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21 Abstract

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Real-Time Control (RTC) technology is increasingly applied in Rainwater Harvesting (RWH) systems to optimise their performance related to water supply and flood mitigation. However, most studies to date have focussed on testing the benefits at an individual site scale, leaving the potential benefits for downstream stormwater networks largely untested. In this study, we developed a methodology to predict how at-source RTC RWH systems influence the behaviour of a stormwater network. Simulation was enabled by coupling the drainage model in SWMM with an RTC RWH model coded using the R software. We modelled two different RTC strategies across a range of system settings (e.g. storage size for RWH and proportion of storage to which RTC is applied) under two different climate scenarios—current and future climates. The simulations showed that RTC reduced flooding volume and peak flow of the stormwater network, leading to a potential mitigation of urban flooding risks, while also providing a decentralised supplementary water supply. Implementing RTC in more of RWH storages yielded greater benefits than simply increasing storage capacity, in both current and future climates. More importantly, the RTC systems are capable of more precisely managing the resultant flow regime in reducing the erosion and restoring the pre-development conditions in sensitive receiving waters. Our study suggests that RTC RWH storages distributed throughout a catchment can substantially improve the performance of existing drainage systems, potentially avoiding or deferring expensive network upgrades. Investments in real-time control technology would appear to be more promising than investments in detention volume alone.

1. Introduction

Urbanisation creates critical challenges for water management. Water scarcity, caused
by population growth and dwindling freshwater resources, is still a major social and economic
challenge in many cities (Vörösmarty et al., 2010). Urban flooding risks are increased by the
excessive surface runoff and intensified peak flow, which result from increased impervious
areas in conventional stormwater drainage networks (Jongman et al., 2012; Nirupama &
Simonovic, 2006). These conventional stormwater networks, which aim to drain stormwater in
the quickest possible time through hydraulically-efficient infrastructure (e.g. pipes), also
connect impervious runoff directly to the receiving water, grossly altering natural flow regimes
through increased frequency and magnitude of stormwater flow (Bhaskar et al., 2016; Leopold,
1968), along with reduced recession times (Burns et al., 2005) and stream baseflow (Booth &
Jackson, 1997; Price, 2011). Such hydrological changes cause substantial channel erosion
(Hammer, 1972; Russell et al., 2020), habitat loss and ecological degradation in urban streams,
with subsequent reduction in biodiversity and ecosystem services (Bunn & Arthington, 2002;
King et al., 2005; Poff et al., 1997; Walsh et al., 2012).
Rainwater harvesting systems (RWH) are widely used as a traditional source of primary
or supplementary water supply (Gardner & Vieritz, 2010; Mikkelsen et al., 1999; Ward et al.,
2012). They also act as a Stormwater Control Measure (SCM), capturing and storing the runoff
from impervious surfaces (e.g. roofs) which is then diverted to supply household end-uses.
Such a design provides complementary retention to reduce the volume, frequency and peak of
urban runoff, which can reduce stormwater network overflows and mitigate urban flooding
risks (Burns et al., 2015; Jamali et al., 2019; Schubert et al., 2017). Such systems offer benefits
in potentially delaying the upgrade of water supply and drainage infrastructure (Coombes &
Kuczera, 2003), although the extent of benefit depends strongly on their storage capacity and
characteristics of the household water demand (Campisano & Modica, 2016).

Application of Real-time Control (RTC) technology has the potential to enhance RWH performance in relation to both water supply and flood mitigation (Roman et al., 2017; Xu et al., 2020a). Real-time control is a collection of software, sensors, communication devices and actuators (Bennett, 1994), which can be combined to provide RWH systems with digital information (e.g. rainfall forecast) and adapt its operation in real-time in response to operating conditions. Doing so allows RWH systems to evolve from their conventional static nature to highly adaptive (Kerkez et al., 2016). Real-time controlled RWH systems generally release stored rainwater prior to a rainfall event (termed here as 'pre-storm releases'), through a remotely controlled discharge structure, to proactively create sufficient capacity for the predicted inflows, thus minimizing the magnitude and frequency of uncontrolled overflows. A range of modelling and empirical studies have demonstrated that RTC outperforms conventional RWH systems in stormwater retention and peak flow reduction (Gee & Hunt, 2016; Oberascher et al., 2019; Roman et al., 2017), with no meaningful impact on water supply performance (Melville-Shreeve et al., 2016; Xu et al., 2018).

