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# Arctic curves of the reflecting boundary six vertex and of the twenty vertex models 

Philippe Di Francesco* ${ }^{\text {C }}$<br>Department of Mathematics, University of Illinois, Urbana, IL 61821, United States of America<br>Institut de physique théorique, Université Paris Saclay, CEA, CNRS, F-91191<br>Gif-Sur-Yvette, France<br>E-mail: philippe@illinois.edu

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## Abstract

We apply the tangent method of Colomo and Sportiello to predict the arctic curves of the six vertex model with reflecting (U-turn) boundary and of the related twenty vertex model with suitable domain wall boundary conditions on a quadrangle, both in their disordered phase.

Keywords: integrable lattice models, arctic phenomenon, domino tilings, six vertex model, lattice paths
(Some figures may appear in colour only in the online journal)

## 1. Introduction

### 1.1. Arctic phenomenon

Geometrically constrained two-dimensional statistical models are known to display the socalled arctic phenomenon in the presence of suitable boundary conditions. This includes 'free fermion' dimer models, where typically dimers choose a preferred crystalline orientation near boundaries while they tend to be disordered (liquid-like) away from the boundaries: the arctic phenomenon is the formation of a sharp phase boundary as the domain is scaled by a large overall factor, the so-called arctic curve separating frozen crystalline from disordered liquid phases. The first observed instance of this phenomenon is the celebrated arctic circle arising in the domino tilings of the Aztec diamond [JPS98], and a general theory was developed for dimers [KO07, KOS06]. The free fermion character of these models can be visualized in their formulation in terms of non-intersecting lattice paths, i.e. families of paths with fixed ends, subject to the condition that they share no vertex (i.e. avoid each-other), and can consequently be expressed in terms of free lattice fermions. A manifestation of the free fermion models is that
*Author to whom any correspondence should be addressed.
their arctic curves are always analytic, and usually algebraic at 'rational' values of interaction parameters, such as in the uniformly weighted cases.

Beyond free fermions, the archetypical model for paths allowed to interact by 'kissing' i.e. sharing a vertex at which they bounce against each-other, is the six vertex ( 6 V ) model. The families of paths describing the model are called osculating paths. With so-called domain wall boundary conditions (DWBC) the 6 V model exhibits an arctic phenomenon in its disordered phase, which was predicted via non-rigorous methods[CNP11, CP10b], the latest of which being the tangent method introduced by Colomo and Sportiello [CS16]. The new feature arising from these studies is that the arctic curves are generically no longer analytic, but rather piecewise analytic. For instance, the arctic curve for large alternating sign matrices (uniformly weighted 6V-DWBC) is made of four pieces of different ellipses as predicted in [CP10b] and later proved in [Agg20].

The tangent method was validated recently in a number of situations, mostly in free fermion situations [CKN21, CPS19, DFG18, DFG19a, DFG19b, DFL18, PR19a]. However, a simple transformation using the integrability of the models allowed to deduce from the 6 V results the arctic curves for another model of osculating paths: the twenty vertex ( 20 V ) model with DWBC1, 2 [DDFG20]. The 20 V model is the triangular lattice version of the 6 V model: in one formulation the configurations of the model are orientation assignments of all edges of the lattice, in such a way that the ice rule is obeyed at each vertex, namely that there be an equal number of edges pointing toward and outwards ( $2+2$ for $6 \mathrm{~V}, 3+3$ for 20V). In [DFG18], four possible variations around DWBC were considered for the 20 V model, denoted DWBC1, $2,3,4$. In the present paper, we will concentrate on the 20 V -DWBC3 model on a quadrangle, which was recently shown to have the same number of configurations as domino tilings of the Aztec triangle of suitable size [DF21]. The proof uses again the integrability of the model to relate its partition function to that of the 6 V model with another type of DWBC, called U-turn, considered by Kuperberg in [Kup02], and whose partition function has a nice determinantal form [Kup02, Tsu98].

In this paper, we set the task of deriving the arctic curves for the U-turn 6 V model, and as by-products, those of the 20V-DWBC3, and of the domino tiling of the Aztec triangle.

## 12 Arctic curves and the tangent method

The systems we are considering in this note are all described in terms of osculating or nonintersecting paths, and are expected to display an arctic curve phenomenon. The rough idea behind the tangent method is as follows. The $n$ paths describing the model's configurations have fixed starting and endpoints, and form a 'soup' whose boundary tends to a subset of the arctic curve. Indeed, this boundary is a solid/liquid separation between an empty phase and one with disordered path configurations. Consider the outermost path forming that boundary: if we displace the endpoint of this path to a point say $L$ outside of the original domain, the path will have to detach itself from the soup, and continue to its endpoint within a mostly empty space, once it gets away from the soup formed by the other paths, where it is most likely to follow a geodesic (a line in all cases of this paper, due to a general argument of [DFL18]). This geodesic is expected to be tangent to the arctic curve in the large $n$ limit. The corresponding path is therefore used as a probe into the arctic curve: the geodesic is determined by the point $L$ and the point $K$ at which it exits the original domain ${ }^{1}$.

The partition function $\Sigma_{n, L}$ of the new model is now a sum over the possible positions of $K$ of the product of two partition functions: (1) $Z_{n, K}$ the partition function of the $n$ osculating/non-

[^0]intersecting paths on the original domain, in which the outer path is conditioned to end at point $K$ instead of its original endpoint. (2) $Y_{K, L}$ the partition function of a single path subject to the same weighting, in some empty space from the point $K$ to the new endpoint $L$. The quantity $\Sigma_{n, L}={ }_{K} Z_{n, K} Y_{K, L}$ is dominated at large $n$ by contributions from the most likely exit point $K(n, L)$. The arctic curve is then recovered as the envelope of the family geodesics through $L$ and $K(n, L)$ for varying $L$ (in rescaled coordinates).

We see that the crucial ingredient in this method is the refined partition function $Z_{n, K}$ in which the outer path is conditioned to exit the domain at point $K$, or rather its normalized version, the 'refined one-point function' $H_{n, K}=Z_{n, K} / Z_{n}$ where we have divided by the original partition function $Z_{n}$. Computing exactly the leading large $n, K, L$ asymptotics of $H_{n, K}$ and $Y_{K, L}$ leads to the determination of $K(n, L)$ by solving a steepest descent problem, and eventually to the arctic curve.

After revisiting the case of the 6 V model for pedagogical purposes in section 3, we will apply the tangent method in section 4 to the case of the $6 \mathrm{~V}^{\prime}$ model on the $(2 \pi 1) \times n$ rectangular grid (a simplified version of the U-turn 6 V model), in section 5 to the case of the 20 V model with DWBC3 on the quadrangleQ, and finally in section 6 to the domino tilings of the Aztec triangle . Note that the tangent method was previously applied in [PR19a] to a particular 'free fermion' case of the U-turn 6 V model, where the arctic curve is a half-circle: the results of section 3 extend this to arbitrary values of the parameters.

### 1.3. Outline of the paper and main results

The paper is organized as follows. In section 2.1 we define the four models studied in this paper. These include: the 6 V model with DWBC, the 6 V model with U-turn boundary conditions and the related $6 \mathrm{~V}^{\prime}$ model, the 20 V model with DWBC3 of reference [DF21], and finally the domino tiling problem of the Aztec triangle introduced and studied in references [DF21, DFG18]. We show in particular that all models are described by families of weighted osculating/non-intersecting paths. In section 2.2, we describe the tangent method in general and how it applies to the determination of the arctic curves of our models.

The next sections are all organized in a similar way, and treat the various models. For each case, we first derive compact relations obeyed by the partition function and one-point function of the model, allowing for extracting asymptotic results. The latter are used to apply the tangent method, and finally obtain the arctic curves of the model. While section 3 revisits the known case of the 6 V model with DWBC, as a pedagogical warmup, the remaining sections provide new results: section 4 is about the $6 \mathrm{~V}^{\prime}$ model, section 5 the 20 V model with DWBC3, and section 6 the domino tilings of the Aztec triangle. We obtain arctic curves in all cases: theorems $3.6,4.15,5.3$ and 6.2 cover respectively the cases of $6 \mathrm{~V}, 6 \mathrm{~V}^{\prime}, 20 \mathrm{~V}$ and domino tilings.

We gather a few concluding remarks in section 7 .

## 2 Models, paths and the tangent method

## 21. The models

In this paper we consider 4 different models: three vertex models with particular domain-wall type boundary conditions ( 6 vertex on an $n \times n$ square grid, 6 vertex with $U$-turn boundaries on a $2 n-1 \times n$ rectangular grid, and 20 vertex on the quadrangle $\mathrm{Q}_{n}$ ), and one model of domino tilings of the Aztec triangle $\mathrm{T}_{n}$.
21.1. 6 V model with $D W B C$. The 6 V model is the archetype of integrable ice-type model on the two-dimensional square lattice. Its configurations are obtained by orienting the edges of


Figure 1. The 6 vertex environments obeying the ice rule on the square lattice (top) and their osculating path reformulation (bottom). We have indicated the corresponding types (a)-(c).
the lattice (with arrows) in such a way that each vertex has exactly two entering and two outgoing arrows (the so-called 'ice rule'). This gives rise to the ${ }_{2}^{4}=6$ local environments of figure 1 (top row), traditionally called (a)-(c) types. Here we consider the 6 V model on an $n$ w square grid with fixed DWBC, i.e. the $2 n$ horizontal boundary arrows ( $n$ on the West (W) and $n$ on the East (E) boundaries) pointing toward the square domain and the $2 n$ vertical ones ( $n$ on the North (N) and $n$ on the South (S) boundaries) outwards (see figure 2(a) for an illustration). Finally, the configurations are weighted by the product of local vertex weights over the domain ${ }^{2}$, parameterized by real 'spectral parameters' $u, v$ attached to the horizontal and vertical line that intersect at the vertex, taking the following values in the so-called disordered regime, which we consider in this paper:

$$
\begin{equation*}
a=\rho \sin (u-v+\eta), \quad b=\rho \sin (u-v-\eta), \quad c=\rho \sin (2 \eta) \tag{2.1}
\end{equation*}
$$

for $a, b, c$ type vertices respectively. The overall fixed factor $\rho>0$ emphasizes the projective nature of the weights and the homogeneity of the partition function (weighted sum over configurations), from which $\rho^{n^{2}}$ factors out. Positivity of the weights imposes the condition:

$$
\begin{equation*}
\eta<u-v<\pi-\eta, \quad 0<\eta<\frac{\pi}{2} \tag{2.2}
\end{equation*}
$$

In the following we shall consider the homogeneous partition function $Z^{6 \mathrm{~V}}{ }_{[ }[u, v] \equiv$ $Z_{n}^{6 \mathrm{~V}}[u-v]$ in which all horizontal spectral parameters at taking the value $u$ and all vertical ones the value $v$, so that weights are uniformly defined by (2.1), and where we note that both the weights and the partition function only depend on the quantity $u-v$. As stressed in [CP10a], the partition function enjoys the following crucial symmetry property:

$$
\begin{equation*}
Z_{n}^{6 \mathrm{~V}}[\pi-(u-v)]=Z_{n}^{6 \mathrm{~V}}[u-v] . \tag{2.3}
\end{equation*}
$$

This is a consequence of the reflection symmetry of the weights: indeed, the DWBC are unchanged if we reflect the domain w.r.t. say a horizontal line. However, such a reflection interchanges vertices of types $a, b$ while keeping $c$-type environments unchanged. The same result is independently obtained by keeping the original setting, but applying the transformation

[^1]

Figure 2. (a) A sample configuration of the 6 V model with DWBC (for $n=9$ ) and (b) its reformulation in terms of osculating paths.
$(u-v) \rightarrow \pi-(u-v)$ which leaves the domain (2.2) invariant, and under which the weights $a$ and $b$ are interchanged, while $c$ remains invariant, and (2.3) follows.

This model was extensively studied [ICK92, Kor82, Lie67], and turned out to play a crucial role in Kuperberg's proof of the alternating sign matrix (ASM) conjecture [Bre99, Kup96]. The enumeration of ASM is realized at the 'ASM point' where all weights are equal to 1 , namely:

$$
\begin{equation*}
\eta=\frac{\pi}{6}, \quad u-v=\frac{\pi}{2}, \quad \rho=\frac{1}{\cos (\eta)} \tag{2.4}
\end{equation*}
$$

while the weighted enumeration (with a factor $\tau$ per entry -1 in the ASM) is provided by picking

$$
\begin{equation*}
u-v=\frac{\pi}{2}, \quad \rho=\frac{1}{\cos (\eta)}, \quad \tau=4 \sin ^{2}(\eta), \quad 0<\eta<\frac{\pi}{2} \tag{2.5}
\end{equation*}
$$

namely $(a, b, c)=\left(1,1,{ }^{\vee} \bar{\tau}\right)$, with the particular cases of $1,2,3$-enumeration, for the choices $\eta=\frac{\pi}{6}, \frac{\pi}{4}, \frac{\pi}{3}$ respectively. The ' $20 \mathrm{~V}-\mathrm{DWBC1}, 2$ point' is another interesting combinatorial point, which corresponds to the identification of the number of 20V DWBC1,2 configurations in terms of 6V DWBC [DFG18], with the choice:

$$
\begin{equation*}
\eta=\frac{\pi}{8}, \quad u-v=\frac{5 \pi}{8}, \quad \rho=\sqrt{ }-\frac{\sqrt{2}}{2} \tag{2.6}
\end{equation*}
$$

corresponding to weights $(a, b, c)=(1, \sqrt{ }, \overline{2}, 1)$.
More recently the thermodynamic free energy of the model was obtained in [BF06, KZJ00, ZJ00], and the arctic curves were derived using various semi-rigorous methods, such as the tangent method in [CPS19, CS16], and further used in [DDFG20] to determine the arctic curves of the 20 V DWBC1,2 models.

The configurations of the model can be rephrased in terms of families of osculating paths as follows. Pick a base orientation of arrows, say to the left and down, and mark all the edges of any given configurations that respect the base orientation. Note that all the W and S boundary edges are marked, while the N and E ones are not. The marked edges can be combined into paths say


Figure 3. (a) U-turn boundary 6V model: each U-turn (marked by a black dot along the W boundary) transmits the arrow orientation through the dot. (b) When all $u_{i}=\vartheta_{-} \eta$, the weights $y_{\mathrm{d}}=0$, hence all arrows go up through the U-turns, which may be cut out as shown. The bottom row becomes trivially fixed to the same $b$-type vertex. (c) The $6 \mathrm{~V}^{\prime}$ model is finally obtained by cutting out the trivial $b$-type vertices.
starting at the W boundary and ending at the S one, with right and down steps only, that are nonintersecting but may kiss/osculate by pairs at fully marked vertices: the corresponding six local configurations are depicted on the second row of figure 1 . The osculating path formulation is well adapted to the tangent method as we shall see below. For illustration, we have represented in figure 2 a sample 6 V DWBC configuration both in the arrow (a) and osculating path (b) formulations.

212 6V model with U-turn boundary and 6V model. Kuperberg considered different symmetry classes of ASM, which in turn correspond to different variations around the 6V-DWBC model [Kup02]. In particular he found a remarkable connection between vertically symmetric ASMs (VSASM) and the 6 V model with so-called U-turn boundary conditions ( $6 \mathrm{~V}-\mathrm{U}$ ), also considered independently by Tsuchiya [Tsu98]. The 6V-U model is defined on a rectangular grid of square lattice of size $2 n_{\searrow} n$ with the usual DWBC along the $\mathrm{N}, \mathrm{S}$ boundaries (each with $n$ outgoing vertical arrows) and E boundary (with $2 n$ entering horizontal arrows), while the W boundary has U-turns connecting the $2 n$ horizontal boundary edges (which we label $0,1,2, \ldots, 2 n-1$ from bottom to top) by $n$ consecutive pairs ( $2 i, 2 i+1$ ), $i=0,1,2, \ldots, h^{2}$ (see figure 3(a) for an illustration). Each U-turn transmits the arrow orientation through the marked dot. The horizontal lines connected by a U-turn receive horizontal spectral parameters - $u_{i}$ (even label $2 i$ ) and $u_{i}$ (odd label $2 i+1$ ), while vertical spectral parameters are denoted by $v_{i}, i=1,2, \ldots, n$ from left to right. As before, we consider the disordered regime, with trigonometric weights depending on horizontal and vertical spectral parameters as in the case of the $6 \mathrm{~V}-\mathrm{DWBC}$ model. The local weights, say at the intersection of a horizontal line with spectral parameter $u$ and vertical line with spectral parameter $v$ are:

$$
\begin{equation*}
a_{o}=\rho_{o} \sin (u-v+\eta), \quad b_{o}=\rho_{o} \sin (u-v-\eta), \quad c_{o}=\rho_{o} \sin (2 \eta) \tag{2.7}
\end{equation*}
$$

on odd rows, while we must apply the transformation $u \rightarrow-u$ on even rows, resulting in:

$$
\begin{equation*}
a_{e}=\rho_{e} \sin (\eta-u-v), \quad b_{e}=\rho_{e} \sin (-u-v-\eta), \quad c_{e}=\rho_{e} \sin (2 \eta) \tag{2.8}
\end{equation*}
$$

and where the overall constant factors $\rho_{o}, \rho_{e}>0$ emphasize the projective character of the weights. Finally, U-turns receive weights:

$$
\begin{equation*}
y_{\mathrm{u}}(u)=-\sin (u-\vartheta+\eta) \quad y_{\mathrm{d}}(u)=\sin (u+\vartheta+\eta) \tag{2.9}
\end{equation*}
$$

according to whether the transmitted arrow goes up or down. We must further constrain $u, v, \vartheta$ so that the weights of configurations of the $6 \mathrm{~V}-\mathrm{U}$ model are positive. A natural choice is $0<\vartheta<\frac{\pi}{2}$ and the following domain for the $u, v, \eta$ parameters:

$$
\begin{equation*}
\eta<u-v<\pi-\eta, \quad \eta-\pi<u+v<-\eta, \quad 0<\eta<\frac{\pi}{2} . \tag{2.10}
\end{equation*}
$$

For the purpose of this paper, we will consider the uniform case, where all horizontal odd spectral parameters are equal with value $u_{i}=u$ for all $i$, and all vertical ones are equal, with value $v_{j}=v$ for all $j$, so that weights of odd/even rows are given by (2.7) and (2.8) respectively. Moreover, we pick $\vartheta=-u-\eta$, thus enforcing that at each U-turn the arrows go up ${ }^{3}$. Dividing each U-turn into two horizontal edges, we now obtain arrows that alternate in/out along the W boundary (as shown in figure $3(\mathrm{~b})$ ). Note that the bottom row of vertices has all its edge orientations fixed by the ice rule. Upon dividing by the corresponding product of local even $b$-type weights, we may safely remove the $n$ vertices of the bottom line. After dividing by the weights of the removed vertices and U-turns, we are left with the 6 V model on a rectangular grid of square lattice with size $2 n-1 \times n$, and with usual DWBC along the N, E, S boundaries, while arrows alternate in/out from bottom to top along the W boundary (as depicted in figure 3(c)). Note that the rows are now labeled $1,2, \ldots, 2 n-1$ from bottom to top. By lack of a better name, we shall refer to this model as the $6 \mathrm{~V}^{\prime}$ model, and denote by $Z_{n}^{6 \mathrm{v}^{\prime}}[u, v]$ the corresponding homogeneous partition function. Similarly to the 6V-DWBC case, this partition function enjoys a reflection symmetry property:

$$
\begin{equation*}
Z_{n}^{6 \mathrm{v}^{\prime}}[-u,-\pi-v]=Z_{n}^{6 \mathrm{v}^{\prime}}[u, v] \tag{2.11}
\end{equation*}
$$

Indeed, like in the 6 V case, applying a reflection w.r.t. a horizontal line to the rectangular domain interchanges vertices of type $a_{\circlearrowleft} b_{o}$ and $a_{e} b_{e}$ while $c$-type vertices are unchanged. The same result is obtained in the original setting by applying the transformation $(u, v)(\rightarrow u,-\pi-k)$, which leaves the domain (2.10) invariant, and (2.11) follows.

We now examine a few 'combinatorial points' in parameter space, where the partition function of the $6 \mathrm{~V}^{\prime}$ model has some known combinatorial interpretations. Similarly to the 6 V DWBC case, the enumeration of VSASM is realized [Kup02] at the 'VSASM point' of the 6 V ' model, where all weights are equal to 1 , namely:

$$
\begin{equation*}
\eta=\frac{\pi}{6}, \quad u=0, \quad v=-\frac{\pi}{2}, \quad \rho_{o}=\rho_{e}=\frac{1}{\cos (\eta)} \tag{2.12}
\end{equation*}
$$

[^2]

Figure 4. (a) A sample configuration of the $6 \mathrm{~V}^{\prime}$ model (for $n=5$ ) and (b) its reformulation in terms of osculating paths.
$\rightarrow \rightarrow \rightarrow+\rightarrow \rightarrow+\infty \rightarrow+\infty \rightarrow+\infty$
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$$








Figure 5. The twenty vertex environments obeying the ice rule on the triangular lattice (top two rows) together with their osculating Schröder path reformulation (bottom two rows).
while the refined enumeration corresponds to [Kup02]:

$$
\begin{equation*}
u=0, \quad v=-\frac{\pi}{2}, \quad \rho_{o}=\rho_{e}=\frac{1}{\cos (\eta)}, \quad \tau=4 \sin ^{2}(\eta) \tag{2.13}
\end{equation*}
$$

with even and odd weights $\left(a_{i}, b_{i}, c_{i}\right)=\left(1,1,{ }^{\prime} \bar{\tau}\right)$, with the particular cases of 1,2,3enumeration of VSASM corresponding respectively to $\eta=\frac{\pi}{6}, \frac{\pi}{4}, \frac{\pi}{3}$. The ' $20 \mathrm{~V}-\mathrm{DWBC} 3$ point' is another interesting combinatorial point, which corresponds to the identification of the


Figure 6. (a) A sample configuration of the 20 V model with DWBC3 on the quadrangle $\mathrm{Q}_{n}$ (with $n=9$ here) and (b) its osculating Schröder path reformulation.
number of 20 V DWBC3 configurations on $\mathrm{Q}_{n}$ in terms of $6 \mathrm{~V}^{\prime}$ DWBC [DF21], with the choice:

$$
\begin{equation*}
\eta=\frac{\pi}{8}, \quad u=\frac{\pi}{8}, \quad v=-\frac{\pi}{2}, \quad \rho_{o}=\rho_{e}={ }^{\sqrt{ }} \overline{2} . \tag{2.14}
\end{equation*}
$$

Like in the $6 \mathrm{~V}-\mathrm{DWBC}$ case, the configurations of the model may be rephrased in terms of osculating paths. Using the same recipe, we see that configurations are in bijection with families of $n$ osculating paths, starting at odd horizontal edges along the W boundary, and ending at all vertical edges along the $S$ boundary. For illustration, we have represented in figure 4 a sample $6 \mathrm{~V}^{\prime}$ configuration both in the arrow (a) and osculating path (b) formulations.

The U-turn $6 \mathrm{~V} / 6 \mathrm{~V}^{\prime}$ model thermodynamic free energy was derived in reference [RK15], boundary correlations were studied in [PR19b], and arctic curves were derived in the VSASM case [DFL18] and in the particular free fermion case corresponding to $\eta=\frac{\pi}{4}, u=0$, $v=-\frac{\pi}{2}$ [PR19a].
21.3. 20 V model with DWBC3. The 20 V model is a two-dimensional ice-type model defined on the triangular lattice. As in the 6 V case, edges are oriented in such a way that at each vertex there are exactly three incoming and three outgoing arrows. This gives rise to the ${ }_{3}^{6}=20$ local vertex configurations depicted in figure 5. Recently this model was considered with special boundary conditions [DFG18] emulating DWBC on some particular domains. For simplicity, the triangular lattice is represented with vertices in $Z^{2}$, and edges of the square lattice are supplemented by the second diagonal of each square face. Edges are accordingly called horizontal, vertical and diagonal.

In reference [DFG18], four types of boundary conditions (DWBC1, 2, 3, 4) were considered on an $n \times n$ square grid in this representation, with remarkable combinatorial properties. The


Figure 7. The seven classes of vertices of the 20 V model (in osculating Schröder path formulation), and their corresponding weights $\omega_{i}, i=0,1,2, \ldots, 6$.


Figure 8. (a) A sample domino tiling of the Aztec triangle $\mathrm{T}_{n}$ (here for $n=6$ ) and (b) its non-intersecting Schröder path formulation. The dictionary for the path steps (horizontal, vertical, empty, diagonal) is indicated for each of the four (bicolored) domino configurations.

DWBC1, 2 are closest to the 6V-DWBC, and correspond to arrows entering the domain on the W and E boundaries, and exiting on the N and S boundaries, with a particular choice of the NW and SE corner diagonal edges as belonging to the W and S boundaries respectively (DWBC1) or to the N and E (DWBC2). The DWBC3 is a more relaxed version of DWBC, where only the horizontal arrows point toward the domain on the W boundary, and only vertical arrows point outward on the S boundary, while all other arrows point outward on W and N , and inward on $S$ and $E$. In [DFG18], a family of pentagonal extensions of the grid was considered, and the corresponding 20 V configurations were conjectured to correspond to the domino tilings of special domains, viewed as truncations of the Aztec triangle. The conjecture was proved in [DF21] for the maximal extension, namely the 20 V model with DWBC3 on the quadrangle $\mathrm{Q}^{n}$ of shape $n \times{ }^{n} \times(2 n-1) \times n$ (see figure 6(a) for an illustration), whose partition function was shown to be identical to that of domino tilings of the Aztec trianglq ${ }_{n}$ (see figure 8(a)). In the present paper, we shall concentrate on this model.

Like in the 6 V case, we may rephrase the arrow configurations of the 20 V model in terms of osculating paths with horizontal, vertical and diagonal steps along the corresponding edges of the lattice (these are usually called Schröder paths). This is done similarly by picking a base orientation (right, down, and diagonal down and right) of all the edges of the lattice, and marking only those edges of a given configuration of the 20 V model that agree with it. The selected edges are assembled again into non-intersecting, but possibly kissing paths traveling to the right and down. We have represented in figure 5 (bottom two rows) the 20 local path configurations at a vertex corresponding to the 20 arrow configurations (top two rows). In the
osculating Schröder path formulation, the DWBC3 onQ gives rise to families of $n$ osculating paths starting at the $n$ odd horizontal edges along the W boundary, and ending at the $n$ vertical edges of the diagonal SW boundary, as displayed in figure 6(b).

