

Exploiting sparsity in polynomial optimization

Victor Magron

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Exploiting sparsity in polynomial optimization

Victor Magron LAAS CNRS

https://homepages.laas.fr/vmagron/SparsePOPJNCF23.pdf

Journées Nationales de Calcul Formel 6-10 March 2023









Looks like a regular polynomial optimization problem (POP):

inf
$$f(\mathbf{x})$$

s.t. $\mathbf{x} \in \mathbf{X} = \{\mathbf{x} \in \mathbb{R}^n : g_j(\mathbf{x}) \ge 0\}$

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1 — 2 — 3 ----- 99 – 100

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PERFORMANCE



VS



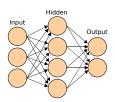
ACCURACY

Everywhere (almost)!

Everywhere (almost)!

Deep learning

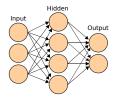
→ robustness, computer vision



Everywhere (almost)!

Deep learning

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Power systems

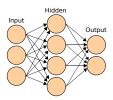
→ AC optimal power-flow, stability



Everywhere (almost)!

Deep learning

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Power systems

→ AC optimal power-flow, stability



Quantum Systems



NP-hard NON CONVEX Problem
$$f_{min} = \inf f(x)$$

Theory

(Primal) (Dual)
$$\inf \int f \, d\mu \qquad \sup \quad \lambda$$
 with μ proba \Rightarrow INFINITE LP \Leftarrow with $f - \lambda \geqslant 0$

NP-hard NON CONVEX Problem $f_{min} = \inf f(x)$

Practice

(Primal **Relaxation**)

moments $\int \mathbf{x}^{\alpha} d\mu$

(Dual **Strengthening**)

 $f - \lambda =$ sum of squares

finite number \Rightarrow

SDP

← fixed degree

Lasserre's Hierarchy of **CONVEX Problems** $\uparrow f_{min}$ [Lasserre '01]

degree $r \& n \text{ vars } \Longrightarrow \binom{n+2r}{n} \text{ SDP } \text{VARIABLES}$



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NP hard General Problem: $f_{\min} := \min_{\mathbf{x} \in \mathbf{X}} f(\mathbf{x})$

Semialgebraic set $\mathbf{X} = \{\mathbf{x} \in \mathbb{R}^n : g_j(\mathbf{x}) \geqslant 0\}$

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$$\mathbf{X} = \{ \mathbf{x} \in \mathbb{R}^n : g_j(\mathbf{x}) \ge 0 \}$$

 $\mathbf{X} = [0, 1]^2 = \{ \mathbf{x} \in \mathbb{R}^2 : x_1(1 - x_1) \ge 0, \quad x_2(1 - x_2) \ge 0 \}$

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$$\frac{f}{x_1 x_2} = \frac{1}{-\frac{1}{8} + \frac{1}{2} \left(x_1 + x_2 - \frac{1}{2} \right)^2} + \frac{1}{2} \underbrace{x_1 (1 - x_1)}^{\sigma_1} + \underbrace{\frac{g_1}{2}}_{x_2 (1 - x_2)} \underbrace{x_2 (1 - x_2)}^{g_2}$$

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Sums of squares (SOS) σ_j

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Sums of squares (SOS) σ_i

Quadratic module: $\mathcal{M}(\mathbf{X})_r = \left\{ \sigma_0 + \sum_j \sigma_j g_j, \deg \sigma_j g_j \leqslant 2r \right\}$

NP-hard NON CONVEX Problem $f_{\min} = \inf_{\mathbf{x} \in \mathbf{X}} f(\mathbf{x})$

- lacksquare space $\mathcal{M}_+(\mathbf{X})$ of probability measures supported on \mathbf{X}
- lacksquare quadratic module $\mathcal{Q}(\mathbf{X}) = \left\{ \sigma_0 + \sum_j \sigma_j g_j, \text{ with } \sigma_j \text{ SOS } \right\}$

Infinite-dimensional linear programs (LP)

$$\begin{array}{lll} \text{(Primal)} & \text{(Dual)} \\ & \inf & \int_{\mathbf{X}} f \, d\mu & = & \sup & \lambda \\ & \text{s.t.} & \mu \in \mathcal{M}_+(\mathbf{X}) & \text{s.t.} & \lambda \in \mathbb{R} \\ & & & f - \lambda \in \mathcal{Q}(\mathbf{X}) \end{array}$$

NP-hard NON CONVEX Problem $f_{\min} = \inf_{\mathbf{x} \in \mathbf{X}} f(\mathbf{x})$

- Pseudo-moment sequences y up to order r
- Truncated quadratic module $Q(\mathbf{X})_r$

Finite-dimensional semidefinite programs (SDP)

$$\begin{array}{lll} \text{(Moment)} & \text{(SOS)} \\ \inf & \sum_{\alpha} f_{\alpha} \, y_{\alpha} & = & \sup \quad \lambda \\ \text{s.t.} & \mathbf{M}_{r-r_{j}}(g_{j} \, \mathbf{y}) \succcurlyeq 0 & \text{s.t.} \quad \lambda \in \mathbb{R} \\ & y_{0} = 1 & f - \lambda \in \mathcal{Q}(\mathbf{X})_{r} \end{array}$$

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Primal-dual "SPARSE" variants?

Sparse SDP

Correlative sparsity

Term sparsity

Ideal sparsity

Tutorial session

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Tutorial session

Symmetric matrices indexed by graph vertices

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Symmetric matrices indexed by graph vertices



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Symmetric matrices indexed by graph vertices



 \forall no edge between 1 and 3 \iff 0 entry in the (1,3) entry

chord = edge between two nonconsecutive vertices in a cycle

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chord = edge between two nonconsecutive vertices in a cycle

chordal graph = all cycles of length ≥ 4 have at least one chord

clique = a fully connected subset of vertices

Chordal extensions



Chordal extensions



Fact

Any non-chordal graph can always be extended to a chordal graph, by adding appropriate edges

Chordal extensions



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**Chordal extension is not unique!

Chordal extensions

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Any non-chordal graph can always be extended to a chordal graph, by adding appropriate edges

Chordal extension is not unique!

1 - 2 | X | | 4 - 3

approximately minimal

maximal

Theorem [Gavril '72, Vandenberghe & Andersen '15]

The maximal cliques of a chordal graph can be enumerated in linear time in the number of nodes and edges.

