

### ON THE EXISTENCE OF WEAK SOLUTION OF THE KINETIC FOKKER-PLANCK EQUATION IN A BOUNDED DOMAIN WITH ABSORBING BOUNDARY

Étienne Bernard

### ▶ To cite this version:

Étienne Bernard. ON THE EXISTENCE OF WEAK SOLUTION OF THE KINETIC FOKKER-PLANCK EQUATION IN A BOUNDED DOMAIN WITH ABSORBING BOUNDARY. 2023. hal-04197938v1

### HAL Id: hal-04197938 https://hal.science/hal-04197938v1

Preprint submitted on 6 Sep 2023 (v1), last revised 3 Nov 2023 (v2)

**HAL** is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

# ON THE EXISTENCE OF WEAK SOLUTION OF THE KINETIC FOKKER-PLANCK EQUATION IN A BOUNDED DOMAIN WITH ABSORBING BOUNDARY

#### ÉTIENNE BERNARD

September 6, 2023

### Introduction

In the present paper, we discuss the existence and unicity of weak solutions of the kinetic Fokker-Planck equation in a bounded domain with absorbing boundary. More precisely, let an integer  $d \geq 2$  and let  $\Omega$  be a bounded, open and smooth subset of  $\mathbb{R}^d$ . As its boundary is smooth, we can define for any  $q \in \partial \Omega$  the outer normal vector  $n_q$ . Thus, we can decompose  $\partial \Omega = \Gamma^+ \cup \Gamma^- \cup \Gamma^0$  with:

$$\Gamma^{+} = \{(q, p) \in \partial\Omega \times \mathbb{R}^{d} | p \cdot n_{q} > 0 \},$$
  

$$\Gamma^{-} = \{(q, p) \in \partial\Omega \times \mathbb{R}^{d} | p \cdot n_{q} < 0 \},$$
  

$$\Gamma^{0} = \{(q, p) \in \partial\Omega \times \mathbb{R}^{d} | p \cdot n_{q} = 0 \}.$$

Let  $\sigma \in \mathbb{R}_+^*$ ,  $\gamma \in \mathbb{R}$  and  $F \in C^{\infty}(\mathbb{R}^d, \mathbb{R}^d)$ , we introduce the operator:

(1) 
$$\mathcal{L} = -p \cdot \nabla_q - F(q) \cdot \nabla_p + \gamma \nabla_p \cdot (p \cdot) + \frac{\sigma^2}{2} \Delta_p,$$

and its formal adjoint in  $L^2(dx)$ 

(2) 
$$\mathcal{L}^* = p \cdot \nabla_q + F(q) \cdot \nabla_p - \gamma p \cdot \nabla_p + \frac{\sigma^2}{2} \Delta_p.$$

Following [8, 9], we denote  $D := \Omega \times \mathbb{R}^d$ ,  $\overline{D} = \overline{\Omega} \times \mathbb{R}^d$  and  $\partial D := \partial \Omega \times \mathbb{R}^d$ . The variable  $x \in D$  represents the couple  $(q, p) \in D$  and dx = dqdp. We will use preferably this notation except when the two variables q and p do not have symmetrical roles, such as the beginning of subsection 2.1.

The so-called kinetic Fokker-Planck equation is the following initial-boundary problem  $f \equiv f(t, x)$ :

(3) 
$$\begin{cases} \partial_t f &= \mathcal{L}f \text{ on } (0,T) \times D, \ T > 0, \\ f(t,x) &= 0 \text{ on } (0,T) \times \Gamma^-, \\ f(0,x) &= f^{in}(x) \text{ on } D. \end{cases}$$

It models the collective behavior of particles evolving inside  $\Omega$  with velocity in  $\mathbb{R}^d$ , with initial distribution  $f^{in}$ , submitted to an exterior force F with a thermal bath encoded by the term of diffusion in velocity  $\frac{\sigma^2}{2}\Delta_p$  and the friction term  $\gamma\nabla_p\cdot(p\cdot)$ . More precisely, the quantity  $f(x)\mathrm{d}x\equiv f(t,q,p)\mathrm{d}t\mathrm{d}q\mathrm{d}q$  represents the number of particles at time interval  $[t,t+\mathrm{d}t]$ , in the volume  $B(q,\mathrm{d}q)\subset\Omega$  and with velocities in  $B(p,\mathrm{d}p)\subset\mathbb{R}^d$ . The homogeneous boundary condition f(t,x)=0 on  $(0,T)\times\Gamma^-$  means that whenever a particle coming from the interior of  $\Omega$  hits the boundary, it exits and disappears forever.

In the case of  $\Omega = \mathbb{R}^d$ , the theory of the kinetic Fokker-Planck equation is well-established. The bounded case is another matter because of the trace issue in kinetic theory. For more details, we refer to the enlightening discussion in Stéphane Mischler's "habilitation à diriger les recherches" p. 29-32. Let us just recall here that a possible strategy is to bypass the trace issue by define a weaker notion of solution with a

smaller space of test functions canceling on the problematic part of the boundary. This strategy is followed in [5] that we recall now in more detail:

Let T>0, define the cylinder domain  $Q_T:=[0,T]\times\overline{D}$  and the following space of test functions:

$$\mathcal{D}_{Q_T} := \left\{ \phi \in C_c^{\infty}(Q_T) \mid \phi(t, x) = 0 \text{ whenever } x \in \Gamma^+ \cup \Gamma^0 \right\}$$

We recall that  $C_c^{\infty}(Q_T)$  denotes the space of smooth functions with compact support in  $Q_T$ . In [5], it is denoted by  $C_0^{\infty}(Q_T)$  without being explicitly defined but the context implies the compact support in velocity. Indee, the definition of a weak solution in [5] (see below) implicitly requires that  $(\partial_t \phi + \mathcal{L}^* \phi)$  belongs to  $L^{\infty}(Q_T)$  whereas a smooth function "vanishing at infinity" may not have its derivative essentially bounded.