As detailed in [DFG18, Kel74], the model receives integrable weights inherited from those of the 6 V model upon resolving the triple intersections of spectral parameter lines at each vertex into three simple intersections corresponding to three 6 V models on three distinct lattices. Integrability was used in [DF21] to transform the partition function of the 20V DWBC3 model into that of a $6 \mathrm{~V}^{\prime}$ model, for a particular normalization of spectral parameters of the 20 V model. With this normalization, the seven local vertex weights corresponding to the dictionary of figure 7 read respectively:

$$
\begin{align*}
& \omega_{0}=v \sin (u-v+\eta) \sin (\eta-u-v) \sin (2 u+2 \eta) \\
& \omega_{1}=v \sin (u-v-\eta) \sin (-u-v-\eta) \sin (2 u+2 \eta) \\
& \omega_{2}=v \sin (u-v-\eta) \sin (2 u+2 \eta) \sin (2 \eta) \\
& \omega_{3}=v\left\{\sin ^{3}(2 \eta)+\sin (u-v+\eta) \sin (-u-v-\eta) \sin (2 u)\right\},  \tag{2.15}\\
& \omega_{4}=v \sin (2 u+2 \eta) \sin (\eta-u-v) \sin (2 \eta) \\
& \omega_{5}=v \sin (u-v-\eta) \sin (\eta-u-v) \sin (2 \eta) \\
& \omega_{6}=v \sin (u-v-\eta) \sin (\eta-u-v) \sin (2 u)
\end{align*}
$$

where again the fixed overall factor $v>0$ emphasises the projective nature of the weights. Note that each vertex is the intersection of three lines (horizontal, vertical, diagonal) each of which carries a spectral parameter $(\eta+u, v, u$ respectively). The domain of parameters ensuring positivity of the weights is:

$$
\begin{equation*}
0<u<\frac{\pi}{2}-\eta \quad \eta<u-v<\pi-\eta \quad \eta<-u-v<\pi-\eta \quad 0<\eta<\frac{\pi}{2} \tag{2.16}
\end{equation*}
$$

(Note the similarity with the domain (2.10) for the $6 \mathrm{~V}^{\prime}$ model, the only extra condition being that $u>0$ ).

Note the existence of a combinatorial point where the weights are uniform and all equal to 1 :

$$
\begin{equation*}
\eta=\frac{\pi}{8}, \quad u=\frac{\pi}{8}, \quad v=-4 \eta=-\frac{\pi}{2} \quad v=\sqrt{ }- \tag{2.17}
\end{equation*}
$$

identical to the $20 \mathrm{~V}-\mathrm{DWBC} 3$ point of the $6 \mathrm{~V}^{\prime}$ model, where the partition functions of both models are related [DF21].
21.4 Domino tilings of the Aztec triangle. Our fourth class of objects is the tiling configurations by means of $2 \times 1$ dominos of the 'Aztec triangle' of order $n$ [DF21, DFG18], denoted $T_{n}$, depicted in figure 8(a). The identity between the number of 20V-DWBC3 configurations on $\mathrm{Q}_{n}$ and the number of domino tilings of the Aztec triangle $\Gamma_{n}$ was conjectured in [DFG18] and proved in [DF21]. In section 6 below, we will make use of this correspondence to determine the limit shape of typical domino tilings of $T_{\mathrm{F}}$ for large $n$.

It proves useful to rephrase the domino tiling problem in terms of non-intersecting lattice paths, as indicated in figure 8(b), where the indicated dictionary between bi-colored dominos and path steps has been used to reexpress bijectively the tiling configuration into a family of non-intersecting lattice paths with fixed ends on the diagonal NW and $S$ boundaries of the domain. As indicated, the paths may have horizontal, vertical and diagonal steps and are therefore non-intersecting Schröder paths.


Figure 9. Application of the tangent method to determine the NE branch of the arctic curve, illustrated for the four models studied in this paper: $6 \mathrm{~V}-\mathrm{DWBC}$ (top left), $6 \mathrm{~V}^{\prime}$ (bottom left), 20V-DWBC3 (top right) and domino tilings of the Aztec triangle (bottom right). In all cases, the endpoint of the topmost path is displaced from its original position (white dot) to the right, at some distance / (red dot). The partition function splits into the modified partition function of the model $Z_{n, k}$ with exit point at position $k$ (pink domain) and that, $Y_{k, l}$, of a single path from the exit point to the displaced endpoint with the same ambient weights (light blue domain). The tangent method uses the most likely position $k=k(I)$ namely the one giving the largest contribution to the total partition function. The relevant portion of arctic curve is given by the envelope of the family of lines through $(I, 0)$ and $(0, k(I))$ (the green and red points), in rescaled coordinates with the origin at the SE corner of the original domain. All dimensions are expressed in units of the underlying lattice grid.

## 22 Tangent method: combining one-point functions and paths

This section details how the tangent method of [CS16] works and how we are going to apply it to the four models studied in this paper: the 6 V -DWBC, $6 \mathrm{~V}^{\prime}, 20 \mathrm{~V}$-DWBC3 and finally the domino tiling of the Aztec triangle, all expressed in the (possibly osculating) path formulation.
221. The tangent method. As explained in the introduction, the tangent method consists in finding the most likely exit point from the original domain of the topmost path, given that its end has been displaced away from the domain. To determine this point, we consider the full partition function $\Sigma_{n, l}$ of the model, which is made of two pieces (corresponding respectively to the pink and light blue domains in figure 9):
. The modified partition function $Z_{n, k}$ for the set of $n$ weighted paths in the original domain, with the (topmost) $n$th path constrained to exit the domain along the E border at a fixed height $k$ (green dot in figure 9), normalized into the 'refined one-point function'
$H_{n, k}=Z_{n, k} / Z_{n}$.

- The partition function $Y_{k, l}$ of a single weighted path constrained to start at the previous exit point and end at a fixed endpoint (displaced at distance $/$ from its original position, second green dot in figure 9).
The full partition function reads: $\Sigma_{n, I}=\sum_{k n} H_{n, k} Y_{k, I}$, where $\mu=1$ for the 6 V -DWBC and the domino tiling models, and $\mu=2$ in the other models. Note that all weights (including those of the single path) are those of the underlying vertex model; in particular, the vertices not visited by the single path (in the light blue zones of figure 9) receive the weight of the empty vertex configuration.

Next we go to the large $n=N$ scaling limit and use large $N$ estimates of both partition functions to find the leading contribution to the sum in $\Sigma_{n, I}$. More precisely, setting $n=N$, $I=\lambda N$, the limiting solution of the saddle-point approximation to the sum, in the form of some function $\kappa(\lambda)$ where $k(I)=\mu N \kappa(\lambda)$ is the most likely position of the exit point. The (rescaled) arctic curve is then obtained as the envelope of the family of lines through the most likely exit point and the fixed endpoint, both functions of the parameter $\lambda$. More precisely, we must estimate the large $N$ behavior of the total partition function $\Sigma_{n, i}$ :

$$
\Sigma_{N, \lambda N} \quad \mu N \int_{0}^{1} \mathrm{~d} \kappa H_{N, \mu \kappa N} Y_{\mu \kappa N, \lambda N},
$$

where we have replaced the summation by an integral over the rescaled variable $\kappa=k /(\mu N)$. In sections 3-6 below, we work out the explicit asymptotics of both functions in the integrand, in the form $H_{N, \mu \kappa N} \quad \mathrm{e}^{N S_{\mathrm{H}}(k)}$ and $Y_{\mu \kappa N, \lambda_{N}} \quad \mathrm{e}^{N S_{Y}(k)}$. The leading contribution to the integral comes from the solution $\kappa=\kappa(\lambda)$ to the saddle-point equation $\partial_{\kappa} S_{\mathrm{H}}+\partial_{\kappa} S_{Y}=0$. This gives the most likely exit point $(0, \mu \kappa(\lambda))$ (in rescaled variables). The tangent line in rescaled variables is the line through $(0, \mu \kappa(\lambda))$ and $(\lambda, 0)$, with equation

$$
\begin{equation*}
y+A x_{-} B=0, \quad A=\frac{\mu \kappa(\lambda)}{\lambda}, \quad B=\mu \kappa(\lambda) . \tag{2.18}
\end{equation*}
$$

As we shall see, the family of tangent lines is best described in terms of the parameter $\xi$ (the deviation from uniform vertical spectral parameter in the last (E-most) column $v_{n}=v+\xi$. In particular the relationship between $\lambda$ and $\kappa(\lambda)$ takes the parametric form: $(\kappa(\lambda), \lambda)=(\kappa[\xi], \lambda[\xi])$, for $\xi \in I, I$ an interval determined by the conditions that $\lambda[\xi]>0$ and $\kappa[\xi] \in[0,1]$. The envelope of the family of lines

$$
\begin{equation*}
F_{\xi}(x, y):=y+A[\xi] x-B[\xi]=0 \tag{2.19}
\end{equation*}
$$

is determined as the solution of the linear system $F_{\xi}(x, y)=\partial_{\xi} F(x, y)=0$, and gives rise to the parametric equations for the arctic curve:

$$
\begin{equation*}
x=X[\xi]:=\frac{B^{\prime}[\xi]}{\overline{A^{\prime}[\xi]}}, \quad y=Y[\xi]:=B[\xi]-\frac{A[\xi]}{A^{\prime}[\xi]} \quad(\xi \in I) . \tag{2.20}
\end{equation*}
$$

By the geometry of the problem, only a portion of the arctic curve can be obtained in this way: moving the exit point to the right along the line through all other exit points covers a portion of arctic curve between a point of tangency to the E vertical border of the original domain (when the endpoint tends to its original position) and a point of tangency to the horizontal N border of the domain (when the endpoint tends to infinity on the right along the line), or equivalently corresponding to the slope $A\left[\xi \in\left[0, \infty_{\infty}\right.\right.$ This condition was used to restrict the domain of the variable $\xi \mathcal{E}$. This portion of arctic curve is on the NE corner of the domain, and we shall refer to it as the NE branch of the arctic curve.


Figure 10. From NE to SE branch in the $6 \mathrm{~V}^{\prime}$ model: (a) configuration of the $6 \mathrm{~V}^{\prime}$ model (b) after application of the VF (c) after application of the reflection (R), leading to another $6 \mathrm{~V}^{\prime}$ configuration, with weights of $a_{i}$ and $b_{i}$ types interchanged for $i=e, o$.

The case of the domino tiling of the Aztec triangle is simpler: as a (free fermion) dimer model, it is expected on general grounds [KOS06] to have an analytic arctic curve, equal to the analytic continuation of its NE branch. As we shall see, the cases of 6 V -DWBC, $6 \mathrm{~V}^{\prime}$ and 20V-DWBC3 are more involved, and lead in general to non-analytic arctic curves.

222 Other branches. To reach other portions of the arctic curve, we will have to resort to various tricks, all based on the same principle: we switch to a different interpretation of the configurations of the original model, to express them in terms of different families of paths, to which the tangent method can be applied again.
2221. 6V-DWBC and 6 V cases.In the case of the $6 \mathrm{~V}-\mathrm{DWBC} / 6 \mathrm{~V}^{\prime}$ model arctic curves, we have access to the SE branch by reinterpreting the 6 V configurations in terms of paths with the same starting points (every point/every other point along the W vertical border) but with endpoints along the N border (see figures 10 (a) and (b) for an illustration in the $6 \mathrm{~V}^{\prime}$ case). This corresponds to redefining the base orientation of edges (and direction of travel of the paths) to be to the right and up: we call this transformation on the paths vertical flip (VF). The osculation at each vertex must be redefined so that all paths now go horizontally right and vertically up. The SE branch of the arctic curve is obtained by applying the tangent method to this new family of paths. The easiest way to do so is to reflect the picture w.r.t. a horizontal line, so that the setting is that of the $6 \mathrm{~V}^{\prime}$ model again: we call this transformation reflection $(\mathbf{R})$ as shown in figure 10(c). The net effect of the composition of VF followed by $\mathbf{R}$ on the model is simply to interchange the $a$ and $b$ type weights, a transformation also implemented by the involution * acting on the spectral parameters as follows:

$$
\begin{align*}
& u \rightarrow u^{*}=\pi-u \quad(6 \mathrm{~V}-\mathrm{DWBC})  \tag{2.21}\\
& (u, v) \rightarrow\left(u^{*}=-u, v^{*}=-\pi-v\right) \tag{2.22}
\end{align*}
$$



Figure 11. The shear trick: (a) configuration of the 20V-DWBC3 (b) after application of the VF (c) after application of the reflection (R) (d) after the shear transformation (S).

This gives rise ${ }^{4}$ to the new weights $a^{*}=b, b^{*}=a, c^{*}=c(6 \mathrm{~V}-\mathrm{DWBC})$ or $a_{i}^{*}=b_{i}$, $b_{i}^{*}=a_{i}, c_{i}^{*}=c_{i}, i=o, e\left(6 \mathrm{~V}^{\prime}\right)$.

The 'upside-down' one-point function must also be reinterpreted as $H_{n, k}=H_{n, \mu n-k}^{*}$ where the latter is computed with the new transformed weights. Similarly, the path partition function $Y_{k, I}$ with starting point $(0, k)$ and endpoint $(\boldsymbol{I}, 0)$ is reinterpreted as the partition function $Y_{\mu n-k, I}^{*}$ with the new weights. More precisely setting the origin of the rescaled domain at the SE corner of the domain, the vertices of the rescaled domain are: SE: $(0,0), \mathrm{NE}:(0, \mu)$, NW: $(-1, \mu)$, SW: $(-1,0)$. The large $n=N$ optimization problem leading to the most likely exit point $(0, \mu \kappa(\lambda))$ leads now to the most likely exit point $\left(0, \mu\left(+\kappa^{*}(\lambda)\right)\right)$ and the associated family of rescaled lines. The SE branch of arctic curve is obtained by reflecting back the envelope of this family, and effectively amounts to applying * to the NE branch and reflecting it w.r.t. the line $y=\mu / 2$, namely applying the transformation

$$
\begin{equation*}
(x, y) \mapsto(x, \mu-y) \tag{2.23}
\end{equation*}
$$

with $\mu=1$ for the 6 V -DWBC model, and $\mu=2$ for the $6 \mathrm{~V}^{\prime}$ model.
2222 20V-DWBC3 case In the case of the 20V-DWBC3 model illustrated in figure 11(a), the same idea leading to the SE branch must be adapted (by adapting the 'shear trick' devised in reference [DDFG20]). More precisely, as in the $6 \mathrm{~V}-\mathrm{DWBC}$ and $6 \mathrm{~V}^{\prime}$ cases, we first redefine the base edge orientation so that horizontal/diagonal edges point right/down, but vertical edges point up. Alternatively, compared to the original base orientation, this simply interchanges vertical edges which are occupied by path steps with vertical edges which are empty and vice versa (like in the $6 \mathrm{~V}, 6 \mathrm{~V}^{\prime}$ cases, we call this $\mathbf{V F}=\mathrm{VP}$, see figure $11(\mathrm{~b})$ ). The osculation at each vertex must be redefined so that all paths now go horizontally right, diagonally down and vertically up: in particular the paths now end on the $n$ vertical edges of the N boundary (see figure 11(b)). To match this with a 20 V configuration of $\mathbb{Q}^{2}$, we must reflect the configuration w.r.t. a horizontal line (we call this again $\mathbf{R}=$ reflection, see figure 11(c)). However, the quadrangular domain $\mathrm{Q}_{n}$ is not invariant under horizontal reflection: to recover it, we apply a shear transformation as indicated in figure 11(d) (we call this $\mathbf{S}=$ shear). More precisely setting the origin

[^3]of the rescaled domain at the SE corner of the domain, the vertices of the rescaled quadrangle $\mathbb{Q} / N$ are: SE:( 0,0 ), NE:( 0,2 ), NW:( 4,2 ), SW:( 4,1$)$. Applying successively (in rescaled variables $(x, y)$ ) the reflection $(x, y) \rightarrow(x,-y)$, shear $(x, y) \rightarrow\left(x, y_{-} x\right)$, and finally translation by $(0,2)$ leaves the domain invariant, but effectively flips the orientation of the vertical edges in the 20 V -DWBC3 configuration. Note that the final configuration after application of VF, $R, S$ (figure 11(d)) is slightly different from a 20 V -DWBC3 configuration, as all the starting steps along the W boundary are diagonal, as opposed to horizontal. This clearly makes no difference in the case of uniform weights, however for non-uniform weights this changes the weights along the W boundary. We argue nonetheless that this mild boundary effect does not affect the asymptotic behavior of bulk quantities as all other weights are the same in both situations. In particular, we expect the arctic curve to be the same in the original 20V-DWBC3 model with horizontal starting steps along the W boundary, and in the modified one, where all starting steps are diagonal.

Let us now examine the fate of the local vertex environments of figure 7 under the sequence of transformations $\mathbf{V F}, R, S$. It is easy to see that under this transformation the types of vertices are mapped as follows: $\omega_{0} \leftrightarrow \omega_{1}, \omega_{2} \leftrightarrow \omega_{4}$, while all other types are preserved. For illustration, the top left vertex of type $\omega_{2}$ of figure 7 is successively transformed into the top left vertex of type $\omega_{4}$ as follows:


We finally note that the involution $*$ which maps the weights $\left(\omega_{0}, \omega_{1}, \omega_{2}, \omega_{3}, \omega_{4}, \omega_{5}, \omega_{6}\right) \mapsto$ ( $\omega_{1}, \omega_{0}, \omega_{4}, \omega_{3}, \omega_{2}, \omega_{5}, \omega_{6}$ ) is simply given by

$$
\begin{equation*}
(u, v)>\rightarrow\left(u^{*}, v^{*}\right)=(u,-v-\pi) \quad(20 \mathrm{~V}-\mathrm{DWBC} 3) . \tag{2.24}
\end{equation*}
$$

As before, we have to reinterpret $H_{n, k}=H_{n, 2 n \_k}^{*}$ and $Y_{k, I}=Y_{2 n k, I}^{*}$ leading to the most likely exit point $2 N\left(1-\kappa^{*}(\lambda)\right)$ in rescaled variables $\kappa=k /(2 N)$ and $\lambda=I / N$. The SE branch is finally obtained by applying the reflection/shear/translation $(x, y) \perp_{-}\left(x, 2 \quad-x_{-} y\right)$ to the NE one after applying *, namely changing $\downarrow v-\pi$.-

This gives access to the SE branch in all 6V-DWBC, 6V' and 20V-DWBC3 cases. Except in the free fermion cases, where arctic curves are expected to be analytic, we have no prediction for other portions of arctic curve when they exist.

## 3. 6 V model

## 31. Partition function and one-point function

31.1. Inhomogeneous partition function. A general result [ICK92] provides a determinant formula for the partition function $Z_{n}^{6 \mathrm{~V}}[\mathbf{u}, \mathbf{v}]$ of the inhomogeneous 6 V -DWBC model, with horizontal/vertical spectral parameters $\mathbf{u}=u_{1}, u_{2}, \ldots, u_{n} / \mathbf{v}=v_{1}, v_{2}, \ldots, v_{n}$.

Theorem 3.1. Let

$$
m(u, v):=m\left(u_{-} v\right):=\frac{1}{\sin (u-v+\eta) \sin (u-v-\eta)}
$$

The full inhomogeneous $6 V-D W B C$ partition function reads:

$$
\begin{equation*}
Z_{n}^{6 \mathrm{~V}}[\mathbf{u}, \mathbf{v}]=\rho^{n} \sin ^{n}(\eta) \operatorname{det}_{1 \leq i, j \leq n} m\left(u_{i}, v_{j}\right)^{n}-\frac{i, j=1 \sin \left(u_{i}-v_{j}+\eta\right) \sin \left(u_{i}-v_{j}-\eta\right)}{1 \leq i<j \leq n \sin \left(u_{i}-u_{j}\right) \sin \left(v_{j}-v_{i}\right)} . \tag{3.1}
\end{equation*}
$$

312 Homogeneous limit. The homogeneous limit $Z^{6 \mathrm{~V}}{ }_{[ }[u-v]$ of the inhomogeneous partition function $Z_{n}^{6 \mathrm{~V}}[\mathbf{u}, \mathbf{v}]$ in which $u_{i} \rightarrow u$ and $v_{i} \rightarrow v$ for all $i$ involves the quantity

Using Taylor expansion of rows and columns leads to the determinant

$$
D_{n}[u]=\operatorname{det}_{0 \leq i, j \leq n-1} \partial_{u}^{i+j} m(u) .
$$

This determinant obeys a simple quadratic relation as a consequence of Plücker/Desnanot-Jacobi relations (up to some permutation of rows and columns) relating a determinant to some of its minors of size 1 and 2 less, summarized in the following lemma.

Lemma 3.2. Given an $n+1 \times n+1$ square matrix $M$, its determinant $|M|$ and minors $|M|^{b}$ (with row a and column b removed), and $|M|_{a_{1}, a_{2}}^{b_{1}, b_{2}}$ (with rows $a_{1}, a_{2}$ and columns $b_{1}, b_{2}$ removed are related via:

$$
|M| \times|M|_{n, n+1}^{n, n+1}=|M|_{n}^{n} \times|M|_{n+1}^{n+1}-|M|_{n+1}^{n} \times|M|_{n}^{n+1} .
$$

Applying this to the matrix $M=\mathrm{d}_{l}^{i+j_{m}} m(u)_{0 \leq i, j \leq n}$, we easily get

$$
D_{n+1}[u] D_{n-1}[u]=\underset{u}{D_{n}[u] \partial^{2} D_{n}[u]-\left(\partial_{u} D_{n}[u]\right)^{2}}=D_{n}[u]^{2} \partial^{2} \log \left(D_{n}[u]\right) .
$$

As a direct consequence, we have

Theorem 3.3. The quantity $\Delta_{n}[u]$ obeys the following recursion relation for all $n \geq 1$ :

$$
\begin{equation*}
\frac{\Delta_{n+1}[u] \Delta_{n-1}[u]}{\Delta_{n}[u]^{2}}=\frac{1}{\bar{n}^{2}}{ }_{u}{ }^{2} \log \left(\Delta_{n}[u]\right) \tag{3.3}
\end{equation*}
$$

with the convention that $\Delta_{0}[u]=1$.
Note that this relation determines $\Delta_{n}[u]$ recursively, from the initial data $\Delta_{0}[u]=1$ and $\Delta_{1}[u]=m[u]$. Finally the homogeneous partition function $Z_{n}^{6 \mathrm{~V}}[u, v]$ is expressed as

$$
\begin{equation*}
\frac{Z_{n}^{6 \mathrm{~V}}[u-v]}{\sin ^{n}(2 \eta)}=\Delta_{n}[u-v](\rho \sin (u-v+\eta) \sin (u-v-\eta))^{n} .^{2} \tag{3.4}
\end{equation*}
$$

31.3 One-point function. We now consider a slightly more general limit, in which we take $u_{1}, u_{2}, \ldots, u_{n} \rightarrow u$ and $v_{1}, v_{2}, \ldots, v_{n-1} \rightarrow v$ but the last vertical spectral parameter is kept
arbitrary, say $v_{n}=w=v+\xi$. The corresponding partition function $Z_{n}^{6 \mathrm{~V}}[u-v ; \xi]$ is again obtained as a limit of the inhomogeneous formula (3.1). We have

$$
\begin{align*}
\frac{Z^{6 \mathrm{~V}}[u-v ; \xi]}{\sin ^{n}(2 \eta)}= & \Delta_{n}[u-v ; \xi](\rho \sin (u-v+\eta) \sin (u-v-\eta))^{n(n-1)} \\
& \times(\rho \sin (u-v-\xi+\eta) \sin (u-v-\xi-\eta))^{n}
\end{align*}
$$

in terms of a function

$$
\begin{aligned}
& \Delta_{n}[u-v ; \xi]:=\lim _{\substack{u_{1}, u_{2} m_{n}, m_{n-u} \\
v_{1}, v_{2}, v_{n}+1 \\
v_{n} \rightarrow v+\xi}} \frac{\operatorname{det}_{1 \leq i, j \leq n} m\left(u_{i}-v_{j}\right)}{1 \leq i<j \leq n \sin \left(u_{i}-u_{j}\right) \sin \left(v_{j}-v_{i}\right)} \\
& =: \frac{(-1)^{n-1}(n-1)!}{\sin ^{n-1}(\xi) \quad \substack{n-1 \\
i=(i!)^{2}}} D_{n}[u-v ; \xi] \text {, }
\end{aligned}
$$

where

$$
\begin{equation*}
D_{n}[u ; \xi]=\operatorname{det} \quad\left\{\delta_{u}^{i+j} m(u)\right\}_{\substack{0 \leq i \leq n-1 \\ 0 \leq j \leq n-2}}\left\{\partial^{i}{ }_{l} m(u-\xi)\right\}_{0 \leq i \leq n-1} \tag{3.6}
\end{equation*}
$$

identical to $D_{n}[u]$ except for its last column.
We define the 'one-point function' as the ratio

$$
H_{n}^{6 \mathrm{~V}}[u ; \xi]:=\frac{Z_{n}^{6 \mathrm{~V}}[u ; \xi]}{Z^{6 \mathrm{~V}}[u]}=\frac{\Delta_{n}[u ; \xi]}{\Delta_{n}[u]} \frac{\sin (u-\xi+\eta) \sin (u-\xi-\eta)}{\sin (u+\eta) \sin (u-\eta)}{ }^{n} .
$$

Applying again lemma 3.2 this time with the matrix $M$ in the expression (3.6) for $D_{n+1}[u ; \xi]$, we find that

$$
\begin{equation*}
D_{n+1}[u ; \xi] D_{n-1}[u]=D_{n}[u] \partial_{u} D_{n}[u ; \xi]-D_{n}[u ; \xi] \partial_{u} D_{n}[u] . \tag{3.7}
\end{equation*}
$$

We also introduce the reduced one-point function

$$
\begin{equation*}
H_{n}[u ; \xi]:=(-1)^{n-1}(n-1)!\frac{D_{n}[u ; \xi]}{D_{n}[u]}=\sin ^{n-1}(\xi) \frac{\Delta_{n}[u ; \xi]}{\Delta_{n}[u]} \tag{3.8}
\end{equation*}
$$

in terms of which

$$
\begin{equation*}
H_{n}^{6 \mathrm{~V}}[u ; \xi]=\sin (\xi) H_{n}[u ; \xi] \frac{\sin (u-\xi+\eta) \sin (u-\xi-\eta)}{\sin (u+\eta) \sin (u-\eta) \sin (\xi)}{ }^{n} . \tag{3.9}
\end{equation*}
$$

The reduced one-point function is determined by the following relation, as a direct consequence of (3.7).

