

Exploiting sparsity in polynomial optimization Victor Magron

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Victor Magron LAAS CNRS

https://homepages.laas.fr/vmagron/SparsePOPJNCF23.pdf

Journées Nationales de Calcul Formel 6-10 March 2023





Looks like a regular polynomial optimization problem (POP):

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$$f(\mathbf{x})$$

s.t. $\mathbf{x} \in \mathbf{X} = {\mathbf{x} \in \mathbb{R}^n : g_j(\mathbf{x}) \ge 0}$

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PERFORMANCE



ACCURACY

Victor Magron

Exploiting sparsity in polynomial optimization

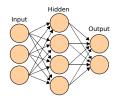
1 - 2 - 3 ----- 99 - 100

Everywhere (almost)!

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Deep learning

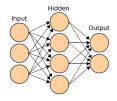
 \rightsquigarrow robustness, computer vision



Everywhere (almost)!

Deep learning

→ robustness, computer vision



Power systems

~ AC optimal power-flow, stability



Everywhere (almost)!

Deep learning

~> robustness, computer vision

Power systems

~ AC optimal power-flow, stability

Quantum Systems

→ condensed matter, entanglement





Hidden

Output

Input

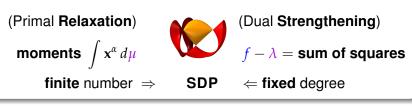






NP-hard NON CONVEX Problem $f_{\min} = \inf f(\mathbf{x})$

Practice



LASSERRE'S HIERARCHY of **CONVEX PROBLEMS** $\uparrow f_{min}$ [Lasserre '01]

degree r & n vars $\implies \binom{n+2r}{n}$ SDP variables



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HOW TO OVERCOME THIS NO-FREE LUNCH RULE?

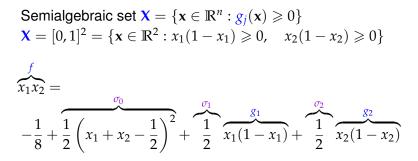
NP hard General Problem: $f_{\min} := \min_{\mathbf{x} \in \mathbf{X}} f(\mathbf{x})$

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Semialgebraic set $\mathbf{X} = \{\mathbf{x} \in \mathbb{R}^n : g_j(\mathbf{x}) \ge 0\}$ $\mathbf{X} = [0, 1]^2 = \{\mathbf{x} \in \mathbb{R}^2 : x_1(1 - x_1) \ge 0, \quad x_2(1 - x_2) \ge 0\}$

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Sums of squares (SOS) σ_i

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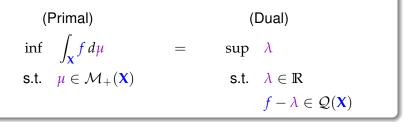
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Sums of squares (SOS) σ_i

Quadratic module:
$$\mathcal{M}(\mathbf{X})_r = \left\{ \sigma_0 + \sum_j \sigma_j g_j, \deg \sigma_j g_j \leqslant 2r \right\}$$

NP-hard NON CONVEX Problem $f_{\min} = \inf_{\mathbf{x} \in \mathbf{X}} f(\mathbf{x})$ **space** $\mathcal{M}_+(\mathbf{X})$ of probability measures supported on \mathbf{X} **quadratic module** $\mathcal{Q}(\mathbf{X}) = \left\{ \sigma_0 + \sum_i \sigma_i g_i, \text{ with } \sigma_i \text{ SOS } \right\}$

Infinite-dimensional linear programs (LP)



NP-hard NON CONVEX Problem $f_{\min} = \inf_{\mathbf{x} \in \mathbf{X}} f(\mathbf{x})$

- Pseudo-moment sequences y up to order r
- Truncated quadratic module $Q(\mathbf{X})_r$

Finite-dimensional semidefinite programs (SDP)

(Moment) (SOS)
inf
$$\sum_{\alpha} f_{\alpha} y_{\alpha} = \sup \lambda$$

s.t. $\mathbf{M}_{r-r_j}(g_j \mathbf{y}) \succeq 0$ s.t. $\lambda \in \mathbb{R}$
 $y_0 = 1$ $f - \lambda \in \mathcal{Q}(\mathbf{X})_r$

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Primal-dual "SPARSE" variants?

Sparse SDP

Correlative sparsity

Term sparsity

Ideal sparsity

Tutorial session

Sparse SDP

Correlative sparsity

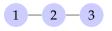
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Tutorial session

Symmetric matrices indexed by graph vertices

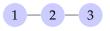
Symmetric matrices indexed by graph vertices





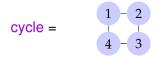
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Symmetric matrices indexed by graph vertices





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cycle =
$$\begin{pmatrix} 1 & -2 \\ -4 & -3 \end{pmatrix}$$

chord = edge between two nonconsecutive vertices in a cycle

Symmetric matrices indexed by graph vertices

1 - 2 - 3



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chordal graph = all cycles of length \ge 4 have at least one chord

clique = a fully connected subset of vertices



Chordal extensions



Chordal extensions



Fact

Any non-chordal graph can always be extended to a chordal graph, by adding appropriate edges

Chordal extensions



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Any non-chordal graph can always be extended to a chordal graph, by adding appropriate edges

V Chordal extension is not unique!

Chordal extensions



Fact

Any non-chordal graph can always be extended to a chordal graph, by adding appropriate edges





approximately minimal



maximal

Theorem [Gavril '72, Vandenberghe & Andersen '15]

The maximal cliques of a chordal graph can be enumerated in linear time in the number of nodes and edges.

RIP Theorem for chordal graphs [Blair & Peyton '93]

For a chordal graph with maximal cliques I_1, \ldots, I_p :

$$(\mathsf{RIP}) \quad \forall k$$

(possibly after reordering)

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♥ RIP holds for chains 1 - 2 - 3 ----- 99 - 100

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V RIP holds for numerous applications!

Semidefinite Programming (SDP)

$$\min_{\mathbf{y}} \quad \mathbf{c}^{\top} \mathbf{y} \\ \mathbf{s.t.} \quad \sum_{i} \mathbf{F}_{i} y_{i} \succeq \mathbf{F}_{0}$$

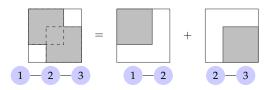


- Linear cost c
- Symmetric matrices F₀, F_i
- Linear matrix inequalities "F ≽ 0" (F has nonnegative eigenvalues)

Spectrahedron

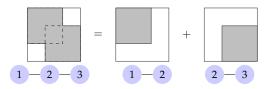
Theorem [Griewank Toint '84, Agler et al. '88]

Chordal graph *G* with *n* vertices & maximal cliques I_1 , I_2 $Q_G \ge 0$ with nonzero entries corresponding to edges of *G* $\implies Q_G = P_1^T Q_1 P_1 + P_2^T Q_2 P_2$ with $Q_k \ge 0$ indexed by I_k



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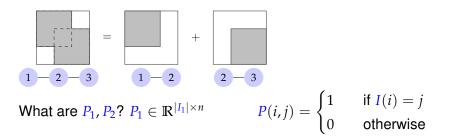
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What are P_1, P_2 ?

