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Thunks and Debits in Separation Logic with Time Credits

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A thunk is a mutable data structure that offers a simple memoization service: it stores either a suspended computation or the result of this computation. Okasaki [1999] presents many data structures that exploit thunks to achieve good amortized time complexity. He analyzes their complexity by associating a debit with every thunk. A debit can be paid off in several increments; a thunk whose debit has been fully paid off can be forced. Quite strikingly, a debit is associated also with future thunks, which do not yet exist in memory. Some of the debit of a faraway future thunk can be transferred to a nearer future thunk. We present a complete machine-checked reconstruction of Okasaki's reasoning rules in Iris^S, a rich separation logic with time credits. We demonstrate the applicability of the rules by verifying a few operations on streams as well as several of Okasaki's data structures, namely the physicist's queue, implicit queues, and the banker's queue.

CCS Concepts: • **Theory of computation** → **Separation logic; Program verification.**

Additional Key Words and Phrases: program verification, separation logic, time complexity

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1 INTRODUCTION

In a famous book, Okasaki [1999] presents several data structures for purely functional programs. These data structures are *persistent* [Driscoll et al. 1989], that is, apparently immutable. Instead of mutating its argument, an update operation returns a new data structure, leaving the observable content of the original data structure intact.

In order to achieve good time complexity, Okasaki uses thunks, also known as suspensions. A *thunk* is a mutable data structure that offers a simple memoization service: it stores either a suspended computation or the result of this computation. The use of thunks does not affect the functional behavior of a program, but allows delaying a computation until the moment where its result is definitely needed, while still sharing this result. Thus, the use of thunks can improve the time complexity of a program, without impacting its final result. For this reason, thunks are

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```

1 type 'a stream = 'a cell thunk
2 and 'a cell   = Nil | Cons of 'a * 'a stream
3
4 let nil () : 'a stream =
5   Thunk.create @@ fun () -> Nil
6
7 let uncons (s : 'a stream) : 'a * 'a stream =
8   match Thunk.force s with
9   | Nil           -> assert false (* dead branch *)
10  | Cons (x, s) -> x, s
11
12 let rec append (s1 : 'a stream) (s2 : 'a stream) : 'a stream =
13   Thunk.create @@ fun () -> match Thunk.force s1 with
14   | Nil           -> Thunk.force s2
15   | Cons (x, s1) -> Cons (x, append s1 s2)
16
17 let rec revl_append (l : 'a list) (c : 'a cell) : 'a cell =
18   match l with
19   | []           -> c
20   | x :: l -> revl_append l (Cons (x, Thunk.create @@ fun () -> c))
21
22 let revl (l : 'a list) : 'a stream =
23   Thunk.create @@ fun () -> revl_append l Nil

```

Fig. 1. Streams: OCaml Code

accepted as an essential part of the “functional programming” toolbox [Hughes 1989]. In fact, in the functional programming language Haskell, creating and forcing thunks are implicit operations.

Thunks are a basic building block in the construction of *streams*, whose definition appears in Figure 1. A stream is a lazy list: each stream cell is wrapped in a thunk, so it is evaluated only on demand. Figure 1 presents several functions on streams. The functions `Thunk.create` and `Thunk.force` are used to create and force thunks. The function `append` (line 12) lazily appends two streams: a thunk in the stream `s1` and `s2` is forced only when needed, that is, only when the corresponding thunk in the result stream is forced. `revl` (line 22) reverses a list, returning a stream. It is also lazy, insofar as possible: the expensive list reversal operation (performed by the auxiliary function `revl_append`) is carried out only when the first thunk of the result stream is forced.

Okasaki’s complexity bounds are *amortized* [Tarjan 1985]: that is, the actual cost of an operation may be higher than its advertised cost. Still, the advertised complexity bounds are sound, and can be used to compute a safe bound on the global execution time of a program. The basic idea of amortization [Tarjan 1985] is simple: if the advertised cost of some operations is made slightly higher than their actual cost, then a sequence of operations accumulates a certain amount of *credit*, which can be used to justify an occasional “expensive” operation, whose actual cost exceeds its advertised cost. One must stress, however, that Okasaki does not reason in terms of credit, and cannot do so, because he needs thunks to be shareable. Sharing credit leads to an unsound analysis, as credit can then be spent twice. Instead, Okasaki reasons in terms of *debit*. With every thunk, he associates a debit, a nonnegative integer number, which indicates how much one must pay *before* this thunk can be forced. In other words, Okasaki ensures that the actual cost of forcing a thunk is

always *paid for in advance*. Once its debt has been paid off, a thunk can be forced as many times as one wishes, essentially “for free”, that is, at cost $O(1)$. Even if thunks are shared, this analysis is sound: indeed, duplicating a debt leads to an over-approximation of a program’s time complexity.

In summary, Okasaki’s thunks with debits support three main operations: creation, forcing, and *paying*. When a new thunk is created, its debit is the cost of the suspended computation. If the debit associated with this thunk becomes zero, then this thunk can be forced. Between these two points in time, this thunk’s debit can be reduced by paying, in one or more increments. Paying is a ghost operation: it has no runtime effect, as there is no runtime accounting of debits. Paying decreases the debit of a thunk from n down to $n - k$ and is itself regarded as an operation that costs k units of time. Danielsson [2008] must be credited for this crisp explanation of Okasaki’s analysis technique.

Because every cell in a stream involves a thunk, it is natural to represent the “cost” of a stream as a sequence of debits, recording the cost of forcing each stream cell, or, more accurately, the remaining debt associated with each stream cell. The “cost” of each operation on streams can then be expressed in terms of sequences of debits. For example, the debit sequence of the stream returned by `append` is roughly the concatenation of the debit sequences of the two argument streams, plus an overhead of $O(1)$ that is added to the first part of the new debit sequence, so as to account for the cost of concatenation itself. (Details appear in §6.3 and Figure 16.) As another example, in the stream returned by `revl`, the first thunk has debit $O(n)$, where n is the length of the list l , while the following thunks have debit zero: indeed, the expensive list reversal operation is performed when the first thunk is forced, and the remaining thunks require no computation at all.

In this paper, we wish to give a mechanized and foundational account of Okasaki’s debit-based reasoning discipline. We want our mechanized reasoning rules to be expressive enough to verify the functional correctness and time complexity of Okasaki’s functional data structures and of (possibly imperative) client programs that use these data structures. This requires addressing several challenges:

- (1) We need a program logic that can express and verify worst-case bounds on execution time. This logic must allow debit-based reasoning about thunks, but must not be restricted to this style of reasoning: code that does not involve thunks typically requires credit-based reasoning.
- (2) Similarly, this logic must allow reasoning not only about purely functional data structures, but also about imperative data structures and algorithms. In other words, it must support modular reasoning about mutable state.
- (3) As demonstrated by `append`, it is common to construct a thunk which (when forced) forces another thunk. Unfortunately, in the presence of mutable state, one can also construct a *reentrant* thunk, that is, a thunk that attempts to force itself, resulting (at best) in a graceful runtime error or (at worst) in undesirable behavior, such as divergence. We want the logic to statically forbid reentrancy, thereby offering a strong guarantee: *a verified program cannot fail at runtime and must terminate within the advertised time bound*.
- (4) Although we have written that it is “natural” to associate a sequence of debits with a stream, this style of reasoning is in fact highly nontrivial, as it involves keeping track of and updating the debt of *future* thunks. That is, a thunk’s debit conceptually exists and can be updated (via a so-called *deep payment*) *before* this thunk actually exists in the machine’s memory! As a key example, we show that streams enjoy an intuitively simple *debit forwarding* rule, which allows *shifting debits towards the left* in a sequence of debits. To illustrate this rule, consider the composite operation `append f (revl r)`, where f is a stream of length n and r is a list of length n . Suppose that every thunk in the stream f has debit $O(1)$. Then, according to the specifications of `revl` and `append` that we have sketched, this composite operation

produces a stream whose debit sequence is $O(1)$ everywhere, except for the central thunk, whose debit is $O(n)$. However, debit forwarding allows us to change our view of this stream by distributing the high debt of the central thunk onto the preceding thunks. The debit of every thunk in the first half of the sequence is increased by $O(1)$, therefore remains $O(1)$, while the debit of the central thunk is reduced to $O(1)$. This nontrivial reasoning step is carried out *before* the stream constructed by `append f (revl r)` is forced. It plays a crucial role in the verification of the banker’s queue (§7).

Several papers in the literature address some, but not all, of these challenges:

- Danielsson [2008] proposes a type system, embedded in Agda, featuring an abstract type *Thunk n a* and a number of operations on this type. The integer parameter n is the debit associated with this thunk; the parameter a is the type of its result. This pioneering work however exhibits several major limitations: it is limited to purely functional programs and debit-based reasoning; it does not seem to prevent reentrancy or nontermination (§9); and the proof of type soundness is not formally connected with the API that a user of the library sees. Finally, *deep payment* (which we use to justify debit forwarding) appears in the API but is not covered by the soundness proof. Thus, Danielsson addresses Challenge 4 but not Challenges 1 to 3.
- Several authors [Atkey 2011; Hoffmann et al. 2013; Charguéraud and Pottier 2017; Haslbeck and Nipkow 2018; Zhan and Haslbeck 2018; Mével et al. 2019; Haslbeck and Lammich 2021] use *separation logic with time credits* to verify worst-case amortized time complexity bounds for possibly imperative programs. The basic idea is simple: one arranges so that every step of computation consumes one *time credit*, where a time credit is a ghost resource. Because credits can be neither forged nor duplicated, the amount of credits that are initially made available (in the precondition of a closed program) must be a bound on the total execution time of this program. Among these authors, only Mével et al. [2019] formalize thunks and debits; however, their reasoning rules support neither thunks that force thunks nor debit forwarding. Thus, these works address Challenges 1 and 2 but not Challenges 3 or 4.

Because none of these papers addresses all challenges simultaneously, no foundational verification of the time complexity of Okasaki’s notorious algorithms [1999] has been carried out until now.

Contributions. To address Challenges 1 and 2, we use Mével et al.’s Iris[§], a Separation Logic with time credits that is implemented inside the Coq proof assistant on top of the Iris framework [Jung et al. 2018]. Inside this existing logic, we verify a “thunk” library, equipped with a rich “debit” API, which supports nested thunks and deep payment, addressing Challenges 3 and 4. Using this library, we implement and verify several of Okasaki’s data structures, namely the banker’s queue [Okasaki 1999, §6.3.2] (§7), the physicist’s queue [Okasaki 1999, §6.4.2], and implicit queues [Okasaki 1999, §11.1] (§8). In each case, we verify functional correctness, termination, and worst-case amortized time complexity. Thanks to the modularity of Iris[§], our verified data structures can be used as part of verified programs that involve time-credit-based reasoning, mutable state, or shared-memory concurrency. (Our thunks are not thread-safe; our API ensures that they are used sequentially.)

Road Map. Our thunk library is organized in three layers of abstraction. After recalling some of the concepts of Iris (§2), we present the bottom layer, a novel ghost data structure, the *piggy bank* (§3). None of the operations on piggy banks has a runtime effect. The main three operations on piggy banks, namely creating, paying, and breaking (forcing) a bank, are ghost updates. The corresponding reasoning rules distill the essence of Okasaki’s debit-based reasoning. In the second layer (§4), we implement thunks and establish reasoning rules that match Okasaki’s informal rules. These rules include **THUNK-CONSEQUENCE** (Figure 5), which, together with **THUNK-PAY** (Figure 6),

justifies deep payment. This key rule is absent in Mével et al.'s earlier work. Our construction of thunks relies on piggy banks in two distinct places and can associate *an unbounded number of piggy banks* with a single thunk. In the third and last layer (§5), we equip thunks with a notion of *height* that simplifies the way in which we rule out reentrancy while still allowing thunks to force thunks.

On top of thunks, we implement streams (§6). We establish a number of reasoning rules about streams, including the debit forwarding rule **STREAM-FORWARD-DEBIT** (Figure 13), which distributes a debit over several thunks in a stream, by moving parts of this debit from the right toward the left, that is, from thunks that are more distant in the future towards thunks that are closer in the future.

After presenting our proofs of three of Okasaki's data structures (§7, §8), we review the related work (§9) and conclude (§10). We believe that our work provides a nice example of the construction of high-level abstractions on top of low-level logical concepts such as time credits, ghost state, and invariants. All of our results are machine-checked; our proofs are available [Anonymous 2023]. For readability, in the paper, we present code in OCaml syntax. The code that we actually verify is expressed in HeapLang, an untyped call-by-value λ -calculus with dynamically allocated mutable state, whose definition is bundled with Iris.

