15 *Let $\Omega_h = \Omega \times (0, h)$ with $\Omega \subset \mathbb{R}^2$ be a simply connected ¹³ $C^{1,1}$ domain. In the regime (1.4) of parameters $h, \eta(h), \varepsilon(h) > 0$, we consider a family of magnetizations $\{\mathbf{m}_h : \Omega_h \rightarrow \mathbb{S}^2\}_{h \rightarrow 0}$ and stray field potentials $\{U_h\}_{h \rightarrow 0}$ given by (1.3) of uniformly bounded energy $\limsup_{h \rightarrow 0} E_h(\mathbf{m}_h) < \infty$. Then we have the estimates as $h \rightarrow 0$.¹⁴*

$$0 \leq \frac{1}{\eta^2 |\log \varepsilon|} \left[\int_{\Omega} (1 - |\bar{\mathbf{m}}_h|^2) dx - \int_{\Omega} \bar{m}_{h,3}^2 dx \right] = \sqrt{\frac{E_h(\mathbf{m}_h)}{|\log \varepsilon|}} O\left(\frac{h}{\eta^2}\right) \quad (3.1)$$

and

$$E_h(\mathbf{m}_h) \geq \bar{E}_h(\bar{\mathbf{m}}_h) - \left(\bar{E}_h(\bar{\mathbf{m}}_h) + \sqrt{\frac{E_h(\mathbf{m}_h)}{|\log \varepsilon|}} \right) O(\lambda(h)), \quad (3.2)$$

where $\bar{\mathbf{m}}_h = (\bar{m}_h, \bar{m}_{h,3})$ is the x_3 -average of \mathbf{m}_h , \bar{E}_h is the reduced energy defined in (1.9), and

$$\lambda(h) = \frac{h}{\eta^2} \left(\frac{\log \frac{\eta^2}{h}}{|\log \varepsilon|} + 1 \right) = \frac{1}{\varepsilon |\log \varepsilon|} \frac{\log |\log h|}{|\log h|} \ll 1. \quad (3.3)$$

Note that $\lambda(h) \ll 1$ is a direct consequence of (1.5).

Proof. First, we prove the estimate (3.1) for the distance of $\bar{\mathbf{m}}_h$ to the unit sphere \mathbb{S}^2 . For that, denoting $\mathbf{m}_h = (m_{h,1}, m_{h,2}, m_{h,3})$ and recalling that $|\bar{\mathbf{m}}_h| \leq 1 = |\mathbf{m}_h|$ in Ω_h , the Cauchy-Schwarz

¹³This assumption is crucial: in fact, we use e.g. in the proof of Lemma 16 that $\bar{E}_h(\bar{\mathbf{m}}_h) \gtrsim 1$ as $h \rightarrow 0$ which may fail if the domain is topologically an annulus. Lower energy configurations are possible there, compare Remark 14.

¹⁴The implicit constants in the big O notation in (3.1) and (3.2) depend only on Ω .

and Poincaré inequalities imply for $1 \leq k \leq 3$:

$$\begin{aligned}
\int_{\Omega_h} |m_{h,k}^2(x, x_3) - \bar{m}_{h,k}^2(x)| d\mathbf{x} &\leq 2 \int_{\Omega} dx \int_0^h |m_{h,k}(x, x_3) - \bar{m}_{h,k}(x)| dx_3 \\
&\leq 2\sqrt{h} \int_{\Omega} dx \left(\int_0^h |m_{h,k}(x, x_3) - \bar{m}_{h,k}(x)|^2 dx_3 \right)^{1/2} \\
&\leq Ch^{3/2} \int_{\Omega} dx \left(\int_0^h |\partial_{x_3} m_{h,k}(x, x_3)|^2 dx_3 \right)^{1/2} \\
&\leq Ch^{3/2} \left(\int_{\Omega_h} |\partial_{x_3} m_{h,k}(\mathbf{x})|^2 d\mathbf{x} \right)^{1/2},
\end{aligned}$$

for $C > 0$ is a constant depending only on Ω that changes from line to line. Since $|\mathbf{m}_h| = 1$, summing for $k = 1, 2, 3$, we deduce

$$\int_{\Omega} (1 - |\bar{\mathbf{m}}_h|^2) dx \leq Ch(|\log \varepsilon| E_h(\mathbf{m}_h))^{1/2}, \quad (3.4)$$

which leads to (3.1) because $0 \leq 1 - |\bar{\mathbf{m}}_h|^2 = (1 - |\bar{m}_h|^2) - \bar{m}_{h,3}^2$.

For the second inequality, we start by noting that Jensen's inequality implies

$$\int_{\Omega} |\nabla \bar{\mathbf{m}}_h|^2 dx \leq \frac{1}{h} \int_{\Omega_h} |\nabla \mathbf{m}_h|^2 dx.$$

To estimate the stray field energy, we use the strategy of Kohn-Slastikov (see [28], Lemma 3). We denote by $\bar{U}_h \in H^1(\mathbb{R}^3)$ the stray field potential associated to $\bar{\mathbf{m}}_h \mathbf{1}_{\Omega_h}$ in (1.8). The definition of Helmholtz projection (1.1) together with the Poincaré inequality lead to

$$\begin{aligned}
\int_{\mathbb{R}^3} |\nabla U_h|^2 dx &\leq \int_{\Omega_h} |\mathbf{m}_h|^2 dx \leq Ch, \quad \int_{\mathbb{R}^3} |\nabla \bar{U}_h|^2 dx \leq \int_{\Omega_h} |\bar{\mathbf{m}}_h|^2 dx \leq Ch, \\
\int_{\mathbb{R}^3} |\nabla U_h - \nabla \bar{U}_h|^2 dx &\leq \int_{\Omega_h} |\mathbf{m}_h - \bar{\mathbf{m}}_h|^2 dx \leq Ch^2 \int_{\Omega_h} |\partial_{x_3} \mathbf{m}_h|^2 dx.
\end{aligned}$$

Since $\|a\|^2 - \|b\|^2 \leq (2\|a - b\|^2(\|a\|^2 + \|b\|^2))^{1/2}$, we finally obtain:

$$\begin{aligned}
\frac{1}{\eta^2 h |\log \varepsilon|} \left| \int_{\mathbb{R}^3} |\nabla U_h|^2 dx - \int_{\mathbb{R}^3} |\nabla \bar{U}_h|^2 dx \right| &\leq \frac{Ch}{\eta^2 |\log \varepsilon|} \left(\frac{1}{h} \int_{\Omega_h} |\partial_{x_3} \mathbf{m}_h|^2 dx \right)^{1/2} \\
&\leq C \frac{h}{\eta^2} \sqrt{\frac{E_h(\mathbf{m}_h)}{|\log \varepsilon|}}.
\end{aligned}$$

Next, we use Lemma 16 below to estimate the stray field energy generated by \bar{U}_h . Then (3.2) follows by using (3.1). \square

The following result improves computations of [8] and [28] in our regime (1.4).

Lemma 16 *Under the assumptions in Lemma 15, if \bar{U}_h is the stray field potential associated to the x_3 -average $\bar{\mathbf{m}}_h : \Omega \rightarrow \bar{B}^3$ in (1.8), then we have for $h \rightarrow 0$:*

$$\frac{1}{|\log \varepsilon|} \left| \frac{1}{\eta^2 h} \int_{\mathbb{R}^3} |\nabla \bar{U}_h|^2 dx - \frac{1}{\eta^2} \int_{\Omega} \bar{m}_{h,3}^2 dx - \frac{1}{2\pi\varepsilon} \int_{\partial\Omega} (\bar{m}_h \cdot \nu)^2 d\mathcal{H}^1 \right| \leq C\lambda(h) \bar{E}_h(\bar{\mathbf{m}}_h) \quad (3.5)$$

where $\lambda(h) > 0$ is given in (3.3) and $C > 0$ is a constant depending on Ω .

Proof. From (1.1), integration by parts yields

$$\int_{\mathbb{R}^3} |\nabla \bar{U}_h|^2 d\mathbf{x} = \int_{\Omega_h} \nabla \bar{U}_h \cdot \bar{\mathbf{m}}_h d\mathbf{x} = - \int_{\Omega_h} \bar{U}_h \nabla \cdot \bar{\mathbf{m}}_h d\mathbf{x} + \int_{\partial\Omega_h} \bar{U}_h (\bar{\mathbf{m}}_h \cdot \boldsymbol{\nu}) d\mathcal{H}^2(\mathbf{x}),$$

where $\boldsymbol{\nu} = (\nu, \nu_3)$ is the unit outer normal vector to $\partial\Omega_h$. By Proposition 24 in the Appendix, we have for every $\mathbf{x} \in \mathbb{R}^3$:

$$4\pi \bar{U}_h(\mathbf{x}) = - \int_{\Omega_h} \frac{1}{|\mathbf{x} - \mathbf{y}|} \nabla \cdot \bar{\mathbf{m}}_h(\mathbf{y}) d\mathbf{y} + \int_{\partial\Omega_h} \frac{1}{|\mathbf{x} - \mathbf{y}|} (\bar{\mathbf{m}}_h \cdot \boldsymbol{\nu})(\mathbf{y}) d\mathcal{H}^2(\mathbf{y}).$$

Combining the above equalities, we obtain:

$$4\pi \int_{\mathbb{R}^3} |\nabla \bar{U}_h|^2 d\mathbf{x} = \mathcal{A} + 2\mathcal{B} + \mathcal{C}$$

where the terms \mathcal{A} and \mathcal{B} are estimated as in [28, Lemma 1 and 2] using the generalized Young's inequality:¹⁵

$$\begin{aligned} |\mathcal{A}| &= \left| \int_0^h \int_0^h \int_{\Omega} \int_{\Omega} \frac{\nabla \cdot \bar{\mathbf{m}}_h(x) \nabla \cdot \bar{\mathbf{m}}_h(y)}{\sqrt{|x-y|^2 + (x_3 - y_3)^2}} dx dy \right| \\ &\leq h^2 \int_{\Omega} \int_{\Omega} \frac{|\nabla \cdot \bar{\mathbf{m}}_h(x)| |\nabla \cdot \bar{\mathbf{m}}_h(y)|}{|x-y|} dx dy \\ &\leq Ch^2 \int_{\Omega} |\nabla \cdot \bar{\mathbf{m}}_h|^2 dx \leq Ch^2 |\log \varepsilon| \bar{E}_h(\bar{\mathbf{m}}_h), \end{aligned}$$

and¹⁶

$$\begin{aligned} |\mathcal{B}| &= \left| \int_{\Omega_h} \int_{\partial\Omega_h} \frac{\nabla \cdot \bar{\mathbf{m}}_h(x) (\bar{\mathbf{m}}_h \cdot \boldsymbol{\nu})(\mathbf{y})}{|\mathbf{x} - \mathbf{y}|} dx dy \right| \\ &= \left| \int_0^h \int_0^h \int_{\Omega} \int_{\partial\Omega} \frac{\nabla \cdot \bar{\mathbf{m}}_h(x) (\bar{\mathbf{m}}_h \cdot \boldsymbol{\nu})(y)}{\sqrt{|x-y|^2 + (x_3 - y_3)^2}} dx dy \right| \\ &\leq h^2 \int_{\Omega} \int_{\partial\Omega} \frac{|\nabla \cdot \bar{\mathbf{m}}_h(x)| |(\bar{\mathbf{m}}_h \cdot \boldsymbol{\nu})(y)|}{|x-y|} dx dy \\ &\leq Ch^2 \|\nabla \cdot \bar{\mathbf{m}}_h\|_{L^2(\Omega)} \|(\bar{\mathbf{m}}_h \cdot \boldsymbol{\nu})\|_{L^2(\partial\Omega)} \\ &\leq Ch^2 \varepsilon^{1/2} |\log \varepsilon| \bar{E}_h(\bar{\mathbf{m}}_h), \end{aligned}$$

while

$$\mathcal{C} = \int_{\partial\Omega_h} \int_{\partial\Omega_h} \frac{(\bar{\mathbf{m}}_h \cdot \boldsymbol{\nu})(\mathbf{x}) (\bar{\mathbf{m}}_h \cdot \boldsymbol{\nu})(\mathbf{y})}{|\mathbf{x} - \mathbf{y}|} dx dy = \mathcal{C}_1 + \mathcal{C}_2$$

with¹⁷

$$\mathcal{C}_1 = 4\pi h \int_{\Omega} \int_{\Omega} \bar{m}_{h,3}(x) \bar{m}_{h,3}(y) \Gamma_h(x-y) dx dy$$

¹⁵In particular, if $f \in L^2(\Omega)$ and $g \in L^2(\partial\Omega)$, then $\int_{\Omega} \int_{\partial\Omega} \frac{f(x)g(y)}{|x-y|} dx d\mathcal{H}^1(y) \leq C \|f\|_{L^2(\Omega)} \|g\|_{L^2(\partial\Omega)}$. Indeed, denoting for $y \in \partial\Omega$, $F(y) = \int_{\Omega} \frac{f(x)}{|x-y|} dx$, Hölder's inequality implies $F^2(y) \leq \int_{\Omega} \frac{1}{|x-y|^{3/2}} dx \int_{\Omega} \frac{f^2(x)}{|x-y|^{1/2}} dx$ and thus, $\int_{\partial\Omega} F^2(y) d\mathcal{H}^1(y) \leq c(\Omega) \|f\|_{L^2(\Omega)}^2 \sup_{x \in \Omega} \int_{\Omega} \frac{1}{|x-y|^{1/2}} d\mathcal{H}^1(y) \leq C(\Omega) \|f\|_{L^2(\Omega)}^2$. The claimed inequality follows by the Cauchy-Schwarz inequality.