In [5] a function  $f \in L^{\infty}([0,T];L^1(D))$  is called a weak solution of (3) if it verifies [5, formula (1.7)]:

$$\int_{D} f(\partial_{t}\phi + \mathcal{L}^{*}\phi) dt dx + \int_{D} f^{in}(x)\phi(0,x) dx = 0, \ \forall \phi \in \mathcal{D}_{Q_{T}}.$$

It is easy to check that a classical solution of (3) would be also such a weak solution. However, we emphasize that, as the space of test functions is smaller, the notion of weak solution is therefore weaker that the usual. In [5], it is claimed to have established the existence of a weak solution provided that  $f^{in}$  satisfies a few conditions [5, Theorem 1.1]. But the proof of a crucial lemma [5, Lemma 2.3] has a gap which turns out difficult to fill (see the discussion in Appendix A in the first version of [2]). Carrillo's paper is sometimes cited decisively for other results such as [10] where the authors extend Carrillo's theory to the case of reflexive boundary with a test function space calibrated to bypass the trace issue in the same spirite as Carrillo's approach. To the best of my knowledge, I am not aware of any work that rigorously proves the existence and a fortiori the uniqueness of a weak solution. Meanwhile, in a series of articles, [8, 9], the existence of classical solutions with several interesting properties to the initial-boundary problem associated to  $\mathcal{L}^*$  is established with probabilistic tools. The aim of the present paper is to deduce by duality a theory of weak solution from these articles.

We first recall that a real valued function f defined on a local compact space E vanishing "at infinity" is defined by

$$\forall \varepsilon > 0, \exists \text{ compact } K_{\varepsilon} \subset E : \sup_{x \in K_{\varepsilon}^{c}} |f(x)| \leq \varepsilon.$$

We denote by  $C_0^{\infty}(E)$  the set of smooth functions vanishing at infinity on E.

We introduce the following space:

$$\mathcal{D}_{\tilde{Q}_T} := \big\{ \phi \in C_0^\infty \big( \tilde{Q}_T \big) \, \big| \phi \in L^1(D; L^\infty((0,T))) \text{ and } (\partial_t + \mathcal{L}^*) \phi \in L^\infty(Q_T) \, \big\},$$

with

$$\tilde{Q}_T := [0, T[ \times (\overline{\Omega} \setminus (\Gamma^+ \cup \Gamma^0)) \times \mathbb{R}^d.$$

Notice that by extension by continuity, we have  $\phi \in C^b([0,T] \times \overline{D})$  with  $\phi(T,\cdot) = 0$  and  $\phi = 0$  on  $\Gamma^+ \cup \Gamma^0$  for any  $\phi \in \mathcal{D}_{\tilde{Q}_T}$  wich implies  $\mathcal{D}_{Q_T} \subset \mathcal{D}_{\tilde{Q}_T}$ . We now give a new definition of weak solution.

**Definition 1.** A function  $f \in L^{\infty}([0,T];L^1(D))$  is said to be a weak solution of (3) with initial condition  $f^{in}$  if it satisfies

$$\int_{D} f(\partial_{t} \phi + \mathcal{L}^{*} \phi) dt dx + \int_{D} f^{in}(x) \phi(0, x) dx = 0, \ \forall \phi \in \mathcal{D}_{\tilde{Q}_{T}}.$$

We can now state the first main result:

**Theorem 2** (Existence and uniqueness). For any  $f^{in} \in L^1(D)$ , there exists a unique weak solution  $f \in L^{\infty}([0,T];L^1(D))$  of (3) with initial condition  $f^{in}$  in the sense of Definition 1.

The existence and the uniqueness of the weak solution together with the properties derived in [8, 9] implies the existence of a strongly continuous semigroup with nice properties:

**Theorem 3.** Let  $f^{in} \in L^1(D)$ , then:

- (1) (Semigroup property) There exists a positive, irreducible and immediately compact  $C_0$  semigroup  $(P_t)_{t\geq 0}$  such that for any  $f^{in} \in L^1(D)$ ,  $t \mapsto P_t f^{in}$  is the unique weak solution of (3) with initial condition  $f^{in}$  in the sense of Definition 1.
- (2) (Regularity) For any t > 0, we have  $P_t f^{in} \in C^{\infty}(D) \cap C^b(\overline{D})$
- (3) (Balanced exponential growth), let denotes the spectral bound of the operator  $\mathcal{L}$

$$s(\mathcal{L}) := \sup \{ Re\lambda \, | \lambda \in \sigma(\mathcal{L}) \}$$

then  $s(\mathcal{L}) \in \sigma(\mathcal{L})$  with  $s(\mathcal{L}) < 0$  and up to a multiplicative constant, there exists unique nonnegative functions  $\varphi$  and  $\psi \in C^b(\overline{D}) \cap L^1(D)$  such that

$$\mathcal{L}\varphi = s(\mathcal{L})\varphi, \ \mathcal{L}^*\psi = s(\mathcal{L})\psi.$$

Moreover, normalizing  $\psi$  such that  $\int_D \psi \varphi = 1$ , we have

$$\lim_{t \to +\infty} \left\| \left| e^{-s(\mathcal{L})t} P_t - \varphi \otimes \psi \right| \right\|_{L^1(D)} = 0,$$

where

$$\forall f \in L^1(D) \ (\varphi \otimes \psi)(f) = \left(\int_D \psi f\right) \varphi,$$

and  $\|\cdot\|_{L^1(D)}$  denotes the norm operator in  $L^1(D)$ .

As  $f(t,\cdot) \in C^b(\overline{D})$ , we can define  $\gamma f \in C^b(\partial D)$  and  $\gamma_{\pm} f := \gamma f_{|\pm(p \cdot n_q) > 0}$  but we have more:

**Theorem 4** (Trace). Let  $\gamma f$  the trace of f defined as above, then  $\gamma f \in L^1(\partial\Omega \times \mathbb{R}^d; |p \cdot n_q| d\sigma_{\partial\Omega} dp)$  where  $d\sigma_{\partial\Omega}$  denotes the Lebesgue measure on  $\partial\Omega$ . And for any t > 0 and for any  $\phi \in C^{\infty}(D) \cap C(\overline{D})$  we have

$$\int_{D} (\mathcal{L}f)\phi = \int_{D} f\mathcal{L}^*\phi + \int_{\partial D} \gamma f\phi (n_q \cdot p) \mathrm{d}p \mathrm{d}\sigma_{\partial\Omega}.$$

**Remark 1.** The results on the existence and integrability of the traces are all the more remarkable that in general it is not true in mathematical kinetic theory that even for  $f \in L^1$  such that  $q \cdot \nabla_p f \in L^1$ :

$$\gamma f \in L^1(\Omega \times \mathcal{V}; |n_a \cdot p| \mathrm{d}p \mathrm{d}q)$$

see for instance [3] for a counter-example.

As the proofs of Theorem 2 and Theorem 3 rely heavily upon [8, 9] and upon the theory of Banach lattice, for sake of completeness, we will first recall the mots importants points of [8, 9] and of the theory of Banach lattice In Section 1. Then, we will establish Theorem 2 and Theorem 3 in Section 2. After that, the proof of will be given in Section 3.