RIP Theorem for chordal graphs [Blair & Peyton '93]

For a chordal graph with maximal cliques I_1, \ldots, I_p :

$$(\mathsf{RIP}) \quad \forall k$$

(possibly after reordering)

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- $\stackrel{\smile}{V}$ RIP always holds for p=2
- RIP holds for chains

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(RIP)
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(possibly after reordering)

- RIP holds for chains

RIP holds for numerous applications!

Semidefinite Programming (SDP)

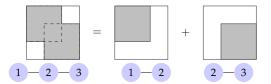
$$\min_{\mathbf{y}} \quad \mathbf{c}^{\mathsf{T}} \mathbf{y}$$
s.t.
$$\sum_{i} \mathbf{F}_{i} y_{i} \succcurlyeq \mathbf{F}_{0}$$



- Linear cost c
- Symmetric matrices \mathbf{F}_0 , \mathbf{F}_i
- Linear matrix inequalities "F >> 0"(F has nonnegative eigenvalues)

Spectrahedron

Theorem [Griewank Toint '84, Agler et al. '88]



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Chordal graph G with n vertices & maximal cliques I_1 , I_2 $Q_G \geqslant 0$ with nonzero entries corresponding to edges of G $\implies Q_G = P_1^T Q_1 P_1 + P_2^T Q_2 P_2$ with $Q_k \geqslant 0$ indexed by I_k

What are P_1, P_2 ?

Theorem [Griewank Toint '84, Agler et al. '88]

What are
$$P_1, P_2$$
? $P_1 \in \mathbb{R}^{|I_1| \times n}$

$$P(i,j) = \begin{cases} 1 & \text{if } I(i) = j \\ 0 & \text{otherwise} \end{cases}$$

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$$1-2-3$$
 $1-2$ $2-3$

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$$I_1 = (1,2) \Rightarrow P_1 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

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 $P_1^T Q_1 P_1$ inflates a $|I_1| \times |I_1|$ matrix Q_1 into a sparse $n \times n$ matrix

Sparse SDP

Correlative sparsity

Term sparsity

Ideal sparsity

Tutorial session

Fixploit few links between variables [Lasserre, Waki et al. '06]

$$f(\mathbf{x}) = x_2x_5 + x_3x_6 - x_2x_3 - x_5x_6 + x_1(-x_1 + x_2 + x_3 - x_4 + x_5 + x_6)$$

Correlative sparsity pattern (csp) graph G

$$Vertices = \{1, \dots, n\}$$

 $(i,j) \in \mathsf{Edges} \Longleftrightarrow x_i x_j \text{ appears in } f$

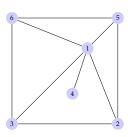


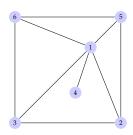
Figure 2 Exploit few links between variables [Lasserre, Waki et al. '06]

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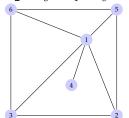
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 appears in f



Similar construction with constraints $\mathbf{X} = \{\mathbf{x} \in \mathbb{R}^n : g_i(\mathbf{x}) \ge 0\}$

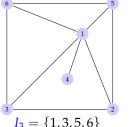
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Chordal graph after adding edge (3,5)



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Chordal graph after adding edge (3,5)



maximal cliques
$$I_1 = \{1,4\}$$
 $I_2 = \{1,2,3,5\}$ $I_3 = \{1,3,5,6\}$

$$f = f_1 + f_2 + f_3$$
 where f_k involves **only** variables in I_k

 \widecheck{V} Let us index moment matrices and SOS with the cliques I_k

A sparse variant of Putinar's Positivstellensatz

Convergence of the Moment-SOS hierarchy is based on:

Theorem [Putinar '93] Positivstellensatz

If **X** contains a ball constraint $N - \sum_i x_i^2 \ge 0$ then

$$f > 0$$
 on $\mathbf{X} = \{\mathbf{x} : g_j(\mathbf{x}) \geqslant 0\} \implies f = \sigma_0 + \sum_j \sigma_j g_j$ with σ_j SOS

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Theorem: Sparse Putinar's representation [Lasserre '06]

$$f = \sum_k f_k$$
, f_k depends on $\mathbf{x}(I_k)$
 $f > 0$ on \mathbf{X}
Each g_j depends on some I_k
RIP holds for (I_k)

ball constraints for each $x(I_k)$

$$f = \sum_{k} (\sigma_{0k} + \sum_{j \in J_k} \sigma_j g_j)$$

$$SOS \sigma_{0k} \text{ "sees" vars in } I_k$$

 \Rightarrow SOS σ_{0k} "sees" vars σ_j "sees" vars from g_j

A first key message



SUMS OF SQUARES PRESERVE SPARSITY



Let $\mathbf{X} = \{\mathbf{x} : g_j(\mathbf{x}) \ge 0\}$ be compact and $f = \sum_k f_k$, with f_k depends on $\mathbf{x}(I_k)$, and f > 0 on \mathbf{X}

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 $\mathbf{X}_k = \{\mathbf{x}(I_k) : g_j(\mathbf{x}) \geqslant 0 : j \in J_k\}$ = the subspace of \mathbf{X} which only "sees" variables indexed by I_k

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Lemma [Grimm et al. '07]

If RIP holds for (I_k) then

 $f = \sum_k h_k$, with h_k depends on $\mathbf{x}(I_k)$, and $h_k > 0$ on \mathbf{X}_k

Let $\mathbf{X} = \{\mathbf{x} : g_j(\mathbf{x}) \geqslant 0\}$ be compact and $f = \sum_k f_k$, with f_k depends on $\mathbf{x}(I_k)$, and f > 0 on \mathbf{X}

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Lemma [Grimm et al. '07]

If RIP holds for (I_k) then $f = \sum_k h_k$, with h_k depends on $\mathbf{x}(I_k)$, and $h_k > 0$ on \mathbf{X}_k

 \bigvee Prove this lemma by induction on the number of subsets I_k

Let $\mathbf{X} = \{\mathbf{x} : g_j(\mathbf{x}) \geqslant 0\}$ be compact and $f = \sum_k f_k$, with f_k depends on $\mathbf{x}(I_k)$, and f > 0 on \mathbf{X}

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For each subset I_k , submatrix of $\mathbf{M}_r(\mathbf{y})$ corresponding of rows & columns indexed by monomials in $\mathbf{x}(I_k)$

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$$I_1 = \{1,4\} \implies$$
 monomials in x_1, x_4

$$\mathbf{M}_{1}(\mathbf{y}, I_{1}) = \begin{pmatrix} 1 & | & y_{1,0,0,0,0,0} & y_{0,0,0,1,0,0} \\ & - & - & - \\ y_{1,0,0,0,0,0} & | & y_{2,0,0,0,0,0} & y_{1,0,0,1,0,0} \\ y_{0,0,0,1,0,0} & | & y_{1,0,0,1,0,0} & y_{0,0,0,2,0,0} \end{pmatrix}$$