2 A REFRESHER ON IRIS AND IRIS[§]

Even a basic introduction to Iris [Jung et al. 2018] might occupy more space than is available in this paper. In this section, we recall some of the key concepts, intuition, and notation of Iris, and we hope that a reader who is not an expert in Iris can grasp the intuition behind the abstractions that we build. As an example, we need a reader who looks at the reasoning rule **THUNK-PAY** (Figure 6) to at least understand that it is a ghost update (\Rightarrow) that consumes k time credits ($\$k$) and decreases the debit of a thunk from n down to $n - k$.

Assertions. Separation logic uses *assertions* to describe certain *knowledge* about the world and to encode *permissions* to change the world in certain ways. By “the world”, we mean both the physical state of the machine and the ghost state that has been allocated as part of the proof. Some assertions are *pure*, that is, independent of the world. For example, the assertion $\ulcorner x = 0 \urcorner$ asserts that the equation $x = 0$, which involves the mathematical variable x , holds. Pure assertions are a special case of *persistent* assertions. Although persistent assertions may depend on the world, once they hold, they hold forever. For instance, the assertion *Thunk* $p \mathcal{F} t n R \phi$, which asserts (among other things) that t is the address of a valid thunk in memory, is persistent. This reflects the fact that a thunk cannot be destroyed.¹ A persistent assertion is duplicable: if P is persistent, then P entails the conjunction $P * P$. The fact that *Thunk* is persistent reflects that it is safe to share a thunk. Finally, an assertion that is neither pure nor persistent is *affine*. An affine assertion typically represents a combination of knowledge and permission. For instance, the *points-to* assertion $t \mapsto v$ represents both the exclusive knowledge that the memory location t currently contains the value v and an exclusive permission to write a new value at this location.

The natural notions of conjunction and implication are the separating conjunction $*$ and the magic wand \multimap . (The non-separating conjunction \wedge and implication \Rightarrow are not used in this paper.) A magic wand $P \multimap Q$ can be read as an implication; however, one must keep in mind that (unless P is persistent) applying this magic wand *consumes* P . A magic wand itself is *not* persistent, so it can be applied only once. It can be made persistent by using the *persistence modality*: $\Box(P \multimap Q)$ is a magic wand that can be used as many times as one wishes.

Ghost state. Like physical state, *ghost state* is dynamically allocated. The law $\text{True} \Rightarrow \exists y. \{ \gamma \mapsto m \}$ (provided by Iris) allocates a fresh ghost cell, at address y , whose initial content is m . We write

¹HeapLang does not have explicit memory deallocation. We assume that a garbage collector reclaims unreachable objects.

$\gamma, \delta, \varphi, \pi$ for ghost addresses. A *ghost update* assertion $P \Rightarrow Q$ means that, by consuming P and by updating the ghost state, it is possible to reach a state where Q holds. A ghost update is applied as part of a proof; such an application is not visible in the code. The content m of a ghost cell γ is an element of a *camera* M that is implicitly associated with γ and that is chosen when this ghost cell is allocated. For our purposes, a camera is a commutative monoid (M, \cdot) equipped with a notion of *validity*, such that *valid* $(m_1 \cdot m_2)$ implies *valid* $m_1 \wedge$ *valid* m_2 . By design, the logic guarantees that the content of a ghost cell is always a valid element. This is expressed by the law $\{\gamma \mapsto m\} \vdash \ulcorner \text{valid } m \urcorner$. The *ghost points-to* assertion $\{\gamma \mapsto m\}$ means that m is *one fragment* of the content of the ghost cell γ , and represents the ownership of just this fragment. This is reflected by the composition law $\{\gamma \mapsto m_1 \cdot m_2\} \equiv \{\gamma \mapsto m_1\} * \{\gamma \mapsto m_2\}$, which allows ghost points-to assertions to be split and joined, and by the *frame-preserving update* law, which is stated as follows: if for every m' *valid* $(m_1 \cdot m')$ implies *valid* $(m_2 \cdot m')$ then $\{\gamma \mapsto m_1\} \Rightarrow \{\gamma \mapsto m_2\}$.

A *meta witness* $t \rightsquigarrow \gamma$, a persistent assertion, indicates that the ghost address γ has been associated with the physical memory location t . The law $t \rightsquigarrow \gamma_1 * t \rightsquigarrow \gamma_2 \vdash \ulcorner \gamma_1 = \gamma_2 \urcorner$ (provided by Iris) states that this association is unique: it forms a (partial) map of physical locations to ghost addresses.

Invariants. Roughly speaking, an *invariant* is an assertion which, by convention and from a certain point on, must hold “at all times”. The assertion \boxed{I} indicates that the assertion I has been made an invariant. The law $I \Rightarrow \boxed{I}$ dynamically establishes a new invariant. Even if I is not persistent, \boxed{I} is persistent: the knowledge that an invariant exists can be shared. This knowledge allows *accessing* the invariant, that is, *opening* and *closing* it. Opening an invariant produces the assertion I , allowing the user to exploit I and possibly to destroy it, thereby temporarily violating the invariant. Closing an invariant requires the user to provide I and consumes it, thereby re-establishing the invariant.

Thus, the claim that an invariant holds “at all times” is a white lie. An invariant holds at all times *except while it is being accessed*. Therefore, the logic must forbid reentrant access to an invariant, that is, forbid opening an invariant that is already open. But how does one tell whether an invariant is currently open or closed, and how long may an invariant remain open?

One can imagine more than one way of answering these questions. Indeed Iris offers two flavors of invariants, which represent two incomparable points in the design space. An *atomic invariant* can be violated only during an atomic instruction and must be immediately restored. This may seem restrictive; on the upside, an atomic invariant can be accessed without presenting an affine token. A *non-atomic invariant* can remain violated for an unbounded time. This may seem flexible; on the downside, accessing a non-atomic invariant requires presenting an affine token.

An *atomic invariant* \boxed{I}^A is labeled with a *namespace* A . This annotation is used to forbid reentrant access: two invariants can be simultaneously opened only if they are labeled with disjoint namespaces.² Enforcing this policy requires keeping track, at all times, of which invariants can currently be accessed. We omit the details, but note that the *ghost update* connective $\Rightarrow_{\mathcal{E}}$ must be indexed with a mask \mathcal{E} . In short, $P \Rightarrow_{\mathcal{E}} Q$ means that P can be transformed into Q while accessing only those invariants whose namespace A is in the set \mathcal{E} . One may omit this mask when it is \top .

A *non-atomic invariant* \boxed{I}_p^N is labeled with a *pool* p and a namespace N . Opening such an invariant consumes an affine token $\sharp_p^{\mathcal{F}}$, where $\uparrow N \subseteq \mathcal{F}$ must hold. Closing the invariant causes this token to re-appear. Such a token can be split, thanks to the axiom $\sharp_p^{\mathcal{F}_1 \uplus \mathcal{F}_2} \equiv \sharp_p^{\mathcal{F}_1} * \sharp_p^{\mathcal{F}_2}$, so two non-atomic invariants can be simultaneously opened if they are annotated with disjoint namespaces. A fresh pool can be allocated at any time, together with a new token that governs it, thanks to the law $\text{True} \Rightarrow \exists p. \sharp_p^{\top}$.

²A *namespace* A, N is a string. A *mask* \mathcal{E}, \mathcal{F} is a set of such strings. If N is a namespace, then its *upward closure* $\uparrow N$, a mask, is the set of all strings that admit N as a prefix. The *full mask* \top is the set of all strings. We write $\mathcal{E}_1 \# \mathcal{E}_2$ when the masks \mathcal{E}_1 and \mathcal{E}_2 are disjoint. We say that two namespaces N_1 and N_2 are disjoint when $\uparrow N_1 \# \uparrow N_2$ holds.

The *later* modality \triangleright weakens an assertion. Roughly, the assertion $\triangleright P$ means that the assertion P will hold in the next time step, that is, after the next atomic instruction is executed. This modality appears in the reasoning rules for invariants, where it serves to forbid certain logical paradoxes. Our claim that opening an invariant produces I and closing it consumes I was another white lie: these operations actually produce and consume $\triangleright I$. This is visible in some of our reasoning rules, such as **PIGGYBANK-BREAK** (Figure 2), but can otherwise be ignored.

Hoare triples. A specification traditionally takes the form $\{P\} e \{\phi\}$, where the precondition P is an assertion about the initial state, the expression e is the program fragment of interest, and the postcondition ϕ describes the result value and the final state: if v is the result value then ϕv is an assertion about the final state. We use the sugared form $\{P\} e \text{ returns } (\exists \vec{x}) v \{Q\}$ as a short-hand for $\{P\} e \{\lambda v'. \exists \vec{x}. \lceil v' = v \rceil * Q\}$. This can be read as follows: “provided the initial state satisfies P , then e does not crash, and if it terminates, then, for some \vec{x} , it returns the value v , and the final state satisfies Q ”. A triple is persistent: it allows the expression e to be executed as many times as one wishes. We occasionally need a *one-shot triple*, written $\mathbf{1} \{P\} e \text{ returns } (\exists \vec{x}) v \{Q\}$. Its meaning is the same as that of a persistent triple, except that it allows e to be executed at most once. It is an affine assertion. An ordinary triple is a one-shot triple wrapped in a persistence modality \square .

Time credits. Iris^{\$} [Mével et al. 2019] extends Iris with *time credits*. The assertion $\$n$ represents n time credits. It is affine: time credits can be discarded but not duplicated. The reasoning rules of the logic ensure that every instruction consumes one time credit. As a result, if the triple $\{\$n\} e \{\phi\}$ holds, where e is a *closed* expression (a complete program), then e does not crash and *must terminate in at most n steps*. In other words, the logic offers a worst-case time complexity guarantee.

In general, a specification provides a worst-case *amortized* time complexity guarantee. For instance, **THUNK-FORCE** (Figure 6) does *not* guarantee that *force* t runs in at most \underline{F} steps. Although only \underline{F} time credits are ostensibly visible in the precondition, the assertion *Thunk* $p \mathcal{F} t \ 0 \ R \ \phi$, which is also part of the precondition, offers access to an invariant which possibly contains more credits. Thus, this specification means that the *amortized* time complexity of *force* is \underline{F} .

Abstract literal constants, such as \underline{N} and \underline{F} , hide concrete numeric constants. For instance, \underline{N} , the cost of creating a new thunk, is 3, while \underline{F} , the cost of forcing a thunk, is 11. In our Coq proofs, these literal constants are defined at the top level and are made opaque as soon as possible. In the paper, their definitions are omitted. Every literal constant is denoted by an underlined capital letter.

3 PIGGY BANKS

Once upon a time, in a faraway university, a class of students wanted to throw a big party. Alas, food, drinks, disguises, and other equipment were then and there very expensive. So, the students’ first action was to install in the classrooms, in the students’ lounge, in the dormitories, and in several other locations, a number of porcelain piggy banks. The students declared that everyone could contribute whatever amount he or she desired, in whatever location and at whatever time he or she desired. They agreed that, once the total accumulated amount reached a hundred sovereigns, they would break all piggy banks and throw a big party.

Alas, because one could not see through a piggy bank, one could not tell how much money was inside it. And because piggy banks were installed in many places, there was no coordination between contributors. No student could be reliably informed of all contributions, and there was no way of maintaining a registry of all contributions. Faced with these difficulties, the students adopted a habit of telling each other how much money they thought remained to be collected. One morning, in the students’ lounge, Charles was told by Brian, “97 to go”. There, Charles put one sovereign into the piggy bank. As he exited the room, he ran into Sophie and Sara, whom he told,

“96 to go”. Later on during that day, at different times and in different places, Sophie and Sara each contributed one sovereign. In the evening, each of them independently told Brian, “95 to go”.

When the students finally determined that the piggy banks could safely be broken, they found that they had accumulated much more than a hundred sovereigns. It was a big party.

This fable is intended to suggest that, independently of physical mechanisms such as a distributed piggy bank in a university or a thunk in a computer’s memory, there is a sound and useful pattern of logical reasoning about credit that is accumulated via uncoordinated payments. This pattern involves the concepts of *true debit*, or “how much really is still missing”, *apparent debit*, or “how much Sophie thinks is still missing”, and the property that an apparent debit is always an over-approximation of the true debit.