¹⁶Note that the terms in the integrand of \mathcal{B} corresponding to the top and bottom boundary $\partial\Omega_h$ will cancel after integration.

¹⁷Note that the terms in the integrand of \mathcal{C} corresponding to the mixing term $\bar{m}_{h,3}(\mathbf{x})(\bar{\mathbf{m}}_h \cdot \boldsymbol{\nu})(\mathbf{y})$ as \mathbf{x} covers the top and bottom boundary $\partial\Omega_h$ will cancel after integration.

where $\Gamma_h(x) = \frac{1}{2\pi h} \left(\frac{1}{|x|} - \frac{1}{\sqrt{|x|^2+h^2}} \right)$, $x \in \mathbb{R}^2$ and

$$\mathcal{C}_2 = \int_0^h \int_0^h \int_{\partial\Omega} \int_{\partial\Omega} \frac{(\bar{m}_h \cdot \nu)(x) (\bar{m}_h \cdot \nu)(y)}{|\mathbf{x} - \mathbf{y}|} d\mathbf{x} d\mathbf{y}.$$

Estimate of \mathcal{C}_1 : The main novelty compared to the study in Kohn-Slastikov [28] is the following result, which replaces a limit calculation by a more quantitative estimate:

$$\frac{1}{\eta^2 |\log \varepsilon|} \left| \frac{\mathcal{C}_1}{4\pi h} - \int_{\Omega} \bar{m}_{h,3}^2(x) dx \right| \leq C \frac{h}{\eta^2} \left(\frac{\log \frac{\eta^2}{h}}{|\log \varepsilon|} + 1 \right) \bar{E}_h(\bar{\mathbf{m}}_h). \quad (3.6)$$

For that, since $\text{diam}(\Omega) = 1$ we can use that $\Gamma_h(x) = \frac{h}{2\pi|x|^2} \rho_h(|x|)$ for $x \in B^2 \subset \mathbb{R}^2$ where

$$\rho_h(r) = \frac{r}{(r + \sqrt{r^2 + h^2})\sqrt{r^2 + h^2}} \mathbf{1}_{\{0 \leq r \leq 1\}}(r), \quad r \geq 0.$$

First, note that $\{\rho_h\}_{h \downarrow 0}$ is a bounded sequence in $L^1(\mathbb{R}^2)$, i.e.,

$$\int_{\mathbb{R}^2} \rho_h(|x|) dx \leq \pi. \quad (3.7)$$

Moreover, for every $R \in (0, 1]$, one computes:

$$\begin{aligned} \int_{B_R(0)} \Gamma_h(x) dx &= h \int_0^R \frac{dr}{(r + \sqrt{r^2 + h^2})\sqrt{r^2 + h^2}} \\ &= \int_0^{R/h} \frac{ds}{(s + \sqrt{s^2 + 1})\sqrt{s^2 + 1}} = 1 - \left(\frac{R}{h} + \sqrt{1 + \left(\frac{R}{h}\right)^2} \right)^{-1} \leq 1. \end{aligned}$$

In particular, we get

$$0 \leq 1 - \int_{B_R(0)} \Gamma_h(x) dx \leq \frac{h}{R} \quad \text{for } R \in (0, 1]. \quad (3.8)$$

Since Ω is $C^{1,1}$, there exists $r_1 := r_1(\Omega) \in (0, 1 = \text{diam}(\Omega))$ such that every point $x \in \Omega$ with $\text{dist}(x, \partial\Omega) < r_1$ has a unique orthogonal projection on the boundary $\partial\Omega$, i.e., the crossing of two normal directions on $\partial\Omega$ in the interior of Ω happens at a distance larger than r_1 from the boundary. For $R < r_1$ we denote by

$$\Omega_R = \{x \in \Omega : \text{dist}(x, \partial\Omega) < R\} \quad (3.9)$$

the region around the boundary $\partial\Omega$ at a distance less than R . Writing $2\bar{m}_{h,3}(x)\bar{m}_{h,3}(y) = \bar{m}_{h,3}(x)^2 + \bar{m}_{h,3}(y)^2 - (\bar{m}_{h,3}(x) - \bar{m}_{h,3}(y))^2$, we obtain that:

$$\mathcal{C}_1 = -\mathcal{E}_1 + \mathcal{E}_2$$

with

$$\begin{aligned} \mathcal{E}_1 &= h^2 \int_{\Omega} \int_{\Omega} \frac{(\bar{m}_{h,3}(x) - \bar{m}_{h,3}(y))^2}{|x - y|^2} \rho_h(|x - y|) dx dy \\ &\leq h^2 \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \int_0^1 \left| \nabla [T(\bar{m}_{h,3})](x + s(y - x)) \right|^2 \rho_h(|x - y|) dx dy ds \\ &\leq h^2 \int_{\mathbb{R}^2} |\nabla [T(\bar{m}_{h,3})](x)|^2 dx \int_{\mathbb{R}^2} \rho_h(|y|) dy \\ &\stackrel{(3.7)}{\leq} Ch^2 \int_{\Omega} (|\nabla \bar{m}_{h,3}|^2 + \bar{m}_{h,3}^2) dx \leq Ch^2 |\log \varepsilon| \bar{E}_h(\bar{\mathbf{m}}_h), \end{aligned}$$

where $T : H^1(\Omega) \rightarrow H^1(\mathbb{R}^2)$ is a linear continuous extension operator, $\bar{m}_{h,3}^2 \leq 1 - |\bar{m}_h|^2$, $\eta \leq 1$ and

$$\mathcal{E}_2 = 4\pi h \int_{\Omega} \int_{\Omega} \bar{m}_{h,3}^2(x) \Gamma_h(|x-y|) dx dy.$$

It remains to estimate \mathcal{E}_2 . As $\eta \rightarrow 0$, we may assume in the regime (1.4) that $2h \leq \eta^2 \leq \frac{r_1}{2}$. By decomposing the domain $x \in \Omega = \Omega_h \cup (\Omega_{\eta^2} \setminus \Omega_h) \cup (\Omega \setminus \Omega_{\eta^2})$ (with the notation (3.9)), since $\bar{m}_{h,3}^2 \leq 1 - |\bar{m}_h|^2 \leq 1$, we compute:¹⁸

$$\begin{aligned} & \left| \frac{\mathcal{E}_2}{4\pi h} - \int_{\Omega} \bar{m}_{h,3}^2(x) dx \right| \stackrel{(3.8)}{=} \int_{\Omega} \bar{m}_{h,3}^2(x) \left(1 - \int_{\Omega} \Gamma_h(|x-y|) dy \right) dx \\ & \stackrel{(3.8)}{\leq} \int_{\Omega_h} 1 dx + \int_{\Omega_{\eta^2} \setminus \Omega_h} \frac{h}{\text{dist}(x, \partial\Omega)} dx + \frac{h}{\eta^2} \int_{\Omega \setminus \Omega_{\eta^2}} (1 - \bar{m}_h^2(x)) dx \\ & \leq C \left(h + h \int_h^{\eta^2} \frac{dr}{r} \right) + h |\log \varepsilon| \bar{E}_h(\bar{\mathbf{m}}_h) \leq Ch \left(\log \frac{\eta^2}{h} + |\log \varepsilon| \right) \bar{E}_h(\bar{\mathbf{m}}_h), \end{aligned}$$

where $C = C(\partial\Omega) > 0$ depends only on the geometry of Ω and we have used Lemma 19 below yielding $\bar{E}_h(\bar{\mathbf{m}}_h) \geq 2\pi - o(1)$ as $h \rightarrow 0$. Thus, (3.6) is proved.

Estimate of \mathcal{C}_2 : We prove that

$$\frac{1}{|\log \varepsilon|} \left| \frac{\mathcal{C}_2}{4\pi\eta^2 h} - \frac{1}{2\pi\varepsilon} \int_{\partial\Omega} (\bar{m}_h \cdot \nu)^2 d\mathcal{H}^1 \right| \ll \frac{h}{\eta^2} \bar{E}_h(\bar{\mathbf{m}}_h). \quad (3.10)$$

This estimate is similar to Lemma 4 in Kohn-Slastikov [28], but more delicate to prove in our regime. The idea here is to use a stronger estimate inspired by the work of Carbou [8]. For that, we write

$$\frac{\mathcal{C}_2}{4\pi\eta^2 h |\log \varepsilon|} = \frac{\mathcal{G}_1 + \mathcal{G}_2}{4\pi}$$

with the rescaled quantities in h :

$$\mathcal{G}_1 = \frac{h}{\eta^2 |\log \varepsilon|} \int_{\partial\Omega} \int_{\partial\Omega} (\bar{m}_h \cdot \nu)^2(x) K_h(x-y) dx dy$$

where

$$K_h(z) = \int_0^1 \int_0^1 \frac{1}{\sqrt{|z|^2 + h^2(s-t)^2}} ds dt, \quad z \in \mathbb{R}^2 \quad (3.11)$$

and

$$\begin{aligned} |\mathcal{G}_2| &= \frac{h}{\eta^2 |\log \varepsilon|} \left| \int_0^1 \int_0^1 \int_{\partial\Omega} \int_{\partial\Omega} \frac{(\bar{m}_h \cdot \nu)(x) ((\bar{m}_h \cdot \nu)(x) - (\bar{m}_h \cdot \nu)(y))}{\sqrt{|x-y|^2 + h^2(s-t)^2}} dx dy ds dt \right| \\ &\leq \frac{h}{\eta^2 |\log \varepsilon|} \int_{\partial\Omega} \int_{\partial\Omega} |(\bar{m}_h \cdot \nu)(x)| \frac{|(\bar{m}_h \cdot \nu)(x) - (\bar{m}_h \cdot \nu)(y)|}{|x-y|} dx dy \\ &\leq \frac{Ch}{\eta^2 |\log \varepsilon|} \|\bar{m}_h \cdot \nu\|_{L^2(\partial\Omega)} \|\bar{m}_h \cdot \nu\|_{\dot{H}^{1/2}(\partial\Omega)} \\ &\leq \frac{Ch}{\eta^2 |\log \varepsilon|} \sqrt{\varepsilon |\log \varepsilon| \bar{E}_h(\bar{\mathbf{m}}_h)} \|\bar{m}_h \cdot \nu\|_{\dot{H}^1(\Omega)} \leq \frac{Ch\varepsilon^{1/2}}{\eta^2} \bar{E}_h(\bar{\mathbf{m}}_h) \ll \frac{h}{\eta^2} \bar{E}_h(\bar{\mathbf{m}}_h). \end{aligned}$$

¹⁸We use that $1 - \int_{\Omega} \Gamma_h(|x-y|) dy \leq 1 - \int_{B(0, \text{dist}(x, \partial\Omega))} \Gamma_h(|z|) dz$ if $x \in \Omega_{\eta^2} \setminus \Omega_h$, and $1 - \int_{\Omega} \Gamma_h(|x-y|) dy \leq 1 - \int_{B(0, \eta^2)} \Gamma_h(|z|) dz$ if $x \in \Omega \setminus \Omega_{\eta^2}$.