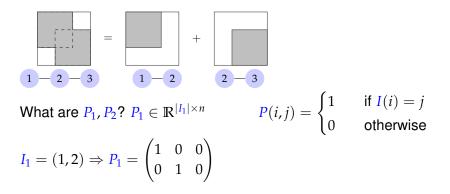
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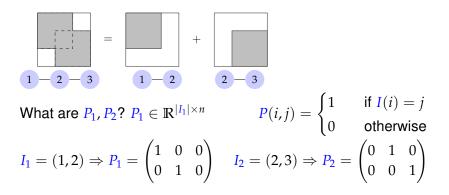
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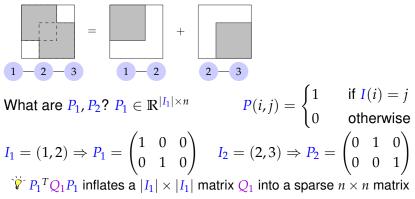
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Exploiting sparsity in polynomial optimization

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Victor Magron

Exploiting sparsity in polynomial optimization

Sparse SDP

Correlative sparsity

Term sparsity

Ideal sparsity

Tutorial session

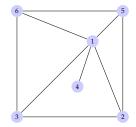
Y Exploit few links between variables [Lasserre, Waki et al. '06]

$$f(\mathbf{x}) = x_2 x_5 + x_3 x_6 - x_2 x_3 - x_5 x_6 + x_1 (-x_1 + x_2 + x_3 - x_4 + x_5 + x_6)$$

Correlative sparsity pattern (csp) graph G

Vertices =
$$\{1, \ldots, n\}$$

$$(i, j) \in \mathsf{Edges} \iff x_i x_j$$
 appears in f



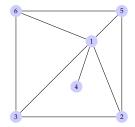
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Similar construction with constraints $\mathbf{X} = {\mathbf{x} \in \mathbb{R}^n : g_j(\mathbf{x}) \ge 0}$

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Chordal graph after adding edge (3,5)

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Chordal graph after adding edge (3,5)
maximal cliques $I_1 = \{1,4\}$ $I_2 = \{1,2,3,5\}$ $I_3 = \{1,3,5,6\}$

 $f = f_1 + f_2 + f_3$ where f_k involves **only** variables in I_k

 \overleftarrow{V} Let us index moment matrices and SOS with the cliques I_k

A sparse variant of Putinar's Positivstellensatz

Convergence of the Moment-SOS hierarchy is based on:

Theorem [Putinar '93] Positivstellensatz

If **X** contains a ball constraint $N - \sum_i x_i^2 \ge 0$ then

$$f > 0$$
 on $\mathbf{X} = {\mathbf{x} : g_j(\mathbf{x}) \ge 0} \implies f = \sigma_0 + \sum_j \sigma_j g_j$ with σ_j SOS

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Theorem: Sparse Putinar's representation [Lasserre '06]

$$f = \sum_{k} f_{k}, f_{k} \text{ depends on } \mathbf{x}(I_{k})$$

$$f > 0 \text{ on } \mathbf{X}$$
Each g_{j} depends on some I_{k}
RIP holds for (I_{k})
ball constraints for each $\mathbf{x}(I_{k})$

$$\implies \begin{cases} f = \sum_{k} (\sigma_{0k} + \sum_{j \in J_{k}} \sigma_{j}g_{j}) \\ \text{SOS } \sigma_{0k} \text{ "sees" vars in } I_{k} \\ \sigma_{j} \text{ "sees" vars from } g_{j} \end{cases}$$

A first key message

🕅 SUMS OF SQUARES PRESERVE SPARSITY

Victor Magron

Exploiting sparsity in polynomial optimization

Let $\mathbf{X} = {\mathbf{x} : g_j(\mathbf{x}) \ge 0}$ be compact and $f = \sum_k f_k$, with f_k depends on $\mathbf{x}(I_k)$, and f > 0 on \mathbf{X}

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 $\mathbf{X}_k = {\mathbf{x}(I_k) : g_j(\mathbf{x}) \ge 0 : j \in J_k}$ = the subspace of \mathbf{X} which only "sees" variables indexed by I_k

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Lemma [Grimm et al. '07]

If RIP holds for (I_k) then $f = \sum_k h_k$, with h_k depends on $\mathbf{x}(I_k)$, and $h_k > 0$ on \mathbf{X}_k

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If RIP holds for (I_k) then $f = \sum_k h_k$, with h_k depends on $\mathbf{x}(I_k)$, and $h_k > 0$ on \mathbf{X}_k

\overleftarrow{V} Prove this lemma by induction on the number of subsets I_k

Let $\mathbf{X} = {\mathbf{x} : g_j(\mathbf{x}) \ge 0}$ be compact and $f = \sum_k f_k$, with f_k depends on $\mathbf{x}(I_k)$, and f > 0 on \mathbf{X}

 $\mathbf{X}_k = {\mathbf{x}(I_k) : g_j(\mathbf{x}) \ge 0 : j \in J_k}$ = the subspace of \mathbf{X} which only "sees" variables indexed by I_k

Lemma [Grimm et al. '07]

If RIP holds for (I_k) then $f = \sum_k h_k$, with h_k depends on $\mathbf{x}(I_k)$, and $h_k > 0$ on \mathbf{X}_k

 \overleftarrow{V} Prove this lemma by induction on the number of subsets I_k

\overleftarrow{v} Then apply Putinar to each h_k

For each subset I_k , submatrix of $M_r(y)$ corresponding of rows & columns indexed by monomials in $x(I_k)$

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$$I_1 = \{1, 4\} \implies \text{monomials in } x_1, x_4$$

$$\mathbf{M}_1(\mathbf{y}, I_1) = \begin{pmatrix} 1 & \mid y_{1,0,0,0,0,0} & y_{0,0,0,1,0,0} \\ & - & - & - \\ y_{1,0,0,0,0,0} & \mid y_{2,0,0,0,0,0} & y_{1,0,0,1,0,0} \\ y_{0,0,0,1,0,0} & \mid y_{1,0,0,1,0,0} & y_{0,0,0,2,0,0} \end{pmatrix}$$

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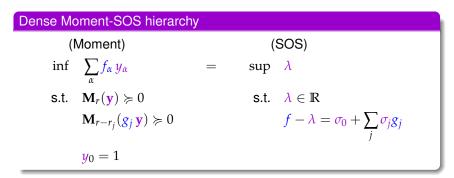
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 \forall same for each localizing matrix $\mathbf{M}_r(g_j \mathbf{y})$

Sparse primal-dual Moment-SOS hierarchy

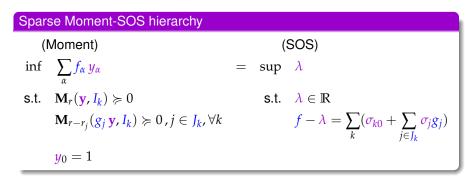
$$f_{\min} = \inf_{\mathbf{x} \in \mathbf{X}} f(\mathbf{x}) \text{ with } \mathbf{X} = \{\mathbf{x} : g_j(\mathbf{x}) \ge 0\}$$