It seems desirable to isolate this pattern and to establish its logical soundness independently of any physical mechanism. To do so, inside Iris, we develop the *piggy bank*, a ghost data structure, and we equip it with an API that supports the desired reasoning rules. There is no code: a piggy bank is a purely logical concept. Our construction of thunks (§4.2.1, §4.2.2) uses piggy banks at two distinct levels and can cause an unbounded number of piggy banks to be associated with a single thunk. This suggests that it is worthwhile to make piggy banks a stand-alone abstraction.

3.1 Piggy Banks: Interface

A piggy bank can be abstractly described as a ghost data structure that is in one of two states (either it is pending, or it is forced) and whose transition from the pending state to the forced state has a certain cost (that is, the transition requires a certain number of time credits).

There is no need for concrete descriptions of the pending state and of the forced state. We assume that these states are described by two parameters $P : \mathbb{N} \rightarrow iProp$ and $Q : iProp$, where $iProp$ is the type of Iris assertions. The assertion $P \text{ } nc$ means that the piggy bank is in the pending state and that nc , standing for “necessary credits”, is the number of credits that we aim to accumulate before transitioning to the forced state. The assertion Q means that the piggy bank is in the forced state.

We want a piggy bank to be shared between several participants, so it must be described by a persistent predicate, *PiggyBank*. Participants must be allowed to pay, that is, to insert time credits into the piggy bank. This is a ghost operation. Each participant must be able to pay independently, without coordinating with other participants, so, as suggested by the fable, the *PiggyBank* assertion must keep track of an apparent debit, that is, a nonnegative number of debits, n . Once a participant sees an apparent debit of zero, we want this participant to be able to deduce that enough credit has been accumulated to allow the transition to take place. We want this participant to be allowed to *break* (or *force*) the bank and either perform the transition, or discover that the transition has been performed already by another participant.

Although paying and breaking the bank are ghost operations, these two operations have rather different characteristics. We wish to think of paying as an atomic update of the ghost state of the piggy bank; and we would like paying to be permitted at all times. The act of breaking the bank, on the other hand, cannot be regarded as atomic. A participant who breaks the bank and finds it in the pending state is expected to perform a transition to the forced state, that is, to update the physical state from $P \text{ } nc$ to Q . This can require many steps of computation. For instance, forcing a thunk requires calling a user-supplied function and updating the physical state of the thunk. While this computation is ongoing, the piggy bank is not in a valid state: neither $P \text{ } nc$ nor Q holds. So, while the piggy bank is being forced, one must forbid any attempt to force it again. These considerations suggest that breaking the bank must be viewed as a sequence of two ghost updates: an update that causes a transition from the pending state to a transient state, and an update that causes a transition from this transient state to the forced state.

$$\begin{array}{c}
\text{PIGGYBANK-PERSIST} \\
\text{persistent}(\text{PiggyBank } P \ Q \ A \ p \ N \ n)
\end{array}
\qquad
\begin{array}{c}
\text{PIGGYBANK-INCREASE-DEBIT} \\
\frac{n_1 \leq n_2}{\text{PiggyBank } P \ Q \ A \ p \ N \ n_1 \ -*} \\
\text{PiggyBank } P \ Q \ A \ p \ N \ n_2
\end{array}$$

$$\begin{array}{c}
\text{PIGGYBANK-CREATE} \\
P \ n \Rightarrow_{\mathcal{E}} \text{PiggyBank } P \ Q \ A \ p \ N \ n
\end{array}
\qquad
\begin{array}{c}
\text{PIGGYBANK-PAY} \\
\frac{\uparrow A \subseteq \mathcal{E}}{\text{PiggyBank } P \ Q \ A \ p \ N \ n \ * \ \$k \Rightarrow_{\mathcal{E}}} \\
\text{PiggyBank } P \ Q \ A \ p \ N \ (n - k)
\end{array}$$

$$\begin{array}{c}
\text{PIGGYBANK-BREAK} \\
\frac{\uparrow A \subseteq \mathcal{E} \quad \uparrow N \subseteq \mathcal{E} \quad \uparrow N \subseteq \mathcal{F}}{\text{PiggyBank } P \ Q \ A \ p \ N \ 0 \ * \ \xi_p^{\mathcal{F}} \Rightarrow_{\mathcal{E}}} \\
\exists nc. \left(\begin{array}{l} ((\triangleright P \ nc \ * \ \$nc) \vee \triangleright Q) \ * \\ (\triangleright Q \Rightarrow_{\mathcal{E}} \xi_p^{\mathcal{F}}) \end{array} \right)
\end{array}
\qquad
\begin{array}{c}
\text{PIGGYBANK-PEEK} \\
\frac{\uparrow A \subseteq \mathcal{E} \quad \uparrow N \subseteq \mathcal{E} \quad \uparrow N \subseteq \mathcal{F}}{\text{PiggyBank } P \ Q \ A \ p \ N \ n \ * \ \xi_p^{\mathcal{F}} \ -*} \\
(\forall nc, \triangleright P \ nc \ -* \triangleright \text{False}) \ -* \\
(\triangleright Q \ -* \triangleright \square Q') \Rightarrow_{\mathcal{E}} \\
\text{PiggyBank } P \ Q \ A \ p \ N \ 0 \ * \ \triangleright \square Q' \ * \ \xi_p^{\mathcal{F}}
\end{array}$$

Fig. 2. Piggy Banks: Reasoning Rules

These considerations suggest that the implementation of the piggy bank should involve both an atomic invariant and a non-atomic invariant (§2). This, in turn, suggests that the predicate *PiggyBank* should be parameterized with a namespace A (serving as an index for the atomic invariant) and with a pool p and a namespace N (serving as indices for the non-atomic invariant). Together, the parameters A, p, N can be thought of as a “region” in which the piggy bank exists.

Our reasoning rules for piggy banks appear in Figure 2. The assertion $\text{PiggyBank } P \ Q \ A \ p \ N \ n$ means that there exists a piggy bank whose pending and forced states are described by P and Q , whose region is A, p, N , and whose number of debits is n . The parameter n is the most interesting one: in the rules of Figure 2, the five other parameters are fixed.

The rule **PIGGYBANK-PERSIST** states that a *PiggyBank* assertion is persistent. That is, a piggy bank can be shared. **PIGGYBANK-INCREASE-DEBIT** states that *PiggyBank* is covariant in the parameter n . In other words, it is safe to increase an apparent debit. This rule is intuitively sound because it preserves the fact that an apparent debit is an over-approximation of the true debit. **PIGGYBANK-CREATE** allocates a new piggy bank. It is a ghost update. The piggy bank must initially be in its pending state: the user must establish the assertion $P \ nc$, which is consumed. The user chooses nc , the number of credits that must be accumulated before the piggy bank can be broken. Thus, nc is the initial value of the true debit, and it is also the initial apparent debit. **PIGGYBANK-PAY**, also a ghost update, allows contributing k time credits to a piggy bank. The apparent debit decreases from n to $n - k$. (This is subtraction in the natural numbers, so $n - k \geq 0$ holds.)

We now come to the most complex rule, **PIGGYBANK-BREAK**. This rule allows the user to break a piggy bank whose apparent debit is 0. This is intuitively permitted because, if the apparent debit is 0, then the true debit must be 0 as well. As explained earlier, this rule is expressed via two nested ghost updates. The outermost update initiates the process of breaking the bank. It consumes the affine token $\xi_p^{\mathcal{F}}$, where $\uparrow N \subseteq \mathcal{F}$ must hold: this forbids an attempt to break this piggy bank again while it is already being broken. It produces the following situation: for some value of nc , both of the following assertions hold:

PiggyBank $P Q A p N n \triangleq$

$\exists \varphi, \pi, nc.$

$$\boxed{\exists \text{forced}. \varphi \mapsto \bullet \text{forced}} * \text{if } \neg \text{forced} \text{ then } P \text{ nc else } Q \boxed{N}_p *$$

$$\boxed{\exists \text{forced}, ac. \varphi \mapsto \circ \text{forced}} * \boxed{\pi \mapsto \bullet ac} * \text{if } \neg \text{forced} \text{ then } \$ac \text{ else } \ulcorner nc \leq ac \urcorner^A *$$

$$\boxed{\pi \mapsto \circ (nc - n)}$$

Fig. 3. Piggy Banks: Internal Definition

- (1) either the piggy bank is in its pending state $P \text{ nc}$, in which case nc time credits are available (because the true debit is zero), or the piggy bank is already in its forced state Q ;
- (2) whatever state the piggy bank is currently in, the user must bring it into the forced state Q so as to be able to apply the innermost ghost update, which ends the process of breaking the bank and causes the affine token ℓ_p^F to re-appear.

The variable nc is existentially quantified because the cost of moving from the pending state to the forced state is unknown: it cannot be deduced from the *PiggyBank* assertion. The fact that this variable is shared between the conjuncts $P \text{ nc}$ and $\$nc$ guarantees that “enough” credit is available.

Whereas forcing requires an affine token (which disappears while forcing is in progress, and re-appears when the process is complete), paying does not require a token. Therefore, while a bank is being forced, forcing it again is disallowed, but paying remains permitted.

In the interest of space, we explain **PIGGYBANK-PEEK** only briefly. This rule states that if the user is somehow able to prove that this piggy bank cannot be in its pending state (that is, $P \text{ nc}$ implies false), then it must be in its forced state and the piggy bank’s apparent debit can be set to 0. This rule is later exploited to establish the rule **THUNKVAL-FORCE**.

3.2 Piggy Banks: Construction

The definition of the predicate *PiggyBank* appears in Figure 3. It may be of interest mainly to readers who are familiar with Iris; other readers may wish to skip this part. Its most interesting aspect is that it involves both an atomic invariant and a non-atomic invariant. This follows from the fact that we want paying to be atomic, a single ghost update, whereas breaking the bank must be non-atomic, a sequence of two ghost updates. The atomic invariant holds “always”: it can be violated and must be restored during an atomic instruction. The non-atomic invariant holds “except while the piggy bank is being broken”: thus, it can remain violated over a long period of time.

The two invariants are not independent of one another: they must agree on the question of whether an attempt to break the piggy bank has begun already. We impose this agreement by letting the two invariants share a ghost cell φ whose content, a Boolean value *forced*, reflects this information. The invariants cannot directly share the variable *forced*: that would make *forced* itself invariant. Instead, they share the address φ of a ghost cell whose content can change over time.

For this purpose, we use the `excl_auth` camera from the Iris library. This camera offers a way of expressing the idea that a resource has exactly two owners, whose roles are symmetric. Thus, two assertions control the ghost cell φ : the assertion $\boxed{\varphi \mapsto \bullet \text{forced}}_1$ represents the view of one owner; the assertion $\boxed{\varphi \mapsto \circ \text{forced}}_2$ is the view of the other owner. These assertions satisfy the agreement law $\boxed{\varphi \mapsto \bullet \text{forced}}_1 * \boxed{\varphi \mapsto \circ \text{forced}}_2 \vdash \ulcorner \text{forced}_1 = \text{forced}_2 \urcorner$, which states that when the owners confront their views, they must find that they agree. They also satisfy the update law $\boxed{\varphi \mapsto \bullet \text{forced}}_1 * \boxed{\varphi \mapsto \circ \text{forced}}_2 \Rightarrow \boxed{\varphi \mapsto \bullet \text{forced}}'_1 * \boxed{\varphi \mapsto \circ \text{forced}}'_2$, which states that when the owners combine their powers, they are able to change the content of the ghost cell.

```

1 type 'a state = UNEVALUATED of (unit -> 'a) | EVALUATED of 'a
2 type 'a thunk = 'a state ref
3 let create f = ref (UNEVALUATED f)
4 let force t =
5   match !t with
6   | UNEVALUATED f -> let v = f() in t := EVALUATED v; v (* evaluate and memoize *)
7   | EVALUATED v -> v (* look up memoized value *)

```

Fig. 4. Thunks: OCaml Code

At this point, we can explain the first invariant in the definition of *PiggyBank* (Figure 3). It is the non-atomic invariant. It states that if the piggy bank has never been broken then it must be in the pending state $P\ nc$, otherwise it must be in the forced state Q . While the piggy bank is being broken, this invariant does not hold: the piggy bank is then in neither state.