Real-time control application to rainwater has advanced in recent times to include the use of longer rainfall forecast windows. Xu et al. (2020b) modelled three different RTC strategies using a 7-day lead precipitation forecast. They found that increasing the rainfall forecast window, which extends the predictive horizon of the pre-storm releases, resulted in a better attenuation of the peak flow. This approach also reduced overflow frequency and extended the recession time, leading to an RTC outflow regime much closer to that of natural streams (Xu et al., 2020b). Such an approach could potentially counteract the negative hydrologic impacts caused by urbanisation (Leopold, 1968; Poff et al., 2010).

The focus of RTC application to RWH systems, to date, has mainly been on the effectiveness at the land parcel, leaving its impacts on stormwater networks largely untested (Xu et al., 2020a). Understanding whether the benefits gained at each parcel can be

accumulated and translated to a larger scale such as the catchment, is vital to understand the potential cost-effectiveness of RTC RWH systems for adapting to a changing climate. This requires explicit consideration of the behaviour of a distributed network of RTC RWH systems and the hydraulic behaviour of the stormwater network.

In this study, we evaluated the impact of at-source RTC RWH systems on the behaviour of a stormwater network. We adopted two different RTC strategies, to (i) mitigate floods and (ii) deliver a more natural overall flow regime (for further details see Xu et al., 2020b), and modelled their impact on a stormwater network across a range of system settings, under two different climate scenarios (i.e. current and future climates), during a 7-month simulation period. Network flooding volume and peak flow reduction were characterised, with a more detailed analysis on the network outflow regime.

We hypothesised that operating RWH systems using RTC could reduce flooding volume and peak flow for a stormwater network in both current and future climates, which could mitigate the risks of urban flooding, while providing a decentralised supplementary water supply. Our results demonstrated that implementing higher proportions of RTC systems provided larger benefits than simply increasing the storage capacity, potentially avoiding or deferring expensive upgrades for stormwater infrastructure. Our work provides useful insights for application of at-source RTC RWH systems in future smart stormwater management.

2. Methods

To predict the impact of RTC RWH systems on the performance of a stormwater network, we used a modelling approach which combined outputs from a volumetric RTC RWH behaviour model coded in R software (version 4.1; R Core Team, 2021), with the 1-D hydraulic model in the Stormwater Management Model (SWMM version 5.1 executed by PCSWMM 7.4; Rossman, 2015). A similar modelling tool is also available in Python as an integrated library

'pyswmm' (McDonnell et al., 2020). The steps are illustrated in Figure 1 and details are given below. The analysis was undertaken on a stormwater network located in a city in the province of Quebec, in Canada, for which the SWMM model was adapted from Shishegar et al. (2021). RWH systems were assumed to only connect to roofs, while stormwater runoff from other surfaces (e.g. pavement) was conveyed directly to the drainage network.

2.1 RTC Strategies

We adopted two RTC strategies, as per Xu et al. (2020b): Strategy S1 ('Flood Mitigation') was designed to minimise storage overflows and Strategy S2 ('Longest Discharge') was designed to attenuate the flashiness and magnitude of pre-storm releases, to return to a more natural flow regime. In Strategy S1, overflows predicted to occur within the next seven days are released uniformly over the next 24-hr window. In contrast, Strategy S2 aims to achieve the longest possible duration for each pre-storm release (i.e. the pre-storm releases start seven days in advance and finish before the predicted rain). Both RTC strategies are based on 7-day lead rainfall forecast, with the forecast assumed to be perfect (i.e. no forecast error was modelled), as the forecast error has little impact on overall system performance when a 7-day rolling horizon is applied (see more details in section 2.2.2; Shishegar et al., 2021).

2.2 Modelling procedure

A modelling procedure (Figure 1) was developed to test the performance of the proposed RTC system. This procedure includes three different modules: rainfall-runoff module (M1), RTC module (M2) and drainage simulation module (M3). M1 utilises a hydrological model, providing the 6-min catchment runoff and daily runoff forecast as input to M2. M2 generates the outflow from each at-source RTC system using the pre-defined control strategies (as explained in section 2.1), which is then used by M3 to model the flow dynamics in the

stormwater network. M1 and M3 were enabled by SWMM, while M2 was computed by a custom-written RTC algorithm in R software.

2.2.1 M1 Rainfall-Runoff Module

In M1, two distinct runoff sources were generated: the roof runoff, used as the inflow to the RWH system, and the surface runoff from the remaining surfaces of the catchment. Both were simulated by the rainfall-runoff model in SWMM (see more details in section 2.3 Study Catchment) using real rainfall data. Roof runoff was modelled separately from other land uses (i.e. pavement and pervious areas), because the RTC RWH behaviour cannot be implemented directly in SWMM: the prediction and control of the RTC systems were therefore run in the RTC module (M2). Roof areas were obtained by mapping each individual household and were grouped by each catchment boundary (i.e. each catchment had one integrated roof area). The imperviousness of roofs was assumed to be 100% and with a depression storage of 1.5 mm (American Society of Civil Engineers, 1992). The imperviousness of each catchment for other surfaces (e.g. pavement and pervious area) was then recalculated to exclude the area of roof catchment, based on the mapping of the study catchment.