Exploiting sparsity in polynomial optimization

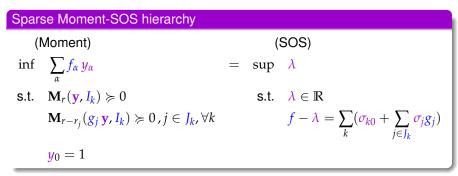
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RIP holds for (I_k) + ball constraints for each $\mathbf{x}(I_k) \implies$ Primal and dual optimal value converge to f_{\min} by sparse Putinar

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Exploiting sparsity in polynomial optimization

Computational cost

$$f_{\min} = \inf_{\mathbf{x} \in \mathbf{X}} f(\mathbf{x}) \text{ with } \mathbf{X} = \{\mathbf{x} : g_j(\mathbf{x}) \ge 0, j \le m\}$$

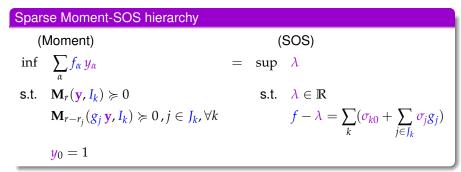
$$\tau = \max\{|I_1|, \dots, |I_p|\}$$

Sparse Moment-SOS hierarchy				
(Moment)		(SOS)		SOS)
inf	$\sum_{\alpha} f_{\alpha} y_{\alpha}$	=	sup	λ
s.t.	$\mathbf{M}_r(\mathbf{y}, \mathbf{I}_k) \succcurlyeq 0$		s.t.	$\lambda \in \mathbb{R}$
	$\mathbf{M}_{r-r_j}(g_j \mathbf{y}, I_k) \succcurlyeq 0, j \in J_k, \forall k$			$f - \lambda = \sum_{k} (\sigma_{k0} + \sum_{j \in J_k} \sigma_j g_j)$
	$y_0 = 1$			

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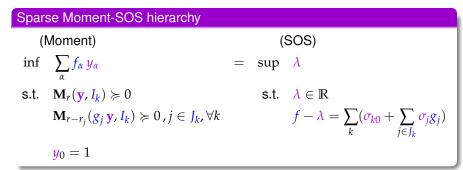


(m+p) SOS in at most τ vars of degree $\leq 2r$

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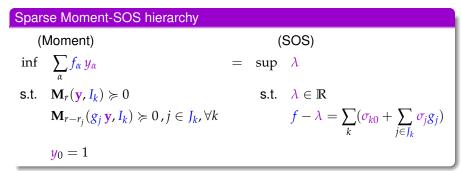


(m + p) SOS in at most τ vars of degree $\leq 2r$ $\bigvee (m + p) O(r^{\tau})$ SDP vars

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(m + p) SOS in at most τ vars of degree $\leq 2r$ $\overleftrightarrow{}(m + p) \mathcal{O}(r^{\tau})$ SDP vars vs $(m + 1) \mathcal{O}(r^{n})$ in the dense SDP

In the dense setting:

$$f_{\min} = \inf_{\mu} \int_{\mathbf{X}} f \, d\mu$$

s.t. $\mu \in \mathcal{M}_{+}(\mathbf{X})$

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Sparse moment SDPs relax the sparse LP over measures:

$$f_{cs} = \inf_{\mu_k} \sum_k \int_{\mathbf{X}_k} f_k \, d\mu_k$$

s.t. $\pi_{jk} \mu_j = \pi_{kj} \mu_k$, $\mu_k \in \mathcal{M}_+(\mathbf{X}_k)$

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Exploiting sparsity in polynomial optimization

The dual of sparse Putinar's Positivstellensatz

Theorem [Lasserre '06]

RIP holds for
$$(I_k) \implies f_{\min} = f_{cs} = \inf_{\mu_k} \sum_k \int_{\mathbf{X}_k} f_k d\mu_k$$

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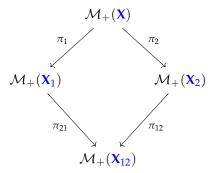
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 \overleftarrow{V} Proof: there exists $\mu \in \mathcal{M}_+(\mathbf{X})$ with marginal μ_k on \mathbf{X}_k



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Exploiting sparsity in polynomial optimization

A first (dual) key message

V THE MEASURE LP PRESERVES SPARSITY **V**

Let r_{\min} be the minimal relaxation order.

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Theorem: dense extraction [Lasserre & Henrion '05]

Assume that the moment SDP has an optimal solution \mathbf{y} with cost f^r and

$$\operatorname{rank} \mathbf{M}_{r'}(\mathbf{y}) = \operatorname{rank} \mathbf{M}_{r'-r_{\min}}(\mathbf{y})$$
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Then $f^r = f_{\min}$ and the LP over measures has an optimal solution $\mu \in \mathcal{M}_+(\mathbf{X})$ supported on $t = \operatorname{rank} \mathbf{M}_{r'}(\mathbf{y})$ points of \mathbf{X} .

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Extraction possible with the Gloptipoly software

 $a_k = \max_{i \in I_k} r_i$ = max half degree of g_i depending on I_k .

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Theorem: sparse extraction [Lasserre '06]

Assume that the sparse moment SDP has an optimal solution ${\bf y}$ with cost $f_{\rm CS}^r$ and

rank
$$\mathbf{M}_r(\mathbf{y}, \mathbf{I}_k) = \operatorname{rank} \mathbf{M}_{r-a_k}(\mathbf{y}, \mathbf{I}_k)$$

rank $\mathbf{M}_r(\mathbf{y}, \mathbf{I}_k \cap \mathbf{I}_j) = 1$

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V RIP is not required! **V** Extract $\mathbf{x}(k)$ from $\mathbf{M}_r(\mathbf{y}, \mathbf{I}_k) \implies$ minimizer \mathbf{x} with $(x_i)_{i \in I_k} = \mathbf{x}(k)$

Application to rational functions

$$f_{\min} = \inf_{\mathbf{x} \in \mathbf{X}} \sum_{i} \frac{p_i(\mathbf{x})}{q_i(\mathbf{x})}, \quad q_i > 0 \text{ on } \mathbf{X}, \quad p_i, q_i \text{ depends only on } I_i$$

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Theorem: dense measure LP [Bugarin et al. '16]

$$f_{\min} = \inf_{\substack{\mu_i \in \mathcal{M}_+(\mathbf{X}) \\ \mathbf{S.t.}}} \sum_i \int_{\mathbf{X}} p_i \, d\mu_i$$

s.t.
$$\int_{\mathbf{X}} \mathbf{x}^{\alpha} \, q_i \, d\mu_i = \int_{\mathbf{X}} \mathbf{x}^{\alpha} \, q_1 \, d\mu_1, \, \alpha \in \mathbb{N}^n$$
$$\int_{\mathbf{X}} q_1 \, d\mu_1 = 1$$

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[Magron Constantinides Donaldson '17]

Exact $f(\mathbf{x}) = x_1 x_2 + x_3 x_4$

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Exact $f(\mathbf{x}) = x_1 x_2 + x_3 x_4$ Floating-point $\hat{f}(\mathbf{x}, \mathbf{e}) = [x_1 x_2 (1 + e_1) + x_3 x_4 (1 + e_2)](1 + e_3)$

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1: Error $f(\mathbf{x}) - \hat{f}(\mathbf{x}, \mathbf{e}) = \ell(\mathbf{x}, \mathbf{e}) + h(\mathbf{x}, \mathbf{e}), \ell$ linear in e