Another ghost cell, π , appears in the following two lines. This cell keeps track of the total amount of the payments that the piggy bank has received. This amount grows in a monotonic manner: it can never decrease. Two kinds of assertions control this cell. The affine assertion $\{\pi \mapsto \bullet ac\}$ represents the authority to read the cell and to increase its value. A persistent assertion $\{\pi \mapsto \circ k\}$ is a guarantee that the value of the cell is at least k . These assertions satisfy the agreement law $\{\pi \mapsto \bullet ac\} * \{\pi \mapsto \circ k\} \vdash \ulcorner k \leq ac \urcorner$ and the update law $\{\pi \mapsto \bullet ac\} \Rightarrow \{\pi \mapsto \bullet (ac + k)\} * \{\pi \mapsto \circ (ac + k)\}$.

We can now explain the second invariant in Figure 3. It is the atomic invariant. It holds the authoritative view $\{\pi \mapsto \bullet ac\}$, which guarantees that ac (for “available credit”) is the total amount of payment received so far. Furthermore, if the bank has never been broken yet, then this invariant guarantees that ac time credits are available. Otherwise, no credit is available: then, the invariant guarantees $nc \leq ac$, which means that the available credit has exceeded the necessary credit.

On the last line of Figure 3, we find a persistent witness $\{\pi \mapsto \circ (nc - n)\}$. By opening the atomic invariant and by exploiting the agreement law, this witness allows obtaining the inequality $nc - n \leq ac$. If the apparent debit n is zero, then one obtains $nc \leq ac$: that is, there is enough accumulated credit to cover the cost of the transition from the pending state to the forced state.

THEOREM 3.1. *The predicate *PiggyBank* satisfies the reasoning rules of Figure 2.*

4 THUNKS

Our implementation of thunks appears in Figure 4. In the following, we first present the reasoning rules that we wish to establish about thunks (§4.1). Then, we present the nontrivial construction that lets us obtain these rules (§4.2).

4.1 Thunks: Interface

The predicate *Thunk* $p\ \mathcal{F}\ t\ n\ R\ \phi$ describes a thunk at location t in memory. The pool p and the mask \mathcal{F} play the same role as in the previous section (§3): in short, they determine which token $\mathcal{F}_p^{\mathcal{F}}$ is required to force this thunk. The parameter n also plays the same role as in the previous section: it is an apparent debit associated with this thunk. The parameter R is a resource that is required and preserved by the suspended computation. The presence of this parameter allows us to describe thunks that have side effects and thunks whose execution requires a certain token. The latter category includes thunks that force other thunks, something that is commonly needed. The

$$\begin{array}{c}
\text{THUNK-CREATE} \\
\hline
\uparrow N \subseteq \mathcal{F} \\
\hline
\{\$N * \text{isAction } f \ n \ R \ \phi\} \\
\text{create } f \\
\text{returns } (\exists t) \ t \ \{\text{Thunk } p \ \mathcal{F} \ t \ n \ R \ \phi\}
\end{array}
\qquad
\begin{array}{c}
\text{THUNK-CONSEQUENCE} \\
\hline
\text{Thunk } p \ \mathcal{F} \ t \ n_1 \ R \ \phi \ -* \\
\text{isUpdate } n_2 \ R \ \phi \ \psi \ \Rightarrow_{\mathcal{E}} \\
\text{Thunk } p \ \mathcal{F} \ t \ (n_1 + n_2) \ R \ \psi
\end{array}$$

Fig. 5. Thunks: Creation Rule and Consequence Rule

$$\begin{array}{c}
\text{THUNK-PERSIST} \\
\text{persistent}(\text{Thunk } p \ \mathcal{F} \ t \ n \ R \ \phi)
\end{array}
\qquad
\begin{array}{c}
\text{THUNK-INCREASE-DEBIT} \\
\hline
n_1 \leq n_2 \\
\hline
\text{Thunk } p \ \mathcal{F} \ t \ n_1 \ R \ \phi \ -* \\
\text{Thunk } p \ \mathcal{F} \ t \ n_2 \ R \ \phi
\end{array}
\qquad
\begin{array}{c}
\text{THUNK-PAY} \\
\hline
\uparrow \text{ThunkPayment} \subseteq \mathcal{E} \\
\hline
\text{Thunk } p \ \mathcal{F} \ t \ n \ R \ \phi \ * \ \$k \ \Rightarrow_{\mathcal{E}} \\
\text{Thunk } p \ \mathcal{F} \ t \ (n - k) \ R \ \phi
\end{array}$$

$$\begin{array}{c}
\text{THUNK-FORCE} \\
\left\{ \begin{array}{l} \text{Thunk } p \ \mathcal{F} \ t \ 0 \ R \ \phi \ * \\ \$F * \mathcal{F}_p * R \end{array} \right\} \\
\text{force } t \\
\text{returns } (\exists v) \ v \ \{\text{ThunkVal } t \ v \ * \ \square \ \phi \ v \ * \ \mathcal{F}_p * R\}
\end{array}$$

Fig. 6. Thunks: Common Reasoning Rules

$$\begin{array}{c}
\text{THUNKVAL-PERSIST} \\
\text{persistent}(\text{ThunkVal } t \ v)
\end{array}
\qquad
\begin{array}{c}
\text{THUNKVAL-TIMELESS} \\
\text{timeless}(\text{ThunkVal } t \ v)
\end{array}$$

$$\begin{array}{c}
\text{THUNKVAL-CONFRONT} \\
\text{ThunkVal } t \ v_1 \ * \ \text{ThunkVal } t \ v_2 \ \vdash \ulcorner v_1 = v_2 \urcorner
\end{array}
\qquad
\begin{array}{c}
\text{THUNKVAL-FORCE} \\
\{\text{ThunkVal } t \ v \ * \ \$F\} \text{ force } t \ \text{returns } v \ \{\}
\end{array}$$

Fig. 7. Forced-Thunk Witnesses: Reasoning Rules

parameter $\phi : \text{Val} \rightarrow \text{iProp}$ determines the postcondition of the thunk: it is $\square \phi$. That is, once this thunk is forced and produces a value v , the assertion $\square \phi \ v$ can be expected to hold.³

The full set of reasoning rules for thunks appears in Figures 5, 6, and 7. The rules are split in three groups for reasons that will be apparent in the next subsection (§4.2).

THUNK-CREATE (Figure 5) describes the creation of a new thunk via the function call $\text{create } f$. The behavior of f is specified by the premise $\text{isAction } f \ n \ R \ \phi$, which denotes the one-shot triple $\mathbf{1} \ \{R * \$n\} \ f() \ \text{returns } (\exists v) \ v \ \{R * \square \phi \ v\}$. This assertion is a permission to call $f()$ at most once. It indicates that the call $f()$ consumes n time credits and must return a value v such that $\square \phi \ v$ holds. The resource R is required, but not consumed, by this call. Under this hypothesis on f , **THUNK-CREATE** states that $\text{create } f$ costs a constant amount of credits $\$N$ and returns a thunk whose apparent debit, resource requirement, and postcondition are described by n, R, ϕ . The amount N is part of the thunks interface; its concrete value is irrelevant and is not exposed: from the point of view of the client it simply represents an abstract integer. The pool p and mask \mathcal{F} are

³Instead of requiring the postcondition to be in the syntactic form $\square \phi$, we could equivalently allow an arbitrary *persistent* postcondition. The postcondition of a thunk must be persistent because a thunk can be forced arbitrarily many times yet always returns the same value.

chosen by the user. These parameters determine which token $\mathcal{F}_p^{\mathcal{F}}$ will be required when forcing this thunk. A systematic way of instantiating these parameters is discussed in the next section (§5).

The rules **THUNK-PERSIST**, **THUNK-INCREASE-DEBIT**, and **THUNK-PAY** (Figure 6) are analogous to **PIGGYBANK-PERSIST**, **PIGGYBANK-INCREASE-DEBIT**, and **PIGGYBANK-PAY**. They state that thunks can be shared, that it is permitted to over-approximate an apparent debit, and that an apparent debit can be reduced by paying. (In **THUNK-PAY**, one can see that the parameter A of piggy banks has been instantiated with a fixed namespace *ThunkPayment*.)

THUNK-FORCE allows forcing a thunk whose apparent debit is zero. This consumes $\$F$, a constant number of time credits. In other words, the amortized time complexity of this operation is $O(1)$, because the cost of the suspended computation has been paid for in advance. The token $\mathcal{F}_p^{\mathcal{F}}$ and the resource R are required and preserved. The token $\mathcal{F}_p^{\mathcal{F}}$ is required to force the thunk itself, whereas the token R is required by the suspended computation. These two assertions are *separately* required: that is, they cannot be the same token. Indeed, as will be evident in the next subsection (§4.2), the process of breaking the thunk’s piggy bank begins (therefore, the token $\mathcal{F}_p^{\mathcal{F}}$ disappears) before the suspended computation is executed, and ends after the suspended computation terminates.

Forcing a thunk produces a value v such that the persistent assertions $\text{ThunkVal } t \ v$ and $\Box \phi \ v$ hold. The assertion $\text{ThunkVal } t \ v$ is a witness that the value of the thunk t has been forever decided and that it is v . The assertion $\Box \phi \ v$ means that $\phi \ v$ holds now and forever and can be exploited as many times as one wishes.

The predicate ThunkVal satisfies the reasoning rules in Figure 7. The rule **THUNKVAL-PERSIST** reflects the fact that once the association between t and v has been decided, it remains fixed forever. The rule **THUNKVAL-TIMELESS** states that $\triangleright \text{ThunkVal } t \ v$ is essentially the same as $\text{ThunkVal } t \ v$; this is of technical interest only. The agreement law **THUNKVAL-CONFRONT** states that if a thunk has been forced twice in the past then the same value must have been returned twice. Finally, **THUNKVAL-FORCE** allows forcing a thunk that has been forced already. This assumption is reflected by the appearance of the assertion $\text{ThunkVal } t \ v$ in the precondition. There is no requirement that the thunk’s apparent debit be zero. As in **THUNK-FORCE**, forcing consumes $\$F$. The value that is obtained by forcing this thunk must be v , the value that was predicted by the witness $\text{ThunkVal } t \ v$. Unlike **THUNK-FORCE**, this rule requires neither the token $\mathcal{F}_p^{\mathcal{F}}$ nor the resource R . They are not necessary because no suspended computation is executed. Also unlike **THUNK-FORCE**, and perhaps surprisingly, this rule does not guarantee $\Box \phi \ v$. In the presence of **THUNK-CONSEQUENCE**, this cannot be guaranteed. In short, the assumption $\text{ThunkVal } t \ v$ guarantees that this physical thunk has been forced already; but it could be wrapped in a number of (ghost) proxy thunks (§4.2.2) that have not been forced yet.

The rule **THUNK-CONSEQUENCE** (Figure 5) allows changing the postcondition of a thunk from $\Box \phi$ to $\Box \psi$. In the special case where n_2 is zero, this rule weakens the postcondition of a thunk, which is why we name it the *consequence rule*. In the case where n_2 is nonzero, this rule *increases* the apparent debit of the thunk from n_1 to $n_1 + n_2$. In return, the update⁴ from $\Box \phi \ v$ to $\Box \psi \ v$ is allowed to consume n_2 time credits.

4.2 Thunks: Construction

It is not easy to define the predicates Thunk and ThunkVal in such a way that all of the rules of Figures 5, 6, and 7 are satisfied. A key contribution of this paper is to propose a definition of

⁴ We write $\text{isUpdate } n \ R \ \phi \ \psi$ for the assertion $\forall v. (R * \$n * \Box \phi \ v) \Rightarrow_{\top} (R * \Box \psi \ v)$. This update is affine; it can be used only once. It consumes n time credits, requires $\Box \phi \ v$, and establishes $\Box \psi \ v$. The resource R is required, but not consumed. The full mask \top allows this update to access all atomic invariants. In particular, **THUNK-PAY** can be exploited.