Above, we used the Cauchy-Schwarz inequality and we have extended ν as a Lipschitz vector field in $\bar{\Omega}$ with $|\nu| \leq 2$ so that Lemma 19 below yields for $h > 0$ small:

$$\|(\bar{m}_h \cdot \nu)\|_{\dot{H}^1(\Omega)} \leq C(\|\bar{m}_h\|_{\dot{H}^1(\Omega)} + 1) \lesssim \sqrt{|\log \varepsilon| \bar{E}_h(\bar{\mathbf{m}}_h)} + \sqrt{\bar{E}_h(\bar{\mathbf{m}}_h)} \lesssim \sqrt{|\log \varepsilon| \bar{E}_h(\bar{\mathbf{m}}_h)}.$$

It remains to estimate \mathcal{G}_1 . In fact, as $\varepsilon = \frac{\eta^2}{h|\log h|}$, one has that

$$\begin{aligned} & \left| \frac{\mathcal{G}_1}{4\pi} - \frac{1}{2\pi\varepsilon|\log \varepsilon|} \int_{\partial\Omega} (\bar{m}_h \cdot \nu)^2 d\mathcal{H}^1 \right| \\ & \leq \frac{1}{4\pi\varepsilon|\log \varepsilon|} \int_{\partial\Omega} (\bar{m}_h \cdot \nu)^2 dx \left\| 2 - \frac{1}{|\log h|} \int_{\partial\Omega} K_h(x-y) dy \right\|_{L^\infty(x \in \partial\Omega)} \\ & \stackrel{\text{Lemma 17}}{\leq} \frac{C}{|\log h|} \bar{E}_h(\bar{\mathbf{m}}_h) = \frac{h\varepsilon}{\eta^2} \bar{E}_h(\bar{\mathbf{m}}_h) \stackrel{(1.4)}{\ll} \frac{h}{\eta^2} \bar{E}_h(\bar{\mathbf{m}}_h). \end{aligned}$$

Therefore, (3.10) follows and the proof of Lemma 16 is finished. \square

We have used above the following estimate of K_h in (3.11) that permits to track its dependance in h , which is an improvement of a result of Carbou [8, p. 1537]:

Lemma 17 *Assume that $\partial\Omega$ is a simply connected $C^{1,1}$ domain and let K_h given by (3.11). Then*

$$\sup_{x \in \partial\Omega} \left| \frac{1}{|\log h|} \int_{\partial\Omega} K_h(x-y) dy - 2 \right| \leq \frac{C}{|\log h|} \quad \text{for } h \in (0, \frac{1}{2}]. \quad (3.12)$$

Proof. Note that by symmetry, for every $z \in \mathbb{R}^2$,

$$K_h(z) = \int_0^1 \int_0^1 \frac{1}{\sqrt{|z|^2 + h^2(s-t)^2}} ds dt = 2 \int_0^1 \int_0^t \frac{1}{\sqrt{|z|^2 + h^2(s-t)^2}} ds dt.$$

By a change of variable, the inner integral becomes:

$$\int_0^t \frac{1}{\sqrt{|z|^2 + h^2(s-t)^2}} ds = \frac{1}{h} \int_0^{ht} \frac{1}{\sqrt{|z|^2 + w^2}} dw = \frac{1}{h} \operatorname{arsinh}\left(\frac{ht}{|z|}\right), \quad z \neq 0,$$

where $\operatorname{arsinh}(t) = \log(t + \sqrt{t^2 + 1})$ for $t \in \mathbb{R}$, so that integration by parts yields

$$K_h(z) = \frac{2}{h} \int_0^1 \operatorname{arsinh}\left(\frac{ht}{|z|}\right) dt = \frac{2}{h} f\left(\frac{|z|}{h}\right), \quad z \neq 0,$$

where

$$f(t) := \operatorname{arsinh} \frac{1}{t} - \frac{1}{t + \sqrt{1+t^2}} > 0, \quad t > 0$$

is a positive and decreasing function on $(0, \infty)$. Moreover, we check that:¹⁹

$$\lim_{t \rightarrow 0} \frac{f(t)}{\log \frac{1}{t}} = 1 \quad \text{and} \quad \left| t f(t) - \frac{1}{2} \right| \leq \frac{C}{t^2} \quad \text{as } t \rightarrow \infty,$$

so that

$$\left| \int_0^t f(s) ds - \frac{\log t}{2} \right| \leq C \quad \text{and} \quad \left| \frac{1}{t} \int_0^t s f(s) ds \right| \leq C \quad \text{as } t \rightarrow \infty. \quad (3.13)$$

¹⁹The second inequality follows for example by considering $g(s) = \frac{1}{s} f(\frac{1}{s})$, since $g(s) \rightarrow \frac{1}{2}$ and $g'(s) \rightarrow 0$ as $s \rightarrow 0$.

For fixed $x \in \partial\Omega$, we set $z = x - y$ and integrate over $y \in \partial\Omega$. We choose the arclength parameterization $\phi : [0, L] \rightarrow \partial\Omega$ such that $\phi(0) = x$ and ϕ is bijective (ϕ extends to a periodic $C^{1,1}$ function on \mathbb{R}) with $|\frac{d}{dt}\phi| = 1$ in $[0, L]$ (here, L is the length of $\partial\Omega$). Since ϕ is $C^{1,1}$, Taylor's expansion implies for $\alpha = \frac{1}{2}\|\frac{d^2}{dt^2}\phi\|_{L^\infty} > 0$:

$$|s|(1 - \alpha|s|) \leq |\phi(t+s) - \phi(t)| \leq |s|(1 + \alpha|s|), \quad \text{for every } t, s \in \mathbb{R}. \quad (3.14)$$

Since ϕ is continuous and injective on every interval of length less than L , then for every $\kappa \in (0, \frac{L}{2})$ there exists $\beta = \beta(\kappa) > 0$ such that

$$L \geq |\phi(t+s) - \phi(t)| \geq \beta \quad \text{for every } t \in \mathbb{R}, s \in (\kappa, L - \kappa). \quad (3.15)$$

Fix some small κ (more precisely, assume $\kappa < \min\{\frac{L}{100}, \frac{1}{2\alpha}\}$ and $0 < 2\kappa\alpha(1 - \frac{\kappa\alpha}{2}) < \frac{1}{2}$). Then

$$\int_{\partial\Omega} K_h(x-y)dy = \frac{2}{h} \int_{-\kappa}^{\kappa} f\left(\frac{|\phi(s)-x|}{h}\right)ds + \frac{2}{h} \int_{\kappa}^{L-\kappa} f\left(\frac{|\phi(s)-x|}{h}\right)ds =: I_1(h) + I_2(h).$$

As f is decreasing, we can estimate this from above and below using estimates (3.14) and (3.15). In particular, as $\phi(0) = x$,

$$\frac{4}{h} \int_0^{\kappa} f\left(\frac{(1+\alpha s)s}{h}\right)ds \leq I_1(h) \leq \frac{4}{h} \int_0^{\kappa} f\left(\frac{(1-\alpha s)s}{h}\right)ds$$

and similarly,

$$\frac{2(L-2\kappa)}{L} \left(\frac{L}{h} f\left(\frac{L}{h}\right)\right) = \frac{2}{h} \int_{\kappa}^{L-\kappa} f\left(\frac{L}{h}\right)ds \leq I_2(h) \leq \frac{2}{h} \int_{\kappa}^{L-\kappa} f\left(\frac{\beta}{h}\right)ds = \frac{2(L-2\kappa)}{\beta} \left(\frac{\beta}{h} f\left(\frac{\beta}{h}\right)\right).$$

As $tf(t) \rightarrow \frac{1}{2}$ as $t \rightarrow \infty$, we obtain that

$$0 \leq I_2(h) \leq C \quad \text{as } h \rightarrow 0.$$

It remains to prove that $I_1(h) \sim 2|\log h|$ as $h \rightarrow 0$. For that, note that by substitution,

$$\int_0^{\kappa} f\left(\frac{s(1 \pm \alpha s)}{h}\right)ds = h \int_0^{\kappa(1 \pm \alpha\kappa)/h} \frac{f(t)}{\sqrt{1 \pm 4ht\alpha}} dt.$$

Lower bound for $I_1(h)$. Observe that $\frac{1}{\sqrt{1+s}} \geq 1 - \frac{s}{2}$ for every $s > 0$ (in particular for $s = 4ht\alpha$). It follows that

$$I_1(h) \geq 4 \int_0^{\kappa(1+\alpha\kappa)/h} f(t)dt - 8h\alpha \int_0^{\kappa(1+\alpha\kappa)/h} tf(t)dt \stackrel{(3.13)}{\geq} 2|\log h| - C.$$

Upper bound for $I_1(h)$. We similarly use $\frac{1}{\sqrt{1-s}} \leq 1 + 2s$ for every $s \in [0, \frac{1}{2}]$ (in particular for $s = 4ht\alpha \in [0, 2\kappa\alpha(1 - \kappa\alpha)] \subset [0, \frac{1}{2}]$ by our choice of some small fixed κ and $h < 1/2$). It follows that

$$I_1(h) \leq 4 \int_0^{\kappa(1-\alpha\kappa)/h} f(t)dt + 32h\alpha \int_0^{\kappa(1-\alpha\kappa)/h} tf(t)dt \stackrel{(3.13)}{\leq} 2|\log h| + C.$$

Thus, (3.12) follows. \square

Proof of Theorem 1. We may assume $\sup_h E_h(\mathbf{m}_h) \leq K < \infty$. From (3.2) of Lemma 15, we see that

$$E_h(\mathbf{m}_h) \geq \bar{E}_h(\bar{\mathbf{m}}_h) - \left(\bar{E}_h(\bar{\mathbf{m}}_h) + \sqrt{\frac{K}{|\log \varepsilon|}} \right) \lambda(h),$$

where $\lambda(h)$ is given in (3.3). From (1.5) we see that $\lambda(h) = o(1)$ as $\varepsilon \rightarrow 0$, and we can conclude that we must have

$$\limsup_{h \rightarrow 0} \bar{E}_h(\bar{\mathbf{m}}_h) \leq K,$$

so we obtain the bound

$$E_h(\mathbf{m}_h) \geq \bar{E}_h(\bar{\mathbf{m}}_h) - \lambda(h) \left(K + 1 + 2\sqrt{\frac{K}{|\log \varepsilon|}} \right) = \bar{E}_h(\bar{\mathbf{m}}_h) - o(1) \quad \text{as } h \rightarrow 0.$$

Furthermore, in the regime (1.6),

$$\lambda(h) = \frac{\log |\log h|}{\varepsilon |\log \varepsilon| |\log h|} \ll \frac{1}{|\log \varepsilon|},$$

and hence we obtain

$$E_h(\mathbf{m}_h) \geq \bar{E}_h(\bar{\mathbf{m}}_h) - o\left(\frac{1}{|\log \varepsilon|}\right) \quad \text{as } h \rightarrow 0.$$

If the magnetizations \mathbf{m}_h are invariant in x_3 -direction (when \mathbf{m}_h coincides with the average $\bar{\mathbf{m}}_h$), then clearly

$$\frac{1}{h} \int_{\Omega_h} |\nabla \mathbf{m}_h|^2 dx = \int_{\Omega} |\nabla \bar{\mathbf{m}}_h|^2 dx,$$

and since $U_h = \bar{U}_h$ in \mathbb{R}^3 , the stray field term in $E_h(\mathbf{m}_h)$ and the penalty terms in $\bar{E}_h(\bar{\mathbf{m}}_h)$ are close to each other by (3.5), so the asymptotic inequalities become asymptotic equalities as claimed. \square

4 Proof of Theorem 9

In this section we prove Theorem 9 as a consequence of the estimates in Theorem 1 and the results we obtained in [22] for a functional related to \bar{E}_h in (1.9). More precisely, in [22], we studied the following energy functional for $u \in H^1(\Omega; \mathbb{R}^2)$:

$$E_{\varepsilon, \eta}(u) = \int_{\Omega} |\nabla u|^2 dx + \frac{1}{\eta^2} \int_{\Omega} (1 - |u|^2)^2 dx + \frac{1}{2\pi\varepsilon} \int_{\partial\Omega} (u \cdot \nu)^2 d\mathcal{H}^1, \quad \varepsilon, \eta > 0. \quad (4.1)$$

