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Smart soils track the formation of pH gradients across the rhizosphere

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7 **Abstract**

8 *Aims*

9 Our understanding of the rhizosphere is limited by the lack of techniques for *in situ* live
10 microscopy. Soil is opaque and allows only superficial or destructive observations.
11 Here, the aim is to fabricate and test artificial substrates, termed smart soils, that are
12 dedicated to live microscopy of rhizosphere processes.

13 *Methods*

14 The transparency of smart soils was achieved using polymer particles with refractive
15 index matching that of water. The surface of the particles was modified both to retain
16 water and act as a local sensor to report on pore space pH via fluorescence emissions.
17 Multispectral signals were acquired from the particles using a light sheet microscope,
18 and machine learning algorithms predicted the changes and spatial distribution in pH at
19 the surface of the smart soil particles.

20 *Results*

21 The technique we report on here was able to predict pH live and *in situ* within ± 0.5
22 units of the true pH value. pH distribution could be reconstructed across a volume of
23 several cubic centimetres around plant roots at 10 μm resolution. Using smart soils of
24 different composition, we revealed how root exudation and pore structure create
25 variability in chemical properties.

26 *Conclusion*

27 The study demonstrates how smart soils could be used to better understand the
28 functioning of the rhizosphere

29 **Keywords:** Sensing soil, root, rhizosphere, light sheet microscopy, live imaging

30

31 **Introduction**

32 Studies of dynamic biological processes in soil are challenging. Direct observations and
33 the use of optical microscopes are limited because soils block electromagnetic signals in
34 the visible domain and invasive approaches permanently disrupt the functioning of
35 communities of biological organisms. The radio waves used in ground penetrating
36 radars can penetrate soils, but cannot resolve micrometric variation (Jol 2008). The
37 application of penetrating radiation such as X-ray or neutron tomography successfully
38 depict the physical structure of soils non-destructively (Moradi et al. 2011; Koebernick
39 et al. 2019; Burr-Hersey et al. 2020), but biological or geochemical processes are more
40 difficult to detect. Techniques such as X-Ray fluorescence provide insights into the
41 chemical structures of soil (Van Veelen et al. 2020) and recent advances in X-Ray
42 microscopy now enable the resolution of small biological structures such as plant
43 anatomical features (Duncan et al. 2022). However, there are limitations on the use of
44 such techniques in real-time experiments due to both the radiation doses required and
45 the time needed to acquire each time point (Zappala et al. 2013).

46 Since *in vivo* observations are rendered impractical in natural soils, the use of artificial
47 media as model systems have become central to rhizosphere studies. Liquid cultures
48 offer simple ways to monitor root growth while sampling for compounds released by
49 roots and microbes (Oburger and Jones 2018). However, these systems lack the physical
50 support and physical/chemical heterogeneity to allow microbes to establish in the root
51 surroundings. Experiments in hydroponic systems create homogeneous conditions that
52 significantly decrease the richness and diversity of microbial communities (Korenblum
53 et al. 2020). Growth substrates, such as hydrogels, can mimic the mechanical resistance
54 of soils (Clark et al., 1999) and facilitate biochemical studies of the rhizosphere through

55 inclusion of indicator dyes (Kopittke and Menzies 2004) or the use of techniques such
56 as microdialysis extraction (Plett et al. 2021). But hydrogels also lack physical
57 heterogeneity and cannot be aerated with hypoxic conditions developing with depth due
58 to the slow diffusion of oxygen (Van der Meeren et al. 2001).

59 Recent studies have demonstrated the possibility of culturing and observing soil
60 organisms in transparent soils (Downie et al. 2012; O'Callaghan et al. 2018; Ma et al.
61 2019; Sharma et al. 2020). Transparent soils are artificial substrates composed of solid
62 particles whose refractive index matches that of water such that light can penetrate the
63 substrate without significant scattering, reflection and refraction by the soil particles.
64 Live observations of biological activity can then be made in the pore space between soil
65 particles (Liu et al. 2021; Engelhardt et al. 2022), and physical manipulations such as
66 ablation or cell guiding can be achieved using lasers (Ge et al. 2021), for example to
67 control the number of bacterial cells attached to a specific plant tissue (Ge et al. 2023).

68 Rhizosphere research has also greatly benefitted from the recent development of
69 optochemical sensors, notably planar optodes and zymography. A layer of analyte
70 sensitive material is applied at the surface of the soil, and changes in fluorescence
71 intensity, fluorescence lifetime, transmittance, or colour can be captured by a camera
72 and correlated to soil chemical composition (Baldini et al. 2006; Blossfeld and Gansert
73 2007). The technique is now widely used to study changes in chemical activity along
74 plant roots, including pH (Koop-Jakobsen et al. 2018; Sun et al. 2019), oxygen (Han et
75 al. 2016; Rudolph-Mohr et al. 2021) or ammonium (Strömberg 2008), and to report on
76 the activity of various types of enzymes (Giles et al. 2018). Optodes also exist for the
77 detection of nitrate (Huber et al. 2001) and potassium (Lookadoo et al. 2021) but these
78 have not yet been applied to the soil environment. As a result of these optochemical
79 sensors being applied at the surface of the soil, measurements may not correlate well

80 with actual soil properties *in situ*. Therefore, a possible next step is to engineer the
81 transparent soil particles themselves to enable the acquisition of optical signals
82 reporting on soil conditions locally and at the microscopic scale (Figure 1). We termed
83 these substrates smart soils.

84 Here we present the development of the first generation of such smart soils. The
85 approach proposed is to use FEP (Fluorinated Ethylene Propylene), a low cost and low
86 refractive index fluoropolymer and combines it with optochemical sensors that measure
87 chemical properties at the surface of smart soil particles. We have optimised the smart
88 soils for root growth and measurement of pH, an important indicator of nutrient
89 availability, plant stress and soil function. We demonstrate acquisition of multispectral
90 signals *in situ* from the smart soil particles using light sheet microscopy and assess how
91 the pore structure and root exudation contribute to the formation of pH heterogeneity in
92 soil.

