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Convergence rate of entropy-regularized multi-marginal optimal transport costs

Luca Nenna* and Paul Pegon†

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We investigate the convergence rate of multi-marginal optimal transport costs that are regularized with the Boltzmann-Shannon entropy, as the noise parameter ε tends to 0. We establish lower and upper bounds on the difference with the unregularized cost of the form $C\varepsilon \log(1/\varepsilon) + O(\varepsilon)$ for some explicit dimensional constants C depending on the marginals and on the ground cost, but not on the optimal transport plans themselves. Upper bounds are obtained for Lipschitz costs or locally semi-concave costs for a finer estimate, and lower bounds for \mathcal{C}^2 costs satisfying some signature condition on the mixed second derivatives that may include degenerate costs, thus generalizing results previously in the two marginals case and for non-degenerate costs. We obtain in particular matching bounds in some typical situations where the optimal plan is deterministic.

Keywords. optimal transport, multi-marginal optimal transport, entropic regularization, Schrödinger problem, convex analysis, Rényi dimension.

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Notations

X_i	a subset of \mathbb{R}^N for any index $i \in \{1, \dots, m\}$
\mathbf{X}	product space $X_1 \times \dots \times X_m$;
x_i, x, \mathbf{x}	a point in X_i , in some $X_j, j \in \{1, \dots, m\}$, and in \mathbf{X} respectively;
x_q	$(x_i)_{i \in q}$ if $q \subseteq \{1, \dots, m\}$ and $\mathbf{x} \in \mathbf{X}$;
$ \cdot $	Euclidean norm on \mathbb{R}^N ;
$\ \cdot\ $	norm on $\mathbb{R}^N \times \dots \times \mathbb{R}^N$ defined by $\ \mathbf{x}\ = \max_{1 \leq i \leq m} x_i $ if $\mathbf{x} = (x_1, \dots, x_m)$;
$B_r(x), B_r(\mathbf{x})$	open ball of radius r centered at $x \in \mathbb{R}^N$ or $\mathbf{x} \in (\mathbb{R}^N)^m$ for the above norms;
$\mathcal{E}_{\text{loc}}^{0,1}(X)$	space of real-valued locally Lipschitz functions on X which is a sub-manifold of \mathbb{R}^N or $(\mathbb{R}^N)^m$;
$[f]_{\mathcal{E}^{0,1}(X)}$	Lipschitz constant of $f : X \rightarrow \mathbb{R}$ where X is a subset of \mathbb{R}^N or $(\mathbb{R}^N)^m$ for the above norms;
$\mathcal{E}_{\text{loc}}^{1,1}(X)$	space of differentiable real-valued functions on X , a sub-manifold of \mathbb{R}^N or $(\mathbb{R}^N)^m$, with locally Lipschitz differential;
$\mathcal{P}(X)$	space of probability measures on a metric space X ;
$\text{spt } \mu$	support of the measure μ ;
$M_N(\mathbb{R})$	space of real matrices of size $N \times N$, endowed with the Frobenius norm induced by the scalar product $A \cdot B := \text{Tr}(A^T B)$, for $A, B \in M_N(\mathbb{R})$;
$S_N(\mathbb{R})$	subspace of real symmetric matrices of size $N \times N$;
\mathcal{H}_X^s	s -dimensional Hausdorff measure on the metric space X endowed with the Borel σ -algebra (the subscript X will often be dropped);
Δ_P	simplex of P-uples $t = (t_p)_{p \in P}$ such that $t_p \geq 0$ for all $p \in P$ and $\sum_{p \in P} t_p = 1$.

1 Introduction

We consider a m -uple of probability measures μ_i compactly supported on sub-manifolds $X_i \subseteq \mathbb{R}^N$ of dimension d_i and a cost function $c : X_1 \times \dots \times X_m \rightarrow \mathbb{R}_+$. The Entropic Multi-Marginal Optimal Transport problem is defined as :

$$\text{MOT}_\varepsilon := \inf \left\{ \int_{X_1 \times \dots \times X_m} c \, d\gamma + \varepsilon \text{Ent}(\gamma | \otimes_{i=1}^m \mu_i) \mid \gamma \in \Pi(\mu_1, \dots, \mu_m) \right\}, \quad (\text{MOT}_\varepsilon)$$

where $\Pi(\mu_1, \dots, \mu_m)$ denotes the set of all probability measures γ having μ_i for $i \in \{1, \dots, m\}$ as marginals. The classical multi-marginal optimal transport problem cor-

responds to the case where $\varepsilon = 0$. In the last decade, these two classes of problems (entropic optimal transport and multi-marginal optimal transport) have witnessed a growing interest and they are now an active research topic.

Entropic optimal transport (EOT) has found applications and proved to be an efficient way to approximate Optimal Transport (OT) problems, especially from a computational viewpoint. Indeed, when it comes to solving EOT by alternating Kullback-Leibler projections on the two marginal constraints, by the algebraic properties of the entropy such iterative projections correspond to the celebrated Sinkhorn’s algorithm [Sin64], applied in this framework in the pioneering works [Cut13; Ben+15]. The simplicity and the good convergence guarantees (see [FL89; MG20]) of this method compared to the algorithms used for the OT problems, then determined the success of EOT for applications in machine learning, statistics, image processing, language processing and other areas (see the monograph [PC19] and references therein).

As concerns multi-marginal optimal transport (MOT), it arises naturally in many different areas of applications, including economics [CE10], financial mathematics [BHP13; DS14a; DS14b; Enn+22], statistics [BK18; CCG16], image processing [Rab+11], tomography [Abr+17], machine learning [Haa+21; TJK22], fluid dynamics [Bre89] and quantum physics and chemistry, in the framework of density functional theory [BDG12; CFK13]. The structure of solutions to the multi-marginal optimal transport problem is a notoriously delicate issue, and is still not well understood, despite substantial efforts on the part of many researchers [GŚ98; Car03; CN08; Hei02; Pas11; Pas12; KP14; KP15; CDD15; CS16; PV21b; MP17; PV21a]; see also the surveys [Pas15] and [DGN15]. Since MOT_ε can be seen a perturbation of MOT_0 , it is natural to study the behaviour as ε vanishes. In this paper we are mainly interested in investigating the rate of convergence of the entropic cost MOT_ε to MOT_0 under some mild assumptions on the cost functions and marginals.

In particular we are going to extend the techniques introduced in [CPT23] for two marginals to the multi-marginal case which will also let us generalize the bounds in [CPT23] to the case of degenerate cost functions. For the two marginals and non-degenerate case we also refer the reader to a very recent (and elegant) paper [MS23] where the authors push a little further the analysis of the convergence rate by disentangling the roles of $\int c d\gamma$ and the relative entropy in the total cost and deriving convergence rate for both these terms. Notice that concerning the convergence rate of the entropic multi-marginal optimal transport an upper bound has been already established in [EN22], which depends on the number of marginals and the quantization dimension of the optimal solutions to (MOT_ε) with $\varepsilon = 0$. Here we provide a improved, smaller, upper bound, which will depend only on the marginals, but not on the optimal transport plans for the un-regularized problem, and we also provide a lower bound depending on a signature condition on the mixed second derivatives of the cost function, that was introduced in [Pas12].

Our main findings can be summarized as follows: we establish two **upper bounds**, one valid for locally Lipschitz costs and a finer one valid for locally semi-concave costs. The proofs rely, as in [CPT23], on a multi-marginal variant of the block approximation introduced in [Car+17]. Notice that in this case the bound will depend only on the

dimension of the support of the marginals. Moreover, for locally semi-concave cost functions, by exploiting Alexandrov-type results as in [CPT23], we improve the upper bound by a 1/2 factor, obtaining the following inequality for some $C^* \in \mathbb{R}_+$

$$\boxed{\text{MOT}_\varepsilon \leq \text{MOT}_0 + \frac{1}{2} \left(\sum_{i=1}^m d_i - \max_{1 \leq i \leq m} d_i \right) \varepsilon \log(1/\varepsilon) + C^* \varepsilon.} \quad (1.1)$$

We stress that this upper bound is smaller or equal than the one provided in [EN22, Theorem 3.8], which is of the form $\frac{1}{2}(m-1)D\varepsilon \log(1/\varepsilon) + O(\varepsilon)$ where D is a quantization dimension of the support of an optimal transport plan. Thus D must be greater or equal than the maximum dimension of the support of the marginals, and of course $\sum_{i=1}^m d_i - \max_{1 \leq i \leq m} d_i \leq (m-1) \max_{1 \leq i \leq m} d_i$. The inequality may be strict for example in the two marginals case with unequal dimension, as shown in Section 5.