$$\begin{aligned}
& \text{BasicThunk } p \mathcal{F} t n R \phi \triangleq \\
& \quad \exists \delta, N. \ulcorner \uparrow N \subseteq \mathcal{F} \urcorner * t \rightsquigarrow \delta * \text{PiggyBank} \\
& \quad (\lambda nc. \exists f. \boxed{\delta \mapsto ?} * t \mapsto \text{UNEVALUATED } f * \text{isAction } f \text{ nc } R \phi) \quad \text{— the pending state} \\
& \quad (\exists v. \boxed{\delta \mapsto v} * t \mapsto \text{EVALUATED } v * \Box \phi v) \quad \text{— the forced state} \\
& \quad \text{ThunkPayment } p N n \\
& \text{ThunkVal } t v \triangleq \\
& \quad \exists \delta. t \rightsquigarrow \delta * \boxed{\delta \mapsto v}
\end{aligned}$$

Fig. 8. Basic Thunks and Forced-Thunk Witnesses: Definitions

Thunk that validates all of the desired rules. Although it is technically possible to give a monolithic definition, we prefer to approach the problem in three stages, as follows.

- (1) We define a predicate *BasicThunk* that satisfies all of the desired rules except the consequence rule. It is analogous to Mével et al.’s *isThunk*, but instead of relying directly on a single non-atomic invariant, it is built on top of our “piggy bank” abstraction, which combines an atomic invariant and a non-atomic invariant. As a result, *BasicThunk* validates **THUNK-PAY**.
- (2) We remark that applying the reasoning rule **THUNK-CONSEQUENCE** to an existing thunk t seems closely related to constructing a new thunk t' via the expression $\text{create } (\lambda(). \text{force } t)$. Although applying the consequence rule is a ghost operation and does not create a new thunk at runtime, this analogy suggests that *applying the consequence rule should allocate a new piggy bank*. Guided by this idea, we propose a construction that supports *one* application of the consequence rule. Assuming that we have a predicate *Thunk* that satisfies the rules of Figure 6, we construct a new predicate *ProxyThunk*, which also satisfies these rules, and we establish a version of the consequence rule that expects a *Thunk* and produces a *ProxyThunk*.
- (3) It is then a relatively simple exercise to prove that this construction can be iterated as many times as desired. By building on top of *BasicThunk* and *ProxyThunk*, we are able to propose a definition of *Thunk* that satisfies all of the desired rules, including **THUNK-CONSEQUENCE**.

This three-stage construction is presented in the next three subsections (§4.2.1, §4.2.2, §4.2.3). We remark that the definition of the predicate *ThunkVal* is not problematic. We give a definition of *ThunkVal* in the first stage (§4.2.1) and keep this definition in the following stages.

4.2.1 Basic Thunks. The definition of the predicate *BasicThunk* appears in Figure 8. Although this definition may at first sight seem somewhat cryptic, it is actually fairly straightforward. It involves two main ingredients: a ghost cell δ and a piggy bank.

The ghost cell δ records whether the value of this thunk is still undecided or decided. This ghost cell inhabits the camera $\text{Ex}(\cdot) +_z \text{AG}(\text{Val})$, also known as the “one-shot” camera [Jung et al. 2018, §2.1]. This gives rise to the following assertions and laws. The assertion $\boxed{\delta \mapsto ?}$ means that the value is not decided yet. This assertion is affine: it represents a unique permission to make a decision. The assertion $\boxed{\delta \mapsto v}$ means that the value has been decided and that this value is v . This assertion is persistent: once a value has been decided, this decision cannot be undone, so the information that the value is v remains valid forever and can be shared. These assertions satisfy the decision law $\boxed{\delta \mapsto ?} \Rightarrow \boxed{\delta \mapsto v}$, the agreement law $\boxed{\delta \mapsto v_1} * \boxed{\delta \mapsto v_2} \vdash \ulcorner v_1 = v_2 \urcorner$, and the disagreement law $\boxed{\delta \mapsto ?} * \boxed{\delta \mapsto v} \vdash \text{False}$. A meta witness $t \rightsquigarrow \delta$ records that the ghost cell δ is uniquely associated with the thunk t . This ensures that all *BasicThunk* and *ThunkVal* assertions for the thunk t refer to the same ghost cell δ .

$$\begin{array}{l}
\text{ProxyThunk } p \mathcal{F} t n R \psi \triangleq \\
\exists n_1, n_2, \phi, \mathcal{F}_1, N. \quad \lceil \mathcal{F}_1 \uplus \uparrow N \subseteq \mathcal{F} \rceil * \\
\text{Thunk } p \mathcal{F}_1 t n_1 R \phi * \\
\text{PiggyBank} \\
(\lambda nc. \lceil nc = n_1 + n_2 \rceil * \text{isUpdate } n_2 R \phi \psi) \\
(\exists v. \text{ThunkVal } t v * \square \psi v) \\
\text{ThunkPayment } p N n
\end{array}
\quad
\begin{array}{l}
\text{PROXY-CREATE} \\
\frac{\mathcal{F}_1 \uplus \uparrow N \subseteq \mathcal{F}}{\text{Thunk } p \mathcal{F}_1 t n_1 R \phi *} \\
\text{isUpdate } n_2 R \phi \psi \Rightarrow_{\varepsilon} \\
\text{ProxyThunk } p \mathcal{F} t (n_1 + n_2) R \psi
\end{array}$$

Fig. 9. Proxy Thunks: Definition and Creation Rule

The concept of a piggy bank has been presented already (§3). There remains to explain how the parameters P and Q , which represent the pending and forced states of the piggy bank, are instantiated in Figure 8. In the pending state, the ghost cell δ is undecided; the physical cell t contains the value *UNEVALUATED* f ; and there exists a unique permission to invoke $f()$. The cost of this invocation, nc , is not known, but the piggy bank is set up so that this cost must be fully paid for before the piggy bank can be forced. The apparent debit n of the piggy bank is also the apparent debit of the thunk. In the forced state, the ghost cell δ has been set to v , for some value v ; the physical memory cell t contains the value *EVALUATED* v ; and the postcondition $\square \phi v$ is satisfied.

THEOREM 4.1. *The predicate BasicThunk satisfies the rule THUNK-CREATE in Figure 5, where Thunk is replaced with BasicThunk. Furthermore, it satisfies all of the rules in Figure 6, where the same replacement is made. Finally, the predicate ThunkVal satisfies the rules in Figure 7.*

4.2.2 Proxy Thunks. Alas, basic thunks do not satisfy the consequence rule. The problem can be traced back to the piggy bank invariants, which fix the postcondition ϕ and the number of necessary credits nc . This forbids installing a new postcondition and a new number of necessary credits.

Fortunately, there is a simple way of working around this problem. The idea is to *allocate a new piggy bank* when the consequence rule is applied to an existing thunk t . If the existing thunk has an apparent debit of n_1 and if the update from ϕ to ψ has a cost of n_2 , then the number of time credits that the new piggy bank aims to collect is set to $n_1 + n_2$. Thus, the apparent debit of the new piggy bank is $n_1 + n_2$. Once the new piggy bank has reached its aim, breaking it produces $n_1 + n_2$ credits. Out of these, n_1 credits are used to force the thunk, producing a value v such that $\square \phi v$ holds. The remaining n_2 credits are then used to execute the ghost update and obtain $\square \psi v$.

In this subsection, for simplicity, we focus on *one* application of the consequence rule. We assume that we have a predicate *Thunk* that satisfies the rules of Figure 6. We refer to this set of rules as the “common thunk API”. We construct a new predicate *ProxyThunk*, which also satisfies the common thunk API. Its definition appears in Figure 9. The “creation rule” for proxy thunks, also shown in Figure 9, is a consequence rule that expects a *Thunk* and produces a *ProxyThunk*. The term “proxy thunk” is meant to suggest that a proxy thunk is a ghost wrapper around a pre-existing thunk.

The main components in the definition of proxy thunks are the underlying thunk, whose apparent debit is n_1 , and the proxy thunk’s piggy bank. The apparent debit n of the piggy bank is the apparent debit of the proxy thunk. The pending state of this piggy bank contains a one-shot ghost update from ϕ to ψ , whose cost is n_2 . The equation $nc = n_1 + n_2$ records the fact that this piggy bank aims to collect enough credit to force the underlying thunk and apply this update. The forced state contains just a forced-thunk witness *ThunkVal* $t v$ together with the postcondition $\square \psi v$.

$$\begin{aligned}
& \text{RecThunk } 0 \ p \ \mathcal{F} \ t \ n \ R \ \phi \triangleq \text{BasicThunk } p \ \mathcal{F} \ t \ n \ R \ \phi \\
& \text{RecThunk } (d + 1) \ p \ \mathcal{F} \ t \ n \ R \ \phi \triangleq \text{ProxyThunk } [\text{Thunk} := \text{RecThunk } d] \ p \ \mathcal{F} \ t \ n \ R \ \phi \\
& \text{Thunk } p \ \mathcal{F} \ t \ n \ R \ \phi \triangleq \exists N, d, \mathcal{F}'. \ulcorner \forall d'. d < d' \Rightarrow \mathcal{F}' \# \uparrow(N \cdot d') \urcorner * \\
& \quad \ulcorner \mathcal{F}' \subseteq \uparrow N \subseteq \mathcal{F} \urcorner * \\
& \quad \text{RecThunk } d \ p \ \mathcal{F}' \ t \ n \ R \ \phi
\end{aligned}$$

Fig. 10. Thunks: Definition

The side condition $\mathcal{F}_1 \uplus \uparrow N \subseteq \mathcal{F}$ guarantees that out of the token $\mathcal{F}_p^{\mathcal{F}}$, which the user supplies when forcing the proxy thunk, we can extract the tokens $\mathcal{F}_p^{\mathcal{F}_1} * \mathcal{F}_p^{\uparrow N}$, which are required in order to simultaneously break the proxy's piggy bank and force the underlying thunk.

THEOREM 4.2. *The predicate `ProxyThunk` satisfies the rule `PROXY-CREATE` in Figure 9. Furthermore, it satisfies all of the rules in Figure 6, where `Thunk` is replaced with `ProxyThunk`.*

4.2.3 Thunks. The construction of the previous subsection is heterogeneous and allows applying the consequence rule once: when applied to a thunk, it produces a proxy thunk. Fortunately, this construction is generic: it can be applied to an arbitrary predicate `Thunk`, provided this predicate is persistent and satisfies the common thunk API in Figure 6. Both `BasicThunk` and `ProxyThunk` meet these requirements. Thus, the construction can be iterated. We do so in Figure 10.

The definition is conceptually straightforward. First, we inductively define a predicate `RecThunk d`, which layers d proxy thunks on top of a base thunk. Then, we define the predicate `Thunk` via an existential quantification over d : that is, we say that a “thunk” is a basic thunk wrapped in an arbitrary number of proxy thunks. Two technical formulae involving masks record that (1) we have an infinite family of pairwise disjoint masks, namely $\uparrow(N \cdot d)$, where d is an integer index; and (2) after d levels of proxy thunks have been stacked above a basic thunk, the masks up to level d have been used up, but the masks above level d are still available for use.

THEOREM 4.3. *The predicate `Thunk` satisfies all of the rules in Figures 5 and 6.*

A new piggy bank is created at two different times: when a thunk is first created, and when the consequence rule is applied to an existing thunk. Thus, an arbitrary number of piggy banks can be simultaneously associated with a single thunk, and can be simultaneously active. Fortunately, in our proofs, this global view is never needed.

5 HEIGHT-INDEXED THUNKS

The predicate `Thunk` is quite general but can be a little difficult to use. When a thunk is forced, one must *separately* supply the token $\mathcal{F}_p^{\mathcal{F}}$, which allows forcing the thunk itself, and the resource R , which allows the suspended computation to have certain effects. When one wishes to construct a thunk that forces one or more other thunks, the parameter R must typically be instantiated with a token of the form $\mathcal{F}_p^{\mathcal{F}'}$ where \mathcal{F} and \mathcal{F}' are disjoint. In short, we have set up a token-based discipline that forbids reentrant thunks. This is good, but this discipline can be heavy and confusing.

In order to address this difficulty once and for all and to save the end user some pain, we set up a simple system based on natural integer *heights* h . We define a new predicate `HThunk p h t n φ` where the two parameters \mathcal{F} and R are replaced with a single parameter h . Our intent is to allow a thunk at height h to force thunks at lower heights, that is, at heights less than h . A thunk cannot force a thunk that lies at the same height as itself or higher. A thunk at height h can *construct* or *return* a thunk at an arbitrary height: no constraint relates the parameters h and ϕ .