93

94 **Materials and methods**

95 *FEP core particles*

96 FEP (Fluorinated Ethylene Propylene or *poly(tetrafluoroethylene-co-*
97 *hexafluoropropylene)* copolymer is a plastic commonly produced by industries for
98 tubing, coatings, and cable manufacturing (Ebnesajjad 2015)). Particles were obtained
99 from the factory (Holscott, UK) in the form of pellets (virgin material used for
100 extrusion) and chunks (factory waste). Chunk FEP particles were sieved to remove
101 particles above 1.25 mm. Both types of particles were treated in oxygen plasma at 100
102 W for 1 min (HPT-100, Henniker, UK) to remove dust and other surface residues before
103 further chemical processing.

104 *Synthesis and characterisation*

105 FEP and fluoropolymers in general have characteristics critical for application to
106 optochemical sensing, e.g. they have both a low refractive index and high transparency
107 (Hougham et al. 1999; Okamoto et al. 2014; Ameduri and Fomin 2020). They are also
108 chemically inert and have properties such as photostability along with great chemical,
109 thermal and oxidation resistance (Dams and Hintzer 2016; Henry et al. 2018). Because
110 FEP is transparent and has a refractive index of 1.341 – 1.347 (DuPont 2013), the
111 particle allows index matching in the smart soil interstices with water and subsequent
112 acquisition of fluorescent signal from the inner pore structure. However, some
113 properties, such as hydrophobicity and chemical stability make them challenging for use
114 as a soil substitute. Here, we synthesize polymers that can transform the properties of
115 FEP to increase the hydrophilicity of the surface for improved retention of water, and to
116 include an optochemical sensor for the detection of pH gradients.

117 Reagents consisted of 2,2,2-trifluoroethyl α -fluoroacrylate (FATRIFE) and
118 hexafluoroisopropyl α -fluoroacrylate (FAHFIP) purchased from Scientific Industrial
119 Application P and M (Russia). These fluorinated monomers were used to increase the
120 fluorine content of the terpolymer and increase the likelihood of fluorine-fluorine
121 interaction with FEP (Baker et al. 2012; Panini and Chopra 2015; Pigliacelli et al.
122 2022). Oligo(ethylene glycol) methyl ether methacrylate ($M_n= 300$ g/mol), Nile Blue A
123 (>75%), acryloyl chloride (97 %), methyl ethyl ketone (MEK), acetonitrile were
124 purchased from (Sigma Aldrich, France) while *tert*-butyl peroxyvalate (TBPPi, 75%)
125 was gifted by Akzo Nobel (France). Nile Blue methacrylate (NBMA) was synthesized
126 according to a previous report (Alcantar et al. 2000). Poly(FATRIFE-*ter*-PEGMA-*ter*-
127 NBMA) terpolymers were characterized by ^1H and ^{19}F NMR spectroscopies (AC 400
128 spectrometer, Bruker, France) and size exclusion chromatography (model 210, Varian

129 Prostar, France) using 0.1 M LiBr/DMF as the eluent, calibrated with PMMA narrow
130 standards. Fourier transform infrared spectroscopy (FTIR) analyses were performed in
131 the Attenuated Total Reflectance (ATR) mode (Spectrum 1000, Perkin-Elmer, France).
132 Thirty two scans were carried out on a selection of particles, at wavelength between 400
133 and 4000 cm^{-1} with a resolution of $\pm 2 \text{ cm}^{-1}$. “The synthesis of poly(FATRIFE-*ter*-
134 PEGMA-*ter*-NBMA) terpolymers was achieved by conventional radical polymerization.
135 A 50 ml round bottom flask equipped with a condenser and a magnetic stirring bar was
136 filled with TBPPi (0.101 g, 0.57 mmol), FATRIFE (4.94 g, 28.70 mmol), PEGMA
137 (8.60 g, 28.70 mmol), NBMA (29 mg, 0.057 mmol), TBPPi (0.101 g, 0.57 mmol) and
138 32 ml DMF. The reaction medium was deoxygenated by bubbling with nitrogen for 15
139 mins and then placed into an oil bath at 56 °C. Terpolymerization was stopped after 4
140 hours by immersing the flask in liquid nitrogen and exposing its content to air. The
141 crude product was purified by precipitation from water, filtering, lyophilisation (81 %
142 yield) prior to characterisation by ^1H , ^{19}F and IR spectroscopies.

143 *Preparation of fluorinated ethylene-propylene [poly(tetrafluoroethylene-co-*
144 *hexafluoropropylene FEP) particles*

145 In the next step, FEP particles were coated with the functional polymer to modify the
146 surface properties of the particles. 0.40 g of poly(FATRIFE-*ter*-PEGMA-*ter*-NBMA)
147 terpolymer was dissolved in 25 ml methyl-ethyl ketone (25642.325, VWR, UK) in a
148 500 ml rotary evaporator flask containing 20 g of FEP at 40 °C. The rotation speed was
149 increased progressively during the evaporation of the solvent to reach a speed of 240
150 rpm. Particles were then dried overnight at 40 °C. The use of solvent during the coating
151 maintained sterility (Hoell et al. 2012). To test for coating stability, particles were
152 placed in a test tube immersed in water and spun horizontally at room temperature for
153 several weeks. Then, the particles were filtered and dried in an oven for 12 hours at 40

154 °C and analysed by FTIR spectroscopy as described above. Water contact angle
155 measurements were performed with a contact angle goniometer (OCA contact angle
156 system, Neurtek Instruments, Spain). Water retention curves for the chunk and pellet
157 FEP particles (packed loosely at a density of approximately 0.5 g cm^{-3}), as well as for
158 the functional terpolymer were obtain using a tension plate (Sandbox 08.01,
159 Eijkelkamp, Netherland). Samples were weighed daily, and water tension was adjusted
160 when no loss was recorded between two measurements. The water tension applied
161 varied from 0 kPa to 8 kPa in intervals of 0.25 kPa initially and increasing progressively
162 to 0.85 kPa. Spectral properties of the polymers were characterised using a standard
163 multiplate reader (VarioskanTM LUX Multimode, Thermo Scientific, UK).

164 *Plant material and growth conditions*

165 Lettuce (*Lactuca sativa*) cv. all year round (Sutton Seeds, UK) seedlings were sterilised
166 in 10% bleach for 20 minutes and then washed 6 times in sterile dH₂O (O'Callaghan et
167 al. 2018). Then the seeds placed on the surface of 1% water agar gel in a Petri dish
168 under a laminar air flow cabinet to maintain axenic conditions, and then kept at 20 °C
169 for 24 h wrapped in aluminium in an incubator. After germination, the seedlings were
170 planted into mesocosm chambers on the surface of the substrate under sterile conditions.