For the **lower bound**, from the dual formulation of (MOT $_\varepsilon$) we have

$$\text{MOT}_\varepsilon \geq \text{MOT}_0 - \varepsilon \log \int_{\prod_{i=1}^m X_i} e^{-\frac{E(x_1, \dots, x_m)}{\varepsilon}} d \otimes_{i=1}^m \mu_i(x_i),$$

where $E(x_1, \dots, x_m) = c(x_1, \dots, x_m) - \oplus_{i=1}^m \phi_i(x_i)$ is the duality gap and (ϕ_1, \dots, ϕ_m) are Kantorovich potentials for the un-regularized problem (MOT $_\varepsilon$) with $\varepsilon = 0$. By using the singular values decomposition of the bilinear form obtained as an average of mixed second derivatives of the cost and a signature condition introduced in [Pas11], we are able to prove that E detaches quadratically from the set $\{E = 0\}$ and this allows us to estimate the previous integral in the desired way as in [CPT23] and improve the results in [EN22] where only an upper bound depending on the quantization dimension of the solution to the un-regularized problem is provided. Moreover, this slightly more flexible use of Minty's trick compared to [CPT23] allows us to obtain a lower bound also for degenerate cost functions in the two marginals setting. Given a κ depending on a signature condition (see (PS(κ))) on the second mixed derivatives of the cost, the lower bound can be summarized as follows

$$\boxed{\text{MOT}_\varepsilon \geq \text{MOT}_0 + \frac{\kappa}{2} \varepsilon \log(1/\varepsilon) - C_* \varepsilon.} \quad (1.2)$$

for some $C_* \in \mathbb{R}_+$.

The paper is organized as follows: in Section 2 we recall the multi-marginal optimal transport problem, some results concerning the structure of the optimal solution, in particular the ones in [Pas11], and define its entropy regularization. Section 3 is devoted to the upper bounds stated in Proposition 3.2 and Proposition 3.7. In Section 4 we establish the lower bound stated in Proposition 4.2. Finally, in Section 5 we provide some examples for which we can get the matching bounds.

2 Preliminaries

Given m probability compactly supported measures μ_i on sub-manifolds X_i of dimension d_i in \mathbb{R}^N for $i = 1, 2, \dots, m$ and a continuous cost function $c : X_1 \times X_2 \times \dots \times X_m \rightarrow \mathbb{R}_+$,

the multi-marginal optimal transport problem consists in solving the following optimization problem

$$\text{MOT}_0 := \inf_{\gamma \in \Pi(\mu_1, \dots, \mu_m)} \int_{\mathbf{X}} c(x_1, \dots, x_m) d\gamma \quad (\text{MOT})$$

where $\mathbf{X} := X_1 \times X_2 \times \dots \times X_m$ and $\Pi(\mu_1, \dots, \mu_m)$ denotes the set of probability measures on \mathbf{X} whose marginals are the μ_i . The formulation above is also known as the *Kantorovich problem* and it amounts to a linear minimization problem over a convex, weakly compact set; it is then not difficult to prove the existence of a solution by the direct method of calculus of variations. Much of the attention in the optimal transport community is rather focused on uniqueness and the structure of the minimizers. In particular one is mainly interested in determining if the solution is concentrated on the graph of a function (T_2, \dots, T_m) over the first marginal, where $(T_i)_\# \mu_1 = \mu_i$ for $i = 1, \dots, m$, in which case this function induces a solution *à la Monge*, that is $\gamma = (\text{Id}, T_2, \dots, T_m)_\# \mu_1$.

In the two marginals setting, the theory is fairly well understood and it is well-known that under mild conditions on the cost function (e.g. twist condition) and marginals (e.g. being absolutely continuous with respect to Lebesgue), the solution to (MOT) is unique and is concentrated on the graph of a function; we refer the reader to [San15] to have a glimpse of it. The extension to the multi-marginal case is still not well understood, but it has attracted recently a lot of attention due to a diverse variety of applications. In particular in his seminal works [Pas11; Pas12] Pass established some conditions, more restrictive than in the two marginals case, to ensure the existence of a solution concentrated on a graph. In this work we rely on the following (local) result in [Pas12] giving an upper bound on the dimension of the support of the solution to (MOT). Let P be the set of partitions of $\{1, \dots, m\}$ into two non-empty disjoint subsets: $p = \{p_-, p_+\} \in P$ if $p_- \cup p_+ = \{1, \dots, m\}$, $p_- \cap p_+ = \emptyset$ and $p_-, p_+ \neq \emptyset$. Then for each $p \in P$ we denote by g_p the bilinear form on \mathbf{X} as

$$g_p = D_{p_- p_+}^2 c + D_{p_+ p_-}^2 c \quad \text{where} \quad D_{pq}^2 c := \sum_{i \in p, j \in q} D_{x_i x_j}^2 c$$

for every $p, q \subseteq \{1, \dots, m\}$, and $D_{x_i x_j}^2 c := \sum_{\alpha_i, \alpha_j} \frac{\partial^2 c}{x_i^{\alpha_i} x_j^{\alpha_j}} dx_i^{\alpha_i} \otimes dx_j^{\alpha_j}$, defined for every i, j on the whole tangent bundle $T\mathbf{X}$.

Define $G := \{\sum_{p \in P} t_p g_p \mid (t_p)_{p \in P} \in \Delta_P\}$ to be the convex hull generated by the g_p , then it is easy to verify that each $g \in G$ is symmetric and therefore its signature is well defined. Then, the following result from [Pas12] gives a control on the dimension of the support of the optimizer(s) in terms of these signatures.

Theorem 2.1 (Part of [Pas12, Theorem 2.3]). *Let γ a solution to (MOT) and suppose that at some point $\mathbf{x} \in \mathbf{X}$, the signature of some $g \in G$ is (d^+, d^-, d^0) , that is the number of positive, negative and zero eigenvalues. Then, there exists a neighbourhood $N_{\mathbf{x}}$ of \mathbf{x} such that $N_{\mathbf{x}} \cap \text{spt } \gamma$ is contained in a Lipschitz sub-manifold of \mathbf{X} with dimension no greater than $\sum_{i=1}^m d_i - d^+(g(\mathbf{x}))$.*

Remark 2.2. For the following it is important to notice that by standard linear algebra arguments we have for each $g \in G$ that $d^+(g) \leq \sum_{i=1}^m d_i - \max_i d_i$. This implies that the smallest bound on the dimension of $\text{spt } \gamma$ which [Theorem 2.1](#) can provide is $\max_i d_i$.

Remark 2.3 (Two marginals case). When $m = 2$, the only $g \in G$ coincides precisely with the pseudo-metric introduced by Kim-McCann in [\[KM10\]](#). Assuming for simplicity that $d_1 = d_2 = d$, they noted that g has signature $(d, d, 0)$ whenever c is non-degenerate so [Theorem 2.1](#) generalizes their result since it applies even when non-degeneracy fails providing new information in the two marginals case: the signature of g is $(r, r, 2d - 2r)$ where r is the rank of $D_{x_1 x_2}^2 c$. Notice that this will help us to generalize the results established in [\[CPT23; EN22\]](#) to the case of a degenerate cost function.

It is well known that under some mild assumptions the Kantorovich problem [\(MOT\)](#) is dual to the following

$$\sup \left\{ \sum_{i=1}^m \int_{X_i} \phi_i(x_i) d\mu_i \mid \phi_i \in \mathcal{C}_b(X_i), \sum_{i=1}^m \phi_i(x^i) \leq c(x_1, \dots, x_m) \right\}. \quad (\text{MD})$$

We recall the entropic counterpart of [\(MOT\)](#): given m probability measures μ_i on X_i as before, and a continuous cost function $c : \mathbf{X} \rightarrow \mathbb{R}_+$ the MOT_ε problem is

$$\text{MOT}_\varepsilon = \inf_{\gamma \in \Pi(\mu_1, \dots, \mu_m)} \int_{\mathbf{X}} c d\gamma + \varepsilon \text{Ent}(\gamma \mid \otimes_{i=1}^m \mu_i), \quad (\text{MOT}_\varepsilon)$$

where $\text{Ent}(\cdot \mid \otimes_{i=1}^m \mu_i)$ is the Boltzmann-Shannon relative entropy (or Kullback-Leibler divergence) w.r.t. the product measure $\otimes_{i=1}^m \mu_i$, defined for general probability measures p, q as

$$\text{Ent}(p \mid q) = \begin{cases} \int_{\mathbb{R}^d} \rho \log(\rho) dq & \text{if } p = \rho q, \\ +\infty & \text{otherwise.} \end{cases}$$

The fact that q is a probability measure ensures that $\text{Ent}(p \mid q) \geq 0$. The dual problem of [\(MOT\)_\varepsilon](#) reads as

$$\text{MOT}_\varepsilon = \varepsilon + \sup \left\{ \sum_{i=1}^m \int_{X_i} \phi_i(x_i) d\mu_i - \varepsilon \int_{\mathbf{X}} e^{\frac{\sum_{i=1}^m \phi_i(x_i) - c(\mathbf{x})}{\varepsilon}} d \otimes_{i=1}^m \mu_i \mid \phi_i \in \mathcal{C}_b(X_i) \right\}, \quad (\text{MD}_\varepsilon)$$

which is invariant by $(\phi_1, \dots, \phi_m) \mapsto (\phi_1 + \lambda_1, \dots, \phi_m + \lambda_m)$ where $(\lambda_1, \dots, \lambda_m) \in \mathbb{R}^m$ and $\sum_{i=1}^m \lambda_i = 0$, see [\[Léo14; NW22; MG20\]](#) for some recent presentations. It admits an equivalent “log-sum-exp” form:

$$\text{MOT}_\varepsilon = \sup \left\{ \sum_{i=1}^m \int_{X_i} \phi_i(x_i) d\mu_i - \varepsilon \log \left(\int_{\mathbf{X}} e^{\frac{\sum_{i=1}^m \phi_i(x_i) - c(\mathbf{x})}{\varepsilon}} d \otimes_{i=1}^m \mu_i \right) \mid \phi_i \in \mathcal{C}_b(X_i) \right\}, \quad (\text{MD}'_\varepsilon)$$

which is invariant by the same transformations without assuming $\sum_{i=1}^m \lambda_i = 0$.

