

Does a small perturbation created by an upper-limb exoskeleton impact our coordination in reaching tasks?

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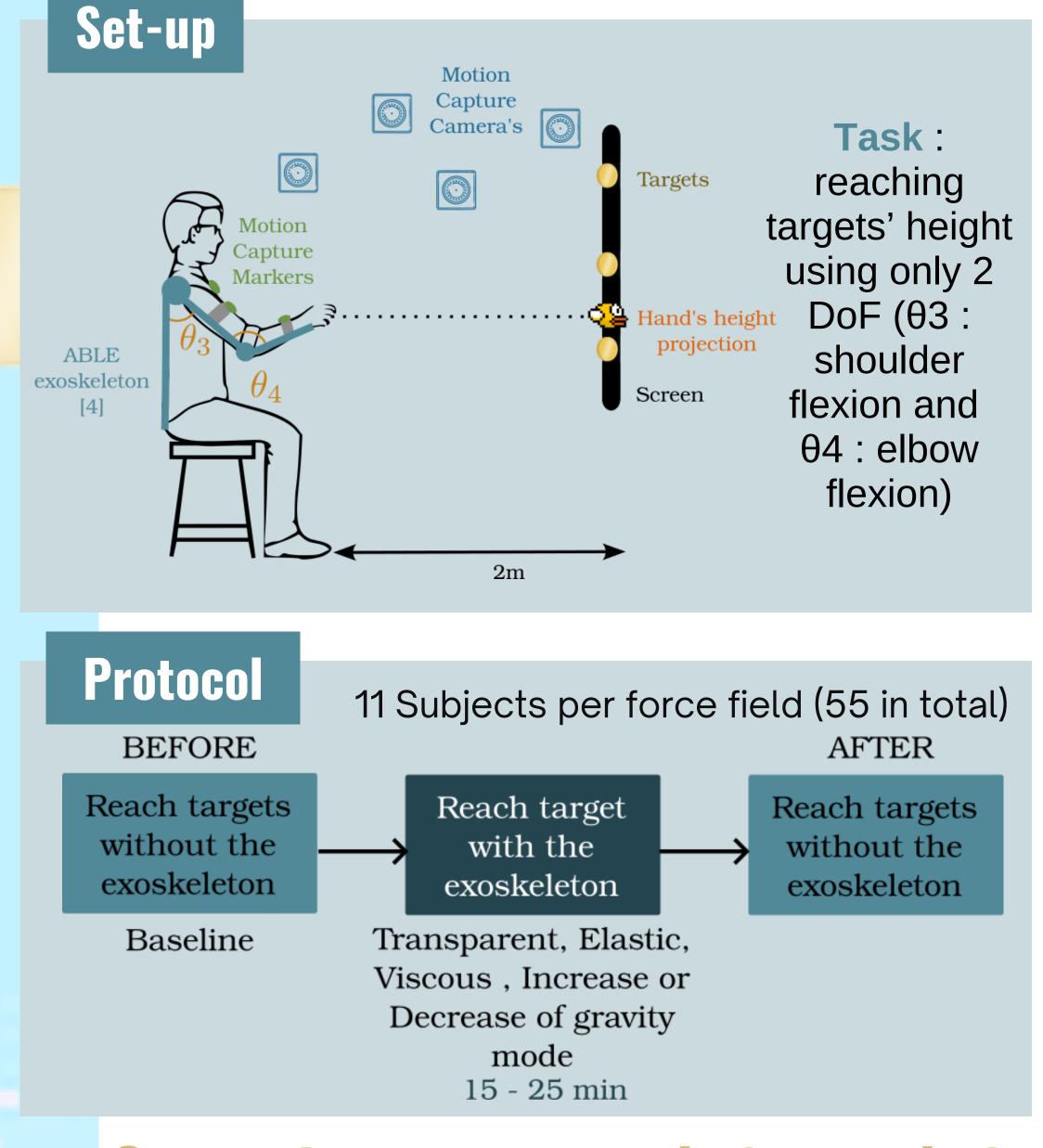
Does a small perturbation created by an upper-limb exoskeleton impact our coordination in reaching tasks?