In our context $\varepsilon = \varepsilon(h)$ and $\eta = \eta(h)$, note that for $u \in H^1(\Omega; \mathbb{R}^2)$ with $|u| \leq 1$ in Ω ,

$$\bar{E}_h(u) \geq \frac{1}{|\log \varepsilon|} E_{\varepsilon, \eta}(u) \quad (4.2)$$

because $(1 - |u|^2)^2 \leq (1 - |u|^2)$ as $|u| \leq 1$. We always use for $u \in H^1(\Omega; \mathbb{R}^2)$ the identification $u \equiv (u, 0) \in H^1(\Omega; \mathbb{R}^3)$ as \bar{E}_h is defined for \bar{B}^3 -valued maps. Moreover, if $u \in H^1(\Omega; \mathbb{S}^1)$, then (4.2) becomes equality:

$$\bar{E}_h(u) = \frac{1}{|\log \varepsilon|} E_{\varepsilon, \eta}(u). \quad (4.3)$$

We recall here the Γ -convergence result that we established in our previous paper [22, Theorems 1.2, 1.4 and 1.5] that is essential in the sequel:

Theorem 18 ([22]) Let $\Omega \subset \mathbb{R}^2$ be a bounded, simply connected $C^{1,1}$ domain, $\varepsilon \rightarrow 0$ and $\eta = \eta(\varepsilon) \rightarrow 0$ be sequences / families satisfying $|\log \varepsilon| \ll |\log \eta|$. Assume $u_\varepsilon \in H^1(\Omega; \mathbb{R}^2)$ satisfy

$$\limsup_{\varepsilon \rightarrow 0} \frac{1}{|\log \varepsilon|} E_{\varepsilon, \eta}(u_\varepsilon) < \infty.$$

- i) **Compactness of global Jacobians and $L^p(\partial\Omega)$ -compactness of $u_\varepsilon|_{\partial\Omega}$.** For a subsequence, the global Jacobians $\mathcal{J}(u_\varepsilon)$ converge to a measure J on the closure $\overline{\Omega}$ in the sense of (1.19), J is supported on $\partial\Omega$ and has the form (1.20) for N distinct boundary vortices $a_j \in \partial\Omega$ carrying the non-zero multiplicities $d_j \in \mathbb{Z} \setminus \{0\}$. Moreover, for a subsequence, the trace $u_\varepsilon|_{\partial\Omega}$ converges as $\varepsilon \rightarrow 0$ in $L^p(\partial\Omega)$ (for every $p \in [1, \infty)$) to $e^{i\phi} \in BV(\partial\Omega; \mathbb{S}^1)$ for a lifting ϕ of the tangent field $\pm\tau$ on $\partial\Omega$ determined (up to a constant in $\pi\mathbb{Z}$) by $\partial_\tau\phi = -J$ on $\partial\Omega$.
- ii) **Energy lower bound at the first order.** If (u_ε) satisfies the convergence assumption on the Jacobians as the sequence / family $\varepsilon \rightarrow 0$ as in i), then²⁰

$$\liminf_{\varepsilon \rightarrow 0} \frac{1}{|\log \varepsilon|} E_{\varepsilon, \eta}(u_\varepsilon) \geq \pi \sum_{j=1}^N |d_j| = |J + \varkappa \mathcal{H}^1 \llcorner \partial\Omega|(\partial\Omega). \quad (4.4)$$

If we additionally assume the following sharper bound:

$$\limsup_{\varepsilon \rightarrow 0} (E_{\varepsilon, \eta}(u_\varepsilon) - \pi \sum_{j=1}^N |d_j| |\log \varepsilon|) < \infty, \quad (4.5)$$

then the following results hold:

- iii) **Single multiplicity and second order lower bound.** The multiplicities satisfy $d_j = \pm 1$ for $1 \leq j \leq N$, so $\sum_{j=1}^N |d_j| = N$ and there holds the finer energy bound

$$\liminf_{\varepsilon \rightarrow 0} (E_{\varepsilon, \eta}(u_\varepsilon) - \pi N |\log \varepsilon|) \geq W_\Omega(\{(a_j, d_j)\}) + \gamma_0 N, \quad (4.6)$$

with $\gamma_0 = \pi \log \frac{e}{4\pi}$ a universal constant and W_Ω the renormalised energy defined in (1.17).

- iv) **Penalty bound.** The penalty terms are of order $O(1)$, i.e.,

$$\limsup_{\varepsilon \rightarrow 0} \left(\frac{1}{\eta^2} \int_\Omega (1 - |u_\varepsilon|^2)^2 dx + \frac{1}{2\pi\varepsilon} \int_{\partial\Omega} (u_\varepsilon \cdot \nu)^2 d\mathcal{H}^1 \right) < \infty. \quad (4.7)$$

- v) **Local energy lower bound.** There are $\rho_0 > 0$, $\varepsilon_0 > 0$ and $C > 0$ such that the energy of u_ε near the singularities satisfies for all the $\varepsilon < \varepsilon_0$ in the sequence / family and $\rho < \rho_0$:

$$\left(\int_{\Omega \cap \bigcup_{j=1}^N B_\rho(a_j)} |\nabla u_\varepsilon|^2 dx - \pi N \log \frac{\rho}{\varepsilon} \right) > -C. \quad (4.8)$$

- vi) **$L^p(\Omega)$ -compactness of maps u_ε .** For any $q \in [1, 2)$, the sequence / family $(u_\varepsilon)_\varepsilon$ is uniformly bounded in $W^{1,q}(\Omega; \mathbb{R}^2)$. Moreover, for a subsequence, u_ε converges as $\varepsilon \rightarrow 0$ strongly in $L^p(\Omega; \mathbb{R}^2)$ for any $p \in [1, \infty)$ to $e^{i\hat{\phi}}$, where $\hat{\phi} \in W^{1,q}(\Omega)$ is an extension (not necessarily harmonic) to Ω of the lifting $\phi \in BV(\partial\Omega)$ determined in point i).

²⁰Recall that $J + \varkappa \mathcal{H}^1 \llcorner \partial\Omega = \pi \sum_{j=1}^N d_j \delta_{a_j}$.

Finally, we have a matching **upper bound construction**:

vii) Given any N distinct points $a_j \in \partial\Omega$ with their multiplicity $d_j \in \mathbb{Z} \setminus \{0\}$ satisfying the constraint $\sum_{j=1}^N d_j = 2$, we can construct for every $\varepsilon \in (0, \frac{1}{2})$, $u_\varepsilon \in H^1(\Omega; \mathbb{S}^1)$ such that the global Jacobians $\mathcal{J}(u_\varepsilon)$ converge to $J = -\varkappa \mathcal{H}^1 \llcorner \partial\Omega + \pi \sum_{j=1}^N d_j \delta_{a_j}$ as in (1.19). Furthermore, u_ε converge strongly to a canonical harmonic map m_* associated to $\{(a_j, d_j)\}$ in $L^p(\Omega)$ and $L^p(\partial\Omega)$ for all $p \in [1, \infty)$. and the energies satisfy

$$\lim_{\varepsilon \rightarrow 0} \frac{1}{|\log \varepsilon|} E_{\varepsilon, \eta}(u_\varepsilon) = \pi \sum_{j=1}^N |d_j|.$$

If furthermore $|d_j| = 1$ for all $j = 1, \dots, N$, then u_ε can be chosen such that

$$\lim_{\varepsilon \rightarrow 0} (E_{\varepsilon, \eta}(u_\varepsilon) - \pi N |\log \varepsilon|) = W_\Omega(\{(a_j, d_j)\}) + N\gamma_0.$$

Using Theorem 18, we first show a uniform lower bound for \bar{E}_h that is required in the proof of Lemma 15 (which we used for proving Theorem 1). The assumption that Ω is simply connected (or at least not topologically an annulus, compare Remark 14) is very important. As the result is only about \bar{E}_h , our reasoning to establish Theorem 1 is not circular.

Lemma 19 *Let $\mathbf{m}_h \in H^1(\Omega; \mathbb{R}^3)$ with $|\mathbf{m}_h| \leq 1$ in Ω . Then*

$$\liminf_{h \rightarrow 0} \bar{E}_h(\mathbf{m}_h) \geq 2\pi.$$

Proof. We denote $\mathbf{m}_h = (m_h, m_{3,h})$. As $\bar{E}_h(\mathbf{m}_h) \geq \bar{E}_h(m_h, 0)$, we may assume $\mathbf{m}_h = (m_h, 0)$ and $\limsup_{h \rightarrow 0} \bar{E}_h(\mathbf{m}_h) \leq C$. Writing $\varepsilon = \varepsilon(h)$, $\eta = \eta(h)$ and $u_\varepsilon := m_h \in H^1(\Omega; \mathbb{R}^2)$, we have from (4.2) that $\bar{E}_h(\mathbf{m}_h) \geq \frac{1}{|\log \varepsilon|} E_{\varepsilon, \eta}(u_\varepsilon)$. We furthermore restrict ourselves to a subsequence $\varepsilon \rightarrow 0$ such that $E_{\varepsilon, \eta}(u_\varepsilon)/|\log \varepsilon| \rightarrow \liminf_{\varepsilon \rightarrow 0} E_{\varepsilon, \eta}(u_\varepsilon)/|\log \varepsilon|$. Hence we can apply Theorem 18 and obtain for a further subsequence that the global Jacobians $\mathcal{J}(u_\varepsilon)$ converge to a measure J supported on the boundary $\partial\Omega$ of the form $J = -\varkappa \mathcal{H}^1 \llcorner \partial\Omega + \pi \sum_{j=1}^N d_j \delta_{a_j}$, $a_j \in \partial\Omega$, $d_j \in \mathbb{Z} \setminus \{0\}$, $\sum_{j=1}^N d_j = 2$; moreover, Theorem 18 yields

$$\liminf_{\varepsilon \rightarrow 0} \frac{1}{|\log \varepsilon|} E_{\varepsilon, \eta}(u_\varepsilon) \geq \pi \sum_{j=1}^N |d_j| \geq \pi \left| \sum_{j=1}^N d_j \right| = 2\pi,$$

which proves the claim. \square

We are now in the position to prove Theorem 9.

Proof of Theorem 9. We start by proving the compactness statement in (i). For that, we assume $\mathbf{m}_h : \Omega_h \rightarrow \mathbb{S}^2$ is a sequence of magnetizations such that $\sup_h E_h(\mathbf{m}_h) \leq C$ and we set $\bar{\mathbf{m}}_h = (\bar{m}_h, \bar{m}_{h,3})$ the average magnetization in (1.7). By Theorem 1 and (4.2), we have

$$C \geq \limsup_{h \rightarrow 0} \bar{E}_h(\bar{\mathbf{m}}_h) \geq \limsup_{\varepsilon \rightarrow 0} \frac{1}{|\log \varepsilon|} E_{\varepsilon, \eta}(\bar{m}_h).$$

Note that (1.4) implies $|\log \varepsilon| \ll \frac{1}{\varepsilon} \ll |\log \eta|$. Thus, the compactness statement of Theorem 18 applies to $u_\varepsilon := \bar{m}_h$ yielding the relative compactness of $\mathcal{J}(\bar{m}_h)$ as well as the $L^p(\partial\Omega)$ -relative compactness of the traces $\bar{m}_h|_{\partial\Omega}$ for every $p \in [1, \infty)$; as every limit of this sequence takes values in \mathbb{S}^1 on $\partial\Omega$ and $\bar{m}_{h,3}^2 \leq 1 - |\bar{m}_h|^2$, it yields $\bar{m}_{h,3} \rightarrow 0$ in $L^2(\partial\Omega)$. As $|\bar{m}_{h,3}| \leq 1$, we conclude for a subsequence, $\bar{m}_{h,3} \rightarrow 0$ in $L^p(\partial\Omega)$ for every $p \in [1, \infty)$ which proves (i).

From (4.4) and Theorem 1, we establish (ii):

$$\liminf_{h \rightarrow 0} E_h(\mathbf{m}_h) \geq \liminf_{h \rightarrow 0} \bar{E}_h(\bar{\mathbf{m}}_h) \geq \liminf_{\varepsilon \rightarrow 0} \frac{1}{|\log \varepsilon|} E_{\varepsilon, \eta}(\bar{m}_h) \geq \pi \sum_{j=1}^N |d_j|.$$

Moreover, in the regime (1.6), the assumption $\limsup_{h \rightarrow 0} |\log \varepsilon| (E_h(\mathbf{m}_h) - \pi \sum_{j=1}^N |d_j|) \leq C$, together with the improved estimate (1.10) of Theorem 1 yields (4.5); thus, by Theorem 18, we have $|d_j| = 1$ for every $1 \leq j \leq N$ and together with (4.6), the statement (iii) also follows.