From [\(MOT\)_\varepsilon](#) and [\(MD\)_\varepsilon](#) we recover, as $\varepsilon \rightarrow 0$, the unregularized multi-marginal optimal transport [\(MOT\)](#) and its dual [\(MD\)](#) we have introduced above. The link between

multi-marginal optimal transport and its entropic regularization is very strong and a consequence of the Γ -convergence of (MOT_ε) towards (MOT) (one can adapt the proof in [Car+17] or see [BCN19; GKR20] for Γ -convergence in some specific cases) is that

$$\lim_{\varepsilon \rightarrow 0} \text{MOT}_\varepsilon = \text{MOT}_0.$$

By the direct method in the calculus of variations and strict convexity of the entropy, one can show that (MOT_ε) admits a unique solution γ_ε , called *optimal entropic plan*. Moreover, there exist m real-valued Borel functions ϕ_i^ε such that

$$\gamma_\varepsilon = \exp\left(\frac{\bigoplus_{i=1}^m \phi_i^\varepsilon - c}{\varepsilon}\right) \otimes_{i=1}^m \mu_i, \quad (2.1)$$

where $\bigoplus_{i=1}^m \phi_i^\varepsilon := (x_1, \dots, x_m) \mapsto \sum_{i=1}^m \phi_i^\varepsilon(x_i)$, and in particular we have that that

$$\text{MOT}_\varepsilon = \sum_{i=1}^m \int_{X_i} \phi_i^\varepsilon \, d\mu_i \quad (2.2)$$

and these functions, which have continuous representatives, are a.s. uniquely determined up to additive constants. The reader is referred to the analysis of [MG20], to [Nen16] for the extension to the multi-marginal setting, and to [BL92; BLN94; Csi75; FG97; RT98] for earlier references on the two marginals framework.

The functions ϕ_i^ε in (2.1) are called *Schrödinger potentials*, the terminology being motivated by the fact that they solve the dual problem (MD_ε) . Furthermore, ϕ_i^ε are the (unique) solutions to the so-called *Schrödinger system*

$$\phi_i(x_i) = -\varepsilon \log \int_{\mathbf{X}_{-i}} e^{\frac{\bigoplus_{j=1, j \neq i}^m \phi_j^\varepsilon - c(x)}{\varepsilon}} \, d \otimes_{j=1, j \neq i}^m \mu_j \text{ for } \mu_i\text{-a.e. } x_i, \forall i = 1, \dots, m, \quad (2.3)$$

where $\mathbf{X}_{-i} = \prod_{j=1, j \neq i}^m X_j$. Note that (2.3) is a softmin version of the multi-marginal c -conjugacy relation for Kantorovich potentials.

3 Upper bounds

We start by establishing an upper bound, which will depend on the dimension of the marginals, for locally Lipschitz cost functions. We will then improve it for locally semi-concave (in particular \mathcal{C}^2) cost functions.

3.1 Upper bound for locally Lipschitz costs

The natural notion of dimension which arises in our context is the *entropy dimension*, also called *information dimension* or *Rényi dimension* [Rén59].

Definition 3.1 (Rényi dimension [You82]). If μ is a probability measure over a sub-manifold X of \mathbb{R}^d , we set for every $\delta > 0$,

$$H_\delta(\mu) = \inf \left\{ \sum_{n \in \mathbb{N}} \mu(A_n) \log(1/\mu(A_n)) : \forall n, \text{diam}(A_n) \leq \delta, \text{ and } X = \bigsqcup_{n \in \mathbb{N}} A_n \right\},$$

where the infimum is taken over countable partitions $(A_n)_{n \in \mathbb{N}}$ of X by Borel subsets of diameter less than δ , and we define the *lower and upper entropy dimension* of μ respectively by:

$$\underline{\dim}_R(\mu) := \liminf_{\delta \rightarrow 0^+} \frac{H_\delta(\mu)}{\log(1/\delta)}, \quad \overline{\dim}_R(\mu) := \limsup_{\delta \rightarrow 0^+} \frac{H_\delta(\mu)}{\log(1/\delta)}.$$

Notice that if μ is compactly supported on a Lipschitz manifold of dimension d , then $N_\delta(\text{spt } \mu) \leq d \log(1/\delta) + C$ for some constant $C > 0$ and $\delta \in (0, 1]$, where $N_\delta(\text{spt } \mu)$ is the box-counting number of $\text{spt } \mu$, i.e. the minimal number of sets of diameter $\delta > 0$ which cover $\text{spt } \mu$. In particular, by concavity of $t \mapsto t \log(1/t)$, we have

$$H_\delta(\mu) \leq \log N_\delta(\text{spt } \mu). \quad (3.1)$$

We refer to the beginning of [CPT23, §3.1] for additional information and references on Rényi dimension.

The following proposition establishes an upper bound for locally Lipschitz costs.

Proposition 3.2. *Assume that $\mu_i \in \mathcal{P}(X_i)$ for $i \in \{1, \dots, m\}$ are compactly supported measures on Lipschitz sub-manifolds of dimension d_i , respectively, and c is of class $\mathcal{C}_{\text{loc}}^{0,1}(\mathbf{X})$, then*

$$\boxed{\text{MOT}_\varepsilon \leq \text{MOT}_0 + \left(\sum_{i=1}^m d_i - \max_{j=1, \dots, m} d_j \right) \varepsilon \log(1/\varepsilon) + O(\varepsilon).} \quad (3.2)$$

Proof. Given an optimal plan γ_0 for MOT_0 , we use the so-called “block approximation” introduced in [Car+17]. For every $\delta > 0$ and i , consider a partition $X_i = \bigsqcup_{n \in \mathbb{N}} A_i^n$ of Borel sets such that $\text{diam}(A_i^n) \leq \delta$ for every $n \in \mathbb{N}$, and set

$$\mu_i^n := \begin{cases} \frac{\mu_i \llcorner A_i^n}{\mu_i(A_i^n)} & \text{if } \mu_i(A_i^n) > 0, \\ 0 & \text{otherwise,} \end{cases}$$

then for every m -uple $n = (n_1, \dots, n_m) \in \mathbb{N}^m$,

$$(\gamma_0)^n := \gamma_0(A_1^{n_1} \times \dots \times A_m^{n_m}) \mu_1^{n_1} \otimes \dots \otimes \mu_m^{n_m},$$

and finally,

$$\gamma_\delta := \sum_{n \in \mathbb{N}^m} (\gamma_0)^n.$$

By definition, $\gamma_\delta \ll \otimes_i \mu_i$ and we may check that its marginals are μ_i . Besides, for $\otimes_i \mu_i$ -almost every $\mathbf{x} = (x_1, \dots, x_m) \in \prod_{i=1}^m A_i^{n_i}$,

$$\frac{d\gamma_\delta}{d \otimes_i \mu_i}(x_1, \dots, x_m) := \begin{cases} \frac{\gamma_0(A_1^{n_1} \times \dots \times A_m^{n_m})}{\mu_1(A_1^{n_1}) \dots \mu_m(A_m^{n_m})} & \text{if } \mu_1(A_1^{n_1}) \dots \mu_m(A_m^{n_m}) > 0 \\ 0 & \text{otherwise.} \end{cases}$$