Theorem 3.4. The reduced one-point function $H_{n}[u ; \xi]$ of the $6 V-D W B C$ model satisfies the following relation:

$$
\frac{H_{n+1}[u ; \xi]}{H_{n}[u ; \xi]} \frac{\Delta_{n+1}[u] \Delta_{n=1}[u]}{\Delta^{n}[u]^{2}}+\frac{1}{{ }_{n}}+\frac{-}{\partial_{u}} \log \left(H_{n}[u ; \xi]\right)=0 .
$$

## 32 Large $n$ limit: free energy and one-point function asymptotics

In the following sections, we use the fact that the 6 V weights depend on the quantity $u-v$ only. Without loss of generality we shall set $v=0$ from now on.
321. Free energy. In this section, we reproduce an argument of [CP10a, KZJ00] leading to the large $n$ asymptotics of the partition function of the $6 \mathrm{~V}-\mathrm{DWBC}$ model.

The free energy per site $f^{6 \mathrm{~V}}[u]$ of the 6 V -DWBC model is defined via the large $n=N$ limit

$$
f^{6 \mathrm{~V}}[u]=-\lim _{N \rightarrow \infty} \frac{1}{N^{2}} \log \left(Z_{N}^{\mathrm{V}}[u]\right)
$$

or equivalently as the leading asymptotics $Z_{N}^{6 \mathrm{~V}}[u] \quad{ }_{N \rightarrow \infty} \mathrm{e}^{-N 2 f 6 \mathrm{~V}[u]}$. Substituting this into (3.4), we get:

$$
\begin{equation*}
f^{6 \mathrm{~V}}[u]=f[u]-\log (\rho \sin (u+\eta) \sin (u-\eta)) \tag{3.11}
\end{equation*}
$$

in terms of the limit

$$
f[u]:=-\lim _{N \rightarrow \infty} \frac{1}{N^{2}} \log \left(\Delta_{N}[u]\right)
$$

Finally, substituting the large $N$ asymptotics $\Delta_{N}[\mathrm{u}] \quad{ }_{N \rightarrow \infty} \mathrm{e}^{-N 2 f[u]}$ into (3.3) yields the following differential equation (1D Liouville equation)

$$
\mathrm{e}^{-2 f[u]}+\partial_{u}^{2} f[u]=0 .
$$

To fix the solution, let us derive some symmetry and some limit of $\Delta_{N}[u]$.
First note that the reflection symmetry $u \rightarrow \pi-u$ from (2.3), together with the relation (3.11) imply that

$$
f[\pi-u]=f[u] .
$$

Next let us consider the limit $u \rightarrow \eta$ of $\Delta_{n}[u]$. Setting $u=\eta+\epsilon$, we may perform the homogeneous limit (3.2) by setting $u_{i}=u+\epsilon x_{i}, v_{i}=\epsilon y_{i}$ (recall we have set $v=0$ ) and taking all $x_{i}, y_{i} \rightarrow 0$. We have for small $\epsilon$

$$
m\left(u_{i_{-}} \quad v\right)=\frac{1}{\epsilon \sin (2 \eta)\left(1+x_{i}-y_{j}\right)}+O(1)
$$

Using the Cauchy determinant formula, we find that


We deduce that

$$
\left.\lim _{N \rightarrow \infty}-\frac{1}{N^{2}} \log \left(\Delta_{N}[\eta+\epsilon]\right) ._{\epsilon \rightarrow 0} \log (\epsilon) \Rightarrow f[\eta+\epsilon] \right\rvert\, \epsilon \Theta \quad \log (\epsilon)
$$

Defining $W[u]:=\mathrm{e}^{f[u]}$, we find that $W$ satisfies the following conditions:
$W[u] \partial^{2} W[u]-\left(\partial_{u} W[u]\right)^{2}=. W[u] \quad \partial_{u} W[u]=1$
$\partial_{u} W[u] \quad \partial_{u}^{2} W[u]$

$$
W[\pi-u]=W[u], \quad W[\eta]=0 .
$$

The constant Wronskian condition implies that $W[u]$ obeys a second order linear differential equation, with general solution of the form $W[u]=\frac{\sin (\alpha u+b)}{\alpha}$. The parameter $B$ is fixed by the vanishing condition $W[\eta]=0$, and $\alpha$ by the symmetry condition $W[\pi-u]=W[u]$. We find the solution

$$
\begin{equation*}
W[u]=\frac{\sin (\alpha(u-\eta))}{\alpha}, \tag{3.12}
\end{equation*}
$$

where $\alpha(\pi-u-\eta)=\pi-\alpha(u-\eta)$, and finally

$$
\begin{equation*}
f[u]=\log \frac{\sin (\alpha(u-\eta))}{\alpha}, \quad \alpha=\frac{\pi}{\pi-2 \eta} \tag{3.13}
\end{equation*}
$$

Substituting this into (3.11), we finally get the thermodynamic free energy of the 6 V -DWBC model in the disordered regime:

$$
\begin{equation*}
f^{6 \mathrm{~V}}[u]=\quad \log \frac{\alpha \rho \sin (u+\eta) \sin (u-\eta)}{\sin (\alpha(u-\eta))} \tag{3.14}
\end{equation*}
$$

with $\alpha$ as in (3.13).
322 One-point function. We present now a simplified version of the argument given in [CP10a] to derive the asymptotics of the one-point function $H_{n}[u ; \xi]$. By equation (3.10) we may infer the large $n=N$ leading behavior of $H_{n}[u ; \xi]$ to be:

$$
\begin{equation*}
H_{N}[u ; \xi] \quad{ }_{N \rightarrow \infty} \mathrm{e}^{-N \psi[u ; \xi] .} \tag{3.15}
\end{equation*}
$$

Substituting this into (3.10) yields the differential equation:

$$
\mathrm{e}^{-\psi[u ; \xi]-2 f[u]}-\partial_{u} \psi[u ; \xi]=0 \Rightarrow \partial_{u} \mathrm{e}^{\psi[u ; \xi]}=\mathrm{e}^{-2 f[u]}
$$

Using the result (3.13) for $f[u]$, this is easily integrated into

$$
\mathrm{e}^{\psi[u ; \xi]}=c[\xi]-\alpha \cot (\alpha(u-\eta))
$$

for some integration constant $c[\xi]$ independent of $u$, and $\alpha$ as in (3.13). To fix the integration constant, let us consider the limit when $u-\xi-\eta \rightarrow 0$, by setting $\xi=u-\eta+\epsilon$ for a small $\epsilon \rightarrow 0$. Noting that

$$
\partial_{u}^{i} m[u-\xi]^{\}} \cdot{ }_{\xi=u-\eta+\epsilon}=-\frac{}{\sin (2 \eta) \epsilon^{i+1}}+O\left(\epsilon^{-i}\right)
$$

we see that the determinant for $D_{N}[u ; \xi]$ (3.6) is dominated by the term in the last row and column $i=j=N-1$, resulting in the leading behavior

$$
\begin{array}{ccc}
\underline{D}_{N}[u ; \xi] & -\underline{D}_{N=1}[u] & \\
D^{N}[u] & -(N-1)!\sin (2 \eta) \epsilon^{N} D^{N}[u] & (N-1)! \\
& \Rightarrow H_{N}[u ; u-\eta+\epsilon] \quad \frac{W^{2 N}}{\epsilon^{N}} \\
& \frac{W^{2}}{\epsilon \sin (u-\eta)}
\end{array}
$$

where we have used the defining relation (3.8) for $H_{N}[u ; \xi]$. Sending $\epsilon \rightarrow 0$, we conclude that

$$
\lim _{\xi \rightarrow u-\eta} \mathrm{e}^{\psi[u ; \xi]}=0
$$

This immediately gives $c[\xi]=\alpha \cot (\alpha \xi)$, and finally

$$
\begin{equation*}
\mathrm{e}^{\psi[u ; \xi]}=\frac{\alpha \sin (\alpha(u-\xi-\eta))}{\sin (\alpha \xi) \sin (\alpha(u-\eta))} \tag{3.16}
\end{equation*}
$$

Collecting all the above results, we finally get the asymptotics of the 6 V one-point function.

Theorem 3.5. The $6 V-D W B C$ one-point function $H_{n}^{6 \mathrm{~V}}[u ; \xi]$ has the following large $n=N$ behavior:

$$
\begin{aligned}
& H_{N}^{6 \mathrm{~V}}[u ; \xi] \quad \mathrm{e}^{-N \psi_{[u ; \xi]}^{6 \mathrm{~V}}} \\
& \psi^{6 \mathrm{~V}}[u ; \xi]=\quad \log \frac{\sin (\alpha \xi) \sin (\alpha(u-\eta)) \sin (u-\xi+\eta) \sin (u-\xi-\eta)}{\alpha \sin (\alpha(u-\xi-\eta)) \sin (\xi) \sin (u+\eta) \sin (u-\eta)}
\end{aligned}
$$

with $\alpha$ as in (3.13).

Proof. By the relation (3.9), we immediately get

$$
\psi^{6 \mathrm{~V}}[u]=\psi[u]+\log \frac{\sin (\xi) \sin (u+\eta) \sin (u-\eta)}{\sin (u-\xi+\eta) \sin (u-\xi-\eta)}
$$

and the theorem follows.
323. Refined partition functions and one-point functions. To apply the tangent method, we need the large $n, k$ asymptotics of the refined partition functions $Z_{n, k}^{6}[u], k=1,2, \ldots, n$, defined as follows. Given a configuration of $n$ osculating paths contributing to $Z_{n}^{6 \mathrm{~V}}[u]$ (with all horizontal spectral parameters equal to $u$ and all vertical ones to 0 ), let us focus on the topmost path: let us record the first visit of this path to the east-most vertical line, say at the intersection with the $k$ th horizontal line from the bottom. Note that the path accesses the last vertical via a horizontal step, and ends with $k$ vertical steps until the east-most endpoint. We define the refined partition functions $Z_{n, k}^{6 \mathrm{~V}}[u]$ to be the sum of all contributions in which the topmost path has these $k+1$ last steps.

The quantities $Z_{n, k}^{6 \mathrm{~V}}[u]$ turn out to be generated by the semi-inhomogeneouspartition function $Z_{n}^{6 \mathrm{~V}}[u ; \xi]$ (3.5), for which the last vertical spectral parameter is replaced by $\xi$. Introducing relative weights $(\bar{a}, \bar{b}, \bar{c})$ for the last column, as the following ratios of weights at $v=\xi$ by those at $v=0$ :

$$
\bar{a}=\frac{\sin (u-\xi+\eta)}{\sin (u+\eta)}, \quad \bar{b}=\frac{\sin (u-\xi-\eta)}{\sin (u-\eta)}, \quad \bar{c}=1,
$$

we have the following decomposition:

$$
Z_{n}^{6 \mathrm{~V}}[u ; \xi]=\sum_{k=1}^{\sum \operatorname{V}} Z_{n, k}^{6}[u] \bar{b}^{k-1} \bar{c} \bar{a}^{n-k}=\bar{a}^{n-1} \tau_{k=1}^{k r} \tau^{k-1} Z_{n, k}^{6 \mathrm{~V}}[u]
$$

in terms of a parameter

$$
\begin{equation*}
\tau:=\frac{\bar{b}}{-}=\frac{\sin (u-\xi-\eta) \sin (u+\eta)}{\sin (u-\xi+\eta) \sin (u-\eta)} \tag{3.17}
\end{equation*}
$$

In applying the tangent method, we truncate the topmost path after its last horizontal step (see an illustration in the top left of figure 9 in the pink domain). The effect of removing the last $k$ vertical steps and replacing them by empty edges is an overall multiplication by a factor $(1 / c)(a / b)^{k-1}$ (as we have cut ${ }^{5}$ the turning $c$-type vertex and replaced the $k$ - $1 b$-type vertices by $a$-type ones). This suggests to define refined one-point functions as the ratios

$$
H_{n, k}[u]:=\frac{1}{c} \begin{array}{lll}
a & { }^{k-1} & \frac{Z_{n, u}^{6 \mathrm{~V}}[u]}{Z_{n}^{6 \mathrm{~V}}[u]}
\end{array} .
$$

The above relation between refined partition functions turns into the following relation between one-point function and refined one-point functions:

$$
\begin{equation*}
c \frac{H_{n}^{6 \mathrm{~V}}[u ; \xi]}{\bar{a}^{n-1}}=\sum_{k=1}^{n} t^{k-1} H_{n, k}[u], \tag{3.18}
\end{equation*}
$$

where we have used a new parameter

$$
\begin{equation*}
t=\frac{{ }_{-}{ }_{\bar{a}}}{}=\frac{\sin (u-\xi-\eta)}{\sin (u-\xi+\eta)}=: t_{6 \mathrm{~V}}[\xi] . \tag{3.19}
\end{equation*}
$$

Let us now consider the large $n=N$ scaling limit of $H_{n, k}[u]$ in which the ratio $\kappa=k / N$ is kept finite. Using the relation (3.18) and the asymptotics of the one-point function $H_{N}^{6 \mathrm{~V}}[u ; \xi]$ of theorem 3.5, we have at leading order as $N \rightarrow \infty$ :

$$
\begin{equation*}
H_{N, \kappa N}[u] \quad-\frac{\mathrm{d} t}{2 \mathrm{i} \pi t} \mathrm{e}^{-N S_{0}(\kappa, t)}, \quad S_{0}(\kappa, t)=\kappa \log (t)+\phi^{6 \mathrm{~V}}[u ; \xi], \tag{3.20}
\end{equation*}
$$

where we have defined

$$
\phi^{6 \mathrm{~V}}[u ; \xi]:=\psi^{6 \mathrm{~V}}[u ; \xi]+\log (\bar{a})=\quad \log \frac{\sin (\alpha \xi) \sin (\alpha(u-\eta)) \sin (u-\xi-\eta)}{\alpha \sin (\xi) \sin (u-\eta) \sin (\alpha(u-\xi-\eta))} .
$$

Here the variable $t$ is integrated over a contour around the origin to extract the coefficient of $t^{k-1}$ in $H_{n, k}[u]$, and $\xi$ is an implicit function of $t$ upon inverting the equation $t_{6 \mathrm{~V}}[\xi]=t$.

The integral is dominated by the solution of the saddle-point equation $\partial_{t} S_{0}(\kappa, t)=0$ or equivalently $\partial_{\xi} S_{0}\left(\kappa, t_{6 \mathrm{~V}}[\xi]\right)=0$ resulting in

$$
\begin{align*}
\kappa= & \kappa_{6 \mathrm{~V}}[\xi]:=--\frac{t_{6 \mathrm{~V}}[\xi]}{} \partial \phi^{6 \mathrm{~V}}[u ; \xi] \\
= & \{\cot (u-\xi-\eta)+\cot (\xi)-\alpha \cot (\alpha \xi)-\alpha \cot (\alpha(u-\xi-\eta))\} \\
& \times \frac{\sin (u-\xi+\eta) \sin (u-\xi-\eta)}{\sin (2 \eta)} \tag{3.21}
\end{align*}
$$

with $\alpha$ as in (3.13).

[^4]
## 33. Paths

331. Partition function. The second ingredient of the tangent method is the partition function $Y_{k, I}$ for a single weighted path in empty space with the same weights as the 6 V osculating paths (see an example of such a path in the light blue domain of figure 9 top left). Note that the path starts where the topmost one in $H_{n, k}[u]$ stopped, namely with a preliminary horizontal step, and end with a vertical step at position I (measured from the original position in $Z_{n}$ ) on the $S$ boundary. Note also that all empty vertices receive the weight $a$ of (2.1). We may therefore factor out an unimportant overall weight $a^{n \prime}$, and weight the path by the product of its relative vertex weights:

$$
a_{0}=1, \quad b_{0}=\frac{b}{a}=\frac{\sin (u-\eta)}{\sin (u+\eta)}, \quad c_{0}=\frac{c}{a}=\frac{\sin (2 \eta)}{\sin (u+\eta)},
$$

for respectively $a, b$ and $c$ type vertices.
Let us use a step-to-step transfer matrix formulation of the path, namely a matrix $T$ describing the transfer from a step to the next. Each step may be in either of two states: horizontal or vertical, and the matrix entry is the corresponding 6 V weight at the vertex shared by the step and its successor, which we multiply by an extra weight $z, w$ if the next step is horizontal, vertical respectively. This gives the matrix

$$
T \quad \begin{array}{cc}
b_{0} z & c_{0} z \\
c_{0} w & \overline{\sigma_{0}} w
\end{array}
$$

allowing to express the generating function $P(z, w):=\sum_{k, l \geq 0} Y_{k, \prime}, z^{\prime} w^{k+1}$ as

$$
P(z, w)=0 \quad 1 \cdot\left(\mathrm{I}-T_{6 \mathrm{~V}}\right)^{-1} \quad \mathrm{l}^{0}=\underset{0}{1-b z-b{ }_{0} W} \underset{c_{0} W}{ } 1+\frac{c^{2}-b^{2}}{z_{0}} z_{0} .
$$

Using the new weights

$$
\gamma_{1}=b_{0}=\frac{\underline{\sin (u-\eta)}}{\sin (u+\eta)}, \quad: \quad \gamma_{2}={ }^{c^{2}-b^{2}} b_{0}{ }^{0}=\frac{\underline{\sin (3 \eta-u)}}{\sin (u-\eta)} .
$$

We deduce that

332 Asymptotics. We now consider the scaling limit of large $n=N$ and $\kappa=k / N, \lambda=1 / N$ fixed. Replacing the summation in (3.22) with an integral over $p_{2}=P_{2} / N$ and using the Stirling formula, we find the leading large $N$ behavior of $Y_{k, l}$ :

$$
\begin{aligned}
Y_{\kappa N, \lambda N} & \int_{\kappa}{ }_{0} \mathrm{~d} p 2 \mathrm{e}^{-N S_{1}\left(\kappa, p_{2}\right)} \\
S_{1}\left(\kappa, p_{2}\right)= & p_{2} \log \frac{p_{2}}{v}+\left(\kappa-p_{2}\right) \log \left(\kappa-p_{2}\right)+\left(\lambda-p_{2}\right) \log \left(\lambda-p_{2}\right) \\
& -\left(\kappa+\lambda-p_{2}\right) \log \left(\nu_{1}\left(\kappa+\lambda-p_{2}\right)\right) .
\end{aligned}
$$

## 34. Arctic curves

We now apply the tangent method. We must solve for the saddle-point equations for the total action $S\left(\kappa, \xi, p_{2}\right)=S_{0}(\kappa, t[\xi])+S_{1}\left(\kappa, p_{2}\right)$, namely $\partial_{\kappa} S=0$ and $\partial_{p_{2}} S=0$, while the last equation $\partial_{\xi} S=0$ eventually allows us to solve for $\kappa=\kappa[\xi]$ by using the result (3.21). We get:

$$
-\frac{t\left(\kappa-p_{2}\right)}{\gamma_{1}\left(\kappa+\lambda-p_{2}\right)}=1, \quad \frac{\underline{k}_{1} \ldots p_{2}\left(\kappa+\lambda-p_{2}\right)}{\gamma_{2}\left(\kappa-p_{2}\right)\left(\lambda-p_{2}\right)}=1
$$

with the following unique solution:

$$
\frac{\underline{2}_{2}}{\kappa}=-\frac{\sin (u-3 \eta) \sin (\xi)}{\sin (u-\xi-\eta) \sin (2 \eta)}, \quad \frac{\kappa}{\lambda}=\frac{\sin (u-\xi+\eta) \sin (u-\xi-\eta)}{\sin (\xi) \sin (\xi-2 \eta)}
$$

parameterized by $\xi$ via $t=t_{6 \mathrm{~V}}[\xi]$ (3.19) and $\kappa=\kappa_{6 \mathrm{~V}}[\xi]$ (3.21). In particular this determines $\kappa$ as a function of $\lambda$ in the parametric form $(\kappa, \lambda)=\left(\kappa_{6 \mathrm{~V}}[\xi], \lambda_{6 \mathrm{~V}}[\xi]\right)$, where

$$
\lambda_{6 \mathrm{~V}}[\xi]:=\kappa_{6 \mathrm{~V}}[\xi] \frac{\sin (\xi) \sin (\xi-2 \eta)}{\sin (u-\xi+\eta) \sin (u-\xi-\eta)} .
$$

This allows us to identify the slope $A[\xi]=\frac{\kappa_{6} \mathrm{~V}[\xi]}{\lambda 6 \mathrm{~V}[\xi]}$ and the intercept $B[\xi]=\kappa_{6 \mathrm{~V}}[\xi]$ for the family of tangents: $F_{\xi}[x, y]=y+A[\xi] x-B[\xi]=0$. The parameter $\xi$ is constrained by the condition that $A[\xi]>0$ which implies that $\xi \mp u+\eta-\pi, 0]$. Using the expression for the envelope (2.20), we arrive at the final result.

Theorem 3.6. The NE portion of the arctic curve for the 6 V -DWBC model in the disordered regime is predicted by the tangent method to be given parametrically by:

$$
x=\underset{\mathrm{NE}}{X^{6 \mathrm{~V}}[\xi]:=} \frac{B^{\prime}[\xi]}{\overline{A^{\prime}[\xi]}}, \quad y=\underset{\mathrm{NE}}{Y^{6 \mathrm{~V}}[\xi]}:=B[\xi]-\frac{A[\xi]}{B^{\prime}[\xi],} \quad(\xi \in[u+\eta-\pi, 0]),
$$

where

$$
\begin{aligned}
A[\xi]= & \frac{\sin (u-\xi+\eta) \sin (u-\xi-\eta)}{\sin (\xi) \sin (\xi-2 \eta)} \\
B[\xi]= & \{\cot (u-\xi-\eta)+\cot (\xi)-\alpha \cot (\alpha \xi)-\alpha \cot (\alpha(u-\xi-\eta))\} \\
& \times \frac{\sin (u-\xi+\eta) \sin (u-\xi-\eta)}{\sin (2 \eta)}
\end{aligned}
$$

with $\alpha$ as in (3.13).
As explained in section 2.2.2, we easily get the SE portion of the arctic curve, by applying the transformation ${ }^{*}: u \quad u^{*}=\pi-u$, and the change of coordinates (2.23) for $\mu=1$. As a result we have the following.

Theorem 3.7. The SE portion of the arctic curve for the 6V-DWBC model in the disordered regime is predicted by the tangent method to be given parametrically by:

$$
x=X_{\mathrm{SE}}^{G \mathrm{~V}}[\xi]:=X_{\mathrm{SE}}^{\mathrm{SV}}[\xi]^{*}, \quad y=Y_{\mathrm{SE}}^{\mathrm{S}}[\xi]:=1-Y_{\mathrm{V}_{\mathrm{N}}^{\prime}}^{\mathrm{V}}[\xi]^{*}, \quad(\xi \in[\eta-u, 0])
$$

with $\underset{\mathrm{NE}}{X^{6 \mathrm{~V}}}, Y_{\mathrm{NE}}^{6 \mathrm{~V}}$ as in theorem 3.6.

Finally, we note that the weights (2.1) and the DWBC are invariant under central symmetry, which reflects all arrow orientations. As a consequence, the arctic curve of the 6 V -DWBC model is centro-symmetric as well, and it can be easily completed by applying the central symmetry $(x, y) \mapsto(\perp-x, 1-y)$ to the NE and SE branches to respectively produce the SW and NW ones.

Remark 3.8. At the self-dual point $u=u^{*}=\frac{\pi}{2}_{2}$, the arctic curve is symmetric w.r.t. the horizontal line $y=1 / 2$, as well as the vertical line $x=-1 / 2$ by the central symmetry. The full curve is then obtained by successive reflections of the NE branch; as an example the limit shape of ASMs [CP10b] is made of 4 reflected portions of ellipse. This is no longer true if $u /=2^{\frac{\pi}{\underline{I}}}$.

## 4. $6 V^{\prime}$ model

### 4.1. Partition function and one-point function

4.1. Inhomogeneous partition function. The partition function of the inhomogeneous Uturn boundary 6 V model was derived by Kuperberg and independently by Tsuchiya [Kup02, Tsu98]. Let

$$
m_{\mathrm{U}}(u, v):=\frac{1}{\sin (u-v+\eta) \sin (u-v-\eta)}-\frac{1}{\sin (u+v+\eta) \sin (u+v-\eta)}
$$

Note that as opposed to the 6 V case, this is no longer a function of $u_{-} v$ only, but includes a reflected term which is a function of $u+v$.

Theorem 4.1. The $U$-turn boundary $6 V$ partition function reads:

$$
\begin{aligned}
& Z_{n}^{6 \mathrm{~V}-\mathrm{U}}[\mathbf{u}, \mathbf{v} ; \vartheta] \\
& =\left(\rho_{c} \rho_{o}\right)^{n^{2}} \operatorname{det}_{1 \leq i, j \leq n} m_{\mathrm{U}}\left(u_{i}, v_{j}\right)
\end{aligned}
$$

As mentioned above and illustrated in figure 3 , the $6 \mathrm{~V}^{\prime}$ model corresponds to the choice of parameter $\vartheta=-u-\eta$, which ensures that $y_{u}(u)=0$ for all U-turns. The partition function corresponding to this choice, where we cut out the U-turns of figure 3(a) and remove their weights, as well as the weights of the trivially fixed $b$-type vertices of the bottom row in figure 3(b), reads:

$$
\begin{equation*}
Z_{n}^{\mathrm{ov}^{\prime}}[u, \mathbf{v}]=\lim _{\substack{u_{i}-u \\ \vartheta \rightarrow-u-\eta}} \frac{(-1)^{n} Z^{6 \mathrm{~V}-\mathrm{U}}[\mathbf{u}, \mathbf{v} ; \vartheta]}{\sin ^{n}(2 u+2 \eta) \rho_{e}^{n}} \frac{n}{\substack{i=1 \\ \sin \left(-u-v_{i}-\eta\right)}}, \tag{4.2}
\end{equation*}
$$

where we have identified the limit of the U-turn weights to be $y_{d}\left(u_{i}\right) \rightarrow-\sin (2 u+2 \eta)$ and that of the $b$ weights of the bottom (even) row to be $b_{e} \rightarrow \rho_{e} \sin \left(-u-v_{i}-\eta\right)$.