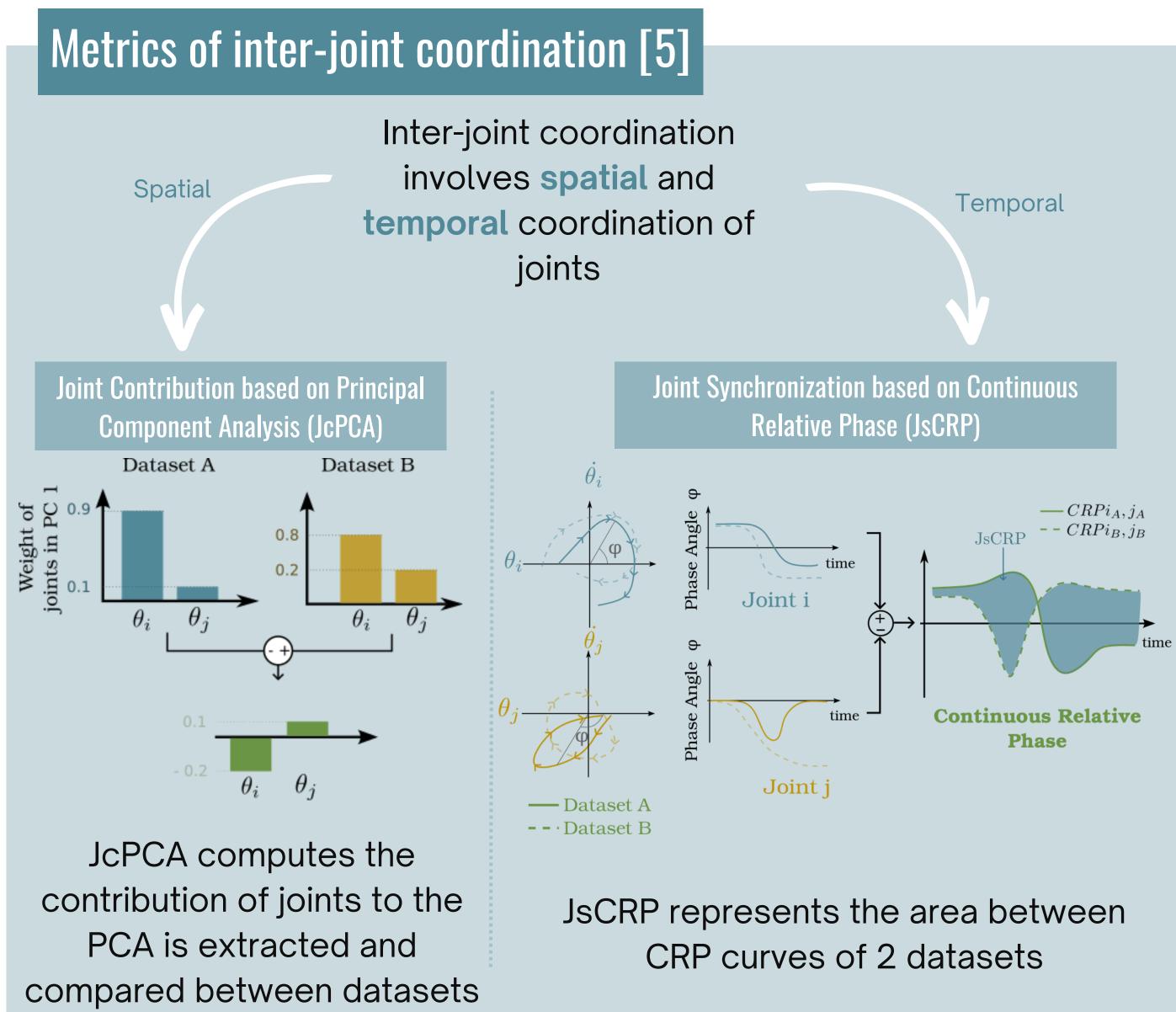
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A low-magnitude perturbation applied by an exoskeleton at the joint level still alters joint coordination once the disturbance is removed, even though task performance is unchanged.

The impact of perturbations applied at the human end-effector level has been widely studied as well as the learning process which results from it [1]. However, the effect of perturbations at the joint level and the learning process related to it has been poorly investigated [2] [3]. Indeed, due to the redundancy of human limbs, perturbations at the joint level do not necessarily affect the task and therefore, the central nervous system might adapt differently. This study investigates the impact of a low-amplitude joint-level perturbation on our coordination strategies while performing a reaching task.







Comparing movements before and after being exposed to the force field in the exoskeleton.

End effector and joints results

End-effec.

- No significant differences on the endeffector metric nor on range of motions of joints.
- Only the Visous Force Field is statistically significant (*) for the overshoot metric and joint range of motion 3

	distance (%)	Overshoot (%)	End-effec. velocity (%)	Task Time (%)	maximum velocity (%)
Transp.	-0.1±0.16	-0.97±2.48	0.00 ± 0.34	-0.05 ± 0.23	-0.03±0.33
Elastic	-0.04 ± 0.17	-0.20 ± 0.74	0.10 ± 0.46	-0.06 ± 0.33	-0.06 ± 0.28
Viscous	0.07 ± 0.17	0.5±0.4**	0.01 ± 0.51	-0.13 ± 0.22	-0.16±0.35
Decr.	-0.15±0.18	-0.63 ± 1.35	-0.17±0.63	-0.08 ± 0.24	0.03 ± 0.23
Incr.	-0.04 ± 0.18	-0.23 ± 1.47	-0.65 ± 2.32	-0.01 ± 0.18	0.06 ± 0.18
	ROM 1	(%) ROM	2 (%) RO	M 3 (%)	ROM 4 (%)

 -0.39 ± 0.87 -0.03 ± 0.13 0.08 ± 0.31 -0.20 ± 0.55 Transp. -0.02 ± 0.21 0.15 ± 0.23 -0.05 ± 0.38 -0.48 ± 0.95 Elastic $0.40\pm0.27^*$ -0.18±0.33 -0.45±0.57 0.09 ± 0.37 Viscous -0.05±0.31 -0.18±0.44 -0.57 ± 0.81 0.00 ± 0.36 Decr. -0.18±0.75 -0.06 ± 0.47 0.10 ± 0.56 -1.28 ± 2.11 Incr.