## 1. Of Banach lattices and probabilistic investigations of the kinetic Fokker-Planck equation

First, we recall the main elements of the theory of Banach lattice and a few of useful theorems around positive operators and semigroups of operators in a Banach lattice. Then, we recall and synthesize the main results of [8, 9].

1.1. Banach lattices. First, we underline that  $L^1(D)$  is a ordered set with the partial order defined by

$$0 \le f$$
 if and only if  $0 \le f(x)$  a.e. on D.

This ordered space is a Banach lattice, meaning that the ordering is compatible with the vector structure and is such that

$$\forall f, g \in L^1(D), \text{ if } |g| \le |f|, \text{ then } ||g||_{L^1(D)} \le ||g||_{L^1(D)}.$$

A semigroup  $S \equiv (S_t)_{t>0}$  is said to be positive if it preserves positivity, i.e.

$$f \geq 0 \Rightarrow S_t f \geq 0$$
, for each  $t \geq 0$ .

A closed subspace I of  $L^1(D)$  is said to be an (order) ideal if

$$\forall (f,g) \in L^1(D) \times I, |f| \leq |g| \Rightarrow f \in I.$$

The null subspace  $\{0\}$  and  $L^1(D)$  are ideals. A semigroup  $\mathcal{S}$  is said to be irreducible if and only if the only ideals that are invariant for  $\mathcal{S}$  are  $\{0\}$  and  $L^1(D)$ . That is equivalent to the following property (for instance [12, Proposition III.8.3 p.186]):

$$\forall 0 \le f \in L^1(D), 0 \le g \in L^{\infty}(D) \text{ with } f \ne 0, g \ne 0, \exists t > 0 : \int_D g S_t f > 0.$$

In others words, an irreducible semigroup spreads the support of any nonnegative function through the entire space. A nonnegative function  $f \in L^1(D)$  is a quasi-interior point if it is a.e. strictly positive on D. In  $L^{\infty}(D)$  that is also a Banach lattice, a non negative function g is a quasi-interior point if there exists  $\delta > 0$  such that  $\delta \mathbb{1}_D \leq g$  a.e. The ground bound of a  $C_0$ -semigroup S is

$$\omega_0(\mathcal{S}) := \inf_{\omega \in \mathbb{R}} \left\{ \exists M \ge 0 : ||S_t|| \le M e^{\omega t} \right\}$$

It is known [1, Proposition 12.1 p. 181] that

$$\omega_0(\mathcal{S}) = \lim_{t \to \infty} \frac{\log ||S_t||}{t} = \inf_{t \ge 0} \frac{\log ||S_t||}{t},$$

and that for any t > 0, the spectral radius of  $S_t$  is equal to:

$$(4) r(S_t) = e^{t\omega_0(S)}.$$

and let A an unbounded operator, we recall its spectral bound is

$$s(A) := \sup \{ \operatorname{Re} \mu \mid \mu \in \sigma(A) \}$$

where  $\sigma(A)$  is the spectrum of A. If  $\mathcal{S}$  is a positive  $C_0$ -semigroup on  $L^1(D)$  then its growth bound coincides with the spectral bound of its generator (see for instance [1, Theorem 12.17 p.193]).

**Lemma 5.** Let A be a positive, compact and irreducible operator on  $L^1(D)$ 

(1) then r(A) > 0 and there exists  $u \in L^1(D)$  and  $v \in L^{\infty}(D)$  strictly positive a.e., unique up to a multiplicative constant such that

$$\begin{cases} Au &= r(A)u, \\ A'v &= r(A)v. \end{cases}$$

(2) Besides, let  $\lambda > 0$  such there exists nonnegative  $\in L^1(D)$  with  $Aw = \mu w$  then  $\lambda = r(A)$  and w = u up to a multiplicative constant.

*Proof.* The first point is classical in Banach lattice theory and is known as De Pagter's theorem [6]. The second point is almost immediate, but despite my best efforts, I have not found citable results in the literature. For the sake of completeness, I provide the evidence. As w is nonnegative and v strictly positive a.e., we have  $\int_{\Omega \times \mathbb{R}^d} vw > 0$  Keeping that in mind,  $Aw = \mu w$  implies

$$\int_{D} Awv = \mu \int wv$$

thus, as  $\int_D vw > 0$  is strictly positive

$$r(A) = \mu,$$

and the equality of w with u is a direct consequence of the uniqueness of the eigenvector associated to r(A).

The theory of the balanced growth is very rich. The following proposition is a special case, it is a synthesis of Propositions 2.3 and 2.4 and 2.5 and Remark 2.2 in [13]) and for the precise form of P, see Proposition III.8.5 p. 189 in [12].

**Lemma 6.** Let  $(S_t)_{t\geq 0}$  a irreducible, positive and compact semigroup on a Banach lattice E, then there exists a positive projection of rank one,  $P=x_0\otimes x_0^{'}$  where  $x_0$  is, up to a constant, the eigenvalue associated to s(A) and  $x_0^{'}\in E^{'}$  such that  $x_0^{'}(x_0)=1$ , and constants  $\delta>0$  and  $M\geq 1$  such that

$$\left\| \left\| e^{-ts(A)} S_t - P \right\| \right\|_{L^1(D)} \le M e^{-\delta t}.$$

1.2. A brief recalling of the results of Tony Lelièvre and alii. We recall here the theory developed by Tony Lelièvre, Mouad Ramil, and Julien Reygnier in a probabilistic framework for the kinetic Fokker-Planck in a bounded domain with absorbing [8, 9]. From here, we use there notations except the ones of the operators  $\mathcal{L}$  and  $\mathcal{L}^*$ . Indeed, in [8, 9],  $\mathcal{L}$  (respectively,  $\mathcal{L}^*$ ) corresponds to  $\mathcal{L}^*$  (respectively  $\mathcal{L}$ ) in the present paper, because the operator  $\mathcal{L}^*$  defined in (2).