171 Biocompatibility assays were performed with chunk FEP particles, fine sand (Pennine
172 Aggregates, MS01 0001), agricultural soil (Cambisol, Sandy loam, 71% sand, 19% silt
173 and 10% clay, Dundee, 56°27'34.8" N 3°4'21.01"W) and water agar (1% , Sigma
174 A1296-100G). For smart soil, 1.4 cm^3 of substrate were introduced in glass vials (75mm
175 x 9mm) and 0.8 ml of half MS liquid solution (pH 7, Sigma-Aldrich M5519) was
176 added. For the other soils, 1.4 cm^3 of substrate were introduced in glass vials and 0.3 ml
177 of distilled water was added. Sterilised lettuce seeds were grown at 21°C for 12 days

178 with 16 hours light and 8 hours dark period. Plants were harvested for measurement of
179 shoot dry weight and root length at the end of the experiment.

180 For imaging, mesocosm chambers consisted of two glass slides ($76 \times 26 \times 1$ mm,
181 VWR) separated by a 3 mm thick-spacer made of Polydimethylsiloxane (PDMS) were
182 constructed as described by Liu et al (2021). Smart soil was added to the microcosms
183 and compacted by gentle tamping. Two thirds of the mesocosm chambers were filled
184 with smart soil. 1.5 ml of half MS liquid solution was added. The smart soils were
185 therefore imaged unsaturated. Following planting the mesocosms were sealed with
186 parafilm tape. The mesocosms were kept in an incubator at 20 °C with 16 h light period
187 ($60 \mu\text{mol}/\text{mm}^2\text{s}$) and 8 h dark period. Plants were grown for one week (ensuring that the
188 roots did not reach the bottom of the mesocosm chamber) after which the analysis of the
189 spatial distribution of pH was performed. For live imaging 10 samples were sown in
190 total. 5 lettuce plants grew in chunk FEP particles and 5 lettuce plants grew in pellet
191 FEP particles. Additional time lapse imaging was carried out on one sample for
192 illustration purposes.

193

194 *Quantitative imaging*

195 The mesocosms contained a mixture of nutrient solution, air and smart soil particles.
196 Although the water added increased the transparency, air remaining within the pores of
197 smart soils caused significant challenges for imaging due to the reflection and scattering
198 of light. In this next step, we develop a live imaging method based on the Light Sheet
199 Fluorescence Microscope (LSFM) developed by Liu *et al* (2021). In short, a thin sheet
200 of light was created using a laser source. The light sheet passed through the sample with
201 the microscope objective and digital camera placed perpendicular to the light sheet to

202 capture light emitted from the sample either through scattering or fluorescence at
203 maximum dynamic range (16 bits). Long pass filters were used so that only
204 fluorescence signals were collected. The camera collected a 2D cross section of the
205 fluorescence signal emitted by the sample. A motorised stage was then used to acquire
206 2D cross sections across the whole sample so that a complete 3D reconstruction of the
207 pore structure could be achieved. The system was equipped with a four wavelength-
208 laser source (Vortran Versalase, Laser 2000 Ltd, UK) with wavelengths of 488 nm, 514
209 nm, 561 nm and 633 nm with the imaging arm fitted with long pass filters of 530 nm,
210 570 nm, 645 nm and 665 nm, respectively (Thorlabs FGL530, FGL570, FGL645,
211 FGL665). The signal corresponding to each fluorescence signal was recorded in
212 separate images noted $I_i \in \{488 \text{ nm}, 514 \text{ nm}, 561 \text{ nm} \text{ and } 633 \text{ nm}\}$. For example, I_{488}
213 represents the fluorescent signal collected when 488 nm wavelength laser was used in
214 combination with a long pass filter of 530 nm. I_i is not a scalar quantity but a function
215 of the position in the x-y plane of the image so that $I_i(x, y)$ is the pixel intensity
216 collected at positions x and y from laser excitation at wavelength i .

217 A dataset was assembled to calibrate pH predictions. Samples contained only smart
218 soils kept at 11 different pH levels achieved using MES acid monohydrate and Na
219 buffers at respective pH of 4.97, 5.20, 5.37, 5.58, 5.78, 6.03, 6.18, 6.38, 6.63, 6.80 and
220 6.97 (Merck 1.06126 and 1.06197). Image data were collected from 3 experimental
221 runs. Four Images were collected for each pH and for each of the four wavelengths (i.e.
222 44 images for each location measured). Points of interests were automatically extracted
223 from images obtained at 488 nm excitation and 530 nm emission (Figure S1). These
224 points were then used to collect a dataset describing the relation between pixel
225 intensities at all wavelengths and pH values. Regressions were established between pH
226 and image intensity ratios $\text{pH} = f\left(\frac{I_i}{I_j}\right), i \neq j$ (Figure S2). To further improve

227 predictions, neural network models of the type $pH = f(I_i, x, y)$, were developed using
228 Multi-layer Perceptron regressor with rectified linear unit function and trained using a
229 Limited-memory BFGS optimiser. The final neural network model contained 3 layers of
230 12 neurons each (Figures S3 and S4).

231 *Computation and statistical analysis*

232 Computations were performed using the Scikit-learn library (Pedregosa et al. 2011).
233 Datasets of pixel intensity at known pH was compiled with macros and scripts
234 developed in ImageJ. Analysis of variance and Tuckey's post hoc tests were achieved
235 using R with a statistical significance level 0.05. Analysis of pH variations surrounding
236 plant roots done using the nlme library (Pinheiro et al. 2013).