To prove (iv), note that (4.8) together with Jensen's inequality imply for $\varepsilon < \varepsilon_0$ and $\rho < \rho_0$:

$$\frac{1}{h} \int_{(\Omega \cap \bigcup_{j=1}^N B_\rho(a_j)) \times (0, h)} |\nabla \mathbf{m}_h|^2 dx \geq \int_{\Omega \cap \bigcup_{j=1}^N B_\rho(a_j)} |\nabla \bar{m}_h|^2 dx \geq \pi N \log \frac{\rho}{\varepsilon} - C.$$

Combined with the upper bound for the energy

$$\frac{1}{h} \int_{\Omega_h} |\nabla \mathbf{m}_h|^2 dx \leq |\log \varepsilon| E_h(\mathbf{m}_h) \leq \pi N |\log \varepsilon| + C,$$

we obtain for every $\rho < \rho_0$:

$$\frac{1}{h} \int_{(\Omega \setminus \bigcup_{j=1}^N B_\rho(a_j)) \times (0, h)} |\nabla \mathbf{m}_h|^2 dx \leq C(1 + \log \frac{1}{\rho}).$$

We now use the argument of Struwe [41] to obtain L^q bounds for $\nabla \mathbf{m}_h$ for every $q \in [1, 2)$ (see also [22, Lemma 4.17]). Set $\omega_s = (\Omega \setminus \bigcup_{j=1}^N B_s(a_j)) \times (0, h)$. Then for all s , $|\omega_s \setminus \omega_{2s}| \leq Cs^2h$. With $s_k = 2^{1-k}\rho_0$, $k = 1, 2, \dots$, we find, adjusting the constant, that

$$\int_{\omega_{s_k}} |\nabla \mathbf{m}_h|^2 dx \leq Chk. \quad (4.9)$$

We compute using Hölder's inequality and (4.9):

$$\begin{aligned} \int_{\Omega_h} |\nabla \mathbf{m}_h|^q dx &= \int_{\omega_{s_1}} |\nabla \mathbf{m}_h|^q dx + \sum_{k=1}^{\infty} \int_{\omega_{s_{k+1}} \setminus \omega_{s_k}} |\nabla \mathbf{m}_h|^q dx \\ &\leq Ch + \sum_{k=1}^{\infty} \left(\int_{\omega_{s_{k+1}} \setminus \omega_{s_k}} |\nabla \mathbf{m}_h|^2 dx \right)^{\frac{q}{2}} |\omega_{s_{k+1}} \setminus \omega_{s_k}|^{1-\frac{q}{2}} \\ &\leq Ch + C \sum_{k=1}^{\infty} (kh)^{\frac{q}{2}} (2^{-2k}h)^{1-\frac{q}{2}} \leq Ch + Ch \sum_{k=1}^{\infty} k^{\frac{q}{2}} 2^{-k(2-q)} \leq C(q)h, \end{aligned}$$

where the above infinite sum is convergent since we assumed $1 \leq q < 2$. By rescaling $\tilde{\mathbf{m}}_h(x, x_3) = \mathbf{m}_h(x, hx_3)$ with $\tilde{\mathbf{m}}_h = (\tilde{m}_h, \tilde{m}_{h,3}) : \Omega_1 \rightarrow \mathbb{S}^2$, we have for $h < 1$ and $1 \leq q < 2$:

$$\|\nabla \tilde{\mathbf{m}}_h\|_{L^q(\Omega_1)}^q \leq \int_{\Omega_1} |\nabla \tilde{\mathbf{m}}_h|^q + \frac{|\partial_{x_3} \tilde{\mathbf{m}}_h|^q}{h^q} dx = \frac{1}{h} \int_{\Omega_h} |\nabla \mathbf{m}_h|^q dx \leq C(q). \quad (4.10)$$

By compact embedding of $W^{1,q}(\Omega_1) \subset L^2(\Omega_1)$ for $q \in (1, 2)$, we obtain after extraction the strong convergence $\tilde{\mathbf{m}}_h \rightarrow \tilde{\mathbf{m}}$ in $L^2(\Omega_1)$ to a limit $\tilde{\mathbf{m}} \in W^{1,q}(\Omega_1)$. For a further subsequence, we can assume pointwise convergence almost everywhere, so we have $|\tilde{\mathbf{m}}| = 1$ almost everywhere as $|\tilde{\mathbf{m}}_h| = 1$. Moreover, we deduce the strong convergence $\tilde{\mathbf{m}}_h \rightarrow \tilde{\mathbf{m}}$ in $L^p(\Omega_1)$ for all $1 \leq p < \infty$. By (4.10), we also get $\|\partial_{x_3} \tilde{\mathbf{m}}_h\|_{L^q} \rightarrow 0$ for every $q \in [1, 2)$, so $\partial_{x_3} \tilde{\mathbf{m}} = 0$ in Ω_1 . Hence $\tilde{\mathbf{m}}$ is equal to its x_3 -average, i.e., $\tilde{\mathbf{m}} = \bar{\mathbf{m}}(x) : \Omega \rightarrow \mathbb{S}^2$ (which obviously is the $L^p(\Omega)$ -limit of the x_3 -average of $\tilde{\mathbf{m}}_h$ since $\tilde{\mathbf{m}}_h \rightarrow \tilde{\mathbf{m}}$ in $L^p(\Omega_1)$ for all $1 \leq p < \infty$). Note that the x_3 -average of $\tilde{\mathbf{m}}_h$ coincides with $\bar{\mathbf{m}}_h$ in Ω , so the $L^p(\Omega)$ -limit of $\bar{\mathbf{m}}_h$ is $\tilde{\mathbf{m}}$. By point *vi*) in Theorem 18 on $L^p(\Omega)$ -limiting behaviour of $u_\varepsilon = \bar{m}_h$, we then deduce that the limit $\tilde{\mathbf{m}}$ has the form $(\tilde{m}, 0)$ with $\tilde{m} : \Omega \rightarrow \mathbb{S}^1$. Moreover, Jensen's inequality applied in (4.10) yields $\nabla \bar{m}_h$ is bounded²¹ in $L^q(\Omega)$ for every $q \in [1, 2)$. Then the strong $L^3(\Omega)$ -convergence of \bar{m}_h and weak $L^{3/2}(\Omega)$ -convergence of $\nabla \bar{m}_h$ imply that

$$-\langle \mathcal{J}(\bar{m}_h), \zeta \rangle = \int_{\Omega} \bar{m}_h \times \nabla \bar{m}_h \cdot \nabla^\perp \zeta \, dx \rightarrow \int_{\Omega} \tilde{m} \times \nabla \tilde{m} \cdot \nabla^\perp \zeta \, dx = -\langle \mathcal{J}(\tilde{m}), \zeta \rangle,$$

for every $\zeta \in W^{1,\infty}(\Omega)$. By point *i*), we conclude that $\mathcal{J}(\tilde{m}) = J$ as claimed. \square

We now show the corresponding upper bound:

Proof of Theorem 10. For $j = 1, \dots, N$ let $a_j \in \partial\Omega$ be distinct points and $d_j \in \mathbb{Z} \setminus \{0\}$ such that $\sum_{j=1}^N d_j = 2$. Let $u_\varepsilon : \Omega \rightarrow \mathbb{S}^1$ be chosen as in part *vii*) of Theorem 18. Set $\mathbf{M}_h(x, x_3) = (u_\varepsilon(x), 0) \in \mathbb{S}^1 \times \{0\}$ for $0 < x_3 < h$ and $x \in \Omega$. Clearly \mathbf{M}_h satisfies *i*). As \mathbf{M}_h is x_3 -independent, then \mathbf{M}_h coincides with its average $\bar{\mathbf{M}}_h$ in (1.7) with the in-plane components $M_h = u_\varepsilon$ in Ω . As $|u_\varepsilon| = 1$ in Ω and $\bar{\mathbf{M}}_h$ is in-plane in Ω , (4.3) yields $\bar{E}_h(\bar{\mathbf{M}}_h) = \frac{1}{|\log \varepsilon|} E_{\varepsilon, \eta}(u_\varepsilon)$. By the choice of u_ε , $\mathcal{J}(M_h) = \mathcal{J}(u_\varepsilon) \rightarrow J$ in the sense of (1.19) and we also have the desired convergence of M_h to m_* . By Theorem 1 and the x_3 -independence of \mathbf{M}_h , the choice of u_ε implies in the regime (1.4):

$$E_h(\mathbf{M}_h) = \bar{E}_h(\bar{\mathbf{M}}_h) + o(1) = \frac{1}{|\log \varepsilon|} E_{\varepsilon, \eta}(u_\varepsilon) + o(1) \rightarrow \pi \sum_{j=1}^N |d_j| \quad \text{as } h \rightarrow 0.$$

This is *ii*). To show *iii*), we just note that if additionally $|d_j| = 1$ for all j , the above argument yields in the regime (1.6) via part *vii*) in Theorem 18:

$$\lim_{h \rightarrow 0} |\log \varepsilon| (E_h(\mathbf{M}_h) - \pi N) = \lim_{h \rightarrow 0} |\log \varepsilon| \left(\bar{E}_h(\bar{\mathbf{M}}_h) + o\left(\frac{1}{|\log \varepsilon|}\right) - \pi N \right) = W_\Omega(\{(a_j, d_j)\}) + N\gamma_0.$$

\square

Finally, we prove Corollary 11 for the behavior of minimizers:

Proof of Corollary 11. The existence of minimizers of (1.2) is a consequence of the direct method in calculus of variations and of the continuity of the linear operator $\mathbf{m}_h \in L^2(\Omega_h) \mapsto \nabla U_h \in L^2(\mathbb{R}^3)$ given in (1.3). Let $(\mathbf{m}_h)_{h \rightarrow 0}$ be a sequence of minimizers of E_h and the regime (1.4) hold. Using Theorem 10 for $d_1 = d_2 = 1$ and $\hat{a}_1 \neq \hat{a}_2$ minimizers of $W_\Omega(\{(a_1, 1), (a_2, 1)\})$ in (1.18), there exists a sequence $(\bar{\mathbf{M}}_h)_{h \rightarrow 0}$ with $\lim_{h \rightarrow 0} E_h(\bar{\mathbf{M}}_h) = 2\pi$. As $E_h(\mathbf{m}_h) \leq E_h(\bar{\mathbf{M}}_h)$ by minimality, we obtain $\limsup_{h \rightarrow 0} E_h(\mathbf{m}_h) \leq 2\pi$. From Theorem 9 *i*) and *ii*), up to a subsequence, the global Jacobians $\mathcal{J}(\bar{m}_h)$ of the in-plane averages \bar{m}_h satisfy $\mathcal{J}(\bar{m}_h) \rightarrow J = -\varkappa \mathcal{H}^1 \llcorner \partial\Omega + \pi \sum_{j=1}^N d_j \delta_{a_j}$ in the sense of (1.19) for some distinct points $a_j \in \partial\Omega$ with multiplicities $d_j \in \mathbb{Z} \setminus \{0\}$ such that $\sum_{j=1}^N d_j = 2$,

²¹This is also a consequence of point *vi*) in Theorem 18.

and $\liminf_{h \rightarrow 0} E_h(\mathbf{m}_h) \geq \pi \sum_{j=1}^N |d_j|$. Thus, $\sum_{j=1}^N d_j = 2 \geq \sum_{j=1}^N |d_j|$ yielding either ($N = 1$ and $d_1 = 2$), or ($N = 2$ and $d_1 = d_2 = 1$). In both cases we have $\mathcal{J}(\bar{m}_h) \rightarrow J = -\varkappa \mathcal{H}^1 \llcorner \partial\Omega + \pi(\delta_{a_1^*} + \delta_{a_2^*})$ for some $a_1^*, a_2^* \in \partial\Omega$ (not necessarily distinct) and $\lim_{h \rightarrow 0} E_h(\mathbf{m}_h) = 2\pi$ as claimed.