Remark 4.2. Note that in (4.1) the dependence on the parameter $\vartheta$ is only through the prefactor ${ }_{i} \sin \left(\vartheta-v_{i}\right)$. The 'worst case scenario' is the homogeneous limit where all $v_{i} \rightarrow v$, and where this gives a factor $\sin ^{n}(\vartheta-v)_{1}$ In any gase, this does not affect the yalue of the thermodynamic free energy $\left.f \stackrel{ }{=} \lim _{n \rightarrow \infty}-\right)_{1} \log \left(Z^{q}\right)$, which is independent of $\vartheta$. We may therefore safely fix the value of $\vartheta$ to suit our needs.
4.12 Homogeneous limit. Like in the 6 V case, the homogeneous limit where we take all $u_{i} \rightarrow u$ and all $v_{i} \rightarrow v$ involves the quantity:

$$
\Delta_{n}[u, v]:=\lim _{\substack{u \rightarrow u_{i} \\ v \rightarrow v_{i}}} \frac{\operatorname{det}_{1 \leq i, j \leq n} m_{U}\left(u_{i}, v_{j}\right)}{\left(u_{i}-u_{j}\right)\left(v_{j}-v_{i}\right)}
$$

Upon Taylor-expanding rows and columns, we may rewrite:

$$
\sum_{0 \leq i, j \leq n-1} \frac{\partial^{i} \partial^{j} m_{U}(u, v)}{i!j!}=:-\frac{1}{\substack{n^{-} 1 \\ i=0}}(i!)^{2}-D_{n}[u, v],
$$



$$
\begin{equation*}
D_{n}[u, v]=\operatorname{det}_{0 \leq i, j \leq n-1}(-1)^{j} \partial^{i} d^{j} m_{\mathrm{U}}(u, v) \tag{4.3}
\end{equation*}
$$

Using the relation (4.2) and the result of theorem 4.1, we obtain the homogeneous partition function of the $6 \mathrm{~V}^{\prime}$ model:

$$
\begin{equation*}
\frac{Z^{6 \mathrm{v}^{\prime}}[u, v]}{n^{n--n^{n}} \rho_{o}^{n^{2}} \sin n(2 \eta)}=\Delta_{n}[u, v] \frac{(\sin (u-v+\eta) \sin (u-v-\eta) \sin (u+v+\eta) \sin (u+v-\eta))^{n^{2}}}{(\sin (2 u) \sin (2 v))^{n(n+1) / 2}} . \tag{4.4}
\end{equation*}
$$

To determine $\Delta_{n}[u, v]$ one uses like in the 6 V case the Plücker/Desnanot-Jacobi relation of lemma 3.2 applied to the $n+1 \times n+1$ matrix $M$ in the definition of $D_{n+1}[u, v]$ (4.3):

$$
D_{n+1}[u, v] D_{n-1}[u, v]=\partial_{u} D_{n}[u, v] \partial_{v} D_{n}[u, v]-D_{n}[u, v] \partial_{u} \partial_{v} D_{n}[u, v]
$$

which implies

$$
\begin{equation*}
\frac{D_{n+1}[u, v] D_{n=1}[u, v]}{\left(D_{n}[u, v]\right)^{2}}+\partial_{u} \partial_{v} \log \left(D_{n}[u, v]\right)=0 . \tag{4.5}
\end{equation*}
$$

As a direct consequence, we have:

Theorem 4.3. The quantity $\Delta_{n}[u, v]$ obeys the following recursion relation:

$$
\begin{equation*}
\frac{\Delta_{n+1}[u, v] \Delta_{n=1}[u, v]}{\Delta_{n}[u, v]^{2}}+\frac{1}{n^{2}} \partial_{u} \partial_{v} \log \left(\Delta_{n}[u, v]\right)=0 . \tag{4.6}
\end{equation*}
$$

Note that the latter can be used to determine $\Delta_{n}[u, v]$ recursively, starting with $\Delta_{0}[u, v]=1$ and $\Delta_{1}[u, v]=m_{\mathrm{U}}(u, v)$, as we illustrate now with a few simple examples.

Example 4.4. Let us consider the 'classical limit' $\eta \rightarrow 0$, where:

$$
m_{\mathrm{U}}(u, v)=\frac{1}{\sin ^{2}(u-v)}-\frac{1}{\sin ^{2}(u+v)}=\frac{\sin (2 u) \sin (2 v)}{\sin ^{2}(u-v) \sin ^{2}(u+v)}
$$

We have:

Theorem 4.5. In the classical case $\eta=0$, we have for all $n \geq 1$ :

$$
\Delta_{n}[u, v]=n!{\frac{-}{\sin (2 u) \sin (2 v)}{\frac{\sin }{}{ }^{2}(u-v) \sin ^{2}(u+v)}_{n(n+1) / 2}}
$$

Proof. The proof is by induction on $n$, using (4.6), and follows from the relation

$$
\frac{\sin (2 u) \sin (2 v)}{\sin ^{2}(u-v) \sin ^{2}(u+v)}-\partial_{u} \partial_{v} \log (\sin (u-v) \sin (u+v))=0 .
$$

Q
Note that the corresponding $6 \mathrm{~V}^{\prime}$ partition function vanishes, however we get a finite limit for the quantity

$$
\lim _{n \rightarrow 0} \frac{Z_{n}^{6 \mathrm{v}^{\prime}}[u, v]}{{\rho_{e}^{2}}^{2}-\rho^{2} \rho_{o}^{2} \sin ^{n}(2 \eta)}=n!(\sin (u-v) \sin (u+v))^{n(n-1)} .
$$

This result has a simple interpretation: sending $\eta-0$ implies both $c_{e}$ and $c_{o}$ type vertices have vanishing weights. However, without the ability to turn right, none of the osculating paths can satisfy the boundary conditions, unless each path is allowed at least one right turn. In this formulation, we must no longer see the paths as osculating, but rather as crossing at fully occupied $a$-type vertices. The minimal case is if each path has exactly one turn (and the vanishing weight $\sin ^{n}(2 \eta)$ is divided before taking the $\eta \rightarrow 0$ limit). For each $i=1,2, \ldots, n$, the $i$ th path from the bottom starts with say $j=\sigma(i)$ horizontal steps, then turns right and ends with $2 i 1$ vertical steps at the $j$ th endpoint. Clearly there are as many such configurations as permutations $\sigma$ of the $n$ path ends, which accounts for an overall factor of $n!$. Collecting all the Boltzmann weights gives the remaining factor.

Example 4.6. We now consider the 'free fermion' case $\eta=\pi_{4}$ where

$$
\begin{aligned}
m_{\mathrm{U}}\left(u,{ }^{v}\right)= & \frac{1}{\sin u-v+{ }_{-}^{\pi} \sin u-v-{ }_{-}^{\pi}-\sin u+v+\pi_{-}^{\pi} \sin u+v-\pi_{-}} \\
& \frac{4 \sin (2 u) \sin (2 v)}{4}
\end{aligned}
$$

Theorem 4.7. In the free fermion case $\eta=\frac{\pi^{4}}{n}$ we have for all $n \geq 1$ :

$$
\Delta_{n}[u, v]=\frac{(\cos (2(u-v)) \cos (2(u+v)))^{n 2}}{}
$$

Proof. The proof is by induction on $n$ using (4.6), and follows from the relation

$$
\frac{4 \sin (4 u) \sin (4 v)}{\cos ^{2}(2(u-v)) \cos ^{2}(2(u+v))}+\partial_{u} \partial_{v} \log (\cos (2(u-v)) \cos (2(u+v)))=0
$$

The corresponding $6 \mathrm{~V}^{\prime}$ partition function reads:

$$
\frac{Z^{6 \mathrm{~V}^{\prime}}[u, v]}{\rho_{e}^{n^{2}-n} \rho_{o}^{n^{2}}}=(\cos (2 u) \cos (2 v))^{n(n-1) / 2} .
$$

4.1.3. One-point function. As in the case of the 6 V model, we consider the semi-homogeneous partition function $Z_{n}^{6 \mathrm{v}^{\prime}}[u, v ; \xi]$ with the same boundary conditions as $Z_{n}^{6 \mathrm{v}^{\prime}}[u, v]$ but with a different vertical spectral parameter in the last column, set to $v_{n}=v+\xi$. It is again obtained as a limit of (4.2) and reads:

$$
\begin{align*}
& \frac{Z_{n}^{6 \mathrm{~V}^{\prime}}[u, v ; \xi]}{\rho_{e}^{n^{n^{2}}-n^{n}} \rho_{o}^{n^{2}} \sin ^{n}(2 \eta)} \\
& =\Delta_{n}[u, v ; \xi] \frac{\left(\operatorname { s i n } ( u - v + \eta ) \operatorname { s i n } ( u - v - \eta ) \operatorname { s i n } \left(u+v+\frac{n)+\infty \sin (u+v-n}{\left.\sin (2 \xi+2 v)(\sin (\xi+2 v))^{n}(\sin (2 u))\right)_{2}^{n(n-1)}}(\sin (2 v))^{n} \frac{2}{2}\right.\right.}{2} \\
& \times(\sin (u-v-\xi+\eta) \sin (u-v-\xi-\eta) \sin (u+v+\xi+\eta) \sin (u+v+\xi-\eta)) \tag{4.8}
\end{align*}
$$

in terms of the semi-homogeneous quantity

$$
\Delta_{n}[u, v ; \xi]:=\lim _{\substack{u_{1} \\ v_{1}, \ldots, v_{n-1}-m_{n}, v_{n} \rightarrow v+\xi}} \frac{\operatorname{det}_{1 \leq i, j \leq n} m_{\mathrm{U}}\left(u_{i}, v_{j}\right)}{1 \leq i<j \leq n \sin \left(u_{i}-u_{j}\right) \sin \left(v_{j}-v_{i}\right)} .
$$

Repeating the Taylor expansion of rows and columns except the last one, we may rewrite:

$$
\begin{align*}
\Delta_{n}[u, v ; \xi]= & \frac{(-1)^{n(n-1) / 2}}{\sin ^{n-1}(\xi)} \\
& \times \operatorname{det} \frac{\partial_{u}^{i} \partial_{V}^{j} m_{\mathrm{U}}(u, v)}{i!j!} \underset{\substack{i=1, \ldots, n=1 \\
j=, \ldots n-\\
0, \ldots, 2}}{\substack{0}} \cdot{\frac{\partial_{u}^{i} m_{\mathrm{U}}(u, w)}{i!}}_{i=0, \ldots, n-1} \\
= & \frac{(-1)^{n-1}(n-1)!}{\sin ^{n-1}(\xi) \quad \begin{array}{c}
n-1 \\
i=0 \\
\left.\sin ^{2}!\right)^{2}
\end{array} D_{n}[u, v ; \xi],} \tag{4.9}
\end{align*}
$$

where the determinant $D_{n}[u, v ; \xi]$ reads

$$
\begin{equation*}
D_{n}[u, v ; \xi]=\operatorname{det} \quad(-1)^{j} \partial^{i}{ }_{u} \partial^{j} m_{\mathrm{U}}(u, v)_{\substack{i=1, \ldots, n-1 \\ j=0, \ldots, 2^{-}}}^{\}} \partial^{i} m_{\mathrm{U}}(u, v+\xi)^{\}}{ }_{i=0, \ldots, n-1} . \tag{4.10}
\end{equation*}
$$

As before, we define the one-point function $H_{n}^{6 v^{\prime}}[u, v ; \xi]$ as the ratio:

$$
\begin{align*}
H_{n}^{\operatorname{sv^{\prime }}}[u, v ; \xi]: & \frac{Z_{i 6 \mathrm{v}}[u, v ; \xi]}{Z_{n}^{6 \mathrm{v}^{\prime}}[u, v]} \\
= & \frac{\Delta_{n}[u, v ; \xi]}{\Delta_{n}[u, v]} \underset{\sin (\xi+2 v)}{\sin (2 \xi+2 v)}-\frac{\sin (2 v)}{\sin (\xi+2 v)}{ }^{n} \\
& \times \frac{\sin (u-v-\xi+\eta) \sin (u-v-\xi-\eta) \sin (u+v+\xi+\eta) \sin (u+v+\xi-\eta)}{\sin (u-v+\eta) \sin (u-v-\eta) \sin (u+v+\eta) \sin (u+v-\eta)}{ }^{n} \tag{4.11}
\end{align*}
$$

The Plücker/Desnanot-Jacobi relation of lemma 3.2 applied to the $n+1 \times n+1$ matrix $M$ in the definition of $D_{n+1}[u, v ; \xi]$ (4.10) implies the following:

$$
D_{n+1}[u, v ; \xi] D_{n-1}[u, v]=D_{n}[u, v ; \xi] \partial_{u} D_{n}[u, v]-D_{n}[u, v] \partial_{u} D_{n}[u, v ; \xi] .
$$

Introducing the reduced one-point function

$$
\begin{equation*}
H_{n}[u, v ; \xi]:=(-1)^{n-1}(n-1)!\frac{D_{n}[u, v ; \zeta]}{D_{n}[u, v]}=\sin ^{n-1}(\xi) \frac{\Delta_{n}[u, v ; \zeta]}{\Delta_{n}[u, v]} \tag{4.12}
\end{equation*}
$$

we may recast the above into the following.

Theorem 4.8. The reduced one-point function of the $6 V^{\prime}$ model obeys the following relation:

$$
\frac{H_{n+1}[u, v ; \xi] \Delta_{n}=1[u, v] \Delta_{n+1}[u, v]}{H_{n}[u, v ; \xi]}+1
$$

$$
\begin{equation*}
{ }_{c}^{\Delta_{n}^{n}[u, v]^{2}}+{ }^{-}{ }^{-} \partial_{u} \log \left(H_{n}[u, v ; \xi]\right)=0 . \tag{4.13}
\end{equation*}
$$

Together with (4.6), this determines $H_{n}[u, v ; \xi]$ recursively, using the initial data $H_{1}[u, v ; \xi]=\frac{m \cup(u, v+\xi)}{m \cup(u, v)}$, and in turn the one-point function $H_{n}^{6 V}[u, v ; \xi]$ via:

$$
H_{n}^{6 v^{\prime}}[u, v ; \xi]
$$

$$
=H_{n}[u, v ; \xi] \frac{\sin (\xi) \sin (\xi+2 v)}{\sin (2 \xi+2 v)} \quad \sin (\xi) \sin (\xi+2 v) \quad n
$$

$$
\begin{equation*}
\times \quad \frac{\sin (u-v-\xi+\eta) \sin (u-v-\xi-\eta) \sin (u+v+\xi+\eta) \sin (u+v+\xi-\eta)}{\sin (u-v+\eta) \sin (u-v-\eta) \sin (u+v+\eta) \sin (u+v-\eta)} . \tag{4.14}
\end{equation*}
$$

## 42 Large $n$ limit: free energy and one-point function asymptotics

421. Free energy. For large $n=N$, like in the 6 V case, the relation (4.6) leads to the following leading behavior for the function $\Delta_{n}[u, v]$ :

$$
\begin{equation*}
\Delta_{N}[u, v] \quad \mathrm{e}^{-N^{2} f[u, v]} \tag{4.15}
\end{equation*}
$$

for some function $f[u, v]$ to be determined (see [RK15] for a full derivation).
421.1. Liouville equation and free energy For large $n=N$, substituting the behavior (4.15) into equation (4.6), and expanding at leading order in $N^{-1}$, we get the following 2D Liouville partial differential equation for the function $f[u, v]$ :

$$
\begin{equation*}
\partial_{u} \partial_{v} f[u, v]-\mathrm{e}^{-2 f[u, v]}=0 . \tag{4.16}
\end{equation*}
$$

Introducing the function $W[u, v]:=\mathrm{e}^{f[u, v]}$ this may be rewritten as:

$$
W \partial_{u} \partial_{v} W-\partial_{u} W \partial_{v} W=1 .
$$

The general solution $W$ of this equation is known to be [Cro97, Lio53]:

$$
\begin{equation*}
W[u, v]=\frac{g(u)-h(v)}{\left|g^{\prime}(u) h^{\prime}(v)\right|^{\frac{1}{2}}} \tag{4.17}
\end{equation*}
$$

for some arbitrary differentiable functions $g, h$. In [RK15], the functions $g, h$ are fixed by use of symmetries and known limits of $W$, leading to the following.

Theorem 4.9 ([RK15]). The leading asymptotics of the determinant $\Delta_{n}[u, v]$ is given by $W[u, v]=\lim _{N \rightarrow \infty} \Delta_{N}[u, v]^{-} \frac{1}{N^{2}}$ where $:$

$$
\begin{equation*}
W[u, v]=\frac{\sin (\alpha(u-v-\eta)) \sin (\alpha(-u-v-\eta))}{\alpha|\sin (2 \alpha u) \sin (2 \alpha(v+\eta))|^{\frac{1}{2}}} \tag{4.18}
\end{equation*}
$$

with

$$
\begin{equation*}
\alpha=\frac{\pi}{\pi-2 \eta} . \tag{4.19}
\end{equation*}
$$

Theorem 4.9 gives access to the full free energy $f^{6 \mathrm{~V}^{\prime}}$ of the $6 \mathrm{~V}^{\prime}$ model, as defined by the large $N$ asymptotics $Z \mathrm{~N}^{\mathrm{V}^{\prime}}[u, v] \mathrm{e}^{-N 2 f 6 \mathrm{~V}[u, v]}$, where as a consequence of (4.4), we have:

$$
\begin{align*}
f^{6 \mathrm{v}^{\prime}}[u, v]= & f[u, v] \\
& +\log \frac{\sqrt{ } \frac{|\sin (2 u) \sin (2 v)|}{\rho_{e} \rho_{o} \sin (u-v+\eta) \sin (u-v-\eta) \sin (u+v+\eta) \sin (u+v-\eta)}}{} \quad . \tag{4.20}
\end{align*}
$$

This leads immediately to the following.

Corollary 4.10 ([RK15]). The free energy of the $6 V^{\prime}$ model in the disordered regime reads:

$+\log$

$$
\begin{gather*}
\sin (\alpha(u-v-\eta)) \sin (\alpha(-u-v-\eta))  \tag{4.21}\\
\alpha \rho_{e} \rho_{o} \sin (u-v+\eta) \sin (u-v-\eta) \sin (u+v+\eta) \sin (u+v-\eta)
\end{gather*}
$$

We also have access to the free energy $f^{20 \mathrm{~V}}$ of the 20 V DWBC3 model defined in section 2.1.3, which will be studied in section 5 below. The free energy is defined via $Z_{N}^{20 \mathrm{~V}}[u, v] \mathrm{e}^{-N 2} f{ }^{20 \mathrm{~V}[u, v]}$ for large $N$. As a consequence of (5.2) which relates the partition functions of the $20 \mathrm{~V}-\mathrm{DWBC} 3$ and $6 \mathrm{~V}^{\prime}$ models (see also reference [DF21]), we have the relation:

$$
\begin{equation*}
f^{20 \mathrm{~V}}[u, v]=f^{6 \mathrm{~V}^{\prime}}[u, v]+\frac{1}{2} \log v^{3} \sin ^{3}(2 u+2 \eta) \sin (u-v-\eta) \sin (u+v-\eta) . \tag{4.22}
\end{equation*}
$$

Let us apply this to the uniform case (2.17), where the partition function $Z_{\mathrm{Z}^{6}}{ }^{\mathrm{V}}$ of the $6 \mathrm{~V}^{\prime}$ model on the $(2 n-1) \times n$ grid is related to the number of configurations $Z_{n}^{20 V}$ of the 20 V model with DWBC3 on the quadrangle $\mathrm{Q}_{n}$ [DF21] (see section 2.1.3). Using theorem 4.9 and the relations (4.21) and (4.22), and approaching the desired value $v=-4 \eta+\epsilon$, while $u=\eta$, we get for $\eta=\frac{\pi}{8}, \alpha={ }_{3}, v={ }^{4}$ :
$\qquad$ $\begin{array}{llll}1 & \underline{16} & 8 & 9 / 4\end{array}$

|  |  |  |  |
| :---: | :---: | :---: | :---: |
|  |  |  |  |

This is in agreement with the asymptotics of the exact conjectured formula of reference [DF21] for the uniformly weighted partition function, namely:

$$
\begin{equation*}
Z^{2} \mathrm{~N}^{\mathrm{ov}}=2^{N(N-1) / 2}{ }_{i=0}^{N-1} \frac{(4 i+2)!}{(n+2 i+1)!} \quad{\frac{2^{9 / 2}}{3^{9 / 4}}}^{N^{2}} \tag{4.23}
\end{equation*}
$$

easily derived by use of the Stirling formula.
422 One-point function. We now derive the large $n=N$ asymptotics of the one-point function $H_{n}^{6 \mathrm{~V}^{\prime}}[u, v ; \xi]$ (4.11). From equation (4.14), the latter is simply expressed in terms of the reduced one-point function $H_{n}[u, v ; \xi]$ (4.12). Like in the 6 V case, we first derive a differential equation governing the asymptotic behavior of $H_{n}[u, v ; \xi]$, and compute a number of limits to fix integration constants. It turns out that our conjecture 4.9 is sufficient to determine asymptotics completely.

By theorem 4.8, $H_{n}[u, v ; \xi]$ must satisfy (4.13), which implies the leading asymptotic behavior

$$
\begin{equation*}
H_{N}[u, v ; \xi] \quad N \rightarrow \infty \quad \mathrm{e}^{-N \psi[u, v ; \xi]} \tag{4.24}
\end{equation*}
$$

for some function $\psi[u, v ; \xi]$. As a simple confirmation, using the definition (4.12) and the fact that $\Delta_{n}[u, v ; 0]=\Delta_{n}[u, v]$, we find that $H_{n}[u, v ; \xi] \xi_{\rightarrow 0} \xi^{n-1}$, resulting in:

$$
\begin{equation*}
\psi[u, v ; \xi] \quad \xi \rightarrow 0-\log (\xi) . \tag{4.25}
\end{equation*}
$$

4221. Differential equation Substituting the expressions (4.15) and (4.24) into equation (4.13) for $n=N$, and expanding to leading order in $N^{-1}$, we get the following partial differential equation:

$$
\begin{equation*}
\partial_{u} \psi[u, v ; \xi]-\mathrm{e}^{-2 f[u, v]-\psi[u, v ; \xi]}=0 \tag{4.26}
\end{equation*}
$$

4222 Limits In addition to the limit (4.25) above, let us consider the limit $u-v_{-} \xi_{-}$ $\eta \rightarrow 0$, by setting $\xi=u-v-\eta-\epsilon$ and sending $\epsilon \rightarrow 0$. The entries of the last column of the determinant $D_{N}[u, v ; v+\xi]$ (4.10) read:

$$
\partial_{u}^{i} m_{\mathrm{U}}(u, u-\eta-\epsilon)=\frac{1}{\frac{(-1)^{i}}{}{ }^{i} i!}+O\left(\epsilon^{-i}\right)
$$

The dominant term is in the last row and results in

$$
D_{N}[u, v ; u-\eta-\epsilon] \quad \frac{(-1)^{N-1}(N-1)!}{\sin (2 \eta) \epsilon^{N}} D_{N-1}[u, v] .
$$

We deduce that

$$
\begin{aligned}
H_{-}\left[u, \underline{u} ; u_{-} \quad v \quad \eta_{-} \quad \epsilon\right]= & \left(\begin{array}{cc}
\left.\frac{1}{N}\right)^{N-1}(N & 1)!
\end{array} \frac{D_{N}[u, v ; u-\eta-\epsilon]}{D_{N}[u, v]}\right. \\
& \frac{(N-1)!^{2}}{\epsilon_{N-1}[u, v]} \\
& \frac{1}{\epsilon^{N}} \frac{D_{N-1}[u, v]}{\Delta_{N}(2 \eta) \epsilon^{N}[u, v]} \frac{W[u, v]^{2 N}}{\epsilon^{N}}
\end{aligned}
$$

where we have used the large $N$ asymptotics $\Delta_{N}[u, v] \quad W[u, v]^{-N 2}$. Matching this with the asymptotics (4.24), we conclude that

$$
\begin{equation*}
\psi[u, v, u-v-\eta+\epsilon]_{\epsilon \rightarrow 0} \quad \log \frac{\epsilon}{W[u, v]^{2}} . \tag{4.27}
\end{equation*}
$$

Repeating the analysis for $\xi=\eta-u-v+\epsilon$, we find analogously:

$$
\begin{equation*}
\psi[u, v, \eta-u-v+\epsilon]_{\epsilon \rightarrow 0} \quad \log \cdot \frac{\epsilon}{W[u, v]^{2}} . \tag{4.28}
\end{equation*}
$$

4223. Solution Note that equation (4.26) may be rewritten in the form $\partial_{u}\left(\mathrm{e}^{\psi}\right)=\mathrm{e}^{-2 f}=$ $W^{-2}$. This can be integrated w.r.t. the variable $u$ as follows:

$$
\begin{equation*}
\mathrm{e}^{\psi[u, v, \xi]}=c[v, \xi]-\frac{\alpha \sin (2 \alpha(v+\eta))}{\sin (\alpha(u-v-\eta)) \sin (\alpha(u+v+\eta))} \tag{4.29}
\end{equation*}
$$

for some integration constant $c[v, \xi]$ independent of $u$.
We now use the limit (4.27) to express that, for $\xi=u-v-\eta+\epsilon$ and $\epsilon \rightarrow 0$, we have $\mathrm{e}^{\psi[u, v ; \xi]} \rightarrow 0$. This gives:

$$
c[v, u-v-\eta]=\frac{\alpha \sin (2 \alpha(v+\eta))}{\sin (\alpha(u-v-\eta)) \sin (\alpha(u+v+\eta))}
$$

which is valid for all $u, v$. In particular, setting $u=v+\eta+\xi$ yields the integration constant

$$
c[v, \xi]=\frac{\alpha \sin (2 \alpha(v+\eta))}{\sin (\alpha \xi) \sin (\alpha(\xi+2 v+2 \eta))}
$$

which we plug back into (4.29) to finally get:

$$
\begin{equation*}
\psi[u, v ; \xi]=\log \frac{\alpha \sin (2 \alpha(v+\eta)) \sin (\alpha(u-v-\xi-\eta)) \sin (\alpha(u+v+\xi+\eta))}{\sin (\alpha(u-v-\eta)) \sin (\alpha(u+v+\eta)) \sin (\alpha \xi) \sin (\alpha(\xi+2 v+2 \eta))} . \tag{4.30}
\end{equation*}
$$

Using the relation (4.14) this leads to the following result for the one-point function asymptotics.