237

238 **Results**

239 *Functionalisation of Fluoropolymers allows fabrication of smart soil particles*

240 This study has successfully used waste FEP (Fluorinated Ethylene Propylene or
241 *poly(tetrafluoroethylene-co-hexafluoropropylene)* copolymer for the design of smart
242 soil particles. Waste FEP particles were coated with a thin polymer shell augmenting
243 them with a range of custom properties (Figure 1). The design of the shell was achieved
244 by conventional radical terpolymerisation of three comonomers, each of them bringing
245 specific and complementary properties. We synthesised and trialled numerous materials
246 (Supplementary Information 1) and can conclude that key elements are needed for
247 successful use of smart soils as a plant growth medium. First, a fluoropolymer matrix
248 was required for bonding, since it is known that Fluorine-Fluorine specific interactions
249 are possible. 2,2,2-trifluoroethyl α -fluoroacrylate (FATRIFE) monomer were used, but
250 similar attachment could be obtained with hexafluoroisopropyl α -fluoroacrylate

251 (FAHFIP). Plant growth also requires the particle to retain water and nutrients at the
252 surface of the particle. Because of the hydrophobic behaviour of FEP and fluoroalkyl α -
253 fluoroacrylates, hydrophilicity was achieved by addition of either carboxylic acids
254 (brought by 2-trifluoromethyl acrylic acid (MAF) or methacrylic acid) or
255 oligo(ethylene oxide) groups. Finally, the use of sensors for acquisition of biological or
256 environmental signals, was demonstrated with the addition of dyes based on fluorescein
257 and Nile Blue. The terpolymerisation of FATRIFE with polyethylene glycol
258 methacrylate (PEGMA) and Nile blue methacrylate (NBMA), initiated by *tert*-butyl
259 peroxyvalate (TBPPi), resulted in a wide range of terpolymers the compositions of
260 which were determined by ^1H and ^{19}F NMR spectroscopy.

261 *Functional materials improve growth conditions and allow attachment of pH sensor*

262 The main polymer tested in this study was poly(FATRIFE-*ter*-PEGMA-*ter*-NBMA)
263 terpolymer with 75/25/0.1 molar ratio (Figure 2A). Fourier-transform infrared
264 spectroscopy (FTIR) of the coating demonstrated the successful deposition of the
265 material on the surface of the particles (Figure 2B). The coating produced strong
266 adhesion on the FEP which resisted two months of spinning in water. The particles were
267 subsequently tested for their ability to deliver optical signals using a light sheet
268 microscope (Figure 2C). The coating drastically reduced the water contact angle of FEP
269 particles and therefore increased the ability of the substrate to hold water. The water
270 contact angle measured for uncoated particles was $108.8 \pm 0.5^\circ$ (n=6). By comparison,
271 the water contact angle measured on particles coated with the functional polymer was
272 $46.3 \pm 2.1^\circ$ (n=6) (Figure 2D). Once assembled into its granular form loose and
273 unpacked, the smart soil had a density of $0.537 \pm 0.08 \text{ g/cm}^3$ (n=6). Since solid FEP has
274 a density of 2.150 g/cm^3 , the estimated porosity of the smart soil was 75%. The
275 increased wettability of the particle surfaces following coating led to much improved

276 water retention (Figure 2E). The smart soils were trialled for biocompatibility. An
277 analysis of variance showed there was no significant differences on the shoot biomass
278 between treatments ($p=0.25$). A strong effect was observed on the morphology of the
279 root system ($p<0.05$). Plants grown in soil produced larger root systems while plants
280 grown in sand produced the smallest root systems. The root systems of plants grown in
281 smart soil were shorter than those of plants grown in soil, but not statistically different
282 from those of plants grown in gel (Figure 3). Further characterisation of polymer is
283 presented in the Supplementary Information.

284 *Multispectral light sheet imaging resolves pH changes at the micro-scale, live and in*
285 *situ*

286 Although particles showed consistent changes in fluorescent intensity, the response
287 varied significantly between individual particles (Figure 4A). To overcome this feature,
288 a ratiometric fluorescence approach was first attempted, but this yielded pH predictions
289 with limited accuracy (Figure S2). The best results with ratiometric fluorescence were
290 obtained with light excitation at 488 nm and 633 nm and calculation of prediction
291 intervals showed 95% predictions of pH values were within ± 0.5 units of the true pH
292 value. Machine learning proved more successful. Here we used four illumination
293 wavelengths (488 nm, 514 nm, 561 nm and 633 nm). For each wavelength a fluorescent
294 signal was recorded and a neural network model used to predict pH values from both
295 the xy-position in the image and the collection of fluorescent responses from all four
296 excitation wavelengths (Figures 4B & C). Results showed the machine learning
297 approach improved predictions significantly in a test dataset (Figure 4C, $t=79.9$,
298 $p<0.001$), with 95% of the predictions falling within -0.4 and 0.3 units of the true pH
299 value, almost doubling the precision of the ratiometric fluorescence predictions.
300 Ratiometric fluorescence predictions also introduced bias leading to underestimation of

301 large pH values (supplementary Figure S2). Up to 80% of variation in pH was correctly
302 predicted using neural networks with only 46% of the variance explained by the
303 ratiometric fluorescence approach.

304 *Smart soil particles help understand the formation of soil chemical heterogeneity*

305 Using the fabricated smart soil particles, pH dynamics in the rhizosphere of plants were
306 observed up to one week after germination. The first indication of root driven pH
307 change was visible after 4 days (data not shown). Following growth in the smart soils,
308 we could observe changes in chemical properties by the naked eye (Figure 5A) and
309 subsequently analyse how these changes relate to soil and root biological activity. Maps
310 of entire seedlings and surrounding smart soils were assembled by tessellating images to
311 produce volume data corresponding to up to 3 cm³ of substrate at 10 µm resolution with
312 each time point producing a dataset of approximately 4 Gb. pH predictions obtained
313 from the data acquired 7 days after inoculation (Figure 5B-D) revealed how soil
314 chemical heterogeneity may form as a result of root exudation, and how this process is
315 influenced by the generation of microsites and the type of FEP particles. Non-linear
316 mixed effect models (Supplementary Information 2) showed that when roots grew in
317 smart soil made of chunk FEP particles (factory waste), the pH increased by 2.65 over a
318 distance of approximately 2 mm from the root (scale parameter 0.51 in sigmoid
319 growth). In contrast, the increase of pH around roots grown in smart soil made of pellet
320 FEP particles (virgin material prior to melt processing) was limited to 0.87 and this was
321 observed at greater distance than in smart soil made of chunk FEP particles (scale factor
322 0.65, Figure 5E). Application of the Likelihood Ratio tests ($\chi^2=1612.45$, $p < 0.001$)
323 showed this trend was highly significant. Chunk FEP particles also produced a more
324 heterogeneous chemical environment with variance increasing with distance from the
325 root (Figure 5F) and therefore equated more closely to the properties of natural soils.