2.2.2 M2 Real-Time Control Module

The RTC module (M2) determines the pre-storm releases through control variables and simulates the performance of RTC systems under different strategies. It consists of three steps. In the first step, RWH Prediction, operating at a daily time-step, anticipates system overflows for RTC decision-making using the Rainwater Harvesting Behaviour Model (Equations 1-3). Yield-after-spillage rules were applied to provide a more accurate estimation of yield (Fewkes & Butler, 2000; Equation 1). System inflow was predicted prior to the actual events using a 7-day runoff forecast extracted from the output of M1. The forecast is updated every 24 hours. Overflows are considered as unregulated — i.e. they occurred whenever the maximum capacity

is exceeded. First flush diversion system was excluded from the model, given that the use, type and volumetric behaviour of filtration devices, if present, is highly variable.

$$Q_{oi,t} = \max \begin{cases} V_{i,t-1} + Q_{a_{i,t}} - S_i \\ 0 \end{cases}$$
 (1)

$$Y_{i,t} = min \begin{cases} D_{i,t} \\ V_{i,t-1} - Q_{bi,t} \end{cases}$$
 (2)

$$V_{i,t} = min \begin{cases} V_{i,t-1} + Q_{a_{i,t}} - Y_{i,t} - Q_{b_{i,t}} \\ S_i - Y_{i,t} - Q_{b_{i,t}} \end{cases}$$
 (3)

where $V_{i,t}$ and $V_{i,t-1}$ are the volume (L) in system i ($i \in N_T$) at the end of time step t (current) and t-1 (previous) respectively, $Y_{i,t}$ is the rainwater yield in system i at t (L/timestep), $Q_{b_{i,t}}$ is the RTC pre-storm release (control variable) from system i at t (L/timestep), $Q_{o_{i,t}}$ is tank overflow from system i at t (L/timestep), S_i is tank storage capacity (L) of system i, $D_{i,t}$ is the demand (L/timestep) from tank i at time t, $Q_{a_{i,t}}$ is the system i inflow at time t (L/timestep), N_T represents the set of tanks

In the second step, pre-storm release plans are developed to minimize the system overflows, based on the developed strategies. The overflow volume predicted for the RTC system corresponds to all roof surfaces connected to RTC RWH systems (see more details in section 2.3).

In the third step, the RWH Simulation (Figure 1) models the performance of defined controls using the RWH behaviour model (Equations 1-3). While the process is similar to RWH Prediction, this step is run on a 6-min time step, to capture system inflow and outflow dynamics. It utilised continuous simulation, assuming that all systems were empty at the beginning of the entire simulation period, meaning that this initial condition will not reset at each event. Finally, outflows (i.e. pre-storm releases and any overflows) from each system are summed and fed into the Drainage Simulation Module (M3).

Prediction and simulation components are operated on a 7-day rolling horizon. This setting, also known as receding horizon, has been used in the Model Predictive Control of urban

drainage systems (Lund et al., 2018). RWH Prediction decides the RTC plan for the next 7-day period, given its ability to inform controlled releases long before the actual event (Xu et al., 2020b). However, only the actions in the first 24-hour period of that rolling horizon are implemented in the RWH Simulation component, which is then renewed recursively, on a daily basis, when forecast information is updated. This approach creates the possibility to account for forecast errors (which typically decrease as the forecast window decreases), to minimise the impact of these errors on system performance.

2.2.3 M3 Drainage Simulation Module: combining R and SWMM model

The Drainage Simulation Module (M3), based on SWMM, aims to model the impact of RTC and RWH systems on flow dynamics in stormwater networks. Outflow time-series data from M2 are fed into each catchment node as external inflow, representing the flow from roof areas. Each roof area is set to be 0% imperviousness with depression storages of 99 mm to ensure zero runoff is produced in the hydrological model (as the roof runoff is being modelled by M1). Finally, model results, such as total flooding volume and network outflow, are stored and evaluated using a range of assessment metrics (see section 2.4).