Let  $(X_t^x = (q_t^x, p_t^x))_{t \ge 0}$  the Langevin process starting at  $x \in D$  at t = 0 defined by the following SDE:

$$\begin{cases} dq_t^x &= p_t^x dt, \\ dp_t^x &= F(q_t^x) dt - \gamma p_t^x dt + \sigma dB_t, \\ (q_0^x, p_0^x) &= x, \end{cases}$$

where  $(B_t)_{t\geq 0}$  is a d-dimensional Brownian motion. Define also the first exit time from D of the process  $(X_t^x)_{t\geq 0}$ :

$$\tau_{\partial}^x := \inf \{ t > 0 : X_t^x \notin D \}.$$

We denote the following unbounded operator:

$$\mathcal{L}_{\gamma}^* \equiv p \cdot \nabla_q + F(q) \cdot \nabla_p - \gamma p \cdot \nabla_p + \frac{\sigma^2}{2} \Delta_p.$$

It is the operator defined in (2) with the subscript  $\gamma$  in order to emphasize its dependence on the parameter  $\gamma$ . It is the infinitesimal generator of the Langevin process whereas (3) describes the evolution of Langevin process absorbed at  $\partial D$ . That explains why in a probabilistic framework such as in [8, 9], the initial problem with  $\mathcal{L}_{\gamma}^*$  is most often studied while in mathematical physics, it is (3) that arouses the most interest.

That being said, the first main result [8, Theorem 2.10] is then

**Theorem 7.** Let  $\gamma \in \mathbb{R}$  and let  $f \in C^b(D \cup \Gamma^-)$  and define

$$u_{\gamma}:(t,x)\mapsto \mathbb{E}\Big[\mathbb{1}_{\tau_{\partial}^x>t}f(X_t^x)\Big]$$

then

(1) (Initial and boundary values) the function u satisfies:

$$u_{\gamma}(0,x) = \begin{cases} f(x) & \text{if } x \in D \cup \Gamma^{-}, \\ 0 & \text{if } x \in \Gamma^{+} \cup \Gamma^{0}, \end{cases}$$

and

$$\forall t > 0, \forall x \in \Gamma^+ \cup \Gamma^0, u(t, x) = 0.$$

(2) (Continuity) we have:

$$u_{\gamma} \in C^b((\mathbb{R}_+ \times \overline{D}) \setminus (\{0\} \times (\Gamma^- \cup \Gamma^0)))$$

(3) (Interior regularity)  $u \in C^{\infty}(\mathbb{R}_{+}^{*})$  and, for all t > 0,  $x \in D$ 

$$\partial_t u_{\gamma} = \mathcal{L}_{\gamma}^* u_{\gamma}$$

Moreover,  $f \mapsto \left((t,x) \mapsto \mathbb{E}\left[\mathbbm{1}_{\tau_{\partial}^x > t} f(X_t^x)\right]\right)$  is a semigroup with nice properties including the existence of a transition kernel. We sum up the main results (specially Theorem 2.7 and Theorem 2.9 in [9] and Theorem 2.14 in [8]).

**Theorem 8.** Let  $\gamma \in \mathbb{R}$ , there exists

$$(t, x, y) \mapsto p_t^{\gamma}(x, y) \in C^{\infty}(\mathbb{R}_+^* \times D \times D) \cap C(\mathbb{R}_+^* \times \overline{D} \times \overline{D})$$

which satisfies for all t > 0

- $\begin{array}{l} \bullet \ p_t^{\gamma}(x,y) > 0 \ for \ all \ x \not\in \Gamma^+ \cup \Gamma^0 \ \ and \ y \not\in \Gamma^- \cup \Gamma^0 \\ \bullet \ p_t^{\gamma}(x,y) = 0 \ \ if \ x \in \Gamma^+ \cup \Gamma^0 \ \ or \ y \in \Gamma^- \cup \Gamma^0 \end{array}$

Moreover, for  $f \in C^b(\overline{D})$ , the functions  $u_{\gamma}, v_{\gamma}$  defined by

$$\forall t > 0, \forall x \in D, u_{\gamma}(t, x) := \int_{D} p_{t}^{\gamma}(x, y) f(y) dy, \ v_{\gamma}(t, x) := \int_{D} p_{t}^{\gamma}(y, x) f(y) dy$$

are in  $C^{\infty}(\mathbb{R}_+^* \times D)$  and satisfy

(5) 
$$\begin{cases} \partial_t u_{\gamma} &= \mathcal{L}_{\gamma}^* u_{\gamma}, \\ u_{\gamma} &= 0 \text{ on } \Gamma^+, \\ u_{\gamma}(0, \cdot) = f; \end{cases}$$

and

(6) 
$$\begin{cases} \partial_t v_{\gamma} &= \mathcal{L}_{\gamma} v_{\gamma}, \\ v_{\gamma} &= 0 \ on \ \Gamma^-, \\ v_{\gamma}(0,\cdot) = f. \end{cases}$$

Besides, the solution of (5) satisfies Maximum principle. For any t > 0, the operator

$$Q_t^{\gamma} f : x \in \overline{D} \mapsto \mathbb{E}\left[\mathbb{1}_{\tau_{\partial}^x > t} f(X_t^x)\right] = \int p_t^{\gamma}(y, x) f(y) dy$$

is well-defined and forms a positive and irreducible semigroup of compact operators  $(Q_t^\gamma)_{t>0}$  on  $L^n(D)$  to  $L^n(D)$  and  $C^b(\overline{D})$  to  $C^b(\overline{D})$ . Moreover, it maps  $L^n(D)$  into  $C^b(\overline{D})$  continuously for any  $n \in [1, \infty]$ .

Eventually, we recall here a special case of Theorem 2.13 in [9], the last property being a consequence of the irreducibility of the semigroup (see Lemma 4.3 in [8])

**Theorem 9.** Under assumptions above, there exists  $\lambda_{\gamma} > 0$  such that  $\lambda_{\gamma} + \gamma d > 0$  and positive functions  $\varphi_{\gamma}, \psi_{\gamma} \in C^{b}(\overline{D}) \cap L^{1}(D)$ , unique up to multiplicative constants such

(7) 
$$\begin{cases} \mathcal{L}\varphi_{\gamma} + \lambda_{\gamma}\varphi_{\gamma} &= 0\\ \varphi_{\gamma} &= 0 \text{ on } \Gamma^{-} \cup \Gamma^{0} \end{cases}$$

and

(8) 
$$\begin{cases} \mathcal{L}^* \psi_{\gamma} + \lambda_{\gamma} \psi_{\gamma} &= 0 \\ \psi_{\gamma} &= 0 \text{ on } \Gamma^+ \cup \Gamma^0. \end{cases}$$

#### 2. Proof of Theorem 2 and Theorem 3

We establish here Theorem 2 and Theorem 3. The proof of Theorem 2 is split into several steps.