FORCE FIELDS HAVE NO IMPACT ON THE TASK'S PERFORMANCE ...

Inter-joint coordination results

 JcPCA θ_3 8
 7
 10
 11
 8

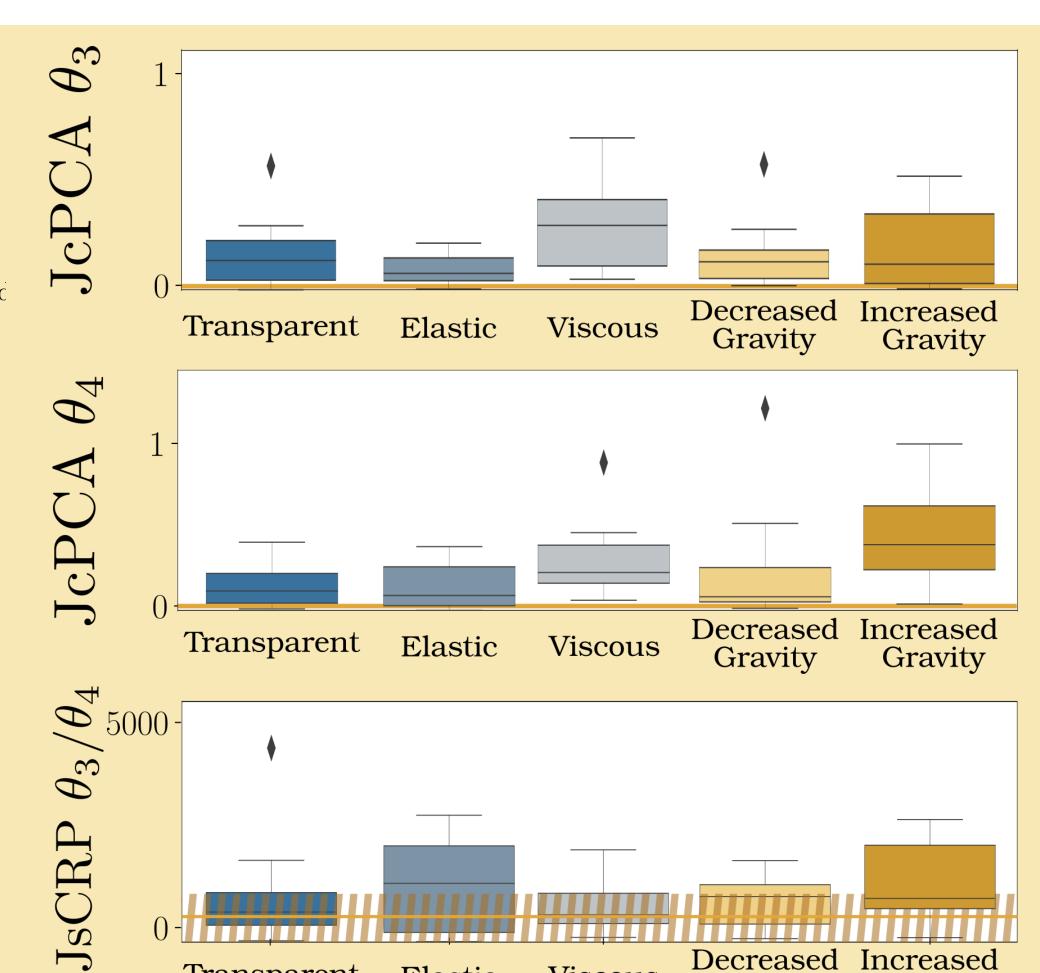
 JcPCA θ_4 6
 8
 9
 6
 9

 JsCRP θ_3/θ_4 7
 7
 4
 7
 9

Γable 1: Number of participants (out of 11 per group) that modified their coordination strategy to each force field

- Viscous and Decrease of gravity are the force field with the most important effect on θ3 contribution.
- Increase of gravity is the field that creates the greater change of interjoint coordination both for spatial and temporal organization of joints.
- *Elastic* force field impacts essentially the joint synchronization
- Even the *Transparent* force field affects most of the subjects.

... BUT THE COORDINATION STRATEGIES CHANGED!



• The crosshatching area is the natural variability of all subject (i.e. their variability within the Natural Before Exposition Condition)

Viscous

Transparent Elastic









Conclusion & Discussion

SHORT EXPOSITION OF LOW-MAGNITUDE FORCE FIELD IMPACTED COORDINATION STRATEGIES!

• There is **no differences** in the task performance before and after exposition to the force field regarding the **end-effector** and the joints ROM.

Time to

- The coordination strategies is most impacted by the viscous force field. The Increase of gravity force field created greater change in the coordination strategies for more than half of the subjects.
- Long term effect of those force fields should be investigated.
- The evolution of the coordination strategy during the exposition to the force field could be explored.
- The exploration of the individual characteristics (fatigue generated, vigor, etc.) could explain why did some subjects adapt or not to the force fields

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