Theorem 4.11. The one-pointfunction $H_{2}^{6 \mathrm{~V}^{\prime}}[u, v ; \xi]$ has the following large $n=N$ behavior:

$$
\begin{aligned}
H_{N}^{6 \mathrm{~V}}[u, v ; \xi] \quad & \mathrm{e}^{-N \psi^{6 \mathrm{~b}}}[u, v ; \xi] \\
\psi^{6 \mathrm{~V}^{\prime}}[u, v ; \xi]= & \log \frac{\sin (\alpha(u-v-\eta)) \sin (\alpha(u+v+\eta)) \sin (\alpha \xi) \sin (\alpha(\xi+2 v+2 \eta))}{\alpha \sin (2 \alpha(v+\eta)) \sin (\alpha(u-v-\xi-\eta)) \sin (\alpha(u+v+\xi+\eta))} \\
& \log \frac{\sin (2 v) \sin (u-v-\xi+\eta) \sin (u-v-\xi-\eta) \sin (u+v+\xi-\eta) \sin (u+v+\xi+\eta)}{\sin (\xi) \sin (\xi+2 v) \sin (u-v+\eta) \sin (u-v-\eta) \sin (u+v-\eta) \sin (u+v+\eta)}
\end{aligned}
$$

with $\alpha$ as in (3.13).
As a consistency check, we find that $\lim _{\xi \rightarrow 0} \psi^{6 \mathrm{v}^{\prime}}[u, v ; \xi]=0$, in agreement with the fact that $H_{n}^{6 v^{\prime}}[u, v ; 0]=1$ by definition.

Remark 4.12. In the case of the more general U-turn 6 V model (with arbitrary value of the parameter $\vartheta$ ), we already showed in remark 4.2 that the thermodynamic free energy of the model is independent of $\vartheta$, therefore identical to that of the $6 \mathrm{~V}^{\prime}$ model. The same argument may be applied to the one-point function, whose leading asymptotics is independent of $\vartheta$ as well, and therefore the same for U-turn 6 V and $6 \mathrm{~V}^{\prime}$ models.

Remark 4.13. Independently of theorem 4.9, equation (4.26) can be solved in terms of the generic function $g$ which determines the general solution (4.17) to the Liouville equation with the correct symmetries and limits, namely such that $h(v)=g(v+\eta)$, with the expression:

$$
W[u, v]=\frac{g[u]-g[v+\eta]}{\left|g^{\prime}(u) g^{\prime}(v+\eta)\right|} .
$$

Solving equation (4.26) in the same manner as above, we obtain:

$$
\psi[u, v ; \xi]=\log \frac{(g(u)-g(v+\xi+\eta)) g^{\prime}(v+\eta)}{(g(u)-g(v+\eta))(g(v+\xi+\eta)-g(v+\eta))} .
$$

In particular, we recover the solution for the $6 \mathrm{~V}-\mathrm{DWBC}$ case by picking $g(u)=\tan (\alpha u)$, which leads to

$$
\begin{aligned}
W[u, v] & =\frac{\sin (\alpha(u-v-\eta))}{\alpha}=W[u-v] \\
\psi[u, v ; \xi] & =\log \frac{\alpha \sin (\alpha(u-v-\eta-\xi))}{\sin (\alpha \xi) \sin (\alpha(u-v-\eta))} \quad=\psi[u-v ; \xi]
\end{aligned}
$$

in agreement with (3.12) and (3.16).

### 4.3 Paths

431. Partition function. With the setting of figure 9 (bottom left, light blue domain), we wish to compute the partition function $Y_{k, l}$ of a single path of the $6 \mathrm{~V}^{\prime}$ model in the first quadrant $\mathrm{Z}_{+}^{2}$, with starting point $(0, k)$ and endpoint $(I, 0)$. The weights of the path are those of the $6 \mathrm{~V}^{\prime}$ model, namely ( $b_{o}, c_{o}$ ) for a path (going straight, turning) at a vertex with second coordinate $y=2 j, j=0,1,2, \ldots$ and ( $b_{e}, c_{e}$ ) for a path (going straight, turning) at a vertex with second coordinate $y=2 j+1, j=0,1,2$, However the path crosses a domain of empty vertices, each receiving weights $a_{e}, a_{o}$ depending on the parity of their second coordinate $y$. Factoring an overall weight $\left(a_{o}\right)^{n \prime}\left(a_{e}\right)^{(n-1) /}$ which does not affect our study, the weights of the path steps must be divided by $a_{e}, a_{o}$ and finally read:

$$
\begin{array}{ll}
b_{0}=\frac{\underline{b}_{o}}{a_{o}}=\frac{\sin (u-v-\eta)}{\sin (u-v+\eta)}, & c_{0}=\frac{\underline{c}_{o}}{a_{o}}=\frac{\sin (2 \eta)}{\sin (u-v+\eta)} \\
b_{1}=\frac{b_{e}}{a_{e}}=\frac{\sin (u+v+\eta)}{\sin (u+v-\eta)}, & c_{1}=\frac{c_{e}}{a_{e}}=\frac{\sin (2 \eta)}{\sin (\eta-u-v)} \tag{4.31}
\end{array}
$$

for vertices with $y=2 j$ and $y=2 j+1$ respectively. Note that the path has a horizontal step just before entering the first quadrant, and has a final vertical step.

The partition function $Y_{k, \prime}$ is computed by use of a transfer matrix technique. Each path is traveled from $\mathrm{N}, \mathrm{W}$ to $\mathrm{S}, \mathrm{E}$, and the transfer matrix is a $4 \times 4$ matrix $T_{6 \mathrm{v}^{\prime}}$ whose entries
correspond to the vertex weight for the transition from the entering step at each visited vertex to the outgoing step, with the four possible configurations $(\rightarrow o),(p o),(\rightarrow e),(\mid, e)$ of horizon$\mathrm{tal} / \mathrm{vertical}$ step ending at an odd/even vertex. Moreover we include an extra weight $z, w$ per horizontal, vertical outgoing step respectively. The matrix $T_{6 \mathrm{v}^{\prime}}$ reads:

$$
T_{6 \mathrm{~V}^{\prime}}=\left|\begin{array}{cccc}
b_{0} z & c_{0} z & 0 & 0 \\
0 & 0 & c_{1} w & b_{1} w \\
0 & 0 & b_{1} z & c_{1} z \\
c_{0} w & b_{0} w & 0 & 0
\end{array}\right| .
$$

We deduce the generating function for the $Y_{k}$, :

$$
\begin{align*}
& Y^{6 \mathrm{~V}^{\prime}}(z, w)=\sum_{k, l \geq 0} Y_{k, l} w^{k+1} z^{\prime}=(0,0,0,1)\left(\mathrm{I}-T_{6 \mathrm{~V}}\right)^{\prime-1}\left|\begin{array}{c}
1 \\
0 \\
1 \\
1
\end{array}\right| \\
& =\frac{w\left(c_{0}\left(1-b_{1} z\right)+c_{1} w\left(b_{0}+\left(c^{2}-b^{2} d z\right)\right)\right.}{22_{2}{ }_{2}{ }_{2}{ }_{2}{ }_{2}{ }^{2}\left(b_{0}+\left(c_{0}-b_{0}\right) z\right)\left(b_{1}+\left(c_{1}-b_{1}\right) z\right)} \\
& =c_{0} \sum_{j \geq 0} w^{2 j+1} \frac{\left(b_{0}+\left(a_{j}^{2}-b_{j}^{2}\right) z\right)^{j}\left(b_{1}+\left(c_{1}^{2}-b_{1}^{2}\right) z\right)^{j}}{\left(1-b_{0} z\right)^{j+1}\left(1-b_{1} z\right)^{j}} \\
& +c_{1} \sum_{j \geq 0} w^{2 j+2} \frac{\left(b_{0}+\left(c_{0}^{2}-b_{0}^{2}\right) z\right)^{j+1}\left(b_{1}+\left(c^{2}{ }_{1}-b^{2}\right) z\right)^{j}}{\left(1-b_{0} z\right)^{j+1}\left(1-b_{1} z\right)^{j+1}} \\
& \underline{k+\epsilon} \quad k-\epsilon \\
& =\sum_{k \geq 0} w^{k+1} c_{\epsilon} \frac{\left(\nu_{1}\left(1+\nu_{3} z\right)\right)^{2}\left(\nu_{2}\left(1+\nu_{4} z\right)\right)^{2}}{\left(1-\gamma_{1} z\right)^{1+\frac{k-\epsilon}{2}}\left(1-\gamma_{2} z\right)^{\frac{k+\epsilon}{2}}}, \tag{4.32}
\end{align*}
$$

where we have used the notation $\epsilon:=k \bmod 2$ (with $\epsilon \in\{0,1\}$ ), and the following weights:

$$
\begin{align*}
& \gamma_{1}=b_{0}=\frac{\sin (u-v-\eta)}{\sin (u-v+\eta)}, \quad \gamma_{2}=b_{1}=\frac{\sin (u+v+\eta)}{\sin (u+v-\eta)}{ }^{\prime} \\
& c^{2}-b^{2}  \tag{4.33}\\
& \gamma_{3}={ }^{-}{ }^{0} b_{0}{ }^{0}=-\frac{\sin (u-v+3 \eta)}{\sin (u-v-\eta)}, \quad \gamma_{4}=\frac{{ }^{1} b^{2}}{b_{1}}=-\frac{\sin (u+v+3 \eta)}{\sin (u+v+\eta)} .
\end{align*}
$$

To obtain (4.32), we have used the fact that the first step of path is horizontal with $y$ parity unspecified (and receives no weight $z$ ), and the last step is vertical, with $y=0$ (and receives the weight $w$ ).

432 Asymptotics. We wish to take the large $n=N$ scaling limit with $\kappa=k /(2 N)$ and $\lambda=I / N$ finite. Further expanding (4.32) in powers of $z$, we find:

$$
\begin{aligned}
& \Sigma \\
& Y_{k, l}=\begin{array}{cccc}
\substack{P_{1}, P_{2}, P_{3}, P_{P} \geq 0 \\
P_{1}+P_{2}+P_{3}+P_{4}=l} & P_{1} & P_{2} & P_{3} \\
& & & \\
\hline
\end{array} \\
& \times \quad 2^{\frac{k-\epsilon}{P}} V_{1}^{P_{1}+\frac{k+\epsilon}{2}} v_{2}^{P_{2}+\frac{k-\epsilon}{2}} V_{3}^{P_{3}} \gamma_{4}^{P_{4}} \\
& \int_{1} \\
& Y_{2 \kappa N, \lambda N} \quad \mathrm{~d} p_{2} \mathrm{~d} p_{3} \mathrm{~d} p_{4} \mathrm{e}^{-N S_{1}^{6 \mathrm{~V}^{\prime}}\left({ }_{\kappa \kappa}\right)_{2} p 3_{3}^{p} 4} \\
& 0
\end{aligned}
$$

$$
\begin{align*}
S_{1}^{6 \mathrm{v}^{\prime}}\left(\kappa, p_{2}, p_{3}, p_{4}\right)= & -\left(\kappa+\lambda-p_{2}-p_{3}-p_{4}\right) \log \left(\kappa+\lambda-p_{2}-p_{3}-p_{4}\right) \\
& +\left(\lambda-p_{2}-p_{3}-p_{4}\right) \log \left(\lambda-p_{2}-p_{3}-p_{4}\right) \\
& -\left(\kappa+p_{2}\right) \log \left(\kappa+p_{2}\right)+p_{2} \log \left(p_{2}\right)+p_{3} \log \left(p_{3}\right) \\
& +\left(\kappa-p_{3}\right) \log \left(\kappa-p_{3}\right)+p_{4} \log \left(p_{4}\right)+\left(\kappa-p_{4}\right) \log \left(\kappa-p_{4}\right) \\
& -\left(\kappa+\lambda-p_{2}-p_{3}-p_{4}\right) \log \left(\nu_{1}\right)-\left(\kappa+p_{2}\right) \log \left(\nu_{2}\right) \\
& -p_{3} \log \left(\gamma_{3}\right)-p_{4} \log \left(\nu_{4}\right) . \tag{4.34}
\end{align*}
$$

Here we have eliminated $P_{1}$ and replaced the remaining summations over $P_{i}$ by integrations over $p_{i}=P_{i} / n$ in $[0,1]$. Note that this covers the case of vanishing weights $\gamma_{i}$ for $i=3$ or 4 as well: if $\gamma_{i}=0$ we simply suppress $P_{i}$ from the above expression, which in turn corresponds to taking the $p_{i} \rightarrow 0$ limit at finite $\gamma_{i}$ in (4.34).

## 44. Refined one-point functions and asymptotics

44.1. Refined partition function. Let $Z_{n, k}^{6 \mathrm{v}^{\prime}}[u, v]$ denote the refined partition function of the $6 \mathrm{~V}^{\prime}$ model on the rectangular grid of size $(2 n-1) \times n$ with uniform weights (2.7) and (2.8), in which the rightmost path is conditioned to first visit the rightmost vertical line at a point at position $k \notin 1,2 n 1 \ddagger$ (counted from bottom to top), before going vertically down until its endpoint, as illustrated in figure 9 (bottom left, pink domain, with the $k$ final steps removed). This quantity is easily related to the semi-homogeneous partition function $Z_{n}^{6 \mathrm{v}^{\prime}}[u, v ; \xi]$ as follows. In the latter, only the weights of the last column (with spectral parameter $v_{n}=v+\xi$ ) are different, and depend on the parity of the vertex height. Let us denote by $\left(\bar{a}_{i}, \bar{b}_{i}, \bar{c}_{i}\right), i=o, e$ the relative $6 \mathrm{~V}^{\prime}$ weights (ratio of the value at $v+\xi$ by that at $v$ ):

$$
\begin{array}{lll}
\bar{a}_{o}=\frac{\sin (u-v-\xi+\eta)}{\sin (u-v+\eta)}, & \bar{b}_{o}=\frac{\sin (u-v-\xi-\eta)}{\sin (u-v-\eta)}, & \bar{c}_{o}=1 \\
\bar{a}_{e}=\frac{\sin (u+v+\xi-\eta)}{\sin (u+v-\eta)}, & \bar{b}_{e}=\frac{\sin (u+v+\xi+\eta)}{\sin (u+v+\eta)}, & \bar{c}_{e}=1 .
\end{array}
$$

Contributions to $Z_{n, k}^{6 \mathrm{v}^{\prime}}[u, v]$ have a last column with $k-1$ bottom vertices of type b (vertical step), the $k$ th vertex of type $c$ (right turn), and the top $2 n 1-k$ vertices of type $a$ (empty). Splitting contributions according to the parity of the position of the point of entry into the last column of the rightmost path, we arrive at:

$$
\begin{aligned}
Z_{n}^{6 \mathrm{v}^{\prime}}[u, v ; \xi]= & \sum_{j=1}^{\mathrm{K}} Z_{n, 2 j-1}^{6 \mathrm{v}^{\prime}}[u, v]\left(\bar{b}_{o} \bar{b}_{e}\right)^{j-1} \bar{c}_{o}\left(\bar{a}_{e} \bar{a}_{o}\right)^{n-j} \\
& +\sum_{j=1}^{\sum_{n, 2 j}^{6}} Z_{\mathrm{v}^{\prime}}[u, v]\left(\bar{b}_{o} \bar{b}_{e}\right)^{j-1} \bar{b}_{o} \bar{c}_{e} \bar{a}_{o}\left(\bar{a}_{e} \bar{a}_{o}\right)^{n-j-1} \\
= & \left(\bar{a}_{e} \bar{a}_{o}\right)^{n-1} \sum_{j=1}^{n} \tau^{j-1}\left\{Z_{n, 2 j-1}^{6 \mathrm{v}^{\prime}}[u, v]+Z_{n, 2 j}^{6 \mathrm{~V}^{\prime}}[u, v] \sigma\right\},
\end{aligned}
$$

where we have used the values $\bar{c}_{o}=\bar{c}_{e}=1$ and the parameters

$$
\tau:=\frac{\bar{b}_{o} \bar{b}_{e}}{\bar{a}_{e} \bar{a}_{o}}=\frac{\sin (u-v-\xi-\eta) \sin (u+v+\xi+\eta) \sin (u-v+\eta) \sin (u+v-\eta)}{\sin (u-v-\eta) \sin (u+v+\eta) \sin (u-v-\xi+\eta) \sin (u+v+\xi-\eta)}
$$

$$
\sigma:=\frac{\bar{b}_{o}}{\bar{a}_{e}}=\frac{\sin (u-v-\xi-\eta) \sin (u+v-\eta)}{\sin (u-v-\eta) \sin (u+v+\xi-\eta)} .
$$

For use with the tangent method, we need to consider the refined one-point function $H_{n, k}[u, v]$ defined as the ratio of the partition function of the $6 \mathrm{~V}^{\prime}$ model in which the topmost path ends at position $k$ with a horizontal last step between the $n \quad 1$ st vertical and the rightmost vertical, to that of the usual $6 \mathrm{~V}^{\prime}$ partition function. Note that the numerator is slightly different from the refined partition function $Z_{n, k}^{6 \mathrm{~V}^{\prime}}[u, v]$ as the rightmost path does not continue with $k$ vertical steps after hitting the rightmost vertical. Consequently, we must replace the $k 1$ corresponding $b$-type weights with $a$-type weights:

$$
\begin{aligned}
& H_{n, 2 j-1}[u, v]:=\begin{array}{c}
\underline{a}_{o} a_{\underline{e}}{ }^{j-1} Z^{6 \mathrm{v}^{\prime}{ }_{1}{ }_{1}[u, v]} \\
b_{o} b_{e}
\end{array},
\end{aligned}
$$

In terms of the one-point function $H_{n}^{6 v^{\prime}}[u, v ; \xi]$ (4.11), the above identity reads:

$$
H_{n}^{6 \mathrm{v}}[u, v ; \xi]=\left(\bar{a}_{e} \bar{a}_{o}\right)^{n-1} \sum_{j=1}^{\sum} t^{j-1}\left\{H_{n, 2 j-1}[u, v]+H_{n, 2 j}[u, v] s\right\}
$$

where

$$
\begin{aligned}
& t=\tau \frac{\underline{b}_{o} \underline{b}_{e}}{a_{o} a_{e}}=\frac{\sin (u-v-\xi-\eta) \sin (u+v+\xi+\eta)}{\sin (u-v-\xi+\eta) \sin (u+v+\xi-\eta)} \\
& s=\sigma^{\underline{b_{o}}}=\frac{\sin (u-v-\xi-\eta) \sin (u+v-\eta)}{\sin (u-v+\eta) \sin (u+v+\xi-\eta)}
\end{aligned}
$$

442 Asymptotics. We wish to estimate the leading behavior of the one-point function $H_{N, k}[u, v]$ for large $N$ and $\kappa=k /(2 N)$ finite. To this end, we use the asymptotics of the function $H_{N}^{6 v^{\prime}}[u, v ; \xi]$ (theorem 4.11) to estimate for large $N$ :

$$
\begin{align*}
& \frac{H_{N}^{6 V^{\prime}}[u, v ; \xi]}{\left(\bar{a}_{e} \bar{a}_{o}\right)^{N-1}} \quad \mathrm{e}^{-N \phi^{6 V^{\prime}}{ }_{[u, v ; \xi]}} \\
& \phi^{6 \mathrm{v}^{\prime}}[u, v ; \xi]=\psi^{6 \mathrm{v}^{\prime}}[u, v ; \xi]+\log \frac{\int \sin (u-v-\xi+\eta) \sin (u+v+\xi-\eta)}{\sin (u-v+\eta) \sin (u+v-\eta)} \\
& =\int_{\log } \frac{\sin (2 v) \sin (u-v-\xi-\eta) \sin (u+v+\xi+\eta)}{\sin (2 v+\xi) \sin (u-v-\eta) \sin (u+v+\eta)}, \\
& \int \log -\frac{\sin (\alpha \xi) \sin (\alpha(\xi+2 v+2 \eta)) \sin (\alpha(u-v-\eta)) \sin (\alpha(u+v+\eta \eta))}{\alpha \sin (\xi) \sin (2 \alpha(v+\eta)) \sin (\alpha(u-v-\xi-\eta)) \sin (\alpha(u+v+\xi+\eta))} . \tag{4.35}
\end{align*}
$$

This leads finally to the following result.

Theorem 4.14. The large $N$ asymptotics of the refined one-point function for the $6 V^{\prime}$ model are given by:

$$
H_{N, 2 \kappa N}[u, v] \quad-\frac{\mathrm{d} t}{2 \mathrm{i} \pi t} \mathrm{e}^{-N S_{0}^{6 \mathrm{~V}^{\prime}}(\kappa, t)}
$$

$$
\begin{equation*}
S_{0^{6 \mathrm{~V}^{\prime}}}(\kappa, t)=\phi^{6 \mathrm{~V}^{\prime}}[u, v, \xi]+\kappa \log (t), \tag{4.36}
\end{equation*}
$$

where the variable $t$ is integrated over a contour around the origin, $\phi^{6 \mathrm{v}^{\prime}}[u, v, \xi]$ is as in (4.35), and where $\xi$ can be thought of as an implicit function of the variable $t$, upon inversion of the relation

$$
\begin{equation*}
t=t_{6 \mathrm{v}^{\prime}}[\xi]:=\frac{\sin (u-v-\xi-\eta) \sin (u+v+\xi+\eta)}{\sin (u-v-\xi+\eta) \sin (u+v+\xi-\eta)} \tag{4.37}
\end{equation*}
$$

The leading contribution to (4.36) is determined by the solution of the saddle point equation $\partial_{t} S_{0}^{\sigma}(\kappa, t)=0$ or equivalently $\partial_{\xi} S_{0}^{\sigma}\left(\kappa, t_{6 \mathrm{v}^{\prime}}[\xi]\right)=0$, leading to:

$$
\begin{equation*}
\kappa=\kappa_{6 \mathrm{v}^{\prime}}[\xi]:=-\frac{t_{6 \mathrm{v}^{\prime}}[\xi]}{\partial_{\xi} \tau_{6 \mathrm{~V}}}[\xi] \partial_{\xi} \phi^{6 \mathrm{v}^{\prime}}[u, v ; \xi] . \tag{4.38}
\end{equation*}
$$

Explicitly we have:

$$
\begin{align*}
\kappa_{6 \mathrm{v}^{\prime}}[\xi]= & \{\cot (u-v-\eta-\xi)+\cot (\xi)+\cot (\xi+2 v)-\cot (u+v+\eta+\xi) \\
& -\alpha(\cot (\alpha(u-v-\eta-\xi))+\cot (\alpha \xi) \\
& +\cot (\alpha(\xi+2 v+2 \eta))-\cot (\alpha(u+v+\eta+\xi)))\} \\
& \times \frac{\sin (u+v-\eta+\xi) \sin (u+v+\eta+\xi) \sin (u-v-\eta-\xi) \sin (u-v+\eta-\xi)}{\sin (2 \eta)(\cos (2 \eta)-\cos (2 u) \cos (2 v+2 \xi))} \tag{4.39}
\end{align*}
$$

with $\alpha=\frac{\pi}{\pi-2 \eta}$ as usual.

### 4.5 Arctic curves

451. NE branch. As explained above, the first application of the tangent method gives access to the portion of the arctic curve situated in the NE corner of the rectangular domain.

Theorem 4.15. The NE branch of the arctic curve for the $6 V^{\prime}$ model as predicted by the tangent method is given by the parametric equations

$$
x=\underset{\mathrm{NE}}{X^{6 \mathrm{~V}^{\prime}}[\xi]=\frac{B^{\prime}[\xi]}{\overline{A^{\prime}[\xi]}} \quad y=\underset{\mathrm{NE}}{Y^{6 \mathrm{~V}^{\prime}}}[\xi]=B[\xi]-\frac{A[\xi]}{A^{\prime}[\xi]} B^{\prime}[\xi]}
$$

with the parameter range:

$$
\xi \in \eta+|u|-v-\pi, 0
$$

and where

$$
A[\xi]=2 \frac{\sin (u-v-\eta-\xi) \sin (u-v+\eta-\xi) \sin (u+v-\eta+\xi) \sin (u+v+\eta+\xi)}{\sin (\xi-2 \eta) \sin (\xi)(\cos (2 \eta)-\cos (2 u) \cos (2 v+2 \xi))}
$$

and $B[\xi]=2 \kappa_{6 \mathrm{v}^{\prime}}[\xi]$, with $\kappa_{6 \mathrm{v}^{\prime}}[\xi]$ is as in (4.39).