2.1. A semigroup for the kinetic Fokker-Planck equation. In order to use the results of [8, 9] recalled above, first notice that if  $u_{-\gamma}$  is the solution associated to  $\mathcal{L}_{-\gamma}^*$  as in Theorems 7 and 8 then it is  $C^{\infty}(\mathbb{R}_+^* \times D)$  and thus we can derive it in classical sense. It is then easy to check that the function

$$v(t,q,p) := e^{d\gamma t} u_{-\gamma}(t,q,-p)$$

solves (3) in the classical sense. That remark motivates the introduction of the operator defined on the set of measurable functions  $L^0(D)$ 

$$(Sf)(q,p) := f(q,-p) \ \forall f \in L^0(D).$$

The operator S is obviously bounded on  $L^n(D)$  and  $C^b(\overline{D})$ , moreover we have  $S^2 = I$  which imply that the operators defined by

$$(9) P_{\iota}^{\gamma} := e^{d\gamma t} S Q_{\iota}^{-\gamma} S.$$

with  $Q_t^{\gamma}$  defined in Theorem 8, form a semigroup, which, together with Theorem 2.8 in [9], implies the following theorem:

**Theorem 10.** The operators  $(P_t^{\gamma})_{t>0}$  form a positive and irreducible semigroup of compact operators on  $L^n(D)$  for any  $n \in [1,\infty]$  and  $C^b(\overline{D})$ . Moreover, it maps  $L^n(D)$  into  $C^b(\overline{D})$ . And for any  $f \in L^n(D)$ ,  $v_{\gamma} := P_t^{\gamma} f$  is in  $C^{\infty}(\mathbb{R}_+^* \times D)$  and satisfies

$$\begin{cases} \partial_t v_{\gamma} &= \mathcal{L}_{\gamma} v_{\gamma} \ on \ D, \\ v_{\gamma} &= 0 \ on \ \Gamma^-, \\ v_{\gamma}(0, \cdot) &= f. \end{cases}$$

Moreover, we have the identity for any  $f \in C^b(\overline{D})$  and  $v_{\gamma} = P_t^{\gamma} f$ 

$$v_{\gamma} = \int_{D} p_t^{\gamma}(y, x) f(y) dy.$$

where  $p_t^{\gamma}$  is the transition kernel defined in Thorem 8.

From here on, we drop the subscript  $\gamma$  whenever it is obvious from the context what the value of  $\gamma$  is,  $P_t$  for  $P_t^{\gamma}$  and so on. We now show that  $P_t$  is a substochastic semigroup:

### **Lemma 11.** For any t > 0

$$|||P_t||_{L^1(D)} \leq 1.$$

As consequence,  $\forall f \in L^1(D), t \mapsto P_t f \in L^\infty(\mathbb{R}_+; L^1(D)).$ 

*Proof.* By density, it suffices to show that for any t > 0 and for any  $f \in C^b(\overline{D})$ , we have

$$||P_t f||_{L^1(D)} \le ||f||_{L^1(D)}.$$

By Theorem 10 we have for any  $f \in C^b(\overline{D})$ 

$$P_t f = \int_D p_t^{\gamma}(y, x) f(y) dy$$

thus for any  $g \in L^{\infty}(D)$  by Fubini-Tonelli

$$\int_{D} P_{t} f g dx = \int_{D} \int_{D} p_{t}(y, x) f(y) g(x) dy dx$$
$$= \int_{D} f(y) \left( \int_{D} p_{t}(y, x) g(x) dx \right) dy$$

Thus by Maximum principle applied to  $\int_D p_t(y,x)g(x)dx$  that is solution of (5) by Theorem 8, we have for any  $g \in L^{\infty}(D)$ 

$$\left| \int_D P_t f g \right| \le \|f\|_{L^1(D)} \|g\|_{L^{\infty}(D)}$$

which implies by Hahn-Banach:

$$||P_t f||_{L^1(D)} \le ||f||_{L^1(D)}$$

which is the desired result.

**Lemma 12.** Let  $\lambda > 0$  and  $\varphi$  be defined as in Theorem 9, then

$$P_t \varphi = e^{-\lambda t} \varphi, \forall t > 0.$$

We can now show that  $(P_t)_{t\geq 0}$  is a strongly continuous semigroup:

**Proposition 13.** The operators  $(P_t)_{t\geq 0}$  with  $P_0 = I$  and  $(P_t)_{t>0}$  defined above form a  $C_0$ -semigroup of  $L^1(D)$ . As a consequence, the semigroup  $(Q_t)_{t\geq 0}$  associated to the adjoint Cauchy problem is also strongly continuous on  $\mathbb{R}_+$  in  $L^1(D)$ .

*Proof.* It is already known that  $(P_t)_{t>0}$  is strongly continuous on  $\mathbb{R}_+^*$  by Theorem 8. It remains to show that it is strongly continuous at t=0. By Proposition I.5.3 p. 38 in [7], it suffices to show that there exist  $\delta > 0$ ,  $M \ge 1$ , and a dense subset  $\mathcal{D} \subset L^1(D)$  such that

- (1)  $||P_t||_{L^1(D)} \leq M$  for all  $t \in [0, \delta]$ ,
- (2)  $\lim_{t\to 0^+} P_t g = g$  strongly in  $L^1(D)$  for all  $g \in \mathcal{D}$ .

By Lemma 11, we know that  $||P_t||_{L^1(D)} \le 1$ . It remains to establish (2) for  $\mathcal{D} = C_c(D)$ . Let  $g \in C_c(D)$  that we assume nonnegative and denote  $h(t,x) := P_t g(x)$  for any  $x \in D$ , we know that  $h \in C(\mathbb{R}_+ \times D)$ , thus for any  $t \in [0,T]$ ,  $x \mapsto h(t,x)$  is measurable. In the same way, for every  $x \in D$ ,  $t \mapsto h(t,x)$  is continuous. Let  $\varphi$  defined in Theorem 9 and Lemma 12. As  $g \in C_c(D)$  and  $\varphi > 0$  everywhere, there exists C > 0 such that

$$g \leq C\varphi$$
 a.e. on D

and by positivity of  $P_t$  and Lemma 12, we have

$$h \le Ce^{-\lambda t} \varphi \le C\varphi$$
 a.e. on  $D, \forall t \ge 0$ 

with  $\varphi \in L^1(D)$ . In others words, h is dominated on [0,T] by a integrable function on D which implies that:

$$t \to \int_{D} h(t,x) dx$$
 is continuous on  $[0,T]$ .