326

327 **Discussion**

328 *The challenges of the fabrication of smart soils*

329 This work investigated the fabrication of functional materials to not only mimic the
330 properties of the surface of particles, but also to facilitate the monitoring of chemical
331 variables involved in the functioning of the rhizosphere. Enhancing the properties of
332 such specialised fluoropolymers is challenging because of their lack of reactivity, but
333 we have developed a three step-strategy to overcome these difficulties. The synthesis of
334 functional polymers is first optimised without the core for characterisation of chemical,
335 physical and optical properties. Synthesis is followed by fast particle prototyping using
336 Fluorine-Fluorine interaction (Baker et al. 2012; Pigliacelli et al. 2022) to coat FEP
337 particles and allowing the blending of polymers or the recovery of the polymers tested
338 for reuse. Production of the final prototype could then be achieved by radiografting
339 polymerisation (Dargaville et al. 2003) for long term stability of the particle. Here such
340 a graft polymerisation of the functional polymer was successfully tested on FEP
341 particles, but not presented because it did not produce enough substrate for the study.
342 Finally, reusability, cost and the possibility to use waste material, which is not recycled
343 in the case of FEP (Dams and Hintzer 2016), will be important technological
344 considerations for future development of smart soils. This study has also established the
345 possibility of using factory waste for the fabrication of smart soils.

346 The development of this first generation of smart soils also gave indications on the
347 limitations of current fabrication techniques. Results showed that surface attachment
348 and coating stability require the introduction of an additional monomer(s), making the
349 synthesis more complex and costly. The future development of graft polymerisation

350 (Ruckenstein and Li 2005) could both significantly improve the number of uses of smart
351 soils and reduce the quantity of functional polymers needed for fabrication. Combining
352 sufficient ion exchange and water retention capacity within each individual particle was
353 challenging because the ionic strength of acid groups could not offset the strong
354 hydrophobic nature of fluoropolymers. The water contact angle of the surface of the
355 particles were reduced from 112° to as low as 88° using 2-trifluoromethacrylic acid
356 (MAF), and these results are similar to other available techniques such as H₂ or O₂
357 plasma etching (Park et al. 2002) and water retention of coarse sand was achieved.
358 Oligo(ethylene glycol) made surfaces highly hydrophilic (46 °) but did not provide any
359 surface charge for binding of mineral ions.

360 This work did not study the processing of FEP into particles. FEP particles were
361 generated at the supplier's premises by shredding FEP films. Even when complemented
362 by sieving, the resulting granular medium did not produce particles whose longest axis
363 was below 2 mm. In addition, the particles typically have flake-like shapes which did
364 not mimic well the granular properties of natural soils. Finally, fabrication techniques
365 proposed in this study are suitable to produce only a few grams of smart soil in one run.
366 The coating of the particles was the main bottleneck in the fabrication pipeline and was
367 limited by the size of the flask of the rotary evaporator. However, scaling this process
368 up is achievable using industrial coating techniques such as spray coating (Turton and
369 Cheng 2005).

370

371 *Using smart soil to study rhizosphere dynamics*

372 We used smart soils to study acidification resulting from root exudation. Roots are
373 known to release H⁺ ions to counterbalance cation uptake and various organic acids

374 which drive down soil pH and solubilise mineral ions adsorbed on soil particles (Ryan
375 et al. 2001). Live measurements of pH within 3 mm of the smart soil showed
376 acidification occurred within a few millimetres from the root surface which confirms
377 earlier studies made in natural soils (Jones et al. 2004; Koop-Jakobsen et al. 2018; Sun
378 et al. 2019). The smart soils also revealed that chemical changes induced by the roots
379 are intimately related to the structure of the granular media itself. Smaller particles
380 introduced more variable conditions around the root, perhaps due to reduced diffusion
381 coefficients and more tortuous diffusion pathways interacting with variation in
382 exudation patterns. Utilisation of our new technology revealed characteristics of pH
383 changes induced by root exudation at far higher resolution than previously possible with
384 techniques such as planar optodes or zymography assays, (Blossfeld and Gansert 2007;
385 Giles et al. 2018), allowing the possibility for reconstruction of the spatial structure of
386 chemical gradients in samples of small size. Current non-destructive imaging techniques
387 have not, previous to this study, delivered real-time observations of chemical or
388 biological activity *in situ* within soil.

389 Our results also revealed current limitations of using artificial substrates as substitutes
390 for natural soils. Although surfaces of smart soil particles were highly hydrophilic
391 (Figure 2), the particle size distributions of smart soils were too coarse to match the
392 water retention from a sand. The irregular shapes of the chunk FEP smart particles
393 occasionally formed large pores which resulted in a porosity of about 75%, which is
394 larger than most soils (Morris and Johnson 1967). The chemistry of the surface of soil
395 particles is equally difficult to optimise. The surface of natural soil particles is
396 chemically diverse and adsorbs ions in complex ways. Typical examples include the
397 fixation of phosphate which can be achieved by different oxides, hydroxides and clay
398 surfaces (Barrow 2017), or the adsorption of potassium which can be either in

399 exchangeable form or fixed between mineral layers (Zhang et al. 2009). Achieving such
400 binding specificity is challenging, and only ion exchange capacity has been
401 demonstrated so far (Downie et al. 2012).

402 The ability of the smart soil to generate optical signals through live microscopy is also
403 critical for the observation of rhizosphere processes. In this study, we noted that the
404 quality of the signals was primarily affected by the particle size distribution and water
405 content. The best signal was acquired during calibration when particles were isolated
406 and completely saturated in the buffer solution (Figure 4 B). However, the air left in the
407 pores degraded the signal significantly. The degradation is due to reflection and
408 diffraction at air-liquid interfaces, which affects both excited and emitted light. When
409 using smart soils made of pellets, there were fewer air-liquid interfaces and thus the
410 variability of the calculated pH values was limited. However, when using smart soils
411 made of chunk FEP particles, we observed a decline in accuracy and significant
412 variability in the calculated pH, in some cases leading to atypical pH values (Figure 5).
413 The scattering of the FEP particle could be detected by the microscope (Figure 2) but its
414 effect was less important than that caused by air. To limit the artefacts in this initial
415 study, we chose to perform the study with both sterilised smart soil and seed and also to
416 work with thin layers of soil (3 mm thickness). Improving light transmittance by
417 saturating the volume with water enabled imaging through samples that are centimetres
418 in size (Martins et al. 2019), but this can significantly affect diffusion and pH
419 distribution in the substrate. Developing more transparent FEP alternatives seems
420 unrealistic in the short term because of the difficulty in synthesizing polymers with high
421 fluorine content.