Proof. We may now bring together the ingredients of the tangent method. We determine the family of tangents $F_{\xi}(x, y)=y+A[\xi] x-B[\xi]$ defined in section 2.2 . We already identified the
intercept $B[\xi]=2 \kappa_{6 \mathrm{v}^{\prime}}[\xi]$ with $\kappa_{6 \mathrm{v}^{\prime}}[\xi]$ given by (4.39). To determine the slope $A[\xi]=2 \kappa / \lambda$, we must find the leading contribution to the total partition function

$$
\begin{aligned}
& { }_{k=1}^{2_{n-1}} H_{N, k}[u, v] Y_{k, l} \quad{ }_{0}^{\mathrm{J}} \mathrm{~d} \kappa H_{N, 2 \kappa N}[u, v] Y_{2 \kappa N, \lambda N} \quad \mathrm{~J}_{1}^{1} \mathrm{~d} \kappa \mathrm{~d} p_{2} \mathrm{~d} p_{4}, \mathrm{~d} p_{5} \mathrm{e}^{-N S^{6 \mathrm{v}^{\prime}}{ }_{(\kappa, p 2, p 4, p s, t)}}
\end{aligned}
$$

with $S_{0}^{6 \mathrm{v}^{\prime}}(\kappa, t)$ as in (4.36) and $S_{1}^{6 \mathrm{v}^{\prime}}\left(\kappa, p_{2}, p_{3}, p_{4}\right)$ as in (4.34). As in the 6 V case, the saddlepoint equation $\partial_{\xi} S^{6 \mathrm{~V}^{\prime}}=0$ is solved by (4.39), and amounts to parameterizing $\kappa=K_{6 \mathrm{~V}^{\prime}}[\xi]$ in terms of the parameter $\xi$. The saddle-point equations $\partial_{K} S^{6 \mathrm{~V}^{\prime}}=\partial_{p_{2}} S^{6 \mathrm{~V}^{\prime}}=\partial_{p_{3}} S^{6 \mathrm{~V}^{\prime}}=\partial_{p_{4}} S^{6 \mathrm{~V}^{\prime}}=$ 0 give rise to the system of algebraic equations:

$$
\begin{aligned}
& \frac{t}{\gamma_{1} \boldsymbol{V}}=\frac{\left(p_{2}+\kappa\right)\left(\kappa+\lambda-p_{2}-p_{3}-p_{4}\right)}{\left(p_{3}-\kappa\right)\left(p_{4}-\kappa\right)} \\
& 2 \\
& \underline{k}_{1}=\left(p_{2}+\kappa\right)\left(\lambda-p_{2}-p_{3}-p_{4}\right) \\
& \nu_{2} \quad p_{2}\left(\kappa+\lambda-p_{2}-p_{3}-p_{4}\right) \\
& \underline{\underline{L}}_{1}=\frac{\left(\kappa-p_{3}\right)\left(\lambda-p_{2}-p_{3}-p_{4}\right)}{p_{3}(\kappa)} \\
& \nu_{3} \quad p_{3}\left(\kappa+\lambda-p_{2}-p_{3}-p_{4}\right) \\
& \begin{array}{l}
\underline{K}_{1} \\
\gamma_{4}
\end{array}=\frac{\left(\kappa-p_{4}\right)\left(\lambda-p_{2}-p_{3}-p_{4}\right)}{p_{4}\left(\kappa+\lambda-p_{2}-p_{3}-p_{4}\right)} .
\end{aligned}
$$

Substituting the values of the weights $Y_{i}(4.33)$ and $t=t_{6 V^{\prime}}[\xi]$ (4.37), we find the unique solution such that $\lambda, \kappa>0$ :

$$
\begin{align*}
& \underline{p}_{\underline{2}}=-\frac{\sin (u+v+\eta) \sin (\xi) \quad}{\kappa} \quad \underline{p_{3}}=-\frac{\sin (u-v-3 \eta) \sin (\xi)}{\sin (2 \eta) \sin (u+v-\eta+\xi)} \quad \kappa \quad \sin (2 \eta) \sin (u-v-\eta-\xi) \\
& p_{4} \\
& \frac{\sin (u+v+3 \eta) \sin (\xi)}{\kappa}=\frac{}{\sin (2 \eta) \sin (u+v+\eta+\xi)} \\
& \frac{\kappa}{\lambda}=\frac{\sin (u-v-\eta-\xi) \sin (u-v+\eta-\xi) \sin (u+v-\eta+\xi) \sin (u+v+\eta+\xi)}{\sin (\xi-2 \eta) \sin (\xi)(\cos (2 \eta)-\cos (2 u) \cos (2 v+2 \xi))}
\end{align*}
$$

Using the parametrization $\kappa=\kappa_{6 \mathrm{~V}^{\prime}}[\xi]$, we may interpret the last equation as determining $\lambda$ as a function $\lambda_{6 \mathrm{v}^{\prime}}[\xi]$ of the parameter $\xi$, where:

$$
\begin{align*}
\lambda_{6 \mathrm{v}^{\prime}}[\xi]:= & \kappa_{6 \mathrm{v}^{\prime}}[\xi] \\
& \times \frac{\sin (\xi-2 \eta) \sin (\xi)(\cos (2 \eta)-\cos (2 u) \cos (2 v+2 \xi))}{\sin (u-v-\eta-\xi) \sin (u-v+\eta-\xi) \sin (u+v-\eta+\xi) \sin (u+v+\eta+\xi)} . \tag{4.41}
\end{align*}
$$

To summarize, we have found the most likely exit point $\kappa$ as an implicit function of the arbitrary parameter $\lambda$, via the parametric equations $(\kappa, \lambda)=\left(\kappa_{6 \mathrm{~V}^{\prime}}[\xi], \lambda_{6 \mathrm{~V}^{\prime}}[\xi]\right)$, which results in the family of tangent lines with equations $F_{\xi}(x, y)=0$. The theorem follows from the expressions (2.20), by identifying the slope $A[\xi]=2 \kappa_{6 \mathrm{v}^{\prime}}[\xi] / \lambda_{6 \mathrm{v}^{\prime}}[\xi]$, while the range of the parameter $\xi$ corresponds to imposing $A[\xi] \in[0, \infty)$.
4.52 SE branch. As mentioned in section 2.2.2, a simple transformation of the model gives access to the portion of the arctic curve situated in the SE corner of the rectangular domain: we must change parameters $(u, v) \gg\left(u^{*}, v^{*}\right)=(-u,-v-\pi)$ and coordinates $(x, y)>\rightarrow(x, 2-$ $x-y$ ).

Theorem 4.16. The $S E$ branch of the arctic curve for the $6 V^{\prime}$ model is given by the parametric equations

$$
\begin{aligned}
& x=X_{S \mathrm{E}}^{\mathrm{G}}[\xi]=X_{\mathrm{S}}^{\mathrm{S} \mathrm{~V}^{\prime}}{ }^{*}[\xi] \quad y=Y_{\mathrm{SE}}^{\mathrm{V}}[\xi]=2-Y_{\mathrm{NE}}^{6 \mathrm{~N}^{\prime}}[\xi] \quad(\xi \in[\eta+|u|+v, 0]) \\
& \text { with } X_{\mathrm{NE}}^{6 \mathrm{~V}^{\prime}}, Y_{\mathrm{NE}}^{6 \mathrm{~V}^{\prime}} \text { as in theorem } 4.15 \text {, and where the superscript }{ }^{*} \text { standsfor the transformation } \\
& (u, v) \quad\left(u^{*}, v^{*}\right)=(-u,-v-\pi) \text {, which we have also applied to the parameter range. }
\end{aligned}
$$

Remark 4.17. In the case $v=-\frac{\pi}{2}=v^{*}$, we note that the equation of the tangent is invariant under $u \rightarrow-u=u^{*}$. We deduce that the arctic curve is symmetric w.r.t. the line $y=1$, and that the SE branch is simply the reflection of the NE branch: $X_{\mathrm{SE}}=X_{\mathrm{NE}}, Y_{\mathrm{SE}}=2-Y_{\mathrm{NE}}$. This is no longer true when $v /=-2^{\frac{\pi}{2}}$.

## 4. Examples

In this section, we illustrate theorems 4.15 and 4.16 with some concrete examples.
4.61. The ' $6 V$ ' case $u=0, v=-\pi$. The condition $u=0$ implies that all horizontal spectral parameters are equal, and that the Boltzmann weights (2.7) and (2.8) lose their dependence on the parity of the row (upon taking $\rho_{e}=\rho_{o}=\rho$ ). In fact this gives a mapping to the weights (2.1) of the ordinary 6 V model via $\left(u_{6 \mathrm{v}^{\prime}}, v_{6 \mathrm{v}^{\prime}}\right) \quad\left(0,-u_{6} \mathrm{~V}\right)$. We may wonder how the U-turn boundary condition has affected the thermodynamics of the 6V-DWBC model. In fact, extending the usual connection between ASM and VSASM, it is easy to identify the $6 \mathrm{~V}^{\prime}$ model at $u=0$ with a 6 V -DWBC model on a grid of 'double' size $2 n+\nless 2 n+1$, and whose configurations are vertically symmetric, i.e. invariant under reflection w.r.t. a vertical line. As noted in remark 3.8, the parameter $u$ in the 6V-DWBC case may be interpreted as an anisotropy parameter. Indeed, the value $u=\frac{\pi}{2}$ corresponds for the 6V-DWBC model to identical weights $a=b$ which imply invariance of the partition function under reflection w.r.t. a horizontal line. However, when $u \neq \frac{\pi}{2}$, this is no longer true, as the weights $a=b$ are interchanged in the reflection. As a consequence, the tangency points of the arctic curve to the boundary of the domain move away from their symmetric positions. We expect therefore a connection between 6 V -DWBC and $6 \mathrm{~V}^{\prime}$ models only at the isotropic point $u_{6 \mathrm{~V}}=\frac{\pi}{2}$, corresponding to $\left(u_{6 \mathrm{~V}^{\prime}}, \mathrm{v}_{6 \mathrm{v}^{\prime}}\right)=\left(0,-\frac{\pi}{2}\right)$. Note that this point corresponds to the $\tau$-enumeration of VSASM (for the $6 \mathrm{~V}^{\prime}$ side) and ASM (for the 6 V side), with $\tau=4 \sin ^{2}(\eta)$.

Theorem 4.18. For arbitrary $0<\eta<\frac{\pi}{2}$, the arctic curve for the $6 V^{\prime}$ model with $\left(u_{6 \mathrm{v}^{\prime}}, v_{6 \mathrm{v}^{\prime}}\right)=\left(0,-\frac{\pi}{2}\right)$ as obtained via the tangent method assuming conjecture 4.9 holds is identical to that of the $6 V-D W B C$ model with $u_{6 \mathrm{~V}}=\frac{\pi}{2}$ in the NE/SE sector, up to global rescaling.

Proof. As our choice of parameters is invariant under the symmetry * for both the $6 \mathrm{~V}^{\prime}$ case $\left(u_{6 \mathrm{~V}^{\prime}}, v_{6 \mathrm{~V}^{\prime}}\right)^{*}=\left(u_{6 \mathrm{~V}^{\prime}}, v_{6 \mathrm{~V}^{\prime}}\right)=\left(0,-\frac{\pi}{2}\right)$ and the 6 V case $u_{6 \mathrm{~V}}^{*}=u_{6 \mathrm{~V}}=\frac{\pi}{2}$, we simply have to compare the envelope of the corresponding families of tangent lines leading to the NE branches,


Figure 12. Arctic curves for the $6 \mathrm{~V}^{\prime}$ model with parameter $u=0$. Left: case $v=\frac{\pi}{2}$, with $\eta$ ranging from $0^{+}$(outermost curve) to $\sqrt{2}-$ (innermost curve): all curves are symmetric w.r.t. the line $y=1$, and coincide with those of the 6 V -DWBC model (NE/SE portions). Right: arctic curve of the $6 \mathrm{~V}^{\prime}$ model for $\eta=\frac{\pi}{3}, u=0$ and $v=-\pi \frac{\pi}{2}$ (red curve) compared with the arctic curve of the 6V-DWBC model (scaled by a factor of 2) for the same value of $\eta$ and the value $u=\frac{\pi}{2}+\frac{\pi}{12}$ leading to the same Boltzmann weights (blue curve).
as given by theorems 3.6 and 4.15. We have the two families (we add a superscript $6 \mathrm{~V}, 6 \mathrm{~V}^{\prime}$ to avoid ambiguities):

$$
y+A^{6 \mathrm{~V}}[\xi] x-B^{6 \mathrm{~V}}[\xi]=0 \quad \text { and } \quad y+A^{6 \mathrm{~V}^{\prime}}[\xi] x-B^{6 \mathrm{~V}^{\prime}}[\xi]=0 .
$$

We find:

$$
\lim _{u \rightarrow 0, v \rightarrow-\frac{\pi}{2}} A^{6 \mathrm{~V}^{\prime}}[\xi]=\lim _{u \rightarrow \frac{\pi}{2}} A^{6 \mathrm{~V}}[\xi], \quad \lim _{u \rightarrow 0, v \rightarrow-\frac{\pi}{2}} B^{6 \mathrm{~V}^{\prime}}[\xi]=2 \lim _{u \rightarrow \frac{\pi}{2}} B^{6 \mathrm{~V}}[\xi]
$$

while the 6 V and $6 \mathrm{~V}^{\prime}$ ranges of the parameter $\xi$ coincide with $\xi \in\left[\eta-\frac{\pi}{2}, 0\right]$. We deduce that upon rescaling of $x$ and $¥$ by a factor of 2 the two families are identical, and conclude that $\left(X_{\mathrm{NE}}^{\circ}[\xi], Y_{\mathrm{NE}}^{0}[\xi]\right)=2\left(X_{\mathrm{NE}}^{6 V}[\xi], Y^{6}[\xi]\right)$. The SE branch identification follows immediately from our remark on the symmetry ${ }^{\mathrm{NE}}$, leading to $\left(X_{\mathrm{SE}}^{6 \mathrm{~V}^{\prime}}[\xi], Y_{\mathrm{SE}}^{6 \mathrm{~V}^{\prime}}[\xi]\right)=2\left(X_{\mathrm{SE}}^{6 \mathrm{~V}}[\xi], Y_{\mathrm{SE}}^{6 \mathrm{~V}}[\xi]\right)$ as well, and the theorem follows.

A particular case of theorem 4.18 corresponds to the uniform case where the 6 V -DWBC model boils down to the enumeration of ASM, and the $6 \mathrm{~V}^{\prime}$ model to that of VSASM. The arctic curves for both these cases were derived in [CP10a, CP10b] and [DFL18] respectively, and shown to coincide.

For illustration, we have represented in figure 12 (left) the corresponding arctic curves for some values of $\eta$ ranging from $0^{+}$to $\frac{\pi}{2}-$ : the curves are identical to the NE/SE portions of the arctic curve of the $6 \mathrm{~V}-\mathrm{DWBC}$ model, upon a rescaling by a global factor of 2 . For $\eta \rightarrow 0^{+}$, we


Figure 13. Arctic curves for the free fermion case $\eta=\frac{\pi}{4}$ of the $6 \mathrm{~V}^{\prime}$ model. Left: symmetric case $v=-\frac{\pi}{2}$, with $u$ ranging from $0^{+}$(outermost curve on the vertical $x=-1$ ) to $\pi-$ (innermost curve on the vertical $x=-1$ ): all curves are symmetric w.r.t. the line

find the following limiting arctic curve:

$$
\left.\left(X_{\mathrm{NE}}, Y_{\mathrm{NE}}\right)\right|_{\eta \rightarrow 0}=\frac{1}{\pi}(2 \xi-\sin (2 \xi)), 1-\frac{1}{\pi}(2 \xi+\sin (2 \xi)) \quad \xi \in-\frac{\pi}{2}, 0 .
$$

The limit $\eta \rightarrow \frac{\pi}{2}^{-}$is singular, as the parameter $\alpha=\pi /(\pi-2 \eta)$ diverges. However, one can take a double scaling limit $\eta=\frac{\pi}{2}-\epsilon, \xi=\epsilon \zeta$, and $\epsilon \rightarrow 0$, in which case the limiting curve reads:

$$
\begin{aligned}
& \left.X_{\mathrm{NE}}\right|_{\epsilon \rightarrow 0}=\frac{(2+\zeta)^{2}\left(\cos (2 \pi \zeta)-1+2 \pi \zeta^{2}\left(\pi\left(1-\zeta^{2}\right) \cos (\pi \zeta)+2 \zeta \sin (\pi \zeta)\right)\right.}{4\left(1+\zeta+\zeta^{2}\right) \sin ^{2}(\pi \zeta)} \\
& \left.Y_{\mathrm{NE}}\right|_{\epsilon \rightarrow 0}=\frac{(1+\zeta)^{2}\left(3 \sin ^{2}(\pi \zeta)+\pi(1-\zeta)^{2}(\pi \zeta(2+\zeta) \cos (\pi \zeta)-2(1+\zeta) \sin (\pi \zeta))\right.}{2\left(1+\zeta+\zeta^{2}\right) \sin ^{2}(\pi \zeta)}
\end{aligned}
$$

for $\zeta \in(-1,0]$.


Figure 14. Arctic curve (NE and SE portions) of the ' 20 V point' of the $6 \mathrm{~V}^{\prime}$ model,


By contrast, in the anisotropic case where $u_{6 \mathrm{v}^{\prime}}=0$ but $v_{6 \mathrm{v}^{\prime}} \neq-\frac{\pi}{2}\left(\right.$ and $\left.u_{6 \mathrm{~V}}=-v_{6 \mathrm{v}^{\prime}}=\frac{\pi}{2}\right)$, the arctic curves no longer coincide. For illustration, the predicted NE and SE portions of arctic curve of the $6 \mathrm{~V}^{\prime}$ model at $\eta=\frac{\pi}{3}, u_{6 \mathrm{v}^{\prime}}=0, v_{6 \mathrm{v}^{\prime}}=-\frac{\pi}{2}-\frac{\pi}{12}$ are depicted in figure 12 (right), together with the arctic curve of the $6_{\underline{\pi}}-D_{\underline{\pi}}$ WBC model with the same values of the weights (i.e. with same $\eta$ and $u_{6 \mathrm{~V}}=-v_{6 \mathrm{v}^{\prime}}={ }_{2}+{ }_{12}$ ): the resulting curves are very different. In particular, the $6 \mathrm{~V}^{\prime}$ curve is anchored at the endpoints $(-1,0)$ and $(-1,2)$ with horizo ntal tangents, whereas the 6 V curve has horizontal tangents at different points $2\left(1-\tau_{3}^{2}\right), 2$
$(-0.309,2)$ and $4\left(\frac{y}{-3}-1\right), 0 \quad(-1.69,0)$.
4.62 The 'free fermion' case $\eta=\frac{\pi}{4}$. This case is nicer in the sense that arctic curves are expected to be analytic. In particular, we checked that the SE portion of the arctic curve is indeed the analytic continuation of the NE one. In figure 13 (left) we represent arctic curves for $\eta=\frac{\pi}{4}$ and the isotropic value $v=-\frac{\pi}{2}$ with $u$ ranging from $0^{+}$to $\frac{\pi-}{4}$. The $u=0$ arctic curve is given by $(x, y)=(\cos (2 \xi)-1, \sin (2 \xi)+1)$ : it is the half-circle $(x+1)^{2}+(y-1)^{2}=1$ with $x \geq-1$, first obtained in [PR19a]. The case $u=\frac{\pi}{4}$ is singular. As before, we consider the


Figure 15. Arctic curve (NE and SE portions) of the $6 \mathrm{~V}^{\prime}$ model with $\eta=\frac{\pi}{3}, u=\frac{\pi}{12}$ and $v$ varying from $-{ }_{2}^{\pi}$ (leftmost curve on top) to ${ }^{\pi}{ }^{\pi} \overline{\overline{2}}-{ }_{12}$ (rightmost curve on top).
double-scaling limit $u=\frac{\pi}{4}+\epsilon$ and $\xi=\epsilon \zeta$, leading to the limiting curve:

$$
(x, y)=-\frac{\zeta^{2}}{1+\zeta^{2}}, \frac{(1+\zeta)^{2}}{1+\zeta^{2}}
$$

equal to the ellipse $(2 x+1)^{2}+(y-1)^{2}=1$ inscribed in the rectangle $[-1,0] \times[0,2]$. We see that the gap between the endpoints of the arctic curve on the vertical $x=-1$ ranges from 2 (semi-circle case) to 0 (ellipse case). This type of arctic curve was also encountered when considering lozenge tilings (an archetypical free fermion model) with free boundary conditions in [DFR12].

In figure 13 (right) we represent arctic curves for $\eta=\frac{\pi}{4}$ and a sample anisotropic value $v=-\frac{\pi}{2}-\frac{\pi}{12}$ with $u$ ranging from $0^{+}$to $\frac{\pi}{6}$. The $u=0$ arctic curve is the quartic:

$$
(x, y)=-\sin ^{2}(\xi) \quad 1+\frac{\cos ^{2}(\xi)}{\cos ^{2} \frac{\pi}{6}-\xi} \quad, \frac{1}{2} \frac{\cos ^{2} \frac{\pi}{6}+\xi}{\cos ^{2} \frac{\pi}{6}-} 1+\sqrt{ } \overline{3} \sin \pi{ }_{3}+2 \xi
$$

The limit $u \rightarrow{ }_{\bar{\sigma}}^{\pi-}$ is singular, but the double scaling línit $u={ }_{\sigma}^{\pi}-\epsilon$ and $\xi=\zeta^{\sqrt{~}} \epsilon$ and $\epsilon \rightarrow 0$ leads to the segment

$$
(x, y)=-1+\frac{1}{1+\frac{43}{} \zeta^{2}}, \frac{2}{1+\frac{43}{} \zeta^{2}} \quad(\zeta \in[0, \infty))
$$

that joins point $(-1,0)$ to $(0,2)$.
4.63. 20 V case. This case corresponds to $\eta=\frac{\pi}{,}{ }_{8} u=\eta=\underline{\pi}$ and $v=-4 \eta=-\frac{\pi}{4}$, by analogy with the 6 V model with DWBC whose partition function is identical to that of the uniformly weighted 20V model with DWBC1,2 studied in references [DDFG20, DFG18]. The corresponding NE/SE portions of arctic curve are depicted in figure 14.
464. Generic case. We present a 'generic case' in figure 15 with $\eta={\underset{3}{3}}^{\pi^{\prime}} u={ }_{-12}^{\pi}$ and $v$ varying from $-\frac{\pi}{2}$ to $-\frac{\pi}{2}-\frac{\pi}{12}$ As before the case $v=-\frac{\pi}{2}-\frac{\pi}{1}$ is singular, but may be investigated via a double scaling limit, leading to the segment joining $(-1,0)$ to $(0,2)$.

## 5. 20 V model with DWBC3

## 5. Partition function and one-point function

In reference [DF21] the partition function of the 20V-DWBC3 model was related to that of the $6 \mathrm{~V}^{\prime}$ model, by use of the integrability of the weights (2.15). More precisely, let us denote by $Z_{n}^{20 \mathrm{~V}}[u, \mathbf{v}]$ the semi-homogeneous partition function of the $20 \mathrm{~V}-\mathrm{DWBC} 3$ model, with all horizontal spectral parameters equal to $\eta+u$, all diagonal ones to- $u$ and arbitrary vertical spectral parameters $\mathbf{v}=v_{1}, v_{2}, \ldots, v_{n}$, and by $Z_{n}^{6 \mathrm{v}^{\prime}}[u, \mathbf{v}]$ the partition function of the $6 \mathrm{~V}^{\prime}$ model with horizontal spectral parameters all equal to $u$ and arbitrary vertical spectral parameters $\mathbf{v}$. We have:

Theorem 5.1 [ DF21]. The following relation holds for all $n \geq 1$ :

$$
\begin{align*}
Z_{n}^{20 \mathrm{~V}}[u, \mathbf{v}]= & \alpha_{n}^{n(3 n-1) / 2} Z_{n}^{6 \mathrm{v}^{\prime}}[u, \mathbf{v}] \sin (2 u+2 \eta)^{n(3 n-1) / 2} \\
& \times{ }_{i=1} \sin \left(u-v_{i}-\eta\right)^{i-1} \sin \left(\eta-u-v_{i}\right)^{i} . \tag{5.1}
\end{align*}
$$

In the homogeneous case where all $v_{i}=v$ for all $i$, this reduces to:

$$
\begin{align*}
Z_{n}^{20 \mathrm{~V}}[u, v]= & \alpha^{n(3 n-1) / 2} Z_{n}^{6 \mathrm{v}^{\prime}}[u, v] \sin (2 u+2 \eta)^{n(3 n-1) / 2} \\
& \times \sin (u-v-\eta)^{n(n-1) / 2} \sin (\eta-u-v)^{n(n+1) / 2} \tag{5.2}
\end{align*}
$$

Next we define the one-point function $H_{n}^{20 \mathrm{~V}}[u, v ; \xi]$ as the ratio:

$$
\begin{align*}
H_{n}^{20 \mathrm{~V}}[u, v ; \xi] & :=-\frac{Z_{n}^{20 \mathrm{~V}}[u, v ; \xi]}{Z_{n}^{20 \mathrm{~V}}[u, v]} \\
& =\frac{\sin (u-v-\xi-\eta)}{\sin (u-v-\eta)}^{n-1} \frac{\sin (\eta-u-v-\xi)}{\sin (\eta-u-v)}{ }^{n} H_{n}^{6 \mathrm{~V}^{\prime}}[u, v ; \xi] \tag{5.3}
\end{align*}
$$

where in $Z_{n}^{20 \mathrm{~V}}[u, v ; \xi]$ we have kept $v_{1}=v_{2}=\cdots=v_{n-1}=v$ but relaxed the last value $v_{n}=v+\xi$. Like in the 6 V and $6 \mathrm{~V}^{\prime}$ cases, this function will be a crucial ingredient of the tangent method.