In the regime (1.6), we similarly deduce using (iii) of Theorem 10 that

$$\limsup_{h \rightarrow 0} (|\log \varepsilon|(E_h(\mathbf{m}_h) - 2\pi)) \leq W_\Omega(\{(\hat{a}_1, 1), (\hat{a}_2, 1)\}) + 2\gamma_0.$$

From (iii) of Theorem 9 we obtain that $N = 2$, $d_1 = d_2 = 1$ and $a_1 = a_1^* \neq a_2^* = a_2$ and $W_\Omega(\{(a_1^*, 1), (a_2^*, 1)\}) \leq W_\Omega(\{(\hat{a}_1, 1), (\hat{a}_2, 1)\})$, so the pair (a_1^*, a_2^*) minimizes the renormalized energy in (1.18) and $|\log \varepsilon|(E_h(\mathbf{m}_h) - 2\pi) \rightarrow W_\Omega(\{(\hat{a}_1, 1), (\hat{a}_2, 1)\}) + 2\gamma_0$ as $h \rightarrow 0$. The convergence of (\mathbf{m}_h) follows from Theorem 9 (iv). The identification of the limit with $(m_*, 0)$ where m_* is one of the two canonical harmonic maps associated to $\{(a_1^*, 1), (a_2^*, 1)\}$ is a consequence of our argument in [22, Corollary 1.6]. Indeed, by (1.10) and (1.11),

$$E_{\varepsilon, \eta}(\bar{m}_h) - 2\pi |\log \varepsilon| \leq |\log \varepsilon|(\bar{E}_h(\bar{\mathbf{m}}_h) - 2\pi) \leq W_\Omega(\{(a_1^*, 1), (a_2^*, 1)\}) + 2\gamma_0 + o(1),$$

we can deduce that (90) in the proof of Corollary 1.6 of [22] holds; thus, the rest of that proof (the argument only requires the almost minimality condition (90), not actual minimality) then shows that the limit of $(\bar{m}_h)_{h \rightarrow 0}$ must be m_* . \square

5 Canonical harmonic maps and the renormalized energy

In this section we compute the renormalized energy defined in (1.17) and prove the existence of minimisers in the situation of two boundary vortices of multiplicity 1. First, we compute the renormalized energy in terms of a solution to a Neumann problem (see (5.2)) which is similar to the method of Bethuel-Brezis-Hélein [5] (compare also [30, Proposition 7.1]). Second, we prove Theorem 6, i.e., an exact formula in the situation of a disk domain that we transfer afterwards to a general bounded $C^{1,1}$ simply connected domain via a conformal map.

We start by proving the following formula of the renormalized energy proving in particular that the limit in (1.17) exists:

Proposition 20 *Let $\Omega \subset \mathbb{R}^2$ be a simply connected $C^{1,1}$ domain with outer unit normal field ν and let \varkappa denote the curvature of the boundary $\partial\Omega$. We consider $N \geq 2$ distinct points $a_j \in \partial\Omega$ carrying the multiplicities $d_j \in \{\pm 1\}$ with $\sum_{j=1}^N d_j = 2$. Then the limit in (1.17) exists and the renormalized energy satisfies*

$$W_\Omega(\{(a_j, d_j)\}) = -\pi \sum_{k \neq j} d_k d_j \log |a_k - a_j| - \int_{\partial\Omega} \psi \varkappa d\mathcal{H}^1 + \pi \sum_{j=1}^N d_j R(a_j), \quad (5.1)$$

where ψ denotes the unique (up to an additive constant) solution in $W^{1,q}(\Omega)$ for every $q \in [1, 2)$ of the inhomogeneous Neumann problem

$$\begin{cases} \Delta \psi &= 0 & \text{in } \Omega \\ \frac{\partial \psi}{\partial \nu} &= -\varkappa + \pi \sum_{j=1}^N d_j \delta_{a_j} & \text{on } \partial\Omega, \end{cases} \quad (5.2)$$

and R is the harmonic function given by $R(z) = \psi(z) + \sum_{j=1}^N d_j \log |z - a_j|$. It satisfies $R \in C^{0,\alpha}(\bar{\Omega})$ for every $\alpha \in (0, 1)$ and $R \in W^{s,p}(\Omega)$ for every $p \in [1, \infty)$ and $s \in [1, 1 + \frac{1}{p})$.

Remark 21 While ψ is determined only up to an additive constant (idem for R), the above formula (5.1) is independent of that constant due to the Gauss-Bonnet formula and the constraint $\sum d_j = 2$.

Remark 22 In Definition 5, we asked for $e^{i\phi} \cdot \nu = 0$. We can replace the unit vector field ν (of degree 1) that we want $e^{i\phi}$ to be perpendicular to by a more general unit vector field V , compare [22, Remark 1.2] and [30, Proposition 7.1].

Proof. First, we show that (5.2) admits a unique solution (up to an additive constant) in $W^{1,q}(\Omega)$ for every $q \in [1, 2)$. Indeed, the existence result is a direct consequence of the fact that any conjugate harmonic function ψ of ϕ_* introduced in Definition 2 satisfies (5.2). Such a function ϕ_* exists since $-\int_{\partial\Omega} \varkappa d\mathcal{H}^1 + \pi \sum_{j=1}^N d_j = 0$ (by the Gauss-Bonnet theorem and the constraint $\sum_{j=1}^N d_j = 2$); moreover, $\phi_* \in W^{s+\frac{1}{p}, p}(\Omega)$ for every $s \in (0, 1)$ and $p \in (1, \frac{1}{s})$ (because of the trace theorem and the fact that $\phi_*|_{\partial\Omega} \in BV \cap L^\infty(\partial\Omega) \subset W^{s,p}(\Omega)$ for every $s \in (0, 1)$ and $p \in [1, \frac{1}{s})$ by Sobolev embedding), in particular, $\phi_* \in W^{1,q}(\Omega)$ for every $q \in [1, 2)$; thus, a conjugate harmonic function ψ of ϕ_* (i.e., $\phi_* + i\psi$ is holomorphic in Ω) satisfies (5.2) (via the Cauchy-Riemann equations) and $\psi \in W^{1,q}(\Omega)$ for every $q \in [1, 2)$. The uniqueness (up to a constant) of $\psi \in W^{1,q}(\Omega)$ for $q \in [1, 2)$ is proved as follows²²: if $\tilde{\psi} \in W^{1,q}$ is another solution of (5.2), then the difference $\hat{\psi} = \psi - \tilde{\psi} \in W^{1,q}(\Omega)$ for $q \in [1, 2)$ satisfies $\int_{\Omega} \nabla \hat{\psi} \cdot \nabla \zeta dx = 0$ for every $\zeta \in W^{1,p}(\Omega)$ for $p > 2$. Up to subtracting a constant, we may assume that $\int_{\Omega} \hat{\psi} dx = 0$; letting $\zeta \in W^{3,q}(\Omega)$ be a solution of $\Delta \zeta = \hat{\psi}$ in Ω and $\frac{\partial \zeta}{\partial \nu} = 0$ on $\partial\Omega$, integration by parts yields

$$\int_{\Omega} \hat{\psi}^2 dx = \int_{\Omega} \hat{\psi} \Delta \zeta dx = - \int_{\Omega} \nabla \hat{\psi} \cdot \nabla \zeta dx + \int_{\partial\Omega} \hat{\psi} \frac{\partial \zeta}{\partial \nu} d\mathcal{H}^1 = 0,$$

i.e., $\hat{\psi} = 0$ in Ω .

We now study the function $R(z) = \psi(z) + \sum_{j=1}^N d_j \log |z - a_j|$ defined for $z \in \Omega$. The above properties of ψ yield R is harmonic in Ω and $R \in W^{1,q}(\Omega)$ for every $q \in [1, 2)$. In fact, R has better regularity. Indeed, note that $\frac{\partial}{\partial \nu} \log |z - a_j| = -\pi \delta_{a_j} + Q_j(z)$ for $z \in \partial\Omega$ where $Q_j \in L^\infty(\partial\Omega)$.²³ Thus, by (5.2), we compute $\frac{\partial}{\partial \nu} R = -\varkappa + \sum_{j=1}^N d_j Q_j \in L^\infty(\partial\Omega)$. Standard elliptic theory²⁴ implies $R \in W^{s,p}(\Omega)$ for every $p \in [1, \infty)$ and $s \in [1, 1 + \frac{1}{p})$, in particular, $R \in H^1(\Omega)$ and $R \in C^{0,\alpha}(\bar{\Omega})$ for every $\alpha \in (0, 1)$ by Sobolev embedding.

Finally, we prove (5.1). On $\Omega_\rho = \Omega \setminus \bigcup_{j=1}^N B_\rho(a_j)$ with the outer unit normal vector ν , we now calculate

$$\int_{\Omega_\rho} |\nabla \phi_*|^2 dx = \int_{\Omega_\rho} |\nabla \psi|^2 dx = \int_{\partial\Omega_\rho} \psi \frac{\partial \psi}{\partial \nu} d\mathcal{H}^1.$$

The final integral can be split into

$$\int_{\partial\Omega_\rho} \psi \frac{\partial \psi}{\partial \nu} d\mathcal{H}^1 = \int_{\partial\Omega_\rho \cap \partial\Omega} \psi \frac{\partial \psi}{\partial \nu} d\mathcal{H}^1 - \sum_{j=1}^N \int_{\partial B_\rho(a_j) \cap \Omega} \psi \frac{\partial \psi}{\partial \rho} d\mathcal{H}^1,$$

²²A second proof can be given using the uniqueness of the conjugate function ϕ (up to an additive function) explained in Remark 3.

²³For $\partial\Omega$, we use the counterclockwise arc-length parametrization $\gamma \in C^{1,1}$ with $|\gamma'| = 1$ and $\gamma(0) = a_j$. Writing $\tau(t) = \gamma'(t)$ and $\nu(t) = -\gamma'(t)^\perp$, then $\frac{\partial \log |z - a_j|}{\partial \nu}|_{z=\gamma(t)} = \frac{(\gamma(t) - a_j) \cdot \nu(t)}{|\gamma(t) - a_j|^2} =: Q_j(\gamma(t))$ for every $t \neq 0$. This is a bounded function because $\gamma(t) - a_j = t(\tau(t) + O(t))$ and $(\gamma(t) - a_j) \cdot \nu(t) = \int_0^t (\gamma(s) - a_j) \cdot \nu'(s) ds = \pm \int_0^t s(1 + O(s)) \varkappa(s) ds = O(t^2)$.

²⁴One can deduce this regularity by using a conjugate harmonic function for R .

with $\frac{\partial}{\partial \rho}$ denoting the radial derivative at $\partial B_\rho(a_j)$. The first term in the above RHS converges as $\rho \rightarrow 0$:

$$\int_{\partial \Omega_\rho \cap \partial \Omega} \psi \frac{\partial \psi}{\partial \nu} d\mathcal{H}^1 = - \int_{\partial \Omega_\rho \cap \partial \Omega} \psi \varkappa d\mathcal{H}^1 \rightarrow - \int_{\partial \Omega} \psi \varkappa d\mathcal{H}^1,$$

because $\varkappa \in L^\infty(\partial \Omega)$ and $\psi \in L^1(\partial \Omega)$ (by the trace theorem for $\psi \in W^{1,1}(\Omega)$). For the second term, we observe that on $\partial B_\rho(a_j) \cap \Omega$, $\frac{\partial \psi}{\partial \rho} = -\frac{d_j}{\rho} + \frac{\partial R}{\partial \rho} + S_j(z)$, where S_j is smooth in $\overline{B_\rho(a_j)} \cap \Omega$ for small $\rho > 0$, so

$$- \int_{\partial B_\rho(a_j) \cap \Omega} \psi \frac{\partial \psi}{\partial \rho} d\mathcal{H}^1 = \int_{\partial B_\rho(a_j) \cap \Omega} \left(R(z) - \sum_{k=1}^N d_k \log |z - a_k| \right) \left(\frac{d_j}{\rho} - \frac{\partial R}{\partial \rho} - S_j(z) \right) d\mathcal{H}^1.$$

Thus, since $\mathcal{H}^1(\partial B_\rho(a_j) \cap \Omega) = \pi \rho + o(\rho)$, we have for $\rho \rightarrow 0$: $\int_{\partial B_\rho(a_j) \cap \Omega} R S_j d\mathcal{H}^1 \rightarrow 0$,

$$\begin{aligned} \frac{d_j}{\rho} \int_{\partial B_\rho(a_j) \cap \Omega} R d\mathcal{H}^1 &\rightarrow \pi d_j R(a_j), & \frac{d_j}{\rho} \int_{\partial B_\rho(a_j) \cap \Omega} \log |z - a_k| d\mathcal{H}^1 &\rightarrow \pi d_j \log |a_j - a_k|, \quad k \neq j, \\ \int_{\partial B_\rho(a_j) \cap \Omega} R \frac{\partial R}{\partial \rho} d\mathcal{H}^1 &= \int_{B_\rho(a_j) \cap \Omega} |\nabla R|^2 dx - \int_{B_\rho(a_j) \cap \partial \Omega} R \frac{\partial R}{\partial \nu} d\mathcal{H}^1 \rightarrow 0, \end{aligned} \quad (5.3)$$

because $R \in H^1(\Omega) \cap C^0(\overline{\Omega})$ and $\frac{\partial R}{\partial \nu} \in L^\infty(\partial \Omega)$. Also, as in (5.3), integration by parts in $B_\rho(a_j) \cap \Omega$ yields $\int_{\partial B_\rho(a_j) \cap \Omega} \frac{\partial R}{\partial \rho} \zeta d\mathcal{H}^1 \rightarrow 0$ as $\rho \rightarrow 0$ for the functions $\zeta = |\log \rho|$, resp. $\zeta(z) = \log |z - a_k|$ for $k \neq j$. Summing after j , as $d_j^2 = 1$, the above estimates for $\rho \rightarrow 0$ lead to the representation formula (5.1) via Definition 5. \square