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- 2: Bound $h(\mathbf{x}, \mathbf{e})$ with interval arithmetic
- 3: Bound $\ell(x, e)$ with SPARSE SUMS OF SQUARES

$$\forall I_k \to {\mathbf{x}, e_k} \implies \boxed{m r^{n+1} \text{ instead of } r^{n+m}}$$
 SDP vars

$$\begin{aligned} f &= x_2 x_5 + x_3 x_6 - x_2 x_3 - x_5 x_6 + x_1 (-x_1 + x_2 + x_3 - x_4 + x_5 + x_6) \\ \mathbf{x} &\in [4.00, 6.36]^6, \quad \mathbf{e} \in [-\epsilon, \epsilon]^{15}, \quad \epsilon = 2^{-53} \end{aligned}$$

Dense SDP: $\binom{6+15+4}{6+15} = 12650$ variables \rightsquigarrow Out of memory

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$$f = x_2 x_5 + x_3 x_6 - x_2 x_3 - x_5 x_6 + x_1 (-x_1 + x_2 + x_3 - x_4 + x_5 + x_6)$$
$$\mathbf{x} \in [4.00, 6.36]^6, \quad \mathbf{e} \in [-\epsilon, \epsilon]^{15}, \quad \epsilon = 2^{-53}$$

Dense SDP: $\binom{6+15+4}{6+15}$ = 12650 variables \sim Out of memory

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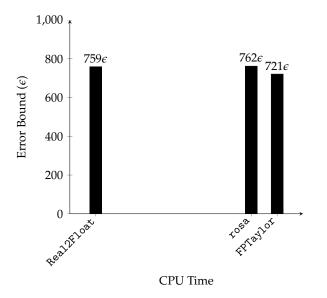
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SMT-based rosa tool: 762ϵ (19 × more CPU)

Victor Magron

Exploiting sparsity in polynomial optimization



Exploiting sparsity in polynomial optimization

Extension to noncommutative optimization

Self-adjoint noncommutative variables $a_i, b_j \in \mathcal{B}(\mathcal{H})$

$$f = a_1(b_1 + b_2 + b_3) + a_2(b_1 + b_2 - b_3) + a_3(b_1 - b_2) - b_1 - 2b_1 - b_2$$

with $a_1 a_2 \neq a_2 a_1$, involution $(a_1 b_3)^* = b_3 a_1$

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Constraints
$$\mathbf{X} = \{(a, b) : a_i^2 = a_i, b_j^2 = b_j, a_i b_j = b_j a_i\}$$

Extension to noncommutative optimization

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Constraints $\mathbf{X} = \{(a, b) : a_i^2 = a_i, b_j^2 = b_j, a_i b_j = b_j a_i\}$

MINIMAL EIGENVALUE OPTIMIZATION

$$\lambda_{\min} = \inf \left\{ \langle f(a,b)\mathbf{v}, \mathbf{v} \rangle : (a,b) \in \mathbf{X}, \|\mathbf{v}\| = 1 \right\}$$

Self-adjoint noncommutative variables $a_i, b_j \in \mathcal{B}(\mathcal{H})$

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= sup λ
s.t. $f(a,b) - \lambda \mathbf{I} \succeq 0, \quad \forall (a,b) \in \mathbf{X}$

Ball constraint $N - \sum_i x_i^2 \succeq 0$ in **X**

Theorem: NC Putinar's representation [Helton & McCullough '02]

$$f \succ 0 \text{ on } \mathbf{X} \implies f = \sum_{i} s_{i}^{\star} s_{i} + \sum_{j} \sum_{i} t_{ji}^{\star} g_{j} t_{ji}$$
 with $s_{i}, t_{ji} \in \mathbb{R} \langle \underline{x} \rangle$

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NC variant of Lasserre's Hierarchy for λ_{min} :

$$\forall$$
 replace " $f - \lambda \mathbf{I} \succeq 0$ on **X**" by $f - \lambda \mathbf{I} = \sum_{i} s_{i}^{*} s_{i} + \sum_{j} \sum_{i} t_{ji}^{*} g_{j} t_{ji}$
with s_{i} , t_{ji} of **bounded** degrees = SDP **V**

Self-adjoint noncommutative (NC) variables $x = (x_1, ..., x_n)$

Theorem [Helton & McCullough '02]

 $f \succcurlyeq 0 \Leftrightarrow f$ SOS (all positive polynomials are sums of squares)

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Theorem: Sparse NC Positivstellensatz [Klep Magron Povh '21]

 $\begin{array}{c|c} f = \sum_{k} f_{k}, f_{k} \text{ depends on } x(I_{k}) \\ f > 0 \text{ on } \{ \mathbf{x} : g_{j}(\mathbf{x}) \ge 0 \} \\ \text{chordal graph with cliques } I_{k} \implies \\ \text{ball constraints for each } x(I_{k}) \qquad \\ t_{ji} \text{ "} \end{array}$

$$f = \sum_{k,i} (s_{ki}^{\star} s_{ki} + \sum_{j \in J_k} t_{ji}^{\star} g_j t_{ji})$$

$$\overline{s_{ki}} \text{ "sees" vars in } I_k$$

$$t_{ji} \text{ "sees" vars from } g_j$$

I₃₃₂₂ Bell inequality (entanglement in quantum information)

 $f = a_1(b_1 + b_2 + b_3) + a_2(b_1 + b_2 - b_3) + a_3(b_1 - b_2) - a_1 - 2b_1 - b_2$

Maximal violation levels \rightarrow **upper bounds** on λ_{\max} of f on $\{a, b : a_i^2 = a_i \quad b_i^2 = b_i \quad a_i b_j = b_j a_i\}$

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level	sparse
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dense [Pál & Vértesi '18] 0.2509397

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2	0.2550008	0.2509397
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3'		0.25087 <mark>54</mark> (<mark>1 day</mark>)
4	0.2508917	

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dense [Pál & Vértesi '1
0.2509397
0.2508756
0.25087 <mark>54</mark> (1 day)

5 0.25087<mark>63</mark>

8]

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level sparse dense [Pál & Vértesi '18] 2 0.2550008 0.2509397 3 0.2511592 0.2508756 3' 0.2508754 (1 day) 4 0.2508917 5 0.2508763 6 0.2508753977180 (1 hour) vs PERFORMANCE ACCURACY

Exploiting sparsity in polynomial optimization

Application to SOS of bounded degrees

Theorem: sparse BSOS representation [Weisser et al. '18]

If $0 \leq g_j \leq 1$ on **X**, f > 0 on **X** & RIP holds for (I_k) then

$$f = \sum_{k} \left(\sigma_k + \sum_{lpha,eta} c_{k,lphaeta} \prod_{j\in J_k} g_j^{lpha_j} (1-g_j)^{eta_j}
ight),$$

with σ_k SOS of degree $\leq 2r$

Application to sparse positive definite forms

Theorem: [Reznick '95] Positivstellensatz

pd form
$$f \implies f = \frac{\sigma}{\|\mathbf{x}\|_2^{2r}}$$
 with σ SOS, $r \in \mathbb{N}$

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Sparse $f \sum_k f_k$, with f_k only depends on I_k RUNNING INTERSECTION PROPERTY (RIP)

$$orall k \quad \underbrace{I_k \cap igcup_{j < k}}_{\hat{I}_k} I_j \subseteq I_{s_k} \quad ext{for some } s_k < k$$