As h is nonnegative, Schaffé's lemma implies:

(10) 
$$||P_t g - g||_{L^1(D)} \to 0 \text{ as } t \to 0^+ \ \forall \text{ nonnegative } g \in C_c(D)$$

Now consider  $g \in C_c(D)$  that can change sign and let  $g = g_+ - g_-$  with  $g_{\pm} \in C_c(D)$  and  $g_{\pm} \ge 0$ . We have

$$||P_t g - g||_{L^1(D)} \le ||P_t g_+ - g_+||_{L^1(D)} + ||P_t g_- - g_-||_{L^1(D)}$$

thus by (10)

$$||P_t g - g||_{L^1(D)} \to 0 \text{ as } t \to 0^+ \ \forall g \in C_c(D),$$

Consequently,  $(P_t)_{t\geq 0}$  is a  $C_0$ -semigroup of  $L^1(D)$ .

As for  $(Q_t)_{t>0}$ , it is a direct consequence of (9), i.e.

$$Q_t^{\gamma} = e^{d\gamma t} S P_t^{-\gamma} S.$$

Let us make also an important remark

Remark 2. For any t > 0, the kernel  $p_t$  satisfies a Gaussian upper-bound (see [8, Corollary 2.22] or [9, Theorem 2.7]) that is established by studying the Langevin process on the space  $\mathbb{R}^{2d}$  after extending the driving force over the whole space. The authors have deduced an inequality valid on the whole space which they then truncate on  $\Omega \times \mathbb{R}^d$ . As the two functions are continuous, the proof of the authors implies that the inequality is valid on  $\overline{\Omega} \times \mathbb{R}^d$  and thus on  $\partial \Omega \times \mathbb{R}^d$ .

The recall being done, for the sake of readability, we split the proof of Theorem 2 into several steps. First we show that for any  $f^{in} \in L^1(\Omega \times \mathbb{R}^d)$ ,  $t \mapsto P_t f^{in}$  belongs to the good function space.

**Lemma 14.** Let  $f^{in} \in L^1(D)$  and  $f := P_t f^{in}$  with  $(P_t)_{t>0}$  defined in Theorems 8 and 7. Then  $f \in L^{\infty}([0,T];L^1(D))$ .

*Proof.* It is simply a direct consequence that for any t > 0, we have  $||P_t f^{in}||_{L^1(D)} \le ||f^{in}||_{L^1(D)}$ .

We now show that for any smooth initial condition, the solution in the sense of Theorems 8 and 7 is also a weak solution.

**Lemma 15.** Let  $f^{in} \in C^b(D \cup \Gamma^+)$  and  $u := P_t f^{in}$  with  $(P_t)_{t>0}$  defined in Theorems 8 and 7, then for any  $\phi \in \mathcal{D}_{Q_T}$  we have

$$\int_{Q_T} u(\partial_t \phi + \mathcal{L}^* \phi) dt dq dp + \int_D f^{in}(q, p) \phi(0, q, p) dq = 0.$$

In others words, u is a weak solution of (3)

*Proof.* We cannot apply integration by parts (Green Theorem) to the cylindric domain  $Q_T$  because f is not  $C^1$  on  $Q_T$ . Therefore, we introduce  $\varepsilon \in (0,T)$  and the subset:

$$Q_{\varepsilon,T} := [\varepsilon,T] \times D.$$

Let  $f^{in} \in C^b(D \cup \Gamma^+)$  and let u be defined in Theorem 7. We have  $u \in C^b(\overline{Q}_{\varepsilon,T}) \cap C^\infty(Q_{\varepsilon,T})$ , so that by Green Theorem applied to the cylindric domain (see Theorem 5.5 p. 47 in [11]), we have for any  $\phi \in \mathcal{D}_{\tilde{Q}_T}$ 

$$0 = \iint_{Q_{\varepsilon,T}} (\partial_t u - \mathcal{L}u)\phi dt dx$$
$$= \iint_{Q_{\varepsilon,T}} (-\partial_t \phi - \mathcal{L}^*\phi) u dt dx - \iint_D u(\varepsilon, x)\phi(\varepsilon, x) dx$$

We know that, since  $u \in C^b((\mathbb{R}_+ \times \overline{D}) \setminus (\{0\} \times (\Gamma^- \cup \Gamma^0)))$ ,

$$u(\varepsilon,\cdot)\phi(\varepsilon,\cdot)\to f^{in}\phi(0,\cdot)$$
 as  $\varepsilon\to 0^+$  a.e. on  $\Omega\times\mathbb{R}^d$ .

Moreover

$$|u(\varepsilon,\cdot)\phi(\varepsilon,\cdot)| \le ||f^{in}||_{L^{\infty}(D)} \left(\sup_{\varepsilon>0} \phi(\varepsilon,\cdot)\right)$$

As  $(\sup_{\varepsilon} \phi(\varepsilon, \cdot)) \in L^1(\Omega \times \mathbb{R}^d)$  since it is in  $\mathcal{D}_{\tilde{Q}_T}$ , we can apply dominated convergence to get:

$$\iint_D u(\varepsilon, x) \phi(\varepsilon, x) \mathrm{d}x \to_{\varepsilon \to 0^+} \iint_D f^{in} \phi \mathrm{d}x$$

Hence u satisfies for all  $\phi \in \mathcal{D}_{\tilde{O}_T}$ 

$$\iint_{Q_{\varepsilon,T}} (\partial_t \phi + \mathcal{L}^* \phi) u dt dx + \iint_D f^{in}(x) \phi(0,x) dx = 0$$

which is the desired result.

Let now extend the result above to the case of  $f^{in} \in L^1(D)$ .

**Lemma 16.** Let  $f^{in} \in L^1(D)$  and for any t > 0,  $f(t, \cdot) := P_t f^{in}$  then  $f \in L^{\infty}([0, T]; L^1(D))$  and for any  $\phi \in \mathcal{D}_{Q_T}$  we have

$$\int_{Q_T} f(\partial_t \phi + \mathcal{L}^* \phi) dt dq dp + \int_D f^{in}(q, p) \phi(0, q, p) dq = 0.$$

In others words, f is a weak solution of (3)

*Proof.* Let  $f^{in} \in L^1(D)$ . We know that for any t > 0,  $P_t \in \mathcal{L}(L^p(D))$ . Keeping it in mind, take  $f_n^{in} \in C_0^\infty(D)$  such that  $f_n^{in} \to_{n \to +\infty} f^{in}$  in  $L^1(D)$ . Then, denoting  $f_n := P_t f_n^{in}$  we have by Lemma 15 for any  $\phi \in \mathcal{D}_{\tilde{Q}_T}$  and for any  $n \in \mathbb{N}$ :

(11) 
$$\int_{Q_T} f_n(\partial_t \phi + \mathcal{L}^* \phi) dt dq dp + \int_D f_n^{in}(q, p) \phi(0, q, p) dq = 0.$$

By Lebesgue partial converse theorem (see Theorem 4.9 p. 94 in [4]), we can moreover assume that, up to a subsequence, there exists  $g \in L^1(D)$  such that:

$$|f_n^{in}(x)| \le g$$
 a.e. in  $x \in D$ ,

and

$$f_n^{in} \to f^{in}$$
 a.e. in  $x \in D$ .