$$\begin{array}{c}
\text{HTHUNK-PERSIST} \\
\text{persistent}(H\text{Thunk } p \ h \ t \ n \ \phi)
\end{array}
\qquad
\begin{array}{c}
\text{HTHUNK-CREATE} \\
\{\underline{\$N} * \text{isAction } f \ n \ (\zeta_p^h) \ \phi\} \\
\text{create } f \\
\text{returns } (\exists t) \ t \ \{H\text{Thunk } p \ h \ t \ n \ \phi\}
\end{array}$$

$$\begin{array}{c}
\text{HTHUNK-INC-HEIGHT-DEBIT} \\
\frac{h_1 \leq h_2 \quad n_1 \leq n_2}{H\text{Thunk } p \ h_1 \ t \ n_1 \ \phi * \\ H\text{Thunk } p \ h_2 \ t \ n_2 \ \phi}
\end{array}
\qquad
\begin{array}{c}
\text{HTHUNK-PAY} \\
\frac{\uparrow \text{ThunkPayment} \subseteq \mathcal{E}}{H\text{Thunk } p \ h \ t \ n \ \phi * \$k \Rightarrow_{\mathcal{E}} \\ H\text{Thunk } p \ h \ t \ (n - k) \ \phi}
\end{array}$$

$$\begin{array}{c}
\text{HTHUNK-CONSEQUENCE} \\
H\text{Thunk } p \ h \ t \ n_1 \ \phi * \\
(\forall v. \$n_2 * \square \phi \ v \Rightarrow_{\top} \square \psi \ v) \Rightarrow_{\mathcal{E}} \\
H\text{Thunk } p \ h \ t \ (n_1 + n_2) \ \psi
\end{array}
\qquad
\begin{array}{c}
\text{HTHUNK-FORCE} \\
\left\{ \begin{array}{l} H\text{Thunk } p \ h \ t \ 0 \ \phi * \\ \$F * \zeta_p^{h'} * \ulcorner h < h' \urcorner \end{array} \right\} \\
\text{force } t \\
\text{returns } (\exists v) \ v \ \{\square \phi \ v * \text{ThunkVal } t \ v * \zeta_p^{h'}\}
\end{array}$$

Fig. 11. Height-Indexed Thunks: Reasoning Rules

For simplicity, this API removes the ability for a suspended computation to have side effects other than forcing thunks: that is, the parameter R disappears. It could be preserved if desired.

For the sake of brevity, we omit the definition of the predicate $H\text{Thunk}$. Its reasoning rules appear in Figure 11. The affine token ζ_p^h allows forcing thunks whose height is less than h (**HTHUNK-FORCE**). When a thunk is created at height h , the token that is passed to the suspended computation is ζ_p^h (**HTHUNK-CREATE**). Thus, the new thunk can force thunks at lower heights only. We remark that a height is not a creation time. Indeed, a thunk at height 0 can be created after, and even created by, a thunk at height 1. Instead, a height represents the length of a dependency chain: a thunk at height 2 is a thunk that can force a thunk that can force a thunk. Heights can be safely over-approximated: this is stated by **HTHUNK-INC-HEIGHT-DEBIT**. In a token, h can be instantiated with ∞ . The token ζ_p^∞ can force thunks of arbitrary height. It appears in the API of the banker's queue (Figure 18).

6 STREAMS

A *stream* is a list whose elements are computed on demand and memoized. In lazy programming languages, such as Haskell, this data structure is referred to simply as a “list”. In a strict programming language, such as OCaml, lists and streams are distinct (albeit closely related) data structures. The definition of streams as an algebraic data type appears in the first two lines of Figure 1. In short, a *stream* s is a thunk, which, once forced, produces a cell; and a *cell* is either the value Nil or a value of the form $\text{Cons}(x, s')$, where x is an element and s' is again a stream. A stream can be thought of as a chain of thunks, where each thunk produces the next thunk in the chain.

In the following, we define a predicate $\text{Stream } p \ h \ s \ ds \ xs$, which describes a stream (§6.1); we establish several reasoning rules that this predicate satisfies (§6.2); and we establish specifications for a few common operations on streams (§6.3). We do not verify a full-fledged stream library; we verify only the operations needed by the banker's queue, which are shown in Figure 1.

6.1 The predicate *Stream*

The parameters p and h of the predicate Stream play the same role as the parameters p and h of the predicate $H\text{Thunk}$. They are a non-atomic pool p and an integer height h , and they indicate that the

$$\begin{aligned}
\text{Stream } p \ h \ s \ [] \ xs &\triangleq \text{False} \\
\text{Stream } p \ h \ s \ (d :: ds) \ xs &\triangleq \text{HThunk } p \ h \ s \ d \ (\lambda c. \text{StreamCell } p \ h \ c \ ds \ xs) \\
\text{StreamCell } p \ h \ c \ ds \ [] &\triangleq \ulcorner c = \text{Nil} \urcorner * \ulcorner ds = [] \urcorner \\
\text{StreamCell } p \ h \ c \ ds \ (x :: xs) &\triangleq \exists s. \ulcorner c = \text{Cons}(x, s) \urcorner * \text{Stream } p \ h \ s \ ds \ xs
\end{aligned}$$

Fig. 12. Streams: Definition

$$\begin{array}{c}
\text{STREAM-PERSIST} \\
\text{persistent}(\text{Stream } p \ h \ s \ ds \ xs) \\
\\
\text{STREAM-INCREASE-HEIGHT} \\
\frac{h_1 \leq h_2}{\text{Stream } p \ h_1 \ s \ ds \ xs \multimap \text{Stream } p \ h_2 \ s \ ds \ xs} \\
\\
\text{STREAM-FORWARD-DEBIT} \\
\frac{\uparrow \text{ThunkPayment} \subseteq \mathcal{E} \quad (m) \ ds_1 \leq ds_2 \ (n)}{\text{Stream } p \ h \ s \ ds_1 \ xs * \$m \Rightarrow_{\mathcal{E}} \text{Stream } p \ h \ s \ ds_2 \ xs} \\
\\
\text{STREAM-FORCE} \\
\left\{ \begin{array}{l} \text{Stream } p \ h \ s \ (0 :: ds) \ xs * \\ \$F' * \not\!z_p^{h'} * \ulcorner h < h' \urcorner \end{array} \right\} \text{force } s \\
\text{returns } (\exists c) \ c \left\{ \begin{array}{l} \text{StreamCell } p \ h \ c \ ds \ xs * \\ \text{ThunkVal } s \ c * \not\!z_p^{h'} \end{array} \right\} \\
\\
\text{STREAM-CREATE} \\
\{ \$N' * \text{isCellAction } p \ h \ d \ e \ ds \ xs \} \text{create } (\lambda(). e) \\
\text{returns } (\exists s) \ s \ \{ \text{Stream } p \ h \ s \ (d :: ds) \ xs \}
\end{array}$$

Fig. 13. Streams: Reasoning Rules

token $\not\!z_p^h$ is required in order to force every thunk in the stream. The parameter s is the stream itself; it is the location in memory of the thunk that represents the head of the stream. The parameter xs is the sequence of the elements of the stream. It predicts the shape of the value produced by each thunk in the stream, where a shape is either Nil or $\text{Cons}(x, _)$. The parameter ds is the sequence of debits associated with each thunk in the stream. It tells how much remains to be paid in order to force each thunk. It is worth noting that xs and ds predict the value and apparent cost of each thunk in the stream possibly *before* this thunk is even constructed in memory.

The definitions of the predicates Stream and StreamCell appear in Figure 12. They are mutually inductive. They are straightforward, so we do not paraphrase them. Because a stream of n elements involves $n + 1$ thunks, in an assertion $\text{Stream } p \ h \ s \ ds \ xs$, one can informally⁵ expect $|ds| = |xs| + 1$. In $\text{StreamCell } p \ h \ c \ ds \ xs$, one can informally expect $|ds| = |xs|$.

6.2 Reasoning Rules for Streams

Our reasoning rules for streams appear in Figure 13. Most of them are reformulations of the corresponding rules for height-indexed thunks (Figure 11), so we do not explain them again.

⁵Technically, $\text{Stream } p \ h \ s \ ds \ xs \vdash |ds| = |xs| + 1$ does *not* hold. A straightforward proof attempt fails, because the postcondition of a thunk does not hold until this thunk has been forced. One could strengthen the definition of Stream so that this entailment holds, but we have not felt the need to do so. The weaker entailment $\text{Stream } p \ h \ s \ ds \ xs \vdash |ds| > 0$ does hold and has been sufficient for our purposes.

$$\begin{array}{c}
\text{SUB-NIL} \\
\frac{n \leq m}{(m) [] \leq [] (n)} \\
\text{SUB-CONS} \\
\frac{d_1 \leq m + d_2 \quad (m + d_2 - d_1) ds_1 \leq ds_2 (n)}{(m) d_1 :: ds_1 \leq d_2 :: ds_2 (n)}
\end{array}$$

Fig. 14. Subsumption over Sequences of Debts: Definition

$$\begin{array}{c}
\text{SUB-VARIANCE} \\
\frac{(m) ds_1 \leq ds_2 (n) \quad m \leq m' \quad n' \leq n}{(m') ds_1 \leq ds_2 (n')} \\
\text{SUB-REFL} \\
(m) ds \leq ds (m) \\
\text{SUB-TRANS} \\
\frac{(m_1) ds_1 \leq ds_2 (n_1) \quad (m_2) ds_2 \leq ds_3 (n_2)}{(m_1 + m_2) ds_1 \leq ds_3 (n_1 + n_2)} \\
\text{SUB-APPEND} \\
\frac{(m) ds_1 \leq ds_2 (n) \quad (n) ds'_1 \leq ds'_2 (k)}{(m) ds_1 ++ ds'_1 \leq ds_2 ++ ds'_2 (k)} \\
\text{SUB-ADD-SLACK} \\
\frac{(m) ds_1 \leq ds_2 (n)}{(m + k) ds_1 \leq ds_2 (n + k)} \\
\text{SUB-REPEAT} \\
\frac{d_1 \leq d_2}{(0) d_1^n \leq d_2^n (n \times (d_2 - d_1))}
\end{array}$$

Fig. 15. Subsumption over Sequences of Debts: Properties

STREAM-FORCE requires the head thunk to have zero debts. **STREAM-CREATE** relies on the auxiliary predicate *isCellAction*⁶ in the same way that **THUNK-CREATE** and **HThunk-CREATE** rely on *isAction*.

The most notable rule in Figure 13 is **STREAM-FORWARD-DEBIT**. This rule allows managing a stream's debit in several ways. It allows paying (that is, consuming a number of time credits) so as to decrease the cost of a thunk, which can be either the head thunk or a deeper thunk. Furthermore, it allows moving debts from the right towards the left in the list ds . In other words, it allows transferring some of the debit of a faraway thunk to a thunk that lies nearer in the future. This is intuitively sound because this implies that one must pay earlier. Technically, the proof of soundness of **STREAM-FORWARD-DEBIT** relies on the consequence rule **HThunk-CONSEQUENCE**.

STREAM-FORWARD-DEBIT involves the *debit subsumption* judgement $(m) ds_1 \leq ds_2 (n)$, whose intuitive meaning is as follows: provided one pays m time credits *now*, it is safe to transform the sequence ds_1 into the sequence ds_2 , and this results in n leftover time credits *in the future*, after the thunks described by the lists ds_1 and ds_2 have been forced.

The presence of the parameter n in this judgement may seem surprising, especially since the n leftover credits are unused (wasted) by **STREAM-FORWARD-DEBIT**. Still, this parameter is useful because it enables compositional proofs of subsumption; this is most visible in **SUB-APPEND** (Figure 15).

An inductive definition of the subsumption judgement appears in Figure 14. In **SUB-CONS**, it may be the case that d_1 is greater than d_2 . In this case, the premise $d_1 \leq m + d_2$ allows part of the m time credits at hand to be spent on the first thunk, *decreasing* its apparent cost from d_1 to d_2 . It may also be the case that d_1 is less than or equal to d_2 . In that case, the apparent cost of the first thunk is *increased*, causing *more than* m time credits to become available for spending on the thunks that follow. In either case, the number of credits that can be spent on the tail of the stream is $(m + d_2) - d_1$, which is why this number appears in the second premise of **SUB-CONS**.