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Theorem: sparse Reznick [Mai Lasserre Magron '20]

$$\mathsf{RIP} \implies \left| f = \sum_{k} \frac{\sigma_{k}}{H_{k}r} \right| \text{ with } \sigma_{k} \text{ SOS only depends on } I_{k}$$

Uniform H_k involve products $||\mathbf{x}(I)||_2^2$ for $I \in \{I_k, \hat{I}_k, \hat{I}_i : s_i = k\}$

Polynomial matrix inequalities [Zheng & Fantuzzi '20]

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Volume computation [Tacchi et al. '21]

Robustness of implicit deep networks [Chen et al. '21]

Sparse SDP

Correlative sparsity

Term sparsity

Ideal sparsity

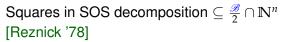
Tutorial session

Term sparsity via Newton polytope

$$f = 4x_1^4x_2^6 + x_1^2 - x_1x_2^2 + x_2^2$$

spt(f) = {(4,6), (2,0), (1,2), (0,2)}

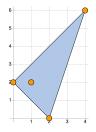
Newton polytope $\mathscr{B} = \operatorname{conv}(\operatorname{spt}(f))$



$$f = \begin{pmatrix} x_1 & x_2 & x_1x_2 & x_1x_2^2 & x_1^2x_2^3 \end{pmatrix} \underbrace{Q}_{\geq 0} \begin{pmatrix} x_1 \\ x_2 \\ x_1x_2 \\ x_1x_2^2 \\ x_1x_2^2 \\ x_1^2x_2^3 \end{pmatrix}$$



Exploiting sparsity in polynomial optimization





$$f = x_1^2 - 2x_1x_2 + 3x_2^2 - 2x_1^2x_2 + 2x_1^2x_2^2 - 2x_2x_3 + 6x_3^2 + 18x_2^2x_3 - 54x_2x_3^2 + 142x_2^2x_3^2$$
[Reznick '78] $\rightarrow f = (1 \quad x_1 \quad x_2 \quad x_3 \quad x_1x_2 \quad x_2x_3) \underbrace{Q}_{\geq 0} \begin{pmatrix} 1 \\ x_1 \\ x_2 \\ x_3 \\ x_1x_2 \\ x_2x_3 \end{pmatrix}$
 $\sim \rightarrow \frac{6 \times 7}{2} = 21$ "unknown" entries in Q

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$$+ 6x_3^2 + 18x_2^2x_3 - 54x_2x_3^2 + 142x_2^2x_3^2$$
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 \rightarrow 6 + 9 = 15 "unknown" entries in $Q_{G'}$

At step r of the hierarchy, tsp graph G has

Nodes V = monomials of degree $\leq r$

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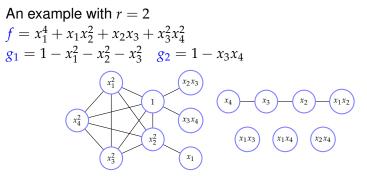
Nodes V = monomials of degree $\leq r$ Edges E with

$$\{\alpha,\beta\}\in E\Leftrightarrow \alpha+\beta\in \operatorname{supp} f\bigcup \operatorname{supp} g_j\bigcup_{|\alpha|\leqslant r}2\alpha$$

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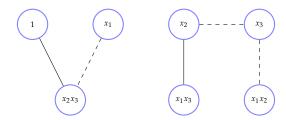
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Exploiting sparsity in polynomial optimization

Term sparsity: support extension

$\alpha' + \beta' = \alpha + \beta$ and $(\alpha, \beta) \in E \Rightarrow (\alpha', \beta') \in E$



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→ support extension

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 \rightsquigarrow support extension \rightsquigarrow chordal extension G'

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 \rightsquigarrow support extension \rightsquigarrow chordal extension G'

By iteratively performing support extension & chordal extension

$$G^{(1)} = G' \subseteq \cdots \subseteq G^{(s)} \subseteq G^{(s+1)} \subseteq \cdots$$

 \bigvee Two-level hierarchy of lower bounds for f_{\min} , indexed by sparse order *s* and relaxation order *r*

Victor Magron

Exploiting sparsity in polynomial optimization

Let G' be a chordal extension of G with maximal cliques (C_i)

 $C_i \mapsto \mathbf{M}_{C_i}(\mathbf{y})$

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$$\overleftarrow{V}$$
 Each constraint $G_j \rightsquigarrow G_j^{(s)} \rightsquigarrow$ cliques $C_{j,i}^{(s)}$

Victor Magron

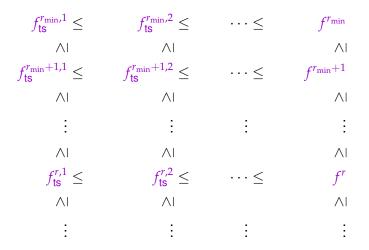
Let $C_{j,i}^{(s)}$ be the maximal cliques of $G_j^{(s)}$. For each $s \ge 1$

$$f_{ts}^{r,s} = \inf \sum_{\alpha} f_{\alpha} y_{\alpha}$$

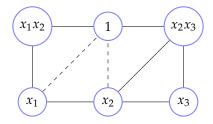
s.t.
$$\mathbf{M}_{C_{0,i}^{(s)}}(\mathbf{y}) \succeq 0$$
$$\mathbf{M}_{C_{j,i}^{(s)}}(g_{j} \mathbf{y}) \succeq 0$$
$$y_{0} = 1$$

V dual yields the TSSOS hierarchy

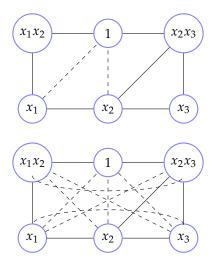
A two-level hierarchy of lower bounds



Different choices of chordal extensions



Different choices of chordal extensions



Theorem [Lasserre Magron Wang '21]

Fixing a sparse order *s*, the sequence $(f_{ts}^{r,s})_{r \ge r_{min}}$ is monotonically non-decreasing.

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 \dot{V} The block structures converge to the one determined by the sign symmetries if the maximal chordal extension and monomial basis are used.