Let us compute its entropy and assume for simplicity that the measure μ_m is the one such that $\overline{\dim}_R(\mu_m) = \max_{i=1, \dots, m} \overline{\dim}(\mu_i)$:

$$\begin{aligned} \text{Ent}(\gamma_\delta | \otimes_{i=1}^m \mu_i) &= \sum_{n \in \mathbb{N}^m} \int_{\prod_{i=1}^m A_i^{n_i}} \log \left(\frac{\gamma_0(A_1^{n_1} \times \dots \times A_m^{n_m})}{\mu_1(A_1^{n_1}) \dots \mu_m(A_m^{n_m})} \right) d\gamma_\delta \\ &= \sum_{n \in \mathbb{N}^m} \gamma_0(A_1^{n_1} \times \dots \times A_m^{n_m}) \log \left(\frac{\gamma_0(A_1^{n_1} \times \dots \times A_m^{n_m})}{\mu_1(A_1^{n_1}) \dots \mu_m(A_m^{n_m})} \right) \\ &= \sum_{n \in \mathbb{N}^m} \gamma_0(A_1^{n_1} \times \dots \times A_m^{n_m}) \log \left(\frac{\gamma_0(A_1^{n_1} \times \dots \times A_m^{n_m})}{\mu_m(A_m^{n_m})} \right) \\ &\quad + \sum_{j=1}^{m-1} \sum_{n \in \mathbb{N}^m} \gamma_0(A_1^{n_1} \times \dots \times A_m^{n_m}) \log(1/\mu_j(A_j^{n_j})) \\ &= \sum_{n \in \mathbb{N}^m} \gamma_0(A_1^{n_1} \times \dots \times A_m^{n_m}) \log \left(\frac{\gamma_0(A_1^{n_1} \times \dots \times A_m^{n_m})}{\mu_m(A_m^{n_m})} \right) \\ &\quad + \sum_{j=1}^{m-1} \sum_{n \in \mathbb{N}^{m-1}} \mu_j(A_j^{n_j}) \log(1/\mu_j(A_j^{n_j})) \\ &\leq \sum_{j=1}^{m-1} \sum_{n \in \mathbb{N}^{m-1}} \mu_j(A_j^{n_j}) \log(1/\mu_j(A_j^{n_j})). \end{aligned}$$

the last inequality coming from the inequality $\gamma_0(A_1^{n_1} \times \dots \times A_m^{n_m}) \leq \mu_m(A_m^{n_m})$. Taking 1-optimal partitions $(A_j^n)_{n \in \mathbb{N}}$ of diameter smaller than δ in the definition of $H_\delta(\mu_j)$, we get by definition of H_δ ,

$$\text{Ent}(\gamma_\delta | \otimes_{i=1}^m \mu_i) \leq \sum_{j=1}^{m-1} H_\delta(\mu_j) + 1.$$

Notice that $W_\infty(\gamma_\delta, \gamma_0) \leq \delta$ (taking the ℓ^∞ norm), thus taking γ_δ as competitor in

(MOT $_\varepsilon$) we obtain

$$\begin{aligned}
\text{MOT}_\varepsilon &\leq \int c \, d\gamma_\delta + \varepsilon \sum_{j \leq m-1} H_\delta(\mu_j) + \varepsilon \\
&\leq \text{MOT}_0 + \sum_{j_1, \dots, j_m} \int_{B_{j_1, \dots, j_m}} c \, d(\gamma_\delta - \gamma_0) + \varepsilon \sum_{j \leq m-1} H_\delta(\mu_j) + \varepsilon \\
&\leq \text{MOT}_0 + \sum_{j_1, \dots, j_m} [c]_{\mathcal{C}^{0,1}(B_{j_1, \dots, j_m})} W_1(\gamma_\delta \llcorner B_{j_1, \dots, j_m}, \gamma_0 \llcorner B_{j_1, \dots, j_m}) + \varepsilon \sum_{j \leq m-1} H_\delta(\mu_j) + \varepsilon \\
&\leq \text{MOT}_0 + L\delta + \varepsilon \sum_{j \leq m-1} \frac{H_\delta(\mu_j)}{\log(1/\delta)} \log(1/\delta) + \varepsilon,
\end{aligned} \tag{3.3}$$

where we have considered a covering of each sub-manifold X_i , that is $X_i \subseteq \bigcup_{j_i} B_{\delta_0}(a_i^{j_i})$ with $\delta \leq \delta_0$, $B_{j_1, \dots, j_m} = B_{\delta_0}(a_1^{j_1}) \times \dots \times B_{\delta_0}(a_m^{j_m})$ for all j_1, \dots, j_m and

$$L = \sum_{j_1, \dots, j_m} [c]_{\mathcal{C}^{0,1}(B_{j_1, \dots, j_m})}.$$

Taking $\delta = \varepsilon$ and considering that μ_i are concentrated on sub-manifolds of dimension d_i then $H_\delta(\mu_i) \leq d_i \log(1/\delta) + C^* - 1$ for some $C^* \geq 1$ and we get

$$\text{MOT}_\varepsilon \leq \text{MOT}_0 + \left(\sum_{j \leq m-1} d_j \right) \varepsilon \log(1/\varepsilon) + C^* \varepsilon.$$

□

Remark 3.3. Notice that by taking $m = 2$ and $d_1 = d_2 = d$, one easily retrieves the results in [CPT23]. Besides, if the μ_i 's are merely assumed to have compact support (not necessarily supported on a sub-manifold), the same proof actually shows the slightly weaker estimate

$$\text{MOT}_\varepsilon \leq \text{MOT}_0 + \left(\sum_{i=1}^m \overline{\dim}_R(\mu_i) - \max_{j=1, \dots, m} \overline{\dim}_R(\mu_j) \right) \varepsilon \log(1/\varepsilon) + o(\varepsilon \log(1/\varepsilon)). \tag{3.4}$$

3.2 Upper bound for locally semi-concave costs

We provide now a finer upper bound under the additional assumptions that the X_i 's are \mathcal{C}^2 sub-manifolds of \mathbb{R}^N , c is locally semi-concave as in Definition 3.4 (in particular if $c \in \mathcal{C}^2(\mathbf{X}, \mathbb{R}_+)$), and the μ_i 's are measures in $L^\infty(\mathcal{H}_{X_i}^{d_i})$ with compact support in X_i .

Definition 3.4. A function $f : X \rightarrow \mathbb{R}$ defined on a \mathcal{C}^2 sub-manifold $X \subseteq \mathbb{R}^N$ of dimension d is *locally semiconcave* if for every $x \in X$ there exists a local chart (i.e. a \mathcal{C}^2 diffeomorphism) $\psi : U \rightarrow \Omega$ where $U \subseteq X$ is an open neighborhood of x and Ω is an open convex subset of \mathbb{R}^d , such that $f \circ \psi^{-1}$ is λ -concave for some $\lambda \in \mathbb{R}$, meaning $f \circ \psi^{-1} - \lambda|\cdot|^2$ is concave on Ω .

Lemma 3.5 (Local semiconcavity and covering). *Let $c : \mathbf{X} \rightarrow \mathbb{R}_+$ be a locally semiconcave cost function and $(\phi_i)_{1 \leq i \leq m} \in \prod_{1 \leq i \leq m} \mathcal{C}(K_i)$ be a system of c -conjugate functions defined on compact subsets $K_i \subseteq X_i$. We can find for every $i \in \{1, \dots, m\}$ a finite open covering $(U_i^j)_{1 \leq j \leq J}$ of K_i and local charts $\psi_i^j : U_i^j \rightarrow \Omega_i^j$ such that for some $\lambda \in \mathbb{R}$:*

(i) *for every $\mathbf{j} = (j_1, \dots, j_m) \in \{1, \dots, J\}^m$, $c \circ (\psi^{\mathbf{j}})^{-1}$ is λ -concave on $\Omega^{\mathbf{j}} := \prod_{1 \leq i \leq m} \Omega_i^{j_i}$,*

(ii) *for every $(i, j) \in \{1, \dots, m\} \times \{1, \dots, J\}$, $\phi_i \circ (\psi_i^j)^{-1}$ is λ -concave on Ω_i^j .*

In particular, all the ϕ_i 's are locally semiconcave.

Proof. For every i , by compactness of the K_i 's we can find a finite open covering $(U_i^j)_{1 \leq j \leq J}$ of K_i and local charts $\psi_i^j : U_i^j \rightarrow \Omega_i^j$ such that for every $\mathbf{j} = (j_1, \dots, j_m) \in \{1, \dots, J\}^m$, $c \circ (\psi^{\mathbf{j}})^{-1} - \lambda |\cdot|^2$ is concave for some $\lambda_j \in \mathbb{R}$, where $\psi^{\mathbf{j}} := (\psi_1^{j_1}, \dots, \psi_m^{j_m})$. We may assume that $\lambda_j = \lambda$ for every \mathbf{j} , by taking $\lambda = \max\{\lambda_j : \mathbf{j} \in \{1, \dots, J\}^m\}$. Fix $i \in \{1, \dots, m\}$, $j \in \{1, \dots, J\}$, then for every $\mathbf{k} = (k_\ell)_{\ell \neq i} \in \{1, \dots, J\}^{m-1}$ set $\Omega^{\mathbf{k}} = \prod_{\ell \neq i} \Omega_\ell^{k_\ell}$ and $\psi^{\mathbf{k}} = (\psi_1^{k_1}, \dots, \psi_{i-1}^{k_{i-1}}, \psi_i^j, \psi_{i+1}^{k_{i+1}}, \dots)$. Notice that for every $y \in \Omega_i^j$,

$$\begin{aligned} \phi_i \circ (\psi_i^j)^{-1}(y) &= \inf_{(x_\ell)_{\ell \neq i}} c(x_1, \dots, x_{i-1}, (\psi_i^j)^{-1}(y), x_{i+1}, \dots) - \sum_{\ell \neq i} \phi_\ell(x_\ell) \\ &= \min_{\mathbf{k}} \inf_{(y_\ell)_{\ell \neq i} \in \Omega^{\mathbf{k}}} c \circ (\psi^{\mathbf{k}})^{-1}(y_1, \dots, y_{i-1}, y, y_{i+1}, \dots) - \sum_{\ell \neq i} \phi_\ell \circ (\psi_\ell^{k_\ell})^{-1}(y_\ell), \end{aligned}$$

and we see that it is λ -concave as an infimum of λ -concave functions. \square

We are going to use an integral variant of Alexandrov Theorem which is proved in [CPT23].