To a reader who has difficulty understanding this definition, we may propose an alternative characterization of the subsumption judgement, which helps see why **STREAM-FORWARD-DEBIT** is sound. Intuitively, for this rule to be sound, it must be the case that, by applying this rule, one

⁶ We write $\text{isCellAction } p \ h \ d \ e \ ds \ xs$ for $\mathbf{1} \{ \mathcal{I}_p^h * \$d \} e$ returns $(\exists c) c \{ \text{StreamCell } p \ h \ c \ ds \ xs * \mathcal{I}_p^h \}$. This assertion is a permission to execute the expression e at most once. It indicates that e may consume d time credits and must return a stream cell c such that $\text{StreamCell } p \ h \ c \ ds \ xs$ holds. The resource \mathcal{I}_p^h may be used and must be preserved.

$$\begin{array}{c}
\text{STREAM-REVL} \\
\left\{ \begin{array}{l} \text{List } l \text{ } xs * \\ \$R' * \ulcorner n = |xs| \urcorner \end{array} \right\} \\
\text{revl } l \\
\text{returns } (\exists s) s \left\{ \begin{array}{l} \text{Stream } p \text{ } h \text{ } s \\ (\underline{R}n :: 0^n) (\text{rev } xs) \end{array} \right\}
\end{array}
\qquad
\begin{array}{c}
\text{STREAM-APPEND} \\
\left\{ \begin{array}{l} \text{Stream } p \text{ } h \text{ } s_1 \text{ } ds_1 \text{ } xs_1 * \\ \text{Stream } p \text{ } h \text{ } s_2 \text{ } ds_2 \text{ } xs_2 * \$P \end{array} \right\} \\
\text{append } s_1 \text{ } s_2 \\
\text{returns } (\exists s) s \left\{ \begin{array}{l} \text{Stream } p \text{ } (h + 1) \text{ } s \\ (ds_1 \bowtie ds_2) (xs_1 ++ xs_2) \end{array} \right\}
\end{array}$$

Fig. 16. Streams: Specifications of *revl* and *append*

promises to pay no less and to pay no later. Thus, for every index i , it must be the case that forcing the first i thunks in the stream appears no less expensive after the rule is applied than it did before the rule was applied. The subsumption judgement indeed satisfies a property of this kind: it is expressed by the following lemma.

LEMMA 6.1 (SUBSUMPTION OF SEQUENCES OF DEBITS, EXPRESSED IN TERMS OF PARTIAL SUMS). *Suppose the lists ds_1 and ds_2 have the same length. Then the judgement $\exists n. (m) ds_1 \leq ds_2 (n)$ is equivalent to $\forall i. \sum(\text{take } i \text{ } ds_1) \leq m + \sum(\text{take } i \text{ } ds_2)$.*

The subsumption judgement enjoys a number of reasoning rules, which are presented in Figure 15. The judgement $(m) ds_1 \leq ds_2 (n)$ is covariant in m and contravariant in n (**SUB-VARIANCE**). It is reflexive (**SUB-REFL**), transitive (**SUB-TRANS**), and compatible with list concatenation (**SUB-APPEND**). Extra credit at the left end translates to extra credit at the right end (**SUB-ADD-SLACK**). Finally, increasing the apparent cost of the first n thunks from d_1 to d_2 results in $n \times (d_2 - d_1)$ extra credit at the right end (**SUB-REPEAT**). As a more readable special case, an increase of 1 in the debit of the first n thunks justifies a decrease of n in the debit of the thunk that follows. In other words, an expensive thunk can be made to appear cheap provided it lies far enough away in the future. This reasoning rule plays a key role in Okasaki's amortized analysis of the banker's queue (§7).

6.3 Operations on Streams

There remains to present the specifications of the operations on streams whose code appears in Figure 1. For the sake of brevity, we omit the specifications of the tiny functions *nil* and *uncons*: they are similar to **STREAM-CREATE** and **STREAM-FORCE**. We also omit the specification of *revl_append*. We present the specifications of the last two functions, *revl* and *append*, in Figure 16.

STREAM-REVL states that *revl* transforms an immutable list l whose elements form the sequence xs into a stream s whose elements form the sequence $\text{rev } xs$. (The pure assertion $\text{List } l \text{ } xs$ indicates that the value l is an immutable list whose elements form the sequence xs .) If the sequence xs has length n , then this stream involves $n + 1$ thunks. The postcondition in **STREAM-REVL** indicates that the first thunk is expensive, while the remaining n thunks are cheap: the first thunk carries debit $\underline{R}n$ (where \underline{R} is a constant), while every other thunk carries debit zero. The first thunk is expensive because, when it is forced, *revl_append* $l \text{ } Nil$ is invoked (line 23 in Figure 1). This function call requires linear time because it eagerly traverses the list l and immediately constructs the remaining n thunks. These thunks are cheap because they immediately return a pre-existing value. The function call *revl* l itself has constant time complexity: **STREAM-REVL** requires a constant amount \underline{R}' of time credits.

STREAM-APPEND states that *append* $s_1 \text{ } s_2$ has constant complexity: it consumes \underline{P} time credits. If the streams s_1 and s_2 represent the sequences of elements xs_1 and xs_2 then the stream returned by *append* represents the sequence $xs_1 ++ xs_2$. More crucially, if the sequences of debits associated with s_1 and s_2 are ds_1 and ds_2 , then the sequence of debits associated with this stream is $ds_1 \bowtie ds_2$.

```

1  type 'a queue =
2    { lenf: int; f: 'a stream; lenr: int; r: 'a list }
3
4  let empty () =
5    { lenf = 0; f = nil(); lenr = 0; r = [] }
6
7  let check ({ lenf = lenf ; f = f; lenr = lenr; r = r } as q) =
8    if lenf >= lenr then q
9    else { lenf = lenf + lenr; f = append f (revl r); lenr = 0; r = [] }
10
11 let snoc q x =
12   check { q with lenr = q.lenr + 1; r = x :: q.r }
13
14 let extract q =
15   let x, f = uncons q.f in
16   x, check { q with f = f; lenf = q.lenf - 1 }

```

Fig. 17. The Banker's Queue: OCaml Code

The *debit join* operation \bowtie is defined as follows, where \underline{A} and \underline{B} are integer constants:

$$(ds_1 ++ [d_1]) \bowtie (d_2 :: ds_2) \triangleq \text{map } (\underline{A} + _) \ ds_1 \ ++ \ (\underline{A} + d_1 + \underline{B} + d_2) :: ds_2$$

If ds_1 has length $n_1 + 1$ and ds_2 has length $1 + n_2$ then $ds_1 \bowtie ds_2$ has length $n_1 + 1 + n_2$. The computation of $ds_1 \bowtie ds_2$ can be informally described as follows: first, add \underline{A} to every element of ds_1 ; then, meld the two sequences, by fusing (adding) the last element of the first sequence with the first element of the second sequence; finally, add \underline{B} to this fused element. This specification reflects the fact that (1) the overall cost of a stream concatenation operation is $\underline{A}(n_1 + 1) + \underline{B}$, where n_1 is the number of elements of the first stream; and (2) the cost of concatenation is distributed across the first $n_1 + 1$ thunks of the result stream: each of the first n_1 thunks bears a cost of \underline{A} ; the next thunk bears a cost of $\underline{A} + \underline{B}$; and the remaining n_2 thunks bear no cost.

STREAM-APPEND states that if the streams s_1 and s_2 have height h then the stream returned by *append* has height $h + 1$. This reflects the fact that a thunk in this new stream can depend on (force) a thunk in the stream s_1 or in the stream s_2 . Such precise height information is necessary during the inductive proof of *append*, and can be necessary also in some usage scenarios of *append*. In the banker's queue (§7), it is not needed: there, we work with streams of unknown height.

7 THE BANKER'S QUEUE

The banker's queue [Okasaki 1999, §6.3.2] is a persistent FIFO queue whose main operations, *snoc* and *extract*, have constant amortized time complexity. In the following, we present a specification for the banker's queue, explain how the banker's queue is implemented, and verify that the code satisfies the specification. Because the implementation involves a stream, we rely on the streams library presented in the previous section (§6).

It is worth pointing out that we do not simply replicate Okasaki's analysis of the queue. Instead, we propose a *simpler analysis*, which is made possible by the powerful reasoning rule **STREAM-FORWARD-DEBIT**. Instead of working with iterated sums of debits, as Okasaki does, we use a sequence of elementary proof steps that rely on the properties of debit subsumption (Figures 14 and 15).

<p>BANKER-PERSISTENT $\text{persistent}(BQueue\ p\ q\ xs)$</p>	<p>BANKER-EMPTY $\{\\$E\}\ \text{empty}()\ \text{returns}(\exists q)\ q\ \{BQueue\ p\ q\ []\}$</p>
<p>BANKER-SNOC $\{\\$S\} * BQueue\ p\ q\ xs\}$ $\text{snoc}\ q\ x$ $\text{returns}(\exists q')\ q'\ \{BQueue\ p\ q'\ (xs\ ++ [x])\}$</p>	<p>BANKER-EXTRACT $\{\\$X\} * BQueue\ p\ q\ (x :: xs) * \zeta_p^\infty\}$ $\text{extract}\ q$ $\text{returns}(\exists q')\ (x, q')\ \{BQueue\ p\ q'\ xs * \zeta_p^\infty\}$</p>

Fig. 18. Banker's Queue: Public Interface

Interface and specification of the banker's queue. Three functions make up the main entry points of the library: *empty* creates a new empty queue; *snoc* inserts an element at the rear end of a queue; *extract* extracts an element at the front end of a queue.

Every operation has constant amortized time complexity. This implies that every sequence of operations on queues has linear cost in the number of operations. This is true even if queues are used in a non-linear manner, that is, even if operations are applied not only to the newest version of a queue, but also to old versions.

Our formal specification of the banker's queue appears in Figure 18. The assertion $BQueue\ p\ q\ xs$ means that q is a queue, allocated in pool p , whose elements form the sequence xs . This assertion is persistent. This means that queues can be shared and that the queue operations are not destructive: one may apply an operation to an old queue. The rules **BANKER-EMPTY**, **BANKER-SNOC** and **BANKER-EXTRACT** provide specifications for *empty*, *snoc*, and *extract*. Each of them requires a constant amount of time credits in its precondition (E , S and X respectively). The specification of *extract* requires and preserves the token ζ_p^∞ , which allows forcing thunks of arbitrary height (§5). As noted earlier (§2), a fresh pool can be allocated at any time, together with a new token for it, thanks to the law $\text{True} \Rightarrow \exists p. \zeta_p^\infty$, which is also part of the public specification.

To a reader who wonders why $BQueue$ must be parameterized with a pool p , and why *extract* must require a token, we point out that this is actually necessary. HeapLang has shared-memory concurrency, and our implementation of thunks is (by design) not thread-safe. The token discipline prevents two threads from racing on a thunk.

Implementation of the banker's queue. The implementation appears in Figure 17. A queue is a record of four fields: a “front” stream of elements f , a “rear” list of elements r , and their respective lengths, $\text{len}f$ and $\text{len}r$. Elements are inserted into the queue by prepending to the rear list, and are extracted from the queue by extracting from the front stream. As a result, the elements of the rear list are stored in logically reverse order: if the elements of the front stream form the sequence fs and if the elements of the rear list form the sequence rs , then the sequence of elements contained in the queue is $fs\ ++\ \text{rev}\ rs$. The inequality $|rs| \leq |fs|$ is maintained: the rear list never contains more elements than the front stream.

When the length of the rear list exceeds the length of the front stream, the queue must be rebalanced. This is done by the auxiliary function *check*. Rebalancing involves reversing the rear list, converting it into a stream, and appending this stream at the end of the front stream. The reversal and conversion into a stream are performed by *revl*. According to **STREAM-REVL** (Figure 16), an invocation of *revl* has constant time complexity, but returns a stream whose first thunk has linear cost. Thus, rebalancing itself is cheap, but constructs an expensive thunk, which (after rebalancing) appears in the middle of the front stream. Okasaki's insight is that the cost of this expensive thunk can be distributed onto the linear number of thunks that appear in front of it. This translates to a constant amount of extra debit per thunk, which is acceptable.