422

423 *New materials and technologies for the next generation of smart soils*

424 New materials and technologies offer huge opportunities to further enhance the
425 capabilities of smart soil particles, for example improving the wettability of the particles
426 using polymer brush structures (Zahner et al. 2011; Kobayashi et al. 2012), optimising
427 the porosity of polymers (Vos et al. 2013) or the roughness of surfaces (Tokunaga
428 2009). Materials could also be engineered to mimic more closely the binding of mineral
429 elements and pH dependence of surface properties. Microfabrication techniques could
430 be used to engineer the size and shapes of particles with a high precision (Aufrecht et al.
431 2022) and to better control environmental conditions in microcosm experiments
432 (Stanley et al. 2018). More realistic biotic environments could also be obtained by
433 combining synthetic communities of bacteria (Herrera Paredes et al. 2018) and soil
434 organic matter. The scaling up of fabrication processes will results in large volume of
435 substrates available for experiments and growing of larger plants for longer periods of
436 time. Attaching sensors to monitor oxygen (Bittig et al. 2018) and nutrient concentration
437 (Strömberg 2008) would in turn improve the understanding of the formation and
438 diversity of rhizosphere microhabitats. Finally, improved image processing algorithms
439 could considerably enhance the accuracy of measurements, bypassing noise and artifact
440 and extracting the relevant parts of the soil volume for prediction and analysis (Schlüter
441 et al. 2022). Smart soil technologies are bringing unique new capabilities to monitor and
442 quantify biological and chemical processes in the rhizosphere, and in the future, they
443 could help drive understanding of soil biodiversity and promote new forms of
444 agronomic screening in industry.

445

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456 **Author contributions:**

457 Conceptualization: LXD, BA, VL, MPM, TJD

458 Methodology: LXD, BA, VL, MPM, TSG

459 Investigation: DP, QY, PF, YH, BB, BVT

460 Funding acquisition: LXD

461 Project administration: LXD

462 Supervision: LXD, BA, TSG, TJD, VL, MPM

463 Writing – original draft: DP, QY, PF, YH, LXD

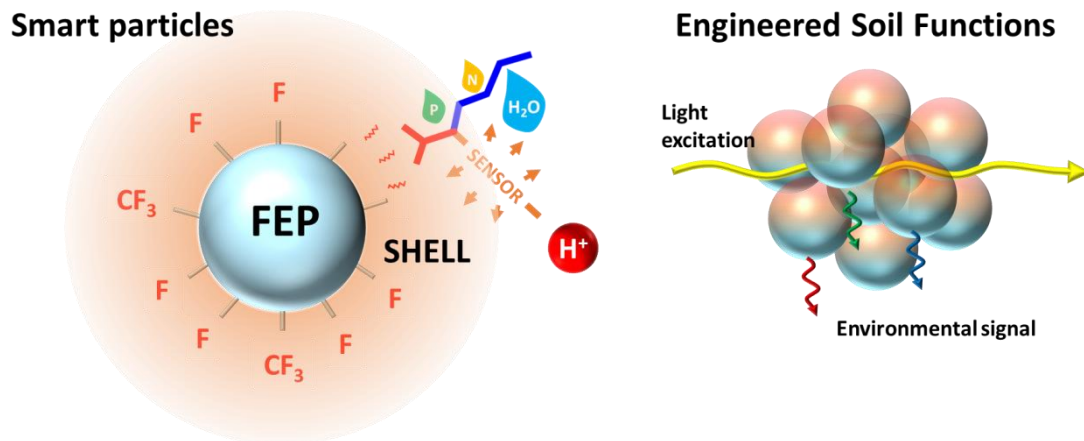
464 Writing – review & editing: BA, VL, MPM, TSG, TJD