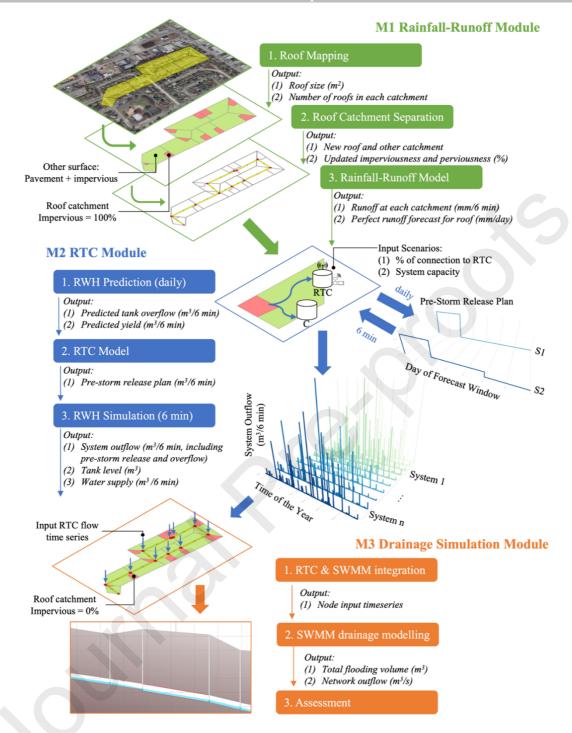


Figure 1. Conceptual representation of modelling procedure, including three modules: (1) M1 Rainfall-Runoff Module, (2) M2 RTC Module, and (3) M3 Drainage Simulation Module. RTC represents for Real-Time Control systems, while C represents for Conventional RWH systems.

2.3 Study catchment

The study area is a small urban district, with primarily residential land use, located in a mid-size municipality in the province of Quebec, Canada. It is approximately 7.3 ha in area,

with an average imperviousness of 45.9% and includes 70 houses with an average roof area of 188.8 m². The SWMM model of the drainage network was adapted from Shishegar et al. (2021) (Figure 2). The study catchment is drained to a combined sewer system with limited capacity, with recorded flooding issues in upstream nodes. For this study, a separate stormwater system is assumed by excluding the wastewater flow (i.e. set as zero). The study catchment consists of 10 subcatchments (with an average slope of 2%), 10 nodes and 10 pipes with diameters varying from 200 mm upstream to 600 mm downstream.

Rainfall observations, adopted from Shishegar et al. (2021), were obtained from a rain gauge near the study stormwater network (Latitude: 46°01'00" N, Longitude: 71°57'00" W; Environment and Climate Change Canada, 2021). An individual rain event was defined as having more than 0.2 mm of rainfall with an antecedent dry period of 6 hr. In total, 77 rain events were exacted from a 7-month period (i.e. 1st April to 31st Oct 2013), with total precipitation of 796.4 mm.

A domestic water demand profile was adopted from local authority data (Ministry of Municipal Affairs and Housing, 2020), which indicates a daily water consumption of 275 L/person/day. A population of 2.1 person per household was assumed according to the census in the nearby catchment (Statistics Canada, 2017). RWH systems were assumed to supply toilet flushing, which counts for 30% of the domestic demand, with two peak usages at 9 am and 7 pm in the diurnal pattern, leading to 173.3 L/day for each household. Although such supply has not been implemented in this study catchment, it is commonly used in many countries, such as Australia, Europe and America, reflecting the general use of rainwater harvesting systems (Campisano et al., 2017).



Figure 2. Schematic illustration of study district, located in the province of Quebec, Canada.

2.4 Scenarios and Input Data

A range of scenarios were designed to test the impact of RTC system settings on network performance. We considered five rainwater storage capacities, relative to the roof areas (i.e. 5, 10, 20, 40, 80 L/m²) and five different storage capacities to which RTC is applied (e.g. 100% represents all RWH systems are operated by RTC). All of these were compared to a baseline scenario (i.e. no RWH system). Two climate conditions – *current* and *future* - were applied to evaluate the performance of the proposed RTC strategies in the context of climate change. Future rainfall is projected by adding a fixed factor of 15% to all rainfall data values. This simple approach has been adopted by previous studies in the southern Québec region (Bilodeau et al., 2018; Shishegar et al., 2021), although future increases in rainfall intensities are likely, in reality, to vary by region, season (Ouranos, 2015) and return period of rainfall events (Mailhot et al., 2012).