Lemma 3.6 (Lemma 3.6 [CPT23]). *Let $f : \Omega \rightarrow \mathbb{R}$ be a λ -concave function defined on a convex open set $\Omega \subseteq \mathbb{R}^d$, for some $\lambda \geq 0$. There exists a constant $C \geq 0$ depending only on d such that:*

$$\int_{\Omega} \sup_{y \in B_r(x) \cap \Omega} |f(y) - (f(x) + \nabla f(x) \cdot (y - x))| dx \leq Cr^2 \mathcal{H}^{d-1}(\partial\Omega) ([f]_{\mathcal{C}^{0,1}(\Omega)} + \lambda \text{diam}(\Omega)). \quad (3.5)$$

Proposition 3.7. *Let $c \in \mathcal{C}^2(\mathbf{X})$ and assume that for every $i \in \{1, \dots, m\}$, $X_i \subseteq \mathbb{R}^N$ is a \mathcal{C}^2 sub-manifold of dimension d_i and $\mu_i \in L^\infty(\mathcal{H}_{X_i}^{d_i})$ is a probability measure compactly supported in X_i . Then there exists a constant $C^* \geq 0$ such that*

$$\boxed{\text{MOT}_\varepsilon \leq \text{MOT}_0 + \frac{1}{2} \left(\sum_{i=1}^m d_i - \max_{1 \leq i \leq m} d_i \right) \varepsilon \log(1/\varepsilon) + C^* \varepsilon.} \quad (3.6)$$

Proof. The measures μ_i being compactly supported in X_i , take for every $i \in \{1, \dots, m\}$ an open subset U_i such that $\text{spt } \mu_i \subseteq U_i \Subset X_i$ and define the compact set $K_i \subseteq \bar{U}_i$.

Take $(\phi_i)_{1 \leq i \leq m} \in \prod_{1 \leq i \leq m} \mathcal{C}(K_i)$ a m -uple of c -conjugate Kantorovich potentials and a transport plan $\gamma_0 \in \bar{\Pi}(\mu_1, \dots, \mu_m)$ which are optimal for the unregularized problems. In particular,

$$\begin{aligned} E &:= c - \bigoplus_{i=1}^m \phi_i \geq 0 \quad \text{on} \quad \mathbf{U} := \prod_{1 \leq i \leq m} U_i, \\ E &= 0 \quad \text{on} \quad \text{spt } \gamma_0 \subseteq \mathbf{U}. \end{aligned} \tag{3.7}$$

For every i we consider the coverings $(U_i^j)_{1 \leq j \leq J}$ provided by [Lemma 3.5](#) and we notice by compactness that there exists open subsets $\tilde{U}_i^j \Subset U_i^j$ such that $(\tilde{U}_i^j)_{1 \leq j \leq J}$ is still an open covering of K_i and such that for a small $\delta_0 > 0$, the δ_0 -neighbourhood of $\tilde{\Omega}_i^j := \psi_i^j(\tilde{U}_i^j)$ is included in Ω_i^j . For $\delta \in (0, \delta_0)$ we consider the block approximation γ_δ of γ_0 built in the proof of [Proposition 3.2](#), as well as $\kappa_\delta \in \Pi(\gamma_0, \gamma_\delta)$ such that $\sup_{(\mathbf{x}_0, \mathbf{x}) \in \text{spt } \kappa_\delta} \|\mathbf{x}_0 - \mathbf{x}\| \leq \delta$. For every $\mathbf{j} = (j_1, \dots, j_m) \in \{1, \dots, m\}$, we set $E^{\mathbf{j}} := E \circ (\psi^{\mathbf{j}})^{-1}$ and $U^{\mathbf{j}} := \prod_{i=1}^m U_i^{j_i}$, and we write:

$$\begin{aligned} \int_{\mathbf{X}} c \, d\gamma_\delta - \int_{\mathbf{X}} c \, d\gamma_0 &= \int_{\mathbf{X}} E \, d\gamma_\delta \\ &= \int_{\mathbf{X} \times \mathbf{X}} E(\mathbf{x}) \, d\kappa_\delta(\mathbf{x}_0, \mathbf{x}) \\ &\leq \sum_{\mathbf{j}=(j_1, \dots, j_m)} \int_{(\mathbf{x}_0, \mathbf{x}) \in \tilde{U}^{\mathbf{j}} \times \mathbf{X}} E(\mathbf{x}) \, d\kappa_\delta(\mathbf{x}_0, \mathbf{x}) \\ &\leq \sum_{\mathbf{j}=(j_1, \dots, j_m)} \int_{(\mathbf{x}_0, \mathbf{x}) \in (U^{\mathbf{j}})^2} E^{\mathbf{j}}(\psi^{\mathbf{j}}(\mathbf{x})) \, d\kappa_\delta(\mathbf{x}_0, \mathbf{x}). \end{aligned}$$

Notice that for γ_0 -a.e. $\mathbf{x}_0 \in U^{\mathbf{j}}$, $E^{\mathbf{j}}$ is differentiable at $\psi^{\mathbf{j}}(\mathbf{x}_0)$, or equivalently E is differentiable at \mathbf{x}_0 . Indeed c is differentiable everywhere, and for every i, j , $\phi_i \circ (\psi_i^j)^{-1}$ is semi-concave thus differentiable \mathcal{L}^{d_i} -a.e. and hence ϕ_i is differentiable μ_i -a.e. because $\mu_i \ll \mathcal{H}^{d_i}$ and ψ_i^j is bi-Lipschitz, which in turn implies that $\bigoplus_{i=1}^m \phi$ is differentiable γ_0 -a.e. because $\gamma_0 \in \Pi(\mu_1, \dots, \mu_m)$. Moreover, by [\(3.7\)](#) we have $T_{\psi^{\mathbf{j}}(\mathbf{x}_0)} E^{\mathbf{j}} \equiv 0$ for γ_0 -a.e. $\mathbf{x}_0 \in U^{\mathbf{j}}$. We may then compute:

$$\begin{aligned} &\int_{\mathbf{X}} c \, d\gamma_\delta - \int_{\mathbf{X}} c \, d\gamma_0 \\ &\leq \sum_{\mathbf{j}=(j_1, \dots, j_m)} \int_{(\mathbf{x}_0, \mathbf{x}) \in (U^{\mathbf{j}})^2} \left(E^{\mathbf{j}}(\psi^{\mathbf{j}}(\mathbf{x})) - T_{\psi^{\mathbf{j}}(\mathbf{x}_0)} E^{\mathbf{j}}(\psi^{\mathbf{j}}(\mathbf{x}) - \psi^{\mathbf{j}}(\mathbf{x}_0)) \right) \, d\kappa_\delta(\mathbf{x}_0, \mathbf{x}) \\ &= \sum_{\mathbf{j}=(j_1, \dots, j_m)} \left(\int_{(\mathbf{x}_0, \mathbf{x}) \in (U^{\mathbf{j}})^2} \left(c^{\mathbf{j}}(\psi^{\mathbf{j}}(\mathbf{x})) - T_{\psi^{\mathbf{j}}(\mathbf{x}_0)} c^{\mathbf{j}}(\psi^{\mathbf{j}}(\mathbf{x}) - \psi^{\mathbf{j}}(\mathbf{x}_0)) \right) \, d\kappa_\delta(\mathbf{x}_0, \mathbf{x}) + \right. \\ &\quad \left. \sum_{1 \leq i \leq m} \int_{(x_0, x) \in (U_i^{j_i})^2} \left(\phi_i^{j_i}(\psi_i^{j_i}(x)) - T_{\psi_i^{j_i}(x_0)} \phi_i^{j_i}(\psi_i^{j_i}(x) - \psi_i^{j_i}(x_0)) \right) \, d(e_i, e_i) \# \kappa_\delta(x_0, x) \right). \end{aligned} \tag{3.8}$$