465

466 **7. Declaration of interests**

467 There is NO Competing Interest.

468 **Figures**

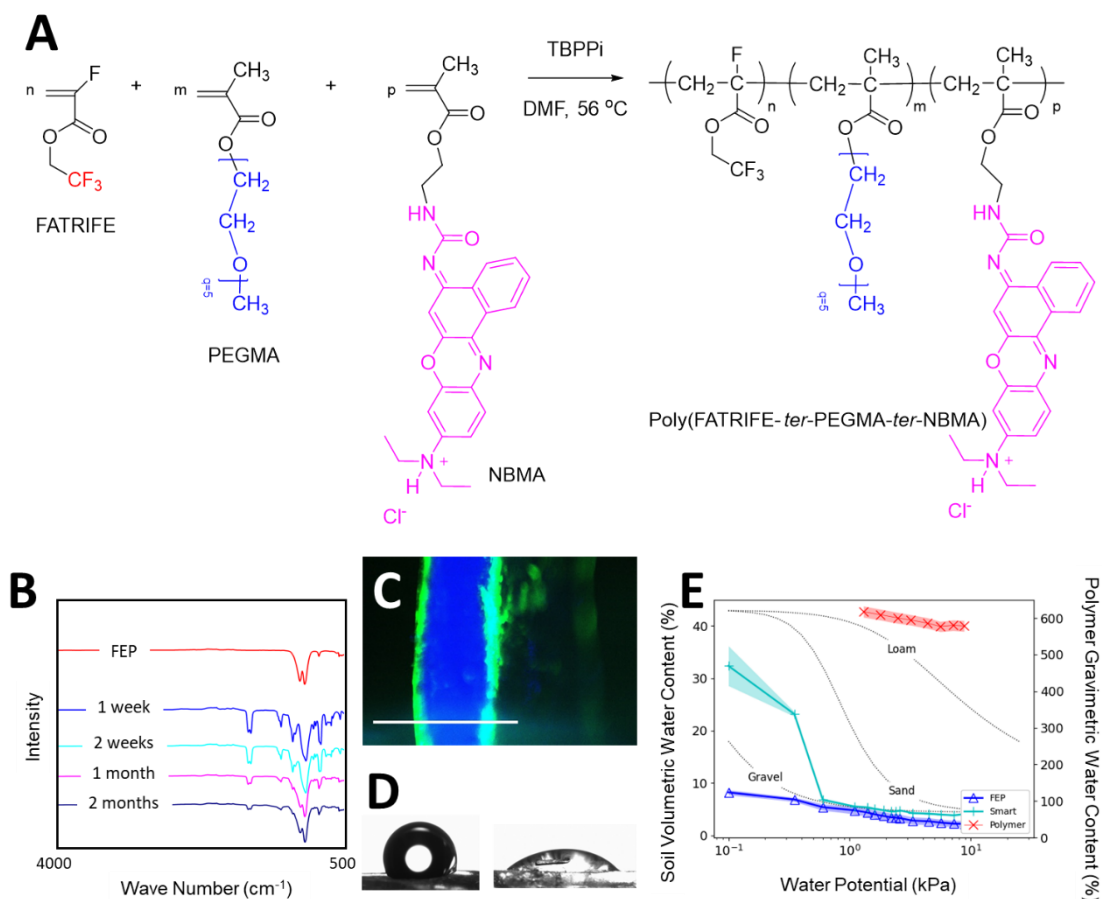


469

470 Figure 1. Smart soil particles are made of a core based of waste Fluorinated Ethylene
471 Propylene (FEP), which is embedded into a functional terpolymer, the shell (left). The
472 shell holds water and nutrients and includes a sensor (here a pH sensor). The soil is
473 subsequently able to respond to external stimuli such as light of various wavelength to
474 report on processes affecting the shell (right).

475

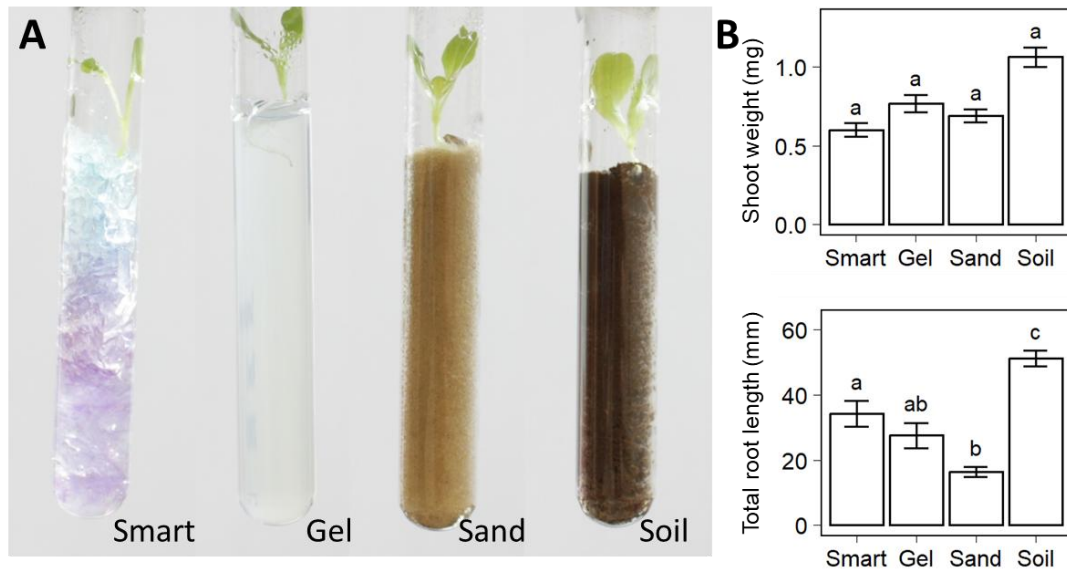
476



477

478 Figure 2. Using FEP particles for the fabrication of smart soil particles. (A) Chemical
 479 structure of the polymeric shell material encoding three different functions. The
 480 polymer consisted of α -fluoro-2,2,2-trifluoroacrylate (FATRIFE) for the attachment
 481 onto the FEP core, PEGMA (Polyethyleneglycol methacrylate) enhanced water
 482 retention and Nile Blue methacrylate (NBMA) brought the pH sensor. Materials were
 483 tested for various properties during the optimisation of the chemical structure
 484 (Supplementary Information 1). (B) The stability of coatings was studied using FTIR.
 485 FEP FTIR spectrum (top red) was compared to those of the coatings immediately, after
 486 1 week, 2 weeks, one month and two months (from green top to bottom black
 487 respectively). (C) The particles were tested for imaging using light sheet scattering
 488 (blue) and fluorescence (green) signals (scale bar 1 mm). (D) Water contact angle
 489 measurement of FEP (hydrophobic, > 90, left), and that of the functional polymer

490 (hydrophilic, $<90^\circ$, right). (E) Water retention of the terpolymers containing PEGMA
491 (red x) increased the water retention of FEP soil particles (cyan +) with comparison to
492 virgin FEP particles (blue Δ). van Genuchten curves (dashed lines) for gravel
493 (Tokunaga et al. 2002), sand, sandy loam and loam soils (Šimůnek et al. 2006) are given
494 for comparison. Shaded areas indicate mean value \pm SE for smart soil and the range of
495 values observed in natural sandy soils.