2.5 Assessment Metrics

Two metrics were adopted to quantitatively evaluate the impact of RTC RWH systems on the drainage network performance, namely peak flow and flooding volume reduction (Table 1). These metrics were both assessed at the catchment scale, and quantify, respectively, the maximum outflow rate (m³/s) at the network outfall and total network flooding volume (i.e. the sum of flooding volume from each node in m³), standardised by its performance relative to the baseline scenario. The network outflow is also characterized using a flow duration curve (i.e. to better understand the distribution of the flows during the 7-month period (Quinn et al., 2021)), which compares the outflow regimes of two RTC systems with a conventional RWH system without RTC. In addition, we assessed the water supply efficiency of the RWH systems at the catchment-scale across the full range of scenarios (see Table 1 below).

To understand the specific performance gain resulting from RTC implementation, flooding volume at each node in one RTC scenario (e.g. 40 L/m² systems operated by strategy S1) was plotted against the baseline scenario. Moreover, three of the most intense rainfall events, along with one event that has the longest duration and largest rainfall depth over the simulation period, were selected as illustrative examples to demonstrate peak flow reduction.

Table 1.Assessment Metrics for Triple Objectives of Rainwater Harvesting

Assessment Metrics	Equation	Description
Peak Flow Reduction (%)	$ ho_{peakflow} = rac{Q_{out,max_{baseline}} - Q_{out,max_{RTC}}}{Q_{out,max_{baseline}}}$	Peak flow reduction of RTC strategies compared to the conventional system. Q_{out} refers to the outflow of the entire drainage network.

Flooding Volume Reduction (%)	$ ho_{flooding} = rac{V_{flooding_{baseline}} - \ V_{flooding_{RTC}}}{V_{flooding_{baseline}}}$	$V_{flooding_{baseline}}$ and $V_{flooding_{RTC}}$ are the total flooding volume of baseline (i.e. without any RWH systems) and RTC scenarios
Water Supply Efficiency (%)	$Ews = \sum_{i \in N_T} \frac{\sum_{t} Y_{i,t}}{\sum_{t} D_{i,t}} / n$	respectively. $Y_{i,t}$ and $D_{i,t}$ are the rainwater yield and water demand in system i ($i \in N_T$) at time t (L/6 minutes). n is the total number of tanks (i.e. size of N_T), N_T represents the set of tanks.

3. Results

3.1 Network Flooding Volume

As expected, the implementation of RWH systems reduced the total network flooding volume (Figure 3a). Conventional systems without RTC (i.e. 0% RTC) demonstrated an average of 17% flooding volume reduction compared to the baseline scenario (i.e. 0 L/m² tank size) which resulted in total flooding volume of 812 m³. The flooding volume reduction performance of these passively controlled tanks gradually increased with system capacity.

Increasing the use of RTC further reduced the flooding risk, by mitigating network flooding volume (Figure 3a). Operating all RWH system using RTC S1 (i.e. 100% RTC) reduced the network flooding volume up to 82%. Equipping roof areas with 10 L/m² RTC RWH systems doubled the flooding volume reduction achieved by much bigger (80 L/m²) conventional RWH systems, with total flooding volume of 352 and 609 m³, respectively. More importantly, the performance gain from increasing the proportion of controlled tanks was larger for small sized system (i.e. < 20 L/m²), decreasing in relative terms where larger rainwater storages were used.

A similar trend in flooding volume reduction was modelled under the future climate, across all scenarios. While both the conventional and RTC demonstrated approximately 5% decrease in performance under future climate, the smallest RTC system (i.e. 5 L/m²) outperformed the largest conventional system (i.e. 80 L/m²), with 29% and 21% flooding volume reduction, respectively.

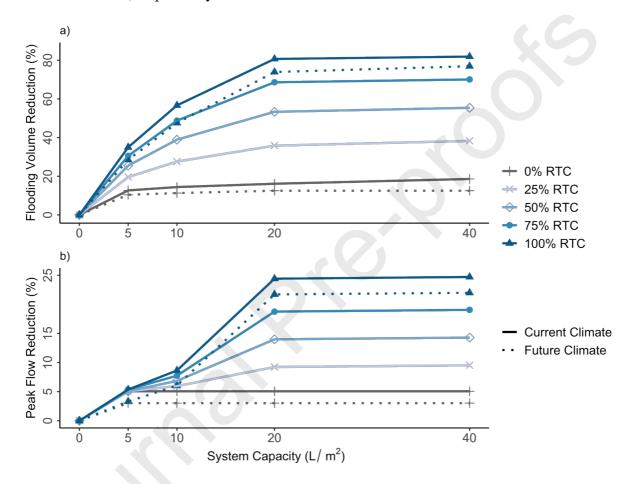


Figure 3. Evaluation of a) flooding volume and b) outlet peak flow reduction performance in a range of scenarios under current and future climates under the Strategy S1 Flood Protection for the 7-month simulation period.