We now present a somewhat more geometric argument to compute the renormalized energy in Definition 5. This is based on the identification of the canonical harmonic maps with prescribed boundary vortices. In the following, we prove Theorem 4, i.e., an explicit formula of these canonical harmonic maps, first in the case of a disk domain, second on a general $C^{1,1}$ domain via a conformal Riemann map.²⁵

Proof of Theorem 4. The idea is to use the following two claims:

Claim 1. If $\Omega = \mathbb{R}_+^2$, then for any $N \geq 1$ distinct points $\{a_j\}_{1 \leq j \leq N}$ on $\partial \Omega = \mathbb{R} \times \{0\}$ with multiplicities²⁶ $d_1, \dots, d_N \in \mathbb{Z} \setminus \{0\}$, the canonical harmonic map with prescribed boundary vortices $\{(a_j, d_j)\}$ has the form

$$m_*(z) = \pm \prod_{j=1}^N \left(\frac{z - a_j}{|z - a_j|} \right)^{d_j}, \quad \text{for all } z \in \mathbb{R}^2.$$

Claim 2. Let $\Phi : \overline{\omega} \rightarrow \overline{\Omega}$ be a C^1 conformal diffeomorphism with inverse Ψ between two simply connected domains $\omega, \Omega \subset \mathbb{R}^2$. If m_* is a canonical harmonic map with prescribed boundary vortices $\{(a_j, d_j)\}$ on $\partial \omega$ (where $\{a_j\}_{1 \leq j \leq N}$ are distinct points on $\partial \omega$ and d_j are non-zero integers satisfying $\sum_{j=1}^N d_j = 2$), then M_* given in (1.16) is the canonical harmonic map with prescribed boundary vortices $\{(\Phi(a_j), d_j)\}$ on $\partial \Omega$.

Proof of Claim 1. In the case of the domain \mathbb{R}_+^2 , a canonical harmonic map satisfies $m_*(z) = e^{i\phi_*(z)}$ in $z = (x, y) \in \mathbb{R}_+^2$ with $\Delta \phi_* = 0$ in \mathbb{R}_+^2 and $\partial_x \phi_* = -\pi \sum_{j=1}^N d_j \delta_{a_j}$ on $\mathbb{R} \times \{0\}$ where

²⁵For a related calculation (with boundary values $\{\pm 1\}$ instead of \pm the unit tangent), see Cabré et al. [6].

²⁶In this case, there is **no** constraint on $\sum_{j=1}^N d_j$.

$\phi_*(\mathbb{R} \times \{0\}) \subset \pi\mathbb{Z}$. As in the proof of Proposition 20, any solution ϕ_* of this problem is determined via a conjugate harmonic function that has the form $\psi_*(z) = -\sum_{j=1}^N d_j \log |z - a_j|$ for $z \in \mathbb{R}_+^2$. So, if Arg is a smooth argument in $\mathbb{C} \setminus \mathbb{R}_+$, then $\phi_*(z) = \sum_{j=1}^N d_j \text{Arg}(z - a_j)$ for $z \in \mathbb{R}_+^2$ is a solution of our problem, unique up to an additive constant in $\pi\mathbb{Z}$.

Proof of Claim 2. As Φ is a conformal map, we know that any point $z \in \partial\omega$ is mapped to $\Phi(z) \in \partial\Omega$; also, any unit tangent vector $v \in \mathbb{S}^1$ on $\partial\omega$ at z is mapped to $\Phi'(z)v$, so the associated unit tangent on $\partial\Omega$ at $\Phi(z)$ is given by $\frac{v\Phi'(z)}{|\Phi'(z)|}$ and the orientation with respect to the outer normal fields at $\partial\omega$ and $\partial\Omega$ is preserved. This means that if m_* is a canonical harmonic map with prescribed boundary vortices $\{(a_j, d_j)\}$ on $\partial\omega$, then the map given by $w = \Phi(z) \in \bar{\Omega} \mapsto \tilde{m}_*(z) = m_*(z) \frac{\Phi'(z)}{|\Phi'(z)|}$, in other words $M_*(w) = m_*(\Psi(w)) \frac{\Phi'(\Psi(w))}{|\Phi'(\Psi(w))|}$ yields a map that is tangential to $\partial\Omega \setminus \{\Phi(a_j)\}$. Note that $\Phi'(z) = |\Phi'(z)|e^{i\Theta(z)}$ for a smooth harmonic function $\Theta : \omega \rightarrow \mathbb{R}$ (recall that Φ' is holomorphic and never zero on the simply connected domain ω , so it has a holomorphic logarithm).

Since $m_* = e^{i\phi_*}$ in ω , it yields $M_* = e^{i\tilde{\phi}_*}$ with

$$\tilde{\phi}_*(w) = \phi_*(\Psi(w)) + \Theta(\Psi(w)) \quad \text{for every } w \in \Omega \quad (5.4)$$

yielding $\tilde{\phi}_*$ is harmonic in Ω . Since Θ is smooth, the degrees of m_* near a_j and M_* near $\Phi(a_j)$ are the same.

Coming back to the proof of Theorem 4, in the case of the unit disk $\Omega = B_1$ and $a_1, \dots, a_N \in \partial B_1$, we choose $\omega = \mathbb{R}_+^2$ and for each $b \in \partial B_1 \setminus \{a_1, \dots, a_N\}$, we consider the conformal map $\Phi : \mathbb{R}_+^2 \rightarrow \bar{B}_1$ given by $\Phi(z) = b \frac{z-i}{z+i}$ for $z \in \mathbb{R}_+^2 \subset \mathbb{C}$ with the inverse $\Psi(w) = i \frac{w+b}{b-w}$ for $w \in B_1$. Letting $\alpha_j = \Psi(a_j)$ for $j = 1, \dots, N$ and m_* be the canonical harmonic map in ω given at Claim 1 for prescribed boundary vortices $\{(\alpha_j, d_j)\}$ where $\sum_{j=1}^N d_j = 2$, then one uses Claim 2 to deduce a canonical harmonic map M_* as in (1.15) with prescribed boundary vortices $\{(a_j, d_j)\}$. (The constraint $\sum_{j=1}^N d_j = 2$ is essential in the formula (1.15) even if Claim 1 was independent of this constraint.) By the uniqueness of the canonical map (up to the transformation $M_* \mapsto -M_*$) for prescribed boundary vortices $\{(a_j, d_j)\}$, we deduce the uniqueness in (1.15).²⁷ The general case of an arbitrary simply connected domain Ω follows by Claim 2. \square

We now prove the formula of the renormalized energy stated in Theorem 6:

Proof of Theorem 6. The idea is to determine the solution ψ in (5.2):

Fact 1. If $\Omega = \mathbb{R}_+^2$, then for any $N \geq 1$ distinct points $\{a_j\}_{1 \leq j \leq N}$ on $\partial\Omega = \mathbb{R} \times \{0\}$ with multiplicities²⁸ $d_1, \dots, d_N \in \mathbb{Z} \setminus \{0\}$, the solution (up to an additive constant) of (5.2) has the form

$$\psi_*(z) = -\sum_{j=1}^N d_j \log |z - a_j| \quad \text{for all } z \in \mathbb{R}^2.$$

²⁷The uniqueness in (1.15) yields the following fundamental identity: for every $b, \tilde{b} \in \partial B_1 \setminus \{a_1, \dots, a_N\}$, then

$$b \prod_{j=1}^N \left(\frac{|b - a_j|}{b - a_j} \right)^{d_j} = \pm \tilde{b} \prod_{j=1}^N \left(\frac{|\tilde{b} - a_j|}{\tilde{b} - a_j} \right)^{d_j},$$

where $\sum_{j=1}^N d_j = 2$. In fact, this identity can be proved as follows: if $b = e^{i\beta}$ and $a_j = e^{i\alpha_j}$, then $b - a_j = |b - a_j| e^{i \frac{\beta + \alpha_j \pm \pi}{2}}$ which yields the results due to the constraint $\sum_{j=1}^N d_j = 2$ with $d_j \in \mathbb{Z} \setminus \{0\}$.

²⁸In this case, there is **no** constraint $\sum_{j=1}^N d_j = 2$.

(This is because $\frac{\partial}{\partial y} \log |z - a_j| = \pi \delta_{a_j}$ for $z = (x, y)|_{y=0}$.)

Fact 2. Let $\Phi : \bar{\omega} \rightarrow \bar{\Omega}$ be a C^1 conformal diffeomorphism with inverse Ψ between two $C^{1,1}$ simply connected domains $\omega, \Omega \subset \mathbb{R}^2$. If ψ_* is a solution of (5.2) with prescribed boundary vortices $\{(a_j, d_j)\}$ on $\partial\omega$ (where $\{a_j\}_{1 \leq j \leq N}$ are distinct points on $\partial\omega$ and d_j are non-zero integers satisfying $\sum_{j=1}^N d_j = 2$), then

$$\tilde{\psi}_*(w) = \psi_*(\Psi(w)) + \log |\Psi'(w)| \quad \text{for every } w \in \Omega$$

is a solution of (5.2) with prescribed boundary vortices $\{(\Phi(a_j), d_j)\}$ on $\partial\Omega$. (This is a consequence of (5.4) where $\tilde{\phi}_*(w)$ and $\phi_*(z)$ are harmonic conjugates²⁹ of $\tilde{\psi}_*(w)$ and $\psi_*(z)$ respectively, while $\Theta(z)$ is a conjugate harmonic of $-\log |\Phi'(z)| = \log |\Psi'(w)|$ for every $z = \Psi(w) \in \omega$.)

Case 1. $\Omega = B_1$. As in the proof of Theorem 4, we choose $\omega = \mathbb{R}_+^2$ and $b \in \partial B_1 \setminus \{a_1, \dots, a_N\}$; then we consider the conformal map $\Phi : \bar{\mathbb{R}}_+^2 \rightarrow \bar{B}_1$ given by $\Phi(z) = b \frac{z-i}{z+i}$ for every $z \in \mathbb{R}_+^2 \subset \mathbb{C}$ with inverse $\Psi(w) = i \frac{w+b}{b-w}$ for every $w \in B_1$. By Facts 1 and 2, a solution ψ_* of (5.2) in B_1 is given by

$$\begin{aligned} \psi_*(w) &= - \sum_j d_j \log |\Psi(w) - \Psi(a_j)| + \log \frac{2}{|b-w|^2} \\ &= - \sum_j d_j \log \frac{2|w-a_j|}{|b-w| \cdot |b-a_j|} + \log \frac{2}{|b-w|^2} \\ &= - \sum_j d_j \log |w-a_j| + R(w) \quad \text{for all } w \in B_1, \end{aligned} \tag{5.5}$$

where R is a constant function in B_1 (because of the constraint $\sum_j d_j = 2$). Using that on ∂B_1 , $\varkappa = 1$ and³⁰ $\int_{\partial B_1} \log |z-a| d\mathcal{H}^1 = 0$ for all $a \in \partial B_1$, we conclude to the desired formula via (5.1) and Remark 21.

Case 2. General domain Ω . We use Fact 2 and Case 1 where we can replace ψ_* in (5.5) by $\psi_* - R$ as R is a constant function (due to Remark 21). Therefore, the solution $\tilde{\psi}_*$ of (5.2) in Ω is given by

$$\tilde{\psi}_*(w) = - \sum_j d_j \log |\Psi(w) - \Psi(a_j)| + \log |\Psi'(w)| \quad \text{for all } w \in \Omega.$$

It follows that

$$\tilde{R}(w) = \tilde{\psi}_*(w) + \sum_j d_j \log |w-a_j| = - \sum_j d_j \log \frac{|\Psi(w) - \Psi(a_j)|}{|w-a_j|} + \log |\Psi'(w)|.$$

As $d_k^2 = 1$ for every k , it yields

$$\pi d_k \tilde{R}(a_k) = -\pi \sum_{j \neq k} d_k d_j \log \frac{|\Psi(a_k) - \Psi(a_j)|}{|a_k - a_j|} + \pi(d_k - 1) \log |\Psi'(a_k)|$$

and the desired formula follows by (5.1). □

²⁹Recall our sign convention that $\phi_* + i\psi_*$ is holomorphic in ω .