Now, since c^j is λ -concave on each $\Omega^j := \psi^j(U^j)$, whenever $\|\mathbf{x}_0 - \mathbf{x}\| \leq \delta$ we have

$$c^j(\psi^j(\mathbf{x})) - T_{\psi^j(\mathbf{x}_0)} c^j(\psi^j(\mathbf{x}) - \psi^j(\mathbf{x}_0)) \leq \lambda \frac{\|\psi^j(\mathbf{x}) - \psi^j(\mathbf{x}_0)\|^2}{2} \leq \frac{\lambda L^j}{2} \delta^2, \quad (3.9)$$

where $L^j := \max\{\text{Lip}(\psi^j), \text{Lip}((\psi^j)^{-1})\}$. Besides, we may apply [Lemma 3.6](#) to each $\phi_i^{j_i}$ over $\Omega_i^{j_i}$ to get

$$\begin{aligned} & \int_{(x_0, x) \in (U_i^{j_i})^2} \left(\phi_i^{j_i}(\psi_i^{j_i}(x)) - T_{\psi_i^{j_i}(x_0)} \phi_i^{j_i}(\psi_i^{j_i}(x) - \psi_i^{j_i}(x_0)) \right) \\ & \leq \int_{x_0 \in U_i^{j_i}} \sup_{y \in B_{L^j \delta}(\psi_i^{j_i}(x_0)) \cap \Omega_i^{j_i}} \left| \phi_i^{j_i}(y) - T_{\psi_i^{j_i}(x_0)} \phi_i^{j_i}(y - \psi_i^{j_i}(x_0)) \right| d(e_i, e_i)_{\#} \kappa_{\delta}(x_0, x) \\ & = \int_{U_i^{j_i}} \sup_{y \in B_{L^j \delta}(\psi_i^{j_i}(x_0)) \cap \Omega_i^{j_i}} \left| \phi_i^{j_i}(y) - T_{\psi_i^{j_i}(x_0)} \phi_i^{j_i}(y - \psi_i^{j_i}(x_0)) \right| d\mu_i(x_0) \\ & \leq \int_{\Omega_i^{j_i}} \sup_{y \in B_{L^j \delta}(y_0) \cap \Omega_i^{j_i}} \left| \phi_i^{j_i}(y) - T_{y_0} \phi_i^{j_i}(y - y_0) \right| d(\psi_i^{j_i})_{\#} \mu_i(y_0) \\ & \leq \|\mu_i\|_{L^\infty(\mathcal{H}^{d_i})} L^j C (L^j \delta)^2 \mathcal{H}^{d_i-1}(\partial \Omega_i^{j_i}) \left([\phi_i^{j_i}]_{\mathcal{C}^{0,1}(\Omega_i^{j_i})} + \lambda \text{diam}(\Omega_i^{j_i}) \right) \\ & \leq C^j \delta^2, \end{aligned} \quad (3.10)$$

for some constant $C^j \in (0, +\infty)$. Reporting [\(3.9\)](#) and [\(3.10\)](#) in [\(3.8\)](#) yields

$$\int_{\mathbf{X}} c d\gamma_{\delta} - \int_{\mathbf{X}} c d\gamma_0 \leq \sum_{j=1}^m \left(\frac{\lambda L^j}{2} + C^j \right) \delta^2 =: C' \delta^2.$$

Finally, we proceed as in the end of the proof of [Proposition 3.2](#), taking γ_{δ} as competitor in the primal formulation [\(MOT \$_{\varepsilon}\$ \)](#), so as to obtain

$$\begin{aligned} \text{MOT}_{\varepsilon} - \text{MOT}_0 & \leq \int_{\mathbf{X}} c d\gamma_{\delta} - \int_{\mathbf{X}} c d\gamma_0 + \varepsilon \sum_{i \leq m-1} H_{\delta}(\mu_j) + \varepsilon \\ & \leq C' \delta^2 + \varepsilon \sum_{i \leq m-1} (d_i \log(1/\delta) + C''), \end{aligned}$$

where $C'' \in (0, +\infty)$ is a constant such that $H_{\delta}(\mu_i) \leq d_i \log(1/\delta) + C'' - 1$. Taking $\delta = \sqrt{\varepsilon}$ provides the desired estimate

$$\text{MOT}_{\varepsilon} - \text{MOT}_0 \leq \frac{1}{2} \left(\sum_{i=1}^{m-1} d_i \right) \varepsilon \log(1/\varepsilon) + (C' + C'') \varepsilon,$$

recalling that the index $i = m$ was chosen merely to simplify notations. \square

4 Lower bound for \mathcal{C}^2 costs with a signature condition

In this section we consider a cost $c \in \mathcal{C}^2(\mathbf{X}, \mathbb{R}_+)$ where $\mathbf{X} = X_1 \times \dots \times X_m$ and $X_i \subseteq \mathbb{R}^N$ is a \mathcal{C}^2 sub-manifold of dimension d_i and $\text{spt } \mu_i$ is a compact subset of X_i for every $i \in \{1, \dots, m\}$. If g is a bilinear form we denote by $(d^+(g), d^-(g), d^0(g))$ its signature.

Lemma 4.1. *Let $c \in \mathcal{C}^2(\mathbf{X}, \mathbb{R}_+)$ and $(\phi_1, \dots, \phi_m) \in \mathcal{C}(K_1) \times \dots \times \mathcal{C}(K_m)$ be a system of c -conjugate functions on subsets $K_i \subseteq X_i$. We set $E := c - \phi_1 \oplus \dots \oplus \phi_m$ on $\mathbf{K} := K_1 \times \dots \times K_m$. Take $\bar{\mathbf{x}} \in \mathbf{K}$ and $g = \{\sum_{p \in P} t_p g_p(\bar{\mathbf{x}}) \text{ for } (t_p)_{p \in P} \in \Delta_P\}$. Then there exists local coordinates around $\bar{\mathbf{x}}$, i.e. \mathcal{C}^2 diffeomorphisms*

$$u = (u^0, u^-, u^+) : U_{\bar{\mathbf{x}}} \subseteq \mathbf{X} \rightarrow \mathbb{R}^{d^0(g)} \times \mathbb{R}^{d^-(g)} \times \mathbb{R}^{d^+(g)}$$

defined on a neighborhood of $\bar{\mathbf{x}}$ such that if $\mathbf{x}, \mathbf{x}' \in B_r(\bar{\mathbf{x}}) \subseteq U_{\bar{\mathbf{x}}}$,

$$\frac{E(\mathbf{x}') + E(\mathbf{x})}{2} \geq |u^+(\mathbf{x}') - u^+(\mathbf{x})|^2 - |u^-(\mathbf{x}') - u^-(\mathbf{x})|^2 - \varepsilon(r)|u(\mathbf{x}') - u(\mathbf{x})|^2 \quad (4.1)$$

where $\varepsilon(r) \geq 0$ tends to 0 as $r \rightarrow 0$.

Proof. Let $p = \{p_-, p_+\} \in P$. For $y \in \prod_{i \in p_{\pm}} K_i$, we set

$$\phi_{p_{\pm}}(y) = \sum_{i \in p_{\pm}} \phi_i(y_i).$$

We identify any $\mathbf{x} \in \mathbf{K}$ with (x_{p_-}, x_{p_+}) . Since the (ϕ_i) are c -conjugate, if $\mathbf{x}, \mathbf{x}' \in \mathbf{K}$, we have:

$$\begin{aligned} E(\mathbf{x}') &= c(x'_{p_-}, x'_{p_+}) - \phi_{p_-}(x'_{p_-}) - \phi_{p_+}(x'_{p_+}) \\ &\geq c(x'_{p_-}, x'_{p_+}) - (c(x'_{p_-}, x_{p_+}) - \phi_{p_+}(x_{p_+})) - (c(x_{p_-}, x'_{p_+}) - \phi_{p_-}(x_{p_-})) \\ &= c(x'_{p_-}, x'_{p_+}) - c(x'_{p_-}, x_{p_+}) - c(x_{p_-}, x'_{p_+}) + c(x_{p_-}, x_{p_+}) - E(\mathbf{x}). \end{aligned}$$

Now we do computations in local charts $\psi_i : U_i \subseteq X_i \rightarrow \psi_i(U_i) \subseteq \mathbb{R}^{d_i}$ which are \mathcal{C}^2 diffeomorphisms such that $B_R(\bar{x}_i) \subseteq U_i$ and $\psi_i(U_i)$ are convex. We keep the same notation with a slight abuse¹, and use Taylor's integral formula:

$$E(\mathbf{x}') + E(\mathbf{x}) \geq \int_0^1 \int_0^1 D_{p_- p_+}^2 c(\mathbf{x}_{s,t})(x'_{p_-} - x_{p_-}, x'_{p_+} - x_{p_+})$$

where $\mathbf{x}_{s,t} := (x_{p_-} + (1-s)x'_{p_-}, x_{p_+} + (1-t)x'_{p_+})$ for $s, t \in [0, 1]$. Since $|D_{p_- p_+}^2 c(\mathbf{x}_{s,t}) - D_{p_- p_+}^2 c(\bar{\mathbf{x}})| \leq \varepsilon(\bar{\mathbf{x}}, \mathbf{r})$ where $\varepsilon(\bar{\mathbf{x}}, \mathbf{r})$ is independent from p and tends to 0 as $r \rightarrow 0$, and since by definition $D^2 c(\bar{\mathbf{x}})(x'_{p_-} - x_{p_-}, x'_{p_+} - x_{p_+}) = \frac{1}{2} g_p(\bar{\mathbf{x}})(\mathbf{x}' - \mathbf{x})$, it holds:

$$E(\mathbf{x}) + E(\mathbf{x}') \geq \frac{1}{2} g_p(\bar{\mathbf{x}})(\mathbf{x}' - \mathbf{x}) - \varepsilon(\bar{\mathbf{x}}, \mathbf{r}) \|\mathbf{x}' - \mathbf{x}\|^2.$$

¹Any linear combination $az_i + by_i$ will designate $\psi_i^{-1}(a\psi_i(z_i) + b\psi_i(y_i))$.