The enhanced network flooding volume reduction provided by RTC is due to the

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improved stormwater control at-source. This is illustrated by the presence of flooding volume in the upstream nodes within the baseline scenario (Figure 4a). Retrofitting with 40 L/m² RTC system (Figure 4b) can completely retain the flooding volume within nodes 3 and 4, while providing 88% and 77% flooding volume reduction to nodes 1 and 2 respectively, mitigating

a total of 665 m³ node flooding volume for the entire network during the 7-month simulation period.

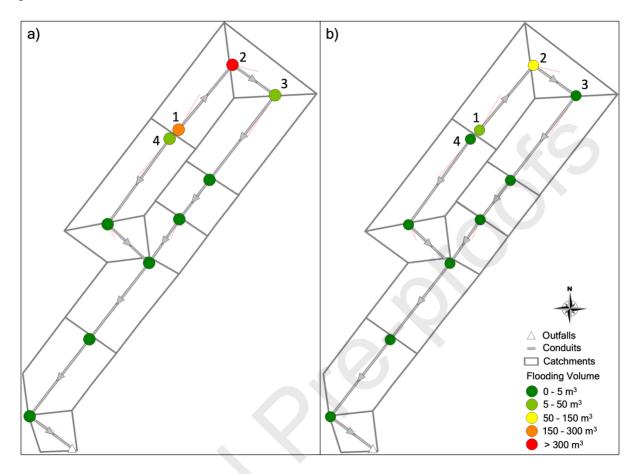


Figure 4. Flooding volume at each node of the study catchment in different scenarios during the 7-month simulation period, for a) baseline scenario and b) all the roofs connected to a 40 L/m² RTC system operated by Strategy S1 Flood Protection.

3.2 Flow Regime

3.2.1 Peak Flow Reduction

Operating RWH systems by RTC with S1 was shown to effectively reduce the peak flow at the drainage network outfall. Like the network flooding volume reduction, enhancing the proportion of RTC systems improved the peak flow reduction by up to 25% and 22% (Figure 3b) in the current and future climates, respectively. Increasing the storage capacity improved peak flow reduction, but the gains achieved were clearly constrained by the proportion of storages operated by RTC, with no gain in performance for systems size greater

than 5 L/m² for passively controlled systems. Conversely, scenarios with RTC applied to only 25% of storages saw gains in performance with incrementally larger storages.

Real-time controlled systems were also modelled to mitigate peak flow in large rainfall events (Table 2). The Flood Mitigation strategy (S1), with a capacity of 40 L/m², for example, was shown to reduce peak flows by 25% to 40% in the most intense events (i.e. 9th August, 27th June and 28th June events), while achieving a 32% peak reduction during the largest and longest rain event (i.e. 23th May event which has total rainfall depth of 89.6 mm over 76.3 hr). This performance was also resilient against future climate, where an increasing of 15% rainfall resulted in an average loss of approximately 2% in the achieved peak flow reduction.

Table 2.Peak flow reduction at the outfall of the study catchment in four large events in 2013.

	Rainfall		Current Climate		Future Climate		
		Rainfall	Maximum	Peak Flow	Rainfall	Maximum	Peak Flow
Date	Duration (hr)	Depth	6-min Intensity	Reduction	Depth	6-min Intensity	Reduction
	(m)	(mm)	(mm/hr)	(%)	(mm)	(mm/hr)	(%)
9 August	4	21.8	63.6	25	25.1	73.1	22
27 June	2	8.4	48	40	9.7	55.2	37
28 June	3.9	21.8	39.6	33	25.1	45.5	30
23 May	76.3	89.6	30	32	103	34.5	31

3.2.2 Outflow Characterisation

The outflows of two of the modelled RTC scenarios were characterized, for illustration, by a flow duration curve, with a comparison to the conventional systems (Figure 5). Both RTC systems demonstrated similar performance in reducing the magnitude and flashness of high flows compared to the conventional system, especially for the highest flow Q5 (observed less than 5% of the time). However, the RTC release using S2 Longest Discharge strategy was able

to better attenuate the flows, especially for Q5 – Q60 (Figure 5). The Flood Mitigation strategy (S1) showed higher flows during Q5 - Q20, but with a sudden decrease towards low flow levels. In contrast, the Longest Discharge strategy (S2) generally produced more muted high flows, decreasing more gradually (i.e. lower rate of change) until the turning point occurred later at Q60. This gives a more constant overall flow regime.