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 \forall same for each localizing matrix $\mathbf{M}_r(g_i\mathbf{y})$

Sparse primal-dual Moment-SOS hierarchy

$$f_{\min} = \inf_{\mathbf{x} \in \mathbf{X}} f(\mathbf{x}) \text{ with } \mathbf{X} = \{\mathbf{x} : g_i(\mathbf{x}) \ge 0\}$$

Dense Moment-SOS hierarchy

$$\begin{array}{lll} \text{(Moment)} & \text{(SOS)} \\ & \inf & \sum_{\alpha} f_{\alpha} \, y_{\alpha} & = & \sup \quad \lambda \\ & \text{s.t.} & \mathbf{M}_{r}(\mathbf{y}) \succcurlyeq 0 & \text{s.t.} & \lambda \in \mathbb{R} \\ & & \mathbf{M}_{r-r_{j}}(g_{j} \, \mathbf{y}) \succcurlyeq 0 & f - \lambda = \sigma_{0} + \sum_{j} \sigma_{j} g_{j} \end{array}$$

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Each g_i depends on some I_k

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Sparse Moment-SOS hierarchy

$$(Moment) \qquad (SOS)$$

$$\inf \ \sum_{\alpha} f_{\alpha} y_{\alpha} \qquad = \sup \ \lambda$$

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$$y_{0} = 1$$

RIP holds for (I_k) + ball constraints for each $x(I_k)$ \Longrightarrow Primal and dual optimal value converge to f_{\min} by sparse Putinar

Computational cost

$$f_{\min} = \inf_{\mathbf{x} \in \mathbf{X}} f(\mathbf{x}) \text{ with } \mathbf{X} = \{\mathbf{x} : g_j(\mathbf{x}) \geqslant 0, j \leqslant m\}$$

 $\tau = \max\{|I_1|, \dots, |I_p|\}$

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(m+p) SOS in at most τ vars of degree $\leq 2r$

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 $(m+p)\mathcal{O}(r^{\tau})$ SDP vars

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(m+p) SOS in at most τ vars of degree $\leq 2r$

 $(m+p) \mathcal{O}(r^{\tau})$ SDP vars vs $(m+1) \mathcal{O}(r^n)$ in the dense SDP

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$$f_{\min} = \inf_{\mu} \int_{\mathbf{X}} f \, d\mu$$

s.t. $\mu \in \mathcal{M}_{+}(\mathbf{X})$

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Sparse moment SDPs relax the sparse LP over measures:

$$f_{\text{cs}} = \inf_{\mu_k} \sum_{k} \int_{\mathbf{X}_k} f_k \, d\mu_k$$

s.t. $\pi_{jk} \mu_j = \pi_{kj} \mu_k$, $\mu_k \in \mathcal{M}_+(\mathbf{X}_k)$

The dual of sparse Putinar's Positivstellensatz

Theorem [Lasserre '06]

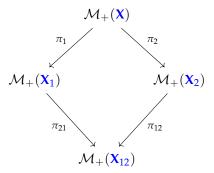
RIP holds for
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 \mathcal{V} Proof: there exists $\mu \in \mathcal{M}_+(\mathbf{X})$ with marginal μ_k on \mathbf{X}_k



A first (dual) key message



THE MEASURE LP PRESERVES SPARSITY V



Let r_{\min} be the minimal relaxation order.

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Theorem: dense extraction [Lasserre & Henrion '05]

Assume that the moment SDP has an optimal solution \mathbf{y} with cost f^r and

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Then $f^r = f_{\min}$ and the LP over measures has an optimal solution $\mu \in \mathcal{M}_+(\mathbf{X})$ supported on $t = \operatorname{rank} \mathbf{M}_{r'}(\mathbf{y})$ points of \mathbf{X} .

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Extraction possible with the Gloptipoly software

 $a_k = \max_{j \in J_k} r_j = \max$ half degree of g_j depending on I_k .

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- RIP is not required!
- \bigvee Extract $\mathbf{x}(k)$ from $\mathbf{M}_r(\mathbf{y}, \mathbf{I}_k) \implies$ minimizer \mathbf{x} with $(x_i)_{i \in I_k} = \mathbf{x}(k)$

Application to rational functions

$$f_{\min} = \inf_{\mathbf{x} \in \mathbf{X}} \sum_{i} \frac{p_i(\mathbf{x})}{q_i(\mathbf{x})}, \quad q_i > 0 \text{ on } \mathbf{X}, \quad p_i, q_i \text{ depends only on } I_i$$

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Theorem: dense measure LP [Bugarin et al. '16]

$$f_{\min} = \inf_{\mu_i \in \mathcal{M}_+(\mathbf{X})} \sum_i \int_{\mathbf{X}} p_i \, d\mu_i$$
s.t.
$$\int_{\mathbf{X}} \mathbf{x}^{\alpha} \, q_i \, d\mu_i = \int_{\mathbf{X}} \mathbf{x}^{\alpha} \, q_1 \, d\mu_1, \, \alpha \in \mathbb{N}^n$$

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1: Error
$$f(x) - \hat{f}(x, e) = \ell(x, e) + h(x, e)$$
, ℓ linear in e

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- 1: Error $f(x) \hat{f}(x, e) = \ell(x, e) + h(x, e)$, ℓ linear in e
- 2: Bound h(x, e) with interval arithmetic

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- 1: Error $f(x) \hat{f}(x, e) = \ell(x, e) + h(x, e)$, ℓ linear in e
- 2: Bound h(x, e) with interval arithmetic
- 3: Bound $\ell(x, e)$ with Sparse Sums of Squares

$$\bigvee I_k \to \{\mathbf{x}, e_k\} \implies \boxed{m \, r^{n+1} \text{ instead of } r^{n+m}} \text{SDP vars}$$

$$f = x_2 x_5 + x_3 x_6 - x_2 x_3 - x_5 x_6 + x_1 (-x_1 + x_2 + x_3 - x_4 + x_5 + x_6)$$
$$\mathbf{x} \in [4.00, 6.36]^6, \quad \mathbf{e} \in [-\epsilon, \epsilon]^{15}, \quad \epsilon = 2^{-53}$$