That implies immediately:

(12) 
$$\int_{D} f_{n}^{in}(q,p)\phi(0,x)dx \to \int_{D} f^{in}(x)\phi(0,x)dx \text{ as } n \to +\infty,$$

and

(13) 
$$\forall (t,x) \in [0,T] \times D, \ \int_D p_t(y,x) f_n^{in} dy \to_{n \to +\infty}, \int_D p_t(y,x) f^{in} dy.$$

Besides, observe that

$$0 \le f_n(t, x) \le \int_D f_n^{in}(y) p_t(y, x) dy \le \int_D g(y) p_t(y, x) dy$$

with  $\int_D g(y)p_t(y,x)dy \in L^1([0,T] \times D)$  and by (13)

$$\int_D f_n^{in}(y) p_t(y, x) dy \to \int_D f^{in}(y) p_t(y, x) dy \text{ a.e. in } (t, x) \in [0, T] \times D$$

as  $n \to +\infty$ . Therefore by dominated convergence we have

$$f_n \to f$$
 in  $L^1([0,T] \times D)$  – strong

as  $n \to +\infty$ . That implies:

(14) 
$$\int_{Q_T} f_n(-\partial_t \phi + \mathcal{L}^* \phi) dt dq dp \to \int_{Q_T} f(-\partial_t \phi + \mathcal{L}^* \phi) dt dq dp$$

as  $n \to +\infty$ . Applying (12) and (14) to (11) shows that f is a weak solution to the initial boundary problem (3) with  $f^{in}$  as initial condition.

As for the uniqueness of the weak solution, as the problem is linear, it suffices to show that  $f \in L^1(Q_T)$  such that

$$\int_{Q_T} f(\partial_t \phi + \mathcal{L}^* \phi) dt dq dp = 0, \ \forall \phi \in \mathcal{D}_{\tilde{Q}_T}$$

implies

$$f = 0$$

If for any  $\psi \in C_c((0,T) \times D)$ , there exists  $\phi \in \mathcal{D}_{\tilde{Q}_T}$  solution of the backward problem

(15) 
$$\begin{cases} \partial_t \phi + \mathcal{L}^* \phi &= \psi \\ \phi_{|\Gamma^0 \cup \Gamma^-} &= 0 \\ \phi(T, \cdot) &= 0 \end{cases}$$

that would imply that f = 0 in distributional sense and thus f = 0 in  $L^1(Q_T)$ . Consider the forward problem:

(16) 
$$\begin{cases} \partial_t \tilde{\phi} - \mathcal{L}^* \tilde{\phi} &= \psi \\ \tilde{\phi}_{|\Gamma^0 \cup \Gamma^-} &= 0 \\ \tilde{\phi}(0, \cdot) &= 0 \end{cases}$$

It is obvious that  $t \mapsto \tilde{\phi}(T - t, \cdot)$  is solution of (15). As  $(Q_t)_{t \geq 0}$  is strongly continuous by Proposition 13, we have by Duhamel formula [7, Corollary III.1.7 p. 161]

$$\tilde{\phi} = \int_0^t Q_{t-s} \psi(s) \mathrm{d}s$$

thus

$$\phi = \int_0^{T-t} Q_{T-t-s} \psi(s) ds$$
$$= \int_t^T Q_{T-s} \psi(s-t) ds$$

It remains to show that  $\phi \in \mathcal{D}_{\tilde{Q}_T}$  to conclude. By linearity, we can assume that  $\psi$  is nonnegative. That being said, first, by the properties of the function  $p_t$  (Theorems 8 and 7 above), we have  $\phi \in C_0^{\infty}(\tilde{Q}_T)$ . Besides, we have obviously  $(\partial_t + \mathcal{L}^*)\phi \in L^{\infty}(Q_T)$ . Eventually, let  $\psi_{\lambda}$  being the positive eigenvector associated to  $\mathcal{L}^*$ , see (8) in Theorem 9, with eigenvalue  $\lambda$  and  $\int_D \psi_{\lambda} = 1$ . Let K compact of  $(0,T) \times D$  such that supp  $\psi \subset K$ . As There  $\psi_{\lambda}$  is positive everywhere on D and constant in time, there exists c > 0 such that  $\psi_{\lambda} \geq c$  for any  $(t,x) \in K$ . Therefore, there exists C > 0 such that

$$\psi \leq C\psi_{\lambda}$$
 everywhere on  $(0,T)\times D$ .

As  $(Q_t)_{t>0}$  are positive operators, the properties of  $\psi_{\lambda}$  and the inequality above imply

$$Q_{t-s}\psi(s) \le Ce^{-\lambda(t-s)}\psi_{\lambda}.$$

Integrating the inequality above in time  $s \in [0, t]$  leads to:

$$\tilde{\phi} \le \frac{C}{\lambda} (1 - e^{-\lambda t}) \psi_{\lambda},$$

thus

$$0 \le \phi \le \frac{C}{\lambda} \Big( 1 - e^{-\lambda(T-t)} \Big) \psi_{\lambda}$$

which implies that  $\phi \in L^1(D; L^\infty((0,T)))$ . Consequently,  $\phi \in \mathcal{D}_{\tilde{Q}_T}$  which is the desired conclusion.

### 2.2. **Proof of Theorem 3.** Now, we establish here Theorem 3

- (1) By Theorem 2, for any  $f^{in} \in L^1(D)$ , there exists a unique weak solution f in sense of Definition 1, thus we have  $f(t,\cdot) = P_t f^{in}$  with  $(P_t)_{t\geq 0}$  defined in (9). By Theorem 10, Lemma 11 and Proposition 13, it is a positive, irreducible, contractive and compact  $C_0$  semigroup.
- (2) By Theorem 7 with the property of semigroup, we have for any  $f^{in} \in L^1(D)$ ,  $\forall t > 0$ ,  $P_t f^{in} \in C^{\infty}(D) \cap C^b(\overline{D})$ .
- (3) With the properties of the semigroup established above, the balanced growth law of  $(P_t)_{t\geq 0}$  is a direct consequence of Lemma 6 with the eigenvectors identified in Theorem 9.