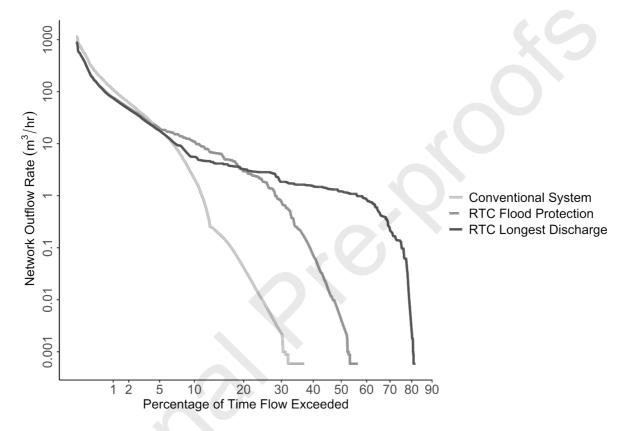


Figure 5. Outflow Duration Curve (i.e. showing percentage of the time of a given flow magnitude is exceeded) of RTC S1 Flood Protection (i.e. grey) and S2 Longest Discharge (i.e. black) compared to conventional system (i.e. light grey). The x-axis is scaled to 0 – 90% due to the cease-to-flow condition (i.e. no flow) occurring after Q90. All the roof catchments were equipped with 40 L/m² tank, while both of the RTC proportions were set as 100%. Network outflow is obtained at the outlet of the study catchment, which is computed by the hydraulic model using SWMM.

3.3 Water Supply

Water supply performance was similar for both RTC strategies, being somewhat lower than that of conventional systems. Indeed, RTC Flood Protection demonstrated an average of

74% (\pm 21%) supply efficiency across all scenarios, compared to 94% (\pm 5.3%) in conventional systems. The decrease in efficiency is relatively larger in small sized systems (e.g. 5 and 10 L/m²), diminishing in large systems (e.g. 80 L/m²) where the difference is generally less than 2%.

4. Discussion

4.1 Impact of RTC

Increasing the proportion of RWH storages controlled by RTC dramatically improved the performance in terms of peak flow and flooding volume reduction. This can also be achieved by increasing storage capacity, although a diminishing marginal return occurred when the capacity of the RTC systems exceeded 20 L/m². The magnitude of performance gained from increasing RTC proportion was relatively greater than simply increase tank capacity. This observation confirmed that implementation of RTC can make the most of each RWH storage through adaptive management of its capacity, improving retention of runoff, thus reducing network flooding while maintaining water supply performance, although the pre-storm release could reduce the security in storage for supply. RTC RWH systems have the potential to deliver significant cost savings; systems operated by RTC can be built at a smaller size, while delivering the same level of service as a larger conventional design. Doing so can help to reduce the overall cost, especially in high-density urban environments, where space is limited (i.e. insufficient space or high cost for large tanks). Similarly, retrofitting of RTC to existing RWH storages will improve their performance, reducing flood risk of the stormwater network, without requiring replacement of existing storages.

Increasing storage volume improved peak flow reduction, but in conventional storages, this occurred only for increases up to around 20 L/m². Above that, any gain was very small. This is because, regardless of storage volume, the limited water demand means that these tanks

remain near full most of the time (Jones & Hunt, 2010). Implementation of RTC overcomes this limitation; the RTC systems can better mitigate the peak flow by proactively emptying the storage through the pre-storm releases. It offers flexibility to create the necessary capacity in real-time allowing RTC RWH systems to better reduce the storm runoff at its source, prior to the pipe network, thus potentially reducing flooding risks for the downstream receiving waters.

This adaptive approach could also be extended to reduce the risks of combined sewer overflows (CSO), which pose a major hazard to urban water environment (Ellis & Hvitved-Jacobsen, 1996; Passerat et al., 2011). Real-time control can also be applied to decentralised and centralised stormwater systems that include storage to create resilience in urban drainage networks, and cope with increasing impervious runoff caused by changing land use and climate change, allowing high-cost infrastructure upgrades to be postponed or avoided.

In theory, the maximum peak flow reduction in this study is approximately 40%, given that the RWH storages are limited to only control the runoff from roof surfaces which occupies around 40% of the total impervious areas. Therefore, the impact of RTC on the drainage network is constrained by the extent of its application. This will likely occur in practical implementation, given that RWH systems are generally utilised to manage roof runoff only (Campisano et al., 2017), with ground-level runoff being unaffected. Future work could be undertaken to test approaches to circumvent this physical constraint, for example by coupling the RTC RWH systems with other stormwater control measures (SCMs; e.g. biofilters (Shen et al., 2019) and detention basin (Shishegar et al., 2019)). Real-time control could be applied to this network of SCMs. Indeed, RTC technology is increasingly applied in both nature-based and storage-based SCMs, with growing interest in investigating the mechanisms and benefits on the collaborative operation of multiple systems at a range of geographical scales (Di Matteo et al., 2019; Liang et al., 2021; Mullapudi et al., 2018).