Dense SDP: $\binom{6+15+4}{6+15} = 12650$ variables \sim Out of memory

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Sparse SDP Real2Float tool: $15\binom{6+1+4}{6+1} = 4950 \rightsquigarrow 759\epsilon$

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Symbolic Taylor FPTaylor tool: 721ϵ (21 × more CPU)

$$f = x_2 x_5 + x_3 x_6 - x_2 x_3 - x_5 x_6 + x_1 (-x_1 + x_2 + x_3 - x_4 + x_5 + x_6)$$
$$\mathbf{x} \in [4.00, 6.36]^6, \quad \mathbf{e} \in [-\epsilon, \epsilon]^{15}, \quad \epsilon = 2^{-53}$$

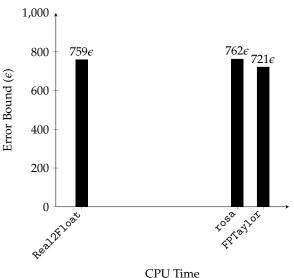
Dense SDP: $\binom{6+15+4}{6+15} = 12650$ variables \sim Out of memory

Sparse SDP Real2Float tool: $15\binom{6+1+4}{6+1} = 4950 \rightsquigarrow 759\epsilon$

Interval arithmetic: 922ϵ (10 × less CPU)

Symbolic Taylor FPTaylor tool: 721ϵ (21 × more CPU)

SMT-based rosa tool: 762ϵ (19 × more CPU)



Extension to noncommutative optimization

Self-adjoint noncommutative variables $a_i, b_i \in \mathcal{B}(\mathcal{H})$

$$f = a_1(b_1 + b_2 + b_3) + a_2(b_1 + b_2 - b_3) + a_3(b_1 - b_2) - b_1 - 2b_1 - b_2$$

with $a_1 a_2 \neq a_2 a_1$, involution $(a_1 b_3)^* = b_3 a_1$

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Constraints $\mathbf{X} = \{(a, b) : a_i^2 = a_i, b_j^2 = b_j, a_i b_j = b_j a_i \}$

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MINIMAL EIGENVALUE OPTIMIZATION

$$\lambda_{\min} = \inf \{ \langle f(a,b)\mathbf{v}, \mathbf{v} \rangle : (a,b) \in \mathbf{X}, ||\mathbf{v}|| = 1 \}$$

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$$= \sup \quad \lambda$$
$$\text{s.t.} \quad f(a,b) - \lambda \mathbf{I} \succcurlyeq 0, \quad \forall (a,b) \in \mathbf{X}$$

Ball constraint $N - \sum_i x_i^2 \geq 0$ in **X**

Theorem: NC Putinar's representation [Helton & McCullough '02]

$$f\succ 0 \text{ on } \mathbf{X} \implies \boxed{f=\sum_i s_i^\star s_i + \sum_j \sum_i t_{ji}^\star g_j t_{ji}} \text{ with } s_i,\, t_{ji} \in \mathbb{R}\langle \underline{x}\rangle$$

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NC variant of Lasserre's Hierarchy for λ_{min} :

Freplace "
$$f - \lambda \mathbf{I} \geq 0$$
 on \mathbf{X} " by $f - \lambda \mathbf{I} = \sum_i s_i^* s_i + \sum_j \sum_i t_{ji}^* g_j t_{ji}$ with s_i, t_{ji} of **bounded** degrees = SDP

Self-adjoint noncommutative (NC) variables $x = (x_1, ..., x_n)$

Theorem [Helton & McCullough '02]

 $f \succcurlyeq 0 \Leftrightarrow f$ SOS (all positive polynomials are sums of squares)

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Theorem: Sparse NC Positivstellensatz [Klep Magron Povh '21]

$$\begin{array}{l} f = \sum_k f_k, \, f_k \text{ depends on } x(I_k) \\ f > 0 \text{ on } \{\mathbf{x}: g_j(\mathbf{x}) \geqslant 0\} \\ \text{chordal graph with cliques } I_k \implies \\ \text{ball constraints for each } \mathbf{x}(I_k) \end{array}$$

$$f = \sum_{k,i} (s_{ki}^{\star} s_{ki} + \sum_{j \in J_k} t_{ji}^{\star} g_j t_{ji})$$

 s_{ki} "sees" vars in I_k t_{ii} "sees" vars from g_i

 I_{3322} Bell inequality (entanglement in quantum information)

$$f = a_1(b_1 + b_2 + b_3) + a_2(b_1 + b_2 - b_3) + a_3(b_1 - b_2) - a_1 - 2b_1 - b_2$$

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level sparse 2 0.2550008

dense [Pál & Vértesi '18] 0.2509397

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3	0.2511592	0.2508756

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3'		0.2508754 (1 day)
4	0.2508917	
5	0.2508763	
6	0.2508753977180	(1 hour)

PERFORMANCE



V.S



ACCURACY

Application to SOS of bounded degrees

Theorem: sparse BSOS representation [Weisser et al. '18]

If $0 \le g_i \le 1$ on \mathbf{X} , f > 0 on \mathbf{X} & RIP holds for (I_k) then

$$f = \sum_{k} \left(\sigma_k + \sum_{\alpha,\beta} c_{k,\alpha\beta} \prod_{j \in J_k} g_j^{\alpha_j} (1 - g_j)^{\beta_j} \right) ,$$

with σ_k SOS of degree $\leq 2r$

Application to sparse positive definite forms

Theorem: [Reznick '95] Positivstellensatz

pd form
$$f \implies \left| f = \frac{\sigma}{\|\mathbf{x}\|_2^{2r}} \right|$$
 with σ SOS, $r \in \mathbb{N}$

Application to sparse positive definite forms

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$$\mathsf{pd}\;\mathsf{form}\;f\;\Longrightarrow\;\left|f=\frac{\sigma}{\|\mathbf{x}\|_2^{2r}}\right|\mathsf{with}\;\sigma\;\mathsf{SOS},\,r\in\mathbb{N}$$

Sparse $f \sum_k f_k$, with f_k only depends on I_k RUNNING INTERSECTION PROPERTY (RIP)

$$orall k \quad I_k \cap igcup_{j < k} I_j \subseteq I_{s_k} \quad ext{for some } s_k < k$$

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Theorem: sparse Reznick [Mai Lasserre Magron '20]

$$\mathsf{RIP} \implies \boxed{f = \sum_k \frac{\sigma_k}{H_k{}^r}} \text{ with } \sigma_k \text{ SOS only depends on } I_k$$

Uniform H_k involve products $||\mathbf{x}(I)||_2^2$ for $I \in \{I_k, \hat{I}_k, \hat{I}_i : s_i = k\}$