Taking $g = \sum_{p \in P} t_p g_p(\bar{\mathbf{x}})$ and averaging the previous inequality yields:

$$E(\mathbf{x}) + E(\mathbf{x}') \geq \frac{1}{2} g(\mathbf{x}' - \mathbf{x}) - \varepsilon(\bar{\mathbf{x}}, r) \|\mathbf{x}' - \mathbf{x}\|^2. \quad (4.2)$$

Finally, we can find a linear isomorphism $Q \in GL(\sum_i d_i, \mathbb{R})$ which trivializes g , i.e. such that after setting $u := Q \circ (\psi_1, \dots, \psi_m)$ and denoting $u = (u^+, u^-, u^0) : \prod_i U_i \rightarrow \mathbb{R}^{d^+(g)} \times \mathbb{R}^{d^-(g)} \times \mathbb{R}^{d^0(g)}$ then:

$$\frac{1}{4} g(\mathbf{x}' - \mathbf{x}) = |u^+(\mathbf{x}') - u^+(\mathbf{x})|^2 - |u^-(\mathbf{x}') - u^-(\mathbf{x})|^2.$$

We get the result by replacing ε with $\|Q\|^{-1}\varepsilon$. \square

We will use the following positive signature condition:

$$\begin{aligned} & \text{for every } \mathbf{x} \in X_1 \times \dots \times X_m, \quad d_c^+(\mathbf{x}) \geq \kappa \quad \text{where} \\ & d_c^\pm(\mathbf{x}) := \max \{ d^\pm(g) : g \in \text{conv}_{p \in P} \{ g_p(\mathbf{x}) \} \}. \end{aligned} \quad (\text{PS}(\kappa))$$

Proposition 4.2. *We assume that for every i , $\mu_i \in L^\infty(\mathcal{H}^{d_i} \llcorner X_i)$ and has compact support in X_i . If $(\text{PS}(\kappa))$ is satisfied, then there exists a constant $C_* \in [0, \infty)$ such that for every $\varepsilon > 0$,*

$$\boxed{\text{MOT}_\varepsilon \geq \text{MOT}_0 + \frac{\kappa}{2} \varepsilon \log(1/\varepsilon) - C_* \varepsilon.} \quad (4.3)$$

Proof. The measures μ_i being supported on some compact subsets $K_i \subseteq X_i$, consider a family $(\phi_i)_{1 \leq i \leq m} \in \mathcal{C}(K_1) \times \dots \times \mathcal{C}(K_m)$ of c -conjugate Kantorovich potentials. Taking $(\phi_i)_{1 \leq i \leq m}$ as competitor in (MD'_ε) , we get the lower bound:

$$\begin{aligned} \text{MOT}_\varepsilon & \geq \sum_{i=1}^m \int_{X_i} \phi_i d\mu_i - \varepsilon \log \left(\int_{\prod_{1 \leq i \leq m} X_i} e^{-\frac{E}{\varepsilon}} d \otimes_{1 \leq i \leq m} \mu_i \right) \\ & = \text{MOT}_0 - \varepsilon \log \left(\int_{\prod_{1 \leq i \leq m} X_i} e^{-\frac{E}{\varepsilon}} d \otimes_{1 \leq i \leq m} \mu_i \right), \end{aligned}$$

where $E := c - \bigoplus_{1 \leq i \leq m} \phi_i$ on $\mathbf{X} := \prod_{1 \leq i \leq m} X_i$ as in [Lemma 4.1](#). We are going to show that for some constant $C > 0$ and for every $\varepsilon > 0$,

$$\int_{\mathbf{X}} e^{-E/\varepsilon} d \otimes_{1 \leq i \leq m} \mu_i \leq C \varepsilon^{\kappa/2},$$

which yields [\(4.3\)](#) with $C_* = \log(C)$.

For every $\bar{\mathbf{x}} \in \mathbf{K} := \prod_{1 \leq i \leq m} K_i$, we consider a quadratic form $g_{\bar{\mathbf{x}}} = \sum_p t_p g_p(\bar{\mathbf{x}})$ of signature $(\kappa, d_{\bar{\mathbf{x}}}^-, d_{\bar{\mathbf{x}}}^0)$, which is possible thanks to $(\text{PS}(\kappa))$, and take a local chart

$$u_{\bar{\mathbf{x}}} : U_{\bar{\mathbf{x}}} \subseteq \mathbf{X} \rightarrow B_{R_{\bar{\mathbf{x}}}}^\kappa \times B_{R_{\bar{\mathbf{x}}}}^{d_{\bar{\mathbf{x}}}^-} \times B_{R_{\bar{\mathbf{x}}}}^{d_{\bar{\mathbf{x}}}^0}$$

as given by [Lemma 4.1](#), such that [\(4.1\)](#) holds with $\varepsilon(R_{\bar{\mathbf{x}}}) \leq 1/2$. Notice that $u_{\bar{\mathbf{x}}}$ is bi-Lipschitz with some constant $L_{\bar{\mathbf{x}}}$ on $V_{\bar{\mathbf{x}}} := u_{\bar{\mathbf{x}}}^{-1}(B_{R_{\bar{\mathbf{x}}}/2}^\kappa \times B_{R_{\bar{\mathbf{x}}}/2}^{d_{\bar{\mathbf{x}}}^-} \times B_{R_{\bar{\mathbf{x}}}/2}^{d_{\bar{\mathbf{x}}}^0})$.

For every i we may write $\mu_i = f_i \mathcal{H}_{X_i}^{d_i}$. By applying several times the co-area formula [Fed96, Theorem 3.2.22] to the projection maps onto X_i , we may justify that

$$\mathcal{H}_X^d = \otimes_{1 \leq i \leq m} \mathcal{H}_{X_i}^{d_i} \quad \text{where} \quad d = \sum_i d_i.$$

We set $E_{\bar{x}} := E \circ u_{\bar{x}}^{-1} : B_{R_{\bar{x}}}^\kappa \times B_{R_{\bar{x}}}^{d_{\bar{x}}^-} \times B_{R_{\bar{x}}}^{d_{\bar{x}}^0} \rightarrow [0, +\infty]$ and we apply the area formula:

$$\begin{aligned} \int_{V_{\bar{x}}} e^{-E/\varepsilon} d \otimes_{1 \leq i \leq m} \mu_i &= \int_{V_{\bar{x}}} e^{-E/\varepsilon} (\otimes_{1 \leq i \leq m} f_i) d \mathcal{H}_X^d \\ &= \int_{B_{R_{\bar{x}/2}}^\kappa \times B_{R_{\bar{x}/2}}^{d_{\bar{x}}^-} \times B_{R_{\bar{x}/2}}^{d_{\bar{x}}^0}} e^{-E_{\bar{x}}/\varepsilon} (\otimes_{1 \leq i \leq m} f_i) J u_{\bar{x}}^{-1} d \mathcal{L}^\kappa \otimes \mathcal{L}^{d_{\bar{x}}^-} \otimes \mathcal{L}^{d_{\bar{x}}^0} \\ &\leq L_{\bar{x}} \prod_{1 \leq i \leq m} \|\mu_i\|_{L^\infty(\mathcal{H}^{d_i} \llcorner X_i)} \int_{B_{R_{\bar{x}/2}}^\kappa \times B_{R_{\bar{x}/2}}^{d_{\bar{x}}^-} \times B_{R_{\bar{x}/2}}^{d_{\bar{x}}^0}} e^{-E_{\bar{x}}(u^+, u^-, u^0)/\varepsilon} d(u^+, u^-, u^0). \end{aligned}$$