## 52 Refined one-point functions and asymptotics

521. Refined partition function. Let $Z_{n, k}^{20 \mathrm{~V}}[u, v]$ denote the partition function of the 20 V model on the quadrangle $Q_{n}$ with uniform weights (2.15), in which the rightmost path is conditioned to first visit the rightmost column at a point at position $k$ [ $\mathcal{L} 2 n 1]$ (see figure 16 for an illustration). We may split this partition function into $Z_{n, k}^{20 \mathrm{~V}}[u, v]=Z_{n, k}^{20 \mathrm{~V}}[u, v]+Z_{n, k}^{20 \mathrm{~V}}[u, v]$ according to whether the topmost path accesses the point $k$ via a horizontal - or diagonal $\backslash$ step, before terminating with $k$ vertical steps until its endpoint. This quantity is easily related to the partially inhomogeneous partition function $Z_{n}^{20 \mathrm{~V}}[u, v ; \xi]$ (5.3). Recall that for the latter the weights are homogeneous with parameters $u, v$ except for the $n$th column in which $v$ is replaced by $v+\xi$. Let $\bar{\omega}_{i}:=\omega_{i}[u, v+\xi] / \omega_{i}[u, v]$ be the relative Boltzmann weights for the last column, as compared to the homogeneous values. Specifically, using the weights:

$$
\begin{array}{ll}
\bar{\omega}_{0}=\frac{\sin (u-v-\xi+\eta) \sin (\eta-u-v-\xi)}{\sin (u-v+\eta) \sin (\eta-u-v)}, & \bar{\omega}_{2}=\frac{\sin (u-v-\xi-\eta)}{\sin (u-v-\eta)} \\
\bar{\omega}_{1}=\frac{\sin (u-v-\xi-\eta) \sin (-u-v-\xi-\eta)}{\sin (u-v-\eta) \sin (-u-v-\eta)}, & \bar{\omega}_{4}=\frac{\sin (\eta-u-v-\xi)}{\sin (\eta-u-v)}
\end{array}
$$

we find the following relation, expressing the decomposition of the contributions to $Z_{n}^{20 \mathrm{~V}}[u, v ; \xi]$ according to the configurations of their topmost path (see figure 16 for an illustration):

$$
\begin{equation*}
\underset{n, k}{\bar{\omega}_{4} Z^{20 \mathrm{~V}_{-}}[u, v]+\bar{\omega}_{2} Z_{n, k}^{20 \mathrm{~V}} \backslash[u, v] \quad \bar{\omega}^{2 n-k-1} \bar{\omega}^{k-1}=Z_{n}^{20 \mathrm{~V}}[u, v ; \xi] . . . ~} \tag{5.4}
\end{equation*}
$$

Introducing the parameters

$$
\tau:=\frac{\bar{\omega}_{1}}{\bar{\omega}_{0}}, \quad \sigma:=\frac{\bar{\omega}_{2}}{\bar{\omega}_{4}}
$$

this reads:

522 Refined one-point function. As in the $6 \mathrm{~V}^{\prime}$ case, the corresponding (normalized) refined one-point functions $H_{n, k}^{20 \mathrm{~V}}-[u, v], H_{n, k}^{20 \mathrm{~V}}[u, v]$ are ratios of slightly modified refined partition functions to the original homogeneous partition function $Z_{n}^{20 \mathrm{~V}}[u, v]$. The corresponding configurations have a topmost path that stops at the point $k$ after a last step from the $n-1$ th vertical to the $n$th one (see figure 9 top right, pink domain). Compared to $Z_{n, k}^{20 \mathrm{~V}}-[u, v], Z_{n, k}^{20 \mathrm{~V}} \backslash[u, v]$, we must remove the last $k$ vertical steps of the topmost path, and thus replace the $k$ corresponding weights by 1 (instead of $\omega_{4}, \omega_{2}$ ) for the turning vertex, and by $\omega_{0}$ (instead of $\omega_{1}$ ) for the $k-1$


Figure 16. A sample contribution to the refined partition function $Z_{n, k}^{20 \mathrm{~V}}[u, v]$. In this particular example, the contribution pertains to $Z_{n, k}^{20 \backslash} \backslash[u, v]$. The medallions detail the various weights involved in the last column.
vertices crossed by the path:

$$
\begin{array}{rlrr}
H^{20 \mathrm{~V}-}-[u, v]= & \underline{1} & \underline{\omega}_{0} & \frac{Z_{n, k}^{20 \mathrm{~V}}-[u, v]}{\omega_{4}} \\
\omega_{1} & Z^{00 \mathrm{~V}}[u, v] \\
\left.H_{n, k}^{20 \mathrm{~V} \backslash} \backslash u, v\right]= & \underline{1}^{\omega_{2}} & \underline{\omega}_{0} & \frac{Z_{n, k}^{20 \mathrm{~V}} \backslash[u, v]}{\omega_{2}}  \tag{5.5}\\
& \omega_{1} & Z^{00 \mathrm{~V}}[u, v]
\end{array}
$$

We deduce the relation
where we have used the parameters

$$
\begin{align*}
& t=\tau_{\underline{\omega_{1}}}^{\omega_{0}}=\frac{\sin (u-v-\xi-\eta) \sin (-u-v-\xi-\eta)}{\sin (u-v-\xi+\eta) \sin (\eta-u-v-\xi)}=: t_{20 \mathrm{v}}[\xi], \\
& s=\sigma^{\underline{\omega_{2}}} \omega_{4}=\frac{\sin (u-v-\xi-\eta)}{\sin (\eta-u-v-\xi)} . \tag{5.7}
\end{align*}
$$

We note that the function $t_{20 \mathrm{~V}}[\xi]$ is identical to $t_{6 \mathrm{v}^{\prime}}[\xi]$ of the $6 \mathrm{~V}^{\prime}$ model (4.37).
523. Relation to 6 V one-point function. Using equation (5.3), and noting moreover that $\bar{a}_{o} \bar{a}_{e}=\bar{\omega}_{0}$, we may express:

$$
\begin{array}{cc}
\frac{H_{n}^{20 \mathrm{v}}[u, v ; \xi]}{0} & \frac{\sin (u-v-\xi-\eta)}{n-1}-\frac{\sin (u-v+\eta)}{}{ }^{n} H^{6 \mathrm{v}^{\prime}}[u, v ; \xi]  \tag{5.8}\\
\bar{\omega}^{2 n-1} & \sin (u-v-\eta) \\
\end{array}
$$

524. Asymptotics. We now turn to large $n=N$ asymptotics of the one-point functions (5.5) with the scaled exit point position $\kappa=k /(2 N)$ kept finite. We first note that the relation (5.8) yields the large $N$ asymptotics

$$
\begin{align*}
& \frac{H_{N}^{20 \mathrm{v}}[u, v ; \xi]}{\bar{\omega}_{0}^{2 N-1}} \mathrm{e}^{-N \phi}{ }_{[u, v, \xi]}^{20 \mathrm{v}} \\
& \phi^{20 \mathrm{v}}[u, v ; \xi]= \phi^{6 \mathrm{v}^{\prime}}[u, v, \xi] \quad \log \frac{\sin (u-v-\xi-\eta) \sin (u-v+\eta)}{\sin (u-v-\xi+\eta) \sin (u-v-\eta)} \\
&=-\log \frac{\sin (2 v) \sin ^{2}(u-v-\xi-\eta) \sin (u+v+\xi+\eta) \sin (u-v+\eta)}{\sin (2 v+\xi) \sin ^{2}(u-v-\eta) \sin (u+v+\eta) \sin (u-v-\xi+\eta)} \\
& \log \frac{\sin (\alpha \xi) \sin (\alpha(\xi+2 v+2 \eta)) \sin (\alpha(u-v-\eta)) \sin (\alpha(u+v+\eta))}{\alpha \sin (\xi) \sin (2 \alpha(v+\eta)) \sin (\alpha(u-v-\xi-\eta)) \sin (\alpha(u+v+\xi+\eta))}
\end{align*}
$$

As the parameter $s$ is finite and independent of $k$, using the relation (5.6), the connection between $H_{n}^{20 \mathrm{~V}}[u, v ; \xi]$ to the $6 \mathrm{~V}^{\prime}$ one-point function (5.8) and finally the asymptotics (5.3), we get identical leading behaviors for both one-point functions.

Theorem 5.2. The large $n=N$ scaling limit of the refined one-point functions $H_{n, k}^{20 v}-[u, v]$ and $H_{n, k}^{20 \vee} \backslash[u, v]$ reads:

$$
\begin{gathered}
H_{N, 2 \kappa N}^{20 \mathrm{~V}-}[u, v] \quad H_{N, 2 \kappa N}^{20 \mathrm{~V} \backslash}[u, v] \quad-\frac{\mathrm{d} t}{2 \mathrm{i} \pi t} \mathrm{e}^{-N S_{0}^{20 \mathrm{v}}(\kappa, t)} \\
S_{0}^{2 \mathrm{~V}}(\kappa, t):=\phi^{20 \mathrm{~V}}[u, v ; \xi]+2 \kappa \log (t)
\end{gathered}
$$

where $\phi^{20 \mathrm{~V}}[u, v ; \xi]$ is as in (5.9), and in which the variables t and $\xi$ are related via $t=t_{20 \mathrm{v}}[\xi]$ (5.7).

As before, the integral is dominated at large $N$ by the solution of the saddle-point equation
$\partial_{t} S^{200}(\kappa, t)=0$, or equivalently, changing integration variables to $\xi: \partial_{\xi} S^{20 才}\left(\kappa, t_{20 \mathrm{~V}}[\xi]\right)=0$.
Using the identification $t_{20 \mathrm{~V}}[\xi]=t_{6 \mathrm{v}^{\prime}}[\xi]$, this is easily solved as

$$
\begin{align*}
\kappa= & \kappa_{20 \mathrm{v}}[\xi]:=-\frac{1 t_{6 \mathrm{v}^{\prime}}[\xi]}{2 \partial_{\xi t 6 \mathrm{v}^{\prime}}[\xi]} \partial \phi^{20 \mathrm{v}}[u, v ; \xi] \\
= & \frac{\kappa_{6 \mathrm{v}^{\prime}}[\xi]}{2}+\frac{\cot (u-v-\xi+\eta)-\cot (u-v-\xi-\eta)}{2 \sin (2 \eta)} \\
& \times \frac{\sin ^{2}\left(u-v_{-} \xi+\eta\right) \sin ^{2}\left(u-v_{-} \xi \quad \eta\right)}{\cos (2 u) \cos (2 \xi+2 v)-\cos (2 \eta)} \tag{5.10}
\end{align*}
$$

with $K_{6 v^{\prime}}[\xi]$ as in (4.38) and (4.39).

## 53. Paths

531. Partition function. With the setting of figure 9 (top right, light blue domain), we wish to compute the partition function $Y_{k, \prime}\left(\boldsymbol{B}_{1}, \boldsymbol{B}_{2}\right)$ of a single (Schröder) path of the 20 V model in the first quadrant $Z_{+}^{2}$, with starting point $(0, k)$ and endpoint $(I, 0)$. We include a weight $B_{1}, \boldsymbol{B}_{2}$ according to the configuration of the step taken before entering the path domain (last step in the pink domain, respectively horizontal or diagonal).

The paths receive homogeneous 20 V weights (2.15), with horizontal, vertical, diagonal uniform spectral parameters $u+\eta, v,-u$ respectively, while all vertices not visited by the path receive the weight $\omega_{0}$. As in the previous cases, we may factor out an unimportant overall factor $\omega_{0}^{k \prime}$ (where $k I$ is the area of the light blue rectangle $[0, \Pi] \times[0, k]$ in figure 9 top right), and weight the vertices visited by the path by and extra factor $\frac{1}{\omega 0}$.

The partition function $Y_{k, \prime}\left(\boldsymbol{B}_{1}, \boldsymbol{B}_{2}\right)$ is computed by use of a transfer matrix technique (see [DDFG20] appendix B for details with slightly different definitions). Each path is traveled from N, W to S, E, and the transfer matrix is a $3 \times 3$ matrix whose entries correspond to the vertex weight for the transition from the entering step at each visited vertex to the outgoing step. The three states are $(\rightarrow, \mid)$ for respectively a horizontal, diagonal, vertical step ending at the transition vertex. Moreover we include an extra weight $z, z w, w$ per horizontal, diagonal, vertical outgoing step respectively. Note that the step prior to entering the quadrant (exit from the rectangular domain) may be either horizontal (with an extra weight $\boldsymbol{B}_{1}$ ) or diagonal (with an extra weight $B_{2}$ ), while the last step is vertical. The transfer matrix $T_{20 \mathrm{v}}$ reads:

$$
T_{20 \mathrm{~V}}=\frac{1}{\omega_{0}} \begin{array}{ccc}
\omega_{6} z & \omega_{5} z & \omega_{4} z \\
\omega_{5} z W & \omega_{3} z w & \omega_{2} z W \\
\omega_{4} w & \omega_{2} w & \omega_{1} w
\end{array} .
$$

The generating function for the $Y_{k, I}$ reads

$$
\left.\sum_{Y_{k, l}\left(B_{1}, B_{2}\right) z^{k} w^{l+1}=(0,0,1)\left(\mathrm{I}-T_{20 \mathrm{~V}}\right)^{-}} \quad \begin{array}{c}
\left(\begin{array}{c} 
\\
\boldsymbol{B}_{1} \\
\mathrm{~B}_{2}
\end{array}\right) . \\
0
\end{array}\right) .
$$

This is a rational fraction with denominator $\operatorname{det}\left(\mathrm{I}-T_{20 \mathrm{v}}\right)=1-\alpha_{1} w-\alpha_{2} z-\alpha_{3} z w-$ $\alpha_{4} z w^{2}-\alpha_{5} z^{2} w-\alpha_{6} z^{2} w^{2}$, where

$$
\begin{align*}
& \alpha_{1}=\frac{\frac{\omega_{1}}{\omega_{0}}, \quad \alpha_{2}=\frac{\omega_{6}}{\omega_{0}}, \quad \alpha_{3}=\frac{\omega_{0} \omega_{3}+\omega_{4}^{2}-\omega_{1} \omega_{6}}{\omega_{0}^{2}}}{\alpha_{4}=\frac{\omega_{2}^{2}-\omega_{1} \omega_{3}}{\omega^{2}}, \quad \alpha_{5}=\frac{\omega_{5}^{2}-\omega_{6} \omega_{3}}{\omega^{2}},} \\
& \alpha_{6}=\frac{2 \omega_{2} \omega_{4} \omega_{5}+\omega_{1} \omega_{6} \omega_{3}-\omega_{3} \omega^{2}-\omega_{1} \omega^{2}-\omega_{6} \omega^{2}}{\omega_{0}^{3}}
\end{align*}
$$

532 Asymptotics. We now consider the large $n=N, k, l$ limit, with $\kappa=k /(2 N)$ and $\lambda=$ $I / N$ fixed. Like in section 4.3.2 above, the asymptotics of $Y_{k, \boldsymbol{\prime}}$ are determined by the
denominator (5.11), and read (see also reference [DDFG20] appendix B for details):

$$
S_{1}^{20 \mathrm{~V}}\left(\kappa, p_{3}, p_{4}, p_{5}, p_{6}\right)=-\left(2 \kappa+\lambda-p_{3}-2 p_{4}-2 p_{5}-3 p_{6}\right) \log \left(2 \kappa+\lambda-p_{3}-2 p_{4}-2 p_{5}-3 p_{6}\right)
$$

$$
+\left(2 \kappa-p_{3}-2 p_{4}-p_{5}-2 p_{6}\right) \log \frac{2 \kappa-p_{3}-2 p_{4}-p_{5}-2 p_{6}}{\alpha}
$$

$$
+\left(\lambda-p_{3}-p_{4}-2 p_{5}-2 p_{6}\right) \log \frac{\lambda-p_{3}-p_{4}-2 p_{5}-2 p_{6}}{\alpha}
$$

$$
\begin{equation*}
+\underbrace{{ }^{6}}_{i=3} p_{i} \log \frac{p_{i}}{\alpha_{i}} \tag{5.12}
\end{equation*}
$$

As before this also covers the case of vanishing weights $\alpha_{i}$ by taking the limit $p_{i} \rightarrow 0$ at finite $\alpha_{i}$ in the above.

## 54. Arctic curves

Theorem 5.3. The NE branch of the arctic curve for the 20V-DWBC3 model on the quadrangle $\mathrm{Q}_{n}$ is predicted by the tangent method to be:

$$
x=\underset{\mathrm{NE}}{X^{20 \mathrm{~V}}[\xi]}=\frac{B^{\prime}[\xi]}{\overline{A^{\prime}[\xi]}}, \quad y=\underset{\mathrm{NE}}{Y^{20 \mathrm{~V}}}[\xi]=B[\xi]-\frac{A[\xi]}{A^{\prime}[\xi]} B^{\prime}[\xi],
$$

where $B[\xi]=2 \kappa_{20 \mathrm{~V}}[\xi]$ with $\kappa_{20 \mathrm{v}}[\xi]$ as in (5.10), and where $A[\xi]$ is given by

$$
\begin{align*}
A[\xi]= & \frac{\cos (2 \eta)-\cos (u+v+\eta) \cos (u+v-\eta+2 \xi)}{\cos (2 \eta)-\cos (2 u) \cos (2 v+2 \xi)} \\
& \times \frac{\sin (u-v-\eta-\xi) \sin (u-v+\eta-\xi)}{\sin (\xi) \sin (\xi-2 \eta)} \tag{5.13}
\end{align*}
$$

and with the parameter range:

$$
\xi \in[\eta+u-v-\pi, 0] .
$$

Proof. We may now bring together the ingredients of the tangent method. We determine the family of tangents $F \xi(x, y)=y+A[\xi] x-B[\xi]$ defined in section 2.2. We already identified the intercept $B[\xi]=2 \kappa_{20 \mathrm{v}}[\xi]$ with $\kappa_{20 \mathrm{v}}[\xi]$ given by (5.10). To determine the slope $A[\xi]=2 \kappa / \lambda$, we must find the leading contribution to the total partition function

$$
\begin{aligned}
& { }_{k=1}^{2_{n-1}} H_{N, k}[u, v] Y_{k, I} \quad \int_{0}{ }^{1} \mathrm{~d} \kappa H_{N, 2 \kappa N}[u, v] Y_{2 \kappa N, \lambda N} \\
& -\frac{\mathrm{d} t}{2 \mathrm{i} \pi t} \int_{0}^{\int_{1}} \mathrm{~d} \kappa \mathrm{~d} p_{3} \mathrm{~d} p_{4}, \mathrm{~d} p_{5} \mathrm{~d} p_{6} \mathrm{e}^{-N S^{20 \mathrm{~V}}\left(\kappa, p_{3}, p_{4}, p 5, p_{6}, t\right)} \\
& S^{6 \mathrm{v}^{\prime}}\left(\kappa, p_{2}, p_{4}, p_{5}, t\right):=S_{0}^{20 \mathrm{v}}(\kappa, t)+S_{1}^{20 \mathrm{~V}}\left(\kappa, p_{3}, p_{4}, p_{5}, p_{6}\right),
\end{aligned}
$$

$$
\begin{aligned}
& \int 1 \\
& Y_{2 \kappa N, \lambda N} \quad{ }_{0} d_{3} \mathrm{~d} p \quad \mathrm{~d} p \quad \mathrm{~d} p \quad \mathrm{e}^{\left.-\mathrm{N}_{4}^{20 v_{(\kappa, p 3, p 4, p 5}}{ }^{2} p_{6}\right)}
\end{aligned}
$$

where the contour of integration of the variable $t$ circles the origin, and with $S_{0}^{20 V}(\kappa, t)$ as in (4.36) and $S_{1}^{20 \mathrm{~V}}\left(\kappa, p_{3}, p_{4}, p_{5}, p_{6}\right)$ as in (5.12). As in the 6 V case, the first saddle-point equation reads $\partial_{t} S^{20 \mathrm{~V}}=0$ or equivalently $\partial_{\xi} S^{20 \mathrm{~V}}=0$, in terms of the dependent variable $\xi$ via $t=t_{20 \mathrm{~V}}[\xi]$. The latter is solved by (5.10), and amounts to parameterizing $\kappa=\kappa_{20 \mathrm{~V}}[\xi]$ in terms of the parameter $\xi$. The other saddle-point equations $\partial_{k} S^{20 \mathrm{~V}}=\partial_{p_{3}} S^{20 \mathrm{~V}}=\partial_{p_{4}} S^{20 \mathrm{~V}}=$ $\partial_{p_{5}} S^{20 \mathrm{~V}}=\partial_{p_{6}} S^{20 \mathrm{~V}}=0$ give rise to the system of algebraic equations:

$$
\begin{aligned}
& \frac{t}{\alpha_{1}}=\frac{2 \kappa+\lambda-p_{3}-2 p_{4}-2 p_{5}-3 p_{6}}{2 \kappa-p_{3}-2 p_{4}-p_{5}-2 p_{6}} \\
& \frac{\alpha_{1}}{2} \underline{\alpha}_{2} \underline{p}_{3} \\
& \alpha_{3}=\frac{\left(2 \kappa-p_{3}-2 p_{4}-p_{5}-2 p_{6}\right)\left(\lambda-p_{3}-p_{4}-2 p_{5}-2 p_{6}\right)}{2 \kappa+\lambda-p_{3}-2 p_{4}-2 p_{5}-3 p_{6}} \\
& \frac{\alpha_{1}^{2} \alpha_{2} p_{4}}{\alpha_{4}}=\frac{\left(2 \kappa-p_{3}-2 p_{4}-p_{5}-2 p_{6}\right)^{2}\left(\lambda-p_{3}-p_{4}-2 p_{5}-2 p_{6}\right)}{\left(2 \kappa+\lambda-p_{3}-2 p_{4}-2 p_{5}-3 p_{6}\right)^{2}} \\
& \frac{\alpha_{1} \alpha_{2}^{2} p_{5}}{\alpha_{5}}=\frac{\left(2 \kappa-p_{3}-2 p_{4}-p_{5}-2 p_{6}\right)\left(\lambda-p_{3}-p_{4}-2 p_{5}-2 p_{6}\right)^{2}}{\left(2 \kappa+\lambda-p_{3}-2 p_{4}-2 p_{5}-3 p_{6}\right)^{2}} \\
& \alpha^{2} \alpha^{2} p_{6}\left(2 \kappa-p_{3}-2 p_{4}-p_{5}-2 p_{6}\right)^{2}\left(\lambda-p_{3}-p_{4}-2 p_{5}-2 p_{6}\right)^{2} \\
& \frac{1}{1_{2}^{2}} \alpha_{6}^{2}=\frac{\left(\lambda-p_{3}-2 p_{4}-2 p_{5}-3 p_{6}\right)^{3}}{} .
\end{aligned}
$$

Substituting the values of $t=t_{20 \mathrm{~V}}[\xi]$ (5.7) and of the weights $\alpha_{i}$ (5.11) expressed using (2.15):

$$
\begin{aligned}
& \alpha_{1}=\frac{\sin (u-v-\eta) \sin (u+v+\eta)}{\sin (u-v+\eta) \sin (u+v-\eta)}, \quad \alpha_{2}=-\frac{\sin (2 u) \sin (u-v-\eta)}{\sin (2 u+2 \eta) \sin (u-v+\eta)} \\
& \alpha_{3}=\frac{2 \sin (2 \eta) \sin (2 u) \sin u-v+\tilde{\pi}_{4} \sin u+v+\underline{\pi}_{4}-\sin ^{2}(2 \eta)}{\sin (2 u+2 \eta) \sin (u-v+\eta) \sin (u+v-\eta)} \\
& \alpha_{4}=\frac{\sin (2 u) \sin (u-v-\eta) \sin (u+v+3 \eta)}{\sin (2 u+2 \eta) \sin (u-v+\eta) \sin (\eta-u-v)} \\
& \alpha_{5}=\frac{\sin (2 u-2 \eta) \sin (u-v-\eta) \sin (u+v+\eta)}{\sin (2 u+2 \eta) \sin (u-v+\eta) \sin (\eta-u-v)} \\
& \alpha_{6}=\frac{\sin (u-v-3 \eta) \sin (u+v+3 \eta) \sin (2 u-2 \eta)}{\sin (u-v+\eta) \sin (u+v-\eta) \sin (2 u+2 \eta)}
\end{aligned}
$$

we find the unique solution such that $\lambda, \kappa>0$ :

$$
\begin{aligned}
& \underline{p}_{3}= \\
& \kappa \frac{2 \sin (\xi-2 \eta) \sin (\xi) \sin (u+v+\xi-\eta) \sin (u+v+\xi+\eta)}{\sin (2 \eta) \sin (u-v-\eta)(\cos (2 u) \cos (u+v+\eta)-\cos (2 \eta) \cos (u-v-2 \xi+\eta))} \\
& \underline{p}_{4}= \frac{\cos ^{2}(2 u)-\cos (4 \eta)-\sin (2 u) \sin (2 v+2 \eta)}{\cos (2 \eta)-\cos (u+v+\eta) \cos (u+v+2 \xi-\eta)} \\
& \times \frac{\sin (2 u) \sin (u+v+3 \eta) \sin (u-v-\xi+\eta) \sin (u-v-\xi-\eta)(\cos (2 u) \cos (u+v+\eta)-\cos (2 \eta) \cos (u-v-2 \xi+\eta))}{\sin (\xi-2 \eta) \sin (\xi) \sin ^{2}(u+v+\xi-\eta)} \\
& \times \frac{\cos (2 \eta)-\cos (u+v+\eta) \cos (u+v+2 \xi-\eta)}{52}
\end{aligned}
$$

$$
\begin{align*}
\underline{p_{5}}= & \frac{2 \sin (2 u-2 \eta) \sin (u+v+\eta)}{\sin ^{2}(2 \eta)(\cos (2 u) \cos (u+v+\eta)-\cos (2 \eta) \cos (u-v-2 \xi+\eta))} \\
\underline{p_{6}}= & \frac{\sin ^{2}(\xi) \sin ^{2}(u+v+\xi+\eta)}{\cos (2 \eta)-\cos (u+v+\eta) \cos (u+v+2 \xi-\eta)} \\
& \frac{2 \sin (2 u-2 \eta) \sin (u-v-3 \eta) \sin (u+v+3 \eta) \sin ^{2}(\xi)}{\sin ^{2}(2 \eta) \sin (u-v-\eta)(\cos (2 u) \cos (u+v+\eta)-\cos (2 \eta) \cos (u-v-2 \xi+\eta))} \\
& \times \frac{\sin (u-v-\xi+\eta) \sin (u+v+\xi-\eta) \sin (u+v+\xi+\eta)}{\sin (u-v-\xi-\eta)(\cos (2 \eta)-\cos (u+v+\eta) \cos (u+v+2 \xi-\eta))} \\
\frac{\kappa}{\lambda}= & \frac{\sin (u-v-\xi-\eta) \sin (u-v-\xi+\eta)(\cos (2 \eta)-\cos (u+v+\eta) \cos (u+v+2 \xi-\eta))}{2 \sin (\xi-2 \eta) \sin (\xi)(\cos (2 \eta)-\cos (2 u) \cos (2 v+2 \xi))}
\end{align*}
$$

Using the parametrization $\kappa=\kappa_{20 \mathrm{~V}}[\zeta]$, we may interpret the last equation as determining $\lambda$ as a function $\lambda_{20 \mathrm{v}}[\xi]$ of the parameter $\xi$, where:

$$
\begin{align*}
\lambda_{20 \mathrm{~V}}[\xi]:= & \kappa_{20 \mathrm{v}}[\xi] \frac{2 \sin (\xi) \sin (\xi-2 \eta)}{\sin (u-v-\eta-\xi) \sin (u-v+\eta-\xi)} \\
& \times \frac{\cos (2 \eta)-\cos (u+v+\eta) \cos (u+v-\eta+2 \xi)}{\cos (2 \eta)-\cos (2 u) \cos (2 v+2 \xi)} \tag{5.15}
\end{align*}
$$

To summarize, we have found the most likely exit point $\kappa$ as an implicit function of the arbitrary parameter $\lambda$, via the parametric equations $(\kappa, \lambda)=\left(\kappa_{20 \mathrm{~V}}[\xi], \lambda_{20 \mathrm{~V}}[\xi]\right)$, which results in the family of tangent lines $F_{\xi}(x, y)=0$. The theorem follows from the expressions (2.20), by identifying the slope $A[\xi]=2 \kappa_{20 \mathrm{v}}[\xi] / \lambda_{20 \mathrm{~V}}[\xi]$, while the range of the parameter $\xi$ corresponds to imposing $A[\xi] \in[0, \infty)$.