Robust Geometric Perception [Yang & Carlone '20]

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Volume computation [Tacchi et al. '21]

Robustness of implicit deep networks [Chen et al. '21]

Sparse SDF

Correlative sparsity

Term sparsity

Ideal sparsity

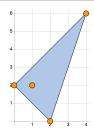
Tutorial session

Term sparsity via Newton polytope

$$f = 4x_1^4x_2^6 + x_1^2 - x_1x_2^2 + x_2^2$$

$$\mathsf{spt}(f) = \{(4,6), (2,0), (1,2), (0,2)\}$$

Newton polytope $\mathscr{B} = \operatorname{conv}\left(\operatorname{spt}(f)\right)$



Squares in SOS decomposition $\subseteq \frac{\mathscr{B}}{2} \cap \mathbb{N}^n$ [Reznick '78]



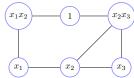
$$f = \begin{pmatrix} x_1 & x_2 & x_1 x_2 & x_1 x_2^2 & x_1^2 x_2^3 \end{pmatrix} \underbrace{Q}_{\geq 0} \begin{pmatrix} x_1 \\ x_2 \\ x_1 x_2 \\ x_1 x_2^2 \\ x_1^2 x_2^3 \end{pmatrix}$$

$$f = x_1^2 - 2x_1x_2 + 3x_2^2 - 2x_1^2x_2 + 2x_1^2x_2^2 - 2x_2x_3 \\ + 6x_3^2 + 18x_2^2x_3 - 54x_2x_3^2 + 142x_2^2x_3^2$$
 [Reznick '78] $\rightarrow f = \begin{pmatrix} 1 & x_1 & x_2 & x_3 & x_1x_2 & x_2x_3 \end{pmatrix}$ $\searrow \frac{Q}{x_1}$ $\searrow \frac{6 \times 7}{2} = 21$ "unknown" entries in Q

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$$\Rightarrow \frac{6\times7}{2} = 21 \text{ "unknown" entries in } Q$$

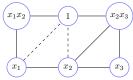
Term sparsity pattern graph G



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V Term sparsity pattern graph *G* + chordal extension *G'*

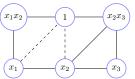


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▼ Term sparsity pattern graph *G* + chordal extension *G'*



Replace Q by $Q_{G'}$ with nonzero entries at edges of $G' \rightsquigarrow 6 + 9 = 15$ "unknown" entries in $Q_{G'}$

At step *r* of the hierarchy, tsp graph *G* has

Nodes V = monomials of degree $\leq r$

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$$\{\alpha, \beta\} \in E \Leftrightarrow \alpha + \beta \in \operatorname{supp} f \bigcup \operatorname{supp} g_j \bigcup_{|\alpha| \leqslant r} 2\alpha$$

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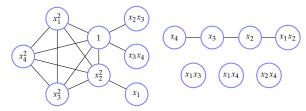
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An example with r=2

$$f = x_1^4 + x_1 x_2^2 + x_2 x_3 + x_3^2 x_4^2$$

$$g_1 = 1 - x_1^2 - x_2^2 - x_3^2 \quad g_2 = 1 - x_3 x_4$$



Term sparsity: support extension

$$\alpha' + \beta' = \alpha + \beta \text{ and } (\alpha, \beta) \in E \Rightarrow (\alpha', \beta') \in E$$

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By iteratively performing support extension & chordal extension

$$G^{(1)} = G' \subseteq \cdots \subseteq G^{(s)} \subseteq G^{(s+1)} \subseteq \cdots$$

 \bigvee Two-level hierarchy of lower bounds for f_{\min} , indexed by sparse order s and relaxation order r

Let G' be a chordal extension of G with maximal cliques (C_i)

$$C_i \longmapsto \mathbf{M}_{C_i}(\mathbf{y})$$

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 \bigvee Each constraint $G_j \leadsto G_j^{(s)} \leadsto$ cliques $C_{j,i}^{(s)}$

Let $C_{j,i}^{(s)}$ be the maximal cliques of $G_j^{(s)}$. For each $s \geq 1$

$$f_{ts}^{r,s} = \inf \sum_{\alpha} \int_{\alpha} y_{\alpha}$$
s.t.
$$\mathbf{M}_{C_{0,i}^{(s)}}(\mathbf{y}) \geq 0$$

$$\mathbf{M}_{C_{j,i}^{(s)}}(g_{j}\mathbf{y}) \geq 0$$

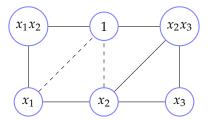
$$y_{0} = 1$$

V dual yields the TSSOS hierarchy

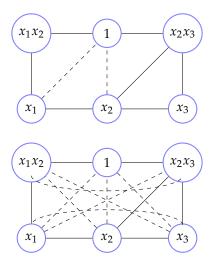
A two-level hierarchy of lower bounds

$f_{ts}^{r_{min},1} \leq$	$f_{ts}^{r_{min},2} \leq$	$\cdots \leq$	$f^{r_{\min}}$
\wedge I	\wedge I		\wedge I
$f_{ts}^{r_{min}+1,1} \leq$	$f_{\mathrm{ts}}^{r_{\mathrm{min}}+1,2} \leq$	$\cdots \leq$	$f^{r_{\min}+1}$
\wedge I	\wedge I		\wedge I
÷	÷	÷	:
\wedge I	\wedge I		\wedge I
$f_{ts}^{r,1} \leq$	$f_{ts}^{r,2} \leq$	$\cdots \leq$	f^r
\wedge I	\wedge I		\wedge I
:	:	:	:

Different choices of chordal extensions



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$$f = 1 + x_1^2 x_2^4 + x_1^4 x_2^2 + x_1^4 x_2^4 - x_1 x_2^2 - 3x_1^2 x_2^2$$

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$$\begin{array}{l} f = 1 + x_1^2 x_2^4 + x_1^4 x_2^2 + x_1^4 x_2^4 - x_1 x_2^2 - 3 x_1^2 x_2^2 \\ \text{Newton polytope} \leadsto \mathscr{B} = \begin{pmatrix} 1 & x_1 x_2 & x_1 x_2^2 & x_1^2 x_2 & x_1^2 x_2^2 \end{pmatrix} \end{array}$$

$$x_2 \mapsto -x_2$$

Sign-symmetries blocks $(1 \quad x_1 x_2^2 \quad x_1^2 x_2^2) \quad (x_1 x_2 \quad x_1^2 x_2)$
TSSOS blocks $(1 \quad x_1 x_2^2 \quad x_1^2 x_2^2) \quad (x_1 x_2) \quad (x_1^2 x_2)$