$$\begin{aligned}
bqueueDebts\ nf\ nr &\triangleq \underline{K}^{nf-nr} ++ 0^{\min(nf,nr)+1} \\
BQueueRaw\ p\ q\ fs\ rs &\triangleq \exists s, h, l. \left\{ \begin{array}{l} \ulcorner q = (|fs|, s, |rs|, l) \urcorner * \\ Stream\ p\ h\ s\ (bqueueDebts\ |fs|\ |rs|)\ fs * List\ l\ rs \end{array} \right. \\
BQueue\ p\ q\ xs &\triangleq \exists fs, rs. BQueueRaw\ p\ q\ fs\ rs * \ulcorner xs = fs ++ rev\ rs \wedge |rs| \leq |fs| \urcorner
\end{aligned}$$

Fig. 19. Banker's Queue: Definitions

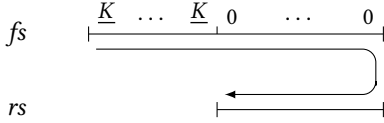


Fig. 20. A balanced banker's queue. The front stream is annotated with debts. The arrow indicates the logical order of elements.

$$\begin{aligned}
& \text{BANKER-CHECK} \\
& \{ \$H * BQueueRaw\ p\ q\ fs\ rs * \ulcorner |rs| \leq |fs| + 1 \urcorner \} \\
& \quad \text{check}\ q \\
& \text{returns } (\exists q')\ q' \{ BQueue\ p\ q'\ (fs ++ rev\ rs) \}
\end{aligned}$$

Fig. 21. Banker's Queue: Specification of *check*

The predicate BQueue. Figure 19 presents the definition of $BQueue\ p\ q\ xs$. It is constructed by combining the assertions $xs = fs ++ rev\ rs$ and $|rs| \leq |fs|$, which we have explained already, with a lower-level assertion, $BQueueRaw\ p\ q\ fs\ rs$. This assertion states that q is a 4-tuple, requires the two length fields to contain the integer values $|fs|$ and $|rs|$, and uses the predicates *Stream* and *List* to describe the front stream and rear list. The most noteworthy aspect is that the debit sequence of the front stream is fully determined: it is $bqueueDebts\ |fs|\ |rs|$. The definition of $bqueueDebts$ states that the first $nf - nr$ thunks in the front stream carry debit \underline{K} , where $\underline{K} \triangleq \underline{A} + \underline{B} + \underline{R}$, whereas the remaining thunks carry debit zero. This is illustrated in Figure 20. In our illustrations (Figures 20, 22, and 23), the debit associated with the very last thunk of the front stream, which is always 0, is never shown.

Specification of check. The specification of the function *check*, which rebalances a queue, appears in Figure 21. It states that *check* accepts an imbalanced queue and returns a balanced queue. Because *check* is called by every operation, *check* can expect that the length of the rear list exceeds the length of the front stream by at most one.

Verifying snoc and extract. *snoc* causes the rear list to grow by one element. To preserve the debit invariant (Figure 20), one must pay for the last thunk in the front stream whose debit is nonzero. This is illustrated in Figure 22 (left). This is done by applying **STREAM-FORWARD-DEBIT**. This requires proving the subsumption judgement $(\underline{K})\ \underline{K}^n ++ \underline{K} :: 0^m \leq \underline{K}^n ++ 0 :: 0^m\ (0)$, which follows from **SUB-APPEND**, **SUB-CONS**, and **SUB-REFL**.

The function *extract* forces and discards the first thunk of the front stream, as pictured in Figure 22 (right). Thus, it is necessary to first pay for this thunk. This can be done by applying **STREAM-FORWARD-DEBIT** and proving the subsumption judgement $(\underline{K})\ \underline{K} :: \underline{K}^n ++ 0^m \leq 0 :: \underline{K}^n ++ 0^m\ (0)$, which follows from **SUB-CONS** and **SUB-REFL**. This is a trivial instance of **STREAM-FORWARD-DEBIT**, that is, an ordinary payment as opposed to a deep payment.

Verifying check. Because *check* empties the rear list, it is clear that it restores the invariant $|rs| \leq |fs|$. How *check* restores the debit invariant is more subtle. Let us consider an unbalanced queue whose front and rear sequences of elements are fs and rs . Let us write n for $|fs|$, so that we have $|rs| = n + 1$. According to the debit invariant, every thunk in the front stream has debit zero. This situation is represented in step (A) of Figure 23. The proof proceeds as follows:



Fig. 22. Left: after *snoc* has inserted an element in the rear list. Right: before *extract* removes an element of the front stream. Highlighted in red: the thunk whose debit must be paid off.

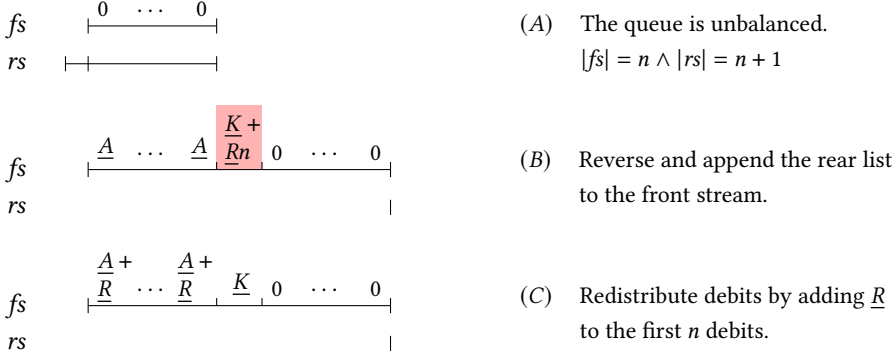


Fig. 23. Rebalancing. In red: the costly thunk whose debit must be distributed among the front thunks.

- (1) According to **STREAM-REVL** and **STREAM-APPEND**, reversing the rear list and appending the result to the front stream produces a stream whose debits are $0^{n+1} \bowtie \underline{R}(n+1) :: 0^{n+1}$. This debit sequence has length $2n+2$: this is consistent with the fact that the new front stream has $2n+1$ elements. By definition of the debit join operator \bowtie , this is: $\underline{A}^n ++ (\underline{A} + \underline{B} + \underline{R}(n+1)) :: 0^{n+1}$. Because \underline{K} is $\underline{A} + \underline{B} + \underline{R}$, this sequence of debits is also $\underline{A}^n ++ (\underline{K} + \underline{Rn}) :: 0^{n+1}$. It is depicted in step (B) of Figure 23.
- (2) Then, the key step of the proof is to *distribute* the expensive debit $\underline{K} + \underline{Rn}$ onto earlier debits. We increase each of the first n debits by \underline{R} , so as to be allowed to reduce the expensive debit from $\underline{K} + \underline{Rn}$ down to \underline{K} . The result is illustrated in step (C) of Figure 23. This redistribution of debit is permitted by **STREAM-FORWARD-DEBIT** provided we establish the subsumption judgement $(0) \underline{A}^n ++ (\underline{K} + \underline{Rn}) :: 0^{n+1} \leq (\underline{A} + \underline{R})^n ++ \underline{K} :: 0^{n+1} (0)$. This judgement follows from **SUB-APPEND**, **SUB-REPEAT**, **SUB-CONS**, and **SUB-REFL**.
- (3) Because $\underline{A} + \underline{R} \leq \underline{K}$ holds, we can now over-approximate every debit by \underline{K} , except for the very last debit, which must remain zero. We exploit the subsumption judgement $(0) (\underline{A} + \underline{R})^n ++ \underline{K} :: 0^{n+1} \leq \underline{K}^{2n+1} ++ [0] (0)$. The debit sequence $\underline{K}^{2n+1} ++ [0]$ is equal to *bqueueDebits* $(2n+1) 0$, which is the expected sequence of debits for a balanced queue whose front stream has length $2n+1$ and whose rear list is empty.

8 THE PHYSICIST'S QUEUE; IMPLICIT QUEUES

We verify two additional persistent data structures found in Okasaki's book. Both exploit thunks to achieve amortized constant time complexity.

The physicist's queue [Okasaki 1999, §6.4.2] is similar to the banker's queue. It involves front and rear lists of elements and rebalances them when necessary. Its analysis is somewhat more elementary than the banker's queue's, because a physicist's queue involves a single thunk instead of a stream. The rule **THUNK-CONSEQUENCE** is not needed. The physicist's queue does involve a thunk that forces another thunk. Our height-indexed thunks (§5) allow this.

Implicit queues [Okasaki 1999, §11.1] are a more complex data structure. Their implementation relies on recursive slowdown: the queue is structured in layers, where each layer stores twice as many elements as the previous layer. When one layer is at hand, accessing the next layer requires forcing a thunk. Therefore, an implicit queue has the same general structure as a stream: it involves a sequence of nested thunks. Our implementation and our debit invariant closely follow Okasaki’s. They match Danielsson’s as well [Danielsson 2008, §8.1], although Danielsson chooses a slightly different way of defining the data structure. To carry out the complexity analysis, we make full use of the height-indexed thunk API (§5). Here, the use of `THUNK-CONSEQUENCE` is crucial.

9 RELATED WORK

Okasaki [1999] invents the debit-based approach to the amortized time complexity analysis of lazy, purely functional data structures. He describes this approach in a clear but informal way. Danielsson [2008] uses Agda to define a formal complexity analysis, to prove its soundness, and to verify some of Okasaki’s data structures, including the banker’s queue and implicit queues. Deep payment is used in the verification of the banker’s queue, but is not supported in the proof of soundness of the analysis. Like Okasaki’s informal discipline, Danielsson’s system is purely based on debits and does not include a subsystem that aims to forbid reentrancy, such as our “height” discipline (§5). It could be that he does not need such a subsystem because his type system guarantees termination. However, in the presence of the fixed point combinator `fix`, it is not clear whether this is true. Danielsson does not prove that every well-typed program terminates. He establishes a weak time complexity guarantee: if a program has type τ and *if this program reaches a weak head normal form* in n steps then $n \leq \text{time}(\tau)$ holds. Thus, the possibility that the program diverges remains open. Atkey [2011] suggests extending separation logic with time credits and using it to carry out amortized time complexity analyses. Pilkiewicz and Pottier [2011] independently introduce the concept of time credit in an affine type system and suggest that time credits, in combination with monotonic ghost state and a form of invariant, can be used to reconstruct Okasaki’s debit-based analysis of thunks. Their work is however informal. Mével et al. [2019] carry out a similar programme in the formal setting of Iris^S, which they construct on top of Iris. Unfortunately, their work exhibits several shortcomings. First, because they use a single token for all thunks in the world, they do not support thunks that force thunks. Second, because they do not isolate the abstract concept of a piggy bank and effectively hard-wire exactly one piggy bank per thunk, they cannot justify deep payment. They do not verify any of Okasaki’s algorithms.

Inspired by Danielsson’s work, McCarthy et al. [2016] define in Coq a monad that keeps track of costs. They place emphasis on obtaining clean OCaml code via Coq’s extraction facility. They use the pure, call-by-value fragment of OCaml; no thunks are involved. Also inspired by Danielsson, Handley et al. [2020] develop a semi-automated system, based on Liquid Haskell, to verify the time complexity of Haskell programs. A *pay* combinator is supported; deep payment is not. The soundness of the system is stated but not formally verified. Madhavan et al. [2017] present a system that infers and verifies resource bounds for higher-order functional programs that involve thunks or memoization tables. Nipkow and Brinkop [2019] verify the amortized complexity of several functional data structures in Isabelle/HOL. These data structures do not involve thunks, and the analysis is credit-based, not debit-based. Hackett and Hutton [2019] propose both an operational semantics and a denotational cost semantics for lazy (call-by-need) programs, based on the idea of *clairvoyant evaluation*, where the mutable state inherent in thunks is replaced with nondeterminism. Inspired by this idea, Li et al. [2021] define the *clairvoyance monad*, a model of laziness that is shallowly embedded inside Coq, and develop two program logics of over- and under-approximation to reason about the cost of lazy programs. They do not reason in terms of debits.

10 CONCLUSION

For the first time, we have fully reconstructed Okasaki’s debit-based reasoning rules, as well as Okasaki’s analyses of the banker’s queue, the physicist’s queue, and implicit queues, in the formal and foundational setting of separation logic with time credits. Our proofs are machine-checked [Anonymous 2023]. We view this result as an enlightening and useful bridge between the worlds of purely functional programming and imperative programming. From a technical point of view, ghost piggy banks are an original concept and make unusual use of atomic and non-atomic invariants in combination. Our modular construction of thunks on top of piggy banks, in several steps, is original. We hope that the reader finds it elegant.

One area where engineering work is needed is in the quality of the implementation of Iris[§] [Mével et al. 2019]. The fact that Iris[§] is implemented on top of Iris via a program transformation, the *tick translation*, should be an implementation detail; yet it is currently apparent. We find that this creates unnecessary difficulty for the end user.

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