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 $f = 1 + x_1^2 x_2^4 + x_1^4 x_2^2 + x_1^4 x_2^4 - x_1 x_2^2 - 3x_1^2 x_2^2$ Newton polytope $\rightsquigarrow \mathscr{B} = (1 \quad x_1 x_2 \quad x_1 x_2^2 \quad x_1^2 x_2 \quad x_1^2 x_2^2)$

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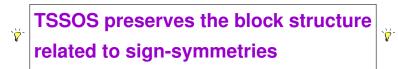
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 $x_2 \mapsto -x_2$ Sign-symmetries blocks $(1 \quad x_1 x_2^2)$ TSSOS blocks $(1 \quad x_1 x_2^2)$

ocks
$$(1 \quad x_1 x_2^2 \quad x_1^2 x_2^2) \quad (x_1 x_2 \quad x_1^2 x_2) \\ (1 \quad x_1 x_2^2 \quad x_1^2 x_2^2) \quad (x_1 x_2) \quad (x_1^2 x_2) \end{cases}$$

Victor Magron

Exploiting sparsity in polynomial optimization



Comparison with (S)DSOS

Let *f* be a nonnegative polynomial of degree 2*d f* is SOS \Leftrightarrow *f* = **v**^{*T*}**Qv** with **Q** \succeq 0 \rightsquigarrow semidefinite program where **v** contains 1, *x*₁,..., *x*_n, *x*₁²,..., *x*_n^{*d*}

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To reduce the number of "unknown" entries in Q, one can force: [Ahmadi & Majumdar '14]

- **1** Q diagonally dominant: $Q_{ii} \ge \sum_{j \neq i} Q_{ij} \rightsquigarrow$ linear program
- 2 Q \sim to a diag. dominant matrix \rightsquigarrow second-order program

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Theorem [Lasserre Magron Wang '21]

The first TSSOS relaxation is always more accurate than the SDSOS relaxation

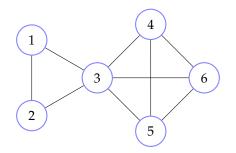
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- \forall a two-level CS-TSSOS hierarchy of lower bounds for f_{\min}

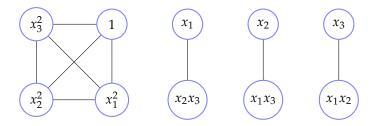
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csp graph



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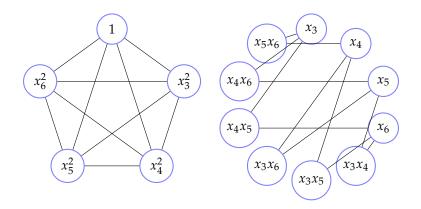
tsp graph for the first clique



Exploiting sparsity in polynomial optimization

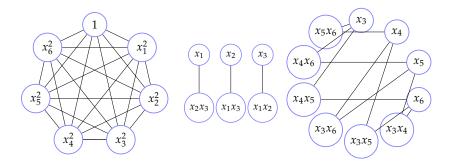
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tsp graph for the second clique

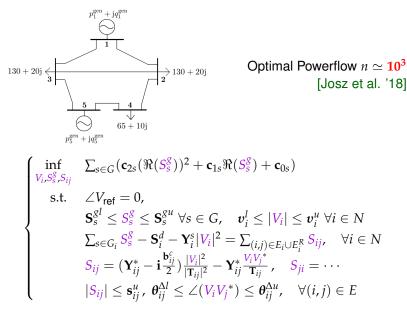


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tsp graph without correlative sparsity



Application to optimal power-flow



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Exploiting sparsity in polynomial optimization

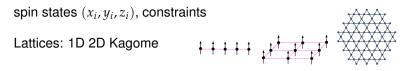
Application to optimal power-flow

mb = the maximal size of blocks m = number of constraints

n	т	CS (<i>r</i> = 2)			CS+TS ($r = 2, s = 1$)		
		mb	time (s)	gap	mb	time (s)	gap
114	315	66	5.59	0.39%	31	2.01	0.73%
348	1809	253	_	_	34	278	0.05%
766	3322	153	585	0.68%	44	33.9	0.77%
1112	4613	496	—	—	31	410	0.25%
4356	18257	378	—	—	27	934	0.51%
6698	29283	1326	—	—	76	1886	0.47%

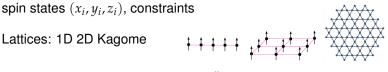
Ground-state energy \Leftrightarrow minimal eigenvalue of an Hamiltonian

$$H = \sum_{\langle i,j \rangle} \left(x_i \, x_j + y_i \, y_j + z_i \, z_j \right)$$



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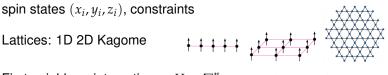
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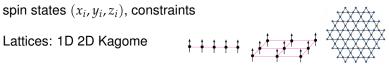


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periodic boundary conditions \Rightarrow n+1=1

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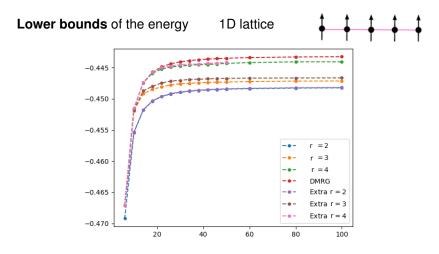
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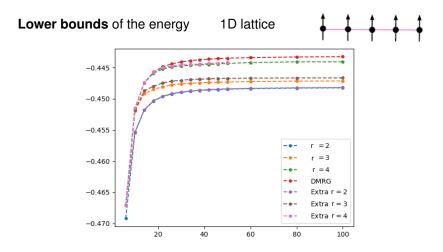
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Existing \pm efficient techniques: quantum Monte Carlo & variational algorithms \Rightarrow **upper bounds** on minimal energy



Dense r = 4, $n = 10^2 \Rightarrow 10^{11}$ variables (solvers handle $\simeq 10^4$)



Dense r = 4, $n = 10^2 \Rightarrow 10^{11}$ variables (solvers handle $\simeq 10^4$) **Sparse** solved within 1 hour on PFCALCUL at LAAS

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Exploiting sparsity in polynomial optimization

CLASSICAL WORLD

$$\psi^*(A_1 \otimes B_1 + A_1 \otimes B_2 + A_2 \otimes B_1 - A_2 \otimes B_2)\psi \leqslant 2$$

for separable states $\psi \in \mathbb{C}^k \otimes \mathbb{C}^k$ and matrices A_j , B_j satisfying $A_j^* = A_j$, $A_j^2 = I$, $B_j^* = B_j$, $B_j^2 = I$

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TSIRELSON'S BOUND: $2 \rightarrow 2\sqrt{2}$ for maximally entangled states $\psi^*(A \otimes B)\psi = \operatorname{tr}(AB)$

$$2\sqrt{2} = \operatorname{tr}_{\max}\{a_1b_1 + a_1b_2 + a_2b_1 - a_2b_2 : a_j^2 = b_j^2 = 1\}$$

COVARIANCES OF QUANTUM CORRELATIONS

$$\operatorname{cov}_{\psi}(A,B) = \psi^*(A \otimes B)\psi - \psi^*(A \otimes I)\psi \cdot \psi^*(I \otimes B)\psi$$

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V 2nd sparse SDP gives also 5 ... 10 times faster

Lyapunov function

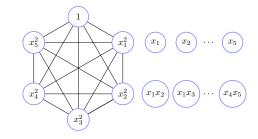
$$f = \sum_{i=1}^{N} a_i (x_i^2 + x_i^4) - \sum_{i,k=1}^{N} b_{ik} x_i^2 x_k^2 \quad a_i \in [1,2] \quad b_{ik} \in [\frac{0.5}{N}, \frac{1.5}{N}]$$

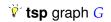
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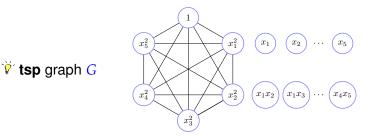




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 $\rightsquigarrow (N+1)^2$ "unknown" entries in $Q_G = 36$ for N = 5

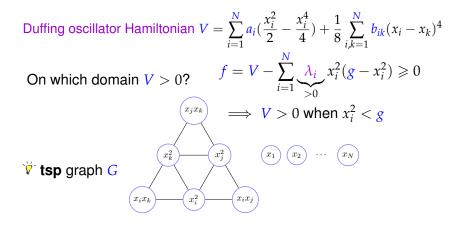
Proof that $f \ge 0$ for N = 80 in ~ 10 seconds!