However, maintaining the ecological integrity of an aquatic ecosystem requires not only alleviation of peak flow, but restoration of a flow regime as close as possible to its natural (pre-urbanisation) state (Poff et al., 1997). Doing so requires consideration of various aspects of the flow regime, including magnitude, frequency, timing, duration and flashiness. Therefore, while both developed RTC strategies successfully reduced the magnitude of peak, performing the pre-storm releases over a longer period at a lower rate, as occurred in S2 (Longest Discharge), was far more effective in delivering a flow regime more typical of pre-urban conditions. This outcome also has the benefit of minimising the hydraulic disturbance and subsequent erosion of downstream channels (Hawley et al., 2013; Russell et al., 2020).

4.2 Implementation at catchment-scale

Recent advances in low-cost sensor technology enable the real-time monitoring of environmental conditions (e.g. water level in stormwater networks and streamflow) and system dynamics (e.g. water level in the tanks and actuator status), providing a feasible and affordable solution for large-scale deployment (Cherqui et al., 2019; Montserrat et al., 2013; Shi et al., 2021). The collected data can be transmitted via innovative communication technology, such as Low Power Wide Area Networks (LPWAN), which is characterised by low energy consumption and high transmission ranges (Silva et al., 2017). Such a technique has begun to be applied in operating multiple site-scale RTC RWH systems, powered by solar panels and batteries, at catchment-scale (Oberascher et al., 2021). Further gains can likely be made through the integration of sensor data and online hydrodynamic models, to improve the network performance of RTC RWH systems (Bartos & Kerkez, 2021).

One important driver of implementation relates to the costs and benefits of RTC RWH systems. While the cost of such system is context specific, several studies have concluded that rainwater storages retrofitted by RTC technology is a more cost-effective solution when

broader criteria, such as flood control and environmental benefits, are considered (Melville-Shreeve et al., 2016; Parker et al., 2022). Additional benefits could also be obtained from the coordinated control of multiple rainwater storages at network scale given the synergies it can provide. Future research is needed to evaluate the costs and benefit of more complex RTC schemes, in specific regulatory and infrastructure contexts.

4.3 Future research

Future research is required to investigate the effectiveness of control strategies which permit the spatially distributed RWH systems to collaborate across the catchment. This could be achieved by optimisation-based control, although doing so will require overcoming the computational challenges associated with running optimisation and hydraulic models in real-time. The performance of such control could also be compared with simpler rule-based control, as simplicity of implementation will be helpful in opening up the benefits of RTC to a wider range of actors. Future areas of research should also include a closed-loop control where real-time monitoring data (e.g. water level in each drainage node) could provide feed-back to improve the control strategy, minimising the impacts of uncertainties in weather forecast and system dynamics. Another area of future work could be to propagate the sort of 1-D hydraulic modelling carried out here with a 2-D flood model. Even more complex feedback loops could be investigated if modelling both 1 and 2-D domains.

5. Conclusion

In this study, we modelled the impact of at-source RTC RWH systems on the behaviour of a stormwater network, through the integration of a RTC model in R software and a 1-D hydraulic model in SWMM. Two different RTC strategies, one for mitigating floods, the other aimed at delivering a more natural flow regime, were tested across a range of system settings under two climate scenarios—current and future climates. We concluded that the use of RTC

can substantially reduce the network flooding volume and peak flow in both current and future climates and mitigate the risks of urban flooding, while providing a decentralised water supply. Implementing higher proportions of RTC systems provided larger relative benefits than simply increasing the storage capacity of RWH systems. Moreover, the RTC systems fundamentally modified the flow regimes of the network outflow, which reveals a promising potential in reducing erosion and restoring pre-development flow regimes in receiving waters. Our study suggests that RTC storages distributed throughout a stormwater network can substantially improve its performance, potentially avoiding or deferring expensive sewer network upgrades. Investments in RTC technology would appear to be more promising than investments in detention volume alone.

Acknowledgments

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685	Highlights:
686	Impact of real-time control (RTC) rainwater harvesting systems on stormwater
687	network was modelled by coupling SWMM and RTC model in R.
688	Real-time controlled rainwater harvesting systems can mitigate drainage network
689	flooding by reducing stormwater runoff at source.
690	Implementing RTC in RWH storages yielded greater benefits than simply increasing
691	storage capacity.