As explained in section 2.2.2, the SE branch of the arctic curve is easily obtained by applying the transformation $(u, v) \mapsto\left(u^{*}, v^{*}\right)=(u,-v-\pi)$ and the change of coordinates $(x, y)>\rightarrow(x, 2-x-y)$.

Theorem 5.4. The SE branch of the arctic curve for the 20V-DWBC3 model is given by the parametric equations

$$
\begin{aligned}
x & =X_{\mathrm{SE}}^{20 \mathrm{~V}}[\xi]=X_{\mathrm{NE}}^{20 \mathrm{~V}}[\xi]^{*} \\
y & =Y_{\mathrm{SE}}^{2 \mathrm{~V}}[\xi]=2-X_{\mathrm{NE}}^{2 \mathrm{NV}}[\xi]^{*}-Y_{\mathrm{NE}}^{20 \mathrm{E}}[\xi]^{*} \quad(\xi \in[\eta+u+v, 0])
\end{aligned}
$$

with $X_{\mathrm{NE}}^{20 \mathrm{~V}}, Y_{\mathrm{NE}}^{20 \mathrm{~V}}$ as in theorem 5.3, and where the superscript $*$ stands for the transformation $(u, v)>\rightarrow\left(u^{*}, v^{*}\right)=(u,-v-\pi)$, which we have also applied to the range of $\xi$.

## 55. Examples

We now illustrate the results of theorems 5.3 and 5.4 in a few examples.
551. Case $u=0$. In this case the arctic curve is entirely made of its NE and SE portions, as it touches the W boundary at points $(1,1)$ and $(1,2)$, both with a tangent of slope $1 / 2$ (corresponding to $A=1 / 2$ ) for all values of $\eta, v$. We have represented in figure 17 (left) the


Figure 17. Left: arctic curve of the 20V-DWBC3 in the cases $u=0, v=-\frac{\pi}{2}$ and $\eta$ varying from $0+$ (outermost curve) to $\frac{\pi}{\pi}-$ (innermost curve). Right; arctic curve of the
$20 V-D W B C 3$ in the cases $u=0, \eta=\frac{\pi}{\pi}$ and $v$ varying between $-\frac{1}{\pi}-\quad$ (topmost NE curve) and $-\overline{\pi^{2}}$ (bottommost).
arctic curves for the self-dual value $v=-\frac{\pi}{2}$ and for $\eta$ ranging from $0^{+}$to $\frac{\pi}{2}$. The arctic curve for $\eta=0$ reads:

$$
\left(X_{\mathrm{NE}}[\xi], Y_{\mathrm{NE}}[\xi]\right)=\frac{2 \xi-\sin (2 \xi)}{\pi}, 1-2 \frac{\xi}{\pi} \quad \xi \in-\frac{\pi}{2}, 0
$$

The limit $\eta \rightarrow \frac{\pi}{2}$ - is singular, however we find a finite result by setting $\eta=\frac{\pi}{2}-\epsilon$ and $\xi=\epsilon \zeta$, and then sending $\epsilon \rightarrow 0$, with the result:

$$
\begin{aligned}
X_{\mathrm{NE}}= & \frac{(2+\zeta)^{2}\left(\cos (2 \pi \zeta)-1+2 \pi \zeta^{2}\left(\pi\left(1-\zeta^{2}\right) \cos (\pi \zeta)+2 \zeta \sin (\pi \zeta)\right)\right.}{4\left(1+\zeta+\zeta^{2}\right) \sin ^{2}(\pi \zeta)} \\
Y_{\mathrm{NE}}= & 1+\frac{1-\frac{\pi\left(1-\zeta^{2}\right)}{\zeta}-\frac{2 \sin (\pi \zeta)}{(2+\zeta)\left(2 \zeta^{2}+2 \zeta-1\right)\left(\cos (2 \pi \zeta)-1+2 \pi \zeta^{2}\left(\pi\left(1-\zeta^{2}\right) \cos (\pi \zeta)+2 \zeta \sin (\pi \zeta)\right)\right.}}{8\left(1+\zeta+\zeta^{2}\right) \sin ^{2}(\pi \zeta)} .
\end{aligned}
$$

In all these cases, the SE branch is given by $\left(X_{\mathrm{SE}}, Y_{\mathrm{SE}}\right)=\left(X_{\mathrm{NE}}, 2-X_{\mathrm{NE}}-Y_{\mathrm{NE}}\right)$ as $v=v^{*}$. We also represent non-selfdual cases in figure 17 (right), for $u=0, \eta=\frac{\pi}{6}$ and $v$ varying between $2^{-\frac{\pi}{6}} \frac{\pi}{\square}$ and $\overline{2}^{\underline{\pi}}$. We see that the tangency point on the vertical $x=0$ moves away from the self-dual point $(0,1)$, and that the curves are no longer nested as in the $v=-\frac{\pi}{2}$ case.

552 Uniform case. As is easily checked $\mathfrak{g n}$ the weights (2.15), the uniform case corresponds to $\eta=\frac{\pi}{8}=u, v=-\frac{\pi}{2}$ and $v=2$ (2.17). The NE and SE portions of the arctic curve predicted by theorems 5.3 and 5.4 have a vertical tangent at $(0,1)$, a horizontal tangent at $\sqrt{-}-3-3), 2 \quad(-0.845,2)$ and a diagonal tangent of slope -1 at $\frac{2}{3}(\sqrt{3}-3),{ }_{3}^{2}(3-\sqrt{ } 3) \quad(-0.845,0845)$. We have represented in figure 17 (left) the NE and SE portions of the arctic curve together with the rescaled quadrangular domain $\lim _{n \rightarrow \infty}$ Q $n$.

As pointed out before, the tangent method does not allow to predict the NW and SW portions of the arctic curve. It is interesting however to notice that the NE portion of the curve is algebraic. With a suitable shift of the origin to the point $(-2,1)$, namely substituting $(x, y) \rightarrow(x-2, y+1)$, we obtain the following algebraic equation:

$$
\begin{align*}
& 3^{6} x^{2}+y^{2}-\underline{2}^{5}-5^{33} 3^{3} x^{2}+y^{2}-\underline{2}_{3}^{3}-23^{2} 5^{4} x^{2}+y^{2}-\underline{2}_{3}^{2} \\
& \quad-2^{2} 5^{5}\left(x^{2}+y^{2}-4 x^{2} y^{2}\right)=0 \tag{5.16}
\end{align*}
$$

We have represented this algebraic curve in figure 18 (right) together with the NE portion of the uniform 20V-DWBC3 curve, and the scaled quadrangular domain (in black). We see that the SE portion of the arctic curve (dashed black curve) is obtained as the shear of the analytic continuation of the NE portion (red curve).
553. Free fermion case. In view of the connection to the $6 \mathrm{~V}^{\prime}$ model (with same values of $\eta, u, v)$ it is clear that $\eta=\frac{\pi}{4}$ plays the role of free fermion point. In particular, we expect the arctic curve to be analytic. As a highly non-trivial check, we have verified that at $\eta=$ 年 and for all allowed values of $u, v$ the SE branch is the analytic continuation of the NE branch. Like in the $6 \mathrm{~V}^{\prime}$ case, we also get access to the NW and SW branches via analytic continuation. We have represented in figure 19 a sequence of cases with $\eta=\frac{\pi}{4}, u=\frac{\pi}{16}$ and $v$ varying (1) from $-\frac{\pi}{2}$ to $-_{-2}^{\frac{\pi}{2}}+\frac{\frac{3 \pi}{16}}{16}$ (left) and (2) from ${ }_{-2}^{\frac{\pi}{2}}{ }_{-16}{ }^{\frac{3 \pi}{\text { to }}} z_{2}^{\frac{\pi}{( }}$ (right). We see that in the case (1) the curve is anchored at the point $(-1,2)$ while the other end along the vertical $x=-1$ varies along the W boundary. The reverse phenomenon is observed in the case (2), where the curve is anchored at the point $(-1,1)$ and its other end varies along the W boundary.
554. Generic case. We finally present in figure 20 a 'generic' case with no special symmetry: $\eta=\frac{\pi}{8}$, and $v=-\frac{\pi}{2}-\frac{\pi}{32} /=v^{*}=-\frac{\pi}{2}+\frac{\pi}{32}$, for $u$ varying from 0 to $\frac{11 \pi}{32}=\pi+v-\eta$. The last value is singular, and must be approached as $u=\frac{11 \pi}{32}-\epsilon, \xi=\epsilon^{1 / 2} \zeta$ with $\epsilon \rightarrow 0$. The result is a line segment joining the points $(-1,1)$ and $(0,2)$.

## 6. Aztec triangle domino tilings

## 61. Partition function and one-point functions

In reference [DF21], a correspondence was established between the 20V-DWBC3 model on $\mathrm{Q}^{n}$ and the domino tiling problem of the Aztec triangle 不. First it was shown that the models share the same uniformly weighted partition function (total number of configurations):

$$
Z_{n}^{20 \mathrm{~V}}=Z_{n}^{\mathrm{DT}}
$$

Next this correspondence was refined by considering the (uniformly weighted) 20V-DWBC3 refined partition functions $Z_{n, k}^{20 V}, k=1,2, \ldots, 2 n 1$, equal to the refined partition function of section 5.2.1 with the parameters (2.17). Their counterparts are the refined partition functions of


Figure 18. Left: arctic curve ( $\mathrm{NE}=$ red and $\mathrm{SE}=$ blue portions) of the uniform 20 V DWBG3 model on its rescaled domain (black), corresponding to $\eta=\pi, u=\pi$ and $\underline{2}$. Right: arctic curve of the uniform 20V-DWBC3 model (NE brañch in thícker blue line, SE branch in dashed black), together with the analytic continuation of its NE portion (in red). The arrow indicates the shear transformation from the latter to the SE branch.
the domino tiling problem $Z_{n, k}^{\mathrm{DT}}$ defined in a similar manner, using the non-intersecting Schröder path formulation of section 2.1.4, as the number of configurations in which the topmost path is conditioned to first enter the last vertical at position $k=0,1, \ldots, n-1$, before ending with $k$ vertical steps (see the pink domain in figure 9 (bottom right) for an illustration). In reference [DF21], it was shown that

$$
\begin{equation*}
Z_{n, k}^{\mathrm{DT}}=Z_{n, n+k+1}^{20 \mathrm{~V}}+Z_{n, n+k}^{20 \mathrm{~V}} \tag{6.1}
\end{equation*}
$$

This implies the following relation between the corresponding refined one-point functions $H_{n, k}^{20 \mathrm{~V}}=Z_{n, k}^{20 \mathrm{~V}} / Z_{n}^{20 \mathrm{~V}}$ and $H_{n, k}^{\mathrm{DT}}=Z_{n, k}^{\mathrm{DT}} / Z_{n}^{\mathrm{DT}}:$

$$
\begin{equation*}
H_{n, k}^{\mathrm{DT}}=H_{n, n+k+1}^{20 \mathrm{~V}}+H_{n, n+k}^{20 \mathrm{~V}} . \tag{6.2}
\end{equation*}
$$

## 62 Arctic curves

621. Asymptotics of the one-point function. As usual, we explore the asymptotics of the refined one-point function $H_{n, k}^{\mathrm{DT}}$ for the domino tiling model in the scaling limit of large $n=N$ and $\kappa=k / N$ finite. The relation (6.2) allows immediately to express:


Figure 19. Left: arctic curve of the free fermion 20V-DWBC3 model for $\eta=\frac{\pi}{4}, u=\frac{\pi}{16}$ and $v$ varying from $-\frac{\pi}{2}$ (topmost) to $-\frac{\pi}{2}+3 \frac{\pi}{16}$ (bottommost). Right: same, but with ${ }^{16}$ varying from $-\pi_{2}-3 \pi_{16}$ (topmost) to $-{ }^{\pi}$ ( bottommost).

Theorem 6.1. The large $n=N$ asymptotics of the refined one-point function $H_{n, k}^{\mathrm{DT}}$ for the domino tiling model reads:

$$
\begin{equation*}
H_{N, \kappa N}^{\mathrm{DT}}=2 H_{N, 2 \kappa^{\prime} N}^{20 \mathrm{~V}}, \quad \kappa^{\prime}=\frac{1+\kappa}{2} \tag{6.3}
\end{equation*}
$$

and

$$
H_{N, K N}^{\mathrm{DT}} \quad-\frac{\mathrm{d} t}{2 \mathrm{i} \pi t} \mathrm{e}^{-N S_{0}^{\mathrm{DT}}(\kappa, t)}
$$

$$
S^{\mathrm{PT}}(\kappa, t)=S_{0}^{20 \mathrm{~V}} \frac{1+\kappa}{2}, t=\phi^{20 \mathrm{~V}}[u, v ; \xi]+(1+\kappa) \log (t)
$$

where the contour of integration of the variable t circles the origin, and the variable $\xi$ depends implicitly on $t$ via $t=t_{20 \mathrm{~V}}[\xi]$ (5.7).

Similarly to the $6 \mathrm{~V}^{\prime}$ and 20 V cases, the saddle-point equation in the variable $\xi$ reads $\partial_{\xi} S_{0}^{\mathrm{DT}}\left(\kappa, t_{20 \mathrm{~V}}[\xi]\right)=0$, with the solution:

$$
\begin{equation*}
\kappa=\kappa_{\mathrm{DT}}[\xi]:=2 \kappa_{20 \mathrm{~V}}[\xi]-1 \quad \xi \in-\frac{\pi}{4}, 0! \tag{6.4}
\end{equation*}
$$

with $\kappa_{20 \mathrm{~V}}[\xi]$ as in (5.10), and where the range of $\xi$ ensures that $\kappa_{20 \mathrm{v}} \in[1,2]$ hence $\kappa_{\mathrm{DT}} \in[0,1]$.


Figure 20. Left: arctic curve of the 20V-DWBC3 model for $\eta=\frac{\pi}{8}, v=-\frac{\pi}{2}-\frac{\pi}{32}$ and $u$ varying from 0 (innermost) to $\frac{3 \pi}{}$. Right: same, but with $u$
to $\frac{11 \pi}{32}$ (segment).

622 Asymptotics of path partition function. By definition, and comparing figure 9 top right and bottom right (light blue domains), we have in the uniform case: $Y_{k, l}^{\mathrm{DI}}=Y_{k, l}^{20}$. We deduce the asymptotics

$$
Y_{\kappa N, \lambda N}^{\mathrm{DT}} \quad \int_{1}{\left.\mathrm{~d} p 3_{3} \mathrm{e}^{-N S_{1}^{\mathrm{DT}}\left(\kappa, p_{3}\right)}, \quad S_{1}^{\mathrm{DT}}\left(\kappa, p_{3}\right)=S_{1}^{20 \mathrm{~V}}\left(\kappa, p_{3}\right)\right) ~}_{0}
$$

with $S_{1}^{20 V}$ the uniform weight version of (5.12):

$$
\begin{aligned}
S^{20 \mathrm{~V}}\left(\kappa, p_{3}\right)= & -\left(\kappa+\lambda-p_{3}\right) \log \left(\kappa+\lambda-p_{3}\right)+\left(\kappa-p_{3}\right) \log \left(\kappa-p_{3}\right) \\
& +\left(\lambda-p_{3}\right) \log \left(\lambda-p_{3}\right)+p_{3} \log \left(p_{3}\right) .
\end{aligned}
$$

623. Arctic curves via the tangent method. Strictly speaking, the tangent method only predicts the NE portion of the arctic curve. However, the domino tiling problem is of the 'free fermion' class, as it involves only non-intersecting lattice paths (or alternatively the dual is just a dimer model, for which the general results of [KOS06] apply). As such, it has an analytic


Figure 21. Left: arctic curve of the uniformly weighted domino tiling problem of the Aztec triangle, tangent to the NW, N and E boundaries. Right: comparison with the arctic curve of the $20 \mathrm{~V}-\mathrm{DWBC} 3$ model: the blue portion is the common NE branch of the two curves, represented with their respective rescaled domains.
arctic curve, hence we may safely use the analytic continuation of the NE portion predicted by the tangent method.

Theorem 6.2. The arctic curve for the uniform domino tilings of the Aztec triangle, as predicted via the tangent method, reads

$$
x=X^{\mathrm{DT}}[\xi]=\frac{B^{\prime}[\xi]}{\frac{A^{\prime}[\xi]}{A^{\prime}[\xi]}} \quad y=Y^{\mathrm{DT}}[\xi]=B[\xi]-\frac{A[\xi]}{B^{\prime}[\xi]} \quad \xi \in-\frac{3 \pi}{8}, 0,
$$

where

$$
B[\xi]:=\kappa_{\mathrm{DT}}[\xi] \quad \text { and } \quad A[\xi]:=-\cot (2 \xi)
$$

with $\kappa_{\mathrm{DT}}[\xi]$ as in (6.4).

Proof. The rescaled tangent lines are now through the points $(0, \kappa)$ and $(\lambda, 0)$, governed by the equation $y+A x-B=0$ with $A=\kappa / \lambda, B=\kappa$. We have already determined the most likely exit point $\kappa=\kappa_{\text {DT }}[\xi]$ (6.4), leading to $B[\xi]=\kappa_{D T}[\xi]$. To determine $A[\xi]$ we solve the saddle-point equations $\partial_{4 S} \mathrm{DTM}^{\mathrm{DT}}\left(\kappa, t, p_{3}\right)=\partial_{p_{3}} S^{\mathrm{DT}}\left(\kappa, t, p_{3}\right)=0$, in terms of the total action $S^{D T}\left(\kappa, t, p_{3}\right):=S_{0}^{D T}(\kappa, t)+S_{1}^{\text {ST }}\left(\kappa, p_{3}\right)$. These read

$$
t=\frac{\kappa-p_{3}}{\kappa+\lambda-p_{3}}, \quad \frac{p_{3}\left(\kappa+\lambda-p_{3}\right)}{\left(\kappa-p_{3}\right)\left(\lambda-p_{3}\right)}=1
$$

and are easily solved into


The range of parameter $\xi$ for the NE portion of arctic curve is $\xi \in\left[-\pi_{-}, 0\right]$, ensuring that $K_{\mathrm{DT}}[\xi] \in[0,1]$, however as noted above we may extend the range to covertthe entire domain, which corresponds to $K_{D T}[\xi] \in[0,2]$, namely $\xi \in\left[-\frac{3 \pi}{8}, 0\right]$, and the theorem follows.


Figure 22. Left: the arctic curve of the uniform 6V-DWBC/ASM model (red and dashed black curves inside the square) and the analytic continuation of the NE branch (blue ellipse inscribed in a hexagon); the arrow indicates the shear mapping the latter to the SE branch (dashed black curve). Right: the arctic curve for TSSCPP (blue curve inside the pink triangular domain), and that for the lozenge tiling of the regular hexagon obtained by multiple reflections (red circle).

We illustrate the result of theorem 6.2 in figure 21 (left). Note that the curve has a vertical tangent at the origin, and a horizontal tangent at the point $\frac{2}{3}(3-3), 1$, while it ends tangencially on the diagonal NW boundary at the point $\quad 2_{3}^{\frac{\sqrt{2}}{2}}-2,2 \frac{\sqrt{2}}{3}$.

We note that the curve of theorem 6.2 is a portion of an algebraic curve. In fact, changing the origin to $(\ldots 2,0)$ by applying the substitution $(x, y) \rightarrow(x-2, y)$, we find that this curve is given by the same equation (5.16) as in the uniform 20V-DWBC3 case. This is illustrated in figure 21 (right) where we have represented both rescaled domains, and their common NE branch of the arctic curve (in blue).

## 7. Conclusion

In this paper, we have presented the tangent method derivation of arctic curves for the disordered phase of the 6 V -DWBC, $6 \mathrm{~V}^{\prime}, 20 \mathrm{~V}$-DWBC 3 models, as well as for the domino tilings of the Aztec triangle. The main ingredient used is the large size asymptotics of refined onepoint functions, which we derived from the form of the thermodynamic free energy of the $6 \mathrm{~V}^{\prime}$ model in the disordered phase (theorem 4.9), and then deducing all relevant asymptotics from there. Our method however only predicts the NE and SE branches of the relevant arctic curves. It would be desirable to find the remaining NW and SW branches of the arctic curves when applicable.

Another question regards the other possible phases of the 6V-U model: unfortunately the thermodynamic free energy is known only for the disordered phases (see [RK15]), and this problem should be addressed first.

The results for the $6 \mathrm{~V}^{\prime}$ and 20V-DWBC3 models of the present paper complement earlier results on the 6V-DWBC [CS16, DFL18] and 20V-DWBC1, 2 models [DFG20], which display non-analytic arctic curves as well. The key to the non-analyticity can be traced back to the symmetries of the systems, allowing for determining their SE branch in terms of the NE branch of another system obtained by applying an involution ${ }_{\star}$ to its weights together with a geometric transformation of the plane involving a reflection and possibly a shear. Note also that our results


Figure 23. The expected arctic curve of the uniformly weighted domino tiling problem of Ciucu's cruciform region (in red), is obtained as the multiple reflection of the arctic curve of the Aztec triangle (in blue). The resulting clover-shaped curve is the analytic continuation to the whole plane of the blue portion.
for the $6 \mathrm{~V}^{\prime}$ model also apply to the more general case of U-turn boundary 6 V model, which is expected to share the same arctic curves.

Finally, let us compare the situation of the 20V-DWBC3 model to that of ASMs, with the known enumeration formula:

$$
\mathrm{ASM}=\frac{\left(n^{2} j+1\right)!}{j=0}{ }^{n} \quad,(n+j)!
$$

a formula strikingly reminiscent of (4.23). The analogy goes further: we have found that the NE/SE portion of arctic curve for large uniform 20V-DWBC3 configurations is piecewise algebraic, the SE portion being equal to a shear transformation of the analytic continuation of the NE portion (see figure 18 right). The same holds for ASMs, whose NE/SE portion of arctic curve is piecewise elliptic, the SE portion being obtained by a shear transformation of the ellipse containing the NE portion (see figure 22 left). The algebraic curve (5.16) clearly plays a role similar to this ellipse.

Finally, recall that ASMs of size $n$ are also in same number as TSSCPP [MRR86], which can be viewed as rhombus tilings of a regular hexagon with edges of length $2 n$, which satisfy all the symmetries of the hexagon. The triangular fundamental domain under these symmetries occupies $\frac{1}{1}$ th of the hexagon, which is recovered by successive reflections (see figure 22 right for an illustration). As such, the arctic curve for TSSCPP was argued in [DFR12] to be identical to that of the full hexagon without any symmetry constraint, i.e. the inscribed circle in the uniform case. There is a clear analogy between TSSCPP and the domino tilings of the Aztec triangle, in which the algebraic curve (5.16) plays the role of this circle.

Recently Ciucu [Ciu21] noticed a relation between the number of domino tilings of the Aztec triangle $T_{2}$ and that of a cruciform domain $C_{2 n-1,2 n-n-1}^{n-1}$, obtained by 'symmetrization', namely a succession of 'reflections' of the original Aztec triangle. We believe that the curve (5.16), which is the analytic continuation of the arctic curve for the triangle, is in fact the complete arctic curve for the rescaled large $n$ cruciform domain. As visual evidence, we have displayed both curves in figure 23, together with the original asymptotic Aztec triangle (shaded in pink) and its 7 reflected copies. Figure 23 suggests that, similarly to the TSSCPP case, the Aztec triangle could be the fundamental domain for symmetric tilings of a crosslike shaped domain probably similar to that considered by Ciucu.

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## Data availability statement

All data that support the findings of this study are included within the article (and any supplementary files).

## ORCID iDs

Philippe Di Francesco © https://orcid.org/0000-0003-0336-4814

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[^0]:    ${ }^{1}$ Both points $K$ and $L$ scale linearly with the size $n$ so that a thermodynamic limit can be reached.

[^1]:    ${ }^{2}$ We restrict throughout the paper to the disordered regime, in which all weights are trigonometric.

[^2]:    ${ }^{3}$ This choice simplifies the model by fixing the orientations of all arrows along the W boundary. However, we argue that the thermodynamics of the model are insensitive to that choice. For instance, the thermodynamic free energy, a bulk quantity, is independent of the choice of $\vartheta$ (see remark 4.2 below). So is the one-point function (see remark 4.12 below). As a consequence, the arctic curves of the U -turn 6 V and of the $6 \mathrm{~V}^{\prime}$ models are expected to be identical.

[^3]:    ${ }^{4}$ Here and in the following the superscript * indicates that the corresponding quantity is obtained by changing $u \rightarrow u^{*}$ (6V-DWBC) or $(u, v) \rightarrow\left(u^{*}, v^{*}\right)\left(6 V^{\prime}\right)$.

[^4]:    ${ }^{5}$ Here we choose not to attach any weight to the end vertex at height $k$, as it will be part of the partition function of the single path treated in next section.