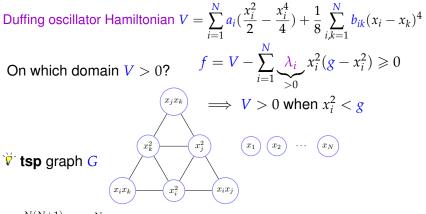
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Exploiting sparsity in polynomial optimization

Duffing oscillator Hamiltonian
$$V = \sum_{i=1}^{N} a_i (\frac{x_i^2}{2} - \frac{x_i^4}{4}) + \frac{1}{8} \sum_{i,k=1}^{N} b_{ik} (x_i - x_k)^4$$

On which domain $V > 0$? $f = V - \sum_{i=1}^{N} \underbrace{\lambda_i}_{>0} x_i^2 (g - x_i^2) \ge 0$
 $\implies V > 0$ when $x_i^2 < g$





 $\sim \frac{N(N+1)}{2} + 6\binom{N}{2} + N$ "unknown" entries in $Q_G = 80$ for N = 5

Proof that $f \ge 0$ for N = 50 in ~ 1 second!

Given $\mathcal{A} = \{A_1, \dots, A_m\} \subseteq \mathbb{R}^{n \times n}$, the JSR is

$$\rho(\mathcal{A}) := \lim_{k \to \infty} \max_{\sigma \in \{1, \dots, m\}^k} ||A_{\sigma_1} A_{\sigma_2} \cdots A_{\sigma_k}||^{\frac{1}{k}}$$

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Tons of applications:

- stability of switched linear systems
- continuity of wavelet functions
- trackability of graphs

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... NP-hard to compute/approximate

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Given $\mathcal{A} = \{A_1, \dots, A_m\} \subseteq \mathbb{R}^{n \times n}$, if a positive definite form f of degree 2r satisfies

 $f(\boldsymbol{A}_i \mathbf{x}) \leqslant \gamma^{2r} f(\mathbf{x}) \quad \forall i, \mathbf{x}$

Then $\rho(\mathcal{A}) \leqslant \gamma$

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$$\begin{split} \tilde{\mathbf{V}} \rho(\mathcal{A}) \leqslant \rho^{r}(\mathcal{A}) &= \inf_{f \in \mathbb{R}[\mathbf{x}]_{2r}, \gamma} \gamma \\ \text{s.t.} \begin{cases} f(\mathbf{x}) - ||\mathbf{x}||_{2}^{2r} \text{ SOS} \\ \gamma^{2r} f(\mathbf{x}) - f(A_{i}\mathbf{x}) \text{ SOS} \end{cases} \end{split}$$

Exploiting sparsity in polynomial optimization

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Bisection on γ + SDP

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Exploiting sparsity in polynomial optimization

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Recursively, $f_{s-1} = \sum_{\alpha \in \mathscr{A}^{(s-1)}} c_{\alpha} \mathbf{x}^{\alpha}$ and

$$\mathscr{A}^{(s)} = \mathscr{A}^{(s-1)} \cup \bigcup_{i} \operatorname{supp}(f_{s-1}(A_{i}\mathbf{x})) \quad \mathscr{A}_{i}^{(s)} = \mathscr{A}^{(s)} \cup \operatorname{supp}(f_{s}(A_{i}\mathbf{x}))$$

Theorem: Sparse JSR [Maggio Magron Wang '21]

$$\begin{split} \tilde{\mathbf{V}}^{r} \rho(\mathcal{A}) \leqslant \rho^{r}(\mathcal{A}) \leqslant \rho^{r,s}(\mathcal{A}) &= \inf_{f \in \mathbb{R}[\mathscr{A}^{(s)}], \gamma} \gamma \\ \text{s.t.} \begin{cases} f(\mathbf{x}) - ||\mathbf{x}||_{2}^{2r} \operatorname{SOS}(\mathscr{A}^{(s)}) \\ \gamma^{2r} f(\mathbf{x}) - f(A_{i}\mathbf{x}) \operatorname{SOS}(\mathscr{A}_{i}^{(s)}) \end{cases} \end{split}$$

Closed-loop system evolves according to either a completed or a missed computation (A_H or A_M): $\mathcal{A} = \{A_H A_M{}^i \mid i < m\}$ Closed-loop system evolves according to either a completed or a missed computation (A_H or A_M): $\mathcal{A} = \{A_H A_M{}^i \mid i < m\}$

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(un)stability test with 10 matrices & n = 25 or 2 matrices & n = 100 intractable with the dense JSR

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(un)stability test with 10 matrices & n = 25 or 2 matrices & n = 100 intractable with the dense JSR V takes less than 10 seconds with the Sparse JSR! Sparse SDP

Correlative sparsity

Term sparsity

Ideal sparsity

Tutorial session

$$f_{\min} = \inf\{f(x_1, x_2) : x_1 x_2 = 0\}$$

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Theorem [Korda-Laurent-Magron-Steenkamp '22]

Ideal-sparse hierarchies provide better bounds than the dense ones



ACCURACY

Victor Magron

Given a symmetric nonnegative matrix A, find the smallest r_+ s.t.

$$A = \sum_{\ell=1}^{r_+} a_\ell a_\ell^T \qquad ext{ for } a_\ell \geqslant 0$$

 r_+ is called the completely positive rank

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X hard to compute

✓ Relax/convexify with a linear program over measures

$$r_{+} \ge \inf_{\mu} \{ \int_{K_{A}} 1d\mu : \int_{K_{A}} x_{i}x_{j}d\mu = A_{ij} \ (i, j \in V) \ , \quad \mathsf{supp}(\mu) \subseteq K_{A} \}$$

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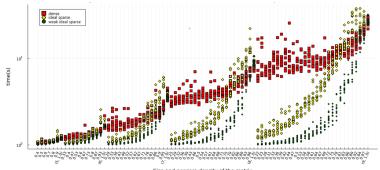
$$\begin{split} K_A &= \{ \mathbf{x} : \sqrt{A_{ii}} x_i - x_i \ge 0, \quad A_{ij} - x_i x_j \ge 0 \ (i,j) \in E_A , \\ x_i x_j &= 0 \ (i,j) \in \overline{E}_A , \quad A - \mathbf{x} \mathbf{x}^T \succcurlyeq 0 \} \end{split}$$

Victor Magron

Exploiting sparsity in polynomial optimization

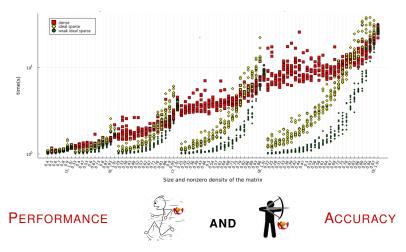
Random instances, order 2

Random instances, order 2



Size and nonzero density of the matrix

Random instances, order 2



Exploiting sparsity in polynomial optimization

SPARSITY EXPLOITING CONVERGING HIERARCHIES to minimize polynomials, eigenvalue/trace, joint spectral radii

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FAST IMPLEMENTATION IN JULIA: TSSOS, NCTSSOS, SparseJSR

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 \checkmark Combine correlative & term sparsity for problems with $n = 10^3$

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FAST IMPLEMENTATION IN JULIA: TSSOS, NCTSSOS, SparseJSR

 \overleftarrow{V} Combine correlative & term sparsity for problems with $n = 10^3$





Term sparsity: Smart solution extraction?