### 3. A Trace theory for the kinetic Fokker-Planck equation

We now establish a trace theory for the kinetic Fokker-Planck equation. First, using the regularity of the weak solution, we can easily define its trace:

**Lemma 17.** Let f be the weak solution with initial condition  $f^{in} \in L^1(D)$ . The trace of f on  $\mathbb{R}_+^* \times \partial D$  is well defined with  $\gamma f := f_{|\partial D}$  and  $\gamma_{\pm} := \gamma f_{|\pm(p \cdot n_q)>0}$ . Moreover we have

$$\gamma_- f = 0 \text{ and } \gamma_+ \in L^1(\partial\Omega \times \mathbb{R}^d; |n_q \cdot p| dq dp).$$

*Proof.* By Theorem 8, we know that for any t > 0,  $P_t$  maps continuously  $L^1(D)$  into  $C^b(\overline{D})$ . Thus we can define  $\gamma f := f_{\partial\Omega \times \mathbb{R}^d}$  and  $\gamma_{\pm} := \gamma f_{|\pm(p \cdot n_g)>0}$ .

Besides, by semigroup property, we have for any t > 0,  $P_t f^{in} = P_{t/2} (P_{t/2} f^{in})$  with  $P_{t/2} f^{in} \in C^b(\overline{D})$  which implies by Theorem 7 that  $\gamma_- f = 0$ .

Now show that  $\gamma_+ f \in L^1(\partial\Omega \times \mathbb{R}^d; |n_q \cdot p| dq dp)$ . As for any t > 0,  $\gamma_+ f \in C^b(\partial D)$ , it is measurable. Now we have by the semigroup property and by continuity:

$$\gamma_+ f(t, x) = \int_D p_{t/2}(x, y) f\left(\frac{t}{2}, y\right) dy$$

with  $y \mapsto f(\frac{t}{2}, y) \in C^b(\partial D)$ , thus

$$|\gamma_+ f(t,x)| \le \left\| f\left(\frac{t}{2},\cdot\right) \right\|_{C^b(\partial D)} \int_D p_{t/2}(x,y) \mathrm{d}y.$$

The Gaussian estimates on  $p_{t/2}$  (see [8, Corollary 2.22] and Remark 2) implies that

$$x \in \partial D \mapsto \int_D p_{t/2}(x, y) dy \in L^1(\partial \Omega \times \mathbb{R}^d; |n_q \cdot p| d\sigma_{\partial \Omega} dp),$$

hence the desired result.

The existence of the trace and the regularity of the weak solution implies that the integration by parts, also known as Green's formula, is satisfied:

**Lemma 18.** Let f be the weak solution with initial condition  $f^{in} \in L^1(D)$  and let  $\gamma f$  be its trace. Then, it satisfies Green's formula, meaning that for any t > 0 and for any  $\phi \in C^{\infty}(D) \cap C(\overline{D})$  we have

$$\int_{D} (\mathcal{L}f)\phi = \int_{D} f\mathcal{L}^*\phi + \int_{\partial D} \gamma f\phi (n_q \cdot p) \mathrm{d}p \mathrm{d}\sigma_{\partial\Omega}.$$

*Proof.* By unicity of the weak solution, we know that for any t > 0,  $f = P_t f^{in}$  and thus  $f \in C^{\infty}(D) \cap C(\overline{D})$  with  $\gamma f \in L^1(\partial\Omega \times \mathbb{R}^d; |n_q \cdot | \mathrm{d}\sigma_{\partial\Omega}\mathrm{d}p)$  by Lemma 17. Hence, the classical theorem of Green's formula (Integration by parts) [11, Th 5.5 p. 47] applies here and leads to the desired result.

### References

- [1] A. Bátkai, M. Kramar Fijavz, and A. Rhandi. *Positive Operator Semigroups*. Operator Theory: Advances and Applications. Birkhäuser Cham, 2017.
- D. Albritton, S. Armstrong, J.-C. Mourrat, and M. Novack. Variational methods for the kinetic Fokker-Planck equation, February 2019.
- [3] Claude Bardos. Problèmes aux limites pour les équations aux dérivées partielles du premier ordre à coefficients réels; théorèmes d'approximation; application à l'équation de transport. Annales scientifiques de l'École Normale Supérieure, 3(2):185–233, 1970.
- [4] Haim Brezis. Functional Analysis, Sobolev Spaces and Partial Differential Equations. Springer New York, New York, NY, 2011.
- [5] José A. Carrillo. Global weak solutions for the initial-boundary-value problems Vlasov-Poisson-Fokker-Planck System. Mathematical Methods in the Applied Sciences, 21(10):907-938, 1998.
- [6] Ben de Pagter. Irreducible compact operators. Math Z, 192(1):149–153, March 1986.
- [7] Klaus-Jochen Engel and Rainer Nagel, editors. One-Parameter Semigroups for Linear Evolution Equations. Graduate Texts in Mathematics. Springer, New York, NY, first edition, 2000.
- [8] Tony Lelièvre, Mouad Ramil, and Julien Reygner. A probabilistic study of the kinetic Fokker–Planck equation in cylindrical domains. J. Evol. Equ., 22(2):38, April 2022.
- [9] Tony Lelièvre, Mouad Ramil, and Julien Reygner. Quasi-stationary distribution for the Langevin process in cylindrical domains, Part I: Existence, uniqueness and long-time convergence. Stochastic Processes and their Applications, 144:173– 201, February 2022.
- [10] A. Mellet and A. Vasseur. Global weak solutions for a Vlasov–Fokker–Planck/Navier–Stokes system of equations. Math. Models Methods Appl. Sci., 17(07):1039–1063, July 2007.
- [11] Friedrich Sauvigny. Partial Differential Equations 1 Foundations and Integral Representations. Universitext. Springer, London, 2012.
- [12] Helmut H. Schaefer. Banach Lattices and Positives Operators. Die Grundlehren Der Mathematischen Wissenschaften. Springer, Berlin, Heidelberg, first edition, 1974.
- [13] G. F. Webb. An Operator-Theoretic Formulation of Asynchronous Exponential Growth. *Transactions of the American Mathematical Society*, 303(2):751–763, 1987.

EB: ENPC, France

 $Email\ address: \verb| etienne.bernard@enpc.fr|$