Now, for every $(u^-, u^0) \in B_{R_{\bar{x}/2}}^{d_{\bar{x}}^-} \times B_{R_{\bar{x}/2}}^{d_{\bar{x}}^0}$, consider $f^+(u^-, u^0)$ a minimizer of $E_{\bar{x}}(\cdot, u^-, u^0)$ over $\bar{B}_{R_{\bar{x}/2}}^\kappa$. By (4.1) of Lemma 4.1, for every $(u^+, u^-, u^0) \in B_{R_{\bar{x}/2}}^\kappa \times B_{R_{\bar{x}/2}}^{d_{\bar{x}}^-} \times B_{R_{\bar{x}/2}}^{d_{\bar{x}}^0}$,

$$\begin{aligned} E_{\bar{x}}(u^+, u^-, u^0) &\geq \frac{1}{2} (E_{\bar{x}}(f^+(u^-, u^0), u^-, u^0) + E_{\bar{x}}(u^+, u^-, u^0)) \\ &\geq (1 - 1/2) |u^+ - f^+(u^-, u^0)|^2 = \frac{1}{2} |u^+ - f^+(u^-, u^0)|^2. \end{aligned}$$

As a consequence we obtain:

$$\begin{aligned} &\int_{B_{R_{\bar{x}/2}}^\kappa \times B_{R_{\bar{x}/2}}^{d_{\bar{x}}^-} \times B_{R_{\bar{x}/2}}^{d_{\bar{x}}^0}} e^{-E_{\bar{x}}(u^+, u^-, u^0)/\varepsilon} d(u^+, u^-, u^0) \\ &\leq \int_{B_{R_{\bar{x}/2}}^{d_{\bar{x}}^-} \times B_{R_{\bar{x}/2}}^{d_{\bar{x}}^0}} \int_{B_{R_{\bar{x}/2}}^\kappa} e^{-\frac{|u^+ - f^+(u^-, u^0)|^2}{2\varepsilon}} du^+ d(u^-, u^0) \\ &\leq \varepsilon^{\kappa/2} \omega_{d_{\bar{x}}^-} \omega_{d_{\bar{x}}^0} R_{\bar{x}}^{d_{\bar{x}}^- + d_{\bar{x}}^0} \int_{\mathbb{R}^\kappa} e^{-|u|^2/2} du = C_{\bar{x}} \varepsilon^{\kappa/2} \end{aligned}$$

for some constant $C_{\bar{x}} > 0$. The sets $\{V_{\bar{x}}\}_{\bar{x} \in \Sigma}$ form an open covering of the compact set $\Sigma := \{\mathbf{x} \in \mathbf{K} : E(\mathbf{x}) = 0\}$, hence we may extract a finite covering $V_{\bar{x}_1}, \dots, V_{\bar{x}_I}$ and:

$$\int_{\bigcup_{i=1}^I V_{\bar{x}_i}} e^{-E/\varepsilon} d \otimes_{1 \leq i \leq m} \mu_i \leq \varepsilon^{\kappa/2} \left(\sum_{1 \leq i \leq I} L_{\bar{x}_i} C_{\bar{x}_i} \right) \left(\prod_{1 \leq i \leq m} \|\mu_i\|_{L^\infty(\mathcal{H}^{d_i} \llcorner X_i)} \right) = c_1 \varepsilon^{\kappa/2},$$

for some constant $c_1 \in (0, +\infty)$. Finally, since E is continuous and does not vanish on the compact set $\mathbf{K}' = \mathbf{K} \setminus \bigcup_{i=1}^I V_{\bar{x}_i}$, it is bounded from below on \mathbf{K}' by some constant $c_2 > 0$. Therefore, for every $\varepsilon > 0$,

$$\int_{\mathbf{X}} e^{-E/\varepsilon} d \otimes_{1 \leq i \leq m} \mu_i \leq c_1 \varepsilon^{\kappa/2} + e^{-c_2/\varepsilon} \leq C \varepsilon^{\kappa/2},$$

for some constant $C > 0$. This concludes the proof. \square

5 Examples and matching bound

We devote this section to applying the results we have stated above to several cost functions. For simplicity we can assume that the dimensions of the X_i are all equal to some common d and the cost function c is \mathcal{C}^2 . As in [Pas12] we consider, for the lower bound, the metric \bar{g} such that $t_p = \frac{1}{2^{m-1}-1}$ for all $p \in P$, we remind that P is the set of partition of $\{1, \dots, m\}$ into two non empty disjoint subsets.

Example 5.1 (Two marginals case). In previous works [CPT23; EN22] concerning the rate of convergence for the two marginals problem, it was assumed that the cost function must satisfy a non degeneracy condition, that is $D_{x_1 x_2}^2 c$ must be of full rank. A direct consequence of our analysis is that we can provide a lower bound (the upper bound does not depend on such a condition) for costs for which the non-degeneracy condition fails. Let r be the rank of $D_{x_1 x_2}^2 c$ at the point where the non-degeneracy condition fails, then the signature of \bar{g} at this point is given by $(r, r, 2d - 2r)$ meaning that locally the support of the optimal γ_0 is at most $2d - r$ dimensional. Thus, the bounds become

$$\boxed{\frac{r}{2}\varepsilon \log(1/\varepsilon) - C_*\varepsilon \leq \text{OT}_\varepsilon - \text{OT}_0 \leq \frac{d}{2}\varepsilon \log(1/\varepsilon) + C^*\varepsilon,}$$

for some constants $C_*, C^* > 0$. Notice that if $D_{x_1, x_2}^2 c$ has full rank then $r = d$ and we retrieve the matching bound results of [CPT23; EN22].

Example 5.2 (Two marginals case and unequal dimension). Consider now the two marginals case but unequal dimensional, that is for example $d_1 > d_2$. Then, if $D_{x_1, x_2}^2 c$ has full rank, that is $r = d_2$, we obtain a matching bound depending only on the lower dimensional marginal

$$\boxed{\frac{d_2}{2}\varepsilon \log(1/\varepsilon) - C_*\varepsilon \leq \text{OT}_\varepsilon - \text{OT}_0 \leq \frac{d_2}{2}\varepsilon \log(1/\varepsilon) + C^*\varepsilon,}$$

for some constants $C_*, C^* > 0$. If μ_1 is absolutely continuous with respect to \mathcal{H}^{d_1} on some smooth sub-manifold of dimension d_1 , then any optimal transport plan would be concentrated on a set of Hausdorff dimension no less than d_1 , and thus the upper bound given in [EN22, Theorem 3.8] would be $\frac{d_1}{2}\varepsilon \log(1/\varepsilon) + O(\varepsilon)$, which is strictly worse than our estimate.

Example 5.3 (Negative harmonic cost). Consider the cost $c(x_1, \dots, x_m) = h(\sum_{i=1}^m x_i)$ where h is \mathcal{C}^c and $D^2 h > 0$. Assuming that the marginals have finite second moments, when $h(x) = |x|^2$ this kind of cost is equivalent to the harmonic negative cost that is $c(x_1, \dots, x_m) = -\sum_{i < j} |x_i - x_j|^2$ (here $|\cdot|$ denotes the standard euclidean norm), see [DGN15] for more details. It follows now that the signature of the metric \bar{g} is $(d, (m-1)d, 0)$ thus the bounds between MOT_ε and MOT_0 that we obtain are

$$\boxed{\frac{d}{2}\varepsilon \log(1/\varepsilon) - C_*\varepsilon \leq \text{MOT}_\varepsilon - \text{MOT}_0 \leq \frac{1}{2}\left((m-1)d\right)\varepsilon \log(1/\varepsilon) + C^*\varepsilon,}$$

for some constants $C_*, C^* > 0$. We remark that it is known from [Pas12; DGN15] that a transport plan γ_0 is optimal if and only if it is supported on the set $\{(x_1, \dots, x_m) \mid \sum_{i=1}^m x_i = l\}$, where $l \in \mathbb{R}^d$ is any constant and there exists solutions whose support has dimension exactly $(m-1)d$.

Example 5.4 (Gangbo-Świąch cost and Wasserstein barycenter). Suppose that $c(x_1, \dots, x_m) = \sum_{i < j} |x_i - x_j|^2$, known as the Gangbo-Świąch cost [GŚ98]. Notice that the cost is equivalent to $c(x_1, \dots, x_m) = h(\sum_{i < j} x_i)$ where h is \mathcal{C}^2 and $D^2h < 0$, then the signature of \bar{g} is $((m-1)d, d, 0)$ and we have a matching bound

$$\boxed{\frac{1}{2} \left((m-1)d \right) \varepsilon \log(1/\varepsilon) - C_* \varepsilon \leq \text{MOT}_\varepsilon - \text{MOT}_0 \leq \frac{1}{2} \left((m-1)d \right) \varepsilon \log(1/\varepsilon) + C^* \varepsilon.}$$

Notice now that considering the MOT_0 problem with a cost $c(x_1, \dots, x_m) = \sum_i |x_i - T(x_1, \dots, x_m)|^2$, where $T(x_1, \dots, x_m) = \sum_{i=1}^m \lambda_i x_i$ is the Euclidean barycenter, is equivalent to the MOT_0 with the Gangbo-Świąch cost and the matching bound above still holds. Moreover, the multi-marginal problem with this particular cost has been shown [AC11] to be equivalent to the Wasserstein barycenter, that is $T_{\#} \gamma_0 = \nu$ is the barycenter of μ_1, \dots, μ_m .

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