Term sparsity: Smart solution extraction?

Ideal sparsity: tensor (nonnegative, symmetric) ranks?



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Numerical conditioning of sparse SDP?



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Numerical conditioning of sparse SDP?

Combination with symmetries?



Term sparsity: Smart solution extraction?

Ideal sparsity: tensor (nonnegative, symmetric) ranks?

Numerical conditioning of sparse SDP?

Combination with symmetries?

Y Tons of applications!

https://homepages.laas.fr/vmagron

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Sparse SDP

Correlative sparsity

Term sparsity

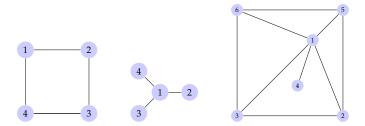
Ideal sparsity

Tutorial session

Motzkin $f = x_1^4 x_2^2 + x_1^2 x_2^4 - 3x_1^2 x_2^2 + 1$

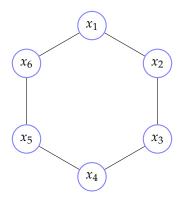
- **1** Compute the Newton polytope of *f*
- **2** Show that f is not SOS

Chordal or not chordal?

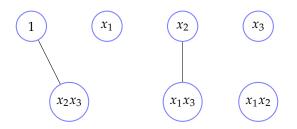


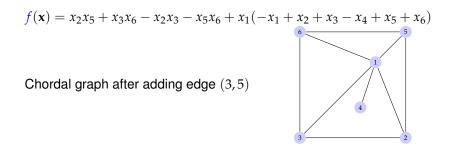
Exploiting sparsity in polynomial optimization

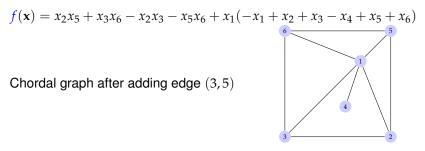
Chordal extension



Support extension







How many SDP variables in the dense and sparse relaxation at order r = 1, 2, 3?

Write the first (correlative) sparse moment relaxation of

$$\inf_{\mathbf{x}} \quad x_1 x_2 + x_1 x_3 + x_1 x_4 \\
\text{s.t.} \quad x_1^2 + x_2^2 \leqslant 1 \\
\quad x_1^2 + x_3^2 \leqslant 1 \\
\quad x_1^2 + x_4^2 \leqslant 1$$

Measure LP preserves sparsity

 $f = f_1 + f_2$, f_k depends on I_k , **X** compact & each g_j depends either on I_1 or I_2 .

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 $f = f_1 + f_2$, f_k depends on I_k , **X** compact & each g_j depends either on I_1 or I_2 . Prove that

$$f_{\min} = \inf_{\mu \in \mathcal{M}_{+}(\mathbf{X})} \int_{\mathbf{X}} f \, d\mu = f_{\text{CS}} = \inf_{\substack{\mu_{1}, \mu_{2} \\ \mu_{1}, \mu_{2} \\ \text{s.t.}} \quad \int_{\mathbf{X}_{1}} f_{1} \, d\mu_{1} + \int_{\mathbf{X}_{2}} f_{2} \, d\mu_{2}$$
$$\text{s.t.} \quad \pi_{12}\mu_{1} = \pi_{21}\mu_{2}$$
$$\mu_{1} \in \mathcal{M}_{+}(\mathbf{X}_{1}), \quad \mu_{2} \in \mathcal{M}_{+}(\mathbf{X}_{2})$$

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 $\forall (u_k)$ feasible for $f_{cs} \implies \exists \mu \in \mathcal{M}_+(\mathbf{X})$ with marginal μ_k on \mathbf{X}_k $\mathcal{M}_+(\mathbf{X})$ π_1 π_2 $\mathcal{M}_{+}(\mathbf{X}_{2})$ $\mathcal{M}_{+}(\mathbf{X}_{1})$ π_{21} π_{12} $\mathcal{M}_{+}(\mathbf{X}_{12})$

Exploiting sparsity in polynomial optimization

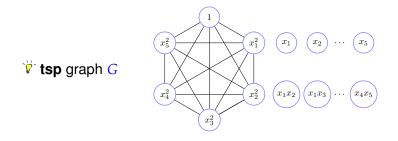
(1/2)

$$f = \sum_{i=1}^{N} (x_i^2 + x_i^4) - \sum_{i,k=1}^{N} x_i^2 x_k^2$$

How many entries in the dense & sparse SOS/moment matrices?

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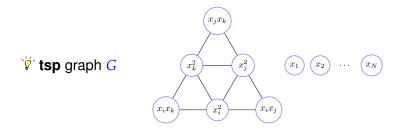
$$f = \sum_{i=1}^{N} \left(\frac{x_i^2}{2} - \frac{x_i^4}{4}\right) + \sum_{i,k=1}^{N} (x_i - x_k)^4$$

How many entries in the dense & sparse SOS/moment matrices?

(2/2)

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Exploiting sparsity in polynomial optimization

$$f_1 = x_1^4 + (x_1x_2 - 1)^2$$
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Compute the dense relaxation f^2 Compare with the correlative sparse relaxation f_{cs}^2 Compare with the term sparse relaxation $f_{ts}^{2,s}$ for s = 1, 2, ... $f_1 = x_1^4 + (x_1x_2 - 1)^2$ $f_2 = x_2^2x_3^2 + (x_3^2 - 1)^2$ $f = f_1 + f_2$

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Y Install and run TSSOS:

] add https://github.com/wangjie212/TSSOS using TSSOS, DynamicPolynomials

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    using TSSOS, DynamicPolynomials
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    dense2,sol,data=cs_tssos_first([f], x, 2,
    CS=false,TS=false);
```

$$f = f_1 + f_2$$
 $\mathbb{B}_{nc} = \{x : 1 - x_1^2 - x_2^2 - x_3^2 \succeq 0, 1 - x_2^2 - x_3^2 - x_4^2 \succeq 0\}$

(2/2)

 $f = f_1 + f_2 \qquad \mathbb{B}_{\mathsf{nc}} = \{ x : 1 - x_1^2 - x_2^2 - x_3^2 \succcurlyeq 0, 1 - x_2^2 - x_3^2 - x_4^2 \succcurlyeq 0 \}$

Compute $\lambda_{\min}(f)$ on \mathbb{B}_{nc} with 2nd dense relaxation

(2/2)

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Compute $\lambda_{\min}(f)$ on \mathbb{B}_{nc} with 2nd dense relaxation

```
cs_nctssos_first([f;ncball],x,2,CS=false, TS=false,
obj="eigen");
```

 $f = f_1 + f_2 \qquad \mathbb{B}_{\mathsf{nc}} = \{ x : 1 - x_1^2 - x_2^2 - x_3^2 \succcurlyeq 0, 1 - x_2^2 - x_3^2 - x_4^2 \succcurlyeq 0 \}$

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