A second key message



TSSOS preserves the block structure related to sign-symmetries



Comparison with (S)DSOS

Let f be a nonnegative polynomial of degree 2d f is SOS $\Leftrightarrow f = \mathbf{v}^T \mathbf{Q} \mathbf{v}$ with $\mathbf{Q} \succcurlyeq 0 \leadsto$ semidefinite program where \mathbf{v} contains $1, x_1, \ldots, x_n, x_1^2, \ldots, x_n^d$

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To reduce the number of "unknown" entries in Q, one can force: [Ahmadi & Majumdar '14]

- **1** Q diagonally dominant: $Q_{ii} \geqslant \sum_{i \neq i} Q_{ij} \rightsquigarrow \text{linear program}$
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Theorem [Lasserre Magron Wang '21]

The first TSSOS relaxation is always more accurate than the SDSOS relaxation

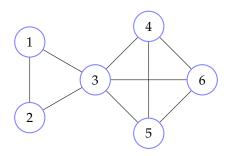
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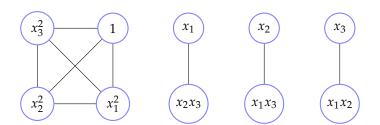
$$f = 1 + \sum_{i=1}^{6} x_i^4 + x_1 x_2 x_3 + x_3 x_4 x_5 + x_3 x_4 x_6 + x_3 x_5 x_6 + x_4 x_5 x_6$$

csp graph



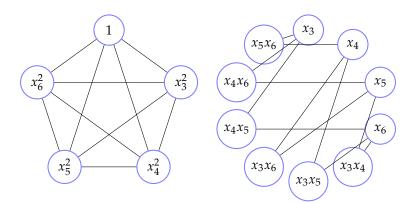
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tsp graph for the first clique



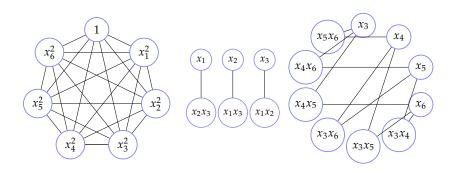
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tsp graph for the second clique

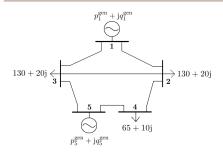


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tsp graph without correlative sparsity



Application to optimal power-flow



Optimal Powerflow $n \simeq 10^3$ [Josz et al. '18]

$$\begin{aligned} &\inf_{V_{i},S_{s}^{g},S_{ij}} \quad \sum_{s \in G} (\mathbf{c}_{2s}(\Re(S_{s}^{g}))^{2} + \mathbf{c}_{1s}\Re(S_{s}^{g}) + \mathbf{c}_{0s}) \\ &\text{s.t.} \quad \angle V_{\mathsf{ref}} = 0, \\ &\mathbf{S}_{s}^{gl} \leq S_{s}^{g} \leq \mathbf{S}_{s}^{gu} \ \forall s \in G, \quad \boldsymbol{v}_{i}^{l} \leq |V_{i}| \leq \boldsymbol{v}_{i}^{u} \ \forall i \in N \\ &\sum_{s \in G_{i}} S_{s}^{g} - \mathbf{S}_{i}^{d} - \mathbf{Y}_{i}^{s} |V_{i}|^{2} = \sum_{(i,j) \in E_{i} \cup E_{i}^{g}} S_{ij}, \quad \forall i \in N \\ &S_{ij} = (\mathbf{Y}_{ij}^{*} - \mathbf{i} \frac{\mathbf{b}_{ij}^{c}}{2}) \frac{|V_{i}|^{2}}{|\mathbf{T}_{ij}|^{2}} - \mathbf{Y}_{ij}^{*} \frac{V_{i}V_{j}^{*}}{\mathbf{T}_{ij}}, \quad S_{ji} = \cdots \\ &|S_{ij}| \leq \mathbf{s}_{ij}^{u}, \ \boldsymbol{\theta}_{ij}^{\Delta l} \leq \angle(V_{i}V_{j}^{*}) \leq \boldsymbol{\theta}_{ij}^{\Delta u}, \quad \forall (i,j) \in E \end{aligned}$$

Application to optimal power-flow

mb = the maximal size of blocksm = number of constraints

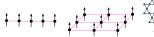
n m	111	CS (r = 2)			CS+TS $(r = 2, s = 1)$		
	l III	mb	time (s)	gap	mb	time (s)	gap
114	315	66	5.59	0.39%	31	2.01	0.73%
348	1809	253	_	_	34	278	0.05%
766	3322	153	585	0.68%	44	33.9	0.77%
1112	4613	496	_	_	31	410	0.25%
4356	18257	378	_	_	27	934	0.51%
6698	29283	1326	_	_	76	1886	0.47%

Ground-state energy ⇔ minimal eigenvalue of an Hamiltonian

$$H = \sum_{\langle i,j\rangle} (x_i x_j + y_i y_j + z_i z_j)$$

spin states (x_i, y_i, z_i) , constraints

Lattices: 1D 2D Kagome



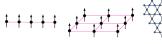


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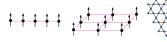
First neighbors interactions : $H = \sum_{i=1}^{n} x_i x_{i+1} + y_i y_{i+1} + z_i z_{i+1}$

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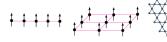
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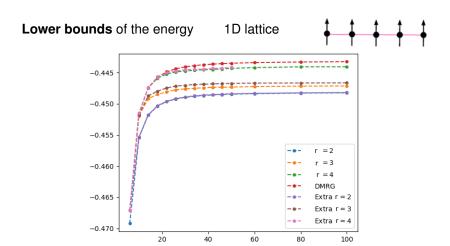




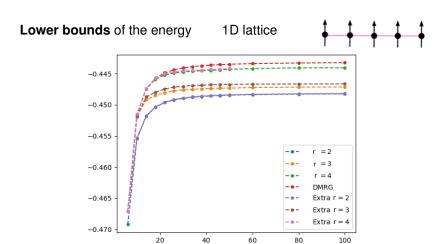
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Existing \pm efficient techniques: quantum Monte Carlo & variational algorithms \Rightarrow **upper bounds** on minimal energy



Dense r = 4, $n = 10^2 \Rightarrow 10^{11}$ variables (solvers handle $\simeq 10^4$)