³⁰For $a \in \partial B_1$, $z \in B_1 \mapsto \log |z-a|$ is harmonic, so the mean-value formula leads to $0 = \log |z-a|_{z=0} = \frac{1}{2\pi r} \int_{\partial B(0,r)} \log |z-a| d\mathcal{H}^1 = \frac{1}{2\pi} \int_{\partial B_1} \log |rz-a| d\mathcal{H}^1 \rightarrow \frac{1}{2\pi} \int_{\partial B_1} \log |z-a| d\mathcal{H}^1$ as $r \uparrow 1$ by dominated convergence theorem (due to the fact that $\log |z-a| \in L^1(\partial B_1)$).

Remark 23 It is possible to also encode the effect of a small applied field or anisotropy in the renormalized energy, as has been done by Kurzke-Melcher-Moser [34] for interior vortices. In this case, the optimal phase is no longer harmonic, but satisfies a nonlinear elliptic equation instead.

Proof of Corollary 7. If $\Phi : \overline{B_1} \rightarrow \overline{\Omega}$ is a C^1 conformal diffeomorphism with inverse Ψ , setting $b_1 = \Psi(a_1) \in \partial B_1$, $b_2 = \Psi(a_2) \in \partial B_1$ for two distinct points $a_1, a_2 \in \partial\Omega$, Remark 8 yields

$$\begin{aligned} & W_\Omega(\{(a_1, 1), (a_2, 1)\}) \\ &= -2\pi \log |b_1 - b_2| + \int_{\partial B_1} \varkappa(\Phi(z)) |\Phi'(z)| \left(\log |z - b_1| + \log |z - b_2| + \log |\Phi'(z)| \right) d\mathcal{H}^1(z). \end{aligned}$$

Let $D = (\partial\Omega \times \partial\Omega) \setminus \{(a, a) : a \in \partial\Omega\}$. In order to prove the existence of minimizers of $W_\Omega(\{(\cdot, 1), (\cdot, 1)\})$ over D , we consider a minimizing sequence $(a_1^{(n)}, a_2^{(n)}) \in D$ for every $n \in \mathbb{N}$. Set $b_1^{(n)} = \Psi(a_1^{(n)})$ and $b_2^{(n)} = \Psi(a_2^{(n)})$. As $\partial\Omega$ is compact, up to a subsequence, we can assume that $a_1^{(n)} \rightarrow a_1^*$ and $a_2^{(n)} \rightarrow a_2^*$ as $n \rightarrow \infty$; thus, $b_1^{(n)} \rightarrow \Psi(a_1) =: b_1^*$ and $b_2^{(n)} \rightarrow \Psi(a_2) =: b_2^*$. Note that

$$(b_1, b_2) \in \partial B_1 \times \partial B_1 \mapsto \int_{\partial B_1} \varkappa(\Phi(z)) |\Phi'(z)| \left(\log |z - b_1| + \log |z - b_2| + \log |\Phi'(z)| \right) d\mathcal{H}^1(z)$$

is a bounded function as $\varkappa \in L^\infty(\partial\Omega)$. As $\left(W_\Omega(\{(a_1^{(n)}, 1), (a_2^{(n)}, 1)\}) \right)_n$ is bounded, it implies that $(\log |b_1^{(n)} - b_2^{(n)}|)_n$ is bounded; thus, $b_1^* \neq b_2^*$ and so, $a_1^* \neq a_2^*$ (as Ψ is injective), i.e., $(a_1^*, a_2^*) \in D$. By the continuity of $W_\Omega(\{(\cdot, 1), (\cdot, 1)\})$ over D , we deduce that (a_1^*, a_2^*) is a minimizer. If $\Omega = B_1$, then $W_\Omega(\{(a_1, 1), (a_2, 1)\}) = -2\pi \log |a_1 - a_2|$ and any diameter (a_1^*, a_2^*) minimizes the renormalized energy reaching the minimal value $-2\pi \log 2$. \square

A Existence and uniqueness of the stray field

We prove existence and uniqueness of the H^1 stray field potential U in (1.1) and we determine the exact formula of U .

Proposition 24 *Let $\omega \subset \mathbb{R}^3$ be a bounded open set and $\mathbf{m} \in L^2(\omega, \mathbb{R}^3)$. Then there exists a unique stray field potential $U \in H^1(\mathbb{R}^3)$ of the problem (1.1). The exact expression is given by the convolution*

$$U(\mathbf{x}) = -\frac{1}{4\pi|\mathbf{x}|} \star \nabla \cdot (\mathbf{m}\mathbf{1}_\omega) \quad \text{in } \mathbb{R}^3$$

of the distribution of compact support $\nabla \cdot (\mathbf{m}\mathbf{1}_\omega)$ and the tempered distribution $V(\mathbf{x}) = -\frac{1}{4\pi|\mathbf{x}|} \in \mathcal{S}'(\mathbb{R}^3)$ that is the fundamental solution $\Delta V = \delta_0$ in \mathbb{R}^3 . Moreover, if ω is Lipschitz and $\mathbf{m} \in H^1(\omega, \mathbb{R}^3)$, then

$$4\pi U(\mathbf{x}) = -\int_\omega \frac{1}{|\mathbf{x} - \mathbf{y}|} \nabla \cdot \mathbf{m}(\mathbf{y}) \, d\mathbf{y} + \int_{\partial\omega} \frac{1}{|\mathbf{x} - \mathbf{y}|} (\mathbf{m} \cdot \boldsymbol{\nu})(\mathbf{y}) \, d\mathcal{H}^2(\mathbf{y}), \quad (\text{A.1})$$

where $\boldsymbol{\nu}$ is the unit outer normal vector at $\partial\omega$.

Proof. We apply Lax-Milgram's theorem for the problem (1.1) in the Beppo-Levi space (in other words, the homogeneous \dot{H}^1 -space):

$$\begin{aligned}\mathcal{BL} &= \{U : \mathbb{R}^3 \rightarrow \mathbb{R} : \nabla U \in L^2(\mathbb{R}^3), \frac{U}{1+|\mathbf{x}|} \in L^2(\mathbb{R}^3)\} \\ &= \{U \in \mathcal{S}'(\mathbb{R}^3) : \mathcal{F}(U) \in L^2_{loc}(\mathbb{R}^3), |\boldsymbol{\xi}| \mathcal{F}(U) \in L^2(\mathbb{R}^3)\} =: \dot{H}^1(\mathbb{R}^3),\end{aligned}$$

where $\mathcal{F}(U)(\boldsymbol{\xi}) = \int_{\mathbb{R}^3} e^{-i\mathbf{x} \cdot \boldsymbol{\xi}} U(\mathbf{x}) d\mathbf{x}$ is the Fourier transform of U and $\boldsymbol{\xi}$ is the Fourier variable in \mathbb{R}^3 . The space \mathcal{BL} endowed with the homogeneous \dot{H}^1 -norm, i.e., $U \mapsto \|\nabla U\|_{L^2(\mathbb{R}^3)}$, is a Hilbert space and the set $C_c^\infty(\mathbb{R}^3)$ of smooth compactly supported functions is a dense set. Since $\mathbf{m} \in L^2$, Lax-Milgram's theorem yields the existence and uniqueness of the solution $U \in \mathcal{BL}$ of (1.1), in particular, $\nabla U \in L^2(\mathbb{R}^3)$, the Fourier transform $\mathcal{F}(U) \in L^2_{loc}(\mathbb{R}^3)$ and we have

$$\Delta U = \nabla \cdot (\mathbf{m} \mathbb{1}_\omega) \quad \text{in the sense of distributions in } \mathbb{R}^3.$$

This equation implies the following equality in the Fourier space:

$$\mathcal{F}(U)(\boldsymbol{\xi}) = -\frac{i\boldsymbol{\xi} \cdot \mathcal{F}(\mathbf{m} \mathbb{1}_\omega)(\boldsymbol{\xi})}{|\boldsymbol{\xi}|^2}, \quad \boldsymbol{\xi} \in \mathbb{R}^3 \setminus \{0\}.$$

We check that $U \in L^2(\mathbb{R}^3)$. Indeed,

$$\begin{aligned}(2\pi)^3 \|U\|_{L^2(\mathbb{R}^3)}^2 &= \|\mathcal{F}(U)\|_{L^2(\mathbb{R}^3)}^2 \\ &\leq \int_{|\boldsymbol{\xi}| \geq 1} \frac{|\mathcal{F}(\mathbf{m} \mathbb{1}_\omega)(\boldsymbol{\xi})|^2}{|\boldsymbol{\xi}|^2} d\boldsymbol{\xi} + \int_{|\boldsymbol{\xi}| \leq 1} \frac{|\mathcal{F}(\mathbf{m} \mathbb{1}_\omega)(\boldsymbol{\xi})|^2}{|\boldsymbol{\xi}|^2} d\boldsymbol{\xi}, \\ &\leq \|\mathcal{F}(\mathbf{m} \mathbb{1}_\omega)\|_{L^2(\mathbb{R}^3)}^2 + \|\mathcal{F}(\mathbf{m} \mathbb{1}_\omega)\|_{L^\infty(\mathbb{R}^3)}^2 \int_{|\boldsymbol{\xi}| \leq 1} \frac{1}{|\boldsymbol{\xi}|^2} d\boldsymbol{\xi} \\ &\leq C \left(\|\mathbf{m}\|_{L^2(\omega)}^2 + \|\mathbf{m}\|_{L^1(\omega)}^2 \right) \leq C \|\mathbf{m}\|_{L^2(\omega)}^2.\end{aligned}$$

Let us check that the solution U coincides with $\tilde{U} = V \star \nabla \cdot (\mathbf{m} \mathbb{1}_\omega)$ in \mathbb{R}^3 . Indeed, we have that $V \in L^1(\mathbb{R}^3) + L^4(\mathbb{R}^3)$ (so, V is a tempered distribution in $\mathcal{S}'(\mathbb{R}^3)$ with $\mathcal{F}(V) = -1/|\boldsymbol{\xi}|^2$ for $\boldsymbol{\xi} \neq 0$) and $\nabla \cdot (\mathbf{m} \mathbb{1}_\omega)$ is a distribution of compact support (because ω is bounded); thus, \tilde{U} is a tempered distribution in $\mathcal{S}'(\mathbb{R}^3)$ and we check that $|\boldsymbol{\xi}| \mathcal{F}(\tilde{U}) = |\boldsymbol{\xi}| \mathcal{F}(V) \cdot \mathcal{F}(\nabla \cdot (\mathbf{m} \mathbb{1}_\omega)) \in L^2(\mathbb{R}^3)$, i.e.,

$$\int_{\mathbb{R}^3} |\boldsymbol{\xi}|^2 |\mathcal{F}(\tilde{U})|^2 d\boldsymbol{\xi} = \int_{\mathbb{R}^3} \frac{1}{|\boldsymbol{\xi}|^2} |\mathcal{F}(\nabla \cdot (\mathbf{m} \mathbb{1}_\omega))|^2 d\boldsymbol{\xi} \leq \int_{\mathbb{R}^3} |\mathcal{F}(\mathbf{m} \mathbb{1}_\omega)|^2 d\boldsymbol{\xi} = (2\pi)^3 \|\mathbf{m}\|_{L^2(\omega)}^2.$$

We conclude that \tilde{U} belongs to $\dot{H}^1(\mathbb{R}^3)$, satisfies $\Delta \tilde{U} = \nabla \cdot (\mathbf{m} \mathbb{1}_\omega)$ in \mathbb{R}^3 and by the uniqueness of the solution U of (1.1), it follows that $U = \tilde{U}$ in \mathbb{R}^3 . In the case of a Lipschitz domain ω and $\mathbf{m} \in H^1(\omega, \mathbb{R}^3)$, one decomposes

$$\nabla \cdot (\mathbf{m} \mathbb{1}_\omega) = \nabla \cdot \mathbf{m} \mathcal{H}^3 \llcorner \omega - \mathbf{m} \cdot \nu \mathcal{H}^2 \llcorner \partial \omega$$

in the sense of measures in \mathbb{R}^3 and therefore, (A.1) follows via $U = V \star \nabla \cdot (\mathbf{m} \mathbb{1}_\omega)$. \square

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