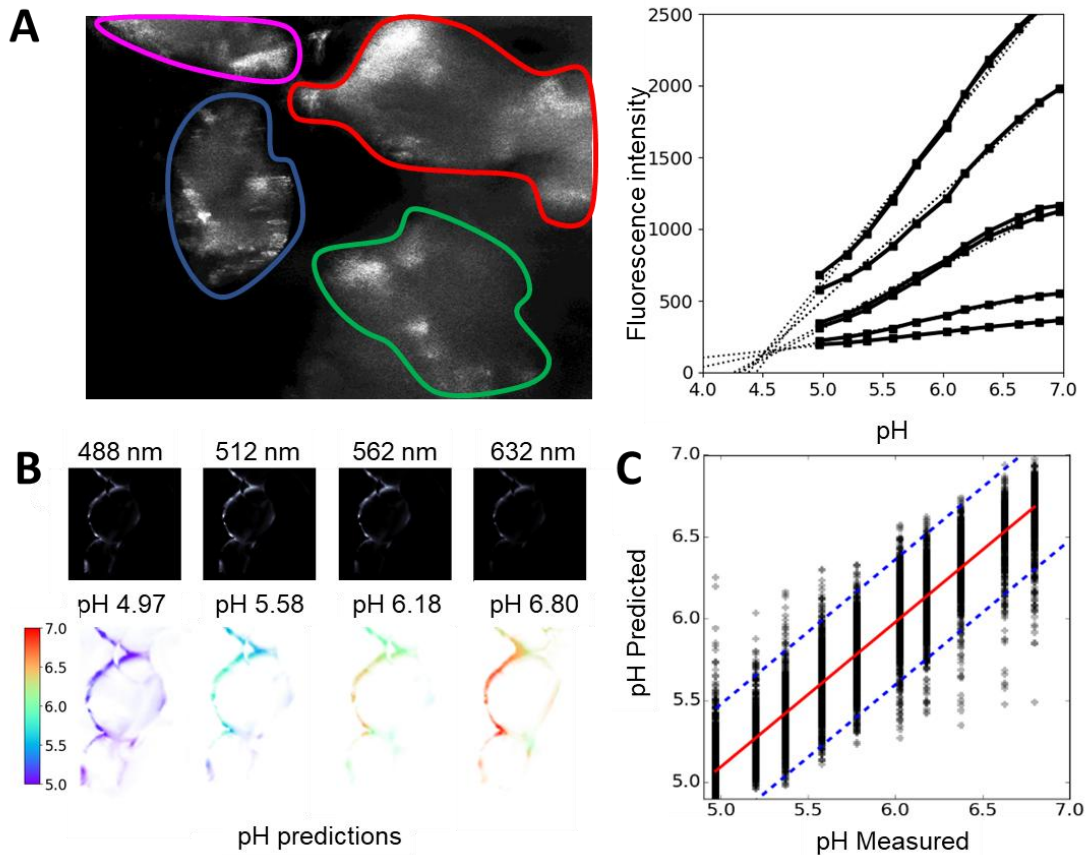


496

497 Figure 3. Biocompatibility of smart soil particles (A) Growth of lettuce seedling in
 498 chunk FEP particles (Smart), water agar (Gel), fine sand (Sand) and an agricultural soil
 499 (Soil). (B) Effect of the nature of substrate on shoot biomass (top) and root biomass
 500 (bottom). An analysis of variance showed root length but not shoot weight were
 501 significantly affected by soil treatments ($p < 0.05$). Error bars indicate mean value \pm SE
 502 for artificial soil and the range of values observed in natural sandy soils; Tukey codes
 503 from post-hoc tests are given where different letters denote statistically different means.

504

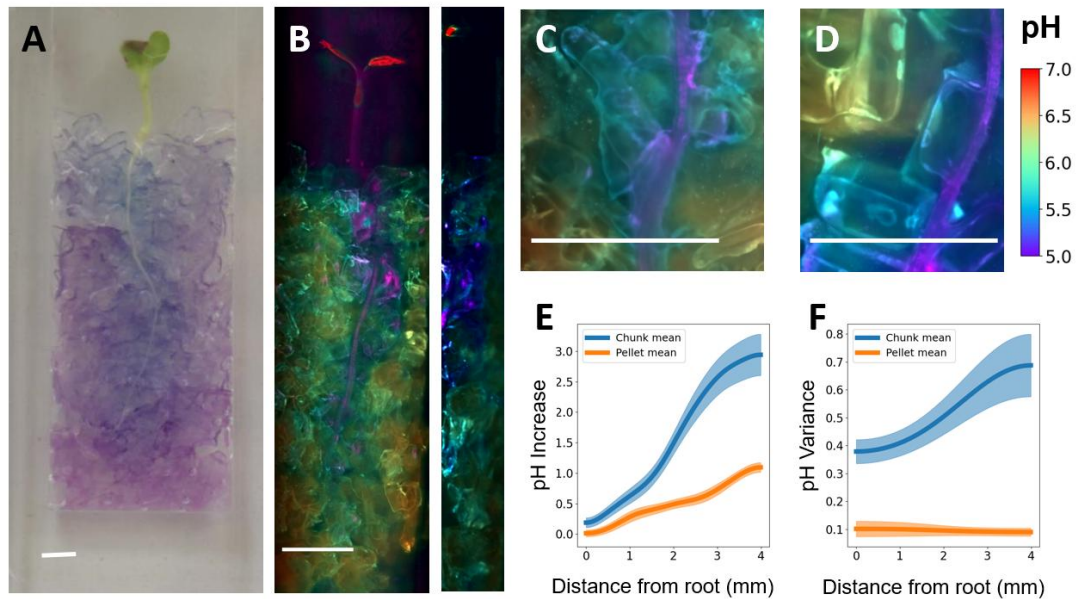
505



506

507 Figure 4. Calibration of pH sensing particles. (A). Change of the green fluorescence
508 (488 nm / 530 nm) from individual particles (here shown in outlines of different
509 colours) in response to a change in pH from 5 to 7 showing linear responses to pH but
510 strong variations in the slope of the response. (B) The machine learning approach
511 utilised data from four fluorescence signals to predict pH in situ from light sheet
512 microscopy. Pseudo colours indicate pH predictions corresponding to the pH buffer
513 used (indicated above each image). (C) pH predictions using the machine learning
514 approach explained up to 80% of the variance of the data and exhibited limited bias.

515



516

517 Figure 5. Smart particles reveal how interaction between root exudation and particle
 518 type affects the chemical heterogeneity of soils. (A) Seedlings grown in chunk FEP
 519 particles induced changes in colours of particles due to acidification. (B) Estimation of
 520 pH values from light sheet microscopy data revealed the pH distribution in the inner soil
 521 (max projection on the left, cross section on the right, scale bar of 4 mm). High
 522 resolution view of example images of roots from which data was acquired on two types
 523 of soils, chunk FEP particles (C) and pellet FEP particles (D) represented with a scale
 524 bar of 4 mm. (E) Change in pH as a function of the distance from the root surface for
 525 chunk FEP particles (blue) and pellet FEP particles (orange). (F) pH variance as a
 526 function of the distance from the root surface for chunk FEP particles (blue) and pellet
 527 FEP particles (orange). Non-linear mixed effect models showed the pH response
 528 observed in the two soils was statistically different ($\chi^2=1612.45$, $p < 0.001$). Confidence
 529 intervals indicate mean value \pm SE.

530

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