Dense r=4, $n=10^2 \Rightarrow 10^{11}$ variables (solvers handle $\simeq 10^4$) Sparse solved within 1 hour on PFCALCUL at LAAS

CLASSICAL WORLD

$$\psi^*(A_1 \otimes B_1 + A_1 \otimes B_2 + A_2 \otimes B_1 - A_2 \otimes B_2)\psi \leqslant 2$$

for separable states $\psi \in \mathbb{C}^k \otimes \mathbb{C}^k$ and matrices A_j, B_j satisfying $A_j^* = A_j, A_j^2 = I, B_j^* = B_j, B_j^2 = I$

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$$2\sqrt{2} = \operatorname{tr}_{\max}\{a_1b_1 + a_1b_2 + a_2b_1 - a_2b_2 : a_i^2 = b_i^2 = 1\}$$

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7 2nd sparse SDP gives also 5 ... 10 times faster

Lyapunov function

$$f = \sum_{i=1}^{N} a_i(x_i^2 + x_i^4) - \sum_{i,k=1}^{N} b_{ik} x_i^2 x_k^2 \quad a_i \in [1,2] \quad b_{ik} \in \left[\frac{0.5}{N}, \frac{1.5}{N}\right]$$

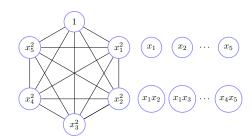
$$\rightsquigarrow \binom{N+2}{2}(\binom{N+2}{2}+1)/2$$
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🏋 tsp graph G

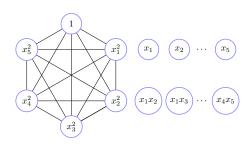


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🍹 tsp graph G



$$\rightsquigarrow (N+1)^2$$
 "unknown" entries in $Q_G = 36$ for $N = 5$

Proof that $f \ge 0$ for N = 80 in ~ 10 seconds!

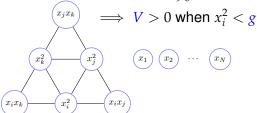
Duffing oscillator Hamiltonian
$$V = \sum_{i=1}^{N} a_i (\frac{x_i^2}{2} - \frac{x_i^4}{4}) + \frac{1}{8} \sum_{i,k=1}^{N} b_{ik} (x_i - x_k)^4$$
On which domain $V > 0$?
$$f = V - \sum_{i=1}^{N} \underbrace{\lambda_i}_{>0} x_i^2 (g - x_i^2) \geqslant 0$$

$$\implies V > 0 \text{ when } x_i^2 < g$$

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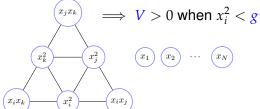


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🏋 tsp graph G

$$\rightsquigarrow \frac{N(N+1)}{2} + 6\binom{N}{2} + N$$
 "unknown" entries in $Q_G = 80$ for $N = 5$

Proof that $f \geqslant 0$ for N = 50 in ~ 1 second!

Given
$$\mathcal{A} = \{A_1, \dots, A_m\} \subseteq \mathbb{R}^{n \times n}$$
, the JSR is
$$\rho(\mathcal{A}) := \lim_{k \to \infty} \max_{\sigma \in \{1, \dots, m\}^k} ||A_{\sigma_1} A_{\sigma_2} \cdots A_{\sigma_k}||^{\frac{1}{k}}$$

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Tons of applications:

- stability of switched linear systems
- continuity of wavelet functions
- trackability of graphs
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... NP-hard to compute/approximate

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Given $\mathcal{A} = \{A_1, \dots, A_m\} \subseteq \mathbb{R}^{n \times n}$, if a positive definite form f of degree 2r satisfies

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Bisection on γ + SDP

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Theorem: Sparse JSR [Maggio Magron Wang '21]

$$\begin{split} \tilde{\mathbf{V}} \cdot \rho(\mathbf{A}) \leqslant \rho^r(\mathbf{A}) \leqslant \rho^{r,s}(\mathbf{A}) &= \inf_{f \in \mathbb{R}[\mathscr{A}^{(s)}], \gamma} \gamma \\ \text{s.t. } \begin{cases} f(\mathbf{x}) - ||\mathbf{x}||_2^{2r} \operatorname{SOS}(\mathscr{A}^{(s)}) \\ \gamma^{2r} f(\mathbf{x}) - f(A_i \mathbf{x}) \operatorname{SOS}(\mathscr{A}_i^{(s)}) \end{cases} \end{split}$$

Closed-loop system evolves according to either a completed or a missed computation (A_H or A_M): $\mathcal{A} = \{A_H A_M{}^i \mid i < m\}$

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(un)stability test with 10 matrices & n = 25 or 2 matrices & n = 100 intractable with the dense JSR

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(un)stability test with 10 matrices & n=25 or 2 matrices & n=100 intractable with the dense JSR \checkmark takes less than 10 seconds with the Sparse JSR!

Sparse SDP

Correlative sparsity

Term sparsity

Ideal sparsity

Tutorial session

$$f_{\min} = \inf\{f(x_1, x_2) : x_1 x_2 = 0\}$$

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Theorem [Korda-Laurent-Magron-Steenkamp '22]

Ideal-sparse hierarchies provide better bounds than the dense ones



ACCURACY

Given a symmetric nonnegative matrix A, find the smallest r_+ s.t.

$$A = \sum_{\ell=1}^{r_+} a_\ell a_\ell^T \qquad \text{for } a_\ell \geqslant 0$$

 r_{+} is called the completely positive rank

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hard to compute

✓ Relax/convexify with a linear program over measures

$$r_+\geqslant\inf_{\mu}\{\int_{K_A}1d\mu:\int_{K_A}x_ix_jd\mu=A_{ij}\;(i,j\in V)\,,\quad \mathrm{supp}(\mu)\subseteq K_A\}$$

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- x hard to compute
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$$r_{+} \geqslant \inf_{\mu} \left\{ \int_{K_{A}} 1d\mu : \int_{K_{A}} x_{i}x_{j}d\mu = A_{ij} \ (i, j \in V) , \quad \operatorname{supp}(\mu) \subseteq K_{A} \right\}$$

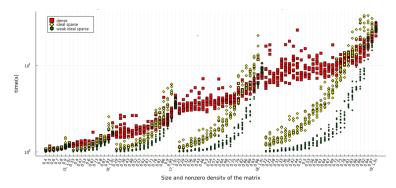
$$X_{+} = \left\{ x : \sqrt{A_{ij}}x_{i} - x_{i} \ge 0 , \quad A_{ij} - x_{ij} \ge 0 , (i, i) \in F_{A} \right\}$$

$$K_A = \{ \mathbf{x} : \sqrt{A_{ii}} x_i - x_i \geqslant 0, \quad A_{ij} - x_i x_j \geqslant 0 \ (i,j) \in E_A,$$

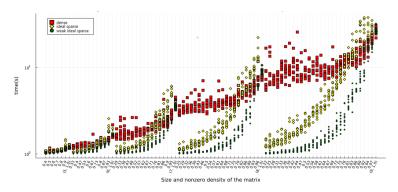
$$x_i x_j = 0 \ (i,j) \in \overline{E}_A, \quad A - \mathbf{x} \mathbf{x}^T \succcurlyeq 0 \}$$

Random instances, order 2

Random instances, order 2



Random instances, order 2



PERFORMANCE



AND



ACCURACY

Sparsity exploiting converging hierarchies to minimize polynomials, eigenvalue/trace, joint spectral radii

SPARSITY EXPLOITING CONVERGING HIERARCHIES to minimize polynomials, eigenvalue/trace, joint spectral radii

FAST IMPLEMENTATION IN JULIA: TSSOS, NCTSSOS, SparseJSR

Sparsity exploiting converging hierarchies to minimize polynomials, eigenvalue/trace, joint spectral radii

FAST IMPLEMENTATION IN JULIA: TSSOS, NCTSSOS, SparseJSR

 $\overset{\smile}{V}$ Combine correlative & term sparsity for problems with $n=10^3$

SPARSITY EXPLOITING CONVERGING HIERARCHIES to minimize polynomials, eigenvalue/trace, joint spectral radii

FAST IMPLEMENTATION IN JULIA: TSSOS, NCTSSOS, SparseJSR

 \tilde{V} Combine correlative & term sparsity for problems with $n=10^3$



Correlative sparsity: Convergence rate?



Correlative sparsity: Convergence rate?



Term sparsity: Smart solution extraction?

Correlative sparsity: Convergence rate?



Term sparsity: Smart solution extraction?

Ideal sparsity: tensor (nonnegative, symmetric) ranks?

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Numerical conditioning of sparse SDP?

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Combination with symmetries?

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Term sparsity: Smart solution extraction?

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Numerical conditioning of sparse SDP?

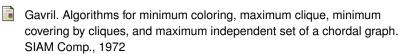
Combination with symmetries?

Tons of applications!

Thank you for your attention!

https://homepages.laas.fr/vmagron

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Sparse SDF

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Term sparsity

Ideal sparsity

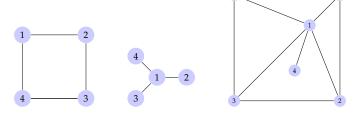
Tutorial session

Newton polytope

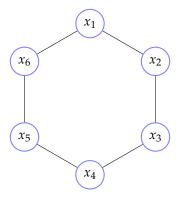
Motzkin
$$f = x_1^4 x_2^2 + x_1^2 x_2^4 - 3x_1^2 x_2^2 + 1$$

- Compute the Newton polytope of f
- 2 Show that f is not SOS

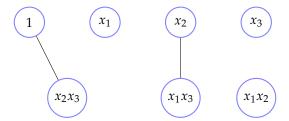
Chordal or not chordal?



Chordal extension



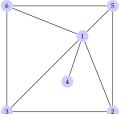
Support extension



How big is CS?

$$f(\mathbf{x}) = x_2 x_5 + x_3 x_6 - x_2 x_3 - x_5 x_6 + x_1 (-x_1 + x_2 + x_3 - x_4 + x_5 + x_6)$$

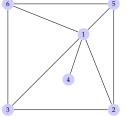
Chordal graph after adding edge (3,5)



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How many SDP variables in the dense and sparse relaxation at order r = 1, 2, 3?

Moment matrix

Write the first (correlative) sparse moment relaxation of

$$\inf_{\mathbf{x}} \quad x_1 x_2 + x_1 x_3 + x_1 x_4$$

s.t.
$$x_1^2 + x_2^2 \leqslant 1$$
$$x_1^2 + x_3^2 \leqslant 1$$
$$x_1^2 + x_4^2 \leqslant 1$$

Measure LP preserves sparsity

 $f = f_1 + f_2$, f_k depends on I_k , X compact & each g_j depends either on I_1 or I_2 .

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$$f_{\min} = \inf_{\mu \in \mathcal{M}_{+}(\mathbf{X})} \int_{\mathbf{X}} f \, d\mu = f_{\text{CS}} = \inf_{\mu_{1}, \mu_{2}} \quad \int_{\mathbf{X}_{1}} f_{1} \, d\mu_{1} + \int_{\mathbf{X}_{2}} f_{2} \, d\mu_{2}$$
s.t.
$$\pi_{12}\mu_{1} = \pi_{21}\mu_{2}$$

$$\mu_{1} \in \mathcal{M}_{+}(\mathbf{X}_{1}), \quad \mu_{2} \in \mathcal{M}_{+}(\mathbf{X}_{2})$$

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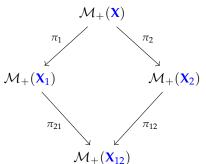
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 \bigvee (μ_k) feasible for $f_{cs} \implies \exists \mu \in \mathcal{M}_+(\mathbf{X})$ with marginal μ_k on \mathbf{X}_k



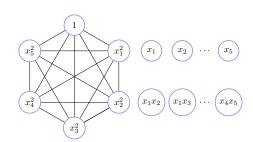
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🏋 **tsp** graph G



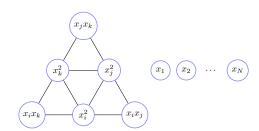
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Compute the dense relaxation f^2 Compare with the correlative sparse relaxation $f_{\rm cs}^2$ Compare with the term sparse relaxation $f_{\rm ts}^{2,s}$ for $s=1,2,\ldots$

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¥ Install and run TSSOS:

] add https://github.com/wangjie212/TSSOS using TSSOS, DynamicPolynomials

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```

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dense2,sol,data=cs_tssos_first([f], x, 2,
CS=false,TS=false);
```

$$f = f_1 + f_2$$
 $\mathbb{B}_{nc} = \{x : 1 - x_1^2 - x_2^2 - x_3^2 \succcurlyeq 0, 1 - x_2^2 - x_3^2 - x_4^2 \succcurlyeq 0\}$

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```
cs_nctssos_first([f;ncball],x,2,CS=false, TS=false,
obj="eigen");
```

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